# my solution to some discussion problems week 11 NOV 12 to NOV 18 ME 240 Dynamics, Fall 2017

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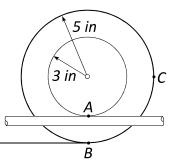
December 30, 2019

My solution is below

#### 0.1 Problem 6 3 Example 1

### Linkage - Acceleration

**Example 5.15**: A 3-in. radius drum is rigidly attached to a 5-in. radius drum as shown. The 3-in drum rolls without sliding on the surface shown, and a cord is wound around 5-in. drum. At the instant shown end D of the cord has a velocity of 8 in/s and an acceleration of 30 in/s², both directed to the left



**Determine** the accelerations of points *A*, *B*, and *C* of the drum.

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Given

$$\vec{V}_D = -8\hat{\imath}$$

$$\vec{a}_D = -30\hat{\imath}$$

But also (assuming cord is not extensible)

$$\vec{V}_B = -8\hat{\imath}$$

$$\vec{a}_B = -30\hat{\imath}$$

Since the point B is also on the large disk, its velocity can be used to find the angular velocity of the disk. The disk is spining in the clockwise direction. Using  $V_B = r\omega_{disk}$ , where r = 5 inch, then  $\omega_{disk} = \frac{-8}{5} = -1.6$  rad/sec or

$$\vec{\omega}_{disk} = -1.6\hat{k}$$

Similarly  $a_B = r\alpha_{disk}$  in the clockwise direction, hence  $\alpha_{disk} = \frac{a_B}{r} = \frac{-30}{5} = -6 \text{ rad/sec}^2$ 

$$\vec{\alpha}_{disk} = -6\hat{k}$$

Now

$$\vec{a}_A = \vec{a}_B + \vec{\alpha}_{AB} \times \vec{r}_{A/B} - \omega_{AB}^2 \vec{r}_{A/B}$$

Where  $\vec{r}_{A/B} = (r_2 - r_1)\hat{\jmath} = (5 - 3)\hat{\jmath} = 2\hat{\jmath}$  and the above becomes

$$\vec{a}_A = -30\hat{\imath} + (-6\hat{k} \times 2\hat{\jmath}) - (-1.6)^2 (2\hat{\jmath})$$

$$= -30\hat{\imath} + (12\hat{\imath}) - 5.12\hat{\jmath}$$

$$= -18\hat{\imath} - 5.12\hat{\jmath}$$

Now

$$\vec{a}_C = \vec{a}_O + \vec{\alpha}_{OC} \times \vec{r}_{C/O} - \omega_{OC}^2 \vec{r}_{C/O}$$

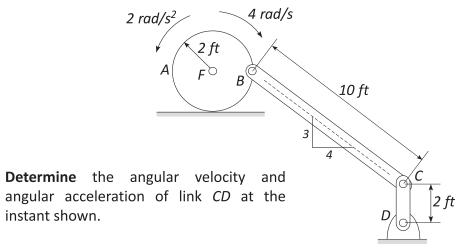
Where O is the center of the disk. Since disk is not sliding, then  $\vec{a}_O = 0$  and  $\vec{r}_{C/O} = 5\hat{\imath}$ . The above becomes

$$\vec{a}_C = -6\hat{k} \times 5\hat{\imath} - (-1.6)^2 5\hat{\imath}$$
  
=  $-30\hat{\jmath} - 12.8\hat{\imath}$ 

## 0.2 Problem 6 3 Example 2 rev2

## Linkage - Acceleration

**Example 5.16**: The disk at A is subjected to the angular motion (velocity and acceleration) shown.



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