

Question 1 (25 points)

The 4-kg rod AB is attached to a collar of negligible mass at A and to a flywheel at B. The flywheel has a mass of 16 kg and a radius of gyration of 180 mm. Knowing that in the position shown the angular velocity of the flywheel is 60 rpm clockwise, determine the angular velocity of the flywheel when Point B is directly below C.

Find ω_2

given $m_A = 0$

$$m_{AB} = 4 \text{ kg}$$

$$m_C = 16 \text{ kg}$$

$$k_c = .18 \text{ m}$$

$$\omega_1 = 60 \text{ rpm} \left(\frac{2\pi}{60} \right) = 2\pi \text{ rad/s}$$

energy method

$$T_1 + V_1 + \cancel{U_{12}} = T_2 + V_2$$

\rightarrow O, by choice of datum O, no external F, M

state

$$T_1 = T_{IC} + T_{AB} + T_{IA}$$

disk rod collar

$$T_1 = \frac{1}{2} I_c \omega_{c1}^2 + \frac{1}{2} m_{AB} V_{G,AB1}^2 + \frac{1}{2} I_{G,AB} \omega_{AB1}^2 + \frac{1}{2} m_b V_{A1}^2$$

from IC

from IC of AB $\Rightarrow \omega_{AB1} = 0$

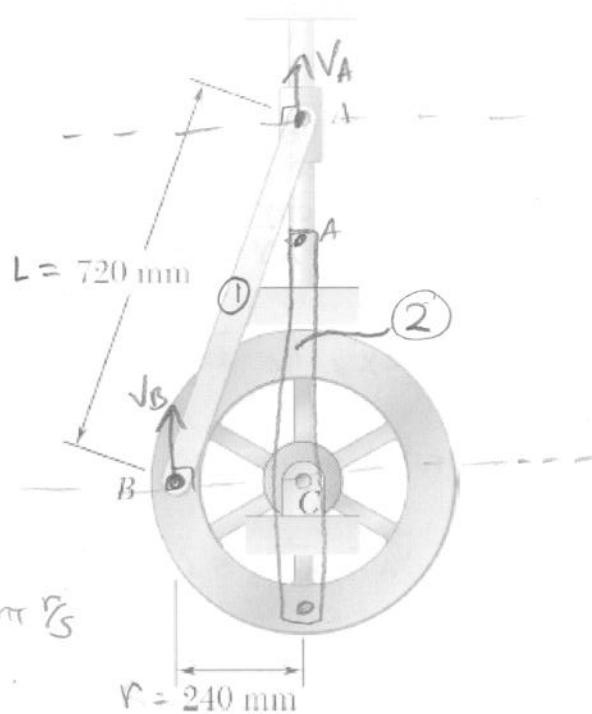
$$\vec{V}_{G,AB1} = \vec{V}_{B1} + \vec{\omega}_{AB1} \times \vec{r}_{G/A} \quad \Rightarrow \quad \vec{V}_{G,AB1} = \vec{V}_{B1} = \vec{\omega}_c \times \vec{r}_{Bc}$$

$$\vec{V}_{G,AB1} = \omega_{c1} r \hat{j}$$

$$T_1 = \frac{1}{2} (m_c k_c^2) \omega_{c1}^2 + \frac{1}{2} m_{AB} (\omega_{c1} r)^2$$

$$T_1 = \frac{1}{2} (16 \text{ kg} \cdot 18 \text{ m}^2) (2\pi)^2 + \frac{1}{2} (4 \text{ kg}) (2\pi (0.24 \text{ m}))^2$$

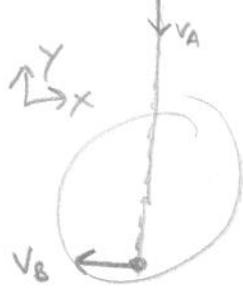
$$T_1 = 14.78 \text{ N-m}$$



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State 2 KE

$$I_C \quad p_t A = I_C$$



$$T_2 = \underbrace{\frac{1}{2} I_C \omega_{c2}^2}_{\text{disc}} + \underbrace{\frac{1}{2} m_{AB} V_{G,AB2}^2}_{\text{rod AB}} + \underbrace{\frac{1}{2} I_{G,AB} \omega_{AB2}^2}_{\text{collar A}} + \underbrace{\frac{1}{2} m_A V_A^2}_{0}$$

I_C @ pt A, so rod AB is in pure rotation about A

from AB $\vec{v}_B = \vec{v}_A + \vec{\omega}_{AB2} \times \vec{r}_{B/A}$ $\vec{\omega}_{AB2} = \omega_{AB2} \hat{k}$

$$\vec{v}_B = \omega_{AB2} L \uparrow$$

$$\vec{r}_{B/A} = -L \hat{j}$$

from disc $\vec{v}_B = \vec{v}_C + \vec{\omega}_{c2} \times \vec{r}_{B/C}$ $\vec{\omega}_{c2} = \omega_{c2} \hat{k}$

$$\vec{v}_B = \omega_{c2} r \uparrow$$

$$\vec{r}_{B/C} = -r \hat{j}$$

Set $\textcircled{1} = \textcircled{2}$ for \vec{v}_B

$$\omega_{AB2} L = \omega_{c2} r \rightarrow \boxed{\omega_{AB2} = \omega_{c2} \frac{r}{L}} *$$

find: $\vec{v}_{G,AB2} = \vec{v}_A + \vec{\omega}_{AB2} \times \vec{r}_{G/A}$ $\vec{r}_{G,AB/A} = -\frac{L}{2} \hat{j}$

$$\boxed{\vec{v}_{G,AB2} = \omega_{c2} \frac{r}{L} \left(\frac{L}{2} \right) \uparrow = \omega_{c2} \frac{r}{2} \uparrow} **$$

Sub * & ** into T_2

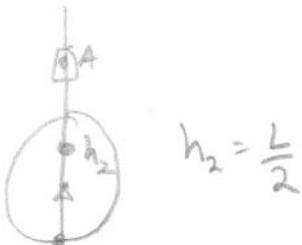
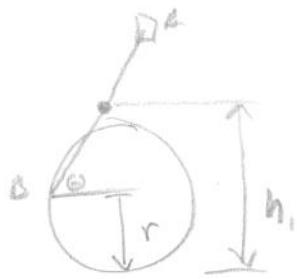
$$T_2 = \frac{1}{2} (m_C k_C^2) \omega_{c2}^2 + \frac{1}{2} m_{AB} \frac{r^2}{4} \omega_{c2}^2 + \frac{1}{2} \left(\frac{1}{2} m_{AB} L^2 \right) \frac{r^2}{L^2} \omega_{c2}^2$$

$$T_2 = \frac{1}{2} (m_C k_C^2) \omega_{c2}^2 + \frac{1}{6} m_{AB} r^2 \omega_{c2}^2$$

$$\boxed{T_2 = 0.298 \omega_{c2}^2}$$

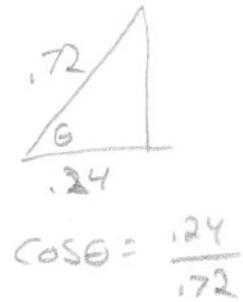
Q1 P.3

State 2: PE $V_2 = m_A g \Delta h_{ABG}$



$$h_2 = \frac{L}{2}$$

$$h_1 = r + \frac{L}{2} \sin\theta$$



$$\cos\theta = \frac{0.24}{0.72}$$

$$\theta = 70.5^\circ$$

$$\Delta h_{AB} = h_2 - h_1 = \frac{L}{2} - \left(r + \frac{L}{2} \sin\theta\right)$$

$$\Delta h_{AB} = -0.219 \text{ m}$$

$$V_2 = m_{AB} g \Delta h_{AB} = 4(9.81)(-0.219 \text{ m}) = -8.59 \text{ Nm}$$

$$T_1 = T_2 + V_2$$

$$14.78 \text{ Nm} = .298 \omega_{c2}^2 - 8.59 \text{ Nm}$$

$$\boxed{\omega_{c2} = 8.86 \text{ rad/s}}$$

Question 2 (25 points)

The crane's telescopic boom rotates with the angular velocity and angular acceleration shown. At the same instant, the boom is extending with a constant speed of 0.5 ft/s, measured relative to the boom. Determine the velocity and acceleration vectors of point B in the XY coordinate system given.

find \vec{V}_{BXY} & \vec{a}_{BXY}

fix rotating CS @ pt A

$$\vec{V}_B = \vec{V}_A + \vec{\omega}_{AB} \times \vec{r}_{BA} + \vec{V}_{B\text{rel}}$$

$$\vec{V}_B = \omega_{AB} \hat{r}_{BA} \uparrow + .5 \hat{j}$$

$$\vec{V}_B = (.02)60 \text{ ft} \uparrow + .5 \text{ ft/s} \hat{j}$$

$$xy \quad \vec{V}_B = 1.2 \hat{i} + .5 \hat{j} \text{ ft/s}$$

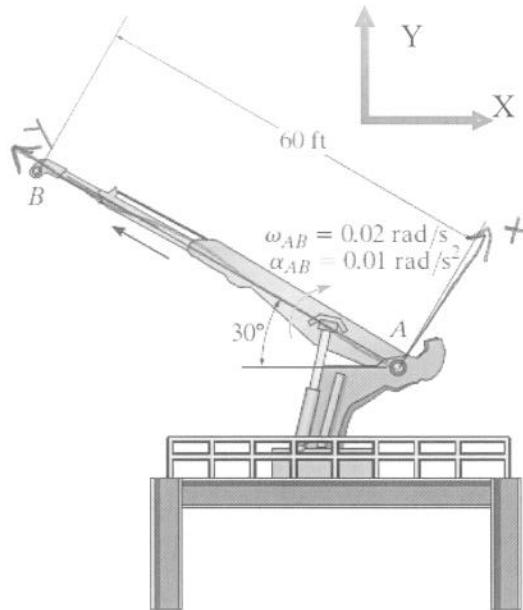
Convert back to XY coords

$$\hat{i} = \sin 30 \hat{I} + \cos 30 \hat{J}$$

$$\hat{j} = -\cos 30 \hat{I} + \sin 30 \hat{J}$$

$$xy \quad \vec{V}_B = 1.2 (\sin 30 \hat{I} + \cos 30 \hat{J}) + .5 (-\cos 30 \hat{I} + \sin 30 \hat{J}) \quad + \boxed{.5}$$

$$\vec{V}_B = .167 \hat{I} + 1.289 \hat{J} \text{ ft/s}$$



$$\vec{V}_{B\text{rel}} = .5 \text{ ft/s} \hat{j}$$

$$\vec{\omega}_{AB} = -.02 \text{ rad/s} \hat{k}$$

$$\vec{r}_{BA} = 60 \text{ ft} \hat{j}$$



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$$\vec{a}_B = \underbrace{\vec{a}_A}_{\text{O, pinned}} + \vec{\alpha}_{AB} \times \vec{r}_{B/A} + \underbrace{\vec{\omega}_{AB} \times (\vec{\omega}_{AB} \times \vec{r}_{B/A})}_{-\omega_{AB}^2 \vec{r}_{B/A}} + 2 \vec{\omega}_{AB} \times \vec{v}_{B/\text{rel}} + \underbrace{\vec{a}_{B/\text{rel}}}_{\text{O, constant } V_{B/\text{rel}}}$$

$$\vec{\alpha}_{AB} = \alpha_{AB} \hat{k} = -0.01 \hat{k} \text{ ft/s}^2$$

$$\vec{a}_B = -0.01 \hat{k} \times 60 \text{ ft} \hat{j} - (0.02)^2 60 \hat{j} + 2(0.02 \hat{k}) \times .5 \hat{j}$$

$$\vec{a}_B = 60(0.01) \hat{i} - 0.02^2 \cdot 60 \hat{j} + 2(0.02) \cdot 0.5 \hat{i}$$

$$xy \quad \vec{a}_B = .62 \hat{i} - .024 \hat{j} \text{ ft/s}^2$$

in XY

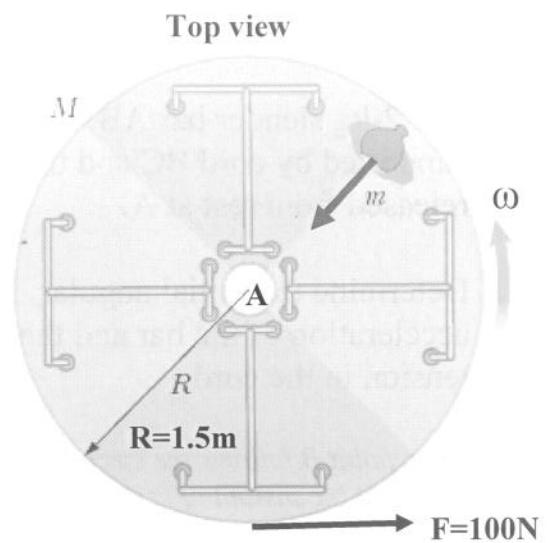
$$\vec{a}_B = .62 (\sin 30 \hat{i} + \cos 30 \hat{j}) - .024 (-\cos 30 \hat{i} + \sin 30 \hat{j}) \text{ ft/s}^2$$

$$\boxed{\vec{a}_B = .331 \hat{i} + .525 \hat{j} \text{ ft/s}^2}$$

Question 3 (25 points)

A merry go round with a rider ($m=20\text{kg}$) is initially rotating at a rate of 5 rad/s about point A. Someone pushes the merry go round with an average force of $F=100\text{N}$ for 5 seconds. During that time the rider moves from the edge of the merry go round to a position 0.5 meters from the center. The angular velocity after the push is 10 rad/s .

Determine the mass of the merry go round assuming it can be modeled as a circular disk.



Given

$$\vec{\omega}_1 = 5 \text{ r/s} \hat{k}$$

$$\vec{\omega}_2 = 10 \text{ r/s} \hat{k}$$

$$m_r = 20 \text{ kg}$$

$$F_{\text{ave}} = 100 \text{ N} \text{ for 5 seconds}$$

$$R = 1.5 \text{ m}$$

moment of inertia

$$I_{A1} = I_0 + m_r R^2$$

$$I_{0,\text{disc}} = \frac{1}{2} m_0 R^2$$

$$I_{A1} = \frac{1}{2} m_0 R^2 + m_r R^2$$

$$I_{A2} = \frac{1}{2} m_0 R^2 + m_r (0.5m)^2$$

Angular momentum - Impulse

$$I_{A1} \vec{\omega}_1 + \int \vec{M} dt = I_{A2} \vec{\omega}_2$$

$$\vec{M} = \cancel{J} \vec{r} \times \vec{F} = 1.5m (100 \text{ N}) \hat{k}$$

$$\left(\frac{1}{2} m_0 (10.5)^2 + 20 \text{ kg} (1.5^2) \right) 5 \text{ r/s} \hat{k} + \int_0^{5 \text{ sec}} 150 \text{ N} dt = \left(\frac{1}{2} m_0 (1.5)^2 + 20 (0.5m)^2 \right) 10 \text{ r/s} \hat{k}$$

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$$5.625 m_b + 225 \frac{kg-m^2}{s} + 150 Nm(5 \text{ sec}) = 11.25 \frac{kg-m^2}{s} (m_b) + 50 \frac{kg}{s}$$

$$225 + 750 = (11.25 - 5.625) m_b$$

$$m_b = 164.4 \text{ kg}$$

Question 4 (25 points)

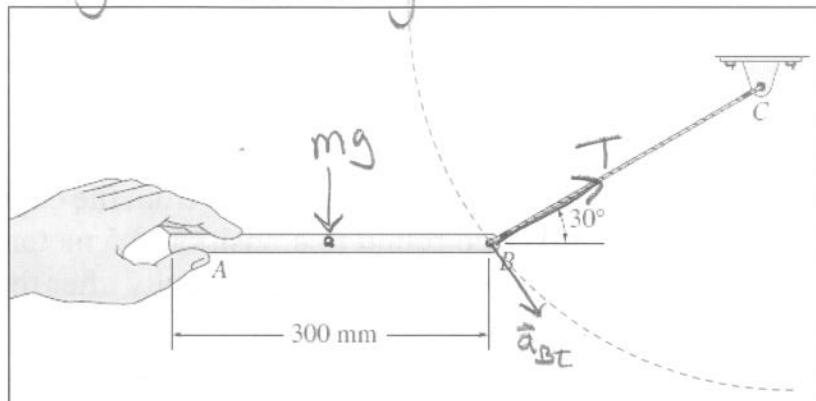
The 2-kg slender bar AB is supported by cord BC and then released from rest at A.

Determine the initial angular acceleration of the bar and the tension in the cord.

Hint: point B follows the circular path shown at the instant of release

Find α_{AB} & T

given $m = 2 \text{ kg}$



$$\text{NT} \quad \vec{a}_B = a_{BN}\hat{i}_N + a_{BT}\hat{i}_T$$

$$a_{BN} = \frac{V_B^2}{r}, \text{ with } V_B = 0 \text{ @ release}$$

$$\vec{a}_B = a_{BT}\hat{i}_T \rightarrow \textcircled{1} [\vec{a}_B = a_B \sin\theta \hat{i} - a_B \cos\theta \hat{j}]$$

$$\rightarrow \sum F_x = T \cos 30^\circ = m a_{Gx}$$

$$+ \uparrow \sum F_y = -mg + T \sin 30^\circ = m a_{Gy}$$

$$\textcircled{2} \sum M_G = T \sin 30^\circ \left(\frac{L}{2}\right) = I_G \alpha_{AB}$$

accel @ B

$$\vec{a}_B = \vec{a}_G + \vec{\alpha}_{AB} \times \vec{r}_{B/G}$$

$$\vec{r}_{B/G} = \frac{3}{2} \hat{i} \uparrow (\text{m})$$

$$\textcircled{2} \quad \vec{a}_B = a_{Gx}\hat{i} + a_{Gy}\hat{j} + \frac{3}{2}\alpha \hat{j}$$

Set i & j components from $\textcircled{1} = \textcircled{2}$

$$\text{i)} a_B \sin\theta = a_{Gx}$$

$$\text{j)} -a_B \cos\theta = a_{Gy} + \frac{3}{2}\alpha$$

3 eqns 4 unknowns
 → use what we know about
 \vec{a}_B to eliminate a
 variable

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i) $a_{Gx} = a_B \sin \theta$, $\theta = 30^\circ$

j) $a_{Gy} = -a_B \cos \theta - .15\alpha$

back to ΣF & ΣM

X) $T \cos 30 = m(a_B \sin \theta)$ $a_B = \frac{T}{m \tan 30^\circ}$

Y) $T \sin 30 - mg = m(-a_B \cos \theta - .15\alpha)$

$$\frac{T \sin 30 - mg}{m} = -\frac{T \cos 30}{m \tan 30^\circ} - .15\alpha$$

$$\frac{T}{m} \left(\underbrace{\sin 30 + \frac{\cos^2 30}{\sin 30}} \right) = g - .15\alpha$$

$$\frac{\sin^2 30 + \cos^2 30}{\sin 30} = \frac{1}{\sin 30} = 2$$

$$\boxed{T = g - .15\alpha}$$

M_G) $T \sin 30 \left(\frac{L}{2}\right) = \frac{1}{12} m L^2 \alpha_{AB}$ w/ $I_G = \frac{1}{12} m L^2$

$$(g - .15\alpha) \frac{L}{4} = \frac{1}{12} m L^2 \alpha_{AB}$$

$$\frac{gL}{4} = \left(\frac{1}{12} m L^2 + .15L \right) \alpha_{AB}$$

$$\frac{(9.81)(m)(.3m)}{4} = \left(\frac{1}{12}(2kg)(.3m)^2 + .15 \frac{(.3m)}{4} \right) \alpha_{AB}$$

$$\boxed{\alpha_{AB} = 28.03 \text{ rad/s}^2}$$

$$T = g - .15\alpha \Rightarrow \boxed{T = 5.61N}$$