## A Solution Manual For

## Differential and integral calculus, vol II By N. Piskunov. 1974



Nasser M. Abbasi

May 15, 2024

## Contents

1 Chapter 1 2

## 1 Chapter 1

1.1 problem Example, page 25 . . . . . . . . . . . . . . . . . . . . . . . . . . . 3
1.2 problem Example, page 27 . . . . . . . . . . . . . . . . . . . . . . . . . . . 17
1.3 problem Example, page 28 . . . . . . . . . . . . . . . . . . . . . . . . . . . 28
1.4 problem Example, page 30 . . . . . . . . . . . . . . . . . . . . . . . . . . . 36
1.5 problem Example, page 33 . . . . . . . . . . . . . . . . . . . . . . . . . . . 49
1.6 problem Example, page 36 . . . . . . . . . . . . . . . . . . . . . . . . . . . 58
1.7 problem Example, page 38 . . . . . . . . . . . . . . . . . . . . . . . . . . . 74
1.8 problem example page 46 . . . . . . . . . . . . . . . . . . . . . . . . . . . 92
1.9 problem example page 47 . . . . . . . . . . . . . . . . . . . . . . . . . . . 96
1.10 problem Example, page 49 . . . . . . . . . . . . . . . . . . . . . . . . . . . 103

## 1.1 problem Example, page 25

1.1.1 Solving as homogeneousTypeD2 ode
1.1.2 Solving as first order ode lie symmetry calculated ode . . . . . . 5
1.1.3 Solving as exact ode . . . . . . . . . . . . . . . . . . . . . . . . 10

Internal problem ID [4345]
Internal file name [OUTPUT/3838_Sunday_June_05_2022_11_20_18_AM_47450005/index.tex]
Book: Differential and integral calculus, vol II By N. Piskunov. 1974
Section: Chapter 1
Problem number: Example, page 25.
ODE order: 1.
ODE degree: 1 .

The type(s) of ODE detected by this program : "homogeneousTypeD2", "exactWithIntegrationFactor", "first_order_ode_lie_symmetry_calculated"

Maple gives the following as the ode type
[[_homogeneous, `class A`], _rational, _dAlembert]

$$
y^{\prime}-\frac{x y}{x^{2}-y^{2}}=0
$$

### 1.1.1 Solving as homogeneousTypeD2 ode

Using the change of variables $y=u(x) x$ on the above ode results in new ode in $u(x)$

$$
u^{\prime}(x) x+u(x)-\frac{x^{2} u(x)}{x^{2}-u(x)^{2} x^{2}}=0
$$

In canonical form the ODE is

$$
\begin{aligned}
u^{\prime} & =F(x, u) \\
& =f(x) g(u) \\
& =-\frac{u^{3}}{x\left(u^{2}-1\right)}
\end{aligned}
$$

Where $f(x)=-\frac{1}{x}$ and $g(u)=\frac{u^{3}}{u^{2}-1}$. Integrating both sides gives

$$
\begin{aligned}
\frac{1}{\frac{u^{3}}{u^{2}-1}} d u & =-\frac{1}{x} d x \\
\int \frac{1}{\frac{u^{3}}{u^{2}-1}} d u & =\int-\frac{1}{x} d x \\
\ln (u)+\frac{1}{2 u^{2}} & =-\ln (x)+c_{2}
\end{aligned}
$$

The solution is

$$
\ln (u(x))+\frac{1}{2 u(x)^{2}}+\ln (x)-c_{2}=0
$$

Replacing $u(x)$ in the above solution by $\frac{y}{x}$ results in the solution for $y$ in implicit form

$$
\begin{aligned}
& \ln \left(\frac{y}{x}\right)+\frac{x^{2}}{2 y^{2}}+\ln (x)-c_{2}=0 \\
& \ln \left(\frac{y}{x}\right)+\frac{x^{2}}{2 y^{2}}+\ln (x)-c_{2}=0
\end{aligned}
$$

Summary
The solution(s) found are the following

$$
\begin{equation*}
\ln \left(\frac{y}{x}\right)+\frac{x^{2}}{2 y^{2}}+\ln (x)-c_{2}=0 \tag{1}
\end{equation*}
$$



Figure 1: Slope field plot

## Verification of solutions

$$
\ln \left(\frac{y}{x}\right)+\frac{x^{2}}{2 y^{2}}+\ln (x)-c_{2}=0
$$

Verified OK.

### 1.1.2 Solving as first order ode lie symmetry calculated ode

Writing the ode as

$$
\begin{aligned}
y^{\prime} & =-\frac{x y}{-x^{2}+y^{2}} \\
y^{\prime} & =\omega(x, y)
\end{aligned}
$$

The condition of Lie symmetry is the linearized PDE given by

$$
\begin{equation*}
\eta_{x}+\omega\left(\eta_{y}-\xi_{x}\right)-\omega^{2} \xi_{y}-\omega_{x} \xi-\omega_{y} \eta=0 \tag{A}
\end{equation*}
$$

The type of this ode is not in the lookup table. To determine $\xi, \eta$ then (A) is solved using ansatz. Making bivariate polynomials of degree 1 to use as anstaz gives

$$
\begin{align*}
& \xi=x a_{2}+y a_{3}+a_{1}  \tag{1E}\\
& \eta=x b_{2}+y b_{3}+b_{1} \tag{2E}
\end{align*}
$$

Where the unknown coefficients are

$$
\left\{a_{1}, a_{2}, a_{3}, b_{1}, b_{2}, b_{3}\right\}
$$

Substituting equations (1E,2E) and $\omega$ into (A) gives

$$
\begin{align*}
b_{2} & -\frac{x y\left(b_{3}-a_{2}\right)}{-x^{2}+y^{2}}-\frac{x^{2} y^{2} a_{3}}{\left(-x^{2}+y^{2}\right)^{2}} \\
& -\left(-\frac{y}{-x^{2}+y^{2}}-\frac{2 x^{2} y}{\left(-x^{2}+y^{2}\right)^{2}}\right)\left(x a_{2}+y a_{3}+a_{1}\right)  \tag{5E}\\
& -\left(-\frac{x}{-x^{2}+y^{2}}+\frac{2 x y^{2}}{\left(-x^{2}+y^{2}\right)^{2}}\right)\left(x b_{2}+y b_{3}+b_{1}\right)=0
\end{align*}
$$

Putting the above in normal form gives

$$
-\frac{3 x^{2} y^{2} b_{2}-2 x y^{3} a_{2}+2 x y^{3} b_{3}-y^{4} a_{3}-y^{4} b_{2}+x^{3} b_{1}-x^{2} y a_{1}+x y^{2} b_{1}-y^{3} a_{1}}{\left(x^{2}-y^{2}\right)^{2}}=0
$$

Setting the numerator to zero gives

$$
\begin{equation*}
-3 x^{2} y^{2} b_{2}+2 x y^{3} a_{2}-2 x y^{3} b_{3}+y^{4} a_{3}+y^{4} b_{2}-x^{3} b_{1}+x^{2} y a_{1}-x y^{2} b_{1}+y^{3} a_{1}=0 \tag{6E}
\end{equation*}
$$

Looking at the above PDE shows the following are all the terms with $\{x, y\}$ in them.

$$
\{x, y\}
$$

The following substitution is now made to be able to collect on all terms with $\{x, y\}$ in them

$$
\left\{x=v_{1}, y=v_{2}\right\}
$$

The above PDE (6E) now becomes

$$
\begin{equation*}
2 a_{2} v_{1} v_{2}^{3}+a_{3} v_{2}^{4}-3 b_{2} v_{1}^{2} v_{2}^{2}+b_{2} v_{2}^{4}-2 b_{3} v_{1} v_{2}^{3}+a_{1} v_{1}^{2} v_{2}+a_{1} v_{2}^{3}-b_{1} v_{1}^{3}-b_{1} v_{1} v_{2}^{2}=0 \tag{7E}
\end{equation*}
$$

Collecting the above on the terms $v_{i}$ introduced, and these are

$$
\left\{v_{1}, v_{2}\right\}
$$

Equation (7E) now becomes

$$
\begin{equation*}
-b_{1} v_{1}^{3}-3 b_{2} v_{1}^{2} v_{2}^{2}+a_{1} v_{1}^{2} v_{2}+\left(2 a_{2}-2 b_{3}\right) v_{1} v_{2}^{3}-b_{1} v_{1} v_{2}^{2}+\left(a_{3}+b_{2}\right) v_{2}^{4}+a_{1} v_{2}^{3}=0 \tag{8E}
\end{equation*}
$$

Setting each coefficients in (8E) to zero gives the following equations to solve

$$
\begin{aligned}
a_{1} & =0 \\
-b_{1} & =0 \\
-3 b_{2} & =0 \\
2 a_{2}-2 b_{3} & =0 \\
a_{3}+b_{2} & =0
\end{aligned}
$$

Solving the above equations for the unknowns gives

$$
\begin{aligned}
a_{1} & =0 \\
a_{2} & =b_{3} \\
a_{3} & =0 \\
b_{1} & =0 \\
b_{2} & =0 \\
b_{3} & =b_{3}
\end{aligned}
$$

Substituting the above solution in the anstaz (1E, 2E) (using 1 as arbitrary value for any unknown in the RHS) gives

$$
\begin{aligned}
& \xi=x \\
& \eta=y
\end{aligned}
$$

Shifting is now applied to make $\xi=0$ in order to simplify the rest of the computation

$$
\begin{aligned}
\eta & =\eta-\omega(x, y) \xi \\
& =y-\left(-\frac{x y}{-x^{2}+y^{2}}\right)(x) \\
& =-\frac{y^{3}}{x^{2}-y^{2}} \\
\xi & =0
\end{aligned}
$$

The next step is to determine the canonical coordinates $R, S$. The canonical coordinates map $(x, y) \rightarrow(R, S)$ where $(R, S)$ are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$
\begin{equation*}
\frac{d x}{\xi}=\frac{d y}{\eta}=d S \tag{1}
\end{equation*}
$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x}+\eta \frac{\partial}{\partial y}\right) S(x, y)=1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable $R$ in the canonical coordinates, where $S(R)$. Since $\xi=0$ then in this special case

$$
R=x
$$

$S$ is found from

$$
\begin{aligned}
S & =\int \frac{1}{\eta} d y \\
& =\int \frac{1}{-\frac{y^{3}}{x^{2}-y^{2}}} d y
\end{aligned}
$$

Which results in

$$
S=\ln (y)+\frac{x^{2}}{2 y^{2}}
$$

Now that $R, S$ are found, we need to setup the ode in these coordinates. This is done by evaluating

$$
\begin{equation*}
\frac{d S}{d R}=\frac{S_{x}+\omega(x, y) S_{y}}{R_{x}+\omega(x, y) R_{y}} \tag{2}
\end{equation*}
$$

Where in the above $R_{x}, R_{y}, S_{x}, S_{y}$ are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$
\omega(x, y)=-\frac{x y}{-x^{2}+y^{2}}
$$

Evaluating all the partial derivatives gives

$$
\begin{aligned}
R_{x} & =1 \\
R_{y} & =0 \\
S_{x} & =\frac{x}{y^{2}} \\
S_{y} & =\frac{-x^{2}+y^{2}}{y^{3}}
\end{aligned}
$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$
\begin{equation*}
\frac{d S}{d R}=0 \tag{2~A}
\end{equation*}
$$

We now need to express the RHS as function of $R$ only. This is done by solving for $x, y$ in terms of $R, S$ from the result obtained earlier and simplifying. This gives

$$
\frac{d S}{d R}=0
$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordiates $R, S$. Integrating the above gives

$$
\begin{equation*}
S(R)=c_{1} \tag{4}
\end{equation*}
$$

To complete the solution, we just need to transform (4) back to $x, y$ coordinates. This results in

$$
\frac{2 \ln (y) y^{2}+x^{2}}{2 y^{2}}=c_{1}
$$

Which simplifies to

$$
\frac{2 \ln (y) y^{2}+x^{2}}{2 y^{2}}=c_{1}
$$

Which gives

$$
y=\mathrm{e}^{\frac{\operatorname{LambertW}\left(-x^{2} \mathrm{e}^{-2 c_{1}}\right)}{2}+c_{1}}
$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

| Original ode in $x, y$ coordinates | Canonical coordinates transformation | ODE in canonical coordinates $(R, S)$ |
| :---: | :---: | :---: |
| $\frac{d y}{d x}=-\frac{x y}{-x^{2}+y^{2}}$ |  | $\frac{d S}{d R}=0$ |
|  |  |  |
|  |  | $\xrightarrow{\rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \longrightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \longrightarrow \rightarrow}$ |
|  |  |  |
| $\rightarrow \rightarrow \times \rightarrow$ | $R=x$ | $\xrightarrow{\rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow}$ |
|  | $2 \ln (u) u^{2}+r^{2}$ |  |
|  | $S=\frac{2 \ln (y) y^{2}+x^{2}}{2 y^{2}}$ |  |
|  | $2 y^{2}$ | $\xrightarrow{\rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow+\rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow}$ |
|  |  | $\xrightarrow{\rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow}$ |
|  |  |  |
|  |  | $\rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow$ 遇 |

## Summary

The solution(s) found are the following

$$
\begin{equation*}
y=\mathrm{e}^{\frac{\operatorname{Lambertw}\left(-x^{2} \mathrm{e}^{2}-2 c_{1}\right)}{2}+c_{1}} \tag{1}
\end{equation*}
$$



Figure 2: Slope field plot

## Verification of solutions

$$
y=\mathrm{e}^{\frac{\operatorname{Lambertw}\left(-x^{2} \mathrm{e}^{-2 c_{1}}\right)}{2}+c_{1}}
$$

Verified OK.

### 1.1.3 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)
To solve an ode of the form

$$
\begin{equation*}
M(x, y)+N(x, y) \frac{d y}{d x}=0 \tag{A}
\end{equation*}
$$

We assume there exists a function $\phi(x, y)=c$ where $c$ is constant, that satisfies the ode. Taking derivative of $\phi$ w.r.t. $x$ gives

$$
\frac{d}{d x} \phi(x, y)=0
$$

Hence

$$
\begin{equation*}
\frac{\partial \phi}{\partial x}+\frac{\partial \phi}{\partial y} \frac{d y}{d x}=0 \tag{B}
\end{equation*}
$$

Comparing ( $\mathrm{A}, \mathrm{B}$ ) shows that

$$
\begin{aligned}
& \frac{\partial \phi}{\partial x}=M \\
& \frac{\partial \phi}{\partial y}=N
\end{aligned}
$$

But since $\frac{\partial^{2} \phi}{\partial x \partial y}=\frac{\partial^{2} \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$
\frac{\partial M}{\partial y}=\frac{\partial N}{\partial x}
$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^{2} \phi}{\partial x \partial y}=\frac{\partial^{2} \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$
\begin{equation*}
M(x, y) \mathrm{d} x+N(x, y) \mathrm{d} y=0 \tag{1A}
\end{equation*}
$$

Therefore

$$
\begin{align*}
\left(-x^{2}+y^{2}\right) \mathrm{d} y & =(-x y) \mathrm{d} x \\
(x y) \mathrm{d} x+\left(-x^{2}+y^{2}\right) \mathrm{d} y & =0 \tag{2~A}
\end{align*}
$$

Comparing (1A) and (2A) shows that

$$
\begin{aligned}
M(x, y) & =x y \\
N(x, y) & =-x^{2}+y^{2}
\end{aligned}
$$

The next step is to determine if the ODE is is exact or not. The ODE is exact when the following condition is satisfied

$$
\frac{\partial M}{\partial y}=\frac{\partial N}{\partial x}
$$

Using result found above gives

$$
\begin{aligned}
\frac{\partial M}{\partial y} & =\frac{\partial}{\partial y}(x y) \\
& =x
\end{aligned}
$$

And

$$
\begin{aligned}
\frac{\partial N}{\partial x} & =\frac{\partial}{\partial x}\left(-x^{2}+y^{2}\right) \\
& =-2 x
\end{aligned}
$$

Since $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$
\begin{aligned}
A & =\frac{1}{N}\left(\frac{\partial M}{\partial y}-\frac{\partial N}{\partial x}\right) \\
& =\frac{1}{-x^{2}+y^{2}}((x)-(-2 x)) \\
& =-\frac{3 x}{x^{2}-y^{2}}
\end{aligned}
$$

Since $A$ depends on $y$, it can not be used to obtain an integrating factor. We will now try a second method to find an integrating factor. Let

$$
\begin{aligned}
B & =\frac{1}{M}\left(\frac{\partial N}{\partial x}-\frac{\partial M}{\partial y}\right) \\
& =\frac{1}{x y}((-2 x)-(x)) \\
& =-\frac{3}{y}
\end{aligned}
$$

Since $B$ does not depend on $x$, it can be used to obtain an integrating factor. Let the integrating factor be $\mu$. Then

$$
\begin{aligned}
\mu & =e^{\int B \mathrm{~d} y} \\
& =e^{\int-\frac{3}{y} \mathrm{~d} y}
\end{aligned}
$$

The result of integrating gives

$$
\begin{aligned}
\mu & =e^{-3 \ln (y)} \\
& =\frac{1}{y^{3}}
\end{aligned}
$$

$M$ and $N$ are now multiplied by this integrating factor, giving new $M$ and new $N$ which are called $\bar{M}$ and $\bar{N}$ so not to confuse them with the original $M$ and $N$.

$$
\begin{aligned}
\bar{M} & =\mu M \\
& =\frac{1}{y^{3}}(x y) \\
& =\frac{x}{y^{2}}
\end{aligned}
$$

And

$$
\begin{aligned}
\bar{N} & =\mu N \\
& =\frac{1}{y^{3}}\left(-x^{2}+y^{2}\right) \\
& =\frac{-x^{2}+y^{2}}{y^{3}}
\end{aligned}
$$

So now a modified ODE is obtained from the original ODE which will be exact and can be solved using the standard method. The modified ODE is

$$
\begin{array}{r}
\bar{M}+\bar{N} \frac{\mathrm{~d} y}{\mathrm{~d} x}=0 \\
\left(\frac{x}{y^{2}}\right)+\left(\frac{-x^{2}+y^{2}}{y^{3}}\right) \frac{\mathrm{d} y}{\mathrm{~d} x}=0
\end{array}
$$

The following equations are now set up to solve for the function $\phi(x, y)$

$$
\begin{align*}
& \frac{\partial \phi}{\partial x}=\bar{M}  \tag{1}\\
& \frac{\partial \phi}{\partial y}=\bar{N} \tag{2}
\end{align*}
$$

Integrating (1) w.r.t. $x$ gives

$$
\begin{align*}
\int \frac{\partial \phi}{\partial x} \mathrm{~d} x & =\int \bar{M} \mathrm{~d} x \\
\int \frac{\partial \phi}{\partial x} \mathrm{~d} x & =\int \frac{x}{y^{2}} \mathrm{~d} x \\
\phi & =\frac{x^{2}}{2 y^{2}}+f(y) \tag{3}
\end{align*}
$$

Where $f(y)$ is used for the constant of integration since $\phi$ is a function of both $x$ and $y$. Taking derivative of equation (3) w.r.t $y$ gives

$$
\begin{equation*}
\frac{\partial \phi}{\partial y}=-\frac{x^{2}}{y^{3}}+f^{\prime}(y) \tag{4}
\end{equation*}
$$

But equation (2) says that $\frac{\partial \phi}{\partial y}=\frac{-x^{2}+y^{2}}{y^{3}}$. Therefore equation (4) becomes

$$
\begin{equation*}
\frac{-x^{2}+y^{2}}{y^{3}}=-\frac{x^{2}}{y^{3}}+f^{\prime}(y) \tag{5}
\end{equation*}
$$

Solving equation (5) for $f^{\prime}(y)$ gives

$$
f^{\prime}(y)=\frac{1}{y}
$$

Integrating the above w.r.t $y$ gives

$$
\begin{aligned}
\int f^{\prime}(y) \mathrm{d} y & =\int\left(\frac{1}{y}\right) \mathrm{d} y \\
f(y) & =\ln (y)+c_{1}
\end{aligned}
$$

Where $c_{1}$ is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives $\phi$

$$
\phi=\ln (y)+\frac{x^{2}}{2 y^{2}}+c_{1}
$$

But since $\phi$ itself is a constant function, then let $\phi=c_{2}$ where $c_{2}$ is new constant and combining $c_{1}$ and $c_{2}$ constants into new constant $c_{1}$ gives the solution as

$$
c_{1}=\ln (y)+\frac{x^{2}}{2 y^{2}}
$$

The solution becomes

$$
y=\mathrm{e}^{\frac{\operatorname{Lambertw}\left(-x^{2} \mathrm{e}^{-2 c_{1}}\right)}{2}+c_{1}}
$$

Summary
The solution(s) found are the following

$$
\begin{equation*}
y=\mathrm{e}^{\frac{\operatorname{LambertW}\left(-x^{2} \mathrm{e}^{-2 c_{1}}\right)}{2}+c_{1}} \tag{1}
\end{equation*}
$$



Figure 3: Slope field plot

Verification of solutions

$$
y=\mathrm{e}^{\frac{\operatorname{Lambertw}\left(-x^{2} \mathrm{e}^{-2 c_{1}}\right)}{2}+c_{1}}
$$

Verified OK.
Maple trace

```
`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
trying separable
trying inverse linear
trying homogeneous types:
trying homogeneous D
<- homogeneous successful`
```

$\checkmark$ Solution by Maple
Time used: 0.016 (sec). Leaf size: 19
dsolve(diff $(y(x), x)=x * y(x) /\left(x^{\wedge} 2-y(x) \sim 2\right), y(x)$, singsol=all)

$$
y(x)=\sqrt{-\frac{1}{\text { LambertW }\left(-c_{1} x^{2}\right)}} x
$$

$\checkmark$ Solution by Mathematica
Time used: 8.026 (sec). Leaf size: 56
DSolve[y' $[x]==x * y[x] /\left(x^{\wedge} 2-y[x] \sim 2\right), y[x], x$, IncludeSingularSolutions $->$ True]

$$
\begin{aligned}
& y(x) \rightarrow-\frac{i x}{\sqrt{W\left(-e^{-2 c_{1}} x^{2}\right)}} \\
& y(x) \rightarrow \frac{i x}{\sqrt{W\left(-e^{-2 c_{1}} x^{2}\right)}} \\
& y(x) \rightarrow 0
\end{aligned}
$$

## 1.2 problem Example, page 27

### 1.2.1 Solving as homogeneousTypeMapleC ode

1.2.2 Solving as first order ode lie symmetry calculated ode . . . . . . 20

Internal problem ID [4346]
Internal file name [OUTPUT/3839_Sunday_June_05_2022_11_20_25_AM_71334307/index.tex]
Book: Differential and integral calculus, vol II By N. Piskunov. 1974
Section: Chapter 1
Problem number: Example, page 27.
ODE order: 1.
ODE degree: 1.

The type(s) of ODE detected by this program : "homogeneousTypeMapleC", "first__order_ode_lie_symmetry_calculated"

Maple gives the following as the ode type

```
[[_homogeneous, `class C`], _rational, [_Abel, `2nd type`,`
    class A`]]
```

$$
y^{\prime}-\frac{x+y-3}{x-y-1}=0
$$

### 1.2.1 Solving as homogeneousTypeMapleC ode

Let $Y=y+y_{0}$ and $X=x+x_{0}$ then the above is transformed to new ode in $Y(X)$

$$
\frac{d}{d X} Y(X)=-\frac{X+x_{0}+Y(X)+y_{0}-3}{-X-x_{0}+Y(X)+y_{0}+1}
$$

Solving for possible values of $x_{0}$ and $y_{0}$ which makes the above ode a homogeneous ode results in

$$
\begin{aligned}
x_{0} & =2 \\
y_{0} & =1
\end{aligned}
$$

Using these values now it is possible to easily solve for $Y(X)$. The above ode now becomes

$$
\frac{d}{d X} Y(X)=-\frac{X+Y(X)}{-X+Y(X)}
$$

In canonical form, the ODE is

$$
\begin{align*}
Y^{\prime} & =F(X, Y) \\
& =-\frac{X+Y}{-X+Y} \tag{1}
\end{align*}
$$

An ode of the form $Y^{\prime}=\frac{M(X, Y)}{N(X, Y)}$ is called homogeneous if the functions $M(X, Y)$ and $N(X, Y)$ are both homogeneous functions and of the same order. Recall that a function $f(X, Y)$ is homogeneous of order $n$ if

$$
f\left(t^{n} X, t^{n} Y\right)=t^{n} f(X, Y)
$$

In this case, it can be seen that both $M=X+Y$ and $N=X-Y$ are both homogeneous and of the same order $n=1$. Therefore this is a homogeneous ode. Since this ode is homogeneous, it is converted to separable ODE using the substitution $u=\frac{Y}{X}$, or $Y=u X$. Hence

$$
\frac{\mathrm{d} Y}{\mathrm{~d} X}=\frac{\mathrm{d} u}{\mathrm{~d} X} X+u
$$

Applying the transformation $Y=u X$ to the above ODE in (1) gives

$$
\begin{aligned}
\frac{\mathrm{d} u}{\mathrm{~d} X} X+u & =\frac{-u-1}{u-1} \\
\frac{\mathrm{~d} u}{\mathrm{~d} X} & =\frac{\frac{-u(X)-1}{u(X)-1}-u(X)}{X}
\end{aligned}
$$

Or

$$
\frac{d}{d X} u(X)-\frac{\frac{-u(X)-1}{u(X)-1}-u(X)}{X}=0
$$

Or

$$
\left(\frac{d}{d X} u(X)\right) X u(X)-\left(\frac{d}{d X} u(X)\right) X+u(X)^{2}+1=0
$$

Or

$$
X(u(X)-1)\left(\frac{d}{d X} u(X)\right)+u(X)^{2}+1=0
$$

Which is now solved as separable in $u(X)$. Which is now solved in $u(X)$. In canonical form the ODE is

$$
\begin{aligned}
u^{\prime} & =F(X, u) \\
& =f(X) g(u) \\
& =-\frac{u^{2}+1}{X(u-1)}
\end{aligned}
$$

Where $f(X)=-\frac{1}{X}$ and $g(u)=\frac{u^{2}+1}{u-1}$. Integrating both sides gives

$$
\begin{aligned}
\frac{1}{\frac{u^{2}+1}{u-1}} d u & =-\frac{1}{X} d X \\
\int \frac{1}{\frac{u^{2}+1}{u-1}} d u & =\int-\frac{1}{X} d X \\
\frac{\ln \left(u^{2}+1\right)}{2}-\arctan (u) & =-\ln (X)+c_{2}
\end{aligned}
$$

The solution is

$$
\frac{\ln \left(u(X)^{2}+1\right)}{2}-\arctan (u(X))+\ln (X)-c_{2}=0
$$

Now $u$ in the above solution is replaced back by $Y$ using $u=\frac{Y}{X}$ which results in the solution

$$
\frac{\ln \left(\frac{Y(X)^{2}}{X^{2}}+1\right)}{2}-\arctan \left(\frac{Y(X)}{X}\right)+\ln (X)-c_{2}=0
$$

Using the solution for $Y(X)$

$$
\frac{\ln \left(\frac{Y(X)^{2}}{X^{2}}+1\right)}{2}-\arctan \left(\frac{Y(X)}{X}\right)+\ln (X)-c_{2}=0
$$

And replacing back terms in the above solution using

$$
\begin{aligned}
& Y=y+y_{0} \\
& X=x+x_{0}
\end{aligned}
$$

Or

$$
\begin{aligned}
Y & =1+y \\
X & =x+2
\end{aligned}
$$

Then the solution in $y$ becomes

$$
\frac{\ln \left(\frac{(y-1)^{2}}{(-2+x)^{2}}+1\right)}{2}-\arctan \left(\frac{y-1}{-2+x}\right)+\ln (-2+x)-c_{2}=0
$$

## Summary

The solution(s) found are the following

$$
\begin{equation*}
\frac{\ln \left(\frac{(y-1)^{2}}{(-2+x)^{2}}+1\right)}{2}-\arctan \left(\frac{y-1}{-2+x}\right)+\ln (-2+x)-c_{2}=0 \tag{1}
\end{equation*}
$$



Figure 4: Slope field plot

Verification of solutions

$$
\frac{\ln \left(\frac{(y-1)^{2}}{(-2+x)^{2}}+1\right)}{2}-\arctan \left(\frac{y-1}{-2+x}\right)+\ln (-2+x)-c_{2}=0
$$

Verified OK.

### 1.2.2 Solving as first order ode lie symmetry calculated ode

Writing the ode as

$$
\begin{aligned}
y^{\prime} & =-\frac{x+y-3}{-x+y+1} \\
y^{\prime} & =\omega(x, y)
\end{aligned}
$$

The condition of Lie symmetry is the linearized PDE given by

$$
\begin{equation*}
\eta_{x}+\omega\left(\eta_{y}-\xi_{x}\right)-\omega^{2} \xi_{y}-\omega_{x} \xi-\omega_{y} \eta=0 \tag{A}
\end{equation*}
$$

The type of this ode is not in the lookup table. To determine $\xi, \eta$ then (A) is solved using ansatz. Making bivariate polynomials of degree 1 to use as anstaz gives

$$
\begin{align*}
& \xi=x a_{2}+y a_{3}+a_{1}  \tag{1E}\\
& \eta=x b_{2}+y b_{3}+b_{1} \tag{2E}
\end{align*}
$$

Where the unknown coefficients are

$$
\left\{a_{1}, a_{2}, a_{3}, b_{1}, b_{2}, b_{3}\right\}
$$

Substituting equations (1E,2E) and $\omega$ into (A) gives

$$
\begin{align*}
b_{2} & -\frac{(x+y-3)\left(b_{3}-a_{2}\right)}{-x+y+1}-\frac{(x+y-3)^{2} a_{3}}{(-x+y+1)^{2}} \\
& -\left(-\frac{1}{-x+y+1}-\frac{x+y-3}{(-x+y+1)^{2}}\right)\left(x a_{2}+y a_{3}+a_{1}\right)  \tag{5E}\\
& -\left(-\frac{1}{-x+y+1}+\frac{x+y-3}{(-x+y+1)^{2}}\right)\left(x b_{2}+y b_{3}+b_{1}\right)=0
\end{align*}
$$

Putting the above in normal form gives

$$
-\frac{x^{2} a_{2}+x^{2} a_{3}+x^{2} b_{2}-x^{2} b_{3}-2 x y a_{2}+2 x y a_{3}+2 x y b_{2}+2 x y b_{3}-y^{2} a_{2}-y^{2} a_{3}-y^{2} b_{2}+y^{2} b_{3}-2 x a_{2}-6 x c}{(x-y-}
$$

$$
=0
$$

Setting the numerator to zero gives

$$
\begin{align*}
& -x^{2} a_{2}-x^{2} a_{3}-x^{2} b_{2}+x^{2} b_{3}+2 x y a_{2}-2 x y a_{3}-2 x y b_{2}-2 x y b_{3}+y^{2} a_{2}  \tag{6E}\\
& +y^{2} a_{3}+y^{2} b_{2}-y^{2} b_{3}+2 x a_{2}+6 x a_{3}-2 x b_{1}+2 x b_{2}-4 x b_{3}+2 y a_{1} \\
& -2 y a_{2}+4 y a_{3}+2 y b_{2}+6 y b_{3}-2 a_{1}-3 a_{2}-9 a_{3}+4 b_{1}+b_{2}+3 b_{3}=0
\end{align*}
$$

Looking at the above PDE shows the following are all the terms with $\{x, y\}$ in them.

$$
\{x, y\}
$$

The following substitution is now made to be able to collect on all terms with $\{x, y\}$ in them

$$
\left\{x=v_{1}, y=v_{2}\right\}
$$

The above PDE (6E) now becomes

$$
\begin{align*}
& -a_{2} v_{1}^{2}+2 a_{2} v_{1} v_{2}+a_{2} v_{2}^{2}-a_{3} v_{1}^{2}-2 a_{3} v_{1} v_{2}+a_{3} v_{2}^{2}-b_{2} v_{1}^{2}-2 b_{2} v_{1} v_{2}+b_{2} v_{2}^{2}  \tag{7E}\\
& +b_{3} v_{1}^{2}-2 b_{3} v_{1} v_{2}-b_{3} v_{2}^{2}+2 a_{1} v_{2}+2 a_{2} v_{1}-2 a_{2} v_{2}+6 a_{3} v_{1}+4 a_{3} v_{2}-2 b_{1} v_{1} \\
& +2 b_{2} v_{1}+2 b_{2} v_{2}-4 b_{3} v_{1}+6 b_{3} v_{2}-2 a_{1}-3 a_{2}-9 a_{3}+4 b_{1}+b_{2}+3 b_{3}=0
\end{align*}
$$

Collecting the above on the terms $v_{i}$ introduced, and these are

$$
\left\{v_{1}, v_{2}\right\}
$$

Equation (7E) now becomes

$$
\begin{align*}
& \left(-a_{2}-a_{3}-b_{2}+b_{3}\right) v_{1}^{2}+\left(2 a_{2}-2 a_{3}-2 b_{2}-2 b_{3}\right) v_{1} v_{2}  \tag{8E}\\
& \quad+\left(2 a_{2}+6 a_{3}-2 b_{1}+2 b_{2}-4 b_{3}\right) v_{1}+\left(a_{2}+a_{3}+b_{2}-b_{3}\right) v_{2}^{2} \\
& \quad+\left(2 a_{1}-2 a_{2}+4 a_{3}+2 b_{2}+6 b_{3}\right) v_{2}-2 a_{1}-3 a_{2}-9 a_{3}+4 b_{1}+b_{2}+3 b_{3}=0
\end{align*}
$$

Setting each coefficients in (8E) to zero gives the following equations to solve

$$
\begin{array}{r}
-a_{2}-a_{3}-b_{2}+b_{3}=0 \\
a_{2}+a_{3}+b_{2}-b_{3}=0 \\
2 a_{2}-2 a_{3}-2 b_{2}-2 b_{3}=0 \\
2 a_{1}-2 a_{2}+4 a_{3}+2 b_{2}+6 b_{3}=0 \\
2 a_{2}+6 a_{3}-2 b_{1}+2 b_{2}-4 b_{3}=0 \\
-2 a_{1}-3 a_{2}-9 a_{3}+4 b_{1}+b_{2}+3 b_{3}=0
\end{array}
$$

Solving the above equations for the unknowns gives

$$
\begin{aligned}
& a_{1}=b_{2}-2 b_{3} \\
& a_{2}=b_{3} \\
& a_{3}=-b_{2} \\
& b_{1}=-2 b_{2}-b_{3} \\
& b_{2}=b_{2} \\
& b_{3}=b_{3}
\end{aligned}
$$

Substituting the above solution in the anstaz (1E, 2E) (using 1 as arbitrary value for any unknown in the RHS) gives

$$
\begin{aligned}
& \xi=-2+x \\
& \eta=y-1
\end{aligned}
$$

Shifting is now applied to make $\xi=0$ in order to simplify the rest of the computation

$$
\begin{aligned}
\eta & =\eta-\omega(x, y) \xi \\
& =y-1-\left(-\frac{x+y-3}{-x+y+1}\right)(-2+x) \\
& =\frac{-x^{2}-y^{2}+4 x+2 y-5}{x-y-1} \\
\xi & =0
\end{aligned}
$$

The next step is to determine the canonical coordinates $R, S$. The canonical coordinates map $(x, y) \rightarrow(R, S)$ where $(R, S)$ are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$
\begin{equation*}
\frac{d x}{\xi}=\frac{d y}{\eta}=d S \tag{1}
\end{equation*}
$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x}+\eta \frac{\partial}{\partial y}\right) S(x, y)=1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable $R$ in the canonical coordinates, where $S(R)$. Since $\xi=0$ then in this special case

$$
R=x
$$

$S$ is found from

$$
\begin{aligned}
S & =\int \frac{1}{\eta} d y \\
& =\int \frac{1}{\frac{-x^{2}-y^{2}+4 x+2 y-5}{x-y-1}} d y
\end{aligned}
$$

Which results in

$$
S=\frac{\ln \left(x^{2}+y^{2}-4 x-2 y+5\right)}{2}+\frac{2(2-x) \arctan \left(\frac{2 y-2}{2 x-4}\right)}{2 x-4}
$$

Now that $R, S$ are found, we need to setup the ode in these coordinates. This is done by evaluating

$$
\begin{equation*}
\frac{d S}{d R}=\frac{S_{x}+\omega(x, y) S_{y}}{R_{x}+\omega(x, y) R_{y}} \tag{2}
\end{equation*}
$$

Where in the above $R_{x}, R_{y}, S_{x}, S_{y}$ are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$
\omega(x, y)=-\frac{x+y-3}{-x+y+1}
$$

Evaluating all the partial derivatives gives

$$
\begin{aligned}
R_{x} & =1 \\
R_{y} & =0 \\
S_{x} & =\frac{x+y-3}{x^{2}+y^{2}-4 x-2 y+5} \\
S_{y} & =\frac{-x+y+1}{x^{2}+y^{2}-4 x-2 y+5}
\end{aligned}
$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$
\begin{equation*}
\frac{d S}{d R}=0 \tag{2~A}
\end{equation*}
$$

We now need to express the RHS as function of $R$ only. This is done by solving for $x, y$ in terms of $R, S$ from the result obtained earlier and simplifying. This gives

$$
\frac{d S}{d R}=0
$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordiates $R, S$. Integrating the above gives

$$
\begin{equation*}
S(R)=c_{1} \tag{4}
\end{equation*}
$$

To complete the solution, we just need to transform (4) back to $x, y$ coordinates. This results in

$$
\frac{\ln \left(y^{2}+x^{2}-2 y-4 x+5\right)}{2}-\arctan \left(\frac{y-1}{-2+x}\right)=c_{1}
$$

Which simplifies to

$$
\frac{\ln \left(y^{2}+x^{2}-2 y-4 x+5\right)}{2}-\arctan \left(\frac{y-1}{-2+x}\right)=c_{1}
$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

| Original ode in $x, y$ coordinates | $\begin{gathered} \text { Canonical } \\ \text { coordinates } \\ \text { transformation } \end{gathered}$ | ODE in canonical coordinates $(R, S)$ |
| :---: | :---: | :---: |
| $\frac{d y}{d x}=-\frac{x+y-3}{-x+y+1}$ |  | $\frac{d S}{d R}=0$ |
|  |  |  |
| $\rightarrow \rightarrow+\infty$ |  | $\xrightarrow[\rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow+\rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow]{ }$ |
|  |  | $\xrightarrow{\rightarrow \rightarrow \rightarrow \rightarrow \rightarrow+S(R)}$ |
|  |  | $\xrightarrow[\rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow 2 g \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow]{ }$ |
|  | $R=x$ | $\xrightarrow{\rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow}$ |
|  | S $\quad \ln \left(x^{2}+y^{2}-\right.$ | $\rightarrow-4$ |
|  | $S=\frac{\ln \left(x^{2}+y^{2}-4 x\right.}{2}$ | $\xrightarrow{\rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow R^{+}}$ |
|  | - 2 |  |
|  |  | $\rightarrow$ |
|  |  | $\rightarrow$ |

## Summary

The solution(s) found are the following

$$
\begin{equation*}
\frac{\ln \left(y^{2}+x^{2}-2 y-4 x+5\right)}{2}-\arctan \left(\frac{y-1}{-2+x}\right)=c_{1} \tag{1}
\end{equation*}
$$



Figure 5: Slope field plot

## Verification of solutions

$$
\frac{\ln \left(y^{2}+x^{2}-2 y-4 x+5\right)}{2}-\arctan \left(\frac{y-1}{-2+x}\right)=c_{1}
$$

Verified OK.

Maple trace

```
`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
trying separable
trying inverse linear
trying homogeneous types:
trying homogeneous C
trying homogeneous types:
trying homogeneous D
<- homogeneous successful
<- homogeneous successful`
```

$\checkmark$ Solution by Maple
Time used: 0.015 (sec). Leaf size: 32

```
dsolve(diff(y(x),x)=(x+y(x)-3)/(x-y(x)-1),y(x), singsol=all)
```

$$
y(x)=1+\tan \left(\operatorname{RootOf}\left(2 \_Z+\ln \left(\sec \left(\_Z\right)^{2}\right)+2 \ln (x-2)+2 c_{1}\right)\right)(-x+2)
$$

$\checkmark$ Solution by Mathematica
Time used: 0.058 (sec). Leaf size: 57

```
DSolve[y'[x]==(x+y[x]-3)/(x-y[x]-1),y[x],x,IncludeSingularSolutions -> True]
```

$$
\begin{aligned}
& \text { Solve }\left[2 \arctan \left(\frac{y(x)+x-3}{-y(x)+x-1}\right)=\log \left(\frac{x^{2}+y(x)^{2}-2 y(x)-4 x+5}{2(x-2)^{2}}\right)\right. \\
& \left.+2 \log (x-2)+c_{1}, y(x)\right]
\end{aligned}
$$

## 1.3 problem Example, page 28

1.3.1 Solving as first order ode lie symmetry calculated ode . . . . . . 28

Internal problem ID [4347]
Internal file name [OUTPUT/3840_Sunday_June_05_2022_11_20_33_AM_52930794/index.tex]
Book: Differential and integral calculus, vol II By N. Piskunov. 1974
Section: Chapter 1
Problem number: Example, page 28.
ODE order: 1.
ODE degree: 1 .

The type(s) of ODE detected by this program : "first__order_ode__lie_symmetry_calculated"

Maple gives the following as the ode type

```
[[_homogeneous, `class C`], _rational, [_Abel, `2nd type`, `
    class A`]]
```

$$
y^{\prime}-\frac{2 x+y-1}{4 x+2 y+5}=0
$$

### 1.3.1 Solving as first order ode lie symmetry calculated ode

Writing the ode as

$$
\begin{aligned}
y^{\prime} & =\frac{2 x+y-1}{4 x+2 y+5} \\
y^{\prime} & =\omega(x, y)
\end{aligned}
$$

The condition of Lie symmetry is the linearized PDE given by

$$
\begin{equation*}
\eta_{x}+\omega\left(\eta_{y}-\xi_{x}\right)-\omega^{2} \xi_{y}-\omega_{x} \xi-\omega_{y} \eta=0 \tag{A}
\end{equation*}
$$

The type of this ode is not in the lookup table. To determine $\xi, \eta$ then (A) is solved using ansatz. Making bivariate polynomials of degree 1 to use as anstaz gives

$$
\begin{align*}
\xi & =x a_{2}+y a_{3}+a_{1}  \tag{1E}\\
\eta & =x b_{2}+y b_{3}+b_{1} \tag{2E}
\end{align*}
$$

Where the unknown coefficients are

$$
\left\{a_{1}, a_{2}, a_{3}, b_{1}, b_{2}, b_{3}\right\}
$$

Substituting equations (1E, 2 E ) and $\omega$ into (A) gives

$$
\begin{align*}
b_{2} & +\frac{(2 x+y-1)\left(b_{3}-a_{2}\right)}{4 x+2 y+5}-\frac{(2 x+y-1)^{2} a_{3}}{(4 x+2 y+5)^{2}} \\
& -\left(\frac{2}{4 x+2 y+5}-\frac{4(2 x+y-1)}{(4 x+2 y+5)^{2}}\right)\left(x a_{2}+y a_{3}+a_{1}\right)  \tag{5E}\\
& -\left(\frac{1}{4 x+2 y+5}-\frac{2(2 x+y-1)}{(4 x+2 y+5)^{2}}\right)\left(x b_{2}+y b_{3}+b_{1}\right)=0
\end{align*}
$$

Putting the above in normal form gives

$$
\begin{aligned}
& -\frac{8 x^{2} a_{2}+4 x^{2} a_{3}-16 x^{2} b_{2}-8 x^{2} b_{3}+8 x y a_{2}+4 x y a_{3}-16 x y b_{2}-8 x y b_{3}+2 y^{2} a_{2}+y^{2} a_{3}-4 y^{2} b_{2}-2 y^{2} b_{3}+}{(4 x+2 y} \\
& =0
\end{aligned}
$$

Setting the numerator to zero gives

$$
\begin{align*}
& -8 x^{2} a_{2}-4 x^{2} a_{3}+16 x^{2} b_{2}+8 x^{2} b_{3}-8 x y a_{2}-4 x y a_{3}+16 x y b_{2}+8 x y b_{3}  \tag{6E}\\
& \quad-2 y^{2} a_{2}-y^{2} a_{3}+4 y^{2} b_{2}+2 y^{2} b_{3}-20 x a_{2}+4 x a_{3}+33 x b_{2}+6 x b_{3}-3 y a_{2} \\
& -12 y a_{3}+20 y b_{2}-4 y b_{3}-14 a_{1}+5 a_{2}-a_{3}-7 b_{1}+25 b_{2}-5 b_{3}=0
\end{align*}
$$

Looking at the above PDE shows the following are all the terms with $\{x, y\}$ in them.

$$
\{x, y\}
$$

The following substitution is now made to be able to collect on all terms with $\{x, y\}$ in them

$$
\left\{x=v_{1}, y=v_{2}\right\}
$$

The above PDE (6E) now becomes

$$
\begin{align*}
& -8 a_{2} v_{1}^{2}-8 a_{2} v_{1} v_{2}-2 a_{2} v_{2}^{2}-4 a_{3} v_{1}^{2}-4 a_{3} v_{1} v_{2}-a_{3} v_{2}^{2}+16 b_{2} v_{1}^{2}+16 b_{2} v_{1} v_{2}  \tag{7E}\\
& +4 b_{2} v_{2}^{2}+8 b_{3} v_{1}^{2}+8 b_{3} v_{1} v_{2}+2 b_{3} v_{2}^{2}-20 a_{2} v_{1}-3 a_{2} v_{2}+4 a_{3} v_{1}-12 a_{3} v_{2} \\
& +33 b_{2} v_{1}+20 b_{2} v_{2}+6 b_{3} v_{1}-4 b_{3} v_{2}-14 a_{1}+5 a_{2}-a_{3}-7 b_{1}+25 b_{2}-5 b_{3}=0
\end{align*}
$$

Collecting the above on the terms $v_{i}$ introduced, and these are

$$
\left\{v_{1}, v_{2}\right\}
$$

Equation (7E) now becomes

$$
\begin{align*}
& \left(-8 a_{2}-4 a_{3}+16 b_{2}+8 b_{3}\right) v_{1}^{2}+\left(-8 a_{2}-4 a_{3}+16 b_{2}+8 b_{3}\right) v_{1} v_{2}  \tag{8E}\\
& \quad+\left(-20 a_{2}+4 a_{3}+33 b_{2}+6 b_{3}\right) v_{1}+\left(-2 a_{2}-a_{3}+4 b_{2}+2 b_{3}\right) v_{2}^{2} \\
& \quad+\left(-3 a_{2}-12 a_{3}+20 b_{2}-4 b_{3}\right) v_{2}-14 a_{1}+5 a_{2}-a_{3}-7 b_{1}+25 b_{2}-5 b_{3}=0
\end{align*}
$$

Setting each coefficients in (8E) to zero gives the following equations to solve

$$
\begin{array}{r}
-20 a_{2}+4 a_{3}+33 b_{2}+6 b_{3}=0 \\
-8 a_{2}-4 a_{3}+16 b_{2}+8 b_{3}=0 \\
-3 a_{2}-12 a_{3}+20 b_{2}-4 b_{3}=0 \\
-2 a_{2}-a_{3}+4 b_{2}+2 b_{3}=0 \\
-14 a_{1}+5 a_{2}-a_{3}-7 b_{1}+25 b_{2}-5 b_{3}=0
\end{array}
$$

Solving the above equations for the unknowns gives

$$
\begin{aligned}
& a_{1}=a_{1} \\
& a_{2}=2 b_{2} \\
& a_{3}=b_{2} \\
& b_{1}=-2 a_{1}+\frac{9 b_{2}}{2} \\
& b_{2}=b_{2} \\
& b_{3}=\frac{b_{2}}{2}
\end{aligned}
$$

Substituting the above solution in the anstaz (1E,2E) (using 1 as arbitrary value for any unknown in the RHS) gives

$$
\begin{aligned}
& \xi=1 \\
& \eta=-2
\end{aligned}
$$

Shifting is now applied to make $\xi=0$ in order to simplify the rest of the computation

$$
\begin{align*}
\eta & =\eta-\omega(x, y) \xi \\
& =-2-\left(\frac{2 x+y-1}{4 x+2 y+5}\right)  \tag{1}\\
& =\frac{-10 x-5 y-9}{4 x+2 y+5} \\
\xi & =0
\end{align*}
$$

The next step is to determine the canonical coordinates $R, S$. The canonical coordinates map $(x, y) \rightarrow(R, S)$ where $(R, S)$ are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$
\begin{equation*}
\frac{d x}{\xi}=\frac{d y}{\eta}=d S \tag{1}
\end{equation*}
$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x}+\eta \frac{\partial}{\partial y}\right) S(x, y)=1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable $R$ in the canonical coordinates, where $S(R)$. Since $\xi=0$ then in this special case

$$
R=x
$$

$S$ is found from

$$
\begin{aligned}
S & =\int \frac{1}{\eta} d y \\
& =\int \frac{1}{\frac{-10 x-5 y-9}{4 x+2 y+5}} d y
\end{aligned}
$$

Which results in

$$
S=-\frac{2 y}{5}-\frac{7 \ln (10 x+5 y+9)}{25}
$$

Now that $R, S$ are found, we need to setup the ode in these coordinates. This is done by evaluating

$$
\begin{equation*}
\frac{d S}{d R}=\frac{S_{x}+\omega(x, y) S_{y}}{R_{x}+\omega(x, y) R_{y}} \tag{2}
\end{equation*}
$$

Where in the above $R_{x}, R_{y}, S_{x}, S_{y}$ are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$
\omega(x, y)=\frac{2 x+y-1}{4 x+2 y+5}
$$

Evaluating all the partial derivatives gives

$$
\begin{aligned}
R_{x} & =1 \\
R_{y} & =0 \\
S_{x} & =-\frac{14}{50 x+25 y+45} \\
S_{y} & =\frac{-4 x-2 y-5}{10 x+5 y+9}
\end{aligned}
$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$
\begin{equation*}
\frac{d S}{d R}=-\frac{1}{5} \tag{2~A}
\end{equation*}
$$

We now need to express the RHS as function of $R$ only. This is done by solving for $x, y$ in terms of $R, S$ from the result obtained earlier and simplifying. This gives

$$
\frac{d S}{d R}=-\frac{1}{5}
$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordiates $R, S$. Integrating the above gives

$$
\begin{equation*}
S(R)=-\frac{R}{5}+c_{1} \tag{4}
\end{equation*}
$$

To complete the solution, we just need to transform (4) back to $x, y$ coordinates. This results in

$$
-\frac{2 y}{5}-\frac{7 \ln (10 x+5 y+9)}{25}=-\frac{x}{5}+c_{1}
$$

Which simplifies to

$$
-\frac{2 y}{5}-\frac{7 \ln (10 x+5 y+9)}{25}=-\frac{x}{5}+c_{1}
$$

Which gives

$$
y=\frac{\mathrm{e}^{-\operatorname{LambertW}\left(\frac{2 e^{\frac{25 x}{7}+\frac{18}{7}-\frac{25 c_{1}}{7}} 7}{7}\right)+\frac{25 x}{7}+\frac{18}{7}-\frac{25 c_{1}}{7}}}{5}-2 x-\frac{9}{5}
$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.


## Summary

The solution(s) found are the following

$$
\begin{equation*}
y=\frac{\mathrm{e}^{-\operatorname{LambertW}\left(\frac{2 e^{\frac{25 x}{7}+\frac{18}{7}-\frac{25 c_{1}}{7}} 7}{7}\right)+\frac{25 x}{7}+\frac{18}{7}-\frac{25 c_{1}}{7}}}{5}-2 x-\frac{9}{5} \tag{1}
\end{equation*}
$$



Figure 6: Slope field plot

## Verification of solutions

$$
y=\frac{\mathrm{e}^{-\operatorname{LambertW}\left(\frac{2 \mathrm{e}^{\frac{25 x}{7}+\frac{18}{7}-\frac{25 c_{1}}{7}} 7}{7}\right)+\frac{25 x}{7}+\frac{18}{7}-\frac{25 c_{1}}{7}}}{5}-2 x-\frac{9}{5}
$$

Verified OK.

Maple trace

```
`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
trying separable
trying inverse linear
trying homogeneous types:
trying homogeneous C
1st order, trying the canonical coordinates of the invariance group
    -> Calling odsolve with the ODE`, diff(y(x), x) = -2, y(x)` *** Sublevel 2
    Methods for first order ODEs:
    --- Trying classification methods ---
    trying a quadrature
    trying 1st order linear
    <- 1st order linear successful
<- 1st order, canonical coordinates successful
<- homogeneous successful`
```

$\checkmark$ Solution by Maple
Time used: 0.015 (sec). Leaf size: 23

```
dsolve(diff(y(x),x)=(2*x+y(x)-1)/(4*x+2*y(x)+5),y(x), singsol=all)
```

$$
y(x)=\frac{7 \text { LambertW }\left(\frac{2 \mathrm{e}^{\frac{18}{7}+\frac{25 x}{7}-\frac{25 c_{1}}{7}}}{7}\right)}{10}-\frac{9}{5}-2 x
$$

$\checkmark$ Solution by Mathematica
Time used: 3.875 (sec). Leaf size: 41
DSolve[y'[x]==(2*x+y[x]-1)/(4*x+2*y[x]+5),y[x],x,IncludeSingularSolutions $->$ True]

$$
\begin{aligned}
& y(x) \rightarrow \frac{7}{10} W\left(-e^{\frac{25 x}{7}-1+c_{1}}\right)-2 x-\frac{9}{5} \\
& y(x) \rightarrow-2 x-\frac{9}{5}
\end{aligned}
$$

## 1.4 problem Example, page 30

1.4.1 Solving as linear ode . . . . . . . . . . . . . . . . . . . . . . . . 36
1.4.2 Solving as first order ode lie symmetry lookup ode . . . . . . . 38
1.4.3 Solving as exact ode . . . . . . . . . . . . . . . . . . . . . . . . 42
1.4.4 Maple step by step solution . . . . . . . . . . . . . . . . . . . . 47

Internal problem ID [4348]
Internal file name [OUTPUT/3841_Sunday_June_05_2022_11_20_41_AM_63362806/index.tex]
Book: Differential and integral calculus, vol II By N. Piskunov. 1974
Section: Chapter 1
Problem number: Example, page 30.
ODE order: 1.
ODE degree: 1 .

The type(s) of ODE detected by this program : "linear", "exactWithIntegrationFactor", "first_order_ode_lie_symmetry_lookup"

Maple gives the following as the ode type
[_linear]

$$
y^{\prime}-\frac{2 y}{x+1}=(x+1)^{2}
$$

### 1.4.1 Solving as linear ode

Entering Linear first order ODE solver. In canonical form a linear first order is

$$
y^{\prime}+p(x) y=q(x)
$$

Where here

$$
\begin{aligned}
& p(x)=-\frac{2}{x+1} \\
& q(x)=(x+1)^{2}
\end{aligned}
$$

Hence the ode is

$$
y^{\prime}-\frac{2 y}{x+1}=(x+1)^{2}
$$

The integrating factor $\mu$ is

$$
\begin{aligned}
\mu & =\mathrm{e}^{\int-\frac{2}{x+1} d x} \\
& =\frac{1}{(x+1)^{2}}
\end{aligned}
$$

The ode becomes

$$
\begin{aligned}
\frac{\mathrm{d}}{\mathrm{~d} x}(\mu y) & =(\mu)\left((x+1)^{2}\right) \\
\frac{\mathrm{d}}{\mathrm{~d} x}\left(\frac{y}{(x+1)^{2}}\right) & =\left(\frac{1}{(x+1)^{2}}\right)\left((x+1)^{2}\right) \\
\mathrm{d}\left(\frac{y}{(x+1)^{2}}\right) & =\mathrm{d} x
\end{aligned}
$$

Integrating gives

$$
\begin{aligned}
& \frac{y}{(x+1)^{2}}=\int \mathrm{d} x \\
& \frac{y}{(x+1)^{2}}=x+c_{1}
\end{aligned}
$$

Dividing both sides by the integrating factor $\mu=\frac{1}{(x+1)^{2}}$ results in

$$
y=x(x+1)^{2}+c_{1}(x+1)^{2}
$$

which simplifies to

$$
y=(x+1)^{2}\left(x+c_{1}\right)
$$

Summary
The solution(s) found are the following

$$
\begin{equation*}
y=(x+1)^{2}\left(x+c_{1}\right) \tag{1}
\end{equation*}
$$



Figure 7: Slope field plot
Verification of solutions

$$
y=(x+1)^{2}\left(x+c_{1}\right)
$$

Verified OK.

### 1.4.2 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$
\begin{aligned}
& y^{\prime}=\frac{x^{3}+3 x^{2}+3 x+2 y+1}{x+1} \\
& y^{\prime}=\omega(x, y)
\end{aligned}
$$

The condition of Lie symmetry is the linearized PDE given by

$$
\begin{equation*}
\eta_{x}+\omega\left(\eta_{y}-\xi_{x}\right)-\omega^{2} \xi_{y}-\omega_{x} \xi-\omega_{y} \eta=0 \tag{A}
\end{equation*}
$$

The type of this ode is known. It is of type linear. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find $\xi, \eta$

Table 1: Lie symmetry infinitesimal lookup table for known first order ODE's

| ODE class | Form | $\xi$ | $\eta$ |
| :--- | :--- | :--- | :--- |
| linear ode | $y^{\prime}=f(x) y(x)+g(x)$ | 0 | $e^{\int f d x}$ |
| separable ode | $y^{\prime}=f(x) g(y)$ | $\frac{1}{f}$ | 0 |
| quadrature ode | $y^{\prime}=f(x)$ | 0 | 1 |
| quadrature ode | $y^{\prime}=g(y)$ | 1 | 0 |
| homogeneous ODEs of <br> Class A | $y^{\prime}=f\left(\frac{y}{x}\right)$ | $x$ | $y$ |
| homogeneous ODEs of <br> Class C | $y^{\prime}=(a+b x+c y)^{\frac{n}{m}}$ | 1 | $-\frac{b}{c}$ |
| homogeneous class D | $y^{\prime}=\frac{y}{x}+g(x) F\left(\frac{y}{x}\right)$ | $x^{2}$ | $x y$ |
| First order <br> form ID 1 | $y^{2}=g(x) e^{h(x)+b y}+f(x)$ | $\frac{e^{-\int b f(x) d x-h(x)}}{g(x)}$ | $\frac{f(x) e^{-\int b f(x) d x-h(x)}}{g(x)}$ |
| polynomial type ode | $y^{\prime}=\frac{a_{1} x+b_{1} y+c_{1}}{a_{2} x+b_{2} y+c_{2}}$ | $\frac{a_{1} b_{2} x-a_{2} b_{1} x-b_{1} c_{2}+b_{2} c_{1}}{a_{1} b_{2}-a_{2} b_{1}}$ | $\frac{a_{1} b_{2} y-a_{2} b_{1} y-a_{1} c_{2}-a_{2} c_{1}}{a_{1} b_{2}-a_{2} b_{1}}$ |
| Bernoulli ode | $y^{\prime}=f(x) y+g(x) y^{n}$ | 0 | $e^{-\int(n-1) f(x) d x} y^{n}$ |
| Reduced Riccati | $y^{\prime}=f_{1}(x) y+f_{2}(x) y^{2}$ | 0 | $e^{-\int f_{1} d x}$ |

The above table shows that

$$
\begin{align*}
& \xi(x, y)=0 \\
& \eta(x, y)=(x+1)^{2} \tag{A1}
\end{align*}
$$

The next step is to determine the canonical coordinates $R, S$. The canonical coordinates map $(x, y) \rightarrow(R, S)$ where $(R, S)$ are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$
\begin{equation*}
\frac{d x}{\xi}=\frac{d y}{\eta}=d S \tag{1}
\end{equation*}
$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x}+\eta \frac{\partial}{\partial y}\right) S(x, y)=1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable $R$ in the
canonical coordinates, where $S(R)$. Since $\xi=0$ then in this special case

$$
R=x
$$

$S$ is found from

$$
\begin{aligned}
S & =\int \frac{1}{\eta} d y \\
& =\int \frac{1}{(x+1)^{2}} d y
\end{aligned}
$$

Which results in

$$
S=\frac{y}{(x+1)^{2}}
$$

Now that $R, S$ are found, we need to setup the ode in these coordinates. This is done by evaluating

$$
\begin{equation*}
\frac{d S}{d R}=\frac{S_{x}+\omega(x, y) S_{y}}{R_{x}+\omega(x, y) R_{y}} \tag{2}
\end{equation*}
$$

Where in the above $R_{x}, R_{y}, S_{x}, S_{y}$ are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$
\omega(x, y)=\frac{x^{3}+3 x^{2}+3 x+2 y+1}{x+1}
$$

Evaluating all the partial derivatives gives

$$
\begin{aligned}
R_{x} & =1 \\
R_{y} & =0 \\
S_{x} & =-\frac{2 y}{(x+1)^{3}} \\
S_{y} & =\frac{1}{(x+1)^{2}}
\end{aligned}
$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$
\begin{equation*}
\frac{d S}{d R}=1 \tag{2~A}
\end{equation*}
$$

We now need to express the RHS as function of $R$ only. This is done by solving for $x, y$ in terms of $R, S$ from the result obtained earlier and simplifying. This gives

$$
\frac{d S}{d R}=1
$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordiates $R, S$. Integrating the above gives

$$
\begin{equation*}
S(R)=R+c_{1} \tag{4}
\end{equation*}
$$

To complete the solution, we just need to transform (4) back to $x, y$ coordinates. This results in

$$
\frac{y}{(x+1)^{2}}=x+c_{1}
$$

Which simplifies to

$$
\frac{y}{(x+1)^{2}}=x+c_{1}
$$

Which gives

$$
y=(x+1)^{2}\left(x+c_{1}\right)
$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

| Original ode in $x, y$ coordinates | Canonical coordinates transformation | ODE in canonical coordinates $(R, S)$ |
| :---: | :---: | :---: |
| $\frac{d y}{d x}=\frac{x^{3}+3 x^{2}+3 x+2 y+1}{x+1}$ |  | $\frac{d S}{d R}=1$ |
|  |  |  |
|  |  |  |
| P P P 4 |  |  |
|  |  |  |
| ${ }_{4}{ }_{4} \rightarrow$ |  | O刀口 |
|  | $R=x$ |  |
|  | $y$ |  |
|  | $S=\frac{}{(x+1)^{2}}$ |  |
|  | $(x+1)^{2}$ |  |
|  |  |  |
|  |  |  |
|  |  |  |
|  |  |  |

## Summary

The solution(s) found are the following

$$
\begin{equation*}
y=(x+1)^{2}\left(x+c_{1}\right) \tag{1}
\end{equation*}
$$



Figure 8: Slope field plot

## Verification of solutions

$$
y=(x+1)^{2}\left(x+c_{1}\right)
$$

Verified OK.

### 1.4.3 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)
To solve an ode of the form

$$
\begin{equation*}
M(x, y)+N(x, y) \frac{d y}{d x}=0 \tag{A}
\end{equation*}
$$

We assume there exists a function $\phi(x, y)=c$ where $c$ is constant, that satisfies the ode. Taking derivative of $\phi$ w.r.t. $x$ gives

$$
\frac{d}{d x} \phi(x, y)=0
$$

Hence

$$
\begin{equation*}
\frac{\partial \phi}{\partial x}+\frac{\partial \phi}{\partial y} \frac{d y}{d x}=0 \tag{B}
\end{equation*}
$$

Comparing ( $\mathrm{A}, \mathrm{B}$ ) shows that

$$
\begin{aligned}
& \frac{\partial \phi}{\partial x}=M \\
& \frac{\partial \phi}{\partial y}=N
\end{aligned}
$$

But since $\frac{\partial^{2} \phi}{\partial x \partial y}=\frac{\partial^{2} \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$
\frac{\partial M}{\partial y}=\frac{\partial N}{\partial x}
$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^{2} \phi}{\partial x \partial y}=\frac{\partial^{2} \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$
\begin{equation*}
M(x, y) \mathrm{d} x+N(x, y) \mathrm{d} y=0 \tag{1~A}
\end{equation*}
$$

Therefore

$$
\begin{align*}
\mathrm{d} y & =\left(\frac{2 y}{x+1}+(x+1)^{2}\right) \mathrm{d} x \\
\left(-\frac{2 y}{x+1}-(x+1)^{2}\right) \mathrm{d} x+\mathrm{d} y & =0 \tag{2~A}
\end{align*}
$$

Comparing (1A) and (2A) shows that

$$
\begin{aligned}
& M(x, y)=-\frac{2 y}{x+1}-(x+1)^{2} \\
& N(x, y)=1
\end{aligned}
$$

The next step is to determine if the ODE is is exact or not. The ODE is exact when the following condition is satisfied

$$
\frac{\partial M}{\partial y}=\frac{\partial N}{\partial x}
$$

Using result found above gives

$$
\begin{aligned}
\frac{\partial M}{\partial y} & =\frac{\partial}{\partial y}\left(-\frac{2 y}{x+1}-(x+1)^{2}\right) \\
& =-\frac{2}{x+1}
\end{aligned}
$$

And

$$
\begin{aligned}
\frac{\partial N}{\partial x} & =\frac{\partial}{\partial x}(1) \\
& =0
\end{aligned}
$$

Since $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$
\begin{aligned}
A & =\frac{1}{N}\left(\frac{\partial M}{\partial y}-\frac{\partial N}{\partial x}\right) \\
& =1\left(\left(-\frac{2}{x+1}\right)-(0)\right) \\
& =-\frac{2}{x+1}
\end{aligned}
$$

Since $A$ does not depend on $y$, then it can be used to find an integrating factor. The integrating factor $\mu$ is

$$
\begin{aligned}
\mu & =e^{\int A \mathrm{~d} x} \\
& =e^{\int-\frac{2}{x+1} \mathrm{~d} x}
\end{aligned}
$$

The result of integrating gives

$$
\begin{aligned}
\mu & =e^{-2 \ln (x+1)} \\
& =\frac{1}{(x+1)^{2}}
\end{aligned}
$$

$M$ and $N$ are multiplied by this integrating factor, giving new $M$ and new $N$ which are called $\bar{M}$ and $\bar{N}$ for now so not to confuse them with the original $M$ and $N$.

$$
\begin{aligned}
\bar{M} & =\mu M \\
& =\frac{1}{(x+1)^{2}}\left(-\frac{2 y}{x+1}-(x+1)^{2}\right) \\
& =\frac{-x^{3}-3 x^{2}-3 x-2 y-1}{(x+1)^{3}}
\end{aligned}
$$

And

$$
\begin{aligned}
\bar{N} & =\mu N \\
& =\frac{1}{(x+1)^{2}}(1) \\
& =\frac{1}{(x+1)^{2}}
\end{aligned}
$$

Now a modified ODE is ontained from the original ODE, which is exact and can be solved. The modified ODE is

$$
\begin{aligned}
\bar{M}+\bar{N} \frac{\mathrm{~d} y}{\mathrm{~d} x} & =0 \\
\left(\frac{-x^{3}-3 x^{2}-3 x-2 y-1}{(x+1)^{3}}\right)+\left(\frac{1}{(x+1)^{2}}\right) \frac{\mathrm{d} y}{\mathrm{~d} x} & =0
\end{aligned}
$$

The following equations are now set up to solve for the function $\phi(x, y)$

$$
\begin{align*}
& \frac{\partial \phi}{\partial x}=\bar{M}  \tag{1}\\
& \frac{\partial \phi}{\partial y}=\bar{N} \tag{2}
\end{align*}
$$

Integrating (1) w.r.t. $x$ gives

$$
\begin{align*}
\int \frac{\partial \phi}{\partial x} \mathrm{~d} x & =\int \bar{M} \mathrm{~d} x \\
\int \frac{\partial \phi}{\partial x} \mathrm{~d} x & =\int \frac{-x^{3}-3 x^{2}-3 x-2 y-1}{(x+1)^{3}} \mathrm{~d} x \\
\phi & =-x+\frac{y}{(x+1)^{2}}+f(y) \tag{3}
\end{align*}
$$

Where $f(y)$ is used for the constant of integration since $\phi$ is a function of both $x$ and $y$. Taking derivative of equation (3) w.r.t $y$ gives

$$
\begin{equation*}
\frac{\partial \phi}{\partial y}=\frac{1}{(x+1)^{2}}+f^{\prime}(y) \tag{4}
\end{equation*}
$$

But equation (2) says that $\frac{\partial \phi}{\partial y}=\frac{1}{(x+1)^{2}}$. Therefore equation (4) becomes

$$
\begin{equation*}
\frac{1}{(x+1)^{2}}=\frac{1}{(x+1)^{2}}+f^{\prime}(y) \tag{5}
\end{equation*}
$$

Solving equation (5) for $f^{\prime}(y)$ gives

$$
f^{\prime}(y)=0
$$

Therefore

$$
f(y)=c_{1}
$$

Where $c_{1}$ is constant of integration. Substituting this result for $f(y)$ into equation (3) gives $\phi$

$$
\phi=-x+\frac{y}{(x+1)^{2}}+c_{1}
$$

But since $\phi$ itself is a constant function, then let $\phi=c_{2}$ where $c_{2}$ is new constant and combining $c_{1}$ and $c_{2}$ constants into new constant $c_{1}$ gives the solution as

$$
c_{1}=-x+\frac{y}{(x+1)^{2}}
$$

The solution becomes

$$
y=(x+1)^{2}\left(x+c_{1}\right)
$$

Summary
The solution(s) found are the following

$$
\begin{equation*}
y=(x+1)^{2}\left(x+c_{1}\right) \tag{1}
\end{equation*}
$$



Figure 9: Slope field plot

## Verification of solutions

$$
y=(x+1)^{2}\left(x+c_{1}\right)
$$

Verified OK.

### 1.4.4 Maple step by step solution

Let's solve
$y^{\prime}-\frac{2 y}{x+1}=(x+1)^{2}$

- Highest derivative means the order of the ODE is 1
$y^{\prime}$
- Isolate the derivative
$y^{\prime}=\frac{2 y}{x+1}+(x+1)^{2}$
- Group terms with $y$ on the lhs of the ODE and the rest on the rhs of the ODE $y^{\prime}-\frac{2 y}{x+1}=(x+1)^{2}$
- The ODE is linear; multiply by an integrating factor $\mu(x)$
$\mu(x)\left(y^{\prime}-\frac{2 y}{x+1}\right)=\mu(x)(x+1)^{2}$
- Assume the lhs of the ODE is the total derivative $\frac{d}{d x}(\mu(x) y)$
$\mu(x)\left(y^{\prime}-\frac{2 y}{x+1}\right)=\mu^{\prime}(x) y+\mu(x) y^{\prime}$
- Isolate $\mu^{\prime}(x)$
$\mu^{\prime}(x)=-\frac{2 \mu(x)}{x+1}$
- Solve to find the integrating factor
$\mu(x)=\frac{1}{(x+1)^{2}}$
- Integrate both sides with respect to $x$
$\int\left(\frac{d}{d x}(\mu(x) y)\right) d x=\int \mu(x)(x+1)^{2} d x+c_{1}$
- Evaluate the integral on the lhs

$$
\mu(x) y=\int \mu(x)(x+1)^{2} d x+c_{1}
$$

- $\quad$ Solve for $y$
$y=\frac{\int \mu(x)(x+1)^{2} d x+c_{1}}{\mu(x)}$
- $\quad$ Substitute $\mu(x)=\frac{1}{(x+1)^{2}}$

$$
y=(x+1)^{2}\left(\int 1 d x+c_{1}\right)
$$

- Evaluate the integrals on the rhs

$$
y=(x+1)^{2}\left(x+c_{1}\right)
$$

Maple trace

```
`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
<- 1st order linear successful`
```

Solution by Maple
Time used: 0.0 (sec). Leaf size: 13

```
dsolve(diff (y (x),x)-2*y(x)/(1+x)=(x+1)^2,y(x), singsol=all)
    y(x)=(x+\mp@subsup{c}{1}{})(1+x\mp@subsup{)}{}{2}
```

$\sqrt{ }$ Solution by Mathematica
Time used: 0.031 (sec). Leaf size: 15

```
DSolve[y'[x]-2*y[x]/(1+x)==(x+1)~2,y[x],x,IncludeSingularSolutions -> True]
```

$$
y(x) \rightarrow(x+1)^{2}\left(x+c_{1}\right)
$$

## 1.5 problem Example, page 33

1.5.1 Solving as first order ode lie symmetry lookup ode . . . . . . . 49
1.5.2 Solving as bernoulli ode . . . . . . . . . . . . . . . . . . . . . . 53

Internal problem ID [4349]
Internal file name [OUTPUT/3842_Sunday_June_05_2022_11_20_49_AM_77102453/index.tex]
Book: Differential and integral calculus, vol II By N. Piskunov. 1974
Section: Chapter 1
Problem number: Example, page 33.
ODE order: 1.
ODE degree: 1 .

The type(s) of ODE detected by this program : "bernoulli", "first_order__ode_lie_symmetry__lookup"

Maple gives the following as the ode type
[_Bernoulli]

$$
y^{\prime}+x y-x^{3} y^{3}=0
$$

### 1.5.1 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$
\begin{aligned}
& y^{\prime}=y^{3} x^{3}-x y \\
& y^{\prime}=\omega(x, y)
\end{aligned}
$$

The condition of Lie symmetry is the linearized PDE given by

$$
\begin{equation*}
\eta_{x}+\omega\left(\eta_{y}-\xi_{x}\right)-\omega^{2} \xi_{y}-\omega_{x} \xi-\omega_{y} \eta=0 \tag{A}
\end{equation*}
$$

The type of this ode is known. It is of type Bernoulli. Therefore we do not need to solve the $\operatorname{PDE}(A)$, and can just use the lookup table shown below to find $\xi, \eta$

Table 4: Lie symmetry infinitesimal lookup table for known first order ODE's

| ODE class | Form | $\xi$ | $\eta$ |
| :---: | :---: | :---: | :---: |
| linear ode | $y^{\prime}=f(x) y(x)+g(x)$ | 0 | $e^{\int f d x}$ |
| separable ode | $y^{\prime}=f(x) g(y)$ | $\frac{1}{f}$ | 0 |
| quadrature ode | $y^{\prime}=f(x)$ | 0 | 1 |
| quadrature ode | $y^{\prime}=g(y)$ | 1 | 0 |
| homogeneous ODEs of Class A | $y^{\prime}=f\left(\frac{y}{x}\right)$ | $x$ | $y$ |
| homogeneous ODEs of Class C | $y^{\prime}=(a+b x+c y)^{\frac{n}{m}}$ | 1 | $-\frac{b}{c}$ |
| homogeneous class D | $y^{\prime}=\frac{y}{x}+g(x) F\left(\frac{y}{x}\right)$ | $x^{2}$ | $x y$ |
| First order special form ID 1 | $y^{\prime}=g(x) e^{h(x)+b y}+f(x)$ | $\frac{e^{-\int b f(x) d x-h(x)}}{g(x)}$ | $\frac{f(x) e^{-\int b f(x) d x-h(x)}}{g(x)}$ |
| polynomial type ode | $y^{\prime}=\frac{a_{1} x+b_{1} y+c_{1}}{a_{2} x+b_{2} y+c_{2}}$ | $\frac{a_{1} b_{2} x-a_{2} b_{1} x-b_{1} c_{2}+b_{2} c_{1}}{a_{1} b_{2}-a_{2} b_{1}}$ | $\frac{a_{1} b_{2} y-a_{2} b_{1} y-a_{1} c_{2}-a_{2} c_{1}}{a_{1} b_{2}-a_{2} b_{1}}$ |
| Bernoulli ode | $y^{\prime}=f(x) y+g(x) y^{n}$ | 0 | $e^{-\int(n-1) f(x) d x} y^{n}$ |
| Reduced Riccati | $y^{\prime}=f_{1}(x) y+f_{2}(x) y^{2}$ | 0 | $e^{-\int f_{1} d x}$ |

The above table shows that

$$
\begin{align*}
& \xi(x, y)=0 \\
& \eta(x, y)=y^{3} \mathrm{e}^{x^{2}} \tag{A1}
\end{align*}
$$

The next step is to determine the canonical coordinates $R, S$. The canonical coordinates $\operatorname{map}(x, y) \rightarrow(R, S)$ where $(R, S)$ are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$
\begin{equation*}
\frac{d x}{\xi}=\frac{d y}{\eta}=d S \tag{1}
\end{equation*}
$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x}+\eta \frac{\partial}{\partial y}\right) S(x, y)=1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable $R$ in the
canonical coordinates, where $S(R)$. Since $\xi=0$ then in this special case

$$
R=x
$$

$S$ is found from

$$
\begin{aligned}
S & =\int \frac{1}{\eta} d y \\
& =\int \frac{1}{y^{3} \mathrm{e}^{x^{2}}} d y
\end{aligned}
$$

Which results in

$$
S=-\frac{\mathrm{e}^{-x^{2}}}{2 y^{2}}
$$

Now that $R, S$ are found, we need to setup the ode in these coordinates. This is done by evaluating

$$
\begin{equation*}
\frac{d S}{d R}=\frac{S_{x}+\omega(x, y) S_{y}}{R_{x}+\omega(x, y) R_{y}} \tag{2}
\end{equation*}
$$

Where in the above $R_{x}, R_{y}, S_{x}, S_{y}$ are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$
\omega(x, y)=y^{3} x^{3}-x y
$$

Evaluating all the partial derivatives gives

$$
\begin{aligned}
R_{x} & =1 \\
R_{y} & =0 \\
S_{x} & =\frac{x \mathrm{e}^{-x^{2}}}{y^{2}} \\
S_{y} & =\frac{\mathrm{e}^{-x^{2}}}{y^{3}}
\end{aligned}
$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$
\begin{equation*}
\frac{d S}{d R}=x^{3} \mathrm{e}^{-x^{2}} \tag{2~A}
\end{equation*}
$$

We now need to express the RHS as function of $R$ only. This is done by solving for $x, y$ in terms of $R, S$ from the result obtained earlier and simplifying. This gives

$$
\frac{d S}{d R}=R^{3} \mathrm{e}^{-R^{2}}
$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordiates $R, S$. Integrating the above gives

$$
\begin{equation*}
S(R)=-\frac{\left(R^{2}+1\right) \mathrm{e}^{-R^{2}}}{2}+c_{1} \tag{4}
\end{equation*}
$$

To complete the solution, we just need to transform (4) back to $x, y$ coordinates. This results in

$$
-\frac{\mathrm{e}^{-x^{2}}}{2 y^{2}}=-\frac{\left(x^{2}+1\right) \mathrm{e}^{-x^{2}}}{2}+c_{1}
$$

Which simplifies to

$$
-\frac{\mathrm{e}^{-x^{2}}}{2 y^{2}}=-\frac{\left(x^{2}+1\right) \mathrm{e}^{-x^{2}}}{2}+c_{1}
$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

| Original ode in $x, y$ coordinates | Canonical coordinates transformation | ODE in canonical coordinates $(R, S)$ |
| :---: | :---: | :---: |
| $\frac{d y}{d x}=y^{3} x^{3}-x y$ |  | $\frac{d S}{d R}=R^{3} \mathrm{e}^{-R^{2}}$ |
|  |  |  |
|  |  | $\xrightarrow[\rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow+]{ }$ |
|  |  |  |
|  |  |  |
| $\pm \rightarrow \rightarrow \rightarrow \rightarrow-\infty$ |  | $\xrightarrow{\rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow+}$ |
|  | $S=-\mathrm{e}^{-x^{2}}$ | $\xrightarrow[\rightarrow \rightarrow-4 \rightarrow \rightarrow- \pm]{ }$ |
|  | $S=-\frac{2 y^{2}}{}$ | $\xrightarrow[\rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow+]{ }$ |
| -1. ${ }^{\text {a }}$ |  | $\xrightarrow[\rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow+]{ } \xrightarrow[\rightarrow \rightarrow \rightarrow \rightarrow]{ }$ |
|  |  | $\xrightarrow[\rightarrow \rightarrow \rightarrow-]{ }$ |
|  |  | $\xrightarrow[\rightarrow \rightarrow \rightarrow \rightarrow]{ }$ |

## Summary

The solution(s) found are the following

$$
\begin{equation*}
-\frac{\mathrm{e}^{-x^{2}}}{2 y^{2}}=-\frac{\left(x^{2}+1\right) \mathrm{e}^{-x^{2}}}{2}+c_{1} \tag{1}
\end{equation*}
$$



Figure 10: Slope field plot
Verification of solutions

$$
-\frac{\mathrm{e}^{-x^{2}}}{2 y^{2}}=-\frac{\left(x^{2}+1\right) \mathrm{e}^{-x^{2}}}{2}+c_{1}
$$

Verified OK.

### 1.5.2 Solving as bernoulli ode

In canonical form, the ODE is

$$
\begin{aligned}
y^{\prime} & =F(x, y) \\
& =y^{3} x^{3}-x y
\end{aligned}
$$

This is a Bernoulli ODE.

$$
\begin{equation*}
y^{\prime}=-x y+x^{3} y^{3} \tag{1}
\end{equation*}
$$

The standard Bernoulli ODE has the form

$$
\begin{equation*}
y^{\prime}=f_{0}(x) y+f_{1}(x) y^{n} \tag{2}
\end{equation*}
$$

The first step is to divide the above equation by $y^{n}$ which gives

$$
\begin{equation*}
\frac{y^{\prime}}{y^{n}}=f_{0}(x) y^{1-n}+f_{1}(x) \tag{3}
\end{equation*}
$$

The next step is use the substitution $w=y^{1-n}$ in equation (3) which generates a new ODE in $w(x)$ which will be linear and can be easily solved using an integrating factor. Backsubstitution then gives the solution $y(x)$ which is what we want.

This method is now applied to the ODE at hand. Comparing the ODE (1) With (2) Shows that

$$
\begin{aligned}
f_{0}(x) & =-x \\
f_{1}(x) & =x^{3} \\
n & =3
\end{aligned}
$$

Dividing both sides of ODE (1) by $y^{n}=y^{3}$ gives

$$
\begin{equation*}
y^{\prime} \frac{1}{y^{3}}=-\frac{x}{y^{2}}+x^{3} \tag{4}
\end{equation*}
$$

Let

$$
\begin{align*}
w & =y^{1-n} \\
& =\frac{1}{y^{2}} \tag{5}
\end{align*}
$$

Taking derivative of equation (5) w.r.t $x$ gives

$$
\begin{equation*}
w^{\prime}=-\frac{2}{y^{3}} y^{\prime} \tag{6}
\end{equation*}
$$

Substituting equations (5) and (6) into equation (4) gives

$$
\begin{align*}
-\frac{w^{\prime}(x)}{2} & =-w(x) x+x^{3} \\
w^{\prime} & =-2 x^{3}+2 x w \tag{7}
\end{align*}
$$

The above now is a linear ODE in $w(x)$ which is now solved.
Entering Linear first order ODE solver. In canonical form a linear first order is

$$
w^{\prime}(x)+p(x) w(x)=q(x)
$$

Where here

$$
\begin{aligned}
& p(x)=-2 x \\
& q(x)=-2 x^{3}
\end{aligned}
$$

Hence the ode is

$$
w^{\prime}(x)-2 w(x) x=-2 x^{3}
$$

The integrating factor $\mu$ is

$$
\begin{aligned}
\mu & =\mathrm{e}^{\int-2 x d x} \\
& =\mathrm{e}^{-x^{2}}
\end{aligned}
$$

The ode becomes

$$
\begin{aligned}
\frac{\mathrm{d}}{\mathrm{~d} x}(\mu w) & =(\mu)\left(-2 x^{3}\right) \\
\frac{\mathrm{d}}{\mathrm{~d} x}\left(\mathrm{e}^{-x^{2}} w\right) & =\left(\mathrm{e}^{-x^{2}}\right)\left(-2 x^{3}\right) \\
\mathrm{d}\left(\mathrm{e}^{-x^{2}} w\right) & =\left(-2 x^{3} \mathrm{e}^{-x^{2}}\right) \mathrm{d} x
\end{aligned}
$$

Integrating gives

$$
\begin{aligned}
& \mathrm{e}^{-x^{2}} w=\int-2 x^{3} \mathrm{e}^{-x^{2}} \mathrm{~d} x \\
& \mathrm{e}^{-x^{2}} w=\left(x^{2}+1\right) \mathrm{e}^{-x^{2}}+c_{1}
\end{aligned}
$$

Dividing both sides by the integrating factor $\mu=\mathrm{e}^{-x^{2}}$ results in

$$
w(x)=\mathrm{e}^{x^{2}}\left(x^{2}+1\right) \mathrm{e}^{-x^{2}}+c_{1} \mathrm{e}^{x^{2}}
$$

which simplifies to

$$
w(x)=x^{2}+1+c_{1} \mathrm{e}^{x^{2}}
$$

Replacing $w$ in the above by $\frac{1}{y^{2}}$ using equation (5) gives the final solution.

$$
\frac{1}{y^{2}}=x^{2}+1+c_{1} \mathrm{e}^{x^{2}}
$$

Solving for $y$ gives

$$
\begin{aligned}
& y(x)=\frac{1}{\sqrt{x^{2}+1+c_{1} \mathrm{e}^{x^{2}}}} \\
& y(x)=-\frac{1}{\sqrt{x^{2}+1+c_{1} \mathrm{e}^{x^{2}}}}
\end{aligned}
$$

Summary
The solution(s) found are the following

$$
\begin{align*}
& y=\frac{1}{\sqrt{x^{2}+1+c_{1} \mathrm{e}^{x^{2}}}}  \tag{1}\\
& y=-\frac{1}{\sqrt{x^{2}+1+c_{1} \mathrm{e}^{x^{2}}}} \tag{2}
\end{align*}
$$



Figure 11: Slope field plot

Verification of solutions

$$
y=\frac{1}{\sqrt{x^{2}+1+c_{1} \mathrm{e}^{x^{2}}}}
$$

Verified OK.

$$
y=-\frac{1}{\sqrt{x^{2}+1+c_{1} \mathrm{e}^{x^{2}}}}
$$

Verified OK.
Maple trace

```
`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
<- Bernoulli successful`
```

$\checkmark$ Solution by Maple
Time used: 0.016 (sec). Leaf size: 35
dsolve(diff $(y(x), x)+x * y(x)=x^{\wedge} 3 * y(x) \wedge 3, y(x)$, singsol=all)

$$
\begin{aligned}
& y(x)=\frac{1}{\sqrt{\mathrm{e}^{x^{2}} c_{1}+x^{2}+1}} \\
& y(x)=-\frac{1}{\sqrt{\mathrm{e}^{x^{2}} c_{1}+x^{2}+1}}
\end{aligned}
$$

$\checkmark$ Solution by Mathematica
Time used: 7.029 (sec). Leaf size: 50
DSolve [y' $[x]+x * y[x]==x^{\wedge} 3 * y[x] \sim 3, y[x], x$, IncludeSingularSolutions $->$ True]

$$
\begin{aligned}
& y(x) \rightarrow-\frac{1}{\sqrt{x^{2}+c_{1} e^{x^{2}}+1}} \\
& y(x) \rightarrow \frac{1}{\sqrt{x^{2}+c_{1} e^{x^{2}}+1}} \\
& y(x) \rightarrow 0
\end{aligned}
$$

## 1.6 problem Example, page 36

1.6.1 Solving as homogeneousTypeD2 ode . . . . . . . . . . . . . . . 58
1.6.2 Solving as first order ode lie symmetry calculated ode . . . . . . 60
1.6.3 Solving as exact ode . . . . . . . . . . . . . . . . . . . . . . . . 66
1.6.4 Maple step by step solution . . . . . . . . . . . . . . . . . . . . 70

Internal problem ID [4350]
Internal file name [OUTPUT/3843_Sunday_June_05_2022_11_21_02_AM_3402446/index.tex]
Book: Differential and integral calculus, vol II By N. Piskunov. 1974
Section: Chapter 1
Problem number: Example, page 36.
ODE order: 1.
ODE degree: 1.

The type(s) of ODE detected by this program : "exact", "homogeneousTypeD2", "first_order_ode_lie__symmetry__calculated"

Maple gives the following as the ode type
[[_homogeneous, `class A`], _exact, _rational, _dAlembert]

$$
\frac{2 x}{y^{3}}+\frac{\left(y^{2}-3 x^{2}\right) y^{\prime}}{y^{4}}=0
$$

### 1.6.1 Solving as homogeneousTypeD2 ode

Using the change of variables $y=u(x) x$ on the above ode results in new ode in $u(x)$

$$
\frac{2}{x^{2} u(x)^{3}}+\frac{\left(u(x)^{2} x^{2}-3 x^{2}\right)\left(u^{\prime}(x) x+u(x)\right)}{u(x)^{4} x^{4}}=0
$$

In canonical form the ODE is

$$
\begin{aligned}
u^{\prime} & =F(x, u) \\
& =f(x) g(u) \\
& =-\frac{u^{3}-u}{x\left(u^{2}-3\right)}
\end{aligned}
$$

Where $f(x)=-\frac{1}{x}$ and $g(u)=\frac{u^{3}-u}{u^{2}-3}$. Integrating both sides gives

$$
\begin{aligned}
\frac{1}{\frac{u^{3}-u}{u^{2}-3}} d u & =-\frac{1}{x} d x \\
\int \frac{1}{\frac{u^{3}-u}{u^{2}-3}} d u & =\int-\frac{1}{x} d x \\
-\ln (u+1)-\ln (u-1)+3 \ln (u) & =-\ln (x)+c_{2}
\end{aligned}
$$

Raising both side to exponential gives

$$
\mathrm{e}^{-\ln (u+1)-\ln (u-1)+3 \ln (u)}=\mathrm{e}^{-\ln (x)+c_{2}}
$$

Which simplifies to

$$
\frac{u^{3}}{u^{2}-1}=\frac{c_{3}}{x}
$$

The solution is

$$
\frac{u(x)^{3}}{u(x)^{2}-1}=\frac{c_{3}}{x}
$$

Replacing $u(x)$ in the above solution by $\frac{y}{x}$ results in the solution for $y$ in implicit form

$$
\begin{aligned}
\frac{y^{3}}{x^{3}\left(\frac{y^{2}}{x^{2}}-1\right)} & =\frac{c_{3}}{x} \\
\frac{y^{3}}{x\left(y^{2}-x^{2}\right)} & =\frac{c_{3}}{x}
\end{aligned}
$$

Which simplifies to

$$
-\frac{y^{3}}{(x-y)(x+y)}=c_{3}
$$

Summary
The solution(s) found are the following

$$
\begin{equation*}
-\frac{y^{3}}{(x-y)(x+y)}=c_{3} \tag{1}
\end{equation*}
$$



Figure 12: Slope field plot
Verification of solutions

$$
-\frac{y^{3}}{(x-y)(x+y)}=c_{3}
$$

Verified OK.

### 1.6.2 Solving as first order ode lie symmetry calculated ode

Writing the ode as

$$
\begin{aligned}
y^{\prime} & =-\frac{2 x y}{-3 x^{2}+y^{2}} \\
y^{\prime} & =\omega(x, y)
\end{aligned}
$$

The condition of Lie symmetry is the linearized PDE given by

$$
\begin{equation*}
\eta_{x}+\omega\left(\eta_{y}-\xi_{x}\right)-\omega^{2} \xi_{y}-\omega_{x} \xi-\omega_{y} \eta=0 \tag{A}
\end{equation*}
$$

The type of this ode is not in the lookup table. To determine $\xi, \eta$ then (A) is solved using ansatz. Making bivariate polynomials of degree 1 to use as anstaz gives

$$
\begin{gather*}
\xi=x a_{2}+y a_{3}+a_{1}  \tag{1E}\\
\eta=x b_{2}+y b_{3}+b_{1} \tag{2E}
\end{gather*}
$$

Where the unknown coefficients are

$$
\left\{a_{1}, a_{2}, a_{3}, b_{1}, b_{2}, b_{3}\right\}
$$

Substituting equations (1E,2E) and $\omega$ into (A) gives

$$
\begin{align*}
b_{2} & -\frac{2 x y\left(b_{3}-a_{2}\right)}{-3 x^{2}+y^{2}}-\frac{4 x^{2} y^{2} a_{3}}{\left(-3 x^{2}+y^{2}\right)^{2}} \\
& -\left(-\frac{2 y}{-3 x^{2}+y^{2}}-\frac{12 x^{2} y}{\left(-3 x^{2}+y^{2}\right)^{2}}\right)\left(x a_{2}+y a_{3}+a_{1}\right)  \tag{5E}\\
& -\left(-\frac{2 x}{-3 x^{2}+y^{2}}+\frac{4 x y^{2}}{\left(-3 x^{2}+y^{2}\right)^{2}}\right)\left(x b_{2}+y b_{3}+b_{1}\right)=0
\end{align*}
$$

Putting the above in normal form gives
$\frac{3 x^{4} b_{2}+2 x^{2} y^{2} a_{3}-8 x^{2} y^{2} b_{2}+4 x y^{3} a_{2}-4 x y^{3} b_{3}+2 y^{4} a_{3}+y^{4} b_{2}-6 x^{3} b_{1}+6 x^{2} y a_{1}-2 x y^{2} b_{1}+2 y^{3} a_{1}}{\left(3 x^{2}-y^{2}\right)^{2}}$ $=0$

Setting the numerator to zero gives

$$
\begin{align*}
& 3 x^{4} b_{2}+2 x^{2} y^{2} a_{3}-8 x^{2} y^{2} b_{2}+4 x y^{3} a_{2}-4 x y^{3} b_{3}+2 y^{4} a_{3}  \tag{6E}\\
& +y^{4} b_{2}-6 x^{3} b_{1}+6 x^{2} y a_{1}-2 x y^{2} b_{1}+2 y^{3} a_{1}=0
\end{align*}
$$

Looking at the above PDE shows the following are all the terms with $\{x, y\}$ in them.

$$
\{x, y\}
$$

The following substitution is now made to be able to collect on all terms with $\{x, y\}$ in them

$$
\left\{x=v_{1}, y=v_{2}\right\}
$$

The above PDE (6E) now becomes

$$
\begin{align*}
& 4 a_{2} v_{1} v_{2}^{3}+2 a_{3} v_{1}^{2} v_{2}^{2}+2 a_{3} v_{2}^{4}+3 b_{2} v_{1}^{4}-8 b_{2} v_{1}^{2} v_{2}^{2}+b_{2} v_{2}^{4}  \tag{7E}\\
& \quad-4 b_{3} v_{1} v_{2}^{3}+6 a_{1} v_{1}^{2} v_{2}+2 a_{1} v_{2}^{3}-6 b_{1} v_{1}^{3}-2 b_{1} v_{1} v_{2}^{2}=0
\end{align*}
$$

Collecting the above on the terms $v_{i}$ introduced, and these are

$$
\left\{v_{1}, v_{2}\right\}
$$

Equation (7E) now becomes

$$
\begin{align*}
& 3 b_{2} v_{1}^{4}-6 b_{1} v_{1}^{3}+\left(2 a_{3}-8 b_{2}\right) v_{1}^{2} v_{2}^{2}+6 a_{1} v_{1}^{2} v_{2}  \tag{8E}\\
& \quad+\left(4 a_{2}-4 b_{3}\right) v_{1} v_{2}^{3}-2 b_{1} v_{1} v_{2}^{2}+\left(2 a_{3}+b_{2}\right) v_{2}^{4}+2 a_{1} v_{2}^{3}=0
\end{align*}
$$

Setting each coefficients in (8E) to zero gives the following equations to solve

$$
\begin{aligned}
2 a_{1} & =0 \\
6 a_{1} & =0 \\
-6 b_{1} & =0 \\
-2 b_{1} & =0 \\
3 b_{2} & =0 \\
4 a_{2}-4 b_{3} & =0 \\
2 a_{3}-8 b_{2} & =0 \\
2 a_{3}+b_{2} & =0
\end{aligned}
$$

Solving the above equations for the unknowns gives

$$
\begin{aligned}
a_{1} & =0 \\
a_{2} & =b_{3} \\
a_{3} & =0 \\
b_{1} & =0 \\
b_{2} & =0 \\
b_{3} & =b_{3}
\end{aligned}
$$

Substituting the above solution in the anstaz (1E,2E) (using 1 as arbitrary value for any unknown in the RHS) gives

$$
\begin{aligned}
& \xi=x \\
& \eta=y
\end{aligned}
$$

Shifting is now applied to make $\xi=0$ in order to simplify the rest of the computation

$$
\begin{aligned}
\eta & =\eta-\omega(x, y) \xi \\
& =y-\left(-\frac{2 x y}{-3 x^{2}+y^{2}}\right)(x) \\
& =\frac{y x^{2}-y^{3}}{3 x^{2}-y^{2}} \\
\xi & =0
\end{aligned}
$$

The next step is to determine the canonical coordinates $R, S$. The canonical coordinates $\operatorname{map}(x, y) \rightarrow(R, S)$ where $(R, S)$ are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$
\begin{equation*}
\frac{d x}{\xi}=\frac{d y}{\eta}=d S \tag{1}
\end{equation*}
$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x}+\eta \frac{\partial}{\partial y}\right) S(x, y)=1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable $R$ in the canonical coordinates, where $S(R)$. Since $\xi=0$ then in this special case

$$
R=x
$$

$S$ is found from

$$
\begin{aligned}
S & =\int \frac{1}{\eta} d y \\
& =\int \frac{1}{\frac{y x^{2}-y^{3}}{3 x^{2}-y^{2}}} d y
\end{aligned}
$$

Which results in

$$
S=-\ln (x+y)+3 \ln (y)-\ln (-x+y)
$$

Now that $R, S$ are found, we need to setup the ode in these coordinates. This is done by evaluating

$$
\begin{equation*}
\frac{d S}{d R}=\frac{S_{x}+\omega(x, y) S_{y}}{R_{x}+\omega(x, y) R_{y}} \tag{2}
\end{equation*}
$$

Where in the above $R_{x}, R_{y}, S_{x}, S_{y}$ are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$
\omega(x, y)=-\frac{2 x y}{-3 x^{2}+y^{2}}
$$

Evaluating all the partial derivatives gives

$$
\begin{aligned}
R_{x} & =1 \\
R_{y} & =0 \\
S_{x} & =-\frac{2 x}{x^{2}-y^{2}} \\
S_{y} & =-\frac{1}{x+y}+\frac{3}{y}+\frac{1}{x-y}
\end{aligned}
$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$
\begin{equation*}
\frac{d S}{d R}=0 \tag{2~A}
\end{equation*}
$$

We now need to express the RHS as function of $R$ only. This is done by solving for $x, y$ in terms of $R, S$ from the result obtained earlier and simplifying. This gives

$$
\frac{d S}{d R}=0
$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordiates $R, S$. Integrating the above gives

$$
\begin{equation*}
S(R)=c_{1} \tag{4}
\end{equation*}
$$

To complete the solution, we just need to transform (4) back to $x, y$ coordinates. This results in

$$
-\ln (x+y)+3 \ln (y)-\ln (-x+y)=c_{1}
$$

Which simplifies to

$$
-\ln (x+y)+3 \ln (y)-\ln (-x+y)=c_{1}
$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

| Original ode in $x, y$ coordinates | $\begin{gathered} \text { Canonical } \\ \text { coordinates } \\ \text { transformation } \end{gathered}$ | ODE in canonical coordinates $(R, S)$ |
| :---: | :---: | :---: |
| $\frac{d y}{d x}=-\frac{2 x y}{-3 x^{2}+y^{2}}$ |  | $\frac{d S}{d R}=0$ |
|  |  |  |
|  |  |  |
|  |  |  |
| $\rightarrow \rightarrow \rightarrow+\infty$ |  | $\xrightarrow[\rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \longrightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow]{ }$ |
| $\xrightarrow{\rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow-\infty}$ | $R=x$ | $\rightarrow$ |
| $\rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \infty$ | $S=-\ln (x+y)+3 \ln ($ | $\xrightarrow{ }$ |
|  |  |  |
|  |  | $\rightarrow$ |
|  |  |  |
|  |  | $\rightarrow \rightarrow \rightarrow \rightarrow \rightarrow$ 遇 |

## Summary

The solution(s) found are the following

$$
\begin{equation*}
-\ln (x+y)+3 \ln (y)-\ln (-x+y)=c_{1} \tag{1}
\end{equation*}
$$



Figure 13: Slope field plot
Verification of solutions

$$
-\ln (x+y)+3 \ln (y)-\ln (-x+y)=c_{1}
$$

Verified OK.

### 1.6.3 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)
To solve an ode of the form

$$
\begin{equation*}
M(x, y)+N(x, y) \frac{d y}{d x}=0 \tag{A}
\end{equation*}
$$

We assume there exists a function $\phi(x, y)=c$ where $c$ is constant, that satisfies the ode. Taking derivative of $\phi$ w.r.t. $x$ gives

$$
\frac{d}{d x} \phi(x, y)=0
$$

Hence

$$
\begin{equation*}
\frac{\partial \phi}{\partial x}+\frac{\partial \phi}{\partial y} \frac{d y}{d x}=0 \tag{B}
\end{equation*}
$$

Comparing ( $\mathrm{A}, \mathrm{B}$ ) shows that

$$
\begin{aligned}
& \frac{\partial \phi}{\partial x}=M \\
& \frac{\partial \phi}{\partial y}=N
\end{aligned}
$$

But since $\frac{\partial^{2} \phi}{\partial x \partial y}=\frac{\partial^{2} \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$
\frac{\partial M}{\partial y}=\frac{\partial N}{\partial x}
$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^{2} \phi}{\partial x \partial y}=\frac{\partial^{2} \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$
\begin{equation*}
M(x, y) \mathrm{d} x+N(x, y) \mathrm{d} y=0 \tag{1A}
\end{equation*}
$$

Therefore

$$
\begin{align*}
\left(\frac{-3 x^{2}+y^{2}}{y^{4}}\right) \mathrm{d} y & =\left(-\frac{2 x}{y^{3}}\right) \mathrm{d} x \\
\left(\frac{2 x}{y^{3}}\right) \mathrm{d} x+\left(\frac{-3 x^{2}+y^{2}}{y^{4}}\right) \mathrm{d} y & =0 \tag{2~A}
\end{align*}
$$

Comparing (1A) and (2A) shows that

$$
\begin{aligned}
& M(x, y)=\frac{2 x}{y^{3}} \\
& N(x, y)=\frac{-3 x^{2}+y^{2}}{y^{4}}
\end{aligned}
$$

The next step is to determine if the ODE is is exact or not. The ODE is exact when the following condition is satisfied

$$
\frac{\partial M}{\partial y}=\frac{\partial N}{\partial x}
$$

Using result found above gives

$$
\begin{aligned}
\frac{\partial M}{\partial y} & =\frac{\partial}{\partial y}\left(\frac{2 x}{y^{3}}\right) \\
& =-\frac{6 x}{y^{4}}
\end{aligned}
$$

And

$$
\begin{aligned}
\frac{\partial N}{\partial x} & =\frac{\partial}{\partial x}\left(\frac{-3 x^{2}+y^{2}}{y^{4}}\right) \\
& =-\frac{6 x}{y^{4}}
\end{aligned}
$$

Since $\frac{\partial M}{\partial y}=\frac{\partial N}{\partial x}$, then the ODE is exact The following equations are now set up to solve for the function $\phi(x, y)$

$$
\begin{align*}
& \frac{\partial \phi}{\partial x}=M  \tag{1}\\
& \frac{\partial \phi}{\partial y}=N \tag{2}
\end{align*}
$$

Integrating (1) w.r.t. $x$ gives

$$
\begin{align*}
\int \frac{\partial \phi}{\partial x} \mathrm{~d} x & =\int M \mathrm{~d} x \\
\int \frac{\partial \phi}{\partial x} \mathrm{~d} x & =\int \frac{2 x}{y^{3}} \mathrm{~d} x \\
\phi & =\frac{x^{2}}{y^{3}}+f(y) \tag{3}
\end{align*}
$$

Where $f(y)$ is used for the constant of integration since $\phi$ is a function of both $x$ and $y$. Taking derivative of equation (3) w.r.t $y$ gives

$$
\begin{equation*}
\frac{\partial \phi}{\partial y}=-\frac{3 x^{2}}{y^{4}}+f^{\prime}(y) \tag{4}
\end{equation*}
$$

But equation (2) says that $\frac{\partial \phi}{\partial y}=\frac{-3 x^{2}+y^{2}}{y^{4}}$. Therefore equation (4) becomes

$$
\begin{equation*}
\frac{-3 x^{2}+y^{2}}{y^{4}}=-\frac{3 x^{2}}{y^{4}}+f^{\prime}(y) \tag{5}
\end{equation*}
$$

Solving equation (5) for $f^{\prime}(y)$ gives

$$
f^{\prime}(y)=\frac{1}{y^{2}}
$$

Integrating the above w.r.t $y$ gives

$$
\begin{aligned}
\int f^{\prime}(y) \mathrm{d} y & =\int\left(\frac{1}{y^{2}}\right) \mathrm{d} y \\
f(y) & =-\frac{1}{y}+c_{1}
\end{aligned}
$$

Where $c_{1}$ is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives $\phi$

$$
\phi=\frac{x^{2}}{y^{3}}-\frac{1}{y}+c_{1}
$$

But since $\phi$ itself is a constant function, then let $\phi=c_{2}$ where $c_{2}$ is new constant and combining $c_{1}$ and $c_{2}$ constants into new constant $c_{1}$ gives the solution as

$$
c_{1}=\frac{x^{2}}{y^{3}}-\frac{1}{y}
$$

Summary
The solution(s) found are the following

$$
\begin{equation*}
\frac{x^{2}}{y^{3}}-\frac{1}{y}=c_{1} \tag{1}
\end{equation*}
$$



Figure 14: Slope field plot

Verification of solutions

$$
\frac{x^{2}}{y^{3}}-\frac{1}{y}=c_{1}
$$

Verified OK.

### 1.6.4 Maple step by step solution

Let's solve
$\frac{2 x}{y^{3}}+\frac{\left(y^{2}-3 x^{2}\right) y^{\prime}}{y^{4}}=0$

- Highest derivative means the order of the ODE is 1
$y^{\prime}$
$\square \quad$ Check if ODE is exact
- ODE is exact if the lhs is the total derivative of a $C^{2}$ function

$$
F^{\prime}(x, y)=0
$$

- Compute derivative of lhs

$$
F^{\prime}(x, y)+\left(\frac{\partial}{\partial y} F(x, y)\right) y^{\prime}=0
$$

- Evaluate derivatives

$$
-\frac{6 x}{y^{4}}=-\frac{6 x}{y^{4}}
$$

- Condition met, ODE is exact
- Exact ODE implies solution will be of this form

$$
\left[F(x, y)=c_{1}, M(x, y)=F^{\prime}(x, y), N(x, y)=\frac{\partial}{\partial y} F(x, y)\right]
$$

- $\quad$ Solve for $F(x, y)$ by integrating $M(x, y)$ with respect to $x$

$$
F(x, y)=\int \frac{2 x}{y^{3}} d x+f_{1}(y)
$$

- Evaluate integral
$F(x, y)=\frac{x^{2}}{y^{3}}+f_{1}(y)$
- $\quad$ Take derivative of $F(x, y)$ with respect to $y$
$N(x, y)=\frac{\partial}{\partial y} F(x, y)$
- Compute derivative
$\frac{-3 x^{2}+y^{2}}{y^{4}}=-\frac{3 x^{2}}{y^{4}}+\frac{d}{d y} f_{1}(y)$
- Isolate for $\frac{d}{d y} f_{1}(y)$

$$
\frac{d}{d y} f_{1}(y)=\frac{3 x^{2}}{y^{4}}+\frac{-3 x^{2}+y^{2}}{y^{4}}
$$

- $\quad$ Solve for $f_{1}(y)$
$f_{1}(y)=-\frac{1}{y}$
- $\quad$ Substitute $f_{1}(y)$ into equation for $F(x, y)$

$$
F(x, y)=\frac{x^{2}}{y^{3}}-\frac{1}{y}
$$

- $\quad$ Substitute $F(x, y)$ into the solution of the ODE

$$
\frac{x^{2}}{y^{3}}-\frac{1}{y}=c_{1}
$$

- $\quad$ Solve for $y$

$$
\left\{y=\frac{\left(12 \sqrt{3} x \sqrt{27 x^{2} c_{1}^{2}-4} c_{1}+108 x^{2} c_{1}^{2}-8\right)^{\frac{1}{3}}}{6 c_{1}}+\frac{2}{3 c_{1}\left(12 \sqrt{3} x \sqrt{27 x^{2} c_{1}^{2}-4} c_{1}+108 x^{2} c_{1}^{2}-8\right)^{\frac{1}{3}}}-\frac{1}{3 c_{1}}, y=-\frac{\left(12 \sqrt{3} x \sqrt{27 x^{2}}\right.}{}\right.
$$

Maple trace

```
`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
trying separable
trying inverse linear
trying homogeneous types:
trying homogeneous D
<- homogeneous successful`
```

$\checkmark$ Solution by Maple
Time used: 0.016 (sec). Leaf size: 317

```
dsolve(2*x/y(x)^3+(y(x)^2-3*x^2)/(y(x)^4)*diff(y(x),x)=0,y(x), singsol=all)
```

$$
\begin{aligned}
& y(x)=\frac{1+\frac{\left(12 \sqrt{3} x \sqrt{27 x^{2} c_{1}^{2}-4} c_{1}-108 x^{2} c_{1}^{2}+8\right)^{\frac{1}{3}}}{2}+\frac{2}{\left(12 \sqrt{3} x \sqrt{27 x^{2} c_{1}^{2}-4} c_{1}-108 x^{2} c_{1}^{2}+8\right)^{\frac{1}{3}}}}{3 c_{1}} \\
& y(x)= \\
& -\frac{(1+i \sqrt{3})\left(12 \sqrt{3} x \sqrt{27 x^{2} c_{1}^{2}-4} c_{1}-108 x^{2} c_{1}^{2}+8\right)^{\frac{2}{3}}-4 i \sqrt{3}-4\left(12 \sqrt{3} x \sqrt{27 x^{2} c_{1}^{2}-4} c_{1}-108 x^{2} c_{1}^{2}-\right.}{12\left(12 \sqrt{3} x \sqrt{27 x^{2} c_{1}^{2}-4} c_{1}-108 x^{2} c_{1}^{2}+8\right)^{\frac{1}{3}} c_{1}} \\
& y(x) \\
& =\frac{(i \sqrt{3}-1)\left(12 \sqrt{3} x \sqrt{27 x^{2} c_{1}^{2}-4} c_{1}-108 x^{2} c_{1}^{2}+8\right)^{\frac{2}{3}}-4 i \sqrt{3}+4\left(12 \sqrt{3} x \sqrt{27 x^{2} c_{1}^{2}-4} c_{1}-108 x^{2} c_{1}^{2}+\varepsilon\right.}{12\left(12 \sqrt{3} x \sqrt{27 x^{2} c_{1}^{2}-4} c_{1}-108 x^{2} c_{1}^{2}+8\right)^{\frac{1}{3}} c_{1}}
\end{aligned}
$$

## Solution by Mathematica

Time used: 60.204 (sec). Leaf size: 458
DSolve $\left[2 * x / y[x] \wedge 3+\left(y[x] \sim 2-3 * x^{\wedge} 2\right) /(y[x] \sim 4) * y '[x]==0, y[x], x\right.$, IncludeSingularSolutions $->$ True]

$$
\left.\left.\begin{array}{rl}
y(x) \rightarrow & \frac{1}{3}\left(\frac{\sqrt[3]{27 e^{c_{1}} x^{2}+3 \sqrt{81 e^{2 c_{1}} x^{4}-12 e^{4 c_{1}} x^{2}}-2 e^{3 c_{1}}}}{\sqrt[3]{2}}\right. \\
+\frac{\sqrt[3]{2} e^{2 c_{1}}}{\sqrt[3]{27 e^{c_{1}} x^{2}+3 \sqrt{81 e^{2 c_{1}} x^{4}-12 e^{4 c_{1}} x^{2}}}-2 e^{3 c_{1}}}
\end{array}\right) e^{c_{1}}\right) .
$$

## 1.7 problem Example, page 38

1.7.1 Solving as homogeneousTypeD2 ode ..... 74
1.7.2 Solving as first order ode lie symmetry lookup ode ..... 76
1.7.3 Solving as bernoulli ode ..... 80
1.7.4 Solving as exact ode ..... 83
1.7.5 Solving as riccati ode ..... 88

Internal problem ID [4351]
Internal file name [OUTPUT/3844_Sunday_June_05_2022_11_21_09_AM_38053898/index.tex]
Book: Differential and integral calculus, vol II By N. Piskunov. 1974
Section: Chapter 1
Problem number: Example, page 38.
ODE order: 1.
ODE degree: 1 .

The type(s) of ODE detected by this program : "riccati", "bernoulli", "homogeneousTypeD2", "exactWithIntegrationFactor", "first_order_ode_lie_symmetry_lookup"

Maple gives the following as the ode type

```
[[_homogeneous, `class D`], _rational, _Bernoulli]
```

$$
y+x y^{2}-x y^{\prime}=0
$$

### 1.7.1 Solving as homogeneousTypeD2 ode

Using the change of variables $y=u(x) x$ on the above ode results in new ode in $u(x)$

$$
u(x) x+x^{3} u(x)^{2}-x\left(u^{\prime}(x) x+u(x)\right)=0
$$

In canonical form the ODE is

$$
\begin{aligned}
u^{\prime} & =F(x, u) \\
& =f(x) g(u) \\
& =u^{2} x
\end{aligned}
$$

Where $f(x)=x$ and $g(u)=u^{2}$. Integrating both sides gives

$$
\begin{aligned}
\frac{1}{u^{2}} d u & =x d x \\
\int \frac{1}{u^{2}} d u & =\int x d x \\
-\frac{1}{u} & =\frac{x^{2}}{2}+c_{2}
\end{aligned}
$$

The solution is

$$
-\frac{1}{u(x)}-\frac{x^{2}}{2}-c_{2}=0
$$

Replacing $u(x)$ in the above solution by $\frac{y}{x}$ results in the solution for $y$ in implicit form

$$
\begin{aligned}
& -\frac{x}{y}-\frac{x^{2}}{2}-c_{2}=0 \\
& -\frac{x}{y}-\frac{x^{2}}{2}-c_{2}=0
\end{aligned}
$$

Summary
The solution(s) found are the following

$$
\begin{equation*}
-\frac{x}{y}-\frac{x^{2}}{2}-c_{2}=0 \tag{1}
\end{equation*}
$$



Figure 15: Slope field plot
Verification of solutions

$$
-\frac{x}{y}-\frac{x^{2}}{2}-c_{2}=0
$$

Verified OK.

### 1.7.2 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$
\begin{aligned}
y^{\prime} & =\frac{y(x y+1)}{x} \\
y^{\prime} & =\omega(x, y)
\end{aligned}
$$

The condition of Lie symmetry is the linearized PDE given by

$$
\begin{equation*}
\eta_{x}+\omega\left(\eta_{y}-\xi_{x}\right)-\omega^{2} \xi_{y}-\omega_{x} \xi-\omega_{y} \eta=0 \tag{A}
\end{equation*}
$$

The type of this ode is known. It is of type Bernoulli. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find $\xi, \eta$

Table 7: Lie symmetry infinitesimal lookup table for known first order ODE's

| ODE class | Form | $\xi$ | $\eta$ |
| :--- | :--- | :--- | :--- |
| linear ode | $y^{\prime}=f(x) y(x)+g(x)$ | 0 | $e^{\int f d x}$ |
| separable ode | $y^{\prime}=f(x) g(y)$ | $\frac{1}{f}$ | 0 |
| quadrature ode | $y^{\prime}=f(x)$ | 0 | 1 |
| quadrature ode | $y^{\prime}=g(y)$ | 1 | 0 |
| homogeneous ODEs of <br> Class A | $y^{\prime}=f\left(\frac{y}{x}\right)$ | $x$ | $y$ |
| homogeneous ODEs of <br> Class C | $y^{\prime}=(a+b x+c y)^{\frac{n}{m}}$ | 1 | $-\frac{b}{c}$ |
| homogeneous class D | $y^{\prime}=\frac{y}{x}+g(x) F\left(\frac{y}{x}\right)$ | $x^{2}$ | $x y$ |
| First order <br> form ID 1 | special | $y^{\prime}=g(x) e^{h(x)+b y}+f(x)$ | $\frac{e^{-\int b f(x) d x-h(x)}}{g(x)}$ |
| polynomial type ode | $y^{\prime}=\frac{a_{1} x+b_{1} y+c_{1}}{a_{2} x+b_{2} y+c_{2}}$ | $\frac{f(x) e^{-\int b f(x) d x-h(x)}}{g(x)}$ |  |
| Bernoulli ode | $y^{\prime}=f(x) y+g(x) y^{n}$ | 0 | $a_{1} b_{2} x-a_{2} b_{1} x-b_{1} c_{2}+b_{2} c_{1}$ |
| $a_{1} b_{2}-a_{2} b_{1}$ | $\frac{a_{1} b_{2} y-a_{2} b_{1} y-a_{1} c_{2}-a_{2} c_{1}}{a_{1} b_{2}-a_{2} b_{1}}$ |  |  |
| Reduced Riccati | $y^{\prime}=f_{1}(x) y+f_{2}(x) y^{2}$ | 0 | $e^{-\int(n-1) f(x) d x} y^{n}$ |

The above table shows that

$$
\begin{align*}
\xi(x, y) & =0 \\
\eta(x, y) & =\frac{y^{2}}{x} \tag{A1}
\end{align*}
$$

The next step is to determine the canonical coordinates $R, S$. The canonical coordinates map $(x, y) \rightarrow(R, S)$ where $(R, S)$ are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$
\begin{equation*}
\frac{d x}{\xi}=\frac{d y}{\eta}=d S \tag{1}
\end{equation*}
$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x}+\eta \frac{\partial}{\partial y}\right) S(x, y)=1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable $R$ in the
canonical coordinates, where $S(R)$. Since $\xi=0$ then in this special case

$$
R=x
$$

$S$ is found from

$$
\begin{aligned}
S & =\int \frac{1}{\eta} d y \\
& =\int \frac{1}{\frac{y^{2}}{x}} d y
\end{aligned}
$$

Which results in

$$
S=-\frac{x}{y}
$$

Now that $R, S$ are found, we need to setup the ode in these coordinates. This is done by evaluating

$$
\begin{equation*}
\frac{d S}{d R}=\frac{S_{x}+\omega(x, y) S_{y}}{R_{x}+\omega(x, y) R_{y}} \tag{2}
\end{equation*}
$$

Where in the above $R_{x}, R_{y}, S_{x}, S_{y}$ are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$
\omega(x, y)=\frac{y(x y+1)}{x}
$$

Evaluating all the partial derivatives gives

$$
\begin{aligned}
R_{x} & =1 \\
R_{y} & =0 \\
S_{x} & =-\frac{1}{y} \\
S_{y} & =\frac{x}{y^{2}}
\end{aligned}
$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$
\begin{equation*}
\frac{d S}{d R}=x \tag{2~A}
\end{equation*}
$$

We now need to express the RHS as function of $R$ only. This is done by solving for $x, y$ in terms of $R, S$ from the result obtained earlier and simplifying. This gives

$$
\frac{d S}{d R}=R
$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordiates $R, S$. Integrating the above gives

$$
\begin{equation*}
S(R)=\frac{R^{2}}{2}+c_{1} \tag{4}
\end{equation*}
$$

To complete the solution, we just need to transform (4) back to $x, y$ coordinates. This results in

$$
-\frac{x}{y}=\frac{x^{2}}{2}+c_{1}
$$

Which simplifies to

$$
-\frac{x}{y}=\frac{x^{2}}{2}+c_{1}
$$

Which gives

$$
y=-\frac{2 x}{x^{2}+2 c_{1}}
$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

| Original ode in $x, y$ coordinates | Canonical coordinates transformation | ODE in canonical coordinates $(R, S)$ |
| :---: | :---: | :---: |
| $\frac{d y}{d x}=\frac{y(x y+1)}{x}$ |  | $\frac{d S}{d R}=R$ |
|  |  |  |
|  |  |  |
|  |  |  |
|  |  |  |
|  |  |  |
| $\xrightarrow[\rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \rightarrow \infty]{ }$ | $R=x$ |  |
|  | $S=-\frac{x}{y}$ |  |
|  |  |  |
|  | $y$ |  |
|  |  |  |
|  |  |  |
|  |  |  |

## Summary

The solution(s) found are the following

$$
\begin{equation*}
y=-\frac{2 x}{x^{2}+2 c_{1}} \tag{1}
\end{equation*}
$$



Figure 16: Slope field plot
Verification of solutions

$$
y=-\frac{2 x}{x^{2}+2 c_{1}}
$$

Verified OK.

### 1.7.3 Solving as bernoulli ode

In canonical form, the ODE is

$$
\begin{aligned}
y^{\prime} & =F(x, y) \\
& =\frac{y(x y+1)}{x}
\end{aligned}
$$

This is a Bernoulli ODE.

$$
\begin{equation*}
y^{\prime}=\frac{1}{x} y+y^{2} \tag{1}
\end{equation*}
$$

The standard Bernoulli ODE has the form

$$
\begin{equation*}
y^{\prime}=f_{0}(x) y+f_{1}(x) y^{n} \tag{2}
\end{equation*}
$$

The first step is to divide the above equation by $y^{n}$ which gives

$$
\begin{equation*}
\frac{y^{\prime}}{y^{n}}=f_{0}(x) y^{1-n}+f_{1}(x) \tag{3}
\end{equation*}
$$

The next step is use the substitution $w=y^{1-n}$ in equation (3) which generates a new ODE in $w(x)$ which will be linear and can be easily solved using an integrating factor. Backsubstitution then gives the solution $y(x)$ which is what we want.

This method is now applied to the ODE at hand. Comparing the ODE (1) With (2) Shows that

$$
\begin{aligned}
f_{0}(x) & =\frac{1}{x} \\
f_{1}(x) & =1 \\
n & =2
\end{aligned}
$$

Dividing both sides of ODE (1) by $y^{n}=y^{2}$ gives

$$
\begin{equation*}
y^{\prime} \frac{1}{y^{2}}=\frac{1}{x y}+1 \tag{4}
\end{equation*}
$$

Let

$$
\begin{align*}
w & =y^{1-n} \\
& =\frac{1}{y} \tag{5}
\end{align*}
$$

Taking derivative of equation (5) w.r.t $x$ gives

$$
\begin{equation*}
w^{\prime}=-\frac{1}{y^{2}} y^{\prime} \tag{6}
\end{equation*}
$$

Substituting equations (5) and (6) into equation (4) gives

$$
\begin{align*}
-w^{\prime}(x) & =\frac{w(x)}{x}+1 \\
w^{\prime} & =-\frac{w}{x}-1 \tag{7}
\end{align*}
$$

The above now is a linear ODE in $w(x)$ which is now solved.
Entering Linear first order ODE solver. In canonical form a linear first order is

$$
w^{\prime}(x)+p(x) w(x)=q(x)
$$

Where here

$$
\begin{aligned}
& p(x)=\frac{1}{x} \\
& q(x)=-1
\end{aligned}
$$

Hence the ode is

$$
w^{\prime}(x)+\frac{w(x)}{x}=-1
$$

The integrating factor $\mu$ is

$$
\begin{aligned}
& \mu=\mathrm{e}^{\int \frac{1}{x} d x} \\
& =x
\end{aligned}
$$

The ode becomes

$$
\begin{aligned}
\frac{\mathrm{d}}{\mathrm{~d} x}(\mu w) & =(\mu)(-1) \\
\frac{\mathrm{d}}{\mathrm{~d} x}(x w) & =(x)(-1) \\
\mathrm{d}(x w) & =(-x) \mathrm{d} x
\end{aligned}
$$

Integrating gives

$$
\begin{aligned}
& x w=\int-x \mathrm{~d} x \\
& x w=-\frac{x^{2}}{2}+c_{1}
\end{aligned}
$$

Dividing both sides by the integrating factor $\mu=x$ results in

$$
w(x)=-\frac{x}{2}+\frac{c_{1}}{x}
$$

Replacing $w$ in the above by $\frac{1}{y}$ using equation (5) gives the final solution.

$$
\frac{1}{y}=-\frac{x}{2}+\frac{c_{1}}{x}
$$

Or

$$
y=\frac{1}{-\frac{x}{2}+\frac{c_{1}}{x}}
$$

Summary
The solution(s) found are the following

$$
\begin{equation*}
y=\frac{1}{-\frac{x}{2}+\frac{c_{1}}{x}} \tag{1}
\end{equation*}
$$



Figure 17: Slope field plot

## Verification of solutions

$$
y=\frac{1}{-\frac{x}{2}+\frac{c_{1}}{x}}
$$

Verified OK.

### 1.7.4 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)
To solve an ode of the form

$$
\begin{equation*}
M(x, y)+N(x, y) \frac{d y}{d x}=0 \tag{A}
\end{equation*}
$$

We assume there exists a function $\phi(x, y)=c$ where $c$ is constant, that satisfies the ode. Taking derivative of $\phi$ w.r.t. $x$ gives

$$
\frac{d}{d x} \phi(x, y)=0
$$

Hence

$$
\begin{equation*}
\frac{\partial \phi}{\partial x}+\frac{\partial \phi}{\partial y} \frac{d y}{d x}=0 \tag{B}
\end{equation*}
$$

Comparing ( $\mathrm{A}, \mathrm{B}$ ) shows that

$$
\begin{aligned}
& \frac{\partial \phi}{\partial x}=M \\
& \frac{\partial \phi}{\partial y}=N
\end{aligned}
$$

But since $\frac{\partial^{2} \phi}{\partial x \partial y}=\frac{\partial^{2} \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$
\frac{\partial M}{\partial y}=\frac{\partial N}{\partial x}
$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^{2} \phi}{\partial x \partial y}=\frac{\partial^{2} \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$
\begin{equation*}
M(x, y) \mathrm{d} x+N(x, y) \mathrm{d} y=0 \tag{1A}
\end{equation*}
$$

Therefore

$$
\begin{align*}
(-x) \mathrm{d} y & =\left(-y^{2} x-y\right) \mathrm{d} x \\
\left(y^{2} x+y\right) \mathrm{d} x+(-x) \mathrm{d} y & =0 \tag{2~A}
\end{align*}
$$

Comparing (1A) and (2A) shows that

$$
\begin{aligned}
M(x, y) & =y^{2} x+y \\
N(x, y) & =-x
\end{aligned}
$$

The next step is to determine if the ODE is is exact or not. The ODE is exact when the following condition is satisfied

$$
\frac{\partial M}{\partial y}=\frac{\partial N}{\partial x}
$$

Using result found above gives

$$
\begin{aligned}
\frac{\partial M}{\partial y} & =\frac{\partial}{\partial y}\left(y^{2} x+y\right) \\
& =2 x y+1
\end{aligned}
$$

And

$$
\begin{aligned}
\frac{\partial N}{\partial x} & =\frac{\partial}{\partial x}(-x) \\
& =-1
\end{aligned}
$$

Since $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$
\begin{aligned}
A & =\frac{1}{N}\left(\frac{\partial M}{\partial y}-\frac{\partial N}{\partial x}\right) \\
& =-\frac{1}{x}((2 x y+1)-(-1)) \\
& =\frac{-2 x y-2}{x}
\end{aligned}
$$

Since $A$ depends on $y$, it can not be used to obtain an integrating factor. We will now try a second method to find an integrating factor. Let

$$
\begin{aligned}
B & =\frac{1}{M}\left(\frac{\partial N}{\partial x}-\frac{\partial M}{\partial y}\right) \\
& =\frac{1}{y^{2} x+y}((-1)-(2 x y+1)) \\
& =-\frac{2}{y}
\end{aligned}
$$

Since $B$ does not depend on $x$, it can be used to obtain an integrating factor. Let the integrating factor be $\mu$. Then

$$
\begin{aligned}
\mu & =e^{\int B \mathrm{~d} y} \\
& =e^{\int-\frac{2}{y} \mathrm{~d} y}
\end{aligned}
$$

The result of integrating gives

$$
\begin{aligned}
\mu & =e^{-2 \ln (y)} \\
& =\frac{1}{y^{2}}
\end{aligned}
$$

$M$ and $N$ are now multiplied by this integrating factor, giving new $M$ and new $N$ which are called $\bar{M}$ and $\bar{N}$ so not to confuse them with the original $M$ and $N$.

$$
\begin{aligned}
\bar{M} & =\mu M \\
& =\frac{1}{y^{2}}\left(y^{2} x+y\right) \\
& =\frac{x y+1}{y}
\end{aligned}
$$

And

$$
\begin{aligned}
\bar{N} & =\mu N \\
& =\frac{1}{y^{2}}(-x) \\
& =-\frac{x}{y^{2}}
\end{aligned}
$$

So now a modified ODE is obtained from the original ODE which will be exact and can be solved using the standard method. The modified ODE is

$$
\begin{aligned}
\bar{M}+\bar{N} \frac{\mathrm{~d} y}{\mathrm{~d} x} & =0 \\
\left(\frac{x y+1}{y}\right)+\left(-\frac{x}{y^{2}}\right) \frac{\mathrm{d} y}{\mathrm{~d} x} & =0
\end{aligned}
$$

The following equations are now set up to solve for the function $\phi(x, y)$

$$
\begin{align*}
& \frac{\partial \phi}{\partial x}=\bar{M}  \tag{1}\\
& \frac{\partial \phi}{\partial y}=\bar{N} \tag{2}
\end{align*}
$$

Integrating (1) w.r.t. $x$ gives

$$
\begin{align*}
\int \frac{\partial \phi}{\partial x} \mathrm{~d} x & =\int \bar{M} \mathrm{~d} x \\
\int \frac{\partial \phi}{\partial x} \mathrm{~d} x & =\int \frac{x y+1}{y} \mathrm{~d} x \\
\phi & =\frac{x(x y+2)}{2 y}+f(y) \tag{3}
\end{align*}
$$

Where $f(y)$ is used for the constant of integration since $\phi$ is a function of both $x$ and $y$. Taking derivative of equation (3) w.r.t $y$ gives

$$
\begin{align*}
\frac{\partial \phi}{\partial y} & =\frac{x^{2}}{2 y}-\frac{x(x y+2)}{2 y^{2}}+f^{\prime}(y)  \tag{4}\\
& =-\frac{x}{y^{2}}+f^{\prime}(y)
\end{align*}
$$

But equation (2) says that $\frac{\partial \phi}{\partial y}=-\frac{x}{y^{2}}$. Therefore equation (4) becomes

$$
\begin{equation*}
-\frac{x}{y^{2}}=-\frac{x}{y^{2}}+f^{\prime}(y) \tag{5}
\end{equation*}
$$

Solving equation (5) for $f^{\prime}(y)$ gives

$$
f^{\prime}(y)=0
$$

Therefore

$$
f(y)=c_{1}
$$

Where $c_{1}$ is constant of integration. Substituting this result for $f(y)$ into equation (3) gives $\phi$

$$
\phi=\frac{x(x y+2)}{2 y}+c_{1}
$$

But since $\phi$ itself is a constant function, then let $\phi=c_{2}$ where $c_{2}$ is new constant and combining $c_{1}$ and $c_{2}$ constants into new constant $c_{1}$ gives the solution as

$$
c_{1}=\frac{x(x y+2)}{2 y}
$$

The solution becomes

$$
y=\frac{2 x}{-x^{2}+2 c_{1}}
$$

Summary
The solution(s) found are the following

$$
\begin{equation*}
y=\frac{2 x}{-x^{2}+2 c_{1}} \tag{1}
\end{equation*}
$$



Figure 18: Slope field plot

## Verification of solutions

$$
y=\frac{2 x}{-x^{2}+2 c_{1}}
$$

Verified OK.

### 1.7.5 Solving as riccati ode

In canonical form the ODE is

$$
\begin{aligned}
y^{\prime} & =F(x, y) \\
& =\frac{y(x y+1)}{x}
\end{aligned}
$$

This is a Riccati ODE. Comparing the ODE to solve

$$
y^{\prime}=y^{2}+\frac{y}{x}
$$

With Riccati ODE standard form

$$
y^{\prime}=f_{0}(x)+f_{1}(x) y+f_{2}(x) y^{2}
$$

Shows that $f_{0}(x)=0, f_{1}(x)=\frac{1}{x}$ and $f_{2}(x)=1$. Let

$$
\begin{align*}
y & =\frac{-u^{\prime}}{f_{2} u} \\
& =\frac{-u^{\prime}}{u} \tag{1}
\end{align*}
$$

Using the above substitution in the given ODE results (after some simplification)in a second order ODE to solve for $u(x)$ which is

$$
\begin{equation*}
f_{2} u^{\prime \prime}(x)-\left(f_{2}^{\prime}+f_{1} f_{2}\right) u^{\prime}(x)+f_{2}^{2} f_{0} u(x)=0 \tag{2}
\end{equation*}
$$

But

$$
\begin{aligned}
f_{2}^{\prime} & =0 \\
f_{1} f_{2} & =\frac{1}{x} \\
f_{2}^{2} f_{0} & =0
\end{aligned}
$$

Substituting the above terms back in equation (2) gives

$$
u^{\prime \prime}(x)-\frac{u^{\prime}(x)}{x}=0
$$

Solving the above ODE (this ode solved using Maple, not this program), gives

$$
u(x)=c_{2} x^{2}+c_{1}
$$

The above shows that

$$
u^{\prime}(x)=2 c_{2} x
$$

Using the above in (1) gives the solution

$$
y=-\frac{2 c_{2} x}{c_{2} x^{2}+c_{1}}
$$

Dividing both numerator and denominator by $c_{1}$ gives, after renaming the constant $\frac{c_{2}}{c_{1}}=c_{3}$ the following solution

$$
y=-\frac{2 x}{x^{2}+c_{3}}
$$

Summary
The solution(s) found are the following

$$
\begin{equation*}
y=-\frac{2 x}{x^{2}+c_{3}} \tag{1}
\end{equation*}
$$



Figure 19: Slope field plot

Verification of solutions

$$
y=-\frac{2 x}{x^{2}+c_{3}}
$$

Verified OK.
Maple trace

- Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
<- Bernoulli successful`
$\checkmark$ Solution by Maple
Time used: 0.0 (sec). Leaf size: 16
dsolve( $(y(x)+x * y(x) \sim 2)-x * \operatorname{diff}(y(x), x)=0, y(x)$, singsol=all)

$$
y(x)=-\frac{2 x}{x^{2}-2 c_{1}}
$$

$\sqrt{ }$ Solution by Mathematica
Time used: 0.144 (sec). Leaf size: 23
DSolve $\left[(y[x]+x * y[x] \sim 2)-x * y^{\prime}[x]==0, y[x], x\right.$, IncludeSingularSolutions $\rightarrow$ True]

$$
\begin{aligned}
& y(x) \rightarrow-\frac{2 x}{x^{2}-2 c_{1}} \\
& y(x) \rightarrow 0
\end{aligned}
$$

## 1.8 problem example page 46

$$
\text { 1.8.1 Maple step by step solution . . . . . . . . . . . . . . . . . . . . } 93
$$

Internal problem ID [4352]
Internal file name [OUTPUT/3845_Sunday_June_05_2022_11_21_17_AM_49579362/index.tex]
Book: Differential and integral calculus, vol II By N. Piskunov. 1974
Section: Chapter 1
Problem number: example page 46 .
ODE order: 1.
ODE degree: 2.

The type(s) of ODE detected by this program : "quadrature"
Maple gives the following as the ode type
[_quadrature]

$$
y^{2}\left(1+y^{\prime 2}\right)=R^{2}
$$

Solving the given ode for $y^{\prime}$ results in 2 differential equations to solve. Each one of these will generate a solution. The equations generated are

$$
\begin{align*}
y^{\prime} & =\frac{\sqrt{-y^{2}+R^{2}}}{y}  \tag{1}\\
y^{\prime} & =-\frac{\sqrt{-y^{2}+R^{2}}}{y} \tag{2}
\end{align*}
$$

Now each one of the above ODE is solved.
Solving equation (1)
Integrating both sides gives

$$
\begin{aligned}
\int \frac{y}{\sqrt{R^{2}-y^{2}}} d y & =\int d x \\
-\frac{(R-y)(y+R)}{\sqrt{-y^{2}+R^{2}}} & =x+c_{1}
\end{aligned}
$$

## Summary

The solution(s) found are the following

$$
\begin{equation*}
-\frac{(R-y)(y+R)}{\sqrt{-y^{2}+R^{2}}}=x+c_{1} \tag{1}
\end{equation*}
$$

Verification of solutions

$$
-\frac{(R-y)(y+R)}{\sqrt{-y^{2}+R^{2}}}=x+c_{1}
$$

Verified OK.
Solving equation (2)
Integrating both sides gives

$$
\begin{aligned}
& \int-\frac{y}{\sqrt{R^{2}-y^{2}}} d y=\int d x \\
& \frac{(R-y)(y+R)}{\sqrt{-y^{2}+R^{2}}}=x+c_{2}
\end{aligned}
$$

Summary
The solution(s) found are the following

$$
\begin{equation*}
\frac{(R-y)(y+R)}{\sqrt{-y^{2}+R^{2}}}=x+c_{2} \tag{1}
\end{equation*}
$$

Verification of solutions

$$
\frac{(R-y)(y+R)}{\sqrt{-y^{2}+R^{2}}}=x+c_{2}
$$

Verified OK.

### 1.8.1 Maple step by step solution

Let's solve
$y^{2}\left(1+y^{\prime 2}\right)=R^{2}$

- Highest derivative means the order of the ODE is 1 $y^{\prime}$
- Separate variables

$$
\frac{y^{\prime} y}{\sqrt{-y^{2}+R^{2}}}=1
$$

- Integrate both sides with respect to $x$

$$
\int \frac{y^{\prime} y}{\sqrt{-y^{2}+R^{2}}} d x=\int 1 d x+c_{1}
$$

- Evaluate integral

$$
-\sqrt{-y^{2}+R^{2}}=x+c_{1}
$$

- $\quad$ Solve for $y$

$$
\left\{y=\sqrt{R^{2}-c_{1}^{2}-2 c_{1} x-x^{2}}, y=-\sqrt{R^{2}-c_{1}^{2}-2 c_{1} x-x^{2}}\right\}
$$

Maple trace

```
`Methods for first order ODEs:
    *** Sublevel 2 ***
    Methods for first order ODEs:
    -> Solving 1st order ODE of high degree, 1st attempt
    trying 1st order WeierstrassP solution for high degree ODE
    trying 1st order WeierstrassPPrime solution for high degree ODE
    trying 1st order JacobiSN solution for high degree ODE
    trying 1st order ODE linearizable_by_differentiation
    trying differential order: 1; missing variables
    <- differential order: 1; missing x successful`
```


## $\checkmark$ Solution by Maple

Time used: 0.031 (sec). Leaf size: 54

```
dsolve(y(x)^2*(1+diff(y(x),x)^2)=R^2,y(x), singsol=all)
```

$$
\begin{aligned}
& y(x)=-R \\
& y(x)=R \\
& y(x)=\sqrt{R^{2}-c_{1}^{2}+2 c_{1} x-x^{2}} \\
& y(x)=-\sqrt{\left(R+c_{1}-x\right)\left(R-c_{1}+x\right)}
\end{aligned}
$$

$\checkmark$ Solution by Mathematica
Time used: 0.22 (sec). Leaf size: 101
DSolve[y[x] $2 *\left(1+\left(y y^{\prime}[x]\right) \wedge 2\right)==R^{\wedge} 2, y[x], x$, IncludeSingularSolutions $->$ True]

$$
\begin{aligned}
& y(x) \rightarrow-\sqrt{R^{2}-\left(x+c_{1}\right)^{2}} \\
& y(x) \rightarrow \sqrt{R^{2}-\left(x+c_{1}\right)^{2}} \\
& y(x) \rightarrow-\sqrt{R^{2}-\left(x-c_{1}\right)^{2}} \\
& y(x) \rightarrow \sqrt{R^{2}-\left(x-c_{1}\right)^{2}} \\
& y(x) \rightarrow-R \\
& y(x) \rightarrow R
\end{aligned}
$$

## 1.9 problem example page 47

$$
\text { 1.9.1 Solving as clairaut ode . . . . . . . . . . . . . . . . . . . . . . . } 96
$$

Internal problem ID [4353]
Internal file name [OUTPUT/3846_Sunday_June_05_2022_11_21_24_AM_63114565/index.tex]
Book: Differential and integral calculus, vol II By N. Piskunov. 1974
Section: Chapter 1
Problem number: example page 47 .
ODE order: 1.
ODE degree: 4.

The type(s) of ODE detected by this program : "clairaut"
Maple gives the following as the ode type
[_Clairaut]

$$
y-x y^{\prime}-\frac{a y^{\prime}}{\sqrt{1+y^{\prime 2}}}=0
$$

### 1.9.1 Solving as clairaut ode

This is Clairaut ODE. It has the form

$$
y=x y^{\prime}+g\left(y^{\prime}\right)
$$

Where $g$ is function of $y^{\prime}(x)$. Let $p=y^{\prime}$ the ode becomes

$$
y-x p-\frac{a p}{\sqrt{p^{2}+1}}=0
$$

Solving for $y$ from the above results in

$$
\begin{equation*}
y=\frac{p\left(\sqrt{p^{2}+1} x+a\right)}{\sqrt{p^{2}+1}} \tag{1~A}
\end{equation*}
$$

The above ode is a Clairaut ode which is now solved. We start by replacing $y^{\prime}$ by $p$ which gives

$$
\begin{aligned}
y & =x p+\frac{a p}{\sqrt{p^{2}+1}} \\
& =x p+\frac{a p}{\sqrt{p^{2}+1}}
\end{aligned}
$$

Writing the ode as

$$
y=x p+g(p)
$$

We now write $g \equiv g(p)$ to make notation simpler but we should always remember that $g$ is function of $p$ which in turn is function of $x$. Hence the above becomes

$$
\begin{equation*}
y=x p+g \tag{1}
\end{equation*}
$$

Then we see that

$$
g=\frac{a p}{\sqrt{p^{2}+1}}
$$

Taking derivative of (1) w.r.t. $x$ gives

$$
\begin{aligned}
& p=\frac{d}{d x}(x p+g) \\
& p=\left(p+x \frac{d p}{d x}\right)+\left(g^{\prime} \frac{d p}{d x}\right) \\
& p=p+\left(x+g^{\prime}\right) \frac{d p}{d x} \\
& 0=\left(x+g^{\prime}\right) \frac{d p}{d x}
\end{aligned}
$$

Where $g^{\prime}$ is derivative of $g(p)$ w.r.t. $p$. The general solution is given by

$$
\begin{aligned}
\frac{d p}{d x} & =0 \\
p & =c_{1}
\end{aligned}
$$

Substituting this in (1) gives the general solution as

$$
y=c_{1} x+\frac{a c_{1}}{\sqrt{c_{1}^{2}+1}}
$$

The singular solution is found from solving for $p$ from

$$
x+g^{\prime}(p)=0
$$

And substituting the result back in (1). Since we found above that $g=\frac{a p}{\sqrt{p^{2}+1}}$, then the above equation becomes

$$
\begin{aligned}
x+g^{\prime}(p) & =x+\frac{a}{\sqrt{p^{2}+1}}-\frac{a p^{2}}{\left(p^{2}+1\right)^{\frac{3}{2}}} \\
& =0
\end{aligned}
$$

Solving the above for $p$ results in

$$
\begin{aligned}
& p_{1}=\frac{\sqrt{\left(-a x^{2}\right)^{\frac{2}{3}}-x^{2}}}{x} \\
& p_{2}=-\frac{\sqrt{\left(-a x^{2}\right)^{\frac{2}{3}}-x^{2}}}{x} \\
& p_{3}=\frac{\sqrt{2} \sqrt{i \sqrt{3}\left(-a x^{2}\right)^{\frac{2}{3}}-\left(-a x^{2}\right)^{\frac{2}{3}}-2 x^{2}}}{2 x} \\
& p_{4}=-\frac{\sqrt{2} \sqrt{i \sqrt{3}\left(-a x^{2}\right)^{\frac{2}{3}}-\left(-a x^{2}\right)^{\frac{2}{3}}-2 x^{2}}}{2 x} \\
& p_{5}=\frac{\sqrt{-2 i \sqrt{3}\left(-a x^{2}\right)^{\frac{2}{3}}-2\left(-a x^{2}\right)^{\frac{2}{3}}-4 x^{2}}}{2 x} \\
& p_{6}=-\frac{\sqrt{-2 i \sqrt{3}\left(-a x^{2}\right)^{\frac{2}{3}}-2\left(-a x^{2}\right)^{\frac{2}{3}}-4 x^{2}}}{2 x}
\end{aligned}
$$

Substituting the above back in (1) results in

$$
\begin{aligned}
& y_{1}=\frac{\sqrt{\left(-a x^{2}\right)^{\frac{2}{3}}-x^{2}}\left(x \sqrt{\frac{\left(-a x^{2}\right)^{\frac{2}{3}}}{x^{2}}}+a\right)}{x \sqrt{\frac{\left(-a x^{2}\right)^{\frac{2}{3}}}{x^{2}}}} \\
& y_{2}=\frac{\left(-x \sqrt{\left.\frac{\left(-a x^{2}\right)^{\frac{2}{3}}}{x^{2}}-a\right) \sqrt{\left(-a x^{2}\right)^{\frac{2}{3}}-x^{2}}}\right.}{x \sqrt{\frac{\left(-a x^{2}\right)^{\frac{2}{3}}}{x^{2}}}} \\
& \left.y_{3}=\frac{\sqrt{i \sqrt{3}\left(-a x^{2}\right)^{\frac{2}{3}}-\left(-a x^{2}\right)^{\frac{2}{3}}-2 x^{2}}\left(\sqrt{2} x \sqrt{\frac{(i \sqrt{3}-1)\left(-a x^{2}\right)^{\frac{2}{3}}}{x^{2}}}+2 a\right)}{2 x \sqrt{\frac{(i \sqrt{3}-1)\left(-a x^{2}\right)^{\frac{2}{3}}}{x^{2}}}}\right) \\
& y_{4}=-\frac{\sqrt{\frac{(i \sqrt{3}-1)\left(-a x^{2}\right)^{\frac{2}{3}}}{x^{2}}} x}{\left.\sqrt{i \sqrt{3}\left(-a x^{2}\right)^{\frac{2}{3}}-\left(-a x^{2}\right)^{\frac{2}{3}-2 x^{2}}\left(\frac{\sqrt{2} x \sqrt{\frac{(i \sqrt{3}-1)\left(-a x^{2}\right)^{\frac{2}{3}}}{x^{2}}}}{2}\right)}\right)} \\
& \sqrt{2 x \sqrt{-\frac{(1+i \sqrt{3})\left(-a x^{2}\right)^{\frac{2}{3}}}{x^{2}}}} \\
& y_{5}=\frac{\sqrt{-\frac{(1+i \sqrt{3})\left(-a x^{2}\right)^{\frac{2}{3}}}{x^{2}}} x}{\left.\sqrt{-\left(-a x^{2}\right)^{\frac{2}{3}}-i \sqrt{3}\left(-a x^{2}\right)^{\frac{2}{3}-2 x^{2}}\left(\sqrt{2} x \sqrt{-\frac{(1+i \sqrt{3})\left(-a x^{2}\right)^{\frac{2}{3}}}{x^{2}}}\right.}+2 a\right)} \\
& y_{6}=-\frac{\left.\sqrt{-\left(-a x^{2}\right)^{\frac{2}{3}}-i \sqrt{3}\left(-a x^{2}\right)^{\frac{2}{3}-2 x^{2}}\left(\frac{\sqrt{2} x \sqrt{-\frac{(1+i \sqrt{3})\left(-a x^{2}\right)^{\frac{2}{3}}}{x^{2}}}}{2}\right.}\right)}{} \\
& \left.y^{2}\right)
\end{aligned}
$$

## Summary

The solution(s) found are the following

$$
\left.\begin{array}{l}
y=c_{1} x+\frac{a c_{1}}{\sqrt{c_{1}^{2}+1}} \\
y=\frac{\sqrt{\left(-a x^{2}\right)^{\frac{2}{3}}-x^{2}}\left(x \sqrt{\frac{\left(-a x^{2}\right)^{\frac{2}{3}}}{x^{2}}}+a\right)}{x \sqrt{\frac{\left(-a x^{2}\right)^{\frac{2}{3}}}{x^{2}}}} \\
y=\frac{\left(-x \sqrt{\frac{\left(-a x^{2}\right)^{\frac{2}{3}}}{x^{2}}}-a\right) \sqrt{\left(-a x^{2}\right)^{\frac{2}{3}}-x^{2}}}{x \sqrt{\frac{\left(-a x^{2}\right)^{\frac{2}{3}}}{x^{2}}}} \\
\left.y=\frac{\sqrt{i \sqrt{3}\left(-a x^{2}\right)^{\frac{2}{3}}-\left(-a x^{2}\right)^{\frac{2}{3}-2 x^{2}}\left(\sqrt{2} x \sqrt{\frac{(i \sqrt{3}-1)\left(-a x^{2}\right)^{\frac{2}{3}}}{x^{2}}}+2 a\right)}}{\sqrt{\frac{(i \sqrt{3}-1)\left(-a x^{2}\right)^{\frac{2}{3}}}{x^{2}}}}\right) \\
\left.y=-\frac{\sqrt{i \sqrt{3}\left(-a x^{2}\right)^{\frac{2}{3}}-\left(-a x^{2}\right)^{\frac{2}{3}-2 x^{2}}}\left(\frac{\sqrt{2} x \sqrt{\frac{(i \sqrt{3}-1)\left(-a x^{2}\right)^{\frac{2}{3}}}{x^{2}}}}{2}\right.}{2 x}\right) \\
\left.y=\frac{\sqrt{-\left(-a x^{2}\right)^{\frac{2}{3}}-i \sqrt{3}\left(-a x^{2}\right)^{\frac{2}{3}}-2 x^{2}\left(\sqrt{2} x \sqrt{-\frac{(1+i \sqrt{3})\left(-a x^{2}\right)^{\frac{2}{3}}}{x^{2}}}\right.}}{-\frac{(1+i \sqrt{3})\left(-a x^{2}\right)^{\frac{2}{3}}}{x^{2}}}+2 a\right) \\
y=-\frac{\sqrt{-\frac{(1+i \sqrt{3})\left(-a x^{2}\right)^{\frac{2}{3}}}{x^{2}}} x}{\left.\sqrt{-\left(-a x^{2}\right)^{\frac{2}{3}}-i \sqrt{3}\left(-a x^{2}\right)^{\frac{2}{3}-2 x^{2}}\left(\frac{\sqrt{2} x \sqrt{-\frac{(1+i \sqrt{3})\left(-a x^{2}\right)^{\frac{2}{3}}}{x^{2}}}}{2}\right.}\right)}  \tag{7}\\
y
\end{array}\right)
$$

## Verification of solutions

$$
y=c_{1} x+\frac{a c_{1}}{\sqrt{c_{1}^{2}+1}}
$$

Verified OK.

$$
y=\frac{\sqrt{\left(-a x^{2}\right)^{\frac{2}{3}}-x^{2}}\left(x \sqrt{\frac{\left(-a x^{2}\right)^{\frac{2}{3}}}{x^{2}}}+a\right)}{x \sqrt{\frac{\left(-a x^{2}\right)^{\frac{2}{3}}}{x^{2}}}}
$$

Verified OK.

$$
y=\frac{\left(-x \sqrt{\frac{\left(-a x^{2}\right)^{\frac{2}{3}}}{x^{2}}}-a\right) \sqrt{\left(-a x^{2}\right)^{\frac{2}{3}}-x^{2}}}{x \sqrt{\frac{\left(-a x^{2}\right)^{\frac{2}{3}}}{x^{2}}}}
$$

Verified OK.

$$
y=\frac{\sqrt{i \sqrt{3}\left(-a x^{2}\right)^{\frac{2}{3}}-\left(-a x^{2}\right)^{\frac{2}{3}}-2 x^{2}}\left(\sqrt{2} x \sqrt{\frac{(i \sqrt{3}-1)\left(-a x^{2}\right)^{\frac{2}{3}}}{x^{2}}}+2 a\right)}{2 x \sqrt{\frac{(i \sqrt{3}-1)\left(-a x^{2}\right)^{\frac{2}{3}}}{x^{2}}}}
$$

Verified OK.

$$
y=-\frac{\sqrt{i \sqrt{3}\left(-a x^{2}\right)^{\frac{2}{3}}-\left(-a x^{2}\right)^{\frac{2}{3}}-2 x^{2}}\left(\frac{\left.\sqrt{2} x \sqrt{\frac{(i \sqrt{3}-1)\left(-a x^{2}\right)^{\frac{2}{3}}}{x^{2}}}+a\right)}{\sqrt{\frac{(i \sqrt{3}-1)\left(-a x^{2}\right)^{\frac{2}{3}}}{x^{2}}} x} x\right.}{x}
$$

Verified OK.

$$
y=\frac{\sqrt{-\left(-a x^{2}\right)^{\frac{2}{3}}-i \sqrt{3}\left(-a x^{2}\right)^{\frac{2}{3}}-2 x^{2}}\left(\sqrt{2} x \sqrt{-\frac{(1+i \sqrt{3})\left(-a x^{2}\right)^{\frac{2}{3}}}{x^{2}}}+2 a\right)}{2 x \sqrt{-\frac{(1+i \sqrt{3})\left(-a x^{2}\right)^{\frac{2}{3}}}{x^{2}}}}
$$

Verified OK.

$$
y=-\frac{\sqrt{-\left(-a x^{2}\right)^{\frac{2}{3}}-i \sqrt{3}\left(-a x^{2}\right)^{\frac{2}{3}}-2 x^{2}}\left(\frac{\left.\sqrt{2} x \sqrt{-\frac{(1+i \sqrt{3})\left(-a x^{2}\right)^{\frac{2}{3}}}{x^{2}}}+a\right)}{\sqrt{-\frac{(1+i \sqrt{3})\left(-a x^{2}\right)^{\frac{2}{3}}}{101 x^{2}}} x}\right.}{x}
$$

Verified OK.

Maple trace

```
`Methods for first order ODEs:
-> Solving 1st order ODE of high degree, 1st attempt
trying 1st order WeierstrassP solution for high degree ODE
trying 1st order WeierstrassPPrime solution for high degree ODE
trying 1st order JacobiSN solution for high degree ODE
trying 1st order ODE linearizable_by_differentiation
trying differential order: 1; missing variables
trying dAlembert
<- dAlembert successful`
```

$\checkmark$ Solution by Maple
Time used: 1.391 (sec). Leaf size: 17
dsolve( $y(x)=x * \operatorname{diff}(y(x), x)+a * \operatorname{diff}(y(x), x) /(\operatorname{sqrt}(1+\operatorname{diff}(y(x), x) \sim 2)), y(x), \quad$ singsol=all)

$$
y(x)=c_{1}\left(x+\frac{a}{\sqrt{c_{1}^{2}+1}}\right)
$$

$\checkmark$ Solution by Mathematica
Time used: 35.7 (sec). Leaf size: 27
DSolve[y[x]==x*y'[x]+a*y'[x]/(Sqrt[1+(y'[x])~2]),y[x],x,IncludeSingularSolutions $\rightarrow$ True]

$$
\begin{aligned}
& y(x) \rightarrow c_{1}\left(x+\frac{a}{\sqrt{1+c_{1}^{2}}}\right) \\
& y(x) \rightarrow 0
\end{aligned}
$$

### 1.10 problem Example, page 49

1.10.1 Solving as dAlembert ode

Internal problem ID [4354]
Internal file name [OUTPUT/3847_Sunday_June_05_2022_11_27_37_AM_38946746/index.tex]
Book: Differential and integral calculus, vol II By N. Piskunov. 1974
Section: Chapter 1
Problem number: Example, page 49.
ODE order: 1.
ODE degree: 2 .

The type(s) of ODE detected by this program : "dAlembert"
Maple gives the following as the ode type
[[_homogeneous, `class C`], _rational, _dAlembert]

$$
y-x y^{\prime 2}-y^{\prime 2}=0
$$

### 1.10.1 Solving as dAlembert ode

Let $p=y^{\prime}$ the ode becomes

$$
-x p^{2}-p^{2}+y=0
$$

Solving for $y$ from the above results in

$$
\begin{equation*}
y=x p^{2}+p^{2} \tag{1~A}
\end{equation*}
$$

This has the form

$$
\begin{equation*}
y=x f(p)+g(p) \tag{}
\end{equation*}
$$

Where $f, g$ are functions of $p=y^{\prime}(x)$. The above ode is dAlembert ode which is now solved. Taking derivative of $\left({ }^{*}\right)$ w.r.t. $x$ gives

$$
\begin{align*}
p & =f+\left(x f^{\prime}+g^{\prime}\right) \frac{d p}{d x} \\
p-f & =\left(x f^{\prime}+g^{\prime}\right) \frac{d p}{d x} \tag{2}
\end{align*}
$$

Comparing the form $y=x f+g$ to (1A) shows that

$$
\begin{aligned}
& f=p^{2} \\
& g=p^{2}
\end{aligned}
$$

Hence (2) becomes

$$
\begin{equation*}
-p^{2}+p=(2 x p+2 p) p^{\prime}(x) \tag{2~A}
\end{equation*}
$$

The singular solution is found by setting $\frac{d p}{d x}=0$ in the above which gives

$$
-p^{2}+p=0
$$

Solving for $p$ from the above gives

$$
\begin{aligned}
& p=0 \\
& p=1
\end{aligned}
$$

Substituting these in (1A) gives

$$
\begin{aligned}
& y=0 \\
& y=x+1
\end{aligned}
$$

The general solution is found when $\frac{\mathrm{d} p}{\mathrm{~d} x} \neq 0$. From eq. (2A). This results in

$$
\begin{equation*}
p^{\prime}(x)=\frac{-p(x)^{2}+p(x)}{2 p(x) x+2 p(x)} \tag{3}
\end{equation*}
$$

This ODE is now solved for $p(x)$.
Entering Linear first order ODE solver. In canonical form a linear first order is

$$
p^{\prime}(x)+p(x) p(x)=q(x)
$$

Where here

$$
\begin{aligned}
p(x) & =\frac{1}{2 x+2} \\
q(x) & =\frac{1}{2 x+2}
\end{aligned}
$$

Hence the ode is

$$
p^{\prime}(x)+\frac{p(x)}{2 x+2}=\frac{1}{2 x+2}
$$

The integrating factor $\mu$ is

$$
\begin{aligned}
\mu & =\mathrm{e}^{\int \frac{1}{2 x+2} d x} \\
& =\sqrt{x+1}
\end{aligned}
$$

The ode becomes

$$
\begin{aligned}
\frac{\mathrm{d}}{\mathrm{~d} x}(\mu p) & =(\mu)\left(\frac{1}{2 x+2}\right) \\
\frac{\mathrm{d}}{\mathrm{~d} x}(\sqrt{x+1} p) & =(\sqrt{x+1})\left(\frac{1}{2 x+2}\right) \\
\mathrm{d}(\sqrt{x+1} p) & =\left(\frac{1}{2 \sqrt{x+1}}\right) \mathrm{d} x
\end{aligned}
$$

Integrating gives

$$
\begin{aligned}
& \sqrt{x+1} p=\int \frac{1}{2 \sqrt{x+1}} \mathrm{~d} x \\
& \sqrt{x+1} p=\sqrt{x+1}+c_{1}
\end{aligned}
$$

Dividing both sides by the integrating factor $\mu=\sqrt{x+1}$ results in

$$
p(x)=1+\frac{c_{1}}{\sqrt{x+1}}
$$

Substituing the above solution for $p$ in (2A) gives

$$
y=x\left(1+\frac{c_{1}}{\sqrt{x+1}}\right)^{2}+\left(1+\frac{c_{1}}{\sqrt{x+1}}\right)^{2}
$$

Summary
The solution(s) found are the following

$$
\begin{align*}
& y=0  \tag{1}\\
& y=x+1  \tag{2}\\
& y=x\left(1+\frac{c_{1}}{\sqrt{x+1}}\right)^{2}+\left(1+\frac{c_{1}}{\sqrt{x+1}}\right)^{2} \tag{3}
\end{align*}
$$

## Verification of solutions

$$
y=0
$$

Verified OK.

$$
y=x+1
$$

Verified OK.

$$
y=x\left(1+\frac{c_{1}}{\sqrt{x+1}}\right)^{2}+\left(1+\frac{c_{1}}{\sqrt{x+1}}\right)^{2}
$$

Verified OK.
Maple trace

- Methods for first order ODEs:
*** Sublevel 2 ***
Methods for first order ODEs:
-> Solving 1st order ODE of high degree, 1st attempt
trying 1st order WeierstrassP solution for high degree ODE
trying 1st order WeierstrassPPrime solution for high degree ODE
trying 1st order JacobiSN solution for high degree ODE
trying 1st order ODE linearizable_by_differentiation
trying differential order: 1; missing variables
trying dAlembert
<- dAlembert successful`
$\checkmark$ Solution by Maple
Time used: 0.016 (sec). Leaf size: 53

```
dsolve(y(x)=x*diff(y(x),x)^2+diff(y(x),x)^2,y(x), singsol=all)
```

$$
\begin{aligned}
& y(x)=0 \\
& y(x)=\frac{\left(x+1+\sqrt{(1+x)\left(1+c_{1}\right)}\right)^{2}}{1+x} \\
& y(x)=\frac{\left(-x-1+\sqrt{(1+x)\left(1+c_{1}\right)}\right)^{2}}{1+x}
\end{aligned}
$$

$\checkmark$ Solution by Mathematica
Time used: 0.062 (sec). Leaf size: 57
DSolve[y[x]==x*(y'[x])^2+(y'[x])^2,y[x],x,IncludeSingularSolutions $->$ True]

$$
\begin{aligned}
& y(x) \rightarrow x-c_{1} \sqrt{x+1}+1+\frac{c_{1}^{2}}{4} \\
& y(x) \rightarrow x+c_{1} \sqrt{x+1}+1+\frac{c_{1}^{2}}{4} \\
& y(x) \rightarrow 0
\end{aligned}
$$

