### my cheat sheet

# EE 3015 Signals and Systems

# Spring 2020 University of Minnesota, Twin Cities

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### **Contents**

#### ■ Fourier series. Periodic signals, Continuous time

Let  $\omega_0 = \frac{2\pi}{T_0}$  be the fundamental frequency (rad/sec), and  $T_0$  the fundamental period, then

$$x(t) = \sum_{k=-\infty}^{\infty} a_k e^{jk\omega_0 t}$$
$$a_k = \frac{1}{T_0} \int_{T_0} x(t) e^{-jk\omega_0 t} dt$$

#### ■ Fourier series. Periodic signals, Discrete time

Let  $\Omega_0 = \frac{2\pi}{N}$  be the fundamental frequency (rad/sample), and N the fundamental period, then

$$x[n] = \sum_{k=0}^{N-1} a_k e^{jk\Omega_0 n} = \sum_{k=\langle N \rangle} a_k e^{jk\Omega_0 n}$$

$$a_k = \frac{1}{N} \sum_{n=0}^{N-1} x[n] e^{-jk\Omega_0 n} = \frac{1}{N} \sum_{n=\langle N \rangle} x[n] e^{-jk\Omega_0 n}$$

■ Fourier transform. Non periodic signal, Continuous time.

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\omega) e^{i\omega t} d\omega$$
$$X(\omega) = \int_{-\infty}^{\infty} x(t) e^{-i\omega t} dt$$

It is also possible to obtain a Fourier transform for periodic signal. For  $x(t) = \sum_{k=-\infty}^{\infty} a_k e^{ik\omega_0 t}$  its Fourier transform becomes  $(\omega_0 = \frac{2\pi}{T_0})$ 

$$X(\omega) = 2\pi \sum_{k=-\infty}^{\infty} a_k \delta(\omega - k\omega_0)$$

■ Fourier transform. Non periodic signal, Discrete time.

$$x[n] = \frac{1}{2\pi} \int_{-\pi}^{\pi} X(\Omega) e^{j\Omega n} d\Omega$$
$$X(\Omega) = \sum_{n=-\infty}^{\infty} x[n] e^{-j\Omega n}$$

It is also possible to obtain a Fourier transform for periodic discrete signal, where  $\Omega_0 = \frac{2\pi}{N}$ 

$$X(\Omega) = 2\pi \sum_{k=-\infty}^{\infty} a_k \delta \left(\Omega - k\Omega_0\right)$$

■ When input to LTI system is  $x(t) = e^{j\omega t}$  and system has impulse response h(t) then output is

$$y(t) = \int_{-\infty}^{\infty} h(\tau) x(t - \tau) d\tau$$
$$= \int_{-\infty}^{\infty} h(\tau) e^{j\omega(t - \tau)} d\tau$$
$$= e^{j\omega t} \int_{-\infty}^{\infty} h(\tau) e^{-j\omega \tau} d\tau$$
$$= e^{j\omega t} H(\omega)$$

Where  $H(\omega)$  is the Fourier transform of h(t). In the above  $e^{j\omega t}$  is called eigenfunctions of the system and  $H(\omega)$  the eigenvalues.

If input  $x(t) = a \cos(5\omega_0 t + \theta)$  and  $H(\omega)$  is the Fourier transform of the system, then  $y(t) = a |H(5\omega_0)| \cos(5\omega_0 t + \theta + \arg H(5\omega_0))$ 

Same for discrete time.

- Modulation. y(t) = x(t)h(t) in CTFT becomes  $Y(\omega) = \frac{1}{2\pi}X(\omega) \circledast H(\omega)$  where  $X(\omega) \circledast H(\omega) = \int_{-\infty}^{\infty} X(z)H(\omega-z)dz$ . Notice the extra  $\frac{1}{2\pi}$  factor.
- To find discrete period given a signal, write x[n] = x[n+N] and then solve for N. See HW's.

- Fourier transform relations.  $y(t) \iff Y(\omega)$  then  $y(at) \iff \frac{1}{a}Y(\frac{\omega}{a})$
- Euler relations.  $\cos x = \frac{e^{jx} + e^{-jx}}{2}$ ,  $\sin x = \frac{e^{jx} e^{-jx}}{2j}$
- Circuit. Voltage cross resistor R is V(t) = Ri(t). Voltage cross inductor L is  $V(t) = L\frac{di}{dt}$  and current across capacitor C is  $i(t) = C\frac{dV}{dt}$
- Partial fractions.

f(x)	A B
	$\frac{1}{2} + \frac{2}{2}$
(x-a)(x-b)	x-a $x-b$
f(x)	A B
$\overline{(x-a)^2}$	${x-a} + {(x-a)^2}$
f(x)	A Bx+C
$\overline{(x-a)(x^2+bx+c)}$	${x-a} + {x^2+bx+c}$
f(x)	A B C
$\frac{\overline{(x-a)(x+d)^2}}{f(x)}$	${x-a} + {x+d} + {(x+d)^2}$
f(x)	$A \rightarrow B$
$(x+d)^2$	$\frac{1}{x+d} + \frac{1}{(x+d)^2}$
f(x)	A = Bx + C
$\overline{(x-a)(x^2-b^2)}$	$\frac{1}{x+d} + \frac{1}{x^2-b^2}$
f(x)	Ax+B $Cx+D$
$\overline{(x^2-a)(x^2-b)}$	$\frac{1x+b}{x^2-a} + \frac{6x+b}{x^2-b}$
f(x)	Ax+B $Cx+D$
$\overline{\left(x^2-a\right)^2}$	$\frac{1}{x^2-a} + \frac{1}{(x^2-a)^2}$

- Parsevel's. For non-periodic cont. time:  $\int_{-\infty}^{\infty} |x(t)|^2 dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} |X(\omega)|^2 d\omega$ . For periodic cont. time:  $\frac{1}{T} \int_{T} |x(t)|^2 dt = \sum_{k=-\infty}^{\infty} |a_k|^2$ . For discrete:  $\frac{1}{2\pi} \int_{-\infty}^{\infty} |X(\Omega)|^2 d\Omega = \sum_{n=-\infty}^{\infty} |x[n]|^2$ .
- Properties Fourier series. If  $a_k = a_{-k}^*$  then x(t) is real. If  $a_k$  is even, then x(t) is even. For x(t) real and odd, then  $a_k$  are pure imaginary and odd. i.e.  $a_k = -a_{-k}$ , and  $a_0 = 0$ .
- More Fourier transform relations. <u>Continuos time</u>

$e^{-a t }$	$\frac{2a}{a^2+\omega^2}$
$x(t)e^{-j\omega_0t}$	$X(\omega + \omega_0)$
$x(t)e^{j\omega_0t}$	$X(\omega-\omega_0)$
$\frac{\sin(a\omega)}{\omega}$	Box from $t = -a \cdots a$

#### Discrete time

u [n]	$\frac{1}{1-e^{-j\Omega}}$
u[n-1]	$e^{-j\Omega}U(\Omega) = e^{-j\Omega}\frac{1}{1-e^{-j\Omega}}$
$a^nu[n]$	$\frac{1}{1-ae^{-j\Omega}}$
$e^{j\Omega_0 n}x[n]$	$X(\Omega - \Omega_0)$

From above we see that unit delay in discrete time means multiplying by  $e^{-j\Omega}$ .

■ Difference equations.  $y[n-1] \iff e^{-j\Omega}Y(\Omega)$ . For example, given y[n] - ay[n-1] = x[n] then applying DFT gives  $Y(\Omega) - ae^{-j\Omega}Y(\Omega) = X(\Omega)$  or  $H(\Omega) = \frac{Y(\Omega)}{X(\Omega)} = \frac{1}{1-ae^{-j\Omega}}$ . From tables, the inverse DFT of this is  $a^nu[n]$ . Need to know partial fractions sometimes. For example given  $y[n] - \frac{3}{4}y[n-1] + \frac{1}{8}y[n-2] = 2x[n]$  then

$$Y(\Omega) - \frac{3}{4}e^{-j\Omega}Y(\Omega) + \frac{1}{8}e^{-j2\Omega}Y(\Omega) = 2X(\Omega)$$

$$H(\Omega) = \frac{Y(\Omega)}{X(\Omega)}$$

$$= \frac{2}{\left(1 - \frac{3}{4}e^{-j\Omega} + \frac{1}{8}e^{-j2\Omega}\right)}$$

$$= \frac{2}{\left(1 - \frac{1}{2}e^{-j\Omega}\right)\left(1 - \frac{1}{4}e^{-j\Omega}\right)}$$

And using partial fractions gives  $H(\Omega) = \frac{4}{1 - \frac{1}{2}e^{-j\Omega}} - \frac{2}{1 - \frac{1}{4}e^{-j\Omega}}$ . Hence using above table gives  $h[n] = \left(4\left(\frac{1}{2}\right)^n - 2\left(\frac{1}{4}\right)^n\right)u[n]$ 

 $\blacksquare |X(\omega)|^2$  may be interpreted as the energy density spectrum of x(t). This means  $\frac{1}{2\pi} |X(\omega)|^2 d\omega$  is amount of energy in  $d\omega$  range of frequencies. i.e. between  $\omega$  and  $\omega + d\omega$ .  $|X(\omega)|$  is called the gain of the system and  $\arg(H(\omega))$  is called the phase shift of the system. When  $\arg(H(\omega))$  is linear function in  $\omega$  then the effect in time domain is time shift. (delay).

- $\blacksquare$  z transforms  $X(z) = \sum_{n=-\infty}^{\infty} x[n] z^{-n}$ . If  $x[n] \to X(z)$  then  $x[n-1] \to z^{-1}X(z)$ .
- $\blacksquare \frac{\sin(ax)}{ax} = \operatorname{sinc}\left(\frac{ax}{\pi}\right)$  and  $\frac{\sin(x)}{x} = \operatorname{sinc}\left(\frac{x}{\pi}\right)$ . In class we use  $\frac{\sin(\omega_c t)}{\pi t}$ . This has FT as rectangle from  $-\omega_c$  to  $\omega_c$  and amplitude 1.
- in digital, sampling rate is in hz, but units is samples per second and not cycles per second as with analog.

$$\Omega = rac{\omega}{F_{s}}$$

where  $F_s$  is sampling rate in samples per second, and  $\Omega$  is unnormalized digital frequency (radians per sample) and  $\omega$  is analog frequency (radians per second). This can also be written as

$$\Omega = \omega T_s$$

where here  $T_s$  is seconds per sample (i.e. number of seconds to obtain one sample). Per sample is used to make the units come out OK.

■ Trig identities

$$\sin A \cos B = \frac{1}{2} (\sin (A + B) + \sin (A - B))$$

$$\cos A \cos B = \frac{1}{2} (\cos (A + B) + \cos (A - B))$$

$$\sin A \sin B = \frac{1}{2} (\cos (A - B) - \cos (A + B))$$

- Group delay is given by  $-\frac{d}{d\omega}(\arg(H(\omega)))$ . For example, if  $H(\omega) = \frac{1}{2+j\omega}$  then  $\arg(H(\omega)) = -\arctan(\frac{\omega}{2})$  which leads to group delay being  $\frac{2}{4+\omega^2}$ .
- FT of  $\cos{(\omega_c t)}$  has delta at  $\pm \omega_c$  each of amplitude  $\pi$ . And FT of  $\sin{(\omega_c t)}$  has delta at  $\omega_c$  of amplitude  $\frac{\pi}{j}$  and has delta at  $-\omega_c$  of amplitude  $\frac{-\pi}{j}$  and  $\frac{\sin(\omega_c t)}{\pi t}$  has FT as rectangle of amplitude 1 and width from  $-\omega_c$  to  $+\omega_c$ .

$$X(\Omega) = \sum_{n=-\infty}^{\infty} x[n] e^{-j\Omega n}$$

$$= \sum_{n=-\infty}^{\infty} \left(\frac{1}{2}\right)^n \cos\left(\frac{\pi n}{2}\right) u[n] e^{-j\Omega n}$$

$$= \sum_{n=0}^{\infty} \left(\frac{1}{2}\right)^n \cos\left(\frac{\pi n}{2}\right) e^{-j\Omega n}$$

But  $\cos\left(\frac{\pi n}{2}\right) = \frac{1}{2}\left(e^{j\frac{\pi n}{2}} + e^{-j\frac{\pi n}{2}}\right)$  and the above becomes

$$X(\Omega) = \sum_{n=0}^{\infty} \left(\frac{1}{2}\right)^{n} \frac{1}{2} \left(e^{j\frac{\pi n}{2}} + e^{-j\frac{\pi n}{2}}\right) e^{-j\Omega n}$$

$$= \frac{1}{2} \left(\sum_{n=0}^{\infty} \left(\frac{1}{2}\right)^{n} e^{j\frac{\pi n}{2}} e^{-j\Omega n} + \sum_{n=0}^{\infty} \left(\frac{1}{2}\right)^{n} e^{-j\frac{\pi n}{2}} e^{-j\Omega n}\right)$$

$$= \frac{1}{2} \left(\sum_{n=0}^{\infty} \left(\frac{1}{2} e^{j\left(\frac{\pi}{2} - \Omega\right)}\right)^{n} + \sum_{n=0}^{\infty} \left(\frac{1}{2} e^{j\left(-\frac{\pi}{2} - \Omega\right)}\right)^{n}\right)$$

Since  $\frac{1}{2}e^{j\left(\frac{\pi}{2}-\Omega\right)}<1$  then we can use  $\sum_{n=0}^{\infty}a^n=\frac{1}{1-a}$  for both terms and the above becomes

$$X(\Omega) = \frac{1}{2} \left( \frac{1}{1 - \frac{1}{2}e^{j(\frac{\pi}{2} - \Omega)}} + \frac{1}{1 - \frac{1}{2}e^{j(-\frac{\pi}{2} - \Omega)}} \right)$$
$$= \frac{1}{2} \left( \frac{1}{1 - \frac{1}{2}e^{j(\frac{\pi}{2} - \Omega)}} + \frac{1}{1 - \frac{1}{2}e^{-j\frac{\pi}{2}}e^{-j\Omega}} \right)$$

But  $e^{j\frac{\pi}{2}} = j$  and  $e^{-j\frac{\pi}{2}} = -j$  and the above becomes

$$\begin{split} X(\Omega) &= \frac{1}{2} \left( \frac{1}{1 - \frac{1}{2} j e^{-j\Omega}} + \frac{1}{1 + \frac{1}{2} j e^{-j\Omega}} \right) \\ &= \frac{1}{2} \left( \frac{1 + \frac{1}{2} j e^{-j\Omega} + 1 - \frac{1}{2} j e^{-j\Omega}}{\left( 1 - \frac{1}{2} j e^{-j\Omega} \right) \left( 1 + \frac{1}{2} j e^{-j\Omega} \right)} \right) \\ &= \frac{1}{2} \left( \frac{2}{1 + \frac{1}{2} j e^{-j\Omega} - \frac{1}{2} j e^{-j\Omega} - \frac{1}{4} j^2 e^{-2j\Omega}} \right) \\ &= \frac{1}{1 + \frac{1}{4} e^{-2j\Omega}} \end{split}$$

#### ■ Z transforms

u [n]	Z
$a^nu[n]$	$\frac{1}{1-az^{-1}}$
$a^{n-1}u\left[ n-1\right]$	$z^{-1} \frac{1}{1-az^{-1}}$
$a^{n-2}u\left[ n-2\right]$	$z^{-2} \frac{1}{1-az^{-1}}$

If the ROC outside the out most pole, then right-handed signal. (Causal). If the ROC is inside the inner most pole, then left-handed signal (non causal).