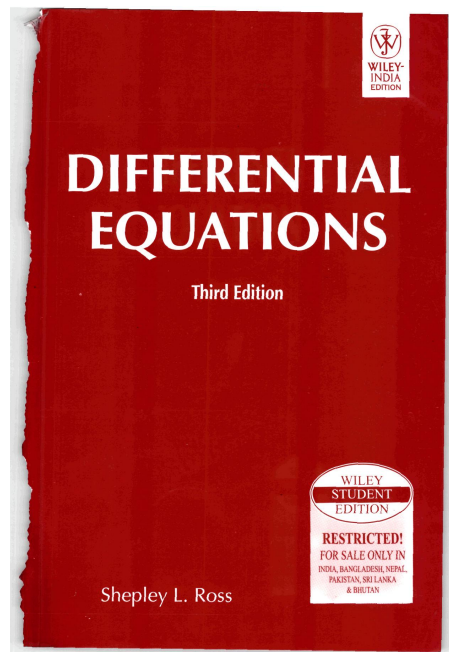


A Solution Manual For

**Differential Equations by Shepley L.
Ross. Third edition. John Willey. New
Delhi. 2004.**



Nasser M. Abbasi

May 15, 2024

Contents

1	Chapter 1, Differential equations and their solutions. Exercises page 13	3
2	Chapter 1, section 1.3. Exercises page 22	158
3	Chapter 2, section 2.1 (Exact differential equations and integrating factors). Exercises page 37	277
4	Chapter 2, section 2.2 (Separable equations). Exercises page 47	448
5	Chapter 2, section 2.3 (Linear equations). Exercises page 56	778
6	Chapter 2, Miscellaneous Review. Exercises page 60	1252
7	Chapter 2, Section 2.4. Special integrating factors and transformations. Exercises page 67	1570
8	Chapter 4, Section 4.1. Basic theory of linear differential equations. Exercises page 113	1719
9	Chapter 4, Section 4.1. Basic theory of linear differential equations. Exercises page 124	1843
10	Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135	1894
11	Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151	2249
12	Chapter 4, Section 4.4. Variation of parameters. Exercises page 162	2854
13	Chapter 4, Section 4.5. The Cauchy-Euler Equation. Exercises page 169	3239
14	Chapter 6, Series solutions of linear differential equations. Section 6.1. Exercises page 232	3836
15	Chapter 6, Series solutions of linear differential equations. Section 6.2 (Frobenius). Exercises page 251	4027

- 16 Chapter 7, Systems of linear differential equations. Section 7.1. Exercises page 277 4369
- 17 Chapter 7, Systems of linear differential equations. Section 7.3. Exercises page 299 4523
- 18 Chapter 7, Systems of linear differential equations. Section 7.4. Exercises page 309 4552
- 19 Chapter 7, Systems of linear differential equations. Section 7.5. Matrices and vectors. Exercises page 345 4587
- 20 Chapter 7, Systems of linear differential equations. Section 7.7. Exercises page 375 4681

1 Chapter 1, Differential equations and their solutions. Exercises page 13

1.1	problem 1(a)	4
1.2	problem 1(b)	19
1.3	problem 1(c)	27
1.4	problem 1(d)	37
1.5	problem 2(a)	50
1.6	problem 2(b)	65
1.7	problem 3(a)	79
1.8	problem 3(b)	92
1.9	problem 4(a)	105
1.10	problem 4(b)	113
1.11	problem 5(a)	118
1.12	problem 5(b)	123
1.13	problem 6(a)	130
1.14	problem 6(b)	143
1.15	problem 7(a)	155

1.1 problem 1(a)

1.1.1	Solving as linear ode	4
1.1.2	Solving as homogeneousTypeD2 ode	6
1.1.3	Solving as first order ode lie symmetry lookup ode	8
1.1.4	Solving as exact ode	12
1.1.5	Maple step by step solution	16

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Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 1, Differential equations and their solutions. Exercises page 13

Problem number: 1(a).

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"linear"**, **"homogeneousTypeD2"**, **"exactWithIntegrationFactor"**, **"first_order_ode_lie_symmetry_lookup"**

Maple gives the following as the ode type

```
[[_linear, `class A`]]
```

$$y' + y = 1 + x$$

1.1.1 Solving as linear ode

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = 1$$
$$q(x) = 1 + x$$

Hence the ode is

$$y' + y = 1 + x$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int 1 dx} \\ &= e^x\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu y) &= (\mu)(1+x) \\ \frac{d}{dx}(e^x y) &= (e^x)(1+x) \\ d(e^x y) &= (e^x(1+x)) dx\end{aligned}$$

Integrating gives

$$\begin{aligned}e^x y &= \int e^x(1+x) dx \\ e^x y &= x e^x + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = e^x$ results in

$$y = e^{-x} x e^x + c_1 e^{-x}$$

which simplifies to

$$y = x + c_1 e^{-x}$$

Summary

The solution(s) found are the following

$$y = x + c_1 e^{-x} \tag{1}$$

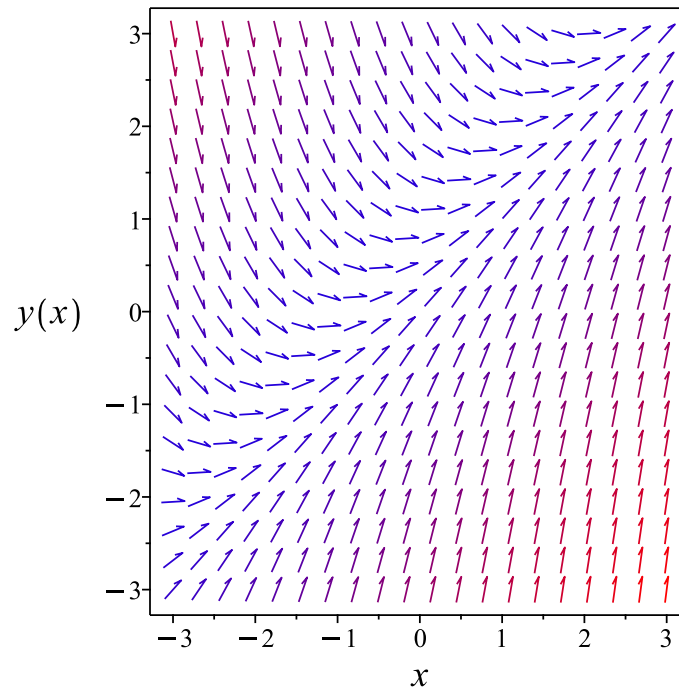


Figure 1: Slope field plot

Verification of solutions

$$y = x + c_1 e^{-x}$$

Verified OK.

1.1.2 Solving as homogeneousTypeD2 ode

Using the change of variables $y = u(x)x$ on the above ode results in new ode in $u(x)$

$$u'(x)x + u(x) + u(x)x = 1 + x$$

In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= \frac{(1+x)(-u+1)}{x} \end{aligned}$$

Where $f(x) = \frac{1+x}{x}$ and $g(u) = -u + 1$. Integrating both sides gives

$$\frac{1}{-u+1} du = \frac{1+x}{x} dx$$

$$\int \frac{1}{-u+1} du = \int \frac{1+x}{x} dx$$

$$-\ln(u-1) = x + \ln(x) + c_2$$

Raising both side to exponential gives

$$\frac{1}{u-1} = e^{x+\ln(x)+c_2}$$

Which simplifies to

$$\frac{1}{u-1} = c_3 e^{x+\ln(x)}$$

Which simplifies to

$$u(x) = \frac{(c_3 e^x x e^{c_2} + 1) e^{-x} e^{-c_2}}{c_3 x}$$

Therefore the solution y is

$$y = ux$$

$$= \frac{(c_3 e^x x e^{c_2} + 1) e^{-x} e^{-c_2}}{c_3}$$

Summary

The solution(s) found are the following

$$y = \frac{(c_3 e^x x e^{c_2} + 1) e^{-x} e^{-c_2}}{c_3} \tag{1}$$

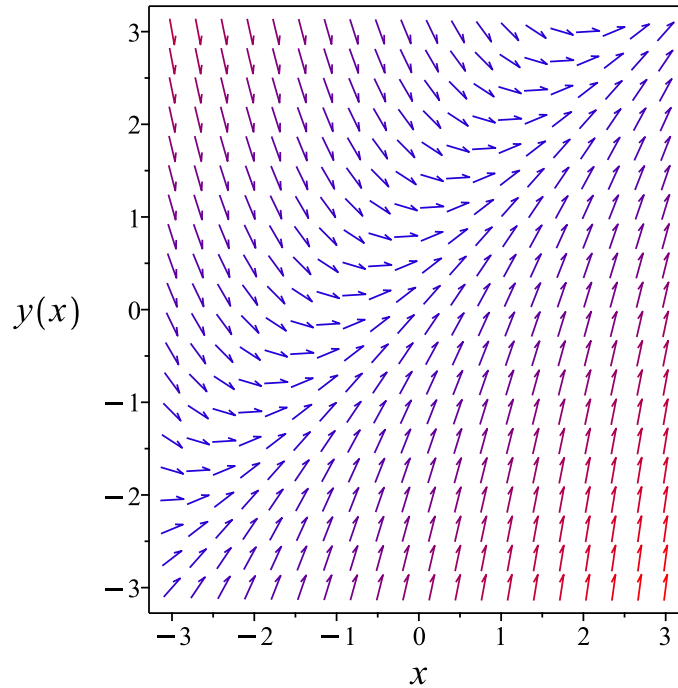


Figure 2: Slope field plot

Verification of solutions

$$y = \frac{(c_3 e^x x e^{c_2} + 1) e^{-x} e^{-c_2}}{c_3}$$

Verified OK.

1.1.3 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$\begin{aligned} y' &= -y + 1 + x \\ y' &= \omega(x, y) \end{aligned}$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 1: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= e^{-x}\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{e^{-x}} dy \end{aligned}$$

Which results in

$$S = e^x y$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -y + 1 + x$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= e^x y \\ S_y &= e^x \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = e^x(1 + x) \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = e^R(1 + R)$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by

integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = e^R R + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$y e^x = x e^x + c_1$$

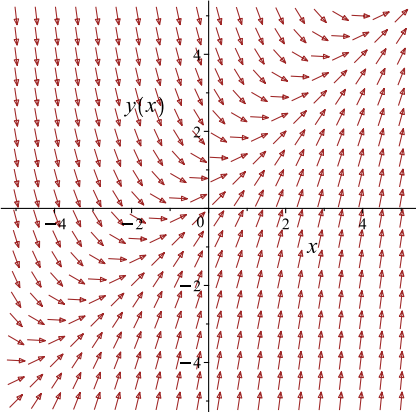
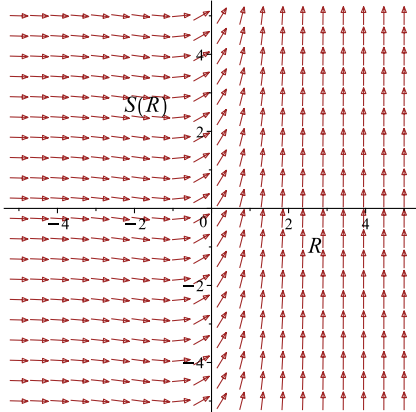
Which simplifies to

$$y e^x = x e^x + c_1$$

Which gives

$$y = (x e^x + c_1) e^{-x}$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -y + 1 + x$ 	$R = x$ $S = e^x y$	$\frac{dS}{dR} = e^R(1 + R)$ 

Summary

The solution(s) found are the following

$$y = (x e^x + c_1) e^{-x} \quad (1)$$

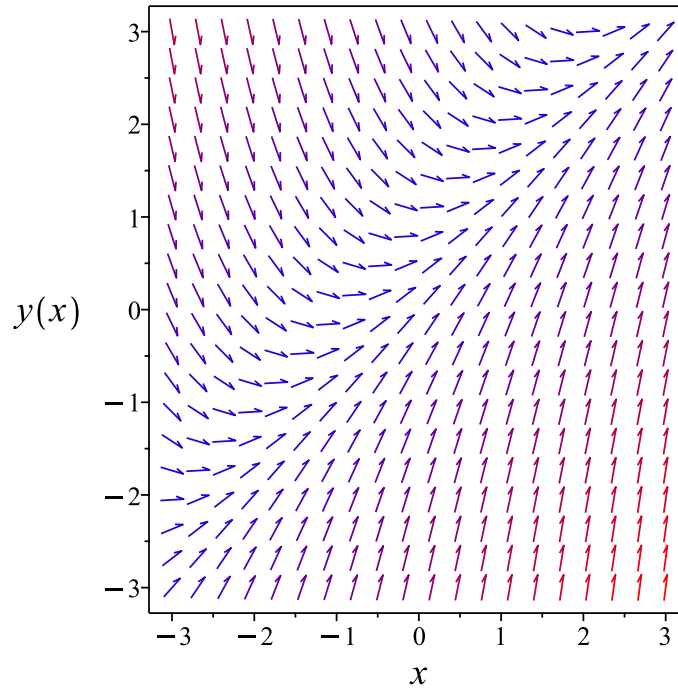


Figure 3: Slope field plot

Verification of solutions

$$y = (x e^x + c_1) e^{-x}$$

Verified OK.

1.1.4 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \tag{1A}$$

Therefore

$$\begin{aligned}dy &= (-y + 1 + x) dx \\ (y - 1 - x) dx + dy &= 0\end{aligned} \tag{2A}$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= y - 1 - x \\ N(x, y) &= 1\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(y - 1 - x) \\ &= 1\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(1) \\ &= 0\end{aligned}$$

Since $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$\begin{aligned} A &= \frac{1}{N} \left(\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} \right) \\ &= 1((1) - (0)) \\ &= 1 \end{aligned}$$

Since A does not depend on y , then it can be used to find an integrating factor. The integrating factor μ is

$$\begin{aligned} \mu &= e^{\int A dx} \\ &= e^{\int 1 dx} \end{aligned}$$

The result of integrating gives

$$\begin{aligned} \mu &= e^x \\ &= e^x \end{aligned}$$

M and N are multiplied by this integrating factor, giving new M and new N which are called \bar{M} and \bar{N} for now so not to confuse them with the original M and N .

$$\begin{aligned} \bar{M} &= \mu M \\ &= e^x(y - 1 - x) \\ &= -e^x(-y + 1 + x) \end{aligned}$$

And

$$\begin{aligned} \bar{N} &= \mu N \\ &= e^x(1) \\ &= e^x \end{aligned}$$

Now a modified ODE is obtained from the original ODE, which is exact and can be solved. The modified ODE is

$$\begin{aligned} \bar{M} + \bar{N} \frac{dy}{dx} &= 0 \\ (-e^x(-y + 1 + x)) + (e^x) \frac{dy}{dx} &= 0 \end{aligned}$$

The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = \bar{M} \tag{1}$$

$$\frac{\partial \phi}{\partial y} = \bar{N} \tag{2}$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int \overline{M} dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int -e^x(-y + 1 + x) dx \\ \phi &= -(-y + x)e^x + f(y)\end{aligned}\tag{3}$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = e^x + f'(y)\tag{4}$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = e^x$. Therefore equation (4) becomes

$$e^x = e^x + f'(y)\tag{5}$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 0$$

Therefore

$$f(y) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(y)$ into equation (3) gives ϕ

$$\phi = -(-y + x)e^x + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -(-y + x)e^x$$

The solution becomes

$$y = (xe^x + c_1)e^{-x}$$

Summary

The solution(s) found are the following

$$y = (xe^x + c_1)e^{-x}\tag{1}$$

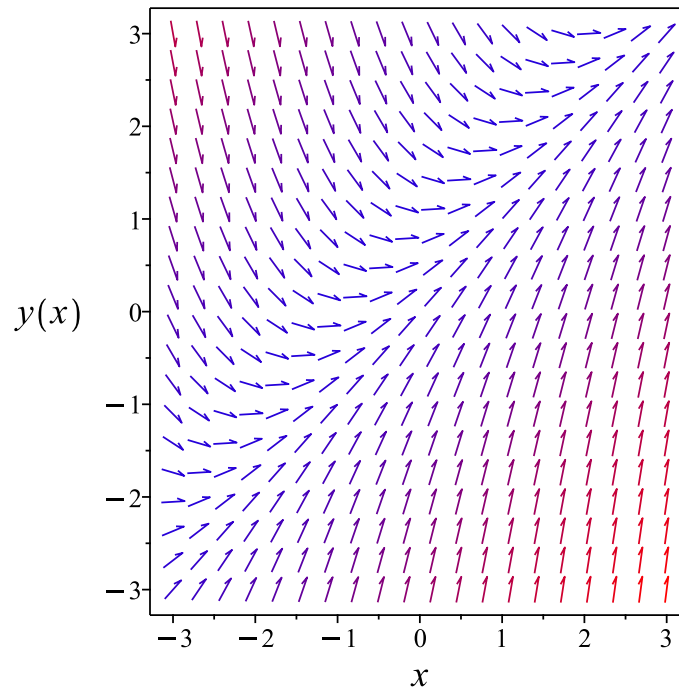


Figure 4: Slope field plot

Verification of solutions

$$y = (x e^x + c_1) e^{-x}$$

Verified OK.

1.1.5 Maple step by step solution

Let's solve

$$y' + y = 1 + x$$

- Highest derivative means the order of the ODE is 1

$$y'$$

- Isolate the derivative

$$y' = -y + 1 + x$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE

$$y' + y = 1 + x$$

- The ODE is linear; multiply by an integrating factor $\mu(x)$

$$\mu(x) (y' + y) = \mu(x) (1 + x)$$

- Assume the lhs of the ODE is the total derivative $\frac{d}{dx}(\mu(x) y)$

$$\mu(x) (y' + y) = \mu'(x) y + \mu(x) y'$$
- Isolate $\mu'(x)$

$$\mu'(x) = \mu(x)$$
- Solve to find the integrating factor

$$\mu(x) = e^x$$
- Integrate both sides with respect to x

$$\int \left(\frac{d}{dx}(\mu(x) y) \right) dx = \int \mu(x) (1 + x) dx + c_1$$
- Evaluate the integral on the lhs

$$\mu(x) y = \int \mu(x) (1 + x) dx + c_1$$
- Solve for y

$$y = \frac{\int \mu(x)(1+x)dx + c_1}{\mu(x)}$$
- Substitute $\mu(x) = e^x$

$$y = \frac{\int e^x(1+x)dx + c_1}{e^x}$$
- Evaluate the integrals on the rhs

$$y = \frac{x e^x + c_1}{e^x}$$
- Simplify

$$y = x + c_1 e^{-x}$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
<- 1st order linear successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 12

```
dsolve(diff(y(x),x)+y(x)=1+x,y(x), singsol=all)
```

$$y(x) = x + c_1 e^{-x}$$

✓ Solution by Mathematica

Time used: 0.04 (sec). Leaf size: 15

```
DSolve[y'[x]+y[x]==1+x,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow x + c_1 e^{-x}$$

1.2 problem 1(b)

1.2.1	Solving as second order linear constant coeff ode	19
1.2.2	Solving using Kovacic algorithm	21
1.2.3	Maple step by step solution	25

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Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 1, Differential equations and their solutions. Exercises page 13

Problem number: 1(b).

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _missing_x]]
```

$$y'' - 7y' + 12y = 0$$

1.2.1 Solving as second order linear constant coeff ode

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = -7, C = 12$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} - 7\lambda e^{\lambda x} + 12e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 - 7\lambda + 12 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = -7, C = 12$ into the above gives

$$\begin{aligned}\lambda_{1,2} &= \frac{7}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{-7^2 - (4)(1)(12)} \\ &= \frac{7}{2} \pm \frac{1}{2}\end{aligned}$$

Hence

$$\lambda_1 = \frac{7}{2} + \frac{1}{2}$$

$$\lambda_2 = \frac{7}{2} - \frac{1}{2}$$

Which simplifies to

$$\lambda_1 = 4$$

$$\lambda_2 = 3$$

Since roots are real and distinct, then the solution is

$$y = c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x}$$

$$y = c_1 e^{(4)x} + c_2 e^{(3)x}$$

Or

$$y = c_1 e^{4x} + e^{3x} c_2$$

Summary

The solution(s) found are the following

$$y = c_1 e^{4x} + e^{3x} c_2 \tag{1}$$

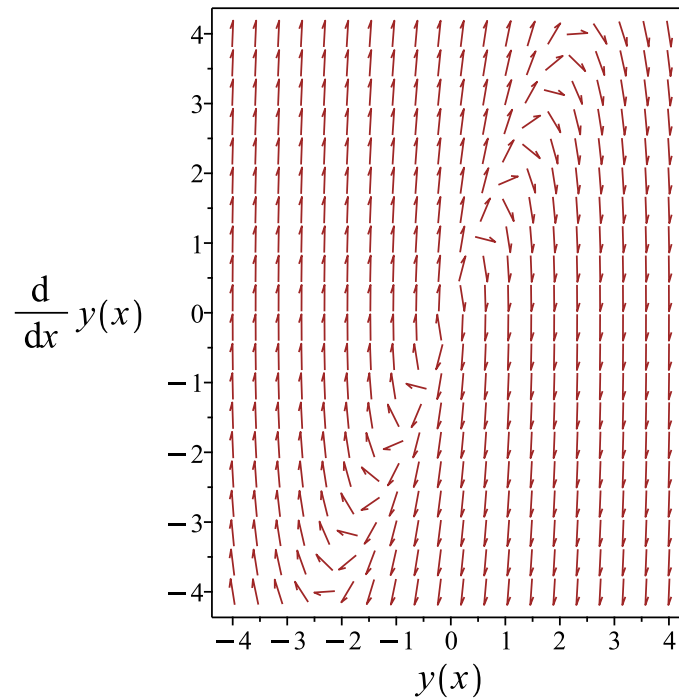


Figure 5: Slope field plot

Verification of solutions

$$y = c_1 e^{4x} + e^{3x} c_2$$

Verified OK.

1.2.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' - 7y' + 12y = 0 \tag{1}$$

$$Ay'' + By' + Cy = 0 \tag{2}$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= -7 \\ C &= 12 \end{aligned} \tag{3}$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{1}{4} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 1 \\ t &= 4 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = \frac{z(x)}{4} \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 4: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = \frac{1}{4}$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = e^{-\frac{x}{2}}$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-7}{1} dx} \\ &= z_1 e^{\frac{7x}{2}} \\ &= z_1 \left(e^{\frac{7x}{2}} \right) \end{aligned}$$

Which simplifies to

$$y_1 = e^{3x}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{-7}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{7x}}{(y_1)^2} dx \\ &= y_1 (e^x) \end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (e^{3x}) + c_2 (e^{3x}(e^x))\end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 e^{3x} + c_2 e^{4x} \tag{1}$$

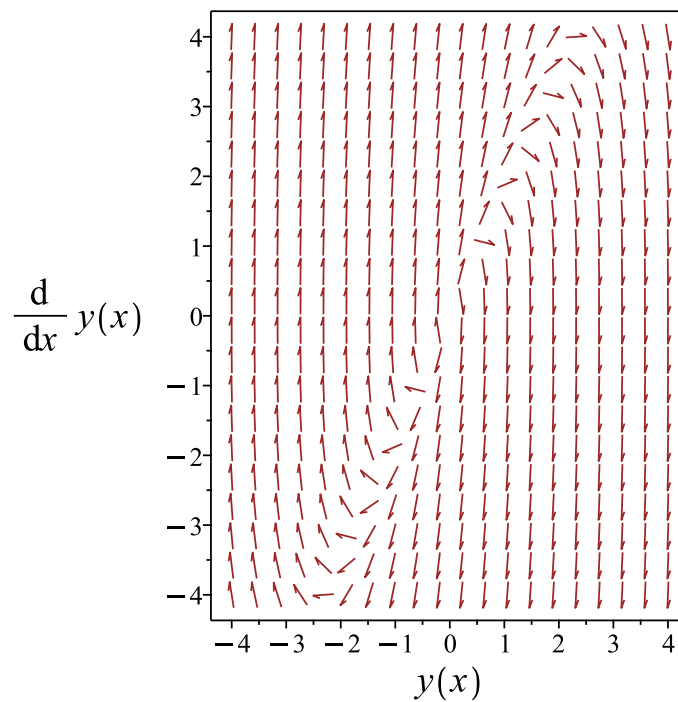


Figure 6: Slope field plot

Verification of solutions

$$y = c_1 e^{3x} + c_2 e^{4x}$$

Verified OK.

1.2.3 Maple step by step solution

Let's solve

$$y'' - 7y' + 12y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of ODE

$$r^2 - 7r + 12 = 0$$

- Factor the characteristic polynomial

$$(r - 3)(r - 4) = 0$$

- Roots of the characteristic polynomial

$$r = (3, 4)$$

- 1st solution of the ODE

$$y_1(x) = e^{3x}$$

- 2nd solution of the ODE

$$y_2(x) = e^{4x}$$

- General solution of the ODE

$$y = c_1y_1(x) + c_2y_2(x)$$

- Substitute in solutions

$$y = c_1e^{3x} + c_2e^{4x}$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
<- constant coefficients successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 17

```
dsolve(diff(y(x),x$2)-7*diff(y(x),x)+12*y(x)=0,y(x), singsol=all)
```

$$y(x) = c_1 e^{4x} + c_2 e^{3x}$$

✓ Solution by Mathematica

Time used: 0.022 (sec). Leaf size: 20

```
DSolve[y''[x]-7*y'[x]+12*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^{3x}(c_2 e^x + c_1)$$

1.3 problem 1(c)

1.3.1	Solving as second order linear constant coeff ode	27
1.3.2	Solving using Kovacic algorithm	30
1.3.3	Maple step by step solution	35

Internal problem ID [11572]

Internal file name [OUTPUT/10554_Thursday_May_18_2023_05_39_32_AM_68847962/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 1, Differential equations and their solutions. Exercises page 13

Problem number: 1(c).

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"kovacic", "second_order_linear_constant_coeff"**

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$y'' - 3y' + 2y = 4x^2$$

1.3.1 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = -3, C = 2, f(x) = 4x^2$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' - 3y' + 2y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = -3, C = 2$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} - 3\lambda e^{\lambda x} + 2e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 - 3\lambda + 2 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = -3, C = 2$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{3}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{-3^2 - (4)(1)(2)} \\ &= \frac{3}{2} \pm \frac{1}{2} \end{aligned}$$

Hence

$$\begin{aligned} \lambda_1 &= \frac{3}{2} + \frac{1}{2} \\ \lambda_2 &= \frac{3}{2} - \frac{1}{2} \end{aligned}$$

Which simplifies to

$$\begin{aligned} \lambda_1 &= 2 \\ \lambda_2 &= 1 \end{aligned}$$

Since roots are real and distinct, then the solution is

$$\begin{aligned} y &= c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x} \\ y &= c_1 e^{(2)x} + c_2 e^{(1)x} \end{aligned}$$

Or

$$y = c_1 e^{2x} + c_2 e^x$$

Therefore the homogeneous solution y_h is

$$y_h = c_1 e^{2x} + c_2 e^x$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$x^2$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{1, x, x^2\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^x, e^{2x}\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_3x^2 + A_2x + A_1$$

The unknowns $\{A_1, A_2, A_3\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$2A_3x^2 + 2A_2x - 6xA_3 + 2A_1 - 3A_2 + 2A_3 = 4x^2$$

Solving for the unknowns by comparing coefficients results in

$$[A_1 = 7, A_2 = 6, A_3 = 2]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = 2x^2 + 6x + 7$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1e^{2x} + c_2e^x) + (2x^2 + 6x + 7) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1e^{2x} + c_2e^x + 2x^2 + 6x + 7 \tag{1}$$

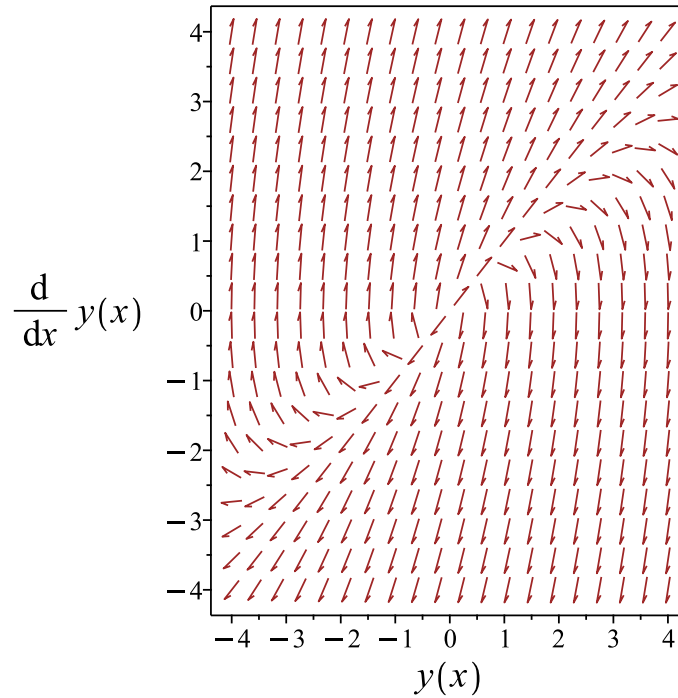


Figure 7: Slope field plot

Verification of solutions

$$y = c_1 e^{2x} + c_2 e^x + 2x^2 + 6x + 7$$

Verified OK.

1.3.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' - 3y' + 2y = 0 \tag{1}$$

$$Ay'' + By' + Cy = 0 \tag{2}$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= -3 \\ C &= 2 \end{aligned} \tag{3}$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{1}{4} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 1 \\ t &= 4 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = \frac{z(x)}{4} \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 6: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = \frac{1}{4}$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = e^{-\frac{x}{2}}$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-3}{1} dx} \\ &= z_1 e^{\frac{3x}{2}} \\ &= z_1 \left(e^{\frac{3x}{2}} \right) \end{aligned}$$

Which simplifies to

$$y_1 = e^x$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{-3}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{3x}}{(y_1)^2} dx \\ &= y_1 (e^x) \end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1(e^x) + c_2(e^x(e^x))\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' - 3y' + 2y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = e^x c_1 + c_2 e^{2x}$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$x^2$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{1, x, x^2\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^x, e^{2x}\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_3 x^2 + A_2 x + A_1$$

The unknowns $\{A_1, A_2, A_3\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$2A_3 x^2 + 2A_2 x - 6xA_3 + 2A_1 - 3A_2 + 2A_3 = 4x^2$$

Solving for the unknowns by comparing coefficients results in

$$[A_1 = 7, A_2 = 6, A_3 = 2]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = 2x^2 + 6x + 7$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (e^x c_1 + c_2 e^{2x}) + (2x^2 + 6x + 7) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = e^x c_1 + c_2 e^{2x} + 2x^2 + 6x + 7 \quad (1)$$

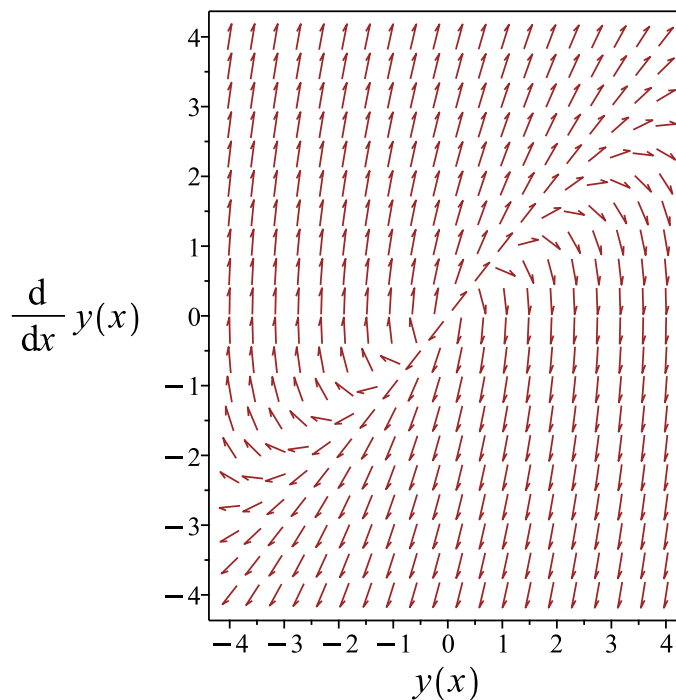


Figure 8: Slope field plot

Verification of solutions

$$y = e^x c_1 + c_2 e^{2x} + 2x^2 + 6x + 7$$

Verified OK.

1.3.3 Maple step by step solution

Let's solve

$$y'' - 3y' + 2y = 4x^2$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of homogeneous ODE

$$r^2 - 3r + 2 = 0$$

- Factor the characteristic polynomial

$$(r - 1)(r - 2) = 0$$

- Roots of the characteristic polynomial

$$r = (1, 2)$$

- 1st solution of the homogeneous ODE

$$y_1(x) = e^x$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = e^{2x}$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = e^x c_1 + c_2 e^{2x} + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = 4x^2 \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} e^x & e^{2x} \\ e^x & 2e^{2x} \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = e^{3x}$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = -4e^x \left(\int x^2 e^{-x} dx \right) + 4e^{2x} \left(\int x^2 e^{-2x} dx \right)$$

- Compute integrals

$$y_p(x) = 2x^2 + 6x + 7$$

- Substitute particular solution into general solution to ODE

$$y = e^x c_1 + c_2 e^{2x} + 2x^2 + 6x + 7$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
trying a double symmetry of the form [xi=0, eta=F(x)]
<- double symmetry of the form [xi=0, eta=F(x)] successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 24

```
dsolve(diff(y(x),x$2)-3*diff(y(x),x)+2*y(x)=4*x^2,y(x), singsol=all)
```

$$y(x) = e^{2x}c_1 + c_2e^x + 2x^2 + 6x + 7$$

✓ Solution by Mathematica

Time used: 0.03 (sec). Leaf size: 29

```
DSolve[y''[x]-3*y'[x]+2*y[x]==4*x^2,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow 2x^2 + 6x + c_1e^x + c_2e^{2x} + 7$$

1.4 problem 1(d)

1.4.1	Solving as linear second order ode solved by an integrating factor ode	37
1.4.2	Solving as second order change of variable on y method 1 ode	39
1.4.3	Solving as second order integrable as is ode	40
1.4.4	Solving as type second_order_integrable_as_is (not using ABC version)	42
1.4.5	Solving using Kovacic algorithm	43
1.4.6	Solving as exact linear second order ode ode	46

Internal problem ID [11573]

Internal file name [OUTPUT/10555_Thursday_May_18_2023_05_39_32_AM_64086885/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 1, Differential equations and their solutions. Exercises page 13

Problem number: 1(d).

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "exact linear second order ode", "second_order_integrable_as_is", "second_order_change_of_variable_on_y_method_1", "linear_second_order_ode_solved_by_an_integrating_factor"

Maple gives the following as the ode type

```
[[_2nd_order, _exact, _linear, _homogeneous]]
```

$$(x^2 + 1) y'' + 4y'x + 2y = 0$$

1.4.1 Solving as linear second order ode solved by an integrating factor ode

The ode satisfies this form

$$y'' + p(x) y' + \frac{(p(x)^2 + p'(x)) y}{2} = f(x)$$

Where $p(x) = \frac{4x}{x^2+1}$. Therefore, there is an integrating factor given by

$$\begin{aligned}M(x) &= e^{\frac{1}{2} \int p \, dx} \\&= e^{\int \frac{4x}{x^2+1} \, dx} \\&= x^2 + 1\end{aligned}$$

Multiplying both sides of the ODE by the integrating factor $M(x)$ makes the left side of the ODE a complete differential

$$\begin{aligned}(M(x)y)'' &= 0 \\((x^2 + 1)y)'' &= 0\end{aligned}$$

Integrating once gives

$$((x^2 + 1)y)' = c_1$$

Integrating again gives

$$((x^2 + 1)y) = c_1x + c_2$$

Hence the solution is

$$y = \frac{c_1x + c_2}{x^2 + 1}$$

Or

$$y = \frac{c_1x}{x^2 + 1} + \frac{c_2}{x^2 + 1}$$

Summary

The solution(s) found are the following

$$y = \frac{c_1x}{x^2 + 1} + \frac{c_2}{x^2 + 1} \tag{1}$$

Verification of solutions

$$y = \frac{c_1x}{x^2 + 1} + \frac{c_2}{x^2 + 1}$$

Verified OK.

1.4.2 Solving as second order change of variable on y method 1 ode

In normal form the given ode is written as

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = \frac{4x}{x^2 + 1}$$
$$q(x) = \frac{2}{x^2 + 1}$$

Calculating the Liouville ode invariant Q given by

$$\begin{aligned} Q &= q - \frac{p'}{2} - \frac{p^2}{4} \\ &= \frac{2}{x^2 + 1} - \frac{\left(\frac{4x}{x^2+1}\right)'}{2} - \frac{\left(\frac{4x}{x^2+1}\right)^2}{4} \\ &= \frac{2}{x^2 + 1} - \frac{\left(\frac{4}{x^2+1} - \frac{8x^2}{(x^2+1)^2}\right)}{2} - \frac{\left(\frac{16x^2}{(x^2+1)^2}\right)}{4} \\ &= \frac{2}{x^2 + 1} - \left(\frac{2}{x^2 + 1} - \frac{4x^2}{(x^2 + 1)^2}\right) - \frac{4x^2}{(x^2 + 1)^2} \\ &= 0 \end{aligned}$$

Since the Liouville ode invariant does not depend on the independent variable x then the transformation

$$y = v(x)z(x) \quad (3)$$

is used to change the original ode to a constant coefficients ode in v . In (3) the term $z(x)$ is given by

$$\begin{aligned} z(x) &= e^{-\left(\int \frac{p(x)}{2} dx\right)} \\ &= e^{-\int \frac{4x}{x^2+1}} \\ &= \frac{1}{x^2 + 1} \end{aligned} \quad (5)$$

Hence (3) becomes

$$y = \frac{v(x)}{x^2 + 1} \quad (4)$$

Applying this change of variable to the original ode results in

$$v''(x) = 0$$

Which is now solved for $v(x)$ Integrating twice gives the solution

$$v(x) = c_1x + c_2$$

Now that $v(x)$ is known, then

$$\begin{aligned} y &= v(x) z(x) \\ &= (c_1x + c_2) (z(x)) \end{aligned} \tag{7}$$

But from (5)

$$z(x) = \frac{1}{x^2 + 1}$$

Hence (7) becomes

$$y = \frac{c_1x + c_2}{x^2 + 1}$$

Summary

The solution(s) found are the following

$$y = \frac{c_1x + c_2}{x^2 + 1} \tag{1}$$

Verification of solutions

$$y = \frac{c_1x + c_2}{x^2 + 1}$$

Verified OK.

1.4.3 Solving as second order integrable as is ode

Integrating both sides of the ODE w.r.t x gives

$$\begin{aligned} \int ((x^2 + 1) y'' + 4y'x + 2y) dx &= 0 \\ 2yx + (x^2 + 1) y' &= c_1 \end{aligned}$$

Which is now solved for y .

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = \frac{2x}{x^2 + 1}$$
$$q(x) = \frac{c_1}{x^2 + 1}$$

Hence the ode is

$$y' + \frac{2xy}{x^2 + 1} = \frac{c_1}{x^2 + 1}$$

The integrating factor μ is

$$\mu = e^{\int \frac{2x}{x^2+1} dx}$$
$$= x^2 + 1$$

The ode becomes

$$\frac{d}{dx}(\mu y) = (\mu) \left(\frac{c_1}{x^2 + 1} \right)$$
$$\frac{d}{dx}((x^2 + 1) y) = (x^2 + 1) \left(\frac{c_1}{x^2 + 1} \right)$$
$$d((x^2 + 1) y) = c_1 dx$$

Integrating gives

$$(x^2 + 1) y = \int c_1 dx$$
$$(x^2 + 1) y = c_1 x + c_2$$

Dividing both sides by the integrating factor $\mu = x^2 + 1$ results in

$$y = \frac{c_1 x}{x^2 + 1} + \frac{c_2}{x^2 + 1}$$

which simplifies to

$$y = \frac{c_1 x + c_2}{x^2 + 1}$$

Summary

The solution(s) found are the following

$$y = \frac{c_1 x + c_2}{x^2 + 1} \tag{1}$$

Verification of solutions

$$y = \frac{c_1 x + c_2}{x^2 + 1}$$

Verified OK.

1.4.4 Solving as type second_order_integrable_as_is (not using ABC version)

Writing the ode as

$$(x^2 + 1) y'' + 4y'x + 2y = 0$$

Integrating both sides of the ODE w.r.t x gives

$$\int ((x^2 + 1) y'' + 4y'x + 2y) dx = 0$$
$$2yx + (x^2 + 1) y' = c_1$$

Which is now solved for y .

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = \frac{2x}{x^2 + 1}$$
$$q(x) = \frac{c_1}{x^2 + 1}$$

Hence the ode is

$$y' + \frac{2xy}{x^2 + 1} = \frac{c_1}{x^2 + 1}$$

The integrating factor μ is

$$\mu = e^{\int \frac{2x}{x^2+1} dx}$$
$$= x^2 + 1$$

The ode becomes

$$\frac{d}{dx}(\mu y) = (\mu) \left(\frac{c_1}{x^2 + 1} \right)$$
$$\frac{d}{dx}((x^2 + 1) y) = (x^2 + 1) \left(\frac{c_1}{x^2 + 1} \right)$$
$$d((x^2 + 1) y) = c_1 dx$$

Integrating gives

$$(x^2 + 1) y = \int c_1 dx$$
$$(x^2 + 1) y = c_1 x + c_2$$

Dividing both sides by the integrating factor $\mu = x^2 + 1$ results in

$$y = \frac{c_1 x}{x^2 + 1} + \frac{c_2}{x^2 + 1}$$

which simplifies to

$$y = \frac{c_1 x + c_2}{x^2 + 1}$$

Summary

The solution(s) found are the following

$$y = \frac{c_1 x + c_2}{x^2 + 1} \quad (1)$$

Verification of solutions

$$y = \frac{c_1 x + c_2}{x^2 + 1}$$

Verified OK.

1.4.5 Solving using Kovacic algorithm

Writing the ode as

$$(x^2 + 1) y'' + 4y'x + 2y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= x^2 + 1 \\ B &= 4x \\ C &= 2 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{0}{1} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 0 \\ t &= 1 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = 0 \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 8: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - -\infty \\ &= \infty \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is *infinity* then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = 0$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = 1$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{4x}{x^2+1} dx} \\ &= z_1 e^{-\ln(x^2+1)} \\ &= z_1 \left(\frac{1}{x^2 + 1} \right) \end{aligned}$$

Which simplifies to

$$y_1 = \frac{1}{x^2 + 1}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{4x}{x^2+1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{-2\ln(x^2+1)}}{(y_1)^2} dx \\ &= y_1(x) \end{aligned}$$

Therefore the solution is

$$\begin{aligned}
y &= c_1 y_1 + c_2 y_2 \\
&= c_1 \left(\frac{1}{x^2 + 1} \right) + c_2 \left(\frac{1}{x^2 + 1} (x) \right)
\end{aligned}$$

Summary

The solution(s) found are the following

$$y = \frac{c_1}{x^2 + 1} + \frac{c_2 x}{x^2 + 1} \quad (1)$$

Verification of solutions

$$y = \frac{c_1}{x^2 + 1} + \frac{c_2 x}{x^2 + 1}$$

Verified OK.

1.4.6 Solving as exact linear second order ode

An ode of the form

$$p(x) y'' + q(x) y' + r(x) y = s(x)$$

is exact if

$$p''(x) - q'(x) + r(x) = 0 \quad (1)$$

For the given ode we have

$$p(x) = x^2 + 1$$

$$q(x) = 4x$$

$$r(x) = 2$$

$$s(x) = 0$$

Hence

$$p''(x) = 2$$

$$q'(x) = 4$$

Therefore (1) becomes

$$2 - (4) + (2) = 0$$

Hence the ode is exact. Since we now know the ode is exact, it can be written as

$$(p(x) y' + (q(x) - p'(x)) y)' = s(x)$$

Integrating gives

$$p(x) y' + (q(x) - p'(x)) y = \int s(x) dx$$

Substituting the above values for p, q, r, s gives

$$2yx + (x^2 + 1) y' = c_1$$

We now have a first order ode to solve which is

$$2yx + (x^2 + 1) y' = c_1$$

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = \frac{2x}{x^2 + 1}$$
$$q(x) = \frac{c_1}{x^2 + 1}$$

Hence the ode is

$$y' + \frac{2xy}{x^2 + 1} = \frac{c_1}{x^2 + 1}$$

The integrating factor μ is

$$\mu = e^{\int \frac{2x}{x^2+1} dx}$$
$$= x^2 + 1$$

The ode becomes

$$\frac{d}{dx}(\mu y) = (\mu) \left(\frac{c_1}{x^2 + 1} \right)$$
$$\frac{d}{dx}((x^2 + 1) y) = (x^2 + 1) \left(\frac{c_1}{x^2 + 1} \right)$$
$$d((x^2 + 1) y) = c_1 dx$$

Integrating gives

$$(x^2 + 1) y = \int c_1 dx$$
$$(x^2 + 1) y = c_1 x + c_2$$

Dividing both sides by the integrating factor $\mu = x^2 + 1$ results in

$$y = \frac{c_1 x}{x^2 + 1} + \frac{c_2}{x^2 + 1}$$

which simplifies to

$$y = \frac{c_1 x + c_2}{x^2 + 1}$$

Summary

The solution(s) found are the following

$$y = \frac{c_1 x + c_2}{x^2 + 1} \quad (1)$$

Verification of solutions

$$y = \frac{c_1 x + c_2}{x^2 + 1}$$

Verified OK.

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
checking if the LODE is of Euler type  
trying a symmetry of the form [xi=0, eta=F(x)]  
<- linear_1 successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 17

```
dsolve((1+x^2)*diff(y(x),x$2)+4*x*diff(y(x),x)+2*y(x)=0,y(x), singsol=all)
```

$$y(x) = \frac{c_1 x + c_2}{x^2 + 1}$$

✓ Solution by Mathematica

Time used: 0.039 (sec). Leaf size: 20

```
DSolve[(1+x^2)*y'[x]+4*x*y'[x]+2*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{c_2 x + c_1}{x^2 + 1}$$

1.5 problem 2(a)

1.5.1	Solving as homogeneousTypeD2 ode	50
1.5.2	Solving as first order ode lie symmetry lookup ode	52
1.5.3	Solving as bernoulli ode	56
1.5.4	Solving as exact ode	59
1.5.5	Maple step by step solution	63

Internal problem ID [11574]

Internal file name [OUTPUT/10556_Thursday_May_18_2023_05_39_34_AM_10656506/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 1, Differential equations and their solutions. Exercises page 13

Problem number: 2(a).

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact", "bernoulli", "homogeneousTypeD2", "first_order_ode_lie_symmetry_lookup"

Maple gives the following as the ode type

```
[[_homogeneous, `class A`], _exact, _rational, _Bernoulli]
```

$$2xyy' + y^2 = -x^2$$

1.5.1 Solving as homogeneousTypeD2 ode

Using the change of variables $y = u(x)x$ on the above ode results in new ode in $u(x)$

$$2x^2u(x)(u'(x)x + u(x)) + u(x)^2x^2 = -x^2$$

In canonical form the ODE is

$$\begin{aligned}u' &= F(x, u) \\ &= f(x)g(u) \\ &= -\frac{3u^2 + 1}{2ux}\end{aligned}$$

Where $f(x) = -\frac{1}{2x}$ and $g(u) = \frac{3u^2+1}{u}$. Integrating both sides gives

$$\begin{aligned}\frac{1}{\frac{3u^2+1}{u}} du &= -\frac{1}{2x} dx \\ \int \frac{1}{\frac{3u^2+1}{u}} du &= \int -\frac{1}{2x} dx \\ \frac{\ln(3u^2+1)}{6} &= -\frac{\ln(x)}{2} + c_2\end{aligned}$$

Raising both side to exponential gives

$$(3u^2+1)^{\frac{1}{6}} = e^{-\frac{\ln(x)}{2}+c_2}$$

Which simplifies to

$$(3u^2+1)^{\frac{1}{6}} = \frac{c_3}{\sqrt{x}}$$

Which simplifies to

$$(3u(x)^2+1)^{\frac{1}{6}} = \frac{c_3 e^{c_2}}{\sqrt{x}}$$

The solution is

$$(3u(x)^2+1)^{\frac{1}{6}} = \frac{c_3 e^{c_2}}{\sqrt{x}}$$

Replacing $u(x)$ in the above solution by $\frac{y}{x}$ results in the solution for y in implicit form

$$\begin{aligned}\left(\frac{3y^2}{x^2}+1\right)^{\frac{1}{6}} &= \frac{c_3 e^{c_2}}{\sqrt{x}} \\ \left(\frac{3y^2+x^2}{x^2}\right)^{\frac{1}{6}} &= \frac{c_3 e^{c_2}}{\sqrt{x}}\end{aligned}$$

Summary

The solution(s) found are the following

$$\left(\frac{3y^2+x^2}{x^2}\right)^{\frac{1}{6}} = \frac{c_3 e^{c_2}}{\sqrt{x}} \quad (1)$$

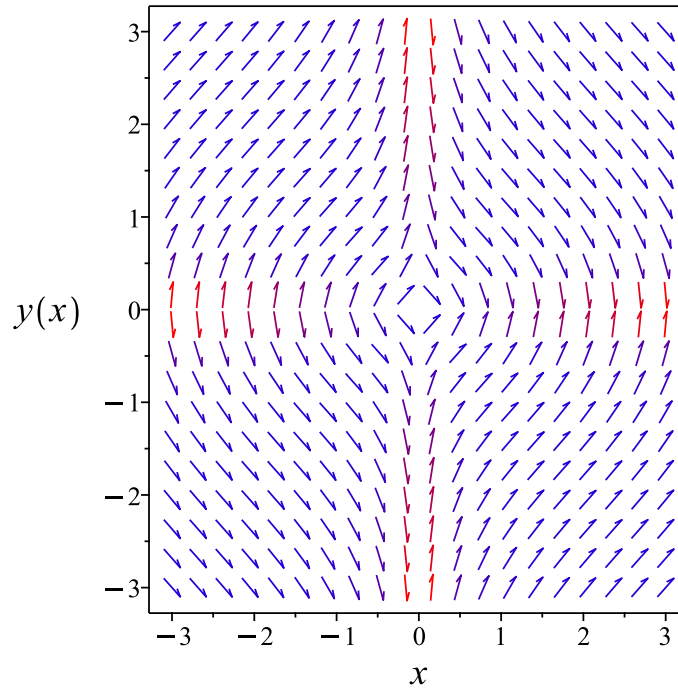


Figure 9: Slope field plot

Verification of solutions

$$\left(\frac{3y^2 + x^2}{x^2}\right)^{\frac{1}{6}} = \frac{c_3 e^{c_2}}{\sqrt{x}}$$

Verified OK.

1.5.2 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = -\frac{x^2 + y^2}{2yx}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **Bernoulli**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 9: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= \frac{1}{xy}\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{1}{xy}} dy \end{aligned}$$

Which results in

$$S = \frac{x y^2}{2}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{x^2 + y^2}{2yx}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= \frac{y^2}{2} \\ S_y &= xy \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = -\frac{x^2}{2} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = -\frac{R^2}{2}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = -\frac{R^3}{6} + c_1 \quad (4)$$

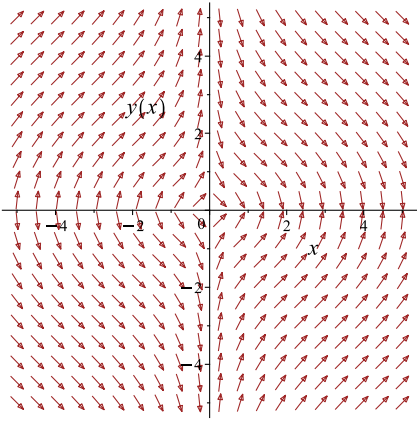
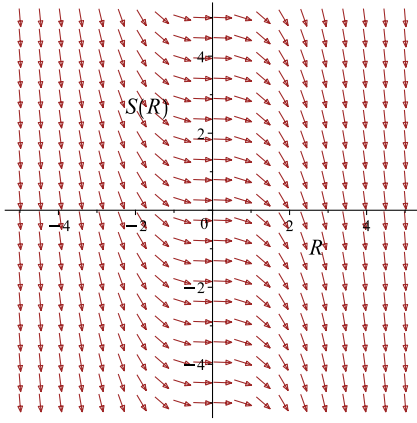
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$\frac{y^2 x}{2} = -\frac{x^3}{6} + c_1$$

Which simplifies to

$$\frac{y^2 x}{2} = -\frac{x^3}{6} + c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{x^2+y^2}{2yx}$ 	$R = x$ $S = \frac{xy^2}{2}$	$\frac{dS}{dR} = -\frac{R^2}{2}$ 

Summary

The solution(s) found are the following

$$\frac{y^2 x}{2} = -\frac{x^3}{6} + c_1 \quad (1)$$

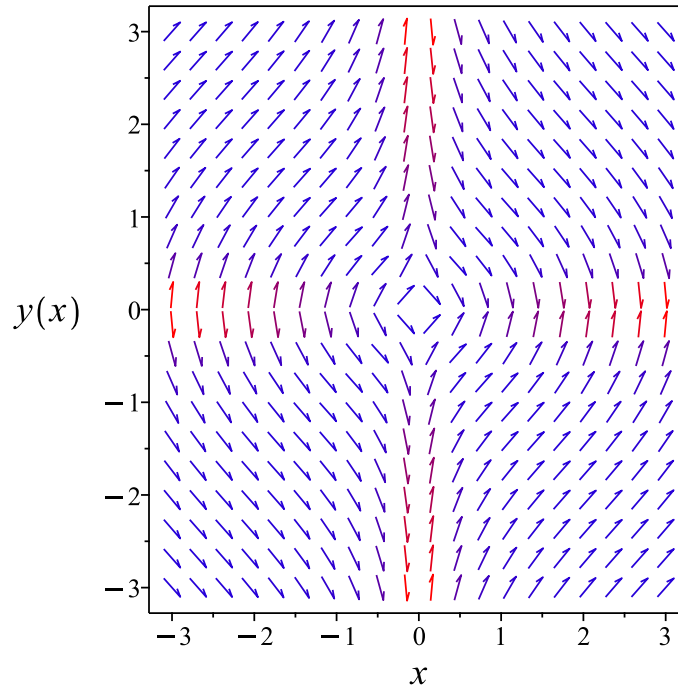


Figure 10: Slope field plot

Verification of solutions

$$\frac{y^2 x}{2} = -\frac{x^3}{6} + c_1$$

Verified OK.

1.5.3 Solving as bernoulli ode

In canonical form, the ODE is

$$\begin{aligned} y' &= F(x, y) \\ &= -\frac{x^2 + y^2}{2yx} \end{aligned}$$

This is a Bernoulli ODE.

$$y' = -\frac{1}{2x}y - \frac{x}{2} \frac{1}{y} \tag{1}$$

The standard Bernoulli ODE has the form

$$y' = f_0(x)y + f_1(x)y^n \tag{2}$$

The first step is to divide the above equation by y^n which gives

$$\frac{y'}{y^n} = f_0(x)y^{1-n} + f_1(x) \tag{3}$$

The next step is use the substitution $w = y^{1-n}$ in equation (3) which generates a new ODE in $w(x)$ which will be linear and can be easily solved using an integrating factor. Backsubstitution then gives the solution $y(x)$ which is what we want.

This method is now applied to the ODE at hand. Comparing the ODE (1) With (2) Shows that

$$\begin{aligned} f_0(x) &= -\frac{1}{2x} \\ f_1(x) &= -\frac{x}{2} \\ n &= -1 \end{aligned}$$

Dividing both sides of ODE (1) by $y^n = \frac{1}{y}$ gives

$$y'y = -\frac{y^2}{2x} - \frac{x}{2} \quad (4)$$

Let

$$\begin{aligned} w &= y^{1-n} \\ &= y^2 \end{aligned} \quad (5)$$

Taking derivative of equation (5) w.r.t x gives

$$w' = 2yy' \quad (6)$$

Substituting equations (5) and (6) into equation (4) gives

$$\begin{aligned} \frac{w'(x)}{2} &= -\frac{w(x)}{2x} - \frac{x}{2} \\ w' &= -\frac{w}{x} - x \end{aligned} \quad (7)$$

The above now is a linear ODE in $w(x)$ which is now solved.

Entering Linear first order ODE solver. In canonical form a linear first order is

$$w'(x) + p(x)w(x) = q(x)$$

Where here

$$\begin{aligned} p(x) &= \frac{1}{x} \\ q(x) &= -x \end{aligned}$$

Hence the ode is

$$w'(x) + \frac{w(x)}{x} = -x$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int \frac{1}{x} dx} \\ &= x\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu w) &= (\mu)(-x) \\ \frac{d}{dx}(xw) &= (x)(-x) \\ d(xw) &= (-x^2) dx\end{aligned}$$

Integrating gives

$$\begin{aligned}xw &= \int -x^2 dx \\ xw &= -\frac{x^3}{3} + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = x$ results in

$$w(x) = -\frac{x^2}{3} + \frac{c_1}{x}$$

Replacing w in the above by y^2 using equation (5) gives the final solution.

$$y^2 = -\frac{x^2}{3} + \frac{c_1}{x}$$

Solving for y gives

$$\begin{aligned}y(x) &= \frac{\sqrt{3} \sqrt{-x(x^3 - 3c_1)}}{3x} \\ y(x) &= -\frac{\sqrt{3} \sqrt{-x(x^3 - 3c_1)}}{3x}\end{aligned}$$

Summary

The solution(s) found are the following

$$y = \frac{\sqrt{3} \sqrt{-x(x^3 - 3c_1)}}{3x} \tag{1}$$

$$y = -\frac{\sqrt{3} \sqrt{-x(x^3 - 3c_1)}}{3x} \tag{2}$$

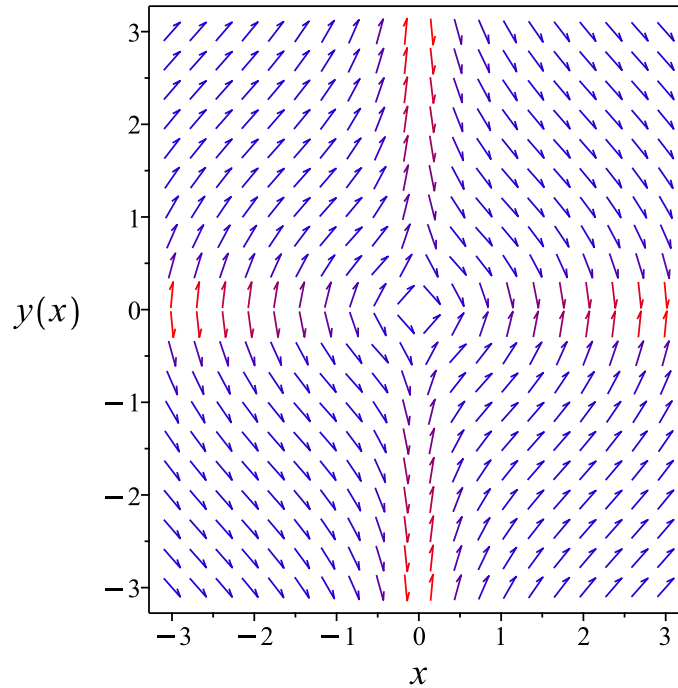


Figure 11: Slope field plot

Verification of solutions

$$y = \frac{\sqrt{3} \sqrt{-x(x^3 - 3c_1)}}{3x}$$

Verified OK.

$$y = -\frac{\sqrt{3} \sqrt{-x(x^3 - 3c_1)}}{3x}$$

Verified OK.

1.5.4 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \quad (\text{B})$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (\text{1A})$$

Therefore

$$\begin{aligned} (2xy) dy &= (-x^2 - y^2) dx \\ (x^2 + y^2) dx + (2xy) dy &= 0 \end{aligned} \quad (\text{2A})$$

Comparing (1A) and (2A) shows that

$$\begin{aligned} M(x, y) &= x^2 + y^2 \\ N(x, y) &= 2xy \end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned} \frac{\partial M}{\partial y} &= \frac{\partial}{\partial y} (x^2 + y^2) \\ &= 2y \end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(2xy) \\ &= 2y\end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \tag{1}$$

$$\frac{\partial \phi}{\partial y} = N \tag{2}$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int M dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int x^2 + y^2 dx \\ \phi &= \frac{1}{3}x^3 + xy^2 + f(y)\end{aligned} \tag{3}$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = 2xy + f'(y) \tag{4}$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = 2xy$. Therefore equation (4) becomes

$$2xy = 2xy + f'(y) \tag{5}$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 0$$

Therefore

$$f(y) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(y)$ into equation (3) gives ϕ

$$\phi = \frac{1}{3}x^3 + xy^2 + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = \frac{1}{3}x^3 + xy^2$$

Summary

The solution(s) found are the following

$$\frac{x^3}{3} + y^2x = c_1 \tag{1}$$

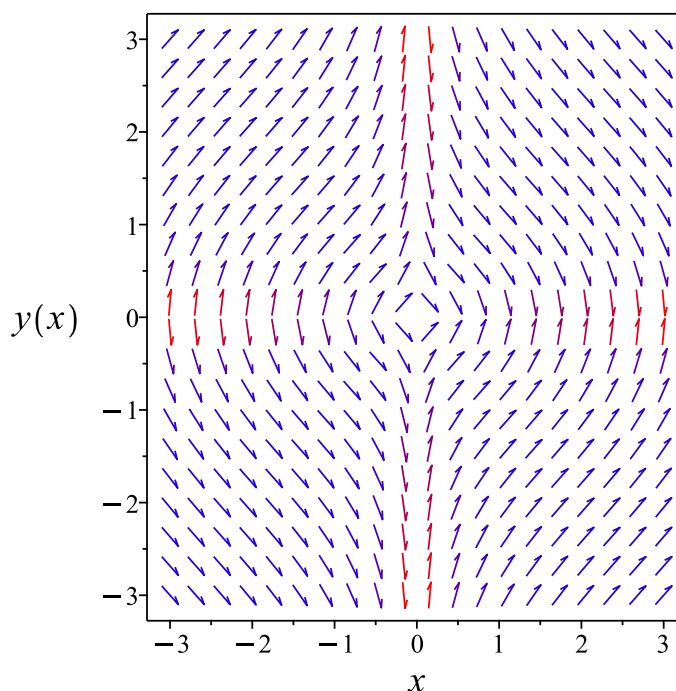


Figure 12: Slope field plot

Verification of solutions

$$\frac{x^3}{3} + y^2x = c_1$$

Verified OK.

1.5.5 Maple step by step solution

Let's solve

$$2xyy' + y^2 = -x^2$$

- Highest derivative means the order of the ODE is 1

y'

- Check if ODE is exact

- ODE is exact if the lhs is the total derivative of a C^2 function

$$F'(x, y) = 0$$

- Compute derivative of lhs

$$F'(x, y) + \left(\frac{\partial}{\partial y} F(x, y)\right) y' = 0$$

- Evaluate derivatives

$$2y = 2y$$

- Condition met, ODE is exact

- Exact ODE implies solution will be of this form

$$\left[F(x, y) = c_1, M(x, y) = F'(x, y), N(x, y) = \frac{\partial}{\partial y} F(x, y) \right]$$

- Solve for $F(x, y)$ by integrating $M(x, y)$ with respect to x

$$F(x, y) = \int (x^2 + y^2) dx + f_1(y)$$

- Evaluate integral

$$F(x, y) = \frac{x^3}{3} + x y^2 + f_1(y)$$

- Take derivative of $F(x, y)$ with respect to y

$$N(x, y) = \frac{\partial}{\partial y} F(x, y)$$

- Compute derivative

$$2xy = 2xy + \frac{d}{dy} f_1(y)$$

- Isolate for $\frac{d}{dy} f_1(y)$

$$\frac{d}{dy} f_1(y) = 0$$

- Solve for $f_1(y)$

$$f_1(y) = 0$$

- Substitute $f_1(y)$ into equation for $F(x, y)$

$$F(x, y) = \frac{1}{3}x^3 + x y^2$$

- Substitute $F(x, y)$ into the solution of the ODE

$$\frac{1}{3}x^3 + x y^2 = c_1$$

- Solve for y

$$\left\{ y = -\frac{\sqrt{3} \sqrt{x(-x^3+3c_1)}}{3x}, y = \frac{\sqrt{3} \sqrt{x(-x^3+3c_1)}}{3x} \right\}$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
<- Bernoulli successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 47

```
dsolve(2*x*y(x)*diff(y(x),x)+x^2+y(x)^2=0,y(x), singsol=all)
```

$$y(x) = -\frac{\sqrt{3} \sqrt{-x(x^3 - 3c_1)}}{3x}$$

$$y(x) = \frac{\sqrt{3} \sqrt{-x(x^3 - 3c_1)}}{3x}$$

✓ Solution by Mathematica

Time used: 0.377 (sec). Leaf size: 60

```
DSolve[2*x*y[x]*y'[x]+x^2+y[x]^2==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow -\frac{\sqrt{-x^3 + 3c_1}}{\sqrt{3}\sqrt{x}}$$

$$y(x) \rightarrow \frac{\sqrt{-x^3 + 3c_1}}{\sqrt{3}\sqrt{x}}$$

1.6 problem 2(b)

1.6.1	Solving as first order ode lie symmetry lookup ode	65
1.6.2	Solving as bernoulli ode	69
1.6.3	Solving as exact ode	73

Internal problem ID [11575]

Internal file name [OUTPUT/10557_Thursday_May_18_2023_05_39_35_AM_47002682/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 1, Differential equations and their solutions. Exercises page 13

Problem number: 2(b).

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "bernoulli", "exactWithIntegrationFactor", "first_order_ode_lie_symmetry_lookup"

Maple gives the following as the ode type

```
[[_homogeneous, `class G`], _rational, _Bernoulli]
```

$$y'x + y - y^3x^3 = 0$$

1.6.1 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = \frac{y(y^2x^3 - 1)}{x}$$
$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2\xi_y - \omega_x\xi - \omega_y\eta = 0 \tag{A}$$

The type of this ode is known. It is of type `Bernoulli`. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 12: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int(n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= y^3x^2\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{y^3 x^2} dy \end{aligned}$$

Which results in

$$S = -\frac{1}{2x^2 y^2}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = \frac{y(y^2 x^3 - 1)}{x}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= \frac{1}{x^3 y^2} \\ S_y &= \frac{1}{y^3 x^2} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 1 \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 1$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = R + c_1 \quad (4)$$

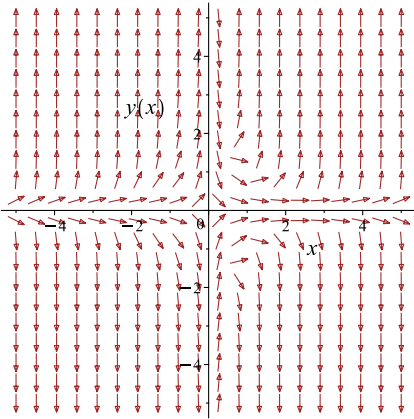
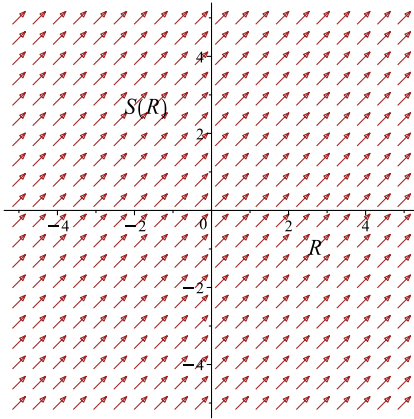
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$-\frac{1}{2x^2y^2} = x + c_1$$

Which simplifies to

$$-\frac{1}{2x^2y^2} = x + c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = \frac{y(y^2x^3-1)}{x}$ 	$R = x$ $S = -\frac{1}{2x^2y^2}$	$\frac{dS}{dR} = 1$ 

Summary

The solution(s) found are the following

$$-\frac{1}{2x^2y^2} = x + c_1 \quad (1)$$

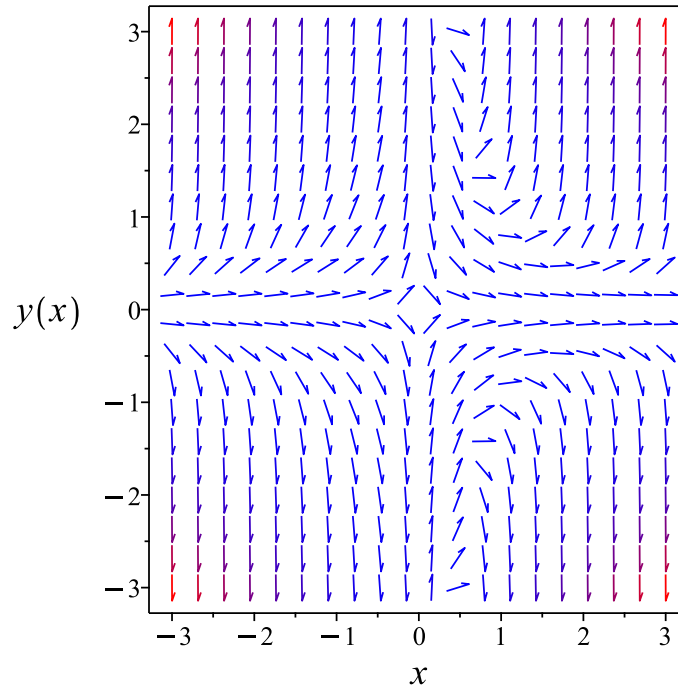


Figure 13: Slope field plot

Verification of solutions

$$-\frac{1}{2x^2y^2} = x + c_1$$

Verified OK.

1.6.2 Solving as bernoulli ode

In canonical form, the ODE is

$$\begin{aligned} y' &= F(x, y) \\ &= \frac{y(y^2x^3 - 1)}{x} \end{aligned}$$

This is a Bernoulli ODE.

$$y' = -\frac{1}{x}y + x^2y^3 \tag{1}$$

The standard Bernoulli ODE has the form

$$y' = f_0(x)y + f_1(x)y^n \tag{2}$$

The first step is to divide the above equation by y^n which gives

$$\frac{y'}{y^n} = f_0(x)y^{1-n} + f_1(x) \tag{3}$$

The next step is use the substitution $w = y^{1-n}$ in equation (3) which generates a new ODE in $w(x)$ which will be linear and can be easily solved using an integrating factor. Backsubstitution then gives the solution $y(x)$ which is what we want.

This method is now applied to the ODE at hand. Comparing the ODE (1) With (2) Shows that

$$\begin{aligned} f_0(x) &= -\frac{1}{x} \\ f_1(x) &= x^2 \\ n &= 3 \end{aligned}$$

Dividing both sides of ODE (1) by $y^n = y^3$ gives

$$y' \frac{1}{y^3} = -\frac{1}{x y^2} + x^2 \quad (4)$$

Let

$$\begin{aligned} w &= y^{1-n} \\ &= \frac{1}{y^2} \end{aligned} \quad (5)$$

Taking derivative of equation (5) w.r.t x gives

$$w' = -\frac{2}{y^3} y' \quad (6)$$

Substituting equations (5) and (6) into equation (4) gives

$$\begin{aligned} -\frac{w'(x)}{2} &= -\frac{w(x)}{x} + x^2 \\ w' &= \frac{2w}{x} - 2x^2 \end{aligned} \quad (7)$$

The above now is a linear ODE in $w(x)$ which is now solved.

Entering Linear first order ODE solver. In canonical form a linear first order is

$$w'(x) + p(x)w(x) = q(x)$$

Where here

$$\begin{aligned} p(x) &= -\frac{2}{x} \\ q(x) &= -2x^2 \end{aligned}$$

Hence the ode is

$$w'(x) - \frac{2w(x)}{x} = -2x^2$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int -\frac{2}{x} dx} \\ &= \frac{1}{x^2}\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu w) &= (\mu)(-2x^2) \\ \frac{d}{dx}\left(\frac{w}{x^2}\right) &= \left(\frac{1}{x^2}\right)(-2x^2) \\ d\left(\frac{w}{x^2}\right) &= -2 dx\end{aligned}$$

Integrating gives

$$\begin{aligned}\frac{w}{x^2} &= \int -2 dx \\ \frac{w}{x^2} &= -2x + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = \frac{1}{x^2}$ results in

$$w(x) = c_1 x^2 - 2x^3$$

Replacing w in the above by $\frac{1}{y^2}$ using equation (5) gives the final solution.

$$\frac{1}{y^2} = c_1 x^2 - 2x^3$$

Solving for y gives

$$\begin{aligned}y(x) &= \frac{1}{\sqrt{c_1 - 2x^3}} \\ y(x) &= -\frac{1}{\sqrt{c_1 - 2x^3}}\end{aligned}$$

Summary

The solution(s) found are the following

$$y = \frac{1}{\sqrt{c_1 - 2x x}} \quad (1)$$

$$y = -\frac{1}{\sqrt{c_1 - 2x x}} \quad (2)$$

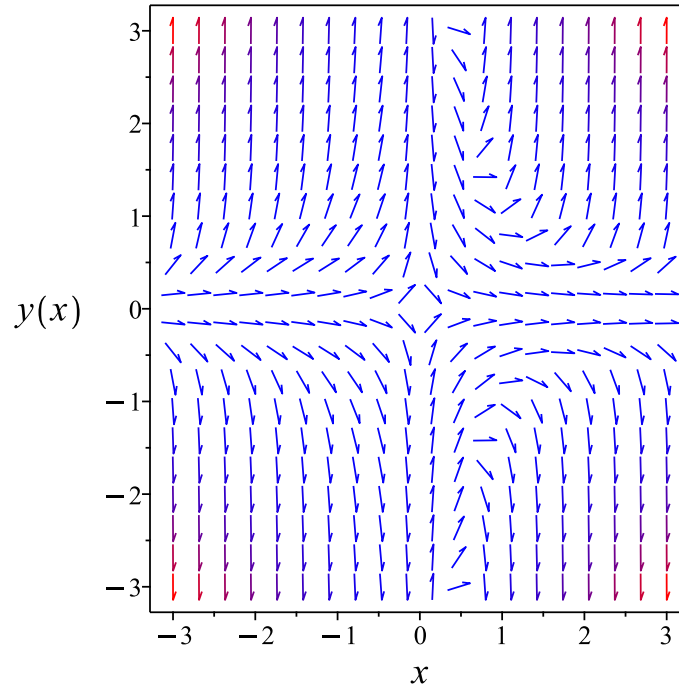


Figure 14: Slope field plot

Verification of solutions

$$y = \frac{1}{\sqrt{c_1 - 2x x}}$$

Verified OK.

$$y = -\frac{1}{\sqrt{c_1 - 2x x}}$$

Verified OK.

1.6.3 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \quad (\text{A})$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \quad (\text{B})$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (\text{1A})$$

Therefore

$$\begin{aligned} (x) dy &= (x^3 y^3 - y) dx \\ (-x^3 y^3 + y) dx + (x) dy &= 0 \end{aligned} \quad (\text{2A})$$

Comparing (1A) and (2A) shows that

$$\begin{aligned} M(x, y) &= -x^3 y^3 + y \\ N(x, y) &= x \end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(-x^3y^3 + y) \\ &= -3y^2x^3 + 1\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(x) \\ &= 1\end{aligned}$$

Since $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$\begin{aligned}A &= \frac{1}{N} \left(\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} \right) \\ &= \frac{1}{x} ((-3y^2x^3 + 1) - (1)) \\ &= -3x^2y^2\end{aligned}$$

Since A depends on y , it can not be used to obtain an integrating factor. We will now try a second method to find an integrating factor. Let

$$\begin{aligned}B &= \frac{1}{M} \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) \\ &= \frac{1}{-x^3y^3 + y} ((1) - (-3y^2x^3 + 1)) \\ &= -\frac{3yx^3}{y^2x^3 - 1}\end{aligned}$$

Since B depends on x , it can not be used to obtain an integrating factor. We will now try a third method to find an integrating factor. Let

$$R = \frac{\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y}}{xM - yN}$$

R is now checked to see if it is a function of only $t = xy$. Therefore

$$\begin{aligned} R &= \frac{\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y}}{xM - yN} \\ &= \frac{(1) - (-3y^2x^3 + 1)}{x(-x^3y^3 + y) - y(x)} \\ &= -\frac{3}{xy} \end{aligned}$$

Replacing all powers of terms xy by t gives

$$R = -\frac{3}{t}$$

Since R depends on t only, then it can be used to find an integrating factor. Let the integrating factor be μ then

$$\begin{aligned} \mu &= e^{\int R dt} \\ &= e^{\int (-\frac{3}{t}) dt} \end{aligned}$$

The result of integrating gives

$$\begin{aligned} \mu &= e^{-3\ln(t)} \\ &= \frac{1}{t^3} \end{aligned}$$

Now t is replaced back with xy giving

$$\mu = \frac{1}{x^3y^3}$$

Multiplying M and N by this integrating factor gives new M and new N which are called \bar{M} and \bar{N} so not to confuse them with the original M and N

$$\begin{aligned} \bar{M} &= \mu M \\ &= \frac{1}{x^3y^3}(-x^3y^3 + y) \\ &= \frac{-y^2x^3 + 1}{y^2x^3} \end{aligned}$$

And

$$\begin{aligned} \bar{N} &= \mu N \\ &= \frac{1}{x^3y^3}(x) \\ &= \frac{1}{y^3x^2} \end{aligned}$$

A modified ODE is now obtained from the original ODE, which is exact and can be solved. The modified ODE is

$$\begin{aligned} \overline{M} + \overline{N} \frac{dy}{dx} &= 0 \\ \left(\frac{-y^2x^3 + 1}{y^2x^3} \right) + \left(\frac{1}{y^3x^2} \right) \frac{dy}{dx} &= 0 \end{aligned}$$

The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = \overline{M} \quad (1)$$

$$\frac{\partial \phi}{\partial y} = \overline{N} \quad (2)$$

Integrating (1) w.r.t. x gives

$$\begin{aligned} \int \frac{\partial \phi}{\partial x} dx &= \int \overline{M} dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int \frac{-y^2x^3 + 1}{y^2x^3} dx \\ \phi &= \frac{-xy^2 - \frac{1}{2x^2}}{y^2} + f(y) \end{aligned} \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\begin{aligned} \frac{\partial \phi}{\partial y} &= -\frac{2(-xy^2 - \frac{1}{2x^2})}{y^3} - \frac{2x}{y} + f'(y) \\ &= \frac{1}{y^3x^2} + f'(y) \end{aligned} \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = \frac{1}{y^3x^2}$. Therefore equation (4) becomes

$$\frac{1}{y^3x^2} = \frac{1}{y^3x^2} + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 0$$

Therefore

$$f(y) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(y)$ into equation (3) gives ϕ

$$\phi = \frac{-x y^2 - \frac{1}{2x^2}}{y^2} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = \frac{-x y^2 - \frac{1}{2x^2}}{y^2}$$

Summary

The solution(s) found are the following

$$\frac{-y^2 x - \frac{1}{2x^2}}{y^2} = c_1 \quad (1)$$

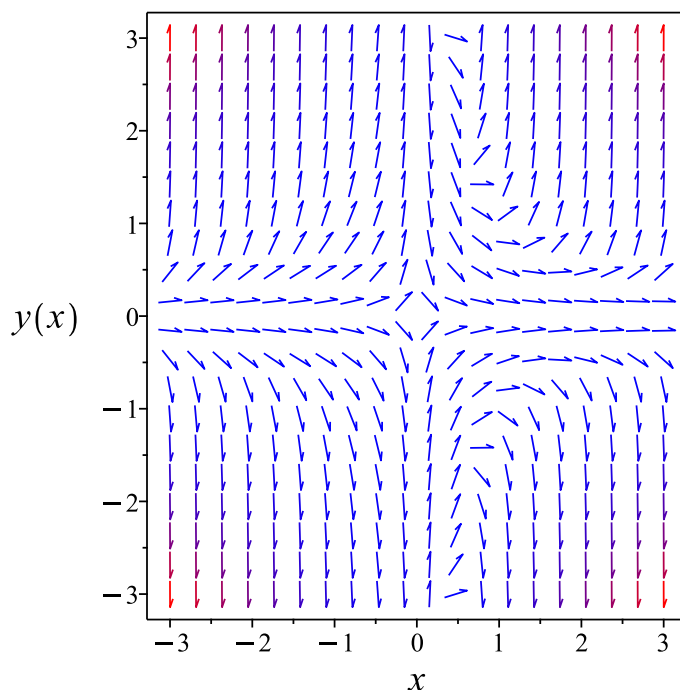


Figure 15: Slope field plot

Verification of solutions

$$\frac{-y^2 x - \frac{1}{2x^2}}{y^2} = c_1$$

Verified OK.

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
trying Bernoulli  
<- Bernoulli successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 30

```
dsolve(x*diff(y(x),x)+y(x)=x^3*y(x)^3,y(x), singsol=all)
```

$$y(x) = \frac{1}{\sqrt{-2x + c_1} x}$$
$$y(x) = -\frac{1}{\sqrt{-2x + c_1} x}$$

✓ Solution by Mathematica

Time used: 0.6 (sec). Leaf size: 44

```
DSolve[x*y'[x]+y[x]==x^3*y[x]^3,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow -\frac{1}{\sqrt{x^2(-2x + c_1)}}$$
$$y(x) \rightarrow \frac{1}{\sqrt{x^2(-2x + c_1)}}$$
$$y(x) \rightarrow 0$$

1.7 problem 3(a)

1.7.1	Solving as linear ode	79
1.7.2	Solving as first order ode lie symmetry lookup ode	81
1.7.3	Solving as exact ode	85
1.7.4	Maple step by step solution	89

Internal problem ID [11576]

Internal file name [OUTPUT/10558_Thursday_May_18_2023_05_39_37_AM_88378866/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 1, Differential equations and their solutions. Exercises page 13

Problem number: 3(a).

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "linear", "exactWithIntegrationFactor", "first_order_ode_lie_symmetry_lookup"

Maple gives the following as the ode type

```
[[_linear, `class A`]]
```

$$y' + 3y = 3x^2e^{-3x}$$

1.7.1 Solving as linear ode

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = 3$$
$$q(x) = 3x^2e^{-3x}$$

Hence the ode is

$$y' + 3y = 3x^2e^{-3x}$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int 3dx} \\ &= e^{3x}\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu y) &= (\mu) (3x^2 e^{-3x}) \\ \frac{d}{dx}(e^{3x}y) &= (e^{3x}) (3x^2 e^{-3x}) \\ d(e^{3x}y) &= (3x^2) dx\end{aligned}$$

Integrating gives

$$\begin{aligned}e^{3x}y &= \int 3x^2 dx \\ e^{3x}y &= x^3 + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = e^{3x}$ results in

$$y = e^{-3x}x^3 + c_1e^{-3x}$$

which simplifies to

$$y = e^{-3x}(x^3 + c_1)$$

Summary

The solution(s) found are the following

$$y = e^{-3x}(x^3 + c_1) \tag{1}$$

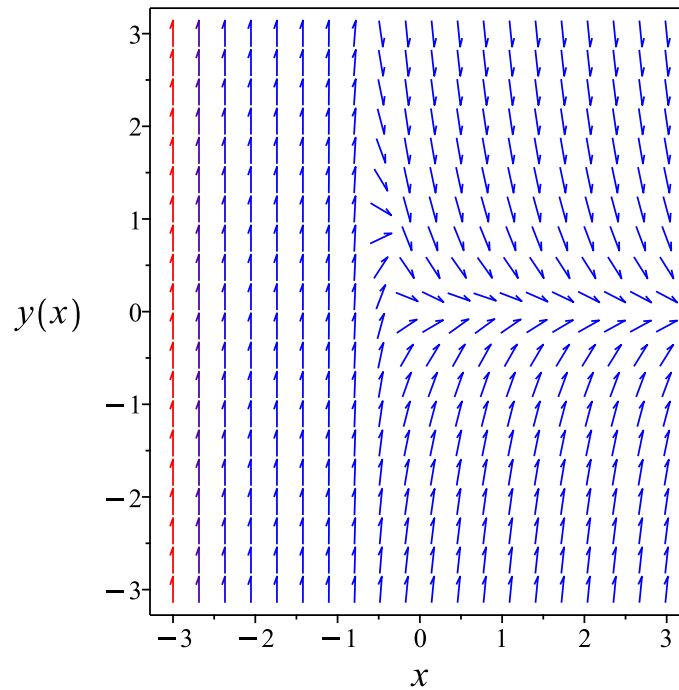


Figure 16: Slope field plot

Verification of solutions

$$y = e^{-3x}(x^3 + c_1)$$

Verified OK.

1.7.2 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = -3y + 3x^2e^{-3x}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2\xi_y - \omega_x\xi - \omega_y\eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 14: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= e^{-3x}\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{e^{-3x}} dy \end{aligned}$$

Which results in

$$S = e^{3x}y$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -3y + 3x^2e^{-3x}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= 3e^{3x}y \\ S_y &= e^{3x} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 3x^2 \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 3R^2$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by

integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = R^3 + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$e^{3x}y = x^3 + c_1$$

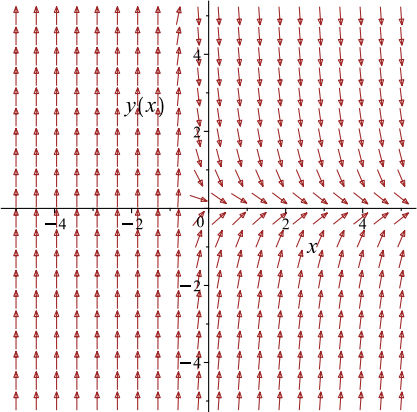
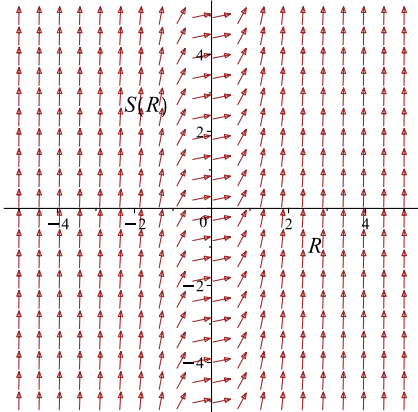
Which simplifies to

$$e^{3x}y = x^3 + c_1$$

Which gives

$$y = e^{-3x}(x^3 + c_1)$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -3y + 3x^2e^{-3x}$ 	$R = x$ $S = e^{3x}y$	$\frac{dS}{dR} = 3R^2$ 

Summary

The solution(s) found are the following

$$y = e^{-3x}(x^3 + c_1) \quad (1)$$

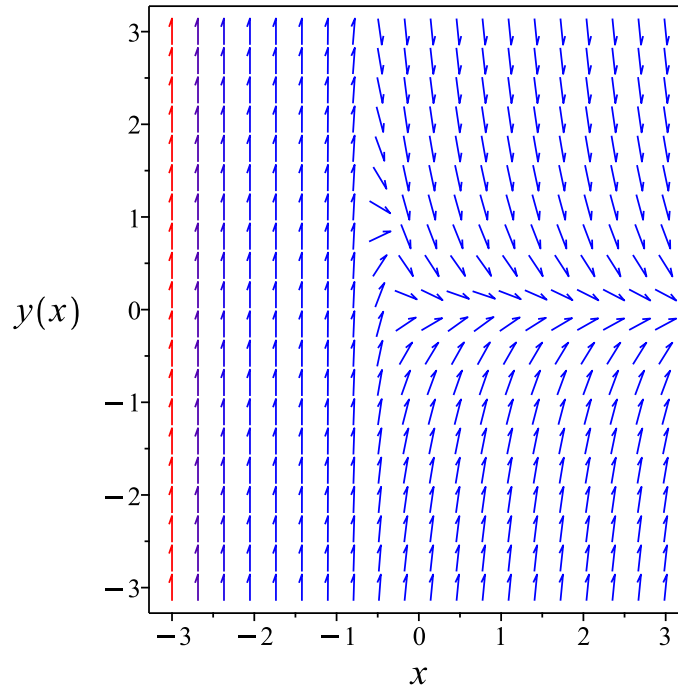


Figure 17: Slope field plot

Verification of solutions

$$y = e^{-3x}(x^3 + c_1)$$

Verified OK.

1.7.3 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx}\phi(x, y) = 0$$

Hence

$$\frac{\partial\phi}{\partial x} + \frac{\partial\phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial\phi}{\partial x} &= M \\ \frac{\partial\phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \tag{1A}$$

Therefore

$$\begin{aligned}dy &= (-3y + 3x^2e^{-3x}) dx \\ (3y - 3x^2e^{-3x}) dx + dy &= 0\end{aligned} \tag{2A}$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= 3y - 3x^2e^{-3x} \\ N(x, y) &= 1\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(3y - 3x^2e^{-3x}) \\ &= 3\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(1) \\ &= 0\end{aligned}$$

Since $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$\begin{aligned} A &= \frac{1}{N} \left(\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} \right) \\ &= 1((3) - (0)) \\ &= 3 \end{aligned}$$

Since A does not depend on y , then it can be used to find an integrating factor. The integrating factor μ is

$$\begin{aligned} \mu &= e^{\int A dx} \\ &= e^{\int 3 dx} \end{aligned}$$

The result of integrating gives

$$\begin{aligned} \mu &= e^{3x} \\ &= e^{3x} \end{aligned}$$

M and N are multiplied by this integrating factor, giving new M and new N which are called \bar{M} and \bar{N} for now so not to confuse them with the original M and N .

$$\begin{aligned} \bar{M} &= \mu M \\ &= e^{3x}(3y - 3x^2 e^{-3x}) \\ &= 3e^{3x}y - 3x^2 \end{aligned}$$

And

$$\begin{aligned} \bar{N} &= \mu N \\ &= e^{3x}(1) \\ &= e^{3x} \end{aligned}$$

Now a modified ODE is obtained from the original ODE, which is exact and can be solved. The modified ODE is

$$\begin{aligned} \bar{M} + \bar{N} \frac{dy}{dx} &= 0 \\ (3e^{3x}y - 3x^2) + (e^{3x}) \frac{dy}{dx} &= 0 \end{aligned}$$

The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = \bar{M} \tag{1}$$

$$\frac{\partial \phi}{\partial y} = \bar{N} \tag{2}$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int \bar{M} dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int 3e^{3x}y - 3x^2 dx \\ \phi &= e^{3x}y - x^3 + f(y)\end{aligned}\quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = e^{3x} + f'(y)\quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = e^{3x}$. Therefore equation (4) becomes

$$e^{3x} = e^{3x} + f'(y)\quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 0$$

Therefore

$$f(y) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(y)$ into equation (3) gives ϕ

$$\phi = e^{3x}y - x^3 + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = e^{3x}y - x^3$$

The solution becomes

$$y = e^{-3x}(x^3 + c_1)$$

Summary

The solution(s) found are the following

$$y = e^{-3x}(x^3 + c_1)\quad (1)$$

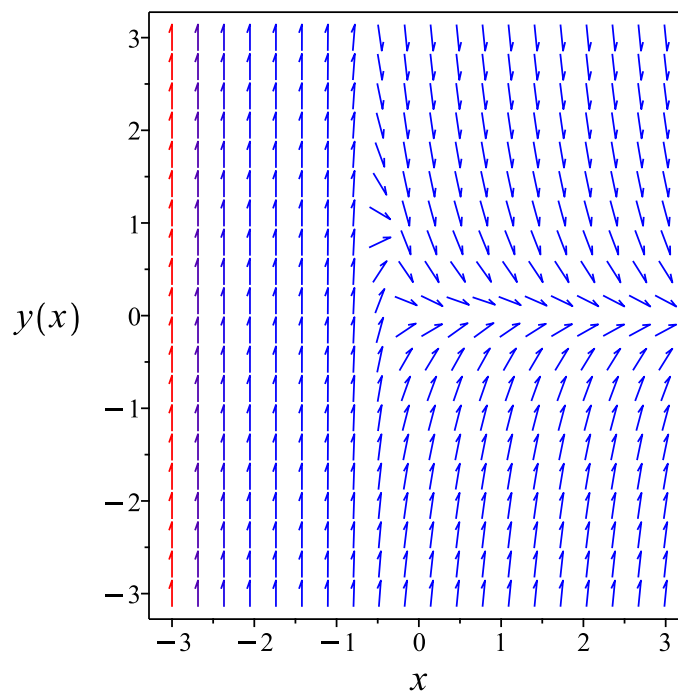


Figure 18: Slope field plot

Verification of solutions

$$y = e^{-3x}(x^3 + c_1)$$

Verified OK.

1.7.4 Maple step by step solution

Let's solve

$$y' + 3y = 3x^2e^{-3x}$$

- Highest derivative means the order of the ODE is 1

$$y'$$

- Isolate the derivative

$$y' = -3y + 3x^2e^{-3x}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE

$$y' + 3y = 3x^2e^{-3x}$$

- The ODE is linear; multiply by an integrating factor $\mu(x)$

$$\mu(x)(y' + 3y) = 3\mu(x)x^2e^{-3x}$$

- Assume the lhs of the ODE is the total derivative $\frac{d}{dx}(\mu(x)y)$

$$\mu(x)(y' + 3y) = \mu'(x)y + \mu(x)y'$$
- Isolate $\mu'(x)$

$$\mu'(x) = 3\mu(x)$$
- Solve to find the integrating factor

$$\mu(x) = e^{3x}$$
- Integrate both sides with respect to x

$$\int \left(\frac{d}{dx}(\mu(x)y)\right) dx = \int 3\mu(x)x^2e^{-3x} dx + c_1$$
- Evaluate the integral on the lhs

$$\mu(x)y = \int 3\mu(x)x^2e^{-3x} dx + c_1$$
- Solve for y

$$y = \frac{\int 3\mu(x)x^2e^{-3x} dx + c_1}{\mu(x)}$$
- Substitute $\mu(x) = e^{3x}$

$$y = \frac{\int 3x^2e^{-3x}e^{3x} dx + c_1}{e^{3x}}$$
- Evaluate the integrals on the rhs

$$y = \frac{x^3 + c_1}{e^{3x}}$$
- Simplify

$$y = e^{-3x}(x^3 + c_1)$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
<- 1st order linear successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 14

```
dsolve(diff(y(x),x)+3*y(x)=3*x^2*exp(-3*x),y(x), singsol=all)
```

$$y(x) = (x^3 + c_1) e^{-3x}$$

✓ Solution by Mathematica

Time used: 0.098 (sec). Leaf size: 17

```
DSolve[y'[x]+3*y[x]==3*x^2*Exp[-3*x],y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^{-3x} (x^3 + c_1)$$

1.8 problem 3(b)

1.8.1	Solving as separable ode	92
1.8.2	Solving as linear ode	94
1.8.3	Solving as first order ode lie symmetry lookup ode	95
1.8.4	Solving as exact ode	99
1.8.5	Maple step by step solution	103

Internal problem ID [11577]

Internal file name [OUTPUT/10559_Thursday_May_18_2023_05_56_26_PM_75656588/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 1, Differential equations and their solutions. Exercises page 13

Problem number: 3(b).

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact", "linear", "separable", "first_order_ode_lie_symmetry_lookup"

Maple gives the following as the ode type

[_separable]

$$y' + 4yx = 8x$$

1.8.1 Solving as separable ode

In canonical form the ODE is

$$\begin{aligned}y' &= F(x, y) \\ &= f(x)g(y) \\ &= x(-4y + 8)\end{aligned}$$

Where $f(x) = x$ and $g(y) = -4y + 8$. Integrating both sides gives

$$\begin{aligned}\frac{1}{-4y + 8} dy &= x dx \\ \int \frac{1}{-4y + 8} dy &= \int x dx\end{aligned}$$

$$-\frac{\ln(y-2)}{4} = \frac{x^2}{2} + c_1$$

Raising both side to exponential gives

$$\frac{1}{(y-2)^{\frac{1}{4}}} = e^{\frac{x^2}{2} + c_1}$$

Which simplifies to

$$\frac{1}{(y-2)^{\frac{1}{4}}} = c_2 e^{\frac{x^2}{2}}$$

Summary

The solution(s) found are the following

$$y = \frac{\left(2c_2^4 e^{2x^2+4c_1} + 1\right) e^{-2x^2-4c_1}}{c_2^4} \quad (1)$$

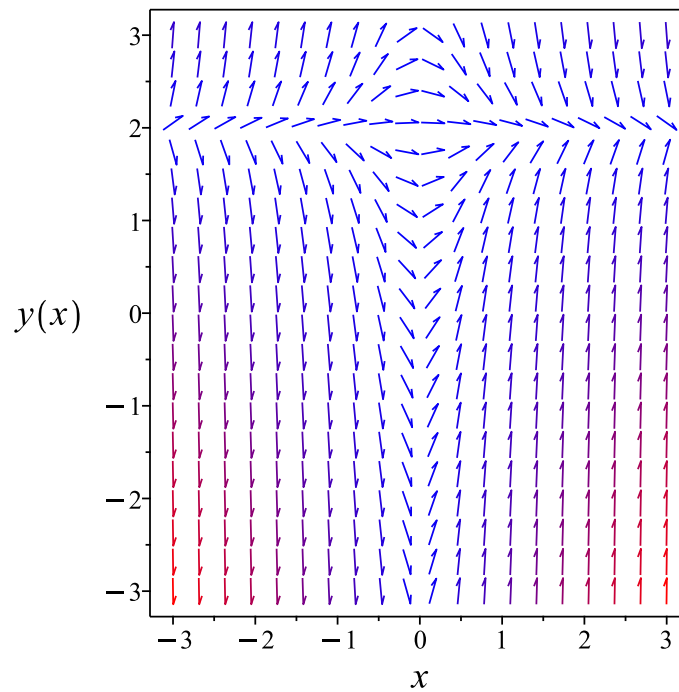


Figure 19: Slope field plot

Verification of solutions

$$y = \frac{\left(2c_2^4 e^{2x^2+4c_1} + 1\right) e^{-2x^2-4c_1}}{c_2^4}$$

Verified OK.

1.8.2 Solving as linear ode

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = 4x$$

$$q(x) = 8x$$

Hence the ode is

$$y' + 4yx = 8x$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int 4x dx} \\ &= e^{2x^2}\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu y) &= (\mu)(8x) \\ \frac{d}{dx}(e^{2x^2}y) &= (e^{2x^2})(8x) \\ d(e^{2x^2}y) &= (8xe^{2x^2}) dx\end{aligned}$$

Integrating gives

$$\begin{aligned}e^{2x^2}y &= \int 8xe^{2x^2} dx \\ e^{2x^2}y &= 2e^{2x^2} + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = e^{2x^2}$ results in

$$y = 2e^{-2x^2}e^{2x^2} + c_1e^{-2x^2}$$

which simplifies to

$$y = 2 + c_1e^{-2x^2}$$

Summary

The solution(s) found are the following

$$y = 2 + c_1e^{-2x^2} \tag{1}$$

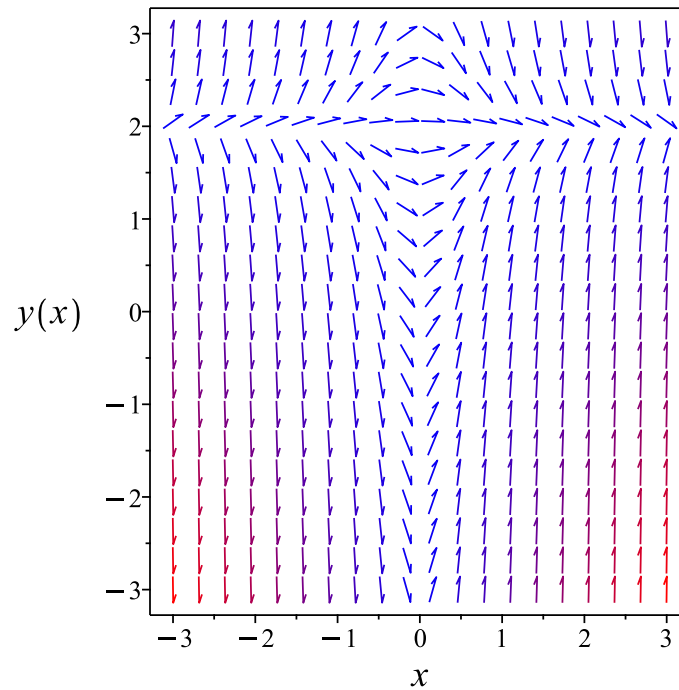


Figure 20: Slope field plot

Verification of solutions

$$y = 2 + c_1 e^{-2x^2}$$

Verified OK.

1.8.3 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = -4xy + 8x$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 17: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= e^{-2x^2}\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right)S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{e^{-2x^2}} dy \end{aligned}$$

Which results in

$$S = e^{2x^2} y$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -4xy + 8x$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= 4x e^{2x^2} y \\ S_y &= e^{2x^2} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 8x e^{2x^2} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 8R e^{2R^2}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by

integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = 2 e^{2R^2} + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$e^{2x^2} y = 2 e^{2x^2} + c_1$$

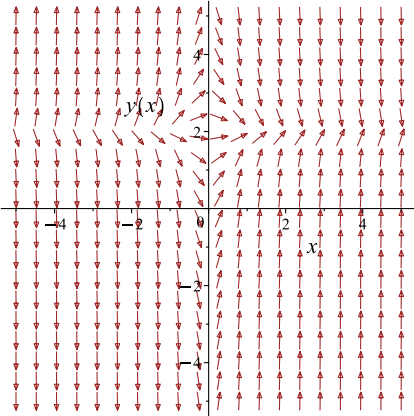
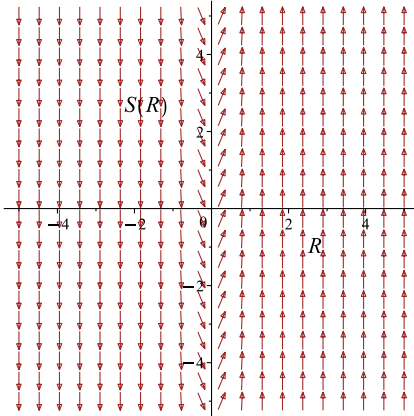
Which simplifies to

$$(y - 2) e^{2x^2} - c_1 = 0$$

Which gives

$$y = \left(2 e^{2x^2} + c_1 \right) e^{-2x^2}$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -4xy + 8x$ 	$R = x$ $S = e^{2x^2} y$	$\frac{dS}{dR} = 8R e^{2R^2}$ 

Summary

The solution(s) found are the following

$$y = \left(2 e^{2x^2} + c_1 \right) e^{-2x^2} \quad (1)$$

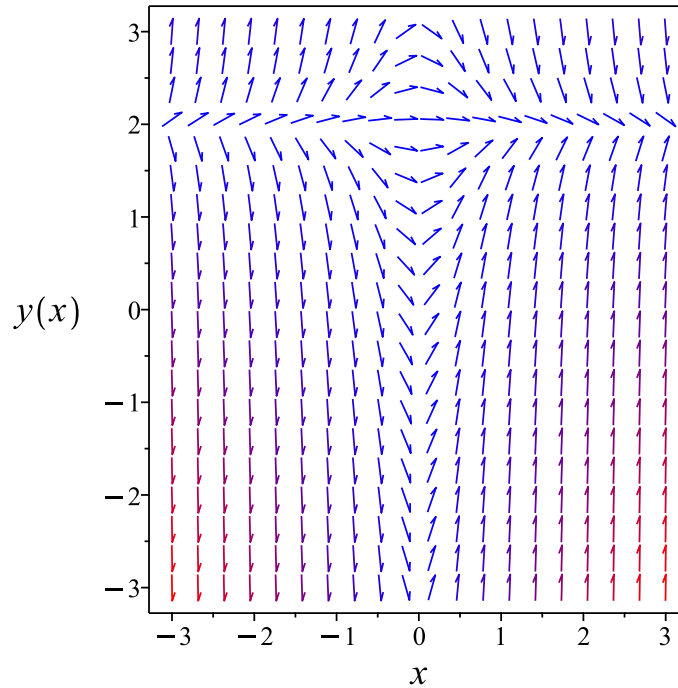


Figure 21: Slope field plot

Verification of solutions

$$y = \left(2 e^{2x^2} + c_1\right) e^{-2x^2}$$

Verified OK.

1.8.4 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (1A)$$

Therefore

$$\begin{aligned}\left(\frac{1}{-4y+8}\right) dy &= (x) dx \\ (-x) dx + \left(\frac{1}{-4y+8}\right) dy &= 0\end{aligned} \quad (2A)$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= -x \\ N(x, y) &= \frac{1}{-4y+8}\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(-x) \\ &= 0\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x} \left(\frac{1}{-4y+8} \right) \\ &= 0\end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \quad (1)$$

$$\frac{\partial \phi}{\partial y} = N \quad (2)$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int M dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int -x dx \\ \phi &= -\frac{x^2}{2} + f(y)\end{aligned} \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = 0 + f'(y) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = \frac{1}{-4y+8}$. Therefore equation (4) becomes

$$\frac{1}{-4y+8} = 0 + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = -\frac{1}{4(y-2)}$$

Integrating the above w.r.t y gives

$$\int f'(y) dy = \int \left(-\frac{1}{4y-8} \right) dy$$
$$f(y) = -\frac{\ln(y-2)}{4} + c_1$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = -\frac{x^2}{2} - \frac{\ln(y-2)}{4} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -\frac{x^2}{2} - \frac{\ln(y-2)}{4}$$

The solution becomes

$$y = e^{-2x^2-4c_1} + 2$$

Summary

The solution(s) found are the following

$$y = e^{-2x^2-4c_1} + 2 \tag{1}$$

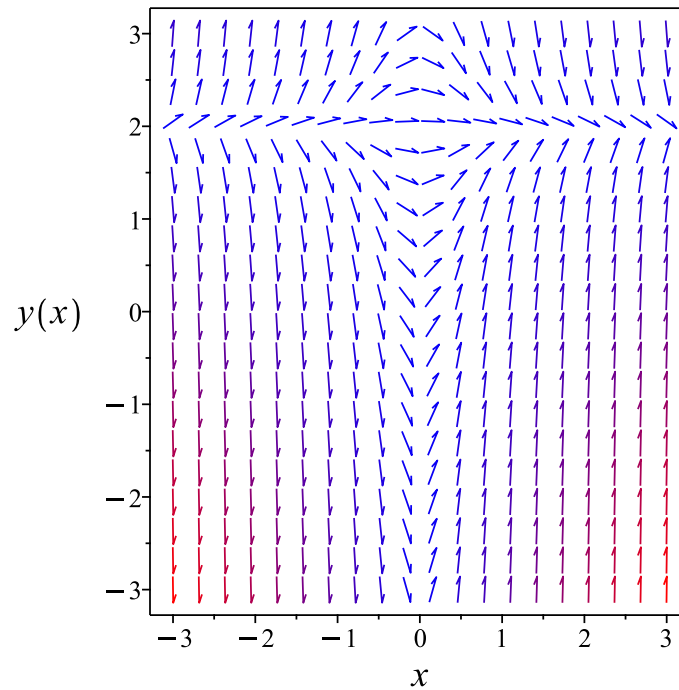


Figure 22: Slope field plot

Verification of solutions

$$y = e^{-2x^2 - 4c_1} + 2$$

Verified OK.

1.8.5 Maple step by step solution

Let's solve

$$y' + 4yx = 8x$$

- Highest derivative means the order of the ODE is 1

$$y'$$

- Separate variables

$$\frac{y'}{y-2} = -4x$$

- Integrate both sides with respect to x

$$\int \frac{y'}{y-2} dx = \int -4x dx + c_1$$

- Evaluate integral

- $\ln(y - 2) = -2x^2 + c_1$
 • Solve for y
 $y = e^{-2x^2 + c_1} + 2$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
<- 1st order linear successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 14

```
dsolve(diff(y(x),x)+4*x*y(x)=8*x,y(x), singsol=all)
```

$$y(x) = 2 + e^{-2x^2} c_1$$

✓ Solution by Mathematica

Time used: 0.074 (sec). Leaf size: 22

```
DSolve[y'[x]+4*x*y[x]==8*x,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow 2 + c_1 e^{-2x^2}$$

$$y(x) \rightarrow 2$$

1.9 problem 4(a)

1.9.1	Solving as second order linear constant coeff ode	105
1.9.2	Solving using Kovacic algorithm	107
1.9.3	Maple step by step solution	111

Internal problem ID [11578]

Internal file name [OUTPUT/10560_Thursday_May_18_2023_05_56_27_PM_64152595/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 1, Differential equations and their solutions. Exercises page 13

Problem number: 4(a).

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"kovacic", "second_order_linear_constant_coeff"**

Maple gives the following as the ode type

```
[[_2nd_order , _missing_x]]
```

$$y'' - 2y' - 8y = 0$$

1.9.1 Solving as second order linear constant coeff ode

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = -2, C = -8$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} - 2\lambda e^{\lambda x} - 8 e^{\lambda x} = 0 \tag{1}$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 - 2\lambda - 8 = 0 \tag{2}$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = -2, C = -8$ into the above gives

$$\begin{aligned}\lambda_{1,2} &= \frac{2}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{-2^2 - (4)(1)(-8)} \\ &= 1 \pm 3\end{aligned}$$

Hence

$$\lambda_1 = 1 + 3$$

$$\lambda_2 = 1 - 3$$

Which simplifies to

$$\lambda_1 = 4$$

$$\lambda_2 = -2$$

Since roots are real and distinct, then the solution is

$$y = c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x}$$

$$y = c_1 e^{(4)x} + c_2 e^{(-2)x}$$

Or

$$y = c_1 e^{4x} + c_2 e^{-2x}$$

Summary

The solution(s) found are the following

$$y = c_1 e^{4x} + c_2 e^{-2x} \tag{1}$$

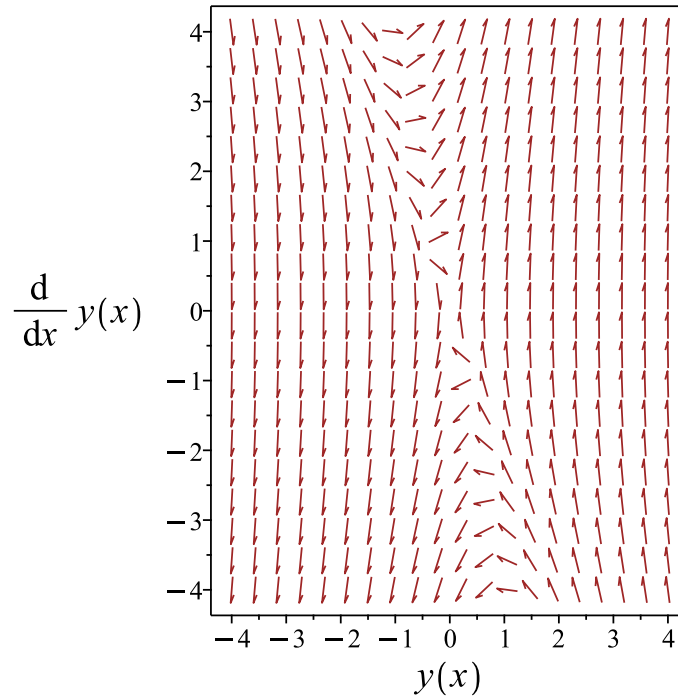


Figure 23: Slope field plot

Verification of solutions

$$y = c_1 e^{4x} + c_2 e^{-2x}$$

Verified OK.

1.9.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' - 2y' - 8y = 0 \tag{1}$$

$$Ay'' + By' + Cy = 0 \tag{2}$$

Comparing (1) and (2) shows that

$$A = 1$$

$$B = -2 \tag{3}$$

$$C = -8$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{9}{1} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 9 \\ t &= 1 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = 9z(x) \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 20: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = 9$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = e^{-3x}$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-2}{1} dx} \\ &= z_1 e^x \\ &= z_1 (e^x) \end{aligned}$$

Which simplifies to

$$y_1 = e^{-2x}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{-2}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{2x}}{(y_1)^2} dx \\ &= y_1 \left(\frac{e^{6x}}{6} \right) \end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (e^{-2x}) + c_2 \left(e^{-2x} \left(\frac{e^{6x}}{6} \right) \right)\end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 e^{-2x} + \frac{c_2 e^{4x}}{6} \quad (1)$$

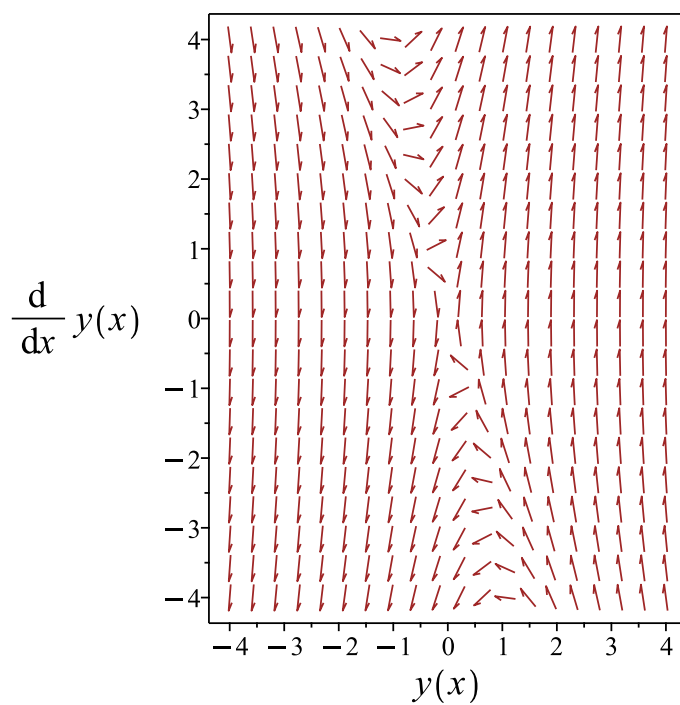


Figure 24: Slope field plot

Verification of solutions

$$y = c_1 e^{-2x} + \frac{c_2 e^{4x}}{6}$$

Verified OK.

1.9.3 Maple step by step solution

Let's solve

$$y'' - 2y' - 8y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of ODE

$$r^2 - 2r - 8 = 0$$

- Factor the characteristic polynomial

$$(r + 2)(r - 4) = 0$$

- Roots of the characteristic polynomial

$$r = (-2, 4)$$

- 1st solution of the ODE

$$y_1(x) = e^{-2x}$$

- 2nd solution of the ODE

$$y_2(x) = e^{4x}$$

- General solution of the ODE

$$y = c_1y_1(x) + c_2y_2(x)$$

- Substitute in solutions

$$y = c_1e^{-2x} + c_2e^{4x}$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
<- constant coefficients successful`
```


✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 17

```
dsolve(diff(y(x),x$2)-2*diff(y(x),x)-8*y(x)=0,y(x), singsol=all)
```

$$y(x) = c_1 e^{4x} + e^{-2x} c_2$$

✓ Solution by Mathematica

Time used: 0.023 (sec). Leaf size: 22

```
DSolve[y''[x]-2*y'[x]-8*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^{-2x} (c_2 e^{6x} + c_1)$$

1.10 problem 4(b)

1.10.1 Maple step by step solution 114

Internal problem ID [11579]

Internal file name [OUTPUT/10561_Thursday_May_18_2023_05_56_28_PM_68847962/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 1, Differential equations and their solutions. Exercises page 13

Problem number: 4(b).

ODE order: 3.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_3rd_order , _missing_x]]
```

$$y''' - 2y'' - 4y' + 8y = 0$$

The characteristic equation is

$$\lambda^3 - 2\lambda^2 - 4\lambda + 8 = 0$$

The roots of the above equation are

$$\lambda_1 = -2$$

$$\lambda_2 = 2$$

$$\lambda_3 = 2$$

Therefore the homogeneous solution is

$$y_h(x) = c_1 e^{-2x} + c_2 e^{2x} + x e^{2x} c_3$$

The fundamental set of solutions for the homogeneous solution are the following

$$y_1 = e^{-2x}$$

$$y_2 = e^{2x}$$

$$y_3 = e^{2x} x$$

Summary

The solution(s) found are the following

$$y = c_1 e^{-2x} + c_2 e^{2x} + x e^{2x} c_3 \quad (1)$$

Verification of solutions

$$y = c_1 e^{-2x} + c_2 e^{2x} + x e^{2x} c_3$$

Verified OK.

1.10.1 Maple step by step solution

Let's solve

$$y''' - 2y'' - 4y' + 8y = 0$$

- Highest derivative means the order of the ODE is 3

$$y'''$$

- Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(x)$

$$y_1(x) = y$$

- Define new variable $y_2(x)$

$$y_2(x) = y'$$

- Define new variable $y_3(x)$

$$y_3(x) = y''$$

- Isolate for $y_3'(x)$ using original ODE

$$y_3'(x) = 2y_3(x) + 4y_2(x) - 8y_1(x)$$

Convert linear ODE into a system of first order ODEs

$$[y_2(x) = y_1'(x), y_3(x) = y_2'(x), y_3'(x) = 2y_3(x) + 4y_2(x) - 8y_1(x)]$$

- Define vector

$$\vec{y}(x) = \begin{bmatrix} y_1(x) \\ y_2(x) \\ y_3(x) \end{bmatrix}$$

- System to solve

$$\vec{y}'(x) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -8 & 4 & 2 \end{bmatrix} \cdot \vec{y}(x)$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -8 & 4 & 2 \end{bmatrix}$$

- Rewrite the system as

$$\vec{y}'(x) = A \cdot \vec{y}(x)$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[-2, \begin{bmatrix} \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix} \right], \left[2, \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right], \left[2, \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[-2, \begin{bmatrix} \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_1 = e^{-2x} \cdot \begin{bmatrix} \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix}$$

- Consider eigenpair, with eigenvalue of algebraic multiplicity 2

$$\left[2, \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right]$$

- First solution from eigenvalue 2

$$\vec{y}_2(x) = e^{2x} \cdot \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix}$$

- Form of the 2nd homogeneous solution where \vec{p} is to be solved for, $\lambda = 2$ is the eigenvalue, and

$$\vec{y}_3(x) = e^{\lambda x} (x\vec{v} + \vec{p})$$

- Note that the x multiplying \vec{v} makes this solution linearly independent to the 1st solution obtained

- Substitute $\vec{y}_3(x)$ into the homogeneous system

$$\lambda e^{\lambda x} (x\vec{v} + \vec{p}) + e^{\lambda x} \vec{v} = (e^{\lambda x} A) \cdot (x\vec{v} + \vec{p})$$

- Use the fact that \vec{v} is an eigenvector of A

$$\lambda e^{\lambda x} (x\vec{v} + \vec{p}) + e^{\lambda x} \vec{v} = e^{\lambda x} (\lambda x\vec{v} + A \cdot \vec{p})$$

- Simplify equation

$$\lambda \vec{p} + \vec{v} = A \cdot \vec{p}$$

- Make use of the identity matrix I

$$(\lambda \cdot I) \cdot \vec{p} + \vec{v} = A \cdot \vec{p}$$

- Condition \vec{p} must meet for $\vec{y}_3(x)$ to be a solution to the homogeneous system

$$(A - \lambda \cdot I) \cdot \vec{p} = -\vec{v}$$

- Choose \vec{p} to use in the second solution to the homogeneous system from eigenvalue 2

$$\left(\begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -8 & 4 & 2 \end{bmatrix} - 2 \cdot \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \cdot \vec{p} = \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix}$$

- Choice of \vec{p}

$$\vec{p} = \begin{bmatrix} -\frac{1}{8} \\ 0 \\ 0 \end{bmatrix}$$

- Second solution from eigenvalue 2

$$\vec{y}_3(x) = e^{2x} \cdot \left(x \cdot \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} + \begin{bmatrix} -\frac{1}{8} \\ 0 \\ 0 \end{bmatrix} \right)$$

- General solution to the system of ODEs

$$\vec{y} = c_1 \vec{y}_1 + c_2 \vec{y}_2(x) + c_3 \vec{y}_3(x)$$

- Substitute solutions into the general solution

$$\vec{y} = c_1 e^{-2x} \cdot \begin{bmatrix} \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix} + c_2 e^{2x} \cdot \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} + e^{2x} c_3 \cdot \left(x \cdot \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} + \begin{bmatrix} -\frac{1}{8} \\ 0 \\ 0 \end{bmatrix} \right)$$

- First component of the vector is the solution to the ODE

$$y = \frac{((2x-1)c_3 + 2c_2)e^{2x}}{8} + \frac{c_1 e^{-2x}}{4}$$

Maple trace

```

`Methods for third order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 21

```
dsolve(diff(y(x),x$3)-2*diff(y(x),x$2)-4*diff(y(x),x)+8*y(x)=0,y(x), singsol=all)
```

$$y(x) = (c_3 x + c_2) e^{2x} + e^{-2x} c_1$$

✓ Solution by Mathematica

Time used: 0.005 (sec). Leaf size: 27

```
DSolve[y'''[x]-2*y''[x]-4*y'[x]+8*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^{-2x} (e^{4x} (c_3 x + c_2) + c_1)$$

1.11 problem 5(a)

1.11.1 Maple step by step solution 119

Internal problem ID [11580]

Internal file name [OUTPUT/10562_Thursday_May_18_2023_05_56_29_PM_64086885/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 1, Differential equations and their solutions. Exercises page 13

Problem number: 5(a).

ODE order: 3.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_3rd_order , _missing_x]]
```

$$y''' - 3y'' - 4y' + 12y = 0$$

The characteristic equation is

$$\lambda^3 - 3\lambda^2 - 4\lambda + 12 = 0$$

The roots of the above equation are

$$\lambda_1 = 2$$

$$\lambda_2 = 3$$

$$\lambda_3 = -2$$

Therefore the homogeneous solution is

$$y_h(x) = c_1e^{-2x} + c_2e^{2x} + c_3e^{3x}$$

The fundamental set of solutions for the homogeneous solution are the following

$$y_1 = e^{-2x}$$

$$y_2 = e^{2x}$$

$$y_3 = e^{3x}$$

Summary

The solution(s) found are the following

$$y = c_1 e^{-2x} + c_2 e^{2x} + c_3 e^{3x} \quad (1)$$

Verification of solutions

$$y = c_1 e^{-2x} + c_2 e^{2x} + c_3 e^{3x}$$

Verified OK.

1.11.1 Maple step by step solution

Let's solve

$$y''' - 3y'' - 4y' + 12y = 0$$

- Highest derivative means the order of the ODE is 3

$$y'''$$

- Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(x)$

$$y_1(x) = y$$

- Define new variable $y_2(x)$

$$y_2(x) = y'$$

- Define new variable $y_3(x)$

$$y_3(x) = y''$$

- Isolate for $y_3'(x)$ using original ODE

$$y_3'(x) = 3y_3(x) + 4y_2(x) - 12y_1(x)$$

Convert linear ODE into a system of first order ODEs

$$[y_2(x) = y_1'(x), y_3(x) = y_2'(x), y_3'(x) = 3y_3(x) + 4y_2(x) - 12y_1(x)]$$

- Define vector

$$\vec{y}(x) = \begin{bmatrix} y_1(x) \\ y_2(x) \\ y_3(x) \end{bmatrix}$$

- System to solve

$$\vec{y}'(x) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -12 & 4 & 3 \end{bmatrix} \cdot \vec{y}(x)$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -12 & 4 & 3 \end{bmatrix}$$

- Rewrite the system as

$$\vec{y}'(x) = A \cdot \vec{y}(x)$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[-2, \begin{bmatrix} \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix} \right], \left[2, \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right], \left[3, \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[-2, \begin{bmatrix} \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_1 = e^{-2x} \cdot \begin{bmatrix} \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[2, \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_2 = e^{2x} \cdot \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[3, \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_3 = e^{3x} \cdot \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix}$$

- General solution to the system of ODEs

$$\vec{y} = c_1 \vec{y}_1 + c_2 \vec{y}_2 + c_3 \vec{y}_3$$

- Substitute solutions into the general solution

$$\vec{y} = c_1 e^{-2x} \cdot \begin{bmatrix} \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix} + c_2 e^{2x} \cdot \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} + c_3 e^{3x} \cdot \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y = \frac{(4c_3 e^{5x} + 9c_2 e^{4x} + 9c_1) e^{-2x}}{36}$$

Maple trace

```

`Methods for third order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 23

```
dsolve(diff(y(x),x$3)-3*diff(y(x),x$2)-4*diff(y(x),x)+12*y(x)=0,y(x), singsol=all)
```

$$y(x) = (c_1 e^{5x} + c_2 e^{4x} + c_3) e^{-2x}$$

✓ Solution by Mathematica

Time used: 0.005 (sec). Leaf size: 29

```
DSolve[y'''[x]-3*y''[x]-4*y'[x]+12*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^{-2x} (e^{4x} (c_3 e^x + c_2) + c_1)$$

1.12 problem 5(b)

1.12.1 Maple step by step solution 125

Internal problem ID [11581]

Internal file name [OUTPUT/10563_Thursday_May_18_2023_05_56_30_PM_47063498/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 1, Differential equations and their solutions. Exercises page 13

Problem number: 5(b).

ODE order: 3.

ODE degree: 1.

The type(s) of ODE detected by this program : **"higher_order_ODE_non_constant_coefficients_of_type_Euler"**

Maple gives the following as the ode type

```
[[_3rd_order , _fully , _exact , _linear]]
```

$$x^3 y''' + 2x^2 y'' - 10y'x - 8y = 0$$

This is Euler ODE of higher order. Let $y = x^\lambda$. Hence

$$y' = \lambda x^{\lambda-1}$$

$$y'' = \lambda(\lambda - 1) x^{\lambda-2}$$

$$y''' = \lambda(\lambda - 1)(\lambda - 2) x^{\lambda-3}$$

Substituting these back into

$$x^3 y''' + 2x^2 y'' - 10y'x - 8y = 0$$

gives

$$-10\lambda x^\lambda + 2x^2 \lambda(\lambda - 1) x^{\lambda-2} + x^3 \lambda(\lambda - 1)(\lambda - 2) x^{\lambda-3} - 8x^\lambda = 0$$

Which simplifies to

$$-10\lambda x^\lambda + 2\lambda(\lambda - 1) x^\lambda + \lambda(\lambda - 1)(\lambda - 2) x^\lambda - 8x^\lambda = 0$$

And since $x^\lambda \neq 0$ then dividing through by x^λ , the above becomes

$$-10\lambda + 2\lambda(\lambda - 1) + \lambda(\lambda - 1)(\lambda - 2) - 8 = 0$$

Simplifying gives the characteristic equation as

$$\lambda^3 - \lambda^2 - 10\lambda - 8 = 0$$

Solving the above gives the following roots

$$\lambda_1 = 4$$

$$\lambda_2 = -2$$

$$\lambda_3 = -1$$

This table summarises the result

root	multiplicity	type of root
-1	1	real root
-2	1	real root
4	1	real root

The solution is generated by going over the above table. For each real root λ of multiplicity one generates a $c_1 x^\lambda$ basis solution. Each real root of multiplicity two, generates $c_1 x^\lambda$ and $c_2 x^\lambda \ln(x)$ basis solutions. Each real root of multiplicity three, generates $c_1 x^\lambda$ and $c_2 x^\lambda \ln(x)$ and $c_3 x^\lambda \ln(x)^2$ basis solutions, and so on. Each complex root $\alpha \pm i\beta$ of multiplicity one generates $x^\alpha (c_1 \cos(\beta \ln(x)) + c_2 \sin(\beta \ln(x)))$ basis solutions. And each complex root $\alpha \pm i\beta$ of multiplicity two generates $\ln(x) x^\alpha (c_1 \cos(\beta \ln(x)) + c_2 \sin(\beta \ln(x)))$ basis solutions. And each complex root $\alpha \pm i\beta$ of multiplicity three generates $\ln(x)^2 x^\alpha (c_1 \cos(\beta \ln(x)) + c_2 \sin(\beta \ln(x)))$ basis solutions. And so on. Using the above show that the solution is

$$y = \frac{c_1}{x} + \frac{c_2}{x^2} + c_3 x^4$$

The fundamental set of solutions for the homogeneous solution are the following

$$y_1 = \frac{1}{x}$$

$$y_2 = \frac{1}{x^2}$$

$$y_3 = x^4$$

Summary

The solution(s) found are the following

$$y = \frac{c_1}{x} + \frac{c_2}{x^2} + c_3x^4 \quad (1)$$

Verification of solutions

$$y = \frac{c_1}{x} + \frac{c_2}{x^2} + c_3x^4$$

Verified OK.

1.12.1 Maple step by step solution

Let's solve

$$x^3y''' + 2y''x^2 - 10y'x - 8y = 0$$

- Highest derivative means the order of the ODE is 3

$$y'''$$

- Isolate 3rd derivative

$$y''' = \frac{8y}{x^3} - \frac{2(y''x - 5y')}{x^2}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y''' + \frac{2y''}{x} - \frac{10y'}{x^2} - \frac{8y}{x^3} = 0$$

- Multiply by denominators of the ODE

$$x^3y''' + 2y''x^2 - 10y'x - 8y = 0$$

- Make a change of variables

$$t = \ln(x)$$

- Substitute the change of variables back into the ODE

- Calculate the 1st derivative of y with respect to x , using the chain rule

$$y' = \left(\frac{d}{dt}y(t)\right) t'(x)$$

- Compute derivative

$$y' = \frac{\frac{d}{dt}y(t)}{x}$$

- Calculate the 2nd derivative of y with respect to x , using the chain rule

$$y'' = \left(\frac{d^2}{dt^2}y(t)\right) t'(x)^2 + t''(x) \left(\frac{d}{dt}y(t)\right)$$

- Compute derivative

$$y'' = \frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2}$$

- Calculate the 3rd derivative of y with respect to x , using the chain rule

$$y''' = \left(\frac{d^3}{dt^3}y(t) \right) t'(x)^3 + 3t'(x)t''(x) \left(\frac{d^2}{dt^2}y(t) \right) + t'''(x) \left(\frac{d}{dt}y(t) \right)$$

- Compute derivative

$$y''' = \frac{\frac{d^3}{dt^3}y(t)}{x^3} - \frac{3\left(\frac{d^2}{dt^2}y(t)\right)}{x^3} + \frac{2\left(\frac{d}{dt}y(t)\right)}{x^3}$$

Substitute the change of variables back into the ODE

$$x^3 \left(\frac{\frac{d^3}{dt^3}y(t)}{x^3} - \frac{3\left(\frac{d^2}{dt^2}y(t)\right)}{x^3} + \frac{2\left(\frac{d}{dt}y(t)\right)}{x^3} \right) + 2 \left(\frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2} \right) x^2 - 10 \frac{d}{dt}y(t) - 8y(t) = 0$$

- Simplify

$$\frac{d^3}{dt^3}y(t) - \frac{d^2}{dt^2}y(t) - 10 \frac{d}{dt}y(t) - 8y(t) = 0$$

- Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(t)$

$$y_1(t) = y(t)$$

- Define new variable $y_2(t)$

$$y_2(t) = \frac{d}{dt}y(t)$$

- Define new variable $y_3(t)$

$$y_3(t) = \frac{d^2}{dt^2}y(t)$$

- Isolate for $\frac{d}{dt}y_3(t)$ using original ODE

$$\frac{d}{dt}y_3(t) = y_3(t) + 10y_2(t) + 8y_1(t)$$

Convert linear ODE into a system of first order ODEs

$$\left[y_2(t) = \frac{d}{dt}y_1(t), y_3(t) = \frac{d}{dt}y_2(t), \frac{d}{dt}y_3(t) = y_3(t) + 10y_2(t) + 8y_1(t) \right]$$

- Define vector

$$\vec{y}(t) = \begin{bmatrix} y_1(t) \\ y_2(t) \\ y_3(t) \end{bmatrix}$$

- System to solve

$$\frac{d}{dt}\vec{y}(t) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 8 & 10 & 1 \end{bmatrix} \cdot \vec{y}(t)$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 8 & 10 & 1 \end{bmatrix}$$

- Rewrite the system as

$$\frac{d}{dt}\vec{y}(t) = A \cdot \vec{y}(t)$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[-2, \begin{bmatrix} \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix} \right], \left[-1, \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \right], \left[4, \begin{bmatrix} \frac{1}{16} \\ \frac{1}{4} \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[-2, \begin{bmatrix} \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_1 = e^{-2t} \cdot \begin{bmatrix} \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[-1, \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_2 = e^{-t} \cdot \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[4, \begin{bmatrix} \frac{1}{16} \\ \frac{1}{4} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_3 = e^{4t} \cdot \begin{bmatrix} \frac{1}{16} \\ \frac{1}{4} \\ 1 \end{bmatrix}$$

- General solution to the system of ODEs

$$\vec{y} = c_1 \vec{y}_1 + c_2 \vec{y}_2 + c_3 \vec{y}_3$$

- Substitute solutions into the general solution

$$\vec{y} = c_1 e^{-2t} \cdot \begin{bmatrix} \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix} + c_2 e^{-t} \cdot \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} + c_3 e^{4t} \cdot \begin{bmatrix} \frac{1}{16} \\ \frac{1}{4} \\ 1 \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y(t) = \frac{(c_3 e^{6t} + 16c_2 e^t + 4c_1) e^{-2t}}{16}$$

- Change variables back using $t = \ln(x)$

$$y = \frac{c_3 x^6 + 16c_2 x + 4c_1}{16x^2}$$

Maple trace

```
`Methods for third order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
checking if the LODE is of Euler type  
<- LODE of Euler type successful`
```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 18

```
dsolve(x^3*diff(y(x),x$3)+2*x^2*diff(y(x),x$2)-10*x*diff(y(x),x)-8*y(x)=0,y(x), singsol=all)
```

$$y(x) = \frac{c_1 x^6 + c_2 x + c_3}{x^2}$$

✓ Solution by Mathematica

Time used: 0.006 (sec). Leaf size: 22

```
DSolve[x^3*y'''[x]+2*x^2*y''[x]-10*x*y'[x]-8*y[x]==0,y[x],x,IncludeSingularSolutions -> True
```

$$y(x) \rightarrow \frac{c_3 x^6 + c_2 x + c_1}{x^2}$$

1.13 problem 6(a)

1.13.1 Solving as linear ode	130
1.13.2 Solving as first order ode lie symmetry lookup ode	132
1.13.3 Solving as exact ode	136
1.13.4 Maple step by step solution	140

Internal problem ID [11582]

Internal file name [OUTPUT/10564_Thursday_May_18_2023_05_56_31_PM_784968/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 1, Differential equations and their solutions. Exercises page 13

Problem number: 6(a).

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "linear", "exactWithIntegrationFactor", "first_order_ode_lie_symmetry_lookup"

Maple gives the following as the ode type

```
[[_linear, `class A`]]
```

$$y' + 2y = 6e^x + 4xe^{-2x}$$

1.13.1 Solving as linear ode

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = 2$$

$$q(x) = (6e^{3x} + 4x)e^{-2x}$$

Hence the ode is

$$y' + 2y = (6e^{3x} + 4x)e^{-2x}$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int 2dx} \\ &= e^{2x}\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu y) &= (\mu) ((6e^{3x} + 4x) e^{-2x}) \\ \frac{d}{dx}(y e^{2x}) &= (e^{2x}) ((6e^{3x} + 4x) e^{-2x}) \\ d(y e^{2x}) &= (6e^{3x} + 4x) dx\end{aligned}$$

Integrating gives

$$\begin{aligned}y e^{2x} &= \int 6e^{3x} + 4x dx \\ y e^{2x} &= 2x^2 + 2e^{3x} + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = e^{2x}$ results in

$$y = e^{-2x} (2x^2 + 2e^{3x}) + c_1 e^{-2x}$$

which simplifies to

$$y = (2e^{3x} + 2x^2 + c_1) e^{-2x}$$

Summary

The solution(s) found are the following

$$y = (2e^{3x} + 2x^2 + c_1) e^{-2x} \tag{1}$$

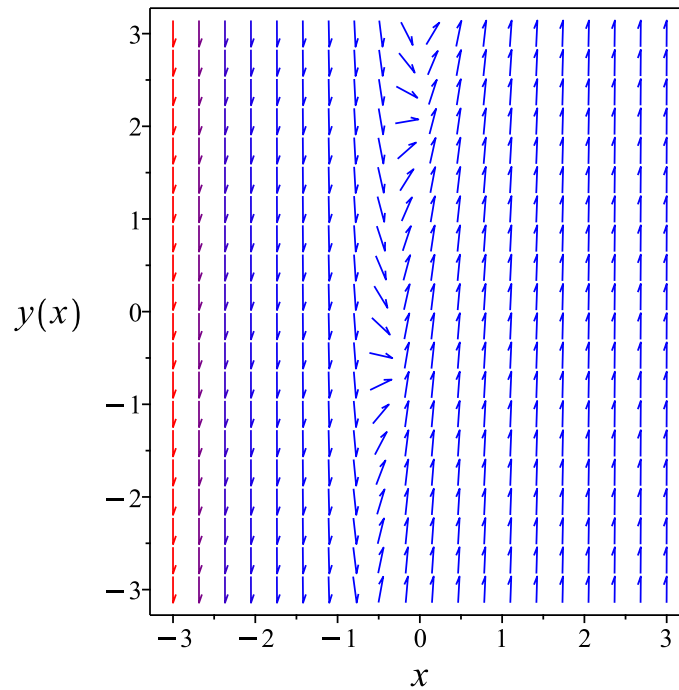


Figure 25: Slope field plot

Verification of solutions

$$y = (2e^{3x} + 2x^2 + c_1)e^{-2x}$$

Verified OK.

1.13.2 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = -2y + 6e^x + 4xe^{-2x}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 25: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= e^{-2x}\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{e^{-2x}} dy \end{aligned}$$

Which results in

$$S = y e^{2x}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -2y + 6e^x + 4xe^{-2x}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= 2y e^{2x} \\ S_y &= e^{2x} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 6e^{3x} + 4x \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 6e^{3R} + 4R$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by

integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = 2R^2 + 2e^{3R} + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$y e^{2x} = 2e^{3x} + 2x^2 + c_1$$

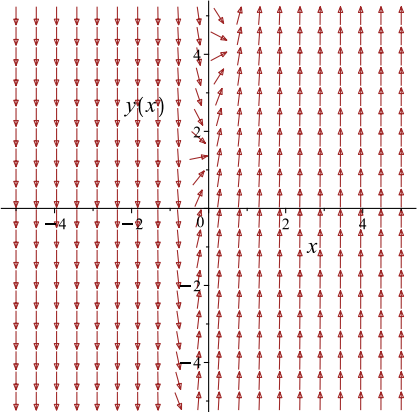
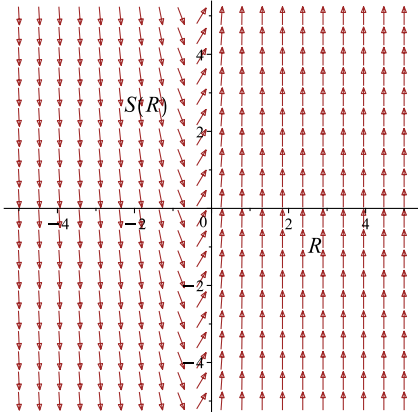
Which simplifies to

$$y e^{2x} = 2e^{3x} + 2x^2 + c_1$$

Which gives

$$y = (2e^{3x} + 2x^2 + c_1) e^{-2x}$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -2y + 6e^x + 4xe^{-2x}$ 	$R = x$ $S = y e^{2x}$	$\frac{dS}{dR} = 6e^{3R} + 4R$ 

Summary

The solution(s) found are the following

$$y = (2e^{3x} + 2x^2 + c_1) e^{-2x} \quad (1)$$

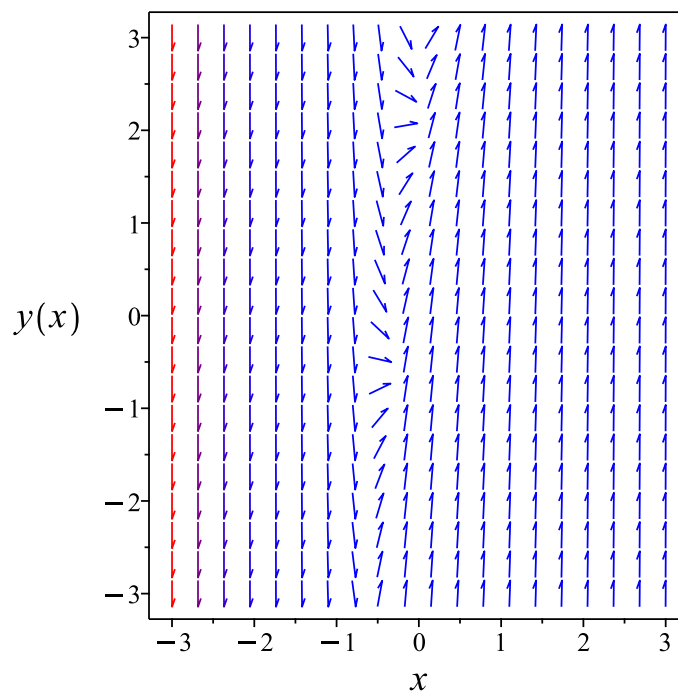


Figure 26: Slope field plot

Verification of solutions

$$y = (2e^{3x} + 2x^2 + c_1)e^{-2x}$$

Verified OK.

1.13.3 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx}\phi(x, y) = 0$$

Hence

$$\frac{\partial\phi}{\partial x} + \frac{\partial\phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (1A)$$

Therefore

$$\begin{aligned}dy &= (-2y + 6e^x + 4xe^{-2x}) dx \\ (2y - 6e^x - 4xe^{-2x}) dx + dy &= 0\end{aligned} \quad (2A)$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= 2y - 6e^x - 4xe^{-2x} \\ N(x, y) &= 1\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y} (2y - 6e^x - 4xe^{-2x}) \\ &= 2\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x} (1) \\ &= 0\end{aligned}$$

Since $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$\begin{aligned} A &= \frac{1}{N} \left(\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} \right) \\ &= 1((2) - (0)) \\ &= 2 \end{aligned}$$

Since A does not depend on y , then it can be used to find an integrating factor. The integrating factor μ is

$$\begin{aligned} \mu &= e^{\int A dx} \\ &= e^{\int 2 dx} \end{aligned}$$

The result of integrating gives

$$\begin{aligned} \mu &= e^{2x} \\ &= e^{2x} \end{aligned}$$

M and N are multiplied by this integrating factor, giving new M and new N which are called \bar{M} and \bar{N} for now so not to confuse them with the original M and N .

$$\begin{aligned} \bar{M} &= \mu M \\ &= e^{2x} (2y - 6e^x - 4xe^{-2x}) \\ &= -6e^{3x} + 2ye^{2x} - 4x \end{aligned}$$

And

$$\begin{aligned} \bar{N} &= \mu N \\ &= e^{2x}(1) \\ &= e^{2x} \end{aligned}$$

Now a modified ODE is obtained from the original ODE, which is exact and can be solved. The modified ODE is

$$\begin{aligned} \bar{M} + \bar{N} \frac{dy}{dx} &= 0 \\ (-6e^{3x} + 2ye^{2x} - 4x) + (e^{2x}) \frac{dy}{dx} &= 0 \end{aligned}$$

The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = \bar{M} \tag{1}$$

$$\frac{\partial \phi}{\partial y} = \bar{N} \tag{2}$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int \overline{M} dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int -6e^{3x} + 2ye^{2x} - 4x dx \\ \phi &= ye^{2x} - 2x^2 - 2e^{3x} + f(y)\end{aligned}\quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = e^{2x} + f'(y)\quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = e^{2x}$. Therefore equation (4) becomes

$$e^{2x} = e^{2x} + f'(y)\quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 0$$

Therefore

$$f(y) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(y)$ into equation (3) gives ϕ

$$\phi = ye^{2x} - 2x^2 - 2e^{3x} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = ye^{2x} - 2x^2 - 2e^{3x}$$

The solution becomes

$$y = (2e^{3x} + 2x^2 + c_1)e^{-2x}$$

Summary

The solution(s) found are the following

$$y = (2e^{3x} + 2x^2 + c_1)e^{-2x}\quad (1)$$

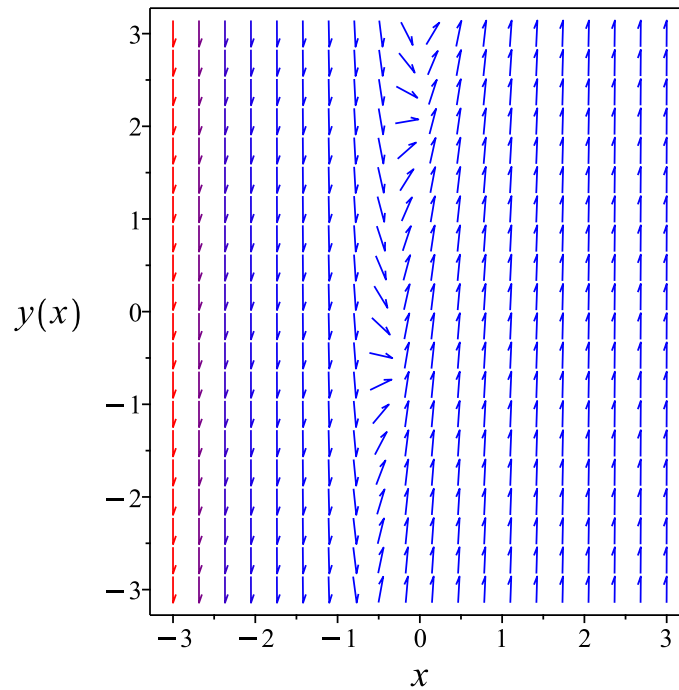


Figure 27: Slope field plot

Verification of solutions

$$y = (2e^{3x} + 2x^2 + c_1)e^{-2x}$$

Verified OK.

1.13.4 Maple step by step solution

Let's solve

$$y' + 2y = 6e^x + 4xe^{-2x}$$

- Highest derivative means the order of the ODE is 1

$$y'$$

- Isolate the derivative

$$y' = -2y + 6e^x + 4xe^{-2x}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE

$$y' + 2y = 6e^x + 4xe^{-2x}$$

- The ODE is linear; multiply by an integrating factor $\mu(x)$

$$\mu(x)(y' + 2y) = \mu(x)(6e^x + 4xe^{-2x})$$

- Assume the lhs of the ODE is the total derivative $\frac{d}{dx}(\mu(x) y)$

$$\mu(x) (y' + 2y) = \mu'(x) y + \mu(x) y'$$
- Isolate $\mu'(x)$

$$\mu'(x) = 2\mu(x)$$
- Solve to find the integrating factor

$$\mu(x) = e^{2x}$$
- Integrate both sides with respect to x

$$\int \left(\frac{d}{dx}(\mu(x) y) \right) dx = \int \mu(x) (6e^x + 4xe^{-2x}) dx + c_1$$
- Evaluate the integral on the lhs

$$\mu(x) y = \int \mu(x) (6e^x + 4xe^{-2x}) dx + c_1$$
- Solve for y

$$y = \frac{\int \mu(x)(6e^x + 4xe^{-2x}) dx + c_1}{\mu(x)}$$
- Substitute $\mu(x) = e^{2x}$

$$y = \frac{\int e^{2x}(6e^x + 4xe^{-2x}) dx + c_1}{e^{2x}}$$
- Evaluate the integrals on the rhs

$$y = \frac{2(e^x)^3 + 2x^2 + c_1}{e^{2x}}$$
- Simplify

$$y = (2e^{3x} + 2x^2 + c_1) e^{-2x}$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
<- 1st order linear successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 22

```
dsolve(diff(y(x),x)+2*y(x)=6*exp(x)+4*x*exp(-2*x),y(x), singsol=all)
```

$$y(x) = (2x^2 + 2e^{3x} + c_1) e^{-2x}$$

✓ Solution by Mathematica

Time used: 0.129 (sec). Leaf size: 26

```
DSolve[y'[x]+2*y[x]==6*Exp[x]+4*x*Exp[-2*x],y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^{-2x} (2x^2 + 2e^{3x} + c_1)$$

1.14 problem 6(b)

1.14.1 Solving as second order linear constant coeff ode	143
1.14.2 Solving as linear second order ode solved by an integrating factor ode	146
1.14.3 Solving using Kovacic algorithm	148
1.14.4 Maple step by step solution	153

Internal problem ID [11583]

Internal file name [OUTPUT/10565_Thursday_May_18_2023_05_56_32_PM_79597876/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 1, Differential equations and their solutions. Exercises page 13

Problem number: 6(b).

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff", "linear_second_order_ode_solved_by_an_integrating_factor"

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' - 4y' + 4y = -8 \sin(2x)$$

1.14.1 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = -4, C = 4, f(x) = -8 \sin(2x)$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' - 4y' + 4y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = -4, C = 4$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} - 4\lambda e^{\lambda x} + 4e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 - 4\lambda + 4 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = -4, C = 4$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{4}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{(-4)^2 - (4)(1)(4)} \\ &= 2 \end{aligned}$$

Hence this is the case of a double root $\lambda_{1,2} = -2$. Therefore the solution is

$$y = c_1 e^{2x} + c_2 e^{2x} x \quad (1)$$

Therefore the homogeneous solution y_h is

$$y_h = c_1 e^{2x} + c_2 e^{2x} x$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$-8 \sin(2x)$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{\cos(2x), \sin(2x)\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^{2x} x, e^{2x}\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1 \cos(2x) + A_2 \sin(2x)$$

The unknowns $\{A_1, A_2\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$8A_1 \sin(2x) - 8A_2 \cos(2x) = -8 \sin(2x)$$

Solving for the unknowns by comparing coefficients results in

$$[A_1 = -1, A_2 = 0]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = -\cos(2x)$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 e^{2x} + c_2 e^{2x} x) + (-\cos(2x)) \end{aligned}$$

Which simplifies to

$$y = e^{2x}(c_2 x + c_1) - \cos(2x)$$

Summary

The solution(s) found are the following

$$y = e^{2x}(c_2 x + c_1) - \cos(2x) \tag{1}$$

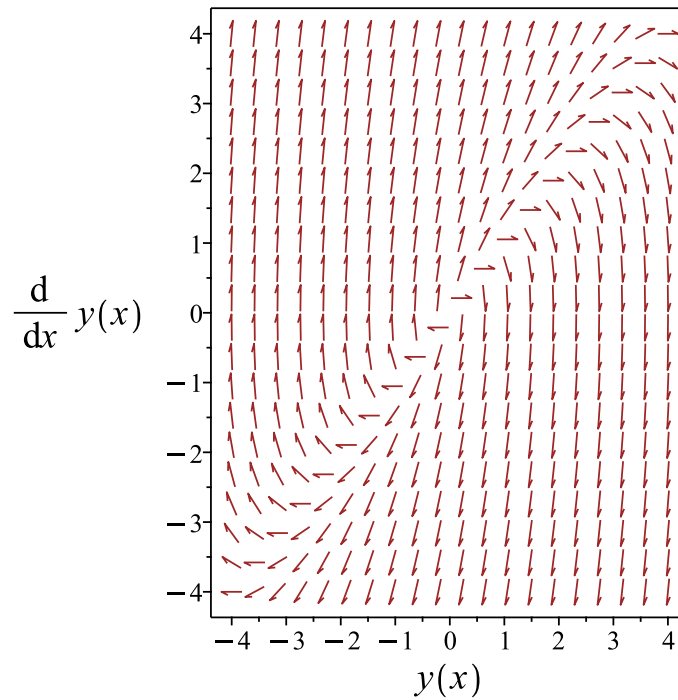


Figure 28: Slope field plot

Verification of solutions

$$y = e^{2x}(c_2x + c_1) - \cos(2x)$$

Verified OK.

1.14.2 Solving as linear second order ode solved by an integrating factor ode

The ode satisfies this form

$$y'' + p(x)y' + \frac{(p(x))^2 + p'(x)}{2}y = f(x)$$

Where $p(x) = -4$. Therefore, there is an integrating factor given by

$$\begin{aligned} M(x) &= e^{\frac{1}{2} \int p dx} \\ &= e^{\int -4 dx} \\ &= e^{-2x} \end{aligned}$$

Multiplying both sides of the ODE by the integrating factor $M(x)$ makes the left side of the ODE a complete differential

$$(M(x)y)'' = -8e^{-2x} \sin(2x)$$

$$(e^{-2x}y)'' = -8e^{-2x} \sin(2x)$$

Integrating once gives

$$(e^{-2x}y)' = 2e^{-2x}(\cos(2x) + \sin(2x)) + c_1$$

Integrating again gives

$$(e^{-2x}y) = c_1x - e^{-2x} \cos(2x) + c_2$$

Hence the solution is

$$y = \frac{c_1x - e^{-2x} \cos(2x) + c_2}{e^{-2x}}$$

Or

$$y = e^{2x}c_1x + c_2e^{2x} - 2\cos(x)^2 + 1$$

Summary

The solution(s) found are the following

$$y = e^{2x}c_1x + c_2e^{2x} - 2\cos(x)^2 + 1 \quad (1)$$

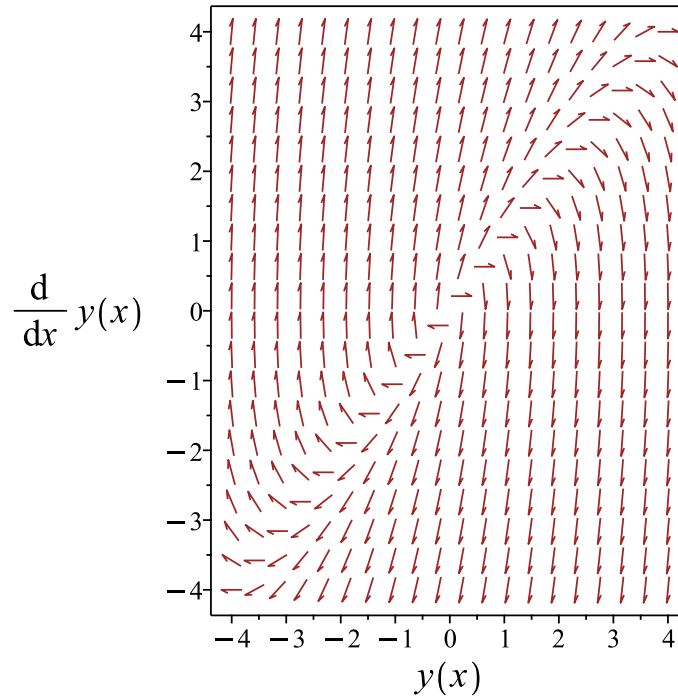


Figure 29: Slope field plot

Verification of solutions

$$y = e^{2x}c_1x + c_2e^{2x} - 2\cos(x)^2 + 1$$

Verified OK.

1.14.3 Solving using Kovacic algorithm

Writing the ode as

$$y'' - 4y' + 4y = 0 \tag{1}$$

$$Ay'' + By' + Cy = 0 \tag{2}$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= -4 \\ C &= 4 \end{aligned} \tag{3}$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{0}{1} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 0 \\ t &= 1 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = 0 \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 28: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - -\infty \\ &= \infty \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is *infinity* then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = 0$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = 1$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-4}{1} dx} \\ &= z_1 e^{2x} \\ &= z_1 (e^{2x}) \end{aligned}$$

Which simplifies to

$$y_1 = e^{2x}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{-4}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{4x}}{(y_1)^2} dx \\ &= y_1(x) \end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (e^{2x}) + c_2 (e^{2x}(x))\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' - 4y' + 4y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1 e^{2x} + c_2 e^{2x} x$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$-8 \sin(2x)$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{\cos(2x), \sin(2x)\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^{2x} x, e^{2x}\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1 \cos(2x) + A_2 \sin(2x)$$

The unknowns $\{A_1, A_2\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$8A_1 \sin(2x) - 8A_2 \cos(2x) = -8 \sin(2x)$$

Solving for the unknowns by comparing coefficients results in

$$[A_1 = -1, A_2 = 0]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = -\cos(2x)$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 e^{2x} + c_2 e^{-2x}) + (-\cos(2x)) \end{aligned}$$

Which simplifies to

$$y = e^{2x}(c_2 x + c_1) - \cos(2x)$$

Summary

The solution(s) found are the following

$$y = e^{2x}(c_2 x + c_1) - \cos(2x) \tag{1}$$

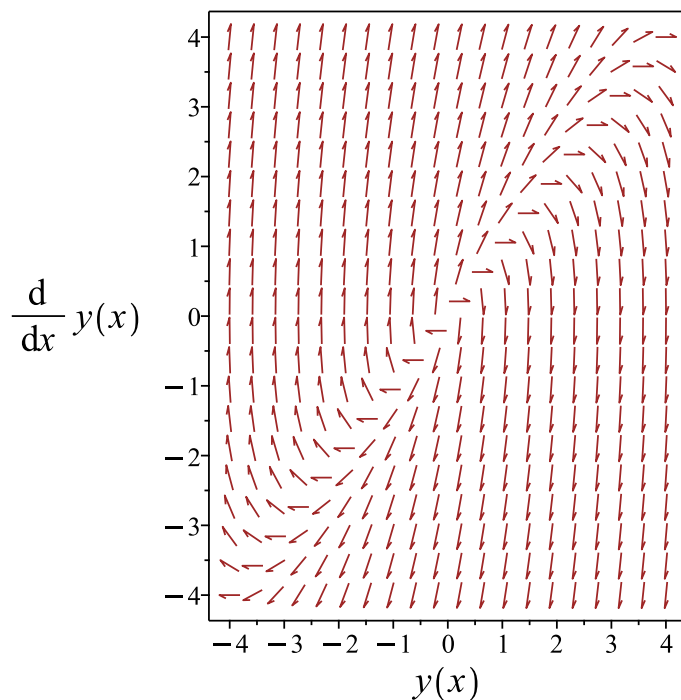


Figure 30: Slope field plot

Verification of solutions

$$y = e^{2x}(c_2x + c_1) - \cos(2x)$$

Verified OK.

1.14.4 Maple step by step solution

Let's solve

$$y'' - 4y' + 4y = -8 \sin(2x)$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of homogeneous ODE

$$r^2 - 4r + 4 = 0$$

- Factor the characteristic polynomial

$$(r - 2)^2 = 0$$

- Root of the characteristic polynomial

$$r = 2$$

- 1st solution of the homogeneous ODE

$$y_1(x) = e^{2x}$$

- Repeated root, multiply $y_1(x)$ by x to ensure linear independence

$$y_2(x) = e^{2x}x$$

- General solution of the ODE

$$y = c_1y_1(x) + c_2y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = c_1e^{2x} + c_2e^{2x}x + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = -8 \sin(2x) \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} e^{2x} & e^{2x}x \\ 2e^{2x} & 2e^{2x}x + e^{2x} \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = e^{4x}$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = 8e^{2x} \left(\int \sin(2x) x e^{-2x} dx - x \left(\int e^{-2x} \sin(2x) dx \right) \right)$$

- Compute integrals

$$y_p(x) = -\cos(2x)$$

- Substitute particular solution into general solution to ODE

$$y = c_2 e^{2x} x + c_1 e^{2x} - \cos(2x)$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
trying a double symmetry of the form [xi=0, eta=F(x)]
-> Try solving first the homogeneous part of the ODE
    checking if the LODE has constant coefficients
    <- constant coefficients successful
<- solving first the homogeneous part of the ODE successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 21

```
dsolve(diff(y(x),x$2)-4*diff(y(x),x)+4*y(x)=-8*sin(2*x),y(x), singsol=all)
```

$$y(x) = (c_1 x + c_2) e^{2x} - \cos(2x)$$

✓ Solution by Mathematica

Time used: 0.039 (sec). Leaf size: 25

```
DSolve[y''[x]-4*y'[x]+4*y[x]==-8*Sin[2*x],y[x],x,IncludeSingularSolutions->True]
```

$$y(x) \rightarrow -\cos(2x) + e^{2x}(c_2 x + c_1)$$

1.15 problem 7(a)

1.15.1 Maple step by step solution 156

Internal problem ID [11584]

Internal file name [OUTPUT/10566_Thursday_May_18_2023_05_56_33_PM_7548041/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 1, Differential equations and their solutions. Exercises page 13

Problem number: 7(a).

ODE order: 1.

ODE degree: 2.

The type(s) of ODE detected by this program : "**quadrature**"

Maple gives the following as the ode type

[_quadrature]

$$y'^2 - 4y = 0$$

Solving the given ode for y' results in 2 differential equations to solve. Each one of these will generate a solution. The equations generated are

$$y' = 2\sqrt{y} \quad (1)$$

$$y' = -2\sqrt{y} \quad (2)$$

Now each one of the above ODE is solved.

Solving equation (1)

Integrating both sides gives

$$\int \frac{1}{2\sqrt{y}} dy = \int dx$$
$$\sqrt{y} = x + c_1$$

Summary

The solution(s) found are the following

$$\sqrt{y} = x + c_1 \quad (1)$$

Verification of solutions

$$\sqrt{y} = x + c_1$$

Verified OK.

Solving equation (2)

Integrating both sides gives

$$\int -\frac{1}{2\sqrt{y}} dy = \int dx$$
$$-\sqrt{y} = x + c_2$$

Summary

The solution(s) found are the following

$$-\sqrt{y} = x + c_2 \tag{1}$$

Verification of solutions

$$-\sqrt{y} = x + c_2$$

Verified OK.

1.15.1 Maple step by step solution

Let's solve

$$y'^2 - 4y = 0$$

- Highest derivative means the order of the ODE is 1

$$y'$$

- Separate variables

$$\frac{y'}{\sqrt{y}} = 2$$

- Integrate both sides with respect to x

$$\int \frac{y'}{\sqrt{y}} dx = \int 2 dx + c_1$$

- Evaluate integral

$$2\sqrt{y} = 2x + c_1$$

- Solve for y

$$y = \frac{1}{4}c_1^2 + c_1x + x^2$$

Maple trace

```
`Methods for first order ODEs:
*** Sublevel 2 ***
Methods for first order ODEs:
-> Solving 1st order ODE of high degree, 1st attempt
trying 1st order WeierstrassP solution for high degree ODE
trying 1st order WeierstrassPPrime solution for high degree ODE
trying 1st order JacobiSN solution for high degree ODE
trying 1st order ODE linearizable_by_differentiation
trying differential order: 1; missing variables
<- differential order: 1; missing x successful`
```

✓ Solution by Maple

Time used: 0.078 (sec). Leaf size: 15

```
dsolve(diff(y(x),x)^2-4*y(x)=0,y(x), singsol=all)
```

$$y(x) = 0$$
$$y(x) = (x - c_1)^2$$

✓ Solution by Mathematica

Time used: 0.079 (sec). Leaf size: 38

```
DSolve[(y'[x])^2-4*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{1}{4}(-2x + c_1)^2$$
$$y(x) \rightarrow \frac{1}{4}(2x + c_1)^2$$
$$y(x) \rightarrow 0$$

2 Chapter 1, section 1.3. Exercises page 22

2.1	problem 1	159
2.2	problem 2(a)	169
2.3	problem 2(b)	183
2.4	problem 3(a)	197
2.5	problem 4(a)	207
2.6	problem 4(b)	217
2.7	problem 4(c)	227
2.8	problem 5	238
2.9	problem 6(a)	247
2.10	problem 6(b)	259
2.11	problem 8	273

2.1 problem 1

2.1.1	Existence and uniqueness analysis	159
2.1.2	Solving as second order linear constant coeff ode	160
2.1.3	Solving using Kovacic algorithm	162
2.1.4	Maple step by step solution	166

Internal problem ID [11585]

Internal file name [OUTPUT/10567_Thursday_May_18_2023_05_56_33_PM_90907946/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 1, section 1.3. Exercises page 22

Problem number: 1.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"kovacic", "second_order_linear_constant_coeff"**

Maple gives the following as the ode type

```
[[_2nd_order , _missing_x]]
```

$$y'' + y' - 6y = 0$$

With initial conditions

$$[y(0) = 6, y'(0) = 2]$$

2.1.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$p(x) = 1$$

$$q(x) = -6$$

$$F = 0$$

Hence the ode is

$$y'' + y' - 6y = 0$$

The domain of $p(x) = 1$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = -6$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

2.1.2 Solving as second order linear constant coeff ode

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 1, C = -6$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + \lambda e^{\lambda x} - 6 e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + \lambda - 6 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 1, C = -6$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{-1}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{1^2 - (4)(1)(-6)} \\ &= -\frac{1}{2} \pm \frac{5}{2} \end{aligned}$$

Hence

$$\lambda_1 = -\frac{1}{2} + \frac{5}{2}$$

$$\lambda_2 = -\frac{1}{2} - \frac{5}{2}$$

Which simplifies to

$$\lambda_1 = 2$$

$$\lambda_2 = -3$$

Since roots are real and distinct, then the solution is

$$y = c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x}$$

$$y = c_1 e^{(2)x} + c_2 e^{(-3)x}$$

Or

$$y = c_1 e^{2x} + c_2 e^{-3x}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{2x} + c_2 e^{-3x} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 6$ and $x = 0$ in the above gives

$$6 = c_1 + c_2 \quad (1A)$$

Taking derivative of the solution gives

$$y' = 2c_1 e^{2x} - 3c_2 e^{-3x}$$

substituting $y' = 2$ and $x = 0$ in the above gives

$$2 = 2c_1 - 3c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 4$$

$$c_2 = 2$$

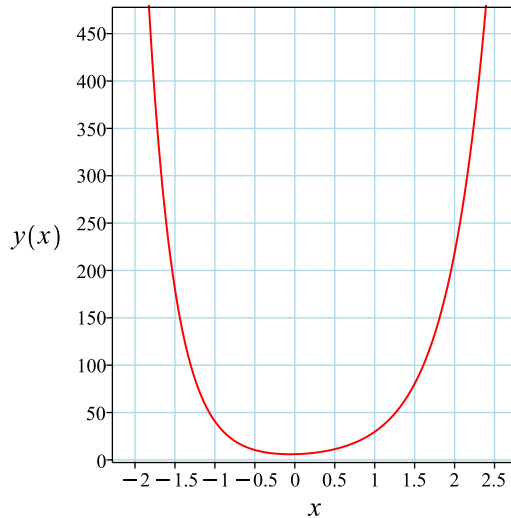
Substituting these values back in above solution results in

$$y = 4e^{2x} + 2e^{-3x}$$

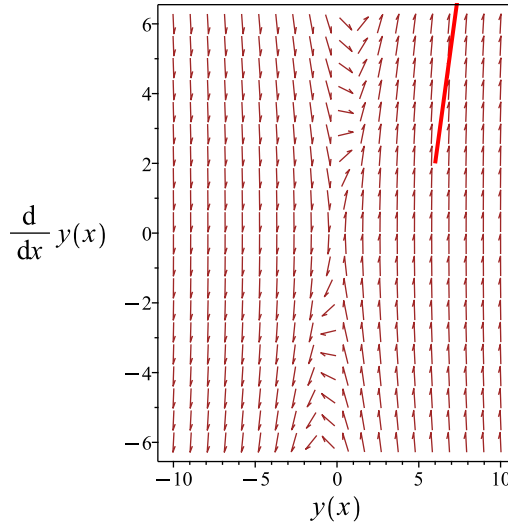
Summary

The solution(s) found are the following

$$y = 4e^{2x} + 2e^{-3x} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = 4e^{2x} + 2e^{-3x}$$

Verified OK.

2.1.3 Solving using Kovacic algorithm

Writing the ode as

$$y'' + y' - 6y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$A = 1$$

$$B = 1$$

$$C = -6$$

(3)

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{25}{4} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 25 \\ t &= 4 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = \frac{25z(x)}{4} \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 31: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = \frac{25}{4}$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = e^{-\frac{5x}{2}}$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{1}{1} dx} \\ &= z_1 e^{-\frac{x}{2}} \\ &= z_1 \left(e^{-\frac{x}{2}} \right) \end{aligned}$$

Which simplifies to

$$y_1 = e^{-3x}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{1}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{-x}}{(y_1)^2} dx \\ &= y_1 \left(\frac{e^{5x}}{5} \right) \end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (e^{-3x}) + c_2 \left(e^{-3x} \left(\frac{e^{5x}}{5} \right) \right)\end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{-3x} + \frac{c_2 e^{2x}}{5} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 6$ and $x = 0$ in the above gives

$$6 = c_1 + \frac{c_2}{5} \quad (1A)$$

Taking derivative of the solution gives

$$y' = -3c_1 e^{-3x} + \frac{2c_2 e^{2x}}{5}$$

substituting $y' = 2$ and $x = 0$ in the above gives

$$2 = -3c_1 + \frac{2c_2}{5} \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 2$$

$$c_2 = 20$$

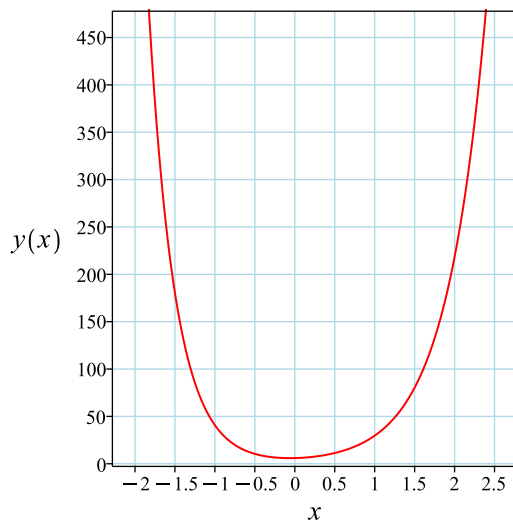
Substituting these values back in above solution results in

$$y = 4e^{2x} + 2e^{-3x}$$

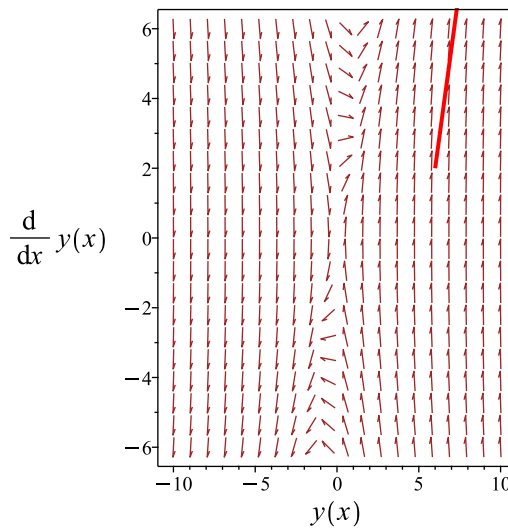
Summary

The solution(s) found are the following

$$y = 4e^{2x} + 2e^{-3x} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = 4e^{2x} + 2e^{-3x}$$

Verified OK.

2.1.4 Maple step by step solution

Let's solve

$$\left[y'' + y' - 6y = 0, y(0) = 6, y' \Big|_{\{x=0\}} = 2 \right]$$

- Highest derivative means the order of the ODE is 2
 y''
- Characteristic polynomial of ODE
 $r^2 + r - 6 = 0$
- Factor the characteristic polynomial
 $(r + 3)(r - 2) = 0$
- Roots of the characteristic polynomial
 $r = (-3, 2)$
- 1st solution of the ODE

$$y_1(x) = e^{-3x}$$

- 2nd solution of the ODE

$$y_2(x) = e^{2x}$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x)$$

- Substitute in solutions

$$y = c_1 e^{-3x} + c_2 e^{2x}$$

- Check validity of solution $y = c_1 e^{-3x} + c_2 e^{2x}$

- Use initial condition $y(0) = 6$

$$6 = c_1 + c_2$$

- Compute derivative of the solution

$$y' = -3c_1 e^{-3x} + 2c_2 e^{2x}$$

- Use the initial condition $y' \Big|_{\{x=0\}} = 2$

$$2 = -3c_1 + 2c_2$$

- Solve for c_1 and c_2

$$\{c_1 = 2, c_2 = 4\}$$

- Substitute constant values into general solution and simplify

$$y = (4e^{5x} + 2)e^{-3x}$$

- Solution to the IVP

$$y = (4e^{5x} + 2)e^{-3x}$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
<- constant coefficients successful`

```


✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 17

```
dsolve([diff(y(x),x$2)+diff(y(x),x)-6*y(x)=0,y(0) = 6, D(y)(0) = 2],y(x), singsol=all)
```

$$y(x) = (4e^{5x} + 2)e^{-3x}$$

✓ Solution by Mathematica

Time used: 0.024 (sec). Leaf size: 20

```
DSolve[{y''[x]+y'[x]-6*y[x]==0,{y[0]==6,y'[0]==2}},y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^{-3x}(4e^{5x} + 2)$$

2.2 problem 2(a)

2.2.1	Existence and uniqueness analysis	169
2.2.2	Solving as linear ode	170
2.2.3	Solving as first order ode lie symmetry lookup ode	172
2.2.4	Solving as exact ode	176
2.2.5	Maple step by step solution	180

Internal problem ID [11586]

Internal file name [OUTPUT/10568_Thursday_May_18_2023_05_56_34_PM_55001789/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 1, section 1.3. Exercises page 22

Problem number: 2(a).

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**linear**", "**exactWithIntegrationFactor**", "**first_order_ode_lie_symmetry_lookup**"

Maple gives the following as the ode type

```
[[_linear, `class A`]]
```

$$y' + y = 2x e^{-x}$$

With initial conditions

$$[y(0) = 2]$$

2.2.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = 1$$

$$q(x) = 2x e^{-x}$$

Hence the ode is

$$y' + y = 2x e^{-x}$$

The domain of $p(x) = 1$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = 2x e^{-x}$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

2.2.2 Solving as linear ode

Entering Linear first order ODE solver. The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int 1 dx} \\ &= e^x\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu y) &= (\mu) (2x e^{-x}) \\ \frac{d}{dx}(e^x y) &= (e^x) (2x e^{-x}) \\ d(e^x y) &= (2x) dx\end{aligned}$$

Integrating gives

$$\begin{aligned}e^x y &= \int 2x dx \\ e^x y &= x^2 + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = e^x$ results in

$$y = x^2 e^{-x} + c_1 e^{-x}$$

which simplifies to

$$y = e^{-x} (x^2 + c_1)$$

Initial conditions are used to solve for c_1 . Substituting $x = 0$ and $y = 2$ in the above solution gives an equation to solve for the constant of integration.

$$2 = c_1$$

$$c_1 = 2$$

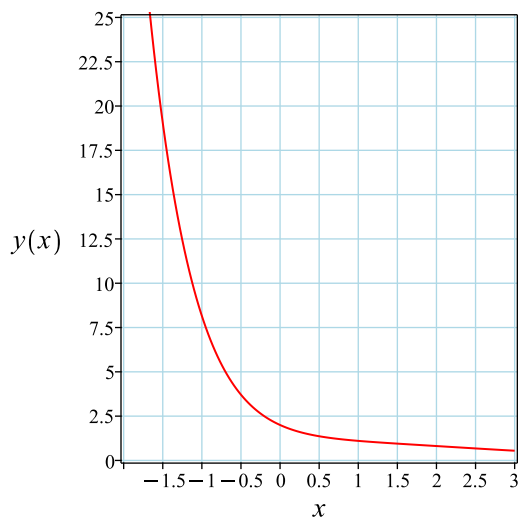
Substituting c_1 found above in the general solution gives

$$y = e^{-x}(x^2 + 2)$$

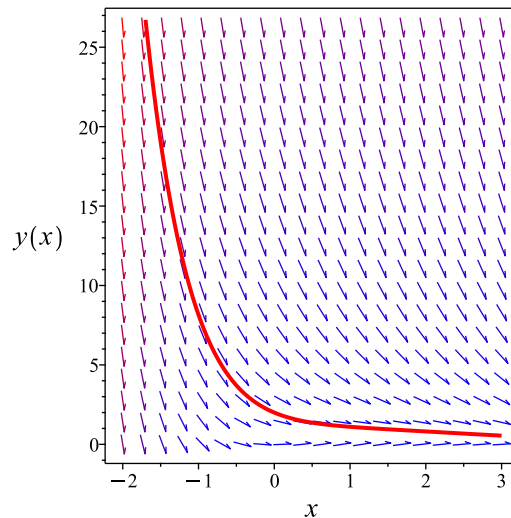
Summary

The solution(s) found are the following

$$y = e^{-x}(x^2 + 2) \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = e^{-x}(x^2 + 2)$$

Verified OK.

2.2.3 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = -y + 2x e^{-x}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 33: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= e^{-x}\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned}S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{e^{-x}} dy\end{aligned}$$

Which results in

$$S = e^x y$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y}\tag{2}$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -y + 2x e^{-x}$$

Evaluating all the partial derivatives gives

$$\begin{aligned}R_x &= 1 \\ R_y &= 0 \\ S_x &= e^x y \\ S_y &= e^x\end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 2x \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 2R$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = R^2 + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$y e^x = x^2 + c_1$$

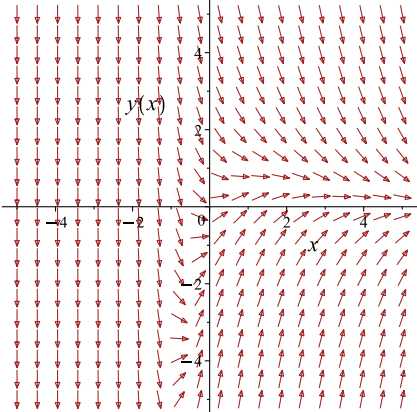
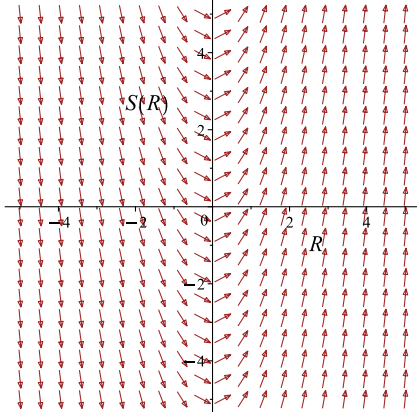
Which simplifies to

$$y e^x = x^2 + c_1$$

Which gives

$$y = e^{-x} (x^2 + c_1)$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -y + 2xe^{-x}$ 	$R = x$ $S = e^x y$	$\frac{dS}{dR} = 2R$ 

Initial conditions are used to solve for c_1 . Substituting $x = 0$ and $y = 2$ in the above solution gives an equation to solve for the constant of integration.

$$2 = c_1$$

$$c_1 = 2$$

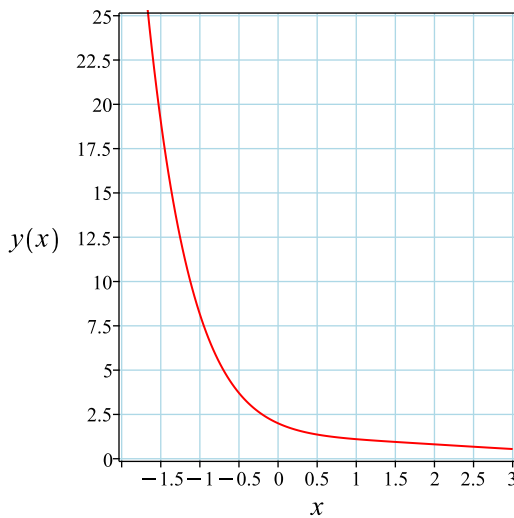
Substituting c_1 found above in the general solution gives

$$y = x^2 e^{-x} + 2e^{-x}$$

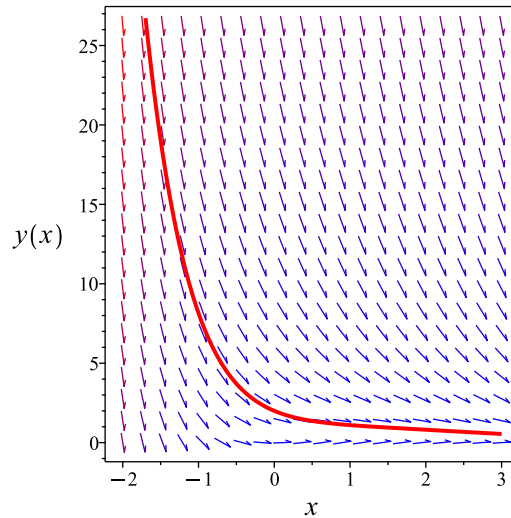
Summary

The solution(s) found are the following

$$y = x^2 e^{-x} + 2e^{-x} \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = x^2 e^{-x} + 2e^{-x}$$

Verified OK.

2.2.4 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \tag{1A}$$

Therefore

$$\begin{aligned} dy &= (-y + 2x e^{-x}) dx \\ (y - 2x e^{-x}) dx + dy &= 0 \end{aligned} \tag{2A}$$

Comparing (1A) and (2A) shows that

$$\begin{aligned} M(x, y) &= y - 2x e^{-x} \\ N(x, y) &= 1 \end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned} \frac{\partial M}{\partial y} &= \frac{\partial}{\partial y} (y - 2x e^{-x}) \\ &= 1 \end{aligned}$$

And

$$\begin{aligned} \frac{\partial N}{\partial x} &= \frac{\partial}{\partial x} (1) \\ &= 0 \end{aligned}$$

Since $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$\begin{aligned} A &= \frac{1}{N} \left(\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} \right) \\ &= 1((1) - (0)) \\ &= 1 \end{aligned}$$

Since A does not depend on y , then it can be used to find an integrating factor. The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int A dx} \\ &= e^{\int 1 dx}\end{aligned}$$

The result of integrating gives

$$\begin{aligned}\mu &= e^x \\ &= e^x\end{aligned}$$

M and N are multiplied by this integrating factor, giving new M and new N which are called \bar{M} and \bar{N} for now so not to confuse them with the original M and N .

$$\begin{aligned}\bar{M} &= \mu M \\ &= e^x(y - 2x e^{-x}) \\ &= e^x y - 2x\end{aligned}$$

And

$$\begin{aligned}\bar{N} &= \mu N \\ &= e^x(1) \\ &= e^x\end{aligned}$$

Now a modified ODE is obtained from the original ODE, which is exact and can be solved. The modified ODE is

$$\begin{aligned}\bar{M} + \bar{N} \frac{dy}{dx} &= 0 \\ (e^x y - 2x) + (e^x) \frac{dy}{dx} &= 0\end{aligned}$$

The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = \bar{M} \tag{1}$$

$$\frac{\partial \phi}{\partial y} = \bar{N} \tag{2}$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int \bar{M} dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int e^x y - 2x dx \\ \phi &= e^x y - x^2 + f(y)\end{aligned} \tag{3}$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial\phi}{\partial y} = e^x + f'(y) \quad (4)$$

But equation (2) says that $\frac{\partial\phi}{\partial y} = e^x$. Therefore equation (4) becomes

$$e^x = e^x + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 0$$

Therefore

$$f(y) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(y)$ into equation (3) gives ϕ

$$\phi = e^x y - x^2 + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = e^x y - x^2$$

The solution becomes

$$y = e^{-x}(x^2 + c_1)$$

Initial conditions are used to solve for c_1 . Substituting $x = 0$ and $y = 2$ in the above solution gives an equation to solve for the constant of integration.

$$2 = c_1$$

$$c_1 = 2$$

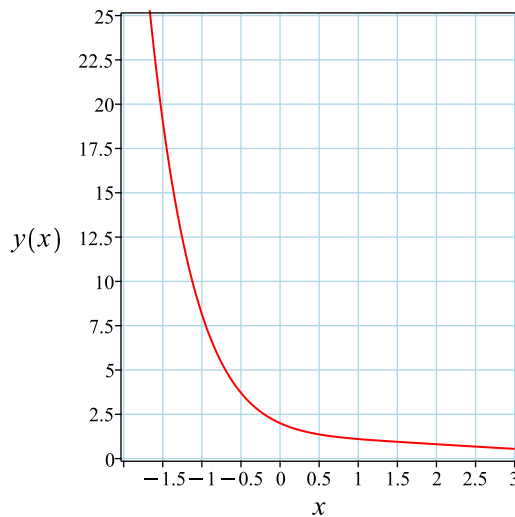
Substituting c_1 found above in the general solution gives

$$y = x^2 e^{-x} + 2 e^{-x}$$

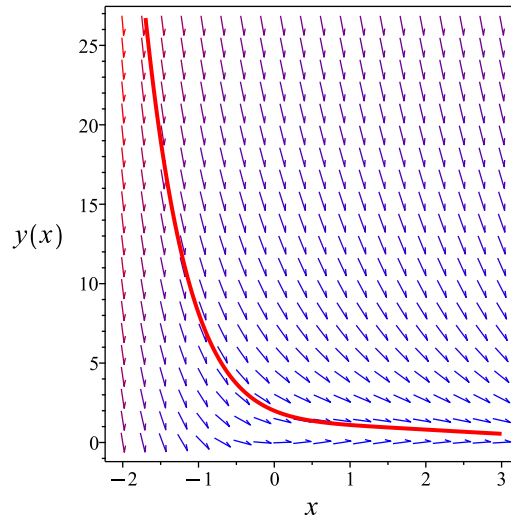
Summary

The solution(s) found are the following

$$y = x^2 e^{-x} + 2 e^{-x} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = x^2 e^{-x} + 2 e^{-x}$$

Verified OK.

2.2.5 Maple step by step solution

Let's solve

$$[y' + y = 2x e^{-x}, y(0) = 2]$$

- Highest derivative means the order of the ODE is 1

$$y'$$

- Isolate the derivative

$$y' = -y + 2x e^{-x}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE

$$y' + y = 2x e^{-x}$$

- The ODE is linear; multiply by an integrating factor $\mu(x)$

$$\mu(x) (y' + y) = 2\mu(x) x e^{-x}$$

- Assume the lhs of the ODE is the total derivative $\frac{d}{dx}(\mu(x) y)$

$$\mu(x) (y' + y) = \mu'(x) y + \mu(x) y'$$

- Isolate $\mu'(x)$

$$\mu'(x) = \mu(x)$$

- Solve to find the integrating factor

$$\mu(x) = e^x$$

- Integrate both sides with respect to x

$$\int \left(\frac{d}{dx}(\mu(x) y) \right) dx = \int 2\mu(x) x e^{-x} dx + c_1$$

- Evaluate the integral on the lhs

$$\mu(x) y = \int 2\mu(x) x e^{-x} dx + c_1$$

- Solve for y

$$y = \frac{\int 2\mu(x) x e^{-x} dx + c_1}{\mu(x)}$$

- Substitute $\mu(x) = e^x$

$$y = \frac{\int 2e^{-x} x e^x dx + c_1}{e^x}$$

- Evaluate the integrals on the rhs

$$y = \frac{x^2 + c_1}{e^x}$$

- Simplify

$$y = e^{-x}(x^2 + c_1)$$

- Use initial condition $y(0) = 2$

$$2 = c_1$$

- Solve for c_1

$$c_1 = 2$$

- Substitute $c_1 = 2$ into general solution and simplify

$$y = e^{-x}(x^2 + 2)$$

- Solution to the IVP

$$y = e^{-x}(x^2 + 2)$$

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
<- 1st order linear successful`
```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 14

```
dsolve([diff(y(x),x)+y(x)=2*x*exp(-x),y(0) = 2],y(x), singsol=all)
```

$$y(x) = (x^2 + 2) e^{-x}$$

✓ Solution by Mathematica

Time used: 0.087 (sec). Leaf size: 16

```
DSolve[{y'[x]+y[x]==2*x*Exp[-x],{y[0]==2}},y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^{-x}(x^2 + 2)$$

2.3 problem 2(b)

2.3.1	Existence and uniqueness analysis	183
2.3.2	Solving as linear ode	184
2.3.3	Solving as first order ode lie symmetry lookup ode	186
2.3.4	Solving as exact ode	190
2.3.5	Maple step by step solution	194

Internal problem ID [11587]

Internal file name [OUTPUT/10569_Thursday_May_18_2023_05_56_36_PM_46001342/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 1, section 1.3. Exercises page 22

Problem number: 2(b).

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**linear**", "**exactWithIntegrationFactor**", "**first_order_ode_lie_symmetry_lookup**"

Maple gives the following as the ode type

```
[[_linear, `class A`]]
```

$$y' + y = 2x e^{-x}$$

With initial conditions

$$[y(-1) = e + 3]$$

2.3.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = 1$$

$$q(x) = 2x e^{-x}$$

Hence the ode is

$$y' + y = 2x e^{-x}$$

The domain of $p(x) = 1$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = -1$ is inside this domain. The domain of $q(x) = 2x e^{-x}$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = -1$ is also inside this domain. Hence solution exists and is unique.

2.3.2 Solving as linear ode

Entering Linear first order ODE solver. The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int 1 dx} \\ &= e^x\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu y) &= (\mu) (2x e^{-x}) \\ \frac{d}{dx}(e^x y) &= (e^x) (2x e^{-x}) \\ d(e^x y) &= (2x) dx\end{aligned}$$

Integrating gives

$$\begin{aligned}e^x y &= \int 2x dx \\ e^x y &= x^2 + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = e^x$ results in

$$y = x^2 e^{-x} + c_1 e^{-x}$$

which simplifies to

$$y = e^{-x} (x^2 + c_1)$$

Initial conditions are used to solve for c_1 . Substituting $x = -1$ and $y = e + 3$ in the above solution gives an equation to solve for the constant of integration.

$$e + 3 = e(1 + c_1)$$

$$c_1 = 3e^{-1}$$

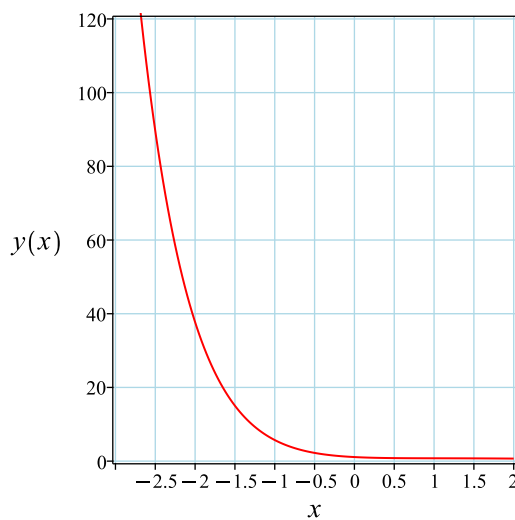
Substituting c_1 found above in the general solution gives

$$y = x^2e^{-x} + 3e^{-x-1}$$

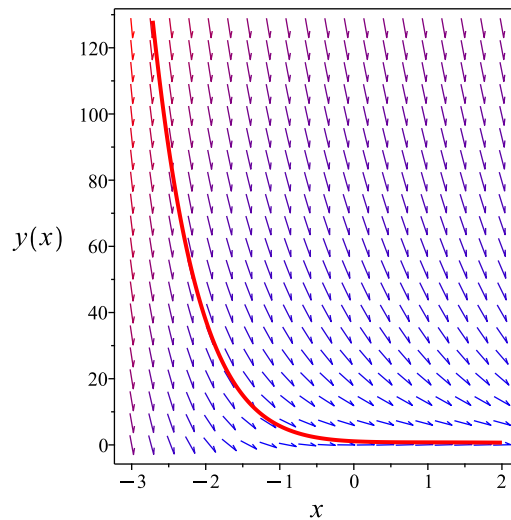
Summary

The solution(s) found are the following

$$y = x^2e^{-x} + 3e^{-x-1} \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = x^2e^{-x} + 3e^{-x-1}$$

Verified OK.

2.3.3 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = -y + 2x e^{-x}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 36: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= e^{-x}\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned}S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{e^{-x}} dy\end{aligned}$$

Which results in

$$S = e^x y$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y}\tag{2}$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -y + 2x e^{-x}$$

Evaluating all the partial derivatives gives

$$\begin{aligned}R_x &= 1 \\ R_y &= 0 \\ S_x &= e^x y \\ S_y &= e^x\end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 2x \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 2R$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = R^2 + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$y e^x = x^2 + c_1$$

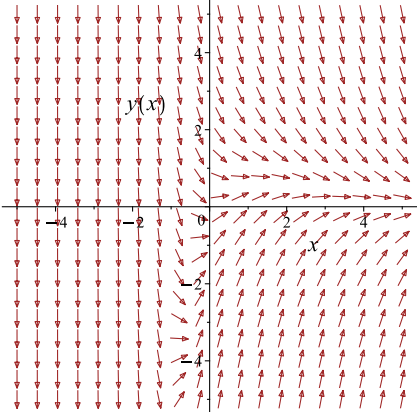
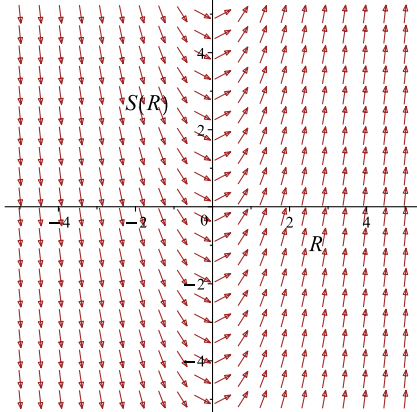
Which simplifies to

$$y e^x = x^2 + c_1$$

Which gives

$$y = e^{-x} (x^2 + c_1)$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -y + 2x e^{-x}$ 	$R = x$ $S = e^x y$	$\frac{dS}{dR} = 2R$ 

Initial conditions are used to solve for c_1 . Substituting $x = -1$ and $y = e + 3$ in the above solution gives an equation to solve for the constant of integration.

$$e + 3 = ec_1 + e$$

$$c_1 = 3e^{-1}$$

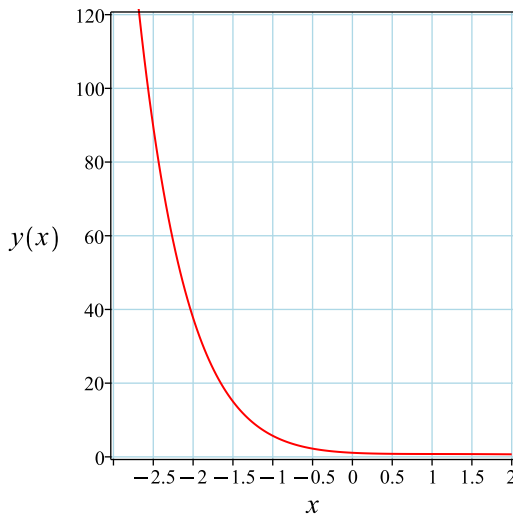
Substituting c_1 found above in the general solution gives

$$y = x^2 e^{-x} + 3e^{-x-1}$$

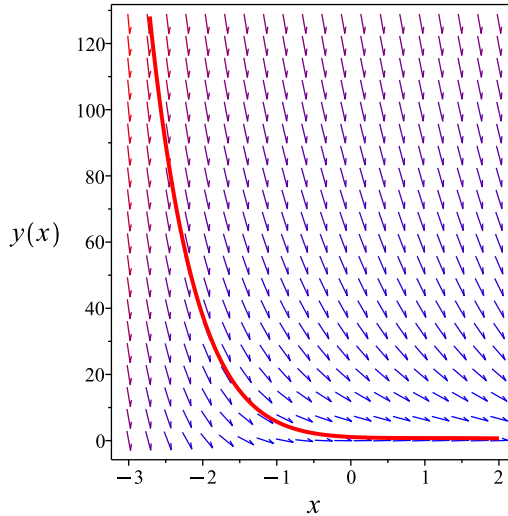
Summary

The solution(s) found are the following

$$y = x^2 e^{-x} + 3e^{-x-1} \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = x^2 e^{-x} + 3 e^{-x-1}$$

Verified OK.

2.3.4 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \tag{1A}$$

Therefore

$$\begin{aligned} dy &= (-y + 2x e^{-x}) dx \\ (y - 2x e^{-x}) dx + dy &= 0 \end{aligned} \tag{2A}$$

Comparing (1A) and (2A) shows that

$$\begin{aligned} M(x, y) &= y - 2x e^{-x} \\ N(x, y) &= 1 \end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned} \frac{\partial M}{\partial y} &= \frac{\partial}{\partial y} (y - 2x e^{-x}) \\ &= 1 \end{aligned}$$

And

$$\begin{aligned} \frac{\partial N}{\partial x} &= \frac{\partial}{\partial x} (1) \\ &= 0 \end{aligned}$$

Since $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$\begin{aligned} A &= \frac{1}{N} \left(\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} \right) \\ &= 1((1) - (0)) \\ &= 1 \end{aligned}$$

Since A does not depend on y , then it can be used to find an integrating factor. The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int A dx} \\ &= e^{\int 1 dx}\end{aligned}$$

The result of integrating gives

$$\begin{aligned}\mu &= e^x \\ &= e^x\end{aligned}$$

M and N are multiplied by this integrating factor, giving new M and new N which are called \bar{M} and \bar{N} for now so not to confuse them with the original M and N .

$$\begin{aligned}\bar{M} &= \mu M \\ &= e^x(y - 2x e^{-x}) \\ &= e^x y - 2x\end{aligned}$$

And

$$\begin{aligned}\bar{N} &= \mu N \\ &= e^x(1) \\ &= e^x\end{aligned}$$

Now a modified ODE is obtained from the original ODE, which is exact and can be solved. The modified ODE is

$$\begin{aligned}\bar{M} + \bar{N} \frac{dy}{dx} &= 0 \\ (e^x y - 2x) + (e^x) \frac{dy}{dx} &= 0\end{aligned}$$

The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = \bar{M} \tag{1}$$

$$\frac{\partial \phi}{\partial y} = \bar{N} \tag{2}$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int \bar{M} dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int e^x y - 2x dx \\ \phi &= e^x y - x^2 + f(y)\end{aligned} \tag{3}$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = e^x + f'(y) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = e^x$. Therefore equation (4) becomes

$$e^x = e^x + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 0$$

Therefore

$$f(y) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(y)$ into equation (3) gives ϕ

$$\phi = e^x y - x^2 + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = e^x y - x^2$$

The solution becomes

$$y = e^{-x}(x^2 + c_1)$$

Initial conditions are used to solve for c_1 . Substituting $x = -1$ and $y = e + 3$ in the above solution gives an equation to solve for the constant of integration.

$$e + 3 = ec_1 + e$$

$$c_1 = 3e^{-1}$$

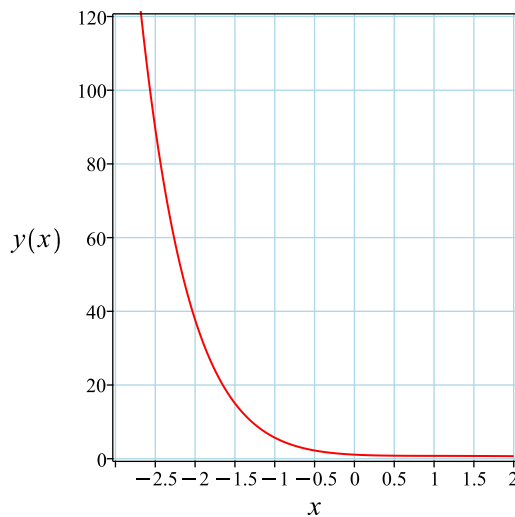
Substituting c_1 found above in the general solution gives

$$y = x^2 e^{-x} + 3e^{-x-1}$$

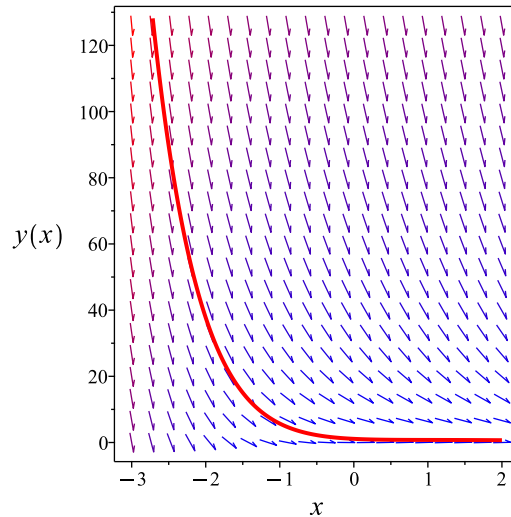
Summary

The solution(s) found are the following

$$y = x^2 e^{-x} + 3 e^{-x-1} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = x^2 e^{-x} + 3 e^{-x-1}$$

Verified OK.

2.3.5 Maple step by step solution

Let's solve

$$[y' + y = 2x e^{-x}, y(-1) = e + 3]$$

- Highest derivative means the order of the ODE is 1

$$y'$$

- Isolate the derivative

$$y' = -y + 2x e^{-x}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE

$$y' + y = 2x e^{-x}$$

- The ODE is linear; multiply by an integrating factor $\mu(x)$

$$\mu(x) (y' + y) = 2\mu(x) x e^{-x}$$

- Assume the lhs of the ODE is the total derivative $\frac{d}{dx}(\mu(x) y)$

$$\mu(x) (y' + y) = \mu'(x) y + \mu(x) y'$$

- Isolate $\mu'(x)$

$$\mu'(x) = \mu(x)$$

- Solve to find the integrating factor

$$\mu(x) = e^x$$

- Integrate both sides with respect to x

$$\int \left(\frac{d}{dx}(\mu(x) y) \right) dx = \int 2\mu(x) x e^{-x} dx + c_1$$

- Evaluate the integral on the lhs

$$\mu(x) y = \int 2\mu(x) x e^{-x} dx + c_1$$

- Solve for y

$$y = \frac{\int 2\mu(x) x e^{-x} dx + c_1}{\mu(x)}$$

- Substitute $\mu(x) = e^x$

$$y = \frac{\int 2e^{-x} x e^x dx + c_1}{e^x}$$

- Evaluate the integrals on the rhs

$$y = \frac{x^2 + c_1}{e^x}$$

- Simplify

$$y = e^{-x}(x^2 + c_1)$$

- Use initial condition $y(-1) = e + 3$

$$e + 3 = e(1 + c_1)$$

- Solve for c_1

$$c_1 = \frac{3}{e}$$

- Substitute $c_1 = \frac{3}{e}$ into general solution and simplify

$$y = (x^2 + 3e^{-1}) e^{-x}$$

- Solution to the IVP

$$y = (x^2 + 3e^{-1}) e^{-x}$$

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
<- 1st order linear successful`
```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 17

```
dsolve([diff(y(x),x)+y(x)=2*x*exp(-x),y(-1) = exp(1)+3],y(x), singsol=all)
```

$$y(x) = (x^2 + 3e^{-1})e^{-x}$$

✓ Solution by Mathematica

Time used: 0.086 (sec). Leaf size: 20

```
DSolve[{y'[x]+y[x]==2*x*Exp[-x],{y[-1]==Exp[1]+3}},y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^{-x-1}(ex^2 + 3)$$

2.4 problem 3(a)

2.4.1	Existence and uniqueness analysis	197
2.4.2	Solving as second order linear constant coeff ode	198
2.4.3	Solving using Kovacic algorithm	200
2.4.4	Maple step by step solution	204

Internal problem ID [11588]

Internal file name [OUTPUT/10570_Thursday_May_18_2023_05_56_36_PM_46263500/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 1, section 1.3. Exercises page 22

Problem number: 3(a).

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"kovacic", "second_order_linear_constant_coeff"**

Maple gives the following as the ode type

```
[[_2nd_order, _missing_x]]
```

$$y'' - y' - 12y = 0$$

With initial conditions

$$[y(0) = 5, y'(0) = 6]$$

2.4.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$p(x) = -1$$

$$q(x) = -12$$

$$F = 0$$

Hence the ode is

$$y'' - y' - 12y = 0$$

The domain of $p(x) = -1$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = -12$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

2.4.2 Solving as second order linear constant coeff ode

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = -1, C = -12$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} - \lambda e^{\lambda x} - 12 e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 - \lambda - 12 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = -1, C = -12$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{1}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{-1^2 - (4)(1)(-12)} \\ &= \frac{1}{2} \pm \frac{7}{2} \end{aligned}$$

Hence

$$\lambda_1 = \frac{1}{2} + \frac{7}{2}$$

$$\lambda_2 = \frac{1}{2} - \frac{7}{2}$$

Which simplifies to

$$\lambda_1 = 4$$

$$\lambda_2 = -3$$

Since roots are real and distinct, then the solution is

$$y = c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x}$$

$$y = c_1 e^{(4)x} + c_2 e^{(-3)x}$$

Or

$$y = c_1 e^{4x} + c_2 e^{-3x}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{4x} + c_2 e^{-3x} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 5$ and $x = 0$ in the above gives

$$5 = c_1 + c_2 \quad (1A)$$

Taking derivative of the solution gives

$$y' = 4c_1 e^{4x} - 3c_2 e^{-3x}$$

substituting $y' = 6$ and $x = 0$ in the above gives

$$6 = 4c_1 - 3c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 3$$

$$c_2 = 2$$

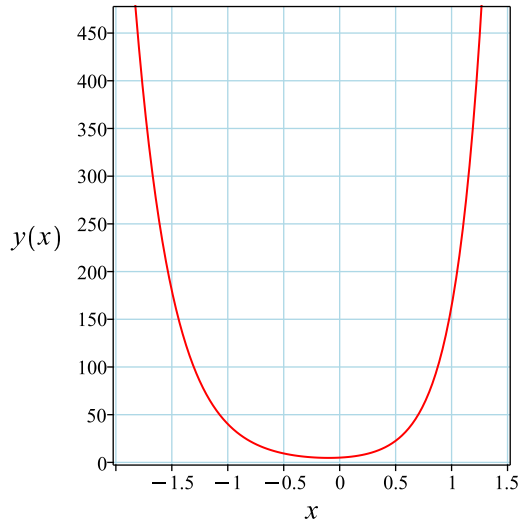
Substituting these values back in above solution results in

$$y = 3e^{4x} + 2e^{-3x}$$

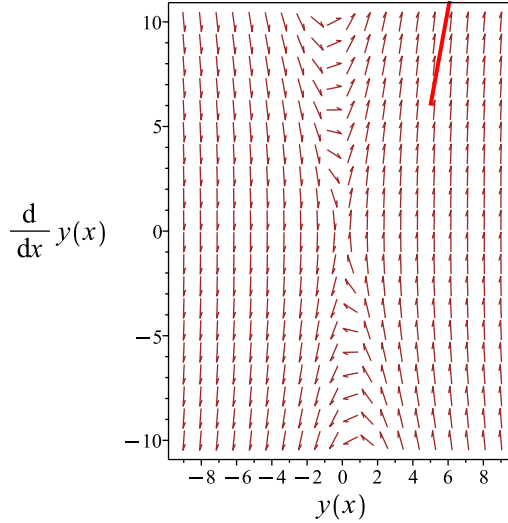
Summary

The solution(s) found are the following

$$y = 3e^{4x} + 2e^{-3x} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = 3e^{4x} + 2e^{-3x}$$

Verified OK.

2.4.3 Solving using Kovacic algorithm

Writing the ode as

$$y'' - y' - 12y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$A = 1$$

$$B = -1 \quad (3)$$

$$C = -12$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{49}{4} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 49 \\ t &= 4 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = \frac{49z(x)}{4} \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 39: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = \frac{49}{4}$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = e^{-\frac{7x}{2}}$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-1}{1} dx} \\ &= z_1 e^{\frac{x}{2}} \\ &= z_1 (e^{\frac{x}{2}}) \end{aligned}$$

Which simplifies to

$$y_1 = e^{-3x}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{-1}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^x}{(y_1)^2} dx \\ &= y_1 \left(\frac{e^{7x}}{7} \right) \end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (e^{-3x}) + c_2 \left(e^{-3x} \left(\frac{e^{7x}}{7} \right) \right)\end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{-3x} + \frac{c_2 e^{4x}}{7} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 5$ and $x = 0$ in the above gives

$$5 = c_1 + \frac{c_2}{7} \quad (1A)$$

Taking derivative of the solution gives

$$y' = -3c_1 e^{-3x} + \frac{4c_2 e^{4x}}{7}$$

substituting $y' = 6$ and $x = 0$ in the above gives

$$6 = -3c_1 + \frac{4c_2}{7} \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 2$$

$$c_2 = 21$$

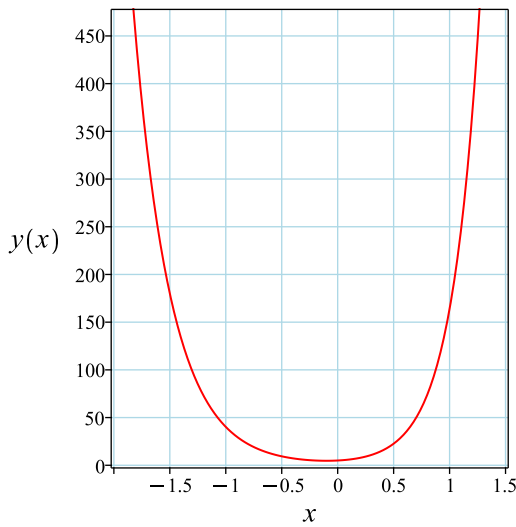
Substituting these values back in above solution results in

$$y = 3e^{4x} + 2e^{-3x}$$

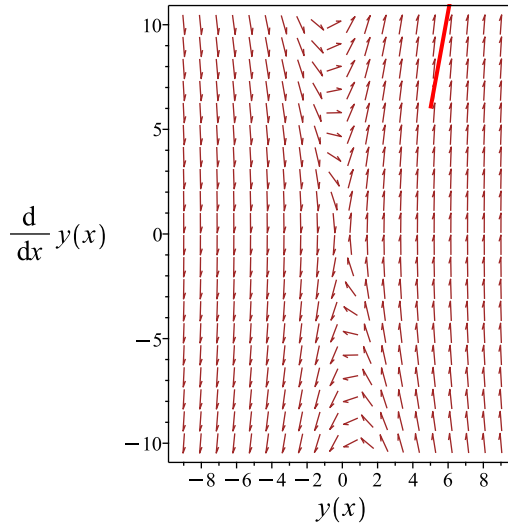
Summary

The solution(s) found are the following

$$y = 3e^{4x} + 2e^{-3x} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = 3e^{4x} + 2e^{-3x}$$

Verified OK.

2.4.4 Maple step by step solution

Let's solve

$$\left[y'' - y' - 12y = 0, y(0) = 5, y'|_{\{x=0\}} = 6 \right]$$

- Highest derivative means the order of the ODE is 2
 y''
- Characteristic polynomial of ODE
 $r^2 - r - 12 = 0$
- Factor the characteristic polynomial
 $(r + 3)(r - 4) = 0$
- Roots of the characteristic polynomial
 $r = (-3, 4)$
- 1st solution of the ODE

$$y_1(x) = e^{-3x}$$

- 2nd solution of the ODE

$$y_2(x) = e^{4x}$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x)$$

- Substitute in solutions

$$y = c_1 e^{-3x} + c_2 e^{4x}$$

- Check validity of solution $y = c_1 e^{-3x} + c_2 e^{4x}$

- Use initial condition $y(0) = 5$

$$5 = c_1 + c_2$$

- Compute derivative of the solution

$$y' = -3c_1 e^{-3x} + 4c_2 e^{4x}$$

- Use the initial condition $y' \Big|_{\{x=0\}} = 6$

$$6 = -3c_1 + 4c_2$$

- Solve for c_1 and c_2

$$\{c_1 = 2, c_2 = 3\}$$

- Substitute constant values into general solution and simplify

$$y = (3e^{7x} + 2)e^{-3x}$$

- Solution to the IVP

$$y = (3e^{7x} + 2)e^{-3x}$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 17

```
dsolve([diff(y(x),x$2)-diff(y(x),x)-12*y(x)=0,y(0) = 5, D(y)(0) = 6],y(x), singsol=all)
```

$$y(x) = (3e^{7x} + 2)e^{-3x}$$

✓ Solution by Mathematica

Time used: 0.022 (sec). Leaf size: 20

```
DSolve[{y''[x]-y'[x]-12*y[x]==0,{y[0]==5,y'[0]==6}},y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^{-3x}(3e^{7x} + 2)$$

2.5 problem 4(a)

2.5.1	Solving as second order linear constant coeff ode	207
2.5.2	Solving as second order ode can be made integrable ode	209
2.5.3	Solving using Kovacic algorithm	211
2.5.4	Maple step by step solution	214

Internal problem ID [11589]

Internal file name [OUTPUT/10571_Thursday_May_18_2023_05_56_37_PM_91740308/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 1, section 1.3. Exercises page 22

Problem number: 4(a).

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff", "second_order_ode_can_be_made_integrable"

Maple gives the following as the ode type

```
[[_2nd_order, _missing_x]]
```

Unable to solve or complete the solution.

$$y'' + y = 0$$

With initial conditions

$$\left[y(0) = 0, y'\left(\frac{\pi}{2}\right) = 1 \right]$$

2.5.1 Solving as second order linear constant coeff ode

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 0, C = 1$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + e^{\lambda x} = 0 \tag{1}$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 1 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 0, C = 1$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{0}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{0^2 - (4)(1)(1)} \\ &= \pm i \end{aligned}$$

Hence

$$\begin{aligned} \lambda_1 &= +i \\ \lambda_2 &= -i \end{aligned}$$

Which simplifies to

$$\begin{aligned} \lambda_1 &= i \\ \lambda_2 &= -i \end{aligned}$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = 0$ and $\beta = 1$. Therefore the final solution, when using Euler relation, can be written as

$$y = e^{\alpha x} (c_1 \cos(\beta x) + c_2 \sin(\beta x))$$

Which becomes

$$y = e^0 (c_1 \cos(x) + c_2 \sin(x))$$

Or

$$y = c_1 \cos(x) + c_2 \sin(x)$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 \cos(x) + c_2 \sin(x) \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 0$ and $x = 0$ in the above gives

$$0 = c_1 \quad (1A)$$

Taking derivative of the solution gives

$$y' = -\sin(x) c_1 + c_2 \cos(x)$$

substituting $y' = 1$ and $x = \frac{\pi}{2}$ in the above gives

$$1 = -c_1 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. There is no solution for the constants of integrations. This solution is removed.

Verification of solutions N/A

2.5.2 Solving as second order ode can be made integrable ode

Multiplying the ode by y' gives

$$y'y'' + yy' = 0$$

Integrating the above w.r.t x gives

$$\int (y'y'' + yy') dx = 0$$
$$\frac{y'^2}{2} + \frac{y^2}{2} = c_2$$

Which is now solved for y . Solving the given ode for y' results in 2 differential equations to solve. Each one of these will generate a solution. The equations generated are

$$y' = \sqrt{-y^2 + 2c_1} \quad (1)$$

$$y' = -\sqrt{-y^2 + 2c_1} \quad (2)$$

Now each one of the above ODE is solved.

Solving equation (1)

Integrating both sides gives

$$\int \frac{1}{\sqrt{-y^2 + 2c_1}} dy = \int dx$$

$$\arctan \left(\frac{y}{\sqrt{-y^2 + 2c_1}} \right) = x + c_2$$

Solving equation (2)

Integrating both sides gives

$$\int -\frac{1}{\sqrt{-y^2 + 2c_1}} dy = \int dx$$

$$-\arctan \left(\frac{y}{\sqrt{-y^2 + 2c_1}} \right) = c_3 + x$$

Initial conditions are used to solve for the constants of integration.

Looking at the First solution

$$\arctan \left(\frac{y}{\sqrt{-y^2 + 2c_1}} \right) = x + c_2 \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 0$ and $x = 0$ in the above gives

$$0 = c_2 \quad (1A)$$

Taking derivative of the solution gives

$$y' = (\tan(x + c_2)^2 + 1) \sqrt{2} \sqrt{\frac{c_1}{\tan(x + c_2)^2 + 1}} - \frac{\tan(x + c_2)^2 \sqrt{2} c_1}{\sqrt{\frac{c_1}{\tan(x + c_2)^2 + 1}} (\tan(x + c_2)^2 + 1)}$$

substituting $y' = 1$ and $x = \frac{\pi}{2}$ in the above gives

$$1 = \frac{\sin(c_2)^2 \sqrt{2} c_1}{\sqrt{\sin(c_2)^2 c_1}} \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. There is no solution for the constants of integrations. This solution is removed.

Looking at the Second solution

$$-\arctan\left(\frac{y}{\sqrt{-y^2+2c_1}}\right) = c_3 + x \quad (2)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 0$ and $x = 0$ in the above gives

$$0 = c_3 \quad (1A)$$

Taking derivative of the solution gives

$$y' = -(\tan(c_3 + x)^2 + 1) \sqrt{2} \sqrt{\frac{c_1}{\tan(c_3 + x)^2 + 1}} + \frac{\tan(c_3 + x)^2 \sqrt{2} c_1}{\sqrt{\frac{c_1}{\tan(c_3 + x)^2 + 1}} (\tan(c_3 + x)^2 + 1)}$$

substituting $y' = 1$ and $x = \frac{\pi}{2}$ in the above gives

$$1 = -\frac{\sin(c_3)^2 \sqrt{2} c_1}{\sqrt{\sin(c_3)^2 c_1}} \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_3\}$. There is no solution for the constants of integrations. This solution is removed.

Verification of solutions N/A

2.5.3 Solving using Kovacic algorithm

Writing the ode as

$$y'' + y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= 0 \\ C &= 1 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-1}{1} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= -1 \\ t &= 1 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = -z(x) \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 41: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = -1$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = \cos(x)$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$y_1 = z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx}$$

Since $B = 0$ then the above reduces to

$$\begin{aligned} y_1 &= z_1 \\ &= \cos(x) \end{aligned}$$

Which simplifies to

$$y_1 = \cos(x)$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Since $B = 0$ then the above becomes

$$\begin{aligned} y_2 &= y_1 \int \frac{1}{y_1^2} dx \\ &= \cos(x) \int \frac{1}{\cos(x)^2} dx \\ &= \cos(x) (\tan(x)) \end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1(\cos(x)) + c_2(\cos(x)(\tan(x)))\end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 \cos(x) + c_2 \sin(x) \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 0$ and $x = 0$ in the above gives

$$0 = c_1 \quad (1A)$$

Taking derivative of the solution gives

$$y' = -\sin(x) c_1 + c_2 \cos(x)$$

substituting $y' = 1$ and $x = \frac{\pi}{2}$ in the above gives

$$1 = -c_1 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. There is no solution for the constants of integrations. This solution is removed.

Verification of solutions N/A

2.5.4 Maple step by step solution

Let's solve

$$\left[y'' + y = 0, y(0) = 0, y' \Big|_{\{x=\frac{\pi}{2}\}} = 1 \right]$$

- Highest derivative means the order of the ODE is 2

y''

- Characteristic polynomial of ODE

$$r^2 + 1 = 0$$

- Use quadratic formula to solve for r

$$r = \frac{0 \pm (\sqrt{-4})}{2}$$
- Roots of the characteristic polynomial

$$r = (-1, 1)$$
- 1st solution of the ODE

$$y_1(x) = \cos(x)$$
- 2nd solution of the ODE

$$y_2(x) = \sin(x)$$
- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x)$$
- Substitute in solutions

$$y = c_1 \cos(x) + c_2 \sin(x)$$
- Check validity of solution $y = c_1 \cos(x) + c_2 \sin(x)$
 - Use initial condition $y(0) = 0$

$$0 = c_1$$
 - Compute derivative of the solution

$$y' = -\sin(x) c_1 + c_2 \cos(x)$$
 - Use the initial condition $y' \Big|_{\{x=\frac{\pi}{2}\}} = 1$

$$1 = -c_1$$
 - Solve for c_1 and c_2
 - The solution does not satisfy the initial conditions

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
<- constant coefficients successful`

```


X Solution by Maple

```
dsolve([diff(y(x),x$2)+y(x)=0,y(0) = 0, D(y)(1/2*Pi) = 1],y(x), singsol=all)
```

No solution found

X Solution by Mathematica

Time used: 0.0 (sec). Leaf size: 0

```
DSolve[{y'[x]+y[x]==0,{y[0]==0,y'[Pi/2]==1}},y[x],x,IncludeSingularSolutions -> True]
```

{}

2.6 problem 4(b)

2.6.1	Solving as second order linear constant coeff ode	217
2.6.2	Solving as second order ode can be made integrable ode	219
2.6.3	Solving using Kovacic algorithm	221
2.6.4	Maple step by step solution	224

Internal problem ID [11590]

Internal file name [OUTPUT/10572_Thursday_May_18_2023_05_56_37_PM_6449168/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 1, section 1.3. Exercises page 22

Problem number: 4(b).

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff", "second_order_ode_can_be_made_integrable"

Maple gives the following as the ode type

```
[[_2nd_order , _missing_x]]
```

Unable to solve or complete the solution.

$$y'' + y = 0$$

With initial conditions

$$\left[y(0) = 0, y'\left(\frac{\pi}{2}\right) = -1 \right]$$

2.6.1 Solving as second order linear constant coeff ode

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 0, C = 1$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + e^{\lambda x} = 0 \tag{1}$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 1 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 0, C = 1$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{0}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{0^2 - (4)(1)(1)} \\ &= \pm i \end{aligned}$$

Hence

$$\begin{aligned} \lambda_1 &= +i \\ \lambda_2 &= -i \end{aligned}$$

Which simplifies to

$$\begin{aligned} \lambda_1 &= i \\ \lambda_2 &= -i \end{aligned}$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = 0$ and $\beta = 1$. Therefore the final solution, when using Euler relation, can be written as

$$y = e^{\alpha x} (c_1 \cos(\beta x) + c_2 \sin(\beta x))$$

Which becomes

$$y = e^0 (c_1 \cos(x) + c_2 \sin(x))$$

Or

$$y = c_1 \cos(x) + c_2 \sin(x)$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 \cos(x) + c_2 \sin(x) \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 0$ and $x = 0$ in the above gives

$$0 = c_1 \quad (1A)$$

Taking derivative of the solution gives

$$y' = -\sin(x) c_1 + c_2 \cos(x)$$

substituting $y' = -1$ and $x = \frac{\pi}{2}$ in the above gives

$$-1 = -c_1 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. There is no solution for the constants of integrations. This solution is removed.

Verification of solutions N/A

2.6.2 Solving as second order ode can be made integrable ode

Multiplying the ode by y' gives

$$y'y'' + yy' = 0$$

Integrating the above w.r.t x gives

$$\int (y'y'' + yy') dx = 0$$
$$\frac{y'^2}{2} + \frac{y^2}{2} = c_2$$

Which is now solved for y . Solving the given ode for y' results in 2 differential equations to solve. Each one of these will generate a solution. The equations generated are

$$y' = \sqrt{-y^2 + 2c_1} \quad (1)$$

$$y' = -\sqrt{-y^2 + 2c_1} \quad (2)$$

Now each one of the above ODE is solved.

Solving equation (1)

Integrating both sides gives

$$\int \frac{1}{\sqrt{-y^2 + 2c_1}} dy = \int dx$$

$$\arctan\left(\frac{y}{\sqrt{-y^2 + 2c_1}}\right) = x + c_2$$

Solving equation (2)

Integrating both sides gives

$$\int -\frac{1}{\sqrt{-y^2 + 2c_1}} dy = \int dx$$

$$-\arctan\left(\frac{y}{\sqrt{-y^2 + 2c_1}}\right) = c_3 + x$$

Initial conditions are used to solve for the constants of integration.

Looking at the First solution

$$\arctan\left(\frac{y}{\sqrt{-y^2 + 2c_1}}\right) = x + c_2 \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 0$ and $x = 0$ in the above gives

$$0 = c_2 \quad (1A)$$

Taking derivative of the solution gives

$$y' = (\tan(x + c_2)^2 + 1) \sqrt{2} \sqrt{\frac{c_1}{\tan(x + c_2)^2 + 1}} - \frac{\tan(x + c_2)^2 \sqrt{2} c_1}{\sqrt{\frac{c_1}{\tan(x + c_2)^2 + 1}} (\tan(x + c_2)^2 + 1)}$$

substituting $y' = -1$ and $x = \frac{\pi}{2}$ in the above gives

$$-1 = \frac{\sin(c_2)^2 \sqrt{2} c_1}{\sqrt{\sin(c_2)^2 c_1}} \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. There is no solution for the constants of integrations. This solution is removed.

Looking at the Second solution

$$-\arctan\left(\frac{y}{\sqrt{-y^2+2c_1}}\right) = c_3 + x \quad (2)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 0$ and $x = 0$ in the above gives

$$0 = c_3 \quad (1A)$$

Taking derivative of the solution gives

$$y' = -(\tan(c_3 + x)^2 + 1) \sqrt{2} \sqrt{\frac{c_1}{\tan(c_3 + x)^2 + 1}} + \frac{\tan(c_3 + x)^2 \sqrt{2} c_1}{\sqrt{\frac{c_1}{\tan(c_3 + x)^2 + 1}} (\tan(c_3 + x)^2 + 1)}$$

substituting $y' = -1$ and $x = \frac{\pi}{2}$ in the above gives

$$-1 = -\frac{\sin(c_3)^2 \sqrt{2} c_1}{\sqrt{\sin(c_3)^2 c_1}} \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_3\}$. There is no solution for the constants of integrations. This solution is removed.

Verification of solutions N/A

2.6.3 Solving using Kovacic algorithm

Writing the ode as

$$y'' + y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= 0 \\ C &= 1 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-1}{1} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= -1 \\ t &= 1 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = -z(x) \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 43: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = -1$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = \cos(x)$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$y_1 = z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx}$$

Since $B = 0$ then the above reduces to

$$\begin{aligned} y_1 &= z_1 \\ &= \cos(x) \end{aligned}$$

Which simplifies to

$$y_1 = \cos(x)$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Since $B = 0$ then the above becomes

$$\begin{aligned} y_2 &= y_1 \int \frac{1}{y_1^2} dx \\ &= \cos(x) \int \frac{1}{\cos(x)^2} dx \\ &= \cos(x) (\tan(x)) \end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1(\cos(x)) + c_2(\cos(x)(\tan(x)))\end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 \cos(x) + c_2 \sin(x) \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 0$ and $x = 0$ in the above gives

$$0 = c_1 \quad (1A)$$

Taking derivative of the solution gives

$$y' = -\sin(x) c_1 + c_2 \cos(x)$$

substituting $y' = -1$ and $x = \frac{\pi}{2}$ in the above gives

$$-1 = -c_1 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. There is no solution for the constants of integrations. This solution is removed.

Verification of solutions N/A

2.6.4 Maple step by step solution

Let's solve

$$\left[y'' + y = 0, y(0) = 0, y' \Big|_{\{x=\frac{\pi}{2}\}} = -1 \right]$$

- Highest derivative means the order of the ODE is 2

y''

- Characteristic polynomial of ODE

$$r^2 + 1 = 0$$

- Use quadratic formula to solve for r

$$r = \frac{0 \pm (\sqrt{-4})}{2}$$
- Roots of the characteristic polynomial

$$r = (-1, 1)$$
- 1st solution of the ODE

$$y_1(x) = \cos(x)$$
- 2nd solution of the ODE

$$y_2(x) = \sin(x)$$
- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x)$$
- Substitute in solutions

$$y = c_1 \cos(x) + c_2 \sin(x)$$
- Check validity of solution $y = c_1 \cos(x) + c_2 \sin(x)$
 - Use initial condition $y(0) = 0$

$$0 = c_1$$
 - Compute derivative of the solution

$$y' = -\sin(x) c_1 + c_2 \cos(x)$$
 - Use the initial condition $y' \Big|_{\{x=\frac{\pi}{2}\}} = -1$

$$-1 = -c_1$$
 - Solve for c_1 and c_2
 - The solution does not satisfy the initial conditions

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

X Solution by Maple

```
dsolve([diff(y(x),x$2)+y(x)=0,y(0) = 0, D(y)(1/2*Pi) = -1],y(x), singsol=all)
```

No solution found

X Solution by Mathematica

Time used: 0.0 (sec). Leaf size: 0

```
DSolve[{y'[x]+y[x]==0,{y[0]==0,y'[Pi/2]==-1}},y[x],x,IncludeSingularSolutions -> True]
```

{}

2.7 problem 4(c)

2.7.1	Solving as second order linear constant coeff ode	227
2.7.2	Solving as second order ode can be made integrable ode	230
2.7.3	Solving using Kovacic algorithm	232

Internal problem ID [11591]

Internal file name [OUTPUT/10573_Thursday_May_18_2023_05_56_38_PM_91594257/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 1, section 1.3. Exercises page 22

Problem number: 4(c).

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff", "second_order_ode_can_be_made_integrable"

Maple gives the following as the ode type

```
[[_2nd_order , _missing_x]]
```

$$y'' + y = 0$$

With initial conditions

$$[y(0) = 0, y'(\pi) = 1]$$

2.7.1 Solving as second order linear constant coeff ode

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 0, C = 1$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + e^{\lambda x} = 0 \tag{1}$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 1 = 0 \tag{2}$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 0, C = 1$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{0}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{0^2 - (4)(1)(1)} \\ &= \pm i \end{aligned}$$

Hence

$$\begin{aligned} \lambda_1 &= +i \\ \lambda_2 &= -i \end{aligned}$$

Which simplifies to

$$\begin{aligned} \lambda_1 &= i \\ \lambda_2 &= -i \end{aligned}$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = 0$ and $\beta = 1$. Therefore the final solution, when using Euler relation, can be written as

$$y = e^{\alpha x} (c_1 \cos(\beta x) + c_2 \sin(\beta x))$$

Which becomes

$$y = e^0 (c_1 \cos(x) + c_2 \sin(x))$$

Or

$$y = c_1 \cos(x) + c_2 \sin(x)$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 \cos(x) + c_2 \sin(x) \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 0$ and $x = 0$ in the above gives

$$0 = c_1 \tag{1A}$$

Taking derivative of the solution gives

$$y' = -\sin(x)c_1 + c_2 \cos(x)$$

substituting $y' = 1$ and $x = \pi$ in the above gives

$$1 = -c_2 \tag{2A}$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$\begin{aligned} c_1 &= 0 \\ c_2 &= -1 \end{aligned}$$

Substituting these values back in above solution results in

$$y = -\sin(x)$$

Summary

The solution(s) found are the following

$$y = -\sin(x) \tag{1}$$

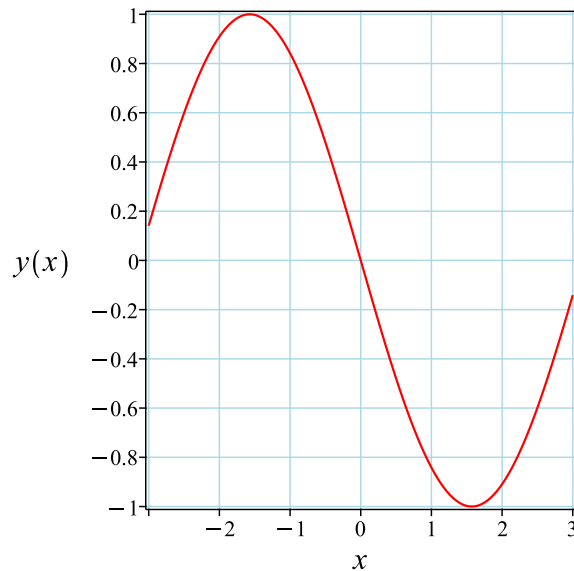


Figure 41: Solution plot

Verification of solutions

$$y = -\sin(x)$$

Verified OK.

2.7.2 Solving as second order ode can be made integrable ode

Multiplying the ode by y' gives

$$y'y'' + yy' = 0$$

Integrating the above w.r.t x gives

$$\int (y'y'' + yy') dx = 0$$
$$\frac{y'^2}{2} + \frac{y^2}{2} = c_2$$

Which is now solved for y . Solving the given ode for y' results in 2 differential equations to solve. Each one of these will generate a solution. The equations generated are

$$y' = \sqrt{-y^2 + 2c_1} \quad (1)$$

$$y' = -\sqrt{-y^2 + 2c_1} \quad (2)$$

Now each one of the above ODE is solved.

Solving equation (1)

Integrating both sides gives

$$\int \frac{1}{\sqrt{-y^2 + 2c_1}} dy = \int dx$$
$$\arctan\left(\frac{y}{\sqrt{-y^2 + 2c_1}}\right) = x + c_2$$

Solving equation (2)

Integrating both sides gives

$$\int -\frac{1}{\sqrt{-y^2 + 2c_1}} dy = \int dx$$
$$-\arctan\left(\frac{y}{\sqrt{-y^2 + 2c_1}}\right) = c_3 + x$$

Initial conditions are used to solve for the constants of integration.

Looking at the First solution

$$\arctan\left(\frac{y}{\sqrt{-y^2+2c_1}}\right) = x + c_2 \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 0$ and $x = 0$ in the above gives

$$0 = c_2 \quad (1A)$$

Taking derivative of the solution gives

$$y' = (\tan(x + c_2)^2 + 1) \sqrt{2} \sqrt{\frac{c_1}{\tan(x + c_2)^2 + 1}} - \frac{\tan(x + c_2)^2 \sqrt{2} c_1}{\sqrt{\frac{c_1}{\tan(x + c_2)^2 + 1}} (\tan(x + c_2)^2 + 1)}$$

substituting $y' = 1$ and $x = \pi$ in the above gives

$$1 = \frac{\cos(c_2)^2 \sqrt{2} c_1}{\sqrt{\cos(c_2)^2 c_1}} \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = \frac{1}{2}$$

$$c_2 = 0$$

Substituting these values back in above solution results in

$$\arctan\left(\frac{y}{\sqrt{1-y^2}}\right) = x$$

Looking at the Second solution

$$-\arctan\left(\frac{y}{\sqrt{-y^2+2c_1}}\right) = c_3 + x \quad (2)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 0$ and $x = 0$ in the above gives

$$0 = c_3 \quad (1A)$$

Taking derivative of the solution gives

$$y' = -(\tan(c_3 + x)^2 + 1) \sqrt{2} \sqrt{\frac{c_1}{\tan(c_3 + x)^2 + 1}} + \frac{\tan(c_3 + x)^2 \sqrt{2} c_1}{\sqrt{\frac{c_1}{\tan(c_3 + x)^2 + 1}} (\tan(c_3 + x)^2 + 1)}$$

substituting $y' = 1$ and $x = \pi$ in the above gives

$$1 = -\frac{\cos(c_3)^2 \sqrt{2} c_1}{\sqrt{\cos(c_3)^2 c_1}} \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_3\}$. Warning, unable to solve for constants of

Summary

The solution(s) found are the following integrations.

$$\arctan\left(\frac{y}{\sqrt{1-y^2}}\right) = x \quad (1)$$

Verification of solutions

$$\arctan\left(\frac{y}{\sqrt{1-y^2}}\right) = x$$

Verified OK.

2.7.3 Solving using Kovacic algorithm

Writing the ode as

$$y'' + y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= 0 \\ C &= 1 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$r = \frac{s}{t} \tag{5}$$

$$= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-1}{1} \tag{6}$$

Comparing the above to (5) shows that

$$s = -1$$

$$t = 1$$

Therefore eq. (4) becomes

$$z''(x) = -z(x) \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 45: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = -1$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = \cos(x)$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$y_1 = z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx}$$

Since $B = 0$ then the above reduces to

$$\begin{aligned} y_1 &= z_1 \\ &= \cos(x) \end{aligned}$$

Which simplifies to

$$y_1 = \cos(x)$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Since $B = 0$ then the above becomes

$$\begin{aligned} y_2 &= y_1 \int \frac{1}{y_1^2} dx \\ &= \cos(x) \int \frac{1}{\cos(x)^2} dx \\ &= \cos(x) (\tan(x)) \end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1(\cos(x)) + c_2(\cos(x)(\tan(x)))\end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 \cos(x) + c_2 \sin(x) \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 0$ and $x = 0$ in the above gives

$$0 = c_1 \quad (1A)$$

Taking derivative of the solution gives

$$y' = -\sin(x) c_1 + c_2 \cos(x)$$

substituting $y' = 1$ and $x = \pi$ in the above gives

$$1 = -c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$\begin{aligned}c_1 &= 0 \\ c_2 &= -1\end{aligned}$$

Substituting these values back in above solution results in

$$y = -\sin(x)$$

Summary

The solution(s) found are the following

$$y = -\sin(x) \quad (1)$$

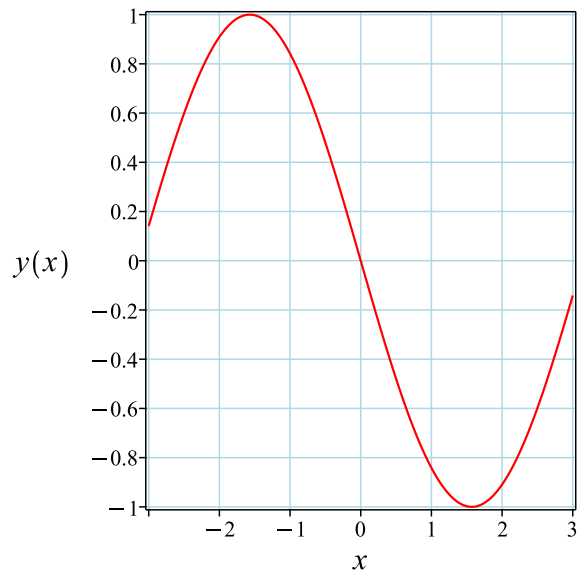


Figure 42: Solution plot

Verification of solutions

$$y = -\sin(x)$$

Verified OK.

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 8

```
dsolve([diff(y(x),x$2)+y(x)=0,y(0) = 0, D(y)(Pi) = 1],y(x), singsol=all)
```

$$y(x) = -\sin(x)$$

✓ Solution by Mathematica

Time used: 0.018 (sec). Leaf size: 9

```
DSolve[{y'[x]+y[x]==0,{y[0]==0,y'[Pi]==1}},y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow -\sin(x)$$

2.8 problem 5

2.8.1 Maple step by step solution 241

Internal problem ID [11592]

Internal file name [OUTPUT/10574_Thursday_May_18_2023_05_56_39_PM_4049348/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 1, section 1.3. Exercises page 22

Problem number: 5.

ODE order: 3.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_ODE_non_constant_coefficients_of_type_Euler**"

Maple gives the following as the ode type

```
[[_3rd_order , _with_linear_symmetries]]
```

$$x^3 y''' - 3x^2 y'' + 6y'x - 6y = 0$$

With initial conditions

$$[y(2) = 0, y'(2) = 2, y''(2) = 6]$$

This is Euler ODE of higher order. Let $y = x^\lambda$. Hence

$$y' = \lambda x^{\lambda-1}$$

$$y'' = \lambda(\lambda - 1) x^{\lambda-2}$$

$$y''' = \lambda(\lambda - 1)(\lambda - 2) x^{\lambda-3}$$

Substituting these back into

$$x^3 y''' - 3x^2 y'' + 6y'x - 6y = 0$$

gives

$$6x\lambda x^{\lambda-1} - 3x^2\lambda(\lambda - 1) x^{\lambda-2} + x^3\lambda(\lambda - 1)(\lambda - 2) x^{\lambda-3} - 6x^\lambda = 0$$

Which simplifies to

$$6\lambda x^\lambda - 3\lambda(\lambda - 1) x^\lambda + \lambda(\lambda - 1)(\lambda - 2) x^\lambda - 6x^\lambda = 0$$

And since $x^\lambda \neq 0$ then dividing through by x^λ , the above becomes

$$6\lambda - 3\lambda(\lambda - 1) + \lambda(\lambda - 1)(\lambda - 2) - 6 = 0$$

Simplifying gives the characteristic equation as

$$\lambda^3 - 6\lambda^2 + 11\lambda - 6 = 0$$

Solving the above gives the following roots

$$\lambda_1 = 1$$

$$\lambda_2 = 2$$

$$\lambda_3 = 3$$

This table summarises the result

root	multiplicity	type of root
1	1	real root
2	1	real root
3	1	real root

The solution is generated by going over the above table. For each real root λ of multiplicity one generates a c_1x^λ basis solution. Each real root of multiplicity two, generates c_1x^λ and $c_2x^\lambda \ln(x)$ basis solutions. Each real root of multiplicity three, generates c_1x^λ and $c_2x^\lambda \ln(x)$ and $c_3x^\lambda \ln(x)^2$ basis solutions, and so on. Each complex root $\alpha \pm i\beta$ of multiplicity one generates $x^\alpha(c_1 \cos(\beta \ln(x)) + c_2 \sin(\beta \ln(x)))$ basis solutions. And each complex root $\alpha \pm i\beta$ of multiplicity two generates $\ln(x) x^\alpha(c_1 \cos(\beta \ln(x)) + c_2 \sin(\beta \ln(x)))$ basis solutions. And each complex root $\alpha \pm i\beta$ of multiplicity three generates $\ln(x)^2 x^\alpha(c_1 \cos(\beta \ln(x)) + c_2 \sin(\beta \ln(x)))$ basis solutions. And so on. Using the above show that the solution is

$$y = c_3x^3 + c_2x^2 + c_1x$$

The fundamental set of solutions for the homogeneous solution are the following

$$y_1 = x$$

$$y_2 = x^2$$

$$y_3 = x^3$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_3x^3 + c_2x^2 + c_1x \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 0$ and $x = 2$ in the above gives

$$0 = 8c_3 + 4c_2 + 2c_1 \quad (1A)$$

Taking derivative of the solution gives

$$y' = 3c_3x^2 + 2c_2x + c_1$$

substituting $y' = 2$ and $x = 2$ in the above gives

$$2 = 12c_3 + 4c_2 + c_1 \quad (2A)$$

Taking two derivatives of the solution gives

$$y'' = 6c_3x + 2c_2$$

substituting $y'' = 6$ and $x = 2$ in the above gives

$$6 = 12c_3 + 2c_2 \quad (3A)$$

Equations {1A,2A,3A} are now solved for $\{c_1, c_2, c_3\}$. Solving for the constants gives

$$c_1 = 2$$

$$c_2 = -3$$

$$c_3 = 1$$

Substituting these values back in above solution results in

$$y = x^3 - 3x^2 + 2x$$

Summary

The solution(s) found are the following

$$y = x^3 - 3x^2 + 2x \quad (1)$$

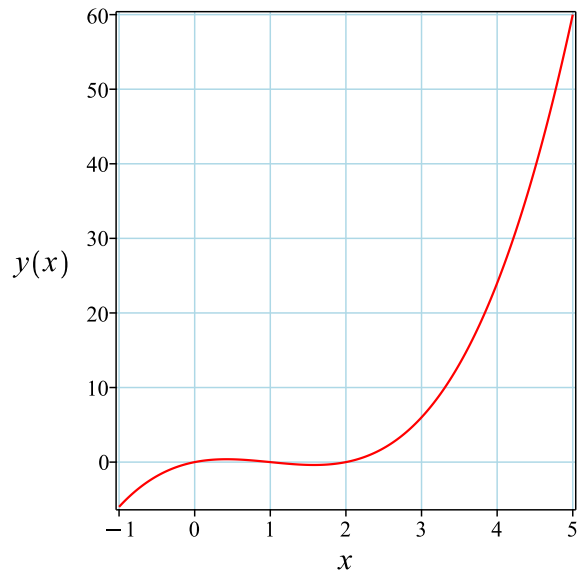


Figure 43: Solution plot

Verification of solutions

$$y = x^3 - 3x^2 + 2x$$

Verified OK.

2.8.1 Maple step by step solution

Let's solve

$$\left[x^3 y''' - 3y'' x^2 + 6y' x - 6y = 0, y(2) = 0, y'|_{\{x=2\}} = 2, y''|_{\{x=2\}} = 6 \right]$$

- Highest derivative means the order of the ODE is 3

$$y'''$$

- Isolate 3rd derivative

$$y''' = \frac{6y}{x^3} + \frac{3(y''x - 2y')}{x^2}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y''' - \frac{3y''}{x} + \frac{6y'}{x^2} - \frac{6y}{x^3} = 0$$

- Multiply by denominators of the ODE

$$x^3 y''' - 3y'' x^2 + 6y' x - 6y = 0$$

- Make a change of variables

$$t = \ln(x)$$

□ Substitute the change of variables back into the ODE

- Calculate the 1st derivative of y with respect to x , using the chain rule

$$y' = \left(\frac{d}{dt}y(t)\right) t'(x)$$

- Compute derivative

$$y' = \frac{\frac{d}{dt}y(t)}{x}$$

- Calculate the 2nd derivative of y with respect to x , using the chain rule

$$y'' = \left(\frac{d^2}{dt^2}y(t)\right) t'(x)^2 + t''(x) \left(\frac{d}{dt}y(t)\right)$$

- Compute derivative

$$y'' = \frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2}$$

- Calculate the 3rd derivative of y with respect to x , using the chain rule

$$y''' = \left(\frac{d^3}{dt^3}y(t)\right) t'(x)^3 + 3t'(x)t''(x) \left(\frac{d^2}{dt^2}y(t)\right) + t'''(x) \left(\frac{d}{dt}y(t)\right)$$

- Compute derivative

$$y''' = \frac{\frac{d^3}{dt^3}y(t)}{x^3} - \frac{3\left(\frac{d^2}{dt^2}y(t)\right)}{x^3} + \frac{2\left(\frac{d}{dt}y(t)\right)}{x^3}$$

Substitute the change of variables back into the ODE

$$x^3 \left(\frac{\frac{d^3}{dt^3}y(t)}{x^3} - \frac{3\left(\frac{d^2}{dt^2}y(t)\right)}{x^3} + \frac{2\left(\frac{d}{dt}y(t)\right)}{x^3} \right) - 3 \left(\frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2} \right) x^2 + 6 \frac{d}{dt}y(t) - 6y(t) = 0$$

• Simplify

$$\frac{d^3}{dt^3}y(t) - 6 \frac{d^2}{dt^2}y(t) + 11 \frac{d}{dt}y(t) - 6y(t) = 0$$

□ Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(t)$

$$y_1(t) = y(t)$$

- Define new variable $y_2(t)$

$$y_2(t) = \frac{d}{dt}y(t)$$

- Define new variable $y_3(t)$

$$y_3(t) = \frac{d^2}{dt^2}y(t)$$

- Isolate for $\frac{d}{dt}y_3(t)$ using original ODE

$$\frac{d}{dt}y_3(t) = 6y_3(t) - 11y_2(t) + 6y_1(t)$$

Convert linear ODE into a system of first order ODEs

$$[y_2(t) = \frac{d}{dt}y_1(t), y_3(t) = \frac{d}{dt}y_2(t), \frac{d}{dt}y_3(t) = 6y_3(t) - 11y_2(t) + 6y_1(t)]$$

- Define vector

$$\vec{y}(t) = \begin{bmatrix} y_1(t) \\ y_2(t) \\ y_3(t) \end{bmatrix}$$

- System to solve

$$\frac{d}{dt}\vec{y}(t) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 6 & -11 & 6 \end{bmatrix} \cdot \vec{y}(t)$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 6 & -11 & 6 \end{bmatrix}$$

- Rewrite the system as

$$\frac{d}{dt}\vec{y}(t) = A \cdot \vec{y}(t)$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[1, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right], \left[2, \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right], \left[3, \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[1, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_1 = e^t \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[2, \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_2 = e^{2t} \cdot \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[3, \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_3 = e^{3t} \cdot \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix}$$

- General solution to the system of ODEs

$$\vec{y} = c_1 \vec{y}_1 + c_2 \vec{y}_2 + c_3 \vec{y}_3$$

- Substitute solutions into the general solution

$$\vec{y} = c_1 e^t \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + c_2 e^{2t} \cdot \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} + c_3 e^{3t} \cdot \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y(t) = c_1 e^t + \frac{c_2 e^{2t}}{4} + \frac{c_3 e^{3t}}{9}$$

- Change variables back using $t = \ln(x)$
 $y = c_1x + \frac{1}{4}c_2x^2 + \frac{1}{9}c_3x^3$
- Use the initial condition $y(2) = 0$
 $0 = 2c_1 + c_2 + \frac{8c_3}{9}$
- Calculate the 1st derivative of the solution
 $y' = c_1 + \frac{1}{2}c_2x + \frac{1}{3}c_3x^2$
- Use the initial condition $y'|_{\{x=2\}} = 2$
 $2 = c_1 + c_2 + \frac{4c_3}{3}$
- Calculate the 2nd derivative of the solution
 $y'' = \frac{c_2}{2} + \frac{2c_3x}{3}$
- Use the initial condition $y''|_{\{x=2\}} = 6$
 $6 = \frac{c_2}{2} + \frac{4c_3}{3}$
- Solve for the unknown coefficients
 $\{c_1 = 2, c_2 = -12, c_3 = 9, x = x\}$
- Solution to the IVP
 $y = x^3 - 3x^2 + 2x$

Maple trace

```

`Methods for third order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
<- LODE of Euler type successful`

```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 16

```
dsolve([x^3*diff(y(x),x$3)-3*x^2*diff(y(x),x$2)+6*x*diff(y(x),x)-6*y(x)=0,y(2) = 0, D(y)(2)
```

$$y(x) = x^3 - 3x^2 + 2x$$

✓ Solution by Mathematica

Time used: 0.013 (sec). Leaf size: 15

```
DSolve[{x^3*y''[x]-3*x^2*y'[x]+6*x*y[x]-6*y[x]==0,{y[2]==0,y'[2]==2,y''[2]==6}},y[x],x,Integrate]
```

$$y(x) \rightarrow x(x^2 - 3x + 2)$$

2.9 problem 6(a)

2.9.1	Existence and uniqueness analysis	247
2.9.2	Solving as separable ode	248
2.9.3	Solving as first order ode lie symmetry lookup ode	249
2.9.4	Solving as exact ode	254
2.9.5	Maple step by step solution	257

Internal problem ID [11593]

Internal file name [OUTPUT/10575_Thursday_May_18_2023_05_56_39_PM_18318295/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 1, section 1.3. Exercises page 22

Problem number: 6(a).

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"exact", "separable", "first_order_ode_lie_symmetry_lookup"**

Maple gives the following as the ode type

`[_separable]`

$$y' - x^2 \sin(y) = 0$$

With initial conditions

$$[y(1) = -2]$$

2.9.1 Existence and uniqueness analysis

This is non linear first order ODE. In canonical form it is written as

$$\begin{aligned}y' &= f(x, y) \\ &= x^2 \sin(y)\end{aligned}$$

The x domain of $f(x, y)$ when $y = -2$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 1$ is inside this domain. The y domain of $f(x, y)$ when $x = 1$ is

$$\{-\infty < y < \infty\}$$

And the point $y_0 = -2$ is inside this domain. Now we will look at the continuity of

$$\begin{aligned}\frac{\partial f}{\partial y} &= \frac{\partial}{\partial y}(x^2 \sin(y)) \\ &= x^2 \cos(y)\end{aligned}$$

The x domain of $\frac{\partial f}{\partial y}$ when $y = -2$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 1$ is inside this domain. The y domain of $\frac{\partial f}{\partial y}$ when $x = 1$ is

$$\{-\infty < y < \infty\}$$

And the point $y_0 = -2$ is inside this domain. Therefore solution exists and is unique.

2.9.2 Solving as separable ode

In canonical form the ODE is

$$\begin{aligned}y' &= F(x, y) \\ &= f(x)g(y) \\ &= x^2 \sin(y)\end{aligned}$$

Where $f(x) = x^2$ and $g(y) = \sin(y)$. Integrating both sides gives

$$\begin{aligned}\frac{1}{\sin(y)} dy &= x^2 dx \\ \int \frac{1}{\sin(y)} dy &= \int x^2 dx \\ \ln(\csc(y) - \cot(y)) &= \frac{x^3}{3} + c_1\end{aligned}$$

Raising both side to exponential gives

$$\csc(y) - \cot(y) = e^{\frac{x^3}{3} + c_1}$$

Which simplifies to

$$\csc(y) - \cot(y) = c_2 e^{\frac{x^3}{3}}$$

Initial conditions are used to solve for c_1 . Substituting $x = 1$ and $y = -2$ in the above solution gives an equation to solve for the constant of integration.

$$-2 = -i \ln \left(\frac{-e^{c_1 + \frac{1}{3}} c_2 + i}{e^{c_1 + \frac{1}{3}} c_2 + i} \right)$$

$$c_1 = -\frac{1}{3} + \ln \left(-\frac{i(e^{-2i} - 1)}{c_2(e^{-2i} + 1)} \right)$$

Substituting c_1 found above in the general solution gives

$$y = -i \ln \left(\frac{-c_2 e^{\frac{x^3}{3} - \frac{1}{3} + \ln \left(-\frac{i(e^{-2i} - 1)}{c_2(e^{-2i} + 1)} \right)} + i}{c_2 e^{\frac{x^3}{3} - \frac{1}{3} + \ln \left(-\frac{i(e^{-2i} - 1)}{c_2(e^{-2i} + 1)} \right)} + i} \right)$$

Summary

The solution(s) found are the following

$$y = -i \ln \left(\frac{-c_2 e^{\frac{x^3}{3} - \frac{1}{3} + \ln \left(-\frac{i(e^{-2i} - 1)}{c_2(e^{-2i} + 1)} \right)} + i}{c_2 e^{\frac{x^3}{3} - \frac{1}{3} + \ln \left(-\frac{i(e^{-2i} - 1)}{c_2(e^{-2i} + 1)} \right)} + i} \right) \quad (1)$$

Verification of solutions

$$y = -i \ln \left(\frac{-c_2 e^{\frac{x^3}{3} - \frac{1}{3} + \ln \left(-\frac{i(e^{-2i} - 1)}{c_2(e^{-2i} + 1)} \right)} + i}{c_2 e^{\frac{x^3}{3} - \frac{1}{3} + \ln \left(-\frac{i(e^{-2i} - 1)}{c_2(e^{-2i} + 1)} \right)} + i} \right)$$

Verified OK.

2.9.3 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = x^2 \sin(y)$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **separable**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 47: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned} \xi(x, y) &= \frac{1}{x^2} \\ \eta(x, y) &= 0 \end{aligned} \quad (\text{A1})$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \quad (1)$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\eta = 0$ then in this special case

$$R = y$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\xi} dx \\ &= \int \frac{1}{\frac{1}{x^2}} dx \end{aligned}$$

Which results in

$$S = \frac{x^3}{3}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = x^2 \sin(y)$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 0 \\ R_y &= 1 \\ S_x &= x^2 \\ S_y &= 0 \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = \csc(y) \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = \csc(R)$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = -\ln(\csc(R) + \cot(R)) + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$\frac{x^3}{3} = -\ln(\csc(y) + \cot(y)) + c_1$$

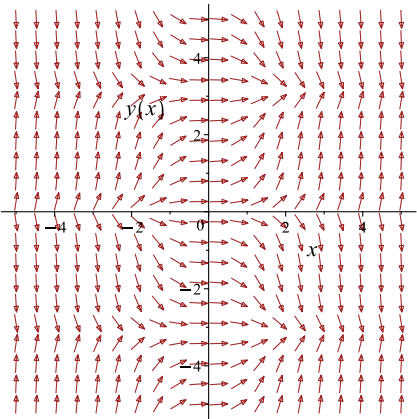
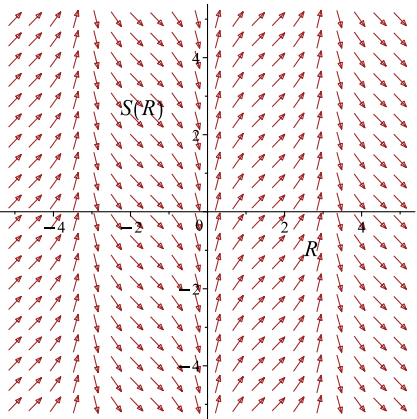
Which simplifies to

$$\frac{x^3}{3} = -\ln(\csc(y) + \cot(y)) + c_1$$

Which gives

$$y = \arctan\left(\frac{2e^{-\frac{x^3}{3}+c_1}}{e^{-\frac{2x^3}{3}+2c_1}+1}, \frac{e^{-\frac{2x^3}{3}+2c_1}-1}{e^{-\frac{2x^3}{3}+2c_1}+1}\right)$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = x^2 \sin(y)$ 	$R = y$ $S = \frac{x^3}{3}$	$\frac{dS}{dR} = \csc(R)$ 

Initial conditions are used to solve for c_1 . Substituting $x = 1$ and $y = -2$ in the above solution gives an equation to solve for the constant of integration.

$$-2 = -i \ln \left(\frac{-e^{-\frac{1}{3}+c_1} - i}{-e^{-\frac{1}{3}+c_1} + i} \right)$$

$$c_1 = \frac{1}{3} + \ln \left(\frac{i(e^{-2i} + 1)}{e^{-2i} - 1} \right)$$

Substituting c_1 found above in the general solution gives

$$y = -i \ln \left(\frac{-e^{-\frac{x^3}{3} + \frac{1}{3} + \ln \left(\frac{i(e^{-2i} + 1)}{e^{-2i} - 1} \right)} - i}{-e^{-\frac{x^3}{3} + \frac{1}{3} + \ln \left(\frac{i(e^{-2i} + 1)}{e^{-2i} - 1} \right)} + i} \right)$$

Summary

The solution(s) found are the following

$$y = -i \ln \left(\frac{-e^{-\frac{x^3}{3} + \frac{1}{3} + \ln \left(\frac{i(e^{-2i} + 1)}{e^{-2i} - 1} \right)} - i}{-e^{-\frac{x^3}{3} + \frac{1}{3} + \ln \left(\frac{i(e^{-2i} + 1)}{e^{-2i} - 1} \right)} + i} \right) \quad (1)$$

Verification of solutions

$$y = -i \ln \left(\frac{-e^{-\frac{x^3}{3} + \frac{1}{3} + \ln \left(\frac{i(e^{-2i} + 1)}{e^{-2i} - 1} \right)} - i}{-e^{-\frac{x^3}{3} + \frac{1}{3} + \ln \left(\frac{i(e^{-2i} + 1)}{e^{-2i} - 1} \right)} + i} \right)$$

Verified OK.

2.9.4 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \quad (\text{A})$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \quad (\text{B})$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (\text{1A})$$

Therefore

$$\begin{aligned} \left(\frac{1}{\sin(y)}\right) dy &= (x^2) dx \\ (-x^2) dx + \left(\frac{1}{\sin(y)}\right) dy &= 0 \end{aligned} \tag{2A}$$

Comparing (1A) and (2A) shows that

$$\begin{aligned} M(x, y) &= -x^2 \\ N(x, y) &= \frac{1}{\sin(y)} \end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned} \frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(-x^2) \\ &= 0 \end{aligned}$$

And

$$\begin{aligned} \frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}\left(\frac{1}{\sin(y)}\right) \\ &= 0 \end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \tag{1}$$

$$\frac{\partial \phi}{\partial y} = N \tag{2}$$

Integrating (1) w.r.t. x gives

$$\begin{aligned} \int \frac{\partial \phi}{\partial x} dx &= \int M dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int -x^2 dx \\ \phi &= -\frac{x^3}{3} + f(y) \end{aligned} \tag{3}$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = 0 + f'(y) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = \frac{1}{\sin(y)}$. Therefore equation (4) becomes

$$\frac{1}{\sin(y)} = 0 + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$\begin{aligned} f'(y) &= \frac{1}{\sin(y)} \\ &= \csc(y) \end{aligned}$$

Integrating the above w.r.t y results in

$$\begin{aligned} \int f'(y) dy &= \int (\csc(y)) dy \\ f(y) &= -\ln(\csc(y) + \cot(y)) + c_1 \end{aligned}$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = -\frac{x^3}{3} - \ln(\csc(y) + \cot(y)) + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -\frac{x^3}{3} - \ln(\csc(y) + \cot(y))$$

Initial conditions are used to solve for c_1 . Substituting $x = 1$ and $y = -2$ in the above solution gives an equation to solve for the constant of integration.

$$-\frac{1}{3} - \ln(\cos(2) + 1) + \ln(\sin(2)) - i\pi = c_1$$

$$c_1 = -\frac{1}{3} - \ln(\cos(2) + 1) + \ln(\sin(2)) - i\pi$$

Substituting c_1 found above in the general solution gives

$$-\frac{x^3}{3} - \ln(\csc(y) + \cot(y)) = -\frac{1}{3} - \ln(\cos(2) + 1) + \ln(\sin(2)) - i\pi$$

Summary

The solution(s) found are the following

$$-\frac{x^3}{3} - \ln(\csc(y) + \cot(y)) = -\frac{1}{3} - \ln(\cos(2) + 1) + \ln(\sin(2)) - i\pi \quad (1)$$

Verification of solutions

$$-\frac{x^3}{3} - \ln(\csc(y) + \cot(y)) = -\frac{1}{3} - \ln(\cos(2) + 1) + \ln(\sin(2)) - i\pi$$

Verified OK.

2.9.5 Maple step by step solution

Let's solve

$$[y' - x^2 \sin(y) = 0, y(1) = -2]$$

- Highest derivative means the order of the ODE is 1

$$y'$$

- Separate variables

$$\frac{y'}{\sin(y)} = x^2$$

- Integrate both sides with respect to x

$$\int \frac{y'}{\sin(y)} dx = \int x^2 dx + c_1$$

- Evaluate integral

$$\ln(\csc(y) - \cot(y)) = \frac{x^3}{3} + c_1$$

- Solve for y

$$y = \arctan\left(\frac{2e^{\frac{x^3}{3} + c_1}}{\left(e^{\frac{x^3}{3} + c_1}\right)^2 + 1}, -\frac{\left(e^{\frac{x^3}{3} + c_1}\right)^2 - 1}{\left(e^{\frac{x^3}{3} + c_1}\right)^2 + 1}\right)$$

- Use initial condition $y(1) = -2$

$$-2 = \arctan \left(\frac{2e^{c_1 + \frac{1}{3}}}{(e^{c_1 + \frac{1}{3}})^2 + 1}, -\frac{(e^{c_1 + \frac{1}{3}})^2 - 1}{(e^{c_1 + \frac{1}{3}})^2 + 1} \right)$$

- Solution does not satisfy initial condition

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
trying separable
<- separable successful`

```

✓ Solution by Maple

Time used: 1.844 (sec). Leaf size: 97

```
dsolve([diff(y(x),x)=x^2*sin(y(x)),y(1) = -2],y(x), singsol=all)
```

$y(x)$

$$= \arctan \left(\frac{2 \sin(2) e^{\frac{(-1+x)(x^2+x+1)}{3}}}{(-1 + \cos(2)) e^{\frac{2(-1+x)(x^2+x+1)}{3}} - 1 - \cos(2)}, \frac{(1 - \cos(2)) e^{\frac{2(-1+x)(x^2+x+1)}{3}} - 1 - \cos(2)}{(-1 + \cos(2)) e^{\frac{2(-1+x)(x^2+x+1)}{3}} - 1 - \cos(2)} \right)$$

✓ Solution by Mathematica

Time used: 0.68 (sec). Leaf size: 23

```
DSolve[{y'[x]==x^2*Sin[y[x]],{y[1]==-2}},y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow -\arccos \left(\tanh \left(\operatorname{arctanh}(\cos(2)) - \frac{x^3}{3} + \frac{1}{3} \right) \right)$$

2.10 problem 6(b)

2.10.1 Existence and uniqueness analysis	259
2.10.2 Solving as separable ode	260
2.10.3 Solving as first order ode lie symmetry lookup ode	261
2.10.4 Solving as exact ode	265
2.10.5 Solving as riccati ode	269
2.10.6 Maple step by step solution	271

Internal problem ID [11594]

Internal file name [OUTPUT/10576_Thursday_May_18_2023_05_59_06_PM_8400801/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 1, section 1.3. Exercises page 22

Problem number: 6(b).

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact", "riccati", "separable", "first_order_ode_lie_symmetry_lookup"

Maple gives the following as the ode type

[_separable]

$$y' - \frac{y^2}{x-2} = 0$$

With initial conditions

$$[y(1) = 0]$$

2.10.1 Existence and uniqueness analysis

This is non linear first order ODE. In canonical form it is written as

$$\begin{aligned} y' &= f(x, y) \\ &= \frac{y^2}{x-2} \end{aligned}$$

The x domain of $f(x, y)$ when $y = 0$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 1$ is inside this domain. The y domain of $f(x, y)$ when $x = 1$ is

$$\{-\infty < y < \infty\}$$

And the point $y_0 = 0$ is inside this domain. Now we will look at the continuity of

$$\begin{aligned}\frac{\partial f}{\partial y} &= \frac{\partial}{\partial y} \left(\frac{y^2}{x-2} \right) \\ &= \frac{2y}{x-2}\end{aligned}$$

The x domain of $\frac{\partial f}{\partial y}$ when $y = 0$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 1$ is inside this domain. The y domain of $\frac{\partial f}{\partial y}$ when $x = 1$ is

$$\{-\infty < y < \infty\}$$

And the point $y_0 = 0$ is inside this domain. Therefore solution exists and is unique.

2.10.2 Solving as separable ode

In canonical form the ODE is

$$\begin{aligned}y' &= F(x, y) \\ &= f(x)g(y) \\ &= \frac{y^2}{x-2}\end{aligned}$$

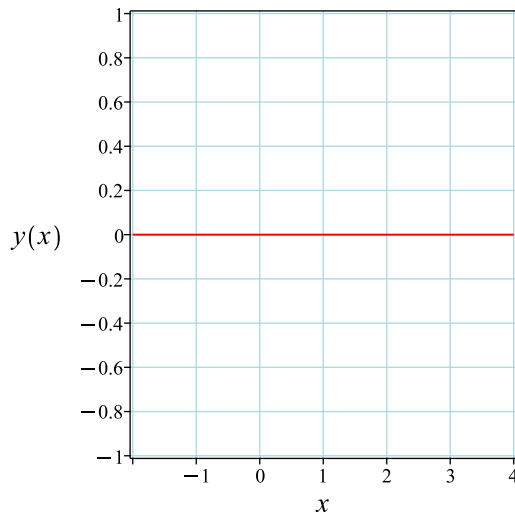
Where $f(x) = \frac{1}{x-2}$ and $g(y) = y^2$. Since unique solution exists and $g(y)$ evaluated at $y_0 = 0$ is zero, then the solution is

$$\begin{aligned}y &= y_0 \\ &= 0\end{aligned}$$

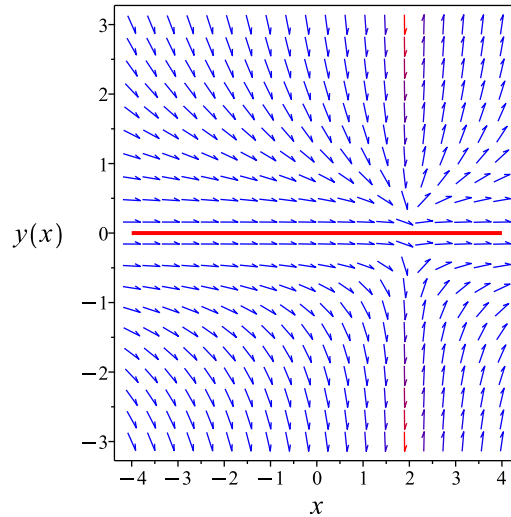
Summary

The solution(s) found are the following

$$y = 0 \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = 0$$

Verified OK.

2.10.3 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = \frac{y^2}{x-2}$$
$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \tag{A}$$

The type of this ode is known. It is of type **separable**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 50: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int(n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= x - 2 \\ \eta(x, y) &= 0\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\eta = 0$ then in this special case

$$R = y$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\xi} dx \\ &= \int \frac{1}{x-2} dx \end{aligned}$$

Which results in

$$S = \ln(x-2)$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = \frac{y^2}{x-2}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 0 \\ R_y &= 1 \\ S_x &= \frac{1}{x-2} \\ S_y &= 0 \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = \frac{1}{y^2} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = \frac{1}{R^2}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = -\frac{1}{R} + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$\ln(x - 2) = -\frac{1}{y} + c_1$$

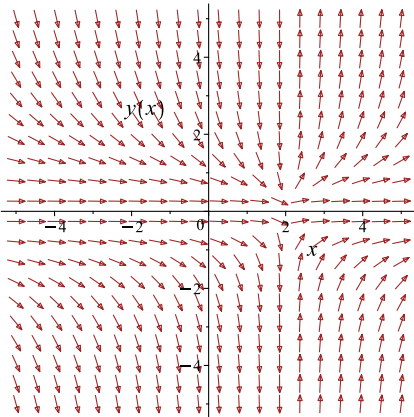
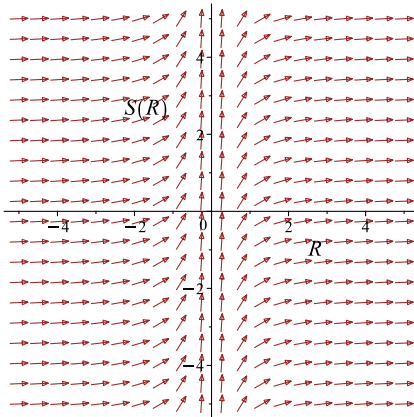
Which simplifies to

$$\ln(x - 2) = -\frac{1}{y} + c_1$$

Which gives

$$y = -\frac{1}{\ln(x - 2) - c_1}$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = \frac{y^2}{x-2}$ 	$R = y$ $S = \ln(x - 2)$	$\frac{dS}{dR} = \frac{1}{R^2}$ 

Initial conditions are used to solve for c_1 . Substituting $x = 1$ and $y = 0$ in the above solution gives an equation to solve for the constant of integration.

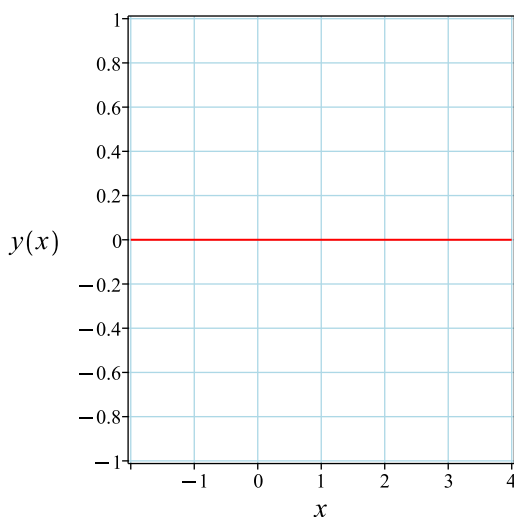
$$0 = -\frac{1}{i\pi - c_1}$$

Unable to solve for constant of integration. Since $\lim_{c_1 \rightarrow \infty} y = -\frac{1}{\ln(x-2)-c_1} = y = 0$

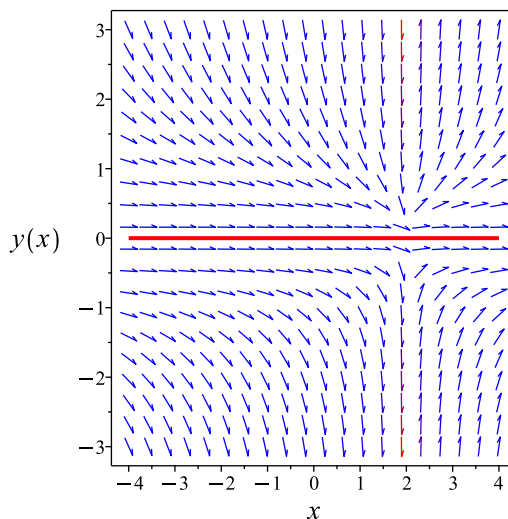
Summary

and this result satisfies the given initial condition. The solution(s) found are the following

$$y = 0$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = 0$$

Verified OK.

2.10.4 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx}\phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \quad (\text{B})$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (\text{1A})$$

Therefore

$$\begin{aligned} \left(\frac{1}{y^2}\right) dy &= \left(\frac{1}{x-2}\right) dx \\ \left(-\frac{1}{x-2}\right) dx + \left(\frac{1}{y^2}\right) dy &= 0 \end{aligned} \quad (\text{2A})$$

Comparing (1A) and (2A) shows that

$$\begin{aligned} M(x, y) &= -\frac{1}{x-2} \\ N(x, y) &= \frac{1}{y^2} \end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned} \frac{\partial M}{\partial y} &= \frac{\partial}{\partial y} \left(-\frac{1}{x-2}\right) \\ &= 0 \end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x} \left(\frac{1}{y^2} \right) \\ &= 0\end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \tag{1}$$

$$\frac{\partial \phi}{\partial y} = N \tag{2}$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int M dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int -\frac{1}{x-2} dx \\ \phi &= -\ln(x-2) + f(y)\end{aligned} \tag{3}$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = 0 + f'(y) \tag{4}$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = \frac{1}{y^2}$. Therefore equation (4) becomes

$$\frac{1}{y^2} = 0 + f'(y) \tag{5}$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = \frac{1}{y^2}$$

Integrating the above w.r.t y gives

$$\begin{aligned}\int f'(y) dy &= \int \left(\frac{1}{y^2} \right) dy \\ f(y) &= -\frac{1}{y} + c_1\end{aligned}$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = -\ln(x-2) - \frac{1}{y} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -\ln(x-2) - \frac{1}{y}$$

The solution becomes

$$y = -\frac{1}{\ln(x-2) + c_1}$$

Initial conditions are used to solve for c_1 . Substituting $x = 1$ and $y = 0$ in the above solution gives an equation to solve for the constant of integration.

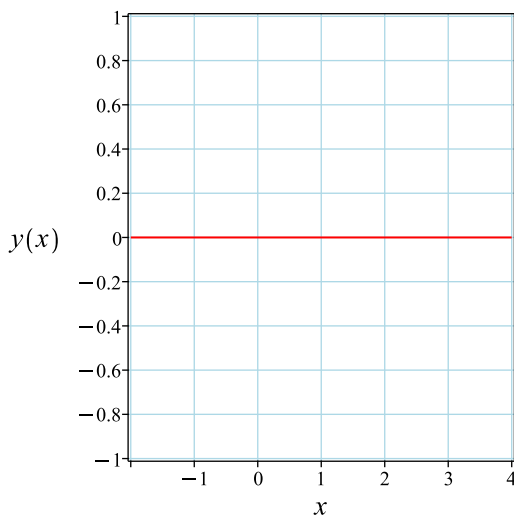
$$0 = -\frac{1}{\ln(1-2) + c_1}$$

Unable to solve for constant of integration. Since $\lim_{c_1 \rightarrow \infty} y = -\frac{1}{\ln(x-2)+c_1} = y = 0$

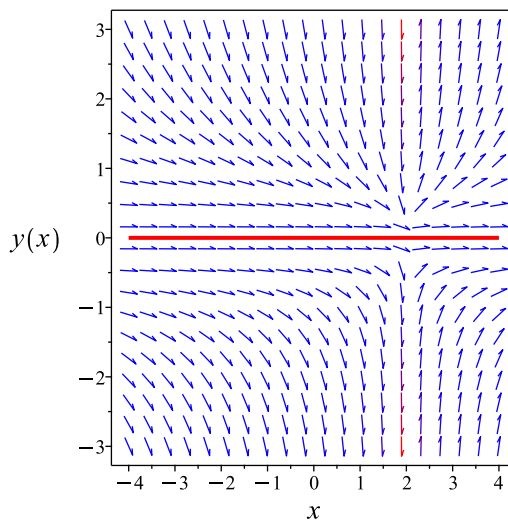
Summary

and this result satisfies the given initial condition. The solution(s) found are the following

$$y = 0$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = 0$$

Verified OK.

2.10.5 Solving as riccati ode

In canonical form the ODE is

$$\begin{aligned}y' &= F(x, y) \\ &= \frac{y^2}{x-2}\end{aligned}$$

This is a Riccati ODE. Comparing the ODE to solve

$$y' = \frac{y^2}{x-2}$$

With Riccati ODE standard form

$$y' = f_0(x) + f_1(x)y + f_2(x)y^2$$

Shows that $f_0(x) = 0$, $f_1(x) = 0$ and $f_2(x) = \frac{1}{x-2}$. Let

$$\begin{aligned}y &= \frac{-u'}{f_2 u} \\ &= \frac{-u'}{\frac{u}{x-2}}\end{aligned}\tag{1}$$

Using the above substitution in the given ODE results (after some simplification) in a second order ODE to solve for $u(x)$ which is

$$f_2 u''(x) - (f_2' + f_1 f_2) u'(x) + f_2^2 f_0 u(x) = 0\tag{2}$$

But

$$\begin{aligned}f_2' &= -\frac{1}{(x-2)^2} \\ f_1 f_2 &= 0 \\ f_2^2 f_0 &= 0\end{aligned}$$

Substituting the above terms back in equation (2) gives

$$\frac{u''(x)}{x-2} + \frac{u'(x)}{(x-2)^2} = 0$$

Solving the above ODE (this ode solved using Maple, not this program), gives

$$u(x) = c_2 \ln(x - 2) + c_1$$

The above shows that

$$u'(x) = \frac{c_2}{x - 2}$$

Using the above in (1) gives the solution

$$y = -\frac{c_2}{c_2 \ln(x - 2) + c_1}$$

Dividing both numerator and denominator by c_1 gives, after renaming the constant $\frac{c_2}{c_1} = c_3$ the following solution

$$y = -\frac{1}{\ln(x - 2) + c_3}$$

Initial conditions are used to solve for c_3 . Substituting $x = 1$ and $y = 0$ in the above solution gives an equation to solve for the constant of integration.

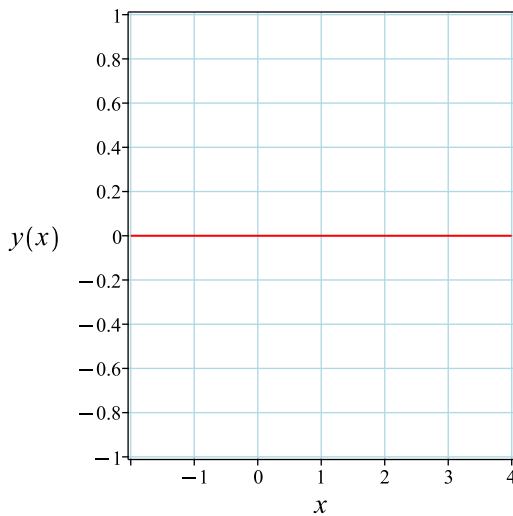
$$0 = -\frac{1}{i\pi + c_3}$$

Unable to solve for constant of integration. Since $\lim_{c_1 \rightarrow \infty}$ gives $y = -\frac{1}{\ln(x-2)+c_3} = y = 0$

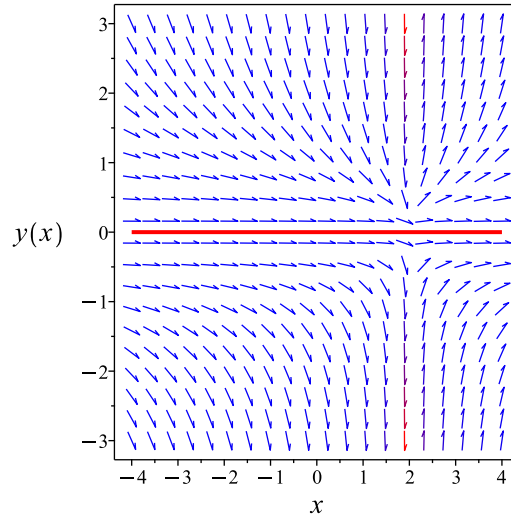
Summary

and this result satisfies the given initial condition. The solution(s) found are the following

$$y = 0$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = 0$$

Verified OK.

2.10.6 Maple step by step solution

Let's solve

$$\left[y' - \frac{y^2}{x-2} = 0, y(1) = 0 \right]$$

- Highest derivative means the order of the ODE is 1

$$y'$$

- Separate variables

$$\frac{y'}{y^2} = \frac{1}{x-2}$$

- Integrate both sides with respect to x

$$\int \frac{y'}{y^2} dx = \int \frac{1}{x-2} dx + c_1$$

- Evaluate integral

$$-\frac{1}{y} = \ln(x-2) + c_1$$

- Solve for y

$$y = -\frac{1}{\ln(x-2)+c_1}$$

- Use initial condition $y(1) = 0$

$$0 = -\frac{1}{1\pi + c_1}$$
- Solution does not satisfy initial condition

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
<- Bernoulli successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 5

```
dsolve([diff(y(x),x)=y(x)^2/(x-2),y(1) = 0],y(x), singsol=all)
```

$$y(x) = 0$$

✓ Solution by Mathematica

Time used: 0.002 (sec). Leaf size: 6

```
DSolve[{y'[x]==y[x]^2/(x-2),{y[1]==0}},y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow 0$$

2.11 problem 8

2.11.1 Existence and uniqueness analysis	273
2.11.2 Solving as quadrature ode	274
2.11.3 Maple step by step solution	275

Internal problem ID [11595]

Internal file name [OUTPUT/10577_Thursday_May_18_2023_05_59_06_PM_93747806/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 1, section 1.3. Exercises page 22

Problem number: 8.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**quadrature**"

Maple gives the following as the ode type

[_quadrature]

$$y' - y^{\frac{1}{3}} = 0$$

With initial conditions

$$[y(0) = 0]$$

2.11.1 Existence and uniqueness analysis

This is non linear first order ODE. In canonical form it is written as

$$\begin{aligned}y' &= f(x, y) \\ &= y^{\frac{1}{3}}\end{aligned}$$

The y domain of $f(x, y)$ when $x = 0$ is

$$\{0 \leq y\}$$

And the point $y_0 = 0$ is inside this domain. Now we will look at the continuity of

$$\begin{aligned}\frac{\partial f}{\partial y} &= \frac{\partial}{\partial y} \left(y^{\frac{1}{3}} \right) \\ &= \frac{1}{3y^{\frac{2}{3}}}\end{aligned}$$

The y domain of $\frac{\partial f}{\partial y}$ when $x = 0$ is

$$\{0 < y\}$$

But the point $y_0 = 0$ is not inside this domain. Hence existence and uniqueness theorem does not apply. Solution exists but no guarantee that unique solution exists.

2.11.2 Solving as quadrature ode

Integrating both sides gives

$$\int \frac{1}{y^{\frac{1}{3}}} dy = \int dx$$
$$\frac{3y^{\frac{2}{3}}}{2} = x + c_1$$

Initial conditions are used to solve for c_1 . Substituting $x = 0$ and $y = 0$ in the above solution gives an equation to solve for the constant of integration.

$$0 = c_1$$

$$c_1 = 0$$

Substituting c_1 found above in the general solution gives

$$\frac{3y^{\frac{2}{3}}}{2} = x$$

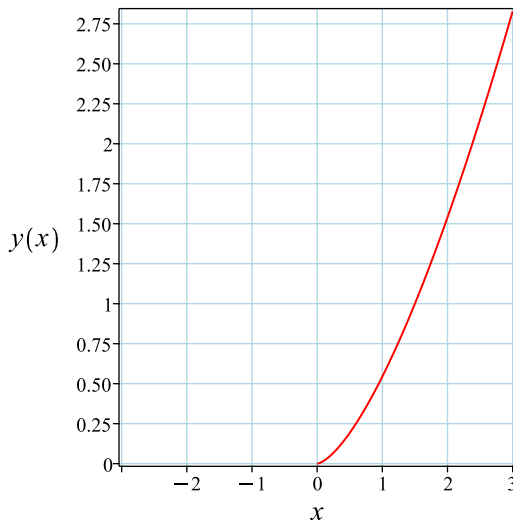
Solving for y from the above gives

$$y = \frac{2x^{\frac{3}{2}}\sqrt{6}}{9}$$

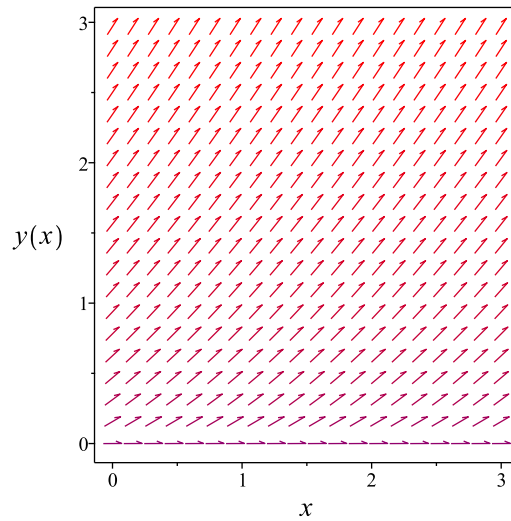
Summary

The solution(s) found are the following

$$y = \frac{2x^{\frac{3}{2}}\sqrt{6}}{9} \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \frac{2x^{\frac{3}{2}}\sqrt{6}}{9}$$

Verified OK.

2.11.3 Maple step by step solution

Let's solve

$$\left[y' - y^{\frac{1}{3}} = 0, y(0) = 0 \right]$$

- Highest derivative means the order of the ODE is 1

y'

- Separate variables

$$\frac{y'}{y^{\frac{1}{3}}} = 1$$

- Integrate both sides with respect to x

$$\int \frac{y'}{y^{\frac{1}{3}}} dx = \int 1 dx + c_1$$

- Evaluate integral

$$\frac{3y^{\frac{2}{3}}}{2} = x + c_1$$

- Solve for y

$$y = \frac{(6x+6c_1)^{\frac{3}{2}}}{27}$$

- Use initial condition $y(0) = 0$

$$0 = \frac{2\sqrt{6}c_1^{\frac{3}{2}}}{9}$$

- Solve for c_1

$$c_1 = 0$$

- Substitute $c_1 = 0$ into general solution and simplify

$$y = \frac{2x^{\frac{3}{2}}\sqrt{6}}{9}$$

- Solution to the IVP

$$y = \frac{2x^{\frac{3}{2}}\sqrt{6}}{9}$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
<- Bernoulli successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 5

```
dsolve([diff(y(x),x)=y(x)^(1/3),y(0) = 0],y(x), singsol=all)
```

$$y(x) = 0$$

✓ Solution by Mathematica

Time used: 0.007 (sec). Leaf size: 21

```
DSolve[{y'[x]==y[x]^(1/3)},{y[0]==0}],y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{2}{3}\sqrt{\frac{2}{3}}x^{3/2}$$

3 Chapter 2, section 2.1 (Exact differential equations and integrating factors). Exercises
page 37

3.1	problem 1	278
3.2	problem 2	294
3.3	problem 3	301
3.4	problem 4	309
3.5	problem 5	312
3.6	problem 7	319
3.7	problem 8	326
3.8	problem 9	333
3.9	problem 10	345
3.10	problem 11	348
3.11	problem 12	357
3.12	problem 13	362
3.13	problem 14	369
3.14	problem 15	374
3.15	problem 16	389
3.16	problem 21	403
3.17	problem 22	416
3.18	problem 24	434

3.1 problem 1

3.1.1	Solving as homogeneousTypeD2 ode	278
3.1.2	Solving as differentialType ode	280
3.1.3	Solving as first order ode lie symmetry calculated ode	282
3.1.4	Solving as exact ode	287
3.1.5	Maple step by step solution	291

Internal problem ID [11596]

Internal file name [OUTPUT/10578_Thursday_May_18_2023_05_59_07_PM_71828352/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 2, section 2.1 (Exact differential equations and integrating factors). Exercises page 37

Problem number: 1.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact", "differentialType", "homogeneousTypeD2", "first_order_ode_lie_symmetry_calculated"

Maple gives the following as the ode type

```
[[_homogeneous, `class A`], _exact, _rational, [_Abel, `2nd type`, `class A`]]
```

$$2y + (2x + y)y' = -3x$$

3.1.1 Solving as homogeneousTypeD2 ode

Using the change of variables $y = u(x)x$ on the above ode results in new ode in $u(x)$

$$2u(x)x + (2x + u(x)x)(u'(x)x + u(x)) = -3x$$

In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= -\frac{u^2 + 4u + 3}{x(u + 2)} \end{aligned}$$

Where $f(x) = -\frac{1}{x}$ and $g(u) = \frac{u^2+4u+3}{u+2}$. Integrating both sides gives

$$\frac{1}{\frac{u^2+4u+3}{u+2}} du = -\frac{1}{x} dx$$

$$\int \frac{1}{\frac{u^2+4u+3}{u+2}} du = \int -\frac{1}{x} dx$$

$$\frac{\ln(u^2 + 4u + 3)}{2} = -\ln(x) + c_2$$

Raising both side to exponential gives

$$\sqrt{u^2 + 4u + 3} = e^{-\ln(x)+c_2}$$

Which simplifies to

$$\sqrt{u^2 + 4u + 3} = \frac{c_3}{x}$$

Which simplifies to

$$\sqrt{u(x)^2 + 4u(x) + 3} = \frac{c_3 e^{c_2}}{x}$$

The solution is

$$\sqrt{u(x)^2 + 4u(x) + 3} = \frac{c_3 e^{c_2}}{x}$$

Replacing $u(x)$ in the above solution by $\frac{y}{x}$ results in the solution for y in implicit form

$$\sqrt{\frac{y^2}{x^2} + \frac{4y}{x} + 3} = \frac{c_3 e^{c_2}}{x}$$

$$\sqrt{\frac{y^2 + 4yx + 3x^2}{x^2}} = \frac{c_3 e^{c_2}}{x}$$

Which simplifies to

$$\sqrt{\frac{(3x + y)(y + x)}{x^2}} = \frac{c_3 e^{c_2}}{x}$$

Summary

The solution(s) found are the following

$$\sqrt{\frac{(3x + y)(y + x)}{x^2}} = \frac{c_3 e^{c_2}}{x} \quad (1)$$

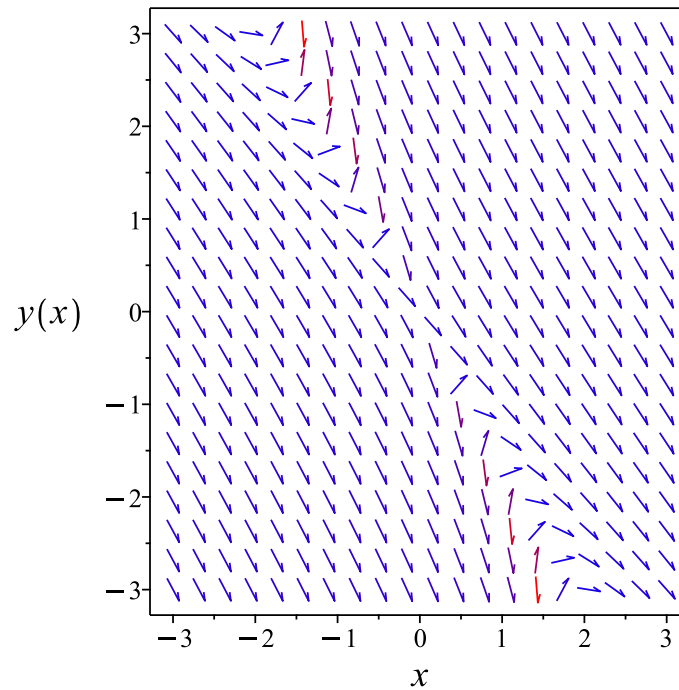


Figure 49: Slope field plot

Verification of solutions

$$\sqrt{\frac{(3x + y)(y + x)}{x^2}} = \frac{c_3 e^{c_2}}{x}$$

Verified OK.

3.1.2 Solving as differentialType ode

Writing the ode as

$$y' = \frac{-3x - 2y}{2x + y} \tag{1}$$

Which becomes

$$(y) dy = (-2x) dy + (-3x - 2y) dx \tag{2}$$

But the RHS is complete differential because

$$(-2x) dy + (-3x - 2y) dx = d\left(-\frac{3}{2}x^2 - 2xy\right)$$

Hence (2) becomes

$$(y) dy = d\left(-\frac{3}{2}x^2 - 2xy\right)$$

Integrating both sides gives these solutions

$$y = -2x + \sqrt{x^2 + 2c_1} + c_1$$

$$y = -2x - \sqrt{x^2 + 2c_1} + c_1$$

Summary

The solution(s) found are the following

$$y = -2x + \sqrt{x^2 + 2c_1} + c_1 \tag{1}$$

$$y = -2x - \sqrt{x^2 + 2c_1} + c_1 \tag{2}$$

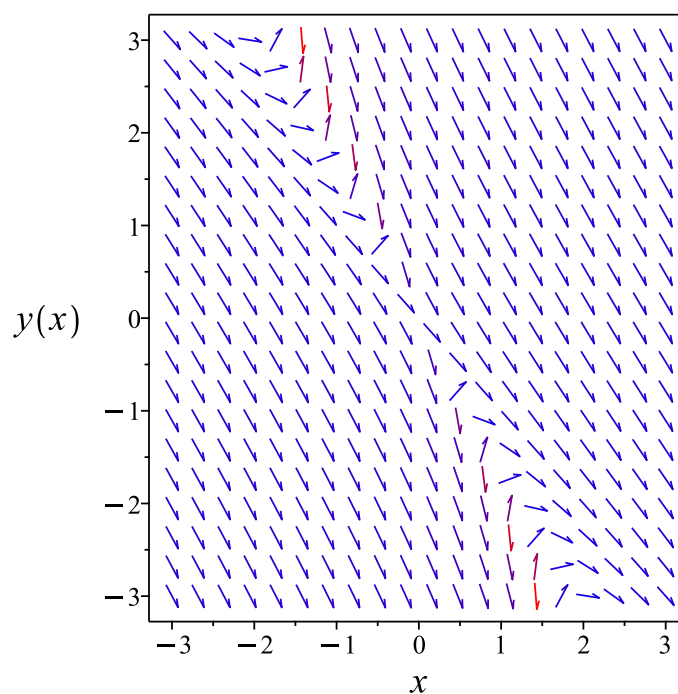


Figure 50: Slope field plot

Verification of solutions

$$y = -2x + \sqrt{x^2 + 2c_1} + c_1$$

Verified OK.

$$y = -2x - \sqrt{x^2 + 2c_1} + c_1$$

Verified OK.

3.1.3 Solving as first order ode lie symmetry calculated ode

Writing the ode as

$$y' = -\frac{3x+2y}{2x+y}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is not in the lookup table. To determine ξ, η then (A) is solved using ansatz. Making bivariate polynomials of degree 1 to use as anstaz gives

$$\xi = xa_2 + ya_3 + a_1 \quad (\text{1E})$$

$$\eta = xb_2 + yb_3 + b_1 \quad (\text{2E})$$

Where the unknown coefficients are

$$\{a_1, a_2, a_3, b_1, b_2, b_3\}$$

Substituting equations (1E,2E) and ω into (A) gives

$$b_2 - \frac{(3x+2y)(b_3-a_2)}{2x+y} - \frac{(3x+2y)^2 a_3}{(2x+y)^2}$$

$$- \left(-\frac{3}{2x+y} + \frac{6x+4y}{(2x+y)^2} \right) (xa_2 + ya_3 + a_1) \quad (\text{5E})$$

$$- \left(-\frac{2}{2x+y} + \frac{3x+2y}{(2x+y)^2} \right) (xb_2 + yb_3 + b_1) = 0$$

Putting the above in normal form gives

$$\frac{6x^2a_2 - 9x^2a_3 + 5x^2b_2 - 6x^2b_3 + 6xya_2 - 12xya_3 + 4xyb_2 - 6xyb_3 + 2y^2a_2 - 5y^2a_3 + y^2b_2 - 2y^2b_3 + xb_1}{(2x+y)^2}$$

$$= 0$$

Setting the numerator to zero gives

$$6x^2a_2 - 9x^2a_3 + 5x^2b_2 - 6x^2b_3 + 6xya_2 - 12xya_3 + 4xyb_2$$

$$- 6xyb_3 + 2y^2a_2 - 5y^2a_3 + y^2b_2 - 2y^2b_3 + xb_1 - ya_1 = 0 \quad (\text{6E})$$

Looking at the above PDE shows the following are all the terms with $\{x, y\}$ in them.

$$\{x, y\}$$

The following substitution is now made to be able to collect on all terms with $\{x, y\}$ in them

$$\{x = v_1, y = v_2\}$$

The above PDE (6E) now becomes

$$\begin{aligned} 6a_2v_1^2 + 6a_2v_1v_2 + 2a_2v_2^2 - 9a_3v_1^2 - 12a_3v_1v_2 - 5a_3v_2^2 + 5b_2v_1^2 \\ + 4b_2v_1v_2 + b_2v_2^2 - 6b_3v_1^2 - 6b_3v_1v_2 - 2b_3v_2^2 - a_1v_2 + b_1v_1 = 0 \end{aligned} \quad (7E)$$

Collecting the above on the terms v_i introduced, and these are

$$\{v_1, v_2\}$$

Equation (7E) now becomes

$$\begin{aligned} (6a_2 - 9a_3 + 5b_2 - 6b_3)v_1^2 + (6a_2 - 12a_3 + 4b_2 - 6b_3)v_1v_2 \\ + b_1v_1 + (2a_2 - 5a_3 + b_2 - 2b_3)v_2^2 - a_1v_2 = 0 \end{aligned} \quad (8E)$$

Setting each coefficients in (8E) to zero gives the following equations to solve

$$\begin{aligned} b_1 &= 0 \\ -a_1 &= 0 \\ 2a_2 - 5a_3 + b_2 - 2b_3 &= 0 \\ 6a_2 - 12a_3 + 4b_2 - 6b_3 &= 0 \\ 6a_2 - 9a_3 + 5b_2 - 6b_3 &= 0 \end{aligned}$$

Solving the above equations for the unknowns gives

$$\begin{aligned} a_1 &= 0 \\ a_2 &= 4a_3 + b_3 \\ a_3 &= a_3 \\ b_1 &= 0 \\ b_2 &= -3a_3 \\ b_3 &= b_3 \end{aligned}$$

Substituting the above solution in the anstaz (1E,2E) (using 1 as arbitrary value for any unknown in the RHS) gives

$$\begin{aligned}\xi &= x \\ \eta &= y\end{aligned}$$

Shifting is now applied to make $\xi = 0$ in order to simplify the rest of the computation

$$\begin{aligned}\eta &= \eta - \omega(x, y) \xi \\ &= y - \left(-\frac{3x + 2y}{2x + y} \right) (x) \\ &= \frac{3x^2 + 4xy + y^2}{2x + y} \\ \xi &= 0\end{aligned}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \quad (1)$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y} \right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned}S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{3x^2 + 4xy + y^2}{2x + y}} dy\end{aligned}$$

Which results in

$$S = \frac{\ln(3x^2 + 4xy + y^2)}{2}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y) S_y}{R_x + \omega(x, y) R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{3x + 2y}{2x + y}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= \frac{3x + 2y}{(y + x)(3x + y)} \\ S_y &= \frac{2x + y}{(y + x)(3x + y)} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 0 \tag{2A}$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 0$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = c_1 \tag{4}$$

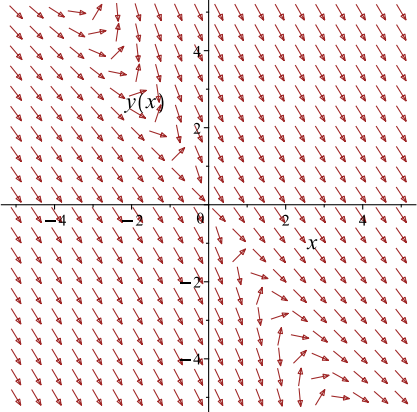
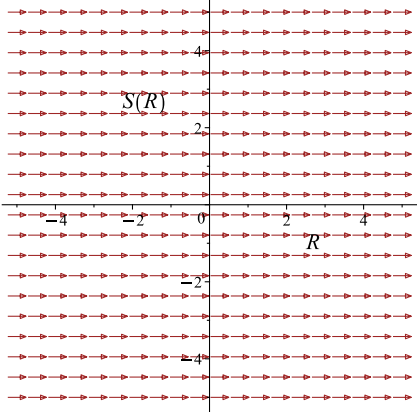
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$\frac{\ln(y + x)}{2} + \frac{\ln(3x + y)}{2} = c_1$$

Which simplifies to

$$\frac{\ln(y + x)}{2} + \frac{\ln(3x + y)}{2} = c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{3x+2y}{2x+y}$ 	$R = x$ $S = \frac{\ln(y+x)}{2} + \frac{\ln(3x+y)}{2}$	$\frac{dS}{dR} = 0$ 

Summary

The solution(s) found are the following

$$\frac{\ln(y+x)}{2} + \frac{\ln(3x+y)}{2} = c_1 \tag{1}$$

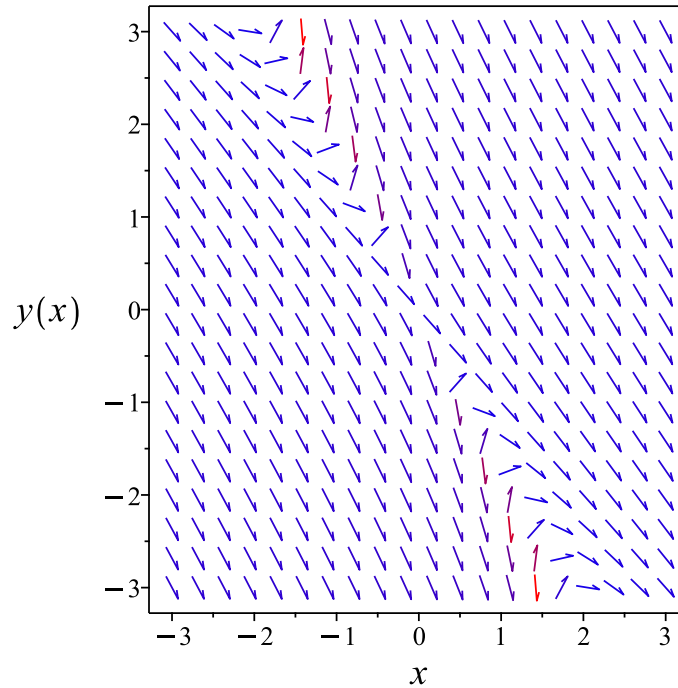


Figure 51: Slope field plot

Verification of solutions

$$\frac{\ln(y+x)}{2} + \frac{\ln(3x+y)}{2} = c_1$$

Verified OK.

3.1.4 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \tag{1A}$$

Therefore

$$\begin{aligned}(2x + y) dy &= (-3x - 2y) dx \\ (3x + 2y) dx + (2x + y) dy &= 0\end{aligned} \tag{2A}$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= 3x + 2y \\ N(x, y) &= 2x + y\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(3x + 2y) \\ &= 2\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(2x + y) \\ &= 2\end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \quad (1)$$

$$\frac{\partial \phi}{\partial y} = N \quad (2)$$

Integrating (1) w.r.t. x gives

$$\int \frac{\partial \phi}{\partial x} dx = \int M dx$$

$$\int \frac{\partial \phi}{\partial x} dx = \int 3x + 2y dx$$

$$\phi = \frac{x(3x + 4y)}{2} + f(y) \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = 2x + f'(y) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = 2x + y$. Therefore equation (4) becomes

$$2x + y = 2x + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = y$$

Integrating the above w.r.t y gives

$$\int f'(y) dy = \int (y) dy$$

$$f(y) = \frac{y^2}{2} + c_1$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = \frac{x(3x + 4y)}{2} + \frac{y^2}{2} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = \frac{x(3x + 4y)}{2} + \frac{y^2}{2}$$

Summary

The solution(s) found are the following

$$\frac{x(3x + 4y)}{2} + \frac{y^2}{2} = c_1 \quad (1)$$

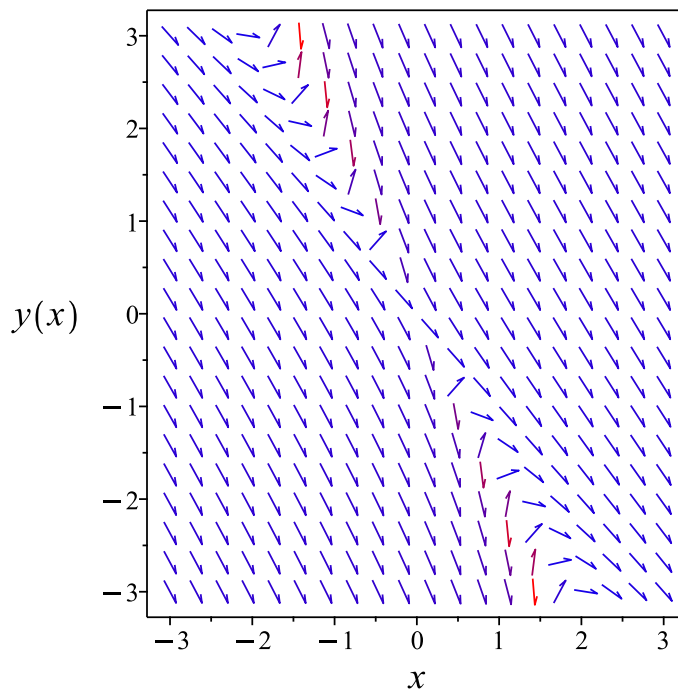


Figure 52: Slope field plot

Verification of solutions

$$\frac{x(3x + 4y)}{2} + \frac{y^2}{2} = c_1$$

Verified OK.

3.1.5 Maple step by step solution

Let's solve

$$2y + (2x + y)y' = -3x$$

- Highest derivative means the order of the ODE is 1
 y'
- Check if ODE is exact
 - ODE is exact if the lhs is the total derivative of a C^2 function
 $F'(x, y) = 0$
 - Compute derivative of lhs
 $F'(x, y) + \left(\frac{\partial}{\partial y} F(x, y)\right) y' = 0$
 - Evaluate derivatives
 $2 = 2$
 - Condition met, ODE is exact
- Exact ODE implies solution will be of this form
 $\left[F(x, y) = c_1, M(x, y) = F'(x, y), N(x, y) = \frac{\partial}{\partial y} F(x, y)\right]$
- Solve for $F(x, y)$ by integrating $M(x, y)$ with respect to x
 $F(x, y) = \int (3x + 2y) dx + f_1(y)$
- Evaluate integral
 $F(x, y) = \frac{3x^2}{2} + 2xy + f_1(y)$
- Take derivative of $F(x, y)$ with respect to y
 $N(x, y) = \frac{\partial}{\partial y} F(x, y)$
- Compute derivative
 $2x + y = 2x + \frac{d}{dy} f_1(y)$
- Isolate for $\frac{d}{dy} f_1(y)$
 $\frac{d}{dy} f_1(y) = y$
- Solve for $f_1(y)$
 $f_1(y) = \frac{y^2}{2}$
- Substitute $f_1(y)$ into equation for $F(x, y)$

$$F(x, y) = \frac{3}{2}x^2 + 2xy + \frac{1}{2}y^2$$

- Substitute $F(x, y)$ into the solution of the ODE

$$\frac{3}{2}x^2 + 2xy + \frac{1}{2}y^2 = c_1$$

- Solve for y

$$\{y = -2x - \sqrt{x^2 + 2c_1}, y = -2x + \sqrt{x^2 + 2c_1}\}$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
trying separable
trying inverse linear
trying homogeneous types:
trying homogeneous D
<- homogeneous successful`

```

✓ Solution by Maple

Time used: 0.063 (sec). Leaf size: 49

```
dsolve((3*x+2*y(x))+(2*x+y(x))*diff(y(x),x)=0,y(x), singsol=all)
```

$$y(x) = \frac{-2c_1x - \sqrt{c_1^2x^2 + 1}}{c_1}$$

$$y(x) = \frac{-2c_1x + \sqrt{c_1^2x^2 + 1}}{c_1}$$

✓ Solution by Mathematica

Time used: 0.781 (sec). Leaf size: 79

```
DSolve[(3*x+2*y[x])+(2*x+y[x])*y'[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow -2x - \sqrt{x^2 + e^{2c_1}}$$

$$y(x) \rightarrow -2x + \sqrt{x^2 + e^{2c_1}}$$

$$y(x) \rightarrow -\sqrt{x^2} - 2x$$

$$y(x) \rightarrow \sqrt{x^2} - 2x$$

3.2 problem 2

3.2.1 Solving as exact ode	294
3.2.2 Maple step by step solution	298

Internal problem ID [11597]

Internal file name [OUTPUT/10579_Thursday_May_18_2023_10_42_42_PM_75656588/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 2, section 2.1 (Exact differential equations and integrating factors). Exercises page 37

Problem number: 2.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"exact"**

Maple gives the following as the ode type

```
[_exact, _rational, [_1st_order, `with_symmetry_[F(x)*G(y),0]`, [_Abel, `2nd type`, `class B`]]
```

$$y^2 + (2yx - 4)y' = -3$$

3.2.1 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial\phi}{\partial x} &= M \\ \frac{\partial\phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \tag{1A}$$

Therefore

$$\begin{aligned}(2xy - 4) dy &= (-y^2 - 3) dx \\ (y^2 + 3) dx + (2xy - 4) dy &= 0\end{aligned} \tag{2A}$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= y^2 + 3 \\ N(x, y) &= 2xy - 4\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(y^2 + 3) \\ &= 2y\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(2xy - 4) \\ &= 2y\end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \quad (1)$$

$$\frac{\partial \phi}{\partial y} = N \quad (2)$$

Integrating (1) w.r.t. x gives

$$\int \frac{\partial \phi}{\partial x} dx = \int M dx$$

$$\int \frac{\partial \phi}{\partial x} dx = \int y^2 + 3 dx$$

$$\phi = (y^2 + 3)x + f(y) \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = 2xy + f'(y) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = 2xy - 4$. Therefore equation (4) becomes

$$2xy - 4 = 2xy + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = -4$$

Integrating the above w.r.t y gives

$$\int f'(y) dy = \int (-4) dy$$

$$f(y) = -4y + c_1$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = (y^2 + 3)x - 4y + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = (y^2 + 3)x - 4y$$

Summary

The solution(s) found are the following

$$(y^2 + 3)x - 4y = c_1 \tag{1}$$

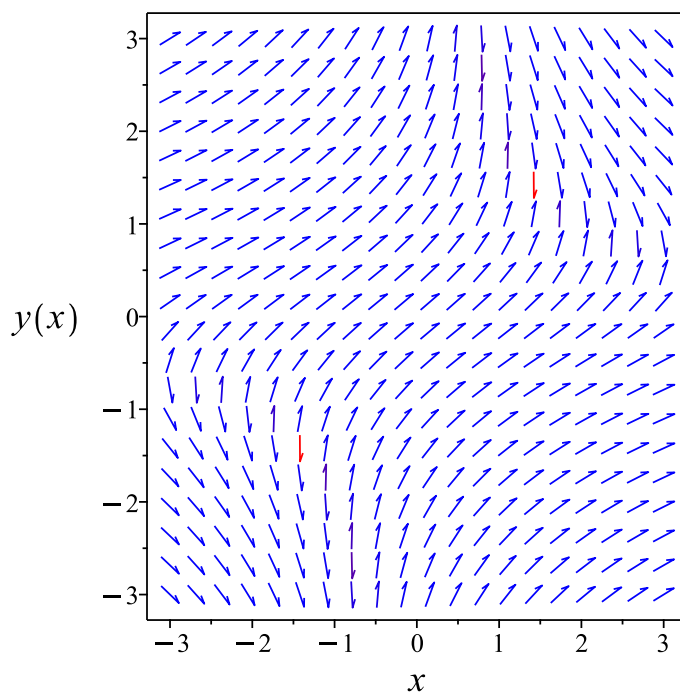


Figure 53: Slope field plot

Verification of solutions

$$(y^2 + 3)x - 4y = c_1$$

Verified OK.

3.2.2 Maple step by step solution

Let's solve

$$y^2 + (2yx - 4)y' = -3$$

- Highest derivative means the order of the ODE is 1

$$y'$$

- Check if ODE is exact

- ODE is exact if the lhs is the total derivative of a C^2 function

$$F'(x, y) = 0$$

- Compute derivative of lhs

$$F'(x, y) + \left(\frac{\partial}{\partial y} F(x, y)\right) y' = 0$$

- Evaluate derivatives

$$2y = 2y$$

- Condition met, ODE is exact

- Exact ODE implies solution will be of this form

$$\left[F(x, y) = c_1, M(x, y) = F'(x, y), N(x, y) = \frac{\partial}{\partial y} F(x, y) \right]$$

- Solve for $F(x, y)$ by integrating $M(x, y)$ with respect to x

$$F(x, y) = \int (y^2 + 3) dx + f_1(y)$$

- Evaluate integral

$$F(x, y) = (y^2 + 3)x + f_1(y)$$

- Take derivative of $F(x, y)$ with respect to y

$$N(x, y) = \frac{\partial}{\partial y} F(x, y)$$

- Compute derivative

$$2xy - 4 = 2xy + \frac{d}{dy} f_1(y)$$

- Isolate for $\frac{d}{dy} f_1(y)$

$$\frac{d}{dy} f_1(y) = -4$$

- Solve for $f_1(y)$

$$f_1(y) = -4y$$

- Substitute $f_1(y)$ into equation for $F(x, y)$

$$F(x, y) = (y^2 + 3)x - 4y$$

- Substitute $F(x, y)$ into the solution of the ODE

$$(y^2 + 3)x - 4y = c_1$$

- Solve for y

$$\left\{ y = \frac{2 + \sqrt{c_1 x - 3x^2 + 4}}{x}, y = -\frac{-2 + \sqrt{c_1 x - 3x^2 + 4}}{x} \right\}$$

Maple trace **Kovacic algorithm successful**

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
trying separable
trying inverse linear
  -> Trying a Liouvillian solution using Kovacics algorithm
      A Liouvillian solution exists
      Reducible group (found an exponential solution)
  <- Kovacics algorithm successful
  <- Abel AIR successful: ODE belongs to the 2F1 3-parameter class
<- inverse linear successful`

```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 62

```
dsolve((y(x)^2+3)+(2*x*y(x)-4)*diff(y(x),x)=0,y(x), singsol=all)
```

$$\frac{-ic_1(y(x)^2 x + 3x - 4y(x)) \sqrt{3} + 12c_1 + i}{(-y(x) \sqrt{3} x + 4\sqrt{3} - 3ix) (\sqrt{3} + iy(x))} = 0$$

✓ Solution by Mathematica

Time used: 0.615 (sec). Leaf size: 79

```
DSolve[(y[x]^2+3)+(2*x*y[x]-4)*y'[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{2 - \sqrt{-3x^2 + c_1x + 4}}{x}$$

$$y(x) \rightarrow \frac{2 + \sqrt{-3x^2 + c_1x + 4}}{x}$$

$$y(x) \rightarrow -i\sqrt{3}$$

$$y(x) \rightarrow i\sqrt{3}$$

3.3 problem 3

3.3.1 Solving as differentialType ode	301
3.3.2 Solving as exact ode	303
3.3.3 Maple step by step solution	306

Internal problem ID [11598]

Internal file name [OUTPUT/10580_Thursday_May_18_2023_10_42_44_PM_48988675/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.1 (Exact differential equations and integrating factors). Exercises page 37

Problem number: 3.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"exact", "differentialType"**

Maple gives the following as the ode type

```
[_exact, _rational, [_1st_order, `_with_symmetry_[F(x),G(x)]`],  
[_Abel, `2nd type`, `class A`]]
```

$$2yx + (x^2 + 4y)y' = -1$$

3.3.1 Solving as differentialType ode

Writing the ode as

$$y' = \frac{-2yx - 1}{x^2 + 4y} \quad (1)$$

Which becomes

$$(4y) dy = (-x^2) dy + (-2xy - 1) dx \quad (2)$$

But the RHS is complete differential because

$$(-x^2) dy + (-2xy - 1) dx = d(-x^2y - x)$$

Hence (2) becomes

$$(4y) dy = d(-x^2y - x)$$

Integrating both sides gives gives these solutions

$$y = -\frac{x^2}{4} + \frac{\sqrt{x^4 + 8c_1 - 8x}}{4} + c_1$$

$$y = -\frac{x^2}{4} - \frac{\sqrt{x^4 + 8c_1 - 8x}}{4} + c_1$$

Summary

The solution(s) found are the following

$$y = -\frac{x^2}{4} + \frac{\sqrt{x^4 + 8c_1 - 8x}}{4} + c_1 \quad (1)$$

$$y = -\frac{x^2}{4} - \frac{\sqrt{x^4 + 8c_1 - 8x}}{4} + c_1 \quad (2)$$

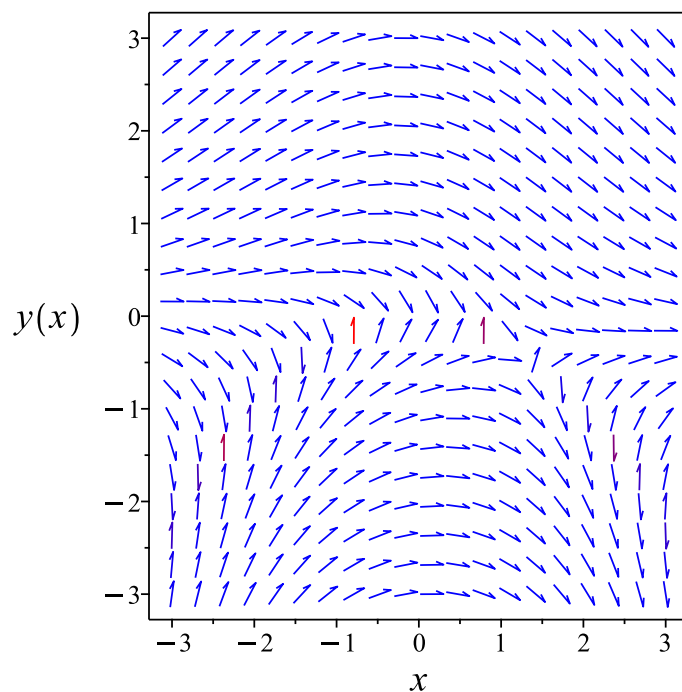


Figure 54: Slope field plot

Verification of solutions

$$y = -\frac{x^2}{4} + \frac{\sqrt{x^4 + 8c_1 - 8x}}{4} + c_1$$

Verified OK.

$$y = -\frac{x^2}{4} - \frac{\sqrt{x^4 + 8c_1 - 8x}}{4} + c_1$$

Verified OK.

3.3.2 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \quad (\text{A})$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \quad (\text{B})$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (\text{1A})$$

Therefore

$$\begin{aligned}(x^2 + 4y) dy &= (-2xy - 1) dx \\ (2xy + 1) dx + (x^2 + 4y) dy &= 0\end{aligned}\tag{2A}$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= 2xy + 1 \\ N(x, y) &= x^2 + 4y\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(2xy + 1) \\ &= 2x\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(x^2 + 4y) \\ &= 2x\end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M\tag{1}$$

$$\frac{\partial \phi}{\partial y} = N\tag{2}$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int M dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int 2xy + 1 dx \\ \phi &= x^2y + x + f(y)\end{aligned}\tag{3}$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial\phi}{\partial y} = x^2 + f'(y) \quad (4)$$

But equation (2) says that $\frac{\partial\phi}{\partial y} = x^2 + 4y$. Therefore equation (4) becomes

$$x^2 + 4y = x^2 + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 4y$$

Integrating the above w.r.t y gives

$$\int f'(y) dy = \int (4y) dy$$
$$f(y) = 2y^2 + c_1$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = x^2y + 2y^2 + x + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = x^2y + 2y^2 + x$$

Summary

The solution(s) found are the following

$$x^2y + 2y^2 + x = c_1 \quad (1)$$

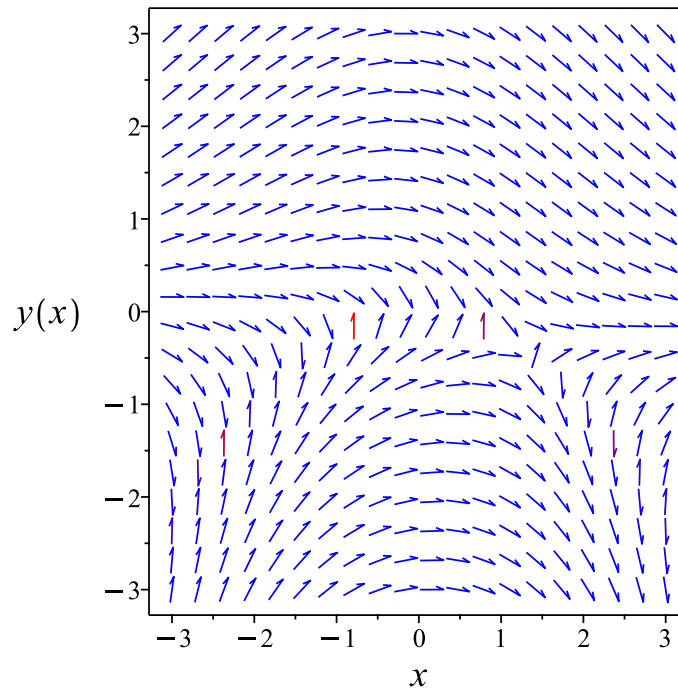


Figure 55: Slope field plot

Verification of solutions

$$x^2y + 2y^2 + x = c_1$$

Verified OK.

3.3.3 Maple step by step solution

Let's solve

$$2yx + (x^2 + 4y)y' = -1$$

- Highest derivative means the order of the ODE is 1
 y'
- Check if ODE is exact
 - ODE is exact if the lhs is the total derivative of a C^2 function
 $F'(x, y) = 0$
 - Compute derivative of lhs
 $F'(x, y) + \left(\frac{\partial}{\partial y}F(x, y)\right)y' = 0$

- Evaluate derivatives
 $2x = 2x$
- Condition met, ODE is exact
- Exact ODE implies solution will be of this form

$$\left[F(x, y) = c_1, M(x, y) = F'(x, y), N(x, y) = \frac{\partial}{\partial y} F(x, y) \right]$$
- Solve for $F(x, y)$ by integrating $M(x, y)$ with respect to x

$$F(x, y) = \int (2xy + 1) dx + f_1(y)$$
- Evaluate integral

$$F(x, y) = x^2y + x + f_1(y)$$
- Take derivative of $F(x, y)$ with respect to y

$$N(x, y) = \frac{\partial}{\partial y} F(x, y)$$
- Compute derivative

$$x^2 + 4y = x^2 + \frac{d}{dy} f_1(y)$$
- Isolate for $\frac{d}{dy} f_1(y)$

$$\frac{d}{dy} f_1(y) = 4y$$
- Solve for $f_1(y)$

$$f_1(y) = 2y^2$$
- Substitute $f_1(y)$ into equation for $F(x, y)$

$$F(x, y) = x^2y + 2y^2 + x$$
- Substitute $F(x, y)$ into the solution of the ODE

$$x^2y + 2y^2 + x = c_1$$
- Solve for y

$$\left\{ y = -\frac{x^2}{4} - \frac{\sqrt{x^4 + 8c_1 - 8x}}{4}, y = -\frac{x^2}{4} + \frac{\sqrt{x^4 + 8c_1 - 8x}}{4} \right\}$$

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
trying Bernoulli  
trying separable  
trying inverse linear  
trying homogeneous types:  
trying Chini  
differential order: 1; looking for linear symmetries  
trying exact  
<- exact successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 47

```
dsolve((2*x*y(x)+1)+(x^2+4*y(x))*diff(y(x),x)=0,y(x), singsol=all)
```

$$y(x) = -\frac{x^2}{4} - \frac{\sqrt{x^4 - 8c_1 - 8x}}{4}$$
$$y(x) = -\frac{x^2}{4} + \frac{\sqrt{x^4 - 8c_1 - 8x}}{4}$$

✓ Solution by Mathematica

Time used: 0.223 (sec). Leaf size: 61

```
DSolve[(2*x*y[x]+1)+(x^2+4*y[x])*y'[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{1}{4} \left(-x^2 - \sqrt{x^4 - 8x + 16c_1} \right)$$
$$y(x) \rightarrow \frac{1}{4} \left(-x^2 + \sqrt{x^4 - 8x + 16c_1} \right)$$

3.4 problem 4

Internal problem ID [11599]

Internal file name [OUTPUT/10581_Thursday_May_18_2023_10_42_45_PM_55985488/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.1 (Exact differential equations and integrating factors). Exercises page 37

Problem number: 4.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**unknown**"

Maple gives the following as the ode type

```
[_rational, [_Abel, `2nd type`, `class A`]]
```

Unable to solve or complete the solution.

$$3x^2y - (x^3 + y)y' = -2$$

Unable to determine ODE type.

Maple trace

```
`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
trying separable
trying inverse linear
trying homogeneous types:
trying Chini
differential order: 1; looking for linear symmetries
trying exact
trying Abel
Looking for potential symmetries
Looking for potential symmetries
Looking for potential symmetries
trying inverse_Riccati
trying an equivalence to an Abel ODE
differential order: 1; trying a linearization to 2nd order
--- trying a change of variables {x -> y(x), y(x) -> x}
differential order: 1; trying a linearization to 2nd order
trying 1st order ODE linearizable_by_differentiation
--- Trying Lie symmetry methods, 1st order ---
`, `-> Computing symmetries using: way = 3
`, `-> Computing symmetries using: way = 4
`, `-> Computing symmetries using: way = 2
trying symmetry patterns for 1st order ODEs
-> trying a symmetry pattern of the form [F(x)*G(y), 0]
-> trying a symmetry pattern of the form [0, F(x)*G(y)]
-> trying symmetry patterns of the forms [F(x),G(y)] and [G(y),F(x)]
-> trying a symmetry pattern of the form [F(x),G(x)]
-> trying a symmetry pattern of the form [F(y),G(y)]
-> trying a symmetry pattern of the form [F(x)+G(y), 0]
-> trying a symmetry pattern of the form [0, F(x)+G(y)]
-> trying a symmetry pattern of the form [F(x),G(x)*y+H(x)]
-> trying a symmetry pattern of conformal type`
```

X Solution by Maple

```
dsolve((3*x^2*y(x)+2)-(x^3+y(x))*diff(y(x),x)=0,y(x), singsol=all)
```

No solution found

X Solution by Mathematica

Time used: 0.0 (sec). Leaf size: 0

```
DSolve[(3*x^2+2)-(x^3+y[x])*y'[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

Not solved

3.5 problem 5

3.5.1 Solving as exact ode	312
3.5.2 Maple step by step solution	316

Internal problem ID [11600]

Internal file name [OUTPUT/10582_Thursday_May_18_2023_10_42_46_PM_41313843/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 2, section 2.1 (Exact differential equations and integrating factors). Exercises page 37

Problem number: 5.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact"

Maple gives the following as the ode type

```
[_exact, _rational, [_Abel, `2nd type`, `class B`]]
```

$$6yx + 2y^2 + (3x^2 + 4yx - 6) y' = 5$$

3.5.1 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial\phi}{\partial x} &= M \\ \frac{\partial\phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \tag{1A}$$

Therefore

$$\begin{aligned}(3x^2 + 4xy - 6) dy &= (-6xy - 2y^2 + 5) dx \\ (6xy + 2y^2 - 5) dx + (3x^2 + 4xy - 6) dy &= 0\end{aligned} \tag{2A}$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= 6xy + 2y^2 - 5 \\ N(x, y) &= 3x^2 + 4xy - 6\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(6xy + 2y^2 - 5) \\ &= 6x + 4y\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(3x^2 + 4xy - 6) \\ &= 6x + 4y\end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \quad (1)$$

$$\frac{\partial \phi}{\partial y} = N \quad (2)$$

Integrating (1) w.r.t. x gives

$$\begin{aligned} \int \frac{\partial \phi}{\partial x} dx &= \int M dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int 6xy + 2y^2 - 5 dx \\ \phi &= 3x^2y + 2xy^2 - 5x + f(y) \end{aligned} \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\begin{aligned} \frac{\partial \phi}{\partial y} &= 3x^2 + 4xy + f'(y) \\ &= x(3x + 4y) + f'(y) \end{aligned} \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = 3x^2 + 4xy - 6$. Therefore equation (4) becomes

$$3x^2 + 4xy - 6 = x(3x + 4y) + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = -6$$

Integrating the above w.r.t y gives

$$\begin{aligned} \int f'(y) dy &= \int (-6) dy \\ f(y) &= -6y + c_1 \end{aligned}$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = 3x^2y + 2xy^2 - 5x - 6y + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = 3x^2y + 2xy^2 - 5x - 6y$$

Summary

The solution(s) found are the following

$$3x^2y + 2y^2x - 5x - 6y = c_1 \tag{1}$$

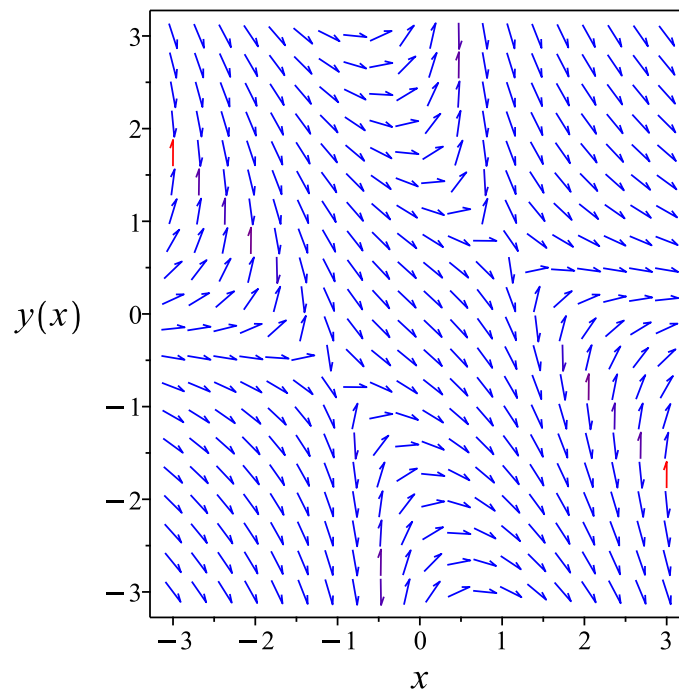


Figure 56: Slope field plot

Verification of solutions

$$3x^2y + 2y^2x - 5x - 6y = c_1$$

Verified OK.

3.5.2 Maple step by step solution

Let's solve

$$6yx + 2y^2 + (3x^2 + 4yx - 6)y' = 5$$

- Highest derivative means the order of the ODE is 1
 y'
- Check if ODE is exact
 - ODE is exact if the lhs is the total derivative of a C^2 function
 $F'(x, y) = 0$
 - Compute derivative of lhs
 $F'(x, y) + \left(\frac{\partial}{\partial y} F(x, y)\right) y' = 0$
 - Evaluate derivatives
 $6x + 4y = 6x + 4y$
 - Condition met, ODE is exact
- Exact ODE implies solution will be of this form
$$\left[F(x, y) = c_1, M(x, y) = F'(x, y), N(x, y) = \frac{\partial}{\partial y} F(x, y) \right]$$
- Solve for $F(x, y)$ by integrating $M(x, y)$ with respect to x
$$F(x, y) = \int (6xy + 2y^2 - 5) dx + f_1(y)$$
- Evaluate integral
$$F(x, y) = 3x^2y + 2xy^2 - 5x + f_1(y)$$
- Take derivative of $F(x, y)$ with respect to y
$$N(x, y) = \frac{\partial}{\partial y} F(x, y)$$
- Compute derivative
$$3x^2 + 4xy - 6 = 3x^2 + 4xy + \frac{d}{dy} f_1(y)$$
- Isolate for $\frac{d}{dy} f_1(y)$
$$\frac{d}{dy} f_1(y) = -6$$
- Solve for $f_1(y)$
$$f_1(y) = -6y$$
- Substitute $f_1(y)$ into equation for $F(x, y)$

$$F(x, y) = 3x^2y + 2xy^2 - 5x - 6y$$

- Substitute $F(x, y)$ into the solution of the ODE

$$3x^2y + 2xy^2 - 5x - 6y = c_1$$

- Solve for y

$$\left\{ y = \frac{-3x^2 + 6 + \sqrt{9x^4 + 8c_1x + 4x^2 + 36}}{4x}, y = -\frac{3x^2 + \sqrt{9x^4 + 8c_1x + 4x^2 + 36} - 6}{4x} \right\}$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
trying separable
trying inverse linear
trying homogeneous types:
trying Chini
differential order: 1; looking for linear symmetries
trying exact
<- exact successful`

```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 69

```
dsolve((6*x*y(x)+2*y(x)^2-5)+(3*x^2+4*x*y(x)-6)*diff(y(x),x)=0,y(x), singsol=all)
```

$$y(x) = \frac{-3x^2 + 6 + \sqrt{9x^4 - 8c_1x + 4x^2 + 36}}{4x}$$

$$y(x) = \frac{-3x^2 + 6 - \sqrt{9x^4 - 8c_1x + 4x^2 + 36}}{4x}$$

✓ Solution by Mathematica

Time used: 0.709 (sec). Leaf size: 79

```
DSolve[(6*x*y[x]+2*y[x]^2-5)+(3*x^2+4*x*y[x]-6)*y'[x]==0,y[x],x,IncludeSingularSolutions ->
```

$$y(x) \rightarrow -\frac{3x^2 + \sqrt{9x^4 + 4x^2 + 16c_1x + 36} - 6}{4x}$$

$$y(x) \rightarrow \frac{-3x^2 + \sqrt{9x^4 + 4x^2 + 16c_1x + 36} + 6}{4x}$$

3.6 problem 7

3.6.1 Solving as exact ode	319
3.6.2 Maple step by step solution	323

Internal problem ID [11601]

Internal file name [OUTPUT/10583_Thursday_May_18_2023_10_42_47_PM_64831531/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.1 (Exact differential equations and integrating factors). Exercises page 37

Problem number: 7.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact"

Maple gives the following as the ode type

```
[_exact, [_Abel, `2nd type`, `class A`]]
```

$$y \sec(x)^2 + (\tan(x) + 2y)y' = -\sec(x) \tan(x)$$

3.6.1 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (1A)$$

Therefore

$$\begin{aligned}(\tan(x) + 2y) dy &= (-y \sec(x)^2 - \sec(x) \tan(x)) dx \\ (y \sec(x)^2 + \sec(x) \tan(x)) dx &+ (\tan(x) + 2y) dy = 0\end{aligned} \quad (2A)$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= y \sec(x)^2 + \sec(x) \tan(x) \\ N(x, y) &= \tan(x) + 2y\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y} (y \sec(x)^2 + \sec(x) \tan(x)) \\ &= \sec(x)^2\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x} (\tan(x) + 2y) \\ &= \sec(x)^2\end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \quad (1)$$

$$\frac{\partial \phi}{\partial y} = N \quad (2)$$

Integrating (1) w.r.t. x gives

$$\begin{aligned} \int \frac{\partial \phi}{\partial x} dx &= \int M dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int y \sec(x)^2 + \sec(x) \tan(x) dx \\ \phi &= y \tan(x) + \sec(x) + f(y) \end{aligned} \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = \tan(x) + f'(y) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = \tan(x) + 2y$. Therefore equation (4) becomes

$$\tan(x) + 2y = \tan(x) + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 2y$$

Integrating the above w.r.t y gives

$$\begin{aligned} \int f'(y) dy &= \int (2y) dy \\ f(y) &= y^2 + c_1 \end{aligned}$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = y \tan(x) + \sec(x) + y^2 + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = y \tan(x) + \sec(x) + y^2$$

Summary

The solution(s) found are the following

$$\tan(x)y + \sec(x) + y^2 = c_1 \tag{1}$$

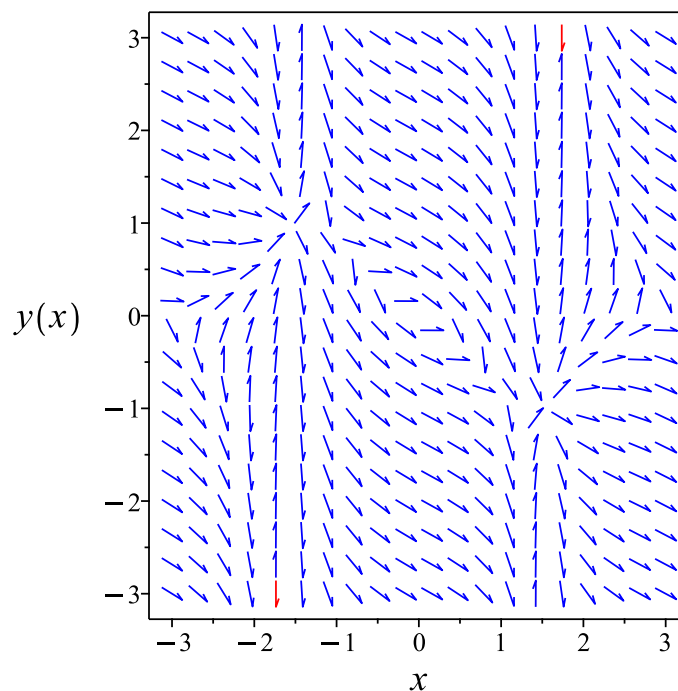


Figure 57: Slope field plot

Verification of solutions

$$\tan(x)y + \sec(x) + y^2 = c_1$$

Verified OK.

3.6.2 Maple step by step solution

Let's solve

$$y \sec(x)^2 + (\tan(x) + 2y) y' = -\sec(x) \tan(x)$$

- Highest derivative means the order of the ODE is 1

y'

- Check if ODE is exact

- ODE is exact if the lhs is the total derivative of a C^2 function

$$F'(x, y) = 0$$

- Compute derivative of lhs

$$F'(x, y) + \left(\frac{\partial}{\partial y} F(x, y) \right) y' = 0$$

- Evaluate derivatives

$$\sec(x)^2 = \tan(x)^2 + 1$$

- Simplify

$$\sec(x)^2 = \sec(x)^2$$

- Condition met, ODE is exact

- Exact ODE implies solution will be of this form

$$\left[F(x, y) = c_1, M(x, y) = F'(x, y), N(x, y) = \frac{\partial}{\partial y} F(x, y) \right]$$

- Solve for $F(x, y)$ by integrating $M(x, y)$ with respect to x

$$F(x, y) = \int (y \sec(x)^2 + \sec(x) \tan(x)) dx + f_1(y)$$

- Evaluate integral

$$F(x, y) = y \tan(x) + \sec(x) + f_1(y)$$

- Take derivative of $F(x, y)$ with respect to y

$$N(x, y) = \frac{\partial}{\partial y} F(x, y)$$

- Compute derivative

$$\tan(x) + 2y = \tan(x) + \frac{d}{dy} f_1(y)$$

- Isolate for $\frac{d}{dy} f_1(y)$

$$\frac{d}{dy} f_1(y) = 2y$$

- Solve for $f_1(y)$

$$f_1(y) = y^2$$

- Substitute $f_1(y)$ into equation for $F(x, y)$

$$F(x, y) = y \tan(x) + \sec(x) + y^2$$

- Substitute $F(x, y)$ into the solution of the ODE

$$y \tan(x) + \sec(x) + y^2 = c_1$$

- Solve for y

$$\left\{ y = -\frac{\sin(x) - \sqrt{4c_1 \cos(x)^2 + \sin(x)^2 - 4 \cos(x)}}{2 \cos(x)}, y = -\frac{\sin(x) + \sqrt{4c_1 \cos(x)^2 + \sin(x)^2 - 4 \cos(x)}}{2 \cos(x)} \right\}$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
trying separable
trying inverse linear
trying homogeneous types:
trying Chini
differential order: 1; looking for linear symmetries
trying exact
<- exact successful`

```

✓ Solution by Maple

Time used: 0.047 (sec). Leaf size: 61

```
dsolve((y(x)*sec(x)^2+sec(x)*tan(x))+(tan(x)+2*y(x))*diff(y(x),x)=0,y(x), singsol=all)
```

$$y(x) = -\frac{\tan(x)}{2} + \frac{\sec(x) \sqrt{-4 \cos(x)^2 c_1 + \sin(x)^2 - 4 \cos(x)}}{2}$$

$$y(x) = -\frac{\tan(x)}{2} - \frac{\sec(x) \sqrt{-4 \cos(x)^2 c_1 + \sin(x)^2 - 4 \cos(x)}}{2}$$

✓ Solution by Mathematica

Time used: 1.831 (sec). Leaf size: 101

```
DSolve[(y[x]*Sec[x]^2+Sec[x]*Tan[x])+(Tan[x]+2*y[x])*y'[x]==0,y[x],x,IncludeSingularSolution
```

$$y(x) \rightarrow \frac{1}{4} \left(-2 \tan(x) - \sqrt{2} \sqrt{\sec^2(x)} \sqrt{-8 \cos(x) + (-1 + 4c_1) \cos(2x) + 1 + 4c_1} \right)$$

$$y(x) \rightarrow \frac{1}{4} \left(-2 \tan(x) + \sqrt{\sec^2(x)} \sqrt{-16 \cos(x) + (-2 + 8c_1) \cos(2x) + 2 + 8c_1} \right)$$

3.7 problem 8

3.7.1 Solving as exact ode 326

Internal problem ID [11602]

Internal file name [OUTPUT/10584_Thursday_May_18_2023_10_42_49_PM_42100361/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.1 (Exact differential equations and integrating factors). Exercises page 37

Problem number: 8.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"exactWithIntegrationFactor"**

Maple gives the following as the ode type

```
[_rational, [_1st_order, `~_with_symmetry_[F(x)*G(y),0]`]]
```

$$\frac{x}{y^2} + \left(\frac{x^2}{y^3} + y\right) y' = -x$$

3.7.1 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (1A)$$

Therefore

$$\begin{aligned}\left(\frac{x^2}{y^3} + y\right) dy &= \left(-\frac{x}{y^2} - x\right) dx \\ \left(\frac{x}{y^2} + x\right) dx + \left(\frac{x^2}{y^3} + y\right) dy &= 0\end{aligned} \quad (2A)$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= \frac{x}{y^2} + x \\ N(x, y) &= \frac{x^2}{y^3} + y\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y} \left(\frac{x}{y^2} + x\right) \\ &= -\frac{2x}{y^3}\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x} \left(\frac{x^2}{y^3} + y \right) \\ &= \frac{2x}{y^3}\end{aligned}$$

Since $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$\begin{aligned}A &= \frac{1}{N} \left(\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} \right) \\ &= \frac{1}{\frac{x^2}{y^3} + y} \left(\left(-\frac{2x}{y^3} \right) - \left(\frac{2x}{y^3} \right) \right) \\ &= -\frac{4x}{y^4 + x^2}\end{aligned}$$

Since A depends on y , it can not be used to obtain an integrating factor. We will now try a second method to find an integrating factor. Let

$$\begin{aligned}B &= \frac{1}{M} \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) \\ &= \frac{1}{\frac{x}{y^2} + x} \left(\left(\frac{2x}{y^3} \right) - \left(-\frac{2x}{y^3} \right) \right) \\ &= \frac{4}{y(y^2 + 1)}\end{aligned}$$

Since B does not depend on x , it can be used to obtain an integrating factor. Let the integrating factor be μ . Then

$$\begin{aligned}\mu &= e^{\int B \, dy} \\ &= e^{\int \frac{4}{y(y^2+1)} \, dy}\end{aligned}$$

The result of integrating gives

$$\begin{aligned}\mu &= e^{4\ln(y) - 2\ln(y^2+1)} \\ &= \frac{y^4}{(y^2 + 1)^2}\end{aligned}$$

M and N are now multiplied by this integrating factor, giving new M and new N which are called \bar{M} and \bar{N} so not to confuse them with the original M and N .

$$\begin{aligned}\bar{M} &= \mu M \\ &= \frac{y^4}{(y^2 + 1)^2} \left(\frac{x}{y^2} + x \right) \\ &= \frac{x y^2}{y^2 + 1}\end{aligned}$$

And

$$\begin{aligned}\bar{N} &= \mu N \\ &= \frac{y^4}{(y^2 + 1)^2} \left(\frac{x^2}{y^3} + y \right) \\ &= \frac{(y^4 + x^2) y}{(y^2 + 1)^2}\end{aligned}$$

So now a modified ODE is obtained from the original ODE which will be exact and can be solved using the standard method. The modified ODE is

$$\begin{aligned}\bar{M} + \bar{N} \frac{dy}{dx} &= 0 \\ \left(\frac{x y^2}{y^2 + 1} \right) + \left(\frac{(y^4 + x^2) y}{(y^2 + 1)^2} \right) \frac{dy}{dx} &= 0\end{aligned}$$

The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = \bar{M} \tag{1}$$

$$\frac{\partial \phi}{\partial y} = \bar{N} \tag{2}$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int \bar{M} dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int \frac{x y^2}{y^2 + 1} dx \\ \phi &= \frac{x^2 y^2}{2y^2 + 2} + f(y)\end{aligned} \tag{3}$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\begin{aligned}\frac{\partial\phi}{\partial y} &= \frac{2x^2y}{2y^2+2} - \frac{4x^2y^3}{(2y^2+2)^2} + f'(y) \\ &= \frac{x^2y}{(y^2+1)^2} + f'(y)\end{aligned}\tag{4}$$

But equation (2) says that $\frac{\partial\phi}{\partial y} = \frac{(y^4+x^2)y}{(y^2+1)^2}$. Therefore equation (4) becomes

$$\frac{(y^4+x^2)y}{(y^2+1)^2} = \frac{x^2y}{(y^2+1)^2} + f'(y)\tag{5}$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = \frac{y^5}{(y^2+1)^2}$$

Integrating the above w.r.t y gives

$$\begin{aligned}\int f'(y) dy &= \int \left(\frac{y^5}{(y^2+1)^2} \right) dy \\ f(y) &= \frac{y^2}{2} - \ln(y^2+1) - \frac{1}{2(y^2+1)} + c_1\end{aligned}$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = \frac{x^2y^2}{2y^2+2} + \frac{y^2}{2} - \ln(y^2+1) - \frac{1}{2(y^2+1)} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = \frac{x^2y^2}{2y^2+2} + \frac{y^2}{2} - \ln(y^2+1) - \frac{1}{2(y^2+1)}$$

Summary

The solution(s) found are the following

$$\frac{x^2 y^2}{2y^2 + 2} + \frac{y^2}{2} - \ln(1 + y^2) - \frac{1}{2(1 + y^2)} = c_1 \quad (1)$$

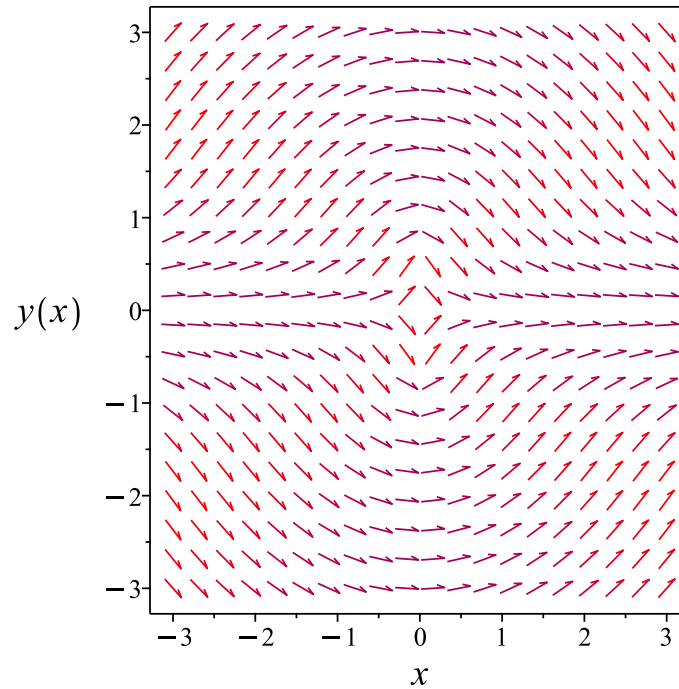


Figure 58: Slope field plot

Verification of solutions

$$\frac{x^2 y^2}{2y^2 + 2} + \frac{y^2}{2} - \ln(1 + y^2) - \frac{1}{2(1 + y^2)} = c_1$$

Verified OK.

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
trying Bernoulli  
trying separable  
trying inverse linear  
trying homogeneous types:  
trying Chini  
differential order: 1; looking for linear symmetries  
trying exact  
<- exact successful`
```

✓ Solution by Maple

Time used: 0.062 (sec). Leaf size: 52

```
dsolve((x/y(x)^2+x)+(x^2/y(x)^3+y(x))*diff(y(x),x)=0,y(x), singsol=all)
```

$$\frac{(-2y(x)^2 - 2) \ln(y(x)^2 + 1) + y(x)^4 + (x^2 + 2c_1 + 1)y(x)^2 + 2c_1 - 1}{2y(x)^2 + 2} = 0$$

✓ Solution by Mathematica

Time used: 0.4 (sec). Leaf size: 55

```
DSolve[(x/y[x]^2+x)+(x^2/y[x]^3+y[x])*y'[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$\text{Solve} \left[\frac{x^2 y(x)^2}{2(y(x)^2 + 1)} + \frac{y(x)^2}{2} - \frac{1}{2(y(x)^2 + 1)} - \log(y(x)^2 + 1) = c_1, y(x) \right]$$

3.8 problem 9

3.8.1	Solving as separable ode	333
3.8.2	Solving as first order ode lie symmetry lookup ode	335
3.8.3	Solving as exact ode	339
3.8.4	Maple step by step solution	343

Internal problem ID [11603]

Internal file name [OUTPUT/10585_Thursday_May_18_2023_10_42_51_PM_54314826/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 2, section 2.1 (Exact differential equations and integrating factors). Exercises page 37

Problem number: 9.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact", "separable", "first_order_ode_lie_symmetry_lookup"

Maple gives the following as the ode type

`[_separable]`

$$\frac{(2s-1)s'}{t} + \frac{s-s^2}{t^2} = 0$$

3.8.1 Solving as separable ode

In canonical form the ODE is

$$\begin{aligned} s' &= F(t, s) \\ &= f(t)g(s) \\ &= \frac{s(s-1)}{t(2s-1)} \end{aligned}$$

Where $f(t) = \frac{1}{t}$ and $g(s) = \frac{s(s-1)}{2s-1}$. Integrating both sides gives

$$\frac{1}{\frac{s(s-1)}{2s-1}} ds = \frac{1}{t} dt$$

$$\int \frac{1}{\frac{s(s-1)}{2s-1}} ds = \int \frac{1}{t} dt$$

$$\ln(s(s-1)) = \ln(t) + c_1$$

Raising both side to exponential gives

$$s(s-1) = e^{\ln(t)+c_1}$$

Which simplifies to

$$s(s-1) = c_2 t$$

Which simplifies to

$$s(s-1) = c_2 e^{c_1 t}$$

The solution is

$$s(s-1) = c_2 e^{c_1 t}$$

Summary

The solution(s) found are the following

$$s(s-1) = c_2 e^{c_1 t} \tag{1}$$

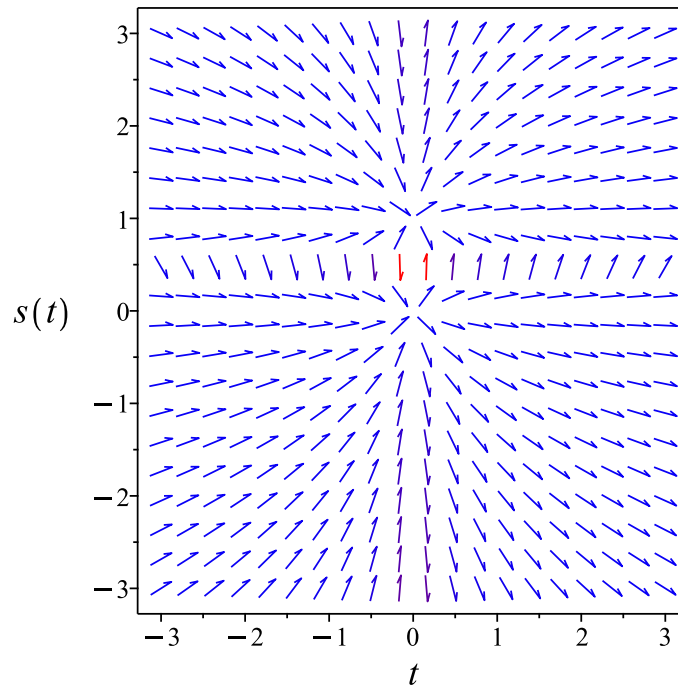


Figure 59: Slope field plot

Verification of solutions

$$s(s - 1) = c_2 e^{c_1 t}$$

Verified OK.

3.8.2 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$s' = \frac{s(s - 1)}{t(2s - 1)}$$
$$s' = \omega(t, s)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_t + \omega(\eta_s - \xi_t) - \omega^2 \xi_s - \omega_t \xi - \omega_s \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **separable**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 59: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(t, s) &= t \\ \eta(t, s) &= 0\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(t, s) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dt}{\xi} = \frac{ds}{\eta} = dS\tag{1}$$

The above comes from the requirements that $(\xi \frac{\partial}{\partial t} + \eta \frac{\partial}{\partial s})S(t, s) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\eta = 0$ then in this special case

$$R = s$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\xi} dt \\ &= \int \frac{1}{t} dt \end{aligned}$$

Which results in

$$S = \ln(t)$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_t + \omega(t, s)S_s}{R_t + \omega(t, s)R_s} \quad (2)$$

Where in the above R_t, R_s, S_t, S_s are all partial derivatives and $\omega(t, s)$ is the right hand side of the original ode given by

$$\omega(t, s) = \frac{s(s-1)}{t(2s-1)}$$

Evaluating all the partial derivatives gives

$$R_t = 0$$

$$R_s = 1$$

$$S_t = \frac{1}{t}$$

$$S_s = 0$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = \frac{2s-1}{s(s-1)} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for t, s in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = \frac{2R-1}{R(R-1)}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = \ln(R(R - 1)) + c_1 \quad (4)$$

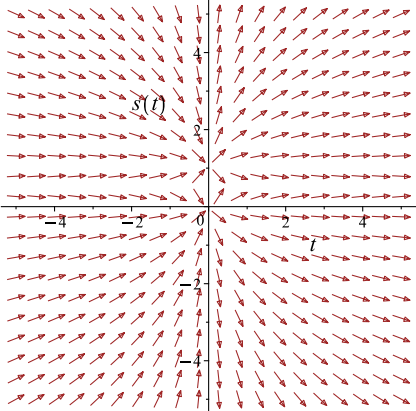
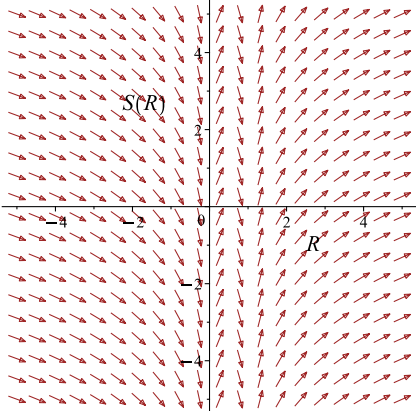
To complete the solution, we just need to transform (4) back to t, s coordinates. This results in

$$\ln(t) = \ln(s(s - 1)) + c_1$$

Which simplifies to

$$\ln(t) = \ln(s(s - 1)) + c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in t, s coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{ds}{dt} = \frac{s(s-1)}{t(2s-1)}$ 	$R = s$ $S = \ln(t)$	$\frac{dS}{dR} = \frac{2R-1}{R(R-1)}$ 

Summary

The solution(s) found are the following

$$\ln(t) = \ln(s(s - 1)) + c_1 \quad (1)$$

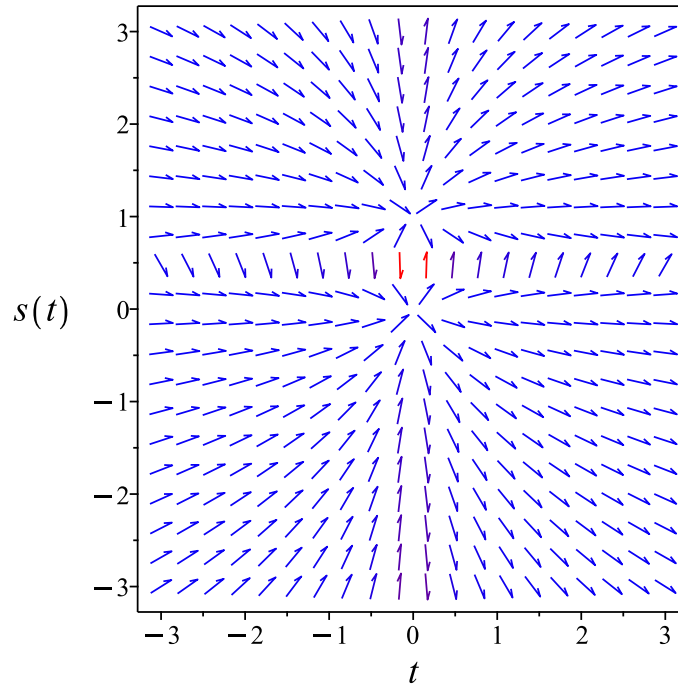


Figure 60: Slope field plot

Verification of solutions

$$\ln(t) = \ln(s(s-1)) + c_1$$

Verified OK.

3.8.3 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(t, s) dt + N(t, s) ds = 0 \tag{1A}$$

Therefore

$$\begin{aligned}\left(\frac{2s-1}{s(s-1)}\right) ds &= \left(\frac{1}{t}\right) dt \\ \left(-\frac{1}{t}\right) dt + \left(\frac{2s-1}{s(s-1)}\right) ds &= 0\end{aligned} \tag{2A}$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(t, s) &= -\frac{1}{t} \\ N(t, s) &= \frac{2s-1}{s(s-1)}\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial s} = \frac{\partial N}{\partial t}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial s} &= \frac{\partial}{\partial s} \left(-\frac{1}{t}\right) \\ &= 0\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial t} &= \frac{\partial}{\partial t} \left(\frac{2s-1}{s(s-1)} \right) \\ &= 0\end{aligned}$$

Since $\frac{\partial M}{\partial s} = \frac{\partial N}{\partial t}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(t, s)$

$$\frac{\partial \phi}{\partial t} = M \quad (1)$$

$$\frac{\partial \phi}{\partial s} = N \quad (2)$$

Integrating (1) w.r.t. t gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial t} dt &= \int M dt \\ \int \frac{\partial \phi}{\partial t} dt &= \int -\frac{1}{t} dt \\ \phi &= -\ln(t) + f(s)\end{aligned} \quad (3)$$

Where $f(s)$ is used for the constant of integration since ϕ is a function of both t and s . Taking derivative of equation (3) w.r.t s gives

$$\frac{\partial \phi}{\partial s} = 0 + f'(s) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial s} = \frac{2s-1}{s(s-1)}$. Therefore equation (4) becomes

$$\frac{2s-1}{s(s-1)} = 0 + f'(s) \quad (5)$$

Solving equation (5) for $f'(s)$ gives

$$f'(s) = \frac{2s-1}{s(s-1)}$$

Integrating the above w.r.t s gives

$$\begin{aligned}\int f'(s) ds &= \int \left(\frac{2s-1}{s(s-1)} \right) ds \\ f(s) &= \ln(s(s-1)) + c_1\end{aligned}$$

Where c_1 is constant of integration. Substituting result found above for $f(s)$ into equation (3) gives ϕ

$$\phi = -\ln(t) + \ln(s(s-1)) + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -\ln(t) + \ln(s(s-1))$$

Summary

The solution(s) found are the following

$$-\ln(t) + \ln(s(s-1)) = c_1 \tag{1}$$

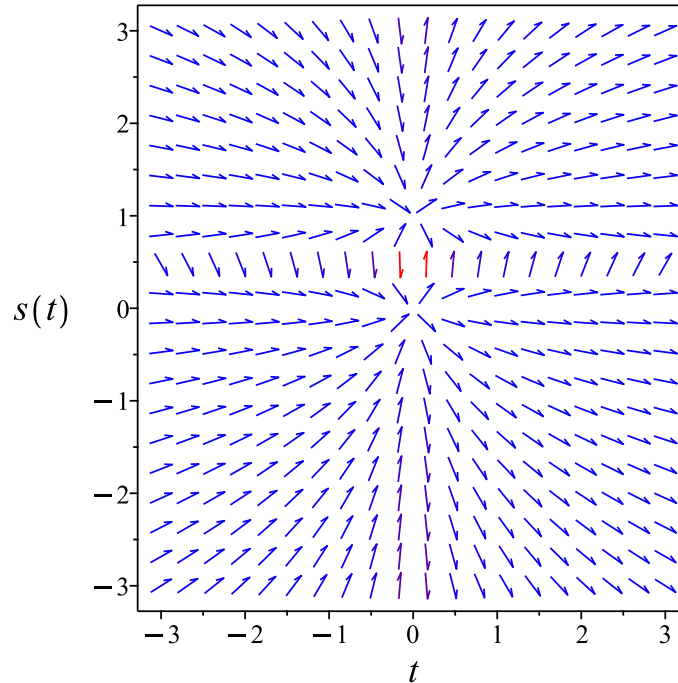


Figure 61: Slope field plot

Verification of solutions

$$-\ln(t) + \ln(s(s-1)) = c_1$$

Verified OK.

3.8.4 Maple step by step solution

Let's solve

$$\frac{(2s-1)s'}{t} + \frac{s-s^2}{t^2} = 0$$

- Highest derivative means the order of the ODE is 1

s'

- Integrate both sides with respect to t

$$\int \left(\frac{(2s-1)s'}{t} + \frac{s-s^2}{t^2} \right) dt = \int 0 dt + c_1$$

- Evaluate integral

$$\frac{s^2-s}{t} = c_1$$

- Solve for s

$$\left\{ s = \frac{1}{2} - \frac{\sqrt{4c_1t+1}}{2}, s = \frac{1}{2} + \frac{\sqrt{4c_1t+1}}{2} \right\}$$

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
trying Bernoulli  
trying separable  
<- separable successful`
```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 31

```
dsolve((2*s(t)-1)/t*diff(s(t),t)+(s(t)-s(t)^2)/t^2=0,s(t), singsol=all)
```

$$s(t) = \frac{1}{2} - \frac{\sqrt{4c_1t+1}}{2}$$
$$s(t) = \frac{1}{2} + \frac{\sqrt{4c_1t+1}}{2}$$

✓ Solution by Mathematica

Time used: 0.682 (sec). Leaf size: 59

```
DSolve[(2*s[t]-1)/t*s'[t]+(s[t]-s[t]^2)/t^2==0,s[t],t,IncludeSingularSolutions -> True]
```

$$s(t) \rightarrow \frac{1}{2}(1 - \sqrt{1 - 4e^{c_1 t}})$$

$$s(t) \rightarrow \frac{1}{2}(1 + \sqrt{1 - 4e^{c_1 t}})$$

$$s(t) \rightarrow 0$$

$$s(t) \rightarrow 1$$

3.9 problem 10

Internal problem ID [11604]

Internal file name [OUTPUT/10586_Thursday_May_18_2023_10_42_52_PM_67193455/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.1 (Exact differential equations and integrating factors). Exercises page 37

Problem number: 10.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**unknown**"

Maple gives the following as the ode type

`[_rational]`

Unable to solve or complete the solution.

$$\frac{2y^{\frac{3}{2}} + 1}{x^{\frac{1}{3}}} + (3\sqrt{x}\sqrt{y} - 1)y' = 0$$

Unable to determine ODE type.

Maple trace

```
`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
trying separable
trying inverse linear
trying homogeneous types:
trying Chini
differential order: 1; looking for linear symmetries
trying exact
Looking for potential symmetries
trying inverse_Riccati
trying an equivalence to an Abel ODE
differential order: 1; trying a linearization to 2nd order
--- trying a change of variables {x -> y(x), y(x) -> x}
differential order: 1; trying a linearization to 2nd order
trying 1st order ODE linearizable_by_differentiation
--- Trying Lie symmetry methods, 1st order ---
`, `-> Computing symmetries using: way = 2
`, `-> Computing symmetries using: way = 3
`, `-> Computing symmetries using: way = 4
`, `-> Computing symmetries using: way = 5
trying symmetry patterns for 1st order ODEs
-> trying a symmetry pattern of the form [F(x)*G(y), 0]
-> trying a symmetry pattern of the form [0, F(x)*G(y)]
-> trying symmetry patterns of the forms [F(x),G(y)] and [G(y),F(x)]
`, `-> Computing symmetries using: way = HINT
-> Calling odsolve with the ODE`, diff(y(x), x)-(1/3)*y(x)/x, y(x)` *** Sublevel 2 *
  Methods for first order ODEs:
  --- Trying classification methods ---
  trying a quadrature
  trying 1st order linear
  <- 1st order linear successful
-> Calling odsolve with the ODE`, diff(y(x), x)-(5/6)*y(x)/x, y(x)` *** Sublevel 2 *
  Methods for first order ODEs:
  --- Trying classification methods ---
  trying a quadrature
  trying 1st order linear
  <- 1st order linear successful
`, `-> Computing symmetries using: way = HINT
-> Calling odsolve with the ODE`, diff(y(x), x)-3*y(x)*x/(2*x^2+x^(1/2)), y(x)` ***
  Methods for first order ODEs:
  --- Trying classification methods ---
  trying a quadrature
```

X Solution by Maple

```
dsolve((2*y(x)^(3/2)+1)/x^(1/3)+(3*x^(1/2)*y(x)^(1/2)-1)*diff(y(x),x)=0,y(x), singsol=all)
```

No solution found

X Solution by Mathematica

Time used: 0.0 (sec). Leaf size: 0

```
DSolve[(2*y[x]^(3/2)+1)/x^(1/3)+(3*x^(1/2)*y[x]^(1/2)-1)*y'[x]==0,y[x],x,IncludeSingularSolu
```

Timed out

3.10 problem 11

3.10.1 Existence and uniqueness analysis	348
3.10.2 Solving as differentialType ode	349
3.10.3 Solving as exact ode	351
3.10.4 Maple step by step solution	354

Internal problem ID [11605]

Internal file name [OUTPUT/10587_Thursday_May_18_2023_10_42_53_PM_49590489/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.1 (Exact differential equations and integrating factors). Exercises page 37

Problem number: 11.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact", "differentialType"

Maple gives the following as the ode type

```
[_exact, _rational, [_1st_order, `_with_symmetry_[F(x),G(x)]`],  
[_Abel, `2nd type`, `class A`]]
```

$$2yx + (x^2 + 4y)y' = 3$$

With initial conditions

$$[y(1) = 2]$$

3.10.1 Existence and uniqueness analysis

This is non linear first order ODE. In canonical form it is written as

$$\begin{aligned}y' &= f(x, y) \\ &= -\frac{2xy - 3}{x^2 + 4y}\end{aligned}$$

The x domain of $f(x, y)$ when $y = 2$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 1$ is inside this domain. The y domain of $f(x, y)$ when $x = 1$ is

$$\left\{ y < -\frac{1}{4} \vee -\frac{1}{4} < y \right\}$$

And the point $y_0 = 2$ is inside this domain. Now we will look at the continuity of

$$\begin{aligned} \frac{\partial f}{\partial y} &= \frac{\partial}{\partial y} \left(-\frac{2xy - 3}{x^2 + 4y} \right) \\ &= -\frac{2x}{x^2 + 4y} + \frac{8xy - 12}{(x^2 + 4y)^2} \end{aligned}$$

The x domain of $\frac{\partial f}{\partial y}$ when $y = 2$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 1$ is inside this domain. The y domain of $\frac{\partial f}{\partial y}$ when $x = 1$ is

$$\left\{ y < -\frac{1}{4} \vee -\frac{1}{4} < y \right\}$$

And the point $y_0 = 2$ is inside this domain. Therefore solution exists and is unique.

3.10.2 Solving as differentialType ode

Writing the ode as

$$y' = \frac{-2yx + 3}{x^2 + 4y} \tag{1}$$

Which becomes

$$(4y) dy = (-x^2) dy + (-2xy + 3) dx \tag{2}$$

But the RHS is complete differential because

$$(-x^2) dy + (-2xy + 3) dx = d(-x^2y + 3x)$$

Hence (2) becomes

$$(4y) dy = d(-x^2y + 3x)$$

Integrating both sides gives gives these solutions

$$y = -\frac{x^2}{4} + \frac{\sqrt{x^4 + 8c_1 + 24x}}{4} + c_1$$

$$y = -\frac{x^2}{4} - \frac{\sqrt{x^4 + 8c_1 + 24x}}{4} + c_1$$

Initial conditions are used to solve for c_1 . Substituting $x = 1$ and $y = 2$ in the above solution gives an equation to solve for the constant of integration.

$$2 = -\frac{1}{4} - \frac{\sqrt{25 + 8c_1}}{4} + c_1$$

$$c_1 = \frac{5}{2} + \frac{\sqrt{11}}{2}$$

Substituting c_1 found above in the general solution gives

$$y = -\frac{x^2}{4} - \frac{\sqrt{x^4 + 20 + 4\sqrt{11} + 24x}}{4} + \frac{5}{2} + \frac{\sqrt{11}}{2}$$

Initial conditions are used to solve for c_1 . Substituting $x = 1$ and $y = 2$ in the above solution gives an equation to solve for the constant of integration.

$$2 = -\frac{1}{4} + \frac{\sqrt{25 + 8c_1}}{4} + c_1$$

$$c_1 = \frac{5}{2} - \frac{\sqrt{11}}{2}$$

Substituting c_1 found above in the general solution gives

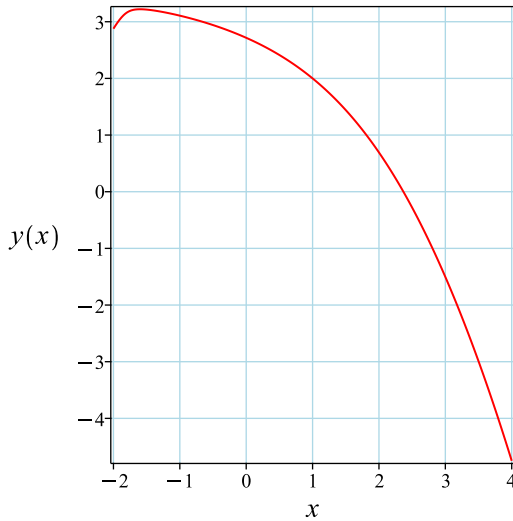
$$y = -\frac{x^2}{4} + \frac{\sqrt{x^4 + 20 - 4\sqrt{11} + 24x}}{4} + \frac{5}{2} - \frac{\sqrt{11}}{2}$$

Summary

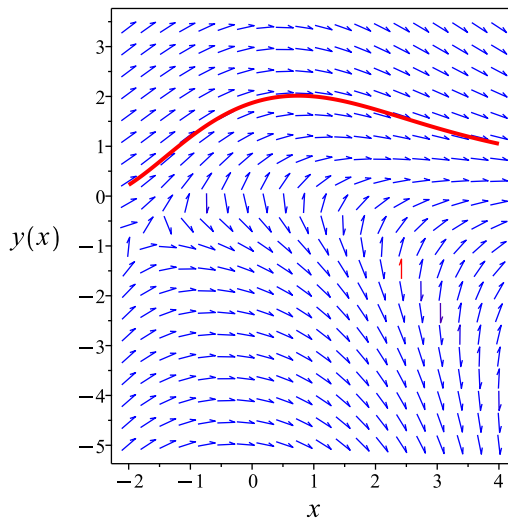
The solution(s) found are the following

$$y = -\frac{x^2}{4} + \frac{\sqrt{x^4 + 20 - 4\sqrt{11} + 24x}}{4} + \frac{5}{2} - \frac{\sqrt{11}}{2} \quad (1)$$

$$y = -\frac{x^2}{4} - \frac{\sqrt{x^4 + 20 + 4\sqrt{11} + 24x}}{4} + \frac{5}{2} + \frac{\sqrt{11}}{2} \quad (2)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = -\frac{x^2}{4} + \frac{\sqrt{x^4 + 20 - 4\sqrt{11} + 24x}}{4} + \frac{5}{2} - \frac{\sqrt{11}}{2}$$

Verified OK.

$$y = -\frac{x^2}{4} - \frac{\sqrt{x^4 + 20 + 4\sqrt{11} + 24x}}{4} + \frac{5}{2} + \frac{\sqrt{11}}{2}$$

Verified OK.

3.10.3 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx}\phi(x, y) = 0$$

Hence

$$\frac{\partial\phi}{\partial x} + \frac{\partial\phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (1A)$$

Therefore

$$\begin{aligned}(x^2 + 4y) dy &= (-2xy + 3) dx \\ (2xy - 3) dx + (x^2 + 4y) dy &= 0\end{aligned} \quad (2A)$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= 2xy - 3 \\ N(x, y) &= x^2 + 4y\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(2xy - 3) \\ &= 2x\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(x^2 + 4y) \\ &= 2x\end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \quad (1)$$

$$\frac{\partial \phi}{\partial y} = N \quad (2)$$

Integrating (1) w.r.t. x gives

$$\begin{aligned} \int \frac{\partial \phi}{\partial x} dx &= \int M dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int 2xy - 3 dx \\ \phi &= x^2y - 3x + f(y) \end{aligned} \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = x^2 + f'(y) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = x^2 + 4y$. Therefore equation (4) becomes

$$x^2 + 4y = x^2 + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 4y$$

Integrating the above w.r.t y gives

$$\begin{aligned} \int f'(y) dy &= \int (4y) dy \\ f(y) &= 2y^2 + c_1 \end{aligned}$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = x^2y + 2y^2 - 3x + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = x^2y + 2y^2 - 3x$$

Initial conditions are used to solve for c_1 . Substituting $x = 1$ and $y = 2$ in the above solution gives an equation to solve for the constant of integration.

$$7 = c_1$$

$$c_1 = 7$$

Substituting c_1 found above in the general solution gives

$$x^2y + 2y^2 - 3x = 7$$

Summary

The solution(s) found are the following

$$x^2y + 2y^2 - 3x = 7 \tag{1}$$

Verification of solutions

$$x^2y + 2y^2 - 3x = 7$$

Verified OK.

3.10.4 Maple step by step solution

Let's solve

$$[2yx + (x^2 + 4y) y' = 3, y(1) = 2]$$

- Highest derivative means the order of the ODE is 1
 y'
- Check if ODE is exact
 - ODE is exact if the lhs is the total derivative of a C^2 function
 $F'(x, y) = 0$
 - Compute derivative of lhs
 $F'(x, y) + \left(\frac{\partial}{\partial y} F(x, y)\right) y' = 0$

- Evaluate derivatives
 $2x = 2x$
- Condition met, ODE is exact
- Exact ODE implies solution will be of this form

$$\left[F(x, y) = c_1, M(x, y) = F'(x, y), N(x, y) = \frac{\partial}{\partial y} F(x, y) \right]$$
- Solve for $F(x, y)$ by integrating $M(x, y)$ with respect to x

$$F(x, y) = \int (2xy - 3) dx + f_1(y)$$
- Evaluate integral

$$F(x, y) = x^2y - 3x + f_1(y)$$
- Take derivative of $F(x, y)$ with respect to y

$$N(x, y) = \frac{\partial}{\partial y} F(x, y)$$
- Compute derivative

$$x^2 + 4y = x^2 + \frac{d}{dy} f_1(y)$$
- Isolate for $\frac{d}{dy} f_1(y)$

$$\frac{d}{dy} f_1(y) = 4y$$
- Solve for $f_1(y)$

$$f_1(y) = 2y^2$$
- Substitute $f_1(y)$ into equation for $F(x, y)$

$$F(x, y) = x^2y + 2y^2 - 3x$$
- Substitute $F(x, y)$ into the solution of the ODE

$$x^2y + 2y^2 - 3x = c_1$$
- Solve for y

$$\left\{ y = -\frac{x^2}{4} - \frac{\sqrt{x^4 + 8c_1 + 24x}}{4}, y = -\frac{x^2}{4} + \frac{\sqrt{x^4 + 8c_1 + 24x}}{4} \right\}$$
- Use initial condition $y(1) = 2$

$$2 = -\frac{1}{4} - \frac{\sqrt{25 + 8c_1}}{4}$$
- Solution does not satisfy initial condition
- Use initial condition $y(1) = 2$

$$2 = -\frac{1}{4} + \frac{\sqrt{25 + 8c_1}}{4}$$

- Solve for c_1
- Substitute $c_1 = 7$ into general solution and simplify

$$y = -\frac{x^2}{4} + \frac{\sqrt{x^4+24x+56}}{4}$$

- Solution to the IVP

$$y = -\frac{x^2}{4} + \frac{\sqrt{x^4+24x+56}}{4}$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
trying separable
trying inverse linear
trying homogeneous types:
trying Chini
differential order: 1; looking for linear symmetries
trying exact
<- exact successful`

```

✓ Solution by Maple

Time used: 0.047 (sec). Leaf size: 22

```
dsolve([(2*x*y(x)-3)+(x^2+4*y(x))*diff(y(x),x)=0,y(1) = 2],y(x), singsol=all)
```

$$y(x) = -\frac{x^2}{4} + \frac{\sqrt{x^4 + 24x + 56}}{4}$$

✓ Solution by Mathematica

Time used: 0.218 (sec). Leaf size: 27

```
DSolve[{(2*x*y[x]-3)+(x^2+4*y[x])*y'[x]==0,{y[1]==2}},y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{1}{4} \left(\sqrt{x^4 + 24x + 56} - x^2 \right)$$

3.11 problem 12

3.11.1 Solving as exact ode 357

Internal problem ID [11606]

Internal file name [OUTPUT/10588_Thursday_May_18_2023_10_42_54_PM_44971533/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.1 (Exact differential equations and integrating factors). Exercises page 37

Problem number: 12.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"exact"**

Maple gives the following as the ode type

`[_exact, _rational]`

$$3x^2y^2 - y^3 + (2yx^3 - 3y^2x + 1) y' = -2x$$

With initial conditions

$$[y(-2) = 1]$$

3.11.1 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial\phi}{\partial x} &= M \\ \frac{\partial\phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \tag{1A}$$

Therefore

$$\begin{aligned}(2y x^3 - 3x y^2 + 1) dy &= (-3x^2 y^2 + y^3 - 2x) dx \\ (3x^2 y^2 - y^3 + 2x) dx + (2y x^3 - 3x y^2 + 1) dy &= 0\end{aligned} \tag{2A}$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= 3x^2 y^2 - y^3 + 2x \\ N(x, y) &= 2y x^3 - 3x y^2 + 1\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(3x^2 y^2 - y^3 + 2x) \\ &= 6x^2 y - 3y^2\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(2y x^3 - 3x y^2 + 1) \\ &= 6x^2 y - 3y^2\end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \quad (1)$$

$$\frac{\partial \phi}{\partial y} = N \quad (2)$$

Integrating (1) w.r.t. x gives

$$\begin{aligned} \int \frac{\partial \phi}{\partial x} dx &= \int M dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int 3x^2y^2 - y^3 + 2x dx \\ \phi &= x(x^2y^2 - y^3 + x) + f(y) \end{aligned} \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\begin{aligned} \frac{\partial \phi}{\partial y} &= x(2x^2y - 3y^2) + f'(y) \\ &= xy(2x^2 - 3y) + f'(y) \end{aligned} \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = 2yx^3 - 3xy^2 + 1$. Therefore equation (4) becomes

$$2yx^3 - 3xy^2 + 1 = xy(2x^2 - 3y) + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 1$$

Integrating the above w.r.t y gives

$$\begin{aligned} \int f'(y) dy &= \int (1) dy \\ f(y) &= y + c_1 \end{aligned}$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = x(x^2y^2 - y^3 + x) + y + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = x(x^2y^2 - y^3 + x) + y$$

Initial conditions are used to solve for c_1 . Substituting $x = -2$ and $y = 1$ in the above solution gives an equation to solve for the constant of integration.

$$-1 = c_1$$

$$c_1 = -1$$

Substituting c_1 found above in the general solution gives

$$x(x^2y^2 - y^3 + x) + y = -1$$

Summary

The solution(s) found are the following

$$y^2x^3 - y^3x + x^2 + y = -1 \quad (1)$$

Verification of solutions

$$y^2x^3 - y^3x + x^2 + y = -1$$

Verified OK.

Maple trace

```
`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
trying separable
trying inverse linear
trying homogeneous types:
trying Chini
differential order: 1; looking for linear symmetries
trying exact
<- exact successful`
```

✓ Solution by Maple

Time used: 28.797 (sec). Leaf size: 210

`dsolve([(3*x^2*y(x)^2-y(x)^3+2*x)+(2*x^3*y(x)-3*x*y(x)^2+1)*diff(y(x),x)=0,y(-2) = 1],y(x),`

$y(x)$

$$= \frac{2^{\frac{2}{3}}(1+i\sqrt{3})\left(\left(2x^7+3\sqrt{3}\sqrt{\frac{4x^{10}+4x^8+44x^5+72x^3+27x-4}{x}}+36x^2+27\right)x^2\right)^{\frac{2}{3}}}{2} + x\left(2x^2\left(\left(2x^7+3\sqrt{3}\sqrt{\frac{4x^{10}+4x^8+44x^5+72x^3+27x-4}{x}}+36x^2+27\right)x\right)\right)$$

✓ Solution by Mathematica

Time used: 60.368 (sec). Leaf size: 250

`DSolve[{(3*x^2*y[x]^2-y[x]^3+2*x)+(2*x^3*y[x]-3*x*y[x]^2+1)*y'[x]==0,{y[-2]==1}},y[x],x,Incl`

$y(x)$

$$\rightarrow \frac{2\sqrt[3]{2}(1-i\sqrt{3})x^6 + 4\sqrt[3]{-2x^9 - 36x^4 - 27x^2 + 3\sqrt{3}\sqrt{x^3(4x^{10} + 4x^8 + 44x^5 + 72x^3 + 27x - 4)}}x^3 + (1}{12x\sqrt[3]{-2x^9 - 36x^4 - 27x^2 + 3\sqrt{3}\sqrt{x^3(4x^{10} + 4x^8 + 44x^5 + 72x^3 + 27x - 4)}}}$$

3.12 problem 13

3.12.1 Existence and uniqueness analysis	362
3.12.2 Solving as exact ode	363
3.12.3 Maple step by step solution	366

Internal problem ID [11607]

Internal file name [OUTPUT/10589_Thursday_May_18_2023_10_42_56_PM_94570214/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.1 (Exact differential equations and integrating factors). Exercises page 37

Problem number: 13.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"exact"**

Maple gives the following as the ode type

```
[_exact, [_Abel, `2nd type`, `class B`]]
```

$$2 \sin(x) \cos(x) y + \sin(x) y^2 + (\sin(x)^2 - 2y \cos(x)) y' = 0$$

With initial conditions

$$[y(0) = 3]$$

3.12.1 Existence and uniqueness analysis

This is non linear first order ODE. In canonical form it is written as

$$\begin{aligned} y' &= f(x, y) \\ &= -\frac{\sin(x) y(2 \cos(x) + y)}{\sin(x)^2 - 2 \cos(x) y} \end{aligned}$$

The x domain of $f(x, y)$ when $y = 3$ is

$$\left\{ \begin{aligned} &-\infty \leq x \leq -\arctan\left(\frac{\sqrt{6\sqrt{10}-18}}{-3+\sqrt{10}}\right) + 2\pi_Z90, \\ &-\arctan\left(\frac{\sqrt{6\sqrt{10}-18}}{-3+\sqrt{10}}\right) + 2\pi_Z90 \leq x \leq \arctan\left(\frac{\sqrt{6\sqrt{10}-18}}{-3+\sqrt{10}}\right) \\ &+ 2\pi_Z90, \arctan\left(-i\sqrt{6\sqrt{10}+18}, -3-\sqrt{10}\right) \\ &+ 2\pi_Z90 < x < \arctan\left(i\sqrt{6\sqrt{10}+18}, -3-\sqrt{10}\right) + 2\pi_Z90 \end{aligned} \right\}$$

But the point $x_0 = 0$ is not inside this domain. Hence existence and uniqueness theorem does not apply. There could be infinite number of solutions, or one solution or no solution at all.

3.12.2 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \quad (\text{A})$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx}\phi(x, y) = 0$$

Hence

$$\frac{\partial\phi}{\partial x} + \frac{\partial\phi}{\partial y} \frac{dy}{dx} = 0 \quad (\text{B})$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial\phi}{\partial x} &= M \\ \frac{\partial\phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (1A)$$

Therefore

$$\begin{aligned} (\sin(x)^2 - 2 \cos(x) y) dy &= (-2 \cos(x) \sin(x) y - \sin(x) y^2) dx \\ (2 \cos(x) \sin(x) y + \sin(x) y^2) dx &+ (\sin(x)^2 - 2 \cos(x) y) dy = 0 \end{aligned} \quad (2A)$$

Comparing (1A) and (2A) shows that

$$\begin{aligned} M(x, y) &= 2 \cos(x) \sin(x) y + \sin(x) y^2 \\ N(x, y) &= \sin(x)^2 - 2 \cos(x) y \end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned} \frac{\partial M}{\partial y} &= \frac{\partial}{\partial y} (2 \cos(x) \sin(x) y + \sin(x) y^2) \\ &= 2 \sin(x) (\cos(x) + y) \end{aligned}$$

And

$$\begin{aligned} \frac{\partial N}{\partial x} &= \frac{\partial}{\partial x} (\sin(x)^2 - 2 \cos(x) y) \\ &= 2 \sin(x) (\cos(x) + y) \end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \quad (1)$$

$$\frac{\partial \phi}{\partial y} = N \quad (2)$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int M dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int 2 \cos(x) \sin(x) y + \sin(x) y^2 dx \\ \phi &= y(\sin(x)^2 - \cos(x) y) + f(y)\end{aligned}\tag{3}$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = \sin(x)^2 - 2 \cos(x) y + f'(y)\tag{4}$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = \sin(x)^2 - 2 \cos(x) y$. Therefore equation (4) becomes

$$\sin(x)^2 - 2 \cos(x) y = \sin(x)^2 - 2 \cos(x) y + f'(y)\tag{5}$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 0$$

Therefore

$$f(y) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(y)$ into equation (3) gives ϕ

$$\phi = y(\sin(x)^2 - \cos(x) y) + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = y(\sin(x)^2 - \cos(x) y)$$

Initial conditions are used to solve for c_1 . Substituting $x = 0$ and $y = 3$ in the above solution gives an equation to solve for the constant of integration.

$$-9 = c_1$$

$$c_1 = -9$$

Substituting c_1 found above in the general solution gives

$$y(\sin(x)^2 - \cos(x)y) = -9$$

Summary

The solution(s) found are the following

$$y(\sin(x)^2 - y \cos(x)) = -9 \quad (1)$$

Verification of solutions

$$y(\sin(x)^2 - y \cos(x)) = -9$$

Verified OK.

3.12.3 Maple step by step solution

Let's solve

$$[2 \sin(x) \cos(x) y + \sin(x) y^2 + (\sin(x)^2 - 2y \cos(x)) y' = 0, y(0) = 3]$$

- Highest derivative means the order of the ODE is 1
- Check if ODE is exact
 - ODE is exact if the lhs is the total derivative of a C^2 function
 - $F'(x, y) = 0$
 - Compute derivative of lhs
 - $F'(x, y) + \left(\frac{\partial}{\partial y} F(x, y)\right) y' = 0$
 - Evaluate derivatives
 - $2 \cos(x) \sin(x) + 2 \sin(x) y = 2 \cos(x) \sin(x) + 2 \sin(x) y$
 - Condition met, ODE is exact
 - Exact ODE implies solution will be of this form
 - $[F(x, y) = c_1, M(x, y) = F'(x, y), N(x, y) = \frac{\partial}{\partial y} F(x, y)]$
 - Solve for $F(x, y)$ by integrating $M(x, y)$ with respect to x
 - $F(x, y) = \int (2 \cos(x) \sin(x) y + \sin(x) y^2) dx + f_1(y)$
 - Evaluate integral

$$F(x, y) = -\cos(x) y^2 + \sin(x)^2 y + f_1(y)$$

- Take derivative of $F(x, y)$ with respect to y

$$N(x, y) = \frac{\partial}{\partial y} F(x, y)$$

- Compute derivative

$$\sin(x)^2 - 2\cos(x)y = -2\cos(x)y + \sin(x)^2 + \frac{d}{dy} f_1(y)$$

- Isolate for $\frac{d}{dy} f_1(y)$

$$\frac{d}{dy} f_1(y) = 0$$

- Solve for $f_1(y)$

$$f_1(y) = 0$$

- Substitute $f_1(y)$ into equation for $F(x, y)$

$$F(x, y) = -\cos(x) y^2 + \sin(x)^2 y$$

- Substitute $F(x, y)$ into the solution of the ODE

$$-\cos(x) y^2 + \sin(x)^2 y = c_1$$

- Solve for y

$$\left\{ y = \frac{\sin(x)^2 - \sqrt{\sin(x)^4 - 4c_1 \cos(x)}}{2\cos(x)}, y = \frac{\sin(x)^2 + \sqrt{\sin(x)^4 - 4c_1 \cos(x)}}{2\cos(x)} \right\}$$

- Use initial condition $y(0) = 3$

$$3 = -\frac{\sqrt{-4c_1}}{2}$$

- Solution does not satisfy initial condition

- Use initial condition $y(0) = 3$

$$3 = \frac{\sqrt{-4c_1}}{2}$$

- Solve for c_1

$$c_1 = -9$$

- Substitute $c_1 = -9$ into general solution and simplify

$$y = \frac{\sec(x) \left(\sin(x)^2 + \sqrt{\sin(x)^4 + 36 \cos(x)} \right)}{2}$$

- Solution to the IVP

$$y = \frac{\sec(x) \left(\sin(x)^2 + \sqrt{\sin(x)^4 + 36 \cos(x)} \right)}{2}$$

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
trying Bernoulli  
trying separable  
trying inverse linear  
trying homogeneous types:  
trying Chini  
differential order: 1; looking for linear symmetries  
trying exact  
<- exact successful`
```

✓ Solution by Maple

Time used: 11.656 (sec). Leaf size: 24

```
dsolve([(2*y(x)*sin(x)*cos(x)+y(x)^2*sin(x))+(sin(x)^2-2*y(x)*cos(x))*diff(y(x),x)=0,y(0) =
```

$$y(x) = \frac{\sec(x) \left(\sin(x)^2 + \sqrt{\sin(x)^4 + 36 \cos(x)} \right)}{2}$$

✓ Solution by Mathematica

Time used: 2.029 (sec). Leaf size: 34

```
DSolve[{(2*y[x]*Sin[x]*Cos[x]+y[x]^2*SIn[x])+(Sin[x]^2-2*y[x]*Cos[x])*y'[x]==0,{y[0]==3}},y[
```

$$y(x) \rightarrow \frac{1}{4} \sec(x) \left(-\cos(2x) + 2\sqrt{\sin^4(x) + 36 \cos(x)} + 1 \right)$$

3.13 problem 14

3.13.1 Existence and uniqueness analysis	369
3.13.2 Solving as exact ode	370

Internal problem ID [11608]

Internal file name [OUTPUT/10590_Thursday_May_18_2023_10_42_58_PM_46650619/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 2, section 2.1 (Exact differential equations and integrating factors). Exercises page 37

Problem number: 14.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"exact"**

Maple gives the following as the ode type

```
[_exact, [_Abel, `2nd type`, `class B`]]
```

$$y e^x + y^2 + (e^x + 2yx) y' = -2 e^x$$

With initial conditions

$$[y(0) = 6]$$

3.13.1 Existence and uniqueness analysis

This is non linear first order ODE. In canonical form it is written as

$$\begin{aligned} y' &= f(x, y) \\ &= -\frac{e^x y + y^2 + 2 e^x}{e^x + 2xy} \end{aligned}$$

The x domain of $f(x, y)$ when $y = 6$ is

$$\left\{ x < -\text{LambertW}\left(-Z92, \frac{1}{12}\right) \vee -\text{LambertW}\left(-Z92, \frac{1}{12}\right) < x \right\}$$

But the point $x_0 = 0$ is not inside this domain. Hence existence and uniqueness theorem does not apply. There could be infinite number of solutions, or one solution or no solution at all.

3.13.2 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \quad (\text{A})$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \quad (\text{B})$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (\text{1A})$$

Therefore

$$\begin{aligned} (e^x + 2xy) dy &= (-e^x y - 2e^x - y^2) dx \\ (e^x y + y^2 + 2e^x) dx + (e^x + 2xy) dy &= 0 \end{aligned} \quad (\text{2A})$$

Comparing (1A) and (2A) shows that

$$\begin{aligned} M(x, y) &= e^x y + y^2 + 2e^x \\ N(x, y) &= e^x + 2xy \end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(e^x y + y^2 + 2e^x) \\ &= e^x + 2y\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(e^x + 2xy) \\ &= e^x + 2y\end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \tag{1}$$

$$\frac{\partial \phi}{\partial y} = N \tag{2}$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int M dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int e^x y + y^2 + 2e^x dx \\ \phi &= e^x(y + 2) + x y^2 + f(y)\end{aligned} \tag{3}$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = e^x + 2xy + f'(y) \tag{4}$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = e^x + 2xy$. Therefore equation (4) becomes

$$e^x + 2xy = e^x + 2xy + f'(y) \tag{5}$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 0$$

Therefore

$$f(y) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(y)$ into equation (3) gives ϕ

$$\phi = e^x(y + 2) + x y^2 + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = e^x(y + 2) + x y^2$$

Initial conditions are used to solve for c_1 . Substituting $x = 0$ and $y = 6$ in the above solution gives an equation to solve for the constant of integration.

$$8 = c_1$$

$$c_1 = 8$$

Substituting c_1 found above in the general solution gives

$$e^x(y + 2) + x y^2 = 8$$

Summary

The solution(s) found are the following

$$e^x(y + 2) + y^2 x = 8 \tag{1}$$

Verification of solutions

$$e^x(y + 2) + y^2 x = 8$$

Verified OK.

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
trying Bernoulli  
trying separable  
trying inverse linear  
trying homogeneous types:  
trying Chini  
differential order: 1; looking for linear symmetries  
trying exact  
<- exact successful`
```

✓ Solution by Maple

Time used: 0.344 (sec). Leaf size: 29

```
dsolve([(y(x)*exp(x)+2*exp(x)+y(x)^2)+(exp(x)+2*x*y(x))*diff(y(x),x)=0,y(0) = 6],y(x), sings
```

$$y(x) = \frac{-e^x + \sqrt{e^{2x} - 8e^x x + 32x}}{2x}$$

✓ Solution by Mathematica

Time used: 32.264 (sec). Leaf size: 37

```
DSolve[{(y[x]*Exp[x]+2*Exp[x]+y[x]^2)+(Exp[x]+2*x*y[x])*y'[x]==0,{y[0]==6}},y[x],x,IncludeSi
```

$$y(x) \rightarrow \frac{\sqrt{-8e^x x + 32x + e^{2x}} - e^x}{2x}$$

3.14 problem 15

3.14.1 Existence and uniqueness analysis	374
3.14.2 Solving as first order ode lie symmetry calculated ode	375
3.14.3 Solving as exact ode	382
3.14.4 Maple step by step solution	386

Internal problem ID [11609]

Internal file name [OUTPUT/10591_Saturday_May_27_2023_03_00_55_AM_75656588/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.1 (Exact differential equations and integrating factors). Exercises page 37

Problem number: 15.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact", "first_order_ode_lie_symmetry_calculated"

Maple gives the following as the ode type

```
[_exact, _rational, [_1st_order, `_with_symmetry_[F(x)*G(y),0]`]]
```

$$\frac{3-y}{x^2} + \frac{(y^2-2x)y'}{y^2x} = 0$$

With initial conditions

$$[y(-1) = 2]$$

3.14.1 Existence and uniqueness analysis

This is non linear first order ODE. In canonical form it is written as

$$\begin{aligned} y' &= f(x, y) \\ &= \frac{y^2(y-3)}{x(y^2-2x)} \end{aligned}$$

The x domain of $f(x, y)$ when $y = 2$ is

$$\{-\infty \leq x < 0, 0 < x < 2, 2 < x \leq \infty\}$$

And the point $x_0 = -1$ is inside this domain. The y domain of $f(x, y)$ when $x = -1$ is

$$\{-\infty < y < \infty\}$$

And the point $y_0 = 2$ is inside this domain. Now we will look at the continuity of

$$\begin{aligned} \frac{\partial f}{\partial y} &= \frac{\partial}{\partial y} \left(\frac{y^2(y-3)}{x(y^2-2x)} \right) \\ &= \frac{2y(y-3)}{x(y^2-2x)} + \frac{y^2}{x(y^2-2x)} - \frac{2y^3(y-3)}{x(y^2-2x)^2} \end{aligned}$$

The x domain of $\frac{\partial f}{\partial y}$ when $y = 2$ is

$$\{-\infty \leq x < 0, 0 < x < 2, 2 < x \leq \infty\}$$

And the point $x_0 = -1$ is inside this domain. The y domain of $\frac{\partial f}{\partial y}$ when $x = -1$ is

$$\{-\infty < y < \infty\}$$

And the point $y_0 = 2$ is inside this domain. Therefore solution exists and is unique.

3.14.2 Solving as first order ode lie symmetry calculated ode

Writing the ode as

$$\begin{aligned} y' &= \frac{y^2(y-3)}{x(y^2-2x)} \\ y' &= \omega(x, y) \end{aligned}$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is not in the lookup table. To determine ξ, η then (A) is solved using ansatz. Making bivariate polynomials of degree 2 to use as anstaz gives

$$\xi = x^2 a_4 + x y a_5 + y^2 a_6 + x a_2 + y a_3 + a_1 \quad (1\text{E})$$

$$\eta = x^2 b_4 + x y b_5 + y^2 b_6 + x b_2 + y b_3 + b_1 \quad (2\text{E})$$

Where the unknown coefficients are

$$\{a_1, a_2, a_3, a_4, a_5, a_6, b_1, b_2, b_3, b_4, b_5, b_6\}$$

Substituting equations (1E,2E) and ω into (A) gives

$$\begin{aligned} & 2xb_4 + yb_5 + b_2 + \frac{y^2(y-3)(-2xa_4 + xb_5 - ya_5 + 2yb_6 - a_2 + b_3)}{x(y^2 - 2x)} \\ & - \frac{y^4(y-3)^2(xa_5 + 2ya_6 + a_3)}{x^2(y^2 - 2x)^2} \\ & - \left(-\frac{y^2(y-3)}{x^2(y^2 - 2x)} + \frac{2y^2(y-3)}{x(y^2 - 2x)^2} \right) (x^2a_4 + xya_5 + y^2a_6 + xa_2 + ya_3 + a_1) \\ & - \left(\frac{2y(y-3)}{x(y^2 - 2x)} + \frac{y^2}{x(y^2 - 2x)} - \frac{2y^3(y-3)}{x(y^2 - 2x)^2} \right) (x^2b_4 \\ & + xyb_5 + y^2b_6 + xb_2 + yb_3 + b_1) = 0 \end{aligned} \quad (5E)$$

Putting the above in normal form gives

$$\begin{aligned} & \frac{x^3y^4b_4 - x^2y^5a_4 + x^2y^5b_5 - xy^6a_5 + xy^6b_6 - y^7a_6 - 2x^4y^2b_4 + 3x^2y^4a_4 - 2x^2y^4a_5 - 3x^2y^4b_5 + 2x^2y^4b_6 + \dots}{=} \\ & = 0 \end{aligned}$$

Setting the numerator to zero gives

$$\begin{aligned} & x^3y^4b_4 - x^2y^5a_4 + x^2y^5b_5 - xy^6a_5 + xy^6b_6 - y^7a_6 - 2x^4y^2b_4 + 3x^2y^4a_4 \\ & - 2x^2y^4a_5 - 3x^2y^4b_5 + 2x^2y^4b_6 + 6xy^5a_5 - 4xy^5a_6 - 6xy^5b_6 + 9y^6a_6 \\ & + 8x^5b_4 - 12x^4yb_4 + 4x^4yb_5 + 2x^3y^2b_2 - 6x^3y^2b_5 - 2x^2y^3a_2 + 6x^2y^3a_5 \\ & + 4x^2y^3b_3 - 4xy^4a_3 - 9xy^4a_5 + 12xy^4a_6 - xy^4b_1 - 3xy^4b_3 + y^5a_1 \\ & + 3y^5a_3 - 18y^5a_6 + 4x^4b_2 - 12x^3yb_2 + 6x^2y^2a_2 + 6x^2y^2b_1 - 6x^2y^2b_3 \\ & - 4xy^3a_1 + 12xy^3a_3 - 3y^4a_1 - 9y^4a_3 - 12x^2yb_1 + 12xy^2a_1 = 0 \end{aligned} \quad (6E)$$

Looking at the above PDE shows the following are all the terms with $\{x, y\}$ in them.

$$\{x, y\}$$

The following substitution is now made to be able to collect on all terms with $\{x, y\}$ in them

$$\{x = v_1, y = v_2\}$$

The above PDE (6E) now becomes

$$\begin{aligned}
& -a_4v_1^2v_2^5 - a_5v_1v_2^6 - a_6v_2^7 + b_4v_1^3v_2^4 + b_5v_1^2v_2^5 + b_6v_1v_2^6 + 3a_4v_1^2v_2^4 - 2a_5v_1^2v_2^4 \\
& + 6a_5v_1v_2^5 - 4a_6v_1v_2^5 + 9a_6v_2^6 - 2b_4v_1^4v_2^2 - 3b_5v_1^2v_2^4 + 2b_6v_1^2v_2^4 - 6b_6v_1v_2^5 \\
& + a_1v_2^5 - 2a_2v_1^2v_2^3 - 4a_3v_1v_2^4 + 3a_3v_2^5 + 6a_5v_1^2v_2^3 - 9a_5v_1v_2^4 + 12a_6v_1v_2^4 \\
& - 18a_6v_2^5 - b_1v_1v_2^4 + 2b_2v_1^3v_2^2 + 4b_3v_1^2v_2^3 - 3b_3v_1v_2^4 + 8b_4v_1^5 - 12b_4v_1^4v_2 \\
& + 4b_5v_1^4v_2 - 6b_5v_1^3v_2^2 - 4a_1v_1v_2^3 - 3a_1v_2^4 + 6a_2v_1^2v_2^2 + 12a_3v_1v_2^3 - 9a_3v_2^4 \\
& + 6b_1v_1^2v_2^2 + 4b_2v_1^4 - 12b_2v_1^3v_2 - 6b_3v_1^2v_2^2 + 12a_1v_1v_2^2 - 12b_1v_1^2v_2 = 0
\end{aligned} \tag{7E}$$

Collecting the above on the terms v_i introduced, and these are

$$\{v_1, v_2\}$$

Equation (7E) now becomes

$$\begin{aligned}
& 8b_4v_1^5 - 2b_4v_1^4v_2^2 + (-12b_4 + 4b_5)v_1^4v_2 + 4b_2v_1^4 + b_4v_1^3v_2^4 + (2b_2 - 6b_5)v_1^3v_2^2 \\
& - 12b_2v_1^3v_2 + (-a_4 + b_5)v_1^2v_2^5 + (3a_4 - 2a_5 - 3b_5 + 2b_6)v_1^2v_2^4 \\
& + (-2a_2 + 6a_5 + 4b_3)v_1^2v_2^3 + (6a_2 + 6b_1 - 6b_3)v_1^2v_2^2 \\
& - 12b_1v_1^2v_2 + (-a_5 + b_6)v_1v_2^6 + (6a_5 - 4a_6 - 6b_6)v_1v_2^5 \\
& + (-4a_3 - 9a_5 + 12a_6 - b_1 - 3b_3)v_1v_2^4 + (-4a_1 + 12a_3)v_1v_2^3 + 12a_1v_1v_2^2 \\
& - a_6v_2^7 + 9a_6v_2^6 + (a_1 + 3a_3 - 18a_6)v_2^5 + (-3a_1 - 9a_3)v_2^4 = 0
\end{aligned} \tag{8E}$$

Setting each coefficients in (8E) to zero gives the following equations to solve

$$\begin{aligned}b_4 &= 0 \\12a_1 &= 0 \\-a_6 &= 0 \\9a_6 &= 0 \\-12b_1 &= 0 \\-12b_2 &= 0 \\4b_2 &= 0 \\-2b_4 &= 0 \\8b_4 &= 0 \\-4a_1 + 12a_3 &= 0 \\-3a_1 - 9a_3 &= 0 \\-a_4 + b_5 &= 0 \\-a_5 + b_6 &= 0 \\2b_2 - 6b_5 &= 0 \\-12b_4 + 4b_5 &= 0 \\a_1 + 3a_3 - 18a_6 &= 0 \\-2a_2 + 6a_5 + 4b_3 &= 0 \\6a_2 + 6b_1 - 6b_3 &= 0 \\6a_5 - 4a_6 - 6b_6 &= 0 \\3a_4 - 2a_5 - 3b_5 + 2b_6 &= 0 \\-4a_3 - 9a_5 + 12a_6 - b_1 - 3b_3 &= 0\end{aligned}$$

Solving the above equations for the unknowns gives

$$\begin{aligned}
 a_1 &= 0 \\
 a_2 &= -3b_6 \\
 a_3 &= 0 \\
 a_4 &= 0 \\
 a_5 &= b_6 \\
 a_6 &= 0 \\
 b_1 &= 0 \\
 b_2 &= 0 \\
 b_3 &= -3b_6 \\
 b_4 &= 0 \\
 b_5 &= 0 \\
 b_6 &= b_6
 \end{aligned}$$

Substituting the above solution in the ansatz (1E,2E) (using 1 as arbitrary value for any unknown in the RHS) gives

$$\begin{aligned}
 \xi &= xy - 3x \\
 \eta &= y^2 - 3y
 \end{aligned}$$

Shifting is now applied to make $\xi = 0$ in order to simplify the rest of the computation

$$\begin{aligned}
 \eta &= \eta - \omega(x, y) \xi \\
 &= y^2 - 3y - \left(\frac{y^2(y-3)}{x(y^2-2x)} \right) (xy - 3x) \\
 &= \frac{2x^2y^2 - 3xy^3 - 6x^2y + 9xy^2}{-xy^2 + 2x^2} \\
 \xi &= 0
 \end{aligned}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{2x^2y^2 - 3xy^3 - 6x^2y + 9xy^2}{-xy^2 + 2x^2}} dy \end{aligned}$$

Which results in

$$S = \frac{\ln(y-3)}{3} - \frac{\ln(y)}{3} + \frac{\ln(-2x+3y)}{3}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = \frac{y^2(y-3)}{x(y^2-2x)}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= \frac{2}{6x-9y} \\ S_y &= \frac{-y^2+2x}{(y-3)y(2x-3y)} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = \frac{1}{3x} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = \frac{1}{3R}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = \frac{\ln(R)}{3} + c_1 \quad (4)$$

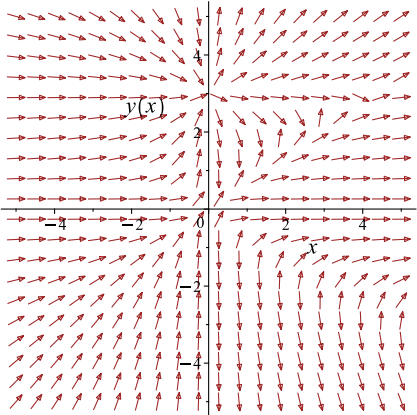
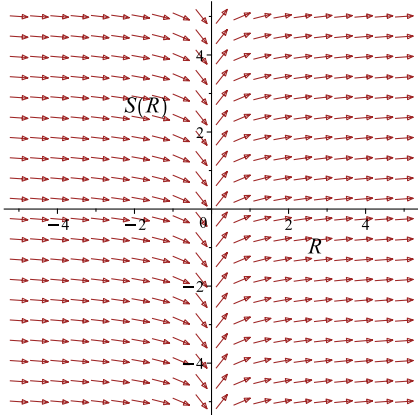
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$\frac{\ln(y-3)}{3} - \frac{\ln(y)}{3} + \frac{\ln(-2x+3y)}{3} = \frac{\ln(x)}{3} + c_1$$

Which simplifies to

$$\frac{\ln(y-3)}{3} - \frac{\ln(y)}{3} + \frac{\ln(-2x+3y)}{3} = \frac{\ln(x)}{3} + c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = \frac{y^2(y-3)}{x(y^2-2x)}$ 	$R = x$ $S = \frac{\ln(y-3)}{3} - \frac{\ln(y)}{3} +$	$\frac{dS}{dR} = \frac{1}{3R}$ 

Initial conditions are used to solve for c_1 . Substituting $x = -1$ and $y = 2$ in the above solution gives an equation to solve for the constant of integration.

$$\frac{i\pi}{3} + \frac{2 \ln(2)}{3} = \frac{i\pi}{3} + c_1$$

$$c_1 = \frac{2 \ln(2)}{3}$$

Substituting c_1 found above in the general solution gives

$$\frac{\ln(y-3)}{3} - \frac{\ln(y)}{3} + \frac{\ln(-2x+3y)}{3} = \frac{\ln(x)}{3} + \frac{2 \ln(2)}{3}$$

Summary

The solution(s) found are the following

$$\frac{\ln(y-3)}{3} - \frac{\ln(y)}{3} + \frac{\ln(-2x+3y)}{3} = \frac{\ln(x)}{3} + \frac{2 \ln(2)}{3} \quad (1)$$

Verification of solutions

$$\frac{\ln(y-3)}{3} - \frac{\ln(y)}{3} + \frac{\ln(-2x+3y)}{3} = \frac{\ln(x)}{3} + \frac{2 \ln(2)}{3}$$

Verified OK.

3.14.3 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \quad (A)$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \quad (B)$$

Comparing (A,B) shows that

$$\frac{\partial \phi}{\partial x} = M$$

$$\frac{\partial \phi}{\partial y} = N$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (1A)$$

Therefore

$$\begin{aligned} \left(\frac{y^2 - 2x}{y^2 x} \right) dy &= \left(-\frac{3 - y}{x^2} \right) dx \\ \left(\frac{3 - y}{x^2} \right) dx + \left(\frac{y^2 - 2x}{y^2 x} \right) dy &= 0 \end{aligned} \quad (2A)$$

Comparing (1A) and (2A) shows that

$$\begin{aligned} M(x, y) &= \frac{3 - y}{x^2} \\ N(x, y) &= \frac{y^2 - 2x}{y^2 x} \end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned} \frac{\partial M}{\partial y} &= \frac{\partial}{\partial y} \left(\frac{3 - y}{x^2} \right) \\ &= -\frac{1}{x^2} \end{aligned}$$

And

$$\begin{aligned} \frac{\partial N}{\partial x} &= \frac{\partial}{\partial x} \left(\frac{y^2 - 2x}{y^2 x} \right) \\ &= -\frac{1}{x^2} \end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \quad (1)$$

$$\frac{\partial \phi}{\partial y} = N \quad (2)$$

Integrating (1) w.r.t. x gives

$$\begin{aligned} \int \frac{\partial \phi}{\partial x} dx &= \int M dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int \frac{3-y}{x^2} dx \\ \phi &= \frac{y-3}{x} + f(y) \end{aligned} \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = \frac{1}{x} + f'(y) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = \frac{y^2-2x}{y^2x}$. Therefore equation (4) becomes

$$\frac{y^2-2x}{y^2x} = \frac{1}{x} + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = -\frac{2}{y^2}$$

Integrating the above w.r.t y gives

$$\begin{aligned} \int f'(y) dy &= \int \left(-\frac{2}{y^2}\right) dy \\ f(y) &= \frac{2}{y} + c_1 \end{aligned}$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = \frac{y-3}{x} + \frac{2}{y} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = \frac{y-3}{x} + \frac{2}{y}$$

Initial conditions are used to solve for c_1 . Substituting $x = -1$ and $y = 2$ in the above solution gives an equation to solve for the constant of integration.

$$2 = c_1$$

$$c_1 = 2$$

Substituting c_1 found above in the general solution gives

$$\frac{y-3}{x} + \frac{2}{y} = 2$$

The above simplifies to

$$-2xy + y^2 + 2x - 3y = 0$$

Summary

The solution(s) found are the following

$$y^2 + (-2x - 3)y + 2x = 0 \tag{1}$$

Verification of solutions

$$y^2 + (-2x - 3)y + 2x = 0$$

Verified OK.

3.14.4 Maple step by step solution

Let's solve

$$\left[\frac{3-y}{x^2} + \frac{(y^2-2x)y'}{y^2x} = 0, y(-1) = 2 \right]$$

- Highest derivative means the order of the ODE is 1
 y'
- Check if ODE is exact
 - ODE is exact if the lhs is the total derivative of a C^2 function
 $F'(x, y) = 0$
 - Compute derivative of lhs
 $F'(x, y) + \left(\frac{\partial}{\partial y} F(x, y) \right) y' = 0$
 - Evaluate derivatives
 $-\frac{1}{x^2} = -\frac{2}{xy^2} - \frac{y^2-2x}{y^2x^2}$
 - Simplify
 $-\frac{1}{x^2} = -\frac{1}{x^2}$
 - Condition met, ODE is exact
- Exact ODE implies solution will be of this form
 $\left[F(x, y) = c_1, M(x, y) = F'(x, y), N(x, y) = \frac{\partial}{\partial y} F(x, y) \right]$
- Solve for $F(x, y)$ by integrating $M(x, y)$ with respect to x
 $F(x, y) = \int \frac{3-y}{x^2} dx + f_1(y)$
- Evaluate integral
 $F(x, y) = -\frac{3-y}{x} + f_1(y)$
- Take derivative of $F(x, y)$ with respect to y
 $N(x, y) = \frac{\partial}{\partial y} F(x, y)$
- Compute derivative
 $\frac{y^2-2x}{y^2x} = \frac{1}{x} + \frac{d}{dy} f_1(y)$
- Isolate for $\frac{d}{dy} f_1(y)$
 $\frac{d}{dy} f_1(y) = -\frac{1}{x} + \frac{y^2-2x}{y^2x}$
- Solve for $f_1(y)$

$$f_1(y) = \frac{y + \frac{2x}{y}}{x} - \frac{y}{x}$$

- Substitute $f_1(y)$ into equation for $F(x, y)$

$$F(x, y) = -\frac{3-y}{x} + \frac{y + \frac{2x}{y}}{x} - \frac{y}{x}$$

- Substitute $F(x, y)$ into the solution of the ODE

$$-\frac{3-y}{x} + \frac{y + \frac{2x}{y}}{x} - \frac{y}{x} = c_1$$

- Solve for y

$$\left\{ y = \frac{c_1 x}{2} + \frac{3}{2} - \frac{\sqrt{c_1^2 x^2 + 6c_1 x - 8x + 9}}{2}, y = \frac{c_1 x}{2} + \frac{3}{2} + \frac{\sqrt{c_1^2 x^2 + 6c_1 x - 8x + 9}}{2} \right\}$$

- Use initial condition $y(-1) = 2$

$$2 = -\frac{c_1}{2} + \frac{3}{2} - \frac{\sqrt{c_1^2 - 6c_1 + 17}}{2}$$

- Solution does not satisfy initial condition

- Use initial condition $y(-1) = 2$

$$2 = -\frac{c_1}{2} + \frac{3}{2} + \frac{\sqrt{c_1^2 - 6c_1 + 17}}{2}$$

- Solve for c_1

$$c_1 = 2$$

- Substitute $c_1 = 2$ into general solution and simplify

$$y = x + \frac{3}{2} + \frac{\sqrt{4x^2 + 4x + 9}}{2}$$

- Solution to the IVP

$$y = x + \frac{3}{2} + \frac{\sqrt{4x^2 + 4x + 9}}{2}$$

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
trying Bernoulli  
trying separable  
trying inverse linear  
trying homogeneous types:  
trying Chini  
differential order: 1; looking for linear symmetries  
trying exact  
<- exact successful`
```

✓ Solution by Maple

Time used: 0.047 (sec). Leaf size: 21

```
dsolve([(3-y(x))/x^2+((y(x)^2-2*x)/(x*y(x)^2))*diff(y(x),x)=0,y(-1) = 2],y(x), singsol=all)
```

$$y(x) = x + \frac{3}{2} + \frac{\sqrt{4x^2 + 4x + 9}}{2}$$

✓ Solution by Mathematica

Time used: 1.961 (sec). Leaf size: 28

```
DSolve[{(3-y[x])/x^2+((y[x]^2-2*x)/(x*y[x]^2))*y'[x]==0,{y[-1]==2}},y[x],x,IncludeSingular
```

$$y(x) \rightarrow \frac{1}{2} \left(\sqrt{4x^2 + 4x + 9} + 2x + 3 \right)$$

3.15 problem 16

3.15.1 Existence and uniqueness analysis	389
3.15.2 Solving as first order ode lie symmetry calculated ode	390
3.15.3 Solving as exact ode	396
3.15.4 Maple step by step solution	400

Internal problem ID [11610]

Internal file name [OUTPUT/10592_Saturday_May_27_2023_03_00_57_AM_57356254/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 2, section 2.1 (Exact differential equations and integrating factors). Exercises page 37

Problem number: 16.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact", "first_order_ode_lie_symmetry_calculated"

Maple gives the following as the ode type

```
[[_homogeneous, `class G`], _exact, _rational]
```

$$\frac{1 + 8xy^{\frac{2}{3}}}{x^{\frac{2}{3}}y^{\frac{1}{3}}} + \frac{\left(2x^{\frac{4}{3}}y^{\frac{2}{3}} - x^{\frac{1}{3}}\right)y'}{y^{\frac{4}{3}}} = 0$$

With initial conditions

$$[y(1) = 8]$$

3.15.1 Existence and uniqueness analysis

This is non linear first order ODE. In canonical form it is written as

$$\begin{aligned} y' &= f(x, y) \\ &= -\frac{8xy^{\frac{5}{3}} + y}{x\left(2xy^{\frac{2}{3}} - 1\right)} \end{aligned}$$

The x domain of $f(x, y)$ when $y = 8$ is

$$\left\{ \frac{1}{8} \leq x \leq \infty, -\infty \leq x < 0, 0 < x \leq \frac{1}{8} \right\}$$

And the point $x_0 = 1$ is inside this domain. The y domain of $f(x, y)$ when $x = 1$ is

$$\left\{ 0 \leq y \leq \frac{\sqrt{2}}{4}, \frac{\sqrt{2}}{4} \leq y \leq \infty \right\}$$

And the point $y_0 = 8$ is inside this domain. Now we will look at the continuity of

$$\begin{aligned} \frac{\partial f}{\partial y} &= \frac{\partial}{\partial y} \left(-\frac{8xy^{\frac{5}{3}} + y}{x(2xy^{\frac{2}{3}} - 1)} \right) \\ &= -\frac{\frac{40xy^{\frac{2}{3}}}{3} + 1}{x(2xy^{\frac{2}{3}} - 1)} + \frac{\frac{32xy^{\frac{5}{3}}}{3} + \frac{4y}{3}}{(2xy^{\frac{2}{3}} - 1)^2 y^{\frac{1}{3}}} \end{aligned}$$

The x domain of $\frac{\partial f}{\partial y}$ when $y = 8$ is

$$\left\{ \frac{1}{8} \leq x \leq \infty, -\infty \leq x < 0, 0 < x \leq \frac{1}{8} \right\}$$

And the point $x_0 = 1$ is inside this domain. The y domain of $\frac{\partial f}{\partial y}$ when $x = 1$ is

$$\left\{ \frac{\sqrt{2}}{4} \leq y \leq \infty, 0 < y \leq \frac{\sqrt{2}}{4} \right\}$$

And the point $y_0 = 8$ is inside this domain. Therefore solution exists and is unique.

3.15.2 Solving as first order ode lie symmetry calculated ode

Writing the ode as

$$\begin{aligned} y' &= -\frac{8xy^{\frac{5}{3}} + y}{x(2xy^{\frac{2}{3}} - 1)} \\ y' &= \omega(x, y) \end{aligned}$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is not in the lookup table. To determine ξ, η then (A) is solved using ansatz. Making bivariate polynomials of degree 1 to use as anstaz gives

$$\xi = xa_2 + ya_3 + a_1 \quad (\text{1E})$$

$$\eta = xb_2 + yb_3 + b_1 \quad (\text{2E})$$

Where the unknown coefficients are

$$\{a_1, a_2, a_3, b_1, b_2, b_3\}$$

Substituting equations (1E,2E) and ω into (A) gives

$$\begin{aligned} & b_2 - \frac{(8xy^{\frac{5}{3}} + y)(b_3 - a_2)}{x(2xy^{\frac{2}{3}} - 1)} - \frac{(8xy^{\frac{5}{3}} + y)^2 a_3}{x^2(2xy^{\frac{2}{3}} - 1)^2} \\ & - \left(-\frac{8y^{\frac{5}{3}}}{x(2xy^{\frac{2}{3}} - 1)} + \frac{8xy^{\frac{5}{3}} + y}{x^2(2xy^{\frac{2}{3}} - 1)} + \frac{2(8xy^{\frac{5}{3}} + y)y^{\frac{2}{3}}}{x(2xy^{\frac{2}{3}} - 1)^2} \right) (xa_2 + ya_3 + a_1) \quad (\text{5E}) \\ & - \left(-\frac{\frac{40xy^{\frac{2}{3}}}{3} + 1}{x(2xy^{\frac{2}{3}} - 1)} + \frac{\frac{32xy^{\frac{5}{3}}}{3} + \frac{4y}{3}}{(2xy^{\frac{2}{3}} - 1)^2 y^{\frac{1}{3}}} \right) (xb_2 + yb_3 + b_1) = 0 \end{aligned}$$

Putting the above in normal form gives

$$\frac{240y^{\frac{11}{3}}x^2a_3 + 48y^{\frac{8}{3}}x^2a_1 - 60y^{\frac{5}{3}}x^4b_2 + 30y^2x^2a_2 + 20x^2y^2b_3 + 60y^3xa_3 - 48y^{\frac{5}{3}}x^3b_1 + 50x^3yb_2 + 38x^2yb_1}{3x^2(2xy^{\frac{2}{3}} - 1)^2 y^{\frac{1}{3}}} = 0$$

Setting the numerator to zero gives

$$\begin{aligned} & -240y^{\frac{11}{3}}x^2a_3 - 48y^{\frac{8}{3}}x^2a_1 + 60y^{\frac{5}{3}}x^4b_2 + 48y^{\frac{5}{3}}x^3b_1 + 3y^{\frac{4}{3}}a_1 - 50x^3yb_2 \quad (\text{6E}) \\ & - 30y^2x^2a_2 - 20x^2y^2b_3 - 60y^3xa_3 - 38x^2yb_1 - 12y^2xa_1 - 3y^{\frac{1}{3}}xb_1 = 0 \end{aligned}$$

Looking at the above PDE shows the following are all the terms with $\{x, y\}$ in them.

$$\left\{ x, y, y^{\frac{1}{3}}, y^{\frac{4}{3}}, y^{\frac{5}{3}}, y^{\frac{8}{3}}, y^{\frac{11}{3}} \right\}$$

The following substitution is now made to be able to collect on all terms with $\{x, y\}$ in them

$$\left\{ x = v_1, y = v_2, y^{\frac{1}{3}} = v_3, y^{\frac{4}{3}} = v_4, y^{\frac{5}{3}} = v_5, y^{\frac{8}{3}} = v_6, y^{\frac{11}{3}} = v_7 \right\}$$

The above PDE (6E) now becomes

$$\begin{aligned} 60v_5v_1^4b_2 - 30v_2^2v_1^2a_2 - 60v_2^3v_1a_3 + 48v_5v_1^3b_1 - 50v_1^3v_2b_2 - 20v_1^2v_2^2b_3 \\ - 48v_6v_1^2a_1 - 12v_2^2v_1a_1 - 240v_7v_1^2a_3 - 38v_1^2v_2b_1 - 3v_3v_1b_1 + 3v_4a_1 = 0 \end{aligned} \quad (7E)$$

Collecting the above on the terms v_i introduced, and these are

$$\{v_1, v_2, v_3, v_4, v_5, v_6, v_7\}$$

Equation (7E) now becomes

$$\begin{aligned} 60v_5v_1^4b_2 - 50v_1^3v_2b_2 + 48v_5v_1^3b_1 + (-30a_2 - 20b_3)v_1^2v_2^2 - 38v_1^2v_2b_1 \\ - 48v_6v_1^2a_1 - 240v_7v_1^2a_3 - 60v_2^3v_1a_3 - 12v_2^2v_1a_1 - 3v_3v_1b_1 + 3v_4a_1 = 0 \end{aligned} \quad (8E)$$

Setting each coefficients in (8E) to zero gives the following equations to solve

$$\begin{aligned} -48a_1 &= 0 \\ -12a_1 &= 0 \\ 3a_1 &= 0 \\ -240a_3 &= 0 \\ -60a_3 &= 0 \\ -38b_1 &= 0 \\ -3b_1 &= 0 \\ 48b_1 &= 0 \\ -50b_2 &= 0 \\ 60b_2 &= 0 \\ -30a_2 - 20b_3 &= 0 \end{aligned}$$

Solving the above equations for the unknowns gives

$$\begin{aligned} a_1 &= 0 \\ a_2 &= a_2 \\ a_3 &= 0 \\ b_1 &= 0 \\ b_2 &= 0 \\ b_3 &= -\frac{3a_2}{2} \end{aligned}$$

Substituting the above solution in the ansatz (1E,2E) (using 1 as arbitrary value for any unknown in the RHS) gives

$$\begin{aligned} \xi &= x \\ \eta &= -\frac{3y}{2} \end{aligned}$$

Shifting is now applied to make $\xi = 0$ in order to simplify the rest of the computation

$$\begin{aligned} \eta &= \eta - \omega(x, y) \xi \\ &= -\frac{3y}{2} - \left(-\frac{8x y^{\frac{5}{3}} + y}{x(2x y^{\frac{2}{3}} - 1)} \right) (x) \\ &= \frac{10x y^{\frac{5}{3}} + 5y}{4x y^{\frac{2}{3}} - 2} \\ \xi &= 0 \end{aligned}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \quad (1)$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y} \right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{10xy^{\frac{5}{3}}+5y}{4xy^{\frac{2}{3}}-2}} dy \end{aligned}$$

Which results in

$$S = \frac{6 \ln(2xy^{\frac{2}{3}} + 1)}{5} - \frac{2 \ln(y)}{5}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{8xy^{\frac{5}{3}} + y}{x(2xy^{\frac{2}{3}} - 1)}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= \frac{12y^{\frac{2}{3}}}{10xy^{\frac{2}{3}} + 5} \\ S_y &= \frac{8x}{y^{\frac{1}{3}}(10xy^{\frac{2}{3}} + 5)} - \frac{2}{5y} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = -\frac{2}{5x} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = -\frac{2}{5R}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = -\frac{2 \ln(R)}{5} + c_1 \quad (4)$$

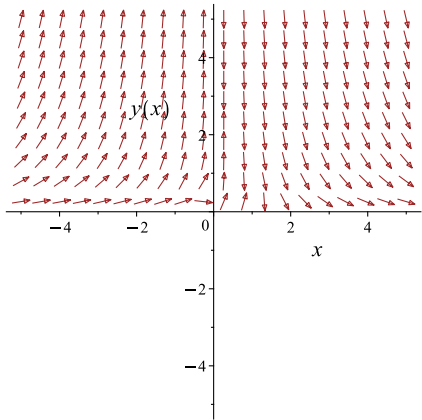
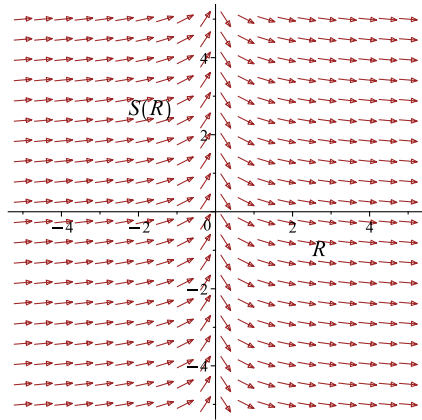
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$\frac{6 \ln(2xy^{\frac{2}{3}} + 1)}{5} - \frac{2 \ln(y)}{5} = -\frac{2 \ln(x)}{5} + c_1$$

Which simplifies to

$$\frac{6 \ln(2xy^{\frac{2}{3}} + 1)}{5} - \frac{2 \ln(y)}{5} = -\frac{2 \ln(x)}{5} + c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{8xy^{\frac{5}{3}} + y}{x(2xy^{\frac{2}{3}} - 1)}$ 	$R = x$ $S = \frac{6 \ln(2xy^{\frac{2}{3}} + 1)}{5}$	$\frac{dS}{dR} = -\frac{2}{5R}$ 

Initial conditions are used to solve for c_1 . Substituting $x = 1$ and $y = 8$ in the above solution gives an equation to solve for the constant of integration.

$$\frac{12 \ln(3)}{5} - \frac{6 \ln(2)}{5} = c_1$$

$$c_1 = \frac{12 \ln(3)}{5} - \frac{6 \ln(2)}{5}$$

Substituting c_1 found above in the general solution gives

$$\frac{6 \ln(2xy^{\frac{2}{3}} + 1)}{5} - \frac{2 \ln(y)}{5} = -\frac{2 \ln(x)}{5} + \frac{12 \ln(3)}{5} - \frac{6 \ln(2)}{5}$$

Summary

The solution(s) found are the following

$$\frac{6 \ln(2xy^{\frac{2}{3}} + 1)}{5} - \frac{2 \ln(y)}{5} = -\frac{2 \ln(x)}{5} + \frac{12 \ln(3)}{5} - \frac{6 \ln(2)}{5} \quad (1)$$

Verification of solutions

$$\frac{6 \ln(2xy^{\frac{2}{3}} + 1)}{5} - \frac{2 \ln(y)}{5} = -\frac{2 \ln(x)}{5} + \frac{12 \ln(3)}{5} - \frac{6 \ln(2)}{5}$$

Verified OK.

3.15.3 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \quad (A)$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \quad (B)$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (1A)$$

Therefore

$$\begin{aligned} & \left(\frac{2x^{\frac{4}{3}}y^{\frac{2}{3}} - x^{\frac{1}{3}}}{y^{\frac{4}{3}}} \right) dy = \left(-\frac{1 + 8xy^{\frac{2}{3}}}{x^{\frac{2}{3}}y^{\frac{1}{3}}} \right) dx \\ & \left(\frac{1 + 8xy^{\frac{2}{3}}}{x^{\frac{2}{3}}y^{\frac{1}{3}}} \right) dx + \left(\frac{2x^{\frac{4}{3}}y^{\frac{2}{3}} - x^{\frac{1}{3}}}{y^{\frac{4}{3}}} \right) dy = 0 \end{aligned} \quad (2A)$$

Comparing (1A) and (2A) shows that

$$\begin{aligned} M(x, y) &= \frac{1 + 8xy^{\frac{2}{3}}}{x^{\frac{2}{3}}y^{\frac{1}{3}}} \\ N(x, y) &= \frac{2x^{\frac{4}{3}}y^{\frac{2}{3}} - x^{\frac{1}{3}}}{y^{\frac{4}{3}}} \end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned} \frac{\partial M}{\partial y} &= \frac{\partial}{\partial y} \left(\frac{1 + 8xy^{\frac{2}{3}}}{x^{\frac{2}{3}}y^{\frac{1}{3}}} \right) \\ &= \frac{8xy^{\frac{2}{3}} - 1}{3x^{\frac{2}{3}}y^{\frac{4}{3}}} \end{aligned}$$

And

$$\begin{aligned} \frac{\partial N}{\partial x} &= \frac{\partial}{\partial x} \left(\frac{2x^{\frac{4}{3}}y^{\frac{2}{3}} - x^{\frac{1}{3}}}{y^{\frac{4}{3}}} \right) \\ &= \frac{8xy^{\frac{2}{3}} - 1}{3x^{\frac{2}{3}}y^{\frac{4}{3}}} \end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \quad (1)$$

$$\frac{\partial \phi}{\partial y} = N \quad (2)$$

Integrating (1) w.r.t. x gives

$$\begin{aligned} \int \frac{\partial \phi}{\partial x} dx &= \int M dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int \frac{1 + 8x y^{\frac{2}{3}}}{x^{\frac{2}{3}} y^{\frac{1}{3}}} dx \\ \phi &= \frac{6x^{\frac{1}{3}} \left(x y^{\frac{2}{3}} + \frac{1}{2} \right)}{y^{\frac{1}{3}}} + f(y) \end{aligned} \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\begin{aligned} \frac{\partial \phi}{\partial y} &= -\frac{2x^{\frac{1}{3}} \left(x y^{\frac{2}{3}} + \frac{1}{2} \right)}{y^{\frac{4}{3}}} + \frac{4x^{\frac{4}{3}}}{y^{\frac{2}{3}}} + f'(y) \\ &= \frac{x^{\frac{1}{3}} \left(2x y^{\frac{2}{3}} - 1 \right)}{y^{\frac{4}{3}}} + f'(y) \end{aligned} \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = \frac{2x^{\frac{4}{3}} y^{\frac{2}{3}} - x^{\frac{1}{3}}}{y^{\frac{4}{3}}}$. Therefore equation (4) becomes

$$\frac{2x^{\frac{4}{3}} y^{\frac{2}{3}} - x^{\frac{1}{3}}}{y^{\frac{4}{3}}} = \frac{x^{\frac{1}{3}} \left(2x y^{\frac{2}{3}} - 1 \right)}{y^{\frac{4}{3}}} + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 0$$

Therefore

$$f(y) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(y)$ into equation (3) gives ϕ

$$\phi = \frac{6x^{\frac{1}{3}} \left(x y^{\frac{2}{3}} + \frac{1}{2} \right)}{y^{\frac{1}{3}}} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = \frac{6x^{\frac{1}{3}} \left(x y^{\frac{2}{3}} + \frac{1}{2} \right)}{y^{\frac{1}{3}}}$$

Initial conditions are used to solve for c_1 . Substituting $x = 1$ and $y = 8$ in the above solution gives an equation to solve for the constant of integration.

$$\frac{27}{2} = c_1$$

$$c_1 = \frac{27}{2}$$

Substituting c_1 found above in the general solution gives

$$\frac{6x^{\frac{1}{3}} \left(x y^{\frac{2}{3}} + \frac{1}{2} \right)}{y^{\frac{1}{3}}} = \frac{27}{2}$$

The above simplifies to

$$12x^{\frac{4}{3}}y^{\frac{2}{3}} - 27y^{\frac{1}{3}} + 6x^{\frac{1}{3}} = 0$$

Summary

The solution(s) found are the following

$$12x^{\frac{4}{3}}y^{\frac{2}{3}} - 27y^{\frac{1}{3}} + 6x^{\frac{1}{3}} = 0 \tag{1}$$

Verification of solutions

$$12x^{\frac{4}{3}}y^{\frac{2}{3}} - 27y^{\frac{1}{3}} + 6x^{\frac{1}{3}} = 0$$

Verified OK.

3.15.4 Maple step by step solution

Let's solve

$$\left[\frac{1+8xy^{\frac{2}{3}}}{x^{\frac{2}{3}}y^{\frac{1}{3}}} + \frac{(2x^{\frac{4}{3}}y^{\frac{2}{3}}-x^{\frac{1}{3}})y'}{y^{\frac{4}{3}}} = 0, y(1) = 8 \right]$$

- Highest derivative means the order of the ODE is 1

y'

- Check if ODE is exact

- ODE is exact if the lhs is the total derivative of a C^2 function

$$F'(x, y) = 0$$

- Compute derivative of lhs

$$F'(x, y) + \left(\frac{\partial}{\partial y} F(x, y) \right) y' = 0$$

- Evaluate derivatives

$$\frac{16x^{\frac{1}{3}}}{3y^{\frac{2}{3}}} - \frac{1+8xy^{\frac{2}{3}}}{3x^{\frac{2}{3}}y^{\frac{4}{3}}} = \frac{\frac{8x^{\frac{1}{3}}y^{\frac{2}{3}}}{3} - \frac{1}{3x^{\frac{2}{3}}}}{y^{\frac{4}{3}}}$$

- Simplify

$$\frac{8xy^{\frac{2}{3}}-1}{3x^{\frac{2}{3}}y^{\frac{4}{3}}} = \frac{8xy^{\frac{2}{3}}-1}{3x^{\frac{2}{3}}y^{\frac{4}{3}}}$$

- Condition met, ODE is exact

- Exact ODE implies solution will be of this form

$$\left[F(x, y) = c_1, M(x, y) = F'(x, y), N(x, y) = \frac{\partial}{\partial y} F(x, y) \right]$$

- Solve for $F(x, y)$ by integrating $M(x, y)$ with respect to x

$$F(x, y) = \int \frac{1+8xy^{\frac{2}{3}}}{x^{\frac{2}{3}}y^{\frac{1}{3}}} dx + f_1(y)$$

- Evaluate integral

$$F(x, y) = \frac{3x^{\frac{1}{3}}+6x^{\frac{4}{3}}y^{\frac{2}{3}}}{y^{\frac{1}{3}}} + f_1(y)$$

- Take derivative of $F(x, y)$ with respect to y

$$N(x, y) = \frac{\partial}{\partial y} F(x, y)$$

- Compute derivative

$$\frac{2x^{\frac{4}{3}}y^{\frac{2}{3}}-x^{\frac{1}{3}}}{y^{\frac{4}{3}}} = -\frac{3x^{\frac{1}{3}}+6x^{\frac{4}{3}}y^{\frac{2}{3}}}{3y^{\frac{4}{3}}} + \frac{4x^{\frac{4}{3}}}{y^{\frac{2}{3}}} + \frac{d}{dy} f_1(y)$$

- Isolate for $\frac{d}{dy}f_1(y)$

$$\frac{d}{dy}f_1(y) = \frac{2x^{\frac{4}{3}}y^{\frac{2}{3}} - x^{\frac{1}{3}}}{y^{\frac{4}{3}}} + \frac{3x^{\frac{1}{3}} + 6x^{\frac{4}{3}}y^{\frac{2}{3}}}{3y^{\frac{4}{3}}} - \frac{4x^{\frac{4}{3}}}{y^{\frac{2}{3}}}$$

- Solve for $f_1(y)$

$$f_1(y) = 0$$

- Substitute $f_1(y)$ into equation for $F(x, y)$

$$F(x, y) = \frac{3x^{\frac{1}{3}} + 6x^{\frac{4}{3}}y^{\frac{2}{3}}}{y^{\frac{1}{3}}}$$

- Substitute $F(x, y)$ into the solution of the ODE

$$\frac{3x^{\frac{1}{3}} + 6x^{\frac{4}{3}}y^{\frac{2}{3}}}{y^{\frac{1}{3}}} = c_1$$

- Solve for y

$$\left\{ y = -\frac{-\frac{3x^{\frac{4}{3}}(-c_1 + \sqrt{c_1^2 - 72x^{\frac{5}{3}}})}{2} + 3c_1x^{\frac{4}{3}} + \frac{c_1^2(-c_1 + \sqrt{c_1^2 - 72x^{\frac{5}{3}}})}{12x^{\frac{1}{3}}}}{36x^{\frac{11}{3}}}, y = -\frac{\frac{3x^{\frac{4}{3}}(c_1 + \sqrt{c_1^2 - 72x^{\frac{5}{3}}})}{2} + 3c_1x^{\frac{4}{3}} - \frac{c_1^2(c_1 + \sqrt{c_1^2 - 72x^{\frac{5}{3}}})}{12x^{\frac{1}{3}}}}{36x^{\frac{11}{3}}} \right\}$$

- Use initial condition $y(1) = 8$

$$8 = -\frac{c_1}{8} + \frac{\sqrt{c_1^2 - 72}}{24} - \frac{c_1^2(-c_1 + \sqrt{c_1^2 - 72})}{432}$$

- Solve for c_1

$$c_1 = \left(-\frac{27}{4} - \frac{21\sqrt{3}}{4}, -\frac{27}{4} + \frac{21\sqrt{3}}{4} \right)$$

- Substitute $c_1 = \left(-\frac{27}{4} - \frac{21\sqrt{3}}{4}, -\frac{27}{4} + \frac{21\sqrt{3}}{4} \right)$ into general solution and simplify

$$y = \frac{(16x^{\frac{5}{3}} - 63\sqrt{3} + 33)\sqrt{-66 + 126\sqrt{3} - 128x^{\frac{5}{3}} + 336\sqrt{3}x^{\frac{5}{3}} - 336\sqrt{3} + 432x^{\frac{5}{3}} + 1620}}{512x^4}$$

- Use initial condition $y(1) = 8$

$$8 = -\frac{c_1}{8} - \frac{\sqrt{c_1^2 - 72}}{24} + \frac{c_1^2(c_1 + \sqrt{c_1^2 - 72})}{432}$$

- Solve for c_1

$$c_1 = \frac{27}{2}$$

- Substitute $c_1 = \frac{27}{2}$ into general solution and simplify

$$y = \frac{(-8x^{\frac{5}{3}} + 81)\sqrt{81 - 32x^{\frac{5}{3}} - 216x^{\frac{5}{3}} + 729}}{128x^4}$$

- Solutions to the IVP

$$\left\{ y = \frac{(-8x^{\frac{5}{3}}+81)\sqrt{81-32x^{\frac{5}{3}}-216x^{\frac{5}{3}}+729}}{128x^4}, y = \frac{(16x^{\frac{5}{3}}-63I\sqrt{3}+33)\sqrt{-66+126I\sqrt{3}-128x^{\frac{5}{3}}+336I\sqrt{3}x^{\frac{5}{3}}-336I\sqrt{3}+432x^{\frac{5}{3}}}}{512x^4} \right.$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
trying separable
trying inverse linear
trying homogeneous types:
trying homogeneous G
1st order, trying the canonical coordinates of the invariance group
<- 1st order, canonical coordinates successful
<- homogeneous successful`

```

✓ Solution by Maple

Time used: 0.172 (sec). Leaf size: 55

```
dsolve([(1+8*x*y(x)^(2/3))/(x^(2/3)*y(x)^(1/3))+((2*x^(4/3)*y(x)^(2/3)-x^(1/3))/(y(x)^(4/3))
```

$$y(x) = \text{RootOf} \left(64_Z^{\frac{7}{3}}x^4 + 96_Z^{\frac{5}{3}}x^3 - 729_Z^{\frac{4}{3}} + 48x^2_Z + 8x_Z^{\frac{1}{3}} \right)$$

✗ Solution by Mathematica

Time used: 0.0 (sec). Leaf size: 0

```
DSolve[{(1+8*x*y[x]^(2/3))/(x^(2/3)*y[x]^(1/3))+((2*x^(4/3)*y[x]^(2/3)-x^(1/3))/(y[x]^(4/3))
```

{}

3.16 problem 21

3.16.1 Solving as first order ode lie symmetry lookup ode	403
3.16.2 Solving as bernoulli ode	407
3.16.3 Solving as exact ode	410

Internal problem ID [11611]

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Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 2, section 2.1 (Exact differential equations and integrating factors). Exercises page 37

Problem number: 21.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "bernoulli", "exactWithIntegrationFactor", "first_order_ode_lie_symmetry_lookup"

Maple gives the following as the ode type

```
[[_homogeneous, `class G`], _rational, _Bernoulli]
```

$$3y^2 + 2xyy' = -4x$$

3.16.1 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = -\frac{3y^2 + 4x}{2xy}$$
$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \tag{A}$$

The type of this ode is known. It is of type Bernoulli. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 66: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int(n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= \frac{1}{x^3y}\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{1}{x^3 y}} dy \end{aligned}$$

Which results in

$$S = \frac{y^2 x^3}{2}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{3y^2 + 4x}{2xy}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= \frac{3x^2 y^2}{2} \\ S_y &= y x^3 \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = -2x^3 \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = -2R^3$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = -\frac{R^4}{2} + c_1 \quad (4)$$

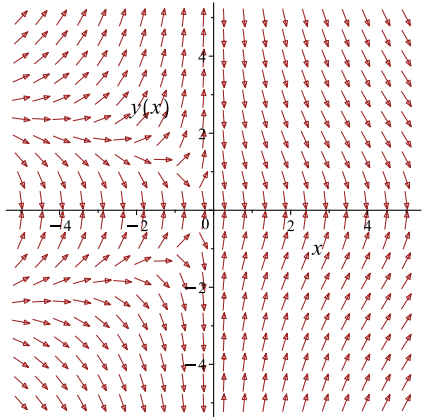
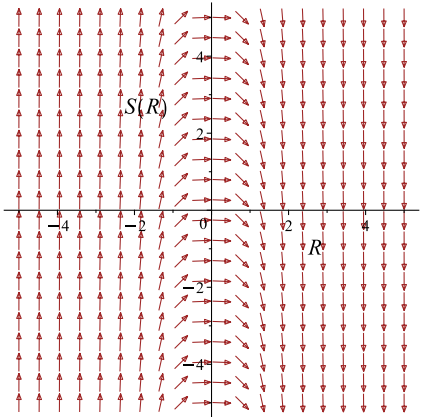
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$\frac{y^2 x^3}{2} = -\frac{x^4}{2} + c_1$$

Which simplifies to

$$\frac{y^2 x^3}{2} = -\frac{x^4}{2} + c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{3y^2 + 4x}{2xy}$ 	$R = x$ $S = \frac{y^2 x^3}{2}$	$\frac{dS}{dR} = -2R^3$ 

Summary

The solution(s) found are the following

$$\frac{y^2 x^3}{2} = -\frac{x^4}{2} + c_1 \quad (1)$$

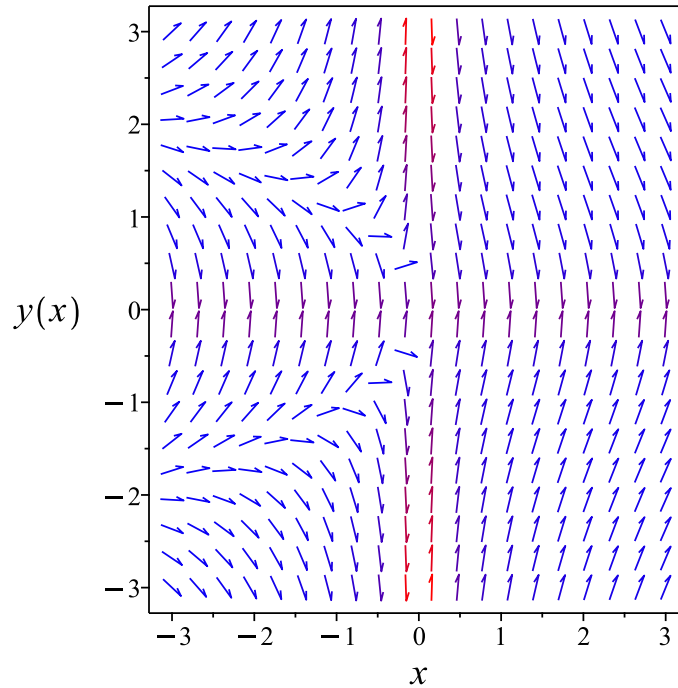


Figure 63: Slope field plot

Verification of solutions

$$\frac{y^2 x^3}{2} = -\frac{x^4}{2} + c_1$$

Verified OK.

3.16.2 Solving as bernoulli ode

In canonical form, the ODE is

$$\begin{aligned} y' &= F(x, y) \\ &= -\frac{3y^2 + 4x}{2xy} \end{aligned}$$

This is a Bernoulli ODE.

$$y' = -\frac{3}{2x}y - 2\frac{1}{y} \quad (1)$$

The standard Bernoulli ODE has the form

$$y' = f_0(x)y + f_1(x)y^n \quad (2)$$

The first step is to divide the above equation by y^n which gives

$$\frac{y'}{y^n} = f_0(x)y^{1-n} + f_1(x) \quad (3)$$

The next step is use the substitution $w = y^{1-n}$ in equation (3) which generates a new ODE in $w(x)$ which will be linear and can be easily solved using an integrating factor. Backsubstitution then gives the solution $y(x)$ which is what we want.

This method is now applied to the ODE at hand. Comparing the ODE (1) With (2) Shows that

$$\begin{aligned}f_0(x) &= -\frac{3}{2x} \\f_1(x) &= -2 \\n &= -1\end{aligned}$$

Dividing both sides of ODE (1) by $y^n = \frac{1}{y}$ gives

$$y'y = -\frac{3y^2}{2x} - 2 \quad (4)$$

Let

$$\begin{aligned}w &= y^{1-n} \\&= y^2\end{aligned} \quad (5)$$

Taking derivative of equation (5) w.r.t x gives

$$w' = 2yy' \quad (6)$$

Substituting equations (5) and (6) into equation (4) gives

$$\begin{aligned}\frac{w'(x)}{2} &= -\frac{3w(x)}{2x} - 2 \\w' &= -\frac{3w}{x} - 4\end{aligned} \quad (7)$$

The above now is a linear ODE in $w(x)$ which is now solved.

Entering Linear first order ODE solver. In canonical form a linear first order is

$$w'(x) + p(x)w(x) = q(x)$$

Where here

$$\begin{aligned}p(x) &= \frac{3}{x} \\q(x) &= -4\end{aligned}$$

Hence the ode is

$$w'(x) + \frac{3w(x)}{x} = -4$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int \frac{3}{x} dx} \\ &= x^3\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu w) &= (\mu)(-4) \\ \frac{d}{dx}(x^3 w) &= (x^3)(-4) \\ d(x^3 w) &= (-4x^3) dx\end{aligned}$$

Integrating gives

$$\begin{aligned}x^3 w &= \int -4x^3 dx \\ x^3 w &= -x^4 + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = x^3$ results in

$$w(x) = -x + \frac{c_1}{x^3}$$

Replacing w in the above by y^2 using equation (5) gives the final solution.

$$y^2 = -x + \frac{c_1}{x^3}$$

Solving for y gives

$$\begin{aligned}y(x) &= \frac{\sqrt{x(-x^4 + c_1)}}{x^2} \\ y(x) &= -\frac{\sqrt{x(-x^4 + c_1)}}{x^2}\end{aligned}$$

Summary

The solution(s) found are the following

$$y = \frac{\sqrt{x(-x^4 + c_1)}}{x^2} \tag{1}$$

$$y = -\frac{\sqrt{x(-x^4 + c_1)}}{x^2} \tag{2}$$

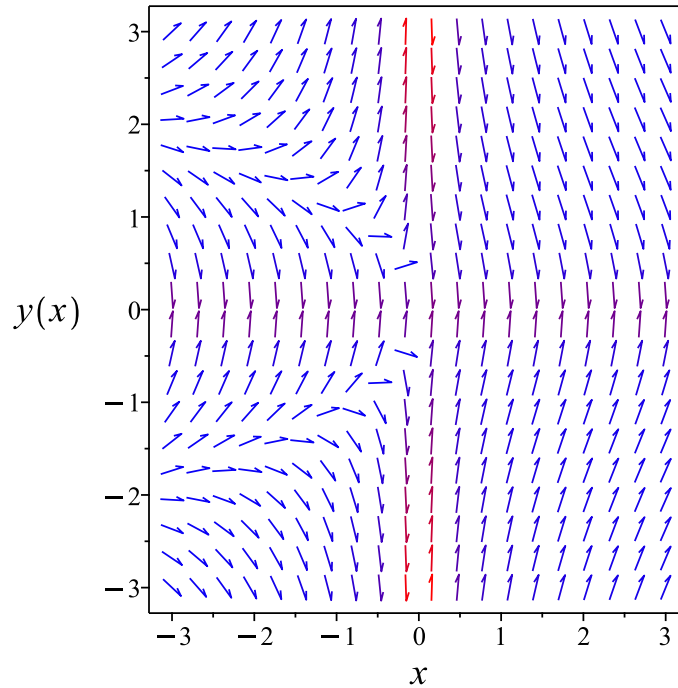


Figure 64: Slope field plot

Verification of solutions

$$y = \frac{\sqrt{x(-x^4 + c_1)}}{x^2}$$

Verified OK.

$$y = -\frac{\sqrt{x(-x^4 + c_1)}}{x^2}$$

Verified OK.

3.16.3 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx}\phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \quad (\text{B})$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (\text{1A})$$

Therefore

$$\begin{aligned} (2xy) dy &= (-3y^2 - 4x) dx \\ (3y^2 + 4x) dx + (2xy) dy &= 0 \end{aligned} \quad (\text{2A})$$

Comparing (1A) and (2A) shows that

$$\begin{aligned} M(x, y) &= 3y^2 + 4x \\ N(x, y) &= 2xy \end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned} \frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(3y^2 + 4x) \\ &= 6y \end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(2xy) \\ &= 2y\end{aligned}$$

Since $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$\begin{aligned}A &= \frac{1}{N} \left(\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} \right) \\ &= \frac{1}{2xy} ((6y) - (2y)) \\ &= \frac{2}{x}\end{aligned}$$

Since A does not depend on y , then it can be used to find an integrating factor. The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int A dx} \\ &= e^{\int \frac{2}{x} dx}\end{aligned}$$

The result of integrating gives

$$\begin{aligned}\mu &= e^{2\ln(x)} \\ &= x^2\end{aligned}$$

M and N are multiplied by this integrating factor, giving new M and new N which are called \bar{M} and \bar{N} for now so not to confuse them with the original M and N .

$$\begin{aligned}\bar{M} &= \mu M \\ &= x^2(3y^2 + 4x) \\ &= 3x^2y^2 + 4x^3\end{aligned}$$

And

$$\begin{aligned}\bar{N} &= \mu N \\ &= x^2(2xy) \\ &= 2y x^3\end{aligned}$$

Now a modified ODE is obtained from the original ODE, which is exact and can be solved. The modified ODE is

$$\begin{aligned}\bar{M} + \bar{N} \frac{dy}{dx} &= 0 \\ (3x^2y^2 + 4x^3) + (2y x^3) \frac{dy}{dx} &= 0\end{aligned}$$

The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = \bar{M} \quad (1)$$

$$\frac{\partial \phi}{\partial y} = \bar{N} \quad (2)$$

Integrating (1) w.r.t. x gives

$$\begin{aligned} \int \frac{\partial \phi}{\partial x} dx &= \int \bar{M} dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int 3x^2y^2 + 4x^3 dx \\ \phi &= x^3(y^2 + x) + f(y) \end{aligned} \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = 2y x^3 + f'(y) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = 2y x^3$. Therefore equation (4) becomes

$$2y x^3 = 2y x^3 + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 0$$

Therefore

$$f(y) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(y)$ into equation (3) gives ϕ

$$\phi = x^3(y^2 + x) + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = x^3(y^2 + x)$$

Summary

The solution(s) found are the following

$$x^3(y^2 + x) = c_1 \quad (1)$$

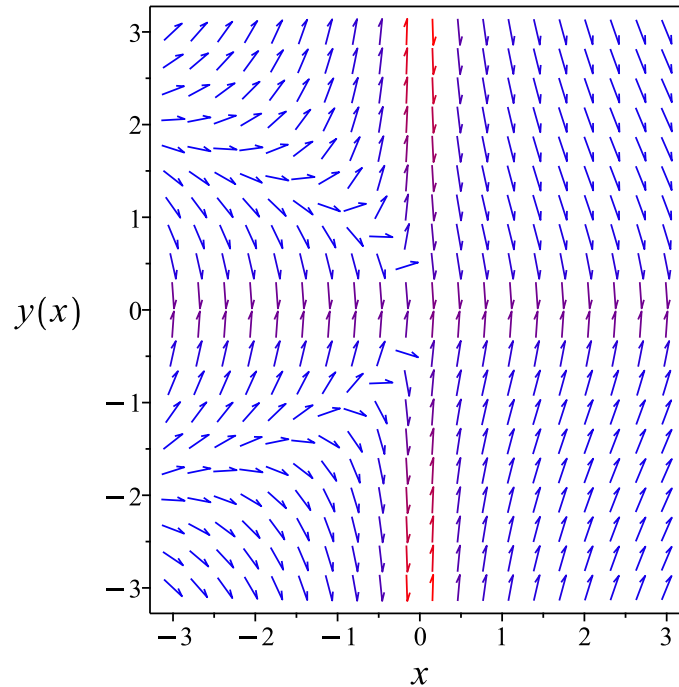


Figure 65: Slope field plot

Verification of solutions

$$x^3(y^2 + x) = c_1$$

Verified OK.

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
trying Bernoulli  
<- Bernoulli successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 38

```
dsolve((4*x+3*y(x)^2)+(2*x*y(x))*diff(y(x),x)=0,y(x), singsol=all)
```

$$y(x) = \frac{\sqrt{x(-x^4 + c_1)}}{x^2}$$
$$y(x) = -\frac{\sqrt{x(-x^4 + c_1)}}{x^2}$$

✓ Solution by Mathematica

Time used: 0.349 (sec). Leaf size: 46

```
DSolve[(4*x+3*y[x]^2)+(2*x*y[x])*y'[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow -\frac{\sqrt{-x^4 + c_1}}{x^{3/2}}$$
$$y(x) \rightarrow \frac{\sqrt{-x^4 + c_1}}{x^{3/2}}$$

3.17 problem 22

3.17.1 Solving as homogeneousTypeD2 ode	416
3.17.2 Solving as first order ode lie symmetry lookup ode	418
3.17.3 Solving as bernoulli ode	422
3.17.4 Solving as exact ode	426
3.17.5 Solving as riccati ode	430

Internal problem ID [11612]

Internal file name [OUTPUT/10594_Saturday_May_27_2023_03_01_02_AM_9338345/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 2, section 2.1 (Exact differential equations and integrating factors). Exercises page 37

Problem number: 22.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "riccati", "bernoulli", "homogeneousTypeD2", "exactWithIntegrationFactor", "first_order_ode_lie_symmetry_lookup"

Maple gives the following as the ode type

```
[[_homogeneous, `class A`], _rational, _Bernoulli]
```

$$y^2 + 2yx - x^2y' = 0$$

3.17.1 Solving as homogeneousTypeD2 ode

Using the change of variables $y = u(x)x$ on the above ode results in new ode in $u(x)$

$$u(x)^2 x^2 + 2u(x)x^2 - x^2(u'(x)x + u(x)) = 0$$

In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= \frac{u(u+1)}{x} \end{aligned}$$

Where $f(x) = \frac{1}{x}$ and $g(u) = u(u + 1)$. Integrating both sides gives

$$\begin{aligned}\frac{1}{u(u+1)} du &= \frac{1}{x} dx \\ \int \frac{1}{u(u+1)} du &= \int \frac{1}{x} dx \\ -\ln(u+1) + \ln(u) &= \ln(x) + c_2\end{aligned}$$

Raising both side to exponential gives

$$e^{-\ln(u+1)+\ln(u)} = e^{\ln(x)+c_2}$$

Which simplifies to

$$\frac{u}{u+1} = c_3 x$$

Therefore the solution y is

$$\begin{aligned}y &= xu \\ &= -\frac{x^2 c_3}{c_3 x - 1}\end{aligned}$$

Summary

The solution(s) found are the following

$$y = -\frac{x^2 c_3}{c_3 x - 1} \tag{1}$$

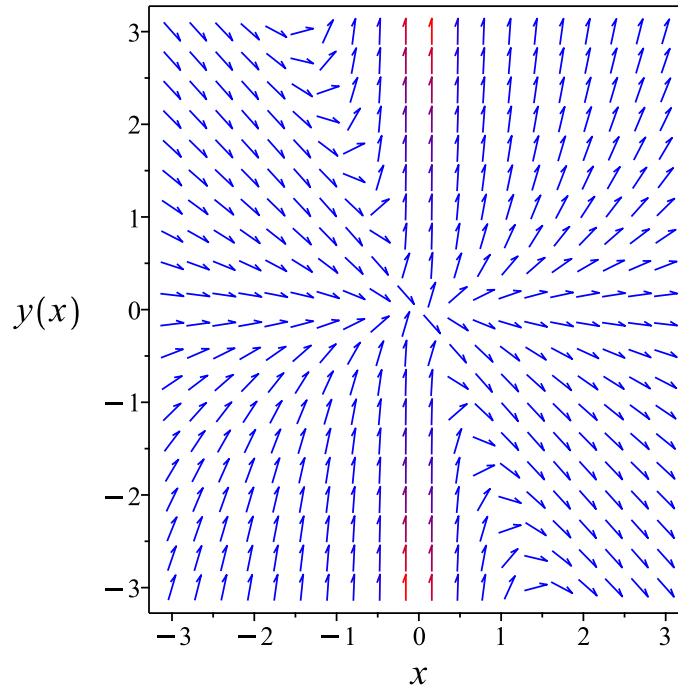


Figure 66: Slope field plot

Verification of solutions

$$y = -\frac{x^2 c_3}{c_3 x - 1}$$

Verified OK.

3.17.2 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = \frac{y(2x + y)}{x^2}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **Bernoulli**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 68: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int(n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= \frac{y^2}{x^2}\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{y^2}{x^2}} dy \end{aligned}$$

Which results in

$$S = -\frac{x^2}{y}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = \frac{y(2x + y)}{x^2}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= -\frac{2x}{y} \\ S_y &= \frac{x^2}{y^2} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 1 \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 1$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = R + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$-\frac{x^2}{y} = x + c_1$$

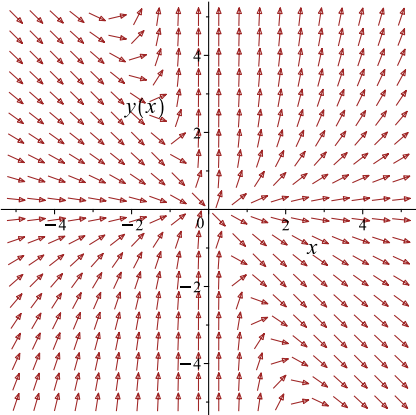
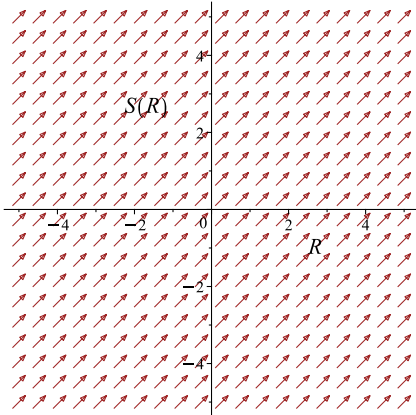
Which simplifies to

$$-\frac{x^2}{y} = x + c_1$$

Which gives

$$y = -\frac{x^2}{x + c_1}$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = \frac{y(2x+y)}{x^2}$ 	$R = x$ $S = -\frac{x^2}{y}$	$\frac{dS}{dR} = 1$ 

Summary

The solution(s) found are the following

$$y = -\frac{x^2}{x + c_1} \quad (1)$$

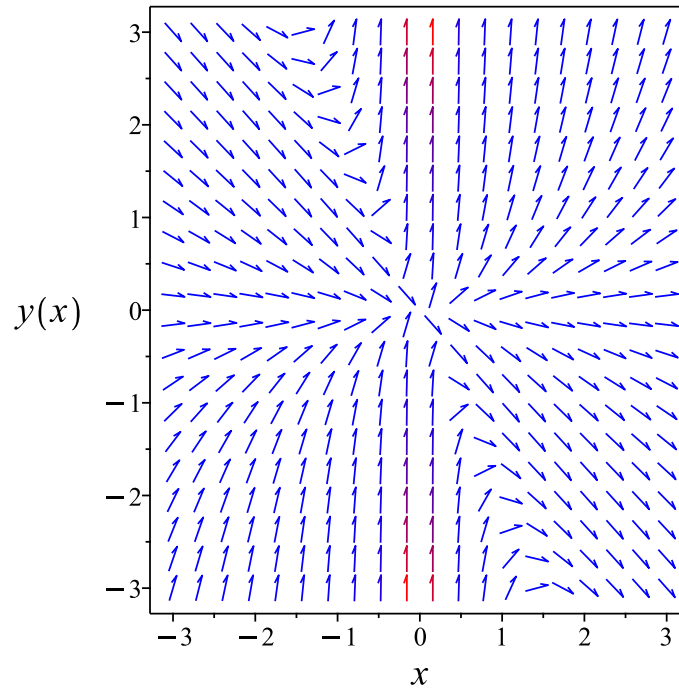


Figure 67: Slope field plot

Verification of solutions

$$y = -\frac{x^2}{x + c_1}$$

Verified OK.

3.17.3 Solving as bernoulli ode

In canonical form, the ODE is

$$\begin{aligned} y' &= F(x, y) \\ &= \frac{y(2x + y)}{x^2} \end{aligned}$$

This is a Bernoulli ODE.

$$y' = \frac{2}{x}y + \frac{1}{x^2}y^2 \quad (1)$$

The standard Bernoulli ODE has the form

$$y' = f_0(x)y + f_1(x)y^n \quad (2)$$

The first step is to divide the above equation by y^n which gives

$$\frac{y'}{y^n} = f_0(x)y^{1-n} + f_1(x) \quad (3)$$

The next step is use the substitution $w = y^{1-n}$ in equation (3) which generates a new ODE in $w(x)$ which will be linear and can be easily solved using an integrating factor. Backsubstitution then gives the solution $y(x)$ which is what we want.

This method is now applied to the ODE at hand. Comparing the ODE (1) With (2) Shows that

$$\begin{aligned} f_0(x) &= \frac{2}{x} \\ f_1(x) &= \frac{1}{x^2} \\ n &= 2 \end{aligned}$$

Dividing both sides of ODE (1) by $y^n = y^2$ gives

$$y' \frac{1}{y^2} = \frac{2}{xy} + \frac{1}{x^2} \quad (4)$$

Let

$$\begin{aligned} w &= y^{1-n} \\ &= \frac{1}{y} \end{aligned} \quad (5)$$

Taking derivative of equation (5) w.r.t x gives

$$w' = -\frac{1}{y^2}y' \quad (6)$$

Substituting equations (5) and (6) into equation (4) gives

$$\begin{aligned} -w'(x) &= \frac{2w(x)}{x} + \frac{1}{x^2} \\ w' &= -\frac{2w}{x} - \frac{1}{x^2} \end{aligned} \quad (7)$$

The above now is a linear ODE in $w(x)$ which is now solved.

Entering Linear first order ODE solver. In canonical form a linear first order is

$$w'(x) + p(x)w(x) = q(x)$$

Where here

$$p(x) = \frac{2}{x}$$
$$q(x) = -\frac{1}{x^2}$$

Hence the ode is

$$w'(x) + \frac{2w(x)}{x} = -\frac{1}{x^2}$$

The integrating factor μ is

$$\mu = e^{\int \frac{2}{x} dx}$$
$$= x^2$$

The ode becomes

$$\frac{d}{dx}(\mu w) = (\mu) \left(-\frac{1}{x^2} \right)$$
$$\frac{d}{dx}(x^2 w) = (x^2) \left(-\frac{1}{x^2} \right)$$
$$d(x^2 w) = -1 dx$$

Integrating gives

$$x^2 w = \int -1 dx$$
$$x^2 w = -x + c_1$$

Dividing both sides by the integrating factor $\mu = x^2$ results in

$$w(x) = -\frac{1}{x} + \frac{c_1}{x^2}$$

which simplifies to

$$w(x) = \frac{-x + c_1}{x^2}$$

Replacing w in the above by $\frac{1}{y}$ using equation (5) gives the final solution.

$$\frac{1}{y} = \frac{-x + c_1}{x^2}$$

Or

$$y = \frac{x^2}{-x + c_1}$$

Summary

The solution(s) found are the following

$$y = \frac{x^2}{-x + c_1} \tag{1}$$

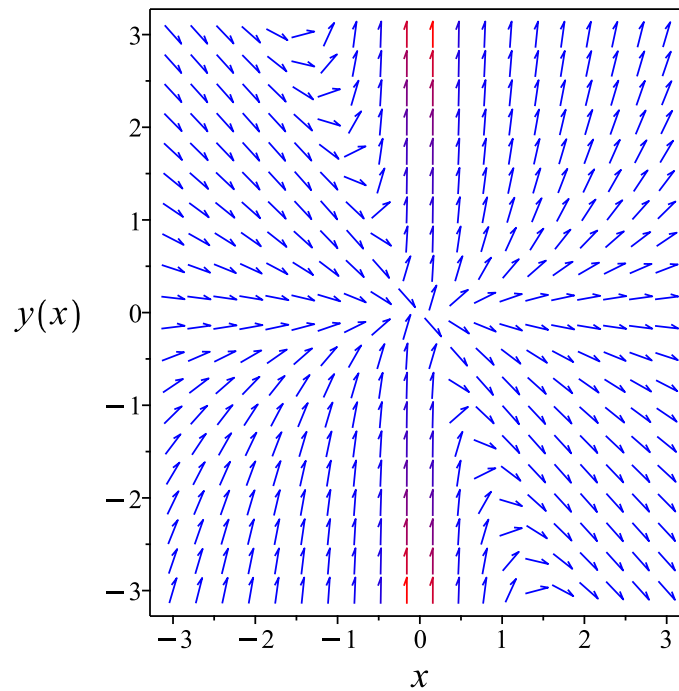


Figure 68: Slope field plot

Verification of solutions

$$y = \frac{x^2}{-x + c_1}$$

Verified OK.

3.17.4 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \quad (\text{A})$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \quad (\text{B})$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (\text{1A})$$

Therefore

$$\begin{aligned} (-x^2) dy &= (-2xy - y^2) dx \\ (2xy + y^2) dx + (-x^2) dy &= 0 \end{aligned} \quad (\text{2A})$$

Comparing (1A) and (2A) shows that

$$\begin{aligned} M(x, y) &= 2xy + y^2 \\ N(x, y) &= -x^2 \end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(2xy + y^2) \\ &= 2y + 2x\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(-x^2) \\ &= -2x\end{aligned}$$

Since $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$\begin{aligned}A &= \frac{1}{N} \left(\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} \right) \\ &= -\frac{1}{x^2} ((2y + 2x) - (-2x)) \\ &= \frac{-4x - 2y}{x^2}\end{aligned}$$

Since A depends on y , it can not be used to obtain an integrating factor. We will now try a second method to find an integrating factor. Let

$$\begin{aligned}B &= \frac{1}{M} \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) \\ &= \frac{1}{y(2x + y)} ((-2x) - (2y + 2x)) \\ &= -\frac{2}{y}\end{aligned}$$

Since B does not depend on x , it can be used to obtain an integrating factor. Let the integrating factor be μ . Then

$$\begin{aligned}\mu &= e^{\int B \, dy} \\ &= e^{\int -\frac{2}{y} \, dy}\end{aligned}$$

The result of integrating gives

$$\begin{aligned}\mu &= e^{-2\ln(y)} \\ &= \frac{1}{y^2}\end{aligned}$$

M and N are now multiplied by this integrating factor, giving new M and new N which are called \overline{M} and \overline{N} so not to confuse them with the original M and N .

$$\begin{aligned}\overline{M} &= \mu M \\ &= \frac{1}{y^2}(2xy + y^2) \\ &= \frac{2x + y}{y}\end{aligned}$$

And

$$\begin{aligned}\overline{N} &= \mu N \\ &= \frac{1}{y^2}(-x^2) \\ &= -\frac{x^2}{y^2}\end{aligned}$$

So now a modified ODE is obtained from the original ODE which will be exact and can be solved using the standard method. The modified ODE is

$$\begin{aligned}\overline{M} + \overline{N} \frac{dy}{dx} &= 0 \\ \left(\frac{2x + y}{y}\right) + \left(-\frac{x^2}{y^2}\right) \frac{dy}{dx} &= 0\end{aligned}$$

The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = \overline{M} \tag{1}$$

$$\frac{\partial \phi}{\partial y} = \overline{N} \tag{2}$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int \overline{M} dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int \frac{2x + y}{y} dx \\ \phi &= \frac{x(y + x)}{y} + f(y)\end{aligned} \tag{3}$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\begin{aligned}\frac{\partial\phi}{\partial y} &= \frac{x}{y} - \frac{x(y+x)}{y^2} + f'(y) \\ &= -\frac{x^2}{y^2} + f'(y)\end{aligned}\tag{4}$$

But equation (2) says that $\frac{\partial\phi}{\partial y} = -\frac{x^2}{y^2}$. Therefore equation (4) becomes

$$-\frac{x^2}{y^2} = -\frac{x^2}{y^2} + f'(y)\tag{5}$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 0$$

Therefore

$$f(y) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(y)$ into equation (3) gives ϕ

$$\phi = \frac{x(y+x)}{y} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = \frac{x(y+x)}{y}$$

The solution becomes

$$y = \frac{x^2}{-x + c_1}$$

Summary

The solution(s) found are the following

$$y = \frac{x^2}{-x + c_1}\tag{1}$$

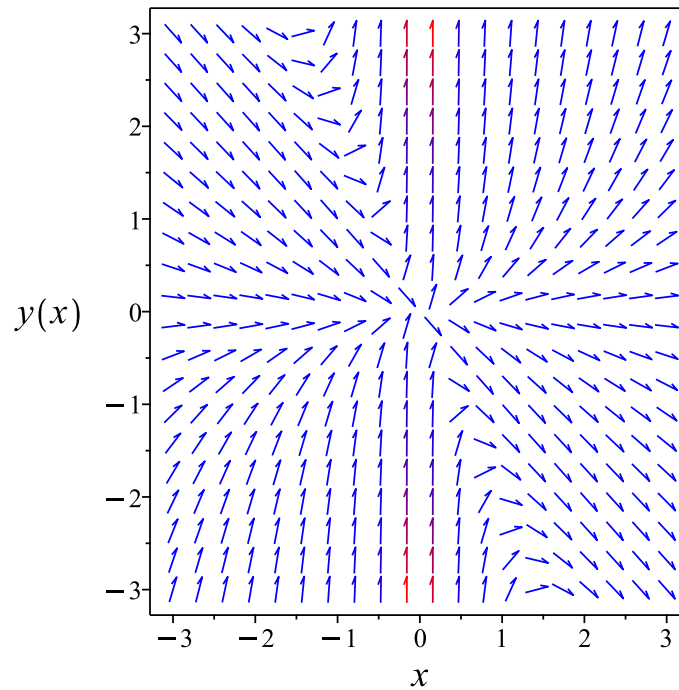


Figure 69: Slope field plot

Verification of solutions

$$y = \frac{x^2}{-x + c_1}$$

Verified OK.

3.17.5 Solving as riccati ode

In canonical form the ODE is

$$\begin{aligned} y' &= F(x, y) \\ &= \frac{y(2x + y)}{x^2} \end{aligned}$$

This is a Riccati ODE. Comparing the ODE to solve

$$y' = \frac{2y}{x} + \frac{y^2}{x^2}$$

With Riccati ODE standard form

$$y' = f_0(x) + f_1(x)y + f_2(x)y^2$$

Shows that $f_0(x) = 0$, $f_1(x) = \frac{2}{x}$ and $f_2(x) = \frac{1}{x^2}$. Let

$$\begin{aligned}y &= \frac{-u'}{f_2 u} \\ &= \frac{-u'}{\frac{u}{x^2}}\end{aligned}\tag{1}$$

Using the above substitution in the given ODE results (after some simplification) in a second order ODE to solve for $u(x)$ which is

$$f_2 u''(x) - (f_2' + f_1 f_2) u'(x) + f_2^2 f_0 u(x) = 0\tag{2}$$

But

$$\begin{aligned}f_2' &= -\frac{2}{x^3} \\ f_1 f_2 &= \frac{2}{x^3} \\ f_2^2 f_0 &= 0\end{aligned}$$

Substituting the above terms back in equation (2) gives

$$\frac{u''(x)}{x^2} = 0$$

Solving the above ODE (this ode solved using Maple, not this program), gives

$$u(x) = c_1 x + c_2$$

The above shows that

$$u'(x) = c_1$$

Using the above in (1) gives the solution

$$y = -\frac{c_1 x^2}{c_1 x + c_2}$$

Dividing both numerator and denominator by c_1 gives, after renaming the constant $\frac{c_2}{c_1} = c_3$ the following solution

$$y = -\frac{c_3 x^2}{c_3 x + 1}$$

Summary

The solution(s) found are the following

$$y = -\frac{c_3 x^2}{c_3 x + 1} \quad (1)$$

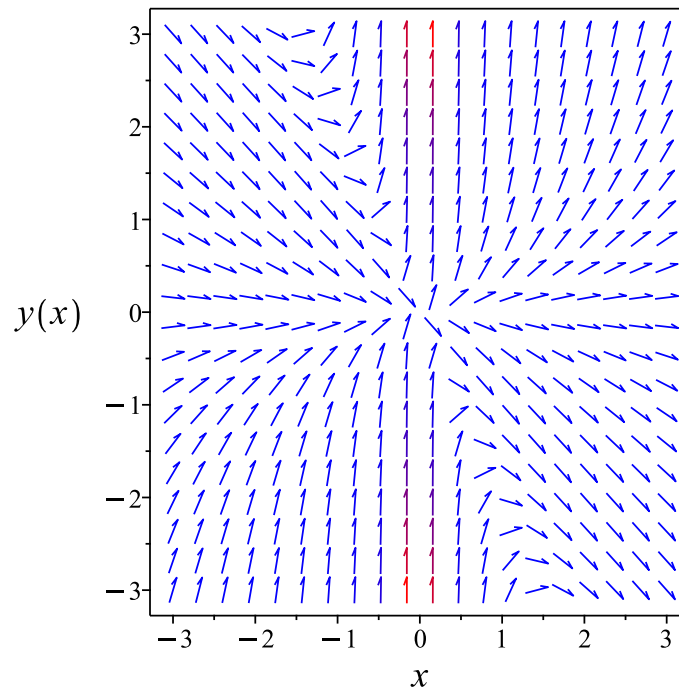


Figure 70: Slope field plot

Verification of solutions

$$y = -\frac{c_3 x^2}{c_3 x + 1}$$

Verified OK.

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
trying Bernoulli  
<- Bernoulli successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 15

```
dsolve((y(x)^2+2*x*y(x))-x^2*diff(y(x),x)=0,y(x), singsol=all)
```

$$y(x) = \frac{x^2}{c_1 - x}$$

✓ Solution by Mathematica

Time used: 0.221 (sec). Leaf size: 23

```
DSolve[(y[x]^2+2*x*y[x])-x^2*y'[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow -\frac{x^2}{x - c_1}$$
$$y(x) \rightarrow 0$$

3.18 problem 24

- 3.18.1 Solving as first order ode lie symmetry calculated ode 434
- 3.18.2 Solving as exact ode 441

Internal problem ID [11613]

Internal file name [OUTPUT/10595_Saturday_May_27_2023_03_01_05_AM_38663670/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 2, section 2.1 (Exact differential equations and integrating factors). Exercises page 37

Problem number: 24.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exactByInspection", "first_order_ode_lie_symmetry_calculated"

Maple gives the following as the ode type

```
[[_1st_order , _with_linear_symmetries] , _rational]
```

$$y + x(x^2 + y^2)^2 + (y(x^2 + y^2)^2 - x) y' = 0$$

3.18.1 Solving as first order ode lie symmetry calculated ode

Writing the ode as

$$y' = -\frac{x^5 + 2y^2x^3 + xy^4 + y}{x^4y + 2y^3x^2 + y^5 - x}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2\xi_y - \omega_x\xi - \omega_y\eta = 0 \tag{A}$$

The type of this ode is not in the lookup table. To determine ξ, η then (A) is solved using ansatz. Making bivariate polynomials of degree 1 to use as anstaz gives

$$\xi = xa_2 + ya_3 + a_1 \tag{1E}$$

$$\eta = xb_2 + yb_3 + b_1 \tag{2E}$$

Where the unknown coefficients are

$$\{a_1, a_2, a_3, b_1, b_2, b_3\}$$

Substituting equations (1E,2E) and ω into (A) gives

$$\begin{aligned} b_2 - \frac{(x^5 + 2y^2x^3 + xy^4 + y)(b_3 - a_2)}{x^4y + 2y^3x^2 + y^5 - x} \\ - \frac{(x^5 + 2y^2x^3 + xy^4 + y)^2 a_3}{(x^4y + 2y^3x^2 + y^5 - x)^2} - \left(\frac{5x^4 + 6x^2y^2 + y^4}{x^4y + 2y^3x^2 + y^5 - x} \right. \\ \left. + \frac{(x^5 + 2y^2x^3 + xy^4 + y)(4yx^3 + 4xy^3 - 1)}{(x^4y + 2y^3x^2 + y^5 - x)^2} \right) (xa_2 + ya_3 + a_1) \\ - \left(\frac{4yx^3 + 4xy^3 + 1}{x^4y + 2y^3x^2 + y^5 - x} \right. \\ \left. + \frac{(x^5 + 2y^2x^3 + xy^4 + y)(x^4 + 6x^2y^2 + 5y^4)}{(x^4y + 2y^3x^2 + y^5 - x)^2} \right) (xb_2 + yb_3 + b_1) = 0 \end{aligned} \quad (5E)$$

Putting the above in normal form gives

$$\frac{-x^{10}a_3 + x^{10}b_2 - 2x^9ya_2 + 2x^9yb_3 + 3x^8y^2a_3 + 3x^8y^2b_2 - 8x^7y^3a_2 + 8x^7y^3b_3 + 2x^6y^4a_3 + 2x^6y^4b_2 - 12x^5y^5a_2 + 12x^5y^5b_3 + 2x^4y^6a_3 + 2x^4y^6b_2 - 12x^3y^7a_2 + 12x^3y^7b_3 + 3x^2y^8a_3 + 3x^2y^8b_2 + 2xy^9a_2 + 2xy^9b_3 + y^{10}a_3 + y^{10}b_2 - x^9b_1 + x^8ya_1 - 4x^7y^2b_1 + 4x^6y^3a_1 - 6x^5y^4b_1 + 6x^4y^5a_1 - 4x^3y^6b_1 + 4x^2y^7a_1 - xy^8b_1 + y^9a_1 - 5x^6a_2 + x^6b_3 - 6x^5ya_3 - 6x^5yb_2 - 9x^4y^2a_2 - 3x^4y^2b_3 - 12x^3y^3a_3 - 12x^3y^3b_2 - 3x^2y^4a_2 - 9x^2y^4b_3 - 6xy^5a_3 - 6xy^5b_2 + y^6a_2 - 5y^6b_3 - 4x^5a_1 - 4x^4yb_1 - 8x^3y^2a_1 - 8x^2y^3b_1 - 4xy^4a_1 - 4y^5b_1 - xb_1 + ya_1}{1} = 0$$

Setting the numerator to zero gives

$$\begin{aligned} -x^{10}a_3 - x^{10}b_2 + 2x^9ya_2 - 2x^9yb_3 - 3x^8y^2a_3 - 3x^8y^2b_2 + 8x^7y^3a_2 \\ - 8x^7y^3b_3 - 2x^6y^4a_3 - 2x^6y^4b_2 + 12x^5y^5a_2 - 12x^5y^5b_3 + 2x^4y^6a_3 \\ + 2x^4y^6b_2 + 8x^3y^7a_2 - 8x^3y^7b_3 + 3x^2y^8a_3 + 3x^2y^8b_2 + 2xy^9a_2 \\ - 2xy^9b_3 + y^{10}a_3 + y^{10}b_2 - x^9b_1 + x^8ya_1 - 4x^7y^2b_1 + 4x^6y^3a_1 \\ - 6x^5y^4b_1 + 6x^4y^5a_1 - 4x^3y^6b_1 + 4x^2y^7a_1 - xy^8b_1 + y^9a_1 - 5x^6a_2 \\ + x^6b_3 - 6x^5ya_3 - 6x^5yb_2 - 9x^4y^2a_2 - 3x^4y^2b_3 - 12x^3y^3a_3 - 12x^3y^3b_2 \\ - 3x^2y^4a_2 - 9x^2y^4b_3 - 6xy^5a_3 - 6xy^5b_2 + y^6a_2 - 5y^6b_3 - 4x^5a_1 \\ - 4x^4yb_1 - 8x^3y^2a_1 - 8x^2y^3b_1 - 4xy^4a_1 - 4y^5b_1 - xb_1 + ya_1 = 0 \end{aligned} \quad (6E)$$

Looking at the above PDE shows the following are all the terms with $\{x, y\}$ in them.

$$\{x, y\}$$

The following substitution is now made to be able to collect on all terms with $\{x, y\}$ in them

$$\{x = v_1, y = v_2\}$$

The above PDE (6E) now becomes

$$\begin{aligned}
& 2a_2v_1^9v_2 + 8a_2v_1^7v_2^3 + 12a_2v_1^5v_2^5 + 8a_2v_1^3v_2^7 + 2a_2v_1v_2^9 - a_3v_1^{10} - 3a_3v_1^8v_2^2 \\
& - 2a_3v_1^6v_2^4 + 2a_3v_1^4v_2^6 + 3a_3v_1^2v_2^8 + a_3v_2^{10} - b_2v_1^{10} - 3b_2v_1^8v_2^2 - 2b_2v_1^6v_2^4 \\
& + 2b_2v_1^4v_2^6 + 3b_2v_1^2v_2^8 + b_2v_2^{10} - 2b_3v_1^9v_2 - 8b_3v_1^7v_2^3 - 12b_3v_1^5v_2^5 \\
& - 8b_3v_1^3v_2^7 - 2b_3v_1v_2^9 + a_1v_1^8v_2 + 4a_1v_1^6v_2^3 + 6a_1v_1^4v_2^5 + 4a_1v_1^2v_2^7 + a_1v_2^9 \\
& - b_1v_1^9 - 4b_1v_1^7v_2^2 - 6b_1v_1^5v_2^4 - 4b_1v_1^3v_2^6 - b_1v_1v_2^8 - 5a_2v_1^6 - 9a_2v_1^4v_2^2 \\
& - 3a_2v_1^2v_2^4 + a_2v_2^6 - 6a_3v_1^5v_2 - 12a_3v_1^3v_2^3 - 6a_3v_1v_2^5 - 6b_2v_1^5v_2 \\
& - 12b_2v_1^3v_2^3 - 6b_2v_1v_2^5 + b_3v_1^6 - 3b_3v_1^4v_2^2 - 9b_3v_1^2v_2^4 - 5b_3v_2^6 - 4a_1v_1^5 \\
& - 8a_1v_1^3v_2^2 - 4a_1v_1v_2^4 - 4b_1v_1^4v_2 - 8b_1v_1^2v_2^3 - 4b_1v_2^5 + a_1v_2 - b_1v_1 = 0
\end{aligned} \tag{7E}$$

Collecting the above on the terms v_i introduced, and these are

$$\{v_1, v_2\}$$

Equation (7E) now becomes

$$\begin{aligned}
& (2a_3 + 2b_2)v_1^4v_2^6 + (-9a_2 - 3b_3)v_1^4v_2^2 + (8a_2 - 8b_3)v_1^3v_2^7 + (-3a_3 - 3b_2)v_1^8v_2^2 + (8a_2 - 8b_3)v_1^7v_2^3 \\
& + (-2a_3 - 2b_2)v_1^6v_2^4 + (12a_2 - 12b_3)v_1^5v_2^5 + (-6a_3 - 6b_2)v_1^5v_2 + (-12a_3 - 12b_2)v_1^3v_2^3 \\
& + (3a_3 + 3b_2)v_1^2v_2^8 + (-3a_2 - 9b_3)v_1^2v_2^4 + (2a_2 - 2b_3)v_1v_2^9 + (-6a_3 - 6b_2)v_1v_2^5 \\
& + (2a_2 - 2b_3)v_1^9v_2 + a_1v_2^9 - b_1v_1^9 - 4a_1v_1^5 - 4b_1v_2^5 + a_1v_2 - b_1v_1 + (a_3 + b_2)v_2^{10} \\
& + (a_2 - 5b_3)v_2^6 + (-5a_2 + b_3)v_1^6 + (-a_3 - b_2)v_1^{10} + a_1v_1^8v_2 + 4a_1v_1^6v_2^3 + 6a_1v_1^4v_2^5 + 4a_1v_1^2v_2^7 \\
& - 4b_1v_1^7v_2^2 - 6b_1v_1^5v_2^4 - 4b_1v_1^3v_2^6 - b_1v_1v_2^8 - 8a_1v_1^3v_2^2 - 4a_1v_1v_2^4 - 4b_1v_1^4v_2 - 8b_1v_1^2v_2^3 = 0
\end{aligned} \tag{8E}$$

Setting each coefficients in (8E) to zero gives the following equations to solve

$$\begin{aligned}a_1 &= 0 \\-8a_1 &= 0 \\-4a_1 &= 0 \\4a_1 &= 0 \\6a_1 &= 0 \\-8b_1 &= 0 \\-6b_1 &= 0 \\-4b_1 &= 0 \\-b_1 &= 0 \\-9a_2 - 3b_3 &= 0 \\-5a_2 + b_3 &= 0 \\-3a_2 - 9b_3 &= 0 \\a_2 - 5b_3 &= 0 \\2a_2 - 2b_3 &= 0 \\8a_2 - 8b_3 &= 0 \\12a_2 - 12b_3 &= 0 \\-12a_3 - 12b_2 &= 0 \\-6a_3 - 6b_2 &= 0 \\-3a_3 - 3b_2 &= 0 \\-2a_3 - 2b_2 &= 0 \\-a_3 - b_2 &= 0 \\a_3 + b_2 &= 0 \\2a_3 + 2b_2 &= 0 \\3a_3 + 3b_2 &= 0\end{aligned}$$

Solving the above equations for the unknowns gives

$$\begin{aligned}a_1 &= 0 \\a_2 &= 0 \\a_3 &= -b_2 \\b_1 &= 0 \\b_2 &= b_2 \\b_3 &= 0\end{aligned}$$

Substituting the above solution in the anstaz (1E,2E) (using 1 as arbitrary value for any unknown in the RHS) gives

$$\begin{aligned}\xi &= -y \\ \eta &= x\end{aligned}$$

Shifting is now applied to make $\xi = 0$ in order to simplify the rest of the computation

$$\begin{aligned}\eta &= \eta - \omega(x, y) \xi \\ &= x - \left(-\frac{x^5 + 2y^2x^3 + xy^4 + y}{x^4y + 2y^3x^2 + y^5 - x} \right) (-y) \\ &= \frac{-x^2 - y^2}{x^4y + 2y^3x^2 + y^5 - x} \\ \xi &= 0\end{aligned}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \quad (1)$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y} \right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned}S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{-x^2 - y^2}{x^4y + 2y^3x^2 + y^5 - x}} dy\end{aligned}$$

Which results in

$$S = -\frac{y^4}{4} - \frac{x^2y^2}{2} + \arctan\left(\frac{y}{x}\right)$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{x^5 + 2y^2x^3 + xy^4 + y}{x^4y + 2y^3x^2 + y^5 - x}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= -\frac{y(yx^3 + xy^3 + 1)}{x^2 + y^2} \\ S_y &= -y^3 - x^2y + \frac{x}{x^2 + y^2} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = x^3 \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = R^3$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = \frac{R^4}{4} + c_1 \quad (4)$$

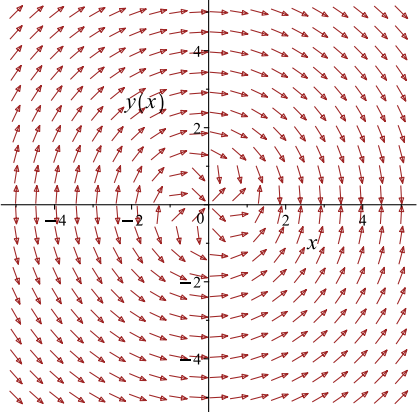
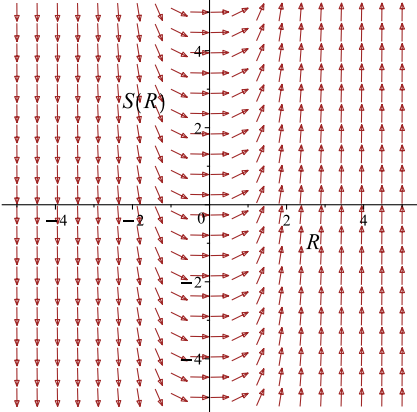
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$-\frac{y^4}{4} - \frac{x^2y^2}{2} + \arctan\left(\frac{y}{x}\right) = \frac{x^4}{4} + c_1$$

Which simplifies to

$$-\frac{y^4}{4} - \frac{x^2y^2}{2} + \arctan\left(\frac{y}{x}\right) = \frac{x^4}{4} + c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{x^5+2y^2x^3+xy^4+y}{x^4y+2y^3x^2+y^5-x}$ 	$R = x$ $S = -\frac{y^4}{4} - \frac{x^2y^2}{2} + \arctan\left(\frac{y}{x}\right)$	$\frac{dS}{dR} = R^3$ 

Summary

The solution(s) found are the following

$$-\frac{y^4}{4} - \frac{x^2y^2}{2} + \arctan\left(\frac{y}{x}\right) = \frac{x^4}{4} + c_1 \tag{1}$$

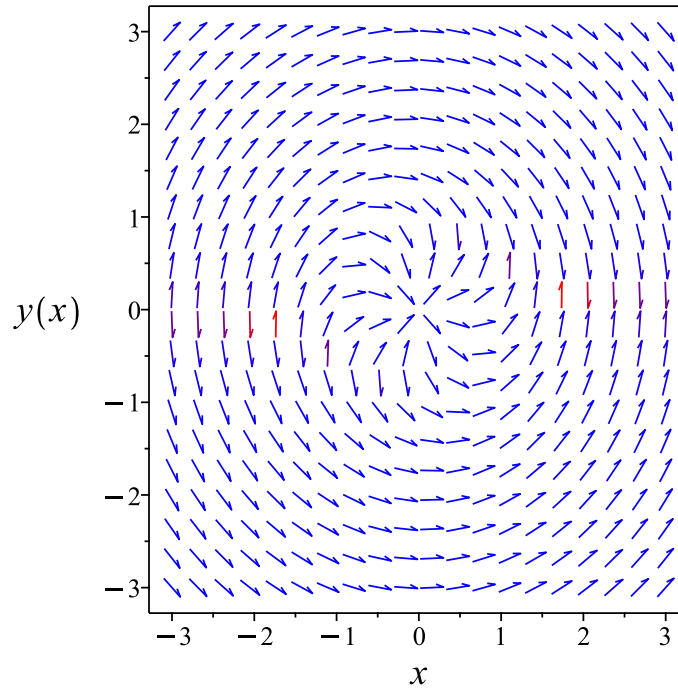


Figure 71: Slope field plot

Verification of solutions

$$-\frac{y^4}{4} - \frac{x^2 y^2}{2} + \arctan\left(\frac{y}{x}\right) = \frac{x^4}{4} + c_1$$

Verified OK.

3.18.2 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (1A)$$

Therefore

$$\begin{aligned}(y(x^2 + y^2)^2 - x) dy &= (-y - (x^2 + y^2)^2 x) dx \\ (y + (x^2 + y^2)^2 x) dx &+ (y(x^2 + y^2)^2 - x) dy = 0\end{aligned} \quad (2A)$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= y + (x^2 + y^2)^2 x \\ N(x, y) &= y(x^2 + y^2)^2 - x\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y} (y + (x^2 + y^2)^2 x) \\ &= 4y x^3 + 4x y^3 + 1\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x} (y(x^2 + y^2)^2 - x) \\ &= 4y x^3 + 4x y^3 - 1\end{aligned}$$

Since $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, then the ODE is not exact. By inspection $\frac{1}{x^2+y^2}$ is an integrating factor. Therefore by multiplying $M = y + x(x^2 + y^2)^2$ and $N = y(x^2 + y^2)^2 - x$ by this integrating factor the ode becomes exact. The new M, N are

$$M = \frac{y + x(x^2 + y^2)^2}{x^2 + y^2}$$

$$N = \frac{y(x^2 + y^2)^2 - x}{x^2 + y^2}$$

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\frac{\partial \phi}{\partial x} = M$$

$$\frac{\partial \phi}{\partial y} = N$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \tag{1A}$$

Therefore

$$\left(\frac{y(x^2 + y^2)^2 - x}{x^2 + y^2}\right) dy = \left(-\frac{y + (x^2 + y^2)^2 x}{x^2 + y^2}\right) dx$$

$$\left(\frac{y + (x^2 + y^2)^2 x}{x^2 + y^2}\right) dx + \left(\frac{y(x^2 + y^2)^2 - x}{x^2 + y^2}\right) dy = 0 \quad (2A)$$

Comparing (1A) and (2A) shows that

$$M(x, y) = \frac{y + (x^2 + y^2)^2 x}{x^2 + y^2}$$

$$N(x, y) = \frac{y(x^2 + y^2)^2 - x}{x^2 + y^2}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\frac{\partial M}{\partial y} = \frac{\partial}{\partial y} \left(\frac{y + (x^2 + y^2)^2 x}{x^2 + y^2} \right)$$

$$= \frac{2x^5 y + 4x^3 y^3 + 2y^5 x + x^2 - y^2}{(x^2 + y^2)^2}$$

And

$$\frac{\partial N}{\partial x} = \frac{\partial}{\partial x} \left(\frac{y(x^2 + y^2)^2 - x}{x^2 + y^2} \right)$$

$$= \frac{2x^5 y + 4x^3 y^3 + 2y^5 x + x^2 - y^2}{(x^2 + y^2)^2}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \quad (1)$$

$$\frac{\partial \phi}{\partial y} = N \quad (2)$$

Integrating (1) w.r.t. x gives

$$\int \frac{\partial \phi}{\partial x} dx = \int M dx$$

$$\int \frac{\partial \phi}{\partial x} dx = \int \frac{y + (x^2 + y^2)^2 x}{x^2 + y^2} dx$$

$$\phi = \frac{x^4}{4} + \frac{x^2 y^2}{2} + \arctan\left(\frac{x}{y}\right) + f(y) \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = x^2 y - \frac{x}{y^2 \left(\frac{x^2}{y^2} + 1\right)} + f'(y) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = \frac{y(x^2 + y^2)^2 - x}{x^2 + y^2}$. Therefore equation (4) becomes

$$\frac{y(x^2 + y^2)^2 - x}{x^2 + y^2} = \frac{x(y x^3 + x y^3 - 1)}{x^2 + y^2} + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = y^3$$

Integrating the above w.r.t y gives

$$\int f'(y) dy = \int (y^3) dy$$

$$f(y) = \frac{y^4}{4} + c_1$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = \frac{x^4}{4} + \frac{x^2 y^2}{2} + \arctan\left(\frac{x}{y}\right) + \frac{y^4}{4} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = \frac{x^4}{4} + \frac{x^2y^2}{2} + \arctan\left(\frac{x}{y}\right) + \frac{y^4}{4}$$

Summary

The solution(s) found are the following

$$\frac{x^4}{4} + \frac{x^2y^2}{2} + \arctan\left(\frac{x}{y}\right) + \frac{y^4}{4} = c_1 \quad (1)$$

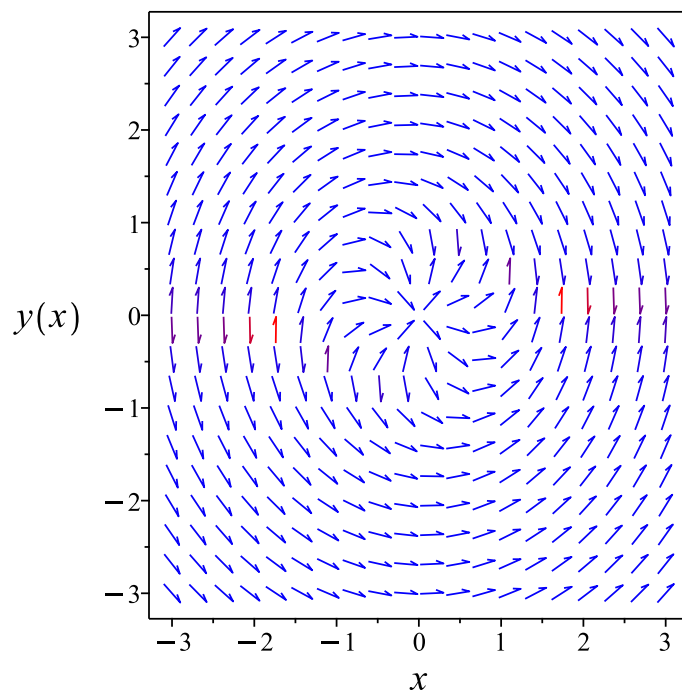


Figure 72: Slope field plot

Verification of solutions

$$\frac{x^4}{4} + \frac{x^2y^2}{2} + \arctan\left(\frac{x}{y}\right) + \frac{y^4}{4} = c_1$$

Verified OK.

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
trying Bernoulli  
trying separable  
trying inverse linear  
trying homogeneous types:  
trying Chini  
differential order: 1; looking for linear symmetries  
differential order: 1; found: 1 linear symmetries. Trying reduction of order  
1st order, trying the canonical coordinates of the invariance group  
<- 1st order, canonical coordinates successful`
```

✓ Solution by Maple

Time used: 0.156 (sec). Leaf size: 28

```
dsolve((y(x)+x*(x^2+y(x)^2)^2)+(y(x)*(x^2+y(x)^2)^2-x)*diff(y(x),x)=0,y(x), singsol=all)
```

$$y(x) = \cot \left(\text{RootOf} \left(4c_1 \sin(_Z)^4 - 4_Z \sin(_Z)^4 - x^4 \right) \right) x$$

✓ Solution by Mathematica

Time used: 0.144 (sec). Leaf size: 40

```
DSolve[(y[x]+x*(x^2+y[x]^2)^2)+(y[x]*(x^2+y[x]^2)^2-x)*y'[x]==0,y[x],x,IncludeSingularSoluti
```

$$\text{Solve} \left[\arctan \left(\frac{x}{y(x)} \right) + \frac{x^4}{4} + \frac{1}{2} x^2 y(x)^2 + \frac{y(x)^4}{4} = c_1, y(x) \right]$$

4 Chapter 2, section 2.2 (Separable equations).

Exercises page 47

4.1	problem 1	449
4.2	problem 2	464
4.3	problem 3	478
4.4	problem 4	492
4.5	problem 5	504
4.6	problem 6	515
4.7	problem 7	527
4.8	problem 8	544
4.9	problem 9	558
4.10	problem 10	572
4.11	problem 11	581
4.12	problem 12	592
4.13	problem 13	608
4.14	problem 14	622
4.15	problem 15	631
4.16	problem 16	645
4.17	problem 17	658
4.18	problem 18	676
4.19	problem 19	693
4.20	problem 20	702
4.21	problem 22(a)	715
4.22	problem 22(b)	731
4.23	problem 23(a)	747
4.24	problem 23(b)	763

4.1 problem 1

4.1.1	Solving as separable ode	449
4.1.2	Solving as linear ode	451
4.1.3	Solving as homogeneousTypeD2 ode	452
4.1.4	Solving as first order ode lie symmetry lookup ode	454
4.1.5	Solving as exact ode	458
4.1.6	Maple step by step solution	462

Internal problem ID [11614]

Internal file name [OUTPUT/10596_Saturday_May_27_2023_03_01_06_AM_105870/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.2 (Separable equations). Exercises page 47

Problem number: 1.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact", "linear", "separable", "homogeneousTypeD2", "first_order_ode_lie_symmetry_lookup"

Maple gives the following as the ode type

[_separable]

$$4yx + (x^2 + 1)y' = 0$$

4.1.1 Solving as separable ode

In canonical form the ODE is

$$\begin{aligned}y' &= F(x, y) \\ &= f(x)g(y) \\ &= -\frac{4xy}{x^2 + 1}\end{aligned}$$

Where $f(x) = -\frac{4x}{x^2+1}$ and $g(y) = y$. Integrating both sides gives

$$\begin{aligned}\frac{1}{y} dy &= -\frac{4x}{x^2+1} dx \\ \int \frac{1}{y} dy &= \int -\frac{4x}{x^2+1} dx \\ \ln(y) &= -2 \ln(x^2+1) + c_1 \\ y &= e^{-2 \ln(x^2+1) + c_1} \\ &= \frac{c_1}{(x^2+1)^2}\end{aligned}$$

Summary

The solution(s) found are the following

$$y = \frac{c_1}{(x^2+1)^2} \tag{1}$$

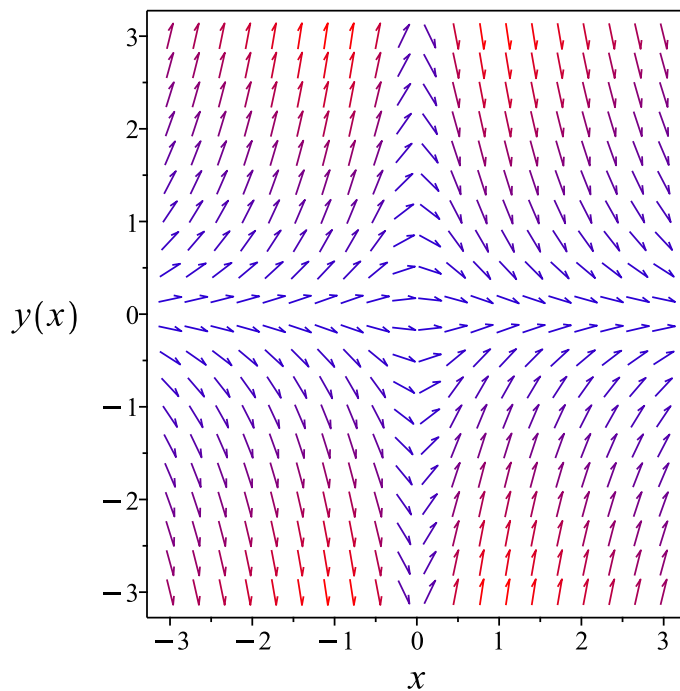


Figure 73: Slope field plot

Verification of solutions

$$y = \frac{c_1}{(x^2+1)^2}$$

Verified OK.

4.1.2 Solving as linear ode

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = \frac{4x}{x^2 + 1}$$
$$q(x) = 0$$

Hence the ode is

$$y' + \frac{4xy}{x^2 + 1} = 0$$

The integrating factor μ is

$$\mu = e^{\int \frac{4x}{x^2+1} dx}$$
$$= (x^2 + 1)^2$$

The ode becomes

$$\frac{d}{dx} \mu y = 0$$
$$\frac{d}{dx} \left((x^2 + 1)^2 y \right) = 0$$

Integrating gives

$$(x^2 + 1)^2 y = c_1$$

Dividing both sides by the integrating factor $\mu = (x^2 + 1)^2$ results in

$$y = \frac{c_1}{(x^2 + 1)^2}$$

Summary

The solution(s) found are the following

$$y = \frac{c_1}{(x^2 + 1)^2} \tag{1}$$

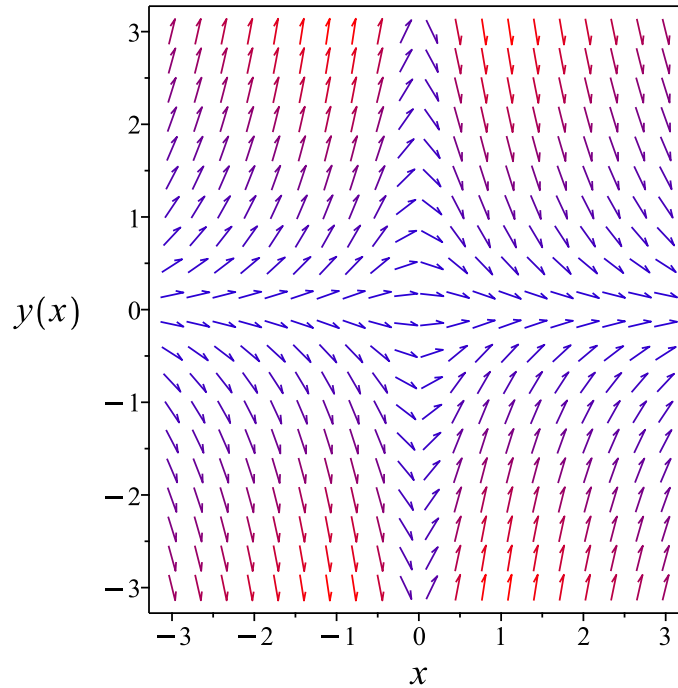


Figure 74: Slope field plot

Verification of solutions

$$y = \frac{c_1}{(x^2 + 1)^2}$$

Verified OK.

4.1.3 Solving as homogeneousTypeD2 ode

Using the change of variables $y = u(x)x$ on the above ode results in new ode in $u(x)$

$$4u(x)x^2 + (x^2 + 1)(u'(x)x + u(x)) = 0$$

In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= -\frac{u(5x^2 + 1)}{x(x^2 + 1)} \end{aligned}$$

Where $f(x) = -\frac{5x^2+1}{x(x^2+1)}$ and $g(u) = u$. Integrating both sides gives

$$\begin{aligned}\frac{1}{u} du &= -\frac{5x^2+1}{x(x^2+1)} dx \\ \int \frac{1}{u} du &= \int -\frac{5x^2+1}{x(x^2+1)} dx \\ \ln(u) &= -\ln(x) - 2\ln(x^2+1) + c_2 \\ u &= e^{-\ln(x)-2\ln(x^2+1)+c_2} \\ &= c_2 e^{-\ln(x)-2\ln(x^2+1)}\end{aligned}$$

Which simplifies to

$$u(x) = \frac{c_2}{x(x^2+1)^2}$$

Therefore the solution y is

$$\begin{aligned}y &= ux \\ &= \frac{c_2}{(x^2+1)^2}\end{aligned}$$

Summary

The solution(s) found are the following

$$y = \frac{c_2}{(x^2+1)^2} \tag{1}$$

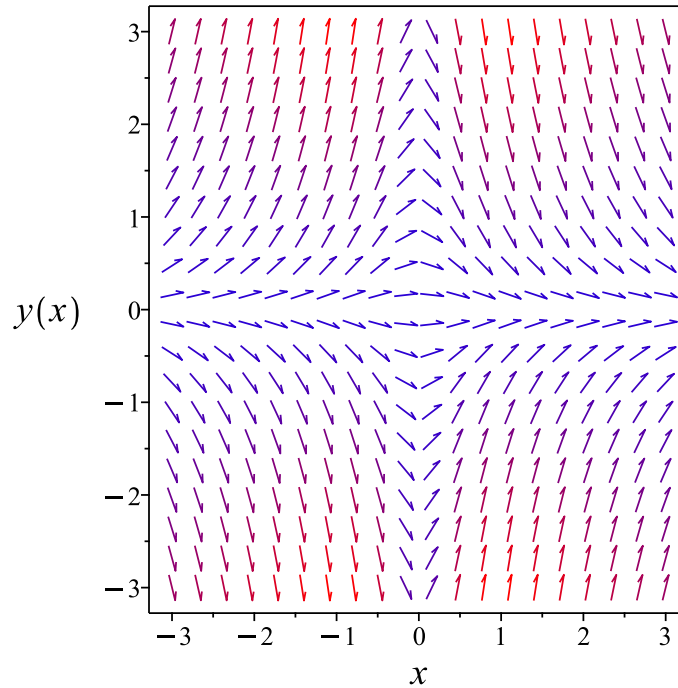


Figure 75: Slope field plot

Verification of solutions

$$y = \frac{c_2}{(x^2 + 1)^2}$$

Verified OK.

4.1.4 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = -\frac{4xy}{x^2 + 1}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 70: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned} \xi(x, y) &= 0 \\ \eta(x, y) &= \frac{1}{(x^2 + 1)^2} \end{aligned} \tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{1}{(x^2+1)^2}} dy \end{aligned}$$

Which results in

$$S = (x^2 + 1)^2 y$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{4xy}{x^2 + 1}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= 4(x^2 + 1)yx \\ S_y &= (x^2 + 1)^2 \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 0 \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 0$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = c_1 \tag{4}$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$(x^2 + 1)^2 y = c_1$$

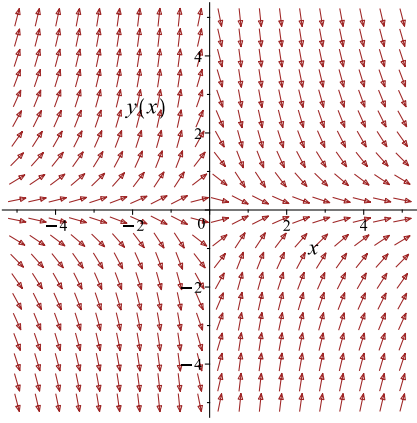
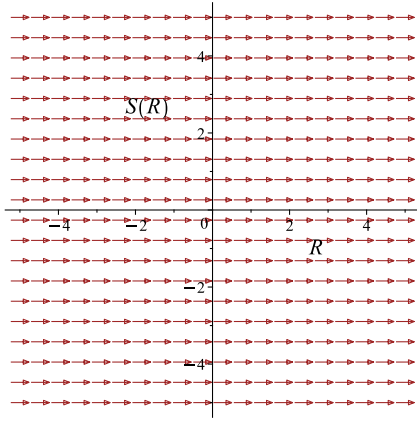
Which simplifies to

$$(x^2 + 1)^2 y = c_1$$

Which gives

$$y = \frac{c_1}{(x^2 + 1)^2}$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{4xy}{x^2+1}$ 	$R = x$ $S = (x^2 + 1)^2 y$	$\frac{dS}{dR} = 0$ 

Summary

The solution(s) found are the following

$$y = \frac{c_1}{(x^2 + 1)^2} \tag{1}$$

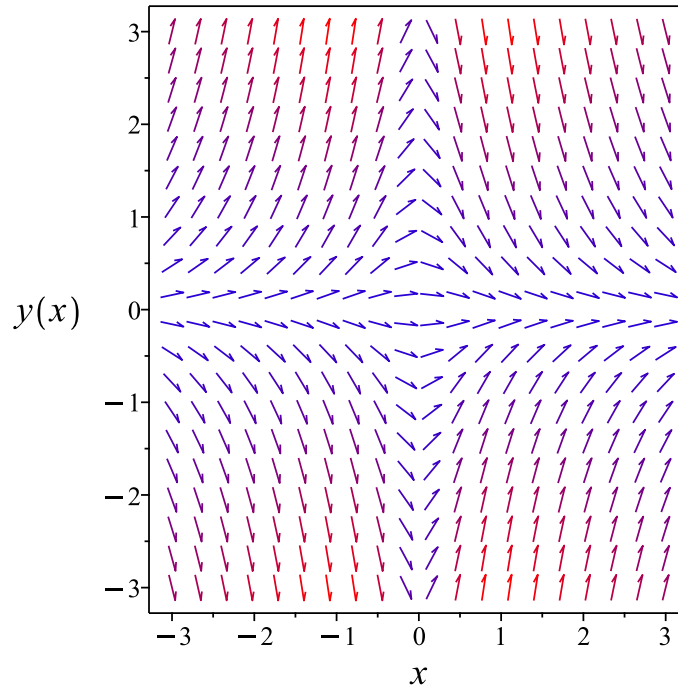


Figure 76: Slope field plot

Verification of solutions

$$y = \frac{c_1}{(x^2 + 1)^2}$$

Verified OK.

4.1.5 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \tag{1A}$$

Therefore

$$\begin{aligned}\left(-\frac{1}{4y}\right) dy &= \left(\frac{x}{x^2 + 1}\right) dx \\ \left(-\frac{x}{x^2 + 1}\right) dx + \left(-\frac{1}{4y}\right) dy &= 0\end{aligned} \tag{2A}$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= -\frac{x}{x^2 + 1} \\ N(x, y) &= -\frac{1}{4y}\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y} \left(-\frac{x}{x^2 + 1}\right) \\ &= 0\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x} \left(-\frac{1}{4y} \right) \\ &= 0\end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \quad (1)$$

$$\frac{\partial \phi}{\partial y} = N \quad (2)$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int M dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int -\frac{x}{x^2 + 1} dx \\ \phi &= -\frac{\ln(x^2 + 1)}{2} + f(y)\end{aligned} \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = 0 + f'(y) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = -\frac{1}{4y}$. Therefore equation (4) becomes

$$-\frac{1}{4y} = 0 + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = -\frac{1}{4y}$$

Integrating the above w.r.t y gives

$$\int f'(y) dy = \int \left(-\frac{1}{4y}\right) dy$$
$$f(y) = -\frac{\ln(y)}{4} + c_1$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = -\frac{\ln(x^2 + 1)}{2} - \frac{\ln(y)}{4} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -\frac{\ln(x^2 + 1)}{2} - \frac{\ln(y)}{4}$$

The solution becomes

$$y = \frac{e^{-4c_1}}{(x^2 + 1)^2}$$

Summary

The solution(s) found are the following

$$y = \frac{e^{-4c_1}}{(x^2 + 1)^2} \quad (1)$$

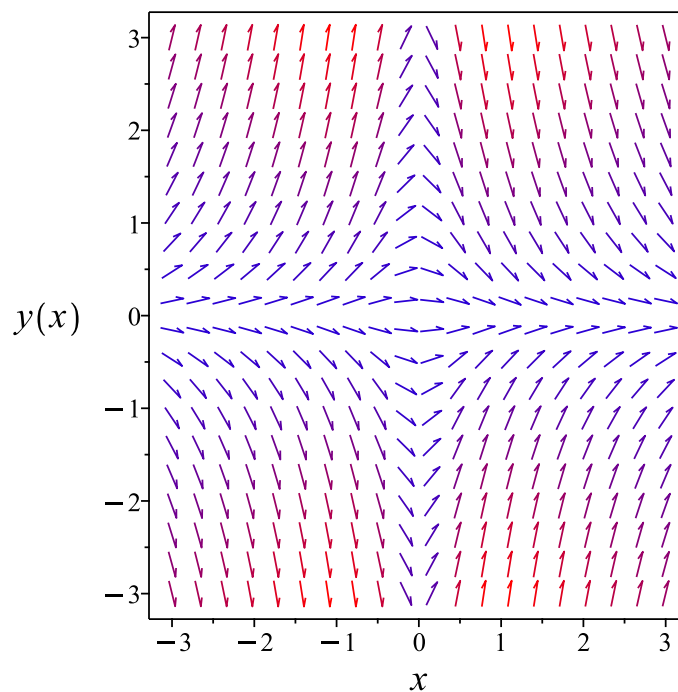


Figure 77: Slope field plot

Verification of solutions

$$y = \frac{e^{-4c_1}}{(x^2 + 1)^2}$$

Verified OK.

4.1.6 Maple step by step solution

Let's solve

$$4yx + (x^2 + 1)y' = 0$$

- Highest derivative means the order of the ODE is 1

$$y'$$

- Separate variables

$$\frac{y'}{y} = -\frac{4x}{x^2+1}$$

- Integrate both sides with respect to x

$$\int \frac{y'}{y} dx = \int -\frac{4x}{x^2+1} dx + c_1$$

- Evaluate integral

$$\ln(y) = -2\ln(x^2 + 1) + c_1$$

- Solve for y

$$y = \frac{e^{c_1}}{(x^2+1)^2}$$

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
<- 1st order linear successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 13

```
dsolve((4*x*y(x))+(x^2+1)*diff(y(x),x)=0,y(x), singsol=all)
```

$$y(x) = \frac{c_1}{(x^2 + 1)^2}$$

✓ Solution by Mathematica

Time used: 0.047 (sec). Leaf size: 20

```
DSolve[(4*x*y[x])+(x^2+1)*y'[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{c_1}{(x^2 + 1)^2}$$
$$y(x) \rightarrow 0$$

4.2 problem 2

4.2.1	Solving as separable ode	464
4.2.2	Solving as linear ode	466
4.2.3	Solving as first order ode lie symmetry lookup ode	468
4.2.4	Solving as exact ode	472
4.2.5	Maple step by step solution	476

Internal problem ID [11615]

Internal file name [OUTPUT/10597_Saturday_May_27_2023_03_01_08_AM_25265056/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.2 (Separable equations). Exercises page 47

Problem number: 2.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact", "linear", "separable", "first_order_ode_lie_symmetry_lookup"

Maple gives the following as the ode type

[_separable]

$$yx + y + (x^2 + 2x)y' = -2x - 2$$

4.2.1 Solving as separable ode

In canonical form the ODE is

$$\begin{aligned}y' &= F(x, y) \\ &= f(x)g(y) \\ &= \frac{(1+x)(-y-2)}{x(x+2)}\end{aligned}$$

Where $f(x) = \frac{1+x}{x(x+2)}$ and $g(y) = -y - 2$. Integrating both sides gives

$$\frac{1}{-y-2} dy = \frac{1+x}{x(x+2)} dx$$

$$\int \frac{1}{-y-2} dy = \int \frac{1+x}{x(x+2)} dx$$

$$-\ln(y+2) = \frac{\ln(x(x+2))}{2} + c_1$$

Raising both side to exponential gives

$$\frac{1}{y+2} = e^{\frac{\ln(x(x+2))}{2} + c_1}$$

Which simplifies to

$$\frac{1}{y+2} = c_2 \sqrt{x(x+2)}$$

Which simplifies to

$$y = -\frac{(2c_2 e^{c_1} \sqrt{x^2 + 2x} - 1) e^{-c_1}}{c_2 \sqrt{x^2 + 2x}}$$

Summary

The solution(s) found are the following

$$y = -\frac{(2c_2 e^{c_1} \sqrt{x^2 + 2x} - 1) e^{-c_1}}{c_2 \sqrt{x^2 + 2x}} \quad (1)$$

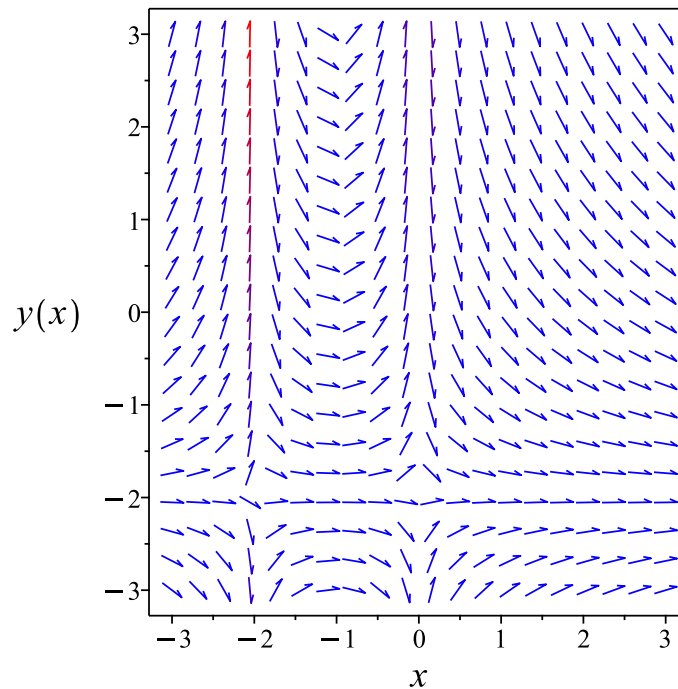


Figure 78: Slope field plot

Verification of solutions

$$y = -\frac{(2c_2 e^{c_1} \sqrt{x^2 + 2x} - 1) e^{-c_1}}{c_2 \sqrt{x^2 + 2x}}$$

Verified OK.

4.2.2 Solving as linear ode

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = -\frac{-x-1}{x(x+2)}$$
$$q(x) = \frac{-2x-2}{x(x+2)}$$

Hence the ode is

$$y' - \frac{(-x-1)y}{x(x+2)} = \frac{-2x-2}{x(x+2)}$$

The integrating factor μ is

$$\mu = e^{\int -\frac{-x-1}{x(x+2)} dx}$$
$$= \sqrt{x(x+2)}$$

The ode becomes

$$\frac{d}{dx}(\mu y) = (\mu) \left(\frac{-2x-2}{x(x+2)} \right)$$
$$\frac{d}{dx}(\sqrt{x(x+2)} y) = (\sqrt{x(x+2)}) \left(\frac{-2x-2}{x(x+2)} \right)$$
$$d(\sqrt{x(x+2)} y) = \left(-\frac{2(1+x)\sqrt{x(x+2)}}{x(x+2)} \right) dx$$

Integrating gives

$$\sqrt{x(x+2)} y = \int -\frac{2(1+x)\sqrt{x(x+2)}}{x(x+2)} dx$$
$$\sqrt{x(x+2)} y = -2\sqrt{x(x+2)} + c_1$$

Dividing both sides by the integrating factor $\mu = \sqrt{x(x+2)}$ results in

$$y = -2 + \frac{c_1}{\sqrt{x(x+2)}}$$

Summary

The solution(s) found are the following

$$y = -2 + \frac{c_1}{\sqrt{x(x+2)}} \tag{1}$$

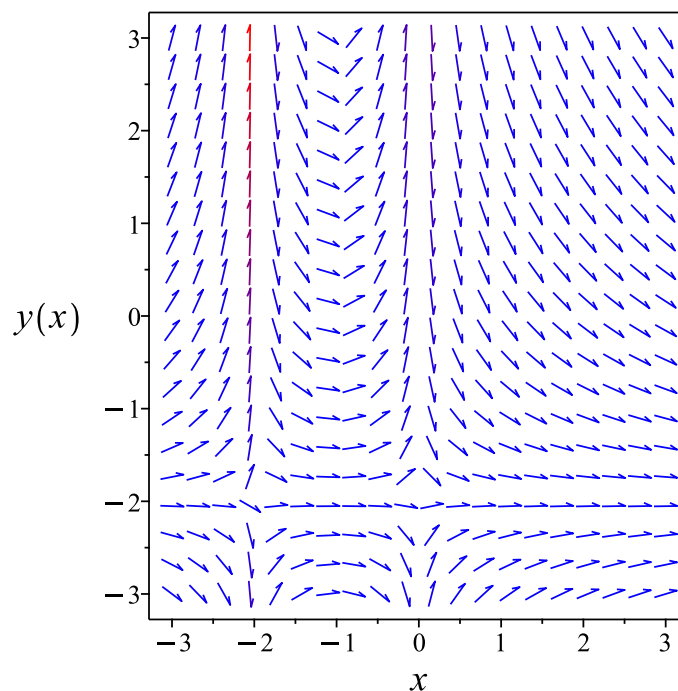


Figure 79: Slope field plot

Verification of solutions

$$y = -2 + \frac{c_1}{\sqrt{x(x+2)}}$$

Verified OK.

4.2.3 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = -\frac{xy + 2x + y + 2}{x(x + 2)}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 73: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= \frac{1}{\sqrt{x(x+2)}}\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned}S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{1}{\sqrt{x(x+2)}}} dy\end{aligned}$$

Which results in

$$S = \sqrt{x(x+2)} y$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y}\tag{2}$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{xy + 2x + y + 2}{x(x+2)}$$

Evaluating all the partial derivatives gives

$$\begin{aligned}R_x &= 1 \\R_y &= 0 \\S_x &= \frac{y(1+x)}{\sqrt{x}\sqrt{x+2}} \\S_y &= \sqrt{x}\sqrt{x+2}\end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = -\frac{2(1+x)}{\sqrt{x}\sqrt{x+2}} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = -\frac{2(1+R)}{\sqrt{R}\sqrt{R+2}}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = -2\sqrt{R}\sqrt{R+2} + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$\sqrt{x}\sqrt{x+2}y = -2\sqrt{x}\sqrt{x+2} + c_1$$

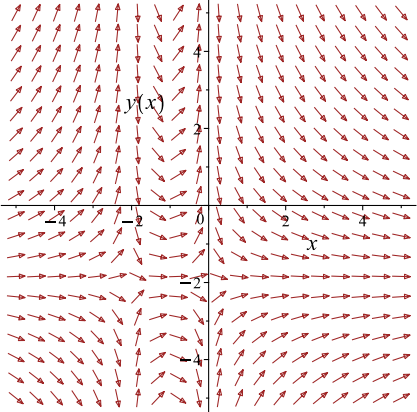
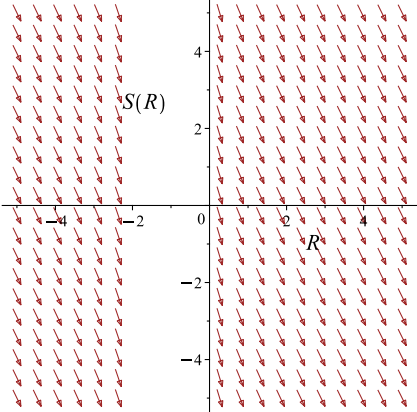
Which simplifies to

$$(y+2)\sqrt{x}\sqrt{x+2} - c_1 = 0$$

Which gives

$$y = -\frac{2\sqrt{x}\sqrt{x+2} - c_1}{\sqrt{x}\sqrt{x+2}}$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{xy+2x+y+2}{x(x+2)}$ 	$R = x$ $S = \sqrt{x} \sqrt{x+2} y$	$\frac{dS}{dR} = -\frac{2(1+R)}{\sqrt{R}\sqrt{R+2}}$ 

Summary

The solution(s) found are the following

$$y = -\frac{2\sqrt{x}\sqrt{x+2} - c_1}{\sqrt{x}\sqrt{x+2}} \quad (1)$$

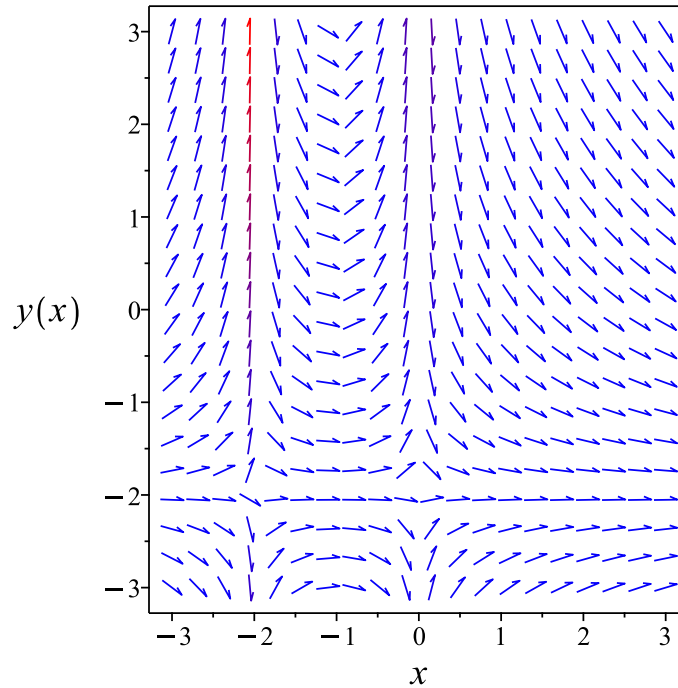


Figure 80: Slope field plot

Verification of solutions

$$y = -\frac{2\sqrt{x}\sqrt{x+2} - c_1}{\sqrt{x}\sqrt{x+2}}$$

Verified OK.

4.2.4 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx}\phi(x, y) = 0$$

Hence

$$\frac{\partial\phi}{\partial x} + \frac{\partial\phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (1A)$$

Therefore

$$\begin{aligned}\left(\frac{1}{-y-2}\right) dy &= \left(\frac{1+x}{x(x+2)}\right) dx \\ \left(-\frac{1+x}{x(x+2)}\right) dx + \left(\frac{1}{-y-2}\right) dy &= 0\end{aligned} \quad (2A)$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= -\frac{1+x}{x(x+2)} \\ N(x, y) &= \frac{1}{-y-2}\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y} \left(-\frac{1+x}{x(x+2)}\right) \\ &= 0\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x} \left(\frac{1}{-y-2} \right) \\ &= 0\end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \quad (1)$$

$$\frac{\partial \phi}{\partial y} = N \quad (2)$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int M dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int -\frac{1+x}{x(x+2)} dx \\ \phi &= -\frac{\ln(x(x+2))}{2} + f(y)\end{aligned} \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = 0 + f'(y) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = \frac{1}{-y-2}$. Therefore equation (4) becomes

$$\frac{1}{-y-2} = 0 + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = -\frac{1}{y+2}$$

Integrating the above w.r.t y gives

$$\begin{aligned}\int f'(y) dy &= \int \left(-\frac{1}{y+2} \right) dy \\ f(y) &= -\ln(y+2) + c_1\end{aligned}$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = -\frac{\ln(x(x+2))}{2} - \ln(y+2) + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -\frac{\ln(x(x+2))}{2} - \ln(y+2)$$

The solution becomes

$$y = e^{-\frac{\ln(x(x+2))}{2} - c_1} - 2$$

Summary

The solution(s) found are the following

$$y = e^{-\frac{\ln(x(x+2))}{2} - c_1} - 2 \tag{1}$$

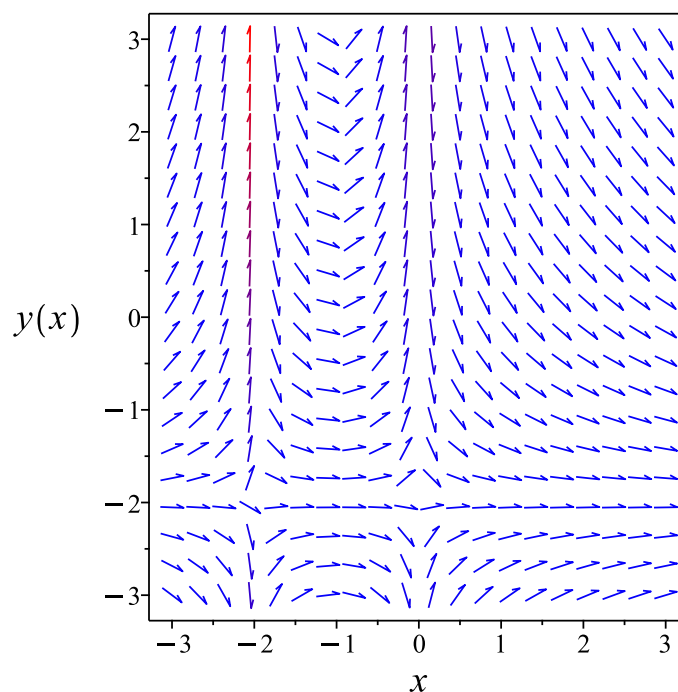


Figure 81: Slope field plot

Verification of solutions

$$y = e^{-\frac{\ln(x(x+2))}{2} - c_1} - 2$$

Verified OK.

4.2.5 Maple step by step solution

Let's solve

$$yx + y + (x^2 + 2x)y' = -2x - 2$$

- Highest derivative means the order of the ODE is 1

y'

- Separate variables

$$\frac{y'}{y+2} = -\frac{1+x}{x(x+2)}$$

- Integrate both sides with respect to x

$$\int \frac{y'}{y+2} dx = \int -\frac{1+x}{x(x+2)} dx + c_1$$

- Evaluate integral

$$\ln(y+2) = -\frac{\ln(x(x+2))}{2} + c_1$$

- Solve for y

$$y = e^{-\frac{\ln(x(x+2))}{2} + c_1} - 2$$

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
<- 1st order linear successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 15

```
dsolve((x*y(x)+2*x+y(x)+2)+(x^2+2*x)*diff(y(x),x)=0,y(x), singsol=all)
```

$$y(x) = -2 + \frac{c_1}{\sqrt{x(x+2)}}$$

✓ Solution by Mathematica

Time used: 0.149 (sec). Leaf size: 27

```
DSolve[(x*y[x]+2*x+y[x]+2)+(x^2+2*x)*y'[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow -2 + \frac{c_1}{\sqrt{x}\sqrt{x+2}}$$

$$y(x) \rightarrow -2$$

4.3 problem 3

4.3.1	Solving as separable ode	478
4.3.2	Solving as first order ode lie symmetry lookup ode	480
4.3.3	Solving as exact ode	484
4.3.4	Solving as riccati ode	488
4.3.5	Maple step by step solution	490

Internal problem ID [11616]

Internal file name [OUTPUT/10598_Saturday_May_27_2023_03_01_10_AM_98812696/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 2, section 2.2 (Separable equations). Exercises page 47

Problem number: 3.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact", "riccati", "separable", "first_order_ode_lie_symmetry_lookup"

Maple gives the following as the ode type

[_separable]

$$2r(s^2 + 1) + (r^4 + 1) s' = 0$$

4.3.1 Solving as separable ode

In canonical form the ODE is

$$\begin{aligned} s' &= F(r, s) \\ &= f(r)g(s) \\ &= \frac{r(-2s^2 - 2)}{r^4 + 1} \end{aligned}$$

Where $f(r) = \frac{r}{r^4+1}$ and $g(s) = -2s^2 - 2$. Integrating both sides gives

$$\begin{aligned} \frac{1}{-2s^2 - 2} ds &= \frac{r}{r^4 + 1} dr \\ \int \frac{1}{-2s^2 - 2} ds &= \int \frac{r}{r^4 + 1} dr \end{aligned}$$

$$-\frac{\arctan(s)}{2} = \frac{\arctan(r^2)}{2} + c_1$$

Which results in

$$s = -\tan(\arctan(r^2) + 2c_1)$$

Summary

The solution(s) found are the following

$$s = -\tan(\arctan(r^2) + 2c_1) \tag{1}$$

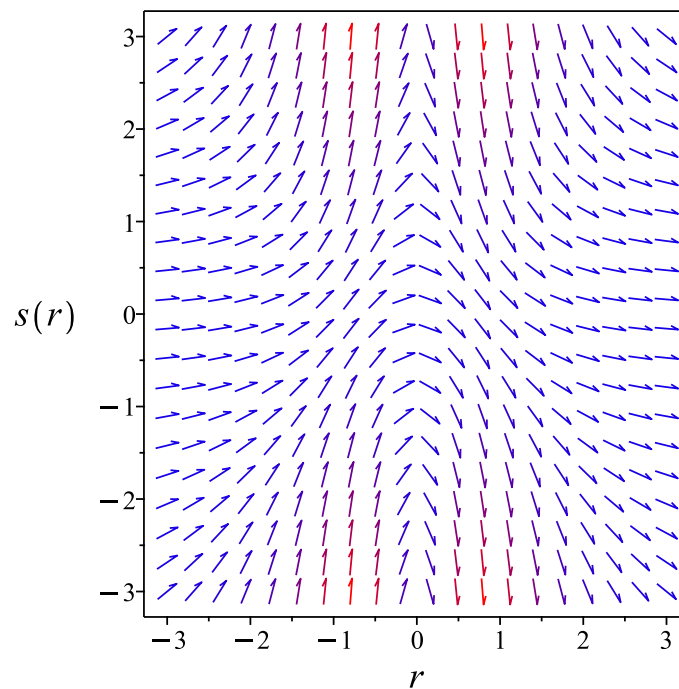


Figure 82: Slope field plot

Verification of solutions

$$s = -\tan(\arctan(r^2) + 2c_1)$$

Verified OK.

4.3.2 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$s' = -\frac{2r(s^2 + 1)}{r^4 + 1}$$

$$s' = \omega(r, s)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_r + \omega(\eta_s - \xi_r) - \omega^2 \xi_s - \omega_r \xi - \omega_s \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **separable**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 76: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(r, s) &= \frac{r^4 + 1}{r} \\ \eta(r, s) &= 0\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(r, s) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dr}{\xi} = \frac{ds}{\eta} = dS\tag{1}$$

The above comes from the requirements that $(\xi \frac{\partial}{\partial r} + \eta \frac{\partial}{\partial s}) S(r, s) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\eta = 0$ then in this special case

$$R = s$$

S is found from

$$\begin{aligned}S &= \int \frac{1}{\xi} dr \\ &= \int \frac{1}{\frac{r^4+1}{r}} dr\end{aligned}$$

Which results in

$$S = \frac{\arctan(r^2)}{2}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_r + \omega(r, s)S_s}{R_r + \omega(r, s)R_s}\tag{2}$$

Where in the above R_r, R_s, S_r, S_s are all partial derivatives and $\omega(r, s)$ is the right hand side of the original ode given by

$$\omega(r, s) = -\frac{2r(s^2 + 1)}{r^4 + 1}$$

Evaluating all the partial derivatives gives

$$\begin{aligned}R_r &= 0 \\R_s &= 1 \\S_r &= \frac{r}{r^4 + 1} \\S_s &= 0\end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = -\frac{1}{2s^2 + 2} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for r, s in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = -\frac{1}{2R^2 + 2}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = -\frac{\arctan(R)}{2} + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to r, s coordinates. This results in

$$\frac{\arctan(r^2)}{2} = -\frac{\arctan(s)}{2} + c_1$$

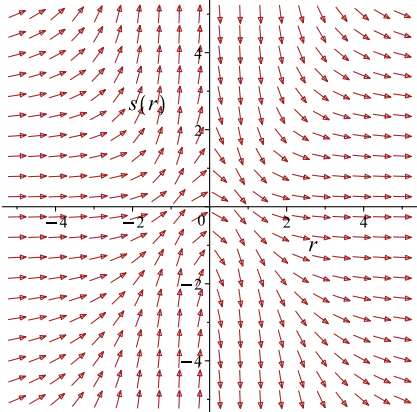
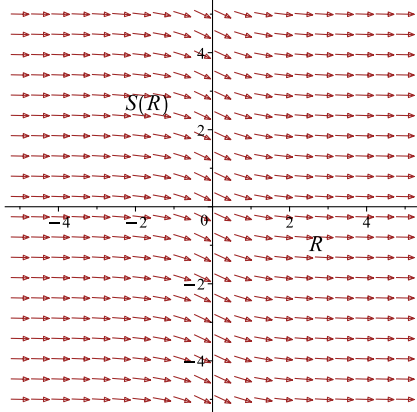
Which simplifies to

$$\frac{\arctan(r^2)}{2} = -\frac{\arctan(s)}{2} + c_1$$

Which gives

$$s = \tan(-\arctan(r^2) + 2c_1)$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in r, s coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{ds}{dr} = -\frac{2r(s^2+1)}{r^4+1}$ 	$R = s$ $S = \frac{\arctan(r^2)}{2}$	$\frac{dS}{dR} = -\frac{1}{2R^2+2}$ 

Summary

The solution(s) found are the following

$$s = \tan(-\arctan(r^2) + 2c_1) \tag{1}$$

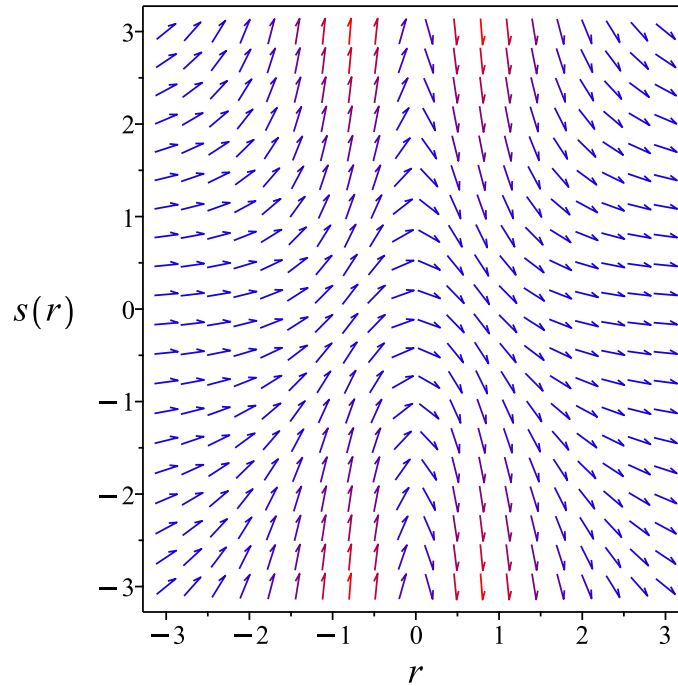


Figure 83: Slope field plot

Verification of solutions

$$s = \tan(-\arctan(r^2) + 2c_1)$$

Verified OK.

4.3.3 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(r, s) dr + N(r, s) ds = 0 \quad (1A)$$

Therefore

$$\begin{aligned}\left(\frac{1}{-2s^2 - 2}\right) ds &= \left(\frac{r}{r^4 + 1}\right) dr \\ \left(-\frac{r}{r^4 + 1}\right) dr + \left(\frac{1}{-2s^2 - 2}\right) ds &= 0\end{aligned} \quad (2A)$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(r, s) &= -\frac{r}{r^4 + 1} \\ N(r, s) &= \frac{1}{-2s^2 - 2}\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial s} = \frac{\partial N}{\partial r}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial s} &= \frac{\partial}{\partial s} \left(-\frac{r}{r^4 + 1}\right) \\ &= 0\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial r} &= \frac{\partial}{\partial r} \left(\frac{1}{-2s^2 - 2} \right) \\ &= 0\end{aligned}$$

Since $\frac{\partial M}{\partial s} = \frac{\partial N}{\partial r}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(r, s)$

$$\frac{\partial \phi}{\partial r} = M \quad (1)$$

$$\frac{\partial \phi}{\partial s} = N \quad (2)$$

Integrating (1) w.r.t. r gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial r} dr &= \int M dr \\ \int \frac{\partial \phi}{\partial r} dr &= \int -\frac{r}{r^4 + 1} dr \\ \phi &= -\frac{\arctan(r^2)}{2} + f(s)\end{aligned} \quad (3)$$

Where $f(s)$ is used for the constant of integration since ϕ is a function of both r and s . Taking derivative of equation (3) w.r.t s gives

$$\frac{\partial \phi}{\partial s} = 0 + f'(s) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial s} = \frac{1}{-2s^2 - 2}$. Therefore equation (4) becomes

$$\frac{1}{-2s^2 - 2} = 0 + f'(s) \quad (5)$$

Solving equation (5) for $f'(s)$ gives

$$f'(s) = -\frac{1}{2(s^2 + 1)}$$

Integrating the above w.r.t s gives

$$\begin{aligned}\int f'(s) ds &= \int \left(-\frac{1}{2s^2 + 2} \right) ds \\ f(s) &= -\frac{\arctan(s)}{2} + c_1\end{aligned}$$

Where c_1 is constant of integration. Substituting result found above for $f(s)$ into equation (3) gives ϕ

$$\phi = -\frac{\arctan(r^2)}{2} - \frac{\arctan(s)}{2} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -\frac{\arctan(r^2)}{2} - \frac{\arctan(s)}{2}$$

Summary

The solution(s) found are the following

$$-\frac{\arctan(r^2)}{2} - \frac{\arctan(s)}{2} = c_1 \tag{1}$$

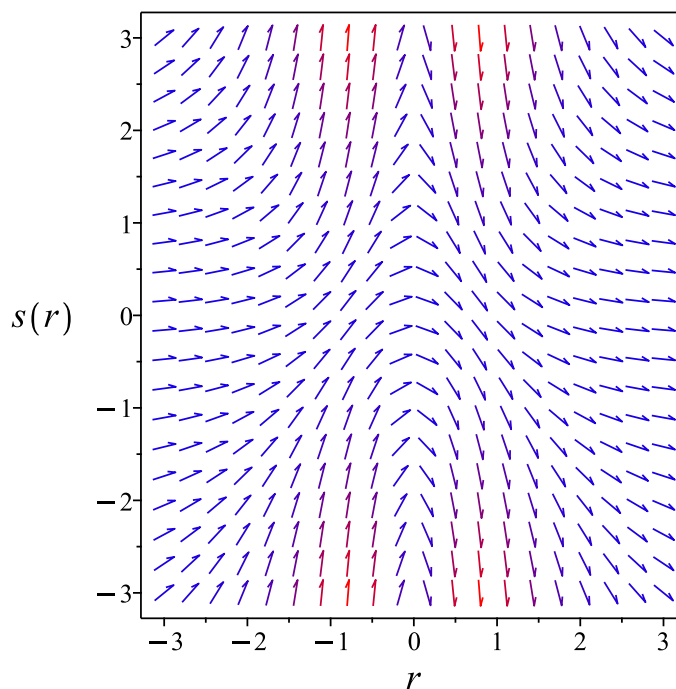


Figure 84: Slope field plot

Verification of solutions

$$-\frac{\arctan(r^2)}{2} - \frac{\arctan(s)}{2} = c_1$$

Verified OK.

4.3.4 Solving as riccati ode

In canonical form the ODE is

$$\begin{aligned} s' &= F(r, s) \\ &= -\frac{2r(s^2 + 1)}{r^4 + 1} \end{aligned}$$

This is a Riccati ODE. Comparing the ODE to solve

$$s' = -\frac{2r s^2}{r^4 + 1} - \frac{2r}{r^4 + 1}$$

With Riccati ODE standard form

$$s' = f_0(r) + f_1(r)s + f_2(r)s^2$$

Shows that $f_0(r) = -\frac{2r}{r^4+1}$, $f_1(r) = 0$ and $f_2(r) = -\frac{2r}{r^4+1}$. Let

$$\begin{aligned} s &= \frac{-u'}{f_2 u} \\ &= \frac{-u'}{-\frac{2ru}{r^4+1}} \end{aligned} \tag{1}$$

Using the above substitution in the given ODE results (after some simplification) in a second order ODE to solve for $u(x)$ which is

$$f_2 u''(r) - (f_2' + f_1 f_2) u'(r) + f_2^2 f_0 u(r) = 0 \tag{2}$$

But

$$\begin{aligned} f_2' &= -\frac{2}{r^4 + 1} + \frac{8r^4}{(r^4 + 1)^2} \\ f_1 f_2 &= 0 \\ f_2^2 f_0 &= -\frac{8r^3}{(r^4 + 1)^3} \end{aligned}$$

Substituting the above terms back in equation (2) gives

$$-\frac{2ru''(r)}{r^4 + 1} - \left(-\frac{2}{r^4 + 1} + \frac{8r^4}{(r^4 + 1)^2} \right) u'(r) - \frac{8r^3 u(r)}{(r^4 + 1)^3} = 0$$

Solving the above ODE (this ode solved using Maple, not this program), gives

$$u(r) = \frac{c_1 r^2 + c_2}{\sqrt{r^4 + 1}}$$

The above shows that

$$u'(r) = \frac{2r(-c_2r^2 + c_1)}{(r^4 + 1)^{\frac{3}{2}}}$$

Using the above in (1) gives the solution

$$s = \frac{-c_2r^2 + c_1}{c_1r^2 + c_2}$$

Dividing both numerator and denominator by c_1 gives, after renaming the constant $\frac{c_2}{c_1} = c_3$ the following solution

$$s = \frac{-r^2 + c_3}{c_3r^2 + 1}$$

Summary

The solution(s) found are the following

$$s = \frac{-r^2 + c_3}{c_3r^2 + 1} \tag{1}$$

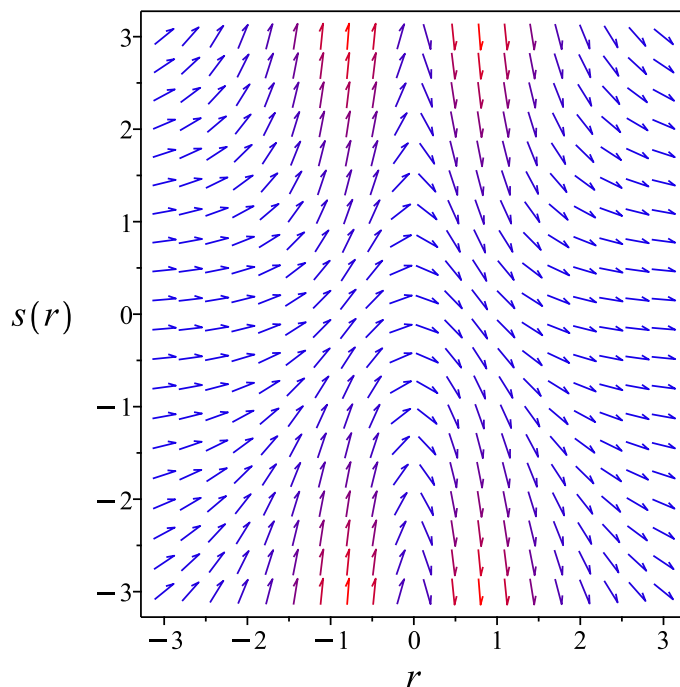


Figure 85: Slope field plot

Verification of solutions

$$s = \frac{-r^2 + c_3}{c_3 r^2 + 1}$$

Verified OK.

4.3.5 Maple step by step solution

Let's solve

$$2r(s^2 + 1) + (r^4 + 1)s' = 0$$

- Highest derivative means the order of the ODE is 1

s'

- Separate variables

$$\frac{s'}{s^2+1} = -\frac{2r}{r^4+1}$$

- Integrate both sides with respect to r

$$\int \frac{s'}{s^2+1} dr = \int -\frac{2r}{r^4+1} dr + c_1$$

- Evaluate integral

$$\arctan(s) = -\arctan(r^2) + c_1$$

- Solve for s

$$s = \tan(-\arctan(r^2) + c_1)$$

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
trying Bernoulli  
trying separable  
<- separable successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 15

```
dsolve(2*r*(s(r)^2+1)+(r^4+1)*diff(s(r),r)=0,s(r), singsol=all)
```

$$s(r) = -\tan(\arctan(r^2) + 2c_1)$$

✓ Solution by Mathematica

Time used: 0.478 (sec). Leaf size: 31

```
DSolve[2*r*(s[r]^2+1)+(r^4+1)*s'[r]==0,s[r],r,IncludeSingularSolutions -> True]
```

$$s(r) \rightarrow -\tan(\arctan(r^2) - c_1)$$

$$s(r) \rightarrow -i$$

$$s(r) \rightarrow i$$

4.4 problem 4

4.4.1	Solving as separable ode	492
4.4.2	Solving as first order ode lie symmetry lookup ode	494
4.4.3	Solving as exact ode	498
4.4.4	Maple step by step solution	502

Internal problem ID [11617]

Internal file name [OUTPUT/10599_Saturday_May_27_2023_03_01_11_AM_17840397/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.2 (Separable equations). Exercises page 47

Problem number: 4.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"exact", "separable", "first_order_ode_lie_symmetry_lookup"**

Maple gives the following as the ode type

`[_separable]`

$$\text{csc}(y) + y' \sec(x) = 0$$

4.4.1 Solving as separable ode

In canonical form the ODE is

$$\begin{aligned} y' &= F(x, y) \\ &= f(x)g(y) \\ &= -\frac{\text{csc}(y)}{\sec(x)} \end{aligned}$$

Where $f(x) = -\frac{1}{\sec(x)}$ and $g(y) = \text{csc}(y)$. Integrating both sides gives

$$\begin{aligned} \frac{1}{\text{csc}(y)} dy &= -\frac{1}{\sec(x)} dx \\ \int \frac{1}{\text{csc}(y)} dy &= \int -\frac{1}{\sec(x)} dx \\ -\cos(y) &= -\sin(x) + c_1 \end{aligned}$$

Which results in

$$y = \pi - \arccos(-\sin(x) + c_1)$$

Summary

The solution(s) found are the following

$$y = \pi - \arccos(-\sin(x) + c_1) \tag{1}$$

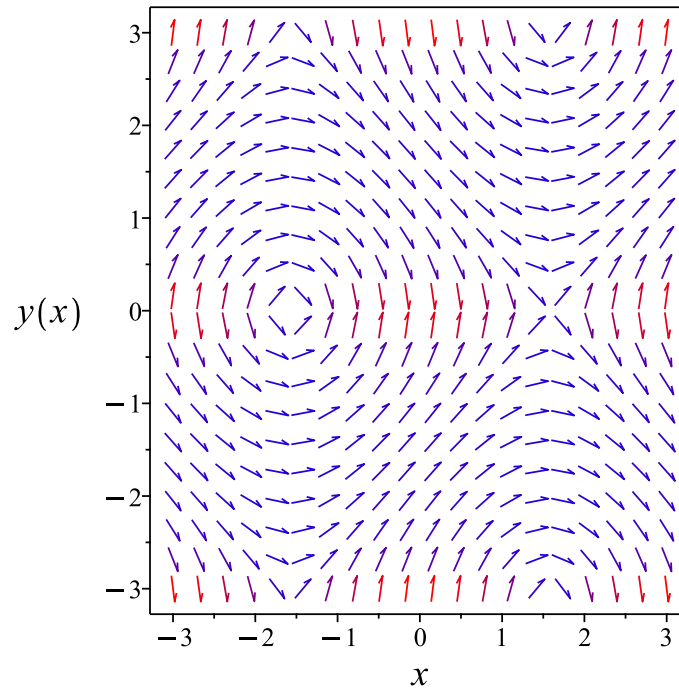


Figure 86: Slope field plot

Verification of solutions

$$y = \pi - \arccos(-\sin(x) + c_1)$$

Verified OK.

4.4.2 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = -\frac{\csc(y)}{\sec(x)}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **separable**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 79: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= -\sec(x) \\ \eta(x, y) &= 0\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\eta = 0$ then in this special case

$$R = y$$

S is found from

$$\begin{aligned}S &= \int \frac{1}{\xi} dx \\ &= \int \frac{1}{-\sec(x)} dx\end{aligned}$$

Which results in

$$S = -\sin(x)$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y}\tag{2}$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{\csc(y)}{\sec(x)}$$

Evaluating all the partial derivatives gives

$$\begin{aligned}R_x &= 0 \\R_y &= 1 \\S_x &= -\cos(x) \\S_y &= 0\end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = \sin(y) \tag{2A}$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = \sin(R)$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = -\cos(R) + c_1 \tag{4}$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$-\sin(x) = -\cos(y) + c_1$$

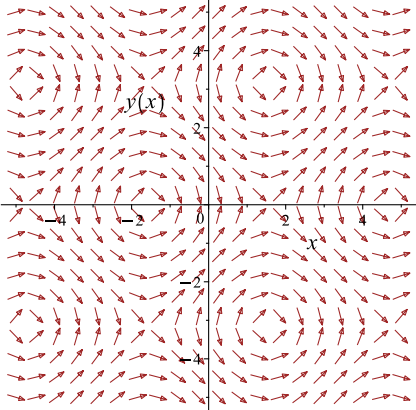
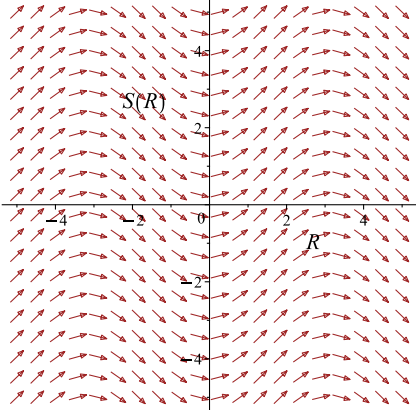
Which simplifies to

$$-\sin(x) = -\cos(y) + c_1$$

Which gives

$$y = \arccos(\sin(x) + c_1)$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{\csc(y)}{\sec(x)}$ 	$R = y$ $S = -\sin(x)$	$\frac{dS}{dR} = \sin(R)$ 

Summary

The solution(s) found are the following

$$y = \arccos(\sin(x) + c_1) \tag{1}$$

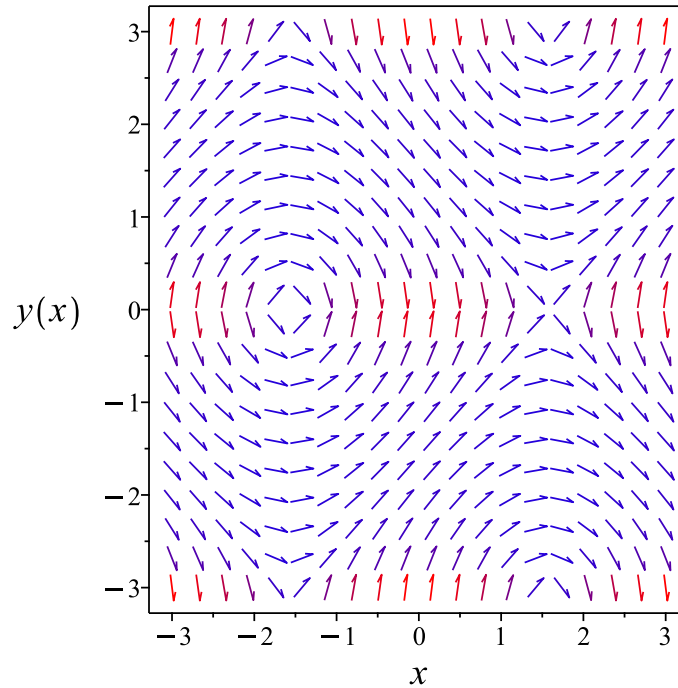


Figure 87: Slope field plot

Verification of solutions

$$y = \arccos(\sin(x) + c_1)$$

Verified OK.

4.4.3 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (1A)$$

Therefore

$$\begin{aligned}\left(-\frac{1}{\csc(y)}\right) dy &= \left(\frac{1}{\sec(x)}\right) dx \\ \left(-\frac{1}{\sec(x)}\right) dx + \left(-\frac{1}{\csc(y)}\right) dy &= 0\end{aligned} \quad (2A)$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= -\frac{1}{\sec(x)} \\ N(x, y) &= -\frac{1}{\csc(y)}\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y} \left(-\frac{1}{\sec(x)}\right) \\ &= 0\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x} \left(-\frac{1}{\csc(y)} \right) \\ &= 0\end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \tag{1}$$

$$\frac{\partial \phi}{\partial y} = N \tag{2}$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int M dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int -\frac{1}{\sec(x)} dx \\ \phi &= -\sin(x) + f(y)\end{aligned} \tag{3}$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = 0 + f'(y) \tag{4}$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = -\frac{1}{\csc(y)}$. Therefore equation (4) becomes

$$-\frac{1}{\csc(y)} = 0 + f'(y) \tag{5}$$

Solving equation (5) for $f'(y)$ gives

$$\begin{aligned}f'(y) &= -\frac{1}{\csc(y)} \\ &= -\sin(y)\end{aligned}$$

Integrating the above w.r.t y results in

$$\int f'(y) dy = \int (-\sin(y)) dy$$
$$f(y) = \cos(y) + c_1$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = -\sin(x) + \cos(y) + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -\sin(x) + \cos(y)$$

Summary

The solution(s) found are the following

$$-\sin(x) + \cos(y) = c_1 \tag{1}$$

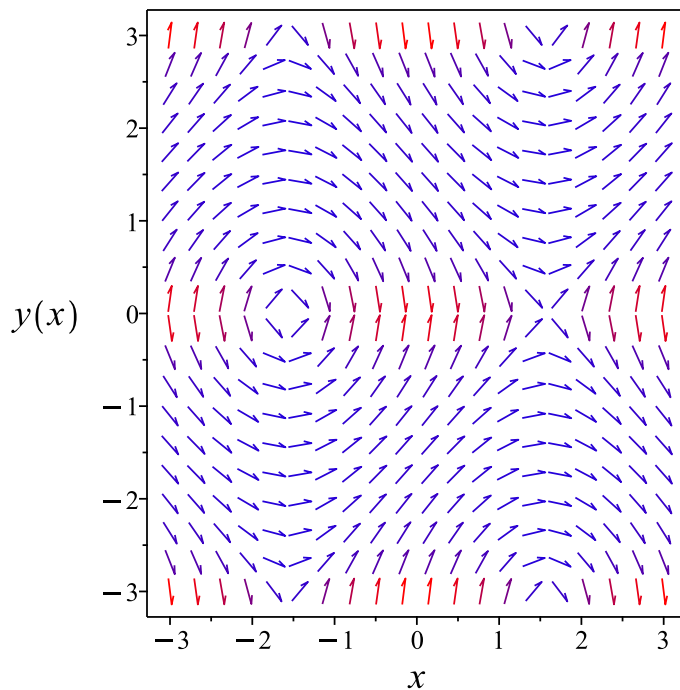


Figure 88: Slope field plot

Verification of solutions

$$-\sin(x) + \cos(y) = c_1$$

Verified OK.

4.4.4 Maple step by step solution

Let's solve

$$\csc(y) + y' \sec(x) = 0$$

- Highest derivative means the order of the ODE is 1

y'

- Separate variables

$$\frac{y'}{\csc(y)} = -\frac{1}{\sec(x)}$$

- Integrate both sides with respect to x

$$\int \frac{y'}{\csc(y)} dx = \int -\frac{1}{\sec(x)} dx + c_1$$

- Evaluate integral

$$-\cos(y) = -\sin(x) + c_1$$

- Solve for y

$$y = \pi - \arccos(-\sin(x) + c_1)$$

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
trying Bernoulli  
trying separable  
<- separable successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 9

```
dsolve(csc(y(x))+sec(x)*diff(y(x),x)=0,y(x), singsol=all)
```

$$y(x) = \arccos(\sin(x) + c_1)$$

✓ Solution by Mathematica

Time used: 0.696 (sec). Leaf size: 27

```
DSolve[Csc[y[x]]+Sec[x]*y'[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow -\arccos(\sin(x) - c_1)$$

$$y(x) \rightarrow \arccos(\sin(x) - c_1)$$

4.5 problem 5

4.5.1	Solving as separable ode	504
4.5.2	Solving as first order ode lie symmetry lookup ode	506
4.5.3	Solving as exact ode	509
4.5.4	Maple step by step solution	513

Internal problem ID [11618]

Internal file name [OUTPUT/10600_Saturday_May_27_2023_03_01_13_AM_76976138/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.2 (Separable equations). Exercises page 47

Problem number: 5.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"exact", "separable", "first_order_ode_lie_symmetry_lookup"**

Maple gives the following as the ode type

`[_separable]`

$$\tan(\theta) + 2r\theta' = 0$$

4.5.1 Solving as separable ode

In canonical form the ODE is

$$\begin{aligned}\theta' &= F(r, \theta) \\ &= f(r)g(\theta) \\ &= -\frac{\tan(\theta)}{2r}\end{aligned}$$

Where $f(r) = -\frac{1}{2r}$ and $g(\theta) = \tan(\theta)$. Integrating both sides gives

$$\begin{aligned}\frac{1}{\tan(\theta)} d\theta &= -\frac{1}{2r} dr \\ \int \frac{1}{\tan(\theta)} d\theta &= \int -\frac{1}{2r} dr \\ \ln(\sin(\theta)) &= -\frac{\ln(r)}{2} + c_1\end{aligned}$$

Raising both side to exponential gives

$$\sin(\theta) = e^{-\frac{\ln(r)}{2} + c_1}$$

Which simplifies to

$$\sin(\theta) = \frac{c_2}{\sqrt{r}}$$

Which simplifies to

$$\theta = \arcsin\left(\frac{c_2 e^{c_1}}{\sqrt{r}}\right)$$

Summary

The solution(s) found are the following

$$\theta = \arcsin\left(\frac{c_2 e^{c_1}}{\sqrt{r}}\right) \tag{1}$$

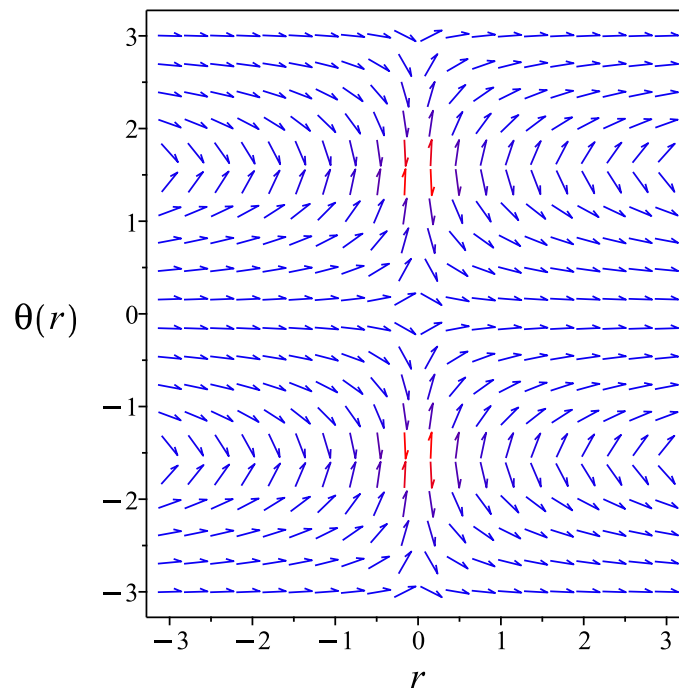


Figure 89: Slope field plot

Verification of solutions

$$\theta = \arcsin\left(\frac{c_2 e^{c_1}}{\sqrt{r}}\right)$$

Verified OK.

4.5.2 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$\theta' = -\frac{\tan(\theta)}{2r}$$

$$\theta' = \omega(r, \theta)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_r + \omega(\eta_\theta - \xi_r) - \omega^2 \xi_\theta - \omega_r \xi - \omega_\theta \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **separable**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 82: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(r, \theta) &= -2r \\ \eta(r, \theta) &= 0\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(r, \theta) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dr}{\xi} = \frac{d\theta}{\eta} = dS\tag{1}$$

The above comes from the requirements that $(\xi \frac{\partial}{\partial r} + \eta \frac{\partial}{\partial \theta}) S(r, \theta) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\eta = 0$ then in this special case

$$R = \theta$$

S is found from

$$\begin{aligned}S &= \int \frac{1}{\xi} dr \\ &= \int \frac{1}{-2r} dr\end{aligned}$$

Which results in

$$S = -\frac{\ln(r)}{2}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_r + \omega(r, \theta)S_\theta}{R_r + \omega(r, \theta)R_\theta}\tag{2}$$

Where in the above $R_r, R_\theta, S_r, S_\theta$ are all partial derivatives and $\omega(r, \theta)$ is the right hand side of the original ode given by

$$\omega(r, \theta) = -\frac{\tan(\theta)}{2r}$$

Evaluating all the partial derivatives gives

$$\begin{aligned}R_r &= 0 \\ R_\theta &= 1 \\ S_r &= -\frac{1}{2r} \\ S_\theta &= 0\end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = \cot(\theta) \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for r, θ in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = \cot(R)$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = \ln(\sin(R)) + c_1 \quad (4)$$

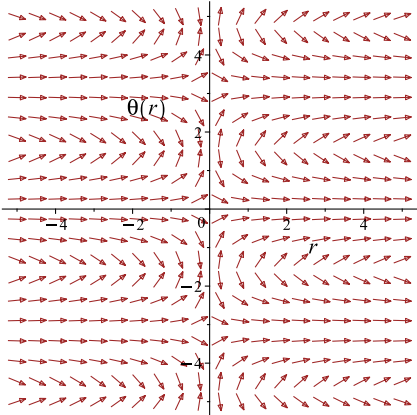
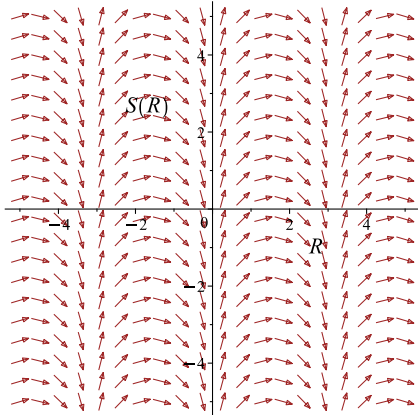
To complete the solution, we just need to transform (4) back to r, θ coordinates. This results in

$$-\frac{\ln(r)}{2} = \ln(\sin(\theta)) + c_1$$

Which simplifies to

$$-\frac{\ln(r)}{2} = \ln(\sin(\theta)) + c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in r, θ coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{d\theta}{dr} = -\frac{\tan(\theta)}{2r}$ 	$R = \theta$ $S = -\frac{\ln(r)}{2}$	$\frac{dS}{dR} = \cot(R)$ 

Summary

The solution(s) found are the following

$$-\frac{\ln(r)}{2} = \ln(\sin(\theta)) + c_1 \quad (1)$$

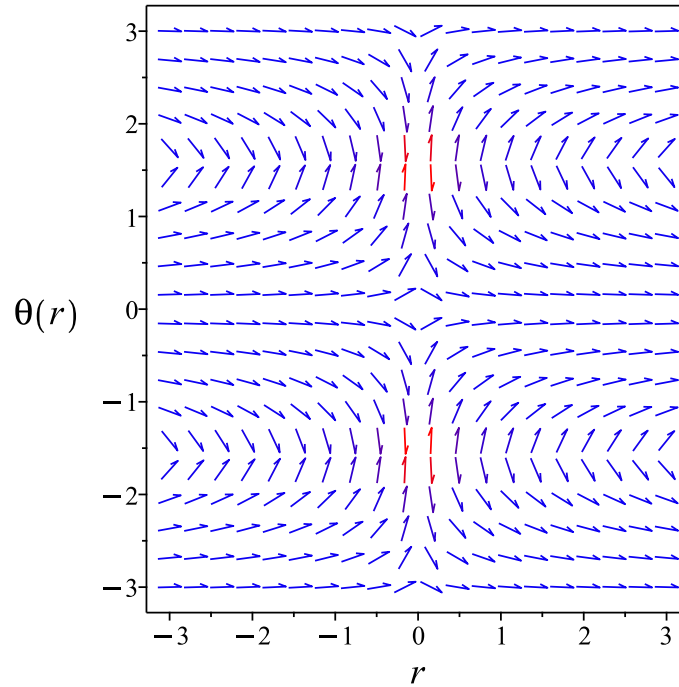


Figure 90: Slope field plot

Verification of solutions

$$-\frac{\ln(r)}{2} = \ln(\sin(\theta)) + c_1$$

Verified OK.

4.5.3 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \quad (\text{A})$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx}\phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \quad (\text{B})$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(r, \theta) dr + N(r, \theta) d\theta = 0 \quad (\text{1A})$$

Therefore

$$\begin{aligned} \left(-\frac{2}{\tan(\theta)}\right) d\theta &= \left(\frac{1}{r}\right) dr \\ \left(-\frac{1}{r}\right) dr + \left(-\frac{2}{\tan(\theta)}\right) d\theta &= 0 \end{aligned} \quad (\text{2A})$$

Comparing (1A) and (2A) shows that

$$\begin{aligned} M(r, \theta) &= -\frac{1}{r} \\ N(r, \theta) &= -\frac{2}{\tan(\theta)} \end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial \theta} = \frac{\partial N}{\partial r}$$

Using result found above gives

$$\begin{aligned} \frac{\partial M}{\partial \theta} &= \frac{\partial}{\partial \theta} \left(-\frac{1}{r}\right) \\ &= 0 \end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial r} &= \frac{\partial}{\partial r} \left(-\frac{2}{\tan(\theta)} \right) \\ &= 0\end{aligned}$$

Since $\frac{\partial M}{\partial \theta} = \frac{\partial N}{\partial r}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(r, \theta)$

$$\frac{\partial \phi}{\partial r} = M \quad (1)$$

$$\frac{\partial \phi}{\partial \theta} = N \quad (2)$$

Integrating (1) w.r.t. r gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial r} dr &= \int M dr \\ \int \frac{\partial \phi}{\partial r} dr &= \int -\frac{1}{r} dr \\ \phi &= -\ln(r) + f(\theta)\end{aligned} \quad (3)$$

Where $f(\theta)$ is used for the constant of integration since ϕ is a function of both r and θ . Taking derivative of equation (3) w.r.t θ gives

$$\frac{\partial \phi}{\partial \theta} = 0 + f'(\theta) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial \theta} = -\frac{2}{\tan(\theta)}$. Therefore equation (4) becomes

$$-\frac{2}{\tan(\theta)} = 0 + f'(\theta) \quad (5)$$

Solving equation (5) for $f'(\theta)$ gives

$$\begin{aligned}f'(\theta) &= -\frac{2}{\tan(\theta)} \\ &= -2 \cot(\theta)\end{aligned}$$

Integrating the above w.r.t θ results in

$$\int f'(\theta) d\theta = \int (-2 \cot(\theta)) d\theta$$

$$f(\theta) = -2 \ln(\sin(\theta)) + c_1$$

Where c_1 is constant of integration. Substituting result found above for $f(\theta)$ into equation (3) gives ϕ

$$\phi = -\ln(r) - 2 \ln(\sin(\theta)) + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -\ln(r) - 2 \ln(\sin(\theta))$$

Summary

The solution(s) found are the following

$$-\ln(r) - 2 \ln(\sin(\theta)) = c_1 \tag{1}$$

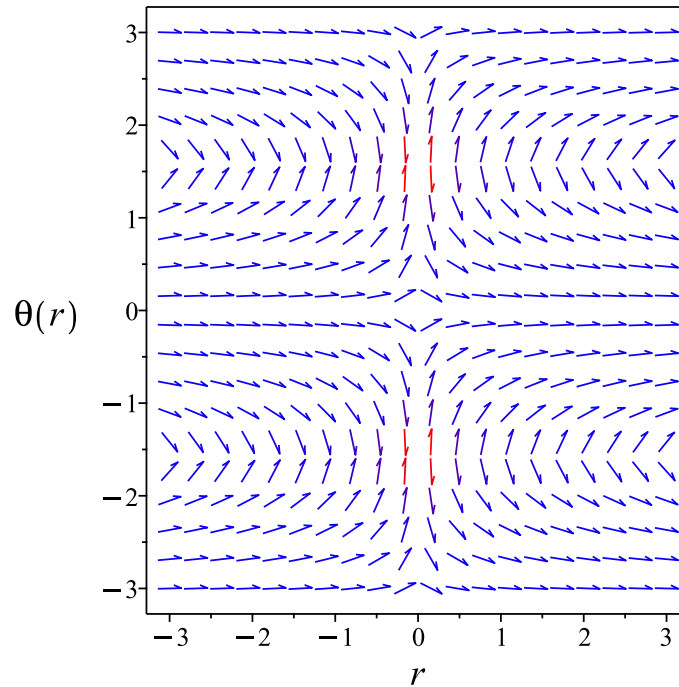


Figure 91: Slope field plot

Verification of solutions

$$-\ln(r) - 2\ln(\sin(\theta)) = c_1$$

Verified OK.

4.5.4 Maple step by step solution

Let's solve

$$\tan(\theta) + 2r\theta' = 0$$

- Highest derivative means the order of the ODE is 1
 θ'

- Separate variables

$$\frac{\theta'}{\tan(\theta)} = -\frac{1}{2r}$$

- Integrate both sides with respect to r

$$\int \frac{\theta'}{\tan(\theta)} dr = \int -\frac{1}{2r} dr + c_1$$

- Evaluate integral

$$\ln(\sin(\theta)) = -\frac{\ln(r)}{2} + c_1$$

- Solve for θ

$$\left\{ \theta = -\arcsin\left(\frac{\sqrt{r e^{2c_1}}}{r}\right), \theta = \arcsin\left(\frac{\sqrt{r e^{2c_1}}}{r}\right) \right\}$$

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
trying Bernoulli  
trying separable  
<- separable successful`
```

✓ Solution by Maple

Time used: 0.313 (sec). Leaf size: 21

```
dsolve(tan(theta(r))+2*r*diff(theta(r),r)=0,theta(r), singsol=all)
```

$$\theta(r) = \arcsin\left(\frac{1}{\sqrt{c_1 r}}\right)$$

$$\theta(r) = -\arcsin\left(\frac{1}{\sqrt{c_1 r}}\right)$$

✓ Solution by Mathematica

Time used: 15.319 (sec). Leaf size: 21

```
DSolve[Tan[theta[r]]+2*r*theta'[r]==0,theta[r],r,IncludeSingularSolutions -> True]
```

$$\theta(r) \rightarrow \arcsin\left(\frac{e^{c_1}}{\sqrt{r}}\right)$$

$$\theta(r) \rightarrow 0$$

4.6 problem 6

4.6.1	Solving as separable ode	515
4.6.2	Solving as first order ode lie symmetry lookup ode	517
4.6.3	Solving as exact ode	521
4.6.4	Maple step by step solution	525

Internal problem ID [11619]

Internal file name [OUTPUT/10601_Saturday_May_27_2023_03_01_15_AM_62894160/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.2 (Separable equations). Exercises page 47

Problem number: 6.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"exact", "separable", "first_order_ode_lie_symmetry_lookup"**

Maple gives the following as the ode type

`[_separable]`

$$(e^v + 1) \cos(u) + e^v(1 + \sin(u)) v' = 0$$

4.6.1 Solving as separable ode

In canonical form the ODE is

$$\begin{aligned} v' &= F(u, v) \\ &= f(u)g(v) \\ &= -\frac{\cos(u)(1 + e^{-v})}{1 + \sin(u)} \end{aligned}$$

Where $f(u) = -\frac{\cos(u)}{1 + \sin(u)}$ and $g(v) = 1 + e^{-v}$. Integrating both sides gives

$$\begin{aligned} \frac{1}{1 + e^{-v}} dv &= -\frac{\cos(u)}{1 + \sin(u)} du \\ \int \frac{1}{1 + e^{-v}} dv &= \int -\frac{\cos(u)}{1 + \sin(u)} du \end{aligned}$$

$$\ln(1 + e^{-v}) - \ln(e^{-v}) = -\ln(1 + \sin(u)) + c_1$$

Raising both side to exponential gives

$$e^{\ln(1+e^{-v})-\ln(e^{-v})} = e^{-\ln(1+\sin(u))+c_1}$$

Which simplifies to

$$e^v + 1 = \frac{c_2}{1 + \sin(u)}$$

Summary

The solution(s) found are the following

$$v = \ln \left(-\frac{1 + \sin(u) - c_2}{1 + \sin(u)} \right) \quad (1)$$

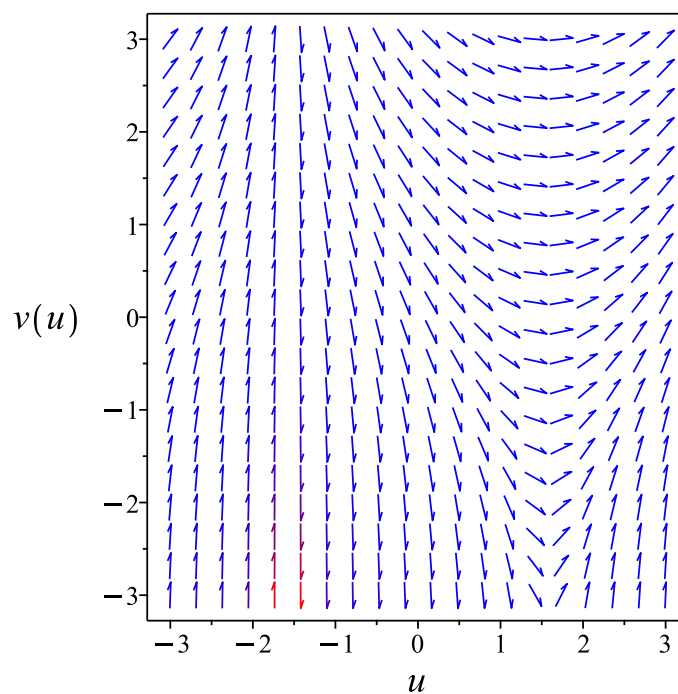


Figure 92: Slope field plot

Verification of solutions

$$v = \ln \left(-\frac{1 + \sin(u) - c_2}{1 + \sin(u)} \right)$$

Verified OK.

4.6.2 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$v' = -\frac{(e^v + 1) \cos(u) e^{-v}}{1 + \sin(u)}$$

$$v' = \omega(u, v)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_u + \omega(\eta_v - \xi_u) - \omega^2 \xi_v - \omega_u \xi - \omega_v \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **separable**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 85: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(u, v) &= -\frac{1 + \sin(u)}{\cos(u)} \\ \eta(u, v) &= 0\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(u, v) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{du}{\xi} = \frac{dv}{\eta} = dS\tag{1}$$

The above comes from the requirements that $(\xi \frac{\partial}{\partial u} + \eta \frac{\partial}{\partial v}) S(u, v) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\eta = 0$ then in this special case

$$R = v$$

S is found from

$$\begin{aligned}S &= \int \frac{1}{\xi} du \\ &= \int \frac{1}{-\frac{1+\sin(u)}{\cos(u)}} du\end{aligned}$$

Which results in

$$S = -\ln(1 + \sin(u))$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_u + \omega(u, v)S_v}{R_u + \omega(u, v)R_v}\tag{2}$$

Where in the above R_u, R_v, S_u, S_v are all partial derivatives and $\omega(u, v)$ is the right hand side of the original ode given by

$$\omega(u, v) = -\frac{(e^v + 1) \cos(u) e^{-v}}{1 + \sin(u)}$$

Evaluating all the partial derivatives gives

$$\begin{aligned}R_u &= 0 \\R_v &= 1 \\S_u &= -\frac{\cos(u)}{1 + \sin(u)} \\S_v &= 0\end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = \frac{e^v}{e^v + 1} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for u, v in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = \frac{e^R}{e^R + 1}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = \ln(e^R + 1) + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to u, v coordinates. This results in

$$-\ln(1 + \sin(u)) = \ln(e^v + 1) + c_1$$

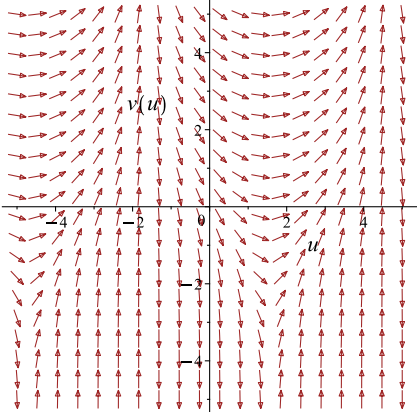
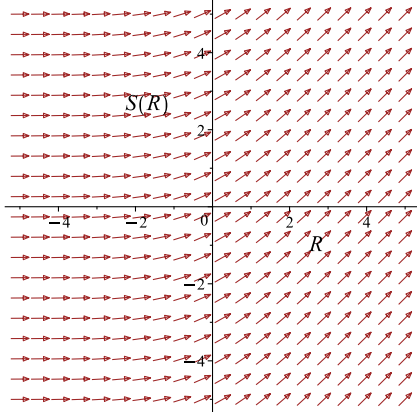
Which simplifies to

$$-\ln(1 + \sin(u)) = \ln(e^v + 1) + c_1$$

Which gives

$$v = \ln\left(-\frac{-1 + \sin(u) e^{c_1} + e^{c_1}}{1 + \sin(u)}\right) - c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in u, v coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dv}{du} = -\frac{(e^v+1)\cos(u)e^{-v}}{1+\sin(u)}$ 	$R = v$ $S = -\ln(1 + \sin(u))$	$\frac{dS}{dR} = \frac{e^R}{e^R+1}$ 

Summary

The solution(s) found are the following

$$v = \ln\left(-\frac{-1 + \sin(u) e^{c_1} + e^{c_1}}{1 + \sin(u)}\right) - c_1 \quad (1)$$

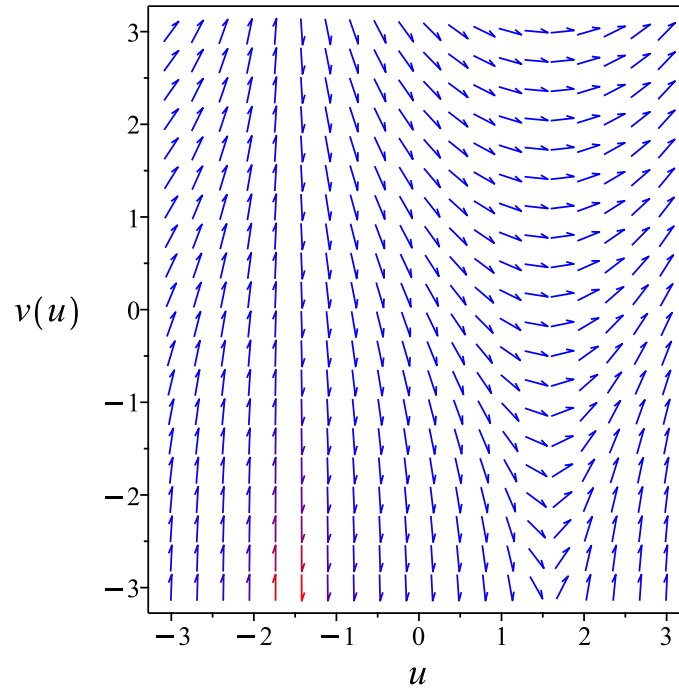


Figure 93: Slope field plot

Verification of solutions

$$v = \ln \left(-\frac{-1 + \sin(u) e^{c_1} + e^{c_1}}{1 + \sin(u)} \right) - c_1$$

Verified OK.

4.6.3 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(u, v) du + N(u, v) dv = 0 \quad (1A)$$

Therefore

$$\begin{aligned}\left(-\frac{e^v}{e^v + 1}\right) dv &= \left(\frac{\cos(u)}{1 + \sin(u)}\right) du \\ \left(-\frac{\cos(u)}{1 + \sin(u)}\right) du + \left(-\frac{e^v}{e^v + 1}\right) dv &= 0\end{aligned} \quad (2A)$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(u, v) &= -\frac{\cos(u)}{1 + \sin(u)} \\ N(u, v) &= -\frac{e^v}{e^v + 1}\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial v} = \frac{\partial N}{\partial u}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial v} &= \frac{\partial}{\partial v} \left(-\frac{\cos(u)}{1 + \sin(u)}\right) \\ &= 0\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial u} &= \frac{\partial}{\partial u} \left(-\frac{e^v}{e^v + 1} \right) \\ &= 0\end{aligned}$$

Since $\frac{\partial M}{\partial v} = \frac{\partial N}{\partial u}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(u, v)$

$$\frac{\partial \phi}{\partial u} = M \quad (1)$$

$$\frac{\partial \phi}{\partial v} = N \quad (2)$$

Integrating (1) w.r.t. u gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial u} du &= \int M du \\ \int \frac{\partial \phi}{\partial u} du &= \int -\frac{\cos(u)}{1 + \sin(u)} du \\ \phi &= -\ln(1 + \sin(u)) + f(v)\end{aligned} \quad (3)$$

Where $f(v)$ is used for the constant of integration since ϕ is a function of both u and v . Taking derivative of equation (3) w.r.t v gives

$$\frac{\partial \phi}{\partial v} = 0 + f'(v) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial v} = -\frac{e^v}{e^v + 1}$. Therefore equation (4) becomes

$$-\frac{e^v}{e^v + 1} = 0 + f'(v) \quad (5)$$

Solving equation (5) for $f'(v)$ gives

$$f'(v) = -\frac{e^v}{e^v + 1}$$

Integrating the above w.r.t v gives

$$\begin{aligned}\int f'(v) dv &= \int \left(-\frac{e^v}{e^v + 1} \right) dv \\ f(v) &= -\ln(e^v + 1) + c_1\end{aligned}$$

Where c_1 is constant of integration. Substituting result found above for $f(v)$ into equation (3) gives ϕ

$$\phi = -\ln(1 + \sin(u)) - \ln(e^v + 1) + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -\ln(1 + \sin(u)) - \ln(e^v + 1)$$

The solution becomes

$$v = \ln\left(-\frac{-1 + \sin(u) e^{c_1} + e^{c_1}}{1 + \sin(u)}\right) - c_1$$

Summary

The solution(s) found are the following

$$v = \ln\left(-\frac{-1 + \sin(u) e^{c_1} + e^{c_1}}{1 + \sin(u)}\right) - c_1 \quad (1)$$

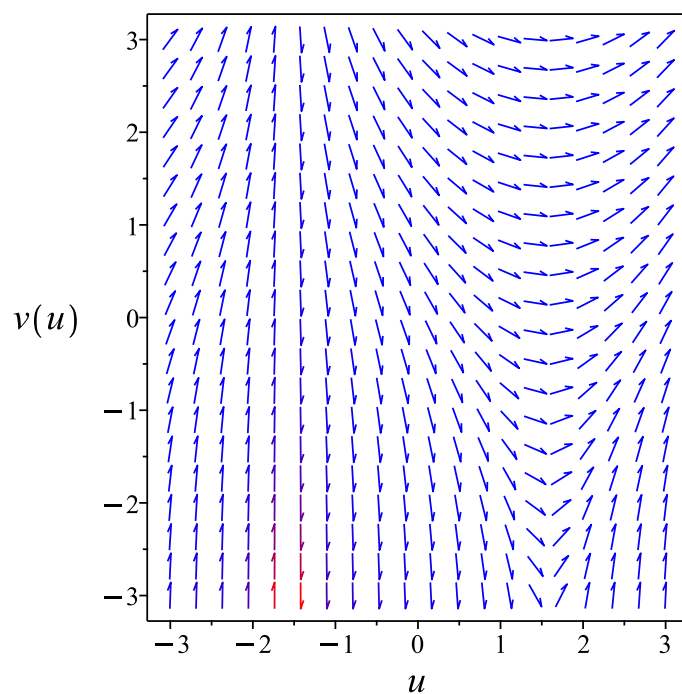


Figure 94: Slope field plot

Verification of solutions

$$v = \ln \left(-\frac{-1 + \sin(u) e^{c_1} + e^{c_1}}{1 + \sin(u)} \right) - c_1$$

Verified OK.

4.6.4 Maple step by step solution

Let's solve

$$(e^v + 1) \cos(u) + e^v(1 + \sin(u)) v' = 0$$

- Highest derivative means the order of the ODE is 1
 v'

- Integrate both sides with respect to u

$$\int ((e^v + 1) \cos(u) + e^v(1 + \sin(u)) v') du = \int 0 du + c_1$$

- Evaluate integral

$$e^v \sin(u) + \sin(u) + e^v = c_1$$

- Solve for v

$$v = \ln \left(-\frac{\sin(u) - c_1}{1 + \sin(u)} \right)$$

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
trying Bernoulli  
trying separable  
<- separable successful`
```

✓ Solution by Maple

Time used: 0.64 (sec). Leaf size: 29

```
dsolve((exp(v(u))+1)*cos(u) + exp(v(u))*(1+sin(u))*diff(v(u),u)=0,v(u), singsol=all)
```

$$v(u) = -\ln \left(\frac{-1 - \sin(u)}{-1 + (1 + \sin(u)) e^{c_1}} \right) - c_1$$

✓ Solution by Mathematica

Time used: 5.457 (sec). Leaf size: 37

```
DSolve[(Exp[v[u]]+1)*Cos[u] + Exp[v[u]]*(1+Sin[u])*v'[u]==0, v[u], u, IncludeSingularSolutions
```

$$v(u) \rightarrow \log \left(-1 + \frac{e^{c_1}}{\left(\sin \left(\frac{u}{2} \right) + \cos \left(\frac{u}{2} \right) \right)^2} \right)$$

$$v(u) \rightarrow i\pi$$

4.7 problem 7

4.7.1	Solving as separable ode	527
4.7.2	Solving as first order ode lie symmetry lookup ode	529
4.7.3	Solving as bernoulli ode	533
4.7.4	Solving as exact ode	537
4.7.5	Maple step by step solution	541

Internal problem ID [11620]

Internal file name [OUTPUT/10602_Saturday_May_27_2023_03_01_16_AM_78210111/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 2, section 2.2 (Separable equations). Exercises page 47

Problem number: 7.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact", "bernoulli", "separable", "first_order_ode_lie_symmetry_lookup"

Maple gives the following as the ode type

`[_separable]`

$$(x + 4) (1 + y^2) + y(x^2 + 3x + 2) y' = 0$$

4.7.1 Solving as separable ode

In canonical form the ODE is

$$\begin{aligned} y' &= F(x, y) \\ &= f(x)g(y) \\ &= \frac{(x + 4) (-y^2 - 1)}{(1 + x) (x + 2) y} \end{aligned}$$

Where $f(x) = \frac{x+4}{(1+x)(x+2)}$ and $g(y) = \frac{-y^2-1}{y}$. Integrating both sides gives

$$\frac{1}{\frac{-y^2-1}{y}} dy = \frac{x + 4}{(1 + x) (x + 2)} dx$$

$$\int \frac{1}{\frac{-y^2-1}{y}} dy = \int \frac{x+4}{(1+x)(x+2)} dx$$

$$-\frac{\ln(y^2+1)}{2} = 3\ln(1+x) - 2\ln(x+2) + c_1$$

Raising both side to exponential gives

$$\frac{1}{\sqrt{y^2+1}} = e^{3\ln(1+x)-2\ln(x+2)+c_1}$$

Which simplifies to

$$\frac{1}{\sqrt{y^2+1}} = c_2 e^{3\ln(1+x)-2\ln(x+2)}$$

The solution is

$$\frac{1}{\sqrt{1+y^2}} = c_2 e^{3\ln(1+x)-2\ln(x+2)+c_1}$$

Summary

The solution(s) found are the following

$$\frac{1}{\sqrt{1+y^2}} = c_2 e^{3\ln(1+x)-2\ln(x+2)+c_1} \quad (1)$$

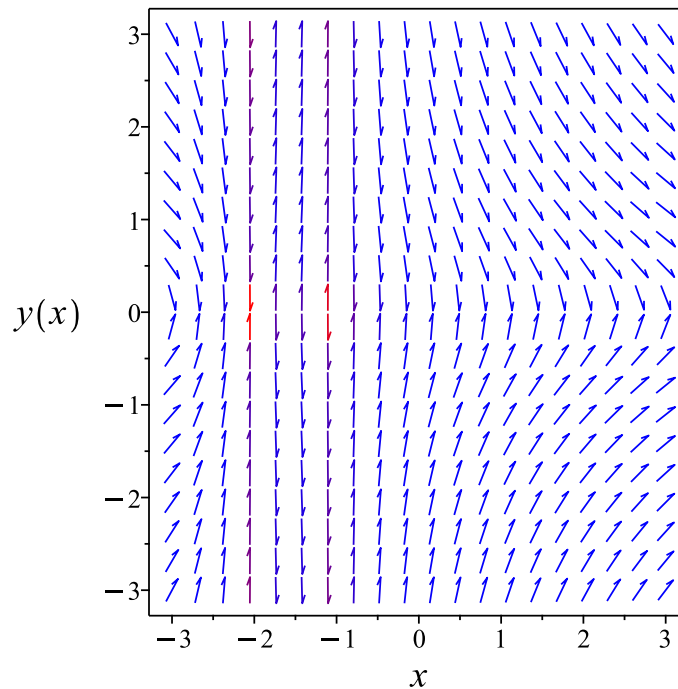


Figure 95: Slope field plot

Verification of solutions

$$\frac{1}{\sqrt{1+y^2}} = c_2 e^{3\ln(1+x) - 2\ln(x+2) + c_1}$$

Verified OK.

4.7.2 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = -\frac{x y^2 + 4y^2 + x + 4}{y(x^2 + 3x + 2)}$$
$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **separable**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 88: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= \frac{(1+x)(x+2)}{x+4} \\ \eta(x, y) &= 0\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\eta = 0$ then in this special case

$$R = y$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\xi} dx \\ &= \int \frac{1}{\frac{(1+x)(x+2)}{x+4}} dx \end{aligned}$$

Which results in

$$S = 3 \ln(1+x) - 2 \ln(x+2)$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{xy^2 + 4y^2 + x + 4}{y(x^2 + 3x + 2)}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 0 \\ R_y &= 1 \\ S_x &= \frac{x+4}{(1+x)(x+2)} \\ S_y &= 0 \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = -\frac{y}{y^2 + 1} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = -\frac{R}{R^2 + 1}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = -\frac{\ln(R^2 + 1)}{2} + c_1 \quad (4)$$

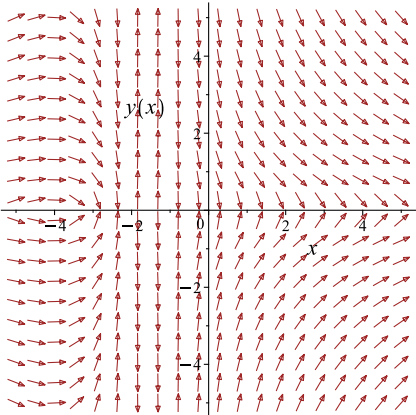
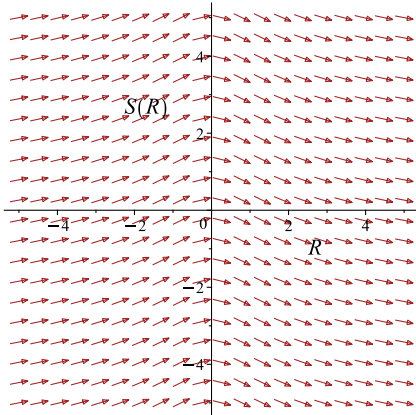
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$3 \ln(1 + x) - 2 \ln(x + 2) = -\frac{\ln(1 + y^2)}{2} + c_1$$

Which simplifies to

$$3 \ln(1 + x) - 2 \ln(x + 2) = -\frac{\ln(1 + y^2)}{2} + c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{xy^2 + 4y^2 + x + 4}{y(x^2 + 3x + 2)}$ 	$R = y$ $S = 3 \ln(1 + x) - 2 \ln(x + 2)$	$\frac{dS}{dR} = -\frac{R}{R^2 + 1}$ 

Summary

The solution(s) found are the following

$$3 \ln(1 + x) - 2 \ln(x + 2) = -\frac{\ln(1 + y^2)}{2} + c_1 \quad (1)$$

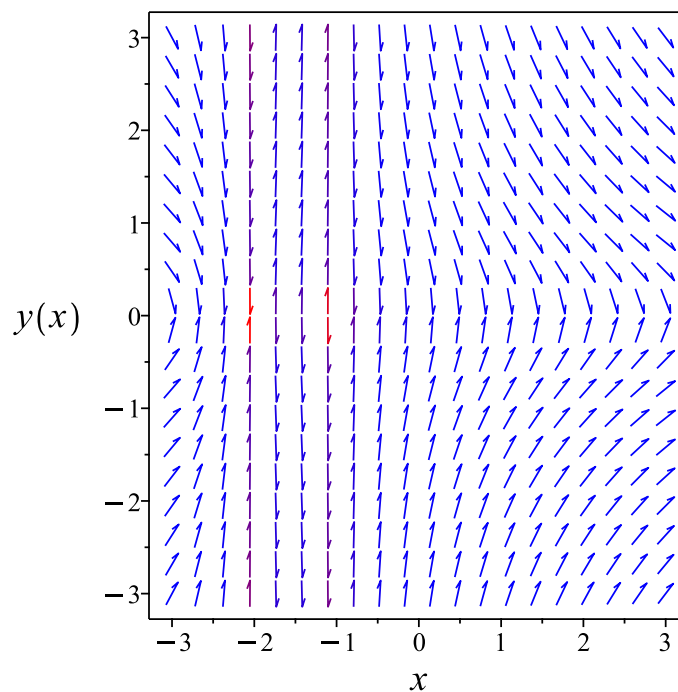


Figure 96: Slope field plot

Verification of solutions

$$3 \ln(1+x) - 2 \ln(x+2) = -\frac{\ln(1+y^2)}{2} + c_1$$

Verified OK.

4.7.3 Solving as bernoulli ode

In canonical form, the ODE is

$$\begin{aligned} y' &= F(x, y) \\ &= -\frac{x y^2 + 4y^2 + x + 4}{y(x^2 + 3x + 2)} \end{aligned}$$

This is a Bernoulli ODE.

$$y' = -\frac{x+4}{x^2+3x+2}y - \frac{x+4}{x^2+3x+2} \frac{1}{y} \quad (1)$$

The standard Bernoulli ODE has the form

$$y' = f_0(x)y + f_1(x)y^n \quad (2)$$

The first step is to divide the above equation by y^n which gives

$$\frac{y'}{y^n} = f_0(x)y^{1-n} + f_1(x) \quad (3)$$

The next step is use the substitution $w = y^{1-n}$ in equation (3) which generates a new ODE in $w(x)$ which will be linear and can be easily solved using an integrating factor. Backsubstitution then gives the solution $y(x)$ which is what we want.

This method is now applied to the ODE at hand. Comparing the ODE (1) With (2) Shows that

$$\begin{aligned} f_0(x) &= -\frac{x+4}{x^2+3x+2} \\ f_1(x) &= -\frac{x+4}{x^2+3x+2} \\ n &= -1 \end{aligned}$$

Dividing both sides of ODE (1) by $y^n = \frac{1}{y}$ gives

$$y'y = -\frac{(x+4)y^2}{x^2+3x+2} - \frac{x+4}{x^2+3x+2} \quad (4)$$

Let

$$\begin{aligned} w &= y^{1-n} \\ &= y^2 \end{aligned} \quad (5)$$

Taking derivative of equation (5) w.r.t x gives

$$w' = 2yy' \quad (6)$$

Substituting equations (5) and (6) into equation (4) gives

$$\begin{aligned} \frac{w'(x)}{2} &= -\frac{(x+4)w(x)}{x^2+3x+2} - \frac{x+4}{x^2+3x+2} \\ w' &= -\frac{2(x+4)w}{x^2+3x+2} - \frac{2(x+4)}{x^2+3x+2} \end{aligned} \quad (7)$$

The above now is a linear ODE in $w(x)$ which is now solved.

Entering Linear first order ODE solver. In canonical form a linear first order is

$$w'(x) + p(x)w(x) = q(x)$$

Where here

$$p(x) = -\frac{-2x - 8}{x^2 + 3x + 2}$$

$$q(x) = \frac{-2x - 8}{x^2 + 3x + 2}$$

Hence the ode is

$$w'(x) - \frac{(-2x - 8)w(x)}{x^2 + 3x + 2} = \frac{-2x - 8}{x^2 + 3x + 2}$$

The integrating factor μ is

$$\mu = e^{\int -\frac{-2x-8}{x^2+3x+2} dx}$$

$$= e^{6\ln(1+x)-4\ln(x+2)}$$

Which simplifies to

$$\mu = \frac{(1+x)^6}{(x+2)^4}$$

The ode becomes

$$\frac{d}{dx}(\mu w) = (\mu) \left(\frac{-2x - 8}{x^2 + 3x + 2} \right)$$

$$\frac{d}{dx} \left(\frac{(1+x)^6 w}{(x+2)^4} \right) = \left(\frac{(1+x)^6}{(x+2)^4} \right) \left(\frac{-2x - 8}{x^2 + 3x + 2} \right)$$

$$d \left(\frac{(1+x)^6 w}{(x+2)^4} \right) = \left(-\frac{2(1+x)^5 (x+4)}{(x+2)^5} \right) dx$$

Integrating gives

$$\frac{(1+x)^6 w}{(x+2)^4} = \int -\frac{2(1+x)^5 (x+4)}{(x+2)^5} dx$$

$$\frac{(1+x)^6 w}{(x+2)^4} = -x^2 + 2x + \frac{6}{(x+2)^3} - \frac{15}{(x+2)^2} + \frac{20}{x+2} - \frac{1}{(x+2)^4} + c_1$$

Dividing both sides by the integrating factor $\mu = \frac{(1+x)^6}{(x+2)^4}$ results in

$$w(x) = \frac{(x+2)^4 \left(-x^2 + 2x + \frac{6}{(x+2)^3} - \frac{15}{(x+2)^2} + \frac{20}{x+2} - \frac{1}{(x+2)^4} \right)}{(1+x)^6} + \frac{c_1 (x+2)^4}{(1+x)^6}$$

which simplifies to

$$w(x) = \frac{-x^6 - 6x^5 + (c_1 - 8)x^4 + (8c_1 + 36)x^3 + (24c_1 + 153)x^2 + (32c_1 + 218)x + 16c_1 + 111}{(1+x)^6}$$

Replacing w in the above by y^2 using equation (5) gives the final solution.

$$y^2 = \frac{-x^6 - 6x^5 + (c_1 - 8)x^4 + (8c_1 + 36)x^3 + (24c_1 + 153)x^2 + (32c_1 + 218)x + 16c_1 + 111}{(1+x)^6}$$

Solving for y gives

$$y(x) = \frac{\sqrt{-x^6 - 6x^5 + (c_1 - 8)x^4 + (8c_1 + 36)x^3 + (24c_1 + 153)x^2 + (32c_1 + 218)x + 16c_1 + 111}}{(1+x)^3}$$

$$y(x) = -\frac{\sqrt{-x^6 - 6x^5 + (c_1 - 8)x^4 + (8c_1 + 36)x^3 + (24c_1 + 153)x^2 + (32c_1 + 218)x + 16c_1 + 111}}{(1+x)^3}$$

Summary

The solution(s) found are the following

$$y = \frac{\sqrt{-x^6 - 6x^5 + (c_1 - 8)x^4 + (8c_1 + 36)x^3 + (24c_1 + 153)x^2 + (32c_1 + 218)x + 16c_1 + 111}}{(1+x)^3} \quad (1)$$

$$y = -\frac{\sqrt{-x^6 - 6x^5 + (c_1 - 8)x^4 + (8c_1 + 36)x^3 + (24c_1 + 153)x^2 + (32c_1 + 218)x + 16c_1 + 111}}{(1+x)^3} \quad (2)$$

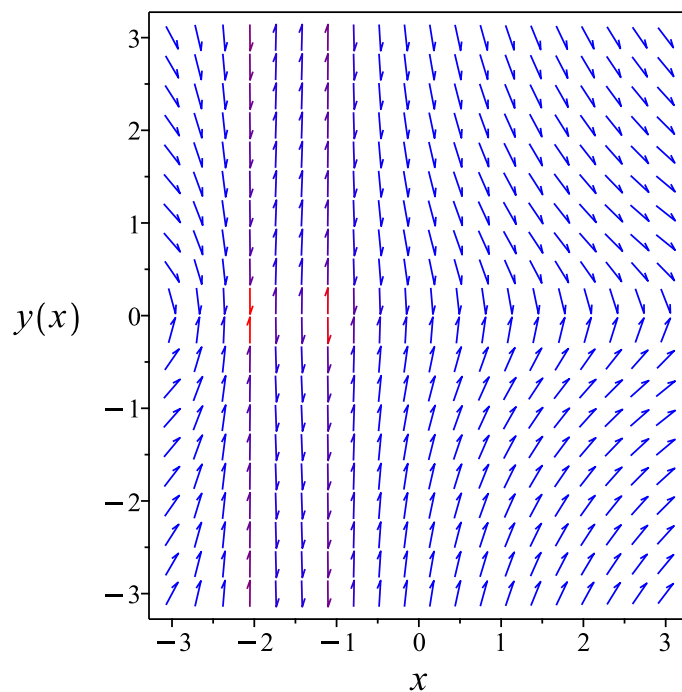


Figure 97: Slope field plot

Verification of solutions

$$y = \frac{\sqrt{-x^6 - 6x^5 + (c_1 - 8)x^4 + (8c_1 + 36)x^3 + (24c_1 + 153)x^2 + (32c_1 + 218)x + 16c_1 + 111}}{(1+x)^3}$$

Verified OK.

$$y = -\frac{\sqrt{-x^6 - 6x^5 + (c_1 - 8)x^4 + (8c_1 + 36)x^3 + (24c_1 + 153)x^2 + (32c_1 + 218)x + 16c_1 + 111}}{(1+x)^3}$$

Verified OK.

4.7.4 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the

ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx}\phi(x, y) = 0$$

Hence

$$\frac{\partial\phi}{\partial x} + \frac{\partial\phi}{\partial y} \frac{dy}{dx} = 0 \quad (\text{B})$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial\phi}{\partial x} &= M \\ \frac{\partial\phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (\text{1A})$$

Therefore

$$\begin{aligned} \left(\frac{y}{-y^2-1}\right) dy &= \left(\frac{x+4}{(1+x)(x+2)}\right) dx \\ \left(-\frac{x+4}{(1+x)(x+2)}\right) dx &+ \left(\frac{y}{-y^2-1}\right) dy = 0 \end{aligned} \quad (\text{2A})$$

Comparing (1A) and (2A) shows that

$$\begin{aligned} M(x, y) &= -\frac{x+4}{(1+x)(x+2)} \\ N(x, y) &= \frac{y}{-y^2-1} \end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y} \left(-\frac{x+4}{(1+x)(x+2)} \right) \\ &= 0\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x} \left(\frac{y}{-y^2-1} \right) \\ &= 0\end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \quad (1)$$

$$\frac{\partial \phi}{\partial y} = N \quad (2)$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int M dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int -\frac{x+4}{(1+x)(x+2)} dx \\ \phi &= -3 \ln(1+x) + 2 \ln(x+2) + f(y)\end{aligned} \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = 0 + f'(y) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = \frac{y}{-y^2-1}$. Therefore equation (4) becomes

$$\frac{y}{-y^2-1} = 0 + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = -\frac{y}{y^2+1}$$

Integrating the above w.r.t y gives

$$\int f'(y) dy = \int \left(-\frac{y}{y^2 + 1} \right) dy$$
$$f(y) = -\frac{\ln(y^2 + 1)}{2} + c_1$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = -3 \ln(1 + x) + 2 \ln(x + 2) - \frac{\ln(y^2 + 1)}{2} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -3 \ln(1 + x) + 2 \ln(x + 2) - \frac{\ln(y^2 + 1)}{2}$$

Summary

The solution(s) found are the following

$$-3 \ln(1 + x) + 2 \ln(x + 2) - \frac{\ln(1 + y^2)}{2} = c_1 \quad (1)$$

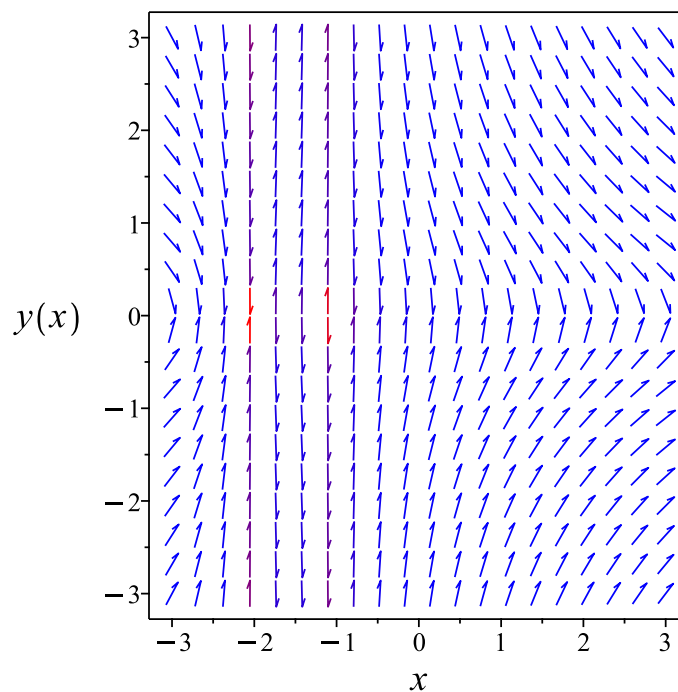


Figure 98: Slope field plot

Verification of solutions

$$-3 \ln(1+x) + 2 \ln(x+2) - \frac{\ln(1+y^2)}{2} = c_1$$

Verified OK.

4.7.5 Maple step by step solution

Let's solve

$$(x+4)(1+y^2) + y(x^2+3x+2)y' = 0$$

- Highest derivative means the order of the ODE is 1

y'

- Separate variables

$$\frac{yy'}{1+y^2} = -\frac{x+4}{x^2+3x+2}$$

- Integrate both sides with respect to x

$$\int \frac{yy'}{1+y^2} dx = \int -\frac{x+4}{x^2+3x+2} dx + c_1$$

- Evaluate integral

$$\frac{\ln(1+y^2)}{2} = -3\ln(1+x) + 2\ln(x+2) + c_1$$

- Solve for y

$$\left\{ y = \frac{\sqrt{x^4 \left(e^{\frac{c_1}{3}}\right)^6 + 8x^3 \left(e^{\frac{c_1}{3}}\right)^6 + 24x^2 \left(e^{\frac{c_1}{3}}\right)^6 + 32x \left(e^{\frac{c_1}{3}}\right)^6 + 16 \left(e^{\frac{c_1}{3}}\right)^6 - x^6 - 6x^5 - 15x^4 - 20x^3 - 15x^2 - 6x - 1}}{(1+x)^3}, y = -\sqrt{x^4 \left(e^{\frac{c_1}{3}}\right)^6}$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
<- Bernoulli successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 114

```
dsolve((x+4)*(y(x)^2+1) + y(x)*(x^2+3*x+2)*diff(y(x),x)=0,y(x), singsol=all)
```

$$y(x) = \frac{\sqrt{-x^6 - 6x^5 + x^4 c_1 + (8c_1 + 100)x^3 + (24c_1 + 345)x^2 + (32c_1 + 474)x + 16c_1 + 239}}{(1+x)^3}$$

$$y(x) = -\frac{\sqrt{-x^6 - 6x^5 + x^4 c_1 + (8c_1 + 100)x^3 + (24c_1 + 345)x^2 + (32c_1 + 474)x + 16c_1 + 239}}{(1+x)^3}$$

✓ Solution by Mathematica

Time used: 5.501 (sec). Leaf size: 126

```
DSolve[(x+4)*(y[x]^2+1) + y[x]*(x^2+3*x+2)*y'[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow -\frac{\sqrt{-(x+1)^6 + e^{2c_1}(x+2)^4}}{(x+1)^3}$$

$$y(x) \rightarrow \frac{\sqrt{-(x+1)^6 + e^{2c_1}(x+2)^4}}{(x+1)^3}$$

$$y(x) \rightarrow -i$$

$$y(x) \rightarrow i$$

$$y(x) \rightarrow \frac{(x+1)^3}{\sqrt{-(x+1)^6}}$$

$$y(x) \rightarrow \frac{\sqrt{-(x+1)^6}}{(x+1)^3}$$

4.8 problem 8

4.8.1	Solving as linear ode	544
4.8.2	Solving as homogeneousTypeD2 ode	546
4.8.3	Solving as first order ode lie symmetry lookup ode	547
4.8.4	Solving as exact ode	551
4.8.5	Maple step by step solution	556

Internal problem ID [11621]

Internal file name [OUTPUT/10603_Saturday_May_27_2023_03_01_19_AM_16407112/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 2, section 2.2 (Separable equations). Exercises page 47

Problem number: 8.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"linear"**, **"homogeneousTypeD2"**, **"exactWithIntegrationFactor"**, **"first_order_ode_lie_symmetry_lookup"**

Maple gives the following as the ode type

`[_linear]`

$$y - y'x = -x$$

4.8.1 Solving as linear ode

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = -\frac{1}{x}$$

$$q(x) = 1$$

Hence the ode is

$$y' - \frac{y}{x} = 1$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int -\frac{1}{x} dx} \\ &= \frac{1}{x}\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu y) &= \mu \\ \frac{d}{dx}\left(\frac{y}{x}\right) &= \frac{1}{x} \\ d\left(\frac{y}{x}\right) &= \frac{1}{x} dx\end{aligned}$$

Integrating gives

$$\begin{aligned}\frac{y}{x} &= \int \frac{1}{x} dx \\ \frac{y}{x} &= \ln(x) + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = \frac{1}{x}$ results in

$$y = x \ln(x) + c_1 x$$

which simplifies to

$$y = x(\ln(x) + c_1)$$

Summary

The solution(s) found are the following

$$y = x(\ln(x) + c_1) \tag{1}$$

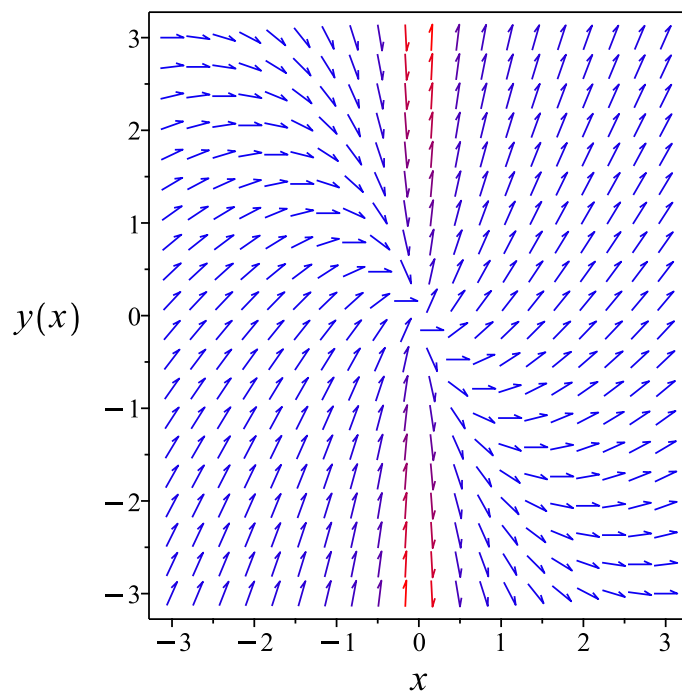


Figure 99: Slope field plot

Verification of solutions

$$y = x(\ln(x) + c_1)$$

Verified OK.

4.8.2 Solving as homogeneousTypeD2 ode

Using the change of variables $y = u(x)x$ on the above ode results in new ode in $u(x)$

$$u(x)x - (u'(x)x + u(x))x = -x$$

Integrating both sides gives

$$\begin{aligned} u(x) &= \int \frac{1}{x} dx \\ &= \ln(x) + c_2 \end{aligned}$$

Therefore the solution y is

$$\begin{aligned} y &= ux \\ &= x(\ln(x) + c_2) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = x(\ln(x) + c_2) \quad (1)$$

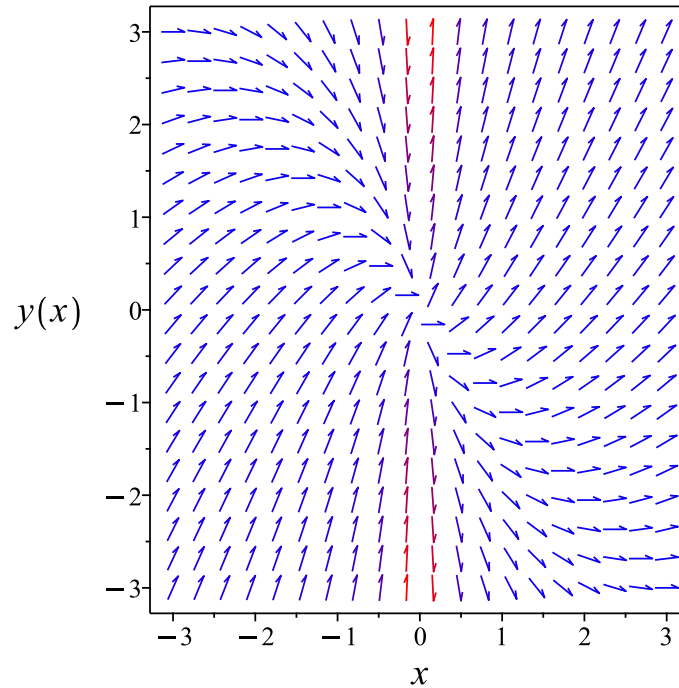


Figure 100: Slope field plot

Verification of solutions

$$y = x(\ln(x) + c_2)$$

Verified OK.

4.8.3 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = \frac{y+x}{x}$$
$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 91: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= x\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{x} dy \end{aligned}$$

Which results in

$$S = \frac{y}{x}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = \frac{y + x}{x}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= -\frac{y}{x^2} \\ S_y &= \frac{1}{x} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = \frac{1}{x} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = \frac{1}{R}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = \ln(R) + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$\frac{y}{x} = \ln(x) + c_1$$

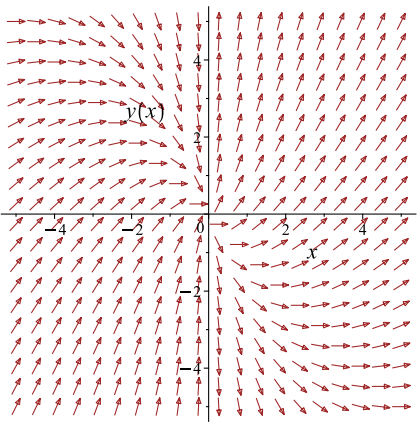
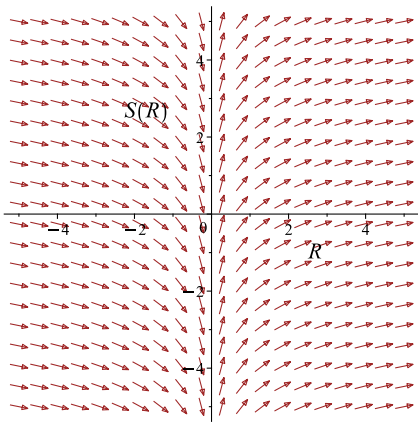
Which simplifies to

$$\frac{y}{x} = \ln(x) + c_1$$

Which gives

$$y = x(\ln(x) + c_1)$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = \frac{y+x}{x}$ 	$R = x$ $S = \frac{y}{x}$	$\frac{dS}{dR} = \frac{1}{R}$ 

Summary

The solution(s) found are the following

$$y = x(\ln(x) + c_1) \quad (1)$$

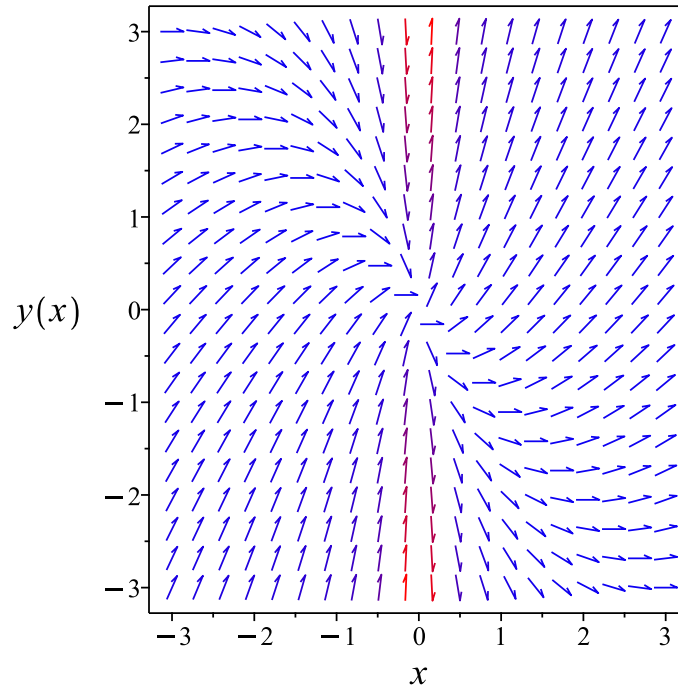


Figure 101: Slope field plot

Verification of solutions

$$y = x(\ln(x) + c_1)$$

Verified OK.

4.8.4 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \tag{1A}$$

Therefore

$$\begin{aligned}(-x) dy &= (-y - x) dx \\ (y + x) dx + (-x) dy &= 0\end{aligned} \tag{2A}$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= y + x \\ N(x, y) &= -x\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(y + x) \\ &= 1\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(-x) \\ &= -1\end{aligned}$$

Since $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$\begin{aligned} A &= \frac{1}{N} \left(\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} \right) \\ &= -\frac{1}{x} ((1) - (-1)) \\ &= -\frac{2}{x} \end{aligned}$$

Since A does not depend on y , then it can be used to find an integrating factor. The integrating factor μ is

$$\begin{aligned} \mu &= e^{\int A \, dx} \\ &= e^{\int -\frac{2}{x} \, dx} \end{aligned}$$

The result of integrating gives

$$\begin{aligned} \mu &= e^{-2 \ln(x)} \\ &= \frac{1}{x^2} \end{aligned}$$

M and N are multiplied by this integrating factor, giving new M and new N which are called \bar{M} and \bar{N} for now so not to confuse them with the original M and N .

$$\begin{aligned} \bar{M} &= \mu M \\ &= \frac{1}{x^2} (y + x) \\ &= \frac{y + x}{x^2} \end{aligned}$$

And

$$\begin{aligned} \bar{N} &= \mu N \\ &= \frac{1}{x^2} (-x) \\ &= -\frac{1}{x} \end{aligned}$$

Now a modified ODE is obtained from the original ODE, which is exact and can be solved. The modified ODE is

$$\begin{aligned} \bar{M} + \bar{N} \frac{dy}{dx} &= 0 \\ \left(\frac{y + x}{x^2} \right) + \left(-\frac{1}{x} \right) \frac{dy}{dx} &= 0 \end{aligned}$$

The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = \overline{M} \quad (1)$$

$$\frac{\partial \phi}{\partial y} = \overline{N} \quad (2)$$

Integrating (1) w.r.t. x gives

$$\begin{aligned} \int \frac{\partial \phi}{\partial x} dx &= \int \overline{M} dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int \frac{y+x}{x^2} dx \\ \phi &= -\frac{y}{x} + \ln(x) + f(y) \end{aligned} \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = -\frac{1}{x} + f'(y) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = -\frac{1}{x}$. Therefore equation (4) becomes

$$-\frac{1}{x} = -\frac{1}{x} + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 0$$

Therefore

$$f(y) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(y)$ into equation (3) gives ϕ

$$\phi = -\frac{y}{x} + \ln(x) + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -\frac{y}{x} + \ln(x)$$

The solution becomes

$$y = x(\ln(x) - c_1)$$

Summary

The solution(s) found are the following

$$y = x(\ln(x) - c_1) \tag{1}$$

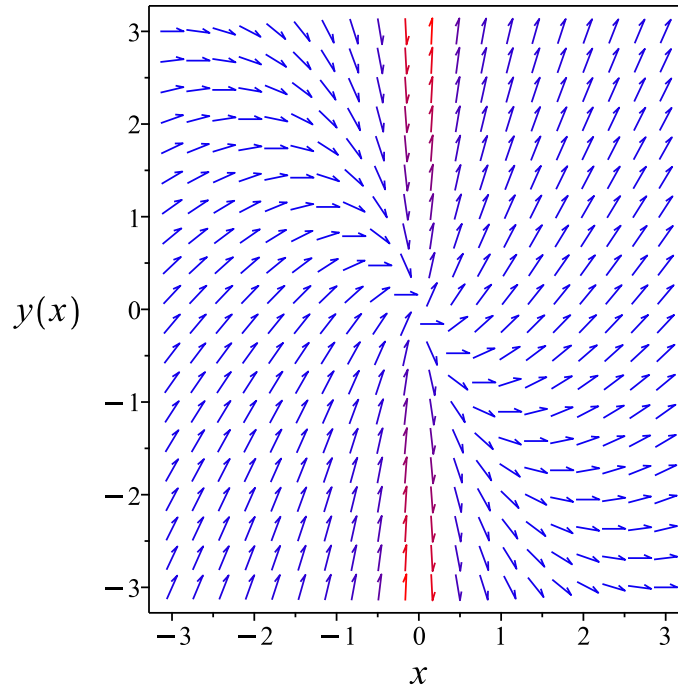


Figure 102: Slope field plot

Verification of solutions

$$y = x(\ln(x) - c_1)$$

Verified OK.

4.8.5 Maple step by step solution

Let's solve

$$y - y'x = -x$$

- Highest derivative means the order of the ODE is 1

$$y'$$

- Isolate the derivative

$$y' = \frac{y}{x} + 1$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE

$$y' - \frac{y}{x} = 1$$

- The ODE is linear; multiply by an integrating factor $\mu(x)$

$$\mu(x) \left(y' - \frac{y}{x} \right) = \mu(x)$$

- Assume the lhs of the ODE is the total derivative $\frac{d}{dx}(\mu(x)y)$

$$\mu(x) \left(y' - \frac{y}{x} \right) = \mu'(x)y + \mu(x)y'$$

- Isolate $\mu'(x)$

$$\mu'(x) = -\frac{\mu(x)}{x}$$

- Solve to find the integrating factor

$$\mu(x) = \frac{1}{x}$$

- Integrate both sides with respect to x

$$\int \left(\frac{d}{dx}(\mu(x)y) \right) dx = \int \mu(x) dx + c_1$$

- Evaluate the integral on the lhs

$$\mu(x)y = \int \mu(x) dx + c_1$$

- Solve for y

$$y = \frac{\int \mu(x) dx + c_1}{\mu(x)}$$

- Substitute $\mu(x) = \frac{1}{x}$

$$y = x \left(\int \frac{1}{x} dx + c_1 \right)$$

- Evaluate the integrals on the rhs

$$y = x(\ln(x) + c_1)$$

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
<- 1st order linear successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 10

```
dsolve((x+y(x))- x*diff(y(x),x)=0,y(x), singsol=all)
```

$$y(x) = (\ln(x) + c_1) x$$

✓ Solution by Mathematica

Time used: 0.037 (sec). Leaf size: 12

```
DSolve[(x+y[x])- x*y'[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow x(\log(x) + c_1)$$

4.9 problem 9

4.9.1	Solving as homogeneousTypeD2 ode	558
4.9.2	Solving as first order ode lie symmetry calculated ode	560
4.9.3	Solving as exact ode	566

Internal problem ID [11622]

Internal file name [OUTPUT/10604_Saturday_May_27_2023_03_01_21_AM_5585912/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 2, section 2.2 (Separable equations). Exercises page 47

Problem number: 9.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**homogeneousTypeD2**", "**exactWithIntegrationFactor**", "**first_order_ode_lie_symmetry_calculated**"

Maple gives the following as the ode type

```
[[_homogeneous, `class A`], _rational, [_Abel, `2nd type`, `class B`]]
```

$$2yx + 3y^2 - (2yx + x^2) y' = 0$$

4.9.1 Solving as homogeneousTypeD2 ode

Using the change of variables $y = u(x)x$ on the above ode results in new ode in $u(x)$

$$2u(x)x^2 + 3u(x)^2x^2 - (2u(x)x^2 + x^2)(u'(x)x + u(x)) = 0$$

In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= \frac{u(u+1)}{(2u+1)x} \end{aligned}$$

Where $f(x) = \frac{1}{x}$ and $g(u) = \frac{u(u+1)}{2u+1}$. Integrating both sides gives

$$\frac{1}{\frac{u(u+1)}{2u+1}} du = \frac{1}{x} dx$$
$$\int \frac{1}{\frac{u(u+1)}{2u+1}} du = \int \frac{1}{x} dx$$
$$\ln(u(u+1)) = \ln(x) + c_2$$

Raising both side to exponential gives

$$u(u+1) = e^{\ln(x)+c_2}$$

Which simplifies to

$$u(u+1) = c_3 x$$

Which simplifies to

$$u(x)(u(x)+1) = c_3 e^{c_2} x$$

The solution is

$$u(x)(u(x)+1) = c_3 e^{c_2} x$$

Replacing $u(x)$ in the above solution by $\frac{y}{x}$ results in the solution for y in implicit form

$$\frac{y\left(\frac{y}{x} + 1\right)}{x} = c_3 e^{c_2} x$$
$$\frac{y(y+x)}{x^2} = c_3 e^{c_2} x$$

Summary

The solution(s) found are the following

$$\frac{y(y+x)}{x^2} = c_3 e^{c_2} x \quad (1)$$

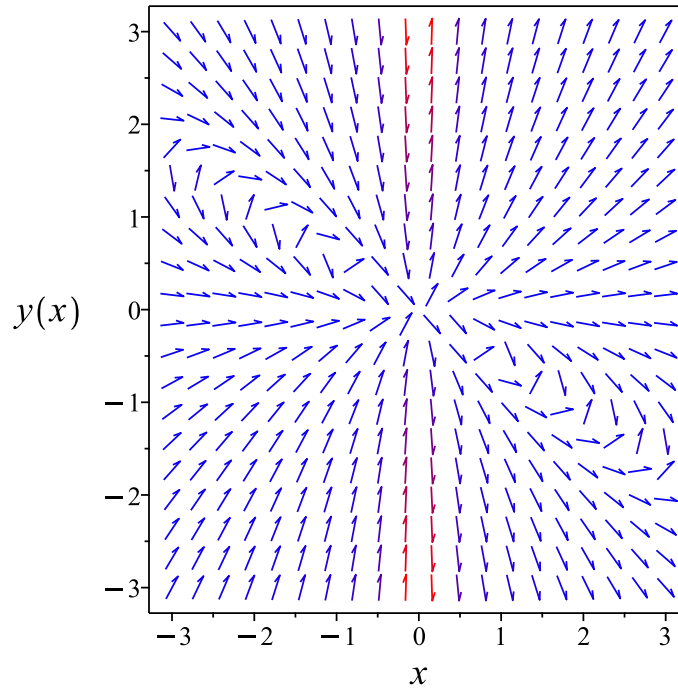


Figure 103: Slope field plot

Verification of solutions

$$\frac{y(y+x)}{x^2} = c_3 e^{c_2 x}$$

Verified OK.

4.9.2 Solving as first order ode lie symmetry calculated ode

Writing the ode as

$$y' = \frac{y(2x+3y)}{x(x+2y)}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is not in the lookup table. To determine ξ, η then (A) is solved using ansatz. Making bivariate polynomials of degree 1 to use as anstaz gives

$$\xi = xa_2 + ya_3 + a_1 \quad (1\text{E})$$

$$\eta = xb_2 + yb_3 + b_1 \quad (2\text{E})$$

Where the unknown coefficients are

$$\{a_1, a_2, a_3, b_1, b_2, b_3\}$$

Substituting equations (1E,2E) and ω into (A) gives

$$\begin{aligned} b_2 + \frac{y(2x+3y)(b_3-a_2)}{x(x+2y)} - \frac{y^2(2x+3y)^2 a_3}{x^2(x+2y)^2} \\ - \left(\frac{2y}{x(x+2y)} - \frac{y(2x+3y)}{x^2(x+2y)} - \frac{y(2x+3y)}{x(x+2y)^2} \right) (xa_2 + ya_3 + a_1) \\ - \left(\frac{2x+3y}{x(x+2y)} + \frac{3y}{x(x+2y)} - \frac{2y(2x+3y)}{x(x+2y)^2} \right) (xb_2 + yb_3 + b_1) = 0 \end{aligned} \quad (5E)$$

Putting the above in normal form gives

$$\frac{x^4 b_2 + 2x^3 y b_2 + x^2 y^2 a_2 + 2x^2 y^2 a_3 + 2x^2 y^2 b_2 - x^2 y^2 b_3 + 6x y^3 a_3 + 3y^4 a_3 + 2x^3 b_1 - 2x^2 y a_1 + 6x^2 y b_1 - \dots}{x^2 (x+2y)^2} = 0$$

Setting the numerator to zero gives

$$\begin{aligned} -x^4 b_2 - 2x^3 y b_2 - x^2 y^2 a_2 - 2x^2 y^2 a_3 - 2x^2 y^2 b_2 + x^2 y^2 b_3 - 6x y^3 a_3 \\ - 3y^4 a_3 - 2x^3 b_1 + 2x^2 y a_1 - 6x^2 y b_1 + 6x y^2 a_1 - 6x y^2 b_1 + 6y^3 a_1 = 0 \end{aligned} \quad (6E)$$

Looking at the above PDE shows the following are all the terms with $\{x, y\}$ in them.

$$\{x, y\}$$

The following substitution is now made to be able to collect on all terms with $\{x, y\}$ in them

$$\{x = v_1, y = v_2\}$$

The above PDE (6E) now becomes

$$\begin{aligned} -a_2 v_1^2 v_2^2 - 2a_3 v_1^2 v_2^2 - 6a_3 v_1 v_2^3 - 3a_3 v_2^4 - b_2 v_1^4 - 2b_2 v_1^3 v_2 - 2b_2 v_1^2 v_2^2 \\ + b_3 v_1^2 v_2^2 + 2a_1 v_1^2 v_2 + 6a_1 v_1 v_2^2 + 6a_1 v_2^3 - 2b_1 v_1^3 - 6b_1 v_1^2 v_2 - 6b_1 v_1 v_2^2 = 0 \end{aligned} \quad (7E)$$

Collecting the above on the terms v_i introduced, and these are

$$\{v_1, v_2\}$$

Equation (7E) now becomes

$$\begin{aligned} -b_2v_1^4 - 2b_2v_1^3v_2 - 2b_1v_1^3 + (-a_2 - 2a_3 - 2b_2 + b_3)v_1^2v_2^2 \\ + (2a_1 - 6b_1)v_1^2v_2 - 6a_3v_1v_2^3 + (6a_1 - 6b_1)v_1v_2^2 - 3a_3v_2^4 + 6a_1v_2^3 = 0 \end{aligned} \quad (8E)$$

Setting each coefficients in (8E) to zero gives the following equations to solve

$$\begin{aligned} 6a_1 &= 0 \\ -6a_3 &= 0 \\ -3a_3 &= 0 \\ -2b_1 &= 0 \\ -2b_2 &= 0 \\ -b_2 &= 0 \\ 2a_1 - 6b_1 &= 0 \\ 6a_1 - 6b_1 &= 0 \\ -a_2 - 2a_3 - 2b_2 + b_3 &= 0 \end{aligned}$$

Solving the above equations for the unknowns gives

$$\begin{aligned} a_1 &= 0 \\ a_2 &= b_3 \\ a_3 &= 0 \\ b_1 &= 0 \\ b_2 &= 0 \\ b_3 &= b_3 \end{aligned}$$

Substituting the above solution in the anstaz (1E,2E) (using 1 as arbitrary value for any unknown in the RHS) gives

$$\begin{aligned} \xi &= x \\ \eta &= y \end{aligned}$$

Shifting is now applied to make $\xi = 0$ in order to simplify the rest of the computation

$$\begin{aligned}\eta &= \eta - \omega(x, y) \xi \\ &= y - \left(\frac{y(2x + 3y)}{x(x + 2y)} \right) (x) \\ &= \frac{-xy - y^2}{x + 2y} \\ \xi &= 0\end{aligned}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \quad (1)$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y} \right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned}S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{-xy - y^2}{x + 2y}} dy\end{aligned}$$

Which results in

$$S = -\ln(y(y + x))$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = \frac{y(2x + 3y)}{x(x + 2y)}$$

Evaluating all the partial derivatives gives

$$\begin{aligned}R_x &= 1 \\R_y &= 0 \\S_x &= -\frac{1}{y+x} \\S_y &= \frac{-x-2y}{y(y+x)}\end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = -\frac{3}{x} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = -\frac{3}{R}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = -3 \ln(R) + c_1 \quad (4)$$

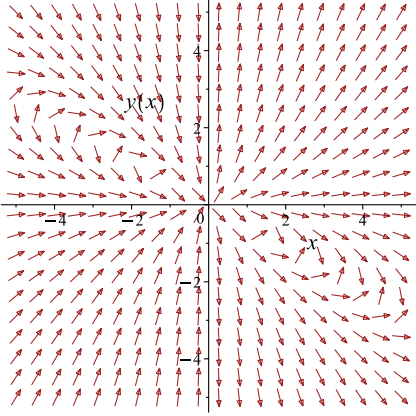
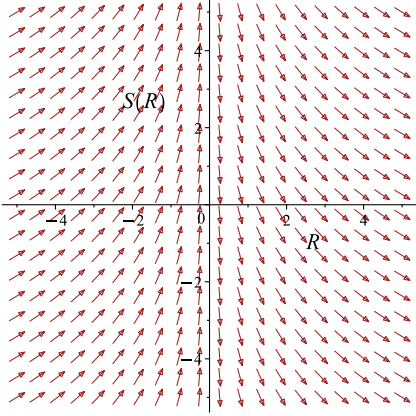
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$-\ln(y) - \ln(y+x) = -3 \ln(x) + c_1$$

Which simplifies to

$$-\ln(y) - \ln(y+x) = -3 \ln(x) + c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = \frac{y(2x+3y)}{x(x+2y)}$ 	$R = x$ $S = -\ln(y) - \ln(y+x)$	$\frac{dS}{dR} = -\frac{3}{R}$ 

Summary

The solution(s) found are the following

$$-\ln(y) - \ln(y+x) = -3\ln(x) + c_1 \tag{1}$$

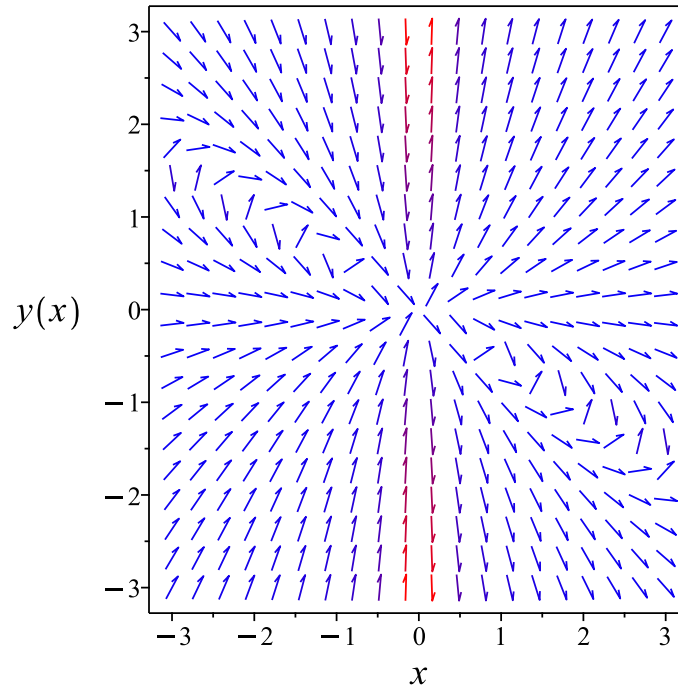


Figure 104: Slope field plot

Verification of solutions

$$-\ln(y) - \ln(y+x) = -3\ln(x) + c_1$$

Verified OK.

4.9.3 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \tag{1A}$$

Therefore

$$\begin{aligned}(-x^2 - 2xy) dy &= (-2xy - 3y^2) dx \\ (2xy + 3y^2) dx + (-x^2 - 2xy) dy &= 0\end{aligned} \tag{2A}$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= 2xy + 3y^2 \\ N(x, y) &= -x^2 - 2xy\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(2xy + 3y^2) \\ &= 6y + 2x\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(-x^2 - 2xy) \\ &= -2x - 2y\end{aligned}$$

Since $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$\begin{aligned} A &= \frac{1}{N} \left(\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} \right) \\ &= -\frac{1}{x(x+2y)} ((6y+2x) - (-2x-2y)) \\ &= -\frac{4}{x} \end{aligned}$$

Since A does not depend on y , then it can be used to find an integrating factor. The integrating factor μ is

$$\begin{aligned} \mu &= e^{\int A \, dx} \\ &= e^{\int -\frac{4}{x} \, dx} \end{aligned}$$

The result of integrating gives

$$\begin{aligned} \mu &= e^{-4 \ln(x)} \\ &= \frac{1}{x^4} \end{aligned}$$

M and N are multiplied by this integrating factor, giving new M and new N which are called \bar{M} and \bar{N} for now so not to confuse them with the original M and N .

$$\begin{aligned} \bar{M} &= \mu M \\ &= \frac{1}{x^4} (2xy + 3y^2) \\ &= \frac{y(2x + 3y)}{x^4} \end{aligned}$$

And

$$\begin{aligned} \bar{N} &= \mu N \\ &= \frac{1}{x^4} (-x^2 - 2xy) \\ &= \frac{-x - 2y}{x^3} \end{aligned}$$

Now a modified ODE is obtained from the original ODE, which is exact and can be solved. The modified ODE is

$$\begin{aligned} \bar{M} + \bar{N} \frac{dy}{dx} &= 0 \\ \left(\frac{y(2x + 3y)}{x^4} \right) + \left(\frac{-x - 2y}{x^3} \right) \frac{dy}{dx} &= 0 \end{aligned}$$

The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = \bar{M} \quad (1)$$

$$\frac{\partial \phi}{\partial y} = \bar{N} \quad (2)$$

Integrating (1) w.r.t. x gives

$$\begin{aligned} \int \frac{\partial \phi}{\partial x} dx &= \int \bar{M} dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int \frac{y(2x + 3y)}{x^4} dx \\ \phi &= -\frac{y(y + x)}{x^3} + f(y) \end{aligned} \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\begin{aligned} \frac{\partial \phi}{\partial y} &= -\frac{y + x}{x^3} - \frac{y}{x^3} + f'(y) \\ &= \frac{-x - 2y}{x^3} + f'(y) \end{aligned} \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = \frac{-x - 2y}{x^3}$. Therefore equation (4) becomes

$$\frac{-x - 2y}{x^3} = \frac{-x - 2y}{x^3} + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 0$$

Therefore

$$f(y) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(y)$ into equation (3) gives ϕ

$$\phi = -\frac{y(y + x)}{x^3} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -\frac{y(y+x)}{x^3}$$

Summary

The solution(s) found are the following

$$-\frac{y(y+x)}{x^3} = c_1 \tag{1}$$

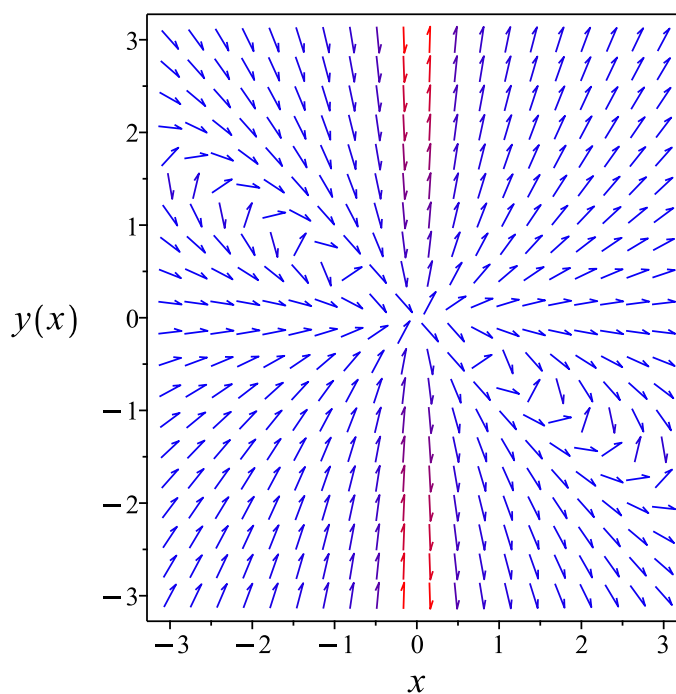


Figure 105: Slope field plot

Verification of solutions

$$-\frac{y(y+x)}{x^3} = c_1$$

Verified OK.

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
trying Bernoulli  
trying separable  
trying inverse linear  
trying homogeneous types:  
trying homogeneous D  
<- homogeneous successful`
```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 33

```
dsolve((2*x*y(x)+3*y(x)^2)- (2*x*y(x)+x^2)*diff(y(x),x)=0,y(x), singsol=all)
```

$$y(x) = -\frac{(1 + \sqrt{4c_1x + 1})x}{2}$$
$$y(x) = \frac{(-1 + \sqrt{4c_1x + 1})x}{2}$$

✓ Solution by Mathematica

Time used: 0.618 (sec). Leaf size: 61

```
DSolve[(2*x*y[x]+3*y[x]^2)- (2*x*y[x]+x^2)*y'[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow -\frac{1}{2}x(1 + \sqrt{1 + 4e^{c_1x}})$$
$$y(x) \rightarrow \frac{1}{2}x(-1 + \sqrt{1 + 4e^{c_1x}})$$
$$y(x) \rightarrow 0$$
$$y(x) \rightarrow -x$$

4.10 problem 10

4.10.1 Solving as homogeneousTypeD2 ode 572

4.10.2 Solving as first order ode lie symmetry calculated ode 574

Internal problem ID [11623]

Internal file name [OUTPUT/10605_Saturday_May_27_2023_03_05_11_AM_66707145/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 2, section 2.2 (Separable equations). Exercises page 47

Problem number: 10.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**homogeneousTypeD2**", "**first_order_ode_lie_symmetry_calculated**"

Maple gives the following as the ode type

```
[[_homogeneous, `class A`], _rational, _dAlembert]
```

$$v^3 + (u^3 - uv^2) v' = 0$$

4.10.1 Solving as homogeneousTypeD2 ode

Using the change of variables $v = u(u)$ on the above ode results in new ode in $u(u)$

$$u(u)^3 u^3 + (u^3 - u^3 u(u)^2) (u'(u) u + u(u)) = 0$$

In canonical form the ODE is

$$\begin{aligned} u' &= F(u, u) \\ &= f(u)g(u) \\ &= \frac{u}{(u^2 - 1)u} \end{aligned}$$

Where $f(u) = \frac{1}{u}$ and $g(u) = \frac{u}{u^2-1}$. Integrating both sides gives

$$\frac{1}{\frac{u}{u^2-1}} du = \frac{1}{u} du$$

$$\int \frac{1}{\frac{u}{u^2-1}} du = \int \frac{1}{u} du$$

$$\frac{u^2}{2} - \ln(u) = \ln(u) + c_2$$

The solution is

$$\frac{u(u)^2}{2} - \ln(u(u)) - \ln(u) - c_2 = 0$$

Replacing $u(u)$ in the above solution by $\frac{v}{u}$ results in the solution for v in implicit form

$$\frac{v^2}{2u^2} - \ln\left(\frac{v}{u}\right) - \ln(u) - c_2 = 0$$

$$\frac{v^2}{2u^2} - \ln\left(\frac{v}{u}\right) - \ln(u) - c_2 = 0$$

Summary

The solution(s) found are the following

$$\frac{v^2}{2u^2} - \ln\left(\frac{v}{u}\right) - \ln(u) - c_2 = 0 \tag{1}$$

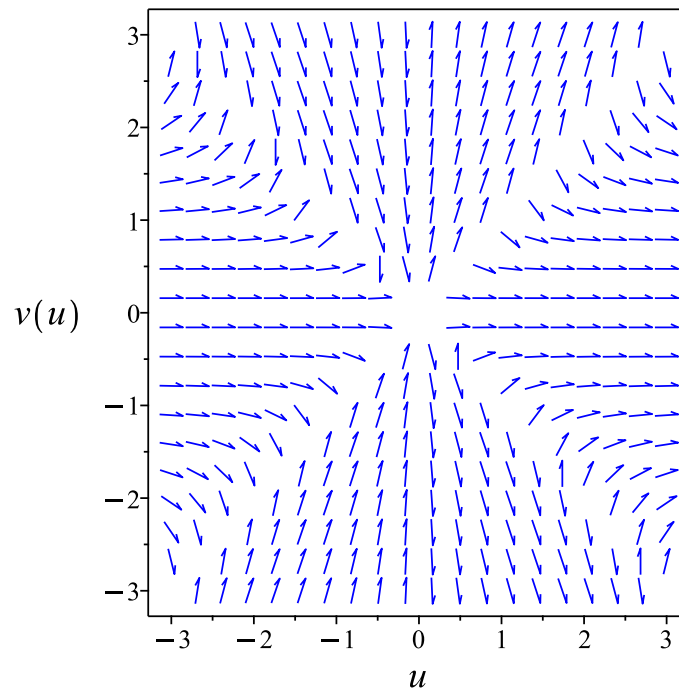


Figure 106: Slope field plot

Verification of solutions

$$\frac{v^2}{2u^2} - \ln\left(\frac{v}{u}\right) - \ln(u) - c_2 = 0$$

Verified OK.

4.10.2 Solving as first order ode lie symmetry calculated ode

Writing the ode as

$$v' = \frac{v^3}{u(-u^2 + v^2)}$$
$$v' = \omega(u, v)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_u + \omega(\eta_v - \xi_u) - \omega^2 \xi_v - \omega_u \xi - \omega_v \eta = 0 \quad (\text{A})$$

The type of this ode is not in the lookup table. To determine ξ, η then (A) is solved using ansatz. Making bivariate polynomials of degree 1 to use as anstaz gives

$$\xi = ua_2 + va_3 + a_1 \quad (\text{1E})$$

$$\eta = ub_2 + vb_3 + b_1 \quad (\text{2E})$$

Where the unknown coefficients are

$$\{a_1, a_2, a_3, b_1, b_2, b_3\}$$

Substituting equations (1E,2E) and ω into (A) gives

$$b_2 + \frac{v^3(b_3 - a_2)}{u(-u^2 + v^2)} - \frac{v^6 a_3}{u^2(-u^2 + v^2)^2}$$
$$- \left(-\frac{v^3}{u^2(-u^2 + v^2)} + \frac{2v^3}{(-u^2 + v^2)^2} \right) (ua_2 + va_3 + a_1) \quad (\text{5E})$$
$$- \left(\frac{3v^2}{u(-u^2 + v^2)} - \frac{2v^4}{u(-u^2 + v^2)^2} \right) (ub_2 + vb_3 + b_1) = 0$$

Putting the above in normal form gives

$$\frac{u^6 b_2 + u^4 v^2 b_2 - 2u^3 v^3 a_2 + 2u^3 v^3 b_3 - 3u^2 v^4 a_3 + 3u^3 v^2 b_1 - 3u^2 v^3 a_1 - u v^4 b_1 + v^5 a_1}{u^2 (u^2 - v^2)^2} = 0$$

Setting the numerator to zero gives

$$u^6 b_2 + u^4 v^2 b_2 - 2u^3 v^3 a_2 + 2u^3 v^3 b_3 - 3u^2 v^4 a_3 + 3u^3 v^2 b_1 - 3u^2 v^3 a_1 - u v^4 b_1 + v^5 a_1 = 0 \quad (6E)$$

Looking at the above PDE shows the following are all the terms with $\{u, v\}$ in them.

$$\{u, v\}$$

The following substitution is now made to be able to collect on all terms with $\{u, v\}$ in them

$$\{u = v_1, v = v_2\}$$

The above PDE (6E) now becomes

$$-2a_2 v_1^3 v_2^3 - 3a_3 v_1^2 v_2^4 + b_2 v_1^6 + b_2 v_1^4 v_2^2 + 2b_3 v_1^3 v_2^3 - 3a_1 v_1^2 v_2^3 + a_1 v_2^5 + 3b_1 v_1^3 v_2^2 - b_1 v_1 v_2^4 = 0 \quad (7E)$$

Collecting the above on the terms v_i introduced, and these are

$$\{v_1, v_2\}$$

Equation (7E) now becomes

$$b_2 v_1^6 + b_2 v_1^4 v_2^2 + (-2a_2 + 2b_3) v_1^3 v_2^3 + 3b_1 v_1^3 v_2^2 - 3a_3 v_1^2 v_2^4 - 3a_1 v_1^2 v_2^3 - b_1 v_1 v_2^4 + a_1 v_2^5 = 0 \quad (8E)$$

Setting each coefficients in (8E) to zero gives the following equations to solve

$$\begin{aligned} a_1 &= 0 \\ b_2 &= 0 \\ -3a_1 &= 0 \\ -3a_3 &= 0 \\ -b_1 &= 0 \\ 3b_1 &= 0 \\ -2a_2 + 2b_3 &= 0 \end{aligned}$$

Solving the above equations for the unknowns gives

$$a_1 = 0$$

$$a_2 = b_3$$

$$a_3 = 0$$

$$b_1 = 0$$

$$b_2 = 0$$

$$b_3 = b_3$$

Substituting the above solution in the anstaz (1E,2E) (using 1 as arbitrary value for any unknown in the RHS) gives

$$\xi = u$$

$$\eta = v$$

Shifting is now applied to make $\xi = 0$ in order to simplify the rest of the computation

$$\begin{aligned} \eta &= \eta - \omega(u, v) \xi \\ &= v - \left(\frac{v^3}{u(-u^2 + v^2)} \right) (u) \\ &= \frac{u^2 v}{u^2 - v^2} \\ \xi &= 0 \end{aligned}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(u, v) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{du}{\xi} = \frac{dv}{\eta} = dS \quad (1)$$

The above comes from the requirements that $(\xi \frac{\partial}{\partial u} + \eta \frac{\partial}{\partial v}) S(u, v) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = u$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{u^2 v}{u^2 - v^2}} dy \end{aligned}$$

Which results in

$$S = -\frac{v^2}{2u^2} + \ln(v)$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_u + \omega(u, v)S_v}{R_u + \omega(u, v)R_v} \quad (2)$$

Where in the above R_u, R_v, S_u, S_v are all partial derivatives and $\omega(u, v)$ is the right hand side of the original ode given by

$$\omega(u, v) = \frac{v^3}{u(-u^2 + v^2)}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_u &= 1 \\ R_v &= 0 \\ S_u &= \frac{v^2}{u^3} \\ S_v &= \frac{u^2 - v^2}{u^2v} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 0 \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for u, v in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 0$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to u, v coordinates. This results in

$$\frac{2 \ln(v) u^2 - v^2}{2u^2} = c_1$$

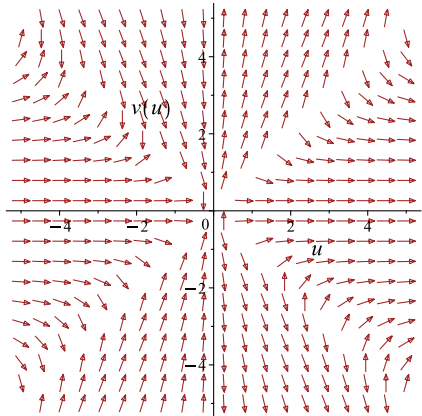
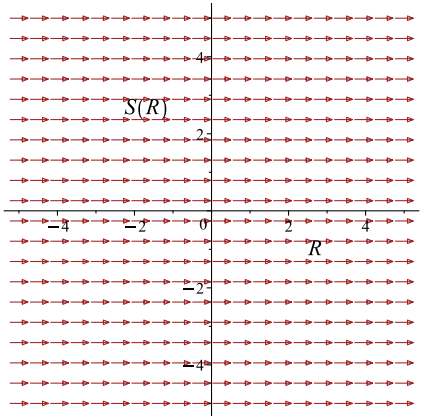
Which simplifies to

$$\frac{2 \ln(v) u^2 - v^2}{2u^2} = c_1$$

Which gives

$$v = e^{-\frac{\text{LambertW}\left(-\frac{e^{2c_1}}{u^2}\right)}{2} + c_1}$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in u, v coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dv}{du} = \frac{v^3}{u(-u^2+v^2)}$ 	$R = u$ $S = \frac{2 \ln(v) u^2 - v^2}{2u^2}$	$\frac{dS}{dR} = 0$ 

Summary

The solution(s) found are the following

$$v = e^{-\frac{\text{LambertW}\left(-\frac{e^{2c_1}}{u^2}\right)}{2} + c_1} \tag{1}$$

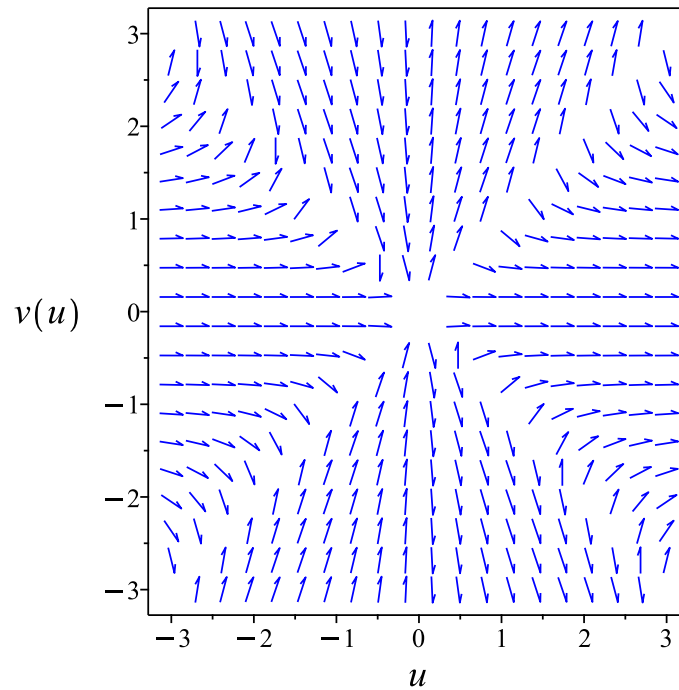


Figure 107: Slope field plot

Verification of solutions

$$v = e^{-\frac{\text{LambertW}\left(-\frac{e^{2c_1}}{u^2}\right)}{2} + c_1}$$

Verified OK.

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
trying separable
trying inverse linear
trying homogeneous types:
trying homogeneous D
<- homogeneous successful`

```

✓ Solution by Maple

Time used: 0.031 (sec). Leaf size: 32

```
dsolve(v(u)^3+ (u^3-u*v(u)^2)*diff(v(u),u)=0,v(u), singsol=all)
```

$$v(u) = \frac{e^{-c_1}}{\sqrt{-\frac{e^{-2c_1}}{u^2 \operatorname{LambertW}\left(-\frac{e^{-2c_1}}{u^2}\right)}}}$$

✓ Solution by Mathematica

Time used: 9.023 (sec). Leaf size: 56

```
DSolve[v[u]^3+ (u^3-u*v[u]^2)*v'[u]==0,v[u],u,IncludeSingularSolutions -> True]
```

$$v(u) \rightarrow -iu \sqrt{W\left(-\frac{e^{-2c_1}}{u^2}\right)}$$

$$v(u) \rightarrow iu \sqrt{W\left(-\frac{e^{-2c_1}}{u^2}\right)}$$

$$v(u) \rightarrow 0$$

4.11 problem 11

- 4.11.1 Solving as homogeneousTypeD ode 581
- 4.11.2 Solving as homogeneousTypeD2 ode 584
- 4.11.3 Solving as first order ode lie symmetry lookup ode 585

Internal problem ID [11624]

Internal file name [OUTPUT/10606_Saturday_May_27_2023_03_05_11_AM_67096172/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.2 (Separable equations). Exercises page 47

Problem number: 11.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"homogeneousTypeD", "homogeneousTypeD2", "first_order_ode_lie_symmetry_lookup"**

Maple gives the following as the ode type

```
[[_homogeneous, `class A`], _dAlembert]
```

$$x \tan\left(\frac{y}{x}\right) + y - y'x = 0$$

4.11.1 Solving as homogeneousTypeD ode

Writing the ode as

$$y' = \tan\left(\frac{y}{x}\right) + \frac{y}{x} \tag{A}$$

The given ode has the form

$$y' = \frac{y}{x} + g(x) f\left(b\frac{y}{x}\right)^{\frac{n}{m}} \tag{1}$$

Where b is scalar and $g(x)$ is function of x and n, m are integers. The solution is given in Kamke page 20. Using the substitution $y(x) = u(x)x$ then

$$\frac{dy}{dx} = \frac{du}{dx}x + u$$

Hence the given ode becomes

$$\begin{aligned}\frac{du}{dx}x + u &= u + g(x) f(bu)^{\frac{n}{m}} \\ u' &= \frac{1}{x}g(x) f(bu)^{\frac{n}{m}}\end{aligned}\tag{2}$$

The above ode is always separable. This is easily solved for u assuming the integration can be resolved, and then the solution to the original ode becomes $y = ux$. Comparing the given ode (A) with the form (1) shows that

$$\begin{aligned}g(x) &= 1 \\ b &= 1 \\ f\left(\frac{bx}{y}\right) &= \tan\left(\frac{y}{x}\right)\end{aligned}$$

Substituting the above in (2) results in the $u(x)$ ode as

$$u'(x) = \frac{\tan(u(x))}{x}$$

Which is now solved as separable In canonical form the ODE is

$$\begin{aligned}u' &= F(x, u) \\ &= f(x)g(u) \\ &= \frac{\tan(u)}{x}\end{aligned}$$

Where $f(x) = \frac{1}{x}$ and $g(u) = \tan(u)$. Integrating both sides gives

$$\begin{aligned}\frac{1}{\tan(u)} du &= \frac{1}{x} dx \\ \int \frac{1}{\tan(u)} du &= \int \frac{1}{x} dx \\ \ln(\sin(u)) &= \ln(x) + c_1\end{aligned}$$

Raising both side to exponential gives

$$\sin(u) = e^{\ln(x)+c_1}$$

Which simplifies to

$$\sin(u) = c_2x$$

Therefore the solution is

$$\begin{aligned}y &= ux \\ &= x \arcsin (c_2 x e^{c_1})\end{aligned}$$

Summary

The solution(s) found are the following

$$y = x \arcsin (c_2 x e^{c_1}) \tag{1}$$

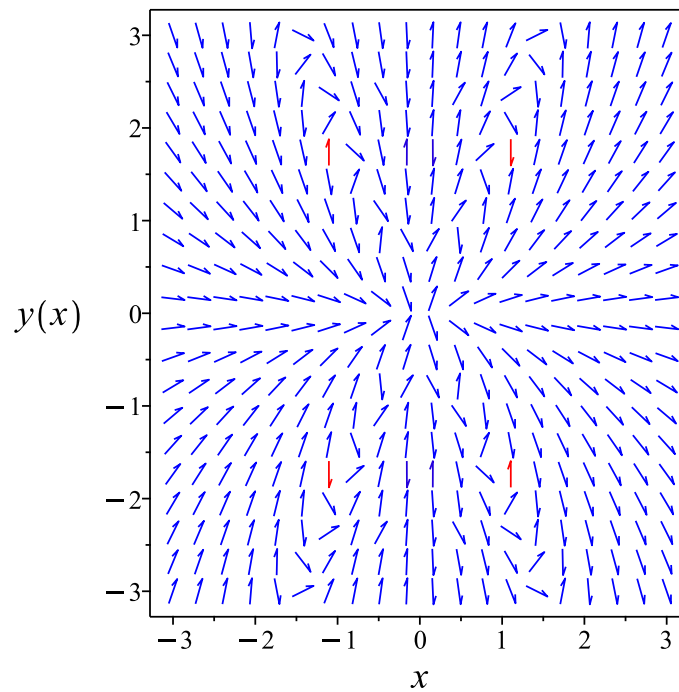


Figure 108: Slope field plot

Verification of solutions

$$y = x \arcsin (c_2 x e^{c_1})$$

Verified OK.

4.11.2 Solving as homogeneous Type D2 ode

Using the change of variables $y = u(x)x$ on the above ode results in new ode in $u(x)$

$$x \tan(u(x)) + u(x)x - (u'(x)x + u(x))x = 0$$

In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= \frac{\tan(u)}{x} \end{aligned}$$

Where $f(x) = \frac{1}{x}$ and $g(u) = \tan(u)$. Integrating both sides gives

$$\begin{aligned} \frac{1}{\tan(u)} du &= \frac{1}{x} dx \\ \int \frac{1}{\tan(u)} du &= \int \frac{1}{x} dx \\ \ln(\sin(u)) &= \ln(x) + c_2 \end{aligned}$$

Raising both side to exponential gives

$$\sin(u) = e^{\ln(x)+c_2}$$

Which simplifies to

$$\sin(u) = c_3 x$$

Therefore the solution y is

$$\begin{aligned} y &= xu \\ &= x \arcsin(c_3 e^{c_2} x) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = x \arcsin(c_3 e^{c_2} x) \tag{1}$$

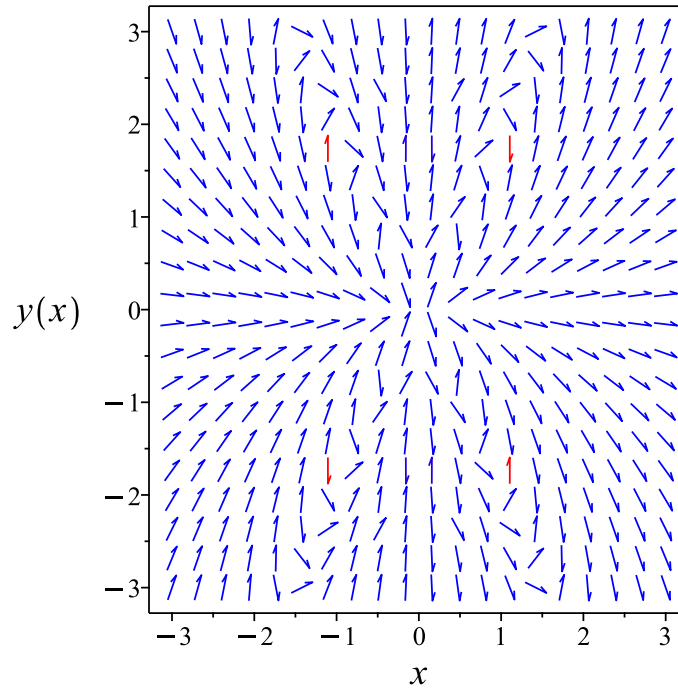


Figure 109: Slope field plot

Verification of solutions

$$y = x \arcsin (c_3 e^{c_2 x})$$

Verified OK.

4.11.3 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = \frac{x \tan \left(\frac{y}{x} \right) + y}{x}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \tag{A}$$

The type of this ode is known. It is of type **homogeneous Type D**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 94: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= x^2 \\ \eta(x, y) &= xy\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Therefore

$$\begin{aligned}\frac{dy}{dx} &= \frac{\eta}{\xi} \\ &= \frac{xy}{x^2} \\ &= \frac{y}{x}\end{aligned}$$

This is easily solved to give

$$y = c_1 x$$

Where now the coordinate R is taken as the constant of integration. Hence

$$R = \frac{y}{x}$$

And S is found from

$$\begin{aligned}dS &= \frac{dx}{\xi} \\ &= \frac{dx}{x^2}\end{aligned}$$

Integrating gives

$$\begin{aligned}S &= \int \frac{dx}{T} \\ &= -\frac{1}{x}\end{aligned}$$

Where the constant of integration is set to zero as we just need one solution. Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = \frac{x \tan\left(\frac{y}{x}\right) + y}{x}$$

Evaluating all the partial derivatives gives

$$\begin{aligned}R_x &= -\frac{y}{x^2} \\ R_y &= \frac{1}{x} \\ S_x &= \frac{1}{x^2} \\ S_y &= 0\end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = \frac{\cot\left(\frac{y}{x}\right)}{x} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = -\cot(R) S(R)$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = \frac{c_1}{\sin(R)} \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$-\frac{1}{x} = \frac{c_1}{\sin\left(\frac{y}{x}\right)}$$

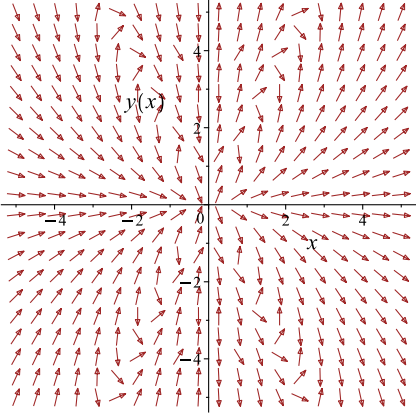
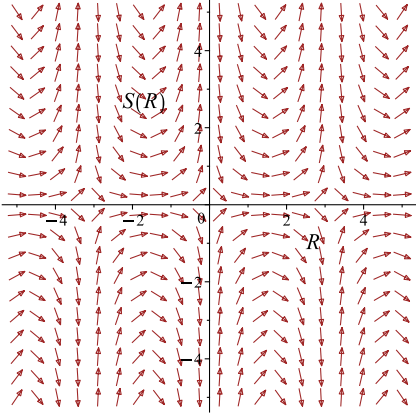
Which simplifies to

$$-\frac{1}{x} = \frac{c_1}{\sin\left(\frac{y}{x}\right)}$$

Which gives

$$y = -\arcsin(c_1 x) x$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = \frac{x \tan\left(\frac{y}{x}\right) + y}{x}$ 	$R = \frac{y}{x}$ $S = -\frac{1}{x}$	$\frac{dS}{dR} = -\cot(R) S(R)$ 

Summary

The solution(s) found are the following

$$y = -\arcsin(c_1 x) x \tag{1}$$

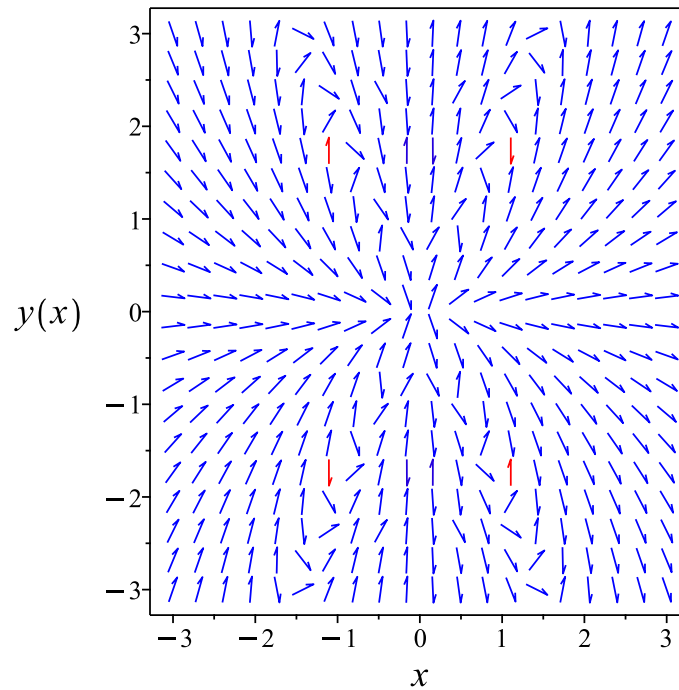


Figure 110: Slope field plot

Verification of solutions

$$y = -\arcsin(c_1 x) x$$

Verified OK.

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
trying separable
trying inverse linear
trying homogeneous types:
trying homogeneous D
<- homogeneous successful`

```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 10

```
dsolve((x*tan(y(x)/x)+y(x))- x*diff(y(x),x)=0,y(x), singsol=all)
```

$$y(x) = \arcsin(c_1 x) x$$

✓ Solution by Mathematica

Time used: 8.002 (sec). Leaf size: 19

```
DSolve[(x*Tan[y[x]/x]+y[x])- x*y'[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow x \arcsin(e^{c_1} x)$$

$$y(x) \rightarrow 0$$

4.12 problem 12

4.12.1 Solving as homogeneousTypeD2 ode	592
4.12.2 Solving as first order ode lie symmetry calculated ode	594
4.12.3 Solving as exact ode	600
4.12.4 Maple step by step solution	604

Internal problem ID [11625]

Internal file name [OUTPUT/10607_Saturday_May_27_2023_03_05_14_AM_78327122/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.2 (Separable equations). Exercises page 47

Problem number: 12.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact", "homogeneousTypeD2", "first_order_ode_lie_symmetry_calculated"

Maple gives the following as the ode type

```
[[_homogeneous, `class A`], _exact, _rational, _dAlembert]
```

$$(2s^2 + 2st + t^2) s' + s^2 + 2st = t^2$$

4.12.1 Solving as homogeneousTypeD2 ode

Using the change of variables $s = u(t)t$ on the above ode results in new ode in $u(t)$

$$(2u(t)^2 t^2 + 2u(t) t^2 + t^2) (u'(t) t + u(t)) + u(t)^2 t^2 + 2u(t) t^2 = t^2$$

In canonical form the ODE is

$$\begin{aligned} u' &= F(t, u) \\ &= f(t)g(u) \\ &= -\frac{2u^3 + 3u^2 + 3u - 1}{t(2u^2 + 2u + 1)} \end{aligned}$$

Where $f(t) = -\frac{1}{t}$ and $g(u) = \frac{2u^3+3u^2+3u-1}{2u^2+2u+1}$. Integrating both sides gives

$$\begin{aligned}\frac{1}{\frac{2u^3+3u^2+3u-1}{2u^2+2u+1}} du &= -\frac{1}{t} dt \\ \int \frac{1}{\frac{2u^3+3u^2+3u-1}{2u^2+2u+1}} du &= \int -\frac{1}{t} dt \\ \frac{\ln(2u^3 + 3u^2 + 3u - 1)}{3} &= -\ln(t) + c_2\end{aligned}$$

Raising both side to exponential gives

$$(2u^3 + 3u^2 + 3u - 1)^{\frac{1}{3}} = e^{-\ln(t)+c_2}$$

Which simplifies to

$$(2u^3 + 3u^2 + 3u - 1)^{\frac{1}{3}} = \frac{c_3}{t}$$

Which simplifies to

$$(2u(t)^3 + 3u(t)^2 + 3u(t) - 1)^{\frac{1}{3}} = \frac{c_3 e^{c_2}}{t}$$

The solution is

$$(2u(t)^3 + 3u(t)^2 + 3u(t) - 1)^{\frac{1}{3}} = \frac{c_3 e^{c_2}}{t}$$

Replacing $u(t)$ in the above solution by $\frac{s}{t}$ results in the solution for s in implicit form

$$\begin{aligned}\left(\frac{2s^3}{t^3} + \frac{3s^2}{t^2} + \frac{3s}{t} - 1\right)^{\frac{1}{3}} &= \frac{c_3 e^{c_2}}{t} \\ \left(\frac{2s^3 + 3s^2t + 3st^2 - t^3}{t^3}\right)^{\frac{1}{3}} &= \frac{c_3 e^{c_2}}{t}\end{aligned}$$

Summary

The solution(s) found are the following

$$\left(\frac{2s^3 + 3s^2t + 3st^2 - t^3}{t^3}\right)^{\frac{1}{3}} = \frac{c_3 e^{c_2}}{t} \quad (1)$$

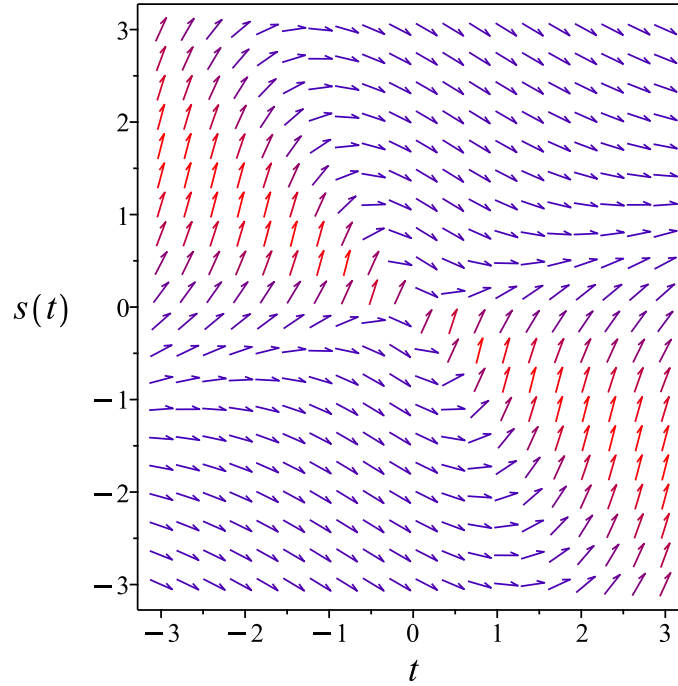


Figure 111: Slope field plot

Verification of solutions

$$\left(\frac{2s^3 + 3s^2t + 3st^2 - t^3}{t^3} \right)^{\frac{1}{3}} = \frac{c_3 e^{c_2}}{t}$$

Verified OK.

4.12.2 Solving as first order ode lie symmetry calculated ode

Writing the ode as

$$s' = -\frac{s^2 + 2st - t^2}{2s^2 + 2st + t^2}$$

$$s' = \omega(t, s)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_t + \omega(\eta_s - \xi_t) - \omega^2 \xi_s - \omega_t \xi - \omega_s \eta = 0 \quad (\text{A})$$

The type of this ode is not in the lookup table. To determine ξ, η then (A) is solved using ansatz. Making bivariate polynomials of degree 1 to use as anstaz gives

$$\xi = sa_3 + ta_2 + a_1 \quad (1\text{E})$$

$$\eta = sb_3 + tb_2 + b_1 \quad (2\text{E})$$

Where the unknown coefficients are

$$\{a_1, a_2, a_3, b_1, b_2, b_3\}$$

Substituting equations (1E,2E) and ω into (A) gives

$$\begin{aligned} b_2 - \frac{(s^2 + 2st - t^2)(b_3 - a_2)}{2s^2 + 2st + t^2} - \frac{(s^2 + 2st - t^2)^2 a_3}{(2s^2 + 2st + t^2)^2} \\ - \left(-\frac{2s - 2t}{2s^2 + 2st + t^2} + \frac{(s^2 + 2st - t^2)(2s + 2t)}{(2s^2 + 2st + t^2)^2} \right) (sa_3 + ta_2 + a_1) \\ - \left(-\frac{2s + 2t}{2s^2 + 2st + t^2} + \frac{(s^2 + 2st - t^2)(4s + 2t)}{(2s^2 + 2st + t^2)^2} \right) (sb_3 + tb_2 + b_1) = 0 \end{aligned} \quad (5E)$$

Putting the above in normal form gives

$$2s^4a_2 + s^4a_3 + 4s^4b_2 - 2s^4b_3 + 8s^3ta_2 - 10s^3ta_3 + 8s^3tb_2 - 8s^3tb_3 - 3s^2t^2a_2 - 6s^2t^2a_3 + 6s^2t^2b_2 + 3s^2t^2b_3$$

$$= 0$$

Setting the numerator to zero gives

$$\begin{aligned} 2s^4a_2 + s^4a_3 + 4s^4b_2 - 2s^4b_3 + 8s^3ta_2 - 10s^3ta_3 + 8s^3tb_2 - 8s^3tb_3 - 3s^2t^2a_2 \\ - 6s^2t^2a_3 + 6s^2t^2b_2 + 3s^2t^2b_3 - 4st^3a_2 + 4st^3a_3 + 10st^3b_2 + 4st^3b_3 - t^4a_2 \\ - t^4a_3 + 5t^4b_2 + t^4b_3 + 2s^3a_1 - 6s^2ta_1 - 2s^2tb_1 - 4st^2a_1 + 6st^2b_1 + 4t^3b_1 = 0 \end{aligned} \quad (6E)$$

Looking at the above PDE shows the following are all the terms with $\{s, t\}$ in them.

$$\{s, t\}$$

The following substitution is now made to be able to collect on all terms with $\{s, t\}$ in them

$$\{s = v_1, t = v_2\}$$

The above PDE (6E) now becomes

$$\begin{aligned} 2a_2v_1^4 + 8a_2v_1^3v_2 - 3a_2v_1^2v_2^2 - 4a_2v_1v_2^3 - a_2v_2^4 + a_3v_1^4 - 10a_3v_1^3v_2 \\ - 6a_3v_1^2v_2^2 + 4a_3v_1v_2^3 - a_3v_2^4 + 4b_2v_1^4 + 8b_2v_1^3v_2 + 6b_2v_1^2v_2^2 \\ + 10b_2v_1v_2^3 + 5b_2v_2^4 - 2b_3v_1^4 - 8b_3v_1^3v_2 + 3b_3v_1^2v_2^2 + 4b_3v_1v_2^3 + b_3v_2^4 \\ + 2a_1v_1^3 - 6a_1v_1^2v_2 - 4a_1v_1v_2^2 - 2b_1v_1^2v_2 + 6b_1v_1v_2^2 + 4b_1v_2^3 = 0 \end{aligned} \quad (7E)$$

Collecting the above on the terms v_i introduced, and these are

$$\{v_1, v_2\}$$

Equation (7E) now becomes

$$\begin{aligned} & (2a_2 + a_3 + 4b_2 - 2b_3)v_1^4 + (8a_2 - 10a_3 + 8b_2 - 8b_3)v_1^3v_2 \\ & + 2a_1v_1^3 + (-3a_2 - 6a_3 + 6b_2 + 3b_3)v_1^2v_2^2 \\ & + (-6a_1 - 2b_1)v_1^2v_2 + (-4a_2 + 4a_3 + 10b_2 + 4b_3)v_1v_2^3 \\ & + (-4a_1 + 6b_1)v_1v_2^2 + (-a_2 - a_3 + 5b_2 + b_3)v_2^4 + 4b_1v_2^3 = 0 \end{aligned} \quad (8E)$$

Setting each coefficients in (8E) to zero gives the following equations to solve

$$\begin{aligned} 2a_1 &= 0 \\ 4b_1 &= 0 \\ -6a_1 - 2b_1 &= 0 \\ -4a_1 + 6b_1 &= 0 \\ -4a_2 + 4a_3 + 10b_2 + 4b_3 &= 0 \\ -3a_2 - 6a_3 + 6b_2 + 3b_3 &= 0 \\ -a_2 - a_3 + 5b_2 + b_3 &= 0 \\ 2a_2 + a_3 + 4b_2 - 2b_3 &= 0 \\ 8a_2 - 10a_3 + 8b_2 - 8b_3 &= 0 \end{aligned}$$

Solving the above equations for the unknowns gives

$$\begin{aligned} a_1 &= 0 \\ a_2 &= b_3 \\ a_3 &= 0 \\ b_1 &= 0 \\ b_2 &= 0 \\ b_3 &= b_3 \end{aligned}$$

Substituting the above solution in the ansatz (1E,2E) (using 1 as arbitrary value for any unknown in the RHS) gives

$$\begin{aligned} \xi &= t \\ \eta &= s \end{aligned}$$

Shifting is now applied to make $\xi = 0$ in order to simplify the rest of the computation

$$\begin{aligned}\eta &= \eta - \omega(t, s) \xi \\ &= s - \left(-\frac{s^2 + 2st - t^2}{2s^2 + 2st + t^2} \right) (t) \\ &= \frac{2s^3 + 3s^2t + 3st^2 - t^3}{2s^2 + 2st + t^2} \\ \xi &= 0\end{aligned}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(t, s) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dt}{\xi} = \frac{ds}{\eta} = dS \quad (1)$$

The above comes from the requirements that $(\xi \frac{\partial}{\partial t} + \eta \frac{\partial}{\partial s}) S(t, s) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = t$$

S is found from

$$\begin{aligned}S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{2s^3 + 3s^2t + 3st^2 - t^3}{2s^2 + 2st + t^2}} dy\end{aligned}$$

Which results in

$$S = \frac{\ln(2s^3 + 3s^2t + 3st^2 - t^3)}{3}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_t + \omega(t, s)S_s}{R_t + \omega(t, s)R_s} \quad (2)$$

Where in the above R_t, R_s, S_t, S_s are all partial derivatives and $\omega(t, s)$ is the right hand side of the original ode given by

$$\omega(t, s) = -\frac{s^2 + 2st - t^2}{2s^2 + 2st + t^2}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_t &= 1 \\ R_s &= 0 \\ S_t &= \frac{s^2 + 2st - t^2}{2s^3 + 3s^2t + 3st^2 - t^3} \\ S_s &= \frac{2s^2 + 2st + t^2}{2s^3 + 3s^2t + 3st^2 - t^3} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 0 \tag{2A}$$

We now need to express the RHS as function of R only. This is done by solving for t, s in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 0$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = c_1 \tag{4}$$

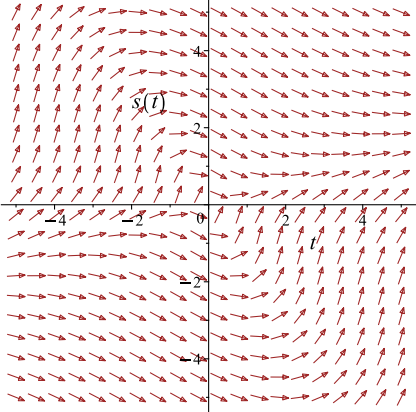
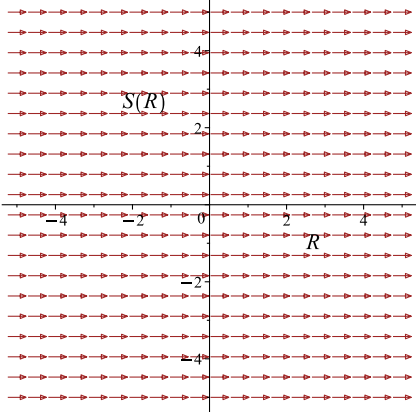
To complete the solution, we just need to transform (4) back to t, s coordinates. This results in

$$\frac{\ln(2s^3 + 3s^2t + 3st^2 - t^3)}{3} = c_1$$

Which simplifies to

$$\frac{\ln(2s^3 + 3s^2t + 3st^2 - t^3)}{3} = c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in t, s coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{ds}{dt} = -\frac{s^2+2st-t^2}{2s^2+2st+t^2}$ 	$R = t$ $S = \frac{\ln(2s^3 + 3s^2t + 3st^2)}{3}$	$\frac{dS}{dR} = 0$ 

Summary

The solution(s) found are the following

$$\frac{\ln(2s^3 + 3s^2t + 3st^2 - t^3)}{3} = c_1 \quad (1)$$

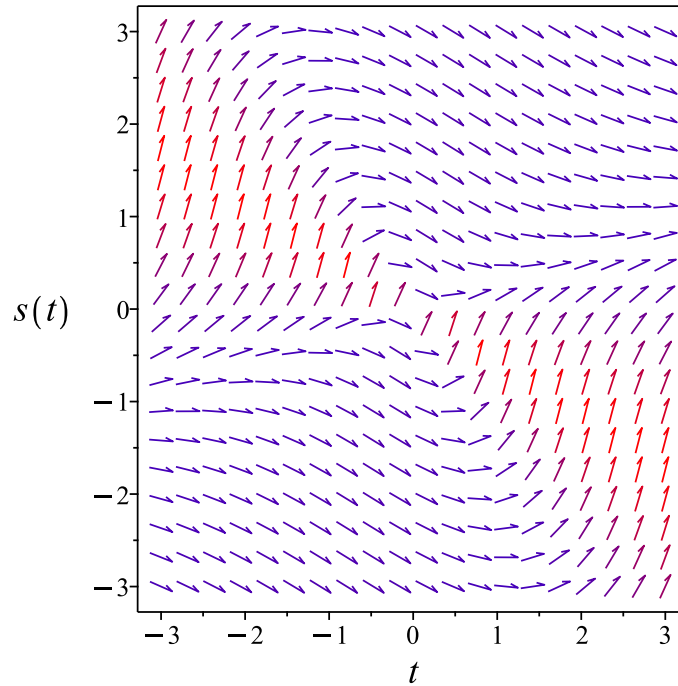


Figure 112: Slope field plot

Verification of solutions

$$\frac{\ln(2s^3 + 3s^2t + 3st^2 - t^3)}{3} = c_1$$

Verified OK.

4.12.3 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx}\phi(x, y) = 0$$

Hence

$$\frac{\partial\phi}{\partial x} + \frac{\partial\phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(t, s) dt + N(t, s) ds = 0 \tag{1A}$$

Therefore

$$\begin{aligned}(2s^2 + 2st + t^2) ds &= (-s^2 - 2st + t^2) dt \\ (s^2 + 2st - t^2) dt + (2s^2 + 2st + t^2) ds &= 0\end{aligned} \tag{2A}$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(t, s) &= s^2 + 2st - t^2 \\ N(t, s) &= 2s^2 + 2st + t^2\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial s} = \frac{\partial N}{\partial t}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial s} &= \frac{\partial}{\partial s}(s^2 + 2st - t^2) \\ &= 2s + 2t\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial t} &= \frac{\partial}{\partial t}(2s^2 + 2st + t^2) \\ &= 2s + 2t\end{aligned}$$

Since $\frac{\partial M}{\partial s} = \frac{\partial N}{\partial t}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(t, s)$

$$\frac{\partial \phi}{\partial t} = M \quad (1)$$

$$\frac{\partial \phi}{\partial s} = N \quad (2)$$

Integrating (1) w.r.t. t gives

$$\begin{aligned} \int \frac{\partial \phi}{\partial t} dt &= \int M dt \\ \int \frac{\partial \phi}{\partial t} dt &= \int s^2 + 2st - t^2 dt \\ \phi &= s^2t + st^2 - \frac{1}{3}t^3 + f(s) \end{aligned} \quad (3)$$

Where $f(s)$ is used for the constant of integration since ϕ is a function of both t and s . Taking derivative of equation (3) w.r.t s gives

$$\begin{aligned} \frac{\partial \phi}{\partial s} &= 2st + t^2 + f'(s) \\ &= t(2s + t) + f'(s) \end{aligned} \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial s} = 2s^2 + 2st + t^2$. Therefore equation (4) becomes

$$2s^2 + 2st + t^2 = t(2s + t) + f'(s) \quad (5)$$

Solving equation (5) for $f'(s)$ gives

$$f'(s) = 2s^2$$

Integrating the above w.r.t s gives

$$\begin{aligned} \int f'(s) ds &= \int (2s^2) ds \\ f(s) &= \frac{2s^3}{3} + c_1 \end{aligned}$$

Where c_1 is constant of integration. Substituting result found above for $f(s)$ into equation (3) gives ϕ

$$\phi = s^2t + st^2 - \frac{1}{3}t^3 + \frac{2}{3}s^3 + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = s^2t + st^2 - \frac{1}{3}t^3 + \frac{2}{3}s^3$$

Summary

The solution(s) found are the following

$$s^2t + st^2 - \frac{t^3}{3} + \frac{2s^3}{3} = c_1 \quad (1)$$

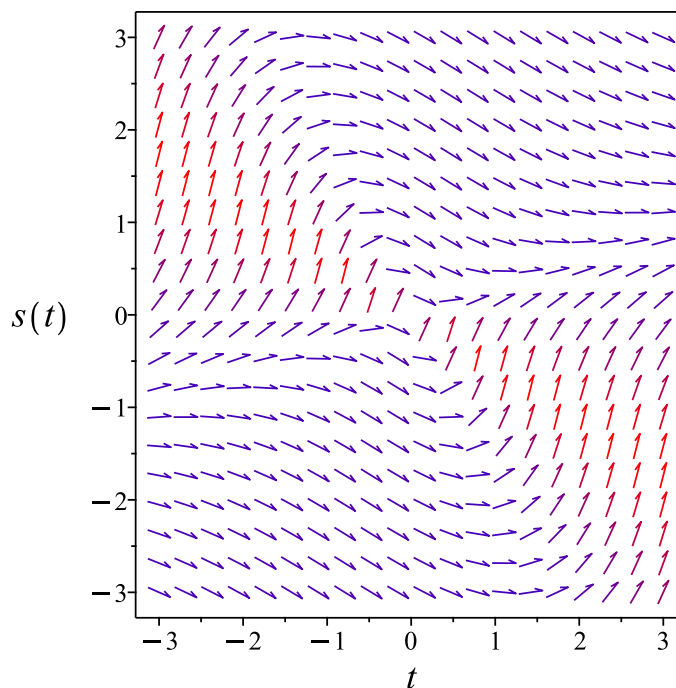


Figure 113: Slope field plot

Verification of solutions

$$s^2t + st^2 - \frac{t^3}{3} + \frac{2s^3}{3} = c_1$$

Verified OK.

4.12.4 Maple step by step solution

Let's solve

$$(2s^2 + 2st + t^2) s' + s^2 + 2st = t^2$$

- Highest derivative means the order of the ODE is 1
 s'
- Check if ODE is exact
 - ODE is exact if the lhs is the total derivative of a C^2 function
 $F'(t, s) = 0$
 - Compute derivative of lhs
 $F'(t, s) + \left(\frac{\partial}{\partial s} F(t, s)\right) s' = 0$
 - Evaluate derivatives
 $2s + 2t = 2s + 2t$
 - Condition met, ODE is exact
- Exact ODE implies solution will be of this form
 $[F(t, s) = c_1, M(t, s) = F'(t, s), N(t, s) = \frac{\partial}{\partial s} F(t, s)]$
- Solve for $F(t, s)$ by integrating $M(t, s)$ with respect to t
 $F(t, s) = \int (s^2 + 2st - t^2) dt + f_1(s)$
- Evaluate integral
 $F(t, s) = s^2t + st^2 - \frac{t^3}{3} + f_1(s)$
- Take derivative of $F(t, s)$ with respect to s
 $N(t, s) = \frac{\partial}{\partial s} F(t, s)$
- Compute derivative
 $2s^2 + 2st + t^2 = 2st + t^2 + \frac{d}{ds} f_1(s)$
- Isolate for $\frac{d}{ds} f_1(s)$
 $\frac{d}{ds} f_1(s) = 2s^2$
- Solve for $f_1(s)$
 $f_1(s) = \frac{2s^3}{3}$
- Substitute $f_1(s)$ into equation for $F(t, s)$
 $F(t, s) = s^2t + st^2 - \frac{1}{3}t^3 + \frac{2}{3}s^3$

- Substitute $F(t, s)$ into the solution of the ODE

$$s^2 t + s t^2 - \frac{1}{3} t^3 + \frac{2}{3} s^3 = c_1$$

- Solve for s

$$\left\{ s = \frac{\left(4t^3 + 6c_1 + \sqrt{17t^6 + 48t^3 c_1 + 36c_1^2}\right)^{\frac{1}{3}}}{2} - \frac{t^2}{2\left(4t^3 + 6c_1 + \sqrt{17t^6 + 48t^3 c_1 + 36c_1^2}\right)^{\frac{1}{3}}} - \frac{t}{2}, s = -\frac{\left(4t^3 + 6c_1 + \sqrt{17t^6 + 48t^3 c_1 + 36c_1^2}\right)^{\frac{1}{3}}}{4}$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
trying separable
trying inverse linear
trying homogeneous types:
trying homogeneous D
<- homogeneous successful`

```

✓ Solution by Maple

Time used: 0.063 (sec). Leaf size: 348

`dsolve((2*s(t)^2+2*s(t)*t+t^2)*diff(s(t),t)+(s(t)^2+2*s(t)*t-t^2)=0,s(t), singsol=all)`

$$s(t) = \frac{\left(4t^3c_1^3 + 2 + \sqrt{17c_1^6t^6 + 16t^3c_1^3 + 4}\right)^{\frac{1}{3}} - \frac{t^2c_1^2}{\left(4t^3c_1^3 + 2 + \sqrt{17c_1^6t^6 + 16t^3c_1^3 + 4}\right)^{\frac{1}{3}}} - c_1t}{2c_1}$$

$$s(t) = \frac{(1 + i\sqrt{3}) \left(4t^3c_1^3 + 2 + \sqrt{17c_1^6t^6 + 16t^3c_1^3 + 4}\right)^{\frac{2}{3}} + c_1t \left(2 \left(4t^3c_1^3 + 2 + \sqrt{17c_1^6t^6 + 16t^3c_1^3 + 4}\right)^{\frac{1}{3}} + (i\sqrt{3} - 1) \left(4t^3c_1^3 + 2 + \sqrt{17c_1^6t^6 + 16t^3c_1^3 + 4}\right)^{\frac{2}{3}} + \left(-2 \left(4t^3c_1^3 + 2 + \sqrt{17c_1^6t^6 + 16t^3c_1^3 + 4}\right)^{\frac{1}{3}} + c_1t(1 - i\sqrt{3}) \left(4t^3c_1^3 + 2 + \sqrt{17c_1^6t^6 + 16t^3c_1^3 + 4}\right)^{\frac{2}{3}}\right)}{4 \left(4t^3c_1^3 + 2 + \sqrt{17c_1^6t^6 + 16t^3c_1^3 + 4}\right)^{\frac{1}{3}} c_1}$$

$$s(t) = \frac{(i\sqrt{3} - 1) \left(4t^3c_1^3 + 2 + \sqrt{17c_1^6t^6 + 16t^3c_1^3 + 4}\right)^{\frac{2}{3}} + \left(-2 \left(4t^3c_1^3 + 2 + \sqrt{17c_1^6t^6 + 16t^3c_1^3 + 4}\right)^{\frac{1}{3}} + c_1t(1 - i\sqrt{3}) \left(4t^3c_1^3 + 2 + \sqrt{17c_1^6t^6 + 16t^3c_1^3 + 4}\right)^{\frac{2}{3}}\right)}{4 \left(4t^3c_1^3 + 2 + \sqrt{17c_1^6t^6 + 16t^3c_1^3 + 4}\right)^{\frac{1}{3}} c_1}$$

✓ Solution by Mathematica

Time used: 48.03 (sec). Leaf size: 616

`DSolve[(2*s[t]^2+2*s[t]*t+t^2)*s'[t]+(s[t]^2+2*s[t]*t-t^2)==0,s[t],t,IncludeSingularSolution`

$$s(t) \rightarrow \frac{1}{2} \left(\sqrt[3]{4t^3 + \sqrt{17t^6 + 16e^{3c_1}t^3 + 4e^{6c_1}} + 2e^{3c_1}} - \frac{t^2}{\sqrt[3]{4t^3 + \sqrt{17t^6 + 16e^{3c_1}t^3 + 4e^{6c_1}} + 2e^{3c_1}}} - t \right)$$

$$s(t) \rightarrow \frac{1}{8} \left(2i(\sqrt{3} + i) \sqrt[3]{4t^3 + \sqrt{17t^6 + 16e^{3c_1}t^3 + 4e^{6c_1}} + 2e^{3c_1}} + \frac{2(1 + i\sqrt{3})t^2}{\sqrt[3]{4t^3 + \sqrt{17t^6 + 16e^{3c_1}t^3 + 4e^{6c_1}} + 2e^{3c_1}}} - 4t \right)$$

$$s(t) \rightarrow \frac{1}{8} \left(-2(1 + i\sqrt{3}) \sqrt[3]{4t^3 + \sqrt{17t^6 + 16e^{3c_1}t^3 + 4e^{6c_1}} + 2e^{3c_1}} + \frac{2(1 - i\sqrt{3})t^2}{\sqrt[3]{4t^3 + \sqrt{17t^6 + 16e^{3c_1}t^3 + 4e^{6c_1}} + 2e^{3c_1}}} - 4t \right)$$

$$s(t) \rightarrow \frac{1}{2} \left(\sqrt[3]{\sqrt{17}\sqrt{t^6} + 4t^3} - \frac{t^2}{\sqrt[3]{\sqrt{17}\sqrt{t^6} + 4t^3}} - t \right)$$

$$s(t) \rightarrow \frac{1}{4} \left((-1 - i\sqrt{3}) \sqrt[3]{\sqrt{17}\sqrt{t^6} + 4t^3} + \frac{(1 - i\sqrt{3})t^2}{\sqrt[3]{\sqrt{17}\sqrt{t^6} + 4t^3}} - 2t \right)$$

$$s(t) \rightarrow \frac{1}{4} \left(i(\sqrt{3} + i) \sqrt[3]{\sqrt{17}\sqrt{t^6} + 4t^3} + \frac{(1 + i\sqrt{3})t^2}{\sqrt[3]{\sqrt{17}\sqrt{t^6} + 4t^3}} - 2t \right)$$

4.13 problem 13

- 4.13.1 Solving as first order ode lie symmetry calculated ode 608
- 4.13.2 Solving as exact ode 615

Internal problem ID [11626]

Internal file name [OUTPUT/10608_Saturday_May_27_2023_03_05_22_AM_44852541/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 2, section 2.2 (Separable equations). Exercises page 47

Problem number: 13.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"exactWithIntegrationFactor", "first_order_ode_lie_symmetry_calculated"**

Maple gives the following as the ode type

```
[[_homogeneous, `class A`], _dAlembert]
```

$$y^2 \sqrt{x^2 + y^2} - xy \sqrt{x^2 + y^2} y' = -x^3$$

4.13.1 Solving as first order ode lie symmetry calculated ode

Writing the ode as

$$y' = \frac{x^3 + y^2 \sqrt{x^2 + y^2}}{xy \sqrt{x^2 + y^2}}$$
$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \tag{A}$$

The type of this ode is not in the lookup table. To determine ξ, η then (A) is solved using ansatz. Making bivariate polynomials of degree 1 to use as anstaz gives

$$\xi = xa_2 + ya_3 + a_1 \tag{1E}$$

$$\eta = xb_2 + yb_3 + b_1 \tag{2E}$$

Where the unknown coefficients are

$$\{a_1, a_2, a_3, b_1, b_2, b_3\}$$

Substituting equations (1E,2E) and ω into (A) gives

$$\begin{aligned} b_2 + \frac{(x^3 + y^2\sqrt{x^2 + y^2})(b_3 - a_2)}{xy\sqrt{x^2 + y^2}} - \frac{(x^3 + y^2\sqrt{x^2 + y^2})^2 a_3}{x^2 y^2 (x^2 + y^2)} \\ - \left(\frac{3x^2 + \frac{y^2 x}{\sqrt{x^2 + y^2}}}{xy\sqrt{x^2 + y^2}} - \frac{x^3 + y^2\sqrt{x^2 + y^2}}{x^2 y\sqrt{x^2 + y^2}} - \frac{x^3 + y^2\sqrt{x^2 + y^2}}{y(x^2 + y^2)^{\frac{3}{2}}} \right) (xa_2 + ya_3 + a_1) \\ - \left(\frac{2y\sqrt{x^2 + y^2} + \frac{y^3}{\sqrt{x^2 + y^2}}}{xy\sqrt{x^2 + y^2}} - \frac{x^3 + y^2\sqrt{x^2 + y^2}}{x y^2\sqrt{x^2 + y^2}} \right. \\ \left. - \frac{x^3 + y^2\sqrt{x^2 + y^2}}{x(x^2 + y^2)^{\frac{3}{2}}} \right) (xb_2 + yb_3 + b_1) = 0 \end{aligned} \quad (5E)$$

Putting the above in normal form gives

$$\begin{aligned} - \frac{(x^2 + y^2)^{\frac{3}{2}} x^6 a_3 - (x^2 + y^2)^{\frac{3}{2}} y^6 a_3 - (x^2 + y^2)^{\frac{3}{2}} y^5 a_1 - 2x^8 y b_3 + 3x^4 y^5 a_2 + 4x^3 y^6 a_3 + 2x^3 y^5 a_1 - x^9 b_2 - \\ = 0 \end{aligned}$$

Setting the numerator to zero gives

$$\begin{aligned} - (x^2 + y^2)^{\frac{3}{2}} x^6 a_3 + (x^2 + y^2)^{\frac{3}{2}} y^6 a_3 + (x^2 + y^2)^{\frac{3}{2}} y^5 a_1 + 2x^8 y b_3 \\ - 3x^4 y^5 a_2 - 4x^3 y^6 a_3 - 2x^3 y^5 a_1 + x^9 b_2 + x^8 b_1 + (x^2 + y^2)^{\frac{3}{2}} x^2 y^4 a_3 \\ - (x^2 + y^2)^{\frac{3}{2}} x^3 y^2 b_1 + (x^2 + y^2)^{\frac{3}{2}} x^2 y^3 a_1 - (x^2 + y^2)^{\frac{3}{2}} x y^4 b_1 - 2x^8 y a_2 \\ - 3x^7 y^2 a_3 + 3x^7 y^2 b_2 - 5x^6 y^3 a_2 + 5x^6 y^3 b_3 - 7x^5 y^4 a_3 + 2x^5 y^4 b_2 \\ + 3x^4 y^5 b_3 - x^7 y a_1 + 3x^6 y^2 b_1 - 3x^5 y^3 a_1 + 2x^4 y^4 b_1 - (x^2 + y^2)^{\frac{5}{2}} y^4 a_3 = 0 \end{aligned} \quad (6E)$$

Simplifying the above gives

$$\begin{aligned}
& -(x^2 + y^2)^{\frac{3}{2}} x^6 a_3 + (x^2 + y^2)^{\frac{3}{2}} y^6 a_3 + (x^2 + y^2) x^7 b_2 \\
& + (x^2 + y^2)^{\frac{3}{2}} y^5 a_1 + (x^2 + y^2) x^6 b_1 - 2(x^2 + y^2)^2 x^3 y^2 a_3 \\
& + (x^2 + y^2)^{\frac{3}{2}} x^2 y^4 a_3 - 3(x^2 + y^2) x^6 y a_2 + 2(x^2 + y^2) x^6 y b_3 \\
& - 2(x^2 + y^2) x^5 y^2 a_3 + (x^2 + y^2) x^5 y^2 b_2 - 3(x^2 + y^2) x^4 y^3 a_2 \\
& + 2(x^2 + y^2) x^4 y^3 b_3 - 2(x^2 + y^2) x^3 y^4 a_3 - (x^2 + y^2)^{\frac{3}{2}} x^3 y^2 b_1 \\
& + (x^2 + y^2)^{\frac{3}{2}} x^2 y^3 a_1 - (x^2 + y^2)^{\frac{3}{2}} x y^4 b_1 - 2(x^2 + y^2) x^5 y a_1 \\
& + (x^2 + y^2) x^4 y^2 b_1 - 2(x^2 + y^2) x^3 y^3 a_1 + x^8 y a_2 + x^7 y^2 a_3 \\
& + x^7 y^2 b_2 + x^6 y^3 a_2 + x^6 y^3 b_3 + x^5 y^4 a_3 + x^5 y^4 b_2 + x^4 y^5 b_3 \\
& + x^7 y a_1 + x^6 y^2 b_1 + x^5 y^3 a_1 + x^4 y^4 b_1 - (x^2 + y^2)^{\frac{5}{2}} y^4 a_3 = 0
\end{aligned} \tag{6E}$$

Since the PDE has radicals, simplifying gives

$$\begin{aligned}
& -x^8 \sqrt{x^2 + y^2} a_3 + \sqrt{x^2 + y^2} y^7 a_1 - 2x^3 \sqrt{x^2 + y^2} y^4 b_1 + 2x^2 \sqrt{x^2 + y^2} y^5 a_1 \\
& - x \sqrt{x^2 + y^2} y^6 b_1 + 2x^8 y b_3 - 3x^4 y^5 a_2 - 4x^3 y^6 a_3 - 2x^3 y^5 a_1 \\
& - x^6 \sqrt{x^2 + y^2} y^2 a_3 - x^5 \sqrt{x^2 + y^2} y^2 b_1 + x^4 \sqrt{x^2 + y^2} y^3 a_1 + x^9 b_2 \\
& + x^8 b_1 - 2x^8 y a_2 - 3x^7 y^2 a_3 + 3x^7 y^2 b_2 - 5x^6 y^3 a_2 + 5x^6 y^3 b_3 - 7x^5 y^4 a_3 \\
& + 2x^5 y^4 b_2 + 3x^4 y^5 b_3 - x^7 y a_1 + 3x^6 y^2 b_1 - 3x^5 y^3 a_1 + 2x^4 y^4 b_1 = 0
\end{aligned}$$

Looking at the above PDE shows the following are all the terms with $\{x, y\}$ in them.

$$\{x, y, \sqrt{x^2 + y^2}\}$$

The following substitution is now made to be able to collect on all terms with $\{x, y\}$ in them

$$\{x = v_1, y = v_2, \sqrt{x^2 + y^2} = v_3\}$$

The above PDE (6E) now becomes

$$\begin{aligned}
& -2v_1^8 v_2 a_2 - 5v_1^6 v_2^3 a_2 - 3v_1^4 v_2^5 a_2 - v_1^8 v_3 a_3 - 3v_1^7 v_2^2 a_3 - v_1^6 v_3 v_2^2 a_3 - 7v_1^5 v_2^4 a_3 \\
& - 4v_1^3 v_2^6 a_3 + v_1^9 b_2 + 3v_1^7 v_2^2 b_2 + 2v_1^5 v_2^4 b_2 + 2v_1^8 v_2 b_3 + 5v_1^6 v_2^3 b_3 + 3v_1^4 v_2^5 b_3 \\
& - v_1^7 v_2 a_1 - 3v_1^5 v_2^3 a_1 + v_1^4 v_3 v_2^3 a_1 - 2v_1^3 v_2^5 a_1 + 2v_1^2 v_3 v_2^5 a_1 + v_3 v_2^7 a_1 \\
& + v_1^8 b_1 + 3v_1^6 v_2^2 b_1 - v_1^5 v_3 v_2^2 b_1 + 2v_1^4 v_2^4 b_1 - 2v_1^3 v_3 v_2^4 b_1 - v_1 v_3 v_2^6 b_1 = 0
\end{aligned} \tag{7E}$$

Collecting the above on the terms v_i introduced, and these are

$$\{v_1, v_2, v_3\}$$

Equation (7E) now becomes

$$\begin{aligned} &v_1^9 b_2 + (-2a_2 + 2b_3) v_1^8 v_2 - v_1^8 v_3 a_3 + v_1^8 b_1 + (-3a_3 + 3b_2) v_1^7 v_2^2 - v_1^7 v_2 a_1 \\ &+ (-5a_2 + 5b_3) v_1^6 v_2^3 - v_1^6 v_3 v_2^2 a_3 + 3v_1^6 v_2^2 b_1 + (-7a_3 + 2b_2) v_1^5 v_2^4 \\ &- 3v_1^5 v_2^3 a_1 - v_1^5 v_3 v_2^2 b_1 + (-3a_2 + 3b_3) v_1^4 v_2^5 + 2v_1^4 v_2^4 b_1 + v_1^4 v_3 v_2^3 a_1 \\ &- 4v_1^3 v_2^6 a_3 - 2v_1^3 v_2^5 a_1 - 2v_1^3 v_3 v_2^4 b_1 + 2v_1^2 v_3 v_2^5 a_1 - v_1 v_3 v_2^6 b_1 + v_3 v_2^7 a_1 = 0 \end{aligned} \quad (8E)$$

Setting each coefficients in (8E) to zero gives the following equations to solve

$$\begin{aligned} a_1 &= 0 \\ b_1 &= 0 \\ b_2 &= 0 \\ -3a_1 &= 0 \\ -2a_1 &= 0 \\ -a_1 &= 0 \\ 2a_1 &= 0 \\ -4a_3 &= 0 \\ -a_3 &= 0 \\ -2b_1 &= 0 \\ -b_1 &= 0 \\ 2b_1 &= 0 \\ 3b_1 &= 0 \\ -5a_2 + 5b_3 &= 0 \\ -3a_2 + 3b_3 &= 0 \\ -2a_2 + 2b_3 &= 0 \\ -7a_3 + 2b_2 &= 0 \\ -3a_3 + 3b_2 &= 0 \end{aligned}$$

Solving the above equations for the unknowns gives

$$a_1 = 0$$

$$a_2 = b_3$$

$$a_3 = 0$$

$$b_1 = 0$$

$$b_2 = 0$$

$$b_3 = b_3$$

Substituting the above solution in the anstaz (1E,2E) (using 1 as arbitrary value for any unknown in the RHS) gives

$$\xi = x$$

$$\eta = y$$

Shifting is now applied to make $\xi = 0$ in order to simplify the rest of the computation

$$\begin{aligned} \eta &= \eta - \omega(x, y) \xi \\ &= y - \left(\frac{x^3 + y^2 \sqrt{x^2 + y^2}}{xy \sqrt{x^2 + y^2}} \right) (x) \\ &= -\frac{x^3}{y \sqrt{x^2 + y^2}} \\ \xi &= 0 \end{aligned}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \quad (1)$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y} \right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{-\frac{x^3}{y \sqrt{x^2 + y^2}}} dy \end{aligned}$$

Which results in

$$S = -\frac{(x^2 + y^2)^{\frac{3}{2}}}{3x^3}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = \frac{x^3 + y^2\sqrt{x^2 + y^2}}{xy\sqrt{x^2 + y^2}}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= \frac{\sqrt{x^2 + y^2} y^2}{x^4} \\ S_y &= -\frac{y\sqrt{x^2 + y^2}}{x^3} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = -\frac{1}{x} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = -\frac{1}{R}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = -\ln(R) + c_1 \quad (4)$$

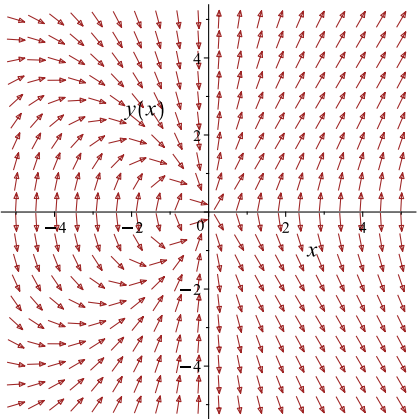
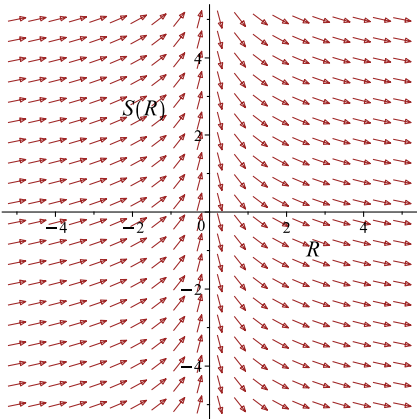
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$-\frac{(x^2 + y^2)^{\frac{3}{2}}}{3x^3} = -\ln(x) + c_1$$

Which simplifies to

$$-\frac{(x^2 + y^2)^{\frac{3}{2}}}{3x^3} = -\ln(x) + c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = \frac{x^3 + y^2 \sqrt{x^2 + y^2}}{xy \sqrt{x^2 + y^2}}$ 	$R = x$ $S = -\frac{(x^2 + y^2)^{\frac{3}{2}}}{3x^3}$	$\frac{dS}{dR} = -\frac{1}{R}$ 

Summary

The solution(s) found are the following

$$-\frac{(x^2 + y^2)^{\frac{3}{2}}}{3x^3} = -\ln(x) + c_1 \tag{1}$$

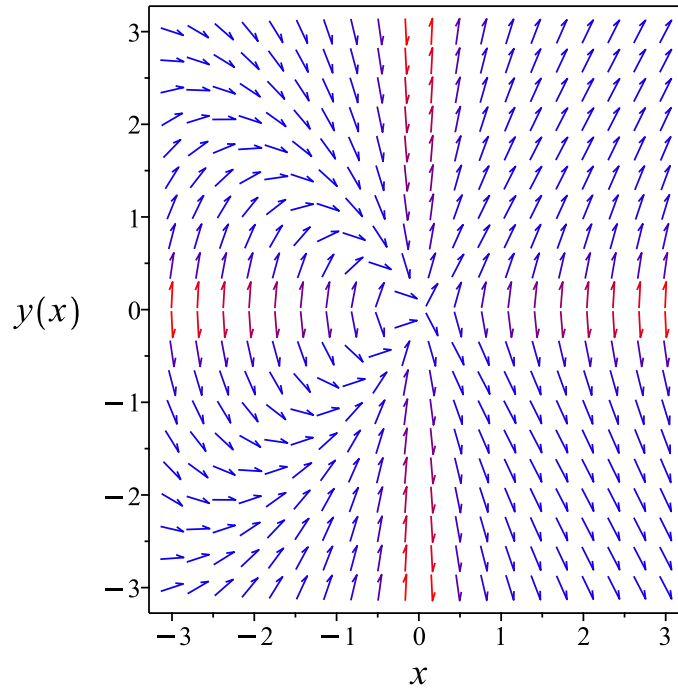


Figure 114: Slope field plot

Verification of solutions

$$-\frac{(x^2 + y^2)^{\frac{3}{2}}}{3x^3} = -\ln(x) + c_1$$

Verified OK.

4.13.2 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx}\phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (1A)$$

Therefore

$$\begin{aligned}(-xy\sqrt{x^2 + y^2}) dy &= (-x^3 - y^2\sqrt{x^2 + y^2}) dx \\ (x^3 + y^2\sqrt{x^2 + y^2}) dx &+ (-xy\sqrt{x^2 + y^2}) dy = 0\end{aligned} \quad (2A)$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= x^3 + y^2\sqrt{x^2 + y^2} \\ N(x, y) &= -xy\sqrt{x^2 + y^2}\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y} (x^3 + y^2\sqrt{x^2 + y^2}) \\ &= \frac{2x^2y + 3y^3}{\sqrt{x^2 + y^2}}\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x} \left(-xy\sqrt{x^2 + y^2} \right) \\ &= \frac{(-2x^2 - y^2)y}{\sqrt{x^2 + y^2}}\end{aligned}$$

Since $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$\begin{aligned}A &= \frac{1}{N} \left(\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} \right) \\ &= -\frac{1}{xy\sqrt{x^2 + y^2}} \left(\left(2y\sqrt{x^2 + y^2} + \frac{y^3}{\sqrt{x^2 + y^2}} \right) - \left(-y\sqrt{x^2 + y^2} - \frac{x^2y}{\sqrt{x^2 + y^2}} \right) \right) \\ &= -\frac{4}{x}\end{aligned}$$

Since A does not depend on y , then it can be used to find an integrating factor. The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int A dx} \\ &= e^{\int -\frac{4}{x} dx}\end{aligned}$$

The result of integrating gives

$$\begin{aligned}\mu &= e^{-4 \ln(x)} \\ &= \frac{1}{x^4}\end{aligned}$$

M and N are multiplied by this integrating factor, giving new M and new N which are called \bar{M} and \bar{N} for now so not to confuse them with the original M and N .

$$\begin{aligned}\bar{M} &= \mu M \\ &= \frac{1}{x^4} \left(x^3 + y^2\sqrt{x^2 + y^2} \right) \\ &= \frac{x^3 + y^2\sqrt{x^2 + y^2}}{x^4}\end{aligned}$$

And

$$\begin{aligned}\bar{N} &= \mu N \\ &= \frac{1}{x^4} \left(-xy\sqrt{x^2 + y^2} \right) \\ &= -\frac{y\sqrt{x^2 + y^2}}{x^3}\end{aligned}$$

Now a modified ODE is obtained from the original ODE, which is exact and can be solved. The modified ODE is

$$\overline{M} + \overline{N} \frac{dy}{dx} = 0$$

$$\left(\frac{x^3 + y^2 \sqrt{x^2 + y^2}}{x^4} \right) + \left(-\frac{y \sqrt{x^2 + y^2}}{x^3} \right) \frac{dy}{dx} = 0$$

The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = \overline{M} \quad (1)$$

$$\frac{\partial \phi}{\partial y} = \overline{N} \quad (2)$$

Integrating (1) w.r.t. x gives

$$\int \frac{\partial \phi}{\partial x} dx = \int \overline{M} dx$$

$$\int \frac{\partial \phi}{\partial x} dx = \int \frac{x^3 + y^2 \sqrt{x^2 + y^2}}{x^4} dx$$

$$\phi = \frac{3 \ln(x) x^3 - x^2 \sqrt{x^2 + y^2} - y^2 \sqrt{x^2 + y^2}}{3x^3} + f(y) \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = \frac{-\frac{x^2 y}{\sqrt{x^2 + y^2}} - 2y \sqrt{x^2 + y^2} - \frac{y^3}{\sqrt{x^2 + y^2}}}{3x^3} + f'(y) \quad (4)$$

$$= -\frac{y \sqrt{x^2 + y^2}}{x^3} + f'(y)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = -\frac{y \sqrt{x^2 + y^2}}{x^3}$. Therefore equation (4) becomes

$$-\frac{y \sqrt{x^2 + y^2}}{x^3} = -\frac{y \sqrt{x^2 + y^2}}{x^3} + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 0$$

Therefore

$$f(y) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(y)$ into equation (3) gives ϕ

$$\phi = \frac{3 \ln(x) x^3 - x^2 \sqrt{x^2 + y^2} - y^2 \sqrt{x^2 + y^2}}{3x^3} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = \frac{3 \ln(x) x^3 - x^2 \sqrt{x^2 + y^2} - y^2 \sqrt{x^2 + y^2}}{3x^3}$$

Summary

The solution(s) found are the following

$$\frac{3 \ln(x) x^3 - x^2 \sqrt{x^2 + y^2} - y^2 \sqrt{x^2 + y^2}}{3x^3} = c_1 \quad (1)$$

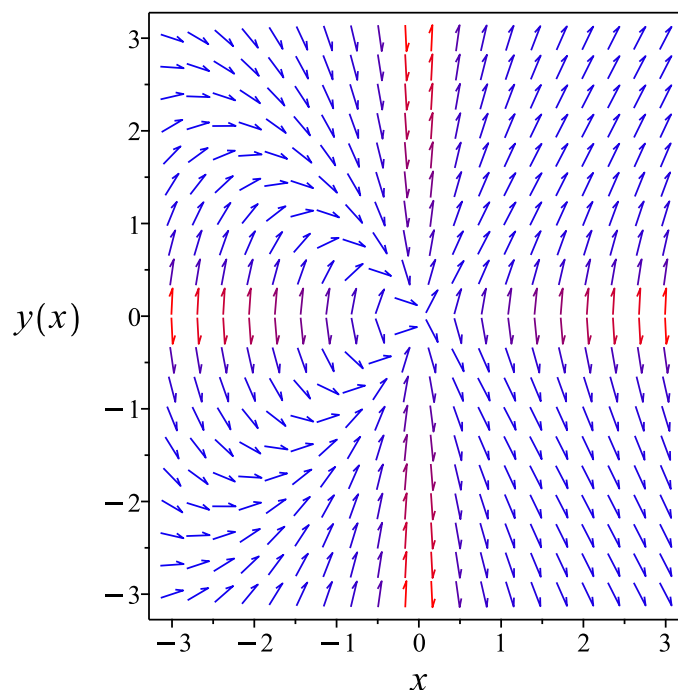


Figure 115: Slope field plot

Verification of solutions

$$\frac{3 \ln(x) x^3 - x^2 \sqrt{x^2 + y^2} - y^2 \sqrt{x^2 + y^2}}{3x^3} = c_1$$

Verified OK.

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying homogeneous types:  
trying homogeneous G  
1st order, trying the canonical coordinates of the invariance group  
<- 1st order, canonical coordinates successful  
<- homogeneous successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 42

```
dsolve((x^3+y(x)^2*sqrt(x^2+y(x)^2))-x*y(x)*sqrt(x^2+y(x)^2)*diff(y(x),x)=0,y(x), singsol=all)
```

$$\frac{(-y(x)^2 - x^2) \sqrt{y(x)^2 + x^2} - x^3(c_1 - 3 \ln(x))}{x^3} = 0$$

✓ Solution by Mathematica

Time used: 28.664 (sec). Leaf size: 265

```
DSolve[(x^3+y[x]^2*Sqrt[x^2+y[x]^2])-x*y[x]*Sqrt[x^2+y[x]^2]*y'[x]==0,y[x],x,IncludeSingular
```

$$y(x) \rightarrow -\sqrt{-x^2 - \frac{1}{2}\sqrt[6]{3}(\sqrt{3} + 3i)\sqrt[3]{x^6(\log(x) + c_1)^2}}$$

$$y(x) \rightarrow \sqrt{-x^2 - \frac{1}{2}\sqrt[6]{3}(\sqrt{3} + 3i)\sqrt[3]{x^6(\log(x) + c_1)^2}}$$

$$y(x) \rightarrow -\sqrt{-x^2 - \frac{1}{2}\sqrt[6]{3}(\sqrt{3} - 3i)\sqrt[3]{x^6(\log(x) + c_1)^2}}$$

$$y(x) \rightarrow \sqrt{-x^2 - \frac{1}{2}\sqrt[6]{3}(\sqrt{3} - 3i)\sqrt[3]{x^6(\log(x) + c_1)^2}}$$

$$y(x) \rightarrow -\sqrt{-x^2 + 3^{2/3}\sqrt[3]{x^6(\log(x) + c_1)^2}}$$

$$y(x) \rightarrow \sqrt{-x^2 + 3^{2/3}\sqrt[3]{x^6(\log(x) + c_1)^2}}$$

4.14 problem 14

4.14.1 Solving as first order ode lie symmetry calculated ode 622

Internal problem ID [11627]

Internal file name [OUTPUT/10609_Saturday_May_27_2023_03_05_26_AM_83606361/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.2 (Separable equations). Exercises page 47

Problem number: 14.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"first_order_ode_lie_symmetry_calculated"**

Maple gives the following as the ode type

```
[[_homogeneous, `class C`], _dAlembert]
```

$$\sqrt{y+x} + \sqrt{-y+x} + (\sqrt{-y+x} - \sqrt{y+x}) y' = 0$$

4.14.1 Solving as first order ode lie symmetry calculated ode

Writing the ode as

$$y' = -\frac{\sqrt{y+x} + \sqrt{-y+x}}{\sqrt{-y+x} - \sqrt{y+x}}$$
$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is not in the lookup table. To determine ξ, η then (A) is solved using ansatz. Making bivariate polynomials of degree 1 to use as anstaz gives

$$\xi = xa_2 + ya_3 + a_1 \quad (1\text{E})$$

$$\eta = xb_2 + yb_3 + b_1 \quad (2\text{E})$$

Where the unknown coefficients are

$$\{a_1, a_2, a_3, b_1, b_2, b_3\}$$

Substituting equations (1E,2E) and ω into (A) gives

$$\begin{aligned} b_2 - \frac{(\sqrt{y+x} + \sqrt{-y+x})(b_3 - a_2)}{\sqrt{-y+x} - \sqrt{y+x}} \\ - \frac{(\sqrt{y+x} + \sqrt{-y+x})^2 a_3}{(\sqrt{-y+x} - \sqrt{y+x})^2} - \left(-\frac{\frac{1}{2\sqrt{y+x}} + \frac{1}{2\sqrt{-y+x}}}{\sqrt{-y+x} - \sqrt{y+x}} \right. \\ \left. + \frac{(\sqrt{y+x} + \sqrt{-y+x}) \left(\frac{1}{2\sqrt{-y+x}} - \frac{1}{2\sqrt{y+x}} \right)}{(\sqrt{-y+x} - \sqrt{y+x})^2} \right) (xa_2 + ya_3 + a_1) \\ - \left(-\frac{\frac{1}{2\sqrt{y+x}} - \frac{1}{2\sqrt{-y+x}}}{\sqrt{-y+x} - \sqrt{y+x}} \right. \\ \left. + \frac{(\sqrt{y+x} + \sqrt{-y+x}) \left(-\frac{1}{2\sqrt{-y+x}} - \frac{1}{2\sqrt{y+x}} \right)}{(\sqrt{-y+x} - \sqrt{y+x})^2} \right) (xb_2 + yb_3 + b_1) = 0 \end{aligned} \quad (5E)$$

Putting the above in normal form gives

$$\frac{(y+x)^{\frac{3}{2}} \sqrt{-y+x} a_2 + (y+x)^{\frac{3}{2}} \sqrt{-y+x} a_3 - (y+x)^{\frac{3}{2}} \sqrt{-y+x} b_2 - (y+x)^{\frac{3}{2}} \sqrt{-y+x} b_3 - \sqrt{y+x} (-\sqrt{-y+x})}{(-\sqrt{-y+x})} = 0$$

Setting the numerator to zero gives

$$\begin{aligned} -(y+x)^{\frac{3}{2}} \sqrt{-y+x} a_2 - (y+x)^{\frac{3}{2}} \sqrt{-y+x} a_3 + (y+x)^{\frac{3}{2}} \sqrt{-y+x} b_2 \\ + (y+x)^{\frac{3}{2}} \sqrt{-y+x} b_3 + \sqrt{y+x} (-y+x)^{\frac{3}{2}} a_2 - \sqrt{y+x} (-y+x)^{\frac{3}{2}} a_3 \\ + \sqrt{y+x} (-y+x)^{\frac{3}{2}} b_2 - \sqrt{y+x} (-y+x)^{\frac{3}{2}} b_3 - 2x^2 a_3 \\ - 2xa_2y + 2yb_3x + 2y^2 b_2 + 2b_1x - 2a_1y = 0 \end{aligned} \quad (6E)$$

Simplifying the above gives

$$\begin{aligned}
& -(y+x)^{\frac{3}{2}} \sqrt{-y+x} a_2 - (y+x)^{\frac{3}{2}} \sqrt{-y+x} a_3 + (y+x)^{\frac{3}{2}} \sqrt{-y+x} b_2 \\
& + (y+x)^{\frac{3}{2}} \sqrt{-y+x} b_3 - 2(y+x)(-y+x) a_3 - 2(y+x)(-y+x) b_2 \\
& + \sqrt{y+x}(-y+x)^{\frac{3}{2}} a_2 - \sqrt{y+x}(-y+x)^{\frac{3}{2}} a_3 + \sqrt{y+x}(-y+x)^{\frac{3}{2}} b_2 \\
& - \sqrt{y+x}(-y+x)^{\frac{3}{2}} b_3 - (y+x) x a_2 + (y+x) x b_2 - (y+x) y a_3 \\
& + (y+x) y b_3 + (-y+x) x a_2 + (-y+x) x b_2 + (-y+x) y a_3 \\
& + (-y+x) y b_3 - (y+x) a_1 + (y+x) b_1 + (-y+x) a_1 + (-y+x) b_1 = 0
\end{aligned} \tag{6E}$$

Since the PDE has radicals, simplifying gives

$$\begin{aligned}
& -2\sqrt{y+x} \sqrt{-y+x} a_3 x + 2\sqrt{y+x} \sqrt{-y+x} b_2 x - 2\sqrt{y+x} \sqrt{-y+x} a_2 y \\
& + 2\sqrt{y+x} \sqrt{-y+x} b_3 y - 2x^2 a_3 - 2x a_2 y + 2y b_3 x + 2y^2 b_2 + 2b_1 x - 2a_1 y = 0
\end{aligned}$$

Looking at the above PDE shows the following are all the terms with $\{x, y\}$ in them.

$$\{x, y, \sqrt{-y+x}, \sqrt{y+x}\}$$

The following substitution is now made to be able to collect on all terms with $\{x, y\}$ in them

$$\{x = v_1, y = v_2, \sqrt{-y+x} = v_3, \sqrt{y+x} = v_4\}$$

The above PDE (6E) now becomes

$$\begin{aligned}
& -2v_4 v_3 a_2 v_2 - 2v_4 v_3 a_3 v_1 + 2v_4 v_3 b_2 v_1 + 2v_4 v_3 b_3 v_2 - 2v_1 a_2 v_2 \\
& - 2v_1^2 a_3 + 2v_2^2 b_2 + 2v_2 b_3 v_1 - 2a_1 v_2 + 2b_1 v_1 = 0
\end{aligned} \tag{7E}$$

Collecting the above on the terms v_i introduced, and these are

$$\{v_1, v_2, v_3, v_4\}$$

Equation (7E) now becomes

$$\begin{aligned}
& -2v_1^2 a_3 + (-2a_2 + 2b_3) v_1 v_2 + (-2a_3 + 2b_2) v_1 v_3 v_4 \\
& + 2b_1 v_1 + 2v_2^2 b_2 + (-2a_2 + 2b_3) v_2 v_3 v_4 - 2a_1 v_2 = 0
\end{aligned} \tag{8E}$$

Setting each coefficients in (8E) to zero gives the following equations to solve

$$\begin{aligned}
 -2a_1 &= 0 \\
 -2a_3 &= 0 \\
 2b_1 &= 0 \\
 2b_2 &= 0 \\
 -2a_2 + 2b_3 &= 0 \\
 -2a_3 + 2b_2 &= 0
 \end{aligned}$$

Solving the above equations for the unknowns gives

$$\begin{aligned}
 a_1 &= 0 \\
 a_2 &= b_3 \\
 a_3 &= 0 \\
 b_1 &= 0 \\
 b_2 &= 0 \\
 b_3 &= b_3
 \end{aligned}$$

Substituting the above solution in the anstaz (1E,2E) (using 1 as arbitrary value for any unknown in the RHS) gives

$$\begin{aligned}
 \xi &= x \\
 \eta &= y
 \end{aligned}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Therefore

$$\begin{aligned}
 \frac{dy}{dx} &= \frac{\eta}{\xi} \\
 &= \frac{y}{x} \\
 &= \frac{y}{x}
 \end{aligned}$$

This is easily solved to give

$$y = c_1 x$$

Where now the coordinate R is taken as the constant of integration. Hence

$$R = \frac{y}{x}$$

And S is found from

$$\begin{aligned} dS &= \frac{dx}{\xi} \\ &= \frac{dx}{x} \end{aligned}$$

Integrating gives

$$\begin{aligned} S &= \int \frac{dx}{T} \\ &= \ln(x) \end{aligned}$$

Where the constant of integration is set to zero as we just need one solution. Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{\sqrt{y+x} + \sqrt{-y+x}}{\sqrt{-y+x} - \sqrt{y+x}}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= -\frac{y}{x^2} \\ R_y &= \frac{1}{x} \\ S_x &= \frac{1}{x} \\ S_y &= 0 \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = \frac{(-\sqrt{-y+x} + \sqrt{y+x})x}{(y+x)\sqrt{-y+x} + \sqrt{y+x}(-y+x)} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = \frac{-\sqrt{-1+R} - i\sqrt{1+R}}{(1+R)\sqrt{-1+R} + i\sqrt{1+R}(-1+R)}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = \frac{i\sqrt{-1+R}\sqrt{1+R} \arctan\left(\frac{1}{\sqrt{R^2-1}}\right)}{\sqrt{R^2-1}} - \ln(R) + c_1 \quad (4)$$

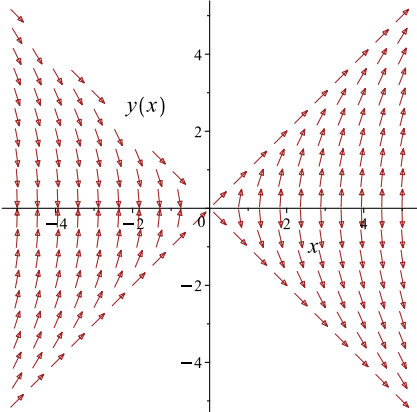
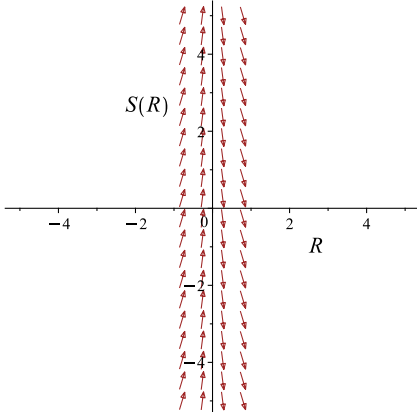
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$\ln(x) = \frac{i\sqrt{\frac{y}{x}-1}\sqrt{\frac{y}{x}+1} \arctan\left(\frac{1}{\sqrt{\frac{y^2}{x^2}-1}}\right)}{\sqrt{\frac{y^2}{x^2}-1}} - \ln\left(\frac{y}{x}\right) + c_1$$

Which simplifies to

$$\ln(x) = \frac{i\sqrt{\frac{y}{x}-1}\sqrt{\frac{y}{x}+1} \arctan\left(\frac{1}{\sqrt{\frac{y^2}{x^2}-1}}\right)}{\sqrt{\frac{y^2}{x^2}-1}} - \ln\left(\frac{y}{x}\right) + c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{\sqrt{y+x} + \sqrt{-y+x}}{\sqrt{-y+x} - \sqrt{y+x}}$ 	$R = \frac{y}{x}$ $S = \ln(x)$	$\frac{dS}{dR} = \frac{-\sqrt{-1+R} - i\sqrt{1+R}}{(1+R)\sqrt{-1+R} + i\sqrt{1+R}(-1+R)}$ 

Summary

The solution(s) found are the following

$$\ln(x) = \frac{i\sqrt{\frac{y}{x}-1}\sqrt{\frac{y}{x}+1}\arctan\left(\frac{1}{\sqrt{\frac{y^2}{x^2}-1}}\right)}{\sqrt{\frac{y^2}{x^2}-1}} - \ln\left(\frac{y}{x}\right) + c_1 \quad (1)$$

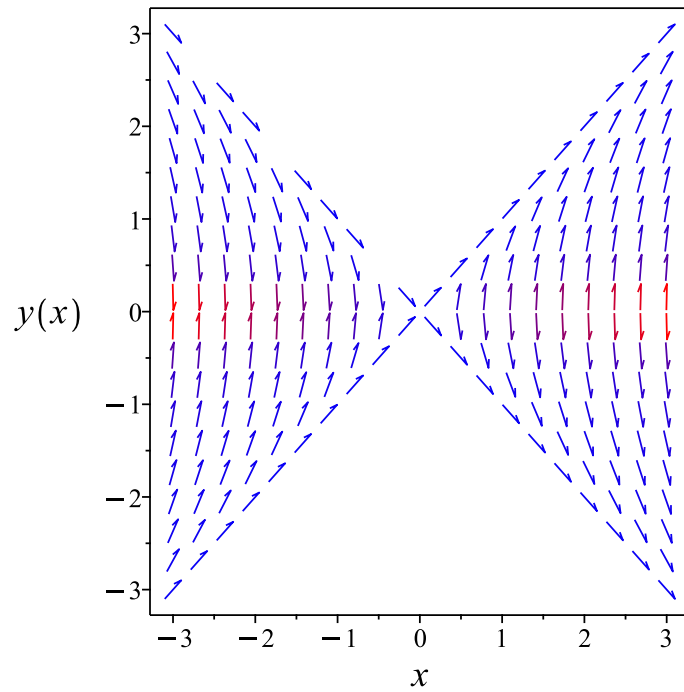


Figure 116: Slope field plot

Verification of solutions

$$\ln(x) = \frac{i\sqrt{\frac{y}{x}-1}\sqrt{\frac{y}{x}+1}\arctan\left(\frac{1}{\sqrt{\frac{y^2}{x^2}-1}}\right)}{\sqrt{\frac{y^2}{x^2}-1}} - \ln\left(\frac{y}{x}\right) + c_1$$

Verified OK.

Maple trace

```
`Methods for first order ODEs:
--- Trying classification methods ---
trying homogeneous types:
trying homogeneous C
trying homogeneous types:
differential order: 1; looking for linear symmetries
differential order: 1; found: 1 linear symmetries. Trying reduction of order
1st order, trying the canonical coordinates of the invariance group
  -> Calling odsolve with the ODE`, diff(y(x), x) = y(x)/x, y(x)`      *** Sublevel 2 ***
      Methods for first order ODEs:
      --- Trying classification methods ---
      trying a quadrature
      trying 1st order linear
      <- 1st order linear successful
<- 1st order, canonical coordinates successful`
```

✓ Solution by Maple

Time used: 2.796 (sec). Leaf size: 36

```
dsolve((sqrt(x+y(x))+sqrt(x-y(x)))+(sqrt(x-y(x))-sqrt(x+y(x)))*diff(y(x),x)=0,y(x), singsol=
```

$$\ln(x) + \ln\left(\frac{y(x)}{x}\right) - \operatorname{arctanh}\left(\frac{1}{\sqrt{\frac{-x^2+y(x)^2}{x^2}}}\right) - c_1 = 0$$

✓ Solution by Mathematica

Time used: 2.828 (sec). Leaf size: 84

```
DSolve[(Sqrt[x+y[x]]+Sqrt[x-y[x]])+(Sqrt[x-y[x]]-Sqrt[x+y[x]])*y'[x]==0,y[x],x,IncludeSingular
```

$$\begin{aligned}y(x) &\rightarrow -\frac{1}{4}\left(\cosh\left(\frac{c_1}{2}\right) + \sinh\left(\frac{c_1}{2}\right)\right)\sqrt{-8ix + \cosh(c_1) + \sinh(c_1)} \\y(x) &\rightarrow \frac{1}{4}\left(\cosh\left(\frac{c_1}{2}\right) + \sinh\left(\frac{c_1}{2}\right)\right)\sqrt{-8ix + \cosh(c_1) + \sinh(c_1)} \\y(x) &\rightarrow 0\end{aligned}$$

4.15 problem 15

4.15.1 Existence and uniqueness analysis	631
4.15.2 Solving as separable ode	632
4.15.3 Solving as first order ode lie symmetry lookup ode	634
4.15.4 Solving as exact ode	638
4.15.5 Maple step by step solution	642

Internal problem ID [11628]

Internal file name [OUTPUT/10610_Saturday_May_27_2023_03_05_35_AM_36326262/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.2 (Separable equations). Exercises page 47

Problem number: 15.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"exact", "separable", "first_order_ode_lie_symmetry_lookup"**

Maple gives the following as the ode type

`[_separable]`

$$y + y(x + 4)y' = -2$$

With initial conditions

$$[y(-3) = -1]$$

4.15.1 Existence and uniqueness analysis

This is non linear first order ODE. In canonical form it is written as

$$\begin{aligned}y' &= f(x, y) \\ &= -\frac{y + 2}{y(x + 4)}\end{aligned}$$

The x domain of $f(x, y)$ when $y = -1$ is

$$\{x < -4 \vee -4 < x\}$$

And the point $x_0 = -3$ is inside this domain. The y domain of $f(x, y)$ when $x = -3$ is

$$\{y < 0 \vee 0 < y\}$$

And the point $y_0 = -1$ is inside this domain. Now we will look at the continuity of

$$\begin{aligned}\frac{\partial f}{\partial y} &= \frac{\partial}{\partial y} \left(-\frac{y+2}{y(x+4)} \right) \\ &= -\frac{1}{y(x+4)} + \frac{y+2}{y^2(x+4)}\end{aligned}$$

The x domain of $\frac{\partial f}{\partial y}$ when $y = -1$ is

$$\{x < -4 \vee -4 < x\}$$

And the point $x_0 = -3$ is inside this domain. The y domain of $\frac{\partial f}{\partial y}$ when $x = -3$ is

$$\{y < 0 \vee 0 < y\}$$

And the point $y_0 = -1$ is inside this domain. Therefore solution exists and is unique.

4.15.2 Solving as separable ode

In canonical form the ODE is

$$\begin{aligned}y' &= F(x, y) \\ &= f(x)g(y) \\ &= -\frac{y+2}{y(x+4)}\end{aligned}$$

Where $f(x) = -\frac{1}{x+4}$ and $g(y) = \frac{y+2}{y}$. Integrating both sides gives

$$\begin{aligned}\frac{1}{\frac{y+2}{y}} dy &= -\frac{1}{x+4} dx \\ \int \frac{1}{\frac{y+2}{y}} dy &= \int -\frac{1}{x+4} dx\end{aligned}$$

$$y - 2 \ln(y+2) = -\ln(x+4) + c_1$$

Which results in

$$y = e^{-\text{LambertW}\left(-\frac{e^{-1+\frac{\ln(x+4)}{2}} - c_1}{2}\right) - 1 + \frac{\ln(x+4)}{2} - \frac{c_1}{2}} - 2$$

Initial conditions are used to solve for c_1 . Substituting $x = -3$ and $y = -1$ in the above solution gives an equation to solve for the constant of integration.

$$-1 = -2 \text{LambertW}\left(-\frac{e^{-1-\frac{c_1}{2}}}{2}\right) - 2$$

$$c_1 = -1$$

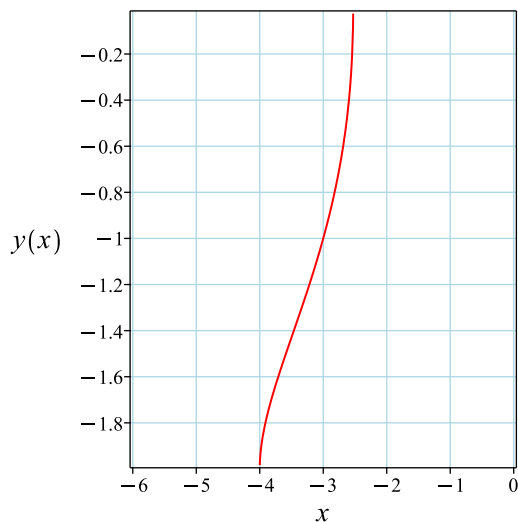
Substituting c_1 found above in the general solution gives

$$y = -2 \text{LambertW}\left(-\frac{e^{-\frac{1}{2}}\sqrt{x+4}}{2}\right) - 2$$

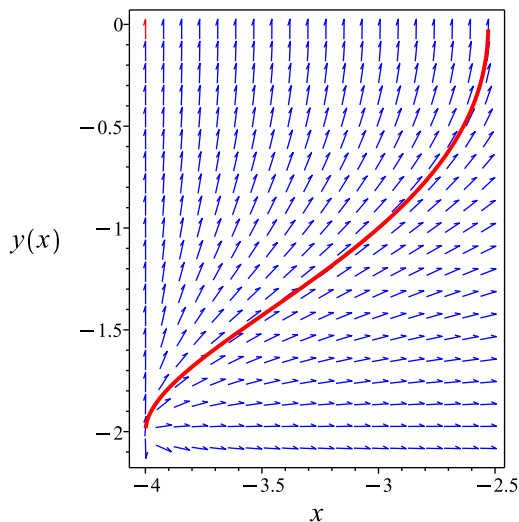
Summary

The solution(s) found are the following

$$y = -2 \text{LambertW}\left(-\frac{e^{-\frac{1}{2}}\sqrt{x+4}}{2}\right) - 2 \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = -2 \operatorname{LambertW} \left(-\frac{e^{-\frac{1}{2}} \sqrt{x+4}}{2} \right) - 2$$

Verified OK.

4.15.3 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = -\frac{y+2}{y(x+4)}$$
$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **separable**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 97: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= -x - 4 \\ \eta(x, y) &= 0\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\eta = 0$ then in this special case

$$R = y$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\xi} dx \\ &= \int \frac{1}{-x-4} dx \end{aligned}$$

Which results in

$$S = -\ln(-x-4)$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{y+2}{y(x+4)}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 0 \\ R_y &= 1 \\ S_x &= \frac{1}{-x-4} \\ S_y &= 0 \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = \frac{y}{y+2} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = \frac{R}{R+2}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = R - 2 \ln(R + 2) + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$-\ln(-x - 4) = y - 2 \ln(y + 2) + c_1$$

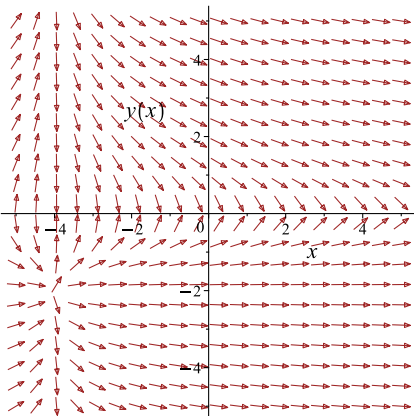
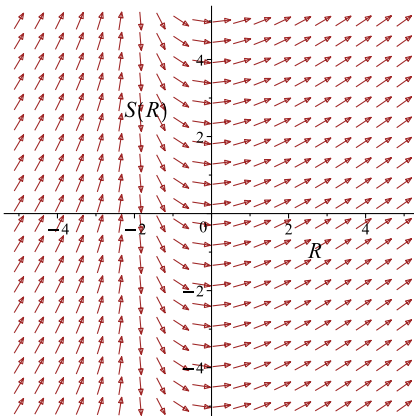
Which simplifies to

$$-\ln(-x - 4) = y - 2 \ln(y + 2) + c_1$$

Which gives

$$y = e^{-\text{LambertW}\left(-e^{\frac{\ln(-x-4) - 1 + c_1}{2}}\right) + \frac{\ln(-x-4) - 1 + c_1}{2}} - 2$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{y+2}{y(x+4)}$ 	$R = y$ $S = -\ln(-x - 4)$	$\frac{dS}{dR} = \frac{R}{R+2}$ 

Initial conditions are used to solve for c_1 . Substituting $x = -3$ and $y = -1$ in the above solution gives an equation to solve for the constant of integration.

$$-1 = -2 \text{LambertW} \left(-\frac{ie^{-1+\frac{c_1}{2}}}{2} \right) - 2$$

$$c_1 = -i\pi + 1$$

Substituting c_1 found above in the general solution gives

$$y = -2 \text{LambertW} \left(\frac{i\sqrt{-x-4}e^{-\frac{1}{2}}}{2} \right) - 2$$

Summary

The solution(s) found are the following

$$y = -2 \text{LambertW} \left(\frac{i\sqrt{-x-4}e^{-\frac{1}{2}}}{2} \right) - 2 \quad (1)$$

Verification of solutions

$$y = -2 \text{LambertW} \left(\frac{i\sqrt{-x-4}e^{-\frac{1}{2}}}{2} \right) - 2$$

Verified OK.

4.15.4 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \quad (A)$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \quad (B)$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (1A)$$

Therefore

$$\begin{aligned}\left(-\frac{y}{y+2}\right) dy &= \left(\frac{1}{x+4}\right) dx \\ \left(-\frac{1}{x+4}\right) dx + \left(-\frac{y}{y+2}\right) dy &= 0\end{aligned} \quad (2A)$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= -\frac{1}{x+4} \\ N(x, y) &= -\frac{y}{y+2}\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y} \left(-\frac{1}{x+4}\right) \\ &= 0\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x} \left(-\frac{y}{y+2} \right) \\ &= 0\end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \tag{1}$$

$$\frac{\partial \phi}{\partial y} = N \tag{2}$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int M dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int -\frac{1}{x+4} dx \\ \phi &= -\ln(x+4) + f(y)\end{aligned} \tag{3}$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = 0 + f'(y) \tag{4}$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = -\frac{y}{y+2}$. Therefore equation (4) becomes

$$-\frac{y}{y+2} = 0 + f'(y) \tag{5}$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = -\frac{y}{y+2}$$

Integrating the above w.r.t y gives

$$\begin{aligned}\int f'(y) dy &= \int \left(-\frac{y}{y+2} \right) dy \\ f(y) &= -y + 2 \ln(y+2) + c_1\end{aligned}$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = -\ln(x+4) - y + 2\ln(y+2) + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -\ln(x+4) - y + 2\ln(y+2)$$

The solution becomes

$$y = e^{-\text{LambertW}\left(-\frac{e^{\frac{\ln(x+4)}{2}-1+\frac{c_1}{2}}}{2}\right) + \frac{\ln(x+4)}{2} - 1 + \frac{c_1}{2}} - 2$$

Initial conditions are used to solve for c_1 . Substituting $x = -3$ and $y = -1$ in the above solution gives an equation to solve for the constant of integration.

$$-1 = -2\text{LambertW}\left(-\frac{e^{-1+\frac{c_1}{2}}}{2}\right) - 2$$

$$c_1 = 1$$

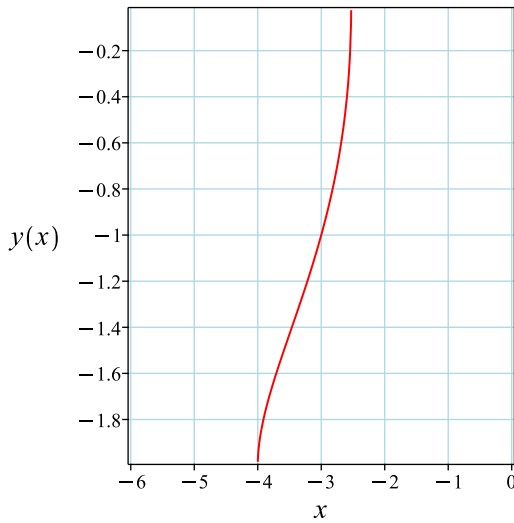
Substituting c_1 found above in the general solution gives

$$y = -2\text{LambertW}\left(-\frac{e^{-\frac{1}{2}}\sqrt{x+4}}{2}\right) - 2$$

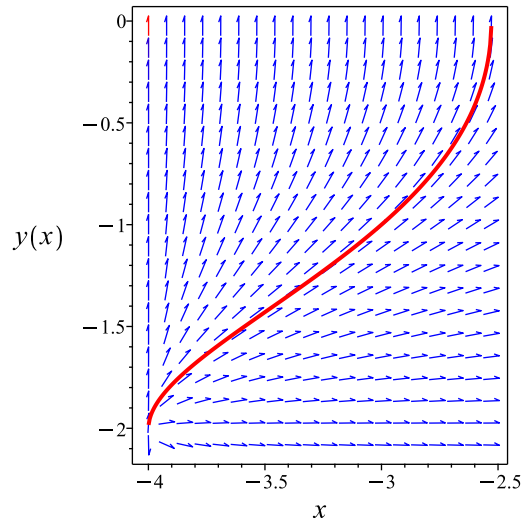
Summary

The solution(s) found are the following

$$y = -2\text{LambertW}\left(-\frac{e^{-\frac{1}{2}}\sqrt{x+4}}{2}\right) - 2 \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = -2 \operatorname{LambertW} \left(-\frac{e^{-\frac{1}{2}\sqrt{x+4}}}{2} \right) - 2$$

Verified OK.

4.15.5 Maple step by step solution

Let's solve

$$[y + y(x + 4) y' = -2, y(-3) = -1]$$

- Highest derivative means the order of the ODE is 1

y'

- Separate variables

$$\frac{y'y}{-y-2} = \frac{1}{x+4}$$

- Integrate both sides with respect to x

$$\int \frac{y'y}{-y-2} dx = \int \frac{1}{x+4} dx + c_1$$

- Evaluate integral

$$-y + 2 \ln(y + 2) = \ln(x + 4) + c_1$$

- Solve for y

$$y = e^{-LambertW\left(-\frac{e^{\frac{\ln(x+4)}{2}-1+\frac{c_1}{2}}}{2}\right) + \frac{\ln(x+4)}{2} - 1 + \frac{c_1}{2}} - 2$$

- Use initial condition $y(-3) = -1$

$$-1 = e^{-LambertW\left(-\frac{e^{-1+\frac{c_1}{2}}}{2}\right) - 1 + \frac{c_1}{2}} - 2$$

- Solve for c_1

$$c_1 = 1$$

- Substitute $c_1 = 1$ into general solution and simplify

$$y = -2LambertW\left(-\frac{e^{-\frac{1}{2}\sqrt{x+4}}}{2}\right) - 2$$

- Solution to the IVP

$$y = -2LambertW\left(-\frac{e^{-\frac{1}{2}\sqrt{x+4}}}{2}\right) - 2$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
trying separable
<- separable successful`

```

✓ Solution by Maple

Time used: 0.156 (sec). Leaf size: 18

```
dsolve([(y(x)+2)+(y(x)*(x+4))*diff(y(x),x)=0,y(-3) = -1],y(x), singsol=all)
```

$$y(x) = -2LambertW\left(-\frac{\sqrt{x+4}e^{-\frac{1}{2}}}{2}\right) - 2$$

✓ Solution by Mathematica

Time used: 12.779 (sec). Leaf size: 26

```
DSolve[{(y[x]+2)+(y[x]*(x+4))*y'[x]==0,{y[-3]==-1}},y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow -2 \left(W \left(-\frac{\sqrt{x+4}}{2\sqrt{e}} \right) + 1 \right)$$

4.16 problem 16

4.16.1 Existence and uniqueness analysis	645
4.16.2 Solving as separable ode	646
4.16.3 Solving as first order ode lie symmetry lookup ode	648
4.16.4 Solving as exact ode	652
4.16.5 Maple step by step solution	656

Internal problem ID [11629]

Internal file name [OUTPUT/10611_Saturday_May_27_2023_03_05_45_AM_99833809/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.2 (Separable equations). Exercises page 47

Problem number: 16.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"exact", "separable", "first_order_ode_lie_symmetry_lookup"**

Maple gives the following as the ode type

`[_separable]`

$$8 \cos (y)^2 + \csc (x)^2 y' = 0$$

With initial conditions

$$\left[y\left(\frac{\pi}{12}\right) = \frac{\pi}{4} \right]$$

4.16.1 Existence and uniqueness analysis

This is non linear first order ODE. In canonical form it is written as

$$\begin{aligned} y' &= f(x, y) \\ &= -\frac{8 \cos (y)^2}{\csc (x)^2} \end{aligned}$$

The x domain of $f(x, y)$ when $y = \frac{\pi}{4}$ is

$$\{x < \pi_{Z95} \vee \pi_{Z95} < x\}$$

And the point $x_0 = \frac{\pi}{12}$ is inside this domain. The y domain of $f(x, y)$ when $x = \frac{\pi}{12}$ is

$$\{-\infty < y < \infty\}$$

And the point $y_0 = \frac{\pi}{4}$ is inside this domain. Now we will look at the continuity of

$$\begin{aligned} \frac{\partial f}{\partial y} &= \frac{\partial}{\partial y} \left(-\frac{8 \cos(y)^2}{\csc(x)^2} \right) \\ &= \frac{16 \cos(y) \sin(y)}{\csc(x)^2} \end{aligned}$$

The x domain of $\frac{\partial f}{\partial y}$ when $y = \frac{\pi}{4}$ is

$$\{x < \pi \vee \pi < x\}$$

And the point $x_0 = \frac{\pi}{12}$ is inside this domain. The y domain of $\frac{\partial f}{\partial y}$ when $x = \frac{\pi}{12}$ is

$$\{-\infty < y < \infty\}$$

And the point $y_0 = \frac{\pi}{4}$ is inside this domain. Therefore solution exists and is unique.

4.16.2 Solving as separable ode

In canonical form the ODE is

$$\begin{aligned} y' &= F(x, y) \\ &= f(x)g(y) \\ &= -\frac{8 \cos(y)^2}{\csc(x)^2} \end{aligned}$$

Where $f(x) = -\frac{8}{\csc(x)^2}$ and $g(y) = \cos(y)^2$. Integrating both sides gives

$$\begin{aligned} \frac{1}{\cos(y)^2} dy &= -\frac{8}{\csc(x)^2} dx \\ \int \frac{1}{\cos(y)^2} dy &= \int -\frac{8}{\csc(x)^2} dx \\ \tan(y) &= 4 \cos(x) \sin(x) - 4x + c_1 \end{aligned}$$

Which results in

$$y = \arctan(4 \cos(x) \sin(x) - 4x + c_1)$$

Initial conditions are used to solve for c_1 . Substituting $x = \frac{\pi}{12}$ and $y = \frac{\pi}{4}$ in the above solution gives an equation to solve for the constant of integration.

$$\frac{\pi}{4} = \arctan\left(4 \cos\left(\frac{\pi}{12}\right) \sin\left(\frac{\pi}{12}\right) - \frac{\pi}{3} + c_1\right)$$

$$c_1 = \frac{\pi}{3}$$

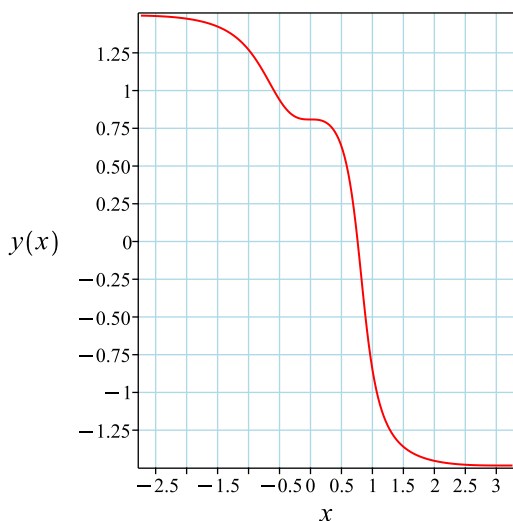
Substituting c_1 found above in the general solution gives

$$y = -\arctan\left(-4 \cos(x) \sin(x) + 4x - \frac{\pi}{3}\right)$$

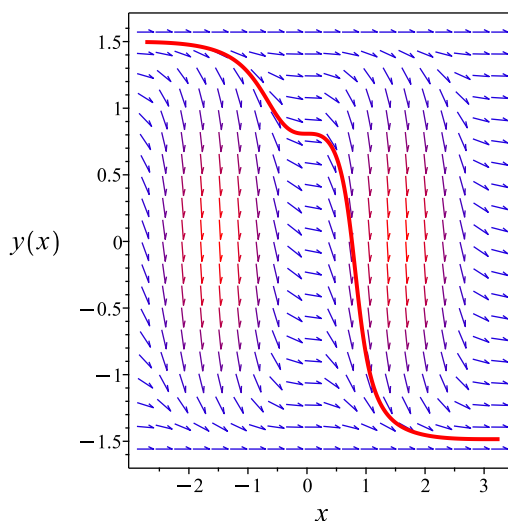
Summary

The solution(s) found are the following

$$y = -\arctan\left(-4 \cos(x) \sin(x) + 4x - \frac{\pi}{3}\right) \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = -\arctan\left(-4 \cos(x) \sin(x) + 4x - \frac{\pi}{3}\right)$$

Verified OK.

4.16.3 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = -\frac{8 \cos(y)^2}{\csc(x)^2}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **separable**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 100: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= -\frac{\csc(x)^2}{8} \\ \eta(x, y) &= 0\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\eta = 0$ then in this special case

$$R = y$$

S is found from

$$\begin{aligned}S &= \int \frac{1}{\xi} dx \\ &= \int \frac{1}{-\frac{\csc(x)^2}{8}} dx\end{aligned}$$

Which results in

$$S = 4 \cos(x) \sin(x) - 4x$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y}\tag{2}$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{8 \cos(y)^2}{\csc(x)^2}$$

Evaluating all the partial derivatives gives

$$\begin{aligned}R_x &= 0 \\R_y &= 1 \\S_x &= -4 + 4 \cos(2x) \\S_y &= 0\end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = \sec(y)^2 \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = \sec(R)^2$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = \tan(R) + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$-4x + 2 \sin(2x) = \tan(y) + c_1$$

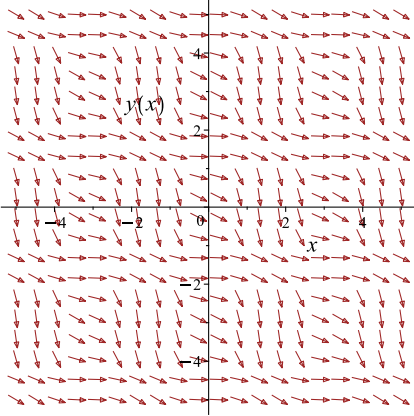
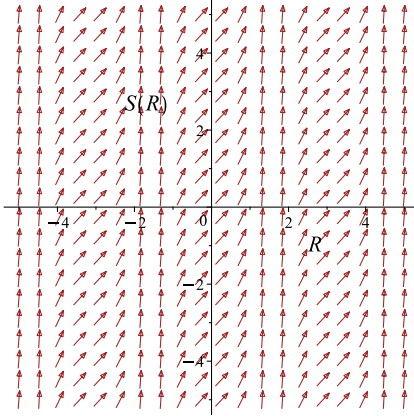
Which simplifies to

$$-4x + 2 \sin(2x) = \tan(y) + c_1$$

Which gives

$$y = -\arctan(4x - 2 \sin(2x) + c_1)$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{8 \cos(y)^2}{\csc(x)^2}$ 	$R = y$ $S = -4x + 2 \sin(2x)$	$\frac{dS}{dR} = \sec(R)^2$ 

Initial conditions are used to solve for c_1 . Substituting $x = \frac{\pi}{12}$ and $y = \frac{\pi}{4}$ in the above solution gives an equation to solve for the constant of integration.

$$\frac{\pi}{4} = -\arctan\left(\frac{\pi}{3} - 1 + c_1\right)$$

$$c_1 = -\frac{\pi}{3}$$

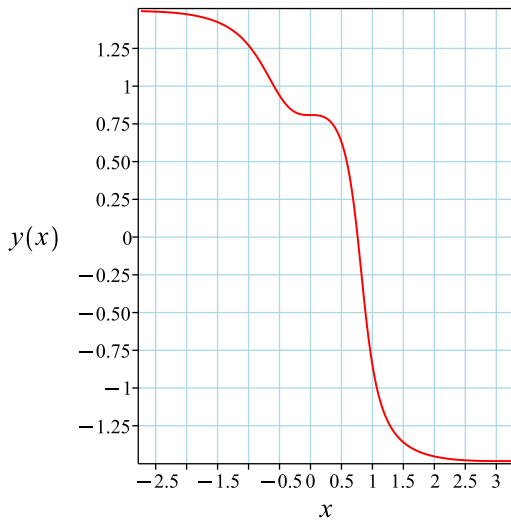
Substituting c_1 found above in the general solution gives

$$y = -\arctan\left(4x - \frac{\pi}{3} - 2 \sin(2x)\right)$$

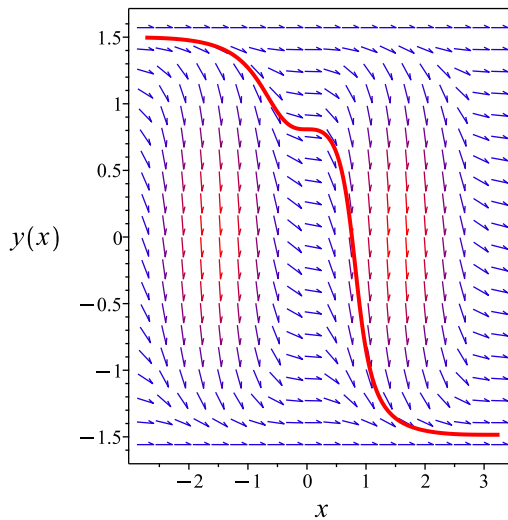
Summary

The solution(s) found are the following

$$y = -\arctan\left(4x - \frac{\pi}{3} - 2 \sin(2x)\right) \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = -\arctan\left(4x - \frac{\pi}{3} - 2\sin(2x)\right)$$

Verified OK.

4.16.4 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx}\phi(x, y) = 0$$

Hence

$$\frac{\partial\phi}{\partial x} + \frac{\partial\phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial\phi}{\partial x} &= M \\ \frac{\partial\phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (1A)$$

Therefore

$$\begin{aligned} \left(-\frac{1}{8 \cos(y)^2}\right) dy &= \left(\frac{1}{\csc(x)^2}\right) dx \\ \left(-\frac{1}{\csc(x)^2}\right) dx + \left(-\frac{1}{8 \cos(y)^2}\right) dy &= 0 \end{aligned} \quad (2A)$$

Comparing (1A) and (2A) shows that

$$\begin{aligned} M(x, y) &= -\frac{1}{\csc(x)^2} \\ N(x, y) &= -\frac{1}{8 \cos(y)^2} \end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned} \frac{\partial M}{\partial y} &= \frac{\partial}{\partial y} \left(-\frac{1}{\csc(x)^2}\right) \\ &= 0 \end{aligned}$$

And

$$\begin{aligned} \frac{\partial N}{\partial x} &= \frac{\partial}{\partial x} \left(-\frac{1}{8 \cos(y)^2}\right) \\ &= 0 \end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \quad (1)$$

$$\frac{\partial \phi}{\partial y} = N \quad (2)$$

Integrating (1) w.r.t. x gives

$$\begin{aligned} \int \frac{\partial \phi}{\partial x} dx &= \int M dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int -\frac{1}{\csc(x)^2} dx \\ \phi &= \frac{\sin(2x)}{4} - \frac{x}{2} + f(y) \end{aligned} \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = 0 + f'(y) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = -\frac{1}{8 \cos(y)^2}$. Therefore equation (4) becomes

$$-\frac{1}{8 \cos(y)^2} = 0 + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = -\frac{1}{8 \cos(y)^2}$$

Integrating the above w.r.t y gives

$$\int f'(y) dy = \int \left(-\frac{\sec(y)^2}{8} \right) dy$$

$$f(y) = -\frac{\tan(y)}{8} + c_1$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = \frac{\sin(2x)}{4} - \frac{x}{2} - \frac{\tan(y)}{8} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = \frac{\sin(2x)}{4} - \frac{x}{2} - \frac{\tan(y)}{8}$$

Initial conditions are used to solve for c_1 . Substituting $x = \frac{\pi}{12}$ and $y = \frac{\pi}{4}$ in the above solution gives an equation to solve for the constant of integration.

$$-\frac{\pi}{24} = c_1$$

$$c_1 = -\frac{\pi}{24}$$

Substituting c_1 found above in the general solution gives

$$\frac{\sin(2x)}{4} - \frac{x}{2} - \frac{\tan(y)}{8} = -\frac{\pi}{24}$$

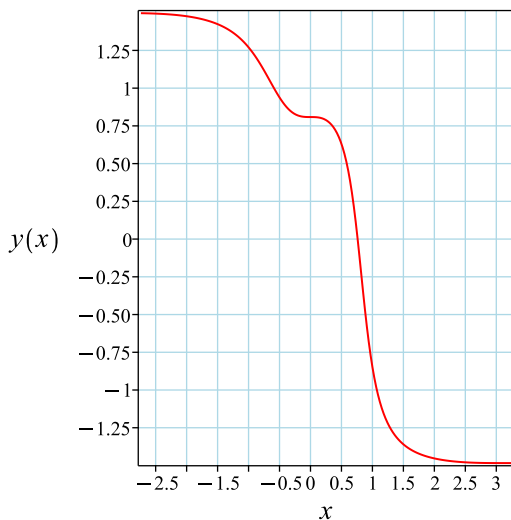
Solving for y from the above gives

$$y = -\arctan\left(4x - \frac{\pi}{3} - 2\sin(2x)\right)$$

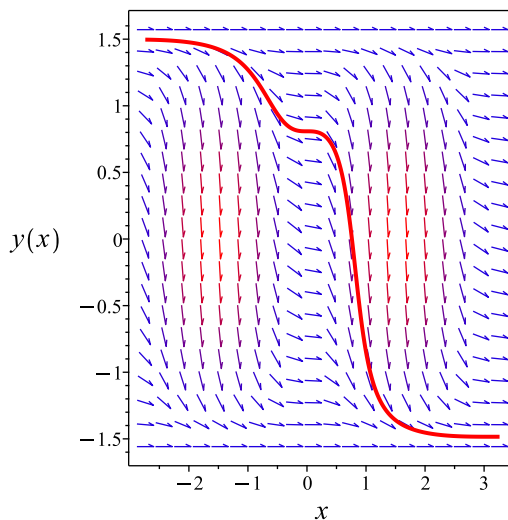
Summary

The solution(s) found are the following

$$y = -\arctan\left(4x - \frac{\pi}{3} - 2\sin(2x)\right) \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = -\arctan\left(4x - \frac{\pi}{3} - 2\sin(2x)\right)$$

Verified OK.

4.16.5 Maple step by step solution

Let's solve

$$\left[8 \cos(y)^2 + \csc(x)^2 y' = 0, y\left(\frac{\pi}{12}\right) = \frac{\pi}{4}\right]$$

- Highest derivative means the order of the ODE is 1

y'

- Separate variables

$$\frac{y'}{\cos(y)^2} = -\frac{8}{\csc(x)^2}$$

- Integrate both sides with respect to x

$$\int \frac{y'}{\cos(y)^2} dx = \int -\frac{8}{\csc(x)^2} dx + c_1$$

- Evaluate integral

$$\tan(y) = 4 \cos(x) \sin(x) - 4x + c_1$$

- Solve for y

$$y = \arctan(4 \cos(x) \sin(x) - 4x + c_1)$$

- Use initial condition $y\left(\frac{\pi}{12}\right) = \frac{\pi}{4}$
 $\frac{\pi}{4} = \arctan\left(4 \cos\left(\frac{\pi}{12}\right) \sin\left(\frac{\pi}{12}\right) - \frac{\pi}{3} + c_1\right)$
- Solve for c_1
 $c_1 = -4 \cos\left(\frac{\pi}{12}\right) \sin\left(\frac{\pi}{12}\right) + \frac{\pi}{3} + 1$
- Substitute $c_1 = -4 \cos\left(\frac{\pi}{12}\right) \sin\left(\frac{\pi}{12}\right) + \frac{\pi}{3} + 1$ into general solution and simplify
 $y = -\arctan\left(4x - \frac{\pi}{3} - 2 \sin(2x)\right)$
- Solution to the IVP
 $y = -\arctan\left(4x - \frac{\pi}{3} - 2 \sin(2x)\right)$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
trying separable
<- separable successful`

```

✓ Solution by Maple

Time used: 0.156 (sec). Leaf size: 20

```
dsolve([(8*cos(y(x))^2)+csc(x)^2*diff(y(x),x)=0,y(1/12*Pi) = 1/4*Pi],y(x), singsol=all)
```

$$y(x) = -\arctan\left(-\frac{\pi}{3} + 4x - 2 \sin(2x)\right)$$

✓ Solution by Mathematica

Time used: 1.156 (sec). Leaf size: 21

```
DSolve[{(8*Cos[y[x]]^2)+Csc[x]^2*y'[x]==0,{y[Pi/12]==Pi/4}},y[x],x,IncludeSingularSolutions
```

$$y(x) \rightarrow \arctan\left(-4x + 2 \sin(2x) + \frac{\pi}{3}\right)$$

4.17 problem 17

4.17.1 Existence and uniqueness analysis	658
4.17.2 Solving as separable ode	659
4.17.3 Solving as first order ode lie symmetry lookup ode	661
4.17.4 Solving as bernoulli ode	666
4.17.5 Solving as exact ode	669
4.17.6 Maple step by step solution	673

Internal problem ID [11630]

Internal file name [OUTPUT/10612_Saturday_May_27_2023_03_05_49_AM_45469359/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 2, section 2.2 (Separable equations). Exercises page 47

Problem number: 17.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact", "bernoulli", "separable", "first_order_ode_lie_symmetry_lookup"

Maple gives the following as the ode type

[_separable]

$$(3x + 8)(y^2 + 4) - 4y(x^2 + 5x + 6)y' = 0$$

With initial conditions

$$[y(1) = 2]$$

4.17.1 Existence and uniqueness analysis

This is non linear first order ODE. In canonical form it is written as

$$\begin{aligned}y' &= f(x, y) \\ &= \frac{3xy^2 + 8y^2 + 12x + 32}{4y(x^2 + 5x + 6)}\end{aligned}$$

The x domain of $f(x, y)$ when $y = 2$ is

$$\{-\infty \leq x < -3, -3 < x < -2, -2 < x \leq \infty\}$$

And the point $x_0 = 1$ is inside this domain. The y domain of $f(x, y)$ when $x = 1$ is

$$\{y < 0 \vee 0 < y\}$$

And the point $y_0 = 2$ is inside this domain. Now we will look at the continuity of

$$\begin{aligned} \frac{\partial f}{\partial y} &= \frac{\partial}{\partial y} \left(\frac{3xy^2 + 8y^2 + 12x + 32}{4y(x^2 + 5x + 6)} \right) \\ &= \frac{6xy + 16y}{4y(x^2 + 5x + 6)} - \frac{3xy^2 + 8y^2 + 12x + 32}{4y^2(x^2 + 5x + 6)} \end{aligned}$$

The x domain of $\frac{\partial f}{\partial y}$ when $y = 2$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 1$ is inside this domain. The y domain of $\frac{\partial f}{\partial y}$ when $x = 1$ is

$$\{y < 0 \vee 0 < y\}$$

And the point $y_0 = 2$ is inside this domain. Therefore solution exists and is unique.

4.17.2 Solving as separable ode

In canonical form the ODE is

$$\begin{aligned} y' &= F(x, y) \\ &= f(x)g(y) \\ &= \frac{(y^2 + 4)(3x + 8)}{4y(x + 3)(x + 2)} \end{aligned}$$

Where $f(x) = \frac{3x+8}{4(x+3)(x+2)}$ and $g(y) = \frac{y^2+4}{y}$. Integrating both sides gives

$$\begin{aligned} \frac{1}{\frac{y^2+4}{y}} dy &= \frac{3x+8}{4(x+3)(x+2)} dx \\ \int \frac{1}{\frac{y^2+4}{y}} dy &= \int \frac{3x+8}{4(x+3)(x+2)} dx \\ \frac{\ln(y^2+4)}{2} &= \frac{\ln(x+3)}{4} + \frac{\ln(x+2)}{2} + c_1 \end{aligned}$$

Raising both side to exponential gives

$$\sqrt{y^2 + 4} = e^{\frac{\ln(x+3)}{4} + \frac{\ln(x+2)}{2} + c_1}$$

Which simplifies to

$$\sqrt{y^2 + 4} = c_2 e^{\frac{\ln(x+3)}{4} + \frac{\ln(x+2)}{2}}$$

Which can be simplified to become

$$\sqrt{y^2 + 4} = c_2 (x + 3)^{\frac{1}{4}} \sqrt{x + 2} e^{c_1}$$

The solution is

$$\sqrt{y^2 + 4} = c_2 (x + 3)^{\frac{1}{4}} \sqrt{x + 2} e^{c_1}$$

Initial conditions are used to solve for c_1 . Substituting $x = 1$ and $y = 2$ in the above solution gives an equation to solve for the constant of integration.

$$2\sqrt{2} = 4^{\frac{1}{4}} \sqrt{3} e^{c_1} c_2$$

$$c_1 = \frac{\ln\left(\frac{4}{3c_2^2}\right)}{2}$$

Substituting c_1 found above in the general solution gives

$$\sqrt{y^2 + 4} = \frac{2c_2 \sqrt{x + 2} (x + 3)^{\frac{1}{4}} \sqrt{3} \sqrt{\frac{1}{c_2^2}}}{3}$$

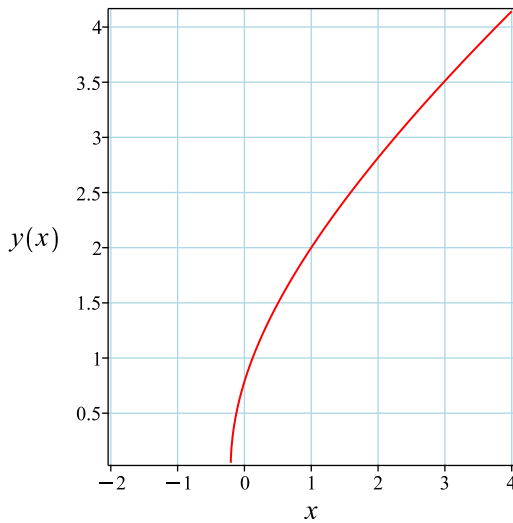
Solving for y from the above gives

$$y = \frac{2\sqrt{-9 + (3x + 6)\sqrt{x + 3}}}{3}$$

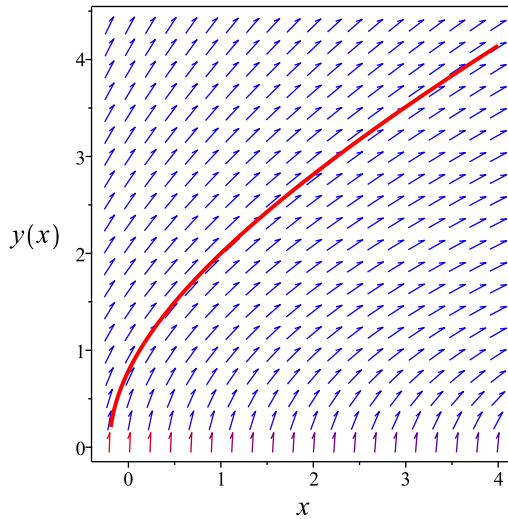
Summary

The solution(s) found are the following

$$y = \frac{2\sqrt{-9 + (3x + 6)\sqrt{x + 3}}}{3} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \frac{2\sqrt{-9 + (3x + 6)\sqrt{x + 3}}}{3}$$

Verified OK. {positive}

4.17.3 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = \frac{3x y^2 + 8y^2 + 12x + 32}{4y(x^2 + 5x + 6)}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **separable**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 103: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= \frac{4(x+3)(x+2)}{3x+8} \\ \eta(x, y) &= 0\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\eta = 0$ then in this special case

$$R = y$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\xi} dx \\ &= \int \frac{1}{\frac{4(x+3)(x+2)}{3x+8}} dx \end{aligned}$$

Which results in

$$S = \frac{\ln(x+3)}{4} + \frac{\ln(x+2)}{2}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = \frac{3xy^2 + 8y^2 + 12x + 32}{4y(x^2 + 5x + 6)}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 0 \\ R_y &= 1 \\ S_x &= \frac{3x+8}{4(x+3)(x+2)} \\ S_y &= 0 \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = \frac{y}{y^2 + 4} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = \frac{R}{R^2 + 4}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = \frac{\ln(R^2 + 4)}{2} + c_1 \quad (4)$$

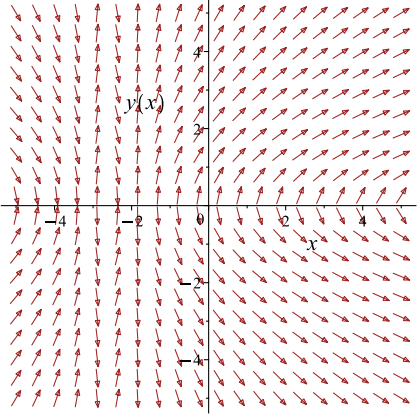
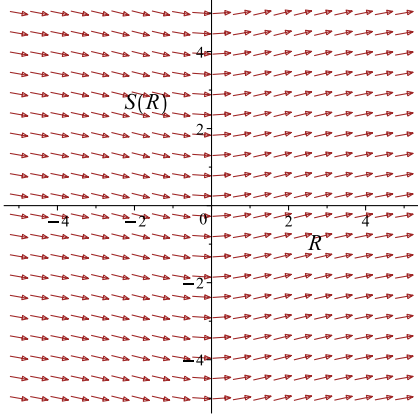
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$\frac{\ln(x+3)}{4} + \frac{\ln(x+2)}{2} = \frac{\ln(y^2+4)}{2} + c_1$$

Which simplifies to

$$\frac{\ln(x+3)}{4} + \frac{\ln(x+2)}{2} = \frac{\ln(y^2+4)}{2} + c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = \frac{3xy^2 + 8y^2 + 12x + 32}{4y(x^2 + 5x + 6)}$ 	$R = y$ $S = \frac{\ln(x+3)}{4} + \frac{\ln(x+2)}{2}$	$\frac{dS}{dR} = \frac{R}{R^2 + 4}$ 

Initial conditions are used to solve for c_1 . Substituting $x = 1$ and $y = 2$ in the above solution gives an equation to solve for the constant of integration.

$$\frac{\ln(2)}{2} + \frac{\ln(3)}{2} = \frac{3 \ln(2)}{2} + c_1$$

$$c_1 = -\ln(2) + \frac{\ln(3)}{2}$$

Substituting c_1 found above in the general solution gives

$$\frac{\ln(x+3)}{4} + \frac{\ln(x+2)}{2} = \frac{\ln(y^2+4)}{2} - \ln(2) + \frac{\ln(3)}{2}$$

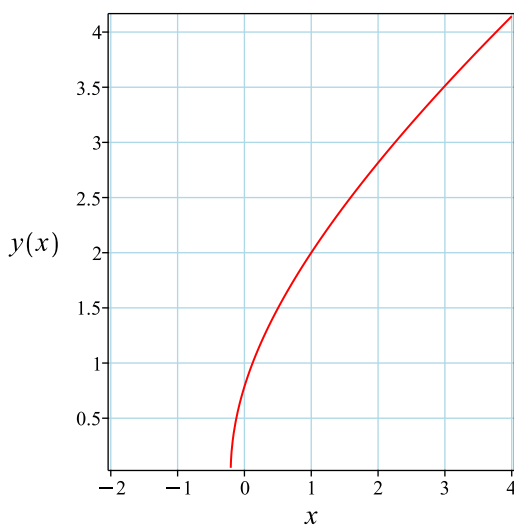
Solving for y from the above gives

$$y = \frac{2\sqrt{-9 + (3x+6)\sqrt{x+3}}}{3}$$

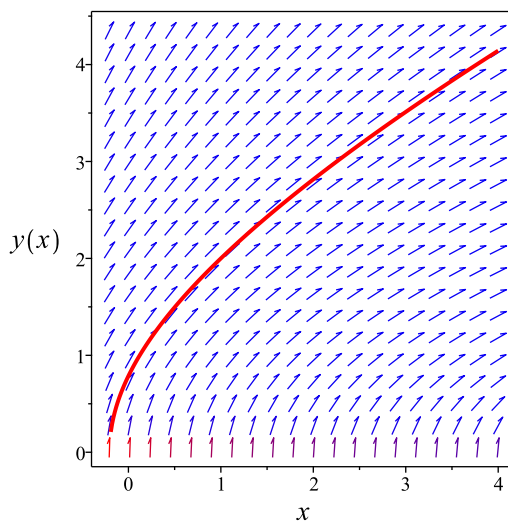
Summary

The solution(s) found are the following

$$y = \frac{2\sqrt{-9 + (3x+6)\sqrt{x+3}}}{3} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \frac{2\sqrt{-9 + (3x+6)\sqrt{x+3}}}{3}$$

Verified OK. {positive}

4.17.4 Solving as bernoulli ode

In canonical form, the ODE is

$$\begin{aligned}y' &= F(x, y) \\ &= \frac{3x y^2 + 8y^2 + 12x + 32}{4y(x^2 + 5x + 6)}\end{aligned}$$

This is a Bernoulli ODE.

$$y' = \frac{3x + 8}{4x^2 + 20x + 24}y + \frac{12x + 32}{4x^2 + 20x + 24} \frac{1}{y} \quad (1)$$

The standard Bernoulli ODE has the form

$$y' = f_0(x)y + f_1(x)y^n \quad (2)$$

The first step is to divide the above equation by y^n which gives

$$\frac{y'}{y^n} = f_0(x)y^{1-n} + f_1(x) \quad (3)$$

The next step is use the substitution $w = y^{1-n}$ in equation (3) which generates a new ODE in $w(x)$ which will be linear and can be easily solved using an integrating factor. Backsubstitution then gives the solution $y(x)$ which is what we want.

This method is now applied to the ODE at hand. Comparing the ODE (1) With (2) Shows that

$$\begin{aligned}f_0(x) &= \frac{3x + 8}{4x^2 + 20x + 24} \\ f_1(x) &= \frac{12x + 32}{4x^2 + 20x + 24} \\ n &= -1\end{aligned}$$

Dividing both sides of ODE (1) by $y^n = \frac{1}{y}$ gives

$$y'y = \frac{(3x + 8)y^2}{4x^2 + 20x + 24} + \frac{12x + 32}{4x^2 + 20x + 24} \quad (4)$$

Let

$$\begin{aligned}w &= y^{1-n} \\ &= y^2\end{aligned} \quad (5)$$

Taking derivative of equation (5) w.r.t x gives

$$w' = 2yy' \quad (6)$$

Substituting equations (5) and (6) into equation (4) gives

$$\begin{aligned}\frac{w'(x)}{2} &= \frac{(3x+8)w(x)}{4x^2+20x+24} + \frac{12x+32}{4x^2+20x+24} \\ w' &= \frac{(3x+8)w}{2x^2+10x+12} + \frac{12x+32}{2x^2+10x+12}\end{aligned}\tag{7}$$

The above now is a linear ODE in $w(x)$ which is now solved.

Entering Linear first order ODE solver. In canonical form a linear first order is

$$w'(x) + p(x)w(x) = q(x)$$

Where here

$$\begin{aligned}p(x) &= -\frac{3x+8}{2x^2+10x+12} \\ q(x) &= \frac{6x+16}{x^2+5x+6}\end{aligned}$$

Hence the ode is

$$w'(x) - \frac{(3x+8)w(x)}{2x^2+10x+12} = \frac{6x+16}{x^2+5x+6}$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int -\frac{3x+8}{2x^2+10x+12} dx} \\ &= e^{-\frac{\ln(x+3)}{2} - \ln(x+2)}\end{aligned}$$

Which simplifies to

$$\mu = \frac{1}{\sqrt{x+3}(x+2)}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu w) &= (\mu) \left(\frac{6x+16}{x^2+5x+6} \right) \\ \frac{d}{dx} \left(\frac{w}{\sqrt{x+3}(x+2)} \right) &= \left(\frac{1}{\sqrt{x+3}(x+2)} \right) \left(\frac{6x+16}{x^2+5x+6} \right) \\ d \left(\frac{w}{\sqrt{x+3}(x+2)} \right) &= \left(\frac{6x+16}{(x+3)^{\frac{3}{2}}(x+2)^2} \right) dx\end{aligned}$$

Integrating gives

$$\frac{w}{\sqrt{x+3}(x+2)} = \int \frac{6x+16}{(x+3)^{\frac{3}{2}}(x+2)^2} dx$$
$$\frac{w}{\sqrt{x+3}(x+2)} = -\frac{4}{\sqrt{x+3}(x+2)} + c_1$$

Dividing both sides by the integrating factor $\mu = \frac{1}{\sqrt{x+3}(x+2)}$ results in

$$w(x) = -4 + c_1(x+2)\sqrt{x+3}$$

Replacing w in the above by y^2 using equation (5) gives the final solution.

$$y^2 = -4 + c_1(x+2)\sqrt{x+3}$$

Initial conditions are used to solve for c_1 . Substituting $x = 1$ and $y = 2$ in the above solution gives an equation to solve for the constant of integration.

$$4 = -4 + 6c_1$$

$$c_1 = \frac{4}{3}$$

Substituting c_1 found above in the general solution gives

$$y^2 = -4 + \frac{4\sqrt{x+3}x}{3} + \frac{8\sqrt{x+3}}{3}$$

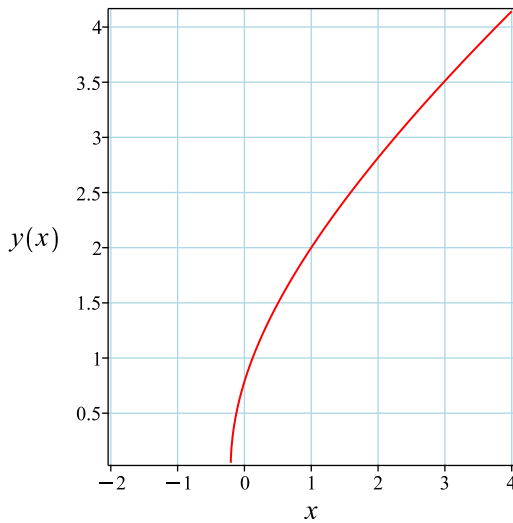
Solving for y from the above gives

$$y = \frac{2\sqrt{-9 + (3x+6)\sqrt{x+3}}}{3}$$

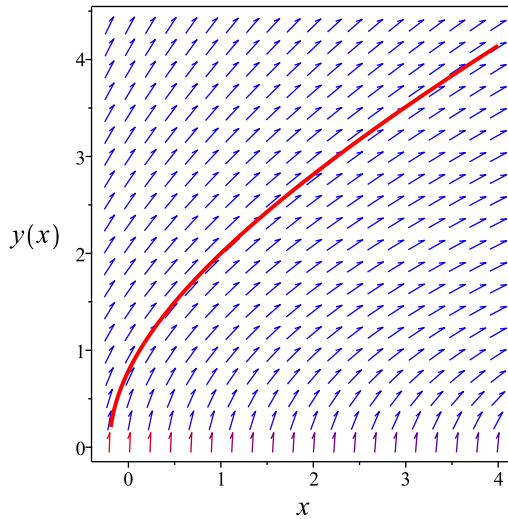
Summary

The solution(s) found are the following

$$y = \frac{2\sqrt{-9 + (3x+6)\sqrt{x+3}}}{3} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \frac{2\sqrt{-9 + (3x + 6)\sqrt{x + 3}}}{3}$$

Verified OK. {positive}

4.17.5 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx}\phi(x, y) = 0$$

Hence

$$\frac{\partial\phi}{\partial x} + \frac{\partial\phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (1A)$$

Therefore

$$\begin{aligned}\left(\frac{4y}{y^2 + 4}\right) dy &= \left(\frac{3x + 8}{(x + 3)(x + 2)}\right) dx \\ \left(-\frac{3x + 8}{(x + 3)(x + 2)}\right) dx &+ \left(\frac{4y}{y^2 + 4}\right) dy = 0\end{aligned} \quad (2A)$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= -\frac{3x + 8}{(x + 3)(x + 2)} \\ N(x, y) &= \frac{4y}{y^2 + 4}\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y} \left(-\frac{3x + 8}{(x + 3)(x + 2)} \right) \\ &= 0\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x} \left(\frac{4y}{y^2 + 4} \right) \\ &= 0\end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \tag{1}$$

$$\frac{\partial \phi}{\partial y} = N \tag{2}$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int M dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int -\frac{3x + 8}{(x + 3)(x + 2)} dx \\ \phi &= -\ln(x + 3) - 2\ln(x + 2) + f(y)\end{aligned} \tag{3}$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = 0 + f'(y) \tag{4}$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = \frac{4y}{y^2 + 4}$. Therefore equation (4) becomes

$$\frac{4y}{y^2 + 4} = 0 + f'(y) \tag{5}$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = \frac{4y}{y^2 + 4}$$

Integrating the above w.r.t y gives

$$\begin{aligned}\int f'(y) dy &= \int \left(\frac{4y}{y^2 + 4} \right) dy \\ f(y) &= 2\ln(y^2 + 4) + c_1\end{aligned}$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = -\ln(x+3) - 2\ln(x+2) + 2\ln(y^2+4) + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -\ln(x+3) - 2\ln(x+2) + 2\ln(y^2+4)$$

Initial conditions are used to solve for c_1 . Substituting $x = 1$ and $y = 2$ in the above solution gives an equation to solve for the constant of integration.

$$4\ln(2) - 2\ln(3) = c_1$$

$$c_1 = 4\ln(2) - 2\ln(3)$$

Substituting c_1 found above in the general solution gives

$$-\ln(x+3) - 2\ln(x+2) + 2\ln(y^2+4) = 4\ln(2) - 2\ln(3)$$

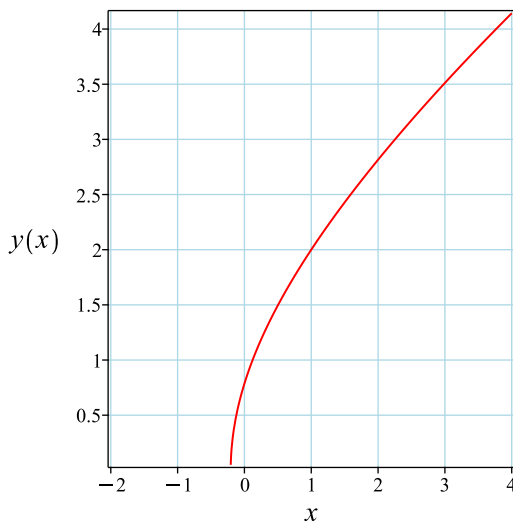
Solving for y from the above gives

$$y = \frac{2\sqrt{-9 + (3x+6)\sqrt{x+3}}}{3}$$

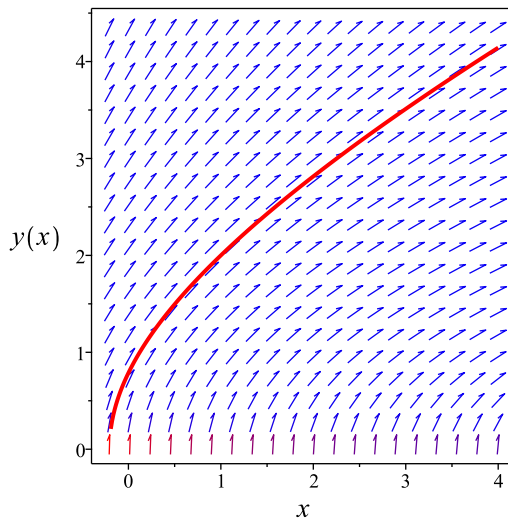
Summary

The solution(s) found are the following

$$y = \frac{2\sqrt{-9 + (3x+6)\sqrt{x+3}}}{3} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \frac{2\sqrt{-9 + (3x + 6)}\sqrt{x + 3}}{3}$$

Verified OK. {positive}

4.17.6 Maple step by step solution

Let's solve

$$[(3x + 8)(y^2 + 4) - 4y(x^2 + 5x + 6)y'] = 0, y(1) = 2]$$

- Highest derivative means the order of the ODE is 1

$$y'$$

- Separate variables

$$\frac{y'y}{y^2+4} = \frac{3x+8}{4(x^2+5x+6)}$$

- Integrate both sides with respect to x

$$\int \frac{y'y}{y^2+4} dx = \int \frac{3x+8}{4(x^2+5x+6)} dx + c_1$$

- Evaluate integral

$$\frac{\ln(y^2+4)}{2} = \frac{\ln(x+3)}{4} + \frac{\ln(x+2)}{2} + c_1$$

- Solve for y

$$\left\{ y = \frac{\sqrt{-e^{-\frac{\ln(x+3)}{2}-2c_1} \left(4e^{-\frac{\ln(x+3)}{2}-2c_1} - x - 2\right)}}{e^{-\frac{\ln(x+3)}{2}-2c_1}}, y = -\frac{\sqrt{-e^{-\frac{\ln(x+3)}{2}-2c_1} \left(4e^{-\frac{\ln(x+3)}{2}-2c_1} - x - 2\right)}}{e^{-\frac{\ln(x+3)}{2}-2c_1}} \right\}$$

- Use initial condition $y(1) = 2$

$$2 = \frac{\sqrt{-e^{-\ln(2)-2c_1} (4e^{-\ln(2)-2c_1} - 3)}}{e^{-\ln(2)-2c_1}}$$

- Solve for c_1

$$c_1 = -\frac{\ln(2)}{2} - \frac{\ln\left(\frac{3}{8}\right)}{2}$$

- Substitute $c_1 = -\frac{\ln(2)}{2} - \frac{\ln\left(\frac{3}{8}\right)}{2}$ into general solution and simplify

$$y = \frac{2\sqrt{3}\sqrt{x+3}\sqrt{\frac{-3+(x+2)\sqrt{x+3}}{x+3}}}{3}$$

- Use initial condition $y(1) = 2$

$$2 = -\frac{\sqrt{-e^{-\ln(2)-2c_1} (4e^{-\ln(2)-2c_1} - 3)}}{e^{-\ln(2)-2c_1}}$$

- Solution does not satisfy initial condition

- Solution to the IVP

$$y = \frac{2\sqrt{3}\sqrt{x+3}\sqrt{\frac{-3+(x+2)\sqrt{x+3}}{x+3}}}{3}$$

Maple trace

```
`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
<- Bernoulli successful`
```

✓ Solution by Maple

Time used: 0.047 (sec). Leaf size: 21

```
dsolve([(3*x+8)*(y(x)^2+4)-4*y(x)*(x^2+5*x+6)*diff(y(x),x)=0,y(1) = 2],y(x), singsol=all)
```

$$y(x) = \frac{2\sqrt{-9 + (3x + 6)\sqrt{x + 3}}}{3}$$

✓ Solution by Mathematica

Time used: 4.88 (sec). Leaf size: 36

```
DSolve[{(3*x+8)*(y[x]^2+4)-4*y[x]*(x^2+5*x+6)*y'[x]==0,{y[1]==2}},y[x],x,IncludeSingularSolu
```

$$y(x) \rightarrow \frac{2\sqrt{\sqrt{x+3}x+2\sqrt{x+3}}-3}{\sqrt{3}}$$

4.18 problem 18

4.18.1 Existence and uniqueness analysis	676
4.18.2 Solving as homogeneousTypeD2 ode	677
4.18.3 Solving as first order ode lie symmetry lookup ode	679
4.18.4 Solving as bernoulli ode	684
4.18.5 Solving as exact ode	687

Internal problem ID [11631]

Internal file name [OUTPUT/10613_Saturday_May_27_2023_03_05_51_AM_85233479/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.2 (Separable equations). Exercises page 47

Problem number: 18.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**bernoulli**", "**homogeneousTypeD2**", "**exactWithIntegrationFactor**", "**first_order_ode_lie_symmetry_lookup**"

Maple gives the following as the ode type

```
[[_homogeneous, `class A`], _rational, _Bernoulli]
```

$$3y^2 - 2xyy' = -x^2$$

With initial conditions

$$[y(2) = 6]$$

4.18.1 Existence and uniqueness analysis

This is non linear first order ODE. In canonical form it is written as

$$y' = f(x, y) = \frac{x^2 + 3y^2}{2xy}$$

The x domain of $f(x, y)$ when $y = 6$ is

$$\{x < 0 \vee 0 < x\}$$

And the point $x_0 = 2$ is inside this domain. The y domain of $f(x, y)$ when $x = 2$ is

$$\{y < 0 \vee 0 < y\}$$

And the point $y_0 = 6$ is inside this domain. Now we will look at the continuity of

$$\begin{aligned} \frac{\partial f}{\partial y} &= \frac{\partial}{\partial y} \left(\frac{x^2 + 3y^2}{2xy} \right) \\ &= \frac{3}{x} - \frac{x^2 + 3y^2}{2x y^2} \end{aligned}$$

The x domain of $\frac{\partial f}{\partial y}$ when $y = 6$ is

$$\{x < 0 \vee 0 < x\}$$

And the point $x_0 = 2$ is inside this domain. The y domain of $\frac{\partial f}{\partial y}$ when $x = 2$ is

$$\{y < 0 \vee 0 < y\}$$

And the point $y_0 = 6$ is inside this domain. Therefore solution exists and is unique.

4.18.2 Solving as homogeneous Type D2 ode

Using the change of variables $y = u(x)x$ on the above ode results in new ode in $u(x)$

$$3u(x)^2 x^2 - 2x^2 u(x) (u'(x)x + u(x)) = -x^2$$

In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= \frac{u^2 + 1}{2ux} \end{aligned}$$

Where $f(x) = \frac{1}{2x}$ and $g(u) = \frac{u^2+1}{u}$. Integrating both sides gives

$$\begin{aligned} \frac{1}{\frac{u^2+1}{u}} du &= \frac{1}{2x} dx \\ \int \frac{1}{\frac{u^2+1}{u}} du &= \int \frac{1}{2x} dx \\ \frac{\ln(u^2 + 1)}{2} &= \frac{\ln(x)}{2} + c_2 \end{aligned}$$

Raising both side to exponential gives

$$\sqrt{u^2 + 1} = e^{\frac{\ln(x)}{2} + c_2}$$

Which simplifies to

$$\sqrt{u^2 + 1} = c_3 \sqrt{x}$$

Which simplifies to

$$\sqrt{u(x)^2 + 1} = c_3 \sqrt{x} e^{c_2}$$

The solution is

$$\sqrt{u(x)^2 + 1} = c_3 \sqrt{x} e^{c_2}$$

Replacing $u(x)$ in the above solution by $\frac{y}{x}$ results in the solution for y in implicit form

$$\begin{aligned}\sqrt{\frac{y^2}{x^2} + 1} &= c_3 \sqrt{x} e^{c_2} \\ \sqrt{\frac{x^2 + y^2}{x^2}} &= c_3 \sqrt{x} e^{c_2}\end{aligned}$$

Substituting initial conditions and solving for c_2 gives $c_2 = \frac{\ln\left(\frac{5}{c_3^2}\right)}{2}$. Hence the solution becomes Initial conditions are used to solve for c_3 . Substituting $x = 2$ and $y = 6$ in the above solution gives an equation to solve for the constant of integration.

$$\sqrt{10} = \sqrt{2} c_3 \sqrt{5} \sqrt{\frac{1}{c_3^2}}$$

This solution is valid for any c_3 . Hence there are infinite number of solutions.

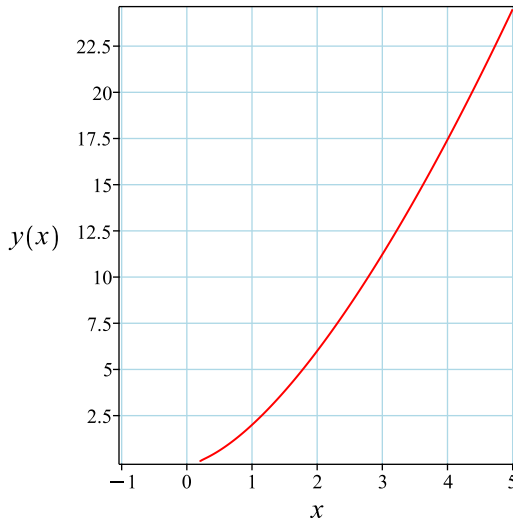
Solving for y from the above gives

$$y = \sqrt{5x - 1} x$$

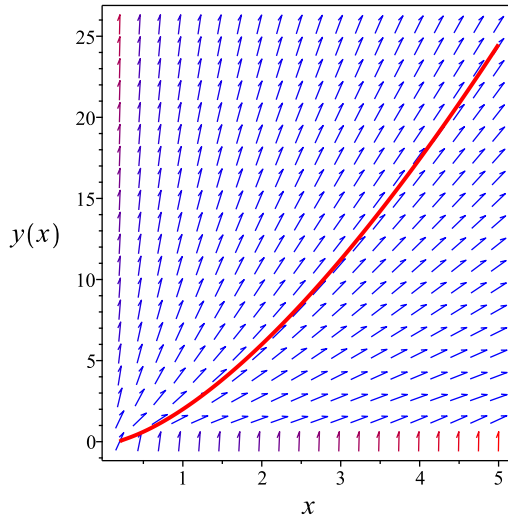
Summary

The solution(s) found are the following

$$y = \sqrt{5x - 1} x \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \sqrt{5x - 1} x$$

Verified OK. {positive}

4.18.3 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = \frac{x^2 + 3y^2}{2xy}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **Bernoulli**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 106: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= \frac{x^3}{y}\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{x^3}{y}} dy \end{aligned}$$

Which results in

$$S = \frac{y^2}{2x^3}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = \frac{x^2 + 3y^2}{2xy}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= -\frac{3y^2}{2x^4} \\ S_y &= \frac{y}{x^3} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = \frac{1}{2x^2} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = \frac{1}{2R^2}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = -\frac{1}{2R} + c_1 \quad (4)$$

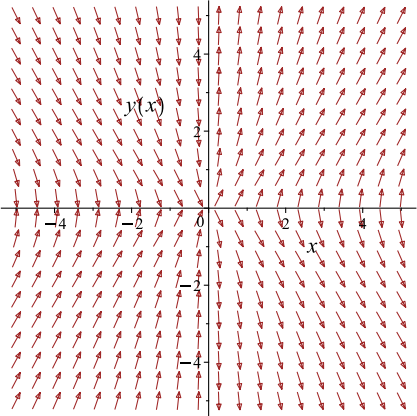
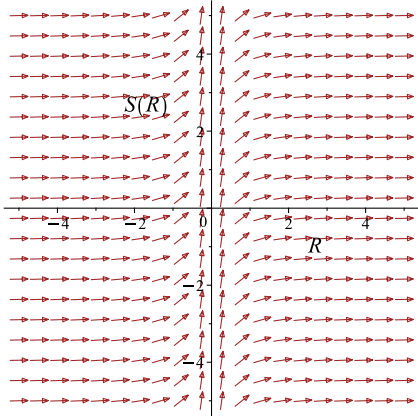
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$\frac{y^2}{2x^3} = -\frac{1}{2x} + c_1$$

Which simplifies to

$$\frac{y^2}{2x^3} = -\frac{1}{2x} + c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = \frac{x^2 + 3y^2}{2xy}$ 	$R = x$ $S = \frac{y^2}{2x^3}$	$\frac{dS}{dR} = \frac{1}{2R^2}$ 

Initial conditions are used to solve for c_1 . Substituting $x = 2$ and $y = 6$ in the above solution gives an equation to solve for the constant of integration.

$$\frac{9}{4} = c_1 - \frac{1}{4}$$

$$c_1 = \frac{5}{2}$$

Substituting c_1 found above in the general solution gives

$$\frac{y^2}{2x^3} = \frac{5x - 1}{2x}$$

The above simplifies to

$$-5x^3 + x^2 + y^2 = 0$$

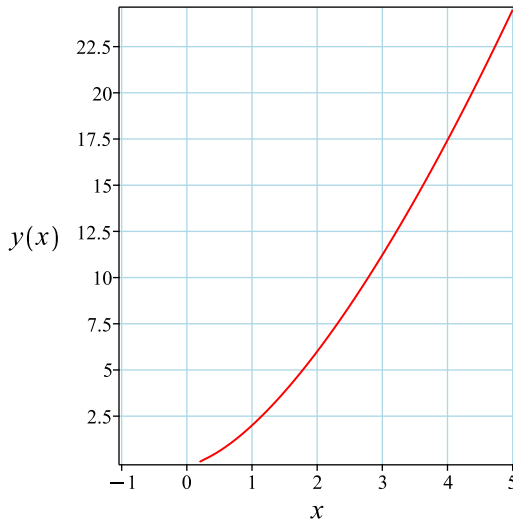
Solving for y from the above gives

$$y = \sqrt{5x - 1} x$$

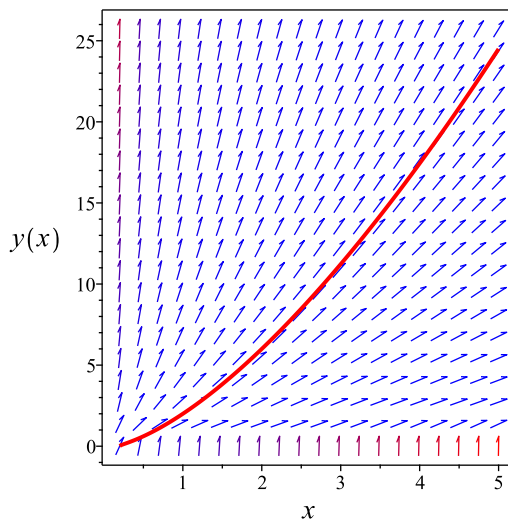
Summary

The solution(s) found are the following

$$y = \sqrt{5x - 1} x \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \sqrt{5x - 1} x$$

Verified OK. {positive}

4.18.4 Solving as bernoulli ode

In canonical form, the ODE is

$$\begin{aligned}y' &= F(x, y) \\ &= \frac{x^2 + 3y^2}{2xy}\end{aligned}$$

This is a Bernoulli ODE.

$$y' = \frac{3}{2x}y + \frac{x}{2} \frac{1}{y} \quad (1)$$

The standard Bernoulli ODE has the form

$$y' = f_0(x)y + f_1(x)y^n \quad (2)$$

The first step is to divide the above equation by y^n which gives

$$\frac{y'}{y^n} = f_0(x)y^{1-n} + f_1(x) \quad (3)$$

The next step is use the substitution $w = y^{1-n}$ in equation (3) which generates a new ODE in $w(x)$ which will be linear and can be easily solved using an integrating factor. Backsubstitution then gives the solution $y(x)$ which is what we want.

This method is now applied to the ODE at hand. Comparing the ODE (1) With (2) Shows that

$$\begin{aligned}f_0(x) &= \frac{3}{2x} \\ f_1(x) &= \frac{x}{2} \\ n &= -1\end{aligned}$$

Dividing both sides of ODE (1) by $y^n = \frac{1}{y}$ gives

$$y'y = \frac{3y^2}{2x} + \frac{x}{2} \quad (4)$$

Let

$$\begin{aligned}w &= y^{1-n} \\ &= y^2\end{aligned} \quad (5)$$

Taking derivative of equation (5) w.r.t x gives

$$w' = 2yy' \quad (6)$$

Substituting equations (5) and (6) into equation (4) gives

$$\begin{aligned}\frac{w'(x)}{2} &= \frac{3w(x)}{2x} + \frac{x}{2} \\ w' &= \frac{3w}{x} + x\end{aligned}\tag{7}$$

The above now is a linear ODE in $w(x)$ which is now solved.

Entering Linear first order ODE solver. In canonical form a linear first order is

$$w'(x) + p(x)w(x) = q(x)$$

Where here

$$\begin{aligned}p(x) &= -\frac{3}{x} \\ q(x) &= x\end{aligned}$$

Hence the ode is

$$w'(x) - \frac{3w(x)}{x} = x$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int -\frac{3}{x} dx} \\ &= \frac{1}{x^3}\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu w) &= (\mu)(x) \\ \frac{d}{dx}\left(\frac{w}{x^3}\right) &= \left(\frac{1}{x^3}\right)(x) \\ d\left(\frac{w}{x^3}\right) &= \frac{1}{x^2} dx\end{aligned}$$

Integrating gives

$$\begin{aligned}\frac{w}{x^3} &= \int \frac{1}{x^2} dx \\ \frac{w}{x^3} &= -\frac{1}{x} + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = \frac{1}{x^3}$ results in

$$w(x) = c_1 x^3 - x^2$$

Replacing w in the above by y^2 using equation (5) gives the final solution.

$$y^2 = c_1 x^3 - x^2$$

Initial conditions are used to solve for c_1 . Substituting $x = 2$ and $y = 6$ in the above solution gives an equation to solve for the constant of integration.

$$36 = 8c_1 - 4$$

$$c_1 = 5$$

Substituting c_1 found above in the general solution gives

$$y^2 = 5x^3 - x^2$$

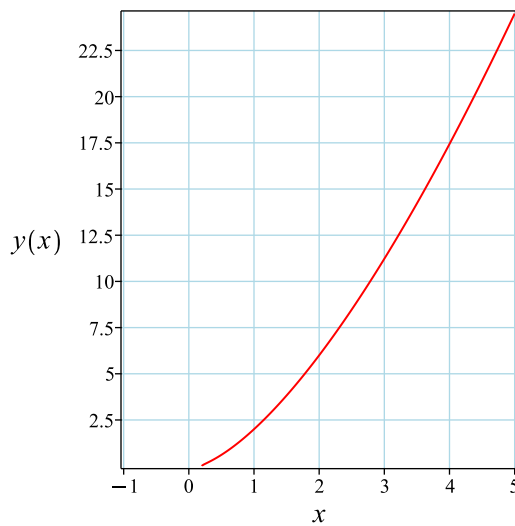
Solving for y from the above gives

$$y = \sqrt{5x - 1} x$$

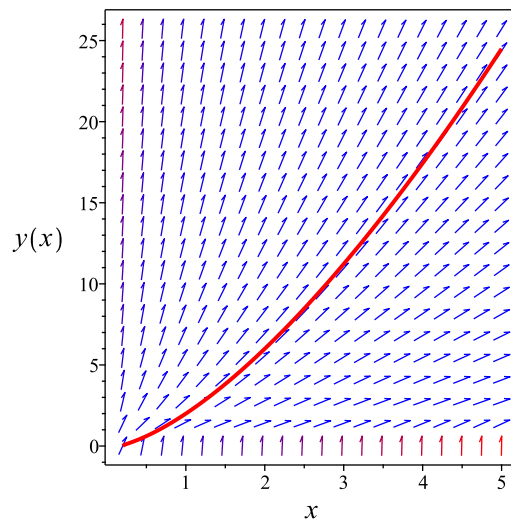
Summary

The solution(s) found are the following

$$y = \sqrt{5x - 1} x \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \sqrt{5x - 1} x$$

Verified OK. {positive}

4.18.5 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \quad (\text{A})$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx}\phi(x, y) = 0$$

Hence

$$\frac{\partial\phi}{\partial x} + \frac{\partial\phi}{\partial y} \frac{dy}{dx} = 0 \quad (\text{B})$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial\phi}{\partial x} &= M \\ \frac{\partial\phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (\text{1A})$$

Therefore

$$\begin{aligned} (-2xy) dy &= (-x^2 - 3y^2) dx \\ (x^2 + 3y^2) dx + (-2xy) dy &= 0 \end{aligned} \quad (\text{2A})$$

Comparing (1A) and (2A) shows that

$$\begin{aligned} M(x, y) &= x^2 + 3y^2 \\ N(x, y) &= -2xy \end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(x^2 + 3y^2) \\ &= 6y\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(-2xy) \\ &= -2y\end{aligned}$$

Since $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$\begin{aligned}A &= \frac{1}{N} \left(\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} \right) \\ &= -\frac{1}{2xy} ((6y) - (-2y)) \\ &= -\frac{4}{x}\end{aligned}$$

Since A does not depend on y , then it can be used to find an integrating factor. The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int A dx} \\ &= e^{\int -\frac{4}{x} dx}\end{aligned}$$

The result of integrating gives

$$\begin{aligned}\mu &= e^{-4 \ln(x)} \\ &= \frac{1}{x^4}\end{aligned}$$

M and N are multiplied by this integrating factor, giving new M and new N which are called \bar{M} and \bar{N} for now so not to confuse them with the original M and N .

$$\begin{aligned}\bar{M} &= \mu M \\ &= \frac{1}{x^4}(x^2 + 3y^2) \\ &= \frac{x^2 + 3y^2}{x^4}\end{aligned}$$

And

$$\begin{aligned}\bar{N} &= \mu N \\ &= \frac{1}{x^4}(-2xy) \\ &= -\frac{2y}{x^3}\end{aligned}$$

Now a modified ODE is obtained from the original ODE, which is exact and can be solved. The modified ODE is

$$\begin{aligned}\bar{M} + \bar{N} \frac{dy}{dx} &= 0 \\ \left(\frac{x^2 + 3y^2}{x^4} \right) + \left(-\frac{2y}{x^3} \right) \frac{dy}{dx} &= 0\end{aligned}$$

The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = \bar{M} \tag{1}$$

$$\frac{\partial \phi}{\partial y} = \bar{N} \tag{2}$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int \bar{M} dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int \frac{x^2 + 3y^2}{x^4} dx \\ \phi &= \frac{-x^2 - y^2}{x^3} + f(y)\end{aligned} \tag{3}$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = -\frac{2y}{x^3} + f'(y) \tag{4}$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = -\frac{2y}{x^3}$. Therefore equation (4) becomes

$$-\frac{2y}{x^3} = -\frac{2y}{x^3} + f'(y) \tag{5}$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 0$$

Therefore

$$f(y) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(y)$ into equation (3) gives ϕ

$$\phi = \frac{-x^2 - y^2}{x^3} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = \frac{-x^2 - y^2}{x^3}$$

Initial conditions are used to solve for c_1 . Substituting $x = 2$ and $y = 6$ in the above solution gives an equation to solve for the constant of integration.

$$-5 = c_1$$

$$c_1 = -5$$

Substituting c_1 found above in the general solution gives

$$\frac{-x^2 - y^2}{x^3} = -5$$

The above simplifies to

$$5x^3 - x^2 - y^2 = 0$$

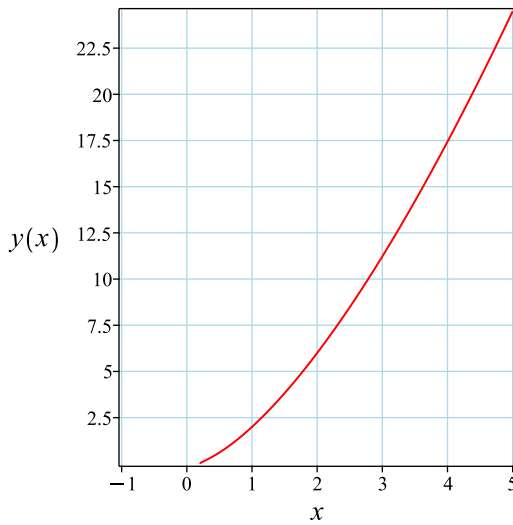
Solving for y from the above gives

$$y = \sqrt{5x - 1} x$$

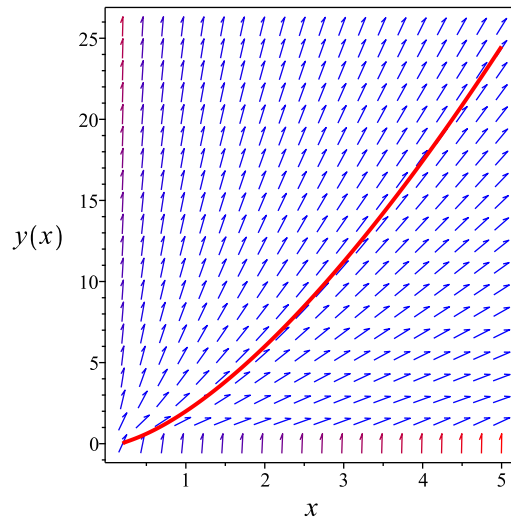
Summary

The solution(s) found are the following

$$y = \sqrt{5x - 1} x \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \sqrt{5x - 1} x$$

Verified OK. {positive}

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
<- Bernoulli successful`

```

✓ Solution by Maple

Time used: 0.062 (sec). Leaf size: 13

```
dsolve([(x^2+3*y(x)^2)-2*x*y(x)*diff(y(x),x)=0,y(2) = 6],y(x), singsol=all)
```

$$y(x) = \sqrt{5x - 1} x$$

✓ Solution by Mathematica

Time used: 0.455 (sec). Leaf size: 16

```
DSolve[{(x^2+3*y[x]^2)-2*x*y[x]*y'[x]==0,{y[2]==6}},y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow x\sqrt{5x-1}$$

4.19 problem 19

4.19.1 Existence and uniqueness analysis	693
4.19.2 Solving as homogeneousTypeD2 ode	694
4.19.3 Solving as first order ode lie symmetry calculated ode	695

Internal problem ID [11632]

Internal file name [OUTPUT/10614_Saturday_May_27_2023_03_06_24_AM_45212028/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 2, section 2.2 (Separable equations). Exercises page 47

Problem number: 19.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**homogeneousTypeD2**", "**first_order_ode_lie_symmetry_calculated**"

Maple gives the following as the ode type

```
[[_homogeneous, `class A`], _rational, [_Abel, `2nd type`, `class A`]]
```

$$-5y + (4x - y)y' = -2x$$

With initial conditions

$$[y(1) = 4]$$

4.19.1 Existence and uniqueness analysis

This is non linear first order ODE. In canonical form it is written as

$$\begin{aligned} y' &= f(x, y) \\ &= -\frac{-2x + 5y}{-4x + y} \end{aligned}$$

The x domain of $f(x, y)$ when $y = 4$ is

$$\{x < 1 \vee 1 < x\}$$

But the point $x_0 = 1$ is not inside this domain. Hence existence and uniqueness theorem does not apply. There could be infinite number of solutions, or one solution or no solution at all.

4.19.2 Solving as homogeneous Type D2 ode

Using the change of variables $y = u(x)x$ on the above ode results in new ode in $u(x)$

$$-5u(x)x + (4x - u(x)x)(u'(x)x + u(x)) = -2x$$

In canonical form the ODE is

$$\begin{aligned}u' &= F(x, u) \\ &= f(x)g(u) \\ &= -\frac{u^2 + u - 2}{(u - 4)x}\end{aligned}$$

Where $f(x) = -\frac{1}{x}$ and $g(u) = \frac{u^2 + u - 2}{u - 4}$. Integrating both sides gives

$$\begin{aligned}\frac{1}{\frac{u^2 + u - 2}{u - 4}} du &= -\frac{1}{x} dx \\ \int \frac{1}{\frac{u^2 + u - 2}{u - 4}} du &= \int -\frac{1}{x} dx \\ -\ln(u - 1) + 2\ln(u + 2) &= -\ln(x) + c_2\end{aligned}$$

Raising both side to exponential gives

$$e^{-\ln(u-1)+2\ln(u+2)} = e^{-\ln(x)+c_2}$$

Which simplifies to

$$\frac{(u + 2)^2}{u - 1} = \frac{c_3}{x}$$

The solution is

$$\frac{(u(x) + 2)^2}{u(x) - 1} = \frac{c_3}{x}$$

Replacing $u(x)$ in the above solution by $\frac{y}{x}$ results in the solution for y in implicit form

$$\begin{aligned}\frac{\left(\frac{y}{x} + 2\right)^2}{\frac{y}{x} - 1} &= \frac{c_3}{x} \\ \frac{(2x + y)^2}{(y - x)x} &= \frac{c_3}{x}\end{aligned}$$

Which simplifies to

$$-\frac{(2x + y)^2}{-y + x} = c_3$$

Substituting initial conditions and solving for c_3 gives $c_3 = 12$. Hence the solution be-

Summary

The solution(s) found are the following comes

$$-\frac{(2x + y)^2}{-y + x} = 12 \tag{1}$$

Verification of solutions

$$-\frac{(2x + y)^2}{-y + x} = 12$$

Verified OK.

4.19.3 Solving as first order ode lie symmetry calculated ode

Writing the ode as

$$y' = -\frac{-2x + 5y}{-4x + y}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \tag{A}$$

The type of this ode is not in the lookup table. To determine ξ, η then (A) is solved using ansatz. Making bivariate polynomials of degree 1 to use as anstaz gives

$$\xi = xa_2 + ya_3 + a_1 \tag{1E}$$

$$\eta = xb_2 + yb_3 + b_1 \tag{2E}$$

Where the unknown coefficients are

$$\{a_1, a_2, a_3, b_1, b_2, b_3\}$$

Substituting equations (1E,2E) and ω into (A) gives

$$\begin{aligned}
& b_2 - \frac{(-2x + 5y)(b_3 - a_2)}{-4x + y} - \frac{(-2x + 5y)^2 a_3}{(-4x + y)^2} \\
& - \left(\frac{2}{-4x + y} - \frac{4(-2x + 5y)}{(-4x + y)^2} \right) (xa_2 + ya_3 + a_1) \\
& - \left(-\frac{5}{-4x + y} + \frac{-2x + 5y}{(-4x + y)^2} \right) (xb_2 + yb_3 + b_1) = 0
\end{aligned} \tag{5E}$$

Putting the above in normal form gives

$$\frac{8x^2a_2 - 4x^2a_3 - 2x^2b_2 - 8x^2b_3 - 4xya_2 + 20xya_3 - 8xyb_2 + 4xyb_3 + 5y^2a_2 - 7y^2a_3 + y^2b_2 - 5y^2b_3 - 18xa_1 - 18yb_1}{(4x - y)^2} = 0$$

Setting the numerator to zero gives

$$\begin{aligned}
& 8x^2a_2 - 4x^2a_3 - 2x^2b_2 - 8x^2b_3 - 4xya_2 + 20xya_3 - 8xyb_2 \\
& + 4xyb_3 + 5y^2a_2 - 7y^2a_3 + y^2b_2 - 5y^2b_3 - 18xb_1 + 18ya_1 = 0
\end{aligned} \tag{6E}$$

Looking at the above PDE shows the following are all the terms with $\{x, y\}$ in them.

$$\{x, y\}$$

The following substitution is now made to be able to collect on all terms with $\{x, y\}$ in them

$$\{x = v_1, y = v_2\}$$

The above PDE (6E) now becomes

$$\begin{aligned}
& 8a_2v_1^2 - 4a_2v_1v_2 + 5a_2v_2^2 - 4a_3v_1^2 + 20a_3v_1v_2 - 7a_3v_2^2 - 2b_2v_1^2 \\
& - 8b_2v_1v_2 + b_2v_2^2 - 8b_3v_1^2 + 4b_3v_1v_2 - 5b_3v_2^2 + 18a_1v_2 - 18b_1v_1 = 0
\end{aligned} \tag{7E}$$

Collecting the above on the terms v_i introduced, and these are

$$\{v_1, v_2\}$$

Equation (7E) now becomes

$$(8a_2 - 4a_3 - 2b_2 - 8b_3) v_1^2 + (-4a_2 + 20a_3 - 8b_2 + 4b_3) v_1 v_2 - 18b_1 v_1 + (5a_2 - 7a_3 + b_2 - 5b_3) v_2^2 + 18a_1 v_2 = 0 \quad (8E)$$

Setting each coefficients in (8E) to zero gives the following equations to solve

$$\begin{aligned} 18a_1 &= 0 \\ -18b_1 &= 0 \\ -4a_2 + 20a_3 - 8b_2 + 4b_3 &= 0 \\ 5a_2 - 7a_3 + b_2 - 5b_3 &= 0 \\ 8a_2 - 4a_3 - 2b_2 - 8b_3 &= 0 \end{aligned}$$

Solving the above equations for the unknowns gives

$$\begin{aligned} a_1 &= 0 \\ a_2 &= a_3 + b_3 \\ a_3 &= a_3 \\ b_1 &= 0 \\ b_2 &= 2a_3 \\ b_3 &= b_3 \end{aligned}$$

Substituting the above solution in the anstaz (1E,2E) (using 1 as arbitrary value for any unknown in the RHS) gives

$$\begin{aligned} \xi &= x \\ \eta &= y \end{aligned}$$

Shifting is now applied to make $\xi = 0$ in order to simplify the rest of the computation

$$\begin{aligned} \eta &= \eta - \omega(x, y) \xi \\ &= y - \left(-\frac{-2x + 5y}{-4x + y} \right) (x) \\ &= \frac{2x^2 - xy - y^2}{4x - y} \\ \xi &= 0 \end{aligned}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \quad (1)$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{2x^2 - xy - y^2}{4x - y}} dy \end{aligned}$$

Which results in

$$S = -\ln(y - x) + 2\ln(2x + y)$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{-2x + 5y}{-4x + y}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= \frac{1}{y - x} + \frac{4}{2x + y} \\ S_y &= \frac{1}{-y + x} + \frac{2}{2x + y} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 0 \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 0$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = c_1 \tag{4}$$

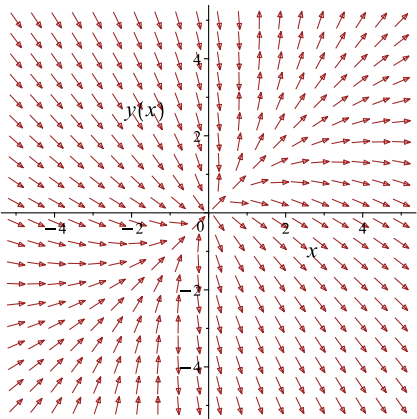
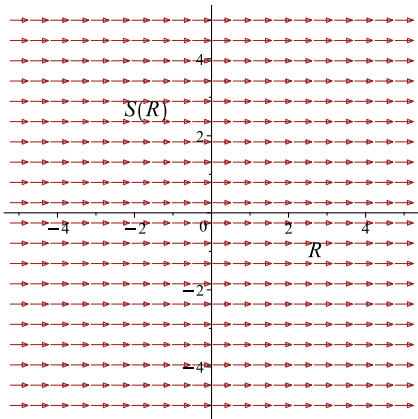
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$-\ln(y - x) + 2 \ln(2x + y) = c_1$$

Which simplifies to

$$-\ln(y - x) + 2 \ln(2x + y) = c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{-2x+5y}{-4x+y}$ 	$R = x$ $S = -\ln(y - x) + 2 \ln(2x + y)$	$\frac{dS}{dR} = 0$ 

Initial conditions are used to solve for c_1 . Substituting $x = 1$ and $y = 4$ in the above solution gives an equation to solve for the constant of integration.

$$2 \ln(2) + \ln(3) = c_1$$

$$c_1 = 2 \ln(2) + \ln(3)$$

Substituting c_1 found above in the general solution gives

$$-\ln(y - x) + 2 \ln(2x + y) = 2 \ln(2) + \ln(3)$$

Summary

The solution(s) found are the following

$$-\ln(y - x) + 2 \ln(2x + y) = 2 \ln(2) + \ln(3) \quad (1)$$

Verification of solutions

$$-\ln(y - x) + 2 \ln(2x + y) = 2 \ln(2) + \ln(3)$$

Verified OK.

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
trying Bernoulli  
trying separable  
trying inverse linear  
trying homogeneous types:  
trying homogeneous D  
<- homogeneous successful`
```

✓ Solution by Maple

Time used: 0.218 (sec). Leaf size: 35

```
dsolve([(2*x-5*y(x))+(4*x-y(x))*diff(y(x),x)=0,y(1) = 4],y(x), singsol=all)
```

$$y(x) = 6 - 2x - 6\sqrt{1-x}$$
$$y(x) = 6 - 2x + 6\sqrt{1-x}$$

✓ Solution by Mathematica

Time used: 2.199 (sec). Leaf size: 41

```
DSolve[{(2*x-5*y[x])+(4*x-y[x])*y'[x]==0,{y[1]==4}},y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow -2x - 6i\sqrt{x-1} + 6$$

$$y(x) \rightarrow -2x + 6i\sqrt{x-1} + 6$$

4.20 problem 20

4.20.1 Existence and uniqueness analysis	702
4.20.2 Solving as homogeneousTypeD2 ode	703
4.20.3 Solving as first order ode lie symmetry calculated ode	705
4.20.4 Solving as exact ode	710

Internal problem ID [11633]

Internal file name [OUTPUT/10615_Saturday_May_27_2023_03_06_35_AM_56839210/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.2 (Separable equations). Exercises page 47

Problem number: 20.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**homogeneousTypeD2**", "**exactWithIntegrationFactor**", "**first_order_ode_lie_symmetry_calculated**"

Maple gives the following as the ode type

```
[[_homogeneous, `class A`], _rational, [_Abel, `2nd type`, `class B`]]
```

$$9yx + 5y^2 - (6x^2 + 4yx) y' = -3x^2$$

With initial conditions

$$[y(2) = -6]$$

4.20.1 Existence and uniqueness analysis

This is non linear first order ODE. In canonical form it is written as

$$\begin{aligned} y' &= f(x, y) \\ &= \frac{3x^2 + 9xy + 5y^2}{2x(3x + 2y)} \end{aligned}$$

The x domain of $f(x, y)$ when $y = -6$ is

$$\{-\infty \leq x < 0, 0 < x < 4, 4 < x \leq \infty\}$$

And the point $x_0 = 2$ is inside this domain. The y domain of $f(x, y)$ when $x = 2$ is

$$\{y < -3 \vee -3 < y\}$$

And the point $y_0 = -6$ is inside this domain. Now we will look at the continuity of

$$\begin{aligned} \frac{\partial f}{\partial y} &= \frac{\partial}{\partial y} \left(\frac{3x^2 + 9xy + 5y^2}{2x(3x + 2y)} \right) \\ &= \frac{10y + 9x}{2x(3x + 2y)} - \frac{3x^2 + 9xy + 5y^2}{x(3x + 2y)^2} \end{aligned}$$

The x domain of $\frac{\partial f}{\partial y}$ when $y = -6$ is

$$\{-\infty \leq x < 0, 0 < x < 4, 4 < x \leq \infty\}$$

And the point $x_0 = 2$ is inside this domain. The y domain of $\frac{\partial f}{\partial y}$ when $x = 2$ is

$$\{y < -3 \vee -3 < y\}$$

And the point $y_0 = -6$ is inside this domain. Therefore solution exists and is unique.

4.20.2 Solving as homogeneous TypeD2 ode

Using the change of variables $y = u(x)x$ on the above ode results in new ode in $u(x)$

$$9u(x)x^2 + 5u(x)^2x^2 - (6x^2 + 4u(x)x^2)(u'(x)x + u(x)) = -3x^2$$

In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= \frac{u^2 + 3u + 3}{2x(2u + 3)} \end{aligned}$$

Where $f(x) = \frac{1}{2x}$ and $g(u) = \frac{u^2 + 3u + 3}{2u + 3}$. Integrating both sides gives

$$\begin{aligned} \frac{1}{\frac{u^2 + 3u + 3}{2u + 3}} du &= \frac{1}{2x} dx \\ \int \frac{1}{\frac{u^2 + 3u + 3}{2u + 3}} du &= \int \frac{1}{2x} dx \\ \ln(u^2 + 3u + 3) &= \frac{\ln(x)}{2} + c_2 \end{aligned}$$

Raising both side to exponential gives

$$u^2 + 3u + 3 = e^{\frac{\ln(x)}{2} + c_2}$$

Which simplifies to

$$u^2 + 3u + 3 = c_3 \sqrt{x}$$

Which simplifies to

$$u(x)^2 + 3u(x) + 3 = c_3 \sqrt{x} e^{c_2}$$

The solution is

$$u(x)^2 + 3u(x) + 3 = c_3 \sqrt{x} e^{c_2}$$

Replacing $u(x)$ in the above solution by $\frac{y}{x}$ results in the solution for y in implicit form

$$\begin{aligned} \frac{y^2}{x^2} + \frac{3y}{x} + 3 &= c_3 \sqrt{x} e^{c_2} \\ \frac{y^2}{x^2} + \frac{3y}{x} + 3 &= c_3 \sqrt{x} e^{c_2} \end{aligned}$$

Substituting initial conditions and solving for c_2 gives $c_2 = \frac{\ln\left(\frac{9}{2c_3^2}\right)}{2}$. Hence the solution becomes Initial conditions are used to solve for c_3 . Substituting $x = 2$ and $y = -6$ in the above solution gives an equation to solve for the constant of integration.

$$3 = 3c_3 \sqrt{\frac{1}{c_3^2}}$$

This solution is valid for any c_3 . Hence there are infinite number of solutions.

Summary

The solution(s) found are the following

$$\frac{y^2}{x^2} + \frac{3y}{x} + 3 = \frac{3c_3 \sqrt{x} \sqrt{2} \sqrt{\frac{1}{c_3^2}}}{2} \quad (1)$$

Verification of solutions

$$\frac{y^2}{x^2} + \frac{3y}{x} + 3 = \frac{3c_3 \sqrt{x} \sqrt{2} \sqrt{\frac{1}{c_3^2}}}{2}$$

Verified OK.

4.20.3 Solving as first order ode lie symmetry calculated ode

Writing the ode as

$$y' = \frac{3x^2 + 9xy + 5y^2}{2x(3x + 2y)}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is not in the lookup table. To determine ξ, η then (A) is solved using ansatz. Making bivariate polynomials of degree 1 to use as anstaz gives

$$\xi = xa_2 + ya_3 + a_1 \quad (\text{1E})$$

$$\eta = xb_2 + yb_3 + b_1 \quad (\text{2E})$$

Where the unknown coefficients are

$$\{a_1, a_2, a_3, b_1, b_2, b_3\}$$

Substituting equations (1E,2E) and ω into (A) gives

$$b_2 + \frac{(3x^2 + 9xy + 5y^2)(b_3 - a_2)}{2x(3x + 2y)} - \frac{(3x^2 + 9xy + 5y^2)^2 a_3}{4x^2(3x + 2y)^2}$$

$$- \left(\frac{9y + 6x}{2x(3x + 2y)} - \frac{3x^2 + 9xy + 5y^2}{2x^2(3x + 2y)} - \frac{3(3x^2 + 9xy + 5y^2)}{2x(3x + 2y)^2} \right) (xa_2 + ya_3 + a_1) \quad (\text{5E})$$

$$- \left(\frac{10y + 9x}{2x(3x + 2y)} - \frac{3x^2 + 9xy + 5y^2}{x(3x + 2y)^2} \right) (xb_2 + yb_3 + b_1) = 0$$

Putting the above in normal form gives

$$\frac{18x^4 a_2 + 9x^4 a_3 + 6x^4 b_2 - 18x^4 b_3 + 24x^3 y a_2 + 54x^3 y a_3 + 12x^3 y b_2 - 24x^3 y b_3 + 6x^2 y^2 a_2 + 69x^2 y^2 a_3 + 4x^2 y^2 b_2 - 12x^2 y^2 b_3 + 30x y^3 a_3 - 5y^4 a_3 - 42x^3 b_1 + 42x^2 y a_1 - 60x^2 y b_1 + 60x y^2 a_1 - 20x y^2 b_1 + 20y^3 a_1}{4x^2(3x + 2y)^2} = 0$$

Setting the numerator to zero gives

$$-18x^4 a_2 - 9x^4 a_3 - 6x^4 b_2 + 18x^4 b_3 - 24x^3 y a_2 - 54x^3 y a_3 - 12x^3 y b_2 + 24x^3 y b_3 - 6x^2 y^2 a_2 - 69x^2 y^2 a_3 - 4x^2 y^2 b_2 + 6x^2 y^2 b_3 - 30x y^3 a_3 - 5y^4 a_3 - 42x^3 b_1 + 42x^2 y a_1 - 60x^2 y b_1 + 60x y^2 a_1 - 20x y^2 b_1 + 20y^3 a_1 = 0 \quad (\text{6E})$$

Looking at the above PDE shows the following are all the terms with $\{x, y\}$ in them.

$$\{x, y\}$$

The following substitution is now made to be able to collect on all terms with $\{x, y\}$ in them

$$\{x = v_1, y = v_2\}$$

The above PDE (6E) now becomes

$$\begin{aligned} & -18a_2v_1^4 - 24a_2v_1^3v_2 - 6a_2v_1^2v_2^2 - 9a_3v_1^4 - 54a_3v_1^3v_2 - 69a_3v_1^2v_2^2 - 30a_3v_1v_2^3 \\ & - 5a_3v_2^4 - 6b_2v_1^4 - 12b_2v_1^3v_2 - 4b_2v_1^2v_2^2 + 18b_3v_1^4 + 24b_3v_1^3v_2 + 6b_3v_1^2v_2^2 \\ & + 42a_1v_1^2v_2 + 60a_1v_1v_2^2 + 20a_1v_2^3 - 42b_1v_1^3 - 60b_1v_1^2v_2 - 20b_1v_1v_2^2 = 0 \end{aligned} \quad (7E)$$

Collecting the above on the terms v_i introduced, and these are

$$\{v_1, v_2\}$$

Equation (7E) now becomes

$$\begin{aligned} & (-18a_2 - 9a_3 - 6b_2 + 18b_3)v_1^4 + (-24a_2 - 54a_3 - 12b_2 + 24b_3)v_1^3v_2 \\ & - 42b_1v_1^3 + (-6a_2 - 69a_3 - 4b_2 + 6b_3)v_1^2v_2^2 + (42a_1 - 60b_1)v_1^2v_2 \\ & - 30a_3v_1v_2^3 + (60a_1 - 20b_1)v_1v_2^2 - 5a_3v_2^4 + 20a_1v_2^3 = 0 \end{aligned} \quad (8E)$$

Setting each coefficients in (8E) to zero gives the following equations to solve

$$\begin{aligned} 20a_1 &= 0 \\ -30a_3 &= 0 \\ -5a_3 &= 0 \\ -42b_1 &= 0 \\ 42a_1 - 60b_1 &= 0 \\ 60a_1 - 20b_1 &= 0 \\ -24a_2 - 54a_3 - 12b_2 + 24b_3 &= 0 \\ -18a_2 - 9a_3 - 6b_2 + 18b_3 &= 0 \\ -6a_2 - 69a_3 - 4b_2 + 6b_3 &= 0 \end{aligned}$$

Solving the above equations for the unknowns gives

$$a_1 = 0$$

$$a_2 = b_3$$

$$a_3 = 0$$

$$b_1 = 0$$

$$b_2 = 0$$

$$b_3 = b_3$$

Substituting the above solution in the anstaz (1E,2E) (using 1 as arbitrary value for any unknown in the RHS) gives

$$\xi = x$$

$$\eta = y$$

Shifting is now applied to make $\xi = 0$ in order to simplify the rest of the computation

$$\begin{aligned} \eta &= \eta - \omega(x, y) \xi \\ &= y - \left(\frac{3x^2 + 9xy + 5y^2}{2x(3x + 2y)} \right) (x) \\ &= \frac{-3x^2 - 3xy - y^2}{6x + 4y} \\ \xi &= 0 \end{aligned}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \quad (1)$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y} \right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{-3x^2 - 3xy - y^2}{6x + 4y}} dy \end{aligned}$$

Which results in

$$S = -2 \ln(3x^2 + 3xy + y^2)$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = \frac{3x^2 + 9xy + 5y^2}{2x(3x + 2y)}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= \frac{-12x - 6y}{3x^2 + 3xy + y^2} \\ S_y &= \frac{-6x - 4y}{3x^2 + 3xy + y^2} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = -\frac{5}{x} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = -\frac{5}{R}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = -5 \ln(R) + c_1 \quad (4)$$

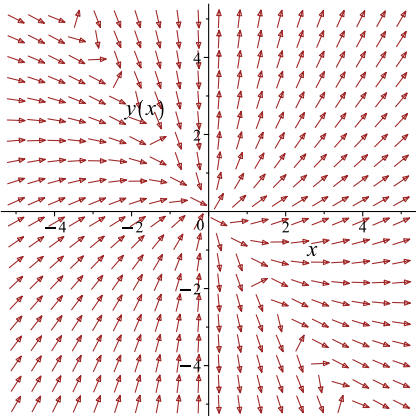
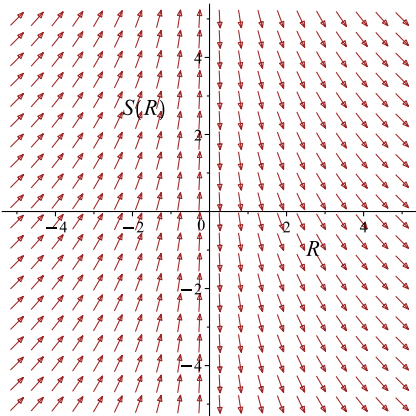
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$-2 \ln(y^2 + 3yx + 3x^2) = -5 \ln(x) + c_1$$

Which simplifies to

$$-2 \ln (y^2 + 3yx + 3x^2) = -5 \ln (x) + c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = \frac{3x^2 + 9xy + 5y^2}{2x(3x + 2y)}$ 	$R = x$ $S = -2 \ln (3x^2 + 3xy + y^2)$	$\frac{dS}{dR} = -\frac{5}{R}$ 

Initial conditions are used to solve for c_1 . Substituting $x = 2$ and $y = -6$ in the above solution gives an equation to solve for the constant of integration.

$$-2 \ln (3) - 4 \ln (2) = -5 \ln (2) + c_1$$

$$c_1 = \ln (2) - 2 \ln (3)$$

Substituting c_1 found above in the general solution gives

$$-2 \ln (3x^2 + 3xy + y^2) = -5 \ln (x) + \ln (2) - 2 \ln (3)$$

Summary

The solution(s) found are the following

$$-2 \ln (y^2 + 3yx + 3x^2) = -5 \ln (x) + \ln (2) - 2 \ln (3) \quad (1)$$

Verification of solutions

$$-2 \ln (y^2 + 3yx + 3x^2) = -5 \ln (x) + \ln (2) - 2 \ln (3)$$

Verified OK.

4.20.4 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \quad (\text{A})$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \quad (\text{B})$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (\text{1A})$$

Therefore

$$\begin{aligned} (-6x^2 - 4xy) dy &= (-3x^2 - 9xy - 5y^2) dx \\ (3x^2 + 9xy + 5y^2) dx &+ (-6x^2 - 4xy) dy = 0 \end{aligned} \quad (\text{2A})$$

Comparing (1A) and (2A) shows that

$$\begin{aligned} M(x, y) &= 3x^2 + 9xy + 5y^2 \\ N(x, y) &= -6x^2 - 4xy \end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(3x^2 + 9xy + 5y^2) \\ &= 10y + 9x\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(-6x^2 - 4xy) \\ &= -12x - 4y\end{aligned}$$

Since $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$\begin{aligned}A &= \frac{1}{N} \left(\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} \right) \\ &= -\frac{1}{6x^2 + 4xy} ((10y + 9x) - (-12x - 4y)) \\ &= -\frac{7}{2x}\end{aligned}$$

Since A does not depend on y , then it can be used to find an integrating factor. The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int A dx} \\ &= e^{\int -\frac{7}{2x} dx}\end{aligned}$$

The result of integrating gives

$$\begin{aligned}\mu &= e^{-\frac{7 \ln(x)}{2}} \\ &= \frac{1}{x^{\frac{7}{2}}}\end{aligned}$$

M and N are multiplied by this integrating factor, giving new M and new N which are called \bar{M} and \bar{N} for now so not to confuse them with the original M and N .

$$\begin{aligned}\bar{M} &= \mu M \\ &= \frac{1}{x^{\frac{7}{2}}}(3x^2 + 9xy + 5y^2) \\ &= \frac{3x^2 + 9xy + 5y^2}{x^{\frac{7}{2}}}\end{aligned}$$

And

$$\begin{aligned}\bar{N} &= \mu N \\ &= \frac{1}{x^{\frac{7}{2}}}(-6x^2 - 4xy) \\ &= \frac{-6x - 4y}{x^{\frac{5}{2}}}\end{aligned}$$

Now a modified ODE is obtained from the original ODE, which is exact and can be solved. The modified ODE is

$$\begin{aligned}\bar{M} + \bar{N} \frac{dy}{dx} &= 0 \\ \left(\frac{3x^2 + 9xy + 5y^2}{x^{\frac{7}{2}}} \right) + \left(\frac{-6x - 4y}{x^{\frac{5}{2}}} \right) \frac{dy}{dx} &= 0\end{aligned}$$

The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = \bar{M} \quad (1)$$

$$\frac{\partial \phi}{\partial y} = \bar{N} \quad (2)$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int \bar{M} dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int \frac{3x^2 + 9xy + 5y^2}{x^{\frac{7}{2}}} dx \\ \phi &= -\frac{6(x^2 + xy + \frac{1}{3}y^2)}{x^{\frac{5}{2}}} + f(y)\end{aligned} \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = -\frac{6(x + \frac{2y}{3})}{x^{\frac{5}{2}}} + f'(y) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = \frac{-6x - 4y}{x^{\frac{5}{2}}}$. Therefore equation (4) becomes

$$\frac{-6x - 4y}{x^{\frac{5}{2}}} = \frac{-6x - 4y}{x^{\frac{5}{2}}} + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 0$$

Therefore

$$f(y) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(y)$ into equation (3) gives ϕ

$$\phi = -\frac{6(x^2 + xy + \frac{1}{3}y^2)}{x^{\frac{5}{2}}} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -\frac{6(x^2 + xy + \frac{1}{3}y^2)}{x^{\frac{5}{2}}}$$

Initial conditions are used to solve for c_1 . Substituting $x = 2$ and $y = -6$ in the above solution gives an equation to solve for the constant of integration.

$$-3\sqrt{2} = c_1$$

$$c_1 = -3\sqrt{2}$$

Substituting c_1 found above in the general solution gives

$$-\frac{6(x^2 + xy + \frac{1}{3}y^2)}{x^{\frac{5}{2}}} = -3\sqrt{2}$$

The above simplifies to

$$3\sqrt{2}x^{\frac{5}{2}} - 6x^2 - 6xy - 2y^2 = 0$$

Summary

The solution(s) found are the following

$$3\sqrt{2}x^{\frac{5}{2}} - 6x^2 - 6yx - 2y^2 = 0 \tag{1}$$

Verification of solutions

$$3\sqrt{2}x^{\frac{5}{2}} - 6x^2 - 6yx - 2y^2 = 0$$

Verified OK.

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
trying Bernoulli  
trying separable  
trying inverse linear  
trying homogeneous types:  
trying homogeneous D  
<- homogeneous successful`
```

✓ Solution by Maple

Time used: 0.265 (sec). Leaf size: 21

```
dsolve([(3*x^2+9*x*y(x)+5*y(x)^2)-(6*x^2+4*x*y(x))*diff(y(x),x)=0,y(2) = -6],y(x), singsol=a
```

$$y(x) = -\frac{\left(3 + \sqrt{-3 + 6\sqrt{2}\sqrt{x}}\right)x}{2}$$

✓ Solution by Mathematica

Time used: 37.251 (sec). Leaf size: 30

```
DSolve[{(3*x^2+9*x*y[x]+5*y[x]^2)-(6*x^2+4*x*y[x])*y'[x]==0,{y[2]==-6}},y[x],x,IncludeSingular
```

$$y(x) \rightarrow -\frac{1}{2}\left(\sqrt{6\sqrt{2}\sqrt{x}-3}+3\right)x$$

4.21 problem 22(a)

4.21.1 Solving as homogeneousTypeD2 ode	715
4.21.2 Solving as differentialType ode	717
4.21.3 Solving as first order ode lie symmetry calculated ode	719
4.21.4 Solving as exact ode	724
4.21.5 Maple step by step solution	728

Internal problem ID [11634]

Internal file name [OUTPUT/10616_Saturday_May_27_2023_04_14_52_AM_90704318/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 2, section 2.2 (Separable equations). Exercises page 47

Problem number: 22(a).

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact", "differentialType", "homogeneousTypeD2", "first_order_ode_lie_symmetry_calculated"

Maple gives the following as the ode type

```
[[_homogeneous, `class A`], _exact, _rational, [_Abel, `2nd
  type`, `class A`]]
```

$$2y + (2x - y)y' = -x$$

4.21.1 Solving as homogeneousTypeD2 ode

Using the change of variables $y = u(x)x$ on the above ode results in new ode in $u(x)$

$$2u(x)x + (2x - u(x)x)(u'(x)x + u(x)) = -x$$

In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= -\frac{u^2 - 4u - 1}{(u - 2)x} \end{aligned}$$

Where $f(x) = -\frac{1}{x}$ and $g(u) = \frac{u^2-4u-1}{u-2}$. Integrating both sides gives

$$\begin{aligned}\frac{1}{\frac{u^2-4u-1}{u-2}} du &= -\frac{1}{x} dx \\ \int \frac{1}{\frac{u^2-4u-1}{u-2}} du &= \int -\frac{1}{x} dx \\ \frac{\ln(u^2 - 4u - 1)}{2} &= -\ln(x) + c_2\end{aligned}$$

Raising both side to exponential gives

$$\sqrt{u^2 - 4u - 1} = e^{-\ln(x)+c_2}$$

Which simplifies to

$$\sqrt{u^2 - 4u - 1} = \frac{c_3}{x}$$

Which simplifies to

$$\sqrt{u(x)^2 - 4u(x) - 1} = \frac{c_3 e^{c_2}}{x}$$

The solution is

$$\sqrt{u(x)^2 - 4u(x) - 1} = \frac{c_3 e^{c_2}}{x}$$

Replacing $u(x)$ in the above solution by $\frac{y}{x}$ results in the solution for y in implicit form

$$\begin{aligned}\sqrt{\frac{y^2}{x^2} - \frac{4y}{x} - 1} &= \frac{c_3 e^{c_2}}{x} \\ \sqrt{\frac{y^2 - 4yx - x^2}{x^2}} &= \frac{c_3 e^{c_2}}{x}\end{aligned}$$

Summary

The solution(s) found are the following

$$\sqrt{\frac{y^2 - 4yx - x^2}{x^2}} = \frac{c_3 e^{c_2}}{x} \quad (1)$$

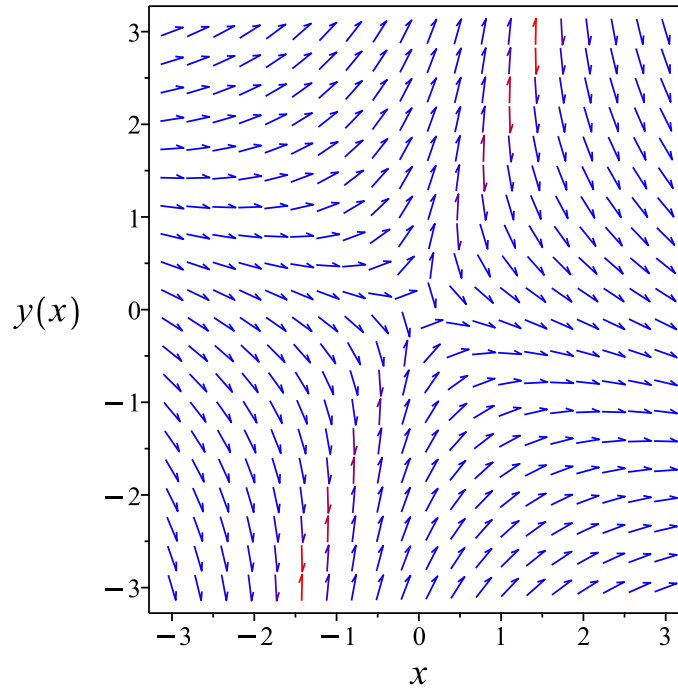


Figure 130: Slope field plot

Verification of solutions

$$\sqrt{\frac{y^2 - 4yx - x^2}{x^2}} = \frac{c_3 e^{c_2}}{x}$$

Verified OK.

4.21.2 Solving as differentialType ode

Writing the ode as

$$y' = \frac{-x - 2y}{2x - y} \tag{1}$$

Which becomes

$$(-y) dy = (-2x) dy + (-x - 2y) dx \tag{2}$$

But the RHS is complete differential because

$$(-2x) dy + (-x - 2y) dx = d\left(-\frac{1}{2}x^2 - 2xy\right)$$

Hence (2) becomes

$$(-y) dy = d\left(-\frac{1}{2}x^2 - 2xy\right)$$

Integrating both sides gives gives these solutions

$$y = 2x + \sqrt{5x^2 - 2c_1} + c_1$$

$$y = 2x - \sqrt{5x^2 - 2c_1} + c_1$$

Summary

The solution(s) found are the following

$$y = 2x + \sqrt{5x^2 - 2c_1} + c_1 \tag{1}$$

$$y = 2x - \sqrt{5x^2 - 2c_1} + c_1 \tag{2}$$

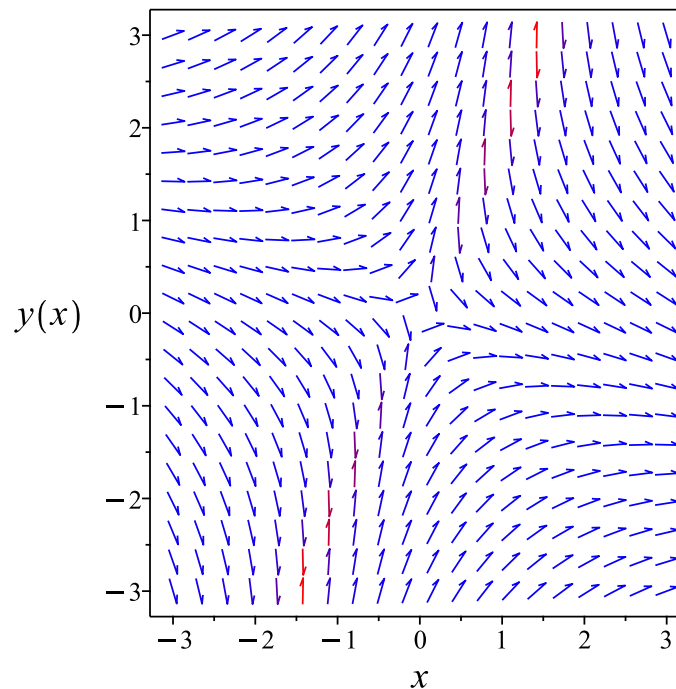


Figure 131: Slope field plot

Verification of solutions

$$y = 2x + \sqrt{5x^2 - 2c_1} + c_1$$

Verified OK.

$$y = 2x - \sqrt{5x^2 - 2c_1} + c_1$$

Verified OK.

4.21.3 Solving as first order ode lie symmetry calculated ode

Writing the ode as

$$y' = \frac{x + 2y}{-2x + y}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is not in the lookup table. To determine ξ, η then (A) is solved using ansatz. Making bivariate polynomials of degree 1 to use as anstaz gives

$$\xi = xa_2 + ya_3 + a_1 \quad (\text{1E})$$

$$\eta = xb_2 + yb_3 + b_1 \quad (\text{2E})$$

Where the unknown coefficients are

$$\{a_1, a_2, a_3, b_1, b_2, b_3\}$$

Substituting equations (1E,2E) and ω into (A) gives

$$b_2 + \frac{(x + 2y)(b_3 - a_2)}{-2x + y} - \frac{(x + 2y)^2 a_3}{(-2x + y)^2}$$

$$- \left(\frac{1}{-2x + y} + \frac{2x + 4y}{(-2x + y)^2} \right) (xa_2 + ya_3 + a_1) \quad (\text{5E})$$

$$- \left(\frac{2}{-2x + y} - \frac{x + 2y}{(-2x + y)^2} \right) (xb_2 + yb_3 + b_1) = 0$$

Putting the above in normal form gives

$$\frac{2x^2 a_2 - x^2 a_3 + 9x^2 b_2 - 2x^2 b_3 - 2xy a_2 - 4xy a_3 - 4xy b_2 + 2xy b_3 - 2y^2 a_2 - 9y^2 a_3 + y^2 b_2 + 2y^2 b_3 + 5xb_1 - 5ya_1}{(2x - y)^2}$$

$$= 0$$

Setting the numerator to zero gives

$$2x^2 a_2 - x^2 a_3 + 9x^2 b_2 - 2x^2 b_3 - 2xy a_2 - 4xy a_3 - 4xy b_2$$

$$+ 2xy b_3 - 2y^2 a_2 - 9y^2 a_3 + y^2 b_2 + 2y^2 b_3 + 5xb_1 - 5ya_1 = 0 \quad (\text{6E})$$

Looking at the above PDE shows the following are all the terms with $\{x, y\}$ in them.

$$\{x, y\}$$

The following substitution is now made to be able to collect on all terms with $\{x, y\}$ in them

$$\{x = v_1, y = v_2\}$$

The above PDE (6E) now becomes

$$\begin{aligned} 2a_2v_1^2 - 2a_2v_1v_2 - 2a_2v_2^2 - a_3v_1^2 - 4a_3v_1v_2 - 9a_3v_2^2 + 9b_2v_1^2 \\ - 4b_2v_1v_2 + b_2v_2^2 - 2b_3v_1^2 + 2b_3v_1v_2 + 2b_3v_2^2 - 5a_1v_2 + 5b_1v_1 = 0 \end{aligned} \quad (7E)$$

Collecting the above on the terms v_i introduced, and these are

$$\{v_1, v_2\}$$

Equation (7E) now becomes

$$\begin{aligned} (2a_2 - a_3 + 9b_2 - 2b_3)v_1^2 + (-2a_2 - 4a_3 - 4b_2 + 2b_3)v_1v_2 \\ + 5b_1v_1 + (-2a_2 - 9a_3 + b_2 + 2b_3)v_2^2 - 5a_1v_2 = 0 \end{aligned} \quad (8E)$$

Setting each coefficients in (8E) to zero gives the following equations to solve

$$\begin{aligned} -5a_1 &= 0 \\ 5b_1 &= 0 \\ -2a_2 - 9a_3 + b_2 + 2b_3 &= 0 \\ -2a_2 - 4a_3 - 4b_2 + 2b_3 &= 0 \\ 2a_2 - a_3 + 9b_2 - 2b_3 &= 0 \end{aligned}$$

Solving the above equations for the unknowns gives

$$\begin{aligned} a_1 &= 0 \\ a_2 &= -4a_3 + b_3 \\ a_3 &= a_3 \\ b_1 &= 0 \\ b_2 &= a_3 \\ b_3 &= b_3 \end{aligned}$$

Substituting the above solution in the anstaz (1E,2E) (using 1 as arbitrary value for any unknown in the RHS) gives

$$\begin{aligned}\xi &= x \\ \eta &= y\end{aligned}$$

Shifting is now applied to make $\xi = 0$ in order to simplify the rest of the computation

$$\begin{aligned}\eta &= \eta - \omega(x, y) \xi \\ &= y - \left(\frac{x + 2y}{-2x + y} \right) (x) \\ &= \frac{x^2 + 4xy - y^2}{2x - y} \\ \xi &= 0\end{aligned}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \quad (1)$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y} \right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned}S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{x^2 + 4xy - y^2}{2x - y}} dy\end{aligned}$$

Which results in

$$S = \frac{\ln(-x^2 - 4xy + y^2)}{2}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = \frac{x + 2y}{-2x + y}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= \frac{x + 2y}{x^2 + 4xy - y^2} \\ S_y &= \frac{2x - y}{x^2 + 4xy - y^2} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 0 \tag{2A}$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 0$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = c_1 \tag{4}$$

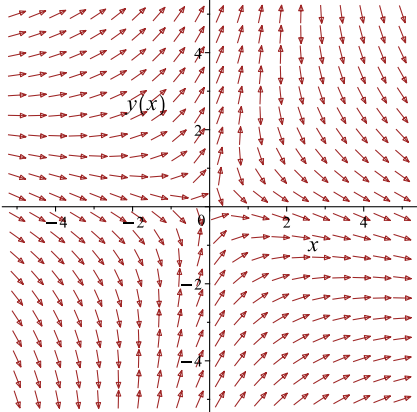
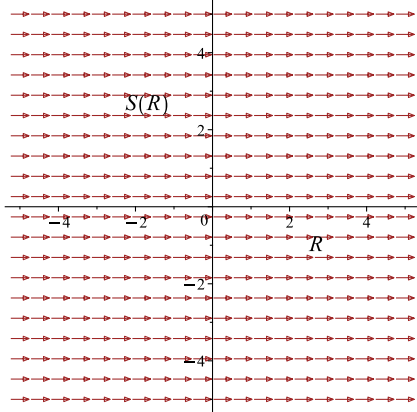
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$\frac{\ln(y^2 - 4yx - x^2)}{2} = c_1$$

Which simplifies to

$$\frac{\ln(y^2 - 4yx - x^2)}{2} = c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = \frac{x+2y}{-2x+y}$ 	$R = x$ $S = \frac{\ln(-x^2 - 4xy + y^2)}{2}$	$\frac{dS}{dR} = 0$ 

Summary

The solution(s) found are the following

$$\frac{\ln(y^2 - 4yx - x^2)}{2} = c_1 \tag{1}$$

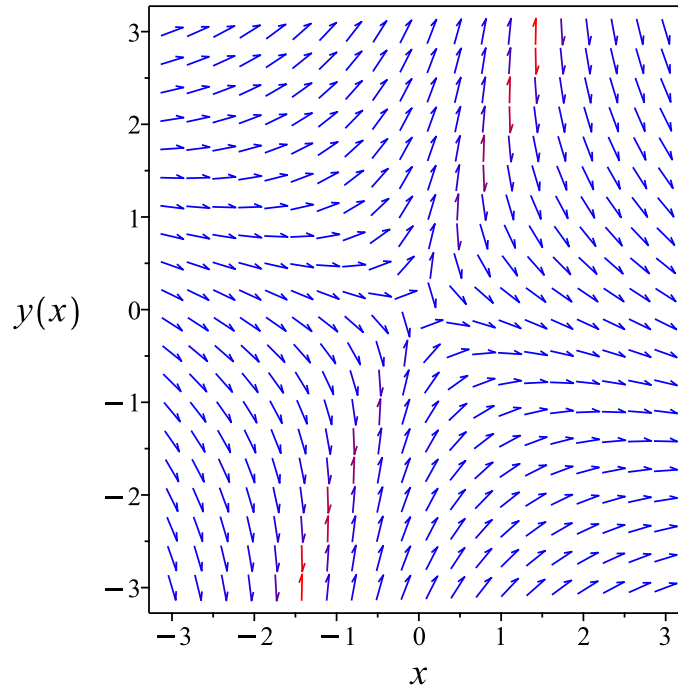


Figure 132: Slope field plot

Verification of solutions

$$\frac{\ln(y^2 - 4yx - x^2)}{2} = c_1$$

Verified OK.

4.21.4 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \tag{1A}$$

Therefore

$$\begin{aligned}(2x - y) dy &= (-x - 2y) dx \\ (x + 2y) dx + (2x - y) dy &= 0\end{aligned} \tag{2A}$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= x + 2y \\ N(x, y) &= 2x - y\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(x + 2y) \\ &= 2\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(2x - y) \\ &= 2\end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \quad (1)$$

$$\frac{\partial \phi}{\partial y} = N \quad (2)$$

Integrating (1) w.r.t. x gives

$$\int \frac{\partial \phi}{\partial x} dx = \int M dx$$

$$\int \frac{\partial \phi}{\partial x} dx = \int x + 2y dx$$

$$\phi = \frac{x(x + 4y)}{2} + f(y) \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = 2x + f'(y) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = 2x - y$. Therefore equation (4) becomes

$$2x - y = 2x + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = -y$$

Integrating the above w.r.t y gives

$$\int f'(y) dy = \int (-y) dy$$

$$f(y) = -\frac{y^2}{2} + c_1$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = \frac{x(x + 4y)}{2} - \frac{y^2}{2} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = \frac{x(x + 4y)}{2} - \frac{y^2}{2}$$

Summary

The solution(s) found are the following

$$\frac{x(4y + x)}{2} - \frac{y^2}{2} = c_1 \quad (1)$$

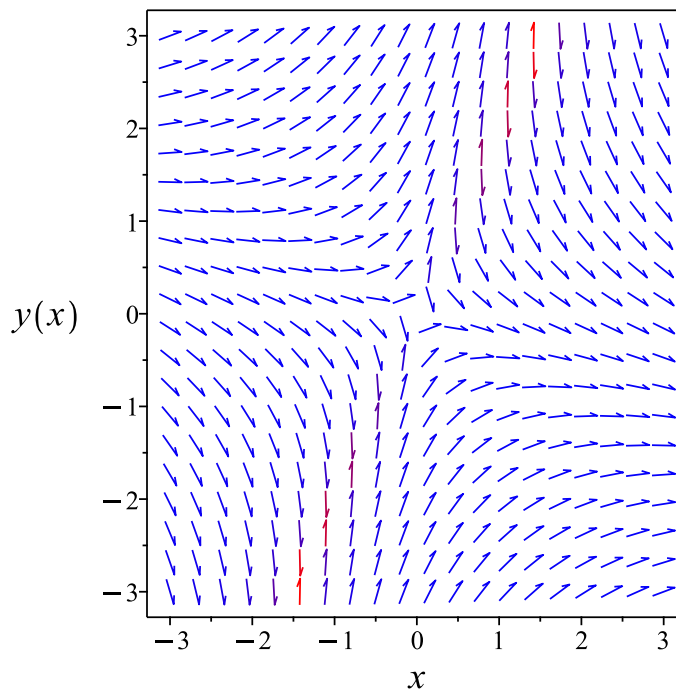


Figure 133: Slope field plot

Verification of solutions

$$\frac{x(4y + x)}{2} - \frac{y^2}{2} = c_1$$

Verified OK.

4.21.5 Maple step by step solution

Let's solve

$$2y + (2x - y)y' = -x$$

- Highest derivative means the order of the ODE is 1

$$y'$$

- Check if ODE is exact

- ODE is exact if the lhs is the total derivative of a C^2 function

$$F'(x, y) = 0$$

- Compute derivative of lhs

$$F'(x, y) + \left(\frac{\partial}{\partial y} F(x, y)\right) y' = 0$$

- Evaluate derivatives

$$2 = 2$$

- Condition met, ODE is exact

- Exact ODE implies solution will be of this form

$$\left[F(x, y) = c_1, M(x, y) = F'(x, y), N(x, y) = \frac{\partial}{\partial y} F(x, y) \right]$$

- Solve for $F(x, y)$ by integrating $M(x, y)$ with respect to x

$$F(x, y) = \int (x + 2y) dx + f_1(y)$$

- Evaluate integral

$$F(x, y) = \frac{x^2}{2} + 2xy + f_1(y)$$

- Take derivative of $F(x, y)$ with respect to y

$$N(x, y) = \frac{\partial}{\partial y} F(x, y)$$

- Compute derivative

$$2x - y = 2x + \frac{d}{dy} f_1(y)$$

- Isolate for $\frac{d}{dy} f_1(y)$

$$\frac{d}{dy} f_1(y) = -y$$

- Solve for $f_1(y)$

$$f_1(y) = -\frac{y^2}{2}$$

- Substitute $f_1(y)$ into equation for $F(x, y)$

$$F(x, y) = \frac{1}{2}x^2 + 2xy - \frac{1}{2}y^2$$

- Substitute $F(x, y)$ into the solution of the ODE

$$\frac{1}{2}x^2 + 2xy - \frac{1}{2}y^2 = c_1$$

- Solve for y

$$\{y = 2x - \sqrt{5x^2 - 2c_1}, y = 2x + \sqrt{5x^2 - 2c_1}\}$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
trying separable
trying inverse linear
trying homogeneous types:
trying homogeneous D
<- homogeneous successful`

```

✓ Solution by Maple

Time used: 0.047 (sec). Leaf size: 51

```
dsolve((x+2*y(x))+(2*x-y(x))*diff(y(x),x)=0,y(x), singsol=all)
```

$$y(x) = \frac{2c_1x - \sqrt{5c_1^2x^2 + 1}}{c_1}$$

$$y(x) = \frac{2c_1x + \sqrt{5c_1^2x^2 + 1}}{c_1}$$

✓ Solution by Mathematica

Time used: 0.777 (sec). Leaf size: 94

```
DSolve[(x+2*y[x])+(2*x-y[x])*y'[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow 2x - \sqrt{5x^2 + e^{2c_1}}$$

$$y(x) \rightarrow 2x + \sqrt{5x^2 + e^{2c_1}}$$

$$y(x) \rightarrow 2x - \sqrt{5}\sqrt{x^2}$$

$$y(x) \rightarrow \sqrt{5}\sqrt{x^2} + 2x$$

4.22 problem 22(b)

4.22.1 Solving as homogeneousTypeD2 ode	731
4.22.2 Solving as differentialType ode	733
4.22.3 Solving as first order ode lie symmetry calculated ode	735
4.22.4 Solving as exact ode	740
4.22.5 Maple step by step solution	744

Internal problem ID [11635]

Internal file name [OUTPUT/10617_Saturday_May_27_2023_04_14_56_AM_12227773/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 2, section 2.2 (Separable equations). Exercises page 47

Problem number: 22(b).

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact", "differentialType", "homogeneousTypeD2", "first_order_ode_lie_symmetry_calculated"

Maple gives the following as the ode type

```
[[_homogeneous, `class A`], _exact, _rational, [_Abel, `2nd
  type`, `class A`]]
```

$$-y - (y + x)y' = -3x$$

4.22.1 Solving as homogeneousTypeD2 ode

Using the change of variables $y = u(x)x$ on the above ode results in new ode in $u(x)$

$$-u(x)x - (u(x)x + x)(u'(x)x + u(x)) = -3x$$

In canonical form the ODE is

$$\begin{aligned}u' &= F(x, u) \\ &= f(x)g(u) \\ &= -\frac{u^2 + 2u - 3}{(u + 1)x}\end{aligned}$$

Where $f(x) = -\frac{1}{x}$ and $g(u) = \frac{u^2+2u-3}{u+1}$. Integrating both sides gives

$$\frac{1}{\frac{u^2+2u-3}{u+1}} du = -\frac{1}{x} dx$$

$$\int \frac{1}{\frac{u^2+2u-3}{u+1}} du = \int -\frac{1}{x} dx$$

$$\frac{\ln(u^2 + 2u - 3)}{2} = -\ln(x) + c_2$$

Raising both side to exponential gives

$$\sqrt{u^2 + 2u - 3} = e^{-\ln(x)+c_2}$$

Which simplifies to

$$\sqrt{u^2 + 2u - 3} = \frac{c_3}{x}$$

Which simplifies to

$$\sqrt{u(x)^2 + 2u(x) - 3} = \frac{c_3 e^{c_2}}{x}$$

The solution is

$$\sqrt{u(x)^2 + 2u(x) - 3} = \frac{c_3 e^{c_2}}{x}$$

Replacing $u(x)$ in the above solution by $\frac{y}{x}$ results in the solution for y in implicit form

$$\sqrt{\frac{y^2}{x^2} + \frac{2y}{x} - 3} = \frac{c_3 e^{c_2}}{x}$$

$$\sqrt{\frac{y^2 + 2yx - 3x^2}{x^2}} = \frac{c_3 e^{c_2}}{x}$$

Which simplifies to

$$\sqrt{-\frac{(3x + y)(-y + x)}{x^2}} = \frac{c_3 e^{c_2}}{x}$$

Summary

The solution(s) found are the following

$$\sqrt{-\frac{(3x + y)(-y + x)}{x^2}} = \frac{c_3 e^{c_2}}{x} \quad (1)$$

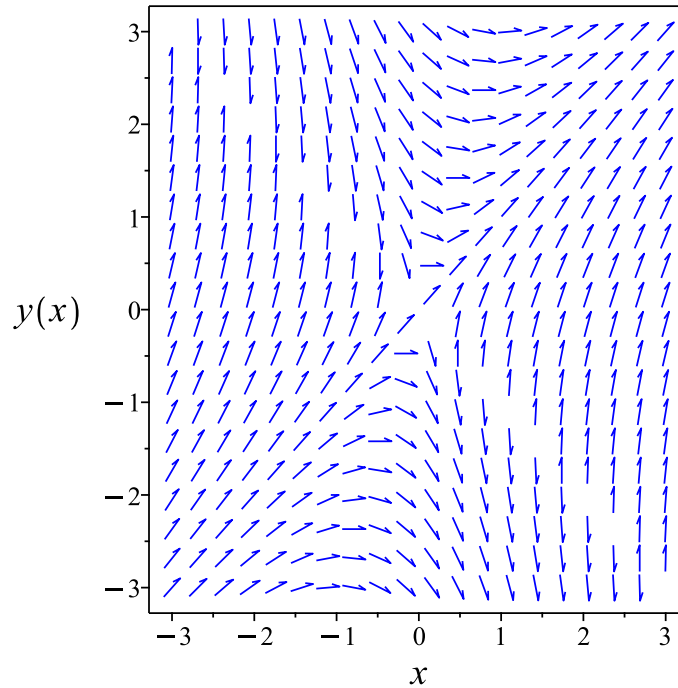


Figure 134: Slope field plot

Verification of solutions

$$\sqrt{-\frac{(3x + y)(-y + x)}{x^2}} = \frac{c_3 e^{c_2}}{x}$$

Verified OK.

4.22.2 Solving as differentialType ode

Writing the ode as

$$y' = \frac{-3x + y}{-y - x} \tag{1}$$

Which becomes

$$(y) dy = (-x) dy + (3x - y) dx \tag{2}$$

But the RHS is complete differential because

$$(-x) dy + (3x - y) dx = d\left(\frac{3}{2}x^2 - xy\right)$$

Hence (2) becomes

$$(y) dy = d\left(\frac{3}{2}x^2 - xy\right)$$

Integrating both sides gives gives these solutions

$$y = -x + \sqrt{4x^2 + 2c_1} + c_1$$

$$y = -x - \sqrt{4x^2 + 2c_1} + c_1$$

Summary

The solution(s) found are the following

$$y = -x + \sqrt{4x^2 + 2c_1} + c_1 \tag{1}$$

$$y = -x - \sqrt{4x^2 + 2c_1} + c_1 \tag{2}$$

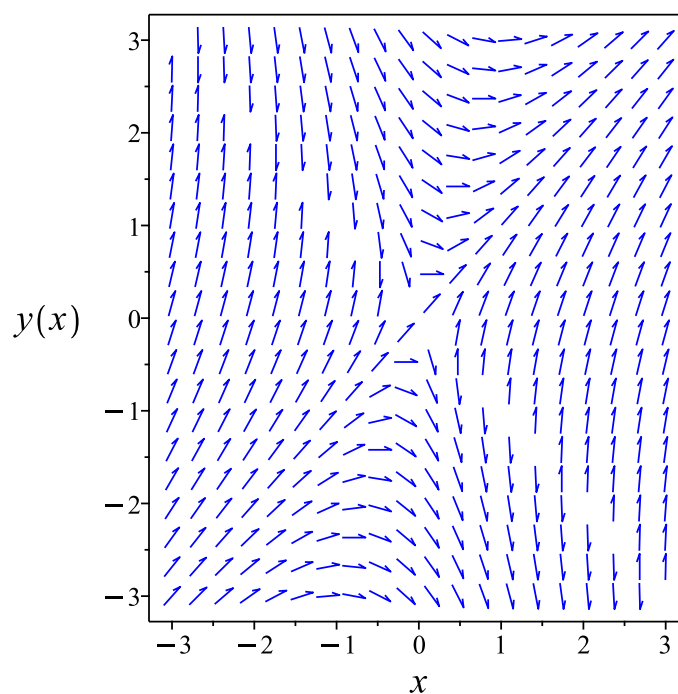


Figure 135: Slope field plot

Verification of solutions

$$y = -x + \sqrt{4x^2 + 2c_1} + c_1$$

Verified OK.

$$y = -x - \sqrt{4x^2 + 2c_1} + c_1$$

Verified OK.

4.22.3 Solving as first order ode lie symmetry calculated ode

Writing the ode as

$$y' = -\frac{-3x + y}{y + x}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is not in the lookup table. To determine ξ, η then (A) is solved using ansatz. Making bivariate polynomials of degree 1 to use as anstaz gives

$$\xi = xa_2 + ya_3 + a_1 \quad (\text{1E})$$

$$\eta = xb_2 + yb_3 + b_1 \quad (\text{2E})$$

Where the unknown coefficients are

$$\{a_1, a_2, a_3, b_1, b_2, b_3\}$$

Substituting equations (1E,2E) and ω into (A) gives

$$b_2 - \frac{(-3x + y)(b_3 - a_2)}{y + x} - \frac{(-3x + y)^2 a_3}{(y + x)^2}$$

$$- \left(\frac{3}{y + x} + \frac{-3x + y}{(y + x)^2} \right) (xa_2 + ya_3 + a_1) \quad (\text{5E})$$

$$- \left(-\frac{1}{y + x} + \frac{-3x + y}{(y + x)^2} \right) (xb_2 + yb_3 + b_1) = 0$$

Putting the above in normal form gives

$$\frac{3x^2a_2 + 9x^2a_3 - 5x^2b_2 - 3x^2b_3 + 6xya_2 - 6xya_3 - 2xyb_2 - 6xyb_3 - y^2a_2 + 5y^2a_3 - y^2b_2 + y^2b_3 - 4xb_1}{(y + x)^2}$$

$$= 0$$

Setting the numerator to zero gives

$$-3x^2a_2 - 9x^2a_3 + 5x^2b_2 + 3x^2b_3 - 6xya_2 + 6xya_3 + 2xyb_2 \quad (\text{6E})$$

$$+ 6xyb_3 + y^2a_2 - 5y^2a_3 + y^2b_2 - y^2b_3 + 4xb_1 - 4ya_1 = 0$$

Looking at the above PDE shows the following are all the terms with $\{x, y\}$ in them.

$$\{x, y\}$$

The following substitution is now made to be able to collect on all terms with $\{x, y\}$ in them

$$\{x = v_1, y = v_2\}$$

The above PDE (6E) now becomes

$$\begin{aligned} & -3a_2v_1^2 - 6a_2v_1v_2 + a_2v_2^2 - 9a_3v_1^2 + 6a_3v_1v_2 - 5a_3v_2^2 + 5b_2v_1^2 \\ & + 2b_2v_1v_2 + b_2v_2^2 + 3b_3v_1^2 + 6b_3v_1v_2 - b_3v_2^2 - 4a_1v_2 + 4b_1v_1 = 0 \end{aligned} \quad (7E)$$

Collecting the above on the terms v_i introduced, and these are

$$\{v_1, v_2\}$$

Equation (7E) now becomes

$$\begin{aligned} & (-3a_2 - 9a_3 + 5b_2 + 3b_3)v_1^2 + (-6a_2 + 6a_3 + 2b_2 + 6b_3)v_1v_2 \\ & + 4b_1v_1 + (a_2 - 5a_3 + b_2 - b_3)v_2^2 - 4a_1v_2 = 0 \end{aligned} \quad (8E)$$

Setting each coefficients in (8E) to zero gives the following equations to solve

$$\begin{aligned} -4a_1 &= 0 \\ 4b_1 &= 0 \\ -6a_2 + 6a_3 + 2b_2 + 6b_3 &= 0 \\ -3a_2 - 9a_3 + 5b_2 + 3b_3 &= 0 \\ a_2 - 5a_3 + b_2 - b_3 &= 0 \end{aligned}$$

Solving the above equations for the unknowns gives

$$\begin{aligned} a_1 &= 0 \\ a_2 &= 2a_3 + b_3 \\ a_3 &= a_3 \\ b_1 &= 0 \\ b_2 &= 3a_3 \\ b_3 &= b_3 \end{aligned}$$

Substituting the above solution in the anstaz (1E,2E) (using 1 as arbitrary value for any unknown in the RHS) gives

$$\begin{aligned}\xi &= x \\ \eta &= y\end{aligned}$$

Shifting is now applied to make $\xi = 0$ in order to simplify the rest of the computation

$$\begin{aligned}\eta &= \eta - \omega(x, y) \xi \\ &= y - \left(-\frac{-3x + y}{y + x} \right) (x) \\ &= \frac{-3x^2 + 2xy + y^2}{y + x} \\ \xi &= 0\end{aligned}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \quad (1)$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y} \right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned}S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{-3x^2 + 2xy + y^2}{y + x}} dy\end{aligned}$$

Which results in

$$S = \frac{\ln(-3x^2 + 2xy + y^2)}{2}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y) S_y}{R_x + \omega(x, y) R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{-3x + y}{y + x}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= \frac{3x - y}{(3x + y)(-y + x)} \\ S_y &= \frac{-y - x}{(3x + y)(-y + x)} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 0 \tag{2A}$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 0$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = c_1 \tag{4}$$

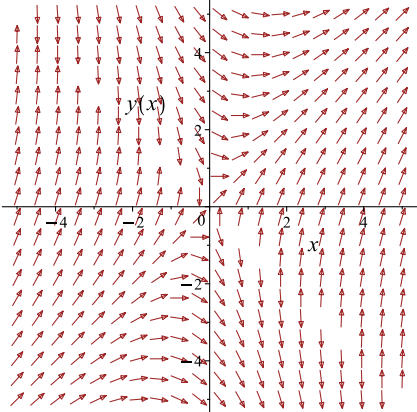
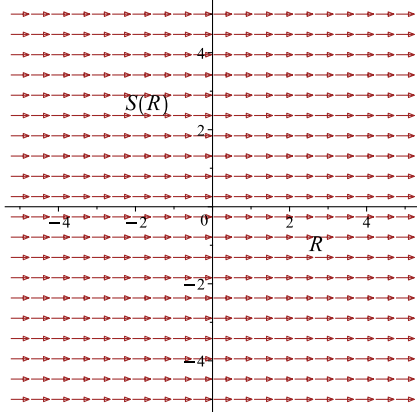
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$\frac{\ln(-3x - y)}{2} + \frac{\ln(-y + x)}{2} = c_1$$

Which simplifies to

$$\frac{\ln(-3x - y)}{2} + \frac{\ln(-y + x)}{2} = c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{-3x+y}{y+x}$ 	$R = x$ $S = \frac{\ln(-3x - y)}{2} + \frac{\ln(-y + x)}{2}$	$\frac{dS}{dR} = 0$ 

Summary

The solution(s) found are the following

$$\frac{\ln(-3x - y)}{2} + \frac{\ln(-y + x)}{2} = c_1 \tag{1}$$

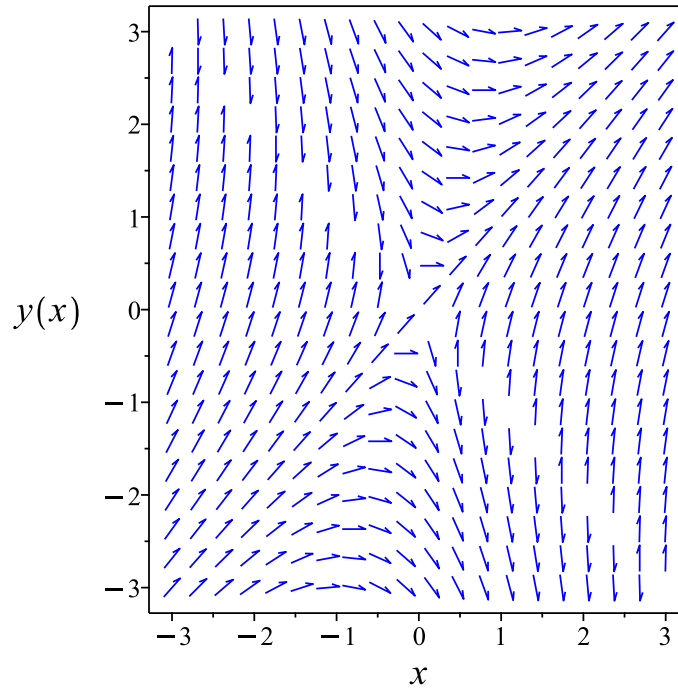


Figure 136: Slope field plot

Verification of solutions

$$\frac{\ln(-3x - y)}{2} + \frac{\ln(-y + x)}{2} = c_1$$

Verified OK.

4.22.4 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx}\phi(x, y) = 0$$

Hence

$$\frac{\partial\phi}{\partial x} + \frac{\partial\phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \tag{1A}$$

Therefore

$$\begin{aligned}(-y - x) dy &= (-3x + y) dx \\ (3x - y) dx + (-y - x) dy &= 0\end{aligned} \tag{2A}$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= 3x - y \\ N(x, y) &= -y - x\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(3x - y) \\ &= -1\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(-y - x) \\ &= -1\end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \quad (1)$$

$$\frac{\partial \phi}{\partial y} = N \quad (2)$$

Integrating (1) w.r.t. x gives

$$\begin{aligned} \int \frac{\partial \phi}{\partial x} dx &= \int M dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int 3x - y dx \\ \phi &= \frac{x(3x - 2y)}{2} + f(y) \end{aligned} \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = -x + f'(y) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = -y - x$. Therefore equation (4) becomes

$$-y - x = -x + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = -y$$

Integrating the above w.r.t y gives

$$\begin{aligned} \int f'(y) dy &= \int (-y) dy \\ f(y) &= -\frac{y^2}{2} + c_1 \end{aligned}$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = \frac{x(3x - 2y)}{2} - \frac{y^2}{2} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = \frac{x(3x - 2y)}{2} - \frac{y^2}{2}$$

Summary

The solution(s) found are the following

$$\frac{x(3x - 2y)}{2} - \frac{y^2}{2} = c_1 \quad (1)$$

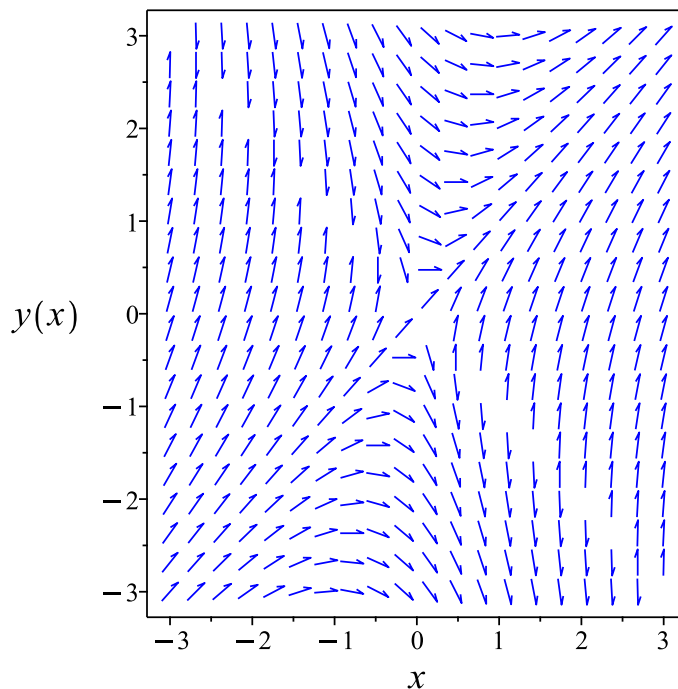


Figure 137: Slope field plot

Verification of solutions

$$\frac{x(3x - 2y)}{2} - \frac{y^2}{2} = c_1$$

Verified OK.

4.22.5 Maple step by step solution

Let's solve

$$-y - (y + x) y' = -3x$$

- Highest derivative means the order of the ODE is 1

y'

- Check if ODE is exact

- ODE is exact if the lhs is the total derivative of a C^2 function

$$F'(x, y) = 0$$

- Compute derivative of lhs

$$F'(x, y) + \left(\frac{\partial}{\partial y} F(x, y) \right) y' = 0$$

- Evaluate derivatives

$$-1 = -1$$

- Condition met, ODE is exact

- Exact ODE implies solution will be of this form

$$\left[F(x, y) = c_1, M(x, y) = F'(x, y), N(x, y) = \frac{\partial}{\partial y} F(x, y) \right]$$

- Solve for $F(x, y)$ by integrating $M(x, y)$ with respect to x

$$F(x, y) = \int (3x - y) dx + f_1(y)$$

- Evaluate integral

$$F(x, y) = \frac{3x^2}{2} - xy + f_1(y)$$

- Take derivative of $F(x, y)$ with respect to y

$$N(x, y) = \frac{\partial}{\partial y} F(x, y)$$

- Compute derivative

$$-y - x = -x + \frac{d}{dy} f_1(y)$$

- Isolate for $\frac{d}{dy} f_1(y)$

$$\frac{d}{dy} f_1(y) = -y$$

- Solve for $f_1(y)$

$$f_1(y) = -\frac{y^2}{2}$$

- Substitute $f_1(y)$ into equation for $F(x, y)$

$$F(x, y) = \frac{3}{2}x^2 - xy - \frac{1}{2}y^2$$

- Substitute $F(x, y)$ into the solution of the ODE

$$\frac{3}{2}x^2 - xy - \frac{1}{2}y^2 = c_1$$

- Solve for y

$$\{y = -x - \sqrt{4x^2 - 2c_1}, y = -x + \sqrt{4x^2 - 2c_1}\}$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
trying separable
trying inverse linear
trying homogeneous types:
trying homogeneous D
<- homogeneous successful`

```

✓ Solution by Maple

Time used: 0.047 (sec). Leaf size: 51

```
dsolve((3*x-y(x))-(x+y(x))*diff(y(x),x)=0,y(x), singsol=all)
```

$$y(x) = \frac{-c_1x - \sqrt{4c_1^2x^2 + 1}}{c_1}$$

$$y(x) = \frac{-c_1x + \sqrt{4c_1^2x^2 + 1}}{c_1}$$

✓ Solution by Mathematica

Time used: 0.752 (sec). Leaf size: 85

```
DSolve[(3*x-y[x])-(x+y[x])*y'[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow -x - \sqrt{4x^2 + e^{2c_1}}$$

$$y(x) \rightarrow -x + \sqrt{4x^2 + e^{2c_1}}$$

$$y(x) \rightarrow -2\sqrt{x^2} - x$$

$$y(x) \rightarrow 2\sqrt{x^2} - x$$

4.23 problem 23(a)

4.23.1 Solving as homogeneousTypeD2 ode	747
4.23.2 Solving as first order ode lie symmetry calculated ode	749
4.23.3 Solving as exact ode	755
4.23.4 Maple step by step solution	759

Internal problem ID [11636]

Internal file name [OUTPUT/10618_Saturday_May_27_2023_04_15_00_AM_83412974/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 2, section 2.2 (Separable equations). Exercises page 47

Problem number: 23(a).

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact", "homogeneousTypeD2", "first_order_ode_lie_symmetry_calculated"

Maple gives the following as the ode type

```
[[_homogeneous, `class A`], _exact, _rational, _dAlembert]
```

$$2y^2 + (4yx - y^2) y' = -x^2$$

4.23.1 Solving as homogeneousTypeD2 ode

Using the change of variables $y = u(x)x$ on the above ode results in new ode in $u(x)$

$$2u(x)^2 x^2 + (4u(x)x^2 - u(x)^2 x^2) (u'(x)x + u(x)) = -x^2$$

In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= -\frac{u^3 - 6u^2 - 1}{ux(u - 4)} \end{aligned}$$

Where $f(x) = -\frac{1}{x}$ and $g(u) = \frac{u^3-6u^2-1}{(u-4)u}$. Integrating both sides gives

$$\begin{aligned}\frac{1}{\frac{u^3-6u^2-1}{(u-4)u}} du &= -\frac{1}{x} dx \\ \int \frac{1}{\frac{u^3-6u^2-1}{(u-4)u}} du &= \int -\frac{1}{x} dx \\ \frac{\ln(u^3 - 6u^2 - 1)}{3} &= -\ln(x) + c_2\end{aligned}$$

Raising both side to exponential gives

$$(u^3 - 6u^2 - 1)^{\frac{1}{3}} = e^{-\ln(x)+c_2}$$

Which simplifies to

$$(u^3 - 6u^2 - 1)^{\frac{1}{3}} = \frac{c_3}{x}$$

Which simplifies to

$$(u(x)^3 - 6u(x)^2 - 1)^{\frac{1}{3}} = \frac{c_3 e^{c_2}}{x}$$

The solution is

$$(u(x)^3 - 6u(x)^2 - 1)^{\frac{1}{3}} = \frac{c_3 e^{c_2}}{x}$$

Replacing $u(x)$ in the above solution by $\frac{y}{x}$ results in the solution for y in implicit form

$$\begin{aligned}\left(\frac{y^3}{x^3} - \frac{6y^2}{x^2} - 1\right)^{\frac{1}{3}} &= \frac{c_3 e^{c_2}}{x} \\ \left(\frac{y^3 - 6y^2x - x^3}{x^3}\right)^{\frac{1}{3}} &= \frac{c_3 e^{c_2}}{x}\end{aligned}$$

Summary

The solution(s) found are the following

$$\left(\frac{y^3 - 6y^2x - x^3}{x^3}\right)^{\frac{1}{3}} = \frac{c_3 e^{c_2}}{x} \quad (1)$$

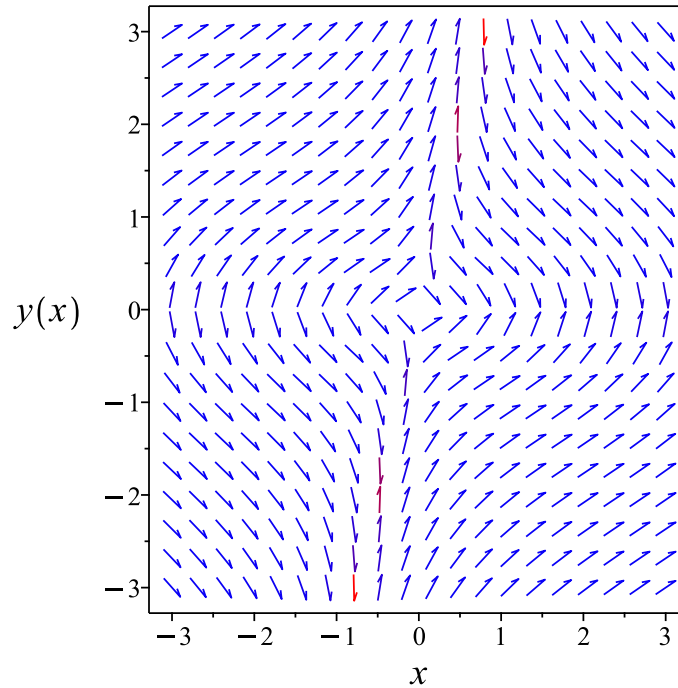


Figure 138: Slope field plot

Verification of solutions

$$\left(\frac{y^3 - 6y^2x - x^3}{x^3} \right)^{\frac{1}{3}} = \frac{c_3 e^{c_2}}{x}$$

Verified OK.

4.23.2 Solving as first order ode lie symmetry calculated ode

Writing the ode as

$$y' = \frac{x^2 + 2y^2}{y(-4x + y)}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is not in the lookup table. To determine ξ, η then (A) is solved using ansatz. Making bivariate polynomials of degree 1 to use as anstaz gives

$$\xi = xa_2 + ya_3 + a_1 \quad (\text{1E})$$

$$\eta = xb_2 + yb_3 + b_1 \quad (\text{2E})$$

Where the unknown coefficients are

$$\{a_1, a_2, a_3, b_1, b_2, b_3\}$$

Substituting equations (1E,2E) and ω into (A) gives

$$\begin{aligned} b_2 + \frac{(x^2 + 2y^2)(b_3 - a_2)}{y(-4x + y)} - \frac{(x^2 + 2y^2)^2 a_3}{y^2(-4x + y)^2} \\ - \left(\frac{2x}{y(-4x + y)} + \frac{4x^2 + 8y^2}{y(-4x + y)^2} \right) (xa_2 + ya_3 + a_1) \\ - \left(\frac{4}{-4x + y} - \frac{x^2 + 2y^2}{y^2(-4x + y)} - \frac{x^2 + 2y^2}{y(-4x + y)^2} \right) (xb_2 + yb_3 + b_1) = 0 \end{aligned} \quad (5E)$$

Putting the above in normal form gives

$$\frac{-x^4 a_3 + 4x^4 b_2 - 8x^3 y a_2 - 2x^3 y b_2 + 8x^3 y b_3 + 3x^2 y^2 a_2 - 24x^2 y^2 b_2 - 3x^2 y^2 b_3 + 2x y^3 a_3 + 8x y^3 b_2 + 2y^4 a_2}{y^2(4x - y)^2} = 0$$

Setting the numerator to zero gives

$$\begin{aligned} -x^4 a_3 - 4x^4 b_2 + 8x^3 y a_2 + 2x^3 y b_2 - 8x^3 y b_3 - 3x^2 y^2 a_2 + 24x^2 y^2 b_2 \\ + 3x^2 y^2 b_3 - 2x y^3 a_3 - 8x y^3 b_2 - 2y^4 a_2 - 12y^4 a_3 + y^4 b_2 + 2y^4 b_3 \\ - 4x^3 b_1 + 4x^2 y a_1 + 2x^2 y b_1 - 2x y^2 a_1 + 8x y^2 b_1 - 8y^3 a_1 = 0 \end{aligned} \quad (6E)$$

Looking at the above PDE shows the following are all the terms with $\{x, y\}$ in them.

$$\{x, y\}$$

The following substitution is now made to be able to collect on all terms with $\{x, y\}$ in them

$$\{x = v_1, y = v_2\}$$

The above PDE (6E) now becomes

$$\begin{aligned} 8a_2 v_1^3 v_2 - 3a_2 v_1^2 v_2^2 - 2a_2 v_2^4 - a_3 v_1^4 - 2a_3 v_1 v_2^3 - 12a_3 v_2^4 - 4b_2 v_1^4 \\ + 2b_2 v_1^3 v_2 + 24b_2 v_1^2 v_2^2 - 8b_2 v_1 v_2^3 + b_2 v_2^4 - 8b_3 v_1^3 v_2 + 3b_3 v_1^2 v_2^2 + 2b_3 v_2^4 \\ + 4a_1 v_1^2 v_2 - 2a_1 v_1 v_2^2 - 8a_1 v_2^3 - 4b_1 v_1^3 + 2b_1 v_1^2 v_2 + 8b_1 v_1 v_2^2 = 0 \end{aligned} \quad (7E)$$

Collecting the above on the terms v_i introduced, and these are

$$\{v_1, v_2\}$$

Equation (7E) now becomes

$$\begin{aligned} &(-a_3 - 4b_2) v_1^4 + (8a_2 + 2b_2 - 8b_3) v_1^3 v_2 - 4b_1 v_1^3 \\ &+ (-3a_2 + 24b_2 + 3b_3) v_1^2 v_2^2 + (4a_1 + 2b_1) v_1^2 v_2 + (-2a_3 - 8b_2) v_1 v_2^3 \\ &+ (-2a_1 + 8b_1) v_1 v_2^2 + (-2a_2 - 12a_3 + b_2 + 2b_3) v_2^4 - 8a_1 v_2^3 = 0 \end{aligned} \quad (8E)$$

Setting each coefficients in (8E) to zero gives the following equations to solve

$$\begin{aligned} -8a_1 &= 0 \\ -4b_1 &= 0 \\ -2a_1 + 8b_1 &= 0 \\ 4a_1 + 2b_1 &= 0 \\ -2a_3 - 8b_2 &= 0 \\ -a_3 - 4b_2 &= 0 \\ -3a_2 + 24b_2 + 3b_3 &= 0 \\ 8a_2 + 2b_2 - 8b_3 &= 0 \\ -2a_2 - 12a_3 + b_2 + 2b_3 &= 0 \end{aligned}$$

Solving the above equations for the unknowns gives

$$\begin{aligned} a_1 &= 0 \\ a_2 &= b_3 \\ a_3 &= 0 \\ b_1 &= 0 \\ b_2 &= 0 \\ b_3 &= b_3 \end{aligned}$$

Substituting the above solution in the anstaz (1E,2E) (using 1 as arbitrary value for any unknown in the RHS) gives

$$\begin{aligned} \xi &= x \\ \eta &= y \end{aligned}$$

Shifting is now applied to make $\xi = 0$ in order to simplify the rest of the computation

$$\begin{aligned}\eta &= \eta - \omega(x, y) \xi \\ &= y - \left(\frac{x^2 + 2y^2}{y(-4x + y)} \right) (x) \\ &= \frac{x^3 + 6xy^2 - y^3}{4xy - y^2} \\ \xi &= 0\end{aligned}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \quad (1)$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y} \right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned}S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{x^3 + 6xy^2 - y^3}{4xy - y^2}} dy\end{aligned}$$

Which results in

$$S = \frac{\ln(-x^3 - 6xy^2 + y^3)}{3}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = \frac{x^2 + 2y^2}{y(-4x + y)}$$

Evaluating all the partial derivatives gives

$$\begin{aligned}R_x &= 1 \\R_y &= 0 \\S_x &= \frac{x^2 + 2y^2}{x^3 + 6xy^2 - y^3} \\S_y &= \frac{y(4x - y)}{x^3 + 6xy^2 - y^3}\end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 0 \tag{2A}$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 0$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = c_1 \tag{4}$$

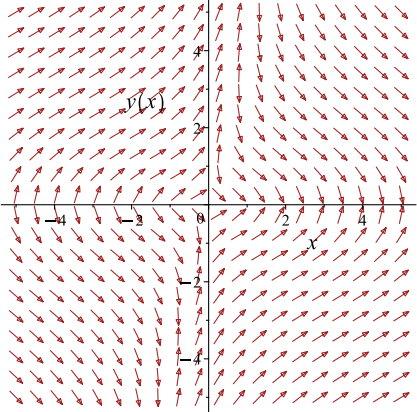
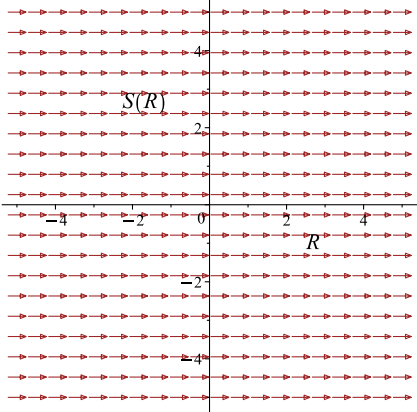
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$\frac{\ln(y^3 - 6y^2x - x^3)}{3} = c_1$$

Which simplifies to

$$\frac{\ln(y^3 - 6y^2x - x^3)}{3} = c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = \frac{x^2 + 2y^2}{y(-4x + y)}$ 	$R = x$ $S = \frac{\ln(-x^3 - 6xy^2 + y^3)}{3}$	$\frac{dS}{dR} = 0$ 

Summary

The solution(s) found are the following

$$\frac{\ln(y^3 - 6y^2x - x^3)}{3} = c_1 \tag{1}$$

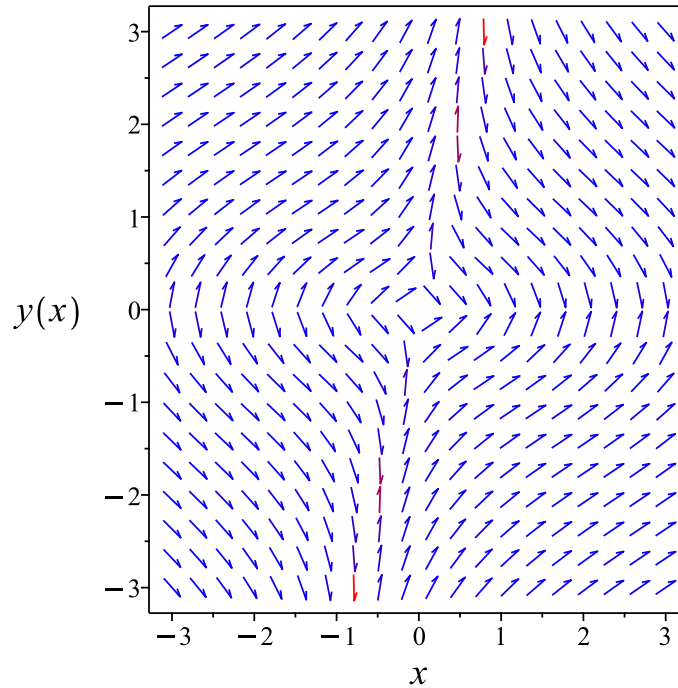


Figure 139: Slope field plot

Verification of solutions

$$\frac{\ln(y^3 - 6y^2x - x^3)}{3} = c_1$$

Verified OK.

4.23.3 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx}\phi(x, y) = 0$$

Hence

$$\frac{\partial\phi}{\partial x} + \frac{\partial\phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \tag{1A}$$

Therefore

$$\begin{aligned}(4xy - y^2) dy &= (-x^2 - 2y^2) dx \\ (x^2 + 2y^2) dx + (4xy - y^2) dy &= 0\end{aligned} \tag{2A}$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= x^2 + 2y^2 \\ N(x, y) &= 4xy - y^2\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(x^2 + 2y^2) \\ &= 4y\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(4xy - y^2) \\ &= 4y\end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \quad (1)$$

$$\frac{\partial \phi}{\partial y} = N \quad (2)$$

Integrating (1) w.r.t. x gives

$$\int \frac{\partial \phi}{\partial x} dx = \int M dx$$

$$\int \frac{\partial \phi}{\partial x} dx = \int x^2 + 2y^2 dx$$

$$\phi = \frac{1}{3}x^3 + 2xy^2 + f(y) \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = 4xy + f'(y) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = 4xy - y^2$. Therefore equation (4) becomes

$$4xy - y^2 = 4xy + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = -y^2$$

Integrating the above w.r.t y gives

$$\int f'(y) dy = \int (-y^2) dy$$

$$f(y) = -\frac{y^3}{3} + c_1$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = \frac{1}{3}x^3 + 2xy^2 - \frac{1}{3}y^3 + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = \frac{1}{3}x^3 + 2xy^2 - \frac{1}{3}y^3$$

Summary

The solution(s) found are the following

$$\frac{x^3}{3} + 2y^2x - \frac{y^3}{3} = c_1 \quad (1)$$

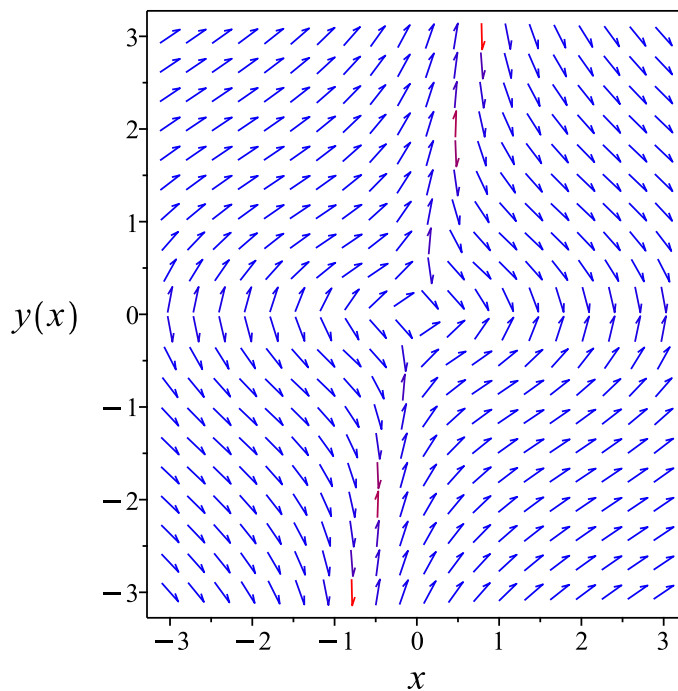


Figure 140: Slope field plot

Verification of solutions

$$\frac{x^3}{3} + 2y^2x - \frac{y^3}{3} = c_1$$

Verified OK.

4.23.4 Maple step by step solution

Let's solve

$$2y^2 + (4yx - y^2) y' = -x^2$$

- Highest derivative means the order of the ODE is 1

y'

- Check if ODE is exact

- ODE is exact if the lhs is the total derivative of a C^2 function

$$F'(x, y) = 0$$

- Compute derivative of lhs

$$F'(x, y) + \left(\frac{\partial}{\partial y} F(x, y) \right) y' = 0$$

- Evaluate derivatives

$$4y = 4y$$

- Condition met, ODE is exact

- Exact ODE implies solution will be of this form

$$\left[F(x, y) = c_1, M(x, y) = F'(x, y), N(x, y) = \frac{\partial}{\partial y} F(x, y) \right]$$

- Solve for $F(x, y)$ by integrating $M(x, y)$ with respect to x

$$F(x, y) = \int (x^2 + 2y^2) dx + f_1(y)$$

- Evaluate integral

$$F(x, y) = \frac{x^3}{3} + 2xy^2 + f_1(y)$$

- Take derivative of $F(x, y)$ with respect to y

$$N(x, y) = \frac{\partial}{\partial y} F(x, y)$$

- Compute derivative

$$4xy - y^2 = 4xy + \frac{d}{dy} f_1(y)$$

- Isolate for $\frac{d}{dy} f_1(y)$

$$\frac{d}{dy} f_1(y) = -y^2$$

- Solve for $f_1(y)$

$$f_1(y) = -\frac{y^3}{3}$$

- Substitute $f_1(y)$ into equation for $F(x, y)$

$$F(x, y) = \frac{1}{3}x^3 + 2xy^2 - \frac{1}{3}y^3$$

- Substitute $F(x, y)$ into the solution of the ODE

$$\frac{1}{3}x^3 + 2xy^2 - \frac{1}{3}y^3 = c_1$$

- Solve for y

$$\left\{ y = \frac{\left(68x^3 - 12c_1 + 4\sqrt{33x^6 - 102c_1x^3 + 9c_1^2}\right)^{\frac{1}{3}}}{2} + \frac{8x^2}{\left(68x^3 - 12c_1 + 4\sqrt{33x^6 - 102c_1x^3 + 9c_1^2}\right)^{\frac{1}{3}}} + 2x, y = -\frac{\left(68x^3 - 12c_1 + 4\sqrt{33x^6 - 102c_1x^3 + 9c_1^2}\right)^{\frac{1}{3}}}{2} - \frac{8x^2}{\left(68x^3 - 12c_1 + 4\sqrt{33x^6 - 102c_1x^3 + 9c_1^2}\right)^{\frac{1}{3}}} + 2x \right.$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
trying separable
trying inverse linear
trying homogeneous types:
trying homogeneous D
<- homogeneous successful`

```

✓ Solution by Maple

Time used: 0.063 (sec). Leaf size: 439

`dsolve((x^2+2*y(x)^2)+(4*x*y(x)-y(x)^2)*diff(y(x),x)=0,y(x), singsol=all)`

$$y(x) = \frac{\left(\frac{4+68c_1^3x^3+4\sqrt{33c_1^6x^6+34c_1^3x^3+1}}{2}\right)^{\frac{1}{3}} + \frac{8x^2c_1^2}{\left(4+68c_1^3x^3+4\sqrt{33c_1^6x^6+34c_1^3x^3+1}\right)^{\frac{1}{3}}} + 2c_1x}{c_1}$$

$$y(x) = \frac{-\left(\frac{4+68c_1^3x^3+4\sqrt{33c_1^6x^6+34c_1^3x^3+1}}{4}\right)^{\frac{1}{3}} - \frac{4x^2c_1^2}{\left(4+68c_1^3x^3+4\sqrt{33c_1^6x^6+34c_1^3x^3+1}\right)^{\frac{1}{3}}} + 2c_1x - \frac{i\sqrt{3}\left(-16c_1^2x^2+\left(4+68c_1^3x^3+4\sqrt{33c_1^6x^6+34c_1^3x^3+1}\right)^{\frac{1}{3}}\right)}{4\left(4+68c_1^3x^3+4\sqrt{33c_1^6x^6+34c_1^3x^3+1}\right)^{\frac{1}{3}}}}{c_1}$$

$$y(x) = \frac{16i\sqrt{3}c_1^2x^2 - i\sqrt{3}\left(4 + 68c_1^3x^3 + 4\sqrt{33c_1^6x^6 + 34c_1^3x^3 + 1}\right)^{\frac{2}{3}} + 16c_1^2x^2 - 8c_1x\left(4 + 68c_1^3x^3 + 4\sqrt{33c_1^6x^6 + 34c_1^3x^3 + 1}\right)^{\frac{1}{3}}}{4\left(4 + 68c_1^3x^3 + 4\sqrt{33c_1^6x^6 + 34c_1^3x^3 + 1}\right)^{\frac{1}{3}}}$$

✓ Solution by Mathematica

Time used: 33.481 (sec). Leaf size: 731

DSolve[(x^2+2*y[x]^2)+(4*x*y[x]-y[x]^2)*y'[x]==0,y[x],x,IncludeSingularSolutions -> True]

$$y(x) \rightarrow \frac{\sqrt[3]{17x^3 + \sqrt{33x^6 + 34e^{3c_1}x^3 + e^{6c_1}} + e^{3c_1}}}{\sqrt[3]{2}} + \frac{4\sqrt[3]{2}x^2}{\sqrt[3]{17x^3 + \sqrt{33x^6 + 34e^{3c_1}x^3 + e^{6c_1}} + e^{3c_1}}} + 2x$$

$$y(x) \rightarrow -\frac{(1 - i\sqrt{3})\sqrt[3]{17x^3 + \sqrt{33x^6 + 34e^{3c_1}x^3 + e^{6c_1}} + e^{3c_1}}}{2\sqrt[3]{2}} - \frac{2\sqrt[3]{2}(1 + i\sqrt{3})x^2}{\sqrt[3]{17x^3 + \sqrt{33x^6 + 34e^{3c_1}x^3 + e^{6c_1}} + e^{3c_1}}} + 2x$$

$$y(x) \rightarrow -\frac{(1 + i\sqrt{3})\sqrt[3]{17x^3 + \sqrt{33x^6 + 34e^{3c_1}x^3 + e^{6c_1}} + e^{3c_1}}}{2\sqrt[3]{2}} - \frac{2\sqrt[3]{2}(1 - i\sqrt{3})x^2}{\sqrt[3]{17x^3 + \sqrt{33x^6 + 34e^{3c_1}x^3 + e^{6c_1}} + e^{3c_1}}} + 2x$$

$$y(x) \rightarrow \frac{8\sqrt[3]{2}x^2 + 4\sqrt[3]{\sqrt{33}\sqrt{x^6} + 17x^3}x + 2^{2/3}(\sqrt{33}\sqrt{x^6} + 17x^3)^{2/3}}{2\sqrt[3]{\sqrt{33}\sqrt{x^6} + 17x^3}}$$

$$y(x) \rightarrow \frac{8i\sqrt[3]{2}\sqrt{3}x^2 - 8\sqrt[3]{2}x^2 + 8\sqrt[3]{\sqrt{33}\sqrt{x^6} + 17x^3}x - i2^{2/3}\sqrt{3}(\sqrt{33}\sqrt{x^6} + 17x^3)^{2/3} - 2^{2/3}(\sqrt{33}\sqrt{x^6} + 17x^3)}{4\sqrt[3]{\sqrt{33}\sqrt{x^6} + 17x^3}}$$

$$y(x) \rightarrow \frac{(\sqrt{33}\sqrt{x^6} + 17x^3)^{2/3} \text{Root}[2\#1^3 - 1\&, 3] - 4\sqrt[3]{-2}x^2 + 2\sqrt[3]{\sqrt{33}\sqrt{x^6} + 17x^3}x}{\sqrt[3]{\sqrt{33}\sqrt{x^6} + 17x^3}}$$

4.24 problem 23(b)

4.24.1 Solving as homogeneousTypeD2 ode	763
4.24.2 Solving as first order ode lie symmetry calculated ode	765
4.24.3 Solving as exact ode	771
4.24.4 Maple step by step solution	775

Internal problem ID [11637]

Internal file name [OUTPUT/10619_Saturday_May_27_2023_04_15_05_AM_75348991/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 2, section 2.2 (Separable equations). Exercises page 47

Problem number: 23(b).

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact", "homogeneousTypeD2", "first_order_ode_lie_symmetry_calculated"

Maple gives the following as the ode type

```
[[_homogeneous, `class A`], _exact, _rational, [_Abel, `2nd
  type`, `class B`]]
```

$$2yx + y^2 + (2yx + x^2) y' = -2x^2$$

4.24.1 Solving as homogeneousTypeD2 ode

Using the change of variables $y = u(x)x$ on the above ode results in new ode in $u(x)$

$$2u(x)x^2 + u(x)^2x^2 + (2u(x)x^2 + x^2)(u'(x)x + u(x)) = -2x^2$$

In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= -\frac{3u^2 + 3u + 2}{x(2u + 1)} \end{aligned}$$

Where $f(x) = -\frac{1}{x}$ and $g(u) = \frac{3u^2+3u+2}{2u+1}$. Integrating both sides gives

$$\begin{aligned}\frac{1}{\frac{3u^2+3u+2}{2u+1}} du &= -\frac{1}{x} dx \\ \int \frac{1}{\frac{3u^2+3u+2}{2u+1}} du &= \int -\frac{1}{x} dx \\ \frac{\ln(3u^2 + 3u + 2)}{3} &= -\ln(x) + c_2\end{aligned}$$

Raising both side to exponential gives

$$(3u^2 + 3u + 2)^{\frac{1}{3}} = e^{-\ln(x)+c_2}$$

Which simplifies to

$$(3u^2 + 3u + 2)^{\frac{1}{3}} = \frac{c_3}{x}$$

Which simplifies to

$$(3u(x)^2 + 3u(x) + 2)^{\frac{1}{3}} = \frac{c_3 e^{c_2}}{x}$$

The solution is

$$(3u(x)^2 + 3u(x) + 2)^{\frac{1}{3}} = \frac{c_3 e^{c_2}}{x}$$

Replacing $u(x)$ in the above solution by $\frac{y}{x}$ results in the solution for y in implicit form

$$\begin{aligned}\left(\frac{3y^2}{x^2} + \frac{3y}{x} + 2\right)^{\frac{1}{3}} &= \frac{c_3 e^{c_2}}{x} \\ \left(\frac{3y^2 + 3yx + 2x^2}{x^2}\right)^{\frac{1}{3}} &= \frac{c_3 e^{c_2}}{x}\end{aligned}$$

Summary

The solution(s) found are the following

$$\left(\frac{3y^2 + 3yx + 2x^2}{x^2}\right)^{\frac{1}{3}} = \frac{c_3 e^{c_2}}{x} \quad (1)$$

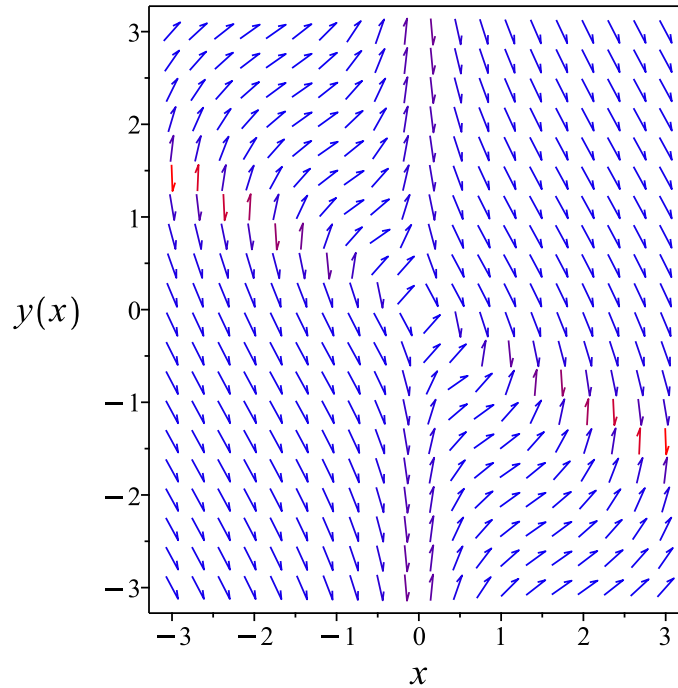


Figure 141: Slope field plot

Verification of solutions

$$\left(\frac{3y^2 + 3yx + 2x^2}{x^2} \right)^{\frac{1}{3}} = \frac{c_3 e^{c_2}}{x}$$

Verified OK.

4.24.2 Solving as first order ode lie symmetry calculated ode

Writing the ode as

$$y' = -\frac{2x^2 + 2xy + y^2}{x(x + 2y)}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is not in the lookup table. To determine ξ, η then (A) is solved using ansatz. Making bivariate polynomials of degree 1 to use as anstaz gives

$$\xi = xa_2 + ya_3 + a_1 \quad (\text{1E})$$

$$\eta = xb_2 + yb_3 + b_1 \quad (\text{2E})$$

Where the unknown coefficients are

$$\{a_1, a_2, a_3, b_1, b_2, b_3\}$$

Substituting equations (1E,2E) and ω into (A) gives

$$\begin{aligned} b_2 - \frac{(2x^2 + 2xy + y^2)(b_3 - a_2)}{x(x+2y)} - \frac{(2x^2 + 2xy + y^2)^2 a_3}{x^2(x+2y)^2} \\ - \left(-\frac{4x+2y}{x(x+2y)} + \frac{2x^2+2xy+y^2}{x^2(x+2y)} + \frac{2x^2+2xy+y^2}{x(x+2y)^2} \right) (xa_2 + ya_3 + a_1) \\ - \left(-\frac{2y+2x}{x(x+2y)} + \frac{4x^2+4xy+2y^2}{x(x+2y)^2} \right) (xb_2 + yb_3 + b_1) = 0 \end{aligned} \quad (5E)$$

Putting the above in normal form gives

$$\frac{2x^4a_2 - 4x^4a_3 - x^4b_2 - 2x^4b_3 + 8x^3ya_2 - 8x^3ya_3 + 6x^3yb_2 - 8x^3yb_3 + 3x^2y^2a_2 - 6x^2y^2a_3 + 6x^2y^2b_2 - 3x^2y^2b_3 - 6xy^3a_2 + 6xy^3a_3 - 3y^4a_2 + 3y^4a_3 - 2x^3b_1 + 2x^2ya_1 + 2x^2yb_1 - 2xy^2a_1 + 2xy^2b_1 - 2y^3a_1}{x^2(x+2y)^2} = 0$$

Setting the numerator to zero gives

$$\begin{aligned} 2x^4a_2 - 4x^4a_3 - x^4b_2 - 2x^4b_3 + 8x^3ya_2 - 8x^3ya_3 + 6x^3yb_2 - 8x^3yb_3 \\ + 3x^2y^2a_2 - 6x^2y^2a_3 + 6x^2y^2b_2 - 3x^2y^2b_3 - 6xy^3a_2 + 6xy^3a_3 - 3y^4a_2 + 3y^4a_3 \\ - 2x^3b_1 + 2x^2ya_1 + 2x^2yb_1 - 2xy^2a_1 + 2xy^2b_1 - 2y^3a_1 = 0 \end{aligned} \quad (6E)$$

Looking at the above PDE shows the following are all the terms with $\{x, y\}$ in them.

$$\{x, y\}$$

The following substitution is now made to be able to collect on all terms with $\{x, y\}$ in them

$$\{x = v_1, y = v_2\}$$

The above PDE (6E) now becomes

$$\begin{aligned} 2a_2v_1^4 + 8a_2v_1^3v_2 + 3a_2v_1^2v_2^2 - 4a_3v_1^4 - 8a_3v_1^3v_2 - 6a_3v_1^2v_2^2 - 6a_3v_1v_2^3 \\ - 3a_3v_2^4 - b_2v_1^4 + 6b_2v_1^3v_2 + 6b_2v_1^2v_2^2 - 2b_3v_1^4 - 8b_3v_1^3v_2 - 3b_3v_1^2v_2^2 \\ + 2a_1v_1^2v_2 - 2a_1v_1v_2^2 - 2a_1v_2^3 - 2b_1v_1^3 + 2b_1v_1^2v_2 + 2b_1v_1v_2^2 = 0 \end{aligned} \quad (7E)$$

Collecting the above on the terms v_i introduced, and these are

$$\{v_1, v_2\}$$

Equation (7E) now becomes

$$\begin{aligned} (2a_2 - 4a_3 - b_2 - 2b_3)v_1^4 + (8a_2 - 8a_3 + 6b_2 - 8b_3)v_1^3v_2 \\ - 2b_1v_1^3 + (3a_2 - 6a_3 + 6b_2 - 3b_3)v_1^2v_2^2 + (2a_1 + 2b_1)v_1^2v_2 \\ - 6a_3v_1v_2^3 + (-2a_1 + 2b_1)v_1v_2^2 - 3a_3v_2^4 - 2a_1v_2^3 = 0 \end{aligned} \quad (8E)$$

Setting each coefficients in (8E) to zero gives the following equations to solve

$$\begin{aligned} -2a_1 &= 0 \\ -6a_3 &= 0 \\ -3a_3 &= 0 \\ -2b_1 &= 0 \\ -2a_1 + 2b_1 &= 0 \\ 2a_1 + 2b_1 &= 0 \\ 2a_2 - 4a_3 - b_2 - 2b_3 &= 0 \\ 3a_2 - 6a_3 + 6b_2 - 3b_3 &= 0 \\ 8a_2 - 8a_3 + 6b_2 - 8b_3 &= 0 \end{aligned}$$

Solving the above equations for the unknowns gives

$$\begin{aligned} a_1 &= 0 \\ a_2 &= b_3 \\ a_3 &= 0 \\ b_1 &= 0 \\ b_2 &= 0 \\ b_3 &= b_3 \end{aligned}$$

Substituting the above solution in the anstaz (1E,2E) (using 1 as arbitrary value for any unknown in the RHS) gives

$$\begin{aligned} \xi &= x \\ \eta &= y \end{aligned}$$

Shifting is now applied to make $\xi = 0$ in order to simplify the rest of the computation

$$\begin{aligned}\eta &= \eta - \omega(x, y) \xi \\ &= y - \left(-\frac{2x^2 + 2xy + y^2}{x(x + 2y)} \right) (x) \\ &= \frac{2x^2 + 3xy + 3y^2}{x + 2y} \\ \xi &= 0\end{aligned}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \quad (1)$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y} \right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned}S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{2x^2 + 3xy + 3y^2}{x + 2y}} dy\end{aligned}$$

Which results in

$$S = \frac{\ln(2x^2 + 3xy + 3y^2)}{3}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{2x^2 + 2xy + y^2}{x(x + 2y)}$$

Evaluating all the partial derivatives gives

$$\begin{aligned}R_x &= 1 \\R_y &= 0 \\S_x &= \frac{4x + 3y}{6x^2 + 9xy + 9y^2} \\S_y &= \frac{x + 2y}{2x^2 + 3xy + 3y^2}\end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = -\frac{1}{3R} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = -\frac{1}{3R}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = -\frac{\ln(R)}{3} + c_1 \quad (4)$$

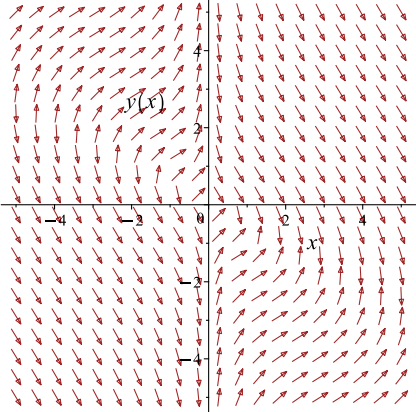
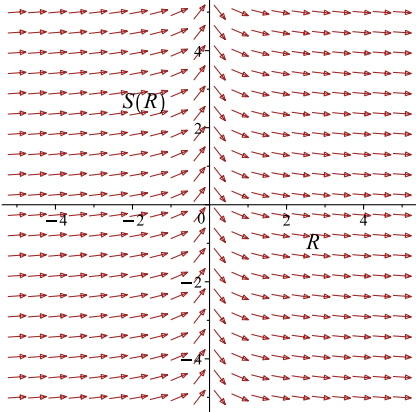
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$\frac{\ln(3y^2 + 3yx + 2x^2)}{3} = -\frac{\ln(x)}{3} + c_1$$

Which simplifies to

$$\frac{\ln(3y^2 + 3yx + 2x^2)}{3} = -\frac{\ln(x)}{3} + c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{2x^2+2xy+y^2}{x(x+2y)}$ 	$R = x$ $S = \frac{\ln(2x^2 + 3xy + 3y^2)}{3}$	$\frac{dS}{dR} = -\frac{1}{3R}$ 

Summary

The solution(s) found are the following

$$\frac{\ln(3y^2 + 3yx + 2x^2)}{3} = -\frac{\ln(x)}{3} + c_1 \tag{1}$$

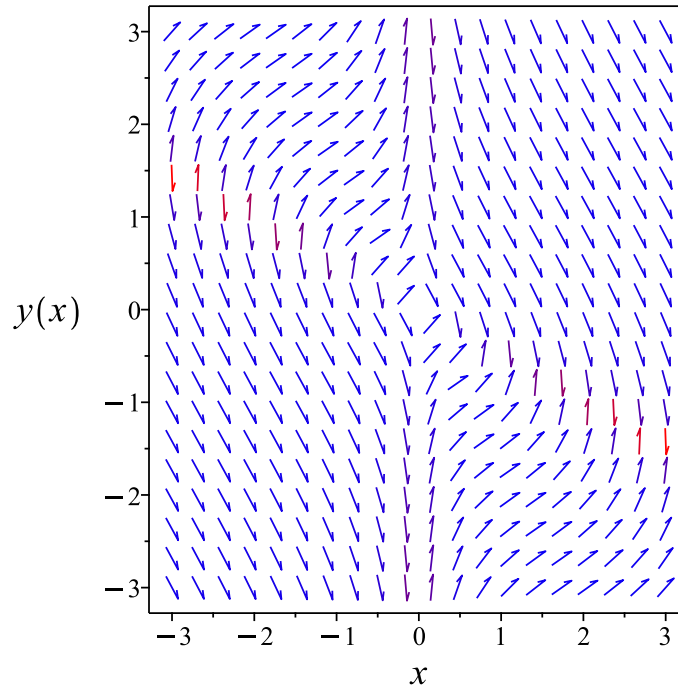


Figure 142: Slope field plot

Verification of solutions

$$\frac{\ln(3y^2 + 3yx + 2x^2)}{3} = -\frac{\ln(x)}{3} + c_1$$

Verified OK.

4.24.3 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx}\phi(x, y) = 0$$

Hence

$$\frac{\partial\phi}{\partial x} + \frac{\partial\phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial\phi}{\partial x} &= M \\ \frac{\partial\phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \tag{1A}$$

Therefore

$$\begin{aligned}(x^2 + 2xy) dy &= (-2x^2 - 2xy - y^2) dx \\ (2x^2 + 2xy + y^2) dx + (x^2 + 2xy) dy &= 0\end{aligned} \tag{2A}$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= 2x^2 + 2xy + y^2 \\ N(x, y) &= x^2 + 2xy\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(2x^2 + 2xy + y^2) \\ &= 2y + 2x\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(x^2 + 2xy) \\ &= 2y + 2x\end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \quad (1)$$

$$\frac{\partial \phi}{\partial y} = N \quad (2)$$

Integrating (1) w.r.t. x gives

$$\begin{aligned} \int \frac{\partial \phi}{\partial x} dx &= \int M dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int 2x^2 + 2xy + y^2 dx \\ \phi &= \frac{2}{3}x^3 + x^2y + xy^2 + f(y) \end{aligned} \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\begin{aligned} \frac{\partial \phi}{\partial y} &= x^2 + 2xy + f'(y) \\ &= x(x + 2y) + f'(y) \end{aligned} \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = x^2 + 2xy$. Therefore equation (4) becomes

$$x^2 + 2xy = x(x + 2y) + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 0$$

Therefore

$$f(y) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(y)$ into equation (3) gives ϕ

$$\phi = \frac{2}{3}x^3 + x^2y + xy^2 + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = \frac{2}{3}x^3 + x^2y + xy^2$$

Summary

The solution(s) found are the following

$$\frac{2x^3}{3} + x^2y + y^2x = c_1 \quad (1)$$

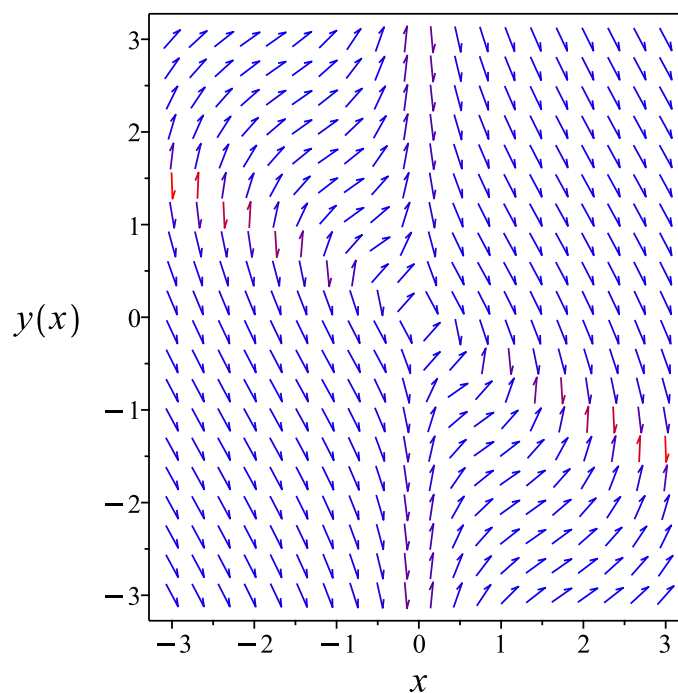


Figure 143: Slope field plot

Verification of solutions

$$\frac{2x^3}{3} + x^2y + y^2x = c_1$$

Verified OK.

4.24.4 Maple step by step solution

Let's solve

$$2yx + y^2 + (2yx + x^2) y' = -2x^2$$

- Highest derivative means the order of the ODE is 1

y'

- Check if ODE is exact

- ODE is exact if the lhs is the total derivative of a C^2 function

$$F'(x, y) = 0$$

- Compute derivative of lhs

$$F'(x, y) + \left(\frac{\partial}{\partial y} F(x, y) \right) y' = 0$$

- Evaluate derivatives

$$2y + 2x = 2y + 2x$$

- Condition met, ODE is exact

- Exact ODE implies solution will be of this form

$$\left[F(x, y) = c_1, M(x, y) = F'(x, y), N(x, y) = \frac{\partial}{\partial y} F(x, y) \right]$$

- Solve for $F(x, y)$ by integrating $M(x, y)$ with respect to x

$$F(x, y) = \int (2x^2 + 2xy + y^2) dx + f_1(y)$$

- Evaluate integral

$$F(x, y) = \frac{2x^3}{3} + x^2y + xy^2 + f_1(y)$$

- Take derivative of $F(x, y)$ with respect to y

$$N(x, y) = \frac{\partial}{\partial y} F(x, y)$$

- Compute derivative

$$x^2 + 2xy = x^2 + 2xy + \frac{d}{dy} f_1(y)$$

- Isolate for $\frac{d}{dy} f_1(y)$

$$\frac{d}{dy} f_1(y) = 0$$

- Solve for $f_1(y)$

$$f_1(y) = 0$$

- Substitute $f_1(y)$ into equation for $F(x, y)$

$$F(x, y) = \frac{2}{3}x^3 + x^2y + xy^2$$

- Substitute $F(x, y)$ into the solution of the ODE

$$\frac{2}{3}x^3 + x^2y + xy^2 = c_1$$

- Solve for y

$$\left\{ y = \frac{-3x^2 + \sqrt{-15x^4 + 36c_1x}}{6x}, y = -\frac{3x^2 + \sqrt{-15x^4 + 36c_1x}}{6x} \right\}$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
trying separable
trying inverse linear
trying homogeneous types:
trying homogeneous D
<- homogeneous successful`

```

✓ Solution by Maple

Time used: 0.047 (sec). Leaf size: 80

```
dsolve((2*x^2+2*x*y(x)+y(x)^2)+(x^2+2*x*y(x))*diff(y(x),x)=0,y(x), singsol=all)
```

$$y(x) = \frac{-3c_1^2x^2 + \sqrt{3} \sqrt{-5 \left(c_1^3x^3 - \frac{4}{5}\right) c_1x}}{6c_1^2x}$$

$$y(x) = \frac{-3c_1^2x^2 - \sqrt{3} \sqrt{-5 \left(c_1^3x^3 - \frac{4}{5}\right) c_1x}}{6c_1^2x}$$

✓ Solution by Mathematica

Time used: 1.277 (sec). Leaf size: 150

```
DSolve[(2*x^2+2*x*y[x]+y[x]^2)+(x^2+2*x*y[x])*y'[x]==0,y[x],x,IncludeSingularSolutions -> Tr
```

$$y(x) \rightarrow \frac{1}{6} \left(-3x - \frac{\sqrt{3}\sqrt{-5x^3 + 4e^{3c_1}}}{\sqrt{x}} \right)$$

$$y(x) \rightarrow \frac{1}{6} \left(-3x + \frac{\sqrt{3}\sqrt{-5x^3 + 4e^{3c_1}}}{\sqrt{x}} \right)$$

$$y(x) \rightarrow \frac{1}{6} x \left(\frac{\sqrt{15}x^{3/2}}{\sqrt{-x^3}} - 3 \right)$$

$$y(x) \rightarrow \frac{\sqrt{\frac{5}{3}}\sqrt{-x^3}}{2\sqrt{x}} - \frac{x}{2}$$

5 Chapter 2, section 2.3 (Linear equations).

Exercises page 56

5.1	problem 1	780
5.2	problem 2	793
5.3	problem 3	806
5.4	problem 4	819
5.5	problem 5	832
5.6	problem 6	846
5.7	problem 7	860
5.8	problem 8	874
5.9	problem 9	887
5.10	problem 10	900
5.11	problem 11	906
5.12	problem 12	919
5.13	problem 13	932
5.14	problem 14	945
5.15	problem 15	957
5.16	problem 16	975
5.17	problem 17	990
5.18	problem 18	1006
5.19	problem 19	1021
5.20	problem 20	1035
5.21	problem 21	1050
5.22	problem 22	1063
5.23	problem 23	1077
5.24	problem 24	1092
5.25	problem 25	1106
5.26	problem 26	1119
5.27	problem 27	1133
5.28	problem 28	1145
5.29	problem 29	1157
5.30	problem 30	1169
5.31	problem 31	1182
5.32	problem 35 (b)	1193
5.33	problem 37 (a)	1206
5.34	problem 37 (b)	1211
5.35	problem 39	1223
5.36	problem 40	1234

5.37 problem 41 1238

5.1 problem 1

5.1.1	Solving as linear ode	780
5.1.2	Solving as first order ode lie symmetry lookup ode	782
5.1.3	Solving as exact ode	786
5.1.4	Maple step by step solution	791

Internal problem ID [11638]

Internal file name [OUTPUT/11647_Tuesday_April_09_2024_02_04_51_AM_19754612/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.3 (Linear equations). Exercises page 56

Problem number: 1.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"linear"**, **"exactWithIntegrationFactor"**, **"first_order_ode_lie_symmetry_lookup"**

Maple gives the following as the ode type

`[_linear]`

$$y' + \frac{3y}{x} = 6x^2$$

5.1.1 Solving as linear ode

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = \frac{3}{x}$$
$$q(x) = 6x^2$$

Hence the ode is

$$y' + \frac{3y}{x} = 6x^2$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int \frac{3}{x} dx} \\ &= x^3\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu y) &= (\mu) (6x^2) \\ \frac{d}{dx}(y x^3) &= (x^3) (6x^2) \\ d(y x^3) &= (6x^5) dx\end{aligned}$$

Integrating gives

$$\begin{aligned}y x^3 &= \int 6x^5 dx \\ y x^3 &= x^6 + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = x^3$ results in

$$y = x^3 + \frac{c_1}{x^3}$$

Summary

The solution(s) found are the following

$$y = x^3 + \frac{c_1}{x^3} \tag{1}$$

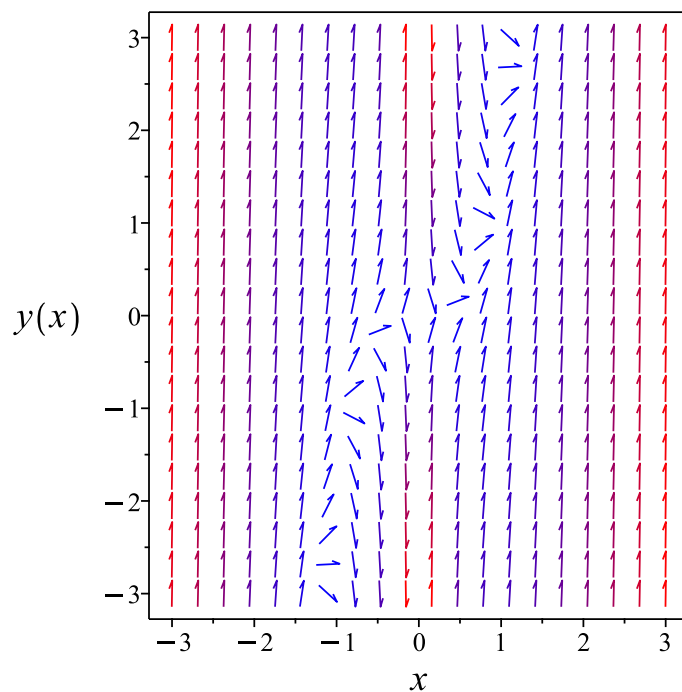


Figure 144: Slope field plot

Verification of solutions

$$y = x^3 + \frac{c_1}{x^3}$$

Verified OK.

5.1.2 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = -\frac{3(-2x^3 + y)}{x}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 112: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= \frac{1}{x^3}\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{1}{x^3}} dy \end{aligned}$$

Which results in

$$S = y x^3$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{3(-2x^3 + y)}{x}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= 3x^2y \\ S_y &= x^3 \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 6x^5 \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 6R^5$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by

integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = R^6 + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$yx^3 = x^6 + c_1$$

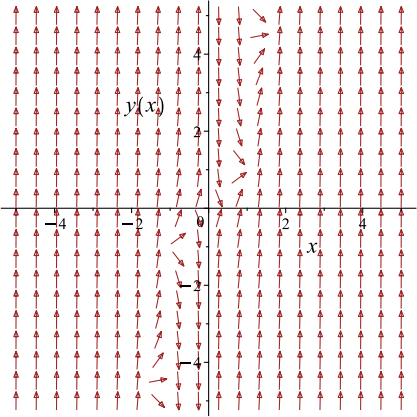
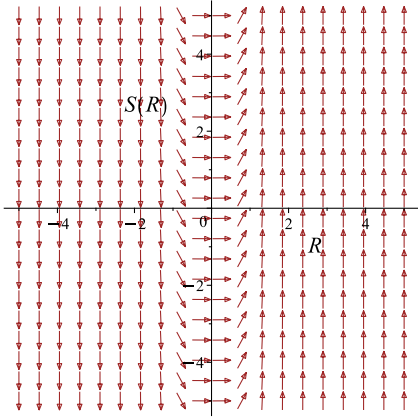
Which simplifies to

$$yx^3 = x^6 + c_1$$

Which gives

$$y = \frac{x^6 + c_1}{x^3}$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{3(-2x^3+y)}{x}$ 	$R = x$ $S = yx^3$	$\frac{dS}{dR} = 6R^5$ 

Summary

The solution(s) found are the following

$$y = \frac{x^6 + c_1}{x^3} \quad (1)$$

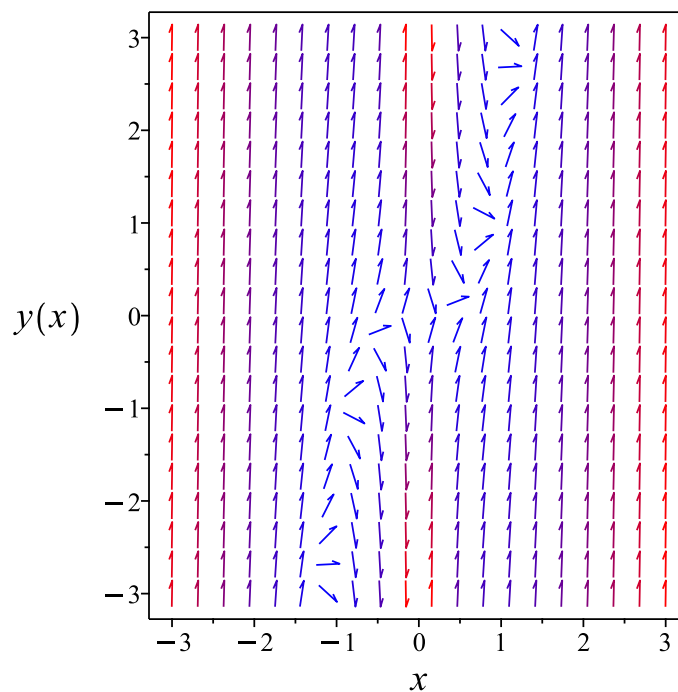


Figure 145: Slope field plot

Verification of solutions

$$y = \frac{x^6 + c_1}{x^3}$$

Verified OK.

5.1.3 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \tag{1A}$$

Therefore

$$\begin{aligned}dy &= \left(-\frac{3y}{x} + 6x^2 \right) dx \\ \left(\frac{3y}{x} - 6x^2 \right) dx + dy &= 0\end{aligned} \tag{2A}$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= \frac{3y}{x} - 6x^2 \\ N(x, y) &= 1\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y} \left(\frac{3y}{x} - 6x^2 \right) \\ &= \frac{3}{x}\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(1) \\ &= 0\end{aligned}$$

Since $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$\begin{aligned}A &= \frac{1}{N} \left(\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} \right) \\ &= 1 \left(\left(\frac{3}{x} \right) - (0) \right) \\ &= \frac{3}{x}\end{aligned}$$

Since A does not depend on y , then it can be used to find an integrating factor. The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int A dx} \\ &= e^{\int \frac{3}{x} dx}\end{aligned}$$

The result of integrating gives

$$\begin{aligned}\mu &= e^{3 \ln(x)} \\ &= x^3\end{aligned}$$

M and N are multiplied by this integrating factor, giving new M and new N which are called \bar{M} and \bar{N} for now so not to confuse them with the original M and N .

$$\begin{aligned}\bar{M} &= \mu M \\ &= x^3 \left(\frac{3y}{x} - 6x^2 \right) \\ &= -6x^5 + 3x^2y\end{aligned}$$

And

$$\begin{aligned}\bar{N} &= \mu N \\ &= x^3(1) \\ &= x^3\end{aligned}$$

Now a modified ODE is obtained from the original ODE, which is exact and can be solved. The modified ODE is

$$\begin{aligned}\bar{M} + \bar{N} \frac{dy}{dx} &= 0 \\ (-6x^5 + 3x^2y) + (x^3) \frac{dy}{dx} &= 0\end{aligned}$$

The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = \bar{M} \tag{1}$$

$$\frac{\partial \phi}{\partial y} = \bar{N} \tag{2}$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int \bar{M} dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int -6x^5 + 3x^2y dx \\ \phi &= -\frac{(2x^3 - y)^2}{4} + f(y)\end{aligned} \tag{3}$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = x^3 - \frac{y}{2} + f'(y) \tag{4}$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = x^3$. Therefore equation (4) becomes

$$x^3 = x^3 - \frac{y}{2} + f'(y) \tag{5}$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = \frac{y}{2}$$

Integrating the above w.r.t y gives

$$\begin{aligned}\int f'(y) dy &= \int \left(\frac{y}{2}\right) dy \\ f(y) &= \frac{y^2}{4} + c_1\end{aligned}$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = -\frac{(2x^3 - y)^2}{4} + \frac{y^2}{4} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -\frac{(2x^3 - y)^2}{4} + \frac{y^2}{4}$$

The solution becomes

$$y = \frac{x^6 + c_1}{x^3}$$

Summary

The solution(s) found are the following

$$y = \frac{x^6 + c_1}{x^3} \tag{1}$$

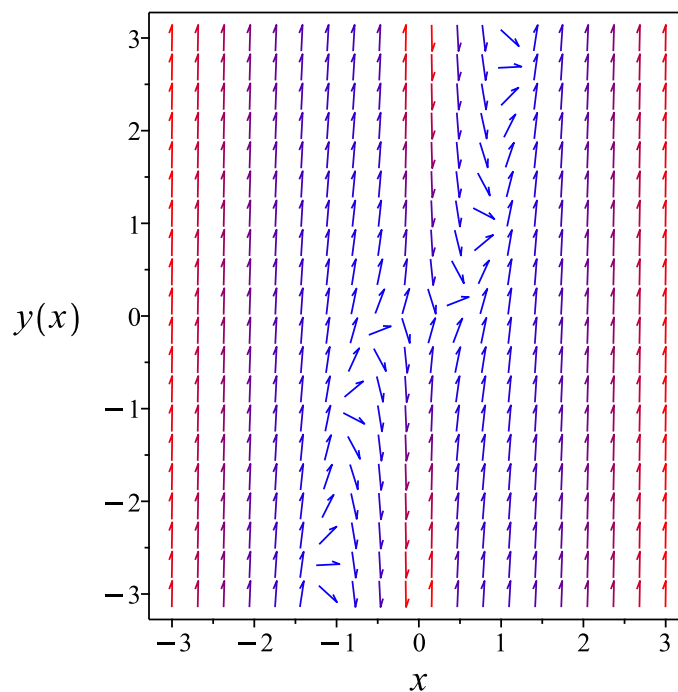


Figure 146: Slope field plot

Verification of solutions

$$y = \frac{x^6 + c_1}{x^3}$$

Verified OK.

5.1.4 Maple step by step solution

Let's solve

$$y' + \frac{3y}{x} = 6x^2$$

- Highest derivative means the order of the ODE is 1

$$y'$$

- Isolate the derivative

$$y' = -\frac{3y}{x} + 6x^2$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE

$$y' + \frac{3y}{x} = 6x^2$$

- The ODE is linear; multiply by an integrating factor $\mu(x)$

$$\mu(x) \left(y' + \frac{3y}{x} \right) = 6\mu(x) x^2$$

- Assume the lhs of the ODE is the total derivative $\frac{d}{dx}(\mu(x) y)$

$$\mu(x) \left(y' + \frac{3y}{x} \right) = \mu'(x) y + \mu(x) y'$$

- Isolate $\mu'(x)$

$$\mu'(x) = \frac{3\mu(x)}{x}$$

- Solve to find the integrating factor

$$\mu(x) = x^3$$

- Integrate both sides with respect to x

$$\int \left(\frac{d}{dx}(\mu(x) y) \right) dx = \int 6\mu(x) x^2 dx + c_1$$

- Evaluate the integral on the lhs

$$\mu(x) y = \int 6\mu(x) x^2 dx + c_1$$

- Solve for y

$$y = \frac{\int 6\mu(x)x^2 dx + c_1}{\mu(x)}$$

- Substitute $\mu(x) = x^3$

$$y = \frac{\int 6x^5 dx + c_1}{x^3}$$

- Evaluate the integrals on the rhs

$$y = \frac{x^6 + c_1}{x^3}$$

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
<- 1st order linear successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 13

```
dsolve(diff(y(x),x)+3*y(x)/x=6*x^2,y(x), singsol=all)
```

$$y(x) = \frac{x^6 + c_1}{x^3}$$

✓ Solution by Mathematica

Time used: 0.071 (sec). Leaf size: 15

```
DSolve[y'[x]+3*y[x]/x==6*x^2,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{x^6 + c_1}{x^3}$$

5.2 problem 2

5.2.1	Solving as linear ode	793
5.2.2	Solving as first order ode lie symmetry lookup ode	795
5.2.3	Solving as exact ode	799
5.2.4	Maple step by step solution	804

Internal problem ID [11639]

Internal file name [OUTPUT/11648_Tuesday_April_09_2024_02_04_53_AM_58150107/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.3 (Linear equations). Exercises page 56

Problem number: 2.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"linear"**, **"exactWithIntegrationFactor"**, **"first_order_ode_lie_symmetry_lookup"**

Maple gives the following as the ode type

`[_linear]`

$$x^4y' + 2yx^3 = 1$$

5.2.1 Solving as linear ode

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = \frac{2}{x}$$
$$q(x) = \frac{1}{x^4}$$

Hence the ode is

$$y' + \frac{2y}{x} = \frac{1}{x^4}$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int \frac{2}{x} dx} \\ &= x^2\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu y) &= (\mu) \left(\frac{1}{x^4} \right) \\ \frac{d}{dx}(x^2 y) &= (x^2) \left(\frac{1}{x^4} \right) \\ d(x^2 y) &= \frac{1}{x^2} dx\end{aligned}$$

Integrating gives

$$\begin{aligned}x^2 y &= \int \frac{1}{x^2} dx \\ x^2 y &= -\frac{1}{x} + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = x^2$ results in

$$y = -\frac{1}{x^3} + \frac{c_1}{x^2}$$

which simplifies to

$$y = \frac{c_1 x - 1}{x^3}$$

Summary

The solution(s) found are the following

$$y = \frac{c_1 x - 1}{x^3} \tag{1}$$

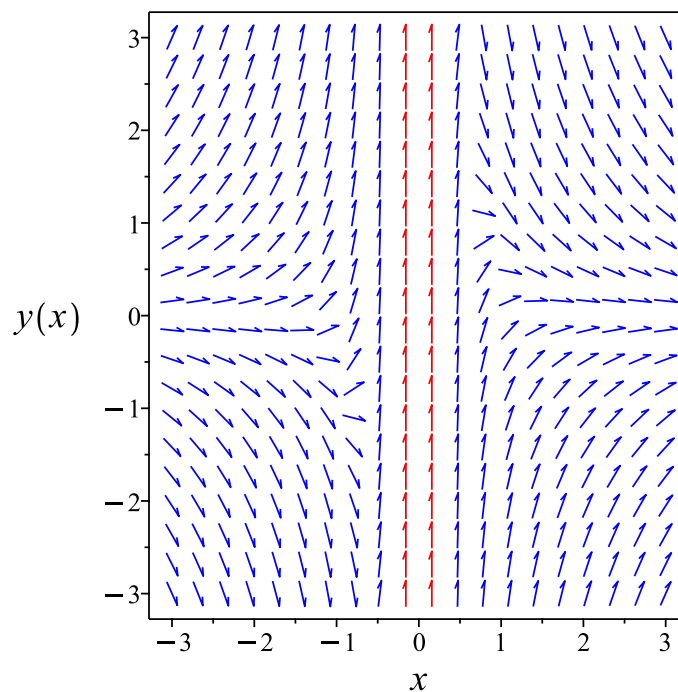


Figure 147: Slope field plot

Verification of solutions

$$y = \frac{c_1 x - 1}{x^3}$$

Verified OK.

5.2.2 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = -\frac{2yx^3 - 1}{x^4}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 115: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= \frac{1}{x^2}\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right)S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{1}{x^2}} dy \end{aligned}$$

Which results in

$$S = x^2 y$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{2y x^3 - 1}{x^4}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= 2xy \\ S_y &= x^2 \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = \frac{1}{x^2} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = \frac{1}{R^2}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by

integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = -\frac{1}{R} + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$x^2 y = -\frac{1}{x} + c_1$$

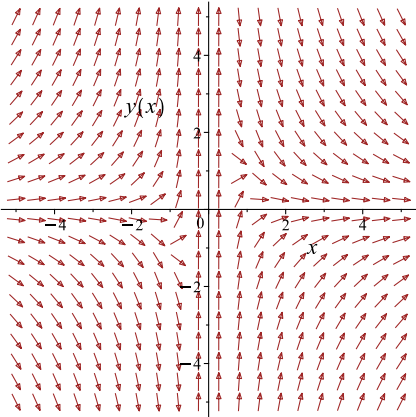
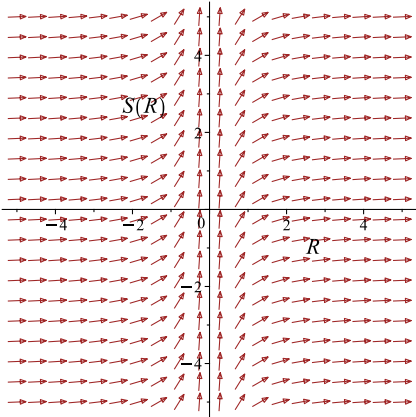
Which simplifies to

$$x^2 y = -\frac{1}{x} + c_1$$

Which gives

$$y = \frac{c_1 x - 1}{x^3}$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{2yx^3-1}{x^4}$ 	$R = x$ $S = x^2 y$	$\frac{dS}{dR} = \frac{1}{R^2}$ 

Summary

The solution(s) found are the following

$$y = \frac{c_1 x - 1}{x^3} \quad (1)$$

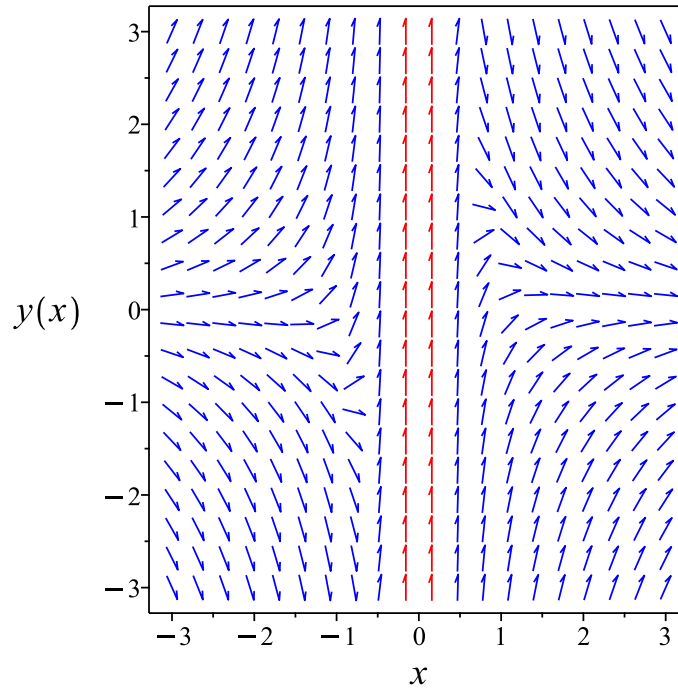


Figure 148: Slope field plot

Verification of solutions

$$y = \frac{c_1 x - 1}{x^3}$$

Verified OK.

5.2.3 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \tag{1A}$$

Therefore

$$\begin{aligned}(x^4) dy &= (-2y x^3 + 1) dx \\ (2y x^3 - 1) dx + (x^4) dy &= 0\end{aligned} \tag{2A}$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= 2y x^3 - 1 \\ N(x, y) &= x^4\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(2y x^3 - 1) \\ &= 2x^3\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(x^4) \\ &= 4x^3\end{aligned}$$

Since $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$\begin{aligned} A &= \frac{1}{N} \left(\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} \right) \\ &= \frac{1}{x^4} ((2x^3) - (4x^3)) \\ &= -\frac{2}{x} \end{aligned}$$

Since A does not depend on y , then it can be used to find an integrating factor. The integrating factor μ is

$$\begin{aligned} \mu &= e^{\int A \, dx} \\ &= e^{\int -\frac{2}{x} \, dx} \end{aligned}$$

The result of integrating gives

$$\begin{aligned} \mu &= e^{-2 \ln(x)} \\ &= \frac{1}{x^2} \end{aligned}$$

M and N are multiplied by this integrating factor, giving new M and new N which are called \bar{M} and \bar{N} for now so not to confuse them with the original M and N .

$$\begin{aligned} \bar{M} &= \mu M \\ &= \frac{1}{x^2} (2y x^3 - 1) \\ &= \frac{2y x^3 - 1}{x^2} \end{aligned}$$

And

$$\begin{aligned} \bar{N} &= \mu N \\ &= \frac{1}{x^2} (x^4) \\ &= x^2 \end{aligned}$$

Now a modified ODE is obtained from the original ODE, which is exact and can be solved. The modified ODE is

$$\begin{aligned} \bar{M} + \bar{N} \frac{dy}{dx} &= 0 \\ \left(\frac{2y x^3 - 1}{x^2} \right) + (x^2) \frac{dy}{dx} &= 0 \end{aligned}$$

The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = \bar{M} \quad (1)$$

$$\frac{\partial \phi}{\partial y} = \bar{N} \quad (2)$$

Integrating (1) w.r.t. x gives

$$\int \frac{\partial \phi}{\partial x} dx = \int \bar{M} dx$$
$$\int \frac{\partial \phi}{\partial x} dx = \int \frac{2yx^3 - 1}{x^2} dx$$
$$\phi = x^2y + \frac{1}{x} + f(y) \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = x^2 + f'(y) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = x^2$. Therefore equation (4) becomes

$$x^2 = x^2 + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 0$$

Therefore

$$f(y) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(y)$ into equation (3) gives ϕ

$$\phi = x^2y + \frac{1}{x} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = x^2y + \frac{1}{x}$$

The solution becomes

$$y = \frac{c_1 x - 1}{x^3}$$

Summary

The solution(s) found are the following

$$y = \frac{c_1 x - 1}{x^3} \tag{1}$$

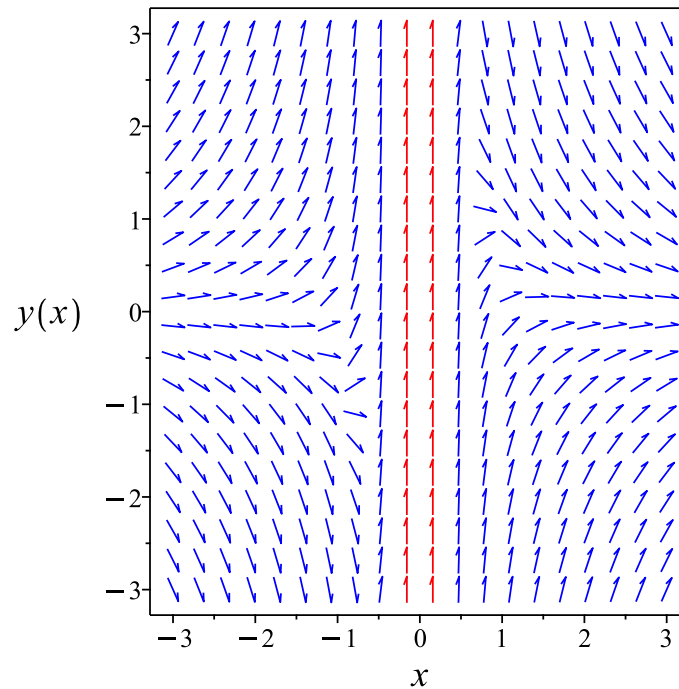


Figure 149: Slope field plot

Verification of solutions

$$y = \frac{c_1 x - 1}{x^3}$$

Verified OK.

5.2.4 Maple step by step solution

Let's solve

$$x^4 y' + 2yx^3 = 1$$

- Highest derivative means the order of the ODE is 1

$$y'$$

- Isolate the derivative

$$y' = -\frac{2y}{x} + \frac{1}{x^4}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE

$$y' + \frac{2y}{x} = \frac{1}{x^4}$$

- The ODE is linear; multiply by an integrating factor $\mu(x)$

$$\mu(x) \left(y' + \frac{2y}{x} \right) = \frac{\mu(x)}{x^4}$$

- Assume the lhs of the ODE is the total derivative $\frac{d}{dx}(\mu(x)y)$

$$\mu(x) \left(y' + \frac{2y}{x} \right) = \mu'(x)y + \mu(x)y'$$

- Isolate $\mu'(x)$

$$\mu'(x) = \frac{2\mu(x)}{x}$$

- Solve to find the integrating factor

$$\mu(x) = x^2$$

- Integrate both sides with respect to x

$$\int \left(\frac{d}{dx}(\mu(x)y) \right) dx = \int \frac{\mu(x)}{x^4} dx + c_1$$

- Evaluate the integral on the lhs

$$\mu(x)y = \int \frac{\mu(x)}{x^4} dx + c_1$$

- Solve for y

$$y = \frac{\int \frac{\mu(x)}{x^4} dx + c_1}{\mu(x)}$$

- Substitute $\mu(x) = x^2$

$$y = \frac{\int \frac{1}{x^2} dx + c_1}{x^2}$$

- Evaluate the integrals on the rhs

$$y = \frac{-\frac{1}{x} + c_1}{x^2}$$

- Simplify

$$y = \frac{c_1 x - 1}{x^3}$$

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
<- 1st order linear successful`
```

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 13

```
dsolve(x^4*diff(y(x),x)+2*x^3*y(x)=1,y(x), singsol=all)
```

$$y(x) = \frac{c_1 x - 1}{x^3}$$

✓ Solution by Mathematica

Time used: 0.027 (sec). Leaf size: 15

```
DSolve[x^4*y'[x]+2*x^3*y[x]==1,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{-1 + c_1 x}{x^3}$$

5.3 problem 3

5.3.1	Solving as linear ode	806
5.3.2	Solving as first order ode lie symmetry lookup ode	808
5.3.3	Solving as exact ode	812
5.3.4	Maple step by step solution	816

Internal problem ID [11640]

Internal file name [OUTPUT/11649_Tuesday_April_09_2024_02_04_54_AM_84307621/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.3 (Linear equations). Exercises page 56

Problem number: 3.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "linear", "exactWithIntegrationFactor", "first_order_ode_lie_symmetry_lookup"

Maple gives the following as the ode type

```
[[_linear, `class A`]]
```

$$y' + 3y = 3x^2e^{-3x}$$

5.3.1 Solving as linear ode

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = 3$$
$$q(x) = 3x^2e^{-3x}$$

Hence the ode is

$$y' + 3y = 3x^2e^{-3x}$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int 3dx} \\ &= e^{3x}\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu y) &= (\mu) (3x^2 e^{-3x}) \\ \frac{d}{dx}(e^{3x}y) &= (e^{3x}) (3x^2 e^{-3x}) \\ d(e^{3x}y) &= (3x^2) dx\end{aligned}$$

Integrating gives

$$\begin{aligned}e^{3x}y &= \int 3x^2 dx \\ e^{3x}y &= x^3 + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = e^{3x}$ results in

$$y = e^{-3x}x^3 + c_1e^{-3x}$$

which simplifies to

$$y = e^{-3x}(x^3 + c_1)$$

Summary

The solution(s) found are the following

$$y = e^{-3x}(x^3 + c_1) \tag{1}$$

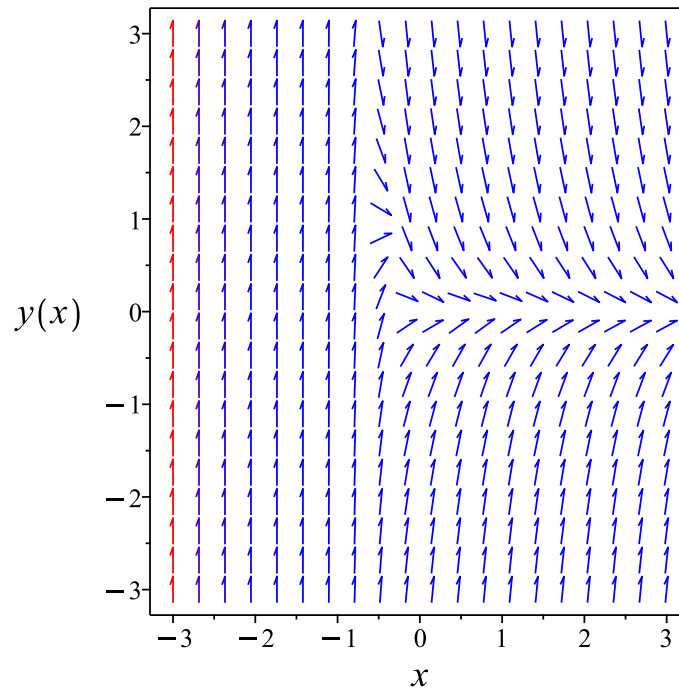


Figure 150: Slope field plot

Verification of solutions

$$y = e^{-3x}(x^3 + c_1)$$

Verified OK.

5.3.2 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = -3y + 3x^2e^{-3x}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2\xi_y - \omega_x\xi - \omega_y\eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 118: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= e^{-3x}\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{e^{-3x}} dy \end{aligned}$$

Which results in

$$S = e^{3x}y$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -3y + 3x^2e^{-3x}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= 3e^{3x}y \\ S_y &= e^{3x} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 3x^2 \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 3R^2$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by

integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = R^3 + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$e^{3x}y = x^3 + c_1$$

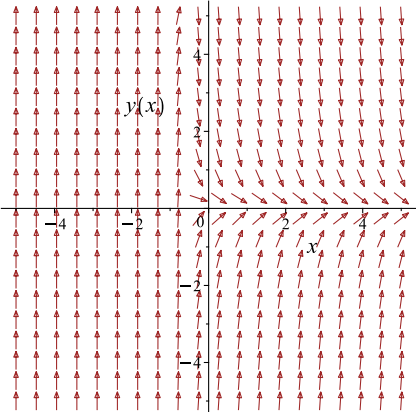
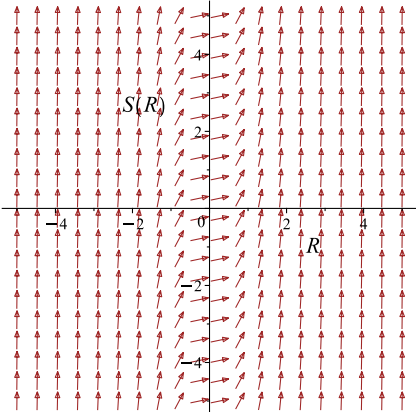
Which simplifies to

$$e^{3x}y = x^3 + c_1$$

Which gives

$$y = e^{-3x}(x^3 + c_1)$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -3y + 3x^2e^{-3x}$ 	$R = x$ $S = e^{3x}y$	$\frac{dS}{dR} = 3R^2$ 

Summary

The solution(s) found are the following

$$y = e^{-3x}(x^3 + c_1) \quad (1)$$

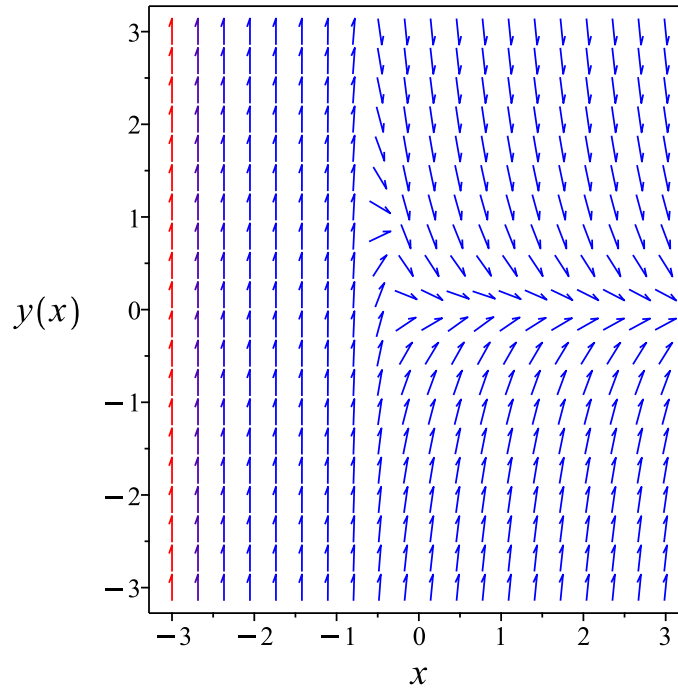


Figure 151: Slope field plot

Verification of solutions

$$y = e^{-3x}(x^3 + c_1)$$

Verified OK.

5.3.3 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx}\phi(x, y) = 0$$

Hence

$$\frac{\partial\phi}{\partial x} + \frac{\partial\phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial\phi}{\partial x} &= M \\ \frac{\partial\phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \tag{1A}$$

Therefore

$$\begin{aligned}dy &= (-3y + 3x^2e^{-3x}) dx \\ (3y - 3x^2e^{-3x}) dx + dy &= 0\end{aligned} \tag{2A}$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= 3y - 3x^2e^{-3x} \\ N(x, y) &= 1\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(3y - 3x^2e^{-3x}) \\ &= 3\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(1) \\ &= 0\end{aligned}$$

Since $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$\begin{aligned} A &= \frac{1}{N} \left(\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} \right) \\ &= 1((3) - (0)) \\ &= 3 \end{aligned}$$

Since A does not depend on y , then it can be used to find an integrating factor. The integrating factor μ is

$$\begin{aligned} \mu &= e^{\int A dx} \\ &= e^{\int 3 dx} \end{aligned}$$

The result of integrating gives

$$\begin{aligned} \mu &= e^{3x} \\ &= e^{3x} \end{aligned}$$

M and N are multiplied by this integrating factor, giving new M and new N which are called \bar{M} and \bar{N} for now so not to confuse them with the original M and N .

$$\begin{aligned} \bar{M} &= \mu M \\ &= e^{3x}(3y - 3x^2 e^{-3x}) \\ &= 3e^{3x}y - 3x^2 \end{aligned}$$

And

$$\begin{aligned} \bar{N} &= \mu N \\ &= e^{3x}(1) \\ &= e^{3x} \end{aligned}$$

Now a modified ODE is obtained from the original ODE, which is exact and can be solved. The modified ODE is

$$\begin{aligned} \bar{M} + \bar{N} \frac{dy}{dx} &= 0 \\ (3e^{3x}y - 3x^2) + (e^{3x}) \frac{dy}{dx} &= 0 \end{aligned}$$

The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = \bar{M} \tag{1}$$

$$\frac{\partial \phi}{\partial y} = \bar{N} \tag{2}$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int \overline{M} dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int 3e^{3x}y - 3x^2 dx \\ \phi &= e^{3x}y - x^3 + f(y)\end{aligned}\quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = e^{3x} + f'(y)\quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = e^{3x}$. Therefore equation (4) becomes

$$e^{3x} = e^{3x} + f'(y)\quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 0$$

Therefore

$$f(y) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(y)$ into equation (3) gives ϕ

$$\phi = e^{3x}y - x^3 + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = e^{3x}y - x^3$$

The solution becomes

$$y = e^{-3x}(x^3 + c_1)$$

Summary

The solution(s) found are the following

$$y = e^{-3x}(x^3 + c_1)\quad (1)$$

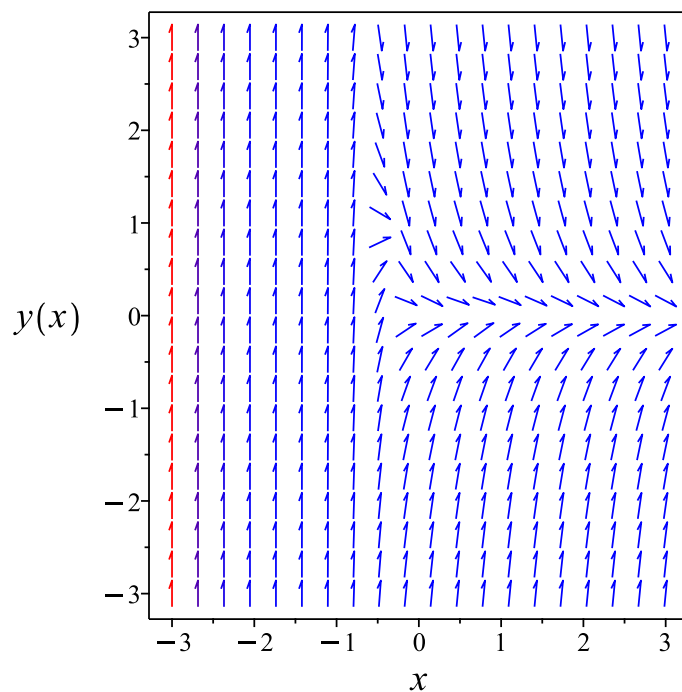


Figure 152: Slope field plot

Verification of solutions

$$y = e^{-3x}(x^3 + c_1)$$

Verified OK.

5.3.4 Maple step by step solution

Let's solve

$$y' + 3y = 3x^2e^{-3x}$$

- Highest derivative means the order of the ODE is 1

$$y'$$

- Isolate the derivative

$$y' = -3y + 3x^2e^{-3x}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE

$$y' + 3y = 3x^2e^{-3x}$$

- The ODE is linear; multiply by an integrating factor $\mu(x)$

$$\mu(x)(y' + 3y) = 3\mu(x)x^2e^{-3x}$$

- Assume the lhs of the ODE is the total derivative $\frac{d}{dx}(\mu(x)y)$

$$\mu(x)(y' + 3y) = \mu'(x)y + \mu(x)y'$$
- Isolate $\mu'(x)$

$$\mu'(x) = 3\mu(x)$$
- Solve to find the integrating factor

$$\mu(x) = e^{3x}$$
- Integrate both sides with respect to x

$$\int \left(\frac{d}{dx}(\mu(x)y)\right) dx = \int 3\mu(x)x^2e^{-3x} dx + c_1$$
- Evaluate the integral on the lhs

$$\mu(x)y = \int 3\mu(x)x^2e^{-3x} dx + c_1$$
- Solve for y

$$y = \frac{\int 3\mu(x)x^2e^{-3x} dx + c_1}{\mu(x)}$$
- Substitute $\mu(x) = e^{3x}$

$$y = \frac{\int 3x^2e^{-3x}e^{3x} dx + c_1}{e^{3x}}$$
- Evaluate the integrals on the rhs

$$y = \frac{x^3 + c_1}{e^{3x}}$$
- Simplify

$$y = e^{-3x}(x^3 + c_1)$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
<- 1st order linear successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 14

```
dsolve(diff(y(x),x)+3*y(x)=3*x^2*exp(-3*x),y(x), singsol=all)
```

$$y(x) = (x^3 + c_1) e^{-3x}$$

✓ Solution by Mathematica

Time used: 0.057 (sec). Leaf size: 17

```
DSolve[y'[x]+3*y[x]==3*x^2*Exp[-3*x],y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^{-3x} (x^3 + c_1)$$

5.4 problem 4

5.4.1	Solving as separable ode	819
5.4.2	Solving as linear ode	821
5.4.3	Solving as first order ode lie symmetry lookup ode	822
5.4.4	Solving as exact ode	826
5.4.5	Maple step by step solution	830

Internal problem ID [11641]

Internal file name [OUTPUT/11650_Tuesday_April_09_2024_02_04_54_AM_54658325/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.3 (Linear equations). Exercises page 56

Problem number: 4.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact", "linear", "separable", "first_order_ode_lie_symmetry_lookup"

Maple gives the following as the ode type

[_separable]

$$y' + 4yx = 8x$$

5.4.1 Solving as separable ode

In canonical form the ODE is

$$\begin{aligned}y' &= F(x, y) \\ &= f(x)g(y) \\ &= x(-4y + 8)\end{aligned}$$

Where $f(x) = x$ and $g(y) = -4y + 8$. Integrating both sides gives

$$\begin{aligned}\frac{1}{-4y + 8} dy &= x dx \\ \int \frac{1}{-4y + 8} dy &= \int x dx\end{aligned}$$

$$-\frac{\ln(y-2)}{4} = \frac{x^2}{2} + c_1$$

Raising both side to exponential gives

$$\frac{1}{(y-2)^{\frac{1}{4}}} = e^{\frac{x^2}{2} + c_1}$$

Which simplifies to

$$\frac{1}{(y-2)^{\frac{1}{4}}} = c_2 e^{\frac{x^2}{2}}$$

Summary

The solution(s) found are the following

$$y = \frac{\left(2c_2^4 e^{2x^2+4c_1} + 1\right) e^{-2x^2-4c_1}}{c_2^4} \quad (1)$$

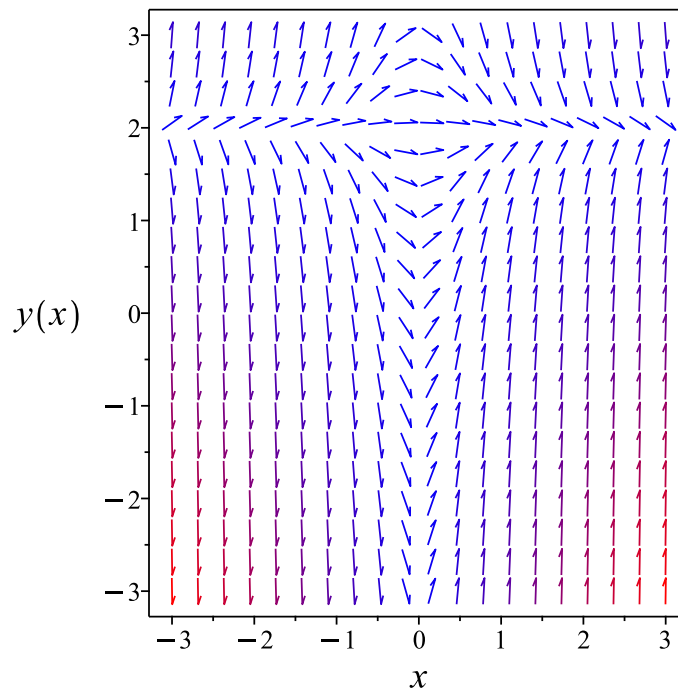


Figure 153: Slope field plot

Verification of solutions

$$y = \frac{\left(2c_2^4 e^{2x^2+4c_1} + 1\right) e^{-2x^2-4c_1}}{c_2^4}$$

Verified OK.

5.4.2 Solving as linear ode

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = 4x$$

$$q(x) = 8x$$

Hence the ode is

$$y' + 4yx = 8x$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int 4x dx} \\ &= e^{2x^2}\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu y) &= (\mu)(8x) \\ \frac{d}{dx}(e^{2x^2}y) &= (e^{2x^2})(8x) \\ d(e^{2x^2}y) &= (8xe^{2x^2}) dx\end{aligned}$$

Integrating gives

$$\begin{aligned}e^{2x^2}y &= \int 8xe^{2x^2} dx \\ e^{2x^2}y &= 2e^{2x^2} + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = e^{2x^2}$ results in

$$y = 2e^{-2x^2}e^{2x^2} + c_1e^{-2x^2}$$

which simplifies to

$$y = 2 + c_1e^{-2x^2}$$

Summary

The solution(s) found are the following

$$y = 2 + c_1e^{-2x^2} \tag{1}$$

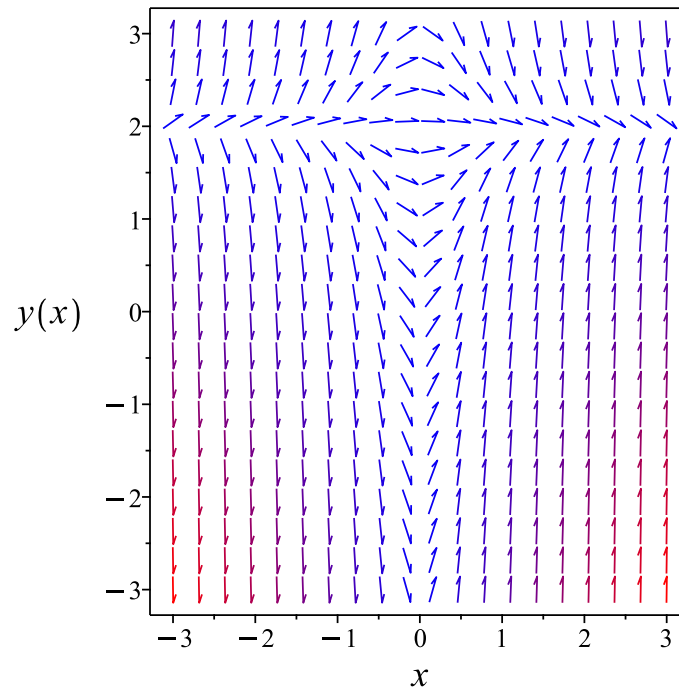


Figure 154: Slope field plot

Verification of solutions

$$y = 2 + c_1 e^{-2x^2}$$

Verified OK.

5.4.3 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = -4xy + 8x$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \tag{A}$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 121: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= e^{-2x^2}\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right)S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{e^{-2x^2}} dy \end{aligned}$$

Which results in

$$S = e^{2x^2} y$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -4xy + 8x$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= 4x e^{2x^2} y \\ S_y &= e^{2x^2} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 8x e^{2x^2} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 8R e^{2R^2}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by

integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = 2 e^{2R^2} + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$e^{2x^2} y = 2 e^{2x^2} + c_1$$

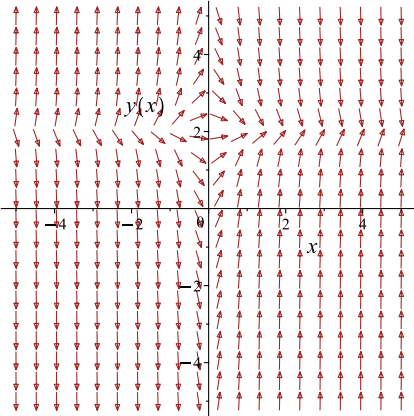
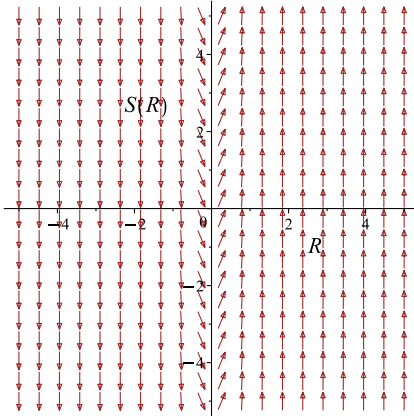
Which simplifies to

$$(y - 2) e^{2x^2} - c_1 = 0$$

Which gives

$$y = \left(2 e^{2x^2} + c_1 \right) e^{-2x^2}$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -4xy + 8x$ 	$R = x$ $S = e^{2x^2} y$	$\frac{dS}{dR} = 8R e^{2R^2}$ 

Summary

The solution(s) found are the following

$$y = \left(2 e^{2x^2} + c_1 \right) e^{-2x^2} \quad (1)$$

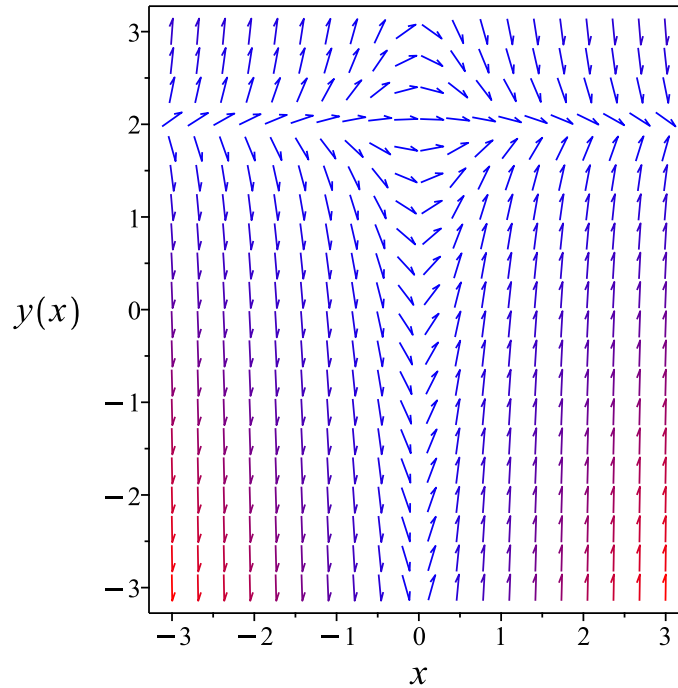


Figure 155: Slope field plot

Verification of solutions

$$y = \left(2 e^{2x^2} + c_1\right) e^{-2x^2}$$

Verified OK.

5.4.4 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \quad (\text{A})$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \quad (\text{B})$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial\phi}{\partial x} &= M \\ \frac{\partial\phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \tag{1A}$$

Therefore

$$\begin{aligned}\left(\frac{1}{-4y+8}\right) dy &= (x) dx \\ (-x) dx + \left(\frac{1}{-4y+8}\right) dy &= 0\end{aligned} \tag{2A}$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= -x \\ N(x, y) &= \frac{1}{-4y+8}\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(-x) \\ &= 0\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x} \left(\frac{1}{-4y+8} \right) \\ &= 0\end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \tag{1}$$

$$\frac{\partial \phi}{\partial y} = N \tag{2}$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int M dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int -x dx \\ \phi &= -\frac{x^2}{2} + f(y)\end{aligned} \tag{3}$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = 0 + f'(y) \tag{4}$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = \frac{1}{-4y+8}$. Therefore equation (4) becomes

$$\frac{1}{-4y+8} = 0 + f'(y) \tag{5}$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = -\frac{1}{4(y-2)}$$

Integrating the above w.r.t y gives

$$\int f'(y) dy = \int \left(-\frac{1}{4y-8} \right) dy$$
$$f(y) = -\frac{\ln(y-2)}{4} + c_1$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = -\frac{x^2}{2} - \frac{\ln(y-2)}{4} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -\frac{x^2}{2} - \frac{\ln(y-2)}{4}$$

The solution becomes

$$y = e^{-2x^2-4c_1} + 2$$

Summary

The solution(s) found are the following

$$y = e^{-2x^2-4c_1} + 2 \tag{1}$$

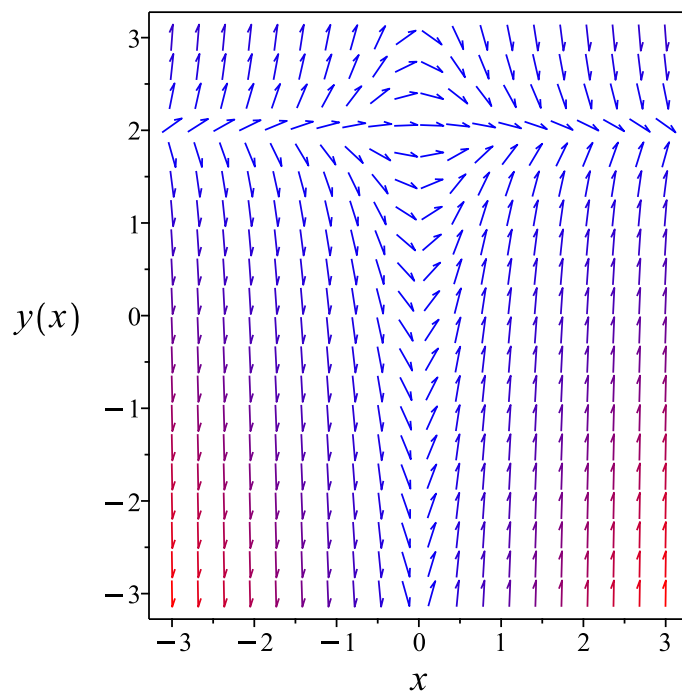


Figure 156: Slope field plot

Verification of solutions

$$y = e^{-2x^2 - 4c_1} + 2$$

Verified OK.

5.4.5 Maple step by step solution

Let's solve

$$y' + 4yx = 8x$$

- Highest derivative means the order of the ODE is 1

$$y'$$

- Separate variables

$$\frac{y'}{y-2} = -4x$$

- Integrate both sides with respect to x

$$\int \frac{y'}{y-2} dx = \int -4x dx + c_1$$

- Evaluate integral

- $\ln(y - 2) = -2x^2 + c_1$
Solve for y
 $y = e^{-2x^2 + c_1} + 2$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
<- 1st order linear successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 14

```
dsolve(diff(y(x),x)+4*x*y(x)=8*x,y(x), singsol=all)
```

$$y(x) = 2 + e^{-2x^2} c_1$$

✓ Solution by Mathematica

Time used: 0.041 (sec). Leaf size: 22

```
DSolve[y'[x]+4*x*y[x]==8*x,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow 2 + c_1 e^{-2x^2}$$

$$y(x) \rightarrow 2$$

5.5 problem 5

5.5.1	Solving as separable ode	832
5.5.2	Solving as linear ode	834
5.5.3	Solving as first order ode lie symmetry lookup ode	836
5.5.4	Solving as exact ode	840
5.5.5	Maple step by step solution	844

Internal problem ID [11642]

Internal file name [OUTPUT/11651_Tuesday_April_09_2024_02_04_55_AM_68847940/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 2, section 2.3 (Linear equations). Exercises page 56

Problem number: 5.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact", "linear", "separable", "first_order_ode_lie_symmetry_lookup"

Maple gives the following as the ode type

[_separable]

$$x' + \frac{x}{t^2} = \frac{1}{t^2}$$

5.5.1 Solving as separable ode

In canonical form the ODE is

$$\begin{aligned}x' &= F(t, x) \\ &= f(t)g(x) \\ &= \frac{1-x}{t^2}\end{aligned}$$

Where $f(t) = \frac{1}{t^2}$ and $g(x) = 1 - x$. Integrating both sides gives

$$\frac{1}{1-x} dx = \frac{1}{t^2} dt$$

$$\int \frac{1}{1-x} dx = \int \frac{1}{t^2} dt$$

$$-\ln(x-1) = -\frac{1}{t} + c_1$$

Raising both side to exponential gives

$$\frac{1}{x-1} = e^{-\frac{1}{t}+c_1}$$

Which simplifies to

$$\frac{1}{x-1} = c_2 e^{-\frac{1}{t}}$$

Summary

The solution(s) found are the following

$$x = \frac{\left(c_2 e^{\frac{c_1 t-1}{t}} + 1\right) e^{-\frac{c_1 t-1}{t}}}{c_2} \quad (1)$$

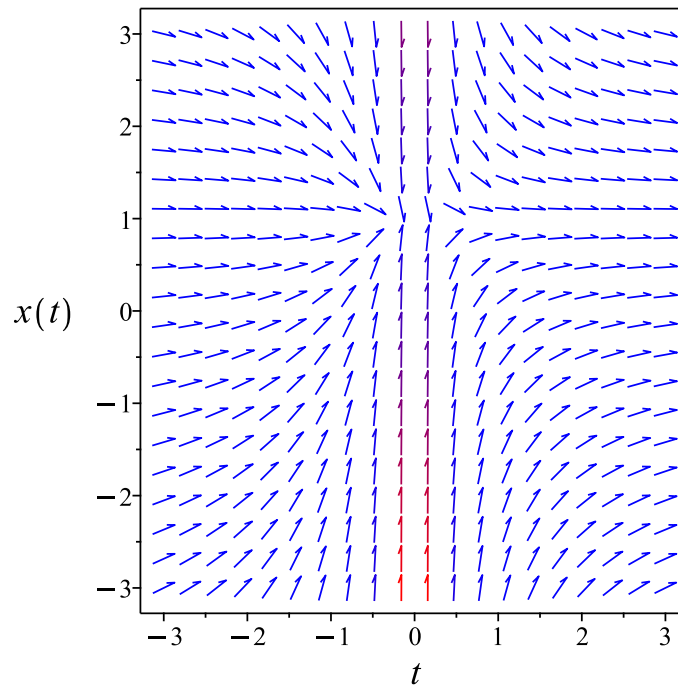


Figure 157: Slope field plot

Verification of solutions

$$x = \frac{\left(c_2 e^{\frac{c_1 t - 1}{t}} + 1\right) e^{-\frac{c_1 t - 1}{t}}}{c_2}$$

Verified OK.

5.5.2 Solving as linear ode

Entering Linear first order ODE solver. In canonical form a linear first order is

$$x' + p(t)x = q(t)$$

Where here

$$p(t) = \frac{1}{t^2}$$
$$q(t) = \frac{1}{t^2}$$

Hence the ode is

$$x' + \frac{x}{t^2} = \frac{1}{t^2}$$

The integrating factor μ is

$$\mu = e^{\int \frac{1}{t^2} dt}$$
$$= e^{-\frac{1}{t}}$$

The ode becomes

$$\frac{d}{dt}(\mu x) = (\mu) \left(\frac{1}{t^2}\right)$$
$$\frac{d}{dt}\left(e^{-\frac{1}{t}} x\right) = \left(e^{-\frac{1}{t}}\right) \left(\frac{1}{t^2}\right)$$
$$d\left(e^{-\frac{1}{t}} x\right) = \left(\frac{e^{-\frac{1}{t}}}{t^2}\right) dt$$

Integrating gives

$$e^{-\frac{1}{t}} x = \int \frac{e^{-\frac{1}{t}}}{t^2} dt$$
$$e^{-\frac{1}{t}} x = e^{-\frac{1}{t}} + c_1$$

Dividing both sides by the integrating factor $\mu = e^{-\frac{1}{t}}$ results in

$$x = e^{\frac{1}{t}} e^{-\frac{1}{t}} + c_1 e^{\frac{1}{t}}$$

which simplifies to

$$x = 1 + c_1 e^{\frac{1}{t}}$$

Summary

The solution(s) found are the following

$$x = 1 + c_1 e^{\frac{1}{t}} \tag{1}$$

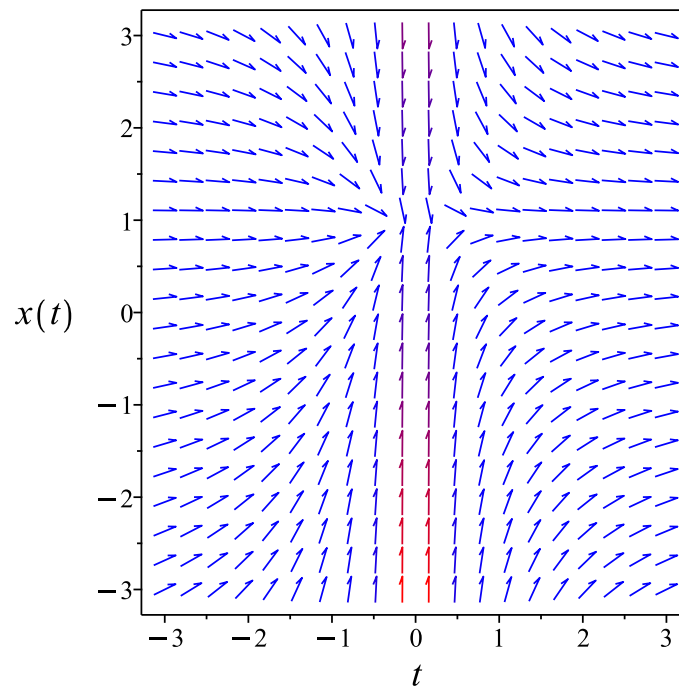


Figure 158: Slope field plot

Verification of solutions

$$x = 1 + c_1 e^{\frac{1}{t}}$$

Verified OK.

5.5.3 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$x' = -\frac{x-1}{t^2}$$

$$x' = \omega(t, x)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_t + \omega(\eta_x - \xi_t) - \omega^2 \xi_x - \omega_t \xi - \omega_x \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 124: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(t, x) &= 0 \\ \eta(t, x) &= e^{\frac{1}{t}}\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(t, x) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dt}{\xi} = \frac{dx}{\eta} = dS\tag{1}$$

The above comes from the requirements that $(\xi \frac{\partial}{\partial t} + \eta \frac{\partial}{\partial x}) S(t, x) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = t$$

S is found from

$$\begin{aligned}S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{e^{\frac{1}{t}}} dy\end{aligned}$$

Which results in

$$S = e^{-\frac{1}{t}} x$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_t + \omega(t, x)S_x}{R_t + \omega(t, x)R_x}\tag{2}$$

Where in the above R_t, R_x, S_t, S_x are all partial derivatives and $\omega(t, x)$ is the right hand side of the original ode given by

$$\omega(t, x) = -\frac{x-1}{t^2}$$

Evaluating all the partial derivatives gives

$$\begin{aligned}R_t &= 1 \\ R_x &= 0 \\ S_t &= \frac{e^{-\frac{1}{t}} x}{t^2} \\ S_x &= e^{-\frac{1}{t}}\end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = \frac{e^{-\frac{1}{t}}}{t^2} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for t, x in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = \frac{e^{-\frac{1}{R}}}{R^2}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = e^{-\frac{1}{R}} + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to t, x coordinates. This results in

$$e^{-\frac{1}{t}}x = e^{-\frac{1}{t}} + c_1$$

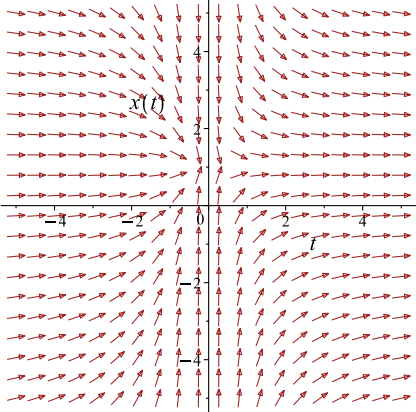
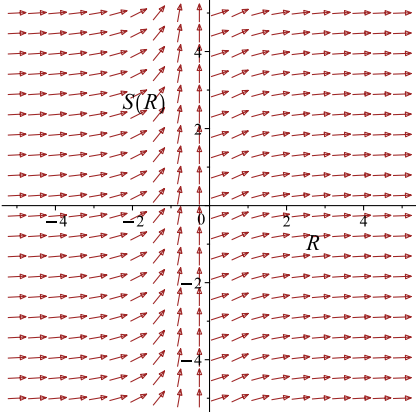
Which simplifies to

$$e^{-\frac{1}{t}}(x - 1) - c_1 = 0$$

Which gives

$$x = \left(e^{-\frac{1}{t}} + c_1 \right) e^{\frac{1}{t}}$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in t, x coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dx}{dt} = -\frac{x-1}{t^2}$ 	$R = t$ $S = e^{-\frac{1}{t}} x$	$\frac{dS}{dR} = \frac{e^{-\frac{1}{R}}}{R^2}$ 

Summary

The solution(s) found are the following

$$x = \left(e^{-\frac{1}{t}} + c_1 \right) e^{\frac{1}{t}} \quad (1)$$

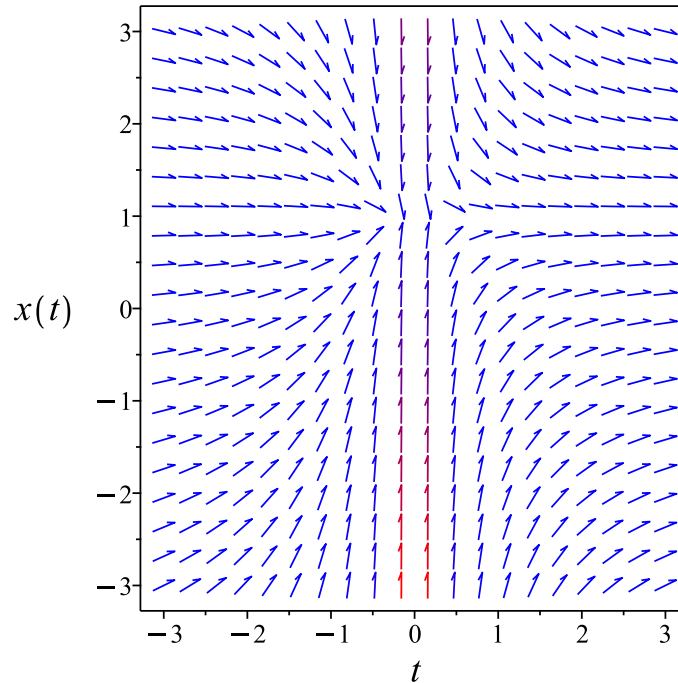


Figure 159: Slope field plot

Verification of solutions

$$x = \left(e^{-\frac{1}{t}} + c_1 \right) e^{\frac{1}{t}}$$

Verified OK.

5.5.4 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(t, x) dt + N(t, x) dx = 0 \tag{1A}$$

Therefore

$$\begin{aligned}\left(\frac{1}{1-x}\right) dx &= \left(\frac{1}{t^2}\right) dt \\ \left(-\frac{1}{t^2}\right) dt + \left(\frac{1}{1-x}\right) dx &= 0\end{aligned} \tag{2A}$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(t, x) &= -\frac{1}{t^2} \\ N(t, x) &= \frac{1}{1-x}\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial x} = \frac{\partial N}{\partial t}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial x} &= \frac{\partial}{\partial x} \left(-\frac{1}{t^2}\right) \\ &= 0\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial t} &= \frac{\partial}{\partial t} \left(\frac{1}{1-x} \right) \\ &= 0\end{aligned}$$

Since $\frac{\partial M}{\partial x} = \frac{\partial N}{\partial t}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(t, x)$

$$\frac{\partial \phi}{\partial t} = M \quad (1)$$

$$\frac{\partial \phi}{\partial x} = N \quad (2)$$

Integrating (1) w.r.t. t gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial t} dt &= \int M dt \\ \int \frac{\partial \phi}{\partial t} dt &= \int -\frac{1}{t^2} dt \\ \phi &= \frac{1}{t} + f(x)\end{aligned} \quad (3)$$

Where $f(x)$ is used for the constant of integration since ϕ is a function of both t and x . Taking derivative of equation (3) w.r.t x gives

$$\frac{\partial \phi}{\partial x} = 0 + f'(x) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial x} = \frac{1}{1-x}$. Therefore equation (4) becomes

$$\frac{1}{1-x} = 0 + f'(x) \quad (5)$$

Solving equation (5) for $f'(x)$ gives

$$f'(x) = -\frac{1}{x-1}$$

Integrating the above w.r.t x gives

$$\begin{aligned}\int f'(x) dx &= \int \left(-\frac{1}{x-1} \right) dx \\ f(x) &= -\ln(x-1) + c_1\end{aligned}$$

Where c_1 is constant of integration. Substituting result found above for $f(x)$ into equation (3) gives ϕ

$$\phi = \frac{1}{t} - \ln(x - 1) + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = \frac{1}{t} - \ln(x - 1)$$

The solution becomes

$$x = e^{-\frac{c_1 t - 1}{t}} + 1$$

Summary

The solution(s) found are the following

$$x = e^{-\frac{c_1 t - 1}{t}} + 1 \tag{1}$$

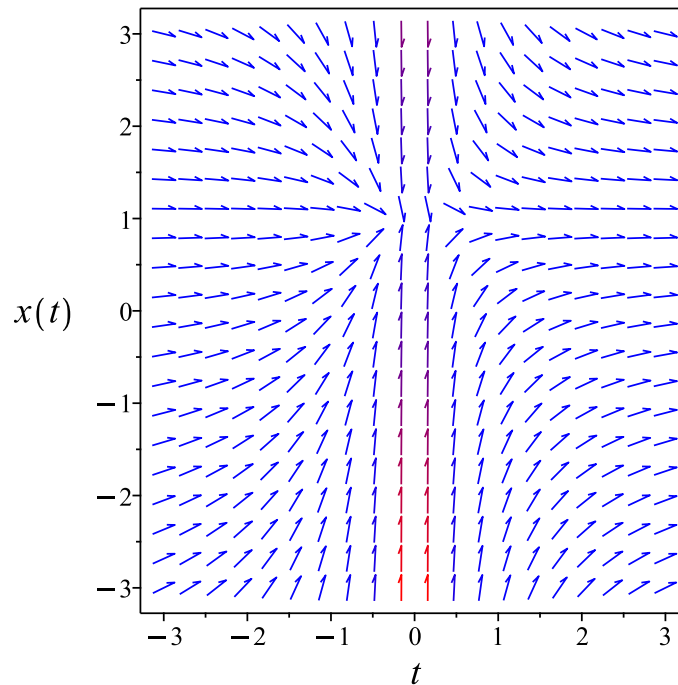


Figure 160: Slope field plot

Verification of solutions

$$x = e^{-\frac{c_1 t - 1}{t}} + 1$$

Verified OK.

5.5.5 Maple step by step solution

Let's solve

$$x' + \frac{x}{t^2} = \frac{1}{t^2}$$

- Highest derivative means the order of the ODE is 1

$$x'$$

- Separate variables

$$\frac{x'}{x-1} = -\frac{1}{t^2}$$

- Integrate both sides with respect to t

$$\int \frac{x'}{x-1} dt = \int -\frac{1}{t^2} dt + c_1$$

- Evaluate integral

$$\ln(x-1) = \frac{1}{t} + c_1$$

- Solve for x

$$x = e^{\frac{c_1 t + 1}{t}} + 1$$

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
<- 1st order linear successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 12

```
dsolve(diff(x(t),t)+x(t)/t^2=1/t^2,x(t), singsol=all)
```

$$x(t) = 1 + e^{\frac{1}{t}} c_1$$

✓ Solution by Mathematica

Time used: 0.029 (sec). Leaf size: 20

```
DSolve[x'[t]+x[t]/t^2==1/t^2,x[t],t,IncludeSingularSolutions -> True]
```

$$x(t) \rightarrow 1 + c_1 e^{\frac{1}{t}}$$

$$x(t) \rightarrow 1$$

5.6 problem 6

5.6.1	Solving as separable ode	846
5.6.2	Solving as linear ode	848
5.6.3	Solving as first order ode lie symmetry lookup ode	850
5.6.4	Solving as exact ode	854
5.6.5	Maple step by step solution	858

Internal problem ID [11643]

Internal file name [OUTPUT/11652_Tuesday_April_09_2024_02_04_56_AM_51780437/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.3 (Linear equations). Exercises page 56

Problem number: 6.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact", "linear", "separable", "first_order_ode_lie_symmetry_lookup"

Maple gives the following as the ode type

[_separable]

$$(u^2 + 1)v' + 4vu = 3u$$

5.6.1 Solving as separable ode

In canonical form the ODE is

$$\begin{aligned}v' &= F(u, v) \\ &= f(u)g(v) \\ &= \frac{u(-4v + 3)}{u^2 + 1}\end{aligned}$$

Where $f(u) = \frac{u}{u^2+1}$ and $g(v) = -4v + 3$. Integrating both sides gives

$$\begin{aligned}\frac{1}{-4v + 3} dv &= \frac{u}{u^2 + 1} du \\ \int \frac{1}{-4v + 3} dv &= \int \frac{u}{u^2 + 1} du\end{aligned}$$

$$-\frac{\ln(-4v+3)}{4} = \frac{\ln(u^2+1)}{2} + c_1$$

Raising both side to exponential gives

$$\frac{1}{(-4v+3)^{\frac{1}{4}}} = e^{\frac{\ln(u^2+1)}{2} + c_1}$$

Which simplifies to

$$\frac{1}{(-4v+3)^{\frac{1}{4}}} = c_2 \sqrt{u^2+1}$$

Which simplifies to

$$v = \frac{\left(3c_2^4 e^{4c_1} (u^2+1)^2 - 1\right) e^{-4c_1}}{4c_2^4 (u^2+1)^2}$$

Summary

The solution(s) found are the following

$$v = \frac{\left(3c_2^4 e^{4c_1} (u^2+1)^2 - 1\right) e^{-4c_1}}{4c_2^4 (u^2+1)^2} \quad (1)$$

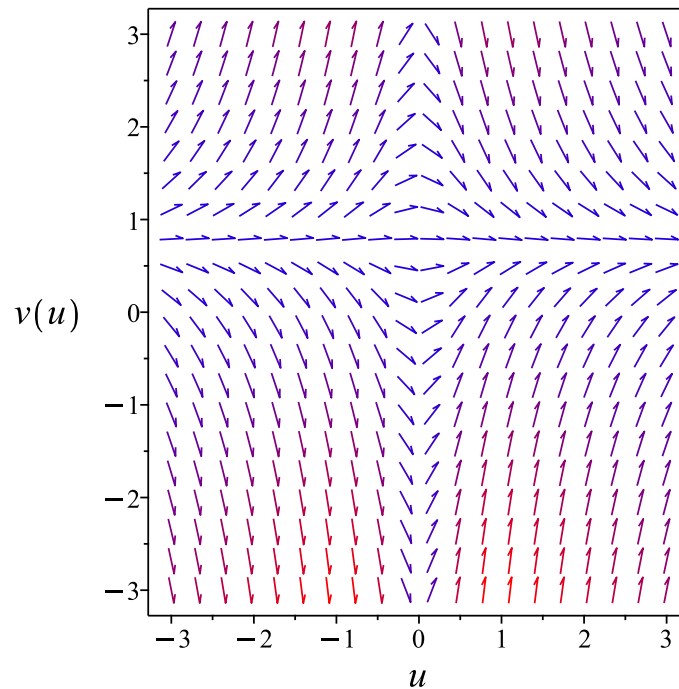


Figure 161: Slope field plot

Verification of solutions

$$v = \frac{\left(3c_2^4 e^{4c_1} (u^2 + 1)^2 - 1\right) e^{-4c_1}}{4c_2^4 (u^2 + 1)^2}$$

Verified OK.

5.6.2 Solving as linear ode

Entering Linear first order ODE solver. In canonical form a linear first order is

$$v' + p(u)v = q(u)$$

Where here

$$p(u) = \frac{4u}{u^2 + 1}$$
$$q(u) = \frac{3u}{u^2 + 1}$$

Hence the ode is

$$v' + \frac{4uv}{u^2 + 1} = \frac{3u}{u^2 + 1}$$

The integrating factor μ is

$$\mu = e^{\int \frac{4u}{u^2+1} du}$$
$$= (u^2 + 1)^2$$

The ode becomes

$$\frac{d}{du}(\mu v) = (\mu) \left(\frac{3u}{u^2 + 1} \right)$$
$$\frac{d}{du} \left((u^2 + 1)^2 v \right) = \left((u^2 + 1)^2 \right) \left(\frac{3u}{u^2 + 1} \right)$$
$$d \left((u^2 + 1)^2 v \right) = (3u(u^2 + 1)) du$$

Integrating gives

$$(u^2 + 1)^2 v = \int 3u(u^2 + 1) du$$
$$(u^2 + 1)^2 v = \frac{3(u^2 + 1)^2}{4} + c_1$$

Dividing both sides by the integrating factor $\mu = (u^2 + 1)^2$ results in

$$v = \frac{3}{4} + \frac{c_1}{(u^2 + 1)^2}$$

Summary

The solution(s) found are the following

$$v = \frac{3}{4} + \frac{c_1}{(u^2 + 1)^2} \tag{1}$$

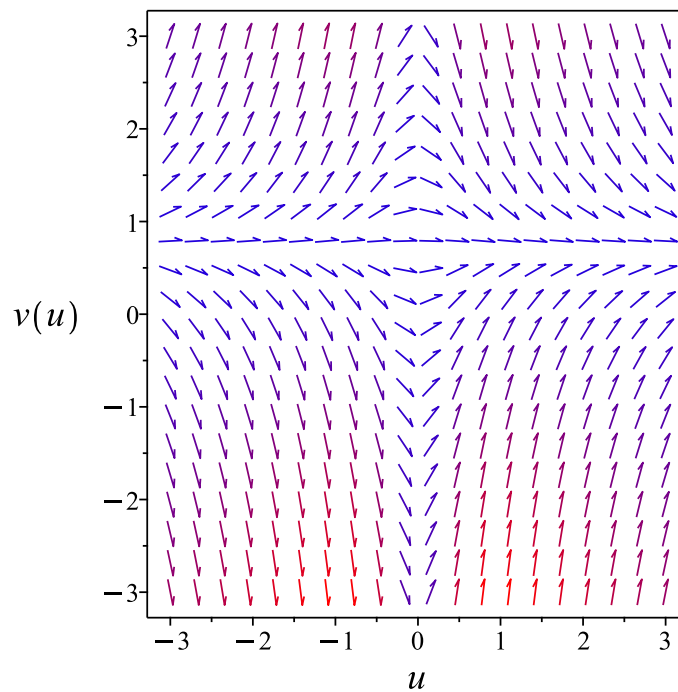


Figure 162: Slope field plot

Verification of solutions

$$v = \frac{3}{4} + \frac{c_1}{(u^2 + 1)^2}$$

Verified OK.

5.6.3 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$v' = -\frac{u(4v-3)}{u^2+1}$$

$$v' = \omega(u, v)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_u + \omega(\eta_v - \xi_u) - \omega^2 \xi_v - \omega_u \xi - \omega_v \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 127: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(u, v) &= 0 \\ \eta(u, v) &= \frac{1}{(u^2 + 1)^2}\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(u, v) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{du}{\xi} = \frac{dv}{\eta} = dS\tag{1}$$

The above comes from the requirements that $(\xi \frac{\partial}{\partial u} + \eta \frac{\partial}{\partial v}) S(u, v) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = u$$

S is found from

$$\begin{aligned}S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{1}{(u^2+1)^2}} dy\end{aligned}$$

Which results in

$$S = (u^2 + 1)^2 v$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_u + \omega(u, v)S_v}{R_u + \omega(u, v)R_v}\tag{2}$$

Where in the above R_u, R_v, S_u, S_v are all partial derivatives and $\omega(u, v)$ is the right hand side of the original ode given by

$$\omega(u, v) = -\frac{u(4v - 3)}{u^2 + 1}$$

Evaluating all the partial derivatives gives

$$\begin{aligned}R_u &= 1 \\R_v &= 0 \\S_u &= 4(u^2 + 1)vu \\S_v &= (u^2 + 1)^2\end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 3u^3 + 3u \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for u, v in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 3R^3 + 3R$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = \frac{3(R^2 + 1)^2}{4} + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to u, v coordinates. This results in

$$(u^2 + 1)^2 v = \frac{3(u^2 + 1)^2}{4} + c_1$$

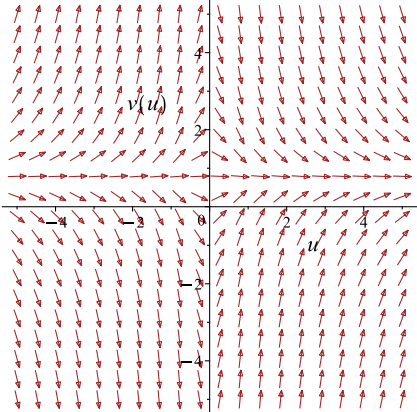
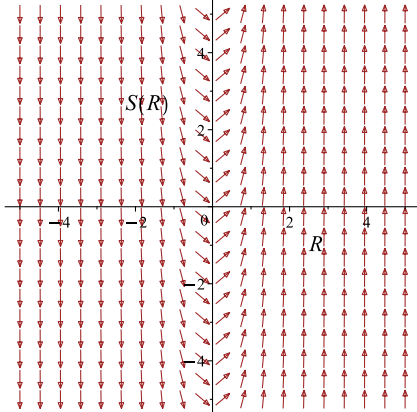
Which simplifies to

$$(u^2 + 1)^2 v = \frac{3(u^2 + 1)^2}{4} + c_1$$

Which gives

$$v = \frac{3u^4 + 6u^2 + 4c_1 + 3}{4(u^2 + 1)^2}$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in u, v coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dv}{du} = -\frac{u(4v-3)}{u^2+1}$ 	$R = u$ $S = (u^2 + 1)^2 v$	$\frac{dS}{dR} = 3R^3 + 3R$ 

Summary

The solution(s) found are the following

$$v = \frac{3u^4 + 6u^2 + 4c_1 + 3}{4(u^2 + 1)^2} \tag{1}$$

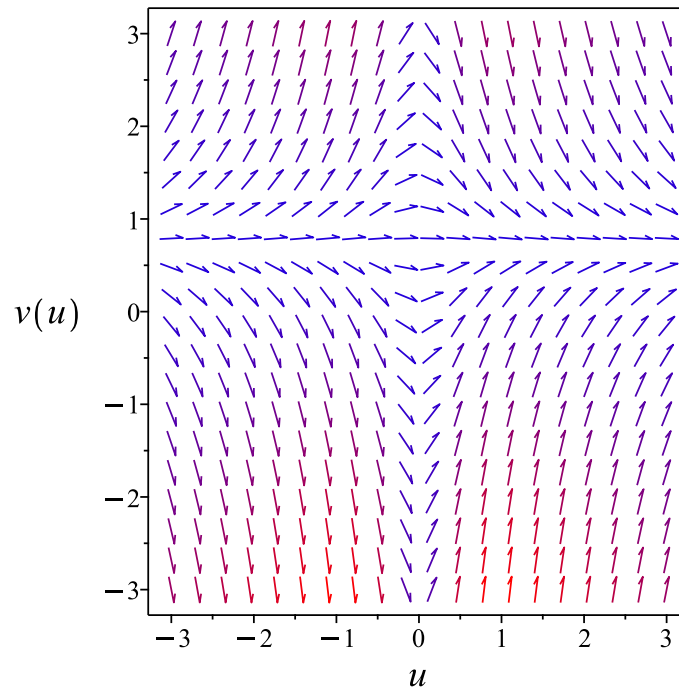


Figure 163: Slope field plot

Verification of solutions

$$v = \frac{3u^4 + 6u^2 + 4c_1 + 3}{4(u^2 + 1)^2}$$

Verified OK.

5.6.4 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx}\phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(u, v) du + N(u, v) dv = 0 \tag{1A}$$

Therefore

$$\begin{aligned}\left(\frac{1}{-4v+3}\right) dv &= \left(\frac{u}{u^2+1}\right) du \\ \left(-\frac{u}{u^2+1}\right) du + \left(\frac{1}{-4v+3}\right) dv &= 0\end{aligned} \tag{2A}$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(u, v) &= -\frac{u}{u^2+1} \\ N(u, v) &= \frac{1}{-4v+3}\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial v} = \frac{\partial N}{\partial u}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial v} &= \frac{\partial}{\partial v} \left(-\frac{u}{u^2+1}\right) \\ &= 0\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial u} &= \frac{\partial}{\partial u} \left(\frac{1}{-4v+3} \right) \\ &= 0\end{aligned}$$

Since $\frac{\partial M}{\partial v} = \frac{\partial N}{\partial u}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(u, v)$

$$\frac{\partial \phi}{\partial u} = M \tag{1}$$

$$\frac{\partial \phi}{\partial v} = N \tag{2}$$

Integrating (1) w.r.t. u gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial u} du &= \int M du \\ \int \frac{\partial \phi}{\partial u} du &= \int -\frac{u}{u^2+1} du \\ \phi &= -\frac{\ln(u^2+1)}{2} + f(v)\end{aligned} \tag{3}$$

Where $f(v)$ is used for the constant of integration since ϕ is a function of both u and v . Taking derivative of equation (3) w.r.t v gives

$$\frac{\partial \phi}{\partial v} = 0 + f'(v) \tag{4}$$

But equation (2) says that $\frac{\partial \phi}{\partial v} = \frac{1}{-4v+3}$. Therefore equation (4) becomes

$$\frac{1}{-4v+3} = 0 + f'(v) \tag{5}$$

Solving equation (5) for $f'(v)$ gives

$$f'(v) = -\frac{1}{4v-3}$$

Integrating the above w.r.t v gives

$$\begin{aligned}\int f'(v) dv &= \int \left(-\frac{1}{4v-3} \right) dv \\ f(v) &= -\frac{\ln(4v-3)}{4} + c_1\end{aligned}$$

Where c_1 is constant of integration. Substituting result found above for $f(v)$ into equation (3) gives ϕ

$$\phi = -\frac{\ln(u^2 + 1)}{2} - \frac{\ln(4v - 3)}{4} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -\frac{\ln(u^2 + 1)}{2} - \frac{\ln(4v - 3)}{4}$$

The solution becomes

$$v = \frac{3u^4 + 6u^2 + e^{-4c_1} + 3}{4u^4 + 8u^2 + 4}$$

Summary

The solution(s) found are the following

$$v = \frac{3u^4 + 6u^2 + e^{-4c_1} + 3}{4u^4 + 8u^2 + 4} \quad (1)$$

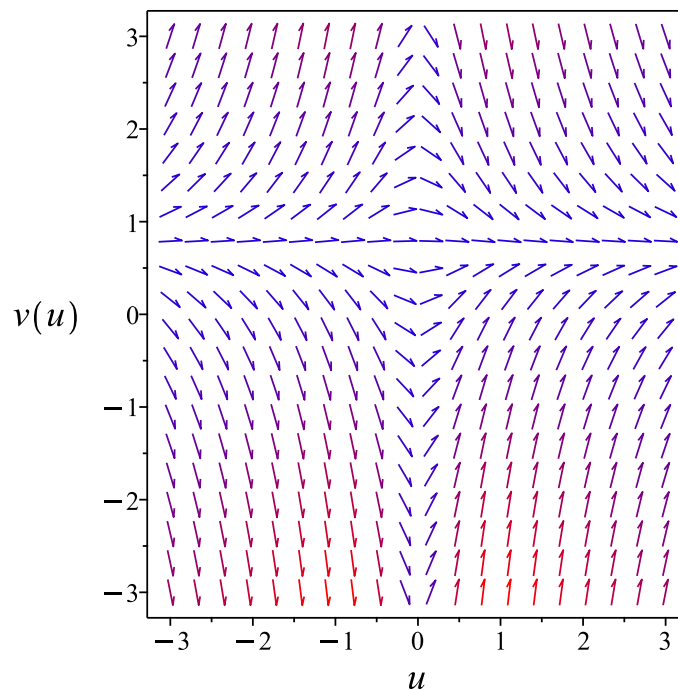


Figure 164: Slope field plot

Verification of solutions

$$v = \frac{3u^4 + 6u^2 + e^{-4c_1} + 3}{4u^4 + 8u^2 + 4}$$

Verified OK.

5.6.5 Maple step by step solution

Let's solve

$$(u^2 + 1)v' + 4vu = 3u$$

- Highest derivative means the order of the ODE is 1

v'

- Separate variables

$$\frac{v'}{4v-3} = -\frac{u}{u^2+1}$$

- Integrate both sides with respect to u

$$\int \frac{v'}{4v-3} du = \int -\frac{u}{u^2+1} du + c_1$$

- Evaluate integral

$$\frac{\ln(4v-3)}{4} = -\frac{\ln(u^2+1)}{2} + c_1$$

- Solve for v

$$v = \frac{3u^4 + 6u^2 + e^{4c_1} + 3}{4(u^4 + 2u^2 + 1)}$$

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
<- 1st order linear successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 15

```
dsolve((u^2+1)*diff(v(u),u)+4*u*v(u)=3*u,v(u), singsol=all)
```

$$v(u) = \frac{3}{4} + \frac{c_1}{(u^2 + 1)^2}$$

✓ Solution by Mathematica

Time used: 0.032 (sec). Leaf size: 38

```
DSolve[(u^2+1)*v'[u]+4*u*v[u]==3*u,v[u],u,IncludeSingularSolutions -> True]
```

$$v(u) \rightarrow \frac{3u^4 + 6u^2 + 4c_1}{4(u^2 + 1)^2}$$

$$v(u) \rightarrow \frac{3}{4}$$

5.7 problem 7

5.7.1	Solving as linear ode	860
5.7.2	Solving as differentialType ode	862
5.7.3	Solving as first order ode lie symmetry lookup ode	864
5.7.4	Solving as exact ode	868
5.7.5	Maple step by step solution	872

Internal problem ID [11644]

Internal file name [OUTPUT/11653_Tuesday_April_09_2024_02_04_57_AM_21312822/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.3 (Linear equations). Exercises page 56

Problem number: 7.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"exact"**, **"linear"**, **"differentialType"**, **"first_order_ode_lie_symmetry_lookup"**

Maple gives the following as the ode type

`[_linear]`

$$y'x + \frac{(2x+1)y}{1+x} = x-1$$

5.7.1 Solving as linear ode

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = -\frac{-2x-1}{x(1+x)}$$

$$q(x) = \frac{x-1}{x}$$

Hence the ode is

$$y' - \frac{(-2x-1)y}{x(1+x)} = \frac{x-1}{x}$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int -\frac{2x-1}{x(1+x)} dx} \\ &= x(1+x)\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu y) &= (\mu) \left(\frac{x-1}{x} \right) \\ \frac{d}{dx}(x(1+x)y) &= (x(1+x)) \left(\frac{x-1}{x} \right) \\ d(x(1+x)y) &= (x^2-1) dx\end{aligned}$$

Integrating gives

$$\begin{aligned}x(1+x)y &= \int x^2 - 1 dx \\ x(1+x)y &= \frac{1}{3}x^3 - x + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = x(1+x)$ results in

$$y = \frac{\frac{1}{3}x^3 - x}{x(1+x)} + \frac{c_1}{x(1+x)}$$

which simplifies to

$$y = \frac{x^3 + 3c_1 - 3x}{3x(1+x)}$$

Summary

The solution(s) found are the following

$$y = \frac{x^3 + 3c_1 - 3x}{3x(1+x)} \tag{1}$$

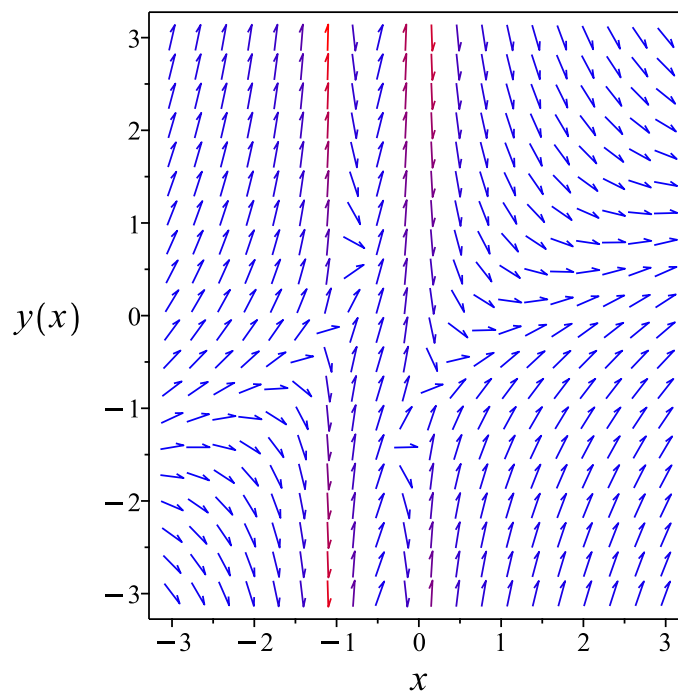


Figure 165: Slope field plot

Verification of solutions

$$y = \frac{x^3 + 3c_1 - 3x}{3x(1+x)}$$

Verified OK.

5.7.2 Solving as differentialType ode

Writing the ode as

$$y' = \frac{-\frac{(2x+1)y}{1+x} + x - 1}{x} \tag{1}$$

Which becomes

$$0 = (-x^2 - x) dy + (x^2 - 2xy - y - 1) dx \tag{2}$$

But the RHS is complete differential because

$$(-x^2 - x) dy + (x^2 - 2xy - y - 1) dx = d\left(\frac{1}{3}x^3 - x^2y - xy - x\right)$$

Hence (2) becomes

$$0 = d\left(\frac{1}{3}x^3 - x^2y - xy - x\right)$$

Integrating both sides gives gives these solutions

$$y = \frac{x^3 + 3c_1 - 3x}{3x(1+x)} + c_1$$

Summary

The solution(s) found are the following

$$y = \frac{x^3 + 3c_1 - 3x}{3x(1+x)} + c_1 \quad (1)$$

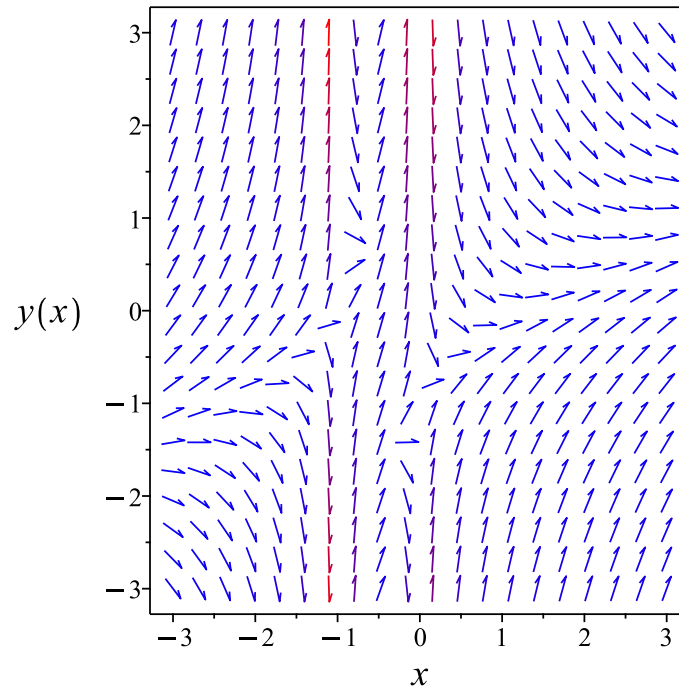


Figure 166: Slope field plot

Verification of solutions

$$y = \frac{x^3 + 3c_1 - 3x}{3x(1+x)} + c_1$$

Verified OK.

5.7.3 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = -\frac{-x^2 + 2xy + y + 1}{(1+x)x}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 130: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= \frac{1}{x(1+x)}\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned}S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{1}{x(1+x)}} dy\end{aligned}$$

Which results in

$$S = x(1+x)y$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y}\tag{2}$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{-x^2 + 2xy + y + 1}{(1+x)x}$$

Evaluating all the partial derivatives gives

$$\begin{aligned}R_x &= 1 \\R_y &= 0 \\S_x &= (2x + 1)y \\S_y &= x(1 + x)\end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = x^2 - 1 \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = R^2 - 1$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = \frac{1}{3}R^3 - R + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$x(1 + x)y = \frac{1}{3}x^3 - x + c_1$$

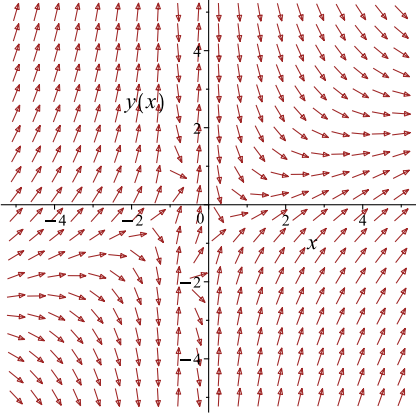
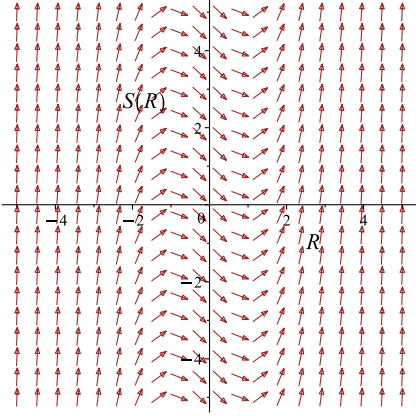
Which simplifies to

$$x(1 + x)y = \frac{1}{3}x^3 - x + c_1$$

Which gives

$$y = \frac{x^3 + 3c_1 - 3x}{3x(1 + x)}$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{-x^2+2xy+y+1}{(1+x)x}$ 	$R = x$ $S = x(1+x)y$	$\frac{dS}{dR} = R^2 - 1$ 

Summary

The solution(s) found are the following

$$y = \frac{x^3 + 3c_1 - 3x}{3x(1+x)} \tag{1}$$

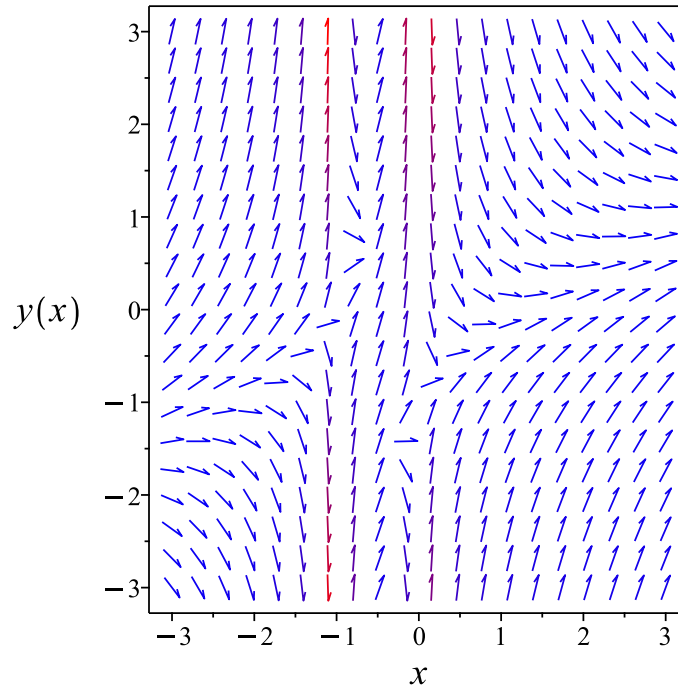


Figure 167: Slope field plot

Verification of solutions

$$y = \frac{x^3 + 3c_1 - 3x}{3x(1+x)}$$

Verified OK.

5.7.4 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx}\phi(x, y) = 0$$

Hence

$$\frac{\partial\phi}{\partial x} + \frac{\partial\phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (1A)$$

Therefore

$$\begin{aligned}(x(1+x)) dy &= (x^2 - 2xy - y - 1) dx \\ (-x^2 + 2xy + y + 1) dx &+ (x(1+x)) dy = 0\end{aligned} \quad (2A)$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= -x^2 + 2xy + y + 1 \\ N(x, y) &= x(1+x)\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(-x^2 + 2xy + y + 1) \\ &= 2x + 1\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(x(1+x)) \\ &= 2x + 1\end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \quad (1)$$

$$\frac{\partial \phi}{\partial y} = N \quad (2)$$

Integrating (1) w.r.t. x gives

$$\int \frac{\partial \phi}{\partial x} dx = \int M dx$$

$$\int \frac{\partial \phi}{\partial x} dx = \int -x^2 + 2xy + y + 1 dx$$

$$\phi = -\frac{1}{3}x^3 + x^2y + xy + x + f(y) \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = x^2 + x + f'(y) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = x(1 + x)$. Therefore equation (4) becomes

$$x(1 + x) = x^2 + x + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 0$$

Therefore

$$f(y) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(y)$ into equation (3) gives ϕ

$$\phi = -\frac{1}{3}x^3 + x^2y + xy + x + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -\frac{1}{3}x^3 + x^2y + xy + x$$

The solution becomes

$$y = \frac{x^3 + 3c_1 - 3x}{3x(1+x)}$$

Summary

The solution(s) found are the following

$$y = \frac{x^3 + 3c_1 - 3x}{3x(1+x)} \tag{1}$$

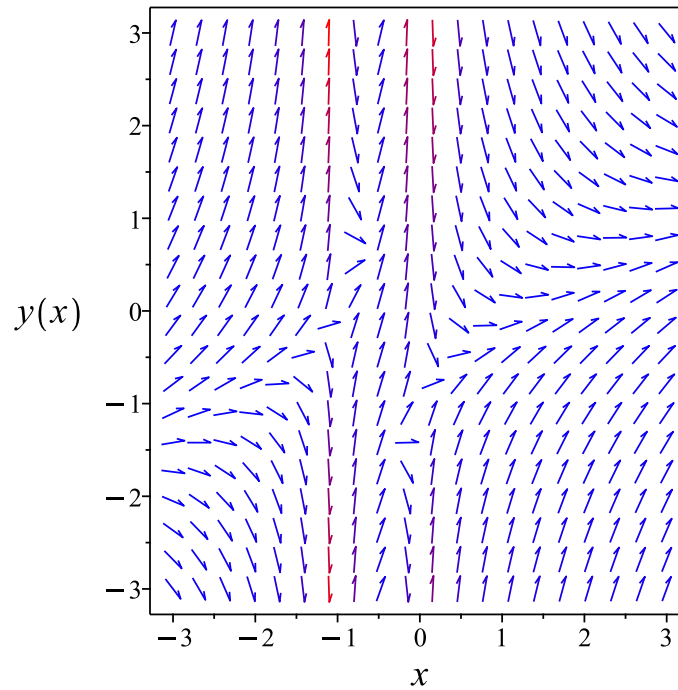


Figure 168: Slope field plot

Verification of solutions

$$y = \frac{x^3 + 3c_1 - 3x}{3x(1+x)}$$

Verified OK.

5.7.5 Maple step by step solution

Let's solve

$$y'x + \frac{(2x+1)y}{1+x} = x - 1$$

- Highest derivative means the order of the ODE is 1

$$y'$$

- Isolate the derivative

$$y' = -\frac{(2x+1)y}{x(1+x)} + \frac{x-1}{x}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE

$$y' + \frac{(2x+1)y}{x(1+x)} = \frac{x-1}{x}$$

- The ODE is linear; multiply by an integrating factor $\mu(x)$

$$\mu(x) \left(y' + \frac{(2x+1)y}{x(1+x)} \right) = \frac{\mu(x)(x-1)}{x}$$

- Assume the lhs of the ODE is the total derivative $\frac{d}{dx}(\mu(x)y)$

$$\mu(x) \left(y' + \frac{(2x+1)y}{x(1+x)} \right) = \mu'(x)y + \mu(x)y'$$

- Isolate $\mu'(x)$

$$\mu'(x) = \frac{\mu(x)(2x+1)}{x(1+x)}$$

- Solve to find the integrating factor

$$\mu(x) = x(1+x)$$

- Integrate both sides with respect to x

$$\int \left(\frac{d}{dx}(\mu(x)y) \right) dx = \int \frac{\mu(x)(x-1)}{x} dx + c_1$$

- Evaluate the integral on the lhs

$$\mu(x)y = \int \frac{\mu(x)(x-1)}{x} dx + c_1$$

- Solve for y

$$y = \frac{\int \frac{\mu(x)(x-1)}{x} dx + c_1}{\mu(x)}$$

- Substitute $\mu(x) = x(1+x)$

$$y = \frac{\int (x-1)(1+x) dx + c_1}{x(1+x)}$$

- Evaluate the integrals on the rhs

$$y = \frac{\frac{1}{3}x^3 - x + c_1}{x(1+x)}$$

- Simplify

$$y = \frac{x^3 + 3c_1 - 3x}{3x(1+x)}$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
<- 1st order linear successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 24

```
dsolve(x*diff(y(x),x)+(2*x+1)/(x+1)*y(x)=x-1,y(x), singsol=all)
```

$$y(x) = \frac{x^3 + 3c_1 - 3x}{3x(1+x)}$$

✓ Solution by Mathematica

Time used: 0.037 (sec). Leaf size: 28

```
DSolve[x*y'[x]+(2*x+1)/(x+1)*y[x]==x-1,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{x^3 - 3x + 3c_1}{3x(x+1)}$$

5.8 problem 8

5.8.1	Solving as linear ode	874
5.8.2	Solving as first order ode lie symmetry lookup ode	876
5.8.3	Solving as exact ode	880
5.8.4	Maple step by step solution	885

Internal problem ID [11645]

Internal file name [OUTPUT/11654_Tuesday_April_09_2024_02_04_58_AM_13102016/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.3 (Linear equations). Exercises page 56

Problem number: 8.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"linear", "exactWithIntegrationFactor", "first_order_ode_lie_symmetry_lookup"**

Maple gives the following as the ode type

`[_linear]`

$$(x^2 + x - 2) y' + 3y(1 + x) = x - 1$$

5.8.1 Solving as linear ode

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = -\frac{-3x - 3}{x^2 + x - 2}$$
$$q(x) = \frac{1}{x + 2}$$

Hence the ode is

$$y' - \frac{(-3x - 3)y}{x^2 + x - 2} = \frac{1}{x + 2}$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int -\frac{-3x-3}{x^2+x-2} dx} \\ &= e^{2\ln(x-1)+\ln(x+2)}\end{aligned}$$

Which simplifies to

$$\mu = x^3 - 3x + 2$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu y) &= (\mu) \left(\frac{1}{x+2} \right) \\ \frac{d}{dx}((x^3 - 3x + 2) y) &= (x^3 - 3x + 2) \left(\frac{1}{x+2} \right) \\ d((x^3 - 3x + 2) y) &= (x-1)^2 dx\end{aligned}$$

Integrating gives

$$\begin{aligned}(x^3 - 3x + 2) y &= \int (x-1)^2 dx \\ (x^3 - 3x + 2) y &= \frac{(x-1)^3}{3} + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = x^3 - 3x + 2$ results in

$$y = \frac{(x-1)^3}{3x^3 - 9x + 6} + \frac{c_1}{x^3 - 3x + 2}$$

which simplifies to

$$y = \frac{x^3 - 3x^2 + 3c_1 + 3x - 1}{3x^3 - 9x + 6}$$

Summary

The solution(s) found are the following

$$y = \frac{x^3 - 3x^2 + 3c_1 + 3x - 1}{3x^3 - 9x + 6} \quad (1)$$

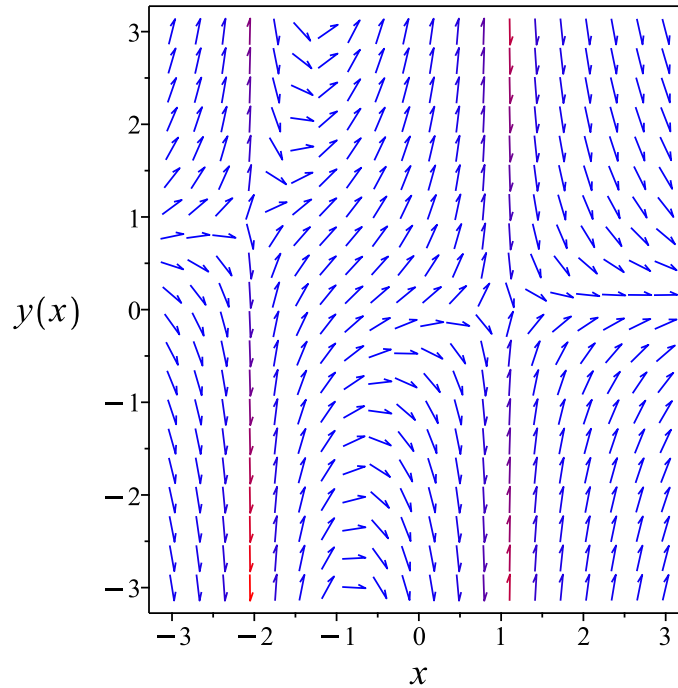


Figure 169: Slope field plot

Verification of solutions

$$y = \frac{x^3 - 3x^2 + 3c_1 + 3x - 1}{3x^3 - 9x + 6}$$

Verified OK.

5.8.2 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = -\frac{3xy - x + 3y + 1}{x^2 + x - 2}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 133: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= e^{-2\ln(x-1)-\ln(x+2)}\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{e^{-2\ln(x-1)-\ln(x+2)}} dy \end{aligned}$$

Which results in

$$S = (x - 1)^2 (x + 2) y$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{3xy - x + 3y + 1}{x^2 + x - 2}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= 3x^2y - 3y \\ S_y &= (x - 1)^2 (x + 2) \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = (x - 1)^2 \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = (R - 1)^2$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by

integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = \frac{(R-1)^3}{3} + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$(x-1)^2(x+2)y = \frac{(x-1)^3}{3} + c_1$$

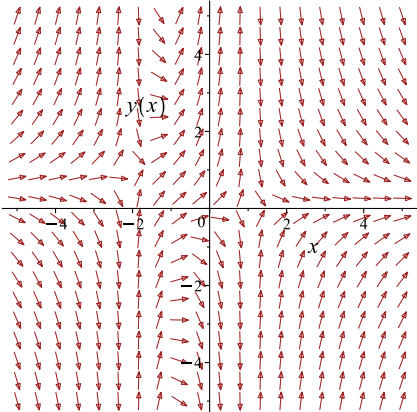
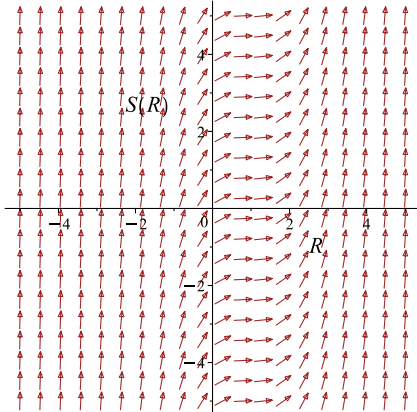
Which simplifies to

$$(x-1)^2(x+2)y = \frac{(x-1)^3}{3} + c_1$$

Which gives

$$y = \frac{x^3 - 3x^2 + 3c_1 + 3x - 1}{3(x-1)^2(x+2)}$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{3xy-x+3y+1}{x^2+x-2}$ 	$R = x$ $S = (x-1)^2(x+2)y$	$\frac{dS}{dR} = (R-1)^2$ 

Summary

The solution(s) found are the following

$$y = \frac{x^3 - 3x^2 + 3c_1 + 3x - 1}{3(x-1)^2(x+2)} \quad (1)$$

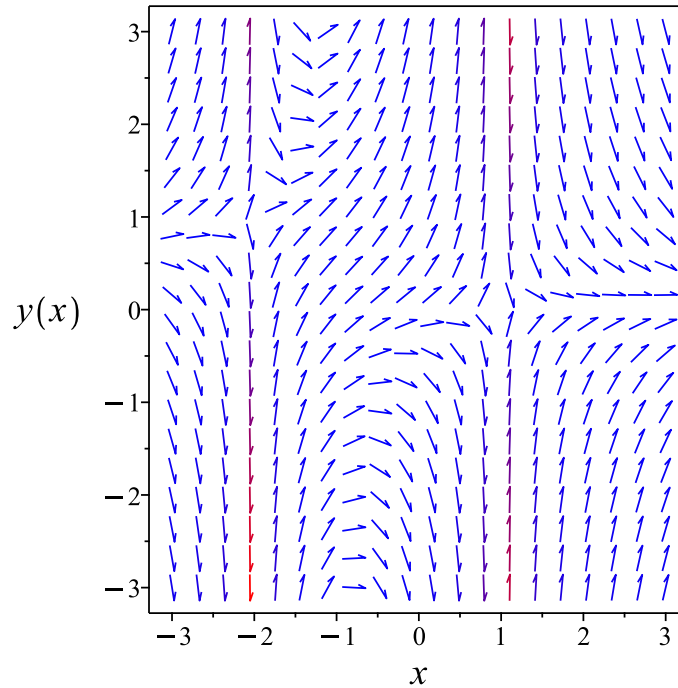


Figure 170: Slope field plot

Verification of solutions

$$y = \frac{x^3 - 3x^2 + 3c_1 + 3x - 1}{3(x-1)^2(x+2)}$$

Verified OK.

5.8.3 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx}\phi(x, y) = 0$$

Hence

$$\frac{\partial\phi}{\partial x} + \frac{\partial\phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \tag{1A}$$

Therefore

$$\begin{aligned}(x^2 + x - 2) dy &= (-3y(1 + x) + x - 1) dx \\ (3y(1 + x) - x + 1) dx + (x^2 + x - 2) dy &= 0\end{aligned} \tag{2A}$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= 3y(1 + x) - x + 1 \\ N(x, y) &= x^2 + x - 2\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(3y(1 + x) - x + 1) \\ &= 3x + 3\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(x^2 + x - 2) \\ &= 2x + 1\end{aligned}$$

Since $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$\begin{aligned} A &= \frac{1}{N} \left(\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} \right) \\ &= \frac{1}{x^2 + x - 2} ((3x + 3) - (2x + 1)) \\ &= \frac{1}{x - 1} \end{aligned}$$

Since A does not depend on y , then it can be used to find an integrating factor. The integrating factor μ is

$$\begin{aligned} \mu &= e^{\int A dx} \\ &= e^{\int \frac{1}{x-1} dx} \end{aligned}$$

The result of integrating gives

$$\begin{aligned} \mu &= e^{\ln(x-1)} \\ &= x - 1 \end{aligned}$$

M and N are multiplied by this integrating factor, giving new M and new N which are called \overline{M} and \overline{N} for now so not to confuse them with the original M and N .

$$\begin{aligned} \overline{M} &= \mu M \\ &= x - 1(3y(1 + x) - x + 1) \\ &= (3y - 1)x^2 + 2x - 1 - 3y \end{aligned}$$

And

$$\begin{aligned} \overline{N} &= \mu N \\ &= x - 1(x^2 + x - 2) \\ &= (x - 1)^2(x + 2) \end{aligned}$$

Now a modified ODE is obtained from the original ODE, which is exact and can be solved. The modified ODE is

$$\begin{aligned} \overline{M} + \overline{N} \frac{dy}{dx} &= 0 \\ ((3y - 1)x^2 + 2x - 1 - 3y) + ((x - 1)^2(x + 2)) \frac{dy}{dx} &= 0 \end{aligned}$$

The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = \bar{M} \quad (1)$$

$$\frac{\partial \phi}{\partial y} = \bar{N} \quad (2)$$

Integrating (1) w.r.t. x gives

$$\begin{aligned} \int \frac{\partial \phi}{\partial x} dx &= \int \bar{M} dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int (3y - 1)x^2 + 2x - 1 - 3y dx \\ \phi &= \frac{x(3x^2y - x^2 + 3x - 9y - 3)}{3} + f(y) \end{aligned} \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\begin{aligned} \frac{\partial \phi}{\partial y} &= \frac{x(3x^2 - 9)}{3} + f'(y) \\ &= x(x^2 - 3) + f'(y) \end{aligned} \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = (x - 1)^2(x + 2)$. Therefore equation (4) becomes

$$(x - 1)^2(x + 2) = x(x^2 - 3) + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 2$$

Integrating the above w.r.t y gives

$$\begin{aligned} \int f'(y) dy &= \int (2) dy \\ f(y) &= 2y + c_1 \end{aligned}$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = \frac{x(3x^2y - x^2 + 3x - 9y - 3)}{3} + 2y + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = \frac{x(3x^2y - x^2 + 3x - 9y - 3)}{3} + 2y$$

The solution becomes

$$y = \frac{x^3 - 3x^2 + 3c_1 + 3x}{3x^3 - 9x + 6}$$

Summary

The solution(s) found are the following

$$y = \frac{x^3 - 3x^2 + 3c_1 + 3x}{3x^3 - 9x + 6} \quad (1)$$

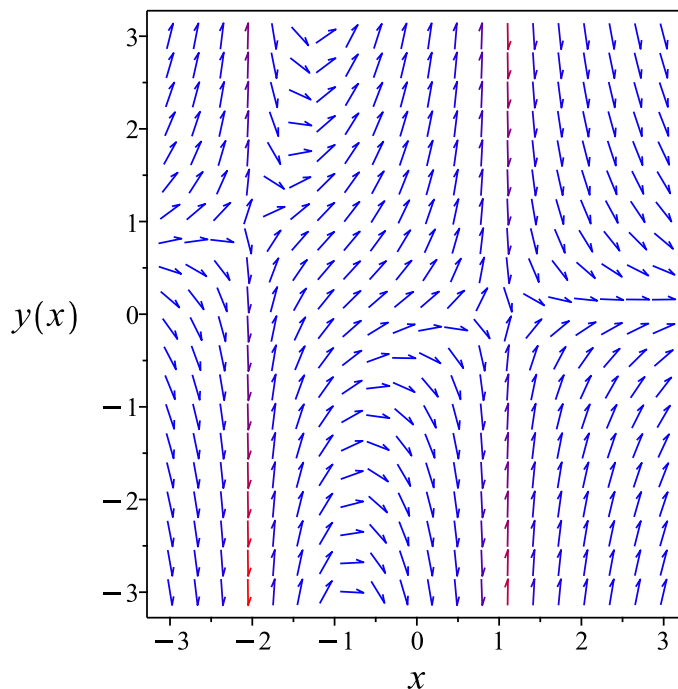


Figure 171: Slope field plot

Verification of solutions

$$y = \frac{x^3 - 3x^2 + 3c_1 + 3x}{3x^3 - 9x + 6}$$

Verified OK.

5.8.4 Maple step by step solution

Let's solve

$$(x^2 + x - 2)y' + 3y(1 + x) = x - 1$$

- Highest derivative means the order of the ODE is 1

$$y'$$

- Isolate the derivative

$$y' = -\frac{3(1+x)y}{x^2+x-2} + \frac{1}{x+2}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE

$$y' + \frac{3(1+x)y}{x^2+x-2} = \frac{1}{x+2}$$

- The ODE is linear; multiply by an integrating factor $\mu(x)$

$$\mu(x) \left(y' + \frac{3(1+x)y}{x^2+x-2} \right) = \frac{\mu(x)}{x+2}$$

- Assume the lhs of the ODE is the total derivative $\frac{d}{dx}(\mu(x)y)$

$$\mu(x) \left(y' + \frac{3(1+x)y}{x^2+x-2} \right) = \mu'(x)y + \mu(x)y'$$

- Isolate $\mu'(x)$

$$\mu'(x) = \frac{3\mu(x)(1+x)}{x^2+x-2}$$

- Solve to find the integrating factor

$$\mu(x) = (x - 1)^2 (x + 2)$$

- Integrate both sides with respect to x

$$\int \left(\frac{d}{dx}(\mu(x)y) \right) dx = \int \frac{\mu(x)}{x+2} dx + c_1$$

- Evaluate the integral on the lhs

$$\mu(x)y = \int \frac{\mu(x)}{x+2} dx + c_1$$

- Solve for y

$$y = \frac{\int \frac{\mu(x)}{x+2} dx + c_1}{\mu(x)}$$

- Substitute $\mu(x) = (x - 1)^2 (x + 2)$

$$y = \frac{\int (x-1)^2 dx + c_1}{(x-1)^2(x+2)}$$

- Evaluate the integrals on the rhs

$$y = \frac{\frac{(x-1)^3}{3} + c_1}{(x-1)^2(x+2)}$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
<- 1st order linear successful`

```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 24

```
dsolve((x^2+x-2)*diff(y(x),x)+3*(x+1)*y(x)=x-1,y(x), singsol=all)
```

$$y(x) = \frac{\frac{(-1+x)^3}{3} + c_1}{(x+2)(-1+x)^2}$$

✓ Solution by Mathematica

Time used: 0.041 (sec). Leaf size: 34

```
DSolve[(x^2+x-2)*y'[x]+3*(x+1)*y[x]==x-1,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{x^3 - 3x^2 + 3x + 3c_1}{3x^3 - 9x + 6}$$

5.9 problem 9

5.9.1	Solving as linear ode	887
5.9.2	Solving as first order ode lie symmetry lookup ode	889
5.9.3	Solving as exact ode	893
5.9.4	Maple step by step solution	897

Internal problem ID [11646]

Internal file name [OUTPUT/11655_Tuesday_April_09_2024_02_04_59_AM_70744530/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.3 (Linear equations). Exercises page 56

Problem number: 9.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"linear"**, **"exactWithIntegrationFactor"**, **"first_order_ode_lie_symmetry_lookup"**

Maple gives the following as the ode type

`[_linear]`

$$y'x + yx + y = 1$$

5.9.1 Solving as linear ode

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = -\frac{-x-1}{x}$$

$$q(x) = \frac{1}{x}$$

Hence the ode is

$$y' - \frac{(-x-1)y}{x} = \frac{1}{x}$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int -\frac{x-1}{x} dx} \\ &= e^{x+\ln(x)}\end{aligned}$$

Which simplifies to

$$\mu = x e^x$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu y) &= (\mu) \left(\frac{1}{x}\right) \\ \frac{d}{dx}(x e^x y) &= (x e^x) \left(\frac{1}{x}\right) \\ d(x e^x y) &= e^x dx\end{aligned}$$

Integrating gives

$$\begin{aligned}x e^x y &= \int e^x dx \\ x e^x y &= e^x + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = x e^x$ results in

$$y = \frac{e^{-x} e^x}{x} + \frac{c_1 e^{-x}}{x}$$

which simplifies to

$$y = \frac{c_1 e^{-x} + 1}{x}$$

Summary

The solution(s) found are the following

$$y = \frac{c_1 e^{-x} + 1}{x} \tag{1}$$

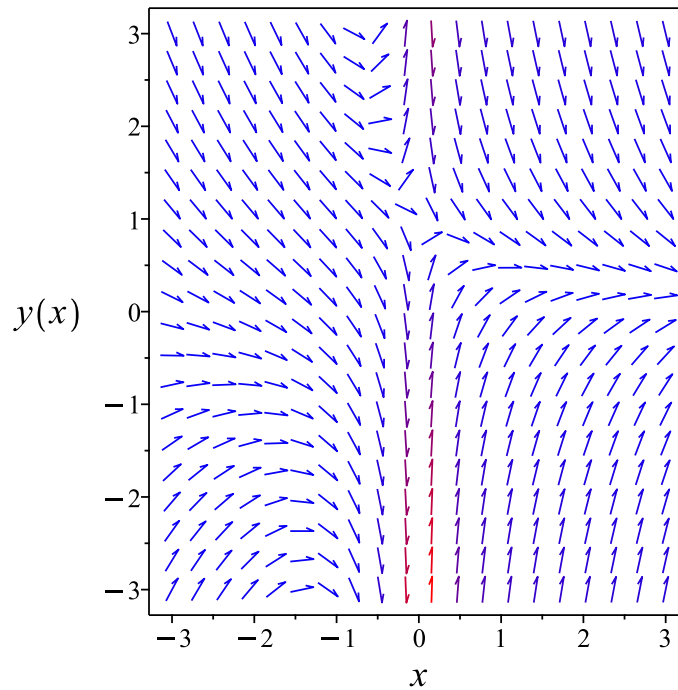


Figure 172: Slope field plot

Verification of solutions

$$y = \frac{c_1 e^{-x} + 1}{x}$$

Verified OK.

5.9.2 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = -\frac{xy + y - 1}{x}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 136: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= e^{-x-\ln(x)}\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{e^{-x-\ln(x)}} dy \end{aligned}$$

Which results in

$$S = x e^x y$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{xy + y - 1}{x}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= e^x y (1 + x) \\ S_y &= x e^x \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = e^x \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = e^R$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by

integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = e^R + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$yx e^x = e^x + c_1$$

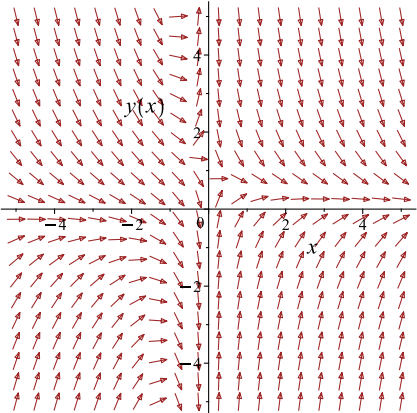
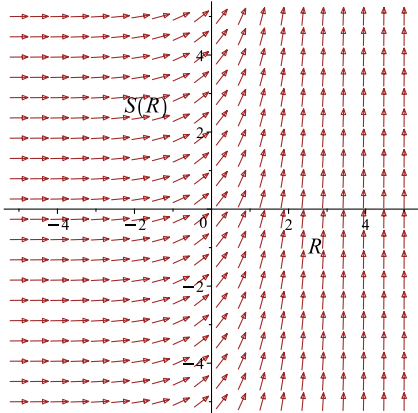
Which simplifies to

$$yx e^x = e^x + c_1$$

Which gives

$$y = \frac{(e^x + c_1) e^{-x}}{x}$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{xy+y-1}{x}$ 	$R = x$ $S = x e^x y$	$\frac{dS}{dR} = e^R$ 

Summary

The solution(s) found are the following

$$y = \frac{(e^x + c_1) e^{-x}}{x} \quad (1)$$

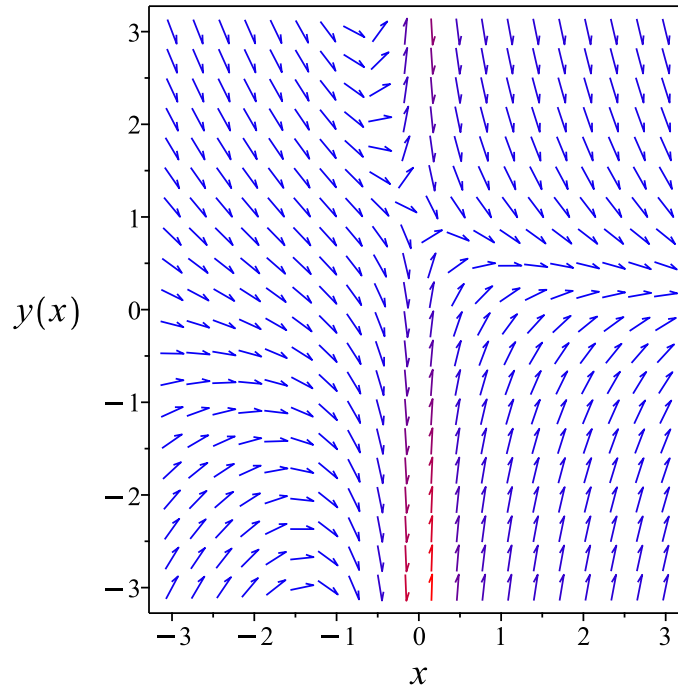


Figure 173: Slope field plot

Verification of solutions

$$y = \frac{(e^x + c_1) e^{-x}}{x}$$

Verified OK.

5.9.3 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \tag{1A}$$

Therefore

$$\begin{aligned}(x) dy &= (-xy - y + 1) dx \\ (xy + y - 1) dx + (x) dy &= 0\end{aligned} \tag{2A}$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= xy + y - 1 \\ N(x, y) &= x\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(xy + y - 1) \\ &= 1 + x\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(x) \\ &= 1\end{aligned}$$

Since $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$\begin{aligned} A &= \frac{1}{N} \left(\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} \right) \\ &= \frac{1}{x} ((1+x) - (1)) \\ &= 1 \end{aligned}$$

Since A does not depend on y , then it can be used to find an integrating factor. The integrating factor μ is

$$\begin{aligned} \mu &= e^{\int A dx} \\ &= e^{\int 1 dx} \end{aligned}$$

The result of integrating gives

$$\begin{aligned} \mu &= e^x \\ &= e^x \end{aligned}$$

M and N are multiplied by this integrating factor, giving new M and new N which are called \bar{M} and \bar{N} for now so not to confuse them with the original M and N .

$$\begin{aligned} \bar{M} &= \mu M \\ &= e^x(xy + y - 1) \\ &= e^x(xy + y - 1) \end{aligned}$$

And

$$\begin{aligned} \bar{N} &= \mu N \\ &= e^x(x) \\ &= x e^x \end{aligned}$$

Now a modified ODE is obtained from the original ODE, which is exact and can be solved. The modified ODE is

$$\begin{aligned} \bar{M} + \bar{N} \frac{dy}{dx} &= 0 \\ (e^x(xy + y - 1)) + (x e^x) \frac{dy}{dx} &= 0 \end{aligned}$$

The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = \bar{M} \tag{1}$$

$$\frac{\partial \phi}{\partial y} = \bar{N} \tag{2}$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int \overline{M} dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int e^x(xy + y - 1) dx \\ \phi &= (xy - 1)e^x + f(y)\end{aligned}\tag{3}$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = x e^x + f'(y)\tag{4}$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = x e^x$. Therefore equation (4) becomes

$$x e^x = x e^x + f'(y)\tag{5}$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 0$$

Therefore

$$f(y) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(y)$ into equation (3) gives ϕ

$$\phi = (xy - 1)e^x + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = (xy - 1)e^x$$

The solution becomes

$$y = \frac{(e^x + c_1)e^{-x}}{x}$$

Summary

The solution(s) found are the following

$$y = \frac{(e^x + c_1) e^{-x}}{x} \quad (1)$$

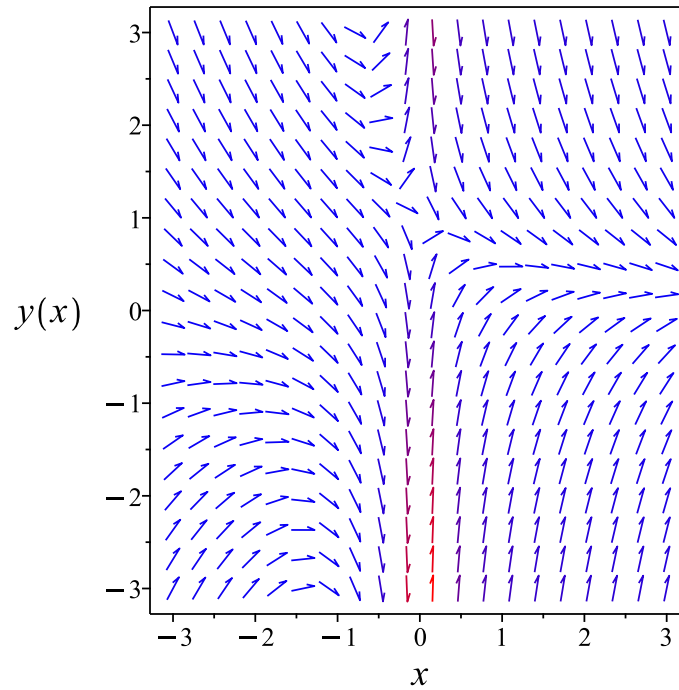


Figure 174: Slope field plot

Verification of solutions

$$y = \frac{(e^x + c_1) e^{-x}}{x}$$

Verified OK.

5.9.4 Maple step by step solution

Let's solve

$$y'x + yx + y = 1$$

- Highest derivative means the order of the ODE is 1

y'

- Isolate the derivative

$$y' = -\frac{(1+x)y}{x} + \frac{1}{x}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE

$$y' + \frac{(1+x)y}{x} = \frac{1}{x}$$

- The ODE is linear; multiply by an integrating factor $\mu(x)$

$$\mu(x) \left(y' + \frac{(1+x)y}{x} \right) = \frac{\mu(x)}{x}$$

- Assume the lhs of the ODE is the total derivative $\frac{d}{dx}(\mu(x)y)$

$$\mu(x) \left(y' + \frac{(1+x)y}{x} \right) = \mu'(x)y + \mu(x)y'$$

- Isolate $\mu'(x)$

$$\mu'(x) = \frac{\mu(x)(1+x)}{x}$$

- Solve to find the integrating factor

$$\mu(x) = x e^x$$

- Integrate both sides with respect to x

$$\int \left(\frac{d}{dx}(\mu(x)y) \right) dx = \int \frac{\mu(x)}{x} dx + c_1$$

- Evaluate the integral on the lhs

$$\mu(x)y = \int \frac{\mu(x)}{x} dx + c_1$$

- Solve for y

$$y = \frac{\int \frac{\mu(x)}{x} dx + c_1}{\mu(x)}$$

- Substitute $\mu(x) = x e^x$

$$y = \frac{\int e^x dx + c_1}{x e^x}$$

- Evaluate the integrals on the rhs

$$y = \frac{e^x + c_1}{e^x x}$$

- Simplify

$$y = \frac{c_1 e^{-x} + 1}{x}$$

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
<- 1st order linear successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 16

```
dsolve(x*diff(y(x),x)+(x*y(x)+y(x)-1)=0,y(x), singsol=all)
```

$$y(x) = \frac{c_1 e^{-x} + 1}{x}$$

✓ Solution by Mathematica

Time used: 0.028 (sec). Leaf size: 19

```
DSolve[x*y'[x]+(x*y[x]+y[x]-1)==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{1 + c_1 e^{-x}}{x}$$

5.10 problem 10

5.10.1 Solving as exact ode 900

Internal problem ID [11647]

Internal file name [OUTPUT/11656_Tuesday_April_09_2024_02_04_59_AM_24934280/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.3 (Linear equations). Exercises page 56

Problem number: 10.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"exactWithIntegrationFactor"**

Maple gives the following as the ode type

```
[_rational, [_1st_order, ` _with_symmetry_[F(x)*G(y),0] `]]
```

$$y + (y^2x + x - y)y' = 0$$

5.10.1 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (1A)$$

Therefore

$$\begin{aligned} (x y^2 + x - y) dy &= (-y) dx \\ (y) dx + (x y^2 + x - y) dy &= 0 \end{aligned} \quad (2A)$$

Comparing (1A) and (2A) shows that

$$\begin{aligned} M(x, y) &= y \\ N(x, y) &= x y^2 + x - y \end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned} \frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(y) \\ &= 1 \end{aligned}$$

And

$$\begin{aligned} \frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(x y^2 + x - y) \\ &= y^2 + 1 \end{aligned}$$

Since $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$\begin{aligned} A &= \frac{1}{N} \left(\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} \right) \\ &= \frac{1}{x y^2 + x - y} ((1) - (y^2 + 1)) \\ &= -\frac{y^2}{x y^2 + x - y} \end{aligned}$$

Since A depends on y , it can not be used to obtain an integrating factor. We will now try a second method to find an integrating factor. Let

$$\begin{aligned} B &= \frac{1}{M} \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) \\ &= \frac{1}{y} ((y^2 + 1) - (1)) \\ &= y \end{aligned}$$

Since B does not depend on x , it can be used to obtain an integrating factor. Let the integrating factor be μ . Then

$$\begin{aligned} \mu &= e^{\int B \, dy} \\ &= e^{\int y \, dy} \end{aligned}$$

The result of integrating gives

$$\begin{aligned} \mu &= e^{\frac{y^2}{2}} \\ &= e^{\frac{y^2}{2}} \end{aligned}$$

M and N are now multiplied by this integrating factor, giving new M and new N which are called \bar{M} and \bar{N} so not to confuse them with the original M and N .

$$\begin{aligned} \bar{M} &= \mu M \\ &= e^{\frac{y^2}{2}} (y) \\ &= y e^{\frac{y^2}{2}} \end{aligned}$$

And

$$\begin{aligned} \bar{N} &= \mu N \\ &= e^{\frac{y^2}{2}} (x y^2 + x - y) \\ &= (x y^2 + x - y) e^{\frac{y^2}{2}} \end{aligned}$$

So now a modified ODE is obtained from the original ODE which will be exact and can be solved using the standard method. The modified ODE is

$$\begin{aligned} \bar{M} + \bar{N} \frac{dy}{dx} &= 0 \\ \left(y e^{\frac{y^2}{2}} \right) + \left((x y^2 + x - y) e^{\frac{y^2}{2}} \right) \frac{dy}{dx} &= 0 \end{aligned}$$

The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = \overline{M} \quad (1)$$

$$\frac{\partial \phi}{\partial y} = \overline{N} \quad (2)$$

Integrating (1) w.r.t. x gives

$$\int \frac{\partial \phi}{\partial x} dx = \int \overline{M} dx$$

$$\int \frac{\partial \phi}{\partial x} dx = \int y e^{\frac{y^2}{2}} dx$$

$$\phi = y e^{\frac{y^2}{2}} x + f(y) \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = e^{\frac{y^2}{2}} x + y^2 e^{\frac{y^2}{2}} x + f'(y) \quad (4)$$

$$= e^{\frac{y^2}{2}} x (y^2 + 1) + f'(y)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = (x y^2 + x - y) e^{\frac{y^2}{2}}$. Therefore equation (4) becomes

$$(x y^2 + x - y) e^{\frac{y^2}{2}} = e^{\frac{y^2}{2}} x (y^2 + 1) + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = -y e^{\frac{y^2}{2}}$$

Integrating the above w.r.t y gives

$$\int f'(y) dy = \int \left(-y e^{\frac{y^2}{2}} \right) dy$$

$$f(y) = -e^{\frac{y^2}{2}} + c_1$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = y e^{\frac{y^2}{2}} x - e^{\frac{y^2}{2}} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = y e^{\frac{y^2}{2}} x - e^{\frac{y^2}{2}}$$

Summary

The solution(s) found are the following

$$y e^{\frac{y^2}{2}} x - e^{\frac{y^2}{2}} = c_1 \tag{1}$$

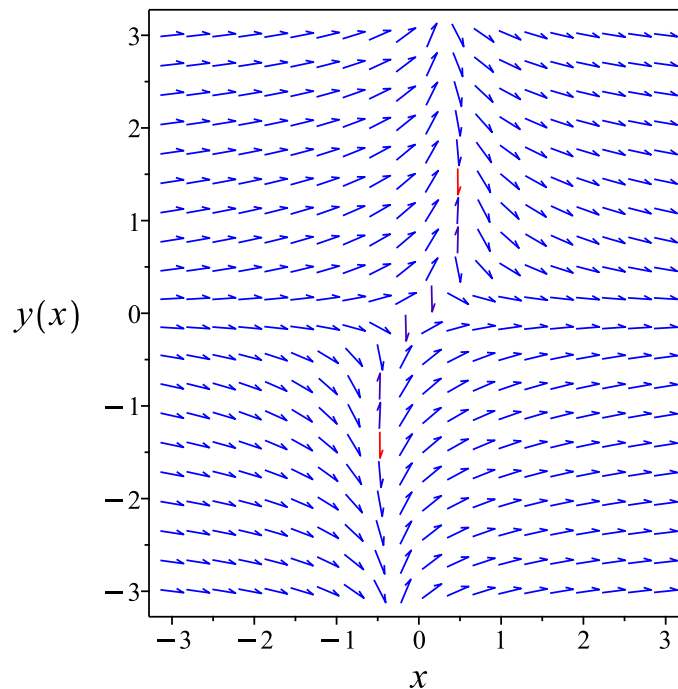


Figure 175: Slope field plot

Verification of solutions

$$y e^{\frac{y^2}{2}} x - e^{\frac{y^2}{2}} = c_1$$

Verified OK.

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
trying Bernoulli  
trying separable  
trying inverse linear  
<- 1st order linear successful  
<- inverse linear successful`
```

✓ Solution by Maple

Time used: 0.031 (sec). Leaf size: 35

```
dsolve(y(x)+(x*y(x)^2+x-y(x))*diff(y(x),x)=0,y(x), singsol=all)
```

$$y(x) = \frac{e^{\text{RootOf}(c_1^2 e^{2-Z} + 2x^2 - Z + 2c_1 e^{-Z} + 1)} c_1 + 1}{x}$$

✓ Solution by Mathematica

Time used: 0.206 (sec). Leaf size: 27

```
DSolve[y[x]+(x*y[x]^2+x-y[x])*y'[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$\text{Solve} \left[x = \frac{1}{y(x)} + \frac{c_1 e^{-\frac{1}{2}y(x)^2}}{y(x)}, y(x) \right]$$

5.11 problem 11

5.11.1 Solving as linear ode	906
5.11.2 Solving as first order ode lie symmetry lookup ode	908
5.11.3 Solving as exact ode	912
5.11.4 Maple step by step solution	916

Internal problem ID [11648]

Internal file name [OUTPUT/11657_Tuesday_April_09_2024_02_05_00_AM_74603805/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.3 (Linear equations). Exercises page 56

Problem number: 11.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**linear**", "**exactWithIntegrationFactor**", "**first_order_ode_lie_symmetry_lookup**"

Maple gives the following as the ode type

[_linear]

$$r' + r \tan(t) = \cos(t)$$

5.11.1 Solving as linear ode

Entering Linear first order ODE solver. In canonical form a linear first order is

$$r' + p(t)r = q(t)$$

Where here

$$p(t) = \tan(t)$$

$$q(t) = \cos(t)$$

Hence the ode is

$$r' + r \tan(t) = \cos(t)$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int \tan(t) dt} \\ &= \frac{1}{\cos(t)}\end{aligned}$$

Which simplifies to

$$\mu = \sec(t)$$

The ode becomes

$$\begin{aligned}\frac{d}{dt}(\mu r) &= (\mu) (\cos(t)) \\ \frac{d}{dt}(\sec(t) r) &= (\sec(t)) (\cos(t)) \\ d(\sec(t) r) &= dt\end{aligned}$$

Integrating gives

$$\begin{aligned}\sec(t) r &= \int dt \\ \sec(t) r &= t + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = \sec(t)$ results in

$$r = \cos(t) t + c_1 \cos(t)$$

which simplifies to

$$r = \cos(t) (t + c_1)$$

Summary

The solution(s) found are the following

$$r = \cos(t) (t + c_1) \tag{1}$$

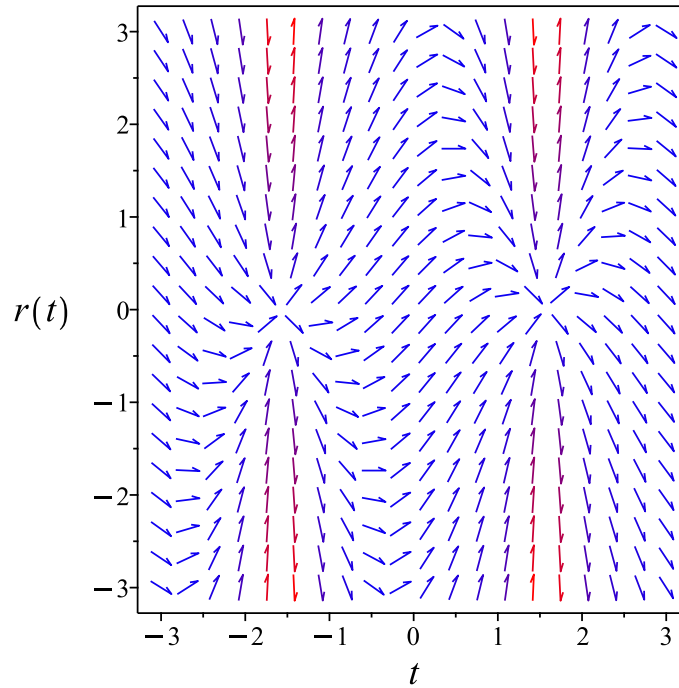


Figure 176: Slope field plot

Verification of solutions

$$r = \cos(t)(t + c_1)$$

Verified OK.

5.11.2 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$r' = -r \tan(t) + \cos(t)$$

$$r' = \omega(t, r)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_t + \omega(\eta_r - \xi_t) - \omega^2 \xi_r - \omega_t \xi - \omega_r \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 139: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(t, r) &= 0 \\ \eta(t, r) &= \cos(t)\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(t, r) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dt}{\xi} = \frac{dr}{\eta} = dS\tag{1}$$

The above comes from the requirements that $(\xi \frac{\partial}{\partial t} + \eta \frac{\partial}{\partial r})S(t, r) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = t$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\cos(t)} dy \end{aligned}$$

Which results in

$$S = \frac{r}{\cos(t)}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_t + \omega(t, r)S_r}{R_t + \omega(t, r)R_r} \quad (2)$$

Where in the above R_t, R_r, S_t, S_r are all partial derivatives and $\omega(t, r)$ is the right hand side of the original ode given by

$$\omega(t, r) = -r \tan(t) + \cos(t)$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_t &= 1 \\ R_r &= 0 \\ S_t &= \tan(t) \sec(t) r \\ S_r &= \sec(t) \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 1 \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for t, r in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 1$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by

integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = R + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to t, r coordinates. This results in

$$\sec(t) r = t + c_1$$

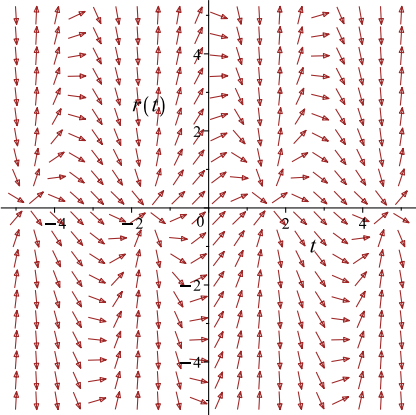
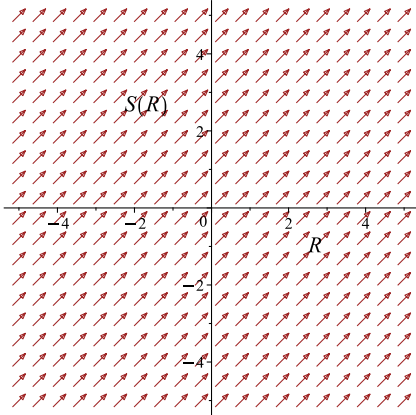
Which simplifies to

$$\sec(t) r = t + c_1$$

Which gives

$$r = \frac{t + c_1}{\sec(t)}$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in t, r coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dr}{dt} = -r \tan(t) + \cos(t)$ 	$R = t$ $S = \sec(t) r$	$\frac{dS}{dR} = 1$ 

Summary

The solution(s) found are the following

$$r = \frac{t + c_1}{\sec(t)} \quad (1)$$

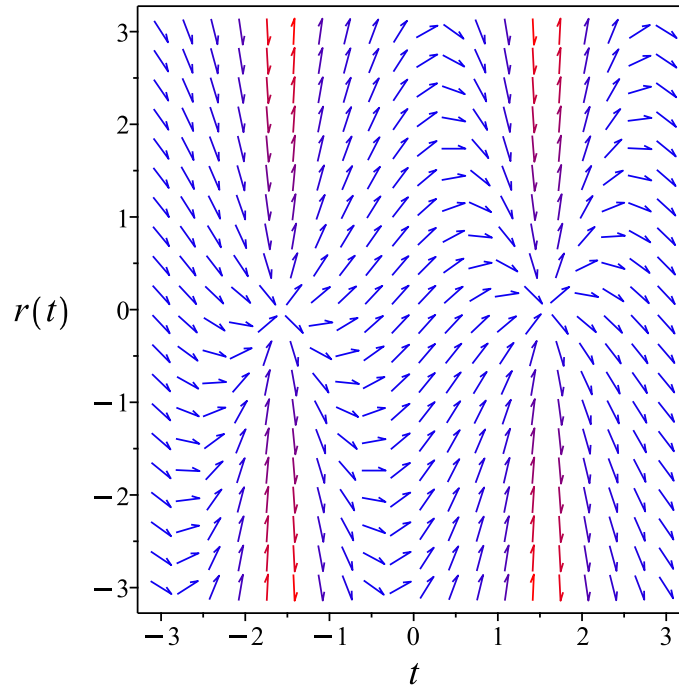


Figure 177: Slope field plot

Verification of solutions

$$r = \frac{t + c_1}{\sec(t)}$$

Verified OK.

5.11.3 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(t, r) dt + N(t, r) dr = 0 \tag{1A}$$

Therefore

$$\begin{aligned}dr &= (-r \tan(t) + \cos(t)) dt \\ (r \tan(t) - \cos(t)) dt + dr &= 0\end{aligned} \tag{2A}$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(t, r) &= r \tan(t) - \cos(t) \\ N(t, r) &= 1\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial r} = \frac{\partial N}{\partial t}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial r} &= \frac{\partial}{\partial r}(r \tan(t) - \cos(t)) \\ &= \tan(t)\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial t} &= \frac{\partial}{\partial t}(1) \\ &= 0\end{aligned}$$

Since $\frac{\partial M}{\partial r} \neq \frac{\partial N}{\partial t}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$\begin{aligned} A &= \frac{1}{N} \left(\frac{\partial M}{\partial r} - \frac{\partial N}{\partial t} \right) \\ &= 1((\tan(t)) - (0)) \\ &= \tan(t) \end{aligned}$$

Since A does not depend on r , then it can be used to find an integrating factor. The integrating factor μ is

$$\begin{aligned} \mu &= e^{\int A dt} \\ &= e^{\int \tan(t) dt} \end{aligned}$$

The result of integrating gives

$$\begin{aligned} \mu &= e^{-\ln(\cos(t))} \\ &= \sec(t) \end{aligned}$$

M and N are multiplied by this integrating factor, giving new M and new N which are called \bar{M} and \bar{N} for now so not to confuse them with the original M and N .

$$\begin{aligned} \bar{M} &= \mu M \\ &= \sec(t) (r \tan(t) - \cos(t)) \\ &= -1 + \tan(t) \sec(t) r \end{aligned}$$

And

$$\begin{aligned} \bar{N} &= \mu N \\ &= \sec(t) (1) \\ &= \sec(t) \end{aligned}$$

Now a modified ODE is obtained from the original ODE, which is exact and can be solved. The modified ODE is

$$\begin{aligned} \bar{M} + \bar{N} \frac{dr}{dt} &= 0 \\ (-1 + \tan(t) \sec(t) r) + (\sec(t)) \frac{dr}{dt} &= 0 \end{aligned}$$

The following equations are now set up to solve for the function $\phi(t, r)$

$$\frac{\partial \phi}{\partial t} = \bar{M} \tag{1}$$

$$\frac{\partial \phi}{\partial r} = \bar{N} \tag{2}$$

Integrating (1) w.r.t. t gives

$$\int \frac{\partial \phi}{\partial t} dt = \int \overline{M} dt$$

$$\int \frac{\partial \phi}{\partial t} dt = \int -1 + \tan(t) \sec(t) r dt$$

$$\phi = -t + \sec(t) r + f(r) \quad (3)$$

Where $f(r)$ is used for the constant of integration since ϕ is a function of both t and r . Taking derivative of equation (3) w.r.t r gives

$$\frac{\partial \phi}{\partial r} = \sec(t) + f'(r) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial r} = \sec(t)$. Therefore equation (4) becomes

$$\sec(t) = \sec(t) + f'(r) \quad (5)$$

Solving equation (5) for $f'(r)$ gives

$$f'(r) = 0$$

Therefore

$$f(r) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(r)$ into equation (3) gives ϕ

$$\phi = -t + \sec(t) r + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -t + \sec(t) r$$

The solution becomes

$$r = \frac{t + c_1}{\sec(t)}$$

Summary

The solution(s) found are the following

$$r = \frac{t + c_1}{\sec(t)} \quad (1)$$

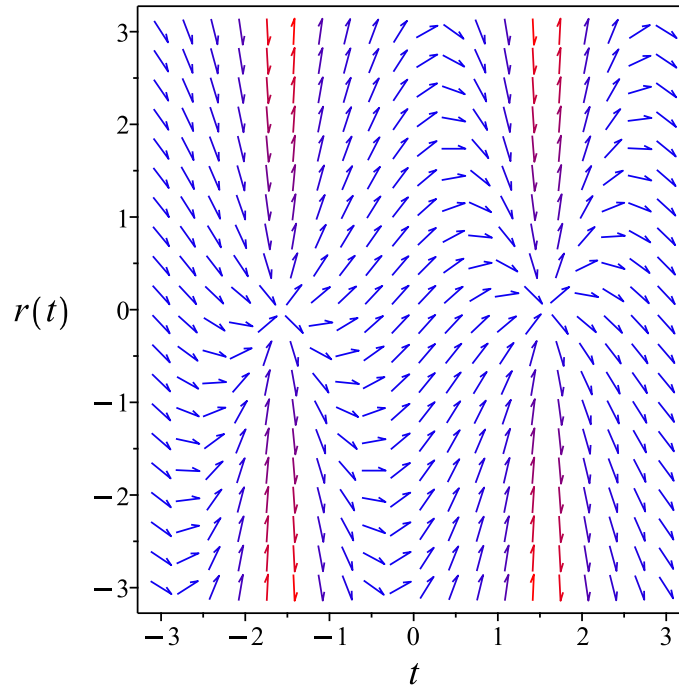


Figure 178: Slope field plot

Verification of solutions

$$r = \frac{t + c_1}{\sec(t)}$$

Verified OK.

5.11.4 Maple step by step solution

Let's solve

$$r' + r \tan(t) = \cos(t)$$

- Highest derivative means the order of the ODE is 1

$$r'$$

- Isolate the derivative

$$r' = -r \tan(t) + \cos(t)$$

- Group terms with r on the lhs of the ODE and the rest on the rhs of the ODE

$$r' + r \tan(t) = \cos(t)$$

- The ODE is linear; multiply by an integrating factor $\mu(t)$

$$\mu(t) (r' + r \tan(t)) = \mu(t) \cos(t)$$

- Assume the lhs of the ODE is the total derivative $\frac{d}{dt}(\mu(t) r)$

$$\mu(t) (r' + r \tan(t)) = \mu'(t) r + \mu(t) r'$$

- Isolate $\mu'(t)$

$$\mu'(t) = \mu(t) \tan(t)$$

- Solve to find the integrating factor

$$\mu(t) = \frac{1}{\cos(t)}$$

- Integrate both sides with respect to t

$$\int \left(\frac{d}{dt}(\mu(t) r) \right) dt = \int \mu(t) \cos(t) dt + c_1$$

- Evaluate the integral on the lhs

$$\mu(t) r = \int \mu(t) \cos(t) dt + c_1$$

- Solve for r

$$r = \frac{\int \mu(t) \cos(t) dt + c_1}{\mu(t)}$$

- Substitute $\mu(t) = \frac{1}{\cos(t)}$

$$r = \cos(t) \left(\int 1 dt + c_1 \right)$$

- Evaluate the integrals on the rhs

$$r = \cos(t) (t + c_1)$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
<- 1st order linear successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 10

```
dsolve(diff(r(t),t)+r(t)*tan(t)=cos(t),r(t), singsol=all)
```

$$r(t) = (t + c_1) \cos(t)$$

✓ Solution by Mathematica

Time used: 0.06 (sec). Leaf size: 12

```
DSolve[r'[t]+r[t]*Tan[t]==Cos[t],r[t],t,IncludeSingularSolutions -> True]
```

$$r(t) \rightarrow (t + c_1) \cos(t)$$

5.12 problem 12

5.12.1 Solving as linear ode	919
5.12.2 Solving as first order ode lie symmetry lookup ode	921
5.12.3 Solving as exact ode	925
5.12.4 Maple step by step solution	930

Internal problem ID [11649]

Internal file name [OUTPUT/11658_Tuesday_April_09_2024_02_05_01_AM_43799744/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.3 (Linear equations). Exercises page 56

Problem number: 12.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"linear", "exactWithIntegrationFactor", "first_order_ode_lie_symmetry_lookup"**

Maple gives the following as the ode type

`[_linear]`

$$\cos(t)r' + r \sin(t) = \cos(t)^4$$

5.12.1 Solving as linear ode

Entering Linear first order ODE solver. In canonical form a linear first order is

$$r' + p(t)r = q(t)$$

Where here

$$p(t) = \tan(t)$$

$$q(t) = \cos(t)^3$$

Hence the ode is

$$r' + r \tan(t) = \cos(t)^3$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int \tan(t) dt} \\ &= \frac{1}{\cos(t)}\end{aligned}$$

Which simplifies to

$$\mu = \sec(t)$$

The ode becomes

$$\begin{aligned}\frac{d}{dt}(\mu r) &= (\mu) (\cos(t)^3) \\ \frac{d}{dt}(\sec(t) r) &= (\sec(t)) (\cos(t)^3) \\ d(\sec(t) r) &= \cos(t)^2 dt\end{aligned}$$

Integrating gives

$$\begin{aligned}\sec(t) r &= \int \cos(t)^2 dt \\ \sec(t) r &= \frac{\cos(t) \sin(t)}{2} + \frac{t}{2} + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = \sec(t)$ results in

$$r = \cos(t) \left(\frac{\cos(t) \sin(t)}{2} + \frac{t}{2} \right) + c_1 \cos(t)$$

which simplifies to

$$r = \frac{\cos(t) (\cos(t) \sin(t) + 2c_1 + t)}{2}$$

Summary

The solution(s) found are the following

$$r = \frac{\cos(t) (\cos(t) \sin(t) + 2c_1 + t)}{2} \tag{1}$$

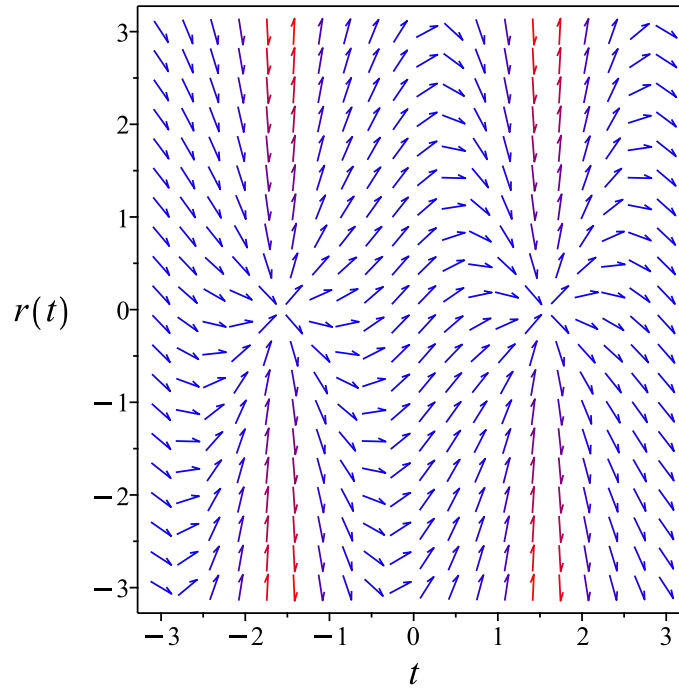


Figure 179: Slope field plot

Verification of solutions

$$r = \frac{\cos(t) (\cos(t) \sin(t) + 2c_1 + t)}{2}$$

Verified OK.

5.12.2 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$r' = \frac{-r \sin(t) + \cos(t)^4}{\cos(t)}$$

$$r' = \omega(t, r)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_t + \omega(\eta_r - \xi_t) - \omega^2 \xi_r - \omega_t \xi - \omega_r \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 142: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(t, r) &= 0 \\ \eta(t, r) &= \cos(t)\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(t, r) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dt}{\xi} = \frac{dr}{\eta} = dS\tag{1}$$

The above comes from the requirements that $(\xi \frac{\partial}{\partial t} + \eta \frac{\partial}{\partial r})S(t, r) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = t$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\cos(t)} dy \end{aligned}$$

Which results in

$$S = \frac{r}{\cos(t)}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_t + \omega(t, r)S_r}{R_t + \omega(t, r)R_r} \quad (2)$$

Where in the above R_t, R_r, S_t, S_r are all partial derivatives and $\omega(t, r)$ is the right hand side of the original ode given by

$$\omega(t, r) = \frac{-r \sin(t) + \cos(t)^4}{\cos(t)}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_t &= 1 \\ R_r &= 0 \\ S_t &= \tan(t) \sec(t) r \\ S_r &= \sec(t) \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = \cos(t)^2 \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for t, r in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = \cos(R)^2$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = \frac{R}{2} + c_1 + \frac{\sin(2R)}{4} \quad (4)$$

To complete the solution, we just need to transform (4) back to t, r coordinates. This results in

$$\sec(t) r = \frac{t}{2} + c_1 + \frac{\sin(2t)}{4}$$

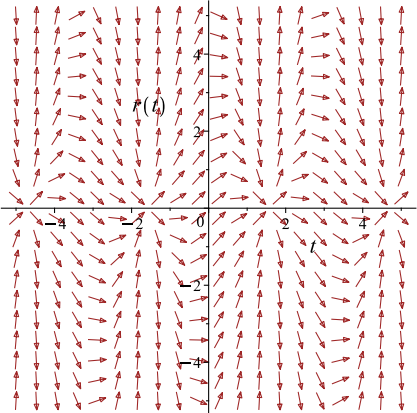
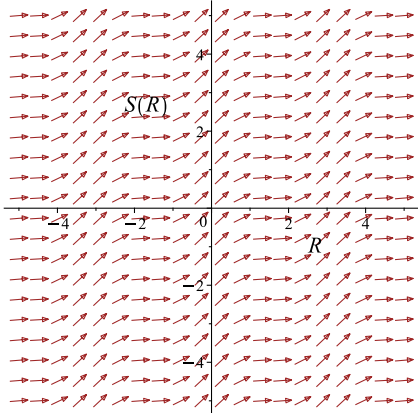
Which simplifies to

$$\sec(t) r = \frac{t}{2} + c_1 + \frac{\sin(2t)}{4}$$

Which gives

$$r = \frac{4c_1 + 2t + \sin(2t)}{4 \sec(t)}$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in t, r coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dr}{dt} = \frac{-r \sin(t) + \cos(t)^4}{\cos(t)}$ 	$R = t$ $S = \sec(t) r$	$\frac{dS}{dR} = \cos(R)^2$ 

Summary

The solution(s) found are the following

$$r = \frac{4c_1 + 2t + \sin(2t)}{4 \sec(t)} \quad (1)$$

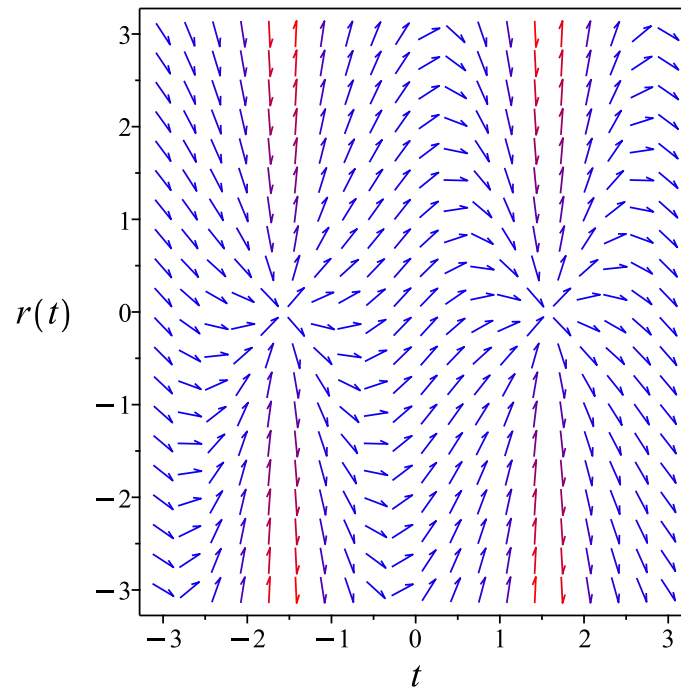


Figure 180: Slope field plot

Verification of solutions

$$r = \frac{4c_1 + 2t + \sin(2t)}{4 \sec(t)}$$

Verified OK.

5.12.3 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \quad (A)$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the

ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx}\phi(x, y) = 0$$

Hence

$$\frac{\partial\phi}{\partial x} + \frac{\partial\phi}{\partial y} \frac{dy}{dx} = 0 \quad (\text{B})$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial\phi}{\partial x} &= M \\ \frac{\partial\phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(t, r) dt + N(t, r) dr = 0 \quad (\text{1A})$$

Therefore

$$\begin{aligned} (\cos(t)) dr &= (-r \sin(t) + \cos(t)^4) dt \\ (r \sin(t) - \cos(t)^4) dt &+ (\cos(t)) dr = 0 \end{aligned} \quad (\text{2A})$$

Comparing (1A) and (2A) shows that

$$\begin{aligned} M(t, r) &= r \sin(t) - \cos(t)^4 \\ N(t, r) &= \cos(t) \end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial r} = \frac{\partial N}{\partial t}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial r} &= \frac{\partial}{\partial r}(r \sin(t) - \cos(t)^4) \\ &= \sin(t)\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial t} &= \frac{\partial}{\partial t}(\cos(t)) \\ &= -\sin(t)\end{aligned}$$

Since $\frac{\partial M}{\partial r} \neq \frac{\partial N}{\partial t}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$\begin{aligned}A &= \frac{1}{N} \left(\frac{\partial M}{\partial r} - \frac{\partial N}{\partial t} \right) \\ &= \sec(t) ((\sin(t)) - (-\sin(t))) \\ &= 2 \tan(t)\end{aligned}$$

Since A does not depend on r , then it can be used to find an integrating factor. The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int A dt} \\ &= e^{\int 2 \tan(t) dt}\end{aligned}$$

The result of integrating gives

$$\begin{aligned}\mu &= e^{-2 \ln(\cos(t))} \\ &= \sec(t)^2\end{aligned}$$

M and N are multiplied by this integrating factor, giving new M and new N which are called \bar{M} and \bar{N} for now so not to confuse them with the original M and N .

$$\begin{aligned}\bar{M} &= \mu M \\ &= \sec(t)^2 (r \sin(t) - \cos(t)^4) \\ &= \tan(t) \sec(t) r - \cos(t)^2\end{aligned}$$

And

$$\begin{aligned}\bar{N} &= \mu N \\ &= \sec(t)^2 (\cos(t)) \\ &= \sec(t)\end{aligned}$$

Now a modified ODE is obtained from the original ODE, which is exact and can be solved. The modified ODE is

$$\begin{aligned} \overline{M} + \overline{N} \frac{dr}{dt} &= 0 \\ (\tan(t) \sec(t) r - \cos(t)^2) + (\sec(t)) \frac{dr}{dt} &= 0 \end{aligned}$$

The following equations are now set up to solve for the function $\phi(t, r)$

$$\frac{\partial \phi}{\partial t} = \overline{M} \quad (1)$$

$$\frac{\partial \phi}{\partial r} = \overline{N} \quad (2)$$

Integrating (1) w.r.t. t gives

$$\begin{aligned} \int \frac{\partial \phi}{\partial t} dt &= \int \overline{M} dt \\ \int \frac{\partial \phi}{\partial t} dt &= \int \tan(t) \sec(t) r - \cos(t)^2 dt \\ \phi &= \sec(t) r - \frac{\cos(t) \sin(t)}{2} - \frac{t}{2} + f(r) \end{aligned} \quad (3)$$

Where $f(r)$ is used for the constant of integration since ϕ is a function of both t and r . Taking derivative of equation (3) w.r.t r gives

$$\frac{\partial \phi}{\partial r} = \sec(t) + f'(r) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial r} = \sec(t)$. Therefore equation (4) becomes

$$\sec(t) = \sec(t) + f'(r) \quad (5)$$

Solving equation (5) for $f'(r)$ gives

$$f'(r) = 0$$

Therefore

$$f(r) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(r)$ into equation (3) gives ϕ

$$\phi = \sec(t) r - \frac{\cos(t) \sin(t)}{2} - \frac{t}{2} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = \sec(t) r - \frac{\cos(t) \sin(t)}{2} - \frac{t}{2}$$

The solution becomes

$$r = \frac{\cos(t) \sin(t) + 2c_1 + t}{2 \sec(t)}$$

Summary

The solution(s) found are the following

$$r = \frac{\cos(t) \sin(t) + 2c_1 + t}{2 \sec(t)} \quad (1)$$

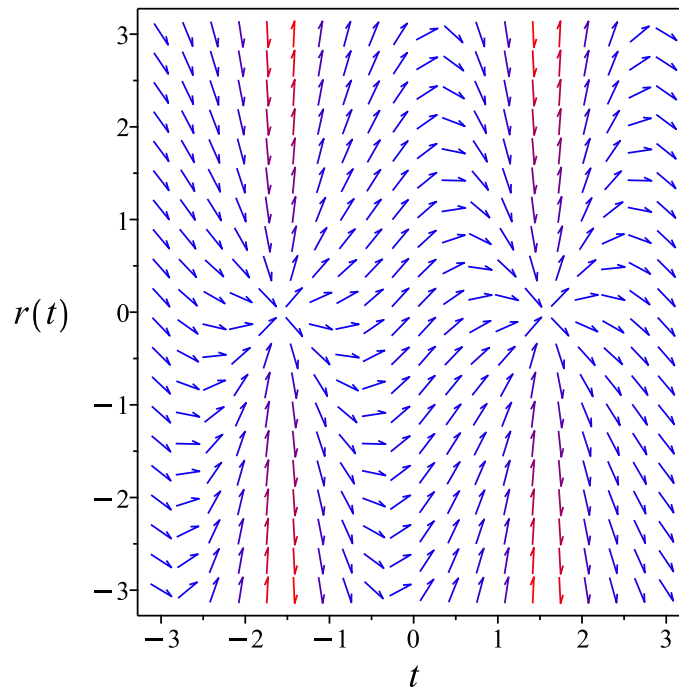


Figure 181: Slope field plot

Verification of solutions

$$r = \frac{\cos(t) \sin(t) + 2c_1 + t}{2 \sec(t)}$$

Verified OK.

5.12.4 Maple step by step solution

Let's solve

$$\cos(t) r' + r \sin(t) = \cos(t)^4$$

- Highest derivative means the order of the ODE is 1

$$r'$$

- Isolate the derivative

$$r' = -\frac{\sin(t)r}{\cos(t)} + \cos(t)^3$$

- Group terms with r on the lhs of the ODE and the rest on the rhs of the ODE

$$r' + \frac{\sin(t)r}{\cos(t)} = \cos(t)^3$$

- The ODE is linear; multiply by an integrating factor $\mu(t)$

$$\mu(t) \left(r' + \frac{\sin(t)r}{\cos(t)} \right) = \mu(t) \cos(t)^3$$

- Assume the lhs of the ODE is the total derivative $\frac{d}{dt}(\mu(t)r)$

$$\mu(t) \left(r' + \frac{\sin(t)r}{\cos(t)} \right) = \mu'(t)r + \mu(t)r'$$

- Isolate $\mu'(t)$

$$\mu'(t) = \frac{\mu(t) \sin(t)}{\cos(t)}$$

- Solve to find the integrating factor

$$\mu(t) = \frac{1}{\cos(t)}$$

- Integrate both sides with respect to t

$$\int \left(\frac{d}{dt}(\mu(t)r) \right) dt = \int \mu(t) \cos(t)^3 dt + c_1$$

- Evaluate the integral on the lhs

$$\mu(t)r = \int \mu(t) \cos(t)^3 dt + c_1$$

- Solve for r

$$r = \frac{\int \mu(t) \cos(t)^3 dt + c_1}{\mu(t)}$$

- Substitute $\mu(t) = \frac{1}{\cos(t)}$

$$r = \cos(t) \left(\int \cos(t)^2 dt + c_1 \right)$$
- Evaluate the integrals on the rhs

$$r = \cos(t) \left(\frac{\cos(t)\sin(t)}{2} + \frac{t}{2} + c_1 \right)$$
- Simplify

$$r = \frac{\cos(t)(\cos(t)\sin(t)+2c_1+t)}{2}$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
<- 1st order linear successful`

```

✓ Solution by Maple
 Time used: 0.0 (sec). Leaf size: 19

```

dsolve(cos(t)*diff(r(t),t)+(r(t)*sin(t)-cos(t)^4)=0,r(t), singsol=all)

```

$$r(t) = \frac{(2t + \sin(2t) + 4c_1) \cos(t)}{4}$$

✓ Solution by Mathematica
 Time used: 0.052 (sec). Leaf size: 22

```

DSolve[Cos[t]*r'[t]+(r[t]*Sin[t]-Cos[t]^4)==0,r[t],t,IncludeSingularSolutions -> True]

```

$$r(t) \rightarrow \frac{1}{2} \cos(t)(t + \sin(t) \cos(t) + 2c_1)$$

5.13 problem 13

5.13.1 Solving as linear ode	932
5.13.2 Solving as first order ode lie symmetry lookup ode	934
5.13.3 Solving as exact ode	938
5.13.4 Maple step by step solution	942

Internal problem ID [11650]

Internal file name [OUTPUT/11659_Tuesday_April_09_2024_02_05_03_AM_81013467/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.3 (Linear equations). Exercises page 56

Problem number: 13.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact", "linear", "first_order_ode_lie_symmetry_lookup"

Maple gives the following as the ode type

`[_linear]`

$$-y \cos(x) - (1 + \sin(x))y' = -\cos(x)^2$$

5.13.1 Solving as linear ode

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = \frac{\cos(x)}{1 + \sin(x)}$$

$$q(x) = -\sin(x) + 1$$

Hence the ode is

$$y' + \frac{\cos(x)y}{1 + \sin(x)} = -\sin(x) + 1$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int \frac{\cos(x)}{1+\sin(x)} dx} \\ &= 1 + \sin(x)\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu y) &= (\mu)(-\sin(x) + 1) \\ \frac{d}{dx}((1 + \sin(x))y) &= (1 + \sin(x))(-\sin(x) + 1) \\ d((1 + \sin(x))y) &= \cos(x)^2 dx\end{aligned}$$

Integrating gives

$$\begin{aligned}(1 + \sin(x))y &= \int \cos(x)^2 dx \\ (1 + \sin(x))y &= \frac{\cos(x)\sin(x)}{2} + \frac{x}{2} + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = 1 + \sin(x)$ results in

$$y = \frac{\frac{\cos(x)\sin(x)}{2} + \frac{x}{2}}{1 + \sin(x)} + \frac{c_1}{1 + \sin(x)}$$

which simplifies to

$$y = \frac{\cos(x)\sin(x) + 2c_1 + x}{2 + 2\sin(x)}$$

Summary

The solution(s) found are the following

$$y = \frac{\cos(x)\sin(x) + 2c_1 + x}{2 + 2\sin(x)} \quad (1)$$

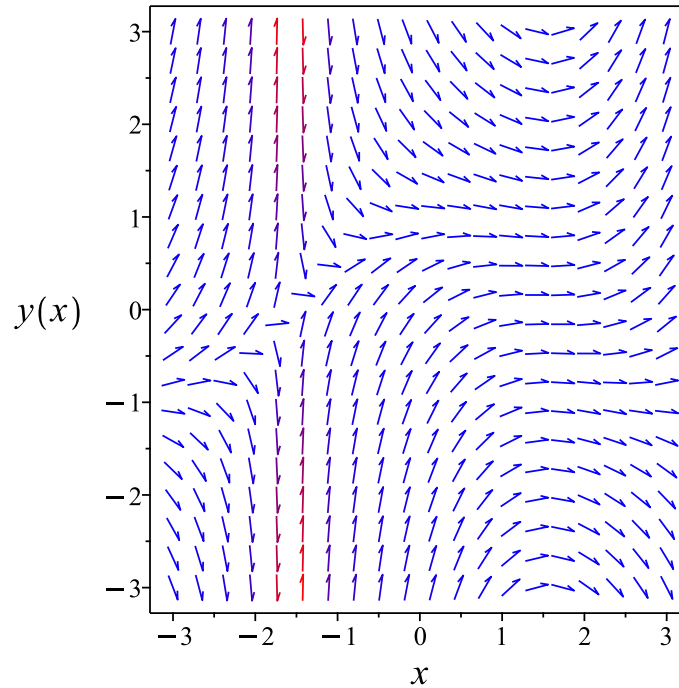


Figure 182: Slope field plot

Verification of solutions

$$y = \frac{\cos(x) \sin(x) + 2c_1 + x}{2 + 2 \sin(x)}$$

Verified OK.

5.13.2 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = \frac{\cos(x) (\cos(x) - y)}{1 + \sin(x)}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 145: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int(n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned} \xi(x, y) &= 0 \\ \eta(x, y) &= \frac{1}{1 + \sin(x)} \end{aligned} \tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{1}{1+\sin(x)}} dy \end{aligned}$$

Which results in

$$S = (1 + \sin(x)) y$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = \frac{\cos(x)(\cos(x) - y)}{1 + \sin(x)}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= \cos(x) y \\ S_y &= 1 + \sin(x) \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = \cos(x)^2 \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = \cos(R)^2$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = \frac{R}{2} + c_1 + \frac{\sin(2R)}{4} \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$(1 + \sin(x))y = \frac{x}{2} + c_1 + \frac{\sin(2x)}{4}$$

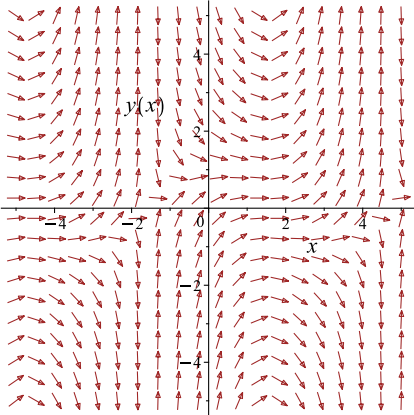
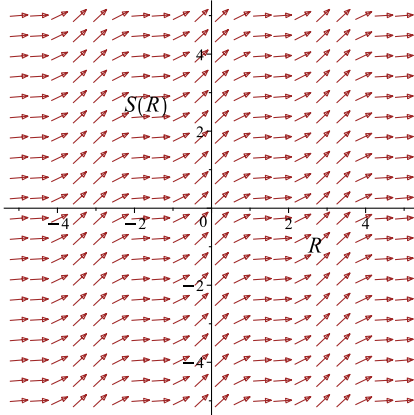
Which simplifies to

$$(1 + \sin(x))y = \frac{x}{2} + c_1 + \frac{\sin(2x)}{4}$$

Which gives

$$y = \frac{4c_1 + 2x + \sin(2x)}{4 + 4\sin(x)}$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = \frac{\cos(x)(\cos(x)-y)}{1+\sin(x)}$ 	$R = x$ $S = (1 + \sin(x))y$	$\frac{dS}{dR} = \cos(R)^2$ 

Summary

The solution(s) found are the following

$$y = \frac{4c_1 + 2x + \sin(2x)}{4 + 4 \sin(x)} \quad (1)$$

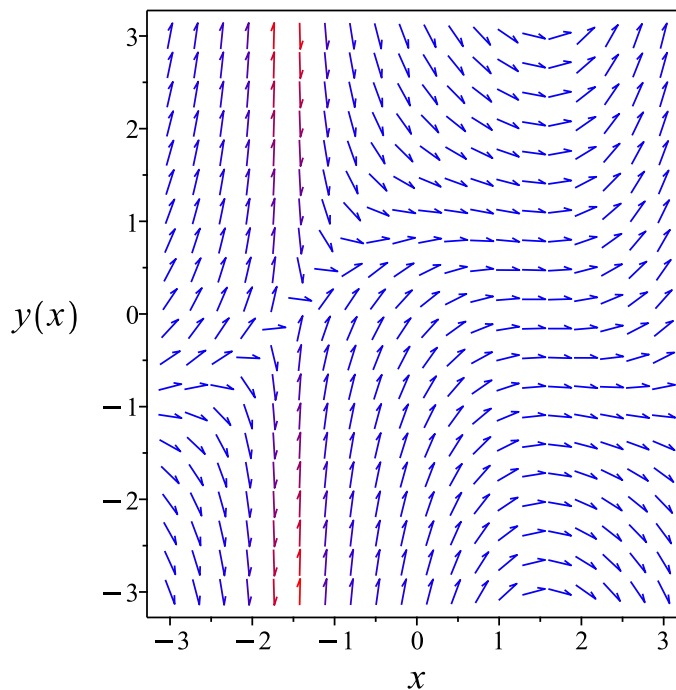


Figure 183: Slope field plot

Verification of solutions

$$y = \frac{4c_1 + 2x + \sin(2x)}{4 + 4 \sin(x)}$$

Verified OK.

5.13.3 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \quad (A)$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the

ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx}\phi(x, y) = 0$$

Hence

$$\frac{\partial\phi}{\partial x} + \frac{\partial\phi}{\partial y} \frac{dy}{dx} = 0 \quad (\text{B})$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial\phi}{\partial x} &= M \\ \frac{\partial\phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (\text{1A})$$

Therefore

$$\begin{aligned} (-1 - \sin(x)) dy &= (-\cos(x)^2 + \cos(x)y) dx \\ (\cos(x)^2 - \cos(x)y) dx &+ (-1 - \sin(x)) dy = 0 \end{aligned} \quad (\text{2A})$$

Comparing (1A) and (2A) shows that

$$\begin{aligned} M(x, y) &= \cos(x)^2 - \cos(x)y \\ N(x, y) &= -1 - \sin(x) \end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y} (\cos(x)^2 - \cos(x)y) \\ &= -\cos(x)\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x} (-1 - \sin(x)) \\ &= -\cos(x)\end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \tag{1}$$

$$\frac{\partial \phi}{\partial y} = N \tag{2}$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int M dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int \cos(x)^2 - \cos(x)y dx \\ \phi &= \frac{\sin(x)(\cos(x) - 2y)}{2} + \frac{x}{2} + f(y)\end{aligned} \tag{3}$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = -\sin(x) + f'(y) \tag{4}$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = -1 - \sin(x)$. Therefore equation (4) becomes

$$-1 - \sin(x) = -\sin(x) + f'(y) \tag{5}$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = -1$$

Integrating the above w.r.t y gives

$$\int f'(y) dy = \int (-1) dy$$
$$f(y) = -y + c_1$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = \frac{\sin(x)(\cos(x) - 2y)}{2} + \frac{x}{2} - y + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = \frac{\sin(x)(\cos(x) - 2y)}{2} + \frac{x}{2} - y$$

The solution becomes

$$y = \frac{\cos(x)\sin(x) - 2c_1 + x}{2 + 2\sin(x)}$$

Summary

The solution(s) found are the following

$$y = \frac{\cos(x)\sin(x) - 2c_1 + x}{2 + 2\sin(x)} \quad (1)$$

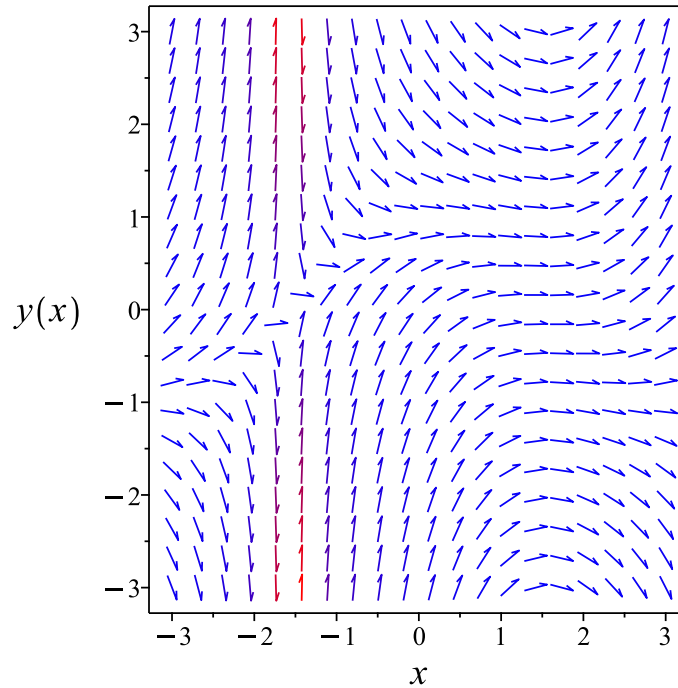


Figure 184: Slope field plot

Verification of solutions

$$y = \frac{\cos(x) \sin(x) - 2c_1 + x}{2 + 2 \sin(x)}$$

Verified OK.

5.13.4 Maple step by step solution

Let's solve

$$-y \cos(x) - (1 + \sin(x)) y' = -\cos(x)^2$$

- Highest derivative means the order of the ODE is 1

$$y'$$

- Isolate the derivative

$$y' = -\frac{\cos(x)y}{1+\sin(x)} + \frac{\cos(x)^2}{1+\sin(x)}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE

$$y' + \frac{\cos(x)y}{1+\sin(x)} = \frac{\cos(x)^2}{1+\sin(x)}$$

- The ODE is linear; multiply by an integrating factor $\mu(x)$

$$\mu(x) \left(y' + \frac{\cos(x)y}{1+\sin(x)} \right) = \frac{\mu(x) \cos(x)^2}{1+\sin(x)}$$

- Assume the lhs of the ODE is the total derivative $\frac{d}{dx}(\mu(x)y)$

$$\mu(x) \left(y' + \frac{\cos(x)y}{1+\sin(x)} \right) = \mu'(x)y + \mu(x)y'$$

- Isolate $\mu'(x)$

$$\mu'(x) = \frac{\mu(x) \cos(x)}{1+\sin(x)}$$

- Solve to find the integrating factor

$$\mu(x) = 1 + \sin(x)$$

- Integrate both sides with respect to x

$$\int \left(\frac{d}{dx}(\mu(x)y) \right) dx = \int \frac{\mu(x) \cos(x)^2}{1+\sin(x)} dx + c_1$$

- Evaluate the integral on the lhs

$$\mu(x)y = \int \frac{\mu(x) \cos(x)^2}{1+\sin(x)} dx + c_1$$

- Solve for y

$$y = \frac{\int \frac{\mu(x) \cos(x)^2}{1+\sin(x)} dx + c_1}{\mu(x)}$$

- Substitute $\mu(x) = 1 + \sin(x)$

$$y = \frac{\int \cos(x)^2 dx + c_1}{1+\sin(x)}$$

- Evaluate the integrals on the rhs

$$y = \frac{\frac{\cos(x) \sin(x)}{2} + \frac{x}{2} + c_1}{1+\sin(x)}$$

- Simplify

$$y = \frac{\cos(x) \sin(x) + 2c_1 + x}{2+2\sin(x)}$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
<- 1st order linear successful`

```


✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 23

```
dsolve((cos(x)^2-y(x)*cos(x))-(1+sin(x))*diff(y(x),x)=0,y(x), singsol=all)
```

$$y(x) = \frac{\sin(x) \cos(x) + 2c_1 + x}{2 + 2 \sin(x)}$$

✓ Solution by Mathematica

Time used: 0.314 (sec). Leaf size: 25

```
DSolve[(Cos[x]^2-y[x]*Cos[x])-(1+Sin[x])*y'[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{x + \sin(x) \cos(x) + 2c_1}{2 \sin(x) + 2}$$

5.14 problem 14

5.14.1 Solving as linear ode	945
5.14.2 Solving as first order ode lie symmetry lookup ode	947
5.14.3 Solving as exact ode	951
5.14.4 Maple step by step solution	955

Internal problem ID [11651]

Internal file name [OUTPUT/11660_Tuesday_April_09_2024_02_05_05_AM_97015726/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.3 (Linear equations). Exercises page 56

Problem number: 14.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"exact", "linear", "first_order_ode_lie_symmetry_lookup"**

Maple gives the following as the ode type

`[_linear]`

$$y \sin(2x) + (1 + \sin(x)^2) y' = \cos(x)$$

5.14.1 Solving as linear ode

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = -\frac{2 \sin(2x)}{-3 + \cos(2x)}$$

$$q(x) = -\frac{\cos(x)}{\cos(x)^2 - 2}$$

Hence the ode is

$$y' - \frac{2 \sin(2x) y}{-3 + \cos(2x)} = -\frac{\cos(x)}{\cos(x)^2 - 2}$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int -\frac{2\sin(2x)}{-3+\cos(2x)} dx} \\ &= -3 + \cos(2x)\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu y) &= (\mu) \left(-\frac{\cos(x)}{\cos(x)^2 - 2} \right) \\ \frac{d}{dx}((-3 + \cos(2x)) y) &= (-3 + \cos(2x)) \left(-\frac{\cos(x)}{\cos(x)^2 - 2} \right) \\ d((-3 + \cos(2x)) y) &= (-2 \cos(x)) dx\end{aligned}$$

Integrating gives

$$\begin{aligned}(-3 + \cos(2x)) y &= \int -2 \cos(x) dx \\ (-3 + \cos(2x)) y &= -2 \sin(x) + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = -3 + \cos(2x)$ results in

$$y = -\frac{2 \sin(x)}{-3 + \cos(2x)} + \frac{c_1}{-3 + \cos(2x)}$$

which simplifies to

$$y = \frac{-2 \sin(x) + c_1}{2 \cos(x)^2 - 4}$$

Summary

The solution(s) found are the following

$$y = \frac{-2 \sin(x) + c_1}{2 \cos(x)^2 - 4} \tag{1}$$

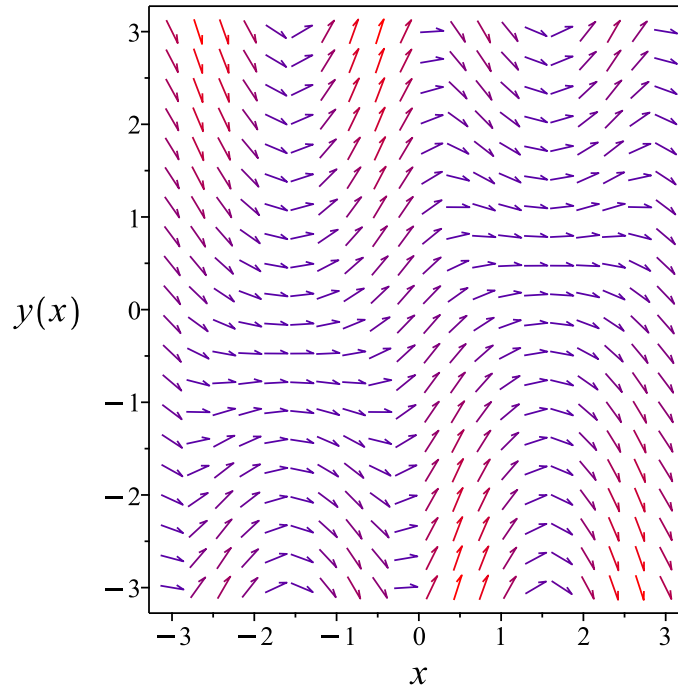


Figure 185: Slope field plot

Verification of solutions

$$y = \frac{-2 \sin(x) + c_1}{2 \cos(x)^2 - 4}$$

Verified OK.

5.14.2 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = \frac{-y \sin(2x) + \cos(x)}{1 + \sin(x)^2}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 148: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned} \xi(x, y) &= 0 \\ \eta(x, y) &= \frac{1}{-3 + \cos(2x)} \end{aligned} \tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{1}{-3+\cos(2x)}} dy \end{aligned}$$

Which results in

$$S = (-3 + \cos(2x))y$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = \frac{-y \sin(2x) + \cos(x)}{1 + \sin(x)^2}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= -2y \sin(2x) \\ S_y &= -3 + \cos(2x) \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = -2 \cos(x) \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = -2 \cos(R)$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = -2 \sin(R) + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$(-3 + \cos(2x)) y = -2 \sin(x) + c_1$$

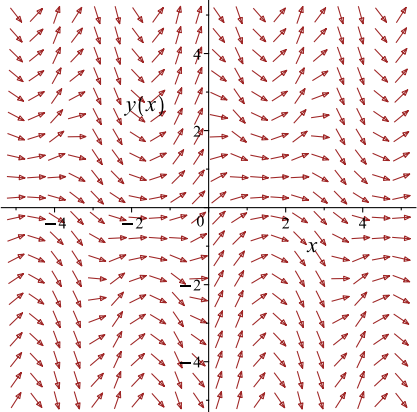
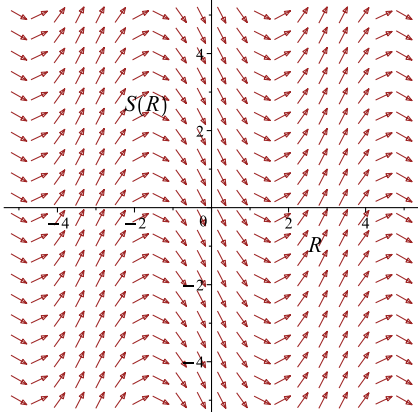
Which simplifies to

$$(-3 + \cos(2x)) y = -2 \sin(x) + c_1$$

Which gives

$$y = -\frac{2 \sin(x) - c_1}{-3 + \cos(2x)}$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = \frac{-y \sin(2x) + \cos(x)}{1 + \sin(x)^2}$ 	$R = x$ $S = (-3 + \cos(2x)) y$	$\frac{dS}{dR} = -2 \cos(R)$ 

Summary

The solution(s) found are the following

$$y = -\frac{2 \sin(x) - c_1}{-3 + \cos(2x)} \quad (1)$$

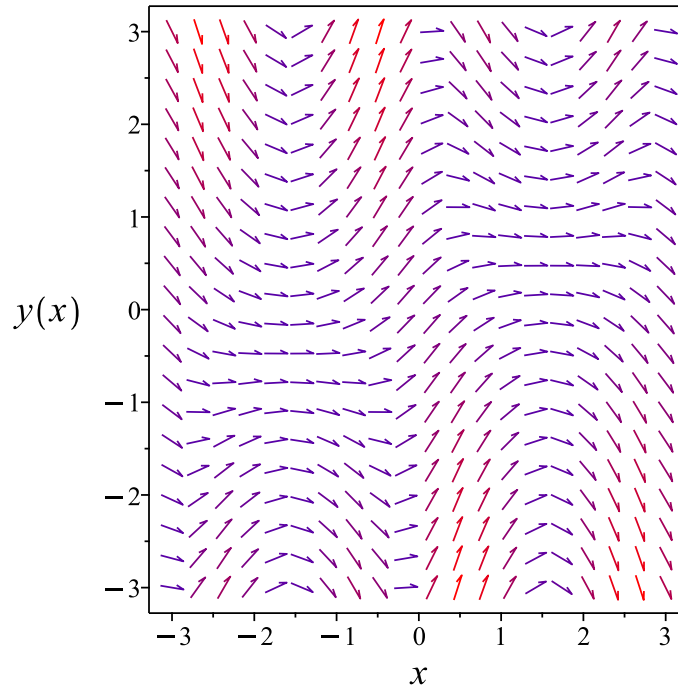


Figure 186: Slope field plot

Verification of solutions

$$y = -\frac{2 \sin(x) - c_1}{-3 + \cos(2x)}$$

Verified OK.

5.14.3 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \tag{1A}$$

Therefore

$$\begin{aligned}(1 + \sin(x)^2) dy &= (-y \sin(2x) + \cos(x)) dx \\ (y \sin(2x) - \cos(x)) dx + (1 + \sin(x)^2) dy &= 0\end{aligned} \tag{2A}$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= y \sin(2x) - \cos(x) \\ N(x, y) &= 1 + \sin(x)^2\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(y \sin(2x) - \cos(x)) \\ &= \sin(2x)\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(1 + \sin(x)^2) \\ &= \sin(2x)\end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \quad (1)$$

$$\frac{\partial \phi}{\partial y} = N \quad (2)$$

Integrating (1) w.r.t. x gives

$$\begin{aligned} \int \frac{\partial \phi}{\partial x} dx &= \int M dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int y \sin(2x) - \cos(x) dx \\ \phi &= -y \cos(x)^2 - \sin(x) + \frac{y}{2} + f(y) \end{aligned} \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\begin{aligned} \frac{\partial \phi}{\partial y} &= -\cos(x)^2 + \frac{1}{2} + f'(y) \\ &= -\frac{\cos(2x)}{2} + f'(y) \end{aligned} \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = 1 + \sin(x)^2$. Therefore equation (4) becomes

$$1 + \sin(x)^2 = -\frac{\cos(2x)}{2} + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$\begin{aligned} f'(y) &= \frac{\cos(2x)}{2} + 1 + \sin(x)^2 \\ &= \frac{3}{2} \end{aligned}$$

Integrating the above w.r.t y results in

$$\begin{aligned} \int f'(y) dy &= \int \left(\frac{3}{2}\right) dy \\ f(y) &= \frac{3y}{2} + c_1 \end{aligned}$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = -y \cos(x)^2 - \sin(x) + 2y + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -y \cos(x)^2 - \sin(x) + 2y$$

The solution becomes

$$y = -\frac{\sin(x) + c_1}{\cos(x)^2 - 2}$$

Summary

The solution(s) found are the following

$$y = -\frac{\sin(x) + c_1}{\cos(x)^2 - 2} \tag{1}$$

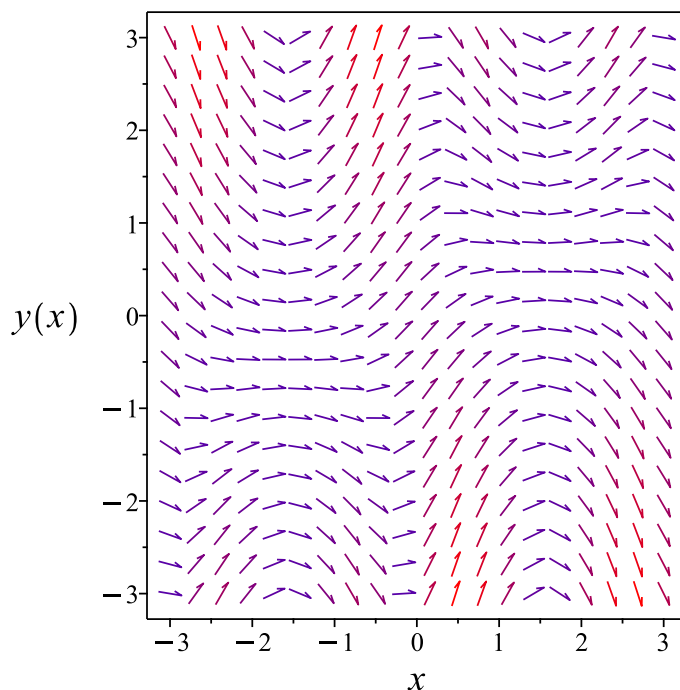


Figure 187: Slope field plot

Verification of solutions

$$y = -\frac{\sin(x) + c_1}{\cos(x)^2 - 2}$$

Verified OK.

5.14.4 Maple step by step solution

Let's solve

$$y \sin(2x) + (1 + \sin(x)^2) y' = \cos(x)$$

- Highest derivative means the order of the ODE is 1

$$y'$$

- Isolate the derivative

$$y' = -\frac{\sin(2x)y}{1+\sin(x)^2} + \frac{\cos(x)}{1+\sin(x)^2}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE

$$y' + \frac{\sin(2x)y}{1+\sin(x)^2} = \frac{\cos(x)}{1+\sin(x)^2}$$

- The ODE is linear; multiply by an integrating factor $\mu(x)$

$$\mu(x) \left(y' + \frac{\sin(2x)y}{1+\sin(x)^2} \right) = \frac{\mu(x) \cos(x)}{1+\sin(x)^2}$$

- Assume the lhs of the ODE is the total derivative $\frac{d}{dx}(\mu(x)y)$

$$\mu(x) \left(y' + \frac{\sin(2x)y}{1+\sin(x)^2} \right) = \mu'(x)y + \mu(x)y'$$

- Isolate $\mu'(x)$

$$\mu'(x) = \frac{\mu(x) \sin(2x)}{1+\sin(x)^2}$$

- Solve to find the integrating factor

$$\mu(x) = \cos(x)^2 - 2$$

- Integrate both sides with respect to x

$$\int \left(\frac{d}{dx}(\mu(x)y) \right) dx = \int \frac{\mu(x) \cos(x)}{1+\sin(x)^2} dx + c_1$$

- Evaluate the integral on the lhs

$$\mu(x)y = \int \frac{\mu(x) \cos(x)}{1+\sin(x)^2} dx + c_1$$

- Solve for y

$$y = \frac{\int \frac{\mu(x) \cos(x)}{1+\sin(x)^2} dx + c_1}{\mu(x)}$$

- Substitute $\mu(x) = \cos(x)^2 - 2$

$$y = \frac{\int \frac{(\cos(x)^2 - 2) \cos(x)}{1 + \sin(x)^2} dx + c_1}{\cos(x)^2 - 2}$$

- Evaluate the integrals on the rhs

$$y = \frac{-\sin(x) + c_1}{\cos(x)^2 - 2}$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
<- 1st order linear successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 21

```
dsolve((y(x)*sin(2*x)-cos(x))+(1+sin(x)^2)*diff(y(x),x)=0,y(x), singsol=all)
```

$$y(x) = \frac{-\sin(x) - c_1}{\cos(x)^2 - 2}$$

✓ Solution by Mathematica

Time used: 0.173 (sec). Leaf size: 21

```
DSolve[(y[x]*Sin[2*x]-Cos[x])+(1+Sin[x]^2)*y'[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{-2 \sin(x) + c_1}{\cos(2x) - 3}$$

5.15 problem 15

5.15.1 Solving as separable ode	957
5.15.2 Solving as homogeneousTypeD2 ode	959
5.15.3 Solving as first order ode lie symmetry lookup ode	960
5.15.4 Solving as bernoulli ode	964
5.15.5 Solving as exact ode	967
5.15.6 Solving as riccati ode	971
5.15.7 Maple step by step solution	973

Internal problem ID [11652]

Internal file name [OUTPUT/11661_Tuesday_April_09_2024_02_05_08_AM_34006736/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.3 (Linear equations). Exercises page 56

Problem number: 15.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact", "riccati", "bernoulli", "separable", "homogeneousTypeD2", "first_order_ode_lie_symmetry_lookup"

Maple gives the following as the ode type

[_separable]

$$y' - \frac{y}{x} + \frac{y^2}{x} = 0$$

5.15.1 Solving as separable ode

In canonical form the ODE is

$$\begin{aligned}y' &= F(x, y) \\ &= f(x)g(y) \\ &= -\frac{y(y-1)}{x}\end{aligned}$$

Where $f(x) = -\frac{1}{x}$ and $g(y) = y(y - 1)$. Integrating both sides gives

$$\begin{aligned}\frac{1}{y(y-1)} dy &= -\frac{1}{x} dx \\ \int \frac{1}{y(y-1)} dy &= \int -\frac{1}{x} dx \\ \ln(y-1) - \ln(y) &= -\ln(x) + c_1\end{aligned}$$

Raising both side to exponential gives

$$e^{\ln(y-1)-\ln(y)} = e^{-\ln(x)+c_1}$$

Which simplifies to

$$\frac{y-1}{y} = \frac{c_2}{x}$$

Summary

The solution(s) found are the following

$$y = -\frac{x}{-x + c_2} \tag{1}$$

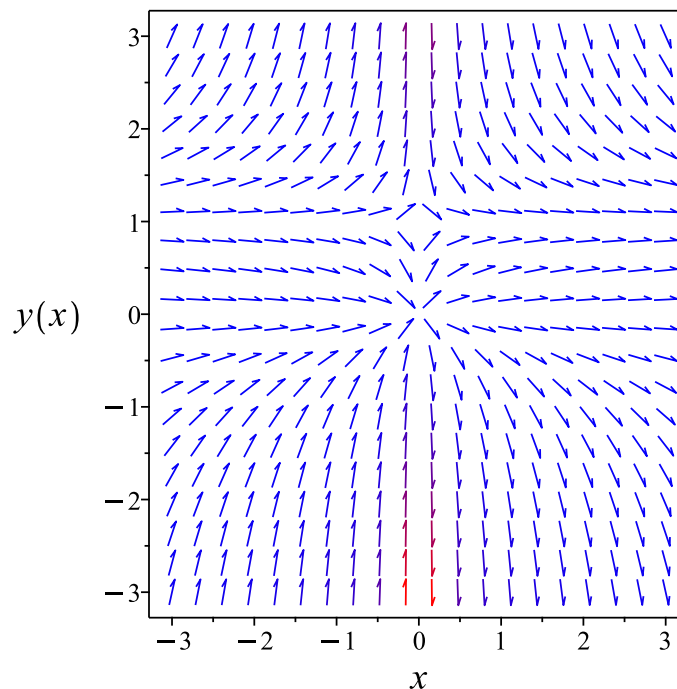


Figure 188: Slope field plot

Verification of solutions

$$y = -\frac{x}{-x + c_2}$$

Verified OK.

5.15.2 Solving as homogeneous Type D2 ode

Using the change of variables $y = u(x)x$ on the above ode results in new ode in $u(x)$

$$u'(x)x + u(x)^2x = 0$$

Integrating both sides gives

$$\int -\frac{1}{u^2} du = x + c_2$$
$$\frac{1}{u} = x + c_2$$

Solving for u gives these solutions

$$u_1 = \frac{1}{x + c_2}$$

Therefore the solution y is

$$y = xu$$
$$= \frac{x}{x + c_2}$$

Summary

The solution(s) found are the following

$$y = \frac{x}{x + c_2} \tag{1}$$

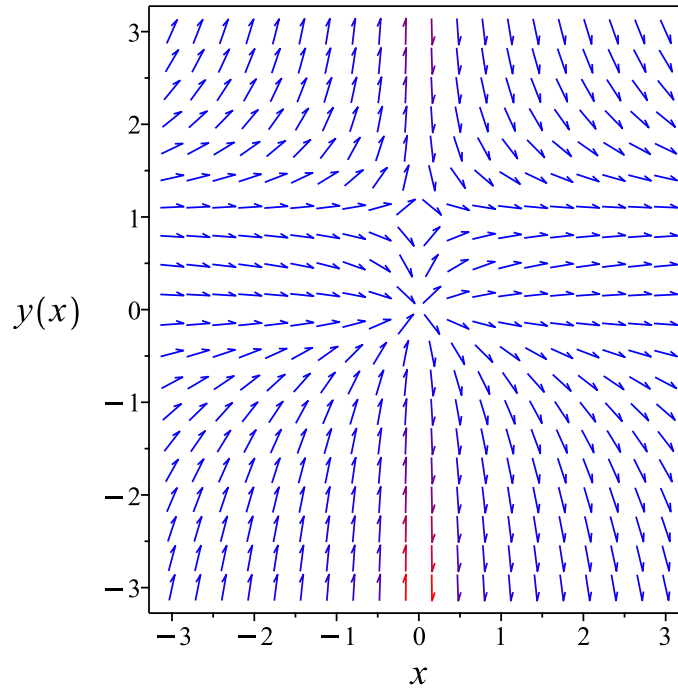


Figure 189: Slope field plot

Verification of solutions

$$y = \frac{x}{x + c_2}$$

Verified OK.

5.15.3 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = -\frac{y(y-1)}{x}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **separable**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 151: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int(n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= -x \\ \eta(x, y) &= 0\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\eta = 0$ then in this special case

$$R = y$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\xi} dx \\ &= \int \frac{1}{-x} dx \end{aligned}$$

Which results in

$$S = -\ln(x)$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{y(y-1)}{x}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 0 \\ R_y &= 1 \\ S_x &= -\frac{1}{x} \\ S_y &= 0 \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = \frac{1}{y(y-1)} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = \frac{1}{R(R-1)}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = \ln(R - 1) - \ln(R) + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$-\ln(x) = \ln(y - 1) - \ln(y) + c_1$$

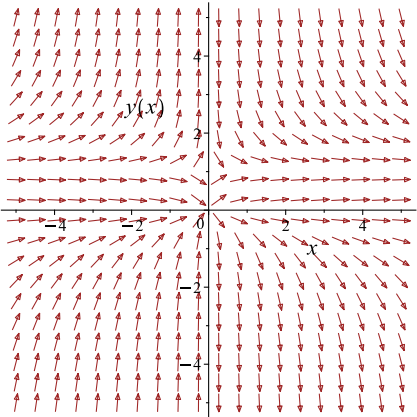
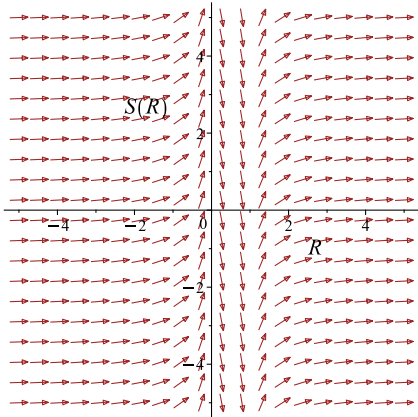
Which simplifies to

$$-\ln(x) = \ln(y - 1) - \ln(y) + c_1$$

Which gives

$$y = \frac{x e^{c_1}}{e^{c_1} x - 1}$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{y(y-1)}{x}$ 	$R = y$ $S = -\ln(x)$	$\frac{dS}{dR} = \frac{1}{R(R-1)}$ 

Summary

The solution(s) found are the following

$$y = \frac{x e^{c_1}}{e^{c_1} x - 1} \quad (1)$$

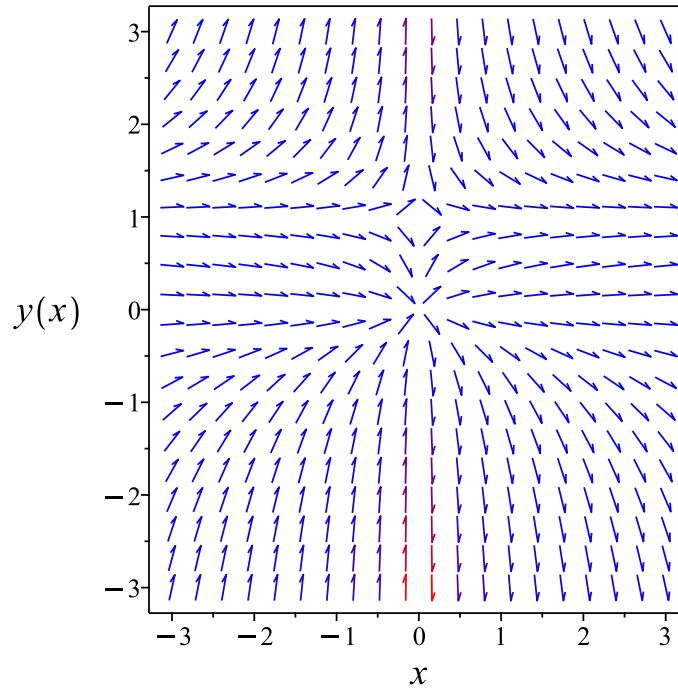


Figure 190: Slope field plot

Verification of solutions

$$y = \frac{x e^{c_1}}{e^{c_1} x - 1}$$

Verified OK.

5.15.4 Solving as bernoulli ode

In canonical form, the ODE is

$$\begin{aligned} y' &= F(x, y) \\ &= -\frac{y(y-1)}{x} \end{aligned}$$

This is a Bernoulli ODE.

$$y' = \frac{1}{x}y - \frac{1}{x}y^2 \tag{1}$$

The standard Bernoulli ODE has the form

$$y' = f_0(x)y + f_1(x)y^n \tag{2}$$

The first step is to divide the above equation by y^n which gives

$$\frac{y'}{y^n} = f_0(x)y^{1-n} + f_1(x) \tag{3}$$

The next step is use the substitution $w = y^{1-n}$ in equation (3) which generates a new ODE in $w(x)$ which will be linear and can be easily solved using an integrating factor. Backsubstitution then gives the solution $y(x)$ which is what we want.

This method is now applied to the ODE at hand. Comparing the ODE (1) With (2) Shows that

$$\begin{aligned} f_0(x) &= \frac{1}{x} \\ f_1(x) &= -\frac{1}{x} \\ n &= 2 \end{aligned}$$

Dividing both sides of ODE (1) by $y^n = y^2$ gives

$$y' \frac{1}{y^2} = \frac{1}{xy} - \frac{1}{x} \quad (4)$$

Let

$$\begin{aligned} w &= y^{1-n} \\ &= \frac{1}{y} \end{aligned} \quad (5)$$

Taking derivative of equation (5) w.r.t x gives

$$w' = -\frac{1}{y^2} y' \quad (6)$$

Substituting equations (5) and (6) into equation (4) gives

$$\begin{aligned} -w'(x) &= \frac{w(x)}{x} - \frac{1}{x} \\ w' &= -\frac{w}{x} + \frac{1}{x} \end{aligned} \quad (7)$$

The above now is a linear ODE in $w(x)$ which is now solved.

Entering Linear first order ODE solver. In canonical form a linear first order is

$$w'(x) + p(x)w(x) = q(x)$$

Where here

$$\begin{aligned} p(x) &= \frac{1}{x} \\ q(x) &= \frac{1}{x} \end{aligned}$$

Hence the ode is

$$w'(x) + \frac{w(x)}{x} = \frac{1}{x}$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int \frac{1}{x} dx} \\ &= x\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu w) &= (\mu) \left(\frac{1}{x}\right) \\ \frac{d}{dx}(xw) &= (x) \left(\frac{1}{x}\right) \\ d(xw) &= dx\end{aligned}$$

Integrating gives

$$\begin{aligned}xw &= \int dx \\ xw &= x + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = x$ results in

$$w(x) = 1 + \frac{c_1}{x}$$

Replacing w in the above by $\frac{1}{y}$ using equation (5) gives the final solution.

$$\frac{1}{y} = 1 + \frac{c_1}{x}$$

Or

$$y = \frac{1}{1 + \frac{c_1}{x}}$$

Which is simplified to

$$y = \frac{x}{x + c_1}$$

Summary

The solution(s) found are the following

$$y = \frac{x}{x + c_1} \tag{1}$$

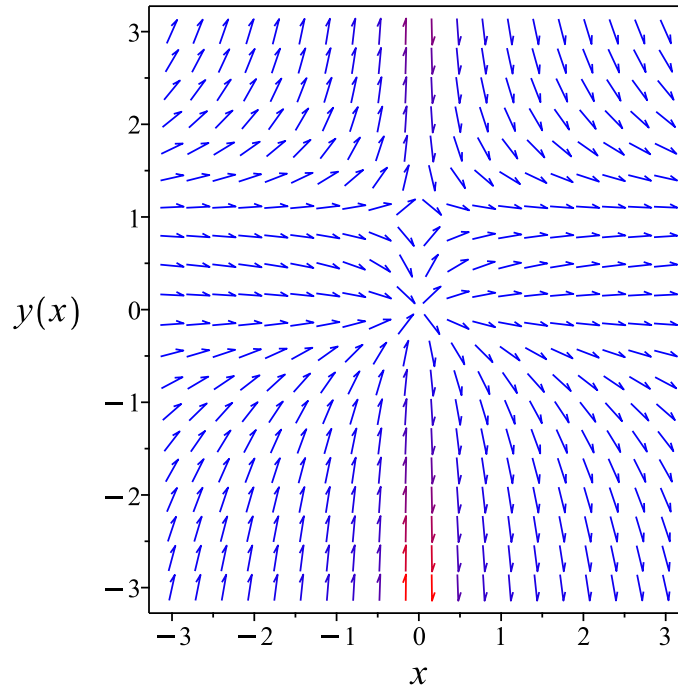


Figure 191: Slope field plot

Verification of solutions

$$y = \frac{x}{x + c_1}$$

Verified OK.

5.15.5 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (1A)$$

Therefore

$$\begin{aligned}\left(-\frac{1}{y(y-1)}\right) dy &= \left(\frac{1}{x}\right) dx \\ \left(-\frac{1}{x}\right) dx + \left(-\frac{1}{y(y-1)}\right) dy &= 0\end{aligned} \quad (2A)$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= -\frac{1}{x} \\ N(x, y) &= -\frac{1}{y(y-1)}\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y} \left(-\frac{1}{x}\right) \\ &= 0\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x} \left(-\frac{1}{y(y-1)} \right) \\ &= 0\end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \tag{1}$$

$$\frac{\partial \phi}{\partial y} = N \tag{2}$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int M dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int -\frac{1}{x} dx \\ \phi &= -\ln(x) + f(y)\end{aligned} \tag{3}$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = 0 + f'(y) \tag{4}$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = -\frac{1}{y(y-1)}$. Therefore equation (4) becomes

$$-\frac{1}{y(y-1)} = 0 + f'(y) \tag{5}$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = -\frac{1}{y(y-1)}$$

Integrating the above w.r.t y gives

$$\begin{aligned}\int f'(y) dy &= \int \left(-\frac{1}{y(y-1)} \right) dy \\ f(y) &= -\ln(y-1) + \ln(y) + c_1\end{aligned}$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = -\ln(x) - \ln(y - 1) + \ln(y) + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -\ln(x) - \ln(y - 1) + \ln(y)$$

The solution becomes

$$y = \frac{x e^{c_1}}{e^{c_1} x - 1}$$

Summary

The solution(s) found are the following

$$y = \frac{x e^{c_1}}{e^{c_1} x - 1} \tag{1}$$

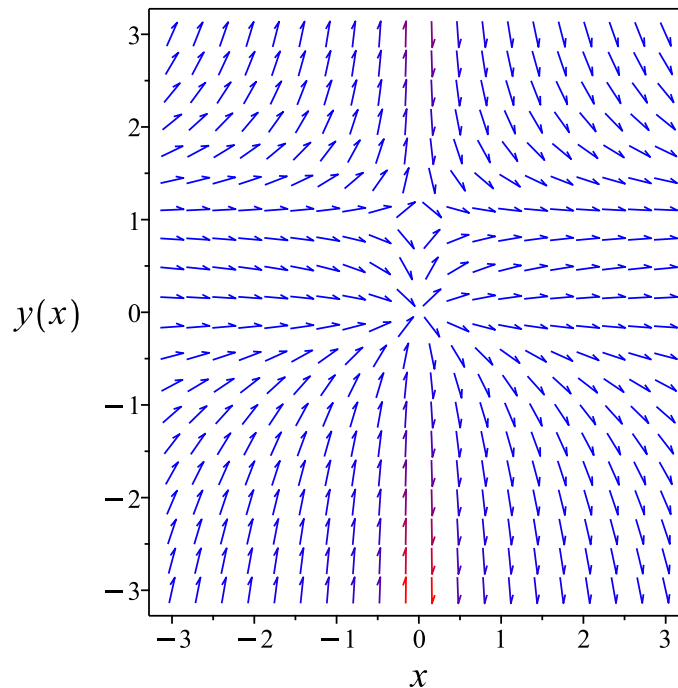


Figure 192: Slope field plot

Verification of solutions

$$y = \frac{x e^{c_1}}{e^{c_1} x - 1}$$

Verified OK.

5.15.6 Solving as riccati ode

In canonical form the ODE is

$$\begin{aligned} y' &= F(x, y) \\ &= -\frac{y(y-1)}{x} \end{aligned}$$

This is a Riccati ODE. Comparing the ODE to solve

$$y' = \frac{y}{x} - \frac{y^2}{x}$$

With Riccati ODE standard form

$$y' = f_0(x) + f_1(x)y + f_2(x)y^2$$

Shows that $f_0(x) = 0$, $f_1(x) = \frac{1}{x}$ and $f_2(x) = -\frac{1}{x}$. Let

$$\begin{aligned} y &= \frac{-u'}{f_2 u} \\ &= \frac{-u'}{-\frac{u}{x}} \end{aligned} \tag{1}$$

Using the above substitution in the given ODE results (after some simplification) in a second order ODE to solve for $u(x)$ which is

$$f_2 u''(x) - (f_2' + f_1 f_2) u'(x) + f_2^2 f_0 u(x) = 0 \tag{2}$$

But

$$\begin{aligned} f_2' &= \frac{1}{x^2} \\ f_1 f_2 &= -\frac{1}{x^2} \\ f_2^2 f_0 &= 0 \end{aligned}$$

Substituting the above terms back in equation (2) gives

$$-\frac{u''(x)}{x} = 0$$

Solving the above ODE (this ode solved using Maple, not this program), gives

$$u(x) = c_1x + c_2$$

The above shows that

$$u'(x) = c_1$$

Using the above in (1) gives the solution

$$y = \frac{c_1x}{c_1x + c_2}$$

Dividing both numerator and denominator by c_1 gives, after renaming the constant $\frac{c_2}{c_1} = c_3$ the following solution

$$y = \frac{c_3x}{c_3x + 1}$$

Summary

The solution(s) found are the following

$$y = \frac{c_3x}{c_3x + 1} \tag{1}$$

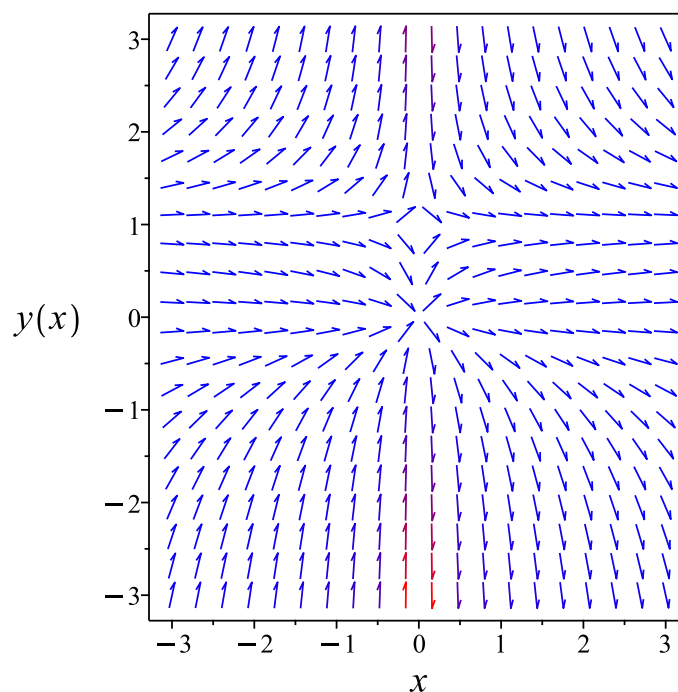


Figure 193: Slope field plot

Verification of solutions

$$y = \frac{c_3 x}{c_3 x + 1}$$

Verified OK.

5.15.7 Maple step by step solution

Let's solve

$$y' - \frac{y}{x} + \frac{y^2}{x} = 0$$

- Highest derivative means the order of the ODE is 1

y'

- Separate variables

$$\frac{y'}{y(y-1)} = -\frac{1}{x}$$

- Integrate both sides with respect to x

$$\int \frac{y'}{y(y-1)} dx = \int -\frac{1}{x} dx + c_1$$

- Evaluate integral

$$\ln(y-1) - \ln(y) = -\ln(x) + c_1$$

- Solve for y

$$y = -\frac{x}{e^{c_1-x}}$$

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
trying Bernoulli  
<- Bernoulli successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 11

```
dsolve(diff(y(x),x)-y(x)/x=-y(x)^2/x,y(x), singsol=all)
```

$$y(x) = \frac{x}{c_1 + x}$$

✓ Solution by Mathematica

Time used: 0.238 (sec). Leaf size: 25

```
DSolve[y'[x]-y[x]/x==y[x]^2/x,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{x}{x + e^{c_1}}$$
$$y(x) \rightarrow 0$$
$$y(x) \rightarrow 1$$

5.16 problem 16

5.16.1 Solving as first order ode lie symmetry lookup ode	975
5.16.2 Solving as bernoulli ode	979
5.16.3 Solving as exact ode	983

Internal problem ID [11653]

Internal file name [OUTPUT/11662_Tuesday_April_09_2024_02_05_09_AM_12694163/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.3 (Linear equations). Exercises page 56

Problem number: 16.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "bernoulli", "exactWithIntegrationFactor", "first_order_ode_lie_symmetry_lookup"

Maple gives the following as the ode type

```
[[_homogeneous, `class G`], _rational, _Bernoulli]
```

$$y'x + y + 2x^6y^4 = 0$$

5.16.1 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = -\frac{y(2x^6y^3 + 1)}{x}$$
$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2\xi_y - \omega_x\xi - \omega_y\eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type `Bernoulli`. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 154: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= y^4x^3\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{y^4 x^3} dy \end{aligned}$$

Which results in

$$S = -\frac{1}{3x^3 y^3}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{y(2x^6 y^3 + 1)}{x}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= \frac{1}{x^4 y^3} \\ S_y &= \frac{1}{x^3 y^4} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = -2x^2 \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = -2R^2$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = -\frac{2R^3}{3} + c_1 \quad (4)$$

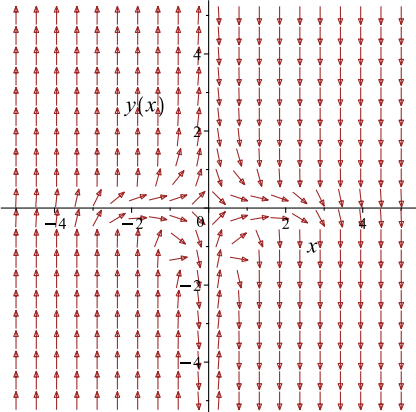
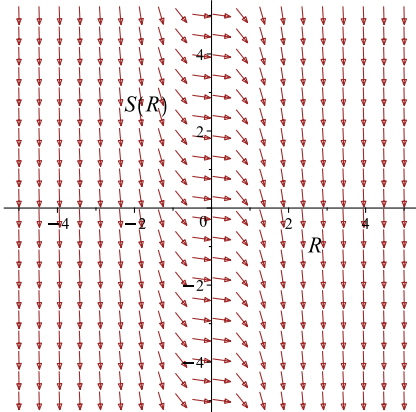
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$-\frac{1}{3x^3y^3} = -\frac{2x^3}{3} + c_1$$

Which simplifies to

$$-\frac{1}{3x^3y^3} = -\frac{2x^3}{3} + c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{y(2x^6y^3+1)}{x}$ 	$R = x$ $S = -\frac{1}{3x^3y^3}$	$\frac{dS}{dR} = -2R^2$ 

Summary

The solution(s) found are the following

$$-\frac{1}{3x^3y^3} = -\frac{2x^3}{3} + c_1 \quad (1)$$

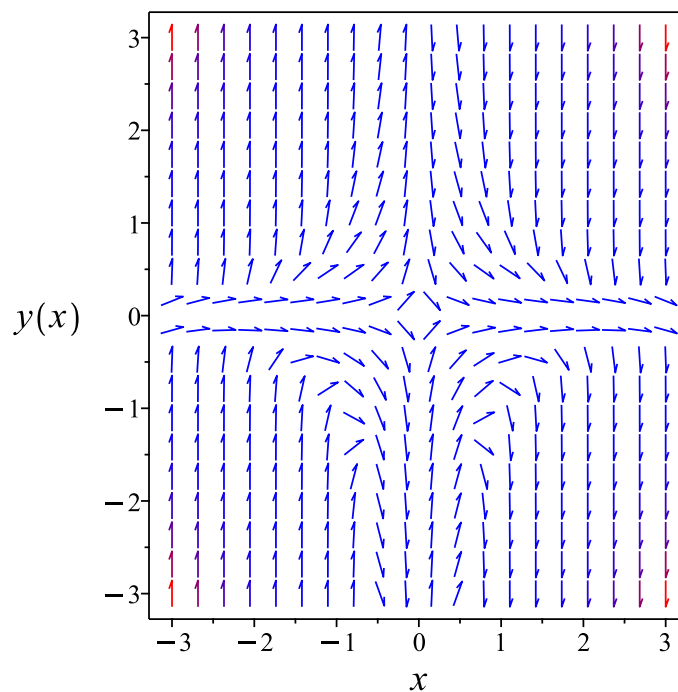


Figure 194: Slope field plot

Verification of solutions

$$-\frac{1}{3x^3y^3} = -\frac{2x^3}{3} + c_1$$

Verified OK.

5.16.2 Solving as bernoulli ode

In canonical form, the ODE is

$$\begin{aligned} y' &= F(x, y) \\ &= -\frac{y(2x^6y^3 + 1)}{x} \end{aligned}$$

This is a Bernoulli ODE.

$$y' = -\frac{1}{x}y - 2x^5y^4 \quad (1)$$

The standard Bernoulli ODE has the form

$$y' = f_0(x)y + f_1(x)y^n \quad (2)$$

The first step is to divide the above equation by y^n which gives

$$\frac{y'}{y^n} = f_0(x)y^{1-n} + f_1(x) \quad (3)$$

The next step is use the substitution $w = y^{1-n}$ in equation (3) which generates a new ODE in $w(x)$ which will be linear and can be easily solved using an integrating factor. Backsubstitution then gives the solution $y(x)$ which is what we want.

This method is now applied to the ODE at hand. Comparing the ODE (1) With (2) Shows that

$$\begin{aligned}f_0(x) &= -\frac{1}{x} \\f_1(x) &= -2x^5 \\n &= 4\end{aligned}$$

Dividing both sides of ODE (1) by $y^n = y^4$ gives

$$y' \frac{1}{y^4} = -\frac{1}{x y^3} - 2x^5 \quad (4)$$

Let

$$\begin{aligned}w &= y^{1-n} \\&= \frac{1}{y^3}\end{aligned} \quad (5)$$

Taking derivative of equation (5) w.r.t x gives

$$w' = -\frac{3}{y^4} y' \quad (6)$$

Substituting equations (5) and (6) into equation (4) gives

$$\begin{aligned}-\frac{w'(x)}{3} &= -\frac{w(x)}{x} - 2x^5 \\w' &= \frac{3w}{x} + 6x^5\end{aligned} \quad (7)$$

The above now is a linear ODE in $w(x)$ which is now solved.

Entering Linear first order ODE solver. In canonical form a linear first order is

$$w'(x) + p(x)w(x) = q(x)$$

Where here

$$\begin{aligned}p(x) &= -\frac{3}{x} \\q(x) &= 6x^5\end{aligned}$$

Hence the ode is

$$w'(x) - \frac{3w(x)}{x} = 6x^5$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int -\frac{3}{x} dx} \\ &= \frac{1}{x^3}\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu w) &= (\mu) (6x^5) \\ \frac{d}{dx}\left(\frac{w}{x^3}\right) &= \left(\frac{1}{x^3}\right) (6x^5) \\ d\left(\frac{w}{x^3}\right) &= (6x^2) dx\end{aligned}$$

Integrating gives

$$\begin{aligned}\frac{w}{x^3} &= \int 6x^2 dx \\ \frac{w}{x^3} &= 2x^3 + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = \frac{1}{x^3}$ results in

$$w(x) = 2x^6 + c_1x^3$$

Replacing w in the above by $\frac{1}{y^3}$ using equation (5) gives the final solution.

$$\frac{1}{y^3} = 2x^6 + c_1x^3$$

Solving for y gives

$$\begin{aligned}y(x) &= \frac{1}{(2x^3 + c_1)^{\frac{1}{3}} x} \\ y(x) &= \frac{i\sqrt{3} - 1}{2(2x^3 + c_1)^{\frac{1}{3}} x} \\ y(x) &= -\frac{1 + i\sqrt{3}}{2(2x^3 + c_1)^{\frac{1}{3}} x}\end{aligned}$$

Summary

The solution(s) found are the following

$$y = \frac{1}{(2x^3 + c_1)^{\frac{1}{3}} x} \quad (1)$$

$$y = \frac{i\sqrt{3} - 1}{2(2x^3 + c_1)^{\frac{1}{3}} x} \quad (2)$$

$$y = -\frac{1 + i\sqrt{3}}{2(2x^3 + c_1)^{\frac{1}{3}} x} \quad (3)$$

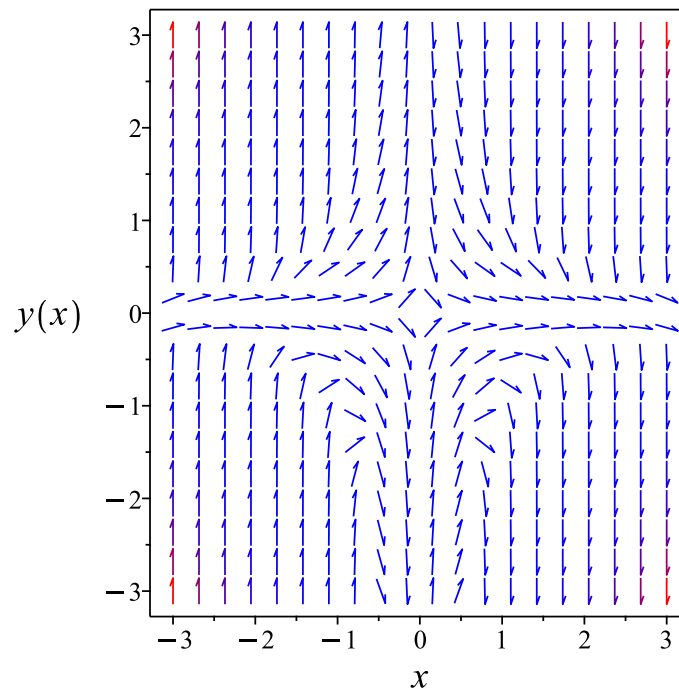


Figure 195: Slope field plot

Verification of solutions

$$y = \frac{1}{(2x^3 + c_1)^{\frac{1}{3}} x}$$

Verified OK.

$$y = \frac{i\sqrt{3} - 1}{2(2x^3 + c_1)^{\frac{1}{3}} x}$$

Verified OK.

$$y = -\frac{1 + i\sqrt{3}}{2(2x^3 + c_1)^{\frac{1}{3}} x}$$

Verified OK.

5.16.3 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \quad (\text{A})$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \quad (\text{B})$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition

$\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (1A)$$

Therefore

$$\begin{aligned} (x) dy &= (-2x^6 y^4 - y) dx \\ (2x^6 y^4 + y) dx + (x) dy &= 0 \end{aligned} \quad (2A)$$

Comparing (1A) and (2A) shows that

$$\begin{aligned} M(x, y) &= 2x^6 y^4 + y \\ N(x, y) &= x \end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned} \frac{\partial M}{\partial y} &= \frac{\partial}{\partial y} (2x^6 y^4 + y) \\ &= 8x^6 y^3 + 1 \end{aligned}$$

And

$$\begin{aligned} \frac{\partial N}{\partial x} &= \frac{\partial}{\partial x} (x) \\ &= 1 \end{aligned}$$

Since $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$\begin{aligned} A &= \frac{1}{N} \left(\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} \right) \\ &= \frac{1}{x} ((8x^6 y^3 + 1) - (1)) \\ &= 8x^5 y^3 \end{aligned}$$

Since A depends on y , it can not be used to obtain an integrating factor. We will now try a second method to find an integrating factor. Let

$$\begin{aligned} B &= \frac{1}{M} \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) \\ &= \frac{1}{2x^6y^4 + y} ((1) - (8x^6y^3 + 1)) \\ &= -\frac{8x^6y^2}{2x^6y^3 + 1} \end{aligned}$$

Since B depends on x , it can not be used to obtain an integrating factor. We will now try a third method to find an integrating factor. Let

$$R = \frac{\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y}}{xM - yN}$$

R is now checked to see if it is a function of only $t = xy$. Therefore

$$\begin{aligned} R &= \frac{\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y}}{xM - yN} \\ &= \frac{(1) - (8x^6y^3 + 1)}{x(2x^6y^4 + y) - y(x)} \\ &= -\frac{4}{xy} \end{aligned}$$

Replacing all powers of terms xy by t gives

$$R = -\frac{4}{t}$$

Since R depends on t only, then it can be used to find an integrating factor. Let the integrating factor be μ then

$$\begin{aligned} \mu &= e^{\int R dt} \\ &= e^{\int (-\frac{4}{t}) dt} \end{aligned}$$

The result of integrating gives

$$\begin{aligned} \mu &= e^{-4 \ln(t)} \\ &= \frac{1}{t^4} \end{aligned}$$

Now t is replaced back with xy giving

$$\mu = \frac{1}{x^4y^4}$$

Multiplying M and N by this integrating factor gives new M and new N which are called \overline{M} and \overline{N} so not to confuse them with the original M and N

$$\begin{aligned}\overline{M} &= \mu M \\ &= \frac{1}{x^4 y^4} (2x^6 y^4 + y) \\ &= \frac{2x^6 y^3 + 1}{x^4 y^3}\end{aligned}$$

And

$$\begin{aligned}\overline{N} &= \mu N \\ &= \frac{1}{x^4 y^4} (x) \\ &= \frac{1}{x^3 y^4}\end{aligned}$$

A modified ODE is now obtained from the original ODE, which is exact and can be solved. The modified ODE is

$$\begin{aligned}\overline{M} + \overline{N} \frac{dy}{dx} &= 0 \\ \left(\frac{2x^6 y^3 + 1}{x^4 y^3} \right) + \left(\frac{1}{x^3 y^4} \right) \frac{dy}{dx} &= 0\end{aligned}$$

The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = \overline{M} \tag{1}$$

$$\frac{\partial \phi}{\partial y} = \overline{N} \tag{2}$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int \overline{M} dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int \frac{2x^6 y^3 + 1}{x^4 y^3} dx \\ \phi &= \frac{2x^6 y^3 - 1}{3x^3 y^3} + f(y)\end{aligned} \tag{3}$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\begin{aligned}\frac{\partial\phi}{\partial y} &= \frac{2x^3}{y} - \frac{2x^6y^3 - 1}{x^3y^4} + f'(y) \\ &= \frac{1}{x^3y^4} + f'(y)\end{aligned}\tag{4}$$

But equation (2) says that $\frac{\partial\phi}{\partial y} = \frac{1}{x^3y^4}$. Therefore equation (4) becomes

$$\frac{1}{x^3y^4} = \frac{1}{x^3y^4} + f'(y)\tag{5}$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 0$$

Therefore

$$f(y) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(y)$ into equation (3) gives ϕ

$$\phi = \frac{2x^6y^3 - 1}{3x^3y^3} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = \frac{2x^6y^3 - 1}{3x^3y^3}$$

Summary

The solution(s) found are the following

$$\frac{2y^3x^6 - 1}{3x^3y^3} = c_1\tag{1}$$

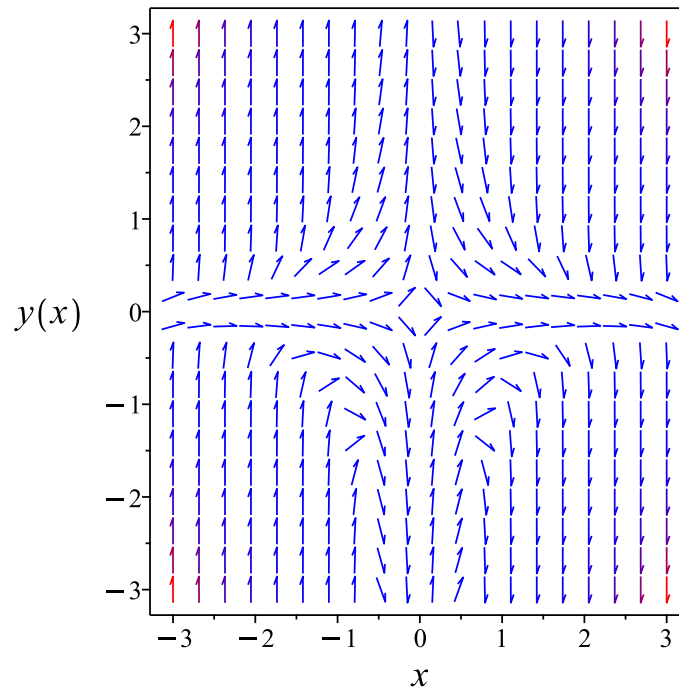


Figure 196: Slope field plot

Verification of solutions

$$\frac{2y^3x^6 - 1}{3x^3y^3} = c_1$$

Verified OK.

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
<- Bernoulli successful`

```

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 67

```
dsolve(x*diff(y(x),x)+y(x)=-2*x^6*y(x)^4,y(x), singsol=all)
```

$$y(x) = \frac{1}{(2x^3 + c_1)^{\frac{1}{3}} x}$$

$$y(x) = -\frac{1 + i\sqrt{3}}{2(2x^3 + c_1)^{\frac{1}{3}} x}$$

$$y(x) = \frac{i\sqrt{3} - 1}{2(2x^3 + c_1)^{\frac{1}{3}} x}$$

✓ Solution by Mathematica

Time used: 0.87 (sec). Leaf size: 79

```
DSolve[x*y'[x]+y[x]==-2*x^6*y[x]^4,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{1}{\sqrt[3]{x^3(2x^3 + c_1)}}$$

$$y(x) \rightarrow -\frac{\sqrt[3]{-1}}{\sqrt[3]{x^3(2x^3 + c_1)}}$$

$$y(x) \rightarrow \frac{(-1)^{2/3}}{\sqrt[3]{x^3(2x^3 + c_1)}}$$

$$y(x) \rightarrow 0$$

5.17 problem 17

5.17.1 Solving as separable ode	990
5.17.2 Solving as first order ode lie symmetry lookup ode	992
5.17.3 Solving as bernoulli ode	996
5.17.4 Solving as exact ode	1000
5.17.5 Maple step by step solution	1004

Internal problem ID [11654]

Internal file name [OUTPUT/11663_Tuesday_April_09_2024_02_05_10_AM_56841430/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.3 (Linear equations). Exercises page 56

Problem number: 17.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact", "bernoulli", "separable", "first_order_ode_lie_symmetry_lookup"

Maple gives the following as the ode type

[_separable]

$$y' + \left(4y - \frac{8}{y^3}\right) x = 0$$

5.17.1 Solving as separable ode

In canonical form the ODE is

$$\begin{aligned}y' &= F(x, y) \\ &= f(x)g(y) \\ &= -\frac{4x(y^4 - 2)}{y^3}\end{aligned}$$

Where $f(x) = -4x$ and $g(y) = \frac{y^4-2}{y^3}$. Integrating both sides gives

$$\frac{1}{\frac{y^4-2}{y^3}} dy = -4x dx$$

$$\int \frac{1}{\frac{y^4-2}{y^3}} dy = \int -4x dx$$

$$\frac{\ln(y^4 - 2)}{4} = -2x^2 + c_1$$

Raising both side to exponential gives

$$(y^4 - 2)^{\frac{1}{4}} = e^{-2x^2+c_1}$$

Which simplifies to

$$(y^4 - 2)^{\frac{1}{4}} = c_2 e^{-2x^2}$$

The solution is

$$(y^4 - 2)^{\frac{1}{4}} = c_2 e^{-2x^2+c_1}$$

Summary

The solution(s) found are the following

$$(y^4 - 2)^{\frac{1}{4}} = c_2 e^{-2x^2+c_1} \tag{1}$$

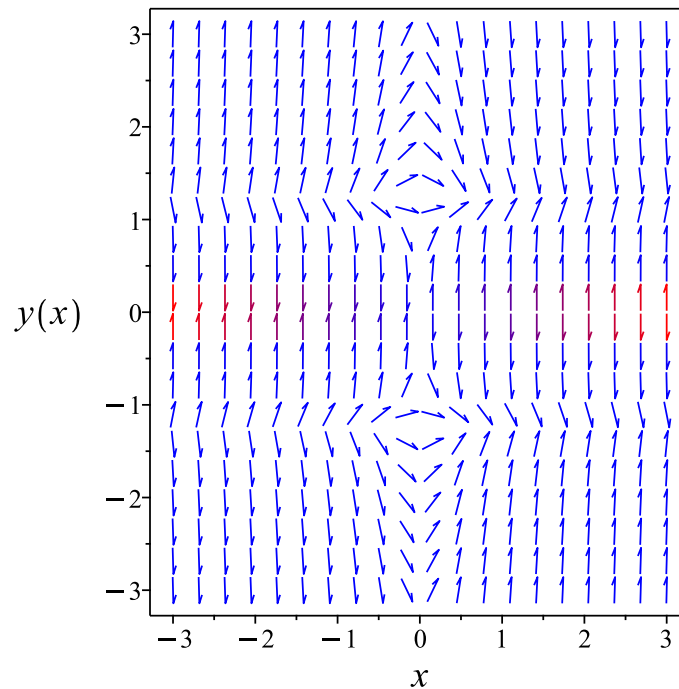


Figure 197: Slope field plot

Verification of solutions

$$(y^4 - 2)^{\frac{1}{4}} = c_2 e^{-2x^2 + c_1}$$

Verified OK.

5.17.2 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = -\frac{4x(y^4 - 2)}{y^3}$$
$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **separable**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 156: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int(n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= -\frac{1}{4x} \\ \eta(x, y) &= 0\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\eta = 0$ then in this special case

$$R = y$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\xi} dx \\ &= \int \frac{1}{-\frac{1}{4x}} dx \end{aligned}$$

Which results in

$$S = -2x^2$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{4x(y^4 - 2)}{y^3}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 0 \\ R_y &= 1 \\ S_x &= -4x \\ S_y &= 0 \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = \frac{y^3}{y^4 - 2} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = \frac{R^3}{R^4 - 2}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = \frac{\ln(R^4 - 2)}{4} + c_1 \quad (4)$$

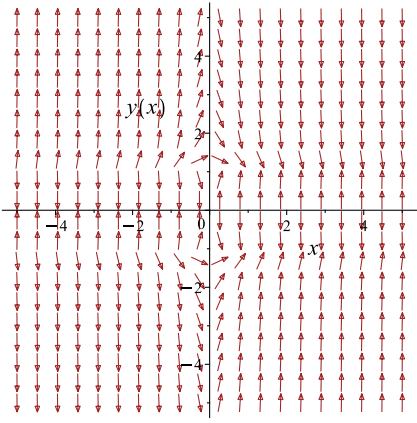
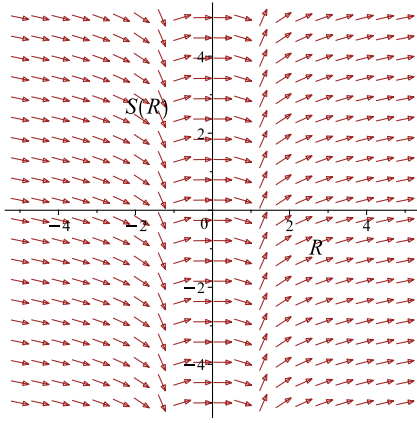
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$-2x^2 = \frac{\ln(y^4 - 2)}{4} + c_1$$

Which simplifies to

$$-2x^2 = \frac{\ln(y^4 - 2)}{4} + c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{4x(y^4-2)}{y^3}$ 	$R = y$ $S = -2x^2$	$\frac{dS}{dR} = \frac{R^3}{R^4-2}$ 

Summary

The solution(s) found are the following

$$-2x^2 = \frac{\ln(y^4 - 2)}{4} + c_1 \quad (1)$$

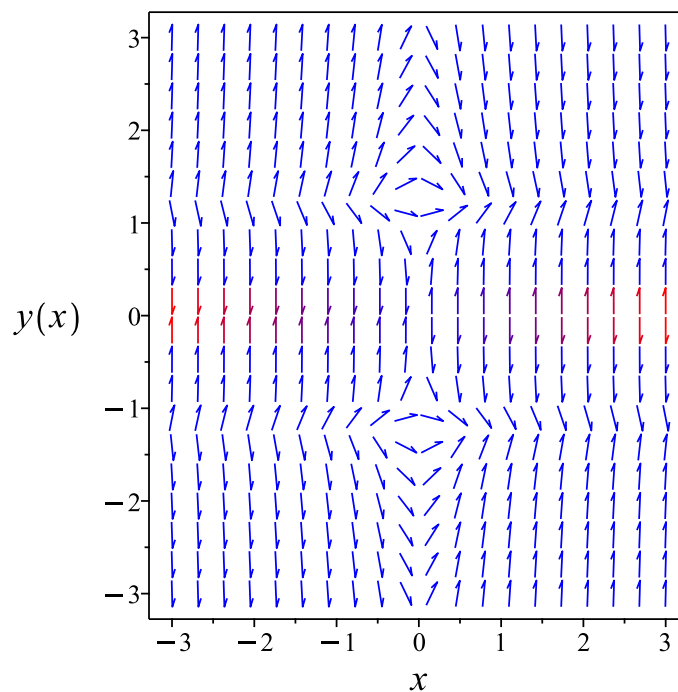


Figure 198: Slope field plot

Verification of solutions

$$-2x^2 = \frac{\ln(y^4 - 2)}{4} + c_1$$

Verified OK.

5.17.3 Solving as bernoulli ode

In canonical form, the ODE is

$$\begin{aligned} y' &= F(x, y) \\ &= -\frac{4x(y^4 - 2)}{y^3} \end{aligned}$$

This is a Bernoulli ODE.

$$y' = -4xy + 8x \frac{1}{y^3} \tag{1}$$

The standard Bernoulli ODE has the form

$$y' = f_0(x)y + f_1(x)y^n \tag{2}$$

The first step is to divide the above equation by y^n which gives

$$\frac{y'}{y^n} = f_0(x)y^{1-n} + f_1(x) \tag{3}$$

The next step is use the substitution $w = y^{1-n}$ in equation (3) which generates a new ODE in $w(x)$ which will be linear and can be easily solved using an integrating factor. Backsubstitution then gives the solution $y(x)$ which is what we want.

This method is now applied to the ODE at hand. Comparing the ODE (1) With (2) Shows that

$$f_0(x) = -4x$$

$$f_1(x) = 8x$$

$$n = -3$$

Dividing both sides of ODE (1) by $y^n = \frac{1}{y^3}$ gives

$$y'y^3 = -4x y^4 + 8x \quad (4)$$

Let

$$\begin{aligned} w &= y^{1-n} \\ &= y^4 \end{aligned} \quad (5)$$

Taking derivative of equation (5) w.r.t x gives

$$w' = 4y^3 y' \quad (6)$$

Substituting equations (5) and (6) into equation (4) gives

$$\begin{aligned} \frac{w'(x)}{4} &= -4w(x)x + 8x \\ w' &= -16xw + 32x \end{aligned} \quad (7)$$

The above now is a linear ODE in $w(x)$ which is now solved.

Entering Linear first order ODE solver. In canonical form a linear first order is

$$w'(x) + p(x)w(x) = q(x)$$

Where here

$$p(x) = 16x$$

$$q(x) = 32x$$

Hence the ode is

$$w'(x) + 16w(x)x = 32x$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int 16x dx} \\ &= e^{8x^2}\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu w) &= (\mu)(32x) \\ \frac{d}{dx}(e^{8x^2}w) &= (e^{8x^2})(32x) \\ d(e^{8x^2}w) &= (32x e^{8x^2}) dx\end{aligned}$$

Integrating gives

$$\begin{aligned}e^{8x^2}w &= \int 32x e^{8x^2} dx \\ e^{8x^2}w &= 2e^{8x^2} + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = e^{8x^2}$ results in

$$w(x) = 2e^{-8x^2}e^{8x^2} + c_1e^{-8x^2}$$

which simplifies to

$$w(x) = 2 + c_1e^{-8x^2}$$

Replacing w in the above by y^4 using equation (5) gives the final solution.

$$y^4 = 2 + c_1e^{-8x^2}$$

Solving for y gives

$$\begin{aligned}y(x) &= \left(2e^{8x^2} + c_1\right)^{\frac{1}{4}} e^{-2x^2} \\ y(x) &= i\left(2e^{8x^2} + c_1\right)^{\frac{1}{4}} e^{-2x^2} \\ y(x) &= -\left(2e^{8x^2} + c_1\right)^{\frac{1}{4}} e^{-2x^2} \\ y(x) &= -i\left(2e^{8x^2} + c_1\right)^{\frac{1}{4}} e^{-2x^2}\end{aligned}$$

Summary

The solution(s) found are the following

$$y = \left(2e^{8x^2} + c_1\right)^{\frac{1}{4}} e^{-2x^2} \quad (1)$$

$$y = i\left(2e^{8x^2} + c_1\right)^{\frac{1}{4}} e^{-2x^2} \quad (2)$$

$$y = -\left(2e^{8x^2} + c_1\right)^{\frac{1}{4}} e^{-2x^2} \quad (3)$$

$$y = -i\left(2e^{8x^2} + c_1\right)^{\frac{1}{4}} e^{-2x^2} \quad (4)$$

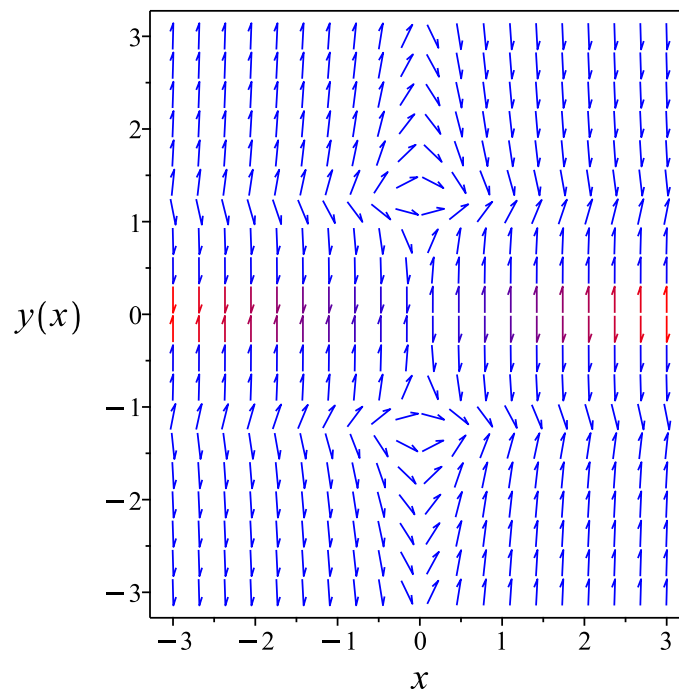


Figure 199: Slope field plot

Verification of solutions

$$y = \left(2e^{8x^2} + c_1\right)^{\frac{1}{4}} e^{-2x^2}$$

Verified OK.

$$y = i\left(2e^{8x^2} + c_1\right)^{\frac{1}{4}} e^{-2x^2}$$

Verified OK.

$$y = -\left(2e^{8x^2} + c_1\right)^{\frac{1}{4}} e^{-2x^2}$$

Verified OK.

$$y = -i\left(2e^{8x^2} + c_1\right)^{\frac{1}{4}} e^{-2x^2}$$

Verified OK.

5.17.4 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (1A)$$

Therefore

$$\begin{aligned} & \left(-\frac{y^3}{4(y^4 - 2)} \right) dy = (x) dx \\ (-x) dx + & \left(-\frac{y^3}{4(y^4 - 2)} \right) dy = 0 \end{aligned} \quad (2A)$$

Comparing (1A) and (2A) shows that

$$\begin{aligned} M(x, y) &= -x \\ N(x, y) &= -\frac{y^3}{4(y^4 - 2)} \end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned} \frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(-x) \\ &= 0 \end{aligned}$$

And

$$\begin{aligned} \frac{\partial N}{\partial x} &= \frac{\partial}{\partial x} \left(-\frac{y^3}{4(y^4 - 2)} \right) \\ &= 0 \end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \quad (1)$$

$$\frac{\partial \phi}{\partial y} = N \quad (2)$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int M dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int -x dx \\ \phi &= -\frac{x^2}{2} + f(y)\end{aligned}\tag{3}$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = 0 + f'(y)\tag{4}$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = -\frac{y^3}{4(y^4-2)}$. Therefore equation (4) becomes

$$-\frac{y^3}{4(y^4-2)} = 0 + f'(y)\tag{5}$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = -\frac{y^3}{4(y^4-2)}$$

Integrating the above w.r.t y gives

$$\begin{aligned}\int f'(y) dy &= \int \left(-\frac{y^3}{4y^4-8}\right) dy \\ f(y) &= -\frac{\ln(y^4-2)}{16} + c_1\end{aligned}$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = -\frac{x^2}{2} - \frac{\ln(y^4-2)}{16} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -\frac{x^2}{2} - \frac{\ln(y^4 - 2)}{16}$$

Summary

The solution(s) found are the following

$$-\frac{x^2}{2} - \frac{\ln(y^4 - 2)}{16} = c_1 \quad (1)$$

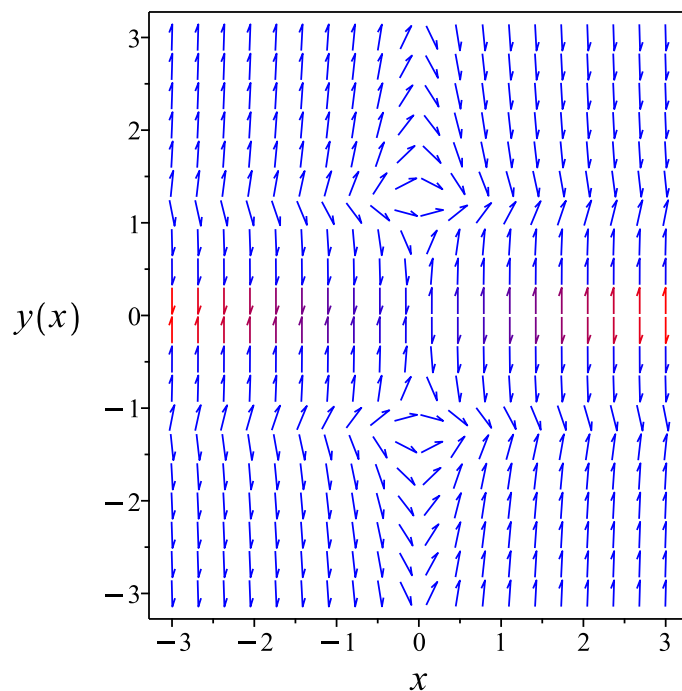


Figure 200: Slope field plot

Verification of solutions

$$-\frac{x^2}{2} - \frac{\ln(y^4 - 2)}{16} = c_1$$

Verified OK.

5.17.5 Maple step by step solution

Let's solve

$$y' + \left(4y - \frac{8}{y^3}\right) x = 0$$

- Highest derivative means the order of the ODE is 1

y'

- Separate variables

$$\frac{y'}{4y - \frac{8}{y^3}} = -x$$

- Integrate both sides with respect to x

$$\int \frac{y'}{4y - \frac{8}{y^3}} dx = \int -x dx + c_1$$

- Evaluate integral

$$\frac{\ln(y^4 - 2)}{16} = -\frac{x^2}{2} + c_1$$

- Solve for y

$$\left\{ y = \frac{\left((e^{c_1})^{16} + 2(e^{x^2})^8\right)^{\frac{1}{4}}}{(e^{x^2})^2}, y = -\frac{\left((e^{c_1})^{16} + 2(e^{x^2})^8\right)^{\frac{1}{4}}}{(e^{x^2})^2} \right\}$$

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
trying Bernoulli  
<- Bernoulli successful`
```

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 94

```
dsolve(diff(y(x),x)+(4*y(x)-8/y(x)^3)*x=0,y(x), singsol=all)
```

$$y(x) = \left(2e^{8x^2} + c_1\right)^{\frac{1}{4}} e^{-2x^2}$$

$$y(x) = -\left(2e^{8x^2} + c_1\right)^{\frac{1}{4}} e^{-2x^2}$$

$$y(x) = -i\left(2e^{8x^2} + c_1\right)^{\frac{1}{4}} e^{-2x^2}$$

$$y(x) = i\left(2e^{8x^2} + c_1\right)^{\frac{1}{4}} e^{-2x^2}$$

✓ Solution by Mathematica

Time used: 1.939 (sec). Leaf size: 145

```
DSolve[y'[x]+(4*y[x]-8/y[x]^3)*x==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow -\sqrt[4]{2 + e^{-8x^2+4c_1}}$$

$$y(x) \rightarrow -i\sqrt[4]{2 + e^{-8x^2+4c_1}}$$

$$y(x) \rightarrow i\sqrt[4]{2 + e^{-8x^2+4c_1}}$$

$$y(x) \rightarrow \sqrt[4]{2 + e^{-8x^2+4c_1}}$$

$$y(x) \rightarrow -\sqrt[4]{2}$$

$$y(x) \rightarrow -i\sqrt[4]{2}$$

$$y(x) \rightarrow i\sqrt[4]{2}$$

$$y(x) \rightarrow \sqrt[4]{2}$$

5.18 problem 18

5.18.1 Solving as separable ode	1006
5.18.2 Solving as first order ode lie symmetry lookup ode	1008
5.18.3 Solving as bernoulli ode	1012
5.18.4 Solving as exact ode	1016
5.18.5 Maple step by step solution	1019

Internal problem ID [11655]

Internal file name [OUTPUT/11664_Tuesday_April_09_2024_02_05_12_AM_38753072/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 2, section 2.3 (Linear equations). Exercises page 56

Problem number: 18.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact", "bernoulli", "separable", "first_order_ode_lie_symmetry_lookup"

Maple gives the following as the ode type

`[_separable]`

$$x' + \frac{(1+t)x}{2t} - \frac{1+t}{xt} = 0$$

5.18.1 Solving as separable ode

In canonical form the ODE is

$$\begin{aligned}x' &= F(t, x) \\ &= f(t)g(x) \\ &= \frac{(1+t)(-x^2+2)}{2tx}\end{aligned}$$

Where $f(t) = \frac{1+t}{2t}$ and $g(x) = \frac{-x^2+2}{x}$. Integrating both sides gives

$$\frac{1}{\frac{-x^2+2}{x}} dx = \frac{1+t}{2t} dt$$

$$\int \frac{1}{\frac{-x^2+2}{x}} dx = \int \frac{1+t}{2t} dt$$

$$-\frac{\ln(x^2-2)}{2} = \frac{t}{2} + \frac{\ln(t)}{2} + c_1$$

Raising both side to exponential gives

$$\frac{1}{\sqrt{x^2-2}} = e^{\frac{t}{2} + \frac{\ln(t)}{2} + c_1}$$

Which simplifies to

$$\frac{1}{\sqrt{x^2-2}} = c_2 e^{\frac{t}{2} + \frac{\ln(t)}{2}}$$

The solution is

$$\frac{1}{\sqrt{x^2-2}} = c_2 e^{\frac{t}{2} + \frac{\ln(t)}{2} + c_1}$$

Summary

The solution(s) found are the following

$$\frac{1}{\sqrt{x^2-2}} = c_2 e^{\frac{t}{2} + \frac{\ln(t)}{2} + c_1} \tag{1}$$

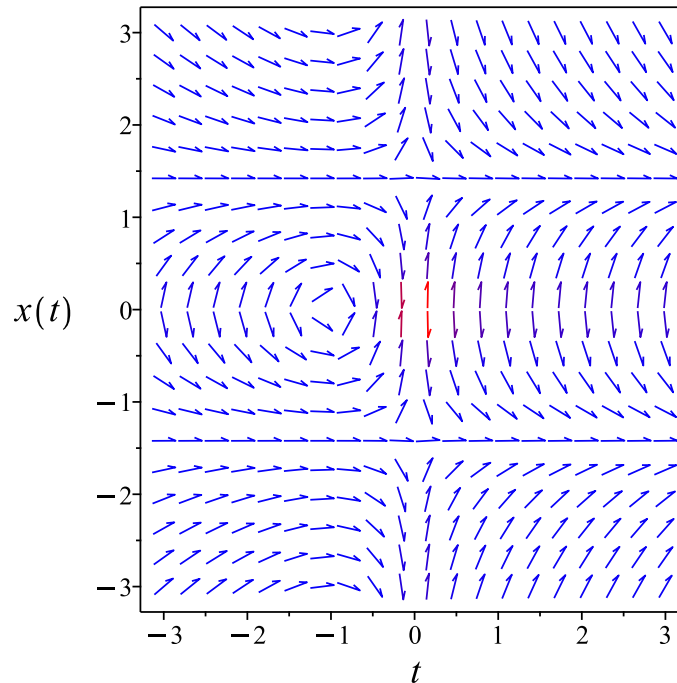


Figure 201: Slope field plot

Verification of solutions

$$\frac{1}{\sqrt{x^2 - 2}} = c_2 e^{\frac{t}{2} + \frac{\ln(t)}{2} + c_1}$$

Verified OK.

5.18.2 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$x' = -\frac{t x^2 + x^2 - 2t - 2}{2tx}$$
$$x' = \omega(t, x)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_t + \omega(\eta_x - \xi_t) - \omega^2 \xi_x - \omega_t \xi - \omega_x \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **separable**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 159: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(t, x) &= \frac{2t}{1+t} \\ \eta(t, x) &= 0\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(t, x) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dt}{\xi} = \frac{dx}{\eta} = dS\tag{1}$$

The above comes from the requirements that $(\xi \frac{\partial}{\partial t} + \eta \frac{\partial}{\partial x}) S(t, x) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\eta = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\xi} dt \\ &= \int \frac{1}{\frac{2t}{1+t}} dt \end{aligned}$$

Which results in

$$S = \frac{t}{2} + \frac{\ln(t)}{2}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_t + \omega(t, x)S_x}{R_t + \omega(t, x)R_x} \quad (2)$$

Where in the above R_t, R_x, S_t, S_x are all partial derivatives and $\omega(t, x)$ is the right hand side of the original ode given by

$$\omega(t, x) = -\frac{t x^2 + x^2 - 2t - 2}{2tx}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_t &= 0 \\ R_x &= 1 \\ S_t &= \frac{1+t}{2t} \\ S_x &= 0 \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = -\frac{x}{x^2 - 2} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for t, x in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = -\frac{R}{R^2 - 2}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = -\frac{\ln(R^2 - 2)}{2} + c_1 \quad (4)$$

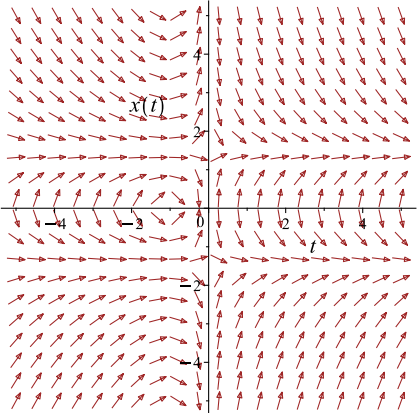
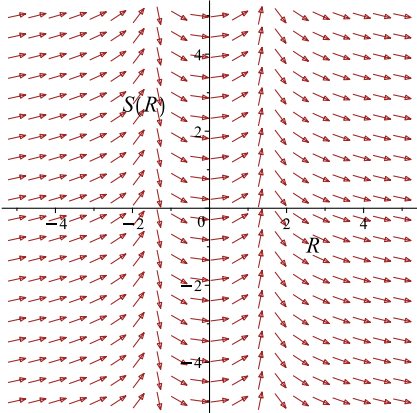
To complete the solution, we just need to transform (4) back to t, x coordinates. This results in

$$\frac{t}{2} + \frac{\ln(t)}{2} = -\frac{\ln(x^2 - 2)}{2} + c_1$$

Which simplifies to

$$\frac{t}{2} + \frac{\ln(t)}{2} = -\frac{\ln(x^2 - 2)}{2} + c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in t, x coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dx}{dt} = -\frac{tx^2 + x^2 - 2t - 2}{2tx}$ 	$R = x$ $S = \frac{t}{2} + \frac{\ln(t)}{2}$	$\frac{dS}{dR} = -\frac{R}{R^2 - 2}$ 

Summary

The solution(s) found are the following

$$\frac{t}{2} + \frac{\ln(t)}{2} = -\frac{\ln(x^2 - 2)}{2} + c_1 \quad (1)$$

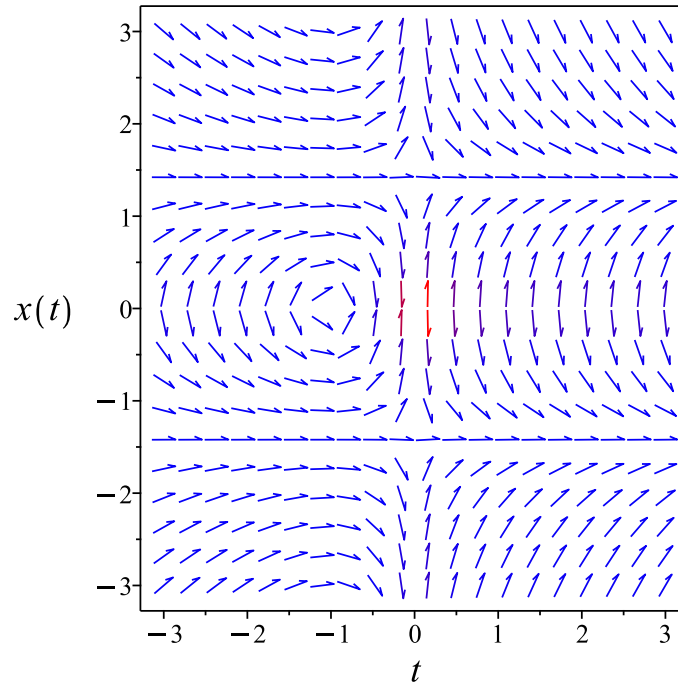


Figure 202: Slope field plot

Verification of solutions

$$\frac{t}{2} + \frac{\ln(t)}{2} = -\frac{\ln(x^2 - 2)}{2} + c_1$$

Verified OK.

5.18.3 Solving as bernoulli ode

In canonical form, the ODE is

$$\begin{aligned} x' &= F(t, x) \\ &= -\frac{t x^2 + x^2 - 2t - 2}{2tx} \end{aligned}$$

This is a Bernoulli ODE.

$$x' = -\frac{1+t}{2t}x - \frac{-2t-2}{2t} \frac{1}{x} \quad (1)$$

The standard Bernoulli ODE has the form

$$x' = f_0(t)x + f_1(t)x^n \quad (2)$$

The first step is to divide the above equation by x^n which gives

$$\frac{x'}{x^n} = f_0(t)x^{1-n} + f_1(t) \quad (3)$$

The next step is use the substitution $w = x^{1-n}$ in equation (3) which generates a new ODE in $w(t)$ which will be linear and can be easily solved using an integrating factor. Backsubstitution then gives the solution $x(t)$ which is what we want.

This method is now applied to the ODE at hand. Comparing the ODE (1) With (2) Shows that

$$\begin{aligned} f_0(t) &= -\frac{1+t}{2t} \\ f_1(t) &= -\frac{-2t-2}{2t} \\ n &= -1 \end{aligned}$$

Dividing both sides of ODE (1) by $x^n = \frac{1}{x}$ gives

$$x'x = -\frac{(1+t)x^2}{2t} - \frac{-2t-2}{2t} \quad (4)$$

Let

$$\begin{aligned} w &= x^{1-n} \\ &= x^2 \end{aligned} \quad (5)$$

Taking derivative of equation (5) w.r.t t gives

$$w' = 2xx' \quad (6)$$

Substituting equations (5) and (6) into equation (4) gives

$$\begin{aligned} \frac{w'(t)}{2} &= -\frac{(1+t)w(t)}{2t} - \frac{-2t-2}{2t} \\ w' &= -\frac{(1+t)w}{t} - \frac{-2t-2}{t} \end{aligned} \quad (7)$$

The above now is a linear ODE in $w(t)$ which is now solved.

Entering Linear first order ODE solver. In canonical form a linear first order is

$$w'(t) + p(t)w(t) = q(t)$$

Where here

$$\begin{aligned} p(t) &= -\frac{-1-t}{t} \\ q(t) &= \frac{2t+2}{t} \end{aligned}$$

Hence the ode is

$$w'(t) - \frac{(-1-t)w(t)}{t} = \frac{2t+2}{t}$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int -\frac{1-t}{t} dt} \\ &= e^{t+\ln(t)}\end{aligned}$$

Which simplifies to

$$\mu = t e^t$$

The ode becomes

$$\begin{aligned}\frac{d}{dt}(\mu w) &= (\mu) \left(\frac{2t+2}{t} \right) \\ \frac{d}{dt}(t e^t w) &= (t e^t) \left(\frac{2t+2}{t} \right) \\ d(t e^t w) &= (2 e^t(1+t)) dt\end{aligned}$$

Integrating gives

$$\begin{aligned}t e^t w &= \int 2 e^t(1+t) dt \\ t e^t w &= 2t e^t + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = t e^t$ results in

$$w(t) = 2 e^{-t} e^t + \frac{c_1 e^{-t}}{t}$$

which simplifies to

$$w(t) = \frac{c_1 e^{-t} + 2t}{t}$$

Replacing w in the above by x^2 using equation (5) gives the final solution.

$$x^2 = \frac{c_1 e^{-t} + 2t}{t}$$

Solving for x gives

$$\begin{aligned}x(t) &= \frac{\sqrt{t e^{-t} c_1 + 2t^2}}{t} \\ x(t) &= -\frac{\sqrt{t e^{-t} c_1 + 2t^2}}{t}\end{aligned}$$

Summary

The solution(s) found are the following

$$x = \frac{\sqrt{te^{-t}c_1 + 2t^2}}{t} \quad (1)$$

$$x = -\frac{\sqrt{te^{-t}c_1 + 2t^2}}{t} \quad (2)$$

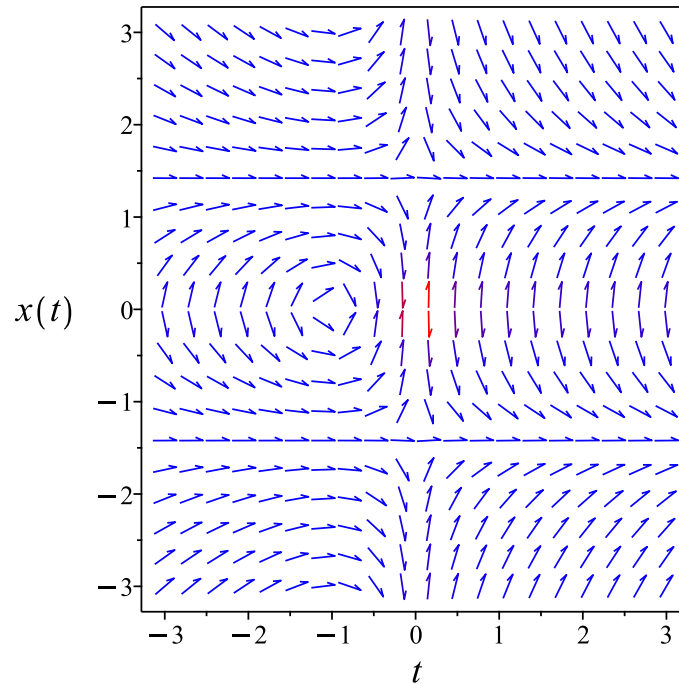


Figure 203: Slope field plot

Verification of solutions

$$x = \frac{\sqrt{te^{-t}c_1 + 2t^2}}{t}$$

Verified OK.

$$x = -\frac{\sqrt{te^{-t}c_1 + 2t^2}}{t}$$

Verified OK.

5.18.4 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \quad (\text{A})$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx}\phi(x, y) = 0$$

Hence

$$\frac{\partial\phi}{\partial x} + \frac{\partial\phi}{\partial y} \frac{dy}{dx} = 0 \quad (\text{B})$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial\phi}{\partial x} &= M \\ \frac{\partial\phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(t, x) dt + N(t, x) dx = 0 \quad (\text{1A})$$

Therefore

$$\begin{aligned} \left(\frac{2x}{-x^2+2}\right) dx &= \left(\frac{1+t}{t}\right) dt \\ \left(-\frac{1+t}{t}\right) dt &+ \left(\frac{2x}{-x^2+2}\right) dx = 0 \end{aligned} \quad (\text{2A})$$

Comparing (1A) and (2A) shows that

$$M(t, x) = -\frac{1+t}{t}$$
$$N(t, x) = \frac{2x}{-x^2+2}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial x} = \frac{\partial N}{\partial t}$$

Using result found above gives

$$\frac{\partial M}{\partial x} = \frac{\partial}{\partial x} \left(-\frac{1+t}{t} \right)$$
$$= 0$$

And

$$\frac{\partial N}{\partial t} = \frac{\partial}{\partial t} \left(\frac{2x}{-x^2+2} \right)$$
$$= 0$$

Since $\frac{\partial M}{\partial x} = \frac{\partial N}{\partial t}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(t, x)$

$$\frac{\partial \phi}{\partial t} = M \tag{1}$$

$$\frac{\partial \phi}{\partial x} = N \tag{2}$$

Integrating (1) w.r.t. t gives

$$\int \frac{\partial \phi}{\partial t} dt = \int M dt$$
$$\int \frac{\partial \phi}{\partial t} dt = \int -\frac{1+t}{t} dt$$
$$\phi = -t - \ln(t) + f(x) \tag{3}$$

Where $f(x)$ is used for the constant of integration since ϕ is a function of both t and x . Taking derivative of equation (3) w.r.t x gives

$$\frac{\partial \phi}{\partial x} = 0 + f'(x) \tag{4}$$

But equation (2) says that $\frac{\partial \phi}{\partial x} = \frac{2x}{-x^2+2}$. Therefore equation (4) becomes

$$\frac{2x}{-x^2+2} = 0 + f'(x) \quad (5)$$

Solving equation (5) for $f'(x)$ gives

$$f'(x) = -\frac{2x}{x^2-2}$$

Integrating the above w.r.t x gives

$$\int f'(x) dx = \int \left(-\frac{2x}{x^2-2} \right) dx$$
$$f(x) = -\ln(x^2-2) + c_1$$

Where c_1 is constant of integration. Substituting result found above for $f(x)$ into equation (3) gives ϕ

$$\phi = -t - \ln(t) - \ln(x^2-2) + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -t - \ln(t) - \ln(x^2-2)$$

Summary

The solution(s) found are the following

$$-t - \ln(t) - \ln(x^2-2) = c_1 \quad (1)$$

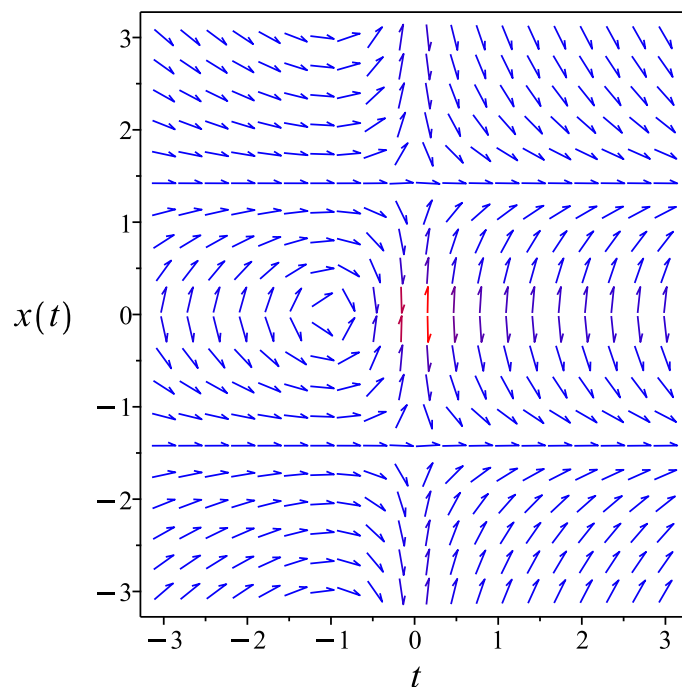


Figure 204: Slope field plot

Verification of solutions

$$-t - \ln(t) - \ln(x^2 - 2) = c_1$$

Verified OK.

5.18.5 Maple step by step solution

Let's solve

$$x' + \frac{(1+t)x}{2t} - \frac{1+t}{xt} = 0$$

- Highest derivative means the order of the ODE is 1

x'

- Separate variables

$$\frac{x'x}{x^2-2} = -\frac{1+t}{2t}$$

- Integrate both sides with respect to t

$$\int \frac{x'x}{x^2-2} dt = \int -\frac{1+t}{2t} dt + c_1$$

- Evaluate integral

$$\frac{\ln(x^2-2)}{2} = -\frac{t}{2} - \frac{\ln(t)}{2} + c_1$$

- Solve for x

$$\left\{ x = \frac{\sqrt{t(e^{-t+2c_1}+2t)}}{t}, x = -\frac{\sqrt{t(e^{-t+2c_1}+2t)}}{t} \right\}$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
<- Bernoulli successful`

```

✓ Solution by Maple

Time used: 0.031 (sec). Leaf size: 46

```
dsolve(diff(x(t),t)+(t+1)/(2*t)*x(t)=(t+1)/(x(t)*t),x(t), singsol=all)
```

$$x(t) = \frac{\sqrt{te^{-t}c_1 + 2t^2}}{t}$$

$$x(t) = -\frac{\sqrt{te^{-t}c_1 + 2t^2}}{t}$$

✓ Solution by Mathematica

Time used: 3.335 (sec). Leaf size: 78

```
DSolve[x'[t]+(t+1)/(2*t)*x[t]==(t+1)/(x[t]*t),x[t],t,IncludeSingularSolutions -> True]
```

$$x(t) \rightarrow -\frac{\sqrt{2t + e^{-t+2c_1}}}{\sqrt{t}}$$

$$x(t) \rightarrow \frac{\sqrt{2t + e^{-t+2c_1}}}{\sqrt{t}}$$

$$x(t) \rightarrow -\sqrt{2}$$

$$x(t) \rightarrow \sqrt{2}$$

5.19 problem 19

5.19.1 Existence and uniqueness analysis	1021
5.19.2 Solving as linear ode	1022
5.19.3 Solving as first order ode lie symmetry lookup ode	1023
5.19.4 Solving as exact ode	1027
5.19.5 Maple step by step solution	1032

Internal problem ID [11656]

Internal file name [OUTPUT/11665_Wednesday_April_10_2024_04_53_59_PM_19754612/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.3 (Linear equations). Exercises page 56

Problem number: 19.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**linear**", "**exactWithIntegrationFactor**", "**first_order_ode_lie_symmetry_lookup**"

Maple gives the following as the ode type

`[_linear]`

$$y'x - 2y = 2x^4$$

With initial conditions

$$[y(2) = 8]$$

5.19.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = -\frac{2}{x}$$
$$q(x) = 2x^3$$

Hence the ode is

$$y' - \frac{2y}{x} = 2x^3$$

The domain of $p(x) = -\frac{2}{x}$ is

$$\{x < 0 \vee 0 < x\}$$

And the point $x_0 = 2$ is inside this domain. The domain of $q(x) = 2x^3$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 2$ is also inside this domain. Hence solution exists and is unique.

5.19.2 Solving as linear ode

Entering Linear first order ODE solver. The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int -\frac{2}{x} dx} \\ &= \frac{1}{x^2}\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu y) &= (\mu) (2x^3) \\ \frac{d}{dx}\left(\frac{y}{x^2}\right) &= \left(\frac{1}{x^2}\right) (2x^3) \\ d\left(\frac{y}{x^2}\right) &= (2x) dx\end{aligned}$$

Integrating gives

$$\begin{aligned}\frac{y}{x^2} &= \int 2x dx \\ \frac{y}{x^2} &= x^2 + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = \frac{1}{x^2}$ results in

$$y = x^4 + c_1 x^2$$

Initial conditions are used to solve for c_1 . Substituting $x = 2$ and $y = 8$ in the above solution gives an equation to solve for the constant of integration.

$$8 = 16 + 4c_1$$

$$c_1 = -2$$

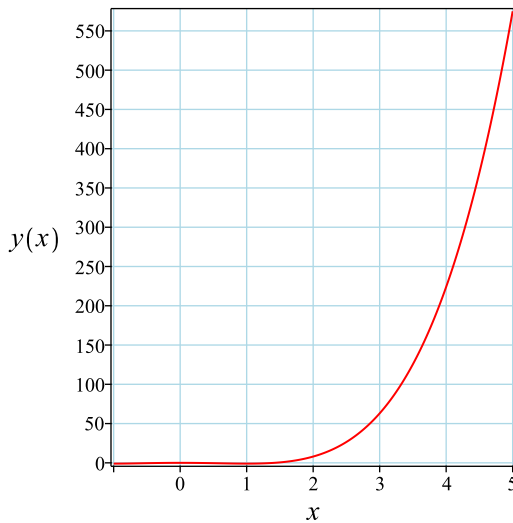
Substituting c_1 found above in the general solution gives

$$y = x^4 - 2x^2$$

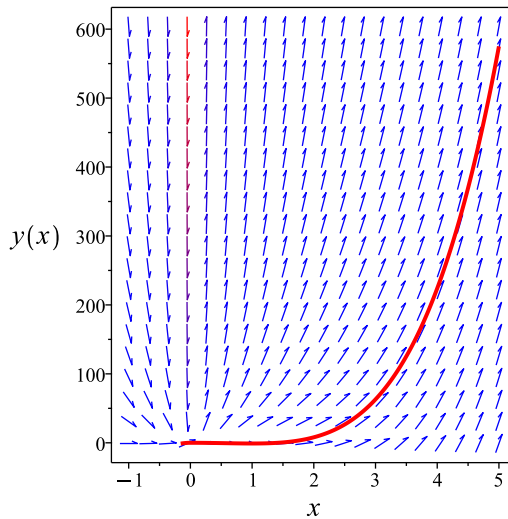
Summary

The solution(s) found are the following

$$y = x^4 - 2x^2 \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = x^4 - 2x^2$$

Verified OK.

5.19.3 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = \frac{2x^4 + 2y}{x}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \tag{A}$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 162: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= x^2\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{x^2} dy \end{aligned}$$

Which results in

$$S = \frac{y}{x^2}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = \frac{2x^4 + 2y}{x}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= -\frac{2y}{x^3} \\ S_y &= \frac{1}{x^2} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 2x \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 2R$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = R^2 + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$\frac{y}{x^2} = x^2 + c_1$$

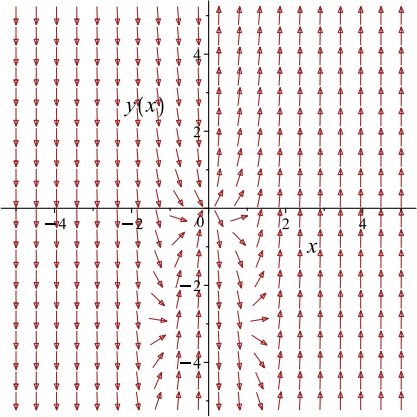
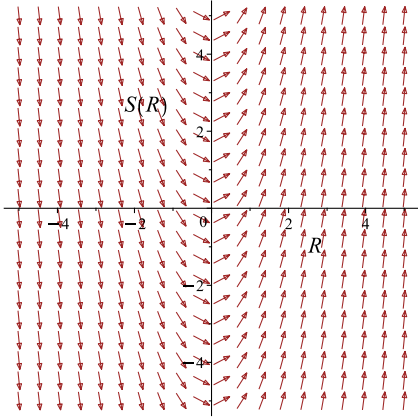
Which simplifies to

$$\frac{y}{x^2} = x^2 + c_1$$

Which gives

$$y = x^2(x^2 + c_1)$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = \frac{2x^4 + 2y}{x}$ 	$R = x$ $S = \frac{y}{x^2}$	$\frac{dS}{dR} = 2R$ 

Initial conditions are used to solve for c_1 . Substituting $x = 2$ and $y = 8$ in the above solution gives an equation to solve for the constant of integration.

$$8 = 16 + 4c_1$$

$$c_1 = -2$$

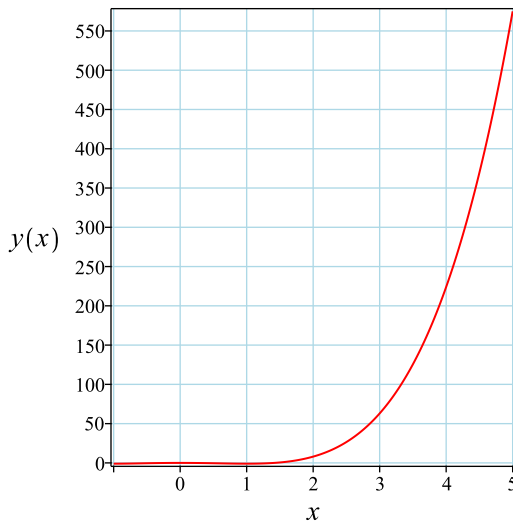
Substituting c_1 found above in the general solution gives

$$y = x^2(x^2 - 2)$$

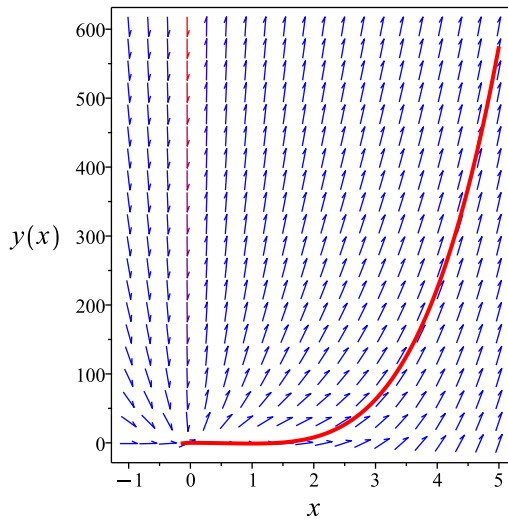
Summary

The solution(s) found are the following

$$y = x^2(x^2 - 2) \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = x^2(x^2 - 2)$$

Verified OK.

5.19.4 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx}\phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \quad (\text{B})$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (\text{1A})$$

Therefore

$$\begin{aligned} (x) dy &= (2x^4 + 2y) dx \\ (-2x^4 - 2y) dx + (x) dy &= 0 \end{aligned} \quad (\text{2A})$$

Comparing (1A) and (2A) shows that

$$\begin{aligned} M(x, y) &= -2x^4 - 2y \\ N(x, y) &= x \end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned} \frac{\partial M}{\partial y} &= \frac{\partial}{\partial y} (-2x^4 - 2y) \\ &= -2 \end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(x) \\ &= 1\end{aligned}$$

Since $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$\begin{aligned}A &= \frac{1}{N} \left(\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} \right) \\ &= \frac{1}{x} ((-2) - (1)) \\ &= -\frac{3}{x}\end{aligned}$$

Since A does not depend on y , then it can be used to find an integrating factor. The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int A \, dx} \\ &= e^{\int -\frac{3}{x} \, dx}\end{aligned}$$

The result of integrating gives

$$\begin{aligned}\mu &= e^{-3 \ln(x)} \\ &= \frac{1}{x^3}\end{aligned}$$

M and N are multiplied by this integrating factor, giving new M and new N which are called \bar{M} and \bar{N} for now so not to confuse them with the original M and N .

$$\begin{aligned}\bar{M} &= \mu M \\ &= \frac{1}{x^3} (-2x^4 - 2y) \\ &= \frac{-2x^4 - 2y}{x^3}\end{aligned}$$

And

$$\begin{aligned}\bar{N} &= \mu N \\ &= \frac{1}{x^3}(x) \\ &= \frac{1}{x^2}\end{aligned}$$

Now a modified ODE is obtained from the original ODE, which is exact and can be solved. The modified ODE is

$$\begin{aligned} \overline{M} + \overline{N} \frac{dy}{dx} &= 0 \\ \left(\frac{-2x^4 - 2y}{x^3} \right) + \left(\frac{1}{x^2} \right) \frac{dy}{dx} &= 0 \end{aligned}$$

The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = \overline{M} \tag{1}$$

$$\frac{\partial \phi}{\partial y} = \overline{N} \tag{2}$$

Integrating (1) w.r.t. x gives

$$\begin{aligned} \int \frac{\partial \phi}{\partial x} dx &= \int \overline{M} dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int \frac{-2x^4 - 2y}{x^3} dx \\ \phi &= \frac{-x^4 + y}{x^2} + f(y) \end{aligned} \tag{3}$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = \frac{1}{x^2} + f'(y) \tag{4}$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = \frac{1}{x^2}$. Therefore equation (4) becomes

$$\frac{1}{x^2} = \frac{1}{x^2} + f'(y) \tag{5}$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 0$$

Therefore

$$f(y) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(y)$ into equation (3) gives ϕ

$$\phi = \frac{-x^4 + y}{x^2} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = \frac{-x^4 + y}{x^2}$$

The solution becomes

$$y = x^2(x^2 + c_1)$$

Initial conditions are used to solve for c_1 . Substituting $x = 2$ and $y = 8$ in the above solution gives an equation to solve for the constant of integration.

$$8 = 16 + 4c_1$$

$$c_1 = -2$$

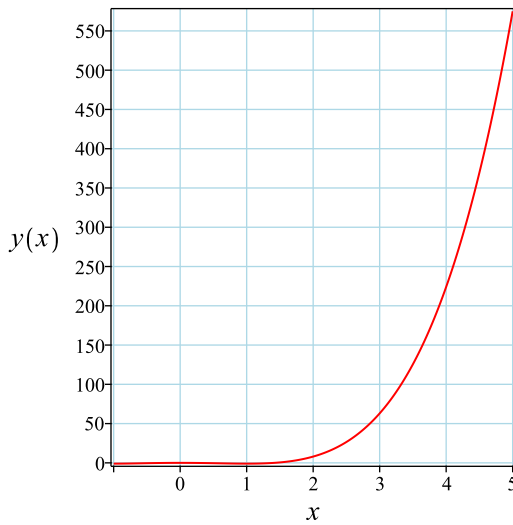
Substituting c_1 found above in the general solution gives

$$y = x^2(x^2 - 2)$$

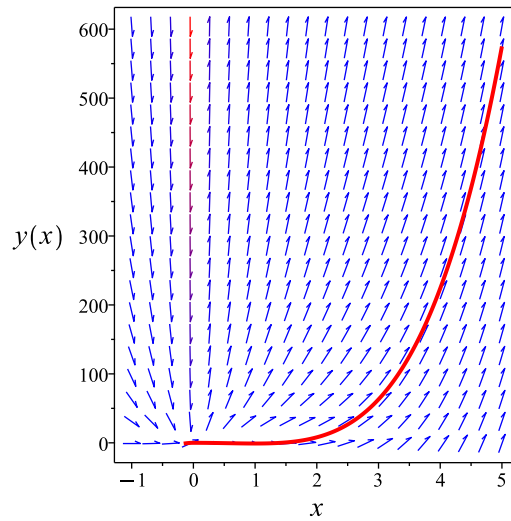
Summary

The solution(s) found are the following

$$y = x^2(x^2 - 2) \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = x^2(x^2 - 2)$$

Verified OK.

5.19.5 Maple step by step solution

Let's solve

$$[y'x - 2y = 2x^4, y(2) = 8]$$

- Highest derivative means the order of the ODE is 1

$$y'$$

- Isolate the derivative

$$y' = \frac{2y}{x} + 2x^3$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE

$$y' - \frac{2y}{x} = 2x^3$$

- The ODE is linear; multiply by an integrating factor $\mu(x)$

$$\mu(x) \left(y' - \frac{2y}{x} \right) = 2\mu(x) x^3$$

- Assume the lhs of the ODE is the total derivative $\frac{d}{dx}(\mu(x)y)$

$$\mu(x) \left(y' - \frac{2y}{x} \right) = \mu'(x)y + \mu(x)y'$$

- Isolate $\mu'(x)$

$$\mu'(x) = -\frac{2\mu(x)}{x}$$
- Solve to find the integrating factor

$$\mu(x) = \frac{1}{x^2}$$
- Integrate both sides with respect to x

$$\int \left(\frac{d}{dx}(\mu(x)y) \right) dx = \int 2\mu(x)x^3 dx + c_1$$
- Evaluate the integral on the lhs

$$\mu(x)y = \int 2\mu(x)x^3 dx + c_1$$
- Solve for y

$$y = \frac{\int 2\mu(x)x^3 dx + c_1}{\mu(x)}$$
- Substitute $\mu(x) = \frac{1}{x^2}$

$$y = x^2 \left(\int 2x dx + c_1 \right)$$
- Evaluate the integrals on the rhs

$$y = x^2(x^2 + c_1)$$
- Use initial condition $y(2) = 8$

$$8 = 16 + 4c_1$$
- Solve for c_1

$$c_1 = -2$$
- Substitute $c_1 = -2$ into general solution and simplify

$$y = x^2(x^2 - 2)$$
- Solution to the IVP

$$y = x^2(x^2 - 2)$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
<- 1st order linear successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 13

```
dsolve([x*diff(y(x),x)-2*y(x)=2*x^4,y(2) = 8],y(x), singsol=all)
```

$$y(x) = (x^2 - 2) x^2$$

✓ Solution by Mathematica

Time used: 0.043 (sec). Leaf size: 14

```
DSolve[{x*y'[x]-2*y[x]==2*x^4,{y[2]==8}},y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow x^2(x^2 - 2)$$

5.20 problem 20

5.20.1 Existence and uniqueness analysis	1035
5.20.2 Solving as separable ode	1036
5.20.3 Solving as linear ode	1038
5.20.4 Solving as first order ode lie symmetry lookup ode	1039
5.20.5 Solving as exact ode	1044
5.20.6 Maple step by step solution	1047

Internal problem ID [11657]

Internal file name [OUTPUT/11666_Wednesday_April_10_2024_04_54_01_PM_33212483/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.3 (Linear equations). Exercises page 56

Problem number: 20.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact", "linear", "separable", "first_order_ode_lie_symmetry_lookup"

Maple gives the following as the ode type

[_separable]

$$y' + 3x^2y = x^2$$

With initial conditions

$$[y(0) = 2]$$

5.20.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = 3x^2$$

$$q(x) = x^2$$

Hence the ode is

$$y' + 3x^2y = x^2$$

The domain of $p(x) = 3x^2$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = x^2$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

5.20.2 Solving as separable ode

In canonical form the ODE is

$$\begin{aligned}y' &= F(x, y) \\ &= f(x)g(y) \\ &= x^2(-3y + 1)\end{aligned}$$

Where $f(x) = x^2$ and $g(y) = -3y + 1$. Integrating both sides gives

$$\begin{aligned}\frac{1}{-3y + 1} dy &= x^2 dx \\ \int \frac{1}{-3y + 1} dy &= \int x^2 dx \\ -\frac{\ln(-3y + 1)}{3} &= \frac{x^3}{3} + c_1\end{aligned}$$

Raising both side to exponential gives

$$\frac{1}{(-3y + 1)^{\frac{1}{3}}} = e^{\frac{x^3}{3} + c_1}$$

Which simplifies to

$$\frac{1}{(-3y + 1)^{\frac{1}{3}}} = c_2 e^{\frac{x^3}{3}}$$

Initial conditions are used to solve for c_1 . Substituting $x = 0$ and $y = 2$ in the above solution gives an equation to solve for the constant of integration.

$$2 = \frac{e^{-3c_1} e^{3c_1} c_2^3 - e^{-3c_1}}{3c_2^3}$$

$$c_1 = -\frac{\ln(-5c_2^3)}{3}$$

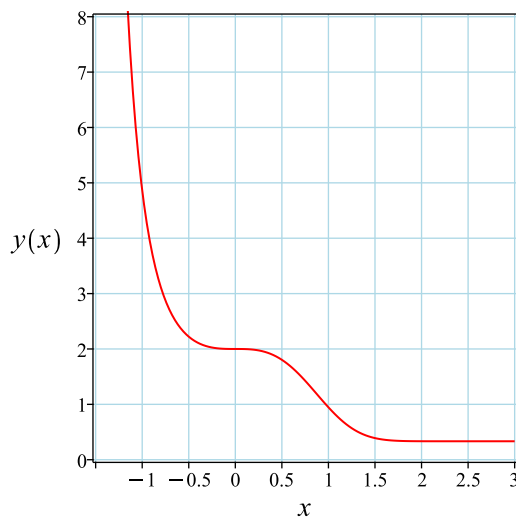
Substituting c_1 found above in the general solution gives

$$y = \frac{1}{3} + \frac{5e^{-x^3}}{3}$$

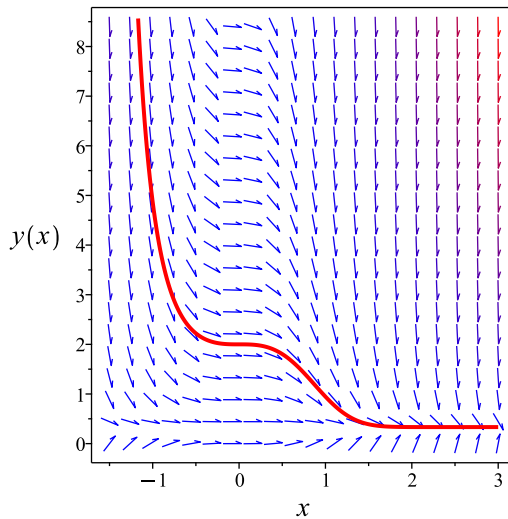
Summary

The solution(s) found are the following

$$y = \frac{1}{3} + \frac{5e^{-x^3}}{3} \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \frac{1}{3} + \frac{5e^{-x^3}}{3}$$

Verified OK.

5.20.3 Solving as linear ode

Entering Linear first order ODE solver. The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int 3x^2 dx} \\ &= e^{x^3}\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu y) &= (\mu)(x^2) \\ \frac{d}{dx}(e^{x^3} y) &= (e^{x^3})(x^2) \\ d(e^{x^3} y) &= (x^2 e^{x^3}) dx\end{aligned}$$

Integrating gives

$$\begin{aligned}e^{x^3} y &= \int x^2 e^{x^3} dx \\ e^{x^3} y &= \frac{e^{x^3}}{3} + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = e^{x^3}$ results in

$$y = \frac{e^{-x^3} e^{x^3}}{3} + c_1 e^{-x^3}$$

which simplifies to

$$y = \frac{1}{3} + c_1 e^{-x^3}$$

Initial conditions are used to solve for c_1 . Substituting $x = 0$ and $y = 2$ in the above solution gives an equation to solve for the constant of integration.

$$2 = c_1 + \frac{1}{3}$$

$$c_1 = \frac{5}{3}$$

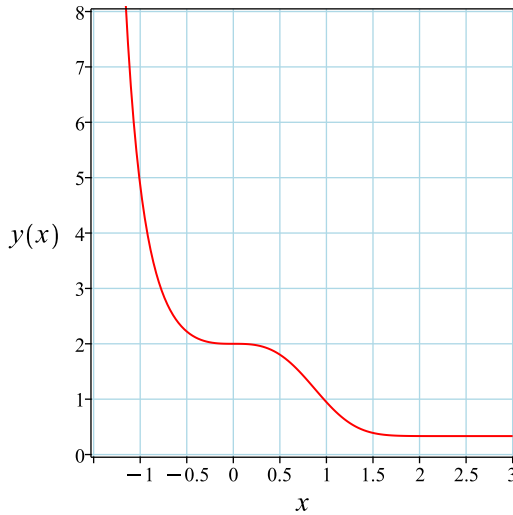
Substituting c_1 found above in the general solution gives

$$y = \frac{1}{3} + \frac{5 e^{-x^3}}{3}$$

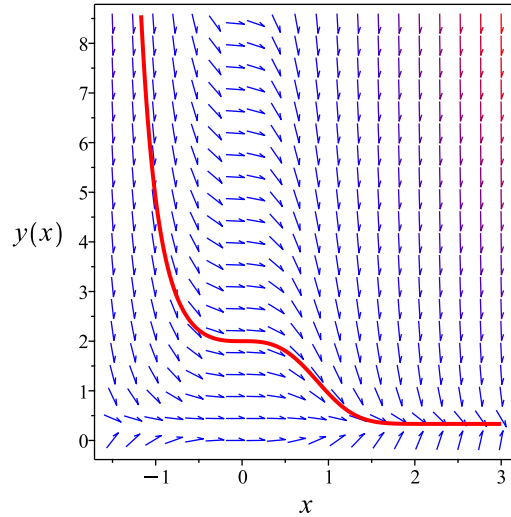
Summary

The solution(s) found are the following

$$y = \frac{1}{3} + \frac{5e^{-x^3}}{3} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \frac{1}{3} + \frac{5e^{-x^3}}{3}$$

Verified OK.

5.20.4 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = -3x^2y + x^2$$
$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (A)$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 165: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int(n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= e^{-x^3}\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{e^{-x^3}} dy \end{aligned}$$

Which results in

$$S = e^{x^3} y$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -3x^2y + x^2$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= 3x^2e^{x^3}y \\ S_y &= e^{x^3} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = x^2e^{x^3} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = R^2e^{R^3}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by

integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = \frac{e^{R^3}}{3} + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$e^{x^3} y = \frac{e^{x^3}}{3} + c_1$$

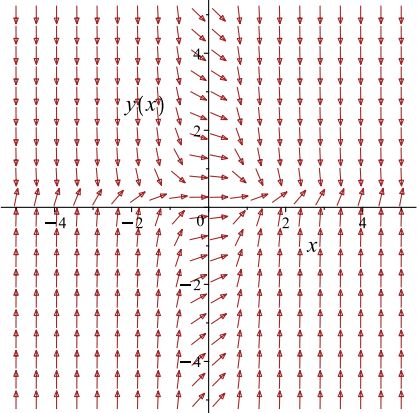
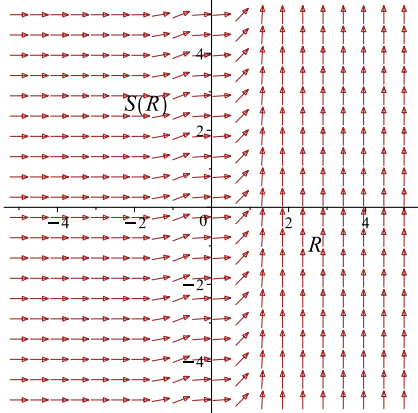
Which simplifies to

$$e^{x^3} y = \frac{e^{x^3}}{3} + c_1$$

Which gives

$$y = \frac{(e^{x^3} + 3c_1) e^{-x^3}}{3}$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -3x^2 y + x^2$ 	$R = x$ $S = e^{x^3} y$	$\frac{dS}{dR} = R^2 e^{R^3}$ 

Initial conditions are used to solve for c_1 . Substituting $x = 0$ and $y = 2$ in the above solution gives an equation to solve for the constant of integration.

$$2 = c_1 + \frac{1}{3}$$

$$c_1 = \frac{5}{3}$$

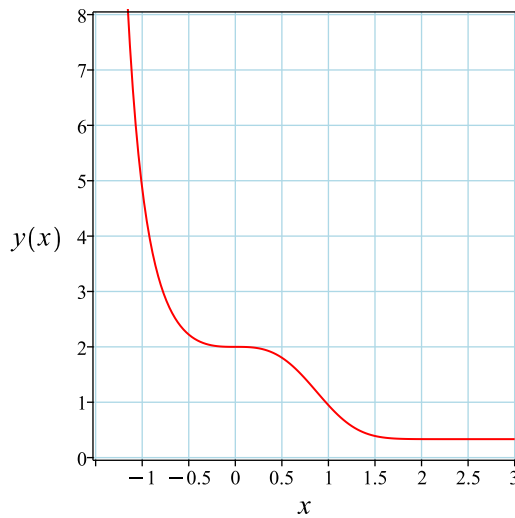
Substituting c_1 found above in the general solution gives

$$y = \frac{1}{3} + \frac{5e^{-x^3}}{3}$$

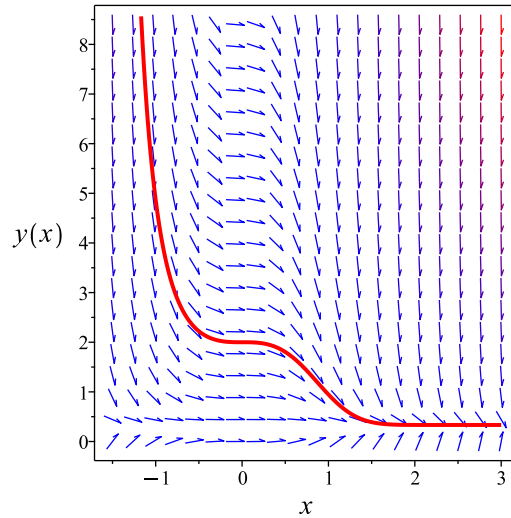
Summary

The solution(s) found are the following

$$y = \frac{1}{3} + \frac{5e^{-x^3}}{3} \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \frac{1}{3} + \frac{5e^{-x^3}}{3}$$

Verified OK.

5.20.5 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \quad (\text{A})$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \quad (\text{B})$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (\text{1A})$$

Therefore

$$\begin{aligned} \left(\frac{1}{-3y+1} \right) dy &= (x^2) dx \\ (-x^2) dx + \left(\frac{1}{-3y+1} \right) dy &= 0 \end{aligned} \quad (\text{2A})$$

Comparing (1A) and (2A) shows that

$$M(x, y) = -x^2$$
$$N(x, y) = \frac{1}{-3y + 1}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\frac{\partial M}{\partial y} = \frac{\partial}{\partial y}(-x^2)$$
$$= 0$$

And

$$\frac{\partial N}{\partial x} = \frac{\partial}{\partial x} \left(\frac{1}{-3y + 1} \right)$$
$$= 0$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \tag{1}$$

$$\frac{\partial \phi}{\partial y} = N \tag{2}$$

Integrating (1) w.r.t. x gives

$$\int \frac{\partial \phi}{\partial x} dx = \int M dx$$

$$\int \frac{\partial \phi}{\partial x} dx = \int -x^2 dx$$

$$\phi = -\frac{x^3}{3} + f(y) \tag{3}$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = 0 + f'(y) \tag{4}$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = \frac{1}{-3y+1}$. Therefore equation (4) becomes

$$\frac{1}{-3y+1} = 0 + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = -\frac{1}{3y-1}$$

Integrating the above w.r.t y gives

$$\begin{aligned} \int f'(y) \, dy &= \int \left(-\frac{1}{3y-1} \right) \, dy \\ f(y) &= -\frac{\ln(3y-1)}{3} + c_1 \end{aligned}$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = -\frac{x^3}{3} - \frac{\ln(3y-1)}{3} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -\frac{x^3}{3} - \frac{\ln(3y-1)}{3}$$

The solution becomes

$$y = \frac{e^{-x^3-3c_1}}{3} + \frac{1}{3}$$

Initial conditions are used to solve for c_1 . Substituting $x = 0$ and $y = 2$ in the above solution gives an equation to solve for the constant of integration.

$$2 = \frac{e^{-3c_1}}{3} + \frac{1}{3}$$

$$c_1 = -\frac{\ln(5)}{3}$$

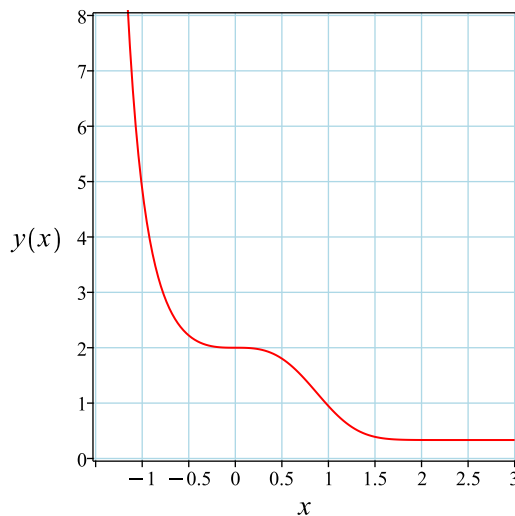
Substituting c_1 found above in the general solution gives

$$y = \frac{1}{3} + \frac{5e^{-x^3}}{3}$$

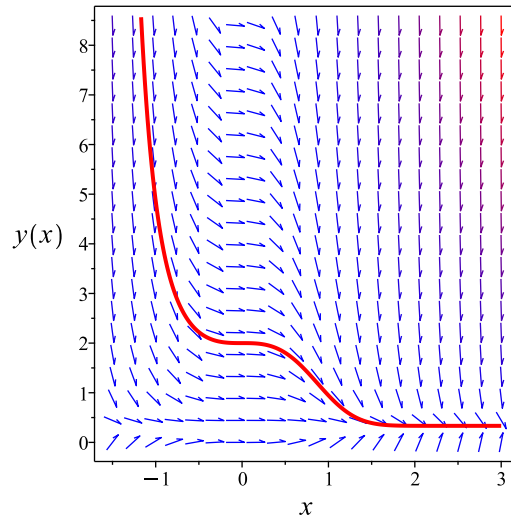
Summary

The solution(s) found are the following

$$y = \frac{1}{3} + \frac{5e^{-x^3}}{3} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \frac{1}{3} + \frac{5e^{-x^3}}{3}$$

Verified OK.

5.20.6 Maple step by step solution

Let's solve

$$[y' + 3x^2y = x^2, y(0) = 2]$$

- Highest derivative means the order of the ODE is 1
- y'
- Separate variables

$$\frac{y'}{3y-1} = -x^2$$

- Integrate both sides with respect to x

$$\int \frac{y'}{3y-1} dx = \int -x^2 dx + c_1$$

- Evaluate integral

$$\frac{\ln(3y-1)}{3} = -\frac{x^3}{3} + c_1$$

- Solve for y

$$y = \frac{e^{-x^3+3c_1}}{3} + \frac{1}{3}$$

- Use initial condition $y(0) = 2$

$$2 = \frac{e^{3c_1}}{3} + \frac{1}{3}$$

- Solve for c_1

$$c_1 = \frac{\ln(5)}{3}$$

- Substitute $c_1 = \frac{\ln(5)}{3}$ into general solution and simplify

$$y = \frac{1}{3} + \frac{5e^{-x^3}}{3}$$

- Solution to the IVP

$$y = \frac{1}{3} + \frac{5e^{-x^3}}{3}$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
<- 1st order linear successful`

```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 14

```
dsolve([diff(y(x),x)+3*x^2*y(x)=x^2,y(0) = 2],y(x), singsol=all)
```

$$y(x) = \frac{1}{3} + \frac{5e^{-x^3}}{3}$$

✓ Solution by Mathematica

Time used: 2.884 (sec). Leaf size: 20

```
DSolve[{y'[x]+3*x^2*y[x]==x^2,{y[0]==2}},y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{5e^{-x^3}}{3} + \frac{1}{3}$$

5.21 problem 21

5.21.1 Existence and uniqueness analysis	1050
5.21.2 Solving as linear ode	1051
5.21.3 Solving as first order ode lie symmetry lookup ode	1052
5.21.4 Solving as exact ode	1057
5.21.5 Maple step by step solution	1060

Internal problem ID [11658]

Internal file name [OUTPUT/11667_Wednesday_April_10_2024_04_54_02_PM_91574622/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.3 (Linear equations). Exercises page 56

Problem number: 21.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"exact", "linear", "first_order_ode_lie_symmetry_lookup"**

Maple gives the following as the ode type

`[_linear]`

$$e^x(y - 3(e^x + 1)^2) + (e^x + 1)y' = 0$$

With initial conditions

$$[y(0) = 4]$$

5.21.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = \frac{e^x}{e^x + 1}$$
$$q(x) = 3e^x(e^x + 1)$$

Hence the ode is

$$y' + \frac{e^x y}{e^x + 1} = 3 e^x (e^x + 1)$$

The domain of $p(x) = \frac{e^x}{e^x + 1}$ is

$$\{2i\pi - Z100 + i\pi < x\}$$

But the point $x_0 = 0$ is not inside this domain. Hence existence and uniqueness theorem does not apply. There could be infinite number of solutions, or one solution or no solution at all.

5.21.2 Solving as linear ode

Entering Linear first order ODE solver. The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int \frac{e^x}{e^x + 1} dx} \\ &= e^x + 1\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu y) &= (\mu) (3 e^x (e^x + 1)) \\ \frac{d}{dx}((e^x + 1) y) &= (e^x + 1) (3 e^x (e^x + 1)) \\ d((e^x + 1) y) &= (3 e^x (e^x + 1)^2) dx\end{aligned}$$

Integrating gives

$$\begin{aligned}(e^x + 1) y &= \int 3 e^x (e^x + 1)^2 dx \\ (e^x + 1) y &= (e^x + 1)^3 + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = e^x + 1$ results in

$$y = (e^x + 1)^2 + \frac{c_1}{e^x + 1}$$

Initial conditions are used to solve for c_1 . Substituting $x = 0$ and $y = 4$ in the above solution gives an equation to solve for the constant of integration.

$$4 = 4 + \frac{c_1}{2}$$

$$c_1 = 0$$

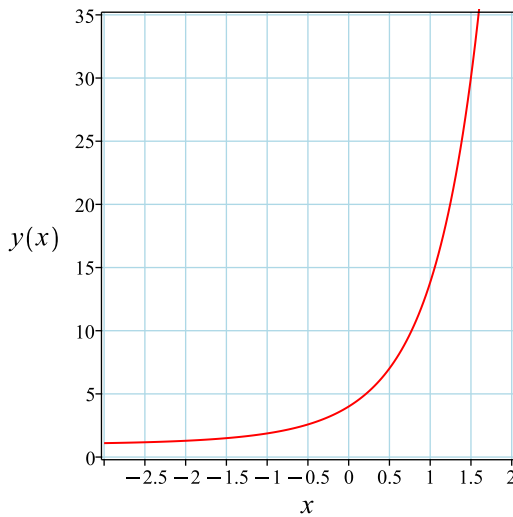
Substituting c_1 found above in the general solution gives

$$y = e^{2x} + 2e^x + 1$$

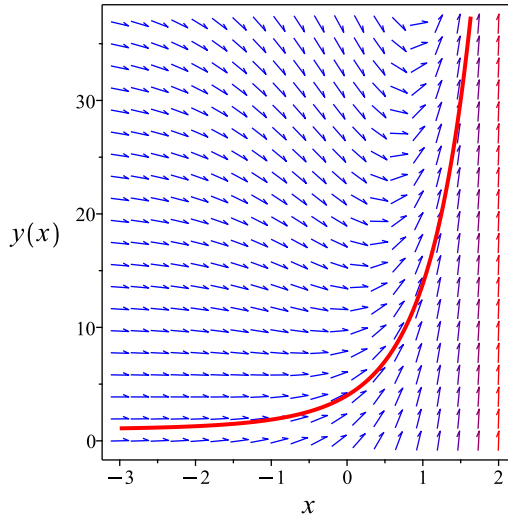
Summary

The solution(s) found are the following

$$y = e^{2x} + 2e^x + 1 \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = e^{2x} + 2e^x + 1$$

Verified OK.

5.21.3 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = \frac{e^x(3e^{2x} + 6e^x - y + 3)}{e^x + 1}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \tag{A}$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 168: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= \frac{1}{e^x + 1}\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{1}{e^x+1}} dy \end{aligned}$$

Which results in

$$S = (e^x + 1) y$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = \frac{e^x(3e^{2x} + 6e^x - y + 3)}{e^x + 1}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= e^x y \\ S_y &= e^x + 1 \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 6e^{2x} + 3e^{3x} + 3e^x \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 6e^{2R} + 3e^{3R} + 3e^R$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = 3e^{2R} + 3e^R + e^{3R} + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$(e^x + 1)y = e^{3x} + 3e^{2x} + 3e^x + c_1$$

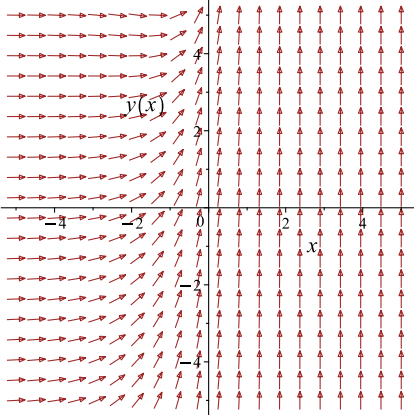
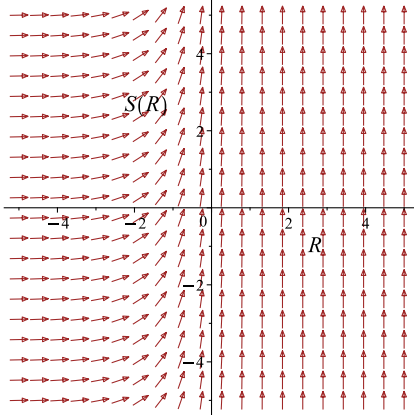
Which simplifies to

$$(e^x + 1)y = e^{3x} + 3e^{2x} + 3e^x + c_1$$

Which gives

$$y = \frac{e^{3x} + 3e^{2x} + 3e^x + c_1}{e^x + 1}$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = \frac{e^x(3e^{2x} + 6e^x - y + 3)}{e^x + 1}$ 	$R = x$ $S = (e^x + 1)y$	$\frac{dS}{dR} = 6e^{2R} + 3e^{3R} + 3e^R$ 

Initial conditions are used to solve for c_1 . Substituting $x = 0$ and $y = 4$ in the above solution gives an equation to solve for the constant of integration.

$$4 = \frac{7}{2} + \frac{c_1}{2}$$

$$c_1 = 1$$

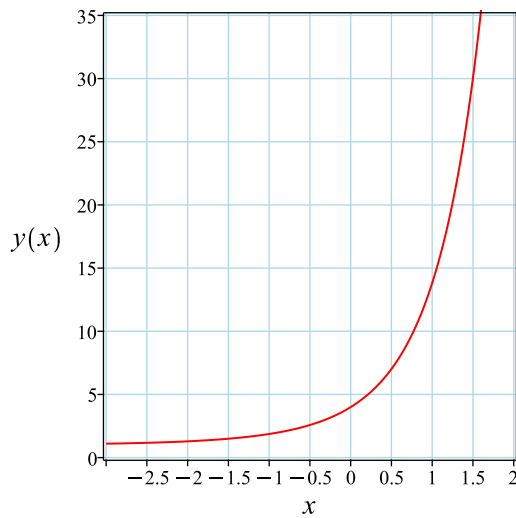
Substituting c_1 found above in the general solution gives

$$y = \frac{e^{3x} + 3e^{2x} + 3e^x + 1}{e^x + 1}$$

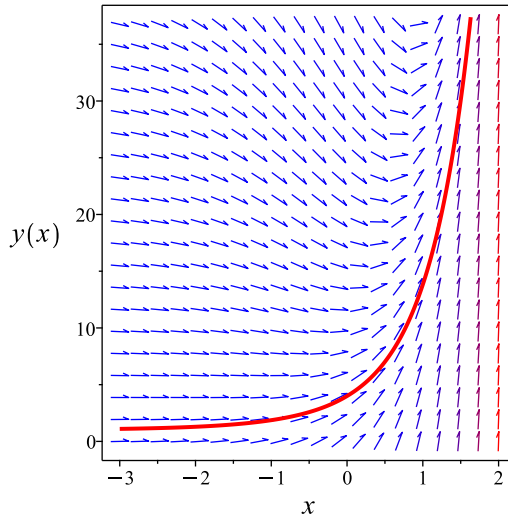
Summary

The solution(s) found are the following

$$y = \frac{e^{3x} + 3e^{2x} + 3e^x + 1}{e^x + 1} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \frac{e^{3x} + 3e^{2x} + 3e^x + 1}{e^x + 1}$$

Verified OK.

5.21.4 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \quad (\text{A})$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx}\phi(x, y) = 0$$

Hence

$$\frac{\partial\phi}{\partial x} + \frac{\partial\phi}{\partial y} \frac{dy}{dx} = 0 \quad (\text{B})$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial\phi}{\partial x} &= M \\ \frac{\partial\phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (\text{1A})$$

Therefore

$$\begin{aligned} (e^x + 1) dy &= (-e^x(y - 3(e^x + 1)^2)) dx \\ (e^x(y - 3(e^x + 1)^2)) dx &+ (e^x + 1) dy = 0 \end{aligned} \quad (\text{2A})$$

Comparing (1A) and (2A) shows that

$$\begin{aligned} M(x, y) &= e^x(y - 3(e^x + 1)^2) \\ N(x, y) &= e^x + 1 \end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(e^x(y - 3(e^x + 1)^2)) \\ &= e^x\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(e^x + 1) \\ &= e^x\end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \tag{1}$$

$$\frac{\partial \phi}{\partial y} = N \tag{2}$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int M dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int e^x(y - 3(e^x + 1)^2) dx \\ \phi &= -3e^{2x} - e^{3x} + (y - 3)e^x + f(y)\end{aligned} \tag{3}$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = e^x + f'(y) \tag{4}$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = e^x + 1$. Therefore equation (4) becomes

$$e^x + 1 = e^x + f'(y) \tag{5}$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 1$$

Integrating the above w.r.t y gives

$$\int f'(y) dy = \int (1) dy$$
$$f(y) = y + c_1$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = -3e^{2x} - e^{3x} + (y - 3)e^x + y + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -3e^{2x} - e^{3x} + (y - 3)e^x + y$$

The solution becomes

$$y = \frac{e^{3x} + 3e^{2x} + 3e^x + c_1}{e^x + 1}$$

Initial conditions are used to solve for c_1 . Substituting $x = 0$ and $y = 4$ in the above solution gives an equation to solve for the constant of integration.

$$4 = \frac{7}{2} + \frac{c_1}{2}$$

$$c_1 = 1$$

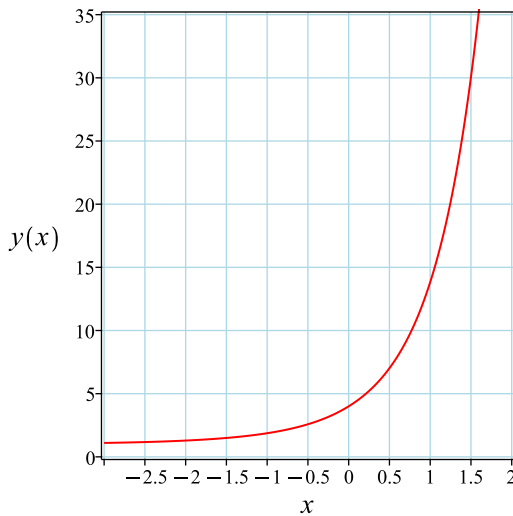
Substituting c_1 found above in the general solution gives

$$y = \frac{e^{3x} + 3e^{2x} + 3e^x + 1}{e^x + 1}$$

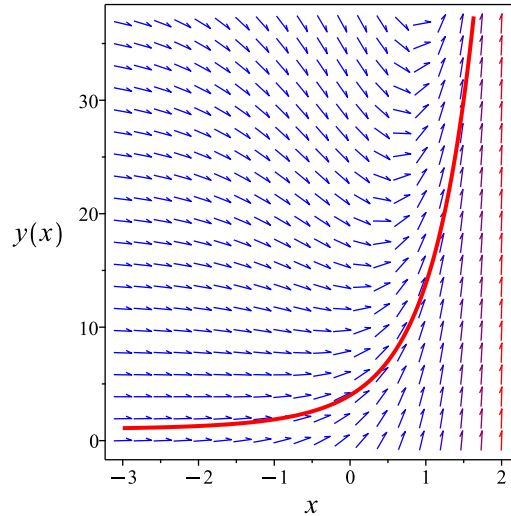
Summary

The solution(s) found are the following

$$y = \frac{e^{3x} + 3e^{2x} + 3e^x + 1}{e^x + 1} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \frac{e^{3x} + 3e^{2x} + 3e^x + 1}{e^x + 1}$$

Verified OK.

5.21.5 Maple step by step solution

Let's solve

$$[e^x(y - 3(e^x + 1)^2) + (e^x + 1)y' = 0, y(0) = 4]$$

- Highest derivative means the order of the ODE is 1

$$y'$$

- Isolate the derivative

$$y' = -\frac{e^x y}{e^x + 1} + 3e^x(e^x + 1)$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE

$$y' + \frac{e^x y}{e^x + 1} = 3e^x(e^x + 1)$$

- The ODE is linear; multiply by an integrating factor $\mu(x)$

$$\mu(x) \left(y' + \frac{e^x y}{e^x + 1} \right) = 3\mu(x) e^x(e^x + 1)$$

- Assume the lhs of the ODE is the total derivative $\frac{d}{dx}(\mu(x)y)$

$$\mu(x) \left(y' + \frac{e^x y}{e^x + 1} \right) = \mu'(x) y + \mu(x) y'$$

- Isolate $\mu'(x)$

$$\mu'(x) = \frac{\mu(x)e^x}{e^x + 1}$$

- Solve to find the integrating factor

$$\mu(x) = e^x + 1$$

- Integrate both sides with respect to x

$$\int \left(\frac{d}{dx}(\mu(x) y) \right) dx = \int 3\mu(x) e^x (e^x + 1) dx + c_1$$

- Evaluate the integral on the lhs

$$\mu(x) y = \int 3\mu(x) e^x (e^x + 1) dx + c_1$$

- Solve for y

$$y = \frac{\int 3\mu(x)e^x(e^x+1)dx+c_1}{\mu(x)}$$

- Substitute $\mu(x) = e^x + 1$

$$y = \frac{\int 3e^x(e^x+1)^2 dx+c_1}{e^x+1}$$

- Evaluate the integrals on the rhs

$$y = \frac{(e^x+1)^3+c_1}{e^x+1}$$

- Simplify

$$y = \frac{e^{3x}+3e^{2x}+3e^x+c_1+1}{e^x+1}$$

- Use initial condition $y(0) = 4$

$$4 = 4 + \frac{c_1}{2}$$

- Solve for c_1

$$c_1 = 0$$

- Substitute $c_1 = 0$ into general solution and simplify

$$y = e^{2x} + 2e^x + 1$$

- Solution to the IVP

$$y = e^{2x} + 2e^x + 1$$

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
<- 1st order linear successful`
```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 14

```
dsolve([exp(x)*(y(x)-3*(exp(x)+1)^2)+(exp(x)+1)*diff(y(x),x)=0,y(0) = 4],y(x), singsol=all)
```

$$y(x) = e^{2x} + 2e^x + 1$$

✓ Solution by Mathematica

Time used: 0.104 (sec). Leaf size: 12

```
DSolve[{Exp[x]*(y[x]-3*(Exp[x]+1)^2)+(Exp[x]+1)*y'[x]==0,{y[0]==4}],y[x],x,IncludeSingularSo
```

$$y(x) \rightarrow (e^x + 1)^2$$

5.22 problem 22

5.22.1 Existence and uniqueness analysis	1063
5.22.2 Solving as separable ode	1064
5.22.3 Solving as linear ode	1066
5.22.4 Solving as first order ode lie symmetry lookup ode	1067
5.22.5 Solving as exact ode	1071
5.22.6 Maple step by step solution	1075

Internal problem ID [11659]

Internal file name [OUTPUT/11668_Wednesday_April_10_2024_04_54_03_PM_15034228/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.3 (Linear equations). Exercises page 56

Problem number: 22.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact", "linear", "separable", "first_order_ode_lie_symmetry_lookup"

Maple gives the following as the ode type

[_separable]

$$2(y + 1)x - (x^2 + 1)y' = 0$$

With initial conditions

$$[y(1) = -5]$$

5.22.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = -\frac{2x}{x^2 + 1}$$
$$q(x) = \frac{2x}{x^2 + 1}$$

Hence the ode is

$$y' - \frac{2xy}{x^2 + 1} = \frac{2x}{x^2 + 1}$$

The domain of $p(x) = -\frac{2x}{x^2+1}$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 1$ is inside this domain. The domain of $q(x) = \frac{2x}{x^2+1}$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 1$ is also inside this domain. Hence solution exists and is unique.

5.22.2 Solving as separable ode

In canonical form the ODE is

$$\begin{aligned}y' &= F(x, y) \\ &= f(x)g(y) \\ &= \frac{x(2y + 2)}{x^2 + 1}\end{aligned}$$

Where $f(x) = \frac{x}{x^2+1}$ and $g(y) = 2y + 2$. Integrating both sides gives

$$\begin{aligned}\frac{1}{2y + 2} dy &= \frac{x}{x^2 + 1} dx \\ \int \frac{1}{2y + 2} dy &= \int \frac{x}{x^2 + 1} dx \\ \frac{\ln(y + 1)}{2} &= \frac{\ln(x^2 + 1)}{2} + c_1\end{aligned}$$

Raising both side to exponential gives

$$\sqrt{y + 1} = e^{\frac{\ln(x^2+1)}{2} + c_1}$$

Which simplifies to

$$\sqrt{y + 1} = c_2 \sqrt{x^2 + 1}$$

Which can be simplified to become

$$y = c_2^2(x^2 + 1)e^{2c_1} - 1$$

Initial conditions are used to solve for c_1 . Substituting $x = 1$ and $y = -5$ in the above solution gives an equation to solve for the constant of integration.

$$-5 = -1 + 2c_2^2e^{2c_1}$$

$$c_1 = \frac{\ln\left(-\frac{2}{c_2^2}\right)}{2}$$

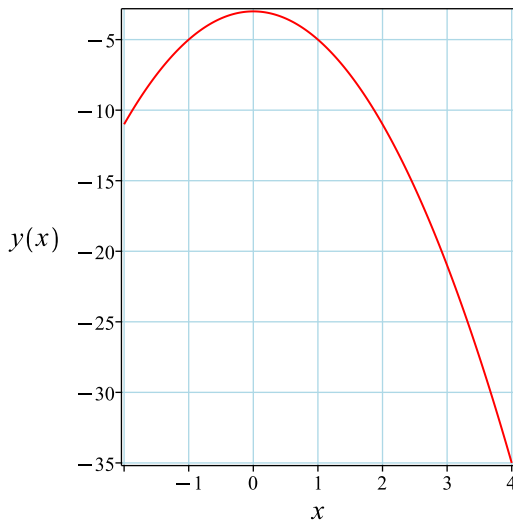
Substituting c_1 found above in the general solution gives

$$y = -2x^2 - 3$$

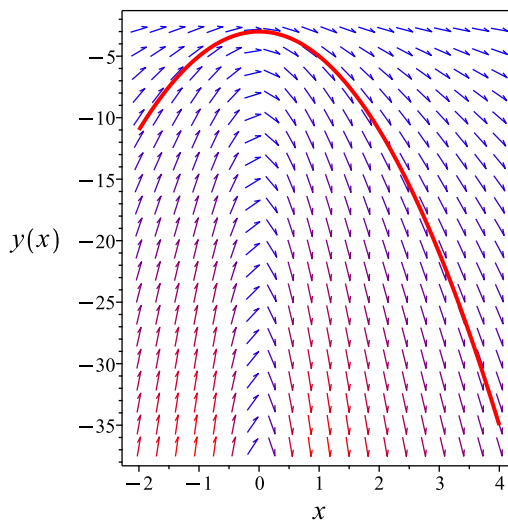
Summary

The solution(s) found are the following

$$y = -2x^2 - 3 \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = -2x^2 - 3$$

Verified OK.

5.22.3 Solving as linear ode

Entering Linear first order ODE solver. The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int -\frac{2x}{x^2+1} dx} \\ &= \frac{1}{x^2 + 1}\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu y) &= (\mu) \left(\frac{2x}{x^2 + 1} \right) \\ \frac{d}{dx} \left(\frac{y}{x^2 + 1} \right) &= \left(\frac{1}{x^2 + 1} \right) \left(\frac{2x}{x^2 + 1} \right) \\ d \left(\frac{y}{x^2 + 1} \right) &= \left(\frac{2x}{(x^2 + 1)^2} \right) dx\end{aligned}$$

Integrating gives

$$\begin{aligned}\frac{y}{x^2 + 1} &= \int \frac{2x}{(x^2 + 1)^2} dx \\ \frac{y}{x^2 + 1} &= -\frac{1}{x^2 + 1} + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = \frac{1}{x^2+1}$ results in

$$y = -1 + c_1(x^2 + 1)$$

which simplifies to

$$y = c_1x^2 + c_1 - 1$$

Initial conditions are used to solve for c_1 . Substituting $x = 1$ and $y = -5$ in the above solution gives an equation to solve for the constant of integration.

$$-5 = 2c_1 - 1$$

$$c_1 = -2$$

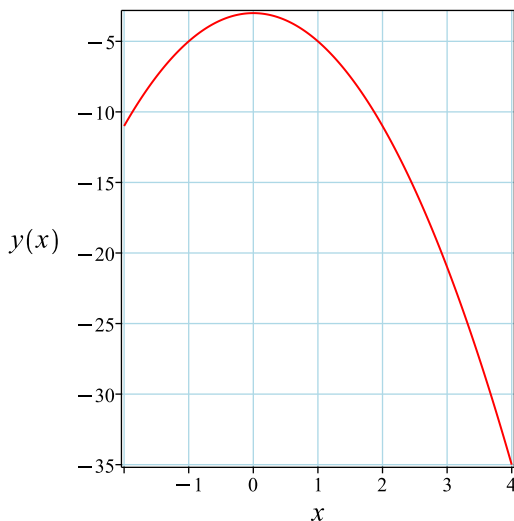
Substituting c_1 found above in the general solution gives

$$y = -2x^2 - 3$$

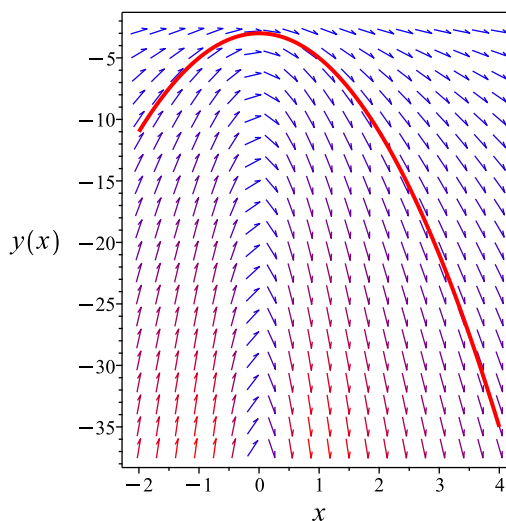
Summary

The solution(s) found are the following

$$y = -2x^2 - 3 \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = -2x^2 - 3$$

Verified OK.

5.22.4 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = \frac{2(y+1)x}{x^2+1}$$
$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (A)$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 171: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= x^2 + 1\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{x^2 + 1} dy \end{aligned}$$

Which results in

$$S = \frac{y}{x^2 + 1}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = \frac{2(y + 1)x}{x^2 + 1}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= -\frac{2yx}{(x^2 + 1)^2} \\ S_y &= \frac{1}{x^2 + 1} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = \frac{2x}{(x^2 + 1)^2} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = \frac{2R}{(R^2 + 1)^2}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = -\frac{1}{R^2 + 1} + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$\frac{y}{x^2 + 1} = -\frac{1}{x^2 + 1} + c_1$$

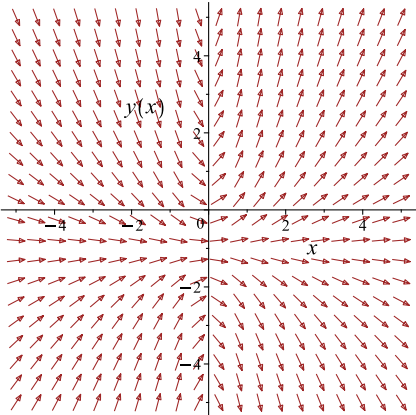
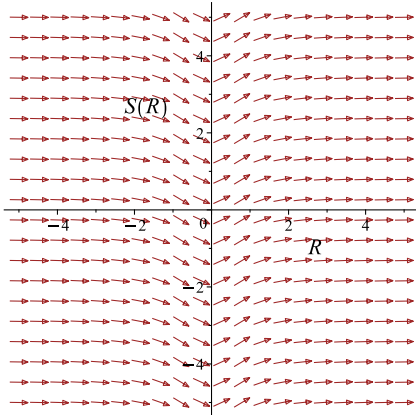
Which simplifies to

$$\frac{y}{x^2 + 1} = -\frac{1}{x^2 + 1} + c_1$$

Which gives

$$y = c_1 x^2 + c_1 - 1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = \frac{2(y+1)x}{x^2+1}$ 	$R = x$ $S = \frac{y}{x^2 + 1}$	$\frac{dS}{dR} = \frac{2R}{(R^2+1)^2}$ 

Initial conditions are used to solve for c_1 . Substituting $x = 1$ and $y = -5$ in the above solution gives an equation to solve for the constant of integration.

$$-5 = 2c_1 - 1$$

$$c_1 = -2$$

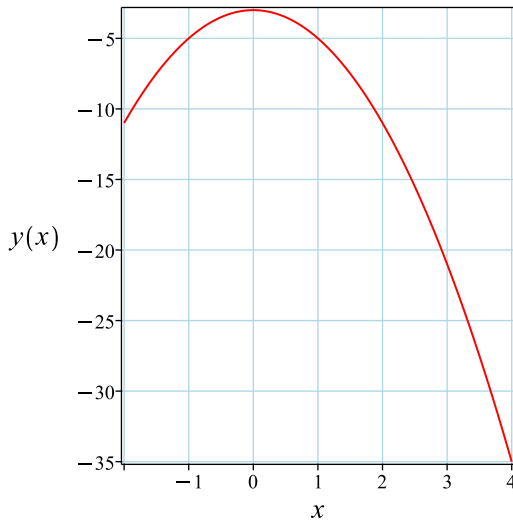
Substituting c_1 found above in the general solution gives

$$y = -2x^2 - 3$$

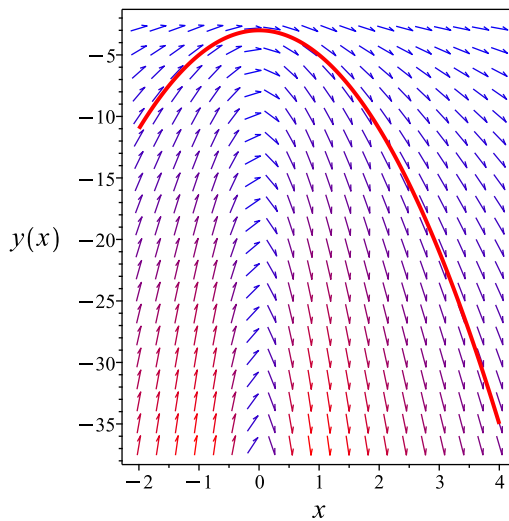
Summary

The solution(s) found are the following

$$y = -2x^2 - 3 \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = -2x^2 - 3$$

Verified OK.

5.22.5 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx}\phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \quad (\text{B})$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (\text{1A})$$

Therefore

$$\begin{aligned} \left(\frac{1}{2y+2}\right) dy &= \left(\frac{x}{x^2+1}\right) dx \\ \left(-\frac{x}{x^2+1}\right) dx + \left(\frac{1}{2y+2}\right) dy &= 0 \end{aligned} \quad (\text{2A})$$

Comparing (1A) and (2A) shows that

$$\begin{aligned} M(x, y) &= -\frac{x}{x^2+1} \\ N(x, y) &= \frac{1}{2y+2} \end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned} \frac{\partial M}{\partial y} &= \frac{\partial}{\partial y} \left(-\frac{x}{x^2+1}\right) \\ &= 0 \end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x} \left(\frac{1}{2y+2} \right) \\ &= 0\end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \quad (1)$$

$$\frac{\partial \phi}{\partial y} = N \quad (2)$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int M dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int -\frac{x}{x^2+1} dx \\ \phi &= -\frac{\ln(x^2+1)}{2} + f(y)\end{aligned} \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = 0 + f'(y) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = \frac{1}{2y+2}$. Therefore equation (4) becomes

$$\frac{1}{2y+2} = 0 + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = \frac{1}{2y+2}$$

Integrating the above w.r.t y gives

$$\int f'(y) dy = \int \left(\frac{1}{2y+2} \right) dy$$
$$f(y) = \frac{\ln(y+1)}{2} + c_1$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = -\frac{\ln(x^2+1)}{2} + \frac{\ln(y+1)}{2} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -\frac{\ln(x^2+1)}{2} + \frac{\ln(y+1)}{2}$$

The solution becomes

$$y = x^2 e^{2c_1} + e^{2c_1} - 1$$

Initial conditions are used to solve for c_1 . Substituting $x = 1$ and $y = -5$ in the above solution gives an equation to solve for the constant of integration.

$$-5 = -1 + 2e^{2c_1}$$

$$c_1 = \frac{\ln(2)}{2} + \frac{i\pi}{2}$$

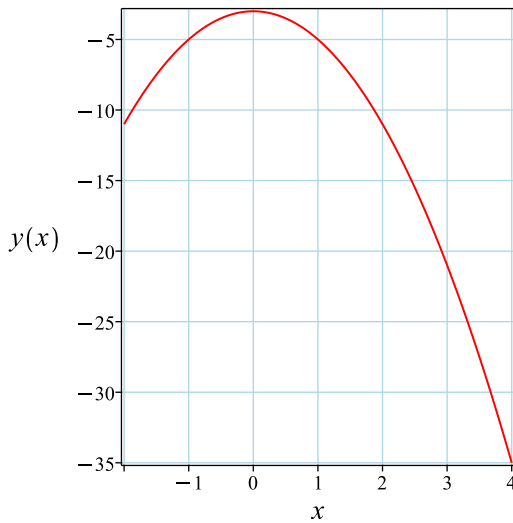
Substituting c_1 found above in the general solution gives

$$y = -2x^2 - 3$$

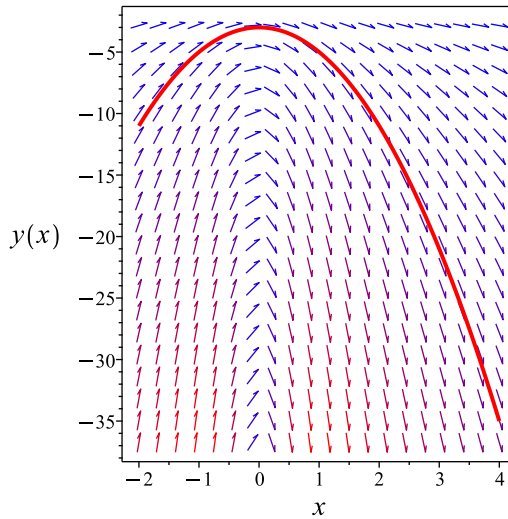
Summary

The solution(s) found are the following

$$y = -2x^2 - 3 \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = -2x^2 - 3$$

Verified OK.

5.22.6 Maple step by step solution

Let's solve

$$[2(y + 1)x - (x^2 + 1)y' = 0, y(1) = -5]$$

- Highest derivative means the order of the ODE is 1

y'

- Separate variables

$$\frac{y'}{y+1} = \frac{2x}{x^2+1}$$

- Integrate both sides with respect to x

$$\int \frac{y'}{y+1} dx = \int \frac{2x}{x^2+1} dx + c_1$$

- Evaluate integral

$$\ln(y + 1) = \ln(x^2 + 1) + c_1$$

- Solve for y

$$y = x^2 e^{c_1} + e^{c_1} - 1$$

- Use initial condition $y(1) = -5$
 $-5 = 2e^{c_1} - 1$
- Solve for c_1
 $c_1 = \ln(2) + I\pi$
- Substitute $c_1 = \ln(2) + I\pi$ into general solution and simplify
 $y = -2x^2 - 3$
- Solution to the IVP
 $y = -2x^2 - 3$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
<- 1st order linear successful`

```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 11

```
dsolve([2*x*(y(x)+1)-(x^2+1)*diff(y(x),x)=0,y(1) = -5],y(x), singsol=all)
```

$$y(x) = -2x^2 - 3$$

✓ Solution by Mathematica

Time used: 0.032 (sec). Leaf size: 12

```
DSolve[{2*x*(y[x]+1)-(x^2+1)*y'[x]==0,{y[1]==-5}},y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow -2x^2 - 3$$

5.23 problem 23

5.23.1 Existence and uniqueness analysis	1077
5.23.2 Solving as linear ode	1078
5.23.3 Solving as first order ode lie symmetry lookup ode	1080
5.23.4 Solving as exact ode	1085
5.23.5 Maple step by step solution	1089

Internal problem ID [11660]

Internal file name [OUTPUT/11669_Wednesday_April_10_2024_04_54_04_PM_9334433/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 2, section 2.3 (Linear equations). Exercises page 56

Problem number: 23.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"linear", "exactWithIntegrationFactor", "first_order_ode_lie_symmetry_lookup"**

Maple gives the following as the ode type

`[_linear]`

$$r' + r \tan(t) = \cos(t)^2$$

With initial conditions

$$\left[r\left(\frac{\pi}{4}\right) = 1 \right]$$

5.23.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$r' + p(t)r = q(t)$$

Where here

$$p(t) = \tan(t)$$

$$q(t) = \cos(t)^2$$

Hence the ode is

$$r' + r \tan(t) = \cos(t)^2$$

The domain of $p(t) = \tan(t)$ is

$$\left\{ t < \frac{1}{2}\pi + \pi \vee \frac{1}{2}\pi + \pi < t \right\}$$

And the point $t_0 = \frac{\pi}{4}$ is inside this domain. The domain of $q(t) = \cos(t)^2$ is

$$\{-\infty < t < \infty\}$$

And the point $t_0 = \frac{\pi}{4}$ is also inside this domain. Hence solution exists and is unique.

5.23.2 Solving as linear ode

Entering Linear first order ODE solver. The integrating factor μ is

$$\begin{aligned} \mu &= e^{\int \tan(t) dt} \\ &= \frac{1}{\cos(t)} \end{aligned}$$

Which simplifies to

$$\mu = \sec(t)$$

The ode becomes

$$\begin{aligned} \frac{d}{dt}(\mu r) &= (\mu) (\cos(t)^2) \\ \frac{d}{dt}(\sec(t) r) &= (\sec(t)) (\cos(t)^2) \\ d(\sec(t) r) &= \cos(t) dt \end{aligned}$$

Integrating gives

$$\begin{aligned} \sec(t) r &= \int \cos(t) dt \\ \sec(t) r &= \sin(t) + c_1 \end{aligned}$$

Dividing both sides by the integrating factor $\mu = \sec(t)$ results in

$$r = \cos(t) \sin(t) + c_1 \cos(t)$$

which simplifies to

$$r = \cos(t) (\sin(t) + c_1)$$

Initial conditions are used to solve for c_1 . Substituting $t = \frac{\pi}{4}$ and $r = 1$ in the above solution gives an equation to solve for the constant of integration.

$$1 = \frac{1}{2} + \frac{\sqrt{2} c_1}{2}$$

$$c_1 = \frac{\sqrt{2}}{2}$$

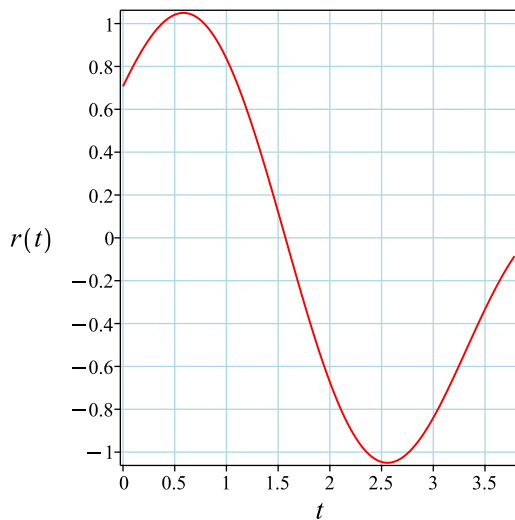
Substituting c_1 found above in the general solution gives

$$r = \cos(t) \sin(t) + \frac{\cos(t) \sqrt{2}}{2}$$

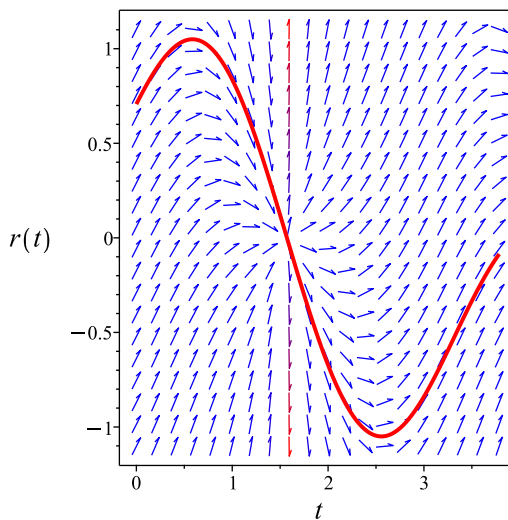
Summary

The solution(s) found are the following

$$r = \cos(t) \sin(t) + \frac{\cos(t) \sqrt{2}}{2} \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$r = \cos(t) \sin(t) + \frac{\cos(t) \sqrt{2}}{2}$$

Verified OK.

5.23.3 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$\begin{aligned} r' &= -r \tan(t) + \cos(t)^2 \\ r' &= \omega(t, r) \end{aligned}$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_t + \omega(\eta_r - \xi_t) - \omega^2 \xi_r - \omega_t \xi - \omega_r \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 174: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(t, r) &= 0 \\ \eta(t, r) &= \cos(t)\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(t, r) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dt}{\xi} = \frac{dr}{\eta} = dS\tag{1}$$

The above comes from the requirements that $(\xi \frac{\partial}{\partial t} + \eta \frac{\partial}{\partial r})S(t, r) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = t$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\cos(t)} dy \end{aligned}$$

Which results in

$$S = \frac{r}{\cos(t)}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_t + \omega(t, r)S_r}{R_t + \omega(t, r)R_r} \quad (2)$$

Where in the above R_t, R_r, S_t, S_r are all partial derivatives and $\omega(t, r)$ is the right hand side of the original ode given by

$$\omega(t, r) = -r \tan(t) + \cos(t)^2$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_t &= 1 \\ R_r &= 0 \\ S_t &= \tan(t) \sec(t) r \\ S_r &= \sec(t) \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = \cos(t) \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for t, r in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = \cos(R)$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by

integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = \sin(R) + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to t, r coordinates. This results in

$$\sec(t) r = \sin(t) + c_1$$

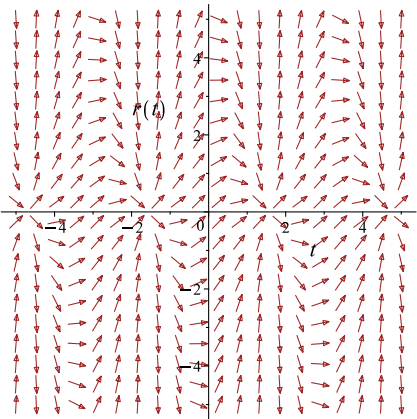
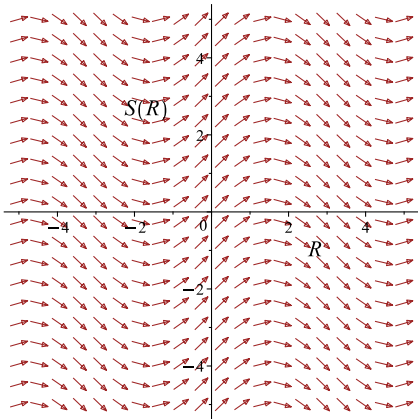
Which simplifies to

$$\sec(t) r = \sin(t) + c_1$$

Which gives

$$r = \frac{\sin(t) + c_1}{\sec(t)}$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in t, r coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dr}{dt} = -r \tan(t) + \cos(t)^2$ 	$R = t$ $S = \sec(t) r$	$\frac{dS}{dR} = \cos(R)$ 

Initial conditions are used to solve for c_1 . Substituting $t = \frac{\pi}{4}$ and $r = 1$ in the above solution gives an equation to solve for the constant of integration.

$$1 = \frac{1}{2} + \frac{\sqrt{2} c_1}{2}$$

$$c_1 = \frac{\sqrt{2}}{2}$$

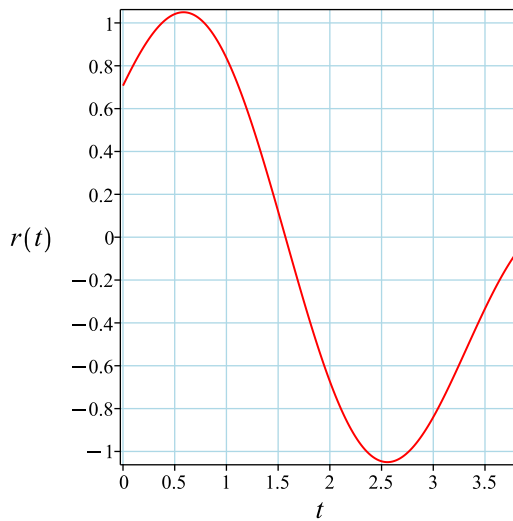
Substituting c_1 found above in the general solution gives

$$r = \cos(t) \sin(t) + \frac{\cos(t) \sqrt{2}}{2}$$

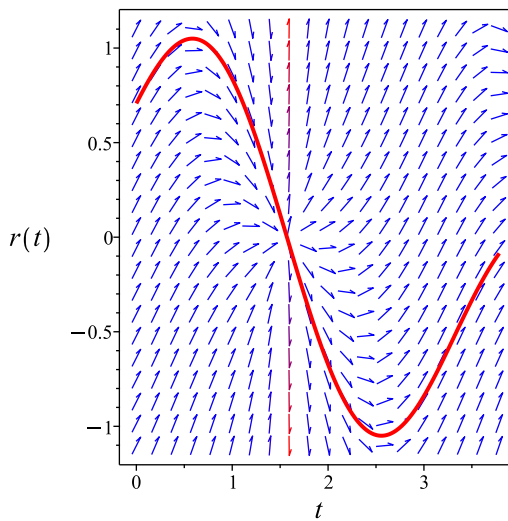
Summary

The solution(s) found are the following

$$r = \cos(t) \sin(t) + \frac{\cos(t) \sqrt{2}}{2} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$r = \cos(t) \sin(t) + \frac{\cos(t) \sqrt{2}}{2}$$

Verified OK.

5.23.4 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \quad (\text{A})$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \quad (\text{B})$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(t, r) dt + N(t, r) dr = 0 \quad (\text{1A})$$

Therefore

$$\begin{aligned} dr &= (-r \tan(t) + \cos(t)^2) dt \\ (r \tan(t) - \cos(t)^2) dt + dr &= 0 \end{aligned} \quad (\text{2A})$$

Comparing (1A) and (2A) shows that

$$\begin{aligned} M(t, r) &= r \tan(t) - \cos(t)^2 \\ N(t, r) &= 1 \end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial r} = \frac{\partial N}{\partial t}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial r} &= \frac{\partial}{\partial r}(r \tan(t) - \cos(t)^2) \\ &= \tan(t)\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial t} &= \frac{\partial}{\partial t}(1) \\ &= 0\end{aligned}$$

Since $\frac{\partial M}{\partial r} \neq \frac{\partial N}{\partial t}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$\begin{aligned}A &= \frac{1}{N} \left(\frac{\partial M}{\partial r} - \frac{\partial N}{\partial t} \right) \\ &= 1((\tan(t)) - (0)) \\ &= \tan(t)\end{aligned}$$

Since A does not depend on r , then it can be used to find an integrating factor. The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int A dt} \\ &= e^{\int \tan(t) dt}\end{aligned}$$

The result of integrating gives

$$\begin{aligned}\mu &= e^{-\ln(\cos(t))} \\ &= \sec(t)\end{aligned}$$

M and N are multiplied by this integrating factor, giving new M and new N which are called \overline{M} and \overline{N} for now so not to confuse them with the original M and N .

$$\begin{aligned}\overline{M} &= \mu M \\ &= \sec(t) (r \tan(t) - \cos(t)^2) \\ &= -\cos(t) + \tan(t) \sec(t) r\end{aligned}$$

And

$$\begin{aligned}\bar{N} &= \mu N \\ &= \sec(t) \quad (1) \\ &= \sec(t)\end{aligned}$$

Now a modified ODE is obtained from the original ODE, which is exact and can be solved. The modified ODE is

$$\begin{aligned}\bar{M} + \bar{N} \frac{dr}{dt} &= 0 \\ (-\cos(t) + \tan(t) \sec(t) r) + (\sec(t)) \frac{dr}{dt} &= 0\end{aligned}$$

The following equations are now set up to solve for the function $\phi(t, r)$

$$\frac{\partial \phi}{\partial t} = \bar{M} \quad (1)$$

$$\frac{\partial \phi}{\partial r} = \bar{N} \quad (2)$$

Integrating (1) w.r.t. t gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial t} dt &= \int \bar{M} dt \\ \int \frac{\partial \phi}{\partial t} dt &= \int -\cos(t) + \tan(t) \sec(t) r dt \\ \phi &= \sec(t) r - \sin(t) + f(r)\end{aligned} \quad (3)$$

Where $f(r)$ is used for the constant of integration since ϕ is a function of both t and r . Taking derivative of equation (3) w.r.t r gives

$$\frac{\partial \phi}{\partial r} = \sec(t) + f'(r) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial r} = \sec(t)$. Therefore equation (4) becomes

$$\sec(t) = \sec(t) + f'(r) \quad (5)$$

Solving equation (5) for $f'(r)$ gives

$$f'(r) = 0$$

Therefore

$$f(r) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(r)$ into equation (3) gives ϕ

$$\phi = \sec(t)r - \sin(t) + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = \sec(t)r - \sin(t)$$

The solution becomes

$$r = \frac{\sin(t) + c_1}{\sec(t)}$$

Initial conditions are used to solve for c_1 . Substituting $t = \frac{\pi}{4}$ and $r = 1$ in the above solution gives an equation to solve for the constant of integration.

$$1 = \frac{1}{2} + \frac{\sqrt{2}c_1}{2}$$

$$c_1 = \frac{\sqrt{2}}{2}$$

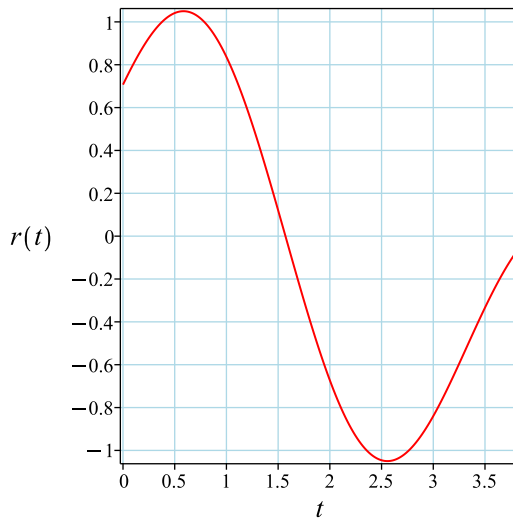
Substituting c_1 found above in the general solution gives

$$r = \cos(t)\sin(t) + \frac{\cos(t)\sqrt{2}}{2}$$

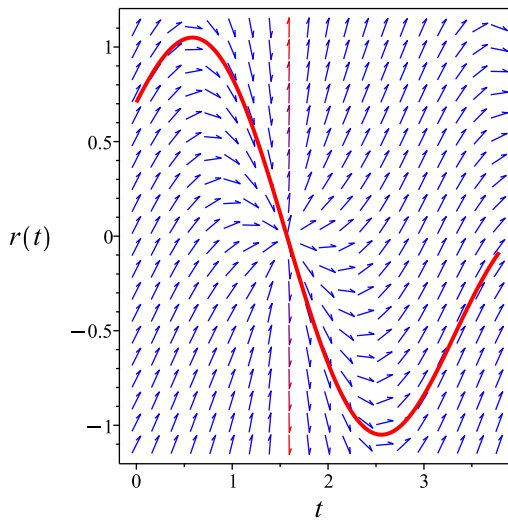
Summary

The solution(s) found are the following

$$r = \cos(t)\sin(t) + \frac{\cos(t)\sqrt{2}}{2} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$r = \cos(t) \sin(t) + \frac{\cos(t) \sqrt{2}}{2}$$

Verified OK.

5.23.5 Maple step by step solution

Let's solve

$$[r' + r \tan(t) = \cos(t)^2, r(\frac{\pi}{4}) = 1]$$

- Highest derivative means the order of the ODE is 1

$$r'$$

- Isolate the derivative

$$r' = -r \tan(t) + \cos(t)^2$$

- Group terms with r on the lhs of the ODE and the rest on the rhs of the ODE

$$r' + r \tan(t) = \cos(t)^2$$

- The ODE is linear; multiply by an integrating factor $\mu(t)$

$$\mu(t) (r' + r \tan(t)) = \mu(t) \cos(t)^2$$

- Assume the lhs of the ODE is the total derivative $\frac{d}{dt}(\mu(t) r)$

$$\mu(t) (r' + r \tan(t)) = \mu'(t) r + \mu(t) r'$$

- Isolate $\mu'(t)$

$$\mu'(t) = \mu(t) \tan(t)$$
- Solve to find the integrating factor

$$\mu(t) = \frac{1}{\cos(t)}$$
- Integrate both sides with respect to t

$$\int \left(\frac{d}{dt}(\mu(t)r) \right) dt = \int \mu(t) \cos(t)^2 dt + c_1$$
- Evaluate the integral on the lhs

$$\mu(t)r = \int \mu(t) \cos(t)^2 dt + c_1$$
- Solve for r

$$r = \frac{\int \mu(t) \cos(t)^2 dt + c_1}{\mu(t)}$$
- Substitute $\mu(t) = \frac{1}{\cos(t)}$

$$r = \cos(t) \left(\int \cos(t) dt + c_1 \right)$$
- Evaluate the integrals on the rhs

$$r = \cos(t) (\sin(t) + c_1)$$
- Use initial condition $r\left(\frac{\pi}{4}\right) = 1$

$$1 = \frac{\sqrt{2} \left(\frac{\sqrt{2}}{2} + c_1 \right)}{2}$$
- Solve for c_1

$$c_1 = \frac{\sqrt{2}}{2}$$
- Substitute $c_1 = \frac{\sqrt{2}}{2}$ into general solution and simplify

$$r = \frac{(2 \sin(t) + \sqrt{2}) \cos(t)}{2}$$
- Solution to the IVP

$$r = \frac{(2 \sin(t) + \sqrt{2}) \cos(t)}{2}$$

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
<- 1st order linear successful`
```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 15

```
dsolve([diff(r(t),t)+r(t)*tan(t)=cos(t)^2,r(1/4*Pi) = 1],r(t), singsol=all)
```

$$r(t) = \frac{(2 \sin(t) + \sqrt{2}) \cos(t)}{2}$$

✓ Solution by Mathematica

Time used: 0.077 (sec). Leaf size: 16

```
DSolve[{r'[t]+r[t]*Tan[t]==Cos[t]^2,{r[Pi/4]==1}},r[t],t,IncludeSingularSolutions -> True]
```

$$r(t) \rightarrow \left(\sin(t) + \frac{1}{\sqrt{2}} \right) \cos(t)$$

5.24 problem 24

5.24.1 Existence and uniqueness analysis	1092
5.24.2 Solving as linear ode	1093
5.24.3 Solving as first order ode lie symmetry lookup ode	1095
5.24.4 Solving as exact ode	1099
5.24.5 Maple step by step solution	1103

Internal problem ID [11661]

Internal file name [OUTPUT/11670_Wednesday_April_10_2024_04_54_05_PM_5880669/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.3 (Linear equations). Exercises page 56

Problem number: 24.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"linear", "exactWithIntegrationFactor", "first_order_ode_lie_symmetry_lookup"**

Maple gives the following as the ode type

```
[[_linear, `class A`]]
```

$$-x + x' = \sin(2t)$$

With initial conditions

$$[x(0) = 0]$$

5.24.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$x' + p(t)x = q(t)$$

Where here

$$p(t) = -1$$

$$q(t) = \sin(2t)$$

Hence the ode is

$$-x + x' = \sin(2t)$$

The domain of $p(t) = -1$ is

$$\{-\infty < t < \infty\}$$

And the point $t_0 = 0$ is inside this domain. The domain of $q(t) = \sin(2t)$ is

$$\{-\infty < t < \infty\}$$

And the point $t_0 = 0$ is also inside this domain. Hence solution exists and is unique.

5.24.2 Solving as linear ode

Entering Linear first order ODE solver. The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int(-1)dt} \\ &= e^{-t}\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dt}(\mu x) &= (\mu)(\sin(2t)) \\ \frac{d}{dt}(e^{-t}x) &= (e^{-t})(\sin(2t)) \\ d(e^{-t}x) &= (e^{-t}\sin(2t)) dt\end{aligned}$$

Integrating gives

$$\begin{aligned}e^{-t}x &= \int e^{-t}\sin(2t) dt \\ e^{-t}x &= -\frac{2e^{-t}\cos(2t)}{5} - \frac{e^{-t}\sin(2t)}{5} + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = e^{-t}$ results in

$$x = e^t \left(-\frac{2e^{-t}\cos(2t)}{5} - \frac{e^{-t}\sin(2t)}{5} \right) + c_1 e^t$$

which simplifies to

$$x = c_1 e^t - \frac{\sin(2t)}{5} - \frac{2\cos(2t)}{5}$$

Initial conditions are used to solve for c_1 . Substituting $t = 0$ and $x = 0$ in the above solution gives an equation to solve for the constant of integration.

$$0 = c_1 - \frac{2}{5}$$

$$c_1 = \frac{2}{5}$$

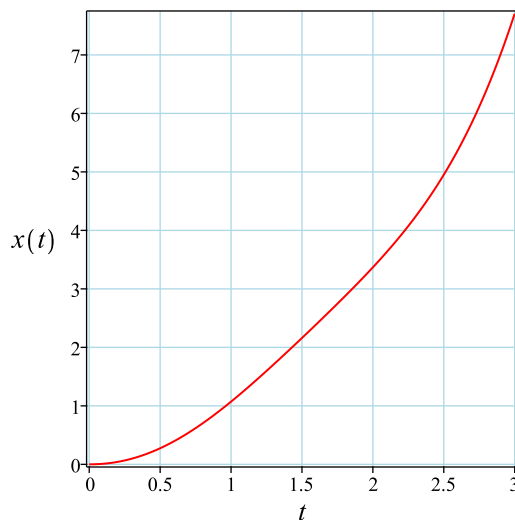
Substituting c_1 found above in the general solution gives

$$x = \frac{2e^t}{5} - \frac{\sin(2t)}{5} - \frac{2\cos(2t)}{5}$$

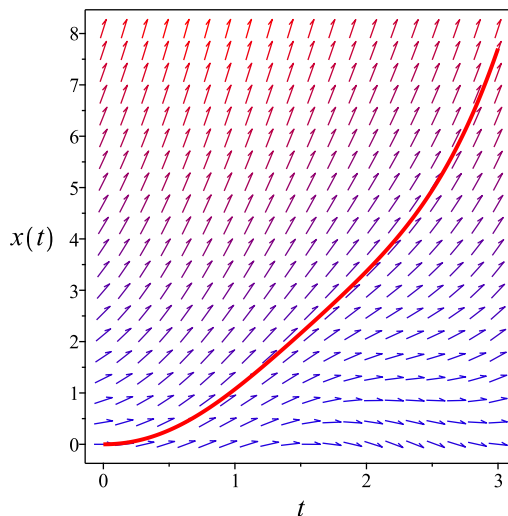
Summary

The solution(s) found are the following

$$x = \frac{2e^t}{5} - \frac{\sin(2t)}{5} - \frac{2\cos(2t)}{5} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$x = \frac{2e^t}{5} - \frac{\sin(2t)}{5} - \frac{2\cos(2t)}{5}$$

Verified OK.

5.24.3 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$\begin{aligned}x' &= x + \sin(2t) \\x' &= \omega(t, x)\end{aligned}$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_t + \omega(\eta_x - \xi_t) - \omega^2 \xi_x - \omega_t \xi - \omega_x \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 177: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int(n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(t, x) &= 0 \\ \eta(t, x) &= e^t\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(t, x) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dt}{\xi} = \frac{dx}{\eta} = dS\tag{1}$$

The above comes from the requirements that $(\xi \frac{\partial}{\partial t} + \eta \frac{\partial}{\partial x}) S(t, x) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = t$$

S is found from

$$\begin{aligned}S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{e^t} dy\end{aligned}$$

Which results in

$$S = e^{-t}x$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_t + \omega(t, x)S_x}{R_t + \omega(t, x)R_x}\tag{2}$$

Where in the above R_t, R_x, S_t, S_x are all partial derivatives and $\omega(t, x)$ is the right hand side of the original ode given by

$$\omega(t, x) = x + \sin(2t)$$

Evaluating all the partial derivatives gives

$$\begin{aligned}R_t &= 1 \\ R_x &= 0 \\ S_t &= -e^{-t}x \\ S_x &= e^{-t}\end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = e^{-t} \sin(2t) \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for t, x in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = e^{-R} \sin(2R)$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = c_1 - \frac{e^{-R}(2 \cos(2R) + \sin(2R))}{5} \quad (4)$$

To complete the solution, we just need to transform (4) back to t, x coordinates. This results in

$$e^{-t}x = -\frac{(\sin(2t) + 2 \cos(2t)) e^{-t}}{5} + c_1$$

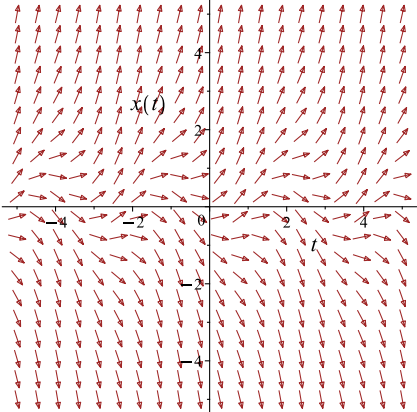
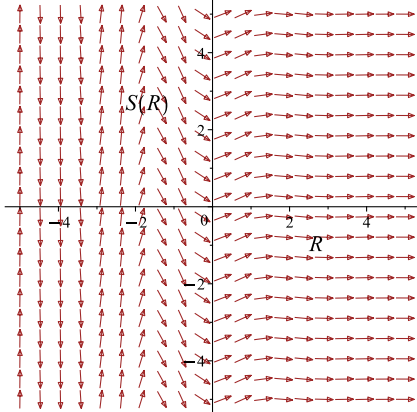
Which simplifies to

$$e^{-t}x = -\frac{(\sin(2t) + 2 \cos(2t)) e^{-t}}{5} + c_1$$

Which gives

$$x = -\frac{e^t(e^{-t} \sin(2t) + 2 e^{-t} \cos(2t) - 5c_1)}{5}$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in t, x coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dx}{dt} = x + \sin(2t)$ 	$R = t$ $S = e^{-t}x$	$\frac{dS}{dR} = e^{-R} \sin(2R)$ 

Initial conditions are used to solve for c_1 . Substituting $t = 0$ and $x = 0$ in the above solution gives an equation to solve for the constant of integration.

$$0 = c_1 - \frac{2}{5}$$

$$c_1 = \frac{2}{5}$$

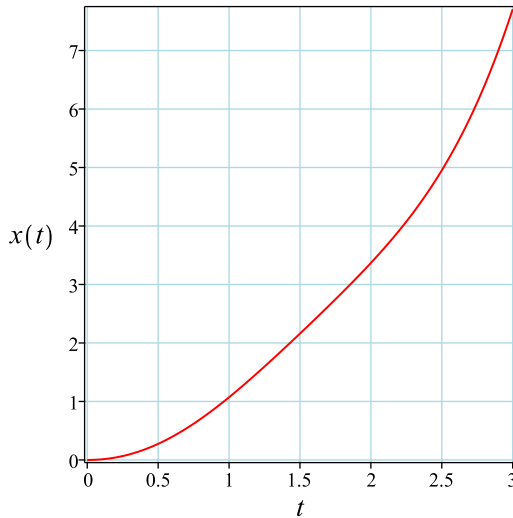
Substituting c_1 found above in the general solution gives

$$x = \frac{2e^t}{5} - \frac{\sin(2t)}{5} - \frac{2\cos(2t)}{5}$$

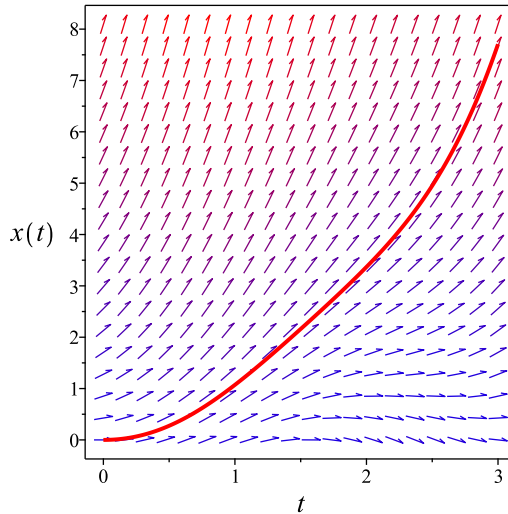
Summary

The solution(s) found are the following

$$x = \frac{2e^t}{5} - \frac{\sin(2t)}{5} - \frac{2\cos(2t)}{5} \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$x = \frac{2e^t}{5} - \frac{\sin(2t)}{5} - \frac{2\cos(2t)}{5}$$

Verified OK.

5.24.4 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(t, x) dt + N(t, x) dx = 0 \tag{1A}$$

Therefore

$$\begin{aligned} dx &= (x + \sin(2t)) dt \\ (-x - \sin(2t)) dt + dx &= 0 \end{aligned} \tag{2A}$$

Comparing (1A) and (2A) shows that

$$\begin{aligned} M(t, x) &= -x - \sin(2t) \\ N(t, x) &= 1 \end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial x} = \frac{\partial N}{\partial t}$$

Using result found above gives

$$\begin{aligned} \frac{\partial M}{\partial x} &= \frac{\partial}{\partial x}(-x - \sin(2t)) \\ &= -1 \end{aligned}$$

And

$$\begin{aligned} \frac{\partial N}{\partial t} &= \frac{\partial}{\partial t}(1) \\ &= 0 \end{aligned}$$

Since $\frac{\partial M}{\partial x} \neq \frac{\partial N}{\partial t}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$\begin{aligned} A &= \frac{1}{N} \left(\frac{\partial M}{\partial x} - \frac{\partial N}{\partial t} \right) \\ &= 1((-1) - (0)) \\ &= -1 \end{aligned}$$

Since A does not depend on x , then it can be used to find an integrating factor. The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int A dt} \\ &= e^{\int -1 dt}\end{aligned}$$

The result of integrating gives

$$\begin{aligned}\mu &= e^{-t} \\ &= e^{-t}\end{aligned}$$

M and N are multiplied by this integrating factor, giving new M and new N which are called \bar{M} and \bar{N} for now so not to confuse them with the original M and N .

$$\begin{aligned}\bar{M} &= \mu M \\ &= e^{-t}(-x - \sin(2t)) \\ &= -e^{-t}(x + \sin(2t))\end{aligned}$$

And

$$\begin{aligned}\bar{N} &= \mu N \\ &= e^{-t}(1) \\ &= e^{-t}\end{aligned}$$

Now a modified ODE is obtained from the original ODE, which is exact and can be solved. The modified ODE is

$$\begin{aligned}\bar{M} + \bar{N} \frac{dx}{dt} &= 0 \\ (-e^{-t}(x + \sin(2t))) + (e^{-t}) \frac{dx}{dt} &= 0\end{aligned}$$

The following equations are now set up to solve for the function $\phi(t, x)$

$$\frac{\partial \phi}{\partial t} = \bar{M} \tag{1}$$

$$\frac{\partial \phi}{\partial x} = \bar{N} \tag{2}$$

Integrating (1) w.r.t. t gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial t} dt &= \int \bar{M} dt \\ \int \frac{\partial \phi}{\partial t} dt &= \int -e^{-t}(x + \sin(2t)) dt \\ \phi &= \frac{(5x + 2 \cos(2t) + \sin(2t)) e^{-t}}{5} + f(x)\end{aligned} \tag{3}$$

Where $f(x)$ is used for the constant of integration since ϕ is a function of both t and x . Taking derivative of equation (3) w.r.t x gives

$$\frac{\partial \phi}{\partial x} = e^{-t} + f'(x) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial x} = e^{-t}$. Therefore equation (4) becomes

$$e^{-t} = e^{-t} + f'(x) \quad (5)$$

Solving equation (5) for $f'(x)$ gives

$$f'(x) = 0$$

Therefore

$$f(x) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(x)$ into equation (3) gives ϕ

$$\phi = \frac{(5x + 2 \cos(2t) + \sin(2t)) e^{-t}}{5} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = \frac{(5x + 2 \cos(2t) + \sin(2t)) e^{-t}}{5}$$

The solution becomes

$$x = -\frac{e^t(e^{-t} \sin(2t) + 2e^{-t} \cos(2t) - 5c_1)}{5}$$

Initial conditions are used to solve for c_1 . Substituting $t = 0$ and $x = 0$ in the above solution gives an equation to solve for the constant of integration.

$$0 = c_1 - \frac{2}{5}$$

$$c_1 = \frac{2}{5}$$

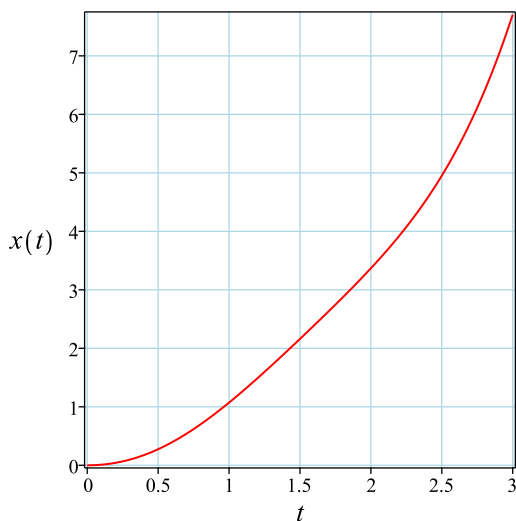
Substituting c_1 found above in the general solution gives

$$x = \frac{2e^t}{5} - \frac{\sin(2t)}{5} - \frac{2\cos(2t)}{5}$$

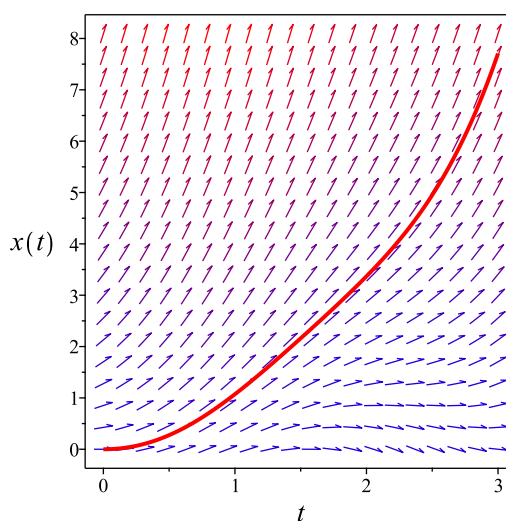
Summary

The solution(s) found are the following

$$x = \frac{2e^t}{5} - \frac{\sin(2t)}{5} - \frac{2\cos(2t)}{5} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$x = \frac{2e^t}{5} - \frac{\sin(2t)}{5} - \frac{2\cos(2t)}{5}$$

Verified OK.

5.24.5 Maple step by step solution

Let's solve

$$[-x + x' = \sin(2t), x(0) = 0]$$

- Highest derivative means the order of the ODE is 1
- Isolate the derivative

$$x' = x + \sin(2t)$$

- Group terms with x on the lhs of the ODE and the rest on the rhs of the ODE

$$-x + x' = \sin(2t)$$

- The ODE is linear; multiply by an integrating factor $\mu(t)$

$$\mu(t)(-x + x') = \mu(t)\sin(2t)$$

- Assume the lhs of the ODE is the total derivative $\frac{d}{dt}(\mu(t)x)$

$$\mu(t)(-x + x') = \mu'(t)x + \mu(t)x'$$

- Isolate $\mu'(t)$

$$\mu'(t) = -\mu(t)$$

- Solve to find the integrating factor

$$\mu(t) = e^{-t}$$

- Integrate both sides with respect to t

$$\int \left(\frac{d}{dt}(\mu(t)x) \right) dt = \int \mu(t)\sin(2t) dt + c_1$$

- Evaluate the integral on the lhs

$$\mu(t)x = \int \mu(t)\sin(2t) dt + c_1$$

- Solve for x

$$x = \frac{\int \mu(t)\sin(2t)dt + c_1}{\mu(t)}$$

- Substitute $\mu(t) = e^{-t}$

$$x = \frac{\int e^{-t}\sin(2t)dt + c_1}{e^{-t}}$$

- Evaluate the integrals on the rhs

$$x = \frac{\frac{e^{-t}\sin(2t)}{5} - \frac{2e^{-t}\cos(2t)}{5} + c_1}{e^{-t}}$$

- Simplify

$$x = c_1 e^t - \frac{\sin(2t)}{5} - \frac{2\cos(2t)}{5}$$

- Use initial condition $x(0) = 0$

$$0 = c_1 - \frac{2}{5}$$

- Solve for c_1

$$c_1 = \frac{2}{5}$$

- Substitute $c_1 = \frac{2}{5}$ into general solution and simplify

$$x = \frac{2e^t}{5} - \frac{\sin(2t)}{5} - \frac{2\cos(2t)}{5}$$

- Solution to the IVP

$$x = \frac{2e^t}{5} - \frac{\sin(2t)}{5} - \frac{2\cos(2t)}{5}$$

Maple trace

```
`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
<- 1st order linear successful`
```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 21

```
dsolve([diff(x(t),t)-x(t)=sin(2*t),x(0) = 0],x(t), singsol=all)
```

$$x(t) = -\frac{2\cos(2t)}{5} - \frac{\sin(2t)}{5} + \frac{2e^t}{5}$$

✓ Solution by Mathematica

Time used: 0.083 (sec). Leaf size: 27

```
DSolve[{x'[t]-x[t]==Sin[2*t],{x[0]==0}},x[t],t,IncludeSingularSolutions -> True]
```

$$x(t) \rightarrow \frac{1}{5}(2e^t - \sin(2t) - 2\cos(2t))$$

5.25 problem 25

5.25.1 Existence and uniqueness analysis	1106
5.25.2 Solving as first order ode lie symmetry lookup ode	1107
5.25.3 Solving as bernoulli ode	1111
5.25.4 Solving as exact ode	1114

Internal problem ID [11662]

Internal file name [OUTPUT/11671_Wednesday_April_10_2024_04_54_06_PM_54278466/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 2, section 2.3 (Linear equations). Exercises page 56

Problem number: 25.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"bernoulli", "exactWithIntegrationFactor", "first_order_ode_lie_symmetry_lookup"**

Maple gives the following as the ode type

```
[[_homogeneous, `class G`], _rational, _Bernoulli]
```

$$y' + \frac{y}{2x} - \frac{x}{y^3} = 0$$

With initial conditions

$$[y(1) = 2]$$

5.25.1 Existence and uniqueness analysis

This is non linear first order ODE. In canonical form it is written as

$$\begin{aligned} y' &= f(x, y) \\ &= -\frac{y^4 - 2x^2}{2xy^3} \end{aligned}$$

The x domain of $f(x, y)$ when $y = 2$ is

$$\{x < 0 \vee 0 < x\}$$

And the point $x_0 = 1$ is inside this domain. The y domain of $f(x, y)$ when $x = 1$ is

$$\{y < 0 \vee 0 < y\}$$

And the point $y_0 = 2$ is inside this domain. Now we will look at the continuity of

$$\begin{aligned} \frac{\partial f}{\partial y} &= \frac{\partial}{\partial y} \left(-\frac{y^4 - 2x^2}{2x y^3} \right) \\ &= -\frac{2}{x} + \frac{\frac{3y^4}{2} - 3x^2}{x y^4} \end{aligned}$$

The x domain of $\frac{\partial f}{\partial y}$ when $y = 2$ is

$$\{x < 0 \vee 0 < x\}$$

And the point $x_0 = 1$ is inside this domain. The y domain of $\frac{\partial f}{\partial y}$ when $x = 1$ is

$$\{y < 0 \vee 0 < y\}$$

And the point $y_0 = 2$ is inside this domain. Therefore solution exists and is unique.

5.25.2 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$\begin{aligned} y' &= -\frac{y^4 - 2x^2}{2x y^3} \\ y' &= \omega(x, y) \end{aligned}$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type Bernoulli. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 180: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= \frac{1}{y^3x^2}\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right)S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{1}{y^3 x^2}} dy \end{aligned}$$

Which results in

$$S = \frac{y^4 x^2}{4}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{y^4 - 2x^2}{2x y^3}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= \frac{x y^4}{2} \\ S_y &= y^3 x^2 \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = x^3 \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = R^3$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = \frac{R^4}{4} + c_1 \quad (4)$$

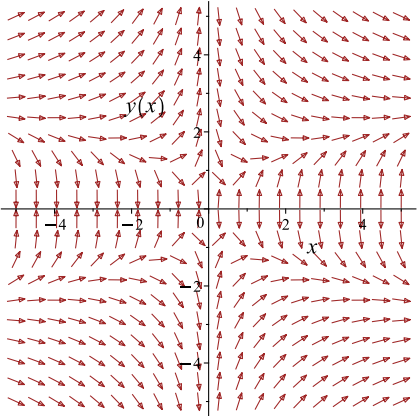
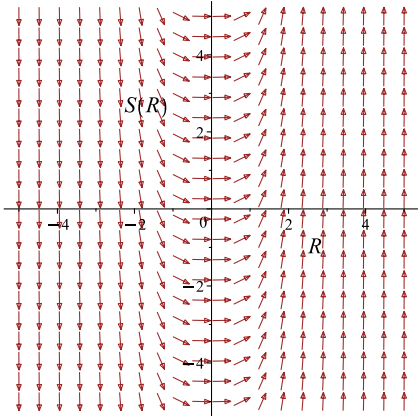
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$\frac{y^4 x^2}{4} = \frac{x^4}{4} + c_1$$

Which simplifies to

$$\frac{y^4 x^2}{4} = \frac{x^4}{4} + c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{y^4 - 2x^2}{2xy^3}$ 	$R = x$ $S = \frac{y^4 x^2}{4}$	$\frac{dS}{dR} = R^3$ 

Initial conditions are used to solve for c_1 . Substituting $x = 1$ and $y = 2$ in the above solution gives an equation to solve for the constant of integration.

$$4 = \frac{1}{4} + c_1$$

$$c_1 = \frac{15}{4}$$

Substituting c_1 found above in the general solution gives

$$\frac{y^4 x^2}{4} = \frac{x^4}{4} + \frac{15}{4}$$

Summary

The solution(s) found are the following

$$\frac{y^4 x^2}{4} = \frac{x^4}{4} + \frac{15}{4} \quad (1)$$

Verification of solutions

$$\frac{y^4 x^2}{4} = \frac{x^4}{4} + \frac{15}{4}$$

Verified OK.

5.25.3 Solving as bernoulli ode

In canonical form, the ODE is

$$\begin{aligned} y' &= F(x, y) \\ &= -\frac{y^4 - 2x^2}{2x y^3} \end{aligned}$$

This is a Bernoulli ODE.

$$y' = -\frac{1}{2x}y + x\frac{1}{y^3} \quad (1)$$

The standard Bernoulli ODE has the form

$$y' = f_0(x)y + f_1(x)y^n \quad (2)$$

The first step is to divide the above equation by y^n which gives

$$\frac{y'}{y^n} = f_0(x)y^{1-n} + f_1(x) \quad (3)$$

The next step is use the substitution $w = y^{1-n}$ in equation (3) which generates a new ODE in $w(x)$ which will be linear and can be easily solved using an integrating factor. Backsubstitution then gives the solution $y(x)$ which is what we want.

This method is now applied to the ODE at hand. Comparing the ODE (1) With (2) Shows that

$$\begin{aligned} f_0(x) &= -\frac{1}{2x} \\ f_1(x) &= x \\ n &= -3 \end{aligned}$$

Dividing both sides of ODE (1) by $y^n = \frac{1}{y^3}$ gives

$$y'y^3 = -\frac{y^4}{2x} + x \quad (4)$$

Let

$$\begin{aligned} w &= y^{1-n} \\ &= y^4 \end{aligned} \quad (5)$$

Taking derivative of equation (5) w.r.t x gives

$$w' = 4y^3y' \quad (6)$$

Substituting equations (5) and (6) into equation (4) gives

$$\begin{aligned} \frac{w'(x)}{4} &= -\frac{w(x)}{2x} + x \\ w' &= -\frac{2w}{x} + 4x \end{aligned} \quad (7)$$

The above now is a linear ODE in $w(x)$ which is now solved.

Entering Linear first order ODE solver. In canonical form a linear first order is

$$w'(x) + p(x)w(x) = q(x)$$

Where here

$$\begin{aligned} p(x) &= \frac{2}{x} \\ q(x) &= 4x \end{aligned}$$

Hence the ode is

$$w'(x) + \frac{2w(x)}{x} = 4x$$

The integrating factor μ is

$$\begin{aligned} \mu &= e^{\int \frac{2}{x} dx} \\ &= x^2 \end{aligned}$$

The ode becomes

$$\begin{aligned} \frac{d}{dx}(\mu w) &= (\mu)(4x) \\ \frac{d}{dx}(x^2 w) &= (x^2)(4x) \\ d(x^2 w) &= (4x^3) dx \end{aligned}$$

Integrating gives

$$x^2 w = \int 4x^3 dx$$

$$x^2 w = x^4 + c_1$$

Dividing both sides by the integrating factor $\mu = x^2$ results in

$$w(x) = x^2 + \frac{c_1}{x^2}$$

Replacing w in the above by y^4 using equation (5) gives the final solution.

$$y^4 = x^2 + \frac{c_1}{x^2}$$

Initial conditions are used to solve for c_1 . Substituting $x = 1$ and $y = 2$ in the above solution gives an equation to solve for the constant of integration.

$$16 = 1 + c_1$$

$$c_1 = 15$$

Substituting c_1 found above in the general solution gives

$$y^4 = \frac{x^4 + 15}{x^2}$$

The above simplifies to

$$y^4 x^2 - x^4 - 15 = 0$$

Summary

The solution(s) found are the following

$$y^4 x^2 - x^4 - 15 = 0 \tag{1}$$

Verification of solutions

$$y^4 x^2 - x^4 - 15 = 0$$

Verified OK.

5.25.4 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \quad (\text{A})$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \quad (\text{B})$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (\text{1A})$$

Therefore

$$\begin{aligned} (2x y^3) dy &= (-y^4 + 2x^2) dx \\ (y^4 - 2x^2) dx + (2x y^3) dy &= 0 \end{aligned} \quad (\text{2A})$$

Comparing (1A) and (2A) shows that

$$\begin{aligned} M(x, y) &= y^4 - 2x^2 \\ N(x, y) &= 2x y^3 \end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(y^4 - 2x^2) \\ &= 4y^3\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(2x y^3) \\ &= 2y^3\end{aligned}$$

Since $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$\begin{aligned}A &= \frac{1}{N} \left(\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} \right) \\ &= \frac{1}{2x y^3} ((4y^3) - (2y^3)) \\ &= \frac{1}{x}\end{aligned}$$

Since A does not depend on y , then it can be used to find an integrating factor. The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int A dx} \\ &= e^{\int \frac{1}{x} dx}\end{aligned}$$

The result of integrating gives

$$\begin{aligned}\mu &= e^{\ln(x)} \\ &= x\end{aligned}$$

M and N are multiplied by this integrating factor, giving new M and new N which are called \bar{M} and \bar{N} for now so not to confuse them with the original M and N .

$$\begin{aligned}\bar{M} &= \mu M \\ &= x(y^4 - 2x^2) \\ &= x y^4 - 2x^3\end{aligned}$$

And

$$\begin{aligned}\bar{N} &= \mu N \\ &= x(2x y^3) \\ &= 2y^3 x^2\end{aligned}$$

Now a modified ODE is obtained from the original ODE, which is exact and can be solved. The modified ODE is

$$\begin{aligned}\bar{M} + \bar{N} \frac{dy}{dx} &= 0 \\ (x y^4 - 2x^3) + (2y^3 x^2) \frac{dy}{dx} &= 0\end{aligned}$$

The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = \bar{M} \quad (1)$$

$$\frac{\partial \phi}{\partial y} = \bar{N} \quad (2)$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int \bar{M} dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int x y^4 - 2x^3 dx \\ \phi &= -\frac{(-y^4 + 2x^2)^2}{8} + f(y)\end{aligned} \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\begin{aligned}\frac{\partial \phi}{\partial y} &= (-y^4 + 2x^2) y^3 + f'(y) \\ &= -y^7 + 2y^3 x^2 + f'(y)\end{aligned} \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = 2y^3 x^2$. Therefore equation (4) becomes

$$2y^3 x^2 = -y^7 + 2y^3 x^2 + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = y^7$$

Integrating the above w.r.t y gives

$$\int f'(y) dy = \int (y^7) dy$$

$$f(y) = \frac{y^8}{8} + c_1$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = -\frac{(-y^4 + 2x^2)^2}{8} + \frac{y^8}{8} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -\frac{(-y^4 + 2x^2)^2}{8} + \frac{y^8}{8}$$

Initial conditions are used to solve for c_1 . Substituting $x = 1$ and $y = 2$ in the above solution gives an equation to solve for the constant of integration.

$$\frac{15}{2} = c_1$$

$$c_1 = \frac{15}{2}$$

Substituting c_1 found above in the general solution gives

$$-\frac{(-y^4 + 2x^2)^2}{8} + \frac{y^8}{8} = \frac{15}{2}$$

Summary

The solution(s) found are the following

$$\frac{y^4 x^2}{2} - \frac{x^4}{2} = \frac{15}{2} \quad (1)$$

Verification of solutions

$$\frac{y^4 x^2}{2} - \frac{x^4}{2} = \frac{15}{2}$$

Verified OK.

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
trying Bernoulli  
<- Bernoulli successful`
```

✓ Solution by Maple

Time used: 0.078 (sec). Leaf size: 17

```
dsolve([diff(y(x),x)+y(x)/(2*x)=x/y(x)^3,y(1) = 2],y(x), singsol=all)
```

$$y(x) = \sqrt{\frac{\sqrt{x^4 + 15}}{x}}$$

✓ Solution by Mathematica

Time used: 0.277 (sec). Leaf size: 20

```
DSolve[{y'[x]+y[x]/(2*x)==x/y[x]^3,{y[1]==2}},y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{\sqrt[4]{x^4 + 15}}{\sqrt{x}}$$

5.26 problem 26

5.26.1 Existence and uniqueness analysis	1119
5.26.2 Solving as first order ode lie symmetry calculated ode	1120
5.26.3 Solving as exact ode	1126

Internal problem ID [11663]

Internal file name [OUTPUT/11672_Wednesday_April_10_2024_04_54_07_PM_3027235/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.3 (Linear equations). Exercises page 56

Problem number: 26.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"exactWithIntegrationFactor", "first_order_ode_lie_symmetry_calculated"**

Maple gives the following as the ode type

```
[[_homogeneous, `class G`], _rational]
```

$$y'x + y - (yx)^{\frac{3}{2}} = 0$$

With initial conditions

$$[y(1) = 4]$$

5.26.1 Existence and uniqueness analysis

This is non linear first order ODE. In canonical form it is written as

$$\begin{aligned} y' &= f(x, y) \\ &= \frac{-y + (xy)^{\frac{3}{2}}}{x} \end{aligned}$$

The x domain of $f(x, y)$ when $y = 4$ is

$$\{0 < x\}$$

And the point $x_0 = 1$ is inside this domain. The y domain of $f(x, y)$ when $x = 1$ is

$$\{0 \leq y\}$$

And the point $y_0 = 4$ is inside this domain. Now we will look at the continuity of

$$\begin{aligned} \frac{\partial f}{\partial y} &= \frac{\partial}{\partial y} \left(\frac{-y + (xy)^{\frac{3}{2}}}{x} \right) \\ &= \frac{-1 + \frac{3x\sqrt{xy}}{2}}{x} \end{aligned}$$

The x domain of $\frac{\partial f}{\partial y}$ when $y = 4$ is

$$\{0 < x\}$$

And the point $x_0 = 1$ is inside this domain. The y domain of $\frac{\partial f}{\partial y}$ when $x = 1$ is

$$\{0 \leq y\}$$

And the point $y_0 = 4$ is inside this domain. Therefore solution exists and is unique.

5.26.2 Solving as first order ode lie symmetry calculated ode

Writing the ode as

$$\begin{aligned} y' &= \frac{-y + (xy)^{\frac{3}{2}}}{x} \\ y' &= \omega(x, y) \end{aligned}$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is not in the lookup table. To determine ξ, η then (A) is solved using ansatz. Making bivariate polynomials of degree 1 to use as anstaz gives

$$\xi = xa_2 + ya_3 + a_1 \quad (1\text{E})$$

$$\eta = xb_2 + yb_3 + b_1 \quad (2\text{E})$$

Where the unknown coefficients are

$$\{a_1, a_2, a_3, b_1, b_2, b_3\}$$

Substituting equations (1E,2E) and ω into (A) gives

$$\begin{aligned}
& b_2 + \frac{\left(-y + (xy)^{\frac{3}{2}}\right) (b_3 - a_2)}{x} - \frac{\left(-y + (xy)^{\frac{3}{2}}\right)^2 a_3}{x^2} \\
& - \left(\frac{3\sqrt{xy}y}{2x} - \frac{-y + (xy)^{\frac{3}{2}}}{x^2}\right) (xa_2 + ya_3 + a_1) \\
& - \frac{\left(-1 + \frac{3x\sqrt{xy}}{2}\right) (xb_2 + yb_3 + b_1)}{x} = 0
\end{aligned} \tag{5E}$$

Putting the above in normal form gives

$$\frac{-2x^3y^3a_3 + 2(xy)^{\frac{3}{2}}xb_3 + 6(xy)^{\frac{3}{2}}ya_3 - 3\sqrt{xy}x^3b_2 - 3\sqrt{xy}x^2ya_2 - 3\sqrt{xy}x^2yb_3 - 3\sqrt{xy}xy^2a_3 + 2(xy)^{\frac{3}{2}}a_1}{2x^2} = 0$$

Setting the numerator to zero gives

$$\begin{aligned}
& -2x^3y^3a_3 + 2(xy)^{\frac{3}{2}}xb_3 + 6(xy)^{\frac{3}{2}}ya_3 - 3\sqrt{xy}x^3b_2 - 3\sqrt{xy}x^2ya_2 \\
& - 3\sqrt{xy}x^2yb_3 - 3\sqrt{xy}xy^2a_3 + 2(xy)^{\frac{3}{2}}a_1 - 3\sqrt{xy}x^2b_1 \\
& - 3\sqrt{xy}xya_1 + 4b_2x^2 - 4y^2a_3 + 2xb_1 - 2ya_1 = 0
\end{aligned} \tag{6E}$$

Since the PDE has radicals, simplifying gives

$$\begin{aligned}
& -2x^3y^3a_3 - 3\sqrt{xy}x^3b_2 - 3\sqrt{xy}x^2ya_2 - \sqrt{xy}x^2yb_3 + 3\sqrt{xy}xy^2a_3 \\
& - 3\sqrt{xy}x^2b_1 - \sqrt{xy}xya_1 + 4b_2x^2 - 4y^2a_3 + 2xb_1 - 2ya_1 = 0
\end{aligned}$$

Looking at the above PDE shows the following are all the terms with $\{x, y\}$ in them.

$$\{x, y, \sqrt{xy}\}$$

The following substitution is now made to be able to collect on all terms with $\{x, y\}$ in them

$$\{x = v_1, y = v_2, \sqrt{xy} = v_3\}$$

The above PDE (6E) now becomes

$$\begin{aligned}
& -2v_1^3v_2^3a_3 - 3v_3v_1^2v_2a_2 + 3v_3v_1v_2^2a_3 - 3v_3v_1^3b_2 - v_3v_1^2v_2b_3 \\
& - v_3v_1v_2a_1 - 3v_3v_1^2b_1 - 4v_2^2a_3 + 4b_2v_1^2 - 2v_2a_1 + 2v_1b_1 = 0
\end{aligned} \tag{7E}$$

Collecting the above on the terms v_i introduced, and these are

$$\{v_1, v_2, v_3\}$$

Equation (7E) now becomes

$$\begin{aligned} -2v_1^3v_2^3a_3 - 3v_3v_1^3b_2 + (-3a_2 - b_3)v_1^2v_2v_3 - 3v_3v_1^2b_1 + 4b_2v_1^2 \\ + 3v_3v_1v_2^2a_3 - v_3v_1v_2a_1 + 2v_1b_1 - 4v_2^2a_3 - 2v_2a_1 = 0 \end{aligned} \quad (8E)$$

Setting each coefficients in (8E) to zero gives the following equations to solve

$$\begin{aligned} -2a_1 &= 0 \\ -a_1 &= 0 \\ -4a_3 &= 0 \\ -2a_3 &= 0 \\ 3a_3 &= 0 \\ -3b_1 &= 0 \\ 2b_1 &= 0 \\ -3b_2 &= 0 \\ 4b_2 &= 0 \\ -3a_2 - b_3 &= 0 \end{aligned}$$

Solving the above equations for the unknowns gives

$$\begin{aligned} a_1 &= 0 \\ a_2 &= a_2 \\ a_3 &= 0 \\ b_1 &= 0 \\ b_2 &= 0 \\ b_3 &= -3a_2 \end{aligned}$$

Substituting the above solution in the anstaz (1E,2E) (using 1 as arbitrary value for any unknown in the RHS) gives

$$\begin{aligned} \xi &= x \\ \eta &= -3y \end{aligned}$$

Shifting is now applied to make $\xi = 0$ in order to simplify the rest of the computation

$$\begin{aligned}\eta &= \eta - \omega(x, y) \xi \\ &= -3y - \left(\frac{-y + (xy)^{\frac{3}{2}}}{x} \right) (x) \\ &= -2y - (xy)^{\frac{3}{2}} \\ \xi &= 0\end{aligned}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \quad (1)$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y} \right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned}S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{-2y - (xy)^{\frac{3}{2}}} dy\end{aligned}$$

Which results in

$$S = \frac{\ln(x\sqrt{xy} + 2)}{2} - \frac{\ln(x\sqrt{xy} - 2)}{2} + \frac{\ln(yx^3 - 4)}{2} - \frac{\ln(y)}{2}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = \frac{-y + (xy)^{\frac{3}{2}}}{x}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= \frac{3x^2y - 6\sqrt{x}\sqrt{y}}{2yx^3 - 8} \\ S_y &= -\frac{x^{\frac{3}{2}}y - 2\sqrt{y}}{y^{\frac{3}{2}}(yx^3 - 4)} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = \frac{3x^3y^{\frac{3}{2}} - 2x^{\frac{5}{2}}\sqrt{xy}y + 4x\sqrt{xy}\sqrt{y} - 4x^{\frac{3}{2}}y - 4\sqrt{y}}{2\sqrt{y}(yx^3 - 4)x} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = -\frac{2}{R}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = -2 \ln(R) + c_1 \quad (4)$$

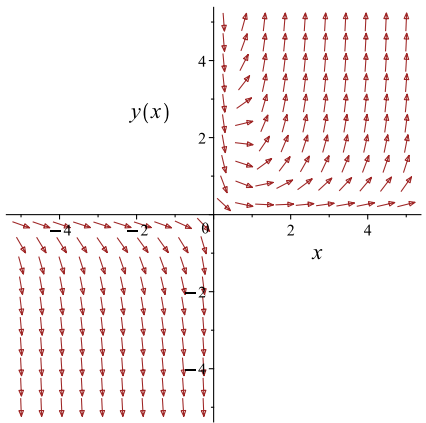
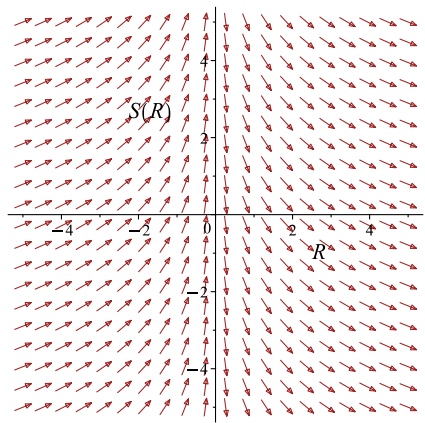
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$\frac{\ln\left(\sqrt{y}x^{\frac{3}{2}} + 2\right)}{2} - \frac{\ln\left(\sqrt{y}x^{\frac{3}{2}} - 2\right)}{2} + \frac{\ln(yx^3 - 4)}{2} - \frac{\ln(y)}{2} = -2 \ln(x) + c_1$$

Which simplifies to

$$\frac{\ln\left(\sqrt{y}x^{\frac{3}{2}} + 2\right)}{2} - \frac{\ln\left(\sqrt{y}x^{\frac{3}{2}} - 2\right)}{2} + \frac{\ln(yx^3 - 4)}{2} - \frac{\ln(y)}{2} = -2 \ln(x) + c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = \frac{-y+(xy)^{\frac{3}{2}}}{x}$ 	$R = x$ $S = \frac{\ln(\sqrt{y}x^{\frac{3}{2}} + 2)}{2}$	$\frac{dS}{dR} = -\frac{2}{R}$ 

Initial conditions are used to solve for c_1 . Substituting $x = 1$ and $y = 4$ in the above solution gives an equation to solve for the constant of integration.

$$\ln(2) = c_1$$

$$c_1 = \ln(2)$$

Substituting c_1 found above in the general solution gives

$$\frac{\ln(\sqrt{y}x^{\frac{3}{2}} + 2)}{2} - \frac{\ln(\sqrt{y}x^{\frac{3}{2}} - 2)}{2} + \frac{\ln(yx^3 - 4)}{2} - \frac{\ln(y)}{2} = -2\ln(x) + \ln(2)$$

Summary

The solution(s) found are the following

$$\frac{\ln(\sqrt{y}x^{\frac{3}{2}} + 2)}{2} - \frac{\ln(\sqrt{y}x^{\frac{3}{2}} - 2)}{2} + \frac{\ln(yx^3 - 4)}{2} - \frac{\ln(y)}{2} = -2\ln(x) + \ln(2) \quad (1)$$

Verification of solutions

$$\frac{\ln(\sqrt{y}x^{\frac{3}{2}} + 2)}{2} - \frac{\ln(\sqrt{y}x^{\frac{3}{2}} - 2)}{2} + \frac{\ln(yx^3 - 4)}{2} - \frac{\ln(y)}{2} = -2\ln(x) + \ln(2)$$

Verified OK.

5.26.3 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \quad (\text{A})$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \quad (\text{B})$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (\text{1A})$$

Therefore

$$\begin{aligned} (x) dy &= \left(-y + (xy)^{\frac{3}{2}} \right) dx \\ \left(y - (xy)^{\frac{3}{2}} \right) dx + (x) dy &= 0 \end{aligned} \quad (\text{2A})$$

Comparing (1A) and (2A) shows that

$$\begin{aligned} M(x, y) &= y - (xy)^{\frac{3}{2}} \\ N(x, y) &= x \end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y} \left(y - (xy)^{\frac{3}{2}} \right) \\ &= 1 - \frac{3x\sqrt{xy}}{2}\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(x) \\ &= 1\end{aligned}$$

Since $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$\begin{aligned}A &= \frac{1}{N} \left(\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} \right) \\ &= \frac{1}{x} \left(\left(1 - \frac{3x\sqrt{xy}}{2} \right) - (1) \right) \\ &= -\frac{3\sqrt{xy}}{2}\end{aligned}$$

Since A depends on y , it can not be used to obtain an integrating factor. We will now try a second method to find an integrating factor. Let

$$\begin{aligned}B &= \frac{1}{M} \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) \\ &= -\frac{1}{y(x\sqrt{xy} - 1)} \left((1) - \left(1 - \frac{3x\sqrt{xy}}{2} \right) \right) \\ &= -\frac{3x\sqrt{xy}}{2y(x\sqrt{xy} - 1)}\end{aligned}$$

Since B depends on x , it can not be used to obtain an integrating factor. We will now try a third method to find an integrating factor. Let

$$R = \frac{\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y}}{xM - yN}$$

R is now checked to see if it is a function of only $t = xy$. Therefore

$$\begin{aligned} R &= \frac{\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y}}{xM - yN} \\ &= \frac{(1) - \left(1 - \frac{3x\sqrt{xy}}{2}\right)}{x\left(y - (xy)^{\frac{3}{2}}\right) - y(x)} \\ &= -\frac{3}{2xy} \end{aligned}$$

Replacing all powers of terms xy by t gives

$$R = -\frac{3}{2t}$$

Since R depends on t only, then it can be used to find an integrating factor. Let the integrating factor be μ then

$$\begin{aligned} \mu &= e^{\int R dt} \\ &= e^{\int \left(-\frac{3}{2t}\right) dt} \end{aligned}$$

The result of integrating gives

$$\begin{aligned} \mu &= e^{-\frac{3 \ln(t)}{2}} \\ &= \frac{1}{t^{\frac{3}{2}}} \end{aligned}$$

Now t is replaced back with xy giving

$$\mu = \frac{1}{(xy)^{\frac{3}{2}}}$$

Multiplying M and N by this integrating factor gives new M and new N which are called \overline{M} and \overline{N} so not to confuse them with the original M and N

$$\begin{aligned} \overline{M} &= \mu M \\ &= \frac{1}{(xy)^{\frac{3}{2}}} \left(y - (xy)^{\frac{3}{2}} \right) \\ &= -\frac{x\sqrt{xy} - 1}{x\sqrt{xy}} \end{aligned}$$

And

$$\begin{aligned} \overline{N} &= \mu N \\ &= \frac{1}{(xy)^{\frac{3}{2}}} (x) \\ &= \frac{1}{y\sqrt{xy}} \end{aligned}$$

A modified ODE is now obtained from the original ODE, which is exact and can be solved. The modified ODE is

$$\begin{aligned} \overline{M} + \overline{N} \frac{dy}{dx} &= 0 \\ \left(-\frac{x\sqrt{xy} - 1}{x\sqrt{xy}} \right) + \left(\frac{1}{y\sqrt{xy}} \right) \frac{dy}{dx} &= 0 \end{aligned}$$

The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = \overline{M} \quad (1)$$

$$\frac{\partial \phi}{\partial y} = \overline{N} \quad (2)$$

Integrating (1) w.r.t. x gives

$$\begin{aligned} \int \frac{\partial \phi}{\partial x} dx &= \int \overline{M} dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int -\frac{x\sqrt{xy} - 1}{x\sqrt{xy}} dx \\ \phi &= -x - \frac{2}{\sqrt{xy}} + f(y) \end{aligned} \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = \frac{x}{(xy)^{\frac{3}{2}}} + f'(y) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = \frac{1}{y\sqrt{xy}}$. Therefore equation (4) becomes

$$\frac{1}{y\sqrt{xy}} = \frac{x}{y\sqrt{xy}} + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 0$$

Therefore

$$f(y) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(y)$ into equation (3) gives ϕ

$$\phi = -x - \frac{2}{\sqrt{xy}} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -x - \frac{2}{\sqrt{xy}}$$

The solution becomes

$$y = \frac{4}{x(c_1^2 + 2c_1x + x^2)}$$

Initial conditions are used to solve for c_1 . Substituting $x = 1$ and $y = 4$ in the above solution gives an equation to solve for the constant of integration.

$$4 = \frac{4}{c_1^2 + 2c_1 + 1}$$

$$c_1 = -2$$

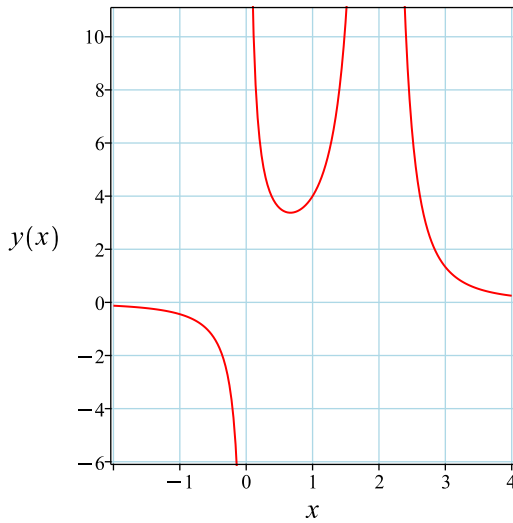
Substituting c_1 found above in the general solution gives

$$y = \frac{4}{x(x^2 - 4x + 4)}$$

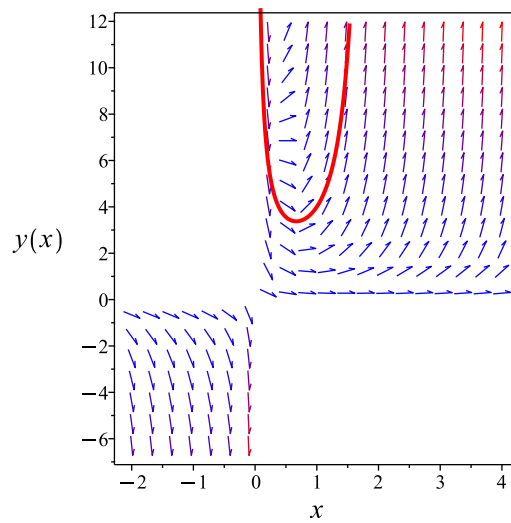
Summary

The solution(s) found are the following

$$y = \frac{4}{x(x^2 - 4x + 4)} \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \frac{4}{x(x^2 - 4x + 4)}$$

Verified OK.

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying homogeneous types:
trying homogeneous G
1st order, trying the canonical coordinates of the invariance group
<- 1st order, canonical coordinates successful
<- homogeneous successful`

```

✓ Solution by Maple

Time used: 0.203 (sec). Leaf size: 9

```
dsolve([x*diff(y(x),x)+y(x)=(x*y(x))^(3/2),y(1) = 4],y(x), singsol=all)
```

$$y(x) = \frac{4}{x^3}$$

✓ Solution by Mathematica

Time used: 0.258 (sec). Leaf size: 24

```
DSolve[{x*y'[x]+y[x]==(x*y[x])^(3/2),{y[1]==4}},y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{4}{x^3}$$

$$y(x) \rightarrow \frac{4}{(x-2)^2 x}$$

5.27 problem 27

5.27.1 Existence and uniqueness analysis	1133
5.27.2 Solving as linear ode	1134
5.27.3 Solving as first order ode lie symmetry lookup ode	1137
5.27.4 Maple step by step solution	1141

Internal problem ID [11664]

Internal file name [OUTPUT/11673_Wednesday_April_10_2024_04_54_24_PM_95791151/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.3 (Linear equations). Exercises page 56

Problem number: 27.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"linear", "first_order_ode_lie_symmetry_lookup"**

Maple gives the following as the ode type

```
[[_linear, `class A`]]
```

$$y' + y = \begin{cases} 2 & 0 \leq x < 1 \\ 0 & 1 \leq x \end{cases}$$

With initial conditions

$$[y(0) = 0]$$

5.27.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = 1$$
$$q(x) = \begin{cases} 0 & x < 0 \\ 2 & 0 < x < 1 \\ 0 & 1 \leq x \end{cases}$$

Hence the ode is

$$y' + y = \begin{cases} 0 & x < 0 \\ 2 & 0 < x < 1 \\ 0 & 1 \leq x \end{cases}$$

The domain of $p(x) = 1$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = \begin{cases} 0 & x < 0 \\ 2 & 0 < x < 1 \\ 0 & 1 \leq x \end{cases}$ is

$$\{0 \leq x \leq 1, 1 \leq x \leq \infty, -\infty \leq x \leq 0\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

5.27.2 Solving as linear ode

Entering Linear first order ODE solver. The integrating factor μ is

$$\begin{aligned} \mu &= e^{\int 1 dx} \\ &= e^x \end{aligned}$$

The ode becomes

$$\frac{d}{dx}(\mu y) = (\mu) \left(\begin{cases} 0 & x < 0 \\ 2 & x < 1 \\ 0 & 1 \leq x \end{cases} \right)$$

$$\frac{d}{dx}(e^x y) = (e^x) \left(\begin{cases} 0 & x < 0 \\ 2 & x < 1 \\ 0 & 1 \leq x \end{cases} \right)$$

$$d(e^x y) = \begin{cases} 0 & x < 0 \\ 2e^x & x < 1 \quad dx \\ 0 & 1 \leq x \end{cases}$$

Integrating gives

$$e^x y = \int \begin{cases} 0 & x < 0 \\ 2e^x & x < 1 \quad dx \\ 0 & 1 \leq x \end{cases}$$

$$e^x y = \begin{cases} 0 & x \leq 0 \\ 2e^x - 2 & x \leq 1 \quad + c_1 \\ 2e - 2 & 1 < x \end{cases}$$

Dividing both sides by the integrating factor $\mu = e^x$ results in

$$y = e^{-x} \left(\begin{cases} 0 & x \leq 0 \\ 2e^x - 2 & x \leq 1 \\ 2e - 2 & 1 < x \end{cases} \right) + c_1 e^{-x}$$

which simplifies to

$$y = e^{-x} \left(-2 \left(\begin{cases} 0 & x \leq 0 \\ 1 - e^x & x \leq 1 \\ 1 - e & 1 < x \end{cases} \right) + c_1 \right)$$

Initial conditions are used to solve for c_1 . Substituting $x = 0$ and $y = 0$ in the above solution gives an equation to solve for the constant of integration.

$$0 = c_1$$

$$c_1 = 0$$

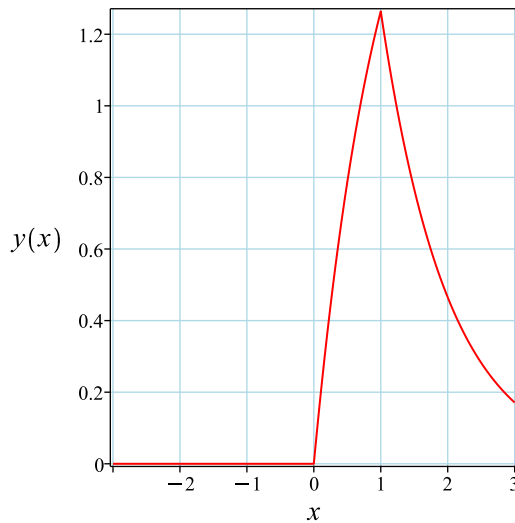
Substituting c_1 found above in the general solution gives

$$y = \begin{cases} 0 & x \leq 0 \\ 2 - 2e^{-x} & 0 < x \leq 1 \\ 2e^{1-x} - 2e^{-x} & 1 < x \\ 0 & \text{otherwise} \end{cases}$$

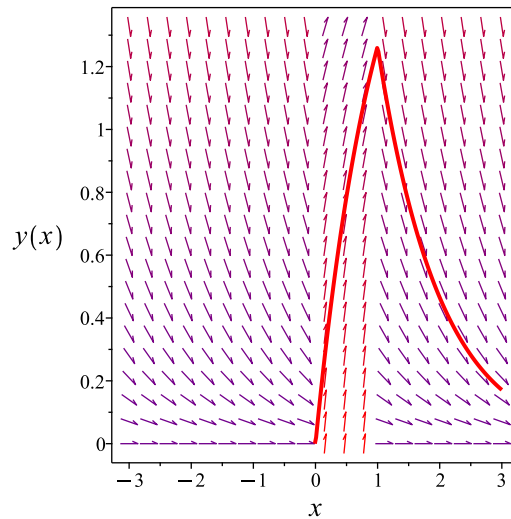
Summary

The solution(s) found are the following

$$y = \begin{cases} 0 & x \leq 0 \\ 2 - 2e^{-x} & 0 < x \leq 1 \\ 2e^{1-x} - 2e^{-x} & 1 < x \\ 0 & \text{otherwise} \end{cases} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \begin{cases} 0 & x \leq 0 \\ 2 - 2e^{-x} & 0 < x \leq 1 \\ 2e^{1-x} - 2e^{-x} & 1 < x \\ 0 & \text{otherwise} \end{cases}$$

Verified OK.

5.27.3 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = -y + \begin{pmatrix} 2 & 0 \leq x < 1 \\ 0 & 1 \leq x \end{pmatrix}$$
$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 182: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= e^{-x}\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{e^{-x}} dy \end{aligned}$$

Which results in

$$S = e^x y$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -y + \left(\begin{cases} 2 & 0 \leq x < 1 \\ 0 & 1 \leq x \end{cases} \right)$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= e^x y \\ S_y &= e^x \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = \begin{cases} 0 & x < 0 \\ 2e^x & 0 \leq x < 1 \\ 0 & 1 \leq x \end{cases} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = \begin{cases} 0 & R < 0 \\ 2e^R & 0 \leq R < 1 \\ 0 & 1 \leq R \end{cases}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = \begin{cases} c_1 & R < 0 \\ c_1 + 2e^R - 2 & 0 < R < 1 \\ c_1 + 2e - 2 & 1 \leq R \end{cases} \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$y e^x = \begin{cases} c_1 & x < 0 \\ c_1 + 2e^x - 2 & 0 < x < 1 \\ c_1 + 2e - 2 & 1 \leq x \end{cases}$$

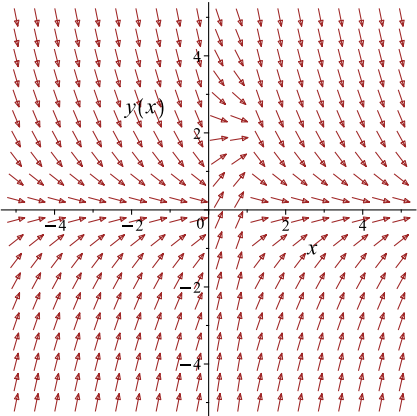
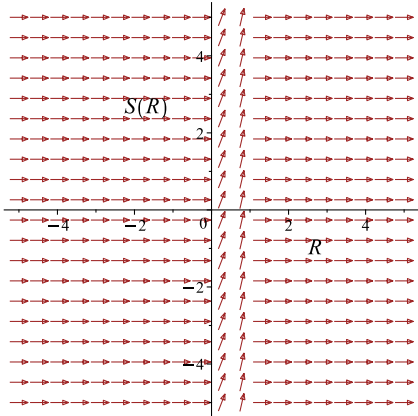
Which simplifies to

$$y e^x = \begin{cases} c_1 & x < 0 \\ c_1 + 2e^x - 2 & 0 < x < 1 \\ c_1 + 2e - 2 & 1 \leq x \end{cases}$$

Which gives

$$y = \begin{cases} [c_1 e^{-x}] & x < 0 \\ [2 + (-2 + c_1) e^{-x}] & 0 < x < 1 \\ [e^{-x}(c_1 + 2e - 2)] & 1 \leq x \end{cases}$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -y + \begin{cases} 2 & 0 \leq x < 1 \\ 0 & 1 \leq x \end{cases}$ 	$R = x$ $S = e^x y$	$\frac{dS}{dR} = \begin{cases} 0 & R < 0 \\ 2e^R & 0 < R < 1 \\ 0 & 1 \leq R \end{cases}$ 

Initial conditions are used to solve for c_1 . Substituting $x = 0$ and $y = 0$ in the above solution gives an equation to solve for the constant of integration.

$$0 = [c_1]$$

Unable to solve for constant of integration. Verification of solutions N/A

5.27.4 Maple step by step solution

Let's solve

$$\left[y' + y = \begin{cases} 2 & 0 \leq x < 1 \\ 0 & 1 \leq x \end{cases}, y(0) = 0 \right]$$

- Highest derivative means the order of the ODE is 1

y'

- Isolate the derivative

$$y' = -y + \begin{cases} 2 & 0 \leq x < 1 \\ 0 & 1 \leq x \end{cases}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE

$$y' + y = \begin{cases} 2 & 0 \leq x < 1 \\ 0 & 1 \leq x \end{cases}$$

- The ODE is linear; multiply by an integrating factor $\mu(x)$

$$\mu(x)(y' + y) = \mu(x) \left(\begin{cases} 2 & 0 \leq x < 1 \\ 0 & 1 \leq x \end{cases} \right)$$

- Assume the lhs of the ODE is the total derivative $\frac{d}{dx}(\mu(x)y)$

$$\mu(x)(y' + y) = \mu'(x)y + \mu(x)y'$$

- Isolate $\mu'(x)$

$$\mu'(x) = \mu(x)$$

- Solve to find the integrating factor

$$\mu(x) = e^x$$

- Integrate both sides with respect to x

$$\int \left(\frac{d}{dx}(\mu(x)y) \right) dx = \int \mu(x) \left(\begin{cases} 2 & 0 \leq x < 1 \\ 0 & 1 \leq x \end{cases} \right) dx + c_1$$

- Evaluate the integral on the lhs

$$\mu(x)y = \int \mu(x) \left(\begin{cases} 2 & 0 \leq x < 1 \\ 0 & 1 \leq x \end{cases} \right) dx + c_1$$

- Solve for y

$$y = \frac{\int \mu(x) \left(\begin{cases} 2 & 0 \leq x < 1 \\ 0 & 1 \leq x \end{cases} \right) dx + c_1}{\mu(x)}$$

- Substitute $\mu(x) = e^x$

$$y = \frac{\int e^x \left(\begin{cases} 2 & 0 \leq x < 1 \\ 0 & 1 \leq x \end{cases} \right) dx + c_1}{e^x}$$

- Evaluate the integrals on the rhs

$$y = \frac{\begin{cases} 0 & x \leq 0 \\ 2e^x - 2 & 0 < x \leq 1 \\ 2e - 2 & 1 < x \end{cases} + c_1}{e^x}$$

- Simplify

$$y = e^{-x} \left(-2 \left(\begin{cases} 0 & x \leq 0 \\ 1 - e^x & 0 < x \leq 1 \\ 1 - e & 1 < x \end{cases} \right) + c_1 \right)$$

- Use initial condition $y(0) = 0$

$$0 = c_1$$

- Solve for c_1

$$c_1 = 0$$

- Substitute $c_1 = 0$ into general solution and simplify

$$y = -2e^{-x} \left(\begin{cases} 0 & x \leq 0 \\ 1 - e^x & 0 < x \leq 1 \\ 1 - e & 1 < x \end{cases} \right)$$

- Solution to the IVP

$$y = -2e^{-x} \left(\begin{cases} 0 & x \leq 0 \\ 1 - e^x & 0 < x \leq 1 \\ 1 - e & 1 < x \end{cases} \right)$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
<- 1st order linear successful`

```


✓ Solution by Maple

Time used: 0.328 (sec). Leaf size: 38

```
dsolve([diff(y(x),x)+y(x)=piecewise(0<=x and x<1,2,x>=1,0),y(0) = 0],y(x), singsol=all)
```

$$y(x) = \begin{cases} 0 & x < 0 \\ 2 - 2e^{-x} & 0 < x < 1 \\ 2e^{1-x} - 2e^{-x} & 1 \leq x \end{cases}$$

✓ Solution by Mathematica

Time used: 0.062 (sec). Leaf size: 38

```
DSolve[{y'[x]+y[x]==Piecewise[{{2,0<=x<1},{0,x>=1}}],{y[0]==0}],y[x],x,IncludeSingularSoluti
```

$$y(x) \rightarrow \begin{cases} 0 & x \leq 0 \\ 2 - 2e^{-x} & 0 < x \leq 1 \\ 2(-1 + e)e^{-x} & \text{True} \end{cases}$$

5.28 problem 28

5.28.1 Existence and uniqueness analysis	1145
5.28.2 Solving as linear ode	1146
5.28.3 Solving as first order ode lie symmetry lookup ode	1149
5.28.4 Maple step by step solution	1153

Internal problem ID [11665]

Internal file name [OUTPUT/11674_Wednesday_April_10_2024_04_54_25_PM_60313912/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.3 (Linear equations). Exercises page 56

Problem number: 28.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**linear**", "**first_order_ode_lie_symmetry_lookup**"

Maple gives the following as the ode type

```
[[_linear, `class A`]]
```

$$y' + y = \begin{cases} 5 & 0 \leq x < 10 \\ 1 & 10 \leq x \end{cases}$$

With initial conditions

$$[y(0) = 6]$$

5.28.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = 1$$
$$q(x) = \begin{cases} 0 & x < 0 \\ 5 & 0 < x < 10 \\ 1 & 10 \leq x \end{cases}$$

Hence the ode is

$$y' + y = \begin{cases} 0 & x < 0 \\ 5 & 0 < x < 10 \\ 1 & 10 \leq x \end{cases}$$

The domain of $p(x) = 1$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = \begin{cases} 0 & x < 0 \\ 5 & 0 < x < 10 \\ 1 & 10 \leq x \end{cases}$ is

$$\{0 \leq x \leq 10, 10 \leq x \leq \infty, -\infty \leq x \leq 0\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

5.28.2 Solving as linear ode

Entering Linear first order ODE solver. The integrating factor μ is

$$\begin{aligned} \mu &= e^{\int 1 dx} \\ &= e^x \end{aligned}$$

The ode becomes

$$\frac{d}{dx}(\mu y) = (\mu) \left(\begin{cases} 0 & x < 0 \\ 5 & x < 10 \\ 1 & 10 \leq x \end{cases} \right)$$

$$\frac{d}{dx}(e^x y) = (e^x) \left(\begin{cases} 0 & x < 0 \\ 5 & x < 10 \\ 1 & 10 \leq x \end{cases} \right)$$

$$d(e^x y) = \left(\left(\begin{cases} 0 & x < 0 \\ 5 & x < 10 \\ 1 & 10 \leq x \end{cases} \right) e^x \right) dx$$

Integrating gives

$$e^x y = \int \left(\begin{cases} 0 & x < 0 \\ 5 & x < 10 \\ 1 & 10 \leq x \end{cases} \right) e^x dx$$

$$e^x y = \begin{cases} 0 & x \leq 0 \\ 5e^x - 5 & x \leq 10 \\ e^x + 4e^{10} - 5 & 10 < x \end{cases} + c_1$$

Dividing both sides by the integrating factor $\mu = e^x$ results in

$$y = e^{-x} \left(\begin{cases} 0 & x \leq 0 \\ 5e^x - 5 & x \leq 10 \\ e^x + 4e^{10} - 5 & 10 < x \end{cases} \right) + c_1 e^{-x}$$

which simplifies to

$$y = e^{-x} \left(\left(\begin{cases} 0 & x \leq 0 \\ 5e^x - 5 & x \leq 10 \\ e^x + 4e^{10} - 5 & 10 < x \end{cases} \right) + c_1 \right)$$

Initial conditions are used to solve for c_1 . Substituting $x = 0$ and $y = 6$ in the above solution gives an equation to solve for the constant of integration.

$$6 = c_1$$

$$c_1 = 6$$

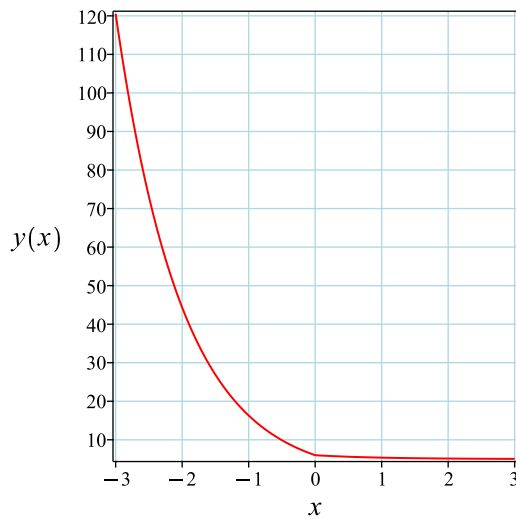
Substituting c_1 found above in the general solution gives

$$y = \begin{cases} 6e^{-x} & x \leq 0 \\ 5 + e^{-x} & 0 < x \leq 10 \\ 4e^{10-x} + 1 + e^{-x} & 10 < x \\ 6e^{-x} & \text{otherwise} \end{cases}$$

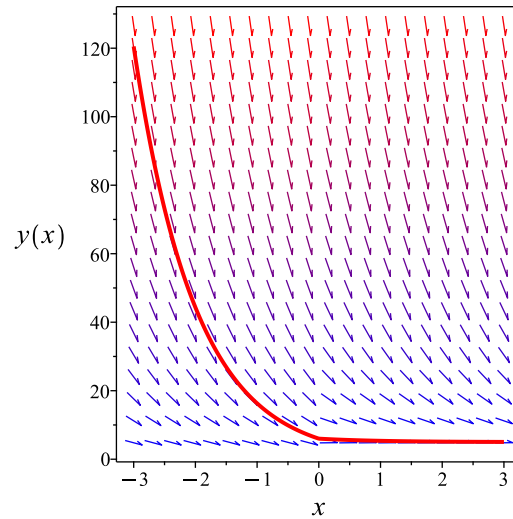
Summary

The solution(s) found are the following

$$y = \begin{cases} 6e^{-x} & x \leq 0 \\ 5 + e^{-x} & 0 < x \leq 10 \\ 4e^{10-x} + 1 + e^{-x} & 10 < x \\ 6e^{-x} & \text{otherwise} \end{cases} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \begin{cases} 6e^{-x} & x \leq 0 \\ 5 + e^{-x} & 0 < x \leq 10 \\ 4e^{10-x} + 1 + e^{-x} & 10 < x \\ 6e^{-x} & \text{otherwise} \end{cases}$$

Verified OK.

5.28.3 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = -y + \left(\begin{cases} 5 & 0 \leq x < 10 \\ 1 & 10 \leq x \end{cases} \right)$$
$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 185: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= e^{-x}\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{e^{-x}} dy \end{aligned}$$

Which results in

$$S = e^x y$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -y + \left(\begin{cases} 5 & 0 \leq x < 10 \\ 1 & 10 \leq x \end{cases} \right)$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= e^x y \\ S_y &= e^x \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = \left(\begin{cases} 0 & x < 0 \\ 5 & x < 10 \\ 1 & 10 \leq x \end{cases} \right) e^x \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = \left(\begin{cases} 0 & R < 0 \\ 5 & R < 10 \\ 1 & 10 \leq R \end{cases} \right) e^R$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = \begin{cases} c_1 & R < 0 \\ c_1 + 5e^R - 5 & 0 < R < 10 \\ c_1 + e^R + 4e^{10} - 5 & 10 \leq R \end{cases} \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$y e^x = \begin{cases} c_1 & x < 0 \\ c_1 + 5e^x - 5 & 0 < x < 10 \\ c_1 + e^x + 4e^{10} - 5 & 10 \leq x \end{cases}$$

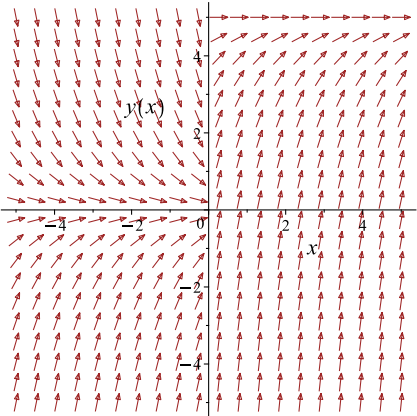
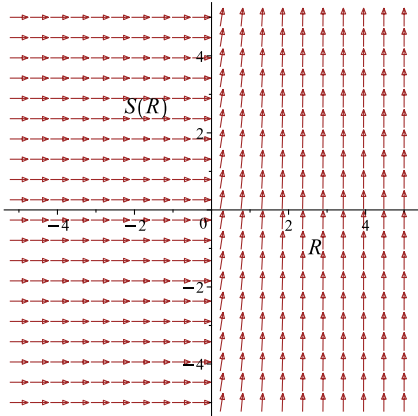
Which simplifies to

$$y e^x = \begin{cases} c_1 & x < 0 \\ c_1 + 5e^x - 5 & 0 < x < 10 \\ c_1 + e^x + 4e^{10} - 5 & 10 \leq x \end{cases}$$

Which gives

$$y = \begin{cases} [c_1 e^{-x}] & x < 0 \\ [5 + (c_1 - 5) e^{-x}] & 0 < x < 10 \\ [4e^{10-x} + 1 + (c_1 - 5) e^{-x}] & 10 \leq x \end{cases}$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -y + \begin{cases} 5 & 0 \leq x < 10 \\ 1 & 10 \leq x \end{cases}$ 	$R = x$ $S = e^x y$	$\frac{dS}{dR} = \begin{cases} 0 & R < 0 \\ 5 & 0 \leq R < 10 \\ 1 & 10 \leq R \end{cases} e^R$ 

Initial conditions are used to solve for c_1 . Substituting $x = 0$ and $y = 6$ in the above solution gives an equation to solve for the constant of integration.

$$6 = [c_1]$$

Unable to solve for constant of integration. Verification of solutions N/A

5.28.4 Maple step by step solution

Let's solve

$$\left[y' + y = \begin{cases} 5 & 0 \leq x < 10 \\ 1 & 10 \leq x \end{cases}, y(0) = 6 \right]$$

- Highest derivative means the order of the ODE is 1
- y'
- Isolate the derivative

$$y' = -y + \begin{cases} 5 & 0 \leq x < 10 \\ 1 & 10 \leq x \end{cases}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE

$$y' + y = \begin{cases} 5 & 0 \leq x < 10 \\ 1 & 10 \leq x \end{cases}$$

- The ODE is linear; multiply by an integrating factor $\mu(x)$

$$\mu(x)(y' + y) = \mu(x) \left(\begin{cases} 5 & 0 \leq x < 10 \\ 1 & 10 \leq x \end{cases} \right)$$

- Assume the lhs of the ODE is the total derivative $\frac{d}{dx}(\mu(x)y)$

$$\mu(x)(y' + y) = \mu'(x)y + \mu(x)y'$$

- Isolate $\mu'(x)$

$$\mu'(x) = \mu(x)$$

- Solve to find the integrating factor

$$\mu(x) = e^x$$

- Integrate both sides with respect to x

$$\int \left(\frac{d}{dx}(\mu(x)y) \right) dx = \int \mu(x) \left(\begin{cases} 5 & 0 \leq x < 10 \\ 1 & 10 \leq x \end{cases} \right) dx + c_1$$

- Evaluate the integral on the lhs

$$\mu(x)y = \int \mu(x) \left(\begin{cases} 5 & 0 \leq x < 10 \\ 1 & 10 \leq x \end{cases} \right) dx + c_1$$

- Solve for y

$$y = \frac{\int \mu(x) \left(\begin{cases} 5 & 0 \leq x < 10 \\ 1 & 10 \leq x \end{cases} \right) dx + c_1}{\mu(x)}$$

- Substitute $\mu(x) = e^x$

$$y = \frac{\int e^x \left(\begin{cases} 5 & 0 \leq x < 10 \\ 1 & 10 \leq x \end{cases} \right) dx + c_1}{e^x}$$

- Evaluate the integrals on the rhs

$$y = \frac{\begin{cases} 0 & x \leq 0 \\ 5e^x - 5 & 0 < x \leq 10 \\ e^x + 4e^{10} - 5 & 10 < x \end{cases} + c_1}{e^x}$$

- Simplify

$$y = e^{-x} \left(\begin{cases} 0 & x \leq 0 \\ 5e^x - 5 & 0 < x \leq 10 \\ e^x + 4e^{10} - 5 & 10 < x \end{cases} + c_1 \right)$$

- Use initial condition $y(0) = 6$

$$6 = c_1$$

- Solve for c_1

$$c_1 = 6$$

- Substitute $c_1 = 6$ into general solution and simplify

$$y = e^{-x} \left(\begin{cases} 6 & x \leq 0 \\ 1 + 5e^x & 0 < x \leq 10 \\ 1 + e^x + 4e^{10} & 10 < x \end{cases} \right)$$

- Solution to the IVP

$$y = e^{-x} \left(\begin{cases} 6 & x \leq 0 \\ 1 + 5e^x & 0 < x \leq 10 \\ 1 + e^x + 4e^{10} & 10 < x \end{cases} \right)$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
<- 1st order linear successful`

```

✓ Solution by Maple

Time used: 7.219 (sec). Leaf size: 40

```
dsolve([diff(y(x),x)+y(x)=piecewise(0<=x and x<10,5,x>=10,1),y(0) = 6],y(x), singsol=all)
```

$$y(x) = \begin{cases} 6e^{-x} & x < 0 \\ e^{-x} + 5 & 0 < x < 10 \\ e^{-x} + 1 + 4e^{10-x} & 10 \leq x \end{cases}$$

✓ Solution by Mathematica

Time used: 0.061 (sec). Leaf size: 45

```
DSolve[{y'[x]+y[x]==Piecewise[{{5,0<=x<10},{1,x>=10}}],{y[0]==6}],y[x],x,IncludeSingularSolu
```

$$y(x) \rightarrow \begin{cases} 6e^{-x} & x \leq 0 \\ e^{-x}(1 + 4e^{10} + e^x) & 0 < x < 10 \\ 5 + e^{-x} & \text{True} \end{cases}$$

5.29 problem 29

5.29.1 Existence and uniqueness analysis	1157
5.29.2 Solving as linear ode	1158
5.29.3 Solving as first order ode lie symmetry lookup ode	1161
5.29.4 Maple step by step solution	1165

Internal problem ID [11666]

Internal file name [OUTPUT/11675_Wednesday_April_10_2024_04_54_26_PM_30453963/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.3 (Linear equations). Exercises page 56

Problem number: 29.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"linear", "first_order_ode_lie_symmetry_lookup"**

Maple gives the following as the ode type

```
[[_linear, `class A`]]
```

$$y' + y = \begin{cases} e^{-x} & 0 \leq x < 2 \\ e^{-2} & 2 \leq x \end{cases}$$

With initial conditions

$$[y(0) = 1]$$

5.29.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = 1$$
$$q(x) = \begin{cases} 0 & x < 0 \\ e^{-x} & 0 < x < 2 \\ e^{-2} & 2 \leq x \end{cases}$$

Hence the ode is

$$y' + y = \begin{cases} 0 & x < 0 \\ e^{-x} & 0 < x < 2 \\ e^{-2} & 2 \leq x \end{cases}$$

The domain of $p(x) = 1$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = \begin{cases} 0 & x < 0 \\ e^{-x} & 0 < x < 2 \\ e^{-2} & 2 \leq x \end{cases}$ is

$$\{x < 0 \vee 0 < x\}$$

But the point $x_0 = 0$ is not inside this domain. Hence existence and uniqueness theorem does not apply. There could be infinite number of solutions, or one solution or no solution at all.

5.29.2 Solving as linear ode

Entering Linear first order ODE solver. The integrating factor μ is

$$\begin{aligned} \mu &= e^{\int 1 dx} \\ &= e^x \end{aligned}$$

The ode becomes

$$\frac{d}{dx}(\mu y) = (\mu) \left(\begin{cases} 0 & x < 0 \\ e^{-x} & x < 2 \\ e^{-2} & 2 \leq x \end{cases} \right)$$

$$\frac{d}{dx}(e^x y) = (e^x) \left(\begin{cases} 0 & x < 0 \\ e^{-x} & x < 2 \\ e^{-2} & 2 \leq x \end{cases} \right)$$

$$d(e^x y) = \begin{cases} 0 & x < 0 \\ 1 & x < 2 \quad dx \\ e^{x-2} & 2 \leq x \end{cases}$$

Integrating gives

$$e^x y = \int \begin{cases} 0 & x < 0 \\ 1 & x < 2 \quad dx \\ e^{x-2} & 2 \leq x \end{cases}$$

$$e^x y = \begin{cases} 0 & x \leq 0 \\ x & x \leq 2 \quad + c_1 \\ e^{x-2} + 1 & 2 < x \end{cases}$$

Dividing both sides by the integrating factor $\mu = e^x$ results in

$$y = e^{-x} \left(\begin{cases} 0 & x \leq 0 \\ x & x \leq 2 \\ e^{x-2} + 1 & 2 < x \end{cases} \right) + c_1 e^{-x}$$

which simplifies to

$$y = e^{-x} \left(\left(\begin{cases} 0 & x \leq 0 \\ x & x \leq 2 \\ e^{x-2} + 1 & 2 < x \end{cases} \right) + c_1 \right)$$

Initial conditions are used to solve for c_1 . Substituting $x = 0$ and $y = 1$ in the above solution gives an equation to solve for the constant of integration.

$$1 = c_1$$

$$c_1 = 1$$

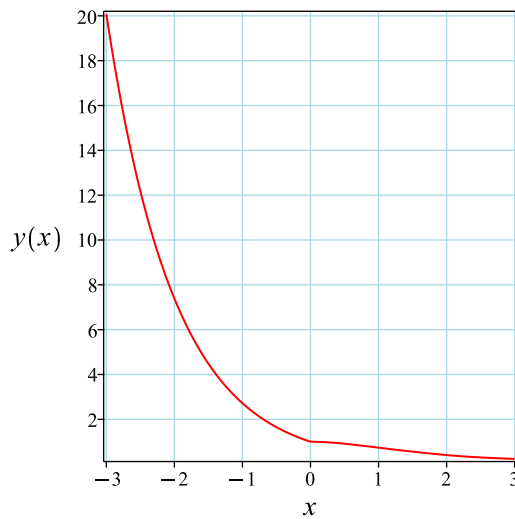
Substituting c_1 found above in the general solution gives

$$y = \begin{cases} e^{-x} & x \leq 0 \\ x e^{-x} + e^{-x} & 0 < x \leq 2 \\ e^{-2} + 2 e^{-x} & 2 < x \\ e^{-x} & \text{otherwise} \end{cases}$$

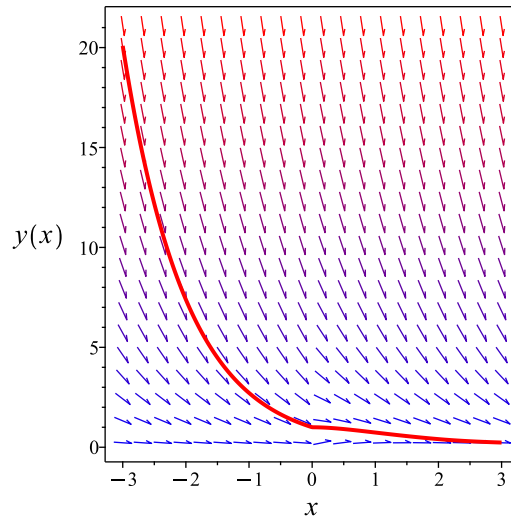
Summary

The solution(s) found are the following

$$y = \begin{cases} e^{-x} & x \leq 0 \\ x e^{-x} + e^{-x} & 0 < x \leq 2 \\ e^{-2} + 2 e^{-x} & 2 < x \\ e^{-x} & \text{otherwise} \end{cases} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \begin{cases} e^{-x} & x \leq 0 \\ x e^{-x} + e^{-x} & 0 < x \leq 2 \\ e^{-2} + 2e^{-x} & 2 < x \\ e^{-x} & \text{otherwise} \end{cases}$$

Verified OK.

5.29.3 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = -y + \begin{pmatrix} e^{-x} & 0 \leq x < 2 \\ e^{-2} & 2 \leq x \end{pmatrix}$$
$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 188: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= e^{-x}\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{e^{-x}} dy \end{aligned}$$

Which results in

$$S = e^x y$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -y + \left(\begin{cases} e^{-x} & 0 \leq x < 2 \\ e^{-2} & 2 \leq x \end{cases} \right)$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= e^x y \\ S_y &= e^x \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = \begin{cases} 0 & x < 0 \\ 1 & 0 < x < 2 \\ e^{x-2} & 2 \leq x \end{cases} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = \begin{cases} 0 & R < 0 \\ 1 & 0 < R < 2 \\ e^{R-2} & 2 \leq R \end{cases}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = \begin{cases} c_1 & R < 0 \\ c_1 + R & 0 < R < 2 \\ c_1 + e^{R-2} + 1 & 2 \leq R \end{cases} \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$y e^x = \begin{cases} c_1 & x < 0 \\ x + c_1 & 0 < x < 2 \\ c_1 + e^{x-2} + 1 & 2 \leq x \end{cases}$$

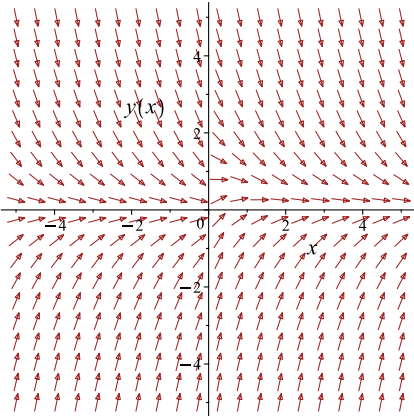
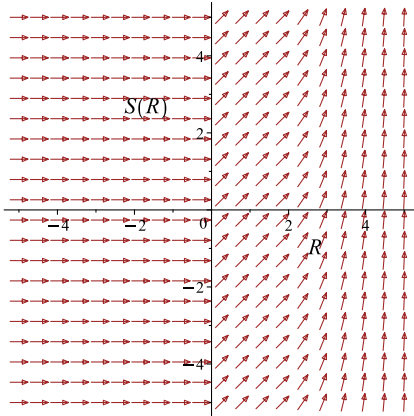
Which simplifies to

$$y e^x = \begin{cases} c_1 & x < 0 \\ x + c_1 & 0 < x < 2 \\ c_1 + e^{x-2} + 1 & 2 \leq x \end{cases}$$

Which gives

$$y = \begin{cases} [c_1 e^{-x}] & x < 0 \\ [e^{-x}(x + c_1)] & 0 < x < 2 \\ [e^{-x}(c_1 + e^{x-2} + 1)] & 2 \leq x \end{cases}$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -y + \begin{cases} e^{-x} & 0 \leq x < 2 \\ e^{-2} & 2 \leq x \end{cases}$ 	$R = x$ $S = e^x y$	$\frac{dS}{dR} = \begin{cases} 0 & R < 0 \\ 1 & 0 \leq R < 2 \\ e^{R-2} & 2 \leq R \end{cases}$ 

Initial conditions are used to solve for c_1 . Substituting $x = 0$ and $y = 1$ in the above solution gives an equation to solve for the constant of integration.

$$1 = [c_1]$$

Unable to solve for constant of integration. Verification of solutions N/A

5.29.4 Maple step by step solution

Let's solve

$$\left[y' + y = \begin{cases} e^{-x} & 0 \leq x < 2 \\ e^{-2} & 2 \leq x \end{cases}, y(0) = 1 \right]$$

- Highest derivative means the order of the ODE is 1
- Isolate the derivative

$$y' = -y + \begin{cases} e^{-x} & 0 \leq x < 2 \\ e^{-2} & 2 \leq x \end{cases}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE

$$y' + y = \begin{cases} e^{-x} & 0 \leq x < 2 \\ e^{-2} & 2 \leq x \end{cases}$$

- The ODE is linear; multiply by an integrating factor $\mu(x)$

$$\mu(x)(y' + y) = \mu(x) \left(\begin{cases} e^{-x} & 0 \leq x < 2 \\ e^{-2} & 2 \leq x \end{cases} \right)$$

- Assume the lhs of the ODE is the total derivative $\frac{d}{dx}(\mu(x)y)$

$$\mu(x)(y' + y) = \mu'(x)y + \mu(x)y'$$

- Isolate $\mu'(x)$

$$\mu'(x) = \mu(x)$$

- Solve to find the integrating factor

$$\mu(x) = e^x$$

- Integrate both sides with respect to x

$$\int \left(\frac{d}{dx}(\mu(x)y) \right) dx = \int \mu(x) \left(\begin{cases} e^{-x} & 0 \leq x < 2 \\ e^{-2} & 2 \leq x \end{cases} \right) dx + c_1$$

- Evaluate the integral on the lhs

$$\mu(x)y = \int \mu(x) \left(\begin{cases} e^{-x} & 0 \leq x < 2 \\ e^{-2} & 2 \leq x \end{cases} \right) dx + c_1$$

- Solve for y

$$y = \frac{\int \mu(x) \left(\begin{cases} e^{-x} & 0 \leq x < 2 \\ e^{-2} & 2 \leq x \end{cases} \right) dx + c_1}{\mu(x)}$$

- Substitute $\mu(x) = e^x$

$$y = \frac{\int e^x \left(\begin{cases} e^{-x} & 0 \leq x < 2 \\ e^{-2} & 2 \leq x \end{cases} \right) dx + c_1}{e^x}$$

- Evaluate the integrals on the rhs

$$y = \frac{\begin{cases} 0 & x \leq 0 \\ x & 0 < x \leq 2 \\ e^{x-2} + 1 & 2 < x \end{cases} + c_1}{e^x}$$

- Simplify

$$y = e^{-x} \left(\begin{cases} 0 & x \leq 0 \\ x & 0 < x \leq 2 \\ e^{x-2} + 1 & 2 < x \end{cases} + c_1 \right)$$

- Use initial condition $y(0) = 1$

$$1 = c_1$$

- Solve for c_1

$$c_1 = 1$$

- Substitute $c_1 = 1$ into general solution and simplify

$$y = e^{-x} \left(\begin{cases} 0 & x \leq 0 \\ x & 0 < x \leq 2 \\ e^{x-2} + 1 & 2 < x \end{cases} + 1 \right)$$

- Solution to the IVP

$$y = e^{-x} \left(\begin{cases} 0 & x \leq 0 \\ x & 0 < x \leq 2 \\ e^{x-2} + 1 & 2 < x \end{cases} + 1 \right)$$

Maple trace

```
`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
<- 1st order linear successful`
```


✓ Solution by Maple

Time used: 0.359 (sec). Leaf size: 35

```
dsolve([diff(y(x),x)+y(x)=piecewise(0<=x and x<2,exp(-x),x>=2,exp(-2)),y(0) = 1],y(x), sings
```

$$y(x) = \begin{cases} e^{-x} & x < 0 \\ e^{-x}(1+x) & 0 < x < 2 \\ 2e^{-x} + e^{-2} & 2 \leq x \end{cases}$$

✓ Solution by Mathematica

Time used: 0.103 (sec). Leaf size: 40

```
DSolve[{y'[x]+y[x]==Piecewise[{{Exp[-x],0<=x<2},{Exp[-2],x>=2}},{y[0]==1}],y[x],x,IncludeSi
```

$$y(x) \rightarrow \begin{cases} e^{-x} & x \leq 0 \\ \frac{1}{e^2} + 2e^{-x} & x > 2 \\ e^{-x}(x+1) & \text{True} \end{cases}$$

5.30 problem 30

5.30.1 Existence and uniqueness analysis	1169
5.30.2 Solving as linear ode	1170
5.30.3 Solving as first order ode lie symmetry lookup ode	1173
5.30.4 Maple step by step solution	1179

Internal problem ID [11667]

Internal file name [OUTPUT/11676_Wednesday_April_10_2024_04_54_27_PM_23925784/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.3 (Linear equations). Exercises page 56

Problem number: 30.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"linear", "first_order_ode_lie_symmetry_lookup"**

Maple gives the following as the ode type

`[_linear]`

$$(x + 2)y' + y = \begin{cases} 2x & 0 \leq x < 2 \\ 4 & 2 \leq x \end{cases}$$

With initial conditions

$$[y(0) = 4]$$

5.30.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = \frac{1}{x+2}$$
$$q(x) = \frac{2 \left(\begin{array}{l} 0 \quad x < 0 \\ x \quad x < 2 \\ 2 \quad 2 \leq x \end{array} \right)}{x+2}$$

Hence the ode is

$$y' + \frac{y}{x+2} = \frac{2 \left(\begin{array}{l} 0 \quad x < 0 \\ x \quad x < 2 \\ 2 \quad 2 \leq x \end{array} \right)}{x+2}$$

The domain of $p(x) = \frac{1}{x+2}$ is

$$\{x < -2 \vee -2 < x\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = \frac{2 \left(\begin{array}{l} 0 \quad x < 0 \\ x \quad x < 2 \\ 2 \quad 2 \leq x \end{array} \right)}{x+2}$ is

$$\{x < -2 \vee -2 < x\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

5.30.2 Solving as linear ode

Entering Linear first order ODE solver. The integrating factor μ is

$$\begin{aligned} \mu &= e^{\int \frac{1}{x+2} dx} \\ &= x + 2 \end{aligned}$$

The ode becomes

$$\frac{d}{dx}(\mu y) = (\mu) \left(\frac{2 \left(\begin{cases} 0 & x < 0 \\ x & x < 2 \\ 2 & 2 \leq x \end{cases} \right)}{x+2} \right)$$

$$\frac{d}{dx}((x+2)y) = (x+2) \left(\frac{2 \left(\begin{cases} 0 & x < 0 \\ x & x < 2 \\ 2 & 2 \leq x \end{cases} \right)}{x+2} \right)$$

$$d((x+2)y) = \left(2 \left(\begin{cases} 0 & x < 0 \\ x & x < 2 \\ 2 & 2 \leq x \end{cases} \right) \right) dx$$

Integrating gives

$$(x+2)y = \int 2 \left(\begin{cases} 0 & x < 0 \\ x & x < 2 \\ 2 & 2 \leq x \end{cases} \right) dx$$

$$(x+2)y = 2 \left(\begin{cases} 0 & x \leq 0 \\ \frac{x^2}{2} & x \leq 2 \\ 2x-2 & 2 < x \end{cases} \right) + c_1$$

Dividing both sides by the integrating factor $\mu = x + 2$ results in

$$y = \frac{2 \left(\begin{cases} 0 & x \leq 0 \\ \frac{x^2}{2} & x \leq 2 \\ 2x-2 & 2 < x \end{cases} \right)}{x+2} + \frac{c_1}{x+2}$$

which simplifies to

$$y = \frac{\left(\begin{cases} 0 & x \leq 0 \\ x^2 & x \leq 2 \\ 4x - 4 & 2 < x \end{cases} \right) + c_1}{x + 2}$$

Initial conditions are used to solve for c_1 . Substituting $x = 0$ and $y = 4$ in the above solution gives an equation to solve for the constant of integration.

$$4 = \frac{c_1}{2}$$

$$c_1 = 8$$

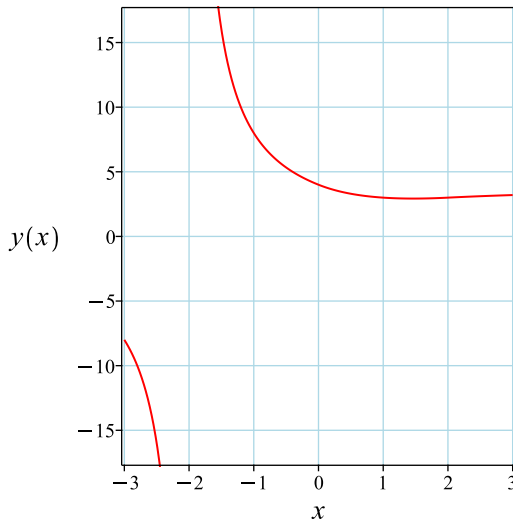
Substituting c_1 found above in the general solution gives

$$y = \begin{cases} \frac{8}{x+2} & x \leq 0 \\ \frac{x^2+8}{x+2} & x \leq 2 \\ \frac{4+4x}{x+2} & 2 < x \\ \frac{8}{x+2} & \text{otherwise} \end{cases}$$

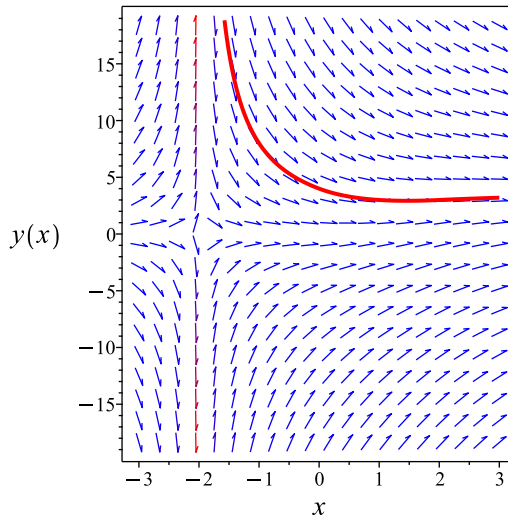
Summary

The solution(s) found are the following

$$y = \begin{cases} \frac{8}{x+2} & x \leq 0 \\ \frac{x^2+8}{x+2} & x \leq 2 \\ \frac{4+4x}{x+2} & 2 < x \\ \frac{8}{x+2} & \text{otherwise} \end{cases} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \begin{cases} \frac{8}{x+2} & x \leq 0 \\ \frac{x^2+8}{x+2} & 0 < x \leq 2 \\ \frac{4+4x}{x+2} & 2 < x \\ \frac{8}{x+2} & \text{otherwise} \end{cases}$$

Verified OK.

5.30.3 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = - \frac{\left(\begin{cases} 2x & 0 \leq x < 2 \\ 4 & 2 \leq x \end{cases} \right)}{x+2}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 191: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= \frac{1}{x+2}\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{1}{x+2}} dy \end{aligned}$$

Which results in

$$S = (x + 2) y$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = - \frac{y - \left(\begin{cases} 2x & 0 \leq x < 2 \\ 4 & 2 \leq x \end{cases} \right)}{x + 2}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= y \\ S_y &= x + 2 \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 2 \left(\begin{cases} 0 & x < 0 \\ x & x < 2 \\ 2 & 2 \leq x \end{cases} \right) \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 2 \left(\begin{cases} 0 & R < 0 \\ R & R < 2 \\ 2 & 2 \leq R \end{cases} \right)$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = \begin{cases} c_1 & R < 0 \\ R^2 + c_1 & R < 2 \\ c_1 - 4 + 4R & 2 \leq R \end{cases} \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$(x+2)y = \begin{cases} c_1 & x < 0 \\ x^2 + c_1 & x < 2 \\ c_1 + 4x - 4 & 2 \leq x \end{cases}$$

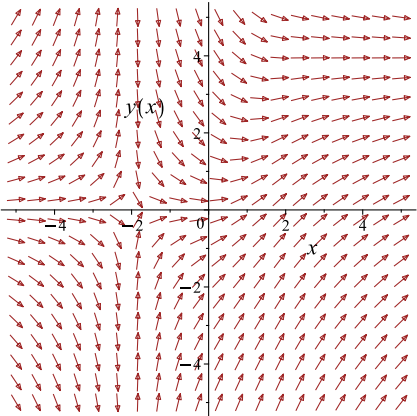
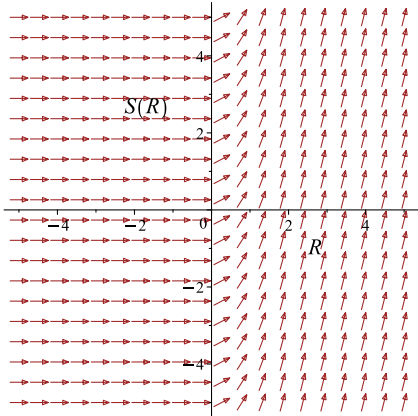
Which simplifies to

$$(x+2)y = \begin{cases} c_1 & x < 0 \\ x^2 + c_1 & x < 2 \\ c_1 + 4x - 4 & 2 \leq x \end{cases}$$

Which gives

$$y = \frac{\begin{cases} c_1 & x < 0 \\ x^2 + c_1 & x < 2 \\ c_1 + 4x - 4 & 2 \leq x \end{cases}}{x+2}$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{y \begin{cases} 2x & 0 \leq x < 2 \\ 4 & 2 \leq x \end{cases}}{x+2}$ 	$R = x$ $S = (x + 2)y$	$\frac{dS}{dR} = 2 \begin{cases} 0 & R < 0 \\ R & R < 2 \\ 2 & 2 \leq R \end{cases}$ 

Initial conditions are used to solve for c_1 . Substituting $x = 0$ and $y = 4$ in the above solution gives an equation to solve for the constant of integration.

$$4 = \frac{c_1}{2}$$

$$c_1 = 8$$

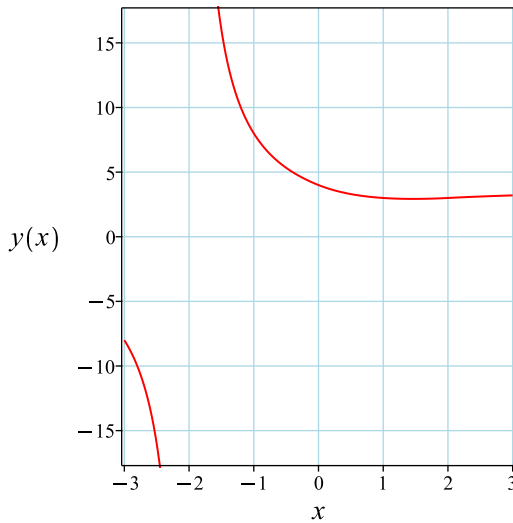
Substituting c_1 found above in the general solution gives

$$y = \begin{cases} \frac{8}{x+2} & x < 0 \\ \frac{x^2+8}{x+2} & 0 < x < 2 \\ \frac{4+4x}{x+2} & 2 \leq x \\ 0 & \text{otherwise} \end{cases}$$

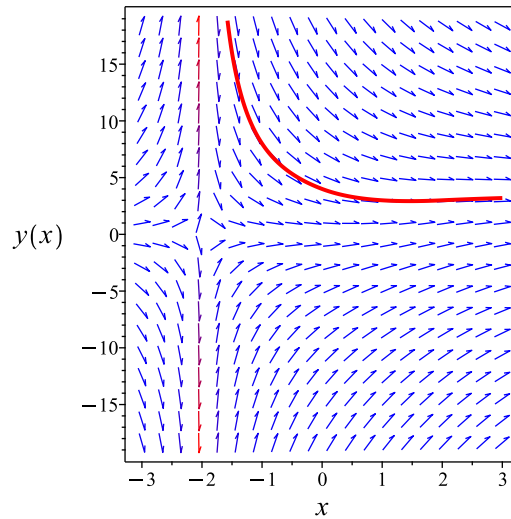
Summary

The solution(s) found are the following

$$y = \begin{cases} \frac{8}{x+2} & x < 0 \\ \frac{x^2+8}{x+2} & 0 < x < 2 \\ \frac{4+4x}{x+2} & 2 \leq x \\ 0 & \text{otherwise} \end{cases} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \begin{cases} \frac{8}{x+2} & x < 0 \\ \frac{x^2+8}{x+2} & 0 < x < 2 \\ \frac{4+4x}{x+2} & 2 \leq x \\ 0 & \text{otherwise} \end{cases}$$

Verified OK.

5.30.4 Maple step by step solution

Let's solve

$$\left[(x+2)y' + y = \begin{cases} 2x & 0 \leq x < 2 \\ 4 & 2 \leq x \end{cases}, y(0) = 4 \right]$$

- Highest derivative means the order of the ODE is 1

$$y'$$

- Isolate the derivative

$$y' = -\frac{y}{x+2} + \frac{\begin{cases} 2x & 0 \leq x < 2 \\ 4 & 2 \leq x \end{cases}}{x+2}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE

$$y' + \frac{y}{x+2} = \frac{\begin{cases} 2x & 0 \leq x < 2 \\ 4 & 2 \leq x \end{cases}}{x+2}$$

- The ODE is linear; multiply by an integrating factor $\mu(x)$

$$\mu(x) \left(y' + \frac{y}{x+2} \right) = \frac{\mu(x) \left(\begin{cases} 2x & 0 \leq x < 2 \\ 4 & 2 \leq x \end{cases} \right)}{x+2}$$

- Assume the lhs of the ODE is the total derivative $\frac{d}{dx}(\mu(x)y)$

$$\mu(x) \left(y' + \frac{y}{x+2} \right) = \mu'(x)y + \mu(x)y'$$

- Isolate $\mu'(x)$

$$\mu'(x) = \frac{\mu(x)}{x+2}$$

- Solve to find the integrating factor

$$\mu(x) = x + 2$$

- Integrate both sides with respect to x

$$\int \left(\frac{d}{dx}(\mu(x)y) \right) dx = \int \frac{\mu(x) \left(\begin{cases} 2x & 0 \leq x < 2 \\ 4 & 2 \leq x \end{cases} \right)}{x+2} dx + c_1$$

- Evaluate the integral on the lhs

$$\mu(x) y = \int \frac{\mu(x) \left(\begin{cases} 2x & 0 \leq x < 2 \\ 4 & 2 \leq x \end{cases} \right)}{x+2} dx + c_1$$

- Solve for y

$$y = \frac{\int \frac{\mu(x) \left(\begin{cases} 2x & 0 \leq x < 2 \\ 4 & 2 \leq x \end{cases} \right)}{x+2} dx + c_1}{\mu(x)}$$

- Substitute $\mu(x) = x + 2$

$$y = \frac{\int \left(\begin{cases} 2x & 0 \leq x < 2 \\ 4 & 2 \leq x \end{cases} \right) dx + c_1}{x+2}$$

- Evaluate the integrals on the rhs

$$y = \frac{\begin{cases} 0 & x \leq 0 \\ x^2 & 0 < x \leq 2 \\ 4x - 4 & 2 < x \end{cases} + c_1}{x+2}$$

- Use initial condition $y(0) = 4$

$$4 = \frac{c_1}{2}$$

- Solve for c_1

$$c_1 = 8$$

- Substitute $c_1 = 8$ into general solution and simplify

$$y = \frac{\begin{cases} 0 & x \leq 0 \\ x^2 & 0 < x \leq 2 \\ 4x - 4 & 2 < x \end{cases} + 8}{x+2}$$

- Solution to the IVP

$$y = \frac{\begin{cases} 0 & x \leq 0 \\ x^2 & 0 < x \leq 2 \\ 4x - 4 & 2 < x \end{cases} + 8}{x+2}$$

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
<- 1st order linear successful`
```

✓ Solution by Maple

Time used: 0.265 (sec). Leaf size: 31

```
dsolve([(x+2)*diff(y(x),x)+y(x)=piecewise(0<=x and x<2,2*x,x>=2,4),y(0) = 4],y(x), singsol=a
```

$$y(x) = \frac{\begin{cases} 8 & x < 0 \\ x^2 + 8 & 0 \leq x < 2 \\ 4 + 4x & 2 \leq x \end{cases}}{x + 2}$$

✓ Solution by Mathematica

Time used: 0.074 (sec). Leaf size: 43

```
DSolve[{(x+2)*y'[x]+y[x]==Piecewise[{{2*x,0<=x<2},{4,x>=2}},{y[0]==4}],y[x],x,IncludeSingular
```

$$y(x) \rightarrow \begin{cases} \frac{8}{x+2} & x \leq 0 \\ \frac{4(x+1)}{x+2} & 0 < x < 2 \\ \frac{x^2+8}{x+2} & \text{True} \end{cases}$$

5.31 problem 31

5.31.1 Solving as linear ode	1182
5.31.2 Solving as first order ode lie symmetry lookup ode	1184
5.31.3 Solving as exact ode	1187
5.31.4 Maple step by step solution	1191

Internal problem ID [11668]

Internal file name [OUTPUT/11677_Wednesday_April_10_2024_04_54_28_PM_25898883/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.3 (Linear equations). Exercises page 56

Problem number: 31.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"linear"**, **"exactWithIntegrationFactor"**, **"first_order_ode_lie_symmetry_lookup"**

Maple gives the following as the ode type

```
[[_linear, `class A`]]
```

$$ay' + yb = k e^{-\lambda x}$$

5.31.1 Solving as linear ode

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = \frac{b}{a}$$
$$q(x) = \frac{k e^{-\lambda x}}{a}$$

Hence the ode is

$$y' + \frac{by}{a} = \frac{k e^{-\lambda x}}{a}$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int \frac{b}{a} dx} \\ &= e^{\frac{bx}{a}}\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu y) &= (\mu) \left(\frac{k e^{-\lambda x}}{a} \right) \\ \frac{d}{dx} \left(e^{\frac{bx}{a}} y \right) &= \left(e^{\frac{bx}{a}} \right) \left(\frac{k e^{-\lambda x}}{a} \right) \\ d \left(e^{\frac{bx}{a}} y \right) &= \left(\frac{k e^{-\frac{x(a\lambda-b)}{a}}}{a} \right) dx\end{aligned}$$

Integrating gives

$$\begin{aligned}e^{\frac{bx}{a}} y &= \int \frac{k e^{-\frac{x(a\lambda-b)}{a}}}{a} dx \\ e^{\frac{bx}{a}} y &= -\frac{k e^{-\frac{x(a\lambda-b)}{a}}}{a\lambda - b} + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = e^{\frac{bx}{a}}$ results in

$$y = -\frac{e^{-\frac{bx}{a}} k e^{-\frac{x(a\lambda-b)}{a}}}{a\lambda - b} + c_1 e^{-\frac{bx}{a}}$$

which simplifies to

$$y = \frac{c_1(a\lambda - b) e^{-\frac{bx}{a}} - k e^{-\lambda x}}{a\lambda - b}$$

Summary

The solution(s) found are the following

$$y = \frac{c_1(a\lambda - b) e^{-\frac{bx}{a}} - k e^{-\lambda x}}{a\lambda - b} \quad (1)$$

Verification of solutions

$$y = \frac{c_1(a\lambda - b) e^{-\frac{bx}{a}} - k e^{-\lambda x}}{a\lambda - b}$$

Verified OK.

5.31.2 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = -\frac{by - k e^{-\lambda x}}{a}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 194: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= e^{-\frac{bx}{a}}\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned}S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{e^{-\frac{bx}{a}}} dy\end{aligned}$$

Which results in

$$S = e^{\frac{bx}{a}} y$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y}\tag{2}$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{by - k e^{-\lambda x}}{a}$$

Evaluating all the partial derivatives gives

$$\begin{aligned}R_x &= 1 \\R_y &= 0 \\S_x &= \frac{b e^{\frac{bx}{a}} y}{a} \\S_y &= e^{\frac{bx}{a}}\end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = \frac{k e^{-\frac{x(a\lambda-b)}{a}}}{a} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = \frac{k e^{-\frac{R(a\lambda-b)}{a}}}{a}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = -\frac{k e^{-\frac{R(a\lambda-b)}{a}}}{a\lambda - b} + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$e^{\frac{bx}{a}} y = -\frac{k e^{-\frac{x(a\lambda-b)}{a}}}{a\lambda - b} + c_1$$

Which simplifies to

$$e^{\frac{bx}{a}} y = -\frac{k e^{-\frac{x(a\lambda-b)}{a}}}{a\lambda - b} + c_1$$

Which gives

$$y = -\frac{\left(-\lambda c_1 a + k e^{-\frac{x(a\lambda-b)}{a}} + c_1 b\right) e^{-\frac{bx}{a}}}{a\lambda - b}$$

Summary

The solution(s) found are the following

$$y = -\frac{\left(-\lambda c_1 a + k e^{-\frac{x(a\lambda-b)}{a}} + c_1 b\right) e^{-\frac{bx}{a}}}{a\lambda - b} \quad (1)$$

Verification of solutions

$$y = -\frac{\left(-\lambda c_1 a + k e^{-\frac{x(a\lambda-b)}{a}} + c_1 b\right) e^{-\frac{bx}{a}}}{a\lambda - b}$$

Verified OK.

5.31.3 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \quad (A)$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \quad (B)$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might

or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (1A)$$

Therefore

$$\begin{aligned} (a) dy &= (-by + k e^{-\lambda x}) dx \\ (by - k e^{-\lambda x}) dx + (a) dy &= 0 \end{aligned} \quad (2A)$$

Comparing (1A) and (2A) shows that

$$\begin{aligned} M(x, y) &= by - k e^{-\lambda x} \\ N(x, y) &= a \end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned} \frac{\partial M}{\partial y} &= \frac{\partial}{\partial y} (by - k e^{-\lambda x}) \\ &= b \end{aligned}$$

And

$$\begin{aligned} \frac{\partial N}{\partial x} &= \frac{\partial}{\partial x} (a) \\ &= 0 \end{aligned}$$

Since $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$\begin{aligned} A &= \frac{1}{N} \left(\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} \right) \\ &= \frac{1}{a} ((b) - (0)) \\ &= \frac{b}{a} \end{aligned}$$

Since A does not depend on y , then it can be used to find an integrating factor. The integrating factor μ is

$$\begin{aligned} \mu &= e^{\int A dx} \\ &= e^{\int \frac{b}{a} dx} \end{aligned}$$

The result of integrating gives

$$\begin{aligned}\mu &= e^{\frac{bx}{a}} \\ &= e^{\frac{bx}{a}}\end{aligned}$$

M and N are multiplied by this integrating factor, giving new M and new N which are called \overline{M} and \overline{N} for now so not to confuse them with the original M and N .

$$\begin{aligned}\overline{M} &= \mu M \\ &= e^{\frac{bx}{a}} (by - k e^{-\lambda x}) \\ &= e^{\frac{bx}{a}} (by - k e^{-\lambda x})\end{aligned}$$

And

$$\begin{aligned}\overline{N} &= \mu N \\ &= e^{\frac{bx}{a}} (a) \\ &= e^{\frac{bx}{a}} a\end{aligned}$$

Now a modified ODE is obtained from the original ODE, which is exact and can be solved. The modified ODE is

$$\begin{aligned}\overline{M} + \overline{N} \frac{dy}{dx} &= 0 \\ \left(e^{\frac{bx}{a}} (by - k e^{-\lambda x}) \right) + \left(e^{\frac{bx}{a}} a \right) \frac{dy}{dx} &= 0\end{aligned}$$

The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = \overline{M} \tag{1}$$

$$\frac{\partial \phi}{\partial y} = \overline{N} \tag{2}$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int \overline{M} dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int e^{\frac{bx}{a}} (by - k e^{-\lambda x}) dx \\ \phi &= \frac{\left(k e^{-\frac{x(a\lambda - b)}{a}} + y(a\lambda - b) e^{\frac{bx}{a}} \right) a}{a\lambda - b} + f(y)\end{aligned} \tag{3}$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = e^{\frac{bx}{a}} a + f'(y) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = e^{\frac{bx}{a}} a$. Therefore equation (4) becomes

$$e^{\frac{bx}{a}} a = e^{\frac{bx}{a}} a + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 0$$

Therefore

$$f(y) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(y)$ into equation (3) gives ϕ

$$\phi = \frac{\left(k e^{-\frac{x(a\lambda-b)}{a}} + y(a\lambda - b) e^{\frac{bx}{a}} \right) a}{a\lambda - b} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = \frac{\left(k e^{-\frac{x(a\lambda-b)}{a}} + y(a\lambda - b) e^{\frac{bx}{a}} \right) a}{a\lambda - b}$$

The solution becomes

$$y = -\frac{\left(k e^{-\frac{x(a\lambda-b)}{a}} a - \lambda c_1 a + c_1 b \right) e^{-\frac{bx}{a}}}{a(a\lambda - b)}$$

Summary

The solution(s) found are the following

$$y = -\frac{\left(k e^{-\frac{x(a\lambda-b)}{a}} a - \lambda c_1 a + c_1 b \right) e^{-\frac{bx}{a}}}{a(a\lambda - b)} \quad (1)$$

Verification of solutions

$$y = -\frac{\left(k e^{-\frac{x(a\lambda-b)}{a}} a - \lambda c_1 a + c_1 b\right) e^{-\frac{bx}{a}}}{a(a\lambda - b)}$$

Verified OK.

5.31.4 Maple step by step solution

Let's solve

$$ay' + by = k e^{-\lambda x}$$

- Highest derivative means the order of the ODE is 1

$$y'$$

- Isolate the derivative

$$y' = -\frac{by}{a} + \frac{k e^{-\lambda x}}{a}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE

$$y' + \frac{by}{a} = \frac{k e^{-\lambda x}}{a}$$

- The ODE is linear; multiply by an integrating factor $\mu(x)$

$$\mu(x) \left(y' + \frac{by}{a}\right) = \frac{\mu(x)k e^{-\lambda x}}{a}$$

- Assume the lhs of the ODE is the total derivative $\frac{d}{dx}(\mu(x)y)$

$$\mu(x) \left(y' + \frac{by}{a}\right) = \mu'(x)y + \mu(x)y'$$

- Isolate $\mu'(x)$

$$\mu'(x) = \frac{\mu(x)b}{a}$$

- Solve to find the integrating factor

$$\mu(x) = e^{\frac{bx}{a}}$$

- Integrate both sides with respect to x

$$\int \left(\frac{d}{dx}(\mu(x)y)\right) dx = \int \frac{\mu(x)k e^{-\lambda x}}{a} dx + c_1$$

- Evaluate the integral on the lhs

$$\mu(x)y = \int \frac{\mu(x)k e^{-\lambda x}}{a} dx + c_1$$

- Solve for y

$$y = \frac{\int \frac{\mu(x)k e^{-\lambda x}}{a} dx + c_1}{\mu(x)}$$

- Substitute $\mu(x) = e^{\frac{bx}{a}}$

$$y = \frac{\int \frac{k e^{-\lambda x} e^{\frac{bx}{a}}}{e^{\frac{bx}{a}}} dx + c_1}{e^{\frac{bx}{a}}}$$

- Evaluate the integrals on the rhs

$$y = \frac{-\frac{k e^{-\lambda x} e^{\frac{bx}{a}}}{a\lambda - b} + c_1}{e^{\frac{bx}{a}}}$$

- Simplify

$$y = \frac{e^{-\frac{bx}{a}} \left(-k e^{-\frac{x(a\lambda - b)}{a}} + (a\lambda - b)c_1 \right)}{a\lambda - b}$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
<- 1st order linear successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 49

```
dsolve(a*diff(y(x),x)+b*y(x)=k*exp(-lambda*x),y(x), singsol=all)
```

$$y(x) = \frac{\left(-k e^{-\frac{x(a\lambda - b)}{a}} + c_1(a\lambda - b) \right) e^{-\frac{bx}{a}}}{a\lambda - b}$$

✓ Solution by Mathematica

Time used: 0.087 (sec). Leaf size: 44

```
DSolve[a*y'[x]+b*y[x]==k*Exp[\[Lambda]*x],y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{e^{-\frac{bx}{a}} \left(k e^{x\left(\frac{b}{a} + \lambda\right)} + c_1(a\lambda + b) \right)}{a\lambda + b}$$

5.32 problem 35 (b)

5.32.1 Solving as linear ode	1193
5.32.2 Solving as first order ode lie symmetry lookup ode	1195
5.32.3 Solving as exact ode	1199
5.32.4 Maple step by step solution	1203

Internal problem ID [11669]

Internal file name [OUTPUT/11678_Wednesday_April_10_2024_04_54_29_PM_13645783/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.3 (Linear equations). Exercises page 56

Problem number: 35 (b).

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"linear", "exactWithIntegrationFactor", "first_order_ode_lie_symmetry_lookup"**

Maple gives the following as the ode type

```
[[_linear, `class A`]]
```

$$y' + y = 2 \sin(x) + 5 \sin(2x)$$

5.32.1 Solving as linear ode

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = 1$$

$$q(x) = 2 \sin(x) + 5 \sin(2x)$$

Hence the ode is

$$y' + y = 2 \sin(x) + 5 \sin(2x)$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int 1 dx} \\ &= e^x\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu y) &= (\mu) (2 \sin(x) + 5 \sin(2x)) \\ \frac{d}{dx}(e^x y) &= (e^x) (2 \sin(x) + 5 \sin(2x)) \\ d(e^x y) &= ((2 \sin(x) + 5 \sin(2x)) e^x) dx\end{aligned}$$

Integrating gives

$$\begin{aligned}e^x y &= \int (2 \sin(x) + 5 \sin(2x)) e^x dx \\ e^x y &= e^x (\sin(2x) - 2 \cos(2x)) - e^x \cos(x) + e^x \sin(x) + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = e^x$ results in

$$y = e^{-x} (e^x (\sin(2x) - 2 \cos(2x)) - e^x \cos(x) + e^x \sin(x)) + c_1 e^{-x}$$

which simplifies to

$$y = c_1 e^{-x} - 4 \cos(x)^2 + (2 \sin(x) - 1) \cos(x) + \sin(x) + 2$$

Summary

The solution(s) found are the following

$$y = c_1 e^{-x} - 4 \cos(x)^2 + (2 \sin(x) - 1) \cos(x) + \sin(x) + 2 \quad (1)$$

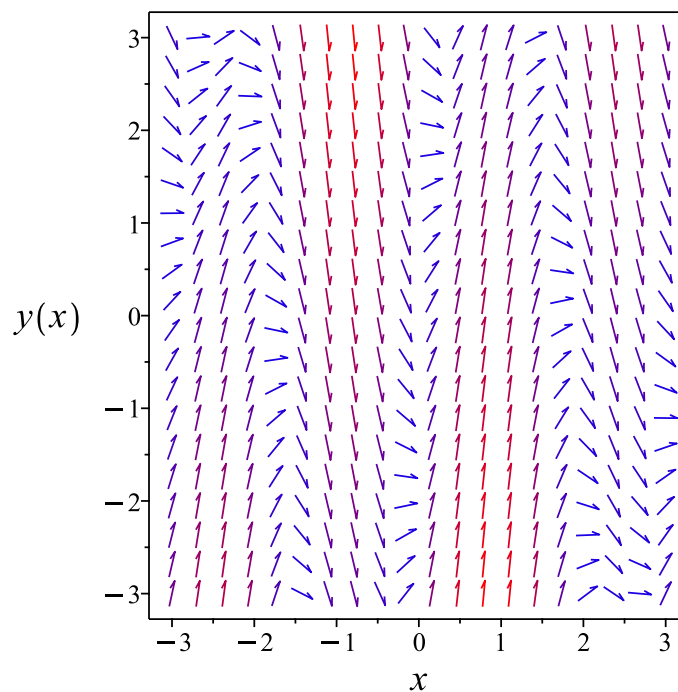


Figure 231: Slope field plot

Verification of solutions

$$y = c_1 e^{-x} - 4 \cos(x)^2 + (2 \sin(x) - 1) \cos(x) + \sin(x) + 2$$

Verified OK.

5.32.2 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = -y + 2 \sin(x) + 5 \sin(2x)$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 197: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= e^{-x}\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{e^{-x}} dy \end{aligned}$$

Which results in

$$S = e^x y$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -y + 2 \sin(x) + 5 \sin(2x)$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= e^x y \\ S_y &= e^x \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = (2 \sin(x) + 5 \sin(2x)) e^x \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = (2 \sin(R) + 5 \sin(2R)) e^R$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by

integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = c_1 - e^R(\cos(R) + 2 \cos(2R) - \sin(R) - \sin(2R)) \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$y e^x = c_1 - e^x(-\sin(2x) + 2 \cos(2x) + \cos(x) - \sin(x))$$

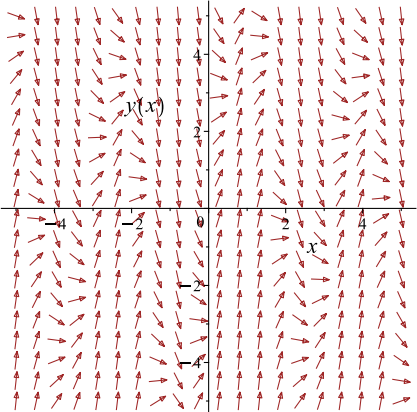
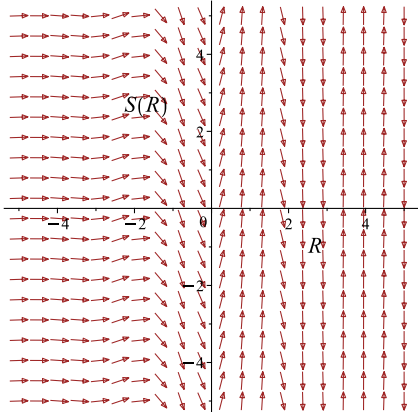
Which simplifies to

$$y e^x = c_1 - e^x(-\sin(2x) + 2 \cos(2x) + \cos(x) - \sin(x))$$

Which gives

$$y = e^{-x}(e^x \sin(2x) + e^x \sin(x) - e^x \cos(x) - 2 e^x \cos(2x) + c_1)$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -y + 2 \sin(x) + 5 \sin(2x)$ 	$R = x$ $S = e^x y$	$\frac{dS}{dR} = (2 \sin(R) + 5 \sin(2R)) e^R$ 

Summary

The solution(s) found are the following

$$y = e^{-x}(e^x \sin(2x) + e^x \sin(x) - e^x \cos(x) - 2 e^x \cos(2x) + c_1) \quad (1)$$

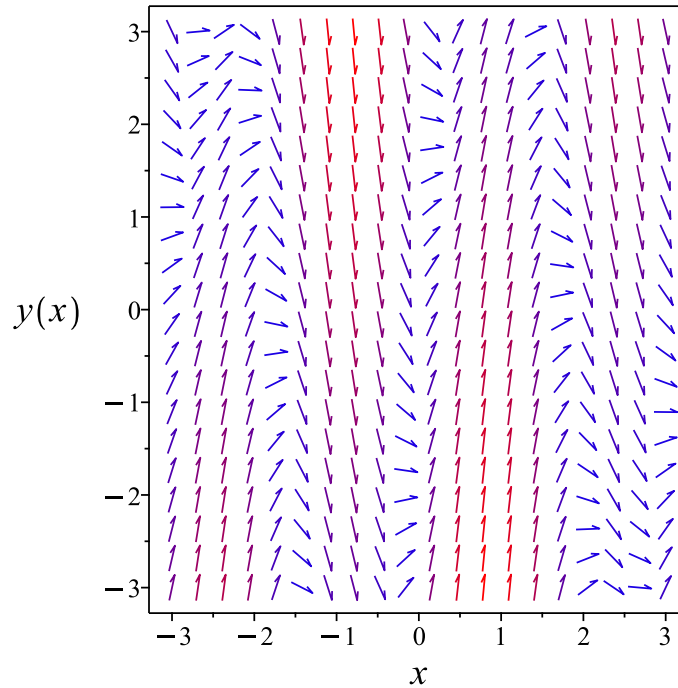


Figure 232: Slope field plot

Verification of solutions

$$y = e^{-x}(e^x \sin(2x) + e^x \sin(x) - e^x \cos(x) - 2e^x \cos(2x) + c_1)$$

Verified OK.

5.32.3 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \quad (\text{A})$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \quad (\text{B})$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial\phi}{\partial x} &= M \\ \frac{\partial\phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \tag{1A}$$

Therefore

$$\begin{aligned}dy &= (-y + 2 \sin(x) + 5 \sin(2x)) dx \\ (y - 2 \sin(x) - 5 \sin(2x)) dx + dy &= 0\end{aligned} \tag{2A}$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= y - 2 \sin(x) - 5 \sin(2x) \\ N(x, y) &= 1\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(y - 2 \sin(x) - 5 \sin(2x)) \\ &= 1\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(1) \\ &= 0\end{aligned}$$

Since $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$\begin{aligned} A &= \frac{1}{N} \left(\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} \right) \\ &= 1((1) - (0)) \\ &= 1 \end{aligned}$$

Since A does not depend on y , then it can be used to find an integrating factor. The integrating factor μ is

$$\begin{aligned} \mu &= e^{\int A dx} \\ &= e^{\int 1 dx} \end{aligned}$$

The result of integrating gives

$$\begin{aligned} \mu &= e^x \\ &= e^x \end{aligned}$$

M and N are multiplied by this integrating factor, giving new M and new N which are called \bar{M} and \bar{N} for now so not to confuse them with the original M and N .

$$\begin{aligned} \bar{M} &= \mu M \\ &= e^x(y - 2 \sin(x) - 5 \sin(2x)) \\ &= (y - 2 \sin(x) - 5 \sin(2x)) e^x \end{aligned}$$

And

$$\begin{aligned} \bar{N} &= \mu N \\ &= e^x(1) \\ &= e^x \end{aligned}$$

Now a modified ODE is obtained from the original ODE, which is exact and can be solved. The modified ODE is

$$\begin{aligned} \bar{M} + \bar{N} \frac{dy}{dx} &= 0 \\ ((y - 2 \sin(x) - 5 \sin(2x)) e^x) + (e^x) \frac{dy}{dx} &= 0 \end{aligned}$$

The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = \bar{M} \tag{1}$$

$$\frac{\partial \phi}{\partial y} = \bar{N} \tag{2}$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int \bar{M} dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int (y - 2 \sin(x) - 5 \sin(2x)) e^x dx \\ \phi &= e^x(-\sin(2x) + 2 \cos(2x) + \cos(x) - \sin(x) + y) + f(y)\end{aligned}\quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = e^x + f'(y)\quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = e^x$. Therefore equation (4) becomes

$$e^x = e^x + f'(y)\quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 0$$

Therefore

$$f(y) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(y)$ into equation (3) gives ϕ

$$\phi = e^x(-\sin(2x) + 2 \cos(2x) + \cos(x) - \sin(x) + y) + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = e^x(-\sin(2x) + 2 \cos(2x) + \cos(x) - \sin(x) + y)$$

The solution becomes

$$y = e^{-x}(e^x \sin(2x) + e^x \sin(x) - e^x \cos(x) - 2e^x \cos(2x) + c_1)$$

Summary

The solution(s) found are the following

$$y = e^{-x}(e^x \sin(2x) + e^x \sin(x) - e^x \cos(x) - 2e^x \cos(2x) + c_1) \quad (1)$$

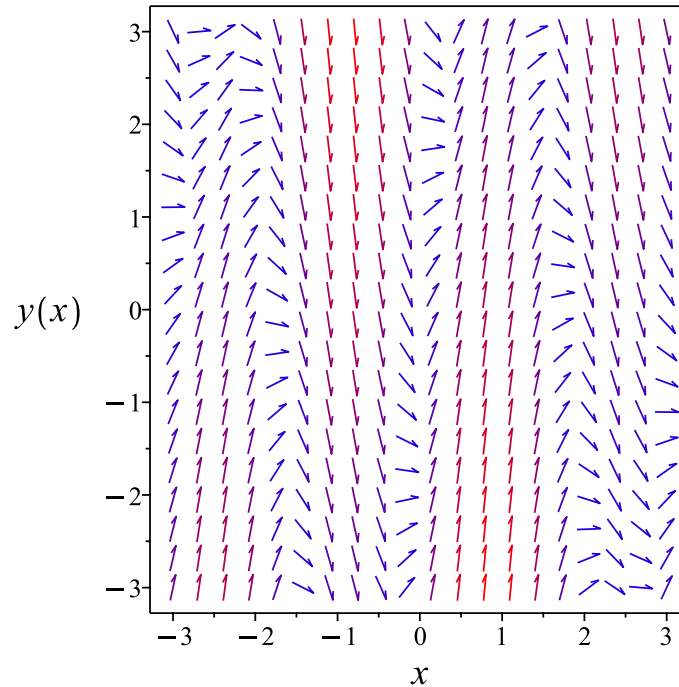


Figure 233: Slope field plot

Verification of solutions

$$y = e^{-x}(e^x \sin(2x) + e^x \sin(x) - e^x \cos(x) - 2e^x \cos(2x) + c_1)$$

Verified OK.

5.32.4 Maple step by step solution

Let's solve

$$y' + y = 2 \sin(x) + 5 \sin(2x)$$

- Highest derivative means the order of the ODE is 1

$$y'$$

- Isolate the derivative

$$y' = -y + 2 \sin(x) + 5 \sin(2x)$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE

$$y' + y = 2 \sin(x) + 5 \sin(2x)$$

- The ODE is linear; multiply by an integrating factor $\mu(x)$

$$\mu(x) (y' + y) = \mu(x) (2 \sin(x) + 5 \sin(2x))$$

- Assume the lhs of the ODE is the total derivative $\frac{d}{dx}(\mu(x) y)$

$$\mu(x) (y' + y) = \mu'(x) y + \mu(x) y'$$

- Isolate $\mu'(x)$

$$\mu'(x) = \mu(x)$$

- Solve to find the integrating factor

$$\mu(x) = e^x$$

- Integrate both sides with respect to x

$$\int \left(\frac{d}{dx}(\mu(x) y) \right) dx = \int \mu(x) (2 \sin(x) + 5 \sin(2x)) dx + c_1$$

- Evaluate the integral on the lhs

$$\mu(x) y = \int \mu(x) (2 \sin(x) + 5 \sin(2x)) dx + c_1$$

- Solve for y

$$y = \frac{\int \mu(x)(2 \sin(x) + 5 \sin(2x)) dx + c_1}{\mu(x)}$$

- Substitute $\mu(x) = e^x$

$$y = \frac{\int (2 \sin(x) + 5 \sin(2x)) e^x dx + c_1}{e^x}$$

- Evaluate the integrals on the rhs

$$y = \frac{e^x (\sin(2x) - 2 \cos(2x)) - e^x \cos(x) + e^x \sin(x) + c_1}{e^x}$$

- Simplify

$$y = c_1 e^{-x} - 4 \cos(x)^2 + (2 \sin(x) - 1) \cos(x) + \sin(x) + 2$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
<- 1st order linear successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 27

```
dsolve(diff(y(x),x)+y(x)=2*sin(x)+5*sin(2*x),y(x), singsol=all)
```

$$y(x) = -\cos(x) - 2\cos(2x) + \sin(x) + \sin(2x) + c_1e^{-x}$$

✓ Solution by Mathematica

Time used: 0.131 (sec). Leaf size: 30

```
DSolve[y'[x]+y[x]==2*Sin[x]+5*Sin[2*x],y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \sin(x) + \sin(2x) - \cos(x) - 2\cos(2x) + c_1e^{-x}$$

5.33 problem 37 (a)

5.33.1 Solving as exact ode 1206

Internal problem ID [11670]

Internal file name [OUTPUT/11679_Wednesday_April_10_2024_04_54_30_PM_22507291/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.3 (Linear equations). Exercises page 56

Problem number: 37 (a).

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"exact"**

Maple gives the following as the ode type

[`y=_G(x,y')`]

$$\cos(y)y' + \frac{\sin(y)}{x} = 1$$

5.33.1 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (1A)$$

Therefore

$$\begin{aligned} (x \cos(y)) dy &= (-\sin(y) + x) dx \\ (\sin(y) - x) dx + (x \cos(y)) dy &= 0 \end{aligned} \quad (2A)$$

Comparing (1A) and (2A) shows that

$$\begin{aligned} M(x, y) &= \sin(y) - x \\ N(x, y) &= x \cos(y) \end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned} \frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(\sin(y) - x) \\ &= \cos(y) \end{aligned}$$

And

$$\begin{aligned} \frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(x \cos(y)) \\ &= \cos(y) \end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \quad (1)$$

$$\frac{\partial \phi}{\partial y} = N \quad (2)$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int M dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int \sin(y) - x dx \\ \phi &= -\frac{x(-2 \sin(y) + x)}{2} + f(y)\end{aligned}\quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = x \cos(y) + f'(y) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = x \cos(y)$. Therefore equation (4) becomes

$$x \cos(y) = x \cos(y) + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 0$$

Therefore

$$f(y) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(y)$ into equation (3) gives ϕ

$$\phi = -\frac{x(-2 \sin(y) + x)}{2} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -\frac{x(-2 \sin(y) + x)}{2}$$

Summary

The solution(s) found are the following

$$-\frac{x(-2 \sin(y) + x)}{2} = c_1 \quad (1)$$

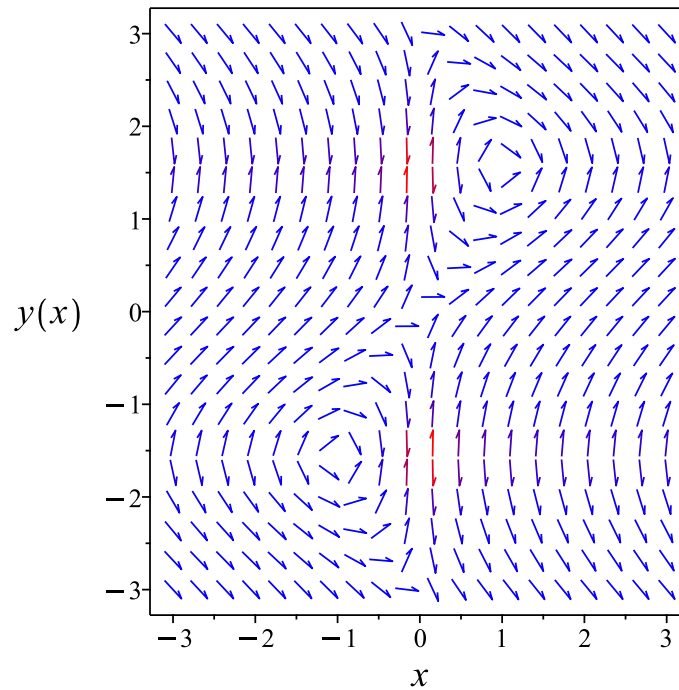


Figure 234: Slope field plot

Verification of solutions

$$-\frac{x(-2 \sin(y) + x)}{2} = c_1$$

Verified OK.

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
trying separable
trying inverse linear
trying homogeneous types:
trying Chini
differential order: 1; looking for linear symmetries
trying exact
<- exact successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 21

```
dsolve(cos(y(x))*diff(y(x),x)+1/x*sin(y(x))=1,y(x), singsol=all)
```

$$y(x) = -\arcsin\left(\frac{-x^2 + 2c_1}{2x}\right)$$

✓ Solution by Mathematica

Time used: 8.67 (sec). Leaf size: 18

```
DSolve[Cos[y[x]]*y'[x]+1/x*Sin[y[x]]==1,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \arcsin\left(\frac{x}{2} + \frac{c_1}{x}\right)$$

5.34 problem 37 (b)

5.34.1 Solving as separable ode	1211
5.34.2 Solving as first order ode lie symmetry lookup ode	1213
5.34.3 Solving as exact ode	1217
5.34.4 Maple step by step solution	1221

Internal problem ID [11671]

Internal file name [OUTPUT/11680_Wednesday_April_10_2024_04_54_32_PM_51224347/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.3 (Linear equations). Exercises page 56

Problem number: 37 (b).

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"exact", "separable", "first_order_ode_lie_symmetry_lookup"**

Maple gives the following as the ode type

`[_separable]`

$$(y + 1)y' + x(y^2 + 2y) = x$$

5.34.1 Solving as separable ode

In canonical form the ODE is

$$\begin{aligned}y' &= F(x, y) \\ &= f(x)g(y) \\ &= -\frac{x(y^2 + 2y - 1)}{y + 1}\end{aligned}$$

Where $f(x) = -x$ and $g(y) = \frac{y^2+2y-1}{y+1}$. Integrating both sides gives

$$\begin{aligned}\frac{1}{\frac{y^2+2y-1}{y+1}} dy &= -x dx \\ \int \frac{1}{\frac{y^2+2y-1}{y+1}} dy &= \int -x dx\end{aligned}$$

$$\frac{\ln(y^2 + 2y - 1)}{2} = -\frac{x^2}{2} + c_1$$

Raising both side to exponential gives

$$\sqrt{y^2 + 2y - 1} = e^{-\frac{x^2}{2} + c_1}$$

Which simplifies to

$$\sqrt{y^2 + 2y - 1} = c_2 e^{-\frac{x^2}{2}}$$

The solution is

$$\sqrt{y^2 + 2y - 1} = c_2 e^{-\frac{x^2}{2} + c_1}$$

Summary

The solution(s) found are the following

$$\sqrt{y^2 + 2y - 1} = c_2 e^{-\frac{x^2}{2} + c_1} \quad (1)$$

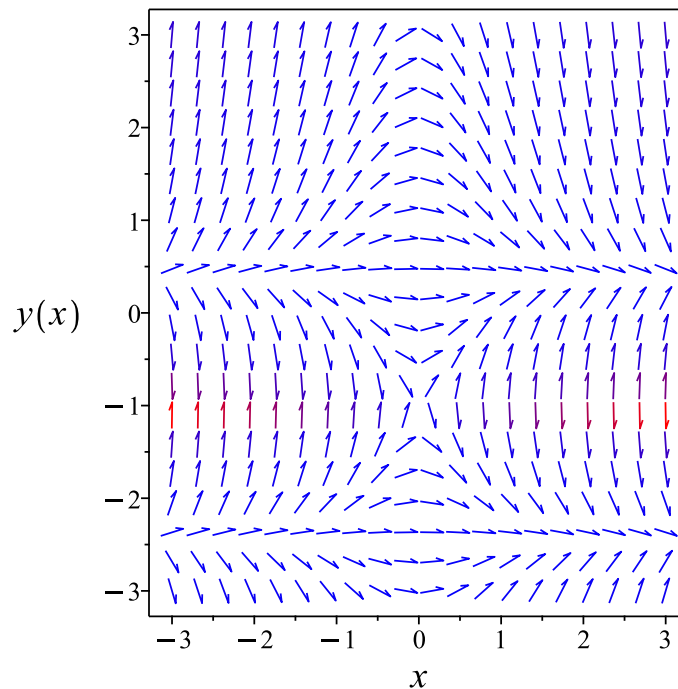


Figure 235: Slope field plot

Verification of solutions

$$\sqrt{y^2 + 2y - 1} = c_2 e^{-\frac{x^2}{2} + c_1}$$

Verified OK.

5.34.2 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = -\frac{x(y^2 + 2y - 1)}{y + 1}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **separable**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 200: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= -\frac{1}{x} \\ \eta(x, y) &= 0\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\eta = 0$ then in this special case

$$R = y$$

S is found from

$$\begin{aligned}S &= \int \frac{1}{\xi} dx \\ &= \int \frac{1}{-\frac{1}{x}} dx\end{aligned}$$

Which results in

$$S = -\frac{x^2}{2}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y}\tag{2}$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{x(y^2 + 2y - 1)}{y + 1}$$

Evaluating all the partial derivatives gives

$$\begin{aligned}R_x &= 0 \\R_y &= 1 \\S_x &= -x \\S_y &= 0\end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = \frac{y + 1}{y^2 + 2y - 1} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = \frac{R + 1}{R^2 + 2R - 1}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = \frac{\ln(R^2 + 2R - 1)}{2} + c_1 \quad (4)$$

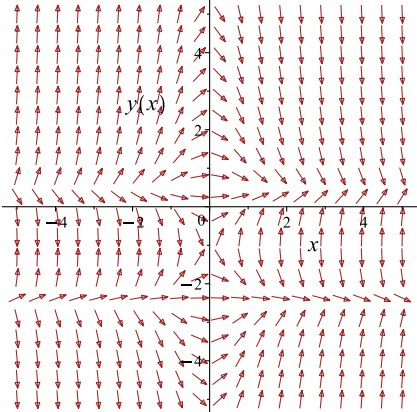
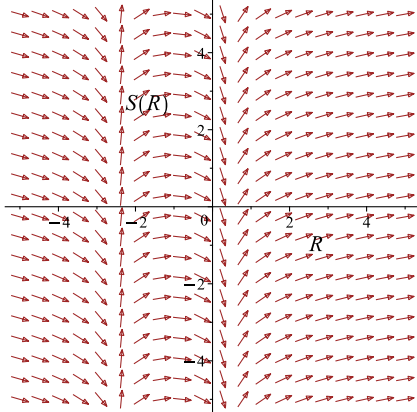
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$-\frac{x^2}{2} = \frac{\ln(y^2 + 2y - 1)}{2} + c_1$$

Which simplifies to

$$-\frac{x^2}{2} = \frac{\ln(y^2 + 2y - 1)}{2} + c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{x(y^2+2y-1)}{y+1}$ 	$R = y$ $S = -\frac{x^2}{2}$	$\frac{dS}{dR} = \frac{R+1}{R^2+2R-1}$ 

Summary

The solution(s) found are the following

$$-\frac{x^2}{2} = \frac{\ln(y^2 + 2y - 1)}{2} + c_1 \tag{1}$$

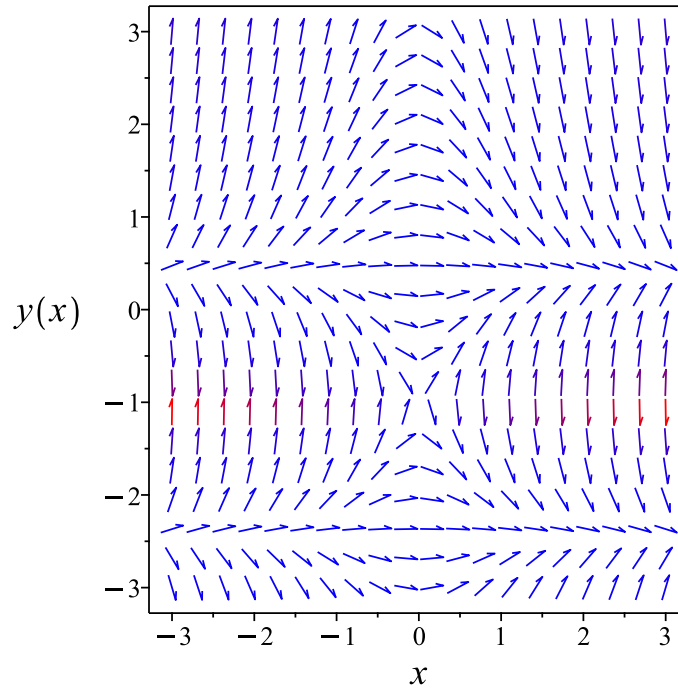


Figure 236: Slope field plot

Verification of solutions

$$-\frac{x^2}{2} = \frac{\ln(y^2 + 2y - 1)}{2} + c_1$$

Verified OK.

5.34.3 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx}\phi(x, y) = 0$$

Hence

$$\frac{\partial\phi}{\partial x} + \frac{\partial\phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial\phi}{\partial x} &= M \\ \frac{\partial\phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \tag{1A}$$

Therefore

$$\begin{aligned}\left(-\frac{y+1}{y^2+2y-1}\right) dy &= (x) dx \\ (-x) dx + \left(-\frac{y+1}{y^2+2y-1}\right) dy &= 0\end{aligned} \tag{2A}$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= -x \\ N(x, y) &= -\frac{y+1}{y^2+2y-1}\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(-x) \\ &= 0\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x} \left(-\frac{y+1}{y^2+2y-1} \right) \\ &= 0\end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \tag{1}$$

$$\frac{\partial \phi}{\partial y} = N \tag{2}$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int M dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int -x dx \\ \phi &= -\frac{x^2}{2} + f(y)\end{aligned} \tag{3}$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = 0 + f'(y) \tag{4}$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = -\frac{y+1}{y^2+2y-1}$. Therefore equation (4) becomes

$$-\frac{y+1}{y^2+2y-1} = 0 + f'(y) \tag{5}$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = -\frac{y+1}{y^2+2y-1}$$

Integrating the above w.r.t y gives

$$\int f'(y) dy = \int \left(\frac{-y-1}{y^2+2y-1} \right) dy$$
$$f(y) = -\frac{\ln(y^2+2y-1)}{2} + c_1$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = -\frac{x^2}{2} - \frac{\ln(y^2+2y-1)}{2} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -\frac{x^2}{2} - \frac{\ln(y^2+2y-1)}{2}$$

Summary

The solution(s) found are the following

$$-\frac{x^2}{2} - \frac{\ln(y^2+2y-1)}{2} = c_1 \tag{1}$$

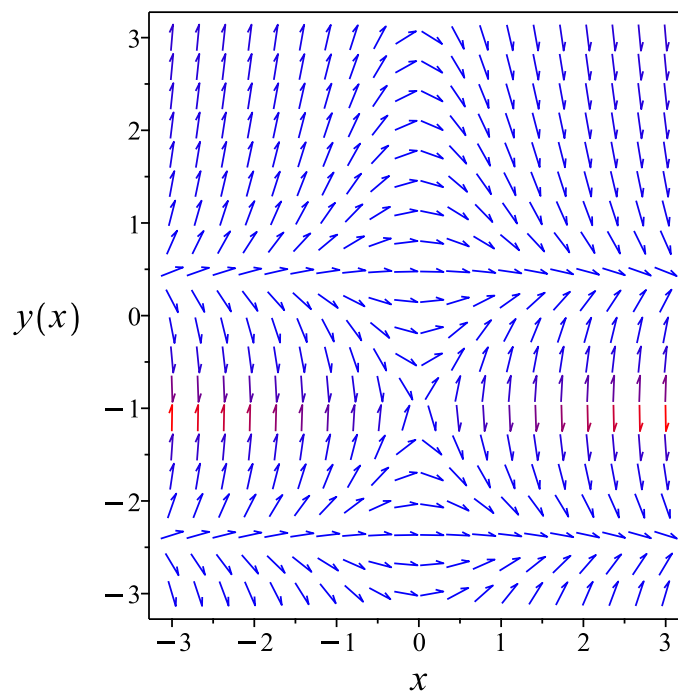


Figure 237: Slope field plot

Verification of solutions

$$-\frac{x^2}{2} - \frac{\ln(y^2 + 2y - 1)}{2} = c_1$$

Verified OK.

5.34.4 Maple step by step solution

Let's solve

$$(y + 1)y' + x(y^2 + 2y) = x$$

- Highest derivative means the order of the ODE is 1

y'

- Separate variables

$$\frac{y'(y+1)}{y^2+2y-1} = -x$$

- Integrate both sides with respect to x

$$\int \frac{y'(y+1)}{y^2+2y-1} dx = \int -x dx + c_1$$

- Evaluate integral

$$\frac{\ln(y^2+2y-1)}{2} = -\frac{x^2}{2} + c_1$$

- Solve for y

$$\left\{ y = -1 - \sqrt{2 + e^{-x^2+2c_1}}, y = -1 + \sqrt{2 + e^{-x^2+2c_1}} \right\}$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
trying separable
<- separable successful`

```

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 37

```
dsolve((y(x)+1)*diff(y(x),x)+x*(y(x)^2+2*y(x))=x,y(x), singsol=all)
```

$$y(x) = -1 - \sqrt{2 + e^{-x^2} c_1}$$

$$y(x) = -1 + \sqrt{2 + e^{-x^2} c_1}$$

✓ Solution by Mathematica

Time used: 29.843 (sec). Leaf size: 163

```
DSolve[(y[x]+1)*y'[x]+x*(y[x]^2+2*y[x])=x,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow -1 - e^{-x^2} \sqrt{e^{x^2} (2e^{x^2} + e^{2c_1})}$$

$$y(x) \rightarrow -1 + e^{-x^2} \sqrt{e^{x^2} (2e^{x^2} + e^{2c_1})}$$

$$y(x) \rightarrow -1 - \sqrt{2}$$

$$y(x) \rightarrow \sqrt{2} - 1$$

$$y(x) \rightarrow \sqrt{2} e^{-x^2} \sqrt{e^{2x^2}} - 1$$

$$y(x) \rightarrow -\sqrt{2} e^{-x^2} \sqrt{e^{2x^2}} - 1$$

5.35 problem 39

5.35.1 Solving as first order ode lie symmetry calculated ode 1223

5.35.2 Solving as riccati ode 1230

Internal problem ID [11672]

Internal file name [OUTPUT/11681_Wednesday_April_10_2024_04_54_33_PM_13637091/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.3 (Linear equations). Exercises page 56

Problem number: 39.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**riccati**", "**first_order_ode_lie_symmetry_calculated**"

Maple gives the following as the ode type

[_Riccati]

$$y' - (1 - x)y^2 - (2x - 1)y = -x$$

5.35.1 Solving as first order ode lie symmetry calculated ode

Writing the ode as

$$y' = -xy^2 + 2xy + y^2 - x - y$$
$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \tag{A}$$

The type of this ode is not in the lookup table. To determine ξ, η then (A) is solved using ansatz. Making bivariate polynomials of degree 2 to use as anstaz gives

$$\xi = x^2 a_4 + xy a_5 + y^2 a_6 + xa_2 + ya_3 + a_1 \tag{1E}$$

$$\eta = x^2 b_4 + xy b_5 + y^2 b_6 + xb_2 + yb_3 + b_1 \tag{2E}$$

Where the unknown coefficients are

$$\{a_1, a_2, a_3, a_4, a_5, a_6, b_1, b_2, b_3, b_4, b_5, b_6\}$$

Substituting equations (1E,2E) and ω into (A) gives

$$\begin{aligned} & 2xb_4 + yb_5 + b_2 \\ & + (-xy^2 + 2xy + y^2 - x - y)(-2xa_4 + xb_5 - ya_5 + 2yb_6 - a_2 + b_3) \\ & - (-xy^2 + 2xy + y^2 - x - y)^2(xa_5 + 2ya_6 + a_3) \\ & - (-y^2 + 2y - 1)(x^2a_4 + xya_5 + y^2a_6 + xa_2 + ya_3 + a_1) \\ & - (-2xy + 2x + 2y - 1)(x^2b_4 + xyb_5 + y^2b_6 + xb_2 + yb_3 + b_1) = 0 \end{aligned} \quad (5E)$$

Putting the above in normal form gives

$$\begin{aligned} & -x^3y^4a_5 - 2x^2y^5a_6 + 4x^3y^3a_5 - x^2y^4a_3 + 2x^2y^4a_5 + 8x^2y^4a_6 + 4xy^5a_6 \\ & - 6x^3y^2a_5 + 4x^2y^3a_3 - 6x^2y^3a_5 - 12x^2y^3a_6 + 2xy^4a_3 - xy^4a_5 \\ & - 12xy^4a_6 - 2y^5a_6 + 4x^3ya_5 + 2x^3yb_4 - 6x^2y^2a_3 + 3x^2y^2a_4 + 6x^2y^2a_5 \\ & + 8x^2y^2a_6 + x^2y^2b_5 - 6xy^3a_3 + 4xy^3a_5 + 12xy^3a_6 - y^4a_3 + 5y^4a_6 \\ & - x^3a_5 - 2x^3b_4 + 4x^2ya_3 - 6x^2ya_4 - 2x^2ya_5 - 2x^2ya_6 + 2x^2yb_2 - 2x^2yb_4 \\ & + 2xy^2a_2 + 6xy^2a_3 - 2xy^2a_4 - 5xy^2a_5 - 4xy^2a_6 + xy^2b_3 - xy^2b_5 \\ & + 2xy^2b_6 + 3y^3a_3 - y^3a_5 - 4y^3a_6 - x^2a_3 + 3x^2a_4 - 2x^2b_2 + x^2b_4 - x^2b_5 \\ & - 4xya_2 - 2xya_3 + 2xya_4 + 2xya_5 + 2xyb_1 - 2xyb_2 - 2xyb_6 + y^2a_1 \\ & - y^2a_2 - 3y^2a_3 + y^2a_5 + y^2a_6 - y^2b_3 - y^2b_6 + 2xa_2 - 2xb_1 + xb_2 \\ & - xb_3 + 2xb_4 - 2ya_1 + ya_2 + ya_3 - 2yb_1 + yb_5 + a_1 + b_1 + b_2 = 0 \end{aligned}$$

Setting the numerator to zero gives

$$\begin{aligned} & -x^3y^4a_5 - 2x^2y^5a_6 + 4x^3y^3a_5 - x^2y^4a_3 + 2x^2y^4a_5 + 8x^2y^4a_6 \\ & + 4xy^5a_6 - 6x^3y^2a_5 + 4x^2y^3a_3 - 6x^2y^3a_5 - 12x^2y^3a_6 + 2xy^4a_3 \\ & - xy^4a_5 - 12xy^4a_6 - 2y^5a_6 + 4x^3ya_5 + 2x^3yb_4 - 6x^2y^2a_3 \\ & + 3x^2y^2a_4 + 6x^2y^2a_5 + 8x^2y^2a_6 + x^2y^2b_5 - 6xy^3a_3 + 4xy^3a_5 \\ & + 12xy^3a_6 - y^4a_3 + 5y^4a_6 - x^3a_5 - 2x^3b_4 + 4x^2ya_3 - 6x^2ya_4 \\ & - 2x^2ya_5 - 2x^2ya_6 + 2x^2yb_2 - 2x^2yb_4 + 2xy^2a_2 + 6xy^2a_3 \\ & - 2xy^2a_4 - 5xy^2a_5 - 4xy^2a_6 + xy^2b_3 - xy^2b_5 + 2xy^2b_6 + 3y^3a_3 \\ & - y^3a_5 - 4y^3a_6 - x^2a_3 + 3x^2a_4 - 2x^2b_2 + x^2b_4 - x^2b_5 - 4xya_2 \\ & - 2xya_3 + 2xya_4 + 2xya_5 + 2xyb_1 - 2xyb_2 - 2xyb_6 + y^2a_1 - y^2a_2 \\ & - 3y^2a_3 + y^2a_5 + y^2a_6 - y^2b_3 - y^2b_6 + 2xa_2 - 2xb_1 + xb_2 - xb_3 \\ & + 2xb_4 - 2ya_1 + ya_2 + ya_3 - 2yb_1 + yb_5 + a_1 + b_1 + b_2 = 0 \end{aligned} \quad (6E)$$

Looking at the above PDE shows the following are all the terms with $\{x, y\}$ in them.

$$\{x, y\}$$

The following substitution is now made to be able to collect on all terms with $\{x, y\}$ in them

$$\{x = v_1, y = v_2\}$$

The above PDE (6E) now becomes

$$\begin{aligned}
& -a_5v_1^3v_2^4 - 2a_6v_1^2v_2^5 - a_3v_1^2v_2^4 + 4a_5v_1^3v_2^3 + 2a_5v_1^2v_2^4 + 8a_6v_1^2v_2^4 \\
& + 4a_6v_1v_2^5 + 4a_3v_1^2v_2^3 + 2a_3v_1v_2^4 - 6a_5v_1^3v_2^2 - 6a_5v_1^2v_2^3 - a_5v_1v_2^4 \\
& - 12a_6v_1^2v_2^3 - 12a_6v_1v_2^4 - 2a_6v_2^5 - 6a_3v_1^2v_2^2 - 6a_3v_1v_2^3 - a_3v_2^4 \\
& + 3a_4v_1^2v_2^2 + 4a_5v_1^3v_2 + 6a_5v_1^2v_2^2 + 4a_5v_1v_2^3 + 8a_6v_1^2v_2^2 + 12a_6v_1v_2^3 \\
& + 5a_6v_2^4 + 2b_4v_1^3v_2 + b_5v_1^2v_2^2 + 2a_2v_1v_2^2 + 4a_3v_1^2v_2 + 6a_3v_1v_2^2 + 3a_3v_2^3 \\
& - 6a_4v_1^2v_2 - 2a_4v_1v_2^2 - a_5v_1^3 - 2a_5v_1^2v_2 - 5a_5v_1v_2^2 - a_5v_2^3 - 2a_6v_1^2v_2 \\
& - 4a_6v_1v_2^2 - 4a_6v_2^3 + 2b_2v_1^2v_2 + b_3v_1v_2^2 - 2b_4v_1^3 - 2b_4v_1^2v_2 - b_5v_1v_2^2 \\
& + 2b_6v_1v_2^2 + a_1v_2^2 - 4a_2v_1v_2 - a_2v_2^2 - a_3v_1^2 - 2a_3v_1v_2 - 3a_3v_2^2 + 3a_4v_1^2 \\
& + 2a_4v_1v_2 + 2a_5v_1v_2 + a_5v_2^2 + a_6v_2^2 + 2b_1v_1v_2 - 2b_2v_1^2 - 2b_2v_1v_2 \\
& - b_3v_2^2 + b_4v_1^2 - b_5v_1^2 - 2b_6v_1v_2 - b_6v_2^2 - 2a_1v_2 + 2a_2v_1 + a_2v_2 + a_3v_2 \\
& - 2b_1v_1 - 2b_1v_2 + b_2v_1 - b_3v_1 + 2b_4v_1 + b_5v_2 + a_1 + b_1 + b_2 = 0
\end{aligned} \tag{7E}$$

Collecting the above on the terms v_i introduced, and these are

$$\{v_1, v_2\}$$

Equation (7E) now becomes

$$\begin{aligned}
& (4a_5 + 2b_4)v_1^3v_2 + (-a_3 + 2a_5 + 8a_6)v_1^2v_2^4 \\
& + (4a_3 - 6a_5 - 12a_6)v_1^2v_2^3 + (-6a_3 + 3a_4 + 6a_5 + 8a_6 + b_5)v_1^2v_2^2 \\
& + (4a_3 - 6a_4 - 2a_5 - 2a_6 + 2b_2 - 2b_4)v_1^2v_2 \\
& + (2a_3 - a_5 - 12a_6)v_1v_2^4 + (-6a_3 + 4a_5 + 12a_6)v_1v_2^3 \\
& + (2a_2 + 6a_3 - 2a_4 - 5a_5 - 4a_6 + b_3 - b_5 + 2b_6)v_1v_2^2 \\
& + (-4a_2 - 2a_3 + 2a_4 + 2a_5 + 2b_1 - 2b_2 - 2b_6)v_1v_2 + a_1 + b_1 \\
& + b_2 + (-a_5 - 2b_4)v_1^3 - 2a_6v_2^5 + (-a_3 + 3a_4 - 2b_2 + b_4 - b_5)v_2^2 \\
& + (2a_2 - 2b_1 + b_2 - b_3 + 2b_4)v_1 + (-a_3 + 5a_6)v_2^4 + (3a_3 - a_5 - 4a_6)v_2^3 \\
& + (a_1 - a_2 - 3a_3 + a_5 + a_6 - b_3 - b_6)v_2^2 + (-2a_1 + a_2 + a_3 - 2b_1 + b_5)v_2 \\
& - a_5v_1^3v_2^4 - 2a_6v_1^2v_2^5 + 4a_5v_1^3v_2^3 + 4a_6v_1v_2^5 - 6a_5v_1^3v_2^2 = 0
\end{aligned} \tag{8E}$$

Setting each coefficients in (8E) to zero gives the following equations to solve

$$\begin{aligned} -6a_5 &= 0 \\ -a_5 &= 0 \\ 4a_5 &= 0 \\ -2a_6 &= 0 \\ 4a_6 &= 0 \\ -a_3 + 5a_6 &= 0 \\ -a_5 - 2b_4 &= 0 \\ 4a_5 + 2b_4 &= 0 \\ a_1 + b_1 + b_2 &= 0 \\ -6a_3 + 4a_5 + 12a_6 &= 0 \\ -a_3 + 2a_5 + 8a_6 &= 0 \\ 2a_3 - a_5 - 12a_6 &= 0 \\ 3a_3 - a_5 - 4a_6 &= 0 \\ 4a_3 - 6a_5 - 12a_6 &= 0 \\ -2a_1 + a_2 + a_3 - 2b_1 + b_5 &= 0 \\ 2a_2 - 2b_1 + b_2 - b_3 + 2b_4 &= 0 \\ -6a_3 + 3a_4 + 6a_5 + 8a_6 + b_5 &= 0 \\ -a_3 + 3a_4 - 2b_2 + b_4 - b_5 &= 0 \\ 4a_3 - 6a_4 - 2a_5 - 2a_6 + 2b_2 - 2b_4 &= 0 \\ a_1 - a_2 - 3a_3 + a_5 + a_6 - b_3 - b_6 &= 0 \\ -4a_2 - 2a_3 + 2a_4 + 2a_5 + 2b_1 - 2b_2 - 2b_6 &= 0 \\ 2a_2 + 6a_3 - 2a_4 - 5a_5 - 4a_6 + b_3 - b_5 + 2b_6 &= 0 \end{aligned}$$

Solving the above equations for the unknowns gives

$$\begin{aligned}
 a_1 &= -b_6 \\
 a_2 &= 0 \\
 a_3 &= 0 \\
 a_4 &= 0 \\
 a_5 &= 0 \\
 a_6 &= 0 \\
 b_1 &= b_6 \\
 b_2 &= 0 \\
 b_3 &= -2b_6 \\
 b_4 &= 0 \\
 b_5 &= 0 \\
 b_6 &= b_6
 \end{aligned}$$

Substituting the above solution in the anstaz (1E,2E) (using 1 as arbitrary value for any unknown in the RHS) gives

$$\begin{aligned}
 \xi &= -1 \\
 \eta &= y^2 - 2y + 1
 \end{aligned}$$

Shifting is now applied to make $\xi = 0$ in order to simplify the rest of the computation

$$\begin{aligned}
 \eta &= \eta - \omega(x, y) \xi \\
 &= y^2 - 2y + 1 - (-x y^2 + 2xy + y^2 - x - y) (-1) \\
 &= -x y^2 + 2xy + 2y^2 - x - 3y + 1 \\
 \xi &= 0
 \end{aligned}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{-x y^2 + 2xy + 2y^2 - x - 3y + 1} dy \end{aligned}$$

Which results in

$$S = \ln(y - 1) + \frac{(-x + 2) \ln(xy - x - 2y + 1)}{x - 2}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -x y^2 + 2xy + y^2 - x - y$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= \frac{-y + 1}{(x - 2)y + 1 - x} \\ S_y &= -\frac{1}{(y - 1)((x - 2)y + 1 - x)} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 1 \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 1$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = R + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$\ln(y - 1) - \ln((y - 1)x - 2y + 1) = x + c_1$$

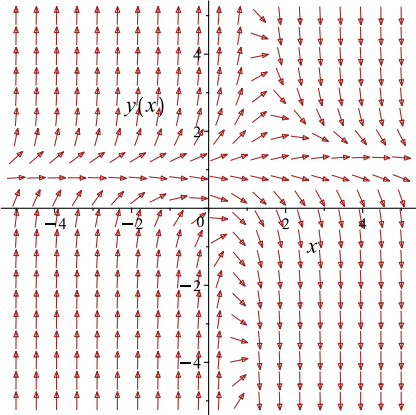
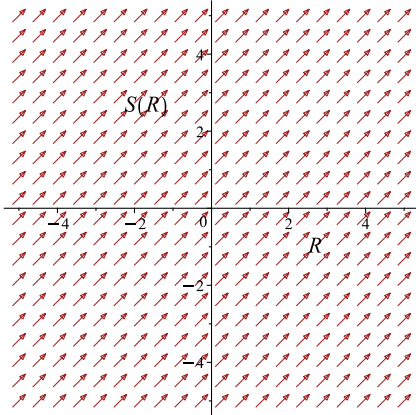
Which simplifies to

$$\ln(y - 1) - \ln((y - 1)x - 2y + 1) = x + c_1$$

Which gives

$$y = \frac{x e^{x+c_1} - e^{x+c_1} - 1}{-1 + x e^{x+c_1} - 2 e^{x+c_1}}$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -x y^2 + 2xy + y^2 - x - y$ 	$R = x$ $S = \ln(y - 1) - \ln((y - 1)x - 2y + 1)$	$\frac{dS}{dR} = 1$ 

Summary

The solution(s) found are the following

$$y = \frac{x e^{x+c_1} - e^{x+c_1} - 1}{-1 + x e^{x+c_1} - 2 e^{x+c_1}} \quad (1)$$

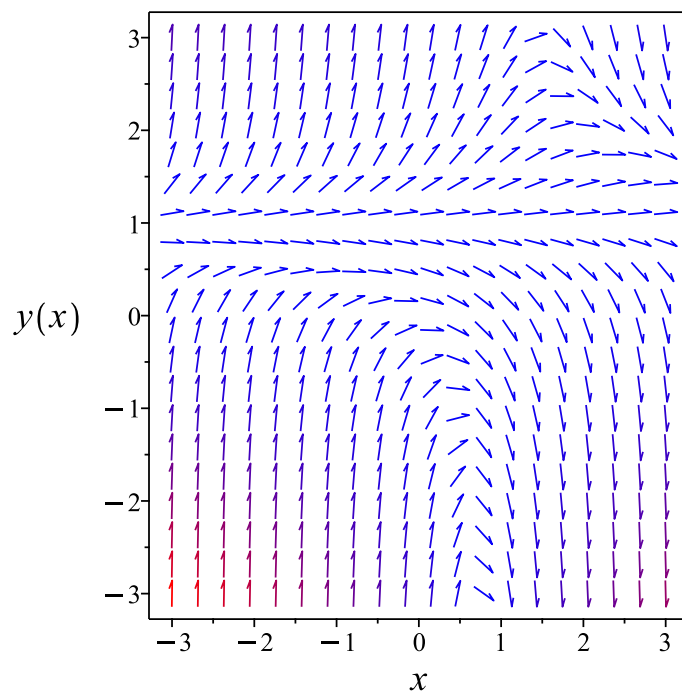


Figure 238: Slope field plot

Verification of solutions

$$y = \frac{x e^{x+c_1} - e^{x+c_1} - 1}{-1 + x e^{x+c_1} - 2 e^{x+c_1}}$$

Verified OK.

5.35.2 Solving as riccati ode

In canonical form the ODE is

$$\begin{aligned} y' &= F(x, y) \\ &= -x y^2 + 2xy + y^2 - x - y \end{aligned}$$

This is a Riccati ODE. Comparing the ODE to solve

$$y' = -x y^2 + 2xy + y^2 - x - y$$

With Riccati ODE standard form

$$y' = f_0(x) + f_1(x)y + f_2(x)y^2$$

Shows that $f_0(x) = -x$, $f_1(x) = 2x - 1$ and $f_2(x) = 1 - x$. Let

$$\begin{aligned} y &= \frac{-u'}{f_2 u} \\ &= \frac{-u'}{(1-x)u} \end{aligned} \quad (1)$$

Using the above substitution in the given ODE results (after some simplification) in a second order ODE to solve for $u(x)$ which is

$$f_2 u''(x) - (f_2' + f_1 f_2) u'(x) + f_2^2 f_0 u(x) = 0 \quad (2)$$

But

$$\begin{aligned} f_2' &= -1 \\ f_1 f_2 &= (2x - 1)(1 - x) \\ f_2^2 f_0 &= -(1 - x)^2 x \end{aligned}$$

Substituting the above terms back in equation (2) gives

$$(1 - x) u''(x) - (-1 + (2x - 1)(1 - x)) u'(x) - (1 - x)^2 x u(x) = 0$$

Solving the above ODE (this ode solved using Maple, not this program), gives

$$u(x) = c_1 e^{\frac{x(x-2)}{2}} + c_2 e^{\frac{x^2}{2}} (x - 2)$$

The above shows that

$$u'(x) = \left((x - 1) c_2 e^{\frac{x^2}{2}} + c_1 e^{\frac{x(x-2)}{2}} \right) (x - 1)$$

Using the above in (1) gives the solution

$$y = - \frac{\left((x - 1) c_2 e^{\frac{x^2}{2}} + c_1 e^{\frac{x(x-2)}{2}} \right) (x - 1)}{(1 - x) \left(c_1 e^{\frac{x(x-2)}{2}} + c_2 e^{\frac{x^2}{2}} (x - 2) \right)}$$

Dividing both numerator and denominator by c_1 gives, after renaming the constant $\frac{c_2}{c_1} = c_3$ the following solution

$$y = \frac{(x - 1) e^{\frac{x^2}{2}} + c_3 e^{\frac{x(x-2)}{2}}}{c_3 e^{\frac{x(x-2)}{2}} + e^{\frac{x^2}{2}} (x - 2)}$$

Summary

The solution(s) found are the following

$$y = \frac{(x - 1) e^{\frac{x^2}{2}} + c_3 e^{\frac{x(x-2)}{2}}}{c_3 e^{\frac{x(x-2)}{2}} + e^{\frac{x^2}{2}} (x - 2)} \quad (1)$$

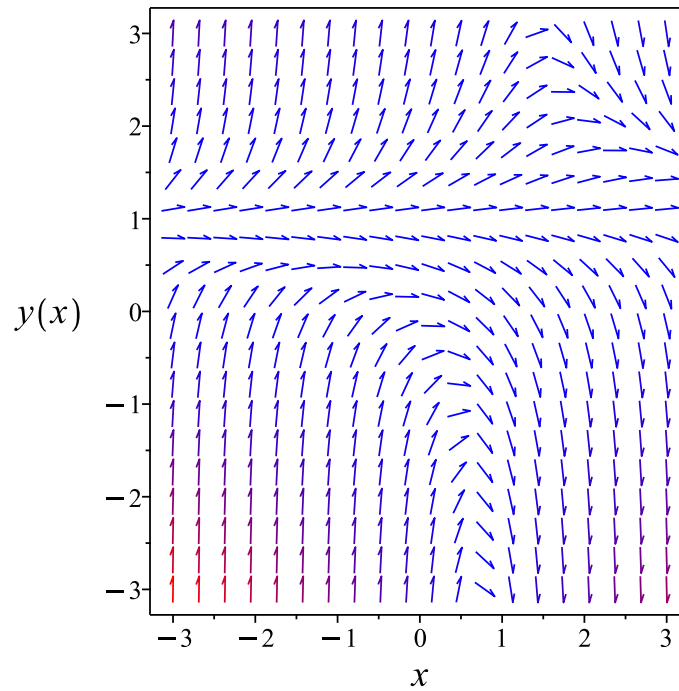


Figure 239: Slope field plot

Verification of solutions

$$y = \frac{(x - 1) e^{\frac{x^2}{2}} + c_3 e^{\frac{x(x-2)}{2}}}{c_3 e^{\frac{x(x-2)}{2}} + e^{\frac{x^2}{2}} (x - 2)}$$

Verified OK.

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
trying Bernoulli  
trying separable  
trying inverse linear  
trying homogeneous types:  
trying Chini  
differential order: 1; looking for linear symmetries  
trying exact  
Looking for potential symmetries  
trying Riccati  
trying Riccati sub-methods:  
  <- Riccati particular case Kamke (a) successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 31

```
dsolve(diff(y(x),x)=(1-x)*y(x)^2+(2*x-1)*y(x)-x,y(x), singsol=all)
```

$$y(x) = \frac{(2x - 2)e^x - c_1}{(2x - 4)e^x - c_1}$$

✓ Solution by Mathematica

Time used: 0.197 (sec). Leaf size: 28

```
DSolve[y'[x]==(1-x)*y[x]^2+(2*x-1)*y[x]-x,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow 1 + \frac{e^x}{e^x(x - 2) + c_1}$$
$$y(x) \rightarrow 1$$

5.36 problem 40

5.36.1 Solving as riccati ode 1234

Internal problem ID [11673]

Internal file name [OUTPUT/11682_Wednesday_April_10_2024_04_54_35_PM_23538320/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.3 (Linear equations). Exercises page 56

Problem number: 40.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**riccati**"

Maple gives the following as the ode type

[_Riccati]

$$y' + y^2 - yx = 1$$

5.36.1 Solving as riccati ode

In canonical form the ODE is

$$\begin{aligned}y' &= F(x, y) \\ &= xy - y^2 + 1\end{aligned}$$

This is a Riccati ODE. Comparing the ODE to solve

$$y' = xy - y^2 + 1$$

With Riccati ODE standard form

$$y' = f_0(x) + f_1(x)y + f_2(x)y^2$$

Shows that $f_0(x) = 1$, $f_1(x) = x$ and $f_2(x) = -1$. Let

$$\begin{aligned}y &= \frac{-u'}{f_2 u} \\ &= \frac{-u'}{-u}\end{aligned}\tag{1}$$

Using the above substitution in the given ODE results (after some simplification) in a second order ODE to solve for $u(x)$ which is

$$f_2 u''(x) - (f_2' + f_1 f_2) u'(x) + f_2^2 f_0 u(x) = 0 \quad (2)$$

But

$$\begin{aligned} f_2' &= 0 \\ f_1 f_2 &= -x \\ f_2^2 f_0 &= 1 \end{aligned}$$

Substituting the above terms back in equation (2) gives

$$-u''(x) + x u'(x) + u(x) = 0$$

Solving the above ODE (this ode solved using Maple, not this program), gives

$$u(x) = e^{\frac{x^2}{2}} \left(c_1 \operatorname{erf} \left(\frac{\sqrt{2} x}{2} \right) + c_2 \right)$$

The above shows that

$$u'(x) = \frac{x\sqrt{\pi} \left(c_1 \operatorname{erf} \left(\frac{\sqrt{2} x}{2} \right) + c_2 \right) e^{\frac{x^2}{2}} + \sqrt{2} c_1}{\sqrt{\pi}}$$

Using the above in (1) gives the solution

$$y = \frac{\left(x\sqrt{\pi} \left(c_1 \operatorname{erf} \left(\frac{\sqrt{2} x}{2} \right) + c_2 \right) e^{\frac{x^2}{2}} + \sqrt{2} c_1 \right) e^{-\frac{x^2}{2}}}{\sqrt{\pi} \left(c_1 \operatorname{erf} \left(\frac{\sqrt{2} x}{2} \right) + c_2 \right)}$$

Dividing both numerator and denominator by c_1 gives, after renaming the constant $\frac{c_2}{c_1} = c_3$ the following solution

$$y = \frac{\sqrt{2} c_3 e^{-\frac{x^2}{2}} + \sqrt{\pi} x \left(c_3 \operatorname{erf} \left(\frac{\sqrt{2} x}{2} \right) + 1 \right)}{\sqrt{\pi} \left(c_3 \operatorname{erf} \left(\frac{\sqrt{2} x}{2} \right) + 1 \right)}$$

Summary

The solution(s) found are the following

$$y = \frac{\sqrt{2} c_3 e^{-\frac{x^2}{2}} + \sqrt{\pi} x \left(c_3 \operatorname{erf} \left(\frac{\sqrt{2} x}{2} \right) + 1 \right)}{\sqrt{\pi} \left(c_3 \operatorname{erf} \left(\frac{\sqrt{2} x}{2} \right) + 1 \right)} \quad (1)$$

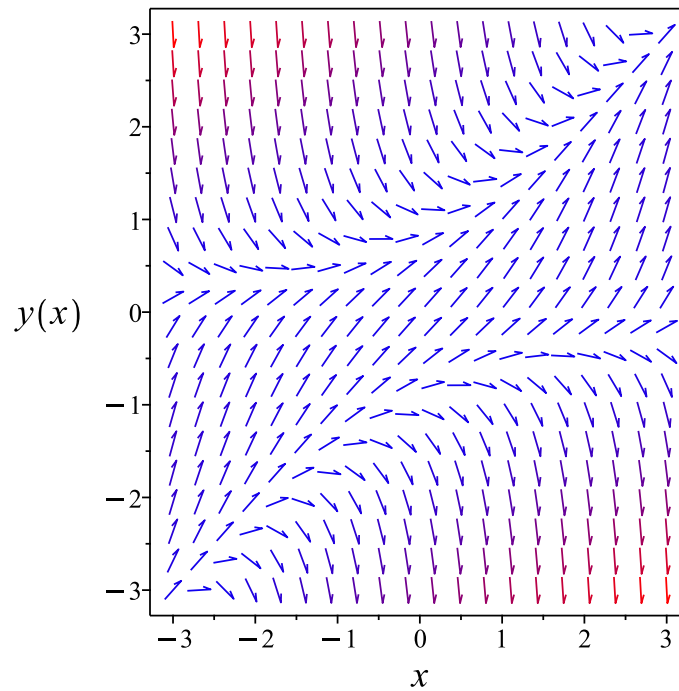


Figure 240: Slope field plot

Verification of solutions

$$y = \frac{\sqrt{2} c_3 e^{-\frac{x^2}{2}} + \sqrt{\pi} x \left(c_3 \operatorname{erf} \left(\frac{\sqrt{2} x}{2} \right) + 1 \right)}{\sqrt{\pi} \left(c_3 \operatorname{erf} \left(\frac{\sqrt{2} x}{2} \right) + 1 \right)}$$

Verified OK.

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
trying Bernoulli  
trying separable  
trying inverse linear  
trying homogeneous types:  
trying Chini  
differential order: 1; looking for linear symmetries  
trying exact  
Looking for potential symmetries  
found: 2 potential symmetries. Proceeding with integration step`
```

✓ Solution by Maple

Time used: 0.031 (sec). Leaf size: 53

```
dsolve(diff(y(x),x)=-y(x)^2+x*y(x)+1,y(x), singsol=all)
```

$$y(x) = \frac{\sqrt{\pi} \sqrt{2} \operatorname{erf}\left(\frac{x\sqrt{2}}{2}\right) x + 2c_1 x + 2e^{-\frac{x^2}{2}}}{\sqrt{\pi} \sqrt{2} \operatorname{erf}\left(\frac{x\sqrt{2}}{2}\right) + 2c_1}$$

✓ Solution by Mathematica

Time used: 0.154 (sec). Leaf size: 45

```
DSolve[y'[x]==-y[x]^2+x*y[x]+1,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow x + \frac{e^{-\frac{x^2}{2}}}{\sqrt{\frac{\pi}{2}} \operatorname{erf}\left(\frac{x}{\sqrt{2}}\right) + c_1}$$
$$y(x) \rightarrow x$$

5.37 problem 41

5.37.1 Solving as first order ode lie symmetry calculated ode 1238

5.37.2 Solving as riccati ode 1247

Internal problem ID [11674]

Internal file name [OUTPUT/11683_Wednesday_April_10_2024_04_54_36_PM_3623463/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, section 2.3 (Linear equations). Exercises page 56

Problem number: 41.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**riccati**", "**first_order_ode_lie_symmetry_calculated**"

Maple gives the following as the ode type

```
[[_1st_order, `_with_symmetry_[F(x),G(x)]`], _Riccati]
```

$$y' + 8y^2x - 4x(4x + 1)y = -8x^3 - 4x^2 + 1$$

5.37.1 Solving as first order ode lie symmetry calculated ode

Writing the ode as

$$\begin{aligned}y' &= -8x^3 + 16x^2y - 8xy^2 - 4x^2 + 4xy + 1 \\y' &= \omega(x, y)\end{aligned}$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2\xi_y - \omega_x\xi - \omega_y\eta = 0 \quad (\text{A})$$

The type of this ode is not in the lookup table. To determine ξ, η then (A) is solved using ansatz. Making bivariate polynomials of degree 2 to use as anstaz gives

$$\xi = x^2a_4 + xya_5 + y^2a_6 + xa_2 + ya_3 + a_1 \quad (1\text{E})$$

$$\eta = x^2b_4 + xyb_5 + y^2b_6 + xb_2 + yb_3 + b_1 \quad (2\text{E})$$

Where the unknown coefficients are

$$\{a_1, a_2, a_3, a_4, a_5, a_6, b_1, b_2, b_3, b_4, b_5, b_6\}$$

Substituting equations (1E,2E) and ω into (A) gives

$$\begin{aligned} & 2xb_4 + yb_5 + b_2 \\ & + (-8x^3 + 16x^2y - 8xy^2 - 4x^2 + 4xy + 1) (-2xa_4 + xb_5 - ya_5 + 2yb_6 - a_2 + b_3) \\ & - (-8x^3 + 16x^2y - 8xy^2 - 4x^2 + 4xy + 1)^2 (xa_5 + 2ya_6 + a_3) \\ & - (-24x^2 + 32xy - 8y^2 - 8x + 4y) (x^2a_4 + xya_5 + y^2a_6 + xa_2 + ya_3 + a_1) \\ & - (16x^2 - 16xy + 4x) (x^2b_4 + xyb_5 + y^2b_6 + xb_2 + yb_3 + b_1) = 0 \end{aligned} \quad (5E)$$

Putting the above in normal form gives

$$\begin{aligned} & -64x^7a_5 + 256x^6ya_5 - 128x^6ya_6 - 384x^5y^2a_5 + 512x^5y^2a_6 \\ & + 256x^4y^3a_5 - 768x^4y^3a_6 - 64x^3y^4a_5 + 512x^3y^4a_6 - 128x^2y^5a_6 \\ & - 64x^6a_3 - 64x^6a_5 + 256x^5ya_3 + 192x^5ya_5 - 128x^5ya_6 - 384x^4y^2a_3 \\ & - 192x^4y^2a_5 + 384x^4y^2a_6 + 256x^3y^3a_3 + 64x^3y^3a_5 - 384x^3y^3a_6 \\ & - 64x^2y^4a_3 + 128x^2y^4a_6 - 64x^5a_3 - 16x^5a_5 + 192x^4ya_3 + 32x^4ya_5 \\ & - 32x^4ya_6 - 192x^3y^2a_3 - 16x^3y^2a_5 + 64x^3y^2a_6 + 64x^2y^3a_3 \\ & - 32x^2y^3a_6 - 16x^4a_3 + 40x^4a_4 + 16x^4a_5 - 16x^4b_4 - 8x^4b_5 + 32x^3ya_3 \\ & - 64x^3ya_4 + 32x^3ya_6 + 16x^3yb_4 - 16x^3yb_6 - 16x^2y^2a_3 + 24x^2y^2a_4 \\ & - 32x^2y^2a_5 - 40x^2y^2a_6 + 8x^2y^2b_5 + 16x^2y^2b_6 + 16xy^3a_5 + 8y^4a_6 \\ & + 32x^3a_2 + 16x^3a_3 + 16x^3a_4 + 8x^3a_5 - 16x^3b_2 - 8x^3b_3 - 4x^3b_4 - 4x^3b_5 \\ & - 48x^2ya_2 - 8x^2ya_3 - 12x^2ya_4 + 4x^2ya_5 + 16x^2ya_6 + 16x^2yb_2 - 8x^2yb_6 \\ & + 16xy^2a_2 - 16xy^2a_3 - 8xy^2a_5 - 8xy^2a_6 + 8xy^2b_3 + 4xy^2b_6 + 8y^3a_3 \\ & - 4y^3a_6 + 24x^2a_1 + 12x^2a_2 + 8x^2a_3 - 16x^2b_1 - 4x^2b_2 - 4x^2b_3 - 32xya_1 \\ & - 8xya_2 + 16xyb_1 + 8y^2a_1 - 4y^2a_3 + 8xa_1 - 2xa_4 - xa_5 - 4xb_1 \\ & + 2xb_4 + xb_5 - 4ya_1 - ya_5 - 2ya_6 + yb_5 + 2yb_6 - a_2 - a_3 + b_2 + b_3 = 0 \end{aligned}$$

Setting the numerator to zero gives

$$\begin{aligned}
& -64x^7a_5 + 256x^6ya_5 - 128x^6ya_6 - 384x^5y^2a_5 + 512x^5y^2a_6 \\
& + 256x^4y^3a_5 - 768x^4y^3a_6 - 64x^3y^4a_5 + 512x^3y^4a_6 - 128x^2y^5a_6 \\
& - 64x^6a_3 - 64x^6a_5 + 256x^5ya_3 + 192x^5ya_5 - 128x^5ya_6 \\
& - 384x^4y^2a_3 - 192x^4y^2a_5 + 384x^4y^2a_6 + 256x^3y^3a_3 \\
& + 64x^3y^3a_5 - 384x^3y^3a_6 - 64x^2y^4a_3 + 128x^2y^4a_6 - 64x^5a_3 \\
& - 16x^5a_5 + 192x^4ya_3 + 32x^4ya_5 - 32x^4ya_6 - 192x^3y^2a_3 \\
& - 16x^3y^2a_5 + 64x^3y^2a_6 + 64x^2y^3a_3 - 32x^2y^3a_6 - 16x^4a_3 \\
& + 40x^4a_4 + 16x^4a_5 - 16x^4b_4 - 8x^4b_5 + 32x^3ya_3 - 64x^3ya_4 \\
& + 32x^3ya_6 + 16x^3yb_4 - 16x^3yb_6 - 16x^2y^2a_3 + 24x^2y^2a_4 \\
& - 32x^2y^2a_5 - 40x^2y^2a_6 + 8x^2y^2b_5 + 16x^2y^2b_6 + 16xy^3a_5 \\
& + 8y^4a_6 + 32x^3a_2 + 16x^3a_3 + 16x^3a_4 + 8x^3a_5 - 16x^3b_2 - 8x^3b_3 \\
& - 4x^3b_4 - 4x^3b_5 - 48x^2ya_2 - 8x^2ya_3 - 12x^2ya_4 + 4x^2ya_5 \\
& + 16x^2ya_6 + 16x^2yb_2 - 8x^2yb_6 + 16xy^2a_2 - 16xy^2a_3 - 8xy^2a_5 \\
& - 8xy^2a_6 + 8xy^2b_3 + 4xy^2b_6 + 8y^3a_3 - 4y^3a_6 + 24x^2a_1 \\
& + 12x^2a_2 + 8x^2a_3 - 16x^2b_1 - 4x^2b_2 - 4x^2b_3 - 32xya_1 - 8xya_2 \\
& + 16xyb_1 + 8y^2a_1 - 4y^2a_3 + 8xa_1 - 2xa_4 - xa_5 - 4xb_1 + 2xb_4 \\
& + xb_5 - 4ya_1 - ya_5 - 2ya_6 + yb_5 + 2yb_6 - a_2 - a_3 + b_2 + b_3 = 0
\end{aligned} \tag{6E}$$

Looking at the above PDE shows the following are all the terms with $\{x, y\}$ in them.

$$\{x, y\}$$

The following substitution is now made to be able to collect on all terms with $\{x, y\}$ in them

$$\{x = v_1, y = v_2\}$$

The above PDE (6E) now becomes

$$\begin{aligned}
& -64a_5v_1^7 + 256a_5v_1^6v_2 - 384a_5v_1^5v_2^2 + 256a_5v_1^4v_2^3 - 64a_5v_1^3v_2^4 \\
& - 128a_6v_1^6v_2 + 512a_6v_1^5v_2^2 - 768a_6v_1^4v_2^3 + 512a_6v_1^3v_2^4 \\
& - 128a_6v_1^2v_2^5 - 64a_3v_1^6 + 256a_3v_1^5v_2 - 384a_3v_1^4v_2^2 + 256a_3v_1^3v_2^3 \\
& - 64a_3v_1^2v_2^4 - 64a_5v_1^6 + 192a_5v_1^5v_2 - 192a_5v_1^4v_2^2 + 64a_5v_1^3v_2^3 \\
& - 128a_6v_1^5v_2 + 384a_6v_1^4v_2^2 - 384a_6v_1^3v_2^3 + 128a_6v_1^2v_2^4 \\
& - 64a_3v_1^5 + 192a_3v_1^4v_2 - 192a_3v_1^3v_2^2 + 64a_3v_1^2v_2^3 - 16a_5v_1^5 \\
& + 32a_5v_1^4v_2 - 16a_5v_1^3v_2^2 - 32a_6v_1^4v_2 + 64a_6v_1^3v_2^2 - 32a_6v_1^2v_2^3 \\
& - 16a_3v_1^4 + 32a_3v_1^3v_2 - 16a_3v_1^2v_2^2 + 40a_4v_1^4 - 64a_4v_1^3v_2 \\
& + 24a_4v_1^2v_2^2 + 16a_5v_1^4 - 32a_5v_1^2v_2^2 + 16a_5v_1v_2^3 + 32a_6v_1^3v_2 \\
& - 40a_6v_1^2v_2^2 + 8a_6v_2^4 - 16b_4v_1^4 + 16b_4v_1^3v_2 - 8b_5v_1^4 + 8b_5v_1^2v_2^2 \\
& - 16b_6v_1^3v_2 + 16b_6v_1^2v_2^2 + 32a_2v_1^3 - 48a_2v_1^2v_2 + 16a_2v_1v_2^2 \\
& + 16a_3v_1^3 - 8a_3v_1^2v_2 - 16a_3v_1v_2^2 + 8a_3v_2^3 + 16a_4v_1^3 - 12a_4v_1^2v_2 \\
& + 8a_5v_1^3 + 4a_5v_1^2v_2 - 8a_5v_1v_2^2 + 16a_6v_1^2v_2 - 8a_6v_1v_2^2 - 4a_6v_2^3 \\
& - 16b_2v_1^3 + 16b_2v_1^2v_2 - 8b_3v_1^3 + 8b_3v_1v_2^2 - 4b_4v_1^3 - 4b_5v_1^3 \\
& - 8b_6v_1^2v_2 + 4b_6v_1v_2^2 + 24a_1v_1^2 - 32a_1v_1v_2 + 8a_1v_2^2 + 12a_2v_1^2 \\
& - 8a_2v_1v_2 + 8a_3v_1^2 - 4a_3v_2^2 - 16b_1v_1^2 + 16b_1v_1v_2 - 4b_2v_1^2 \\
& - 4b_3v_1^2 + 8a_1v_1 - 4a_1v_2 - 2a_4v_1 - a_5v_1 - a_5v_2 - 2a_6v_2 \\
& - 4b_1v_1 + 2b_4v_1 + b_5v_1 + b_5v_2 + 2b_6v_2 - a_2 - a_3 + b_2 + b_3 = 0
\end{aligned} \tag{7E}$$

Collecting the above on the terms v_i introduced, and these are

$$\{v_1, v_2\}$$

Equation (7E) now becomes

$$\begin{aligned}
& -a_2 - a_3 + b_2 + b_3 \\
& + (-16a_3 + 24a_4 - 32a_5 - 40a_6 + 8b_5 + 16b_6) v_1^2 v_2^2 \\
& + (-48a_2 - 8a_3 - 12a_4 + 4a_5 + 16a_6 + 16b_2 - 8b_6) v_1^2 v_2 \\
& + (16a_2 - 16a_3 - 8a_5 - 8a_6 + 8b_3 + 4b_6) v_1 v_2^2 \\
& + (-32a_1 - 8a_2 + 16b_1) v_1 v_2 + (256a_5 - 128a_6) v_1^6 v_2 \\
& + (-384a_5 + 512a_6) v_1^5 v_2^2 + (256a_3 + 192a_5 - 128a_6) v_1^5 v_2 \\
& + (256a_5 - 768a_6) v_1^4 v_2^3 + (-384a_3 - 192a_5 + 384a_6) v_1^4 v_2^2 \\
& + (192a_3 + 32a_5 - 32a_6) v_1^4 v_2 + (-64a_5 + 512a_6) v_1^3 v_2^4 \\
& + (256a_3 + 64a_5 - 384a_6) v_1^3 v_2^3 + (-192a_3 - 16a_5 + 64a_6) v_1^3 v_2^2 \\
& + (32a_3 - 64a_4 + 32a_6 + 16b_4 - 16b_6) v_1^3 v_2 + (-64a_3 + 128a_6) v_1^2 v_2^4 \\
& + (64a_3 - 32a_6) v_1^2 v_2^3 - 128a_6 v_1^2 v_2^5 - 64a_5 v_1^7 + 8a_6 v_2^4 \\
& + 16a_5 v_1 v_2^3 + (24a_1 + 12a_2 + 8a_3 - 16b_1 - 4b_2 - 4b_3) v_1^2 \\
& + (8a_1 - 2a_4 - a_5 - 4b_1 + 2b_4 + b_5) v_1 + (8a_3 - 4a_6) v_2^3 \\
& + (8a_1 - 4a_3) v_2^2 + (-4a_1 - a_5 - 2a_6 + b_5 + 2b_6) v_2 \\
& + (-64a_3 - 64a_5) v_1^6 + (-64a_3 - 16a_5) v_1^5 \\
& + (-16a_3 + 40a_4 + 16a_5 - 16b_4 - 8b_5) v_1^4 \\
& + (32a_2 + 16a_3 + 16a_4 + 8a_5 - 16b_2 - 8b_3 - 4b_4 - 4b_5) v_1^3 = 0
\end{aligned} \tag{8E}$$

Setting each coefficients in (8E) to zero gives the following equations to solve

$$\begin{aligned}
 -64a_5 &= 0 \\
 16a_5 &= 0 \\
 -128a_6 &= 0 \\
 8a_6 &= 0 \\
 8a_1 - 4a_3 &= 0 \\
 -64a_3 - 64a_5 &= 0 \\
 -64a_3 - 16a_5 &= 0 \\
 -64a_3 + 128a_6 &= 0 \\
 8a_3 - 4a_6 &= 0 \\
 64a_3 - 32a_6 &= 0 \\
 -384a_5 + 512a_6 &= 0 \\
 -64a_5 + 512a_6 &= 0 \\
 256a_5 - 768a_6 &= 0 \\
 256a_5 - 128a_6 &= 0 \\
 -32a_1 - 8a_2 + 16b_1 &= 0 \\
 -384a_3 - 192a_5 + 384a_6 &= 0 \\
 -192a_3 - 16a_5 + 64a_6 &= 0 \\
 192a_3 + 32a_5 - 32a_6 &= 0 \\
 256a_3 + 64a_5 - 384a_6 &= 0 \\
 256a_3 + 192a_5 - 128a_6 &= 0 \\
 -a_2 - a_3 + b_2 + b_3 &= 0 \\
 -4a_1 - a_5 - 2a_6 + b_5 + 2b_6 &= 0 \\
 -16a_3 + 40a_4 + 16a_5 - 16b_4 - 8b_5 &= 0 \\
 32a_3 - 64a_4 + 32a_6 + 16b_4 - 16b_6 &= 0 \\
 8a_1 - 2a_4 - a_5 - 4b_1 + 2b_4 + b_5 &= 0 \\
 24a_1 + 12a_2 + 8a_3 - 16b_1 - 4b_2 - 4b_3 &= 0 \\
 16a_2 - 16a_3 - 8a_5 - 8a_6 + 8b_3 + 4b_6 &= 0 \\
 -16a_3 + 24a_4 - 32a_5 - 40a_6 + 8b_5 + 16b_6 &= 0 \\
 -48a_2 - 8a_3 - 12a_4 + 4a_5 + 16a_6 + 16b_2 - 8b_6 &= 0 \\
 32a_2 + 16a_3 + 16a_4 + 8a_5 - 16b_2 - 8b_3 - 4b_4 - 4b_5 &= 0
 \end{aligned}$$

Solving the above equations for the unknowns gives

$$\begin{aligned}
 a_1 &= 0 \\
 a_2 &= 0 \\
 a_3 &= 0 \\
 a_4 &= 0 \\
 a_5 &= 0 \\
 a_6 &= 0 \\
 b_1 &= 0 \\
 b_2 &= \frac{b_6}{2} \\
 b_3 &= -\frac{b_6}{2} \\
 b_4 &= b_6 \\
 b_5 &= -2b_6 \\
 b_6 &= b_6
 \end{aligned}$$

Substituting the above solution in the anstaz (1E,2E) (using 1 as arbitrary value for any unknown in the RHS) gives

$$\begin{aligned}
 \xi &= 0 \\
 \eta &= x^2 - 2xy + y^2 + \frac{1}{2}x - \frac{1}{2}y
 \end{aligned}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{x^2 - 2xy + y^2 + \frac{1}{2}x - \frac{1}{2}y} dy \end{aligned}$$

Which results in

$$S = 2 \ln(2y - 2x - 1) - 2 \ln(y - x)$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -8x^3 + 16x^2y - 8xy^2 - 4x^2 + 4xy + 1$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= -\frac{2}{(2x - 2y + 1)(-y + x)} \\ S_y &= \frac{2}{(2x - 2y + 1)(-y + x)} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = -8R \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = -8R$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by

integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = -4R^2 + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$2 \ln(2y - 2x - 1) - 2 \ln(y - x) = -4x^2 + c_1$$

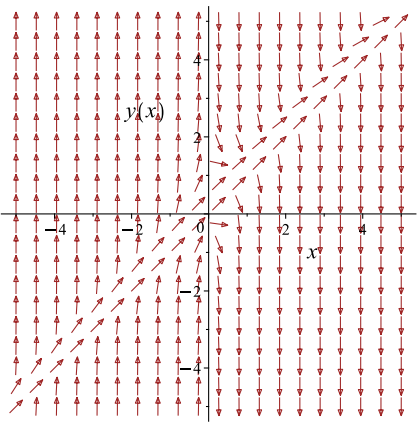
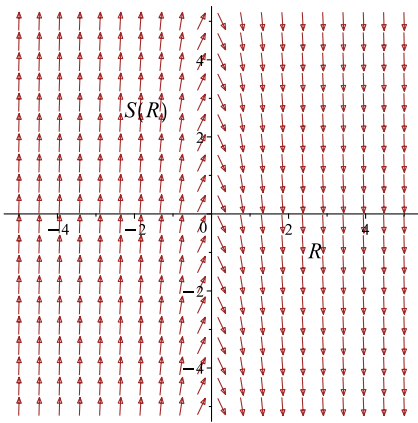
Which simplifies to

$$2 \ln(2y - 2x - 1) - 2 \ln(y - x) = -4x^2 + c_1$$

Which gives

$$y = \frac{x e^{-2x^2 + \frac{c_1}{2}} - 2x - 1}{e^{-2x^2 + \frac{c_1}{2}} - 2}$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$-8x^3 + 16x^2y - 8xy^2 - 4x^2 + 4xy + 1$ 	$R = x$ $S = 2 \ln(2y - 2x - 1)$	$\frac{dS}{dR} = -8R$ 

Summary

The solution(s) found are the following

$$y = \frac{x e^{-2x^2 + \frac{c_1}{2}} - 2x - 1}{e^{-2x^2 + \frac{c_1}{2}} - 2} \quad (1)$$

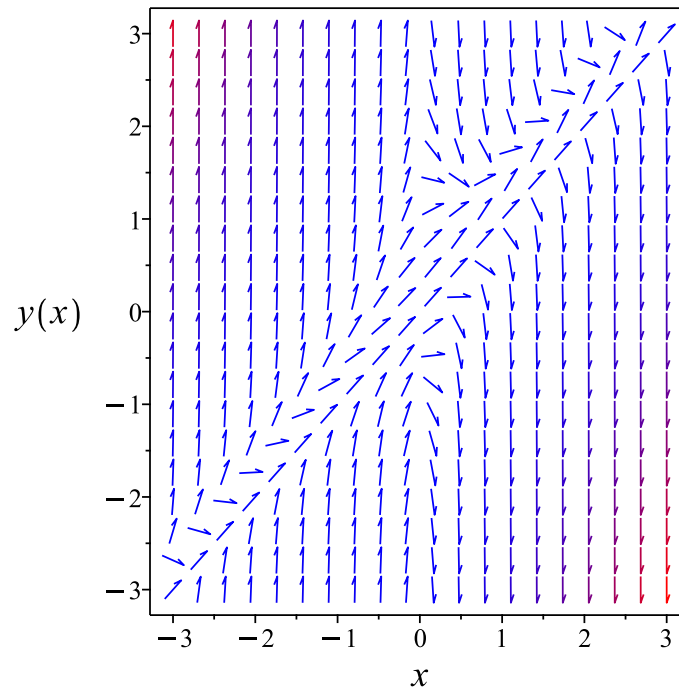


Figure 241: Slope field plot

Verification of solutions

$$y = \frac{x e^{-2x^2 + \frac{c_1}{2}} - 2x - 1}{e^{-2x^2 + \frac{c_1}{2}} - 2}$$

Verified OK.

5.37.2 Solving as riccati ode

In canonical form the ODE is

$$\begin{aligned} y' &= F(x, y) \\ &= -8x^3 + 16x^2y - 8xy^2 - 4x^2 + 4xy + 1 \end{aligned}$$

This is a Riccati ODE. Comparing the ODE to solve

$$y' = -8x^3 + 16x^2y - 8xy^2 - 4x^2 + 4xy + 1$$

With Riccati ODE standard form

$$y' = f_0(x) + f_1(x)y + f_2(x)y^2$$

Shows that $f_0(x) = -8x^3 - 4x^2 + 1$, $f_1(x) = 16x^2 + 4x$ and $f_2(x) = -8x$. Let

$$\begin{aligned} y &= \frac{-u'}{f_2 u} \\ &= \frac{-u'}{-8xu} \end{aligned} \quad (1)$$

Using the above substitution in the given ODE results (after some simplification) in a second order ODE to solve for $u(x)$ which is

$$f_2 u''(x) - (f_2' + f_1 f_2) u'(x) + f_2^2 f_0 u(x) = 0 \quad (2)$$

But

$$\begin{aligned} f_2' &= -8 \\ f_1 f_2 &= -8(16x^2 + 4x) x \\ f_2^2 f_0 &= 64x^2(-8x^3 - 4x^2 + 1) \end{aligned}$$

Substituting the above terms back in equation (2) gives

$$-8xu''(x) - (-8 - 8(16x^2 + 4x) x) u'(x) + 64x^2(-8x^3 - 4x^2 + 1) u(x) = 0$$

Solving the above ODE (this ode solved using Maple, not this program), gives

$$u(x) = c_1 e^{\frac{8x^3}{3}} + c_2 e^{\frac{8}{3}x^3 + 2x^2}$$

The above shows that

$$u'(x) = 8x \left(c_2 \left(x + \frac{1}{2} \right) e^{\frac{8}{3}x^3 + 2x^2} + e^{\frac{8x^3}{3}} c_1 x \right)$$

Using the above in (1) gives the solution

$$y = \frac{c_2 \left(x + \frac{1}{2} \right) e^{\frac{8}{3}x^3 + 2x^2} + e^{\frac{8x^3}{3}} c_1 x}{c_1 e^{\frac{8x^3}{3}} + c_2 e^{\frac{8}{3}x^3 + 2x^2}}$$

Dividing both numerator and denominator by c_1 gives, after renaming the constant $\frac{c_2}{c_1} = c_3$ the following solution

$$y = \frac{2 e^{\frac{8x^3}{3}} c_3 x + 2 e^{\frac{8}{3}x^3 + 2x^2} x + e^{\frac{8x^3}{3}} c_3}{2 c_3 e^{\frac{8x^3}{3}} + 2 e^{\frac{8}{3}x^3 + 2x^2}}$$

Summary

The solution(s) found are the following

$$y = \frac{2e^{\frac{8x^3}{3}}c_3x + 2e^{\frac{8}{3}x^3+2x^2}x + e^{\frac{8}{3}x^3+2x^2}}{2c_3e^{\frac{8x^3}{3}} + 2e^{\frac{8}{3}x^3+2x^2}} \quad (1)$$

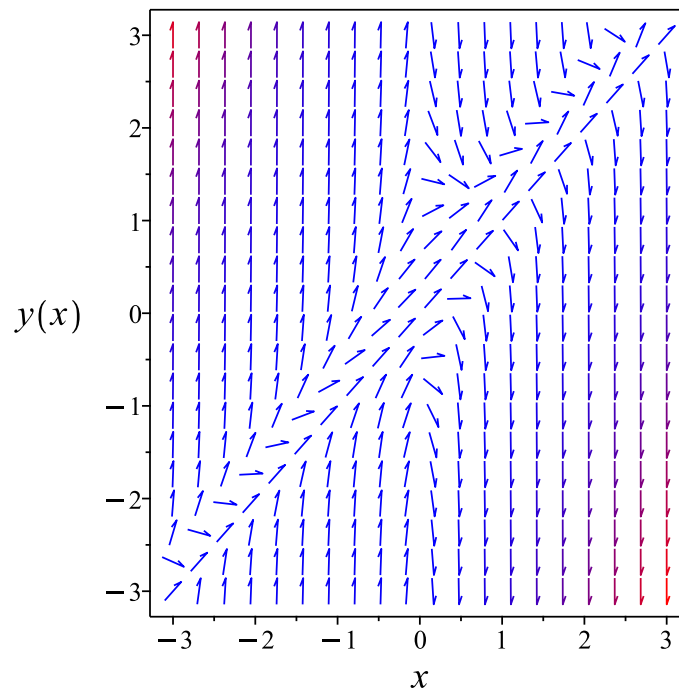


Figure 242: Slope field plot

Verification of solutions

$$y = \frac{2e^{\frac{8x^3}{3}}c_3x + 2e^{\frac{8}{3}x^3+2x^2}x + e^{\frac{8}{3}x^3+2x^2}}{2c_3e^{\frac{8x^3}{3}} + 2e^{\frac{8}{3}x^3+2x^2}}$$

Verified OK.

Maple trace Kovacic algorithm successful

```
`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
trying separable
trying inverse linear
trying homogeneous types:
trying Chini
differential order: 1; looking for linear symmetries
trying exact
Looking for potential symmetries
trying Riccati
trying Riccati sub-methods:
  trying Riccati to 2nd Order
  -> Calling odsolve with the ODE`, diff(diff(y(x), x), x) = (16*x^3+4*x^2+1)*(diff(y(x), x), x)
  Methods for second order ODEs:
  --- Trying classification methods ---
  trying a quadrature
  checking if the LODE has constant coefficients
  checking if the LODE is of Euler type
  trying a symmetry of the form [xi=0, eta=F(x)]
  checking if the LODE is missing y
  -> Trying a Liouvillian solution using Kovacics algorithm
  A Liouvillian solution exists
  Reducible group (found an exponential solution)
  Reducible group (found another exponential solution)
  <- Kovacics algorithm successful
  <- Riccati to 2nd Order successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 60

```
dsolve(diff(y(x),x)=-8*x*y(x)^2+4*x*(4*x+1)*y(x)-(8*x^3+4*x^2-1),y(x), singsol=all)
```

$$y(x) = \frac{c_1(2x+1)e^{\frac{8}{3}x^3+2x^2} + 2e^{\frac{8}{3}x^3}}{2c_1e^{\frac{8}{3}x^3+2x^2} + 2e^{\frac{8}{3}x^3}}$$

✓ Solution by Mathematica

Time used: 0.196 (sec). Leaf size: 30

```
DSolve[y'[x]==-8*x*y[x]^2+4*x*(4*x+1)*y[x]-(8*x^3+4*x^2-1),y[x],x,IncludeSingularSolutions
```

$$y(x) \rightarrow \frac{1}{4}(\tanh(x^2 + ic_1) + 4x + 1)$$

$$y(x) \rightarrow \text{Indeterminate}$$

6 Chapter 2, Miscellaneous Review. Exercises

page 60

6.1	problem 1	1253
6.2	problem 2	1268
6.3	problem 3	1282
6.4	problem 4	1296
6.5	problem 5	1309
6.6	problem 6	1318
6.7	problem 7	1333
6.8	problem 8	1347
6.9	problem 9	1359
6.10	problem 10	1372
6.11	problem 11	1385
6.12	problem 12	1394
6.13	problem 13	1409
6.14	problem 14	1423
6.15	problem 15	1437
6.16	problem 16	1454
6.17	problem 17	1470
6.18	problem 18	1485
6.19	problem 19	1491
6.20	problem 20	1507
6.21	problem 21	1516
6.22	problem 22	1533
6.23	problem 23	1545
6.24	problem 24	1558

6.1 problem 1

6.1.1	Solving as separable ode	1253
6.1.2	Solving as linear ode	1255
6.1.3	Solving as homogeneousTypeD2 ode	1256
6.1.4	Solving as first order ode lie symmetry lookup ode	1258
6.1.5	Solving as exact ode	1262
6.1.6	Maple step by step solution	1266

Internal problem ID [11675]

Internal file name [OUTPUT/11684_Wednesday_April_10_2024_04_54_38_PM_81155065/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, Miscellaneous Review. Exercises page 60

Problem number: 1.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact", "linear", "separable", "homogeneousTypeD2", "first_order_ode_lie_symmetry_lookup"

Maple gives the following as the ode type

[_separable]

$$6x^2y - (x^3 + 1)y' = 0$$

6.1.1 Solving as separable ode

In canonical form the ODE is

$$\begin{aligned}y' &= F(x, y) \\ &= f(x)g(y) \\ &= \frac{6x^2y}{x^3 + 1}\end{aligned}$$

Where $f(x) = \frac{6x^2}{x^3+1}$ and $g(y) = y$. Integrating both sides gives

$$\begin{aligned}\frac{1}{y} dy &= \frac{6x^2}{x^3+1} dx \\ \int \frac{1}{y} dy &= \int \frac{6x^2}{x^3+1} dx \\ \ln(y) &= 2 \ln(x^3+1) + c_1 \\ y &= e^{2 \ln(x^3+1) + c_1} \\ &= c_1(x^3+1)^2\end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1(x^3 + 1)^2 \tag{1}$$

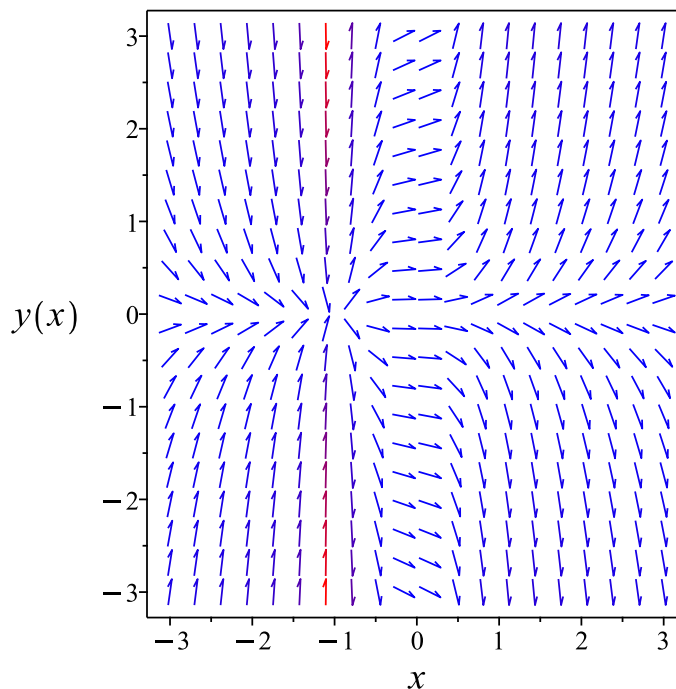


Figure 243: Slope field plot

Verification of solutions

$$y = c_1(x^3 + 1)^2$$

Verified OK.

6.1.2 Solving as linear ode

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = -\frac{6x^2}{x^3 + 1}$$

$$q(x) = 0$$

Hence the ode is

$$y' - \frac{6x^2y}{x^3 + 1} = 0$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int -\frac{6x^2}{x^3+1} dx} \\ &= \frac{1}{(x^3 + 1)^2}\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}\mu y &= 0 \\ \frac{d}{dx}\left(\frac{y}{(x^3 + 1)^2}\right) &= 0\end{aligned}$$

Integrating gives

$$\frac{y}{(x^3 + 1)^2} = c_1$$

Dividing both sides by the integrating factor $\mu = \frac{1}{(x^3+1)^2}$ results in

$$y = c_1(x^3 + 1)^2$$

Summary

The solution(s) found are the following

$$y = c_1(x^3 + 1)^2 \tag{1}$$

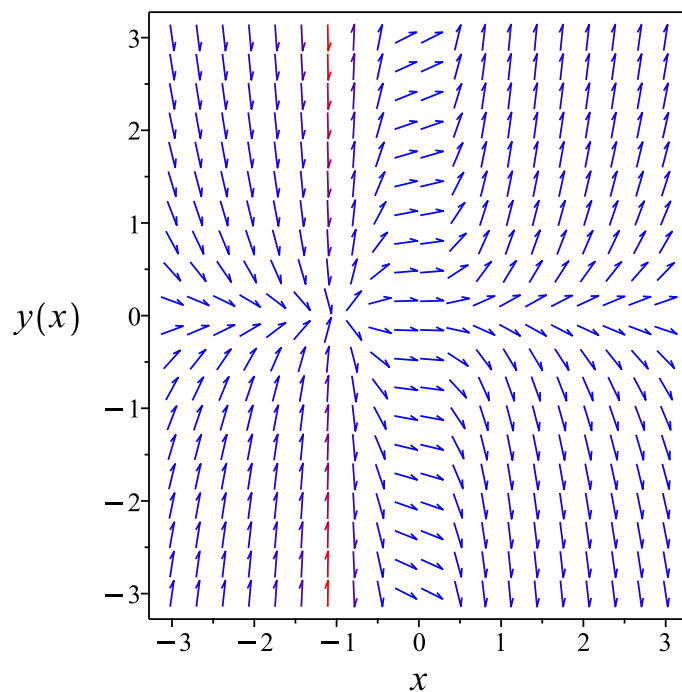


Figure 244: Slope field plot

Verification of solutions

$$y = c_1(x^3 + 1)^2$$

Verified OK.

6.1.3 Solving as homogeneousTypeD2 ode

Using the change of variables $y = u(x)x$ on the above ode results in new ode in $u(x)$

$$6x^3u(x) - (x^3 + 1)(u'(x)x + u(x)) = 0$$

In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= \frac{u(5x^3 - 1)}{x(x^3 + 1)} \end{aligned}$$

Where $f(x) = \frac{5x^3-1}{x(x^3+1)}$ and $g(u) = u$. Integrating both sides gives

$$\begin{aligned}\frac{1}{u} du &= \frac{5x^3 - 1}{x(x^3 + 1)} dx \\ \int \frac{1}{u} du &= \int \frac{5x^3 - 1}{x(x^3 + 1)} dx \\ \ln(u) &= 2 \ln(1+x) - \ln(x) + 2 \ln(x^2 - x + 1) + c_2 \\ u &= e^{2 \ln(1+x) - \ln(x) + 2 \ln(x^2 - x + 1) + c_2} \\ &= c_2 e^{2 \ln(1+x) - \ln(x) + 2 \ln(x^2 - x + 1)}\end{aligned}$$

Which simplifies to

$$u(x) = c_2 \left(x^5 + 2x^2 + \frac{1}{x} \right)$$

Therefore the solution y is

$$\begin{aligned}y &= xu \\ &= xc_2 \left(x^5 + 2x^2 + \frac{1}{x} \right)\end{aligned}$$

Summary

The solution(s) found are the following

$$y = xc_2 \left(x^5 + 2x^2 + \frac{1}{x} \right) \tag{1}$$

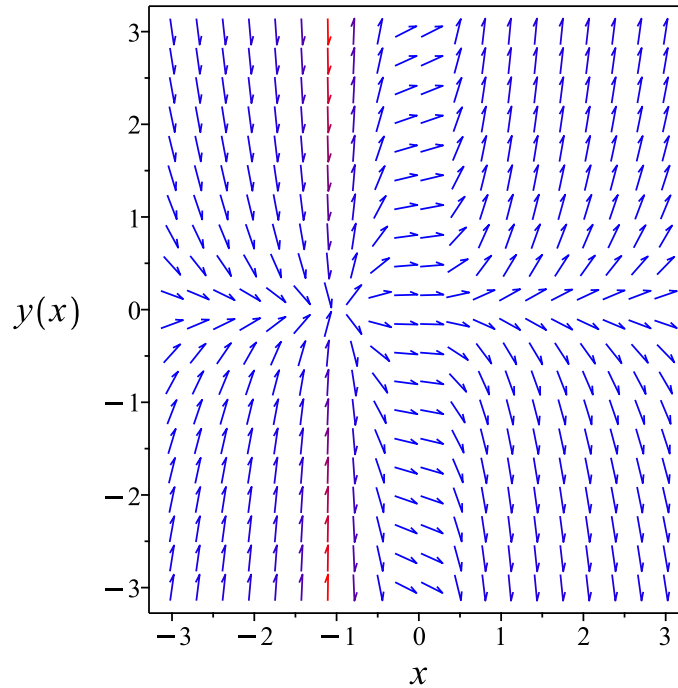


Figure 245: Slope field plot

Verification of solutions

$$y = xc_2 \left(x^5 + 2x^2 + \frac{1}{x} \right)$$

Verified OK.

6.1.4 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = \frac{6x^2y}{x^3 + 1}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \tag{A}$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 203: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int(n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= (x^3 + 1)^2\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{(x^3 + 1)^2} dy \end{aligned}$$

Which results in

$$S = \frac{y}{(x^3 + 1)^2}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = \frac{6x^2y}{x^3 + 1}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= -\frac{6y x^2}{(x^3 + 1)^3} \\ S_y &= \frac{1}{(x^3 + 1)^2} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 0 \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 0$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = c_1 \tag{4}$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$\frac{y}{(x^3 + 1)^2} = c_1$$

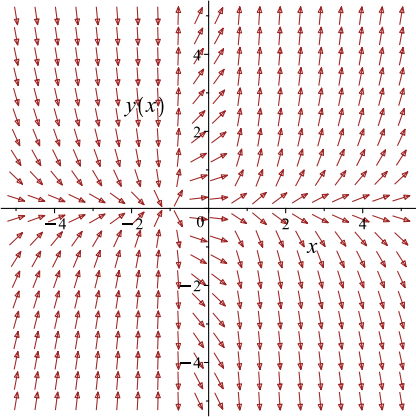
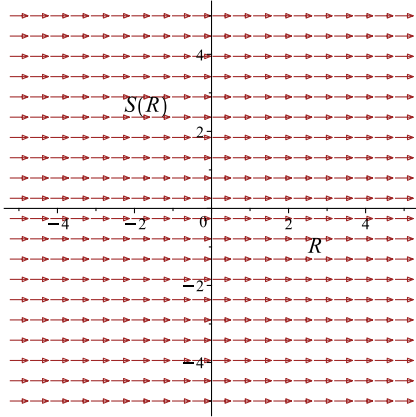
Which simplifies to

$$\frac{y}{(x^3 + 1)^2} = c_1$$

Which gives

$$y = c_1(x^3 + 1)^2$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = \frac{6x^2y}{x^3+1}$ 	$R = x$ $S = \frac{y}{(x^3 + 1)^2}$	$\frac{dS}{dR} = 0$ 

Summary

The solution(s) found are the following

$$y = c_1(x^3 + 1)^2 \tag{1}$$

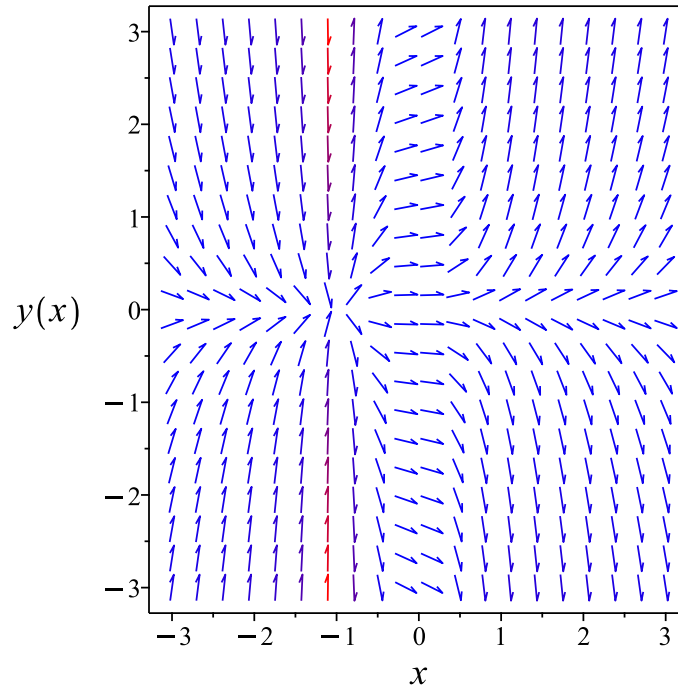


Figure 246: Slope field plot

Verification of solutions

$$y = c_1(x^3 + 1)^2$$

Verified OK.

6.1.5 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx}\phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (1A)$$

Therefore

$$\begin{aligned}\left(\frac{1}{6y}\right) dy &= \left(\frac{x^2}{x^3 + 1}\right) dx \\ \left(-\frac{x^2}{x^3 + 1}\right) dx + \left(\frac{1}{6y}\right) dy &= 0\end{aligned} \quad (2A)$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= -\frac{x^2}{x^3 + 1} \\ N(x, y) &= \frac{1}{6y}\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y} \left(-\frac{x^2}{x^3 + 1}\right) \\ &= 0\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x} \left(\frac{1}{6y} \right) \\ &= 0\end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \tag{1}$$

$$\frac{\partial \phi}{\partial y} = N \tag{2}$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int M dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int -\frac{x^2}{x^3 + 1} dx \\ \phi &= -\frac{\ln(x^3 + 1)}{3} + f(y)\end{aligned} \tag{3}$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = 0 + f'(y) \tag{4}$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = \frac{1}{6y}$. Therefore equation (4) becomes

$$\frac{1}{6y} = 0 + f'(y) \tag{5}$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = \frac{1}{6y}$$

Integrating the above w.r.t y gives

$$\int f'(y) dy = \int \left(\frac{1}{6y} \right) dy$$
$$f(y) = \frac{\ln(y)}{6} + c_1$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = -\frac{\ln(x^3 + 1)}{3} + \frac{\ln(y)}{6} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -\frac{\ln(x^3 + 1)}{3} + \frac{\ln(y)}{6}$$

The solution becomes

$$y = e^{6c_1} (x^3 + 1)^2$$

Summary

The solution(s) found are the following

$$y = e^{6c_1} (x^3 + 1)^2 \tag{1}$$

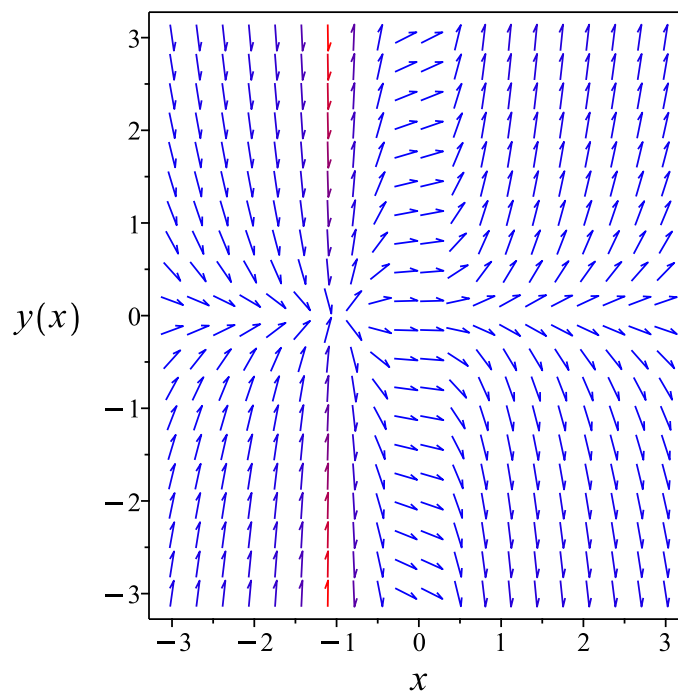


Figure 247: Slope field plot

Verification of solutions

$$y = e^{6c_1} (x^3 + 1)^2$$

Verified OK.

6.1.6 Maple step by step solution

Let's solve

$$6x^2y - (x^3 + 1)y' = 0$$

- Highest derivative means the order of the ODE is 1

y'

- Separate variables

$$\frac{y'}{y} = \frac{6x^2}{x^3+1}$$

- Integrate both sides with respect to x

$$\int \frac{y'}{y} dx = \int \frac{6x^2}{x^3+1} dx + c_1$$

- Evaluate integral

- $\ln(y) = 2 \ln(x^3 + 1) + c_1$
 • Solve for y
 $y = e^{c_1} (x^3 + 1)^2$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
<- 1st order linear successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 13

```
dsolve(6*x^2*y(x)-(x^3+1)*diff(y(x),x)=0,y(x), singsol=all)
```

$$y(x) = c_1(x^3 + 1)^2$$

✓ Solution by Mathematica

Time used: 0.031 (sec). Leaf size: 20

```
DSolve[6*x^2*y[x]-(x^3+1)*y'[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow c_1(x^3 + 1)^2$$

$$y(x) \rightarrow 0$$

6.2 problem 2

6.2.1	Solving as first order ode lie symmetry calculated ode	1268
6.2.2	Solving as exact ode	1274
6.2.3	Maple step by step solution	1277

Internal problem ID [11676]

Internal file name [OUTPUT/11685_Wednesday_April_10_2024_04_54_39_PM_80429987/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, Miscellaneous Review. Exercises page 60

Problem number: 2.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact", "first_order_ode_lie_symmetry_calculated"

Maple gives the following as the ode type

```
[[_homogeneous, `class G`], _exact, _rational]
```

$$(3x^2y^2 - x)y' + 2y^3x - y = 0$$

6.2.1 Solving as first order ode lie symmetry calculated ode

Writing the ode as

$$y' = -\frac{y(2xy^2 - 1)}{x(3xy^2 - 1)}$$
$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2\xi_y - \omega_x\xi - \omega_y\eta = 0 \tag{A}$$

The type of this ode is not in the lookup table. To determine ξ, η then (A) is solved using ansatz. Making bivariate polynomials of degree 1 to use as anstaz gives

$$\xi = xa_2 + ya_3 + a_1 \tag{1E}$$

$$\eta = xb_2 + yb_3 + b_1 \tag{2E}$$

Where the unknown coefficients are

$$\{a_1, a_2, a_3, b_1, b_2, b_3\}$$

Substituting equations (1E,2E) and ω into (A) gives

$$\begin{aligned} b_2 - \frac{y(2xy^2 - 1)(b_3 - a_2)}{x(3xy^2 - 1)} - \frac{y^2(2xy^2 - 1)^2 a_3}{x^2(3xy^2 - 1)^2} \\ - \left(-\frac{2y^3}{x(3xy^2 - 1)} + \frac{y(2xy^2 - 1)}{x^2(3xy^2 - 1)} + \frac{3y^3(2xy^2 - 1)}{x(3xy^2 - 1)^2} \right) (xa_2 + ya_3 + a_1) \quad (5E) \\ - \left(-\frac{2xy^2 - 1}{x(3xy^2 - 1)} - \frac{4y^2}{3xy^2 - 1} + \frac{6y^2(2xy^2 - 1)}{(3xy^2 - 1)^2} \right) (xb_2 + yb_3 + b_1) = 0 \end{aligned}$$

Putting the above in normal form gives

$$\frac{15x^4y^4b_2 - 10x^2y^6a_3 + 6x^3y^4b_1 - 6x^2y^5a_1 - 9x^3y^2b_2 + x^2y^3a_2 + 2x^2y^3b_3 + 10xy^4a_3 - 3x^2y^2b_1 + 6xy^3a_1}{x^2(3xy^2 - 1)^2} = 0$$

Setting the numerator to zero gives

$$\begin{aligned} 15x^4y^4b_2 - 10x^2y^6a_3 + 6x^3y^4b_1 - 6x^2y^5a_1 - 9x^3y^2b_2 + x^2y^3a_2 + 2x^2y^3b_3 \quad (6E) \\ + 10xy^4a_3 - 3x^2y^2b_1 + 6xy^3a_1 + 2b_2x^2 - 2y^2a_3 + xb_1 - ya_1 = 0 \end{aligned}$$

Looking at the above PDE shows the following are all the terms with $\{x, y\}$ in them.

$$\{x, y\}$$

The following substitution is now made to be able to collect on all terms with $\{x, y\}$ in them

$$\{x = v_1, y = v_2\}$$

The above PDE (6E) now becomes

$$\begin{aligned} -10a_3v_1^2v_2^6 + 15b_2v_1^4v_2^4 - 6a_1v_1^2v_2^5 + 6b_1v_1^3v_2^4 + a_2v_1^2v_2^3 + 10a_3v_1v_2^4 - 9b_2v_1^3v_2^2 \quad (7E) \\ + 2b_3v_1^2v_2^3 + 6a_1v_1v_2^3 - 3b_1v_1^2v_2^2 - 2a_3v_2^2 + 2b_2v_1^2 - a_1v_2 + b_1v_1 = 0 \end{aligned}$$

Collecting the above on the terms v_i introduced, and these are

$$\{v_1, v_2\}$$

Equation (7E) now becomes

$$15b_2v_1^4v_2^4 + 6b_1v_1^3v_2^4 - 9b_2v_1^3v_2^2 - 10a_3v_1^2v_2^6 - 6a_1v_1^2v_2^5 + (a_2 + 2b_3)v_1^2v_2^3 - 3b_1v_1^2v_2^2 + 2b_2v_1^2 + 10a_3v_1v_2^4 + 6a_1v_1v_2^3 + b_1v_1 - 2a_3v_2^2 - a_1v_2 = 0 \quad (8E)$$

Setting each coefficients in (8E) to zero gives the following equations to solve

$$\begin{aligned} b_1 &= 0 \\ -6a_1 &= 0 \\ -a_1 &= 0 \\ 6a_1 &= 0 \\ -10a_3 &= 0 \\ -2a_3 &= 0 \\ 10a_3 &= 0 \\ -3b_1 &= 0 \\ 6b_1 &= 0 \\ -9b_2 &= 0 \\ 2b_2 &= 0 \\ 15b_2 &= 0 \\ a_2 + 2b_3 &= 0 \end{aligned}$$

Solving the above equations for the unknowns gives

$$\begin{aligned} a_1 &= 0 \\ a_2 &= -2b_3 \\ a_3 &= 0 \\ b_1 &= 0 \\ b_2 &= 0 \\ b_3 &= b_3 \end{aligned}$$

Substituting the above solution in the anstaz (1E,2E) (using 1 as arbitrary value for any unknown in the RHS) gives

$$\begin{aligned} \xi &= -2x \\ \eta &= y \end{aligned}$$

Shifting is now applied to make $\xi = 0$ in order to simplify the rest of the computation

$$\begin{aligned}\eta &= \eta - \omega(x, y) \xi \\ &= y - \left(-\frac{y(2x y^2 - 1)}{x(3x y^2 - 1)} \right) (-2x) \\ &= \frac{-x y^3 + y}{3x y^2 - 1} \\ \xi &= 0\end{aligned}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \quad (1)$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y} \right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned}S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{-x y^3 + y}{3x y^2 - 1}} dy\end{aligned}$$

Which results in

$$S = -\ln(y(x y^2 - 1))$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y) S_y}{R_x + \omega(x, y) R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{y(2x y^2 - 1)}{x(3x y^2 - 1)}$$

Evaluating all the partial derivatives gives

$$\begin{aligned}R_x &= 1 \\R_y &= 0 \\S_x &= -\frac{y^2}{x y^2 - 1} \\S_y &= -\frac{1}{y} - \frac{2xy}{x y^2 - 1}\end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = \frac{1}{x} \tag{2A}$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = \frac{1}{R}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = \ln(R) + c_1 \tag{4}$$

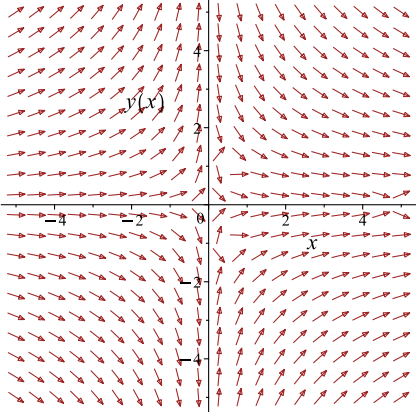
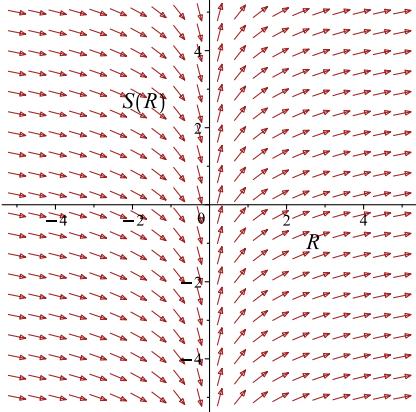
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$-\ln(y) - \ln(y^2x - 1) = \ln(x) + c_1$$

Which simplifies to

$$-\ln(y) - \ln(y^2x - 1) = \ln(x) + c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{y(2xy^2-1)}{x(3xy^2-1)}$ 	$R = x$ $S = -\ln(y) - \ln(xy^2 - 1)$	$\frac{dS}{dR} = \frac{1}{R}$ 

Summary

The solution(s) found are the following

$$-\ln(y) - \ln(y^2x - 1) = \ln(x) + c_1 \tag{1}$$

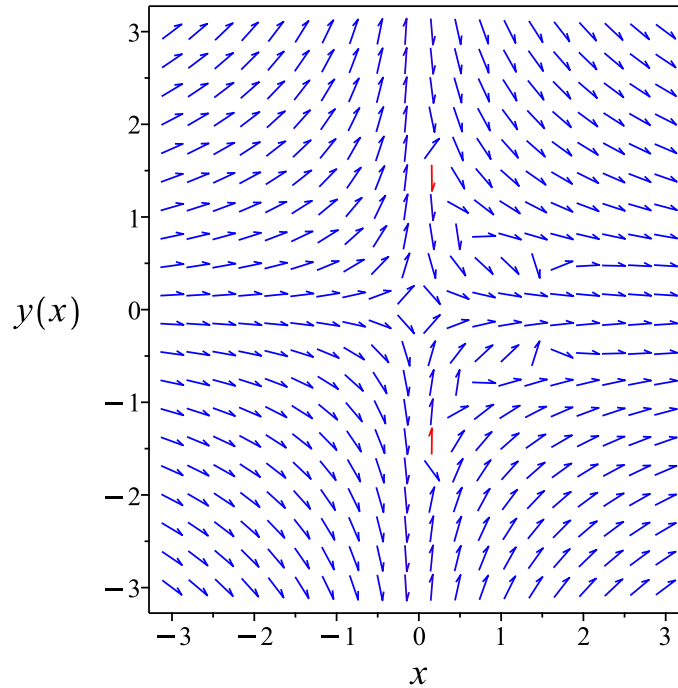


Figure 248: Slope field plot

Verification of solutions

$$-\ln(y) - \ln(y^2x - 1) = \ln(x) + c_1$$

Verified OK.

6.2.2 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx}\phi(x, y) = 0$$

Hence

$$\frac{\partial\phi}{\partial x} + \frac{\partial\phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (1A)$$

Therefore

$$\begin{aligned}(3x^2y^2 - x) dy &= (-2xy^3 + y) dx \\ (2xy^3 - y) dx + (3x^2y^2 - x) dy &= 0\end{aligned} \quad (2A)$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= 2xy^3 - y \\ N(x, y) &= 3x^2y^2 - x\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(2xy^3 - y) \\ &= 6xy^2 - 1\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(3x^2y^2 - x) \\ &= 6xy^2 - 1\end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \quad (1)$$

$$\frac{\partial \phi}{\partial y} = N \quad (2)$$

Integrating (1) w.r.t. x gives

$$\begin{aligned} \int \frac{\partial \phi}{\partial x} dx &= \int M dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int 2xy^3 - y dx \\ \phi &= xy(x y^2 - 1) + f(y) \end{aligned} \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\begin{aligned} \frac{\partial \phi}{\partial y} &= x(x y^2 - 1) + 2x^2 y^2 + f'(y) \\ &= 3x^2 y^2 - x + f'(y) \end{aligned} \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = 3x^2 y^2 - x$. Therefore equation (4) becomes

$$3x^2 y^2 - x = 3x^2 y^2 - x + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 0$$

Therefore

$$f(y) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(y)$ into equation (3) gives ϕ

$$\phi = xy(x y^2 - 1) + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = xy(x y^2 - 1)$$

Summary

The solution(s) found are the following

$$y(y^2x - 1)x = c_1 \quad (1)$$

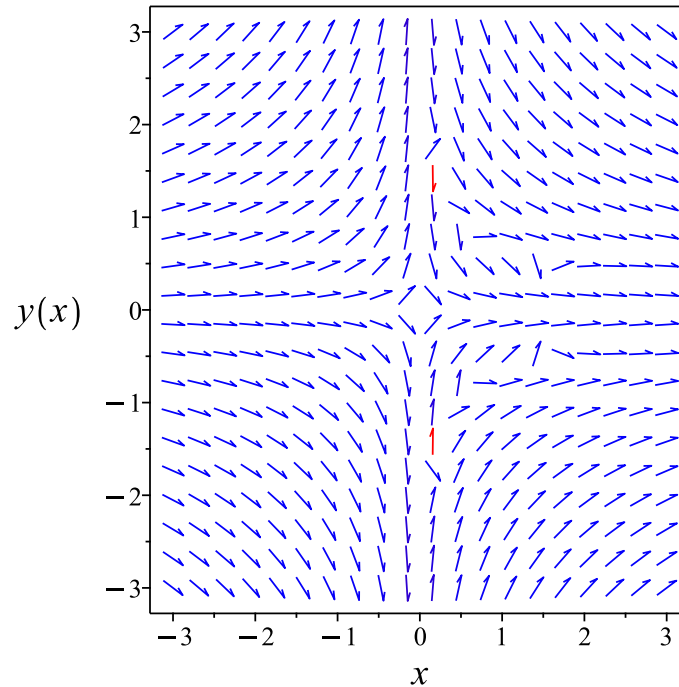


Figure 249: Slope field plot

Verification of solutions

$$y(y^2x - 1)x = c_1$$

Verified OK.

6.2.3 Maple step by step solution

Let's solve

$$(3x^2y^2 - x)y' + 2y^3x - y = 0$$

- Highest derivative means the order of the ODE is 1
- y'
- Check if ODE is exact
 - ODE is exact if the lhs is the total derivative of a C^2 function

$$F'(x, y) = 0$$

- Compute derivative of lhs

$$F'(x, y) + \left(\frac{\partial}{\partial y} F(x, y) \right) y' = 0$$

- Evaluate derivatives

$$6x y^2 - 1 = 6x y^2 - 1$$

- Condition met, ODE is exact

- Exact ODE implies solution will be of this form

$$\left[F(x, y) = c_1, M(x, y) = F'(x, y), N(x, y) = \frac{\partial}{\partial y} F(x, y) \right]$$

- Solve for $F(x, y)$ by integrating $M(x, y)$ with respect to x

$$F(x, y) = \int (2x y^3 - y) dx + f_1(y)$$

- Evaluate integral

$$F(x, y) = y(x^2 y^2 - x) + f_1(y)$$

- Take derivative of $F(x, y)$ with respect to y

$$N(x, y) = \frac{\partial}{\partial y} F(x, y)$$

- Compute derivative

$$3x^2 y^2 - x = 3x^2 y^2 - x + \frac{d}{dy} f_1(y)$$

- Isolate for $\frac{d}{dy} f_1(y)$

$$\frac{d}{dy} f_1(y) = 0$$

- Solve for $f_1(y)$

$$f_1(y) = 0$$

- Substitute $f_1(y)$ into equation for $F(x, y)$

$$F(x, y) = y(x^2 y^2 - x)$$

- Substitute $F(x, y)$ into the solution of the ODE

$$y(x^2 y^2 - x) = c_1$$

- Solve for y

$$\left\{ \begin{array}{l} y = \frac{\left(\left(12\sqrt{3} \sqrt{27c_1^2 - 4x + 108c_1} \right) x \right)^{\frac{1}{3}}}{6x} + \frac{2}{\left(\left(12\sqrt{3} \sqrt{27c_1^2 - 4x + 108c_1} \right) x \right)^{\frac{1}{3}}}, y = -\frac{\left(\left(12\sqrt{3} \sqrt{27c_1^2 - 4x + 108c_1} \right) x \right)^{\frac{1}{3}}}{12x} \end{array} \right.$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
trying separable
trying inverse linear
trying homogeneous types:
trying homogeneous G
<- homogeneous successful`

```


✓ Solution by Maple

Time used: 0.078 (sec). Leaf size: 1127

`dsolve((3*x^2*y(x)^2-x)*diff(y(x),x)+(2*x*y(x)^3-y(x))=0,y(x), singsol=all)`

$y(x) =$

$$\frac{\sqrt{3}\sqrt{2}\sqrt{\left(\left(3\sqrt{3}\sqrt{27c_1^2-4c_1x+27c_1-2x}\right)x^2\right)^{\frac{1}{3}}\left(2x^22^{\frac{1}{3}}+2^{\frac{2}{3}}\left(\left(3\sqrt{3}\sqrt{27c_1^2-4c_1x+27c_1-2x}\right)x^2\right)^{\frac{1}{3}}\right)}}{6\left(\left(3\sqrt{3}\sqrt{27c_1^2-4c_1x+27c_1-2x}\right)x^2\right)^{\frac{1}{3}}x}$$

$y(x)$

$$= \frac{\sqrt{3}\sqrt{2}\sqrt{\left(\left(3\sqrt{3}\sqrt{27c_1^2-4c_1x+27c_1-2x}\right)x^2\right)^{\frac{1}{3}}\left(2x^22^{\frac{1}{3}}+2^{\frac{2}{3}}\left(\left(3\sqrt{3}\sqrt{27c_1^2-4c_1x+27c_1-2x}\right)x^2\right)^{\frac{1}{3}}\right)}}{6\left(\left(3\sqrt{3}\sqrt{27c_1^2-4c_1x+27c_1-2x}\right)x^2\right)^{\frac{1}{3}}x}$$

$y(x) =$

$$\frac{\sqrt{3}\sqrt{\left(i\left(-2x^22^{\frac{1}{3}}+2^{\frac{2}{3}}\left(\left(3\sqrt{3}\sqrt{27c_1^2-4c_1x+27c_1-2x}\right)x^4\right)^{\frac{1}{3}}\right)\sqrt{3}-2x^22^{\frac{1}{3}}+8x\left(\left(3\sqrt{3}\sqrt{27c_1^2-4c_1x+27c_1-2x}\right)x^2\right)^{\frac{1}{3}}\right)}}{6\left(\left(3\sqrt{3}\sqrt{27c_1^2-4c_1x+27c_1-2x}\right)x^2\right)^{\frac{1}{3}}x}$$

$y(x)$

$$= \frac{\sqrt{3}\sqrt{\left(i\left(-2x^22^{\frac{1}{3}}+2^{\frac{2}{3}}\left(\left(3\sqrt{3}\sqrt{27c_1^2-4c_1x+27c_1-2x}\right)x^4\right)^{\frac{1}{3}}\right)\sqrt{3}-2x^22^{\frac{1}{3}}+8x\left(\left(3\sqrt{3}\sqrt{27c_1^2-4c_1x+27c_1-2x}\right)x^2\right)^{\frac{1}{3}}\right)}}{6\left(\left(3\sqrt{3}\sqrt{27c_1^2-4c_1x+27c_1-2x}\right)x^2\right)^{\frac{1}{3}}x}$$

$y(x) =$

$$\frac{\sqrt{3}\sqrt{\left(-i\left(-2x^22^{\frac{1}{3}}+2^{\frac{2}{3}}\left(\left(3\sqrt{3}\sqrt{27c_1^2-4c_1x+27c_1-2x}\right)x^4\right)^{\frac{1}{3}}\right)\sqrt{3}-2x^22^{\frac{1}{3}}+8x\left(\left(3\sqrt{3}\sqrt{27c_1^2-4c_1x+27c_1-2x}\right)x^2\right)^{\frac{1}{3}}\right)}}{6\left(\left(3\sqrt{3}\sqrt{27c_1^2-4c_1x+27c_1-2x}\right)x^2\right)^{\frac{1}{3}}x}$$

$y(x)$

$$= \frac{\sqrt{3}\sqrt{\left(-i\left(-2x^22^{\frac{1}{3}}+2^{\frac{2}{3}}\left(\left(3\sqrt{3}\sqrt{27c_1^2-4c_1x+27c_1-2x}\right)x^4\right)^{\frac{1}{3}}\right)\sqrt{3}-2x^22^{\frac{1}{3}}+8x\left(\left(3\sqrt{3}\sqrt{27c_1^2-4c_1x+27c_1-2x}\right)x^2\right)^{\frac{1}{3}}\right)}}{6\left(\left(3\sqrt{3}\sqrt{27c_1^2-4c_1x+27c_1-2x}\right)x^2\right)^{\frac{1}{3}}x}$$

✓ Solution by Mathematica

Time used: 30.566 (sec). Leaf size: 356

```
DSolve[(3*x^2*y[x]^2-x)*y'[x]+(2*x*y[x]^3-y[x])==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{2\sqrt[3]{3}x^3 + \sqrt[3]{2}\left(\sqrt{3}\sqrt{x^8(-4x+27c_1^2)} + 9c_1x^4\right)^{2/3}}{6^{2/3}x^2\sqrt[3]{\sqrt{3}\sqrt{x^8(-4x+27c_1^2)} + 9c_1x^4}}$$

$$y(x) \rightarrow \frac{i\sqrt[3]{3}(\sqrt{3}+i)\left(2\sqrt{3}\sqrt{x^8(-4x+27c_1^2)} + 18c_1x^4\right)^{2/3} - 2\sqrt[3]{2}\sqrt[6]{3}(\sqrt{3}+3i)x^3}{12x^2\sqrt[3]{\sqrt{3}\sqrt{x^8(-4x+27c_1^2)} + 9c_1x^4}}$$

$$y(x) \rightarrow \frac{\sqrt[3]{3}(-1-i\sqrt{3})\left(2\sqrt{3}\sqrt{x^8(-4x+27c_1^2)} + 18c_1x^4\right)^{2/3} - 2\sqrt[3]{2}\sqrt[6]{3}(\sqrt{3}-3i)x^3}{12x^2\sqrt[3]{\sqrt{3}\sqrt{x^8(-4x+27c_1^2)} + 9c_1x^4}}$$

6.3 problem 3

6.3.1	Solving as separable ode	1282
6.3.2	Solving as linear ode	1284
6.3.3	Solving as first order ode lie symmetry lookup ode	1286
6.3.4	Solving as exact ode	1290
6.3.5	Maple step by step solution	1294

Internal problem ID [11677]

Internal file name [OUTPUT/11686_Wednesday_April_10_2024_04_54_41_PM_24706420/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, Miscellaneous Review. Exercises page 60

Problem number: 3.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact", "linear", "separable", "first_order_ode_lie_symmetry_lookup"

Maple gives the following as the ode type

[_separable]

$$y + x(1 + x)y' = 1$$

6.3.1 Solving as separable ode

In canonical form the ODE is

$$\begin{aligned}y' &= F(x, y) \\ &= f(x)g(y) \\ &= \frac{1 - y}{x(1 + x)}\end{aligned}$$

Where $f(x) = \frac{1}{x(1+x)}$ and $g(y) = 1 - y$. Integrating both sides gives

$$\frac{1}{1 - y} dy = \frac{1}{x(1 + x)} dx$$

$$\int \frac{1}{1-y} dy = \int \frac{1}{x(1+x)} dx$$

$$-\ln(y-1) = -\ln(1+x) + \ln(x) + c_1$$

Raising both side to exponential gives

$$\frac{1}{y-1} = e^{-\ln(1+x)+\ln(x)+c_1}$$

Which simplifies to

$$\frac{1}{y-1} = c_2 e^{-\ln(1+x)+\ln(x)}$$

Which simplifies to

$$y = \frac{\left(\frac{c_2 e^{c_1} x}{1+x} + 1\right) (1+x) e^{-c_1}}{c_2 x}$$

Summary

The solution(s) found are the following

$$y = \frac{\left(\frac{c_2 e^{c_1} x}{1+x} + 1\right) (1+x) e^{-c_1}}{c_2 x} \tag{1}$$

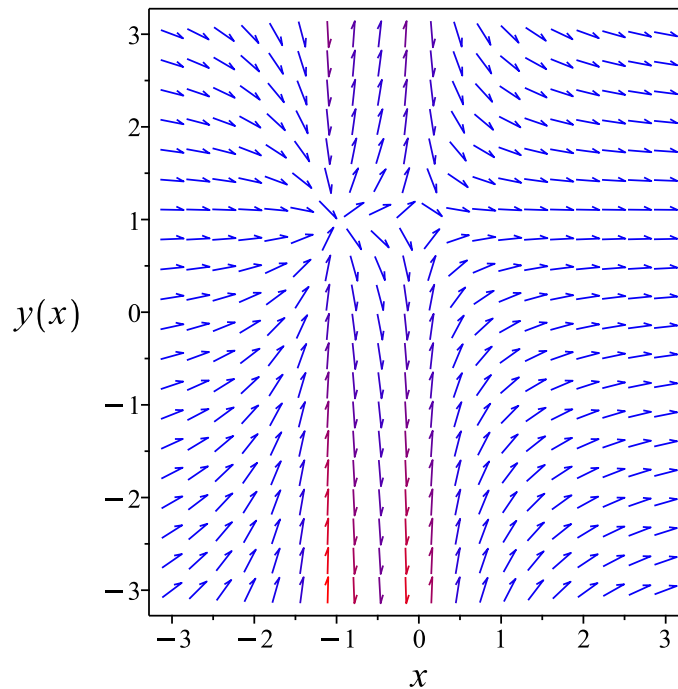


Figure 250: Slope field plot

Verification of solutions

$$y = \frac{\left(\frac{c_2 e^{c_1 x}}{1+x} + 1\right)(1+x)e^{-c_1}}{c_2 x}$$

Verified OK.

6.3.2 Solving as linear ode

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = \frac{1}{x(1+x)}$$
$$q(x) = \frac{1}{x(1+x)}$$

Hence the ode is

$$y' + \frac{y}{x(1+x)} = \frac{1}{x(1+x)}$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int \frac{1}{x(1+x)} dx} \\ &= e^{-\ln(1+x) + \ln(x)}\end{aligned}$$

Which simplifies to

$$\mu = \frac{x}{1+x}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu y) &= (\mu) \left(\frac{1}{x(1+x)}\right) \\ \frac{d}{dx} \left(\frac{xy}{1+x}\right) &= \left(\frac{x}{1+x}\right) \left(\frac{1}{x(1+x)}\right) \\ d\left(\frac{xy}{1+x}\right) &= \frac{1}{(1+x)^2} dx\end{aligned}$$

Integrating gives

$$\begin{aligned}\frac{xy}{1+x} &= \int \frac{1}{(1+x)^2} dx \\ \frac{xy}{1+x} &= -\frac{1}{1+x} + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = \frac{x}{1+x}$ results in

$$y = -\frac{1}{x} + \frac{c_1(1+x)}{x}$$

which simplifies to

$$y = \frac{c_1x + c_1 - 1}{x}$$

Summary

The solution(s) found are the following

$$y = \frac{c_1x + c_1 - 1}{x} \tag{1}$$

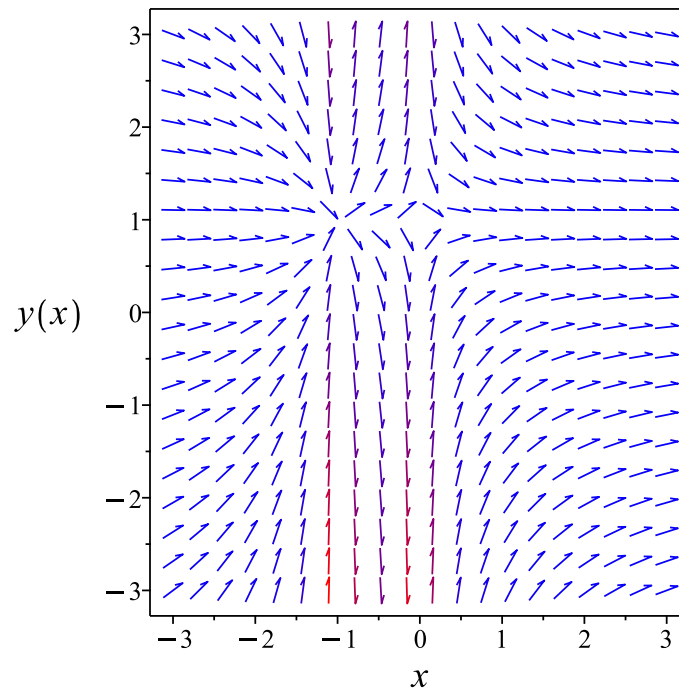


Figure 251: Slope field plot

Verification of solutions

$$y = \frac{c_1x + c_1 - 1}{x}$$

Verified OK.

6.3.3 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = -\frac{y-1}{x(1+x)}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 207: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= e^{\ln(1+x) - \ln(x)}\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned}S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{e^{\ln(1+x) - \ln(x)}} dy\end{aligned}$$

Which results in

$$S = \frac{xy}{1+x}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y}\tag{2}$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{y-1}{x(1+x)}$$

Evaluating all the partial derivatives gives

$$\begin{aligned}R_x &= 1 \\R_y &= 0 \\S_x &= \frac{y}{(1+x)^2} \\S_y &= \frac{x}{1+x}\end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = \frac{1}{(1+x)^2} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = \frac{1}{(1+R)^2}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = -\frac{1}{1+R} + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$\frac{xy}{1+x} = -\frac{1}{1+x} + c_1$$

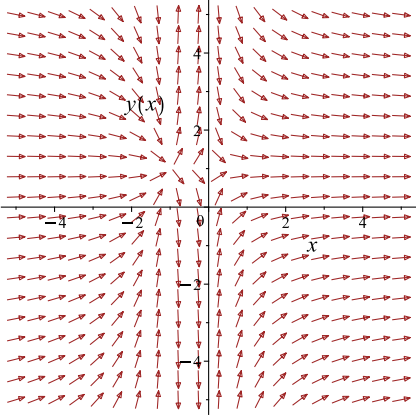
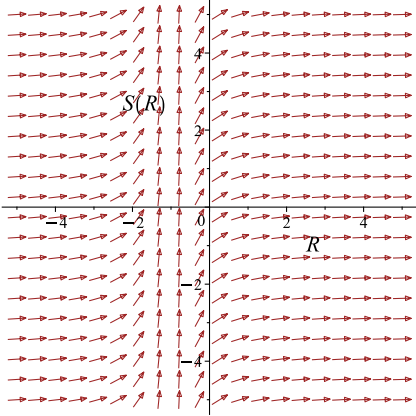
Which simplifies to

$$\frac{xy}{1+x} = -\frac{1}{1+x} + c_1$$

Which gives

$$y = \frac{c_1x + c_1 - 1}{x}$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{y-1}{x(1+x)}$ 	$R = x$ $S = \frac{xy}{1+x}$	$\frac{dS}{dR} = \frac{1}{(1+R)^2}$ 

Summary

The solution(s) found are the following

$$y = \frac{c_1 x + c_1 - 1}{x} \tag{1}$$

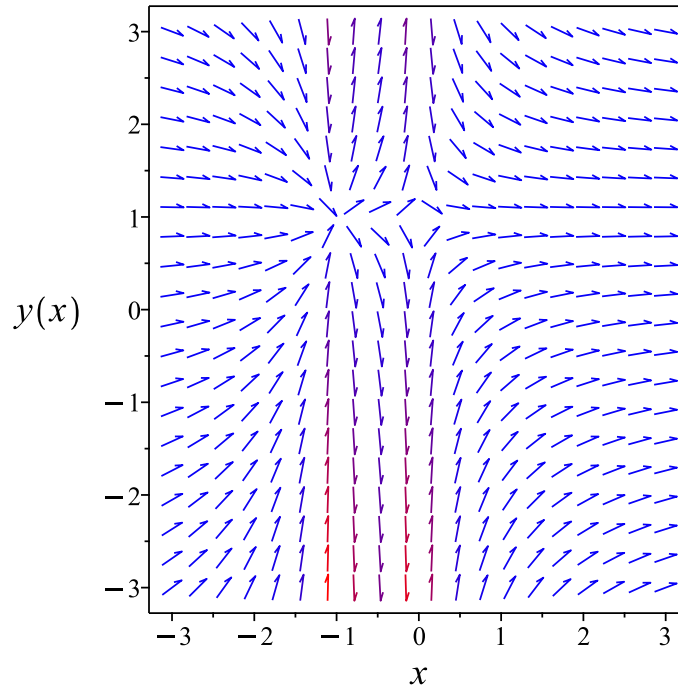


Figure 252: Slope field plot

Verification of solutions

$$y = \frac{c_1 x + c_1 - 1}{x}$$

Verified OK.

6.3.4 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (1A)$$

Therefore

$$\begin{aligned}\left(\frac{1}{1-y}\right) dy &= \left(\frac{1}{x(1+x)}\right) dx \\ \left(-\frac{1}{x(1+x)}\right) dx + \left(\frac{1}{1-y}\right) dy &= 0\end{aligned} \quad (2A)$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= -\frac{1}{x(1+x)} \\ N(x, y) &= \frac{1}{1-y}\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y} \left(-\frac{1}{x(1+x)}\right) \\ &= 0\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x} \left(\frac{1}{1-y} \right) \\ &= 0\end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \quad (1)$$

$$\frac{\partial \phi}{\partial y} = N \quad (2)$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int M dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int -\frac{1}{x(1+x)} dx \\ \phi &= \ln(1+x) - \ln(x) + f(y)\end{aligned} \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = 0 + f'(y) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = \frac{1}{1-y}$. Therefore equation (4) becomes

$$\frac{1}{1-y} = 0 + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = -\frac{1}{y-1}$$

Integrating the above w.r.t y gives

$$\begin{aligned}\int f'(y) dy &= \int \left(-\frac{1}{y-1} \right) dy \\ f(y) &= -\ln(y-1) + c_1\end{aligned}$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = \ln(1+x) - \ln(x) - \ln(y-1) + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = \ln(1+x) - \ln(x) - \ln(y-1)$$

The solution becomes

$$y = \frac{(e^{c_1}x + x + 1)e^{-c_1}}{x}$$

Summary

The solution(s) found are the following

$$y = \frac{(e^{c_1}x + x + 1)e^{-c_1}}{x} \tag{1}$$

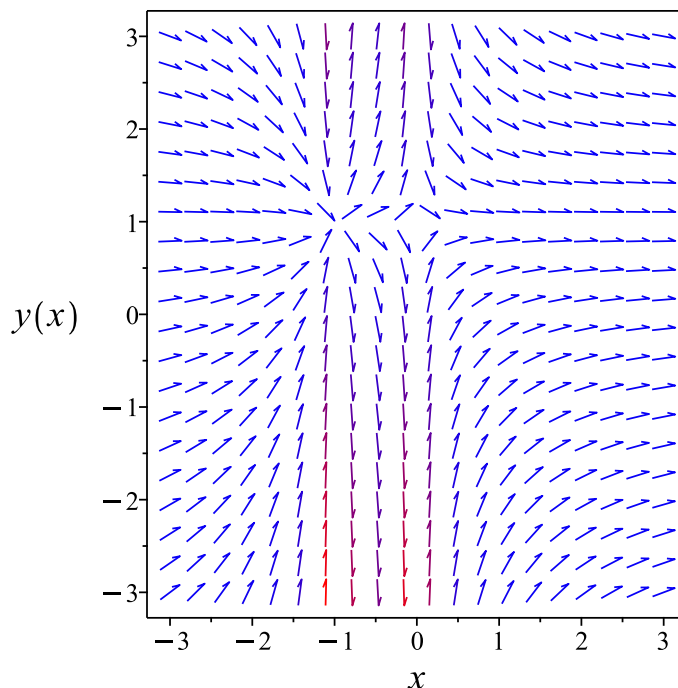


Figure 253: Slope field plot

Verification of solutions

$$y = \frac{(e^{c_1}x + x + 1)e^{-c_1}}{x}$$

Verified OK.

6.3.5 Maple step by step solution

Let's solve

$$y + x(1+x)y' = 1$$

- Highest derivative means the order of the ODE is 1

$$y'$$

- Separate variables

$$\frac{y'}{1-y} = \frac{1}{x(1+x)}$$

- Integrate both sides with respect to x

$$\int \frac{y'}{1-y} dx = \int \frac{1}{x(1+x)} dx + c_1$$

- Evaluate integral

$$-\ln(1-y) = -\ln(1+x) + \ln(x) + c_1$$

- Solve for y

$$y = \frac{e^{c_1}x - x - 1}{e^{c_1}x}$$

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
<- 1st order linear successful`
```

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 14

```
dsolve((y(x)-1)+(x*(x+1))*diff(y(x),x)=0,y(x), singsol=all)
```

$$y(x) = \frac{c_1x + c_1 - 1}{x}$$

✓ Solution by Mathematica

Time used: 0.03 (sec). Leaf size: 22

```
DSolve[(y[x]-1)+(x*(x+1))*y'[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{-1 + c_1(x + 1)}{x}$$

$$y(x) \rightarrow 1$$

6.4 problem 4

6.4.1	Solving as linear ode	1296
6.4.2	Solving as first order ode lie symmetry lookup ode	1298
6.4.3	Solving as exact ode	1302
6.4.4	Maple step by step solution	1307

Internal problem ID [11678]

Internal file name [OUTPUT/11687_Wednesday_April_10_2024_04_54_41_PM_36212687/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, Miscellaneous Review. Exercises page 60

Problem number: 4.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"linear"**, **"exactWithIntegrationFactor"**, **"first_order_ode_lie_symmetry_lookup"**

Maple gives the following as the ode type

`[_linear]`

$$-2y + y'x = -x^2$$

6.4.1 Solving as linear ode

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = -\frac{2}{x}$$

$$q(x) = -x$$

Hence the ode is

$$y' - \frac{2y}{x} = -x$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int -\frac{2}{x} dx} \\ &= \frac{1}{x^2}\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu y) &= (\mu)(-x) \\ \frac{d}{dx}\left(\frac{y}{x^2}\right) &= \left(\frac{1}{x^2}\right)(-x) \\ d\left(\frac{y}{x^2}\right) &= \left(-\frac{1}{x}\right) dx\end{aligned}$$

Integrating gives

$$\begin{aligned}\frac{y}{x^2} &= \int -\frac{1}{x} dx \\ \frac{y}{x^2} &= -\ln(x) + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = \frac{1}{x^2}$ results in

$$y = -x^2 \ln(x) + c_1 x^2$$

which simplifies to

$$y = x^2(-\ln(x) + c_1)$$

Summary

The solution(s) found are the following

$$y = x^2(-\ln(x) + c_1) \tag{1}$$

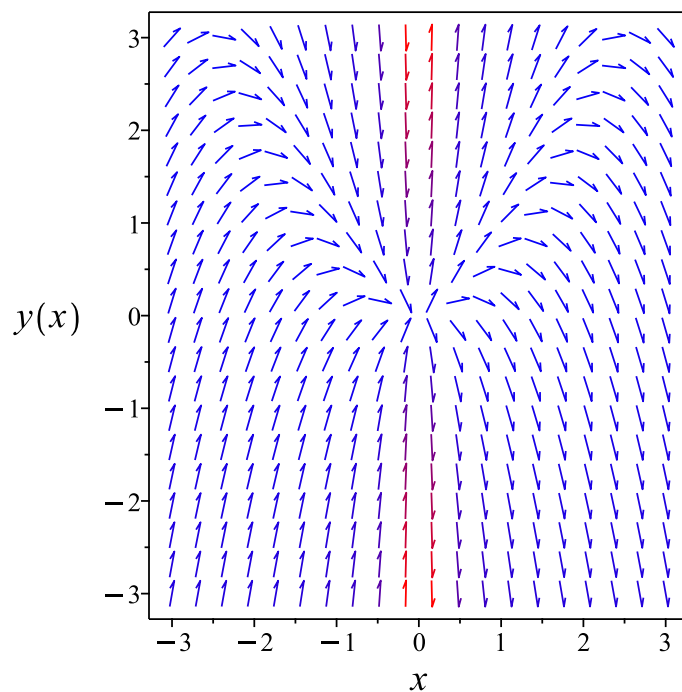


Figure 254: Slope field plot

Verification of solutions

$$y = x^2(-\ln(x) + c_1)$$

Verified OK.

6.4.2 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = \frac{-x^2 + 2y}{x}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 210: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int(n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= x^2\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{x^2} dy \end{aligned}$$

Which results in

$$S = \frac{y}{x^2}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = \frac{-x^2 + 2y}{x}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= -\frac{2y}{x^3} \\ S_y &= \frac{1}{x^2} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = -\frac{1}{x} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = -\frac{1}{R}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = -\ln(R) + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$\frac{y}{x^2} = -\ln(x) + c_1$$

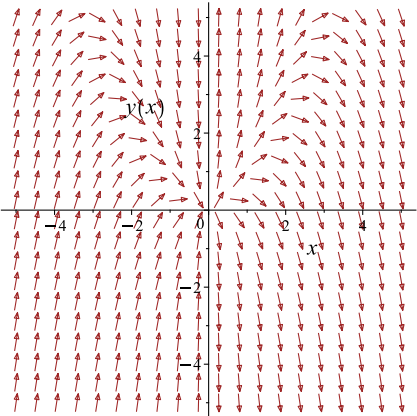
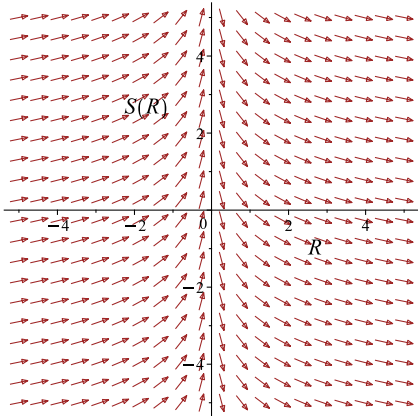
Which simplifies to

$$\frac{y}{x^2} = -\ln(x) + c_1$$

Which gives

$$y = -x^2(\ln(x) - c_1)$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = \frac{-x^2 + 2y}{x}$ 	$R = x$ $S = \frac{y}{x^2}$	$\frac{dS}{dR} = -\frac{1}{R}$ 

Summary

The solution(s) found are the following

$$y = -x^2(\ln(x) - c_1) \quad (1)$$

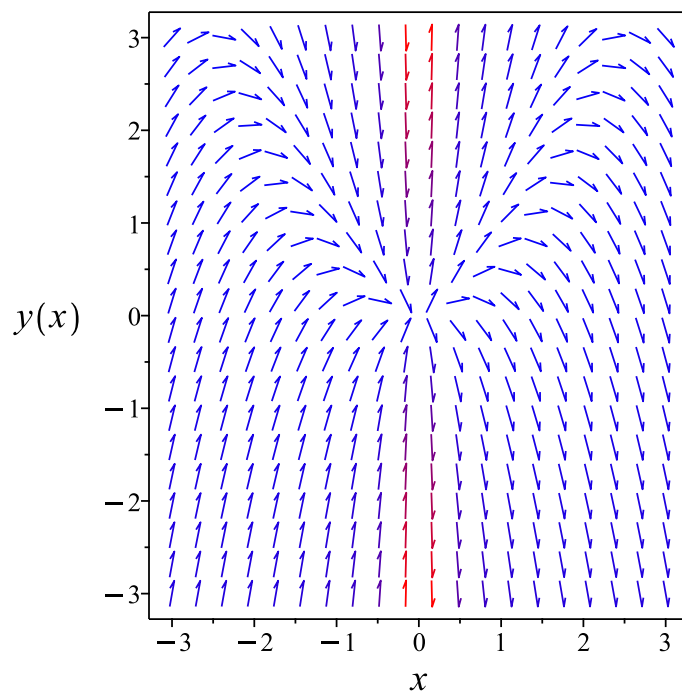


Figure 255: Slope field plot

Verification of solutions

$$y = -x^2(\ln(x) - c_1)$$

Verified OK.

6.4.3 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx}\phi(x, y) = 0$$

Hence

$$\frac{\partial\phi}{\partial x} + \frac{\partial\phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial\phi}{\partial x} &= M \\ \frac{\partial\phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \tag{1A}$$

Therefore

$$\begin{aligned}(x) dy &= (-x^2 + 2y) dx \\ (x^2 - 2y) dx + (x) dy &= 0\end{aligned} \tag{2A}$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= x^2 - 2y \\ N(x, y) &= x\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(x^2 - 2y) \\ &= -2\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(x) \\ &= 1\end{aligned}$$

Since $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$\begin{aligned} A &= \frac{1}{N} \left(\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} \right) \\ &= \frac{1}{x} ((-2) - (1)) \\ &= -\frac{3}{x} \end{aligned}$$

Since A does not depend on y , then it can be used to find an integrating factor. The integrating factor μ is

$$\begin{aligned} \mu &= e^{\int A \, dx} \\ &= e^{\int -\frac{3}{x} \, dx} \end{aligned}$$

The result of integrating gives

$$\begin{aligned} \mu &= e^{-3 \ln(x)} \\ &= \frac{1}{x^3} \end{aligned}$$

M and N are multiplied by this integrating factor, giving new M and new N which are called \bar{M} and \bar{N} for now so not to confuse them with the original M and N .

$$\begin{aligned} \bar{M} &= \mu M \\ &= \frac{1}{x^3} (x^2 - 2y) \\ &= \frac{x^2 - 2y}{x^3} \end{aligned}$$

And

$$\begin{aligned} \bar{N} &= \mu N \\ &= \frac{1}{x^3} (x) \\ &= \frac{1}{x^2} \end{aligned}$$

Now a modified ODE is obtained from the original ODE, which is exact and can be solved. The modified ODE is

$$\begin{aligned} \bar{M} + \bar{N} \frac{dy}{dx} &= 0 \\ \left(\frac{x^2 - 2y}{x^3} \right) + \left(\frac{1}{x^2} \right) \frac{dy}{dx} &= 0 \end{aligned}$$

The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = \bar{M} \quad (1)$$

$$\frac{\partial \phi}{\partial y} = \bar{N} \quad (2)$$

Integrating (1) w.r.t. x gives

$$\begin{aligned} \int \frac{\partial \phi}{\partial x} dx &= \int \bar{M} dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int \frac{x^2 - 2y}{x^3} dx \\ \phi &= \frac{y}{x^2} + \ln(x) + f(y) \end{aligned} \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = \frac{1}{x^2} + f'(y) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = \frac{1}{x^2}$. Therefore equation (4) becomes

$$\frac{1}{x^2} = \frac{1}{x^2} + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 0$$

Therefore

$$f(y) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(y)$ into equation (3) gives ϕ

$$\phi = \frac{y}{x^2} + \ln(x) + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = \frac{y}{x^2} + \ln(x)$$

The solution becomes

$$y = -x^2(\ln(x) - c_1)$$

Summary

The solution(s) found are the following

$$y = -x^2(\ln(x) - c_1) \tag{1}$$

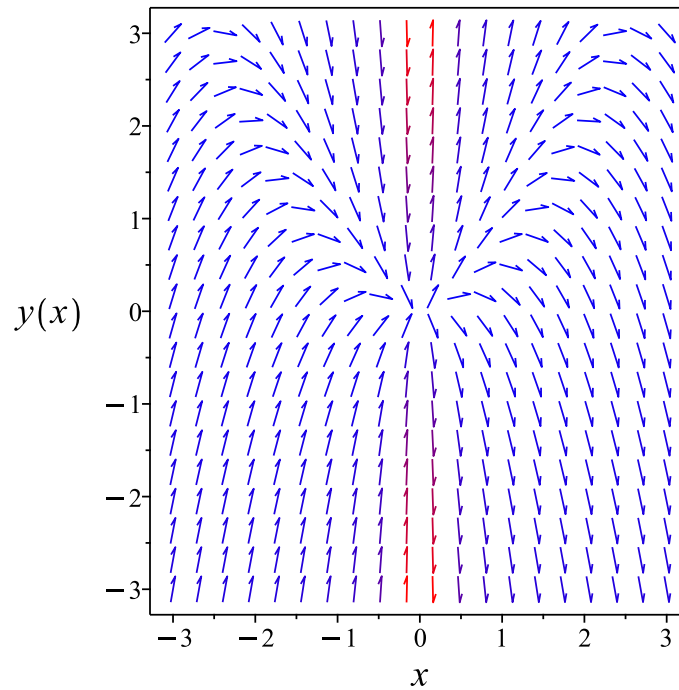


Figure 256: Slope field plot

Verification of solutions

$$y = -x^2(\ln(x) - c_1)$$

Verified OK.

6.4.4 Maple step by step solution

Let's solve

$$-2y + y'x = -x^2$$

- Highest derivative means the order of the ODE is 1

$$y'$$

- Isolate the derivative

$$y' = \frac{2y}{x} - x$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE

$$y' - \frac{2y}{x} = -x$$

- The ODE is linear; multiply by an integrating factor $\mu(x)$

$$\mu(x) \left(y' - \frac{2y}{x} \right) = -\mu(x) x$$

- Assume the lhs of the ODE is the total derivative $\frac{d}{dx}(\mu(x) y)$

$$\mu(x) \left(y' - \frac{2y}{x} \right) = \mu'(x) y + \mu(x) y'$$

- Isolate $\mu'(x)$

$$\mu'(x) = -\frac{2\mu(x)}{x}$$

- Solve to find the integrating factor

$$\mu(x) = \frac{1}{x^2}$$

- Integrate both sides with respect to x

$$\int \left(\frac{d}{dx}(\mu(x) y) \right) dx = \int -\mu(x) x dx + c_1$$

- Evaluate the integral on the lhs

$$\mu(x) y = \int -\mu(x) x dx + c_1$$

- Solve for y

$$y = \frac{\int -\mu(x) x dx + c_1}{\mu(x)}$$

- Substitute $\mu(x) = \frac{1}{x^2}$

$$y = x^2 \left(\int -\frac{1}{x} dx + c_1 \right)$$

- Evaluate the integrals on the rhs

$$y = x^2(-\ln(x) + c_1)$$

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
<- 1st order linear successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 14

```
dsolve((x^2-2*y(x))*(diff(y(x),x))=0,y(x), singsol=all)
```

$$y(x) = (-\ln(x) + c_1) x^2$$

✓ Solution by Mathematica

Time used: 0.025 (sec). Leaf size: 16

```
DSolve[(x^2-2*y[x])*(y'[x])=0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow x^2(-\log(x) + c_1)$$

6.5 problem 5

- 6.5.1 Solving as homogeneousTypeD2 ode 1309
- 6.5.2 Solving as first order ode lie symmetry calculated ode 1311

Internal problem ID [11679]

Internal file name [OUTPUT/11688_Wednesday_April_10_2024_04_54_42_PM_93828384/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, Miscellaneous Review. Exercises page 60

Problem number: 5.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**homogeneousTypeD2**", "**first_order_ode_lie_symmetry_calculated**"

Maple gives the following as the ode type

```
[[_homogeneous, `class A`], _rational, [_Abel, `2nd type`, `class A`]]
```

$$-5y + (y + x)y' = -3x$$

6.5.1 Solving as homogeneousTypeD2 ode

Using the change of variables $y = u(x)x$ on the above ode results in new ode in $u(x)$

$$-5u(x)x + (u(x)x + x)(u'(x)x + u(x)) = -3x$$

In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= -\frac{u^2 - 4u + 3}{x(u + 1)} \end{aligned}$$

Where $f(x) = -\frac{1}{x}$ and $g(u) = \frac{u^2-4u+3}{u+1}$. Integrating both sides gives

$$\frac{1}{\frac{u^2-4u+3}{u+1}} du = -\frac{1}{x} dx$$

$$\int \frac{1}{\frac{u^2-4u+3}{u+1}} du = \int -\frac{1}{x} dx$$

$$2 \ln(u-3) - \ln(u-1) = -\ln(x) + c_2$$

Raising both side to exponential gives

$$e^{2\ln(u-3)-\ln(u-1)} = e^{-\ln(x)+c_2}$$

Which simplifies to

$$\frac{(u-3)^2}{u-1} = \frac{c_3}{x}$$

The solution is

$$\frac{(u(x)-3)^2}{u(x)-1} = \frac{c_3}{x}$$

Replacing $u(x)$ in the above solution by $\frac{y}{x}$ results in the solution for y in implicit form

$$\frac{\left(\frac{y}{x}-3\right)^2}{\frac{y}{x}-1} = \frac{c_3}{x}$$
$$\frac{(-3x+y)^2}{x(y-x)} = \frac{c_3}{x}$$

Which simplifies to

$$-\frac{(3x-y)^2}{-y+x} = c_3$$

Summary

The solution(s) found are the following

$$-\frac{(3x-y)^2}{-y+x} = c_3 \quad (1)$$

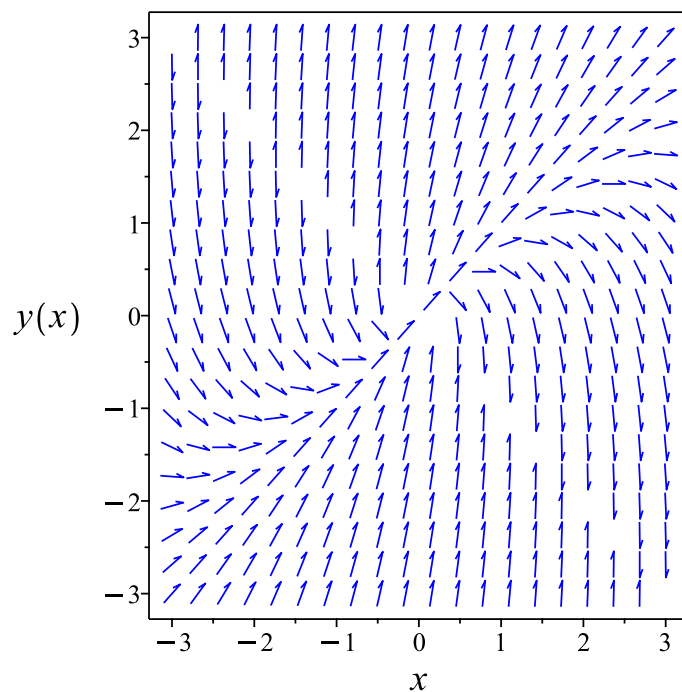


Figure 257: Slope field plot

Verification of solutions

$$-\frac{(3x - y)^2}{-y + x} = c_3$$

Verified OK.

6.5.2 Solving as first order ode lie symmetry calculated ode

Writing the ode as

$$y' = \frac{-3x + 5y}{y + x}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is not in the lookup table. To determine ξ, η then (A) is solved using ansatz. Making bivariate polynomials of degree 1 to use as anstaz gives

$$\xi = xa_2 + ya_3 + a_1 \quad (1\text{E})$$

$$\eta = xb_2 + yb_3 + b_1 \quad (2\text{E})$$

Where the unknown coefficients are

$$\{a_1, a_2, a_3, b_1, b_2, b_3\}$$

Substituting equations (1E,2E) and ω into (A) gives

$$\begin{aligned} b_2 + \frac{(-3x + 5y)(b_3 - a_2)}{y + x} - \frac{(-3x + 5y)^2 a_3}{(y + x)^2} \\ - \left(\frac{3}{y + x} - \frac{-3x + 5y}{(y + x)^2} \right) (xa_2 + ya_3 + a_1) \\ - \left(\frac{5}{y + x} - \frac{-3x + 5y}{(y + x)^2} \right) (xb_2 + yb_3 + b_1) = 0 \end{aligned} \quad (5E)$$

Putting the above in normal form gives

$$\frac{3x^2a_2 - 9x^2a_3 - 7x^2b_2 - 3x^2b_3 + 6xya_2 + 30xya_3 + 2xyb_2 - 6xyb_3 - 5y^2a_2 - 17y^2a_3 + y^2b_2 + 5y^2b_3 - 8xa_1 - 8yb_1}{(y + x)^2} = 0$$

Setting the numerator to zero gives

$$\begin{aligned} 3x^2a_2 - 9x^2a_3 - 7x^2b_2 - 3x^2b_3 + 6xya_2 + 30xya_3 + 2xyb_2 \\ - 6xyb_3 - 5y^2a_2 - 17y^2a_3 + y^2b_2 + 5y^2b_3 - 8xb_1 + 8ya_1 = 0 \end{aligned} \quad (6E)$$

Looking at the above PDE shows the following are all the terms with $\{x, y\}$ in them.

$$\{x, y\}$$

The following substitution is now made to be able to collect on all terms with $\{x, y\}$ in them

$$\{x = v_1, y = v_2\}$$

The above PDE (6E) now becomes

$$\begin{aligned} 3a_2v_1^2 + 6a_2v_1v_2 - 5a_2v_2^2 - 9a_3v_1^2 + 30a_3v_1v_2 - 17a_3v_2^2 - 7b_2v_1^2 \\ + 2b_2v_1v_2 + b_2v_2^2 - 3b_3v_1^2 - 6b_3v_1v_2 + 5b_3v_2^2 + 8a_1v_2 - 8b_1v_1 = 0 \end{aligned} \quad (7E)$$

Collecting the above on the terms v_i introduced, and these are

$$\{v_1, v_2\}$$

Equation (7E) now becomes

$$(3a_2 - 9a_3 - 7b_2 - 3b_3)v_1^2 + (6a_2 + 30a_3 + 2b_2 - 6b_3)v_1v_2 - 8b_1v_1 + (-5a_2 - 17a_3 + b_2 + 5b_3)v_2^2 + 8a_1v_2 = 0 \quad (8E)$$

Setting each coefficients in (8E) to zero gives the following equations to solve

$$\begin{aligned} 8a_1 &= 0 \\ -8b_1 &= 0 \\ -5a_2 - 17a_3 + b_2 + 5b_3 &= 0 \\ 3a_2 - 9a_3 - 7b_2 - 3b_3 &= 0 \\ 6a_2 + 30a_3 + 2b_2 - 6b_3 &= 0 \end{aligned}$$

Solving the above equations for the unknowns gives

$$\begin{aligned} a_1 &= 0 \\ a_2 &= -4a_3 + b_3 \\ a_3 &= a_3 \\ b_1 &= 0 \\ b_2 &= -3a_3 \\ b_3 &= b_3 \end{aligned}$$

Substituting the above solution in the anstaz (1E,2E) (using 1 as arbitrary value for any unknown in the RHS) gives

$$\begin{aligned} \xi &= x \\ \eta &= y \end{aligned}$$

Shifting is now applied to make $\xi = 0$ in order to simplify the rest of the computation

$$\begin{aligned} \eta &= \eta - \omega(x, y) \xi \\ &= y - \left(\frac{-3x + 5y}{y + x} \right) (x) \\ &= \frac{3x^2 - 4xy + y^2}{y + x} \\ \xi &= 0 \end{aligned}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \quad (1)$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{3x^2 - 4xy + y^2}{y+x}} dy \end{aligned}$$

Which results in

$$S = -\ln(y - x) + 2\ln(-3x + y)$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = \frac{-3x + 5y}{y + x}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= \frac{1}{y - x} - \frac{6}{-3x + y} \\ S_y &= \frac{y + x}{(3x - y)(-y + x)} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 0 \tag{2A}$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 0$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = c_1 \tag{4}$$

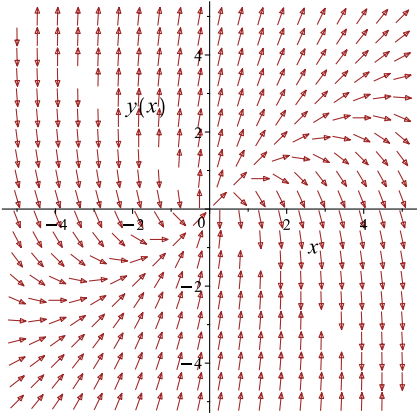
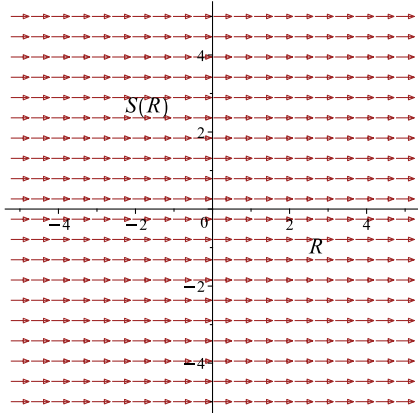
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$-\ln(y - x) + 2 \ln(-3x + y) = c_1$$

Which simplifies to

$$-\ln(y - x) + 2 \ln(-3x + y) = c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = \frac{-3x+5y}{y+x}$ 	$R = x$ $S = -\ln(y - x) + 2 \ln(-3x + y)$	$\frac{dS}{dR} = 0$ 

Summary

The solution(s) found are the following

$$-\ln(y-x) + 2\ln(-3x+y) = c_1 \quad (1)$$

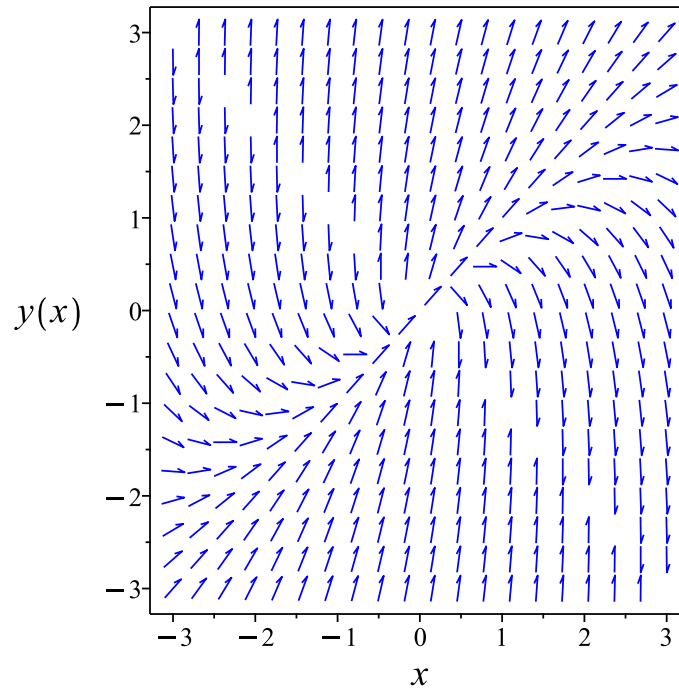


Figure 258: Slope field plot

Verification of solutions

$$-\ln(y-x) + 2\ln(-3x+y) = c_1$$

Verified OK.

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
trying Bernoulli  
trying separable  
trying inverse linear  
trying homogeneous types:  
trying homogeneous D  
<- homogeneous successful`
```

✓ Solution by Maple

Time used: 0.031 (sec). Leaf size: 47

```
dsolve((3*x-5*y(x))+(x+y(x))*diff(y(x),x)=0,y(x), singsol=all)
```

$$y(x) = \frac{6c_1x - \sqrt{8c_1x + 1} + 1}{2c_1}$$
$$y(x) = \frac{6c_1x + 1 + \sqrt{8c_1x + 1}}{2c_1}$$

✓ Solution by Mathematica

Time used: 1.033 (sec). Leaf size: 80

```
DSolve[(3*x-5*y[x])+(x+y[x])*y'[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{1}{2} \left(6x - e^{\frac{c_1}{2}} \sqrt{-8x + e^{c_1}} - e^{c_1} \right)$$
$$y(x) \rightarrow \frac{1}{2} \left(6x + e^{\frac{c_1}{2}} \sqrt{-8x + e^{c_1}} - e^{c_1} \right)$$

6.6 problem 6

6.6.1	Solving as separable ode	1318
6.6.2	Solving as linear ode	1320
6.6.3	Solving as homogeneousTypeD2 ode	1321
6.6.4	Solving as first order ode lie symmetry lookup ode	1323
6.6.5	Solving as exact ode	1327
6.6.6	Maple step by step solution	1331

Internal problem ID [11680]

Internal file name [OUTPUT/11689_Wednesday_April_10_2024_04_54_44_PM_77178628/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, Miscellaneous Review. Exercises page 60

Problem number: 6.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact", "linear", "separable", "homogeneousTypeD2", "first_order_ode_lie_symmetry_lookup"

Maple gives the following as the ode type

[_separable]

$$e^{2x}y^2 + (ye^{2x} - 2y)y' = 0$$

6.6.1 Solving as separable ode

In canonical form the ODE is

$$\begin{aligned}y' &= F(x, y) \\ &= f(x)g(y) \\ &= -\frac{e^{2x}y}{e^{2x} - 2}\end{aligned}$$

Where $f(x) = -\frac{e^{2x}}{e^{2x}-2}$ and $g(y) = y$. Integrating both sides gives

$$\begin{aligned}\frac{1}{y} dy &= -\frac{e^{2x}}{e^{2x}-2} dx \\ \int \frac{1}{y} dy &= \int -\frac{e^{2x}}{e^{2x}-2} dx \\ \ln(y) &= -\frac{\ln(e^{2x}-2)}{2} + c_1 \\ y &= e^{-\frac{\ln(e^{2x}-2)}{2} + c_1} \\ &= \frac{c_1}{\sqrt{e^{2x}-2}}\end{aligned}$$

Summary

The solution(s) found are the following

$$y = \frac{c_1}{\sqrt{e^{2x}-2}} \tag{1}$$

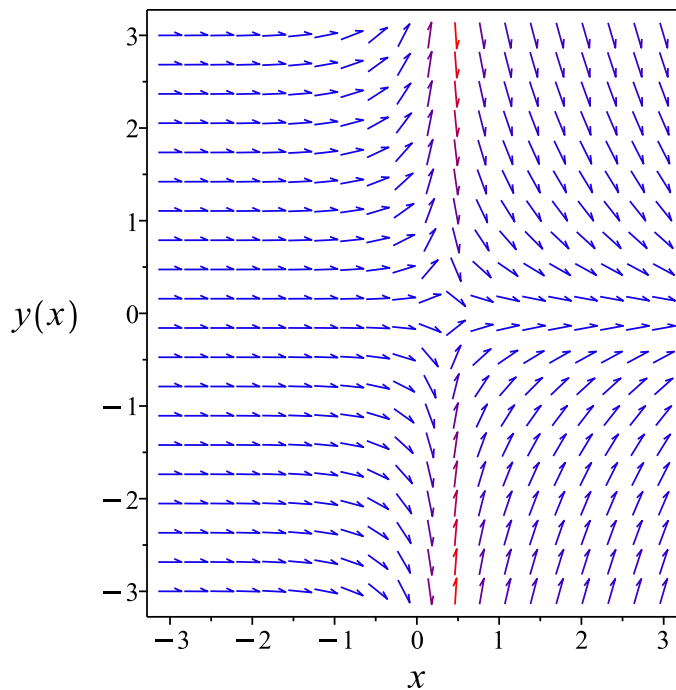


Figure 259: Slope field plot

Verification of solutions

$$y = \frac{c_1}{\sqrt{e^{2x}-2}}$$

Verified OK.

6.6.2 Solving as linear ode

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = \frac{e^{2x}}{e^{2x} - 2}$$

$$q(x) = 0$$

Hence the ode is

$$y' + \frac{e^{2x}y}{e^{2x} - 2} = 0$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int \frac{e^{2x}}{e^{2x} - 2} dx} \\ &= \sqrt{e^{2x} - 2}\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}\mu y &= 0 \\ \frac{d}{dx}(\sqrt{e^{2x} - 2}y) &= 0\end{aligned}$$

Integrating gives

$$\sqrt{e^{2x} - 2}y = c_1$$

Dividing both sides by the integrating factor $\mu = \sqrt{e^{2x} - 2}$ results in

$$y = \frac{c_1}{\sqrt{e^{2x} - 2}}$$

Summary

The solution(s) found are the following

$$y = \frac{c_1}{\sqrt{e^{2x} - 2}} \tag{1}$$

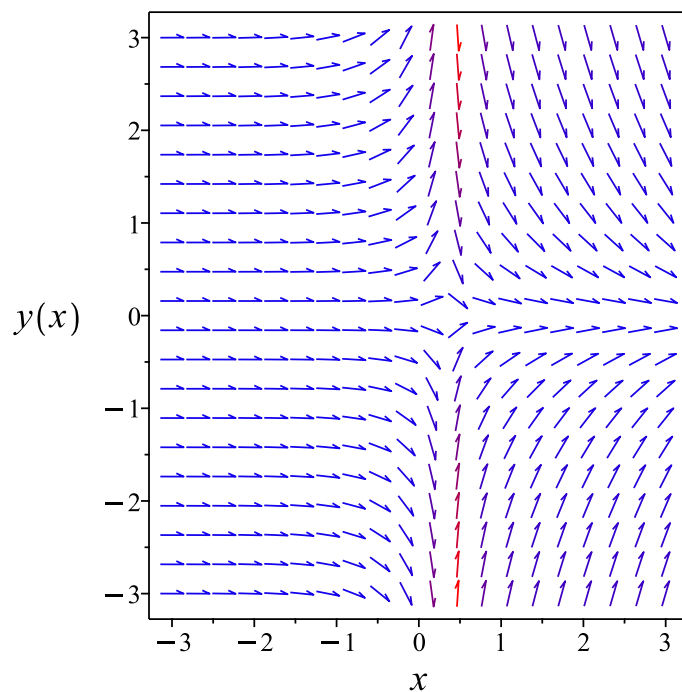


Figure 260: Slope field plot

Verification of solutions

$$y = \frac{c_1}{\sqrt{e^{2x} - 2}}$$

Verified OK.

6.6.3 Solving as homogeneousTypeD2 ode

Using the change of variables $y = u(x)x$ on the above ode results in new ode in $u(x)$

$$e^{2x}u(x)^2 x^2 + (u(x)x e^{2x} - 2u(x)x)(u'(x)x + u(x)) = 0$$

In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= -\frac{u(e^{2x}x + e^{2x} - 2)}{x(e^{2x} - 2)} \end{aligned}$$

Where $f(x) = -\frac{e^{2x}x + e^{2x} - 2}{x(e^{2x} - 2)}$ and $g(u) = u$. Integrating both sides gives

$$\begin{aligned}\frac{1}{u} du &= -\frac{e^{2x}x + e^{2x} - 2}{x(e^{2x} - 2)} dx \\ \int \frac{1}{u} du &= \int -\frac{e^{2x}x + e^{2x} - 2}{x(e^{2x} - 2)} dx \\ \ln(u) &= -\ln(x) - \frac{\ln(e^{2x} - 2)}{2} + c_2 \\ u &= e^{-\ln(x) - \frac{\ln(e^{2x} - 2)}{2} + c_2} \\ &= c_2 e^{-\ln(x) - \frac{\ln(e^{2x} - 2)}{2}}\end{aligned}$$

Which simplifies to

$$u(x) = \frac{c_2}{x\sqrt{e^{2x} - 2}}$$

Therefore the solution y is

$$\begin{aligned}y &= ux \\ &= \frac{c_2}{\sqrt{e^{2x} - 2}}\end{aligned}$$

Summary

The solution(s) found are the following

$$y = \frac{c_2}{\sqrt{e^{2x} - 2}} \tag{1}$$

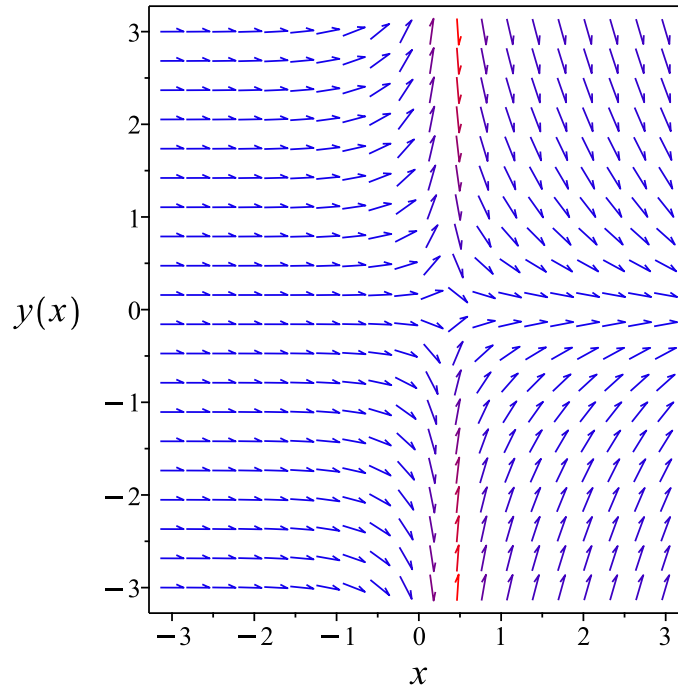


Figure 261: Slope field plot

Verification of solutions

$$y = \frac{c_2}{\sqrt{e^{2x} - 2}}$$

Verified OK.

6.6.4 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = -\frac{e^{2x}y}{e^{2x} - 2}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \tag{A}$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 213: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int(n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned} \xi(x, y) &= 0 \\ \eta(x, y) &= \frac{1}{\sqrt{e^{2x} - 2}} \end{aligned} \tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{1}{\sqrt{e^{2x}-2}}} dy \end{aligned}$$

Which results in

$$S = \sqrt{e^{2x} - 2} y$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{e^{2x}y}{e^{2x} - 2}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= \frac{y e^{2x}}{\sqrt{e^{2x} - 2}} \\ S_y &= \sqrt{e^{2x} - 2} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 0 \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 0$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$y\sqrt{e^{2x} - 2} = c_1$$

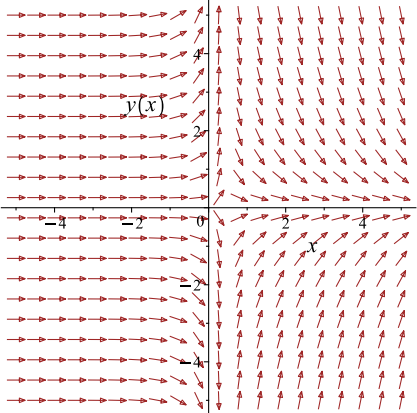
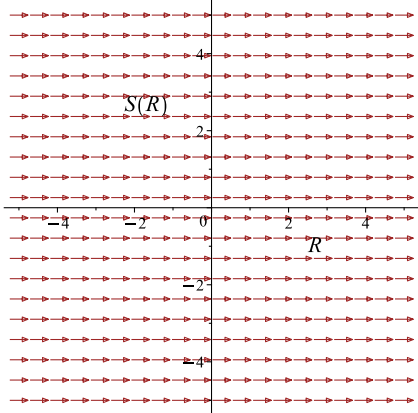
Which simplifies to

$$y\sqrt{e^{2x} - 2} = c_1$$

Which gives

$$y = \frac{c_1}{\sqrt{e^{2x} - 2}}$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{e^{2x}y}{e^{2x}-2}$ 	$R = x$ $S = \sqrt{e^{2x} - 2} y$	$\frac{dS}{dR} = 0$ 

Summary

The solution(s) found are the following

$$y = \frac{c_1}{\sqrt{e^{2x} - 2}} \quad (1)$$

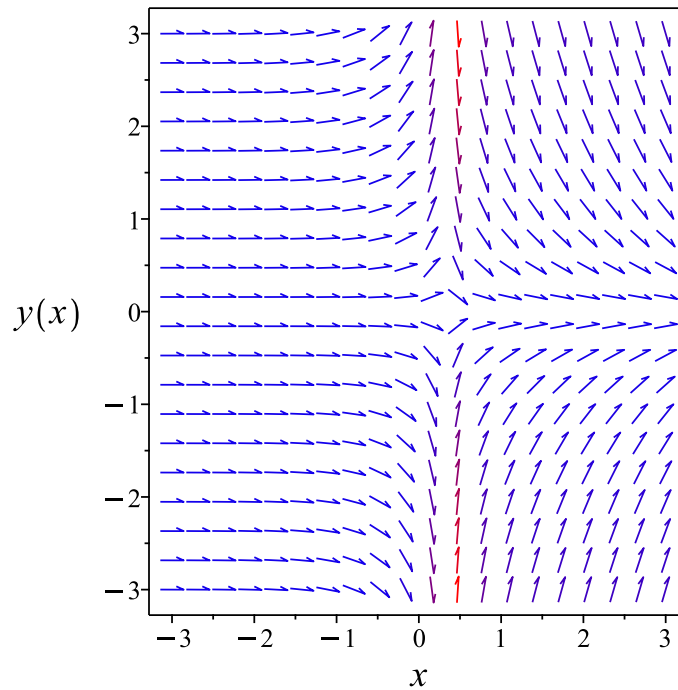


Figure 262: Slope field plot

Verification of solutions

$$y = \frac{c_1}{\sqrt{e^{2x} - 2}}$$

Verified OK.

6.6.5 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx}\phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (1A)$$

Therefore

$$\begin{aligned}\left(-\frac{1}{y}\right) dy &= \left(\frac{e^{2x}}{e^{2x} - 2}\right) dx \\ \left(-\frac{e^{2x}}{e^{2x} - 2}\right) dx + \left(-\frac{1}{y}\right) dy &= 0\end{aligned} \quad (2A)$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= -\frac{e^{2x}}{e^{2x} - 2} \\ N(x, y) &= -\frac{1}{y}\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y} \left(-\frac{e^{2x}}{e^{2x} - 2}\right) \\ &= 0\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x} \left(-\frac{1}{y} \right) \\ &= 0\end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \tag{1}$$

$$\frac{\partial \phi}{\partial y} = N \tag{2}$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int M dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int -\frac{e^{2x}}{e^{2x} - 2} dx \\ \phi &= -\frac{\ln(e^{2x} - 2)}{2} + f(y)\end{aligned} \tag{3}$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = 0 + f'(y) \tag{4}$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = -\frac{1}{y}$. Therefore equation (4) becomes

$$-\frac{1}{y} = 0 + f'(y) \tag{5}$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = -\frac{1}{y}$$

Integrating the above w.r.t y gives

$$\begin{aligned}\int f'(y) dy &= \int \left(-\frac{1}{y} \right) dy \\ f(y) &= -\ln(y) + c_1\end{aligned}$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = -\frac{\ln(e^{2x} - 2)}{2} - \ln(y) + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -\frac{\ln(e^{2x} - 2)}{2} - \ln(y)$$

The solution becomes

$$y = e^{-\frac{\ln(e^{2x} - 2)}{2} - c_1}$$

Summary

The solution(s) found are the following

$$y = e^{-\frac{\ln(e^{2x} - 2)}{2} - c_1} \tag{1}$$

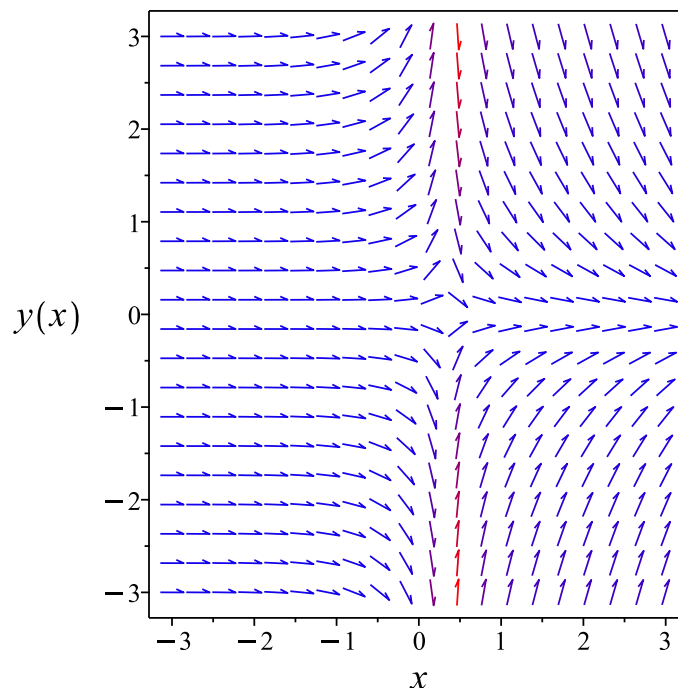


Figure 263: Slope field plot

Verification of solutions

$$y = e^{-\frac{\ln(e^{2x}-2)}{2} - c_1}$$

Verified OK.

6.6.6 Maple step by step solution

Let's solve

$$e^{2x}y^2 + (ye^{2x} - 2y)y' = 0$$

- Highest derivative means the order of the ODE is 1

y'

- Integrate both sides with respect to x

$$\int (e^{2x}y^2 + (ye^{2x} - 2y)y') dx = \int 0 dx + c_1$$

- Evaluate integral

$$\frac{(e^{2x}-2)y^2}{2} = c_1$$

- Solve for y

$$\left\{ y = \frac{\sqrt{2}\sqrt{(e^{2x}-2)c_1}}{e^{2x}-2}, y = -\frac{\sqrt{2}\sqrt{(e^{2x}-2)c_1}}{e^{2x}-2} \right\}$$

Maple trace

```
`Classification methods on request
Methods to be used are: [exact]
-----
* Tackling ODE using method: exact
--- Trying classification methods ---
trying exact
<- exact successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 58

```
dsolve((exp(2*x)*y(x)^2)+(exp(2*x)*y(x)-2*y(x))*diff(y(x),x)=0,y(x), singsol=all)
```

$$y(x) = 0$$

$$y(x) = \frac{\sqrt{2} \sqrt{-(e^{2x} - 2)} c_1}{e^{2x} - 2}$$

$$y(x) = -\frac{\sqrt{2} \sqrt{-(e^{2x} - 2)} c_1}{e^{2x} - 2}$$

✓ Solution by Mathematica

Time used: 0.071 (sec). Leaf size: 29

```
DSolve[(Exp[2*x]*y[x]^2)+(Exp[2*x]*y[x]-2*y[x])*y'[x]==0,y[x],x,IncludeSingularSolutions ->
```

$$y(x) \rightarrow 0$$

$$y(x) \rightarrow \frac{c_1}{\sqrt{e^{2x} - 2}}$$

$$y(x) \rightarrow 0$$

6.7 problem 7

6.7.1	Solving as separable ode	1333
6.7.2	Solving as linear ode	1335
6.7.3	Solving as first order ode lie symmetry lookup ode	1337
6.7.4	Solving as exact ode	1341
6.7.5	Maple step by step solution	1345

Internal problem ID [11681]

Internal file name [OUTPUT/11690_Wednesday_April_10_2024_04_54_45_PM_15215251/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, Miscellaneous Review. Exercises page 60

Problem number: 7.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact", "linear", "separable", "first_order_ode_lie_symmetry_lookup"

Maple gives the following as the ode type

[_separable]

$$8yx^3 + (x^4 + 1)y' = 12x^3$$

6.7.1 Solving as separable ode

In canonical form the ODE is

$$\begin{aligned}y' &= F(x, y) \\ &= f(x)g(y) \\ &= \frac{x^3(-8y + 12)}{x^4 + 1}\end{aligned}$$

Where $f(x) = \frac{x^3}{x^4+1}$ and $g(y) = -8y + 12$. Integrating both sides gives

$$\frac{1}{-8y + 12} dy = \frac{x^3}{x^4 + 1} dx$$

$$\int \frac{1}{-8y + 12} dy = \int \frac{x^3}{x^4 + 1} dx$$

$$-\frac{\ln(-2y + 3)}{8} = \frac{\ln(x^4 + 1)}{4} + c_1$$

Raising both side to exponential gives

$$\frac{1}{(-2y + 3)^{\frac{1}{8}}} = e^{\frac{\ln(x^4 + 1)}{4} + c_1}$$

Which simplifies to

$$\frac{1}{(-2y + 3)^{\frac{1}{8}}} = c_2(x^4 + 1)^{\frac{1}{4}}$$

Which simplifies to

$$y = \frac{\left(3c_2^8 e^{8c_1} (x^4 + 1)^2 - 1\right) e^{-8c_1}}{2c_2^8 (x^4 + 1)^2}$$

Summary

The solution(s) found are the following

$$y = \frac{\left(3c_2^8 e^{8c_1} (x^4 + 1)^2 - 1\right) e^{-8c_1}}{2c_2^8 (x^4 + 1)^2} \quad (1)$$

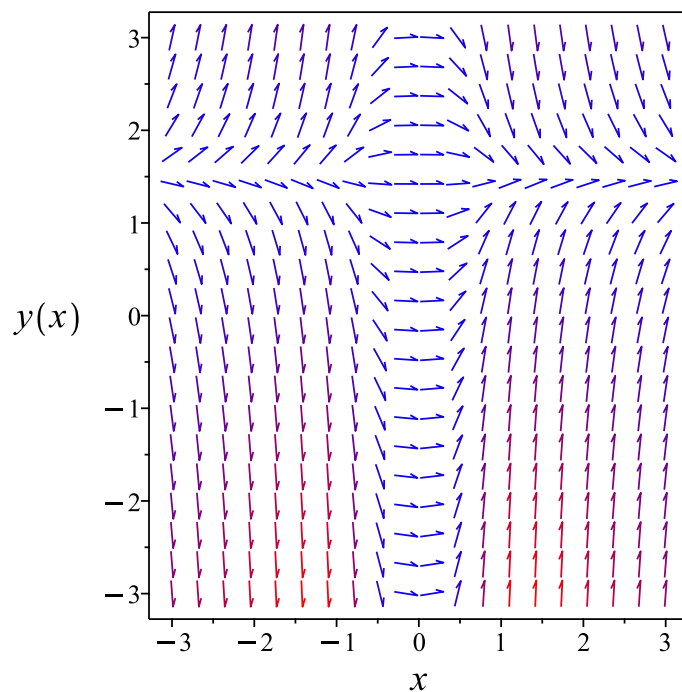


Figure 264: Slope field plot

Verification of solutions

$$y = \frac{\left(3c_2^8 e^{8c_1} (x^4 + 1)^2 - 1\right) e^{-8c_1}}{2c_2^8 (x^4 + 1)^2}$$

Verified OK.

6.7.2 Solving as linear ode

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = \frac{8x^3}{x^4 + 1}$$

$$q(x) = \frac{12x^3}{x^4 + 1}$$

Hence the ode is

$$y' + \frac{8x^3 y}{x^4 + 1} = \frac{12x^3}{x^4 + 1}$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int \frac{8x^3}{x^4+1} dx} \\ &= (x^4 + 1)^2\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu y) &= (\mu) \left(\frac{12x^3}{x^4 + 1} \right) \\ \frac{d}{dx} \left((x^4 + 1)^2 y \right) &= \left((x^4 + 1)^2 \right) \left(\frac{12x^3}{x^4 + 1} \right) \\ d \left((x^4 + 1)^2 y \right) &= (12x^3 (x^4 + 1)) dx\end{aligned}$$

Integrating gives

$$\begin{aligned}(x^4 + 1)^2 y &= \int 12x^3 (x^4 + 1) dx \\ (x^4 + 1)^2 y &= \frac{3(x^4 + 1)^2}{2} + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = (x^4 + 1)^2$ results in

$$y = \frac{3}{2} + \frac{c_1}{(x^4 + 1)^2}$$

Summary

The solution(s) found are the following

$$y = \frac{3}{2} + \frac{c_1}{(x^4 + 1)^2} \tag{1}$$

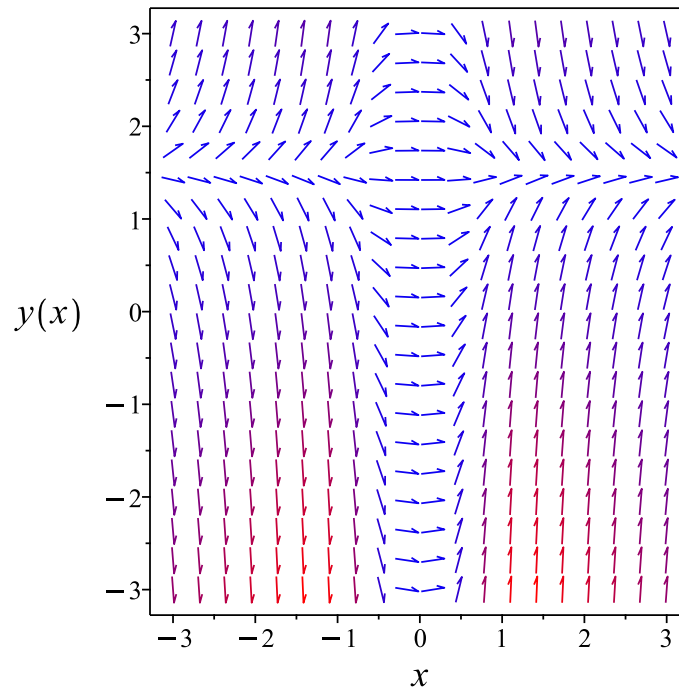


Figure 265: Slope field plot

Verification of solutions

$$y = \frac{3}{2} + \frac{c_1}{(x^4 + 1)^2}$$

Verified OK.

6.7.3 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = -\frac{4x^3(2y - 3)}{x^4 + 1}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 216: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned} \xi(x, y) &= 0 \\ \eta(x, y) &= \frac{1}{(x^4 + 1)^2} \end{aligned} \tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{1}{(x^4+1)^2}} dy \end{aligned}$$

Which results in

$$S = (x^4 + 1)^2 y$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{4x^3(2y - 3)}{x^4 + 1}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= 8(x^4 + 1) y x^3 \\ S_y &= (x^4 + 1)^2 \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 12x^7 + 12x^3 \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 12R^7 + 12R^3$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = \frac{3(R^4 + 1)^2}{2} + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$(x^4 + 1)^2 y = \frac{3(x^4 + 1)^2}{2} + c_1$$

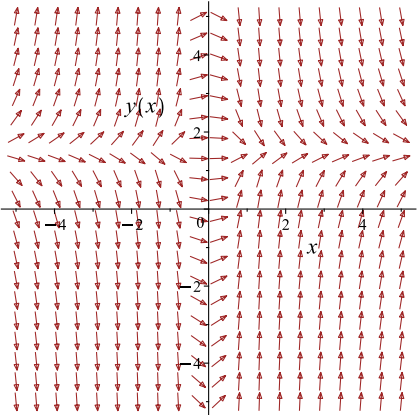
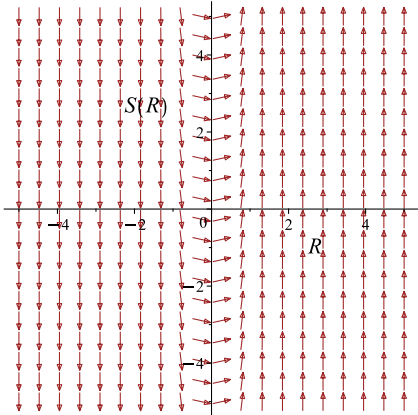
Which simplifies to

$$(x^4 + 1)^2 y = \frac{3(x^4 + 1)^2}{2} + c_1$$

Which gives

$$y = \frac{3x^8 + 6x^4 + 2c_1 + 3}{2(x^4 + 1)^2}$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{4x^3(2y-3)}{x^4+1}$ 	$R = x$ $S = (x^4 + 1)^2 y$	$\frac{dS}{dR} = 12R^7 + 12R^3$ 

Summary

The solution(s) found are the following

$$y = \frac{3x^8 + 6x^4 + 2c_1 + 3}{2(x^4 + 1)^2} \quad (1)$$

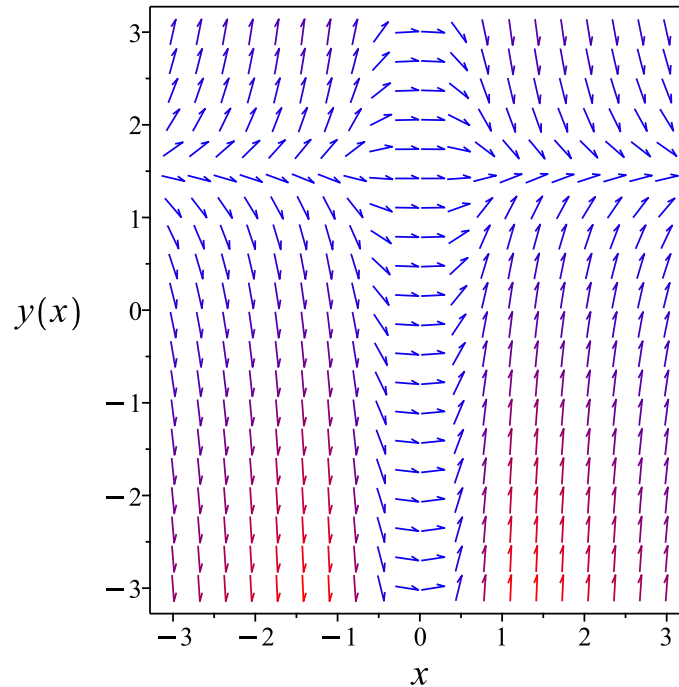


Figure 266: Slope field plot

Verification of solutions

$$y = \frac{3x^8 + 6x^4 + 2c_1 + 3}{2(x^4 + 1)^2}$$

Verified OK.

6.7.4 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \quad (A)$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the

ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx}\phi(x, y) = 0$$

Hence

$$\frac{\partial\phi}{\partial x} + \frac{\partial\phi}{\partial y} \frac{dy}{dx} = 0 \quad (\text{B})$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial\phi}{\partial x} &= M \\ \frac{\partial\phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (1A)$$

Therefore

$$\begin{aligned} \left(\frac{1}{-8y+12}\right) dy &= \left(\frac{x^3}{x^4+1}\right) dx \\ \left(-\frac{x^3}{x^4+1}\right) dx + \left(\frac{1}{-8y+12}\right) dy &= 0 \end{aligned} \quad (2A)$$

Comparing (1A) and (2A) shows that

$$\begin{aligned} M(x, y) &= -\frac{x^3}{x^4+1} \\ N(x, y) &= \frac{1}{-8y+12} \end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y} \left(-\frac{x^3}{x^4 + 1} \right) \\ &= 0\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x} \left(\frac{1}{-8y + 12} \right) \\ &= 0\end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \quad (1)$$

$$\frac{\partial \phi}{\partial y} = N \quad (2)$$

Integrating (1) w.r.t. x gives

$$\int \frac{\partial \phi}{\partial x} dx = \int M dx$$

$$\int \frac{\partial \phi}{\partial x} dx = \int -\frac{x^3}{x^4 + 1} dx$$

$$\phi = -\frac{\ln(x^4 + 1)}{4} + f(y) \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = 0 + f'(y) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = \frac{1}{-8y+12}$. Therefore equation (4) becomes

$$\frac{1}{-8y + 12} = 0 + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = -\frac{1}{4(2y - 3)}$$

Integrating the above w.r.t y gives

$$\int f'(y) dy = \int \left(-\frac{1}{8y-12} \right) dy$$
$$f(y) = -\frac{\ln(2y-3)}{8} + c_1$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = -\frac{\ln(x^4+1)}{4} - \frac{\ln(2y-3)}{8} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -\frac{\ln(x^4+1)}{4} - \frac{\ln(2y-3)}{8}$$

The solution becomes

$$y = \frac{3x^8 + 6x^4 + e^{-8c_1} + 3}{2x^8 + 4x^4 + 2}$$

Summary

The solution(s) found are the following

$$y = \frac{3x^8 + 6x^4 + e^{-8c_1} + 3}{2x^8 + 4x^4 + 2} \quad (1)$$

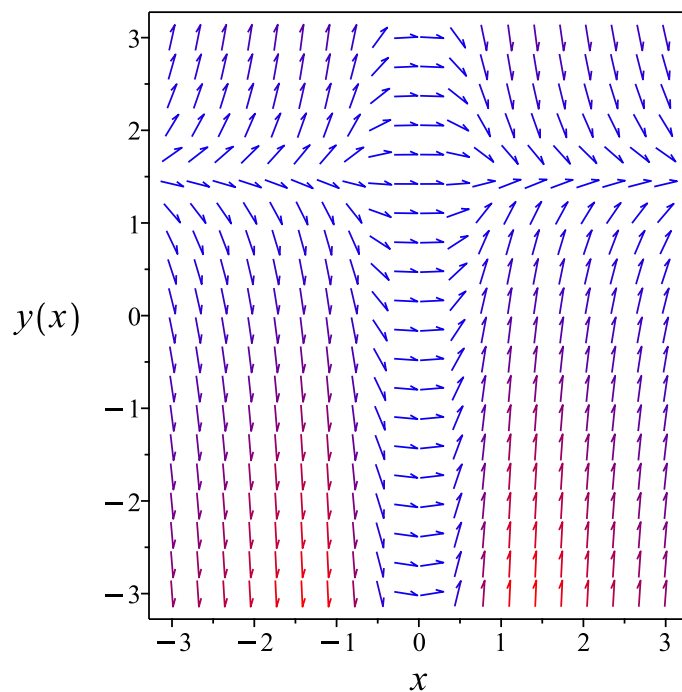


Figure 267: Slope field plot

Verification of solutions

$$y = \frac{3x^8 + 6x^4 + e^{-8c_1} + 3}{2x^8 + 4x^4 + 2}$$

Verified OK.

6.7.5 Maple step by step solution

Let's solve

$$8yx^3 + (x^4 + 1)y' = 12x^3$$

- Highest derivative means the order of the ODE is 1

y'

- Separate variables

$$\frac{y'}{2y-3} = -\frac{4x^3}{x^4+1}$$

- Integrate both sides with respect to x

$$\int \frac{y'}{2y-3} dx = \int -\frac{4x^3}{x^4+1} dx + c_1$$

- Evaluate integral

$$\frac{\ln(2y-3)}{2} = -\ln(x^4 + 1) + c_1$$

- Solve for y

$$y = \frac{3x^8 + 6x^4 + e^{2c_1} + 3}{2(x^8 + 2x^4 + 1)}$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
<- 1st order linear successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 15

```
dsolve((8*x^3*y(x)-12*x^3)+(1+x^4)*diff(y(x),x)=0,y(x), singsol=all)
```

$$y(x) = \frac{3}{2} + \frac{c_1}{(x^4 + 1)^2}$$

✓ Solution by Mathematica

Time used: 0.036 (sec). Leaf size: 38

```
DSolve[(8*x^3*y[x]-12*x^3)+(1+x^4)*y'[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{3x^8 + 6x^4 + 2c_1}{2(x^4 + 1)^2}$$

$$y(x) \rightarrow \frac{3}{2}$$

6.8 problem 8

6.8.1	Solving as homogeneousTypeD2 ode	1347
6.8.2	Solving as first order ode lie symmetry calculated ode	1349
6.8.3	Solving as riccati ode	1355

Internal problem ID [11682]

Internal file name [OUTPUT/11691_Wednesday_April_10_2024_04_54_46_PM_66245698/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, Miscellaneous Review. Exercises page 60

Problem number: 8.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**riccati**", "**homogeneousTypeD2**", "**first_order_ode_lie_symmetry_calculated**"

Maple gives the following as the ode type

```
[[_homogeneous, `class A`], _rational, _Riccati]
```

$$yx + y^2 + 2x^2y' = -2x^2$$

6.8.1 Solving as homogeneousTypeD2 ode

Using the change of variables $y = u(x)x$ on the above ode results in new ode in $u(x)$

$$u(x)x^2 + u(x)^2x^2 + 2x^2(u'(x)x + u(x)) = -2x^2$$

In canonical form the ODE is

$$\begin{aligned}u' &= F(x, u) \\ &= f(x)g(u) \\ &= \frac{-\frac{1}{2}u^2 - \frac{3}{2}u - 1}{x}\end{aligned}$$

Where $f(x) = \frac{1}{x}$ and $g(u) = -\frac{1}{2}u^2 - \frac{3}{2}u - 1$. Integrating both sides gives

$$\begin{aligned}\frac{1}{-\frac{1}{2}u^2 - \frac{3}{2}u - 1} du &= \frac{1}{x} dx \\ \int \frac{1}{-\frac{1}{2}u^2 - \frac{3}{2}u - 1} du &= \int \frac{1}{x} dx \\ -2 \ln(u+1) + 2 \ln(u+2) &= \ln(x) + c_2\end{aligned}$$

The above can be written as

$$\begin{aligned}(-2)(\ln(u+1) - \ln(u+2)) &= \ln(x) + 2c_2 \\ \ln(u+1) - \ln(u+2) &= \left(-\frac{1}{2}\right)(\ln(x) + 2c_2) \\ &= -\frac{\ln(x)}{2} - c_2\end{aligned}$$

Raising both side to exponential gives

$$e^{\ln(u+1) - \ln(u+2)} = e^{-\frac{\ln(x)}{2} - \frac{c_2}{2}}$$

Which simplifies to

$$\begin{aligned}\frac{u+1}{u+2} &= -\frac{c_2}{2\sqrt{x}} \\ &= \frac{c_3}{\sqrt{x}}\end{aligned}$$

Therefore the solution y is

$$\begin{aligned}y &= xu \\ &= -\frac{x(\sqrt{x} - 2c_3)}{\sqrt{x} - c_3}\end{aligned}$$

Summary

The solution(s) found are the following

$$y = -\frac{x(\sqrt{x} - 2c_3)}{\sqrt{x} - c_3} \tag{1}$$

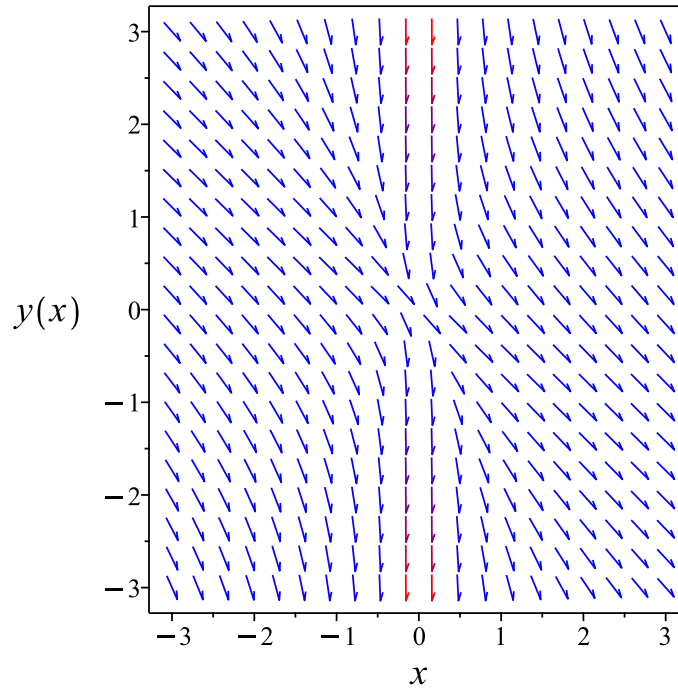


Figure 268: Slope field plot

Verification of solutions

$$y = -\frac{x(\sqrt{x} - 2c_3)}{\sqrt{x} - c_3}$$

Verified OK.

6.8.2 Solving as first order ode lie symmetry calculated ode

Writing the ode as

$$y' = -\frac{2x^2 + xy + y^2}{2x^2}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \tag{A}$$

The type of this ode is not in the lookup table. To determine ξ, η then (A) is solved using ansatz. Making bivariate polynomials of degree 1 to use as anstaz gives

$$\xi = xa_2 + ya_3 + a_1 \tag{1E}$$

$$\eta = xb_2 + yb_3 + b_1 \tag{2E}$$

Where the unknown coefficients are

$$\{a_1, a_2, a_3, b_1, b_2, b_3\}$$

Substituting equations (1E,2E) and ω into (A) gives

$$\begin{aligned} b_2 - \frac{(2x^2 + xy + y^2)(b_3 - a_2)}{2x^2} - \frac{(2x^2 + xy + y^2)^2 a_3}{4x^4} \\ - \left(-\frac{4x + y}{2x^2} + \frac{2x^2 + xy + y^2}{x^3} \right) (xa_2 + ya_3 + a_1) \\ + \frac{(x + 2y)(xb_2 + yb_3 + b_1)}{2x^2} = 0 \end{aligned} \quad (5E)$$

Putting the above in normal form gives

$$\frac{4x^4 a_2 - 4x^4 a_3 + 6b_2 x^4 - 4x^4 b_3 - 4x^3 y a_3 + 4x^3 y b_2 - 2x^2 y^2 a_2 - 7x^2 y^2 a_3 + 2x^2 y^2 b_3 - 6x y^3 a_3 - y^4 a_3 + 2x^3 b_1 - 2x^2 y a_1 + 4x^2 y b_1 - 4x y^2 a_1}{4x^4} = 0$$

Setting the numerator to zero gives

$$\begin{aligned} 4x^4 a_2 - 4x^4 a_3 + 6b_2 x^4 - 4x^4 b_3 - 4x^3 y a_3 + 4x^3 y b_2 - 2x^2 y^2 a_2 - 7x^2 y^2 a_3 \\ + 2x^2 y^2 b_3 - 6x y^3 a_3 - y^4 a_3 + 2x^3 b_1 - 2x^2 y a_1 + 4x^2 y b_1 - 4x y^2 a_1 = 0 \end{aligned} \quad (6E)$$

Looking at the above PDE shows the following are all the terms with $\{x, y\}$ in them.

$$\{x, y\}$$

The following substitution is now made to be able to collect on all terms with $\{x, y\}$ in them

$$\{x = v_1, y = v_2\}$$

The above PDE (6E) now becomes

$$\begin{aligned} 4a_2 v_1^4 - 2a_2 v_1^2 v_2^2 - 4a_3 v_1^4 - 4a_3 v_1^3 v_2 - 7a_3 v_1^2 v_2^2 - 6a_3 v_1 v_2^3 - a_3 v_2^4 + 6b_2 v_1^4 \\ + 4b_2 v_1^3 v_2 - 4b_3 v_1^4 + 2b_3 v_1^2 v_2^2 - 2a_1 v_1^2 v_2 - 4a_1 v_1 v_2^2 + 2b_1 v_1^3 + 4b_1 v_1^2 v_2 = 0 \end{aligned} \quad (7E)$$

Collecting the above on the terms v_i introduced, and these are

$$\{v_1, v_2\}$$

Equation (7E) now becomes

$$(4a_2 - 4a_3 + 6b_2 - 4b_3)v_1^4 + (-4a_3 + 4b_2)v_1^3v_2 + 2b_1v_1^3 + (-2a_2 - 7a_3 + 2b_3)v_1^2v_2^2 + (-2a_1 + 4b_1)v_1^2v_2 - 6a_3v_1v_2^3 - 4a_1v_1v_2^2 - a_3v_2^4 = 0 \quad (8E)$$

Setting each coefficients in (8E) to zero gives the following equations to solve

$$\begin{aligned} -4a_1 &= 0 \\ -6a_3 &= 0 \\ -a_3 &= 0 \\ 2b_1 &= 0 \\ -2a_1 + 4b_1 &= 0 \\ -4a_3 + 4b_2 &= 0 \\ -2a_2 - 7a_3 + 2b_3 &= 0 \\ 4a_2 - 4a_3 + 6b_2 - 4b_3 &= 0 \end{aligned}$$

Solving the above equations for the unknowns gives

$$\begin{aligned} a_1 &= 0 \\ a_2 &= b_3 \\ a_3 &= 0 \\ b_1 &= 0 \\ b_2 &= 0 \\ b_3 &= b_3 \end{aligned}$$

Substituting the above solution in the anstaz (1E,2E) (using 1 as arbitrary value for any unknown in the RHS) gives

$$\begin{aligned} \xi &= x \\ \eta &= y \end{aligned}$$

Shifting is now applied to make $\xi = 0$ in order to simplify the rest of the computation

$$\begin{aligned}\eta &= \eta - \omega(x, y) \xi \\ &= y - \left(-\frac{2x^2 + xy + y^2}{2x^2} \right) (x) \\ &= \frac{2x^2 + 3xy + y^2}{2x} \\ \xi &= 0\end{aligned}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \quad (1)$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y} \right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned}S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{2x^2 + 3xy + y^2}{2x}} dy\end{aligned}$$

Which results in

$$S = 2 \ln(y + x) - 2 \ln(2x + y)$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{2x^2 + xy + y^2}{2x^2}$$

Evaluating all the partial derivatives gives

$$\begin{aligned}R_x &= 1 \\R_y &= 0 \\S_x &= -\frac{2y}{(y+x)(2x+y)} \\S_y &= \frac{2x}{(y+x)(2x+y)}\end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = -\frac{1}{x} \tag{2A}$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = -\frac{1}{R}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = -\ln(R) + c_1 \tag{4}$$

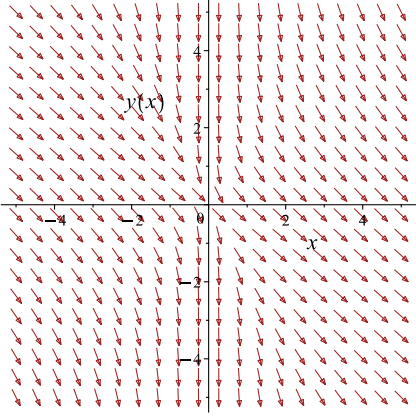
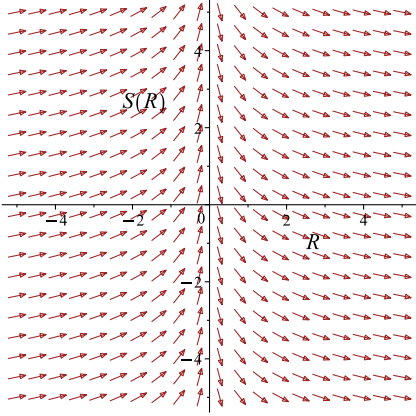
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$2\ln(y+x) - 2\ln(2x+y) = -\ln(x) + c_1$$

Which simplifies to

$$2\ln(y+x) - 2\ln(2x+y) = -\ln(x) + c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{2x^2 + xy + y^2}{2x^2}$ 	$R = x$ $S = 2 \ln(y + x) - 2 \ln(2x)$	$\frac{dS}{dR} = -\frac{1}{R}$ 

Summary

The solution(s) found are the following

$$2 \ln(y + x) - 2 \ln(2x + y) = -\ln(x) + c_1 \tag{1}$$

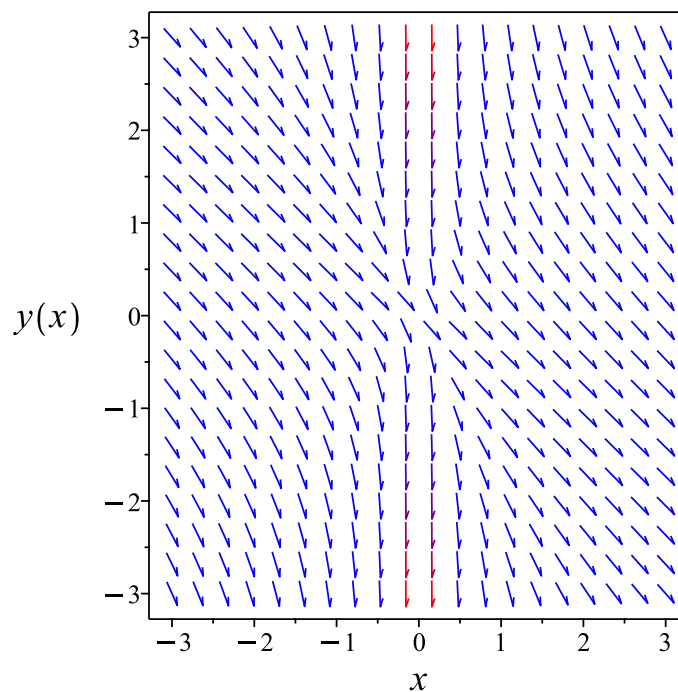


Figure 269: Slope field plot

Verification of solutions

$$2 \ln(y + x) - 2 \ln(2x + y) = -\ln(x) + c_1$$

Verified OK.

6.8.3 Solving as riccati ode

In canonical form the ODE is

$$\begin{aligned} y' &= F(x, y) \\ &= -\frac{2x^2 + xy + y^2}{2x^2} \end{aligned}$$

This is a Riccati ODE. Comparing the ODE to solve

$$y' = -1 - \frac{y}{2x} - \frac{y^2}{2x^2}$$

With Riccati ODE standard form

$$y' = f_0(x) + f_1(x)y + f_2(x)y^2$$

Shows that $f_0(x) = -1$, $f_1(x) = -\frac{1}{2x}$ and $f_2(x) = -\frac{1}{2x^2}$. Let

$$\begin{aligned} y &= \frac{-u'}{f_2 u} \\ &= \frac{-u'}{-\frac{u}{2x^2}} \end{aligned} \quad (1)$$

Using the above substitution in the given ODE results (after some simplification) in a second order ODE to solve for $u(x)$ which is

$$f_2 u''(x) - (f_2' + f_1 f_2) u'(x) + f_2^2 f_0 u(x) = 0 \quad (2)$$

But

$$\begin{aligned} f_2' &= \frac{1}{x^3} \\ f_1 f_2 &= \frac{1}{4x^3} \\ f_2^2 f_0 &= -\frac{1}{4x^4} \end{aligned}$$

Substituting the above terms back in equation (2) gives

$$-\frac{u''(x)}{2x^2} - \frac{5u'(x)}{4x^3} - \frac{u(x)}{4x^4} = 0$$

Solving the above ODE (this ode solved using Maple, not this program), gives

$$u(x) = \frac{c_1}{\sqrt{x}} + \frac{c_2}{x}$$

The above shows that

$$u'(x) = -\frac{c_1}{2x^{\frac{3}{2}}} - \frac{c_2}{x^2}$$

Using the above in (1) gives the solution

$$y = \frac{2\left(-\frac{c_1}{2x^{\frac{3}{2}}} - \frac{c_2}{x^2}\right)x^2}{\frac{c_1}{\sqrt{x}} + \frac{c_2}{x}}$$

Dividing both numerator and denominator by c_1 gives, after renaming the constant $\frac{c_2}{c_1} = c_3$ the following solution

$$y = \frac{(-c_3x - 2\sqrt{x})x}{c_3x + \sqrt{x}}$$

Summary

The solution(s) found are the following

$$y = \frac{(-c_3x - 2\sqrt{x})x}{c_3x + \sqrt{x}} \tag{1}$$

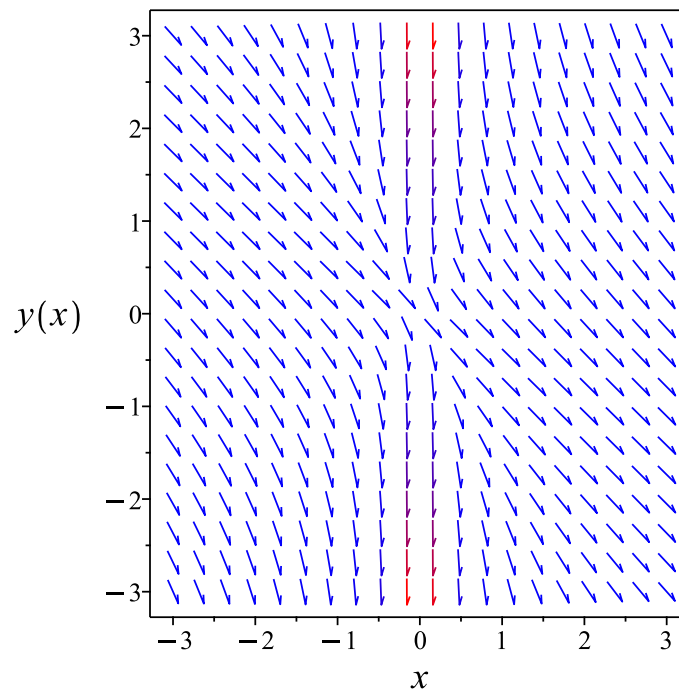


Figure 270: Slope field plot

Verification of solutions

$$y = \frac{(-c_3x - 2\sqrt{x})x}{c_3x + \sqrt{x}}$$

Verified OK.

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
trying Bernoulli  
trying separable  
trying inverse linear  
trying homogeneous types:  
trying homogeneous D  
<- homogeneous successful`
```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 49

```
dsolve((2*x^2+x*y(x)+y(x)^2)+(2*x^2)*diff(y(x),x)=0,y(x), singsol=all)
```

$$y(x) = -\frac{(c_1x - \sqrt{c_1x - 2})x}{c_1x - 1}$$
$$y(x) = -\frac{(c_1x + \sqrt{c_1x - 2})x}{c_1x - 1}$$

✓ Solution by Mathematica

Time used: 2.203 (sec). Leaf size: 47

```
DSolve[(2*x^2+x*y[x]+y[x]^2)+(2*x^2)*y'[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{x(\sqrt{x} - 2e^{c_1})}{-\sqrt{x} + e^{c_1}}$$
$$y(x) \rightarrow -2x$$
$$y(x) \rightarrow -x$$

6.9 problem 9

- 6.9.1 Solving as first order ode lie symmetry calculated ode 1359
6.9.2 Solving as exact ode 1365

Internal problem ID [11683]

Internal file name [OUTPUT/11692_Wednesday_April_10_2024_04_54_48_PM_84959607/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 2, Miscellaneous Review. Exercises page 60

Problem number: 9.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"exactWithIntegrationFactor",
"first_order_ode_lie_symmetry_calculated"**

Maple gives the following as the ode type

```
[[_homogeneous, `class G`], _rational, [_Abel, `2nd type`, `class B`]]
```

$$y' - \frac{4y^2x^3 - 3x^2y}{x^3 - 2yx^4} = 0$$

6.9.1 Solving as first order ode lie symmetry calculated ode

Writing the ode as

$$y' = -\frac{y(4xy - 3)}{x(2xy - 1)}$$
$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is not in the lookup table. To determine ξ, η then (A) is solved using ansatz. Making bivariate polynomials of degree 1 to use as anstaz gives

$$\xi = xa_2 + ya_3 + a_1 \quad (1\text{E})$$

$$\eta = xb_2 + yb_3 + b_1 \quad (2\text{E})$$

Where the unknown coefficients are

$$\{a_1, a_2, a_3, b_1, b_2, b_3\}$$

Substituting equations (1E,2E) and ω into (A) gives

$$\begin{aligned} b_2 - \frac{y(4xy-3)(b_3-a_2)}{x(2xy-1)} - \frac{y^2(4xy-3)^2 a_3}{x^2(2xy-1)^2} \\ - \left(\frac{y(4xy-3)}{x^2(2xy-1)} - \frac{4y^2}{x(2xy-1)} + \frac{2y^2(4xy-3)}{x(2xy-1)^2} \right) (xa_2 + ya_3 + a_1) \\ - \left(-\frac{4xy-3}{x(2xy-1)} - \frac{4y}{2xy-1} + \frac{2y(4xy-3)}{(2xy-1)^2} \right) (xb_2 + yb_3 + b_1) = 0 \end{aligned} \quad (5E)$$

Putting the above in normal form gives

$$\frac{12x^4y^2b_2 - 24x^2y^4a_3 + 8x^3y^2b_1 - 8x^2y^3a_1 - 12x^3yb_2 + 2x^2y^2a_2 + 2x^2y^2b_3 + 36xy^3a_3 - 8x^2yb_1 + 12xy^2a_1}{x^2(2xy-1)^2} = 0$$

Setting the numerator to zero gives

$$\begin{aligned} 12x^4y^2b_2 - 24x^2y^4a_3 + 8x^3y^2b_1 - 8x^2y^3a_1 - 12x^3yb_2 + 2x^2y^2a_2 + 2x^2y^2b_3 \\ + 36xy^3a_3 - 8x^2yb_1 + 12xy^2a_1 + 4b_2x^2 - 12y^2a_3 + 3xb_1 - 3ya_1 = 0 \end{aligned} \quad (6E)$$

Looking at the above PDE shows the following are all the terms with $\{x, y\}$ in them.

$$\{x, y\}$$

The following substitution is now made to be able to collect on all terms with $\{x, y\}$ in them

$$\{x = v_1, y = v_2\}$$

The above PDE (6E) now becomes

$$\begin{aligned} -24a_3v_1^2v_2^4 + 12b_2v_1^4v_2^2 - 8a_1v_1^2v_2^3 + 8b_1v_1^3v_2^2 + 2a_2v_1^2v_2^2 + 36a_3v_1v_2^3 - 12b_2v_1^3v_2 \\ + 2b_3v_1^2v_2^2 + 12a_1v_1v_2^2 - 8b_1v_1^2v_2 - 12a_3v_2^2 + 4b_2v_1^2 - 3a_1v_2 + 3b_1v_1 = 0 \end{aligned} \quad (7E)$$

Collecting the above on the terms v_i introduced, and these are

$$\{v_1, v_2\}$$

Equation (7E) now becomes

$$12b_2v_1^4v_2^2 + 8b_1v_1^3v_2^2 - 12b_2v_1^3v_2 - 24a_3v_1^2v_2^4 - 8a_1v_1^2v_2^3 + (2a_2 + 2b_3)v_1^2v_2^2 - 8b_1v_1^2v_2 + 4b_2v_1^2 + 36a_3v_1v_2^3 + 12a_1v_1v_2^2 + 3b_1v_1 - 12a_3v_2^2 - 3a_1v_2 = 0 \quad (8E)$$

Setting each coefficients in (8E) to zero gives the following equations to solve

$$\begin{aligned} -8a_1 &= 0 \\ -3a_1 &= 0 \\ 12a_1 &= 0 \\ -24a_3 &= 0 \\ -12a_3 &= 0 \\ 36a_3 &= 0 \\ -8b_1 &= 0 \\ 3b_1 &= 0 \\ 8b_1 &= 0 \\ -12b_2 &= 0 \\ 4b_2 &= 0 \\ 12b_2 &= 0 \\ 2a_2 + 2b_3 &= 0 \end{aligned}$$

Solving the above equations for the unknowns gives

$$\begin{aligned} a_1 &= 0 \\ a_2 &= -b_3 \\ a_3 &= 0 \\ b_1 &= 0 \\ b_2 &= 0 \\ b_3 &= b_3 \end{aligned}$$

Substituting the above solution in the ansatz (1E,2E) (using 1 as arbitrary value for any unknown in the RHS) gives

$$\begin{aligned} \xi &= -x \\ \eta &= y \end{aligned}$$

Shifting is now applied to make $\xi = 0$ in order to simplify the rest of the computation

$$\begin{aligned}\eta &= \eta - \omega(x, y) \xi \\ &= y - \left(-\frac{y(4xy - 3)}{x(2xy - 1)} \right) (-x) \\ &= \frac{-2xy^2 + 2y}{2xy - 1} \\ \xi &= 0\end{aligned}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \quad (1)$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y} \right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned}S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{-2xy^2 + 2y}{2xy - 1}} dy\end{aligned}$$

Which results in

$$S = -\frac{\ln(y(xy - 1))}{2}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{y(4xy - 3)}{x(2xy - 1)}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= -\frac{y}{2xy - 2} \\ S_y &= \frac{-2xy + 1}{2y(xy - 1)} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = \frac{3}{2x} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = \frac{3}{2R}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = \frac{3 \ln(R)}{2} + c_1 \quad (4)$$

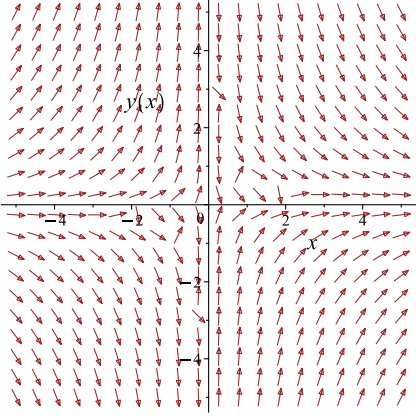
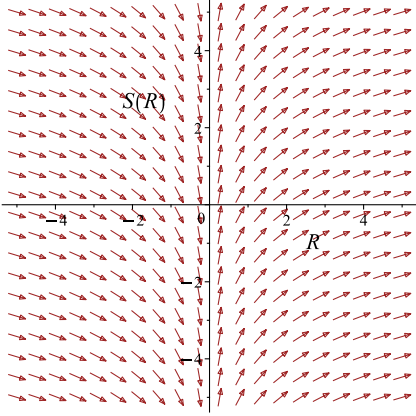
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$-\frac{\ln(y)}{2} - \frac{\ln(yx - 1)}{2} = \frac{3 \ln(x)}{2} + c_1$$

Which simplifies to

$$-\frac{\ln(y)}{2} - \frac{\ln(yx - 1)}{2} = \frac{3 \ln(x)}{2} + c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{y(4xy-3)}{x(2xy-1)}$ 	$R = x$ $S = -\frac{\ln(y)}{2} - \frac{\ln(xy-1)}{2}$	$\frac{dS}{dR} = \frac{3}{2R}$ 

Summary

The solution(s) found are the following

$$-\frac{\ln(y)}{2} - \frac{\ln(yx-1)}{2} = \frac{3\ln(x)}{2} + c_1 \tag{1}$$

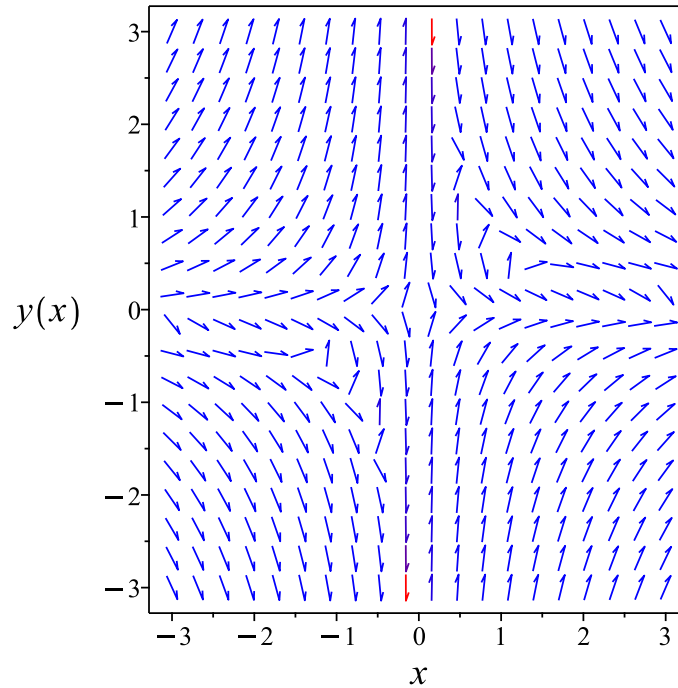


Figure 271: Slope field plot

Verification of solutions

$$-\frac{\ln(y)}{2} - \frac{\ln(yx - 1)}{2} = \frac{3 \ln(x)}{2} + c_1$$

Verified OK.

6.9.2 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (1A)$$

Therefore

$$\begin{aligned}dy &= \left(\frac{4y^2x^3 - 3x^2y}{-2x^4y + x^3} \right) dx \\ \left(-\frac{4y^2x^3 - 3x^2y}{-2x^4y + x^3} \right) dx + dy &= 0\end{aligned} \quad (2A)$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= -\frac{4y^2x^3 - 3x^2y}{-2x^4y + x^3} \\ N(x, y) &= 1\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y} \left(-\frac{4y^2x^3 - 3x^2y}{-2x^4y + x^3} \right) \\ &= \frac{8x^2y^2 - 8xy + 3}{x(2xy - 1)^2}\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(1) \\ &= 0\end{aligned}$$

Since $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$\begin{aligned}A &= \frac{1}{N} \left(\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} \right) \\ &= 1 \left(\left(-\frac{8yx^3 - 3x^2}{-2x^4y + x^3} - \frac{2(4y^2x^3 - 3x^2y)x^4}{(-2x^4y + x^3)^2} \right) - (0) \right) \\ &= \frac{8x^2y^2 - 8xy + 3}{x(2xy - 1)^2}\end{aligned}$$

Since A depends on y , it can not be used to obtain an integrating factor. We will now try a second method to find an integrating factor. Let

$$\begin{aligned}B &= \frac{1}{M} \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) \\ &= \frac{2x^2y - x}{4xy^2 - 3y} \left((0) - \left(-\frac{8yx^3 - 3x^2}{-2x^4y + x^3} - \frac{2(4y^2x^3 - 3x^2y)x^4}{(-2x^4y + x^3)^2} \right) \right) \\ &= \frac{-8x^2y^2 + 8xy - 3}{8y^3x^2 - 10xy^2 + 3y}\end{aligned}$$

Since B depends on x , it can not be used to obtain an integrating factor. We will now try a third method to find an integrating factor. Let

$$R = \frac{\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y}}{xM - yN}$$

R is now checked to see if it is a function of only $t = xy$. Therefore

$$\begin{aligned}R &= \frac{\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y}}{xM - yN} \\ &= \frac{(0) - \left(-\frac{8yx^3 - 3x^2}{-2x^4y + x^3} - \frac{2(4y^2x^3 - 3x^2y)x^4}{(-2x^4y + x^3)^2} \right)}{x \left(-\frac{4y^2x^3 - 3x^2y}{-2x^4y + x^3} \right) - y(1)} \\ &= \frac{-8x^2y^2 + 8xy - 3}{4x(xy - 1)y \left(xy - \frac{1}{2} \right)}\end{aligned}$$

Replacing all powers of terms xy by t gives

$$R = \frac{-8t^2 + 8t - 3}{4t(t-1)\left(t - \frac{1}{2}\right)}$$

Since R depends on t only, then it can be used to find an integrating factor. Let the integrating factor be μ then

$$\begin{aligned}\mu &= e^{\int R dt} \\ &= e^{\int \left(\frac{-8t^2 + 8t - 3}{4t(t-1)\left(t - \frac{1}{2}\right)}\right) dt}\end{aligned}$$

The result of integrating gives

$$\begin{aligned}\mu &= e^{-\frac{3\ln(t-1)}{2} - \frac{3\ln(t)}{2} + \ln(2t-1)} \\ &= \frac{2t-1}{(t-1)^{\frac{3}{2}} t^{\frac{3}{2}}}\end{aligned}$$

Now t is replaced back with xy giving

$$\mu = \frac{2xy-1}{(xy-1)^{\frac{3}{2}} (xy)^{\frac{3}{2}}}$$

Multiplying M and N by this integrating factor gives new M and new N which are called \bar{M} and \bar{N} so not to confuse them with the original M and N

$$\begin{aligned}\bar{M} &= \mu M \\ &= \frac{2xy-1}{(xy-1)^{\frac{3}{2}} (xy)^{\frac{3}{2}}} \left(-\frac{4y^2x^3 - 3x^2y}{-2x^4y + x^3} \right) \\ &= \frac{4xy-3}{x^2\sqrt{xy} (xy-1)^{\frac{3}{2}}}\end{aligned}$$

And

$$\begin{aligned}\bar{N} &= \mu N \\ &= \frac{2xy-1}{(xy-1)^{\frac{3}{2}} (xy)^{\frac{3}{2}}} (1) \\ &= \frac{2xy-1}{(xy-1)^{\frac{3}{2}} xy\sqrt{xy}}\end{aligned}$$

A modified ODE is now obtained from the original ODE, which is exact and can be solved. The modified ODE is

$$\begin{aligned}\bar{M} + \bar{N} \frac{dy}{dx} &= 0 \\ \left(\frac{4xy-3}{x^2\sqrt{xy} (xy-1)^{\frac{3}{2}}} \right) + \left(\frac{2xy-1}{(xy-1)^{\frac{3}{2}} xy\sqrt{xy}} \right) \frac{dy}{dx} &= 0\end{aligned}$$

The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = \bar{M} \quad (1)$$

$$\frac{\partial \phi}{\partial y} = \bar{N} \quad (2)$$

Integrating (1) w.r.t. x gives

$$\begin{aligned} \int \frac{\partial \phi}{\partial x} dx &= \int \bar{M} dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int \frac{4xy - 3}{x^2 \sqrt{xy} (xy - 1)^{\frac{3}{2}}} dx \\ \phi &= -\frac{2}{\sqrt{xy - 1} x \sqrt{xy}} + f(y) \end{aligned} \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\begin{aligned} \frac{\partial \phi}{\partial y} &= \frac{1}{(xy - 1)^{\frac{3}{2}} \sqrt{xy}} + \frac{1}{\sqrt{xy - 1} (xy)^{\frac{3}{2}}} + f'(y) \\ &= \frac{2xy - 1}{(xy - 1)^{\frac{3}{2}} xy \sqrt{xy}} + f'(y) \end{aligned} \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = \frac{2xy - 1}{(xy - 1)^{\frac{3}{2}} xy \sqrt{xy}}$. Therefore equation (4) becomes

$$\frac{2xy - 1}{(xy - 1)^{\frac{3}{2}} xy \sqrt{xy}} = \frac{2xy - 1}{(xy - 1)^{\frac{3}{2}} xy \sqrt{xy}} + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 0$$

Therefore

$$f(y) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(y)$ into equation (3) gives ϕ

$$\phi = -\frac{2}{\sqrt{xy - 1} x \sqrt{xy}} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -\frac{2}{\sqrt{xy-1}x\sqrt{xy}}$$

Summary

The solution(s) found are the following

$$-\frac{2}{\sqrt{yx-1}x\sqrt{yx}} = c_1 \tag{1}$$

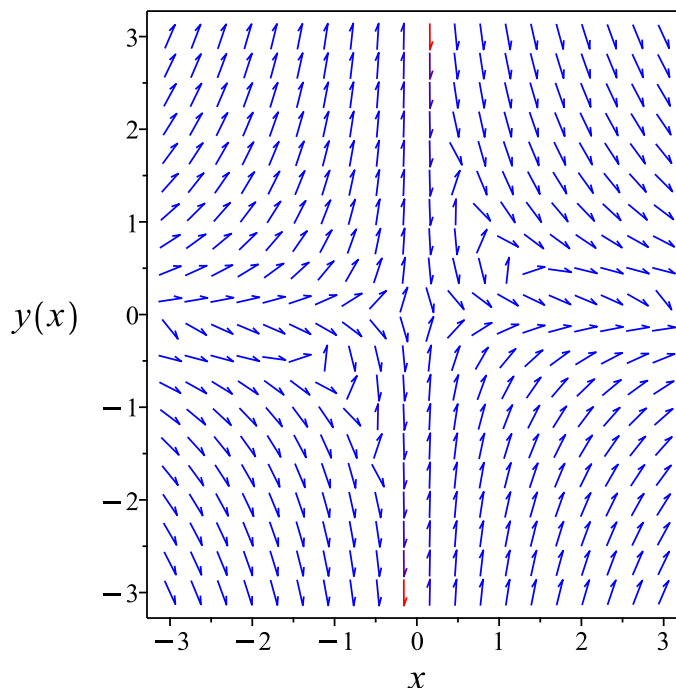


Figure 272: Slope field plot

Verification of solutions

$$-\frac{2}{\sqrt{yx-1}x\sqrt{yx}} = c_1$$

Verified OK.

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
trying Bernoulli  
trying separable  
trying inverse linear  
trying homogeneous types:  
trying homogeneous G  
<- homogeneous successful`
```

✓ Solution by Maple

Time used: 0.078 (sec). Leaf size: 41

```
dsolve(diff(y(x),x)=(4*x^3*y(x)^2-3*x^2*y(x))/(x^3-2*x^4*y(x)),y(x), singsol=all)
```

$$y(x) = \frac{x - \sqrt{x^2 + 4c_1}}{2x^2}$$
$$y(x) = \frac{x + \sqrt{x^2 + 4c_1}}{2x^2}$$

✓ Solution by Mathematica

Time used: 0.575 (sec). Leaf size: 78

```
DSolve[y'[x]==(4*x^3*y[x]^2-3*x^2*y[x])/(x^3-2*x^4*y[x]),y[x],x,IncludeSingularSolutions ->
```

$$y(x) \rightarrow \frac{x^3 - \sqrt{x^2} \sqrt{x^4 + 4c_1 x^2}}{2x^4}$$
$$y(x) \rightarrow \frac{x^3 + \sqrt{x^2} \sqrt{x^4 + 4c_1 x^2}}{2x^4}$$

6.10 problem 10

6.10.1 Solving as linear ode	1372
6.10.2 Solving as first order ode lie symmetry lookup ode	1374
6.10.3 Solving as exact ode	1378
6.10.4 Maple step by step solution	1383

Internal problem ID [11684]

Internal file name [OUTPUT/11693_Wednesday_April_10_2024_04_54_49_PM_86942080/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, Miscellaneous Review. Exercises page 60

Problem number: 10.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"linear", "exactWithIntegrationFactor", "first_order_ode_lie_symmetry_lookup"**

Maple gives the following as the ode type

`[_linear]`

$$(1 + x)y' + yx = e^{-x}$$

6.10.1 Solving as linear ode

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = \frac{x}{1+x}$$
$$q(x) = \frac{e^{-x}}{1+x}$$

Hence the ode is

$$y' + \frac{xy}{1+x} = \frac{e^{-x}}{1+x}$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int \frac{x}{1+x} dx} \\ &= e^{x - \ln(1+x)}\end{aligned}$$

Which simplifies to

$$\mu = \frac{e^x}{1+x}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu y) &= (\mu) \left(\frac{e^{-x}}{1+x} \right) \\ \frac{d}{dx} \left(\frac{e^x y}{1+x} \right) &= \left(\frac{e^x}{1+x} \right) \left(\frac{e^{-x}}{1+x} \right) \\ d \left(\frac{e^x y}{1+x} \right) &= \frac{1}{(1+x)^2} dx\end{aligned}$$

Integrating gives

$$\begin{aligned}\frac{e^x y}{1+x} &= \int \frac{1}{(1+x)^2} dx \\ \frac{e^x y}{1+x} &= -\frac{1}{1+x} + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = \frac{e^x}{1+x}$ results in

$$y = -e^{-x} + c_1(1+x)e^{-x}$$

which simplifies to

$$y = e^{-x}(c_1 x + c_1 - 1)$$

Summary

The solution(s) found are the following

$$y = e^{-x}(c_1 x + c_1 - 1) \tag{1}$$

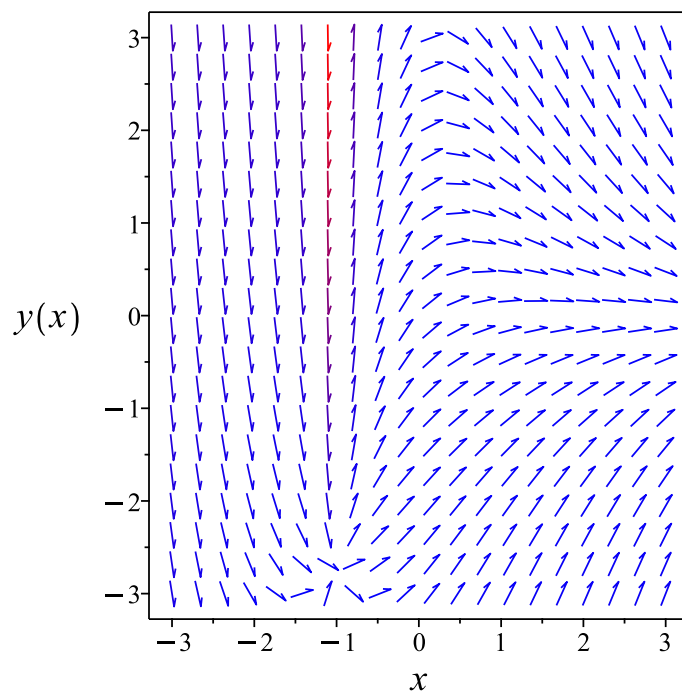


Figure 273: Slope field plot

Verification of solutions

$$y = e^{-x}(c_1x + c_1 - 1)$$

Verified OK.

6.10.2 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = \frac{-xy + e^{-x}}{1+x}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2\xi_y - \omega_x\xi - \omega_y\eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 219: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= e^{-x+\ln(1+x)}\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{e^{-x+\ln(1+x)}} dy \end{aligned}$$

Which results in

$$S = \frac{e^x y}{1+x}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = \frac{-xy + e^{-x}}{1+x}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= \frac{e^x y x}{(1+x)^2} \\ S_y &= \frac{e^x}{1+x} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = \frac{1}{(1+x)^2} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = \frac{1}{(1+R)^2}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = -\frac{1}{1+R} + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$\frac{e^x y}{1+x} = -\frac{1}{1+x} + c_1$$

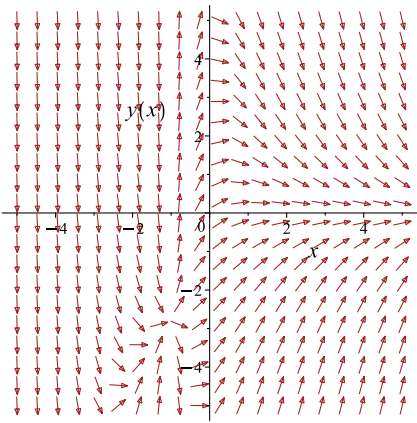
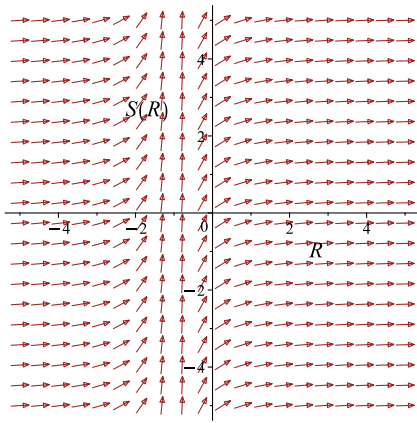
Which simplifies to

$$\frac{e^x y}{1+x} = -\frac{1}{1+x} + c_1$$

Which gives

$$y = e^{-x}(c_1 x + c_1 - 1)$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = \frac{-xy + e^{-x}}{1+x}$ 	$R = x$ $S = \frac{e^x y}{1+x}$	$\frac{dS}{dR} = \frac{1}{(1+R)^2}$ 

Summary

The solution(s) found are the following

$$y = e^{-x}(c_1 x + c_1 - 1) \quad (1)$$

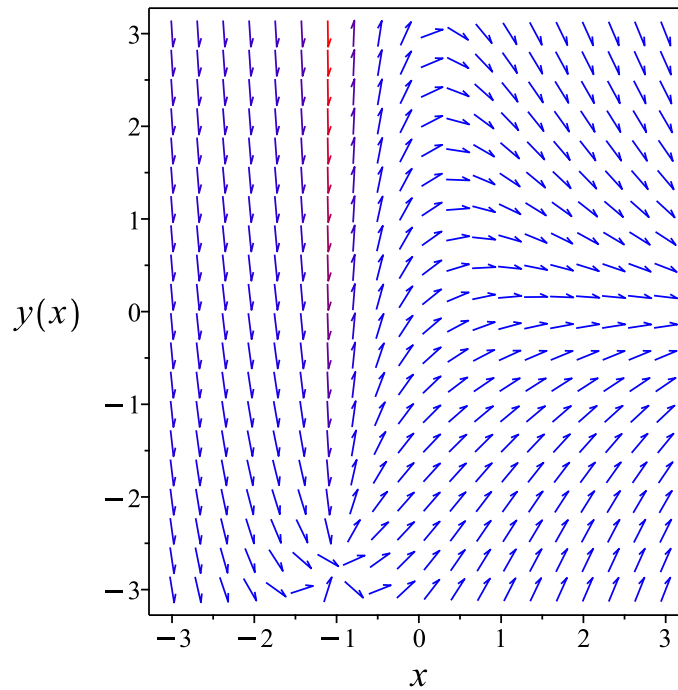


Figure 274: Slope field plot

Verification of solutions

$$y = e^{-x}(c_1x + c_1 - 1)$$

Verified OK.

6.10.3 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx}\phi(x, y) = 0$$

Hence

$$\frac{\partial\phi}{\partial x} + \frac{\partial\phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \tag{1A}$$

Therefore

$$\begin{aligned}(1+x) dy &= (-xy + e^{-x}) dx \\ (xy - e^{-x}) dx + (1+x) dy &= 0\end{aligned} \tag{2A}$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= xy - e^{-x} \\ N(x, y) &= 1 + x\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(xy - e^{-x}) \\ &= x\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(1+x) \\ &= 1\end{aligned}$$

Since $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$\begin{aligned} A &= \frac{1}{N} \left(\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} \right) \\ &= \frac{1}{1+x} ((x) - (1)) \\ &= \frac{x-1}{1+x} \end{aligned}$$

Since A does not depend on y , then it can be used to find an integrating factor. The integrating factor μ is

$$\begin{aligned} \mu &= e^{\int A dx} \\ &= e^{\int \frac{x-1}{1+x} dx} \end{aligned}$$

The result of integrating gives

$$\begin{aligned} \mu &= e^{x-2\ln(1+x)} \\ &= \frac{e^x}{(1+x)^2} \end{aligned}$$

M and N are multiplied by this integrating factor, giving new M and new N which are called \bar{M} and \bar{N} for now so not to confuse them with the original M and N .

$$\begin{aligned} \bar{M} &= \mu M \\ &= \frac{e^x}{(1+x)^2} (xy - e^{-x}) \\ &= \frac{x e^x y - 1}{(1+x)^2} \end{aligned}$$

And

$$\begin{aligned} \bar{N} &= \mu N \\ &= \frac{e^x}{(1+x)^2} (1+x) \\ &= \frac{e^x}{1+x} \end{aligned}$$

Now a modified ODE is obtained from the original ODE, which is exact and can be solved. The modified ODE is

$$\begin{aligned} \bar{M} + \bar{N} \frac{dy}{dx} &= 0 \\ \left(\frac{x e^x y - 1}{(1+x)^2} \right) + \left(\frac{e^x}{1+x} \right) \frac{dy}{dx} &= 0 \end{aligned}$$

The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = \overline{M} \quad (1)$$

$$\frac{\partial \phi}{\partial y} = \overline{N} \quad (2)$$

Integrating (1) w.r.t. x gives

$$\int \frac{\partial \phi}{\partial x} dx = \int \overline{M} dx$$

$$\int \frac{\partial \phi}{\partial x} dx = \int \frac{x e^x y - 1}{(1+x)^2} dx$$

$$\phi = \frac{e^x y + 1}{1+x} + f(y) \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = \frac{e^x}{1+x} + f'(y) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = \frac{e^x}{1+x}$. Therefore equation (4) becomes

$$\frac{e^x}{1+x} = \frac{e^x}{1+x} + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 0$$

Therefore

$$f(y) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(y)$ into equation (3) gives ϕ

$$\phi = \frac{e^x y + 1}{1+x} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = \frac{e^x y + 1}{1+x}$$

The solution becomes

$$y = e^{-x}(c_1x + c_1 - 1)$$

Summary

The solution(s) found are the following

$$y = e^{-x}(c_1x + c_1 - 1) \tag{1}$$

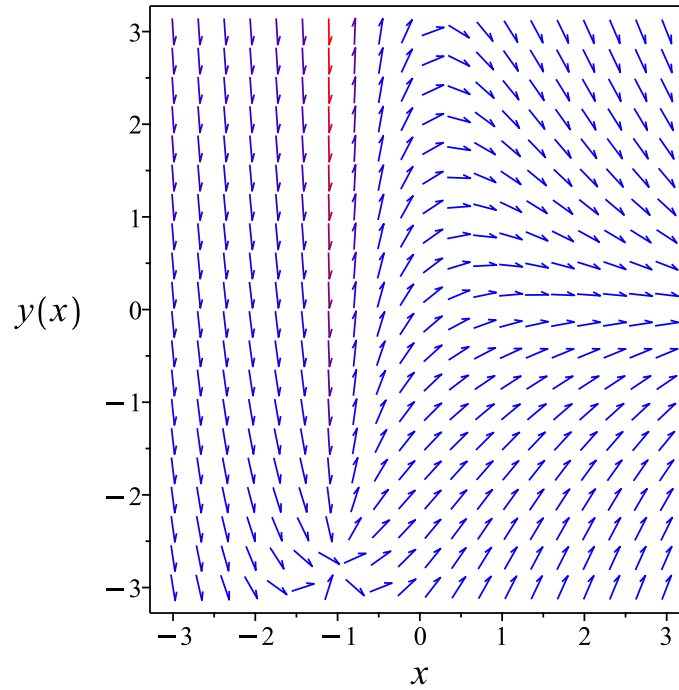


Figure 275: Slope field plot

Verification of solutions

$$y = e^{-x}(c_1x + c_1 - 1)$$

Verified OK.

6.10.4 Maple step by step solution

Let's solve

$$(1+x)y' + yx = e^{-x}$$

- Highest derivative means the order of the ODE is 1

$$y'$$

- Isolate the derivative

$$y' = -\frac{xy}{1+x} + \frac{e^{-x}}{1+x}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE

$$y' + \frac{xy}{1+x} = \frac{e^{-x}}{1+x}$$

- The ODE is linear; multiply by an integrating factor $\mu(x)$

$$\mu(x) \left(y' + \frac{xy}{1+x} \right) = \frac{\mu(x)e^{-x}}{1+x}$$

- Assume the lhs of the ODE is the total derivative $\frac{d}{dx}(\mu(x)y)$

$$\mu(x) \left(y' + \frac{xy}{1+x} \right) = \mu'(x)y + \mu(x)y'$$

- Isolate $\mu'(x)$

$$\mu'(x) = \frac{\mu(x)x}{1+x}$$

- Solve to find the integrating factor

$$\mu(x) = \frac{e^x}{1+x}$$

- Integrate both sides with respect to x

$$\int \left(\frac{d}{dx}(\mu(x)y) \right) dx = \int \frac{\mu(x)e^{-x}}{1+x} dx + c_1$$

- Evaluate the integral on the lhs

$$\mu(x)y = \int \frac{\mu(x)e^{-x}}{1+x} dx + c_1$$

- Solve for y

$$y = \frac{\int \frac{\mu(x)e^{-x}}{1+x} dx + c_1}{\mu(x)}$$

- Substitute $\mu(x) = \frac{e^x}{1+x}$

$$y = \frac{(1+x) \left(\int \frac{e^{-x}e^x}{(1+x)^2} dx + c_1 \right)}{e^x}$$

- Evaluate the integrals on the rhs

$$y = \frac{(1+x) \left(-\frac{1}{1+x} + c_1 \right)}{e^x}$$

- Simplify

$$y = e^{-x}(c_1x + c_1 - 1)$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
<- 1st order linear successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 15

```
dsolve((x+1)*diff(y(x),x)+x*y(x)=exp(-x),y(x), singsol=all)
```

$$y(x) = e^{-x}(c_1x + c_1 - 1)$$

✓ Solution by Mathematica

Time used: 0.062 (sec). Leaf size: 19

```
DSolve[(x+1)*y'[x]+x*y[x]==Exp[-x],y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^{-x}(-1 + c_1(x + 1))$$

6.11 problem 11

6.11.1 Solving as homogeneousTypeD2 ode 1385

6.11.2 Solving as first order ode lie symmetry calculated ode 1387

Internal problem ID [11685]

Internal file name [OUTPUT/11694_Wednesday_April_10_2024_04_54_50_PM_17922417/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 2, Miscellaneous Review. Exercises page 60

Problem number: 11.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**homogeneousTypeD2**", "**first_order_ode_lie_symmetry_calculated**"

Maple gives the following as the ode type

```
[[_homogeneous, `class A`], _rational, [_Abel, `2nd type`, `class A`]]
```

$$y' - \frac{2x - 7y}{3y - 8x} = 0$$

6.11.1 Solving as homogeneousTypeD2 ode

Using the change of variables $y = u(x)x$ on the above ode results in new ode in $u(x)$

$$u'(x)x + u(x) - \frac{2x - 7u(x)x}{3u(x)x - 8x} = 0$$

In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= -\frac{3u^2 - u - 2}{x(3u - 8)} \end{aligned}$$

Where $f(x) = -\frac{1}{x}$ and $g(u) = \frac{3u^2-u-2}{3u-8}$. Integrating both sides gives

$$\begin{aligned}\frac{1}{\frac{3u^2-u-2}{3u-8}} du &= -\frac{1}{x} dx \\ \int \frac{1}{\frac{3u^2-u-2}{3u-8}} du &= \int -\frac{1}{x} dx \\ -\ln(u-1) + 2\ln(3u+2) &= -\ln(x) + c_2\end{aligned}$$

Raising both side to exponential gives

$$e^{-\ln(u-1)+2\ln(3u+2)} = e^{-\ln(x)+c_2}$$

Which simplifies to

$$\frac{(3u+2)^2}{u-1} = \frac{c_3}{x}$$

The solution is

$$\frac{(3u(x)+2)^2}{u(x)-1} = \frac{c_3}{x}$$

Replacing $u(x)$ in the above solution by $\frac{y}{x}$ results in the solution for y in implicit form

$$\begin{aligned}\frac{\left(\frac{3y}{x}+2\right)^2}{\frac{y}{x}-1} &= \frac{c_3}{x} \\ \frac{(2x+3y)^2}{(y-x)x} &= \frac{c_3}{x}\end{aligned}$$

Which simplifies to

$$-\frac{(2x+3y)^2}{-y+x} = c_3$$

Summary

The solution(s) found are the following

$$-\frac{(2x+3y)^2}{-y+x} = c_3 \quad (1)$$

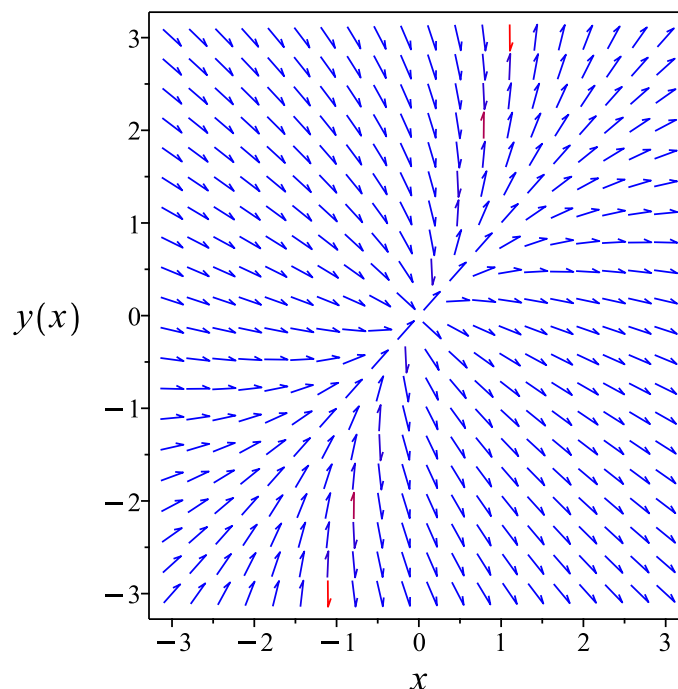


Figure 276: Slope field plot

Verification of solutions

$$-\frac{(2x + 3y)^2}{-y + x} = c_3$$

Verified OK.

6.11.2 Solving as first order ode lie symmetry calculated ode

Writing the ode as

$$y' = -\frac{-2x + 7y}{3y - 8x}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is not in the lookup table. To determine ξ, η then (A) is solved using ansatz. Making bivariate polynomials of degree 1 to use as anstaz gives

$$\xi = xa_2 + ya_3 + a_1 \quad (1\text{E})$$

$$\eta = xb_2 + yb_3 + b_1 \quad (2\text{E})$$

Where the unknown coefficients are

$$\{a_1, a_2, a_3, b_1, b_2, b_3\}$$

Substituting equations (1E,2E) and ω into (A) gives

$$\begin{aligned} b_2 - \frac{(-2x + 7y)(b_3 - a_2)}{3y - 8x} - \frac{(-2x + 7y)^2 a_3}{(3y - 8x)^2} \\ - \left(\frac{2}{3y - 8x} - \frac{8(-2x + 7y)}{(3y - 8x)^2} \right) (xa_2 + ya_3 + a_1) \\ - \left(-\frac{7}{3y - 8x} + \frac{-6x + 21y}{(3y - 8x)^2} \right) (xb_2 + yb_3 + b_1) = 0 \end{aligned} \quad (5E)$$

Putting the above in normal form gives

$$\frac{16x^2a_2 - 4x^2a_3 + 14x^2b_2 - 16x^2b_3 - 12xya_2 + 28xya_3 - 48xyb_2 + 12xyb_3 + 21y^2a_2 + y^2a_3 + 9y^2b_2 - 21y^2b_3}{(-3y + 8x)^2} = 0$$

Setting the numerator to zero gives

$$\begin{aligned} 16x^2a_2 - 4x^2a_3 + 14x^2b_2 - 16x^2b_3 - 12xya_2 + 28xya_3 - 48xyb_2 \\ + 12xyb_3 + 21y^2a_2 + y^2a_3 + 9y^2b_2 - 21y^2b_3 - 50xb_1 + 50ya_1 = 0 \end{aligned} \quad (6E)$$

Looking at the above PDE shows the following are all the terms with $\{x, y\}$ in them.

$$\{x, y\}$$

The following substitution is now made to be able to collect on all terms with $\{x, y\}$ in them

$$\{x = v_1, y = v_2\}$$

The above PDE (6E) now becomes

$$\begin{aligned} 16a_2v_1^2 - 12a_2v_1v_2 + 21a_2v_2^2 - 4a_3v_1^2 + 28a_3v_1v_2 + a_3v_2^2 + 14b_2v_1^2 \\ - 48b_2v_1v_2 + 9b_2v_2^2 - 16b_3v_1^2 + 12b_3v_1v_2 - 21b_3v_2^2 + 50a_1v_2 - 50b_1v_1 = 0 \end{aligned} \quad (7E)$$

Collecting the above on the terms v_i introduced, and these are

$$\{v_1, v_2\}$$

Equation (7E) now becomes

$$(16a_2 - 4a_3 + 14b_2 - 16b_3)v_1^2 + (-12a_2 + 28a_3 - 48b_2 + 12b_3)v_1v_2 - 50b_1v_1 + (21a_2 + a_3 + 9b_2 - 21b_3)v_2^2 + 50a_1v_2 = 0 \quad (8E)$$

Setting each coefficients in (8E) to zero gives the following equations to solve

$$\begin{aligned} 50a_1 &= 0 \\ -50b_1 &= 0 \\ -12a_2 + 28a_3 - 48b_2 + 12b_3 &= 0 \\ 16a_2 - 4a_3 + 14b_2 - 16b_3 &= 0 \\ 21a_2 + a_3 + 9b_2 - 21b_3 &= 0 \end{aligned}$$

Solving the above equations for the unknowns gives

$$\begin{aligned} a_1 &= 0 \\ a_2 &= a_2 \\ a_3 &= -3a_2 + 3b_3 \\ b_1 &= 0 \\ b_2 &= -2a_2 + 2b_3 \\ b_3 &= b_3 \end{aligned}$$

Substituting the above solution in the ansatz (1E,2E) (using 1 as arbitrary value for any unknown in the RHS) gives

$$\begin{aligned} \xi &= 3y \\ \eta &= 2x + y \end{aligned}$$

Shifting is now applied to make $\xi = 0$ in order to simplify the rest of the computation

$$\begin{aligned} \eta &= \eta - \omega(x, y) \xi \\ &= 2x + y - \left(-\frac{-2x + 7y}{3y - 8x} \right) (3y) \\ &= \frac{16x^2 + 8xy - 24y^2}{-3y + 8x} \\ \xi &= 0 \end{aligned}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \quad (1)$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{16x^2 + 8xy - 24y^2}{-3y + 8x}} dy \end{aligned}$$

Which results in

$$S = \frac{\ln(2x + 3y)}{4} - \frac{\ln(y - x)}{8}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{-2x + 7y}{3y - 8x}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= \frac{2x - 7y}{16x^2 + 8xy - 24y^2} \\ S_y &= \frac{-3y + 8x}{16x^2 + 8xy - 24y^2} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 0 \tag{2A}$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 0$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = c_1 \tag{4}$$

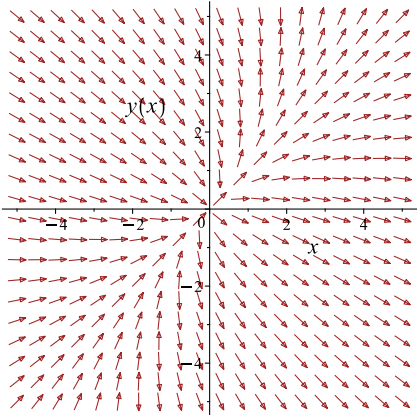
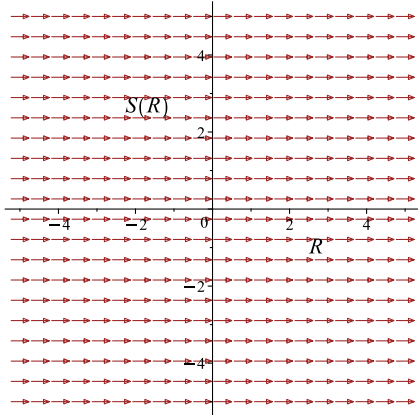
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$\frac{\ln(2x + 3y)}{4} - \frac{\ln(y - x)}{8} = c_1$$

Which simplifies to

$$\frac{\ln(2x + 3y)}{4} - \frac{\ln(y - x)}{8} = c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{-2x+7y}{3y-8x}$ 	$R = x$ $S = \frac{\ln(2x + 3y)}{4} - \frac{\ln(y - x)}{8}$	$\frac{dS}{dR} = 0$ 

Summary

The solution(s) found are the following

$$\frac{\ln(2x + 3y)}{4} - \frac{\ln(y - x)}{8} = c_1 \quad (1)$$

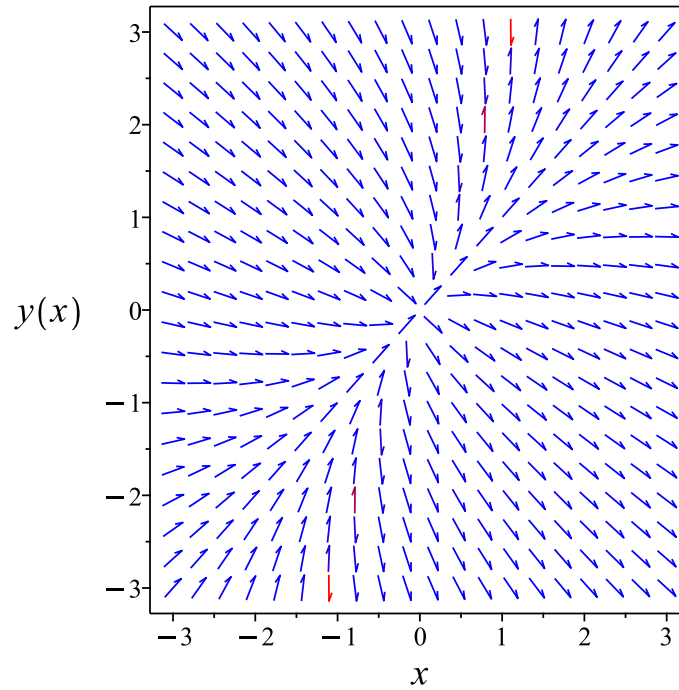


Figure 277: Slope field plot

Verification of solutions

$$\frac{\ln(2x + 3y)}{4} - \frac{\ln(y - x)}{8} = c_1$$

Verified OK.

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
trying Bernoulli  
trying separable  
trying inverse linear  
trying homogeneous types:  
trying homogeneous D  
<- homogeneous successful`
```

✓ Solution by Maple

Time used: 0.032 (sec). Leaf size: 47

```
dsolve(diff(y(x),x)=(2*x-7*y(x))/(3*y(x)-8*x),y(x), singsol=all)
```

$$y(x) = \frac{-12c_1x - \sqrt{-60c_1x + 1} + 1}{18c_1}$$
$$y(x) = \frac{-12c_1x + 1 + \sqrt{-60c_1x + 1}}{18c_1}$$

✓ Solution by Mathematica

Time used: 0.969 (sec). Leaf size: 80

```
DSolve[y'[x]==(2*x-7*y[x])/(3*y[x]-8*x),y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{1}{18} \left(-12x - e^{\frac{c_1}{2}} \sqrt{60x + e^{c_1}} - e^{c_1} \right)$$
$$y(x) \rightarrow \frac{1}{18} \left(-12x + e^{\frac{c_1}{2}} \sqrt{60x + e^{c_1}} - e^{c_1} \right)$$

6.12 problem 12

6.12.1 Solving as separable ode	1394
6.12.2 Solving as first order ode lie symmetry lookup ode	1396
6.12.3 Solving as bernoulli ode	1400
6.12.4 Solving as exact ode	1404
6.12.5 Maple step by step solution	1407

Internal problem ID [11686]

Internal file name [OUTPUT/11695_Wednesday_April_10_2024_04_54_52_PM_34915414/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 2, Miscellaneous Review. Exercises page 60

Problem number: 12.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact", "bernoulli", "separable", "first_order_ode_lie_symmetry_lookup"

Maple gives the following as the ode type

[_separable]

$$x^2y' + yx - y^3x = 0$$

6.12.1 Solving as separable ode

In canonical form the ODE is

$$\begin{aligned}y' &= F(x, y) \\ &= f(x)g(y) \\ &= \frac{y^3 - y}{x}\end{aligned}$$

Where $f(x) = \frac{1}{x}$ and $g(y) = y^3 - y$. Integrating both sides gives

$$\begin{aligned}\frac{1}{y^3 - y} dy &= \frac{1}{x} dx \\ \int \frac{1}{y^3 - y} dy &= \int \frac{1}{x} dx\end{aligned}$$

$$\frac{\ln(y-1)}{2} + \frac{\ln(y+1)}{2} - \ln(y) = \ln(x) + c_1$$

Raising both side to exponential gives

$$e^{\frac{\ln(y-1)}{2} + \frac{\ln(y+1)}{2} - \ln(y)} = e^{\ln(x) + c_1}$$

Which simplifies to

$$\frac{\sqrt{y-1} \sqrt{y+1}}{y} = c_2 x$$

The solution is

$$\frac{\sqrt{y-1} \sqrt{y+1}}{y} = c_2 x$$

Summary

The solution(s) found are the following

$$\frac{\sqrt{y-1} \sqrt{y+1}}{y} = c_2 x \tag{1}$$

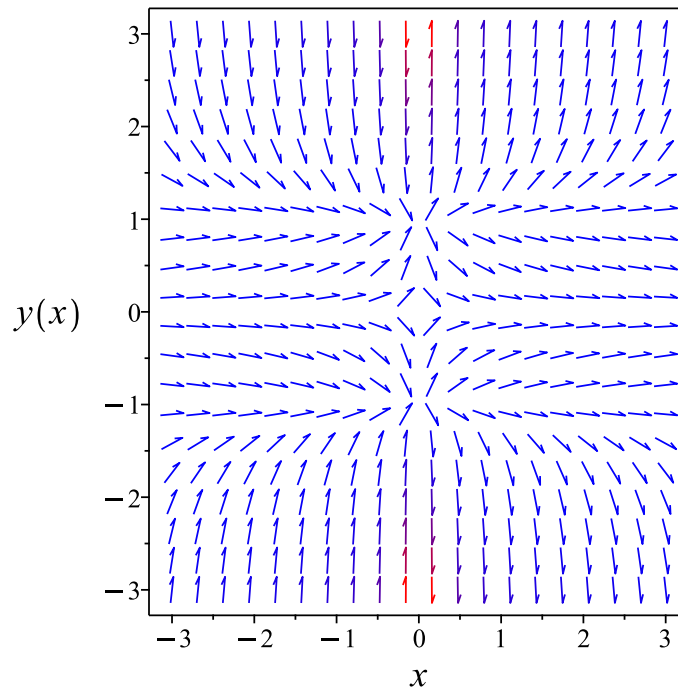


Figure 278: Slope field plot

Verification of solutions

$$\frac{\sqrt{y-1}\sqrt{y+1}}{y} = c_2x$$

Verified OK.

6.12.2 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = \frac{y(y^2 - 1)}{x}$$
$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2\xi_y - \omega_x\xi - \omega_y\eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **separable**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 222: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= x \\ \eta(x, y) &= 0\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\eta = 0$ then in this special case

$$R = y$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\xi} dx \\ &= \int \frac{1}{x} dx \end{aligned}$$

Which results in

$$S = \ln(x)$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = \frac{y(y^2 - 1)}{x}$$

Evaluating all the partial derivatives gives

$$R_x = 0$$

$$R_y = 1$$

$$S_x = \frac{1}{x}$$

$$S_y = 0$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = \frac{1}{y^3 - y} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = \frac{1}{R^3 - R}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = \frac{\ln(R-1)}{2} + \frac{\ln(R+1)}{2} - \ln(R) + c_1 \quad (4)$$

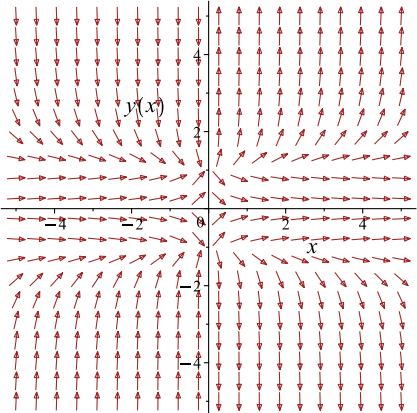
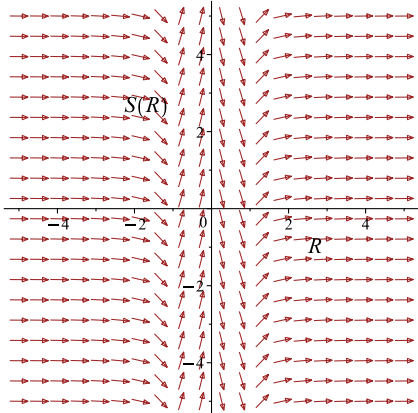
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$\ln(x) = \frac{\ln(y-1)}{2} + \frac{\ln(y+1)}{2} - \ln(y) + c_1$$

Which simplifies to

$$\ln(x) = \frac{\ln(y-1)}{2} + \frac{\ln(y+1)}{2} - \ln(y) + c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = \frac{y(y^2-1)}{x}$ 	$R = y$ $S = \ln(x)$	$\frac{dS}{dR} = \frac{1}{R^3-R}$ 

Summary

The solution(s) found are the following

$$\ln(x) = \frac{\ln(y-1)}{2} + \frac{\ln(y+1)}{2} - \ln(y) + c_1 \quad (1)$$

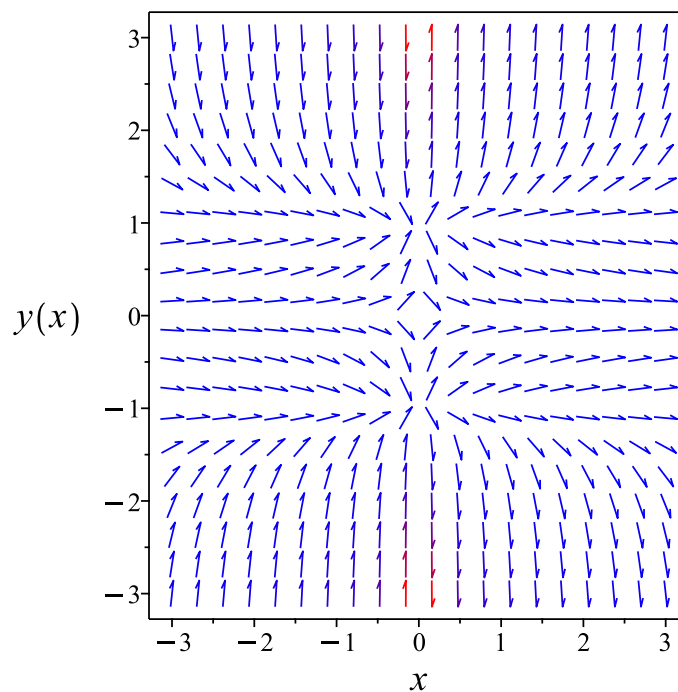


Figure 279: Slope field plot

Verification of solutions

$$\ln(x) = \frac{\ln(y-1)}{2} + \frac{\ln(y+1)}{2} - \ln(y) + c_1$$

Verified OK.

6.12.3 Solving as bernoulli ode

In canonical form, the ODE is

$$\begin{aligned} y' &= F(x, y) \\ &= \frac{y(y^2 - 1)}{x} \end{aligned}$$

This is a Bernoulli ODE.

$$y' = -\frac{1}{x}y + \frac{1}{x}y^3 \quad (1)$$

The standard Bernoulli ODE has the form

$$y' = f_0(x)y + f_1(x)y^n \quad (2)$$

The first step is to divide the above equation by y^n which gives

$$\frac{y'}{y^n} = f_0(x)y^{1-n} + f_1(x) \quad (3)$$

The next step is use the substitution $w = y^{1-n}$ in equation (3) which generates a new ODE in $w(x)$ which will be linear and can be easily solved using an integrating factor. Backsubstitution then gives the solution $y(x)$ which is what we want.

This method is now applied to the ODE at hand. Comparing the ODE (1) With (2) Shows that

$$\begin{aligned}f_0(x) &= -\frac{1}{x} \\f_1(x) &= \frac{1}{x} \\n &= 3\end{aligned}$$

Dividing both sides of ODE (1) by $y^n = y^3$ gives

$$y' \frac{1}{y^3} = -\frac{1}{x y^2} + \frac{1}{x} \quad (4)$$

Let

$$\begin{aligned}w &= y^{1-n} \\&= \frac{1}{y^2}\end{aligned} \quad (5)$$

Taking derivative of equation (5) w.r.t x gives

$$w' = -\frac{2}{y^3} y' \quad (6)$$

Substituting equations (5) and (6) into equation (4) gives

$$\begin{aligned}-\frac{w'(x)}{2} &= -\frac{w(x)}{x} + \frac{1}{x} \\w' &= \frac{2w}{x} - \frac{2}{x}\end{aligned} \quad (7)$$

The above now is a linear ODE in $w(x)$ which is now solved.

Entering Linear first order ODE solver. In canonical form a linear first order is

$$w'(x) + p(x)w(x) = q(x)$$

Where here

$$\begin{aligned}p(x) &= -\frac{2}{x} \\q(x) &= -\frac{2}{x}\end{aligned}$$

Hence the ode is

$$w'(x) - \frac{2w(x)}{x} = -\frac{2}{x}$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int -\frac{2}{x} dx} \\ &= \frac{1}{x^2}\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu w) &= (\mu) \left(-\frac{2}{x}\right) \\ \frac{d}{dx}\left(\frac{w}{x^2}\right) &= \left(\frac{1}{x^2}\right) \left(-\frac{2}{x}\right) \\ d\left(\frac{w}{x^2}\right) &= \left(-\frac{2}{x^3}\right) dx\end{aligned}$$

Integrating gives

$$\begin{aligned}\frac{w}{x^2} &= \int -\frac{2}{x^3} dx \\ \frac{w}{x^2} &= \frac{1}{x^2} + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = \frac{1}{x^2}$ results in

$$w(x) = c_1 x^2 + 1$$

Replacing w in the above by $\frac{1}{y^2}$ using equation (5) gives the final solution.

$$\frac{1}{y^2} = c_1 x^2 + 1$$

Solving for y gives

$$\begin{aligned}y(x) &= \frac{1}{\sqrt{c_1 x^2 + 1}} \\ y(x) &= -\frac{1}{\sqrt{c_1 x^2 + 1}}\end{aligned}$$

Summary

The solution(s) found are the following

$$y = \frac{1}{\sqrt{c_1 x^2 + 1}} \quad (1)$$

$$y = -\frac{1}{\sqrt{c_1 x^2 + 1}} \quad (2)$$

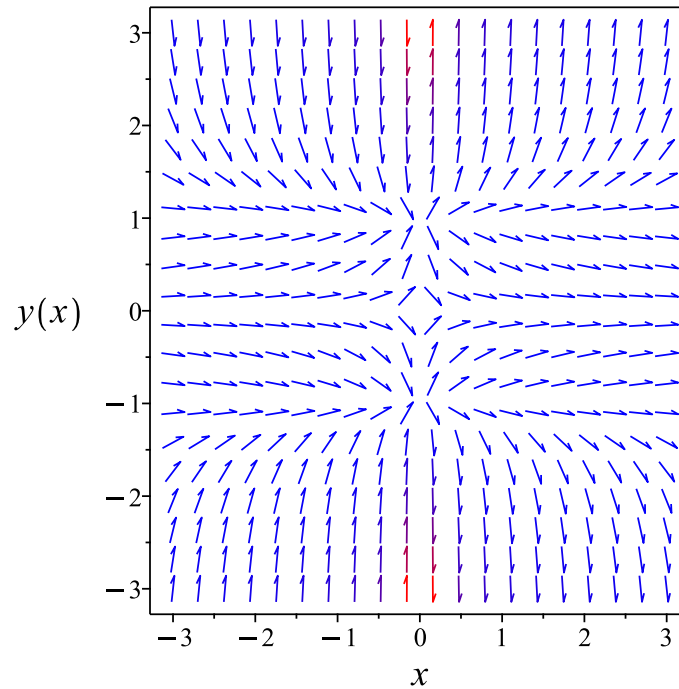


Figure 280: Slope field plot

Verification of solutions

$$y = \frac{1}{\sqrt{c_1 x^2 + 1}}$$

Verified OK.

$$y = -\frac{1}{\sqrt{c_1 x^2 + 1}}$$

Verified OK.

6.12.4 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \quad (\text{A})$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx}\phi(x, y) = 0$$

Hence

$$\frac{\partial\phi}{\partial x} + \frac{\partial\phi}{\partial y} \frac{dy}{dx} = 0 \quad (\text{B})$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial\phi}{\partial x} &= M \\ \frac{\partial\phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (\text{1A})$$

Therefore

$$\begin{aligned} \left(\frac{1}{y(y^2-1)}\right) dy &= \left(\frac{1}{x}\right) dx \\ \left(-\frac{1}{x}\right) dx + \left(\frac{1}{y(y^2-1)}\right) dy &= 0 \end{aligned} \quad (\text{2A})$$

Comparing (1A) and (2A) shows that

$$M(x, y) = -\frac{1}{x}$$
$$N(x, y) = \frac{1}{y(y^2 - 1)}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\frac{\partial M}{\partial y} = \frac{\partial}{\partial y} \left(-\frac{1}{x} \right)$$
$$= 0$$

And

$$\frac{\partial N}{\partial x} = \frac{\partial}{\partial x} \left(\frac{1}{y(y^2 - 1)} \right)$$
$$= 0$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \tag{1}$$

$$\frac{\partial \phi}{\partial y} = N \tag{2}$$

Integrating (1) w.r.t. x gives

$$\int \frac{\partial \phi}{\partial x} dx = \int M dx$$
$$\int \frac{\partial \phi}{\partial x} dx = \int -\frac{1}{x} dx$$
$$\phi = -\ln(x) + f(y) \tag{3}$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = 0 + f'(y) \tag{4}$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = \frac{1}{y(y^2-1)}$. Therefore equation (4) becomes

$$\frac{1}{y(y^2-1)} = 0 + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$\begin{aligned} f'(y) &= \frac{1}{y(y^2-1)} \\ &= \frac{1}{y^3-y} \end{aligned}$$

Integrating the above w.r.t y results in

$$\begin{aligned} \int f'(y) dy &= \int \left(\frac{1}{y^3-y} \right) dy \\ f(y) &= \frac{\ln(y-1)}{2} + \frac{\ln(y+1)}{2} - \ln(y) + c_1 \end{aligned}$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = -\ln(x) + \frac{\ln(y-1)}{2} + \frac{\ln(y+1)}{2} - \ln(y) + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -\ln(x) + \frac{\ln(y-1)}{2} + \frac{\ln(y+1)}{2} - \ln(y)$$

Summary

The solution(s) found are the following

$$-\ln(x) + \frac{\ln(y-1)}{2} + \frac{\ln(y+1)}{2} - \ln(y) = c_1 \quad (1)$$

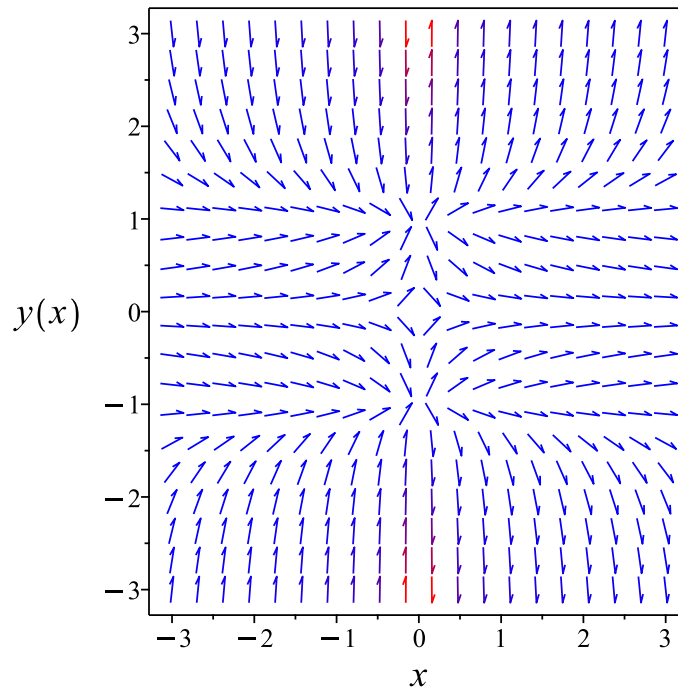


Figure 281: Slope field plot

Verification of solutions

$$-\ln(x) + \frac{\ln(y-1)}{2} + \frac{\ln(y+1)}{2} - \ln(y) = c_1$$

Verified OK.

6.12.5 Maple step by step solution

Let's solve

$$x^2 y' + yx - y^3 x = 0$$

- Highest derivative means the order of the ODE is 1

y'

- Separate variables

$$\frac{y'}{y(y-1)(y+1)} = \frac{1}{x}$$

- Integrate both sides with respect to x

$$\int \frac{y'}{y(y-1)(y+1)} dx = \int \frac{1}{x} dx + c_1$$

- Evaluate integral

$$\frac{\ln(y-1)}{2} + \frac{\ln(y+1)}{2} - \ln(y) = \ln(x) + c_1$$

- Solve for y

$$\left\{ y = -\frac{\sqrt{-(e^{c_1})^2 x^2 + 1} - 1}{\sqrt{-(e^{c_1})^2 x^2 + 1}} + 1, y = -\frac{\sqrt{-(e^{c_1})^2 x^2 + 1} + 1}{\sqrt{-(e^{c_1})^2 x^2 + 1}} + 1 \right\}$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
<- Bernoulli successful`

```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 27

```
dsolve(x^2*diff(y(x),x)+x*y(x)=x*y(x)^3,y(x), singsol=all)
```

$$y(x) = \frac{1}{\sqrt{c_1 x^2 + 1}}$$

$$y(x) = -\frac{1}{\sqrt{c_1 x^2 + 1}}$$

✓ Solution by Mathematica

Time used: 0.242 (sec). Leaf size: 58

```
DSolve[x^2*y'[x]+x*y[x]==x*y[x]^3,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow -\frac{1}{\sqrt{1 + e^{2c_1} x^2}}$$

$$y(x) \rightarrow \frac{1}{\sqrt{1 + e^{2c_1} x^2}}$$

$$y(x) \rightarrow -1$$

$$y(x) \rightarrow 0$$

$$y(x) \rightarrow 1$$

6.13 problem 13

6.13.1 Solving as separable ode	1409
6.13.2 Solving as linear ode	1411
6.13.3 Solving as first order ode lie symmetry lookup ode	1413
6.13.4 Solving as exact ode	1417
6.13.5 Maple step by step solution	1421

Internal problem ID [11687]

Internal file name [OUTPUT/11696_Wednesday_April_10_2024_04_54_53_PM_72324803/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, Miscellaneous Review. Exercises page 60

Problem number: 13.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact", "linear", "separable", "first_order_ode_lie_symmetry_lookup"

Maple gives the following as the ode type

[_separable]

$$(x^3 + 1) y' + 6x^2 y = 6x^2$$

6.13.1 Solving as separable ode

In canonical form the ODE is

$$\begin{aligned} y' &= F(x, y) \\ &= f(x)g(y) \\ &= \frac{x^2(-6y + 6)}{x^3 + 1} \end{aligned}$$

Where $f(x) = \frac{x^2}{x^3+1}$ and $g(y) = -6y + 6$. Integrating both sides gives

$$\frac{1}{-6y + 6} dy = \frac{x^2}{x^3 + 1} dx$$

$$\int \frac{1}{-6y+6} dy = \int \frac{x^2}{x^3+1} dx$$

$$-\frac{\ln(y-1)}{6} = \frac{\ln(x^3+1)}{3} + c_1$$

Raising both side to exponential gives

$$\frac{1}{(y-1)^{\frac{1}{6}}} = e^{\frac{\ln(x^3+1)}{3} + c_1}$$

Which simplifies to

$$\frac{1}{(y-1)^{\frac{1}{6}}} = c_2(x^3+1)^{\frac{1}{3}}$$

Which simplifies to

$$y = \frac{\left(c_2^6 e^{6c_1} (x^3+1)^2 + 1\right) e^{-6c_1}}{c_2^6 (x^3+1)^2}$$

Summary

The solution(s) found are the following

$$y = \frac{\left(c_2^6 e^{6c_1} (x^3+1)^2 + 1\right) e^{-6c_1}}{c_2^6 (x^3+1)^2} \quad (1)$$

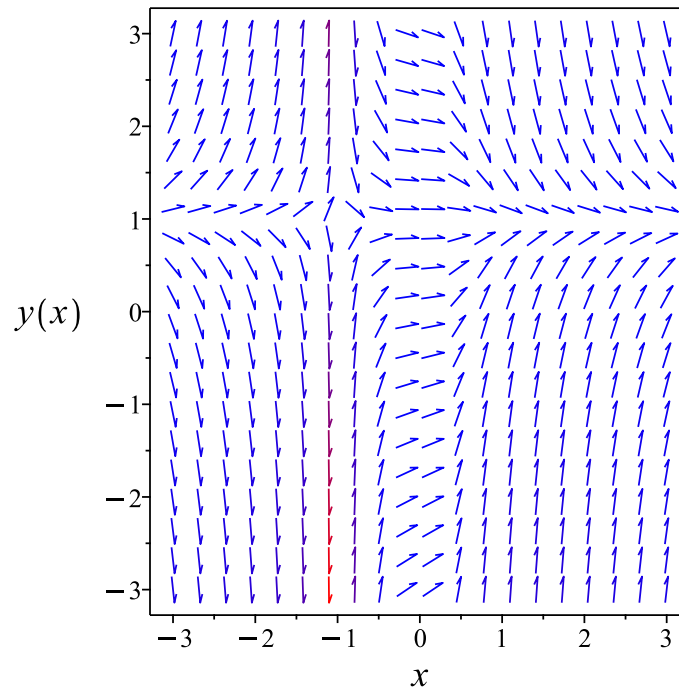


Figure 282: Slope field plot

Verification of solutions

$$y = \frac{\left(c_2^6 e^{6c_1} (x^3 + 1)^2 + 1 \right) e^{-6c_1}}{c_2^6 (x^3 + 1)^2}$$

Verified OK.

6.13.2 Solving as linear ode

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = \frac{6x^2}{x^3 + 1}$$

$$q(x) = \frac{6x^2}{x^3 + 1}$$

Hence the ode is

$$y' + \frac{6x^2 y}{x^3 + 1} = \frac{6x^2}{x^3 + 1}$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int \frac{6x^2}{x^3+1} dx} \\ &= (x^3 + 1)^2\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu y) &= (\mu) \left(\frac{6x^2}{x^3 + 1} \right) \\ \frac{d}{dx} \left((x^3 + 1)^2 y \right) &= \left((x^3 + 1)^2 \right) \left(\frac{6x^2}{x^3 + 1} \right) \\ d \left((x^3 + 1)^2 y \right) &= (6x^5 + 6x^2) dx\end{aligned}$$

Integrating gives

$$\begin{aligned}(x^3 + 1)^2 y &= \int 6x^5 + 6x^2 dx \\ (x^3 + 1)^2 y &= x^6 + 2x^3 + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = (x^3 + 1)^2$ results in

$$y = \frac{x^6 + 2x^3}{(x^3 + 1)^2} + \frac{c_1}{(x^3 + 1)^2}$$

which simplifies to

$$y = \frac{x^6 + 2x^3 + c_1}{(x^3 + 1)^2}$$

Summary

The solution(s) found are the following

$$y = \frac{x^6 + 2x^3 + c_1}{(x^3 + 1)^2} \tag{1}$$

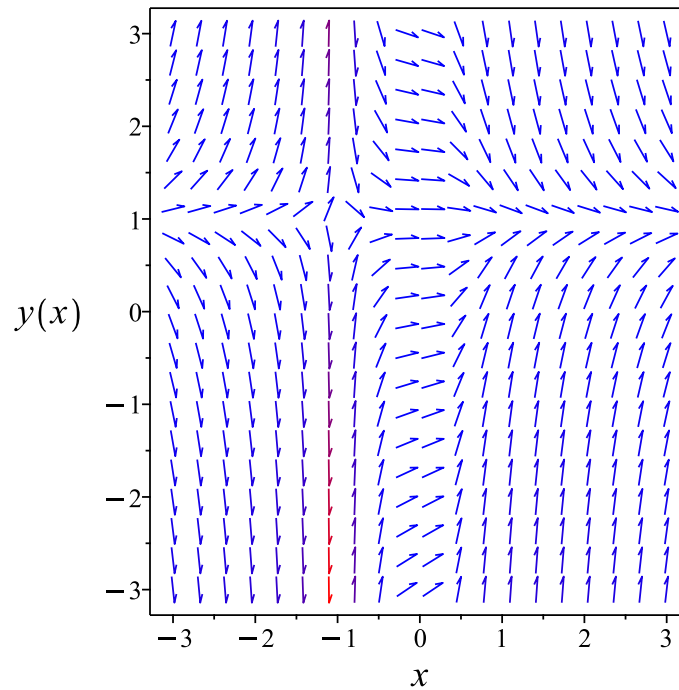


Figure 283: Slope field plot

Verification of solutions

$$y = \frac{x^6 + 2x^3 + c_1}{(x^3 + 1)^2}$$

Verified OK.

6.13.3 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = -\frac{6(y-1)x^2}{x^3+1}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 225: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned} \xi(x, y) &= 0 \\ \eta(x, y) &= \frac{1}{(x^3 + 1)^2} \end{aligned} \tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{1}{(x^3+1)^2}} dy \end{aligned}$$

Which results in

$$S = (x^3 + 1)^2 y$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{6(y-1)x^2}{x^3+1}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= 6x^5y + 6x^2y \\ S_y &= (x^3 + 1)^2 \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 6x^5 + 6x^2 \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 6R^5 + 6R^2$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = R^6 + 2R^3 + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$(x^3 + 1)^2 y = x^6 + 2x^3 + c_1$$

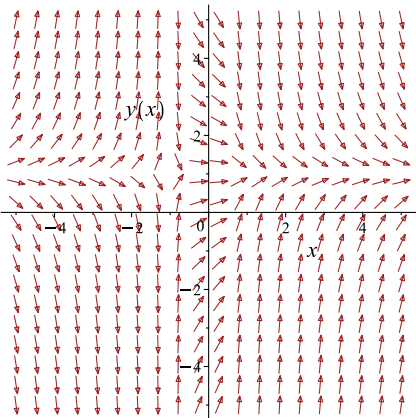
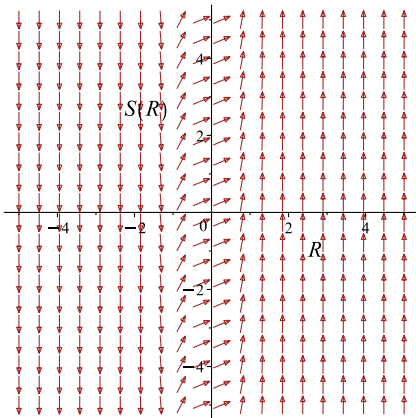
Which simplifies to

$$(x^3 + 1)^2 y = x^6 + 2x^3 + c_1$$

Which gives

$$y = \frac{x^6 + 2x^3 + c_1}{(x^3 + 1)^2}$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{6(y-1)x^2}{x^3+1}$ 	$R = x$ $S = (x^3 + 1)^2 y$	$\frac{dS}{dR} = 6R^5 + 6R^2$ 

Summary

The solution(s) found are the following

$$y = \frac{x^6 + 2x^3 + c_1}{(x^3 + 1)^2} \quad (1)$$

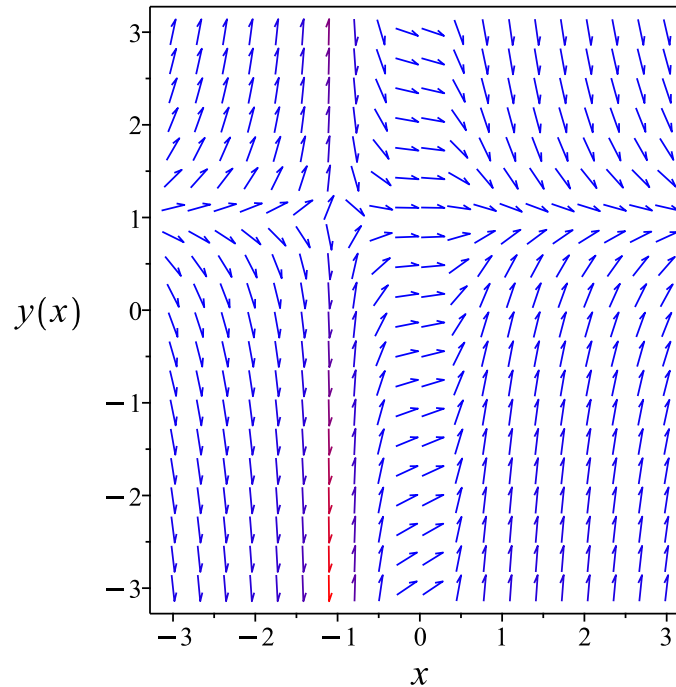


Figure 284: Slope field plot

Verification of solutions

$$y = \frac{x^6 + 2x^3 + c_1}{(x^3 + 1)^2}$$

Verified OK.

6.13.4 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \quad (\text{A})$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the

ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx}\phi(x, y) = 0$$

Hence

$$\frac{\partial\phi}{\partial x} + \frac{\partial\phi}{\partial y} \frac{dy}{dx} = 0 \quad (\text{B})$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial\phi}{\partial x} &= M \\ \frac{\partial\phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (\text{1A})$$

Therefore

$$\begin{aligned} \left(\frac{1}{-6y+6}\right) dy &= \left(\frac{x^2}{x^3+1}\right) dx \\ \left(-\frac{x^2}{x^3+1}\right) dx + \left(\frac{1}{-6y+6}\right) dy &= 0 \end{aligned} \quad (\text{2A})$$

Comparing (1A) and (2A) shows that

$$\begin{aligned} M(x, y) &= -\frac{x^2}{x^3+1} \\ N(x, y) &= \frac{1}{-6y+6} \end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y} \left(-\frac{x^2}{x^3 + 1} \right) \\ &= 0\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x} \left(\frac{1}{-6y + 6} \right) \\ &= 0\end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \tag{1}$$

$$\frac{\partial \phi}{\partial y} = N \tag{2}$$

Integrating (1) w.r.t. x gives

$$\int \frac{\partial \phi}{\partial x} dx = \int M dx$$

$$\int \frac{\partial \phi}{\partial x} dx = \int -\frac{x^2}{x^3 + 1} dx$$

$$\phi = -\frac{\ln(x^3 + 1)}{3} + f(y) \tag{3}$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = 0 + f'(y) \tag{4}$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = \frac{1}{-6y+6}$. Therefore equation (4) becomes

$$\frac{1}{-6y + 6} = 0 + f'(y) \tag{5}$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = -\frac{1}{6(y - 1)}$$

Integrating the above w.r.t y gives

$$\int f'(y) dy = \int \left(-\frac{1}{6y-6} \right) dy$$
$$f(y) = -\frac{\ln(y-1)}{6} + c_1$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = -\frac{\ln(x^3+1)}{3} - \frac{\ln(y-1)}{6} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -\frac{\ln(x^3+1)}{3} - \frac{\ln(y-1)}{6}$$

The solution becomes

$$y = \frac{x^6 + 2x^3 + e^{-6c_1} + 1}{x^6 + 2x^3 + 1}$$

Summary

The solution(s) found are the following

$$y = \frac{x^6 + 2x^3 + e^{-6c_1} + 1}{x^6 + 2x^3 + 1} \tag{1}$$

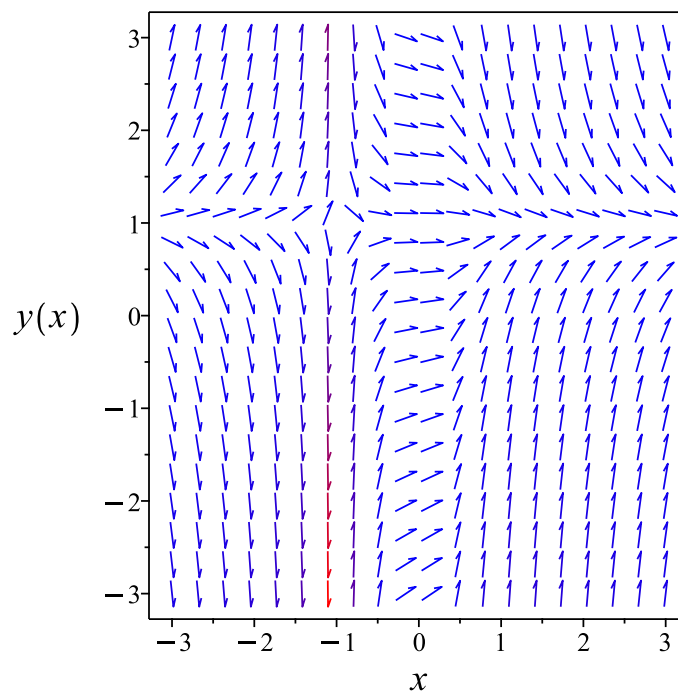


Figure 285: Slope field plot

Verification of solutions

$$y = \frac{x^6 + 2x^3 + e^{-6c_1} + 1}{x^6 + 2x^3 + 1}$$

Verified OK.

6.13.5 Maple step by step solution

Let's solve

$$(x^3 + 1)y' + 6x^2y = 6x^2$$

- Highest derivative means the order of the ODE is 1

y'

- Separate variables

$$\frac{y'}{y-1} = -\frac{6x^2}{(1+x)(x^2-x+1)}$$

- Integrate both sides with respect to x

$$\int \frac{y'}{y-1} dx = \int -\frac{6x^2}{(1+x)(x^2-x+1)} dx + c_1$$

- Evaluate integral

$$\ln(y - 1) = -2 \ln((1 + x)(x^2 - x + 1)) + c_1$$

- Solve for y

$$y = \frac{x^6 + 2x^3 + e^{c_1} + 1}{x^6 + 2x^3 + 1}$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
<- 1st order linear successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 22

```
dsolve((x^3+1)*diff(y(x),x)+6*x^2*y(x)=6*x^2,y(x), singsol=all)
```

$$y(x) = \frac{x^6 + 2x^3 + c_1}{(x^3 + 1)^2}$$

✓ Solution by Mathematica

Time used: 0.033 (sec). Leaf size: 29

```
DSolve[(x^3+1)*y'[x]+6*x^2*y[x]==6*x^2,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{x^6 + 2x^3 + c_1}{(x^3 + 1)^2}$$

$$y(x) \rightarrow 1$$

6.14 problem 14

- 6.14.1 Solving as homogeneousTypeD2 ode 1423
- 6.14.2 Solving as first order ode lie symmetry calculated ode 1425
- 6.14.3 Solving as exact ode 1431

Internal problem ID [11688]

Internal file name [OUTPUT/11697_Wednesday_April_10_2024_04_54_54_PM_9116467/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, Miscellaneous Review. Exercises page 60

Problem number: 14.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"homogeneousTypeD2", "exactWithIntegrationFactor", "first_order_ode_lie_symmetry_calculated"**

Maple gives the following as the ode type

```
[[_homogeneous, `class A`], _rational, [_Abel, `2nd type`, `class B`]]
```

$$y' - \frac{2x^2 + y^2}{2yx - x^2} = 0$$

6.14.1 Solving as homogeneousTypeD2 ode

Using the change of variables $y = u(x)x$ on the above ode results in new ode in $u(x)$

$$u'(x)x + u(x) - \frac{2x^2 + u(x)^2 x^2}{2u(x)x^2 - x^2} = 0$$

In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= -\frac{u^2 - u - 2}{x(2u - 1)} \end{aligned}$$

Where $f(x) = -\frac{1}{x}$ and $g(u) = \frac{u^2-u-2}{2u-1}$. Integrating both sides gives

$$\frac{1}{\frac{u^2-u-2}{2u-1}} du = -\frac{1}{x} dx$$

$$\int \frac{1}{\frac{u^2-u-2}{2u-1}} du = \int -\frac{1}{x} dx$$

$$\ln(u^2 - u - 2) = -\ln(x) + c_2$$

Raising both side to exponential gives

$$u^2 - u - 2 = e^{-\ln(x)+c_2}$$

Which simplifies to

$$u^2 - u - 2 = \frac{c_3}{x}$$

Which simplifies to

$$u(x)^2 - u(x) - 2 = \frac{c_3 e^{c_2}}{x}$$

The solution is

$$u(x)^2 - u(x) - 2 = \frac{c_3 e^{c_2}}{x}$$

Replacing $u(x)$ in the above solution by $\frac{y}{x}$ results in the solution for y in implicit form

$$\frac{y^2}{x^2} - \frac{y}{x} - 2 = \frac{c_3 e^{c_2}}{x}$$

$$\frac{y^2}{x^2} - \frac{y}{x} - 2 = \frac{c_3 e^{c_2}}{x}$$

Which simplifies to

$$\frac{y^2 - yx - 2x^2}{x} = c_3 e^{c_2}$$

Summary

The solution(s) found are the following

$$\frac{y^2 - yx - 2x^2}{x} = c_3 e^{c_2} \quad (1)$$

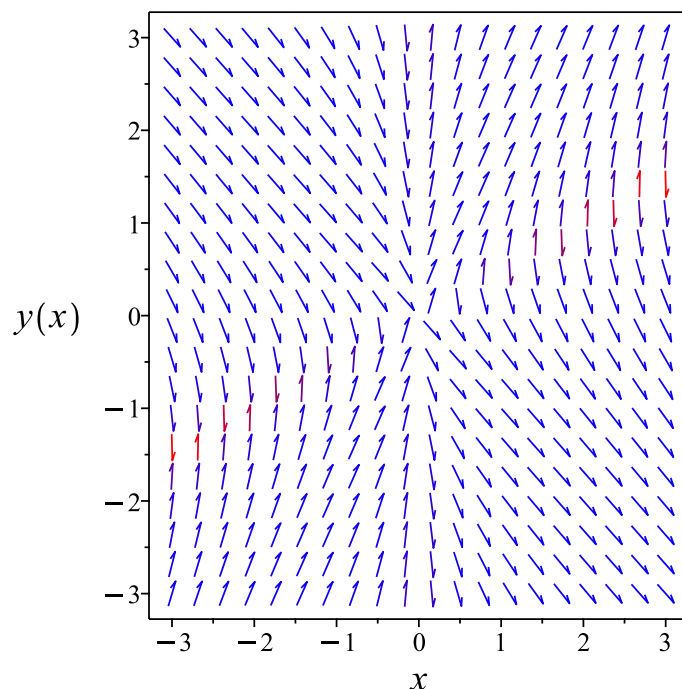


Figure 286: Slope field plot

Verification of solutions

$$\frac{y^2 - yx - 2x^2}{x} = c_3 e^{c_2}$$

Verified OK.

6.14.2 Solving as first order ode lie symmetry calculated ode

Writing the ode as

$$y' = \frac{2x^2 + y^2}{x(-x + 2y)}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is not in the lookup table. To determine ξ, η then (A) is solved using ansatz. Making bivariate polynomials of degree 1 to use as anstaz gives

$$\xi = xa_2 + ya_3 + a_1 \quad (\text{1E})$$

$$\eta = xb_2 + yb_3 + b_1 \quad (\text{2E})$$

Where the unknown coefficients are

$$\{a_1, a_2, a_3, b_1, b_2, b_3\}$$

Substituting equations (1E,2E) and ω into (A) gives

$$\begin{aligned} b_2 + \frac{(2x^2 + y^2)(b_3 - a_2)}{x(-x + 2y)} - \frac{(2x^2 + y^2)^2 a_3}{x^2(-x + 2y)^2} \\ - \left(\frac{4}{-x + 2y} - \frac{2x^2 + y^2}{x^2(-x + 2y)} + \frac{2x^2 + y^2}{x(-x + 2y)^2} \right) (xa_2 + ya_3 + a_1) \\ - \left(\frac{2y}{x(-x + 2y)} - \frac{2(2x^2 + y^2)}{x(-x + 2y)^2} \right) (xb_2 + yb_3 + b_1) = 0 \end{aligned} \quad (5E)$$

Putting the above in normal form gives

$$\frac{2x^4 a_2 - 4x^4 a_3 + 5x^4 b_2 - 2x^4 b_3 - 8x^3 y a_2 - 2x^3 y b_2 + 8x^3 y b_3 - x^2 y^2 a_2 - 8x^2 y^2 a_3 + 2x^2 y^2 b_2 + x^2 y^2 b_3 - 2x^2 y^2 a_1 - 4x^2 y^2 b_1 + 2x^2 y^2 a_1 + 2x^2 y^2 b_1 - 2x^2 y^2 a_1 - 2x^2 y^2 b_1 + 2y^3 a_1}{(x - 2y)^2 x^2} = 0$$

Setting the numerator to zero gives

$$\begin{aligned} 2x^4 a_2 - 4x^4 a_3 + 5x^4 b_2 - 2x^4 b_3 - 8x^3 y a_2 - 2x^3 y b_2 + 8x^3 y b_3 \\ - x^2 y^2 a_2 - 8x^2 y^2 a_3 + 2x^2 y^2 b_2 + x^2 y^2 b_3 - 2x y^3 a_3 + y^4 a_3 \\ + 4x^3 b_1 - 4x^2 y a_1 + 2x^2 y b_1 - 2x y^2 a_1 - 2x y^2 b_1 + 2y^3 a_1 = 0 \end{aligned} \quad (6E)$$

Looking at the above PDE shows the following are all the terms with $\{x, y\}$ in them.

$$\{x, y\}$$

The following substitution is now made to be able to collect on all terms with $\{x, y\}$ in them

$$\{x = v_1, y = v_2\}$$

The above PDE (6E) now becomes

$$\begin{aligned} 2a_2 v_1^4 - 8a_2 v_1^3 v_2 - a_2 v_1^2 v_2^2 - 4a_3 v_1^4 - 8a_3 v_1^2 v_2^2 - 2a_3 v_1 v_2^3 + a_3 v_2^4 \\ + 5b_2 v_1^4 - 2b_2 v_1^3 v_2 + 2b_2 v_1^2 v_2^2 - 2b_3 v_1^4 + 8b_3 v_1^3 v_2 + b_3 v_1^2 v_2^2 \\ - 4a_1 v_1^2 v_2 - 2a_1 v_1 v_2^2 + 2a_1 v_2^3 + 4b_1 v_1^3 + 2b_1 v_1^2 v_2 - 2b_1 v_1 v_2^2 = 0 \end{aligned} \quad (7E)$$

Collecting the above on the terms v_i introduced, and these are

$$\{v_1, v_2\}$$

Equation (7E) now becomes

$$\begin{aligned} &(2a_2 - 4a_3 + 5b_2 - 2b_3) v_1^4 + (-8a_2 - 2b_2 + 8b_3) v_1^3 v_2 \\ &+ 4b_1 v_1^3 + (-a_2 - 8a_3 + 2b_2 + b_3) v_1^2 v_2^2 + (-4a_1 + 2b_1) v_1^2 v_2 \\ &- 2a_3 v_1 v_2^3 + (-2a_1 - 2b_1) v_1 v_2^2 + a_3 v_2^4 + 2a_1 v_2^3 = 0 \end{aligned} \quad (8E)$$

Setting each coefficients in (8E) to zero gives the following equations to solve

$$\begin{aligned} a_3 &= 0 \\ 2a_1 &= 0 \\ -2a_3 &= 0 \\ 4b_1 &= 0 \\ -4a_1 + 2b_1 &= 0 \\ -2a_1 - 2b_1 &= 0 \\ -8a_2 - 2b_2 + 8b_3 &= 0 \\ -a_2 - 8a_3 + 2b_2 + b_3 &= 0 \\ 2a_2 - 4a_3 + 5b_2 - 2b_3 &= 0 \end{aligned}$$

Solving the above equations for the unknowns gives

$$\begin{aligned} a_1 &= 0 \\ a_2 &= b_3 \\ a_3 &= 0 \\ b_1 &= 0 \\ b_2 &= 0 \\ b_3 &= b_3 \end{aligned}$$

Substituting the above solution in the anstaz (1E,2E) (using 1 as arbitrary value for any unknown in the RHS) gives

$$\begin{aligned} \xi &= x \\ \eta &= y \end{aligned}$$

Shifting is now applied to make $\xi = 0$ in order to simplify the rest of the computation

$$\begin{aligned}\eta &= \eta - \omega(x, y) \xi \\ &= y - \left(\frac{2x^2 + y^2}{x(-x + 2y)} \right) (x) \\ &= \frac{2x^2 + xy - y^2}{x - 2y} \\ \xi &= 0\end{aligned}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \quad (1)$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y} \right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned}S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{2x^2 + xy - y^2}{x - 2y}} dy\end{aligned}$$

Which results in

$$S = \ln(-2x^2 - xy + y^2)$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = \frac{2x^2 + y^2}{x(-x + 2y)}$$

Evaluating all the partial derivatives gives

$$\begin{aligned}R_x &= 1 \\R_y &= 0 \\S_x &= \frac{4x + y}{(y + x)(2x - y)} \\S_y &= \frac{x - 2y}{(y + x)(2x - y)}\end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = \frac{1}{x} \tag{2A}$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = \frac{1}{R}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = \ln(R) + c_1 \tag{4}$$

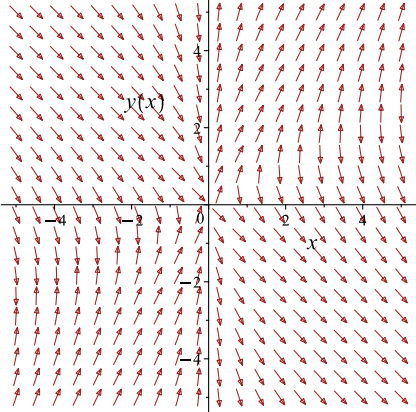
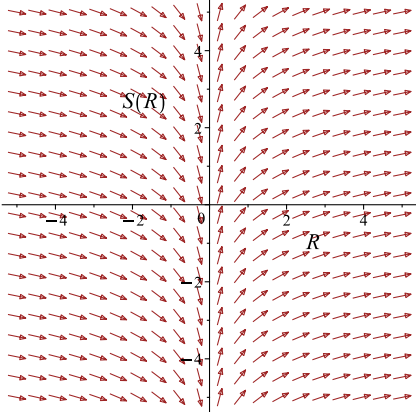
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$\ln(-y - x) + \ln(2x - y) = \ln(x) + c_1$$

Which simplifies to

$$\ln(-y - x) + \ln(2x - y) = \ln(x) + c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = \frac{2x^2 + y^2}{x(-x + 2y)}$ 	$R = x$ $S = \ln(-y - x) + \ln(2x)$	$\frac{dS}{dR} = \frac{1}{R}$ 

Summary

The solution(s) found are the following

$$\ln(-y - x) + \ln(2x - y) = \ln(x) + c_1 \tag{1}$$

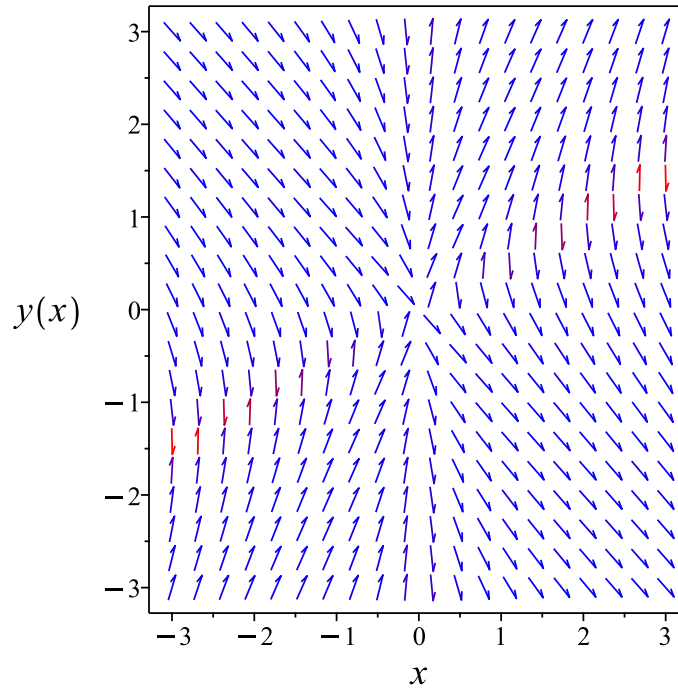


Figure 287: Slope field plot

Verification of solutions

$$\ln(-y - x) + \ln(2x - y) = \ln(x) + c_1$$

Verified OK.

6.14.3 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial\phi}{\partial x} &= M \\ \frac{\partial\phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \tag{1A}$$

Therefore

$$\begin{aligned}(x(-x + 2y)) dy &= (2x^2 + y^2) dx \\ (-2x^2 - y^2) dx + (x(-x + 2y)) dy &= 0\end{aligned} \tag{2A}$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= -2x^2 - y^2 \\ N(x, y) &= x(-x + 2y)\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(-2x^2 - y^2) \\ &= -2y\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(x(-x + 2y)) \\ &= -2x + 2y\end{aligned}$$

Since $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$\begin{aligned} A &= \frac{1}{N} \left(\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} \right) \\ &= -\frac{1}{x(x-2y)} ((-2y) - (-2x+2y)) \\ &= -\frac{2}{x} \end{aligned}$$

Since A does not depend on y , then it can be used to find an integrating factor. The integrating factor μ is

$$\begin{aligned} \mu &= e^{\int A dx} \\ &= e^{\int -\frac{2}{x} dx} \end{aligned}$$

The result of integrating gives

$$\begin{aligned} \mu &= e^{-2 \ln(x)} \\ &= \frac{1}{x^2} \end{aligned}$$

M and N are multiplied by this integrating factor, giving new M and new N which are called \bar{M} and \bar{N} for now so not to confuse them with the original M and N .

$$\begin{aligned} \bar{M} &= \mu M \\ &= \frac{1}{x^2} (-2x^2 - y^2) \\ &= \frac{-2x^2 - y^2}{x^2} \end{aligned}$$

And

$$\begin{aligned} \bar{N} &= \mu N \\ &= \frac{1}{x^2} (x(-x+2y)) \\ &= \frac{-x+2y}{x} \end{aligned}$$

Now a modified ODE is obtained from the original ODE, which is exact and can be solved. The modified ODE is

$$\begin{aligned} \bar{M} + \bar{N} \frac{dy}{dx} &= 0 \\ \left(\frac{-2x^2 - y^2}{x^2} \right) + \left(\frac{-x+2y}{x} \right) \frac{dy}{dx} &= 0 \end{aligned}$$

The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = \bar{M} \quad (1)$$

$$\frac{\partial \phi}{\partial y} = \bar{N} \quad (2)$$

Integrating (1) w.r.t. x gives

$$\begin{aligned} \int \frac{\partial \phi}{\partial x} dx &= \int \bar{M} dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int \frac{-2x^2 - y^2}{x^2} dx \\ \phi &= -2x + \frac{y^2}{x} + f(y) \end{aligned} \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = \frac{2y}{x} + f'(y) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = \frac{-x+2y}{x}$. Therefore equation (4) becomes

$$\frac{-x + 2y}{x} = \frac{2y}{x} + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = -1$$

Integrating the above w.r.t y gives

$$\begin{aligned} \int f'(y) dy &= \int (-1) dy \\ f(y) &= -y + c_1 \end{aligned}$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = -2x + \frac{y^2}{x} - y + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -2x + \frac{y^2}{x} - y$$

Summary

The solution(s) found are the following

$$-2x + \frac{y^2}{x} - y = c_1 \tag{1}$$

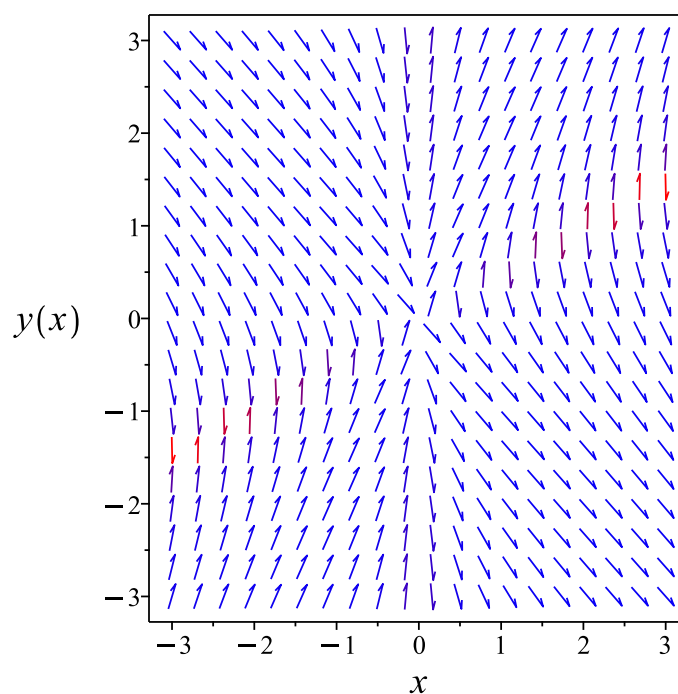


Figure 288: Slope field plot

Verification of solutions

$$-2x + \frac{y^2}{x} - y = c_1$$

Verified OK.

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
trying Bernoulli  
trying separable  
trying inverse linear  
trying homogeneous types:  
trying homogeneous D  
<- homogeneous successful`
```

✓ Solution by Maple

Time used: 0.031 (sec). Leaf size: 57

```
dsolve(diff(y(x),x)=(2*x^2+y(x)^2)/(2*x*y(x)-x^2),y(x), singsol=all)
```

$$y(x) = \frac{c_1 x - \sqrt{9c_1^2 x^2 + 4c_1 x}}{2c_1}$$
$$y(x) = \frac{c_1 x + \sqrt{9c_1^2 x^2 + 4c_1 x}}{2c_1}$$

✓ Solution by Mathematica

Time used: 2.748 (sec). Leaf size: 93

```
DSolve[y'[x]==(2*x^2+y[x]^2)/(2*x*y[x]-x^2),y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{1}{2} \left(x - \sqrt{x(9x - 4e^{c_1})} \right)$$
$$y(x) \rightarrow \frac{1}{2} \left(x + \sqrt{x(9x - 4e^{c_1})} \right)$$
$$y(x) \rightarrow \frac{1}{2} \left(x - 3\sqrt{x^2} \right)$$
$$y(x) \rightarrow \frac{1}{2} \left(3\sqrt{x^2} + x \right)$$

6.15 problem 15

6.15.1 Existence and uniqueness analysis	1437
6.15.2 Solving as homogeneousTypeD2 ode	1438
6.15.3 Solving as first order ode lie symmetry lookup ode	1440
6.15.4 Solving as bernoulli ode	1445
6.15.5 Solving as exact ode	1448

Internal problem ID [11689]

Internal file name [OUTPUT/11698_Wednesday_April_10_2024_04_54_58_PM_46377333/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 2, Miscellaneous Review. Exercises page 60

Problem number: 15.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**bernoulli**", "**homogeneousTypeD2**", "**exactWithIntegrationFactor**", "**first_order_ode_lie_symmetry_lookup**"

Maple gives the following as the ode type

```
[[_homogeneous, `class A`], _rational, _Bernoulli]
```

$$y^2 - 2xyy' = -x^2$$

With initial conditions

$$[y(1) = 2]$$

6.15.1 Existence and uniqueness analysis

This is non linear first order ODE. In canonical form it is written as

$$y' = f(x, y) = \frac{x^2 + y^2}{2yx}$$

The x domain of $f(x, y)$ when $y = 2$ is

$$\{x < 0 \vee 0 < x\}$$

And the point $x_0 = 1$ is inside this domain. The y domain of $f(x, y)$ when $x = 1$ is

$$\{y < 0 \vee 0 < y\}$$

And the point $y_0 = 2$ is inside this domain. Now we will look at the continuity of

$$\begin{aligned} \frac{\partial f}{\partial y} &= \frac{\partial}{\partial y} \left(\frac{x^2 + y^2}{2yx} \right) \\ &= \frac{1}{x} - \frac{x^2 + y^2}{2y^2x} \end{aligned}$$

The x domain of $\frac{\partial f}{\partial y}$ when $y = 2$ is

$$\{x < 0 \vee 0 < x\}$$

And the point $x_0 = 1$ is inside this domain. The y domain of $\frac{\partial f}{\partial y}$ when $x = 1$ is

$$\{y < 0 \vee 0 < y\}$$

And the point $y_0 = 2$ is inside this domain. Therefore solution exists and is unique.

6.15.2 Solving as homogeneous Type D2 ode

Using the change of variables $y = u(x)x$ on the above ode results in new ode in $u(x)$

$$u(x)^2 x^2 - 2x^2 u(x) (u'(x)x + u(x)) = -x^2$$

In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= -\frac{u^2 - 1}{2ux} \end{aligned}$$

Where $f(x) = -\frac{1}{2x}$ and $g(u) = \frac{u^2-1}{u}$. Integrating both sides gives

$$\begin{aligned} \frac{1}{\frac{u^2-1}{u}} du &= -\frac{1}{2x} dx \\ \int \frac{1}{\frac{u^2-1}{u}} du &= \int -\frac{1}{2x} dx \\ \frac{\ln(u-1)}{2} + \frac{\ln(u+1)}{2} &= -\frac{\ln(x)}{2} + c_2 \end{aligned}$$

The above can be written as

$$\begin{aligned}\left(\frac{1}{2}\right) (\ln(u-1) + \ln(u+1)) &= -\frac{\ln(x)}{2} + 2c_2 \\ \ln(u-1) + \ln(u+1) &= (2) \left(-\frac{\ln(x)}{2} + 2c_2\right) \\ &= -\ln(x) + 4c_2\end{aligned}$$

Raising both side to exponential gives

$$e^{\ln(u-1)+\ln(u+1)} = e^{-\ln(x)+2c_2}$$

Which simplifies to

$$\begin{aligned}u^2 - 1 &= \frac{2c_2}{x} \\ &= \frac{c_3}{x}\end{aligned}$$

The solution is

$$u(x)^2 - 1 = \frac{c_3}{x}$$

Replacing $u(x)$ in the above solution by $\frac{y}{x}$ results in the solution for y in implicit form

$$\begin{aligned}\frac{y^2}{x^2} - 1 &= \frac{c_3}{x} \\ \frac{y^2}{x^2} - 1 &= \frac{c_3}{x}\end{aligned}$$

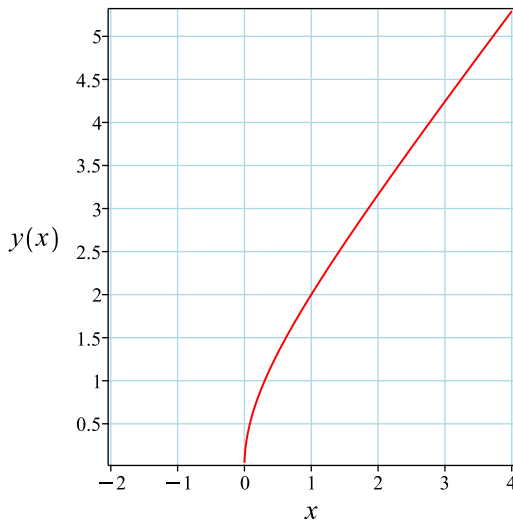
Substituting initial conditions and solving for c_3 gives $c_3 = 3$. Hence the solution becomes Solving for y from the above gives

$$y = \sqrt{x(x+3)}$$

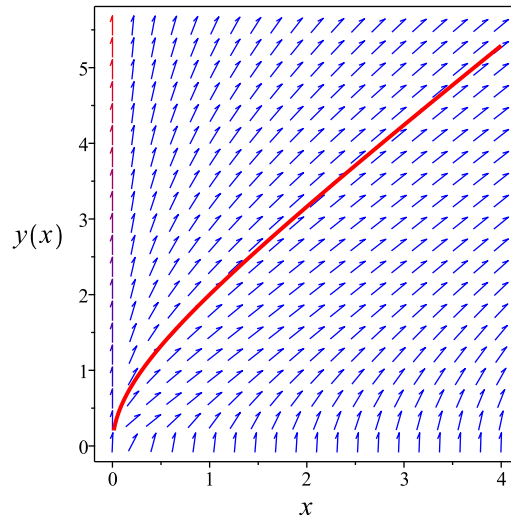
Summary

The solution(s) found are the following

$$y = \sqrt{x(x+3)} \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \sqrt{x(x+3)}$$

Verified OK.

6.15.3 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = \frac{x^2 + y^2}{2yx}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **Bernoulli**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 228: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= \frac{x}{y}\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{x}{y}} dy \end{aligned}$$

Which results in

$$S = \frac{y^2}{2x}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = \frac{x^2 + y^2}{2yx}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= -\frac{y^2}{2x^2} \\ S_y &= \frac{y}{x} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = \frac{1}{2} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = \frac{1}{2}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = \frac{R}{2} + c_1 \quad (4)$$

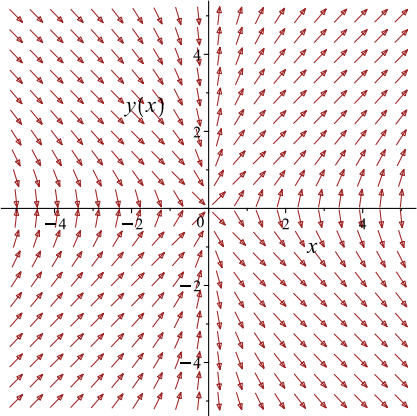
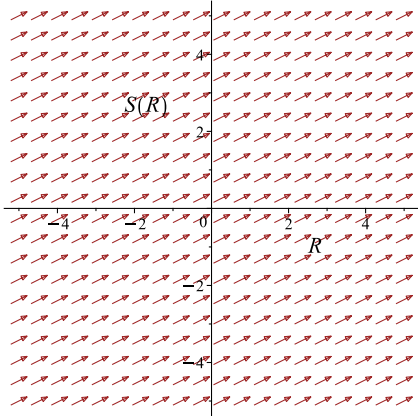
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$\frac{y^2}{2x} = \frac{x}{2} + c_1$$

Which simplifies to

$$\frac{y^2}{2x} = \frac{x}{2} + c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = \frac{x^2 + y^2}{2yx}$ 	$R = x$ $S = \frac{y^2}{2x}$	$\frac{dS}{dR} = \frac{1}{2}$ 

Initial conditions are used to solve for c_1 . Substituting $x = 1$ and $y = 2$ in the above solution gives an equation to solve for the constant of integration.

$$2 = \frac{1}{2} + c_1$$

$$c_1 = \frac{3}{2}$$

Substituting c_1 found above in the general solution gives

$$\frac{y^2}{2x} = \frac{x}{2} + \frac{3}{2}$$

The above simplifies to

$$-x^2 + y^2 - 3x = 0$$

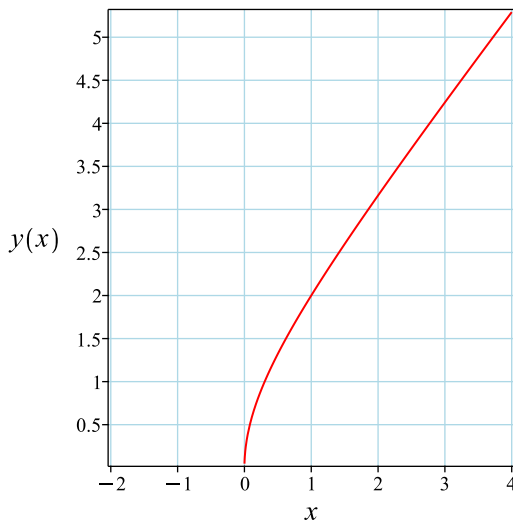
Solving for y from the above gives

$$y = \sqrt{x(x+3)}$$

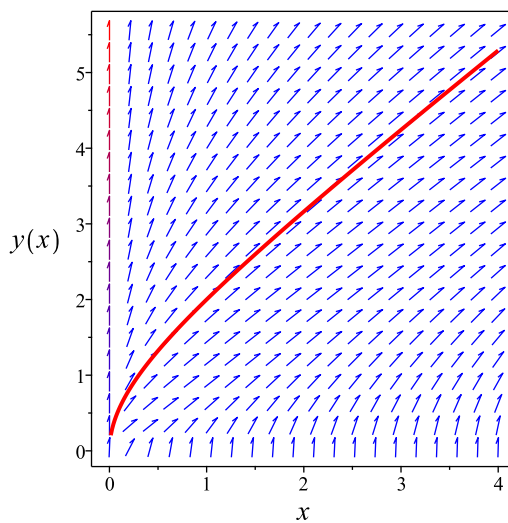
Summary

The solution(s) found are the following

$$y = \sqrt{x(x+3)} \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \sqrt{x(x+3)}$$

Verified OK.

6.15.4 Solving as bernoulli ode

In canonical form, the ODE is

$$\begin{aligned}y' &= F(x, y) \\ &= \frac{x^2 + y^2}{2yx}\end{aligned}$$

This is a Bernoulli ODE.

$$y' = \frac{1}{2x}y + \frac{x}{2} \frac{1}{y} \quad (1)$$

The standard Bernoulli ODE has the form

$$y' = f_0(x)y + f_1(x)y^n \quad (2)$$

The first step is to divide the above equation by y^n which gives

$$\frac{y'}{y^n} = f_0(x)y^{1-n} + f_1(x) \quad (3)$$

The next step is use the substitution $w = y^{1-n}$ in equation (3) which generates a new ODE in $w(x)$ which will be linear and can be easily solved using an integrating factor. Backsubstitution then gives the solution $y(x)$ which is what we want.

This method is now applied to the ODE at hand. Comparing the ODE (1) With (2) Shows that

$$\begin{aligned}f_0(x) &= \frac{1}{2x} \\ f_1(x) &= \frac{x}{2} \\ n &= -1\end{aligned}$$

Dividing both sides of ODE (1) by $y^n = \frac{1}{y}$ gives

$$y'y = \frac{y^2}{2x} + \frac{x}{2} \quad (4)$$

Let

$$\begin{aligned}w &= y^{1-n} \\ &= y^2\end{aligned} \quad (5)$$

Taking derivative of equation (5) w.r.t x gives

$$w' = 2yy' \quad (6)$$

Substituting equations (5) and (6) into equation (4) gives

$$\begin{aligned}\frac{w'(x)}{2} &= \frac{w(x)}{2x} + \frac{x}{2} \\ w' &= \frac{w}{x} + x\end{aligned}\tag{7}$$

The above now is a linear ODE in $w(x)$ which is now solved.

Entering Linear first order ODE solver. In canonical form a linear first order is

$$w'(x) + p(x)w(x) = q(x)$$

Where here

$$\begin{aligned}p(x) &= -\frac{1}{x} \\ q(x) &= x\end{aligned}$$

Hence the ode is

$$w'(x) - \frac{w(x)}{x} = x$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int -\frac{1}{x} dx} \\ &= \frac{1}{x}\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu w) &= (\mu)(x) \\ \frac{d}{dx}\left(\frac{w}{x}\right) &= \left(\frac{1}{x}\right)(x) \\ d\left(\frac{w}{x}\right) &= dx\end{aligned}$$

Integrating gives

$$\begin{aligned}\frac{w}{x} &= \int dx \\ \frac{w}{x} &= x + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = \frac{1}{x}$ results in

$$w(x) = c_1x + x^2$$

which simplifies to

$$w(x) = x(x + c_1)$$

Replacing w in the above by y^2 using equation (5) gives the final solution.

$$y^2 = x(x + c_1)$$

Initial conditions are used to solve for c_1 . Substituting $x = 1$ and $y = 2$ in the above solution gives an equation to solve for the constant of integration.

$$4 = 1 + c_1$$

$$c_1 = 3$$

Substituting c_1 found above in the general solution gives

$$y^2 = x(x + 3)$$

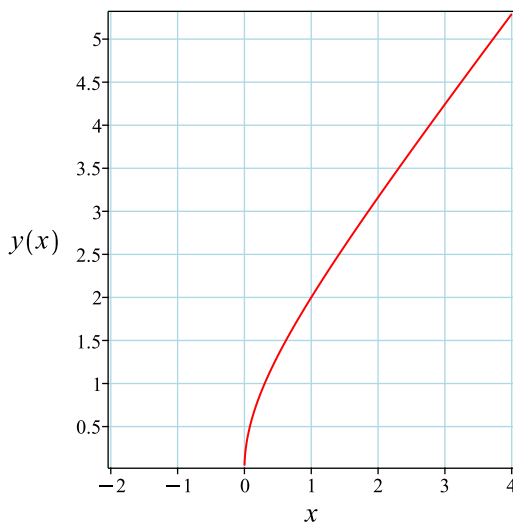
Solving for y from the above gives

$$y = \sqrt{x(x + 3)}$$

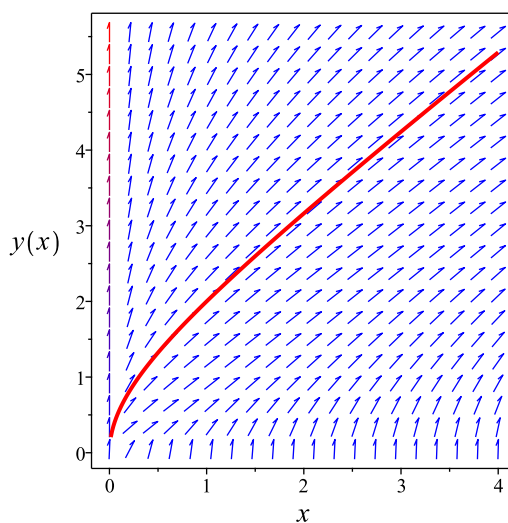
Summary

The solution(s) found are the following

$$y = \sqrt{x(x + 3)} \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \sqrt{x(x+3)}$$

Verified OK.

6.15.5 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \quad (\text{A})$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \quad (\text{B})$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (\text{1A})$$

Therefore

$$\begin{aligned} (-2xy) dy &= (-x^2 - y^2) dx \\ (x^2 + y^2) dx + (-2xy) dy &= 0 \end{aligned} \quad (\text{2A})$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= x^2 + y^2 \\N(x, y) &= -2xy\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(x^2 + y^2) \\&= 2y\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(-2xy) \\&= -2y\end{aligned}$$

Since $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$\begin{aligned}A &= \frac{1}{N} \left(\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} \right) \\&= -\frac{1}{2xy} ((2y) - (-2y)) \\&= -\frac{2}{x}\end{aligned}$$

Since A does not depend on y , then it can be used to find an integrating factor. The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int A dx} \\&= e^{\int -\frac{2}{x} dx}\end{aligned}$$

The result of integrating gives

$$\begin{aligned}\mu &= e^{-2 \ln(x)} \\&= \frac{1}{x^2}\end{aligned}$$

M and N are multiplied by this integrating factor, giving new M and new N which are called \overline{M} and \overline{N} for now so not to confuse them with the original M and N .

$$\begin{aligned}\overline{M} &= \mu M \\ &= \frac{1}{x^2}(x^2 + y^2) \\ &= \frac{x^2 + y^2}{x^2}\end{aligned}$$

And

$$\begin{aligned}\overline{N} &= \mu N \\ &= \frac{1}{x^2}(-2xy) \\ &= -\frac{2y}{x}\end{aligned}$$

Now a modified ODE is obtained from the original ODE, which is exact and can be solved. The modified ODE is

$$\begin{aligned}\overline{M} + \overline{N} \frac{dy}{dx} &= 0 \\ \left(\frac{x^2 + y^2}{x^2}\right) + \left(-\frac{2y}{x}\right) \frac{dy}{dx} &= 0\end{aligned}$$

The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = \overline{M} \tag{1}$$

$$\frac{\partial \phi}{\partial y} = \overline{N} \tag{2}$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int \overline{M} dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int \frac{x^2 + y^2}{x^2} dx \\ \phi &= x - \frac{y^2}{x} + f(y)\end{aligned} \tag{3}$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = -\frac{2y}{x} + f'(y) \tag{4}$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = -\frac{2y}{x}$. Therefore equation (4) becomes

$$-\frac{2y}{x} = -\frac{2y}{x} + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 0$$

Therefore

$$f(y) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(y)$ into equation (3) gives ϕ

$$\phi = x - \frac{y^2}{x} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = x - \frac{y^2}{x}$$

Initial conditions are used to solve for c_1 . Substituting $x = 1$ and $y = 2$ in the above solution gives an equation to solve for the constant of integration.

$$-3 = c_1$$

$$c_1 = -3$$

Substituting c_1 found above in the general solution gives

$$x - \frac{y^2}{x} = -3$$

The above simplifies to

$$x^2 - y^2 + 3x = 0$$

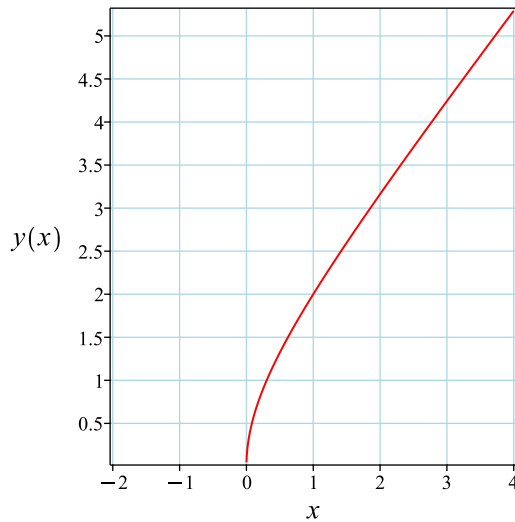
Solving for y from the above gives

$$y = \sqrt{x(x+3)}$$

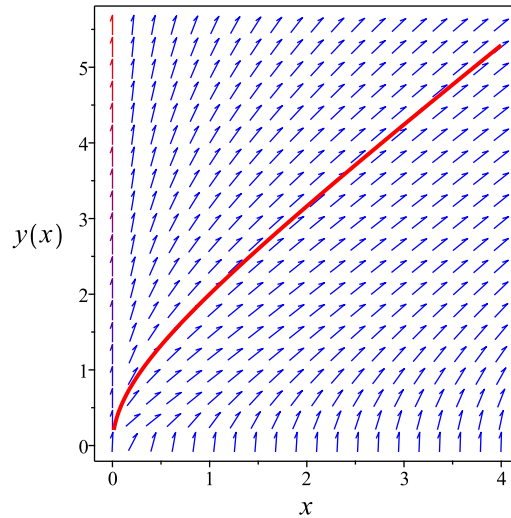
Summary

The solution(s) found are the following

$$y = \sqrt{x(x+3)} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \sqrt{x(x+3)}$$

Verified OK.

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
trying Bernoulli  
<- Bernoulli successful`
```

✓ Solution by Maple

Time used: 0.047 (sec). Leaf size: 13

```
dsolve([(x^2+y(x)^2)-2*x*y(x)*diff(y(x),x)=0,y(1) = 2],y(x), singsol=all)
```

$$y(x) = \sqrt{(x+3)x}$$

✓ Solution by Mathematica

Time used: 0.175 (sec). Leaf size: 18

```
DSolve[{(x^2+y[x]^2)-2*x*y[x]*y'[x]==0,{y[1]==2}},y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \sqrt{x}\sqrt{x+3}$$

6.16 problem 16

6.16.1 Existence and uniqueness analysis	1454
6.16.2 Solving as separable ode	1455
6.16.3 Solving as first order ode lie symmetry lookup ode	1456
6.16.4 Solving as bernoulli ode	1461
6.16.5 Solving as exact ode	1464
6.16.6 Maple step by step solution	1468

Internal problem ID [11690]

Internal file name [OUTPUT/11699_Wednesday_April_10_2024_04_55_03_PM_17615973/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, Miscellaneous Review. Exercises page 60

Problem number: 16.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact", "bernoulli", "separable", "first_order_ode_lie_symmetry_lookup"

Maple gives the following as the ode type

[_separable]

$$2y^2 + (-x^2 + 1)yy' = -8$$

With initial conditions

$$[y(3) = 0]$$

6.16.1 Existence and uniqueness analysis

This is non linear first order ODE. In canonical form it is written as

$$\begin{aligned}y' &= f(x, y) \\ &= \frac{2y^2 + 8}{(x^2 - 1)y}\end{aligned}$$

$f(x, y)$ is not defined at $y = 0$ therefore existence and uniqueness theorem do not apply.

6.16.2 Solving as separable ode

In canonical form the ODE is

$$\begin{aligned}y' &= F(x, y) \\ &= f(x)g(y) \\ &= \frac{2y^2 + 8}{(x^2 - 1)y}\end{aligned}$$

Where $f(x) = \frac{2}{x^2-1}$ and $g(y) = \frac{y^2+4}{y}$. Integrating both sides gives

$$\begin{aligned}\frac{1}{\frac{y^2+4}{y}} dy &= \frac{2}{x^2-1} dx \\ \int \frac{1}{\frac{y^2+4}{y}} dy &= \int \frac{2}{x^2-1} dx \\ \frac{\ln(y^2+4)}{2} &= -2 \operatorname{arctanh}(x) + c_1\end{aligned}$$

Raising both side to exponential gives

$$\sqrt{y^2+4} = e^{-2 \operatorname{arctanh}(x)+c_1}$$

Which simplifies to

$$\sqrt{y^2+4} = \frac{c_2(-x^2+1)}{(1+x)^2}$$

The solution is

$$\sqrt{y^2+4} = c_2 e^{-2 \operatorname{arctanh}(x)+c_1}$$

Initial conditions are used to solve for c_1 . Substituting $x = 3$ and $y = 0$ in the above solution gives an equation to solve for the constant of integration.

$$2 = -\frac{e^{c_1}c_2}{2}$$

$$c_1 = \ln\left(-\frac{4}{c_2}\right)$$

Substituting c_1 found above in the general solution gives

$$\sqrt{y^2+4} = \frac{4x-4}{1+x}$$

The above simplifies to

$$\sqrt{y^2 + 4} x + \sqrt{y^2 + 4} - 4x + 4 = 0$$

Summary

The solution(s) found are the following

$$\sqrt{y^2 + 4} x + \sqrt{y^2 + 4} - 4x + 4 = 0 \quad (1)$$

Verification of solutions

$$\sqrt{y^2 + 4} x + \sqrt{y^2 + 4} - 4x + 4 = 0$$

Verified OK.

6.16.3 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = \frac{2y^2 + 8}{(x^2 - 1)y}$$
$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (A)$$

The type of this ode is known. It is of type **separable**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 230: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= \frac{x^2}{2} - \frac{1}{2} \\ \eta(x, y) &= 0\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\eta = 0$ then in this special case

$$R = y$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\xi} dx \\ &= \int \frac{1}{\frac{x^2}{2} - \frac{1}{2}} dx \end{aligned}$$

Which results in

$$S = -2 \operatorname{arctanh}(x)$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = \frac{2y^2 + 8}{(x^2 - 1)y}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 0 \\ R_y &= 1 \\ S_x &= \frac{2}{x^2 - 1} \\ S_y &= 0 \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = \frac{y}{y^2 + 4} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = \frac{R}{R^2 + 4}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = \frac{\ln(R^2 + 4)}{2} + c_1 \quad (4)$$

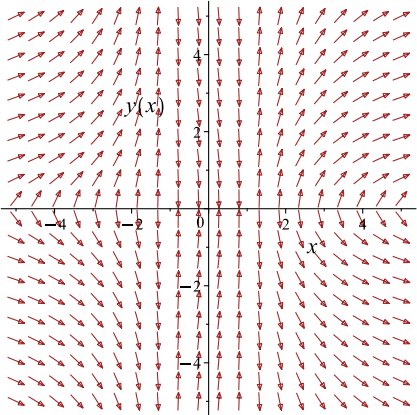
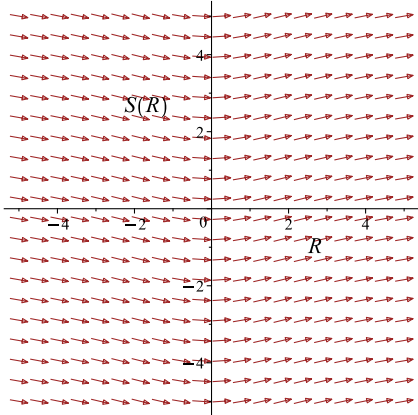
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$-2 \operatorname{arctanh}(x) = \frac{\ln(y^2 + 4)}{2} + c_1$$

Which simplifies to

$$-2 \operatorname{arctanh}(x) = \frac{\ln(y^2 + 4)}{2} + c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = \frac{2y^2+8}{(x^2-1)y}$ 	$R = y$ $S = -2 \operatorname{arctanh}(x)$	$\frac{dS}{dR} = \frac{R}{R^2+4}$ 

Initial conditions are used to solve for c_1 . Substituting $x = 3$ and $y = 0$ in the above solution gives an equation to solve for the constant of integration.

$$-2 \operatorname{arccoth}(3) + i\pi = \ln(2) + c_1$$

$$c_1 = i\pi - \ln(2) - 2 \operatorname{arccoth}(3)$$

Substituting c_1 found above in the general solution gives

$$-2 \operatorname{arctanh}(x) = \frac{\ln(y^2 + 4)}{2} + i\pi - \ln(2) - 2 \operatorname{arccoth}(3)$$

Solving for y from the above gives

$$y = 2\sqrt{-1 + e^{-4 \operatorname{arctanh}(x) + 4 \operatorname{arccoth}(3)}}$$

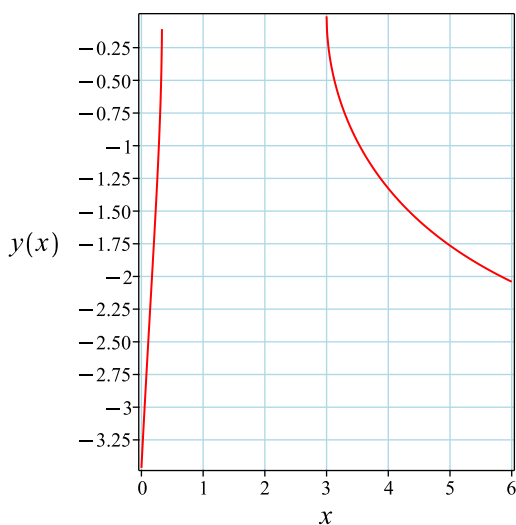
$$y = -2\sqrt{-1 + e^{-4 \operatorname{arctanh}(x) + 4 \operatorname{arccoth}(3)}}$$

Summary

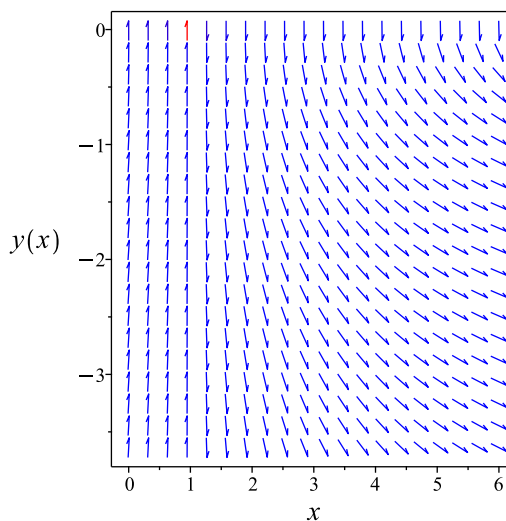
The solution(s) found are the following

$$y = 2\sqrt{-1 + e^{-4 \operatorname{arctanh}(x) + 4 \operatorname{arccoth}(3)}} \quad (1)$$

$$y = -2\sqrt{-1 + e^{-4 \operatorname{arctanh}(x) + 4 \operatorname{arccoth}(3)}} \quad (2)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = 2\sqrt{-1 + e^{-4 \operatorname{arctanh}(x) + 4 \operatorname{arccoth}(3)}}$$

Verified OK. {positive}

$$y = -2\sqrt{-1 + e^{-4 \operatorname{arctanh}(x) + 4 \operatorname{arccoth}(3)}}$$

Verified OK. {positive}

6.16.4 Solving as bernoulli ode

In canonical form, the ODE is

$$\begin{aligned}y' &= F(x, y) \\ &= \frac{2y^2 + 8}{(x^2 - 1)y}\end{aligned}$$

This is a Bernoulli ODE.

$$y' = \frac{2}{x^2 - 1}y + \frac{8}{x^2 - 1} \frac{1}{y} \quad (1)$$

The standard Bernoulli ODE has the form

$$y' = f_0(x)y + f_1(x)y^n \quad (2)$$

The first step is to divide the above equation by y^n which gives

$$\frac{y'}{y^n} = f_0(x)y^{1-n} + f_1(x) \quad (3)$$

The next step is use the substitution $w = y^{1-n}$ in equation (3) which generates a new ODE in $w(x)$ which will be linear and can be easily solved using an integrating factor. Backsubstitution then gives the solution $y(x)$ which is what we want.

This method is now applied to the ODE at hand. Comparing the ODE (1) With (2) Shows that

$$\begin{aligned}f_0(x) &= \frac{2}{x^2 - 1} \\ f_1(x) &= \frac{8}{x^2 - 1} \\ n &= -1\end{aligned}$$

Dividing both sides of ODE (1) by $y^n = \frac{1}{y}$ gives

$$y'y = \frac{2y^2}{x^2 - 1} + \frac{8}{x^2 - 1} \quad (4)$$

Let

$$\begin{aligned}w &= y^{1-n} \\ &= y^2\end{aligned} \quad (5)$$

Taking derivative of equation (5) w.r.t x gives

$$w' = 2yy' \quad (6)$$

Substituting equations (5) and (6) into equation (4) gives

$$\begin{aligned}\frac{w'(x)}{2} &= \frac{2w(x)}{x^2-1} + \frac{8}{x^2-1} \\ w' &= \frac{4w}{x^2-1} + \frac{16}{x^2-1}\end{aligned}\tag{7}$$

The above now is a linear ODE in $w(x)$ which is now solved.

Entering Linear first order ODE solver. In canonical form a linear first order is

$$w'(x) + p(x)w(x) = q(x)$$

Where here

$$\begin{aligned}p(x) &= -\frac{4}{x^2-1} \\ q(x) &= \frac{16}{x^2-1}\end{aligned}$$

Hence the ode is

$$w'(x) - \frac{4w(x)}{x^2-1} = \frac{16}{x^2-1}$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int -\frac{4}{x^2-1} dx} \\ &= \frac{(1+x)^4}{(-x^2+1)^2}\end{aligned}$$

Which simplifies to

$$\mu = \frac{(1+x)^2}{(x-1)^2}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu w) &= (\mu) \left(\frac{16}{x^2-1} \right) \\ \frac{d}{dx} \left(\frac{(1+x)^2 w}{(x-1)^2} \right) &= \left(\frac{(1+x)^2}{(x-1)^2} \right) \left(\frac{16}{x^2-1} \right) \\ d \left(\frac{(1+x)^2 w}{(x-1)^2} \right) &= \left(\frac{16+16x}{(x-1)^3} \right) dx\end{aligned}$$

Integrating gives

$$\frac{(1+x)^2 w}{(x-1)^2} = \int \frac{16+16x}{(x-1)^3} dx$$
$$\frac{(1+x)^2 w}{(x-1)^2} = -\frac{16}{x-1} - \frac{16}{(x-1)^2} + c_1$$

Dividing both sides by the integrating factor $\mu = \frac{(1+x)^2}{(x-1)^2}$ results in

$$w(x) = \frac{(x-1)^2 \left(-\frac{16}{x-1} - \frac{16}{(x-1)^2} \right)}{(1+x)^2} + \frac{c_1(x-1)^2}{(1+x)^2}$$

which simplifies to

$$w(x) = \frac{c_1 x^2 + (-2c_1 - 16)x + c_1}{(1+x)^2}$$

Replacing w in the above by y^2 using equation (5) gives the final solution.

$$y^2 = \frac{c_1 x^2 + (-2c_1 - 16)x + c_1}{(1+x)^2}$$

Initial conditions are used to solve for c_1 . Substituting $x = 3$ and $y = 0$ in the above solution gives an equation to solve for the constant of integration.

$$0 = \frac{c_1}{4} - 3$$

$$c_1 = 12$$

Substituting c_1 found above in the general solution gives

$$y^2 = \frac{12x^2 - 40x + 12}{(1+x)^2}$$

The above simplifies to

$$x^2 y^2 + 2x y^2 - 12x^2 + y^2 + 40x - 12 = 0$$

Summary

The solution(s) found are the following

$$x^2 y^2 + 2y^2 x - 12x^2 + y^2 + 40x - 12 = 0 \quad (1)$$

Verification of solutions

$$x^2 y^2 + 2y^2 x - 12x^2 + y^2 + 40x - 12 = 0$$

Verified OK.

6.16.5 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \quad (\text{A})$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx}\phi(x, y) = 0$$

Hence

$$\frac{\partial\phi}{\partial x} + \frac{\partial\phi}{\partial y} \frac{dy}{dx} = 0 \quad (\text{B})$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial\phi}{\partial x} &= M \\ \frac{\partial\phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (\text{1A})$$

Therefore

$$\begin{aligned} \left(\frac{y}{2y^2+8}\right) dy &= \left(\frac{1}{x^2-1}\right) dx \\ \left(-\frac{1}{x^2-1}\right) dx + \left(\frac{y}{2y^2+8}\right) dy &= 0 \end{aligned} \quad (\text{2A})$$

Comparing (1A) and (2A) shows that

$$M(x, y) = -\frac{1}{x^2 - 1}$$
$$N(x, y) = \frac{y}{2y^2 + 8}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\frac{\partial M}{\partial y} = \frac{\partial}{\partial y} \left(-\frac{1}{x^2 - 1} \right)$$
$$= 0$$

And

$$\frac{\partial N}{\partial x} = \frac{\partial}{\partial x} \left(\frac{y}{2y^2 + 8} \right)$$
$$= 0$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \tag{1}$$

$$\frac{\partial \phi}{\partial y} = N \tag{2}$$

Integrating (1) w.r.t. x gives

$$\int \frac{\partial \phi}{\partial x} dx = \int M dx$$
$$\int \frac{\partial \phi}{\partial x} dx = \int -\frac{1}{x^2 - 1} dx$$
$$\phi = \operatorname{arctanh}(x) + f(y) \tag{3}$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = 0 + f'(y) \tag{4}$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = \frac{y}{2y^2+8}$. Therefore equation (4) becomes

$$\frac{y}{2y^2+8} = 0 + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = \frac{y}{2y^2+8}$$

Integrating the above w.r.t y gives

$$\int f'(y) dy = \int \left(\frac{y}{2y^2+8} \right) dy$$

$$f(y) = \frac{\ln(y^2+4)}{4} + c_1$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = \operatorname{arctanh}(x) + \frac{\ln(y^2+4)}{4} + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = \operatorname{arctanh}(x) + \frac{\ln(y^2+4)}{4}$$

Initial conditions are used to solve for c_1 . Substituting $x = 3$ and $y = 0$ in the above solution gives an equation to solve for the constant of integration.

$$\operatorname{arccoth}(3) - \frac{i\pi}{2} + \frac{\ln(2)}{2} = c_1$$

$$c_1 = \operatorname{arccoth}(3) - \frac{i\pi}{2} + \frac{\ln(2)}{2}$$

Substituting c_1 found above in the general solution gives

$$\operatorname{arctanh}(x) + \frac{\ln(y^2+4)}{4} = \operatorname{arccoth}(3) - \frac{i\pi}{2} + \frac{\ln(2)}{2}$$

Solving for y from the above gives

$$y = 2\sqrt{-1 + e^{-4 \operatorname{arctanh}(x)+4 \operatorname{arccoth}(3)}}$$

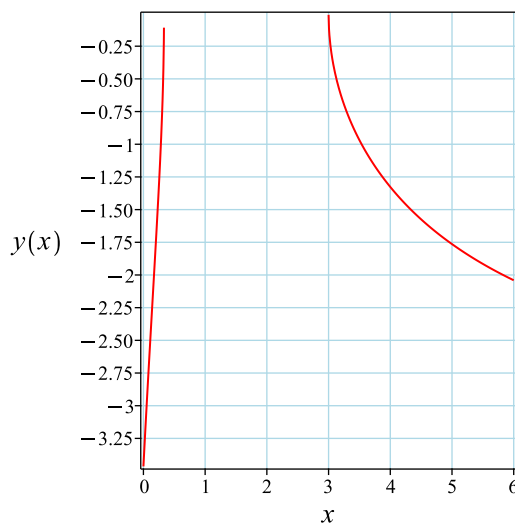
$$y = -2\sqrt{-1 + e^{-4 \operatorname{arctanh}(x)+4 \operatorname{arccoth}(3)}}$$

Summary

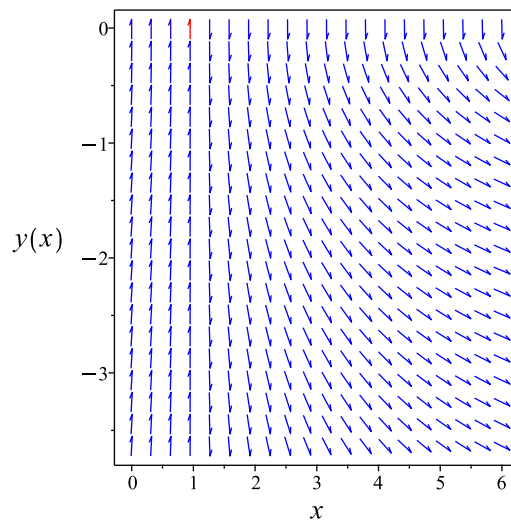
The solution(s) found are the following

$$y = 2\sqrt{-1 + e^{-4 \operatorname{arctanh}(x)+4 \operatorname{arccoth}(3)}} \quad (1)$$

$$y = -2\sqrt{-1 + e^{-4 \operatorname{arctanh}(x)+4 \operatorname{arccoth}(3)}} \quad (2)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = 2\sqrt{-1 + e^{-4 \operatorname{arctanh}(x)+4 \operatorname{arccoth}(3)}}$$

Verified OK. {positive}

$$y = -2\sqrt{-1 + e^{-4 \operatorname{arctanh}(x)+4 \operatorname{arccoth}(3)}}$$

Verified OK. {positive}

6.16.6 Maple step by step solution

Let's solve

$$[2y^2 + (-x^2 + 1)yy' = -8, y(3) = 0]$$

- Highest derivative means the order of the ODE is 1

y'

- Separate variables

$$\frac{y'y}{-2y^2-8} = \frac{1}{-x^2+1}$$

- Integrate both sides with respect to x

$$\int \frac{y'y}{-2y^2-8} dx = \int \frac{1}{-x^2+1} dx + c_1$$

- Evaluate integral

$$-\frac{\ln(y^2+4)}{4} = \operatorname{arctanh}(x) + c_1$$

- Solve for y

$$\left\{ y = \sqrt{-4 + e^{-4 \operatorname{arctanh}(x) - 4c_1}}, y = -\sqrt{-4 + e^{-4 \operatorname{arctanh}(x) - 4c_1}} \right\}$$

- Use initial condition $y(3) = 0$

$$0 = \sqrt{-4 + e^{-4 \operatorname{arctanh}(\frac{1}{3}) - 4c_1}}$$

- Solve for c_1

$$c_1 = -\operatorname{arctanh}(\frac{1}{3}) - \frac{\ln(2)}{2}$$

- Substitute $c_1 = -\operatorname{arctanh}(\frac{1}{3}) - \frac{\ln(2)}{2}$ into general solution and simplify

$$y = 2\sqrt{-1 + e^{-4 \operatorname{arctanh}(x) + 4 \operatorname{arctanh}(\frac{1}{3})}}$$

- Use initial condition $y(3) = 0$

$$0 = -\sqrt{-4 + e^{-4 \operatorname{arctanh}(\frac{1}{3}) - 4c_1}}$$

- Solve for c_1

$$c_1 = -\operatorname{arctanh}(\frac{1}{3}) - \frac{\ln(2)}{2}$$

- Substitute $c_1 = -\operatorname{arctanh}(\frac{1}{3}) - \frac{\ln(2)}{2}$ into general solution and simplify

$$y = -2\sqrt{-1 + e^{-4 \operatorname{arctanh}(x) + 4 \operatorname{arctanh}(\frac{1}{3})}}$$

- Solutions to the IVP

$$\left\{ y = -2\sqrt{-1 + e^{-4 \operatorname{arctanh}(x) + 4 \operatorname{arctanh}(\frac{1}{3})}}, y = 2\sqrt{-1 + e^{-4 \operatorname{arctanh}(x) + 4 \operatorname{arctanh}(\frac{1}{3})}} \right\}$$

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
trying Bernoulli  
<- Bernoulli successful`
```

✓ Solution by Maple

Time used: 0.046 (sec). Leaf size: 45

```
dsolve([2*(y(x)^2+4)+(1-x^2)*y(x)*diff(y(x),x)=0,y(3) = 0],y(x), singsol=all)
```

$$y(x) = -\frac{2\sqrt{3x^2 - 10x + 3}}{1 + x}$$
$$y(x) = \frac{2\sqrt{3x^2 - 10x + 3}}{1 + x}$$

✓ Solution by Mathematica

Time used: 0.886 (sec). Leaf size: 51

```
DSolve[{2*(y[x]^2+4)+(1-x^2)*y[x]*y'[x]==0,{y[3]==0}},y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow -\frac{2\sqrt{3x^2 - 10x + 3}}{x + 1}$$
$$y(x) \rightarrow \frac{2\sqrt{3x^2 - 10x + 3}}{x + 1}$$

6.17 problem 17

6.17.1 Existence and uniqueness analysis	1470
6.17.2 Solving as first order ode lie symmetry lookup ode	1471
6.17.3 Solving as bernoulli ode	1476
6.17.4 Solving as exact ode	1479
6.17.5 Maple step by step solution	1482

Internal problem ID [11691]

Internal file name [OUTPUT/11700_Wednesday_April_10_2024_04_55_07_PM_1436126/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, Miscellaneous Review. Exercises page 60

Problem number: 17.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact", "bernoulli", "first_order_ode_lie_symmetry_lookup"

Maple gives the following as the ode type

```
[_exact , _Bernoulli]
```

$$e^{2x}y^2 + e^{2x}yy' = 2x$$

With initial conditions

$$[y(0) = 2]$$

6.17.1 Existence and uniqueness analysis

This is non linear first order ODE. In canonical form it is written as

$$\begin{aligned} y' &= f(x, y) \\ &= -\frac{(e^{2x}y^2 - 2x)e^{-2x}}{y} \end{aligned}$$

The x domain of $f(x, y)$ when $y = 2$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The y domain of $f(x, y)$ when $x = 0$ is

$$\{-\infty < y < \infty\}$$

And the point $y_0 = 2$ is inside this domain. Now we will look at the continuity of

$$\begin{aligned} \frac{\partial f}{\partial y} &= \frac{\partial}{\partial y} \left(-\frac{(e^{2x}y^2 - 2x)e^{-2x}}{y} \right) \\ &= -2 + \frac{(e^{2x}y^2 - 2x)e^{-2x}}{y^2} \end{aligned}$$

The x domain of $\frac{\partial f}{\partial y}$ when $y = 2$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The y domain of $\frac{\partial f}{\partial y}$ when $x = 0$ is

$$\{-\infty < y < \infty\}$$

And the point $y_0 = 2$ is inside this domain. Therefore solution exists and is unique.

6.17.2 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$\begin{aligned} y' &= -\frac{(e^{2x}y^2 - 2x)e^{-2x}}{y} \\ y' &= \omega(x, y) \end{aligned}$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **Bernoulli**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 233: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= \frac{e^{-2x}}{y}\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{e^{-2x}}{y}} dy \end{aligned}$$

Which results in

$$S = \frac{e^{2x} y^2}{2}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{(e^{2x} y^2 - 2x) e^{-2x}}{y}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= e^{2x} y^2 \\ S_y &= y e^{2x} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 2x \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 2R$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = R^2 + c_1 \quad (4)$$

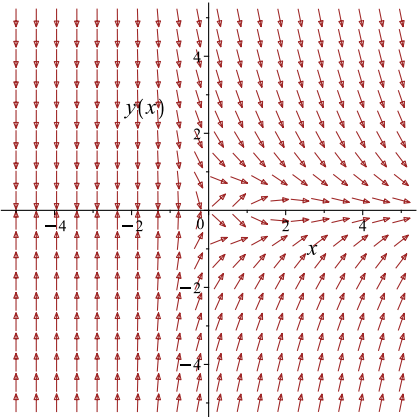
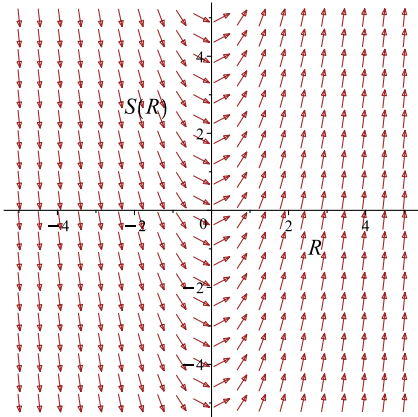
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$\frac{e^{2x}y^2}{2} = x^2 + c_1$$

Which simplifies to

$$\frac{e^{2x}y^2}{2} = x^2 + c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{(e^{2x}y^2 - 2x)e^{-2x}}{y}$ 	$R = x$ $S = \frac{e^{2x}y^2}{2}$	$\frac{dS}{dR} = 2R$ 

Initial conditions are used to solve for c_1 . Substituting $x = 0$ and $y = 2$ in the above solution gives an equation to solve for the constant of integration.

$$2 = c_1$$

$$c_1 = 2$$

Substituting c_1 found above in the general solution gives

$$\frac{e^{2x}y^2}{2} = x^2 + 2$$

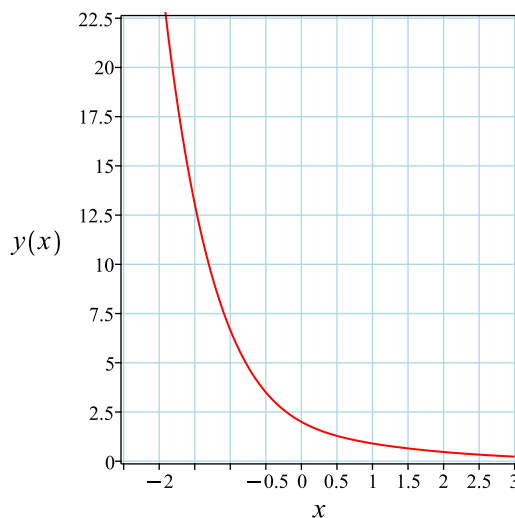
Solving for y from the above gives

$$y = e^{-2x}\sqrt{2} \sqrt{e^{2x}(x^2 + 2)}$$

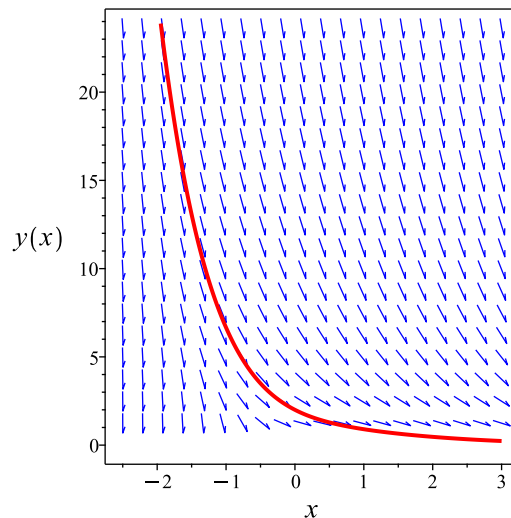
Summary

The solution(s) found are the following

$$y = e^{-2x}\sqrt{2} \sqrt{e^{2x}(x^2 + 2)} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = e^{-2x}\sqrt{2} \sqrt{e^{2x}(x^2 + 2)}$$

Verified OK.

6.17.3 Solving as bernoulli ode

In canonical form, the ODE is

$$\begin{aligned}y' &= F(x, y) \\ &= -\frac{(e^{2x}y^2 - 2x)e^{-2x}}{y}\end{aligned}$$

This is a Bernoulli ODE.

$$y' = -y + 2xe^{-2x}\frac{1}{y} \quad (1)$$

The standard Bernoulli ODE has the form

$$y' = f_0(x)y + f_1(x)y^n \quad (2)$$

The first step is to divide the above equation by y^n which gives

$$\frac{y'}{y^n} = f_0(x)y^{1-n} + f_1(x) \quad (3)$$

The next step is use the substitution $w = y^{1-n}$ in equation (3) which generates a new ODE in $w(x)$ which will be linear and can be easily solved using an integrating factor. Backsubstitution then gives the solution $y(x)$ which is what we want.

This method is now applied to the ODE at hand. Comparing the ODE (1) With (2) Shows that

$$\begin{aligned}f_0(x) &= -1 \\ f_1(x) &= 2xe^{-2x} \\ n &= -1\end{aligned}$$

Dividing both sides of ODE (1) by $y^n = \frac{1}{y}$ gives

$$y'y = -y^2 + 2xe^{-2x} \quad (4)$$

Let

$$\begin{aligned}w &= y^{1-n} \\ &= y^2\end{aligned} \quad (5)$$

Taking derivative of equation (5) w.r.t x gives

$$w' = 2yy' \quad (6)$$

Substituting equations (5) and (6) into equation (4) gives

$$\begin{aligned}\frac{w'(x)}{2} &= -w(x) + 2x e^{-2x} \\ w' &= -2w + 4x e^{-2x}\end{aligned}\tag{7}$$

The above now is a linear ODE in $w(x)$ which is now solved.

Entering Linear first order ODE solver. In canonical form a linear first order is

$$w'(x) + p(x)w(x) = q(x)$$

Where here

$$\begin{aligned}p(x) &= 2 \\ q(x) &= 4x e^{-2x}\end{aligned}$$

Hence the ode is

$$w'(x) + 2w(x) = 4x e^{-2x}$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int 2dx} \\ &= e^{2x}\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu w) &= (\mu) (4x e^{-2x}) \\ \frac{d}{dx}(e^{2x} w) &= (e^{2x}) (4x e^{-2x}) \\ d(e^{2x} w) &= (4x) dx\end{aligned}$$

Integrating gives

$$\begin{aligned}e^{2x} w &= \int 4x dx \\ e^{2x} w &= 2x^2 + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = e^{2x}$ results in

$$w(x) = 2x^2 e^{-2x} + c_1 e^{-2x}$$

which simplifies to

$$w(x) = e^{-2x} (2x^2 + c_1)$$

Replacing w in the above by y^2 using equation (5) gives the final solution.

$$y^2 = e^{-2x}(2x^2 + c_1)$$

Initial conditions are used to solve for c_1 . Substituting $x = 0$ and $y = 2$ in the above solution gives an equation to solve for the constant of integration.

$$4 = c_1$$

$$c_1 = 4$$

Substituting c_1 found above in the general solution gives

$$y^2 = 2e^{-2x}(x^2 + 2)$$

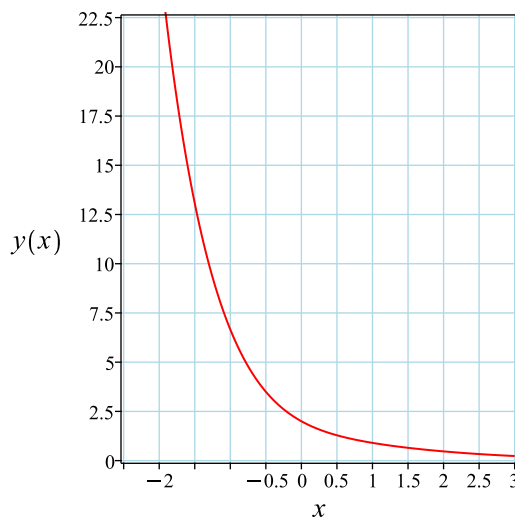
Solving for y from the above gives

$$y = \sqrt{2} \sqrt{e^{-2x}(x^2 + 2)}$$

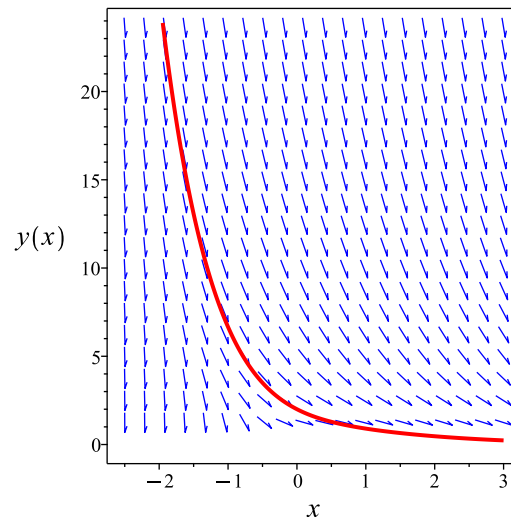
Summary

The solution(s) found are the following

$$y = \sqrt{2} \sqrt{e^{-2x}(x^2 + 2)} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \sqrt{2} \sqrt{e^{-2x}(x^2 + 2)}$$

Verified OK.

6.17.4 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \quad (\text{A})$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \quad (\text{B})$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (\text{1A})$$

Therefore

$$\begin{aligned} (y e^{2x}) dy &= (-e^{2x} y^2 + 2x) dx \\ (e^{2x} y^2 - 2x) dx + (y e^{2x}) dy &= 0 \end{aligned} \quad (\text{2A})$$

Comparing (1A) and (2A) shows that

$$\begin{aligned} M(x, y) &= e^{2x} y^2 - 2x \\ N(x, y) &= y e^{2x} \end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(e^{2x}y^2 - 2x) \\ &= 2ye^{2x}\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(ye^{2x}) \\ &= 2ye^{2x}\end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \tag{1}$$

$$\frac{\partial \phi}{\partial y} = N \tag{2}$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int M dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int e^{2x}y^2 - 2x dx \\ \phi &= \frac{e^{2x}y^2}{2} - x^2 + f(y)\end{aligned} \tag{3}$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = ye^{2x} + f'(y) \tag{4}$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = ye^{2x}$. Therefore equation (4) becomes

$$ye^{2x} = ye^{2x} + f'(y) \tag{5}$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 0$$

Therefore

$$f(y) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(y)$ into equation (3) gives ϕ

$$\phi = \frac{e^{2x}y^2}{2} - x^2 + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = \frac{e^{2x}y^2}{2} - x^2$$

Initial conditions are used to solve for c_1 . Substituting $x = 0$ and $y = 2$ in the above solution gives an equation to solve for the constant of integration.

$$2 = c_1$$

$$c_1 = 2$$

Substituting c_1 found above in the general solution gives

$$\frac{e^{2x}y^2}{2} - x^2 = 2$$

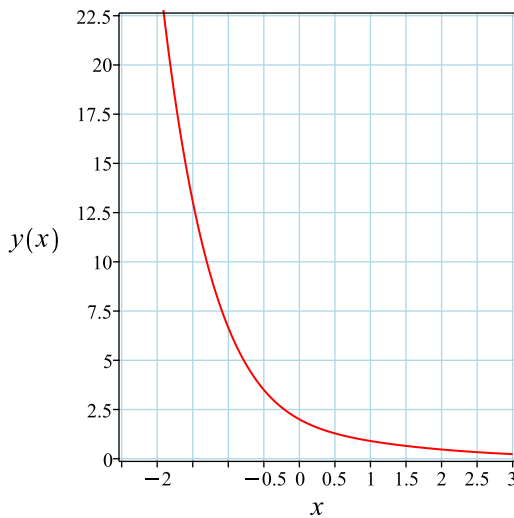
Solving for y from the above gives

$$y = e^{-2x}\sqrt{2} \sqrt{e^{2x}(x^2 + 2)}$$

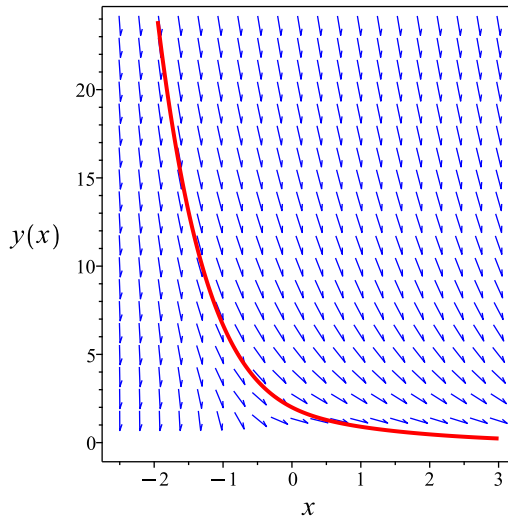
Summary

The solution(s) found are the following

$$y = e^{-2x}\sqrt{2} \sqrt{e^{2x}(x^2 + 2)} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = e^{-2x} \sqrt{2} \sqrt{e^{2x} (x^2 + 2)}$$

Verified OK.

6.17.5 Maple step by step solution

Let's solve

$$[e^{2x}y^2 + e^{2x}yy' = 2x, y(0) = 2]$$

- Highest derivative means the order of the ODE is 1
- Check if ODE is exact
 - ODE is exact if the lhs is the total derivative of a C^2 function
 - Compute derivative of lhs
 - Evaluate derivatives
 - Condition met, ODE is exact

- Exact ODE implies solution will be of this form

$$\left[F(x, y) = c_1, M(x, y) = F'(x, y), N(x, y) = \frac{\partial}{\partial y} F(x, y) \right]$$
- Solve for $F(x, y)$ by integrating $M(x, y)$ with respect to x

$$F(x, y) = \int (e^{2x}y^2 - 2x) dx + f_1(y)$$
- Evaluate integral

$$F(x, y) = \frac{e^{2x}y^2}{2} - x^2 + f_1(y)$$
- Take derivative of $F(x, y)$ with respect to y

$$N(x, y) = \frac{\partial}{\partial y} F(x, y)$$
- Compute derivative

$$y e^{2x} = y e^{2x} + \frac{d}{dy} f_1(y)$$
- Isolate for $\frac{d}{dy} f_1(y)$

$$\frac{d}{dy} f_1(y) = 0$$
- Solve for $f_1(y)$

$$f_1(y) = 0$$
- Substitute $f_1(y)$ into equation for $F(x, y)$

$$F(x, y) = \frac{e^{2x}y^2}{2} - x^2$$
- Substitute $F(x, y)$ into the solution of the ODE

$$\frac{e^{2x}y^2}{2} - x^2 = c_1$$
- Solve for y

$$\left\{ y = \frac{\sqrt{2} \sqrt{e^{2x}(x^2+c_1)}}{e^{2x}}, y = -\frac{\sqrt{2} \sqrt{e^{2x}(x^2+c_1)}}{e^{2x}} \right\}$$
- Use initial condition $y(0) = 2$

$$2 = \sqrt{c_1} \sqrt{2}$$
- Solve for c_1

$$c_1 = 2$$
- Substitute $c_1 = 2$ into general solution and simplify

$$y = e^{-2x} \sqrt{2} \sqrt{(e^x)^2 (x^2 + 2)}$$
- Use initial condition $y(0) = 2$

$$2 = -\sqrt{c_1} \sqrt{2}$$

- Solution does not satisfy initial condition
- Solution to the IVP

$$y = e^{-2x} \sqrt{2} \sqrt{(e^x)^2 (x^2 + 2)}$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
<- Bernoulli successful`

```

✓ Solution by Maple

Time used: 0.141 (sec). Leaf size: 24

```
dsolve([(exp(2*x)*y(x)^2-2*x)+(exp(2*x)*y(x))*diff(y(x),x)=0,y(0) = 2],y(x), singsol=all)
```

$$y(x) = e^{-2x} \sqrt{2} \sqrt{e^{2x} (x^2 + 2)}$$

✓ Solution by Mathematica

Time used: 0.337 (sec). Leaf size: 25

```
DSolve[{(Exp[2*x]*y[x]^2-2*x)+(Exp[2*x]*y[x])*y'[x]==0,{y[0]==2}},y[x],x,IncludeSingularSolu
```

$$y(x) \rightarrow \sqrt{2} e^{-x} \sqrt{x^2 + 2}$$

6.18 problem 18

- 6.18.1 Existence and uniqueness analysis 1485
6.18.2 Solving as exact ode 1486

Internal problem ID [11692]

Internal file name [OUTPUT/11701_Wednesday_April_10_2024_04_55_08_PM_24887235/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, Miscellaneous Review. Exercises page 60

Problem number: 18.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"exact"**

Maple gives the following as the ode type

`[_exact, _rational]`

$$2y^2x + (2x^2y + 6y^2) y' = -3x^2$$

With initial conditions

$$[y(1) = 2]$$

6.18.1 Existence and uniqueness analysis

This is non linear first order ODE. In canonical form it is written as

$$\begin{aligned} y' &= f(x, y) \\ &= -\frac{x(2y^2 + 3x)}{2y(x^2 + 3y)} \end{aligned}$$

The x domain of $f(x, y)$ when $y = 2$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 1$ is inside this domain. The y domain of $f(x, y)$ when $x = 1$ is

$$\left\{ -\infty \leq y < 0, 0 < y < -\frac{1}{3}, -\frac{1}{3} < y \leq \infty \right\}$$

And the point $y_0 = 2$ is inside this domain. Now we will look at the continuity of

$$\begin{aligned}\frac{\partial f}{\partial y} &= \frac{\partial}{\partial y} \left(-\frac{x(2y^2 + 3x)}{2y(x^2 + 3y)} \right) \\ &= -\frac{2x}{x^2 + 3y} + \frac{x(2y^2 + 3x)}{2y^2(x^2 + 3y)} + \frac{3x(2y^2 + 3x)}{2y(x^2 + 3y)^2}\end{aligned}$$

The x domain of $\frac{\partial f}{\partial y}$ when $y = 2$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 1$ is inside this domain. The y domain of $\frac{\partial f}{\partial y}$ when $x = 1$ is

$$\left\{ -\infty \leq y < 0, 0 < y < -\frac{1}{3}, -\frac{1}{3} < y \leq \infty \right\}$$

And the point $y_0 = 2$ is inside this domain. Therefore solution exists and is unique.

6.18.2 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \tag{1A}$$

Therefore

$$\begin{aligned} (2x^2y + 6y^2) dy &= (-2xy^2 - 3x^2) dx \\ (2xy^2 + 3x^2) dx + (2x^2y + 6y^2) dy &= 0 \end{aligned} \tag{2A}$$

Comparing (1A) and (2A) shows that

$$\begin{aligned} M(x, y) &= 2xy^2 + 3x^2 \\ N(x, y) &= 2x^2y + 6y^2 \end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned} \frac{\partial M}{\partial y} &= \frac{\partial}{\partial y} (2xy^2 + 3x^2) \\ &= 4xy \end{aligned}$$

And

$$\begin{aligned} \frac{\partial N}{\partial x} &= \frac{\partial}{\partial x} (2x^2y + 6y^2) \\ &= 4xy \end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \tag{1}$$

$$\frac{\partial \phi}{\partial y} = N \tag{2}$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int M dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int 2xy^2 + 3x^2 dx \\ \phi &= x^2(y^2 + x) + f(y)\end{aligned}\tag{3}$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = 2x^2y + f'(y)\tag{4}$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = 2x^2y + 6y^2$. Therefore equation (4) becomes

$$2x^2y + 6y^2 = 2x^2y + f'(y)\tag{5}$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 6y^2$$

Integrating the above w.r.t y gives

$$\begin{aligned}\int f'(y) dy &= \int (6y^2) dy \\ f(y) &= 2y^3 + c_1\end{aligned}$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = x^2(y^2 + x) + 2y^3 + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = x^2(y^2 + x) + 2y^3$$

Initial conditions are used to solve for c_1 . Substituting $x = 1$ and $y = 2$ in the above solution gives an equation to solve for the constant of integration.

$$21 = c_1$$

$$c_1 = 21$$

Substituting c_1 found above in the general solution gives

$$x^2(y^2 + x) + 2y^3 = 21$$

Summary

The solution(s) found are the following

$$x^2y^2 + x^3 + 2y^3 = 21 \quad (1)$$

Verification of solutions

$$x^2y^2 + x^3 + 2y^3 = 21$$

Verified OK.

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
trying Bernoulli  
trying separable  
trying inverse linear  
trying homogeneous types:  
trying Chini  
differential order: 1; looking for linear symmetries  
trying exact  
<- exact successful`
```

✓ Solution by Maple

Time used: 0.156 (sec). Leaf size: 87

```
dsolve([(3*x^2+2*x*y(x)^2)+(2*x^2*y(x)+6*y(x)^2)*diff(y(x),x)=0,y(1) = 2],y(x), singsol=all)
```

$$y(x) = \frac{(1134 - 54x^3 - x^6 + 6\sqrt{3x^9 + 18x^6 - 3402x^3 + 35721})^{\frac{1}{3}}}{6} + \frac{x^4}{6(1134 - 54x^3 - x^6 + 6\sqrt{3x^9 + 18x^6 - 3402x^3 + 35721})^{\frac{1}{3}}} - \frac{x^2}{6}$$

✓ Solution by Mathematica

Time used: 4.797 (sec). Leaf size: 103

```
DSolve[{(3*x^2+2*x*y[x]^2)+(2*x^2*y[x]+6*y[x]^2)*y'[x]==0,{y[1]==2}},y[x],x,IncludeSingularS
```

$$y(x) \rightarrow \frac{1}{6} \left(-x^2 + \sqrt[3]{-x^6 - 54x^3 + 6\sqrt{3}\sqrt{x^9 + 6x^6 - 1134x^3 + 11907} + 1134} + \frac{x^4}{\sqrt[3]{-x^6 - 54x^3 + 6\sqrt{3}\sqrt{x^9 + 6x^6 - 1134x^3 + 11907} + 1134}} \right)$$

6.19 problem 19

6.19.1 Existence and uniqueness analysis	1491
6.19.2 Solving as separable ode	1492
6.19.3 Solving as first order ode lie symmetry lookup ode	1494
6.19.4 Solving as bernoulli ode	1498
6.19.5 Solving as exact ode	1501
6.19.6 Maple step by step solution	1504

Internal problem ID [11693]

Internal file name [OUTPUT/11702_Wednesday_April_10_2024_04_55_10_PM_49928285/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, Miscellaneous Review. Exercises page 60

Problem number: 19.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"exact", "bernoulli", "separable", "first_order_ode_lie_symmetry_lookup"**

Maple gives the following as the ode type

`[_separable]`

$$4xyy' - y^2 = 1$$

With initial conditions

$$[y(2) = 1]$$

6.19.1 Existence and uniqueness analysis

This is non linear first order ODE. In canonical form it is written as

$$\begin{aligned} y' &= f(x, y) \\ &= \frac{y^2 + 1}{4yx} \end{aligned}$$

The x domain of $f(x, y)$ when $y = 1$ is

$$\{x < 0 \vee 0 < x\}$$

And the point $x_0 = 2$ is inside this domain. The y domain of $f(x, y)$ when $x = 2$ is

$$\{y < 0 \vee 0 < y\}$$

And the point $y_0 = 1$ is inside this domain. Now we will look at the continuity of

$$\begin{aligned}\frac{\partial f}{\partial y} &= \frac{\partial}{\partial y} \left(\frac{y^2 + 1}{4yx} \right) \\ &= \frac{1}{2x} - \frac{y^2 + 1}{4y^2x}\end{aligned}$$

The x domain of $\frac{\partial f}{\partial y}$ when $y = 1$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 2$ is inside this domain. The y domain of $\frac{\partial f}{\partial y}$ when $x = 2$ is

$$\{y < 0 \vee 0 < y\}$$

And the point $y_0 = 1$ is inside this domain. Therefore solution exists and is unique.

6.19.2 Solving as separable ode

In canonical form the ODE is

$$\begin{aligned}y' &= F(x, y) \\ &= f(x)g(y) \\ &= \frac{y^2 + 1}{4yx}\end{aligned}$$

Where $f(x) = \frac{1}{4x}$ and $g(y) = \frac{y^2+1}{y}$. Integrating both sides gives

$$\begin{aligned}\frac{1}{\frac{y^2+1}{y}} dy &= \frac{1}{4x} dx \\ \int \frac{1}{\frac{y^2+1}{y}} dy &= \int \frac{1}{4x} dx \\ \frac{\ln(y^2 + 1)}{2} &= \frac{\ln(x)}{4} + c_1\end{aligned}$$

Raising both side to exponential gives

$$\sqrt{y^2 + 1} = e^{\frac{\ln(x)}{4} + c_1}$$

Which simplifies to

$$\sqrt{y^2 + 1} = c_2 x^{\frac{1}{4}}$$

Which can be simplified to become

$$\sqrt{1 + y^2} = c_2 x^{\frac{1}{4}} e^{c_1}$$

The solution is

$$\sqrt{1 + y^2} = c_2 x^{\frac{1}{4}} e^{c_1}$$

Initial conditions are used to solve for c_1 . Substituting $x = 2$ and $y = 1$ in the above solution gives an equation to solve for the constant of integration.

$$\sqrt{2} = 2^{\frac{1}{4}} e^{c_1} c_2$$

$$c_1 = \frac{\ln\left(\frac{2}{c_2^4}\right)}{4}$$

Substituting c_1 found above in the general solution gives

$$\sqrt{y^2 + 1} = c_2 x^{\frac{1}{4}} \sqrt{\sqrt{2}} \sqrt{\frac{1}{c_2^4}}$$

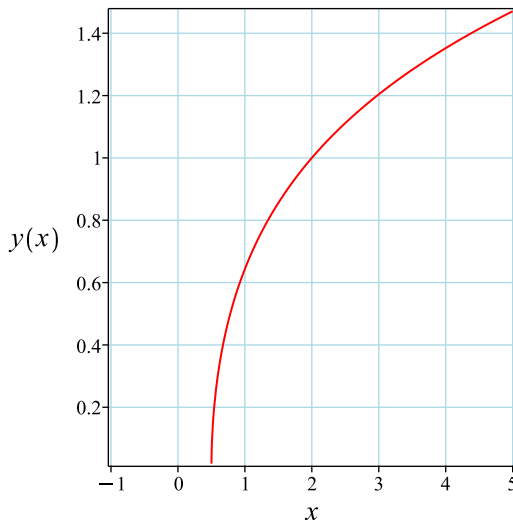
Solving for y from the above gives

$$y = \sqrt{\sqrt{x} \sqrt{2} - 1}$$

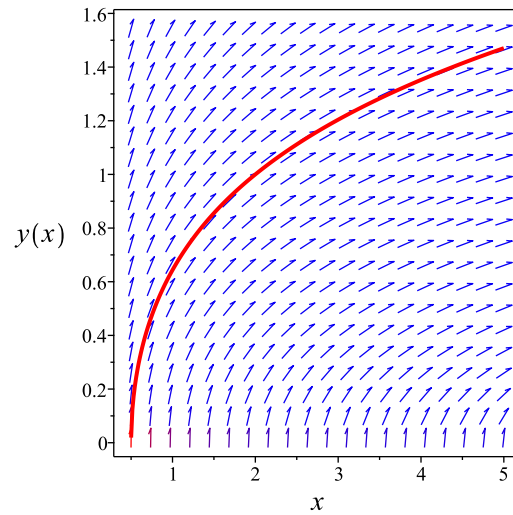
Summary

The solution(s) found are the following

$$y = \sqrt{\sqrt{x} \sqrt{2} - 1} \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \sqrt{\sqrt{x} \sqrt{2} - 1}$$

Verified OK. {positive}

6.19.3 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = \frac{y^2 + 1}{4yx}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **separable**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 236: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 4x \\ \eta(x, y) &= 0\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\eta = 0$ then in this special case

$$R = y$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\xi} dx \\ &= \int \frac{1}{4x} dx \end{aligned}$$

Which results in

$$S = \frac{\ln(x)}{4}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = \frac{y^2 + 1}{4yx}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 0 \\ R_y &= 1 \\ S_x &= \frac{1}{4x} \\ S_y &= 0 \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = \frac{y}{y^2 + 1} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = \frac{R}{R^2 + 1}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = \frac{\ln(R^2 + 1)}{2} + c_1 \quad (4)$$

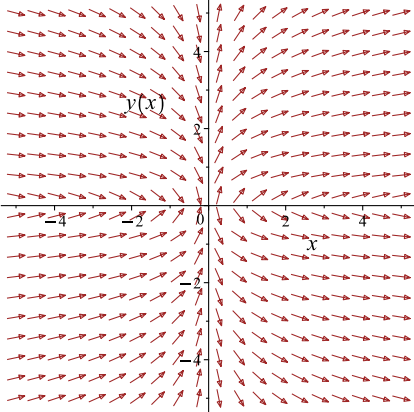
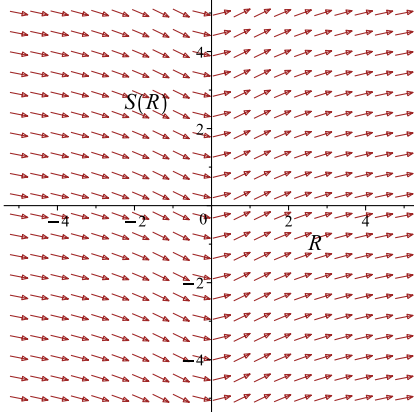
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$\frac{\ln(x)}{4} = \frac{\ln(1 + y^2)}{2} + c_1$$

Which simplifies to

$$\frac{\ln(x)}{4} = \frac{\ln(1 + y^2)}{2} + c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = \frac{y^2+1}{4yx}$ 	$R = y$ $S = \frac{\ln(x)}{4}$	$\frac{dS}{dR} = \frac{R}{R^2+1}$ 

Initial conditions are used to solve for c_1 . Substituting $x = 2$ and $y = 1$ in the above solution gives an equation to solve for the constant of integration.

$$\frac{\ln(2)}{4} = \frac{\ln(2)}{2} + c_1$$

$$c_1 = -\frac{\ln(2)}{4}$$

Substituting c_1 found above in the general solution gives

$$\frac{\ln(x)}{4} = \frac{\ln(y^2 + 1)}{2} - \frac{\ln(2)}{4}$$

Summary

The solution(s) found are the following

$$\frac{\ln(x)}{4} = \frac{\ln(1 + y^2)}{2} - \frac{\ln(2)}{4} \quad (1)$$

Verification of solutions

$$\frac{\ln(x)}{4} = \frac{\ln(1 + y^2)}{2} - \frac{\ln(2)}{4}$$

Verified OK.

6.19.4 Solving as bernoulli ode

In canonical form, the ODE is

$$\begin{aligned} y' &= F(x, y) \\ &= \frac{y^2 + 1}{4yx} \end{aligned}$$

This is a Bernoulli ODE.

$$y' = \frac{1}{4x}y + \frac{1}{4x} \frac{1}{y} \quad (1)$$

The standard Bernoulli ODE has the form

$$y' = f_0(x)y + f_1(x)y^n \quad (2)$$

The first step is to divide the above equation by y^n which gives

$$\frac{y'}{y^n} = f_0(x)y^{1-n} + f_1(x) \quad (3)$$

The next step is use the substitution $w = y^{1-n}$ in equation (3) which generates a new ODE in $w(x)$ which will be linear and can be easily solved using an integrating factor. Backsubstitution then gives the solution $y(x)$ which is what we want.

This method is now applied to the ODE at hand. Comparing the ODE (1) With (2) Shows that

$$\begin{aligned}f_0(x) &= \frac{1}{4x} \\f_1(x) &= \frac{1}{4x} \\n &= -1\end{aligned}$$

Dividing both sides of ODE (1) by $y^n = \frac{1}{y}$ gives

$$y'y = \frac{y^2}{4x} + \frac{1}{4x} \quad (4)$$

Let

$$\begin{aligned}w &= y^{1-n} \\&= y^2\end{aligned} \quad (5)$$

Taking derivative of equation (5) w.r.t x gives

$$w' = 2yy' \quad (6)$$

Substituting equations (5) and (6) into equation (4) gives

$$\begin{aligned}\frac{w'(x)}{2} &= \frac{w(x)}{4x} + \frac{1}{4x} \\w' &= \frac{w}{2x} + \frac{1}{2x}\end{aligned} \quad (7)$$

The above now is a linear ODE in $w(x)$ which is now solved.

Entering Linear first order ODE solver. In canonical form a linear first order is

$$w'(x) + p(x)w(x) = q(x)$$

Where here

$$\begin{aligned}p(x) &= -\frac{1}{2x} \\q(x) &= \frac{1}{2x}\end{aligned}$$

Hence the ode is

$$w'(x) - \frac{w(x)}{2x} = \frac{1}{2x}$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int -\frac{1}{2x} dx} \\ &= \frac{1}{\sqrt{x}}\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu w) &= (\mu) \left(\frac{1}{2x} \right) \\ \frac{d}{dx} \left(\frac{w}{\sqrt{x}} \right) &= \left(\frac{1}{\sqrt{x}} \right) \left(\frac{1}{2x} \right) \\ d \left(\frac{w}{\sqrt{x}} \right) &= \left(\frac{1}{2x^{\frac{3}{2}}} \right) dx\end{aligned}$$

Integrating gives

$$\begin{aligned}\frac{w}{\sqrt{x}} &= \int \frac{1}{2x^{\frac{3}{2}}} dx \\ \frac{w}{\sqrt{x}} &= -\frac{1}{\sqrt{x}} + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = \frac{1}{\sqrt{x}}$ results in

$$w(x) = -1 + c_1\sqrt{x}$$

Replacing w in the above by y^2 using equation (5) gives the final solution.

$$y^2 = -1 + c_1\sqrt{x}$$

Initial conditions are used to solve for c_1 . Substituting $x = 2$ and $y = 1$ in the above solution gives an equation to solve for the constant of integration.

$$1 = -1 + \sqrt{2}c_1$$

$$c_1 = \sqrt{2}$$

Substituting c_1 found above in the general solution gives

$$y^2 = \sqrt{x}\sqrt{2} - 1$$

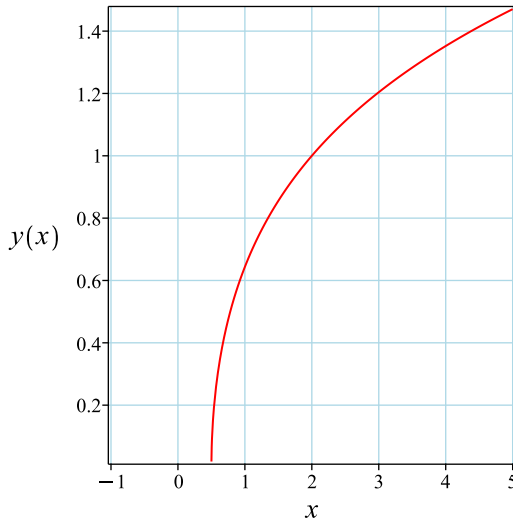
Solving for y from the above gives

$$y = \sqrt{\sqrt{x}\sqrt{2} - 1}$$

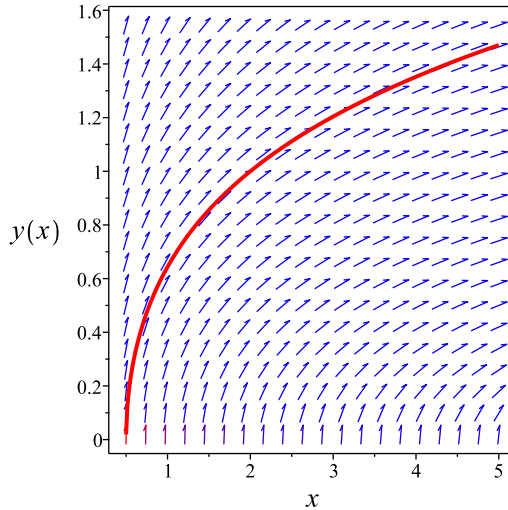
Summary

The solution(s) found are the following

$$y = \sqrt{\sqrt{x} \sqrt{2} - 1} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \sqrt{\sqrt{x} \sqrt{2} - 1}$$

Verified OK. {positive}

6.19.5 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \quad (A)$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \quad (B)$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial\phi}{\partial x} &= M \\ \frac{\partial\phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \tag{1A}$$

Therefore

$$\begin{aligned}\left(\frac{4y}{y^2 + 1}\right) dy &= \left(\frac{1}{x}\right) dx \\ \left(-\frac{1}{x}\right) dx + \left(\frac{4y}{y^2 + 1}\right) dy &= 0\end{aligned} \tag{2A}$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= -\frac{1}{x} \\ N(x, y) &= \frac{4y}{y^2 + 1}\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y} \left(-\frac{1}{x}\right) \\ &= 0\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x} \left(\frac{4y}{y^2 + 1} \right) \\ &= 0\end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \quad (1)$$

$$\frac{\partial \phi}{\partial y} = N \quad (2)$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int M dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int -\frac{1}{x} dx \\ \phi &= -\ln(x) + f(y)\end{aligned} \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = 0 + f'(y) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = \frac{4y}{y^2+1}$. Therefore equation (4) becomes

$$\frac{4y}{y^2 + 1} = 0 + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = \frac{4y}{y^2 + 1}$$

Integrating the above w.r.t y gives

$$\begin{aligned}\int f'(y) dy &= \int \left(\frac{4y}{y^2 + 1} \right) dy \\ f(y) &= 2 \ln(y^2 + 1) + c_1\end{aligned}$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = -\ln(x) + 2\ln(y^2 + 1) + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -\ln(x) + 2\ln(y^2 + 1)$$

Initial conditions are used to solve for c_1 . Substituting $x = 2$ and $y = 1$ in the above solution gives an equation to solve for the constant of integration.

$$\ln(2) = c_1$$

$$c_1 = \ln(2)$$

Substituting c_1 found above in the general solution gives

$$-\ln(x) + 2\ln(y^2 + 1) = \ln(2)$$

Summary

The solution(s) found are the following

$$-\ln(x) + 2\ln(1 + y^2) = \ln(2) \tag{1}$$

Verification of solutions

$$-\ln(x) + 2\ln(1 + y^2) = \ln(2)$$

Verified OK.

6.19.6 Maple step by step solution

Let's solve

$$[4xyy' - y^2 = 1, y(2) = 1]$$

- Highest derivative means the order of the ODE is 1

y'

- Separate variables

$$\frac{y'y}{1+y^2} = \frac{1}{4x}$$

- Integrate both sides with respect to x

$$\int \frac{y'y}{1+y^2} dx = \int \frac{1}{4x} dx + c_1$$

- Evaluate integral

$$\frac{\ln(1+y^2)}{2} = \frac{\ln(x)}{4} + c_1$$

- Use initial condition $y(2) = 1$

$$\frac{\ln(2)}{2} = \frac{\ln(2)}{4} + c_1$$

- Solve for c_1

$$c_1 = \frac{\ln(2)}{4}$$

- Substitute $c_1 = \frac{\ln(2)}{4}$ into general solution and simplify

$$\frac{\ln(1+y^2)}{2} = \frac{\ln(x)}{4} + \frac{\ln(2)}{4}$$

- Solution to the IVP

$$\frac{\ln(1+y^2)}{2} = \frac{\ln(x)}{4} + \frac{\ln(2)}{4}$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
<- Bernoulli successful`

```

✓ Solution by Maple

Time used: 0.062 (sec). Leaf size: 15

```
dsolve([4*x*y(x)*diff(y(x),x)=y(x)^2+1,y(2) = 1],y(x), singsol=all)
```

$$y(x) = \sqrt{\sqrt{2} \sqrt{x} - 1}$$

✓ Solution by Mathematica

Time used: 3.741 (sec). Leaf size: 22

```
DSolve[{4*x*y[x]*y'[x]==y[x]^2+1,{y[2]==1}},y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \sqrt{\sqrt{2}\sqrt{x} - 1}$$

6.20 problem 20

- 6.20.1 Existence and uniqueness analysis 1507
- 6.20.2 Solving as homogeneousTypeD2 ode 1508
- 6.20.3 Solving as first order ode lie symmetry calculated ode 1510

Internal problem ID [11694]

Internal file name [OUTPUT/11703_Wednesday_April_10_2024_04_55_13_PM_71646592/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 2, Miscellaneous Review. Exercises page 60

Problem number: 20.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**homogeneousTypeD2**", "**first_order_ode_lie_symmetry_calculated**"

Maple gives the following as the ode type

```
[[_homogeneous, `class A`], _rational, [_Abel, `2nd type`, `class A`]]
```

$$y' - \frac{2x + 7y}{-2y + 2x} = 0$$

With initial conditions

$$[y(1) = 2]$$

6.20.1 Existence and uniqueness analysis

This is non linear first order ODE. In canonical form it is written as

$$\begin{aligned} y' &= f(x, y) \\ &= -\frac{2x + 7y}{2(y - x)} \end{aligned}$$

The x domain of $f(x, y)$ when $y = 2$ is

$$\{x < 2 \vee 2 < x\}$$

And the point $x_0 = 1$ is inside this domain. The y domain of $f(x, y)$ when $x = 1$ is

$$\{y < 1 \vee 1 < y\}$$

And the point $y_0 = 2$ is inside this domain. Now we will look at the continuity of

$$\begin{aligned} \frac{\partial f}{\partial y} &= \frac{\partial}{\partial y} \left(-\frac{2x + 7y}{2(y - x)} \right) \\ &= -\frac{7}{2(y - x)} + \frac{2x + 7y}{2(y - x)^2} \end{aligned}$$

The x domain of $\frac{\partial f}{\partial y}$ when $y = 2$ is

$$\{x < 2 \vee 2 < x\}$$

And the point $x_0 = 1$ is inside this domain. The y domain of $\frac{\partial f}{\partial y}$ when $x = 1$ is

$$\{y < 1 \vee 1 < y\}$$

And the point $y_0 = 2$ is inside this domain. Therefore solution exists and is unique.

6.20.2 Solving as homogeneous Type D2 ode

Using the change of variables $y = u(x)x$ on the above ode results in new ode in $u(x)$

$$u'(x)x + u(x) - \frac{2x + 7u(x)x}{-2u(x)x + 2x} = 0$$

In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= -\frac{2u^2 + 5u + 2}{2x(u - 1)} \end{aligned}$$

Where $f(x) = -\frac{1}{2x}$ and $g(u) = \frac{2u^2 + 5u + 2}{u - 1}$. Integrating both sides gives

$$\begin{aligned} \frac{1}{\frac{2u^2 + 5u + 2}{u - 1}} du &= -\frac{1}{2x} dx \\ \int \frac{1}{\frac{2u^2 + 5u + 2}{u - 1}} du &= \int -\frac{1}{2x} dx \\ -\frac{\ln(2u + 1)}{2} + \ln(u + 2) &= -\frac{\ln(x)}{2} + c_2 \end{aligned}$$

Raising both side to exponential gives

$$e^{-\frac{\ln(2u+1)}{2} + \ln(u+2)} = e^{-\frac{\ln(x)}{2} + c_2}$$

Which simplifies to

$$\frac{u+2}{\sqrt{2u+1}} = \frac{c_3}{\sqrt{x}}$$

The solution is

$$\frac{u(x)+2}{\sqrt{2u(x)+1}} = \frac{c_3}{\sqrt{x}}$$

Replacing $u(x)$ in the above solution by $\frac{y}{x}$ results in the solution for y in implicit form

$$\begin{aligned} \frac{\frac{y}{x} + 2}{\sqrt{\frac{2y}{x} + 1}} &= \frac{c_3}{\sqrt{x}} \\ \frac{2x + y}{\sqrt{\frac{x+2y}{x}} \sqrt{x}} &= \frac{c_3}{\sqrt{x}} \end{aligned}$$

Which simplifies to

$$\frac{2x + y}{\sqrt{\frac{x+2y}{x}} \sqrt{x}} = c_3$$

Substituting initial conditions and solving for c_3 gives $c_3 = \frac{4\sqrt{5}}{5}$. Hence the solution be-

Summary

The solution(s) found are the following

comes

$$\frac{2x + y}{\sqrt{\frac{x+2y}{x}} \sqrt{x}} = \frac{4\sqrt{5}}{5} \quad (1)$$

Verification of solutions

$$\frac{2x + y}{\sqrt{\frac{x+2y}{x}} \sqrt{x}} = \frac{4\sqrt{5}}{5}$$

Verified OK.

6.20.3 Solving as first order ode lie symmetry calculated ode

Writing the ode as

$$y' = -\frac{2x + 7y}{2(y - x)}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is not in the lookup table. To determine ξ, η then (A) is solved using ansatz. Making bivariate polynomials of degree 1 to use as anstaz gives

$$\xi = xa_2 + ya_3 + a_1 \quad (\text{1E})$$

$$\eta = xb_2 + yb_3 + b_1 \quad (\text{2E})$$

Where the unknown coefficients are

$$\{a_1, a_2, a_3, b_1, b_2, b_3\}$$

Substituting equations (1E,2E) and ω into (A) gives

$$b_2 - \frac{(2x + 7y)(b_3 - a_2)}{2(y - x)} - \frac{(2x + 7y)^2 a_3}{4(y - x)^2}$$

$$- \left(-\frac{1}{y - x} - \frac{2x + 7y}{2(y - x)^2} \right) (xa_2 + ya_3 + a_1) \quad (\text{5E})$$

$$- \left(-\frac{7}{2(y - x)} + \frac{2x + 7y}{2(y - x)^2} \right) (xb_2 + yb_3 + b_1) = 0$$

Putting the above in normal form gives

$$\frac{4x^2 a_2 + 4x^2 a_3 + 14x^2 b_2 - 4x^2 b_3 - 8xy a_2 + 28xy a_3 + 8xy b_2 + 8xy b_3 - 14y^2 a_2 + 31y^2 a_3 - 4y^2 b_2 + 14y^2 b_3}{4(-y + x)^2}$$

$$= 0$$

Setting the numerator to zero gives

$$-4x^2 a_2 - 4x^2 a_3 - 14x^2 b_2 + 4x^2 b_3 + 8xy a_2 - 28xy a_3 - 8xy b_2$$

$$- 8xy b_3 + 14y^2 a_2 - 31y^2 a_3 + 4y^2 b_2 - 14y^2 b_3 - 18xb_1 + 18ya_1 = 0 \quad (\text{6E})$$

Looking at the above PDE shows the following are all the terms with $\{x, y\}$ in them.

$$\{x, y\}$$

The following substitution is now made to be able to collect on all terms with $\{x, y\}$ in them

$$\{x = v_1, y = v_2\}$$

The above PDE (6E) now becomes

$$\begin{aligned} -4a_2v_1^2 + 8a_2v_1v_2 + 14a_2v_2^2 - 4a_3v_1^2 - 28a_3v_1v_2 - 31a_3v_2^2 - 14b_2v_1^2 \\ - 8b_2v_1v_2 + 4b_2v_2^2 + 4b_3v_1^2 - 8b_3v_1v_2 - 14b_3v_2^2 + 18a_1v_2 - 18b_1v_1 = 0 \end{aligned} \quad (7E)$$

Collecting the above on the terms v_i introduced, and these are

$$\{v_1, v_2\}$$

Equation (7E) now becomes

$$\begin{aligned} (-4a_2 - 4a_3 - 14b_2 + 4b_3)v_1^2 + (8a_2 - 28a_3 - 8b_2 - 8b_3)v_1v_2 \\ - 18b_1v_1 + (14a_2 - 31a_3 + 4b_2 - 14b_3)v_2^2 + 18a_1v_2 = 0 \end{aligned} \quad (8E)$$

Setting each coefficients in (8E) to zero gives the following equations to solve

$$\begin{aligned} 18a_1 &= 0 \\ -18b_1 &= 0 \\ -4a_2 - 4a_3 - 14b_2 + 4b_3 &= 0 \\ 8a_2 - 28a_3 - 8b_2 - 8b_3 &= 0 \\ 14a_2 - 31a_3 + 4b_2 - 14b_3 &= 0 \end{aligned}$$

Solving the above equations for the unknowns gives

$$\begin{aligned} a_1 &= 0 \\ a_2 &= -\frac{5b_2}{2} + b_3 \\ a_3 &= -b_2 \\ b_1 &= 0 \\ b_2 &= b_2 \\ b_3 &= b_3 \end{aligned}$$

Substituting the above solution in the anstaz (1E,2E) (using 1 as arbitrary value for any unknown in the RHS) gives

$$\begin{aligned}\xi &= x \\ \eta &= y\end{aligned}$$

Shifting is now applied to make $\xi = 0$ in order to simplify the rest of the computation

$$\begin{aligned}\eta &= \eta - \omega(x, y) \xi \\ &= y - \left(-\frac{2x + 7y}{2(y - x)} \right) (x) \\ &= \frac{-2x^2 - 5xy - 2y^2}{-2y + 2x} \\ \xi &= 0\end{aligned}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \quad (1)$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y} \right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned}S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{-2x^2 - 5xy - 2y^2}{-2y + 2x}} dy\end{aligned}$$

Which results in

$$S = 2 \ln(2x + y) - \ln(x + 2y)$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y) S_y}{R_x + \omega(x, y) R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{2x + 7y}{2(y - x)}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= \frac{4}{2x + y} - \frac{1}{x + 2y} \\ S_y &= \frac{2y - 2x}{(x + 2y)(2x + y)} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 0 \tag{2A}$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 0$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = c_1 \tag{4}$$

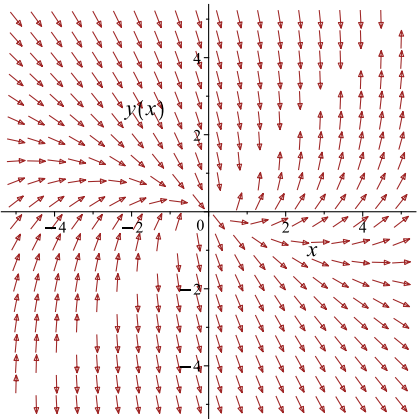
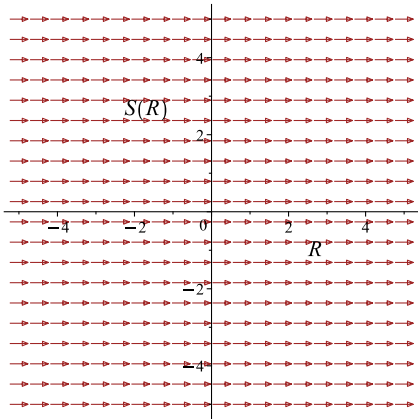
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$2 \ln(2x + y) - \ln(x + 2y) = c_1$$

Which simplifies to

$$2 \ln(2x + y) - \ln(x + 2y) = c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{2x+7y}{2(y-x)}$ 	$R = x$ $S = 2 \ln(2x + y) - \ln(x)$	$\frac{dS}{dR} = 0$ 

Initial conditions are used to solve for c_1 . Substituting $x = 1$ and $y = 2$ in the above solution gives an equation to solve for the constant of integration.

$$4 \ln(2) - \ln(5) = c_1$$

$$c_1 = 4 \ln(2) - \ln(5)$$

Substituting c_1 found above in the general solution gives

$$2 \ln(2x + y) - \ln(x + 2y) = 4 \ln(2) - \ln(5)$$

Summary

The solution(s) found are the following

$$2 \ln(2x + y) - \ln(x + 2y) = 4 \ln(2) - \ln(5) \quad (1)$$

Verification of solutions

$$2 \ln(2x + y) - \ln(x + 2y) = 4 \ln(2) - \ln(5)$$

Verified OK.

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
trying Bernoulli  
trying separable  
trying inverse linear  
trying homogeneous types:  
trying homogeneous D  
<- homogeneous successful`
```

✓ Solution by Maple

Time used: 0.203 (sec). Leaf size: 18

```
dsolve([diff(y(x),x)=(2*x+7*y(x))/(2*x-2*y(x)),y(1) = 2],y(x), singsol=all)
```

$$y(x) = \frac{4\sqrt{16-15x}}{5} - 2x + \frac{16}{5}$$

✓ Solution by Mathematica

Time used: 1.383 (sec). Leaf size: 25

```
DSolve[{y'[x]==(2*x+7*y[x])/(2*x-2*y[x]),{y[1]==2}},y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{2}{5}(-5x + 2\sqrt{16-15x} + 8)$$

6.21 problem 21

6.21.1 Existence and uniqueness analysis	1517
6.21.2 Solving as separable ode	1517
6.21.3 Solving as linear ode	1519
6.21.4 Solving as homogeneousTypeD2 ode	1520
6.21.5 Solving as first order ode lie symmetry lookup ode	1522
6.21.6 Solving as exact ode	1527
6.21.7 Maple step by step solution	1530

Internal problem ID [11695]

Internal file name [OUTPUT/11704_Wednesday_April_10_2024_04_55_15_PM_67684932/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, Miscellaneous Review. Exercises page 60

Problem number: 21.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact", "linear", "separable", "homogeneousTypeD2", "first_order_ode_lie_symmetry_lookup"

Maple gives the following as the ode type

`[_separable]`

$$y' - \frac{xy}{x^2 + 1} = 0$$

With initial conditions

$$[y(\sqrt{15}) = 2]$$

6.21.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = -\frac{x}{x^2 + 1}$$

$$q(x) = 0$$

Hence the ode is

$$y' - \frac{xy}{x^2 + 1} = 0$$

The domain of $p(x) = -\frac{x}{x^2+1}$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = \sqrt{15}$ is inside this domain. Hence solution exists and is unique.

6.21.2 Solving as separable ode

In canonical form the ODE is

$$\begin{aligned}y' &= F(x, y) \\ &= f(x)g(y) \\ &= \frac{xy}{x^2 + 1}\end{aligned}$$

Where $f(x) = \frac{x}{x^2+1}$ and $g(y) = y$. Integrating both sides gives

$$\begin{aligned}\frac{1}{y} dy &= \frac{x}{x^2 + 1} dx \\ \int \frac{1}{y} dy &= \int \frac{x}{x^2 + 1} dx \\ \ln(y) &= \frac{\ln(x^2 + 1)}{2} + c_1 \\ y &= e^{\frac{\ln(x^2+1)}{2} + c_1} \\ &= c_1 \sqrt{x^2 + 1}\end{aligned}$$

Initial conditions are used to solve for c_1 . Substituting $x = \sqrt{15}$ and $y = 2$ in the above solution gives an equation to solve for the constant of integration.

$$2 = 4c_1$$

$$c_1 = \frac{1}{2}$$

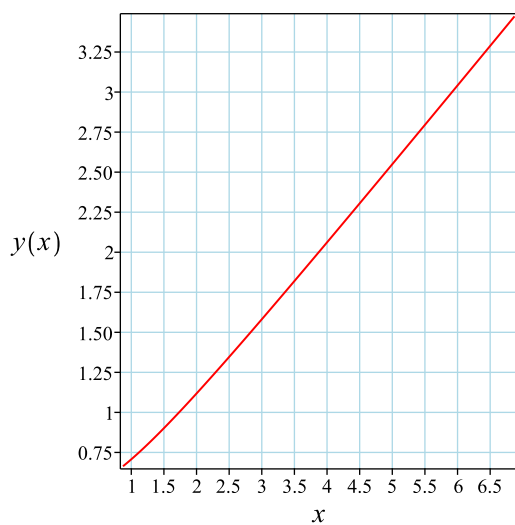
Substituting c_1 found above in the general solution gives

$$y = \frac{\sqrt{x^2 + 1}}{2}$$

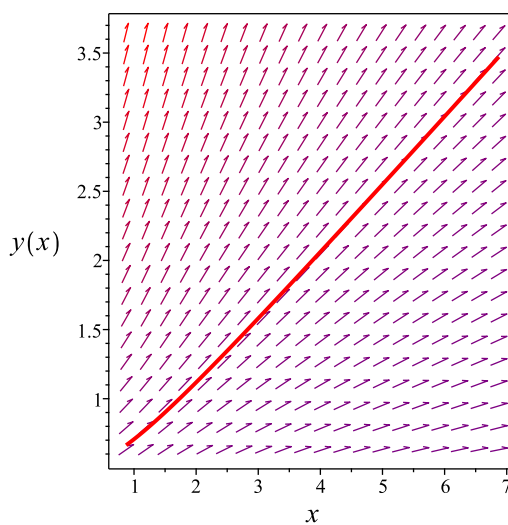
Summary

The solution(s) found are the following

$$y = \frac{\sqrt{x^2 + 1}}{2} \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \frac{\sqrt{x^2 + 1}}{2}$$

Verified OK.

6.21.3 Solving as linear ode

Entering Linear first order ODE solver. The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int -\frac{x}{x^2+1} dx} \\ &= \frac{1}{\sqrt{x^2+1}}\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}\mu y &= 0 \\ \frac{d}{dx}\left(\frac{y}{\sqrt{x^2+1}}\right) &= 0\end{aligned}$$

Integrating gives

$$\frac{y}{\sqrt{x^2+1}} = c_1$$

Dividing both sides by the integrating factor $\mu = \frac{1}{\sqrt{x^2+1}}$ results in

$$y = c_1\sqrt{x^2+1}$$

Initial conditions are used to solve for c_1 . Substituting $x = \sqrt{15}$ and $y = 2$ in the above solution gives an equation to solve for the constant of integration.

$$2 = 4c_1$$

$$c_1 = \frac{1}{2}$$

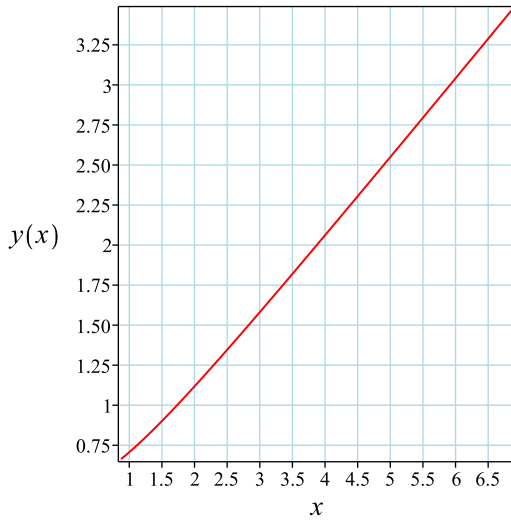
Substituting c_1 found above in the general solution gives

$$y = \frac{\sqrt{x^2+1}}{2}$$

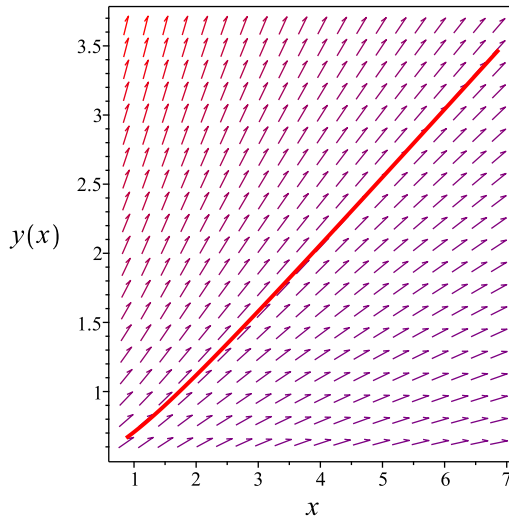
Summary

The solution(s) found are the following

$$y = \frac{\sqrt{x^2+1}}{2} \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \frac{\sqrt{x^2 + 1}}{2}$$

Verified OK.

6.21.4 Solving as homogeneousTypeD2 ode

Using the change of variables $y = u(x)x$ on the above ode results in new ode in $u(x)$

$$u'(x)x + u(x) - \frac{x^2 u(x)}{x^2 + 1} = 0$$

In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= -\frac{u}{x(x^2 + 1)} \end{aligned}$$

Where $f(x) = -\frac{1}{x(x^2+1)}$ and $g(u) = u$. Integrating both sides gives

$$\begin{aligned}\frac{1}{u} du &= -\frac{1}{x(x^2+1)} dx \\ \int \frac{1}{u} du &= \int -\frac{1}{x(x^2+1)} dx \\ \ln(u) &= -\ln(x) + \frac{\ln(x^2+1)}{2} + c_2 \\ u &= e^{-\ln(x) + \frac{\ln(x^2+1)}{2} + c_2} \\ &= c_2 e^{-\ln(x) + \frac{\ln(x^2+1)}{2}}\end{aligned}$$

Which simplifies to

$$u(x) = \frac{c_2 \sqrt{x^2+1}}{x}$$

Therefore the solution y is

$$\begin{aligned}y &= xu \\ &= c_2 \sqrt{x^2+1}\end{aligned}$$

Initial conditions are used to solve for c_2 . Substituting $x = \sqrt{15}$ and $y = 2$ in the above solution gives an equation to solve for the constant of integration.

$$2 = 4c_2$$

$$c_2 = \frac{1}{2}$$

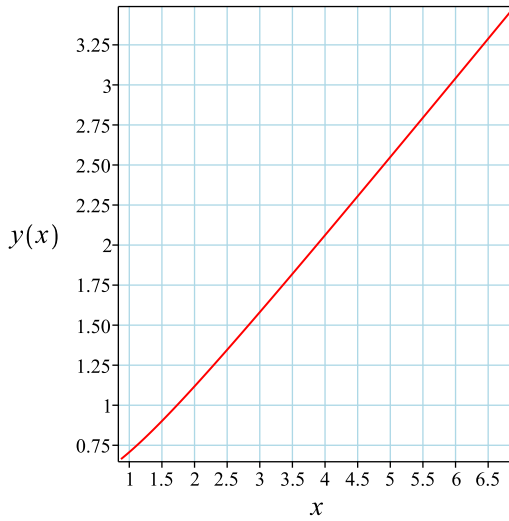
Substituting c_2 found above in the general solution gives

$$y = \frac{\sqrt{x^2+1}}{2}$$

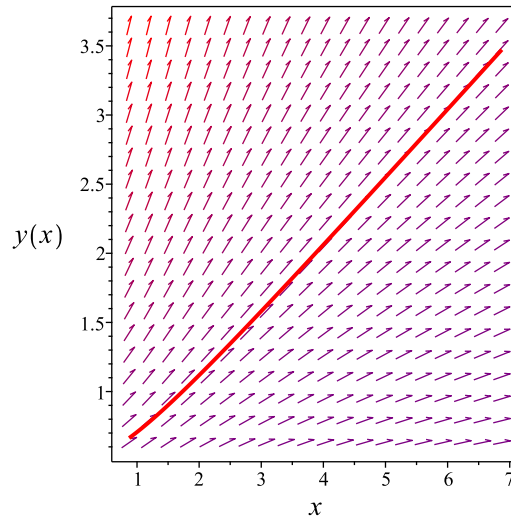
Summary

The solution(s) found are the following

$$y = \frac{\sqrt{x^2+1}}{2} \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \frac{\sqrt{x^2 + 1}}{2}$$

Verified OK.

6.21.5 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = \frac{xy}{x^2 + 1}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 239: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= \sqrt{x^2 + 1}\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right)S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\sqrt{x^2 + 1}} dy \end{aligned}$$

Which results in

$$S = \frac{y}{\sqrt{x^2 + 1}}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = \frac{xy}{x^2 + 1}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= -\frac{yx}{(x^2 + 1)^{\frac{3}{2}}} \\ S_y &= \frac{1}{\sqrt{x^2 + 1}} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 0 \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 0$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = c_1 \tag{4}$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$\frac{y}{\sqrt{x^2 + 1}} = c_1$$

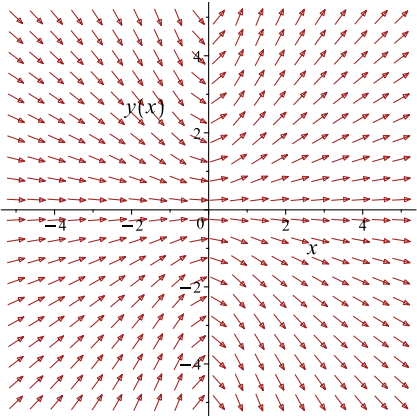
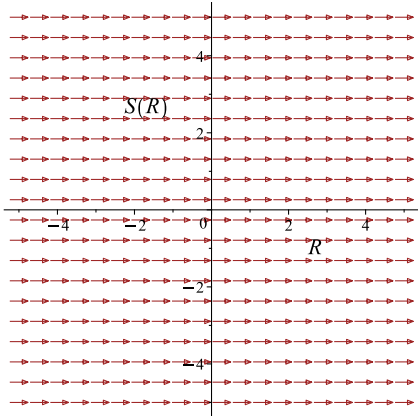
Which simplifies to

$$\frac{y}{\sqrt{x^2 + 1}} = c_1$$

Which gives

$$y = c_1 \sqrt{x^2 + 1}$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = \frac{xy}{x^2+1}$ 	$R = x$ $S = \frac{y}{\sqrt{x^2 + 1}}$	$\frac{dS}{dR} = 0$ 

Initial conditions are used to solve for c_1 . Substituting $x = \sqrt{15}$ and $y = 2$ in the above solution gives an equation to solve for the constant of integration.

$$2 = 4c_1$$

$$c_1 = \frac{1}{2}$$

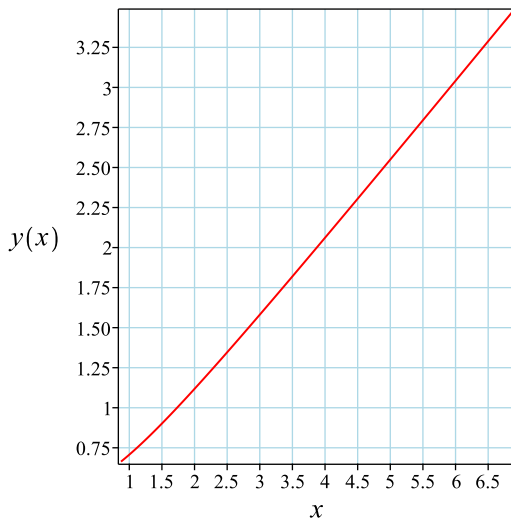
Substituting c_1 found above in the general solution gives

$$y = \frac{\sqrt{x^2 + 1}}{2}$$

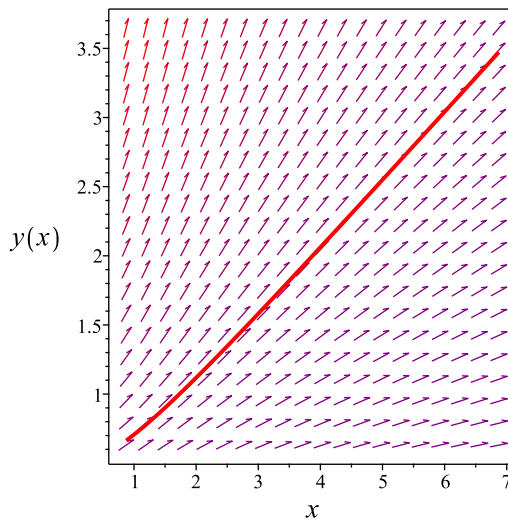
Summary

The solution(s) found are the following

$$y = \frac{\sqrt{x^2 + 1}}{2} \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \frac{\sqrt{x^2 + 1}}{2}$$

Verified OK.

6.21.6 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \quad (\text{A})$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx}\phi(x, y) = 0$$

Hence

$$\frac{\partial\phi}{\partial x} + \frac{\partial\phi}{\partial y} \frac{dy}{dx} = 0 \quad (\text{B})$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial\phi}{\partial x} &= M \\ \frac{\partial\phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2\phi}{\partial x\partial y} = \frac{\partial^2\phi}{\partial y\partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (\text{1A})$$

Therefore

$$\begin{aligned} \left(\frac{1}{y}\right) dy &= \left(\frac{x}{x^2+1}\right) dx \\ \left(-\frac{x}{x^2+1}\right) dx + \left(\frac{1}{y}\right) dy &= 0 \end{aligned} \quad (\text{2A})$$

Comparing (1A) and (2A) shows that

$$M(x, y) = -\frac{x}{x^2 + 1}$$
$$N(x, y) = \frac{1}{y}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\frac{\partial M}{\partial y} = \frac{\partial}{\partial y} \left(-\frac{x}{x^2 + 1} \right)$$
$$= 0$$

And

$$\frac{\partial N}{\partial x} = \frac{\partial}{\partial x} \left(\frac{1}{y} \right)$$
$$= 0$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \tag{1}$$

$$\frac{\partial \phi}{\partial y} = N \tag{2}$$

Integrating (1) w.r.t. x gives

$$\int \frac{\partial \phi}{\partial x} dx = \int M dx$$

$$\int \frac{\partial \phi}{\partial x} dx = \int -\frac{x}{x^2 + 1} dx$$

$$\phi = -\frac{\ln(x^2 + 1)}{2} + f(y) \tag{3}$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = 0 + f'(y) \tag{4}$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = \frac{1}{y}$. Therefore equation (4) becomes

$$\frac{1}{y} = 0 + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = \frac{1}{y}$$

Integrating the above w.r.t y gives

$$\int f'(y) \, dy = \int \left(\frac{1}{y} \right) \, dy$$
$$f(y) = \ln(y) + c_1$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = -\frac{\ln(x^2 + 1)}{2} + \ln(y) + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = -\frac{\ln(x^2 + 1)}{2} + \ln(y)$$

The solution becomes

$$y = e^{\frac{\ln(x^2+1)}{2} + c_1}$$

Initial conditions are used to solve for c_1 . Substituting $x = \sqrt{15}$ and $y = 2$ in the above solution gives an equation to solve for the constant of integration.

$$2 = 4 e^{c_1}$$

$$c_1 = -\ln(2)$$

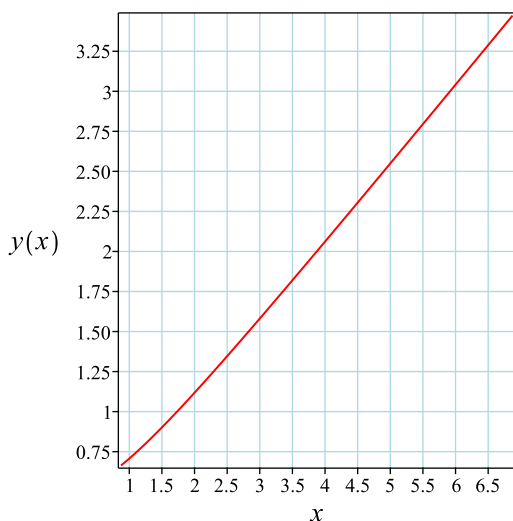
Substituting c_1 found above in the general solution gives

$$y = \frac{\sqrt{x^2 + 1}}{2}$$

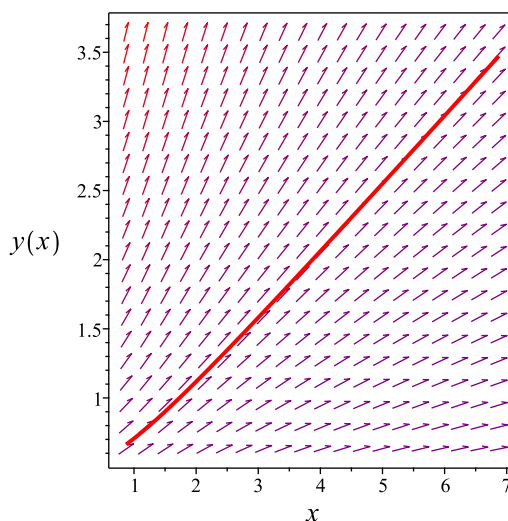
Summary

The solution(s) found are the following

$$y = \frac{\sqrt{x^2 + 1}}{2} \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \frac{\sqrt{x^2 + 1}}{2}$$

Verified OK.

6.21.7 Maple step by step solution

Let's solve

$$\left[y' - \frac{xy}{x^2+1} = 0, y(\sqrt{15}) = 2 \right]$$

- Highest derivative means the order of the ODE is 1

y'

- Separate variables

$$\frac{y'}{y} = \frac{x}{x^2+1}$$
- Integrate both sides with respect to x

$$\int \frac{y'}{y} dx = \int \frac{x}{x^2+1} dx + c_1$$
- Evaluate integral

$$\ln(y) = \frac{\ln(x^2+1)}{2} + c_1$$
- Solve for y

$$y = e^{\frac{\ln(x^2+1)}{2} + c_1}$$
- Use initial condition $y(\sqrt{15}) = 2$

$$2 = e^{2\ln(2) + c_1}$$
- Solve for c_1

$$c_1 = -\ln(2)$$
- Substitute $c_1 = -\ln(2)$ into general solution and simplify

$$y = \frac{\sqrt{x^2+1}}{2}$$
- Solution to the IVP

$$y = \frac{\sqrt{x^2+1}}{2}$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
<- 1st order linear successful`

```

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 13

```
dsolve([diff(y(x),x)=(x*y(x))/(x^2+1),y(sqrt(15)) = 2],y(x), singsol=all)
```

$$y(x) = \frac{\sqrt{x^2+1}}{2}$$

✓ Solution by Mathematica

Time used: 0.028 (sec). Leaf size: 18

```
DSolve[{y'[x]==(x*y[x])/(x^2+1)},{y[Sqrt[15]]==2},y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{\sqrt{x^2 + 1}}{2}$$

6.22 problem 22

6.22.1 Existence and uniqueness analysis	1533
6.22.2 Solving as linear ode	1534
6.22.3 Solving as first order ode lie symmetry lookup ode	1537
6.22.4 Maple step by step solution	1541

Internal problem ID [11696]

Internal file name [OUTPUT/11705_Wednesday_April_10_2024_04_55_16_PM_71593933/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, Miscellaneous Review. Exercises page 60

Problem number: 22.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**linear**", "**first_order_ode_lie_symmetry_lookup**"

Maple gives the following as the ode type

```
[[_linear, `class A`]]
```

$$y' + y = \begin{cases} 1 & 0 \leq x < 2 \\ 0 & 0 < x \end{cases}$$

With initial conditions

$$[y(0) = 0]$$

6.22.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = 1$$
$$q(x) = \begin{cases} 0 & x < 0 \\ 1 & 0 < x < 2 \\ 0 & 2 \leq x \end{cases}$$

Hence the ode is

$$y' + y = \begin{cases} 0 & x < 0 \\ 1 & 0 < x < 2 \\ 0 & 2 \leq x \end{cases}$$

The domain of $p(x) = 1$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = \begin{cases} 0 & x < 0 \\ 1 & 0 < x < 2 \\ 0 & 2 \leq x \end{cases}$ is

$$\{0 \leq x \leq 2, 2 \leq x \leq \infty, -\infty \leq x \leq 0\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

6.22.2 Solving as linear ode

Entering Linear first order ODE solver. The integrating factor μ is

$$\begin{aligned} \mu &= e^{\int 1 dx} \\ &= e^x \end{aligned}$$

The ode becomes

$$\frac{d}{dx}(\mu y) = (\mu) \left(\begin{cases} 0 & x < 0 \\ 1 & x < 2 \\ 0 & 2 \leq x \end{cases} \right)$$

$$\frac{d}{dx}(e^x y) = (e^x) \left(\begin{cases} 0 & x < 0 \\ 1 & x < 2 \\ 0 & 2 \leq x \end{cases} \right)$$

$$d(e^x y) = \begin{cases} 0 & x < 0 \\ e^x & x < 2 \quad dx \\ 0 & 2 \leq x \end{cases}$$

Integrating gives

$$e^x y = \int \begin{cases} 0 & x < 0 \\ e^x & x < 2 \quad dx \\ 0 & 2 \leq x \end{cases}$$

$$e^x y = \begin{cases} 0 & x \leq 0 \\ -1 + e^x & x \leq 2 \quad + c_1 \\ e^2 - 1 & 2 < x \end{cases}$$

Dividing both sides by the integrating factor $\mu = e^x$ results in

$$y = e^{-x} \left(\begin{cases} 0 & x \leq 0 \\ -1 + e^x & x \leq 2 \\ e^2 - 1 & 2 < x \end{cases} \right) + c_1 e^{-x}$$

which simplifies to

$$y = e^{-x} \left(\left(\begin{cases} 0 & x \leq 0 \\ -1 + e^x & x \leq 2 \\ e^2 - 1 & 2 < x \end{cases} \right) + c_1 \right)$$

Initial conditions are used to solve for c_1 . Substituting $x = 0$ and $y = 0$ in the above solution gives an equation to solve for the constant of integration.

$$0 = c_1$$

$$c_1 = 0$$

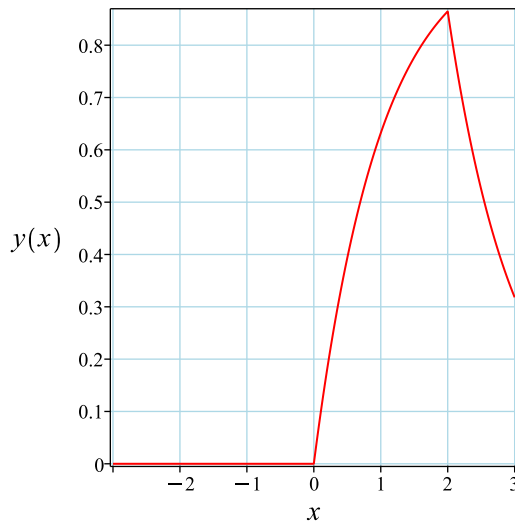
Substituting c_1 found above in the general solution gives

$$y = \begin{cases} 0 & x \leq 0 \\ 1 - e^{-x} & 0 < x \leq 2 \\ e^{-x+2} - e^{-x} & 2 < x \\ 0 & \text{otherwise} \end{cases}$$

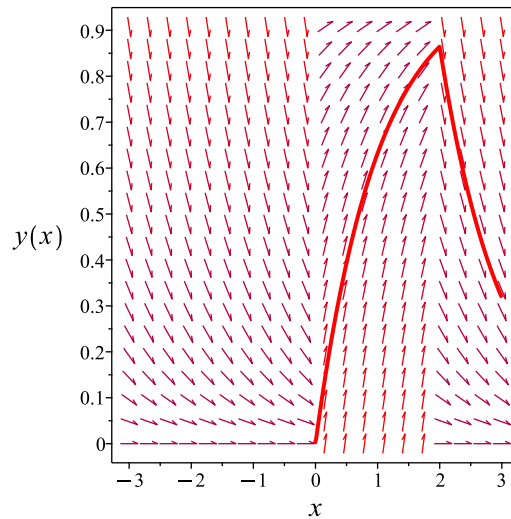
Summary

The solution(s) found are the following

$$y = \begin{cases} 0 & x \leq 0 \\ 1 - e^{-x} & 0 < x \leq 2 \\ e^{-x+2} - e^{-x} & 2 < x \\ 0 & \text{otherwise} \end{cases} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \begin{cases} 0 & x \leq 0 \\ 1 - e^{-x} & 0 < x \leq 2 \\ e^{-x+2} - e^{-x} & 2 < x \\ 0 & \text{otherwise} \end{cases}$$

Verified OK.

6.22.3 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = -y + \begin{pmatrix} 1 & 0 \leq x < 2 \\ 0 & 0 < x \end{pmatrix}$$
$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 242: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= e^{-x}\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{e^{-x}} dy \end{aligned}$$

Which results in

$$S = e^x y$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -y + \left(\begin{cases} 1 & 0 \leq x < 2 \\ 0 & 0 < x \end{cases} \right)$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= e^x y \\ S_y &= e^x \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = \begin{cases} 0 & x < 0 \\ e^x & 0 < x < 2 \\ 0 & 2 \leq x \end{cases} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = \begin{cases} 0 & R < 0 \\ e^R & 0 < R < 2 \\ 0 & 2 \leq R \end{cases}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = \begin{cases} c_1 & R < 0 \\ c_1 + e^R - 1 & 0 < R < 2 \\ c_1 + e^2 - 1 & 2 \leq R \end{cases} \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$y e^x = \begin{cases} c_1 & x < 0 \\ c_1 - 1 + e^x & 0 < x < 2 \\ c_1 + e^2 - 1 & 2 \leq x \end{cases}$$

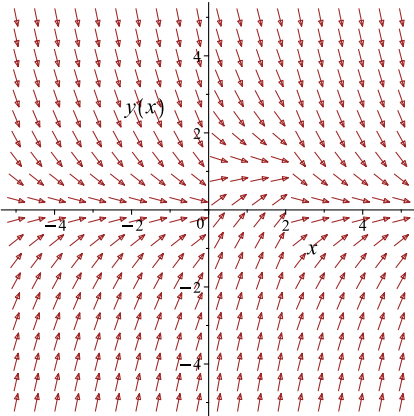
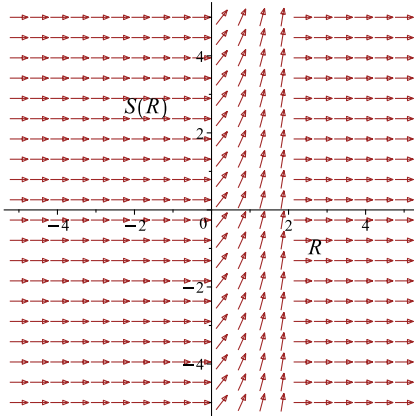
Which simplifies to

$$y e^x = \begin{cases} c_1 & x < 0 \\ c_1 - 1 + e^x & 0 < x < 2 \\ c_1 + e^2 - 1 & 2 \leq x \end{cases}$$

Which gives

$$y = \begin{cases} [c_1 e^{-x}] & x < 0 \\ [1 + (-1 + c_1) e^{-x}] & 0 < x < 2 \\ [e^{-x}(c_1 + e^2 - 1)] & 2 \leq x \end{cases}$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -y + \begin{cases} 1 & 0 \leq x < 2 \\ 0 & 0 < x \end{cases}$ 	$R = x$ $S = e^x y$	$\frac{dS}{dR} = \begin{cases} 0 & R < 0 \\ e^R & 0 < R < 2 \\ 0 & 2 \leq R \end{cases}$ 

Initial conditions are used to solve for c_1 . Substituting $x = 0$ and $y = 0$ in the above solution gives an equation to solve for the constant of integration.

$$0 = [c_1]$$

Unable to solve for constant of integration. Verification of solutions N/A

6.22.4 Maple step by step solution

Let's solve

$$\left[y' + y = \begin{cases} 1 & 0 \leq x < 2 \\ 0 & 0 < x \end{cases}, y(0) = 0 \right]$$

- Highest derivative means the order of the ODE is 1
- y'
- Isolate the derivative

$$y' = -y + \begin{cases} 1 & 0 \leq x < 2 \\ 0 & 0 < x \end{cases}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE

$$y' + y = \begin{cases} 1 & 0 \leq x < 2 \\ 0 & 0 < x \end{cases}$$

- The ODE is linear; multiply by an integrating factor $\mu(x)$

$$\mu(x)(y' + y) = \mu(x) \left(\begin{cases} 1 & 0 \leq x < 2 \\ 0 & 0 < x \end{cases} \right)$$

- Assume the lhs of the ODE is the total derivative $\frac{d}{dx}(\mu(x)y)$

$$\mu(x)(y' + y) = \mu'(x)y + \mu(x)y'$$

- Isolate $\mu'(x)$

$$\mu'(x) = \mu(x)$$

- Solve to find the integrating factor

$$\mu(x) = e^x$$

- Integrate both sides with respect to x

$$\int \left(\frac{d}{dx}(\mu(x)y) \right) dx = \int \mu(x) \left(\begin{cases} 1 & 0 \leq x < 2 \\ 0 & 0 < x \end{cases} \right) dx + c_1$$

- Evaluate the integral on the lhs

$$\mu(x)y = \int \mu(x) \left(\begin{cases} 1 & 0 \leq x < 2 \\ 0 & 0 < x \end{cases} \right) dx + c_1$$

- Solve for y

$$y = \frac{\int \mu(x) \left(\begin{cases} 1 & 0 \leq x < 2 \\ 0 & 0 < x \end{cases} \right) dx + c_1}{\mu(x)}$$

- Substitute $\mu(x) = e^x$

$$y = \frac{\int e^x \left(\begin{cases} 1 & 0 \leq x < 2 \\ 0 & 0 < x \end{cases} \right) dx + c_1}{e^x}$$

- Evaluate the integrals on the rhs

$$y = \frac{\begin{cases} 0 & x \leq 0 \\ -1 + e^x & 0 < x \leq 2 \\ e^2 - 1 & 2 < x \end{cases} + c_1}{e^x}$$

- Simplify

$$y = e^{-x} \left(\begin{cases} 0 & x \leq 0 \\ -1 + e^x & 0 < x \leq 2 \\ e^2 - 1 & 2 < x \end{cases} + c_1 \right)$$

- Use initial condition $y(0) = 0$

$$0 = c_1$$

- Solve for c_1

$$c_1 = 0$$

- Substitute $c_1 = 0$ into general solution and simplify

$$y = e^{-x} \left(\begin{cases} 0 & x \leq 0 \\ -1 + e^x & 0 < x \leq 2 \\ e^2 - 1 & 2 < x \end{cases} \right)$$

- Solution to the IVP

$$y = e^{-x} \left(\begin{cases} 0 & x \leq 0 \\ -1 + e^x & 0 < x \leq 2 \\ e^2 - 1 & 2 < x \end{cases} \right)$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
<- 1st order linear successful`

```


✓ Solution by Maple

Time used: 0.313 (sec). Leaf size: 36

```
dsolve([diff(y(x),x)+y(x)=piecewise(0<=x and x<2,1,x>0,0),y(0) = 0],y(x), singsol=all)
```

$$y(x) = \begin{cases} 0 & x < 0 \\ 1 - e^{-x} & 0 < x < 2 \\ e^{2-x} - e^{-x} & 2 \leq x \end{cases}$$

✓ Solution by Mathematica

Time used: 0.059 (sec). Leaf size: 39

```
DSolve[{y'[x]+y[x]==Piecewise[{{1,0<=x<2},{0,x>2}}],{y[0]==0}],y[x],x,IncludeSingularSolutio
```

$$y(x) \rightarrow \begin{cases} 0 & x \leq 0 \\ 1 - e^{-x} & 0 < x \leq 2 \\ e^{-x}(-1 + e^2) & \text{True} \end{cases}$$

6.23 problem 23

6.23.1 Existence and uniqueness analysis	1545
6.23.2 Solving as linear ode	1546
6.23.3 Solving as first order ode lie symmetry lookup ode	1549
6.23.4 Maple step by step solution	1555

Internal problem ID [11697]

Internal file name [OUTPUT/11706_Wednesday_April_10_2024_04_55_17_PM_81399686/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, Miscellaneous Review. Exercises page 60

Problem number: 23.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**linear**", "**first_order_ode_lie_symmetry_lookup**"

Maple gives the following as the ode type

`[_linear]`

$$(x + 2)y' + y = \begin{cases} 2x & 0 \leq x \leq 2 \\ 4 & 2 < x \end{cases}$$

With initial conditions

$$[y(0) = 4]$$

6.23.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = \frac{1}{x+2}$$

$$q(x) = \frac{2 \left(\begin{array}{l} 0 \quad x < 0 \\ x \quad x \leq 2 \\ 2 \quad 2 < x \end{array} \right)}{x+2}$$

Hence the ode is

$$y' + \frac{y}{x+2} = \frac{2 \left(\begin{array}{l} 0 \quad x < 0 \\ x \quad x \leq 2 \\ 2 \quad 2 < x \end{array} \right)}{x+2}$$

The domain of $p(x) = \frac{1}{x+2}$ is

$$\{x < -2 \vee -2 < x\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = \frac{2 \left(\begin{array}{l} 0 \quad x < 0 \\ x \quad x \leq 2 \\ 2 \quad 2 < x \end{array} \right)}{x+2}$ is

$$\{x < -2 \vee -2 < x\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

6.23.2 Solving as linear ode

Entering Linear first order ODE solver. The integrating factor μ is

$$\begin{aligned} \mu &= e^{\int \frac{1}{x+2} dx} \\ &= x + 2 \end{aligned}$$

The ode becomes

$$\frac{d}{dx}(\mu y) = (\mu) \left(\frac{2 \left(\begin{cases} 0 & x < 0 \\ x & x \leq 2 \\ 2 & 2 < x \end{cases} \right)}{x+2} \right)$$

$$\frac{d}{dx}((x+2)y) = (x+2) \left(\frac{2 \left(\begin{cases} 0 & x < 0 \\ x & x \leq 2 \\ 2 & 2 < x \end{cases} \right)}{x+2} \right)$$

$$d((x+2)y) = \left(2 \left(\begin{cases} 0 & x < 0 \\ x & x \leq 2 \\ 2 & 2 < x \end{cases} \right) \right) dx$$

Integrating gives

$$(x+2)y = \int 2 \left(\begin{cases} 0 & x < 0 \\ x & x \leq 2 \\ 2 & 2 < x \end{cases} \right) dx$$

$$(x+2)y = 2 \left(\begin{cases} 0 & x \leq 0 \\ \frac{x^2}{2} & x \leq 2 \\ 2x-2 & 2 < x \end{cases} \right) + c_1$$

Dividing both sides by the integrating factor $\mu = x + 2$ results in

$$y = \frac{2 \left(\begin{cases} 0 & x \leq 0 \\ \frac{x^2}{2} & x \leq 2 \\ 2x-2 & 2 < x \end{cases} \right)}{x+2} + \frac{c_1}{x+2}$$

which simplifies to

$$y = \frac{\left(\begin{cases} 0 & x \leq 0 \\ x^2 & x \leq 2 \\ 4x - 4 & 2 < x \end{cases} \right) + c_1}{x + 2}$$

Initial conditions are used to solve for c_1 . Substituting $x = 0$ and $y = 4$ in the above solution gives an equation to solve for the constant of integration.

$$4 = \frac{c_1}{2}$$

$$c_1 = 8$$

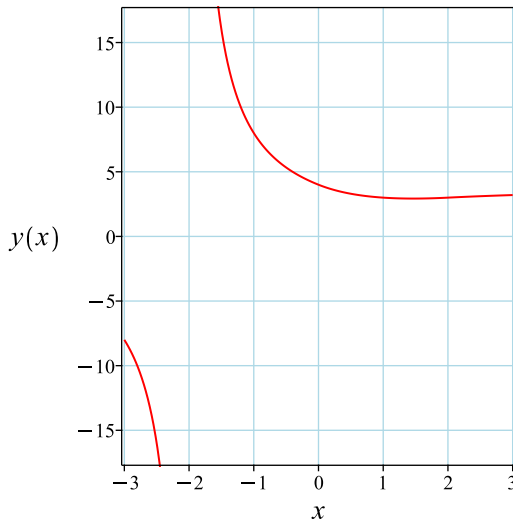
Substituting c_1 found above in the general solution gives

$$y = \begin{cases} \frac{8}{x+2} & x \leq 0 \\ \frac{x^2+8}{x+2} & x \leq 2 \\ \frac{4+4x}{x+2} & 2 < x \\ \frac{8}{x+2} & \text{otherwise} \end{cases}$$

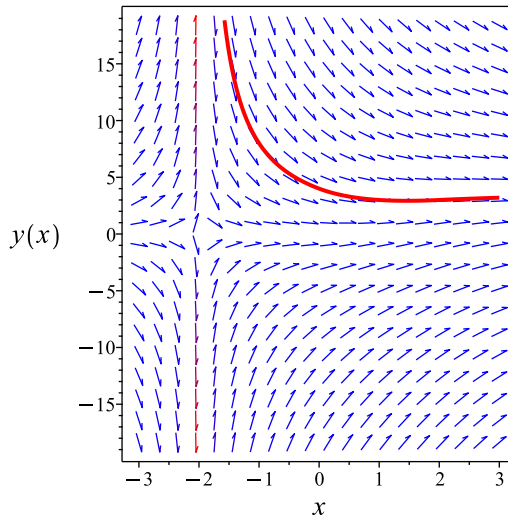
Summary

The solution(s) found are the following

$$y = \begin{cases} \frac{8}{x+2} & x \leq 0 \\ \frac{x^2+8}{x+2} & x \leq 2 \\ \frac{4+4x}{x+2} & 2 < x \\ \frac{8}{x+2} & \text{otherwise} \end{cases} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \begin{cases} \frac{8}{x+2} & x \leq 0 \\ \frac{x^2+8}{x+2} & 0 < x \leq 2 \\ \frac{4+4x}{x+2} & 2 < x \\ \frac{8}{x+2} & \text{otherwise} \end{cases}$$

Verified OK.

6.23.3 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = - \frac{\left(\begin{cases} 2x & 0 \leq x \leq 2 \\ 4 & 2 < x \end{cases} \right)}{x+2}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **linear**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 245: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int(n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned} \xi(x, y) &= 0 \\ \eta(x, y) &= \frac{1}{x+2} \end{aligned} \tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the

canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{1}{x+2}} dy \end{aligned}$$

Which results in

$$S = (x + 2) y$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = - \frac{y - \left(\begin{cases} 2x & 0 \leq x \leq 2 \\ 4 & 2 < x \end{cases} \right)}{x + 2}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= y \\ S_y &= x + 2 \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 2 \left(\begin{cases} 0 & x < 0 \\ x & x \leq 2 \\ 2 & 2 < x \end{cases} \right) \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 2 \left(\begin{cases} 0 & R < 0 \\ R & R \leq 2 \\ 2 & 2 < R \end{cases} \right)$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = \begin{cases} c_1 & R < 0 \\ R^2 + c_1 & R < 2 \\ c_1 - 4 + 4R & 2 \leq R \end{cases} \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$(x+2)y = \begin{cases} c_1 & x < 0 \\ x^2 + c_1 & x < 2 \\ c_1 + 4x - 4 & 2 \leq x \end{cases}$$

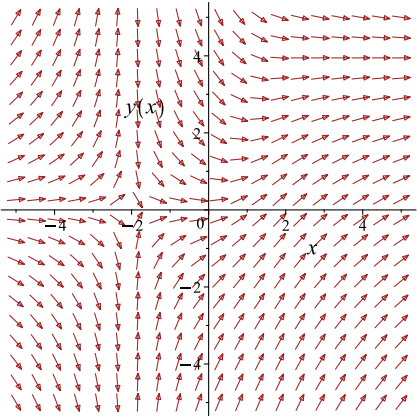
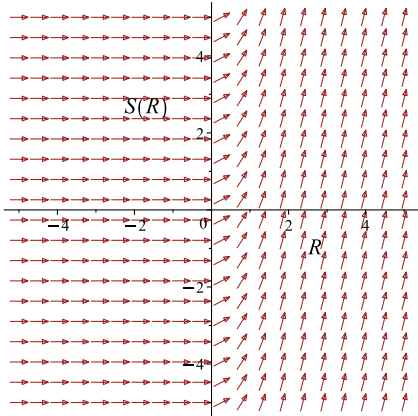
Which simplifies to

$$(x+2)y = \begin{cases} c_1 & x < 0 \\ x^2 + c_1 & x < 2 \\ c_1 + 4x - 4 & 2 \leq x \end{cases}$$

Which gives

$$y = \frac{\begin{cases} c_1 & x < 0 \\ x^2 + c_1 & x < 2 \\ c_1 + 4x - 4 & 2 \leq x \end{cases}}{x+2}$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{y \begin{cases} 2x & 0 \leq x \leq 2 \\ 4 & 2 < x \end{cases}}{x+2}$ 	$R = x$ $S = (x + 2)y$	$\frac{dS}{dR} = 2 \begin{cases} 0 & R < 0 \\ R & R \leq 2 \\ 2 & 2 < R \end{cases}$ 

Initial conditions are used to solve for c_1 . Substituting $x = 0$ and $y = 4$ in the above solution gives an equation to solve for the constant of integration.

$$4 = \frac{c_1}{2}$$

$$c_1 = 8$$

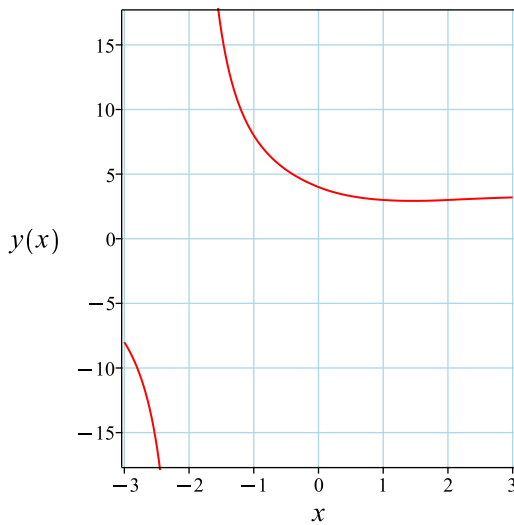
Substituting c_1 found above in the general solution gives

$$y = \begin{cases} \frac{8}{x+2} & x < 0 \\ \frac{x^2+8}{x+2} & 0 < x < 2 \\ \frac{4+4x}{x+2} & 2 \leq x \\ 0 & \text{otherwise} \end{cases}$$

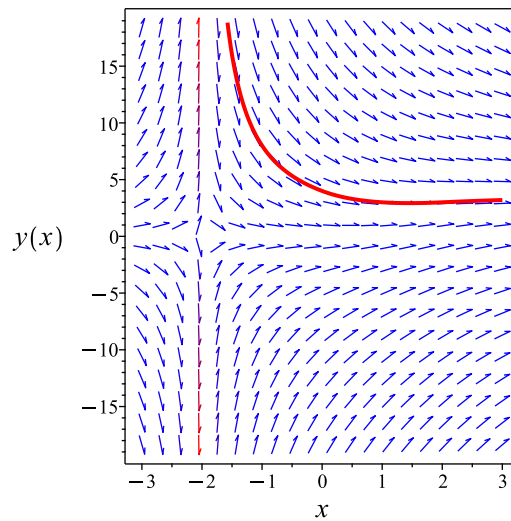
Summary

The solution(s) found are the following

$$y = \begin{cases} \frac{8}{x+2} & x < 0 \\ \frac{x^2+8}{x+2} & 0 < x < 2 \\ \frac{4+4x}{x+2} & 2 \leq x \\ 0 & \text{otherwise} \end{cases} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \begin{cases} \frac{8}{x+2} & x < 0 \\ \frac{x^2+8}{x+2} & 0 < x < 2 \\ \frac{4+4x}{x+2} & 2 \leq x \\ 0 & \text{otherwise} \end{cases}$$

Verified OK.

6.23.4 Maple step by step solution

Let's solve

$$\left[(x+2)y' + y = \begin{cases} 2x & 0 \leq x \leq 2 \\ 4 & 2 < x \end{cases}, y(0) = 4 \right]$$

- Highest derivative means the order of the ODE is 1

y'

- Isolate the derivative

$$y' = -\frac{y}{x+2} + \frac{\begin{cases} 2x & 0 \leq x \leq 2 \\ 4 & 2 < x \end{cases}}{x+2}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE

$$y' + \frac{y}{x+2} = \frac{\begin{cases} 2x & 0 \leq x \leq 2 \\ 4 & 2 < x \end{cases}}{x+2}$$

- The ODE is linear; multiply by an integrating factor $\mu(x)$

$$\mu(x) \left(y' + \frac{y}{x+2} \right) = \frac{\mu(x) \left(\begin{cases} 2x & 0 \leq x \leq 2 \\ 4 & 2 < x \end{cases} \right)}{x+2}$$

- Assume the lhs of the ODE is the total derivative $\frac{d}{dx}(\mu(x)y)$

$$\mu(x) \left(y' + \frac{y}{x+2} \right) = \mu'(x)y + \mu(x)y'$$

- Isolate $\mu'(x)$

$$\mu'(x) = \frac{\mu(x)}{x+2}$$

- Solve to find the integrating factor

$$\mu(x) = x + 2$$

- Integrate both sides with respect to x

$$\int \left(\frac{d}{dx}(\mu(x)y) \right) dx = \int \frac{\mu(x) \left(\begin{cases} 2x & 0 \leq x \leq 2 \\ 4 & 2 < x \end{cases} \right)}{x+2} dx + c_1$$

- Evaluate the integral on the lhs

$$\mu(x) y = \int \frac{\mu(x) \left(\begin{cases} 2x & 0 \leq x \leq 2 \\ 4 & 2 < x \end{cases} \right)}{x+2} dx + c_1$$

- Solve for y

$$y = \frac{\int \frac{\mu(x) \left(\begin{cases} 2x & 0 \leq x \leq 2 \\ 4 & 2 < x \end{cases} \right)}{x+2} dx + c_1}{\mu(x)}$$

- Substitute $\mu(x) = x + 2$

$$y = \frac{\int \left(\begin{cases} 2x & 0 \leq x \leq 2 \\ 4 & 2 < x \end{cases} \right) dx + c_1}{x+2}$$

- Evaluate the integrals on the rhs

$$y = \frac{\begin{cases} 0 & x \leq 0 \\ x^2 & 0 < x \leq 2 \\ 4x - 4 & 2 < x \end{cases} + c_1}{x+2}$$

- Use initial condition $y(0) = 4$

$$4 = \frac{c_1}{2}$$

- Solve for c_1

$$c_1 = 8$$

- Substitute $c_1 = 8$ into general solution and simplify

$$y = \frac{\begin{cases} 0 & x \leq 0 \\ x^2 & 0 < x \leq 2 \\ 4x - 4 & 2 < x \end{cases} + 8}{x+2}$$

- Solution to the IVP

$$y = \frac{\begin{cases} 0 & x \leq 0 \\ x^2 & 0 < x \leq 2 \\ 4x - 4 & 2 < x \end{cases} + 8}{x+2}$$

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
<- 1st order linear successful`
```

✓ Solution by Maple

Time used: 0.063 (sec). Leaf size: 31

```
dsolve([(x+2)*diff(y(x),x)+y(x)=piecewise(0<=x and x<=2,2*x,x>2,4),y(0) = 4],y(x), singsol=a
```

$$y(x) = \frac{\begin{cases} 8 & x < 0 \\ x^2 + 8 & 0 \leq x < 2 \\ 4 + 4x & 2 \leq x \end{cases}}{x + 2}$$

✓ Solution by Mathematica

Time used: 0.248 (sec). Leaf size: 43

```
DSolve[{(x+2)*y'[x]+y[x]==Piecewise[{{2*x,0<=x<=2},{4,x>2}],{y[0]==4}],y[x],x,IncludeSingular
```

$$y(x) \rightarrow \begin{cases} \frac{8}{x+2} & x \leq 0 \\ \frac{4(x+1)}{x+2} & x > 2 \\ \frac{x^2+8}{x+2} & \text{True} \end{cases}$$

6.24 problem 24

6.24.1 Existence and uniqueness analysis	1558
6.24.2 Solving as homogeneousTypeD2 ode	1559
6.24.3 Solving as first order ode lie symmetry lookup ode	1561
6.24.4 Solving as bernoulli ode	1565

Internal problem ID [11698]

Internal file name [OUTPUT/11707_Wednesday_April_10_2024_04_55_18_PM_22551060/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 2, Miscellaneous Review. Exercises page 60

Problem number: 24.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**bernoulli**", "**homogeneousTypeD2**", "**first_order_ode_lie_symmetry_lookup**"

Maple gives the following as the ode type

```
[[_homogeneous, `class A`], _rational, _Bernoulli]
```

$$x^2y' + yx - \frac{y^3}{x} = 0$$

With initial conditions

$$[y(1) = 1]$$

6.24.1 Existence and uniqueness analysis

This is non linear first order ODE. In canonical form it is written as

$$\begin{aligned} y' &= f(x, y) \\ &= \frac{y(-x^2 + y^2)}{x^3} \end{aligned}$$

The x domain of $f(x, y)$ when $y = 1$ is

$$\{x < 0 \vee 0 < x\}$$

And the point $x_0 = 1$ is inside this domain. The y domain of $f(x, y)$ when $x = 1$ is

$$\{-\infty < y < \infty\}$$

And the point $y_0 = 1$ is inside this domain. Now we will look at the continuity of

$$\begin{aligned} \frac{\partial f}{\partial y} &= \frac{\partial}{\partial y} \left(\frac{y(-x^2 + y^2)}{x^3} \right) \\ &= \frac{-x^2 + y^2}{x^3} + \frac{2y^2}{x^3} \end{aligned}$$

The x domain of $\frac{\partial f}{\partial y}$ when $y = 1$ is

$$\{x < 0 \vee 0 < x\}$$

And the point $x_0 = 1$ is inside this domain. The y domain of $\frac{\partial f}{\partial y}$ when $x = 1$ is

$$\{-\infty < y < \infty\}$$

And the point $y_0 = 1$ is inside this domain. Therefore solution exists and is unique.

6.24.2 Solving as homogeneous TypeD2 ode

Using the change of variables $y = u(x)x$ on the above ode results in new ode in $u(x)$

$$x^2(u'(x)x + u(x)) + u(x)x^2 - u(x)^3x^2 = 0$$

In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= \frac{u(u^2 - 2)}{x} \end{aligned}$$

Where $f(x) = \frac{1}{x}$ and $g(u) = u(u^2 - 2)$. Integrating both sides gives

$$\begin{aligned} \frac{1}{u(u^2 - 2)} du &= \frac{1}{x} dx \\ \int \frac{1}{u(u^2 - 2)} du &= \int \frac{1}{x} dx \\ -\frac{\ln(u)}{2} + \frac{\ln(u^2 - 2)}{4} &= \ln(x) + c_2 \end{aligned}$$

Raising both side to exponential gives

$$e^{-\frac{\ln(u)}{2} + \frac{\ln(u^2-2)}{4}} = e^{\ln(x)+c_2}$$

Which simplifies to

$$\frac{(u^2 - 2)^{\frac{1}{4}}}{\sqrt{u}} = c_3 x$$

The solution is

$$\frac{(u(x)^2 - 2)^{\frac{1}{4}}}{\sqrt{u(x)}} = c_3 x$$

Replacing $u(x)$ in the above solution by $\frac{y}{x}$ results in the solution for y in implicit form

$$\frac{\left(\frac{y^2}{x^2} - 2\right)^{\frac{1}{4}}}{\sqrt{\frac{y}{x}}} = c_3 x$$
$$\frac{\left(\frac{y^2-2x^2}{x^2}\right)^{\frac{1}{4}}}{\sqrt{\frac{y}{x}}} = c_3 x$$

Substituting initial conditions and solving for c_3 gives $c_3 = (-1)^{\frac{1}{4}}$. Hence the solution be-

Summary

The solution(s) found are the following

comes

$$\frac{\left(\frac{y^2-2x^2}{x^2}\right)^{\frac{1}{4}}}{\sqrt{\frac{y}{x}}} = (-1)^{\frac{1}{4}} x \quad (1)$$

Verification of solutions

$$\frac{\left(\frac{y^2-2x^2}{x^2}\right)^{\frac{1}{4}}}{\sqrt{\frac{y}{x}}} = (-1)^{\frac{1}{4}} x$$

Verified OK.

6.24.3 Solving as first order ode lie symmetry lookup ode

Writing the ode as

$$y' = \frac{y(-x^2 + y^2)}{x^3}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is known. It is of type **Bernoulli**. Therefore we do not need to solve the PDE (A), and can just use the lookup table shown below to find ξ, η

Table 248: Lie symmetry infinitesimal lookup table for known first order ODE's

ODE class	Form	ξ	η
linear ode	$y' = f(x)y(x) + g(x)$	0	$e^{\int f dx}$
separable ode	$y' = f(x)g(y)$	$\frac{1}{f}$	0
quadrature ode	$y' = f(x)$	0	1
quadrature ode	$y' = g(y)$	1	0
homogeneous ODEs of Class A	$y' = f\left(\frac{y}{x}\right)$	x	y
homogeneous ODEs of Class C	$y' = (a + bx + cy)^{\frac{n}{m}}$	1	$-\frac{b}{c}$
homogeneous class D	$y' = \frac{y}{x} + g(x)F\left(\frac{y}{x}\right)$	x^2	xy
First order special form ID 1	$y' = g(x)e^{h(x)+by} + f(x)$	$\frac{e^{-\int bf(x)dx-h(x)}}{g(x)}$	$\frac{f(x)e^{-\int bf(x)dx-h(x)}}{g(x)}$
polynomial type ode	$y' = \frac{a_1x+b_1y+c_1}{a_2x+b_2y+c_2}$	$\frac{a_1b_2x-a_2b_1x-b_1c_2+b_2c_1}{a_1b_2-a_2b_1}$	$\frac{a_1b_2y-a_2b_1y-a_1c_2-a_2c_1}{a_1b_2-a_2b_1}$
Bernoulli ode	$y' = f(x)y + g(x)y^n$	0	$e^{-\int (n-1)f(x)dx}y^n$
Reduced Riccati	$y' = f_1(x)y + f_2(x)y^2$	0	$e^{-\int f_1 dx}$

The above table shows that

$$\begin{aligned}\xi(x, y) &= 0 \\ \eta(x, y) &= y^3 x^2\end{aligned}\tag{A1}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS\tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned}S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{y^3 x^2} dy\end{aligned}$$

Which results in

$$S = -\frac{1}{2x^2 y^2}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y}\tag{2}$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = \frac{y(-x^2 + y^2)}{x^3}$$

Evaluating all the partial derivatives gives

$$\begin{aligned}R_x &= 1 \\R_y &= 0 \\S_x &= \frac{1}{x^3 y^2} \\S_y &= \frac{1}{y^3 x^2}\end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = \frac{1}{x^5} \tag{2A}$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = \frac{1}{R^5}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = -\frac{1}{4R^4} + c_1 \tag{4}$$

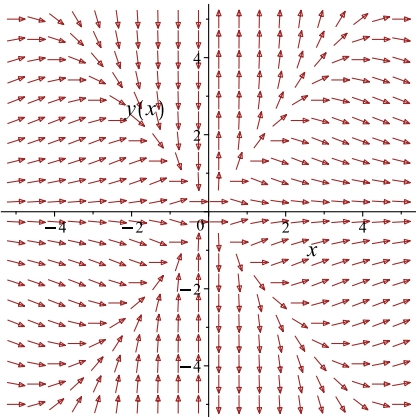
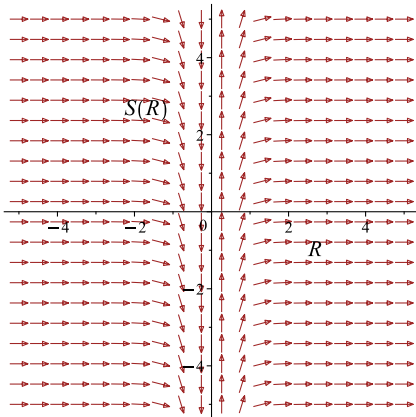
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$-\frac{1}{2x^2 y^2} = -\frac{1}{4x^4} + c_1$$

Which simplifies to

$$-\frac{1}{2x^2 y^2} = -\frac{1}{4x^4} + c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = \frac{y(-x^2+y^2)}{x^3}$ 	$R = x$ $S = -\frac{1}{2x^2y^2}$	$\frac{dS}{dR} = \frac{1}{R^5}$ 

Initial conditions are used to solve for c_1 . Substituting $x = 1$ and $y = 1$ in the above solution gives an equation to solve for the constant of integration.

$$-\frac{1}{2} = c_1 - \frac{1}{4}$$

$$c_1 = -\frac{1}{4}$$

Substituting c_1 found above in the general solution gives

$$-\frac{1}{2x^2y^2} = -\frac{x^4 + 1}{4x^4}$$

The above simplifies to

$$x^4y^2 - 2x^2 + y^2 = 0$$

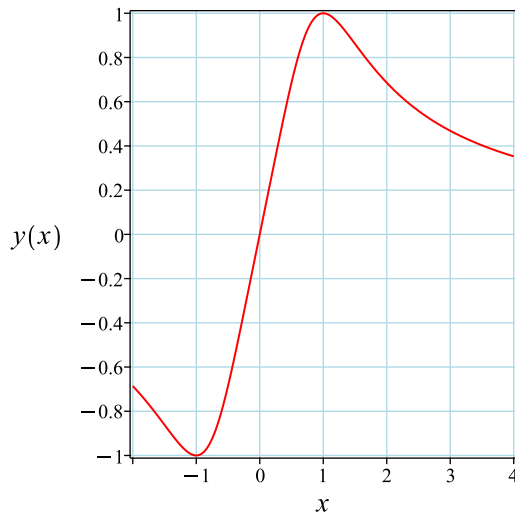
Solving for y from the above gives

$$y = \frac{2x}{\sqrt{2x^4 + 2}}$$

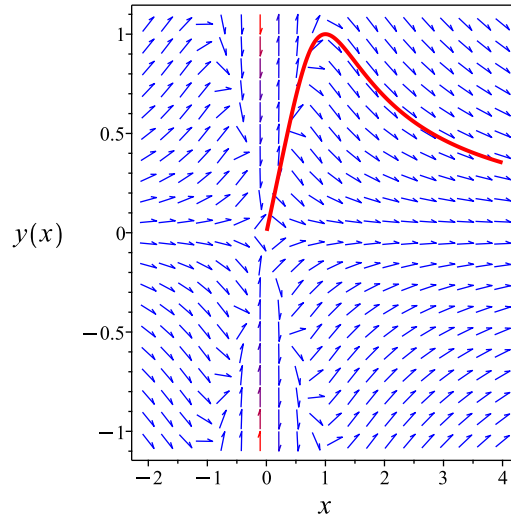
Summary

The solution(s) found are the following

$$y = \frac{2x}{\sqrt{2x^4 + 2}} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \frac{2x}{\sqrt{2x^4 + 2}}$$

Verified OK.

6.24.4 Solving as bernoulli ode

In canonical form, the ODE is

$$\begin{aligned} y' &= F(x, y) \\ &= \frac{y(-x^2 + y^2)}{x^3} \end{aligned}$$

This is a Bernoulli ODE.

$$y' = -\frac{1}{x}y + \frac{1}{x^3}y^3 \quad (1)$$

The standard Bernoulli ODE has the form

$$y' = f_0(x)y + f_1(x)y^n \quad (2)$$

The first step is to divide the above equation by y^n which gives

$$\frac{y'}{y^n} = f_0(x)y^{1-n} + f_1(x) \quad (3)$$

The next step is use the substitution $w = y^{1-n}$ in equation (3) which generates a new ODE in $w(x)$ which will be linear and can be easily solved using an integrating factor. Backsubstitution then gives the solution $y(x)$ which is what we want.

This method is now applied to the ODE at hand. Comparing the ODE (1) With (2) Shows that

$$\begin{aligned} f_0(x) &= -\frac{1}{x} \\ f_1(x) &= \frac{1}{x^3} \\ n &= 3 \end{aligned}$$

Dividing both sides of ODE (1) by $y^n = y^3$ gives

$$y' \frac{1}{y^3} = -\frac{1}{x y^2} + \frac{1}{x^3} \quad (4)$$

Let

$$\begin{aligned} w &= y^{1-n} \\ &= \frac{1}{y^2} \end{aligned} \quad (5)$$

Taking derivative of equation (5) w.r.t x gives

$$w' = -\frac{2}{y^3} y' \quad (6)$$

Substituting equations (5) and (6) into equation (4) gives

$$\begin{aligned} -\frac{w'(x)}{2} &= -\frac{w(x)}{x} + \frac{1}{x^3} \\ w' &= \frac{2w}{x} - \frac{2}{x^3} \end{aligned} \quad (7)$$

The above now is a linear ODE in $w(x)$ which is now solved.

Entering Linear first order ODE solver. In canonical form a linear first order is

$$w'(x) + p(x)w(x) = q(x)$$

Where here

$$p(x) = -\frac{2}{x}$$
$$q(x) = -\frac{2}{x^3}$$

Hence the ode is

$$w'(x) - \frac{2w(x)}{x} = -\frac{2}{x^3}$$

The integrating factor μ is

$$\mu = e^{\int -\frac{2}{x} dx}$$
$$= \frac{1}{x^2}$$

The ode becomes

$$\frac{d}{dx}(\mu w) = (\mu) \left(-\frac{2}{x^3}\right)$$
$$\frac{d}{dx}\left(\frac{w}{x^2}\right) = \left(\frac{1}{x^2}\right) \left(-\frac{2}{x^3}\right)$$
$$d\left(\frac{w}{x^2}\right) = \left(-\frac{2}{x^5}\right) dx$$

Integrating gives

$$\frac{w}{x^2} = \int -\frac{2}{x^5} dx$$
$$\frac{w}{x^2} = \frac{1}{2x^4} + c_1$$

Dividing both sides by the integrating factor $\mu = \frac{1}{x^2}$ results in

$$w(x) = \frac{1}{2x^2} + c_1 x^2$$

Replacing w in the above by $\frac{1}{y^2}$ using equation (5) gives the final solution.

$$\frac{1}{y^2} = \frac{1}{2x^2} + c_1 x^2$$

Initial conditions are used to solve for c_1 . Substituting $x = 1$ and $y = 1$ in the above solution gives an equation to solve for the constant of integration.

$$1 = \frac{1}{2} + c_1$$

$$c_1 = \frac{1}{2}$$

Substituting c_1 found above in the general solution gives

$$\frac{1}{y^2} = \frac{x^4 + 1}{2x^2}$$

The above simplifies to

$$-x^4 y^2 + 2x^2 - y^2 = 0$$

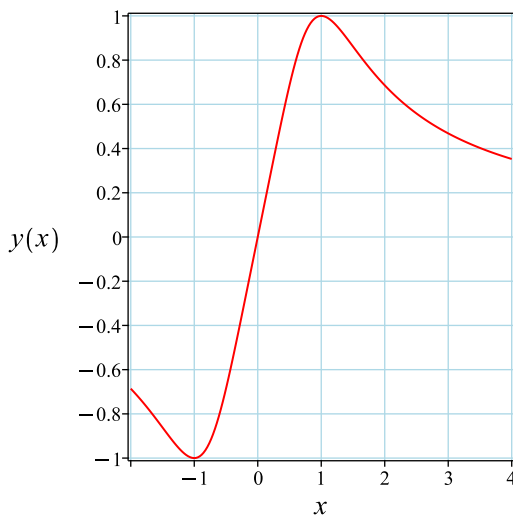
Solving for y from the above gives

$$y = \frac{2x}{\sqrt{2x^4 + 2}}$$

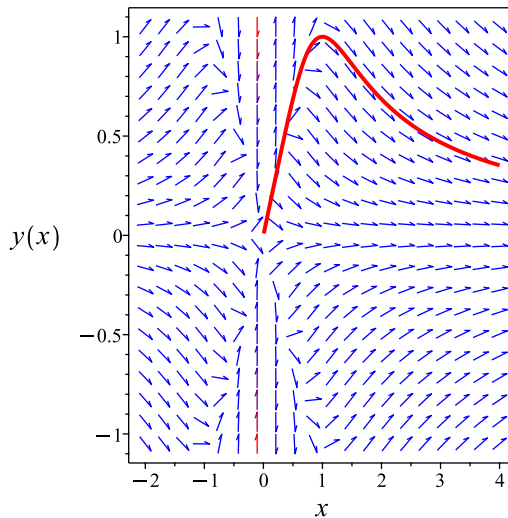
Summary

The solution(s) found are the following

$$y = \frac{2x}{\sqrt{2x^4 + 2}} \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \frac{2x}{\sqrt{2x^4 + 2}}$$

Verified OK.

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
trying Bernoulli  
<- Bernoulli successful`
```

✓ Solution by Maple

Time used: 0.063 (sec). Leaf size: 16

```
dsolve([x^2*diff(y(x),x)+x*y(x)=y(x)^3/x,y(1) = 1],y(x), singsol=all)
```

$$y(x) = \frac{2x}{\sqrt{2x^4 + 2}}$$

✓ Solution by Mathematica

Time used: 0.355 (sec). Leaf size: 21

```
DSolve[{x^2*y'[x]+x*y[x]==y[x]^3/x,{y[1]==1}],y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{\sqrt{2}x}{\sqrt{x^4 + 1}}$$

7 Chapter 2, Section 2.4. Special integrating factors and transformations. Exercises page 67

7.1	problem 1	1571
7.2	problem 2	1577
7.3	problem 3	1583
7.4	problem 4	1589
7.5	problem 5	1601
7.6	problem 6	1614
7.7	problem 7	1622
7.8	problem 8	1639
7.9	problem 9	1647
7.10	problem 10	1658
7.11	problem 11	1669
7.12	problem 12	1687
7.13	problem 13	1699
7.14	problem 14	1708

7.1 problem 1

7.1.1 Solving as exact ode 1571

Internal problem ID [11699]

Internal file name [OUTPUT/11708_Wednesday_April_10_2024_04_55_32_PM_43910952/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, Section 2.4. Special integrating factors and transformations. Exercises page 67

Problem number: 1.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"exactWithIntegrationFactor"**

Maple gives the following as the ode type

```
[_rational, [_Abel, `2nd type`, `class B`]]
```

$$5yx + 4y^2 + (2yx + x^2) y' = -1$$

7.1.1 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (1A)$$

Therefore

$$\begin{aligned} (x^2 + 2xy) dy &= (-5xy - 4y^2 - 1) dx \\ (5xy + 4y^2 + 1) dx + (x^2 + 2xy) dy &= 0 \end{aligned} \quad (2A)$$

Comparing (1A) and (2A) shows that

$$\begin{aligned} M(x, y) &= 5xy + 4y^2 + 1 \\ N(x, y) &= x^2 + 2xy \end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned} \frac{\partial M}{\partial y} &= \frac{\partial}{\partial y} (5xy + 4y^2 + 1) \\ &= 5x + 8y \end{aligned}$$

And

$$\begin{aligned} \frac{\partial N}{\partial x} &= \frac{\partial}{\partial x} (x^2 + 2xy) \\ &= 2y + 2x \end{aligned}$$

Since $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$\begin{aligned} A &= \frac{1}{N} \left(\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} \right) \\ &= \frac{1}{x(x+2y)} ((5x+8y) - (2y+2x)) \\ &= \frac{3}{x} \end{aligned}$$

Since A does not depend on y , then it can be used to find an integrating factor. The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int A dx} \\ &= e^{\int \frac{3}{x} dx}\end{aligned}$$

The result of integrating gives

$$\begin{aligned}\mu &= e^{3\ln(x)} \\ &= x^3\end{aligned}$$

M and N are multiplied by this integrating factor, giving new M and new N which are called \overline{M} and \overline{N} for now so not to confuse them with the original M and N .

$$\begin{aligned}\overline{M} &= \mu M \\ &= x^3(5xy + 4y^2 + 1) \\ &= (5xy + 4y^2 + 1)x^3\end{aligned}$$

And

$$\begin{aligned}\overline{N} &= \mu N \\ &= x^3(x^2 + 2xy) \\ &= x^4(x + 2y)\end{aligned}$$

Now a modified ODE is obtained from the original ODE, which is exact and can be solved. The modified ODE is

$$\begin{aligned}\overline{M} + \overline{N} \frac{dy}{dx} &= 0 \\ ((5xy + 4y^2 + 1)x^3) + (x^4(x + 2y)) \frac{dy}{dx} &= 0\end{aligned}$$

The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = \overline{M} \tag{1}$$

$$\frac{\partial \phi}{\partial y} = \overline{N} \tag{2}$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int \overline{M} dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int (5xy + 4y^2 + 1)x^3 dx \\ \phi &= x^5y + x^4y^2 + \frac{1}{4}x^4 + f(y)\end{aligned} \tag{3}$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\begin{aligned}\frac{\partial\phi}{\partial y} &= x^5 + 2x^4y + f'(y) \\ &= x^4(x + 2y) + f'(y)\end{aligned}\tag{4}$$

But equation (2) says that $\frac{\partial\phi}{\partial y} = x^4(x + 2y)$. Therefore equation (4) becomes

$$x^4(x + 2y) = x^4(x + 2y) + f'(y)\tag{5}$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 0$$

Therefore

$$f(y) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(y)$ into equation (3) gives ϕ

$$\phi = x^5y + x^4y^2 + \frac{1}{4}x^4 + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = x^5y + x^4y^2 + \frac{1}{4}x^4$$

Summary

The solution(s) found are the following

$$yx^5 + y^2x^4 + \frac{x^4}{4} = c_1\tag{1}$$

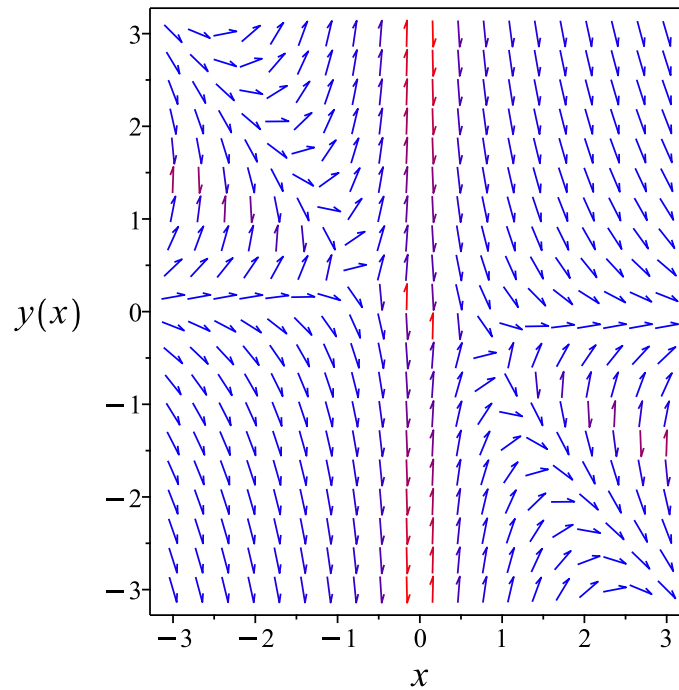


Figure 310: Slope field plot

Verification of solutions

$$yx^5 + y^2x^4 + \frac{x^4}{4} = c_1$$

Verified OK.

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
trying separable
trying inverse linear
trying homogeneous types:
trying Chini
differential order: 1; looking for linear symmetries
trying exact
<- exact successful`

```


✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 59

```
dsolve((5*x*y(x)+4*y(x)^2+1)+(x^2+2*x*y(x))*diff(y(x),x)=0,y(x), singsol=all)
```

$$y(x) = \frac{-x^3 - \sqrt{x^6 - x^4 - 4c_1}}{2x^2}$$
$$y(x) = \frac{-x^3 + \sqrt{x^6 - x^4 - 4c_1}}{2x^2}$$

✓ Solution by Mathematica

Time used: 0.558 (sec). Leaf size: 84

```
DSolve[(5*x*y[x]+4*y[x]^2+1)+(x^2+2*x*y[x])*y'[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow -\frac{x^5 + \sqrt{x^3}\sqrt{x^7 - x^5 + 4c_1}x}{2x^4}$$
$$y(x) \rightarrow -\frac{x}{2} + \frac{\sqrt{x^3}\sqrt{x^7 - x^5 + 4c_1}x}{2x^4}$$

7.2 problem 2

7.2.1 Solving as exact ode 1577

Internal problem ID [11700]

Internal file name [OUTPUT/11709_Thursday_April_11_2024_08_48_33_PM_19754612/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, Section 2.4. Special integrating factors and transformations. Exercises page 67

Problem number: 2.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**exactWithIntegrationFactor**"

Maple gives the following as the ode type

```
[[_1st_order , `_with_symmetry_[F(x),G(x)]`]]
```

$$\tan(y) + (x - x^2 \tan(y)) y' = -2x$$

7.2.1 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \tag{1A}$$

Therefore

$$\begin{aligned} (x - x^2 \tan(y)) dy &= (-2x - \tan(y)) dx \\ (2x + \tan(y)) dx + (x - x^2 \tan(y)) dy &= 0 \end{aligned} \tag{2A}$$

Comparing (1A) and (2A) shows that

$$\begin{aligned} M(x, y) &= 2x + \tan(y) \\ N(x, y) &= x - x^2 \tan(y) \end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned} \frac{\partial M}{\partial y} &= \frac{\partial}{\partial y} (2x + \tan(y)) \\ &= \sec(y)^2 \end{aligned}$$

And

$$\begin{aligned} \frac{\partial N}{\partial x} &= \frac{\partial}{\partial x} (x - x^2 \tan(y)) \\ &= 1 - 2 \tan(y) x \end{aligned}$$

Since $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$\begin{aligned} A &= \frac{1}{N} \left(\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} \right) \\ &= -\frac{1}{x(\tan(y)x - 1)} \left((1 + \tan(y)^2) - (1 - 2 \tan(y)x) \right) \\ &= -\frac{(2x + \tan(y)) \tan(y)}{x(\tan(y)x - 1)} \end{aligned}$$

Since A depends on y , it can not be used to obtain an integrating factor. We will now try a second method to find an integrating factor. Let

$$\begin{aligned} B &= \frac{1}{M} \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) \\ &= \frac{1}{2x + \tan(y)} \left((1 - 2 \tan(y)x) - (1 + \tan(y)^2) \right) \\ &= -\tan(y) \end{aligned}$$

Since B does not depend on x , it can be used to obtain an integrating factor. Let the integrating factor be μ . Then

$$\begin{aligned} \mu &= e^{\int B \, dy} \\ &= e^{\int -\tan(y) \, dy} \end{aligned}$$

The result of integrating gives

$$\begin{aligned} \mu &= e^{\ln(\cos(y))} \\ &= \cos(y) \end{aligned}$$

M and N are now multiplied by this integrating factor, giving new M and new N which are called \bar{M} and \bar{N} so not to confuse them with the original M and N .

$$\begin{aligned} \bar{M} &= \mu M \\ &= \cos(y) (2x + \tan(y)) \\ &= 2x \cos(y) + \sin(y) \end{aligned}$$

And

$$\begin{aligned} \bar{N} &= \mu N \\ &= \cos(y) (x - x^2 \tan(y)) \\ &= -x(\sin(y)x - \cos(y)) \end{aligned}$$

So now a modified ODE is obtained from the original ODE which will be exact and can be solved using the standard method. The modified ODE is

$$\begin{aligned} \overline{M} + \overline{N} \frac{dy}{dx} &= 0 \\ (2x \cos(y) + \sin(y)) + (-x(\sin(y)x - \cos(y))) \frac{dy}{dx} &= 0 \end{aligned}$$

The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = \overline{M} \quad (1)$$

$$\frac{\partial \phi}{\partial y} = \overline{N} \quad (2)$$

Integrating (1) w.r.t. x gives

$$\begin{aligned} \int \frac{\partial \phi}{\partial x} dx &= \int \overline{M} dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int 2x \cos(y) + \sin(y) dx \\ \phi &= (x \cos(y) + \sin(y))x + f(y) \end{aligned} \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = (-\sin(y)x + \cos(y))x + f'(y) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = -x(\sin(y)x - \cos(y))$. Therefore equation (4) becomes

$$-x(\sin(y)x - \cos(y)) = (-\sin(y)x + \cos(y))x + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 0$$

Therefore

$$f(y) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(y)$ into equation (3) gives ϕ

$$\phi = (x \cos(y) + \sin(y))x + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = (x \cos(y) + \sin(y)) x$$

Summary

The solution(s) found are the following

$$(\cos(y) x + \sin(y)) x = c_1 \tag{1}$$

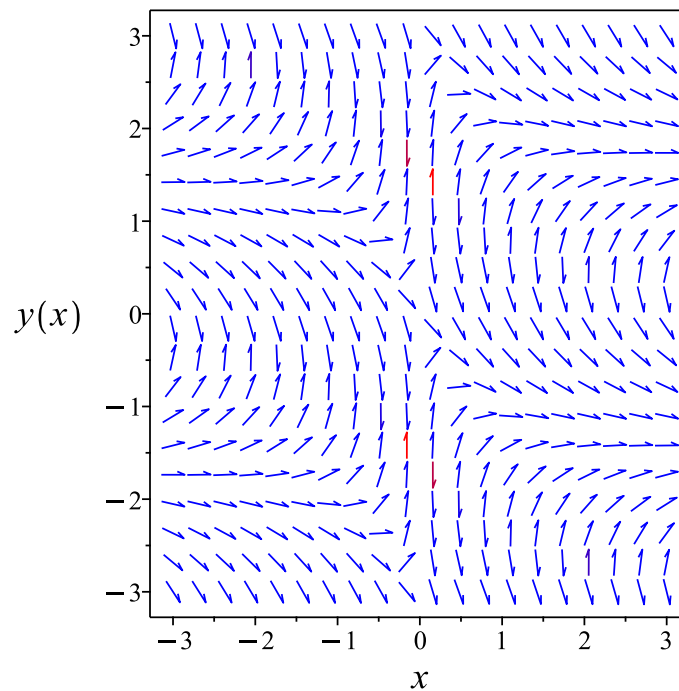


Figure 311: Slope field plot

Verification of solutions

$$(\cos(y) x + \sin(y)) x = c_1$$

Verified OK.

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
trying Bernoulli  
trying separable  
trying inverse linear  
trying homogeneous types:  
trying Chini  
differential order: 1; looking for linear symmetries  
trying exact  
<- exact successful`
```

✓ Solution by Maple

Time used: 0.047 (sec). Leaf size: 134

```
dsolve((2*x+tan(y(x)))+(x-x^2*tan(y(x)))*diff(y(x),x)=0,y(x), singsol=all)
```

$$y(x) = \arctan \left(\frac{-\sqrt{x^4 - c_1^2 + x^2} x - c_1}{(x^2 + 1) x}, \frac{-c_1 x + \sqrt{x^4 - c_1^2 + x^2}}{(x^2 + 1) x} \right)$$
$$y(x) = \arctan \left(\frac{\sqrt{x^4 - c_1^2 + x^2} x - c_1}{(x^2 + 1) x}, \frac{-c_1 x - \sqrt{x^4 - c_1^2 + x^2}}{(x^2 + 1) x} \right)$$

✓ Solution by Mathematica

Time used: 38.283 (sec). Leaf size: 177

```
DSolve[(2*x+Tan[y[x]])+(x-x^2*Tan[y[x]])*y'[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow -\arccos \left(-\frac{c_1 x^2 + \sqrt{x^6 + x^4 - c_1^2 x^2}}{x^4 + x^2} \right)$$
$$y(x) \rightarrow \arccos \left(-\frac{c_1 x^2 + \sqrt{x^6 + x^4 - c_1^2 x^2}}{x^4 + x^2} \right)$$
$$y(x) \rightarrow -\arccos \left(\frac{\sqrt{x^6 + x^4 - c_1^2 x^2} - c_1 x^2}{x^4 + x^2} \right)$$
$$y(x) \rightarrow \arccos \left(\frac{\sqrt{x^6 + x^4 - c_1^2 x^2} - c_1 x^2}{x^4 + x^2} \right)$$

7.3 problem 3

7.3.1 Solving as exact ode 1583

Internal problem ID [11701]

Internal file name [OUTPUT/11710_Thursday_April_11_2024_08_48_36_PM_81880701/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, Section 2.4. Special integrating factors and transformations. Exercises page 67

Problem number: 3.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"exactWithIntegrationFactor"**

Maple gives the following as the ode type

```
[_rational, [_Abel, `2nd type`, `class B`]]
```

$$(1 + x)y^2 + y + (2yx + 1)y' = 0$$

7.3.1 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \tag{A}$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \tag{B}$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \tag{1A}$$

Therefore

$$\begin{aligned} (2xy + 1) dy &= (-(1 + x)y^2 - y) dx \\ ((1 + x)y^2 + y) dx + (2xy + 1) dy &= 0 \end{aligned} \tag{2A}$$

Comparing (1A) and (2A) shows that

$$\begin{aligned} M(x, y) &= (1 + x)y^2 + y \\ N(x, y) &= 2xy + 1 \end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned} \frac{\partial M}{\partial y} &= \frac{\partial}{\partial y} ((1 + x)y^2 + y) \\ &= 1 + (2 + 2x)y \end{aligned}$$

And

$$\begin{aligned} \frac{\partial N}{\partial x} &= \frac{\partial}{\partial x} (2xy + 1) \\ &= 2y \end{aligned}$$

Since $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$\begin{aligned} A &= \frac{1}{N} \left(\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} \right) \\ &= \frac{1}{2xy + 1} ((2y(1 + x) + 1) - (2y)) \\ &= 1 \end{aligned}$$

Since A does not depend on y , then it can be used to find an integrating factor. The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int A dx} \\ &= e^{\int 1 dx}\end{aligned}$$

The result of integrating gives

$$\begin{aligned}\mu &= e^x \\ &= e^x\end{aligned}$$

M and N are multiplied by this integrating factor, giving new M and new N which are called \bar{M} and \bar{N} for now so not to confuse them with the original M and N .

$$\begin{aligned}\bar{M} &= \mu M \\ &= e^x((1+x)y^2 + y) \\ &= y(xy + y + 1)e^x\end{aligned}$$

And

$$\begin{aligned}\bar{N} &= \mu N \\ &= e^x(2xy + 1) \\ &= (2xy + 1)e^x\end{aligned}$$

Now a modified ODE is obtained from the original ODE, which is exact and can be solved. The modified ODE is

$$\begin{aligned}\bar{M} + \bar{N} \frac{dy}{dx} &= 0 \\ (y(xy + y + 1)e^x) + ((2xy + 1)e^x) \frac{dy}{dx} &= 0\end{aligned}$$

The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = \bar{M} \tag{1}$$

$$\frac{\partial \phi}{\partial y} = \bar{N} \tag{2}$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int \bar{M} dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int y(xy + y + 1)e^x dx \\ \phi &= (xy + 1)ye^x + f(y)\end{aligned} \tag{3}$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\begin{aligned}\frac{\partial\phi}{\partial y} &= x e^x y + (xy + 1) e^x + f'(y) \\ &= (2xy + 1) e^x + f'(y)\end{aligned}\tag{4}$$

But equation (2) says that $\frac{\partial\phi}{\partial y} = (2xy + 1) e^x$. Therefore equation (4) becomes

$$(2xy + 1) e^x = (2xy + 1) e^x + f'(y)\tag{5}$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 0$$

Therefore

$$f(y) = c_1$$

Where c_1 is constant of integration. Substituting this result for $f(y)$ into equation (3) gives ϕ

$$\phi = (xy + 1) y e^x + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = (xy + 1) y e^x$$

Summary

The solution(s) found are the following

$$(yx + 1) y e^x = c_1\tag{1}$$

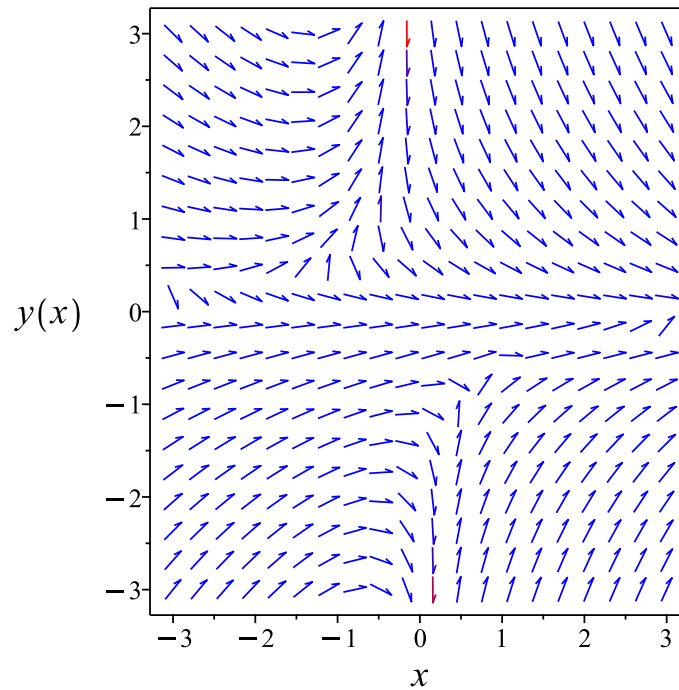


Figure 312: Slope field plot

Verification of solutions

$$(yx + 1) y e^x = c_1$$

Verified OK.

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
trying separable
trying inverse linear
trying homogeneous types:
trying Chini
differential order: 1; looking for linear symmetries
trying exact
<- exact successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 56

```
dsolve((y(x)^2*(x+1)+y(x))+(2*x*y(x)+1)*diff(y(x),x)=0,y(x), singsol=all)
```

$$y(x) = \frac{-1 + \sqrt{e^x(-4c_1x + e^x)} e^{-x}}{2x}$$
$$y(x) = \frac{-\sqrt{e^x(-4c_1x + e^x)} e^{-x} - 1}{2x}$$

✓ Solution by Mathematica

Time used: 2.638 (sec). Leaf size: 69

```
DSolve[(y[x]^2*(x+1)+y[x])+(2*x*y[x]+1)*y'[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow -\frac{1 + \frac{\sqrt{e^x+4c_1x}}{\sqrt{e^x}}}{2x}$$
$$y(x) \rightarrow \frac{-1 + \frac{\sqrt{e^x+4c_1x}}{\sqrt{e^x}}}{2x}$$

7.4 problem 4

7.4.1 Solving as first order ode lie symmetry calculated ode 1589

7.4.2 Solving as exact ode 1595

Internal problem ID [11702]

Internal file name [OUTPUT/11711_Thursday_April_11_2024_08_48_37_PM_11428769/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 2, Section 2.4. Special integrating factors and transformations. Exercises page 67

Problem number: 4.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"exactWithIntegrationFactor", "first_order_ode_lie_symmetry_calculated"**

Maple gives the following as the ode type

[_rational]

$$2y^2x + y + (2y^3 - x)y' = 0$$

7.4.1 Solving as first order ode lie symmetry calculated ode

Writing the ode as

$$y' = -\frac{y(2xy + 1)}{2y^3 - x}$$
$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2\xi_y - \omega_x\xi - \omega_y\eta = 0 \quad (\text{A})$$

The type of this ode is not in the lookup table. To determine ξ, η then (A) is solved using ansatz. Making bivariate polynomials of degree 3 to use as anstaz gives

$$\xi = x^3a_7 + x^2ya_8 + xy^2a_9 + y^3a_{10} + x^2a_4 + xya_5 + y^2a_6 + xa_2 + ya_3 + a_1 \quad (1\text{E})$$

$$\eta = x^3b_7 + x^2yb_8 + xy^2b_9 + y^3b_{10} + x^2b_4 + xyb_5 + y^2b_6 + xb_2 + yb_3 + b_1 \quad (2\text{E})$$

Where the unknown coefficients are

$$\{a_1, a_2, a_3, a_4, a_5, a_6, a_7, a_8, a_9, a_{10}, b_1, b_2, b_3, b_4, b_5, b_6, b_7, b_8, b_9, b_{10}\}$$

Substituting equations (1E,2E) and ω into (A) gives

$$\begin{aligned} & 3x^2b_7 + 2xyb_8 + y^2b_9 + 2xb_4 + yb_5 + b_2 \tag{5E} \\ & \frac{y(2xy + 1)(-3x^2a_7 + x^2b_8 - 2xya_8 + 2xyb_9 - y^2a_9 + 3y^2b_{10} - 2xa_4 + xb_5 - ya_5 + 2yb_6 - a_2 + b_3)}{2y^3 - x} \\ & - \frac{y^2(2xy + 1)^2(x^2a_8 + 2xya_9 + 3y^2a_{10} + xa_5 + 2ya_6 + a_3)}{(2y^3 - x)^2} \\ & - \left(-\frac{2y^2}{2y^3 - x} - \frac{y(2xy + 1)}{(2y^3 - x)^2} \right) (x^3a_7 + x^2ya_8 + xy^2a_9 + y^3a_{10} + x^2a_4 + xya_5 \\ & + y^2a_6 + xa_2 + ya_3 + a_1) - \left(-\frac{2xy + 1}{2y^3 - x} - \frac{2yx}{2y^3 - x} + \frac{6y^3(2xy + 1)}{(2y^3 - x)^2} \right) (x^3b_7 \\ & + x^2yb_8 + xy^2b_9 + y^3b_{10} + x^2b_4 + xyb_5 + y^2b_6 + xb_2 + yb_3 + b_1) = 0 \end{aligned}$$

Putting the above in normal form gives

$$\begin{aligned} & \frac{-2x^4b_7 - 4y^8b_9 - 2y^6a_9 + 10y^6b_{10} + 2y^4a_{10} - 4y^8a_{10} - 12x^2y^6b_7 + 16x^3y^3b_7 - 8xy^7b_8 + 14x^2y^4b_8 - 2x^3y^5b_7 + 8xy^7b_8 - 14x^2y^4b_8 - 2x^3y^5b_7}{=} \\ & = 0 \end{aligned}$$

Setting the numerator to zero gives

$$\begin{aligned} & 2x^4b_7 + 4y^8b_9 + 2y^6a_9 - 10y^6b_{10} - 2y^4a_{10} + 4y^8a_{10} + 12x^2y^6b_7 \\ & - 16x^3y^3b_7 + 8xy^7b_8 - 14x^2y^4b_8 + 2x^3yb_8 - 12xy^5b_9 + 2x^2y^2b_9 \\ & + 16x^3y^5a_7 - 8x^3y^5b_8 + 12x^2y^6a_8 - 12x^2y^6b_9 + 8xy^7a_9 \\ & - 16xy^7b_{10} - 6x^4y^2a_7 - 2x^4y^2b_8 - 8x^3y^3a_8 + 6x^2y^4a_7 - 10x^2y^4a_9 \\ & + 2x^2y^4b_{10} + 4xy^5a_8 - 4x^3y^4a_5 - 4x^3y^4b_4 + 12x^2y^5a_4 - 8x^2y^5a_6 \\ & - 8x^2y^5b_5 + 8xy^6a_5 + 8xy^6b_4 - 12xy^6b_6 - 4x^4yb_4 - 4x^3y^2a_4 \\ & - 2x^3y^2b_5 - 6x^2y^3a_5 - 12x^2y^3b_4 + 4xy^4a_4 - 8xy^4a_6 - 10xy^4b_5 \\ & - x^2ya_4 + x^2yb_5 - xy^2a_5 + xy^2b_6 - 4x^2y^4a_3 - 4x^2y^4b_2 + 8xy^5a_2 \\ & - 8xy^5b_3 - 4xy^4b_1 - 4x^3yb_2 - 2x^2y^2a_2 - 2x^2y^2b_3 - 4xy^3a_3 \\ & - 8xy^3b_2 - 4x^2yb_1 + 4y^6a_3 + 4y^6b_2 + 4y^5a_1 + 2y^4a_2 - 6y^4b_3 \\ & - 4y^3b_1 - xb_1 + ya_1 + 4y^7a_6 + 4y^7b_5 + 2y^5a_5 - 8y^5b_6 + x^3b_4 \\ & - y^3a_6 - 2x^3ya_7 - 2x^2y^2a_8 - 2xy^3a_9 + 2xy^3b_{10} - 4x^4y^4a_8 \\ & - 8x^3y^5a_9 - 12x^2y^6a_{10} - 12xy^5a_{10} - 4x^4y^4b_7 - 4x^5yb_7 = 0 \end{aligned} \tag{6E}$$

Looking at the above PDE shows the following are all the terms with $\{x, y\}$ in them.

$$\{x, y\}$$

The following substitution is now made to be able to collect on all terms with $\{x, y\}$ in them

$$\{x = v_1, y = v_2\}$$

The above PDE (6E) now becomes

$$\begin{aligned}
& 2v_1^4b_7 + 4v_2^8b_9 + 2v_2^6a_9 - 10v_2^6b_{10} - 2v_2^4a_{10} + 4v_2^8a_{10} + 4v_2^6a_3 \\
& + 4v_2^6b_2 + 4v_2^5a_1 + 2v_2^4a_2 - 6v_2^4b_3 - 4v_2^3b_1 - v_1b_1 + v_2a_1 + 4v_2^7a_6 \\
& + 4v_2^7b_5 + 2v_2^5a_5 - 8v_2^5b_6 + v_1^3b_4 - v_2^3a_6 + 12v_1^2v_2^6b_7 - 16v_1^3v_2^3b_7 \\
& + 8v_1v_2^7b_8 - 14v_1^2v_2^4b_8 + 2v_1^3v_2b_8 - 12v_1v_2^5b_9 + 2v_1^2v_2^2b_9 + 16v_1^3v_2^5a_7 \\
& - 8v_1^3v_2^5b_8 + 12v_1^2v_2^6a_8 - 12v_1^2v_2^6b_9 + 8v_1v_2^7a_9 - 16v_1v_2^7b_{10} - 6v_1^4v_2^2a_7 \\
& - 2v_1^4v_2^2b_8 - 8v_1^3v_2^3a_8 + 6v_1^2v_2^4a_7 - 10v_1^2v_2^4a_9 + 2v_1^2v_2^4b_{10} + 4v_1v_2^5a_8 \\
& - 4v_1^3v_2^4a_5 - 4v_1^3v_2^4b_4 + 12v_1^2v_2^5a_4 - 8v_1^2v_2^5a_6 - 8v_1^2v_2^5b_5 + 8v_1v_2^6a_5 \\
& + 8v_1v_2^6b_4 - 12v_1v_2^6b_6 - 4v_1^4v_2b_4 - 4v_1^3v_2^2a_4 - 2v_1^3v_2^2b_5 - 6v_1^2v_2^3a_5 \\
& - 12v_1^2v_2^3b_4 + 4v_1v_2^4a_4 - 8v_1v_2^4a_6 - 10v_1v_2^4b_5 - v_1^2v_2a_4 + v_1^2v_2b_5 \\
& - v_1v_2^2a_5 + v_1v_2^2b_6 - 4v_1^2v_2^4a_3 - 4v_1^2v_2^4b_2 + 8v_1v_2^5a_2 - 8v_1v_2^5b_3 \\
& - 4v_1v_2^4b_1 - 4v_1^3v_2b_2 - 2v_1^2v_2^2a_2 - 2v_1^2v_2^2b_3 - 4v_1v_2^3a_3 - 8v_1v_2^3b_2 \\
& - 4v_1^2v_2b_1 - 2v_1^3v_2a_7 - 2v_1^2v_2^2a_8 - 2v_1v_2^3a_9 + 2v_1v_2^3b_{10} - 4v_1^4v_2^4a_8 \\
& - 8v_1^3v_2^5a_9 - 12v_1^2v_2^6a_{10} - 12v_1v_2^5a_{10} - 4v_1^4v_2^4b_7 - 4v_1^5v_2b_7 = 0
\end{aligned} \tag{7E}$$

Collecting the above on the terms v_i introduced, and these are

$$\{v_1, v_2\}$$

Equation (7E) now becomes

$$\begin{aligned}
& 2v_1^4b_7 - v_1b_1 + v_2a_1 + v_1^3b_4 + (4b_9 + 4a_{10})v_2^8 \\
& + (2a_9 - 10b_{10} + 4a_3 + 4b_2)v_2^6 + (-2a_{10} + 2a_2 - 6b_3)v_2^4 \\
& + (4a_1 + 2a_5 - 8b_6)v_2^5 + (-a_6 - 4b_1)v_2^3 + (4a_6 + 4b_5)v_2^7 \\
& + (-4a_8 - 4b_7)v_2^4v_1^4 + (12b_7 + 12a_8 - 12b_9 - 12a_{10})v_2^6v_1^2 \\
& + (-16b_7 - 8a_8)v_2^3v_1^3 + (8b_8 + 8a_9 - 16b_{10})v_2^7v_1 \\
& + (-14b_8 + 6a_7 - 10a_9 + 2b_{10} - 4a_3 - 4b_2)v_2^4v_1^2 \\
& + (2b_8 - 4b_2 - 2a_7)v_2v_1^3 + (-12b_9 + 4a_8 + 8a_2 - 8b_3 - 12a_{10})v_2^5v_1 \\
& + (2b_9 - 2a_2 - 2b_3 - 2a_8)v_2^2v_1^2 + (16a_7 - 8b_8 - 8a_9)v_2^5v_1^3 \\
& + (-6a_7 - 2b_8)v_2^2v_1^4 + (-4a_5 - 4b_4)v_2^4v_1^3 + (-6a_5 - 12b_4)v_2^3v_1^2 \\
& + (4a_4 - 8a_6 - 4b_1 - 10b_5)v_2^4v_1 + (-a_4 - 4b_1 + b_5)v_2v_1^2 \\
& + (-a_5 + b_6)v_2^2v_1 + (-4a_3 - 8b_2 - 2a_9 + 2b_{10})v_2^3v_1 \\
& - 4v_1^4v_2b_4 + (12a_4 - 8a_6 - 8b_5)v_2^5v_1^2 \\
& + (8a_5 + 8b_4 - 12b_6)v_2^6v_1 + (-4a_4 - 2b_5)v_2^2v_1^3 - 4v_1^5v_2b_7 = 0
\end{aligned} \tag{8E}$$

Setting each coefficients in (8E) to zero gives the following equations to solve

$$\begin{aligned}a_1 &= 0 \\b_4 &= 0 \\-b_1 &= 0 \\-4b_4 &= 0 \\-4b_7 &= 0 \\2b_7 &= 0 \\-4a_4 - 2b_5 &= 0 \\-6a_5 - 12b_4 &= 0 \\-4a_5 - 4b_4 &= 0 \\-a_5 + b_6 &= 0 \\-a_6 - 4b_1 &= 0 \\4a_6 + 4b_5 &= 0 \\-6a_7 - 2b_8 &= 0 \\-4a_8 - 4b_7 &= 0 \\-16b_7 - 8a_8 &= 0 \\4b_9 + 4a_{10} &= 0 \\4a_1 + 2a_5 - 8b_6 &= 0 \\-a_4 - 4b_1 + b_5 &= 0 \\12a_4 - 8a_6 - 8b_5 &= 0 \\8a_5 + 8b_4 - 12b_6 &= 0 \\16a_7 - 8b_8 - 8a_9 &= 0 \\-2a_{10} + 2a_2 - 6b_3 &= 0 \\2b_8 - 4b_2 - 2a_7 &= 0 \\8b_8 + 8a_9 - 16b_{10} &= 0 \\-4a_3 - 8b_2 - 2a_9 + 2b_{10} &= 0 \\4a_4 - 8a_6 - 4b_1 - 10b_5 &= 0 \\2a_9 - 10b_{10} + 4a_3 + 4b_2 &= 0 \\12b_7 + 12a_8 - 12b_9 - 12a_{10} &= 0 \\2b_9 - 2a_2 - 2b_3 - 2a_8 &= 0 \\-12b_9 + 4a_8 + 8a_2 - 8b_3 - 12a_{10} &= 0 \\-14b_8 + 6a_7 - 10a_9 + 2b_{10} - 4a_3 - 4b_2 &= 0\end{aligned}$$

Solving the above equations for the unknowns gives

$$\begin{aligned}
 a_1 &= 0 \\
 a_2 &= \frac{b_9}{2} \\
 a_3 &= 2b_{10} \\
 a_4 &= 0 \\
 a_5 &= 0 \\
 a_6 &= 0 \\
 a_7 &= b_{10} \\
 a_8 &= 0 \\
 a_9 &= 5b_{10} \\
 a_{10} &= -b_9 \\
 b_1 &= 0 \\
 b_2 &= -2b_{10} \\
 b_3 &= \frac{b_9}{2} \\
 b_4 &= 0 \\
 b_5 &= 0 \\
 b_6 &= 0 \\
 b_7 &= 0 \\
 b_8 &= -3b_{10} \\
 b_9 &= b_9 \\
 b_{10} &= b_{10}
 \end{aligned}$$

Substituting the above solution in the ansatz (1E,2E) (using 1 as arbitrary value for any unknown in the RHS) gives

$$\begin{aligned}
 \xi &= x^3 + 5x y^2 + 2y \\
 \eta &= -3x^2 y + y^3 - 2x
 \end{aligned}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \tag{1}$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Unable to determine R . Terminating

7.4.2 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \quad (\text{A})$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \quad (\text{B})$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (\text{1A})$$

Therefore

$$\begin{aligned} (2y^3 - x) dy &= (-2x y^2 - y) dx \\ (2x y^2 + y) dx + (2y^3 - x) dy &= 0 \end{aligned} \quad (\text{2A})$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= 2x y^2 + y \\N(x, y) &= 2y^3 - x\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(2x y^2 + y) \\&= 4xy + 1\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(2y^3 - x) \\&= -1\end{aligned}$$

Since $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$\begin{aligned}A &= \frac{1}{N} \left(\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} \right) \\&= \frac{1}{2y^3 - x} ((4xy + 1) - (-1)) \\&= \frac{-4xy - 2}{-2y^3 + x}\end{aligned}$$

Since A depends on y , it can not be used to obtain an integrating factor. We will now try a second method to find an integrating factor. Let

$$\begin{aligned}B &= \frac{1}{M} \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) \\&= \frac{1}{2x y^2 + y} ((-1) - (4xy + 1)) \\&= -\frac{2}{y}\end{aligned}$$

Since B does not depend on x , it can be used to obtain an integrating factor. Let the integrating factor be μ . Then

$$\begin{aligned}\mu &= e^{\int B \, dy} \\&= e^{\int -\frac{2}{y} \, dy}\end{aligned}$$

The result of integrating gives

$$\begin{aligned}\mu &= e^{-2\ln(y)} \\ &= \frac{1}{y^2}\end{aligned}$$

M and N are now multiplied by this integrating factor, giving new M and new N which are called \overline{M} and \overline{N} so not to confuse them with the original M and N .

$$\begin{aligned}\overline{M} &= \mu M \\ &= \frac{1}{y^2}(2xy^2 + y) \\ &= \frac{2xy + 1}{y}\end{aligned}$$

And

$$\begin{aligned}\overline{N} &= \mu N \\ &= \frac{1}{y^2}(2y^3 - x) \\ &= \frac{2y^3 - x}{y^2}\end{aligned}$$

So now a modified ODE is obtained from the original ODE which will be exact and can be solved using the standard method. The modified ODE is

$$\begin{aligned}\overline{M} + \overline{N} \frac{dy}{dx} &= 0 \\ \left(\frac{2xy + 1}{y}\right) + \left(\frac{2y^3 - x}{y^2}\right) \frac{dy}{dx} &= 0\end{aligned}$$

The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = \overline{M} \tag{1}$$

$$\frac{\partial \phi}{\partial y} = \overline{N} \tag{2}$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int \overline{M} dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int \frac{2xy + 1}{y} dx \\ \phi &= \frac{x(xy + 1)}{y} + f(y)\end{aligned} \tag{3}$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\begin{aligned}\frac{\partial\phi}{\partial y} &= \frac{x^2}{y} - \frac{x(xy+1)}{y^2} + f'(y) \\ &= -\frac{x}{y^2} + f'(y)\end{aligned}\tag{4}$$

But equation (2) says that $\frac{\partial\phi}{\partial y} = \frac{2y^3-x}{y^2}$. Therefore equation (4) becomes

$$\frac{2y^3-x}{y^2} = -\frac{x}{y^2} + f'(y)\tag{5}$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 2y$$

Integrating the above w.r.t y gives

$$\begin{aligned}\int f'(y) dy &= \int (2y) dy \\ f(y) &= y^2 + c_1\end{aligned}$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = \frac{x(xy+1)}{y} + y^2 + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = \frac{x(xy+1)}{y} + y^2$$

Summary

The solution(s) found are the following

$$\frac{x(yx+1)}{y} + y^2 = c_1\tag{1}$$

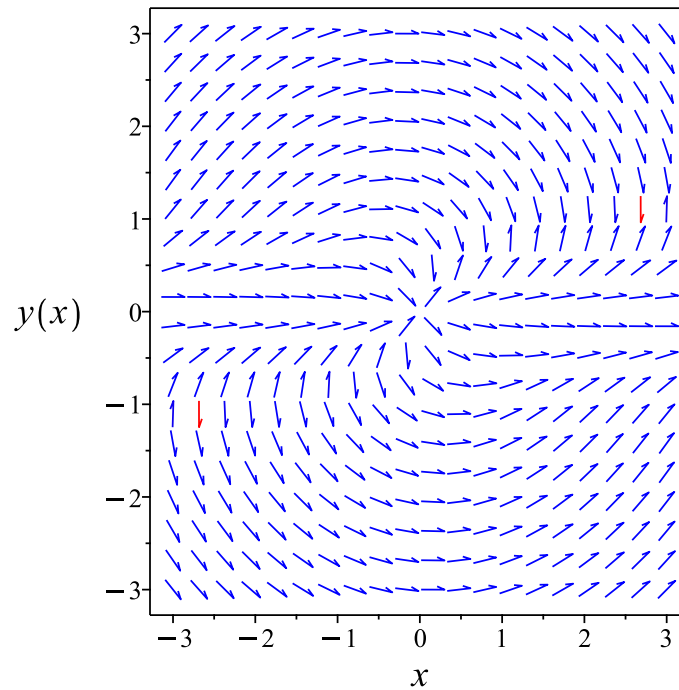


Figure 313: Slope field plot

Verification of solutions

$$\frac{x(yx + 1)}{y} + y^2 = c_1$$

Verified OK.

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
trying separable
trying inverse linear
trying homogeneous types:
trying Chini
differential order: 1; looking for linear symmetries
trying exact
<- exact successful`

```


✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 301

`dsolve((2*x*y(x)^2+y(x))+(2*y(x)^3-x)*diff(y(x),x)=0,y(x), singsol=all)`

$$y(x) = \frac{-12x^2 - 12c_1 + \left(-108x + 12\sqrt{12x^6 + 36x^4c_1 + (36c_1^2 + 81)x^2 + 12c_1^3}\right)^{\frac{2}{3}}}{6 \left(-108x + 12\sqrt{12x^6 + 36x^4c_1 + (36c_1^2 + 81)x^2 + 12c_1^3}\right)^{\frac{1}{3}}}$$

$$y(x) = \frac{\left(\frac{i\sqrt{3}}{12} + \frac{1}{12}\right) \left(-108x + 12\sqrt{12x^6 + 36x^4c_1 + (36c_1^2 + 81)x^2 + 12c_1^3}\right)^{\frac{2}{3}} + (x^2 + c_1)(i\sqrt{3} - 1)}{\left(-108x + 12\sqrt{12x^6 + 36x^4c_1 + (36c_1^2 + 81)x^2 + 12c_1^3}\right)^{\frac{1}{3}}}$$

$$y(x) = \frac{\frac{(i\sqrt{3}-1)(-108x+12\sqrt{12x^6+36x^4c_1+(36c_1^2+81)x^2+12c_1^3})^{\frac{2}{3}}}{12} + (x^2 + c_1)(1 + i\sqrt{3})}{\left(-108x + 12\sqrt{12x^6 + 36x^4c_1 + (36c_1^2 + 81)x^2 + 12c_1^3}\right)^{\frac{1}{3}}}$$

✓ Solution by Mathematica

Time used: 6.163 (sec). Leaf size: 316

`DSolve[(2*x*y[x]^2+y[x])+(2*y[x]^3-x)*y'[x]==0,y[x],x,IncludeSingularSolutions -> True]`

$$y(x) \rightarrow \frac{2^{2/3} \left(-27x + \sqrt{729x^2 + 108(x^2 - c_1)^3}\right)^{2/3} - 6\sqrt[3]{2}(x^2 - c_1)}{6\sqrt[3]{-27x + \sqrt{729x^2 + 108(x^2 - c_1)^3}}}$$

$$y(x) \rightarrow \frac{(1 - i\sqrt{3})(x^2 - c_1)}{2^{2/3} \sqrt[3]{-27x + \sqrt{729x^2 + 108(x^2 - c_1)^3}}}$$

$$- \frac{(1 + i\sqrt{3}) \sqrt[3]{-27x + \sqrt{729x^2 + 108(x^2 - c_1)^3}}}{6\sqrt[3]{2}}$$

$$y(x) \rightarrow \frac{(1 + i\sqrt{3})(x^2 - c_1)}{2^{2/3} \sqrt[3]{-27x + \sqrt{729x^2 + 108(x^2 - c_1)^3}}}$$

$$+ \frac{(-1 + i\sqrt{3}) \sqrt[3]{-27x + \sqrt{729x^2 + 108(x^2 - c_1)^3}}}{6\sqrt[3]{2}}$$

$$y(x) \rightarrow 0$$

7.5 problem 5

7.5.1 Solving as first order ode lie symmetry calculated ode 1601

7.5.2 Solving as exact ode 1607

Internal problem ID [11703]

Internal file name [OUTPUT/11712_Thursday_April_11_2024_08_48_39_PM_50875666/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 2, Section 2.4. Special integrating factors and transformations. Exercises page 67

Problem number: 5.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"exactWithIntegrationFactor", "first_order_ode_lie_symmetry_calculated"**

Maple gives the following as the ode type

```
[[_homogeneous, `class G`], _rational, [_Abel, `2nd type`, `class B`]]
```

$$4y^2x + 6y + (5x^2y + 8x)y' = 0$$

7.5.1 Solving as first order ode lie symmetry calculated ode

Writing the ode as

$$y' = -\frac{2y(2xy + 3)}{x(5xy + 8)}$$
$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2\xi_y - \omega_x\xi - \omega_y\eta = 0 \quad (\text{A})$$

The type of this ode is not in the lookup table. To determine ξ, η then (A) is solved using ansatz. Making bivariate polynomials of degree 1 to use as anstaz gives

$$\xi = xa_2 + ya_3 + a_1 \quad (1\text{E})$$

$$\eta = xb_2 + yb_3 + b_1 \quad (2\text{E})$$

Where the unknown coefficients are

$$\{a_1, a_2, a_3, b_1, b_2, b_3\}$$

Substituting equations (1E,2E) and ω into (A) gives

$$\begin{aligned} b_2 - \frac{2y(2xy+3)(b_3-a_2)}{x(5xy+8)} - \frac{4y^2(2xy+3)^2 a_3}{x^2(5xy+8)^2} \\ - \left(-\frac{4y^2}{x(5xy+8)} + \frac{2y(2xy+3)}{x^2(5xy+8)} + \frac{10y^2(2xy+3)}{x(5xy+8)^2} \right) (xa_2 + ya_3 + a_1) \\ - \left(-\frac{2(2xy+3)}{x(5xy+8)} - \frac{4y}{5xy+8} + \frac{10y(2xy+3)}{(5xy+8)^2} \right) (xb_2 + yb_3 + b_1) = 0 \end{aligned} \quad (5E)$$

Putting the above in normal form gives

$$\frac{45x^4y^2b_2 - 36x^2y^4a_3 + 20x^3y^2b_1 - 20x^2y^3a_1 + 144x^3yb_2 + 2x^2y^2a_2 + 2x^2y^2b_3 - 108xy^3a_3 + 64x^2yb_1 - 60x^2y^2a_1}{x^2(5xy+8)^2} = 0$$

Setting the numerator to zero gives

$$\begin{aligned} 45x^4y^2b_2 - 36x^2y^4a_3 + 20x^3y^2b_1 - 20x^2y^3a_1 + 144x^3yb_2 + 2x^2y^2a_2 + 2x^2y^2b_3 \\ - 108xy^3a_3 + 64x^2yb_1 - 60x^2y^2a_1 + 112b_2x^2 - 84y^2a_3 + 48xb_1 - 48ya_1 = 0 \end{aligned} \quad (6E)$$

Looking at the above PDE shows the following are all the terms with $\{x, y\}$ in them.

$$\{x, y\}$$

The following substitution is now made to be able to collect on all terms with $\{x, y\}$ in them

$$\{x = v_1, y = v_2\}$$

The above PDE (6E) now becomes

$$\begin{aligned} -36a_3v_1^2v_2^4 + 45b_2v_1^4v_2^2 - 20a_1v_1^2v_2^3 + 20b_1v_1^3v_2^2 + 2a_2v_1^2v_2^2 - 108a_3v_1v_2^3 + 144b_2v_1^3v_2 \\ + 2b_3v_1^2v_2^2 - 60a_1v_1v_2^2 + 64b_1v_1^2v_2 - 84a_3v_2^2 + 112b_2v_1^2 - 48a_1v_2 + 48b_1v_1 = 0 \end{aligned} \quad (7E)$$

Collecting the above on the terms v_i introduced, and these are

$$\{v_1, v_2\}$$

Equation (7E) now becomes

$$45b_2v_1^4v_2^2 + 20b_1v_1^3v_2^2 + 144b_2v_1^3v_2 - 36a_3v_1^2v_2^4 - 20a_1v_1^2v_2^3 + (2a_2 + 2b_3)v_1^2v_2^2 + 64b_1v_1^2v_2 + 112b_2v_1^2 - 108a_3v_1v_2^3 - 60a_1v_1v_2^2 + 48b_1v_1 - 84a_3v_2^2 - 48a_1v_2 = 0 \quad (8E)$$

Setting each coefficients in (8E) to zero gives the following equations to solve

$$\begin{aligned} -60a_1 &= 0 \\ -48a_1 &= 0 \\ -20a_1 &= 0 \\ -108a_3 &= 0 \\ -84a_3 &= 0 \\ -36a_3 &= 0 \\ 20b_1 &= 0 \\ 48b_1 &= 0 \\ 64b_1 &= 0 \\ 45b_2 &= 0 \\ 112b_2 &= 0 \\ 144b_2 &= 0 \\ 2a_2 + 2b_3 &= 0 \end{aligned}$$

Solving the above equations for the unknowns gives

$$\begin{aligned} a_1 &= 0 \\ a_2 &= -b_3 \\ a_3 &= 0 \\ b_1 &= 0 \\ b_2 &= 0 \\ b_3 &= b_3 \end{aligned}$$

Substituting the above solution in the anstaz (1E,2E) (using 1 as arbitrary value for any unknown in the RHS) gives

$$\begin{aligned} \xi &= -x \\ \eta &= y \end{aligned}$$

Shifting is now applied to make $\xi = 0$ in order to simplify the rest of the computation

$$\begin{aligned}\eta &= \eta - \omega(x, y) \xi \\ &= y - \left(-\frac{2y(2xy + 3)}{x(5xy + 8)} \right) (-x) \\ &= \frac{xy^2 + 2y}{5xy + 8} \\ \xi &= 0\end{aligned}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \quad (1)$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y} \right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned}S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{xy^2 + 2y}{5xy + 8}} dy\end{aligned}$$

Which results in

$$S = 4 \ln(y) + \ln(xy + 2)$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{2y(2xy + 3)}{x(5xy + 8)}$$

Evaluating all the partial derivatives gives

$$\begin{aligned}R_x &= 1 \\R_y &= 0 \\S_x &= \frac{y}{xy + 2} \\S_y &= \frac{4}{y} + \frac{x}{xy + 2}\end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = -\frac{3}{x} \tag{2A}$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = -\frac{3}{R}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = -3 \ln(R) + c_1 \tag{4}$$

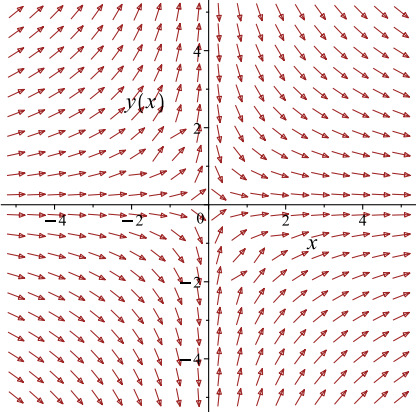
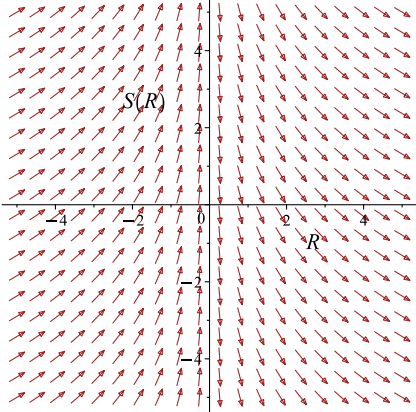
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$4 \ln(y) + \ln(yx + 2) = -3 \ln(x) + c_1$$

Which simplifies to

$$4 \ln(y) + \ln(yx + 2) = -3 \ln(x) + c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{2y(2xy+3)}{x(5xy+8)}$ 	$R = x$ $S = 4 \ln(y) + \ln(xy + 2)$	$\frac{dS}{dR} = -\frac{3}{R}$ 

Summary

The solution(s) found are the following

$$4 \ln(y) + \ln(yx + 2) = -3 \ln(x) + c_1 \tag{1}$$

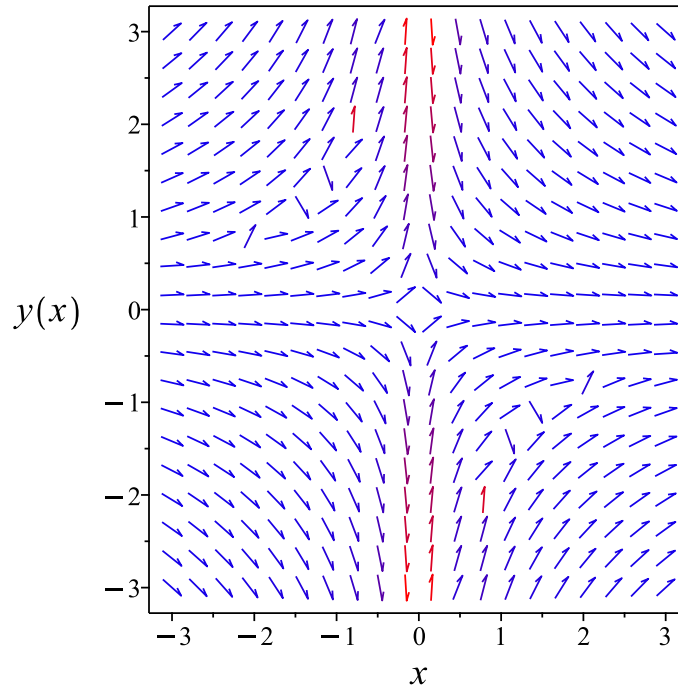


Figure 314: Slope field plot

Verification of solutions

$$4 \ln(y) + \ln(yx + 2) = -3 \ln(x) + c_1$$

Verified OK.

7.5.2 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \quad (\text{A})$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \quad (\text{B})$$

Comparing (A,B) shows that

$$\begin{aligned}\frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N\end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \tag{1A}$$

Therefore

$$\begin{aligned}(5x^2y + 8x) dy &= (-4xy^2 - 6y) dx \\ (4xy^2 + 6y) dx + (5x^2y + 8x) dy &= 0\end{aligned} \tag{2A}$$

Comparing (1A) and (2A) shows that

$$\begin{aligned}M(x, y) &= 4xy^2 + 6y \\ N(x, y) &= 5x^2y + 8x\end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned}\frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(4xy^2 + 6y) \\ &= 8xy + 6\end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(5x^2y + 8x) \\ &= 10xy + 8\end{aligned}$$

Since $\frac{\partial M}{\partial y} \neq \frac{\partial N}{\partial x}$, then the ODE is not exact. Since the ODE is not exact, we will try to find an integrating factor to make it exact. Let

$$\begin{aligned} A &= \frac{1}{N} \left(\frac{\partial M}{\partial y} - \frac{\partial N}{\partial x} \right) \\ &= \frac{1}{5x^2y + 8x} ((8xy + 6) - (10xy + 8)) \\ &= \frac{-2xy - 2}{5x^2y + 8x} \end{aligned}$$

Since A depends on y , it can not be used to obtain an integrating factor. We will now try a second method to find an integrating factor. Let

$$\begin{aligned} B &= \frac{1}{M} \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) \\ &= \frac{1}{4xy^2 + 6y} ((10xy + 8) - (8xy + 6)) \\ &= \frac{xy + 1}{2xy^2 + 3y} \end{aligned}$$

Since B depends on x , it can not be used to obtain an integrating factor. We will now try a third method to find an integrating factor. Let

$$R = \frac{\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y}}{xM - yN}$$

R is now checked to see if it is a function of only $t = xy$. Therefore

$$\begin{aligned} R &= \frac{\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y}}{xM - yN} \\ &= \frac{(10xy + 8) - (8xy + 6)}{x(4xy^2 + 6y) - y(5x^2y + 8x)} \\ &= \frac{-2xy - 2}{xy(xy + 2)} \end{aligned}$$

Replacing all powers of terms xy by t gives

$$R = \frac{-2t - 2}{t(t + 2)}$$

Since R depends on t only, then it can be used to find an integrating factor. Let the integrating factor be μ then

$$\begin{aligned} \mu &= e^{\int R dt} \\ &= e^{\int \left(\frac{-2t-2}{t(t+2)} \right) dt} \end{aligned}$$

The result of integrating gives

$$\begin{aligned}\mu &= e^{-\ln(t(t+2))} \\ &= \frac{1}{t(t+2)}\end{aligned}$$

Now t is replaced back with xy giving

$$\mu = \frac{1}{xy(xy+2)}$$

Multiplying M and N by this integrating factor gives new M and new N which are called \overline{M} and \overline{N} so not to confuse them with the original M and N

$$\begin{aligned}\overline{M} &= \mu M \\ &= \frac{1}{xy(xy+2)}(4xy^2 + 6y) \\ &= \frac{4xy + 6}{(xy+2)x}\end{aligned}$$

And

$$\begin{aligned}\overline{N} &= \mu N \\ &= \frac{1}{xy(xy+2)}(5x^2y + 8x) \\ &= \frac{5xy + 8}{y(xy+2)}\end{aligned}$$

A modified ODE is now obtained from the original ODE, which is exact and can be solved. The modified ODE is

$$\begin{aligned}\overline{M} + \overline{N} \frac{dy}{dx} &= 0 \\ \left(\frac{4xy + 6}{(xy+2)x} \right) + \left(\frac{5xy + 8}{y(xy+2)} \right) \frac{dy}{dx} &= 0\end{aligned}$$

The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = \overline{M} \tag{1}$$

$$\frac{\partial \phi}{\partial y} = \overline{N} \tag{2}$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int \overline{M} dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int \frac{4xy + 6}{(xy + 2)x} dx \\ \phi &= \ln(xy + 2) + 3 \ln(x) + f(y)\end{aligned}\quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = \frac{x}{xy + 2} + f'(y)\quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = \frac{5xy+8}{y(xy+2)}$. Therefore equation (4) becomes

$$\frac{5xy + 8}{y(xy + 2)} = \frac{x}{xy + 2} + f'(y)\quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = \frac{4}{y}$$

Integrating the above w.r.t y gives

$$\begin{aligned}\int f'(y) dy &= \int \left(\frac{4}{y}\right) dy \\ f(y) &= 4 \ln(y) + c_1\end{aligned}$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = \ln(xy + 2) + 3 \ln(x) + 4 \ln(y) + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = \ln(xy + 2) + 3 \ln(x) + 4 \ln(y)$$

Summary

The solution(s) found are the following

$$4 \ln(y) + \ln(yx + 2) + 3 \ln(x) = c_1 \quad (1)$$

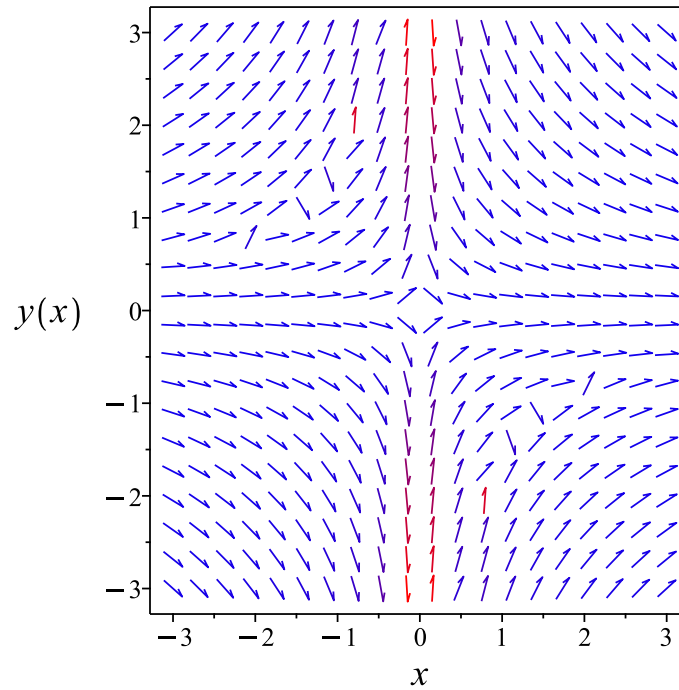


Figure 315: Slope field plot

Verification of solutions

$$4 \ln(y) + \ln(yx + 2) + 3 \ln(x) = c_1$$

Verified OK.

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
trying Bernoulli  
trying separable  
trying inverse linear  
trying homogeneous types:  
trying homogeneous G  
<- homogeneous successful`
```

✓ Solution by Maple

Time used: 0.078 (sec). Leaf size: 23

```
dsolve((4*x*y(x)^2+6*y(x))+(5*x^2*y(x)+8*x)*diff(y(x),x)=0,y(x), singsol=all)
```

$$y(x) = \frac{\text{RootOf}(-\ln(x) + c_1 + \ln(_Z + 2) + 4 \ln(_Z))}{x}$$

✓ Solution by Mathematica

Time used: 1.767 (sec). Leaf size: 156

```
DSolve[(4*x*y[x]^2+6*y[x])+(5*x^2*y[x]+8*x)*y'[x]==0,y[x],x,IncludeSingularSolutions -> True
```

$$\begin{aligned}y(x) &\rightarrow \text{Root} \left[-\#1^5 - \frac{2\#1^4}{x} + \frac{e^{c_1}}{x^4} \&, 1 \right] \\y(x) &\rightarrow \text{Root} \left[-\#1^5 - \frac{2\#1^4}{x} + \frac{e^{c_1}}{x^4} \&, 2 \right] \\y(x) &\rightarrow \text{Root} \left[-\#1^5 - \frac{2\#1^4}{x} + \frac{e^{c_1}}{x^4} \&, 3 \right] \\y(x) &\rightarrow \text{Root} \left[-\#1^5 - \frac{2\#1^4}{x} + \frac{e^{c_1}}{x^4} \&, 4 \right] \\y(x) &\rightarrow \text{Root} \left[-\#1^5 - \frac{2\#1^4}{x} + \frac{e^{c_1}}{x^4} \&, 5 \right]\end{aligned}$$

7.6 problem 6

7.6.1 Solving as first order ode lie symmetry calculated ode 1614

Internal problem ID [11704]

Internal file name [OUTPUT/11713_Thursday_April_11_2024_08_48_41_PM_99209226/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, Section 2.4. Special integrating factors and transformations. Exercises page 67

Problem number: 6.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**first_order_ode_lie_symmetry_calculated**"

Maple gives the following as the ode type

```
[[_homogeneous, `class G`], _rational, [_Abel, `2nd type`, `class B`]]
```

$$8y^3x^2 - 2y^4 + (5y^2x^3 - 8y^3x)y' = 0$$

7.6.1 Solving as first order ode lie symmetry calculated ode

Writing the ode as

$$y' = -\frac{2y(-4x^2 + y)}{x(-5x^2 + 8y)}$$
$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2\xi_y - \omega_x\xi - \omega_y\eta = 0 \quad (\text{A})$$

The type of this ode is not in the lookup table. To determine ξ, η then (A) is solved using ansatz. Making bivariate polynomials of degree 1 to use as anstaz gives

$$\xi = xa_2 + ya_3 + a_1 \quad (1\text{E})$$

$$\eta = xb_2 + yb_3 + b_1 \quad (2\text{E})$$

Where the unknown coefficients are

$$\{a_1, a_2, a_3, b_1, b_2, b_3\}$$

Substituting equations (1E,2E) and ω into (A) gives

$$\begin{aligned} b_2 - \frac{2y(-4x^2 + y)(b_3 - a_2)}{x(-5x^2 + 8y)} - \frac{4y^2(-4x^2 + y)^2 a_3}{x^2(-5x^2 + 8y)^2} \\ - \left(\frac{16y}{-5x^2 + 8y} + \frac{2y(-4x^2 + y)}{x^2(-5x^2 + 8y)} - \frac{20y(-4x^2 + y)}{(-5x^2 + 8y)^2} \right) (xa_2 + ya_3 + a_1) \\ - \left(-\frac{2(-4x^2 + y)}{x(-5x^2 + 8y)} - \frac{2y}{x(-5x^2 + 8y)} \right. \\ \left. + \frac{16y(-4x^2 + y)}{x(-5x^2 + 8y)^2} \right) (xb_2 + yb_3 + b_1) = 0 \end{aligned} \quad (5E)$$

Putting the above in normal form gives

$$\frac{65x^6b_2 - 104x^4y^2a_3 + 40x^5b_1 - 40x^4ya_1 - 100x^4yb_2 - 108x^3y^2a_2 + 54x^3y^2b_3 - 2x^2y^3a_3 - 20x^3yb_1 - 34x^4a_1}{(5x^2 - 8y)^2 x^2} = 0$$

Setting the numerator to zero gives

$$\begin{aligned} 65x^6b_2 - 104x^4y^2a_3 + 40x^5b_1 - 40x^4ya_1 - 100x^4yb_2 - 108x^3y^2a_2 + 54x^3y^2b_3 \\ - 2x^2y^3a_3 - 20x^3yb_1 - 34x^2y^2a_1 + 80x^2y^2b_2 - 20y^4a_3 + 16xy^2b_1 - 16y^3a_1 = 0 \end{aligned} \quad (6E)$$

Looking at the above PDE shows the following are all the terms with $\{x, y\}$ in them.

$$\{x, y\}$$

The following substitution is now made to be able to collect on all terms with $\{x, y\}$ in them

$$\{x = v_1, y = v_2\}$$

The above PDE (6E) now becomes

$$\begin{aligned} -104a_3v_1^4v_2^2 + 65b_2v_1^6 - 40a_1v_1^4v_2 - 108a_2v_1^3v_2^2 - 2a_3v_1^2v_2^3 + 40b_1v_1^5 - 100b_2v_1^4v_2 \\ + 54b_3v_1^3v_2^2 - 34a_1v_1^2v_2^2 - 20a_3v_2^4 - 20b_1v_1^3v_2 + 80b_2v_1^2v_2^2 - 16a_1v_2^3 + 16b_1v_1v_2^2 = 0 \end{aligned} \quad (7E)$$

Collecting the above on the terms v_i introduced, and these are

$$\{v_1, v_2\}$$

Equation (7E) now becomes

$$65b_2v_1^6 + 40b_1v_1^5 - 104a_3v_1^4v_2^2 + (-40a_1 - 100b_2)v_1^4v_2 + (-108a_2 + 54b_3)v_1^3v_2^2 \quad (8E) \\ - 20b_1v_1^3v_2 - 2a_3v_1^2v_2^3 + (-34a_1 + 80b_2)v_1^2v_2^2 + 16b_1v_1v_2^2 - 20a_3v_2^4 - 16a_1v_2^3 = 0$$

Setting each coefficients in (8E) to zero gives the following equations to solve

$$\begin{aligned} -16a_1 &= 0 \\ -104a_3 &= 0 \\ -20a_3 &= 0 \\ -2a_3 &= 0 \\ -20b_1 &= 0 \\ 16b_1 &= 0 \\ 40b_1 &= 0 \\ 65b_2 &= 0 \\ -40a_1 - 100b_2 &= 0 \\ -34a_1 + 80b_2 &= 0 \\ -108a_2 + 54b_3 &= 0 \end{aligned}$$

Solving the above equations for the unknowns gives

$$\begin{aligned} a_1 &= 0 \\ a_2 &= a_2 \\ a_3 &= 0 \\ b_1 &= 0 \\ b_2 &= 0 \\ b_3 &= 2a_2 \end{aligned}$$

Substituting the above solution in the anstaz (1E,2E) (using 1 as arbitrary value for any unknown in the RHS) gives

$$\begin{aligned} \xi &= x \\ \eta &= 2y \end{aligned}$$

Shifting is now applied to make $\xi = 0$ in order to simplify the rest of the computation

$$\begin{aligned}\eta &= \eta - \omega(x, y) \xi \\ &= 2y - \left(-\frac{2y(-4x^2 + y)}{x(-5x^2 + 8y)} \right) (x) \\ &= \frac{18x^2y - 18y^2}{5x^2 - 8y} \\ \xi &= 0\end{aligned}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \quad (1)$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y} \right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned}S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{18x^2y - 18y^2}{5x^2 - 8y}} dy\end{aligned}$$

Which results in

$$S = \frac{\ln(-x^2 + y)}{6} + \frac{5 \ln(y)}{18}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{2y(-4x^2 + y)}{x(-5x^2 + 8y)}$$

Evaluating all the partial derivatives gives

$$\begin{aligned}R_x &= 1 \\R_y &= 0 \\S_x &= \frac{x}{3x^2 - 3y} \\S_y &= -\frac{1}{6x^2 - 6y} + \frac{5}{18y}\end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = -\frac{1}{9x} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = -\frac{1}{9R}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = -\frac{\ln(R)}{9} + c_1 \quad (4)$$

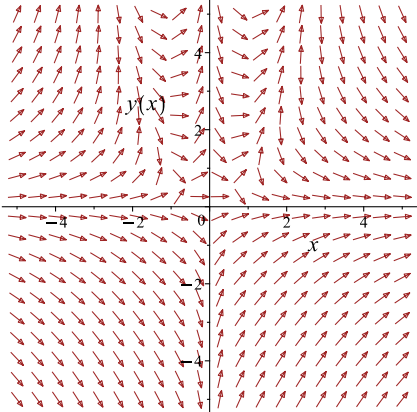
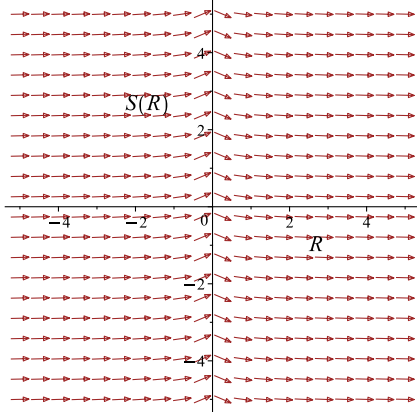
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$\frac{\ln(-x^2 + y)}{6} + \frac{5 \ln(y)}{18} = -\frac{\ln(x)}{9} + c_1$$

Which simplifies to

$$\frac{\ln(-x^2 + y)}{6} + \frac{5 \ln(y)}{18} = -\frac{\ln(x)}{9} + c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{2y(-4x^2+y)}{x(-5x^2+8y)}$ 	$R = x$ $S = \frac{\ln(-x^2 + y)}{6} + \frac{5 \ln(x)}{18}$	$\frac{dS}{dR} = -\frac{1}{9R}$ 

Summary

The solution(s) found are the following

$$\frac{\ln(-x^2 + y)}{6} + \frac{5 \ln(y)}{18} = -\frac{\ln(x)}{9} + c_1 \tag{1}$$

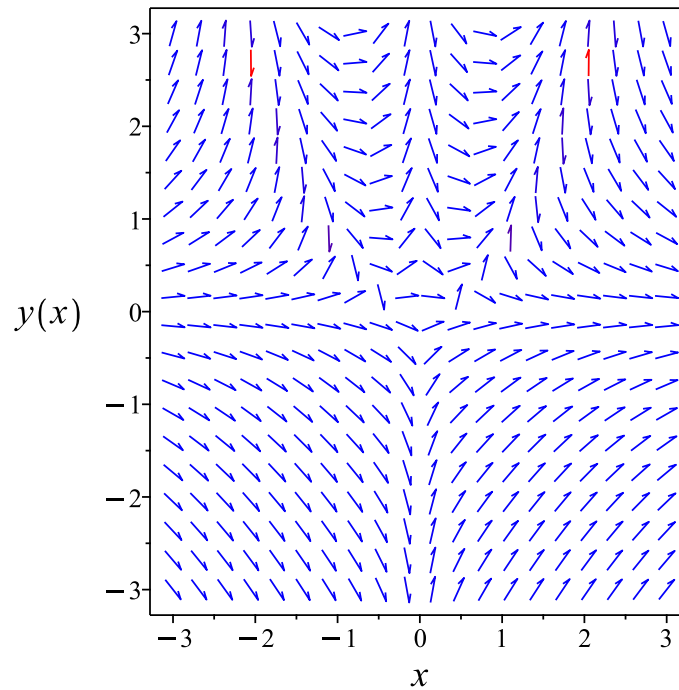


Figure 316: Slope field plot

Verification of solutions

$$\frac{\ln(-x^2 + y)}{6} + \frac{5 \ln(y)}{18} = -\frac{\ln(x)}{9} + c_1$$

Verified OK.

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
trying separable
trying inverse linear
trying homogeneous types:
trying homogeneous G
<- homogeneous successful`

```

✓ Solution by Maple

Time used: 0.703 (sec). Leaf size: 34

```
dsolve((8*x^2*y(x)^3-2*y(x)^4)+(5*x^3*y(x)^2-8*x*y(x)^3)*diff(y(x),x)=0,y(x), singsol=all)
```

$$y(x) = 0$$

$$y(x) = \text{RootOf}(x^6_Z^{48} - x^6_Z^{30} - c_1)^{18} x^2$$

✓ Solution by Mathematica

Time used: 3.924 (sec). Leaf size: 411

```
DSolve[(8*x^2*y[x]^3-2*y[x]^4)+(5*x^3*y[x]^2-8*x*y[x]^3)*y'[x]==0,y[x],x,IncludeSingularSolu
```

$$y(x) \rightarrow 0$$

$$y(x) \rightarrow \text{Root} \left[-\#1^8 + 3\#1^7 x^2 - 3\#1^6 x^4 + \#1^5 x^6 + \frac{e^{18c_1}}{x^2} \&, 1 \right]$$

$$y(x) \rightarrow \text{Root} \left[-\#1^8 + 3\#1^7 x^2 - 3\#1^6 x^4 + \#1^5 x^6 + \frac{e^{18c_1}}{x^2} \&, 2 \right]$$

$$y(x) \rightarrow \text{Root} \left[-\#1^8 + 3\#1^7 x^2 - 3\#1^6 x^4 + \#1^5 x^6 + \frac{e^{18c_1}}{x^2} \&, 3 \right]$$

$$y(x) \rightarrow \text{Root} \left[-\#1^8 + 3\#1^7 x^2 - 3\#1^6 x^4 + \#1^5 x^6 + \frac{e^{18c_1}}{x^2} \&, 4 \right]$$

$$y(x) \rightarrow \text{Root} \left[-\#1^8 + 3\#1^7 x^2 - 3\#1^6 x^4 + \#1^5 x^6 + \frac{e^{18c_1}}{x^2} \&, 5 \right]$$

$$y(x) \rightarrow \text{Root} \left[-\#1^8 + 3\#1^7 x^2 - 3\#1^6 x^4 + \#1^5 x^6 + \frac{e^{18c_1}}{x^2} \&, 6 \right]$$

$$y(x) \rightarrow \text{Root} \left[-\#1^8 + 3\#1^7 x^2 - 3\#1^6 x^4 + \#1^5 x^6 + \frac{e^{18c_1}}{x^2} \&, 7 \right]$$

$$y(x) \rightarrow \text{Root} \left[-\#1^8 + 3\#1^7 x^2 - 3\#1^6 x^4 + \#1^5 x^6 + \frac{e^{18c_1}}{x^2} \&, 8 \right]$$

$$y(x) \rightarrow 0$$

7.7 problem 7

7.7.1	Solving as differentialType ode	1622
7.7.2	Solving as homogeneousTypeMapleC ode	1624
7.7.3	Solving as first order ode lie symmetry calculated ode	1627
7.7.4	Solving as exact ode	1632
7.7.5	Maple step by step solution	1636

Internal problem ID [11705]

Internal file name [OUTPUT/11714_Thursday_April_11_2024_08_48_42_PM_29529941/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 2, Section 2.4. Special integrating factors and transformations. Exercises page 67

Problem number: 7.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact", "differentialType", "homogeneousTypeMapleC", "first_order_ode_lie_symmetry_calculated"

Maple gives the following as the ode type

```
[[_homogeneous, `class C`], _exact, _rational, [_Abel, `2nd type`, `class A`]]
```

$$2y + (2x + y + 1)y' = -5x - 1$$

7.7.1 Solving as differentialType ode

Writing the ode as

$$y' = \frac{-5x - 2y - 1}{2x + y + 1} \quad (1)$$

Which becomes

$$(y + 1) dy = (-2x) dy + (-5x - 2y - 1) dx \quad (2)$$

But the RHS is complete differential because

$$(-2x) dy + (-5x - 2y - 1) dx = d\left(-\frac{5}{2}x^2 - 2xy - x\right)$$

Hence (2) becomes

$$(y + 1) dy = d\left(-\frac{5}{2}x^2 - 2xy - x\right)$$

Integrating both sides gives gives these solutions

$$y = -2x - 1 + \sqrt{-x^2 + 2c_1 + 2x + 1} + c_1$$

$$y = -2x - 1 - \sqrt{-x^2 + 2c_1 + 2x + 1} + c_1$$

Summary

The solution(s) found are the following

$$y = -2x - 1 + \sqrt{-x^2 + 2c_1 + 2x + 1} + c_1 \quad (1)$$

$$y = -2x - 1 - \sqrt{-x^2 + 2c_1 + 2x + 1} + c_1 \quad (2)$$

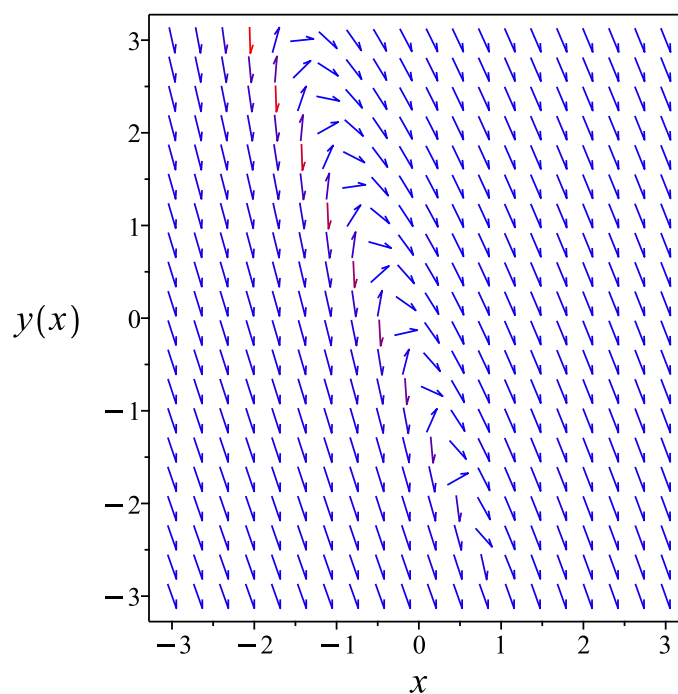


Figure 317: Slope field plot

Verification of solutions

$$y = -2x - 1 + \sqrt{-x^2 + 2c_1 + 2x + 1} + c_1$$

Verified OK.

$$y = -2x - 1 - \sqrt{-x^2 + 2c_1 + 2x + 1} + c_1$$

Verified OK.

7.7.2 Solving as homogeneousTypeMapleC ode

Let $Y = y + y_0$ and $X = x + x_0$ then the above is transformed to new ode in $Y(X)$

$$\frac{d}{dX}Y(X) = -\frac{5X + 5x_0 + 2Y(X) + 2y_0 + 1}{2X + 2x_0 + Y(X) + y_0 + 1}$$

Solving for possible values of x_0 and y_0 which makes the above ode a homogeneous ode results in

$$\begin{aligned}x_0 &= 1 \\y_0 &= -3\end{aligned}$$

Using these values now it is possible to easily solve for $Y(X)$. The above ode now becomes

$$\frac{d}{dX}Y(X) = -\frac{5X + 2Y(X)}{2X + Y(X)}$$

In canonical form, the ODE is

$$\begin{aligned}Y' &= F(X, Y) \\ &= -\frac{5X + 2Y}{2X + Y}\end{aligned}\tag{1}$$

An ode of the form $Y' = \frac{M(X, Y)}{N(X, Y)}$ is called homogeneous if the functions $M(X, Y)$ and $N(X, Y)$ are both homogeneous functions and of the same order. Recall that a function $f(X, Y)$ is homogeneous of order n if

$$f(t^n X, t^n Y) = t^n f(X, Y)$$

In this case, it can be seen that both $M = -5X - 2Y$ and $N = 2X + Y$ are both homogeneous and of the same order $n = 1$. Therefore this is a homogeneous ode. Since this ode is homogeneous, it is converted to separable ODE using the substitution $u = \frac{Y}{X}$, or $Y = uX$. Hence

$$\frac{dY}{dX} = \frac{du}{dX}X + u$$

Applying the transformation $Y = uX$ to the above ODE in (1) gives

$$\begin{aligned}\frac{du}{dX}X + u &= \frac{-2u - 5}{u + 2} \\ \frac{du}{dX} &= \frac{\frac{-2u(X) - 5}{u(X) + 2} - u(X)}{X}\end{aligned}$$

Or

$$\frac{d}{dX}u(X) - \frac{-2u(X)-5}{u(X)+2} - \frac{u(X)}{X} = 0$$

Or

$$\left(\frac{d}{dX}u(X)\right)Xu(X) + 2\left(\frac{d}{dX}u(X)\right)X + u(X)^2 + 4u(X) + 5 = 0$$

Or

$$X(u(X) + 2)\left(\frac{d}{dX}u(X)\right) + u(X)^2 + 4u(X) + 5 = 0$$

Which is now solved as separable in $u(X)$. Which is now solved in $u(X)$. In canonical form the ODE is

$$\begin{aligned}u' &= F(X, u) \\ &= f(X)g(u) \\ &= -\frac{u^2 + 4u + 5}{X(u + 2)}\end{aligned}$$

Where $f(X) = -\frac{1}{X}$ and $g(u) = \frac{u^2+4u+5}{u+2}$. Integrating both sides gives

$$\begin{aligned}\frac{1}{\frac{u^2+4u+5}{u+2}} du &= -\frac{1}{X} dX \\ \int \frac{1}{\frac{u^2+4u+5}{u+2}} du &= \int -\frac{1}{X} dX \\ \frac{\ln(u^2 + 4u + 5)}{2} &= -\ln(X) + c_2\end{aligned}$$

Raising both side to exponential gives

$$\sqrt{u^2 + 4u + 5} = e^{-\ln(X)+c_2}$$

Which simplifies to

$$\sqrt{u^2 + 4u + 5} = \frac{c_3}{X}$$

Which simplifies to

$$\sqrt{u(X)^2 + 4u(X) + 5} = \frac{c_3 e^{c_2}}{X}$$

The solution is

$$\sqrt{u(X)^2 + 4u(X) + 5} = \frac{c_3 e^{c_2}}{X}$$

Now u in the above solution is replaced back by Y using $u = \frac{Y}{X}$ which results in the solution

$$\sqrt{\frac{Y(X)^2}{X^2} + \frac{4Y(X)}{X} + 5} = \frac{c_3 e^{c_2}}{X}$$

Using the solution for $Y(X)$

$$\sqrt{\frac{Y(X)^2 + 4Y(X)X + 5X^2}{X^2}} = \frac{c_3 e^{c_2}}{X}$$

And replacing back terms in the above solution using

$$Y = y + y_0$$

$$X = x + x_0$$

Or

$$Y = y - 3$$

$$X = 1 + x$$

Then the solution in y becomes

$$\sqrt{\frac{(y+3)^2 + 4(y+3)(x-1) + 5(x-1)^2}{(x-1)^2}} = \frac{c_3 e^{c_2}}{x-1}$$

Summary

The solution(s) found are the following

$$\sqrt{\frac{(y+3)^2 + 4(y+3)(x-1) + 5(x-1)^2}{(x-1)^2}} = \frac{c_3 e^{c_2}}{x-1} \quad (1)$$

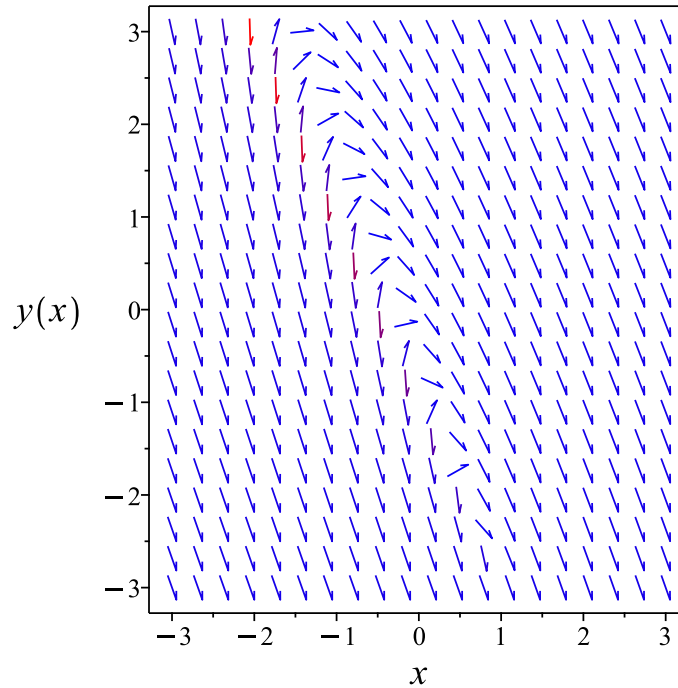


Figure 318: Slope field plot

Verification of solutions

$$\sqrt{\frac{(y+3)^2 + 4(y+3)(x-1) + 5(x-1)^2}{(x-1)^2}} = \frac{c_3 e^{c_2}}{x-1}$$

Verified OK.

7.7.3 Solving as first order ode lie symmetry calculated ode

Writing the ode as

$$y' = -\frac{5x + 2y + 1}{2x + y + 1}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is not in the lookup table. To determine ξ, η then (A) is solved using ansatz. Making bivariate polynomials of degree 1 to use as anstaz gives

$$\xi = xa_2 + ya_3 + a_1 \quad (1\text{E})$$

$$\eta = xb_2 + yb_3 + b_1 \quad (2\text{E})$$

Where the unknown coefficients are

$$\{a_1, a_2, a_3, b_1, b_2, b_3\}$$

Substituting equations (1E,2E) and ω into (A) gives

$$\begin{aligned} b_2 - \frac{(5x + 2y + 1)(b_3 - a_2)}{2x + y + 1} - \frac{(5x + 2y + 1)^2 a_3}{(2x + y + 1)^2} \\ - \left(-\frac{5}{2x + y + 1} + \frac{10x + 4y + 2}{(2x + y + 1)^2} \right) (xa_2 + ya_3 + a_1) \\ - \left(-\frac{2}{2x + y + 1} + \frac{5x + 2y + 1}{(2x + y + 1)^2} \right) (xb_2 + yb_3 + b_1) = 0 \end{aligned} \quad (5E)$$

Putting the above in normal form gives

$$\frac{10x^2a_2 - 25x^2a_3 + 3x^2b_2 - 10x^2b_3 + 10xya_2 - 20xya_3 + 4xyb_2 - 10xyb_3 + 2y^2a_2 - 3y^2a_3 + y^2b_2 - 2y^2b_3}{(2x + y + 1)^2} = 0$$

Setting the numerator to zero gives

$$\begin{aligned} 10x^2a_2 - 25x^2a_3 + 3x^2b_2 - 10x^2b_3 + 10xya_2 - 20xya_3 + 4xyb_2 - 10xyb_3 \\ + 2y^2a_2 - 3y^2a_3 + y^2b_2 - 2y^2b_3 + 10xa_2 - 10xa_3 - xb_1 + 5xb_2 - 7xb_3 \\ + ya_1 + 3ya_2 - ya_3 + 2yb_2 - 2yb_3 + 3a_1 + a_2 - a_3 + b_1 + b_2 - b_3 = 0 \end{aligned} \quad (6E)$$

Looking at the above PDE shows the following are all the terms with $\{x, y\}$ in them.

$$\{x, y\}$$

The following substitution is now made to be able to collect on all terms with $\{x, y\}$ in them

$$\{x = v_1, y = v_2\}$$

The above PDE (6E) now becomes

$$\begin{aligned} 10a_2v_1^2 + 10a_2v_1v_2 + 2a_2v_2^2 - 25a_3v_1^2 - 20a_3v_1v_2 - 3a_3v_2^2 + 3b_2v_1^2 + 4b_2v_1v_2 \\ + b_2v_2^2 - 10b_3v_1^2 - 10b_3v_1v_2 - 2b_3v_2^2 + a_1v_2 + 10a_2v_1 + 3a_2v_2 - 10a_3v_1 - a_3v_2 \\ - b_1v_1 + 5b_2v_1 + 2b_2v_2 - 7b_3v_1 - 2b_3v_2 + 3a_1 + a_2 - a_3 + b_1 + b_2 - b_3 = 0 \end{aligned} \quad (7E)$$

Collecting the above on the terms v_i introduced, and these are

$$\{v_1, v_2\}$$

Equation (7E) now becomes

$$\begin{aligned} & (10a_2 - 25a_3 + 3b_2 - 10b_3)v_1^2 + (10a_2 - 20a_3 + 4b_2 - 10b_3)v_1v_2 \\ & + (10a_2 - 10a_3 - b_1 + 5b_2 - 7b_3)v_1 + (2a_2 - 3a_3 + b_2 - 2b_3)v_2^2 \\ & + (a_1 + 3a_2 - a_3 + 2b_2 - 2b_3)v_2 + 3a_1 + a_2 - a_3 + b_1 + b_2 - b_3 = 0 \end{aligned} \quad (8E)$$

Setting each coefficients in (8E) to zero gives the following equations to solve

$$\begin{aligned} 2a_2 - 3a_3 + b_2 - 2b_3 &= 0 \\ 10a_2 - 25a_3 + 3b_2 - 10b_3 &= 0 \\ 10a_2 - 20a_3 + 4b_2 - 10b_3 &= 0 \\ a_1 + 3a_2 - a_3 + 2b_2 - 2b_3 &= 0 \\ 10a_2 - 10a_3 - b_1 + 5b_2 - 7b_3 &= 0 \\ 3a_1 + a_2 - a_3 + b_1 + b_2 - b_3 &= 0 \end{aligned}$$

Solving the above equations for the unknowns gives

$$\begin{aligned} a_1 &= -a_3 - b_3 \\ a_2 &= 4a_3 + b_3 \\ a_3 &= a_3 \\ b_1 &= 5a_3 + 3b_3 \\ b_2 &= -5a_3 \\ b_3 &= b_3 \end{aligned}$$

Substituting the above solution in the anstaz (1E,2E) (using 1 as arbitrary value for any unknown in the RHS) gives

$$\begin{aligned} \xi &= x - 1 \\ \eta &= 3 + y \end{aligned}$$

Shifting is now applied to make $\xi = 0$ in order to simplify the rest of the computation

$$\begin{aligned} \eta &= \eta - \omega(x, y) \xi \\ &= 3 + y - \left(-\frac{5x + 2y + 1}{2x + y + 1} \right) (x - 1) \\ &= \frac{5x^2 + 4xy + y^2 + 2x + 2y + 2}{2x + y + 1} \\ \xi &= 0 \end{aligned}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \quad (1)$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{5x^2 + 4xy + y^2 + 2x + 2y + 2}{2x + y + 1}} dy \end{aligned}$$

Which results in

$$S = \frac{\ln(5x^2 + 4xy + y^2 + 2x + 2y + 2)}{2}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{5x + 2y + 1}{2x + y + 1}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= \frac{5x + 2y + 1}{5x^2 + (4y + 2)x + y^2 + 2y + 2} \\ S_y &= \frac{2x + y + 1}{y^2 + (4x + 2)y + 5x^2 + 2x + 2} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 0 \tag{2A}$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 0$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = c_1 \tag{4}$$

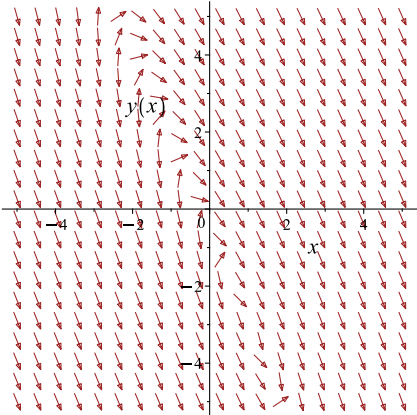
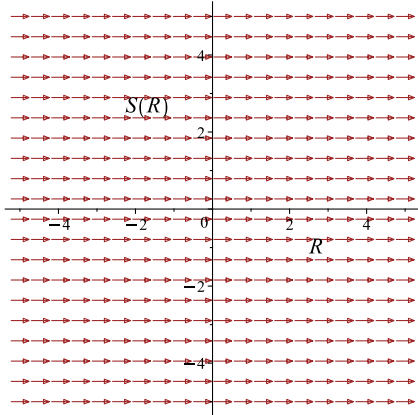
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$\frac{\ln(5x^2 + (4y + 2)x + y^2 + 2y + 2)}{2} = c_1$$

Which simplifies to

$$\frac{\ln(5x^2 + (4y + 2)x + y^2 + 2y + 2)}{2} = c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{5x+2y+1}{2x+y+1}$ 	$R = x$ $S = \frac{\ln(5x^2 + (4y + 2)x + y^2 + 2y + 2)}{2}$	$\frac{dS}{dR} = 0$ 

Summary

The solution(s) found are the following

$$\frac{\ln(5x^2 + (4y + 2)x + y^2 + 2y + 2)}{2} = c_1 \quad (1)$$

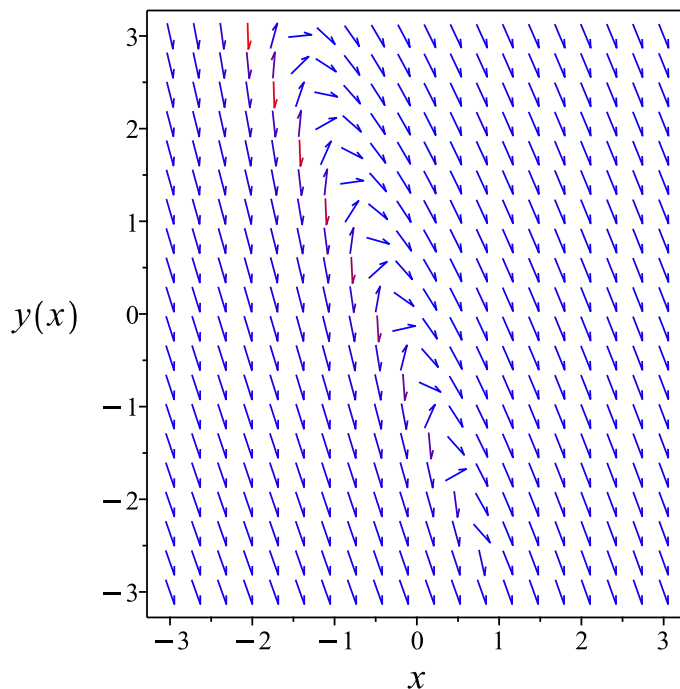


Figure 319: Slope field plot

Verification of solutions

$$\frac{\ln(5x^2 + (4y + 2)x + y^2 + 2y + 2)}{2} = c_1$$

Verified OK.

7.7.4 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \quad (A)$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \quad (\text{B})$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (\text{1A})$$

Therefore

$$\begin{aligned} (2x + y + 1) dy &= (-5x - 2y - 1) dx \\ (5x + 2y + 1) dx + (2x + y + 1) dy &= 0 \end{aligned} \quad (\text{2A})$$

Comparing (1A) and (2A) shows that

$$\begin{aligned} M(x, y) &= 5x + 2y + 1 \\ N(x, y) &= 2x + y + 1 \end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned} \frac{\partial M}{\partial y} &= \frac{\partial}{\partial y} (5x + 2y + 1) \\ &= 2 \end{aligned}$$

And

$$\begin{aligned}\frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(2x + y + 1) \\ &= 2\end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \quad (1)$$

$$\frac{\partial \phi}{\partial y} = N \quad (2)$$

Integrating (1) w.r.t. x gives

$$\begin{aligned}\int \frac{\partial \phi}{\partial x} dx &= \int M dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int 5x + 2y + 1 dx \\ \phi &= \frac{x(5x + 4y + 2)}{2} + f(y)\end{aligned} \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = 2x + f'(y) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = 2x + y + 1$. Therefore equation (4) becomes

$$2x + y + 1 = 2x + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = y + 1$$

Integrating the above w.r.t y gives

$$\begin{aligned}\int f'(y) dy &= \int (y + 1) dy \\ f(y) &= \frac{1}{2}y^2 + y + c_1\end{aligned}$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = \frac{x(5x + 4y + 2)}{2} + \frac{y^2}{2} + y + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = \frac{x(5x + 4y + 2)}{2} + \frac{y^2}{2} + y$$

Summary

The solution(s) found are the following

$$\frac{x(5x + 4y + 2)}{2} + \frac{y^2}{2} + y = c_1 \quad (1)$$

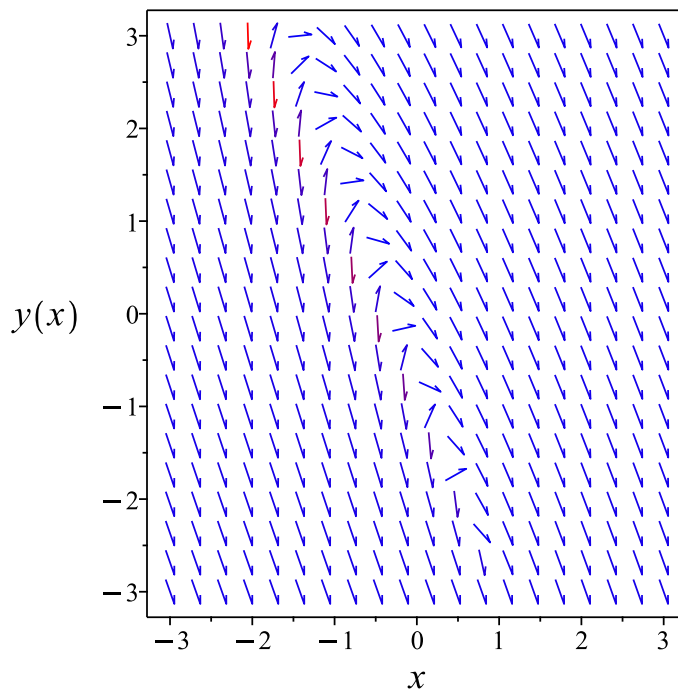


Figure 320: Slope field plot

Verification of solutions

$$\frac{x(5x + 4y + 2)}{2} + \frac{y^2}{2} + y = c_1$$

Verified OK.

7.7.5 Maple step by step solution

Let's solve

$$2y + (2x + y + 1) y' = -5x - 1$$

- Highest derivative means the order of the ODE is 1

y'

- Check if ODE is exact

- ODE is exact if the lhs is the total derivative of a C^2 function

$$F'(x, y) = 0$$

- Compute derivative of lhs

$$F'(x, y) + \left(\frac{\partial}{\partial y} F(x, y) \right) y' = 0$$

- Evaluate derivatives

$$2 = 2$$

- Condition met, ODE is exact

- Exact ODE implies solution will be of this form

$$\left[F(x, y) = c_1, M(x, y) = F'(x, y), N(x, y) = \frac{\partial}{\partial y} F(x, y) \right]$$

- Solve for $F(x, y)$ by integrating $M(x, y)$ with respect to x

$$F(x, y) = \int (5x + 2y + 1) dx + f_1(y)$$

- Evaluate integral

$$F(x, y) = \frac{5x^2}{2} + 2xy + x + f_1(y)$$

- Take derivative of $F(x, y)$ with respect to y

$$N(x, y) = \frac{\partial}{\partial y} F(x, y)$$

- Compute derivative

$$2x + y + 1 = 2x + \frac{d}{dy} f_1(y)$$

- Isolate for $\frac{d}{dy} f_1(y)$

$$\frac{d}{dy} f_1(y) = y + 1$$

- Solve for $f_1(y)$

$$f_1(y) = \frac{1}{2}y^2 + y$$

- Substitute $f_1(y)$ into equation for $F(x, y)$

$$F(x, y) = \frac{5}{2}x^2 + 2xy + x + \frac{1}{2}y^2 + y$$

- Substitute $F(x, y)$ into the solution of the ODE

$$\frac{5}{2}x^2 + 2xy + x + \frac{1}{2}y^2 + y = c_1$$

- Solve for y

$$\{y = -2x - 1 - \sqrt{-x^2 + 2c_1 + 2x + 1}, y = -2x - 1 + \sqrt{-x^2 + 2c_1 + 2x + 1}\}$$

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
trying separable
trying inverse linear
trying homogeneous types:
trying homogeneous C
trying homogeneous types:
trying homogeneous D
<- homogeneous successful
<- homogeneous successful`

```

✓ Solution by Maple

Time used: 0.562 (sec). Leaf size: 32

```
dsolve((5*x+2*y(x)+1)+(2*x+y(x)+1)*diff(y(x),x)=0,y(x), singsol=all)
```

$$y(x) = \frac{-\sqrt{-(-1+x)^2 c_1^2 + 1} + (-2x - 1) c_1}{c_1}$$

✓ Solution by Mathematica

Time used: 0.134 (sec). Leaf size: 53

```
DSolve[(5*x+2*y[x]+1)+(2*x+y[x]+1)*y'[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow -\sqrt{-x^2 + 2x + 1 + c_1} - 2x - 1$$

$$y(x) \rightarrow \sqrt{-x^2 + 2x + 1 + c_1} - 2x - 1$$

7.8 problem 8

7.8.1 Solving as first order ode lie symmetry calculated ode 1639

Internal problem ID [11706]

Internal file name [OUTPUT/11715_Thursday_April_11_2024_08_48_44_PM_93206069/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, Section 2.4. Special integrating factors and transformations. Exercises page 67

Problem number: 8.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**first_order_ode_lie_symmetry_calculated**"

Maple gives the following as the ode type

```
[[_homogeneous, `class C`], _rational, [_Abel, `2nd type`, `class A`]]
```

$$-y - (6x - 2y - 3)y' = -3x - 1$$

7.8.1 Solving as first order ode lie symmetry calculated ode

Writing the ode as

$$y' = \frac{-3x + y - 1}{-6x + 2y + 3}$$
$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is not in the lookup table. To determine ξ, η then (A) is solved using ansatz. Making bivariate polynomials of degree 1 to use as anstaz gives

$$\xi = xa_2 + ya_3 + a_1 \quad (\text{1E})$$

$$\eta = xb_2 + yb_3 + b_1 \quad (\text{2E})$$

Where the unknown coefficients are

$$\{a_1, a_2, a_3, b_1, b_2, b_3\}$$

Substituting equations (1E,2E) and ω into (A) gives

$$\begin{aligned} b_2 + \frac{(-3x + y - 1)(b_3 - a_2)}{-6x + 2y + 3} - \frac{(-3x + y - 1)^2 a_3}{(-6x + 2y + 3)^2} \\ - \left(-\frac{3}{-6x + 2y + 3} + \frac{-18x + 6y - 6}{(-6x + 2y + 3)^2} \right) (xa_2 + ya_3 + a_1) \\ - \left(\frac{1}{-6x + 2y + 3} - \frac{2(-3x + y - 1)}{(-6x + 2y + 3)^2} \right) (xb_2 + yb_3 + b_1) = 0 \end{aligned} \quad (5E)$$

Putting the above in normal form gives

$$\frac{18x^2a_2 + 9x^2a_3 - 36x^2b_2 - 18x^2b_3 - 12xya_2 - 6xya_3 + 24xyb_2 + 12xyb_3 + 2y^2a_2 + y^2a_3 - 4y^2b_2 - 2y^2b_3}{(6x - 2y + 3)^2} = 0$$

Setting the numerator to zero gives

$$\begin{aligned} -18x^2a_2 - 9x^2a_3 + 36x^2b_2 + 18x^2b_3 + 12xya_2 + 6xya_3 - 24xyb_2 - 12xyb_3 \\ - 2y^2a_2 - y^2a_3 + 4y^2b_2 + 2y^2b_3 + 18xa_2 - 6xa_3 - 41xb_2 - 3xb_3 - ya_2 \\ + 17ya_3 + 12yb_2 - 4yb_3 + 15a_1 + 3a_2 - a_3 - 5b_1 + 9b_2 - 3b_3 = 0 \end{aligned} \quad (6E)$$

Looking at the above PDE shows the following are all the terms with $\{x, y\}$ in them.

$$\{x, y\}$$

The following substitution is now made to be able to collect on all terms with $\{x, y\}$ in them

$$\{x = v_1, y = v_2\}$$

The above PDE (6E) now becomes

$$\begin{aligned} -18a_2v_1^2 + 12a_2v_1v_2 - 2a_2v_2^2 - 9a_3v_1^2 + 6a_3v_1v_2 - a_3v_2^2 + 36b_2v_1^2 - 24b_2v_1v_2 \\ + 4b_2v_2^2 + 18b_3v_1^2 - 12b_3v_1v_2 + 2b_3v_2^2 + 18a_2v_1 - a_2v_2 - 6a_3v_1 + 17a_3v_2 \\ - 41b_2v_1 + 12b_2v_2 - 3b_3v_1 - 4b_3v_2 + 15a_1 + 3a_2 - a_3 - 5b_1 + 9b_2 - 3b_3 = 0 \end{aligned} \quad (7E)$$

Collecting the above on the terms v_i introduced, and these are

$$\{v_1, v_2\}$$

Equation (7E) now becomes

$$\begin{aligned} &(-18a_2 - 9a_3 + 36b_2 + 18b_3)v_1^2 + (12a_2 + 6a_3 - 24b_2 - 12b_3)v_1v_2 \\ &+ (18a_2 - 6a_3 - 41b_2 - 3b_3)v_1 + (-2a_2 - a_3 + 4b_2 + 2b_3)v_2^2 \\ &+ (-a_2 + 17a_3 + 12b_2 - 4b_3)v_2 + 15a_1 + 3a_2 - a_3 - 5b_1 + 9b_2 - 3b_3 = 0 \end{aligned} \quad (8E)$$

Setting each coefficients in (8E) to zero gives the following equations to solve

$$\begin{aligned} -18a_2 - 9a_3 + 36b_2 + 18b_3 &= 0 \\ -2a_2 - a_3 + 4b_2 + 2b_3 &= 0 \\ -a_2 + 17a_3 + 12b_2 - 4b_3 &= 0 \\ 12a_2 + 6a_3 - 24b_2 - 12b_3 &= 0 \\ 18a_2 - 6a_3 - 41b_2 - 3b_3 &= 0 \\ 15a_1 + 3a_2 - a_3 - 5b_1 + 9b_2 - 3b_3 &= 0 \end{aligned}$$

Solving the above equations for the unknowns gives

$$\begin{aligned} a_1 &= a_1 \\ a_2 &= 2b_2 \\ a_3 &= -\frac{2b_2}{3} \\ b_1 &= 3a_1 + \frac{10b_2}{3} \\ b_2 &= b_2 \\ b_3 &= -\frac{b_2}{3} \end{aligned}$$

Substituting the above solution in the anstaz (1E,2E) (using 1 as arbitrary value for any unknown in the RHS) gives

$$\begin{aligned} \xi &= 1 \\ \eta &= 3 \end{aligned}$$

Shifting is now applied to make $\xi = 0$ in order to simplify the rest of the computation

$$\begin{aligned}\eta &= \eta - \omega(x, y) \xi \\ &= 3 - \left(\frac{-3x + y - 1}{-6x + 2y + 3} \right) \xi \quad (1) \\ &= \frac{15x - 5y - 10}{6x - 2y - 3} \\ \xi &= 0\end{aligned}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \quad (1)$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y} \right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned}S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{15x-5y-10}{6x-2y-3}} dy\end{aligned}$$

Which results in

$$S = \frac{2y}{5} - \frac{\ln(-3x + y + 2)}{5}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = \frac{-3x + y - 1}{-6x + 2y + 3}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= -\frac{3}{15x - 5y - 10} \\ S_y &= \frac{2}{5} + \frac{1}{15x - 5y - 10} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = \frac{1}{5} \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = \frac{1}{5}$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = \frac{R}{5} + c_1 \quad (4)$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$\frac{2y}{5} - \frac{\ln(-3x + y + 2)}{5} = \frac{x}{5} + c_1$$

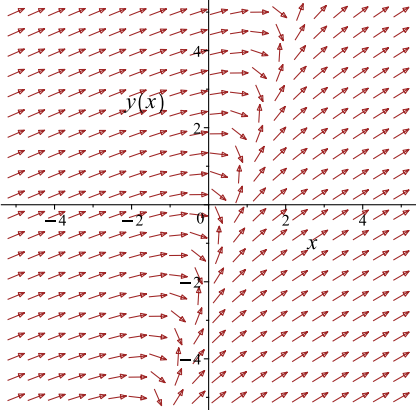
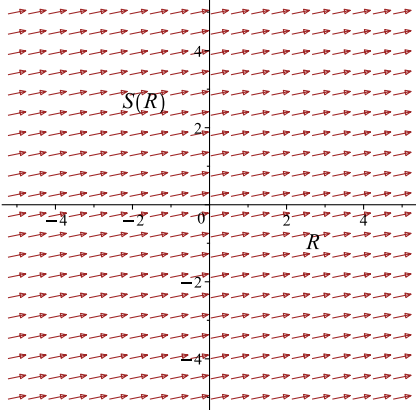
Which simplifies to

$$\frac{2y}{5} - \frac{\ln(-3x + y + 2)}{5} = \frac{x}{5} + c_1$$

Which gives

$$y = -\frac{\text{LambertW}(-2e^{5x-4-5c_1})}{2} + 3x - 2$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = \frac{-3x+y-1}{-6x+2y+3}$ 	$R = x$ $S = \frac{2y}{5} - \frac{\ln(-3x+y+1)}{5}$	$\frac{dS}{dR} = \frac{1}{5}$ 

Summary

The solution(s) found are the following

$$y = -\frac{\text{LambertW}(-2e^{5x-4-5c_1})}{2} + 3x - 2 \quad (1)$$

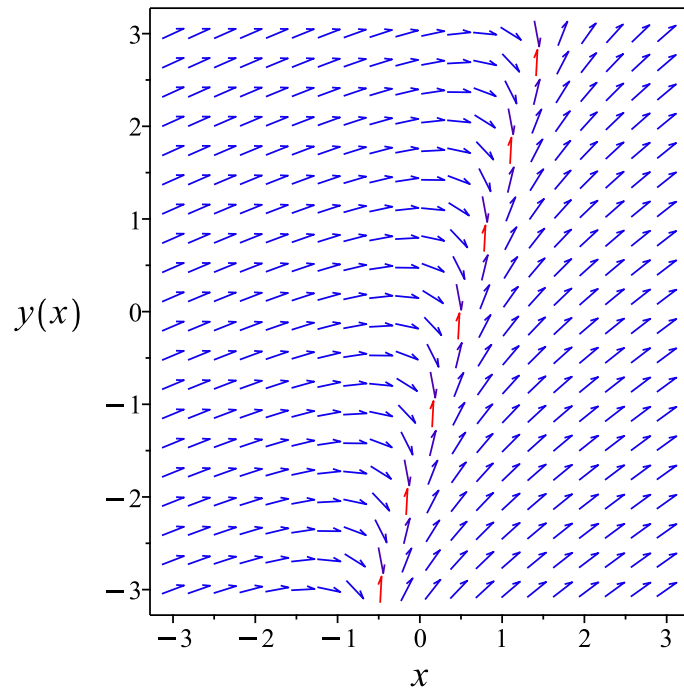


Figure 321: Slope field plot

Verification of solutions

$$y = -\frac{\text{LambertW}(-2e^{5x-4-5c_1})}{2} + 3x - 2$$

Verified OK.

Maple trace

```
`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
trying separable
trying inverse linear
trying homogeneous types:
trying homogeneous C
1st order, trying the canonical coordinates of the invariance group
  -> Calling odsolve with the ODE`, diff(y(x), x) = 3, y(x)`      *** Sublevel 2 ***
      Methods for first order ODEs:
      --- Trying classification methods ---
      trying a quadrature
      trying 1st order linear
      <- 1st order linear successful
<- 1st order, canonical coordinates successful
<- homogeneous successful`
```

✓ Solution by Maple

Time used: 0.031 (sec). Leaf size: 23

```
dsolve((3*x-y(x)+1)-(6*x-2*y(x)-3)*diff(y(x),x)=0,y(x), singsol=all)
```

$$y(x) = -\frac{\text{LambertW}(-2e^{5x-4-5c_1})}{2} + 3x - 2$$

✓ Solution by Mathematica

Time used: 3.097 (sec). Leaf size: 35

```
DSolve[(3*x-y[x]+1)-(6*x-2*y[x]-3)*y'[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow -\frac{1}{2}W(-e^{5x-1+c_1}) + 3x - 2$$
$$y(x) \rightarrow 3x - 2$$

7.9 problem 9

7.9.1 Solving as homogeneousTypeMapleC ode 1647

7.9.2 Solving as first order ode lie symmetry calculated ode 1650

Internal problem ID [11707]

Internal file name [OUTPUT/11716_Thursday_April_11_2024_08_48_45_PM_49666120/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 2, Section 2.4. Special integrating factors and transformations. Exercises page 67

Problem number: 9.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"homogeneousTypeMapleC", "first_order_ode_lie_symmetry_calculated"**

Maple gives the following as the ode type

```
[[_homogeneous, `class C`], _rational, [_Abel, `2nd type`, `class A`]]
```

$$-2y + (2x + y - 1)y' = -x + 3$$

7.9.1 Solving as homogeneousTypeMapleC ode

Let $Y = y + y_0$ and $X = x + x_0$ then the above is transformed to new ode in $Y(X)$

$$\frac{d}{dX}Y(X) = \frac{-X - x_0 + 2Y(X) + 2y_0 + 3}{2X + 2x_0 + Y(X) + y_0 - 1}$$

Solving for possible values of x_0 and y_0 which makes the above ode a homogeneous ode results in

$$\begin{aligned}x_0 &= 1 \\y_0 &= -1\end{aligned}$$

Using these values now it is possible to easily solve for $Y(X)$. The above ode now becomes

$$\frac{d}{dX}Y(X) = \frac{-X + 2Y(X)}{2X + Y(X)}$$

In canonical form, the ODE is

$$\begin{aligned} Y' &= F(X, Y) \\ &= \frac{-X + 2Y}{2X + Y} \end{aligned} \quad (1)$$

An ode of the form $Y' = \frac{M(X, Y)}{N(X, Y)}$ is called homogeneous if the functions $M(X, Y)$ and $N(X, Y)$ are both homogeneous functions and of the same order. Recall that a function $f(X, Y)$ is homogeneous of order n if

$$f(t^n X, t^n Y) = t^n f(X, Y)$$

In this case, it can be seen that both $M = -X + 2Y$ and $N = 2X + Y$ are both homogeneous and of the same order $n = 1$. Therefore this is a homogeneous ode. Since this ode is homogeneous, it is converted to separable ODE using the substitution $u = \frac{Y}{X}$, or $Y = uX$. Hence

$$\frac{dY}{dX} = \frac{du}{dX}X + u$$

Applying the transformation $Y = uX$ to the above ODE in (1) gives

$$\begin{aligned} \frac{du}{dX}X + u &= \frac{2u - 1}{u + 2} \\ \frac{du}{dX} &= \frac{\frac{2u(X)-1}{u(X)+2} - u(X)}{X} \end{aligned}$$

Or

$$\frac{d}{dX}u(X) - \frac{\frac{2u(X)-1}{u(X)+2} - u(X)}{X} = 0$$

Or

$$\left(\frac{d}{dX}u(X)\right)Xu(X) + 2\left(\frac{d}{dX}u(X)\right)X + u(X)^2 + 1 = 0$$

Or

$$X(u(X) + 2)\left(\frac{d}{dX}u(X)\right) + u(X)^2 + 1 = 0$$

Which is now solved as separable in $u(X)$. Which is now solved in $u(X)$. In canonical form the ODE is

$$\begin{aligned} u' &= F(X, u) \\ &= f(X)g(u) \\ &= -\frac{u^2 + 1}{X(u + 2)} \end{aligned}$$

Where $f(X) = -\frac{1}{X}$ and $g(u) = \frac{u^2+1}{u+2}$. Integrating both sides gives

$$\frac{1}{\frac{u^2+1}{u+2}} du = -\frac{1}{X} dX$$

$$\int \frac{1}{\frac{u^2+1}{u+2}} du = \int -\frac{1}{X} dX$$

$$\frac{\ln(u^2 + 1)}{2} + 2 \arctan(u) = -\ln(X) + c_2$$

The solution is

$$\frac{\ln(u(X)^2 + 1)}{2} + 2 \arctan(u(X)) + \ln(X) - c_2 = 0$$

Now u in the above solution is replaced back by Y using $u = \frac{Y}{X}$ which results in the solution

$$\frac{\ln\left(\frac{Y(X)^2}{X^2} + 1\right)}{2} + 2 \arctan\left(\frac{Y(X)}{X}\right) + \ln(X) - c_2 = 0$$

Using the solution for $Y(X)$

$$\frac{\ln\left(\frac{Y(X)^2}{X^2} + 1\right)}{2} + 2 \arctan\left(\frac{Y(X)}{X}\right) + \ln(X) - c_2 = 0$$

And replacing back terms in the above solution using

$$Y = y + y_0$$

$$X = x + x_0$$

Or

$$Y = y - 1$$

$$X = 1 + x$$

Then the solution in y becomes

$$\frac{\ln\left(\frac{(y+1)^2}{(x-1)^2} + 1\right)}{2} + 2 \arctan\left(\frac{y+1}{x-1}\right) + \ln(x-1) - c_2 = 0$$

Summary

The solution(s) found are the following

$$\frac{\ln\left(\frac{(y+1)^2}{(x-1)^2} + 1\right)}{2} + 2 \arctan\left(\frac{y+1}{x-1}\right) + \ln(x-1) - c_2 = 0 \quad (1)$$

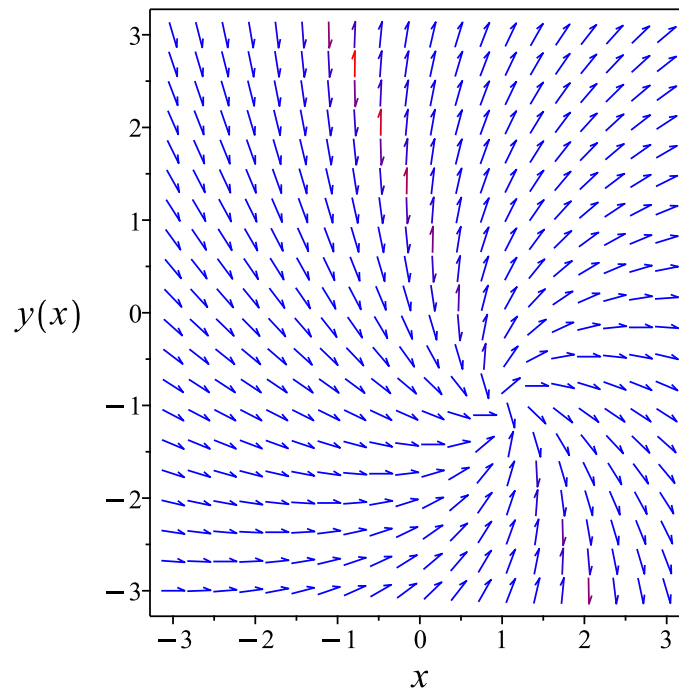


Figure 322: Slope field plot

Verification of solutions

$$\frac{\ln\left(\frac{(y+1)^2}{(x-1)^2} + 1\right)}{2} + 2 \arctan\left(\frac{y+1}{x-1}\right) + \ln(x-1) - c_2 = 0$$

Verified OK.

7.9.2 Solving as first order ode lie symmetry calculated ode

Writing the ode as

$$y' = \frac{-x + 2y + 3}{2x + y - 1}$$
$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is not in the lookup table. To determine ξ, η then (A) is solved using ansatz. Making bivariate polynomials of degree 1 to use as anstaz gives

$$\xi = xa_2 + ya_3 + a_1 \quad (\text{1E})$$

$$\eta = xb_2 + yb_3 + b_1 \quad (\text{2E})$$

Where the unknown coefficients are

$$\{a_1, a_2, a_3, b_1, b_2, b_3\}$$

Substituting equations (1E,2E) and ω into (A) gives

$$\begin{aligned} b_2 + \frac{(-x + 2y + 3)(b_3 - a_2)}{2x + y - 1} - \frac{(-x + 2y + 3)^2 a_3}{(2x + y - 1)^2} \\ - \left(-\frac{1}{2x + y - 1} - \frac{2(-x + 2y + 3)}{(2x + y - 1)^2} \right) (xa_2 + ya_3 + a_1) \\ - \left(\frac{2}{2x + y - 1} - \frac{-x + 2y + 3}{(2x + y - 1)^2} \right) (xb_2 + yb_3 + b_1) = 0 \end{aligned} \quad (\text{5E})$$

Putting the above in normal form gives

$$\frac{2x^2a_2 - x^2a_3 - x^2b_2 - 2x^2b_3 + 2xya_2 + 4xya_3 + 4xyb_2 - 2xyb_3 - 2y^2a_2 + y^2a_3 + y^2b_2 + 2y^2b_3 - 2xa_2 + 6xa_3 - 5xb_1 + xb_2 + 7xb_3 + 5ya_1 - ya_2 - 7ya_3 - 2yb_2 + 6yb_3 + 5a_1 + 3a_2 - 9a_3 + 5b_1 + b_2 - 3b_3}{(2x + y - 1)^2} = 0$$

Setting the numerator to zero gives

$$\begin{aligned} 2x^2a_2 - x^2a_3 - x^2b_2 - 2x^2b_3 + 2xya_2 + 4xya_3 + 4xyb_2 - 2xyb_3 - 2y^2a_2 \\ + y^2a_3 + y^2b_2 + 2y^2b_3 - 2xa_2 + 6xa_3 - 5xb_1 + xb_2 + 7xb_3 + 5ya_1 \\ - ya_2 - 7ya_3 - 2yb_2 + 6yb_3 + 5a_1 + 3a_2 - 9a_3 + 5b_1 + b_2 - 3b_3 = 0 \end{aligned} \quad (\text{6E})$$

Looking at the above PDE shows the following are all the terms with $\{x, y\}$ in them.

$$\{x, y\}$$

The following substitution is now made to be able to collect on all terms with $\{x, y\}$ in them

$$\{x = v_1, y = v_2\}$$

The above PDE (6E) now becomes

$$\begin{aligned} &2a_2v_1^2 + 2a_2v_1v_2 - 2a_2v_2^2 - a_3v_1^2 + 4a_3v_1v_2 + a_3v_2^2 - b_2v_1^2 + 4b_2v_1v_2 + b_2v_2^2 \\ &- 2b_3v_1^2 - 2b_3v_1v_2 + 2b_3v_2^2 + 5a_1v_2 - 2a_2v_1 - a_2v_2 + 6a_3v_1 - 7a_3v_2 - 5b_1v_1 \\ &+ b_2v_1 - 2b_2v_2 + 7b_3v_1 + 6b_3v_2 + 5a_1 + 3a_2 - 9a_3 + 5b_1 + b_2 - 3b_3 = 0 \end{aligned} \quad (7E)$$

Collecting the above on the terms v_i introduced, and these are

$$\{v_1, v_2\}$$

Equation (7E) now becomes

$$\begin{aligned} &(2a_2 - a_3 - b_2 - 2b_3)v_1^2 + (2a_2 + 4a_3 + 4b_2 - 2b_3)v_1v_2 \\ &+ (-2a_2 + 6a_3 - 5b_1 + b_2 + 7b_3)v_1 + (-2a_2 + a_3 + b_2 + 2b_3)v_2^2 \\ &+ (5a_1 - a_2 - 7a_3 - 2b_2 + 6b_3)v_2 + 5a_1 + 3a_2 - 9a_3 + 5b_1 + b_2 - 3b_3 = 0 \end{aligned} \quad (8E)$$

Setting each coefficients in (8E) to zero gives the following equations to solve

$$\begin{aligned} -2a_2 + a_3 + b_2 + 2b_3 &= 0 \\ 2a_2 - a_3 - b_2 - 2b_3 &= 0 \\ 2a_2 + 4a_3 + 4b_2 - 2b_3 &= 0 \\ 5a_1 - a_2 - 7a_3 - 2b_2 + 6b_3 &= 0 \\ -2a_2 + 6a_3 - 5b_1 + b_2 + 7b_3 &= 0 \\ 5a_1 + 3a_2 - 9a_3 + 5b_1 + b_2 - 3b_3 &= 0 \end{aligned}$$

Solving the above equations for the unknowns gives

$$\begin{aligned} a_1 &= -b_2 - b_3 \\ a_2 &= b_3 \\ a_3 &= -b_2 \\ b_1 &= -b_2 + b_3 \\ b_2 &= b_2 \\ b_3 &= b_3 \end{aligned}$$

Substituting the above solution in the anstaz (1E,2E) (using 1 as arbitrary value for any unknown in the RHS) gives

$$\begin{aligned}\xi &= x - 1 \\ \eta &= y + 1\end{aligned}$$

Shifting is now applied to make $\xi = 0$ in order to simplify the rest of the computation

$$\begin{aligned}\eta &= \eta - \omega(x, y) \xi \\ &= y + 1 - \left(\frac{-x + 2y + 3}{2x + y - 1} \right) (x - 1) \\ &= \frac{x^2 + y^2 - 2x + 2y + 2}{2x + y - 1} \\ \xi &= 0\end{aligned}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \quad (1)$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y} \right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned}S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{x^2 + y^2 - 2x + 2y + 2}{2x + y - 1}} dy\end{aligned}$$

Which results in

$$S = \frac{\ln(x^2 + y^2 - 2x + 2y + 2)}{2} + 2 \arctan\left(\frac{2y + 2}{2x - 2}\right)$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y) S_y}{R_x + \omega(x, y) R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = \frac{-x + 2y + 3}{2x + y - 1}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= \frac{x - 2y - 3}{x^2 + y^2 - 2x + 2y + 2} \\ S_y &= \frac{2x + y - 1}{x^2 + y^2 - 2x + 2y + 2} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 0 \tag{2A}$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 0$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = c_1 \tag{4}$$

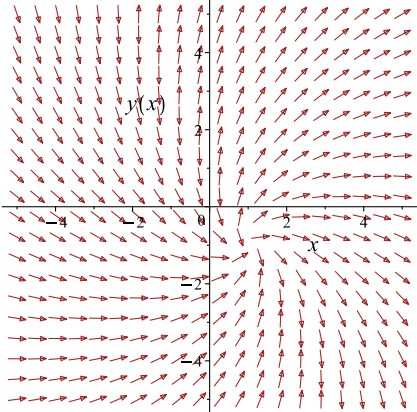
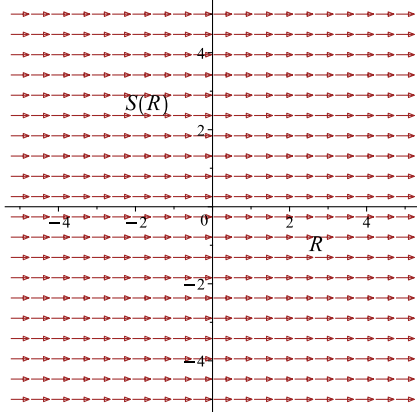
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$\frac{\ln(y^2 + x^2 + 2y - 2x + 2)}{2} + 2 \arctan\left(\frac{y + 1}{x - 1}\right) = c_1$$

Which simplifies to

$$\frac{\ln(y^2 + x^2 + 2y - 2x + 2)}{2} + 2 \arctan\left(\frac{y + 1}{x - 1}\right) = c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = \frac{-x+2y+3}{2x+y-1}$ 	$R = x$ $S = \frac{\ln(x^2 + y^2 - 2x + 2)}{2}$	$\frac{dS}{dR} = 0$ 

Summary

The solution(s) found are the following

$$\frac{\ln(y^2 + x^2 + 2y - 2x + 2)}{2} + 2 \arctan\left(\frac{y+1}{x-1}\right) = c_1 \quad (1)$$

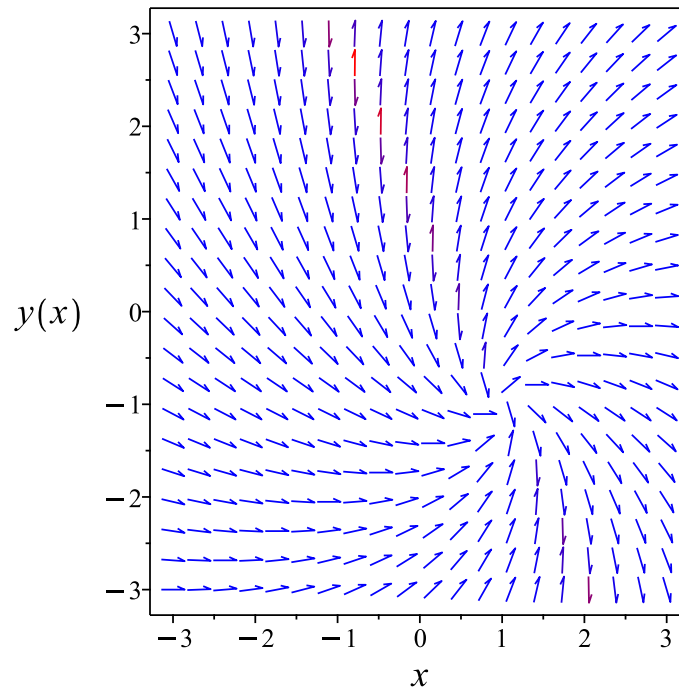


Figure 323: Slope field plot

Verification of solutions

$$\frac{\ln(y^2 + x^2 + 2y - 2x + 2)}{2} + 2 \arctan\left(\frac{y+1}{x-1}\right) = c_1$$

Verified OK.

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
trying Bernoulli  
trying separable  
trying inverse linear  
trying homogeneous types:  
trying homogeneous C  
trying homogeneous types:  
trying homogeneous D  
<- homogeneous successful  
<- homogeneous successful`
```

✓ Solution by Maple

Time used: 0.031 (sec). Leaf size: 31

```
dsolve((x-2*y(x)-3)+(2*x+y(x)-1)*diff(y(x),x)=0,y(x), singsol=all)
```

$$y(x) = -1 - \tan(\text{RootOf}(-4_Z + \ln(\sec(_Z)^2) + 2 \ln(-1 + x) + 2c_1))(-1 + x)$$

✓ Solution by Mathematica

Time used: 0.061 (sec). Leaf size: 66

```
DSolve[(x-2*y[x]-3)+(2*x+y[x]-1)*y'[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$\text{Solve} \left[32 \arctan \left(\frac{2y(x) - x + 3}{y(x) + 2x - 1} \right) + 8 \log \left(\frac{x^2 + y(x)^2 + 2y(x) - 2x + 2}{5(x - 1)^2} \right) + 16 \log(x - 1) + 5c_1 = 0, y(x) \right]$$

7.10 problem 10

7.10.1 Solving as homogeneousTypeMapleC ode 1658

7.10.2 Solving as first order ode lie symmetry calculated ode 1662

Internal problem ID [11708]

Internal file name [OUTPUT/11717_Thursday_April_11_2024_08_48_47_PM_9399003/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 2, Section 2.4. Special integrating factors and transformations. Exercises page 67

Problem number: 10.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"homogeneousTypeMapleC", "first_order_ode_lie_symmetry_calculated"**

Maple gives the following as the ode type

```
[[_homogeneous, `class C`], _rational, [_Abel, `2nd type`, `class A`]]
```

$$-4y - (x + 5y + 3)y' = -10x - 12$$

7.10.1 Solving as homogeneousTypeMapleC ode

Let $Y = y + y_0$ and $X = x + x_0$ then the above is transformed to new ode in $Y(X)$

$$\frac{d}{dX}Y(X) = -\frac{2(2Y(X) + 2y_0 - 5X - 5x_0 - 6)}{X + x_0 + 5Y(X) + 5y_0 + 3}$$

Solving for possible values of x_0 and y_0 which makes the above ode a homogeneous ode results in

$$x_0 = -\frac{4}{3}$$
$$y_0 = -\frac{1}{3}$$

Using these values now it is possible to easily solve for $Y(X)$. The above ode now becomes

$$\frac{d}{dX}Y(X) = -\frac{2(2Y(X) - 5X)}{X + 5Y(X)}$$

In canonical form, the ODE is

$$\begin{aligned} Y' &= F(X, Y) \\ &= -\frac{2(2Y - 5X)}{X + 5Y} \end{aligned} \quad (1)$$

An ode of the form $Y' = \frac{M(X, Y)}{N(X, Y)}$ is called homogeneous if the functions $M(X, Y)$ and $N(X, Y)$ are both homogeneous functions and of the same order. Recall that a function $f(X, Y)$ is homogeneous of order n if

$$f(t^n X, t^n Y) = t^n f(X, Y)$$

In this case, it can be seen that both $M = -4Y + 10X$ and $N = X + 5Y$ are both homogeneous and of the same order $n = 1$. Therefore this is a homogeneous ode. Since this ode is homogeneous, it is converted to separable ODE using the substitution $u = \frac{Y}{X}$, or $Y = uX$. Hence

$$\frac{dY}{dX} = \frac{du}{dX}X + u$$

Applying the transformation $Y = uX$ to the above ODE in (1) gives

$$\begin{aligned} \frac{du}{dX}X + u &= \frac{-4u + 10}{5u + 1} \\ \frac{du}{dX} &= \frac{\frac{-4u(X)+10}{5u(X)+1} - u(X)}{X} \end{aligned}$$

Or

$$\frac{d}{dX}u(X) - \frac{\frac{-4u(X)+10}{5u(X)+1} - u(X)}{X} = 0$$

Or

$$5\left(\frac{d}{dX}u(X)\right)Xu(X) + \left(\frac{d}{dX}u(X)\right)X + 5u(X)^2 + 5u(X) - 10 = 0$$

Or

$$-10 + (5u(X) + 1)X\left(\frac{d}{dX}u(X)\right) + 5u(X)^2 + 5u(X) = 0$$

Which is now solved as separable in $u(X)$. Which is now solved in $u(X)$. In canonical form the ODE is

$$\begin{aligned} u' &= F(X, u) \\ &= f(X)g(u) \\ &= -\frac{5(u^2 + u - 2)}{(5u + 1)X} \end{aligned}$$

Where $f(X) = -\frac{5}{X}$ and $g(u) = \frac{u^2+u-2}{5u+1}$. Integrating both sides gives

$$\frac{1}{\frac{u^2+u-2}{5u+1}} du = -\frac{5}{X} dX$$

$$\int \frac{1}{\frac{u^2+u-2}{5u+1}} du = \int -\frac{5}{X} dX$$

$$2 \ln(u-1) + 3 \ln(u+2) = -5 \ln(X) + c_2$$

Raising both side to exponential gives

$$e^{2\ln(u-1)+3\ln(u+2)} = e^{-5\ln(X)+c_2}$$

Which simplifies to

$$(u-1)^2 (u+2)^3 = \frac{c_3}{X^5}$$

Now u in the above solution is replaced back by Y using $u = \frac{Y}{X}$ which results in the solution

$$Y(X) = \text{RootOf}(8X^5 - 4X^4_Z - 10X^3_Z^2 + X^2_Z^3 + 4X_Z^4 + _Z^5 - c_3)$$

Using the solution for $Y(X)$

$$Y(X) = \text{RootOf}(8X^5 - 4X^4_Z - 10X^3_Z^2 + X^2_Z^3 + 4X_Z^4 + _Z^5 - c_3)$$

And replacing back terms in the above solution using

$$Y = y + y_0$$

$$X = x + x_0$$

Or

$$Y = y - \frac{1}{3}$$

$$X = x - \frac{4}{3}$$

Then the solution in y becomes

$$y + \frac{1}{3} = \text{RootOf}(243_Z^5 + (972x + 1296)_Z^4 + (243x^2 + 648x + 432)_Z^3 + (-2430x^3 - 9720x^2 - 12960x - 4320)_Z^2 + (2430x^3 + 9720x^2 + 12960x + 4320)_Z - c_3)$$

Summary

The solution(s) found are the following

$$y + \frac{1}{3} = \text{RootOf} \left((243_Z^5 + (972x + 1296)_Z^4 + (243x^2 + 648x + 432)_Z^3 \right. \\ \left. + (-2430x^3 - 9720x^2 - 12960x - 5760)_Z^2 \right. \\ \left. + (-972x^4 - 5184x^3 - 10368x^2 - 9216x - 3072)_Z + 1944x^5 + 12960x^4 \right. \\ \left. + 34560x^3 + 46080x^2 - 243c_3 + 30720x + 8192 \right)$$

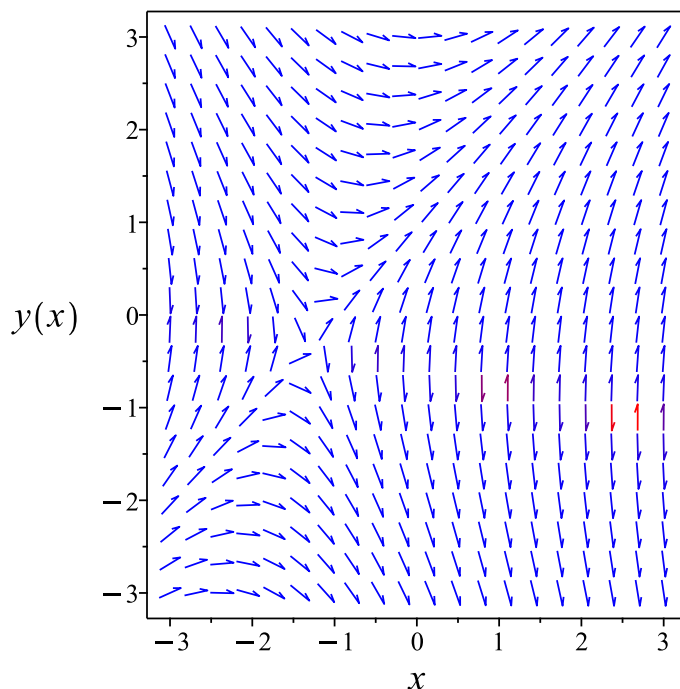


Figure 324: Slope field plot

Verification of solutions

$$y + \frac{1}{3} = \text{RootOf} \left((243_Z^5 + (972x + 1296)_Z^4 + (243x^2 + 648x + 432)_Z^3 \right. \\ \left. + (-2430x^3 - 9720x^2 - 12960x - 5760)_Z^2 \right. \\ \left. + (-972x^4 - 5184x^3 - 10368x^2 - 9216x - 3072)_Z + 1944x^5 + 12960x^4 \right. \\ \left. + 34560x^3 + 46080x^2 - 243c_3 + 30720x + 8192 \right)$$

Verified OK.

7.10.2 Solving as first order ode lie symmetry calculated ode

Writing the ode as

$$y' = -\frac{2(-5x + 2y - 6)}{x + 5y + 3}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is not in the lookup table. To determine ξ, η then (A) is solved using ansatz. Making bivariate polynomials of degree 1 to use as anstaz gives

$$\xi = xa_2 + ya_3 + a_1 \quad (\text{1E})$$

$$\eta = xb_2 + yb_3 + b_1 \quad (\text{2E})$$

Where the unknown coefficients are

$$\{a_1, a_2, a_3, b_1, b_2, b_3\}$$

Substituting equations (1E,2E) and ω into (A) gives

$$b_2 - \frac{2(-5x + 2y - 6)(b_3 - a_2)}{x + 5y + 3} - \frac{4(-5x + 2y - 6)^2 a_3}{(x + 5y + 3)^2}$$

$$- \left(\frac{10}{x + 5y + 3} + \frac{-10x + 4y - 12}{(x + 5y + 3)^2} \right) (xa_2 + ya_3 + a_1) \quad (\text{5E})$$

$$- \left(-\frac{4}{x + 5y + 3} + \frac{-50x + 20y - 60}{(x + 5y + 3)^2} \right) (xb_2 + yb_3 + b_1) = 0$$

Putting the above in normal form gives

$$\frac{10x^2a_2 + 100x^2a_3 - 55x^2b_2 - 10x^2b_3 + 100xya_2 - 80xya_3 - 10xyb_2 - 100xyb_3 - 20y^2a_2 + 70y^2a_3 - 25y^2b_2 - 10y^2b_3 - 60xa_2 - 240xa_3 + 54xb_1 + 78xb_2 + 42xb_3 - 54ya_1 - 48ya_2 + 78ya_3 + 30yb_2 + 120yb_3 - 18a_1 - 36a_2 - 144a_3 + 72b_1 + 9b_2 + 36b_3}{(x + 5y + 3)^3} = 0$$

Setting the numerator to zero gives

$$-10x^2a_2 - 100x^2a_3 + 55x^2b_2 + 10x^2b_3 - 100xya_2 + 80xya_3$$

$$+ 10xyb_2 + 100xyb_3 + 20y^2a_2 - 70y^2a_3 + 25y^2b_2 - 20y^2b_3 - 60xa_2 \quad (\text{6E})$$

$$- 240xa_3 + 54xb_1 + 78xb_2 + 42xb_3 - 54ya_1 - 48ya_2 + 78ya_3$$

$$+ 30yb_2 + 120yb_3 - 18a_1 - 36a_2 - 144a_3 + 72b_1 + 9b_2 + 36b_3 = 0$$

Looking at the above PDE shows the following are all the terms with $\{x, y\}$ in them.

$$\{x, y\}$$

The following substitution is now made to be able to collect on all terms with $\{x, y\}$ in them

$$\{x = v_1, y = v_2\}$$

The above PDE (6E) now becomes

$$\begin{aligned} & -10a_2v_1^2 - 100a_2v_1v_2 + 20a_2v_2^2 - 100a_3v_1^2 + 80a_3v_1v_2 - 70a_3v_2^2 \\ & + 55b_2v_1^2 + 10b_2v_1v_2 + 25b_2v_2^2 + 10b_3v_1^2 + 100b_3v_1v_2 - 20b_3v_2^2 - 54a_1v_2 \\ & - 60a_2v_1 - 48a_2v_2 - 240a_3v_1 + 78a_3v_2 + 54b_1v_1 + 78b_2v_1 + 30b_2v_2 \\ & + 42b_3v_1 + 120b_3v_2 - 18a_1 - 36a_2 - 144a_3 + 72b_1 + 9b_2 + 36b_3 = 0 \end{aligned} \quad (7E)$$

Collecting the above on the terms v_i introduced, and these are

$$\{v_1, v_2\}$$

Equation (7E) now becomes

$$\begin{aligned} & (-10a_2 - 100a_3 + 55b_2 + 10b_3)v_1^2 + (-100a_2 + 80a_3 + 10b_2 + 100b_3)v_1v_2 \\ & + (-60a_2 - 240a_3 + 54b_1 + 78b_2 + 42b_3)v_1 + (20a_2 - 70a_3 + 25b_2 - 20b_3)v_2^2 \\ & + (-54a_1 - 48a_2 + 78a_3 + 30b_2 + 120b_3)v_2 - 18a_1 \\ & - 36a_2 - 144a_3 + 72b_1 + 9b_2 + 36b_3 = 0 \end{aligned} \quad (8E)$$

Setting each coefficients in (8E) to zero gives the following equations to solve

$$\begin{aligned} -100a_2 + 80a_3 + 10b_2 + 100b_3 &= 0 \\ -10a_2 - 100a_3 + 55b_2 + 10b_3 &= 0 \\ 20a_2 - 70a_3 + 25b_2 - 20b_3 &= 0 \\ -54a_1 - 48a_2 + 78a_3 + 30b_2 + 120b_3 &= 0 \\ -60a_2 - 240a_3 + 54b_1 + 78b_2 + 42b_3 &= 0 \\ -18a_1 - 36a_2 - 144a_3 + 72b_1 + 9b_2 + 36b_3 &= 0 \end{aligned}$$

Solving the above equations for the unknowns gives

$$\begin{aligned} a_1 &= -9a_3 + 4b_1 \\ a_2 &= -7a_3 + 3b_1 \\ a_3 &= a_3 \\ b_1 &= b_1 \\ b_2 &= 2a_3 \\ b_3 &= -8a_3 + 3b_1 \end{aligned}$$

Substituting the above solution in the ansatz (1E,2E) (using 1 as arbitrary value for any unknown in the RHS) gives

$$\begin{aligned} \xi &= 4 + 3x \\ \eta &= 3y + 1 \end{aligned}$$

Shifting is now applied to make $\xi = 0$ in order to simplify the rest of the computation

$$\begin{aligned} \eta &= \eta - \omega(x, y) \xi \\ &= 3y + 1 - \left(-\frac{2(-5x + 2y - 6)}{x + 5y + 3} \right) (4 + 3x) \\ &= \frac{-30x^2 + 15xy + 15y^2 - 75x + 30y - 45}{x + 5y + 3} \\ \xi &= 0 \end{aligned}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \quad (1)$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y} \right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{-30x^2 + 15xy + 15y^2 - 75x + 30y - 45}{x + 5y + 3}} dy \end{aligned}$$

Which results in

$$S = \frac{\ln(2x + y + 3)}{5} + \frac{2 \ln(y - 1 - x)}{15}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{2(-5x + 2y - 6)}{x + 5y + 3}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= \frac{2}{10x + 5y + 15} + \frac{2}{15x - 15y + 15} \\ S_y &= \frac{-x - 5y - 3}{15(2x + y + 3)(-y + 1 + x)} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 0 \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 0$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = c_1 \quad (4)$$

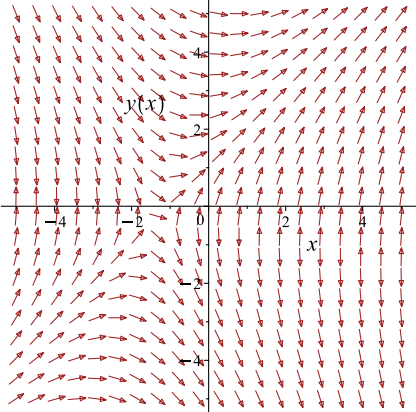
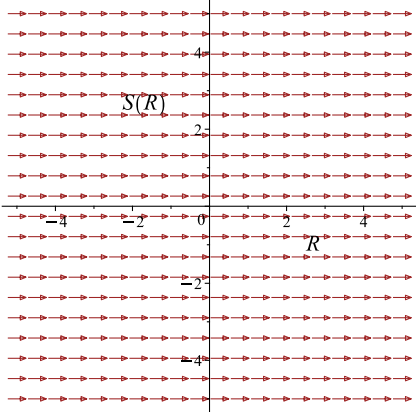
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$\frac{\ln(2x + y + 3)}{5} + \frac{2 \ln(y - 1 - x)}{15} = c_1$$

Which simplifies to

$$\frac{\ln(2x + y + 3)}{5} + \frac{2 \ln(y - 1 - x)}{15} = c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{2(-5x+2y-6)}{x+5y+3}$ 	$R = x$ $S = \frac{\ln(2x + y + 3)}{5} + \frac{2 \ln(y - 1 - x)}{15}$	$\frac{dS}{dR} = 0$ 

Summary

The solution(s) found are the following

$$\frac{\ln(2x + y + 3)}{5} + \frac{2 \ln(y - 1 - x)}{15} = c_1 \tag{1}$$

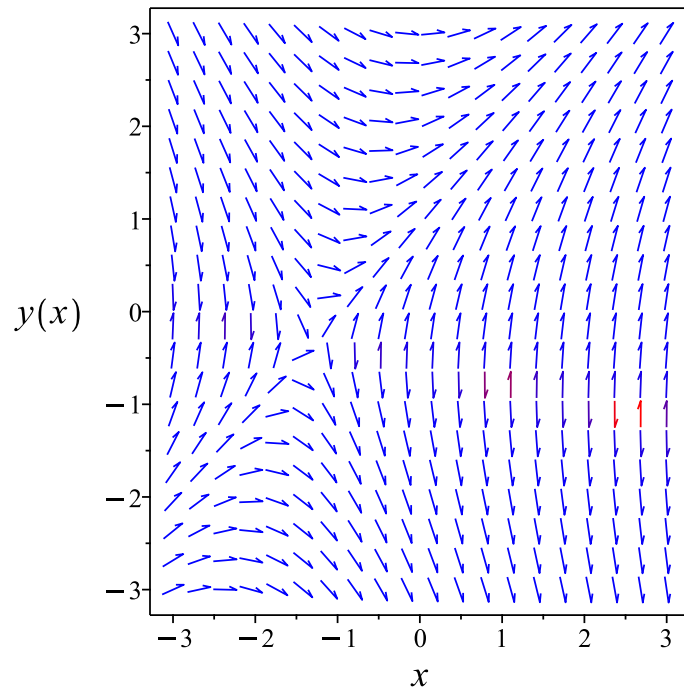


Figure 325: Slope field plot

Verification of solutions

$$\frac{\ln(2x + y + 3)}{5} + \frac{2 \ln(y - 1 - x)}{15} = c_1$$

Verified OK.

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
trying Bernoulli  
trying separable  
trying inverse linear  
trying homogeneous types:  
trying homogeneous C  
trying homogeneous types:  
trying homogeneous D  
<- homogeneous successful  
<- homogeneous successful`
```

✓ Solution by Maple

Time used: 0.859 (sec). Leaf size: 129

```
dsolve((10*x-4*y(x)+12)-(x+5*y(x)+3)*diff(y(x),x)=0,y(x), singsol=all)
```

$y(x)$

$$= \frac{(-3x - 4) \text{RootOf}(-1 + (243c_1x^5 + 1620x^4c_1 + 4320c_1x^3 + 5760c_1x^2 + 3840c_1x + 1024c_1)Z^{25} + (14 - 2x - 3))}{-2x - 3}$$

✓ Solution by Mathematica

Time used: 60.443 (sec). Leaf size: 3061

```
DSolve[(10*x-4*y[x]+12)-(x+5*y[x]+3)*y'[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

Too large to display

7.11 problem 11

7.11.1 Existence and uniqueness analysis	1670
7.11.2 Solving as differentialType ode	1670
7.11.3 Solving as homogeneousTypeMapleC ode	1672
7.11.4 Solving as first order ode lie symmetry calculated ode	1676
7.11.5 Solving as exact ode	1681
7.11.6 Maple step by step solution	1684

Internal problem ID [11709]

Internal file name [OUTPUT/11718_Thursday_April_11_2024_08_48_50_PM_63010928/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, Section 2.4. Special integrating factors and transformations. Exercises page 67

Problem number: 11.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact", "differentialType", "homogeneousTypeMapleC", "first_order_ode_lie_symmetry_calculated"

Maple gives the following as the ode type

```
[[_homogeneous, `class C`], _exact, _rational, [_Abel, `2nd type`, `class A`]]
```

$$4y + (4x + 2y + 2)y' = -6x - 1$$

With initial conditions

$$\left[y\left(\frac{1}{2}\right) = 3 \right]$$

7.11.1 Existence and uniqueness analysis

This is non linear first order ODE. In canonical form it is written as

$$\begin{aligned}y' &= f(x, y) \\ &= -\frac{6x + 4y + 1}{2(2x + y + 1)}\end{aligned}$$

The x domain of $f(x, y)$ when $y = 3$ is

$$\{x < -2 \vee -2 < x\}$$

And the point $x_0 = \frac{1}{2}$ is inside this domain. The y domain of $f(x, y)$ when $x = \frac{1}{2}$ is

$$\{y < -2 \vee -2 < y\}$$

And the point $y_0 = 3$ is inside this domain. Now we will look at the continuity of

$$\begin{aligned}\frac{\partial f}{\partial y} &= \frac{\partial}{\partial y} \left(-\frac{6x + 4y + 1}{2(2x + y + 1)} \right) \\ &= -\frac{2}{2x + y + 1} + \frac{6x + 4y + 1}{2(2x + y + 1)^2}\end{aligned}$$

The x domain of $\frac{\partial f}{\partial y}$ when $y = 3$ is

$$\{x < -2 \vee -2 < x\}$$

And the point $x_0 = \frac{1}{2}$ is inside this domain. The y domain of $\frac{\partial f}{\partial y}$ when $x = \frac{1}{2}$ is

$$\{y < -2 \vee -2 < y\}$$

And the point $y_0 = 3$ is inside this domain. Therefore solution exists and is unique.

7.11.2 Solving as differentialType ode

Writing the ode as

$$y' = \frac{-6x - 4y - 1}{4x + 2y + 2} \tag{1}$$

Which becomes

$$(2y + 2) dy = (-4x) dy + (-6x - 4y - 1) dx \tag{2}$$

But the RHS is complete differential because

$$(-4x) dy + (-6x - 4y - 1) dx = d(-3x^2 - 4xy - x)$$

Hence (2) becomes

$$(2y + 2) dy = d(-3x^2 - 4xy - x)$$

Integrating both sides gives gives these solutions

$$y = -2x - 1 + \sqrt{x^2 + c_1 + 3x + 1} + c_1$$

$$y = -2x - 1 - \sqrt{x^2 + c_1 + 3x + 1} + c_1$$

Initial conditions are used to solve for c_1 . Substituting $x = \frac{1}{2}$ and $y = 3$ in the above solution gives an equation to solve for the constant of integration.

$$3 = -2 - \frac{\sqrt{11 + 4c_1}}{2} + c_1$$

$$c_1 = \frac{11}{2} + 2\sqrt{2}$$

Substituting c_1 found above in the general solution gives

$$y = -2x + \frac{9}{2} - \frac{\sqrt{4x^2 + 26 + 8\sqrt{2} + 12x}}{2} + 2\sqrt{2}$$

Initial conditions are used to solve for c_1 . Substituting $x = \frac{1}{2}$ and $y = 3$ in the above solution gives an equation to solve for the constant of integration.

$$3 = -2 + \frac{\sqrt{11 + 4c_1}}{2} + c_1$$

$$c_1 = \frac{11}{2} - 2\sqrt{2}$$

Substituting c_1 found above in the general solution gives

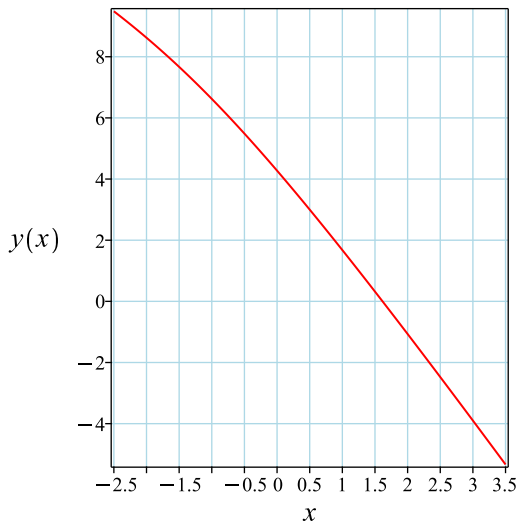
$$y = -2x + \frac{9}{2} + \frac{\sqrt{4x^2 + 26 - 8\sqrt{2} + 12x}}{2} - 2\sqrt{2}$$

Summary

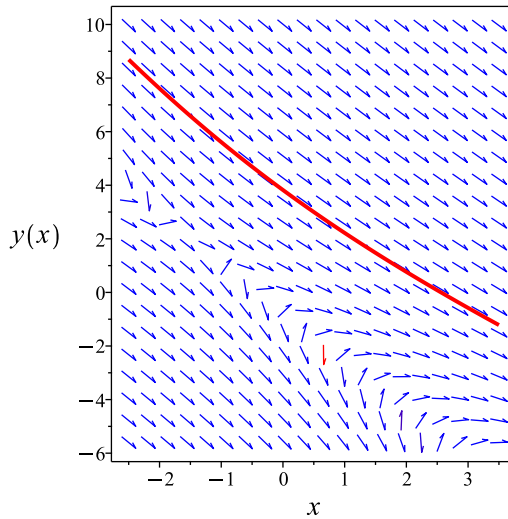
The solution(s) found are the following

$$y = -2x + \frac{9}{2} + \frac{\sqrt{4x^2 + 26 - 8\sqrt{2} + 12x}}{2} - 2\sqrt{2} \quad (1)$$

$$y = -2x + \frac{9}{2} - \frac{\sqrt{4x^2 + 26 + 8\sqrt{2} + 12x}}{2} + 2\sqrt{2} \quad (2)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = -2x + \frac{9}{2} + \frac{\sqrt{4x^2 + 26 - 8\sqrt{2} + 12x}}{2} - 2\sqrt{2}$$

Verified OK.

$$y = -2x + \frac{9}{2} - \frac{\sqrt{4x^2 + 26 + 8\sqrt{2} + 12x}}{2} + 2\sqrt{2}$$

Verified OK.

7.11.3 Solving as homogeneousTypeMapleC ode

Let $Y = y + y_0$ and $X = x + x_0$ then the above is transformed to new ode in $Y(X)$

$$\frac{d}{dX}Y(X) = -\frac{6X + 6x_0 + 4Y(X) + 4y_0 + 1}{2(2X + 2x_0 + Y(X) + y_0 + 1)}$$

Solving for possible values of x_0 and y_0 which makes the above ode a homogeneous ode results in

$$x_0 = -\frac{3}{2}$$

$$y_0 = 2$$

Using these values now it is possible to easily solve for $Y(X)$. The above ode now becomes

$$\frac{d}{dX}Y(X) = -\frac{6X + 4Y(X)}{2(2X + Y(X))}$$

In canonical form, the ODE is

$$\begin{aligned} Y' &= F(X, Y) \\ &= -\frac{3X + 2Y}{2X + Y} \end{aligned} \quad (1)$$

An ode of the form $Y' = \frac{M(X, Y)}{N(X, Y)}$ is called homogeneous if the functions $M(X, Y)$ and $N(X, Y)$ are both homogeneous functions and of the same order. Recall that a function $f(X, Y)$ is homogeneous of order n if

$$f(t^n X, t^n Y) = t^n f(X, Y)$$

In this case, it can be seen that both $M = -3X - 2Y$ and $N = 2X + Y$ are both homogeneous and of the same order $n = 1$. Therefore this is a homogeneous ode. Since this ode is homogeneous, it is converted to separable ODE using the substitution $u = \frac{Y}{X}$, or $Y = uX$. Hence

$$\frac{dY}{dX} = \frac{du}{dX}X + u$$

Applying the transformation $Y = uX$ to the above ODE in (1) gives

$$\begin{aligned} \frac{du}{dX}X + u &= \frac{-2u - 3}{u + 2} \\ \frac{du}{dX} &= \frac{\frac{-2u(X)-3}{u(X)+2} - u(X)}{X} \end{aligned}$$

Or

$$\frac{d}{dX}u(X) - \frac{\frac{-2u(X)-3}{u(X)+2} - u(X)}{X} = 0$$

Or

$$\left(\frac{d}{dX}u(X)\right)Xu(X) + 2\left(\frac{d}{dX}u(X)\right)X + u(X)^2 + 4u(X) + 3 = 0$$

Or

$$X(u(X) + 2)\left(\frac{d}{dX}u(X)\right) + u(X)^2 + 4u(X) + 3 = 0$$

Which is now solved as separable in $u(X)$. Which is now solved in $u(X)$. In canonical form the ODE is

$$\begin{aligned} u' &= F(X, u) \\ &= f(X)g(u) \\ &= -\frac{u^2 + 4u + 3}{X(u + 2)} \end{aligned}$$

Where $f(X) = -\frac{1}{X}$ and $g(u) = \frac{u^2+4u+3}{u+2}$. Integrating both sides gives

$$\begin{aligned}\frac{1}{\frac{u^2+4u+3}{u+2}} du &= -\frac{1}{X} dX \\ \int \frac{1}{\frac{u^2+4u+3}{u+2}} du &= \int -\frac{1}{X} dX \\ \frac{\ln(u^2 + 4u + 3)}{2} &= -\ln(X) + c_2\end{aligned}$$

Raising both side to exponential gives

$$\sqrt{u^2 + 4u + 3} = e^{-\ln(X)+c_2}$$

Which simplifies to

$$\sqrt{u^2 + 4u + 3} = \frac{c_3}{X}$$

Which simplifies to

$$\sqrt{u(X)^2 + 4u(X) + 3} = \frac{c_3 e^{c_2}}{X}$$

The solution is

$$\sqrt{u(X)^2 + 4u(X) + 3} = \frac{c_3 e^{c_2}}{X}$$

Now u in the above solution is replaced back by Y using $u = \frac{Y}{X}$ which results in the solution

$$\sqrt{\frac{Y(X)^2}{X^2} + \frac{4Y(X)}{X} + 3} = \frac{c_3 e^{c_2}}{X}$$

Which simplifies to

$$\sqrt{\frac{(Y(X) + 3X)(Y(X) + X)}{X^2}} = \frac{c_3 e^{c_2}}{X}$$

Using the solution for $Y(X)$

$$\sqrt{\frac{(Y(X) + 3X)(Y(X) + X)}{X^2}} = \frac{c_3 e^{c_2}}{X}$$

And replacing back terms in the above solution using

$$\begin{aligned} Y &= y + y_0 \\ X &= x + x_0 \end{aligned}$$

Or

$$\begin{aligned} Y &= y + 2 \\ X &= x - \frac{3}{2} \end{aligned}$$

Then the solution in y becomes

$$\sqrt{\frac{(y + \frac{5}{2} + 3x)(y - \frac{1}{2} + x)}{(x + \frac{3}{2})^2}} = \frac{c_3 e^{c_2}}{x + \frac{3}{2}}$$

Initial conditions are used to solve for c_2 . Substituting $x = \frac{1}{2}$ and $y = 3$ in the above solution gives an equation to solve for the constant of integration.

$$\begin{aligned} \frac{\sqrt{21}}{2} &= \frac{c_3 e^{c_2}}{2} \\ c_2 &= \frac{\ln\left(\frac{21}{c_3^2}\right)}{2} \end{aligned}$$

Substituting c_2 found above in the general solution gives

$$\sqrt{\frac{(y + \frac{5}{2} + 3x)(x + y - \frac{1}{2})}{(x + \frac{3}{2})^2}} = \frac{2c_3 \sqrt{21} \sqrt{\frac{1}{c_3^2}}}{3 + 2x}$$

The above simplifies to

$$-2c_3 \sqrt{21} \sqrt{\frac{1}{c_3^2}} + 2 \sqrt{\frac{(2y + 5 + 6x)(2x + 2y - 1)}{(3 + 2x)^2}} x + 3 \sqrt{\frac{(2y + 5 + 6x)(2x + 2y - 1)}{(3 + 2x)^2}} = 0$$

Summary

The solution(s) found are the following

$$\sqrt{\frac{(2y + 5 + 6x)(2x + 2y - 1)}{(3 + 2x)^2}} (3 + 2x) - 2\sqrt{21} \operatorname{csgn}\left(\frac{1}{c_3}\right) = 0 \quad (1)$$

Verification of solutions

$$\sqrt{\frac{(2y + 5 + 6x)(2x + 2y - 1)}{(3 + 2x)^2}} (3 + 2x) - 2\sqrt{21} \operatorname{csgn}\left(\frac{1}{c_3}\right) = 0$$

Verified OK.

7.11.4 Solving as first order ode lie symmetry calculated ode

Writing the ode as

$$y' = -\frac{6x + 4y + 1}{2(2x + y + 1)}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is not in the lookup table. To determine ξ, η then (A) is solved using ansatz. Making bivariate polynomials of degree 1 to use as anstaz gives

$$\xi = xa_2 + ya_3 + a_1 \quad (\text{1E})$$

$$\eta = xb_2 + yb_3 + b_1 \quad (\text{2E})$$

Where the unknown coefficients are

$$\{a_1, a_2, a_3, b_1, b_2, b_3\}$$

Substituting equations (1E,2E) and ω into (A) gives

$$b_2 - \frac{(6x + 4y + 1)(b_3 - a_2)}{2(2x + y + 1)} - \frac{(6x + 4y + 1)^2 a_3}{4(2x + y + 1)^2}$$

$$- \left(-\frac{3}{2x + y + 1} + \frac{6x + 4y + 1}{(2x + y + 1)^2} \right) (xa_2 + ya_3 + a_1) \quad (\text{5E})$$

$$- \left(-\frac{2}{2x + y + 1} + \frac{6x + 4y + 1}{2(2x + y + 1)^2} \right) (xb_2 + yb_3 + b_1) = 0$$

Putting the above in normal form gives

$$\frac{24x^2a_2 - 36x^2a_3 + 20x^2b_2 - 24x^2b_3 + 24xya_2 - 48xya_3 + 16xyb_2 - 24xyb_3 + 8y^2a_2 - 20y^2a_3 + 4y^2b_2 - 8y^2b_3 + 24xa_2 - 12xa_3 + 4xb_1 + 22xb_2 - 16xb_3 - 4ya_1 + 10ya_2 + 8yb_2 - 4yb_3 + 8a_1 + 2a_2 - a_3 + 6b_1 + 4b_2 - 2b_3}{4(2x + y + 1)^2} = 0$$

Setting the numerator to zero gives

$$24x^2a_2 - 36x^2a_3 + 20x^2b_2 - 24x^2b_3 + 24xya_2 - 48xya_3 + 16xyb_2 - 24xyb_3 + 8y^2a_2 - 20y^2a_3 + 4y^2b_2 - 8y^2b_3 + 24xa_2 - 12xa_3 + 4xb_1 + 22xb_2 - 16xb_3 - 4ya_1 + 10ya_2 + 8yb_2 - 4yb_3 + 8a_1 + 2a_2 - a_3 + 6b_1 + 4b_2 - 2b_3 = 0 \quad (\text{6E})$$

Looking at the above PDE shows the following are all the terms with $\{x, y\}$ in them.

$$\{x, y\}$$

The following substitution is now made to be able to collect on all terms with $\{x, y\}$ in them

$$\{x = v_1, y = v_2\}$$

The above PDE (6E) now becomes

$$\begin{aligned} 24a_2v_1^2 + 24a_2v_1v_2 + 8a_2v_2^2 - 36a_3v_1^2 - 48a_3v_1v_2 - 20a_3v_2^2 + 20b_2v_1^2 + 16b_2v_1v_2 \\ + 4b_2v_2^2 - 24b_3v_1^2 - 24b_3v_1v_2 - 8b_3v_2^2 - 4a_1v_2 + 24a_2v_1 + 10a_2v_2 - 12a_3v_1 + 4b_1v_1 \\ + 22b_2v_1 + 8b_2v_2 - 16b_3v_1 - 4b_3v_2 + 8a_1 + 2a_2 - a_3 + 6b_1 + 4b_2 - 2b_3 = 0 \end{aligned} \quad (7E)$$

Collecting the above on the terms v_i introduced, and these are

$$\{v_1, v_2\}$$

Equation (7E) now becomes

$$\begin{aligned} (24a_2 - 36a_3 + 20b_2 - 24b_3)v_1^2 + (24a_2 - 48a_3 + 16b_2 - 24b_3)v_1v_2 \\ + (24a_2 - 12a_3 + 4b_1 + 22b_2 - 16b_3)v_1 + (8a_2 - 20a_3 + 4b_2 - 8b_3)v_2^2 \\ + (-4a_1 + 10a_2 + 8b_2 - 4b_3)v_2 + 8a_1 + 2a_2 - a_3 + 6b_1 + 4b_2 - 2b_3 = 0 \end{aligned} \quad (8E)$$

Setting each coefficients in (8E) to zero gives the following equations to solve

$$\begin{aligned} -4a_1 + 10a_2 + 8b_2 - 4b_3 &= 0 \\ 8a_2 - 20a_3 + 4b_2 - 8b_3 &= 0 \\ 24a_2 - 48a_3 + 16b_2 - 24b_3 &= 0 \\ 24a_2 - 36a_3 + 20b_2 - 24b_3 &= 0 \\ 24a_2 - 12a_3 + 4b_1 + 22b_2 - 16b_3 &= 0 \\ 8a_1 + 2a_2 - a_3 + 6b_1 + 4b_2 - 2b_3 &= 0 \end{aligned}$$

Solving the above equations for the unknowns gives

$$\begin{aligned} a_1 &= 4a_3 + \frac{3b_3}{2} \\ a_2 &= 4a_3 + b_3 \\ a_3 &= a_3 \\ b_1 &= -\frac{9a_3}{2} - 2b_3 \\ b_2 &= -3a_3 \\ b_3 &= b_3 \end{aligned}$$

Substituting the above solution in the ansatz (1E,2E) (using 1 as arbitrary value for any unknown in the RHS) gives

$$\begin{aligned} \xi &= x + \frac{3}{2} \\ \eta &= y - 2 \end{aligned}$$

Shifting is now applied to make $\xi = 0$ in order to simplify the rest of the computation

$$\begin{aligned} \eta &= \eta - \omega(x, y) \xi \\ &= y - 2 - \left(-\frac{6x + 4y + 1}{2(2x + y + 1)} \right) \left(x + \frac{3}{2} \right) \\ &= \frac{12x^2 + 16xy + 4y^2 + 4x + 8y - 5}{8x + 4y + 4} \\ \xi &= 0 \end{aligned}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \quad (1)$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y} \right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{12x^2 + 16xy + 4y^2 + 4x + 8y - 5}{8x + 4y + 4}} dy \end{aligned}$$

Which results in

$$S = \frac{\ln(12x^2 + 16xy + 4y^2 + 4x + 8y - 5)}{2}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{6x + 4y + 1}{2(2x + y + 1)}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= \frac{3}{2y + 5 + 6x} + \frac{1}{2x + 2y - 1} \\ S_y &= \frac{1}{2y + 5 + 6x} + \frac{1}{2x + 2y - 1} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 0 \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 0$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by

integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = c_1 \quad (4)$$

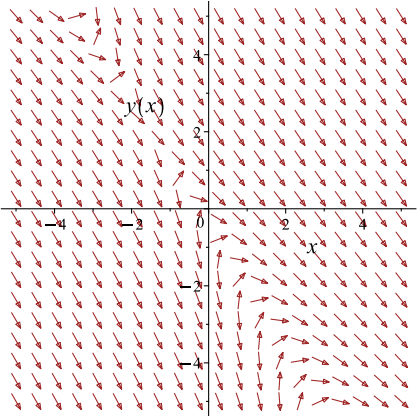
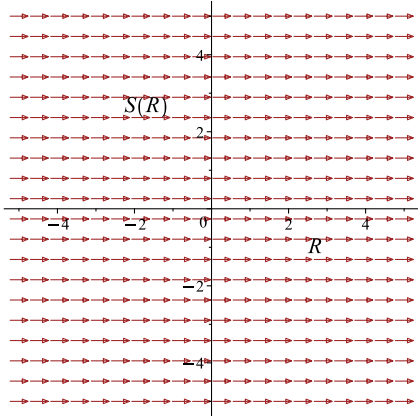
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$\frac{\ln(2y + 5 + 6x)}{2} + \frac{\ln(2x + 2y - 1)}{2} = c_1$$

Which simplifies to

$$\frac{\ln(2y + 5 + 6x)}{2} + \frac{\ln(2x + 2y - 1)}{2} = c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{6x+4y+1}{2(2x+y+1)}$ 	$R = x$ $S = \frac{\ln(2y + 5 + 6x)}{2} + \ln$	$\frac{dS}{dR} = 0$ 

Initial conditions are used to solve for c_1 . Substituting $x = \frac{1}{2}$ and $y = 3$ in the above solution gives an equation to solve for the constant of integration.

$$\ln(2) + \frac{\ln(7)}{2} + \frac{\ln(3)}{2} = c_1$$

$$c_1 = \ln(2) + \frac{\ln(7)}{2} + \frac{\ln(3)}{2}$$

Substituting c_1 found above in the general solution gives

$$\frac{\ln(2y + 5 + 6x)}{2} + \frac{\ln(2x + 2y - 1)}{2} = \ln(2) + \frac{\ln(7)}{2} + \frac{\ln(3)}{2}$$

Summary

The solution(s) found are the following

$$\frac{\ln(2y + 5 + 6x)}{2} + \frac{\ln(2x + 2y - 1)}{2} = \ln(2) + \frac{\ln(7)}{2} + \frac{\ln(3)}{2} \quad (1)$$

Verification of solutions

$$\frac{\ln(2y + 5 + 6x)}{2} + \frac{\ln(2x + 2y - 1)}{2} = \ln(2) + \frac{\ln(7)}{2} + \frac{\ln(3)}{2}$$

Verified OK.

7.11.5 Solving as exact ode

Entering Exact first order ODE solver. (Form one type)

To solve an ode of the form

$$M(x, y) + N(x, y) \frac{dy}{dx} = 0 \quad (A)$$

We assume there exists a function $\phi(x, y) = c$ where c is constant, that satisfies the ode. Taking derivative of ϕ w.r.t. x gives

$$\frac{d}{dx} \phi(x, y) = 0$$

Hence

$$\frac{\partial \phi}{\partial x} + \frac{\partial \phi}{\partial y} \frac{dy}{dx} = 0 \quad (B)$$

Comparing (A,B) shows that

$$\begin{aligned} \frac{\partial \phi}{\partial x} &= M \\ \frac{\partial \phi}{\partial y} &= N \end{aligned}$$

But since $\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ then for the above to be valid, we require that

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

If the above condition is satisfied, then the original ode is called exact. We still need to determine $\phi(x, y)$ but at least we know now that we can do that since the condition

$\frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \phi}{\partial y \partial x}$ is satisfied. If this condition is not satisfied then this method will not work and we have to now look for an integrating factor to force this condition, which might or might not exist. The first step is to write the ODE in standard form to check for exactness, which is

$$M(x, y) dx + N(x, y) dy = 0 \quad (1A)$$

Therefore

$$\begin{aligned} (4x + 2y + 2) dy &= (-6x - 4y - 1) dx \\ (6x + 4y + 1) dx + (4x + 2y + 2) dy &= 0 \end{aligned} \quad (2A)$$

Comparing (1A) and (2A) shows that

$$\begin{aligned} M(x, y) &= 6x + 4y + 1 \\ N(x, y) &= 4x + 2y + 2 \end{aligned}$$

The next step is to determine if the ODE is exact or not. The ODE is exact when the following condition is satisfied

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

Using result found above gives

$$\begin{aligned} \frac{\partial M}{\partial y} &= \frac{\partial}{\partial y}(6x + 4y + 1) \\ &= 4 \end{aligned}$$

And

$$\begin{aligned} \frac{\partial N}{\partial x} &= \frac{\partial}{\partial x}(4x + 2y + 2) \\ &= 4 \end{aligned}$$

Since $\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$, then the ODE is exact. The following equations are now set up to solve for the function $\phi(x, y)$

$$\frac{\partial \phi}{\partial x} = M \quad (1)$$

$$\frac{\partial \phi}{\partial y} = N \quad (2)$$

Integrating (1) w.r.t. x gives

$$\begin{aligned} \int \frac{\partial \phi}{\partial x} dx &= \int M dx \\ \int \frac{\partial \phi}{\partial x} dx &= \int 6x + 4y + 1 dx \\ \phi &= x(3x + 4y + 1) + f(y) \end{aligned} \quad (3)$$

Where $f(y)$ is used for the constant of integration since ϕ is a function of both x and y . Taking derivative of equation (3) w.r.t y gives

$$\frac{\partial \phi}{\partial y} = 4x + f'(y) \quad (4)$$

But equation (2) says that $\frac{\partial \phi}{\partial y} = 4x + 2y + 2$. Therefore equation (4) becomes

$$4x + 2y + 2 = 4x + f'(y) \quad (5)$$

Solving equation (5) for $f'(y)$ gives

$$f'(y) = 2y + 2$$

Integrating the above w.r.t y gives

$$\begin{aligned} \int f'(y) \, dy &= \int (2y + 2) \, dy \\ f(y) &= y^2 + 2y + c_1 \end{aligned}$$

Where c_1 is constant of integration. Substituting result found above for $f(y)$ into equation (3) gives ϕ

$$\phi = x(3x + 4y + 1) + y^2 + 2y + c_1$$

But since ϕ itself is a constant function, then let $\phi = c_2$ where c_2 is new constant and combining c_1 and c_2 constants into new constant c_1 gives the solution as

$$c_1 = x(3x + 4y + 1) + y^2 + 2y$$

Initial conditions are used to solve for c_1 . Substituting $x = \frac{1}{2}$ and $y = 3$ in the above solution gives an equation to solve for the constant of integration.

$$\frac{89}{4} = c_1$$

$$c_1 = \frac{89}{4}$$

Substituting c_1 found above in the general solution gives

$$x(3x + 4y + 1) + y^2 + 2y = \frac{89}{4}$$

Summary

The solution(s) found are the following

$$y^2 + (4x + 2)y + 3x^2 + x = \frac{89}{4} \quad (1)$$

Verification of solutions

$$y^2 + (4x + 2)y + 3x^2 + x = \frac{89}{4}$$

Verified OK.

7.11.6 Maple step by step solution

Let's solve

$$[4y + (4x + 2y + 2)y' = -6x - 1, y(\frac{1}{2}) = 3]$$

- Highest derivative means the order of the ODE is 1
 y'
- Check if ODE is exact
 - ODE is exact if the lhs is the total derivative of a C^2 function
 $F'(x, y) = 0$
 - Compute derivative of lhs
 $F'(x, y) + \left(\frac{\partial}{\partial y}F(x, y)\right)y' = 0$
 - Evaluate derivatives
 $4 = 4$
 - Condition met, ODE is exact
- Exact ODE implies solution will be of this form
 $\left[F(x, y) = c_1, M(x, y) = F'(x, y), N(x, y) = \frac{\partial}{\partial y}F(x, y)\right]$
- Solve for $F(x, y)$ by integrating $M(x, y)$ with respect to x
 $F(x, y) = \int (6x + 4y + 1) dx + f_1(y)$
- Evaluate integral

$$F(x, y) = 3x^2 + 4xy + x + f_1(y)$$

- Take derivative of $F(x, y)$ with respect to y

$$N(x, y) = \frac{\partial}{\partial y} F(x, y)$$

- Compute derivative

$$4x + 2y + 2 = 4x + \frac{d}{dy} f_1(y)$$

- Isolate for $\frac{d}{dy} f_1(y)$

$$\frac{d}{dy} f_1(y) = 2y + 2$$

- Solve for $f_1(y)$

$$f_1(y) = y^2 + 2y$$

- Substitute $f_1(y)$ into equation for $F(x, y)$

$$F(x, y) = 3x^2 + 4xy + y^2 + x + 2y$$

- Substitute $F(x, y)$ into the solution of the ODE

$$3x^2 + 4xy + y^2 + x + 2y = c_1$$

- Solve for y

$$\left\{ y = -2x - 1 - \sqrt{x^2 + c_1 + 3x + 1}, y = -2x - 1 + \sqrt{x^2 + c_1 + 3x + 1} \right\}$$

- Use initial condition $y\left(\frac{1}{2}\right) = 3$

$$3 = -2 - \sqrt{\frac{11}{4} + c_1}$$

- Solution does not satisfy initial condition

- Use initial condition $y\left(\frac{1}{2}\right) = 3$

$$3 = -2 + \sqrt{\frac{11}{4} + c_1}$$

- Solve for c_1

$$c_1 = \frac{89}{4}$$

- Substitute $c_1 = \frac{89}{4}$ into general solution and simplify

$$y = -2x - 1 + \frac{\sqrt{4x^2 + 12x + 93}}{2}$$

- Solution to the IVP

$$y = -2x - 1 + \frac{\sqrt{4x^2 + 12x + 93}}{2}$$

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
trying Bernoulli  
trying separable  
trying inverse linear  
trying homogeneous types:  
trying homogeneous C  
trying homogeneous types:  
trying homogeneous D  
<- homogeneous successful  
<- homogeneous successful`
```

✓ Solution by Maple

Time used: 0.297 (sec). Leaf size: 23

```
dsolve([(6*x+4*y(x)+1)+(4*x+2*y(x)+2)*diff(y(x),x)=0,y(1/2) = 3],y(x), singsol=all)
```

$$y(x) = -2x - 1 + \frac{\sqrt{4x^2 + 12x + 93}}{2}$$

✓ Solution by Mathematica

Time used: 0.143 (sec). Leaf size: 28

```
DSolve[{(6*x+4*y[x]+1)+(4*x+2*y[x]+2)*y'[x]==0,{y[1/2]==3}},y[x],x,IncludeSingularSolutions
```

$$y(x) \rightarrow \frac{1}{2} \left(\sqrt{4x^2 + 12x + 93} - 4x - 2 \right)$$

7.12 problem 12

- 7.12.1 Existence and uniqueness analysis 1687
- 7.12.2 Solving as homogeneousTypeMapleC ode 1688
- 7.12.3 Solving as first order ode lie symmetry calculated ode 1691

Internal problem ID [11710]

Internal file name [OUTPUT/11719_Thursday_April_11_2024_08_48_53_PM_62273029/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 2, Section 2.4. Special integrating factors and transformations. Exercises page 67

Problem number: 12.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**homogeneousTypeMapleC**", "**first_order_ode_lie_symmetry_calculated**"

Maple gives the following as the ode type

```
[[_homogeneous, `class C`], _rational, [_Abel, `2nd type`, `class A`]]
```

$$-y + (x + y + 2)y' = -3x + 6$$

With initial conditions

$$[y(2) = -2]$$

7.12.1 Existence and uniqueness analysis

This is non linear first order ODE. In canonical form it is written as

$$\begin{aligned} y' &= f(x, y) \\ &= \frac{-3x + y + 6}{x + y + 2} \end{aligned}$$

The x domain of $f(x, y)$ when $y = -2$ is

$$\{x < 0 \vee 0 < x\}$$

And the point $x_0 = 2$ is inside this domain. The y domain of $f(x, y)$ when $x = 2$ is

$$\{y < -4 \vee -4 < y\}$$

And the point $y_0 = -2$ is inside this domain. Now we will look at the continuity of

$$\begin{aligned} \frac{\partial f}{\partial y} &= \frac{\partial}{\partial y} \left(\frac{-3x + y + 6}{x + y + 2} \right) \\ &= \frac{1}{x + y + 2} - \frac{-3x + y + 6}{(x + y + 2)^2} \end{aligned}$$

The x domain of $\frac{\partial f}{\partial y}$ when $y = -2$ is

$$\{x < 0 \vee 0 < x\}$$

And the point $x_0 = 2$ is inside this domain. The y domain of $\frac{\partial f}{\partial y}$ when $x = 2$ is

$$\{y < -4 \vee -4 < y\}$$

And the point $y_0 = -2$ is inside this domain. Therefore solution exists and is unique.

7.12.2 Solving as homogeneous Type MapleC ode

Let $Y = y + y_0$ and $X = x + x_0$ then the above is transformed to new ode in $Y(X)$

$$\frac{d}{dX} Y(X) = \frac{-3X - 3x_0 + Y(X) + y_0 + 6}{X + x_0 + Y(X) + y_0 + 2}$$

Solving for possible values of x_0 and y_0 which makes the above ode a homogeneous ode results in

$$\begin{aligned} x_0 &= 1 \\ y_0 &= -3 \end{aligned}$$

Using these values now it is possible to easily solve for $Y(X)$. The above ode now becomes

$$\frac{d}{dX} Y(X) = \frac{-3X + Y(X)}{X + Y(X)}$$

In canonical form, the ODE is

$$\begin{aligned} Y' &= F(X, Y) \\ &= \frac{-3X + Y}{X + Y} \end{aligned} \tag{1}$$

An ode of the form $Y' = \frac{M(X,Y)}{N(X,Y)}$ is called homogeneous if the functions $M(X, Y)$ and $N(X, Y)$ are both homogeneous functions and of the same order. Recall that a function $f(X, Y)$ is homogeneous of order n if

$$f(t^n X, t^n Y) = t^n f(X, Y)$$

In this case, it can be seen that both $M = -3X + Y$ and $N = X + Y$ are both homogeneous and of the same order $n = 1$. Therefore this is a homogeneous ode. Since this ode is homogeneous, it is converted to separable ODE using the substitution $u = \frac{Y}{X}$, or $Y = uX$. Hence

$$\frac{dY}{dX} = \frac{du}{dX}X + u$$

Applying the transformation $Y = uX$ to the above ODE in (1) gives

$$\begin{aligned} \frac{du}{dX}X + u &= \frac{u - 3}{u + 1} \\ \frac{du}{dX} &= \frac{\frac{u(X)-3}{u(X)+1} - u(X)}{X} \end{aligned}$$

Or

$$\frac{d}{dX}u(X) - \frac{\frac{u(X)-3}{u(X)+1} - u(X)}{X} = 0$$

Or

$$\left(\frac{d}{dX}u(X)\right)Xu(X) + \left(\frac{d}{dX}u(X)\right)X + u(X)^2 + 3 = 0$$

Or

$$X(u(X) + 1) \left(\frac{d}{dX}u(X)\right) + u(X)^2 + 3 = 0$$

Which is now solved as separable in $u(X)$. Which is now solved in $u(X)$. In canonical form the ODE is

$$\begin{aligned} u' &= F(X, u) \\ &= f(X)g(u) \\ &= -\frac{u^2 + 3}{X(u + 1)} \end{aligned}$$

Where $f(X) = -\frac{1}{X}$ and $g(u) = \frac{u^2+3}{u+1}$. Integrating both sides gives

$$\begin{aligned} \frac{1}{\frac{u^2+3}{u+1}} du &= -\frac{1}{X} dX \\ \int \frac{1}{\frac{u^2+3}{u+1}} du &= \int -\frac{1}{X} dX \end{aligned}$$

$$\frac{\ln(u^2 + 3)}{2} + \frac{\sqrt{3} \arctan\left(\frac{\sqrt{3}u}{3}\right)}{3} = -\ln(X) + c_2$$

The solution is

$$\frac{\ln(u(X)^2 + 3)}{2} + \frac{\sqrt{3} \arctan\left(\frac{\sqrt{3}u(X)}{3}\right)}{3} + \ln(X) - c_2 = 0$$

Now u in the above solution is replaced back by Y using $u = \frac{Y}{X}$ which results in the solution

$$\frac{\ln\left(\frac{Y(X)^2}{X^2} + 3\right)}{2} + \frac{\sqrt{3} \arctan\left(\frac{\sqrt{3}Y(X)}{3X}\right)}{3} + \ln(X) - c_2 = 0$$

Using the solution for $Y(X)$

$$\frac{\ln\left(\frac{Y(X)^2}{X^2} + 3\right)}{2} + \frac{\sqrt{3} \arctan\left(\frac{\sqrt{3}Y(X)}{3X}\right)}{3} + \ln(X) - c_2 = 0$$

And replacing back terms in the above solution using

$$Y = y + y_0$$

$$X = x + x_0$$

Or

$$Y = y - 3$$

$$X = 1 + x$$

Then the solution in y becomes

$$\frac{\ln\left(\frac{(y+3)^2}{(x-1)^2} + 3\right)}{2} + \frac{\sqrt{3} \arctan\left(\frac{\sqrt{3}(y+3)}{-3+3x}\right)}{3} + \ln(x-1) - c_2 = 0$$

Initial conditions are used to solve for c_2 . Substituting $x = 2$ and $y = -2$ in the above solution gives an equation to solve for the constant of integration.

$$\ln(2) + \frac{\pi\sqrt{3}}{18} - c_2 = 0$$

$$c_2 = \ln(2) + \frac{\pi\sqrt{3}}{18}$$

Substituting c_2 found above in the general solution gives

$$\frac{\ln\left(\frac{3x^2+y^2-6x+6y+12}{(x-1)^2}\right)}{2} + \frac{\sqrt{3} \arctan\left(\frac{\sqrt{3}(3+y)}{-3+3x}\right)}{3} + \ln(x-1) - \ln(2) - \frac{\pi\sqrt{3}}{18} = 0$$

Summary

The solution(s) found are the following

$$\frac{\ln\left(\frac{3x^2+y^2-6x+6y+12}{(x-1)^2}\right)}{2} + \frac{\sqrt{3} \arctan\left(\frac{\sqrt{3}(y+3)}{-3+3x}\right)}{3} + \ln(x-1) - \ln(2) - \frac{\pi\sqrt{3}}{18} = 0 \quad (1)$$

Verification of solutions

$$\frac{\ln\left(\frac{3x^2+y^2-6x+6y+12}{(x-1)^2}\right)}{2} + \frac{\sqrt{3} \arctan\left(\frac{\sqrt{3}(y+3)}{-3+3x}\right)}{3} + \ln(x-1) - \ln(2) - \frac{\pi\sqrt{3}}{18} = 0$$

Verified OK.

7.12.3 Solving as first order ode lie symmetry calculated ode

Writing the ode as

$$y' = \frac{-3x + y + 6}{x + y + 2}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is not in the lookup table. To determine ξ, η then (A) is solved using ansatz. Making bivariate polynomials of degree 1 to use as anstaz gives

$$\xi = xa_2 + ya_3 + a_1 \quad (1\text{E})$$

$$\eta = xb_2 + yb_3 + b_1 \quad (2\text{E})$$

Where the unknown coefficients are

$$\{a_1, a_2, a_3, b_1, b_2, b_3\}$$

Substituting equations (1E,2E) and ω into (A) gives

$$\begin{aligned}
 & b_2 + \frac{(-3x + y + 6)(b_3 - a_2)}{x + y + 2} - \frac{(-3x + y + 6)^2 a_3}{(x + y + 2)^2} \\
 & - \left(\frac{3}{x + y + 2} - \frac{-3x + y + 6}{(x + y + 2)^2} \right) (xa_2 + ya_3 + a_1) \\
 & - \left(\frac{1}{x + y + 2} - \frac{-3x + y + 6}{(x + y + 2)^2} \right) (xb_2 + yb_3 + b_1) = 0
 \end{aligned} \tag{5E}$$

Putting the above in normal form gives

$$\frac{3x^2 a_2 - 9x^2 a_3 - 3x^2 b_2 - 3x^2 b_3 + 6xy a_2 + 6xy a_3 + 2xy b_2 - 6xy b_3 - y^2 a_2 + 3y^2 a_3 + y^2 b_2 + y^2 b_3 + 12xa_2}{(x + y + 2)} = 0$$

Setting the numerator to zero gives

$$\begin{aligned}
 & 3x^2 a_2 - 9x^2 a_3 - 3x^2 b_2 - 3x^2 b_3 + 6xy a_2 + 6xy a_3 + 2xy b_2 - 6xy b_3 \\
 & - y^2 a_2 + 3y^2 a_3 + y^2 b_2 + y^2 b_3 + 12xa_2 + 36xa_3 - 4xb_1 + 8xb_2 + 4ya_1 \\
 & - 8ya_2 + 4yb_2 + 12yb_3 + 12a_1 - 12a_2 - 36a_3 + 4b_1 + 4b_2 + 12b_3 = 0
 \end{aligned} \tag{6E}$$

Looking at the above PDE shows the following are all the terms with $\{x, y\}$ in them.

$$\{x, y\}$$

The following substitution is now made to be able to collect on all terms with $\{x, y\}$ in them

$$\{x = v_1, y = v_2\}$$

The above PDE (6E) now becomes

$$\begin{aligned}
 & 3a_2 v_1^2 + 6a_2 v_1 v_2 - a_2 v_2^2 - 9a_3 v_1^2 + 6a_3 v_1 v_2 + 3a_3 v_2^2 - 3b_2 v_1^2 + 2b_2 v_1 v_2 + b_2 v_2^2 \\
 & - 3b_3 v_1^2 - 6b_3 v_1 v_2 + b_3 v_2^2 + 4a_1 v_2 + 12a_2 v_1 - 8a_2 v_2 + 36a_3 v_1 - 4b_1 v_1 \\
 & + 8b_2 v_1 + 4b_2 v_2 + 12b_3 v_2 + 12a_1 - 12a_2 - 36a_3 + 4b_1 + 4b_2 + 12b_3 = 0
 \end{aligned} \tag{7E}$$

Collecting the above on the terms v_i introduced, and these are

$$\{v_1, v_2\}$$

Equation (7E) now becomes

$$\begin{aligned}
 & (3a_2 - 9a_3 - 3b_2 - 3b_3)v_1^2 + (6a_2 + 6a_3 + 2b_2 - 6b_3)v_1v_2 \\
 & + (12a_2 + 36a_3 - 4b_1 + 8b_2)v_1 + (-a_2 + 3a_3 + b_2 + b_3)v_2^2 \\
 & + (4a_1 - 8a_2 + 4b_2 + 12b_3)v_2 + 12a_1 - 12a_2 - 36a_3 + 4b_1 + 4b_2 + 12b_3 = 0
 \end{aligned} \tag{8E}$$

Setting each coefficients in (8E) to zero gives the following equations to solve

$$\begin{aligned}
 4a_1 - 8a_2 + 4b_2 + 12b_3 &= 0 \\
 -a_2 + 3a_3 + b_2 + b_3 &= 0 \\
 3a_2 - 9a_3 - 3b_2 - 3b_3 &= 0 \\
 6a_2 + 6a_3 + 2b_2 - 6b_3 &= 0 \\
 12a_2 + 36a_3 - 4b_1 + 8b_2 &= 0 \\
 12a_1 - 12a_2 - 36a_3 + 4b_1 + 4b_2 + 12b_3 &= 0
 \end{aligned}$$

Solving the above equations for the unknowns gives

$$\begin{aligned}
 a_1 &= -b_3 + 3a_3 \\
 a_2 &= b_3 \\
 a_3 &= a_3 \\
 b_1 &= 3a_3 + 3b_3 \\
 b_2 &= -3a_3 \\
 b_3 &= b_3
 \end{aligned}$$

Substituting the above solution in the anstaz (1E,2E) (using 1 as arbitrary value for any unknown in the RHS) gives

$$\begin{aligned}
 \xi &= 3 + y \\
 \eta &= -3x + 3
 \end{aligned}$$

Shifting is now applied to make $\xi = 0$ in order to simplify the rest of the computation

$$\begin{aligned}
 \eta &= \eta - \omega(x, y) \xi \\
 &= -3x + 3 - \left(\frac{-3x + y + 6}{x + y + 2} \right) (3 + y) \\
 &= \frac{-3x^2 - y^2 + 6x - 6y - 12}{x + y + 2}
 \end{aligned}$$

$$\xi = 0$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \quad (1)$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y}\right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned} S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{-3x^2 - y^2 + 6x - 6y - 12}{x + y + 2}} dy \end{aligned}$$

Which results in

$$S = -\frac{\ln(3x^2 + y^2 - 6x + 6y + 12)}{2} + \frac{(1-x)\sqrt{3} \arctan\left(\frac{(2y+6)\sqrt{3}}{6x-6}\right)}{-3+3x}$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = \frac{-3x + y + 6}{x + y + 2}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= \frac{-3x + y + 6}{3x^2 + y^2 - 6x + 6y + 12} \\ S_y &= \frac{-x - y - 2}{3x^2 + y^2 - 6x + 6y + 12} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 0 \quad (2A)$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 0$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = c_1 \quad (4)$$

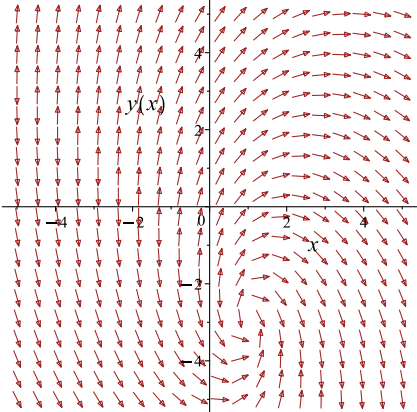
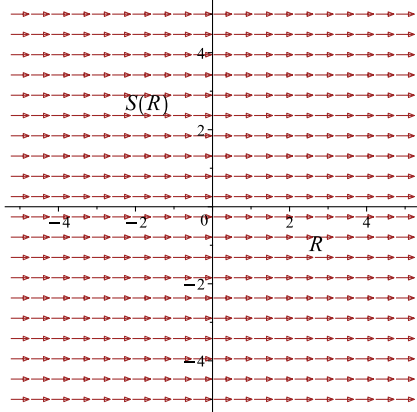
To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$-\frac{\ln(3x^2 + y^2 - 6x + 6y + 12)}{2} - \frac{\sqrt{3} \arctan\left(\frac{\sqrt{3}(y+3)}{-3+3x}\right)}{3} = c_1$$

Which simplifies to

$$-\frac{\ln(3x^2 + y^2 - 6x + 6y + 12)}{2} - \frac{\sqrt{3} \arctan\left(\frac{\sqrt{3}(y+3)}{-3+3x}\right)}{3} = c_1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = \frac{-3x+y+6}{x+y+2}$ 	$R = x$ $S = -\frac{\ln(3x^2 + y^2 - 6x + 6y + 12)}{2} - \frac{\sqrt{3} \arctan\left(\frac{\sqrt{3}(y+3)}{-3+3x}\right)}{3}$	$\frac{dS}{dR} = 0$ 

Initial conditions are used to solve for c_1 . Substituting $x = 2$ and $y = -2$ in the above solution gives an equation to solve for the constant of integration.

$$-\ln(2) - \frac{\pi\sqrt{3}}{18} = c_1$$

$$c_1 = -\ln(2) - \frac{\pi\sqrt{3}}{18}$$

Substituting c_1 found above in the general solution gives

$$-\frac{\ln(3x^2 + y^2 - 6x + 6y + 12)}{2} - \frac{\sqrt{3} \arctan\left(\frac{\sqrt{3}(y+3)}{-3+3x}\right)}{3} = -\ln(2) - \frac{\pi\sqrt{3}}{18}$$

Summary

The solution(s) found are the following

$$-\frac{\ln(3x^2 + y^2 - 6x + 6y + 12)}{2} - \frac{\sqrt{3} \arctan\left(\frac{\sqrt{3}(y+3)}{-3+3x}\right)}{3} = -\ln(2) - \frac{\pi\sqrt{3}}{18} \quad (1)$$

Verification of solutions

$$\frac{\ln(3x^2 + y^2 - 6x + 6y + 12)}{2} - \frac{\sqrt{3} \arctan\left(\frac{\sqrt{3}(y+3)}{-3+3x}\right)}{3} = -\ln(2) - \frac{\pi\sqrt{3}}{18}$$

Verified OK.

Maple trace

```
`Methods for first order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying 1st order linear  
trying Bernoulli  
trying separable  
trying inverse linear  
trying homogeneous types:  
trying homogeneous C  
trying homogeneous types:  
trying homogeneous D  
<- homogeneous successful  
<- homogeneous successful`
```

✓ Solution by Maple

Time used: 9.453 (sec). Leaf size: 120

```
dsolve([(3*x-y(x)-6)+(x+y(x)+2)*diff(y(x),x)=0,y(2) = -2],y(x), singsol=all)
```

$$y(x) = -3 - \sqrt{3} \tan\left(\text{RootOf}\left(-3\sqrt{3} \ln(3) + 6\sqrt{3} \ln(2) - 3\sqrt{3} \ln(\sec(_Z)^2(-1+x)^2) + \pi + 6_Z\right)\right)(-1+x)$$

✓ Solution by Mathematica

Time used: 0.141 (sec). Leaf size: 90

```
DSolve[{(3*x-y[x]-6)+(x+y[x]+2)*y'[x]==0,{y[2]==-2}},y[x],x,IncludeSingularSolutions -> True
```

$$\text{Solve} \left[\frac{\arctan \left(\frac{-y(x)+3x-6}{\sqrt{3}(y(x)+x+2)} \right)}{\sqrt{3}} + \log(2) = \frac{1}{2} \log \left(\frac{3x^2 + y(x)^2 + 6y(x) - 6x + 12}{(x-1)^2} \right) \right. \\ \left. + \log(x-1) + \frac{1}{18} \left(\sqrt{3}\pi + 18\log(2) - 9\log(4) \right), y(x) \right]$$

7.13 problem 13

7.13.1 Existence and uniqueness analysis 1699

7.13.2 Solving as first order ode lie symmetry calculated ode 1700

Internal problem ID [11711]

Internal file name [OUTPUT/11720_Thursday_April_11_2024_08_48_58_PM_23035239/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 2, Section 2.4. Special integrating factors and transformations. Exercises page 67

Problem number: 13.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**first_order_ode_lie_symmetry_calculated**"

Maple gives the following as the ode type

```
[[_homogeneous, `class C`], _rational, [_Abel, `2nd type`, `class A`]]
```

$$3y + (4x + 6y + 1)y' = -2x - 1$$

With initial conditions

$$[y(-2) = 2]$$

7.13.1 Existence and uniqueness analysis

This is non linear first order ODE. In canonical form it is written as

$$\begin{aligned} y' &= f(x, y) \\ &= -\frac{2x + 3y + 1}{4x + 6y + 1} \end{aligned}$$

The x domain of $f(x, y)$ when $y = 2$ is

$$\left\{ x < -\frac{13}{4} \vee -\frac{13}{4} < x \right\}$$

And the point $x_0 = -2$ is inside this domain. The y domain of $f(x, y)$ when $x = -2$ is

$$\left\{ y < \frac{7}{6} \vee \frac{7}{6} < y \right\}$$

And the point $y_0 = 2$ is inside this domain. Now we will look at the continuity of

$$\begin{aligned} \frac{\partial f}{\partial y} &= \frac{\partial}{\partial y} \left(-\frac{2x + 3y + 1}{4x + 6y + 1} \right) \\ &= -\frac{3}{4x + 6y + 1} + \frac{12x + 18y + 6}{(4x + 6y + 1)^2} \end{aligned}$$

The x domain of $\frac{\partial f}{\partial y}$ when $y = 2$ is

$$\left\{ x < -\frac{13}{4} \vee -\frac{13}{4} < x \right\}$$

And the point $x_0 = -2$ is inside this domain. The y domain of $\frac{\partial f}{\partial y}$ when $x = -2$ is

$$\left\{ y < \frac{7}{6} \vee \frac{7}{6} < y \right\}$$

And the point $y_0 = 2$ is inside this domain. Therefore solution exists and is unique.

7.13.2 Solving as first order ode lie symmetry calculated ode

Writing the ode as

$$\begin{aligned} y' &= -\frac{2x + 3y + 1}{4x + 6y + 1} \\ y' &= \omega(x, y) \end{aligned}$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is not in the lookup table. To determine ξ, η then (A) is solved using ansatz. Making bivariate polynomials of degree 1 to use as anstaz gives

$$\xi = xa_2 + ya_3 + a_1 \quad (\text{1E})$$

$$\eta = xb_2 + yb_3 + b_1 \quad (\text{2E})$$

Where the unknown coefficients are

$$\{a_1, a_2, a_3, b_1, b_2, b_3\}$$

Substituting equations (1E,2E) and ω into (A) gives

$$\begin{aligned} b_2 - \frac{(2x + 3y + 1)(b_3 - a_2)}{4x + 6y + 1} - \frac{(2x + 3y + 1)^2 a_3}{(4x + 6y + 1)^2} \\ - \left(-\frac{2}{4x + 6y + 1} + \frac{8x + 12y + 4}{(4x + 6y + 1)^2} \right) (xa_2 + ya_3 + a_1) \\ - \left(-\frac{3}{4x + 6y + 1} + \frac{12x + 18y + 6}{(4x + 6y + 1)^2} \right) (xb_2 + yb_3 + b_1) = 0 \end{aligned} \quad (5E)$$

Putting the above in normal form gives

$$\frac{8x^2a_2 - 4x^2a_3 + 16x^2b_2 - 8x^2b_3 + 24xya_2 - 12xya_3 + 48xyb_2 - 24xyb_3 + 18y^2a_2 - 9y^2a_3 + 36y^2b_2 - 18y^2b_3 - 4xa_2 + 4xa_3 + 5xb_2 - 6xb_3 + 9ya_2 - 8ya_3 + 12yb_2 - 12yb_3 - 2a_1 + a_2 - a_3 - 3b_1 + b_2 - b_3}{(4x + 6y + 1)^2} = 0$$

Setting the numerator to zero gives

$$\begin{aligned} 8x^2a_2 - 4x^2a_3 + 16x^2b_2 - 8x^2b_3 + 24xya_2 - 12xya_3 + 48xyb_2 - 24xyb_3 \\ + 18y^2a_2 - 9y^2a_3 + 36y^2b_2 - 18y^2b_3 + 4xa_2 - 4xa_3 + 5xb_2 - 6xb_3 \\ + 9ya_2 - 8ya_3 + 12yb_2 - 12yb_3 - 2a_1 + a_2 - a_3 - 3b_1 + b_2 - b_3 = 0 \end{aligned} \quad (6E)$$

Looking at the above PDE shows the following are all the terms with $\{x, y\}$ in them.

$$\{x, y\}$$

The following substitution is now made to be able to collect on all terms with $\{x, y\}$ in them

$$\{x = v_1, y = v_2\}$$

The above PDE (6E) now becomes

$$\begin{aligned} 8a_2v_1^2 + 24a_2v_1v_2 + 18a_2v_2^2 - 4a_3v_1^2 - 12a_3v_1v_2 - 9a_3v_2^2 + 16b_2v_1^2 + 48b_2v_1v_2 \\ + 36b_2v_2^2 - 8b_3v_1^2 - 24b_3v_1v_2 - 18b_3v_2^2 + 4a_2v_1 + 9a_2v_2 - 4a_3v_1 - 8a_3v_2 \\ + 5b_2v_1 + 12b_2v_2 - 6b_3v_1 - 12b_3v_2 - 2a_1 + a_2 - a_3 - 3b_1 + b_2 - b_3 = 0 \end{aligned} \quad (7E)$$

Collecting the above on the terms v_i introduced, and these are

$$\{v_1, v_2\}$$

Equation (7E) now becomes

$$\begin{aligned} (8a_2 - 4a_3 + 16b_2 - 8b_3)v_1^2 + (24a_2 - 12a_3 + 48b_2 - 24b_3)v_1v_2 \\ + (4a_2 - 4a_3 + 5b_2 - 6b_3)v_1 + (18a_2 - 9a_3 + 36b_2 - 18b_3)v_2^2 \\ + (9a_2 - 8a_3 + 12b_2 - 12b_3)v_2 - 2a_1 + a_2 - a_3 - 3b_1 + b_2 - b_3 = 0 \end{aligned} \quad (8E)$$

Setting each coefficients in (8E) to zero gives the following equations to solve

$$\begin{aligned} 4a_2 - 4a_3 + 5b_2 - 6b_3 &= 0 \\ 8a_2 - 4a_3 + 16b_2 - 8b_3 &= 0 \\ 9a_2 - 8a_3 + 12b_2 - 12b_3 &= 0 \\ 18a_2 - 9a_3 + 36b_2 - 18b_3 &= 0 \\ 24a_2 - 12a_3 + 48b_2 - 24b_3 &= 0 \\ -2a_1 + a_2 - a_3 - 3b_1 + b_2 - b_3 &= 0 \end{aligned}$$

Solving the above equations for the unknowns gives

$$\begin{aligned} a_1 &= a_1 \\ a_2 &= -8a_1 - 12b_1 \\ a_3 &= -12a_1 - 18b_1 \\ b_1 &= b_1 \\ b_2 &= 4a_1 + 6b_1 \\ b_3 &= 6a_1 + 9b_1 \end{aligned}$$

Substituting the above solution in the anstaz (1E,2E) (using 1 as arbitrary value for any unknown in the RHS) gives

$$\begin{aligned} \xi &= -12x - 18y \\ \eta &= 6x + 9y + 1 \end{aligned}$$

Shifting is now applied to make $\xi = 0$ in order to simplify the rest of the computation

$$\begin{aligned}\eta &= \eta - \omega(x, y) \xi \\ &= 6x + 9y + 1 - \left(-\frac{2x + 3y + 1}{4x + 6y + 1} \right) (-12x - 18y) \\ &= \frac{-2x - 3y + 1}{4x + 6y + 1} \\ \xi &= 0\end{aligned}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \quad (1)$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y} \right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned}S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{-2x-3y+1}{4x+6y+1}} dy\end{aligned}$$

Which results in

$$S = -2y - \ln(2x + 3y - 1)$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y)S_y}{R_x + \omega(x, y)R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{2x + 3y + 1}{4x + 6y + 1}$$

Evaluating all the partial derivatives gives

$$\begin{aligned}R_x &= 1 \\R_y &= 0 \\S_x &= -\frac{2}{2x + 3y - 1} \\S_y &= -2 - \frac{3}{2x + 3y - 1}\end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 1 \tag{2A}$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 1$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = R + c_1 \tag{4}$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$-2y - \ln(2x + 3y - 1) = x + c_1$$

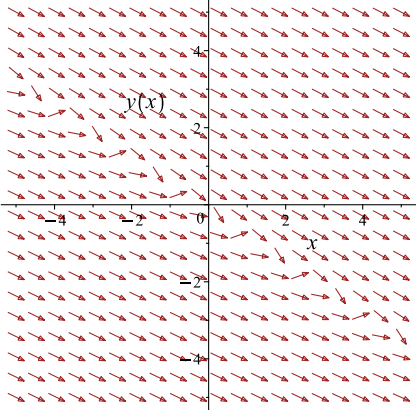
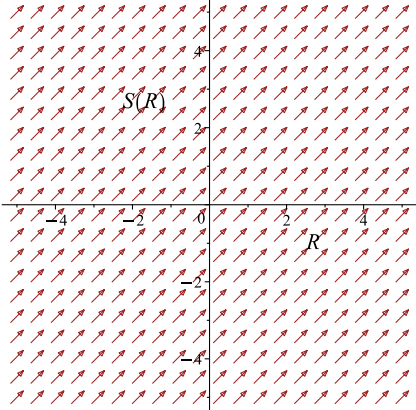
Which simplifies to

$$-2y - \ln(2x + 3y - 1) = x + c_1$$

Which gives

$$y = -\frac{2x}{3} + \frac{\text{LambertW}\left(\frac{2e^{\frac{x}{3} - \frac{2}{3} - c_1}}{3}\right)}{2} + \frac{1}{3}$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{2x+3y+1}{4x+6y+1}$ 	$R = x$ $S = -2y - \ln(2x + 3y - 1)$	$\frac{dS}{dR} = 1$ 

Initial conditions are used to solve for c_1 . Substituting $x = -2$ and $y = 2$ in the above solution gives an equation to solve for the constant of integration.

$$2 = \frac{5}{3} + \frac{\text{LambertW}\left(\frac{2e^{-\frac{4}{3}} - c_1}{3}\right)}{2}$$

$$c_1 = -2$$

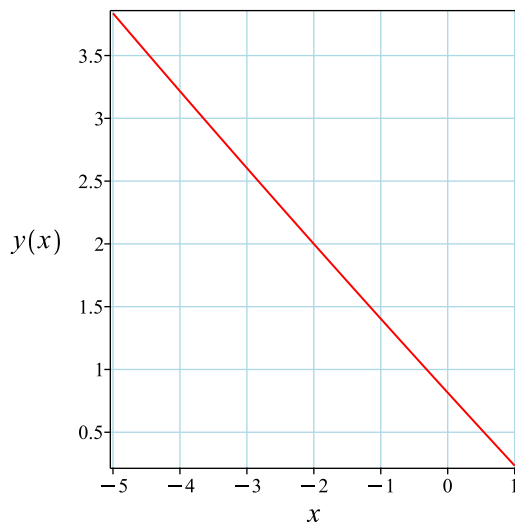
Substituting c_1 found above in the general solution gives

$$y = -\frac{2x}{3} + \frac{\text{LambertW}\left(\frac{2e^{\frac{x}{3} + \frac{4}{3}}}{3}\right)}{2} + \frac{1}{3}$$

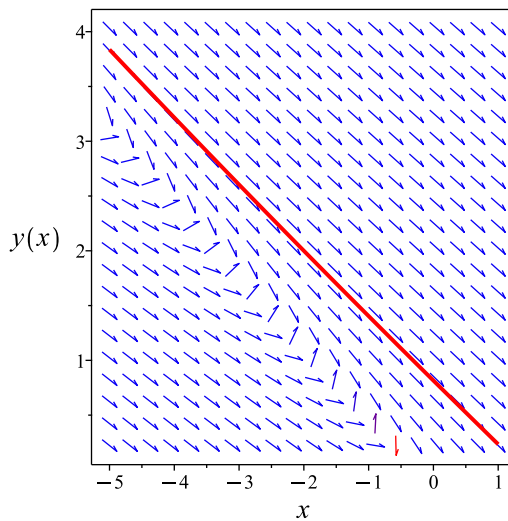
Summary

The solution(s) found are the following

$$y = -\frac{2x}{3} + \frac{\text{LambertW}\left(\frac{2e^{\frac{x}{3} + \frac{4}{3}}}{3}\right)}{2} + \frac{1}{3} \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = -\frac{2x}{3} + \frac{\text{LambertW}\left(\frac{2e^{\frac{x}{3}} + \frac{4}{3}}{3}\right)}{2} + \frac{1}{3}$$

Verified OK.

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
trying separable
trying inverse linear
trying homogeneous types:
trying homogeneous C
1st order, trying the canonical coordinates of the invariance group
<- 1st order, canonical coordinates successful
<- homogeneous successful`

```

✓ Solution by Maple

Time used: 0.156 (sec). Leaf size: 20

```
dsolve([(2*x+3*y(x)+1)+(4*x+6*y(x)+1)*diff(y(x),x)=0,y(-2) = 2],y(x), singsol=all)
```

$$y(x) = \frac{1}{3} - \frac{2x}{3} + \frac{\text{LambertW}\left(\frac{2e^{\frac{4}{3} + \frac{x}{3}}}{3}\right)}{2}$$

✓ Solution by Mathematica

Time used: 4.146 (sec). Leaf size: 30

```
DSolve[{(2*x+3*y[x]+1)+(4*x+6*y[x]+1)*y'[x]==0,{y[-2]==2}},y[x],x,IncludeSingularSolutions -
```

$$y(x) \rightarrow \frac{1}{6} \left(3W\left(\frac{2}{3}e^{\frac{x+4}{3}}\right) - 4x + 2 \right)$$

7.14 problem 14

- 7.14.1 Existence and uniqueness analysis 1708
- 7.14.2 Solving as homogeneousTypeMapleC ode 1709
- 7.14.3 Solving as first order ode lie symmetry calculated ode 1712

Internal problem ID [11712]

Internal file name [OUTPUT/11721_Thursday_April_11_2024_08_49_00_PM_57163841/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 2, Section 2.4. Special integrating factors and transformations. Exercises page 67

Problem number: 14.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "homogeneousTypeMapleC",
"first_order_ode_lie_symmetry_calculated"

Maple gives the following as the ode type

```
[[_homogeneous, `class C`], _rational, [_Abel, `2nd type`, `class A`]]
```

$$3y + (x + y + 1)y' = -4x - 1$$

With initial conditions

$$[y(3) = -4]$$

7.14.1 Existence and uniqueness analysis

This is non linear first order ODE. In canonical form it is written as

$$\begin{aligned} y' &= f(x, y) \\ &= -\frac{4x + 3y + 1}{x + y + 1} \end{aligned}$$

The x domain of $f(x, y)$ when $y = -4$ is

$$\{x < 3 \vee 3 < x\}$$

But the point $x_0 = 3$ is not inside this domain. Hence existence and uniqueness theorem does not apply. There could be infinite number of solutions, or one solution or no solution at all.

7.14.2 Solving as homogeneousTypeMapleC ode

Let $Y = y + y_0$ and $X = x + x_0$ then the above is transformed to new ode in $Y(X)$

$$\frac{d}{dX}Y(X) = -\frac{4X + 4x_0 + 3Y(X) + 3y_0 + 1}{X + x_0 + Y(X) + y_0 + 1}$$

Solving for possible values of x_0 and y_0 which makes the above ode a homogeneous ode results in

$$\begin{aligned}x_0 &= 2 \\y_0 &= -3\end{aligned}$$

Using these values now it is possible to easily solve for $Y(X)$. The above ode now becomes

$$\frac{d}{dX}Y(X) = -\frac{4X + 3Y(X)}{X + Y(X)}$$

In canonical form, the ODE is

$$\begin{aligned}Y' &= F(X, Y) \\ &= -\frac{4X + 3Y}{X + Y}\end{aligned}\tag{1}$$

An ode of the form $Y' = \frac{M(X, Y)}{N(X, Y)}$ is called homogeneous if the functions $M(X, Y)$ and $N(X, Y)$ are both homogeneous functions and of the same order. Recall that a function $f(X, Y)$ is homogeneous of order n if

$$f(t^n X, t^n Y) = t^n f(X, Y)$$

In this case, it can be seen that both $M = -4X - 3Y$ and $N = X + Y$ are both homogeneous and of the same order $n = 1$. Therefore this is a homogeneous ode. Since this ode is homogeneous, it is converted to separable ODE using the substitution $u = \frac{Y}{X}$, or $Y = uX$. Hence

$$\frac{dY}{dX} = \frac{du}{dX}X + u$$

Applying the transformation $Y = uX$ to the above ODE in (1) gives

$$\begin{aligned}\frac{du}{dX}X + u &= \frac{-3u - 4}{u + 1} \\ \frac{du}{dX} &= \frac{\frac{-3u(X)-4}{u(X)+1} - u(X)}{X}\end{aligned}$$

Or

$$\frac{d}{dX}u(X) - \frac{-3u(X)-4 - u(X)}{X} = 0$$

Or

$$\left(\frac{d}{dX}u(X)\right)Xu(X) + \left(\frac{d}{dX}u(X)\right)X + u(X)^2 + 4u(X) + 4 = 0$$

Or

$$X(u(X) + 1) \left(\frac{d}{dX}u(X)\right) + (u(X) + 2)^2 = 0$$

Which is now solved as separable in $u(X)$. Which is now solved in $u(X)$. In canonical form the ODE is

$$\begin{aligned}u' &= F(X, u) \\ &= f(X)g(u) \\ &= -\frac{(u+2)^2}{X(u+1)}\end{aligned}$$

Where $f(X) = -\frac{1}{X}$ and $g(u) = \frac{(u+2)^2}{u+1}$. Integrating both sides gives

$$\begin{aligned}\frac{1}{\frac{(u+2)^2}{u+1}} du &= -\frac{1}{X} dX \\ \int \frac{1}{\frac{(u+2)^2}{u+1}} du &= \int -\frac{1}{X} dX \\ \ln(u+2) + \frac{1}{u+2} &= -\ln(X) + c_2\end{aligned}$$

The solution is

$$\ln(u(X) + 2) + \frac{1}{u(X) + 2} + \ln(X) - c_2 = 0$$

Now u in the above solution is replaced back by Y using $u = \frac{Y}{X}$ which results in the solution

$$\ln\left(\frac{Y(X)}{X} + 2\right) + \frac{1}{\frac{Y(X)}{X} + 2} + \ln(X) - c_2 = 0$$

Using the solution for $Y(X)$

$$\ln\left(\frac{Y(X) + 2X}{X}\right) + \frac{X}{Y(X) + 2X} + \ln(X) - c_2 = 0$$

And replacing back terms in the above solution using

$$Y = y + y_0$$

$$X = x + x_0$$

Or

$$Y = y - 3$$

$$X = x + 2$$

Then the solution in y becomes

$$\ln\left(\frac{2x+y-1}{x-2}\right) + \frac{x-2}{2x+y-1} + \ln(x-2) - c_2 = 0$$

Initial conditions are used to solve for c_2 . Substituting $x = 3$ and $y = -4$ in the above solution gives an equation to solve for the constant of integration.

$$-c_2 + 1 = 0$$

$$c_2 = 1$$

Substituting c_2 found above in the general solution gives

$$\frac{2 \ln\left(\frac{2x+y-1}{x-2}\right) x + \ln\left(\frac{2x+y-1}{x-2}\right) y + 2 \ln(x-2) x + \ln(x-2) y - \ln\left(\frac{2x+y-1}{x-2}\right) - \ln(x-2) - x - y - 1}{2x+y-1} = 0$$

The above simplifies to

$$2 \ln\left(\frac{2x+y-1}{x-2}\right) x + \ln\left(\frac{2x+y-1}{x-2}\right) y + 2 \ln(x-2) x + \ln(x-2) y - \ln\left(\frac{2x+y-1}{x-2}\right) - \ln(x-2)$$

Summary

The solution(s) found are the following

$$(2x+y-1) \ln\left(\frac{2x+y-1}{x-2}\right) + (2x+y-1) \ln(x-2) - x - y - 1 = 0 \quad (1)$$

Verification of solutions

$$(2x+y-1) \ln\left(\frac{2x+y-1}{x-2}\right) + (2x+y-1) \ln(x-2) - x - y - 1 = 0$$

Verified OK.

7.14.3 Solving as first order ode lie symmetry calculated ode

Writing the ode as

$$y' = -\frac{4x + 3y + 1}{x + y + 1}$$

$$y' = \omega(x, y)$$

The condition of Lie symmetry is the linearized PDE given by

$$\eta_x + \omega(\eta_y - \xi_x) - \omega^2 \xi_y - \omega_x \xi - \omega_y \eta = 0 \quad (\text{A})$$

The type of this ode is not in the lookup table. To determine ξ, η then (A) is solved using ansatz. Making bivariate polynomials of degree 1 to use as anstaz gives

$$\xi = xa_2 + ya_3 + a_1 \quad (\text{1E})$$

$$\eta = xb_2 + yb_3 + b_1 \quad (\text{2E})$$

Where the unknown coefficients are

$$\{a_1, a_2, a_3, b_1, b_2, b_3\}$$

Substituting equations (1E,2E) and ω into (A) gives

$$b_2 - \frac{(4x + 3y + 1)(b_3 - a_2)}{x + y + 1} - \frac{(4x + 3y + 1)^2 a_3}{(x + y + 1)^2}$$

$$- \left(-\frac{4}{x + y + 1} + \frac{4x + 3y + 1}{(x + y + 1)^2} \right) (xa_2 + ya_3 + a_1)$$

$$- \left(-\frac{3}{x + y + 1} + \frac{4x + 3y + 1}{(x + y + 1)^2} \right) (xb_2 + yb_3 + b_1) = 0 \quad (\text{5E})$$

Putting the above in normal form gives

$$\frac{4x^2 a_2 - 16x^2 a_3 - 4x^2 b_3 + 8xy a_2 - 24xy a_3 + 2xy b_2 - 8xy b_3 + 3y^2 a_2 - 8y^2 a_3 + y^2 b_2 - 3y^2 b_3 + 8xa_2 - 8xa_3 - 8xb_2 - 8yb_2 + 8ya_2 - 8yb_2 + 8a_1 - 8a_3 + 8b_1 - 8b_3}{(x + y + 1)^2} = 0$$

Setting the numerator to zero gives

$$4x^2 a_2 - 16x^2 a_3 - 4x^2 b_3 + 8xy a_2 - 24xy a_3 + 2xy b_2 - 8xy b_3 + 3y^2 a_2 - 8y^2 a_3 + y^2 b_2 - 3y^2 b_3 + 8xa_2 - 8xa_3 - 8xb_2 - 8yb_2 + 8ya_2 - 8yb_2 + 8a_1 - 8a_3 + 8b_1 - 8b_3 = 0 \quad (\text{6E})$$

Looking at the above PDE shows the following are all the terms with $\{x, y\}$ in them.

$$\{x, y\}$$

The following substitution is now made to be able to collect on all terms with $\{x, y\}$ in them

$$\{x = v_1, y = v_2\}$$

The above PDE (6E) now becomes

$$\begin{aligned} &4a_2v_1^2 + 8a_2v_1v_2 + 3a_2v_2^2 - 16a_3v_1^2 - 24a_3v_1v_2 - 8a_3v_2^2 + 2b_2v_1v_2 + b_2v_2^2 \\ &- 4b_3v_1^2 - 8b_3v_1v_2 - 3b_3v_2^2 + a_1v_2 + 8a_2v_1 + 4a_2v_2 - 8a_3v_1 - 3a_3v_2 - b_1v_1 \\ &+ 4b_2v_1 + 2b_2v_2 - 5b_3v_1 - 2b_3v_2 + 3a_1 + a_2 - a_3 + 2b_1 + b_2 - b_3 = 0 \end{aligned} \quad (7E)$$

Collecting the above on the terms v_i introduced, and these are

$$\{v_1, v_2\}$$

Equation (7E) now becomes

$$\begin{aligned} &(4a_2 - 16a_3 - 4b_3)v_1^2 + (8a_2 - 24a_3 + 2b_2 - 8b_3)v_1v_2 \\ &+ (8a_2 - 8a_3 - b_1 + 4b_2 - 5b_3)v_1 + (3a_2 - 8a_3 + b_2 - 3b_3)v_2^2 \\ &+ (a_1 + 4a_2 - 3a_3 + 2b_2 - 2b_3)v_2 + 3a_1 + a_2 - a_3 + 2b_1 + b_2 - b_3 = 0 \end{aligned} \quad (8E)$$

Setting each coefficients in (8E) to zero gives the following equations to solve

$$\begin{aligned} &4a_2 - 16a_3 - 4b_3 = 0 \\ &3a_2 - 8a_3 + b_2 - 3b_3 = 0 \\ &8a_2 - 24a_3 + 2b_2 - 8b_3 = 0 \\ &a_1 + 4a_2 - 3a_3 + 2b_2 - 2b_3 = 0 \\ &8a_2 - 8a_3 - b_1 + 4b_2 - 5b_3 = 0 \\ &3a_1 + a_2 - a_3 + 2b_1 + b_2 - b_3 = 0 \end{aligned}$$

Solving the above equations for the unknowns gives

$$\begin{aligned} a_1 &= -5a_3 - 2b_3 \\ a_2 &= 4a_3 + b_3 \\ a_3 &= a_3 \\ b_1 &= 8a_3 + 3b_3 \\ b_2 &= -4a_3 \\ b_3 &= b_3 \end{aligned}$$

Substituting the above solution in the anstaz (1E,2E) (using 1 as arbitrary value for any unknown in the RHS) gives

$$\begin{aligned}\xi &= x - 2 \\ \eta &= 3 + y\end{aligned}$$

Shifting is now applied to make $\xi = 0$ in order to simplify the rest of the computation

$$\begin{aligned}\eta &= \eta - \omega(x, y) \xi \\ &= 3 + y - \left(-\frac{4x + 3y + 1}{x + y + 1} \right) (x - 2) \\ &= \frac{4x^2 + 4xy + y^2 - 4x - 2y + 1}{x + y + 1} \\ \xi &= 0\end{aligned}$$

The next step is to determine the canonical coordinates R, S . The canonical coordinates map $(x, y) \rightarrow (R, S)$ where (R, S) are the canonical coordinates which make the original ode become a quadrature and hence solved by integration.

The characteristic pde which is used to find the canonical coordinates is

$$\frac{dx}{\xi} = \frac{dy}{\eta} = dS \quad (1)$$

The above comes from the requirements that $\left(\xi \frac{\partial}{\partial x} + \eta \frac{\partial}{\partial y} \right) S(x, y) = 1$. Starting with the first pair of ode's in (1) gives an ode to solve for the independent variable R in the canonical coordinates, where $S(R)$. Since $\xi = 0$ then in this special case

$$R = x$$

S is found from

$$\begin{aligned}S &= \int \frac{1}{\eta} dy \\ &= \int \frac{1}{\frac{4x^2 + 4xy + y^2 - 4x - 2y + 1}{x + y + 1}} dy\end{aligned}$$

Which results in

$$S = -\frac{-x + 2}{2x + y - 1} + \ln(2x + y - 1)$$

Now that R, S are found, we need to setup the ode in these coordinates. This is done by evaluating

$$\frac{dS}{dR} = \frac{S_x + \omega(x, y) S_y}{R_x + \omega(x, y) R_y} \quad (2)$$

Where in the above R_x, R_y, S_x, S_y are all partial derivatives and $\omega(x, y)$ is the right hand side of the original ode given by

$$\omega(x, y) = -\frac{4x + 3y + 1}{x + y + 1}$$

Evaluating all the partial derivatives gives

$$\begin{aligned} R_x &= 1 \\ R_y &= 0 \\ S_x &= \frac{4x + 3y + 1}{(2x + y - 1)^2} \\ S_y &= \frac{x + y + 1}{(2x + y - 1)^2} \end{aligned}$$

Substituting all the above in (2) and simplifying gives the ode in canonical coordinates.

$$\frac{dS}{dR} = 0 \tag{2A}$$

We now need to express the RHS as function of R only. This is done by solving for x, y in terms of R, S from the result obtained earlier and simplifying. This gives

$$\frac{dS}{dR} = 0$$

The above is a quadrature ode. This is the whole point of Lie symmetry method. It converts an ode, no matter how complicated it is, to one that can be solved by integration when the ode is in the canonical coordinates R, S . Integrating the above gives

$$S(R) = c_1 \tag{4}$$

To complete the solution, we just need to transform (4) back to x, y coordinates. This results in

$$\frac{(2x + y - 1) \ln(2x + y - 1) + x - 2}{2x + y - 1} = c_1$$

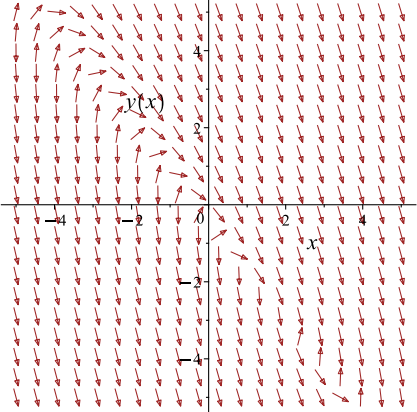
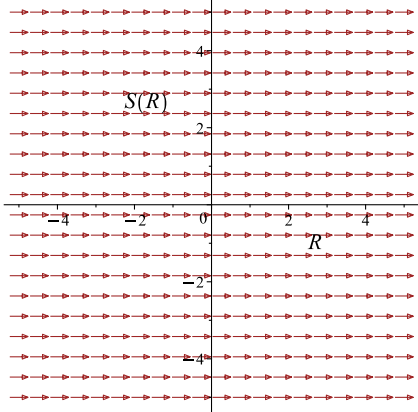
Which simplifies to

$$\frac{(2x + y - 1) \ln(2x + y - 1) + x - 2}{2x + y - 1} = c_1$$

Which gives

$$y = e^{\text{LambertW}(-(x-2)e^{-c_1}) + c_1} - 2x + 1$$

The following diagram shows solution curves of the original ode and how they transform in the canonical coordinates space using the mapping shown.

Original ode in x, y coordinates	Canonical coordinates transformation	ODE in canonical coordinates (R, S)
$\frac{dy}{dx} = -\frac{4x+3y+1}{x+y+1}$ 	$R = x$ $S = \frac{(2x + y - 1) \ln(2x + y - 1)}{2x + y - 1}$	$\frac{dS}{dR} = 0$ 

Initial conditions are used to solve for c_1 . Substituting $x = 3$ and $y = -4$ in the above solution gives an equation to solve for the constant of integration.

$$-4 = \frac{-1 - 5 \text{LambertW}(-e^{-c_1})}{\text{LambertW}(-e^{-c_1})}$$

$$c_1 = 1$$

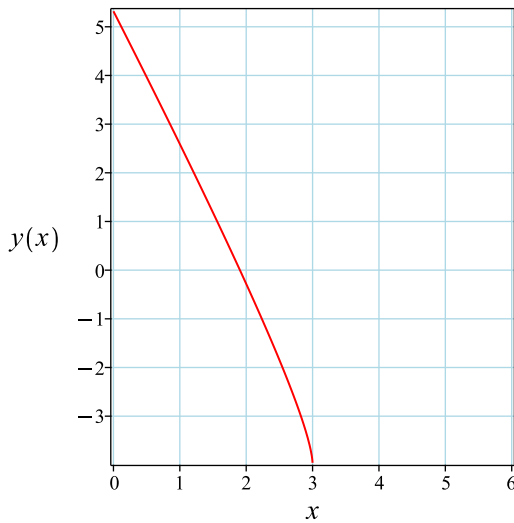
Substituting c_1 found above in the general solution gives

$$y = \frac{-2x \text{LambertW}(-(x-2)e^{-1}) + \text{LambertW}(-(x-2)e^{-1}) - x + 2}{\text{LambertW}(-(x-2)e^{-1})}$$

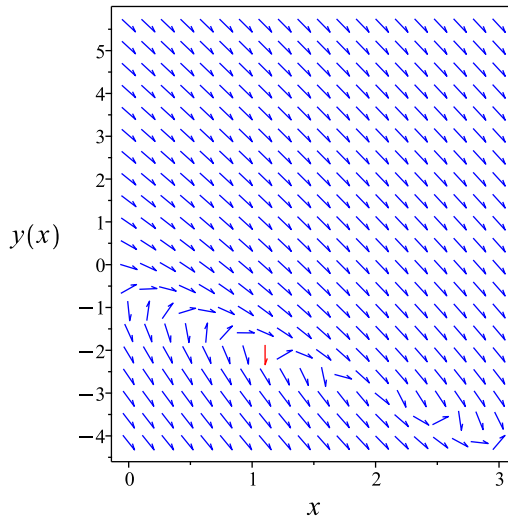
Summary

The solution(s) found are the following

$$y = \frac{-2x \text{LambertW}(-(x-2)e^{-1}) + \text{LambertW}(-(x-2)e^{-1}) - x + 2}{\text{LambertW}(-(x-2)e^{-1})} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \frac{-2x \operatorname{LambertW}(-(x-2)e^{-1}) + \operatorname{LambertW}(-(x-2)e^{-1}) - x + 2}{\operatorname{LambertW}(-(x-2)e^{-1})}$$

Verified OK.

Maple trace

```

`Methods for first order ODEs:
--- Trying classification methods ---
trying a quadrature
trying 1st order linear
trying Bernoulli
trying separable
trying inverse linear
trying homogeneous types:
trying homogeneous C
trying homogeneous types:
trying homogeneous D
<- homogeneous successful
<- homogeneous successful`

```

✓ Solution by Maple

Time used: 0.265 (sec). Leaf size: 39

```
dsolve([(4*x+3*y(x)+1)+(x+y(x)+1)*diff(y(x),x)=0,y(3) = -4],y(x), singsol=all)
```

$$y(x) = \frac{-2x \operatorname{LambertW}(-(x-2)e^{-1}) + \operatorname{LambertW}(-(x-2)e^{-1}) - x + 2}{\operatorname{LambertW}(-(x-2)e^{-1})}$$

✓ Solution by Mathematica

Time used: 65.902 (sec). Leaf size: 197

```
DSolve[{(4*x+3*y[x]+1)+(x+y[x]+1)*y'[x]==0,{y[-2]==2}},y[x],x,IncludeSingularSolutions -> True]
```

$$\text{Solve} \left[\frac{(-2)^{2/3} \left(-2x \log \left(\frac{3(-2)^{2/3}(y(x)+2x-1)}{y(x)+x+1} \right) + (2x-1) \log \left(-\frac{3(-2)^{2/3}(x-2)}{y(x)+x+1} \right) + \log \left(\frac{3(-2)^{2/3}(y(x)+2x-1)}{y(x)+x+1} \right) \right)}{9(y(x)+2x-1)} + \dots \right]$$

8 Chapter 4, Section 4.1. Basic theory of linear differential equations. Exercises page 113

8.1	problem 1 (a)	1720
8.2	problem 1 (b)	1734
8.3	problem 2	1747
8.4	problem 4 (a)	1751
8.5	problem 8	1759
8.6	problem 9	1771
8.7	problem 10	1800
8.8	problem 11	1823
8.9	problem 12	1831
8.10	problem 13	1836

8.1 problem 1 (a)

8.1.1	Existence and uniqueness analysis	1720
8.1.2	Solving as second order linear constant coeff ode	1721
8.1.3	Solving using Kovacic algorithm	1725
8.1.4	Maple step by step solution	1731

Internal problem ID [11713]

Internal file name [OUTPUT/11722_Thursday_April_11_2024_08_49_05_PM_81323681/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.1. Basic theory of linear differential equations. Exercises page 113

Problem number: 1 (a).

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$y'' + 5y' + 6y = e^x$$

With initial conditions

$$[y(0) = 5, y'(0) = 7]$$

8.1.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$p(x) = 5$$

$$q(x) = 6$$

$$F = e^x$$

Hence the ode is

$$y'' + 5y' + 6y = e^x$$

The domain of $p(x) = 5$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = 6$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. The domain of $F = e^x$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

8.1.2 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = 5, C = 6, f(x) = e^x$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 5y' + 6y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 5, C = 6$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + 5\lambda e^{\lambda x} + 6e^{\lambda x} = 0 \tag{1}$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 5\lambda + 6 = 0 \tag{2}$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 5, C = 6$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{-5}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{5^2 - (4)(1)(6)} \\ &= -\frac{5}{2} \pm \frac{1}{2} \end{aligned}$$

Hence

$$\begin{aligned} \lambda_1 &= -\frac{5}{2} + \frac{1}{2} \\ \lambda_2 &= -\frac{5}{2} - \frac{1}{2} \end{aligned}$$

Which simplifies to

$$\begin{aligned} \lambda_1 &= -2 \\ \lambda_2 &= -3 \end{aligned}$$

Since roots are real and distinct, then the solution is

$$\begin{aligned} y &= c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x} \\ y &= c_1 e^{(-2)x} + c_2 e^{(-3)x} \end{aligned}$$

Or

$$y = c_1 e^{-2x} + c_2 e^{-3x}$$

Therefore the homogeneous solution y_h is

$$y_h = c_1 e^{-2x} + c_2 e^{-3x}$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$e^x$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{e^x\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^{-3x}, e^{-2x}\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1 e^x$$

The unknowns $\{A_1\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$12A_1 e^x = e^x$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = \frac{1}{12} \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = \frac{e^x}{12}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 e^{-2x} + c_2 e^{-3x}) + \left(\frac{e^x}{12} \right) \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{-2x} + c_2 e^{-3x} + \frac{e^x}{12} \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 5$ and $x = 0$ in the above gives

$$5 = c_1 + c_2 + \frac{1}{12} \quad (1A)$$

Taking derivative of the solution gives

$$y' = -2c_1e^{-2x} - 3c_2e^{-3x} + \frac{e^x}{12}$$

substituting $y' = 7$ and $x = 0$ in the above gives

$$7 = -2c_1 - 3c_2 + \frac{1}{12} \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = \frac{65}{3}$$
$$c_2 = -\frac{67}{4}$$

Substituting these values back in above solution results in

$$y = \frac{65 e^{-2x}}{3} - \frac{67 e^{-3x}}{4} + \frac{e^x}{12}$$

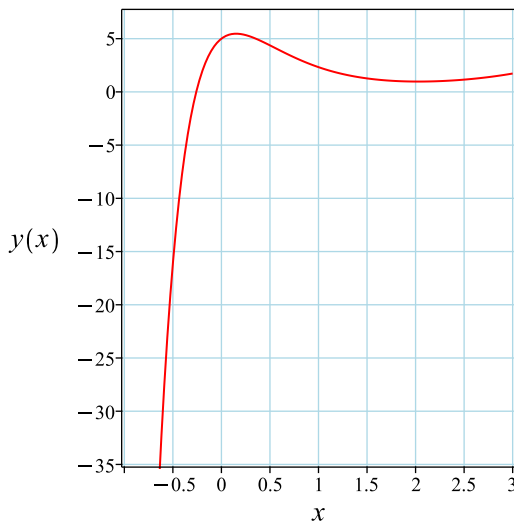
Which simplifies to

$$y = \frac{(e^{4x} + 260 e^x - 201) e^{-3x}}{12}$$

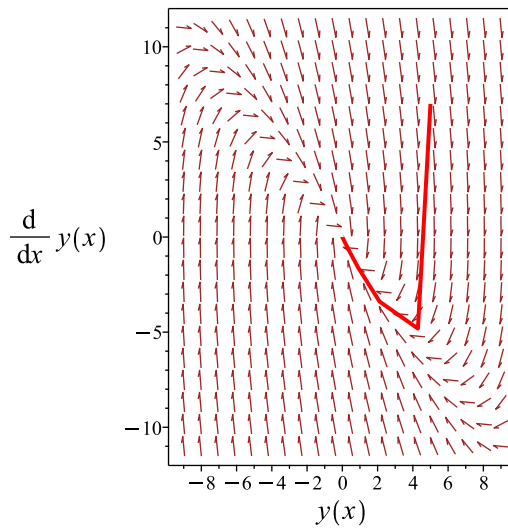
Summary

The solution(s) found are the following

$$y = \frac{(e^{4x} + 260 e^x - 201) e^{-3x}}{12} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \frac{(e^{4x} + 260 e^x - 201) e^{-3x}}{12}$$

Verified OK.

8.1.3 Solving using Kovacic algorithm

Writing the ode as

$$y'' + 5y' + 6y = 0 \tag{1}$$

$$Ay'' + By' + Cy = 0 \tag{2}$$

Comparing (1) and (2) shows that

$$A = 1$$

$$B = 5 \tag{3}$$

$$C = 6$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$r = \frac{s}{t} \tag{5}$$

$$= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{1}{4} \tag{6}$$

Comparing the above to (5) shows that

$$s = 1$$

$$t = 4$$

Therefore eq. (4) becomes

$$z''(x) = \frac{z(x)}{4} \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 252: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned}O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0\end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = \frac{1}{4}$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = e^{-\frac{x}{2}}$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned}y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{5}{1} dx} \\ &= z_1 e^{-\frac{5x}{2}} \\ &= z_1 \left(e^{-\frac{5x}{2}} \right)\end{aligned}$$

Which simplifies to

$$y_1 = e^{-3x}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{5}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{-5x}}{(y_1)^2} dx \\ &= y_1(e^x)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (e^{-3x}) + c_2 (e^{-3x}(e^x))\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 5y' + 6y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1 e^{-3x} + c_2 e^{-2x}$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$e^x$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{e^x\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^{-3x}, e^{-2x}\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1 e^x$$

The unknowns $\{A_1\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$12A_1 e^x = e^x$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = \frac{1}{12} \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = \frac{e^x}{12}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 e^{-3x} + c_2 e^{-2x}) + \left(\frac{e^x}{12} \right) \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{-3x} + c_2 e^{-2x} + \frac{e^x}{12} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 5$ and $x = 0$ in the above gives

$$5 = c_1 + c_2 + \frac{1}{12} \quad (1A)$$

Taking derivative of the solution gives

$$y' = -3c_1 e^{-3x} - 2c_2 e^{-2x} + \frac{e^x}{12}$$

substituting $y' = 7$ and $x = 0$ in the above gives

$$7 = -3c_1 - 2c_2 + \frac{1}{12} \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$\begin{aligned} c_1 &= -\frac{67}{4} \\ c_2 &= \frac{65}{3} \end{aligned}$$

Substituting these values back in above solution results in

$$y = \frac{65 e^{-2x}}{3} - \frac{67 e^{-3x}}{4} + \frac{e^x}{12}$$

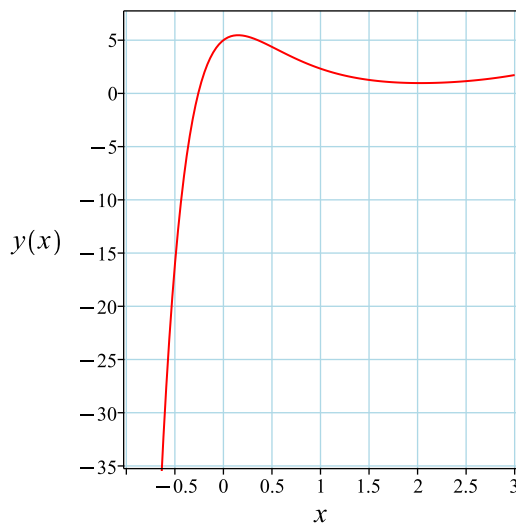
Which simplifies to

$$y = \frac{(e^{4x} + 260 e^x - 201) e^{-3x}}{12}$$

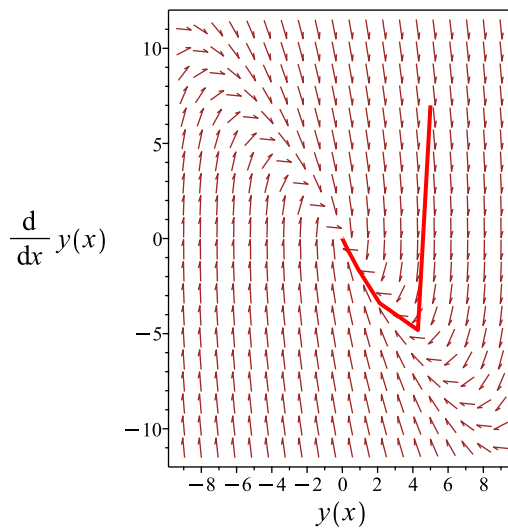
Summary

The solution(s) found are the following

$$y = \frac{(e^{4x} + 260 e^x - 201) e^{-3x}}{12} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \frac{(e^{4x} + 260 e^x - 201) e^{-3x}}{12}$$

Verified OK.

8.1.4 Maple step by step solution

Let's solve

$$\left[y'' + 5y' + 6y = e^x, y(0) = 5, y'|_{\{x=0\}} = 7 \right]$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of homogeneous ODE

$$r^2 + 5r + 6 = 0$$

- Factor the characteristic polynomial

$$(r + 3)(r + 2) = 0$$

- Roots of the characteristic polynomial

$$r = (-3, -2)$$

- 1st solution of the homogeneous ODE

$$y_1(x) = e^{-3x}$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = e^{-2x}$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = c_1 e^{-3x} + c_2 e^{-2x} + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = e^x \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} e^{-3x} & e^{-2x} \\ -3e^{-3x} & -2e^{-2x} \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = e^{-5x}$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = -e^{-3x} \left(\int e^{4x} dx \right) + e^{-2x} \left(\int e^{3x} dx \right)$$

- Compute integrals

$$y_p(x) = \frac{e^x}{12}$$

- Substitute particular solution into general solution to ODE

$$y = c_1 e^{-3x} + c_2 e^{-2x} + \frac{e^x}{12}$$

- Check validity of solution $y = c_1 e^{-3x} + c_2 e^{-2x} + \frac{e^x}{12}$

- Use initial condition $y(0) = 5$

$$5 = c_1 + c_2 + \frac{1}{12}$$

- Compute derivative of the solution

$$y' = -3c_1 e^{-3x} - 2c_2 e^{-2x} + \frac{e^x}{12}$$

- Use the initial condition $y' \Big|_{\{x=0\}} = 7$

$$7 = -3c_1 - 2c_2 + \frac{1}{12}$$

- Solve for c_1 and c_2

$$\left\{ c_1 = -\frac{67}{4}, c_2 = \frac{65}{3} \right\}$$

- Substitute constant values into general solution and simplify

$$y = \frac{(e^{4x} + 260e^x - 201)e^{-3x}}{12}$$

- Solution to the IVP

$$y = \frac{(e^{4x} + 260e^x - 201)e^{-3x}}{12}$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
trying a double symmetry of the form [xi=0, eta=F(x)]
-> Try solving first the homogeneous part of the ODE
    checking if the LODE has constant coefficients
    <- constant coefficients successful
<- solving first the homogeneous part of the ODE successful`

```

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 20

```
dsolve([diff(y(x),x$2)+5*diff(y(x),x)+6*y(x)=exp(x),y(0) = 5, D(y)(0) = 7],y(x), singsol=all
```

$$y(x) = \frac{(e^{4x} + 260e^x - 201)e^{-3x}}{12}$$

✓ Solution by Mathematica

Time used: 0.057 (sec). Leaf size: 26

```
DSolve[{y''[x]+5*y'[x]+6*y[x]==Exp[x],{y[0]==5,y'[0]==7}},y[x],x,IncludeSingularSolutions ->
```

$$y(x) \rightarrow \frac{1}{12}e^{-3x}(260e^x + e^{4x} - 201)$$

8.2 problem 1 (b)

8.2.1 Solving as second order linear constant coeff ode	1734
8.2.2 Solving using Kovacic algorithm	1738
8.2.3 Maple step by step solution	1744

Internal problem ID [11714]

Internal file name [OUTPUT/11723_Thursday_April_11_2024_08_49_06_PM_48965104/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.1. Basic theory of linear differential equations. Exercises page 113

Problem number: 1 (b).

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$y'' + 5y' + 6y = e^x$$

With initial conditions

$$[y(0) = 5, y'(1) = 7]$$

8.2.1 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = 5, C = 6, f(x) = e^x$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 5y' + 6y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 5, C = 6$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + 5\lambda e^{\lambda x} + 6e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 5\lambda + 6 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 5, C = 6$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{-5}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{5^2 - (4)(1)(6)} \\ &= -\frac{5}{2} \pm \frac{1}{2} \end{aligned}$$

Hence

$$\begin{aligned} \lambda_1 &= -\frac{5}{2} + \frac{1}{2} \\ \lambda_2 &= -\frac{5}{2} - \frac{1}{2} \end{aligned}$$

Which simplifies to

$$\begin{aligned} \lambda_1 &= -2 \\ \lambda_2 &= -3 \end{aligned}$$

Since roots are real and distinct, then the solution is

$$\begin{aligned} y &= c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x} \\ y &= c_1 e^{(-2)x} + c_2 e^{(-3)x} \end{aligned}$$

Or

$$y = c_1 e^{-2x} + c_2 e^{-3x}$$

Therefore the homogeneous solution y_h is

$$y_h = c_1 e^{-2x} + c_2 e^{-3x}$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$e^x$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{e^x\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^{-3x}, e^{-2x}\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1 e^x$$

The unknowns $\{A_1\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$12A_1 e^x = e^x$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = \frac{1}{12} \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = \frac{e^x}{12}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 e^{-2x} + c_2 e^{-3x}) + \left(\frac{e^x}{12} \right) \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{-2x} + c_2 e^{-3x} + \frac{e^x}{12} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 5$ and $x = 0$ in the above gives

$$5 = c_1 + c_2 + \frac{1}{12} \quad (1A)$$

Taking derivative of the solution gives

$$y' = -2c_1 e^{-2x} - 3c_2 e^{-3x} + \frac{e^x}{12}$$

substituting $y' = 7$ and $x = 1$ in the above gives

$$7 = \frac{(e^4 - 24ec_1 - 36c_2)e^{-3}}{12} \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = \frac{e^4 - 84e^3 - 177}{24e - 36}$$

$$c_2 = \frac{(-e^3 + 84e^2 + 118)e}{24e - 36}$$

Substituting these values back in above solution results in

$$y = \frac{171e^{4-3x} - 252e^{3-3x} - 2e^{-3x+5} + 236e^{-3x+2} + 2e^{-2x+5} - 171e^{-2x+4} + 4e^{x+2} - 354e^{-2x+1} - 354e^{-2x}}{48e^2 - 144e + 108}$$

Which simplifies to

$$y = \frac{(354e^{1-x} + 171e^4 - 252e^3 + 12e^{3x+1} - 9e^{3x} - 171e^{4-x} + 252e^{-x+3} + 2e^{-x+5} - 236e^{-x+2} - 2e^5 - 354e^{-2x})}{48e^2 - 144e + 108}$$

Summary

The solution(s) found are the following

$$y = \frac{(354e^{1-x} + 171e^4 - 252e^3 + 12e^{3x+1} - 9e^{3x} - 171e^{4-x} + 252e^{-x+3} + 2e^{-x+5} - 236e^{-x+2} - 2e^5 - 354e^{-2x})}{48e^2 - 144e + 108} \quad (1)$$

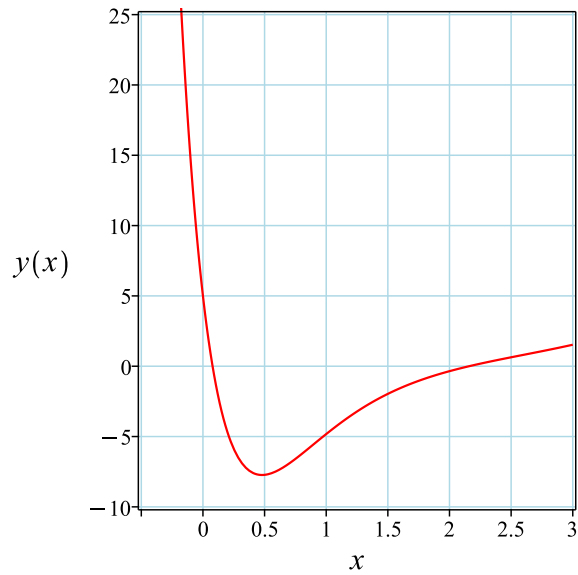


Figure 331: Solution plot

Verification of solutions

$$y = \frac{(354 e^{1-x} + 171 e^4 - 252 e^3 + 12 e^{3x+1} - 9 e^{3x} - 171 e^{4-x} + 252 e^{-x+3} + 2 e^{-x+5} - 236 e^{-x+2} - 2 e^5 - 48 e^2 - 144 e + 108)}{48 e^2 - 144 e + 108}$$

Verified OK.

8.2.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' + 5y' + 6y = 0 \tag{1}$$

$$Ay'' + By' + Cy = 0 \tag{2}$$

Comparing (1) and (2) shows that

$$A = 1$$

$$B = 5 \tag{3}$$

$$C = 6$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$r = \frac{s}{t} \tag{5}$$

$$= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{1}{4} \tag{6}$$

Comparing the above to (5) shows that

$$s = 1$$

$$t = 4$$

Therefore eq. (4) becomes

$$z''(x) = \frac{z(x)}{4} \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 254: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned}O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0\end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = \frac{1}{4}$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = e^{-\frac{x}{2}}$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned}y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{5}{1} dx} \\ &= z_1 e^{-\frac{5x}{2}} \\ &= z_1 \left(e^{-\frac{5x}{2}} \right)\end{aligned}$$

Which simplifies to

$$y_1 = e^{-3x}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{5}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{-5x}}{(y_1)^2} dx \\ &= y_1(e^x)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (e^{-3x}) + c_2 (e^{-3x}(e^x))\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 5y' + 6y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1 e^{-3x} + c_2 e^{-2x}$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$e^x$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{e^x\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^{-3x}, e^{-2x}\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1 e^x$$

The unknowns $\{A_1\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$12A_1 e^x = e^x$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = \frac{1}{12} \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = \frac{e^x}{12}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 e^{-3x} + c_2 e^{-2x}) + \left(\frac{e^x}{12} \right) \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{-3x} + c_2 e^{-2x} + \frac{e^x}{12} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 5$ and $x = 0$ in the above gives

$$5 = c_1 + c_2 + \frac{1}{12} \quad (1A)$$

Taking derivative of the solution gives

$$y' = -3c_1 e^{-3x} - 2c_2 e^{-2x} + \frac{e^x}{12}$$

substituting $y' = 7$ and $x = 1$ in the above gives

$$7 = \frac{(e^4 - 24c_2 e - 36c_1) e^{-3}}{12} \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$\begin{aligned} c_1 &= \frac{(-e^3 + 84e^2 + 118)e}{24e - 36} \\ c_2 &= \frac{e^4 - 84e^3 - 177}{24e - 36} \end{aligned}$$

Substituting these values back in above solution results in

$$y = \frac{171 e^{4-3x} - 252 e^{3-3x} - 2 e^{-3x+5} + 236 e^{-3x+2} + 2 e^{-2x+5} - 171 e^{-2x+4} + 4 e^{x+2} - 354 e^{-2x+1} - 354 e^{-x+5}}{48 e^2 - 144 e + 108}$$

Which simplifies to

$$y = \frac{(354 e^{1-x} + 171 e^4 - 252 e^3 + 12 e^{3x+1} - 9 e^{3x} - 171 e^{4-x} + 252 e^{-x+3} + 2 e^{-x+5} - 236 e^{-x+2} - 2 e^5 - 354 e^{-x+1})}{48 e^2 - 144 e + 108}$$

Summary

The solution(s) found are the following

$$y = \frac{(354 e^{1-x} + 171 e^4 - 252 e^3 + 12 e^{3x+1} - 9 e^{3x} - 171 e^{4-x} + 252 e^{-x+3} + 2 e^{-x+5} - 236 e^{-x+2} - 2 e^5 - 354 e^{-x+1})}{48 e^2 - 144 e + 108} \quad (1)$$

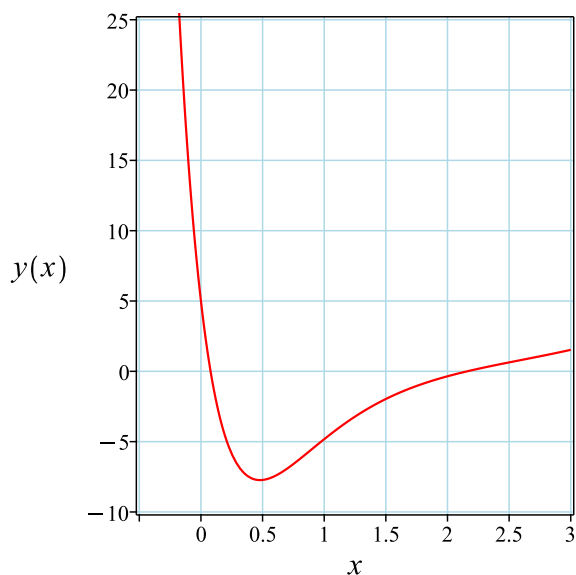


Figure 332: Solution plot

Verification of solutions

$$y = \frac{(354 e^{1-x} + 171 e^4 - 252 e^3 + 12 e^{3x+1} - 9 e^{3x} - 171 e^{4-x} + 252 e^{-x+3} + 2 e^{-x+5} - 236 e^{-x+2} - 2 e^5 - 354 e^{-x+1})}{48 e^2 - 144 e + 108}$$

Verified OK.

8.2.3 Maple step by step solution

Let's solve

$$\left[y'' + 5y' + 6y = e^x, y(0) = 5, y' \Big|_{\{x=1\}} = 7 \right]$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of homogeneous ODE

$$r^2 + 5r + 6 = 0$$

- Factor the characteristic polynomial

$$(r + 3)(r + 2) = 0$$

- Roots of the characteristic polynomial

$$r = (-3, -2)$$

- 1st solution of the homogeneous ODE

$$y_1(x) = e^{-3x}$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = e^{-2x}$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = c_1 e^{-3x} + c_2 e^{-2x} + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x), y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x), y_2(x))} dx \right), f(x) = e^x \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} e^{-3x} & e^{-2x} \\ -3e^{-3x} & -2e^{-2x} \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = e^{-5x}$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = -e^{-3x} \left(\int e^{4x} dx \right) + e^{-2x} \left(\int e^{3x} dx \right)$$

- Compute integrals

$$y_p(x) = \frac{e^x}{12}$$

- Substitute particular solution into general solution to ODE

$$y = c_1 e^{-3x} + c_2 e^{-2x} + \frac{e^x}{12}$$

- Check validity of solution $y = c_1 e^{-3x} + c_2 e^{-2x} + \frac{e^x}{12}$

- Use initial condition $y(0) = 5$

$$5 = c_1 + c_2 + \frac{1}{12}$$

- Compute derivative of the solution

$$y' = -3c_1 e^{-3x} - 2c_2 e^{-2x} + \frac{e^x}{12}$$

- Use the initial condition $y' \Big|_{\{x=1\}} = 7$

$$7 = -3c_1 e^{-3} - 2c_2 e^{-2} + \frac{e}{12}$$

- Solve for c_1 and c_2

$$\left\{ c_1 = \frac{118e^{-2} - e + 84}{12(2e^{-2} - 3e^{-3})}, c_2 = -\frac{-e + 177e^{-3} + 84}{12(2e^{-2} - 3e^{-3})} \right\}$$

- Substitute constant values into general solution and simplify

$$y = \frac{(e^{x+4} + 2e^{4x+1} - e^4 - 84e^{x+3} - 3e^{4x} + 84e^3 + 118e - 177e^x)e^{-3x}}{24e^{-36}}$$

- Solution to the IVP

$$y = \frac{(e^{x+4} + 2e^{4x+1} - e^4 - 84e^{x+3} - 3e^{4x} + 84e^3 + 118e - 177e^x)e^{-3x}}{24e^{-36}}$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
trying a double symmetry of the form [xi=0, eta=F(x)]
-> Try solving first the homogeneous part of the ODE
    checking if the LODE has constant coefficients
    <- constant coefficients successful
<- solving first the homogeneous part of the ODE successful`

```

✓ Solution by Maple

Time used: 0.125 (sec). Leaf size: 55

```
dsolve([diff(y(x),x$2)+5*diff(y(x),x)+6*y(x)=exp(x),y(0) = 5, D(y)(1) = 7],y(x), singsol=all
```

$$y(x) = \frac{(-e^{4-x} + 84e^{3-x} + e^4 + 2e^{3x+1} - 84e^3 + 118e^{1-x} - 3e^{3x} - 177)e^{-2x}}{24e - 36}$$

✓ Solution by Mathematica

Time used: 0.022 (sec). Leaf size: 68

```
DSolve[{y'[x]+5*y'[x]+6*y[x]==Exp[x],{y[0]==5,y'[1]==7}},y[x],x,IncludeSingularSolutions ->
```

$$y(x) \rightarrow \frac{e^{-3x}(-177e^x - 3e^{4x} - 84e^{x+3} + e^{x+4} + 2e^{4x+1} + 118e + 84e^3 - e^4)}{12(2e - 3)}$$

8.3 problem 2

8.3.1 Existence and uniqueness analysis	1747
8.3.2 Maple step by step solution	1748

Internal problem ID [11715]

Internal file name [OUTPUT/11724_Thursday_April_11_2024_08_49_07_PM_26398801/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.1. Basic theory of linear differential equations. Exercises page 113

Problem number: 2.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "**unknown**"

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

Unable to solve or complete the solution.

$$y'' + y'x + x^2y = 0$$

With initial conditions

$$[y(1) = 0, y'(1) = 0]$$

8.3.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$p(x) = x$$

$$q(x) = x^2$$

$$F = 0$$

Hence the ode is

$$y'' + y'x + x^2y = 0$$

The domain of $p(x) = x$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 1$ is inside this domain. The domain of $q(x) = x^2$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 1$ is also inside this domain. Hence solution exists and is unique.

8.3.2 Maple step by step solution

Let's solve

$$\left[y'' + y'x + x^2y = 0, y(1) = 0, y'|_{\{x=1\}} = 0 \right]$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Assume series solution for y

$$y = \sum_{k=0}^{\infty} a_k x^k$$

- Rewrite ODE with series expansions

- Convert $x^2 \cdot y$ to series expansion

$$x^2 \cdot y = \sum_{k=0}^{\infty} a_k x^{k+2}$$

- Shift index using $k- > k - 2$

$$x^2 \cdot y = \sum_{k=2}^{\infty} a_{k-2} x^k$$

- Convert $x \cdot y'$ to series expansion

$$x \cdot y' = \sum_{k=0}^{\infty} a_k k x^k$$

- Convert y'' to series expansion

$$y'' = \sum_{k=2}^{\infty} a_k k(k-1) x^{k-2}$$

- Shift index using $k \rightarrow k+2$

$$y'' = \sum_{k=0}^{\infty} a_{k+2}(k+2)(k+1)x^k$$

Rewrite ODE with series expansions

$$2a_2 + (6a_3 + a_1)x + \left(\sum_{k=2}^{\infty} (a_{k+2}(k+2)(k+1) + a_k k + a_{k-2}) x^k \right) = 0$$

- The coefficients of each power of x must be 0
 $[2a_2 = 0, 6a_3 + a_1 = 0]$
- Solve for the dependent coefficient(s)
 $\{a_2 = 0, a_3 = -\frac{a_1}{6}\}$
- Each term in the series must be 0, giving the recursion relation
 $(k^2 + 3k + 2)a_{k+2} + a_k k + a_{k-2} = 0$
- Shift index using $k \rightarrow k+2$
 $((k+2)^2 + 3k + 8)a_{k+4} + a_{k+2}(k+2) + a_k = 0$
- Recursion relation that defines the series solution to the ODE
 $\left[y = \sum_{k=0}^{\infty} a_k x^k, a_{k+4} = -\frac{ka_{k+2} + a_k + 2a_{k+2}}{k^2 + 7k + 12}, a_2 = 0, a_3 = -\frac{a_1}{6} \right]$

Maple trace

```
`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
trying a symmetry of the form [xi=0, eta=F(x)]
checking if the LODE is missing y
-> Trying a Liouvillian solution using Kovacic's algorithm
<- No Liouvillian solutions exist
-> Trying a solution in terms of special functions:
  -> Bessel
  -> elliptic
  -> Legendre
  -> Kummer
      -> hyper3: Equivalence to 1F1 under a power @ Moebius
      <- hyper3 successful: received ODE is equivalent to the 1F1 ODE
      <- Kummer successful
<- special function solution successful`
```

✓ Solution by Maple

Time used: 0.641 (sec). Leaf size: 5

```
dsolve([diff(y(x),x$2)+x*diff(y(x),x)+x^2*y(x)=0,y(1) = 0, D(y)(1) = 0],y(x), singsol=all)
```

$$y(x) = 0$$

✓ Solution by Mathematica

Time used: 0.101 (sec). Leaf size: 6

```
DSolve[{y'[x]+x*y'[x]+x^2*y[x]==0,{y[1]==0,y'[1]==0}},y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow 0$$

8.4 problem 4 (a)

- 8.4.1 Solving as second order linear constant coeff ode 1751
- 8.4.2 Solving using Kovacic algorithm 1753
- 8.4.3 Maple step by step solution 1757

Internal problem ID [11716]

Internal file name [OUTPUT/11725_Thursday_April_11_2024_08_49_08_PM_4293718/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.1. Basic theory of linear differential equations. Exercises page 113

Problem number: 4 (a).

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _missing_x]]
```

$$y'' - 4y' + 3y = 0$$

8.4.1 Solving as second order linear constant coeff ode

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = -4, C = 3$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} - 4\lambda e^{\lambda x} + 3e^{\lambda x} = 0 \tag{1}$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 - 4\lambda + 3 = 0 \tag{2}$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = -4, C = 3$ into the above gives

$$\begin{aligned}\lambda_{1,2} &= \frac{4}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{-4^2 - (4)(1)(3)} \\ &= 2 \pm 1\end{aligned}$$

Hence

$$\lambda_1 = 2 + 1$$

$$\lambda_2 = 2 - 1$$

Which simplifies to

$$\lambda_1 = 3$$

$$\lambda_2 = 1$$

Since roots are real and distinct, then the solution is

$$y = c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x}$$

$$y = c_1 e^{(3)x} + c_2 e^{(1)x}$$

Or

$$y = c_1 e^{3x} + c_2 e^x$$

Summary

The solution(s) found are the following

$$y = c_1 e^{3x} + c_2 e^x \tag{1}$$

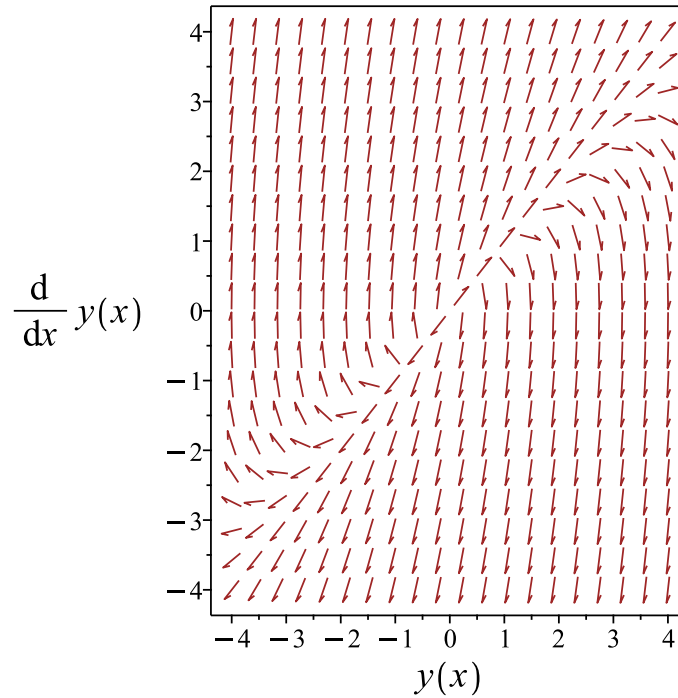


Figure 333: Slope field plot

Verification of solutions

$$y = c_1 e^{3x} + c_2 e^x$$

Verified OK.

8.4.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' - 4y' + 3y = 0 \tag{1}$$

$$Ay'' + By' + Cy = 0 \tag{2}$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= -4 \\ C &= 3 \end{aligned} \tag{3}$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$r = \frac{s}{t} = \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{1}{1} \tag{6}$$

Comparing the above to (5) shows that

$$s = 1$$

$$t = 1$$

Therefore eq. (4) becomes

$$z''(x) = z(x) \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 257: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = 1$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = e^{-x}$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-4}{1} dx} \\ &= z_1 e^{2x} \\ &= z_1 (e^{2x}) \end{aligned}$$

Which simplifies to

$$y_1 = e^x$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{-4}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{4x}}{(y_1)^2} dx \\ &= y_1 \left(\frac{e^{2x}}{2} \right) \end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1(e^x) + c_2\left(e^x\left(\frac{e^{2x}}{2}\right)\right)\end{aligned}$$

Summary

The solution(s) found are the following

$$y = e^x c_1 + \frac{e^{3x} c_2}{2} \tag{1}$$

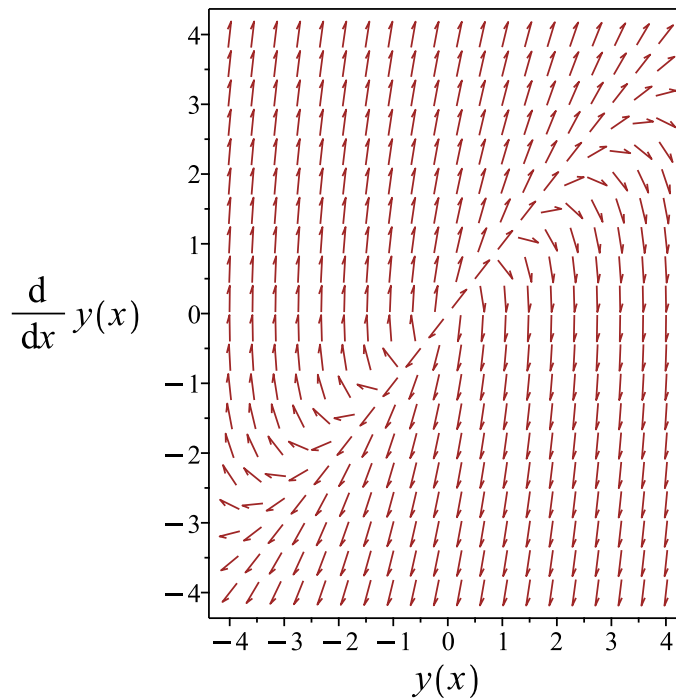


Figure 334: Slope field plot

Verification of solutions

$$y = e^x c_1 + \frac{e^{3x} c_2}{2}$$

Verified OK.

8.4.3 Maple step by step solution

Let's solve

$$y'' - 4y' + 3y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of ODE

$$r^2 - 4r + 3 = 0$$

- Factor the characteristic polynomial

$$(r - 1)(r - 3) = 0$$

- Roots of the characteristic polynomial

$$r = (1, 3)$$

- 1st solution of the ODE

$$y_1(x) = e^x$$

- 2nd solution of the ODE

$$y_2(x) = e^{3x}$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x)$$

- Substitute in solutions

$$y = e^x c_1 + e^{3x} c_2$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
<- constant coefficients successful`
```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 15

```
dsolve(diff(y(x),x$2)-4*diff(y(x),x)+3*y(x)=0,y(x), singsol=all)
```

$$y(x) = c_1 e^x + c_2 e^{3x}$$

✓ Solution by Mathematica

Time used: 0.011 (sec). Leaf size: 20

```
DSolve[y''[x]-4*y'[x]+3*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^x (c_2 e^{2x} + c_1)$$

8.5 problem 8

8.5.1	Existence and uniqueness analysis	1760
8.5.2	Solving as second order linear constant coeff ode	1760
8.5.3	Solving as linear second order ode solved by an integrating factor ode	1762
8.5.4	Solving using Kovacic algorithm	1764
8.5.5	Maple step by step solution	1768

Internal problem ID [11717]

Internal file name [OUTPUT/11726_Thursday_April_11_2024_08_49_08_PM_4170906/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.1. Basic theory of linear differential equations. Exercises page 113

Problem number: 8.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff", "linear_second_order_ode_solved_by_an_integrating_factor"

Maple gives the following as the ode type

```
[[_2nd_order, _missing_x]]
```

$$y'' - 2y' + y = 0$$

With initial conditions

$$[y(0) = 1, y'(0) = 4]$$

8.5.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$p(x) = -2$$

$$q(x) = 1$$

$$F = 0$$

Hence the ode is

$$y'' - 2y' + y = 0$$

The domain of $p(x) = -2$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = 1$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

8.5.2 Solving as second order linear constant coeff ode

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = -2, C = 1$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} - 2\lambda e^{\lambda x} + e^{\lambda x} = 0 \tag{1}$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 - 2\lambda + 1 = 0 \tag{2}$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = -2, C = 1$ into the above gives

$$\begin{aligned}\lambda_{1,2} &= \frac{2}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{(-2)^2 - (4)(1)(1)} \\ &= 1\end{aligned}$$

Hence this is the case of a double root $\lambda_{1,2} = -1$. Therefore the solution is

$$y = c_1 e^x + c_2 x e^x \quad (1)$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = e^x c_1 + c_2 x e^x \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 1$ and $x = 0$ in the above gives

$$1 = c_1 \quad (1A)$$

Taking derivative of the solution gives

$$y' = e^x c_1 + c_2 e^x + c_2 x e^x$$

substituting $y' = 4$ and $x = 0$ in the above gives

$$4 = c_1 + c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 1$$

$$c_2 = 3$$

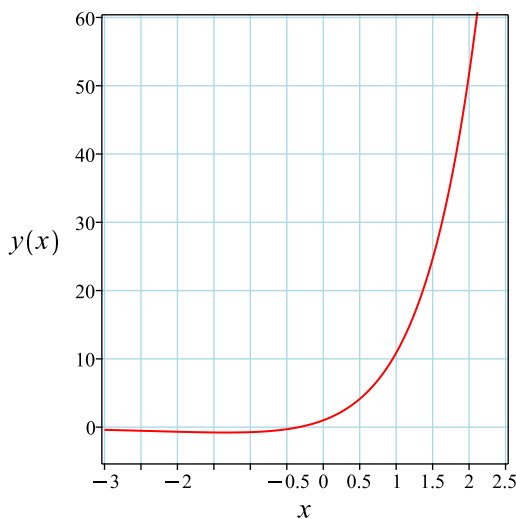
Substituting these values back in above solution results in

$$y = 3x e^x + e^x$$

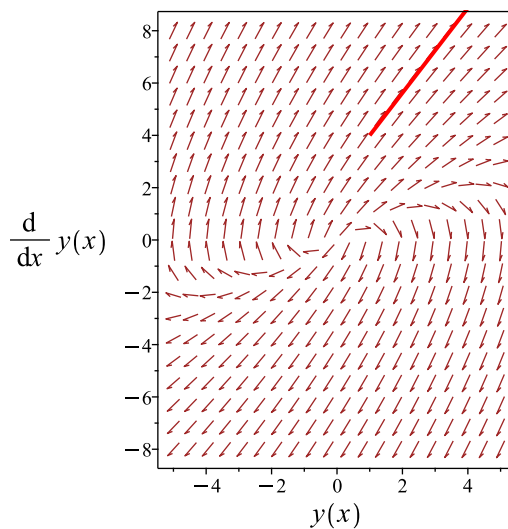
Summary

The solution(s) found are the following

$$y = 3x e^x + e^x \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = 3x e^x + e^x$$

Verified OK.

8.5.3 Solving as linear second order ode solved by an integrating factor ode

The ode satisfies this form

$$y'' + p(x) y' + \frac{(p(x))^2 + p'(x)}{2} y = f(x)$$

Where $p(x) = -2$. Therefore, there is an integrating factor given by

$$\begin{aligned} M(x) &= e^{\frac{1}{2} \int p dx} \\ &= e^{\int -2 dx} \\ &= e^{-x} \end{aligned}$$

Multiplying both sides of the ODE by the integrating factor $M(x)$ makes the left side of the ODE a complete differential

$$\begin{aligned} (M(x)y)'' &= 0 \\ (e^{-x}y)'' &= 0 \end{aligned}$$

Integrating once gives

$$(e^{-x}y)' = c_1$$

Integrating again gives

$$(e^{-x}y) = c_1x + c_2$$

Hence the solution is

$$y = \frac{c_1x + c_2}{e^{-x}}$$

Or

$$y = c_1x e^x + c_2e^x$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1x e^x + c_2e^x \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 1$ and $x = 0$ in the above gives

$$1 = c_2 \tag{1A}$$

Taking derivative of the solution gives

$$y' = e^x c_1 + c_1x e^x + c_2e^x$$

substituting $y' = 4$ and $x = 0$ in the above gives

$$4 = c_1 + c_2 \tag{2A}$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 3$$

$$c_2 = 1$$

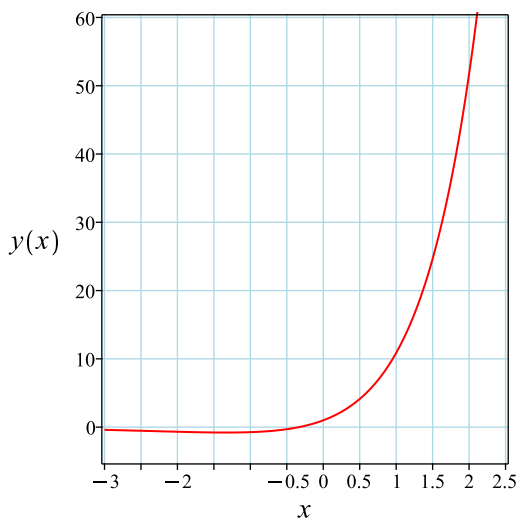
Substituting these values back in above solution results in

$$y = 3x e^x + e^x$$

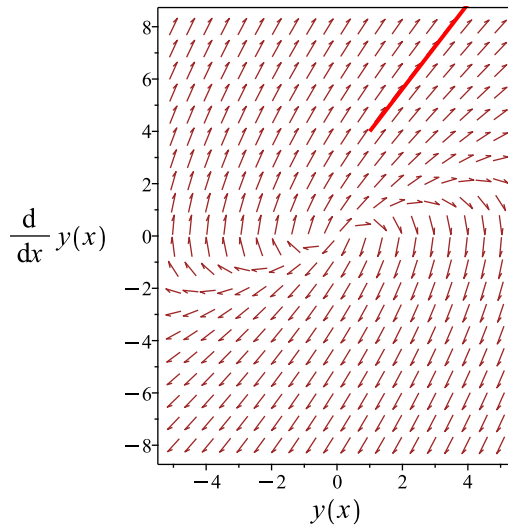
Summary

The solution(s) found are the following

$$y = 3x e^x + e^x \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = 3x e^x + e^x$$

Verified OK.

8.5.4 Solving using Kovacic algorithm

Writing the ode as

$$y'' - 2y' + y = 0 \tag{1}$$

$$Ay'' + By' + Cy = 0 \tag{2}$$

Comparing (1) and (2) shows that

$$A = 1$$

$$B = -2$$

$$C = 1$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$r = \frac{s}{t} \tag{5}$$

$$= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{0}{1} \tag{6}$$

Comparing the above to (5) shows that

$$s = 0$$

$$t = 1$$

Therefore eq. (4) becomes

$$z''(x) = 0 \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 259: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned}O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - -\infty \\ &= \infty\end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is *infinity* then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = 0$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = 1$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned}y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-2}{1} dx} \\ &= z_1 e^x \\ &= z_1(e^x)\end{aligned}$$

Which simplifies to

$$y_1 = e^x$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{-2}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{2x}}{(y_1)^2} dx \\ &= y_1(x)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1(e^x) + c_2(e^x(x))\end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = e^x c_1 + c_2 x e^x \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 1$ and $x = 0$ in the above gives

$$1 = c_1 \quad (1A)$$

Taking derivative of the solution gives

$$y' = e^x c_1 + c_2 e^x + c_2 x e^x$$

substituting $y' = 4$ and $x = 0$ in the above gives

$$4 = c_1 + c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 1$$

$$c_2 = 3$$

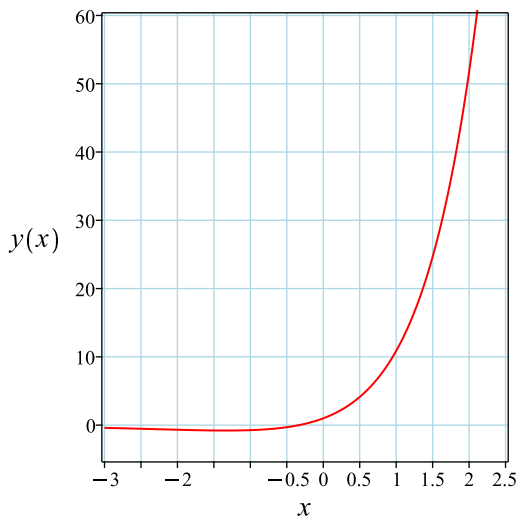
Substituting these values back in above solution results in

$$y = 3x e^x + e^x$$

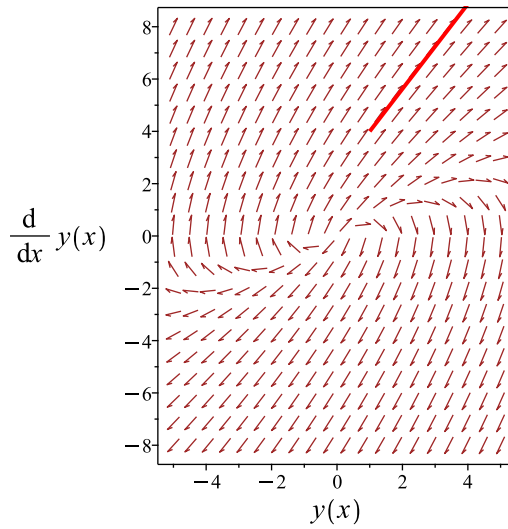
Summary

The solution(s) found are the following

$$y = 3x e^x + e^x \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = 3x e^x + e^x$$

Verified OK.

8.5.5 Maple step by step solution

Let's solve

$$\left[y'' - 2y' + y = 0, y(0) = 1, y' \Big|_{\{x=0\}} = 4 \right]$$

- Highest derivative means the order of the ODE is 2
- y''
- Characteristic polynomial of ODE
- $r^2 - 2r + 1 = 0$
- Factor the characteristic polynomial
- $(r - 1)^2 = 0$
- Root of the characteristic polynomial
- $r = 1$
- 1st solution of the ODE

$$y_1(x) = e^x$$

- Repeated root, multiply $y_1(x)$ by x to ensure linear independence

$$y_2(x) = x e^x$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x)$$

- Substitute in solutions

$$y = e^x c_1 + c_2 x e^x$$

- Check validity of solution $y = e^x c_1 + c_2 x e^x$

- Use initial condition $y(0) = 1$

$$1 = c_1$$

- Compute derivative of the solution

$$y' = e^x c_1 + c_2 e^x + c_2 x e^x$$

- Use the initial condition $y' \Big|_{\{x=0\}} = 4$

$$4 = c_1 + c_2$$

- Solve for c_1 and c_2

$$\{c_1 = 1, c_2 = 3\}$$

- Substitute constant values into general solution and simplify

$$y = e^x(3x + 1)$$

- Solution to the IVP

$$y = e^x(3x + 1)$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 12

```
dsolve([diff(y(x),x$2)-2*diff(y(x),x)+y(x)=0,y(0) = 1, D(y)(0) = 4],y(x), singsol=all)
```

$$y(x) = e^x(3x + 1)$$

✓ Solution by Mathematica

Time used: 0.011 (sec). Leaf size: 14

```
DSolve[{y''[x]-2*y'[x]+y[x]==0,{y[0]==1,y'[0]==4}},y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^x(3x + 1)$$

8.6 problem 9

8.6.1	Existence and uniqueness analysis	1772
8.6.2	Solving as second order euler ode	1772
8.6.3	Solving as linear second order ode solved by an integrating factor ode	1774
8.6.4	Solving as second order change of variable on x method 2 ode .	1776
8.6.5	Solving as second order change of variable on x method 1 ode .	1780
8.6.6	Solving as second order change of variable on y method 1 ode .	1784
8.6.7	Solving as second order change of variable on y method 2 ode .	1786
8.6.8	Solving as second order ode non constant coeff transformation on B ode	1790
8.6.9	Solving using Kovacic algorithm	1793
8.6.10	Maple step by step solution	1797

Internal problem ID [11718]

Internal file name [OUTPUT/11727_Thursday_April_11_2024_08_49_09_PM_74917571/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.1. Basic theory of linear differential equations. Exercises page 113

Problem number: 9.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_euler_ode", "second_order_change_of_variable_on_x_method_1", "second_order_change_of_variable_on_x_method_2", "second_order_change_of_variable_on_y_method_1", "second_order_change_of_variable_on_y_method_2", "linear_second_order_ode_solved_by_an_integrating_factor", "second_order_ode_non_constant_coeff_transformation_on_B"

Maple gives the following as the ode type

```
[[_Emden, _Fowler], [_2nd_order, _linear, `_with_symmetry_[0,F(x)]`]]
```

$$x^2y'' - 2y'x + 2y = 0$$

With initial conditions

$$[y(1) = 3, y'(1) = 2]$$

8.6.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$\begin{aligned} p(x) &= -\frac{2}{x} \\ q(x) &= \frac{2}{x^2} \\ F &= 0 \end{aligned}$$

Hence the ode is

$$y'' - \frac{2y'}{x} + \frac{2y}{x^2} = 0$$

The domain of $p(x) = -\frac{2}{x}$ is

$$\{x < 0 \vee 0 < x\}$$

And the point $x_0 = 1$ is inside this domain. The domain of $q(x) = \frac{2}{x^2}$ is

$$\{x < 0 \vee 0 < x\}$$

And the point $x_0 = 1$ is also inside this domain. Hence solution exists and is unique.

8.6.2 Solving as second order euler ode

This is Euler second order ODE. Let the solution be $y = x^r$, then $y' = rx^{r-1}$ and $y'' = r(r-1)x^{r-2}$. Substituting these back into the given ODE gives

$$x^2(r(r-1))x^{r-2} - 2rxr^{r-1} + 2x^r = 0$$

Simplifying gives

$$r(r-1)x^r - 2rx^r + 2x^r = 0$$

Since $x^r \neq 0$ then dividing throughout by x^r gives

$$r(r-1) - 2r + 2 = 0$$

Or

$$r^2 - 3r + 2 = 0 \quad (1)$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = 1$$

$$r_2 = 2$$

Since the roots are real and distinct, then the general solution is

$$y = c_1 y_1 + c_2 y_2$$

Where $y_1 = x^{r_1}$ and $y_2 = x^{r_2}$. Hence

$$y = c_2 x^2 + c_1 x$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_2 x^2 + c_1 x \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 3$ and $x = 1$ in the above gives

$$3 = c_1 + c_2 \quad (1A)$$

Taking derivative of the solution gives

$$y' = 2c_2 x + c_1$$

substituting $y' = 2$ and $x = 1$ in the above gives

$$2 = 2c_2 + c_1 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 4$$

$$c_2 = -1$$

Substituting these values back in above solution results in

$$y = -x^2 + 4x$$

Summary

The solution(s) found are the following

$$y = -x^2 + 4x \quad (1)$$

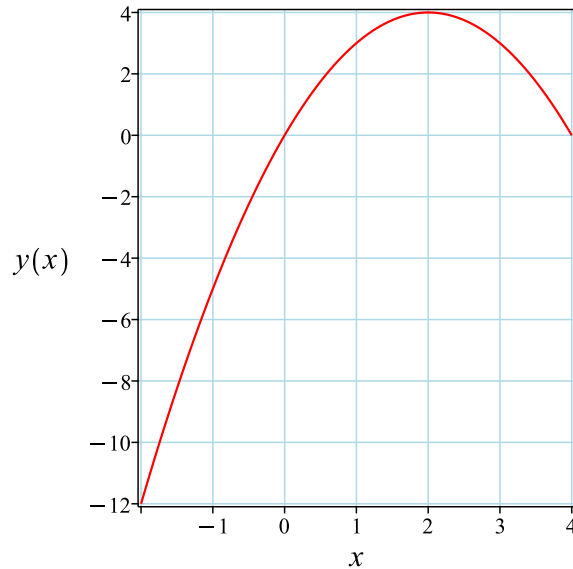


Figure 338: Solution plot

Verification of solutions

$$y = -x^2 + 4x$$

Verified OK.

8.6.3 Solving as linear second order ode solved by an integrating factor ode

The ode satisfies this form

$$y'' + p(x)y' + \frac{(p(x)^2 + p'(x))y}{2} = f(x)$$

Where $p(x) = -\frac{2}{x}$. Therefore, there is an integrating factor given by

$$\begin{aligned} M(x) &= e^{\frac{1}{2} \int p dx} \\ &= e^{\int -\frac{2}{x} dx} \\ &= \frac{1}{x} \end{aligned}$$

Multiplying both sides of the ODE by the integrating factor $M(x)$ makes the left side of the ODE a complete differential

$$(M(x)y)'' = 0$$
$$\left(\frac{y}{x}\right)'' = 0$$

Integrating once gives

$$\left(\frac{y}{x}\right)' = c_1$$

Integrating again gives

$$\left(\frac{y}{x}\right) = c_1x + c_2$$

Hence the solution is

$$y = \frac{c_1x + c_2}{\frac{1}{x}}$$

Or

$$y = c_1x^2 + c_2x$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1x^2 + c_2x \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 3$ and $x = 1$ in the above gives

$$3 = c_1 + c_2 \tag{1A}$$

Taking derivative of the solution gives

$$y' = 2c_1x + c_2$$

substituting $y' = 2$ and $x = 1$ in the above gives

$$2 = 2c_1 + c_2 \tag{2A}$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = -1$$

$$c_2 = 4$$

Substituting these values back in above solution results in

$$y = -x^2 + 4x$$

Summary

The solution(s) found are the following

$$y = -x^2 + 4x \tag{1}$$

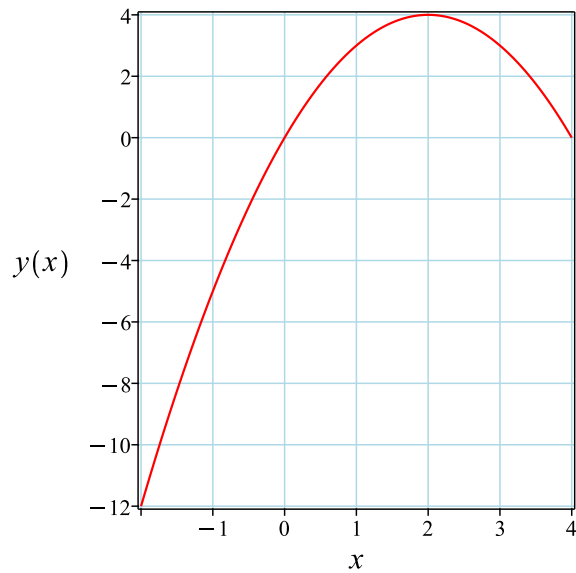


Figure 339: Solution plot

Verification of solutions

$$y = -x^2 + 4x$$

Verified OK.

8.6.4 Solving as second order change of variable on x method 2 ode

In normal form the ode

$$x^2 y'' - 2y'x + 2y = 0 \tag{1}$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \tag{2}$$

Where

$$p(x) = -\frac{2}{x}$$
$$q(x) = \frac{2}{x^2}$$

Applying change of variables $\tau = g(x)$ to (2) gives

$$\frac{d^2}{d\tau^2}y(\tau) + p_1\left(\frac{d}{d\tau}y(\tau)\right) + q_1y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $p_1 = 0$. Eq (4) simplifies to

$$\tau''(x) + p(x)\tau'(x) = 0$$

This ode is solved resulting in

$$\begin{aligned} \tau &= \int e^{-(\int p(x)dx)} dx \\ &= \int e^{-(\int -\frac{2}{x}dx)} dx \\ &= \int e^{2\ln(x)} dx \\ &= \int x^2 dx \\ &= \frac{x^3}{3} \end{aligned} \quad (6)$$

Using (6) to evaluate q_1 from (5) gives

$$\begin{aligned} q_1(\tau) &= \frac{q(x)}{\tau'(x)^2} \\ &= \frac{\frac{2}{x^2}}{x^4} \\ &= \frac{2}{x^6} \end{aligned} \quad (7)$$

Substituting the above in (3) and noting that now $p_1 = 0$ results in

$$\begin{aligned}\frac{d^2}{d\tau^2}y(\tau) + q_1y(\tau) &= 0 \\ \frac{d^2}{d\tau^2}y(\tau) + \frac{2y(\tau)}{x^6} &= 0\end{aligned}$$

But in terms of τ

$$\frac{2}{x^6} = \frac{2}{9\tau^2}$$

Hence the above ode becomes

$$\frac{d^2}{d\tau^2}y(\tau) + \frac{2y(\tau)}{9\tau^2} = 0$$

The above ode is now solved for $y(\tau)$. The ode can be written as

$$9\left(\frac{d^2}{d\tau^2}y(\tau)\right)\tau^2 + 2y(\tau) = 0$$

Which shows it is a Euler ODE. This is Euler second order ODE. Let the solution be $y(\tau) = \tau^r$, then $y' = r\tau^{r-1}$ and $y'' = r(r-1)\tau^{r-2}$. Substituting these back into the given ODE gives

$$9\tau^2(r(r-1))\tau^{r-2} + 0r\tau^{r-1} + 2\tau^r = 0$$

Simplifying gives

$$9r(r-1)\tau^r + 0\tau^r + 2\tau^r = 0$$

Since $\tau^r \neq 0$ then dividing throughout by τ^r gives

$$9r(r-1) + 0 + 2 = 0$$

Or

$$9r^2 - 9r + 2 = 0 \tag{1}$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$\begin{aligned}r_1 &= \frac{1}{3} \\ r_2 &= \frac{2}{3}\end{aligned}$$

Since the roots are real and distinct, then the general solution is

$$y(\tau) = c_1y_1 + c_2y_2$$

Where $y_1 = \tau^{r_1}$ and $y_2 = \tau^{r_2}$. Hence

$$y(\tau) = c_1 \tau^{\frac{1}{3}} + c_2 \tau^{\frac{2}{3}}$$

The above solution is now transformed back to y using (6) which results in

$$y = \frac{c_1 3^{\frac{2}{3}} (x^3)^{\frac{1}{3}}}{3} + \frac{c_2 3^{\frac{1}{3}} (x^3)^{\frac{2}{3}}}{3}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = \frac{c_1 3^{\frac{2}{3}} (x^3)^{\frac{1}{3}}}{3} + \frac{c_2 3^{\frac{1}{3}} (x^3)^{\frac{2}{3}}}{3} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 3$ and $x = 1$ in the above gives

$$3 = \frac{3^{\frac{1}{3}} (c_1 3^{\frac{1}{3}} + c_2)}{3} \quad (1A)$$

Taking derivative of the solution gives

$$y' = \frac{c_1 3^{\frac{2}{3}} x^2}{3 (x^3)^{\frac{2}{3}}} + \frac{2c_2 3^{\frac{1}{3}} x^2}{3 (x^3)^{\frac{1}{3}}}$$

substituting $y' = 2$ and $x = 1$ in the above gives

$$2 = \frac{3^{\frac{1}{3}} (c_1 3^{\frac{1}{3}} + 2c_2)}{3} \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$\begin{aligned} c_1 &= 4 \cdot 3^{\frac{1}{3}} \\ c_2 &= -3^{\frac{2}{3}} \end{aligned}$$

Substituting these values back in above solution results in

$$y = -(x^3)^{\frac{2}{3}} + 4(x^3)^{\frac{1}{3}}$$

Summary

The solution(s) found are the following

$$y = -(x^3)^{\frac{2}{3}} + 4(x^3)^{\frac{1}{3}} \quad (1)$$

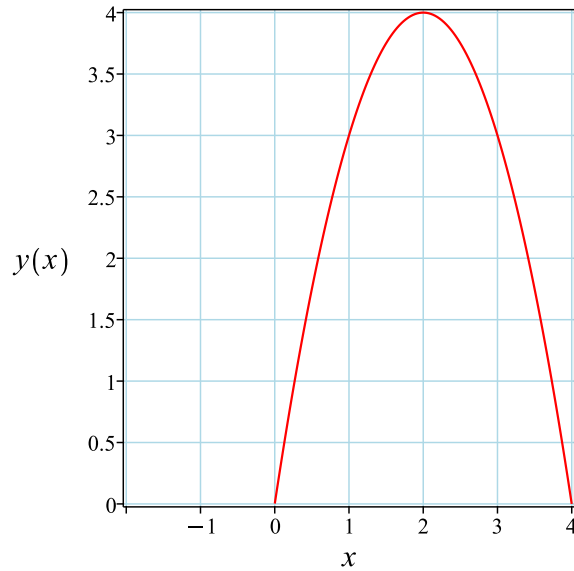


Figure 340: Solution plot

Verification of solutions

$$y = -(x^3)^{\frac{2}{3}} + 4(x^3)^{\frac{1}{3}}$$

Verified OK.

8.6.5 Solving as second order change of variable on x method 1 ode

In normal form the ode

$$x^2 y'' - 2y'x + 2y = 0 \tag{1}$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \tag{2}$$

Where

$$p(x) = -\frac{2}{x}$$

$$q(x) = \frac{2}{x^2}$$

Applying change of variables $\tau = g(x)$ to (2) results

$$\frac{d^2}{d\tau^2}y(\tau) + p_1\left(\frac{d}{d\tau}y(\tau)\right) + q_1y(\tau) = 0 \tag{3}$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x) \tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $q_1 = c^2$ where c is some constant. Therefore from (5)

$$\begin{aligned} \tau' &= \frac{1}{c} \sqrt{q} \\ &= \frac{\sqrt{2} \sqrt{\frac{1}{x^2}}}{c} \\ \tau'' &= -\frac{\sqrt{2}}{c \sqrt{\frac{1}{x^2}} x^3} \end{aligned} \quad (6)$$

Substituting the above into (4) results in

$$\begin{aligned} p_1(\tau) &= \frac{\tau''(x) + p(x) \tau'(x)}{\tau'(x)^2} \\ &= \frac{-\frac{\sqrt{2}}{c \sqrt{\frac{1}{x^2}} x^3} - \frac{2}{x} \frac{\sqrt{2} \sqrt{\frac{1}{x^2}}}{c}}{\left(\frac{\sqrt{2} \sqrt{\frac{1}{x^2}}}{c}\right)^2} \\ &= -\frac{3c\sqrt{2}}{2} \end{aligned}$$

Therefore ode (3) now becomes

$$\begin{aligned} y(\tau)'' + p_1 y(\tau)' + q_1 y(\tau) &= 0 \\ \frac{d^2}{d\tau^2} y(\tau) - \frac{3c\sqrt{2}}{2} \left(\frac{d}{d\tau} y(\tau)\right) + c^2 y(\tau) &= 0 \end{aligned} \quad (7)$$

The above ode is now solved for $y(\tau)$. Since the ode is now constant coefficients, it can be easily solved to give

$$y(\tau) = e^{\frac{3\sqrt{2}c\tau}{4}} \left(c_1 \cosh \left(\frac{\sqrt{2}c\tau}{4} \right) + ic_2 \sinh \left(\frac{\sqrt{2}c\tau}{4} \right) \right)$$

Now from (6)

$$\begin{aligned}\tau &= \int \frac{1}{c} \sqrt{q} dx \\ &= \frac{\int \sqrt{2} \sqrt{\frac{1}{x^2}} dx}{c} \\ &= \frac{\sqrt{2} \sqrt{\frac{1}{x^2}} x \ln(x)}{c}\end{aligned}$$

Substituting the above into the solution obtained gives

$$y = x^{\frac{3}{2}} \left(c_1 \cosh \left(\frac{\ln(x)}{2} \right) + ic_2 \sinh \left(\frac{\ln(x)}{2} \right) \right)$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = x^{\frac{3}{2}} \left(c_1 \cosh \left(\frac{\ln(x)}{2} \right) + ic_2 \sinh \left(\frac{\ln(x)}{2} \right) \right) \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 3$ and $x = 1$ in the above gives

$$3 = c_1 \quad (1A)$$

Taking derivative of the solution gives

$$y' = \frac{3\sqrt{x} \left(c_1 \cosh \left(\frac{\ln(x)}{2} \right) + ic_2 \sinh \left(\frac{\ln(x)}{2} \right) \right)}{2} + x^{\frac{3}{2}} \left(\frac{c_1 \sinh \left(\frac{\ln(x)}{2} \right)}{2x} + \frac{ic_2 \cosh \left(\frac{\ln(x)}{2} \right)}{2x} \right)$$

substituting $y' = 2$ and $x = 1$ in the above gives

$$2 = \frac{3c_1}{2} + \frac{ic_2}{2} \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 3$$

$$c_2 = 5i$$

Substituting these values back in above solution results in

$$y = -5x^{\frac{3}{2}} \sinh\left(\frac{\ln(x)}{2}\right) + 3 \cosh\left(\frac{\ln(x)}{2}\right) x^{\frac{3}{2}}$$

Which simplifies to

$$y = \left(-5 \sinh\left(\frac{\ln(x)}{2}\right) + 3 \cosh\left(\frac{\ln(x)}{2}\right)\right) x^{\frac{3}{2}}$$

Summary

The solution(s) found are the following

$$y = \left(-5 \sinh\left(\frac{\ln(x)}{2}\right) + 3 \cosh\left(\frac{\ln(x)}{2}\right)\right) x^{\frac{3}{2}} \quad (1)$$

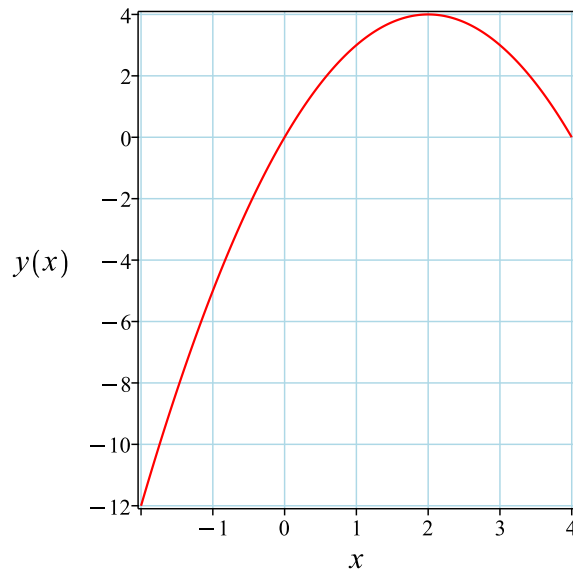


Figure 341: Solution plot

Verification of solutions

$$y = \left(-5 \sinh\left(\frac{\ln(x)}{2}\right) + 3 \cosh\left(\frac{\ln(x)}{2}\right)\right) x^{\frac{3}{2}}$$

Verified OK.

8.6.6 Solving as second order change of variable on y method 1 ode

In normal form the given ode is written as

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = -\frac{2}{x}$$
$$q(x) = \frac{2}{x^2}$$

Calculating the Liouville ode invariant Q given by

$$\begin{aligned} Q &= q - \frac{p'}{2} - \frac{p^2}{4} \\ &= \frac{2}{x^2} - \frac{\left(-\frac{2}{x}\right)'}{2} - \frac{\left(-\frac{2}{x}\right)^2}{4} \\ &= \frac{2}{x^2} - \frac{\left(\frac{2}{x^2}\right)}{2} - \frac{\left(\frac{4}{x^2}\right)}{4} \\ &= \frac{2}{x^2} - \left(\frac{1}{x^2}\right) - \frac{1}{x^2} \\ &= 0 \end{aligned}$$

Since the Liouville ode invariant does not depend on the independent variable x then the transformation

$$y = v(x)z(x) \quad (3)$$

is used to change the original ode to a constant coefficients ode in v . In (3) the term $z(x)$ is given by

$$\begin{aligned} z(x) &= e^{-\left(\int \frac{p(x)}{2} dx\right)} \\ &= e^{-\int \frac{-2}{x}} \\ &= x \end{aligned} \quad (5)$$

Hence (3) becomes

$$y = v(x)x \quad (4)$$

Applying this change of variable to the original ode results in

$$x^3v''(x) = 0$$

Which is now solved for $v(x)$ Integrating twice gives the solution

$$v(x) = c_1x + c_2$$

Now that $v(x)$ is known, then

$$\begin{aligned} y &= v(x) z(x) \\ &= (c_1x + c_2) (z(x)) \end{aligned} \tag{7}$$

But from (5)

$$z(x) = x$$

Hence (7) becomes

$$y = (c_1x + c_2) x$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = (c_1x + c_2) x \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 3$ and $x = 1$ in the above gives

$$3 = c_1 + c_2 \tag{1A}$$

Taking derivative of the solution gives

$$y' = 2c_1x + c_2$$

substituting $y' = 2$ and $x = 1$ in the above gives

$$2 = 2c_1 + c_2 \tag{2A}$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$\begin{aligned} c_1 &= -1 \\ c_2 &= 4 \end{aligned}$$

Substituting these values back in above solution results in

$$y = -x(-4 + x)$$

Summary

The solution(s) found are the following

$$y = -x(-4 + x) \quad (1)$$

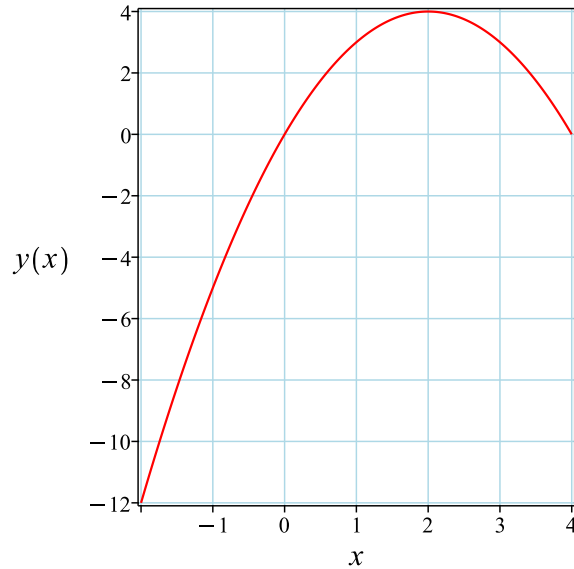


Figure 342: Solution plot

Verification of solutions

$$y = -x(-4 + x)$$

Verified OK.

8.6.7 Solving as second order change of variable on y method 2 ode

In normal form the ode

$$x^2 y'' - 2y'x + 2y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = -\frac{2}{x}$$
$$q(x) = \frac{2}{x^2}$$

Applying change of variables on the dependent variable $y = v(x)x^n$ to (2) gives the following ode where the dependent variables is $v(x)$ and not y .

$$v''(x) + \left(\frac{2n}{x} + p\right)v'(x) + \left(\frac{n(n-1)}{x^2} + \frac{np}{x} + q\right)v(x) = 0 \quad (3)$$

Let the coefficient of $v(x)$ above be zero. Hence

$$\frac{n(n-1)}{x^2} + \frac{np}{x} + q = 0 \quad (4)$$

Substituting the earlier values found for $p(x)$ and $q(x)$ into (4) gives

$$\frac{n(n-1)}{x^2} - \frac{2n}{x^2} + \frac{2}{x^2} = 0 \quad (5)$$

Solving (5) for n gives

$$n = 2 \quad (6)$$

Substituting this value in (3) gives

$$\begin{aligned} v''(x) + \frac{2v'(x)}{x} &= 0 \\ v''(x) + \frac{2v'(x)}{x} &= 0 \end{aligned} \quad (7)$$

Using the substitution

$$u(x) = v'(x)$$

Then (7) becomes

$$u'(x) + \frac{2u(x)}{x} = 0 \quad (8)$$

The above is now solved for $u(x)$. In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= -\frac{2u}{x} \end{aligned}$$

Where $f(x) = -\frac{2}{x}$ and $g(u) = u$. Integrating both sides gives

$$\begin{aligned}\frac{1}{u} du &= -\frac{2}{x} dx \\ \int \frac{1}{u} du &= \int -\frac{2}{x} dx \\ \ln(u) &= -2 \ln(x) + c_1 \\ u &= e^{-2 \ln(x) + c_1} \\ &= \frac{c_1}{x^2}\end{aligned}$$

Now that $u(x)$ is known, then

$$\begin{aligned}v'(x) &= u(x) \\ v(x) &= \int u(x) dx + c_2 \\ &= -\frac{c_1}{x} + c_2\end{aligned}$$

Hence

$$\begin{aligned}y &= v(x) x^n \\ &= \left(-\frac{c_1}{x} + c_2\right) x^2 \\ &= (c_2 x - c_1) x\end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = \left(-\frac{c_1}{x} + c_2\right) x^2 \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 3$ and $x = 1$ in the above gives

$$3 = -c_1 + c_2 \tag{1A}$$

Taking derivative of the solution gives

$$y' = c_1 + 2\left(-\frac{c_1}{x} + c_2\right) x$$

substituting $y' = 2$ and $x = 1$ in the above gives

$$2 = -c_1 + 2c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = -4$$

$$c_2 = -1$$

Substituting these values back in above solution results in

$$y = -x(-4 + x)$$

Summary

The solution(s) found are the following

$$y = -x(-4 + x) \quad (1)$$

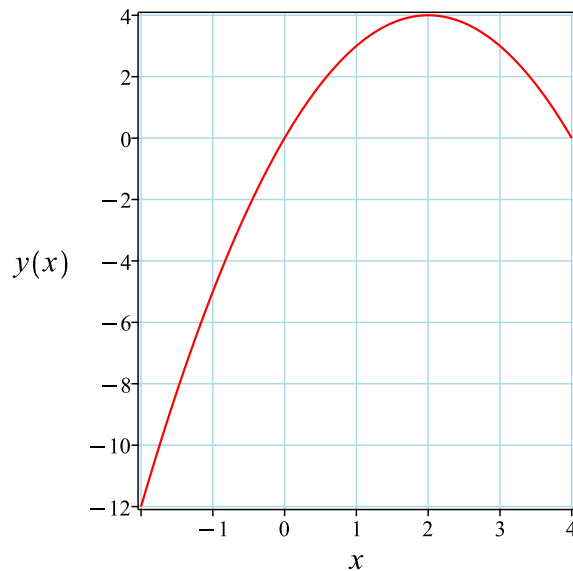


Figure 343: Solution plot

Verification of solutions

$$y = -x(-4 + x)$$

Verified OK.

8.6.8 Solving as second order ode non constant coeff transformation on B ode

Given an ode of the form

$$Ay'' + By' + Cy = F(x)$$

This method reduces the order ode the ODE by one by applying the transformation

$$y = Bv$$

This results in

$$\begin{aligned}y' &= B'v + v'B \\y'' &= B''v + B'v' + v''B + v'B' \\&= v''B + 2v' + B' + B''v\end{aligned}$$

And now the original ode becomes

$$\begin{aligned}A(v''B + 2v'B' + B''v) + B(B'v + v'B) + CBv &= 0 \\ABv'' + (2AB' + B^2)v' + (AB'' + BB' + CB)v &= 0\end{aligned}\tag{1}$$

If the term $AB'' + BB' + CB$ is zero, then this method works and can be used to solve

$$ABv'' + (2AB' + B^2)v' = 0$$

By Using $u = v'$ which reduces the order of the above ode to one. The new ode is

$$ABu' + (2AB' + B^2)u = 0$$

The above ode is first order ode which is solved for u . Now a new ode $v' = u$ is solved for v as first order ode. Then the final solution is obtain from $y = Bv$.

This method works only if the term $AB'' + BB' + CB$ is zero. The given ODE shows that

$$\begin{aligned}A &= x^2 \\B &= -2x \\C &= 2 \\F &= 0\end{aligned}$$

The above shows that for this ode

$$\begin{aligned}AB'' + BB' + CB &= (x^2)(0) + (-2x)(-2) + (2)(-2x) \\&= 0\end{aligned}$$

Hence the ode in v given in (1) now simplifies to

$$-2x^3v'' + (0)v' = 0$$

Now by applying $v' = u$ the above becomes

$$-2x^3u'(x) = 0$$

Which is now solved for u . Integrating both sides gives

$$\begin{aligned}u(x) &= \int 0 \, dx \\ &= c_1\end{aligned}$$

The ode for v now becomes

$$\begin{aligned}v' &= u \\ &= c_1\end{aligned}$$

Which is now solved for v . Integrating both sides gives

$$\begin{aligned}v(x) &= \int c_1 \, dx \\ &= c_1x + c_2\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y(x) &= Bv \\ &= (-2x)(c_1x + c_2) \\ &= -2(c_1x + c_2)x\end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = -2(c_1x + c_2)x \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 3$ and $x = 1$ in the above gives

$$3 = -2c_1 - 2c_2 \tag{1A}$$

Taking derivative of the solution gives

$$y' = -4c_1x - 2c_2$$

substituting $y' = 2$ and $x = 1$ in the above gives

$$2 = -4c_1 - 2c_2 \tag{2A}$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = \frac{1}{2}$$
$$c_2 = -2$$

Substituting these values back in above solution results in

$$y = -x(-4 + x)$$

Summary

The solution(s) found are the following

$$y = -x(-4 + x) \tag{1}$$

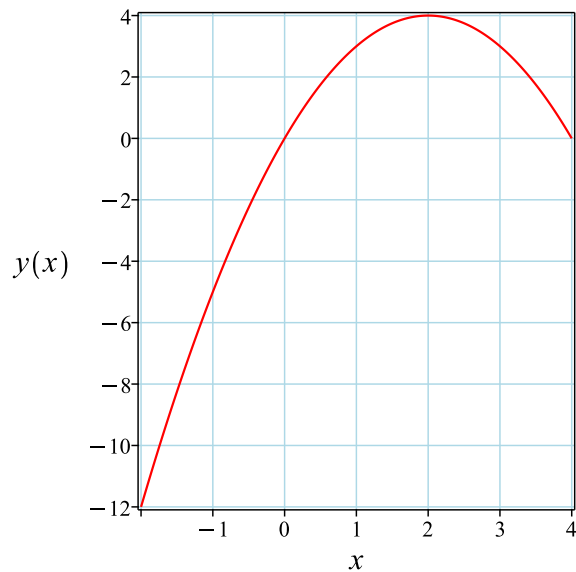


Figure 344: Solution plot

Verification of solutions

$$y = -x(-4 + x)$$

Verified OK.

8.6.9 Solving using Kovacic algorithm

Writing the ode as

$$x^2y'' - 2y'x + 2y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= x^2 \\ B &= -2x \\ C &= 2 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{0}{1} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 0 \\ t &= 1 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = 0 \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 261: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - -\infty \\ &= \infty \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is *infinity* then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = 0$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = 1$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-2x}{x^2} dx} \end{aligned}$$

$$\begin{aligned}
&= z_1 e^{\ln(x)} \\
&= z_1(x)
\end{aligned}$$

Which simplifies to

$$y_1 = x$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}
y_2 &= y_1 \int \frac{e^{\int -\frac{-2x}{x^2} dx}}{(y_1)^2} dx \\
&= y_1 \int \frac{e^{2\ln(x)}}{(y_1)^2} dx \\
&= y_1(x)
\end{aligned}$$

Therefore the solution is

$$\begin{aligned}
y &= c_1 y_1 + c_2 y_2 \\
&= c_1(x) + c_2(x(x))
\end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_2 x^2 + c_1 x \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 3$ and $x = 1$ in the above gives

$$3 = c_1 + c_2 \tag{1A}$$

Taking derivative of the solution gives

$$y' = 2c_2 x + c_1$$

substituting $y' = 2$ and $x = 1$ in the above gives

$$2 = 2c_2 + c_1 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 4$$

$$c_2 = -1$$

Substituting these values back in above solution results in

$$y = -x^2 + 4x$$

Summary

The solution(s) found are the following

$$y = -x^2 + 4x \quad (1)$$

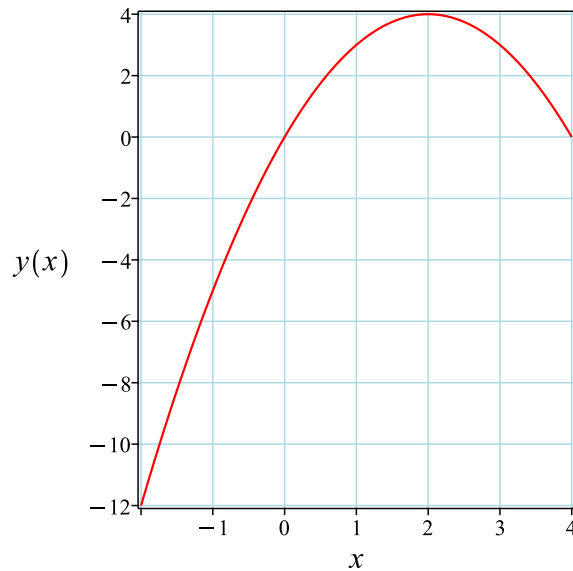


Figure 345: Solution plot

Verification of solutions

$$y = -x^2 + 4x$$

Verified OK.

8.6.10 Maple step by step solution

Let's solve

$$\left[y''x^2 - 2y'x + 2y = 0, y(1) = 3, y'|_{\{x=1\}} = 2 \right]$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = \frac{2y'}{x} - \frac{2y}{x^2}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' - \frac{2y'}{x} + \frac{2y}{x^2} = 0$$

- Multiply by denominators of the ODE

$$y''x^2 - 2y'x + 2y = 0$$

- Make a change of variables

$$t = \ln(x)$$

- Substitute the change of variables back into the ODE

- Calculate the 1st derivative of y with respect to x , using the chain rule

$$y' = \left(\frac{d}{dt} y(t) \right) t'(x)$$

- Compute derivative

$$y' = \frac{\frac{d}{dt} y(t)}{x}$$

- Calculate the 2nd derivative of y with respect to x , using the chain rule

$$y'' = \left(\frac{d^2}{dt^2} y(t) \right) t'(x)^2 + t''(x) \left(\frac{d}{dt} y(t) \right)$$

- Compute derivative

$$y'' = \frac{\frac{d^2}{dt^2} y(t)}{x^2} - \frac{\frac{d}{dt} y(t)}{x^2}$$

Substitute the change of variables back into the ODE

$$\left(\frac{\frac{d^2}{dt^2} y(t)}{x^2} - \frac{\frac{d}{dt} y(t)}{x^2} \right) x^2 - 2 \frac{d}{dt} y(t) + 2y(t) = 0$$

- Simplify

$$\frac{d^2}{dt^2} y(t) - 3 \frac{d}{dt} y(t) + 2y(t) = 0$$

- Characteristic polynomial of ODE

$$r^2 - 3r + 2 = 0$$

- Factor the characteristic polynomial

$$(r - 1)(r - 2) = 0$$

- Roots of the characteristic polynomial

$$r = (1, 2)$$

- 1st solution of the ODE

$$y_1(t) = e^t$$

- 2nd solution of the ODE

$$y_2(t) = e^{2t}$$

- General solution of the ODE

$$y(t) = c_1 y_1(t) + c_2 y_2(t)$$

- Substitute in solutions

$$y(t) = c_1 e^t + c_2 e^{2t}$$

- Change variables back using $t = \ln(x)$

$$y = c_2 x^2 + c_1 x$$

- Simplify

$$y = x(c_2 x + c_1)$$

- Check validity of solution $y = x(c_2 x + c_1)$

- Use initial condition $y(1) = 3$

$$3 = c_1 + c_2$$

- Compute derivative of the solution

$$y' = 2c_2 x + c_1$$

- Use the initial condition $y' \Big|_{\{x=1\}} = 2$

$$2 = 2c_2 + c_1$$

- Solve for c_1 and c_2

$$\{c_1 = 4, c_2 = -1\}$$

- Substitute constant values into general solution and simplify

$$y = -x(-4 + x)$$

- Solution to the IVP

$$y = -x(-4 + x)$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
<- LODE of Euler type successful`

```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 13

```
dsolve([x^2*diff(y(x),x$2)-2*x*diff(y(x),x)+2*y(x)=0,y(1) = 3, D(y)(1) = 2],y(x), singsol=all)
```

$$y(x) = -x^2 + 4x$$

✓ Solution by Mathematica

Time used: 0.01 (sec). Leaf size: 11

```
DSolve[{x^2*y''[x]-2*x*y'[x]+2*y[x]==0,{y[1]==3,y'[1]==2}},y[x],x,IncludeSingularSolutions->False]
```

$$y(x) \rightarrow -((x - 4)x)$$

8.7 problem 10

8.7.1	Existence and uniqueness analysis	1801
8.7.2	Solving as second order euler ode	1801
8.7.3	Solving as second order change of variable on x method 2 ode .	1803
8.7.4	Solving as second order change of variable on x method 1 ode .	1807
8.7.5	Solving as second order change of variable on y method 2 ode .	1810
8.7.6	Solving using Kovacic algorithm	1813
8.7.7	Maple step by step solution	1820

Internal problem ID [11719]

Internal file name [OUTPUT/11728_Thursday_April_11_2024_08_49_11_PM_90841023/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.1. Basic theory of linear differential equations. Exercises page 113

Problem number: 10.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_euler_ode", "second_order_change_of_variable_on_x_method_1", "second_order_change_of_variable_on_x_method_2", "second_order_change_of_variable_on_y_method_2"

Maple gives the following as the ode type

```
[[_Emden, _Fowler], [_2nd_order, _linear, `_with_symmetry_[0,F(x)]`]]
```

$$x^2y'' + y'x - 4y = 0$$

With initial conditions

$$[y(2) = 3, y'(2) = -1]$$

8.7.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$\begin{aligned}p(x) &= \frac{1}{x} \\q(x) &= -\frac{4}{x^2} \\F &= 0\end{aligned}$$

Hence the ode is

$$y'' + \frac{y'}{x} - \frac{4y}{x^2} = 0$$

The domain of $p(x) = \frac{1}{x}$ is

$$\{x < 0 \vee 0 < x\}$$

And the point $x_0 = 2$ is inside this domain. The domain of $q(x) = -\frac{4}{x^2}$ is

$$\{x < 0 \vee 0 < x\}$$

And the point $x_0 = 2$ is also inside this domain. Hence solution exists and is unique.

8.7.2 Solving as second order euler ode

This is Euler second order ODE. Let the solution be $y = x^r$, then $y' = rx^{r-1}$ and $y'' = r(r-1)x^{r-2}$. Substituting these back into the given ODE gives

$$x^2(r(r-1))x^{r-2} + xx^{r-1} - 4x^r = 0$$

Simplifying gives

$$r(r-1)x^r + rx^r - 4x^r = 0$$

Since $x^r \neq 0$ then dividing throughout by x^r gives

$$r(r-1) + r - 4 = 0$$

Or

$$r^2 - 4 = 0 \tag{1}$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = -2$$

$$r_2 = 2$$

Since the roots are real and distinct, then the general solution is

$$y = c_1y_1 + c_2y_2$$

Where $y_1 = x^{r_1}$ and $y_2 = x^{r_2}$. Hence

$$y = \frac{c_1}{x^2} + c_2x^2$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = \frac{c_1}{x^2} + c_2x^2 \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 3$ and $x = 2$ in the above gives

$$3 = \frac{c_1}{4} + 4c_2 \quad (1A)$$

Taking derivative of the solution gives

$$y' = -\frac{2c_1}{x^3} + 2c_2x$$

substituting $y' = -1$ and $x = 2$ in the above gives

$$-1 = -\frac{c_1}{4} + 4c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 8$$

$$c_2 = \frac{1}{4}$$

Substituting these values back in above solution results in

$$y = \frac{x^4 + 32}{4x^2}$$

Summary

The solution(s) found are the following

$$y = \frac{x^4 + 32}{4x^2} \quad (1)$$

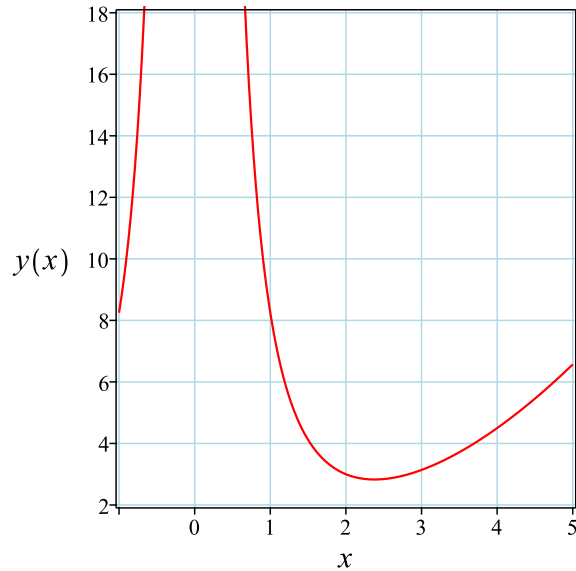


Figure 346: Solution plot

Verification of solutions

$$y = \frac{x^4 + 32}{4x^2}$$

Verified OK.

8.7.3 Solving as second order change of variable on x method 2 ode

In normal form the ode

$$x^2 y'' + y' x - 4y = 0 \quad (1)$$

Becomes

$$y'' + p(x) y' + q(x) y = 0 \quad (2)$$

Where

$$p(x) = \frac{1}{x}$$
$$q(x) = -\frac{4}{x^2}$$

Applying change of variables $\tau = g(x)$ to (2) gives

$$\frac{d^2}{d\tau^2}y(\tau) + p_1\left(\frac{d}{d\tau}y(\tau)\right) + q_1y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $p_1 = 0$. Eq (4) simplifies to

$$\tau''(x) + p(x)\tau'(x) = 0$$

This ode is solved resulting in

$$\begin{aligned} \tau &= \int e^{-(\int p(x)dx)} dx \\ &= \int e^{-(\int \frac{1}{x}dx)} dx \\ &= \int e^{-\ln(x)} dx \\ &= \int \frac{1}{x} dx \\ &= \ln(x) \end{aligned} \quad (6)$$

Using (6) to evaluate q_1 from (5) gives

$$\begin{aligned} q_1(\tau) &= \frac{q(x)}{\tau'(x)^2} \\ &= \frac{-\frac{4}{x^2}}{\frac{1}{x^2}} \\ &= -4 \end{aligned} \quad (7)$$

Substituting the above in (3) and noting that now $p_1 = 0$ results in

$$\begin{aligned} \frac{d^2}{d\tau^2}y(\tau) + q_1y(\tau) &= 0 \\ \frac{d^2}{d\tau^2}y(\tau) - 4y(\tau) &= 0 \end{aligned}$$

The above ode is now solved for $y(\tau)$. This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(\tau) + By'(\tau) + Cy(\tau) = 0$$

Where in the above $A = 1, B = 0, C = -4$. Let the solution be $y(\tau) = e^{\lambda\tau}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda\tau} - 4 e^{\lambda\tau} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda\tau}$ gives

$$\lambda^2 - 4 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 0, C = -4$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{0}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{0^2 - (4)(1)(-4)} \\ &= \pm 2 \end{aligned}$$

Hence

$$\lambda_1 = +2$$

$$\lambda_2 = -2$$

Which simplifies to

$$\lambda_1 = 2$$

$$\lambda_2 = -2$$

Since roots are real and distinct, then the solution is

$$y(\tau) = c_1 e^{\lambda_1 \tau} + c_2 e^{\lambda_2 \tau}$$

$$y(\tau) = c_1 e^{(2)\tau} + c_2 e^{(-2)\tau}$$

Or

$$y(\tau) = c_1 e^{2\tau} + c_2 e^{-2\tau}$$

The above solution is now transformed back to y using (6) which results in

$$y = \frac{c_1x^4 + c_2}{x^2}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = \frac{c_1x^4 + c_2}{x^2} \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 3$ and $x = 2$ in the above gives

$$3 = 4c_1 + \frac{c_2}{4} \tag{1A}$$

Taking derivative of the solution gives

$$y' = 4c_1x - \frac{2(c_1x^4 + c_2)}{x^3}$$

substituting $y' = -1$ and $x = 2$ in the above gives

$$-1 = 4c_1 - \frac{c_2}{4} \tag{2A}$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$\begin{aligned} c_1 &= \frac{1}{4} \\ c_2 &= 8 \end{aligned}$$

Substituting these values back in above solution results in

$$y = \frac{x^4 + 32}{4x^2}$$

Summary

The solution(s) found are the following

$$y = \frac{x^4 + 32}{4x^2} \tag{1}$$

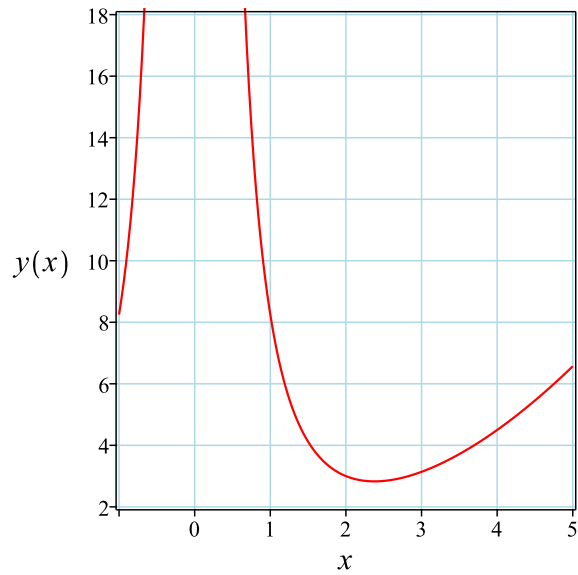


Figure 347: Solution plot

Verification of solutions

$$y = \frac{x^4 + 32}{4x^2}$$

Verified OK.

8.7.4 Solving as second order change of variable on x method 1 ode

In normal form the ode

$$x^2 y'' + y' x - 4y = 0 \tag{1}$$

Becomes

$$y'' + p(x) y' + q(x) y = 0 \tag{2}$$

Where

$$p(x) = \frac{1}{x}$$

$$q(x) = -\frac{4}{x^2}$$

Applying change of variables $\tau = g(x)$ to (2) results

$$\frac{d^2}{d\tau^2} y(\tau) + p_1 \left(\frac{d}{d\tau} y(\tau) \right) + q_1 y(\tau) = 0 \tag{3}$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x) \tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $q_1 = c^2$ where c is some constant. Therefore from (5)

$$\begin{aligned} \tau' &= \frac{1}{c} \sqrt{q} \\ &= \frac{2\sqrt{-\frac{1}{x^2}}}{c} \\ \tau'' &= \frac{2}{c\sqrt{-\frac{1}{x^2}} x^3} \end{aligned} \quad (6)$$

Substituting the above into (4) results in

$$\begin{aligned} p_1(\tau) &= \frac{\tau''(x) + p(x) \tau'(x)}{\tau'(x)^2} \\ &= \frac{\frac{2}{c\sqrt{-\frac{1}{x^2}} x^3} + \frac{1}{x} \frac{2\sqrt{-\frac{1}{x^2}}}{c}}{\left(\frac{2\sqrt{-\frac{1}{x^2}}}{c}\right)^2} \\ &= 0 \end{aligned}$$

Therefore ode (3) now becomes

$$\begin{aligned} y(\tau)'' + p_1 y(\tau)' + q_1 y(\tau) &= 0 \\ \frac{d^2}{d\tau^2} y(\tau) + c^2 y(\tau) &= 0 \end{aligned} \quad (7)$$

The above ode is now solved for $y(\tau)$. Since the ode is now constant coefficients, it can be easily solved to give

$$y(\tau) = c_1 \cos(c\tau) + c_2 \sin(c\tau)$$

Now from (6)

$$\begin{aligned} \tau &= \int \frac{1}{c} \sqrt{q} dx \\ &= \frac{\int 2\sqrt{-\frac{1}{x^2}} dx}{c} \\ &= \frac{2\sqrt{-\frac{1}{x^2}} x \ln(x)}{c} \end{aligned}$$

Substituting the above into the solution obtained gives

$$y = c_1 \cosh(2 \ln(x)) + ic_2 \sinh(2 \ln(x))$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 \cosh(2 \ln(x)) + ic_2 \sinh(2 \ln(x)) \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 3$ and $x = 2$ in the above gives

$$3 = \frac{15ic_2}{8} + \frac{17c_1}{8} \quad (1A)$$

Taking derivative of the solution gives

$$y' = \frac{2c_1 \sinh(2 \ln(x))}{x} + \frac{2ic_2 \cosh(2 \ln(x))}{x}$$

substituting $y' = -1$ and $x = 2$ in the above gives

$$-1 = \frac{17ic_2}{8} + \frac{15c_1}{8} \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = \frac{33}{4}$$
$$c_2 = \frac{31i}{4}$$

Substituting these values back in above solution results in

$$y = \frac{33 \cosh(2 \ln(x))}{4} - \frac{31 \sinh(2 \ln(x))}{4}$$

Summary

The solution(s) found are the following

$$y = \frac{33 \cosh(2 \ln(x))}{4} - \frac{31 \sinh(2 \ln(x))}{4} \quad (1)$$

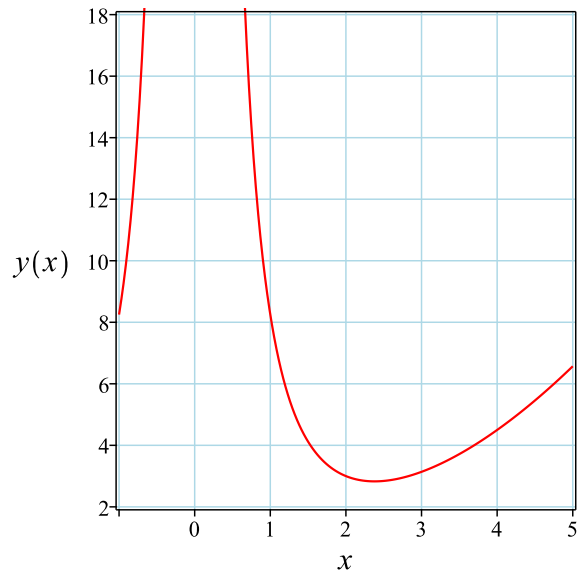


Figure 348: Solution plot

Verification of solutions

$$y = \frac{33 \cosh(2 \ln(x))}{4} - \frac{31 \sinh(2 \ln(x))}{4}$$

Verified OK.

8.7.5 Solving as second order change of variable on y method 2 ode

In normal form the ode

$$x^2 y'' + y' x - 4y = 0 \quad (1)$$

Becomes

$$y'' + p(x) y' + q(x) y = 0 \quad (2)$$

Where

$$p(x) = \frac{1}{x}$$

$$q(x) = -\frac{4}{x^2}$$

Applying change of variables on the dependent variable $y = v(x) x^n$ to (2) gives the following ode where the dependent variables is $v(x)$ and not y .

$$v''(x) + \left(\frac{2n}{x} + p \right) v'(x) + \left(\frac{n(n-1)}{x^2} + \frac{np}{x} + q \right) v(x) = 0 \quad (3)$$

Let the coefficient of $v(x)$ above be zero. Hence

$$\frac{n(n-1)}{x^2} + \frac{np}{x} + q = 0 \quad (4)$$

Substituting the earlier values found for $p(x)$ and $q(x)$ into (4) gives

$$\frac{n(n-1)}{x^2} + \frac{n}{x^2} - \frac{4}{x^2} = 0 \quad (5)$$

Solving (5) for n gives

$$n = 2 \quad (6)$$

Substituting this value in (3) gives

$$\begin{aligned} v''(x) + \frac{5v'(x)}{x} &= 0 \\ v''(x) + \frac{5v'(x)}{x} &= 0 \end{aligned} \quad (7)$$

Using the substitution

$$u(x) = v'(x)$$

Then (7) becomes

$$u'(x) + \frac{5u(x)}{x} = 0 \quad (8)$$

The above is now solved for $u(x)$. In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= -\frac{5u}{x} \end{aligned}$$

Where $f(x) = -\frac{5}{x}$ and $g(u) = u$. Integrating both sides gives

$$\begin{aligned} \frac{1}{u} du &= -\frac{5}{x} dx \\ \int \frac{1}{u} du &= \int -\frac{5}{x} dx \\ \ln(u) &= -5 \ln(x) + c_1 \\ u &= e^{-5 \ln(x) + c_1} \\ &= \frac{c_1}{x^5} \end{aligned}$$

Now that $u(x)$ is known, then

$$\begin{aligned}v'(x) &= u(x) \\v(x) &= \int u(x) dx + c_2 \\&= -\frac{c_1}{4x^4} + c_2\end{aligned}$$

Hence

$$\begin{aligned}y &= v(x) x^n \\&= \left(-\frac{c_1}{4x^4} + c_2\right) x^2 \\&= \frac{4c_2x^4 - c_1}{4x^2}\end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = \left(-\frac{c_1}{4x^4} + c_2\right) x^2 \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 3$ and $x = 2$ in the above gives

$$3 = -\frac{c_1}{16} + 4c_2 \quad (1A)$$

Taking derivative of the solution gives

$$y' = \frac{c_1}{x^3} + 2\left(-\frac{c_1}{4x^4} + c_2\right) x$$

substituting $y' = -1$ and $x = 2$ in the above gives

$$-1 = \frac{c_1}{16} + 4c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$\begin{aligned}c_1 &= -32 \\c_2 &= \frac{1}{4}\end{aligned}$$

Substituting these values back in above solution results in

$$y = \frac{x^4 + 32}{4x^2}$$

Summary

The solution(s) found are the following

$$y = \frac{x^4 + 32}{4x^2} \quad (1)$$

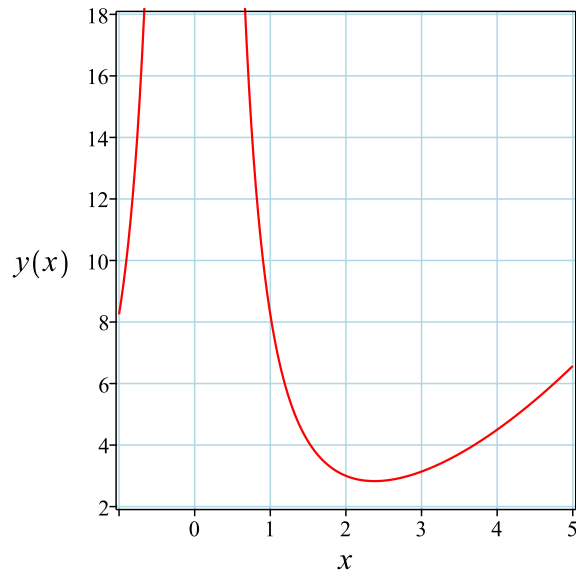


Figure 349: Solution plot

Verification of solutions

$$y = \frac{x^4 + 32}{4x^2}$$

Verified OK.

8.7.6 Solving using Kovacic algorithm

Writing the ode as

$$x^2 y'' + y' x - 4y = 0 \quad (1)$$

$$A y'' + B y' + C y = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= x^2 \\ B &= x \\ C &= -4 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{15}{4x^2} \tag{6}$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 15 \\ t &= 4x^2 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = \left(\frac{15}{4x^2} \right) z(x) \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 263: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned}
 \mathcal{O}(\infty) &= \deg(t) - \deg(s) \\
 &= 2 - 0 \\
 &= 2
 \end{aligned}$$

The poles of r in eq. (7) and the order of each pole are determined by solving for the roots of $t = 4x^2$. There is a pole at $x = 0$ of order 2. Since there is no odd order pole larger than 2 and the order at ∞ is 2 then the necessary conditions for case one are met. Since there is a pole of order 2 then necessary conditions for case two are met. Since pole order is not larger than 2 and the order at ∞ is 2 then the necessary conditions for case three are met. Therefore

$$L = [1, 2, 4, 6, 12]$$

Attempting to find a solution using case $n = 1$.

Looking at poles of order 2. The partial fractions decomposition of r is

$$r = \frac{15}{4x^2}$$

For the pole at $x = 0$ let b be the coefficient of $\frac{1}{x^2}$ in the partial fractions decomposition

of r given above. Therefore $b = \frac{15}{4}$. Hence

$$\begin{aligned} [\sqrt{r}]_c &= 0 \\ \alpha_c^+ &= \frac{1}{2} + \sqrt{1 + 4b} = \frac{5}{2} \\ \alpha_c^- &= \frac{1}{2} - \sqrt{1 + 4b} = -\frac{3}{2} \end{aligned}$$

Since the order of r at ∞ is 2 then $[\sqrt{r}]_\infty = 0$. Let b be the coefficient of $\frac{1}{x^2}$ in the Laurent series expansion of r at ∞ , which can be found by dividing the leading coefficient of s by the leading coefficient of t from

$$r = \frac{s}{t} = \frac{15}{4x^2}$$

Since the $\gcd(s, t) = 1$. This gives $b = \frac{15}{4}$. Hence

$$\begin{aligned} [\sqrt{r}]_\infty &= 0 \\ \alpha_\infty^+ &= \frac{1}{2} + \sqrt{1 + 4b} = \frac{5}{2} \\ \alpha_\infty^- &= \frac{1}{2} - \sqrt{1 + 4b} = -\frac{3}{2} \end{aligned}$$

The following table summarizes the findings so far for poles and for the order of r at ∞ where r is

$$r = \frac{15}{4x^2}$$

pole c location	pole order	$[\sqrt{r}]_c$	α_c^+	α_c^-
0	2	0	$\frac{5}{2}$	$-\frac{3}{2}$

Order of r at ∞	$[\sqrt{r}]_\infty$	α_∞^+	α_∞^-
2	0	$\frac{5}{2}$	$-\frac{3}{2}$

Now that the all $[\sqrt{r}]_c$ and its associated α_c^\pm have been determined for all the poles in the set Γ and $[\sqrt{r}]_\infty$ and its associated α_∞^\pm have also been found, the next step is to determine possible non negative integer d from these using

$$d = \alpha_\infty^{s(\infty)} - \sum_{c \in \Gamma} \alpha_c^{s(c)}$$

Where $s(c)$ is either $+$ or $-$ and $s(\infty)$ is the sign of α_∞^\pm . This is done by trial over all set of families $s = (s(c))_{c \in \Gamma \cup \infty}$ until such d is found to work in finding candidate ω .

Trying $\alpha_{\infty}^{-} = -\frac{3}{2}$ then

$$\begin{aligned} d &= \alpha_{\infty}^{-} - (\alpha_{c_1}^{-}) \\ &= -\frac{3}{2} - \left(-\frac{3}{2}\right) \\ &= 0 \end{aligned}$$

Since d an integer and $d \geq 0$ then it can be used to find ω using

$$\omega = \sum_{c \in \Gamma} \left(s(c)[\sqrt{r}]_c + \frac{\alpha_c^{s(c)}}{x - c} \right) + s(\infty)[\sqrt{r}]_{\infty}$$

The above gives

$$\begin{aligned} \omega &= \left((-)[\sqrt{r}]_{c_1} + \frac{\alpha_{c_1}^{-}}{x - c_1} \right) + (-)[\sqrt{r}]_{\infty} \\ &= -\frac{3}{2x} + (-)(0) \\ &= -\frac{3}{2x} \\ &= -\frac{3}{2x} \end{aligned}$$

Now that ω is determined, the next step is find a corresponding minimal polynomial $p(x)$ of degree $d = 0$ to solve the ode. The polynomial $p(x)$ needs to satisfy the equation

$$p'' + 2\omega p' + (\omega' + \omega^2 - r) p = 0 \quad (1A)$$

Let

$$p(x) = 1 \quad (2A)$$

Substituting the above in eq. (1A) gives

$$\begin{aligned} (0) + 2\left(-\frac{3}{2x}\right)(0) + \left(\left(\frac{3}{2x^2}\right) + \left(-\frac{3}{2x}\right)^2 - \left(\frac{15}{4x^2}\right)\right) &= 0 \\ 0 &= 0 \end{aligned}$$

The equation is satisfied since both sides are zero. Therefore the first solution to the ode $z'' = rz$ is

$$\begin{aligned} z_1(x) &= pe^{\int \omega dx} \\ &= e^{\int -\frac{3}{2x} dx} \\ &= \frac{1}{x^{\frac{3}{2}}} \end{aligned}$$

The first solution to the original ode in y is found from

$$\begin{aligned}y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\&= z_1 e^{-\int \frac{1}{2} \frac{x}{x^2} dx} \\&= z_1 e^{-\frac{\ln(x)}{2}} \\&= z_1 \left(\frac{1}{\sqrt{x}} \right)\end{aligned}$$

Which simplifies to

$$y_1 = \frac{1}{x^2}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{x}{x^2} dx}}{(y_1)^2} dx \\&= y_1 \int \frac{e^{-\ln(x)}}{(y_1)^2} dx \\&= y_1 \left(\frac{x^4}{4} \right)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\&= c_1 \left(\frac{1}{x^2} \right) + c_2 \left(\frac{1}{x^2} \left(\frac{x^4}{4} \right) \right)\end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = \frac{c_1}{x^2} + \frac{c_2 x^2}{4} \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 3$ and $x = 2$ in the above gives

$$3 = \frac{c_1}{4} + c_2 \quad (1A)$$

Taking derivative of the solution gives

$$y' = -\frac{2c_1}{x^3} + \frac{c_2 x}{2}$$

substituting $y' = -1$ and $x = 2$ in the above gives

$$-1 = -\frac{c_1}{4} + c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 8$$

$$c_2 = 1$$

Substituting these values back in above solution results in

$$y = \frac{x^4 + 32}{4x^2}$$

Summary

The solution(s) found are the following

$$y = \frac{x^4 + 32}{4x^2} \quad (1)$$

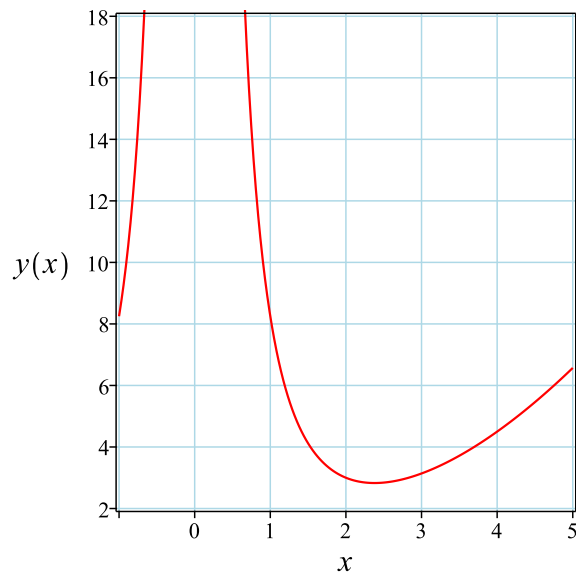


Figure 350: Solution plot

Verification of solutions

$$y = \frac{x^4 + 32}{4x^2}$$

Verified OK.

8.7.7 Maple step by step solution

Let's solve

$$\left[y''x^2 + y'x - 4y = 0, y(2) = 3, y'|_{\{x=2\}} = -1 \right]$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = -\frac{y'}{x} + \frac{4y}{x^2}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + \frac{y'}{x} - \frac{4y}{x^2} = 0$$

- Multiply by denominators of the ODE

$$y''x^2 + y'x - 4y = 0$$

- Make a change of variables

$$t = \ln(x)$$

- Substitute the change of variables back into the ODE

- Calculate the 1st derivative of y with respect to x , using the chain rule

$$y' = \left(\frac{d}{dt}y(t) \right) t'(x)$$

- Compute derivative

$$y' = \frac{\frac{d}{dt}y(t)}{x}$$

- Calculate the 2nd derivative of y with respect to x , using the chain rule

$$y'' = \left(\frac{d^2}{dt^2}y(t) \right) t'(x)^2 + t''(x) \left(\frac{d}{dt}y(t) \right)$$

- Compute derivative

$$y'' = \frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2}$$

Substitute the change of variables back into the ODE

$$\left(\frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2} \right) x^2 + \frac{d}{dt}y(t) - 4y(t) = 0$$

- Simplify

$$\frac{d^2}{dt^2}y(t) - 4y(t) = 0$$

- Characteristic polynomial of ODE

$$r^2 - 4 = 0$$

- Factor the characteristic polynomial

$$(r - 2)(r + 2) = 0$$

- Roots of the characteristic polynomial

$$r = (-2, 2)$$

- 1st solution of the ODE

$$y_1(t) = e^{-2t}$$

- 2nd solution of the ODE

$$y_2(t) = e^{2t}$$

- General solution of the ODE

$$y(t) = c_1y_1(t) + c_2y_2(t)$$

- Substitute in solutions

$$y(t) = c_1e^{-2t} + c_2e^{2t}$$

- Change variables back using $t = \ln(x)$

$$y = \frac{c_1}{x^2} + c_2x^2$$

- Simplify

$$y = \frac{c_1}{x^2} + c_2x^2$$

- Check validity of solution $y = \frac{c_1}{x^2} + c_2x^2$

- Use initial condition $y(2) = 3$

$$3 = \frac{c_1}{4} + 4c_2$$

- Compute derivative of the solution

$$y' = -\frac{2c_1}{x^3} + 2c_2x$$

- Use the initial condition $y' \Big|_{\{x=2\}} = -1$

$$-1 = -\frac{c_1}{4} + 4c_2$$

- Solve for c_1 and c_2

$$\{c_1 = 8, c_2 = \frac{1}{4}\}$$

- Substitute constant values into general solution and simplify

$$y = \frac{x^4+32}{4x^2}$$

- Solution to the IVP

$$y = \frac{x^4+32}{4x^2}$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
<- LODE of Euler type successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 14

```
dsolve([x^2*diff(y(x),x$2)+x*diff(y(x),x)-4*y(x)=0,y(2) = 3, D(y)(2) = -1],y(x), singsol=all
```

$$y(x) = \frac{x^4 + 32}{4x^2}$$

✓ Solution by Mathematica

Time used: 0.011 (sec). Leaf size: 17

```
DSolve[{x^2*y'[x]+x*y'[x]-4*y[x]==0,{y[2]==3,y'[2]==-1}},y[x],x,IncludeSingularSolutions ->
```

$$y(x) \rightarrow \frac{x^4 + 32}{4x^2}$$

8.8 problem 11

- 8.8.1 Solving as second order linear constant coeff ode 1823
- 8.8.2 Solving using Kovacic algorithm 1825
- 8.8.3 Maple step by step solution 1829

Internal problem ID [11720]

Internal file name [OUTPUT/11729_Thursday_April_11_2024_08_49_12_PM_60684601/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.1. Basic theory of linear differential equations. Exercises page 113

Problem number: 11.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _missing_x]]
```

$$y'' - 5y' + 4y = 0$$

8.8.1 Solving as second order linear constant coeff ode

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = -5, C = 4$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} - 5\lambda e^{\lambda x} + 4e^{\lambda x} = 0 \tag{1}$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 - 5\lambda + 4 = 0 \tag{2}$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = -5, C = 4$ into the above gives

$$\begin{aligned}\lambda_{1,2} &= \frac{5}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{-5^2 - (4)(1)(4)} \\ &= \frac{5}{2} \pm \frac{3}{2}\end{aligned}$$

Hence

$$\lambda_1 = \frac{5}{2} + \frac{3}{2}$$

$$\lambda_2 = \frac{5}{2} - \frac{3}{2}$$

Which simplifies to

$$\lambda_1 = 4$$

$$\lambda_2 = 1$$

Since roots are real and distinct, then the solution is

$$y = c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x}$$

$$y = c_1 e^{(4)x} + c_2 e^{(1)x}$$

Or

$$y = c_1 e^{4x} + c_2 e^x$$

Summary

The solution(s) found are the following

$$y = c_1 e^{4x} + c_2 e^x \tag{1}$$

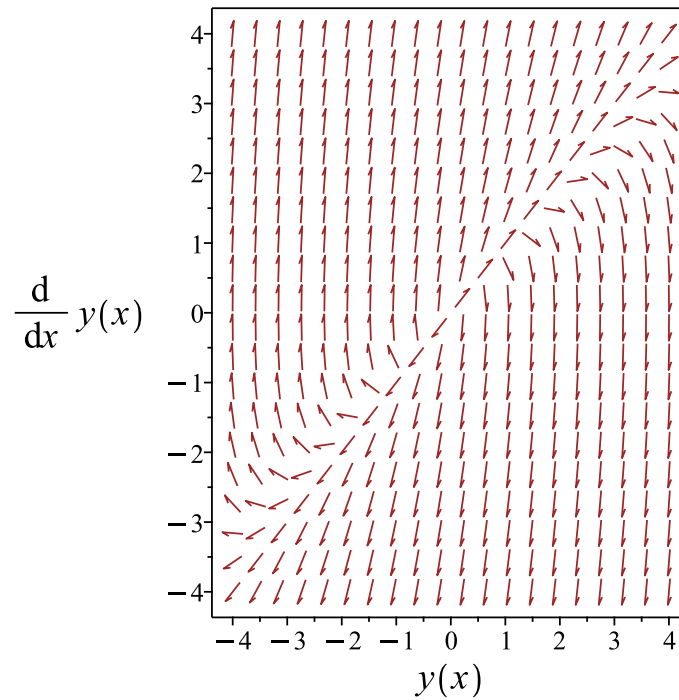


Figure 351: Slope field plot

Verification of solutions

$$y = c_1 e^{4x} + c_2 e^x$$

Verified OK.

8.8.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' - 5y' + 4y = 0 \tag{1}$$

$$Ay'' + By' + Cy = 0 \tag{2}$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= -5 \\ C &= 4 \end{aligned} \tag{3}$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{9}{4} \tag{6}$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 9 \\ t &= 4 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = \frac{9z(x)}{4} \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 265: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = \frac{9}{4}$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = e^{-\frac{3x}{2}}$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-5}{1} dx} \\ &= z_1 e^{\frac{5x}{2}} \\ &= z_1 \left(e^{\frac{5x}{2}} \right) \end{aligned}$$

Which simplifies to

$$y_1 = e^x$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{-5}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{5x}}{(y_1)^2} dx \\ &= y_1 \left(\frac{e^{3x}}{3} \right) \end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1(e^x) + c_2\left(e^x\left(\frac{e^{3x}}{3}\right)\right)\end{aligned}$$

Summary

The solution(s) found are the following

$$y = e^x c_1 + \frac{c_2 e^{4x}}{3} \tag{1}$$

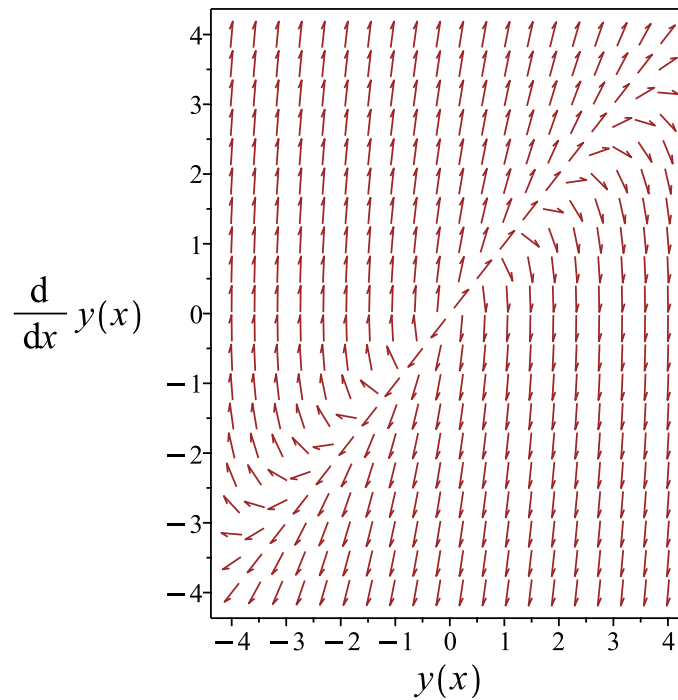


Figure 352: Slope field plot

Verification of solutions

$$y = e^x c_1 + \frac{c_2 e^{4x}}{3}$$

Verified OK.

8.8.3 Maple step by step solution

Let's solve

$$y'' - 5y' + 4y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of ODE

$$r^2 - 5r + 4 = 0$$

- Factor the characteristic polynomial

$$(r - 1)(r - 4) = 0$$

- Roots of the characteristic polynomial

$$r = (1, 4)$$

- 1st solution of the ODE

$$y_1(x) = e^x$$

- 2nd solution of the ODE

$$y_2(x) = e^{4x}$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x)$$

- Substitute in solutions

$$y = e^x c_1 + c_2 e^{4x}$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
<- constant coefficients successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 15

```
dsolve(diff(y(x),x$2)-5*diff(y(x),x)+4*y(x)=0,y(x), singsol=all)
```

$$y(x) = c_1 e^{4x} + c_2 e^x$$

✓ Solution by Mathematica

Time used: 0.011 (sec). Leaf size: 20

```
DSolve[y''[x]-5*y'[x]+4*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^x (c_2 e^{3x} + c_1)$$

8.9 problem 12

8.9.1 Maple step by step solution 1832

Internal problem ID [11721]

Internal file name [OUTPUT/11730_Thursday_April_11_2024_08_49_13_PM_89762227/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.1. Basic theory of linear differential equations. Exercises page 113

Problem number: 12.

ODE order: 3.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_3rd_order , _missing_x]]
```

$$y''' - 6y'' + 5y' + 12y = 0$$

The characteristic equation is

$$\lambda^3 - 6\lambda^2 + 5\lambda + 12 = 0$$

The roots of the above equation are

$$\lambda_1 = 3$$

$$\lambda_2 = 4$$

$$\lambda_3 = -1$$

Therefore the homogeneous solution is

$$y_h(x) = c_1 e^{-x} + e^{3x} c_2 + e^{4x} c_3$$

The fundamental set of solutions for the homogeneous solution are the following

$$y_1 = e^{-x}$$

$$y_2 = e^{3x}$$

$$y_3 = e^{4x}$$

Summary

The solution(s) found are the following

$$y = c_1 e^{-x} + e^{3x} c_2 + e^{4x} c_3 \quad (1)$$

Verification of solutions

$$y = c_1 e^{-x} + e^{3x} c_2 + e^{4x} c_3$$

Verified OK.

8.9.1 Maple step by step solution

Let's solve

$$y''' - 6y'' + 5y' + 12y = 0$$

- Highest derivative means the order of the ODE is 3

$$y'''$$

- Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(x)$

$$y_1(x) = y$$

- Define new variable $y_2(x)$

$$y_2(x) = y'$$

- Define new variable $y_3(x)$

$$y_3(x) = y''$$

- Isolate for $y_3'(x)$ using original ODE

$$y_3'(x) = 6y_3(x) - 5y_2(x) - 12y_1(x)$$

Convert linear ODE into a system of first order ODEs

$$[y_2(x) = y_1'(x), y_3(x) = y_2'(x), y_3'(x) = 6y_3(x) - 5y_2(x) - 12y_1(x)]$$

- Define vector

$$\vec{y}(x) = \begin{bmatrix} y_1(x) \\ y_2(x) \\ y_3(x) \end{bmatrix}$$

- System to solve

$$\vec{y}'(x) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -12 & -5 & 6 \end{bmatrix} \cdot \vec{y}(x)$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -12 & -5 & 6 \end{bmatrix}$$

- Rewrite the system as

$$\vec{y}'(x) = A \cdot \vec{y}(x)$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[-1, \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \right], \left[3, \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix} \right], \left[4, \begin{bmatrix} \frac{1}{16} \\ \frac{1}{4} \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[-1, \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_1 = e^{-x} \cdot \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[3, \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_2 = e^{3x} \cdot \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[4, \begin{bmatrix} \frac{1}{16} \\ \frac{1}{4} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_3 = e^{4x} \cdot \begin{bmatrix} \frac{1}{16} \\ \frac{1}{4} \\ 1 \end{bmatrix}$$

- General solution to the system of ODEs

$$\vec{y} = c_1 \vec{y}_1 + c_2 \vec{y}_2 + c_3 \vec{y}_3$$

- Substitute solutions into the general solution

$$\vec{y} = c_1 e^{-x} \cdot \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} + e^{3x} c_2 \cdot \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix} + e^{4x} c_3 \cdot \begin{bmatrix} \frac{1}{16} \\ \frac{1}{4} \\ 1 \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y = c_1 e^{-x} + \frac{e^{3x} c_2}{9} + \frac{e^{4x} c_3}{16}$$

Maple trace

```

`Methods for third order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 23

```
dsolve(diff(y(x),x$3)-6*diff(y(x),x$2)+5*diff(y(x),x)+12*y(x)=0,y(x), singsol=all)
```

$$y(x) = c_1 e^{4x} + c_2 e^{-x} + c_3 e^{3x}$$

✓ Solution by Mathematica

Time used: 0.009 (sec). Leaf size: 29

```
DSolve[y'''[x]-6*y''[x]+5*y'[x]+12*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^{-x} (e^{4x} (c_3 e^x + c_2) + c_1)$$

8.10 problem 13

8.10.1 Maple step by step solution 1838

Internal problem ID [11722]

Internal file name [OUTPUT/11731_Thursday_April_11_2024_08_49_13_PM_65327505/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.1. Basic theory of linear differential equations. Exercises page 113

Problem number: 13.

ODE order: 3.

ODE degree: 1.

The type(s) of ODE detected by this program : **"higher_order_ODE_non_constant_coefficients_of_type_Euler"**

Maple gives the following as the ode type

```
[[_3rd_order , _with_linear_symmetries]]
```

$$x^3y''' - 4x^2y'' + 8y'x - 8y = 0$$

This is Euler ODE of higher order. Let $y = x^\lambda$. Hence

$$\begin{aligned}y' &= \lambda x^{\lambda-1} \\y'' &= \lambda(\lambda-1)x^{\lambda-2} \\y''' &= \lambda(\lambda-1)(\lambda-2)x^{\lambda-3}\end{aligned}$$

Substituting these back into

$$x^3y''' - 4x^2y'' + 8y'x - 8y = 0$$

gives

$$8\lambda x^{\lambda-1} - 4x^2\lambda(\lambda-1)x^{\lambda-2} + x^3\lambda(\lambda-1)(\lambda-2)x^{\lambda-3} - 8x^\lambda = 0$$

Which simplifies to

$$8\lambda x^\lambda - 4\lambda(\lambda-1)x^\lambda + \lambda(\lambda-1)(\lambda-2)x^\lambda - 8x^\lambda = 0$$

And since $x^\lambda \neq 0$ then dividing through by x^λ , the above becomes

$$8\lambda - 4\lambda(\lambda - 1) + \lambda(\lambda - 1)(\lambda - 2) - 8 = 0$$

Simplifying gives the characteristic equation as

$$\lambda^3 - 7\lambda^2 + 14\lambda - 8 = 0$$

Solving the above gives the following roots

$$\lambda_1 = 1$$

$$\lambda_2 = 2$$

$$\lambda_3 = 4$$

This table summarises the result

root	multiplicity	type of root
1	1	real root
2	1	real root
4	1	real root

The solution is generated by going over the above table. For each real root λ of multiplicity one generates a c_1x^λ basis solution. Each real root of multiplicity two, generates c_1x^λ and $c_2x^\lambda \ln(x)$ basis solutions. Each real root of multiplicity three, generates c_1x^λ and $c_2x^\lambda \ln(x)$ and $c_3x^\lambda \ln(x)^2$ basis solutions, and so on. Each complex root $\alpha \pm i\beta$ of multiplicity one generates $x^\alpha(c_1 \cos(\beta \ln(x)) + c_2 \sin(\beta \ln(x)))$ basis solutions. And each complex root $\alpha \pm i\beta$ of multiplicity two generates $\ln(x) x^\alpha(c_1 \cos(\beta \ln(x)) + c_2 \sin(\beta \ln(x)))$ basis solutions. And each complex root $\alpha \pm i\beta$ of multiplicity three generates $\ln(x)^2 x^\alpha(c_1 \cos(\beta \ln(x)) + c_2 \sin(\beta \ln(x)))$ basis solutions. And so on. Using the above show that the solution is

$$y = c_3x^4 + c_2x^2 + c_1x$$

The fundamental set of solutions for the homogeneous solution are the following

$$y_1 = x$$

$$y_2 = x^2$$

$$y_3 = x^4$$

Summary

The solution(s) found are the following

$$y = c_3x^4 + c_2x^2 + c_1x \tag{1}$$

Verification of solutions

$$y = c_3x^4 + c_2x^2 + c_1x$$

Verified OK.

8.10.1 Maple step by step solution

Let's solve

$$x^3y''' - 4y''x^2 + 8y'x - 8y = 0$$

- Highest derivative means the order of the ODE is 3

$$y'''$$

- Isolate 3rd derivative

$$y''' = \frac{8y}{x^3} + \frac{4(y''x - 2y')}{x^2}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y''' - \frac{4y''}{x} + \frac{8y'}{x^2} - \frac{8y}{x^3} = 0$$

- Multiply by denominators of the ODE

$$x^3y''' - 4y''x^2 + 8y'x - 8y = 0$$

- Make a change of variables

$$t = \ln(x)$$

- Substitute the change of variables back into the ODE

- Calculate the 1st derivative of y with respect to x , using the chain rule

$$y' = \left(\frac{d}{dt}y(t)\right) t'(x)$$

- Compute derivative

$$y' = \frac{\frac{d}{dt}y(t)}{x}$$

- Calculate the 2nd derivative of y with respect to x , using the chain rule

$$y'' = \left(\frac{d^2}{dt^2}y(t)\right) t'(x)^2 + t''(x) \left(\frac{d}{dt}y(t)\right)$$

- Compute derivative

$$y'' = \frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2}$$

- Calculate the 3rd derivative of y with respect to x , using the chain rule

$$y''' = \left(\frac{d^3}{dt^3}y(t)\right) t'(x)^3 + 3t'(x)t''(x) \left(\frac{d^2}{dt^2}y(t)\right) + t'''(x) \left(\frac{d}{dt}y(t)\right)$$

- Compute derivative

$$y''' = \frac{\frac{d^3}{dt^3}y(t)}{x^3} - \frac{3\left(\frac{d^2}{dt^2}y(t)\right)}{x^3} + \frac{2\left(\frac{d}{dt}y(t)\right)}{x^3}$$

Substitute the change of variables back into the ODE

$$x^3 \left(\frac{\frac{d^3}{dt^3}y(t)}{x^3} - \frac{3\left(\frac{d^2}{dt^2}y(t)\right)}{x^3} + \frac{2\left(\frac{d}{dt}y(t)\right)}{x^3} \right) - 4 \left(\frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2} \right) x^2 + 8 \frac{d}{dt}y(t) - 8y(t) = 0$$

- Simplify

$$\frac{d^3}{dt^3}y(t) - 7\frac{d^2}{dt^2}y(t) + 14\frac{d}{dt}y(t) - 8y(t) = 0$$

- Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(t)$

$$y_1(t) = y(t)$$

- Define new variable $y_2(t)$

$$y_2(t) = \frac{d}{dt}y(t)$$

- Define new variable $y_3(t)$

$$y_3(t) = \frac{d^2}{dt^2}y(t)$$

- Isolate for $\frac{d}{dt}y_3(t)$ using original ODE

$$\frac{d}{dt}y_3(t) = 7y_3(t) - 14y_2(t) + 8y_1(t)$$

Convert linear ODE into a system of first order ODEs

$$\left[y_2(t) = \frac{d}{dt}y_1(t), y_3(t) = \frac{d}{dt}y_2(t), \frac{d}{dt}y_3(t) = 7y_3(t) - 14y_2(t) + 8y_1(t) \right]$$

- Define vector

$$\vec{y}(t) = \begin{bmatrix} y_1(t) \\ y_2(t) \\ y_3(t) \end{bmatrix}$$

- System to solve

$$\frac{d}{dt}\vec{y}(t) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 8 & -14 & 7 \end{bmatrix} \cdot \vec{y}(t)$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 8 & -14 & 7 \end{bmatrix}$$

- Rewrite the system as

$$\frac{d}{dt}\vec{y}(t) = A \cdot \vec{y}(t)$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[1, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right], \left[2, \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right], \left[4, \begin{bmatrix} \frac{1}{16} \\ \frac{1}{4} \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[1, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_1 = e^t \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[2, \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_2 = e^{2t} \cdot \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[4, \begin{bmatrix} \frac{1}{16} \\ \frac{1}{4} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_3 = e^{4t} \cdot \begin{bmatrix} \frac{1}{16} \\ \frac{1}{4} \\ 1 \end{bmatrix}$$

- General solution to the system of ODEs

$$\vec{y} = c_1 \vec{y}_1 + c_2 \vec{y}_2 + c_3 \vec{y}_3$$

- Substitute solutions into the general solution

$$\vec{y} = c_1 e^t \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + c_2 e^{2t} \cdot \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} + c_3 e^{4t} \cdot \begin{bmatrix} \frac{1}{16} \\ \frac{1}{4} \\ 1 \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y(t) = c_1 e^t + \frac{c_2 e^{2t}}{4} + \frac{c_3 e^{4t}}{16}$$

- Change variables back using $t = \ln(x)$

$$y = c_1 x + \frac{1}{4} c_2 x^2 + \frac{1}{16} c_3 x^4$$

Maple trace

```

`Methods for third order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
<- LODE of Euler type successful`

```

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 16

```
dsolve(x^3*diff(y(x),x$3)-4*x^2*diff(y(x),x$2)+8*x*diff(y(x),x)-8*y(x)=0,y(x), singsol=all)
```

$$y(x) = x(c_1x^3 + c_3x + c_2)$$

✓ Solution by Mathematica

Time used: 0.004 (sec). Leaf size: 20

```
DSolve[x^3*y'''[x]-4*x^2*y''[x]+8*x*y'[x]-8*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow x(c_3x^3 + c_2x + c_1)$$

9 Chapter 4, Section 4.1. Basic theory of linear differential equations. Exercises page 124

9.1	problem 1	1844
9.2	problem 2	1849
9.3	problem 3	1854
9.4	problem 4	1859
9.5	problem 5	1864
9.6	problem 6	1869
9.7	problem 8	1874
9.8	problem 9	1884

9.1 problem 1

9.1.1 Maple step by step solution 1846

Internal problem ID [11723]

Internal file name [OUTPUT/11732_Thursday_April_11_2024_08_49_13_PM_10371206/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.1. Basic theory of linear differential equations. Exercises page 124

Problem number: 1.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "reduction_of_order", "second_order_euler_ode", "second_order_change_of_variable_on_x_method_1", "second_order_change_of_variable_on_x_method_2", "second_order_change_of_variable_on_y_method_2", "second_order_ode_non_constant_coeff_transformation_on_B"

Maple gives the following as the ode type

```
[[_Emden , _Fowler]]
```

$$x^2y'' - 4y'x + 4y = 0$$

Given that one solution of the ode is

$$y_1 = x$$

Given one basis solution $y_1(x)$, then the second basis solution is given by

$$y_2(x) = y_1 \left(\int \frac{e^{-\int p dx}}{y_1^2} dx \right)$$

Where $p(x)$ is the coefficient of y' when the ode is written in the normal form

$$y'' + p(x)y' + q(x)y = f(x)$$

Looking at the ode to solve shows that

$$p(x) = -\frac{4}{x}$$

Therefore

$$y_2(x) = x \left(\int \frac{e^{-(\int -\frac{4}{x} dx)}}{x^2} dx \right)$$

$$y_2(x) = x \int \frac{x^4}{x^2} dx$$

$$y_2(x) = x \left(\int x^2 dx \right)$$

$$y_2(x) = \frac{x^4}{3}$$

Hence the solution is

$$\begin{aligned} y &= c_1 y_1(x) + c_2 y_2(x) \\ &= c_1 x + \frac{1}{3} c_2 x^4 \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 x + \frac{1}{3} c_2 x^4 \tag{1}$$

Verification of solutions

$$y = c_1 x + \frac{1}{3} c_2 x^4$$

Verified OK.

9.1.1 Maple step by step solution

Let's solve

$$y''x^2 - 4y'x + 4y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = \frac{4y'}{x} - \frac{4y}{x^2}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' - \frac{4y'}{x} + \frac{4y}{x^2} = 0$$

- Multiply by denominators of the ODE

$$y''x^2 - 4y'x + 4y = 0$$

- Make a change of variables

$$t = \ln(x)$$

- Substitute the change of variables back into the ODE

- Calculate the 1st derivative of y with respect to x , using the chain rule

$$y' = \left(\frac{d}{dt}y(t)\right) t'(x)$$

- Compute derivative

$$y' = \frac{\frac{d}{dt}y(t)}{x}$$

- Calculate the 2nd derivative of y with respect to x , using the chain rule

$$y'' = \left(\frac{d^2}{dt^2}y(t)\right) t'(x)^2 + t''(x) \left(\frac{d}{dt}y(t)\right)$$

- Compute derivative

$$y'' = \frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2}$$

Substitute the change of variables back into the ODE

$$\left(\frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2}\right) x^2 - 4\frac{d}{dt}y(t) + 4y(t) = 0$$

- Simplify

$$\frac{d^2}{dt^2}y(t) - 5\frac{d}{dt}y(t) + 4y(t) = 0$$

- Characteristic polynomial of ODE

$$r^2 - 5r + 4 = 0$$

- Factor the characteristic polynomial
 $(r - 1)(r - 4) = 0$
- Roots of the characteristic polynomial
 $r = (1, 4)$
- 1st solution of the ODE
 $y_1(t) = e^t$
- 2nd solution of the ODE
 $y_2(t) = e^{4t}$
- General solution of the ODE
 $y(t) = c_1 y_1(t) + c_2 y_2(t)$
- Substitute in solutions
 $y(t) = c_1 e^t + c_2 e^{4t}$
- Change variables back using $t = \ln(x)$
 $y = c_2 x^4 + c_1 x$
- Simplify
 $y = x(c_2 x^3 + c_1)$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
<- LODE of Euler type successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 13

```
dsolve([x^2*diff(y(x),x$2)-4*x*diff(y(x),x)+4*y(x)=0,x],singsol=all)
```

$$y(x) = x(c_1 x^3 + c_2)$$

✓ Solution by Mathematica

Time used: 0.01 (sec). Leaf size: 16

```
DSolve[x^2*y'[x]-4*x*y'[x]+4*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow x(c_2x^3 + c_1)$$

9.2 problem 2

9.2.1 Maple step by step solution 1850

Internal problem ID [11724]

Internal file name [OUTPUT/11733_Thursday_April_11_2024_08_49_14_PM_11953513/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.1. Basic theory of linear differential equations. Exercises page 124

Problem number: 2.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "**reduction_of_order**", "**second_order_change_of_variable_on_x_method_1**", "**second_order_change_of_variable_on_x_method_2**", "**second_order_ode_non_constant_coeff_transformation_on_B**"

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$(1+x)^2 y'' - 3(1+x) y' + 3y = 0$$

Given that one solution of the ode is

$$y_1 = 1 + x$$

Given one basis solution $y_1(x)$, then the second basis solution is given by

$$y_2(x) = y_1 \left(\int \frac{e^{-\int p dx}}{y_1^2} dx \right)$$

Where $p(x)$ is the coefficient of y' when the ode is written in the normal form

$$y'' + p(x) y' + q(x) y = f(x)$$

Looking at the ode to solve shows that

$$p(x) = \frac{-3x - 3}{x^2 + 2x + 1}$$

Therefore

$$y_2(x) = (1+x) \left(\int \frac{e^{-\left(\int \frac{-3x-3}{x^2+2x+1} dx\right)}}{(1+x)^2} dx \right)$$

$$y_2(x) = 1+x \int \frac{(1+x)^3}{(1+x)^2} dx$$

$$y_2(x) = (1+x) \left(\int (1+x) dx \right)$$

$$y_2(x) = (1+x) \left(x + \frac{1}{2}x^2 \right)$$

Hence the solution is

$$\begin{aligned} y &= c_1 y_1(x) + c_2 y_2(x) \\ &= (1+x) c_1 + c_2 (1+x) \left(x + \frac{1}{2}x^2 \right) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = (1+x) c_1 + c_2 (1+x) \left(x + \frac{1}{2}x^2 \right) \quad (1)$$

Verification of solutions

$$y = (1+x) c_1 + c_2 (1+x) \left(x + \frac{1}{2}x^2 \right)$$

Verified OK.

9.2.1 Maple step by step solution

Let's solve

$$(1+x)^2 y'' + (-3x-3)y' + 3y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = \frac{3y'}{1+x} - \frac{3y}{(1+x)^2}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' - \frac{3y'}{1+x} + \frac{3y}{(1+x)^2} = 0$$

- Check to see if $x_0 = -1$ is a regular singular point

- Define functions

$$\left[P_2(x) = -\frac{3}{1+x}, P_3(x) = \frac{3}{(1+x)^2} \right]$$

- $(1+x) \cdot P_2(x)$ is analytic at $x = -1$

$$\left. ((1+x) \cdot P_2(x)) \right|_{x=-1} = -3$$

- $(1+x)^2 \cdot P_3(x)$ is analytic at $x = -1$

$$\left. ((1+x)^2 \cdot P_3(x)) \right|_{x=-1} = 3$$

- $x = -1$ is a regular singular point

Check to see if $x_0 = -1$ is a regular singular point

$$x_0 = -1$$

- Multiply by denominators

$$(1+x)^2 y'' + (-3x-3)y' + 3y = 0$$

- Change variables using $x = u - 1$ so that the regular singular point is at $u = 0$

$$u^2 \left(\frac{d^2}{du^2} y(u) \right) - 3u \left(\frac{d}{du} y(u) \right) + 3y(u) = 0$$

- Assume series solution for $y(u)$

$$y(u) = \sum_{k=0}^{\infty} a_k u^{k+r}$$

- Rewrite DE with series expansions

- Convert $u \cdot \left(\frac{d}{du} y(u) \right)$ to series expansion

$$u \cdot \left(\frac{d}{du} y(u) \right) = \sum_{k=0}^{\infty} a_k (k+r) u^{k+r}$$

- Convert $u^2 \cdot \left(\frac{d^2}{du^2} y(u) \right)$ to series expansion

$$u^2 \cdot \left(\frac{d^2}{du^2} y(u) \right) = \sum_{k=0}^{\infty} a_k (k+r)(k+r-1) u^{k+r}$$

Rewrite DE with series expansions

$$\sum_{k=0}^{\infty} a_k (k+r-1)(k+r-3) u^{k+r} = 0$$

- a_0 cannot be 0 by assumption, giving the indicial equation
 $r = 0$
- Each term in the series must be 0, giving the recursion relation
 $a_k(k-1)(k-3) = 0$
- Recursion relation that defines series solution to ODE
 $a_k = 0$
- Recursion relation for $r = 0$
 $a_k = 0$
- Solution for $r = 0$
$$\left[y(u) = \sum_{k=0}^{\infty} a_k u^k, a_k = 0 \right]$$
- Revert the change of variables $u = 1 + x$
$$\left[y = \sum_{k=0}^{\infty} a_k (1+x)^k, a_k = 0 \right]$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
<- LODE of Euler type successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 17

```
dsolve([(x+1)^2*diff(y(x),x$2)-3*(x+1)*diff(y(x),x)+3*y(x)=0,x+1],singsol=all)
```

$$y(x) = (1+x)(c_1 + c_2(1+x)^2)$$

✓ Solution by Mathematica

Time used: 0.026 (sec). Leaf size: 20

```
DSolve[(x+1)^2*y'[x]-3*(x+1)*y'[x]+3*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow c_2(x+1)^3 + c_1(x+1)$$

9.3 problem 3

9.3.1 Maple step by step solution 1855

Internal problem ID [11725]

Internal file name [OUTPUT/11734_Thursday_April_11_2024_08_49_14_PM_67310780/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.1. Basic theory of linear differential equations. Exercises page 124

Problem number: 3.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "**reduction_of_order**", "**second_order_change_of_variable_on_y_method_2**", "**second_order_ode_non_constant_coeff_transformation_on_B**"

Maple gives the following as the ode type

[_Gegenbauer]

$$(x^2 - 1) y'' - 2y'x + 2y = 0$$

Given that one solution of the ode is

$$y_1 = x$$

Given one basis solution $y_1(x)$, then the second basis solution is given by

$$y_2(x) = y_1 \left(\int \frac{e^{-\int p dx}}{y_1^2} dx \right)$$

Where $p(x)$ is the coefficient of y' when the ode is written in the normal form

$$y'' + p(x) y' + q(x) y = f(x)$$

Looking at the ode to solve shows that

$$p(x) = -\frac{2x}{x^2 - 1}$$

Therefore

$$y_2(x) = x \left(\int \frac{e^{-\left(\int -\frac{2x}{x^2-1} dx\right)}}{x^2} dx \right)$$

$$y_2(x) = x \int \frac{e^{\ln(x-1)+\ln(1+x)}}{x^2} dx$$

$$y_2(x) = x \left(\int \frac{x^2 - 1}{x^2} dx \right)$$

$$y_2(x) = x \left(x + \frac{1}{x} \right)$$

Hence the solution is

$$\begin{aligned} y &= c_1 y_1(x) + c_2 y_2(x) \\ &= c_1 x + c_2 x \left(x + \frac{1}{x} \right) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 x + c_2 x \left(x + \frac{1}{x} \right) \tag{1}$$

Verification of solutions

$$y = c_1 x + c_2 x \left(x + \frac{1}{x} \right)$$

Verified OK.

9.3.1 Maple step by step solution

Let's solve

$$y''(x^2 - 1) - 2y'x + 2y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = \frac{2xy'}{x^2-1} - \frac{2y}{x^2-1}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' - \frac{2xy'}{x^2-1} + \frac{2y}{x^2-1} = 0$$

□ Check to see if x_0 is a regular singular point

○ Define functions

$$\left[P_2(x) = -\frac{2x}{x^2-1}, P_3(x) = \frac{2}{x^2-1} \right]$$

○ $(1+x) \cdot P_2(x)$ is analytic at $x = -1$

$$\left. ((1+x) \cdot P_2(x)) \right|_{x=-1} = -1$$

○ $(1+x)^2 \cdot P_3(x)$ is analytic at $x = -1$

$$\left. ((1+x)^2 \cdot P_3(x)) \right|_{x=-1} = 0$$

○ $x = -1$ is a regular singular point

Check to see if x_0 is a regular singular point

$$x_0 = -1$$

• Multiply by denominators

$$y''(x^2 - 1) - 2y'x + 2y = 0$$

• Change variables using $x = u - 1$ so that the regular singular point is at $u = 0$

$$(u^2 - 2u) \left(\frac{d^2}{du^2} y(u) \right) + (-2u + 2) \left(\frac{d}{du} y(u) \right) + 2y(u) = 0$$

• Assume series solution for $y(u)$

$$y(u) = \sum_{k=0}^{\infty} a_k u^{k+r}$$

□ Rewrite ODE with series expansions

○ Convert $u^m \cdot \left(\frac{d}{du} y(u) \right)$ to series expansion for $m = 0..1$

$$u^m \cdot \left(\frac{d}{du} y(u) \right) = \sum_{k=0}^{\infty} a_k (k+r) u^{k+r-1+m}$$

○ Shift index using $k \rightarrow k+1-m$

$$u^m \cdot \left(\frac{d}{du} y(u) \right) = \sum_{k=-1+m}^{\infty} a_{k+1-m} (k+1-m+r) u^{k+r}$$

○ Convert $u^m \cdot \left(\frac{d^2}{du^2} y(u) \right)$ to series expansion for $m = 1..2$

$$u^m \cdot \left(\frac{d^2}{du^2} y(u) \right) = \sum_{k=0}^{\infty} a_k (k+r)(k+r-1) u^{k+r-2+m}$$

○ Shift index using $k \rightarrow k+2-m$

$$u^m \cdot \left(\frac{d^2}{du^2} y(u) \right) = \sum_{k=-2+m}^{\infty} a_{k+2-m} (k+2-m+r) (k+1-m+r) u^{k+r}$$

Rewrite ODE with series expansions

$$-2a_0 r(-2+r) u^{-1+r} + \left(\sum_{k=0}^{\infty} (-2a_{k+1} (k+1+r) (k+r-1) + a_k (k+r-1) (k+r-2)) u^{k+r} \right)$$

- a_0 cannot be 0 by assumption, giving the indicial equation

$$-2r(-2+r) = 0$$

- Values of r that satisfy the indicial equation

$$r \in \{0, 2\}$$

- Each term in the series must be 0, giving the recursion relation

$$(k+r-1) ((-2k-2r-2) a_{k+1} + a_k (k+r-2)) = 0$$

- Recursion relation that defines series solution to ODE

$$a_{k+1} = \frac{a_k (k+r-2)}{2(k+1+r)}$$

- Recursion relation for $r = 0$; series terminates at $k = 2$

$$a_{k+1} = \frac{a_k (k-2)}{2(k+1)}$$

- Apply recursion relation for $k = 0$

$$a_1 = -a_0$$

- Apply recursion relation for $k = 1$

$$a_2 = -\frac{a_1}{4}$$

- Express in terms of a_0

$$a_2 = \frac{a_0}{4}$$

- Terminating series solution of the ODE for $r = 0$. Use reduction of order to find the second li

$$y(u) = a_0 \cdot \left(1 - u + \frac{1}{4} u^2 \right)$$

- Revert the change of variables $u = 1 + x$

$$\left[y = \frac{a_0 (x-1)^2}{4} \right]$$

- Recursion relation for $r = 2$

$$a_{k+1} = \frac{a_k k}{2(k+3)}$$

- Solution for $r = 2$

$$\left[y(u) = \sum_{k=0}^{\infty} a_k u^{k+2}, a_{k+1} = \frac{a_k k}{2(k+3)} \right]$$

- Revert the change of variables $u = 1 + x$

$$\left[y = \sum_{k=0}^{\infty} a_k (1+x)^{k+2}, a_{k+1} = \frac{a_k k}{2(k+3)} \right]$$

- Combine solutions and rename parameters

$$\left[y = \frac{a_0(x-1)^2}{4} + \left(\sum_{k=0}^{\infty} b_k (1+x)^{k+2} \right), b_{1+k} = \frac{b_k k}{2(k+3)} \right]$$

Maple trace Kovacic algorithm successful

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
trying a symmetry of the form [xi=0, eta=F(x)]
checking if the LODE is missing y
-> Trying a Liouvillian solution using Kovacics algorithm
    A Liouvillian solution exists
    Reducible group (found an exponential solution)
<- Kovacics algorithm successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 14

```
dsolve([(x^2-1)*diff(y(x),x$2)-2*x*diff(y(x),x)+2*y(x)=0,x],singsol=all)
```

$$y(x) = c_2 x^2 + c_1 x + c_2$$

✓ Solution by Mathematica

Time used: 0.086 (sec). Leaf size: 39

```
DSolve[(x^2-1)*y'[x]-2*x*y'[x]+2*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{\sqrt{x^2-1}(c_1(x-1)^2 + c_2 x)}{\sqrt{1-x^2}}$$

9.4 problem 4

9.4.1 Maple step by step solution 1860

Internal problem ID [11726]

Internal file name [OUTPUT/11735_Thursday_April_11_2024_08_49_14_PM_91859302/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.1. Basic theory of linear differential equations. Exercises page 124

Problem number: 4.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "**reduction_of_order**", "**second_order_change_of_variable_on_y_method_2**"

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$(x^2 - x + 1) y'' - (x^2 + x) y' + y(1 + x) = 0$$

Given that one solution of the ode is

$$y_1 = x$$

Given one basis solution $y_1(x)$, then the second basis solution is given by

$$y_2(x) = y_1 \left(\int \frac{e^{-\int p dx}}{y_1^2} dx \right)$$

Where $p(x)$ is the coefficient of y' when the ode is written in the normal form

$$y'' + p(x) y' + q(x) y = f(x)$$

Looking at the ode to solve shows that

$$p(x) = \frac{-x^2 - x}{x^2 - x + 1}$$

Therefore

$$y_2(x) = x \left(\int \frac{e^{-\left(\int \frac{-x^2-x}{x^2-x+1} dx\right)}}{x^2} dx \right)$$

$$y_2(x) = x \int \frac{e^{x+\ln(x^2-x+1)}}{x^2} dx$$

$$y_2(x) = x \left(\int \frac{e^x(x^2-x+1)}{x^2} dx \right)$$

$$y_2(x) = e^x(x-1)$$

Hence the solution is

$$\begin{aligned} y &= c_1 y_1(x) + c_2 y_2(x) \\ &= c_1 x + c_2 e^x(x-1) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 x + c_2 e^x(x-1) \tag{1}$$

Verification of solutions

$$y = c_1 x + c_2 e^x(x-1)$$

Verified OK.

9.4.1 Maple step by step solution

Let's solve

$$(x^2 - x + 1)y'' + (-x^2 - x)y' + y(1 + x) = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = -\frac{(1+x)y}{x^2-x+1} + \frac{x(1+x)y'}{x^2-x+1}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' - \frac{x(1+x)y'}{x^2-x+1} + \frac{(1+x)y}{x^2-x+1} = 0$$

- Check to see if x_0 is a regular singular point

- Define functions

$$\left[P_2(x) = -\frac{(1+x)x}{x^2-x+1}, P_3(x) = \frac{1+x}{x^2-x+1} \right]$$

- $\left(x - \frac{1}{2} + \frac{I\sqrt{3}}{2}\right) \cdot P_2(x)$ is analytic at $x = \frac{1}{2} - \frac{I\sqrt{3}}{2}$

$$\left(\left(x - \frac{1}{2} + \frac{I\sqrt{3}}{2}\right) \cdot P_2(x) \right) \Big|_{x=\frac{1}{2}-\frac{I\sqrt{3}}{2}} = 0$$

- $\left(x - \frac{1}{2} + \frac{I\sqrt{3}}{2}\right)^2 \cdot P_3(x)$ is analytic at $x = \frac{1}{2} - \frac{I\sqrt{3}}{2}$

$$\left(\left(x - \frac{1}{2} + \frac{I\sqrt{3}}{2}\right)^2 \cdot P_3(x) \right) \Big|_{x=\frac{1}{2}-\frac{I\sqrt{3}}{2}} = 0$$

- $x = \frac{1}{2} - \frac{I\sqrt{3}}{2}$ is a regular singular point

Check to see if x_0 is a regular singular point

$$x_0 = \frac{1}{2} - \frac{I\sqrt{3}}{2}$$

- Multiply by denominators

$$(x^2 - x + 1)y'' - x(1+x)y' + y(1+x) = 0$$

- Change variables using $x = u + \frac{1}{2} - \frac{I\sqrt{3}}{2}$ so that the regular singular point is at $u = 0$

$$(u^2 - Iu\sqrt{3}) \left(\frac{d^2}{du^2} y(u) \right) + (-2u - u^2 + Iu\sqrt{3} + I\sqrt{3}) \left(\frac{d}{du} y(u) \right) + \left(\frac{3}{2} + u - \frac{I\sqrt{3}}{2} \right) y(u) = 0$$

- Assume series solution for $y(u)$

$$y(u) = \sum_{k=0}^{\infty} a_k u^{k+r}$$

- Rewrite ODE with series expansions

- Convert $u^m \cdot y(u)$ to series expansion for $m = 0..1$

$$u^m \cdot y(u) = \sum_{k=0}^{\infty} a_k u^{k+r+m}$$

- Shift index using $k- > k - m$

$$u^m \cdot y(u) = \sum_{k=m}^{\infty} a_{k-m} u^{k+r}$$

- Convert $u^m \cdot \left(\frac{d}{du} y(u) \right)$ to series expansion for $m = 0..2$

$$u^m \cdot \left(\frac{d}{du} y(u) \right) = \sum_{k=0}^{\infty} a_k (k+r) u^{k+r-1+m}$$

- Shift index using $k- > k + 1 - m$

$$u^m \cdot \left(\frac{d}{du} y(u) \right) = \sum_{k=-1+m}^{\infty} a_{k+1-m} (k+1-m+r) u^{k+r}$$

- Convert $u^m \cdot \left(\frac{d^2}{du^2} y(u) \right)$ to series expansion for $m = 1..2$

$$u^m \cdot \left(\frac{d^2}{du^2} y(u) \right) = \sum_{k=0}^{\infty} a_k (k+r) (k+r-1) u^{k+r-2+m}$$

- Shift index using $k \rightarrow k+2-m$

$$u^m \cdot \left(\frac{d^2}{du^2} y(u) \right) = \sum_{k=-2+m}^{\infty} a_{k+2-m} (k+2-m+r) (k+1-m+r) u^{k+r}$$

Rewrite ODE with series expansions

$$-I\sqrt{3}r(r-2)a_0u^{r-1} + \left(-I\sqrt{3}(1+r)(r-1)a_1 + \frac{(3+2Ir\sqrt{3}-I\sqrt{3}+2r^2-6r)a_0}{2} \right) u^r + \left(\sum_{k=1}^{\infty} \left(-I\sqrt{3} \right) \right)$$

- a_0 cannot be 0 by assumption, giving the indicial equation

$$-I\sqrt{3}r(r-2) = 0$$

- Values of r that satisfy the indicial equation

$$r \in \{0, 2\}$$

- Each term must be 0

$$-I\sqrt{3}(1+r)(r-1)a_1 + \frac{(3+2Ir\sqrt{3}-I\sqrt{3}+2r^2-6r)a_0}{2} = 0$$

- Each term in the series must be 0, giving the recursion relation

$$\frac{I((2k+2r-1)a_k - 2(k+1+r)a_{k+1}(k+r-1))\sqrt{3}}{2} + \frac{(3+2k^2+2(-3+2r)k+2r^2-6r)a_k}{2} - a_{k-1}(k-2+r) = 0$$

- Shift index using $k \rightarrow k+1$

$$\frac{I((2k+1+2r)a_{k+1} - 2(k+2+r)a_{k+2}(k+r))\sqrt{3}}{2} + \frac{(3+2(k+1)^2+2(-3+2r)(k+1)+2r^2-6r)a_{k+1}}{2} - a_k(k+r-1) = 0$$

- Recursion relation that defines series solution to ODE

$$a_{k+2} = \frac{-\frac{1}{6} \left(2I\sqrt{3}ra_{k+1} + I\sqrt{3}a_{k+1} + 2I\sqrt{3}ka_{k+1} + 2k^2a_{k+1} + 4kra_{k+1} + 2r^2a_{k+1} - 2ka_k - 2a_{k+1}k - 2ra_k - 2a_{k+1}r + 2a_k - a_{k+1} \right) \sqrt{3}}{k^2 + 2kr + r^2 + 2k + 2r}$$

- Recursion relation for $r = 0$

$$a_{k+2} = \frac{-\frac{1}{6} \left(I\sqrt{3}a_{k+1} + 2I\sqrt{3}ka_{k+1} + 2k^2a_{k+1} - 2ka_k - 2a_{k+1}k + 2a_k - a_{k+1} \right) \sqrt{3}}{k^2 + 2k}$$

- Series not valid for $r = 0$, division by 0 in the recursion relation at $k = 0$

$$a_{k+2} = \frac{-\frac{1}{6} \left(I\sqrt{3}a_{k+1} + 2I\sqrt{3}ka_{k+1} + 2k^2a_{k+1} - 2ka_k - 2a_{k+1}k + 2a_k - a_{k+1} \right) \sqrt{3}}{k^2 + 2k}$$

- Recursion relation for $r = 2$

$$a_{k+2} = \frac{-\frac{1}{6}(5I\sqrt{3}a_{k+1}+2I\sqrt{3}ka_{k+1}+2k^2a_{k+1}+6a_{k+1}k+3a_{k+1}-2ka_k-2a_k)\sqrt{3}}{k^2+6k+8}$$

- Solution for $r = 2$

$$\left[y(u) = \sum_{k=0}^{\infty} a_k u^{k+2}, a_{k+2} = \frac{-\frac{1}{6}(5I\sqrt{3}a_{k+1}+2I\sqrt{3}ka_{k+1}+2k^2a_{k+1}+6a_{k+1}k+3a_{k+1}-2ka_k-2a_k)\sqrt{3}}{k^2+6k+8}, -3I\sqrt{3}a_1 + \dots \right]$$

- Revert the change of variables $u = x - \frac{1}{2} + \frac{I\sqrt{3}}{2}$

$$\left[y = \sum_{k=0}^{\infty} a_k \left(x - \frac{1}{2} + \frac{I\sqrt{3}}{2} \right)^{k+2}, a_{k+2} = \frac{-\frac{1}{6}(5I\sqrt{3}a_{k+1}+2I\sqrt{3}ka_{k+1}+2k^2a_{k+1}+6a_{k+1}k+3a_{k+1}-2ka_k-2a_k)\sqrt{3}}{k^2+6k+8}, -3I\sqrt{3}a_1 + \dots \right]$$

Maple trace Kovacic algorithm successful

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
trying a symmetry of the form [xi=0, eta=F(x)]
checking if the LODE is missing y
-> Trying a Liouvillian solution using Kovacics algorithm
    A Liouvillian solution exists
    Reducible group (found an exponential solution)
    Reducible group (found another exponential solution)
<- Kovacics algorithm successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 15

```
dsolve([(x^2-x+1)*diff(y(x),x$2)-(x^2+x)*diff(y(x),x)+(x+1)*y(x)=0,x],singsol=all)
```

$$y(x) = c_1x + c_2e^x(-1 + x)$$

✓ Solution by Mathematica

Time used: 0.093 (sec). Leaf size: 19

```
DSolve[(x^2-x+1)*y'[x]-(x^2+x)*y'[x]+(x+1)*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow c_1x + c_2e^x(x - 1)$$

9.5 problem 5

9.5.1 Maple step by step solution 1865

Internal problem ID [11727]

Internal file name [OUTPUT/11736_Thursday_April_11_2024_08_49_15_PM_62434432/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.1. Basic theory of linear differential equations. Exercises page 124

Problem number: 5.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "**reduction_of_order**", "**second_order_ode_non_constant_coeff_transformation_on_B**"

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$(2x + 1)y'' - 4(1 + x)y' + 4y = 0$$

Given that one solution of the ode is

$$y_1 = e^{2x}$$

Given one basis solution $y_1(x)$, then the second basis solution is given by

$$y_2(x) = y_1 \left(\int \frac{e^{-(\int p dx)}}{y_1^2} dx \right)$$

Where $p(x)$ is the coefficient of y' when the ode is written in the normal form

$$y'' + p(x)y' + q(x)y = f(x)$$

Looking at the ode to solve shows that

$$p(x) = \frac{-4x - 4}{2x + 1}$$

Therefore

$$y_2(x) = e^{2x} \left(\int e^{-\left(\int \frac{-4x-4}{2x+1} dx\right)} e^{-4x} dx \right)$$

$$y_2(x) = e^{2x} \int \frac{e^{2x+\ln(2x+1)}}{e^{4x}} dx$$

$$y_2(x) = e^{2x} \left(\int (2x+1) e^{-2x} dx \right)$$

$$y_2(x) = -e^{2x}(1+x)e^{-2x}$$

Hence the solution is

$$\begin{aligned} y &= c_1 y_1(x) + c_2 y_2(x) \\ &= c_1 e^{2x} - c_2 e^{2x}(1+x)e^{-2x} \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 e^{2x} - c_2 e^{2x}(1+x)e^{-2x} \quad (1)$$

Verification of solutions

$$y = c_1 e^{2x} - c_2 e^{2x}(1+x)e^{-2x}$$

Verified OK.

9.5.1 Maple step by step solution

Let's solve

$$(2x+1)y'' + (-4x-4)y' + 4y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = -\frac{4y}{2x+1} + \frac{4(1+x)y'}{2x+1}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' - \frac{4(1+x)y'}{2x+1} + \frac{4y}{2x+1} = 0$$

- Check to see if $x_0 = -\frac{1}{2}$ is a regular singular point
 - Define functions

$$\left[P_2(x) = -\frac{4(1+x)}{2x+1}, P_3(x) = \frac{4}{2x+1} \right]$$

- $(x + \frac{1}{2}) \cdot P_2(x)$ is analytic at $x = -\frac{1}{2}$

$$\left. \left((x + \frac{1}{2}) \cdot P_2(x) \right) \right|_{x=-\frac{1}{2}} = -1$$

- $(x + \frac{1}{2})^2 \cdot P_3(x)$ is analytic at $x = -\frac{1}{2}$

$$\left. \left((x + \frac{1}{2})^2 \cdot P_3(x) \right) \right|_{x=-\frac{1}{2}} = 0$$

- $x = -\frac{1}{2}$ is a regular singular point

Check to see if $x_0 = -\frac{1}{2}$ is a regular singular point

$$x_0 = -\frac{1}{2}$$

- Multiply by denominators

$$(2x + 1)y'' + (-4x - 4)y' + 4y = 0$$

- Change variables using $x = u - \frac{1}{2}$ so that the regular singular point is at $u = 0$

$$2u \left(\frac{d^2}{du^2} y(u) \right) + (-4u - 2) \left(\frac{d}{du} y(u) \right) + 4y(u) = 0$$

- Assume series solution for $y(u)$

$$y(u) = \sum_{k=0}^{\infty} a_k u^{k+r}$$

- Rewrite ODE with series expansions

- Convert $u^m \cdot \left(\frac{d}{du} y(u) \right)$ to series expansion for $m = 0..1$

$$u^m \cdot \left(\frac{d}{du} y(u) \right) = \sum_{k=0}^{\infty} a_k (k+r) u^{k+r-1+m}$$

- Shift index using $k \rightarrow k+1-m$

$$u^m \cdot \left(\frac{d}{du} y(u) \right) = \sum_{k=-1+m}^{\infty} a_{k+1-m} (k+1-m+r) u^{k+r}$$

- Convert $u \cdot \left(\frac{d^2}{du^2} y(u) \right)$ to series expansion

$$u \cdot \left(\frac{d^2}{du^2} y(u) \right) = \sum_{k=0}^{\infty} a_k (k+r)(k+r-1) u^{k+r-1}$$

- Shift index using $k \rightarrow k+1$

$$u \cdot \left(\frac{d^2}{du^2} y(u) \right) = \sum_{k=-1}^{\infty} a_{k+1} (k+1+r)(k+r) u^{k+r}$$

Rewrite ODE with series expansions

$$2a_0r(-2+r)u^{-1+r} + \left(\sum_{k=0}^{\infty} (2a_{k+1}(k+1+r)(k+r-1) - 4a_k(k+r-1))u^{k+r} \right) = 0$$

- a_0 cannot be 0 by assumption, giving the indicial equation

$$2r(-2+r) = 0$$

- Values of r that satisfy the indicial equation

$$r \in \{0, 2\}$$

- Each term in the series must be 0, giving the recursion relation

$$2(a_{k+1}(k+1+r) - 2a_k)(k+r-1) = 0$$

- Recursion relation that defines series solution to ODE

$$a_{k+1} = \frac{2a_k}{k+1+r}$$

- Recursion relation for $r = 0$

$$a_{k+1} = \frac{2a_k}{k+1}$$

- Solution for $r = 0$

$$\left[y(u) = \sum_{k=0}^{\infty} a_k u^k, a_{k+1} = \frac{2a_k}{k+1} \right]$$

- Revert the change of variables $u = x + \frac{1}{2}$

$$\left[y = \sum_{k=0}^{\infty} a_k \left(x + \frac{1}{2}\right)^k, a_{k+1} = \frac{2a_k}{k+1} \right]$$

- Recursion relation for $r = 2$

$$a_{k+1} = \frac{2a_k}{k+3}$$

- Solution for $r = 2$

$$\left[y(u) = \sum_{k=0}^{\infty} a_k u^{k+2}, a_{k+1} = \frac{2a_k}{k+3} \right]$$

- Revert the change of variables $u = x + \frac{1}{2}$

$$\left[y = \sum_{k=0}^{\infty} a_k \left(x + \frac{1}{2}\right)^{k+2}, a_{k+1} = \frac{2a_k}{k+3} \right]$$

- Combine solutions and rename parameters

$$\left[y = \left(\sum_{k=0}^{\infty} a_k \left(x + \frac{1}{2}\right)^k \right) + \left(\sum_{k=0}^{\infty} b_k \left(x + \frac{1}{2}\right)^{k+2} \right), a_{1+k} = \frac{2a_k}{1+k}, b_{1+k} = \frac{2b_k}{k+3} \right]$$

Maple trace Kovacic algorithm successful

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
checking if the LODE is of Euler type  
trying a symmetry of the form [xi=0, eta=F(x)]  
checking if the LODE is missing y  
-> Trying a Liouvillian solution using Kovacics algorithm  
  A Liouvillian solution exists  
  Reducible group (found an exponential solution)  
  Reducible group (found another exponential solution)  
<- Kovacics algorithm successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 15

```
dsolve([(2*x+1)*diff(y(x),x$2)-4*(x+1)*diff(y(x),x)+4*y(x)=0,exp(2*x)],singsol=all)
```

$$y(x) = c_2 e^{2x} + c_1 x + c_1$$

✓ Solution by Mathematica

Time used: 0.125 (sec). Leaf size: 23

```
DSolve[(2*x+1)*y'[x]-4*(x+1)*y'[x]+4*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow c_1 e^{2x+1} - c_2(x+1)$$

9.6 problem 6

9.6.1 Maple step by step solution 1870

Internal problem ID [11728]

Internal file name [OUTPUT/11737_Thursday_April_11_2024_08_49_15_PM_96516632/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.1. Basic theory of linear differential equations. Exercises page 124

Problem number: 6.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "**reduction_of_order**", "**second_order_change_of_variable_on_y_method_2**"

Maple gives the following as the ode type

`[[_2nd_order , _with_linear_symmetries]]`

$$(x^3 - x^2) y'' - (x^3 + 2x^2 - 2x) y' + (2x^2 + 2x - 2) y = 0$$

Given that one solution of the ode is

$$y_1 = x^2$$

Given one basis solution $y_1(x)$, then the second basis solution is given by

$$y_2(x) = y_1 \left(\int \frac{e^{-\int p dx}}{y_1^2} dx \right)$$

Where $p(x)$ is the coefficient of y' when the ode is written in the normal form

$$y'' + p(x) y' + q(x) y = f(x)$$

Looking at the ode to solve shows that

$$p(x) = \frac{-x^3 - 2x^2 + 2x}{x^3 - x^2}$$

Therefore

$$y_2(x) = x^2 \left(\int \frac{e^{-\left(\int \frac{-x^3 - 2x^2 + 2x}{x^3 - x^2} dx\right)}}{x^4} dx \right)$$

$$y_2(x) = x^2 \int \frac{e^{x + \ln(x-1) + 2 \ln(x)}}{x^4} dx$$

$$y_2(x) = x^2 \left(\int \frac{(x-1)e^x}{x^2} dx \right)$$

$$y_2(x) = x e^x$$

Hence the solution is

$$\begin{aligned} y &= c_1 y_1(x) + c_2 y_2(x) \\ &= c_1 x^2 + c_2 x e^x \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 x^2 + c_2 x e^x \tag{1}$$

Verification of solutions

$$y = c_1 x^2 + c_2 x e^x$$

Verified OK.

9.6.1 Maple step by step solution

Let's solve

$$y'' x^2 (x-1) + (-x^3 - 2x^2 + 2x) y' + (2x^2 + 2x - 2) y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = -\frac{2(x^2+x-1)y}{x^2(x-1)} + \frac{(x^2+2x-2)y'}{x(x-1)}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' - \frac{(x^2+2x-2)y'}{x(x-1)} + \frac{2(x^2+x-1)y}{x^2(x-1)} = 0$$

- Check to see if x_0 is a regular singular point

- Define functions

$$\left[P_2(x) = -\frac{x^2+2x-2}{x(x-1)}, P_3(x) = \frac{2(x^2+x-1)}{x^2(x-1)} \right]$$

- $x \cdot P_2(x)$ is analytic at $x = 0$

$$(x \cdot P_2(x)) \Big|_{x=0} = -2$$

- $x^2 \cdot P_3(x)$ is analytic at $x = 0$

$$(x^2 \cdot P_3(x)) \Big|_{x=0} = 2$$

- $x = 0$ is a regular singular point

Check to see if x_0 is a regular singular point

$$x_0 = 0$$

- Multiply by denominators

$$y''x^2(x-1) - x(x^2+2x-2)y' + (2x^2+2x-2)y = 0$$

- Assume series solution for y

$$y = \sum_{k=0}^{\infty} a_k x^{k+r}$$

- Rewrite ODE with series expansions

- Convert $x^m \cdot y$ to series expansion for $m = 0..2$

$$x^m \cdot y = \sum_{k=0}^{\infty} a_k x^{k+r+m}$$

- Shift index using $k \rightarrow k - m$

$$x^m \cdot y = \sum_{k=m}^{\infty} a_{k-m} x^{k+r}$$

- Convert $x^m \cdot y'$ to series expansion for $m = 1..3$

$$x^m \cdot y' = \sum_{k=0}^{\infty} a_k (k+r) x^{k+r-1+m}$$

- Shift index using $k \rightarrow k + 1 - m$

$$x^m \cdot y' = \sum_{k=-1+m}^{\infty} a_{k+1-m} (k+1-m+r) x^{k+r}$$

- Convert $x^m \cdot y''$ to series expansion for $m = 2..3$

$$x^m \cdot y'' = \sum_{k=0}^{\infty} a_k (k+r)(k+r-1) x^{k+r-2+m}$$

- Shift index using $k \rightarrow k + 2 - m$

$$x^m \cdot y'' = \sum_{k=-2+m}^{\infty} a_{k+2-m} (k+2-m+r) (k+1-m+r) x^{k+r}$$

Rewrite ODE with series expansions

$$-a_0(-1+r)(-2+r)x^r + (-a_1r(-1+r) + a_0(-1+r)(-2+r))x^{1+r} + \left(\sum_{k=2}^{\infty} (-a_k(k+r-1)) \right) x^{k+r}$$

- a_0 cannot be 0 by assumption, giving the indicial equation

$$-(-1+r)(-2+r) = 0$$

- Values of r that satisfy the indicial equation

$$r \in \{1, 2\}$$

- Each term must be 0

$$-a_1r(-1+r) + a_0(-1+r)(-2+r) = 0$$

- Solve for the dependent coefficient(s)

$$a_1 = \frac{a_0(-2+r)}{r}$$

- Each term in the series must be 0, giving the recursion relation

$$-a_k(k+r-1)(k+r-2) + a_{k-1}(k+r-2)(k-3+r) - a_{k-2}(k-4+r) = 0$$

- Shift index using $k \rightarrow k + 2$

$$-a_{k+2}(k+1+r)(k+r) + a_{k+1}(k+r)(k+r-1) - a_k(k+r-2) = 0$$

- Recursion relation that defines series solution to ODE

$$a_{k+2} = \frac{k^2 a_{k+1} + 2k r a_{k+1} + r^2 a_{k+1} - k a_k - k a_{k+1} - r a_k - r a_{k+1} + 2 a_k}{(k+1+r)(k+r)}$$

- Recursion relation for $r = 1$

$$a_{k+2} = \frac{k^2 a_{k+1} - k a_k + k a_{k+1} + a_k}{(k+2)(k+1)}$$

- Solution for $r = 1$

$$\left[y = \sum_{k=0}^{\infty} a_k x^{k+1}, a_{k+2} = \frac{k^2 a_{k+1} - k a_k + k a_{k+1} + a_k}{(k+2)(k+1)}, a_1 = -a_0 \right]$$

- Recursion relation for $r = 2$

$$a_{k+2} = \frac{k^2 a_{k+1} - k a_k + 3k a_{k+1} + 2 a_{k+1}}{(k+3)(k+2)}$$

- Solution for $r = 2$

$$\left[y = \sum_{k=0}^{\infty} a_k x^{k+2}, a_{k+2} = \frac{k^2 a_{k+1} - k a_k + 3k a_{k+1} + 2 a_{k+1}}{(k+3)(k+2)}, a_1 = 0 \right]$$

- Combine solutions and rename parameters

$$\left[y = \left(\sum_{k=0}^{\infty} a_k x^{1+k} \right) + \left(\sum_{k=0}^{\infty} b_k x^{k+2} \right), a_{k+2} = \frac{k^2 a_{1+k} - k a_k + k a_{1+k} + a_k}{(k+2)(1+k)}, a_1 = -a_0, b_{k+2} = \frac{k^2 b_{1+k} - k b_k + 3 k b_k}{(k+3)(k+2)} \right]$$

Maple trace **Kovacic algorithm successful**

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
trying a symmetry of the form [xi=0, eta=F(x)]
checking if the LODE is missing y
-> Trying a Liouvillian solution using Kovacics algorithm
    A Liouvillian solution exists
    Reducible group (found an exponential solution)
    Reducible group (found another exponential solution)
<- Kovacics algorithm successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 14

```
dsolve([(x^3-x^2)*diff(y(x),x$2)-(x^3+2*x^2-2*x)*diff(y(x),x)+(2*x^2+2*x-2)*y(x)=0,x^2],sing
```

$$y(x) = x(c_2 e^x + c_1 x)$$

✓ Solution by Mathematica

Time used: 0.101 (sec). Leaf size: 36

```
DSolve[(x^3-x^2)*y'[x]-(x^3+2*x^2-2*x)*y'[x]+(2*x^2+2*x-2)*y[x]==0,y[x],x,IncludeSingularSo
```

$$y(x) \rightarrow -\frac{\sqrt{1-xx}(c_2 x - c_1 e^x)}{\sqrt{x-1}}$$

9.7 problem 8

9.7.1 Solving as second order linear constant coeff ode	1874
9.7.2 Solving using Kovacic algorithm	1877
9.7.3 Maple step by step solution	1882

Internal problem ID [11729]

Internal file name [OUTPUT/11738_Thursday_April_11_2024_08_49_16_PM_36339295/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.1. Basic theory of linear differential equations. Exercises page 124

Problem number: 8.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$y'' - 3y' + 2y = 4x^2$$

9.7.1 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = -3, C = 2, f(x) = 4x^2$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' - 3y' + 2y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = -3, C = 2$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} - 3\lambda e^{\lambda x} + 2e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 - 3\lambda + 2 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = -3, C = 2$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{3}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{-3^2 - (4)(1)(2)} \\ &= \frac{3}{2} \pm \frac{1}{2} \end{aligned}$$

Hence

$$\begin{aligned} \lambda_1 &= \frac{3}{2} + \frac{1}{2} \\ \lambda_2 &= \frac{3}{2} - \frac{1}{2} \end{aligned}$$

Which simplifies to

$$\begin{aligned} \lambda_1 &= 2 \\ \lambda_2 &= 1 \end{aligned}$$

Since roots are real and distinct, then the solution is

$$\begin{aligned} y &= c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x} \\ y &= c_1 e^{(2)x} + c_2 e^{(1)x} \end{aligned}$$

Or

$$y = c_1 e^{2x} + c_2 e^x$$

Therefore the homogeneous solution y_h is

$$y_h = c_1 e^{2x} + c_2 e^x$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$x^2$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{1, x, x^2\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^x, e^{2x}\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_3x^2 + A_2x + A_1$$

The unknowns $\{A_1, A_2, A_3\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$2A_3x^2 + 2A_2x - 6xA_3 + 2A_1 - 3A_2 + 2A_3 = 4x^2$$

Solving for the unknowns by comparing coefficients results in

$$[A_1 = 7, A_2 = 6, A_3 = 2]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = 2x^2 + 6x + 7$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1e^{2x} + c_2e^x) + (2x^2 + 6x + 7) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1e^{2x} + c_2e^x + 2x^2 + 6x + 7 \tag{1}$$

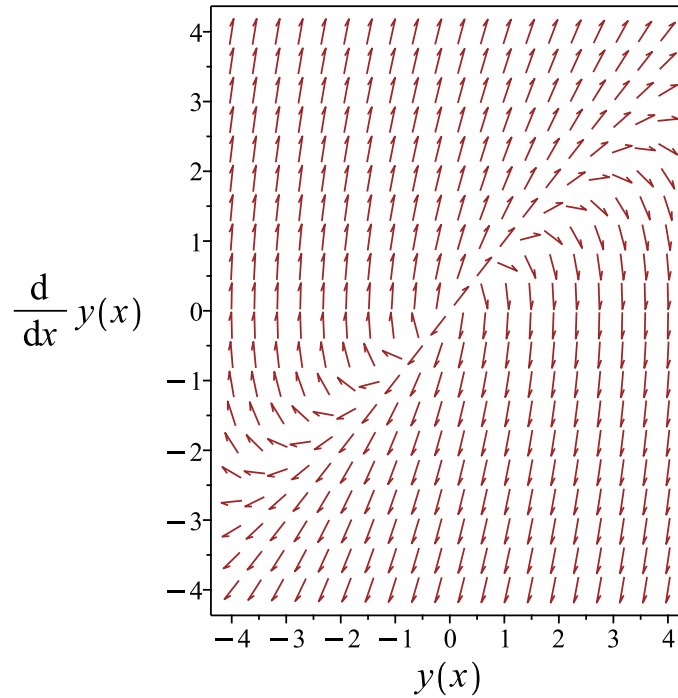


Figure 353: Slope field plot

Verification of solutions

$$y = c_1 e^{2x} + c_2 e^x + 2x^2 + 6x + 7$$

Verified OK.

9.7.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' - 3y' + 2y = 0 \tag{1}$$

$$Ay'' + By' + Cy = 0 \tag{2}$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= -3 \\ C &= 2 \end{aligned} \tag{3}$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{1}{4} \tag{6}$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 1 \\ t &= 4 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = \frac{z(x)}{4} \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 275: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = \frac{1}{4}$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = e^{-\frac{x}{2}}$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-3}{1} dx} \\ &= z_1 e^{\frac{3x}{2}} \\ &= z_1 \left(e^{\frac{3x}{2}} \right) \end{aligned}$$

Which simplifies to

$$y_1 = e^x$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{-3}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{3x}}{(y_1)^2} dx \\ &= y_1(e^x) \end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1(e^x) + c_2(e^x(e^x))\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' - 3y' + 2y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = e^x c_1 + c_2 e^{2x}$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$x^2$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{1, x, x^2\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^x, e^{2x}\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_3 x^2 + A_2 x + A_1$$

The unknowns $\{A_1, A_2, A_3\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$2A_3 x^2 + 2A_2 x - 6xA_3 + 2A_1 - 3A_2 + 2A_3 = 4x^2$$

Solving for the unknowns by comparing coefficients results in

$$[A_1 = 7, A_2 = 6, A_3 = 2]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = 2x^2 + 6x + 7$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (e^x c_1 + c_2 e^{2x}) + (2x^2 + 6x + 7) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = e^x c_1 + c_2 e^{2x} + 2x^2 + 6x + 7 \quad (1)$$

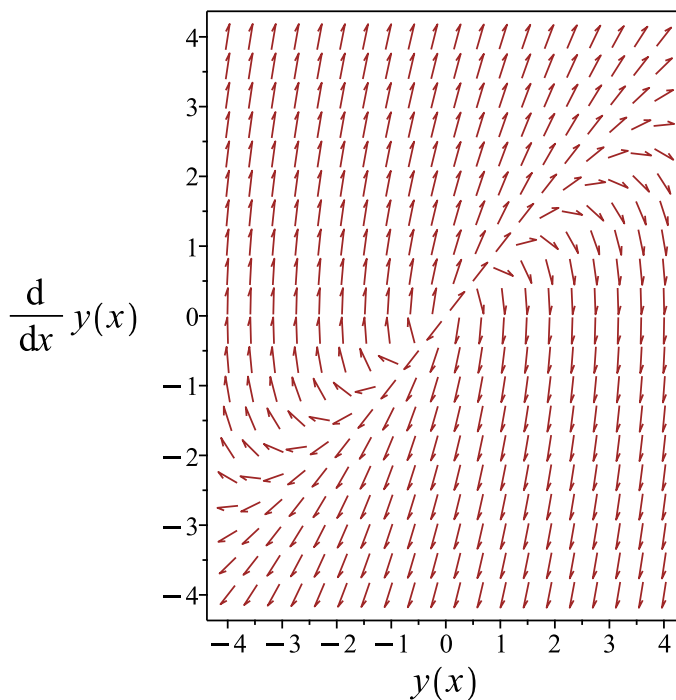


Figure 354: Slope field plot

Verification of solutions

$$y = e^x c_1 + c_2 e^{2x} + 2x^2 + 6x + 7$$

Verified OK.

9.7.3 Maple step by step solution

Let's solve

$$y'' - 3y' + 2y = 4x^2$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of homogeneous ODE

$$r^2 - 3r + 2 = 0$$

- Factor the characteristic polynomial

$$(r - 1)(r - 2) = 0$$

- Roots of the characteristic polynomial

$$r = (1, 2)$$

- 1st solution of the homogeneous ODE

$$y_1(x) = e^x$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = e^{2x}$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = e^x c_1 + c_2 e^{2x} + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = 4x^2 \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} e^x & e^{2x} \\ e^x & 2e^{2x} \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = e^{3x}$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = -4e^x \left(\int x^2 e^{-x} dx \right) + 4e^{2x} \left(\int x^2 e^{-2x} dx \right)$$

- Compute integrals

$$y_p(x) = 2x^2 + 6x + 7$$

- Substitute particular solution into general solution to ODE

$$y = e^x c_1 + c_2 e^{2x} + 2x^2 + 6x + 7$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
trying a double symmetry of the form [xi=0, eta=F(x)]
<- double symmetry of the form [xi=0, eta=F(x)] successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 24

```
dsolve(diff(y(x),x$2)-3*diff(y(x),x)+2*y(x)=4*x^2,y(x), singsol=all)
```

$$y(x) = e^{2x}c_1 + c_2e^x + 2x^2 + 6x + 7$$

✓ Solution by Mathematica

Time used: 0.014 (sec). Leaf size: 29

```
DSolve[y''[x]-3*y'[x]+2*y[x]==4*x^2,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow 2x^2 + 6x + c_1e^x + c_2e^{2x} + 7$$

9.8 problem 9

9.8.1 Solving as second order linear constant coeff ode	1884
9.8.2 Solving using Kovacic algorithm	1887
9.8.3 Maple step by step solution	1892

Internal problem ID [11730]

Internal file name [OUTPUT/11739_Thursday_April_11_2024_08_49_16_PM_66646944/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.1. Basic theory of linear differential equations. Exercises page 124

Problem number: 9.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$y'' - 5y' + 6y = 2 - 12x + 6e^x$$

9.8.1 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = -5, C = 6, f(x) = 2 - 12x + 6e^x$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' - 5y' + 6y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = -5, C = 6$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} - 5\lambda e^{\lambda x} + 6 e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 - 5\lambda + 6 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = -5, C = 6$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{5}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{-5^2 - (4)(1)(6)} \\ &= \frac{5}{2} \pm \frac{1}{2} \end{aligned}$$

Hence

$$\begin{aligned} \lambda_1 &= \frac{5}{2} + \frac{1}{2} \\ \lambda_2 &= \frac{5}{2} - \frac{1}{2} \end{aligned}$$

Which simplifies to

$$\begin{aligned} \lambda_1 &= 3 \\ \lambda_2 &= 2 \end{aligned}$$

Since roots are real and distinct, then the solution is

$$\begin{aligned} y &= c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x} \\ y &= c_1 e^{(3)x} + c_2 e^{(2)x} \end{aligned}$$

Or

$$y = c_1 e^{3x} + c_2 e^{2x}$$

Therefore the homogeneous solution y_h is

$$y_h = c_1 e^{3x} + c_2 e^{2x}$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$2 - 12x + 6e^x$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{e^x\}, \{1, x\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^{2x}, e^{3x}\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1e^x + A_2 + A_3x$$

The unknowns $\{A_1, A_2, A_3\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$2A_1e^x - 5A_3 + 6A_2 + 6A_3x = 2 - 12x + 6e^x$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = 3, A_2 = -\frac{4}{3}, A_3 = -2 \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = 3e^x - \frac{4}{3} - 2x$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1e^{3x} + c_2e^{2x}) + \left(3e^x - \frac{4}{3} - 2x \right) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1e^{3x} + c_2e^{2x} + 3e^x - \frac{4}{3} - 2x \quad (1)$$

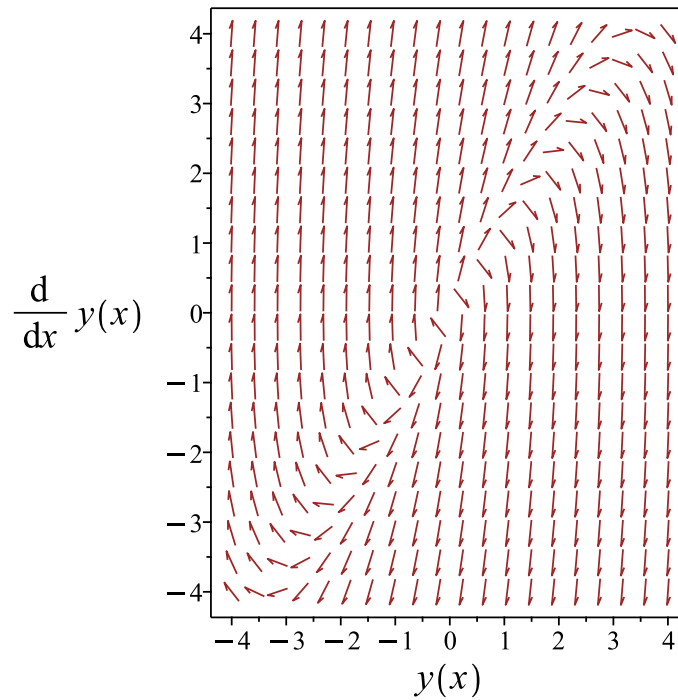


Figure 355: Slope field plot

Verification of solutions

$$y = c_1 e^{3x} + c_2 e^{2x} + 3e^x - \frac{4}{3} - 2x$$

Verified OK.

9.8.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' - 5y' + 6y = 0 \tag{1}$$

$$Ay'' + By' + Cy = 0 \tag{2}$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= -5 \\ C &= 6 \end{aligned} \tag{3}$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{1}{4} \tag{6}$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 1 \\ t &= 4 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = \frac{z(x)}{4} \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 277: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = \frac{1}{4}$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = e^{-\frac{x}{2}}$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-5}{1} dx} \\ &= z_1 e^{\frac{5x}{2}} \\ &= z_1 \left(e^{\frac{5x}{2}} \right) \end{aligned}$$

Which simplifies to

$$y_1 = e^{2x}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{-5}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{5x}}{(y_1)^2} dx \\ &= y_1 (e^x) \end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (e^{2x}) + c_2 (e^{2x}(e^x))\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' - 5y' + 6y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1 e^{2x} + e^{3x} c_2$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$2 - 12x + 6e^x$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{e^x\}, \{1, x\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^{2x}, e^{3x}\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1 e^x + A_2 + A_3 x$$

The unknowns $\{A_1, A_2, A_3\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$2A_1 e^x - 5A_3 + 6A_2 + 6A_3 x = 2 - 12x + 6e^x$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = 3, A_2 = -\frac{4}{3}, A_3 = -2 \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = 3e^x - \frac{4}{3} - 2x$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 e^{2x} + e^{3x} c_2) + \left(3e^x - \frac{4}{3} - 2x \right) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 e^{2x} + e^{3x} c_2 + 3e^x - \frac{4}{3} - 2x \quad (1)$$

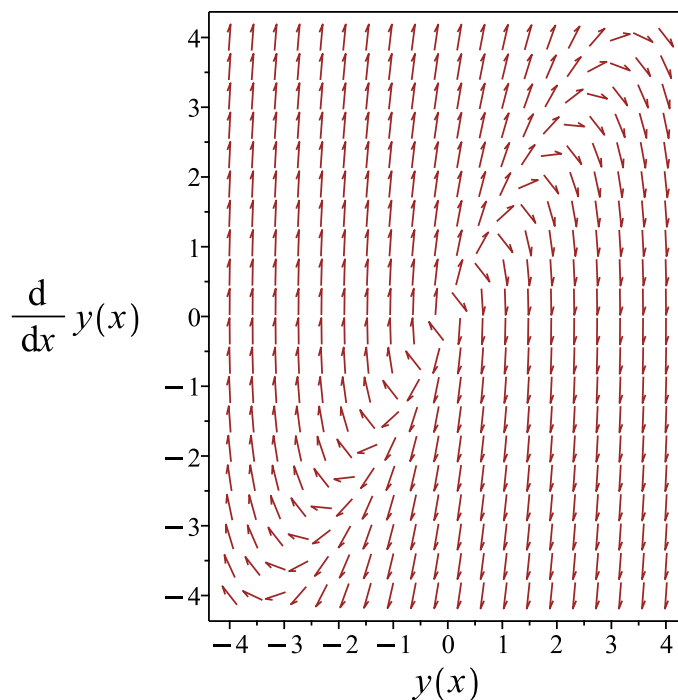


Figure 356: Slope field plot

Verification of solutions

$$y = c_1 e^{2x} + e^{3x} c_2 + 3e^x - \frac{4}{3} - 2x$$

Verified OK.

9.8.3 Maple step by step solution

Let's solve

$$y'' - 5y' + 6y = 2 - 12x + 6e^x$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of homogeneous ODE

$$r^2 - 5r + 6 = 0$$

- Factor the characteristic polynomial

$$(r - 2)(r - 3) = 0$$

- Roots of the characteristic polynomial

$$r = (2, 3)$$

- 1st solution of the homogeneous ODE

$$y_1(x) = e^{2x}$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = e^{3x}$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = c_1 e^{2x} + e^{3x} c_2 + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = 2 - 12x + 6e^x \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} e^{2x} & e^{3x} \\ 2e^{2x} & 3e^{3x} \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = e^{5x}$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = -2e^{2x} \left(\int (1 - 6x + 3e^x) e^{-2x} dx \right) + 2e^{3x} \left(\int (1 - 6x + 3e^x) e^{-3x} dx \right)$$

- Compute integrals

$$y_p(x) = 3e^x - \frac{4}{3} - 2x$$

- Substitute particular solution into general solution to ODE

$$y = c_1 e^{2x} + e^{3x} c_2 + 3e^x - \frac{4}{3} - 2x$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
trying a double symmetry of the form [xi=0, eta=F(x)]
-> Try solving first the homogeneous part of the ODE
    checking if the LODE has constant coefficients
    <- constant coefficients successful
<- solving first the homogeneous part of the ODE successful`

```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 25

```
dsolve(diff(y(x),x$2)-5*diff(y(x),x)+6*y(x)=2-12*x+6*exp(x),y(x), singsol=all)
```

$$y(x) = c_2 e^{2x} + c_1 e^{3x} + 3e^x - 2x - \frac{4}{3}$$

✓ Solution by Mathematica

Time used: 0.15 (sec). Leaf size: 33

```
DSolve[y''[x]-5*y'[x]+6*y[x]==2-12*x+6*Exp[x],y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow -2x + 3e^x + c_1 e^{2x} + c_2 e^{3x} - \frac{4}{3}$$

10 Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients.

Exercises page 135

10.1 problem 1	1896
10.2 problem 2	1904
10.3 problem 3	1912
10.4 problem 4	1920
10.5 problem 5	1928
10.6 problem 6	1933
10.7 problem 7	1938
10.8 problem 8	1947
10.9 problem 9	1956
10.10 problem 10	1964
10.11 problem 11	1972
10.12 problem 12	1982
10.13 problem 13	1993
10.14 problem 14	1998
10.15 problem 15	2004
10.16 problem 16	2006
10.17 problem 17	2011
10.18 problem 18	2016
10.19 problem 19	2018
10.20 problem 20	2026
10.21 problem 21	2033
10.22 problem 22	2039
10.23 problem 23	2046
10.24 problem 24	2053
10.25 problem 25	2060
10.26 problem 26	2070
10.27 problem 27	2080
10.28 problem 28	2090
10.29 problem 29	2100
10.30 problem 30	2112
10.31 problem 31	2124
10.32 problem 32	2136
10.33 problem 33	2148
10.34 problem 34	2158

10.35problem 35	2168
10.36problem 36	2178
10.37problem 37	2188
10.38problem 38	2199
10.39problem 39	2209
10.40problem 40	2216
10.41problem 41	2223
10.42problem 42	2231
10.43problem 45	2237
10.44problem 46	2243

10.1 problem 1

10.1.1 Solving as second order linear constant coeff ode	1896
10.1.2 Solving using Kovacic algorithm	1898
10.1.3 Maple step by step solution	1902

Internal problem ID [11731]

Internal file name [OUTPUT/11740_Thursday_April_11_2024_08_49_17_PM_75053001/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 1.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _missing_x]]
```

$$y'' - 5y' + 6y = 0$$

10.1.1 Solving as second order linear constant coeff ode

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = -5, C = 6$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} - 5\lambda e^{\lambda x} + 6 e^{\lambda x} = 0 \tag{1}$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 - 5\lambda + 6 = 0 \tag{2}$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = -5, C = 6$ into the above gives

$$\begin{aligned}\lambda_{1,2} &= \frac{5}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{-5^2 - (4)(1)(6)} \\ &= \frac{5}{2} \pm \frac{1}{2}\end{aligned}$$

Hence

$$\lambda_1 = \frac{5}{2} + \frac{1}{2}$$

$$\lambda_2 = \frac{5}{2} - \frac{1}{2}$$

Which simplifies to

$$\lambda_1 = 3$$

$$\lambda_2 = 2$$

Since roots are real and distinct, then the solution is

$$y = c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x}$$

$$y = c_1 e^{(3)x} + c_2 e^{(2)x}$$

Or

$$y = c_1 e^{3x} + c_2 e^{2x}$$

Summary

The solution(s) found are the following

$$y = c_1 e^{3x} + c_2 e^{2x} \tag{1}$$

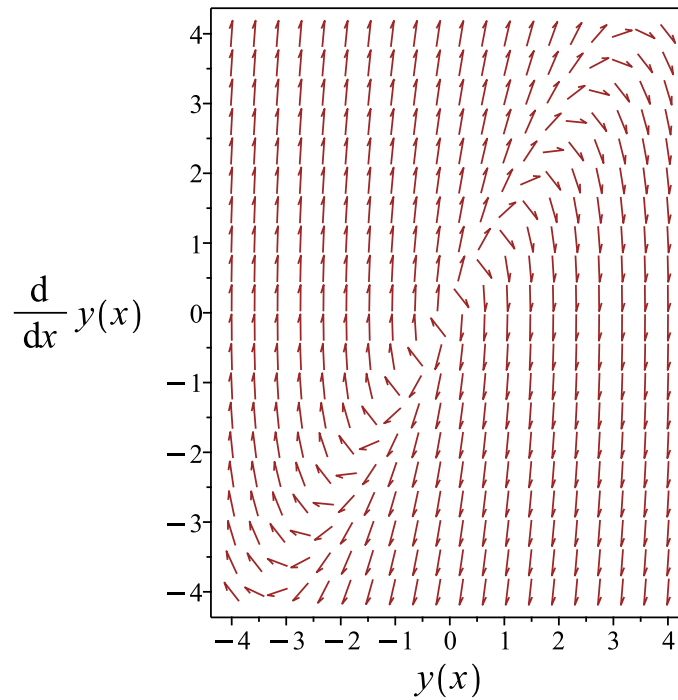


Figure 357: Slope field plot

Verification of solutions

$$y = c_1 e^{3x} + c_2 e^{2x}$$

Verified OK.

10.1.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' - 5y' + 6y = 0 \tag{1}$$

$$Ay'' + By' + Cy = 0 \tag{2}$$

Comparing (1) and (2) shows that

$$A = 1$$

$$B = -5 \tag{3}$$

$$C = 6$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{1}{4} \tag{6}$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 1 \\ t &= 4 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = \frac{z(x)}{4} \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 279: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned}O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0\end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = \frac{1}{4}$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = e^{-\frac{x}{2}}$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned}y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-5}{1} dx} \\ &= z_1 e^{\frac{5x}{2}} \\ &= z_1 \left(e^{\frac{5x}{2}} \right)\end{aligned}$$

Which simplifies to

$$y_1 = e^{2x}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{-5}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{5x}}{(y_1)^2} dx \\ &= y_1(e^x)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (e^{2x}) + c_2 (e^{2x}(e^x))\end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 e^{2x} + e^{3x} c_2 \tag{1}$$

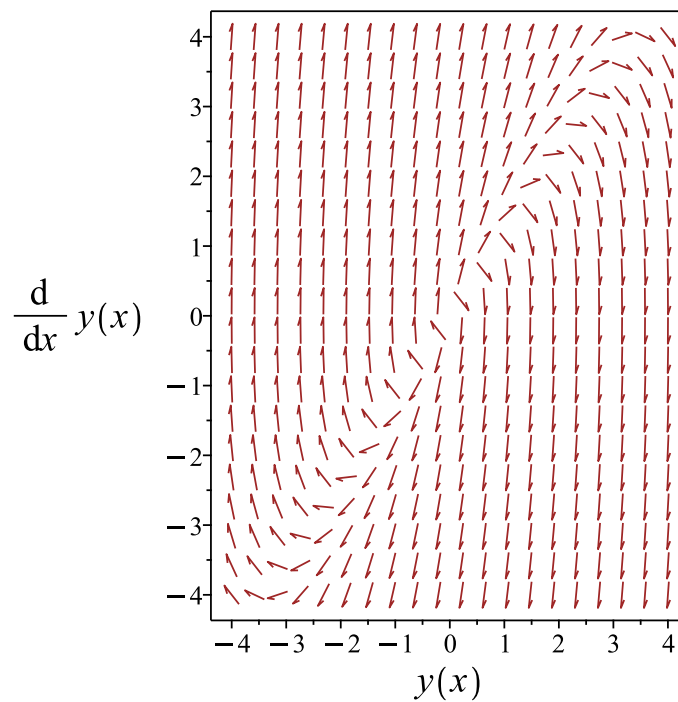


Figure 358: Slope field plot

Verification of solutions

$$y = c_1 e^{2x} + e^{3x} c_2$$

Verified OK.

10.1.3 Maple step by step solution

Let's solve

$$y'' - 5y' + 6y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of ODE

$$r^2 - 5r + 6 = 0$$

- Factor the characteristic polynomial

$$(r - 2)(r - 3) = 0$$

- Roots of the characteristic polynomial

$$r = (2, 3)$$

- 1st solution of the ODE

$$y_1(x) = e^{2x}$$

- 2nd solution of the ODE

$$y_2(x) = e^{3x}$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x)$$

- Substitute in solutions

$$y = c_1 e^{2x} + e^{3x} c_2$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
<- constant coefficients successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 17

```
dsolve(diff(y(x),x$2)-5*diff(y(x),x)+6*y(x)=0,y(x), singsol=all)
```

$$y(x) = e^{2x}c_1 + c_2e^{3x}$$

✓ Solution by Mathematica

Time used: 0.013 (sec). Leaf size: 20

```
DSolve[y''[x]-5*y'[x]+6*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^{2x}(c_2e^x + c_1)$$

10.2 problem 2

10.2.1 Solving as second order linear constant coeff ode	1904
10.2.2 Solving using Kovacic algorithm	1906
10.2.3 Maple step by step solution	1910

Internal problem ID [11732]

Internal file name [OUTPUT/11741_Thursday_April_11_2024_08_49_17_PM_36620420/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 2.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _missing_x]]
```

$$y'' - 2y' - 3y = 0$$

10.2.1 Solving as second order linear constant coeff ode

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = -2, C = -3$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} - 2\lambda e^{\lambda x} - 3e^{\lambda x} = 0 \tag{1}$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 - 2\lambda - 3 = 0 \tag{2}$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = -2, C = -3$ into the above gives

$$\begin{aligned}\lambda_{1,2} &= \frac{2}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{-2^2 - (4)(1)(-3)} \\ &= 1 \pm 2\end{aligned}$$

Hence

$$\lambda_1 = 1 + 2$$

$$\lambda_2 = 1 - 2$$

Which simplifies to

$$\lambda_1 = 3$$

$$\lambda_2 = -1$$

Since roots are real and distinct, then the solution is

$$y = c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x}$$

$$y = c_1 e^{(3)x} + c_2 e^{(-1)x}$$

Or

$$y = c_1 e^{3x} + c_2 e^{-x}$$

Summary

The solution(s) found are the following

$$y = c_1 e^{3x} + c_2 e^{-x} \tag{1}$$

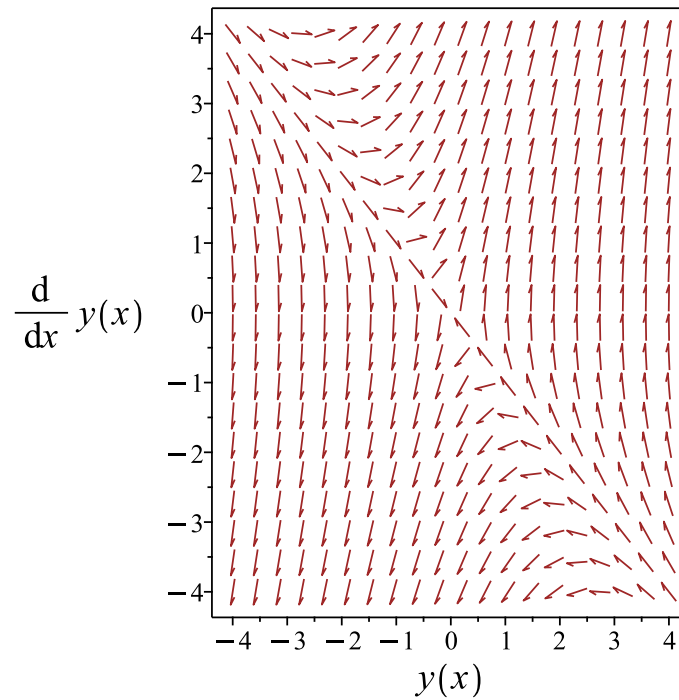


Figure 359: Slope field plot

Verification of solutions

$$y = c_1 e^{3x} + c_2 e^{-x}$$

Verified OK.

10.2.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' - 2y' - 3y = 0 \tag{1}$$

$$Ay'' + By' + Cy = 0 \tag{2}$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= -2 \\ C &= -3 \end{aligned} \tag{3}$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{4}{1} \tag{6}$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 4 \\ t &= 1 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = 4z(x) \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 281: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = 4$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = e^{-2x}$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-2}{1} dx} \\ &= z_1 e^x \\ &= z_1 (e^x) \end{aligned}$$

Which simplifies to

$$y_1 = e^{-x}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{-2}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{2x}}{(y_1)^2} dx \\ &= y_1 \left(\frac{e^{4x}}{4} \right) \end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1(e^{-x}) + c_2\left(e^{-x}\left(\frac{e^{4x}}{4}\right)\right)\end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 e^{-x} + \frac{e^{3x} c_2}{4} \quad (1)$$

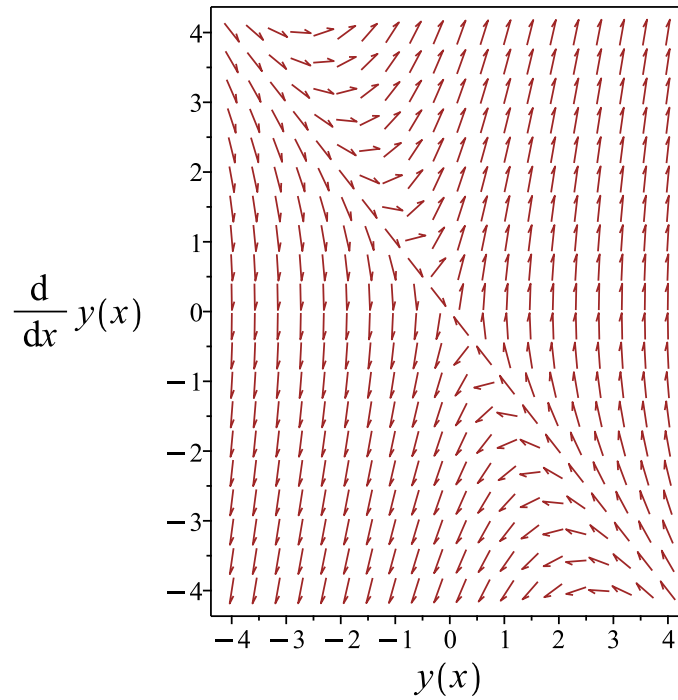


Figure 360: Slope field plot

Verification of solutions

$$y = c_1 e^{-x} + \frac{e^{3x} c_2}{4}$$

Verified OK.

10.2.3 Maple step by step solution

Let's solve

$$y'' - 2y' - 3y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of ODE

$$r^2 - 2r - 3 = 0$$

- Factor the characteristic polynomial

$$(r + 1)(r - 3) = 0$$

- Roots of the characteristic polynomial

$$r = (-1, 3)$$

- 1st solution of the ODE

$$y_1(x) = e^{-x}$$

- 2nd solution of the ODE

$$y_2(x) = e^{3x}$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x)$$

- Substitute in solutions

$$y = c_1 e^{-x} + e^{3x} c_2$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
<- constant coefficients successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 17

```
dsolve(diff(y(x),x$2)-2*diff(y(x),x)-3*y(x)=0,y(x), singsol=all)
```

$$y(x) = c_1 e^{-x} + c_2 e^{3x}$$

✓ Solution by Mathematica

Time used: 0.012 (sec). Leaf size: 22

```
DSolve[y''[x]-2*y'[x]-3*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^{-x}(c_2 e^{4x} + c_1)$$

10.3 problem 3

10.3.1 Solving as second order linear constant coeff ode	1912
10.3.2 Solving using Kovacic algorithm	1914
10.3.3 Maple step by step solution	1918

Internal problem ID [11733]

Internal file name [OUTPUT/11742_Thursday_April_11_2024_08_49_18_PM_66750643/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 3.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"kovacic", "second_order_linear_constant_coeff"**

Maple gives the following as the ode type

```
[[_2nd_order , _missing_x]]
```

$$4y'' - 12y' + 5y = 0$$

10.3.1 Solving as second order linear constant coeff ode

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 4, B = -12, C = 5$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$4\lambda^2 e^{\lambda x} - 12\lambda e^{\lambda x} + 5e^{\lambda x} = 0 \tag{1}$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$4\lambda^2 - 12\lambda + 5 = 0 \tag{2}$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 4, B = -12, C = 5$ into the above gives

$$\begin{aligned}\lambda_{1,2} &= \frac{12}{(2)(4)} \pm \frac{1}{(2)(4)} \sqrt{-12^2 - (4)(4)(5)} \\ &= \frac{3}{2} \pm 1\end{aligned}$$

Hence

$$\lambda_1 = \frac{3}{2} + 1$$

$$\lambda_2 = \frac{3}{2} - 1$$

Which simplifies to

$$\lambda_1 = \frac{5}{2}$$

$$\lambda_2 = \frac{1}{2}$$

Since roots are real and distinct, then the solution is

$$y = c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x}$$

$$y = c_1 e^{(\frac{5}{2})x} + c_2 e^{(\frac{1}{2})x}$$

Or

$$y = c_1 e^{\frac{5x}{2}} + e^{\frac{x}{2}} c_2$$

Summary

The solution(s) found are the following

$$y = c_1 e^{\frac{5x}{2}} + e^{\frac{x}{2}} c_2 \tag{1}$$

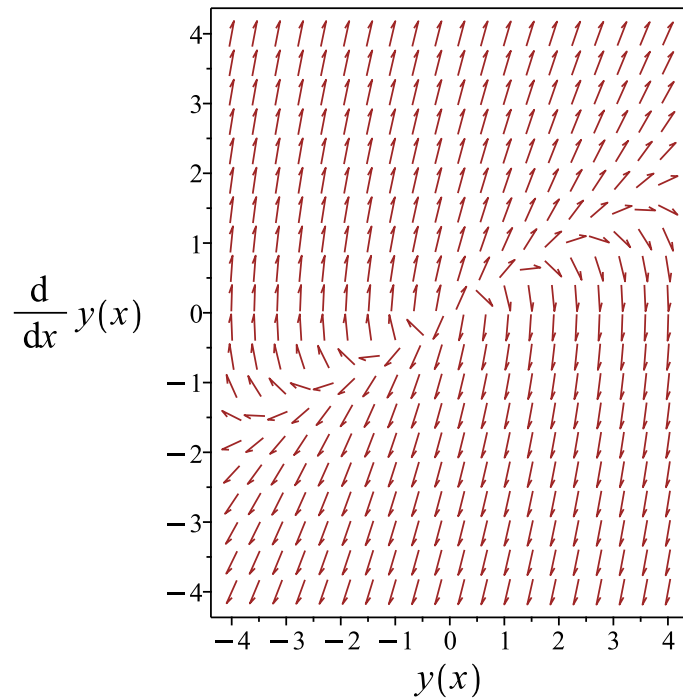


Figure 361: Slope field plot

Verification of solutions

$$y = c_1 e^{\frac{5x}{2}} + e^{\frac{x}{2}} c_2$$

Verified OK.

10.3.2 Solving using Kovacic algorithm

Writing the ode as

$$4y'' - 12y' + 5y = 0 \tag{1}$$

$$Ay'' + By' + Cy = 0 \tag{2}$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 4 \\ B &= -12 \\ C &= 5 \end{aligned} \tag{3}$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$r = \frac{s}{t} = \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{1}{1} \tag{6}$$

Comparing the above to (5) shows that

$$s = 1$$

$$t = 1$$

Therefore eq. (4) becomes

$$z''(x) = z(x) \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 283: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = 1$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = e^{-x}$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-12}{4} dx} \\ &= z_1 e^{\frac{3x}{2}} \\ &= z_1 \left(e^{\frac{3x}{2}} \right) \end{aligned}$$

Which simplifies to

$$y_1 = e^{\frac{3x}{2}}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{-12}{4} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{3x}}{(y_1)^2} dx \\ &= y_1 \left(\frac{e^{2x}}{2} \right) \end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1 \left(e^{\frac{x}{2}} \right) + c_2 \left(e^{\frac{x}{2}} \left(\frac{e^{2x}}{2} \right) \right)\end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 e^{\frac{x}{2}} + \frac{c_2 e^{\frac{5x}{2}}}{2} \quad (1)$$

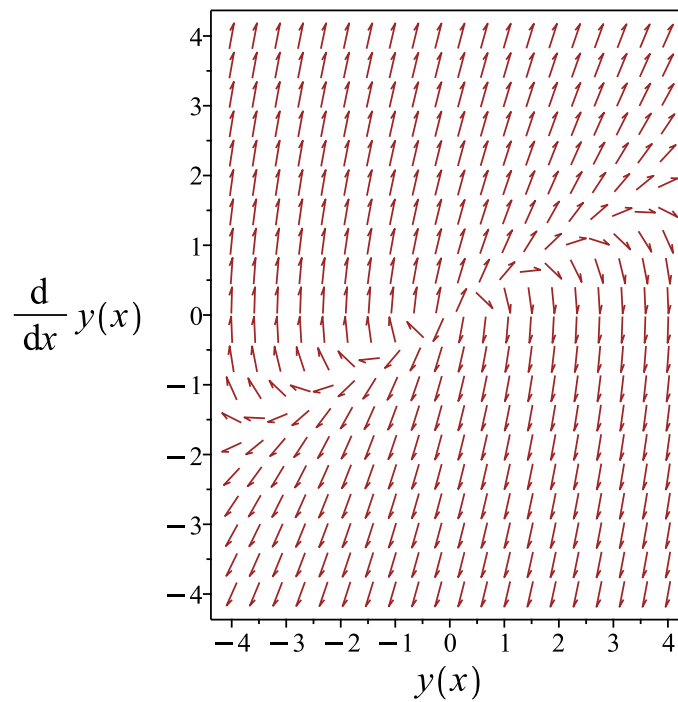


Figure 362: Slope field plot

Verification of solutions

$$y = c_1 e^{\frac{x}{2}} + \frac{c_2 e^{\frac{5x}{2}}}{2}$$

Verified OK.

10.3.3 Maple step by step solution

Let's solve

$$4y'' - 12y' + 5y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = 3y' - \frac{5y}{4}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' - 3y' + \frac{5y}{4} = 0$$

- Characteristic polynomial of ODE

$$r^2 - 3r + \frac{5}{4} = 0$$

- Factor the characteristic polynomial

$$\frac{(2r-1)(2r-5)}{4} = 0$$

- Roots of the characteristic polynomial

$$r = \left(\frac{1}{2}, \frac{5}{2}\right)$$

- 1st solution of the ODE

$$y_1(x) = e^{\frac{x}{2}}$$

- 2nd solution of the ODE

$$y_2(x) = e^{\frac{5x}{2}}$$

- General solution of the ODE

$$y = c_1y_1(x) + c_2y_2(x)$$

- Substitute in solutions

$$y = c_1e^{\frac{x}{2}} + c_2e^{\frac{5x}{2}}$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
<- constant coefficients successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 17

```
dsolve(4*diff(y(x),x$2)-12*diff(y(x),x)+5*y(x)=0,y(x), singsol=all)
```

$$y(x) = c_1 e^{\frac{x}{2}} + c_2 e^{\frac{5x}{2}}$$

✓ Solution by Mathematica

Time used: 0.013 (sec). Leaf size: 24

```
DSolve[4*y''[x]-12*y'[x]+5*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^{x/2}(c_2 e^{2x} + c_1)$$

10.4 problem 4

10.4.1 Solving as second order linear constant coeff ode	1920
10.4.2 Solving using Kovacic algorithm	1922
10.4.3 Maple step by step solution	1926

Internal problem ID [11734]

Internal file name [OUTPUT/11743_Thursday_April_11_2024_08_49_18_PM_78335090/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 4.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"kovacic", "second_order_linear_constant_coeff"**

Maple gives the following as the ode type

```
[[_2nd_order , _missing_x]]
```

$$3y'' - 14y' - 5y = 0$$

10.4.1 Solving as second order linear constant coeff ode

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 3, B = -14, C = -5$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$3\lambda^2 e^{\lambda x} - 14\lambda e^{\lambda x} - 5e^{\lambda x} = 0 \tag{1}$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$3\lambda^2 - 14\lambda - 5 = 0 \tag{2}$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 3, B = -14, C = -5$ into the above gives

$$\begin{aligned}\lambda_{1,2} &= \frac{14}{(2)(3)} \pm \frac{1}{(2)(3)} \sqrt{-14^2 - (4)(3)(-5)} \\ &= \frac{7}{3} \pm \frac{8}{3}\end{aligned}$$

Hence

$$\lambda_1 = \frac{7}{3} + \frac{8}{3}$$

$$\lambda_2 = \frac{7}{3} - \frac{8}{3}$$

Which simplifies to

$$\lambda_1 = 5$$

$$\lambda_2 = -\frac{1}{3}$$

Since roots are real and distinct, then the solution is

$$y = c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x}$$

$$y = c_1 e^{(5)x} + c_2 e^{(-\frac{1}{3})x}$$

Or

$$y = c_1 e^{5x} + c_2 e^{-\frac{x}{3}}$$

Summary

The solution(s) found are the following

$$y = c_1 e^{5x} + c_2 e^{-\frac{x}{3}} \quad (1)$$

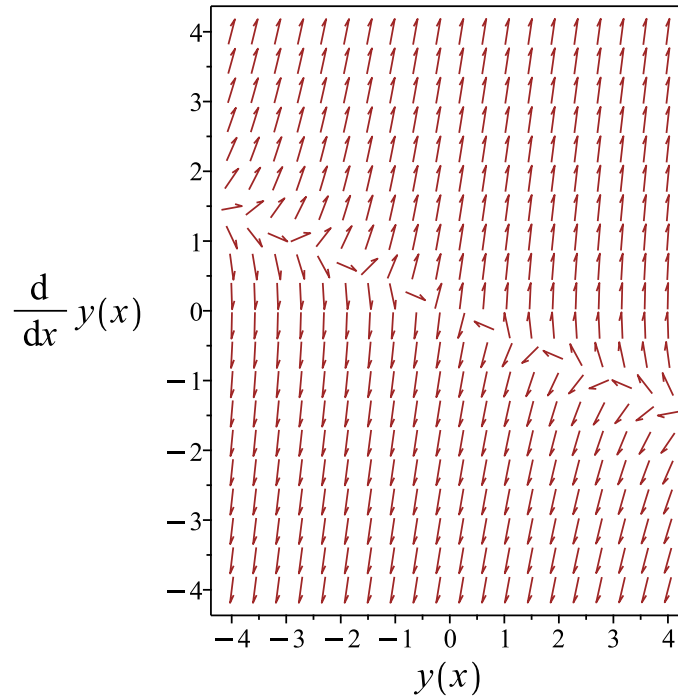


Figure 363: Slope field plot

Verification of solutions

$$y = c_1 e^{5x} + c_2 e^{-\frac{x}{3}}$$

Verified OK.

10.4.2 Solving using Kovacic algorithm

Writing the ode as

$$3y'' - 14y' - 5y = 0 \tag{1}$$

$$Ay'' + By' + Cy = 0 \tag{2}$$

Comparing (1) and (2) shows that

$$A = 3$$

$$B = -14 \tag{3}$$

$$C = -5$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{64}{9} \tag{6}$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 64 \\ t &= 9 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = \frac{64z(x)}{9} \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 285: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = \frac{64}{9}$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = e^{-\frac{8x}{3}}$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-14}{3} dx} \\ &= z_1 e^{\frac{7x}{3}} \\ &= z_1 \left(e^{\frac{7x}{3}} \right) \end{aligned}$$

Which simplifies to

$$y_1 = e^{-\frac{x}{3}}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{-14}{3} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{\frac{14x}{3}}}{(y_1)^2} dx \\ &= y_1 \left(\frac{3 e^{\frac{16x}{3}}}{16} \right) \end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1 \left(e^{-\frac{x}{3}} \right) + c_2 \left(e^{-\frac{x}{3}} \left(\frac{3 e^{\frac{16x}{3}}}{16} \right) \right)\end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 e^{-\frac{x}{3}} + \frac{3c_2 e^{5x}}{16} \quad (1)$$

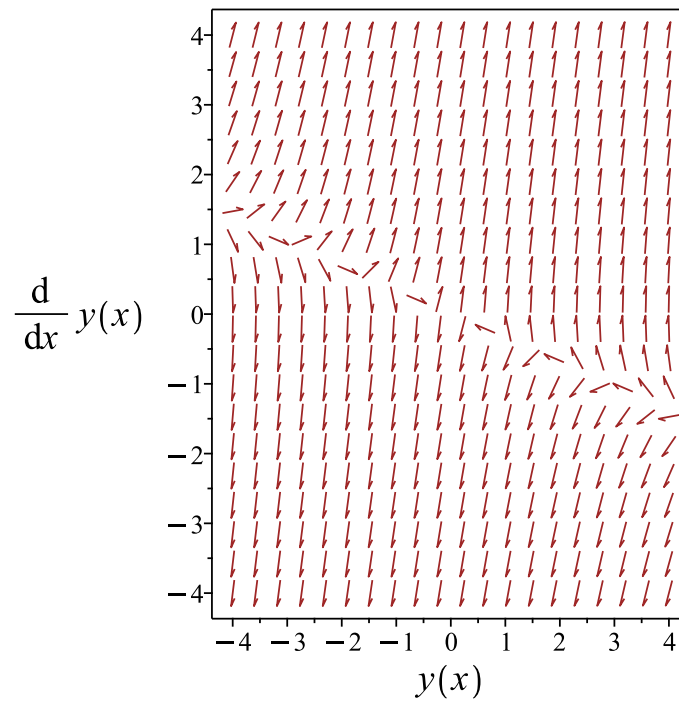


Figure 364: Slope field plot

Verification of solutions

$$y = c_1 e^{-\frac{x}{3}} + \frac{3c_2 e^{5x}}{16}$$

Verified OK.

10.4.3 Maple step by step solution

Let's solve

$$3y'' - 14y' - 5y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = \frac{14y'}{3} + \frac{5y}{3}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' - \frac{14y'}{3} - \frac{5y}{3} = 0$$

- Characteristic polynomial of ODE

$$r^2 - \frac{14}{3}r - \frac{5}{3} = 0$$

- Factor the characteristic polynomial

$$\frac{(3r+1)(r-5)}{3} = 0$$

- Roots of the characteristic polynomial

$$r = \left(5, -\frac{1}{3}\right)$$

- 1st solution of the ODE

$$y_1(x) = e^{5x}$$

- 2nd solution of the ODE

$$y_2(x) = e^{-\frac{x}{3}}$$

- General solution of the ODE

$$y = c_1y_1(x) + c_2y_2(x)$$

- Substitute in solutions

$$y = c_1e^{5x} + c_2e^{-\frac{x}{3}}$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
<- constant coefficients successful`
```

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 17

```
dsolve(3*diff(y(x),x$2)-14*diff(y(x),x)-5*y(x)=0,y(x), singsol=all)
```

$$y(x) = c_1 e^{5x} + c_2 e^{-\frac{x}{3}}$$

✓ Solution by Mathematica

Time used: 0.013 (sec). Leaf size: 24

```
DSolve[3*y''[x]-14*y'[x]-5*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow c_1 e^{-x/3} + c_2 e^{5x}$$

10.5 problem 5

10.5.1 Maple step by step solution 1929

Internal problem ID [11735]

Internal file name [OUTPUT/11744_Thursday_April_11_2024_08_49_19_PM_4021622/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 5.

ODE order: 3.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_3rd_order , _missing_x]]
```

$$y''' - 3y'' - y' + 3y = 0$$

The characteristic equation is

$$\lambda^3 - 3\lambda^2 - \lambda + 3 = 0$$

The roots of the above equation are

$$\lambda_1 = 1$$

$$\lambda_2 = 3$$

$$\lambda_3 = -1$$

Therefore the homogeneous solution is

$$y_h(x) = c_1e^{-x} + c_2e^x + c_3e^{3x}$$

The fundamental set of solutions for the homogeneous solution are the following

$$y_1 = e^{-x}$$

$$y_2 = e^x$$

$$y_3 = e^{3x}$$

Summary

The solution(s) found are the following

$$y = c_1e^{-x} + c_2e^x + c_3e^{3x} \quad (1)$$

Verification of solutions

$$y = c_1e^{-x} + c_2e^x + c_3e^{3x}$$

Verified OK.

10.5.1 Maple step by step solution

Let's solve

$$y''' - 3y'' - y' + 3y = 0$$

- Highest derivative means the order of the ODE is 3
- Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(x)$

$$y_1(x) = y$$

- Define new variable $y_2(x)$

$$y_2(x) = y'$$

- Define new variable $y_3(x)$

$$y_3(x) = y''$$

- Isolate for $y_3'(x)$ using original ODE

$$y_3'(x) = 3y_3(x) + y_2(x) - 3y_1(x)$$

Convert linear ODE into a system of first order ODEs

$$[y_2(x) = y_1'(x), y_3(x) = y_2'(x), y_3'(x) = 3y_3(x) + y_2(x) - 3y_1(x)]$$

- Define vector

$$\vec{y}(x) = \begin{bmatrix} y_1(x) \\ y_2(x) \\ y_3(x) \end{bmatrix}$$

- System to solve

$$\vec{y}'(x) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -3 & 1 & 3 \end{bmatrix} \cdot \vec{y}(x)$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -3 & 1 & 3 \end{bmatrix}$$

- Rewrite the system as

$$\vec{y}'(x) = A \cdot \vec{y}(x)$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[-1, \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \right], \left[1, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right], \left[3, \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[-1, \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_1 = e^{-x} \cdot \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[1, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_2 = e^x \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[3, \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_3 = e^{3x} \cdot \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix}$$

- General solution to the system of ODEs

$$\vec{y} = c_1 \vec{y}_1 + c_2 \vec{y}_2 + c_3 \vec{y}_3$$

- Substitute solutions into the general solution

$$\vec{y} = c_1 e^{-x} \cdot \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} + c_2 e^x \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + c_3 e^{3x} \cdot \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y = c_1 e^{-x} + c_2 e^x + \frac{c_3 e^{3x}}{9}$$

Maple trace

```

`Methods for third order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 21

```
dsolve(diff(y(x),x$3)-3*diff(y(x),x$2)-diff(y(x),x)+3*y(x)=0,y(x), singsol=all)
```

$$y(x) = c_1 e^{-x} + c_2 e^x + c_3 e^{3x}$$

✓ Solution by Mathematica

Time used: 0.003 (sec). Leaf size: 28

```
DSolve[y'''[x]-3*y''[x]-y'[x]+3*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow c_1 e^{-x} + c_2 e^x + c_3 e^{3x}$$

10.6 problem 6

10.6.1 Maple step by step solution 1934

Internal problem ID [11736]

Internal file name [OUTPUT/11745_Thursday_April_11_2024_08_49_19_PM_28454319/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 6.

ODE order: 3.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_3rd_order , _missing_x]]
```

$$y''' - 6y'' + 5y' + 12y = 0$$

The characteristic equation is

$$\lambda^3 - 6\lambda^2 + 5\lambda + 12 = 0$$

The roots of the above equation are

$$\lambda_1 = 3$$

$$\lambda_2 = 4$$

$$\lambda_3 = -1$$

Therefore the homogeneous solution is

$$y_h(x) = c_1 e^{-x} + e^{3x} c_2 + e^{4x} c_3$$

The fundamental set of solutions for the homogeneous solution are the following

$$y_1 = e^{-x}$$

$$y_2 = e^{3x}$$

$$y_3 = e^{4x}$$

Summary

The solution(s) found are the following

$$y = c_1 e^{-x} + e^{3x} c_2 + e^{4x} c_3 \quad (1)$$

Verification of solutions

$$y = c_1 e^{-x} + e^{3x} c_2 + e^{4x} c_3$$

Verified OK.

10.6.1 Maple step by step solution

Let's solve

$$y''' - 6y'' + 5y' + 12y = 0$$

- Highest derivative means the order of the ODE is 3

$$y'''$$

- Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(x)$

$$y_1(x) = y$$

- Define new variable $y_2(x)$

$$y_2(x) = y'$$

- Define new variable $y_3(x)$

$$y_3(x) = y''$$

- Isolate for $y_3'(x)$ using original ODE

$$y_3'(x) = 6y_3(x) - 5y_2(x) - 12y_1(x)$$

Convert linear ODE into a system of first order ODEs

$$[y_2(x) = y_1'(x), y_3(x) = y_2'(x), y_3'(x) = 6y_3(x) - 5y_2(x) - 12y_1(x)]$$

- Define vector

$$\vec{y}(x) = \begin{bmatrix} y_1(x) \\ y_2(x) \\ y_3(x) \end{bmatrix}$$

- System to solve

$$\vec{y}'(x) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -12 & -5 & 6 \end{bmatrix} \cdot \vec{y}(x)$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -12 & -5 & 6 \end{bmatrix}$$

- Rewrite the system as

$$\vec{y}'(x) = A \cdot \vec{y}(x)$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[-1, \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \right], \left[3, \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix} \right], \left[4, \begin{bmatrix} \frac{1}{16} \\ \frac{1}{4} \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[-1, \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_1 = e^{-x} \cdot \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[3, \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_2 = e^{3x} \cdot \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[4, \begin{bmatrix} \frac{1}{16} \\ \frac{1}{4} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_3 = e^{4x} \cdot \begin{bmatrix} \frac{1}{16} \\ \frac{1}{4} \\ 1 \end{bmatrix}$$

- General solution to the system of ODEs

$$\vec{y} = c_1 \vec{y}_1 + c_2 \vec{y}_2 + c_3 \vec{y}_3$$

- Substitute solutions into the general solution

$$\vec{y} = c_1 e^{-x} \cdot \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} + e^{3x} c_2 \cdot \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix} + e^{4x} c_3 \cdot \begin{bmatrix} \frac{1}{16} \\ \frac{1}{4} \\ 1 \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y = c_1 e^{-x} + \frac{e^{3x} c_2}{9} + \frac{e^{4x} c_3}{16}$$

Maple trace

```

`Methods for third order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 23

```
dsolve(diff(y(x),x$3)-6*diff(y(x),x$2)+5*diff(y(x),x)+12*y(x)=0,y(x), singsol=all)
```

$$y(x) = c_1 e^{4x} + c_2 e^{-x} + c_3 e^{3x}$$

✓ Solution by Mathematica

Time used: 0.003 (sec). Leaf size: 29

```
DSolve[y'''[x]-6*y''[x]+5*y'[x]+12*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^{-x} (e^{4x} (c_3 e^x + c_2) + c_1)$$

10.7 problem 7

10.7.1 Solving as second order linear constant coeff ode	1938
10.7.2 Solving as linear second order ode solved by an integrating factor ode	1940
10.7.3 Solving using Kovacic algorithm	1941
10.7.4 Maple step by step solution	1945

Internal problem ID [11737]

Internal file name [OUTPUT/11746_Thursday_April_11_2024_08_49_19_PM_20027788/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 7.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff", "linear_second_order_ode_solved_by_an_integrating_factor"

Maple gives the following as the ode type

```
[[_2nd_order , _missing_x]]
```

$$y'' - 8y' + 16y = 0$$

10.7.1 Solving as second order linear constant coeff ode

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = -8, C = 16$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} - 8\lambda e^{\lambda x} + 16 e^{\lambda x} = 0 \tag{1}$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 - 8\lambda + 16 = 0 \tag{2}$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = -8, C = 16$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{8}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{(-8)^2 - (4)(1)(16)} \\ &= 4 \end{aligned}$$

Hence this is the case of a double root $\lambda_{1,2} = -4$. Therefore the solution is

$$y = c_1 e^{4x} + c_2 x e^{4x} \tag{1}$$

Summary

The solution(s) found are the following

$$y = c_1 e^{4x} + c_2 x e^{4x} \tag{1}$$

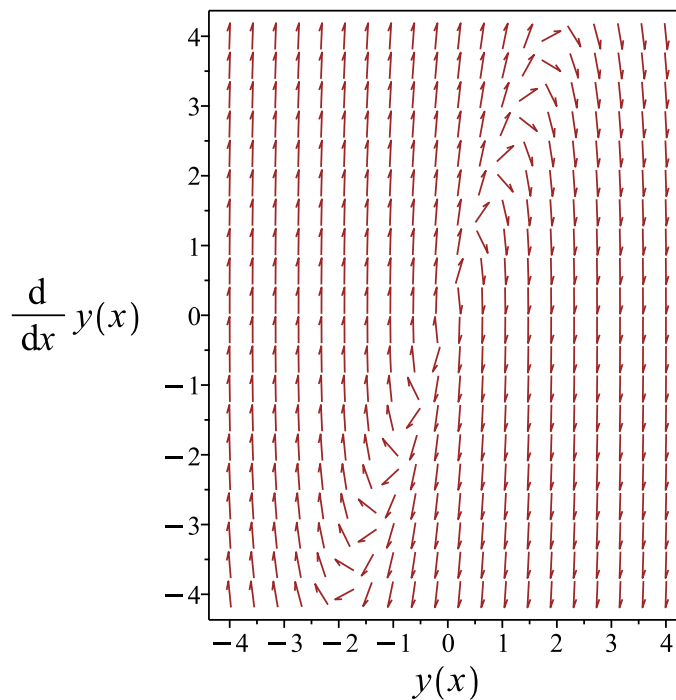


Figure 365: Slope field plot

Verification of solutions

$$y = c_1 e^{4x} + c_2 x e^{4x}$$

Verified OK.

10.7.2 Solving as linear second order ode solved by an integrating factor ode

The ode satisfies this form

$$y'' + p(x)y' + \frac{(p(x)^2 + p'(x))y}{2} = f(x)$$

Where $p(x) = -8$. Therefore, there is an integrating factor given by

$$\begin{aligned}M(x) &= e^{\frac{1}{2} \int p dx} \\ &= e^{\int -8 dx} \\ &= e^{-4x}\end{aligned}$$

Multiplying both sides of the ODE by the integrating factor $M(x)$ makes the left side of the ODE a complete differential

$$\begin{aligned}(M(x)y)'' &= 0 \\ (e^{-4x}y)'' &= 0\end{aligned}$$

Integrating once gives

$$(e^{-4x}y)' = c_1$$

Integrating again gives

$$(e^{-4x}y) = c_1x + c_2$$

Hence the solution is

$$y = \frac{c_1x + c_2}{e^{-4x}}$$

Or

$$y = c_1x e^{4x} + c_2e^{4x}$$

Summary

The solution(s) found are the following

$$y = c_1x e^{4x} + c_2e^{4x} \tag{1}$$

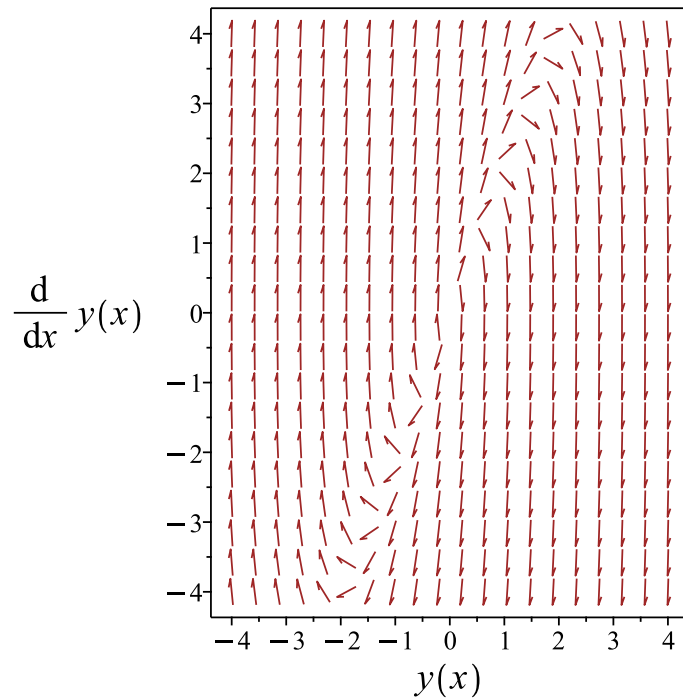


Figure 366: Slope field plot

Verification of solutions

$$y = c_1 x e^{4x} + c_2 e^{4x}$$

Verified OK.

10.7.3 Solving using Kovacic algorithm

Writing the ode as

$$y'' - 8y' + 16y = 0 \tag{1}$$

$$Ay'' + By' + Cy = 0 \tag{2}$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= -8 \\ C &= 16 \end{aligned} \tag{3}$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$r = \frac{s}{t} = \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{0}{1} \tag{6}$$

Comparing the above to (5) shows that

$$s = 0 \\ t = 1$$

Therefore eq. (4) becomes

$$z''(x) = 0 \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 289: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - -\infty \\ &= \infty \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is *infinity* then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = 0$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = 1$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-8}{1} dx} \\ &= z_1 e^{4x} \\ &= z_1 (e^{4x}) \end{aligned}$$

Which simplifies to

$$y_1 = e^{4x}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{-8}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{8x}}{(y_1)^2} dx \\ &= y_1(x) \end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (e^{4x}) + c_2 (e^{4x}(x))\end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 e^{4x} + c_2 x e^{4x} \quad (1)$$

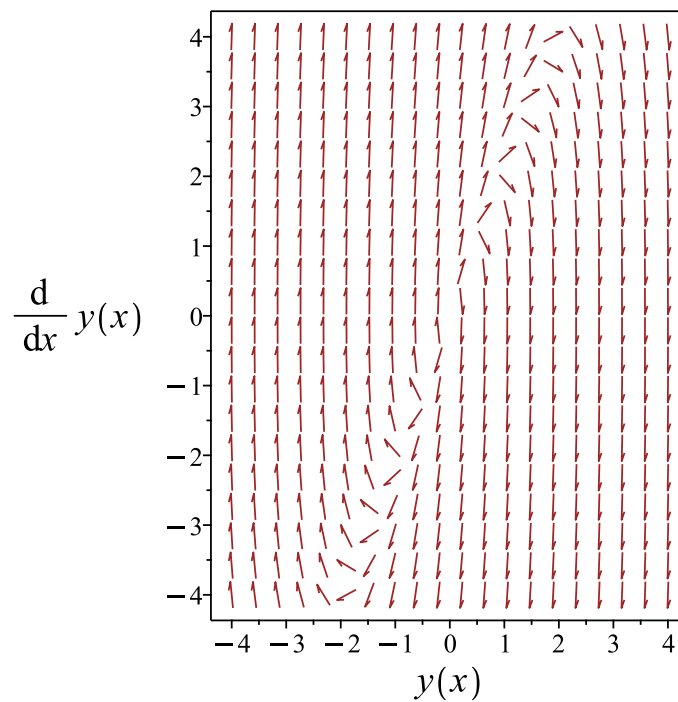


Figure 367: Slope field plot

Verification of solutions

$$y = c_1 e^{4x} + c_2 x e^{4x}$$

Verified OK.

10.7.4 Maple step by step solution

Let's solve

$$y'' - 8y' + 16y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of ODE

$$r^2 - 8r + 16 = 0$$

- Factor the characteristic polynomial

$$(r - 4)^2 = 0$$

- Root of the characteristic polynomial

$$r = 4$$

- 1st solution of the ODE

$$y_1(x) = e^{4x}$$

- Repeated root, multiply $y_1(x)$ by x to ensure linear independence

$$y_2(x) = x e^{4x}$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x)$$

- Substitute in solutions

$$y = c_1 e^{4x} + c_2 x e^{4x}$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
<- constant coefficients successful`
```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 14

```
dsolve(diff(y(x),x$2)-8*diff(y(x),x)+16*y(x)=0,y(x), singsol=all)
```

$$y(x) = e^{4x}(c_2x + c_1)$$

✓ Solution by Mathematica

Time used: 0.013 (sec). Leaf size: 18

```
DSolve[y''[x]-8*y'[x]+16*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^{4x}(c_2x + c_1)$$

10.8 problem 8

10.8.1 Solving as second order linear constant coeff ode	1947
10.8.2 Solving as linear second order ode solved by an integrating factor ode	1949
10.8.3 Solving using Kovacic algorithm	1950
10.8.4 Maple step by step solution	1954

Internal problem ID [11738]

Internal file name [OUTPUT/11747_Thursday_April_11_2024_08_49_20_PM_5835726/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 8.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff", "linear_second_order_ode_solved_by_an_integrating_factor"

Maple gives the following as the ode type

```
[[_2nd_order , _missing_x]]
```

$$4y'' + 4y' + y = 0$$

10.8.1 Solving as second order linear constant coeff ode

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 4, B = 4, C = 1$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$4\lambda^2 e^{\lambda x} + 4\lambda e^{\lambda x} + e^{\lambda x} = 0 \tag{1}$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$4\lambda^2 + 4\lambda + 1 = 0 \tag{2}$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 4, B = 4, C = 1$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{-4}{(2)(4)} \pm \frac{1}{(2)(4)} \sqrt{(4)^2 - (4)(4)(1)} \\ &= -\frac{1}{2} \end{aligned}$$

Hence this is the case of a double root $\lambda_{1,2} = \frac{1}{2}$. Therefore the solution is

$$y = c_1 e^{-\frac{x}{2}} + c_2 x e^{-\frac{x}{2}} \quad (1)$$

Summary

The solution(s) found are the following

$$y = c_1 e^{-\frac{x}{2}} + c_2 x e^{-\frac{x}{2}} \quad (1)$$

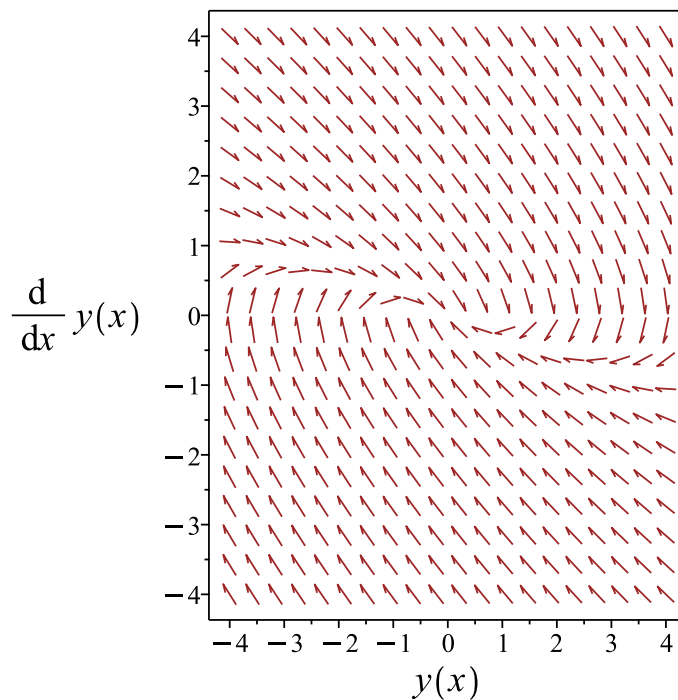


Figure 368: Slope field plot

Verification of solutions

$$y = c_1 e^{-\frac{x}{2}} + c_2 x e^{-\frac{x}{2}}$$

Verified OK.

10.8.2 Solving as linear second order ode solved by an integrating factor ode

The ode satisfies this form

$$y'' + p(x)y' + \frac{(p(x)^2 + p'(x))y}{2} = f(x)$$

Where $p(x) = 1$. Therefore, there is an integrating factor given by

$$\begin{aligned}M(x) &= e^{\frac{1}{2} \int p dx} \\ &= e^{\int 1 dx} \\ &= e^{\frac{x}{2}}\end{aligned}$$

Multiplying both sides of the ODE by the integrating factor $M(x)$ makes the left side of the ODE a complete differential

$$\begin{aligned}(M(x)y)'' &= 0 \\ (e^{\frac{x}{2}}y)'' &= 0\end{aligned}$$

Integrating once gives

$$(e^{\frac{x}{2}}y)' = c_1$$

Integrating again gives

$$(e^{\frac{x}{2}}y) = c_1x + c_2$$

Hence the solution is

$$y = \frac{c_1x + c_2}{e^{\frac{x}{2}}}$$

Or

$$y = c_1x e^{-\frac{x}{2}} + c_2e^{-\frac{x}{2}}$$

Summary

The solution(s) found are the following

$$y = c_1x e^{-\frac{x}{2}} + c_2e^{-\frac{x}{2}} \quad (1)$$

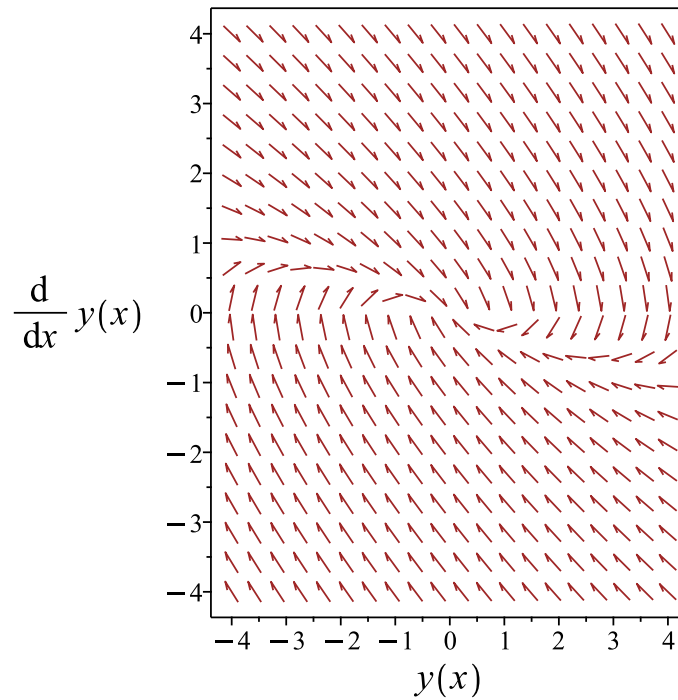


Figure 369: Slope field plot

Verification of solutions

$$y = c_1 x e^{-\frac{x}{2}} + c_2 e^{-\frac{x}{2}}$$

Verified OK.

10.8.3 Solving using Kovacic algorithm

Writing the ode as

$$4y'' + 4y' + y = 0 \tag{1}$$

$$Ay'' + By' + Cy = 0 \tag{2}$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 4 \\ B &= 4 \\ C &= 1 \end{aligned} \tag{3}$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$r = \frac{s}{t} = \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{0}{1} \tag{6}$$

Comparing the above to (5) shows that

$$s = 0 \\ t = 1$$

Therefore eq. (4) becomes

$$z''(x) = 0 \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 291: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - -\infty \\ &= \infty \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is *infinity* then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = 0$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = 1$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{4}{4} dx} \\ &= z_1 e^{-\frac{x}{2}} \\ &= z_1 (e^{-\frac{x}{2}}) \end{aligned}$$

Which simplifies to

$$y_1 = e^{-\frac{x}{2}}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{4}{4} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{-x}}{(y_1)^2} dx \\ &= y_1(x) \end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (e^{-\frac{x}{2}}) + c_2 (e^{-\frac{x}{2}}(x))\end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 e^{-\frac{x}{2}} + c_2 x e^{-\frac{x}{2}} \quad (1)$$

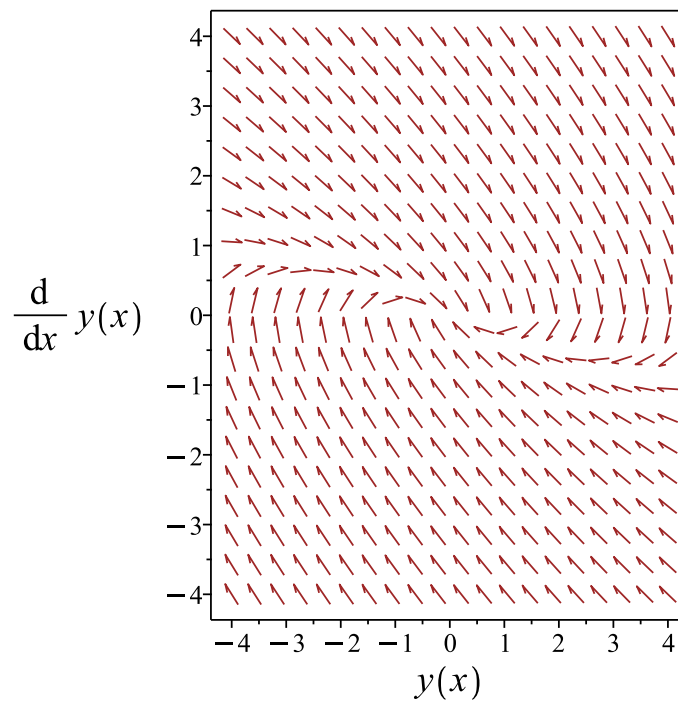


Figure 370: Slope field plot

Verification of solutions

$$y = c_1 e^{-\frac{x}{2}} + c_2 x e^{-\frac{x}{2}}$$

Verified OK.

10.8.4 Maple step by step solution

Let's solve

$$4y'' + 4y' + y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = -y' - \frac{y}{4}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + y' + \frac{y}{4} = 0$$

- Characteristic polynomial of ODE

$$r^2 + r + \frac{1}{4} = 0$$

- Factor the characteristic polynomial

$$\frac{(2r+1)^2}{4} = 0$$

- Root of the characteristic polynomial

$$r = -\frac{1}{2}$$

- 1st solution of the ODE

$$y_1(x) = e^{-\frac{x}{2}}$$

- Repeated root, multiply $y_1(x)$ by x to ensure linear independence

$$y_2(x) = x e^{-\frac{x}{2}}$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x)$$

- Substitute in solutions

$$y = c_1 e^{-\frac{x}{2}} + c_2 x e^{-\frac{x}{2}}$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
<- constant coefficients successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 14

```
dsolve(4*diff(y(x),x$2)+4*diff(y(x),x)+y(x)=0,y(x), singsol=all)
```

$$y(x) = e^{-\frac{x}{2}}(c_2x + c_1)$$

✓ Solution by Mathematica

Time used: 0.015 (sec). Leaf size: 20

```
DSolve[4*y''[x]+4*y'[x]+y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^{-x/2}(c_2x + c_1)$$

10.9 problem 9

10.9.1 Solving as second order linear constant coeff ode	1956
10.9.2 Solving using Kovacic algorithm	1958
10.9.3 Maple step by step solution	1962

Internal problem ID [11739]

Internal file name [OUTPUT/11748_Thursday_April_11_2024_08_49_20_PM_31209479/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 9.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"kovacic", "second_order_linear_constant_coeff"**

Maple gives the following as the ode type

```
[[_2nd_order , _missing_x]]
```

$$y'' - 4y' + 13y = 0$$

10.9.1 Solving as second order linear constant coeff ode

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = -4, C = 13$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} - 4\lambda e^{\lambda x} + 13e^{\lambda x} = 0 \tag{1}$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 - 4\lambda + 13 = 0 \tag{2}$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = -4, C = 13$ into the above gives

$$\begin{aligned}\lambda_{1,2} &= \frac{4}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{-4^2 - (4)(1)(13)} \\ &= 2 \pm 3i\end{aligned}$$

Hence

$$\lambda_1 = 2 + 3i$$

$$\lambda_2 = 2 - 3i$$

Which simplifies to

$$\lambda_1 = 2 + 3i$$

$$\lambda_2 = 2 - 3i$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = 2$ and $\beta = 3$. Therefore the final solution, when using Euler relation, can be written as

$$y = e^{\alpha x}(c_1 \cos(\beta x) + c_2 \sin(\beta x))$$

Which becomes

$$y = e^{2x}(c_1 \cos(3x) + c_2 \sin(3x))$$

Summary

The solution(s) found are the following

$$y = e^{2x}(c_1 \cos(3x) + c_2 \sin(3x)) \quad (1)$$

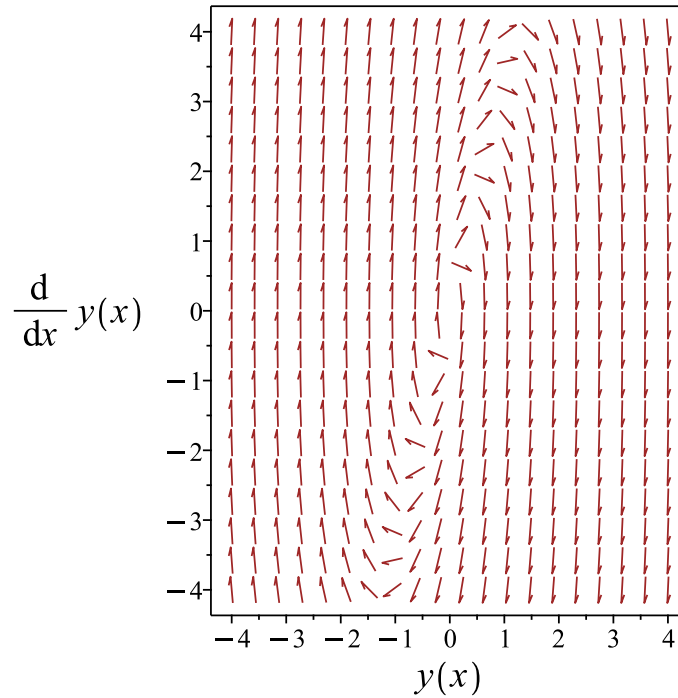


Figure 371: Slope field plot

Verification of solutions

$$y = e^{2x}(c_1 \cos(3x) + c_2 \sin(3x))$$

Verified OK.

10.9.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' - 4y' + 13y = 0 \tag{1}$$

$$Ay'' + By' + Cy = 0 \tag{2}$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= -4 \\ C &= 13 \end{aligned} \tag{3}$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$r = \frac{s}{t} = \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-9}{1} \tag{6}$$

Comparing the above to (5) shows that

$$s = -9$$

$$t = 1$$

Therefore eq. (4) becomes

$$z''(x) = -9z(x) \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 293: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned}O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0\end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = -9$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = \cos(3x)$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned}y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-4}{1} dx} \\ &= z_1 e^{2x} \\ &= z_1 (e^{2x})\end{aligned}$$

Which simplifies to

$$y_1 = e^{2x} \cos(3x)$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{-4}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{4x}}{(y_1)^2} dx \\ &= y_1 \left(\frac{\tan(3x)}{3} \right)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (e^{2x} \cos(3x)) + c_2 \left(e^{2x} \cos(3x) \left(\frac{\tan(3x)}{3} \right) \right)\end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 e^{2x} \cos(3x) + \frac{c_2 e^{2x} \sin(3x)}{3} \quad (1)$$

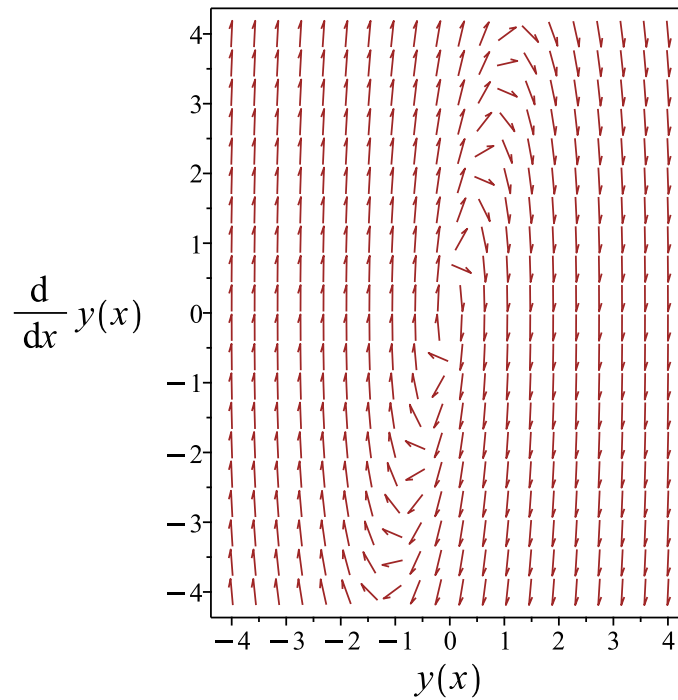


Figure 372: Slope field plot

Verification of solutions

$$y = c_1 e^{2x} \cos(3x) + \frac{c_2 e^{2x} \sin(3x)}{3}$$

Verified OK.

10.9.3 Maple step by step solution

Let's solve

$$y'' - 4y' + 13y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of ODE

$$r^2 - 4r + 13 = 0$$

- Use quadratic formula to solve for r

$$r = \frac{4 \pm (\sqrt{-36})}{2}$$

- Roots of the characteristic polynomial

$$r = (2 - 3i, 2 + 3i)$$

- 1st solution of the ODE

$$y_1(x) = e^{2x} \cos(3x)$$

- 2nd solution of the ODE

$$y_2(x) = e^{2x} \sin(3x)$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x)$$

- Substitute in solutions

$$y = c_1 e^{2x} \cos(3x) + c_2 e^{2x} \sin(3x)$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
<- constant coefficients successful`
```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 22

```
dsolve(diff(y(x),x$2)-4*diff(y(x),x)+13*y(x)=0,y(x), singsol=all)
```

$$y(x) = e^{2x}(c_1 \sin(3x) + c_2 \cos(3x))$$

✓ Solution by Mathematica

Time used: 0.018 (sec). Leaf size: 26

```
DSolve[y''[x]-4*y'[x]+13*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^{2x}(c_2 \cos(3x) + c_1 \sin(3x))$$

10.10 problem 10

10.10.1 Solving as second order linear constant coeff ode	1964
10.10.2 Solving using Kovacic algorithm	1966
10.10.3 Maple step by step solution	1970

Internal problem ID [11740]

Internal file name [OUTPUT/11749_Thursday_April_11_2024_08_49_21_PM_75173537/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 10.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"kovacic", "second_order_linear_constant_coeff"**

Maple gives the following as the ode type

```
[[_2nd_order , _missing_x]]
```

$$y'' + 6y' + 25y = 0$$

10.10.1 Solving as second order linear constant coeff ode

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 6, C = 25$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + 6\lambda e^{\lambda x} + 25 e^{\lambda x} = 0 \tag{1}$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 6\lambda + 25 = 0 \tag{2}$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 6, C = 25$ into the above gives

$$\begin{aligned}\lambda_{1,2} &= \frac{-6}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{6^2 - (4)(1)(25)} \\ &= -3 \pm 4i\end{aligned}$$

Hence

$$\begin{aligned}\lambda_1 &= -3 + 4i \\ \lambda_2 &= -3 - 4i\end{aligned}$$

Which simplifies to

$$\begin{aligned}\lambda_1 &= -3 + 4i \\ \lambda_2 &= -3 - 4i\end{aligned}$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = -3$ and $\beta = 4$. Therefore the final solution, when using Euler relation, can be written as

$$y = e^{\alpha x}(c_1 \cos(\beta x) + c_2 \sin(\beta x))$$

Which becomes

$$y = e^{-3x}(c_1 \cos(4x) + c_2 \sin(4x))$$

Summary

The solution(s) found are the following

$$y = e^{-3x}(c_1 \cos(4x) + c_2 \sin(4x)) \quad (1)$$

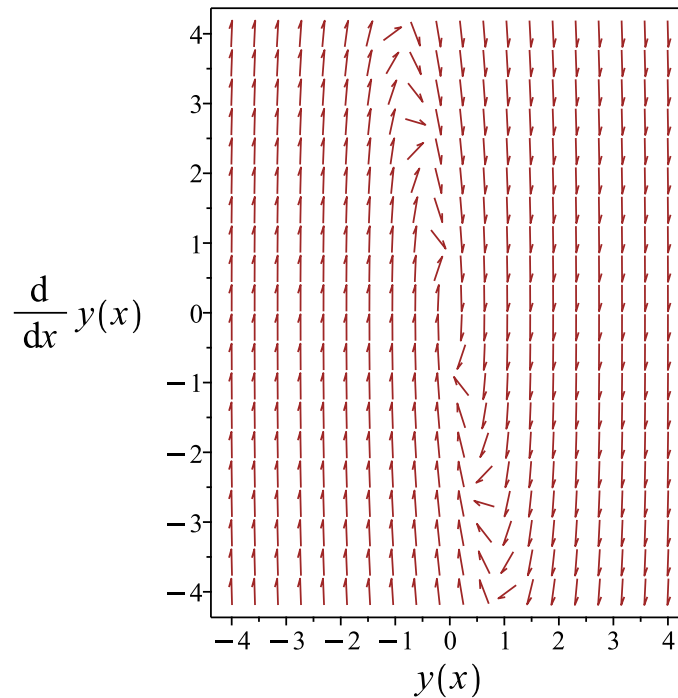


Figure 373: Slope field plot

Verification of solutions

$$y = e^{-3x}(c_1 \cos(4x) + c_2 \sin(4x))$$

Verified OK.

10.10.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' + 6y' + 25y = 0 \tag{1}$$

$$Ay'' + By' + Cy = 0 \tag{2}$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= 6 \\ C &= 25 \end{aligned} \tag{3}$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$r = \frac{s}{t} = \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-16}{1} \tag{6}$$

Comparing the above to (5) shows that

$$s = -16$$

$$t = 1$$

Therefore eq. (4) becomes

$$z''(x) = -16z(x) \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 295: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned}O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0\end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = -16$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = \cos(4x)$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned}y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{6}{1} dx} \\ &= z_1 e^{-3x} \\ &= z_1 (e^{-3x})\end{aligned}$$

Which simplifies to

$$y_1 = e^{-3x} \cos(4x)$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{6}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{-6x}}{(y_1)^2} dx \\ &= y_1 \left(\frac{\tan(4x)}{4} \right)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (e^{-3x} \cos(4x)) + c_2 \left(e^{-3x} \cos(4x) \left(\frac{\tan(4x)}{4} \right) \right)\end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 e^{-3x} \cos(4x) + \frac{c_2 e^{-3x} \sin(4x)}{4} \quad (1)$$

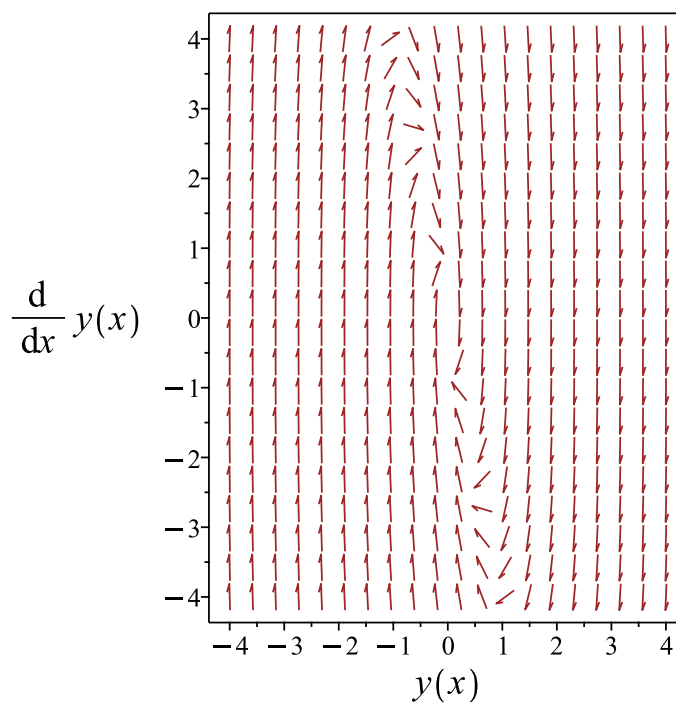


Figure 374: Slope field plot

Verification of solutions

$$y = c_1 e^{-3x} \cos(4x) + \frac{c_2 e^{-3x} \sin(4x)}{4}$$

Verified OK.

10.10.3 Maple step by step solution

Let's solve

$$y'' + 6y' + 25y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of ODE

$$r^2 + 6r + 25 = 0$$

- Use quadratic formula to solve for r

$$r = \frac{(-6) \pm (\sqrt{-64})}{2}$$

- Roots of the characteristic polynomial

$$r = (-3 - 4I, -3 + 4I)$$

- 1st solution of the ODE

$$y_1(x) = e^{-3x} \cos(4x)$$

- 2nd solution of the ODE

$$y_2(x) = e^{-3x} \sin(4x)$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x)$$

- Substitute in solutions

$$y = c_1 e^{-3x} \cos(4x) + c_2 e^{-3x} \sin(4x)$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
<- constant coefficients successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 22

```
dsolve(diff(y(x),x$2)+6*diff(y(x),x)+25*y(x)=0,y(x), singsol=all)
```

$$y(x) = e^{-3x}(c_1 \sin(4x) + c_2 \cos(4x))$$

✓ Solution by Mathematica

Time used: 0.019 (sec). Leaf size: 26

```
DSolve[y''[x]+6*y'[x]+25*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^{-3x}(c_2 \cos(4x) + c_1 \sin(4x))$$

10.11 problem 11

10.11.1 Solving as second order linear constant coeff ode	1972
10.11.2 Solving as second order ode can be made integrable ode	1974
10.11.3 Solving using Kovacic algorithm	1976
10.11.4 Maple step by step solution	1980

Internal problem ID [11741]

Internal file name [OUTPUT/11750_Thursday_April_11_2024_08_49_21_PM_92995520/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 11.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff", "second_order_ode_can_be_made_integrable"

Maple gives the following as the ode type

```
[[_2nd_order, _missing_x]]
```

$$y'' + 9y = 0$$

10.11.1 Solving as second order linear constant coeff ode

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 0, C = 9$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + 9 e^{\lambda x} = 0 \tag{1}$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 9 = 0 \tag{2}$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 0, C = 9$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{0}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{0^2 - (4)(1)(9)} \\ &= \pm 3i \end{aligned}$$

Hence

$$\begin{aligned} \lambda_1 &= +3i \\ \lambda_2 &= -3i \end{aligned}$$

Which simplifies to

$$\begin{aligned} \lambda_1 &= 3i \\ \lambda_2 &= -3i \end{aligned}$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = 0$ and $\beta = 3$. Therefore the final solution, when using Euler relation, can be written as

$$y = e^{\alpha x} (c_1 \cos(\beta x) + c_2 \sin(\beta x))$$

Which becomes

$$y = e^0 (c_1 \cos(3x) + c_2 \sin(3x))$$

Or

$$y = c_1 \cos(3x) + c_2 \sin(3x)$$

Summary

The solution(s) found are the following

$$y = c_1 \cos(3x) + c_2 \sin(3x) \tag{1}$$

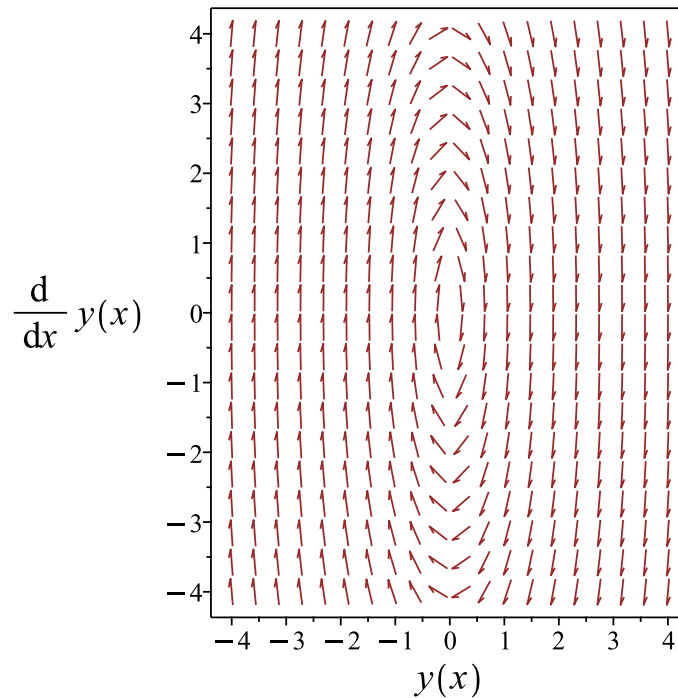


Figure 375: Slope field plot

Verification of solutions

$$y = c_1 \cos(3x) + c_2 \sin(3x)$$

Verified OK.

10.11.2 Solving as second order ode can be made integrable ode

Multiplying the ode by y' gives

$$y'y'' + 9yy' = 0$$

Integrating the above w.r.t x gives

$$\int (y'y'' + 9yy') dx = 0$$

$$\frac{y'^2}{2} + \frac{9y^2}{2} = c_2$$

Which is now solved for y . Solving the given ode for y' results in 2 differential equations to solve. Each one of these will generate a solution. The equations generated are

$$y' = \sqrt{-9y^2 + 2c_1} \tag{1}$$

$$y' = -\sqrt{-9y^2 + 2c_1} \tag{2}$$

Now each one of the above ODE is solved.

Solving equation (1)

Integrating both sides gives

$$\int \frac{1}{\sqrt{-9y^2 + 2c_1}} dy = \int dx$$
$$\frac{\arctan\left(\frac{3y}{\sqrt{-9y^2 + 2c_1}}\right)}{3} = x + c_2$$

Solving equation (2)

Integrating both sides gives

$$\int -\frac{1}{\sqrt{-9y^2 + 2c_1}} dy = \int dx$$
$$-\frac{\arctan\left(\frac{3y}{\sqrt{-9y^2 + 2c_1}}\right)}{3} = c_3 + x$$

Summary

The solution(s) found are the following

$$\frac{\arctan\left(\frac{3y}{\sqrt{-9y^2 + 2c_1}}\right)}{3} = x + c_2 \quad (1)$$

$$-\frac{\arctan\left(\frac{3y}{\sqrt{-9y^2 + 2c_1}}\right)}{3} = c_3 + x \quad (2)$$

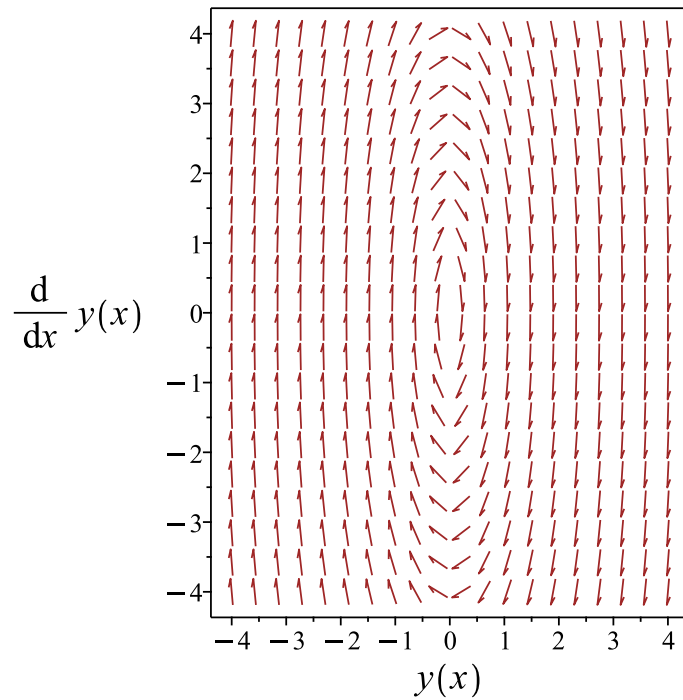


Figure 376: Slope field plot

Verification of solutions

$$\frac{\arctan\left(\frac{3y}{\sqrt{-9y^2+2c_1}}\right)}{3} = x + c_2$$

Verified OK.

$$-\frac{\arctan\left(\frac{3y}{\sqrt{-9y^2+2c_1}}\right)}{3} = c_3 + x$$

Verified OK.

10.11.3 Solving using Kovacic algorithm

Writing the ode as

$$y'' + 9y = 0 \tag{1}$$

$$Ay'' + By' + Cy = 0 \tag{2}$$

Comparing (1) and (2) shows that

$$\begin{aligned}A &= 1 \\B &= 0 \\C &= 9\end{aligned}\tag{3}$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x)\tag{4}$$

Where r is given by

$$\begin{aligned}r &= \frac{s}{t} \\&= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2}\end{aligned}\tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-9}{1}\tag{6}$$

Comparing the above to (5) shows that

$$\begin{aligned}s &= -9 \\t &= 1\end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = -9z(x)\tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 297: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = -9$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = \cos(3x)$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$y_1 = z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx}$$

Since $B = 0$ then the above reduces to

$$\begin{aligned} y_1 &= z_1 \\ &= \cos(3x) \end{aligned}$$

Which simplifies to

$$y_1 = \cos(3x)$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Since $B = 0$ then the above becomes

$$\begin{aligned} y_2 &= y_1 \int \frac{1}{y_1^2} dx \\ &= \cos(3x) \int \frac{1}{\cos(3x)^2} dx \\ &= \cos(3x) \left(\frac{\tan(3x)}{3} \right) \end{aligned}$$

Therefore the solution is

$$\begin{aligned} y &= c_1 y_1 + c_2 y_2 \\ &= c_1(\cos(3x)) + c_2 \left(\cos(3x) \left(\frac{\tan(3x)}{3} \right) \right) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 \cos(3x) + \frac{c_2 \sin(3x)}{3} \tag{1}$$

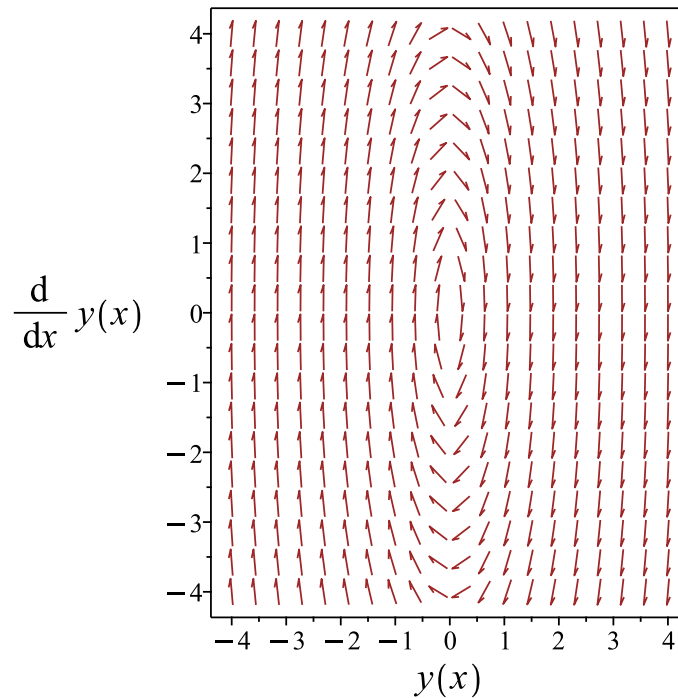


Figure 377: Slope field plot

Verification of solutions

$$y = c_1 \cos(3x) + \frac{c_2 \sin(3x)}{3}$$

Verified OK.

10.11.4 Maple step by step solution

Let's solve

$$y'' + 9y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of ODE

$$r^2 + 9 = 0$$

- Use quadratic formula to solve for r

$$r = \frac{0 \pm (\sqrt{-36})}{2}$$

- Roots of the characteristic polynomial

$$r = (-3I, 3I)$$

- 1st solution of the ODE
 $y_1(x) = \cos(3x)$
- 2nd solution of the ODE
 $y_2(x) = \sin(3x)$
- General solution of the ODE
 $y = c_1 y_1(x) + c_2 y_2(x)$
- Substitute in solutions
 $y = c_1 \cos(3x) + c_2 \sin(3x)$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
<- constant coefficients successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 17

```
dsolve(diff(y(x),x$2)+9*y(x)=0,y(x), singsol=all)
```

$$y(x) = c_1 \sin(3x) + c_2 \cos(3x)$$

✓ Solution by Mathematica

Time used: 0.012 (sec). Leaf size: 20

```
DSolve[y''[x]+9*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow c_1 \cos(3x) + c_2 \sin(3x)$$

10.12 problem 12

10.12.1 Solving as second order linear constant coeff ode	1982
10.12.2 Solving as second order ode can be made integrable ode	1984
10.12.3 Solving using Kovacic algorithm	1986
10.12.4 Maple step by step solution	1990

Internal problem ID [11742]

Internal file name [OUTPUT/11751_Thursday_April_11_2024_08_49_22_PM_63064774/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 12.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff", "second_order_ode_can_be_made_integrable"

Maple gives the following as the ode type

```
[[_2nd_order, _missing_x]]
```

$$4y'' + y = 0$$

10.12.1 Solving as second order linear constant coeff ode

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 4, B = 0, C = 1$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$4\lambda^2 e^{\lambda x} + e^{\lambda x} = 0 \tag{1}$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$4\lambda^2 + 1 = 0 \tag{2}$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 4, B = 0, C = 1$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{0}{(2)(4)} \pm \frac{1}{(2)(4)} \sqrt{0^2 - (4)(4)(1)} \\ &= \pm \frac{i}{2} \end{aligned}$$

Hence

$$\begin{aligned} \lambda_1 &= +\frac{i}{2} \\ \lambda_2 &= -\frac{i}{2} \end{aligned}$$

Which simplifies to

$$\begin{aligned} \lambda_1 &= \frac{i}{2} \\ \lambda_2 &= -\frac{i}{2} \end{aligned}$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = 0$ and $\beta = \frac{1}{2}$. Therefore the final solution, when using Euler relation, can be written as

$$y = e^{\alpha x} (c_1 \cos(\beta x) + c_2 \sin(\beta x))$$

Which becomes

$$y = e^0 \left(c_1 \cos \left(\frac{x}{2} \right) + c_2 \sin \left(\frac{x}{2} \right) \right)$$

Or

$$y = c_1 \cos \left(\frac{x}{2} \right) + c_2 \sin \left(\frac{x}{2} \right)$$

Summary

The solution(s) found are the following

$$y = c_1 \cos \left(\frac{x}{2} \right) + c_2 \sin \left(\frac{x}{2} \right) \quad (1)$$

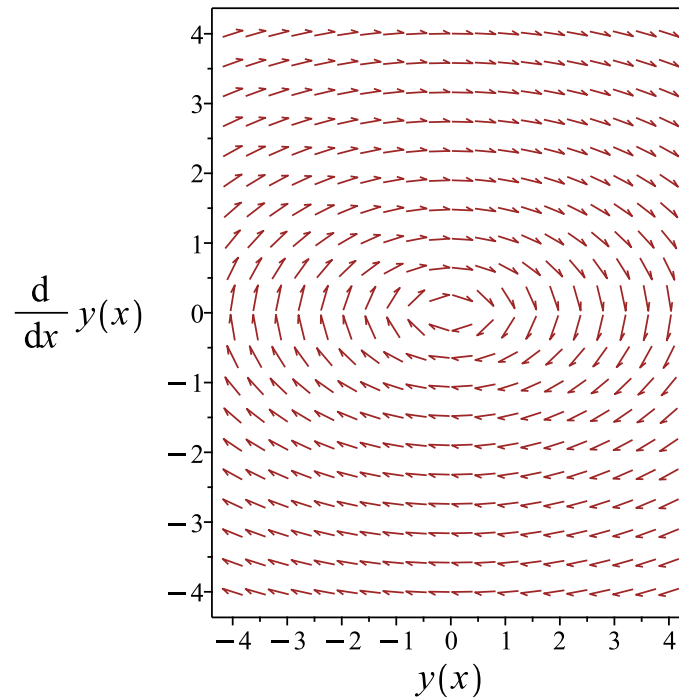


Figure 378: Slope field plot

Verification of solutions

$$y = c_1 \cos\left(\frac{x}{2}\right) + c_2 \sin\left(\frac{x}{2}\right)$$

Verified OK.

10.12.2 Solving as second order ode can be made integrable ode

Multiplying the ode by y' gives

$$4y'y'' + yy' = 0$$

Integrating the above w.r.t x gives

$$\int (4y'y'' + yy') dx = 0$$

$$\frac{y^2}{2} + 2y'^2 = c_2$$

Which is now solved for y . Solving the given ode for y' results in 2 differential equations to solve. Each one of these will generate a solution. The equations generated are

$$y' = \frac{\sqrt{-y^2 + 2c_1}}{2} \quad (1)$$

$$y' = -\frac{\sqrt{-y^2 + 2c_1}}{2} \quad (2)$$

Now each one of the above ODE is solved.

Solving equation (1)

Integrating both sides gives

$$\int \frac{2}{\sqrt{-y^2 + 2c_1}} dy = \int dx$$
$$2 \arctan \left(\frac{y}{\sqrt{-y^2 + 2c_1}} \right) = x + c_2$$

Solving equation (2)

Integrating both sides gives

$$\int -\frac{2}{\sqrt{-y^2 + 2c_1}} dy = \int dx$$
$$-2 \arctan \left(\frac{y}{\sqrt{-y^2 + 2c_1}} \right) = c_3 + x$$

Summary

The solution(s) found are the following

$$2 \arctan \left(\frac{y}{\sqrt{-y^2 + 2c_1}} \right) = x + c_2 \quad (1)$$

$$-2 \arctan \left(\frac{y}{\sqrt{-y^2 + 2c_1}} \right) = c_3 + x \quad (2)$$

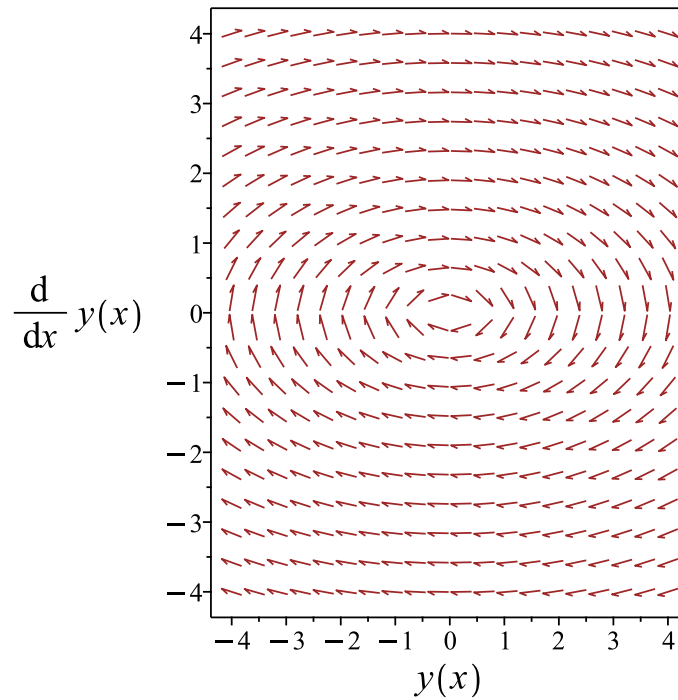


Figure 379: Slope field plot

Verification of solutions

$$2 \arctan \left(\frac{y}{\sqrt{-y^2 + 2c_1}} \right) = x + c_2$$

Verified OK.

$$-2 \arctan \left(\frac{y}{\sqrt{-y^2 + 2c_1}} \right) = c_3 + x$$

Verified OK.

10.12.3 Solving using Kovacic algorithm

Writing the ode as

$$4y'' + y = 0 \tag{1}$$

$$Ay'' + By' + Cy = 0 \tag{2}$$

Comparing (1) and (2) shows that

$$\begin{aligned}A &= 4 \\B &= 0 \\C &= 1\end{aligned}\tag{3}$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x)\tag{4}$$

Where r is given by

$$\begin{aligned}r &= \frac{s}{t} \\&= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2}\end{aligned}\tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-1}{4}\tag{6}$$

Comparing the above to (5) shows that

$$\begin{aligned}s &= -1 \\t &= 4\end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = -\frac{z(x)}{4}\tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 299: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned}
 \mathcal{O}(\infty) &= \deg(t) - \deg(s) \\
 &= 0 - 0 \\
 &= 0
 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = -\frac{1}{4}$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = \cos\left(\frac{x}{2}\right)$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$y_1 = z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx}$$

Since $B = 0$ then the above reduces to

$$\begin{aligned}
 y_1 &= z_1 \\
 &= \cos\left(\frac{x}{2}\right)
 \end{aligned}$$

Which simplifies to

$$y_1 = \cos\left(\frac{x}{2}\right)$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Since $B = 0$ then the above becomes

$$\begin{aligned} y_2 &= y_1 \int \frac{1}{y_1^2} dx \\ &= \cos\left(\frac{x}{2}\right) \int \frac{1}{\cos^2\left(\frac{x}{2}\right)} dx \\ &= \cos\left(\frac{x}{2}\right) \left(2 \tan\left(\frac{x}{2}\right)\right) \end{aligned}$$

Therefore the solution is

$$\begin{aligned} y &= c_1 y_1 + c_2 y_2 \\ &= c_1 \left(\cos\left(\frac{x}{2}\right)\right) + c_2 \left(\cos\left(\frac{x}{2}\right) \left(2 \tan\left(\frac{x}{2}\right)\right)\right) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 \cos\left(\frac{x}{2}\right) + 2c_2 \sin\left(\frac{x}{2}\right) \tag{1}$$

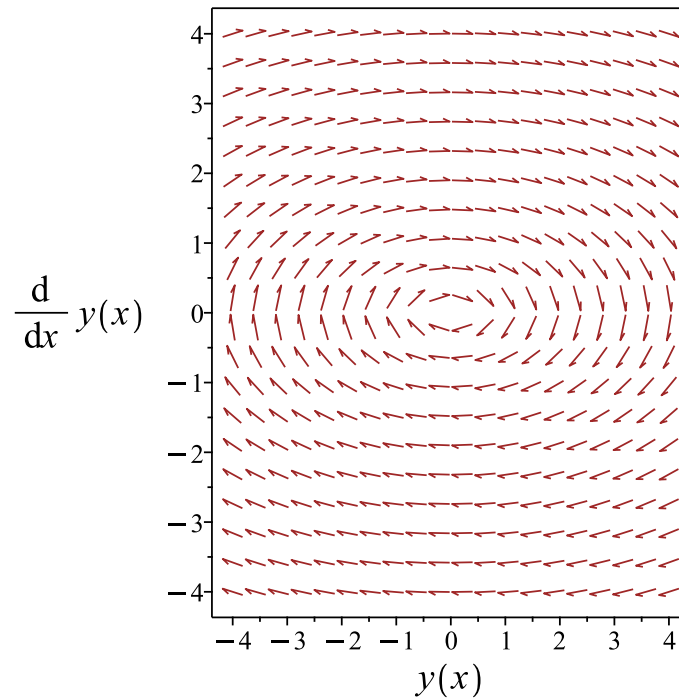


Figure 380: Slope field plot

Verification of solutions

$$y = c_1 \cos\left(\frac{x}{2}\right) + 2c_2 \sin\left(\frac{x}{2}\right)$$

Verified OK.

10.12.4 Maple step by step solution

Let's solve

$$4y'' + y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = -\frac{y}{4}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + \frac{y}{4} = 0$$

- Characteristic polynomial of ODE

$$r^2 + \frac{1}{4} = 0$$

- Use quadratic formula to solve for r

$$r = \frac{0 \pm (\sqrt{-1})}{2}$$

- Roots of the characteristic polynomial

$$r = \left(-\frac{i}{2}, \frac{i}{2}\right)$$

- 1st solution of the ODE

$$y_1(x) = \cos\left(\frac{x}{2}\right)$$

- 2nd solution of the ODE

$$y_2(x) = \sin\left(\frac{x}{2}\right)$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x)$$

- Substitute in solutions

$$y = c_1 \cos\left(\frac{x}{2}\right) + c_2 \sin\left(\frac{x}{2}\right)$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
<- constant coefficients successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 17

```
dsolve(4*diff(y(x),x$2)+y(x)=0,y(x), singsol=all)
```

$$y(x) = c_1 \sin\left(\frac{x}{2}\right) + c_2 \cos\left(\frac{x}{2}\right)$$

✓ Solution by Mathematica

Time used: 0.013 (sec). Leaf size: 24

```
DSolve[4*y''[x]+y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow c_1 \cos\left(\frac{x}{2}\right) + c_2 \sin\left(\frac{x}{2}\right)$$

10.13 problem 13

10.13.1 Maple step by step solution 1994

Internal problem ID [11743]

Internal file name [OUTPUT/11752_Thursday_April_11_2024_08_49_22_PM_74938499/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 13.

ODE order: 3.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_3rd_order , _missing_x]]
```

$$y''' - 5y'' + 7y' - 3y = 0$$

The characteristic equation is

$$\lambda^3 - 5\lambda^2 + 7\lambda - 3 = 0$$

The roots of the above equation are

$$\lambda_1 = 3$$

$$\lambda_2 = 1$$

$$\lambda_3 = 1$$

Therefore the homogeneous solution is

$$y_h(x) = e^x c_1 + c_2 x e^x + c_3 e^{3x}$$

The fundamental set of solutions for the homogeneous solution are the following

$$y_1 = e^x$$

$$y_2 = x e^x$$

$$y_3 = e^{3x}$$

Summary

The solution(s) found are the following

$$y = e^x c_1 + c_2 x e^x + c_3 e^{3x} \quad (1)$$

Verification of solutions

$$y = e^x c_1 + c_2 x e^x + c_3 e^{3x}$$

Verified OK.

10.13.1 Maple step by step solution

Let's solve

$$y''' - 5y'' + 7y' - 3y = 0$$

- Highest derivative means the order of the ODE is 3

$$y'''$$

- Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(x)$

$$y_1(x) = y$$

- Define new variable $y_2(x)$

$$y_2(x) = y'$$

- Define new variable $y_3(x)$

$$y_3(x) = y''$$

- Isolate for $y_3'(x)$ using original ODE

$$y_3'(x) = 5y_3(x) - 7y_2(x) + 3y_1(x)$$

Convert linear ODE into a system of first order ODEs

$$[y_2(x) = y_1'(x), y_3(x) = y_2'(x), y_3'(x) = 5y_3(x) - 7y_2(x) + 3y_1(x)]$$

- Define vector

$$\vec{y}(x) = \begin{bmatrix} y_1(x) \\ y_2(x) \\ y_3(x) \end{bmatrix}$$

- System to solve

$$\vec{y}'(x) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 3 & -7 & 5 \end{bmatrix} \cdot \vec{y}(x)$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 3 & -7 & 5 \end{bmatrix}$$

- Rewrite the system as

$$\vec{y}'(x) = A \cdot \vec{y}(x)$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[1, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right], \left[1, \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \right], \left[3, \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair, with eigenvalue of algebraic multiplicity 2

$$\left[1, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right]$$

- First solution from eigenvalue 1

$$\vec{y}_1(x) = e^x \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

- Form of the 2nd homogeneous solution where \vec{p} is to be solved for, $\lambda = 1$ is the eigenvalue, and

$$\vec{y}_2(x) = e^{\lambda x} (x\vec{v} + \vec{p})$$

- Note that the x multiplying \vec{v} makes this solution linearly independent to the 1st solution obtained

- Substitute $\vec{y}_2(x)$ into the homogeneous system

$$\lambda e^{\lambda x} (x\vec{v} + \vec{p}) + e^{\lambda x} \vec{v} = (e^{\lambda x} A) \cdot (x\vec{v} + \vec{p})$$

- Use the fact that \vec{v} is an eigenvector of A

$$\lambda e^{\lambda x} (x\vec{v} + \vec{p}) + e^{\lambda x} \vec{v} = e^{\lambda x} (\lambda x\vec{v} + A \cdot \vec{p})$$

- Simplify equation

$$\lambda \vec{p} + \vec{v} = A \cdot \vec{p}$$

- Make use of the identity matrix I

$$(\lambda \cdot I) \cdot \vec{p} + \vec{v} = A \cdot \vec{p}$$

- Condition \vec{p} must meet for $\vec{y}_2(x)$ to be a solution to the homogeneous system

$$(A - \lambda \cdot I) \cdot \vec{p} = \vec{v}$$

- Choose \vec{p} to use in the second solution to the homogeneous system from eigenvalue 1

$$\left(\begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 3 & -7 & 5 \end{bmatrix} - 1 \cdot \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \cdot \vec{p} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

- Choice of \vec{p}

$$\vec{p} = \begin{bmatrix} -1 \\ 0 \\ 0 \end{bmatrix}$$

- Second solution from eigenvalue 1

$$\vec{y}_2(x) = e^x \cdot \left(x \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + \begin{bmatrix} -1 \\ 0 \\ 0 \end{bmatrix} \right)$$

- Consider eigenpair

$$\left[3, \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_3 = e^{3x} \cdot \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix}$$

- General solution to the system of ODEs

$$\vec{y} = c_1 \vec{y}_1(x) + c_2 \vec{y}_2(x) + c_3 \vec{y}_3$$

- Substitute solutions into the general solution

$$\vec{y} = e^x c_1 \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + c_2 e^x \cdot \left(x \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + \begin{bmatrix} -1 \\ 0 \\ 0 \end{bmatrix} \right) + c_3 e^{3x} \cdot \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y = \frac{c_3 e^{3x}}{9} + e^x (c_2 (x - 1) + c_1)$$

Maple trace

```
`Methods for third order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
<- constant coefficients successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 19

```
dsolve(diff(y(x),x$3)-5*diff(y(x),x$2)+7*diff(y(x),x)-3*y(x)=0,y(x), singsol=all)
```

$$y(x) = c_1 e^{3x} + e^x (c_3 x + c_2)$$

✓ Solution by Mathematica

Time used: 0.003 (sec). Leaf size: 24

```
DSolve[y'''[x]-5*y''[x]+7*y'[x]-3*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^x (c_2 x + c_3 e^{2x} + c_1)$$

10.14 problem 14

10.14.1 Maple step by step solution 1999

Internal problem ID [11744]

Internal file name [OUTPUT/11753_Thursday_April_11_2024_08_49_23_PM_82557195/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 14.

ODE order: 3.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_3rd_order , _missing_x]]
```

$$4y''' + 4y'' - 7y' + 2y = 0$$

The characteristic equation is

$$4\lambda^3 + 4\lambda^2 - 7\lambda + 2 = 0$$

The roots of the above equation are

$$\lambda_1 = -2$$

$$\lambda_2 = \frac{1}{2}$$

$$\lambda_3 = \frac{1}{2}$$

Therefore the homogeneous solution is

$$y_h(x) = c_1 e^{-2x} + e^{\frac{x}{2}} c_2 + x e^{\frac{x}{2}} c_3$$

The fundamental set of solutions for the homogeneous solution are the following

$$y_1 = e^{-2x}$$

$$y_2 = e^{\frac{x}{2}}$$

$$y_3 = e^{\frac{x}{2}} x$$

Summary

The solution(s) found are the following

$$y = c_1 e^{-2x} + e^{\frac{x}{2}} c_2 + x e^{\frac{x}{2}} c_3 \quad (1)$$

Verification of solutions

$$y = c_1 e^{-2x} + e^{\frac{x}{2}} c_2 + x e^{\frac{x}{2}} c_3$$

Verified OK.

10.14.1 Maple step by step solution

Let's solve

$$4y''' + 4y'' - 7y' + 2y = 0$$

- Highest derivative means the order of the ODE is 3

$$y'''$$

- Isolate 3rd derivative

$$y''' = -y'' + \frac{7y'}{4} - \frac{y}{2}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y''' + y'' - \frac{7y'}{4} + \frac{y}{2} = 0$$

- Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(x)$

$$y_1(x) = y$$

- Define new variable $y_2(x)$

$$y_2(x) = y'$$

- Define new variable $y_3(x)$

$$y_3(x) = y''$$

- Isolate for $y_3'(x)$ using original ODE

$$y_3'(x) = -y_3(x) + \frac{7y_2(x)}{4} - \frac{y_1(x)}{2}$$

Convert linear ODE into a system of first order ODEs

$$\left[y_2(x) = y_1'(x), y_3(x) = y_2'(x), y_3'(x) = -y_3(x) + \frac{7y_2(x)}{4} - \frac{y_1(x)}{2} \right]$$

- Define vector

$$\vec{y}(x) = \begin{bmatrix} y_1(x) \\ y_2(x) \\ y_3(x) \end{bmatrix}$$

- System to solve

$$\vec{y}'(x) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -\frac{1}{2} & \frac{7}{4} & -1 \end{bmatrix} \cdot \vec{y}(x)$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -\frac{1}{2} & \frac{7}{4} & -1 \end{bmatrix}$$

- Rewrite the system as

$$\vec{y}'(x) = A \cdot \vec{y}(x)$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[\left[-2, \begin{bmatrix} \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix} \right], \left[\frac{1}{2}, \begin{bmatrix} 4 \\ 2 \\ 1 \end{bmatrix} \right], \left[\frac{1}{2}, \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \right] \right] \right]$$

- Consider eigenpair

$$\left[\left[-2, \begin{bmatrix} \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix} \right] \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_1 = e^{-2x} \cdot \begin{bmatrix} \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix}$$

- Consider eigenpair, with eigenvalue of algebraic multiplicity 2

$$\left[\frac{1}{2}, \begin{bmatrix} 4 \\ 2 \\ 1 \end{bmatrix} \right]$$

- First solution from eigenvalue $\frac{1}{2}$

$$\vec{y}_2(x) = e^{\frac{x}{2}} \cdot \begin{bmatrix} 4 \\ 2 \\ 1 \end{bmatrix}$$

- Form of the 2nd homogeneous solution where \vec{p} is to be solved for, $\lambda = \frac{1}{2}$ is the eigenvalue, and

$$\vec{y}_3(x) = e^{\lambda x} (x\vec{v} + \vec{p})$$

- Note that the x multiplying \vec{v} makes this solution linearly independent to the 1st solution obtained
- Substitute $\vec{y}_3(x)$ into the homogeneous system

$$\lambda e^{\lambda x} (x\vec{v} + \vec{p}) + e^{\lambda x} \vec{v} = (e^{\lambda x} A) \cdot (x\vec{v} + \vec{p})$$

- Use the fact that \vec{v} is an eigenvector of A

$$\lambda e^{\lambda x} (x\vec{v} + \vec{p}) + e^{\lambda x} \vec{v} = e^{\lambda x} (\lambda x\vec{v} + A \cdot \vec{p})$$

- Simplify equation

$$\lambda \vec{p} + \vec{v} = A \cdot \vec{p}$$

- Make use of the identity matrix I

$$(\lambda \cdot I) \cdot \vec{p} + \vec{v} = A \cdot \vec{p}$$

- Condition \vec{p} must meet for $\vec{y}_3(x)$ to be a solution to the homogeneous system

$$(A - \lambda \cdot I) \cdot \vec{p} = \vec{v}$$

- Choose \vec{p} to use in the second solution to the homogeneous system from eigenvalue $\frac{1}{2}$

$$\left(\begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -\frac{1}{2} & \frac{7}{4} & -1 \end{bmatrix} - \frac{1}{2} \cdot \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \cdot \vec{p} = \begin{bmatrix} 4 \\ 2 \\ 1 \end{bmatrix}$$

- Choice of \vec{p}

$$\vec{p} = \begin{bmatrix} -8 \\ 0 \\ 0 \end{bmatrix}$$

- Second solution from eigenvalue $\frac{1}{2}$

$$\vec{y}_3(x) = e^{\frac{x}{2}} \cdot \left(x \cdot \begin{bmatrix} 4 \\ 2 \\ 1 \end{bmatrix} + \begin{bmatrix} -8 \\ 0 \\ 0 \end{bmatrix} \right)$$

- General solution to the system of ODEs

$$\vec{y} = c_1 \vec{y}_1 + c_2 \vec{y}_2(x) + c_3 \vec{y}_3(x)$$

- Substitute solutions into the general solution

$$\vec{y} = c_1 e^{-2x} \cdot \begin{bmatrix} \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix} + e^{\frac{x}{2}} c_2 \cdot \begin{bmatrix} 4 \\ 2 \\ 1 \end{bmatrix} + c_3 e^{\frac{x}{2}} \cdot \left(x \cdot \begin{bmatrix} 4 \\ 2 \\ 1 \end{bmatrix} + \begin{bmatrix} -8 \\ 0 \\ 0 \end{bmatrix} \right)$$

- First component of the vector is the solution to the ODE

$$y = 4 e^{-2x} \left((x - 2) c_3 + c_2 \right) e^{\frac{5x}{2}} + \frac{c_1}{16}$$

Maple trace

```

`Methods for third order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 21

```
dsolve(4*diff(y(x),x$3)+4*diff(y(x),x$2)-7*diff(y(x),x)+2*y(x)=0,y(x), singsol=all)
```

$$y(x) = \left((c_3 x + c_2) e^{\frac{5x}{2}} + c_1 \right) e^{-2x}$$

✓ Solution by Mathematica

Time used: 0.003 (sec). Leaf size: 93

```
DSolve[4*y'''[x]+4*y''[x]+7*y'[x]+2*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$\begin{aligned}y(x) \rightarrow & c_1 \exp(x\text{Root}[4\#1^3 + 4\#1^2 + 7\#1 + 2\&, 1]) \\ & + c_2 \exp(x\text{Root}[4\#1^3 + 4\#1^2 + 7\#1 + 2\&, 2]) \\ & + c_3 \exp(x\text{Root}[4\#1^3 + 4\#1^2 + 7\#1 + 2\&, 3])\end{aligned}$$

10.15 problem 15

Internal problem ID [11745]

Internal file name [OUTPUT/11754_Thursday_April_11_2024_08_49_23_PM_77245304/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 15.

ODE order: 3.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_3rd_order , _missing_x]]
```

$$y''' - 6y'' + 12y' - 8y = 0$$

The characteristic equation is

$$\lambda^3 - 6\lambda^2 + 12\lambda - 8 = 0$$

The roots of the above equation are

$$\lambda_1 = 2$$

$$\lambda_2 = 2$$

$$\lambda_3 = 2$$

Therefore the homogeneous solution is

$$y_h(x) = c_1 e^{2x} + c_2 e^{2x} x + x^2 e^{2x} c_3$$

The fundamental set of solutions for the homogeneous solution are the following

$$y_1 = e^{2x}$$

$$y_2 = e^{2x} x$$

$$y_3 = x^2 e^{2x}$$

Summary

The solution(s) found are the following

$$y = c_1 e^{2x} + c_2 e^{2x} x + x^2 e^{2x} c_3 \quad (1)$$

Verification of solutions

$$y = c_1 e^{2x} + c_2 e^{2x} x + x^2 e^{2x} c_3$$

Verified OK.

Maple trace

```
`Methods for third order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
<- constant coefficients successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 19

```
dsolve(diff(y(x),x$3)-6*diff(y(x),x$2)+12*diff(y(x),x)-8*y(x)=0,y(x), singsol=all)
```

$$y(x) = e^{2x}(c_3 x^2 + c_2 x + c_1)$$

✓ Solution by Mathematica

Time used: 0.003 (sec). Leaf size: 23

```
DSolve[y'''[x]-6*y''[x]+12*y'[x]-8*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^{2x}(x(c_3 x + c_2) + c_1)$$

10.16 problem 16

10.16.1 Maple step by step solution 2007

Internal problem ID [11746]

Internal file name [OUTPUT/11755_Thursday_April_11_2024_08_49_24_PM_2170690/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 16.

ODE order: 3.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_3rd_order , _missing_x]]
```

$$y''' + 4y'' + 5y' + 6y = 0$$

The characteristic equation is

$$\lambda^3 + 4\lambda^2 + 5\lambda + 6 = 0$$

The roots of the above equation are

$$\lambda_1 = -3$$

$$\lambda_2 = -\frac{1}{2} - \frac{i\sqrt{7}}{2}$$

$$\lambda_3 = -\frac{1}{2} + \frac{i\sqrt{7}}{2}$$

Therefore the homogeneous solution is

$$y_h(x) = c_1 e^{-3x} + e^{\left(-\frac{1}{2} - \frac{i\sqrt{7}}{2}\right)x} c_2 + e^{\left(-\frac{1}{2} + \frac{i\sqrt{7}}{2}\right)x} c_3$$

The fundamental set of solutions for the homogeneous solution are the following

$$y_1 = e^{-3x}$$

$$y_2 = e^{\left(-\frac{1}{2} - \frac{i\sqrt{7}}{2}\right)x}$$

$$y_3 = e^{\left(-\frac{1}{2} + \frac{i\sqrt{7}}{2}\right)x}$$

Summary

The solution(s) found are the following

$$y = c_1 e^{-3x} + e^{\left(-\frac{1}{2} - \frac{i\sqrt{7}}{2}\right)x} c_2 + e^{\left(-\frac{1}{2} + \frac{i\sqrt{7}}{2}\right)x} c_3 \quad (1)$$

Verification of solutions

$$y = c_1 e^{-3x} + e^{\left(-\frac{1}{2} - \frac{i\sqrt{7}}{2}\right)x} c_2 + e^{\left(-\frac{1}{2} + \frac{i\sqrt{7}}{2}\right)x} c_3$$

Verified OK.

10.16.1 Maple step by step solution

Let's solve

$$y''' + 4y'' + 5y' + 6y = 0$$

- Highest derivative means the order of the ODE is 3

$$y'''$$

- Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(x)$

$$y_1(x) = y$$

- Define new variable $y_2(x)$

$$y_2(x) = y'$$

- Define new variable $y_3(x)$

$$y_3(x) = y''$$

- Isolate for $y_3'(x)$ using original ODE

$$y_3'(x) = -4y_3(x) - 5y_2(x) - 6y_1(x)$$

Convert linear ODE into a system of first order ODEs

$$[y_2(x) = y_1'(x), y_3(x) = y_2'(x), y_3'(x) = -4y_3(x) - 5y_2(x) - 6y_1(x)]$$

- Define vector

$$\vec{y}(x) = \begin{bmatrix} y_1(x) \\ y_2(x) \\ y_3(x) \end{bmatrix}$$

- System to solve

$$\vec{y}'(x) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -6 & -5 & -4 \end{bmatrix} \cdot \vec{y}(x)$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -6 & -5 & -4 \end{bmatrix}$$

- Rewrite the system as

$$\vec{y}'(x) = A \cdot \vec{y}(x)$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[-3, \begin{bmatrix} \frac{1}{9} \\ -\frac{1}{3} \\ 1 \end{bmatrix} \right], \left[-\frac{1}{2} - \frac{i\sqrt{7}}{2}, \begin{bmatrix} \frac{1}{\left(-\frac{1}{2} - \frac{i\sqrt{7}}{2}\right)^2} \\ \frac{1}{-\frac{1}{2} - \frac{i\sqrt{7}}{2}} \\ 1 \end{bmatrix} \right], \left[-\frac{1}{2} + \frac{i\sqrt{7}}{2}, \begin{bmatrix} \frac{1}{\left(-\frac{1}{2} + \frac{i\sqrt{7}}{2}\right)^2} \\ \frac{1}{-\frac{1}{2} + \frac{i\sqrt{7}}{2}} \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[-3, \begin{bmatrix} \frac{1}{9} \\ -\frac{1}{3} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_1 = e^{-3x} \cdot \begin{bmatrix} \frac{1}{9} \\ -\frac{1}{3} \\ 1 \end{bmatrix}$$

- Consider complex eigenpair, complex conjugate eigenvalue can be ignored

$$\begin{bmatrix} -\frac{1}{2} - \frac{I\sqrt{7}}{2}, & \begin{bmatrix} \frac{1}{\left(-\frac{1}{2} - \frac{I\sqrt{7}}{2}\right)^2} \\ \frac{1}{-\frac{1}{2} - \frac{I\sqrt{7}}{2}} \\ 1 \end{bmatrix} \end{bmatrix}$$

- Solution from eigenpair

$$e^{\left(-\frac{1}{2} - \frac{I\sqrt{7}}{2}\right)x} \cdot \begin{bmatrix} \frac{1}{\left(-\frac{1}{2} - \frac{I\sqrt{7}}{2}\right)^2} \\ \frac{1}{-\frac{1}{2} - \frac{I\sqrt{7}}{2}} \\ 1 \end{bmatrix}$$

- Use Euler identity to write solution in terms of sin and cos

$$e^{-\frac{x}{2}} \cdot \left(\cos\left(\frac{\sqrt{7}x}{2}\right) - I \sin\left(\frac{\sqrt{7}x}{2}\right) \right) \cdot \begin{bmatrix} \frac{1}{\left(-\frac{1}{2} - \frac{I\sqrt{7}}{2}\right)^2} \\ \frac{1}{-\frac{1}{2} - \frac{I\sqrt{7}}{2}} \\ 1 \end{bmatrix}$$

- Simplify expression

$$e^{-\frac{x}{2}} \cdot \begin{bmatrix} \frac{\cos\left(\frac{\sqrt{7}x}{2}\right) - I \sin\left(\frac{\sqrt{7}x}{2}\right)}{\left(-\frac{1}{2} - \frac{I\sqrt{7}}{2}\right)^2} \\ \frac{\cos\left(\frac{\sqrt{7}x}{2}\right) - I \sin\left(\frac{\sqrt{7}x}{2}\right)}{-\frac{1}{2} - \frac{I\sqrt{7}}{2}} \\ \cos\left(\frac{\sqrt{7}x}{2}\right) - I \sin\left(\frac{\sqrt{7}x}{2}\right) \end{bmatrix}$$

- Both real and imaginary parts are solutions to the homogeneous system

$$\vec{y}_2(x) = e^{-\frac{x}{2}} \cdot \begin{bmatrix} -\frac{3 \cos\left(\frac{\sqrt{7}x}{2}\right)}{8} - \frac{\sin\left(\frac{\sqrt{7}x}{2}\right)\sqrt{7}}{8} \\ -\frac{\cos\left(\frac{\sqrt{7}x}{2}\right)}{4} + \frac{\sin\left(\frac{\sqrt{7}x}{2}\right)\sqrt{7}}{4} \\ \cos\left(\frac{\sqrt{7}x}{2}\right) \end{bmatrix}, \vec{y}_3(x) = e^{-\frac{x}{2}} \cdot \begin{bmatrix} -\frac{\cos\left(\frac{\sqrt{7}x}{2}\right)\sqrt{7}}{8} + \frac{3 \sin\left(\frac{\sqrt{7}x}{2}\right)}{8} \\ \frac{\cos\left(\frac{\sqrt{7}x}{2}\right)\sqrt{7}}{4} + \frac{\sin\left(\frac{\sqrt{7}x}{2}\right)}{4} \\ -\sin\left(\frac{\sqrt{7}x}{2}\right) \end{bmatrix}$$

- General solution to the system of ODEs

$$\vec{y} = c_1 \vec{y}_1 + c_2 \vec{y}_2(x) + c_3 \vec{y}_3(x)$$

- Substitute solutions into the general solution

$$\vec{y} = c_1 e^{-3x} \cdot \begin{bmatrix} \frac{1}{9} \\ -\frac{1}{3} \\ 1 \end{bmatrix} + c_2 e^{-\frac{x}{2}} \cdot \begin{bmatrix} -\frac{3 \cos\left(\frac{\sqrt{7}x}{2}\right) - \sin\left(\frac{\sqrt{7}x}{2}\right)\sqrt{7}}{8} \\ -\frac{\cos\left(\frac{\sqrt{7}x}{2}\right)}{4} + \frac{\sin\left(\frac{\sqrt{7}x}{2}\right)\sqrt{7}}{4} \\ \cos\left(\frac{\sqrt{7}x}{2}\right) \end{bmatrix} + c_3 e^{-\frac{x}{2}} \cdot \begin{bmatrix} -\frac{\cos\left(\frac{\sqrt{7}x}{2}\right)\sqrt{7}}{8} + \frac{3 \sin\left(\frac{\sqrt{7}x}{2}\right)}{8} \\ \frac{\cos\left(\frac{\sqrt{7}x}{2}\right)\sqrt{7}}{4} + \frac{\sin\left(\frac{\sqrt{7}x}{2}\right)}{4} \\ -\sin\left(\frac{\sqrt{7}x}{2}\right) \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y = -\frac{3\left(\frac{c_3\sqrt{7}}{3} + c_2\right)e^{-\frac{x}{2}} \cos\left(\frac{\sqrt{7}x}{2}\right)}{8} - \frac{e^{-\frac{x}{2}}(c_2\sqrt{7} - 3c_3) \sin\left(\frac{\sqrt{7}x}{2}\right)}{8} + \frac{c_1 e^{-3x}}{9}$$

Maple trace

```

`Methods for third order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 37

```
dsolve(diff(y(x),x$3)+4*diff(y(x),x$2)+5*diff(y(x),x)+6*y(x)=0,y(x), singsol=all)
```

$$y(x) = c_1 e^{-3x} + c_2 e^{-\frac{x}{2}} \sin\left(\frac{\sqrt{7}x}{2}\right) + c_3 e^{-\frac{x}{2}} \cos\left(\frac{\sqrt{7}x}{2}\right)$$

✓ Solution by Mathematica

Time used: 0.004 (sec). Leaf size: 56

```
DSolve[y'''[x]+4*y''[x]+5*y'[x]+6*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^{-3x} \left(c_2 e^{5x/2} \cos\left(\frac{\sqrt{7}x}{2}\right) + c_1 e^{5x/2} \sin\left(\frac{\sqrt{7}x}{2}\right) + c_3 \right)$$

10.17 problem 17

10.17.1 Maple step by step solution 2012

Internal problem ID [11747]

Internal file name [OUTPUT/11756_Thursday_April_11_2024_08_49_24_PM_84570994/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 17.

ODE order: 3.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_3rd_order , _missing_x]]
```

$$y''' - y'' + y' - y = 0$$

The characteristic equation is

$$\lambda^3 - \lambda^2 + \lambda - 1 = 0$$

The roots of the above equation are

$$\lambda_1 = 1$$

$$\lambda_2 = i$$

$$\lambda_3 = -i$$

Therefore the homogeneous solution is

$$y_h(x) = e^x c_1 + e^{ix} c_2 + e^{-ix} c_3$$

The fundamental set of solutions for the homogeneous solution are the following

$$y_1 = e^x$$

$$y_2 = e^{ix}$$

$$y_3 = e^{-ix}$$

Summary

The solution(s) found are the following

$$y = e^x c_1 + e^{ix} c_2 + e^{-ix} c_3 \quad (1)$$

Verification of solutions

$$y = e^x c_1 + e^{ix} c_2 + e^{-ix} c_3$$

Verified OK.

10.17.1 Maple step by step solution

Let's solve

$$y''' - y'' + y' - y = 0$$

- Highest derivative means the order of the ODE is 3

$$y'''$$

- Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(x)$

$$y_1(x) = y$$

- Define new variable $y_2(x)$

$$y_2(x) = y'$$

- Define new variable $y_3(x)$

$$y_3(x) = y''$$

- Isolate for $y_3'(x)$ using original ODE

$$y_3'(x) = y_3(x) - y_2(x) + y_1(x)$$

Convert linear ODE into a system of first order ODEs

$$[y_2(x) = y_1'(x), y_3(x) = y_2'(x), y_3'(x) = y_3(x) - y_2(x) + y_1(x)]$$

- Define vector

$$\vec{y}(x) = \begin{bmatrix} y_1(x) \\ y_2(x) \\ y_3(x) \end{bmatrix}$$

- System to solve

$$\vec{y}'(x) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & -1 & 1 \end{bmatrix} \cdot \vec{y}(x)$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & -1 & 1 \end{bmatrix}$$

- Rewrite the system as

$$\vec{y}'(x) = A \cdot \vec{y}(x)$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[1, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right], \left[-I, \begin{bmatrix} -1 \\ I \\ 1 \end{bmatrix} \right], \left[I, \begin{bmatrix} -1 \\ -I \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[1, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_1 = e^x \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

- Consider complex eigenpair, complex conjugate eigenvalue can be ignored

$$\left[-I, \begin{bmatrix} -1 \\ I \\ 1 \end{bmatrix} \right]$$

- Solution from eigenpair

$$e^{-Ix} \cdot \begin{bmatrix} -1 \\ I \\ 1 \end{bmatrix}$$

- Use Euler identity to write solution in terms of sin and cos

$$(\cos(x) - I \sin(x)) \cdot \begin{bmatrix} -1 \\ I \\ 1 \end{bmatrix}$$

- Simplify expression

$$\begin{bmatrix} -\cos(x) + I \sin(x) \\ I(\cos(x) - I \sin(x)) \\ \cos(x) - I \sin(x) \end{bmatrix}$$

- Both real and imaginary parts are solutions to the homogeneous system

$$\left[\vec{y}_2(x) = \begin{bmatrix} -\cos(x) \\ \sin(x) \\ \cos(x) \end{bmatrix}, \vec{y}_3(x) = \begin{bmatrix} \sin(x) \\ \cos(x) \\ -\sin(x) \end{bmatrix} \right]$$

- General solution to the system of ODEs

$$\vec{y} = c_1 \vec{y}_1 + c_2 \vec{y}_2(x) + c_3 \vec{y}_3(x)$$

- Substitute solutions into the general solution

$$\vec{y} = e^x c_1 \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + \begin{bmatrix} -c_2 \cos(x) + c_3 \sin(x) \\ c_2 \sin(x) + c_3 \cos(x) \\ c_2 \cos(x) - c_3 \sin(x) \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y = e^x c_1 + c_3 \sin(x) - c_2 \cos(x)$$

Maple trace

```
`Methods for third order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
<- constant coefficients successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 17

```
dsolve(diff(y(x),x$3)-diff(y(x),x$2)+diff(y(x),x)-y(x)=0,y(x), singsol=all)
```

$$y(x) = c_1 e^x + \sin(x) c_2 + c_3 \cos(x)$$

✓ Solution by Mathematica

Time used: 0.003 (sec). Leaf size: 22

```
DSolve[y'''[x]-y''[x]+y'[x]-y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow c_3 e^x + c_1 \cos(x) + c_2 \sin(x)$$

10.18 problem 18

Internal problem ID [11748]

Internal file name [OUTPUT/11757_Thursday_April_11_2024_08_49_24_PM_39924745/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 18.

ODE order: 4.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_high_order , _missing_x]]
```

$$y'''' + 8y'' + 16y = 0$$

The characteristic equation is

$$\lambda^4 + 8\lambda^2 + 16 = 0$$

The roots of the above equation are

$$\lambda_1 = 2i$$

$$\lambda_2 = -2i$$

$$\lambda_3 = 2i$$

$$\lambda_4 = -2i$$

Therefore the homogeneous solution is

$$y_h(x) = e^{2ix}c_1 + x e^{2ix}c_2 + e^{-2ix}c_3 + x e^{-2ix}c_4$$

The fundamental set of solutions for the homogeneous solution are the following

$$y_1 = e^{2ix}$$

$$y_2 = x e^{2ix}$$

$$y_3 = e^{-2ix}$$

$$y_4 = x e^{-2ix}$$

Summary

The solution(s) found are the following

$$y = e^{2ix}c_1 + x e^{2ix}c_2 + e^{-2ix}c_3 + x e^{-2ix}c_4 \quad (1)$$

Verification of solutions

$$y = e^{2ix}c_1 + x e^{2ix}c_2 + e^{-2ix}c_3 + x e^{-2ix}c_4$$

Verified OK.

Maple trace

```
`Methods for high order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
<- constant coefficients successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 25

```
dsolve(diff(y(x),x$4)+8*diff(y(x),x$2)+16*y(x)=0,y(x), singsol=all)
```

$$y(x) = (c_4x + c_2) \cos(2x) + \sin(2x) (c_3x + c_1)$$

✓ Solution by Mathematica

Time used: 0.003 (sec). Leaf size: 30

```
DSolve[y''''[x]+8*y''[x]+16*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow (c_2x + c_1) \cos(2x) + (c_4x + c_3) \sin(2x)$$

10.19 problem 19

10.19.1 Maple step by step solution 2019

Internal problem ID [11749]

Internal file name [OUTPUT/11758_Thursday_April_11_2024_08_49_25_PM_75101065/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 19.

ODE order: 5.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_high_order , _missing_x]]
```

$$y^{(5)} - 2y'''' + y''' = 0$$

The characteristic equation is

$$\lambda^5 - 2\lambda^4 + \lambda^3 = 0$$

The roots of the above equation are

$$\lambda_1 = 0$$

$$\lambda_2 = 0$$

$$\lambda_3 = 0$$

$$\lambda_4 = 1$$

$$\lambda_5 = 1$$

Therefore the homogeneous solution is

$$y_h(x) = c_3x^2 + c_2x + c_1 + e^x c_4 + x e^x c_5$$

The fundamental set of solutions for the homogeneous solution are the following

$$y_1 = 1$$

$$y_2 = x$$

$$y_3 = x^2$$

$$y_4 = e^x$$

$$y_5 = x e^x$$

Summary

The solution(s) found are the following

$$y = c_3 x^2 + c_2 x + c_1 + e^x c_4 + x e^x c_5 \quad (1)$$

Verification of solutions

$$y = c_3 x^2 + c_2 x + c_1 + e^x c_4 + x e^x c_5$$

Verified OK.

10.19.1 Maple step by step solution

Let's solve

$$y^{(5)} - 2y'''' + y''' = 0$$

- Highest derivative means the order of the ODE is 5
- Convert linear ODE into a system of first order ODEs
 - Define new variable $y_1(x)$
$$y_1(x) = y$$
 - Define new variable $y_2(x)$
$$y_2(x) = y'$$
 - Define new variable $y_3(x)$
$$y_3(x) = y''$$
 - Define new variable $y_4(x)$
$$y_4(x) = y'''$$
 - Define new variable $y_5(x)$
$$y_5(x) = y''''$$

- Isolate for $y_5'(x)$ using original ODE

$$y_5'(x) = 2y_5(x) - y_4(x)$$

Convert linear ODE into a system of first order ODEs

$$[y_2(x) = y_1'(x), y_3(x) = y_2'(x), y_4(x) = y_3'(x), y_5(x) = y_4'(x), y_5'(x) = 2y_5(x) - y_4(x)]$$

- Define vector

$$\vec{y}(x) = \begin{bmatrix} y_1(x) \\ y_2(x) \\ y_3(x) \\ y_4(x) \\ y_5(x) \end{bmatrix}$$

- System to solve

$$\vec{y}'(x) = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & -1 & 2 \end{bmatrix} \cdot \vec{y}(x)$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & -1 & 2 \end{bmatrix}$$

- Rewrite the system as

$$\vec{y}'(x) = A \cdot \vec{y}(x)$$

- To solve the system, find the eigenvalues and eigenvectors of A
- Eigenpairs of A

$$\left[\left[\begin{array}{c} 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{array} \right], \left[\begin{array}{c} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{array} \right], \left[\begin{array}{c} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{array} \right], \left[\begin{array}{c} 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{array} \right], \left[\begin{array}{c} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{array} \right] \right]$$

- Consider eigenpair

$$\left[\begin{array}{c} 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{array} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

- Consider eigenpair

$$\left[\begin{array}{c} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{array} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_2 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

- Consider eigenpair

$$\left[0, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_3 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

- Consider eigenpair, with eigenvalue of algebraic multiplicity 2

$$\left[1, \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} \right]$$

- First solution from eigenvalue 1

$$\vec{y}_4(x) = e^x \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$$

- Form of the 2nd homogeneous solution where \vec{p} is to be solved for, $\lambda = 1$ is the eigenvalue, and

$$\vec{y}_5(x) = e^{\lambda x} (x\vec{v} + \vec{p})$$

- Note that the x multiplying \vec{v} makes this solution linearly independent to the 1st solution obtained

- Substitute $\vec{y}_5(x)$ into the homogeneous system

$$\lambda e^{\lambda x} (x\vec{v} + \vec{p}) + e^{\lambda x} \vec{v} = (e^{\lambda x} A) \cdot (x\vec{v} + \vec{p})$$

- Use the fact that \vec{v} is an eigenvector of A

$$\lambda e^{\lambda x} (x\vec{v} + \vec{p}) + e^{\lambda x} \vec{v} = e^{\lambda x} (\lambda x\vec{v} + A \cdot \vec{p})$$

- Simplify equation

$$\lambda \vec{p} + \vec{v} = A \cdot \vec{p}$$

- Make use of the identity matrix I

$$(\lambda \cdot I) \cdot \vec{p} + \vec{v} = A \cdot \vec{p}$$

- Condition \vec{p} must meet for $\vec{y}_5(x)$ to be a solution to the homogeneous system

$$(A - \lambda \cdot I) \cdot \vec{p} = \vec{v}$$

- Choose \vec{p} to use in the second solution to the homogeneous system from eigenvalue 1

$$\left(\begin{bmatrix} 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & -1 & 2 \end{bmatrix} - 1 \cdot \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix} \right) \cdot \vec{p} = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$$

- Choice of \vec{p}

$$\vec{p} = \begin{bmatrix} -1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

- Second solution from eigenvalue 1

$$\vec{y}_5(x) = e^x \cdot \left(x \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} + \begin{bmatrix} -1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \right)$$

- General solution to the system of ODEs

$$\vec{y} = c_1 \vec{y}_1 + c_2 \vec{y}_2 + c_3 \vec{y}_3 + c_4 \vec{y}_4(x) + c_5 \vec{y}_5(x)$$

- Substitute solutions into the general solution

$$\vec{y} = e^x c_4 \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} + c_5 e^x \cdot \left(x \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} + \begin{bmatrix} -1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \right) + \begin{bmatrix} c_1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y = ((x - 1) c_5 + c_4) e^x + c_1$$

Maple trace

```

`Methods for high order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 22

```
dsolve(diff(y(x),x$5)-2*diff(y(x),x$4)+diff(y(x),x$3)=0,y(x), singsol=all)
```

$$y(x) = (c_5x + c_4)e^x + c_3x^2 + c_2x + c_1$$

✓ Solution by Mathematica

Time used: 0.096 (sec). Leaf size: 30

```
DSolve[y'''''[x]-2*y''''[x]+y'''[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^x(c_2(x - 3) + c_1) + x(c_5x + c_4) + c_3$$

10.20 problem 20

10.20.1 Maple step by step solution 2027

Internal problem ID [11750]

Internal file name [OUTPUT/11759_Thursday_April_11_2024_08_49_25_PM_94911187/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 20.

ODE order: 4.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_high_order, _missing_x]]
```

$$y'''' - y''' - 3y'' + y' + 2y = 0$$

The characteristic equation is

$$\lambda^4 - \lambda^3 - 3\lambda^2 + \lambda + 2 = 0$$

The roots of the above equation are

$$\lambda_1 = 1$$

$$\lambda_2 = 2$$

$$\lambda_3 = -1$$

$$\lambda_4 = -1$$

Therefore the homogeneous solution is

$$y_h(x) = c_1 e^{-x} + x e^{-x} c_2 + c_3 e^x + e^{2x} c_4$$

The fundamental set of solutions for the homogeneous solution are the following

$$\begin{aligned}y_1 &= e^{-x} \\y_2 &= x e^{-x} \\y_3 &= e^x \\y_4 &= e^{2x}\end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 e^{-x} + x e^{-x} c_2 + c_3 e^x + e^{2x} c_4 \quad (1)$$

Verification of solutions

$$y = c_1 e^{-x} + x e^{-x} c_2 + c_3 e^x + e^{2x} c_4$$

Verified OK.

10.20.1 Maple step by step solution

Let's solve

$$y'''' - y''' - 3y'' + y' + 2y = 0$$

- Highest derivative means the order of the ODE is 4

$$y''''$$

- Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(x)$

$$y_1(x) = y$$

- Define new variable $y_2(x)$

$$y_2(x) = y'$$

- Define new variable $y_3(x)$

$$y_3(x) = y''$$

- Define new variable $y_4(x)$

$$y_4(x) = y'''$$

- Isolate for $y_4'(x)$ using original ODE

$$y_4'(x) = y_4(x) + 3y_3(x) - y_2(x) - 2y_1(x)$$

Convert linear ODE into a system of first order ODEs

$$[y_2(x) = y_1'(x), y_3(x) = y_2'(x), y_4(x) = y_3'(x), y_4'(x) = y_4(x) + 3y_3(x) - y_2(x) - 2y_1(x)]$$

- Define vector

$$\vec{y}(x) = \begin{bmatrix} y_1(x) \\ y_2(x) \\ y_3(x) \\ y_4(x) \end{bmatrix}$$

- System to solve

$$\vec{y}'(x) = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -2 & -1 & 3 & 1 \end{bmatrix} \cdot \vec{y}(x)$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -2 & -1 & 3 & 1 \end{bmatrix}$$

- Rewrite the system as

$$\vec{y}'(x) = A \cdot \vec{y}(x)$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[-1, \begin{bmatrix} -1 \\ 1 \\ -1 \\ 1 \end{bmatrix} \right], \left[-1, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \right], \left[1, \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} \right], \left[2, \begin{bmatrix} \frac{1}{8} \\ \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair, with eigenvalue of algebraic multiplicity 2

$$\left[-1, \begin{bmatrix} -1 \\ 1 \\ -1 \\ 1 \end{bmatrix} \right]$$

- First solution from eigenvalue -1

$$\vec{y}_1(x) = e^{-x} \cdot \begin{bmatrix} -1 \\ 1 \\ -1 \\ 1 \end{bmatrix}$$

- Form of the 2nd homogeneous solution where \vec{p} is to be solved for, $\lambda = -1$ is the eigenvalue, a

$$\vec{y}_2(x) = e^{\lambda x} (x\vec{v} + \vec{p})$$

- Note that the x multiplying \vec{v} makes this solution linearly independent to the 1st solution obt

- Substitute $\vec{y}_2(x)$ into the homogeneous system

$$\lambda e^{\lambda x} (x\vec{v} + \vec{p}) + e^{\lambda x} \vec{v} = (e^{\lambda x} A) \cdot (x\vec{v} + \vec{p})$$

- Use the fact that \vec{v} is an eigenvector of A

$$\lambda e^{\lambda x} (x\vec{v} + \vec{p}) + e^{\lambda x} \vec{v} = e^{\lambda x} (\lambda x\vec{v} + A \cdot \vec{p})$$

- Simplify equation

$$\lambda \vec{p} + \vec{v} = A \cdot \vec{p}$$

- Make use of the identity matrix I

$$(\lambda \cdot I) \cdot \vec{p} + \vec{v} = A \cdot \vec{p}$$

- Condition \vec{p} must meet for $\vec{y}_2(x)$ to be a solution to the homogeneous system

$$(A - \lambda \cdot I) \cdot \vec{p} = \vec{v}$$

- Choose \vec{p} to use in the second solution to the homogeneous system from eigenvalue -1

$$\left(\begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -2 & -1 & 3 & 1 \end{bmatrix} - (-1) \cdot \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \right) \cdot \vec{p} = \begin{bmatrix} -1 \\ 1 \\ -1 \\ 1 \end{bmatrix}$$

- Choice of \vec{p}

$$\vec{p} = \begin{bmatrix} -1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

- Second solution from eigenvalue -1

$$\vec{y}_2(x) = e^{-x} \cdot \left(x \cdot \begin{bmatrix} -1 \\ 1 \\ -1 \\ 1 \end{bmatrix} + \begin{bmatrix} -1 \\ 0 \\ 0 \\ 0 \end{bmatrix} \right)$$

- Consider eigenpair

$$\left[1, \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_3 = e^x \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[2, \begin{bmatrix} \frac{1}{8} \\ \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_4 = e^{2x} \cdot \begin{bmatrix} \frac{1}{8} \\ \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix}$$

- General solution to the system of ODEs

$$\vec{y} = c_1 \vec{y}_1(x) + c_2 \vec{y}_2(x) + c_3 \vec{y}_3 + c_4 \vec{y}_4$$

- Substitute solutions into the general solution

$$\vec{y} = c_1 e^{-x} \cdot \begin{bmatrix} -1 \\ 1 \\ -1 \\ 1 \end{bmatrix} + c_2 e^{-x} \cdot \left(x \cdot \begin{bmatrix} -1 \\ 1 \\ -1 \\ 1 \end{bmatrix} + \begin{bmatrix} -1 \\ 0 \\ 0 \\ 0 \end{bmatrix} \right) + c_3 e^x \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} + e^{2x} c_4 \cdot \begin{bmatrix} \frac{1}{8} \\ \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y = ((-x - 1) c_2 - c_1) e^{-x} + c_3 e^x + \frac{e^{2x} c_4}{8}$$

Maple trace

```

`Methods for high order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 25

```
dsolve(diff(y(x),x$4)-diff(y(x),x$3)-3*diff(y(x),x$2)+diff(y(x),x)+2*y(x)=0,y(x), singsol=all)
```

$$y(x) = (c_4 x + c_3) e^{-x} + c_1 e^x + c_2 e^{2x}$$

✓ Solution by Mathematica

Time used: 0.003 (sec). Leaf size: 33

```
DSolve[y''''[x]-y''''[x]-3*y''[x]+y'[x]+2*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^{-x} (c_2 x + e^{2x} (c_4 e^x + c_3) + c_1)$$

10.21 problem 21

10.21.1 Maple step by step solution 2034

Internal problem ID [11751]

Internal file name [OUTPUT/11760_Thursday_April_11_2024_08_49_25_PM_40279363/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 21.

ODE order: 4.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_high_order , _missing_x]]
```

$$y'''' - 3y''' - 2y'' + 2y' + 12y = 0$$

The characteristic equation is

$$\lambda^4 - 3\lambda^3 - 2\lambda^2 + 2\lambda + 12 = 0$$

The roots of the above equation are

$$\lambda_1 = 2$$

$$\lambda_2 = 3$$

$$\lambda_3 = -1 - i$$

$$\lambda_4 = -1 + i$$

Therefore the homogeneous solution is

$$y_h(x) = c_1 e^{2x} + e^{3x} c_2 + e^{(-1+i)x} c_3 + e^{(-1-i)x} c_4$$

The fundamental set of solutions for the homogeneous solution are the following

$$\begin{aligned}y_1 &= e^{2x} \\y_2 &= e^{3x} \\y_3 &= e^{(-1+i)x} \\y_4 &= e^{(-1-i)x}\end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 e^{2x} + e^{3x} c_2 + e^{(-1+i)x} c_3 + e^{(-1-i)x} c_4 \quad (1)$$

Verification of solutions

$$y = c_1 e^{2x} + e^{3x} c_2 + e^{(-1+i)x} c_3 + e^{(-1-i)x} c_4$$

Verified OK.

10.21.1 Maple step by step solution

Let's solve

$$y'''' - 3y''' - 2y'' + 2y' + 12y = 0$$

- Highest derivative means the order of the ODE is 4

$$y''''$$

- Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(x)$

$$y_1(x) = y$$

- Define new variable $y_2(x)$

$$y_2(x) = y'$$

- Define new variable $y_3(x)$

$$y_3(x) = y''$$

- Define new variable $y_4(x)$

$$y_4(x) = y'''$$

- Isolate for $y_4'(x)$ using original ODE

$$y_4'(x) = 3y_4(x) + 2y_3(x) - 2y_2(x) - 12y_1(x)$$

Convert linear ODE into a system of first order ODEs

$$[y_2(x) = y_1'(x), y_3(x) = y_2'(x), y_4(x) = y_3'(x), y_4'(x) = 3y_4(x) + 2y_3(x) - 2y_2(x) - 12y_1(x)]$$

- Define vector

$$\vec{y}(x) = \begin{bmatrix} y_1(x) \\ y_2(x) \\ y_3(x) \\ y_4(x) \end{bmatrix}$$

- System to solve

$$\vec{y}'(x) = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -12 & -2 & 2 & 3 \end{bmatrix} \cdot \vec{y}(x)$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -12 & -2 & 2 & 3 \end{bmatrix}$$

- Rewrite the system as

$$\vec{y}'(x) = A \cdot \vec{y}(x)$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[\begin{bmatrix} 2 \\ \frac{1}{8} \\ \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right], \left[\begin{bmatrix} 3 \\ \frac{1}{27} \\ \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix} \right], \left[-1 - I, \begin{bmatrix} \frac{1}{4} + \frac{I}{4} \\ -\frac{I}{2} \\ -\frac{1}{2} + \frac{I}{2} \\ 1 \end{bmatrix} \right], \left[-1 + I, \begin{bmatrix} \frac{1}{4} - \frac{I}{4} \\ \frac{I}{2} \\ -\frac{1}{2} - \frac{I}{2} \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[2, \begin{bmatrix} \frac{1}{8} \\ \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_1 = e^{2x} \cdot \begin{bmatrix} \frac{1}{8} \\ \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[3, \begin{bmatrix} \frac{1}{27} \\ \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_2 = e^{3x} \cdot \begin{bmatrix} \frac{1}{27} \\ \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix}$$

- Consider complex eigenpair, complex conjugate eigenvalue can be ignored

$$\left[-1 - I, \begin{bmatrix} \frac{1}{4} + \frac{I}{4} \\ -\frac{I}{2} \\ -\frac{1}{2} + \frac{I}{2} \\ 1 \end{bmatrix} \right]$$

- Solution from eigenpair

$$e^{(-1-I)x} \cdot \begin{bmatrix} \frac{1}{4} + \frac{I}{4} \\ -\frac{I}{2} \\ -\frac{1}{2} + \frac{I}{2} \\ 1 \end{bmatrix}$$

- Use Euler identity to write solution in terms of sin and cos

$$e^{-x} \cdot (\cos(x) - I \sin(x)) \cdot \begin{bmatrix} \frac{1}{4} + \frac{I}{4} \\ -\frac{I}{2} \\ -\frac{1}{2} + \frac{I}{2} \\ 1 \end{bmatrix}$$

- Simplify expression

$$e^{-x} \cdot \begin{bmatrix} (\frac{1}{4} + \frac{I}{4})(\cos(x) - I \sin(x)) \\ -\frac{I}{2}(\cos(x) - I \sin(x)) \\ (-\frac{1}{2} + \frac{I}{2})(\cos(x) - I \sin(x)) \\ \cos(x) - I \sin(x) \end{bmatrix}$$

- Both real and imaginary parts are solutions to the homogeneous system

$$\begin{bmatrix} \vec{y}_3(x) = e^{-x} \cdot \begin{bmatrix} \frac{\cos(x)}{4} + \frac{\sin(x)}{4} \\ -\frac{\sin(x)}{2} \\ -\frac{\cos(x)}{2} + \frac{\sin(x)}{2} \\ \cos(x) \end{bmatrix}, \vec{y}_4(x) = e^{-x} \cdot \begin{bmatrix} \frac{\cos(x)}{4} - \frac{\sin(x)}{4} \\ -\frac{\cos(x)}{2} \\ \frac{\sin(x)}{2} + \frac{\cos(x)}{2} \\ -\sin(x) \end{bmatrix} \end{bmatrix}$$

- General solution to the system of ODEs

$$\vec{y} = c_1 \vec{y}_1 + c_2 \vec{y}_2 + c_3 \vec{y}_3(x) + c_4 \vec{y}_4(x)$$

- Substitute solutions into the general solution

$$\vec{y} = c_1 e^{2x} \cdot \begin{bmatrix} \frac{1}{8} \\ \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} + e^{3x} c_2 \cdot \begin{bmatrix} \frac{1}{27} \\ \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix} + c_3 e^{-x} \cdot \begin{bmatrix} \frac{\cos(x)}{4} + \frac{\sin(x)}{4} \\ -\frac{\sin(x)}{2} \\ -\frac{\cos(x)}{2} + \frac{\sin(x)}{2} \\ \cos(x) \end{bmatrix} + c_4 e^{-x} \cdot \begin{bmatrix} \frac{\cos(x)}{4} - \frac{\sin(x)}{4} \\ -\frac{\cos(x)}{2} \\ \frac{\sin(x)}{2} + \frac{\cos(x)}{2} \\ -\sin(x) \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y = \frac{((c_3+c_4) \cos(x)+\sin(x)(c_3-c_4))e^{-x}}{4} + \frac{e^{3x}c_2}{27} + \frac{c_1e^{2x}}{8}$$

Maple trace

```

`Methods for high order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 33

```
dsolve(diff(y(x),x$4)-3*diff(y(x),x$3)-2*diff(y(x),x$2)+2*diff(y(x),x)+12*y(x)=0,y(x), singular
```

$$y(x) = e^{2x}c_1 + c_2e^{3x} + c_3e^{-x} \sin(x) + c_4e^{-x} \cos(x)$$

✓ Solution by Mathematica

Time used: 0.003 (sec). Leaf size: 37

```
DSolve[y''''[x]-3*y'''[x]-2*y''[x]+2*y'[x]+12*y[x]==0,y[x],x,IncludeSingularSolutions -> True
```

$$y(x) \rightarrow e^{-x}(e^{3x}(c_4e^x + c_3) + c_2 \cos(x) + c_1 \sin(x))$$

10.22 problem 22

10.22.1 Maple step by step solution 2040

Internal problem ID [11752]

Internal file name [OUTPUT/11761_Thursday_April_11_2024_08_49_26_PM_31848990/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 22.

ODE order: 4.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_high_order, _missing_x]]
```

$$y'''' + 6y''' + 15y'' + 20y' + 12y = 0$$

The characteristic equation is

$$\lambda^4 + 6\lambda^3 + 15\lambda^2 + 20\lambda + 12 = 0$$

The roots of the above equation are

$$\lambda_1 = i\sqrt{2} - 1$$

$$\lambda_2 = -1 - i\sqrt{2}$$

$$\lambda_3 = -2$$

$$\lambda_4 = -2$$

Therefore the homogeneous solution is

$$y_h(x) = c_1 e^{-2x} + x e^{-2x} c_2 + e^{(i\sqrt{2}-1)x} c_3 + e^{(-1-i\sqrt{2})x} c_4$$

The fundamental set of solutions for the homogeneous solution are the following

$$\begin{aligned}y_1 &= e^{-2x} \\y_2 &= x e^{-2x} \\y_3 &= e^{(i\sqrt{2}-1)x} \\y_4 &= e^{(-1-i\sqrt{2})x}\end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 e^{-2x} + x e^{-2x} c_2 + e^{(i\sqrt{2}-1)x} c_3 + e^{(-1-i\sqrt{2})x} c_4 \quad (1)$$

Verification of solutions

$$y = c_1 e^{-2x} + x e^{-2x} c_2 + e^{(i\sqrt{2}-1)x} c_3 + e^{(-1-i\sqrt{2})x} c_4$$

Verified OK.

10.22.1 Maple step by step solution

Let's solve

$$y'''' + 6y''' + 15y'' + 20y' + 12y = 0$$

- Highest derivative means the order of the ODE is 4

$$y''''$$

- Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(x)$

$$y_1(x) = y$$

- Define new variable $y_2(x)$

$$y_2(x) = y'$$

- Define new variable $y_3(x)$

$$y_3(x) = y''$$

- Define new variable $y_4(x)$

$$y_4(x) = y'''$$

- Isolate for $y_4'(x)$ using original ODE

$$y_4'(x) = -6y_4(x) - 15y_3(x) - 20y_2(x) - 12y_1(x)$$

Convert linear ODE into a system of first order ODEs

$$[y_2(x) = y_1'(x), y_3(x) = y_2'(x), y_4(x) = y_3'(x), y_4'(x) = -6y_4(x) - 15y_3(x) - 20y_2(x) - 12y_1(x)]$$

- Define vector

$$\vec{y}(x) = \begin{bmatrix} y_1(x) \\ y_2(x) \\ y_3(x) \\ y_4(x) \end{bmatrix}$$

- System to solve

$$\vec{y}'(x) = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -12 & -20 & -15 & -6 \end{bmatrix} \cdot \vec{y}(x)$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -12 & -20 & -15 & -6 \end{bmatrix}$$

- Rewrite the system as

$$\vec{y}'(x) = A \cdot \vec{y}(x)$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[-2, \begin{bmatrix} -\frac{1}{8} \\ \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix} \right], \left[-2, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \right], \left[-1 - I\sqrt{2}, \begin{bmatrix} \frac{1}{(-1-I\sqrt{2})^3} \\ \frac{1}{(-1-I\sqrt{2})^2} \\ \frac{1}{-1-I\sqrt{2}} \\ 1 \end{bmatrix} \right], \left[I\sqrt{2} - 1, \begin{bmatrix} \frac{1}{(I\sqrt{2}-1)^3} \\ \frac{1}{(I\sqrt{2}-1)^2} \\ \frac{1}{I\sqrt{2}-1} \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair, with eigenvalue of algebraic multiplicity 2

$$\left[-2, \begin{bmatrix} -\frac{1}{8} \\ \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix} \right]$$

- First solution from eigenvalue -2

$$\vec{y}_1(x) = e^{-2x} \cdot \begin{bmatrix} -\frac{1}{8} \\ \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix}$$

- Form of the 2nd homogeneous solution where \vec{p} is to be solved for, $\lambda = -2$ is the eigenvalue, a

$$\vec{y}_2(x) = e^{\lambda x} (x\vec{v} + \vec{p})$$

- Note that the x multiplying \vec{v} makes this solution linearly independent to the 1st solution obt

- Substitute $\vec{y}_2(x)$ into the homogeneous system

$$\lambda e^{\lambda x} (x\vec{v} + \vec{p}) + e^{\lambda x} \vec{v} = (e^{\lambda x} A) \cdot (x\vec{v} + \vec{p})$$

- Use the fact that \vec{v} is an eigenvector of A

$$\lambda e^{\lambda x} (x\vec{v} + \vec{p}) + e^{\lambda x} \vec{v} = e^{\lambda x} (\lambda x\vec{v} + A \cdot \vec{p})$$

- Simplify equation

$$\lambda \vec{p} + \vec{v} = A \cdot \vec{p}$$

- Make use of the identity matrix I

$$(\lambda \cdot I) \cdot \vec{p} + \vec{v} = A \cdot \vec{p}$$

- Condition \vec{p} must meet for $\vec{y}_2(x)$ to be a solution to the homogeneous system

$$(A - \lambda \cdot I) \cdot \vec{p} = \vec{v}$$

- Choose \vec{p} to use in the second solution to the homogeneous system from eigenvalue -2

$$\left(\begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -12 & -20 & -15 & -6 \end{bmatrix} - (-2) \cdot \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \right) \cdot \vec{p} = \begin{bmatrix} -\frac{1}{8} \\ \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix}$$

- Choice of \vec{p}

$$\vec{p} = \begin{bmatrix} -\frac{1}{16} \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

- Second solution from eigenvalue -2

$$\vec{y}_2(x) = e^{-2x} \cdot \left(x \cdot \begin{bmatrix} -\frac{1}{8} \\ \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix} + \begin{bmatrix} -\frac{1}{16} \\ 0 \\ 0 \\ 0 \end{bmatrix} \right)$$

- Consider complex eigenpair, complex conjugate eigenvalue can be ignored

$$\left[-1 - I\sqrt{2}, \begin{bmatrix} \frac{1}{(-1-I\sqrt{2})^3} \\ \frac{1}{(-1-I\sqrt{2})^2} \\ \frac{1}{-1-I\sqrt{2}} \\ 1 \end{bmatrix} \right]$$

- Solution from eigenpair

$$e^{(-1-I\sqrt{2})x} \cdot \begin{bmatrix} \frac{1}{(-1-I\sqrt{2})^3} \\ \frac{1}{(-1-I\sqrt{2})^2} \\ \frac{1}{-1-I\sqrt{2}} \\ 1 \end{bmatrix}$$

- Use Euler identity to write solution in terms of sin and cos

$$e^{-x} \cdot (\cos(\sqrt{2}x) - I \sin(\sqrt{2}x)) \cdot \begin{bmatrix} \frac{1}{(-1-I\sqrt{2})^3} \\ \frac{1}{(-1-I\sqrt{2})^2} \\ \frac{1}{-1-I\sqrt{2}} \\ 1 \end{bmatrix}$$

- Simplify expression

$$e^{-x} \cdot \begin{bmatrix} \frac{\cos(\sqrt{2}x) - I \sin(\sqrt{2}x)}{(-1-I\sqrt{2})^3} \\ \frac{\cos(\sqrt{2}x) - I \sin(\sqrt{2}x)}{(-1-I\sqrt{2})^2} \\ \frac{\cos(\sqrt{2}x) - I \sin(\sqrt{2}x)}{-1-I\sqrt{2}} \\ \cos(\sqrt{2}x) - I \sin(\sqrt{2}x) \end{bmatrix}$$

- Both real and imaginary parts are solutions to the homogeneous system

$$\vec{y}_3(x) = e^{-x} \cdot \begin{bmatrix} \frac{5 \cos(\sqrt{2}x)}{27} + \frac{\sin(\sqrt{2}x)\sqrt{2}}{27} \\ -\frac{\cos(\sqrt{2}x)}{9} - \frac{2 \sin(\sqrt{2}x)\sqrt{2}}{9} \\ -\frac{\cos(\sqrt{2}x)}{3} + \frac{\sin(\sqrt{2}x)\sqrt{2}}{3} \\ \cos(\sqrt{2}x) \end{bmatrix}, \vec{y}_4(x) = e^{-x} \cdot \begin{bmatrix} \frac{\cos(\sqrt{2}x)\sqrt{2}}{27} - \frac{5 \sin(\sqrt{2}x)}{27} \\ -\frac{2 \cos(\sqrt{2}x)\sqrt{2}}{9} + \frac{\sin(\sqrt{2}x)}{9} \\ \frac{\cos(\sqrt{2}x)\sqrt{2}}{3} + \frac{\sin(\sqrt{2}x)}{3} \\ -\sin(\sqrt{2}x) \end{bmatrix}$$

- General solution to the system of ODEs

$$\vec{y} = c_1 \vec{y}_1(x) + c_2 \vec{y}_2(x) + c_3 \vec{y}_3(x) + c_4 \vec{y}_4(x)$$

- Substitute solutions into the general solution

$$\vec{y} = c_1 e^{-2x} \cdot \begin{bmatrix} -\frac{1}{8} \\ \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix} + c_2 e^{-2x} \cdot \left(x \cdot \begin{bmatrix} -\frac{1}{8} \\ \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix} + \begin{bmatrix} -\frac{1}{16} \\ 0 \\ 0 \\ 0 \end{bmatrix} \right) + c_3 e^{-x} \cdot \begin{bmatrix} \frac{5 \cos(\sqrt{2}x)}{27} + \frac{\sin(\sqrt{2}x)\sqrt{2}}{27} \\ \frac{\cos(\sqrt{2}x)}{9} - \frac{2 \sin(\sqrt{2}x)\sqrt{2}}{9} \\ -\frac{\cos(\sqrt{2}x)}{3} + \frac{\sin(\sqrt{2}x)\sqrt{2}}{3} \\ \cos(\sqrt{2}x) \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y = \frac{5e^{-x}\left(\frac{c_4\sqrt{2}}{5} + c_3\right)\cos(\sqrt{2}x)}{27} + \frac{e^{-x}(\sqrt{2}c_3 - 5c_4)\sin(\sqrt{2}x)}{27} - \frac{\left(x + \frac{1}{2}\right)c_2 + c_1}{8}e^{-2x}$$

Maple trace

```

`Methods for high order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 39

```
dsolve(diff(y(x),x$4)+6*diff(y(x),x$3)+15*diff(y(x),x$2)+20*diff(y(x),x)+12*y(x)=0,y(x), sin
```

$$y(x) = c_4e^{-x}\cos(x\sqrt{2}) + c_3e^{-x}\sin(x\sqrt{2}) + e^{-2x}(c_2x + c_1)$$

✓ Solution by Mathematica

Time used: 0.003 (sec). Leaf size: 46

```
DSolve[y''''[x]+6*y'''[x]+15*y''[x]+20*y'[x]+12*y[x]==0,y[x],x,IncludeSingularSolutions -> T
```

$$y(x) \rightarrow e^{-2x}\left(c_4x + c_2e^x\cos(\sqrt{2}x) + c_1e^x\sin(\sqrt{2}x) + c_3\right)$$

10.23 problem 23

10.23.1 Maple step by step solution 2047

Internal problem ID [11753]

Internal file name [OUTPUT/11762_Thursday_April_11_2024_08_49_26_PM_21910946/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 23.

ODE order: 4.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_high_order , _missing_x]]
```

$$y'''' + y = 0$$

The characteristic equation is

$$\lambda^4 + 1 = 0$$

The roots of the above equation are

$$\begin{aligned}\lambda_1 &= \frac{\sqrt{2}}{2} + \frac{i\sqrt{2}}{2} \\ \lambda_2 &= -\frac{\sqrt{2}}{2} + \frac{i\sqrt{2}}{2} \\ \lambda_3 &= -\frac{\sqrt{2}}{2} - \frac{i\sqrt{2}}{2} \\ \lambda_4 &= \frac{\sqrt{2}}{2} - \frac{i\sqrt{2}}{2}\end{aligned}$$

Therefore the homogeneous solution is

$$y_h(x) = e^{\left(\frac{\sqrt{2}}{2} + \frac{i\sqrt{2}}{2}\right)x} c_1 + e^{\left(-\frac{\sqrt{2}}{2} - \frac{i\sqrt{2}}{2}\right)x} c_2 + e^{\left(\frac{\sqrt{2}}{2} - \frac{i\sqrt{2}}{2}\right)x} c_3 + e^{\left(-\frac{\sqrt{2}}{2} + \frac{i\sqrt{2}}{2}\right)x} c_4$$

The fundamental set of solutions for the homogeneous solution are the following

$$\begin{aligned}y_1 &= e^{\left(\frac{\sqrt{2}}{2} + \frac{i\sqrt{2}}{2}\right)x} \\y_2 &= e^{\left(-\frac{\sqrt{2}}{2} - \frac{i\sqrt{2}}{2}\right)x} \\y_3 &= e^{\left(\frac{\sqrt{2}}{2} - \frac{i\sqrt{2}}{2}\right)x} \\y_4 &= e^{\left(-\frac{\sqrt{2}}{2} + \frac{i\sqrt{2}}{2}\right)x}\end{aligned}$$

Summary

The solution(s) found are the following

$$y = e^{\left(\frac{\sqrt{2}}{2} + \frac{i\sqrt{2}}{2}\right)x} c_1 + e^{\left(-\frac{\sqrt{2}}{2} - \frac{i\sqrt{2}}{2}\right)x} c_2 + e^{\left(\frac{\sqrt{2}}{2} - \frac{i\sqrt{2}}{2}\right)x} c_3 + e^{\left(-\frac{\sqrt{2}}{2} + \frac{i\sqrt{2}}{2}\right)x} c_4 \quad (1)$$

Verification of solutions

$$y = e^{\left(\frac{\sqrt{2}}{2} + \frac{i\sqrt{2}}{2}\right)x} c_1 + e^{\left(-\frac{\sqrt{2}}{2} - \frac{i\sqrt{2}}{2}\right)x} c_2 + e^{\left(\frac{\sqrt{2}}{2} - \frac{i\sqrt{2}}{2}\right)x} c_3 + e^{\left(-\frac{\sqrt{2}}{2} + \frac{i\sqrt{2}}{2}\right)x} c_4$$

Verified OK.

10.23.1 Maple step by step solution

Let's solve

$$y'''' + y = 0$$

- Highest derivative means the order of the ODE is 4

$$y''''$$

- Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(x)$

$$y_1(x) = y$$

- Define new variable $y_2(x)$

$$y_2(x) = y'$$

- Define new variable $y_3(x)$

$$y_3(x) = y''$$

- Define new variable $y_4(x)$

$$y_4(x) = y'''$$

- Isolate for $y_4'(x)$ using original ODE

$$y_4'(x) = -y_1(x)$$

Convert linear ODE into a system of first order ODEs

$$[y_2(x) = y_1'(x), y_3(x) = y_2'(x), y_4(x) = y_3'(x), y_4'(x) = -y_1(x)]$$

- Define vector

$$\vec{y}(x) = \begin{bmatrix} y_1(x) \\ y_2(x) \\ y_3(x) \\ y_4(x) \end{bmatrix}$$

- System to solve

$$\vec{y}'(x) = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -1 & 0 & 0 & 0 \end{bmatrix} \cdot \vec{y}(x)$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -1 & 0 & 0 & 0 \end{bmatrix}$$

- Rewrite the system as

$$\vec{y}'(x) = A \cdot \vec{y}(x)$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[-\frac{\sqrt{2}}{2} - \frac{I\sqrt{2}}{2}, \begin{bmatrix} \frac{1}{\left(-\frac{\sqrt{2}}{2} - \frac{I\sqrt{2}}{2}\right)^3} \\ \frac{1}{\left(-\frac{\sqrt{2}}{2} - \frac{I\sqrt{2}}{2}\right)^2} \\ \frac{1}{-\frac{\sqrt{2}}{2} - \frac{I\sqrt{2}}{2}} \\ 1 \end{bmatrix} \right], \left[-\frac{\sqrt{2}}{2} + \frac{I\sqrt{2}}{2}, \begin{bmatrix} \frac{1}{\left(-\frac{\sqrt{2}}{2} + \frac{I\sqrt{2}}{2}\right)^3} \\ \frac{1}{\left(-\frac{\sqrt{2}}{2} + \frac{I\sqrt{2}}{2}\right)^2} \\ \frac{1}{-\frac{\sqrt{2}}{2} + \frac{I\sqrt{2}}{2}} \\ 1 \end{bmatrix} \right], \left[\frac{\sqrt{2}}{2} - \frac{I\sqrt{2}}{2}, \begin{bmatrix} \frac{1}{\left(\frac{\sqrt{2}}{2} - \frac{I\sqrt{2}}{2}\right)^3} \\ \frac{1}{\left(\frac{\sqrt{2}}{2} - \frac{I\sqrt{2}}{2}\right)^2} \\ \frac{1}{\frac{\sqrt{2}}{2} - \frac{I\sqrt{2}}{2}} \\ 1 \end{bmatrix} \right] \right]$$

- Consider complex eigenpair, complex conjugate eigenvalue can be ignored

$$\begin{bmatrix} -\frac{\sqrt{2}}{2} - \frac{I\sqrt{2}}{2}, & \begin{bmatrix} \frac{1}{\left(-\frac{\sqrt{2}}{2} - \frac{I\sqrt{2}}{2}\right)^3} \\ \frac{1}{\left(-\frac{\sqrt{2}}{2} - \frac{I\sqrt{2}}{2}\right)^2} \\ \frac{1}{-\frac{\sqrt{2}}{2} - \frac{I\sqrt{2}}{2}} \\ 1 \end{bmatrix} \end{bmatrix}$$

- Solution from eigenpair

$$e^{\left(-\frac{\sqrt{2}}{2} - \frac{I\sqrt{2}}{2}\right)x} \cdot \begin{bmatrix} \frac{1}{\left(-\frac{\sqrt{2}}{2} - \frac{I\sqrt{2}}{2}\right)^3} \\ \frac{1}{\left(-\frac{\sqrt{2}}{2} - \frac{I\sqrt{2}}{2}\right)^2} \\ \frac{1}{-\frac{\sqrt{2}}{2} - \frac{I\sqrt{2}}{2}} \\ 1 \end{bmatrix}$$

- Use Euler identity to write solution in terms of sin and cos

$$e^{-\frac{\sqrt{2}x}{2}} \cdot \left(\cos\left(\frac{\sqrt{2}x}{2}\right) - I \sin\left(\frac{\sqrt{2}x}{2}\right) \right) \cdot \begin{bmatrix} \frac{1}{\left(-\frac{\sqrt{2}}{2} - \frac{I\sqrt{2}}{2}\right)^3} \\ \frac{1}{\left(-\frac{\sqrt{2}}{2} - \frac{I\sqrt{2}}{2}\right)^2} \\ \frac{1}{-\frac{\sqrt{2}}{2} - \frac{I\sqrt{2}}{2}} \\ 1 \end{bmatrix}$$

- Simplify expression

$$e^{-\frac{\sqrt{2}x}{2}} \cdot \begin{bmatrix} \frac{\cos\left(\frac{\sqrt{2}x}{2}\right) - I \sin\left(\frac{\sqrt{2}x}{2}\right)}{\left(-\frac{\sqrt{2}}{2} - \frac{I\sqrt{2}}{2}\right)^3} \\ \frac{\cos\left(\frac{\sqrt{2}x}{2}\right) - I \sin\left(\frac{\sqrt{2}x}{2}\right)}{\left(-\frac{\sqrt{2}}{2} - \frac{I\sqrt{2}}{2}\right)^2} \\ \frac{\cos\left(\frac{\sqrt{2}x}{2}\right) - I \sin\left(\frac{\sqrt{2}x}{2}\right)}{-\frac{\sqrt{2}}{2} - \frac{I\sqrt{2}}{2}} \\ \cos\left(\frac{\sqrt{2}x}{2}\right) - I \sin\left(\frac{\sqrt{2}x}{2}\right) \end{bmatrix}$$

- Both real and imaginary parts are solutions to the homogeneous system

$$\vec{y}_1(x) = e^{-\frac{\sqrt{2}x}{2}} \cdot \begin{bmatrix} \frac{\cos\left(\frac{\sqrt{2}x}{2}\right)\sqrt{2}}{2} + \frac{\sin\left(\frac{\sqrt{2}x}{2}\right)\sqrt{2}}{2} \\ -\sin\left(\frac{\sqrt{2}x}{2}\right) \\ -\frac{\cos\left(\frac{\sqrt{2}x}{2}\right)\sqrt{2}}{2} + \frac{\sin\left(\frac{\sqrt{2}x}{2}\right)\sqrt{2}}{2} \\ \cos\left(\frac{\sqrt{2}x}{2}\right) \end{bmatrix}, \vec{y}_2(x) = e^{-\frac{\sqrt{2}x}{2}} \cdot \begin{bmatrix} \frac{\cos\left(\frac{\sqrt{2}x}{2}\right)\sqrt{2}}{2} - \frac{\sin\left(\frac{\sqrt{2}x}{2}\right)\sqrt{2}}{2} \\ -\cos\left(\frac{\sqrt{2}x}{2}\right) \\ \frac{\cos\left(\frac{\sqrt{2}x}{2}\right)\sqrt{2}}{2} + \frac{\sin\left(\frac{\sqrt{2}x}{2}\right)\sqrt{2}}{2} \\ -\sin\left(\frac{\sqrt{2}x}{2}\right) \end{bmatrix}$$

- Consider complex eigenpair, complex conjugate eigenvalue can be ignored

$$\begin{bmatrix} \frac{\sqrt{2}}{2} - \frac{I\sqrt{2}}{2}, \\ \frac{1}{\left(\frac{\sqrt{2}}{2} - \frac{I\sqrt{2}}{2}\right)^3} \\ \frac{1}{\left(\frac{\sqrt{2}}{2} - \frac{I\sqrt{2}}{2}\right)^2} \\ \frac{1}{\frac{\sqrt{2}}{2} - \frac{I\sqrt{2}}{2}} \\ 1 \end{bmatrix}$$

- Solution from eigenpair

$$e^{\left(\frac{\sqrt{2}}{2} - \frac{I\sqrt{2}}{2}\right)x} \cdot \begin{bmatrix} \frac{1}{\left(\frac{\sqrt{2}}{2} - \frac{I\sqrt{2}}{2}\right)^3} \\ \frac{1}{\left(\frac{\sqrt{2}}{2} - \frac{I\sqrt{2}}{2}\right)^2} \\ \frac{1}{\frac{\sqrt{2}}{2} - \frac{I\sqrt{2}}{2}} \\ 1 \end{bmatrix}$$

- Use Euler identity to write solution in terms of sin and cos

$$e^{\frac{\sqrt{2}x}{2}} \cdot \left(\cos\left(\frac{\sqrt{2}x}{2}\right) - I \sin\left(\frac{\sqrt{2}x}{2}\right) \right) \cdot \begin{bmatrix} \frac{1}{\left(\frac{\sqrt{2}}{2} - \frac{I\sqrt{2}}{2}\right)^3} \\ \frac{1}{\left(\frac{\sqrt{2}}{2} - \frac{I\sqrt{2}}{2}\right)^2} \\ \frac{1}{\frac{\sqrt{2}}{2} - \frac{I\sqrt{2}}{2}} \\ 1 \end{bmatrix}$$

- Simplify expression

$$e^{\frac{\sqrt{2}x}{2}} \cdot \begin{bmatrix} \frac{\cos\left(\frac{\sqrt{2}x}{2}\right) - \mathbf{I} \sin\left(\frac{\sqrt{2}x}{2}\right)}{\left(\frac{\sqrt{2}}{2} - \mathbf{I}\frac{\sqrt{2}}{2}\right)^3} \\ \frac{\cos\left(\frac{\sqrt{2}x}{2}\right) - \mathbf{I} \sin\left(\frac{\sqrt{2}x}{2}\right)}{\left(\frac{\sqrt{2}}{2} - \mathbf{I}\frac{\sqrt{2}}{2}\right)^2} \\ \frac{\cos\left(\frac{\sqrt{2}x}{2}\right) - \mathbf{I} \sin\left(\frac{\sqrt{2}x}{2}\right)}{\frac{\sqrt{2}}{2} - \mathbf{I}\frac{\sqrt{2}}{2}} \\ \cos\left(\frac{\sqrt{2}x}{2}\right) - \mathbf{I} \sin\left(\frac{\sqrt{2}x}{2}\right) \end{bmatrix}$$

- Both real and imaginary parts are solutions to the homogeneous system

$$\vec{y}_3(x) = e^{\frac{\sqrt{2}x}{2}} \cdot \begin{bmatrix} -\frac{\cos\left(\frac{\sqrt{2}x}{2}\right)\sqrt{2}}{2} + \frac{\sin\left(\frac{\sqrt{2}x}{2}\right)\sqrt{2}}{2} \\ \sin\left(\frac{\sqrt{2}x}{2}\right) \\ \frac{\cos\left(\frac{\sqrt{2}x}{2}\right)\sqrt{2}}{2} + \frac{\sin\left(\frac{\sqrt{2}x}{2}\right)\sqrt{2}}{2} \\ \cos\left(\frac{\sqrt{2}x}{2}\right) \end{bmatrix}, \vec{y}_4(x) = e^{\frac{\sqrt{2}x}{2}} \cdot \begin{bmatrix} \frac{\cos\left(\frac{\sqrt{2}x}{2}\right)\sqrt{2}}{2} + \frac{\sin\left(\frac{\sqrt{2}x}{2}\right)\sqrt{2}}{2} \\ \cos\left(\frac{\sqrt{2}x}{2}\right) \\ \frac{\cos\left(\frac{\sqrt{2}x}{2}\right)\sqrt{2}}{2} - \frac{\sin\left(\frac{\sqrt{2}x}{2}\right)\sqrt{2}}{2} \\ -\sin\left(\frac{\sqrt{2}x}{2}\right) \end{bmatrix}$$

- General solution to the system of ODEs

$$\vec{y} = c_1 \vec{y}_1(x) + c_2 \vec{y}_2(x) + c_3 \vec{y}_3(x) + c_4 \vec{y}_4(x)$$

- Substitute solutions into the general solution

$$\vec{y} = c_1 e^{-\frac{\sqrt{2}x}{2}} \cdot \begin{bmatrix} \frac{\cos\left(\frac{\sqrt{2}x}{2}\right)\sqrt{2}}{2} + \frac{\sin\left(\frac{\sqrt{2}x}{2}\right)\sqrt{2}}{2} \\ -\sin\left(\frac{\sqrt{2}x}{2}\right) \\ -\frac{\cos\left(\frac{\sqrt{2}x}{2}\right)\sqrt{2}}{2} + \frac{\sin\left(\frac{\sqrt{2}x}{2}\right)\sqrt{2}}{2} \\ \cos\left(\frac{\sqrt{2}x}{2}\right) \end{bmatrix} + c_2 e^{-\frac{\sqrt{2}x}{2}} \cdot \begin{bmatrix} \frac{\cos\left(\frac{\sqrt{2}x}{2}\right)\sqrt{2}}{2} - \frac{\sin\left(\frac{\sqrt{2}x}{2}\right)\sqrt{2}}{2} \\ -\cos\left(\frac{\sqrt{2}x}{2}\right) \\ \frac{\cos\left(\frac{\sqrt{2}x}{2}\right)\sqrt{2}}{2} + \frac{\sin\left(\frac{\sqrt{2}x}{2}\right)\sqrt{2}}{2} \\ -\sin\left(\frac{\sqrt{2}x}{2}\right) \end{bmatrix} + c_3 e^{\frac{\sqrt{2}x}{2}}$$

- First component of the vector is the solution to the ODE

$$y = \frac{\sqrt{2} \left(\left((c_1 + c_2)e^{-\frac{\sqrt{2}x}{2}} - e^{\frac{\sqrt{2}x}{2}}(c_3 - c_4) \right) \cos\left(\frac{\sqrt{2}x}{2}\right) + \left((c_1 - c_2)e^{-\frac{\sqrt{2}x}{2}} + e^{\frac{\sqrt{2}x}{2}}(c_3 + c_4) \right) \sin\left(\frac{\sqrt{2}x}{2}\right) \right)}{2}$$

Maple trace

```
`Methods for high order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
<- constant coefficients successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 61

```
dsolve(diff(y(x),x$4)+y(x)=0,y(x), singsol=all)
```

$$y(x) = \left(-c_1 e^{-\frac{x\sqrt{2}}{2}} - c_2 e^{\frac{x\sqrt{2}}{2}}\right) \sin\left(\frac{x\sqrt{2}}{2}\right) + \left(c_3 e^{-\frac{x\sqrt{2}}{2}} + c_4 e^{\frac{x\sqrt{2}}{2}}\right) \cos\left(\frac{x\sqrt{2}}{2}\right)$$

✓ Solution by Mathematica

Time used: 0.003 (sec). Leaf size: 65

```
DSolve[y''''[x]+y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^{-\frac{x}{\sqrt{2}}} \left((c_1 e^{\sqrt{2}x} + c_2) \cos\left(\frac{x}{\sqrt{2}}\right) + (c_4 e^{\sqrt{2}x} + c_3) \sin\left(\frac{x}{\sqrt{2}}\right) \right)$$

10.24 problem 24

10.24.1 Maple step by step solution 2054

Internal problem ID [11754]

Internal file name [OUTPUT/11763_Thursday_April_11_2024_08_49_26_PM_9690685/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 24.

ODE order: 5.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

`[[_high_order , _quadrature]]`

$$y^{(5)} = 0$$

The characteristic equation is

$$\lambda^5 = 0$$

The roots of the above equation are

$$\lambda_1 = 0$$

$$\lambda_2 = 0$$

$$\lambda_3 = 0$$

$$\lambda_4 = 0$$

$$\lambda_5 = 0$$

Therefore the homogeneous solution is

$$y_h(x) = c_5x^4 + c_4x^3 + c_3x^2 + c_2x + c_1$$

The fundamental set of solutions for the homogeneous solution are the following

$$y_1 = 1$$

$$y_2 = x$$

$$y_3 = x^2$$

$$y_4 = x^3$$

$$y_5 = x^4$$

Summary

The solution(s) found are the following

$$y = c_5x^4 + c_4x^3 + c_3x^2 + c_2x + c_1 \quad (1)$$

Verification of solutions

$$y = c_5x^4 + c_4x^3 + c_3x^2 + c_2x + c_1$$

Verified OK.

10.24.1 Maple step by step solution

Let's solve

$$y^{(5)} = 0$$

- Highest derivative means the order of the ODE is 5
- Convert linear ODE into a system of first order ODEs
 - Define new variable $y_1(x)$
$$y_1(x) = y$$
 - Define new variable $y_2(x)$
$$y_2(x) = y'$$
 - Define new variable $y_3(x)$
$$y_3(x) = y''$$
 - Define new variable $y_4(x)$
$$y_4(x) = y'''$$
 - Define new variable $y_5(x)$
$$y_5(x) = y''''$$

- Isolate for $y'_5(x)$ using original ODE

$$y'_5(x) = 0$$

Convert linear ODE into a system of first order ODEs

$$[y_2(x) = y'_1(x), y_3(x) = y'_2(x), y_4(x) = y'_3(x), y_5(x) = y'_4(x), y'_5(x) = 0]$$

- Define vector

$$\vec{y}(x) = \begin{bmatrix} y_1(x) \\ y_2(x) \\ y_3(x) \\ y_4(x) \\ y_5(x) \end{bmatrix}$$

- System to solve

$$\vec{y}'(x) = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \cdot \vec{y}(x)$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

- Rewrite the system as

$$\vec{y}'(x) = A \cdot \vec{y}(x)$$

- To solve the system, find the eigenvalues and eigenvectors of A
- Eigenpairs of A

$$\left[\begin{array}{c} \left[\begin{array}{c} 1 \\ 0 \\ 0 \\ 0 \end{array} \right] \\ 0, \end{array} \right], \left[\begin{array}{c} \left[\begin{array}{c} 0 \\ 0 \\ 0 \\ 0 \end{array} \right] \\ 0, \end{array} \right], \left[\begin{array}{c} \left[\begin{array}{c} 0 \\ 0 \\ 0 \\ 0 \end{array} \right] \\ 0, \end{array} \right], \left[\begin{array}{c} \left[\begin{array}{c} 0 \\ 0 \\ 0 \\ 0 \end{array} \right] \\ 0, \end{array} \right], \left[\begin{array}{c} \left[\begin{array}{c} 0 \\ 0 \\ 0 \\ 0 \end{array} \right] \\ 0, \end{array} \right]$$

- Consider eigenpair

$$\left[\begin{array}{c} \left[\begin{array}{c} 1 \\ 0 \\ 0 \\ 0 \end{array} \right] \\ 0, \end{array} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

- Consider eigenpair

$$\left[\begin{array}{c} \left[\begin{array}{c} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{array} \right] \\ 0, \end{array} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_2 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

- Consider eigenpair

$$\left[0, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_3 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

- Consider eigenpair

$$\left[0, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_4 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

- Consider eigenpair

$$\left[0, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_5 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

- General solution to the system of ODEs

$$\vec{y} = c_1 \vec{y}_1 + c_2 \vec{y}_2 + c_3 \vec{y}_3 + c_4 \vec{y}_4 + c_5 \vec{y}_5$$

- Substitute solutions into the general solution

$$\vec{y} = \begin{bmatrix} c_1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y = c_1$$

Maple trace

```
`Methods for high order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
<- quadrature successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 27

```
dsolve(diff(y(x),x$5)=0,y(x), singsol=all)
```

$$y(x) = \frac{1}{24}x^4c_1 + \frac{1}{6}c_2x^3 + \frac{1}{2}c_3x^2 + c_4x + c_5$$

✓ Solution by Mathematica

Time used: 0.002 (sec). Leaf size: 27

```
DSolve[y'''''[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow x(x(x(c_5x + c_4) + c_3) + c_2) + c_1$$

10.25 problem 25

10.25.1 Existence and uniqueness analysis	2060
10.25.2 Solving as second order linear constant coeff ode	2061
10.25.3 Solving using Kovacic algorithm	2063
10.25.4 Maple step by step solution	2067

Internal problem ID [11755]

Internal file name [OUTPUT/11764_Thursday_April_11_2024_08_49_27_PM_74442270/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 25.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _missing_x]]
```

$$y'' - y' - 12y = 0$$

With initial conditions

$$[y(0) = 3, y'(0) = 5]$$

10.25.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$p(x) = -1$$

$$q(x) = -12$$

$$F = 0$$

Hence the ode is

$$y'' - y' - 12y = 0$$

The domain of $p(x) = -1$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = -12$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

10.25.2 Solving as second order linear constant coeff ode

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = -1, C = -12$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} - \lambda e^{\lambda x} - 12 e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 - \lambda - 12 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = -1, C = -12$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{1}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{-1^2 - (4)(1)(-12)} \\ &= \frac{1}{2} \pm \frac{7}{2} \end{aligned}$$

Hence

$$\lambda_1 = \frac{1}{2} + \frac{7}{2}$$

$$\lambda_2 = \frac{1}{2} - \frac{7}{2}$$

Which simplifies to

$$\lambda_1 = 4$$

$$\lambda_2 = -3$$

Since roots are real and distinct, then the solution is

$$y = c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x}$$

$$y = c_1 e^{(4)x} + c_2 e^{(-3)x}$$

Or

$$y = c_1 e^{4x} + c_2 e^{-3x}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{4x} + c_2 e^{-3x} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 3$ and $x = 0$ in the above gives

$$3 = c_1 + c_2 \quad (1A)$$

Taking derivative of the solution gives

$$y' = 4c_1 e^{4x} - 3c_2 e^{-3x}$$

substituting $y' = 5$ and $x = 0$ in the above gives

$$5 = 4c_1 - 3c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 2$$

$$c_2 = 1$$

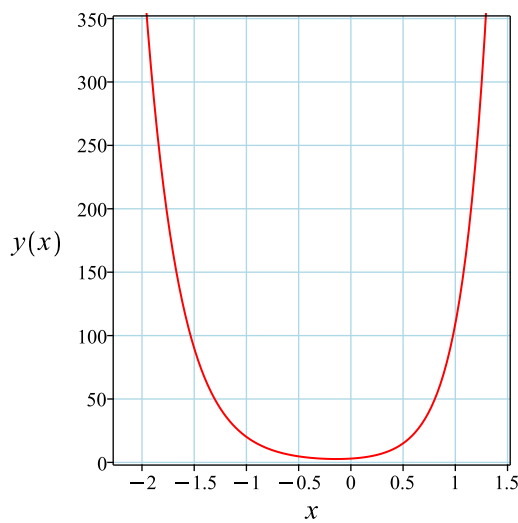
Substituting these values back in above solution results in

$$y = 2e^{4x} + e^{-3x}$$

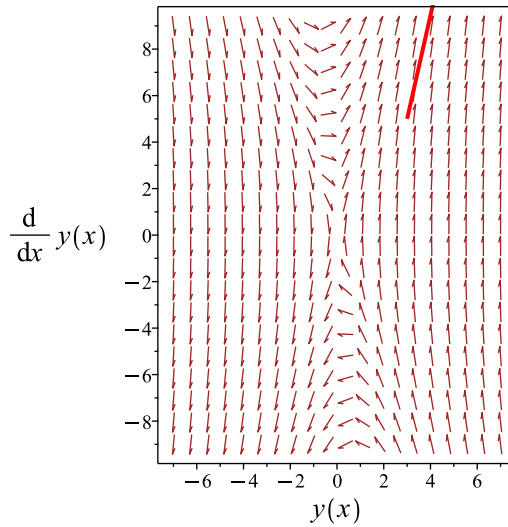
Summary

The solution(s) found are the following

$$y = 2e^{4x} + e^{-3x} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = 2e^{4x} + e^{-3x}$$

Verified OK.

10.25.3 Solving using Kovacic algorithm

Writing the ode as

$$y'' - y' - 12y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$A = 1$$

$$B = -1 \quad (3)$$

$$C = -12$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{49}{4} \tag{6}$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 49 \\ t &= 4 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = \frac{49z(x)}{4} \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 311: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = \frac{49}{4}$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = e^{-\frac{7x}{2}}$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-1}{1} dx} \\ &= z_1 e^{\frac{x}{2}} \\ &= z_1 (e^{\frac{x}{2}}) \end{aligned}$$

Which simplifies to

$$y_1 = e^{-3x}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{-1}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^x}{(y_1)^2} dx \\ &= y_1 \left(\frac{e^{7x}}{7} \right) \end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (e^{-3x}) + c_2 \left(e^{-3x} \left(\frac{e^{7x}}{7} \right) \right)\end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{-3x} + \frac{c_2 e^{4x}}{7} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 3$ and $x = 0$ in the above gives

$$3 = c_1 + \frac{c_2}{7} \quad (1A)$$

Taking derivative of the solution gives

$$y' = -3c_1 e^{-3x} + \frac{4c_2 e^{4x}}{7}$$

substituting $y' = 5$ and $x = 0$ in the above gives

$$5 = -3c_1 + \frac{4c_2}{7} \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 1$$

$$c_2 = 14$$

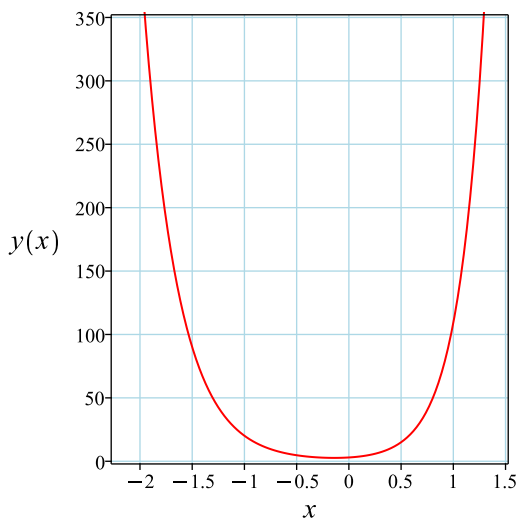
Substituting these values back in above solution results in

$$y = 2e^{4x} + e^{-3x}$$

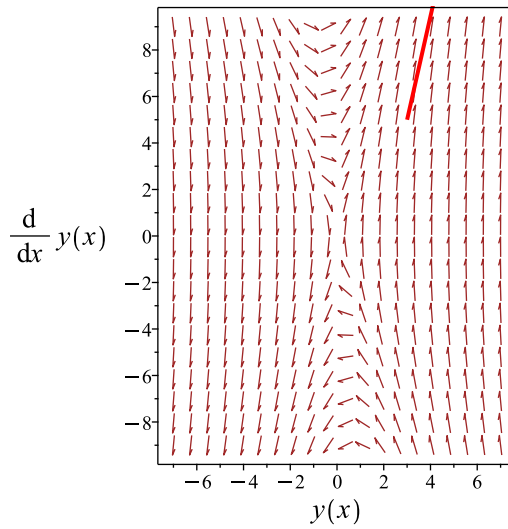
Summary

The solution(s) found are the following

$$y = 2e^{4x} + e^{-3x} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = 2e^{4x} + e^{-3x}$$

Verified OK.

10.25.4 Maple step by step solution

Let's solve

$$\left[y'' - y' - 12y = 0, y(0) = 3, y'|_{\{x=0\}} = 5 \right]$$

- Highest derivative means the order of the ODE is 2
- y''
- Characteristic polynomial of ODE

$$r^2 - r - 12 = 0$$
- Factor the characteristic polynomial

$$(r + 3)(r - 4) = 0$$
- Roots of the characteristic polynomial

$$r = (-3, 4)$$
- 1st solution of the ODE

$$y_1(x) = e^{-3x}$$

- 2nd solution of the ODE

$$y_2(x) = e^{4x}$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x)$$

- Substitute in solutions

$$y = c_1 e^{-3x} + c_2 e^{4x}$$

- Check validity of solution $y = c_1 e^{-3x} + c_2 e^{4x}$

- Use initial condition $y(0) = 3$

$$3 = c_1 + c_2$$

- Compute derivative of the solution

$$y' = -3c_1 e^{-3x} + 4c_2 e^{4x}$$

- Use the initial condition $y' \Big|_{\{x=0\}} = 5$

$$5 = -3c_1 + 4c_2$$

- Solve for c_1 and c_2

$$\{c_1 = 1, c_2 = 2\}$$

- Substitute constant values into general solution and simplify

$$y = (2e^{7x} + 1)e^{-3x}$$

- Solution to the IVP

$$y = (2e^{7x} + 1)e^{-3x}$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 15

```
dsolve([diff(y(x),x$2)-diff(y(x),x)-12*y(x)=0,y(0) = 3, D(y)(0) = 5],y(x), singsol=all)
```

$$y(x) = (2e^{7x} + 1)e^{-3x}$$

✓ Solution by Mathematica

Time used: 0.012 (sec). Leaf size: 18

```
DSolve[{y''[x]-y'[x]-12*y[x]==0,{y[0]==3,y'[0]==5}},y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^{-3x} + 2e^{4x}$$

10.26 problem 26

10.26.1 Existence and uniqueness analysis	2070
10.26.2 Solving as second order linear constant coeff ode	2071
10.26.3 Solving using Kovacic algorithm	2073
10.26.4 Maple step by step solution	2077

Internal problem ID [11756]

Internal file name [OUTPUT/11765_Thursday_April_11_2024_08_49_27_PM_74205676/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 26.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _missing_x]]
```

$$y'' + 7y' + 10y = 0$$

With initial conditions

$$[y(0) = -4, y'(0) = 2]$$

10.26.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$p(x) = 7$$

$$q(x) = 10$$

$$F = 0$$

Hence the ode is

$$y'' + 7y' + 10y = 0$$

The domain of $p(x) = 7$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = 10$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

10.26.2 Solving as second order linear constant coeff ode

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 7, C = 10$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + 7\lambda e^{\lambda x} + 10e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 7\lambda + 10 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 7, C = 10$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{-7}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{7^2 - (4)(1)(10)} \\ &= -\frac{7}{2} \pm \frac{3}{2} \end{aligned}$$

Hence

$$\lambda_1 = -\frac{7}{2} + \frac{3}{2}$$

$$\lambda_2 = -\frac{7}{2} - \frac{3}{2}$$

Which simplifies to

$$\lambda_1 = -2$$

$$\lambda_2 = -5$$

Since roots are real and distinct, then the solution is

$$y = c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x}$$

$$y = c_1 e^{(-2)x} + c_2 e^{(-5)x}$$

Or

$$y = c_1 e^{-2x} + c_2 e^{-5x}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{-2x} + c_2 e^{-5x} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = -4$ and $x = 0$ in the above gives

$$-4 = c_1 + c_2 \quad (1A)$$

Taking derivative of the solution gives

$$y' = -2c_1 e^{-2x} - 5c_2 e^{-5x}$$

substituting $y' = 2$ and $x = 0$ in the above gives

$$2 = -2c_1 - 5c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = -6$$

$$c_2 = 2$$

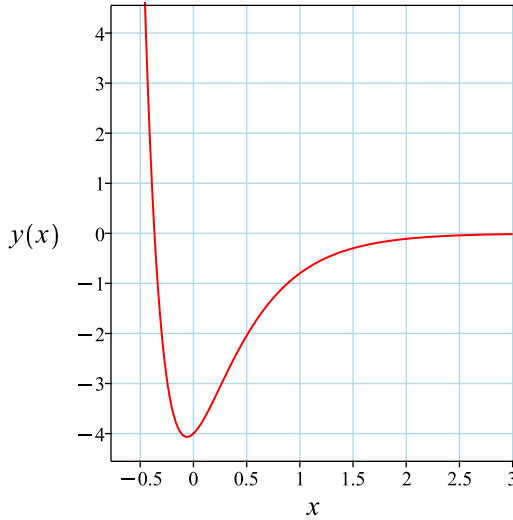
Substituting these values back in above solution results in

$$y = 2 e^{-5x} - 6 e^{-2x}$$

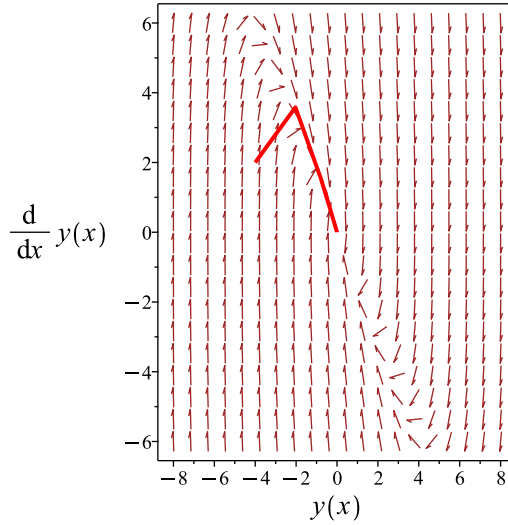
Summary

The solution(s) found are the following

$$y = 2e^{-5x} - 6e^{-2x} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = 2e^{-5x} - 6e^{-2x}$$

Verified OK.

10.26.3 Solving using Kovacic algorithm

Writing the ode as

$$y'' + 7y' + 10y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$A = 1$$

$$B = 7 \quad (3)$$

$$C = 10$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{9}{4} \tag{6}$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 9 \\ t &= 4 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = \frac{9z(x)}{4} \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 313: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = \frac{9}{4}$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = e^{-\frac{3x}{2}}$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{7}{1} dx} \\ &= z_1 e^{-\frac{7x}{2}} \\ &= z_1 \left(e^{-\frac{7x}{2}} \right) \end{aligned}$$

Which simplifies to

$$y_1 = e^{-5x}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{7}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{-7x}}{(y_1)^2} dx \\ &= y_1 \left(\frac{e^{3x}}{3} \right) \end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (e^{-5x}) + c_2 \left(e^{-5x} \left(\frac{e^{3x}}{3} \right) \right)\end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{-5x} + \frac{c_2 e^{-2x}}{3} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = -4$ and $x = 0$ in the above gives

$$-4 = c_1 + \frac{c_2}{3} \quad (1A)$$

Taking derivative of the solution gives

$$y' = -5c_1 e^{-5x} - \frac{2c_2 e^{-2x}}{3}$$

substituting $y' = 2$ and $x = 0$ in the above gives

$$2 = -5c_1 - \frac{2c_2}{3} \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 2$$

$$c_2 = -18$$

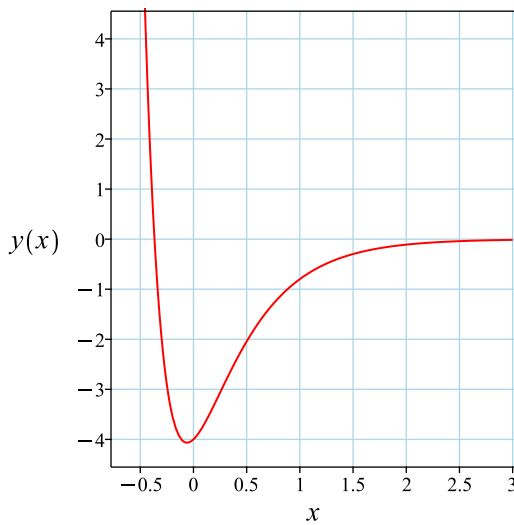
Substituting these values back in above solution results in

$$y = 2e^{-5x} - 6e^{-2x}$$

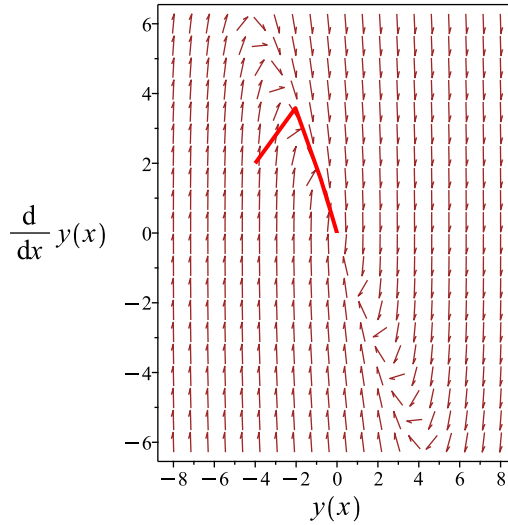
Summary

The solution(s) found are the following

$$y = 2e^{-5x} - 6e^{-2x} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = 2e^{-5x} - 6e^{-2x}$$

Verified OK.

10.26.4 Maple step by step solution

Let's solve

$$\left[y'' + 7y' + 10y = 0, y(0) = -4, y'|_{\{x=0\}} = 2 \right]$$

- Highest derivative means the order of the ODE is 2
 y''
- Characteristic polynomial of ODE
 $r^2 + 7r + 10 = 0$
- Factor the characteristic polynomial
 $(r + 5)(r + 2) = 0$
- Roots of the characteristic polynomial
 $r = (-5, -2)$
- 1st solution of the ODE

$$y_1(x) = e^{-5x}$$

- 2nd solution of the ODE

$$y_2(x) = e^{-2x}$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x)$$

- Substitute in solutions

$$y = c_1 e^{-5x} + c_2 e^{-2x}$$

- Check validity of solution $y = c_1 e^{-5x} + c_2 e^{-2x}$

- Use initial condition $y(0) = -4$

$$-4 = c_1 + c_2$$

- Compute derivative of the solution

$$y' = -5c_1 e^{-5x} - 2c_2 e^{-2x}$$

- Use the initial condition $y' \Big|_{\{x=0\}} = 2$

$$2 = -5c_1 - 2c_2$$

- Solve for c_1 and c_2

$$\{c_1 = 2, c_2 = -6\}$$

- Substitute constant values into general solution and simplify

$$y = 2 e^{-5x} - 6 e^{-2x}$$

- Solution to the IVP

$$y = 2 e^{-5x} - 6 e^{-2x}$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 17

```
dsolve([diff(y(x),x$2)+7*diff(y(x),x)+10*y(x)=0,y(0) = -4, D(y)(0) = 2],y(x), singsol=all)
```

$$y(x) = 2e^{-5x} - 6e^{-2x}$$

✓ Solution by Mathematica

Time used: 0.013 (sec). Leaf size: 20

```
DSolve[{y''[x]+7*y'[x]+10*y[x]==0,{y[0]==-4,y'[0]==2}},y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^{-5x}(2 - 6e^{3x})$$

10.27 problem 27

10.27.1 Existence and uniqueness analysis	2080
10.27.2 Solving as second order linear constant coeff ode	2081
10.27.3 Solving using Kovacic algorithm	2083
10.27.4 Maple step by step solution	2087

Internal problem ID [11757]

Internal file name [OUTPUT/11766_Thursday_April_11_2024_08_49_28_PM_72234192/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 27.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _missing_x]]
```

$$y'' - 6y' + 8y = 0$$

With initial conditions

$$[y(0) = 1, y'(0) = 6]$$

10.27.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$p(x) = -6$$

$$q(x) = 8$$

$$F = 0$$

Hence the ode is

$$y'' - 6y' + 8y = 0$$

The domain of $p(x) = -6$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = 8$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

10.27.2 Solving as second order linear constant coeff ode

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = -6, C = 8$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} - 6\lambda e^{\lambda x} + 8 e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 - 6\lambda + 8 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = -6, C = 8$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{6}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{-6^2 - (4)(1)(8)} \\ &= 3 \pm 1 \end{aligned}$$

Hence

$$\lambda_1 = 3 + 1$$

$$\lambda_2 = 3 - 1$$

Which simplifies to

$$\lambda_1 = 4$$

$$\lambda_2 = 2$$

Since roots are real and distinct, then the solution is

$$y = c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x}$$

$$y = c_1 e^{(4)x} + c_2 e^{(2)x}$$

Or

$$y = c_1 e^{4x} + c_2 e^{2x}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{4x} + c_2 e^{2x} \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 1$ and $x = 0$ in the above gives

$$1 = c_1 + c_2 \tag{1A}$$

Taking derivative of the solution gives

$$y' = 4c_1 e^{4x} + 2c_2 e^{2x}$$

substituting $y' = 6$ and $x = 0$ in the above gives

$$6 = 4c_1 + 2c_2 \tag{2A}$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 2$$

$$c_2 = -1$$

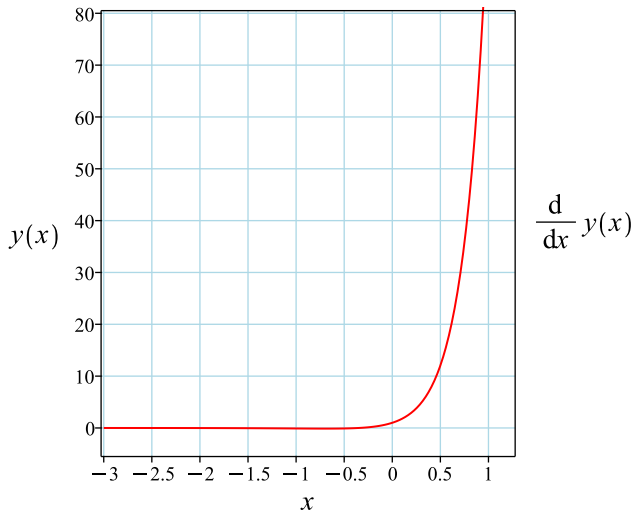
Substituting these values back in above solution results in

$$y = 2e^{4x} - e^{2x}$$

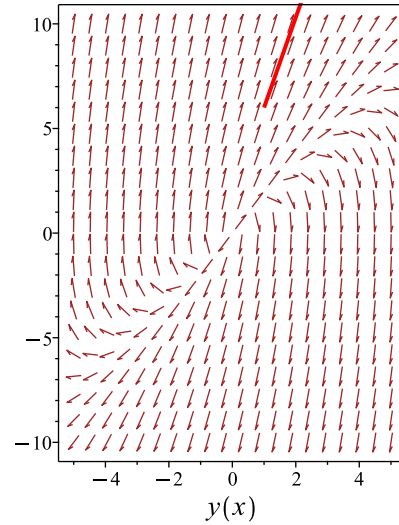
Summary

The solution(s) found are the following

$$y = 2e^{4x} - e^{2x} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = 2e^{4x} - e^{2x}$$

Verified OK.

10.27.3 Solving using Kovacic algorithm

Writing the ode as

$$y'' - 6y' + 8y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= -6 \\ C &= 8 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$r = \frac{s}{t} = \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{1}{1} \tag{6}$$

Comparing the above to (5) shows that

$$s = 1 \\ t = 1$$

Therefore eq. (4) becomes

$$z''(x) = z(x) \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 315: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = 1$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = e^{-x}$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-6}{1} dx} \\ &= z_1 e^{3x} \\ &= z_1 (e^{3x}) \end{aligned}$$

Which simplifies to

$$y_1 = e^{2x}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{-6}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{6x}}{(y_1)^2} dx \\ &= y_1 \left(\frac{e^{2x}}{2} \right) \end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (e^{2x}) + c_2 \left(e^{2x} \left(\frac{e^{2x}}{2} \right) \right)\end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{2x} + \frac{c_2 e^{4x}}{2} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 1$ and $x = 0$ in the above gives

$$1 = c_1 + \frac{c_2}{2} \quad (1A)$$

Taking derivative of the solution gives

$$y' = 2c_1 e^{2x} + 2c_2 e^{4x}$$

substituting $y' = 6$ and $x = 0$ in the above gives

$$6 = 2c_1 + 2c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = -1$$

$$c_2 = 4$$

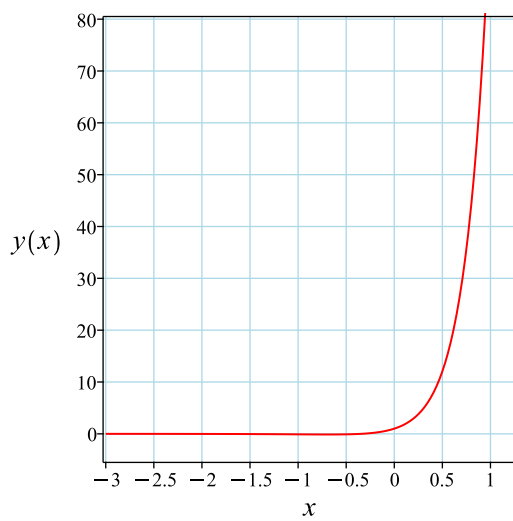
Substituting these values back in above solution results in

$$y = 2e^{4x} - e^{2x}$$

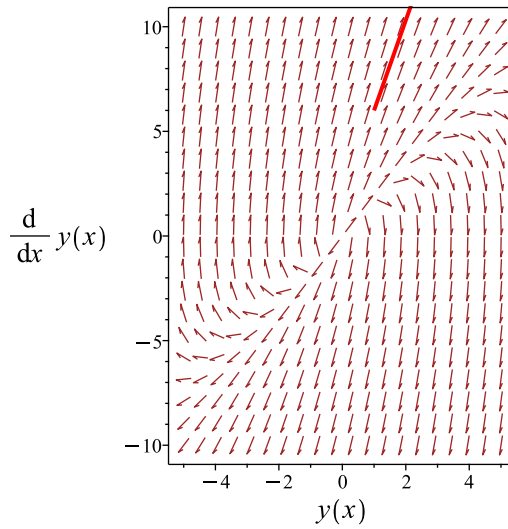
Summary

The solution(s) found are the following

$$y = 2e^{4x} - e^{2x} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = 2e^{4x} - e^{2x}$$

Verified OK.

10.27.4 Maple step by step solution

Let's solve

$$\left[y'' - 6y' + 8y = 0, y(0) = 1, y'|_{\{x=0\}} = 6 \right]$$

- Highest derivative means the order of the ODE is 2
- y''
- Characteristic polynomial of ODE

$$r^2 - 6r + 8 = 0$$
- Factor the characteristic polynomial

$$(r - 2)(r - 4) = 0$$
- Roots of the characteristic polynomial

$$r = (2, 4)$$
- 1st solution of the ODE

$$y_1(x) = e^{2x}$$

- 2nd solution of the ODE

$$y_2(x) = e^{4x}$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x)$$

- Substitute in solutions

$$y = c_1 e^{2x} + c_2 e^{4x}$$

- Check validity of solution $y = c_1 e^{2x} + c_2 e^{4x}$

- Use initial condition $y(0) = 1$

$$1 = c_1 + c_2$$

- Compute derivative of the solution

$$y' = 2c_1 e^{2x} + 4c_2 e^{4x}$$

- Use the initial condition $y' \Big|_{\{x=0\}} = 6$

$$6 = 2c_1 + 4c_2$$

- Solve for c_1 and c_2

$$\{c_1 = -1, c_2 = 2\}$$

- Substitute constant values into general solution and simplify

$$y = 2e^{4x} - e^{2x}$$

- Solution to the IVP

$$y = 2e^{4x} - e^{2x}$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 17

```
dsolve([diff(y(x),x$2)-6*diff(y(x),x)+8*y(x)=0,y(0) = 1, D(y)(0) = 6],y(x), singsol=all)
```

$$y(x) = 2e^{4x} - e^{2x}$$

✓ Solution by Mathematica

Time used: 0.012 (sec). Leaf size: 20

```
DSolve[{y'[x]-6*y'[x]+8*y[x]==0,{y[0]==1,y'[0]==6}},y[x],x,IncludeSingularSolutions -> True
```

$$y(x) \rightarrow e^{2x}(2e^{2x} - 1)$$

10.28 problem 28

10.28.1 Existence and uniqueness analysis	2090
10.28.2 Solving as second order linear constant coeff ode	2091
10.28.3 Solving using Kovacic algorithm	2093
10.28.4 Maple step by step solution	2097

Internal problem ID [11758]

Internal file name [OUTPUT/11767_Thursday_April_11_2024_08_49_28_PM_1544632/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 28.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _missing_x]]
```

$$3y'' + 4y' - 4y = 0$$

With initial conditions

$$[y(0) = 2, y'(0) = -4]$$

10.28.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$p(x) = \frac{4}{3}$$
$$q(x) = -\frac{4}{3}$$
$$F = 0$$

Hence the ode is

$$y'' + \frac{4y'}{3} - \frac{4y}{3} = 0$$

The domain of $p(x) = \frac{4}{3}$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = -\frac{4}{3}$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

10.28.2 Solving as second order linear constant coeff ode

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 3, B = 4, C = -4$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$3\lambda^2 e^{\lambda x} + 4\lambda e^{\lambda x} - 4e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$3\lambda^2 + 4\lambda - 4 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 3, B = 4, C = -4$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{-4}{(2)(3)} \pm \frac{1}{(2)(3)} \sqrt{4^2 - (4)(3)(-4)} \\ &= -\frac{2}{3} \pm \frac{4}{3} \end{aligned}$$

Hence

$$\lambda_1 = -\frac{2}{3} + \frac{4}{3}$$

$$\lambda_2 = -\frac{2}{3} - \frac{4}{3}$$

Which simplifies to

$$\lambda_1 = \frac{2}{3}$$
$$\lambda_2 = -2$$

Since roots are real and distinct, then the solution is

$$y = c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x}$$
$$y = c_1 e^{(\frac{2}{3})x} + c_2 e^{(-2)x}$$

Or

$$y = c_1 e^{\frac{2x}{3}} + c_2 e^{-2x}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{\frac{2x}{3}} + c_2 e^{-2x} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 2$ and $x = 0$ in the above gives

$$2 = c_1 + c_2 \quad (1A)$$

Taking derivative of the solution gives

$$y' = \frac{2c_1 e^{\frac{2x}{3}}}{3} - 2c_2 e^{-2x}$$

substituting $y' = -4$ and $x = 0$ in the above gives

$$-4 = \frac{2c_1}{3} - 2c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 0$$
$$c_2 = 2$$

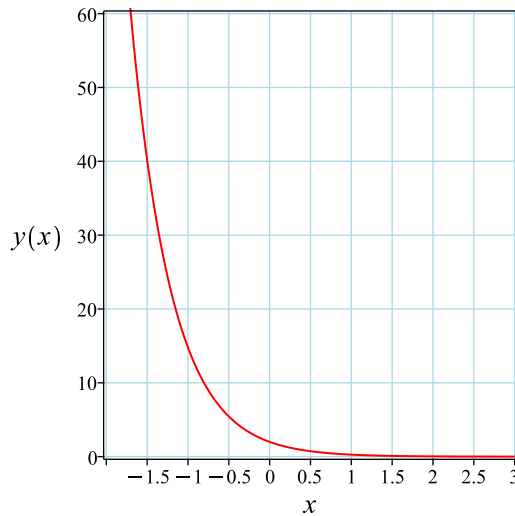
Substituting these values back in above solution results in

$$y = 2 e^{-2x}$$

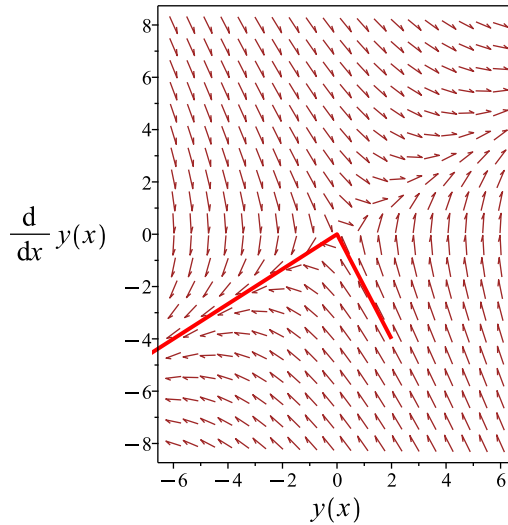
Summary

The solution(s) found are the following

$$y = 2e^{-2x} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = 2e^{-2x}$$

Verified OK.

10.28.3 Solving using Kovacic algorithm

Writing the ode as

$$3y'' + 4y' - 4y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$A = 3$$

$$B = 4 \quad (3)$$

$$C = -4$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{16}{9} \tag{6}$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 16 \\ t &= 9 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = \frac{16z(x)}{9} \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 317: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = \frac{16}{9}$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = e^{-\frac{4x}{3}}$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{4}{3} dx} \\ &= z_1 e^{-\frac{2x}{3}} \\ &= z_1 \left(e^{-\frac{2x}{3}} \right) \end{aligned}$$

Which simplifies to

$$y_1 = e^{-2x}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{4}{3} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{-\frac{4x}{3}}}{(y_1)^2} dx \\ &= y_1 \left(\frac{3 e^{\frac{8x}{3}}}{8} \right) \end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (e^{-2x}) + c_2 \left(e^{-2x} \left(\frac{3e^{\frac{8x}{3}}}{8} \right) \right)\end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{-2x} + \frac{3c_2 e^{\frac{2x}{3}}}{8} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 2$ and $x = 0$ in the above gives

$$2 = c_1 + \frac{3c_2}{8} \quad (1A)$$

Taking derivative of the solution gives

$$y' = -2c_1 e^{-2x} + \frac{c_2 e^{\frac{2x}{3}}}{4}$$

substituting $y' = -4$ and $x = 0$ in the above gives

$$-4 = -2c_1 + \frac{c_2}{4} \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 2$$

$$c_2 = 0$$

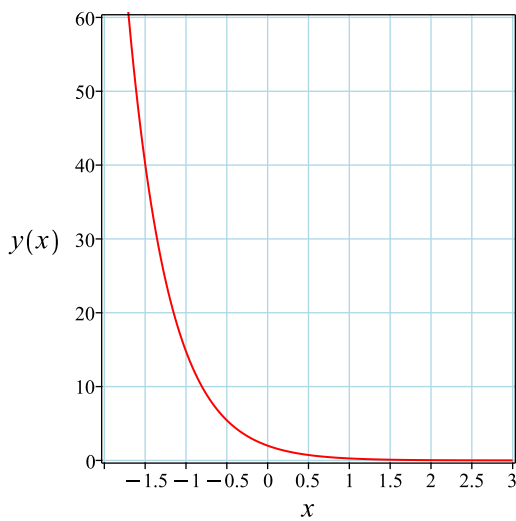
Substituting these values back in above solution results in

$$y = 2e^{-2x}$$

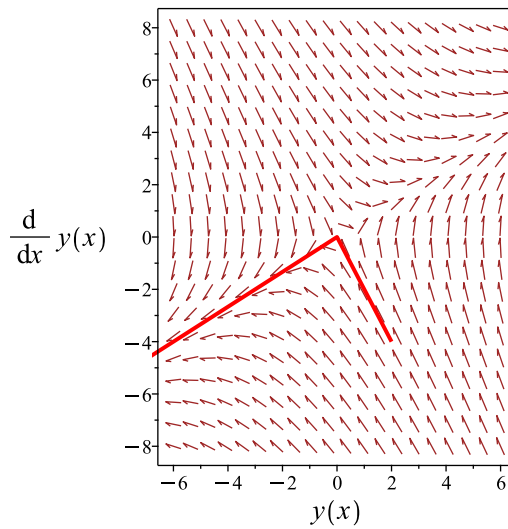
Summary

The solution(s) found are the following

$$y = 2e^{-2x} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = 2e^{-2x}$$

Verified OK.

10.28.4 Maple step by step solution

Let's solve

$$\left[3y'' + 4y' - 4y = 0, y(0) = 2, y'|_{\{x=0\}} = -4 \right]$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = -\frac{4y'}{3} + \frac{4y}{3}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + \frac{4y'}{3} - \frac{4y}{3} = 0$$

- Characteristic polynomial of ODE

$$r^2 + \frac{4}{3}r - \frac{4}{3} = 0$$

- Factor the characteristic polynomial

$$\frac{(r+2)(3r-2)}{3} = 0$$

- Roots of the characteristic polynomial

$$r = \left(-2, \frac{2}{3}\right)$$

- 1st solution of the ODE

$$y_1(x) = e^{-2x}$$

- 2nd solution of the ODE

$$y_2(x) = e^{\frac{2x}{3}}$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x)$$

- Substitute in solutions

$$y = c_1 e^{-2x} + c_2 e^{\frac{2x}{3}}$$

- Check validity of solution $y = c_1 e^{-2x} + c_2 e^{\frac{2x}{3}}$

- Use initial condition $y(0) = 2$

$$2 = c_1 + c_2$$

- Compute derivative of the solution

$$y' = -2c_1 e^{-2x} + \frac{2c_2 e^{\frac{2x}{3}}}{3}$$

- Use the initial condition $y' \Big|_{\{x=0\}} = -4$

$$-4 = -2c_1 + \frac{2c_2}{3}$$

- Solve for c_1 and c_2

$$\{c_1 = 2, c_2 = 0\}$$

- Substitute constant values into general solution and simplify

$$y = 2 e^{-2x}$$

- Solution to the IVP

$$y = 2 e^{-2x}$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
<- constant coefficients successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 10

```
dsolve([3*diff(y(x),x$2)+4*diff(y(x),x)-4*y(x)=0,y(0) = 2, D(y)(0) = -4],y(x), singsol=all)
```

$$y(x) = 2e^{-2x}$$

✓ Solution by Mathematica

Time used: 0.013 (sec). Leaf size: 12

```
DSolve[{3*y'[x]+4*y[x]-4*y[x]==0,{y[0]==2,y'[0]==-4}},y[x],x,IncludeSingularSolutions -> T
```

$$y(x) \rightarrow 2e^{-2x}$$

10.29 problem 29

10.29.1 Existence and uniqueness analysis	2101
10.29.2 Solving as second order linear constant coeff ode	2101
10.29.3 Solving as linear second order ode solved by an integrating factor ode	2103
10.29.4 Solving using Kovacic algorithm	2105
10.29.5 Maple step by step solution	2109

Internal problem ID [11759]

Internal file name [OUTPUT/11768_Thursday_April_11_2024_08_49_29_PM_39302860/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 29.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff", "linear_second_order_ode_solved_by_an_integrating_factor"

Maple gives the following as the ode type

```
[[_2nd_order, _missing_x]]
```

$$y'' + 6y' + 9y = 0$$

With initial conditions

$$[y(0) = 2, y'(0) = -3]$$

10.29.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$p(x) = 6$$

$$q(x) = 9$$

$$F = 0$$

Hence the ode is

$$y'' + 6y' + 9y = 0$$

The domain of $p(x) = 6$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = 9$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

10.29.2 Solving as second order linear constant coeff ode

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 6, C = 9$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + 6\lambda e^{\lambda x} + 9e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 6\lambda + 9 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 6, C = 9$ into the above gives

$$\begin{aligned}\lambda_{1,2} &= \frac{-6}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{(6)^2 - (4)(1)(9)} \\ &= -3\end{aligned}$$

Hence this is the case of a double root $\lambda_{1,2} = 3$. Therefore the solution is

$$y = c_1 e^{-3x} + c_2 x e^{-3x} \quad (1)$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{-3x} + c_2 x e^{-3x} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 2$ and $x = 0$ in the above gives

$$2 = c_1 \quad (1A)$$

Taking derivative of the solution gives

$$y' = -3c_1 e^{-3x} + c_2 e^{-3x} - 3c_2 x e^{-3x}$$

substituting $y' = -3$ and $x = 0$ in the above gives

$$-3 = -3c_1 + c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 2$$

$$c_2 = 3$$

Substituting these values back in above solution results in

$$y = 3x e^{-3x} + 2 e^{-3x}$$

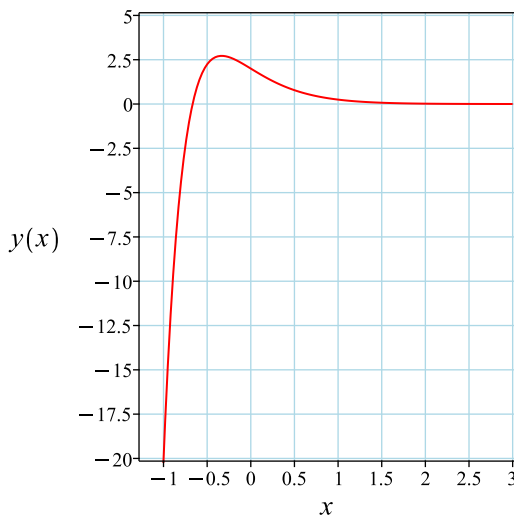
Which simplifies to

$$y = e^{-3x}(3x + 2)$$

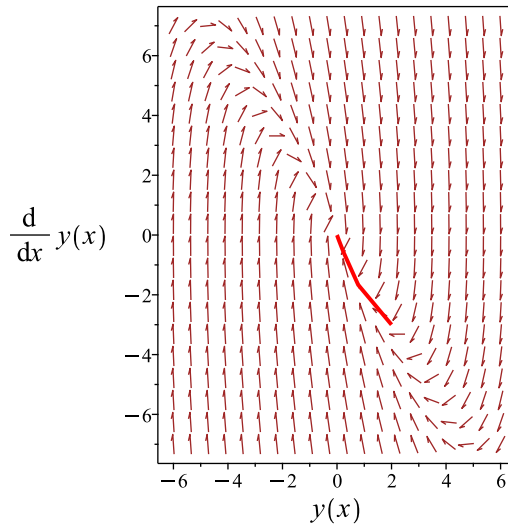
Summary

The solution(s) found are the following

$$y = e^{-3x}(3x + 2) \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = e^{-3x}(3x + 2)$$

Verified OK.

10.29.3 Solving as linear second order ode solved by an integrating factor ode

The ode satisfies this form

$$y'' + p(x)y' + \frac{(p(x)^2 + p'(x))y}{2} = f(x)$$

Where $p(x) = 6$. Therefore, there is an integrating factor given by

$$\begin{aligned} M(x) &= e^{\frac{1}{2} \int p \, dx} \\ &= e^{\int 6 \, dx} \\ &= e^{3x} \end{aligned}$$

Multiplying both sides of the ODE by the integrating factor $M(x)$ makes the left side of the ODE a complete differential

$$\begin{aligned} (M(x)y)'' &= 0 \\ (e^{3x}y)'' &= 0 \end{aligned}$$

Integrating once gives

$$(e^{3x}y)' = c_1$$

Integrating again gives

$$(e^{3x}y) = c_1x + c_2$$

Hence the solution is

$$y = \frac{c_1x + c_2}{e^{3x}}$$

Or

$$y = c_1x e^{-3x} + c_2e^{-3x}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1x e^{-3x} + c_2e^{-3x} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 2$ and $x = 0$ in the above gives

$$2 = c_2 \quad (1A)$$

Taking derivative of the solution gives

$$y' = c_1e^{-3x} - 3c_1x e^{-3x} - 3c_2e^{-3x}$$

substituting $y' = -3$ and $x = 0$ in the above gives

$$-3 = c_1 - 3c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 3$$

$$c_2 = 2$$

Substituting these values back in above solution results in

$$y = 3x e^{-3x} + 2 e^{-3x}$$

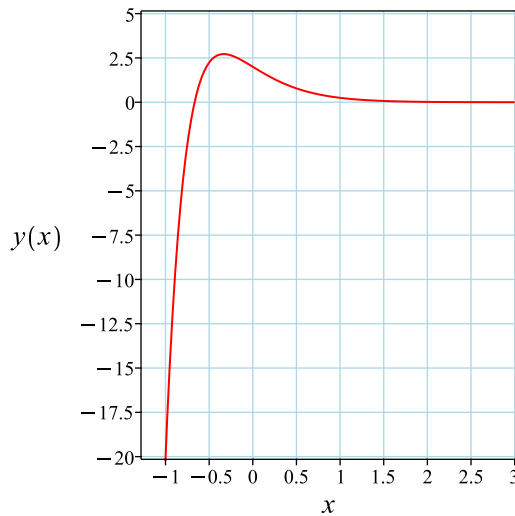
Which simplifies to

$$y = e^{-3x}(3x + 2)$$

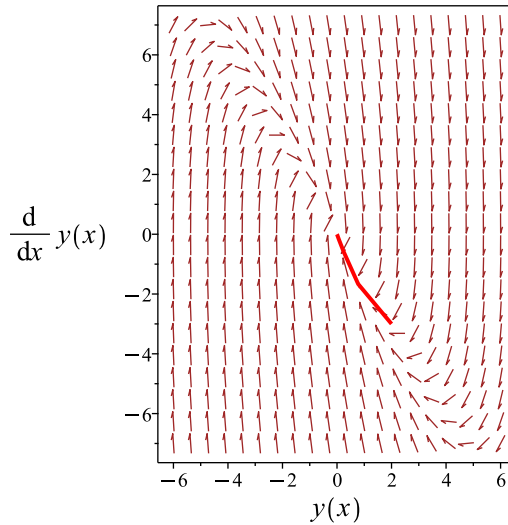
Summary

The solution(s) found are the following

$$y = e^{-3x}(3x + 2) \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = e^{-3x}(3x + 2)$$

Verified OK.

10.29.4 Solving using Kovacic algorithm

Writing the ode as

$$y'' + 6y' + 9y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$A = 1$$

$$B = 6 \quad (3)$$

$$C = 9$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$r = \frac{s}{t} = \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{0}{1} \tag{6}$$

Comparing the above to (5) shows that

$$s = 0 \\ t = 1$$

Therefore eq. (4) becomes

$$z''(x) = 0 \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 319: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned}O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - -\infty \\ &= \infty\end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is *infinity* then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = 0$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = 1$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned}y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{6}{1} dx} \\ &= z_1 e^{-3x} \\ &= z_1 (e^{-3x})\end{aligned}$$

Which simplifies to

$$y_1 = e^{-3x}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{6}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{-6x}}{(y_1)^2} dx \\ &= y_1(x)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (e^{-3x}) + c_2 (e^{-3x}(x))\end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{-3x} + c_2 x e^{-3x} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 2$ and $x = 0$ in the above gives

$$2 = c_1 \quad (1A)$$

Taking derivative of the solution gives

$$y' = -3c_1 e^{-3x} + c_2 e^{-3x} - 3c_2 x e^{-3x}$$

substituting $y' = -3$ and $x = 0$ in the above gives

$$-3 = -3c_1 + c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 2$$

$$c_2 = 3$$

Substituting these values back in above solution results in

$$y = 3x e^{-3x} + 2 e^{-3x}$$

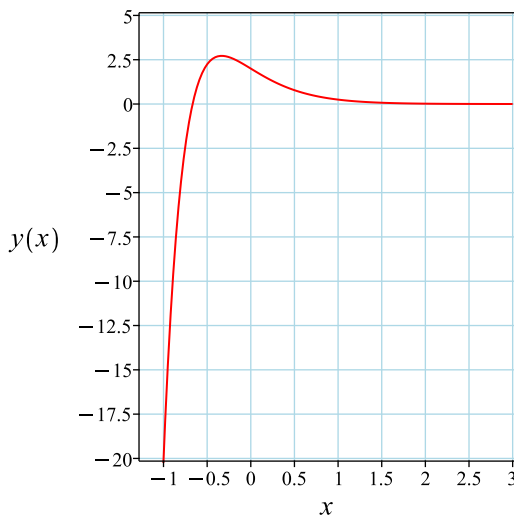
Which simplifies to

$$y = e^{-3x}(3x + 2)$$

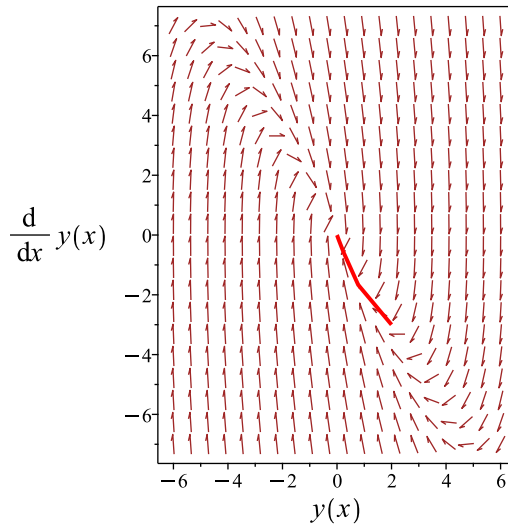
Summary

The solution(s) found are the following

$$y = e^{-3x}(3x + 2) \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = e^{-3x}(3x + 2)$$

Verified OK.

10.29.5 Maple step by step solution

Let's solve

$$\left[y'' + 6y' + 9y = 0, y(0) = 2, y'|_{\{x=0\}} = -3 \right]$$

- Highest derivative means the order of the ODE is 2
 y''
- Characteristic polynomial of ODE
 $r^2 + 6r + 9 = 0$
- Factor the characteristic polynomial
 $(r + 3)^2 = 0$
- Root of the characteristic polynomial
 $r = -3$
- 1st solution of the ODE

$$y_1(x) = e^{-3x}$$

- Repeated root, multiply $y_1(x)$ by x to ensure linear independence

$$y_2(x) = x e^{-3x}$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x)$$

- Substitute in solutions

$$y = c_1 e^{-3x} + c_2 x e^{-3x}$$

- Check validity of solution $y = c_1 e^{-3x} + c_2 x e^{-3x}$

- Use initial condition $y(0) = 2$

$$2 = c_1$$

- Compute derivative of the solution

$$y' = -3c_1 e^{-3x} + c_2 e^{-3x} - 3c_2 x e^{-3x}$$

- Use the initial condition $y' \Big|_{\{x=0\}} = -3$

$$-3 = -3c_1 + c_2$$

- Solve for c_1 and c_2

$$\{c_1 = 2, c_2 = 3\}$$

- Substitute constant values into general solution and simplify

$$y = e^{-3x}(3x + 2)$$

- Solution to the IVP

$$y = e^{-3x}(3x + 2)$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 14

```
dsolve([diff(y(x),x$2)+6*diff(y(x),x)+9*y(x)=0,y(0) = 2, D(y)(0) = -3],y(x), singsol=all)
```

$$y(x) = e^{-3x}(3x + 2)$$

✓ Solution by Mathematica

Time used: 0.013 (sec). Leaf size: 16

```
DSolve[{y''[x]+6*y'[x]+9*y[x]==0,{y[0]==2,y'[0]==-3}},y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^{-3x}(3x + 2)$$

10.30 problem 30

10.30.1 Existence and uniqueness analysis	2113
10.30.2 Solving as second order linear constant coeff ode	2113
10.30.3 Solving as linear second order ode solved by an integrating factor ode	2115
10.30.4 Solving using Kovacic algorithm	2118
10.30.5 Maple step by step solution	2122

Internal problem ID [11760]

Internal file name [OUTPUT/11769_Thursday_April_11_2024_08_49_29_PM_26050774/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 30.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff", "linear_second_order_ode_solved_by_an_integrating_factor"

Maple gives the following as the ode type

```
[[_2nd_order, _missing_x]]
```

$$4y'' - 12y' + 9y = 0$$

With initial conditions

$$[y(0) = 4, y'(0) = 9]$$

10.30.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$p(x) = -3$$

$$q(x) = \frac{9}{4}$$

$$F = 0$$

Hence the ode is

$$y'' - 3y' + \frac{9y}{4} = 0$$

The domain of $p(x) = -3$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = \frac{9}{4}$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

10.30.2 Solving as second order linear constant coeff ode

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 4, B = -12, C = 9$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$4\lambda^2 e^{\lambda x} - 12\lambda e^{\lambda x} + 9 e^{\lambda x} = 0 \tag{1}$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$4\lambda^2 - 12\lambda + 9 = 0 \tag{2}$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 4, B = -12, C = 9$ into the above gives

$$\begin{aligned}\lambda_{1,2} &= \frac{12}{(2)(4)} \pm \frac{1}{(2)(4)} \sqrt{(-12)^2 - (4)(4)(9)} \\ &= \frac{3}{2}\end{aligned}$$

Hence this is the case of a double root $\lambda_{1,2} = -\frac{3}{2}$. Therefore the solution is

$$y = c_1 e^{\frac{3x}{2}} + c_2 x e^{\frac{3x}{2}} \quad (1)$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{\frac{3x}{2}} + c_2 x e^{\frac{3x}{2}} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 4$ and $x = 0$ in the above gives

$$4 = c_1 \quad (1A)$$

Taking derivative of the solution gives

$$y' = \frac{3c_1 e^{\frac{3x}{2}}}{2} + e^{\frac{3x}{2}} c_2 + \frac{3c_2 x e^{\frac{3x}{2}}}{2}$$

substituting $y' = 9$ and $x = 0$ in the above gives

$$9 = \frac{3c_1}{2} + c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 4$$

$$c_2 = 3$$

Substituting these values back in above solution results in

$$y = 3x e^{\frac{3x}{2}} + 4 e^{\frac{3x}{2}}$$

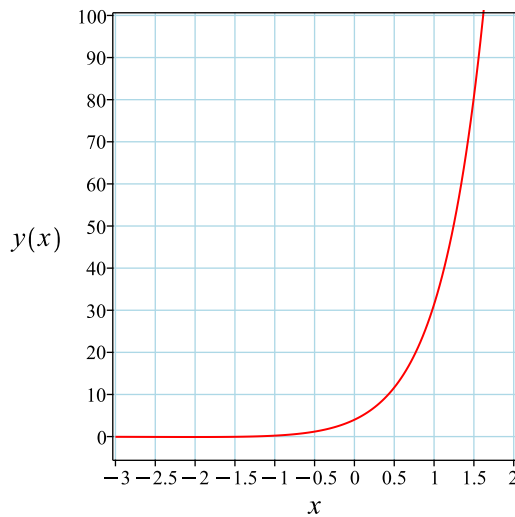
Which simplifies to

$$y = e^{\frac{3x}{2}} (4 + 3x)$$

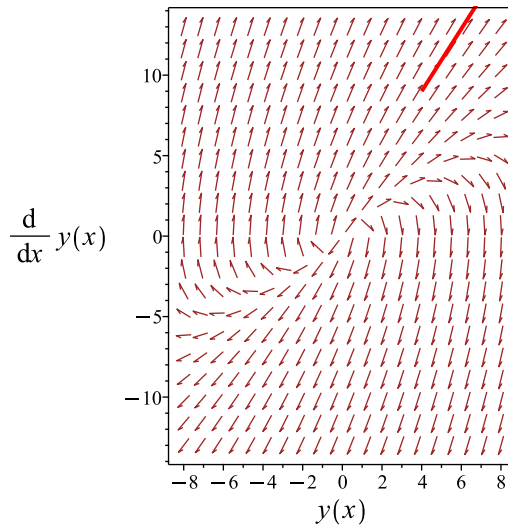
Summary

The solution(s) found are the following

$$y = e^{\frac{3x}{2}}(4 + 3x) \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = e^{\frac{3x}{2}}(4 + 3x)$$

Verified OK.

10.30.3 Solving as linear second order ode solved by an integrating factor ode

The ode satisfies this form

$$y'' + p(x)y' + \frac{(p(x)^2 + p'(x))y}{2} = f(x)$$

Where $p(x) = -3$. Therefore, there is an integrating factor given by

$$\begin{aligned} M(x) &= e^{\frac{1}{2} \int p dx} \\ &= e^{\int -3 dx} \\ &= e^{-\frac{3x}{2}} \end{aligned}$$

Multiplying both sides of the ODE by the integrating factor $M(x)$ makes the left side of the ODE a complete differential

$$(M(x)y)'' = 0$$
$$\left(e^{-\frac{3x}{2}}y\right)'' = 0$$

Integrating once gives

$$\left(e^{-\frac{3x}{2}}y\right)' = c_1$$

Integrating again gives

$$\left(e^{-\frac{3x}{2}}y\right) = c_1x + c_2$$

Hence the solution is

$$y = \frac{c_1x + c_2}{e^{-\frac{3x}{2}}}$$

Or

$$y = c_1x e^{\frac{3x}{2}} + e^{\frac{3x}{2}} c_2$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1x e^{\frac{3x}{2}} + e^{\frac{3x}{2}} c_2 \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 4$ and $x = 0$ in the above gives

$$4 = c_2 \tag{1A}$$

Taking derivative of the solution gives

$$y' = c_1 e^{\frac{3x}{2}} + \frac{3c_1x e^{\frac{3x}{2}}}{2} + \frac{3 e^{\frac{3x}{2}} c_2}{2}$$

substituting $y' = 9$ and $x = 0$ in the above gives

$$9 = c_1 + \frac{3c_2}{2} \tag{2A}$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 3$$

$$c_2 = 4$$

Substituting these values back in above solution results in

$$y = 3x e^{\frac{3x}{2}} + 4 e^{\frac{3x}{2}}$$

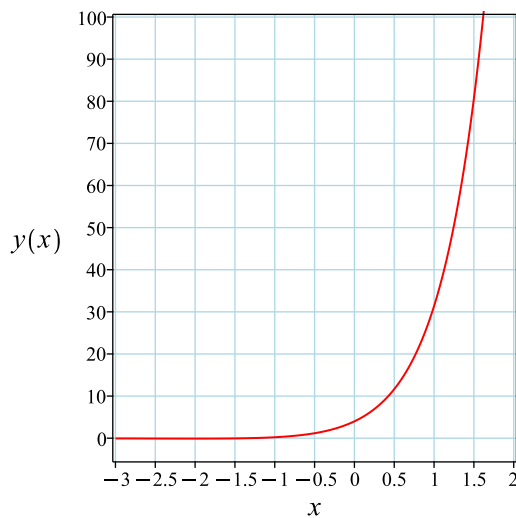
Which simplifies to

$$y = e^{\frac{3x}{2}} (4 + 3x)$$

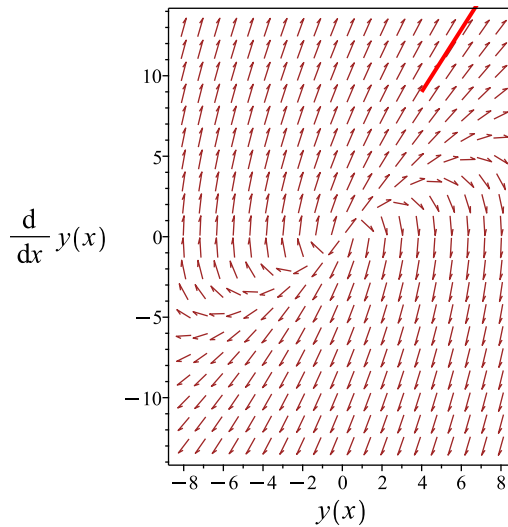
Summary

The solution(s) found are the following

$$y = e^{\frac{3x}{2}} (4 + 3x) \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = e^{\frac{3x}{2}} (4 + 3x)$$

Verified OK.

10.30.4 Solving using Kovacic algorithm

Writing the ode as

$$4y'' - 12y' + 9y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 4 \\ B &= -12 \\ C &= 9 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{0}{1} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 0 \\ t &= 1 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = 0 \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 321: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - -\infty \\ &= \infty \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is *infinity* then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = 0$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = 1$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-12}{4} dx} \end{aligned}$$

$$\begin{aligned}
&= z_1 e^{\frac{3x}{2}} \\
&= z_1 \left(e^{\frac{3x}{2}} \right)
\end{aligned}$$

Which simplifies to

$$y_1 = e^{\frac{3x}{2}}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}
y_2 &= y_1 \int \frac{e^{\int -\frac{-12}{4} dx}}{(y_1)^2} dx \\
&= y_1 \int \frac{e^{3x}}{(y_1)^2} dx \\
&= y_1(x)
\end{aligned}$$

Therefore the solution is

$$\begin{aligned}
y &= c_1 y_1 + c_2 y_2 \\
&= c_1 \left(e^{\frac{3x}{2}} \right) + c_2 \left(e^{\frac{3x}{2}}(x) \right)
\end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{\frac{3x}{2}} + c_2 x e^{\frac{3x}{2}} \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 4$ and $x = 0$ in the above gives

$$4 = c_1 \tag{1A}$$

Taking derivative of the solution gives

$$y' = \frac{3c_1 e^{\frac{3x}{2}}}{2} + e^{\frac{3x}{2}} c_2 + \frac{3c_2 x e^{\frac{3x}{2}}}{2}$$

substituting $y' = 9$ and $x = 0$ in the above gives

$$9 = \frac{3c_1}{2} + c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$\begin{aligned} c_1 &= 4 \\ c_2 &= 3 \end{aligned}$$

Substituting these values back in above solution results in

$$y = 3x e^{\frac{3x}{2}} + 4 e^{\frac{3x}{2}}$$

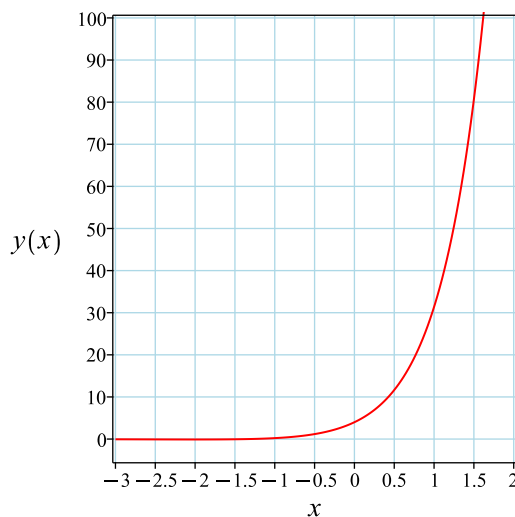
Which simplifies to

$$y = e^{\frac{3x}{2}} (4 + 3x)$$

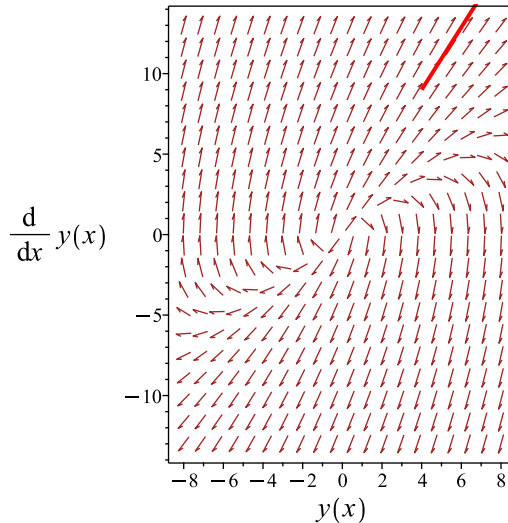
Summary

The solution(s) found are the following

$$y = e^{\frac{3x}{2}} (4 + 3x) \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = e^{\frac{3x}{2}} (4 + 3x)$$

Verified OK.

10.30.5 Maple step by step solution

Let's solve

$$\left[4y'' - 12y' + 9y = 0, y(0) = 4, y' \Big|_{\{x=0\}} = 9 \right]$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = 3y' - \frac{9y}{4}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' - 3y' + \frac{9y}{4} = 0$$

- Characteristic polynomial of ODE

$$r^2 - 3r + \frac{9}{4} = 0$$

- Factor the characteristic polynomial

$$\frac{(2r-3)^2}{4} = 0$$

- Root of the characteristic polynomial

$$r = \frac{3}{2}$$

- 1st solution of the ODE

$$y_1(x) = e^{\frac{3x}{2}}$$

- Repeated root, multiply $y_1(x)$ by x to ensure linear independence

$$y_2(x) = x e^{\frac{3x}{2}}$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x)$$

- Substitute in solutions

$$y = c_1 e^{\frac{3x}{2}} + c_2 x e^{\frac{3x}{2}}$$

- Check validity of solution $y = c_1 e^{\frac{3x}{2}} + c_2 x e^{\frac{3x}{2}}$

- Use initial condition $y(0) = 4$

$$4 = c_1$$

- Compute derivative of the solution

$$y' = \frac{3c_1 e^{\frac{3x}{2}}}{2} + e^{\frac{3x}{2}} c_2 + \frac{3c_2 x e^{\frac{3x}{2}}}{2}$$

- Use the initial condition $y' \Big|_{\{x=0\}} = 9$

$$9 = \frac{3c_1}{2} + c_2$$
- Solve for c_1 and c_2

$$\{c_1 = 4, c_2 = 3\}$$
- Substitute constant values into general solution and simplify
$$y = e^{\frac{3x}{2}}(4 + 3x)$$
- Solution to the IVP
$$y = e^{\frac{3x}{2}}(4 + 3x)$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 14

```
dsolve([4*diff(y(x),x$2)-12*diff(y(x),x)+9*y(x)=0,y(0) = 4, D(y)(0) = 9],y(x), singsol=all)
```

$$y(x) = e^{\frac{3x}{2}}(3x + 4)$$

✓ Solution by Mathematica

Time used: 0.014 (sec). Leaf size: 18

```
DSolve[{4*y''[x]-12*y'[x]+9*y[x]==0,{y[0]==4,y'[0]==9}},y[x],x,IncludeSingularSolutions -> T
```

$$y(x) \rightarrow e^{3x/2}(3x + 4)$$

10.31 problem 31

10.31.1 Existence and uniqueness analysis	2125
10.31.2 Solving as second order linear constant coeff ode	2125
10.31.3 Solving as linear second order ode solved by an integrating factor ode	2127
10.31.4 Solving using Kovacic algorithm	2129
10.31.5 Maple step by step solution	2133

Internal problem ID [11761]

Internal file name [OUTPUT/11770_Thursday_April_11_2024_08_49_30_PM_15626544/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 31.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff", "linear_second_order_ode_solved_by_an_integrating_factor"

Maple gives the following as the ode type

```
[[_2nd_order, _missing_x]]
```

$$y'' + 4y' + 4y = 0$$

With initial conditions

$$[y(0) = 3, y'(0) = 7]$$

10.31.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$p(x) = 4$$

$$q(x) = 4$$

$$F = 0$$

Hence the ode is

$$y'' + 4y' + 4y = 0$$

The domain of $p(x) = 4$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = 4$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

10.31.2 Solving as second order linear constant coeff ode

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 4, C = 4$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + 4\lambda e^{\lambda x} + 4e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 4\lambda + 4 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 4, C = 4$ into the above gives

$$\begin{aligned}\lambda_{1,2} &= \frac{-4}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{(4)^2 - (4)(1)(4)} \\ &= -2\end{aligned}$$

Hence this is the case of a double root $\lambda_{1,2} = 2$. Therefore the solution is

$$y = c_1 e^{-2x} + c_2 x e^{-2x} \quad (1)$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{-2x} + x e^{-2x} c_2 \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 3$ and $x = 0$ in the above gives

$$3 = c_1 \quad (1A)$$

Taking derivative of the solution gives

$$y' = -2c_1 e^{-2x} + c_2 e^{-2x} - 2x e^{-2x} c_2$$

substituting $y' = 7$ and $x = 0$ in the above gives

$$7 = -2c_1 + c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 3$$

$$c_2 = 13$$

Substituting these values back in above solution results in

$$y = 13x e^{-2x} + 3 e^{-2x}$$

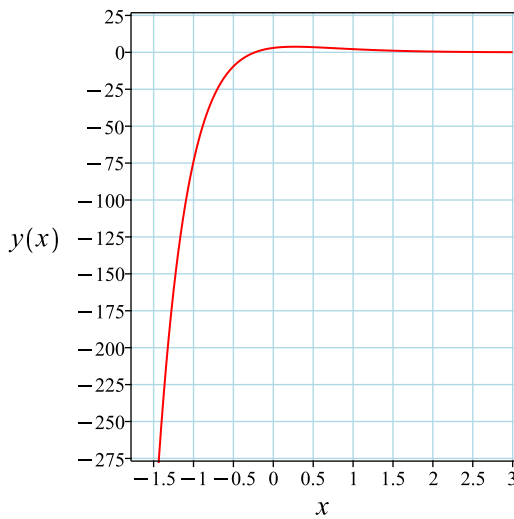
Which simplifies to

$$y = e^{-2x}(3 + 13x)$$

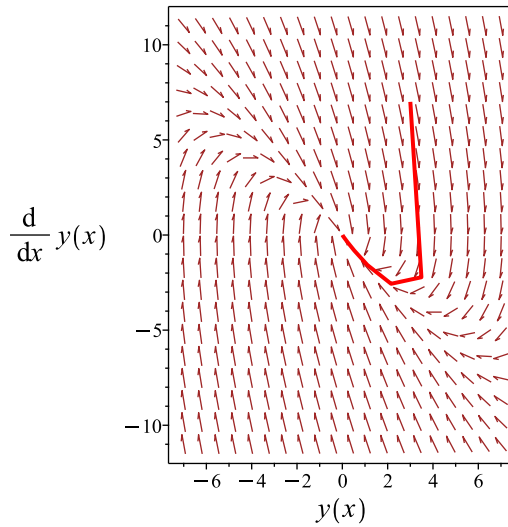
Summary

The solution(s) found are the following

$$y = e^{-2x}(3 + 13x) \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = e^{-2x}(3 + 13x)$$

Verified OK.

10.31.3 Solving as linear second order ode solved by an integrating factor ode

The ode satisfies this form

$$y'' + p(x)y' + \frac{(p(x)^2 + p'(x))y}{2} = f(x)$$

Where $p(x) = 4$. Therefore, there is an integrating factor given by

$$\begin{aligned} M(x) &= e^{\frac{1}{2} \int p dx} \\ &= e^{\int 4 dx} \\ &= e^{2x} \end{aligned}$$

Multiplying both sides of the ODE by the integrating factor $M(x)$ makes the left side of the ODE a complete differential

$$\begin{aligned} (M(x)y)'' &= 0 \\ (ye^{2x})'' &= 0 \end{aligned}$$

Integrating once gives

$$(y e^{2x})' = c_1$$

Integrating again gives

$$(y e^{2x}) = c_1 x + c_2$$

Hence the solution is

$$y = \frac{c_1 x + c_2}{e^{2x}}$$

Or

$$y = c_1 x e^{-2x} + c_2 e^{-2x}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 x e^{-2x} + c_2 e^{-2x} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 3$ and $x = 0$ in the above gives

$$3 = c_2 \quad (1A)$$

Taking derivative of the solution gives

$$y' = c_1 e^{-2x} - 2c_1 x e^{-2x} - 2c_2 e^{-2x}$$

substituting $y' = 7$ and $x = 0$ in the above gives

$$7 = c_1 - 2c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 13$$

$$c_2 = 3$$

Substituting these values back in above solution results in

$$y = 13x e^{-2x} + 3 e^{-2x}$$

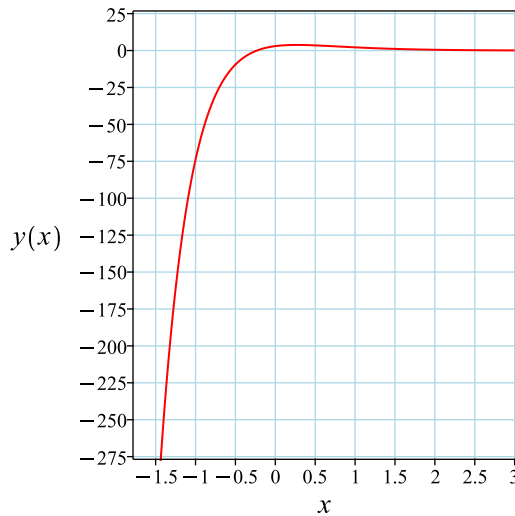
Which simplifies to

$$y = e^{-2x}(3 + 13x)$$

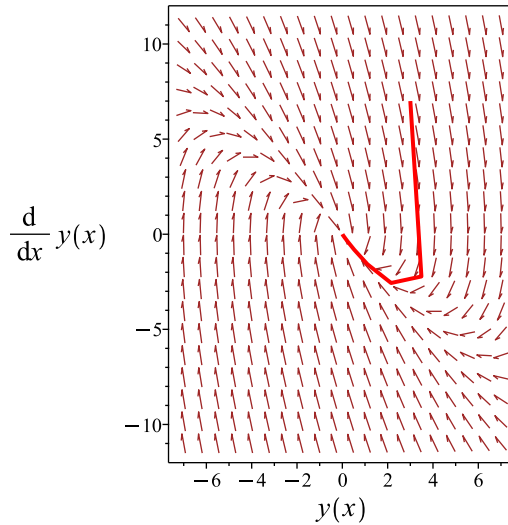
Summary

The solution(s) found are the following

$$y = e^{-2x}(3 + 13x) \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = e^{-2x}(3 + 13x)$$

Verified OK.

10.31.4 Solving using Kovacic algorithm

Writing the ode as

$$y'' + 4y' + 4y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$A = 1$$

$$B = 4 \quad (3)$$

$$C = 4$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{0}{1} \tag{6}$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 0 \\ t &= 1 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = 0 \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 323: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned}O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - -\infty \\ &= \infty\end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is *infinity* then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = 0$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = 1$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned}y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{4}{1} dx} \\ &= z_1 e^{-2x} \\ &= z_1 (e^{-2x})\end{aligned}$$

Which simplifies to

$$y_1 = e^{-2x}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{4}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{-4x}}{(y_1)^2} dx \\ &= y_1(x)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (e^{-2x}) + c_2 (e^{-2x}(x))\end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{-2x} + x e^{-2x} c_2 \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 3$ and $x = 0$ in the above gives

$$3 = c_1 \quad (1A)$$

Taking derivative of the solution gives

$$y' = -2c_1 e^{-2x} + c_2 e^{-2x} - 2x e^{-2x} c_2$$

substituting $y' = 7$ and $x = 0$ in the above gives

$$7 = -2c_1 + c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 3$$

$$c_2 = 13$$

Substituting these values back in above solution results in

$$y = 13x e^{-2x} + 3 e^{-2x}$$

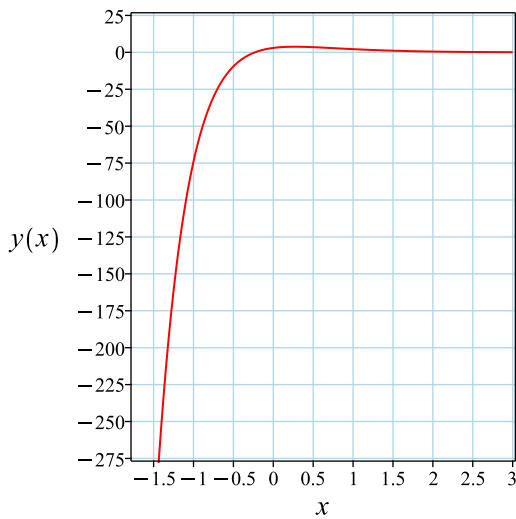
Which simplifies to

$$y = e^{-2x}(3 + 13x)$$

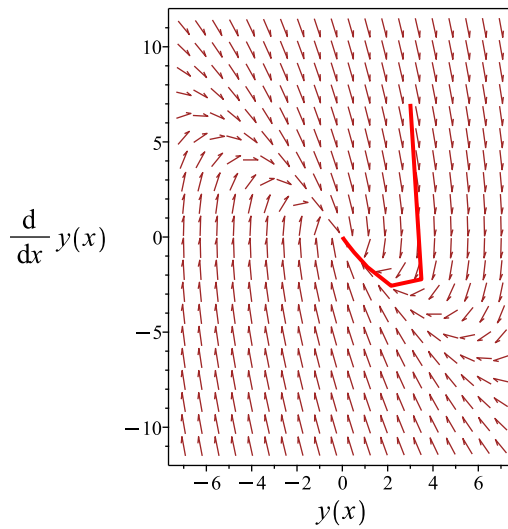
Summary

The solution(s) found are the following

$$y = e^{-2x}(3 + 13x) \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = e^{-2x}(3 + 13x)$$

Verified OK.

10.31.5 Maple step by step solution

Let's solve

$$\left[y'' + 4y' + 4y = 0, y(0) = 3, y'|_{\{x=0\}} = 7 \right]$$

- Highest derivative means the order of the ODE is 2
- y''
- Characteristic polynomial of ODE
- $r^2 + 4r + 4 = 0$
- Factor the characteristic polynomial
- $(r + 2)^2 = 0$
- Root of the characteristic polynomial
- $r = -2$
- 1st solution of the ODE

$$y_1(x) = e^{-2x}$$

- Repeated root, multiply $y_1(x)$ by x to ensure linear independence

$$y_2(x) = x e^{-2x}$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x)$$

- Substitute in solutions

$$y = c_1 e^{-2x} + x e^{-2x} c_2$$

- Check validity of solution $y = c_1 e^{-2x} + x e^{-2x} c_2$

- Use initial condition $y(0) = 3$

$$3 = c_1$$

- Compute derivative of the solution

$$y' = -2c_1 e^{-2x} + c_2 e^{-2x} - 2x e^{-2x} c_2$$

- Use the initial condition $y' \Big|_{\{x=0\}} = 7$

$$7 = -2c_1 + c_2$$

- Solve for c_1 and c_2

$$\{c_1 = 3, c_2 = 13\}$$

- Substitute constant values into general solution and simplify

$$y = e^{-2x}(3 + 13x)$$

- Solution to the IVP

$$y = e^{-2x}(3 + 13x)$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 14

```
dsolve([diff(y(x),x$2)+4*diff(y(x),x)+4*y(x)=0,y(0) = 3, D(y)(0) = 7],y(x), singsol=all)
```

$$y(x) = e^{-2x}(3 + 13x)$$

✓ Solution by Mathematica

Time used: 0.013 (sec). Leaf size: 16

```
DSolve[{y'[x]+4*y'[x]+4*y[x]==0,{y[0]==3,y'[0]==7}},y[x],x,IncludeSingularSolutions -> True
```

$$y(x) \rightarrow e^{-2x}(13x + 3)$$

10.32 problem 32

10.32.1 Existence and uniqueness analysis	2137
10.32.2 Solving as second order linear constant coeff ode	2137
10.32.3 Solving as linear second order ode solved by an integrating factor ode	2139
10.32.4 Solving using Kovacic algorithm	2142
10.32.5 Maple step by step solution	2146

Internal problem ID [11762]

Internal file name [OUTPUT/11771_Thursday_April_11_2024_08_49_31_PM_45171481/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 32.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff", "linear_second_order_ode_solved_by_an_integrating_factor"

Maple gives the following as the ode type

```
[[_2nd_order, _missing_x]]
```

$$9y'' - 6y' + y = 0$$

With initial conditions

$$[y(0) = 3, y'(0) = -1]$$

10.32.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$p(x) = -\frac{2}{3}$$

$$q(x) = \frac{1}{9}$$

$$F = 0$$

Hence the ode is

$$y'' - \frac{2y'}{3} + \frac{y}{9} = 0$$

The domain of $p(x) = -\frac{2}{3}$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = \frac{1}{9}$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

10.32.2 Solving as second order linear constant coeff ode

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 9, B = -6, C = 1$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$9\lambda^2 e^{\lambda x} - 6\lambda e^{\lambda x} + e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$9\lambda^2 - 6\lambda + 1 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 9, B = -6, C = 1$ into the above gives

$$\begin{aligned}\lambda_{1,2} &= \frac{6}{(2)(9)} \pm \frac{1}{(2)(9)} \sqrt{(-6)^2 - (4)(9)(1)} \\ &= \frac{1}{3}\end{aligned}$$

Hence this is the case of a double root $\lambda_{1,2} = -\frac{1}{3}$. Therefore the solution is

$$y = c_1 e^{\frac{x}{3}} + c_2 x e^{\frac{x}{3}} \quad (1)$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{\frac{x}{3}} + c_2 x e^{\frac{x}{3}} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 3$ and $x = 0$ in the above gives

$$3 = c_1 \quad (1A)$$

Taking derivative of the solution gives

$$y' = \frac{c_1 e^{\frac{x}{3}}}{3} + c_2 e^{\frac{x}{3}} + \frac{c_2 x e^{\frac{x}{3}}}{3}$$

substituting $y' = -1$ and $x = 0$ in the above gives

$$-1 = \frac{c_1}{3} + c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$\begin{aligned}c_1 &= 3 \\ c_2 &= -2\end{aligned}$$

Substituting these values back in above solution results in

$$y = -2x e^{\frac{x}{3}} + 3 e^{\frac{x}{3}}$$

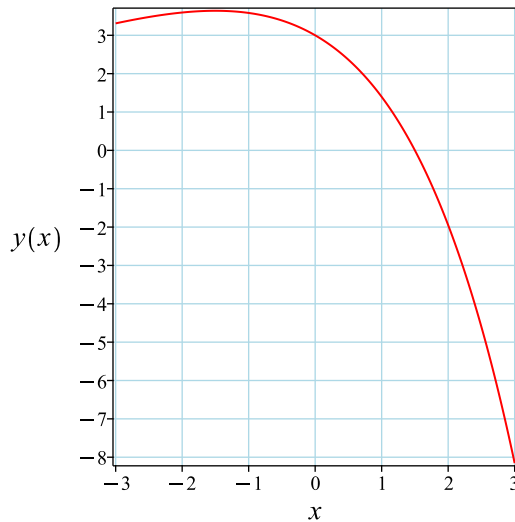
Which simplifies to

$$y = e^{\frac{x}{3}}(-2x + 3)$$

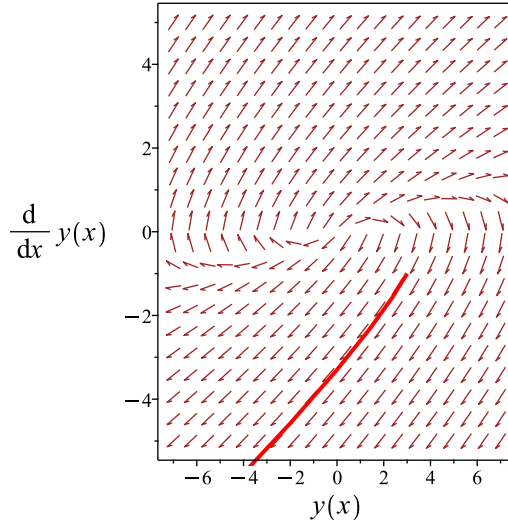
Summary

The solution(s) found are the following

$$y = e^{\frac{x}{3}}(-2x + 3) \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = e^{\frac{x}{3}}(-2x + 3)$$

Verified OK.

10.32.3 Solving as linear second order ode solved by an integrating factor ode

The ode satisfies this form

$$y'' + p(x)y' + \frac{(p(x))^2 + p'(x)}{2}y = f(x)$$

Where $p(x) = -\frac{2}{3}$. Therefore, there is an integrating factor given by

$$\begin{aligned} M(x) &= e^{\frac{1}{2} \int p dx} \\ &= e^{\int -\frac{2}{3} dx} \\ &= e^{-\frac{x}{3}} \end{aligned}$$

Multiplying both sides of the ODE by the integrating factor $M(x)$ makes the left side of the ODE a complete differential

$$(M(x)y)'' = 0$$

$$(e^{-\frac{x}{3}}y)'' = 0$$

Integrating once gives

$$(e^{-\frac{x}{3}}y)' = c_1$$

Integrating again gives

$$(e^{-\frac{x}{3}}y) = c_1x + c_2$$

Hence the solution is

$$y = \frac{c_1x + c_2}{e^{-\frac{x}{3}}}$$

Or

$$y = c_1x e^{\frac{x}{3}} + c_2 e^{\frac{x}{3}}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1x e^{\frac{x}{3}} + c_2 e^{\frac{x}{3}} \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 3$ and $x = 0$ in the above gives

$$3 = c_2 \tag{1A}$$

Taking derivative of the solution gives

$$y' = c_1 e^{\frac{x}{3}} + \frac{c_1x e^{\frac{x}{3}}}{3} + \frac{c_2 e^{\frac{x}{3}}}{3}$$

substituting $y' = -1$ and $x = 0$ in the above gives

$$-1 = c_1 + \frac{c_2}{3} \tag{2A}$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = -2$$

$$c_2 = 3$$

Substituting these values back in above solution results in

$$y = -2x e^{\frac{x}{3}} + 3 e^{\frac{x}{3}}$$

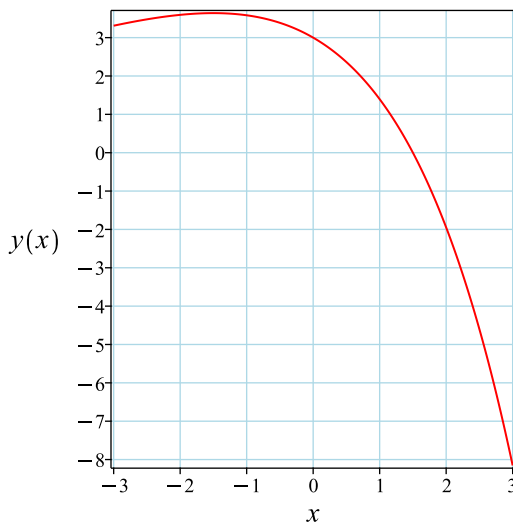
Which simplifies to

$$y = e^{\frac{x}{3}}(-2x + 3)$$

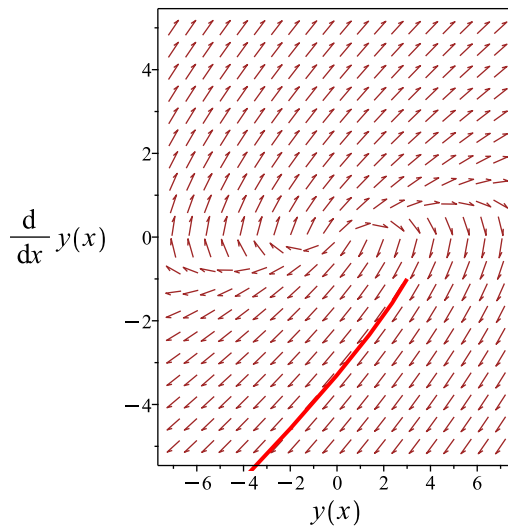
Summary

The solution(s) found are the following

$$y = e^{\frac{x}{3}}(-2x + 3) \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = e^{\frac{x}{3}}(-2x + 3)$$

Verified OK.

10.32.4 Solving using Kovacic algorithm

Writing the ode as

$$9y'' - 6y' + y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 9 \\ B &= -6 \\ C &= 1 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{0}{1} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 0 \\ t &= 1 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = 0 \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 325: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - -\infty \\ &= \infty \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is *infinity* then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = 0$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = 1$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-6}{9} dx} \end{aligned}$$

$$\begin{aligned}
&= z_1 e^{\frac{x}{3}} \\
&= z_1 \left(e^{\frac{x}{3}} \right)
\end{aligned}$$

Which simplifies to

$$y_1 = e^{\frac{x}{3}}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}
y_2 &= y_1 \int \frac{e^{\int -\frac{-6}{9} dx}}{(y_1)^2} dx \\
&= y_1 \int \frac{e^{\frac{2x}{3}}}{(y_1)^2} dx \\
&= y_1(x)
\end{aligned}$$

Therefore the solution is

$$\begin{aligned}
y &= c_1 y_1 + c_2 y_2 \\
&= c_1 \left(e^{\frac{x}{3}} \right) + c_2 \left(e^{\frac{x}{3}}(x) \right)
\end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{\frac{x}{3}} + c_2 x e^{\frac{x}{3}} \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 3$ and $x = 0$ in the above gives

$$3 = c_1 \tag{1A}$$

Taking derivative of the solution gives

$$y' = \frac{c_1 e^{\frac{x}{3}}}{3} + c_2 e^{\frac{x}{3}} + \frac{c_2 x e^{\frac{x}{3}}}{3}$$

substituting $y' = -1$ and $x = 0$ in the above gives

$$-1 = \frac{c_1}{3} + c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$\begin{aligned} c_1 &= 3 \\ c_2 &= -2 \end{aligned}$$

Substituting these values back in above solution results in

$$y = -2x e^{\frac{x}{3}} + 3 e^{\frac{x}{3}}$$

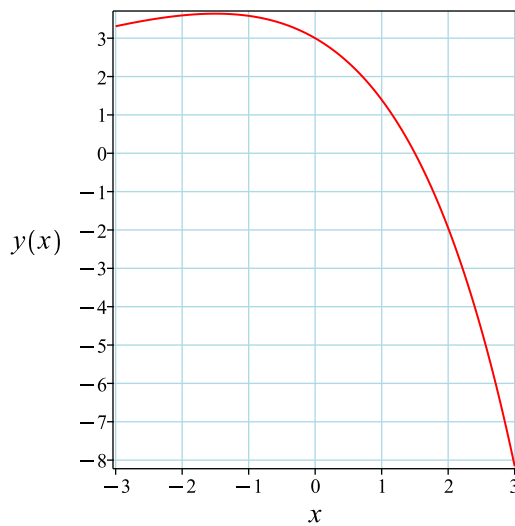
Which simplifies to

$$y = e^{\frac{x}{3}}(-2x + 3)$$

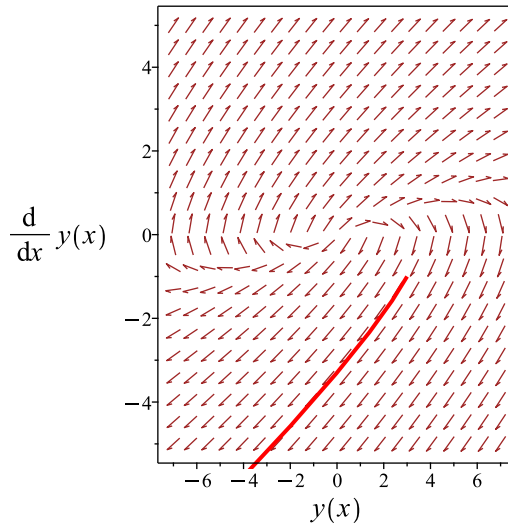
Summary

The solution(s) found are the following

$$y = e^{\frac{x}{3}}(-2x + 3) \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = e^{\frac{x}{3}}(-2x + 3)$$

Verified OK.

10.32.5 Maple step by step solution

Let's solve

$$\left[9y'' - 6y' + y = 0, y(0) = 3, y'|_{\{x=0\}} = -1 \right]$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = \frac{2y'}{3} - \frac{y}{9}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' - \frac{2y'}{3} + \frac{y}{9} = 0$$

- Characteristic polynomial of ODE

$$r^2 - \frac{2}{3}r + \frac{1}{9} = 0$$

- Factor the characteristic polynomial

$$\frac{(3r-1)^2}{9} = 0$$

- Root of the characteristic polynomial

$$r = \frac{1}{3}$$

- 1st solution of the ODE

$$y_1(x) = e^{\frac{x}{3}}$$

- Repeated root, multiply $y_1(x)$ by x to ensure linear independence

$$y_2(x) = x e^{\frac{x}{3}}$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x)$$

- Substitute in solutions

$$y = c_1 e^{\frac{x}{3}} + c_2 x e^{\frac{x}{3}}$$

- Check validity of solution $y = c_1 e^{\frac{x}{3}} + c_2 x e^{\frac{x}{3}}$

- Use initial condition $y(0) = 3$

$$3 = c_1$$

- Compute derivative of the solution

$$y' = \frac{c_1 e^{\frac{x}{3}}}{3} + c_2 e^{\frac{x}{3}} + \frac{c_2 x e^{\frac{x}{3}}}{3}$$

- Use the initial condition $y' \Big|_{\{x=0\}} = -1$

$$-1 = \frac{c_1}{3} + c_2$$
- Solve for c_1 and c_2

$$\{c_1 = 3, c_2 = -2\}$$
- Substitute constant values into general solution and simplify
$$y = e^{\frac{x}{3}}(-2x + 3)$$
- Solution to the IVP
$$y = e^{\frac{x}{3}}(-2x + 3)$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 14

```
dsolve([9*diff(y(x),x$2)-6*diff(y(x),x)+y(x)=0,y(0) = 3, D(y)(0) = -1],y(x), singsol=all)
```

$$y(x) = e^{\frac{x}{3}}(-2x + 3)$$

✓ Solution by Mathematica

Time used: 0.014 (sec). Leaf size: 18

```
DSolve[{9*y''[x]-6*y'[x]+y[x]==0,{y[0]==3,y'[0]==-1}},y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^{x/3}(3 - 2x)$$

10.33 problem 33

10.33.1 Existence and uniqueness analysis	2148
10.33.2 Solving as second order linear constant coeff ode	2149
10.33.3 Solving using Kovacic algorithm	2151
10.33.4 Maple step by step solution	2155

Internal problem ID [11763]

Internal file name [OUTPUT/11772_Thursday_April_11_2024_08_49_31_PM_4033505/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 33.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _missing_x]]
```

$$y'' - 4y' + 29y = 0$$

With initial conditions

$$[y(0) = 0, y'(0) = 5]$$

10.33.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$p(x) = -4$$

$$q(x) = 29$$

$$F = 0$$

Hence the ode is

$$y'' - 4y' + 29y = 0$$

The domain of $p(x) = -4$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = 29$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

10.33.2 Solving as second order linear constant coeff ode

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = -4, C = 29$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} - 4\lambda e^{\lambda x} + 29 e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 - 4\lambda + 29 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = -4, C = 29$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{4}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{-4^2 - (4)(1)(29)} \\ &= 2 \pm 5i \end{aligned}$$

Hence

$$\lambda_1 = 2 + 5i$$

$$\lambda_2 = 2 - 5i$$

Which simplifies to

$$\lambda_1 = 2 + 5i$$

$$\lambda_2 = 2 - 5i$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = 2$ and $\beta = 5$. Therefore the final solution, when using Euler relation, can be written as

$$y = e^{\alpha x}(c_1 \cos(\beta x) + c_2 \sin(\beta x))$$

Which becomes

$$y = e^{2x}(c_1 \cos(5x) + c_2 \sin(5x))$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = e^{2x}(c_1 \cos(5x) + c_2 \sin(5x)) \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 0$ and $x = 0$ in the above gives

$$0 = c_1 \quad (1A)$$

Taking derivative of the solution gives

$$y' = 2e^{2x}(c_1 \cos(5x) + c_2 \sin(5x)) + e^{2x}(-5c_1 \sin(5x) + 5c_2 \cos(5x))$$

substituting $y' = 5$ and $x = 0$ in the above gives

$$5 = 2c_1 + 5c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 0$$

$$c_2 = 1$$

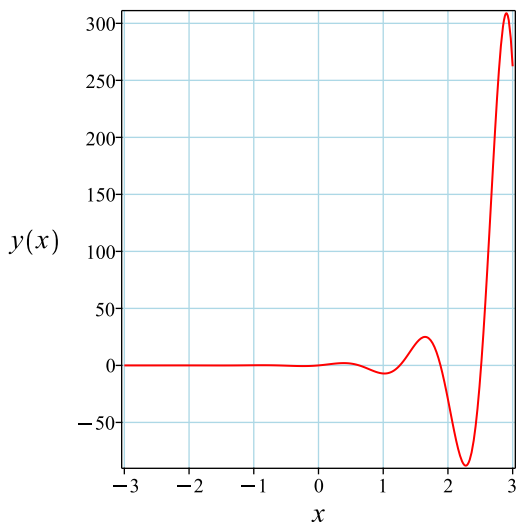
Substituting these values back in above solution results in

$$y = e^{2x} \sin(5x)$$

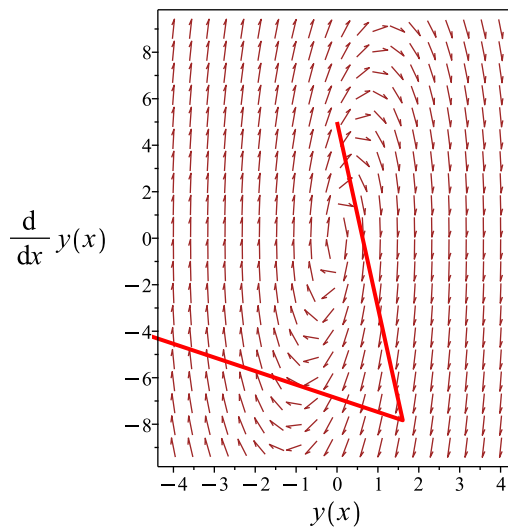
Summary

The solution(s) found are the following

$$y = e^{2x} \sin(5x) \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = e^{2x} \sin(5x)$$

Verified OK.

10.33.3 Solving using Kovacic algorithm

Writing the ode as

$$y'' - 4y' + 29y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= -4 \\ C &= 29 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$r = \frac{s}{t} = \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-25}{1} \tag{6}$$

Comparing the above to (5) shows that

$$s = -25$$

$$t = 1$$

Therefore eq. (4) becomes

$$z''(x) = -25z(x) \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 327: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = -25$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = \cos(5x)$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-4}{1} dx} \\ &= z_1 e^{2x} \\ &= z_1 (e^{2x}) \end{aligned}$$

Which simplifies to

$$y_1 = e^{2x} \cos(5x)$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{-4}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{4x}}{(y_1)^2} dx \\ &= y_1 \left(\frac{\tan(5x)}{5} \right) \end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (e^{2x} \cos(5x)) + c_2 \left(e^{2x} \cos(5x) \left(\frac{\tan(5x)}{5} \right) \right)\end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{2x} \cos(5x) + \frac{e^{2x} c_2 \sin(5x)}{5} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 0$ and $x = 0$ in the above gives

$$0 = c_1 \quad (1A)$$

Taking derivative of the solution gives

$$y' = 2c_1 e^{2x} \cos(5x) - 5c_1 e^{2x} \sin(5x) + \frac{2e^{2x} c_2 \sin(5x)}{5} + e^{2x} c_2 \cos(5x)$$

substituting $y' = 5$ and $x = 0$ in the above gives

$$5 = 2c_1 + c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$\begin{aligned}c_1 &= 0 \\ c_2 &= 5\end{aligned}$$

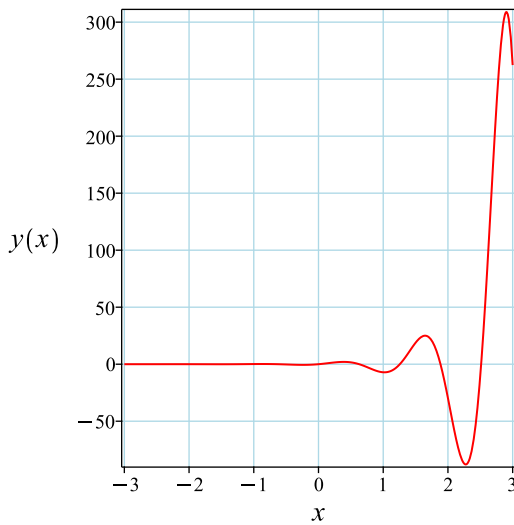
Substituting these values back in above solution results in

$$y = e^{2x} \sin(5x)$$

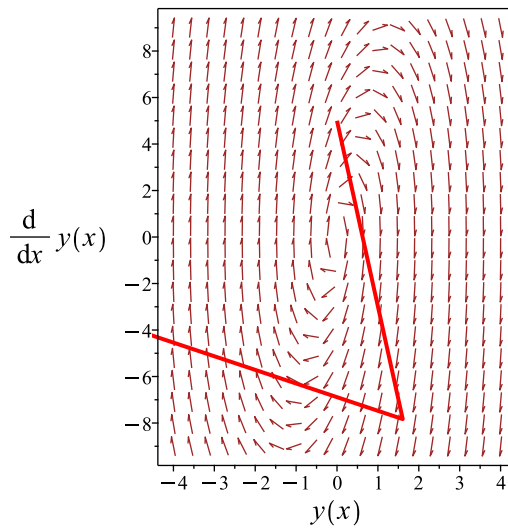
Summary

The solution(s) found are the following

$$y = e^{2x} \sin(5x) \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = e^{2x} \sin(5x)$$

Verified OK.

10.33.4 Maple step by step solution

Let's solve

$$\left[y'' - 4y' + 29y = 0, y(0) = 0, y' \Big|_{\{x=0\}} = 5 \right]$$

- Highest derivative means the order of the ODE is 2
- y''
- Characteristic polynomial of ODE
- $r^2 - 4r + 29 = 0$
- Use quadratic formula to solve for r
- $r = \frac{4 \pm (\sqrt{-100})}{2}$
- Roots of the characteristic polynomial
- $r = (2 - 5I, 2 + 5I)$
- 1st solution of the ODE

$$y_1(x) = e^{2x} \cos(5x)$$

- 2nd solution of the ODE

$$y_2(x) = e^{2x} \sin(5x)$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x)$$

- Substitute in solutions

$$y = c_1 e^{2x} \cos(5x) + e^{2x} c_2 \sin(5x)$$

- Check validity of solution $y = c_1 e^{2x} \cos(5x) + e^{2x} c_2 \sin(5x)$

- Use initial condition $y(0) = 0$

$$0 = c_1$$

- Compute derivative of the solution

$$y' = 2c_1 e^{2x} \cos(5x) - 5c_1 e^{2x} \sin(5x) + 2e^{2x} c_2 \sin(5x) + 5e^{2x} c_2 \cos(5x)$$

- Use the initial condition $y' \Big|_{\{x=0\}} = 5$

$$5 = 2c_1 + 5c_2$$

- Solve for c_1 and c_2

$$\{c_1 = 0, c_2 = 1\}$$

- Substitute constant values into general solution and simplify

$$y = e^{2x} \sin(5x)$$

- Solution to the IVP

$$y = e^{2x} \sin(5x)$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 13

```
dsolve([diff(y(x),x$2)-4*diff(y(x),x)+29*y(x)=0,y(0) = 0, D(y)(0) = 5],y(x), singsol=all)
```

$$y(x) = e^{2x} \sin(5x)$$

✓ Solution by Mathematica

Time used: 0.018 (sec). Leaf size: 15

```
DSolve[{y''[x]-4*y'[x]+29*y[x]==0,{y[0]==0,y'[0]==5}},y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^{2x} \sin(5x)$$

10.34 problem 34

10.34.1 Existence and uniqueness analysis	2158
10.34.2 Solving as second order linear constant coeff ode	2159
10.34.3 Solving using Kovacic algorithm	2161
10.34.4 Maple step by step solution	2166

Internal problem ID [11764]

Internal file name [OUTPUT/11773_Thursday_April_11_2024_08_49_32_PM_86141505/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 34.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _missing_x]]
```

$$y'' + 6y' + 58y = 0$$

With initial conditions

$$[y(0) = -1, y'(0) = 5]$$

10.34.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$p(x) = 6$$

$$q(x) = 58$$

$$F = 0$$

Hence the ode is

$$y'' + 6y' + 58y = 0$$

The domain of $p(x) = 6$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = 58$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

10.34.2 Solving as second order linear constant coeff ode

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 6, C = 58$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + 6\lambda e^{\lambda x} + 58 e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 6\lambda + 58 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 6, C = 58$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{-6}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{6^2 - (4)(1)(58)} \\ &= -3 \pm 7i \end{aligned}$$

Hence

$$\lambda_1 = -3 + 7i$$

$$\lambda_2 = -3 - 7i$$

Which simplifies to

$$\lambda_1 = -3 + 7i$$

$$\lambda_2 = -3 - 7i$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = -3$ and $\beta = 7$. Therefore the final solution, when using Euler relation, can be written as

$$y = e^{\alpha x}(c_1 \cos(\beta x) + c_2 \sin(\beta x))$$

Which becomes

$$y = e^{-3x}(c_1 \cos(7x) + c_2 \sin(7x))$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = e^{-3x}(c_1 \cos(7x) + c_2 \sin(7x)) \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = -1$ and $x = 0$ in the above gives

$$-1 = c_1 \quad (1A)$$

Taking derivative of the solution gives

$$y' = -3e^{-3x}(c_1 \cos(7x) + c_2 \sin(7x)) + e^{-3x}(-7c_1 \sin(7x) + 7c_2 \cos(7x))$$

substituting $y' = 5$ and $x = 0$ in the above gives

$$5 = -3c_1 + 7c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = -1$$

$$c_2 = \frac{2}{7}$$

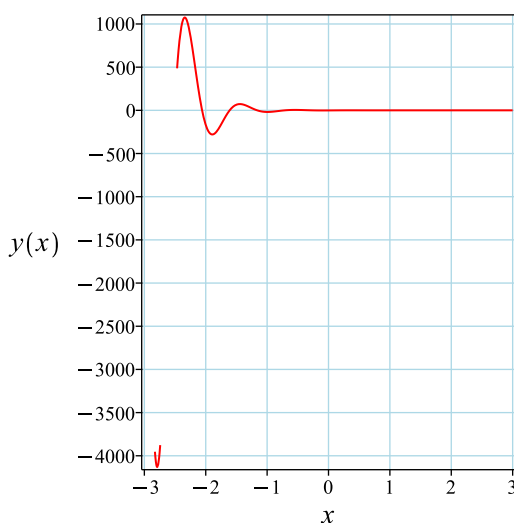
Substituting these values back in above solution results in

$$y = -\frac{e^{-3x}(7 \cos(7x) - 2 \sin(7x))}{7}$$

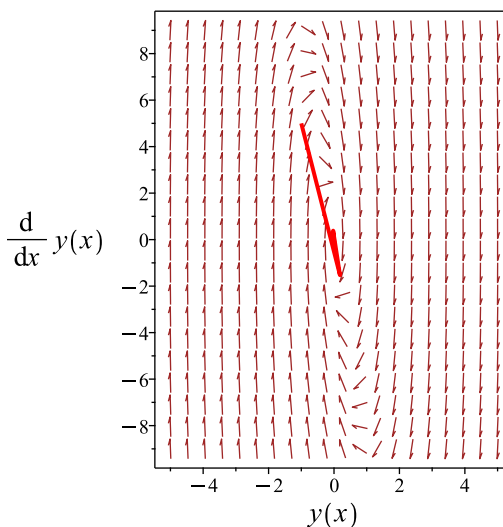
Summary

The solution(s) found are the following

$$y = -\frac{e^{-3x}(7 \cos(7x) - 2 \sin(7x))}{7} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = -\frac{e^{-3x}(7 \cos(7x) - 2 \sin(7x))}{7}$$

Verified OK.

10.34.3 Solving using Kovacic algorithm

Writing the ode as

$$y'' + 6y' + 58y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned}A &= 1 \\B &= 6 \\C &= 58\end{aligned}\tag{3}$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x)\tag{4}$$

Where r is given by

$$\begin{aligned}r &= \frac{s}{t} \\&= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2}\end{aligned}\tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-49}{1}\tag{6}$$

Comparing the above to (5) shows that

$$\begin{aligned}s &= -49 \\t &= 1\end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = -49z(x)\tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 329: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned}
 O(\infty) &= \deg(t) - \deg(s) \\
 &= 0 - 0 \\
 &= 0
 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = -49$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = \cos(7x)$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned}
 y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\
 &= z_1 e^{-\int \frac{1}{2} \frac{6}{1} dx} \\
 &= z_1 e^{-3x} \\
 &= z_1 (e^{-3x})
 \end{aligned}$$

Which simplifies to

$$y_1 = e^{-3x} \cos(7x)$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{6}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{-6x}}{(y_1)^2} dx \\ &= y_1 \left(\frac{\tan(7x)}{7} \right) \end{aligned}$$

Therefore the solution is

$$\begin{aligned} y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (e^{-3x} \cos(7x)) + c_2 \left(e^{-3x} \cos(7x) \left(\frac{\tan(7x)}{7} \right) \right) \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{-3x} \cos(7x) + \frac{c_2 e^{-3x} \sin(7x)}{7} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = -1$ and $x = 0$ in the above gives

$$-1 = c_1 \quad (1A)$$

Taking derivative of the solution gives

$$y' = -3c_1 e^{-3x} \cos(7x) - 7c_1 e^{-3x} \sin(7x) - \frac{3c_2 e^{-3x} \sin(7x)}{7} + c_2 e^{-3x} \cos(7x)$$

substituting $y' = 5$ and $x = 0$ in the above gives

$$5 = -3c_1 + c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = -1$$

$$c_2 = 2$$

Substituting these values back in above solution results in

$$y = -e^{-3x} \cos(7x) + \frac{2e^{-3x} \sin(7x)}{7}$$

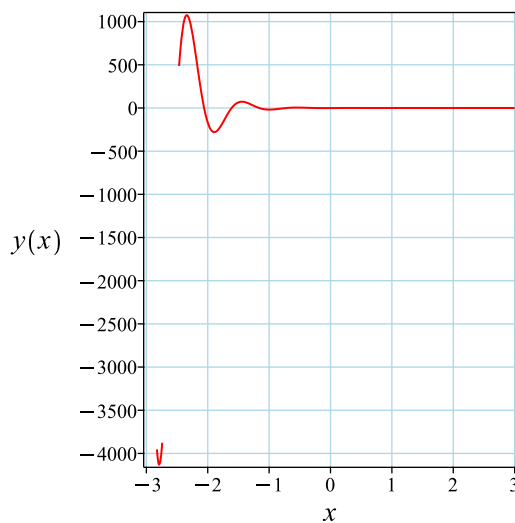
Which simplifies to

$$y = -\frac{e^{-3x}(7 \cos(7x) - 2 \sin(7x))}{7}$$

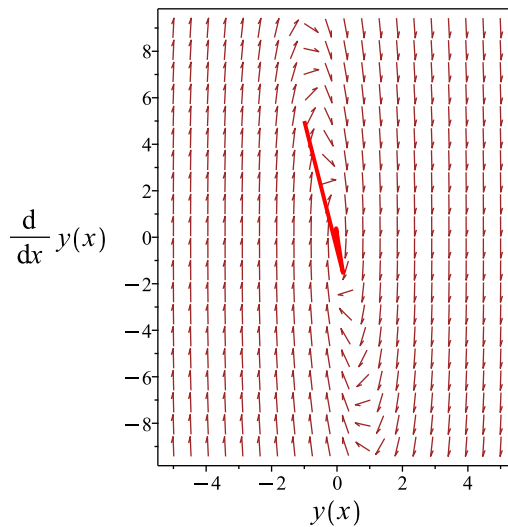
Summary

The solution(s) found are the following

$$y = -\frac{e^{-3x}(7 \cos(7x) - 2 \sin(7x))}{7} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = -\frac{e^{-3x}(7 \cos(7x) - 2 \sin(7x))}{7}$$

Verified OK.

10.34.4 Maple step by step solution

Let's solve

$$\left[y'' + 6y' + 58y = 0, y(0) = -1, y' \Big|_{\{x=0\}} = 5 \right]$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of ODE

$$r^2 + 6r + 58 = 0$$

- Use quadratic formula to solve for r

$$r = \frac{(-6) \pm (\sqrt{-196})}{2}$$

- Roots of the characteristic polynomial

$$r = (-3 - 7I, -3 + 7I)$$

- 1st solution of the ODE

$$y_1(x) = e^{-3x} \cos(7x)$$

- 2nd solution of the ODE

$$y_2(x) = e^{-3x} \sin(7x)$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x)$$

- Substitute in solutions

$$y = c_1 e^{-3x} \cos(7x) + c_2 e^{-3x} \sin(7x)$$

- Check validity of solution $y = c_1 e^{-3x} \cos(7x) + c_2 e^{-3x} \sin(7x)$

- Use initial condition $y(0) = -1$

$$-1 = c_1$$

- Compute derivative of the solution

$$y' = -3c_1 e^{-3x} \cos(7x) - 7c_1 e^{-3x} \sin(7x) - 3c_2 e^{-3x} \sin(7x) + 7c_2 e^{-3x} \cos(7x)$$

- Use the initial condition $y' \Big|_{\{x=0\}} = 5$

$$5 = -3c_1 + 7c_2$$

- Solve for c_1 and c_2

$$\left\{ c_1 = -1, c_2 = \frac{2}{7} \right\}$$

- Substitute constant values into general solution and simplify

$$y = -\frac{e^{-3x}(7\cos(7x) - 2\sin(7x))}{7}$$

- Solution to the IVP

$$y = -\frac{e^{-3x}(7\cos(7x) - 2\sin(7x))}{7}$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.031 (sec). Leaf size: 23

```
dsolve([diff(y(x),x$2)+6*diff(y(x),x)+58*y(x)=0,y(0) = -1, D(y)(0) = 5],y(x), singsol=all)
```

$$y(x) = \frac{e^{-3x}(2\sin(7x) - 7\cos(7x))}{7}$$

✓ Solution by Mathematica

Time used: 0.018 (sec). Leaf size: 27

```
DSolve[{y''[x]+6*y'[x]+58*y[x]==0,{y[0]==-1,y'[0]==5}},y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{1}{7}e^{-3x}(2\sin(7x) - 7\cos(7x))$$

10.35 problem 35

10.35.1 Existence and uniqueness analysis	2168
10.35.2 Solving as second order linear constant coeff ode	2169
10.35.3 Solving using Kovacic algorithm	2171
10.35.4 Maple step by step solution	2175

Internal problem ID [11765]

Internal file name [OUTPUT/11774_Thursday_April_11_2024_08_49_32_PM_47626021/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 35.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _missing_x]]
```

$$y'' + 6y' + 13y = 0$$

With initial conditions

$$[y(0) = 3, y'(0) = -1]$$

10.35.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$p(x) = 6$$

$$q(x) = 13$$

$$F = 0$$

Hence the ode is

$$y'' + 6y' + 13y = 0$$

The domain of $p(x) = 6$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = 13$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

10.35.2 Solving as second order linear constant coeff ode

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 6, C = 13$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + 6\lambda e^{\lambda x} + 13 e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 6\lambda + 13 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 6, C = 13$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{-6}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{6^2 - (4)(1)(13)} \\ &= -3 \pm 2i \end{aligned}$$

Hence

$$\lambda_1 = -3 + 2i$$

$$\lambda_2 = -3 - 2i$$

Which simplifies to

$$\lambda_1 = -3 + 2i$$

$$\lambda_2 = -3 - 2i$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = -3$ and $\beta = 2$. Therefore the final solution, when using Euler relation, can be written as

$$y = e^{\alpha x}(c_1 \cos(\beta x) + c_2 \sin(\beta x))$$

Which becomes

$$y = e^{-3x}(c_1 \cos(2x) + c_2 \sin(2x))$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = e^{-3x}(c_1 \cos(2x) + c_2 \sin(2x)) \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 3$ and $x = 0$ in the above gives

$$3 = c_1 \quad (1A)$$

Taking derivative of the solution gives

$$y' = -3e^{-3x}(c_1 \cos(2x) + c_2 \sin(2x)) + e^{-3x}(-2c_1 \sin(2x) + 2c_2 \cos(2x))$$

substituting $y' = -1$ and $x = 0$ in the above gives

$$-1 = -3c_1 + 2c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 3$$

$$c_2 = 4$$

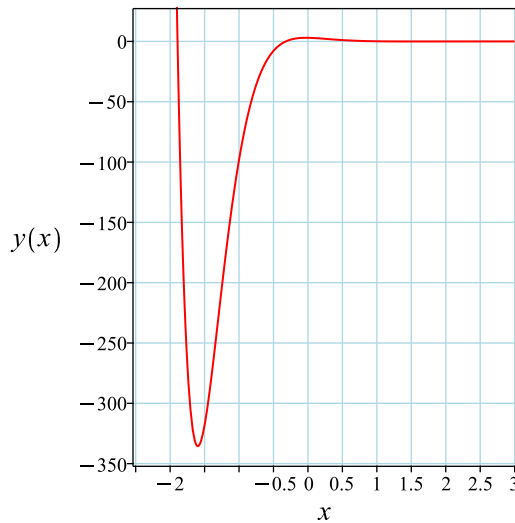
Substituting these values back in above solution results in

$$y = e^{-3x}(3 \cos(2x) + 4 \sin(2x))$$

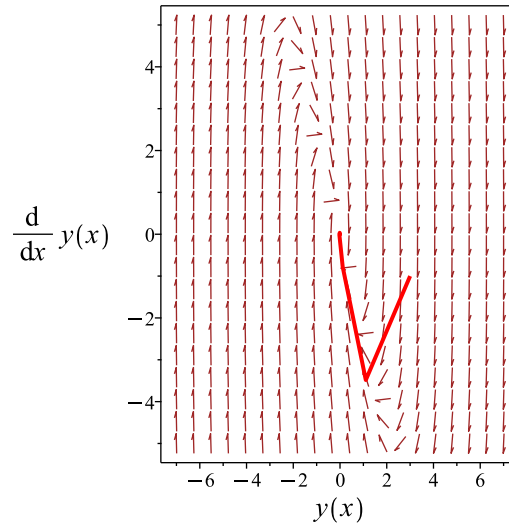
Summary

The solution(s) found are the following

$$y = e^{-3x}(3 \cos(2x) + 4 \sin(2x)) \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = e^{-3x}(3 \cos(2x) + 4 \sin(2x))$$

Verified OK.

10.35.3 Solving using Kovacic algorithm

Writing the ode as

$$y'' + 6y' + 13y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$A = 1$$

$$B = 6 \quad (3)$$

$$C = 13$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$r = \frac{s}{t} = \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-4}{1} \tag{6}$$

Comparing the above to (5) shows that

$$s = -4$$

$$t = 1$$

Therefore eq. (4) becomes

$$z''(x) = -4z(x) \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 331: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned}O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0\end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = -4$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = \cos(2x)$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned}y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{6}{1} dx} \\ &= z_1 e^{-3x} \\ &= z_1 (e^{-3x})\end{aligned}$$

Which simplifies to

$$y_1 = e^{-3x} \cos(2x)$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{6}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{-6x}}{(y_1)^2} dx \\ &= y_1 \left(\frac{\tan(2x)}{2} \right)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (e^{-3x} \cos(2x)) + c_2 \left(e^{-3x} \cos(2x) \left(\frac{\tan(2x)}{2} \right) \right)\end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{-3x} \cos(2x) + \frac{c_2 e^{-3x} \sin(2x)}{2} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 3$ and $x = 0$ in the above gives

$$3 = c_1 \quad (1A)$$

Taking derivative of the solution gives

$$y' = -3c_1 e^{-3x} \cos(2x) - 2c_1 e^{-3x} \sin(2x) - \frac{3c_2 e^{-3x} \sin(2x)}{2} + c_2 e^{-3x} \cos(2x)$$

substituting $y' = -1$ and $x = 0$ in the above gives

$$-1 = -3c_1 + c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$\begin{aligned}c_1 &= 3 \\ c_2 &= 8\end{aligned}$$

Substituting these values back in above solution results in

$$y = 3 e^{-3x} \cos(2x) + 4 e^{-3x} \sin(2x)$$

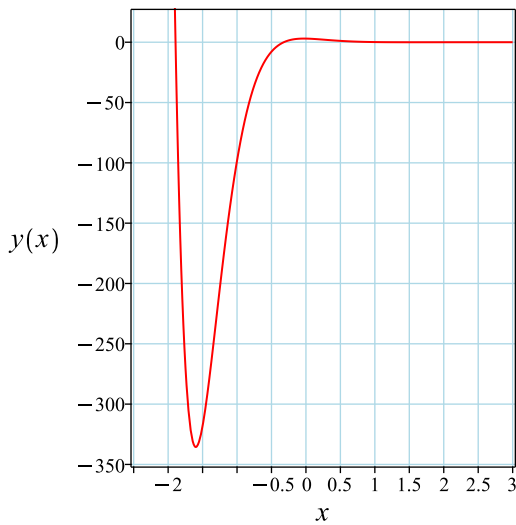
Which simplifies to

$$y = e^{-3x} (3 \cos(2x) + 4 \sin(2x))$$

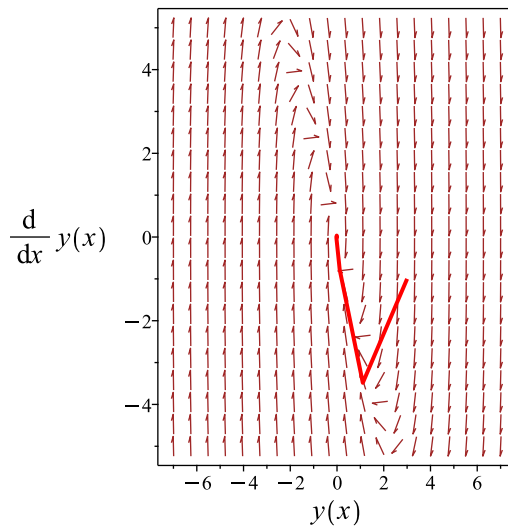
Summary

The solution(s) found are the following

$$y = e^{-3x} (3 \cos(2x) + 4 \sin(2x)) \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = e^{-3x}(3 \cos(2x) + 4 \sin(2x))$$

Verified OK.

10.35.4 Maple step by step solution

Let's solve

$$\left[y'' + 6y' + 13y = 0, y(0) = 3, y'|_{\{x=0\}} = -1 \right]$$

- Highest derivative means the order of the ODE is 2

y''

- Characteristic polynomial of ODE

$$r^2 + 6r + 13 = 0$$

- Use quadratic formula to solve for r

$$r = \frac{(-6) \pm (\sqrt{-16})}{2}$$

- Roots of the characteristic polynomial

$$r = (-3 - 2I, -3 + 2I)$$

- 1st solution of the ODE

$$y_1(x) = e^{-3x} \cos(2x)$$

- 2nd solution of the ODE

$$y_2(x) = e^{-3x} \sin(2x)$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x)$$

- Substitute in solutions

$$y = c_1 e^{-3x} \cos(2x) + c_2 e^{-3x} \sin(2x)$$

- Check validity of solution $y = c_1 e^{-3x} \cos(2x) + c_2 e^{-3x} \sin(2x)$

- Use initial condition $y(0) = 3$

$$3 = c_1$$

- Compute derivative of the solution

$$y' = -3c_1 e^{-3x} \cos(2x) - 2c_1 e^{-3x} \sin(2x) - 3c_2 e^{-3x} \sin(2x) + 2c_2 e^{-3x} \cos(2x)$$

- Use the initial condition $y' \Big|_{\{x=0\}} = -1$

$$-1 = -3c_1 + 2c_2$$

- Solve for c_1 and c_2

$$\{c_1 = 3, c_2 = 4\}$$

- Substitute constant values into general solution and simplify

$$y = e^{-3x}(3 \cos(2x) + 4 \sin(2x))$$

- Solution to the IVP

$$y = e^{-3x}(3 \cos(2x) + 4 \sin(2x))$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 22

```
dsolve([diff(y(x),x$2)+6*diff(y(x),x)+13*y(x)=0,y(0) = 3, D(y)(0) = -1],y(x), singsol=all)
```

$$y(x) = e^{-3x}(4 \sin(2x) + 3 \cos(2x))$$

✓ Solution by Mathematica

Time used: 0.018 (sec). Leaf size: 24

```
DSolve[{y''[x]+6*y'[x]+13*y[x]==0,{y[0]==3,y'[0]==-1}},y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^{-3x}(4 \sin(2x) + 3 \cos(2x))$$

10.36 problem 36

10.36.1 Existence and uniqueness analysis	2178
10.36.2 Solving as second order linear constant coeff ode	2179
10.36.3 Solving using Kovacic algorithm	2181
10.36.4 Maple step by step solution	2185

Internal problem ID [11766]

Internal file name [OUTPUT/11775_Thursday_April_11_2024_08_49_33_PM_53540331/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 36.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _missing_x]]
```

$$y'' + 2y' + 5y = 0$$

With initial conditions

$$[y(0) = 2, y'(0) = 6]$$

10.36.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$p(x) = 2$$

$$q(x) = 5$$

$$F = 0$$

Hence the ode is

$$y'' + 2y' + 5y = 0$$

The domain of $p(x) = 2$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = 5$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

10.36.2 Solving as second order linear constant coeff ode

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 2, C = 5$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + 2\lambda e^{\lambda x} + 5e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 2\lambda + 5 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 2, C = 5$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{-2}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{2^2 - (4)(1)(5)} \\ &= -1 \pm 2i \end{aligned}$$

Hence

$$\lambda_1 = -1 + 2i$$

$$\lambda_2 = -1 - 2i$$

Which simplifies to

$$\lambda_1 = -1 + 2i$$

$$\lambda_2 = -1 - 2i$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = -1$ and $\beta = 2$. Therefore the final solution, when using Euler relation, can be written as

$$y = e^{\alpha x}(c_1 \cos(\beta x) + c_2 \sin(\beta x))$$

Which becomes

$$y = e^{-x}(c_1 \cos(2x) + c_2 \sin(2x))$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = e^{-x}(c_1 \cos(2x) + c_2 \sin(2x)) \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 2$ and $x = 0$ in the above gives

$$2 = c_1 \quad (1A)$$

Taking derivative of the solution gives

$$y' = -e^{-x}(c_1 \cos(2x) + c_2 \sin(2x)) + e^{-x}(-2c_1 \sin(2x) + 2c_2 \cos(2x))$$

substituting $y' = 6$ and $x = 0$ in the above gives

$$6 = -c_1 + 2c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 2$$

$$c_2 = 4$$

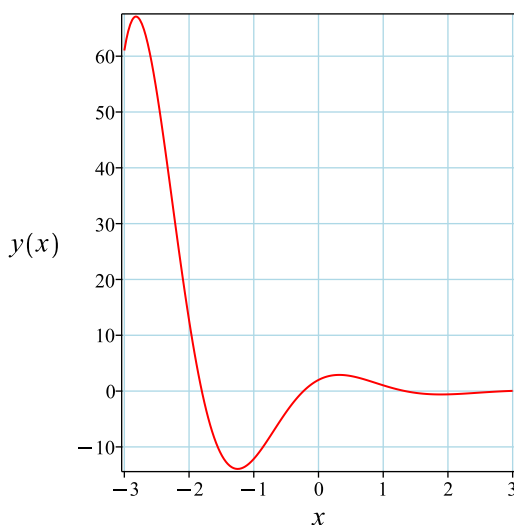
Substituting these values back in above solution results in

$$y = 2e^{-x}(\cos(2x) + 2\sin(2x))$$

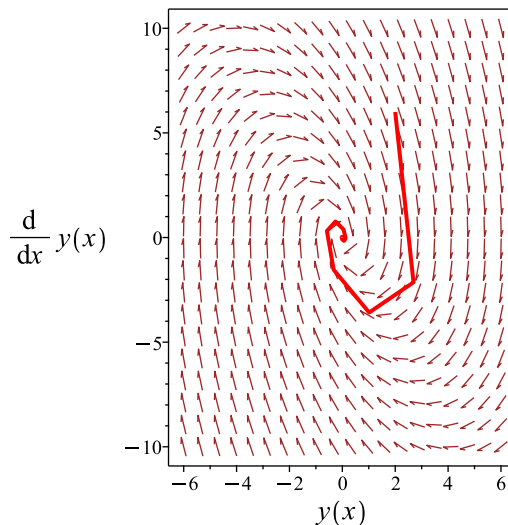
Summary

The solution(s) found are the following

$$y = 2 e^{-x}(\cos(2x) + 2 \sin(2x)) \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = 2 e^{-x}(\cos(2x) + 2 \sin(2x))$$

Verified OK.

10.36.3 Solving using Kovacic algorithm

Writing the ode as

$$y'' + 2y' + 5y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= 2 \\ C &= 5 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$r = \frac{s}{t} = \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-4}{1} \tag{6}$$

Comparing the above to (5) shows that

$$s = -4$$

$$t = 1$$

Therefore eq. (4) becomes

$$z''(x) = -4z(x) \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 333: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = -4$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = \cos(2x)$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{2}{1} dx} \\ &= z_1 e^{-x} \\ &= z_1 (e^{-x}) \end{aligned}$$

Which simplifies to

$$y_1 = e^{-x} \cos(2x)$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{2}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{-2x}}{(y_1)^2} dx \\ &= y_1 \left(\frac{\tan(2x)}{2} \right) \end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (e^{-x} \cos(2x)) + c_2 \left(e^{-x} \cos(2x) \left(\frac{\tan(2x)}{2} \right) \right)\end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{-x} \cos(2x) + \frac{c_2 e^{-x} \sin(2x)}{2} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 2$ and $x = 0$ in the above gives

$$2 = c_1 \quad (1A)$$

Taking derivative of the solution gives

$$y' = -c_1 e^{-x} \cos(2x) - 2c_1 e^{-x} \sin(2x) - \frac{c_2 e^{-x} \sin(2x)}{2} + c_2 e^{-x} \cos(2x)$$

substituting $y' = 6$ and $x = 0$ in the above gives

$$6 = -c_1 + c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$\begin{aligned}c_1 &= 2 \\ c_2 &= 8\end{aligned}$$

Substituting these values back in above solution results in

$$y = 2 e^{-x} \cos(2x) + 4 e^{-x} \sin(2x)$$

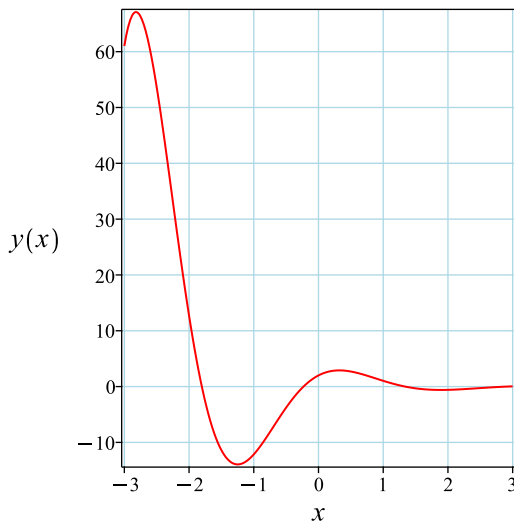
Which simplifies to

$$y = 2 e^{-x} (\cos(2x) + 2 \sin(2x))$$

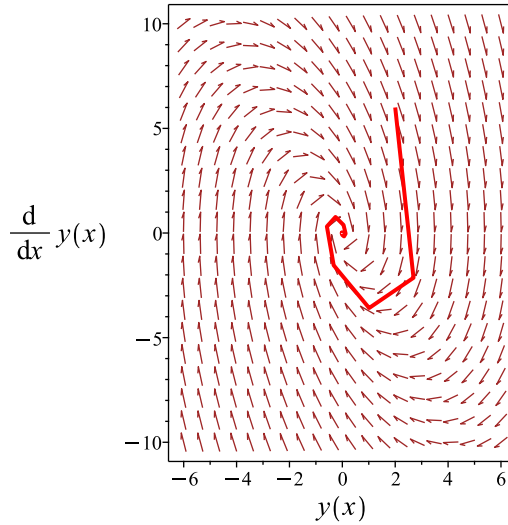
Summary

The solution(s) found are the following

$$y = 2 e^{-x} (\cos(2x) + 2 \sin(2x)) \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = 2 e^{-x} (\cos (2x) + 2 \sin (2x))$$

Verified OK.

10.36.4 Maple step by step solution

Let's solve

$$\left[y'' + 2y' + 5y = 0, y(0) = 2, y' \Big|_{\{x=0\}} = 6 \right]$$

- Highest derivative means the order of the ODE is 2
- y''
- Characteristic polynomial of ODE
- $r^2 + 2r + 5 = 0$
- Use quadratic formula to solve for r
- $r = \frac{(-2) \pm (\sqrt{-16})}{2}$
- Roots of the characteristic polynomial
- $r = (-1 - 2I, -1 + 2I)$
- 1st solution of the ODE

$$y_1(x) = e^{-x} \cos(2x)$$

- 2nd solution of the ODE

$$y_2(x) = e^{-x} \sin(2x)$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x)$$

- Substitute in solutions

$$y = c_1 e^{-x} \cos(2x) + c_2 e^{-x} \sin(2x)$$

- Check validity of solution $y = c_1 e^{-x} \cos(2x) + c_2 e^{-x} \sin(2x)$

- Use initial condition $y(0) = 2$

$$2 = c_1$$

- Compute derivative of the solution

$$y' = -c_1 e^{-x} \cos(2x) - 2c_1 e^{-x} \sin(2x) - c_2 e^{-x} \sin(2x) + 2c_2 e^{-x} \cos(2x)$$

- Use the initial condition $y' \Big|_{\{x=0\}} = 6$

$$6 = -c_1 + 2c_2$$

- Solve for c_1 and c_2

$$\{c_1 = 2, c_2 = 4\}$$

- Substitute constant values into general solution and simplify

$$y = 2 e^{-x} (\cos(2x) + 2 \sin(2x))$$

- Solution to the IVP

$$y = 2 e^{-x} (\cos(2x) + 2 \sin(2x))$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 21

```
dsolve([diff(y(x),x$2)+2*diff(y(x),x)+5*y(x)=0,y(0) = 2, D(y)(0) = 6],y(x), singsol=all)
```

$$y(x) = 2e^{-x}(2\sin(2x) + \cos(2x))$$

✓ Solution by Mathematica

Time used: 0.017 (sec). Leaf size: 23

```
DSolve[{y'[x]+2*y'[x]+5*y[x]==0,{y[0]==2,y'[0]==6}},y[x],x,IncludeSingularSolutions -> True
```

$$y(x) \rightarrow 2e^{-x}(2\sin(2x) + \cos(2x))$$

10.37 problem 37

10.37.1 Existence and uniqueness analysis	2188
10.37.2 Solving as second order linear constant coeff ode	2189
10.37.3 Solving using Kovacic algorithm	2192
10.37.4 Maple step by step solution	2196

Internal problem ID [11767]

Internal file name [OUTPUT/11776_Thursday_April_11_2024_08_49_34_PM_41951789/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 37.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _missing_x]]
```

$$9y'' + 6y' + 5y = 0$$

With initial conditions

$$[y(0) = 6, y'(0) = 0]$$

10.37.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$p(x) = \frac{2}{3}$$
$$q(x) = \frac{5}{9}$$
$$F = 0$$

Hence the ode is

$$y'' + \frac{2y'}{3} + \frac{5y}{9} = 0$$

The domain of $p(x) = \frac{2}{3}$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = \frac{5}{9}$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

10.37.2 Solving as second order linear constant coeff ode

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 9, B = 6, C = 5$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$9\lambda^2 e^{\lambda x} + 6\lambda e^{\lambda x} + 5e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$9\lambda^2 + 6\lambda + 5 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 9, B = 6, C = 5$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{-6}{(2)(9)} \pm \frac{1}{(2)(9)} \sqrt{6^2 - (4)(9)(5)} \\ &= -\frac{1}{3} \pm \frac{2i}{3} \end{aligned}$$

Hence

$$\begin{aligned} \lambda_1 &= -\frac{1}{3} + \frac{2i}{3} \\ \lambda_2 &= -\frac{1}{3} - \frac{2i}{3} \end{aligned}$$

Which simplifies to

$$\lambda_1 = -\frac{1}{3} + \frac{2i}{3}$$
$$\lambda_2 = -\frac{1}{3} - \frac{2i}{3}$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = -\frac{1}{3}$ and $\beta = \frac{2}{3}$. Therefore the final solution, when using Euler relation, can be written as

$$y = e^{\alpha x}(c_1 \cos(\beta x) + c_2 \sin(\beta x))$$

Which becomes

$$y = e^{-\frac{x}{3}} \left(c_1 \cos \left(\frac{2x}{3} \right) + c_2 \sin \left(\frac{2x}{3} \right) \right)$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = e^{-\frac{x}{3}} \left(c_1 \cos \left(\frac{2x}{3} \right) + c_2 \sin \left(\frac{2x}{3} \right) \right) \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 6$ and $x = 0$ in the above gives

$$6 = c_1 \quad (1A)$$

Taking derivative of the solution gives

$$y' = -\frac{e^{-\frac{x}{3}}(c_1 \cos(\frac{2x}{3}) + c_2 \sin(\frac{2x}{3}))}{3} + e^{-\frac{x}{3}} \left(-\frac{2c_1 \sin(\frac{2x}{3})}{3} + \frac{2c_2 \cos(\frac{2x}{3})}{3} \right)$$

substituting $y' = 0$ and $x = 0$ in the above gives

$$0 = -\frac{c_1}{3} + \frac{2c_2}{3} \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 6$$

$$c_2 = 3$$

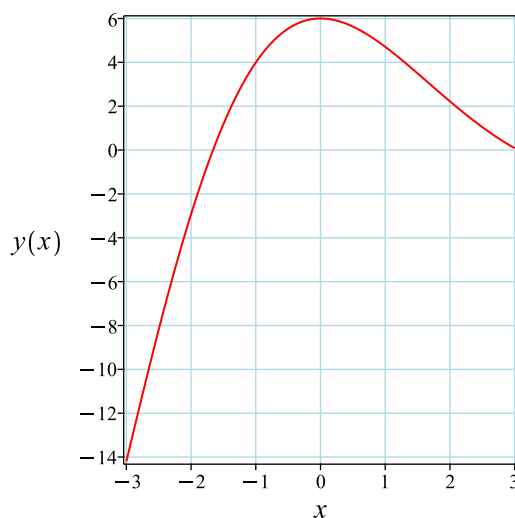
Substituting these values back in above solution results in

$$y = 3 e^{-\frac{2x}{3}} \left(2 \cos \left(\frac{2x}{3} \right) + \sin \left(\frac{2x}{3} \right) \right)$$

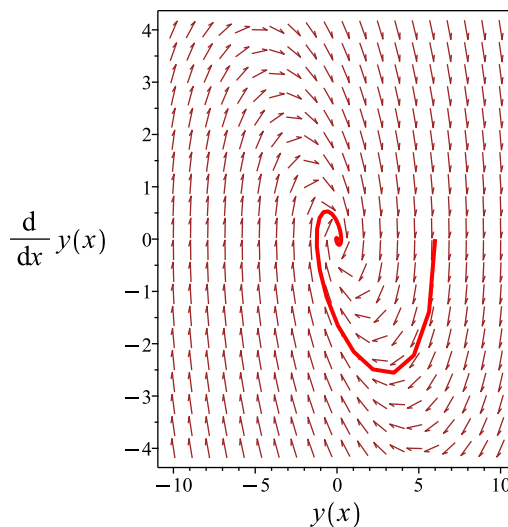
Summary

The solution(s) found are the following

$$y = 3 e^{-\frac{2x}{3}} \left(2 \cos \left(\frac{2x}{3} \right) + \sin \left(\frac{2x}{3} \right) \right) \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = 3 e^{-\frac{2x}{3}} \left(2 \cos \left(\frac{2x}{3} \right) + \sin \left(\frac{2x}{3} \right) \right)$$

Verified OK.

10.37.3 Solving using Kovacic algorithm

Writing the ode as

$$9y'' + 6y' + 5y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 9 \\ B &= 6 \end{aligned} \quad (3)$$

$$C = 5$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-4}{9} \quad (6)$$

Comparing the above to (5) shows that

$$s = -4$$

$$t = 9$$

Therefore eq. (4) becomes

$$z''(x) = -\frac{4z(x)}{9} \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 335: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = -\frac{4}{9}$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = \cos\left(\frac{2x}{3}\right)$$

Using the above, the solution for the original ode can now be found. The first solution

to the original ode in y is found from

$$\begin{aligned}y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\&= z_1 e^{-\int \frac{1}{2} \frac{6}{9} dx} \\&= z_1 e^{-\frac{x}{3}} \\&= z_1 \left(e^{-\frac{x}{3}} \right)\end{aligned}$$

Which simplifies to

$$y_1 = e^{-\frac{x}{3}} \cos\left(\frac{2x}{3}\right)$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{6}{9} dx}}{(y_1)^2} dx \\&= y_1 \int \frac{e^{-\frac{2x}{3}}}{(y_1)^2} dx \\&= y_1 \left(\frac{3 \tan\left(\frac{2x}{3}\right)}{2} \right)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\&= c_1 \left(e^{-\frac{x}{3}} \cos\left(\frac{2x}{3}\right) \right) + c_2 \left(e^{-\frac{x}{3}} \cos\left(\frac{2x}{3}\right) \left(\frac{3 \tan\left(\frac{2x}{3}\right)}{2} \right) \right)\end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{-\frac{x}{3}} \cos\left(\frac{2x}{3}\right) + \frac{3c_2 e^{-\frac{x}{3}} \sin\left(\frac{2x}{3}\right)}{2} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 6$ and $x = 0$ in the above gives

$$6 = c_1 \tag{1A}$$

Taking derivative of the solution gives

$$y' = -\frac{c_1 e^{-\frac{x}{3}} \cos\left(\frac{2x}{3}\right)}{3} - \frac{2c_1 e^{-\frac{x}{3}} \sin\left(\frac{2x}{3}\right)}{3} - \frac{c_2 e^{-\frac{x}{3}} \sin\left(\frac{2x}{3}\right)}{2} + c_2 e^{-\frac{x}{3}} \cos\left(\frac{2x}{3}\right)$$

substituting $y' = 0$ and $x = 0$ in the above gives

$$0 = -\frac{c_1}{3} + c_2 \tag{2A}$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 6$$

$$c_2 = 2$$

Substituting these values back in above solution results in

$$y = 6 e^{-\frac{x}{3}} \cos\left(\frac{2x}{3}\right) + 3 e^{-\frac{x}{3}} \sin\left(\frac{2x}{3}\right)$$

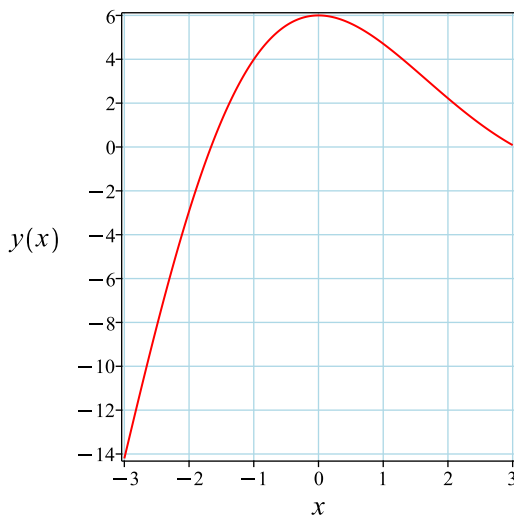
Which simplifies to

$$y = 3 e^{-\frac{x}{3}} \left(2 \cos\left(\frac{2x}{3}\right) + \sin\left(\frac{2x}{3}\right) \right)$$

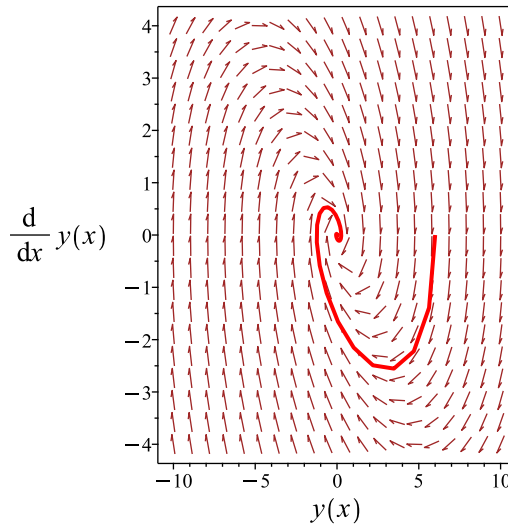
Summary

The solution(s) found are the following

$$y = 3 e^{-\frac{x}{3}} \left(2 \cos\left(\frac{2x}{3}\right) + \sin\left(\frac{2x}{3}\right) \right) \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = 3 e^{-\cos \frac{x}{3}} \left(2 \cos \left(\frac{2x}{3} \right) + \sin \left(\frac{2x}{3} \right) \right)$$

Verified OK.

10.37.4 Maple step by step solution

Let's solve

$$\left[9y'' + 6y' + 5y = 0, y(0) = 6, y' \Big|_{\{x=0\}} = 0 \right]$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = -\frac{2y'}{3} - \frac{5y}{9}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + \frac{2y'}{3} + \frac{5y}{9} = 0$$

- Characteristic polynomial of ODE

$$r^2 + \frac{2}{3}r + \frac{5}{9} = 0$$

- Use quadratic formula to solve for r

$$r = \frac{(-\frac{2}{3}) \pm (\sqrt{-\frac{16}{9}})}{2}$$

- Roots of the characteristic polynomial

$$r = (-\frac{1}{3} - \frac{2i}{3}, -\frac{1}{3} + \frac{2i}{3})$$

- 1st solution of the ODE

$$y_1(x) = e^{-\frac{x}{3}} \cos\left(\frac{2x}{3}\right)$$

- 2nd solution of the ODE

$$y_2(x) = e^{-\frac{x}{3}} \sin\left(\frac{2x}{3}\right)$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x)$$

- Substitute in solutions

$$y = c_1 e^{-\frac{x}{3}} \cos\left(\frac{2x}{3}\right) + c_2 e^{-\frac{x}{3}} \sin\left(\frac{2x}{3}\right)$$

- Check validity of solution $y = c_1 e^{-\frac{x}{3}} \cos\left(\frac{2x}{3}\right) + c_2 e^{-\frac{x}{3}} \sin\left(\frac{2x}{3}\right)$

- Use initial condition $y(0) = 6$

$$6 = c_1$$

- Compute derivative of the solution

$$y' = -\frac{c_1 e^{-\frac{x}{3}} \cos\left(\frac{2x}{3}\right)}{3} - \frac{2c_1 e^{-\frac{x}{3}} \sin\left(\frac{2x}{3}\right)}{3} - \frac{c_2 e^{-\frac{x}{3}} \sin\left(\frac{2x}{3}\right)}{3} + \frac{2c_2 e^{-\frac{x}{3}} \cos\left(\frac{2x}{3}\right)}{3}$$

- Use the initial condition $y' \Big|_{\{x=0\}} = 0$

$$0 = -\frac{c_1}{3} + \frac{2c_2}{3}$$

- Solve for c_1 and c_2

$$\{c_1 = 6, c_2 = 3\}$$

- Substitute constant values into general solution and simplify

$$y = 3 e^{-\frac{x}{3}} \left(2 \cos\left(\frac{2x}{3}\right) + \sin\left(\frac{2x}{3}\right) \right)$$

- Solution to the IVP

$$y = 3 e^{-\frac{x}{3}} \left(2 \cos\left(\frac{2x}{3}\right) + \sin\left(\frac{2x}{3}\right) \right)$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
<- constant coefficients successful`
```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 21

```
dsolve([9*dif(y(x),x$2)+6*dif(y(x),x)+5*y(x)=0,y(0) = 6, D(y)(0) = 0],y(x), singsol=all)
```

$$y(x) = 3e^{-\frac{x}{3}} \left(\sin\left(\frac{2x}{3}\right) + 2 \cos\left(\frac{2x}{3}\right) \right)$$

✓ Solution by Mathematica

Time used: 0.019 (sec). Leaf size: 29

```
DSolve[{9*y''[x]+6*y'[x]+5*y[x]==0,{y[0]==6,y'[0]==0}},y[x],x,IncludeSingularSolutions -> Tr
```

$$y(x) \rightarrow 3e^{-x/3} \left(\sin\left(\frac{2x}{3}\right) + 2 \cos\left(\frac{2x}{3}\right) \right)$$

10.38 problem 38

10.38.1 Existence and uniqueness analysis	2199
10.38.2 Solving as second order linear constant coeff ode	2200
10.38.3 Solving using Kovacic algorithm	2202
10.38.4 Maple step by step solution	2207

Internal problem ID [11768]

Internal file name [OUTPUT/11777_Thursday_April_11_2024_08_49_34_PM_8249898/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 38.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _missing_x]]
```

$$4y'' + 4y' + 37y = 0$$

With initial conditions

$$[y(0) = 2, y'(0) = -4]$$

10.38.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$\begin{aligned} p(x) &= 1 \\ q(x) &= \frac{37}{4} \\ F &= 0 \end{aligned}$$

Hence the ode is

$$y'' + y' + \frac{37y}{4} = 0$$

The domain of $p(x) = 1$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = \frac{37}{4}$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

10.38.2 Solving as second order linear constant coeff ode

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 4, B = 4, C = 37$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$4\lambda^2 e^{\lambda x} + 4\lambda e^{\lambda x} + 37 e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$4\lambda^2 + 4\lambda + 37 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 4, B = 4, C = 37$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{-4}{(2)(4)} \pm \frac{1}{(2)(4)} \sqrt{4^2 - (4)(4)(37)} \\ &= -\frac{1}{2} \pm 3i \end{aligned}$$

Hence

$$\begin{aligned} \lambda_1 &= -\frac{1}{2} + 3i \\ \lambda_2 &= -\frac{1}{2} - 3i \end{aligned}$$

Which simplifies to

$$\lambda_1 = -\frac{1}{2} + 3i$$

$$\lambda_2 = -\frac{1}{2} - 3i$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = -\frac{1}{2}$ and $\beta = 3$. Therefore the final solution, when using Euler relation, can be written as

$$y = e^{\alpha x}(c_1 \cos(\beta x) + c_2 \sin(\beta x))$$

Which becomes

$$y = e^{-\frac{x}{2}}(c_1 \cos(3x) + c_2 \sin(3x))$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = e^{-\frac{x}{2}}(c_1 \cos(3x) + c_2 \sin(3x)) \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 2$ and $x = 0$ in the above gives

$$2 = c_1 \quad (1A)$$

Taking derivative of the solution gives

$$y' = -\frac{e^{-\frac{x}{2}}(c_1 \cos(3x) + c_2 \sin(3x))}{2} + e^{-\frac{x}{2}}(-3c_1 \sin(3x) + 3c_2 \cos(3x))$$

substituting $y' = -4$ and $x = 0$ in the above gives

$$-4 = -\frac{c_1}{2} + 3c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 2$$

$$c_2 = -1$$

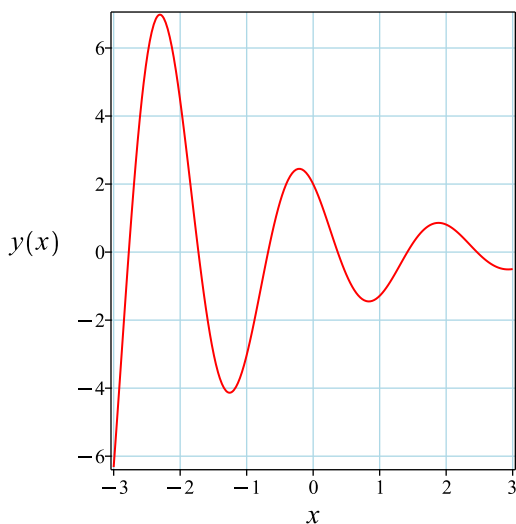
Substituting these values back in above solution results in

$$y = e^{-\frac{x}{2}}(2 \cos(3x) - \sin(3x))$$

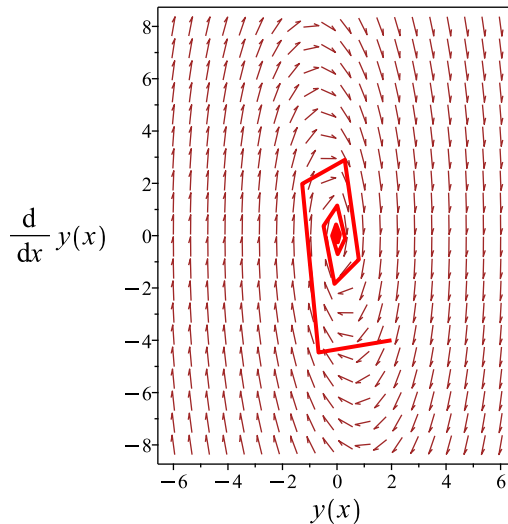
Summary

The solution(s) found are the following

$$y = e^{-\frac{x}{2}}(2 \cos(3x) - \sin(3x)) \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = e^{-\frac{x}{2}}(2 \cos(3x) - \sin(3x))$$

Verified OK.

10.38.3 Solving using Kovacic algorithm

Writing the ode as

$$4y'' + 4y' + 37y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$A = 4$$

$$B = 4$$

$$C = 37$$

(3)

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-9}{1} \tag{6}$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= -9 \\ t &= 1 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = -9z(x) \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 337: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned}
 \mathcal{O}(\infty) &= \deg(t) - \deg(s) \\
 &= 0 - 0 \\
 &= 0
 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = -9$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = \cos(3x)$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned}
 y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\
 &= z_1 e^{-\int \frac{1}{2} \frac{4}{4} dx} \\
 &= z_1 e^{-\frac{x}{2}} \\
 &= z_1 \left(e^{-\frac{x}{2}} \right)
 \end{aligned}$$

Which simplifies to

$$y_1 = e^{-\frac{x}{2}} \cos(3x)$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{4}{4} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{-x}}{(y_1)^2} dx \\ &= y_1 \left(\frac{\tan(3x)}{3} \right) \end{aligned}$$

Therefore the solution is

$$\begin{aligned} y &= c_1 y_1 + c_2 y_2 \\ &= c_1 \left(e^{-\frac{x}{2}} \cos(3x) \right) + c_2 \left(e^{-\frac{x}{2}} \cos(3x) \left(\frac{\tan(3x)}{3} \right) \right) \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{-\frac{x}{2}} \cos(3x) + \frac{c_2 e^{-\frac{x}{2}} \sin(3x)}{3} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 2$ and $x = 0$ in the above gives

$$2 = c_1 \quad (1A)$$

Taking derivative of the solution gives

$$y' = -\frac{c_1 e^{-\frac{x}{2}} \cos(3x)}{2} - 3c_1 e^{-\frac{x}{2}} \sin(3x) - \frac{c_2 e^{-\frac{x}{2}} \sin(3x)}{6} + c_2 e^{-\frac{x}{2}} \cos(3x)$$

substituting $y' = -4$ and $x = 0$ in the above gives

$$-4 = -\frac{c_1}{2} + c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$\begin{aligned} c_1 &= 2 \\ c_2 &= -3 \end{aligned}$$

Substituting these values back in above solution results in

$$y = 2e^{-\frac{x}{2}} \cos(3x) - e^{-\frac{x}{2}} \sin(3x)$$

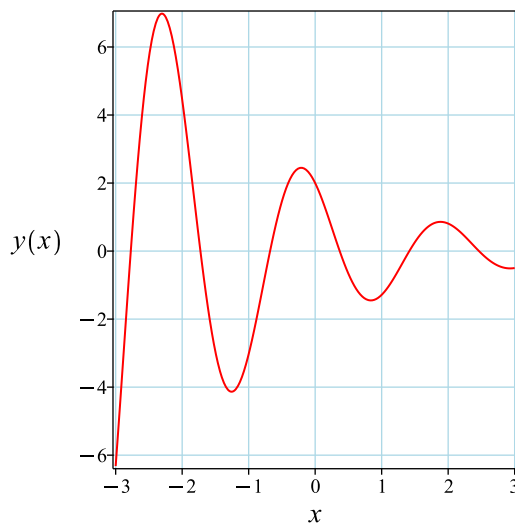
Which simplifies to

$$y = e^{-\frac{x}{2}} (2 \cos(3x) - \sin(3x))$$

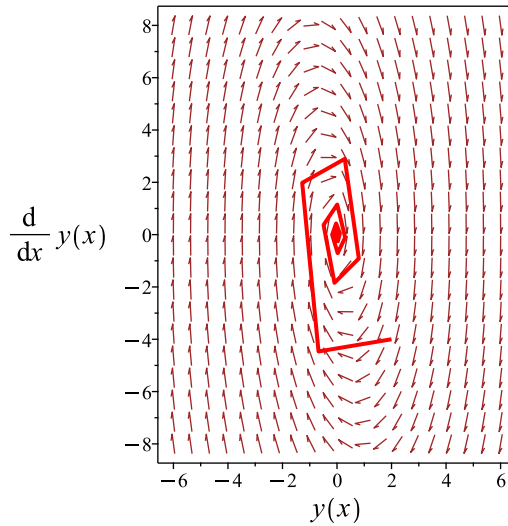
Summary

The solution(s) found are the following

$$y = e^{-\frac{x}{2}} (2 \cos(3x) - \sin(3x)) \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = e^{-\frac{x}{2}} (2 \cos(3x) - \sin(3x))$$

Verified OK.

10.38.4 Maple step by step solution

Let's solve

$$\left[4y'' + 4y' + 37y = 0, y(0) = 2, y'|_{\{x=0\}} = -4 \right]$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = -y' - \frac{37y}{4}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + y' + \frac{37y}{4} = 0$$

- Characteristic polynomial of ODE

$$r^2 + r + \frac{37}{4} = 0$$

- Use quadratic formula to solve for r

$$r = \frac{(-1) \pm (\sqrt{-36})}{2}$$

- Roots of the characteristic polynomial

$$r = \left(-\frac{1}{2} - 3\text{I}, -\frac{1}{2} + 3\text{I} \right)$$

- 1st solution of the ODE

$$y_1(x) = e^{-\frac{x}{2}} \cos(3x)$$

- 2nd solution of the ODE

$$y_2(x) = e^{-\frac{x}{2}} \sin(3x)$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x)$$

- Substitute in solutions

$$y = c_1 e^{-\frac{x}{2}} \cos(3x) + c_2 e^{-\frac{x}{2}} \sin(3x)$$

- Check validity of solution $y = c_1 e^{-\frac{x}{2}} \cos(3x) + c_2 e^{-\frac{x}{2}} \sin(3x)$

- Use initial condition $y(0) = 2$

$$2 = c_1$$

- Compute derivative of the solution

$$y' = -\frac{c_1 e^{-\frac{x}{2}} \cos(3x)}{2} - 3c_1 e^{-\frac{x}{2}} \sin(3x) - \frac{c_2 e^{-\frac{x}{2}} \sin(3x)}{2} + 3c_2 e^{-\frac{x}{2}} \cos(3x)$$

- Use the initial condition $y' \Big|_{\{x=0\}} = -4$

$$-4 = -\frac{c_1}{2} + 3c_2$$
- Solve for c_1 and c_2

$$\{c_1 = 2, c_2 = -1\}$$
- Substitute constant values into general solution and simplify
$$y = e^{-\frac{x}{2}}(2 \cos(3x) - \sin(3x))$$
- Solution to the IVP
$$y = e^{-\frac{x}{2}}(2 \cos(3x) - \sin(3x))$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 22

```
dsolve([4*diff(y(x),x$2)+4*diff(y(x),x)+37*y(x)=0,y(0) = 2, D(y)(0) = -4],y(x), singsol=all)
```

$$y(x) = e^{-\frac{x}{2}}(-\sin(3x) + 2 \cos(3x))$$

✓ Solution by Mathematica

Time used: 0.017 (sec). Leaf size: 26

```
DSolve[{4*y''[x]+4*y'[x]+37*y[x]==0,{y[0]==2,y'[0]==-4}},y[x],x,IncludeSingularSolutions ->
```

$$y(x) \rightarrow e^{-x/2}(2 \cos(3x) - \sin(3x))$$

10.39 problem 39

10.39.1 Maple step by step solution 2211

Internal problem ID [11769]

Internal file name [OUTPUT/11778_Thursday_April_11_2024_08_49_35_PM_59199865/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 39.

ODE order: 3.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_3rd_order , _missing_x]]
```

$$y''' - 6y'' + 11y' - 6y = 0$$

With initial conditions

$$[y(0) = 0, y'(0) = 0, y''(0) = 2]$$

The characteristic equation is

$$\lambda^3 - 6\lambda^2 + 11\lambda - 6 = 0$$

The roots of the above equation are

$$\lambda_1 = 1$$

$$\lambda_2 = 2$$

$$\lambda_3 = 3$$

Therefore the homogeneous solution is

$$y_h(x) = e^x c_1 + c_2 e^{2x} + c_3 e^{3x}$$

The fundamental set of solutions for the homogeneous solution are the following

$$\begin{aligned}y_1 &= e^x \\y_2 &= e^{2x} \\y_3 &= e^{3x}\end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = e^x c_1 + c_2 e^{2x} + c_3 e^{3x} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 0$ and $x = 0$ in the above gives

$$0 = c_1 + c_2 + c_3 \quad (1A)$$

Taking derivative of the solution gives

$$y' = e^x c_1 + 2c_2 e^{2x} + 3c_3 e^{3x}$$

substituting $y' = 0$ and $x = 0$ in the above gives

$$0 = c_1 + 2c_2 + 3c_3 \quad (2A)$$

Taking two derivatives of the solution gives

$$y'' = e^x c_1 + 4c_2 e^{2x} + 9c_3 e^{3x}$$

substituting $y'' = 2$ and $x = 0$ in the above gives

$$2 = c_1 + 4c_2 + 9c_3 \quad (3A)$$

Equations {1A,2A,3A} are now solved for $\{c_1, c_2, c_3\}$. Solving for the constants gives

$$\begin{aligned}c_1 &= 1 \\c_2 &= -2 \\c_3 &= 1\end{aligned}$$

Substituting these values back in above solution results in

$$y = e^x - 2e^{2x} + e^{3x}$$

Summary

The solution(s) found are the following

$$y = e^x - 2e^{2x} + e^{3x} \quad (1)$$

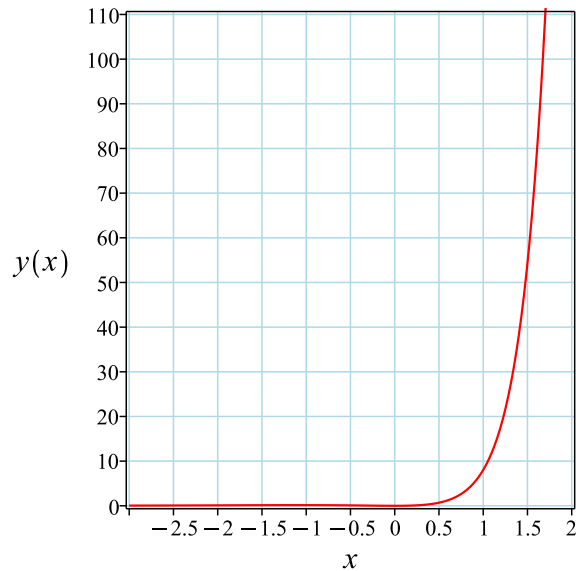


Figure 413: Solution plot

Verification of solutions

$$y = e^x - 2e^{2x} + e^{3x}$$

Verified OK.

10.39.1 Maple step by step solution

Let's solve

$$\left[y''' - 6y'' + 11y' - 6y = 0, y(0) = 0, y' \Big|_{\{x=0\}} = 0, y'' \Big|_{\{x=0\}} = 2 \right]$$

- Highest derivative means the order of the ODE is 3
 y'''
- Convert linear ODE into a system of first order ODEs
 - Define new variable $y_1(x)$
 $y_1(x) = y$
 - Define new variable $y_2(x)$

$$y_2(x) = y'$$

- Define new variable $y_3(x)$

$$y_3(x) = y''$$

- Isolate for $y_3'(x)$ using original ODE

$$y_3'(x) = 6y_3(x) - 11y_2(x) + 6y_1(x)$$

Convert linear ODE into a system of first order ODEs

$$[y_2(x) = y_1'(x), y_3(x) = y_2'(x), y_3'(x) = 6y_3(x) - 11y_2(x) + 6y_1(x)]$$

- Define vector

$$\vec{y}(x) = \begin{bmatrix} y_1(x) \\ y_2(x) \\ y_3(x) \end{bmatrix}$$

- System to solve

$$\vec{y}'(x) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 6 & -11 & 6 \end{bmatrix} \cdot \vec{y}(x)$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 6 & -11 & 6 \end{bmatrix}$$

- Rewrite the system as

$$\vec{y}'(x) = A \cdot \vec{y}(x)$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[1, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right], \left[2, \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right], \left[3, \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[1, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_1 = e^x \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[2, \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_2 = e^{2x} \cdot \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[3, \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_3 = e^{3x} \cdot \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix}$$

- General solution to the system of ODEs

$$\vec{y} = c_1 \vec{y}_1 + c_2 \vec{y}_2 + c_3 \vec{y}_3$$

- Substitute solutions into the general solution

$$\vec{y} = e^x c_1 \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + c_2 e^{2x} \cdot \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} + c_3 e^{3x} \cdot \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y = e^x c_1 + \frac{c_2 e^{2x}}{4} + \frac{c_3 e^{3x}}{9}$$

- Use the initial condition $y(0) = 0$

$$0 = c_1 + \frac{c_2}{4} + \frac{c_3}{9}$$

- Calculate the 1st derivative of the solution

$$y' = e^x c_1 + \frac{c_2 e^{2x}}{2} + \frac{c_3 e^{3x}}{3}$$

- Use the initial condition $y'|_{\{x=0\}} = 0$

$$0 = c_1 + \frac{c_2}{2} + \frac{c_3}{3}$$

- Calculate the 2nd derivative of the solution

$$y'' = e^x c_1 + c_2 e^{2x} + c_3 e^{3x}$$

- Use the initial condition $y''|_{\{x=0\}} = 2$

$$2 = c_1 + c_2 + c_3$$

- Solve for the unknown coefficients

$$\{c_1 = 1, c_2 = -8, c_3 = 9\}$$

- Solution to the IVP

$$y = e^x - 2e^{2x} + e^{3x}$$

Maple trace

```

`Methods for third order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 17

```
dsolve([diff(y(x),x$3)-6*diff(y(x),x$2)+11*diff(y(x),x)-6*y(x)=0,y(0) = 0, D(y)(0) = 0, (D@@
```

$$y(x) = e^x - 2e^{2x} + e^{3x}$$

✓ Solution by Mathematica

Time used: 0.003 (sec). Leaf size: 16

```
DSolve[{y'''[x]-6*y''[x]+11*y'[x]-6*y[x]==0,{y[0]==0,y'[0]==0,y''[0]==2}},y[x],x,IncludeSing
```

$$y(x) \rightarrow e^x(e^x - 1)^2$$

10.40 problem 40

10.40.1 Maple step by step solution 2218

Internal problem ID [11770]

Internal file name [OUTPUT/11779_Thursday_April_11_2024_08_49_35_PM_64211150/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 40.

ODE order: 3.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_3rd_order , _missing_x]]
```

$$y''' - 2y'' + 4y' - 8y = 0$$

With initial conditions

$$[y(0) = 2, y'(0) = 0, y''(0) = 0]$$

The characteristic equation is

$$\lambda^3 - 2\lambda^2 + 4\lambda - 8 = 0$$

The roots of the above equation are

$$\lambda_1 = 2$$

$$\lambda_2 = 2i$$

$$\lambda_3 = -2i$$

Therefore the homogeneous solution is

$$y_h(x) = c_1 e^{2x} + e^{2ix} c_2 + e^{-2ix} c_3$$

The fundamental set of solutions for the homogeneous solution are the following

$$\begin{aligned}y_1 &= e^{2x} \\y_2 &= e^{2ix} \\y_3 &= e^{-2ix}\end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{2x} + e^{2ix} c_2 + e^{-2ix} c_3 \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 2$ and $x = 0$ in the above gives

$$2 = c_1 + c_2 + c_3 \quad (1A)$$

Taking derivative of the solution gives

$$y' = 2c_1 e^{2x} + 2ie^{2ix} c_2 - 2ie^{-2ix} c_3$$

substituting $y' = 0$ and $x = 0$ in the above gives

$$0 = 2c_2 i - 2c_3 i + 2c_1 \quad (2A)$$

Taking two derivatives of the solution gives

$$y'' = 4c_1 e^{2x} - 4e^{2ix} c_2 - 4e^{-2ix} c_3$$

substituting $y'' = 0$ and $x = 0$ in the above gives

$$0 = 4c_1 - 4c_2 - 4c_3 \quad (3A)$$

Equations {1A,2A,3A} are now solved for $\{c_1, c_2, c_3\}$. Solving for the constants gives

$$\begin{aligned}c_1 &= 1 \\c_2 &= \frac{1}{2} + \frac{i}{2} \\c_3 &= \frac{1}{2} - \frac{i}{2}\end{aligned}$$

Substituting these values back in above solution results in

$$y = e^{2x} + \cos(2x) - \sin(2x)$$

Summary

The solution(s) found are the following

$$y = e^{2x} + \cos(2x) - \sin(2x) \quad (1)$$

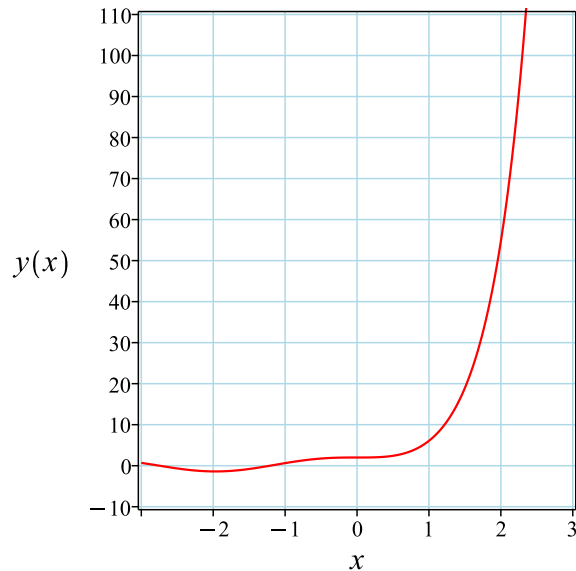


Figure 414: Solution plot

Verification of solutions

$$y = e^{2x} + \cos(2x) - \sin(2x)$$

Verified OK.

10.40.1 Maple step by step solution

Let's solve

$$\left[y''' - 2y'' + 4y' - 8y = 0, y(0) = 2, y'|_{\{x=0\}} = 0, y''|_{\{x=0\}} = 0 \right]$$

- Highest derivative means the order of the ODE is 3

y'''

- Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(x)$

$$y_1(x) = y$$

- Define new variable $y_2(x)$

$$y_2(x) = y'$$

- Define new variable $y_3(x)$

$$y_3(x) = y''$$

- Isolate for $y_3'(x)$ using original ODE

$$y_3'(x) = 2y_3(x) - 4y_2(x) + 8y_1(x)$$

Convert linear ODE into a system of first order ODEs

$$[y_2(x) = y_1'(x), y_3(x) = y_2'(x), y_3'(x) = 2y_3(x) - 4y_2(x) + 8y_1(x)]$$

- Define vector

$$\vec{y}(x) = \begin{bmatrix} y_1(x) \\ y_2(x) \\ y_3(x) \end{bmatrix}$$

- System to solve

$$\vec{y}'(x) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 8 & -4 & 2 \end{bmatrix} \cdot \vec{y}(x)$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 8 & -4 & 2 \end{bmatrix}$$

- Rewrite the system as

$$\vec{y}'(x) = A \cdot \vec{y}(x)$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[\begin{bmatrix} 2 \\ \frac{1}{2} \\ 1 \end{bmatrix} \right], \left[-2\mathbf{I}, \begin{bmatrix} -\frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right], \left[2\mathbf{I}, \begin{bmatrix} -\frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[2, \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_1 = e^{2x} \cdot \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix}$$

- Consider complex eigenpair, complex conjugate eigenvalue can be ignored

$$\left[-2I, \begin{bmatrix} -\frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right]$$

- Solution from eigenpair

$$e^{-2Ix} \cdot \begin{bmatrix} -\frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix}$$

- Use Euler identity to write solution in terms of sin and cos

$$(\cos(2x) - I \sin(2x)) \cdot \begin{bmatrix} -\frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix}$$

- Simplify expression

$$\begin{bmatrix} -\frac{\cos(2x)}{4} + \frac{I \sin(2x)}{4} \\ \frac{1}{2}(\cos(2x) - I \sin(2x)) \\ \cos(2x) - I \sin(2x) \end{bmatrix}$$

- Both real and imaginary parts are solutions to the homogeneous system

$$\left[\vec{y}_2(x) = \begin{bmatrix} -\frac{\cos(2x)}{4} \\ \frac{\sin(2x)}{2} \\ \cos(2x) \end{bmatrix}, \vec{y}_3(x) = \begin{bmatrix} \frac{\sin(2x)}{4} \\ \frac{\cos(2x)}{2} \\ -\sin(2x) \end{bmatrix} \right]$$

- General solution to the system of ODEs

$$\vec{y} = c_1 \vec{y}_1 + c_2 \vec{y}_2(x) + c_3 \vec{y}_3(x)$$

- Substitute solutions into the general solution

$$\vec{y} = c_1 e^{2x} \cdot \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} + \begin{bmatrix} -\frac{c_2 \cos(2x)}{4} + \frac{c_3 \sin(2x)}{4} \\ \frac{c_2 \sin(2x)}{2} + \frac{c_3 \cos(2x)}{2} \\ c_2 \cos(2x) - c_3 \sin(2x) \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y = \frac{c_1 e^{2x}}{4} + \frac{c_3 \sin(2x)}{4} - \frac{c_2 \cos(2x)}{4}$$

- Use the initial condition $y(0) = 2$

$$2 = \frac{c_1}{4} - \frac{c_2}{4}$$

- Calculate the 1st derivative of the solution

$$y' = \frac{c_1 e^{2x}}{2} + \frac{c_3 \cos(2x)}{2} + \frac{c_2 \sin(2x)}{2}$$

- Use the initial condition $y' \Big|_{\{x=0\}} = 0$

$$0 = \frac{c_1}{2} + \frac{c_3}{2}$$

- Calculate the 2nd derivative of the solution

$$y'' = c_1 e^{2x} - c_3 \sin(2x) + c_2 \cos(2x)$$

- Use the initial condition $y'' \Big|_{\{x=0\}} = 0$

$$0 = c_1 + c_2$$

- Solve for the unknown coefficients

$$\{c_1 = 4, c_2 = -4, c_3 = -4\}$$

- Solution to the IVP

$$y = e^{2x} + \cos(2x) - \sin(2x)$$

Maple trace

```
`Methods for third order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
<- constant coefficients successful`
```

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 19

```
dsolve([diff(y(x),x$3)-2*diff(y(x),x$2)+4*diff(y(x),x)-8*y(x)=0,y(0) = 2, D(y)(0) = 0, (D@@2
```

$$y(x) = e^{2x} - \sin(2x) + \cos(2x)$$

✓ Solution by Mathematica

Time used: 0.003 (sec). Leaf size: 21

```
DSolve[{y'''[x]-2*y''[x]+4*y'[x]-8*y[x]==0,{y[0]==2,y'[0]==0,y''[0]==0}},y[x],x,IncludeSingu
```

$$y(x) \rightarrow e^{2x} - \sin(2x) + \cos(2x)$$

10.41 problem 41

10.41.1 Maple step by step solution 2226

Internal problem ID [11771]

Internal file name [OUTPUT/11780_Thursday_April_11_2024_08_49_36_PM_34242024/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 41.

ODE order: 3.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_3rd_order , _missing_x]]
```

$$y''' - 3y'' + 4y = 0$$

With initial conditions

$$[y(0) = 1, y'(0) = -8, y''(0) = -4]$$

The characteristic equation is

$$\lambda^3 - 3\lambda^2 + 4 = 0$$

The roots of the above equation are

$$\lambda_1 = -1$$

$$\lambda_2 = 2$$

$$\lambda_3 = 2$$

Therefore the homogeneous solution is

$$y_h(x) = c_1 e^{-x} + c_2 e^{2x} + x e^{2x} c_3$$

The fundamental set of solutions for the homogeneous solution are the following

$$\begin{aligned}y_1 &= e^{-x} \\y_2 &= e^{2x} \\y_3 &= e^{2x}x\end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1e^{-x} + c_2e^{2x} + xe^{2x}c_3 \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 1$ and $x = 0$ in the above gives

$$1 = c_1 + c_2 \quad (1A)$$

Taking derivative of the solution gives

$$y' = -c_1e^{-x} + 2c_2e^{2x} + e^{2x}c_3 + 2xe^{2x}c_3$$

substituting $y' = -8$ and $x = 0$ in the above gives

$$-8 = -c_1 + 2c_2 + c_3 \quad (2A)$$

Taking two derivatives of the solution gives

$$y'' = c_1e^{-x} + 4c_2e^{2x} + 4e^{2x}c_3 + 4xe^{2x}c_3$$

substituting $y'' = -4$ and $x = 0$ in the above gives

$$-4 = c_1 + 4c_2 + 4c_3 \quad (3A)$$

Equations {1A,2A,3A} are now solved for $\{c_1, c_2, c_3\}$. Solving for the constants gives

$$\begin{aligned}c_1 &= \frac{32}{9} \\c_2 &= -\frac{23}{9} \\c_3 &= \frac{2}{3}\end{aligned}$$

Substituting these values back in above solution results in

$$y = \frac{32e^{-x}}{9} - \frac{23e^{2x}}{9} + \frac{2e^{2x}x}{3}$$

Which simplifies to

$$y = \frac{(6x - 23)e^{2x}}{9} + \frac{32e^{-x}}{9}$$

Summary

The solution(s) found are the following

$$y = \frac{(6x - 23)e^{2x}}{9} + \frac{32e^{-x}}{9} \quad (1)$$

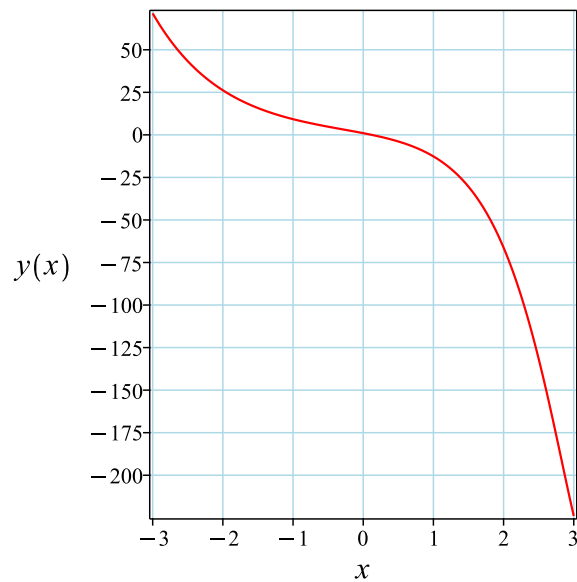


Figure 415: Solution plot

Verification of solutions

$$y = \frac{(6x - 23)e^{2x}}{9} + \frac{32e^{-x}}{9}$$

Verified OK.

10.41.1 Maple step by step solution

Let's solve

$$\left[y''' - 3y'' + 4y = 0, y(0) = 1, y'|_{\{x=0\}} = -8, y''|_{\{x=0\}} = -4 \right]$$

- Highest derivative means the order of the ODE is 3

y'''

- Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(x)$

$$y_1(x) = y$$

- Define new variable $y_2(x)$

$$y_2(x) = y'$$

- Define new variable $y_3(x)$

$$y_3(x) = y''$$

- Isolate for $y'_3(x)$ using original ODE

$$y'_3(x) = 3y_3(x) - 4y_1(x)$$

Convert linear ODE into a system of first order ODEs

$$[y_2(x) = y'_1(x), y_3(x) = y'_2(x), y'_3(x) = 3y_3(x) - 4y_1(x)]$$

- Define vector

$$\vec{y}(x) = \begin{bmatrix} y_1(x) \\ y_2(x) \\ y_3(x) \end{bmatrix}$$

- System to solve

$$\vec{y}'(x) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -4 & 0 & 3 \end{bmatrix} \cdot \vec{y}(x)$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -4 & 0 & 3 \end{bmatrix}$$

- Rewrite the system as

$$\vec{y}'(x) = A \cdot \vec{y}(x)$$

- To solve the system, find the eigenvalues and eigenvectors of A
- Eigenpairs of A

$$\left[\left[-1, \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \right], \left[2, \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right], \left[2, \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[-1, \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_1 = e^{-x} \cdot \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$$

- Consider eigenpair, with eigenvalue of algebraic multiplicity 2

$$\left[2, \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right]$$

- First solution from eigenvalue 2

$$\vec{y}_2(x) = e^{2x} \cdot \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix}$$

- Form of the 2nd homogeneous solution where \vec{p} is to be solved for, $\lambda = 2$ is the eigenvalue, and

$$\vec{y}_3(x) = e^{\lambda x} (x\vec{v} + \vec{p})$$

- Note that the x multiplying \vec{v} makes this solution linearly independent to the 1st solution obtained
- Substitute $\vec{y}_3(x)$ into the homogeneous system

$$\lambda e^{\lambda x} (x\vec{v} + \vec{p}) + e^{\lambda x} \vec{v} = (e^{\lambda x} A) \cdot (x\vec{v} + \vec{p})$$

- Use the fact that \vec{v} is an eigenvector of A

$$\lambda e^{\lambda x} (x\vec{v} + \vec{p}) + e^{\lambda x} \vec{v} = e^{\lambda x} (\lambda x\vec{v} + A \cdot \vec{p})$$

- Simplify equation

$$\lambda \vec{p} + \vec{v} = A \cdot \vec{p}$$

- Make use of the identity matrix I

$$(\lambda \cdot I) \cdot \vec{p} + \vec{v} = A \cdot \vec{p}$$

- Condition \vec{p} must meet for $\vec{y}_3(x)$ to be a solution to the homogeneous system

$$(A - \lambda \cdot I) \cdot \vec{p} = \vec{v}$$

- Choose \vec{p} to use in the second solution to the homogeneous system from eigenvalue 2

$$\left(\begin{pmatrix} \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -4 & 0 & 3 \end{bmatrix} - 2 \cdot \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \end{pmatrix} \cdot \vec{p} = \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right)$$

- Choice of \vec{p}

$$\vec{p} = \begin{bmatrix} -\frac{1}{8} \\ 0 \\ 0 \end{bmatrix}$$

- Second solution from eigenvalue 2

$$\vec{y}_3(x) = e^{2x} \cdot \left(x \cdot \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} + \begin{bmatrix} -\frac{1}{8} \\ 0 \\ 0 \end{bmatrix} \right)$$

- General solution to the system of ODEs

$$\vec{y} = c_1 \vec{y}_1 + c_2 \vec{y}_2(x) + c_3 \vec{y}_3(x)$$

- Substitute solutions into the general solution

$$\vec{y} = c_1 e^{-x} \cdot \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} + c_2 e^{2x} \cdot \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} + e^{2x} c_3 \cdot \left(x \cdot \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} + \begin{bmatrix} -\frac{1}{8} \\ 0 \\ 0 \end{bmatrix} \right)$$

- First component of the vector is the solution to the ODE

$$y = \frac{((2x-1)c_3+2c_2)e^{2x}}{8} + c_1e^{-x}$$

- Use the initial condition $y(0) = 1$

$$1 = -\frac{c_3}{8} + \frac{c_2}{4} + c_1$$

- Calculate the 1st derivative of the solution

$$y' = \frac{e^{2x}c_3}{4} + \frac{((2x-1)c_3+2c_2)e^{2x}}{4} - c_1e^{-x}$$

- Use the initial condition $y'|_{\{x=0\}} = -8$

$$-8 = \frac{c_2}{2} - c_1$$

- Calculate the 2nd derivative of the solution

$$y'' = e^{2x}c_3 + \frac{((2x-1)c_3+2c_2)e^{2x}}{2} + c_1e^{-x}$$

- Use the initial condition $y''|_{\{x=0\}} = -4$

$$-4 = \frac{c_3}{2} + c_2 + c_1$$

- Solve for the unknown coefficients

$$\left\{ c_1 = \frac{32}{9}, c_2 = -\frac{80}{9}, c_3 = \frac{8}{3} \right\}$$

- Solution to the IVP

$$y = \frac{(6x-23)e^{2x}}{9} + \frac{32e^{-x}}{9}$$

Maple trace

```

`Methods for third order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 22

```
dsolve([diff(y(x),x$3)-3*diff(y(x),x$2)+4*y(x)=0,y(0) = 1, D(y)(0) = -8, (D@@2)(y)(0) = -4],
```

$$y(x) = \frac{(6x - 23)e^{2x}}{9} + \frac{32e^{-x}}{9}$$

✓ Solution by Mathematica

Time used: 0.003 (sec). Leaf size: 27

```
DSolve[{y'''[x]-3*y''[x]+4*y[x]==0,{y[0]==1,y'[0]==-8,y''[0]==-4}},y[x],x,IncludeSingularSol
```

$$y(x) \rightarrow \frac{1}{9}e^{-x}(e^{3x}(6x - 23) + 32)$$

10.42 problem 42

10.42.1 Maple step by step solution 2233

Internal problem ID [11772]

Internal file name [OUTPUT/11781_Thursday_April_11_2024_08_49_36_PM_84460581/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 42.

ODE order: 3.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_3rd_order , _missing_x]]
```

$$y''' - 5y'' + 9y' - 5y = 0$$

With initial conditions

$$[y(0) = 0, y'(0) = 1, y''(0) = 6]$$

The characteristic equation is

$$\lambda^3 - 5\lambda^2 + 9\lambda - 5 = 0$$

The roots of the above equation are

$$\lambda_1 = 1$$

$$\lambda_2 = 2 - i$$

$$\lambda_3 = 2 + i$$

Therefore the homogeneous solution is

$$y_h(x) = e^x c_1 + e^{(2+i)x} c_2 + e^{(2-i)x} c_3$$

The fundamental set of solutions for the homogeneous solution are the following

$$\begin{aligned}y_1 &= e^x \\y_2 &= e^{(2+i)x} \\y_3 &= e^{(2-i)x}\end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = e^x c_1 + e^{(2+i)x} c_2 + e^{(2-i)x} c_3 \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 0$ and $x = 0$ in the above gives

$$0 = c_1 + c_2 + c_3 \quad (1A)$$

Taking derivative of the solution gives

$$y' = e^x c_1 + (2+i)e^{(2+i)x} c_2 + (2-i)e^{(2-i)x} c_3$$

substituting $y' = 1$ and $x = 0$ in the above gives

$$1 = c_1 + (2+i)c_2 + (2-i)c_3 \quad (2A)$$

Taking two derivatives of the solution gives

$$y'' = e^x c_1 + (3+4i)e^{(2+i)x} c_2 + (3-4i)e^{(2-i)x} c_3$$

substituting $y'' = 6$ and $x = 0$ in the above gives

$$6 = c_1 + (3+4i)c_2 + (3-4i)c_3 \quad (3A)$$

Equations {1A,2A,3A} are now solved for $\{c_1, c_2, c_3\}$. Solving for the constants gives

$$\begin{aligned}c_1 &= 1 \\c_2 &= -\frac{1}{2} - i \\c_3 &= -\frac{1}{2} + i\end{aligned}$$

Substituting these values back in above solution results in

$$y = e^x - \frac{e^{(2+i)x}}{2} - ie^{(2+i)x} - \frac{e^{(2-i)x}}{2} + ie^{(2-i)x}$$

Summary

The solution(s) found are the following

$$y = \left(-\frac{1}{2} + i\right) e^{(2-i)x} + \left(-\frac{1}{2} - i\right) e^{(2+i)x} + e^x \quad (1)$$

Verification of solutions

$$y = \left(-\frac{1}{2} + i\right) e^{(2-i)x} + \left(-\frac{1}{2} - i\right) e^{(2+i)x} + e^x$$

Verified OK.

10.42.1 Maple step by step solution

Let's solve

$$\left[y''' - 5y'' + 9y' - 5y = 0, y(0) = 0, y' \Big|_{\{x=0\}} = 1, y'' \Big|_{\{x=0\}} = 6 \right]$$

- Highest derivative means the order of the ODE is 3

y'''

- Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(x)$

$$y_1(x) = y$$

- Define new variable $y_2(x)$

$$y_2(x) = y'$$

- Define new variable $y_3(x)$

$$y_3(x) = y''$$

- Isolate for $y_3'(x)$ using original ODE

$$y_3'(x) = 5y_3(x) - 9y_2(x) + 5y_1(x)$$

Convert linear ODE into a system of first order ODEs

$$[y_2(x) = y_1'(x), y_3(x) = y_2'(x), y_3'(x) = 5y_3(x) - 9y_2(x) + 5y_1(x)]$$

- Define vector

$$\vec{y}(x) = \begin{bmatrix} y_1(x) \\ y_2(x) \\ y_3(x) \end{bmatrix}$$

- System to solve

$$\vec{y}'(x) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 5 & -9 & 5 \end{bmatrix} \cdot \vec{y}(x)$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 5 & -9 & 5 \end{bmatrix}$$

- Rewrite the system as

$$\vec{y}'(x) = A \cdot \vec{y}(x)$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right], \left[2 - I, \begin{bmatrix} \frac{3}{25} + \frac{4I}{25} \\ \frac{2}{5} + \frac{I}{5} \\ 1 \end{bmatrix} \right], \left[2 + I, \begin{bmatrix} \frac{3}{25} - \frac{4I}{25} \\ \frac{2}{5} - \frac{I}{5} \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[1, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_1 = e^x \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

- Consider complex eigenpair, complex conjugate eigenvalue can be ignored

$$\left[2 - I, \begin{bmatrix} \frac{3}{25} + \frac{4I}{25} \\ \frac{2}{5} + \frac{I}{5} \\ 1 \end{bmatrix} \right]$$

- Solution from eigenpair

$$e^{(2-I)x} \cdot \begin{bmatrix} \frac{3}{25} + \frac{4I}{25} \\ \frac{2}{5} + \frac{I}{5} \\ 1 \end{bmatrix}$$

- Use Euler identity to write solution in terms of sin and cos

$$e^{2x} \cdot (\cos(x) - I \sin(x)) \cdot \begin{bmatrix} \frac{3}{25} + \frac{4I}{25} \\ \frac{2}{5} + \frac{I}{5} \\ 1 \end{bmatrix}$$

- Simplify expression

$$e^{2x} \cdot \begin{bmatrix} \left(\frac{3}{25} + \frac{4I}{25}\right) (\cos(x) - I \sin(x)) \\ \left(\frac{2}{5} + \frac{I}{5}\right) (\cos(x) - I \sin(x)) \\ \cos(x) - I \sin(x) \end{bmatrix}$$

- Both real and imaginary parts are solutions to the homogeneous system

$$\begin{bmatrix} \vec{y}_2(x) = e^{2x} \cdot \begin{bmatrix} \frac{3 \cos(x)}{25} + \frac{4 \sin(x)}{25} \\ \frac{2 \cos(x)}{5} + \frac{\sin(x)}{5} \\ \cos(x) \end{bmatrix}, \vec{y}_3(x) = e^{2x} \cdot \begin{bmatrix} -\frac{3 \sin(x)}{25} + \frac{4 \cos(x)}{25} \\ -\frac{2 \sin(x)}{5} + \frac{\cos(x)}{5} \\ -\sin(x) \end{bmatrix} \end{bmatrix}$$

- General solution to the system of ODEs

$$\vec{y} = c_1 \vec{y}_1 + c_2 \vec{y}_2(x) + c_3 \vec{y}_3(x)$$

- Substitute solutions into the general solution

$$\vec{y} = e^x c_1 \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + c_2 e^{2x} \cdot \begin{bmatrix} \frac{3 \cos(x)}{25} + \frac{4 \sin(x)}{25} \\ \frac{2 \cos(x)}{5} + \frac{\sin(x)}{5} \\ \cos(x) \end{bmatrix} + e^{2x} c_3 \cdot \begin{bmatrix} -\frac{3 \sin(x)}{25} + \frac{4 \cos(x)}{25} \\ -\frac{2 \sin(x)}{5} + \frac{\cos(x)}{5} \\ -\sin(x) \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y = \frac{\left((3c_2+4c_3) \cos(x) + 4\left(c_2 - \frac{3c_3}{4}\right) \sin(x)\right) e^{2x}}{25} + e^x c_1$$

- Use the initial condition $y(0) = 0$

$$0 = \frac{3c_2}{25} + \frac{4c_3}{25} + c_1$$

- Calculate the 1st derivative of the solution

$$y' = \frac{\left(-3c_2+4c_3\right) \sin(x) + 4\left(c_2 - \frac{3c_3}{4}\right) \cos(x) e^{2x}}{25} + \frac{2\left(\left(3c_2+4c_3\right) \cos(x) + 4\left(c_2 - \frac{3c_3}{4}\right) \sin(x)\right) e^{2x}}{25} + e^x c_1$$

- Use the initial condition $y' \Big|_{\{x=0\}} = 1$

$$1 = \frac{2c_2}{5} + \frac{c_3}{5} + c_1$$

- Calculate the 2nd derivative of the solution

$$y'' = \frac{(-3c_2+4c_3)\cos(x)-4\left(c_2-\frac{3c_3}{4}\right)\sin(x)e^{2x}}{25} + \frac{4(-3c_2+4c_3)\sin(x)+4\left(c_2-\frac{3c_3}{4}\right)\cos(x)e^{2x}}{25} + \frac{4((3c_2+4c_3)\cos(x)+4\left(c_2-\frac{3c_3}{4}\right)\sin(x))e^{2x}}{25}$$

- Use the initial condition $y'' \Big|_{\{x=0\}} = 6$

$$6 = c_1 + c_2$$

- Solve for the unknown coefficients

$$\{c_1 = 1, c_2 = 5, c_3 = -10\}$$

- Solution to the IVP

$$y = (-\cos(x) + 2\sin(x))e^{2x} + e^x$$

Maple trace

```
`Methods for third order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
<- constant coefficients successful`
```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 23

```
dsolve([diff(y(x),x$3)-5*diff(y(x),x$2)+9*diff(y(x),x)-5*y(x)=0,y(0) = 0, D(y)(0) = 1, (D@@2
```

$$y(x) = e^x + (2\sin(x) - \cos(x))e^{2x}$$

✓ Solution by Mathematica

Time used: 0.003 (sec). Leaf size: 25

```
DSolve[{y'''[x]-5*y''[x]+9*y'[x]-5*y[x]==0,{y[0]==0,y'[0]==1,y''[0]==6}},y[x],x,IncludeSingularSolutions->True]
```

$$y(x) \rightarrow e^x(2e^x \sin(x) - e^x \cos(x) + 1)$$

10.43 problem 45

10.43.1 Maple step by step solution 2238

Internal problem ID [11773]

Internal file name [OUTPUT/11782_Thursday_April_11_2024_08_49_37_PM_10735052/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 45.

ODE order: 4.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_high_order , _missing_x]]
```

$$y'''' + 2y'''' + 6y'' + 2y' + 5y = 0$$

The characteristic equation is

$$\lambda^4 + 2\lambda^3 + 6\lambda^2 + 2\lambda + 5 = 0$$

The roots of the above equation are

$$\begin{aligned}\lambda_1 &= i \\ \lambda_2 &= -i \\ \lambda_3 &= -1 - 2i \\ \lambda_4 &= -1 + 2i\end{aligned}$$

Therefore the homogeneous solution is

$$y_h(x) = e^{(-1-2i)x}c_1 + e^{ix}c_2 + e^{(-1+2i)x}c_3 + e^{-ix}c_4$$

The fundamental set of solutions for the homogeneous solution are the following

$$y_1 = e^{(-1-2i)x}$$

$$y_2 = e^{ix}$$

$$y_3 = e^{(-1+2i)x}$$

$$y_4 = e^{-ix}$$

Summary

The solution(s) found are the following

$$y = e^{(-1-2i)x} c_1 + e^{ix} c_2 + e^{(-1+2i)x} c_3 + e^{-ix} c_4 \quad (1)$$

Verification of solutions

$$y = e^{(-1-2i)x} c_1 + e^{ix} c_2 + e^{(-1+2i)x} c_3 + e^{-ix} c_4$$

Verified OK.

10.43.1 Maple step by step solution

Let's solve

$$y'''' + 2y''' + 6y'' + 2y' + 5y = 0$$

- Highest derivative means the order of the ODE is 4

$$y''''$$

- Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(x)$

$$y_1(x) = y$$

- Define new variable $y_2(x)$

$$y_2(x) = y'$$

- Define new variable $y_3(x)$

$$y_3(x) = y''$$

- Define new variable $y_4(x)$

$$y_4(x) = y'''$$

- Isolate for $y_4'(x)$ using original ODE

$$y_4'(x) = -2y_4(x) - 6y_3(x) - 2y_2(x) - 5y_1(x)$$

Convert linear ODE into a system of first order ODEs

$$[y_2(x) = y_1'(x), y_3(x) = y_2'(x), y_4(x) = y_3'(x), y_4'(x) = -2y_4(x) - 6y_3(x) - 2y_2(x) - 5y_1(x)]$$

- Define vector

$$\vec{y}(x) = \begin{bmatrix} y_1(x) \\ y_2(x) \\ y_3(x) \\ y_4(x) \end{bmatrix}$$

- System to solve

$$\vec{y}'(x) = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -5 & -2 & -6 & -2 \end{bmatrix} \cdot \vec{y}(x)$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -5 & -2 & -6 & -2 \end{bmatrix}$$

- Rewrite the system as

$$\vec{y}'(x) = A \cdot \vec{y}(x)$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[\begin{bmatrix} -I \\ -1 \\ I \\ 1 \end{bmatrix} \right], \left[\begin{bmatrix} I \\ -1 \\ -I \\ 1 \end{bmatrix} \right], \left[-1 - 2I, \begin{bmatrix} \frac{11}{125} - \frac{2I}{125} \\ -\frac{3}{25} - \frac{4I}{25} \\ -\frac{1}{5} + \frac{2I}{5} \\ 1 \end{bmatrix} \right], \left[-1 + 2I, \begin{bmatrix} \frac{11}{125} + \frac{2I}{125} \\ -\frac{3}{25} + \frac{4I}{25} \\ -\frac{1}{5} - \frac{2I}{5} \\ 1 \end{bmatrix} \right] \right]$$

- Consider complex eigenpair, complex conjugate eigenvalue can be ignored

$$\left[-\mathbf{I}, \begin{bmatrix} -\mathbf{I} \\ -1 \\ \mathbf{I} \\ 1 \end{bmatrix} \right]$$

- Solution from eigenpair

$$e^{-\mathbf{I}x} \cdot \begin{bmatrix} -\mathbf{I} \\ -1 \\ \mathbf{I} \\ 1 \end{bmatrix}$$

- Use Euler identity to write solution in terms of sin and cos

$$(\cos(x) - \mathbf{I} \sin(x)) \cdot \begin{bmatrix} -\mathbf{I} \\ -1 \\ \mathbf{I} \\ 1 \end{bmatrix}$$

- Simplify expression

$$\begin{bmatrix} -\mathbf{I}(\cos(x) - \mathbf{I} \sin(x)) \\ -\cos(x) + \mathbf{I} \sin(x) \\ \mathbf{I}(\cos(x) - \mathbf{I} \sin(x)) \\ \cos(x) - \mathbf{I} \sin(x) \end{bmatrix}$$

- Both real and imaginary parts are solutions to the homogeneous system

$$\vec{y}_1(x) = \begin{bmatrix} -\sin(x) \\ -\cos(x) \\ \sin(x) \\ \cos(x) \end{bmatrix}, \vec{y}_2(x) = \begin{bmatrix} -\cos(x) \\ \sin(x) \\ \cos(x) \\ -\sin(x) \end{bmatrix}$$

- Consider complex eigenpair, complex conjugate eigenvalue can be ignored

$$\left[-1 - 2I, \begin{bmatrix} \frac{11}{125} - \frac{2I}{125} \\ -\frac{3}{25} - \frac{4I}{25} \\ -\frac{1}{5} + \frac{2I}{5} \\ 1 \end{bmatrix} \right]$$

- Solution from eigenpair

$$e^{(-1-2I)x} \cdot \begin{bmatrix} \frac{11}{125} - \frac{2I}{125} \\ -\frac{3}{25} - \frac{4I}{25} \\ -\frac{1}{5} + \frac{2I}{5} \\ 1 \end{bmatrix}$$

- Use Euler identity to write solution in terms of sin and cos

$$e^{-x} \cdot (\cos(2x) - I \sin(2x)) \cdot \begin{bmatrix} \frac{11}{125} - \frac{2I}{125} \\ -\frac{3}{25} - \frac{4I}{25} \\ -\frac{1}{5} + \frac{2I}{5} \\ 1 \end{bmatrix}$$

- Simplify expression

$$e^{-x} \cdot \begin{bmatrix} \left(\frac{11}{125} - \frac{2I}{125}\right) (\cos(2x) - I \sin(2x)) \\ \left(-\frac{3}{25} - \frac{4I}{25}\right) (\cos(2x) - I \sin(2x)) \\ \left(-\frac{1}{5} + \frac{2I}{5}\right) (\cos(2x) - I \sin(2x)) \\ \cos(2x) - I \sin(2x) \end{bmatrix}$$

- Both real and imaginary parts are solutions to the homogeneous system

$$\vec{y}_3(x) = e^{-x} \cdot \begin{bmatrix} \frac{11 \cos(2x)}{125} - \frac{2 \sin(2x)}{125} \\ -\frac{3 \cos(2x)}{25} - \frac{4 \sin(2x)}{25} \\ -\frac{\cos(2x)}{5} + \frac{2 \sin(2x)}{5} \\ \cos(2x) \end{bmatrix}, \vec{y}_4(x) = e^{-x} \cdot \begin{bmatrix} -\frac{11 \sin(2x)}{125} - \frac{2 \cos(2x)}{125} \\ \frac{3 \sin(2x)}{25} - \frac{4 \cos(2x)}{25} \\ \frac{\sin(2x)}{5} + \frac{2 \cos(2x)}{5} \\ -\sin(2x) \end{bmatrix}$$

- General solution to the system of ODEs

$$\vec{y} = c_1 \vec{y}_1(x) + c_2 \vec{y}_2(x) + c_3 \vec{y}_3(x) + c_4 \vec{y}_4(x)$$

- Substitute solutions into the general solution

$$\vec{y} = c_3 e^{-x} \cdot \begin{bmatrix} \frac{11 \cos(2x)}{125} - \frac{2 \sin(2x)}{125} \\ -\frac{3 \cos(2x)}{25} - \frac{4 \sin(2x)}{25} \\ -\frac{\cos(2x)}{5} + \frac{2 \sin(2x)}{5} \\ \cos(2x) \end{bmatrix} + c_4 e^{-x} \cdot \begin{bmatrix} -\frac{11 \sin(2x)}{125} - \frac{2 \cos(2x)}{125} \\ \frac{3 \sin(2x)}{25} - \frac{4 \cos(2x)}{25} \\ \frac{\sin(2x)}{5} + \frac{2 \cos(2x)}{5} \\ -\sin(2x) \end{bmatrix} + \begin{bmatrix} -\sin(x) c_1 - c_2 \cos(x) \\ -c_1 \cos(x) + c_2 \sin(x) \\ \sin(x) c_1 + c_2 \cos(x) \\ c_1 \cos(x) - c_2 \sin(x) \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y = \frac{\left((22c_3 - 4c_4) \cos(x)^2 - 4 \left(c_3 + \frac{11c_4}{2} \right) \sin(x) \cos(x) - 11c_3 + 2c_4 \right) e^{-x}}{125} - \sin(x) c_1 - c_2 \cos(x)$$

Maple trace

```

`Methods for high order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 36

```
dsolve(diff(y(x),x$4)+2*diff(y(x),x$3)+6*diff(y(x),x$2)+2*diff(y(x),x)+5*y(x))=0,y(x), singularities)
```

$$y(x) = (2c_3 \cos(x) \sin(x) + 2c_4 \cos(x)^2 - c_4) e^{-x} + c_1 \sin(x) + c_2 \cos(x)$$

✓ Solution by Mathematica

Time used: 0.003 (sec). Leaf size: 40

```
DSolve[y''''[x]+2*y'''[x]+6*y''[x]+2*y'[x]+5*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow c_3 \cos(x) + e^{-x}(c_2 \cos(2x) + c_4 e^x \sin(x) + c_1 \sin(2x))$$

10.44 problem 46

10.44.1 Maple step by step solution 2244

Internal problem ID [11774]

Internal file name [OUTPUT/11783_Thursday_April_11_2024_08_49_37_PM_9949308/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.2. The homogeneous linear equation with constant coefficients. Exercises page 135

Problem number: 46.

ODE order: 4.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_high_order , _missing_x]]
```

$$y'''' + 3y''' + y'' + 13y' + 30y = 0$$

The characteristic equation is

$$\lambda^4 + 3\lambda^3 + \lambda^2 + 13\lambda + 30 = 0$$

The roots of the above equation are

$$\lambda_1 = -3$$

$$\lambda_2 = -2$$

$$\lambda_3 = 1 - 2i$$

$$\lambda_4 = 1 + 2i$$

Therefore the homogeneous solution is

$$y_h(x) = c_1 e^{-2x} + c_2 e^{-3x} + e^{(1+2i)x} c_3 + e^{(1-2i)x} c_4$$

The fundamental set of solutions for the homogeneous solution are the following

$$\begin{aligned}y_1 &= e^{-2x} \\y_2 &= e^{-3x} \\y_3 &= e^{(1+2i)x} \\y_4 &= e^{(1-2i)x}\end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1e^{-2x} + c_2e^{-3x} + e^{(1+2i)x}c_3 + e^{(1-2i)x}c_4 \quad (1)$$

Verification of solutions

$$y = c_1e^{-2x} + c_2e^{-3x} + e^{(1+2i)x}c_3 + e^{(1-2i)x}c_4$$

Verified OK.

10.44.1 Maple step by step solution

Let's solve

$$y'''' + 3y''' + y'' + 13y' + 30y = 0$$

- Highest derivative means the order of the ODE is 4

$$y''''$$

- Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(x)$

$$y_1(x) = y$$

- Define new variable $y_2(x)$

$$y_2(x) = y'$$

- Define new variable $y_3(x)$

$$y_3(x) = y''$$

- Define new variable $y_4(x)$

$$y_4(x) = y'''$$

- Isolate for $y_4'(x)$ using original ODE

$$y_4'(x) = -3y_4(x) - y_3(x) - 13y_2(x) - 30y_1(x)$$

Convert linear ODE into a system of first order ODEs

$$[y_2(x) = y_1'(x), y_3(x) = y_2'(x), y_4(x) = y_3'(x), y_4'(x) = -3y_4(x) - y_3(x) - 13y_2(x) - 30y_1(x)]$$

- Define vector

$$\vec{y}(x) = \begin{bmatrix} y_1(x) \\ y_2(x) \\ y_3(x) \\ y_4(x) \end{bmatrix}$$

- System to solve

$$\vec{y}'(x) = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -30 & -13 & -1 & -3 \end{bmatrix} \cdot \vec{y}(x)$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -30 & -13 & -1 & -3 \end{bmatrix}$$

- Rewrite the system as

$$\vec{y}'(x) = A \cdot \vec{y}(x)$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[\begin{bmatrix} -3, \\ \begin{bmatrix} -\frac{1}{27} \\ \frac{1}{9} \\ -\frac{1}{3} \\ 1 \end{bmatrix} \end{bmatrix} \right], \left[\begin{bmatrix} -2, \\ \begin{bmatrix} -\frac{1}{8} \\ \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix} \end{bmatrix} \right], \left[1 - 2I, \begin{bmatrix} -\frac{11}{125} - \frac{2I}{125} \\ -\frac{3}{25} + \frac{4I}{25} \\ \frac{1}{5} + \frac{2I}{5} \\ 1 \end{bmatrix} \right], \left[1 + 2I, \begin{bmatrix} -\frac{11}{125} + \frac{2I}{125} \\ -\frac{3}{25} - \frac{4I}{25} \\ \frac{1}{5} - \frac{2I}{5} \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[-3, \begin{bmatrix} -\frac{1}{27} \\ \frac{1}{9} \\ -\frac{1}{3} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_1 = e^{-3x} \cdot \begin{bmatrix} -\frac{1}{27} \\ \frac{1}{9} \\ -\frac{1}{3} \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[-2, \begin{bmatrix} -\frac{1}{8} \\ \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_2 = e^{-2x} \cdot \begin{bmatrix} -\frac{1}{8} \\ \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix}$$

- Consider complex eigenpair, complex conjugate eigenvalue can be ignored

$$\left[1 - 2I, \begin{bmatrix} -\frac{11}{125} - \frac{2I}{125} \\ -\frac{3}{25} + \frac{4I}{25} \\ \frac{1}{5} + \frac{2I}{5} \\ 1 \end{bmatrix} \right]$$

- Solution from eigenpair

$$e^{(1-2I)x} \cdot \begin{bmatrix} -\frac{11}{125} - \frac{2I}{125} \\ -\frac{3}{25} + \frac{4I}{25} \\ \frac{1}{5} + \frac{2I}{5} \\ 1 \end{bmatrix}$$

- Use Euler identity to write solution in terms of sin and cos

$$e^x \cdot (\cos(2x) - I \sin(2x)) \cdot \begin{bmatrix} -\frac{11}{125} - \frac{2I}{125} \\ -\frac{3}{25} + \frac{4I}{25} \\ \frac{1}{5} + \frac{2I}{5} \\ 1 \end{bmatrix}$$

- Simplify expression

$$e^x \cdot \begin{bmatrix} \left(-\frac{11}{125} - \frac{2I}{125}\right) (\cos(2x) - I \sin(2x)) \\ \left(-\frac{3}{25} + \frac{4I}{25}\right) (\cos(2x) - I \sin(2x)) \\ \left(\frac{1}{5} + \frac{2I}{5}\right) (\cos(2x) - I \sin(2x)) \\ \cos(2x) - I \sin(2x) \end{bmatrix}$$

- Both real and imaginary parts are solutions to the homogeneous system

$$\begin{bmatrix} \vec{y}_3(x) = e^x \cdot \begin{bmatrix} -\frac{11 \cos(2x)}{125} - \frac{2 \sin(2x)}{125} \\ -\frac{3 \cos(2x)}{25} + \frac{4 \sin(2x)}{25} \\ \frac{\cos(2x)}{5} + \frac{2 \sin(2x)}{5} \\ \cos(2x) \end{bmatrix}, \vec{y}_4(x) = e^x \cdot \begin{bmatrix} \frac{11 \sin(2x)}{125} - \frac{2 \cos(2x)}{125} \\ \frac{3 \sin(2x)}{25} + \frac{4 \cos(2x)}{25} \\ -\frac{\sin(2x)}{5} + \frac{2 \cos(2x)}{5} \\ -\sin(2x) \end{bmatrix} \end{bmatrix}$$

- General solution to the system of ODEs

$$\vec{y} = c_1 \vec{y}_1 + c_2 \vec{y}_2 + c_3 \vec{y}_3(x) + c_4 \vec{y}_4(x)$$

- Substitute solutions into the general solution

$$\vec{y} = c_1 e^{-3x} \cdot \begin{bmatrix} -\frac{1}{27} \\ \frac{1}{9} \\ -\frac{1}{3} \\ 1 \end{bmatrix} + c_2 e^{-2x} \cdot \begin{bmatrix} -\frac{1}{8} \\ \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix} + c_3 e^x \cdot \begin{bmatrix} -\frac{11 \cos(2x)}{125} - \frac{2 \sin(2x)}{125} \\ -\frac{3 \cos(2x)}{25} + \frac{4 \sin(2x)}{25} \\ \frac{\cos(2x)}{5} + \frac{2 \sin(2x)}{5} \\ \cos(2x) \end{bmatrix} + e^x c_4 \cdot \begin{bmatrix} \frac{11 \sin(2x)}{125} - \frac{2 \cos(2x)}{125} \\ \frac{3 \sin(2x)}{25} + \frac{4 \cos(2x)}{25} \\ -\frac{\sin(2x)}{5} + \frac{2 \cos(2x)}{5} \\ -\sin(2x) \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y = -\frac{2e^{-3x}\left(\left(\frac{11c_3}{2} + c_4\right)\cos(2x) + \sin(2x)\left(c_3 - \frac{11c_4}{2}\right)\right)e^{4x} + \frac{125c_2e^x}{16} + \frac{125c_1}{54}}{125}$$

Maple trace

```

`Methods for high order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 35

```
dsolve(diff(y(x),x$4)+3*diff(y(x),x$3)+diff(y(x),x$2)+13*diff(y(x),x)+30*y(x)=0,y(x), singularities)
```

$$y(x) = (c_3e^{4x} \sin(2x) + c_4e^{4x} \cos(2x) + c_2e^x + c_1) e^{-3x}$$

✓ Solution by Mathematica

Time used: 0.003 (sec). Leaf size: 43

```
DSolve[y''''[x]+3*y'''[x]+y''[x]+13*y'[x]+30*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow c_2e^x \cos(2x) + e^{-3x}(c_4e^x + c_1e^{4x} \sin(2x) + c_3)$$

11 Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

11.1 problem 1	2251
11.2 problem 2	2263
11.3 problem 3	2274
11.4 problem 4	2285
11.5 problem 5	2296
11.6 problem 6	2307
11.7 problem 7	2318
11.8 problem 8	2329
11.9 problem 9	2340
11.10 problem 10	2348
11.11 problem 11	2356
11.12 problem 12	2364
11.13 problem 13	2372
11.14 problem 14	2384
11.15 problem 15	2397
11.16 problem 16	2406
11.17 problem 17	2414
11.18 problem 18	2424
11.19 problem 19	2428
11.20 problem 20	2436
11.21 problem 21	2445
11.22 problem 22	2456
11.23 problem 23	2467
11.24 problem 24	2471
11.25 problem 25	2483
11.26 problem 26	2496
11.27 problem 27	2509
11.28 problem 28	2522
11.29 problem 29	2535
11.30 problem 30	2550
11.31 problem 31	2565
11.32 problem 32	2578
11.33 problem 33	2591
11.34 problem 34	2605
11.35 problem 35	2620
11.36 problem 36	2636

11.37problem 37	2651
11.38problem 38	2664
11.39problem 39	2677
11.40problem 40	2687
11.41problem 41	2697
11.42problem 42	2708
11.43problem 43	2719
11.44problem 44	2730
11.45problem 45	2744
11.46problem 46	2761
11.47problem 47	2769
11.48problem 48	2773
11.49problem 49	2788
11.50problem 50	2801
11.51problem 51	2810
11.52problem 52	2816
11.53problem 53	2830
11.54problem 54	2842

11.1 problem 1

11.1.1 Solving as second order linear constant coeff ode	2251
11.1.2 Solving using Kovacic algorithm	2255
11.1.3 Maple step by step solution	2260

Internal problem ID [11775]

Internal file name [OUTPUT/11784_Thursday_April_11_2024_08_49_37_PM_56146256/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 1.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$y'' - 3y' + 8y = 4x^2$$

11.1.1 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = -3, C = 8, f(x) = 4x^2$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' - 3y' + 8y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = -3, C = 8$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} - 3\lambda e^{\lambda x} + 8 e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 - 3\lambda + 8 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = -3, C = 8$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{3}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{-3^2 - (4)(1)(8)} \\ &= \frac{3}{2} \pm \frac{i\sqrt{23}}{2} \end{aligned}$$

Hence

$$\begin{aligned} \lambda_1 &= \frac{3}{2} + \frac{i\sqrt{23}}{2} \\ \lambda_2 &= \frac{3}{2} - \frac{i\sqrt{23}}{2} \end{aligned}$$

Which simplifies to

$$\begin{aligned} \lambda_1 &= \frac{3}{2} + \frac{i\sqrt{23}}{2} \\ \lambda_2 &= \frac{3}{2} - \frac{i\sqrt{23}}{2} \end{aligned}$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = \frac{3}{2}$ and $\beta = \frac{\sqrt{23}}{2}$. Therefore the final solution, when using Euler relation, can be written as

$$y = e^{\alpha x} (c_1 \cos(\beta x) + c_2 \sin(\beta x))$$

Which becomes

$$y = e^{\frac{3x}{2}} \left(c_1 \cos \left(\frac{\sqrt{23}x}{2} \right) + c_2 \sin \left(\frac{\sqrt{23}x}{2} \right) \right)$$

Therefore the homogeneous solution y_h is

$$y_h = e^{\frac{3x}{2}} \left(c_1 \cos \left(\frac{\sqrt{23} x}{2} \right) + c_2 \sin \left(\frac{\sqrt{23} x}{2} \right) \right)$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$x^2$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{1, x, x^2\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\left\{ e^{\frac{3x}{2}} \cos \left(\frac{\sqrt{23} x}{2} \right), e^{\frac{3x}{2}} \sin \left(\frac{\sqrt{23} x}{2} \right) \right\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_3 x^2 + A_2 x + A_1$$

The unknowns $\{A_1, A_2, A_3\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$8A_3 x^2 + 8A_2 x - 6xA_3 + 8A_1 - 3A_2 + 2A_3 = 4x^2$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = \frac{1}{64}, A_2 = \frac{3}{8}, A_3 = \frac{1}{2} \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = \frac{1}{2} x^2 + \frac{3}{8} x + \frac{1}{64}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(e^{\frac{3x}{2}} \left(c_1 \cos \left(\frac{\sqrt{23} x}{2} \right) + c_2 \sin \left(\frac{\sqrt{23} x}{2} \right) \right) \right) + \left(\frac{1}{2} x^2 + \frac{3}{8} x + \frac{1}{64} \right) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = e^{\frac{3x}{2}} \left(c_1 \cos \left(\frac{\sqrt{23} x}{2} \right) + c_2 \sin \left(\frac{\sqrt{23} x}{2} \right) \right) + \frac{x^2}{2} + \frac{3x}{8} + \frac{1}{64} \quad (1)$$

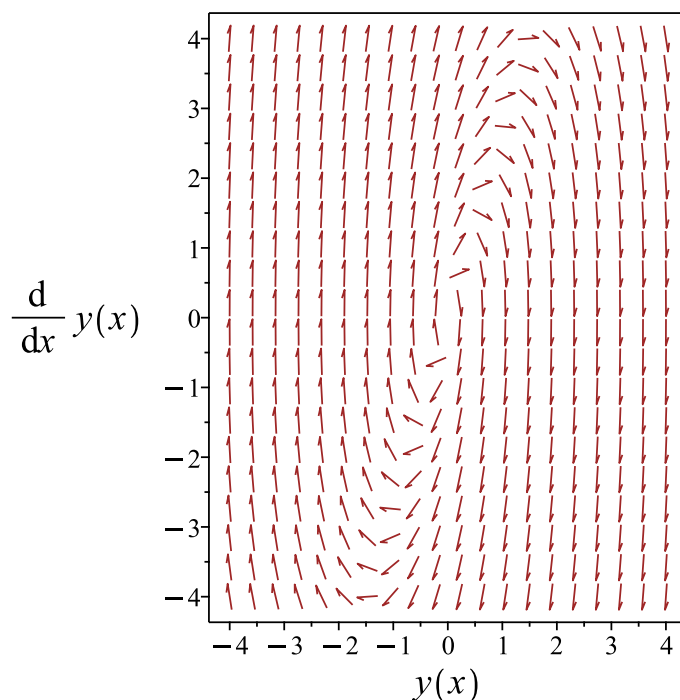


Figure 416: Slope field plot

Verification of solutions

$$y = e^{\frac{3x}{2}} \left(c_1 \cos \left(\frac{\sqrt{23} x}{2} \right) + c_2 \sin \left(\frac{\sqrt{23} x}{2} \right) \right) + \frac{x^2}{2} + \frac{3x}{8} + \frac{1}{64}$$

Verified OK.

11.1.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' - 3y' + 8y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$A = 1$$

$$B = -3 \quad (3)$$

$$C = 8$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$r = \frac{s}{t} \quad (5)$$
$$= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-23}{4} \quad (6)$$

Comparing the above to (5) shows that

$$s = -23$$

$$t = 4$$

Therefore eq. (4) becomes

$$z''(x) = -\frac{23z(x)}{4} \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 345: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = -\frac{23}{4}$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = \cos\left(\frac{\sqrt{23}x}{2}\right)$$

Using the above, the solution for the original ode can now be found. The first solution

to the original ode in y is found from

$$\begin{aligned}y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\&= z_1 e^{-\int \frac{1}{2} \frac{-3}{1} dx} \\&= z_1 e^{\frac{3x}{2}} \\&= z_1 \left(e^{\frac{3x}{2}} \right)\end{aligned}$$

Which simplifies to

$$y_1 = e^{\frac{3x}{2}} \cos \left(\frac{\sqrt{23} x}{2} \right)$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{-3}{1} dx}}{(y_1)^2} dx \\&= y_1 \int \frac{e^{3x}}{(y_1)^2} dx \\&= y_1 \left(\frac{2\sqrt{23} \tan \left(\frac{\sqrt{23} x}{2} \right)}{23} \right)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\&= c_1 \left(e^{\frac{3x}{2}} \cos \left(\frac{\sqrt{23} x}{2} \right) \right) + c_2 \left(e^{\frac{3x}{2}} \cos \left(\frac{\sqrt{23} x}{2} \right) \left(\frac{2\sqrt{23} \tan \left(\frac{\sqrt{23} x}{2} \right)}{23} \right) \right)\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' - 3y' + 8y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = e^{\frac{3x}{2}} \cos\left(\frac{\sqrt{23}x}{2}\right) c_1 + \frac{2c_2 \sin\left(\frac{\sqrt{23}x}{2}\right) e^{\frac{3x}{2}} \sqrt{23}}{23}$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$x^2$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{1, x, x^2\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\left\{ e^{\frac{3x}{2}} \cos\left(\frac{\sqrt{23}x}{2}\right), \frac{2 \sin\left(\frac{\sqrt{23}x}{2}\right) e^{\frac{3x}{2}} \sqrt{23}}{23} \right\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_3x^2 + A_2x + A_1$$

The unknowns $\{A_1, A_2, A_3\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$8A_3x^2 + 8A_2x - 6xA_3 + 8A_1 - 3A_2 + 2A_3 = 4x^2$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = \frac{1}{64}, A_2 = \frac{3}{8}, A_3 = \frac{1}{2} \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = \frac{1}{2}x^2 + \frac{3}{8}x + \frac{1}{64}$$

Therefore the general solution is

$$y = y_h + y_p$$

$$= \left(e^{\frac{3x}{2}} \cos\left(\frac{\sqrt{23}x}{2}\right) c_1 + \frac{2c_2 \sin\left(\frac{\sqrt{23}x}{2}\right) e^{\frac{3x}{2}} \sqrt{23}}{23} \right) + \left(\frac{1}{2}x^2 + \frac{3}{8}x + \frac{1}{64} \right)$$

Summary

The solution(s) found are the following

$$y = e^{\frac{3x}{2}} \cos\left(\frac{\sqrt{23}x}{2}\right) c_1 + \frac{2c_2 \sin\left(\frac{\sqrt{23}x}{2}\right) e^{\frac{3x}{2}} \sqrt{23}}{23} + \frac{x^2}{2} + \frac{3x}{8} + \frac{1}{64} \quad (1)$$

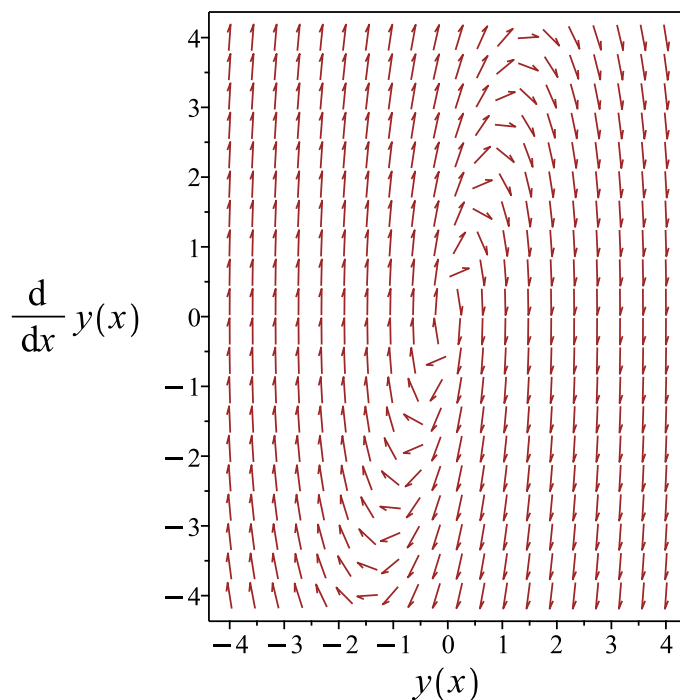


Figure 417: Slope field plot

Verification of solutions

$$y = e^{\frac{3x}{2}} \cos\left(\frac{\sqrt{23}x}{2}\right) c_1 + \frac{2c_2 \sin\left(\frac{\sqrt{23}x}{2}\right) e^{\frac{3x}{2}} \sqrt{23}}{23} + \frac{x^2}{2} + \frac{3x}{8} + \frac{1}{64}$$

Verified OK.

11.1.3 Maple step by step solution

Let's solve

$$y'' - 3y' + 8y = 4x^2$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of homogeneous ODE

$$r^2 - 3r + 8 = 0$$

- Use quadratic formula to solve for r

$$r = \frac{3 \pm (\sqrt{-23})}{2}$$

- Roots of the characteristic polynomial

$$r = \left(\frac{3}{2} - \frac{1\sqrt{23}}{2}, \frac{3}{2} + \frac{1\sqrt{23}}{2}\right)$$

- 1st solution of the homogeneous ODE

$$y_1(x) = e^{\frac{3x}{2}} \cos\left(\frac{\sqrt{23}x}{2}\right)$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = e^{\frac{3x}{2}} \sin\left(\frac{\sqrt{23}x}{2}\right)$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = e^{\frac{3x}{2}} \cos\left(\frac{\sqrt{23}x}{2}\right) c_1 + e^{\frac{3x}{2}} \sin\left(\frac{\sqrt{23}x}{2}\right) c_2 + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = 4x^2 \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} e^{\frac{3x}{2}} \cos\left(\frac{\sqrt{23}x}{2}\right) & e^{\frac{3x}{2}} \sin\left(\frac{\sqrt{23}x}{2}\right) \\ \frac{3e^{\frac{3x}{2}} \cos\left(\frac{\sqrt{23}x}{2}\right)}{2} - \frac{\sin\left(\frac{\sqrt{23}x}{2}\right) e^{\frac{3x}{2}} \sqrt{23}}{2} & \frac{3e^{\frac{3x}{2}} \sin\left(\frac{\sqrt{23}x}{2}\right)}{2} + \frac{e^{\frac{3x}{2}} \sqrt{23} \cos\left(\frac{\sqrt{23}x}{2}\right)}{2} \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = \frac{\sqrt{23}e^{3x}}{2}$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = -\frac{8e^{\frac{3x}{2}}\sqrt{23}\left(\cos\left(\frac{\sqrt{23}x}{2}\right)\left(\int x^2 e^{-\frac{3x}{2}} \sin\left(\frac{\sqrt{23}x}{2}\right) dx\right) - \sin\left(\frac{\sqrt{23}x}{2}\right)\left(\int x^2 e^{-\frac{3x}{2}} \cos\left(\frac{\sqrt{23}x}{2}\right) dx\right)\right)}{23}$$

- Compute integrals

$$y_p(x) = \frac{1}{2}x^2 + \frac{3}{8}x + \frac{1}{64}$$

- Substitute particular solution into general solution to ODE

$$y = e^{\frac{3x}{2}} \cos\left(\frac{\sqrt{23}x}{2}\right) c_1 + e^{\frac{3x}{2}} \sin\left(\frac{\sqrt{23}x}{2}\right) c_2 + \frac{x^2}{2} + \frac{3x}{8} + \frac{1}{64}$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
trying a double symmetry of the form [xi=0, eta=F(x)]
-> Try solving first the homogeneous part of the ODE
    checking if the LODE has constant coefficients
    <- constant coefficients successful
<- solving first the homogeneous part of the ODE successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 40

```
dsolve(diff(y(x),x$2)-3*diff(y(x),x)+8*y(x)=4*x^2,y(x), singsol=all)
```

$$y(x) = e^{\frac{3x}{2}} \sin\left(\frac{\sqrt{23}x}{2}\right) c_2 + e^{\frac{3x}{2}} \cos\left(\frac{\sqrt{23}x}{2}\right) c_1 + \frac{x^2}{2} + \frac{3x}{8} + \frac{1}{64}$$

✓ Solution by Mathematica

Time used: 0.026 (sec). Leaf size: 63

```
DSolve[y''[x]-3*y'[x]+8*y[x]==4*x^2,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{x^2}{2} + \frac{3x}{8} + c_2 e^{3x/2} \cos\left(\frac{\sqrt{23}x}{2}\right) + c_1 e^{3x/2} \sin\left(\frac{\sqrt{23}x}{2}\right) + \frac{1}{64}$$

11.2 problem 2

11.2.1 Solving as second order linear constant coeff ode	2263
11.2.2 Solving using Kovacic algorithm	2266
11.2.3 Maple step by step solution	2271

Internal problem ID [11776]

Internal file name [OUTPUT/11785_Thursday_April_11_2024_08_49_38_PM_3825123/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 2.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' - 2y' - 8y = 4e^{2x} - 21e^{-3x}$$

11.2.1 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = -2, C = -8, f(x) = (4e^{5x} - 21)e^{-3x}$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' - 2y' - 8y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = -2, C = -8$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} - 2\lambda e^{\lambda x} - 8 e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 - 2\lambda - 8 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = -2, C = -8$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{2}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{-2^2 - (4)(1)(-8)} \\ &= 1 \pm 3 \end{aligned}$$

Hence

$$\lambda_1 = 1 + 3$$

$$\lambda_2 = 1 - 3$$

Which simplifies to

$$\lambda_1 = 4$$

$$\lambda_2 = -2$$

Since roots are real and distinct, then the solution is

$$y = c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x}$$

$$y = c_1 e^{(4)x} + c_2 e^{(-2)x}$$

Or

$$y = c_1 e^{4x} + c_2 e^{-2x}$$

Therefore the homogeneous solution y_h is

$$y_h = c_1 e^{4x} + c_2 e^{-2x}$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$(4e^{5x} - 21)e^{-3x}$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{e^{-3x}\}, \{e^{2x}\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^{-2x}, e^{4x}\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1e^{-3x} + A_2e^{2x}$$

The unknowns $\{A_1, A_2\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$7A_1e^{-3x} - 8A_2e^{2x} = (4e^{5x} - 21)e^{-3x}$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = -3, A_2 = -\frac{1}{2} \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = -3e^{-3x} - \frac{e^{2x}}{2}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1e^{4x} + c_2e^{-2x}) + \left(-3e^{-3x} - \frac{e^{2x}}{2} \right) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1e^{4x} + c_2e^{-2x} - 3e^{-3x} - \frac{e^{2x}}{2} \quad (1)$$

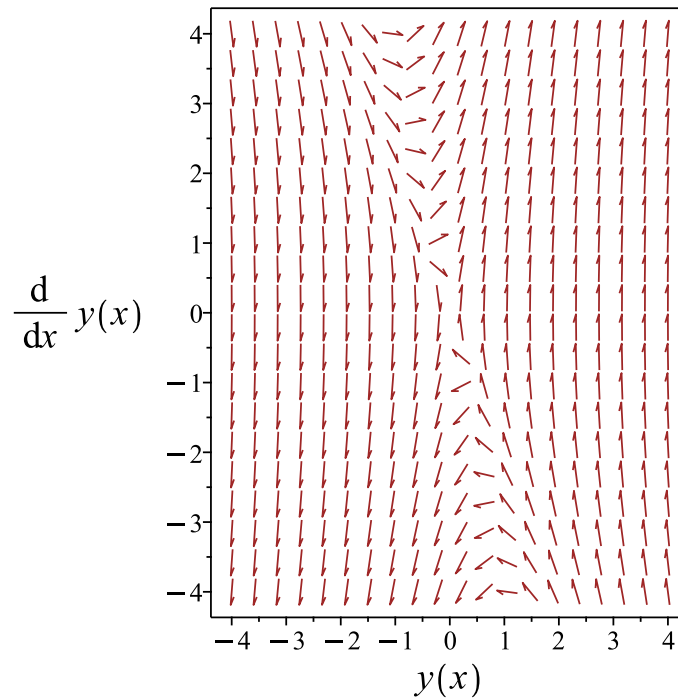


Figure 418: Slope field plot

Verification of solutions

$$y = c_1 e^{4x} + c_2 e^{-2x} - 3e^{-3x} - \frac{e^{2x}}{2}$$

Verified OK.

11.2.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' - 2y' - 8y = 0 \tag{1}$$

$$Ay'' + By' + Cy = 0 \tag{2}$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= -2 \\ C &= -8 \end{aligned} \tag{3}$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$r = \frac{s}{t} = \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{9}{1} \tag{6}$$

Comparing the above to (5) shows that

$$s = 9$$

$$t = 1$$

Therefore eq. (4) becomes

$$z''(x) = 9z(x) \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 347: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = 9$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = e^{-3x}$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-2}{1} dx} \\ &= z_1 e^x \\ &= z_1 (e^x) \end{aligned}$$

Which simplifies to

$$y_1 = e^{-2x}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{-2}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{2x}}{(y_1)^2} dx \\ &= y_1 \left(\frac{e^{6x}}{6} \right) \end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (e^{-2x}) + c_2 \left(e^{-2x} \left(\frac{e^{6x}}{6} \right) \right)\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' - 2y' - 8y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1 e^{-2x} + \frac{c_2 e^{4x}}{6}$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$(4e^{5x} - 21)e^{-3x}$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{e^{-3x}\}, \{e^{2x}\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\left\{ \frac{e^{4x}}{6}, e^{-2x} \right\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1 e^{-3x} + A_2 e^{2x}$$

The unknowns $\{A_1, A_2\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$7A_1e^{-3x} - 8A_2e^{2x} = (4e^{5x} - 21)e^{-3x}$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = -3, A_2 = -\frac{1}{2} \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = -3e^{-3x} - \frac{e^{2x}}{2}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(c_1e^{-2x} + \frac{c_2e^{4x}}{6} \right) + \left(-3e^{-3x} - \frac{e^{2x}}{2} \right) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1e^{-2x} + \frac{c_2e^{4x}}{6} - 3e^{-3x} - \frac{e^{2x}}{2} \quad (1)$$

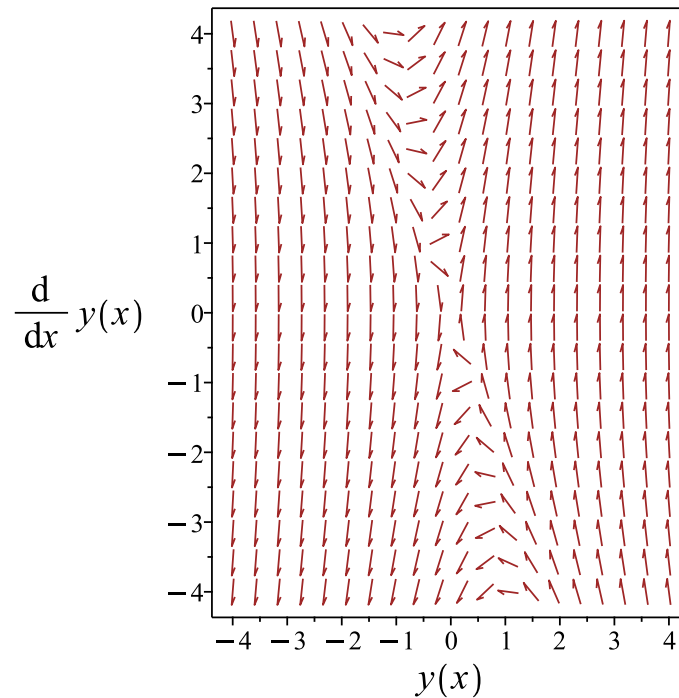


Figure 419: Slope field plot

Verification of solutions

$$y = c_1 e^{-2x} + \frac{c_2 e^{4x}}{6} - 3e^{-3x} - \frac{e^{2x}}{2}$$

Verified OK.

11.2.3 Maple step by step solution

Let's solve

$$y'' - 2y' - 8y = (4e^{5x} - 21)e^{-3x}$$

- Highest derivative means the order of the ODE is 2
 y''
- Characteristic polynomial of homogeneous ODE
 $r^2 - 2r - 8 = 0$
- Factor the characteristic polynomial
 $(r + 2)(r - 4) = 0$
- Roots of the characteristic polynomial

$$r = (-2, 4)$$

- 1st solution of the homogeneous ODE

$$y_1(x) = e^{-2x}$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = e^{4x}$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = c_1 e^{-2x} + c_2 e^{4x} + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = (4e^{5x} - 21)e^{-3x} \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} e^{-2x} & e^{4x} \\ -2e^{-2x} & 4e^{4x} \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = 6e^{2x}$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = -\frac{e^{-2x} \left(\int (4e^{4x} - 21e^{-x}) dx \right)}{6} + \frac{e^{4x} \left(\int (4e^{5x} - 21)e^{-7x} dx \right)}{6}$$

- Compute integrals

$$y_p(x) = -\frac{(e^{5x} + 6)e^{-3x}}{2}$$

- Substitute particular solution into general solution to ODE

$$y = c_1 e^{-2x} + c_2 e^{4x} - \frac{(e^{5x} + 6)e^{-3x}}{2}$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]  
trying a double symmetry of the form [xi=0, eta=F(x)]  
-> Try solving first the homogeneous part of the ODE  
    checking if the LODE has constant coefficients  
    <- constant coefficients successful  
<- solving first the homogeneous part of the ODE successful`
```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 30

```
dsolve(diff(y(x),x$2)-2*diff(y(x),x)-8*y(x)=4*exp(2*x)-21*exp(-3*x),y(x), singsol=all)
```

$$y(x) = \frac{(2c_2e^{7x} - e^{5x} + 2c_1e^x - 6)e^{-3x}}{2}$$

✓ Solution by Mathematica

Time used: 0.098 (sec). Leaf size: 38

```
DSolve[y''[x]-2*y'[x]-8*y[x]==4*Exp[2*x]-21*Exp[-3*x],y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow -\frac{1}{2}e^{-3x}(e^{5x} + 6) + c_1e^{-2x} + c_2e^{4x}$$

11.3 problem 3

11.3.1 Solving as second order linear constant coeff ode	2274
11.3.2 Solving using Kovacic algorithm	2277
11.3.3 Maple step by step solution	2282

Internal problem ID [11777]

Internal file name [OUTPUT/11786_Thursday_April_11_2024_08_49_38_PM_85345288/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 3.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' + 2y' + 5y = 6 \sin(2x) + 7 \cos(2x)$$

11.3.1 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = 2, C = 5, f(x) = 6 \sin(2x) + 7 \cos(2x)$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 2y' + 5y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 2, C = 5$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + 2\lambda e^{\lambda x} + 5 e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 2\lambda + 5 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 2, C = 5$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{-2}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{2^2 - (4)(1)(5)} \\ &= -1 \pm 2i \end{aligned}$$

Hence

$$\lambda_1 = -1 + 2i$$

$$\lambda_2 = -1 - 2i$$

Which simplifies to

$$\lambda_1 = -1 + 2i$$

$$\lambda_2 = -1 - 2i$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = -1$ and $\beta = 2$. Therefore the final solution, when using Euler relation, can be written as

$$y = e^{\alpha x} (c_1 \cos(\beta x) + c_2 \sin(\beta x))$$

Which becomes

$$y = e^{-x} (c_1 \cos(2x) + c_2 \sin(2x))$$

Therefore the homogeneous solution y_h is

$$y_h = e^{-x} (c_1 \cos(2x) + c_2 \sin(2x))$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$6 \sin (2x) + 7 \cos (2x)$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{\cos (2x), \sin (2x)\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^{-x} \cos (2x), e^{-x} \sin (2x)\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1 \cos (2x) + A_2 \sin (2x)$$

The unknowns $\{A_1, A_2\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$A_1 \cos (2x) + A_2 \sin (2x) - 4A_1 \sin (2x) + 4A_2 \cos (2x) = 6 \sin (2x) + 7 \cos (2x)$$

Solving for the unknowns by comparing coefficients results in

$$[A_1 = -1, A_2 = 2]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = -\cos (2x) + 2 \sin (2x)$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (e^{-x}(c_1 \cos (2x) + c_2 \sin (2x))) + (-\cos (2x) + 2 \sin (2x)) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = e^{-x}(c_1 \cos (2x) + c_2 \sin (2x)) - \cos (2x) + 2 \sin (2x) \quad (1)$$

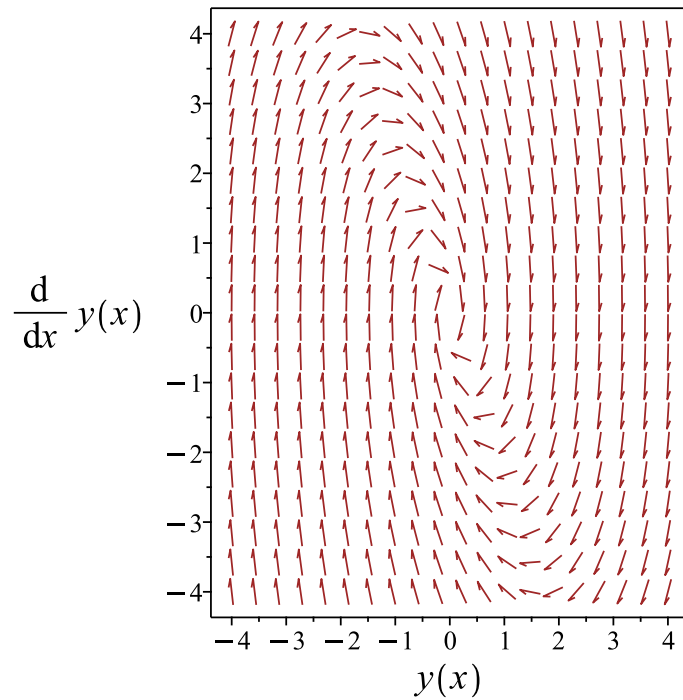


Figure 420: Slope field plot

Verification of solutions

$$y = e^{-x}(c_1 \cos(2x) + c_2 \sin(2x)) - \cos(2x) + 2 \sin(2x)$$

Verified OK.

11.3.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' + 2y' + 5y = 0 \tag{1}$$

$$Ay'' + By' + Cy = 0 \tag{2}$$

Comparing (1) and (2) shows that

$$A = 1$$

$$B = 2 \tag{3}$$

$$C = 5$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-4}{1} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= -4 \\ t &= 1 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = -4z(x) \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 349: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned}O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0\end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = -4$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = \cos(2x)$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned}y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{2}{1} dx} \\ &= z_1 e^{-x} \\ &= z_1 (e^{-x})\end{aligned}$$

Which simplifies to

$$y_1 = e^{-x} \cos(2x)$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{2}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{-2x}}{(y_1)^2} dx \\ &= y_1 \left(\frac{\tan(2x)}{2} \right)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (e^{-x} \cos(2x)) + c_2 \left(e^{-x} \cos(2x) \left(\frac{\tan(2x)}{2} \right) \right)\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 2y' + 5y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1 e^{-x} \cos(2x) + \frac{c_2 e^{-x} \sin(2x)}{2}$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$6 \sin(2x) + 7 \cos(2x)$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{\cos(2x), \sin(2x)\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\left\{ e^{-x} \cos(2x), \frac{e^{-x} \sin(2x)}{2} \right\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1 \cos(2x) + A_2 \sin(2x)$$

The unknowns $\{A_1, A_2\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$A_1 \cos(2x) + A_2 \sin(2x) - 4A_1 \sin(2x) + 4A_2 \cos(2x) = 6 \sin(2x) + 7 \cos(2x)$$

Solving for the unknowns by comparing coefficients results in

$$[A_1 = -1, A_2 = 2]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = -\cos(2x) + 2 \sin(2x)$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(c_1 e^{-x} \cos(2x) + \frac{c_2 e^{-x} \sin(2x)}{2} \right) + (-\cos(2x) + 2 \sin(2x)) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 e^{-x} \cos(2x) + \frac{c_2 e^{-x} \sin(2x)}{2} - \cos(2x) + 2 \sin(2x) \quad (1)$$

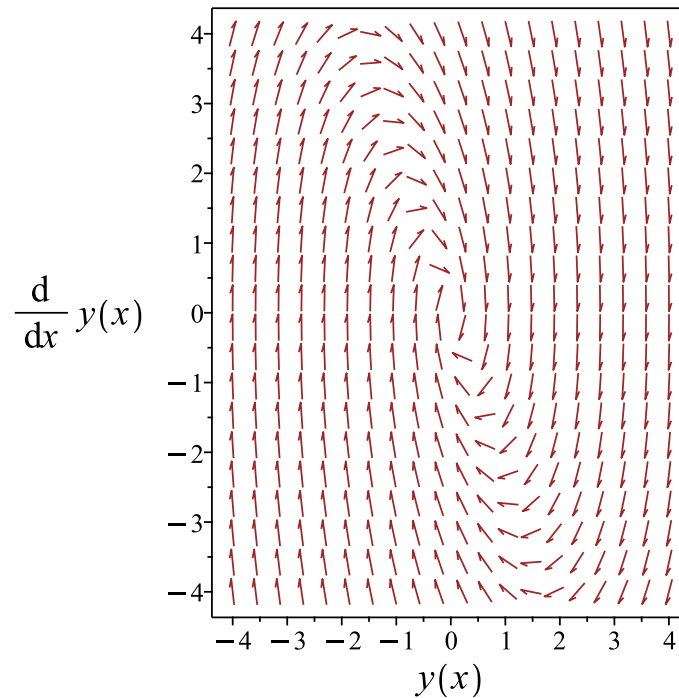


Figure 421: Slope field plot

Verification of solutions

$$y = c_1 e^{-x} \cos(2x) + \frac{c_2 e^{-x} \sin(2x)}{2} - \cos(2x) + 2 \sin(2x)$$

Verified OK.

11.3.3 Maple step by step solution

Let's solve

$$y'' + 2y' + 5y = 6 \sin(2x) + 7 \cos(2x)$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of homogeneous ODE

$$r^2 + 2r + 5 = 0$$

- Use quadratic formula to solve for r

$$r = \frac{(-2) \pm (\sqrt{-16})}{2}$$

- Roots of the characteristic polynomial

$$r = (-1 - 2I, -1 + 2I)$$

- 1st solution of the homogeneous ODE

$$y_1(x) = e^{-x} \cos(2x)$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = e^{-x} \sin(2x)$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = c_1 e^{-x} \cos(2x) + c_2 e^{-x} \sin(2x) + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = 6 \sin(2x) + 7 \cos(2x) \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} e^{-x} \cos(2x) & e^{-x} \sin(2x) \\ -e^{-x} \cos(2x) - 2e^{-x} \sin(2x) & -e^{-x} \sin(2x) + 2e^{-x} \cos(2x) \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = 2e^{-2x}$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = \frac{e^{-x} (\cos(2x) (\int (-7 \sin(4x) - 6 + 6 \cos(4x)) e^x dx) + \sin(2x) (\int (7 \cos(4x) + 7 + 6 \sin(4x)) e^x dx))}{4}$$

- Compute integrals

$$y_p(x) = -\cos(2x) + 2 \sin(2x)$$

- Substitute particular solution into general solution to ODE

$$y = c_1 e^{-x} \cos(2x) + c_2 e^{-x} \sin(2x) - \cos(2x) + 2 \sin(2x)$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]  
trying a double symmetry of the form [xi=0, eta=F(x)]  
-> Try solving first the homogeneous part of the ODE  
    checking if the LODE has constant coefficients  
    <- constant coefficients successful  
<- solving first the homogeneous part of the ODE successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 35

```
dsolve(diff(y(x),x$2)+2*diff(y(x),x)+5*y(x)=6*sin(2*x)+7*cos(2*x),y(x), singsol=all)
```

$$y(x) = (\cos(2x)c_1 + c_2 \sin(2x))e^{-x} - \cos(2x) + 2 \sin(2x)$$

✓ Solution by Mathematica

Time used: 0.026 (sec). Leaf size: 38

```
DSolve[y''[x]+2*y'[x]+5*y[x]==6*Sin[2*x]+7*Cos[2*x],y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^{-x}((-e^x + c_2) \cos(2x) + (2e^x + c_1) \sin(2x))$$

11.4 problem 4

11.4.1 Solving as second order linear constant coeff ode	2285
11.4.2 Solving using Kovacic algorithm	2288
11.4.3 Maple step by step solution	2293

Internal problem ID [11778]

Internal file name [OUTPUT/11787_Thursday_April_11_2024_08_49_39_PM_78115731/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 4.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' + 2y' + 2y = 10 \sin(4x)$$

11.4.1 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = 2, C = 2, f(x) = 10 \sin(4x)$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 2y' + 2y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 2, C = 2$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + 2\lambda e^{\lambda x} + 2e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 2\lambda + 2 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 2, C = 2$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{-2}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{2^2 - (4)(1)(2)} \\ &= -1 \pm i \end{aligned}$$

Hence

$$\lambda_1 = -1 + i$$

$$\lambda_2 = -1 - i$$

Which simplifies to

$$\lambda_1 = -1 + i$$

$$\lambda_2 = -1 - i$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = -1$ and $\beta = 1$. Therefore the final solution, when using Euler relation, can be written as

$$y = e^{\alpha x} (c_1 \cos(\beta x) + c_2 \sin(\beta x))$$

Which becomes

$$y = e^{-x} (c_1 \cos(x) + c_2 \sin(x))$$

Therefore the homogeneous solution y_h is

$$y_h = e^{-x} (c_1 \cos(x) + c_2 \sin(x))$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$10 \sin(4x)$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{\cos(4x), \sin(4x)\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^{-x} \cos(x), e^{-x} \sin(x)\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1 \cos(4x) + A_2 \sin(4x)$$

The unknowns $\{A_1, A_2\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$-14A_1 \cos(4x) - 14A_2 \sin(4x) - 8A_1 \sin(4x) + 8A_2 \cos(4x) = 10 \sin(4x)$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = -\frac{4}{13}, A_2 = -\frac{7}{13} \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = -\frac{4 \cos(4x)}{13} - \frac{7 \sin(4x)}{13}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (e^{-x}(c_1 \cos(x) + c_2 \sin(x))) + \left(-\frac{4 \cos(4x)}{13} - \frac{7 \sin(4x)}{13} \right) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = e^{-x}(c_1 \cos(x) + c_2 \sin(x)) - \frac{4 \cos(4x)}{13} - \frac{7 \sin(4x)}{13} \quad (1)$$

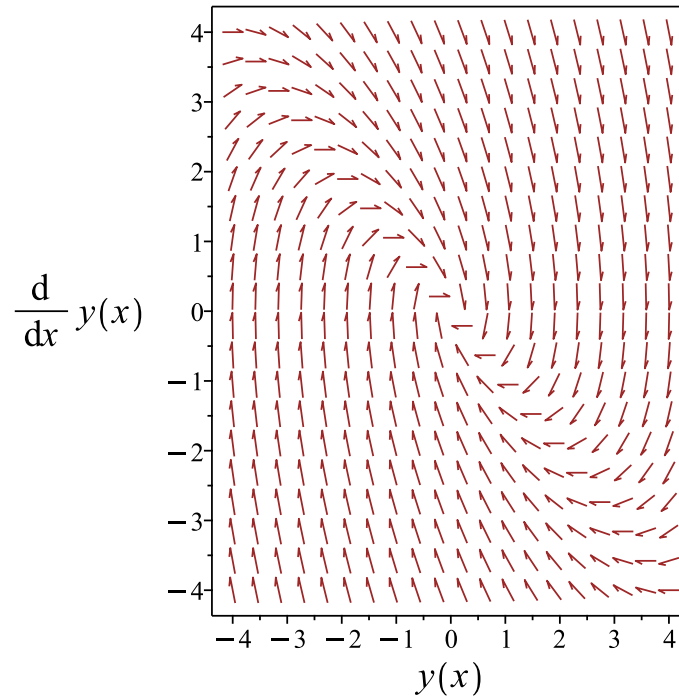


Figure 422: Slope field plot

Verification of solutions

$$y = e^{-x}(c_1 \cos(x) + c_2 \sin(x)) - \frac{4 \cos(4x)}{13} - \frac{7 \sin(4x)}{13}$$

Verified OK.

11.4.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' + 2y' + 2y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned}A &= 1 \\B &= 2 \\C &= 2\end{aligned}\tag{3}$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x)\tag{4}$$

Where r is given by

$$\begin{aligned}r &= \frac{s}{t} \\&= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2}\end{aligned}\tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-1}{1}\tag{6}$$

Comparing the above to (5) shows that

$$\begin{aligned}s &= -1 \\t &= 1\end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = -z(x)\tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 351: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned}
 \mathcal{O}(\infty) &= \deg(t) - \deg(s) \\
 &= 0 - 0 \\
 &= 0
 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = -1$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = \cos(x)$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned}
 y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\
 &= z_1 e^{-\int \frac{1}{2} \frac{2}{1} dx} \\
 &= z_1 e^{-x} \\
 &= z_1 (e^{-x})
 \end{aligned}$$

Which simplifies to

$$y_1 = e^{-x} \cos(x)$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{2}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{-2x}}{(y_1)^2} dx \\ &= y_1(\tan(x)) \end{aligned}$$

Therefore the solution is

$$\begin{aligned} y &= c_1 y_1 + c_2 y_2 \\ &= c_1(e^{-x} \cos(x)) + c_2(e^{-x} \cos(x) (\tan(x))) \end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 2y' + 2y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = \cos(x) e^{-x} c_1 + \sin(x) e^{-x} c_2$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$10 \sin(4x)$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{\cos(4x), \sin(4x)\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^{-x} \cos(x), e^{-x} \sin(x)\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1 \cos(4x) + A_2 \sin(4x)$$

The unknowns $\{A_1, A_2\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$-14A_1 \cos(4x) - 14A_2 \sin(4x) - 8A_1 \sin(4x) + 8A_2 \cos(4x) = 10 \sin(4x)$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = -\frac{4}{13}, A_2 = -\frac{7}{13} \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = -\frac{4 \cos(4x)}{13} - \frac{7 \sin(4x)}{13}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (\cos(x) e^{-x} c_1 + \sin(x) e^{-x} c_2) + \left(-\frac{4 \cos(4x)}{13} - \frac{7 \sin(4x)}{13} \right) \end{aligned}$$

Which simplifies to

$$y = e^{-x}(c_1 \cos(x) + c_2 \sin(x)) - \frac{4 \cos(4x)}{13} - \frac{7 \sin(4x)}{13}$$

Summary

The solution(s) found are the following

$$y = e^{-x}(c_1 \cos(x) + c_2 \sin(x)) - \frac{4 \cos(4x)}{13} - \frac{7 \sin(4x)}{13} \quad (1)$$

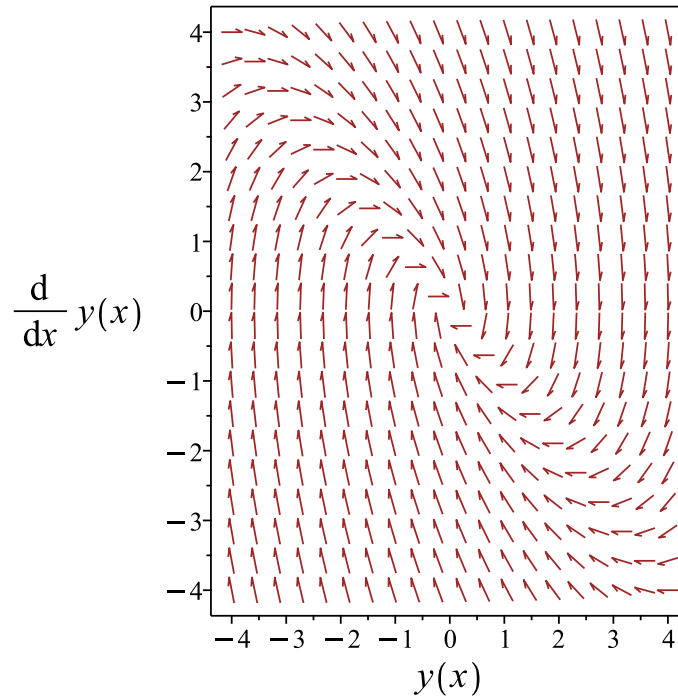


Figure 423: Slope field plot

Verification of solutions

$$y = e^{-x}(c_1 \cos(x) + c_2 \sin(x)) - \frac{4 \cos(4x)}{13} - \frac{7 \sin(4x)}{13}$$

Verified OK.

11.4.3 Maple step by step solution

Let's solve

$$y'' + 2y' + 2y = 10 \sin(4x)$$

- Highest derivative means the order of the ODE is 2
- y''
- Characteristic polynomial of homogeneous ODE

$$r^2 + 2r + 2 = 0$$

- Use quadratic formula to solve for r

$$r = \frac{(-2) \pm (\sqrt{-4})}{2}$$

- Roots of the characteristic polynomial

$$r = (-1 - I, -1 + I)$$

- 1st solution of the homogeneous ODE

$$y_1(x) = e^{-x} \cos(x)$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = e^{-x} \sin(x)$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = \cos(x) e^{-x} c_1 + \sin(x) e^{-x} c_2 + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = 10 \sin(4x) \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} e^{-x} \cos(x) & e^{-x} \sin(x) \\ -e^{-x} \cos(x) - e^{-x} \sin(x) & -e^{-x} \sin(x) + e^{-x} \cos(x) \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = e^{-2x}$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = -10 e^{-x} (\cos(x) (\int \sin(x) \sin(4x) e^x dx) - \sin(x) (\int \cos(x) \sin(4x) e^x dx))$$

- Compute integrals

$$y_p(x) = -\frac{4 \cos(4x)}{13} - \frac{7 \sin(4x)}{13}$$

- Substitute particular solution into general solution to ODE

$$y = \cos(x) e^{-x} c_1 + \sin(x) e^{-x} c_2 - \frac{7 \sin(4x)}{13} - \frac{4 \cos(4x)}{13}$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]  
trying a double symmetry of the form [xi=0, eta=F(x)]  
-> Try solving first the homogeneous part of the ODE  
    checking if the LODE has constant coefficients  
    <- constant coefficients successful  
<- solving first the homogeneous part of the ODE successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 33

```
dsolve(diff(y(x),x$2)+2*diff(y(x),x)+2*y(x)=10*sin(4*x),y(x), singsol=all)
```

$$y(x) = e^{-x} \sin(x) c_2 + e^{-x} \cos(x) c_1 - \frac{7 \sin(4x)}{13} - \frac{4 \cos(4x)}{13}$$

✓ Solution by Mathematica

Time used: 0.026 (sec). Leaf size: 42

```
DSolve[y''[x]+2*y'[x]+2*y[x]==10*Sin[4*x],y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow -\frac{7}{13} \sin(4x) - \frac{4}{13} \cos(4x) + c_2 e^{-x} \cos(x) + c_1 e^{-x} \sin(x)$$

11.5 problem 5

11.5.1 Solving as second order linear constant coeff ode	2296
11.5.2 Solving using Kovacic algorithm	2299
11.5.3 Maple step by step solution	2304

Internal problem ID [11779]

Internal file name [OUTPUT/11788_Thursday_April_11_2024_08_49_40_PM_7302965/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 5.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"kovacic", "second_order_linear_constant_coeff"**

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' + 2y' + 4y = \cos(4x)$$

11.5.1 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = 2, C = 4, f(x) = \cos(4x)$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 2y' + 4y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 2, C = 4$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + 2\lambda e^{\lambda x} + 4e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 2\lambda + 4 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 2, C = 4$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{-2}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{2^2 - (4)(1)(4)} \\ &= -1 \pm i\sqrt{3} \end{aligned}$$

Hence

$$\lambda_1 = -1 + i\sqrt{3}$$

$$\lambda_2 = -1 - i\sqrt{3}$$

Which simplifies to

$$\lambda_1 = i\sqrt{3} - 1$$

$$\lambda_2 = -i\sqrt{3} - 1$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = -1$ and $\beta = \sqrt{3}$. Therefore the final solution, when using Euler relation, can be written as

$$y = e^{\alpha x} (c_1 \cos(\beta x) + c_2 \sin(\beta x))$$

Which becomes

$$y = e^{-x} \left(c_1 \cos(\sqrt{3}x) + c_2 \sin(\sqrt{3}x) \right)$$

Therefore the homogeneous solution y_h is

$$y_h = e^{-x} \left(c_1 \cos(\sqrt{3}x) + c_2 \sin(\sqrt{3}x) \right)$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$\cos(4x)$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{\cos(4x), \sin(4x)\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^{-x} \cos(\sqrt{3}x), e^{-x} \sin(\sqrt{3}x)\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1 \cos(4x) + A_2 \sin(4x)$$

The unknowns $\{A_1, A_2\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$-12A_1 \cos(4x) - 12A_2 \sin(4x) - 8A_1 \sin(4x) + 8A_2 \cos(4x) = \cos(4x)$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = -\frac{3}{52}, A_2 = \frac{1}{26} \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = -\frac{3 \cos(4x)}{52} + \frac{\sin(4x)}{26}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(e^{-x} \left(c_1 \cos(\sqrt{3}x) + c_2 \sin(\sqrt{3}x) \right) \right) + \left(-\frac{3 \cos(4x)}{52} + \frac{\sin(4x)}{26} \right) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = e^{-x} \left(c_1 \cos(\sqrt{3}x) + c_2 \sin(\sqrt{3}x) \right) - \frac{3 \cos(4x)}{52} + \frac{\sin(4x)}{26} \quad (1)$$

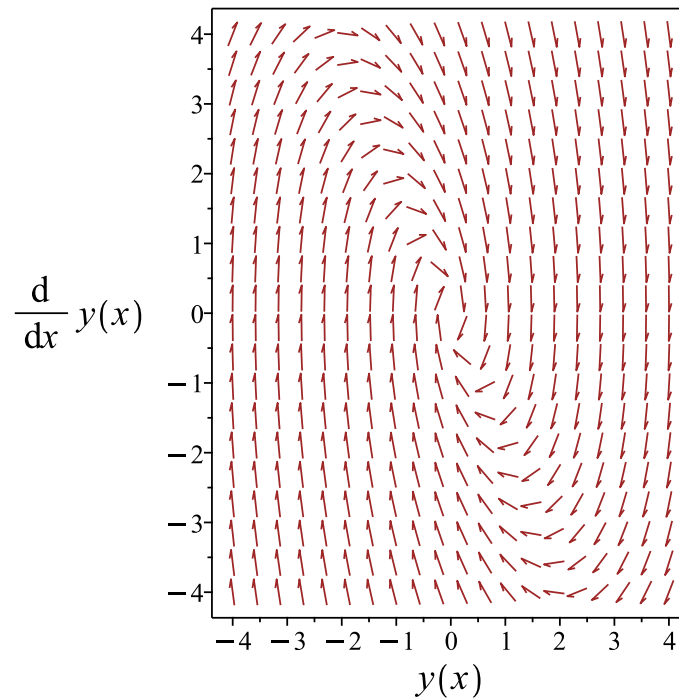


Figure 424: Slope field plot

Verification of solutions

$$y = e^{-x} \left(c_1 \cos(\sqrt{3}x) + c_2 \sin(\sqrt{3}x) \right) - \frac{3 \cos(4x)}{52} + \frac{\sin(4x)}{26}$$

Verified OK.

11.5.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' + 2y' + 4y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned}A &= 1 \\B &= 2 \\C &= 4\end{aligned}\tag{3}$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x)\tag{4}$$

Where r is given by

$$\begin{aligned}r &= \frac{s}{t} \\&= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2}\end{aligned}\tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-3}{1}\tag{6}$$

Comparing the above to (5) shows that

$$\begin{aligned}s &= -3 \\t &= 1\end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = -3z(x)\tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 353: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned}
 \mathcal{O}(\infty) &= \deg(t) - \deg(s) \\
 &= 0 - 0 \\
 &= 0
 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = -3$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = \cos(\sqrt{3}x)$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned}
 y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\
 &= z_1 e^{-\int \frac{1}{2} \frac{2}{1} dx} \\
 &= z_1 e^{-x} \\
 &= z_1 (e^{-x})
 \end{aligned}$$

Which simplifies to

$$y_1 = e^{-x} \cos(\sqrt{3}x)$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{2}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{-2x}}{(y_1)^2} dx \\ &= y_1 \left(\frac{\sqrt{3} \tan(\sqrt{3}x)}{3} \right) \end{aligned}$$

Therefore the solution is

$$\begin{aligned} y &= c_1 y_1 + c_2 y_2 \\ &= c_1 \left(e^{-x} \cos(\sqrt{3}x) \right) + c_2 \left(e^{-x} \cos(\sqrt{3}x) \left(\frac{\sqrt{3} \tan(\sqrt{3}x)}{3} \right) \right) \end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 2y' + 4y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = e^{-x} \cos(\sqrt{3}x) c_1 + \frac{c_2 \sin(\sqrt{3}x) e^{-x} \sqrt{3}}{3}$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$\cos(4x)$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{\cos(4x), \sin(4x)\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\left\{ e^{-x} \cos(\sqrt{3}x), \frac{\sin(\sqrt{3}x) e^{-x} \sqrt{3}}{3} \right\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1 \cos(4x) + A_2 \sin(4x)$$

The unknowns $\{A_1, A_2\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$-12A_1 \cos(4x) - 12A_2 \sin(4x) - 8A_1 \sin(4x) + 8A_2 \cos(4x) = \cos(4x)$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = -\frac{3}{52}, A_2 = \frac{1}{26} \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = -\frac{3 \cos(4x)}{52} + \frac{\sin(4x)}{26}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(e^{-x} \cos(\sqrt{3}x) c_1 + \frac{c_2 \sin(\sqrt{3}x) e^{-x} \sqrt{3}}{3} \right) + \left(-\frac{3 \cos(4x)}{52} + \frac{\sin(4x)}{26} \right) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = e^{-x} \cos(\sqrt{3}x) c_1 + \frac{c_2 \sin(\sqrt{3}x) e^{-x} \sqrt{3}}{3} - \frac{3 \cos(4x)}{52} + \frac{\sin(4x)}{26} \quad (1)$$

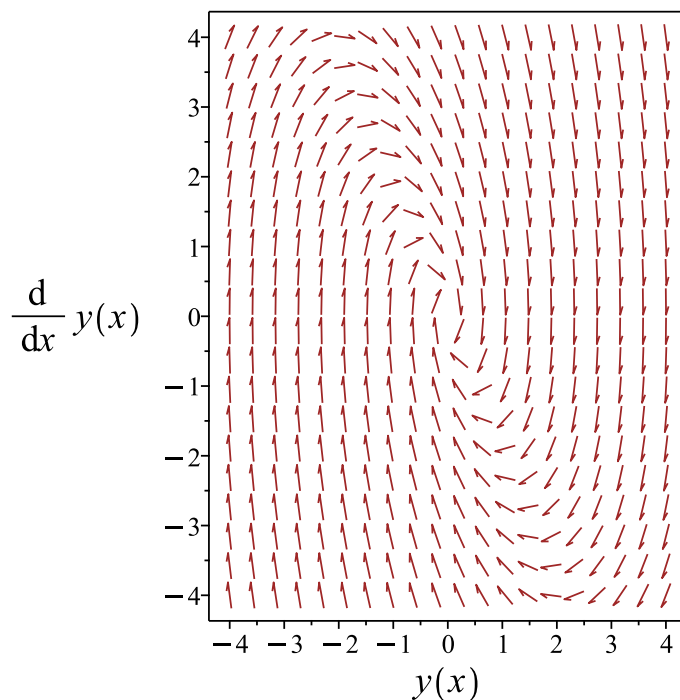


Figure 425: Slope field plot

Verification of solutions

$$y = e^{-x} \cos(\sqrt{3}x) c_1 + \frac{c_2 \sin(\sqrt{3}x) e^{-x} \sqrt{3}}{3} - \frac{3 \cos(4x)}{52} + \frac{\sin(4x)}{26}$$

Verified OK.

11.5.3 Maple step by step solution

Let's solve

$$y'' + 2y' + 4y = \cos(4x)$$

- Highest derivative means the order of the ODE is 2
- y''
- Characteristic polynomial of homogeneous ODE

$$r^2 + 2r + 4 = 0$$

- Use quadratic formula to solve for r

$$r = \frac{(-2) \pm (\sqrt{-12})}{2}$$

- Roots of the characteristic polynomial

$$r = (-I\sqrt{3} - 1, I\sqrt{3} - 1)$$

- 1st solution of the homogeneous ODE

$$y_1(x) = e^{-x} \cos(\sqrt{3}x)$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = e^{-x} \sin(\sqrt{3}x)$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = e^{-x} \cos(\sqrt{3}x) c_1 + e^{-x} \sin(\sqrt{3}x) c_2 + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = \cos(4x) \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{vmatrix} e^{-x} \cos(\sqrt{3}x) & e^{-x} \sin(\sqrt{3}x) \\ -e^{-x} \cos(\sqrt{3}x) - \sin(\sqrt{3}x) e^{-x} \sqrt{3} & -e^{-x} \sin(\sqrt{3}x) + e^{-x} \sqrt{3} \cos(\sqrt{3}x) \end{vmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = \sqrt{3} e^{-2x}$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = -\frac{e^{-x} \sqrt{3} \left(\cos(\sqrt{3}x) \left(\int \cos(4x) e^x \sin(\sqrt{3}x) dx \right) - \sin(\sqrt{3}x) \left(\int \cos(4x) e^x \cos(\sqrt{3}x) dx \right) \right)}{3}$$

- Compute integrals

$$y_p(x) = -\frac{3 \cos(4x)}{52} + \frac{\sin(4x)}{26}$$

- Substitute particular solution into general solution to ODE

$$y = e^{-x} \cos(\sqrt{3}x) c_1 + e^{-x} \sin(\sqrt{3}x) c_2 - \frac{3 \cos(4x)}{52} + \frac{\sin(4x)}{26}$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]  
trying a double symmetry of the form [xi=0, eta=F(x)]  
-> Try solving first the homogeneous part of the ODE  
    checking if the LODE has constant coefficients  
    <- constant coefficients successful  
<- solving first the homogeneous part of the ODE successful`
```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 41

```
dsolve(diff(y(x),x$2)+2*diff(y(x),x)+4*y(x)=cos(4*x),y(x), singsol=all)
```

$$y(x) = e^{-x} \sin(\sqrt{3}x) c_2 + e^{-x} \cos(\sqrt{3}x) c_1 + \frac{\sin(4x)}{26} - \frac{3 \cos(4x)}{52}$$

✓ Solution by Mathematica

Time used: 1.15 (sec). Leaf size: 54

```
DSolve[y''[x]+2*y'[x]+4*y[x]==Cos[4*x],y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{1}{26} \sin(4x) - \frac{3}{52} \cos(4x) + c_2 e^{-x} \cos(\sqrt{3}x) + c_1 e^{-x} \sin(\sqrt{3}x)$$

11.6 problem 6

11.6.1 Solving as second order linear constant coeff ode	2307
11.6.2 Solving using Kovacic algorithm	2310
11.6.3 Maple step by step solution	2315

Internal problem ID [11780]

Internal file name [OUTPUT/11789_Thursday_April_11_2024_08_49_40_PM_29232317/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 6.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$y'' - 3y' - 4y = 16x - 12e^{2x}$$

11.6.1 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = -3, C = -4, f(x) = 16x - 12e^{2x}$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' - 3y' - 4y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = -3, C = -4$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} - 3\lambda e^{\lambda x} - 4e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 - 3\lambda - 4 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = -3, C = -4$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{3}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{-3^2 - (4)(1)(-4)} \\ &= \frac{3}{2} \pm \frac{5}{2} \end{aligned}$$

Hence

$$\lambda_1 = \frac{3}{2} + \frac{5}{2}$$

$$\lambda_2 = \frac{3}{2} - \frac{5}{2}$$

Which simplifies to

$$\lambda_1 = 4$$

$$\lambda_2 = -1$$

Since roots are real and distinct, then the solution is

$$y = c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x}$$

$$y = c_1 e^{(4)x} + c_2 e^{(-1)x}$$

Or

$$y = c_1 e^{4x} + c_2 e^{-x}$$

Therefore the homogeneous solution y_h is

$$y_h = c_1 e^{4x} + c_2 e^{-x}$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$16x - 12e^{2x}$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{e^{2x}\}, \{1, x\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^{-x}, e^{4x}\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1e^{2x} + A_2 + A_3x$$

The unknowns $\{A_1, A_2, A_3\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$-6A_1e^{2x} - 3A_3 - 4A_2 - 4A_3x = 16x - 12e^{2x}$$

Solving for the unknowns by comparing coefficients results in

$$[A_1 = 2, A_2 = 3, A_3 = -4]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = 2e^{2x} + 3 - 4x$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1e^{4x} + c_2e^{-x}) + (2e^{2x} + 3 - 4x) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1e^{4x} + c_2e^{-x} + 2e^{2x} + 3 - 4x \tag{1}$$

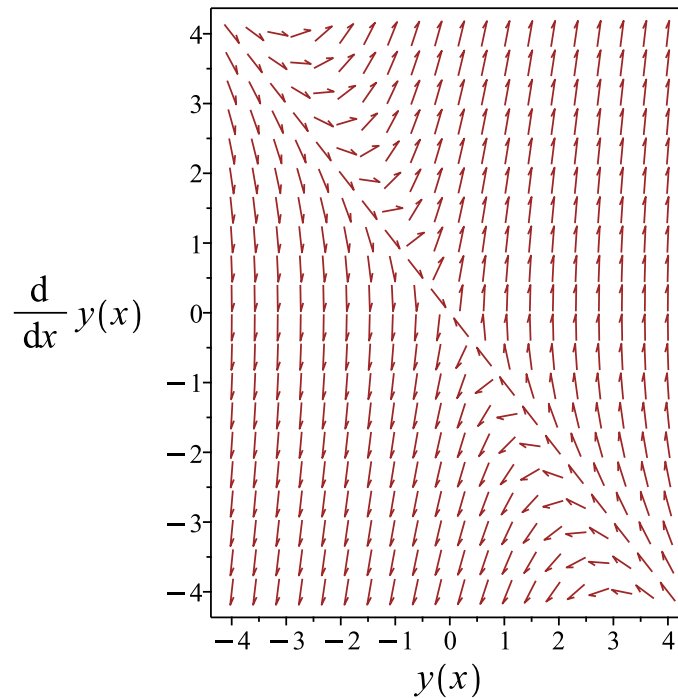


Figure 426: Slope field plot

Verification of solutions

$$y = c_1 e^{4x} + c_2 e^{-x} + 2e^{2x} + 3 - 4x$$

Verified OK.

11.6.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' - 3y' - 4y = 0 \tag{1}$$

$$Ay'' + By' + Cy = 0 \tag{2}$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= -3 \\ C &= -4 \end{aligned} \tag{3}$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{25}{4} \tag{6}$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 25 \\ t &= 4 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = \frac{25z(x)}{4} \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 355: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned}O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0\end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = \frac{25}{4}$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = e^{-\frac{5x}{2}}$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned}y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-3}{1} dx} \\ &= z_1 e^{\frac{3x}{2}} \\ &= z_1 \left(e^{\frac{3x}{2}} \right)\end{aligned}$$

Which simplifies to

$$y_1 = e^{-x}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{-3}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{3x}}{(y_1)^2} dx \\ &= y_1 \left(\frac{e^{5x}}{5} \right)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (e^{-x}) + c_2 \left(e^{-x} \left(\frac{e^{5x}}{5} \right) \right)\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' - 3y' - 4y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1 e^{-x} + \frac{c_2 e^{4x}}{5}$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$16x - 12e^{2x}$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{e^{2x}\}, \{1, x\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\left\{ \frac{e^{4x}}{5}, e^{-x} \right\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1 e^{2x} + A_2 + A_3 x$$

The unknowns $\{A_1, A_2, A_3\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$-6A_1e^{2x} - 3A_3 - 4A_2 - 4A_3x = 16x - 12e^{2x}$$

Solving for the unknowns by comparing coefficients results in

$$[A_1 = 2, A_2 = 3, A_3 = -4]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = 2e^{2x} + 3 - 4x$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(c_1e^{-x} + \frac{c_2e^{4x}}{5} \right) + (2e^{2x} + 3 - 4x) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1e^{-x} + \frac{c_2e^{4x}}{5} + 2e^{2x} + 3 - 4x \quad (1)$$

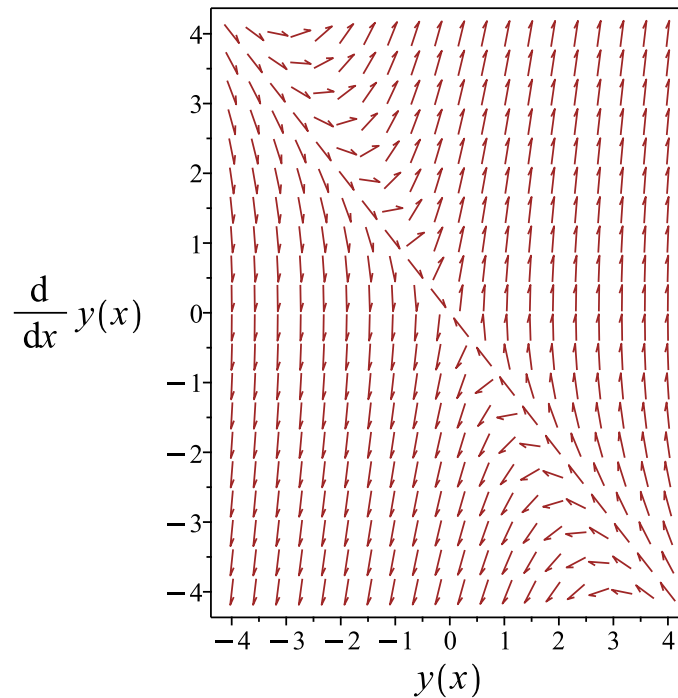


Figure 427: Slope field plot

Verification of solutions

$$y = c_1 e^{-x} + \frac{c_2 e^{4x}}{5} + 2e^{2x} + 3 - 4x$$

Verified OK.

11.6.3 Maple step by step solution

Let's solve

$$y'' - 3y' - 4y = 16x - 12e^{2x}$$

- Highest derivative means the order of the ODE is 2
 y''
- Characteristic polynomial of homogeneous ODE
 $r^2 - 3r - 4 = 0$
- Factor the characteristic polynomial
 $(r + 1)(r - 4) = 0$
- Roots of the characteristic polynomial

$$r = (-1, 4)$$

- 1st solution of the homogeneous ODE

$$y_1(x) = e^{-x}$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = e^{4x}$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = c_1 e^{-x} + c_2 e^{4x} + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = 16x - 12e^{2x} \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} e^{-x} & e^{4x} \\ -e^{-x} & 4e^{4x} \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = 5e^{3x}$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = \frac{4e^{-x} \left(\int (3e^{2x} - 4x)e^x dx \right)}{5} - \frac{4e^{4x} \left(\int (3e^{2x} - 4x)e^{-4x} dx \right)}{5}$$

- Compute integrals

$$y_p(x) = 2e^{2x} + 3 - 4x$$

- Substitute particular solution into general solution to ODE

$$y = c_1 e^{-x} + c_2 e^{4x} + 2e^{2x} + 3 - 4x$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]  
trying a double symmetry of the form [xi=0, eta=F(x)]  
-> Try solving first the homogeneous part of the ODE  
    checking if the LODE has constant coefficients  
    <- constant coefficients successful  
<- solving first the homogeneous part of the ODE successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 27

```
dsolve(diff(y(x),x$2)-3*diff(y(x),x)-4*y(x)=16*x-12*exp(2*x),y(x), singsol=all)
```

$$y(x) = c_2 e^{4x} + c_1 e^{-x} + 2e^{2x} - 4x + 3$$

✓ Solution by Mathematica

Time used: 0.136 (sec). Leaf size: 33

```
DSolve[y''[x]-3*y'[x]-4*y[x]==16*x-12*Exp[2*x],y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow -4x + 2e^{2x} + c_1 e^{-x} + c_2 e^{4x} + 3$$

11.7 problem 7

11.7.1 Solving as second order linear constant coeff ode	2318
11.7.2 Solving using Kovacic algorithm	2321
11.7.3 Maple step by step solution	2326

Internal problem ID [11781]

Internal file name [OUTPUT/11790_Thursday_April_11_2024_08_49_41_PM_4744995/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 7.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' + 6y' + 5y = 2e^x + 10e^{5x}$$

11.7.1 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = 6, C = 5, f(x) = 2e^x + 10e^{5x}$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 6y' + 5y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 6, C = 5$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + 6\lambda e^{\lambda x} + 5 e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 6\lambda + 5 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 6, C = 5$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{-6}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{6^2 - (4)(1)(5)} \\ &= -3 \pm 2 \end{aligned}$$

Hence

$$\lambda_1 = -3 + 2$$

$$\lambda_2 = -3 - 2$$

Which simplifies to

$$\lambda_1 = -1$$

$$\lambda_2 = -5$$

Since roots are real and distinct, then the solution is

$$y = c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x}$$

$$y = c_1 e^{(-1)x} + c_2 e^{(-5)x}$$

Or

$$y = c_1 e^{-x} + c_2 e^{-5x}$$

Therefore the homogeneous solution y_h is

$$y_h = c_1 e^{-x} + c_2 e^{-5x}$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$2e^x + 10e^{5x}$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{e^x\}, \{e^{5x}\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^{-5x}, e^{-x}\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1e^x + A_2e^{5x}$$

The unknowns $\{A_1, A_2\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$12A_1e^x + 60A_2e^{5x} = 2e^x + 10e^{5x}$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = \frac{1}{6}, A_2 = \frac{1}{6} \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = \frac{e^x}{6} + \frac{e^{5x}}{6}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1e^{-x} + c_2e^{-5x}) + \left(\frac{e^x}{6} + \frac{e^{5x}}{6} \right) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1e^{-x} + c_2e^{-5x} + \frac{e^x}{6} + \frac{e^{5x}}{6} \quad (1)$$

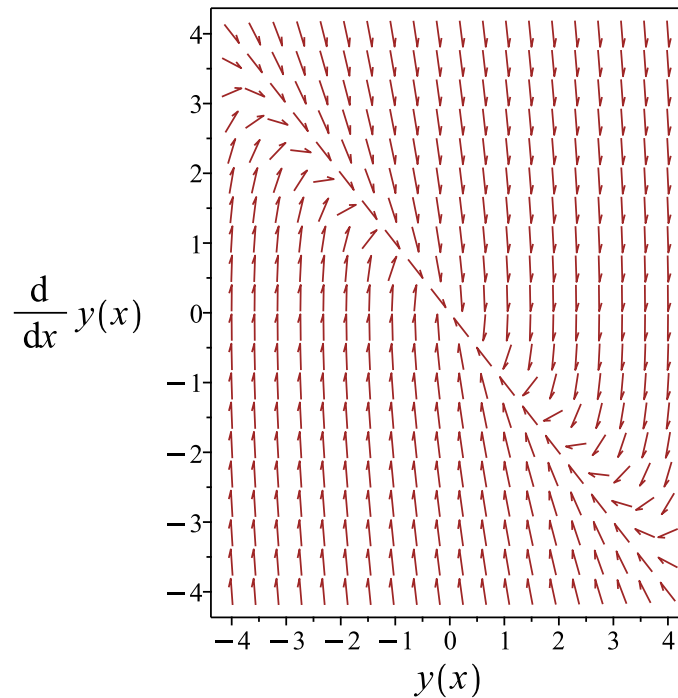


Figure 428: Slope field plot

Verification of solutions

$$y = c_1 e^{-x} + c_2 e^{-5x} + \frac{e^x}{6} + \frac{e^{5x}}{6}$$

Verified OK.

11.7.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' + 6y' + 5y = 0 \tag{1}$$

$$Ay'' + By' + Cy = 0 \tag{2}$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= 6 \\ C &= 5 \end{aligned} \tag{3}$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$r = \frac{s}{t} = \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{4}{1} \tag{6}$$

Comparing the above to (5) shows that

$$s = 4$$

$$t = 1$$

Therefore eq. (4) becomes

$$z''(x) = 4z(x) \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 357: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned}O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0\end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = 4$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = e^{-2x}$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned}y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{6}{1} dx} \\ &= z_1 e^{-3x} \\ &= z_1 (e^{-3x})\end{aligned}$$

Which simplifies to

$$y_1 = e^{-5x}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{6}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{-6x}}{(y_1)^2} dx \\ &= y_1 \left(\frac{e^{4x}}{4} \right)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (e^{-5x}) + c_2 \left(e^{-5x} \left(\frac{e^{4x}}{4} \right) \right)\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 6y' + 5y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1 e^{-5x} + \frac{c_2 e^{-x}}{4}$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$2e^x + 10e^{5x}$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{e^x\}, \{e^{5x}\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\left\{ \frac{e^{-x}}{4}, e^{-5x} \right\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1 e^x + A_2 e^{5x}$$

The unknowns $\{A_1, A_2\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$12A_1e^x + 60A_2e^{5x} = 2e^x + 10e^{5x}$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = \frac{1}{6}, A_2 = \frac{1}{6} \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = \frac{e^x}{6} + \frac{e^{5x}}{6}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(c_1e^{-5x} + \frac{c_2e^{-x}}{4} \right) + \left(\frac{e^x}{6} + \frac{e^{5x}}{6} \right) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1e^{-5x} + \frac{c_2e^{-x}}{4} + \frac{e^x}{6} + \frac{e^{5x}}{6} \quad (1)$$

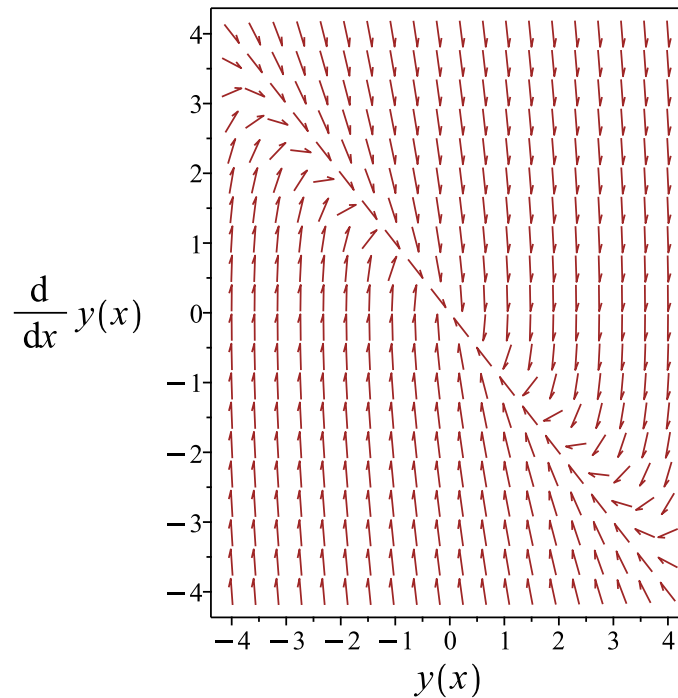


Figure 429: Slope field plot

Verification of solutions

$$y = c_1 e^{-5x} + \frac{c_2 e^{-x}}{4} + \frac{e^x}{6} + \frac{e^{5x}}{6}$$

Verified OK.

11.7.3 Maple step by step solution

Let's solve

$$y'' + 6y' + 5y = 2e^x + 10e^{5x}$$

- Highest derivative means the order of the ODE is 2
- $$y''$$
- Characteristic polynomial of homogeneous ODE
- $$r^2 + 6r + 5 = 0$$
- Factor the characteristic polynomial
- $$(r + 5)(r + 1) = 0$$
- Roots of the characteristic polynomial

$$r = (-5, -1)$$

- 1st solution of the homogeneous ODE

$$y_1(x) = e^{-5x}$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = e^{-x}$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = c_1 e^{-5x} + c_2 e^{-x} + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right) \right], f(x) = 2e^x + 10e^{5x}$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} e^{-5x} & e^{-x} \\ -5e^{-5x} & -e^{-x} \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = 4e^{-6x}$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = -\frac{e^{-5x} \left(\int e^{6x} (5e^{4x} + 1) dx \right)}{2} + \frac{e^{-x} \left(\int e^{2x} (5e^{4x} + 1) dx \right)}{2}$$

- Compute integrals

$$y_p(x) = \frac{e^x}{6} + \frac{e^{5x}}{6}$$

- Substitute particular solution into general solution to ODE

$$y = c_1 e^{-5x} + c_2 e^{-x} + \frac{e^x}{6} + \frac{e^{5x}}{6}$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]  
trying a double symmetry of the form [xi=0, eta=F(x)]  
-> Try solving first the homogeneous part of the ODE  
    checking if the LODE has constant coefficients  
    <- constant coefficients successful  
<- solving first the homogeneous part of the ODE successful`
```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 29

```
dsolve(diff(y(x),x$2)+6*diff(y(x),x)+5*y(x)=2*exp(x)+10*exp(5*x),y(x), singsol=all)
```

$$y(x) = \frac{(e^{10x} + e^{6x} + 6c_1e^{4x} + 6c_2)e^{-5x}}{6}$$

✓ Solution by Mathematica

Time used: 0.089 (sec). Leaf size: 36

```
DSolve[y''[x]+6*y'[x]+5*y[x]==2*Exp[x]+10*Exp[5*x],y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{1}{6}e^x(e^{4x} + 1) + c_1e^{-5x} + c_2e^{-x}$$

11.8 problem 8

11.8.1 Solving as second order linear constant coeff ode	2329
11.8.2 Solving using Kovacic algorithm	2332
11.8.3 Maple step by step solution	2337

Internal problem ID [11782]

Internal file name [OUTPUT/11791_Thursday_April_11_2024_08_49_42_PM_27254097/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 8.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' + 2y' + 10y = 5x e^{-2x}$$

11.8.1 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = 2, C = 10, f(x) = 5x e^{-2x}$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 2y' + 10y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 2, C = 10$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + 2\lambda e^{\lambda x} + 10 e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 2\lambda + 10 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 2, C = 10$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{-2}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{2^2 - (4)(1)(10)} \\ &= -1 \pm 3i \end{aligned}$$

Hence

$$\lambda_1 = -1 + 3i$$

$$\lambda_2 = -1 - 3i$$

Which simplifies to

$$\lambda_1 = -1 + 3i$$

$$\lambda_2 = -1 - 3i$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = -1$ and $\beta = 3$. Therefore the final solution, when using Euler relation, can be written as

$$y = e^{\alpha x} (c_1 \cos(\beta x) + c_2 \sin(\beta x))$$

Which becomes

$$y = e^{-x} (c_1 \cos(3x) + c_2 \sin(3x))$$

Therefore the homogeneous solution y_h is

$$y_h = e^{-x} (c_1 \cos(3x) + c_2 \sin(3x))$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$5x e^{-2x}$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{x e^{-2x}, e^{-2x}\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^{-x} \cos(3x), e^{-x} \sin(3x)\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1 x e^{-2x} + A_2 e^{-2x}$$

The unknowns $\{A_1, A_2\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$-2A_1 e^{-2x} + 10A_1 x e^{-2x} + 10A_2 e^{-2x} = 5x e^{-2x}$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = \frac{1}{2}, A_2 = \frac{1}{10} \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = \frac{x e^{-2x}}{2} + \frac{e^{-2x}}{10}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (e^{-x}(c_1 \cos(3x) + c_2 \sin(3x))) + \left(\frac{x e^{-2x}}{2} + \frac{e^{-2x}}{10} \right) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = e^{-x}(c_1 \cos(3x) + c_2 \sin(3x)) + \frac{x e^{-2x}}{2} + \frac{e^{-2x}}{10} \quad (1)$$

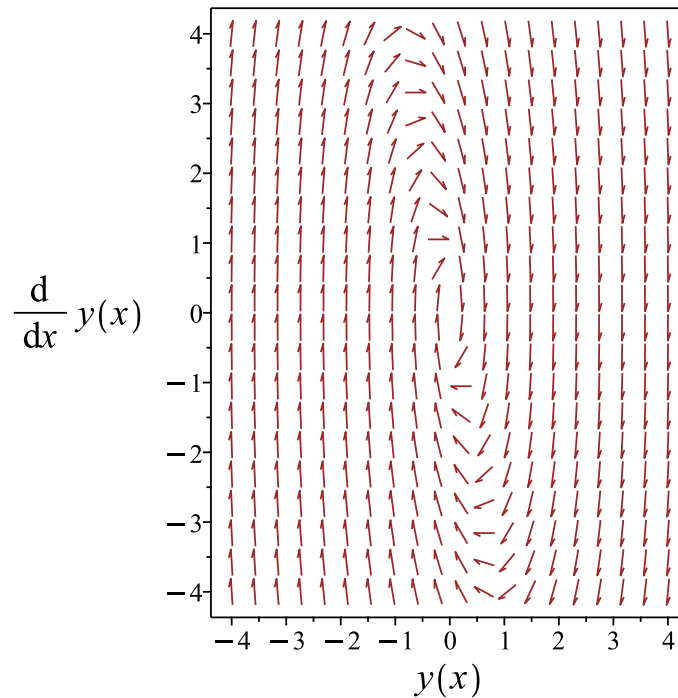


Figure 430: Slope field plot

Verification of solutions

$$y = e^{-x}(c_1 \cos(3x) + c_2 \sin(3x)) + \frac{x e^{-2x}}{2} + \frac{e^{-2x}}{10}$$

Verified OK.

11.8.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' + 2y' + 10y = 0 \tag{1}$$

$$Ay'' + By' + Cy = 0 \tag{2}$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= 2 \\ C &= 10 \end{aligned} \tag{3}$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-9}{1} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= -9 \\ t &= 1 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = -9z(x) \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 359: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = -9$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = \cos(3x)$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{2}{1} dx} \\ &= z_1 e^{-x} \\ &= z_1 (e^{-x}) \end{aligned}$$

Which simplifies to

$$y_1 = e^{-x} \cos(3x)$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{2}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{-2x}}{(y_1)^2} dx \\ &= y_1 \left(\frac{\tan(3x)}{3} \right) \end{aligned}$$

Therefore the solution is

$$y = c_1 y_1 + c_2 y_2$$

$$= c_1 (e^{-x} \cos(3x)) + c_2 \left(e^{-x} \cos(3x) \left(\frac{\tan(3x)}{3} \right) \right)$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 2y' + 10y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = e^{-x} \cos(3x) c_1 + \frac{e^{-x} \sin(3x) c_2}{3}$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$5x e^{-2x}$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{x e^{-2x}, e^{-2x}\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\left\{ e^{-x} \cos(3x), \frac{e^{-x} \sin(3x)}{3} \right\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1 x e^{-2x} + A_2 e^{-2x}$$

The unknowns $\{A_1, A_2\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$-2A_1e^{-2x} + 10A_1xe^{-2x} + 10A_2e^{-2x} = 5xe^{-2x}$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = \frac{1}{2}, A_2 = \frac{1}{10} \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = \frac{xe^{-2x}}{2} + \frac{e^{-2x}}{10}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(e^{-x} \cos(3x) c_1 + \frac{e^{-x} \sin(3x) c_2}{3} \right) + \left(\frac{xe^{-2x}}{2} + \frac{e^{-2x}}{10} \right) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = e^{-x} \cos(3x) c_1 + \frac{e^{-x} \sin(3x) c_2}{3} + \frac{xe^{-2x}}{2} + \frac{e^{-2x}}{10} \quad (1)$$

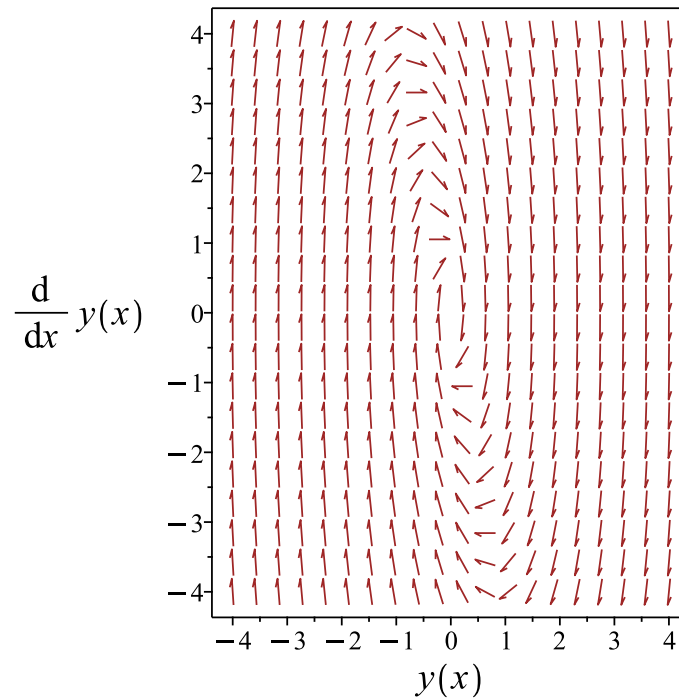


Figure 431: Slope field plot

Verification of solutions

$$y = e^{-x} \cos(3x) c_1 + \frac{e^{-x} \sin(3x) c_2}{3} + \frac{x e^{-2x}}{2} + \frac{e^{-2x}}{10}$$

Verified OK.

11.8.3 Maple step by step solution

Let's solve

$$y'' + 2y' + 10y = 5x e^{-2x}$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of homogeneous ODE

$$r^2 + 2r + 10 = 0$$

- Use quadratic formula to solve for r

$$r = \frac{(-2) \pm (\sqrt{-36})}{2}$$

- Roots of the characteristic polynomial

$$r = (-1 - 3I, -1 + 3I)$$

- 1st solution of the homogeneous ODE

$$y_1(x) = e^{-x} \cos(3x)$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = e^{-x} \sin(3x)$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = e^{-x} \cos(3x) c_1 + e^{-x} \sin(3x) c_2 + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = 5x e^{-2x} \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} e^{-x} \cos(3x) & e^{-x} \sin(3x) \\ -e^{-x} \cos(3x) - 3e^{-x} \sin(3x) & -e^{-x} \sin(3x) + 3e^{-x} \cos(3x) \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = 3e^{-2x}$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = -\frac{5e^{-x}(\cos(3x)(\int e^{-x} \sin(3x)xdx) - \sin(3x)(\int e^{-x} \cos(3x)xdx))}{3}$$

- Compute integrals

$$y_p(x) = \frac{(5x+1)e^{-2x}}{10}$$

- Substitute particular solution into general solution to ODE

$$y = e^{-x} \cos(3x) c_1 + e^{-x} \sin(3x) c_2 + \frac{(5x+1)e^{-2x}}{10}$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]  
trying a double symmetry of the form [xi=0, eta=F(x)]  
-> Try solving first the homogeneous part of the ODE  
    checking if the LODE has constant coefficients  
    <- constant coefficients successful  
<- solving first the homogeneous part of the ODE successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 37

```
dsolve(diff(y(x),x$2)+2*diff(y(x),x)+10*y(x)=5*x*exp(-2*x),y(x), singsol=all)
```

$$y(x) = \frac{(10c_1 \cos(3x) + 10c_2 \sin(3x)) e^{-x}}{10} + \frac{(5x + 1) e^{-2x}}{10}$$

✓ Solution by Mathematica

Time used: 0.026 (sec). Leaf size: 41

```
DSolve[y''[x]+2*y'[x]+10*y[x]==5*x*Exp[-2*x],y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{1}{10} e^{-2x} (5x + 10c_2 e^x \cos(3x) + 10c_1 e^x \sin(3x) + 1)$$

11.9 problem 9

11.9.1 Maple step by step solution 2342

Internal problem ID [11783]

Internal file name [OUTPUT/11792_Thursday_April_11_2024_08_49_42_PM_60476993/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 9.

ODE order: 3.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_3rd_order , _with_linear_symmetries]]
```

$$y''' + 4y'' + y' - 6y = -18x^2 + 1$$

This is higher order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE And y_p is a particular solution to the nonhomogeneous ODE. y_h is the solution to

$$y''' + 4y'' + y' - 6y = 0$$

The characteristic equation is

$$\lambda^3 + 4\lambda^2 + \lambda - 6 = 0$$

The roots of the above equation are

$$\lambda_1 = 1$$

$$\lambda_2 = -3$$

$$\lambda_3 = -2$$

Therefore the homogeneous solution is

$$y_h(x) = c_1 e^{-2x} + c_2 e^x + e^{-3x} c_3$$

The fundamental set of solutions for the homogeneous solution are the following

$$y_1 = e^{-2x}$$

$$y_2 = e^x$$

$$y_3 = e^{-3x}$$

Now the particular solution to the given ODE is found

$$y''' + 4y'' + y' - 6y = -18x^2 + 1$$

The particular solution is found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$x^2 + 1$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{1, x, x^2\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^x, e^{-3x}, e^{-2x}\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_3 x^2 + A_2 x + A_1$$

The unknowns $\{A_1, A_2, A_3\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$-6A_3 x^2 - 6A_2 x + 2xA_3 - 6A_1 + A_2 + 8A_3 = -18x^2 + 1$$

Solving for the unknowns by comparing coefficients results in

$$[A_1 = 4, A_2 = 1, A_3 = 3]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = 3x^2 + x + 4$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1e^{-2x} + c_2e^x + e^{-3x}c_3) + (3x^2 + x + 4) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1e^{-2x} + c_2e^x + e^{-3x}c_3 + 3x^2 + x + 4 \quad (1)$$

Verification of solutions

$$y = c_1e^{-2x} + c_2e^x + e^{-3x}c_3 + 3x^2 + x + 4$$

Verified OK.

11.9.1 Maple step by step solution

Let's solve

$$y''' + 4y'' + y' - 6y = -18x^2 + 1$$

- Highest derivative means the order of the ODE is 3

$$y'''$$

- Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(x)$

$$y_1(x) = y$$

- Define new variable $y_2(x)$

$$y_2(x) = y'$$

- Define new variable $y_3(x)$

$$y_3(x) = y''$$

- Isolate for $y_3'(x)$ using original ODE

$$y_3'(x) = -18x^2 - 4y_3(x) - y_2(x) + 6y_1(x) + 1$$

Convert linear ODE into a system of first order ODEs

$$[y_2(x) = y_1'(x), y_3(x) = y_2'(x), y_3'(x) = -18x^2 - 4y_3(x) - y_2(x) + 6y_1(x) + 1]$$

- Define vector

$$\vec{y}(x) = \begin{bmatrix} y_1(x) \\ y_2(x) \\ y_3(x) \end{bmatrix}$$

- System to solve

$$\vec{y}'(x) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 6 & -1 & -4 \end{bmatrix} \cdot \vec{y}(x) + \begin{bmatrix} 0 \\ 0 \\ -18x^2 + 1 \end{bmatrix}$$

- Define the forcing function

$$\vec{f}(x) = \begin{bmatrix} 0 \\ 0 \\ -18x^2 + 1 \end{bmatrix}$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 6 & -1 & -4 \end{bmatrix}$$

- Rewrite the system as

$$\vec{y}'(x) = A \cdot \vec{y}(x) + \vec{f}$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[-3, \begin{bmatrix} \frac{1}{9} \\ -\frac{1}{3} \\ 1 \end{bmatrix} \right], \left[-2, \begin{bmatrix} \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix} \right], \left[1, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[-3, \begin{bmatrix} \frac{1}{9} \\ -\frac{1}{3} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_1 = e^{-3x} \cdot \begin{bmatrix} \frac{1}{9} \\ -\frac{1}{3} \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[-2, \begin{bmatrix} \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_2 = e^{-2x} \cdot \begin{bmatrix} \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[1, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_3 = e^x \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

- General solution of the system of ODEs can be written in terms of the particular solution $\vec{y}_p(x)$

$$\vec{y}(x) = c_1 \vec{y}_1 + c_2 \vec{y}_2 + c_3 \vec{y}_3 + \vec{y}_p(x)$$

- Fundamental matrix

- Let $\phi(x)$ be the matrix whose columns are the independent solutions of the homogeneous system

$$\phi(x) = \begin{bmatrix} \frac{e^{-3x}}{9} & \frac{e^{-2x}}{4} & e^x \\ -\frac{e^{-3x}}{3} & -\frac{e^{-2x}}{2} & e^x \\ e^{-3x} & e^{-2x} & e^x \end{bmatrix}$$

- The fundamental matrix, $\Phi(x)$ is a normalized version of $\phi(x)$ satisfying $\Phi(0) = I$ where I is the identity matrix

$$\Phi(x) = \phi(x) \cdot \frac{1}{\phi(0)}$$

- Substitute the value of $\phi(x)$ and $\phi(0)$

$$\Phi(x) = \begin{bmatrix} \frac{e^{-3x}}{9} & \frac{e^{-2x}}{4} & e^x \\ -\frac{e^{-3x}}{3} & -\frac{e^{-2x}}{2} & e^x \\ e^{-3x} & e^{-2x} & e^x \end{bmatrix} \cdot \frac{1}{\begin{bmatrix} \frac{1}{9} & \frac{1}{4} & 1 \\ -\frac{1}{3} & -\frac{1}{2} & 1 \\ 1 & 1 & 1 \end{bmatrix}}$$

- Evaluate and simplify to get the fundamental matrix

$$\Phi(x) = \begin{bmatrix} \frac{(e^{4x} + 2e^x - 1)e^{-3x}}{2} & -\frac{(-5e^{4x} + 8e^x - 3)e^{-3x}}{12} & \frac{(e^{4x} - 4e^x + 3)e^{-3x}}{12} \\ \frac{(e^{4x} - 4e^x + 3)e^{-3x}}{2} & \frac{(5e^{4x} + 16e^x - 9)e^{-3x}}{12} & \frac{(e^{4x} + 8e^x - 9)e^{-3x}}{12} \\ \frac{(e^{4x} + 8e^x - 9)e^{-3x}}{2} & -\frac{(-5e^{4x} + 32e^x - 27)e^{-3x}}{12} & \frac{(e^{4x} - 16e^x + 27)e^{-3x}}{12} \end{bmatrix}$$

□

Find a particular solution of the system of ODEs using variation of parameters

- Let the particular solution be the fundamental matrix multiplied by $\vec{v}(x)$ and solve for $\vec{v}(x)$

$$\vec{y}_p(x) = \Phi(x) \cdot \vec{v}(x)$$

- Take the derivative of the particular solution

$$\vec{y}_p'(x) = \Phi'(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x)$$

- Substitute particular solution and its derivative into the system of ODEs

$$\Phi'(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x) = A \cdot \Phi(x) \cdot \vec{v}(x) + \vec{f}(x)$$

- The fundamental matrix has columns that are solutions to the homogeneous system so its derivative is $A \cdot \Phi(x)$

$$A \cdot \Phi(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x) = A \cdot \Phi(x) \cdot \vec{v}(x) + \vec{f}(x)$$

- Cancel like terms

$$\Phi(x) \cdot \vec{v}'(x) = \vec{f}(x)$$

- Multiply by the inverse of the fundamental matrix

$$\vec{v}'(x) = \frac{1}{\Phi(x)} \cdot \vec{f}(x)$$

- Integrate to solve for $\vec{v}(x)$

$$\vec{v}(x) = \int_0^x \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds$$

- Plug $\vec{v}(x)$ into the equation for the particular solution

$$\vec{y}_p(x) = \Phi(x) \cdot \left(\int_0^x \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds \right)$$

- o Plug in the fundamental matrix and the forcing function and compute

$$\vec{y}_p(x) = \begin{bmatrix} e^{-3x} \left((3x^2 + x + 4) e^{3x} - \frac{4e^x}{3} - \frac{35e^{4x}}{12} + \frac{1}{4} \right) \\ \frac{(-35e^{4x} + 72xe^{3x} + 12e^{3x} + 32e^x - 9)e^{-3x}}{12} \\ \frac{(-35e^{4x} + 72e^{3x} - 64e^x + 27)e^{-3x}}{12} \end{bmatrix}$$

- Plug particular solution back into general solution

$$\vec{y}(x) = c_1 \vec{y}_1 + c_2 \vec{y}_2 + c_3 \vec{y}_3 + \begin{bmatrix} e^{-3x} \left((3x^2 + x + 4) e^{3x} - \frac{4e^x}{3} - \frac{35e^{4x}}{12} + \frac{1}{4} \right) \\ \frac{(-35e^{4x} + 72xe^{3x} + 12e^{3x} + 32e^x - 9)e^{-3x}}{12} \\ \frac{(-35e^{4x} + 72e^{3x} - 64e^x + 27)e^{-3x}}{12} \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y = e^{-3x} \left((3x^2 + x + 4) e^{3x} + \frac{c_2 e^x}{4} + e^{4x} c_3 + \frac{c_1}{9} - \frac{4e^x}{3} - \frac{35e^{4x}}{12} + \frac{1}{4} \right)$$

Maple trace

```

`Methods for third order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 3; linear nonhomogeneous with symmetry [0,1]
trying high order linear exact nonhomogeneous
trying differential order: 3; missing the dependent variable
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 34

```
dsolve(diff(y(x),x$3)+4*diff(y(x),x$2)+diff(y(x),x)-6*y(x)=-18*x^2+1,y(x), singsol=all)
```

$$y(x) = e^{-3x} \left((3x^2 + x + 4) e^{3x} + c_1 e^{4x} + c_3 e^x + c_2 \right)$$

✓ Solution by Mathematica

Time used: 0.004 (sec). Leaf size: 35

```
DSolve[y'''[x]+4*y''[x]+y'[x]-6*y[x]==-18*x^2+1,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow 3x^2 + x + c_1e^{-3x} + c_2e^{-2x} + c_3e^x + 4$$

11.10 problem 10

11.10.1 Maple step by step solution 2350

Internal problem ID [11784]

Internal file name [OUTPUT/11793_Thursday_April_11_2024_08_49_43_PM_4198183/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 10.

ODE order: 3.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_3rd_order , _linear , _nonhomogeneous]]
```

$$y''' + 2y'' - 3y' - 10y = 8x e^{-2x}$$

This is higher order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE And y_p is a particular solution to the nonhomogeneous ODE. y_h is the solution to

$$y''' + 2y'' - 3y' - 10y = 0$$

The characteristic equation is

$$\lambda^3 + 2\lambda^2 - 3\lambda - 10 = 0$$

The roots of the above equation are

$$\lambda_1 = 2$$

$$\lambda_2 = -2 - i$$

$$\lambda_3 = -2 + i$$

Therefore the homogeneous solution is

$$y_h(x) = c_1 e^{2x} + e^{(-2-i)x} c_2 + e^{(-2+i)x} c_3$$

The fundamental set of solutions for the homogeneous solution are the following

$$y_1 = e^{2x}$$

$$y_2 = e^{(-2-i)x}$$

$$y_3 = e^{(-2+i)x}$$

Now the particular solution to the given ODE is found

$$y''' + 2y'' - 3y' - 10y = 8x e^{-2x}$$

The particular solution is found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$8x e^{-2x}$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{x e^{-2x}, e^{-2x}\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^{(-2-i)x}, e^{(-2+i)x}, e^{2x}\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1 x e^{-2x} + A_2 e^{-2x}$$

The unknowns $\{A_1, A_2\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$A_1 e^{-2x} - 4A_1 x e^{-2x} - 4A_2 e^{-2x} = 8x e^{-2x}$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = -2, A_2 = -\frac{1}{2} \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = -2x e^{-2x} - \frac{e^{-2x}}{2}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 e^{2x} + e^{(-2-i)x} c_2 + e^{(-2+i)x} c_3) + \left(-2x e^{-2x} - \frac{e^{-2x}}{2} \right) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 e^{2x} + e^{(-2-i)x} c_2 + e^{(-2+i)x} c_3 - 2x e^{-2x} - \frac{e^{-2x}}{2} \quad (1)$$

Verification of solutions

$$y = c_1 e^{2x} + e^{(-2-i)x} c_2 + e^{(-2+i)x} c_3 - 2x e^{-2x} - \frac{e^{-2x}}{2}$$

Verified OK.

11.10.1 Maple step by step solution

Let's solve

$$y''' + 2y'' - 3y' - 10y = 8x e^{-2x}$$

- Highest derivative means the order of the ODE is 3

$$y'''$$

- Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(x)$

$$y_1(x) = y$$

- Define new variable $y_2(x)$

$$y_2(x) = y'$$

- Define new variable $y_3(x)$

$$y_3(x) = y''$$

- Isolate for $y_3'(x)$ using original ODE

$$y_3'(x) = 8x e^{-2x} - 2y_3(x) + 3y_2(x) + 10y_1(x)$$

Convert linear ODE into a system of first order ODEs

$$[y_2(x) = y_1'(x), y_3(x) = y_2'(x), y_3'(x) = 8x e^{-2x} - 2y_3(x) + 3y_2(x) + 10y_1(x)]$$

- Define vector

$$\vec{y}(x) = \begin{bmatrix} y_1(x) \\ y_2(x) \\ y_3(x) \end{bmatrix}$$

- System to solve

$$\vec{y}'(x) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 10 & 3 & -2 \end{bmatrix} \cdot \vec{y}(x) + \begin{bmatrix} 0 \\ 0 \\ 8x e^{-2x} \end{bmatrix}$$

- Define the forcing function

$$\vec{f}(x) = \begin{bmatrix} 0 \\ 0 \\ 8x e^{-2x} \end{bmatrix}$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 10 & 3 & -2 \end{bmatrix}$$

- Rewrite the system as

$$\vec{y}'(x) = A \cdot \vec{y}(x) + \vec{f}$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[\begin{bmatrix} 2 \\ 2 \end{bmatrix}, \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right], \left[-2 - \text{I}, \begin{bmatrix} \frac{3}{25} - \frac{4\text{I}}{25} \\ -\frac{2}{5} + \frac{\text{I}}{5} \\ 1 \end{bmatrix} \right], \left[-2 + \text{I}, \begin{bmatrix} \frac{3}{25} + \frac{4\text{I}}{25} \\ -\frac{2}{5} - \frac{\text{I}}{5} \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[2, \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_1 = e^{2x} \cdot \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix}$$

- Consider complex eigenpair, complex conjugate eigenvalue can be ignored

$$\left[-2 - I, \begin{bmatrix} \frac{3}{25} - \frac{4I}{25} \\ -\frac{2}{5} + \frac{I}{5} \\ 1 \end{bmatrix} \right]$$

- Solution from eigenpair

$$e^{(-2-I)x} \cdot \begin{bmatrix} \frac{3}{25} - \frac{4I}{25} \\ -\frac{2}{5} + \frac{I}{5} \\ 1 \end{bmatrix}$$

- Use Euler identity to write solution in terms of sin and cos

$$e^{-2x} \cdot (\cos(x) - I \sin(x)) \cdot \begin{bmatrix} \frac{3}{25} - \frac{4I}{25} \\ -\frac{2}{5} + \frac{I}{5} \\ 1 \end{bmatrix}$$

- Simplify expression

$$e^{-2x} \cdot \begin{bmatrix} \left(\frac{3}{25} - \frac{4I}{25} \right) (\cos(x) - I \sin(x)) \\ \left(-\frac{2}{5} + \frac{I}{5} \right) (\cos(x) - I \sin(x)) \\ \cos(x) - I \sin(x) \end{bmatrix}$$

- Both real and imaginary parts are solutions to the homogeneous system

$$\left[\vec{y}_2(x) = e^{-2x} \cdot \begin{bmatrix} \frac{3 \cos(x)}{25} - \frac{4 \sin(x)}{25} \\ -\frac{2 \cos(x)}{5} + \frac{\sin(x)}{5} \\ \cos(x) \end{bmatrix}, \vec{y}_3(x) = e^{-2x} \cdot \begin{bmatrix} -\frac{3 \sin(x)}{25} - \frac{4 \cos(x)}{25} \\ \frac{2 \sin(x)}{5} + \frac{\cos(x)}{5} \\ -\sin(x) \end{bmatrix} \right]$$

- General solution of the system of ODEs can be written in terms of the particular solution $\vec{y}_p(x)$

$$\vec{y}(x) = c_1 \vec{y}_1 + c_2 \vec{y}_2(x) + c_3 \vec{y}_3(x) + \vec{y}_p(x)$$

□ Fundamental matrix

- Let $\phi(x)$ be the matrix whose columns are the independent solutions of the homogeneous system

$$\phi(x) = \begin{bmatrix} \frac{e^{2x}}{4} & e^{-2x} \left(\frac{3 \cos(x)}{25} - \frac{4 \sin(x)}{25} \right) & e^{-2x} \left(-\frac{3 \sin(x)}{25} - \frac{4 \cos(x)}{25} \right) \\ \frac{e^{2x}}{2} & e^{-2x} \left(-\frac{2 \cos(x)}{5} + \frac{\sin(x)}{5} \right) & e^{-2x} \left(\frac{2 \sin(x)}{5} + \frac{\cos(x)}{5} \right) \\ e^{2x} & \cos(x) e^{-2x} & -e^{-2x} \sin(x) \end{bmatrix}$$

- The fundamental matrix, $\Phi(x)$ is a normalized version of $\phi(x)$ satisfying $\Phi(0) = I$ where I is the identity matrix

$$\Phi(x) = \phi(x) \cdot \frac{1}{\phi(0)}$$

- Substitute the value of $\phi(x)$ and $\phi(0)$

$$\Phi(x) = \begin{bmatrix} \frac{e^{2x}}{4} & e^{-2x} \left(\frac{3 \cos(x)}{25} - \frac{4 \sin(x)}{25} \right) & e^{-2x} \left(-\frac{3 \sin(x)}{25} - \frac{4 \cos(x)}{25} \right) \\ \frac{e^{2x}}{2} & e^{-2x} \left(-\frac{2 \cos(x)}{5} + \frac{\sin(x)}{5} \right) & e^{-2x} \left(\frac{2 \sin(x)}{5} + \frac{\cos(x)}{5} \right) \\ e^{2x} & \cos(x) e^{-2x} & -e^{-2x} \sin(x) \end{bmatrix} \cdot \frac{1}{\begin{bmatrix} \frac{1}{4} & \frac{3}{25} & -\frac{4}{25} \\ \frac{1}{2} & -\frac{2}{5} & \frac{1}{5} \\ 1 & 1 & 0 \end{bmatrix}}$$

- Evaluate and simplify to get the fundamental matrix

$$\Phi(x) = \begin{bmatrix} \frac{2(6 \cos(x) + 7 \sin(x))e^{-2x}}{17} + \frac{5e^{2x}}{17} & \frac{(-4 \cos(x) + \sin(x))e^{-2x}}{17} + \frac{4e^{2x}}{17} & \frac{(-\cos(x) - 4 \sin(x))e^{-2x}}{17} + \frac{e^{2x}}{17} \\ \frac{10(-\cos(x) - 4 \sin(x))e^{-2x}}{17} + \frac{10e^{2x}}{17} & \frac{(9 \cos(x) + 2 \sin(x))e^{-2x}}{17} + \frac{8e^{2x}}{17} & \frac{(-2 \cos(x) + 9 \sin(x))e^{-2x}}{17} + \frac{2e^{2x}}{17} \\ \frac{10(-2 \cos(x) + 9 \sin(x))e^{-2x}}{17} + \frac{20e^{2x}}{17} & \frac{(-16 \cos(x) - 13 \sin(x))e^{-2x}}{17} + \frac{16e^{2x}}{17} & \frac{(13 \cos(x) - 16 \sin(x))e^{-2x}}{17} + \frac{4e^{2x}}{17} \end{bmatrix}$$

□ Find a particular solution of the system of ODEs using variation of parameters

- Let the particular solution be the fundamental matrix multiplied by $\vec{v}(x)$ and solve for $\vec{v}(x)$

$$\vec{y}_p(x) = \Phi(x) \cdot \vec{v}(x)$$

- Take the derivative of the particular solution

$$\vec{y}_p'(x) = \Phi'(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x)$$

- Substitute particular solution and its derivative into the system of ODEs

$$\Phi'(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x) = A \cdot \Phi(x) \cdot \vec{v}(x) + \vec{f}(x)$$

- The fundamental matrix has columns that are solutions to the homogeneous system so its derivative

$$A \cdot \Phi(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x) = A \cdot \Phi(x) \cdot \vec{v}(x) + \vec{f}(x)$$

- Cancel like terms

$$\Phi(x) \cdot \vec{v}'(x) = \vec{f}(x)$$

- Multiply by the inverse of the fundamental matrix

$$\vec{v}'(x) = \frac{1}{\Phi(x)} \cdot \vec{f}(x)$$

- Integrate to solve for $\vec{v}(x)$

$$\vec{v}(x) = \int_0^x \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds$$

- Plug $\vec{v}(x)$ into the equation for the particular solution

$$\vec{y}_p(x) = \Phi(x) \cdot \left(\int_0^x \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds \right)$$

- Plug in the fundamental matrix and the forcing function and compute

$$\vec{y}_p(x) = \begin{bmatrix} \frac{e^{-2x}(e^{4x}+16\cos(x)+64\sin(x)-68x-17)}{34} \\ \frac{e^{-2x}(e^{4x}+16\cos(x)-72\sin(x)+68x-17)}{17} \\ \frac{2e^{-2x}(e^{4x}-52\cos(x)+64\sin(x)-68x+51)}{17} \end{bmatrix}$$

- Plug particular solution back into general solution

$$\vec{y}(x) = c_1 \vec{y}_1 + c_2 \vec{y}_2(x) + c_3 \vec{y}_3(x) + \begin{bmatrix} \frac{e^{-2x}(e^{4x}+16\cos(x)+64\sin(x)-68x-17)}{34} \\ \frac{e^{-2x}(e^{4x}+16\cos(x)-72\sin(x)+68x-17)}{17} \\ \frac{2e^{-2x}(e^{4x}-52\cos(x)+64\sin(x)-68x+51)}{17} \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y = \frac{((204c_2 - 272c_3 + 800)\cos(x) + (-272c_2 - 204c_3 + 3200)\sin(x) - 3400x - 850)e^{-2x}}{1700} + \frac{(425c_1 + 50)e^{2x}}{1700}$$

Maple trace

```
`Methods for third order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
trying differential order: 3; linear nonhomogeneous with symmetry [0,1]  
trying high order linear exact nonhomogeneous  
trying differential order: 3; missing the dependent variable  
checking if the LODE has constant coefficients  
<- constant coefficients successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 32

```
dsolve(diff(y(x),x$3)+2*diff(y(x),x$2)-3*diff(y(x),x)-10*y(x)=8*x*exp(-2*x),y(x), singsol=all
```

$$y(x) = \frac{(2c_2 \cos(x) + 2c_3 \sin(x) - 4x - 1) e^{-2x}}{2} + e^{2x} c_1$$

✓ Solution by Mathematica

Time used: 0.007 (sec). Leaf size: 40

```
DSolve[y'''[x]+2*y''[x]-3*y'[x]-10*y[x]==8*x*Exp[-2*x],y[x],x,IncludeSingularSolutions -> Tr
```

$$y(x) \rightarrow \frac{1}{2} e^{-2x} (-4x + 2c_3 e^{4x} + 2c_2 \cos(x) + 2c_1 \sin(x) - 1)$$

11.11 problem 11

11.11.1 Maple step by step solution 2358

Internal problem ID [11785]

Internal file name [OUTPUT/11794_Thursday_April_11_2024_08_49_43_PM_74629381/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 11.

ODE order: 3.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_3rd_order , _linear , _nonhomogeneous]]
```

$$y''' + y'' + 3y' - 5y = 5 \sin(2x) + 10x^2 + 3x + 7$$

This is higher order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE And y_p is a particular solution to the nonhomogeneous ODE. y_h is the solution to

$$y''' + y'' + 3y' - 5y = 0$$

The characteristic equation is

$$\lambda^3 + \lambda^2 + 3\lambda - 5 = 0$$

The roots of the above equation are

$$\lambda_1 = 1$$

$$\lambda_2 = -1 - 2i$$

$$\lambda_3 = -1 + 2i$$

Therefore the homogeneous solution is

$$y_h(x) = e^x c_1 + e^{(-1-2i)x} c_2 + e^{(-1+2i)x} c_3$$

The fundamental set of solutions for the homogeneous solution are the following

$$\begin{aligned}y_1 &= e^x \\y_2 &= e^{(-1-2i)x} \\y_3 &= e^{(-1+2i)x}\end{aligned}$$

Now the particular solution to the given ODE is found

$$y''' + y'' + 3y' - 5y = 5 \sin(2x) + 10x^2 + 3x + 7$$

The particular solution is found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$5 \sin(2x) + 10x^2 + 3x + 7$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{\cos(2x), \sin(2x)\}, \{1, x, x^2\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^x, e^{(-1-2i)x}, e^{(-1+2i)x}\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1 \cos(2x) + A_2 \sin(2x) + A_3 + A_4 x + A_5 x^2$$

The unknowns $\{A_1, A_2, A_3, A_4, A_5\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$\begin{aligned}2A_1 \sin(2x) - 2A_2 \cos(2x) - 9A_1 \cos(2x) - 9A_2 \sin(2x) + 2A_5 \\+ 3A_4 + 6A_5 x - 5A_3 - 5A_4 x - 5A_5 x^2 = 5 \sin(2x) + 10x^2 + 3x + 7\end{aligned}$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = \frac{2}{17}, A_2 = -\frac{9}{17}, A_3 = -4, A_4 = -3, A_5 = -2 \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = \frac{2 \cos(2x)}{17} - \frac{9 \sin(2x)}{17} - 4 - 3x - 2x^2$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (e^x c_1 + e^{(-1-2i)x} c_2 + e^{(-1+2i)x} c_3) + \left(\frac{2 \cos(2x)}{17} - \frac{9 \sin(2x)}{17} - 4 - 3x - 2x^2 \right) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = e^x c_1 + e^{(-1-2i)x} c_2 + e^{(-1+2i)x} c_3 + \frac{2 \cos(2x)}{17} - \frac{9 \sin(2x)}{17} - 4 - 3x - 2x^2 \quad (1)$$

Verification of solutions

$$y = e^x c_1 + e^{(-1-2i)x} c_2 + e^{(-1+2i)x} c_3 + \frac{2 \cos(2x)}{17} - \frac{9 \sin(2x)}{17} - 4 - 3x - 2x^2$$

Verified OK.

11.11.1 Maple step by step solution

Let's solve

$$y''' + y'' + 3y' - 5y = 5 \sin(2x) + 10x^2 + 3x + 7$$

- Highest derivative means the order of the ODE is 3

$$y'''$$

- Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(x)$

$$y_1(x) = y$$

- Define new variable $y_2(x)$

$$y_2(x) = y'$$

- Define new variable $y_3(x)$

$$y_3(x) = y''$$

- Isolate for $y_3'(x)$ using original ODE

$$y_3'(x) = 10x^2 - y_3(x) - 3y_2(x) + 5y_1(x) + 5 \sin(2x) + 3x + 7$$

Convert linear ODE into a system of first order ODEs

$$[y_2(x) = y_1'(x), y_3(x) = y_2'(x), y_3'(x) = 10x^2 - y_3(x) - 3y_2(x) + 5y_1(x) + 5 \sin(2x) + 3x + 7]$$

- Define vector

$$\vec{y}(x) = \begin{bmatrix} y_1(x) \\ y_2(x) \\ y_3(x) \end{bmatrix}$$

- System to solve

$$\vec{y}'(x) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 5 & -3 & -1 \end{bmatrix} \cdot \vec{y}(x) + \begin{bmatrix} 0 \\ 0 \\ 5 \sin(2x) + 10x^2 + 3x + 7 \end{bmatrix}$$

- Define the forcing function

$$\vec{f}(x) = \begin{bmatrix} 0 \\ 0 \\ 5 \sin(2x) + 10x^2 + 3x + 7 \end{bmatrix}$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 5 & -3 & -1 \end{bmatrix}$$

- Rewrite the system as

$$\vec{y}'(x) = A \cdot \vec{y}(x) + \vec{f}$$

- To solve the system, find the eigenvalues and eigenvectors of A
- Eigenpairs of A

$$\left[\left[\begin{array}{c} 1 \\ 1 \\ 1 \end{array} \right], \left[-1 - 2I, \begin{array}{c} -\frac{3}{25} - \frac{4I}{25} \\ -\frac{1}{5} + \frac{2I}{5} \\ 1 \end{array} \right], \left[-1 + 2I, \begin{array}{c} -\frac{3}{25} + \frac{4I}{25} \\ -\frac{1}{5} - \frac{2I}{5} \\ 1 \end{array} \right] \right]$$

- Consider eigenpair

$$\left[1, \begin{array}{c} 1 \\ 1 \\ 1 \end{array} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_1 = e^x \cdot \begin{array}{c} 1 \\ 1 \\ 1 \end{array}$$

- Consider complex eigenpair, complex conjugate eigenvalue can be ignored

$$\left[-1 - 2I, \begin{array}{c} -\frac{3}{25} - \frac{4I}{25} \\ -\frac{1}{5} + \frac{2I}{5} \\ 1 \end{array} \right]$$

- Solution from eigenpair

$$e^{(-1-2I)x} \cdot \begin{array}{c} -\frac{3}{25} - \frac{4I}{25} \\ -\frac{1}{5} + \frac{2I}{5} \\ 1 \end{array}$$

- Use Euler identity to write solution in terms of sin and cos

$$e^{-x} \cdot (\cos(2x) - I \sin(2x)) \cdot \begin{array}{c} -\frac{3}{25} - \frac{4I}{25} \\ -\frac{1}{5} + \frac{2I}{5} \\ 1 \end{array}$$

- Simplify expression

$$e^{-x} \cdot \begin{array}{c} \left(-\frac{3}{25} - \frac{4I}{25} \right) (\cos(2x) - I \sin(2x)) \\ \left(-\frac{1}{5} + \frac{2I}{5} \right) (\cos(2x) - I \sin(2x)) \\ \cos(2x) - I \sin(2x) \end{array}$$

- Both real and imaginary parts are solutions to the homogeneous system

$$\vec{y}_2(x) = e^{-x} \cdot \begin{bmatrix} -\frac{3 \cos(2x)}{25} - \frac{4 \sin(2x)}{25} \\ -\frac{\cos(2x)}{5} + \frac{2 \sin(2x)}{5} \\ \cos(2x) \end{bmatrix}, \vec{y}_3(x) = e^{-x} \cdot \begin{bmatrix} \frac{3 \sin(2x)}{25} - \frac{4 \cos(2x)}{25} \\ \frac{\sin(2x)}{5} + \frac{2 \cos(2x)}{5} \\ -\sin(2x) \end{bmatrix}$$

- General solution of the system of ODEs can be written in terms of the particular solution $\vec{y}_p(x)$

$$\vec{y}(x) = c_1 \vec{y}_1 + c_2 \vec{y}_2(x) + c_3 \vec{y}_3(x) + \vec{y}_p(x)$$

- Fundamental matrix

- o Let $\phi(x)$ be the matrix whose columns are the independent solutions of the homogeneous system

$$\phi(x) = \begin{bmatrix} e^x & e^{-x} \left(-\frac{3 \cos(2x)}{25} - \frac{4 \sin(2x)}{25} \right) & e^{-x} \left(\frac{3 \sin(2x)}{25} - \frac{4 \cos(2x)}{25} \right) \\ e^x & e^{-x} \left(-\frac{\cos(2x)}{5} + \frac{2 \sin(2x)}{5} \right) & e^{-x} \left(\frac{\sin(2x)}{5} + \frac{2 \cos(2x)}{5} \right) \\ e^x & e^{-x} \cos(2x) & -e^{-x} \sin(2x) \end{bmatrix}$$

- o The fundamental matrix, $\Phi(x)$ is a normalized version of $\phi(x)$ satisfying $\Phi(0) = I$ where I is the identity matrix

$$\Phi(x) = \phi(x) \cdot \frac{1}{\phi(0)}$$

- o Substitute the value of $\phi(x)$ and $\phi(0)$

$$\Phi(x) = \begin{bmatrix} e^x & e^{-x} \left(-\frac{3 \cos(2x)}{25} - \frac{4 \sin(2x)}{25} \right) & e^{-x} \left(\frac{3 \sin(2x)}{25} - \frac{4 \cos(2x)}{25} \right) \\ e^x & e^{-x} \left(-\frac{\cos(2x)}{5} + \frac{2 \sin(2x)}{5} \right) & e^{-x} \left(\frac{\sin(2x)}{5} + \frac{2 \cos(2x)}{5} \right) \\ e^x & e^{-x} \cos(2x) & -e^{-x} \sin(2x) \end{bmatrix} \cdot \frac{1}{\begin{bmatrix} 1 & -\frac{3}{25} & -\frac{4}{25} \\ 1 & -\frac{1}{5} & \frac{2}{5} \\ 1 & 1 & 0 \end{bmatrix}}$$

- o Evaluate and simplify to get the fundamental matrix

$$\Phi(x) = \begin{bmatrix} \frac{(-\sin(2x) + 3 \cos(2x))e^{-x}}{8} + \frac{5e^x}{8} & \frac{(\sin(2x) - \cos(2x))e^{-x}}{4} + \frac{e^x}{4} & \frac{(-\sin(2x) - \cos(2x))e^{-x}}{8} + \frac{e^x}{8} \\ \frac{(-5 \sin(2x) - 5 \cos(2x))e^{-x}}{8} + \frac{5e^x}{8} & \frac{(\sin(2x) + 3 \cos(2x))e^{-x}}{4} + \frac{e^x}{4} & \frac{(3 \sin(2x) - \cos(2x))e^{-x}}{8} + \frac{e^x}{8} \\ \frac{5(3 \sin(2x) - \cos(2x))e^{-x}}{8} + \frac{5e^x}{8} & \frac{(-\cos(2x) - 7 \sin(2x))e^{-x}}{4} + \frac{e^x}{4} & \frac{(7 \cos(2x) - \sin(2x))e^{-x}}{8} + \frac{e^x}{8} \end{bmatrix}$$

- Find a particular solution of the system of ODEs using variation of parameters

- o Let the particular solution be the fundamental matrix multiplied by $\vec{v}(x)$ and solve for $\vec{v}(x)$

$$\vec{y}_p(x) = \Phi(x) \cdot \vec{v}(x)$$

- o Take the derivative of the particular solution

$$\vec{y}'_p(x) = \Phi'(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x)$$

- Substitute particular solution and its derivative into the system of ODEs

$$\Phi'(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x) = A \cdot \Phi(x) \cdot \vec{v}(x) + \vec{f}(x)$$

- The fundamental matrix has columns that are solutions to the homogeneous system so its derivative is

$$A \cdot \Phi(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x) = A \cdot \Phi(x) \cdot \vec{v}(x) + \vec{f}(x)$$

- Cancel like terms

$$\Phi(x) \cdot \vec{v}'(x) = \vec{f}(x)$$

- Multiply by the inverse of the fundamental matrix

$$\vec{v}'(x) = \frac{1}{\Phi(x)} \cdot \vec{f}(x)$$

- Integrate to solve for $\vec{v}(x)$

$$\vec{v}(x) = \int_0^x \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds$$

- Plug $\vec{v}(x)$ into the equation for the particular solution

$$\vec{y}_p(x) = \Phi(x) \cdot \left(\int_0^x \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds \right)$$

- Plug in the fundamental matrix and the forcing function and compute

$$\vec{y}_p(x) = \begin{bmatrix} \frac{(-4e^{-x}+4)\cos(2x)}{34} - 2x^2 - \frac{e^{-x}\sin(2x)}{34} - 3x + 4e^x - \frac{9\sin(2x)}{17} - 4 \\ \frac{(2e^{-x}-36)\cos(2x)}{34} + \frac{9e^{-x}\sin(2x)}{34} - 4x + 4e^x - \frac{4\sin(2x)}{17} - 3 \\ -4 + \frac{8(-1+e^{-x})\cos(2x)}{17} - \frac{13e^{-x}\sin(2x)}{34} + 4e^x + \frac{36\sin(2x)}{17} \end{bmatrix}$$

- Plug particular solution back into general solution

$$\vec{y}(x) = c_1 \vec{y}_1 + c_2 \vec{y}_2(x) + c_3 \vec{y}_3(x) + \begin{bmatrix} \frac{(-4e^{-x}+4)\cos(2x)}{34} - 2x^2 - \frac{e^{-x}\sin(2x)}{34} - 3x + 4e^x - \frac{9\sin(2x)}{17} \\ \frac{(2e^{-x}-36)\cos(2x)}{34} + \frac{9e^{-x}\sin(2x)}{34} - 4x + 4e^x - \frac{4\sin(2x)}{17} - 3 \\ -4 + \frac{8(-1+e^{-x})\cos(2x)}{17} - \frac{13e^{-x}\sin(2x)}{34} + 4e^x + \frac{36\sin(2x)}{17} \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y = -4 + \frac{((-50-51c_2-68c_3)\cos(2x)-68\sin(2x)(c_2-\frac{3c_3}{4}+\frac{25}{136}))e^{-x}}{425} + \frac{2\cos(2x)}{17} - \frac{9\sin(2x)}{17} + (c_1+4)e^x - 2x^2$$

Maple trace

```
`Methods for third order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
trying differential order: 3; linear nonhomogeneous with symmetry [0,1]  
trying high order linear exact nonhomogeneous  
trying differential order: 3; missing the dependent variable  
checking if the LODE has constant coefficients  
<- constant coefficients successful`
```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 49

```
dsolve(diff(y(x),x$3)+diff(y(x),x$2)+3*diff(y(x),x)-5*y(x)=5*sin(2*x)+10*x^2+3*x+7,y(x), sin
```

$$y(x) = \frac{(17c_3e^{-x} - 9) \sin(2x)}{17} + c_2e^{-x} \cos(2x) - 2x^2 + c_1e^x - 3x + \frac{2 \cos(2x)}{17} - 4$$

✓ Solution by Mathematica

Time used: 0.419 (sec). Leaf size: 55

```
DSolve[y'''[x]+y''[x]+3*y'[x]-5*y[x]==5*Sin[2*x]+10*x^2+3*x+7,y[x],x,IncludeSingularSolution
```

$$y(x) \rightarrow -2x^2 - 3x + c_3e^x + \left(\frac{2}{17} + c_2e^{-x}\right) \cos(2x) + \left(-\frac{9}{17} + c_1e^{-x}\right) \sin(2x) - 4$$

11.12 problem 12

11.12.1 Maple step by step solution 2366

Internal problem ID [11786]

Internal file name [OUTPUT/11795_Thursday_April_11_2024_08_49_44_PM_54708509/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 12.

ODE order: 3.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_3rd_order , _linear , _nonhomogeneous]]
```

$$4y''' - 4y'' - 5y' + 3y = 3x^3 - 8x$$

This is higher order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE And y_p is a particular solution to the nonhomogeneous ODE. y_h is the solution to

$$4y''' - 4y'' - 5y' + 3y = 0$$

The characteristic equation is

$$4\lambda^3 - 4\lambda^2 - 5\lambda + 3 = 0$$

The roots of the above equation are

$$\begin{aligned}\lambda_1 &= \frac{1}{2} \\ \lambda_2 &= \frac{3}{2} \\ \lambda_3 &= -1\end{aligned}$$

Therefore the homogeneous solution is

$$y_h(x) = c_1 e^{-x} + e^{\frac{x}{2}} c_2 + c_3 e^{\frac{3x}{2}}$$

The fundamental set of solutions for the homogeneous solution are the following

$$y_1 = e^{-x}$$

$$y_2 = e^{\frac{x}{2}}$$

$$y_3 = e^{\frac{3x}{2}}$$

Now the particular solution to the given ODE is found

$$4y''' - 4y'' - 5y' + 3y = 3x^3 - 8x$$

The particular solution is found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$x^3 + x$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{1, x, x^2, x^3\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\left\{ e^{-x}, e^{\frac{x}{2}}, e^{\frac{3x}{2}} \right\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_4 x^3 + A_3 x^2 + A_2 x + A_1$$

The unknowns $\{A_1, A_2, A_3, A_4\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$\begin{aligned} 3A_4 x^3 + 3A_3 x^2 - 15x^2 A_4 + 3A_2 x - 10x A_3 - 24x A_4 + 3A_1 - 5A_2 - 8A_3 + 24A_4 \\ = 3x^3 - 8x \end{aligned}$$

Solving for the unknowns by comparing coefficients results in

$$[A_1 = 42, A_2 = 22, A_3 = 5, A_4 = 1]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = x^3 + 5x^2 + 22x + 42$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(c_1 e^{-x} + e^{\frac{x}{2}} c_2 + c_3 e^{\frac{3x}{2}} \right) + (x^3 + 5x^2 + 22x + 42) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 e^{-x} + e^{\frac{x}{2}} c_2 + c_3 e^{\frac{3x}{2}} + x^3 + 5x^2 + 22x + 42 \quad (1)$$

Verification of solutions

$$y = c_1 e^{-x} + e^{\frac{x}{2}} c_2 + c_3 e^{\frac{3x}{2}} + x^3 + 5x^2 + 22x + 42$$

Verified OK.

11.12.1 Maple step by step solution

Let's solve

$$4y''' - 4y'' - 5y' + 3y = 3x^3 - 8x$$

- Highest derivative means the order of the ODE is 3

$$y'''$$

- Isolate 3rd derivative

$$y''' = y'' + \frac{5y'}{4} - \frac{3y}{4} + \frac{3x^3}{4} - 2x$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y''' - y'' - \frac{5y'}{4} + \frac{3y}{4} = \frac{3}{4}x^3 - 2x$$

- Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(x)$

$$y_1(x) = y$$

- Define new variable $y_2(x)$

$$y_2(x) = y'$$

- Define new variable $y_3(x)$

$$y_3(x) = y''$$

- Isolate for $y_3'(x)$ using original ODE

$$y_3'(x) = \frac{3x^3}{4} - 2x + y_3(x) + \frac{5y_2(x)}{4} - \frac{3y_1(x)}{4}$$

Convert linear ODE into a system of first order ODEs

$$\left[y_2(x) = y_1'(x), y_3(x) = y_2'(x), y_3'(x) = \frac{3x^3}{4} - 2x + y_3(x) + \frac{5y_2(x)}{4} - \frac{3y_1(x)}{4} \right]$$

- Define vector

$$\vec{y}(x) = \begin{bmatrix} y_1(x) \\ y_2(x) \\ y_3(x) \end{bmatrix}$$

- System to solve

$$\vec{y}'(x) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -\frac{3}{4} & \frac{5}{4} & 1 \end{bmatrix} \cdot \vec{y}(x) + \begin{bmatrix} 0 \\ 0 \\ \frac{3}{4}x^3 - 2x \end{bmatrix}$$

- Define the forcing function

$$\vec{f}(x) = \begin{bmatrix} 0 \\ 0 \\ \frac{3}{4}x^3 - 2x \end{bmatrix}$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -\frac{3}{4} & \frac{5}{4} & 1 \end{bmatrix}$$

- Rewrite the system as

$$\vec{y}'(x) = A \cdot \vec{y}(x) + \vec{f}$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[-1, \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \right], \left[\frac{1}{2}, \begin{bmatrix} 4 \\ 2 \\ 1 \end{bmatrix} \right], \left[\frac{3}{2}, \begin{bmatrix} \frac{4}{9} \\ \frac{2}{3} \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[-1, \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_1 = e^{-x} \cdot \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[\frac{1}{2}, \begin{bmatrix} 4 \\ 2 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_2 = e^{\frac{x}{2}} \cdot \begin{bmatrix} 4 \\ 2 \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[\frac{3}{2}, \begin{bmatrix} \frac{4}{9} \\ \frac{2}{3} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_3 = e^{\frac{3x}{2}} \cdot \begin{bmatrix} \frac{4}{9} \\ \frac{2}{3} \\ 1 \end{bmatrix}$$

- General solution of the system of ODEs can be written in terms of the particular solution $\vec{y}_p(x)$

$$\vec{y}(x) = c_1 \vec{y}_1 + c_2 \vec{y}_2 + c_3 \vec{y}_3 + \vec{y}_p(x)$$

□ Fundamental matrix

- Let $\phi(x)$ be the matrix whose columns are the independent solutions of the homogeneous system

$$\phi(x) = \begin{bmatrix} e^{-x} & 4e^{\frac{x}{2}} & \frac{4e^{\frac{3x}{2}}}{9} \\ -e^{-x} & 2e^{\frac{x}{2}} & \frac{2e^{\frac{3x}{2}}}{3} \\ e^{-x} & e^{\frac{x}{2}} & e^{\frac{3x}{2}} \end{bmatrix}$$

- The fundamental matrix, $\Phi(x)$ is a normalized version of $\phi(x)$ satisfying $\Phi(0) = I$ where I is the identity matrix

$$\Phi(x) = \phi(x) \cdot \frac{1}{\phi(0)}$$

- Substitute the value of $\phi(x)$ and $\phi(0)$

$$\Phi(x) = \begin{bmatrix} e^{-x} & 4e^{\frac{x}{2}} & \frac{4e^{\frac{3x}{2}}}{9} \\ -e^{-x} & 2e^{\frac{x}{2}} & \frac{2e^{\frac{3x}{2}}}{3} \\ e^{-x} & e^{\frac{x}{2}} & e^{\frac{3x}{2}} \end{bmatrix} \cdot \frac{1}{\begin{bmatrix} 1 & 4 & \frac{4}{9} \\ -1 & 2 & \frac{2}{3} \\ 1 & 1 & 1 \end{bmatrix}}$$

- Evaluate and simplify to get the fundamental matrix

$$\Phi(x) = \begin{bmatrix} \frac{(e^{\frac{5x}{2}} - 5e^{\frac{3x}{2}} - 1)e^{-x}}{5} & \frac{(3e^{\frac{5x}{2}} + 5e^{\frac{3x}{2}} - 8)e^{-x}}{15} & \frac{2(3e^{\frac{5x}{2}} - 5e^{\frac{3x}{2}} + 2)e^{-x}}{15} \\ \frac{(3e^{\frac{5x}{2}} - 5e^{\frac{3x}{2}} + 2)e^{-x}}{10} & \frac{(9e^{\frac{5x}{2}} + 5e^{\frac{3x}{2}} + 16)e^{-x}}{30} & \frac{(9e^{\frac{5x}{2}} - 5e^{\frac{3x}{2}} - 4)e^{-x}}{15} \\ \frac{(9e^{\frac{5x}{2}} - 5e^{\frac{3x}{2}} - 4)e^{-x}}{20} & \frac{(27e^{\frac{5x}{2}} + 5e^{\frac{3x}{2}} - 32)e^{-x}}{60} & \frac{(27e^{\frac{5x}{2}} - 5e^{\frac{3x}{2}} + 8)e^{-x}}{30} \end{bmatrix}$$

□ Find a particular solution of the system of ODEs using variation of parameters

- Let the particular solution be the fundamental matrix multiplied by $\vec{v}(x)$ and solve for $\vec{v}(x)$

$$\vec{y}_p(x) = \Phi(x) \cdot \vec{v}(x)$$

- Take the derivative of the particular solution

$$\vec{y}'_p(x) = \Phi'(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x)$$

- Substitute particular solution and its derivative into the system of ODEs

$$\Phi'(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x) = A \cdot \Phi(x) \cdot \vec{v}(x) + \vec{f}(x)$$

- The fundamental matrix has columns that are solutions to the homogeneous system so its derivative

$$A \cdot \Phi(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x) = A \cdot \Phi(x) \cdot \vec{v}(x) + \vec{f}(x)$$

- Cancel like terms

$$\Phi(x) \cdot \vec{v}'(x) = \vec{f}(x)$$

- Multiply by the inverse of the fundamental matrix

$$\vec{v}'(x) = \frac{1}{\Phi(x)} \cdot \vec{f}(x)$$

- Integrate to solve for $\vec{v}(x)$

$$\vec{v}(x) = \int_0^x \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds$$

- Plug $\vec{v}(x)$ into the equation for the particular solution

$$\vec{y}_p(x) = \Phi(x) \cdot \left(\int_0^x \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds \right)$$

- Plug in the fundamental matrix and the forcing function and compute

$$\vec{y}_p(x) = \begin{bmatrix} e^{-x} \left(-\frac{128e^{\frac{3x}{2}}}{3} + \frac{2}{3} + (x^3 + 5x^2 + 22x + 42)e^x \right) \\ \frac{(9x^2e^x - 64e^{\frac{3x}{2}} + 30xe^x + 66e^x - 2)e^{-x}}{3} \\ \frac{2(-16e^{\frac{3x}{2}} + 9xe^x + 15e^x + 1)e^{-x}}{3} \end{bmatrix}$$

- Plug particular solution back into general solution

$$\vec{y}(x) = c_1 \vec{y}_1 + c_2 \vec{y}_2 + c_3 \vec{y}_3 + \begin{bmatrix} e^{-x} \left(-\frac{128e^{\frac{3x}{2}}}{3} + \frac{2}{3} + (x^3 + 5x^2 + 22x + 42)e^x \right) \\ \frac{(9x^2e^x - 64e^{\frac{3x}{2}} + 30xe^x + 66e^x - 2)e^{-x}}{3} \\ \frac{2(-16e^{\frac{3x}{2}} + 9xe^x + 15e^x + 1)e^{-x}}{3} \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y = e^{-x} \left(\frac{2}{3} + 4 \left(-\frac{32}{3} + c_2 \right) e^{\frac{3x}{2}} + \frac{4c_3 e^{\frac{5x}{2}}}{9} + (x^3 + 5x^2 + 22x + 42)e^x + c_1 \right)$$

Maple trace

```
`Methods for third order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
trying differential order: 3; linear nonhomogeneous with symmetry [0,1]  
trying high order linear exact nonhomogeneous  
trying differential order: 3; missing the dependent variable  
checking if the LODE has constant coefficients  
<- constant coefficients successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 39

```
dsolve(4*diff(y(x),x$3)-4*diff(y(x),x$2)-5*diff(y(x),x)+3*y(x)=3*x^3-8*x,y(x), singsol=all)
```

$$y(x) = \left(c_2 e^{\frac{3x}{2}} + c_3 e^{\frac{5x}{2}} + (x^3 + 5x^2 + 22x + 42) e^x + c_1 \right) e^{-x}$$

✓ Solution by Mathematica

Time used: 0.005 (sec). Leaf size: 46

```
DSolve[4*y'''[x]-4*y''[x]-5*y'[x]+3*y[x]==3*x^3-8*x,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow x^3 + 5x^2 + 22x + c_1 e^{x/2} + c_2 e^{3x/2} + c_3 e^{-x} + 42$$

11.13 problem 13

11.13.1 Solving as second order linear constant coeff ode	2372
11.13.2 Solving using Kovacic algorithm	2375
11.13.3 Maple step by step solution	2382

Internal problem ID [11787]

Internal file name [OUTPUT/11796_Thursday_April_11_2024_08_49_44_PM_37991172/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 13.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' + y' - 6y = 10e^{2x} - 18e^{3x} - 6x - 11$$

11.13.1 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = 1, C = -6, f(x) = 10e^{2x} - 18e^{3x} - 6x - 11$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + y' - 6y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 1, C = -6$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + \lambda e^{\lambda x} - 6 e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + \lambda - 6 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 1, C = -6$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{-1}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{1^2 - (4)(1)(-6)} \\ &= -\frac{1}{2} \pm \frac{5}{2} \end{aligned}$$

Hence

$$\begin{aligned} \lambda_1 &= -\frac{1}{2} + \frac{5}{2} \\ \lambda_2 &= -\frac{1}{2} - \frac{5}{2} \end{aligned}$$

Which simplifies to

$$\begin{aligned} \lambda_1 &= 2 \\ \lambda_2 &= -3 \end{aligned}$$

Since roots are real and distinct, then the solution is

$$\begin{aligned} y &= c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x} \\ y &= c_1 e^{(2)x} + c_2 e^{(-3)x} \end{aligned}$$

Or

$$y = c_1 e^{2x} + c_2 e^{-3x}$$

Therefore the homogeneous solution y_h is

$$y_h = c_1 e^{2x} + c_2 e^{-3x}$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$10e^{2x} - 18e^{3x} - 6x - 11$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{e^{2x}\}, \{e^{3x}\}, \{1, x\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^{-3x}, e^{2x}\}$$

Since e^{2x} is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[\{e^{2x}x\}, \{e^{3x}\}, \{1, x\}]$$

Since there was duplication between the basis functions in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis function in the above updated UC_set.

$$y_p = A_1e^{2x}x + A_2e^{3x} + A_3 + A_4x$$

The unknowns $\{A_1, A_2, A_3, A_4\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$5A_1e^{2x} + 6A_2e^{3x} + A_4 - 6A_3 - 6A_4x = 10e^{2x} - 18e^{3x} - 6x - 11$$

Solving for the unknowns by comparing coefficients results in

$$[A_1 = 2, A_2 = -3, A_3 = 2, A_4 = 1]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = 2e^{2x}x - 3e^{3x} + 2 + x$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1e^{2x} + c_2e^{-3x}) + (2e^{2x}x - 3e^{3x} + 2 + x) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 e^{2x} + c_2 e^{-3x} + 2e^{2x}x - 3e^{3x} + 2 + x \quad (1)$$

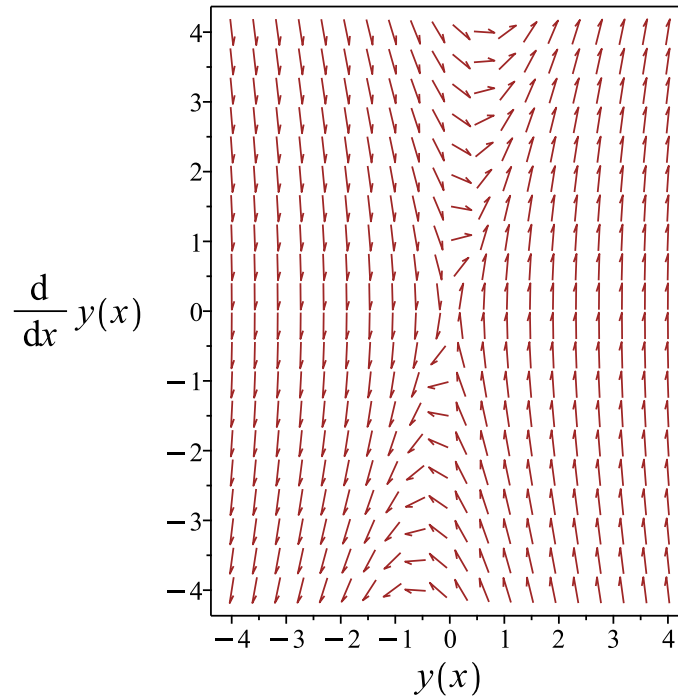


Figure 432: Slope field plot

Verification of solutions

$$y = c_1 e^{2x} + c_2 e^{-3x} + 2e^{2x}x - 3e^{3x} + 2 + x$$

Verified OK.

11.13.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' + y' - 6y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$A = 1$$

$$B = 1 \quad (3)$$

$$C = -6$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{25}{4} \tag{6}$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 25 \\ t &= 4 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = \frac{25z(x)}{4} \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 365: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned}
 \mathcal{O}(\infty) &= \deg(t) - \deg(s) \\
 &= 0 - 0 \\
 &= 0
 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = \frac{25}{4}$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = e^{-\frac{5x}{2}}$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned}
 y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\
 &= z_1 e^{-\int \frac{1}{2} \frac{1}{1} dx} \\
 &= z_1 e^{-\frac{x}{2}} \\
 &= z_1 \left(e^{-\frac{x}{2}} \right)
 \end{aligned}$$

Which simplifies to

$$y_1 = e^{-3x}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{1}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{-x}}{(y_1)^2} dx \\ &= y_1 \left(\frac{e^{5x}}{5} \right) \end{aligned}$$

Therefore the solution is

$$\begin{aligned} y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (e^{-3x}) + c_2 \left(e^{-3x} \left(\frac{e^{5x}}{5} \right) \right) \end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + y' - 6y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1 e^{-3x} + \frac{c_2 e^{2x}}{5}$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of

parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = e^{-3x}$$

$$y_2 = \frac{e^{2x}}{5}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} e^{-3x} & \frac{e^{2x}}{5} \\ \frac{d}{dx}(e^{-3x}) & \frac{d}{dx}\left(\frac{e^{2x}}{5}\right) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} e^{-3x} & \frac{e^{2x}}{5} \\ -3e^{-3x} & \frac{2e^{2x}}{5} \end{vmatrix}$$

Therefore

$$W = (e^{-3x}) \left(\frac{2e^{2x}}{5} \right) - \left(\frac{e^{2x}}{5} \right) (-3e^{-3x})$$

Which simplifies to

$$W = e^{-3x} e^{2x}$$

Which simplifies to

$$W = e^{-x}$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{\frac{e^{2x}(10e^{2x} - 18e^{3x} - 6x - 11)}{5}}{e^{-x}} dx$$

Which simplifies to

$$u_1 = - \int \frac{(10e^{2x} - 18e^{3x} - 6x - 11)e^{3x}}{5} dx$$

Hence

$$u_1 = \frac{3e^{3x}}{5} - \frac{2e^{5x}}{5} + \frac{3e^{6x}}{5} + \frac{2xe^{3x}}{5}$$

And Eq. (3) becomes

$$u_2 = \int \frac{e^{-3x}(10e^{2x} - 18e^{3x} - 6x - 11)}{e^{-x}} dx$$

Which simplifies to

$$u_2 = \int (10e^{2x} - 18e^{3x} - 6x - 11)e^{-2x} dx$$

Hence

$$u_2 = 10x + 7e^{-2x} + 3xe^{-2x} - 18e^x$$

Which simplifies to

$$u_1 = \frac{(3 + 2x)e^{3x}}{5} - \frac{2e^{5x}}{5} + \frac{3e^{6x}}{5}$$
$$u_2 = (-18e^{3x} + 10e^{2x}x + 3x + 7)e^{-2x}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \left(\frac{(3 + 2x)e^{3x}}{5} - \frac{2e^{5x}}{5} + \frac{3e^{6x}}{5} \right) e^{-3x} + \frac{(-18e^{3x} + 10e^{2x}x + 3x + 7)e^{-2x}e^{2x}}{5}$$

Which simplifies to

$$y_p(x) = 2 - \frac{2e^{2x}}{5} - 3e^{3x} + x + 2e^{2x}x$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(c_1 e^{-3x} + \frac{c_2 e^{2x}}{5} \right) + \left(2 - \frac{2e^{2x}}{5} - 3e^{3x} + x + 2e^{2x}x \right) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 e^{-3x} + \frac{c_2 e^{2x}}{5} + 2 - \frac{2e^{2x}}{5} - 3e^{3x} + x + 2e^{2x}x \quad (1)$$

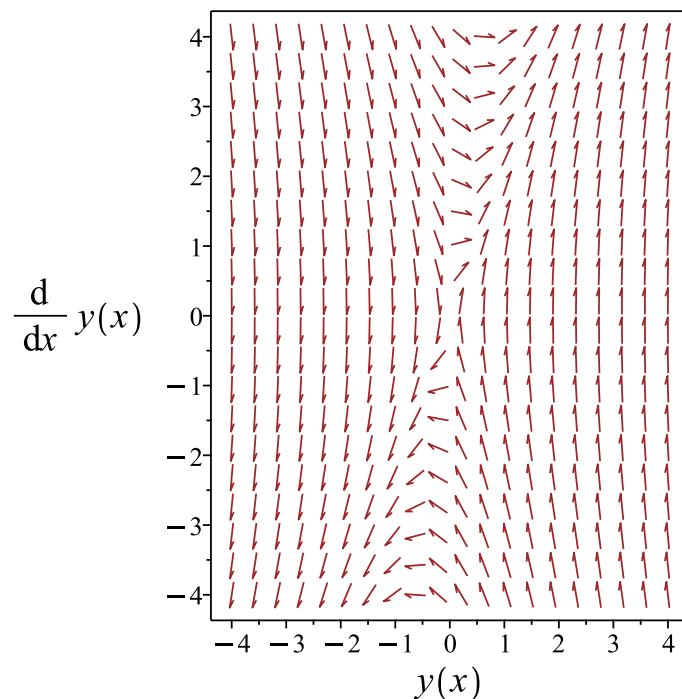


Figure 433: Slope field plot

Verification of solutions

$$y = c_1 e^{-3x} + \frac{c_2 e^{2x}}{5} + 2 - \frac{2e^{2x}}{5} - 3e^{3x} + x + 2e^{2x}x$$

Verified OK.

11.13.3 Maple step by step solution

Let's solve

$$y'' + y' - 6y = 10e^{2x} - 18e^{3x} - 6x - 11$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of homogeneous ODE

$$r^2 + r - 6 = 0$$

- Factor the characteristic polynomial

$$(r + 3)(r - 2) = 0$$

- Roots of the characteristic polynomial

$$r = (-3, 2)$$

- 1st solution of the homogeneous ODE

$$y_1(x) = e^{-3x}$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = e^{2x}$$

- General solution of the ODE

$$y = c_1y_1(x) + c_2y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = c_1e^{-3x} + c_2e^{2x} + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right) \right], f(x) = 10e^{2x} - 18e^{3x} - 6x - 11$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} e^{-3x} & e^{2x} \\ -3e^{-3x} & 2e^{2x} \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = 5e^{-x}$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = \frac{(e^{5x}(\int(10e^{2x}-18e^{3x}-6x-11)e^{-2x}dx) - (\int(10e^{2x}-18e^{3x}-6x-11)e^{3x}dx))e^{-3x}}{5}$$

- Compute integrals

$$y_p(x) = 2 - \frac{2e^{2x}}{5} - 3e^{3x} + x + 2e^{2x}x$$

- Substitute particular solution into general solution to ODE

$$y = c_1e^{-3x} + c_2e^{2x} + 2 - \frac{2e^{2x}}{5} - 3e^{3x} + x + 2e^{2x}x$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
trying a double symmetry of the form [xi=0, eta=F(x)]
-> Try solving first the homogeneous part of the ODE
    checking if the LODE has constant coefficients
    <- constant coefficients successful
<- solving first the homogeneous part of the ODE successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 36

```
dsolve(diff(y(x),x$2)+diff(y(x),x)-6*y(x)=10*exp(2*x)-18*exp(3*x)-6*x-11,y(x), singsol=all)
```

$$y(x) = e^{-3x} \left(\left(2x + c_1 - \frac{2}{5} \right) e^{5x} + (x + 2) e^{3x} + c_2 - 3e^{6x} \right)$$

✓ Solution by Mathematica

Time used: 0.299 (sec). Leaf size: 38

```
DSolve[y''[x]+y'[x]-6*y[x]==10*Exp[2*x]-18*Exp[3*x]-6*x-11,y[x],x,IncludeSingularSolutions->
```

$$y(x) \rightarrow x - 3e^{3x} + c_1e^{-3x} + e^{2x} \left(2x - \frac{2}{5} + c_2 \right) + 2$$

11.14 problem 14

11.14.1 Solving as second order linear constant coeff ode	2384
11.14.2 Solving using Kovacic algorithm	2388
11.14.3 Maple step by step solution	2394

Internal problem ID [11788]

Internal file name [OUTPUT/11797_Thursday_April_11_2024_08_49_45_PM_81940993/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 14.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' + y' - 2y = 6e^{-2x} + 3e^x - 4x^2$$

11.14.1 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = 1, C = -2, f(x) = (-4x^2e^{2x} + 3e^{3x} + 6)e^{-2x}$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + y' - 2y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 1, C = -2$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + \lambda e^{\lambda x} - 2 e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + \lambda - 2 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 1, C = -2$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{-1}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{1^2 - (4)(1)(-2)} \\ &= -\frac{1}{2} \pm \frac{3}{2} \end{aligned}$$

Hence

$$\begin{aligned} \lambda_1 &= -\frac{1}{2} + \frac{3}{2} \\ \lambda_2 &= -\frac{1}{2} - \frac{3}{2} \end{aligned}$$

Which simplifies to

$$\begin{aligned} \lambda_1 &= 1 \\ \lambda_2 &= -2 \end{aligned}$$

Since roots are real and distinct, then the solution is

$$\begin{aligned} y &= c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x} \\ y &= c_1 e^{(1)x} + c_2 e^{(-2)x} \end{aligned}$$

Or

$$y = e^x c_1 + c_2 e^{-2x}$$

Therefore the homogeneous solution y_h is

$$y_h = e^x c_1 + c_2 e^{-2x}$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$(-4x^2e^{2x} + 3e^{3x} + 6)e^{-2x}$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{e^x\}, \{e^{-2x}\}, \{1, x, x^2\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^x, e^{-2x}\}$$

Since e^x is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[\{xe^x\}, \{e^{-2x}\}, \{1, x, x^2\}]$$

Since e^{-2x} is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[\{xe^x\}, \{xe^{-2x}\}, \{1, x, x^2\}]$$

Since there was duplication between the basis functions in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis function in the above updated UC_set.

$$y_p = A_1xe^x + A_2xe^{-2x} + A_3 + A_4x + A_5x^2$$

The unknowns $\{A_1, A_2, A_3, A_4, A_5\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$3A_1e^x - 3A_2e^{-2x} + 2A_5 + A_4 + 2A_5x - 2A_3 - 2A_4x - 2A_5x^2 = (-4x^2e^{2x} + 3e^{3x} + 6)e^{-2x}$$

Solving for the unknowns by comparing coefficients results in

$$[A_1 = 1, A_2 = -2, A_3 = 3, A_4 = 2, A_5 = 2]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = xe^x - 2xe^{-2x} + 3 + 2x + 2x^2$$

Therefore the general solution is

$$\begin{aligned}y &= y_h + y_p \\ &= (e^x c_1 + c_2 e^{-2x}) + (x e^x - 2x e^{-2x} + 3 + 2x + 2x^2)\end{aligned}$$

Summary

The solution(s) found are the following

$$y = e^x c_1 + c_2 e^{-2x} + x e^x - 2x e^{-2x} + 3 + 2x + 2x^2 \quad (1)$$

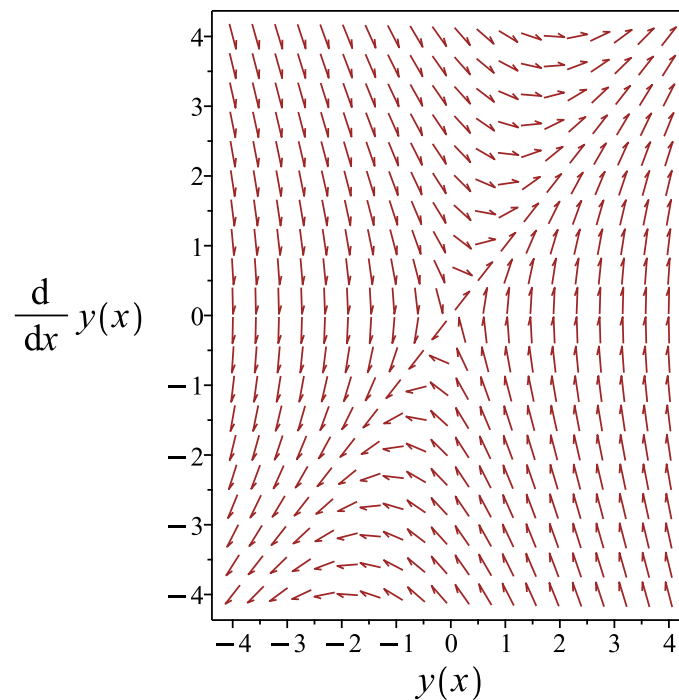


Figure 434: Slope field plot

Verification of solutions

$$y = e^x c_1 + c_2 e^{-2x} + x e^x - 2x e^{-2x} + 3 + 2x + 2x^2$$

Verified OK.

11.14.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' + y' - 2y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$A = 1$$

$$B = 1 \quad (3)$$

$$C = -2$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$r = \frac{s}{t} \quad (5)$$
$$= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{9}{4} \quad (6)$$

Comparing the above to (5) shows that

$$s = 9$$

$$t = 4$$

Therefore eq. (4) becomes

$$z''(x) = \frac{9z(x)}{4} \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 367: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = \frac{9}{4}$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = e^{-\frac{3x}{2}}$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{1}{1} dx} \end{aligned}$$

$$\begin{aligned}
&= z_1 e^{-\frac{x}{2}} \\
&= z_1 \left(e^{-\frac{x}{2}} \right)
\end{aligned}$$

Which simplifies to

$$y_1 = e^{-2x}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}
y_2 &= y_1 \int \frac{e^{\int -\frac{1}{1} dx}}{(y_1)^2} dx \\
&= y_1 \int \frac{e^{-x}}{(y_1)^2} dx \\
&= y_1 \left(\frac{e^{3x}}{3} \right)
\end{aligned}$$

Therefore the solution is

$$\begin{aligned}
y &= c_1 y_1 + c_2 y_2 \\
&= c_1 (e^{-2x}) + c_2 \left(e^{-2x} \left(\frac{e^{3x}}{3} \right) \right)
\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + y' - 2y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1 e^{-2x} + \frac{c_2 e^x}{3}$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = e^{-2x}$$

$$y_2 = \frac{e^x}{3}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} e^{-2x} & \frac{e^x}{3} \\ \frac{d}{dx}(e^{-2x}) & \frac{d}{dx}\left(\frac{e^x}{3}\right) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} e^{-2x} & \frac{e^x}{3} \\ -2e^{-2x} & \frac{e^x}{3} \end{vmatrix}$$

Therefore

$$W = (e^{-2x}) \left(\frac{e^x}{3}\right) - \left(\frac{e^x}{3}\right) (-2e^{-2x})$$

Which simplifies to

$$W = e^{-2x} e^x$$

Which simplifies to

$$W = e^{-x}$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{e^x(-4x^2e^{2x}+3e^{3x}+6)e^{-2x}}{3e^{-x}} dx$$

Which simplifies to

$$u_1 = - \int \left(-\frac{4x^2e^{2x}}{3} + e^{3x} + 2 \right) dx$$

Hence

$$u_1 = -2x + \frac{2x^2e^{2x}}{3} - \frac{2e^{2x}x}{3} + \frac{e^{2x}}{3} - \frac{e^{3x}}{3}$$

And Eq. (3) becomes

$$u_2 = \int \frac{e^{-4x}(-4x^2e^{2x} + 3e^{3x} + 6)}{e^{-x}} dx$$

Which simplifies to

$$u_2 = \int e^{-3x}(-4x^2e^{2x} + 3e^{3x} + 6) dx$$

Hence

$$u_2 = 3x - 2e^{-3x} + 4x^2e^{-x} + 8xe^{-x} + 8e^{-x}$$

Which simplifies to

$$u_1 = \frac{(2x^2 - 2x + 1)e^{2x}}{3} - 2x - \frac{e^{3x}}{3}$$
$$u_2 = (4x^2 + 8x + 8)e^{-x} + 3x - 2e^{-3x}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \left(\frac{(2x^2 - 2x + 1)e^{2x}}{3} - 2x - \frac{e^{3x}}{3} \right) e^{-2x} + \frac{((4x^2 + 8x + 8)e^{-x} + 3x - 2e^{-3x})e^x}{3}$$

Which simplifies to

$$y_p(x) = e^{-2x} \left((2x^2 + 2x + 3) e^{2x} + x e^{3x} - 2x - \frac{e^{3x}}{3} - \frac{2}{3} \right)$$

Therefore the general solution is

$$y = y_h + y_p \\ = \left(c_1 e^{-2x} + \frac{c_2 e^x}{3} \right) + \left(e^{-2x} \left((2x^2 + 2x + 3) e^{2x} + x e^{3x} - 2x - \frac{e^{3x}}{3} - \frac{2}{3} \right) \right)$$

Summary

The solution(s) found are the following

$$y = c_1 e^{-2x} + \frac{c_2 e^x}{3} + e^{-2x} \left((2x^2 + 2x + 3) e^{2x} + x e^{3x} - 2x - \frac{e^{3x}}{3} - \frac{2}{3} \right) \quad (1)$$

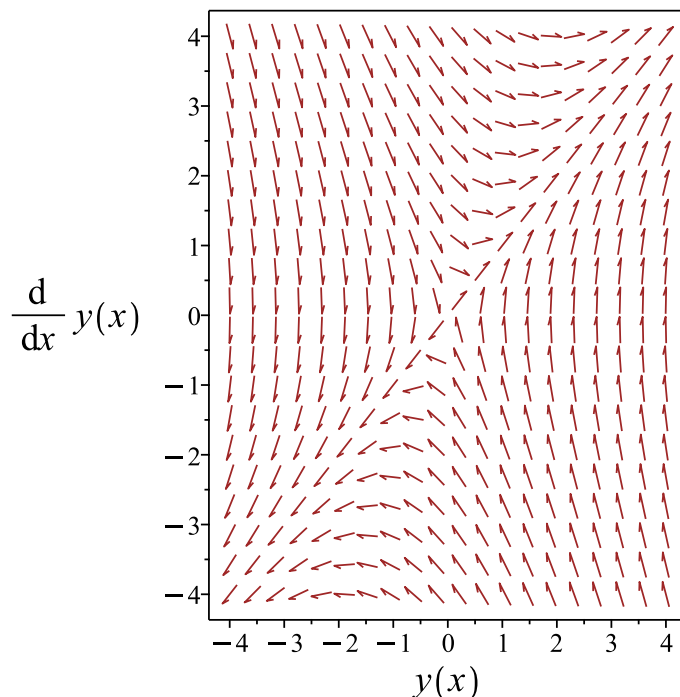


Figure 435: Slope field plot

Verification of solutions

$$y = c_1 e^{-2x} + \frac{c_2 e^x}{3} + e^{-2x} \left((2x^2 + 2x + 3) e^{2x} + x e^{3x} - 2x - \frac{e^{3x}}{3} - \frac{2}{3} \right)$$

Verified OK.

11.14.3 Maple step by step solution

Let's solve

$$y'' + y' - 2y = (-4x^2e^{2x} + 3e^{3x} + 6)e^{-2x}$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = -4e^{2x}e^{-2x}x^2 + 3e^{3x}e^{-2x} - y' + 2y + 6e^{-2x}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + y' - 2y = -(4x^2e^{2x} - 3e^{3x} - 6)e^{-2x}$$

- Characteristic polynomial of homogeneous ODE

$$r^2 + r - 2 = 0$$

- Factor the characteristic polynomial

$$(r + 2)(r - 1) = 0$$

- Roots of the characteristic polynomial

$$r = (-2, 1)$$

- 1st solution of the homogeneous ODE

$$y_1(x) = e^{-2x}$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = e^x$$

- General solution of the ODE

$$y = c_1y_1(x) + c_2y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = c_1e^{-2x} + c_2e^x + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = -(4x^2e^{2x} - 3e^{3x} - 6)e^{-2x} \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} e^{-2x} & e^x \\ -2e^{-2x} & e^x \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = 3e^{-x}$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = -\frac{(e^{3x} \int e^{-3x} (4x^2 e^{2x} - 3e^{3x} - 6) dx) + \int (-4x^2 e^{2x} + 3e^{3x} + 6) dx e^{-2x}}{3}$$

- Compute integrals

$$y_p(x) = e^{-2x} \left((2x^2 + 2x + 3) e^{2x} + x e^{3x} - 2x - \frac{e^{3x}}{3} - \frac{2}{3} \right)$$

- Substitute particular solution into general solution to ODE

$$y = c_1 e^{-2x} + c_2 e^x + e^{-2x} \left((2x^2 + 2x + 3) e^{2x} + x e^{3x} - 2x - \frac{e^{3x}}{3} - \frac{2}{3} \right)$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
trying a double symmetry of the form [xi=0, eta=F(x)]
-> Try solving first the homogeneous part of the ODE
    checking if the LODE has constant coefficients
    <- constant coefficients successful
<- solving first the homogeneous part of the ODE successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 39

```
dsolve(diff(y(x),x$2)+diff(y(x),x)-2*y(x)=6*exp(-2*x)+3*exp(x)-4*x^2,y(x), singsol=all)
```

$$y(x) = e^{-2x} \left((2x^2 + 2x + 3) e^{2x} + \left(c_2 + x - \frac{1}{3} \right) e^{3x} - 2x + c_1 - \frac{2}{3} \right)$$

✓ Solution by Mathematica

Time used: 0.163 (sec). Leaf size: 54

```
DSolve[y''[x]+y'[x]-2*y[x]==6*Exp[-2*x]+3*Exp[x]-4*x^2,y[x],x,IncludeSingularSolutions -> Tr
```

$$y(x) \rightarrow \frac{1}{3}e^{-2x}(e^{2x}(6x^2 + 6x + 9) - 6x + e^{3x}(3x - 1 + 3c_2) - 2 + 3c_1)$$

11.15 problem 15

11.15.1 Maple step by step solution 2399

Internal problem ID [11789]

Internal file name [OUTPUT/11798_Thursday_April_11_2024_08_49_45_PM_5507649/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 15.

ODE order: 3.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_3rd_order , _linear , _nonhomogeneous]]
```

$$y''' - 3y'' + 4y = 4e^x - 18e^{-x}$$

This is higher order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE And y_p is a particular solution to the nonhomogeneous ODE. y_h is the solution to

$$y''' - 3y'' + 4y = 0$$

The characteristic equation is

$$\lambda^3 - 3\lambda^2 + 4 = 0$$

The roots of the above equation are

$$\lambda_1 = -1$$

$$\lambda_2 = 2$$

$$\lambda_3 = 2$$

Therefore the homogeneous solution is

$$y_h(x) = c_1 e^{-x} + c_2 e^{2x} + x e^{2x} c_3$$

The fundamental set of solutions for the homogeneous solution are the following

$$y_1 = e^{-x}$$

$$y_2 = e^{2x}$$

$$y_3 = e^{2x} x$$

Now the particular solution to the given ODE is found

$$y''' - 3y'' + 4y = 4e^x - 18e^{-x}$$

The particular solution is found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$4e^x - 18e^{-x}$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{e^x\}, \{e^{-x}\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^{2x}x, e^{-x}, e^{2x}\}$$

Since e^{-x} is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[\{e^x\}, \{x e^{-x}\}]$$

Since there was duplication between the basis functions in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis function in the above updated UC_set.

$$y_p = A_1 e^x + A_2 x e^{-x}$$

The unknowns $\{A_1, A_2\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$2A_1 e^x + 9A_2 e^{-x} = 4e^x - 18e^{-x}$$

Solving for the unknowns by comparing coefficients results in

$$[A_1 = 2, A_2 = -2]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = 2e^x - 2xe^{-x}$$

Therefore the general solution is

$$\begin{aligned}y &= y_h + y_p \\ &= (c_1e^{-x} + c_2e^{2x} + xe^{2x}c_3) + (2e^x - 2xe^{-x})\end{aligned}$$

Which simplifies to

$$y = (c_3x + c_2)e^{2x} + c_1e^{-x} + 2e^x - 2xe^{-x}$$

Summary

The solution(s) found are the following

$$y = (c_3x + c_2)e^{2x} + c_1e^{-x} + 2e^x - 2xe^{-x} \quad (1)$$

Verification of solutions

$$y = (c_3x + c_2)e^{2x} + c_1e^{-x} + 2e^x - 2xe^{-x}$$

Verified OK.

11.15.1 Maple step by step solution

Let's solve

$$y''' - 3y'' + 4y = 4e^x - 18e^{-x}$$

- Highest derivative means the order of the ODE is 3
- y'''
- Convert linear ODE into a system of first order ODEs
 - Define new variable $y_1(x)$
$$y_1(x) = y$$
 - Define new variable $y_2(x)$

$$y_2(x) = y'$$

- Define new variable $y_3(x)$

$$y_3(x) = y''$$

- Isolate for $y_3'(x)$ using original ODE

$$y_3'(x) = 4e^x - 18e^{-x} + 3y_3(x) - 4y_1(x)$$

Convert linear ODE into a system of first order ODEs

$$[y_2(x) = y_1'(x), y_3(x) = y_2'(x), y_3'(x) = 4e^x - 18e^{-x} + 3y_3(x) - 4y_1(x)]$$

- Define vector

$$\vec{y}(x) = \begin{bmatrix} y_1(x) \\ y_2(x) \\ y_3(x) \end{bmatrix}$$

- System to solve

$$\vec{y}'(x) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -4 & 0 & 3 \end{bmatrix} \cdot \vec{y}(x) + \begin{bmatrix} 0 \\ 0 \\ 4e^x - 18e^{-x} \end{bmatrix}$$

- Define the forcing function

$$\vec{f}(x) = \begin{bmatrix} 0 \\ 0 \\ 4e^x - 18e^{-x} \end{bmatrix}$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -4 & 0 & 3 \end{bmatrix}$$

- Rewrite the system as

$$\vec{y}'(x) = A \cdot \vec{y}(x) + \vec{f}$$

- To solve the system, find the eigenvalues and eigenvectors of A
- Eigenpairs of A

$$\left[\left[-1, \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \right], \left[2, \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right], \left[2, \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[-1, \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_1 = e^{-x} \cdot \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$$

- Consider eigenpair, with eigenvalue of algebraic multiplicity 2

$$\left[2, \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right]$$

- First solution from eigenvalue 2

$$\vec{y}_2(x) = e^{2x} \cdot \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix}$$

- Form of the 2nd homogeneous solution where \vec{p} is to be solved for, $\lambda = 2$ is the eigenvalue, and

$$\vec{y}_3(x) = e^{\lambda x} (x\vec{v} + \vec{p})$$

- Note that the x multiplying \vec{v} makes this solution linearly independent to the 1st solution obtained

- Substitute $\vec{y}_3(x)$ into the homogeneous system

$$\lambda e^{\lambda x} (x\vec{v} + \vec{p}) + e^{\lambda x} \vec{v} = (e^{\lambda x} A) \cdot (x\vec{v} + \vec{p})$$

- Use the fact that \vec{v} is an eigenvector of A

$$\lambda e^{\lambda x} (x\vec{v} + \vec{p}) + e^{\lambda x} \vec{v} = e^{\lambda x} (\lambda x\vec{v} + A \cdot \vec{p})$$

- Simplify equation

$$\lambda \vec{p} + \vec{v} = A \cdot \vec{p}$$

- Make use of the identity matrix I

$$(\lambda \cdot I) \cdot \vec{p} + \vec{v} = A \cdot \vec{p}$$

- Condition \vec{p} must meet for $\vec{y}_3(x)$ to be a solution to the homogeneous system

$$(A - \lambda \cdot I) \cdot \vec{p} = \vec{v}$$

- Choose \vec{p} to use in the second solution to the homogeneous system from eigenvalue 2

$$\left(\begin{pmatrix} \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -4 & 0 & 3 \end{bmatrix} - 2 \cdot \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \end{pmatrix} \cdot \vec{p} = \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right)$$

- Choice of \vec{p}

$$\vec{p} = \begin{bmatrix} -\frac{1}{8} \\ 0 \\ 0 \end{bmatrix}$$

- Second solution from eigenvalue 2

$$\vec{y}_3(x) = e^{2x} \cdot \left(x \cdot \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} + \begin{bmatrix} -\frac{1}{8} \\ 0 \\ 0 \end{bmatrix} \right)$$

- General solution of the system of ODEs can be written in terms of the particular solution $\vec{y}_p(x)$

$$\vec{y}(x) = c_1 \vec{y}_1 + c_2 \vec{y}_2(x) + c_3 \vec{y}_3(x) + \vec{y}_p(x)$$

- Fundamental matrix

- Let $\phi(x)$ be the matrix whose columns are the independent solutions of the homogeneous system

$$\phi(x) = \begin{bmatrix} e^{-x} & \frac{e^{2x}}{4} & e^{2x} \left(\frac{x}{4} - \frac{1}{8} \right) \\ -e^{-x} & \frac{e^{2x}}{2} & \frac{e^{2x}x}{2} \\ e^{-x} & e^{2x} & e^{2x}x \end{bmatrix}$$

- The fundamental matrix, $\Phi(x)$ is a normalized version of $\phi(x)$ satisfying $\Phi(0) = I$ where I is the identity matrix

$$\Phi(x) = \phi(x) \cdot \frac{1}{\phi(0)}$$

- Substitute the value of $\phi(x)$ and $\phi(0)$

$$\Phi(x) = \begin{bmatrix} e^{-x} & \frac{e^{2x}}{4} & e^{2x}\left(\frac{x}{4} - \frac{1}{8}\right) \\ -e^{-x} & \frac{e^{2x}}{2} & \frac{e^{2x}x}{2} \\ e^{-x} & e^{2x} & e^{2x}x \end{bmatrix} \cdot \frac{1}{\begin{bmatrix} 1 & \frac{1}{4} & -\frac{1}{8} \\ -1 & \frac{1}{2} & 0 \\ 1 & 1 & 0 \end{bmatrix}}$$

- Evaluate and simplify to get the fundamental matrix

$$\Phi(x) = \begin{bmatrix} (-2x+1)e^{2x} & -\frac{2e^{-x}}{3} + \frac{2e^{2x}}{3} - e^{2x}x & \frac{e^{-x}}{3} - \frac{e^{2x}}{3} + e^{2x}x \\ -4e^{2x}x & \frac{2e^{-x}}{3} + \frac{e^{2x}}{3} - 2e^{2x}x & -\frac{e^{-x}}{3} + \frac{e^{2x}}{3} + 2e^{2x}x \\ -8e^{2x}x & -\frac{2e^{-x}}{3} + \frac{2e^{2x}}{3} - 4e^{2x}x & \frac{e^{-x}}{3} + \frac{2e^{2x}}{3} + 4e^{2x}x \end{bmatrix}$$

- Find a particular solution of the system of ODEs using variation of parameters

- Let the particular solution be the fundamental matrix multiplied by $\vec{v}(x)$ and solve for $\vec{v}(x)$

$$\vec{y}_p(x) = \Phi(x) \cdot \vec{v}(x)$$

- Take the derivative of the particular solution

$$\vec{y}'_p(x) = \Phi'(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x)$$

- Substitute particular solution and its derivative into the system of ODEs

$$\Phi'(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x) = A \cdot \Phi(x) \cdot \vec{v}(x) + \vec{f}(x)$$

- The fundamental matrix has columns that are solutions to the homogeneous system so its derivative is $A \cdot \Phi(x)$

$$A \cdot \Phi(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x) = A \cdot \Phi(x) \cdot \vec{v}(x) + \vec{f}(x)$$

- Cancel like terms

$$\Phi(x) \cdot \vec{v}'(x) = \vec{f}(x)$$

- Multiply by the inverse of the fundamental matrix

$$\vec{v}'(x) = \frac{1}{\Phi(x)} \cdot \vec{f}(x)$$

- Integrate to solve for $\vec{v}(x)$

$$\vec{v}(x) = \int_0^x \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds$$

- Plug $\vec{v}(x)$ into the equation for the particular solution

$$\vec{y}_p(x) = \Phi(x) \cdot \left(\int_0^x \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds \right)$$

- Plug in the fundamental matrix and the forcing function and compute

$$\vec{y}_p(x) = \begin{bmatrix} \frac{(-18x-14)e^{-x}}{3} + \frac{(-6x-4)e^{2x}}{3} + 6e^x \\ \frac{(18x-4)e^{-x}}{3} + \frac{(-12x-14)e^{2x}}{3} + 6e^x \\ \frac{(-18x-14)e^{-x}}{3} + \frac{(-24x-28)e^{2x}}{3} + 14e^x \end{bmatrix}$$

- Plug particular solution back into general solution

$$\vec{y}(x) = c_1 \vec{y}_1 + c_2 \vec{y}_2(x) + c_3 \vec{y}_3(x) + \begin{bmatrix} \frac{(-18x-14)e^{-x}}{3} + \frac{(-6x-4)e^{2x}}{3} + 6e^x \\ \frac{(18x-4)e^{-x}}{3} + \frac{(-12x-14)e^{2x}}{3} + 6e^x \\ \frac{(-18x-14)e^{-x}}{3} + \frac{(-24x-28)e^{2x}}{3} + 14e^x \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y = \frac{(-32+6(-8+c_3)x+6c_2-3c_3)e^{2x}}{24} + \frac{(-14-18x+3c_1)e^{-x}}{3} + 6e^x$$

Maple trace

```

`Methods for third order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 3; linear nonhomogeneous with symmetry [0,1]
trying high order linear exact nonhomogeneous
trying differential order: 3; missing the dependent variable
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 33

```
dsolve(diff(y(x),x$3)-3*diff(y(x),x$2)+4*y(x)=4*exp(x)-18*exp(-x),y(x), singsol=all)
```

$$y(x) = \frac{(-6x + 3c_1 - 4)e^{-x}}{3} + (c_3x + c_2)e^{2x} + 2e^x$$

✓ Solution by Mathematica

Time used: 0.078 (sec). Leaf size: 44

```
DSolve[y'''[x]-3*y''[x]+4*y[x]==4*Exp[x]-18*Exp[-x],y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{1}{3}e^{-x}(-6x + 6e^{2x} + 3e^{3x}(c_3x + c_2) - 4 + 3c_1)$$

11.16 problem 16

11.16.1 Maple step by step solution 2408

Internal problem ID [11790]

Internal file name [OUTPUT/11799_Thursday_April_11_2024_08_49_46_PM_29813267/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 16.

ODE order: 3.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_3rd_order , _linear , _nonhomogeneous]]
```

$$y''' - 2y'' - y' + 2y = 9e^{2x} - 8e^{3x}$$

This is higher order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE And y_p is a particular solution to the nonhomogeneous ODE. y_h is the solution to

$$y''' - 2y'' - y' + 2y = 0$$

The characteristic equation is

$$\lambda^3 - 2\lambda^2 - \lambda + 2 = 0$$

The roots of the above equation are

$$\lambda_1 = 1$$

$$\lambda_2 = 2$$

$$\lambda_3 = -1$$

Therefore the homogeneous solution is

$$y_h(x) = c_1 e^{-x} + c_2 e^x + e^{2x} c_3$$

The fundamental set of solutions for the homogeneous solution are the following

$$y_1 = e^{-x}$$

$$y_2 = e^x$$

$$y_3 = e^{2x}$$

Now the particular solution to the given ODE is found

$$y''' - 2y'' - y' + 2y = 9e^{2x} - 8e^{3x}$$

The particular solution is found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$9e^{2x} - 8e^{3x}$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{e^{2x}\}, \{e^{3x}\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^x, e^{-x}, e^{2x}\}$$

Since e^{2x} is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[\{e^{2x}x\}, \{e^{3x}\}]$$

Since there was duplication between the basis functions in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis function in the above updated UC_set.

$$y_p = A_1 e^{2x} x + A_2 e^{3x}$$

The unknowns $\{A_1, A_2\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$3A_1 e^{2x} + 8A_2 e^{3x} = 9e^{2x} - 8e^{3x}$$

Solving for the unknowns by comparing coefficients results in

$$[A_1 = 3, A_2 = -1]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = 3e^{2x}x - e^{3x}$$

Therefore the general solution is

$$\begin{aligned}y &= y_h + y_p \\ &= (c_1e^{-x} + c_2e^x + e^{2x}c_3) + (3e^{2x}x - e^{3x})\end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1e^{-x} + c_2e^x + e^{2x}c_3 + 3e^{2x}x - e^{3x} \quad (1)$$

Verification of solutions

$$y = c_1e^{-x} + c_2e^x + e^{2x}c_3 + 3e^{2x}x - e^{3x}$$

Verified OK.

11.16.1 Maple step by step solution

Let's solve

$$y''' - 2y'' - y' + 2y = 9e^{2x} - 8e^{3x}$$

- Highest derivative means the order of the ODE is 3

y'''

- Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(x)$

$$y_1(x) = y$$

- Define new variable $y_2(x)$

$$y_2(x) = y'$$

- Define new variable $y_3(x)$

$$y_3(x) = y''$$

- Isolate for $y_3'(x)$ using original ODE

$$y_3'(x) = 9e^{2x} - 8e^{3x} + 2y_3(x) + y_2(x) - 2y_1(x)$$

Convert linear ODE into a system of first order ODEs

$$[y_2(x) = y_1'(x), y_3(x) = y_2'(x), y_3'(x) = 9e^{2x} - 8e^{3x} + 2y_3(x) + y_2(x) - 2y_1(x)]$$

- Define vector

$$\vec{y}(x) = \begin{bmatrix} y_1(x) \\ y_2(x) \\ y_3(x) \end{bmatrix}$$

- System to solve

$$\vec{y}'(x) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -2 & 1 & 2 \end{bmatrix} \cdot \vec{y}(x) + \begin{bmatrix} 0 \\ 0 \\ 9e^{2x} - 8e^{3x} \end{bmatrix}$$

- Define the forcing function

$$\vec{f}(x) = \begin{bmatrix} 0 \\ 0 \\ 9e^{2x} - 8e^{3x} \end{bmatrix}$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -2 & 1 & 2 \end{bmatrix}$$

- Rewrite the system as

$$\vec{y}'(x) = A \cdot \vec{y}(x) + \vec{f}$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[-1, \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \right], \left[1, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right], \left[2, \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[-1, \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_1 = e^{-x} \cdot \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[1, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_2 = e^x \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[2, \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_3 = e^{2x} \cdot \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix}$$

- General solution of the system of ODEs can be written in terms of the particular solution $\vec{y}_p(x)$
 $\vec{y}(x) = c_1 \vec{y}_1 + c_2 \vec{y}_2 + c_3 \vec{y}_3 + \vec{y}_p(x)$

□ Fundamental matrix

- Let $\phi(x)$ be the matrix whose columns are the independent solutions of the homogeneous system

$$\phi(x) = \begin{bmatrix} e^{-x} & e^x & \frac{e^{2x}}{4} \\ -e^{-x} & e^x & \frac{e^{2x}}{2} \\ e^{-x} & e^x & e^{2x} \end{bmatrix}$$

- The fundamental matrix, $\Phi(x)$ is a normalized version of $\phi(x)$ satisfying $\Phi(0) = I$ where I is the identity matrix

$$\Phi(x) = \phi(x) \cdot \frac{1}{\phi(0)}$$

- Substitute the value of $\phi(x)$ and $\phi(0)$

$$\Phi(x) = \begin{bmatrix} e^{-x} & e^x & \frac{e^{2x}}{4} \\ -e^{-x} & e^x & \frac{e^{2x}}{2} \\ e^{-x} & e^x & e^{2x} \end{bmatrix} \cdot \frac{1}{\begin{bmatrix} 1 & 1 & \frac{1}{4} \\ -1 & 1 & \frac{1}{2} \\ 1 & 1 & 1 \end{bmatrix}}$$

- Evaluate and simplify to get the fundamental matrix

$$\Phi(x) = \begin{bmatrix} \frac{e^{-x}}{3} + e^x - \frac{e^{2x}}{3} & -\frac{e^{-x}}{2} + \frac{e^x}{2} & \frac{e^{-x}}{6} - \frac{e^x}{2} + \frac{e^{2x}}{3} \\ -\frac{e^{-x}}{3} + e^x - \frac{2e^{2x}}{3} & \frac{e^{-x}}{2} + \frac{e^x}{2} & -\frac{e^{-x}}{6} - \frac{e^x}{2} + \frac{2e^{2x}}{3} \\ \frac{e^{-x}}{3} + e^x - \frac{4e^{2x}}{3} & -\frac{e^{-x}}{2} + \frac{e^x}{2} & \frac{e^{-x}}{6} - \frac{e^x}{2} + \frac{4e^{2x}}{3} \end{bmatrix}$$

- Find a particular solution of the system of ODEs using variation of parameters

- Let the particular solution be the fundamental matrix multiplied by $\vec{v}(x)$ and solve for $\vec{v}(x)$

$$\vec{y}_p(x) = \Phi(x) \cdot \vec{v}(x)$$

- Take the derivative of the particular solution

$$\vec{y}'_p(x) = \Phi'(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x)$$

- Substitute particular solution and its derivative into the system of ODEs

$$\Phi'(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x) = A \cdot \Phi(x) \cdot \vec{v}(x) + \vec{f}(x)$$

- The fundamental matrix has columns that are solutions to the homogeneous system so its derivative is $A \cdot \Phi(x)$

$$A \cdot \Phi(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x) = A \cdot \Phi(x) \cdot \vec{v}(x) + \vec{f}(x)$$

- Cancel like terms

$$\Phi(x) \cdot \vec{v}'(x) = \vec{f}(x)$$

- Multiply by the inverse of the fundamental matrix

$$\vec{v}'(x) = \frac{1}{\Phi(x)} \cdot \vec{f}(x)$$

- Integrate to solve for $\vec{v}(x)$

$$\vec{v}(x) = \int_0^x \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds$$

- Plug $\vec{v}(x)$ into the equation for the particular solution

$$\vec{y}_p(x) = \Phi(x) \cdot \left(\int_0^x \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds \right)$$

- Plug in the fundamental matrix and the forcing function and compute

$$\vec{y}_p(x) = \begin{bmatrix} -\frac{4e^{2x}}{3} + 3e^{2x}x - \frac{e^{-x}}{6} + \frac{5e^x}{2} - e^{3x} \\ \frac{e^{2x}}{3} + 6e^{2x}x + \frac{e^{-x}}{6} + \frac{5e^x}{2} - 3e^{3x} \\ \frac{20e^{2x}}{3} + 12e^{2x}x - \frac{e^{-x}}{6} + \frac{5e^x}{2} - 9e^{3x} \end{bmatrix}$$

- Plug particular solution back into general solution

$$\vec{y}(x) = c_1 \vec{y}_1 + c_2 \vec{y}_2 + c_3 \vec{y}_3 + \begin{bmatrix} -\frac{4e^{2x}}{3} + 3e^{2x}x - \frac{e^{-x}}{6} + \frac{5e^x}{2} - e^{3x} \\ \frac{e^{2x}}{3} + 6e^{2x}x + \frac{e^{-x}}{6} + \frac{5e^x}{2} - 3e^{3x} \\ \frac{20e^{2x}}{3} + 12e^{2x}x - \frac{e^{-x}}{6} + \frac{5e^x}{2} - 9e^{3x} \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y = \frac{(36x+3c_3-16)e^{2x}}{12} + \frac{(-1+6c_1)e^{-x}}{6} - e^{3x} + \frac{(5+2c_2)e^x}{2}$$

Maple trace

```

`Methods for third order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 3; linear nonhomogeneous with symmetry [0,1]
trying high order linear exact nonhomogeneous
trying differential order: 3; missing the dependent variable
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 32

```
dsolve(diff(y(x),x$3)-2*diff(y(x),x$2)-diff(y(x),x)+2*y(x)=9*exp(2*x)-8*exp(3*x),y(x), sings
```

$$y(x) = (3x + c_3 - 4)e^{2x} + c_1e^x + c_2e^{-x} - e^{3x}$$

✓ Solution by Mathematica

Time used: 0.033 (sec). Leaf size: 44

```
DSolve[y'''[x]-2*y''[x]-y'[x]+2*y[x]==9*Exp[2*x]-8*Exp[3*x],y[x],x,IncludeSingularSolutions
```

$$y(x) \rightarrow -e^{3x} + c_1e^{-x} + \left(\frac{81}{32} + c_2\right)e^x + e^{2x}(3x - 4 + c_3)$$

11.17 problem 17

11.17.1 Maple step by step solution 2418

Internal problem ID [11791]

Internal file name [OUTPUT/11800_Thursday_April_11_2024_08_49_46_PM_28207374/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 17.

ODE order: 3.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_3rd_order , _missing_y]]
```

$$y''' + y' = 2x^2 + 4 \sin(x)$$

This is higher order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE And y_p is a particular solution to the nonhomogeneous ODE. y_h is the solution to

$$y''' + y' = 0$$

The characteristic equation is

$$\lambda^3 + \lambda = 0$$

The roots of the above equation are

$$\lambda_1 = 0$$

$$\lambda_2 = i$$

$$\lambda_3 = -i$$

Therefore the homogeneous solution is

$$y_h(x) = c_1 + e^{ix}c_2 + e^{-ix}c_3$$

The fundamental set of solutions for the homogeneous solution are the following

$$y_1 = 1$$

$$y_2 = e^{ix}$$

$$y_3 = e^{-ix}$$

Now the particular solution to the given ODE is found

$$y''' + y' = 2x^2 + 4 \sin(x)$$

Let the particular solution be

$$y_p = U_1y_1 + U_2y_2 + U_3y_3$$

Where y_i are the basis solutions found above for the homogeneous solution y_h and $U_i(x)$ are functions to be determined as follows

$$U_i = (-1)^{n-i} \int \frac{F(x)W_i(x)}{aW(x)} dx$$

Where $W(x)$ is the Wronskian and $W_i(x)$ is the Wronskian that results after deleting the last row and the i -th column of the determinant and n is the order of the ODE or equivalently, the number of basis solutions, and a is the coefficient of the leading derivative in the ODE, and $F(x)$ is the RHS of the ODE. Therefore, the first step is to find the Wronskian $W(x)$. This is given by

$$W(x) = \begin{vmatrix} y_1 & y_2 & y_3 \\ y_1' & y_2' & y_3' \\ y_1'' & y_2'' & y_3'' \end{vmatrix}$$

Substituting the fundamental set of solutions y_i found above in the Wronskian gives

$$W = \begin{bmatrix} 1 & e^{ix} & e^{-ix} \\ 0 & ie^{ix} & -ie^{-ix} \\ 0 & -e^{ix} & -e^{-ix} \end{bmatrix}$$

$$|W| = -2ie^{ix}e^{-ix}$$

The determinant simplifies to

$$|W| = -2i$$

Now we determine W_i for each U_i .

$$\begin{aligned} W_1(x) &= \det \begin{bmatrix} e^{ix} & e^{-ix} \\ ie^{ix} & -ie^{-ix} \end{bmatrix} \\ &= -2i \end{aligned}$$

$$\begin{aligned} W_2(x) &= \det \begin{bmatrix} 1 & e^{-ix} \\ 0 & -ie^{-ix} \end{bmatrix} \\ &= -ie^{-ix} \end{aligned}$$

$$\begin{aligned} W_3(x) &= \det \begin{bmatrix} 1 & e^{ix} \\ 0 & ie^{ix} \end{bmatrix} \\ &= ie^{ix} \end{aligned}$$

Now we are ready to evaluate each $U_i(x)$.

$$\begin{aligned} U_1 &= (-1)^{3-1} \int \frac{F(x)W_1(x)}{aW(x)} dx \\ &= (-1)^2 \int \frac{(2x^2 + 4 \sin(x))(-2i)}{(1)(-2i)} dx \\ &= \int \frac{-2i(2x^2 + 4 \sin(x))}{-2i} dx \\ &= \int (2x^2 + 4 \sin(x)) dx \\ &= \frac{2x^3}{3} - 4 \cos(x) \end{aligned}$$

$$\begin{aligned} U_2 &= (-1)^{3-2} \int \frac{F(x)W_2(x)}{aW(x)} dx \\ &= (-1)^1 \int \frac{(2x^2 + 4 \sin(x))(-ie^{-ix})}{(1)(-2i)} dx \\ &= - \int \frac{-i(2x^2 + 4 \sin(x))e^{-ix}}{-2i} dx \\ &= - \int ((x^2 + 2 \sin(x)) e^{-ix}) dx \\ &= - \left(\int (x^2 + 2 \sin(x)) e^{-ix} dx \right) \end{aligned}$$

$$\begin{aligned}
U_3 &= (-1)^{3-3} \int \frac{F(x)W_3(x)}{aW(x)} dx \\
&= (-1)^0 \int \frac{(2x^2 + 4 \sin(x)) (ie^{ix})}{(1)(-2i)} dx \\
&= \int \frac{i(2x^2 + 4 \sin(x)) e^{ix}}{-2i} dx \\
&= \int (-(x^2 + 2 \sin(x)) e^{ix}) dx \\
&= \frac{-4ie^{ix} + (-2 - i)x e^{ix} + (-4 + 2i)e^{ix} \tan\left(\frac{x}{2}\right) + ix^2 e^{ix} + (-2 + i)x e^{ix} \tan\left(\frac{x}{2}\right)^2 + ix^2 e^{ix} \tan\left(\frac{x}{2}\right)^2}{1 + \tan\left(\frac{x}{2}\right)^2} \\
&= \frac{-4ie^{ix} + (-2 - i)x e^{ix} + (-4 + 2i)e^{ix} \tan\left(\frac{x}{2}\right) + ix^2 e^{ix} + (-2 + i)x e^{ix} \tan\left(\frac{x}{2}\right)^2 + ix^2 e^{ix} \tan\left(\frac{x}{2}\right)^2}{1 + \tan\left(\frac{x}{2}\right)^2}
\end{aligned}$$

Now that all the U_i functions have been determined, the particular solution is found from

$$y_p = U_1 y_1 + U_2 y_2 + U_3 y_3$$

Hence

$$\begin{aligned}
y_p &= \left(\frac{2x^3}{3} - 4 \cos(x) \right) \\
&+ \left(- \left(\int (x^2 + 2 \sin(x)) e^{-ix} dx \right) \right) (e^{ix}) \\
&+ \left(\frac{-4ie^{ix} + (-2 - i)x e^{ix} + (-4 + 2i)e^{ix} \tan\left(\frac{x}{2}\right) + ix^2 e^{ix} + (-2 + i)x e^{ix} \tan\left(\frac{x}{2}\right)^2 + ix^2 e^{ix} \tan\left(\frac{x}{2}\right)^2}{1 + \tan\left(\frac{x}{2}\right)^2} \right)
\end{aligned}$$

Therefore the particular solution is

$$y_p = -2i - \left(\int (x^2 + 2 \sin(x)) e^{-ix} dx \right) e^{ix} + (-ix - 2i - 4) \cos(x) + (-2 + i - x) \sin(x) + ix^2 + \frac{2x^3}{3} - 2x$$

Which simplifies to

$$y_p = -2i - \left(\int (x^2 + 2 \sin(x)) \cos(x) dx \right) (i \sin(x) + \cos(x)) + (-\sin(x) + i \cos(x)) \left(\int (x^2 + 2 \sin(x)) \sin(x) dx \right) + (-ix - 2i - 4) \cos(x) + (-2 + i - x) \sin(x) + ix^2 + \frac{2x^3}{3} - 2x$$

Therefore the general solution is

$$\begin{aligned}
y &= y_h + y_p \\
&= (c_1 + e^{ix} c_2 + e^{-ix} c_3) + \left(-2i - \left(\int (x^2 + 2 \sin(x)) \cos(x) dx \right) (i \sin(x) + \cos(x)) \right. \\
&\quad \left. + (-\sin(x) + i \cos(x)) \left(\int (x^2 + 2 \sin(x)) \sin(x) dx \right) + (-ix - 2i - 4) \cos(x) \right. \\
&\quad \left. + (-2 + i - x) \sin(x) + ix^2 + \frac{2x^3}{3} - 2x \right)
\end{aligned}$$

Summary

The solution(s) found are the following

$$\begin{aligned} y = & c_1 + e^{ix}c_2 + e^{-ix}c_3 - 2i - \left(\int (x^2 + 2 \sin(x)) \cos(x) dx \right) (i \sin(x) + \cos(x)) \\ & + (-\sin(x) + i \cos(x)) \left(\int (x^2 + 2 \sin(x)) \sin(x) dx \right) \\ & + (-ix - 2i - 4) \cos(x) + (-2 + i - x) \sin(x) + ix^2 + \frac{2x^3}{3} - 2x \end{aligned} \quad (1)$$

Verification of solutions

$$\begin{aligned} y = & c_1 + e^{ix}c_2 + e^{-ix}c_3 - 2i - \left(\int (x^2 + 2 \sin(x)) \cos(x) dx \right) (i \sin(x) + \cos(x)) \\ & + (-\sin(x) + i \cos(x)) \left(\int (x^2 + 2 \sin(x)) \sin(x) dx \right) \\ & + (-ix - 2i - 4) \cos(x) + (-2 + i - x) \sin(x) + ix^2 + \frac{2x^3}{3} - 2x \end{aligned}$$

Verified OK.

11.17.1 Maple step by step solution

Let's solve

$$y''' + y' = 2x^2 + 4 \sin(x)$$

- Highest derivative means the order of the ODE is 3

$$y''''$$

- Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(x)$

$$y_1(x) = y$$

- Define new variable $y_2(x)$

$$y_2(x) = y'$$

- Define new variable $y_3(x)$

$$y_3(x) = y''$$

- Isolate for $y_3'(x)$ using original ODE

$$y_3'(x) = 2x^2 + 4 \sin(x) - y_2(x)$$

Convert linear ODE into a system of first order ODEs

$$[y_2(x) = y_1'(x), y_3(x) = y_2'(x), y_3'(x) = 2x^2 + 4 \sin(x) - y_2(x)]$$

- Define vector

$$\vec{y}(x) = \begin{bmatrix} y_1(x) \\ y_2(x) \\ y_3(x) \end{bmatrix}$$

- System to solve

$$\vec{y}'(x) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{bmatrix} \cdot \vec{y}(x) + \begin{bmatrix} 0 \\ 0 \\ 2x^2 + 4 \sin(x) \end{bmatrix}$$

- Define the forcing function

$$\vec{f}(x) = \begin{bmatrix} 0 \\ 0 \\ 2x^2 + 4 \sin(x) \end{bmatrix}$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{bmatrix}$$

- Rewrite the system as

$$\vec{y}'(x) = A \cdot \vec{y}(x) + \vec{f}$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[0, \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \right], \left[-I, \begin{bmatrix} -1 \\ I \\ 1 \end{bmatrix} \right], \left[I, \begin{bmatrix} -1 \\ -I \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[0, \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

- Consider complex eigenpair, complex conjugate eigenvalue can be ignored

$$\left[-\mathbf{I}, \begin{bmatrix} -1 \\ \mathbf{I} \\ 1 \end{bmatrix} \right]$$

- Solution from eigenpair

$$e^{-Ix} \cdot \begin{bmatrix} -1 \\ \mathbf{I} \\ 1 \end{bmatrix}$$

- Use Euler identity to write solution in terms of sin and cos

$$(\cos(x) - \mathbf{I} \sin(x)) \cdot \begin{bmatrix} -1 \\ \mathbf{I} \\ 1 \end{bmatrix}$$

- Simplify expression

$$\begin{bmatrix} -\cos(x) + \mathbf{I} \sin(x) \\ \mathbf{I}(\cos(x) - \mathbf{I} \sin(x)) \\ \cos(x) - \mathbf{I} \sin(x) \end{bmatrix}$$

- Both real and imaginary parts are solutions to the homogeneous system

$$\left[\vec{y}_2(x) = \begin{bmatrix} -\cos(x) \\ \sin(x) \\ \cos(x) \end{bmatrix}, \vec{y}_3(x) = \begin{bmatrix} \sin(x) \\ \cos(x) \\ -\sin(x) \end{bmatrix} \right]$$

- General solution of the system of ODEs can be written in terms of the particular solution $\vec{y}_p(x)$

$$\vec{y}(x) = c_1 \vec{y}_1 + c_2 \vec{y}_2(x) + c_3 \vec{y}_3(x) + \vec{y}_p(x)$$

- Fundamental matrix

- Let $\phi(x)$ be the matrix whose columns are the independent solutions of the homogeneous system

$$\phi(x) = \begin{bmatrix} 1 & -\cos(x) & \sin(x) \\ 0 & \sin(x) & \cos(x) \\ 0 & \cos(x) & -\sin(x) \end{bmatrix}$$

- The fundamental matrix, $\Phi(x)$ is a normalized version of $\phi(x)$ satisfying $\Phi(0) = I$ where I is the identity matrix. $\Phi(x) = \phi(x) \cdot \frac{1}{\phi(0)}$

- Substitute the value of $\phi(x)$ and $\phi(0)$

$$\Phi(x) = \begin{bmatrix} 1 & -\cos(x) & \sin(x) \\ 0 & \sin(x) & \cos(x) \\ 0 & \cos(x) & -\sin(x) \end{bmatrix} \cdot \frac{1}{\begin{bmatrix} 1 & -1 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}}$$

- Evaluate and simplify to get the fundamental matrix

$$\Phi(x) = \begin{bmatrix} 1 & \sin(x) & 1 - \cos(x) \\ 0 & \cos(x) & \sin(x) \\ 0 & -\sin(x) & \cos(x) \end{bmatrix}$$

- Find a particular solution of the system of ODEs using variation of parameters

- Let the particular solution be the fundamental matrix multiplied by $\vec{v}(x)$ and solve for $\vec{v}(x)$
 $\vec{y}_p(x) = \Phi(x) \cdot \vec{v}(x)$

- Take the derivative of the particular solution

$$\vec{y}'_p(x) = \Phi'(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x)$$

- Substitute particular solution and its derivative into the system of ODEs

$$\Phi'(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x) = A \cdot \Phi(x) \cdot \vec{v}(x) + \vec{f}(x)$$

- The fundamental matrix has columns that are solutions to the homogeneous system so its derivative is $A \cdot \Phi(x)$

$$A \cdot \Phi(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x) = A \cdot \Phi(x) \cdot \vec{v}(x) + \vec{f}(x)$$

- Cancel like terms

$$\Phi(x) \cdot \vec{v}'(x) = \vec{f}(x)$$

- Multiply by the inverse of the fundamental matrix

$$\vec{v}'(x) = \frac{1}{\Phi(x)} \cdot \vec{f}(x)$$

- Integrate to solve for $\vec{v}(x)$

$$\vec{v}(x) = \int_0^x \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds$$

- Plug $\vec{v}(x)$ into the equation for the particular solution

$$\vec{y}_p(x) = \Phi(x) \cdot \left(\int_0^x \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds \right)$$

- Plug in the fundamental matrix and the forcing function and compute

$$\vec{y}_p(x) = \begin{bmatrix} -2x \sin(x) + 4 \sin(x) + \frac{2x^3}{3} - 4 \cos(x) - 4x + 4 \\ (-2x + 4) \cos(x) + 2x^2 + 2 \sin(x) - 4 \\ (2x - 4) \sin(x) + 4x \end{bmatrix}$$

- Plug particular solution back into general solution

$$\vec{y}(x) = c_1 \vec{y}_1 + c_2 \vec{y}_2(x) + c_3 \vec{y}_3(x) + \begin{bmatrix} -2x \sin(x) + 4 \sin(x) + \frac{2x^3}{3} - 4 \cos(x) - 4x + 4 \\ (-2x + 4) \cos(x) + 2x^2 + 2 \sin(x) - 4 \\ (2x - 4) \sin(x) + 4x \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y = 4 + (-2x + 4 + c_3) \sin(x) + (-4 - c_2) \cos(x) + \frac{2x^3}{3} - 4x + c_1$$

Maple trace

```
`Methods for third order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 3; linear nonhomogeneous with symmetry [0,1]
-> Calling odsolve with the ODE`, diff(diff(_b(_a), _a), _a) = 2*_a^2+4*sin(_a)-_b(_a), _b(
  Methods for second order ODEs:
  --- Trying classification methods ---
  trying a quadrature
  trying high order exact linear fully integrable
  trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
  trying a double symmetry of the form [xi=0, eta=F(x)]
  -> Try solving first the homogeneous part of the ODE
    checking if the LODE has constant coefficients
    <- constant coefficients successful
  <- solving first the homogeneous part of the ODE successful
<- differential order: 3; linear nonhomogeneous with symmetry [0,1] successful`
```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 30

```
dsolve(diff(y(x),x$3)+diff(y(x),x)=2*x^2+4*sin(x),y(x), singsol=all)
```

$$y(x) = (-2 - c_2) \cos(x) + (-2x + c_1) \sin(x) + \frac{2x^3}{3} - 4x + c_3$$

✓ Solution by Mathematica

Time used: 0.233 (sec). Leaf size: 35

```
DSolve[y'''[x]+y'[x]==2*x^2+4*Sin[x],y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{2x^3}{3} - 4x - (2 + c_2) \cos(x) + (-2x + c_1) \sin(x) + c_3$$

11.18 problem 18

Internal problem ID [11792]

Internal file name [OUTPUT/11801_Thursday_April_11_2024_08_49_47_PM_42252830/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 18.

ODE order: 4.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_high_order , _missing_y]]
```

$$y'''' - 3y''' + 2y'' = 3e^{-x} + 6e^{2x} - 6x$$

This is higher order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE And y_p is a particular solution to the nonhomogeneous ODE. y_h is the solution to

$$y'''' - 3y''' + 2y'' = 0$$

The characteristic equation is

$$\lambda^4 - 3\lambda^3 + 2\lambda^2 = 0$$

The roots of the above equation are

$$\lambda_1 = 0$$

$$\lambda_2 = 0$$

$$\lambda_3 = 2$$

$$\lambda_4 = 1$$

Therefore the homogeneous solution is

$$y_h(x) = c_2x + c_1 + c_3e^x + e^{2x}c_4$$

The fundamental set of solutions for the homogeneous solution are the following

$$\begin{aligned}y_1 &= 1 \\y_2 &= x \\y_3 &= e^x \\y_4 &= e^{2x}\end{aligned}$$

Now the particular solution to the given ODE is found

$$y'''' - 3y''' + 2y'' = 3e^{-x} + 6e^{2x} - 6x$$

The particular solution is found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$3e^{-x} + 6e^{2x} - 6x$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{e^{-x}\}, \{e^{2x}\}, \{1, x\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{1, x, e^x, e^{2x}\}$$

Since 1 is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[\{e^{-x}\}, \{e^{2x}\}, \{x, x^2\}]$$

Since x is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[\{e^{-x}\}, \{e^{2x}\}, \{x^2, x^3\}]$$

Since e^{2x} is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[\{e^{-x}\}, \{e^{2x}x\}, \{x^2, x^3\}]$$

Since there was duplication between the basis functions in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis function in the above updated UC_set.

$$y_p = A_1 e^{-x} + A_2 e^{2x} x + A_3 x^2 + A_4 x^3$$

The unknowns $\{A_1, A_2, A_3, A_4\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$6A_1 e^{-x} + 4A_2 e^{2x} - 18A_4 + 4A_3 + 12A_4 x = 3e^{-x} + 6e^{2x} - 6x$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = \frac{1}{2}, A_2 = \frac{3}{2}, A_3 = -\frac{9}{4}, A_4 = -\frac{1}{2} \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = \frac{e^{-x}}{2} + \frac{3e^{2x}x}{2} - \frac{9x^2}{4} - \frac{x^3}{2}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_2 x + c_1 + c_3 e^x + e^{2x} c_4) + \left(\frac{e^{-x}}{2} + \frac{3e^{2x}x}{2} - \frac{9x^2}{4} - \frac{x^3}{2} \right) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_2 x + c_1 + c_3 e^x + e^{2x} c_4 + \frac{e^{-x}}{2} + \frac{3e^{2x}x}{2} - \frac{9x^2}{4} - \frac{x^3}{2} \quad (1)$$

Verification of solutions

$$y = c_2 x + c_1 + c_3 e^x + e^{2x} c_4 + \frac{e^{-x}}{2} + \frac{3e^{2x}x}{2} - \frac{9x^2}{4} - \frac{x^3}{2}$$

Verified OK.

Maple trace

```
`Methods for high order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 4; linear nonhomogeneous with symmetry [0,1]
-> Calling odsolve with the ODE`, diff(diff(_b(_a), _a), _a) = 3*(diff(_b(_a), _a))-2*_b(_a)
  Methods for second order ODEs:
  --- Trying classification methods ---
  trying a quadrature
  trying high order exact linear fully integrable
  trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
  trying a double symmetry of the form [xi=0, eta=F(x)]
  <- double symmetry of the form [xi=0, eta=F(x)] successful
<- differential order: 4; linear nonhomogeneous with symmetry [0,1] successful`
```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 41

```
dsolve(diff(y(x), x$4)-3*diff(y(x), x$3)+2*diff(y(x), x$2)=3*exp(-x)+6*exp(2*x)-6*x, y(x), singular
```

$$y(x) = \frac{(6x + c_1 - 12)e^{2x}}{4} - \frac{x^3}{2} - \frac{9x^2}{4} + c_3x + c_2e^x + c_4 + \frac{e^{-x}}{2}$$

✓ Solution by Mathematica

Time used: 0.372 (sec). Leaf size: 54

```
DSolve[y''''[x]-3*y'''[x]+2*y''[x]==3*Exp[-x]+6*Exp[2*x]-6*x,y[x],x,IncludeSingularSolutions
```

$$y(x) \rightarrow \frac{1}{4} \left(-((2x + 9)x^2) + 2e^{-x} + 4c_1e^x + e^{2x}(6x - 12 + c_2) \right) + c_4x + c_3$$

11.19 problem 19

11.19.1 Maple step by step solution 2430

Internal problem ID [11793]

Internal file name [OUTPUT/11802_Thursday_April_11_2024_08_49_47_PM_75614766/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 19.

ODE order: 3.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

[[_3rd_order , _linear , _nonhomogeneous]]

$$y''' - 6y'' + 11y' - 6y = x e^x - 4 e^{2x} + 6 e^{4x}$$

This is higher order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE And y_p is a particular solution to the nonhomogeneous ODE. y_h is the solution to

$$y''' - 6y'' + 11y' - 6y = 0$$

The characteristic equation is

$$\lambda^3 - 6\lambda^2 + 11\lambda - 6 = 0$$

The roots of the above equation are

$$\lambda_1 = 1$$

$$\lambda_2 = 2$$

$$\lambda_3 = 3$$

Therefore the homogeneous solution is

$$y_h(x) = e^x c_1 + c_2 e^{2x} + c_3 e^{3x}$$

The fundamental set of solutions for the homogeneous solution are the following

$$y_1 = e^x$$

$$y_2 = e^{2x}$$

$$y_3 = e^{3x}$$

Now the particular solution to the given ODE is found

$$y''' - 6y'' + 11y' - 6y = x e^x - 4 e^{2x} + 6 e^{4x}$$

The particular solution is found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$x e^x - 4 e^{2x} + 6 e^{4x}$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{e^{2x}\}, \{e^{4x}\}, \{x e^x, e^x\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^x, e^{2x}, e^{3x}\}$$

Since e^x is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[\{e^{2x}\}, \{e^{4x}\}, \{x e^x, x^2 e^x\}]$$

Since e^{2x} is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[\{e^{2x} x\}, \{e^{4x}\}, \{x e^x, x^2 e^x\}]$$

Since there was duplication between the basis functions in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis function in the above updated UC_set.

$$y_p = A_1 e^{2x} x + A_2 e^{4x} + A_3 x e^x + A_4 x^2 e^x$$

The unknowns $\{A_1, A_2, A_3, A_4\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$4A_4x e^x - A_1e^{2x} + 2A_3e^x - 6A_4e^x + 6A_2e^{4x} = x e^x - 4e^{2x} + 6e^{4x}$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = 4, A_2 = 1, A_3 = \frac{3}{4}, A_4 = \frac{1}{4} \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = 4e^{2x}x + e^{4x} + \frac{3xe^x}{4} + \frac{x^2e^x}{4}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (e^x c_1 + c_2 e^{2x} + c_3 e^{3x}) + \left(4e^{2x}x + e^{4x} + \frac{3xe^x}{4} + \frac{x^2e^x}{4} \right) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = e^x c_1 + c_2 e^{2x} + c_3 e^{3x} + 4e^{2x}x + e^{4x} + \frac{3xe^x}{4} + \frac{x^2e^x}{4} \quad (1)$$

Verification of solutions

$$y = e^x c_1 + c_2 e^{2x} + c_3 e^{3x} + 4e^{2x}x + e^{4x} + \frac{3xe^x}{4} + \frac{x^2e^x}{4}$$

Verified OK.

11.19.1 Maple step by step solution

Let's solve

$$y''' - 6y'' + 11y' - 6y = x e^x - 4e^{2x} + 6e^{4x}$$

- Highest derivative means the order of the ODE is 3

$$y'''$$

□ Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(x)$

$$y_1(x) = y$$

- Define new variable $y_2(x)$

$$y_2(x) = y'$$

- Define new variable $y_3(x)$

$$y_3(x) = y''$$

- Isolate for $y_3'(x)$ using original ODE

$$y_3'(x) = x e^x - 4 e^{2x} + 6 e^{4x} + 6y_3(x) - 11y_2(x) + 6y_1(x)$$

Convert linear ODE into a system of first order ODEs

$$[y_2(x) = y_1'(x), y_3(x) = y_2'(x), y_3'(x) = x e^x - 4 e^{2x} + 6 e^{4x} + 6y_3(x) - 11y_2(x) + 6y_1(x)]$$

- Define vector

$$\vec{y}(x) = \begin{bmatrix} y_1(x) \\ y_2(x) \\ y_3(x) \end{bmatrix}$$

- System to solve

$$\vec{y}'(x) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 6 & -11 & 6 \end{bmatrix} \cdot \vec{y}(x) + \begin{bmatrix} 0 \\ 0 \\ x e^x - 4 e^{2x} + 6 e^{4x} \end{bmatrix}$$

- Define the forcing function

$$\vec{f}(x) = \begin{bmatrix} 0 \\ 0 \\ x e^x - 4 e^{2x} + 6 e^{4x} \end{bmatrix}$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 6 & -11 & 6 \end{bmatrix}$$

- Rewrite the system as

$$\vec{y}'(x) = A \cdot \vec{y}(x) + \vec{f}$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[1, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right], \left[2, \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right], \left[3, \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[1, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_1 = e^x \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[2, \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_2 = e^{2x} \cdot \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[3, \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_3 = e^{3x} \cdot \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix}$$

- General solution of the system of ODEs can be written in terms of the particular solution $\vec{y}_p(x)$

$$\vec{y}(x) = c_1 \vec{y}_1 + c_2 \vec{y}_2 + c_3 \vec{y}_3 + \vec{y}_p(x)$$

□ Fundamental matrix

- Let $\phi(x)$ be the matrix whose columns are the independent solutions of the homogeneous system

$$\phi(x) = \begin{bmatrix} e^x & \frac{e^{2x}}{4} & \frac{e^{3x}}{9} \\ e^x & \frac{e^{2x}}{2} & \frac{e^{3x}}{3} \\ e^x & e^{2x} & e^{3x} \end{bmatrix}$$

- The fundamental matrix, $\Phi(x)$ is a normalized version of $\phi(x)$ satisfying $\Phi(0) = I$ where I is the identity matrix

$$\Phi(x) = \phi(x) \cdot \frac{1}{\phi(0)}$$

- Substitute the value of $\phi(x)$ and $\phi(0)$

$$\Phi(x) = \begin{bmatrix} e^x & \frac{e^{2x}}{4} & \frac{e^{3x}}{9} \\ e^x & \frac{e^{2x}}{2} & \frac{e^{3x}}{3} \\ e^x & e^{2x} & e^{3x} \end{bmatrix} \cdot \frac{1}{\begin{bmatrix} 1 & \frac{1}{4} & \frac{1}{9} \\ 1 & \frac{1}{2} & \frac{1}{3} \\ 1 & 1 & 1 \end{bmatrix}}$$

- Evaluate and simplify to get the fundamental matrix

$$\Phi(x) = \begin{bmatrix} 3e^x - 3e^{2x} + e^{3x} & -\frac{5e^x}{2} + 4e^{2x} - \frac{3e^{3x}}{2} & \frac{e^x}{2} - e^{2x} + \frac{e^{3x}}{2} \\ 3e^x - 6e^{2x} + 3e^{3x} & -\frac{5e^x}{2} + 8e^{2x} - \frac{9e^{3x}}{2} & \frac{e^x}{2} - 2e^{2x} + \frac{3e^{3x}}{2} \\ 3e^x - 12e^{2x} + 9e^{3x} & -\frac{5e^x}{2} + 16e^{2x} - \frac{27e^{3x}}{2} & \frac{e^x}{2} - 4e^{2x} + \frac{9e^{3x}}{2} \end{bmatrix}$$

□ Find a particular solution of the system of ODEs using variation of parameters

- Let the particular solution be the fundamental matrix multiplied by $\vec{v}(x)$ and solve for $\vec{v}(x)$

$$\vec{y}_p(x) = \Phi(x) \cdot \vec{v}(x)$$

- Take the derivative of the particular solution

$$\vec{y}_p'(x) = \Phi'(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x)$$

- Substitute particular solution and its derivative into the system of ODEs

$$\Phi'(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x) = A \cdot \Phi(x) \cdot \vec{v}(x) + \vec{f}(x)$$

- The fundamental matrix has columns that are solutions to the homogeneous system so its derivative is $A \cdot \Phi(x)$

$$A \cdot \Phi(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x) = A \cdot \Phi(x) \cdot \vec{v}(x) + \vec{f}(x)$$

- Cancel like terms

$$\Phi(x) \cdot \vec{v}'(x) = \vec{f}(x)$$

- Multiply by the inverse of the fundamental matrix

$$\vec{v}'(x) = \frac{1}{\Phi(x)} \cdot \vec{f}(x)$$

- Integrate to solve for $\vec{v}(x)$

$$\vec{v}(x) = \int_0^x \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds$$

- Plug $\vec{v}(x)$ into the equation for the particular solution

$$\vec{y}_p(x) = \Phi(x) \cdot \left(\int_0^x \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds \right)$$

- Plug in the fundamental matrix and the forcing function and compute

$$\vec{y}_p(x) = \begin{bmatrix} 2(2x+1)e^{2x} - \frac{39e^{3x}}{8} + e^{4x} + \frac{(2x^2+6x+15)e^x}{8} \\ 8(1+x)e^{2x} - \frac{117e^{3x}}{8} + 4e^{4x} + \frac{(2x^2+10x+21)e^x}{8} \\ 8(3+2x)e^{2x} - \frac{351e^{3x}}{8} + 16e^{4x} + \frac{(2x^2+14x+31)e^x}{8} \end{bmatrix}$$

- Plug particular solution back into general solution

$$\vec{y}(x) = c_1 \vec{y}_1 + c_2 \vec{y}_2 + c_3 \vec{y}_3 + \begin{bmatrix} 2(2x+1)e^{2x} - \frac{39e^{3x}}{8} + e^{4x} + \frac{(2x^2+6x+15)e^x}{8} \\ 8(1+x)e^{2x} - \frac{117e^{3x}}{8} + 4e^{4x} + \frac{(2x^2+10x+21)e^x}{8} \\ 8(3+2x)e^{2x} - \frac{351e^{3x}}{8} + 16e^{4x} + \frac{(2x^2+14x+31)e^x}{8} \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y = \frac{(8+16x+c_2)e^{2x}}{4} + \frac{(8c_3-351)e^{3x}}{72} + e^{4x} + \frac{(2x^2+8c_1+6x+15)e^x}{8}$$

Maple trace

```
`Methods for third order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
trying differential order: 3; linear nonhomogeneous with symmetry [0,1]  
trying high order linear exact nonhomogeneous  
trying differential order: 3; missing the dependent variable  
checking if the LODE has constant coefficients  
<- constant coefficients successful`
```

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 42

```
dsolve(diff(y(x),x$3)-6*diff(y(x),x$2)+11*diff(y(x),x)-6*y(x)=x*exp(x)-4*exp(2*x)+6*exp(4*x)
```

$$y(x) = (4x + c_2)e^{2x} + c_3e^{3x} + e^{4x} + \frac{(2x^2 + 8c_1 + 6x + 7)e^x}{8}$$

✓ Solution by Mathematica

Time used: 0.074 (sec). Leaf size: 53

```
DSolve[y'''[x]-6*y''[x]+11*y'[x]-6*y[x]==x*Exp[x]-4*Exp[2*x]+6*Exp[4*x],y[x],x,IncludeSingular
```

$$y(x) \rightarrow \frac{1}{8}e^x(2x^2 + 6x + 8e^{3x} + 8e^x(4x + c_2) + 8c_3e^{2x} + 7 + 8c_1)$$

11.20 problem 20

11.20.1 Maple step by step solution 2439

Internal problem ID [11794]

Internal file name [OUTPUT/11803_Thursday_April_11_2024_08_49_48_PM_81427022/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 20.

ODE order: 3.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

[[_3rd_order , _linear , _nonhomogeneous]]

$$y''' - 4y'' + 5y' - 2y = 3x^2e^x - 7e^x$$

This is higher order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE And y_p is a particular solution to the nonhomogeneous ODE. y_h is the solution to

$$y''' - 4y'' + 5y' - 2y = 0$$

The characteristic equation is

$$\lambda^3 - 4\lambda^2 + 5\lambda - 2 = 0$$

The roots of the above equation are

$$\lambda_1 = 2$$

$$\lambda_2 = 1$$

$$\lambda_3 = 1$$

Therefore the homogeneous solution is

$$y_h(x) = e^x c_1 + c_2 x e^x + e^{2x} c_3$$

The fundamental set of solutions for the homogeneous solution are the following

$$y_1 = e^x$$

$$y_2 = x e^x$$

$$y_3 = e^{2x}$$

Now the particular solution to the given ODE is found

$$y''' - 4y'' + 5y' - 2y = 3x^2 e^x - 7e^x$$

The particular solution is found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$3x^2 e^x - 7e^x$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[x e^x, x^2 e^x, e^x]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{x e^x, e^x, e^{2x}\}$$

Since e^x is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[x e^x, x^2 e^x, x^3 e^x]$$

Since $x e^x$ is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[x^2 e^x, x^3 e^x, e^x x^4]$$

Since there was duplication between the basis functions in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis function in the above updated UC_set.

$$y_p = A_1 x^2 e^x + A_2 x^3 e^x + A_3 e^x x^4$$

The unknowns $\{A_1, A_2, A_3\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$-6A_2x e^x - 12A_3e^x x^2 + 24A_3e^x x + 6A_2e^x - 2A_1e^x = 3x^2e^x - 7e^x$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = \frac{1}{2}, A_2 = -1, A_3 = -\frac{1}{4} \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = \frac{x^2e^x}{2} - x^3e^x - \frac{e^xx^4}{4}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (e^x c_1 + c_2x e^x + e^{2x} c_3) + \left(\frac{x^2e^x}{2} - x^3e^x - \frac{e^xx^4}{4} \right) \end{aligned}$$

Which simplifies to

$$y = e^{2x} c_3 + e^x(c_2x + c_1) + \frac{x^2e^x}{2} - x^3e^x - \frac{e^xx^4}{4}$$

Summary

The solution(s) found are the following

$$y = e^{2x} c_3 + e^x(c_2x + c_1) + \frac{x^2e^x}{2} - x^3e^x - \frac{e^xx^4}{4} \quad (1)$$

Verification of solutions

$$y = e^{2x} c_3 + e^x(c_2x + c_1) + \frac{x^2e^x}{2} - x^3e^x - \frac{e^xx^4}{4}$$

Verified OK.

11.20.1 Maple step by step solution

Let's solve

$$y''' - 4y'' + 5y' - 2y = 3x^2e^x - 7e^x$$

- Highest derivative means the order of the ODE is 3

$$y'''$$

- Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(x)$

$$y_1(x) = y$$

- Define new variable $y_2(x)$

$$y_2(x) = y'$$

- Define new variable $y_3(x)$

$$y_3(x) = y''$$

- Isolate for $y_3'(x)$ using original ODE

$$y_3'(x) = 3x^2e^x + 4y_3(x) - 5y_2(x) + 2y_1(x) - 7e^x$$

Convert linear ODE into a system of first order ODEs

$$[y_2(x) = y_1'(x), y_3(x) = y_2'(x), y_3'(x) = 3x^2e^x + 4y_3(x) - 5y_2(x) + 2y_1(x) - 7e^x]$$

- Define vector

$$\vec{y}(x) = \begin{bmatrix} y_1(x) \\ y_2(x) \\ y_3(x) \end{bmatrix}$$

- System to solve

$$\vec{y}'(x) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 2 & -5 & 4 \end{bmatrix} \cdot \vec{y}(x) + \begin{bmatrix} 0 \\ 0 \\ 3x^2e^x - 7e^x \end{bmatrix}$$

- Define the forcing function

$$\vec{f}(x) = \begin{bmatrix} 0 \\ 0 \\ 3x^2e^x - 7e^x \end{bmatrix}$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 2 & -5 & 4 \end{bmatrix}$$

- Rewrite the system as

$$\vec{y}'(x) = A \cdot \vec{y}(x) + \vec{f}$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[1, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right], \left[1, \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \right], \left[2, \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair, with eigenvalue of algebraic multiplicity 2

$$\left[1, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right]$$

- First solution from eigenvalue 1

$$\vec{y}_1(x) = e^x \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

- Form of the 2nd homogeneous solution where \vec{p} is to be solved for, $\lambda = 1$ is the eigenvalue, and

$$\vec{y}_2(x) = e^{\lambda x} (x\vec{v} + \vec{p})$$

- Note that the x multiplying \vec{v} makes this solution linearly independent to the 1st solution obtained

- Substitute $\vec{y}_2(x)$ into the homogeneous system

$$\lambda e^{\lambda x} (x\vec{v} + \vec{p}) + e^{\lambda x} \vec{v} = (e^{\lambda x} A) \cdot (x\vec{v} + \vec{p})$$

- Use the fact that \vec{v} is an eigenvector of A

$$\lambda e^{\lambda x} (x\vec{v} + \vec{p}) + e^{\lambda x} \vec{v} = e^{\lambda x} (\lambda x\vec{v} + A \cdot \vec{p})$$

- Simplify equation

$$\lambda \vec{p} + \vec{v} = A \cdot \vec{p}$$

- Make use of the identity matrix I

$$(\lambda \cdot I) \cdot \vec{p} + \vec{v} = A \cdot \vec{p}$$

- Condition \vec{p} must meet for $\vec{y}_2(x)$ to be a solution to the homogeneous system

$$(A - \lambda \cdot I) \cdot \vec{p} = \vec{v}$$

- Choose \vec{p} to use in the second solution to the homogeneous system from eigenvalue 1

$$\left(\begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 2 & -5 & 4 \end{bmatrix} - 1 \cdot \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \cdot \vec{p} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

- Choice of \vec{p}

$$\vec{p} = \begin{bmatrix} -1 \\ 0 \\ 0 \end{bmatrix}$$

- Second solution from eigenvalue 1

$$\vec{y}_2(x) = e^x \cdot \left(x \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + \begin{bmatrix} -1 \\ 0 \\ 0 \end{bmatrix} \right)$$

- Consider eigenpair

$$\left[2, \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_3 = e^{2x} \cdot \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix}$$

- General solution of the system of ODEs can be written in terms of the particular solution $\vec{y}_p(x)$

$$\vec{y}(x) = c_1 \vec{y}_1(x) + c_2 \vec{y}_2(x) + c_3 \vec{y}_3 + \vec{y}_p(x)$$

- Fundamental matrix

- Let $\phi(x)$ be the matrix whose columns are the independent solutions of the homogeneous system

$$\phi(x) = \begin{bmatrix} e^x & e^x(x-1) & \frac{e^{2x}}{4} \\ e^x & x e^x & \frac{e^{2x}}{2} \\ e^x & x e^x & e^{2x} \end{bmatrix}$$

- The fundamental matrix, $\Phi(x)$ is a normalized version of $\phi(x)$ satisfying $\Phi(0) = I$ where I is the identity matrix. $\Phi(x) = \phi(x) \cdot \frac{1}{\phi(0)}$

- Substitute the value of $\phi(x)$ and $\phi(0)$

$$\Phi(x) = \begin{bmatrix} e^x & e^x(x-1) & \frac{e^{2x}}{4} \\ e^x & x e^x & \frac{e^{2x}}{2} \\ e^x & x e^x & e^{2x} \end{bmatrix} \cdot \frac{1}{\begin{bmatrix} 1 & -1 & \frac{1}{4} \\ 1 & 0 & \frac{1}{2} \\ 1 & 0 & 1 \end{bmatrix}}$$

- Evaluate and simplify to get the fundamental matrix

$$\Phi(x) = \begin{bmatrix} -e^x(x-1) & -\frac{e^{2x}}{2} + \frac{e^x(3x+1)}{2} & \frac{e^{2x}}{2} + \frac{e^x(-x-1)}{2} \\ -x e^x & 2e^x + \frac{3x e^x}{2} - e^{2x} & -e^x - \frac{x e^x}{2} + e^{2x} \\ -x e^x & 2e^x + \frac{3x e^x}{2} - 2e^{2x} & -e^x - \frac{x e^x}{2} + 2e^{2x} \end{bmatrix}$$

- Find a particular solution of the system of ODEs using variation of parameters

- Let the particular solution be the fundamental matrix multiplied by $\vec{v}(x)$ and solve for $\vec{v}(x)$

$$\vec{y}_p(x) = \Phi(x) \cdot \vec{v}(x)$$

- Take the derivative of the particular solution

$$\vec{y}'_p(x) = \Phi'(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x)$$

- Substitute particular solution and its derivative into the system of ODEs

$$\Phi'(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x) = A \cdot \Phi(x) \cdot \vec{v}(x) + \vec{f}(x)$$

- The fundamental matrix has columns that are solutions to the homogeneous system so its derivative is $A \cdot \Phi(x)$

$$A \cdot \Phi(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x) = A \cdot \Phi(x) \cdot \vec{v}(x) + \vec{f}(x)$$

- Cancel like terms

$$\Phi(x) \cdot \vec{v}'(x) = \vec{f}(x)$$

- Multiply by the inverse of the fundamental matrix

$$\vec{v}'(x) = \frac{1}{\Phi(x)} \cdot \vec{f}(x)$$

- Integrate to solve for $\vec{v}(x)$

$$\vec{v}(x) = \int_0^x \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds$$

- Plug $\vec{v}(x)$ into the equation for the particular solution

$$\vec{y}_p(x) = \Phi(x) \cdot \left(\int_0^x \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds \right)$$

- Plug in the fundamental matrix and the forcing function and compute

$$\vec{y}_p(x) = \begin{bmatrix} -\frac{e^{2x}}{2} + \frac{(-x^4 - 4x^3 + 2x^2 + 4x + 4)e^x}{8} \\ -e^{2x} + \frac{(-x^4 - 8x^3 - 10x^2 + 8x + 8)e^x}{8} \\ -2e^{2x} + \frac{(-x^4 - 8x^3 - 34x^2 - 40x + 16)e^x}{8} \end{bmatrix}$$

- Plug particular solution back into general solution

$$\vec{y}(x) = c_1 \vec{y}_1(x) + c_2 \vec{y}_2(x) + c_3 \vec{y}_3 + \begin{bmatrix} -\frac{e^{2x}}{2} + \frac{(-x^4 - 4x^3 + 2x^2 + 4x + 4)e^x}{8} \\ -e^{2x} + \frac{(-x^4 - 8x^3 - 10x^2 + 8x + 8)e^x}{8} \\ -2e^{2x} + \frac{(-x^4 - 8x^3 - 34x^2 - 40x + 16)e^x}{8} \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y = \frac{(2c_3 - 4)e^{2x}}{8} - \frac{(x^4 + 4x^3 - 2x^2 + (-8c_2 - 4)x - 8c_1 + 8c_2 - 4)e^x}{8}$$

Maple trace

```

`Methods for third order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 3; linear nonhomogeneous with symmetry [0,1]
trying high order linear exact nonhomogeneous
trying differential order: 3; missing the dependent variable
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 34

```
dsolve(diff(y(x),x$3)-4*diff(y(x),x$2)+5*diff(y(x),x)-2*y(x)=3*x^2*exp(x)-7*exp(x),y(x), sin
```

$$y(x) = -\frac{e^x(x^4 + 4x^3 - 4c_2e^x - 4c_3x - 2x^2 - 4c_1)}{4}$$

✓ Solution by Mathematica

Time used: 0.038 (sec). Leaf size: 47

```
DSolve[y'''[x]-4*y''[x]+5*y'[x]-2*y[x]==3*x^2*Exp[x]-7*Exp[x],y[x],x,IncludeSingularSolution
```

$$y(x) \rightarrow \frac{1}{4}e^x(-x^4 - 4x^3 + 2x^2 + 4(1 + c_2)x + 4(c_3e^x + 1 + c_1))$$

11.21 problem 21

11.21.1 Solving as second order linear constant coeff ode	2445
11.21.2 Solving using Kovacic algorithm	2449
11.21.3 Maple step by step solution	2453

Internal problem ID [11795]

Internal file name [OUTPUT/11804_Thursday_April_11_2024_08_49_48_PM_227895/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 21.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' + y = x \sin(x)$$

11.21.1 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = 0, C = 1, f(x) = x \sin(x)$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 0, C = 1$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 1 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 0, C = 1$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{0}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{0^2 - (4)(1)(1)} \\ &= \pm i \end{aligned}$$

Hence

$$\lambda_1 = +i$$

$$\lambda_2 = -i$$

Which simplifies to

$$\lambda_1 = i$$

$$\lambda_2 = -i$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = 0$ and $\beta = 1$. Therefore the final solution, when using Euler relation, can be written as

$$y = e^{\alpha x} (c_1 \cos(\beta x) + c_2 \sin(\beta x))$$

Which becomes

$$y = e^0 (c_1 \cos(x) + c_2 \sin(x))$$

Or

$$y = c_1 \cos(x) + c_2 \sin(x)$$

Therefore the homogeneous solution y_h is

$$y_h = c_1 \cos(x) + c_2 \sin(x)$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$x \sin(x)$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{x \sin(x), \cos(x) x, \cos(x), \sin(x)\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{\cos(x), \sin(x)\}$$

Since $\cos(x)$ is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[\{x \sin(x), \cos(x) x, \cos(x) x^2, \sin(x) x^2\}]$$

Since there was duplication between the basis functions in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis function in the above updated UC_set.

$$y_p = A_1 x \sin(x) + A_2 \cos(x) x + A_3 \cos(x) x^2 + A_4 \sin(x) x^2$$

The unknowns $\{A_1, A_2, A_3, A_4\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$\begin{aligned} 2A_1 \cos(x) - 2A_2 \sin(x) - 4A_3 \sin(x) x + 2A_3 \cos(x) + 4A_4 \cos(x) x + 2A_4 \sin(x) \\ = x \sin(x) \end{aligned}$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = \frac{1}{4}, A_2 = 0, A_3 = -\frac{1}{4}, A_4 = 0 \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = \frac{x \sin(x)}{4} - \frac{\cos(x) x^2}{4}$$

Therefore the general solution is

$$\begin{aligned}y &= y_h + y_p \\ &= (c_1 \cos(x) + c_2 \sin(x)) + \left(\frac{x \sin(x)}{4} - \frac{\cos(x) x^2}{4} \right)\end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 \cos(x) + c_2 \sin(x) + \frac{x \sin(x)}{4} - \frac{\cos(x) x^2}{4} \quad (1)$$

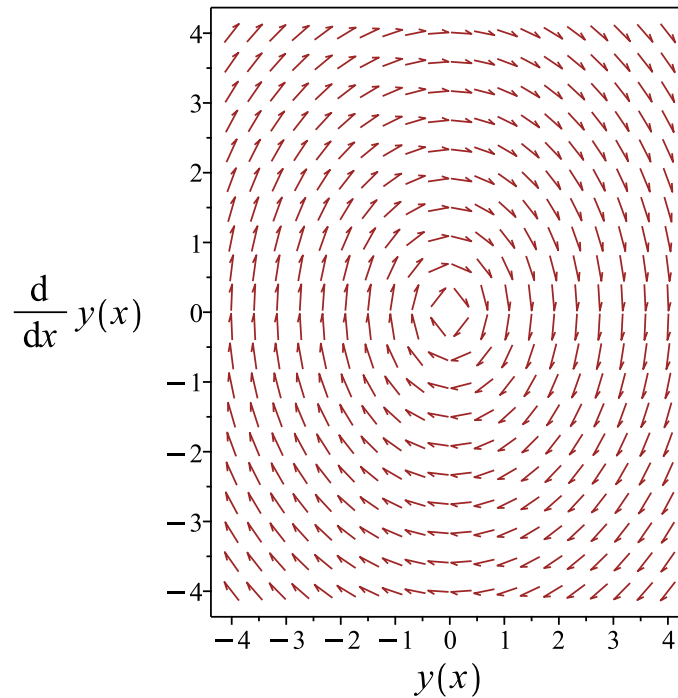


Figure 436: Slope field plot

Verification of solutions

$$y = c_1 \cos(x) + c_2 \sin(x) + \frac{x \sin(x)}{4} - \frac{\cos(x) x^2}{4}$$

Verified OK.

11.21.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' + y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= 0 \\ C &= 1 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-1}{1} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= -1 \\ t &= 1 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = -z(x) \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 374: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = -1$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = \cos(x)$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$y_1 = z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx}$$

Since $B = 0$ then the above reduces to

$$\begin{aligned}y_1 &= z_1 \\ &= \cos(x)\end{aligned}$$

Which simplifies to

$$y_1 = \cos(x)$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Since $B = 0$ then the above becomes

$$\begin{aligned}y_2 &= y_1 \int \frac{1}{y_1^2} dx \\ &= \cos(x) \int \frac{1}{\cos(x)^2} dx \\ &= \cos(x) (\tan(x))\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (\cos(x)) + c_2 (\cos(x) (\tan(x)))\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1 \cos(x) + c_2 \sin(x)$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$x \sin(x)$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{x \sin(x), \cos(x)x, \cos(x), \sin(x)\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{\cos(x), \sin(x)\}$$

Since $\cos(x)$ is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[\{x \sin(x), \cos(x)x, \cos(x)x^2, \sin(x)x^2\}]$$

Since there was duplication between the basis functions in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis function in the above updated UC_set.

$$y_p = A_1 x \sin(x) + A_2 \cos(x)x + A_3 \cos(x)x^2 + A_4 \sin(x)x^2$$

The unknowns $\{A_1, A_2, A_3, A_4\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$\begin{aligned} 2A_1 \cos(x) - 2A_2 \sin(x) - 4A_3 \sin(x)x + 2A_3 \cos(x) + 4A_4 \cos(x)x + 2A_4 \sin(x) \\ = x \sin(x) \end{aligned}$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = \frac{1}{4}, A_2 = 0, A_3 = -\frac{1}{4}, A_4 = 0 \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = \frac{x \sin(x)}{4} - \frac{\cos(x)x^2}{4}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 \cos(x) + c_2 \sin(x)) + \left(\frac{x \sin(x)}{4} - \frac{\cos(x)x^2}{4} \right) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 \cos(x) + c_2 \sin(x) + \frac{x \sin(x)}{4} - \frac{\cos(x) x^2}{4} \quad (1)$$

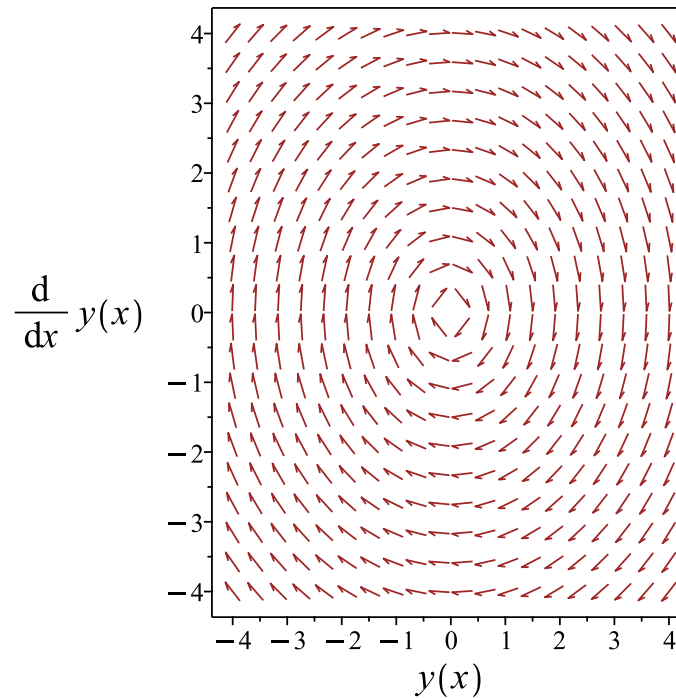


Figure 437: Slope field plot

Verification of solutions

$$y = c_1 \cos(x) + c_2 \sin(x) + \frac{x \sin(x)}{4} - \frac{\cos(x) x^2}{4}$$

Verified OK.

11.21.3 Maple step by step solution

Let's solve

$$y'' + y = x \sin(x)$$

- Highest derivative means the order of the ODE is 2
- y''
- Characteristic polynomial of homogeneous ODE

$$r^2 + 1 = 0$$

- Use quadratic formula to solve for r

$$r = \frac{0 \pm (\sqrt{-4})}{2}$$

- Roots of the characteristic polynomial

$$r = (-I, I)$$

- 1st solution of the homogeneous ODE

$$y_1(x) = \cos(x)$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = \sin(x)$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = c_1 \cos(x) + c_2 \sin(x) + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x), y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x), y_2(x))} dx \right), f(x) = x \sin(x) \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} \cos(x) & \sin(x) \\ -\sin(x) & \cos(x) \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = 1$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = -\cos(x) \left(\int \sin(x)^2 x dx \right) + \frac{\sin(x) \left(\int \sin(2x) x dx \right)}{2}$$

- Compute integrals

$$y_p(x) = \frac{x(-\cos(x)x + \sin(x))}{4}$$

- Substitute particular solution into general solution to ODE

$$y = c_1 \cos(x) + c_2 \sin(x) + \frac{x(-\cos(x)x + \sin(x))}{4}$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]  
trying a double symmetry of the form [xi=0, eta=F(x)]  
-> Try solving first the homogeneous part of the ODE  
    checking if the LODE has constant coefficients  
    <- constant coefficients successful  
<- solving first the homogeneous part of the ODE successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 27

```
dsolve(diff(y(x),x$2)+y(x)=x*sin(x),y(x), singsol=all)
```

$$y(x) = \frac{(-x^2 + 4c_1) \cos(x)}{4} + \frac{\sin(x)(4c_2 + x)}{4}$$

✓ Solution by Mathematica

Time used: 0.046 (sec). Leaf size: 34

```
DSolve[y''[x]+y[x]==x*Sin[x],y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{1}{8}((-2x^2 + 1 + 8c_1) \cos(x) + 2(x + 4c_2) \sin(x))$$

11.22 problem 22

11.22.1 Solving as second order linear constant coeff ode	2456
11.22.2 Solving using Kovacic algorithm	2460
11.22.3 Maple step by step solution	2465

Internal problem ID [11796]

Internal file name [OUTPUT/11805_Thursday_April_11_2024_08_49_49_PM_63250674/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 22.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' + 4y = 12x^2 - 16x \cos(2x)$$

11.22.1 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = 0, C = 4, f(x) = 12x^2 - 16x \cos(2x)$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 4y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 0, C = 4$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + 4 e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 4 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 0, C = 4$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{0}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{0^2 - (4)(1)(4)} \\ &= \pm 2i \end{aligned}$$

Hence

$$\lambda_1 = +2i$$

$$\lambda_2 = -2i$$

Which simplifies to

$$\lambda_1 = 2i$$

$$\lambda_2 = -2i$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = 0$ and $\beta = 2$. Therefore the final solution, when using Euler relation, can be written as

$$y = e^{\alpha x} (c_1 \cos(\beta x) + c_2 \sin(\beta x))$$

Which becomes

$$y = e^0 (c_1 \cos(2x) + c_2 \sin(2x))$$

Or

$$y = c_1 \cos(2x) + c_2 \sin(2x)$$

Therefore the homogeneous solution y_h is

$$y_h = c_1 \cos(2x) + c_2 \sin(2x)$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$12x^2 - 16x \cos(2x)$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{1, x, x^2\}, \{x \cos(2x), \sin(2x)x, \cos(2x), \sin(2x)\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{\cos(2x), \sin(2x)\}$$

Since $\cos(2x)$ is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[\{1, x, x^2\}, \{x \cos(2x), x^2 \cos(2x), x^2 \sin(2x), \sin(2x)x\}]$$

Since there was duplication between the basis functions in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis function in the above updated UC_set.

$$y_p = A_3x^2 + A_2x + A_1 + A_4x \cos(2x) + A_5x^2 \cos(2x) + A_6x^2 \sin(2x) + A_7 \sin(2x)x$$

The unknowns $\{A_1, A_2, A_3, A_4, A_5, A_6, A_7\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$2A_3 - 4A_4 \sin(2x) + 2A_5 \cos(2x) - 8A_5x \sin(2x) + 2A_6 \sin(2x) + 8A_6x \cos(2x) + 4A_7 \cos(2x) + 4A_3x^2 + 4A_2x + 4A_1 = 12x^2 - 16x \cos(2x)$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = -\frac{3}{2}, A_2 = 0, A_3 = 3, A_4 = -1, A_5 = 0, A_6 = -2, A_7 = 0 \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = 3x^2 - \frac{3}{2} - x \cos(2x) - 2x^2 \sin(2x)$$

Therefore the general solution is

$$y = y_h + y_p \\ = (c_1 \cos(2x) + c_2 \sin(2x)) + \left(3x^2 - \frac{3}{2} - x \cos(2x) - 2x^2 \sin(2x) \right)$$

Summary

The solution(s) found are the following

$$y = c_1 \cos(2x) + c_2 \sin(2x) + 3x^2 - \frac{3}{2} - x \cos(2x) - 2x^2 \sin(2x) \quad (1)$$

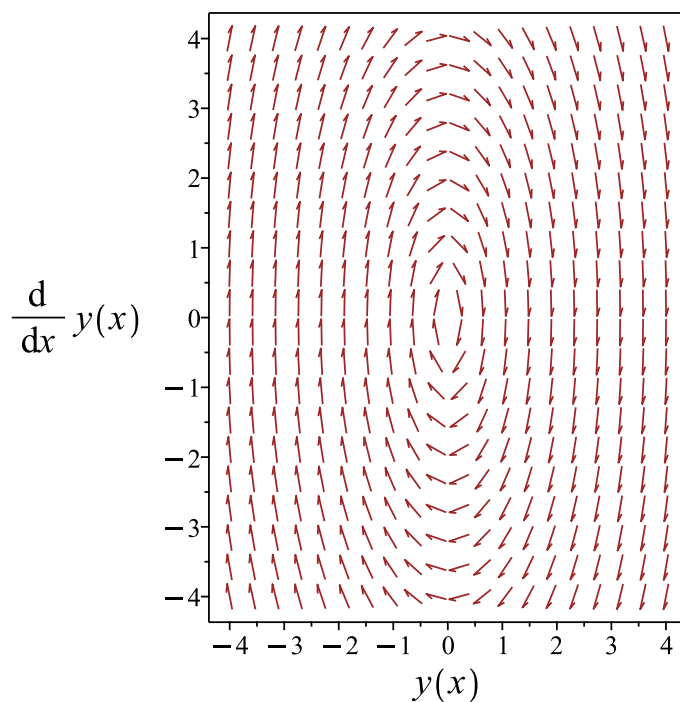


Figure 438: Slope field plot

Verification of solutions

$$y = c_1 \cos(2x) + c_2 \sin(2x) + 3x^2 - \frac{3}{2} - x \cos(2x) - 2x^2 \sin(2x)$$

Verified OK.

11.22.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' + 4y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= 0 \\ C &= 4 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-4}{1} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= -4 \\ t &= 1 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = -4z(x) \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 376: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = -4$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = \cos(2x)$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$y_1 = z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx}$$

Since $B = 0$ then the above reduces to

$$\begin{aligned}y_1 &= z_1 \\ &= \cos(2x)\end{aligned}$$

Which simplifies to

$$y_1 = \cos(2x)$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Since $B = 0$ then the above becomes

$$\begin{aligned}y_2 &= y_1 \int \frac{1}{y_1^2} dx \\ &= \cos(2x) \int \frac{1}{\cos(2x)^2} dx \\ &= \cos(2x) \left(\frac{\tan(2x)}{2} \right)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1(\cos(2x)) + c_2 \left(\cos(2x) \left(\frac{\tan(2x)}{2} \right) \right)\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$.
 y_h is the solution to

$$y'' + 4y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1 \cos(2x) + \frac{c_2 \sin(2x)}{2}$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$12x^2 - 16x \cos(2x)$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{1, x, x^2\}, \{x \cos(2x), \sin(2x)x, \cos(2x), \sin(2x)\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\left\{ \frac{\sin(2x)}{2}, \cos(2x) \right\}$$

Since $\cos(2x)$ is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[\{1, x, x^2\}, \{x \cos(2x), x^2 \cos(2x), x^2 \sin(2x), \sin(2x)x\}]$$

Since there was duplication between the basis functions in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis function in the above updated UC_set.

$$y_p = A_3 x^2 + A_2 x + A_1 + A_4 x \cos(2x) + A_5 x^2 \cos(2x) + A_6 x^2 \sin(2x) + A_7 \sin(2x)x$$

The unknowns $\{A_1, A_2, A_3, A_4, A_5, A_6, A_7\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$2A_3 - 4A_4 \sin(2x) + 2A_5 \cos(2x) - 8A_5 x \sin(2x) + 2A_6 \sin(2x) + 8A_6 x \cos(2x) + 4A_7 \cos(2x) + 4A_3 x^2 + 4A_2 x + 4A_1 = 12x^2 - 16x \cos(2x)$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = -\frac{3}{2}, A_2 = 0, A_3 = 3, A_4 = -1, A_5 = 0, A_6 = -2, A_7 = 0 \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = 3x^2 - \frac{3}{2} - x \cos(2x) - 2x^2 \sin(2x)$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(c_1 \cos(2x) + \frac{c_2 \sin(2x)}{2} \right) + \left(3x^2 - \frac{3}{2} - x \cos(2x) - 2x^2 \sin(2x) \right) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 \cos(2x) + \frac{c_2 \sin(2x)}{2} + 3x^2 - \frac{3}{2} - x \cos(2x) - 2x^2 \sin(2x) \quad (1)$$

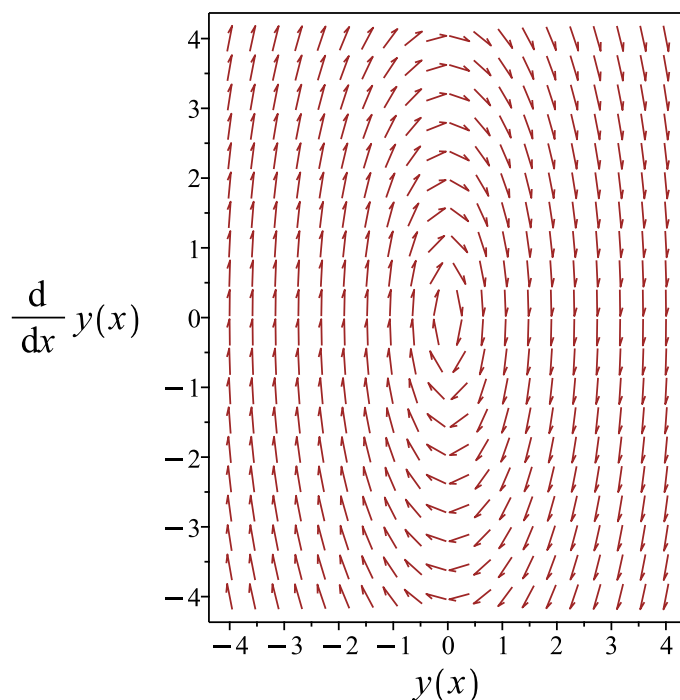


Figure 439: Slope field plot

Verification of solutions

$$y = c_1 \cos(2x) + \frac{c_2 \sin(2x)}{2} + 3x^2 - \frac{3}{2} - x \cos(2x) - 2x^2 \sin(2x)$$

Verified OK.

11.22.3 Maple step by step solution

Let's solve

$$y'' + 4y = 12x^2 - 16x \cos(2x)$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of homogeneous ODE

$$r^2 + 4 = 0$$

- Use quadratic formula to solve for r

$$r = \frac{0 \pm (\sqrt{-16})}{2}$$

- Roots of the characteristic polynomial

$$r = (-2i, 2i)$$

- 1st solution of the homogeneous ODE

$$y_1(x) = \cos(2x)$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = \sin(2x)$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = c_1 \cos(2x) + c_2 \sin(2x) + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = 12x^2 - 16x \cos(2x) \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} \cos(2x) & \sin(2x) \\ -2 \sin(2x) & 2 \cos(2x) \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = 2$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = 2 \cos(2x) \left(\int \sin(2x) x(4 \cos(2x) - 3x) dx \right) - 2 \sin(2x) \left(\int \cos(2x) x(4 \cos(2x) - 3x) dx \right)$$

- Compute integrals

$$y_p(x) = -2x^2 \sin(2x) + \frac{\sin(2x)}{2} - x \cos(2x) + 3x^2 - \frac{3}{2}$$

- Substitute particular solution into general solution to ODE

$$y = c_1 \cos(2x) + c_2 \sin(2x) - 2x^2 \sin(2x) + \frac{\sin(2x)}{2} - x \cos(2x) + 3x^2 - \frac{3}{2}$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
trying a double symmetry of the form [xi=0, eta=F(x)]
-> Try solving first the homogeneous part of the ODE
    checking if the LODE has constant coefficients
    <- constant coefficients successful
<- solving first the homogeneous part of the ODE successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 37

```
dsolve(diff(y(x),x$2)+4*y(x)=12*x^2-16*x*cos(2*x),y(x), singsol=all)
```

$$y(x) = -\frac{3}{2} + \frac{(-8x^2 + 4c_2 + 1) \sin(2x)}{4} + (c_1 - x) \cos(2x) + 3x^2$$

✓ Solution by Mathematica

Time used: 0.251 (sec). Leaf size: 44

```
DSolve[y''[x]+4*y[x]==12*x^2-16*x*Cos[2*x],y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow 3x^2 + \frac{1}{4}(-8x^2 + 1 + 4c_2) \sin(2x) + (-x + c_1) \cos(2x) - \frac{3}{2}$$

11.23 problem 23

Internal problem ID [11797]

Internal file name [OUTPUT/11806_Thursday_April_11_2024_08_49_50_PM_86836542/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 23.

ODE order: 4.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_high_order , _missing_y]]
```

$$y'''' + 2y''' - 3y'' = 18x^2 + 16xe^x + 4e^{3x} - 9$$

This is higher order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE And y_p is a particular solution to the nonhomogeneous ODE. y_h is the solution to

$$y'''' + 2y''' - 3y'' = 0$$

The characteristic equation is

$$\lambda^4 + 2\lambda^3 - 3\lambda^2 = 0$$

The roots of the above equation are

$$\lambda_1 = 0$$

$$\lambda_2 = 0$$

$$\lambda_3 = 1$$

$$\lambda_4 = -3$$

Therefore the homogeneous solution is

$$y_h(x) = c_2x + c_1 + c_3e^x + e^{-3x}c_4$$

The fundamental set of solutions for the homogeneous solution are the following

$$y_1 = 1$$

$$y_2 = x$$

$$y_3 = e^x$$

$$y_4 = e^{-3x}$$

Now the particular solution to the given ODE is found

$$y'''' + 2y''' - 3y'' = 18x^2 + 16xe^x + 4e^{3x} - 9$$

The particular solution is found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$18x^2 + 16xe^x + 4e^{3x} - 9$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{e^{3x}\}, \{xe^x, e^x\}, \{1, x, x^2\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{1, x, e^x, e^{-3x}\}$$

Since 1 is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[\{e^{3x}\}, \{xe^x, e^x\}, \{x, x^2, x^3\}]$$

Since x is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[\{e^{3x}\}, \{xe^x, e^x\}, \{x^2, x^3, x^4\}]$$

Since e^x is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[\{e^{3x}\}, \{xe^x, x^2e^x\}, \{x^2, x^3, x^4\}]$$

Since there was duplication between the basis functions in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis function in the above updated UC_set.

$$y_p = A_1 e^{3x} + A_2 x e^x + A_3 x^2 e^x + A_4 x^2 + A_5 x^3 + A_6 x^4$$

The unknowns $\{A_1, A_2, A_3, A_4, A_5, A_6\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$108A_1 e^{3x} + 4A_2 e^x + 18A_3 e^x + 8A_3 x e^x + 24A_6 + 12A_5 + 48A_6 x - 6A_4 - 18A_5 x - 36A_6 x^2 = 18x^2 + 16x e^x + 4e^{3x} - 9$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = \frac{1}{27}, A_2 = -9, A_3 = 2, A_4 = -\frac{19}{6}, A_5 = -\frac{4}{3}, A_6 = -\frac{1}{2} \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = \frac{e^{3x}}{27} - 9x e^x + 2x^2 e^x - \frac{19x^2}{6} - \frac{4x^3}{3} - \frac{x^4}{2}$$

Therefore the general solution is

$$y = y_h + y_p = (c_2 x + c_1 + c_3 e^x + e^{-3x} c_4) + \left(\frac{e^{3x}}{27} - 9x e^x + 2x^2 e^x - \frac{19x^2}{6} - \frac{4x^3}{3} - \frac{x^4}{2} \right)$$

Summary

The solution(s) found are the following

$$y = c_2 x + c_1 + c_3 e^x + e^{-3x} c_4 + \frac{e^{3x}}{27} - 9x e^x + 2x^2 e^x - \frac{19x^2}{6} - \frac{4x^3}{3} - \frac{x^4}{2} \quad (1)$$

Verification of solutions

$$y = c_2 x + c_1 + c_3 e^x + e^{-3x} c_4 + \frac{e^{3x}}{27} - 9x e^x + 2x^2 e^x - \frac{19x^2}{6} - \frac{4x^3}{3} - \frac{x^4}{2}$$

Verified OK.

Maple trace

```
`Methods for high order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 4; linear nonhomogeneous with symmetry [0,1]
-> Calling odsolve with the ODE`, diff(diff(_b(_a), _a), _a) = 16*_a*exp(_a)+18*_a^2-2*(diff
  Methods for second order ODEs:
  --- Trying classification methods ---
  trying a quadrature
  trying high order exact linear fully integrable
  trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
  trying a double symmetry of the form [xi=0, eta=F(x)]
  -> Try solving first the homogeneous part of the ODE
    checking if the LODE has constant coefficients
    <- constant coefficients successful
    <- solving first the homogeneous part of the ODE successful
  <- differential order: 4; linear nonhomogeneous with symmetry [0,1] successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 64

```
dsolve(diff(y(x),x$4)+2*diff(y(x),x$3)-3*diff(y(x),x$2)=18*x^2+16*x*exp(x)+4*exp(3*x)-9,y(x)
```

$$y(x) = \frac{\left((x^4 + \frac{8}{3}x^3 + \frac{19}{3}x^2 - 2c_3x - 2c_4) e^{3x} + (-4x^2 + 18x - 2c_2 - \frac{57}{2}) e^{4x} - \frac{2c_1}{9} - \frac{2e^{6x}}{27} \right) e^{-3x}}{2}$$

✓ Solution by Mathematica

Time used: 1.232 (sec). Leaf size: 70

```
DSolve[y''''[x]+2*y'''[x]-3*y''[x]==18*x^2+16*x*Exp[x]+4*Exp[3*x]-9,y[x],x,IncludeSingularSo
```

$$y(x) \rightarrow -\frac{1}{6}(3x^2 + 8x + 19)x^2 + \frac{1}{4}e^x(8x^2 - 36x + 57 + 4c_2) + \frac{e^{3x}}{27} + c_4x + \frac{1}{9}c_1e^{-3x} + c_3$$

11.24 problem 24

11.24.1 Maple step by step solution 2476

Internal problem ID [11798]

Internal file name [OUTPUT/11807_Thursday_April_11_2024_08_49_50_PM_12791522/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 24.

ODE order: 4.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_high_order , _linear , _nonhomogeneous]]
```

$$y'''' - 5y''' + 7y'' - 5y' + 6y = 5 \sin(x) - 12 \sin(2x)$$

This is higher order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE And y_p is a particular solution to the nonhomogeneous ODE. y_h is the solution to

$$y'''' - 5y''' + 7y'' - 5y' + 6y = 0$$

The characteristic equation is

$$\lambda^4 - 5\lambda^3 + 7\lambda^2 - 5\lambda + 6 = 0$$

The roots of the above equation are

$$\lambda_1 = 2$$

$$\lambda_2 = 3$$

$$\lambda_3 = i$$

$$\lambda_4 = -i$$

Therefore the homogeneous solution is

$$y_h(x) = c_1 e^{2x} + e^{3x} c_2 + e^{ix} c_3 + e^{-ix} c_4$$

The fundamental set of solutions for the homogeneous solution are the following

$$y_1 = e^{2x}$$

$$y_2 = e^{3x}$$

$$y_3 = e^{ix}$$

$$y_4 = e^{-ix}$$

Now the particular solution to the given ODE is found

$$y'''' - 5y'''' + 7y'' - 5y' + 6y = 5 \sin(x) - 12 \sin(2x)$$

Let the particular solution be

$$y_p = U_1 y_1 + U_2 y_2 + U_3 y_3 + U_4 y_4$$

Where y_i are the basis solutions found above for the homogeneous solution y_h and $U_i(x)$ are functions to be determined as follows

$$U_i = (-1)^{n-i} \int \frac{F(x)W_i(x)}{aW(x)} dx$$

Where $W(x)$ is the Wronskian and $W_i(x)$ is the Wronskian that results after deleting the last row and the i -th column of the determinant and n is the order of the ODE or equivalently, the number of basis solutions, and a is the coefficient of the leading derivative in the ODE, and $F(x)$ is the RHS of the ODE. Therefore, the first step is to find the Wronskian $W(x)$. This is given by

$$W(x) = \begin{vmatrix} y_1 & y_2 & y_3 & y_4 \\ y_1' & y_2' & y_3' & y_4' \\ y_1'' & y_2'' & y_3'' & y_4'' \\ y_1''' & y_2''' & y_3''' & y_4''' \end{vmatrix}$$

Substituting the fundamental set of solutions y_i found above in the Wronskian gives

$$W = \begin{bmatrix} e^{2x} & e^{3x} & e^{ix} & e^{-ix} \\ 2e^{2x} & 3e^{3x} & ie^{ix} & -ie^{-ix} \\ 4e^{2x} & 9e^{3x} & -e^{ix} & -e^{-ix} \\ 8e^{2x} & 27e^{3x} & -ie^{ix} & ie^{-ix} \end{bmatrix}$$

$$|W| = -100ie^{2x}e^{3x}e^{ix}e^{-ix}$$

The determinant simplifies to

$$|W| = -100ie^{5x}$$

Now we determine W_i for each U_i .

$$\begin{aligned} W_1(x) &= \det \begin{bmatrix} e^{3x} & e^{ix} & e^{-ix} \\ 3e^{3x} & ie^{ix} & -ie^{-ix} \\ 9e^{3x} & -e^{ix} & -e^{-ix} \end{bmatrix} \\ &= -20ie^{3x} \end{aligned}$$

$$\begin{aligned} W_2(x) &= \det \begin{bmatrix} e^{2x} & e^{ix} & e^{-ix} \\ 2e^{2x} & ie^{ix} & -ie^{-ix} \\ 4e^{2x} & -e^{ix} & -e^{-ix} \end{bmatrix} \\ &= -10ie^{2x} \end{aligned}$$

$$\begin{aligned} W_3(x) &= \det \begin{bmatrix} e^{2x} & e^{3x} & e^{-ix} \\ 2e^{2x} & 3e^{3x} & -ie^{-ix} \\ 4e^{2x} & 9e^{3x} & -e^{-ix} \end{bmatrix} \\ &= (5 + 5i)e^{(5-i)x} \end{aligned}$$

$$\begin{aligned} W_4(x) &= \det \begin{bmatrix} e^{2x} & e^{3x} & e^{ix} \\ 2e^{2x} & 3e^{3x} & ie^{ix} \\ 4e^{2x} & 9e^{3x} & -e^{ix} \end{bmatrix} \\ &= (5 - 5i)e^{(5+i)x} \end{aligned}$$

Now we are ready to evaluate each $U_i(x)$.

$$\begin{aligned}
 U_1 &= (-1)^{4-1} \int \frac{F(x)W_1(x)}{aW(x)} dx \\
 &= (-1)^3 \int \frac{(5 \sin(x) - 12 \sin(2x))(-20ie^{3x})}{(1)(-100ie^{5x})} dx \\
 &= - \int \frac{-20i(5 \sin(x) - 12 \sin(2x)) e^{3x}}{-100ie^{5x}} dx \\
 &= - \int \left(-\frac{(-5 \sin(x) + 12 \sin(2x)) e^{-2x}}{5} \right) dx \\
 &= \frac{3e^{-2x}(-2 \sin(2x) - 2 \cos(2x))}{10} + \frac{\cos(x) e^{-2x}}{5} + \frac{2e^{-2x} \sin(x)}{5} \\
 &= \frac{3e^{-2x}(-2 \sin(2x) - 2 \cos(2x))}{10} + \frac{\cos(x) e^{-2x}}{5} + \frac{2e^{-2x} \sin(x)}{5}
 \end{aligned}$$

$$\begin{aligned}
 U_2 &= (-1)^{4-2} \int \frac{F(x)W_2(x)}{aW(x)} dx \\
 &= (-1)^2 \int \frac{(5 \sin(x) - 12 \sin(2x))(-10ie^{2x})}{(1)(-100ie^{5x})} dx \\
 &= \int \frac{-10i(5 \sin(x) - 12 \sin(2x)) e^{2x}}{-100ie^{5x}} dx \\
 &= \int \left(-\frac{(-5 \sin(x) + 12 \sin(2x)) e^{-3x}}{10} \right) dx \\
 &= -\frac{6e^{-3x}(-3 \sin(2x) - 2 \cos(2x))}{65} - \frac{e^{-3x} \cos(x)}{20} - \frac{3e^{-3x} \sin(x)}{20} \\
 &= -\frac{6e^{-3x}(-3 \sin(2x) - 2 \cos(2x))}{65} - \frac{e^{-3x} \cos(x)}{20} - \frac{3e^{-3x} \sin(x)}{20}
 \end{aligned}$$

$$\begin{aligned}
 U_3 &= (-1)^{4-3} \int \frac{F(x)W_3(x)}{aW(x)} dx \\
 &= (-1)^1 \int \frac{(5 \sin(x) - 12 \sin(2x))((5 + 5i) e^{(5-i)x})}{(1)(-100ie^{5x})} dx \\
 &= - \int \frac{(5 + 5i)(5 \sin(x) - 12 \sin(2x)) e^{(5-i)x}}{-100ie^{5x}} dx \\
 &= - \int \left(\left(\frac{1}{20} - \frac{i}{20} \right) (-5 \sin(x) + 12 \sin(2x)) e^{-ix} \right) dx \\
 &= - \left(\int \left(\frac{1}{20} - \frac{i}{20} \right) (-5 \sin(x) + 12 \sin(2x)) e^{-ix} dx \right)
 \end{aligned}$$

$$\begin{aligned}
U_4 &= (-1)^{4-4} \int \frac{F(x)W_4(x)}{aW(x)} dx \\
&= (-1)^0 \int \frac{(5 \sin(x) - 12 \sin(2x)) ((5 - 5i) e^{(5+i)x})}{(1) (-100ie^{5x})} dx \\
&= \int \frac{(5 - 5i) (5 \sin(x) - 12 \sin(2x)) e^{(5+i)x}}{-100ie^{5x}} dx \\
&= \int \left(\left(-\frac{1}{20} - \frac{i}{20} \right) (-5 \sin(x) + 12 \sin(2x)) e^{ix} \right) dx \\
&= \int \left(-\frac{1}{20} - \frac{i}{20} \right) (-5 \sin(x) + 12 \sin(2x)) e^{ix} dx
\end{aligned}$$

Now that all the U_i functions have been determined, the particular solution is found from

$$y_p = U_1 y_1 + U_2 y_2 + U_3 y_3 + U_4 y_4$$

Hence

$$\begin{aligned}
y_p &= \left(\frac{3 e^{-2x} (-2 \sin(2x) - 2 \cos(2x))}{10} + \frac{\cos(x) e^{-2x}}{5} + \frac{2 e^{-2x} \sin(x)}{5} \right) (e^{2x}) \\
&+ \left(-\frac{6 e^{-3x} (-3 \sin(2x) - 2 \cos(2x))}{65} - \frac{e^{-3x} \cos(x)}{20} - \frac{3 e^{-3x} \sin(x)}{20} \right) (e^{3x}) \\
&+ \left(-\left(\int \left(\frac{1}{20} - \frac{i}{20} \right) (-5 \sin(x) + 12 \sin(2x)) e^{-ix} dx \right) \right) (e^{ix}) \\
&+ \left(\int \left(-\frac{1}{20} - \frac{i}{20} \right) (-5 \sin(x) + 12 \sin(2x)) e^{ix} dx \right) (e^{-ix})
\end{aligned}$$

Therefore the particular solution is

$$y_p = \left(-\frac{1}{20} + \frac{i}{20} \right) \left(\int (-5 \sin(x) + 12 \sin(2x)) e^{-ix} dx \right) e^{ix} + \left(-\frac{1}{20} - \frac{i}{20} \right) \left(\int (-5 \sin(x) + 12 \sin(2x)) e^{ix} dx \right) e^{-ix}$$

Which simplifies to

$$y_p = \frac{27}{65} + \frac{(\cos(x) - \sin(x)) \left(\int (24 \cos(x) - 5) \sin(x)^2 dx \right)}{10} + \frac{(-\cos(x) - \sin(x)) \left(\int (24 \cos(x) - 5) \sin(x)^2 dx \right)}{10}$$

Therefore the general solution is

$$y = y_h + y_p$$

$$\begin{aligned}
&= (c_1 e^{2x} + e^{3x} c_2 + e^{ix} c_3 + e^{-ix} c_4) \\
&+ \left(\frac{27}{65} + \frac{(\cos(x) - \sin(x)) \left(\int (24 \cos(x) - 5) \sin(x)^2 dx \right)}{10} \right. \\
&\quad + \frac{(-\cos(x) - \sin(x)) \left(\int (24 \cos(x) - 5) \sin(x) \cos(x) dx \right)}{10} - \frac{54 \cos(x)^2}{65} \\
&\quad \left. + \frac{3(13 - 56 \sin(x)) \cos(x)}{260} + \frac{\sin(x)}{4} \right)
\end{aligned}$$

Summary

The solution(s) found are the following

$$\begin{aligned}
y &= c_1 e^{2x} + e^{3x} c_2 + e^{ix} c_3 + e^{-ix} c_4 + \frac{27}{65} \\
&\quad + \frac{(\cos(x) - \sin(x)) \left(\int (24 \cos(x) - 5) \sin(x)^2 dx \right)}{10} \\
&\quad + \frac{(-\cos(x) - \sin(x)) \left(\int (24 \cos(x) - 5) \sin(x) \cos(x) dx \right)}{10} \\
&\quad - \frac{54 \cos(x)^2}{65} + \frac{3(13 - 56 \sin(x)) \cos(x)}{260} + \frac{\sin(x)}{4}
\end{aligned} \tag{1}$$

Verification of solutions

$$\begin{aligned}
y &= c_1 e^{2x} + e^{3x} c_2 + e^{ix} c_3 + e^{-ix} c_4 + \frac{27}{65} + \frac{(\cos(x) - \sin(x)) \left(\int (24 \cos(x) - 5) \sin(x)^2 dx \right)}{10} \\
&\quad + \frac{(-\cos(x) - \sin(x)) \left(\int (24 \cos(x) - 5) \sin(x) \cos(x) dx \right)}{10} \\
&\quad - \frac{54 \cos(x)^2}{65} + \frac{3(13 - 56 \sin(x)) \cos(x)}{260} + \frac{\sin(x)}{4}
\end{aligned}$$

Verified OK.

11.24.1 Maple step by step solution

Let's solve

$$y'''' - 5y''' + 7y'' - 5y' + 6y = 5 \sin(x) - 12 \sin(2x)$$

- Highest derivative means the order of the ODE is 4

y''''

- Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(x)$

$$y_1(x) = y$$

- Define new variable $y_2(x)$

$$y_2(x) = y'$$

- Define new variable $y_3(x)$

$$y_3(x) = y''$$

- Define new variable $y_4(x)$

$$y_4(x) = y'''$$

- Isolate for $y_4'(x)$ using original ODE

$$y_4'(x) = 5 \sin(x) - 12 \sin(2x) + 5y_4(x) - 7y_3(x) + 5y_2(x) - 6y_1(x)$$

Convert linear ODE into a system of first order ODEs

$$[y_2(x) = y_1'(x), y_3(x) = y_2'(x), y_4(x) = y_3'(x), y_4'(x) = 5 \sin(x) - 12 \sin(2x) + 5y_4(x) - 7y_3(x) + 5y_2(x) - 6y_1(x)]$$

- Define vector

$$\vec{y}(x) = \begin{bmatrix} y_1(x) \\ y_2(x) \\ y_3(x) \\ y_4(x) \end{bmatrix}$$

- System to solve

$$\vec{y}'(x) = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -6 & 5 & -7 & 5 \end{bmatrix} \cdot \vec{y}(x) + \begin{bmatrix} 0 \\ 0 \\ 0 \\ 5 \sin(x) - 12 \sin(2x) \end{bmatrix}$$

- Define the forcing function

$$\vec{f}(x) = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 5 \sin(x) - 12 \sin(2x) \end{bmatrix}$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -6 & 5 & -7 & 5 \end{bmatrix}$$

- Rewrite the system as

$$\vec{y}'(x) = A \cdot \vec{y}(x) + \vec{f}$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[\begin{bmatrix} \frac{1}{8} \\ \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right], \left[\begin{bmatrix} \frac{1}{27} \\ \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix} \right], \left[-I, \begin{bmatrix} -I \\ -1 \\ I \\ 1 \end{bmatrix} \right], \left[I, \begin{bmatrix} I \\ -1 \\ -I \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[\begin{bmatrix} \frac{1}{8} \\ \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_1 = e^{2x} \cdot \begin{bmatrix} \frac{1}{8} \\ \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[\begin{bmatrix} \frac{1}{27} \\ \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_2 = e^{3x} \cdot \begin{bmatrix} \frac{1}{27} \\ \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix}$$

- Consider complex eigenpair, complex conjugate eigenvalue can be ignored

$$\left[-I, \begin{bmatrix} -I \\ -1 \\ I \\ 1 \end{bmatrix} \right]$$

- Solution from eigenpair

$$e^{-Ix} \cdot \begin{bmatrix} -I \\ -1 \\ I \\ 1 \end{bmatrix}$$

- Use Euler identity to write solution in terms of sin and cos

$$(\cos(x) - I \sin(x)) \cdot \begin{bmatrix} -I \\ -1 \\ I \\ 1 \end{bmatrix}$$

- Simplify expression

$$\begin{bmatrix} -I(\cos(x) - I \sin(x)) \\ -\cos(x) + I \sin(x) \\ I(\cos(x) - I \sin(x)) \\ \cos(x) - I \sin(x) \end{bmatrix}$$

- Both real and imaginary parts are solutions to the homogeneous system

$$\vec{y}_3(x) = \begin{bmatrix} -\sin(x) \\ -\cos(x) \\ \sin(x) \\ \cos(x) \end{bmatrix}, \vec{y}_4(x) = \begin{bmatrix} -\cos(x) \\ \sin(x) \\ \cos(x) \\ -\sin(x) \end{bmatrix}$$

- General solution of the system of ODEs can be written in terms of the particular solution $\vec{y}_p(x)$
 $\vec{y}(x) = c_1 \vec{y}_1 + c_2 \vec{y}_2 + c_3 \vec{y}_3(x) + c_4 \vec{y}_4(x) + \vec{y}_p(x)$

□ Fundamental matrix

- Let $\phi(x)$ be the matrix whose columns are the independent solutions of the homogeneous system

$$\phi(x) = \begin{bmatrix} \frac{e^{2x}}{8} & \frac{e^{3x}}{27} & -\sin(x) & -\cos(x) \\ \frac{e^{2x}}{4} & \frac{e^{3x}}{9} & -\cos(x) & \sin(x) \\ \frac{e^{2x}}{2} & \frac{e^{3x}}{3} & \sin(x) & \cos(x) \\ e^{2x} & e^{3x} & \cos(x) & -\sin(x) \end{bmatrix}$$

- The fundamental matrix, $\Phi(x)$ is a normalized version of $\phi(x)$ satisfying $\Phi(0) = I$ where I is the identity matrix

$$\Phi(x) = \phi(x) \cdot \frac{1}{\phi(0)}$$

- Substitute the value of $\phi(x)$ and $\phi(0)$

$$\Phi(x) = \begin{bmatrix} \frac{e^{2x}}{8} & \frac{e^{3x}}{27} & -\sin(x) & -\cos(x) \\ \frac{e^{2x}}{4} & \frac{e^{3x}}{9} & -\cos(x) & \sin(x) \\ \frac{e^{2x}}{2} & \frac{e^{3x}}{3} & \sin(x) & \cos(x) \\ e^{2x} & e^{3x} & \cos(x) & -\sin(x) \end{bmatrix} \cdot \begin{bmatrix} 1 & & & \\ \frac{1}{8} & \frac{1}{27} & 0 & -1 \\ \frac{1}{4} & \frac{1}{9} & -1 & 0 \\ \frac{1}{2} & \frac{1}{3} & 0 & 1 \\ 1 & 1 & 1 & 0 \end{bmatrix}$$

- Evaluate and simplify to get the fundamental matrix

$$\Phi(x) = \begin{bmatrix} \frac{3e^{2x}}{5} - \frac{e^{3x}}{5} - \frac{3\sin(x)}{5} + \frac{3\cos(x)}{5} & -\frac{e^{2x}}{5} + \frac{e^{3x}}{10} + \frac{11\sin(x)}{10} + \frac{\cos(x)}{10} & \frac{3e^{2x}}{5} - \frac{e^{3x}}{5} - \frac{3\sin(x)}{5} \\ \frac{6e^{2x}}{5} - \frac{3e^{3x}}{5} - \frac{3\cos(x)}{5} - \frac{3\sin(x)}{5} & -\frac{2e^{2x}}{5} + \frac{3e^{3x}}{10} + \frac{11\cos(x)}{10} - \frac{\sin(x)}{10} & \frac{6e^{2x}}{5} - \frac{3e^{3x}}{5} - \frac{3\cos(x)}{5} \\ \frac{12e^{2x}}{5} - \frac{9e^{3x}}{5} + \frac{3\sin(x)}{5} - \frac{3\cos(x)}{5} & -\frac{4e^{2x}}{5} + \frac{9e^{3x}}{10} - \frac{11\sin(x)}{10} - \frac{\cos(x)}{10} & \frac{12e^{2x}}{5} - \frac{9e^{3x}}{5} + \frac{3\sin(x)}{5} \\ \frac{24e^{2x}}{5} - \frac{27e^{3x}}{5} + \frac{3\cos(x)}{5} + \frac{3\sin(x)}{5} & -\frac{8e^{2x}}{5} + \frac{27e^{3x}}{10} - \frac{11\cos(x)}{10} + \frac{\sin(x)}{10} & \frac{24e^{2x}}{5} - \frac{27e^{3x}}{5} + \frac{3\cos(x)}{5} \end{bmatrix}$$

□ Find a particular solution of the system of ODEs using variation of parameters

- Let the particular solution be the fundamental matrix multiplied by $\vec{v}(x)$ and solve for $\vec{v}(x)$

$$\vec{y}_p(x) = \Phi(x) \cdot \vec{v}(x)$$

- Take the derivative of the particular solution

$$\vec{y}'_p(x) = \Phi'(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x)$$

- Substitute particular solution and its derivative into the system of ODEs

$$\Phi'(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x) = A \cdot \Phi(x) \cdot \vec{v}(x) + \vec{f}(x)$$

- The fundamental matrix has columns that are solutions to the homogeneous system so its derivative is

$$A \cdot \Phi(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x) = A \cdot \Phi(x) \cdot \vec{v}(x) + \vec{f}(x)$$

- Cancel like terms

$$\Phi(x) \cdot \vec{v}'(x) = \vec{f}(x)$$

- Multiply by the inverse of the fundamental matrix

$$\vec{v}'(x) = \frac{1}{\Phi(x)} \cdot \vec{f}(x)$$

- Integrate to solve for $\vec{v}(x)$

$$\vec{v}(x) = \int_0^x \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds$$

- Plug $\vec{v}(x)$ into the equation for the particular solution

$$\vec{y}_p(x) = \Phi(x) \cdot \left(\int_0^x \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds \right)$$

- Plug in the fundamental matrix and the forcing function and compute

$$\vec{y}_p(x) = \begin{bmatrix} -\frac{5}{13} + \frac{2e^{2x}}{5} - \frac{7e^{3x}}{52} + \frac{10 \cos(x)^2}{13} + \frac{(-65x+40 \sin(x)-169) \cos(x)}{260} + \frac{(-6+5x) \sin(x)}{20} \\ -\frac{2}{13} + \frac{4e^{2x}}{5} - \frac{21e^{3x}}{52} + \frac{4 \cos(x)^2}{13} + \frac{(65x-400 \sin(x)-143) \cos(x)}{260} + \frac{(18+5x) \sin(x)}{20} \\ \frac{20}{13} + \frac{8e^{2x}}{5} - \frac{63e^{3x}}{52} - \frac{40 \cos(x)^2}{13} + \frac{(65x-160 \sin(x)+299) \cos(x)}{260} + \frac{(16-5x) \sin(x)}{20} \\ \frac{8}{13} + \frac{16e^{2x}}{5} - \frac{189e^{3x}}{52} - \frac{16 \cos(x)^2}{13} + \frac{(-65x+1600 \sin(x)+273) \cos(x)}{260} + \frac{(-28-5x) \sin(x)}{20} \end{bmatrix}$$

- Plug particular solution back into general solution

$$\vec{y}(x) = c_1 \vec{y}_1 + c_2 \vec{y}_2 + c_3 \vec{y}_3(x) + c_4 \vec{y}_4(x) + \begin{bmatrix} -\frac{5}{13} + \frac{2e^{2x}}{5} - \frac{7e^{3x}}{52} + \frac{10 \cos(x)^2}{13} + \frac{(-65x+40 \sin(x)-169) \cos(x)}{260} \\ -\frac{2}{13} + \frac{4e^{2x}}{5} - \frac{21e^{3x}}{52} + \frac{4 \cos(x)^2}{13} + \frac{(65x-400 \sin(x)-143) \cos(x)}{260} \\ \frac{20}{13} + \frac{8e^{2x}}{5} - \frac{63e^{3x}}{52} - \frac{40 \cos(x)^2}{13} + \frac{(65x-160 \sin(x)+299) \cos(x)}{260} \\ \frac{8}{13} + \frac{16e^{2x}}{5} - \frac{189e^{3x}}{52} - \frac{16 \cos(x)^2}{13} + \frac{(-65x+1600 \sin(x)+273) \cos(x)}{260} \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y = -\frac{5}{13} + \frac{(16+5c_1)e^{2x}}{40} + \frac{(-189+52c_2)e^{3x}}{1404} + \frac{10 \cos(x)^2}{13} + \frac{(-169-65x-260c_4+40 \sin(x)) \cos(x)}{260} + \frac{(-6+5x-20c_3) \sin(x)}{20}$$

Maple trace

```

`Methods for high order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 4; linear nonhomogeneous with symmetry [0,1]
trying high order linear exact nonhomogeneous
trying differential order: 4; missing the dependent variable
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 51

```
dsolve(diff(y(x),x$4)-5*diff(y(x),x$3)+7*diff(y(x),x$2)-5*diff(y(x),x)+6*y(x))=5*sin(x)-12*si
```

$$y(x) = \frac{5 \cos(2x)}{13} + c_3 e^{2x} + c_4 e^{3x} + \frac{\sin(2x)}{13} + \frac{(-2 - 5x + 20c_1) \cos(x)}{20} + \frac{(1 + x + 4c_2) \sin(x)}{4}$$

✓ Solution by Mathematica

Time used: 0.232 (sec). Leaf size: 71

```
DSolve[y''''[x]-5*y'''[x]+7*y''[x]-5*y'[x]+6*y[x]==5*Sin[x]-12*Sin[2*x],y[x],x,IncludeSingular
```

$$y(x) \rightarrow -\frac{5 \sin^2(x)}{13} + \frac{5 \cos^2(x)}{13} + e^{2x}(c_4 e^x + c_3) + \left(\frac{x}{4} + \frac{3}{8} + c_2\right) \sin(x) + \cos(x) \left(-\frac{x}{4} + \frac{2 \sin(x)}{13} - \frac{1}{10} + c_1\right)$$

11.25 problem 25

11.25.1 Existence and uniqueness analysis	2483
11.25.2 Solving as second order linear constant coeff ode	2484
11.25.3 Solving using Kovacic algorithm	2488
11.25.4 Maple step by step solution	2493

Internal problem ID [11799]

Internal file name [OUTPUT/11808_Thursday_April_11_2024_08_49_52_PM_42387168/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 25.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$y'' - 4y' + 3y = 9x^2 + 4$$

With initial conditions

$$[y(0) = 6, y'(0) = 8]$$

11.25.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$p(x) = -4$$

$$q(x) = 3$$

$$F = 9x^2 + 4$$

Hence the ode is

$$y'' - 4y' + 3y = 9x^2 + 4$$

The domain of $p(x) = -4$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = 3$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. The domain of $F = 9x^2 + 4$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

11.25.2 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = -4, C = 3, f(x) = 9x^2 + 4$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' - 4y' + 3y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = -4, C = 3$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} - 4\lambda e^{\lambda x} + 3e^{\lambda x} = 0 \tag{1}$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 - 4\lambda + 3 = 0 \tag{2}$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = -4, C = 3$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{4}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{-4^2 - (4)(1)(3)} \\ &= 2 \pm 1 \end{aligned}$$

Hence

$$\lambda_1 = 2 + 1$$

$$\lambda_2 = 2 - 1$$

Which simplifies to

$$\lambda_1 = 3$$

$$\lambda_2 = 1$$

Since roots are real and distinct, then the solution is

$$y = c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x}$$

$$y = c_1 e^{(3)x} + c_2 e^{(1)x}$$

Or

$$y = c_1 e^{3x} + c_2 e^x$$

Therefore the homogeneous solution y_h is

$$y_h = c_1 e^{3x} + c_2 e^x$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$x^2 + 1$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{1, x, x^2\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^x, e^{3x}\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_3x^2 + A_2x + A_1$$

The unknowns $\{A_1, A_2, A_3\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$3A_3x^2 + 3A_2x - 8xA_3 + 3A_1 - 4A_2 + 2A_3 = 9x^2 + 4$$

Solving for the unknowns by comparing coefficients results in

$$[A_1 = 10, A_2 = 8, A_3 = 3]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = 3x^2 + 8x + 10$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1e^{3x} + c_2e^x) + (3x^2 + 8x + 10) \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1e^{3x} + c_2e^x + 3x^2 + 8x + 10 \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 6$ and $x = 0$ in the above gives

$$6 = c_1 + c_2 + 10 \tag{1A}$$

Taking derivative of the solution gives

$$y' = 3c_1e^{3x} + c_2e^x + 6x + 8$$

substituting $y' = 8$ and $x = 0$ in the above gives

$$8 = 3c_1 + c_2 + 8 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$\begin{aligned} c_1 &= 2 \\ c_2 &= -6 \end{aligned}$$

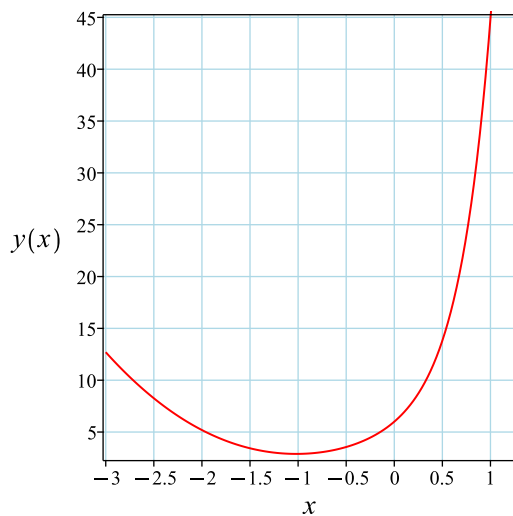
Substituting these values back in above solution results in

$$y = 10 + 3x^2 + 2e^{3x} - 6e^x + 8x$$

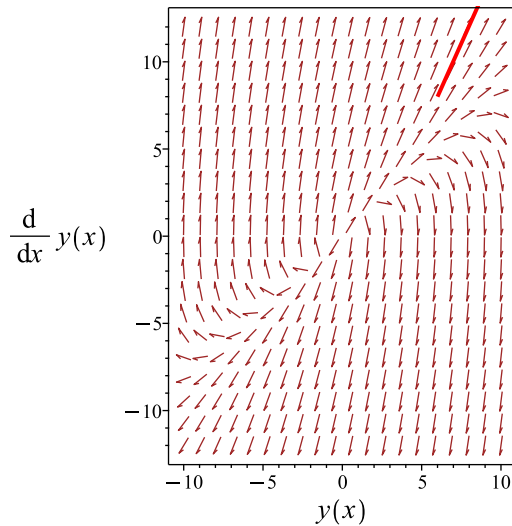
Summary

The solution(s) found are the following

$$y = 10 + 3x^2 + 2e^{3x} - 6e^x + 8x \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = 10 + 3x^2 + 2e^{3x} - 6e^x + 8x$$

Verified OK.

11.25.3 Solving using Kovacic algorithm

Writing the ode as

$$y'' - 4y' + 3y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= -4 \\ C &= 3 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{1}{1} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 1 \\ t &= 1 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = z(x) \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 379: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = 1$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = e^{-x}$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-4}{1} dx} \end{aligned}$$

$$\begin{aligned}
&= z_1 e^{2x} \\
&= z_1 (e^{2x})
\end{aligned}$$

Which simplifies to

$$y_1 = e^x$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}
y_2 &= y_1 \int \frac{e^{\int -\frac{4}{1} dx}}{(y_1)^2} dx \\
&= y_1 \int \frac{e^{4x}}{(y_1)^2} dx \\
&= y_1 \left(\frac{e^{2x}}{2} \right)
\end{aligned}$$

Therefore the solution is

$$\begin{aligned}
y &= c_1 y_1 + c_2 y_2 \\
&= c_1 (e^x) + c_2 \left(e^x \left(\frac{e^{2x}}{2} \right) \right)
\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' - 4y' + 3y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = e^x c_1 + \frac{e^{3x} c_2}{2}$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$x^2 + 1$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{1, x, x^2\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\left\{ \frac{e^{3x}}{2}, e^x \right\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_3x^2 + A_2x + A_1$$

The unknowns $\{A_1, A_2, A_3\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$3A_3x^2 + 3A_2x - 8xA_3 + 3A_1 - 4A_2 + 2A_3 = 9x^2 + 4$$

Solving for the unknowns by comparing coefficients results in

$$[A_1 = 10, A_2 = 8, A_3 = 3]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = 3x^2 + 8x + 10$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(e^x c_1 + \frac{e^{3x} c_2}{2} \right) + (3x^2 + 8x + 10) \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = e^x c_1 + \frac{e^{3x} c_2}{2} + 3x^2 + 8x + 10 \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 6$ and $x = 0$ in the above gives

$$6 = c_1 + \frac{c_2}{2} + 10 \quad (1A)$$

Taking derivative of the solution gives

$$y' = e^x c_1 + \frac{3e^{3x} c_2}{2} + 6x + 8$$

substituting $y' = 8$ and $x = 0$ in the above gives

$$8 = c_1 + \frac{3c_2}{2} + 8 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = -6$$

$$c_2 = 4$$

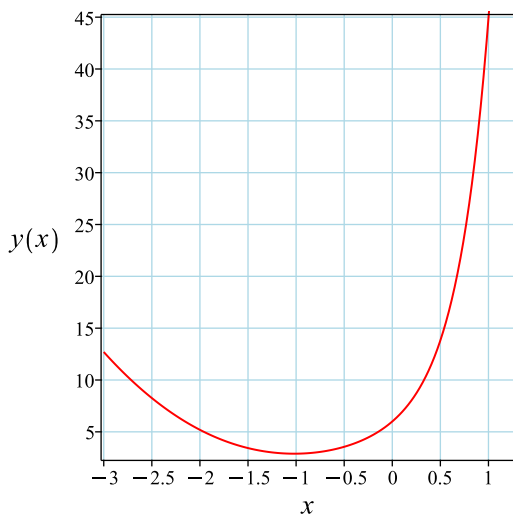
Substituting these values back in above solution results in

$$y = 10 + 3x^2 + 2e^{3x} - 6e^x + 8x$$

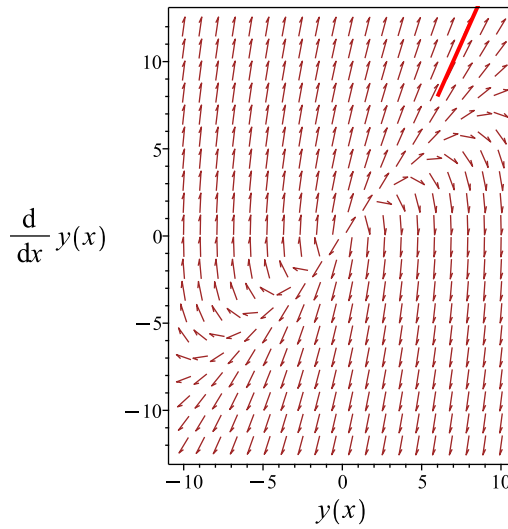
Summary

The solution(s) found are the following

$$y = 10 + 3x^2 + 2e^{3x} - 6e^x + 8x \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = 10 + 3x^2 + 2e^{3x} - 6e^x + 8x$$

Verified OK.

11.25.4 Maple step by step solution

Let's solve

$$\left[y'' - 4y' + 3y = 9x^2 + 4, y(0) = 6, y' \Big|_{\{x=0\}} = 8 \right]$$

- Highest derivative means the order of the ODE is 2
- y''
- Characteristic polynomial of homogeneous ODE
- $r^2 - 4r + 3 = 0$
- Factor the characteristic polynomial
- $(r - 1)(r - 3) = 0$
- Roots of the characteristic polynomial
- $r = (1, 3)$
- 1st solution of the homogeneous ODE

$$y_1(x) = e^x$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = e^{3x}$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = e^x c_1 + e^{3x} c_2 + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = 9x^2 + 4 \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} e^x & e^{3x} \\ e^x & 3e^{3x} \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = 2e^{4x}$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = -\frac{e^x \left(\int (9x^2+4)e^{-x} dx \right)}{2} + \frac{e^{3x} \left(\int e^{-3x} (9x^2+4) dx \right)}{2}$$

- Compute integrals

$$y_p(x) = 3x^2 + 8x + 10$$

- Substitute particular solution into general solution to ODE

$$y = e^x c_1 + e^{3x} c_2 + 3x^2 + 8x + 10$$

- Check validity of solution $y = e^x c_1 + e^{3x} c_2 + 3x^2 + 8x + 10$

- Use initial condition $y(0) = 6$

$$6 = c_1 + c_2 + 10$$

- Compute derivative of the solution

$$y' = e^x c_1 + 3e^{3x} c_2 + 6x + 8$$

- Use the initial condition $y' \Big|_{\{x=0\}} = 8$

$$8 = c_1 + 3c_2 + 8$$

- Solve for c_1 and c_2
 - $\{c_1 = -6, c_2 = 2\}$
- Substitute constant values into general solution and simplify
 - $y = 10 + 3x^2 + 2e^{3x} - 6e^x + 8x$
- Solution to the IVP
 - $y = 10 + 3x^2 + 2e^{3x} - 6e^x + 8x$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
trying a double symmetry of the form [xi=0, eta=F(x)]
-> Try solving first the homogeneous part of the ODE
    checking if the LODE has constant coefficients
    <- constant coefficients successful
<- solving first the homogeneous part of the ODE successful`

```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 24

```
dsolve([diff(y(x),x$2)-4*diff(y(x),x)+3*y(x)=9*x^2+4,y(0) = 6, D(y)(0) = 8],y(x), singsol=al
```

$$y(x) = -6e^x + 2e^{3x} + 3x^2 + 8x + 10$$

✓ Solution by Mathematica

Time used: 0.015 (sec). Leaf size: 27

```
DSolve[{y''[x]-4*y'[x]+3*y[x]==9*x^2+4,{y[0]==6,y'[0]==8}},y[x],x,IncludeSingularSolutions -
```

$$y(x) \rightarrow 3x^2 + 8x - 6e^x + 2e^{3x} + 10$$

11.26 problem 26

11.26.1 Existence and uniqueness analysis	2496
11.26.2 Solving as second order linear constant coeff ode	2497
11.26.3 Solving using Kovacic algorithm	2501
11.26.4 Maple step by step solution	2506

Internal problem ID [11800]

Internal file name [OUTPUT/11809_Thursday_April_11_2024_08_49_52_PM_16421415/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 26.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"kovacic", "second_order_linear_constant_coeff"**

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$y'' + 5y' + 4y = 16x + 20e^x$$

With initial conditions

$$[y(0) = 0, y'(0) = 3]$$

11.26.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$p(x) = 5$$

$$q(x) = 4$$

$$F = 16x + 20e^x$$

Hence the ode is

$$y'' + 5y' + 4y = 16x + 20e^x$$

The domain of $p(x) = 5$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = 4$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. The domain of $F = 16x + 20e^x$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

11.26.2 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = 5, C = 4, f(x) = 16x + 20e^x$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 5y' + 4y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 5, C = 4$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + 5\lambda e^{\lambda x} + 4e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 5\lambda + 4 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 5, C = 4$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{-5}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{5^2 - (4)(1)(4)} \\ &= -\frac{5}{2} \pm \frac{3}{2} \end{aligned}$$

Hence

$$\begin{aligned} \lambda_1 &= -\frac{5}{2} + \frac{3}{2} \\ \lambda_2 &= -\frac{5}{2} - \frac{3}{2} \end{aligned}$$

Which simplifies to

$$\begin{aligned} \lambda_1 &= -1 \\ \lambda_2 &= -4 \end{aligned}$$

Since roots are real and distinct, then the solution is

$$\begin{aligned} y &= c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x} \\ y &= c_1 e^{(-1)x} + c_2 e^{(-4)x} \end{aligned}$$

Or

$$y = c_1 e^{-x} + c_2 e^{-4x}$$

Therefore the homogeneous solution y_h is

$$y_h = c_1 e^{-x} + c_2 e^{-4x}$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$16x + 20e^x$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{e^x\}, \{1, x\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^{-4x}, e^{-x}\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1 e^x + A_2 + A_3 x$$

The unknowns $\{A_1, A_2, A_3\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$10A_1 e^x + 5A_3 + 4A_2 + 4A_3 x = 16x + 20 e^x$$

Solving for the unknowns by comparing coefficients results in

$$[A_1 = 2, A_2 = -5, A_3 = 4]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = 2 e^x - 5 + 4x$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 e^{-x} + c_2 e^{-4x}) + (2 e^x - 5 + 4x) \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{-x} + c_2 e^{-4x} + 2 e^x - 5 + 4x \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 0$ and $x = 0$ in the above gives

$$0 = c_1 + c_2 - 3 \tag{1A}$$

Taking derivative of the solution gives

$$y' = -c_1 e^{-x} - 4c_2 e^{-4x} + 2e^x + 4$$

substituting $y' = 3$ and $x = 0$ in the above gives

$$3 = -c_1 - 4c_2 + 6 \tag{2A}$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 3$$

$$c_2 = 0$$

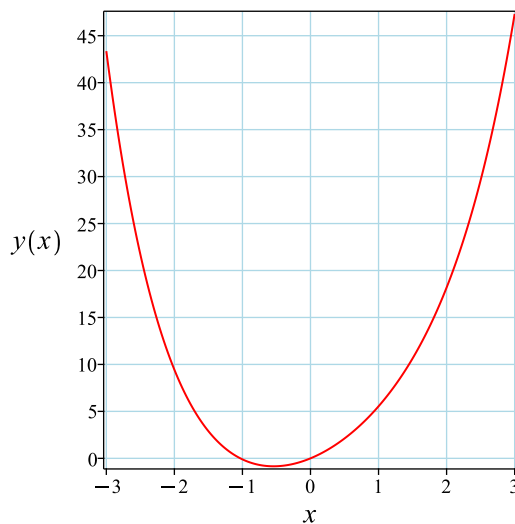
Substituting these values back in above solution results in

$$y = -5 + 2e^x + 3e^{-x} + 4x$$

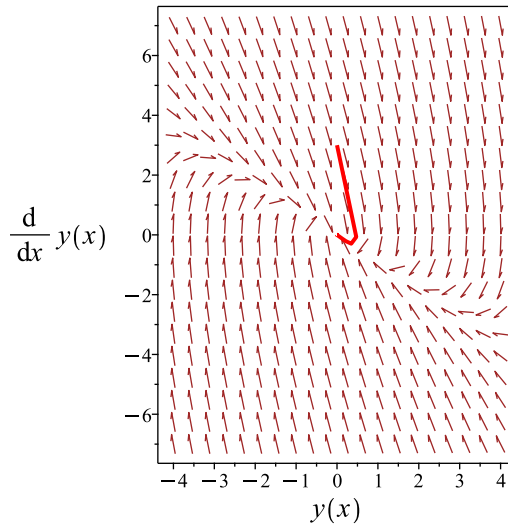
Summary

The solution(s) found are the following

$$y = -5 + 2e^x + 3e^{-x} + 4x \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = -5 + 2e^x + 3e^{-x} + 4x$$

Verified OK.

11.26.3 Solving using Kovacic algorithm

Writing the ode as

$$y'' + 5y' + 4y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$A = 1$$

$$B = 5 \quad (3)$$

$$C = 4$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$r = \frac{s}{t} \quad (5)$$
$$= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{9}{4} \quad (6)$$

Comparing the above to (5) shows that

$$s = 9$$

$$t = 4$$

Therefore eq. (4) becomes

$$z''(x) = \frac{9z(x)}{4} \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 381: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = \frac{9}{4}$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = e^{-\frac{3x}{2}}$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{5}{1} dx} \end{aligned}$$

$$\begin{aligned}
&= z_1 e^{-\frac{5x}{2}} \\
&= z_1 \left(e^{-\frac{5x}{2}} \right)
\end{aligned}$$

Which simplifies to

$$y_1 = e^{-4x}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}
y_2 &= y_1 \int \frac{e^{\int -\frac{5}{1} dx}}{(y_1)^2} dx \\
&= y_1 \int \frac{e^{-5x}}{(y_1)^2} dx \\
&= y_1 \left(\frac{e^{3x}}{3} \right)
\end{aligned}$$

Therefore the solution is

$$\begin{aligned}
y &= c_1 y_1 + c_2 y_2 \\
&= c_1 (e^{-4x}) + c_2 \left(e^{-4x} \left(\frac{e^{3x}}{3} \right) \right)
\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 5y' + 4y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1 e^{-4x} + \frac{c_2 e^{-x}}{3}$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$16x + 20e^x$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{e^x\}, \{1, x\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\left\{ \frac{e^{-x}}{3}, e^{-4x} \right\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1e^x + A_2 + A_3x$$

The unknowns $\{A_1, A_2, A_3\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$10A_1e^x + 5A_3 + 4A_2 + 4A_3x = 16x + 20e^x$$

Solving for the unknowns by comparing coefficients results in

$$[A_1 = 2, A_2 = -5, A_3 = 4]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = 2e^x - 5 + 4x$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(c_1e^{-4x} + \frac{c_2e^{-x}}{3} \right) + (2e^x - 5 + 4x) \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{-4x} + \frac{c_2 e^{-x}}{3} + 2e^x - 5 + 4x \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 0$ and $x = 0$ in the above gives

$$0 = c_1 + \frac{c_2}{3} - 3 \quad (1A)$$

Taking derivative of the solution gives

$$y' = -4c_1 e^{-4x} - \frac{c_2 e^{-x}}{3} + 2e^x + 4$$

substituting $y' = 3$ and $x = 0$ in the above gives

$$3 = -4c_1 - \frac{c_2}{3} + 6 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 0$$

$$c_2 = 9$$

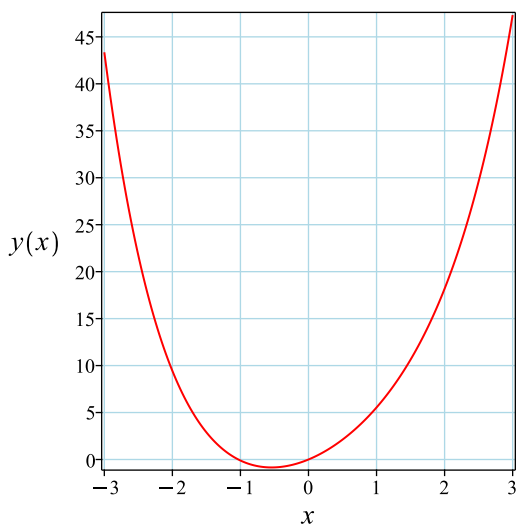
Substituting these values back in above solution results in

$$y = -5 + 2e^x + 3e^{-x} + 4x$$

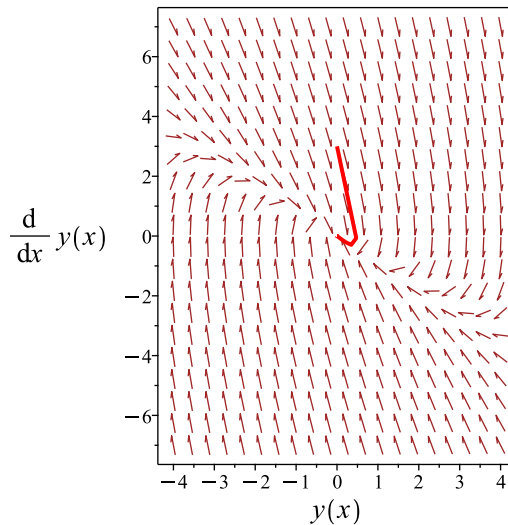
Summary

The solution(s) found are the following

$$y = -5 + 2e^x + 3e^{-x} + 4x \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = -5 + 2e^x + 3e^{-x} + 4x$$

Verified OK.

11.26.4 Maple step by step solution

Let's solve

$$\left[y'' + 5y' + 4y = 16x + 20e^x, y(0) = 0, y' \Big|_{\{x=0\}} = 3 \right]$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of homogeneous ODE

$$r^2 + 5r + 4 = 0$$

- Factor the characteristic polynomial

$$(r + 4)(r + 1) = 0$$

- Roots of the characteristic polynomial

$$r = (-4, -1)$$

- 1st solution of the homogeneous ODE

$$y_1(x) = e^{-4x}$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = e^{-x}$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = c_1 e^{-4x} + c_2 e^{-x} + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = 16x + 20e^x \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} e^{-4x} & e^{-x} \\ -4e^{-4x} & -e^{-x} \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = 3e^{-5x}$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = -\frac{4e^{-4x}(\int(4x+5e^x)e^{4x}dx)}{3} + \frac{4e^{-x}(\int(4x+5e^x)e^x dx)}{3}$$

- Compute integrals

$$y_p(x) = 2e^x - 5 + 4x$$

- Substitute particular solution into general solution to ODE

$$y = c_1e^{-4x} + c_2e^{-x} + 2e^x - 5 + 4x$$

- Check validity of solution $y = c_1e^{-4x} + c_2e^{-x} + 2e^x - 5 + 4x$

- Use initial condition $y(0) = 0$

$$0 = c_1 + c_2 - 3$$

- Compute derivative of the solution

$$y' = -4c_1e^{-4x} - c_2e^{-x} + 2e^x + 4$$

- Use the initial condition $y' \Big|_{\{x=0\}} = 3$

$$3 = -4c_1 - c_2 + 6$$

- Solve for c_1 and c_2

$$\{c_1 = 0, c_2 = 3\}$$

- Substitute constant values into general solution and simplify

$$y = -5 + 2e^x + 3e^{-x} + 4x$$

- Solution to the IVP

$$y = -5 + 2e^x + 3e^{-x} + 4x$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]  
trying a double symmetry of the form [xi=0, eta=F(x)]  
-> Try solving first the homogeneous part of the ODE  
    checking if the LODE has constant coefficients  
    <- constant coefficients successful  
<- solving first the homogeneous part of the ODE successful`
```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 19

```
dsolve([diff(y(x),x$2)+5*diff(y(x),x)+4*y(x)=16*x+20*exp(x),y(0) = 0, D(y)(0) = 3],y(x), sin
```

$$y(x) = 3e^{-x} - 5 + 2e^x + 4x$$

✓ Solution by Mathematica

Time used: 0.125 (sec). Leaf size: 22

```
DSolve[{y''[x]+5*y'[x]+4*y[x]==16*x+20*Exp[x],{y[0]==0,y'[0]==3}},y[x],x,IncludeSingularSolu
```

$$y(x) \rightarrow 4x + 3e^{-x} + 2e^x - 5$$

11.27 problem 27

11.27.1 Existence and uniqueness analysis	2509
11.27.2 Solving as second order linear constant coeff ode	2510
11.27.3 Solving using Kovacic algorithm	2514
11.27.4 Maple step by step solution	2519

Internal problem ID [11801]

Internal file name [OUTPUT/11810_Thursday_April_11_2024_08_49_53_PM_59993326/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 27.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' - 8y' + 15y = 9e^{2x}x$$

With initial conditions

$$[y(0) = 5, y'(0) = 10]$$

11.27.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$p(x) = -8$$

$$q(x) = 15$$

$$F = 9e^{2x}x$$

Hence the ode is

$$y'' - 8y' + 15y = 9e^{2x}x$$

The domain of $p(x) = -8$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = 15$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. The domain of $F = 9e^{2x}x$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

11.27.2 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = -8, C = 15, f(x) = 9e^{2x}x$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' - 8y' + 15y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = -8, C = 15$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} - 8\lambda e^{\lambda x} + 15e^{\lambda x} = 0 \tag{1}$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 - 8\lambda + 15 = 0 \tag{2}$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = -8, C = 15$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{8}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{-8^2 - (4)(1)(15)} \\ &= 4 \pm 1 \end{aligned}$$

Hence

$$\lambda_1 = 4 + 1$$

$$\lambda_2 = 4 - 1$$

Which simplifies to

$$\lambda_1 = 5$$

$$\lambda_2 = 3$$

Since roots are real and distinct, then the solution is

$$y = c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x}$$

$$y = c_1 e^{(5)x} + c_2 e^{(3)x}$$

Or

$$y = c_1 e^{5x} + e^{3x} c_2$$

Therefore the homogeneous solution y_h is

$$y_h = c_1 e^{5x} + e^{3x} c_2$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$9 e^{2x} x$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{e^{2x} x, e^{2x}\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^{3x}, e^{5x}\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1 e^{2x} x + A_2 e^{2x}$$

The unknowns $\{A_1, A_2\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$3A_1 e^{2x} x - 4A_1 e^{2x} + 3A_2 e^{2x} = 9 e^{2x} x$$

Solving for the unknowns by comparing coefficients results in

$$[A_1 = 3, A_2 = 4]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = 3 e^{2x} x + 4 e^{2x}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 e^{5x} + e^{3x} c_2) + (3 e^{2x} x + 4 e^{2x}) \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{5x} + e^{3x} c_2 + 3 e^{2x} x + 4 e^{2x} \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 5$ and $x = 0$ in the above gives

$$5 = c_1 + c_2 + 4 \tag{1A}$$

Taking derivative of the solution gives

$$y' = 5c_1 e^{5x} + 3e^{3x} c_2 + 6e^{2x} x + 11e^{2x}$$

substituting $y' = 10$ and $x = 0$ in the above gives

$$10 = 5c_1 + 3c_2 + 11 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = -2$$

$$c_2 = 3$$

Substituting these values back in above solution results in

$$y = 3e^{2x}x + 4e^{2x} - 2e^{5x} + 3e^{3x}$$

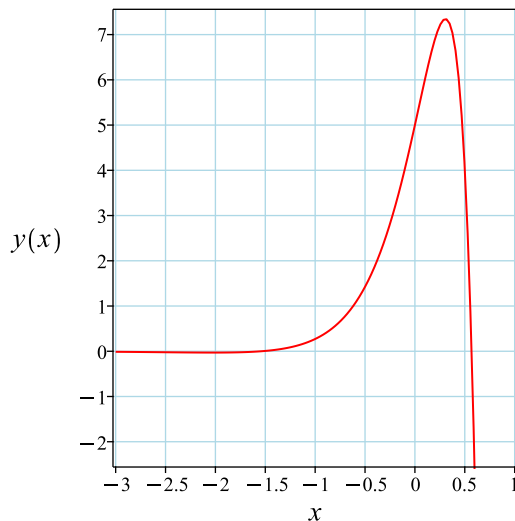
Which simplifies to

$$y = (4 + 3x)e^{2x} + 3e^{3x} - 2e^{5x}$$

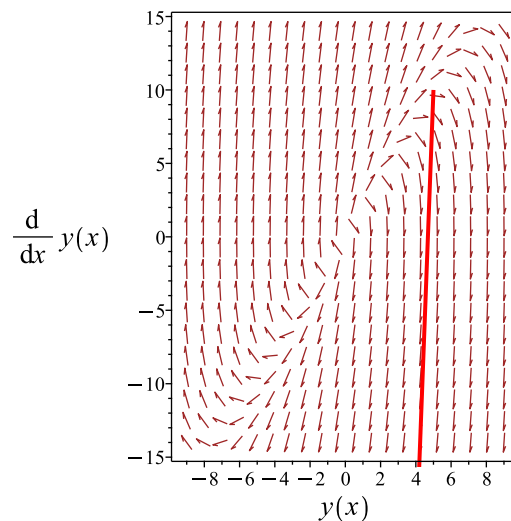
Summary

The solution(s) found are the following

$$y = (4 + 3x)e^{2x} + 3e^{3x} - 2e^{5x} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = (4 + 3x)e^{2x} + 3e^{3x} - 2e^{5x}$$

Verified OK.

11.27.3 Solving using Kovacic algorithm

Writing the ode as

$$y'' - 8y' + 15y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= -8 \\ C &= 15 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{1}{1} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 1 \\ t &= 1 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = z(x) \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 383: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = 1$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = e^{-x}$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-8}{1} dx} \end{aligned}$$

$$\begin{aligned}
&= z_1 e^{4x} \\
&= z_1 (e^{4x})
\end{aligned}$$

Which simplifies to

$$y_1 = e^{3x}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}
y_2 &= y_1 \int \frac{e^{\int -\frac{8}{1} dx}}{(y_1)^2} dx \\
&= y_1 \int \frac{e^{8x}}{(y_1)^2} dx \\
&= y_1 \left(\frac{e^{2x}}{2} \right)
\end{aligned}$$

Therefore the solution is

$$\begin{aligned}
y &= c_1 y_1 + c_2 y_2 \\
&= c_1 (e^{3x}) + c_2 \left(e^{3x} \left(\frac{e^{2x}}{2} \right) \right)
\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' - 8y' + 15y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1 e^{3x} + \frac{c_2 e^{5x}}{2}$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$9e^{2x}x$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{e^{2x}x, e^{2x}\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\left\{ \frac{e^{5x}}{2}, e^{3x} \right\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1e^{2x}x + A_2e^{2x}$$

The unknowns $\{A_1, A_2\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$3A_1e^{2x}x - 4A_1e^{2x} + 3A_2e^{2x} = 9e^{2x}x$$

Solving for the unknowns by comparing coefficients results in

$$[A_1 = 3, A_2 = 4]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = 3e^{2x}x + 4e^{2x}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(c_1e^{3x} + \frac{c_2e^{5x}}{2} \right) + (3e^{2x}x + 4e^{2x}) \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{3x} + \frac{c_2 e^{5x}}{2} + 3 e^{2x} x + 4 e^{2x} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 5$ and $x = 0$ in the above gives

$$5 = c_1 + \frac{c_2}{2} + 4 \quad (1A)$$

Taking derivative of the solution gives

$$y' = 3c_1 e^{3x} + \frac{5c_2 e^{5x}}{2} + 6 e^{2x} x + 11 e^{2x}$$

substituting $y' = 10$ and $x = 0$ in the above gives

$$10 = 3c_1 + \frac{5c_2}{2} + 11 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 3$$

$$c_2 = -4$$

Substituting these values back in above solution results in

$$y = 3 e^{2x} x + 4 e^{2x} - 2 e^{5x} + 3 e^{3x}$$

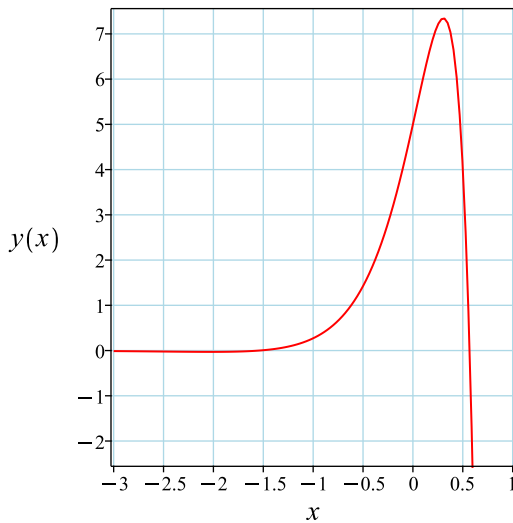
Which simplifies to

$$y = (4 + 3x) e^{2x} + 3 e^{3x} - 2 e^{5x}$$

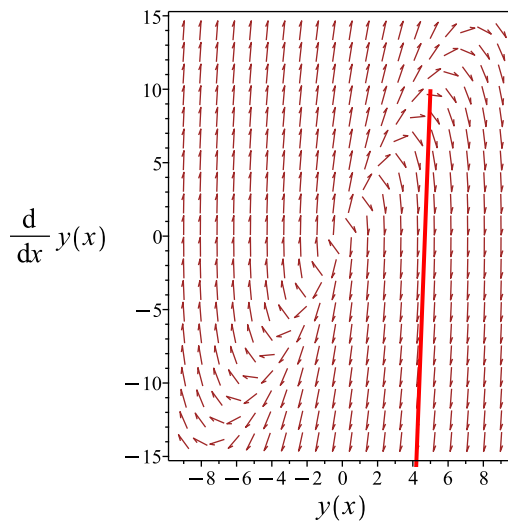
Summary

The solution(s) found are the following

$$y = (4 + 3x) e^{2x} + 3 e^{3x} - 2 e^{5x} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = (4 + 3x)e^{2x} + 3e^{3x} - 2e^{5x}$$

Verified OK.

11.27.4 Maple step by step solution

Let's solve

$$\left[y'' - 8y' + 15y = 9e^{2x}x, y(0) = 5, y'|_{\{x=0\}} = 10 \right]$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of homogeneous ODE

$$r^2 - 8r + 15 = 0$$

- Factor the characteristic polynomial

$$(r - 3)(r - 5) = 0$$

- Roots of the characteristic polynomial

$$r = (3, 5)$$

- 1st solution of the homogeneous ODE

$$y_1(x) = e^{3x}$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = e^{5x}$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = c_1 e^{3x} + c_2 e^{5x} + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = 9e^{2x}x \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} e^{3x} & e^{5x} \\ 3e^{3x} & 5e^{5x} \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = 2e^{8x}$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = -\frac{9e^{3x}(\int x e^{-x} dx)}{2} + \frac{9e^{5x}(\int x e^{-3x} dx)}{2}$$

- Compute integrals

$$y_p(x) = (4 + 3x)e^{2x}$$

- Substitute particular solution into general solution to ODE

$$y = c_1 e^{3x} + c_2 e^{5x} + (4 + 3x)e^{2x}$$

- Check validity of solution $y = c_1 e^{3x} + c_2 e^{5x} + (4 + 3x)e^{2x}$

- Use initial condition $y(0) = 5$

$$5 = c_1 + c_2 + 4$$

- Compute derivative of the solution

$$y' = 3c_1 e^{3x} + 5c_2 e^{5x} + 3e^{2x} + 2(4 + 3x)e^{2x}$$

- Use the initial condition $y' \Big|_{\{x=0\}} = 10$

$$10 = 3c_1 + 5c_2 + 11$$

- Solve for c_1 and c_2

$$\{c_1 = 3, c_2 = -2\}$$

- Substitute constant values into general solution and simplify

$$y = (4 + 3x)e^{2x} + 3e^{3x} - 2e^{5x}$$

- Solution to the IVP

$$y = (4 + 3x)e^{2x} + 3e^{3x} - 2e^{5x}$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
trying a double symmetry of the form [xi=0, eta=F(x)]
-> Try solving first the homogeneous part of the ODE
    checking if the LODE has constant coefficients
    <- constant coefficients successful
<- solving first the homogeneous part of the ODE successful`

```

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 27

```
dsolve([diff(y(x),x$2)-8*diff(y(x),x)+15*y(x)=9*x*exp(2*x),y(0) = 5, D(y)(0) = 10],y(x), sin
```

$$y(x) = -2e^{5x} + 3e^{3x} + (3x + 4)e^{2x}$$

✓ Solution by Mathematica

Time used: 0.019 (sec). Leaf size: 28

```
DSolve[{y'[x]-8*y'[x]+15*y[x]==9*x*Exp[2*x]},{y[0]==5,y'[0]==10}],y[x],x,IncludeSingularSolu
```

$$y(x) \rightarrow e^{2x}(3x + 3e^x - 2e^{3x} + 4)$$

11.28 problem 28

11.28.1 Existence and uniqueness analysis	2522
11.28.2 Solving as second order linear constant coeff ode	2523
11.28.3 Solving using Kovacic algorithm	2527
11.28.4 Maple step by step solution	2532

Internal problem ID [11802]

Internal file name [OUTPUT/11811_Thursday_April_11_2024_08_49_54_PM_95445400/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 28.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' + 7y' + 10y = 4x e^{-3x}$$

With initial conditions

$$[y(0) = 0, y'(0) = -1]$$

11.28.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$p(x) = 7$$

$$q(x) = 10$$

$$F = 4x e^{-3x}$$

Hence the ode is

$$y'' + 7y' + 10y = 4x e^{-3x}$$

The domain of $p(x) = 7$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = 10$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. The domain of $F = 4x e^{-3x}$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

11.28.2 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = 7, C = 10, f(x) = 4x e^{-3x}$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 7y' + 10y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 7, C = 10$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + 7\lambda e^{\lambda x} + 10 e^{\lambda x} = 0 \tag{1}$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 7\lambda + 10 = 0 \tag{2}$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 7, C = 10$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{-7}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{7^2 - (4)(1)(10)} \\ &= -\frac{7}{2} \pm \frac{3}{2} \end{aligned}$$

Hence

$$\begin{aligned} \lambda_1 &= -\frac{7}{2} + \frac{3}{2} \\ \lambda_2 &= -\frac{7}{2} - \frac{3}{2} \end{aligned}$$

Which simplifies to

$$\begin{aligned} \lambda_1 &= -2 \\ \lambda_2 &= -5 \end{aligned}$$

Since roots are real and distinct, then the solution is

$$\begin{aligned} y &= c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x} \\ y &= c_1 e^{(-2)x} + c_2 e^{(-5)x} \end{aligned}$$

Or

$$y = c_1 e^{-2x} + c_2 e^{-5x}$$

Therefore the homogeneous solution y_h is

$$y_h = c_1 e^{-2x} + c_2 e^{-5x}$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$4x e^{-3x}$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{x e^{-3x}, e^{-3x}\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^{-5x}, e^{-2x}\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1 x e^{-3x} + A_2 e^{-3x}$$

The unknowns $\{A_1, A_2\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$A_1 e^{-3x} - 2A_1 x e^{-3x} - 2A_2 e^{-3x} = 4x e^{-3x}$$

Solving for the unknowns by comparing coefficients results in

$$[A_1 = -2, A_2 = -1]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = -2x e^{-3x} - e^{-3x}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 e^{-2x} + c_2 e^{-5x}) + (-2x e^{-3x} - e^{-3x}) \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{-2x} + c_2 e^{-5x} - 2x e^{-3x} - e^{-3x} \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 0$ and $x = 0$ in the above gives

$$0 = c_1 + c_2 - 1 \tag{1A}$$

Taking derivative of the solution gives

$$y' = -2c_1e^{-2x} - 5c_2e^{-5x} + e^{-3x} + 6xe^{-3x}$$

substituting $y' = -1$ and $x = 0$ in the above gives

$$-1 = -2c_1 - 5c_2 + 1 \tag{2A}$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 1$$

$$c_2 = 0$$

Substituting these values back in above solution results in

$$y = -2xe^{-3x} - e^{-3x} + e^{-2x}$$

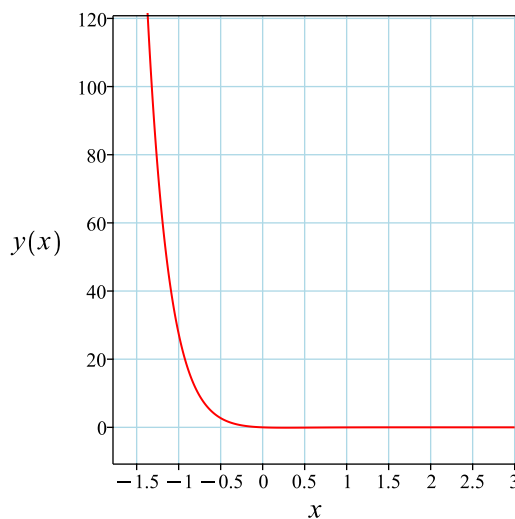
Which simplifies to

$$y = (-2x - 1)e^{-3x} + e^{-2x}$$

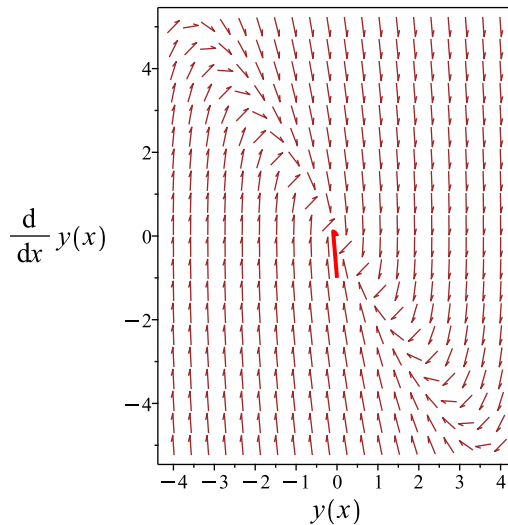
Summary

The solution(s) found are the following

$$y = (-2x - 1)e^{-3x} + e^{-2x} \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = (-2x - 1)e^{-3x} + e^{-2x}$$

Verified OK.

11.28.3 Solving using Kovacic algorithm

Writing the ode as

$$y'' + 7y' + 10y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$A = 1$$

$$B = 7 \quad (3)$$

$$C = 10$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$r = \frac{s}{t} \quad (5)$$
$$= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{9}{4} \quad (6)$$

Comparing the above to (5) shows that

$$s = 9$$

$$t = 4$$

Therefore eq. (4) becomes

$$z''(x) = \frac{9z(x)}{4} \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 385: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = \frac{9}{4}$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = e^{-\frac{3x}{2}}$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{7}{1} dx} \end{aligned}$$

$$\begin{aligned}
&= z_1 e^{-\frac{7x}{2}} \\
&= z_1 \left(e^{-\frac{7x}{2}} \right)
\end{aligned}$$

Which simplifies to

$$y_1 = e^{-5x}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}
y_2 &= y_1 \int \frac{e^{\int -\frac{7}{1} dx}}{(y_1)^2} dx \\
&= y_1 \int \frac{e^{-7x}}{(y_1)^2} dx \\
&= y_1 \left(\frac{e^{3x}}{3} \right)
\end{aligned}$$

Therefore the solution is

$$\begin{aligned}
y &= c_1 y_1 + c_2 y_2 \\
&= c_1 (e^{-5x}) + c_2 \left(e^{-5x} \left(\frac{e^{3x}}{3} \right) \right)
\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 7y' + 10y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1 e^{-5x} + \frac{c_2 e^{-2x}}{3}$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$4x e^{-3x}$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{x e^{-3x}, e^{-3x}\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\left\{ \frac{e^{-2x}}{3}, e^{-5x} \right\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1 x e^{-3x} + A_2 e^{-3x}$$

The unknowns $\{A_1, A_2\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$A_1 e^{-3x} - 2A_1 x e^{-3x} - 2A_2 e^{-3x} = 4x e^{-3x}$$

Solving for the unknowns by comparing coefficients results in

$$[A_1 = -2, A_2 = -1]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = -2x e^{-3x} - e^{-3x}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(c_1 e^{-5x} + \frac{c_2 e^{-2x}}{3} \right) + (-2x e^{-3x} - e^{-3x}) \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{-5x} + \frac{c_2 e^{-2x}}{3} - 2x e^{-3x} - e^{-3x} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 0$ and $x = 0$ in the above gives

$$0 = c_1 + \frac{c_2}{3} - 1 \quad (1A)$$

Taking derivative of the solution gives

$$y' = -5c_1 e^{-5x} - \frac{2c_2 e^{-2x}}{3} + e^{-3x} + 6x e^{-3x}$$

substituting $y' = -1$ and $x = 0$ in the above gives

$$-1 = -5c_1 - \frac{2c_2}{3} + 1 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 0$$

$$c_2 = 3$$

Substituting these values back in above solution results in

$$y = -2x e^{-3x} - e^{-3x} + e^{-2x}$$

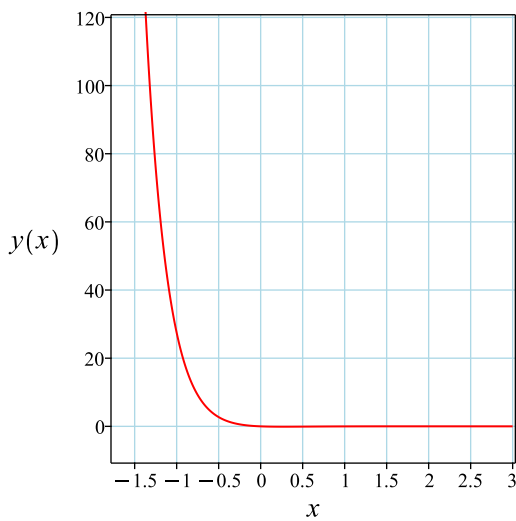
Which simplifies to

$$y = (-2x - 1) e^{-3x} + e^{-2x}$$

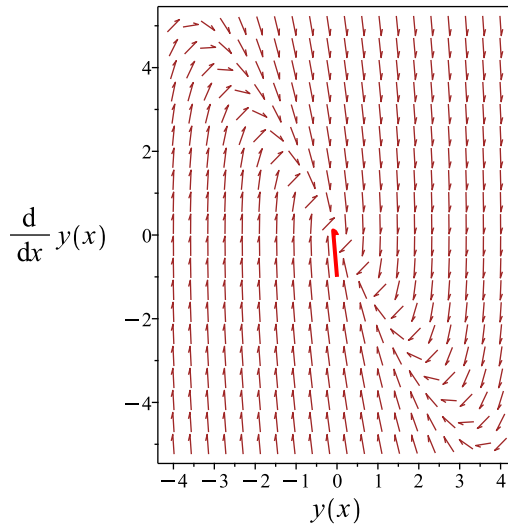
Summary

The solution(s) found are the following

$$y = (-2x - 1) e^{-3x} + e^{-2x} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = (-2x - 1)e^{-3x} + e^{-2x}$$

Verified OK.

11.28.4 Maple step by step solution

Let's solve

$$\left[y'' + 7y' + 10y = 4xe^{-3x}, y(0) = 0, y'|_{\{x=0\}} = -1 \right]$$

- Highest derivative means the order of the ODE is 2
- y''
- Characteristic polynomial of homogeneous ODE

$$r^2 + 7r + 10 = 0$$
- Factor the characteristic polynomial

$$(r + 5)(r + 2) = 0$$
- Roots of the characteristic polynomial

$$r = (-5, -2)$$
- 1st solution of the homogeneous ODE

$$y_1(x) = e^{-5x}$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = e^{-2x}$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = c_1 e^{-5x} + c_2 e^{-2x} + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = 4x e^{-3x} \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} e^{-5x} & e^{-2x} \\ -5e^{-5x} & -2e^{-2x} \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = 3e^{-7x}$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = -\frac{4e^{-5x}(\int e^{2x} x dx)}{3} + \frac{4e^{-2x}(\int x e^{-x} dx)}{3}$$

- Compute integrals

$$y_p(x) = (-2x - 1)e^{-3x}$$

- Substitute particular solution into general solution to ODE

$$y = c_1 e^{-5x} + c_2 e^{-2x} + (-2x - 1)e^{-3x}$$

- Check validity of solution $y = c_1 e^{-5x} + c_2 e^{-2x} + (-2x - 1)e^{-3x}$

- Use initial condition $y(0) = 0$

$$0 = c_1 + c_2 - 1$$

- Compute derivative of the solution

$$y' = -5c_1 e^{-5x} - 2c_2 e^{-2x} - 2e^{-3x} - 3(-2x - 1)e^{-3x}$$

- Use the initial condition $y' \Big|_{\{x=0\}} = -1$

$$-1 = -5c_1 - 2c_2 + 1$$

- Solve for c_1 and c_2

$$\{c_1 = 0, c_2 = 1\}$$
- Substitute constant values into general solution and simplify
$$y = (-2x - 1)e^{-3x} + e^{-2x}$$
- Solution to the IVP
$$y = (-2x - 1)e^{-3x} + e^{-2x}$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
trying a double symmetry of the form [xi=0, eta=F(x)]
-> Try solving first the homogeneous part of the ODE
    checking if the LODE has constant coefficients
    <- constant coefficients successful
<- solving first the homogeneous part of the ODE successful`

```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 19

```
dsolve([diff(y(x),x$2)+7*diff(y(x),x)+10*y(x)=4*x*exp(-3*x),y(0) = 0, D(y)(0) = -1],y(x), si
```

$$y(x) = e^{-2x} + (-2x - 1)e^{-3x}$$

✓ Solution by Mathematica

Time used: 0.022 (sec). Leaf size: 19

```
DSolve[{y''[x]+7*y'[x]+10*y[x]==4*x*Exp[-3*x],{y[0]==0,y'[0]==-1}},y[x],x,IncludeSingularSol
```

$$y(x) \rightarrow e^{-3x}(-2x + e^x - 1)$$

11.29 problem 29

11.29.1 Existence and uniqueness analysis	2536
11.29.2 Solving as second order linear constant coeff ode	2536
11.29.3 Solving as linear second order ode solved by an integrating factor ode	2540
11.29.4 Solving using Kovacic algorithm	2542
11.29.5 Maple step by step solution	2547

Internal problem ID [11803]

Internal file name [OUTPUT/11812_Thursday_April_11_2024_08_49_54_PM_52142107/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 29.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff", "linear_second_order_ode_solved_by_an_integrating_factor"

Maple gives the following as the ode type

```
[[_2nd_order, _with_linear_symmetries]]
```

$$y'' + 8y' + 16y = 8e^{-2x}$$

With initial conditions

$$[y(0) = 2, y'(0) = 0]$$

11.29.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$\begin{aligned}p(x) &= 8 \\q(x) &= 16 \\F &= 8e^{-2x}\end{aligned}$$

Hence the ode is

$$y'' + 8y' + 16y = 8e^{-2x}$$

The domain of $p(x) = 8$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = 16$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. The domain of $F = 8e^{-2x}$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

11.29.2 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = 8, C = 16, f(x) = 8e^{-2x}$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 8y' + 16y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 8, C = 16$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + 8\lambda e^{\lambda x} + 16 e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 8\lambda + 16 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 8, C = 16$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{-8}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{(8)^2 - (4)(1)(16)} \\ &= -4 \end{aligned}$$

Hence this is the case of a double root $\lambda_{1,2} = 4$. Therefore the solution is

$$y = c_1 e^{-4x} + c_2 x e^{-4x} \quad (1)$$

Therefore the homogeneous solution y_h is

$$y_h = c_1 e^{-4x} + c_2 x e^{-4x}$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$8 e^{-2x}$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{e^{-2x}\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^{-4x} x, e^{-4x}\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1 e^{-2x}$$

The unknowns $\{A_1\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$4A_1 e^{-2x} = 8 e^{-2x}$$

Solving for the unknowns by comparing coefficients results in

$$[A_1 = 2]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = 2 e^{-2x}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 e^{-4x} + c_2 x e^{-4x}) + (2 e^{-2x}) \end{aligned}$$

Which simplifies to

$$y = e^{-4x}(c_2 x + c_1) + 2 e^{-2x}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = e^{-4x}(c_2 x + c_1) + 2 e^{-2x} \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 2$ and $x = 0$ in the above gives

$$2 = 2 + c_1 \tag{1A}$$

Taking derivative of the solution gives

$$y' = -4 e^{-4x}(c_2 x + c_1) + c_2 e^{-4x} - 4 e^{-2x}$$

substituting $y' = 0$ and $x = 0$ in the above gives

$$0 = -4 - 4c_1 + c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 0$$

$$c_2 = 4$$

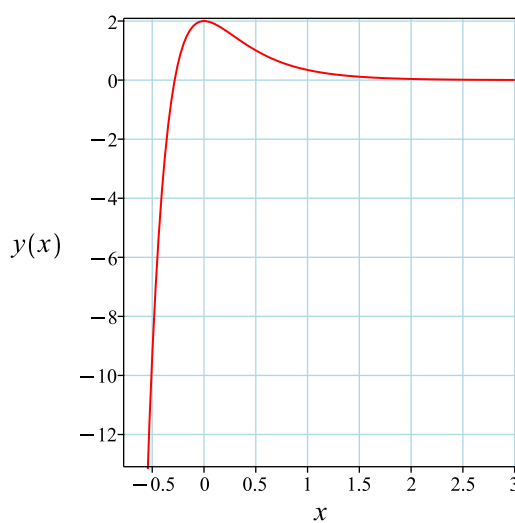
Substituting these values back in above solution results in

$$y = 4e^{-4x}x + 2e^{-2x}$$

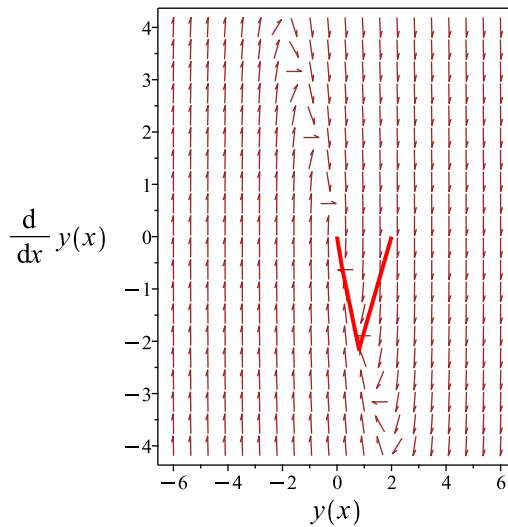
Summary

The solution(s) found are the following

$$y = 4e^{-4x}x + 2e^{-2x} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = 4e^{-4x}x + 2e^{-2x}$$

Verified OK.

11.29.3 Solving as linear second order ode solved by an integrating factor ode

The ode satisfies this form

$$y'' + p(x)y' + \frac{(p(x))^2 + p'(x)}{2}y = f(x)$$

Where $p(x) = 8$. Therefore, there is an integrating factor given by

$$\begin{aligned}M(x) &= e^{\frac{1}{2} \int p \, dx} \\ &= e^{\int 8 \, dx} \\ &= e^{4x}\end{aligned}$$

Multiplying both sides of the ODE by the integrating factor $M(x)$ makes the left side of the ODE a complete differential

$$\begin{aligned}(M(x)y)'' &= 8e^{4x}e^{-2x} \\ (e^{4x}y)'' &= 8e^{4x}e^{-2x}\end{aligned}$$

Integrating once gives

$$(e^{4x}y)' = 4e^{2x} + c_1$$

Integrating again gives

$$(e^{4x}y) = c_1x + 2e^{2x} + c_2$$

Hence the solution is

$$y = \frac{c_1x + 2e^{2x} + c_2}{e^{4x}}$$

Or

$$y = c_1xe^{-4x} + 2e^{-2x} + c_2e^{-4x}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1xe^{-4x} + 2e^{-2x} + c_2e^{-4x} \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 2$ and $x = 0$ in the above gives

$$2 = c_2 + 2 \tag{1A}$$

Taking derivative of the solution gives

$$y' = c_1 e^{-4x} - 4c_1 x e^{-4x} - 4e^{-2x} - 4c_2 e^{-4x}$$

substituting $y' = 0$ and $x = 0$ in the above gives

$$0 = -4 + c_1 - 4c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 4$$

$$c_2 = 0$$

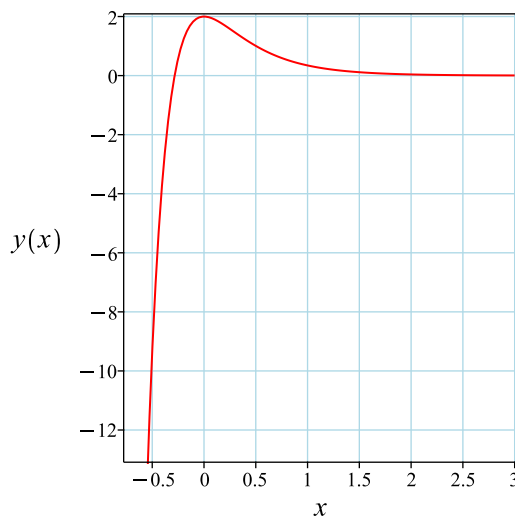
Substituting these values back in above solution results in

$$y = 4e^{-4x}x + 2e^{-2x}$$

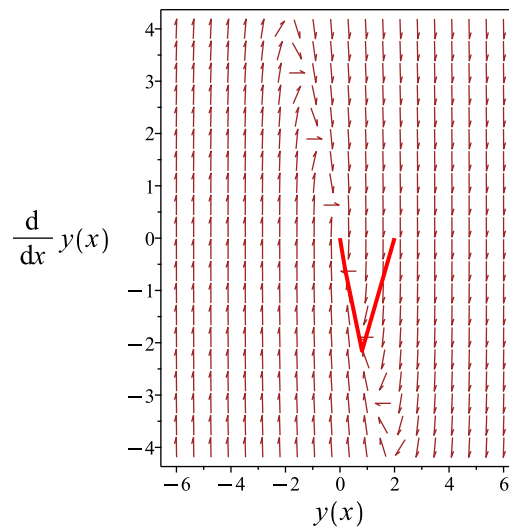
Summary

The solution(s) found are the following

$$y = 4e^{-4x}x + 2e^{-2x} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = 4e^{-4x}x + 2e^{-2x}$$

Verified OK.

11.29.4 Solving using Kovacic algorithm

Writing the ode as

$$y'' + 8y' + 16y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= 8 \\ C &= 16 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{0}{1} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 0 \\ t &= 1 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = 0 \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 387: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - -\infty \\ &= \infty \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is *infinity* then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = 0$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = 1$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{8}{1} dx} \end{aligned}$$

$$\begin{aligned}
&= z_1 e^{-4x} \\
&= z_1 (e^{-4x})
\end{aligned}$$

Which simplifies to

$$y_1 = e^{-4x}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}
y_2 &= y_1 \int \frac{e^{\int -\frac{8}{1} dx}}{(y_1)^2} dx \\
&= y_1 \int \frac{e^{-8x}}{(y_1)^2} dx \\
&= y_1(x)
\end{aligned}$$

Therefore the solution is

$$\begin{aligned}
y &= c_1 y_1 + c_2 y_2 \\
&= c_1 (e^{-4x}) + c_2 (e^{-4x}(x))
\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 8y' + 16y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1 e^{-4x} + c_2 x e^{-4x}$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$8e^{-2x}$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[e^{-2x}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^{-4x}x, e^{-4x}\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1e^{-2x}$$

The unknowns $\{A_1\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$4A_1e^{-2x} = 8e^{-2x}$$

Solving for the unknowns by comparing coefficients results in

$$[A_1 = 2]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = 2e^{-2x}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1e^{-4x} + c_2xe^{-4x}) + (2e^{-2x}) \end{aligned}$$

Which simplifies to

$$y = e^{-4x}(c_2x + c_1) + 2e^{-2x}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = e^{-4x}(c_2x + c_1) + 2e^{-2x} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 2$ and $x = 0$ in the above gives

$$2 = 2 + c_1 \quad (1A)$$

Taking derivative of the solution gives

$$y' = -4e^{-4x}(c_2x + c_1) + c_2e^{-4x} - 4e^{-2x}$$

substituting $y' = 0$ and $x = 0$ in the above gives

$$0 = -4 - 4c_1 + c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 0$$

$$c_2 = 4$$

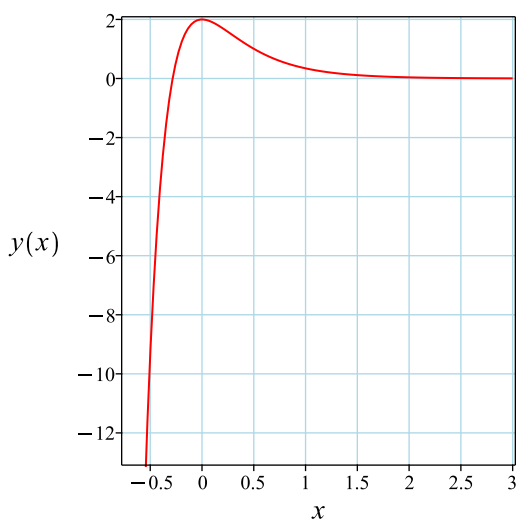
Substituting these values back in above solution results in

$$y = 4e^{-4x}x + 2e^{-2x}$$

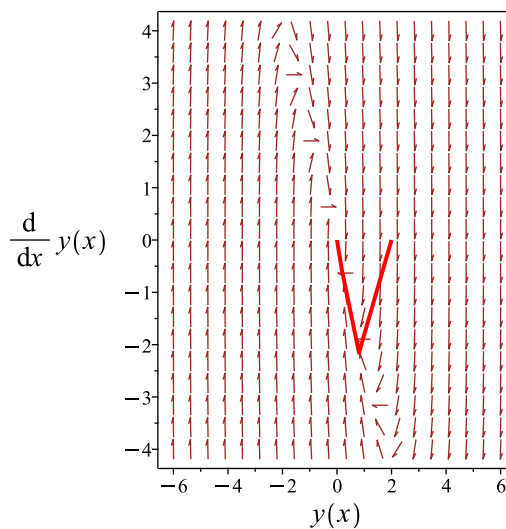
Summary

The solution(s) found are the following

$$y = 4e^{-4x}x + 2e^{-2x} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = 4e^{-4x}x + 2e^{-2x}$$

Verified OK.

11.29.5 Maple step by step solution

Let's solve

$$\left[y'' + 8y' + 16y = 8e^{-2x}, y(0) = 2, y'|_{\{x=0\}} = 0 \right]$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of homogeneous ODE

$$r^2 + 8r + 16 = 0$$

- Factor the characteristic polynomial

$$(r + 4)^2 = 0$$

- Root of the characteristic polynomial

$$r = -4$$

- 1st solution of the homogeneous ODE

$$y_1(x) = e^{-4x}$$

- Repeated root, multiply $y_1(x)$ by x to ensure linear independence

$$y_2(x) = e^{-4x}x$$

- General solution of the ODE

$$y = c_1y_1(x) + c_2y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = c_1e^{-4x} + c_2xe^{-4x} + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = 8e^{-2x} \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} e^{-4x} & e^{-4x}x \\ -4e^{-4x} & -4e^{-4x}x + e^{-4x} \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = e^{-8x}$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = -8e^{-4x} \left(\int e^{2x} x dx - \left(\int e^{2x} dx \right) x \right)$$

- Compute integrals

$$y_p(x) = 2e^{-2x}$$

- Substitute particular solution into general solution to ODE

$$y = c_1 e^{-4x} + c_2 x e^{-4x} + 2e^{-2x}$$

- Check validity of solution $y = c_1 e^{-4x} + c_2 x e^{-4x} + 2e^{-2x}$

- Use initial condition $y(0) = 2$

$$2 = 2 + c_1$$

- Compute derivative of the solution

$$y' = -4c_1 e^{-4x} + c_2 e^{-4x} - 4c_2 x e^{-4x} - 4e^{-2x}$$

- Use the initial condition $y' \Big|_{\{x=0\}} = 0$

$$0 = -4 - 4c_1 + c_2$$

- Solve for c_1 and c_2

$$\{c_1 = 0, c_2 = 4\}$$

- Substitute constant values into general solution and simplify

$$y = 4e^{-4x}x + 2e^{-2x}$$

- Solution to the IVP

$$y = 4e^{-4x}x + 2e^{-2x}$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]  
trying a double symmetry of the form [xi=0, eta=F(x)]  
-> Try solving first the homogeneous part of the ODE  
    checking if the LODE has constant coefficients  
    <- constant coefficients successful  
<- solving first the homogeneous part of the ODE successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 18

```
dsolve([diff(y(x),x$2)+8*diff(y(x),x)+16*y(x)=8*exp(-2*x),y(0) = 2, D(y)(0) = 0],y(x), sings
```

$$y(x) = 4e^{-4x}x + 2e^{-2x}$$

✓ Solution by Mathematica

Time used: 0.02 (sec). Leaf size: 21

```
DSolve[{y''[x]+8*y'[x]+16*y[x]==8*Exp[-2*x],{y[0]==2,y'[0]==0}},y[x],x,IncludeSingularSoluti
```

$$y(x) \rightarrow 2e^{-4x}(2x + e^{2x})$$

11.30 problem 30

11.30.1 Existence and uniqueness analysis	2551
11.30.2 Solving as second order linear constant coeff ode	2551
11.30.3 Solving as linear second order ode solved by an integrating factor ode	2555
11.30.4 Solving using Kovacic algorithm	2557
11.30.5 Maple step by step solution	2562

Internal problem ID [11804]

Internal file name [OUTPUT/11813_Thursday_April_11_2024_08_49_55_PM_97443435/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 30.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff", "linear_second_order_ode_solved_by_an_integrating_factor"

Maple gives the following as the ode type

```
[[_2nd_order, _with_linear_symmetries]]
```

$$y'' + 6y' + 9y = 27e^{-6x}$$

With initial conditions

$$[y(0) = -2, y'(0) = 0]$$

11.30.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$p(x) = 6$$

$$q(x) = 9$$

$$F = 27e^{-6x}$$

Hence the ode is

$$y'' + 6y' + 9y = 27e^{-6x}$$

The domain of $p(x) = 6$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = 9$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. The domain of $F = 27e^{-6x}$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

11.30.2 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = 6, C = 9, f(x) = 27e^{-6x}$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 6y' + 9y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 6, C = 9$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + 6\lambda e^{\lambda x} + 9e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 6\lambda + 9 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 6, C = 9$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{-6}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{(6)^2 - (4)(1)(9)} \\ &= -3 \end{aligned}$$

Hence this is the case of a double root $\lambda_{1,2} = 3$. Therefore the solution is

$$y = c_1 e^{-3x} + c_2 x e^{-3x} \quad (1)$$

Therefore the homogeneous solution y_h is

$$y_h = c_1 e^{-3x} + c_2 x e^{-3x}$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$27 e^{-6x}$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$\{e^{-6x}\}$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{x e^{-3x}, e^{-3x}\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1 e^{-6x}$$

The unknowns $\{A_1\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$9A_1 e^{-6x} = 27 e^{-6x}$$

Solving for the unknowns by comparing coefficients results in

$$[A_1 = 3]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = 3 e^{-6x}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 e^{-3x} + c_2 x e^{-3x}) + (3 e^{-6x}) \end{aligned}$$

Which simplifies to

$$y = e^{-3x}(c_2 x + c_1) + 3 e^{-6x}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = e^{-3x}(c_2 x + c_1) + 3 e^{-6x} \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = -2$ and $x = 0$ in the above gives

$$-2 = 3 + c_1 \tag{1A}$$

Taking derivative of the solution gives

$$y' = -3 e^{-3x}(c_2 x + c_1) + c_2 e^{-3x} - 18 e^{-6x}$$

substituting $y' = 0$ and $x = 0$ in the above gives

$$0 = -18 - 3c_1 + c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = -5$$

$$c_2 = 3$$

Substituting these values back in above solution results in

$$y = 3x e^{-3x} + 3 e^{-6x} - 5 e^{-3x}$$

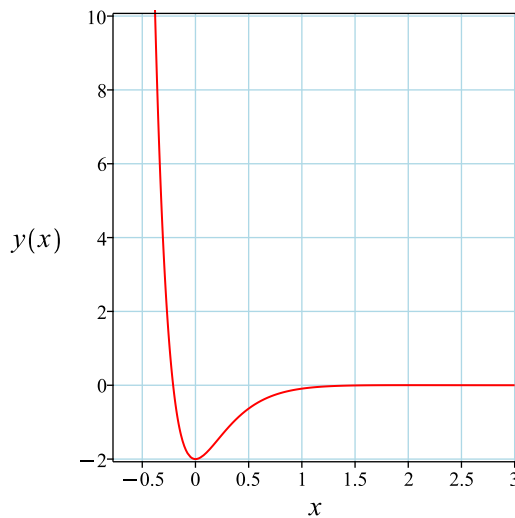
Which simplifies to

$$y = (3x - 5) e^{-3x} + 3 e^{-6x}$$

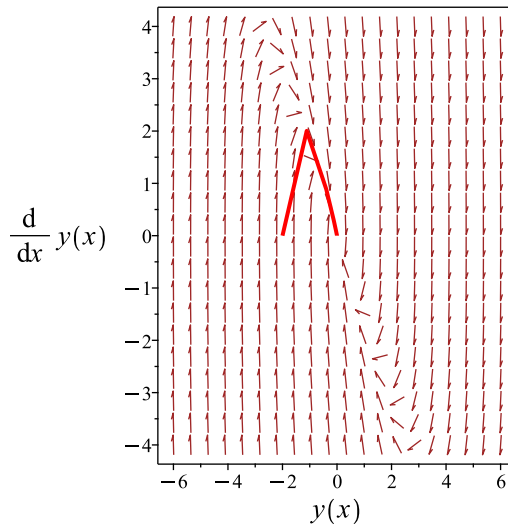
Summary

The solution(s) found are the following

$$y = (3x - 5) e^{-3x} + 3 e^{-6x} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = (3x - 5) e^{-3x} + 3 e^{-6x}$$

Verified OK.

11.30.3 Solving as linear second order ode solved by an integrating factor ode

The ode satisfies this form

$$y'' + p(x)y' + \frac{(p(x))^2 + p'(x)}{2}y = f(x)$$

Where $p(x) = 6$. Therefore, there is an integrating factor given by

$$\begin{aligned}M(x) &= e^{\frac{1}{2} \int p \, dx} \\ &= e^{\int 6 \, dx} \\ &= e^{3x}\end{aligned}$$

Multiplying both sides of the ODE by the integrating factor $M(x)$ makes the left side of the ODE a complete differential

$$\begin{aligned}(M(x)y)'' &= 27e^{3x}e^{-6x} \\ (e^{3x}y)'' &= 27e^{3x}e^{-6x}\end{aligned}$$

Integrating once gives

$$(e^{3x}y)' = -9e^{-3x} + c_1$$

Integrating again gives

$$(e^{3x}y) = c_1x + 3e^{-3x} + c_2$$

Hence the solution is

$$y = \frac{c_1x + 3e^{-3x} + c_2}{e^{3x}}$$

Or

$$y = c_1x e^{-3x} + c_2e^{-3x} + 3e^{-6x}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1x e^{-3x} + c_2e^{-3x} + 3e^{-6x} \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = -2$ and $x = 0$ in the above gives

$$-2 = c_2 + 3 \tag{1A}$$

Taking derivative of the solution gives

$$y' = c_1 e^{-3x} - 3c_1 x e^{-3x} - 3c_2 e^{-3x} - 18 e^{-6x}$$

substituting $y' = 0$ and $x = 0$ in the above gives

$$0 = c_1 - 3c_2 - 18 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 3$$

$$c_2 = -5$$

Substituting these values back in above solution results in

$$y = 3x e^{-3x} + 3 e^{-6x} - 5 e^{-3x}$$

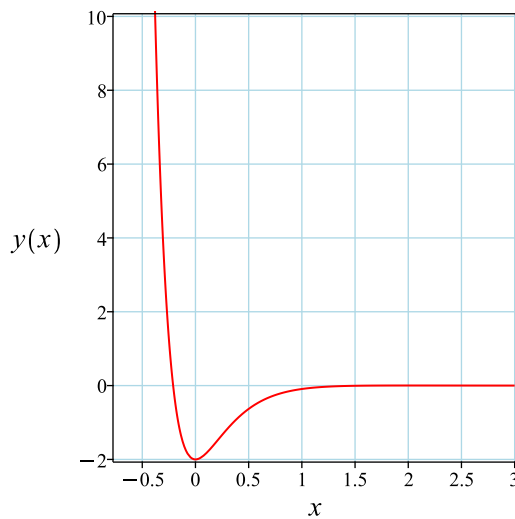
Which simplifies to

$$y = (3x - 5) e^{-3x} + 3 e^{-6x}$$

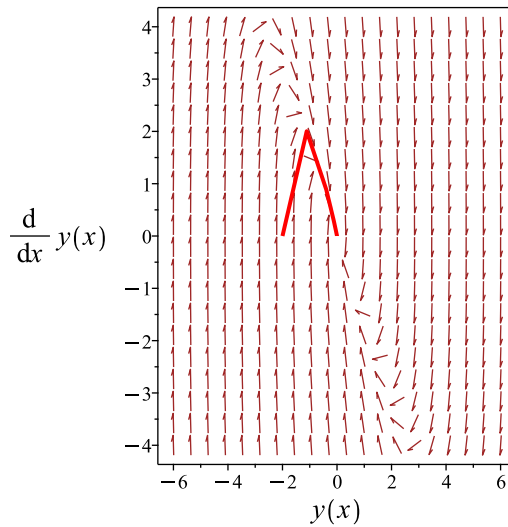
Summary

The solution(s) found are the following

$$y = (3x - 5) e^{-3x} + 3 e^{-6x} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = (3x - 5) e^{-3x} + 3 e^{-6x}$$

Verified OK.

11.30.4 Solving using Kovacic algorithm

Writing the ode as

$$y'' + 6y' + 9y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= 6 \\ C &= 9 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{0}{1} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 0 \\ t &= 1 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = 0 \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 389: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - -\infty \\ &= \infty \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is *infinity* then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = 0$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = 1$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{6}{1} dx} \end{aligned}$$

$$\begin{aligned}
&= z_1 e^{-3x} \\
&= z_1 (e^{-3x})
\end{aligned}$$

Which simplifies to

$$y_1 = e^{-3x}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}
y_2 &= y_1 \int \frac{e^{\int -\frac{6}{1} dx}}{(y_1)^2} dx \\
&= y_1 \int \frac{e^{-6x}}{(y_1)^2} dx \\
&= y_1(x)
\end{aligned}$$

Therefore the solution is

$$\begin{aligned}
y &= c_1 y_1 + c_2 y_2 \\
&= c_1 (e^{-3x}) + c_2 (e^{-3x}(x))
\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 6y' + 9y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1 e^{-3x} + c_2 x e^{-3x}$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$27 e^{-6x}$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{e^{-6x}\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{x e^{-3x}, e^{-3x}\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1 e^{-6x}$$

The unknowns $\{A_1\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$9A_1 e^{-6x} = 27 e^{-6x}$$

Solving for the unknowns by comparing coefficients results in

$$[A_1 = 3]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = 3 e^{-6x}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 e^{-3x} + c_2 x e^{-3x}) + (3 e^{-6x}) \end{aligned}$$

Which simplifies to

$$y = e^{-3x}(c_2 x + c_1) + 3 e^{-6x}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = e^{-3x}(c_2x + c_1) + 3e^{-6x} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = -2$ and $x = 0$ in the above gives

$$-2 = 3 + c_1 \quad (1A)$$

Taking derivative of the solution gives

$$y' = -3e^{-3x}(c_2x + c_1) + c_2e^{-3x} - 18e^{-6x}$$

substituting $y' = 0$ and $x = 0$ in the above gives

$$0 = -18 - 3c_1 + c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = -5$$

$$c_2 = 3$$

Substituting these values back in above solution results in

$$y = 3xe^{-3x} + 3e^{-6x} - 5e^{-3x}$$

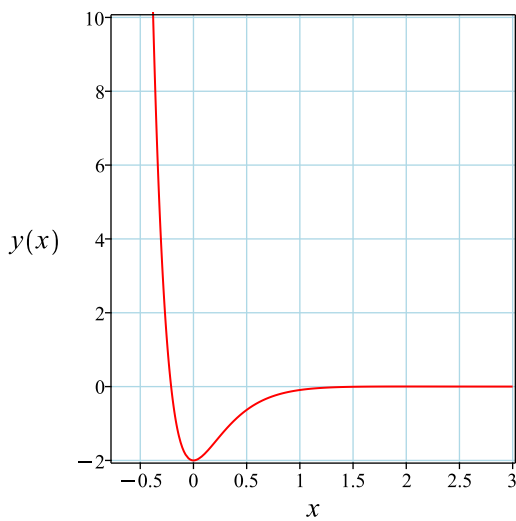
Which simplifies to

$$y = (3x - 5)e^{-3x} + 3e^{-6x}$$

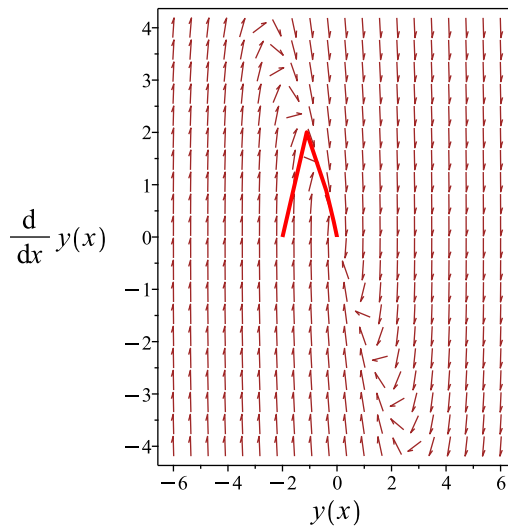
Summary

The solution(s) found are the following

$$y = (3x - 5)e^{-3x} + 3e^{-6x} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = (3x - 5)e^{-3x} + 3e^{-6x}$$

Verified OK.

11.30.5 Maple step by step solution

Let's solve

$$\left[y'' + 6y' + 9y = 27e^{-6x}, y(0) = -2, y' \Big|_{\{x=0\}} = 0 \right]$$

- Highest derivative means the order of the ODE is 2
- y''
- Characteristic polynomial of homogeneous ODE
- $r^2 + 6r + 9 = 0$
- Factor the characteristic polynomial
- $(r + 3)^2 = 0$
- Root of the characteristic polynomial
- $r = -3$
- 1st solution of the homogeneous ODE

$$y_1(x) = e^{-3x}$$

- Repeated root, multiply $y_1(x)$ by x to ensure linear independence

$$y_2(x) = x e^{-3x}$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = c_1 e^{-3x} + c_2 x e^{-3x} + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = 27 e^{-6x} \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} e^{-3x} & x e^{-3x} \\ -3 e^{-3x} & e^{-3x} - 3x e^{-3x} \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = e^{-6x}$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = -27 e^{-3x} \left(\int x e^{-3x} dx - \left(\int e^{-3x} dx \right) x \right)$$

- Compute integrals

$$y_p(x) = 3 e^{-6x}$$

- Substitute particular solution into general solution to ODE

$$y = c_1 e^{-3x} + c_2 x e^{-3x} + 3 e^{-6x}$$

- Check validity of solution $y = c_1 e^{-3x} + c_2 x e^{-3x} + 3 e^{-6x}$

- Use initial condition $y(0) = -2$

$$-2 = 3 + c_1$$

- Compute derivative of the solution

$$y' = -3c_1 e^{-3x} + c_2 e^{-3x} - 3c_2 x e^{-3x} - 18 e^{-6x}$$

- Use the initial condition $y' \Big|_{\{x=0\}} = 0$

$$0 = -18 - 3c_1 + c_2$$

- Solve for c_1 and c_2

$$\{c_1 = -5, c_2 = 3\}$$
- Substitute constant values into general solution and simplify
$$y = (3x - 5)e^{-3x} + 3e^{-6x}$$
- Solution to the IVP
$$y = (3x - 5)e^{-3x} + 3e^{-6x}$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
trying a double symmetry of the form [xi=0, eta=F(x)]
-> Try solving first the homogeneous part of the ODE
    checking if the LODE has constant coefficients
    <- constant coefficients successful
<- solving first the homogeneous part of the ODE successful`

```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 21

```
dsolve([diff(y(x),x$2)+6*diff(y(x),x)+9*y(x)=27*exp(-6*x),y(0) = -2, D(y)(0) = 0],y(x), sing
```

$$y(x) = (3x - 5)e^{-3x} + 3e^{-6x}$$

✓ Solution by Mathematica

Time used: 0.022 (sec). Leaf size: 24

```
DSolve[{y''[x]+6*y'[x]+9*y[x]==27*Exp[-6*x],{y[0]==-2,y'[0]==0}},y[x],x,IncludeSingularSolut
```

$$y(x) \rightarrow e^{-6x}(e^{3x}(3x - 5) + 3)$$

11.31 problem 31

11.31.1 Existence and uniqueness analysis	2565
11.31.2 Solving as second order linear constant coeff ode	2566
11.31.3 Solving using Kovacic algorithm	2570
11.31.4 Maple step by step solution	2575

Internal problem ID [11805]

Internal file name [OUTPUT/11814_Thursday_April_11_2024_08_49_56_PM_89938605/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 31.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$y'' + 4y' + 13y = 18e^{-2x}$$

With initial conditions

$$[y(0) = 0, y'(0) = 4]$$

11.31.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$p(x) = 4$$

$$q(x) = 13$$

$$F = 18e^{-2x}$$

Hence the ode is

$$y'' + 4y' + 13y = 18e^{-2x}$$

The domain of $p(x) = 4$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = 13$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. The domain of $F = 18e^{-2x}$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

11.31.2 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = 4, C = 13, f(x) = 18e^{-2x}$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 4y' + 13y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 4, C = 13$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + 4\lambda e^{\lambda x} + 13e^{\lambda x} = 0 \tag{1}$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 4\lambda + 13 = 0 \tag{2}$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 4, C = 13$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{-4}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{4^2 - (4)(1)(13)} \\ &= -2 \pm 3i \end{aligned}$$

Hence

$$\begin{aligned} \lambda_1 &= -2 + 3i \\ \lambda_2 &= -2 - 3i \end{aligned}$$

Which simplifies to

$$\begin{aligned} \lambda_1 &= -2 + 3i \\ \lambda_2 &= -2 - 3i \end{aligned}$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = -2$ and $\beta = 3$. Therefore the final solution, when using Euler relation, can be written as

$$y = e^{\alpha x} (c_1 \cos(\beta x) + c_2 \sin(\beta x))$$

Which becomes

$$y = e^{-2x} (c_1 \cos(3x) + c_2 \sin(3x))$$

Therefore the homogeneous solution y_h is

$$y_h = e^{-2x} (c_1 \cos(3x) + c_2 \sin(3x))$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$18 e^{-2x}$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$\{e^{-2x}\}$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^{-2x} \cos(3x), e^{-2x} \sin(3x)\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1 e^{-2x}$$

The unknowns $\{A_1\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$9A_1 e^{-2x} = 18 e^{-2x}$$

Solving for the unknowns by comparing coefficients results in

$$[A_1 = 2]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = 2 e^{-2x}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (e^{-2x}(c_1 \cos(3x) + c_2 \sin(3x))) + (2 e^{-2x}) \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = e^{-2x}(c_1 \cos(3x) + c_2 \sin(3x)) + 2 e^{-2x} \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 0$ and $x = 0$ in the above gives

$$0 = c_1 + 2 \tag{1A}$$

Taking derivative of the solution gives

$$y' = -2e^{-2x}(c_1 \cos(3x) + c_2 \sin(3x)) + e^{-2x}(-3c_1 \sin(3x) + 3c_2 \cos(3x)) - 4e^{-2x}$$

substituting $y' = 4$ and $x = 0$ in the above gives

$$4 = -2c_1 + 3c_2 - 4 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$\begin{aligned} c_1 &= -2 \\ c_2 &= \frac{4}{3} \end{aligned}$$

Substituting these values back in above solution results in

$$y = \frac{4e^{-2x} \sin(3x)}{3} - 2e^{-2x} \cos(3x) + 2e^{-2x}$$

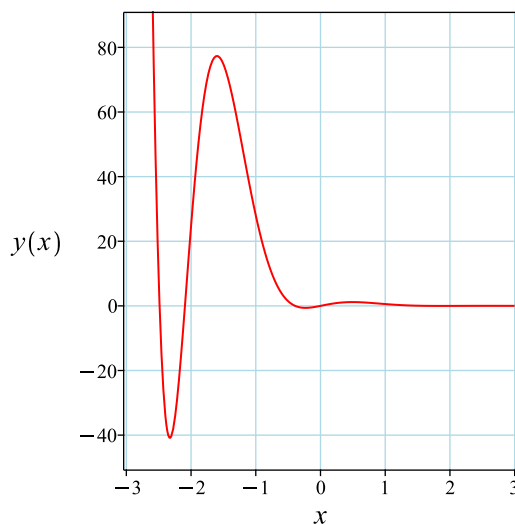
Which simplifies to

$$y = -\frac{2e^{-2x}(-3 - 2\sin(3x) + 3\cos(3x))}{3}$$

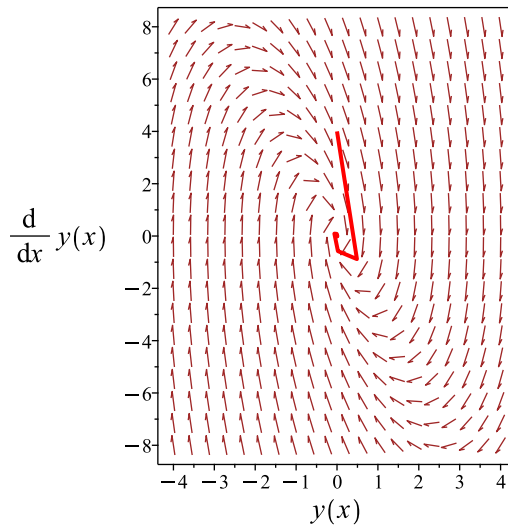
Summary

The solution(s) found are the following

$$y = -\frac{2e^{-2x}(-3 - 2\sin(3x) + 3\cos(3x))}{3} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = -\frac{2e^{-2x}(-3 - 2\sin(3x) + 3\cos(3x))}{3}$$

Verified OK.

11.31.3 Solving using Kovacic algorithm

Writing the ode as

$$y'' + 4y' + 13y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$A = 1$$

$$B = 4 \quad (3)$$

$$C = 13$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$r = \frac{s}{t} \quad (5)$$
$$= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-9}{1} \quad (6)$$

Comparing the above to (5) shows that

$$s = -9$$

$$t = 1$$

Therefore eq. (4) becomes

$$z''(x) = -9z(x) \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 391: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = -9$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = \cos(3x)$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned}y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\&= z_1 e^{-\int \frac{1}{2} \frac{4}{1} dx} \\&= z_1 e^{-2x} \\&= z_1 (e^{-2x})\end{aligned}$$

Which simplifies to

$$y_1 = e^{-2x} \cos(3x)$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{4}{1} dx}}{(y_1)^2} dx \\&= y_1 \int \frac{e^{-4x}}{(y_1)^2} dx \\&= y_1 \left(\frac{\tan(3x)}{3} \right)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\&= c_1 (e^{-2x} \cos(3x)) + c_2 \left(e^{-2x} \cos(3x) \left(\frac{\tan(3x)}{3} \right) \right)\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 4y' + 13y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1 e^{-2x} \cos(3x) + \frac{\sin(3x) e^{-2x} c_2}{3}$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$18 e^{-2x}$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{e^{-2x}\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\left\{ e^{-2x} \cos(3x), \frac{e^{-2x} \sin(3x)}{3} \right\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1 e^{-2x}$$

The unknowns $\{A_1\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$9A_1 e^{-2x} = 18 e^{-2x}$$

Solving for the unknowns by comparing coefficients results in

$$[A_1 = 2]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = 2 e^{-2x}$$

Therefore the general solution is

$$y = y_h + y_p \\ = \left(c_1 e^{-2x} \cos(3x) + \frac{\sin(3x) e^{-2x} c_2}{3} \right) + (2 e^{-2x})$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{-2x} \cos(3x) + \frac{\sin(3x) e^{-2x} c_2}{3} + 2 e^{-2x} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 0$ and $x = 0$ in the above gives

$$0 = c_1 + 2 \quad (1A)$$

Taking derivative of the solution gives

$$y' = -2c_1 e^{-2x} \cos(3x) - 3c_1 e^{-2x} \sin(3x) + \cos(3x) e^{-2x} c_2 - \frac{2 \sin(3x) e^{-2x} c_2}{3} - 4 e^{-2x}$$

substituting $y' = 4$ and $x = 0$ in the above gives

$$4 = -2c_1 - 4 + c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = -2$$

$$c_2 = 4$$

Substituting these values back in above solution results in

$$y = \frac{4 e^{-2x} \sin(3x)}{3} - 2 e^{-2x} \cos(3x) + 2 e^{-2x}$$

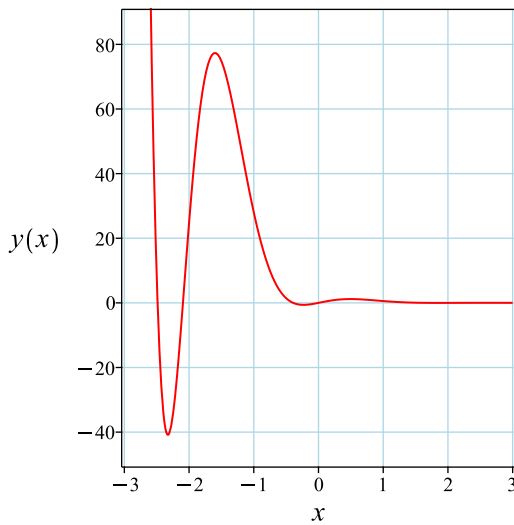
Which simplifies to

$$y = -\frac{2 e^{-2x} (-3 - 2 \sin(3x) + 3 \cos(3x))}{3}$$

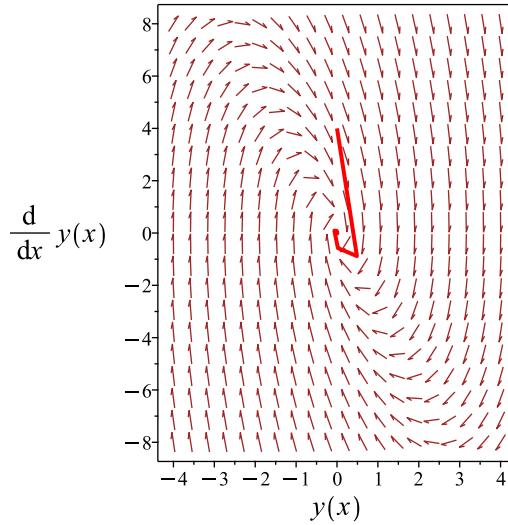
Summary

The solution(s) found are the following

$$y = -\frac{2 e^{-2x} (-3 - 2 \sin(3x) + 3 \cos(3x))}{3} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = -\frac{2e^{-2x}(-3 - 2\sin(3x) + 3\cos(3x))}{3}$$

Verified OK.

11.31.4 Maple step by step solution

Let's solve

$$\left[y'' + 4y' + 13y = 18e^{-2x}, y(0) = 0, y'|_{\{x=0\}} = 4 \right]$$

- Highest derivative means the order of the ODE is 2
- y''
- Characteristic polynomial of homogeneous ODE
- $r^2 + 4r + 13 = 0$
- Use quadratic formula to solve for r
- $r = \frac{(-4) \pm (\sqrt{-36})}{2}$
- Roots of the characteristic polynomial
- $r = (-2 - 3I, -2 + 3I)$
- 1st solution of the homogeneous ODE

$$y_1(x) = e^{-2x} \cos(3x)$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = e^{-2x} \sin(3x)$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = c_1 e^{-2x} \cos(3x) + \sin(3x) e^{-2x} c_2 + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = 18 e^{-2x} \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} e^{-2x} \cos(3x) & e^{-2x} \sin(3x) \\ -2e^{-2x} \cos(3x) - 3e^{-2x} \sin(3x) & -2e^{-2x} \sin(3x) + 3e^{-2x} \cos(3x) \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = 3e^{-4x}$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = -6e^{-2x} (\cos(3x) (\int \sin(3x) dx) - \sin(3x) (\int \cos(3x) dx))$$

- Compute integrals

$$y_p(x) = 2e^{-2x}$$

- Substitute particular solution into general solution to ODE

$$y = c_1 e^{-2x} \cos(3x) + \sin(3x) e^{-2x} c_2 + 2e^{-2x}$$

- Check validity of solution $y = c_1 e^{-2x} \cos(3x) + \sin(3x) e^{-2x} c_2 + 2e^{-2x}$

- Use initial condition $y(0) = 0$

$$0 = c_1 + 2$$

- Compute derivative of the solution

$$y' = -2c_1 e^{-2x} \cos(3x) - 3c_1 e^{-2x} \sin(3x) + 3 \cos(3x) e^{-2x} c_2 - 2 \sin(3x) e^{-2x} c_2 - 4e^{-2x}$$

- Use the initial condition $y' \Big|_{\{x=0\}} = 4$

$$4 = -2c_1 + 3c_2 - 4$$

- Solve for c_1 and c_2

$$\left\{ c_1 = -2, c_2 = \frac{4}{3} \right\}$$

- Substitute constant values into general solution and simplify

$$y = -\frac{2e^{-2x}(-3-2\sin(3x)+3\cos(3x))}{3}$$

- Solution to the IVP

$$y = -\frac{2e^{-2x}(-3-2\sin(3x)+3\cos(3x))}{3}$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
trying a double symmetry of the form [xi=0, eta=F(x)]
-> Try solving first the homogeneous part of the ODE
    checking if the LODE has constant coefficients
    <- constant coefficients successful
<- solving first the homogeneous part of the ODE successful`

```

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 24

```
dsolve([diff(y(x),x$2)+4*diff(y(x),x)+13*y(x)=18*exp(-2*x),y(0) = 0, D(y)(0) = 4],y(x), sing
```

$$y(x) = \frac{2e^{-2x}(2\sin(3x) - 3\cos(3x) + 3)}{3}$$

✓ Solution by Mathematica

Time used: 0.024 (sec). Leaf size: 28

```
DSolve[{y''[x]+4*y'[x]+13*y[x]==18*Exp[-2*x]},{y[0]==0,y'[0]==4},y[x],x,IncludeSingularSolut
```

$$y(x) \rightarrow \frac{1}{3}e^{-2x}(4\sin(3x) - 6\cos(3x) + 6)$$

11.32 problem 32

11.32.1 Existence and uniqueness analysis	2578
11.32.2 Solving as second order linear constant coeff ode	2579
11.32.3 Solving using Kovacic algorithm	2583
11.32.4 Maple step by step solution	2588

Internal problem ID [11806]

Internal file name [OUTPUT/11815_Thursday_April_11_2024_08_49_57_PM_19006565/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 32.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$y'' - 10y' + 29y = 8e^{5x}$$

With initial conditions

$$[y(0) = 0, y'(0) = 8]$$

11.32.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$p(x) = -10$$

$$q(x) = 29$$

$$F = 8e^{5x}$$

Hence the ode is

$$y'' - 10y' + 29y = 8e^{5x}$$

The domain of $p(x) = -10$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = 29$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. The domain of $F = 8e^{5x}$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

11.32.2 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = -10, C = 29, f(x) = 8e^{5x}$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' - 10y' + 29y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = -10, C = 29$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} - 10\lambda e^{\lambda x} + 29 e^{\lambda x} = 0 \tag{1}$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 - 10\lambda + 29 = 0 \tag{2}$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = -10, C = 29$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{10}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{-10^2 - (4)(1)(29)} \\ &= 5 \pm 2i \end{aligned}$$

Hence

$$\lambda_1 = 5 + 2i$$

$$\lambda_2 = 5 - 2i$$

Which simplifies to

$$\lambda_1 = 5 + 2i$$

$$\lambda_2 = 5 - 2i$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = 5$ and $\beta = 2$. Therefore the final solution, when using Euler relation, can be written as

$$y = e^{\alpha x} (c_1 \cos(\beta x) + c_2 \sin(\beta x))$$

Which becomes

$$y = e^{5x} (c_1 \cos(2x) + c_2 \sin(2x))$$

Therefore the homogeneous solution y_h is

$$y_h = e^{5x} (c_1 \cos(2x) + c_2 \sin(2x))$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$8e^{5x}$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{e^{5x}\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^{5x} \cos(2x), e^{5x} \sin(2x)\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1 e^{5x}$$

The unknowns $\{A_1\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$4A_1 e^{5x} = 8 e^{5x}$$

Solving for the unknowns by comparing coefficients results in

$$[A_1 = 2]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = 2 e^{5x}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (e^{5x}(c_1 \cos(2x) + c_2 \sin(2x))) + (2 e^{5x}) \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = e^{5x}(c_1 \cos(2x) + c_2 \sin(2x)) + 2 e^{5x} \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 0$ and $x = 0$ in the above gives

$$0 = c_1 + 2 \tag{1A}$$

Taking derivative of the solution gives

$$y' = 5e^{5x}(c_1 \cos(2x) + c_2 \sin(2x)) + e^{5x}(-2c_1 \sin(2x) + 2c_2 \cos(2x)) + 10e^{5x}$$

substituting $y' = 8$ and $x = 0$ in the above gives

$$8 = 5c_1 + 2c_2 + 10 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = -2$$

$$c_2 = 4$$

Substituting these values back in above solution results in

$$y = -2e^{5x} \cos(2x) + 4e^{5x} \sin(2x) + 2e^{5x}$$

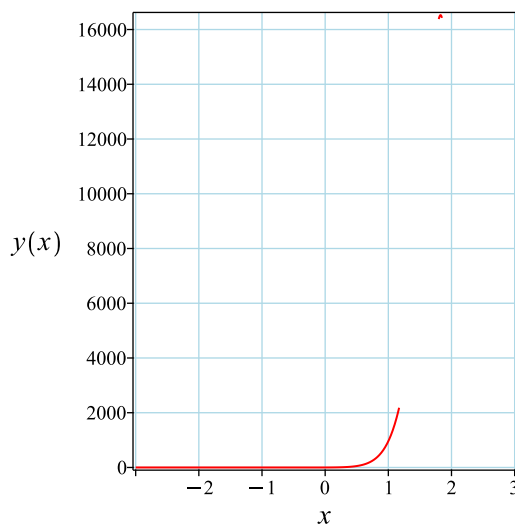
Which simplifies to

$$y = -2e^{5x}(-1 + \cos(2x) - 2\sin(2x))$$

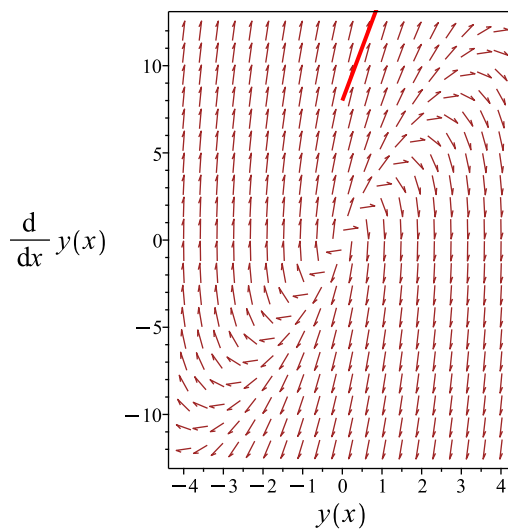
Summary

The solution(s) found are the following

$$y = -2e^{5x}(-1 + \cos(2x) - 2\sin(2x)) \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = -2e^{5x}(-1 + \cos(2x) - 2\sin(2x))$$

Verified OK.

11.32.3 Solving using Kovacic algorithm

Writing the ode as

$$y'' - 10y' + 29y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= -10 \\ C &= 29 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-4}{1} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= -4 \\ t &= 1 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = -4z(x) \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 393: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = -4$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = \cos(2x)$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-10}{1} dx} \end{aligned}$$

$$\begin{aligned}
&= z_1 e^{5x} \\
&= z_1 (e^{5x})
\end{aligned}$$

Which simplifies to

$$y_1 = e^{5x} \cos(2x)$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}
y_2 &= y_1 \int \frac{e^{\int -\frac{-10}{1} dx}}{(y_1)^2} dx \\
&= y_1 \int \frac{e^{10x}}{(y_1)^2} dx \\
&= y_1 \left(\frac{\tan(2x)}{2} \right)
\end{aligned}$$

Therefore the solution is

$$\begin{aligned}
y &= c_1 y_1 + c_2 y_2 \\
&= c_1 (e^{5x} \cos(2x)) + c_2 \left(e^{5x} \cos(2x) \left(\frac{\tan(2x)}{2} \right) \right)
\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' - 10y' + 29y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1 e^{5x} \cos(2x) + \frac{\sin(2x) e^{5x} c_2}{2}$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$8 e^{5x}$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{e^{5x}\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\left\{ e^{5x} \cos(2x), \frac{e^{5x} \sin(2x)}{2} \right\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1 e^{5x}$$

The unknowns $\{A_1\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$4A_1 e^{5x} = 8 e^{5x}$$

Solving for the unknowns by comparing coefficients results in

$$[A_1 = 2]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = 2 e^{5x}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(c_1 e^{5x} \cos(2x) + \frac{\sin(2x) e^{5x} c_2}{2} \right) + (2 e^{5x}) \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{5x} \cos(2x) + \frac{\sin(2x) e^{5x} c_2}{2} + 2 e^{5x} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 0$ and $x = 0$ in the above gives

$$0 = c_1 + 2 \quad (1A)$$

Taking derivative of the solution gives

$$y' = 5c_1 e^{5x} \cos(2x) - 2c_1 e^{5x} \sin(2x) + \cos(2x) e^{5x} c_2 + \frac{5 \sin(2x) e^{5x} c_2}{2} + 10 e^{5x}$$

substituting $y' = 8$ and $x = 0$ in the above gives

$$8 = 5c_1 + 10 + c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = -2$$

$$c_2 = 8$$

Substituting these values back in above solution results in

$$y = -2 e^{5x} \cos(2x) + 4 e^{5x} \sin(2x) + 2 e^{5x}$$

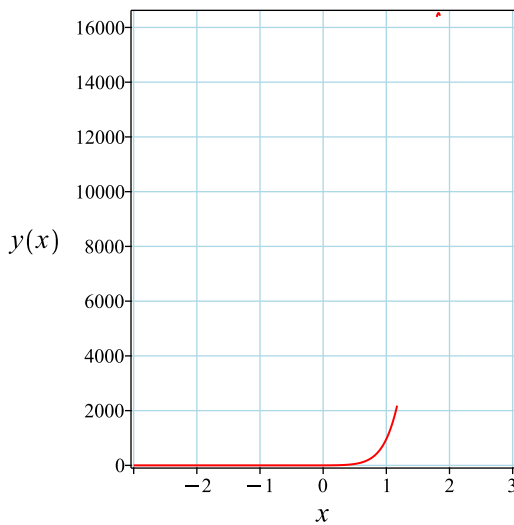
Which simplifies to

$$y = -2 e^{5x} (-1 + \cos(2x) - 2 \sin(2x))$$

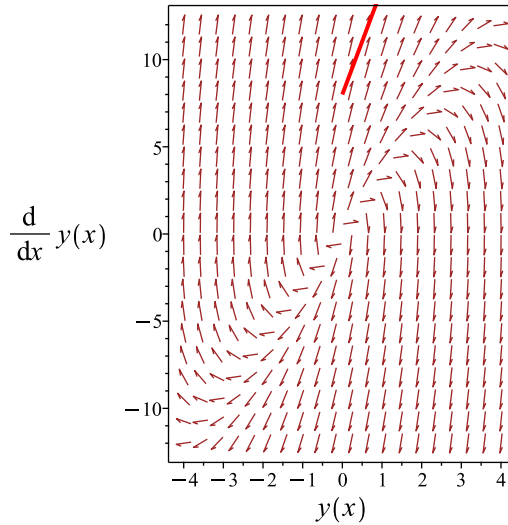
Summary

The solution(s) found are the following

$$y = -2 e^{5x} (-1 + \cos(2x) - 2 \sin(2x)) \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = -2 e^{5x}(-1 + \cos(2x) - 2 \sin(2x))$$

Verified OK.

11.32.4 Maple step by step solution

Let's solve

$$\left[y'' - 10y' + 29y = 8 e^{5x}, y(0) = 0, y'|_{\{x=0\}} = 8 \right]$$

- Highest derivative means the order of the ODE is 2
- y''
- Characteristic polynomial of homogeneous ODE
- $r^2 - 10r + 29 = 0$
- Use quadratic formula to solve for r
- $r = \frac{10 \pm (\sqrt{-16})}{2}$
- Roots of the characteristic polynomial
- $r = (5 - 2I, 5 + 2I)$
- 1st solution of the homogeneous ODE

$$y_1(x) = e^{5x} \cos(2x)$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = e^{5x} \sin(2x)$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = c_1 e^{5x} \cos(2x) + \sin(2x) e^{5x} c_2 + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = 8 e^{5x} \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} e^{5x} \cos(2x) & e^{5x} \sin(2x) \\ 5 e^{5x} \cos(2x) - 2 e^{5x} \sin(2x) & 5 e^{5x} \sin(2x) + 2 e^{5x} \cos(2x) \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = 2 e^{10x}$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = -4 e^{5x} (\cos(2x) (\int \sin(2x) dx) - \sin(2x) (\int \cos(2x) dx))$$

- Compute integrals

$$y_p(x) = 2 e^{5x}$$

- Substitute particular solution into general solution to ODE

$$y = c_1 e^{5x} \cos(2x) + \sin(2x) e^{5x} c_2 + 2 e^{5x}$$

- Check validity of solution $y = c_1 e^{5x} \cos(2x) + \sin(2x) e^{5x} c_2 + 2 e^{5x}$

- Use initial condition $y(0) = 0$

$$0 = c_1 + 2$$

- Compute derivative of the solution

$$y' = 5c_1 e^{5x} \cos(2x) - 2c_1 e^{5x} \sin(2x) + 2 \cos(2x) e^{5x} c_2 + 5 \sin(2x) e^{5x} c_2 + 10 e^{5x}$$

- Use the initial condition $y' \Big|_{\{x=0\}} = 8$

$$8 = 5c_1 + 2c_2 + 10$$

- Solve for c_1 and c_2

$$\{c_1 = -2, c_2 = 4\}$$
- Substitute constant values into general solution and simplify
$$y = -2e^{5x}(-1 + \cos(2x) - 2\sin(2x))$$
- Solution to the IVP
$$y = -2e^{5x}(-1 + \cos(2x) - 2\sin(2x))$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
trying a double symmetry of the form [xi=0, eta=F(x)]
-> Try solving first the homogeneous part of the ODE
    checking if the LODE has constant coefficients
    <- constant coefficients successful
<- solving first the homogeneous part of the ODE successful`

```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 22

```
dsolve([diff(y(x),x$2)-10*diff(y(x),x)+29*y(x)=8*exp(5*x),y(0) = 0, D(y)(0) = 8],y(x), sings
```

$$y(x) = -2e^{5x}(-1 - 2\sin(2x) + \cos(2x))$$

✓ Solution by Mathematica

Time used: 0.021 (sec). Leaf size: 24

```
DSolve[{y'[x]-10*y'[x]+29*y[x]==8*Exp[5*x],{y[0]==0,y'[0]==8}},y[x],x,IncludeSingularSoluti
```

$$y(x) \rightarrow -2e^{5x}(-2\sin(2x) + \cos(2x) - 1)$$

11.33 problem 33

11.33.1 Existence and uniqueness analysis	2591
11.33.2 Solving as second order linear constant coeff ode	2592
11.33.3 Solving using Kovacic algorithm	2596
11.33.4 Maple step by step solution	2602

Internal problem ID [11807]

Internal file name [OUTPUT/11816_Thursday_April_11_2024_08_49_58_PM_34915414/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 33.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' - 4y' + 13y = 8 \sin(3x)$$

With initial conditions

$$[y(0) = 1, y'(0) = 2]$$

11.33.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$p(x) = -4$$

$$q(x) = 13$$

$$F = 8 \sin(3x)$$

Hence the ode is

$$y'' - 4y' + 13y = 8 \sin(3x)$$

The domain of $p(x) = -4$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = 13$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. The domain of $F = 8 \sin(3x)$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

11.33.2 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = -4, C = 13, f(x) = 8 \sin(3x)$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' - 4y' + 13y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = -4, C = 13$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} - 4\lambda e^{\lambda x} + 13e^{\lambda x} = 0 \tag{1}$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 - 4\lambda + 13 = 0 \tag{2}$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = -4, C = 13$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{4}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{-4^2 - (4)(1)(13)} \\ &= 2 \pm 3i \end{aligned}$$

Hence

$$\lambda_1 = 2 + 3i$$

$$\lambda_2 = 2 - 3i$$

Which simplifies to

$$\lambda_1 = 2 + 3i$$

$$\lambda_2 = 2 - 3i$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = 2$ and $\beta = 3$. Therefore the final solution, when using Euler relation, can be written as

$$y = e^{\alpha x} (c_1 \cos(\beta x) + c_2 \sin(\beta x))$$

Which becomes

$$y = e^{2x} (c_1 \cos(3x) + c_2 \sin(3x))$$

Therefore the homogeneous solution y_h is

$$y_h = e^{2x} (c_1 \cos(3x) + c_2 \sin(3x))$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$8 \sin(3x)$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{\cos(3x), \sin(3x)\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^{2x} \cos(3x), e^{2x} \sin(3x)\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1 \cos(3x) + A_2 \sin(3x)$$

The unknowns $\{A_1, A_2\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$4A_1 \cos(3x) + 4A_2 \sin(3x) + 12A_1 \sin(3x) - 12A_2 \cos(3x) = 8 \sin(3x)$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = \frac{3}{5}, A_2 = \frac{1}{5} \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = \frac{3 \cos(3x)}{5} + \frac{\sin(3x)}{5}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (e^{2x}(c_1 \cos(3x) + c_2 \sin(3x))) + \left(\frac{3 \cos(3x)}{5} + \frac{\sin(3x)}{5} \right) \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = e^{2x}(c_1 \cos(3x) + c_2 \sin(3x)) + \frac{3 \cos(3x)}{5} + \frac{\sin(3x)}{5} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 1$ and $x = 0$ in the above gives

$$1 = c_1 + \frac{3}{5} \quad (1A)$$

Taking derivative of the solution gives

$$y' = 2e^{2x}(c_1 \cos(3x) + c_2 \sin(3x)) + e^{2x}(-3c_1 \sin(3x) + 3c_2 \cos(3x)) - \frac{9 \sin(3x)}{5} + \frac{3 \cos(3x)}{5}$$

substituting $y' = 2$ and $x = 0$ in the above gives

$$2 = 2c_1 + \frac{3}{5} + 3c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = \frac{2}{5}$$

$$c_2 = \frac{1}{5}$$

Substituting these values back in above solution results in

$$y = \frac{2e^{2x} \cos(3x)}{5} + \frac{e^{2x} \sin(3x)}{5} + \frac{3 \cos(3x)}{5} + \frac{\sin(3x)}{5}$$

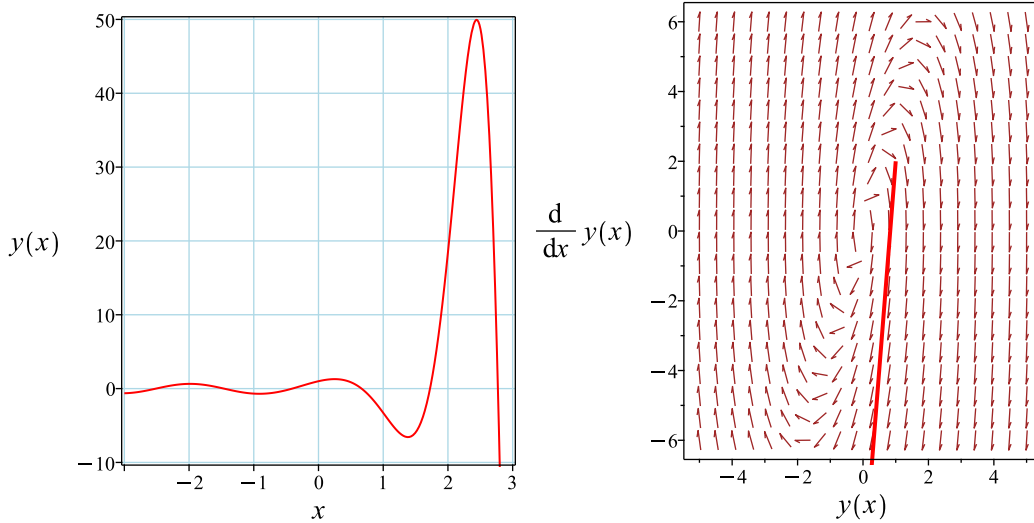
Which simplifies to

$$y = \frac{(2e^{2x} + 3) \cos(3x)}{5} + \frac{\sin(3x)(e^{2x} + 1)}{5}$$

Summary

The solution(s) found are the following

$$y = \frac{(2e^{2x} + 3) \cos(3x)}{5} + \frac{\sin(3x)(e^{2x} + 1)}{5} \quad (1)$$



(a) Solution plot

(b) Slope field plot

Verification of solutions

$$y = \frac{(2e^{2x} + 3) \cos(3x)}{5} + \frac{\sin(3x)(e^{2x} + 1)}{5}$$

Verified OK.

11.33.3 Solving using Kovacic algorithm

Writing the ode as

$$y'' - 4y' + 13y = 0 \tag{1}$$

$$Ay'' + By' + Cy = 0 \tag{2}$$

Comparing (1) and (2) shows that

$$A = 1$$

$$B = -4 \tag{3}$$

$$C = 13$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$r = \frac{s}{t} \tag{5}$$

$$= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-9}{1} \tag{6}$$

Comparing the above to (5) shows that

$$s = -9$$

$$t = 1$$

Therefore eq. (4) becomes

$$z''(x) = -9z(x) \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 395: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned}O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0\end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = -9$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = \cos(3x)$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned}y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-4}{1} dx} \\ &= z_1 e^{2x} \\ &= z_1 (e^{2x})\end{aligned}$$

Which simplifies to

$$y_1 = e^{2x} \cos(3x)$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{-4}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{4x}}{(y_1)^2} dx \\ &= y_1 \left(\frac{\tan(3x)}{3} \right)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (e^{2x} \cos(3x)) + c_2 \left(e^{2x} \cos(3x) \left(\frac{\tan(3x)}{3} \right) \right)\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' - 4y' + 13y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1 e^{2x} \cos(3x) + \frac{e^{2x} c_2 \sin(3x)}{3}$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$8 \sin(3x)$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{\cos(3x), \sin(3x)\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\left\{ e^{2x} \cos(3x), \frac{e^{2x} \sin(3x)}{3} \right\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1 \cos(3x) + A_2 \sin(3x)$$

The unknowns $\{A_1, A_2\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$4A_1 \cos(3x) + 4A_2 \sin(3x) + 12A_1 \sin(3x) - 12A_2 \cos(3x) = 8 \sin(3x)$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = \frac{3}{5}, A_2 = \frac{1}{5} \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = \frac{3 \cos(3x)}{5} + \frac{\sin(3x)}{5}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(c_1 e^{2x} \cos(3x) + \frac{e^{2x} c_2 \sin(3x)}{3} \right) + \left(\frac{3 \cos(3x)}{5} + \frac{\sin(3x)}{5} \right) \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{2x} \cos(3x) + \frac{e^{2x} c_2 \sin(3x)}{3} + \frac{3 \cos(3x)}{5} + \frac{\sin(3x)}{5} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 1$ and $x = 0$ in the above gives

$$1 = c_1 + \frac{3}{5} \quad (1A)$$

Taking derivative of the solution gives

$$y' = 2c_1 e^{2x} \cos(3x) - 3c_1 e^{2x} \sin(3x) + \frac{2e^{2x} c_2 \sin(3x)}{3} + e^{2x} c_2 \cos(3x) - \frac{9 \sin(3x)}{5} + \frac{3 \cos(3x)}{5}$$

substituting $y' = 2$ and $x = 0$ in the above gives

$$2 = 2c_1 + \frac{3}{5} + c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = \frac{2}{5}$$

$$c_2 = \frac{3}{5}$$

Substituting these values back in above solution results in

$$y = \frac{2 e^{2x} \cos(3x)}{5} + \frac{e^{2x} \sin(3x)}{5} + \frac{3 \cos(3x)}{5} + \frac{\sin(3x)}{5}$$

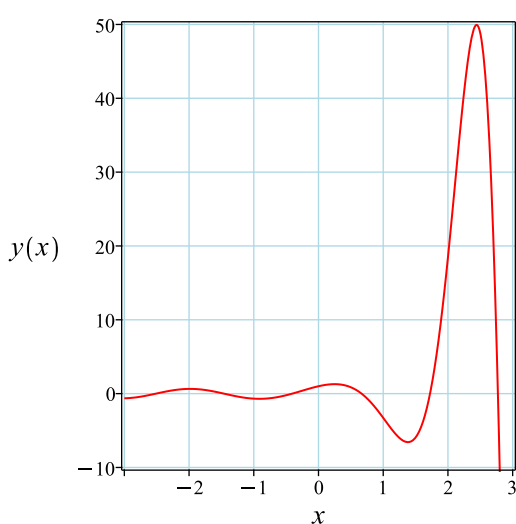
Which simplifies to

$$y = \frac{(2 e^{2x} + 3) \cos(3x)}{5} + \frac{\sin(3x) (e^{2x} + 1)}{5}$$

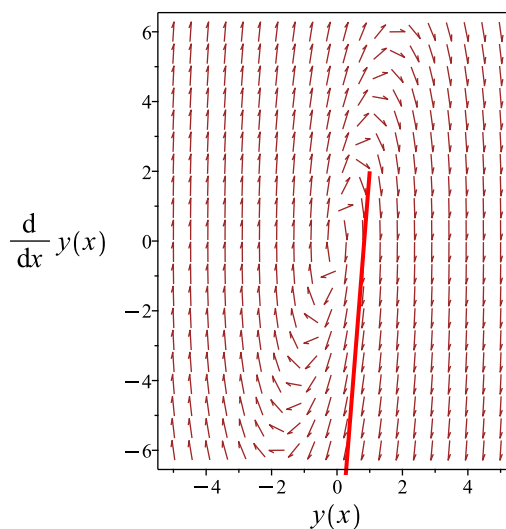
Summary

The solution(s) found are the following

$$y = \frac{(2 e^{2x} + 3) \cos(3x)}{5} + \frac{\sin(3x) (e^{2x} + 1)}{5} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = \frac{(2 e^{2x} + 3) \cos(3x)}{5} + \frac{\sin(3x) (e^{2x} + 1)}{5}$$

Verified OK.

11.33.4 Maple step by step solution

Let's solve

$$\left[y'' - 4y' + 13y = 8 \sin(3x), y(0) = 1, y'|_{\{x=0\}} = 2 \right]$$

- Highest derivative means the order of the ODE is 2
 y''

- Characteristic polynomial of homogeneous ODE

$$r^2 - 4r + 13 = 0$$

- Use quadratic formula to solve for r

$$r = \frac{4 \pm (\sqrt{-36})}{2}$$

- Roots of the characteristic polynomial

$$r = (2 - 3I, 2 + 3I)$$

- 1st solution of the homogeneous ODE

$$y_1(x) = e^{2x} \cos(3x)$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = e^{2x} \sin(3x)$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = c_1 e^{2x} \cos(3x) + e^{2x} c_2 \sin(3x) + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = 8 \sin(3x) \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} e^{2x} \cos(3x) & e^{2x} \sin(3x) \\ 2e^{2x} \cos(3x) - 3e^{2x} \sin(3x) & 2e^{2x} \sin(3x) + 3e^{2x} \cos(3x) \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = 3e^{4x}$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = \frac{4e^{2x}(-2\cos(3x)(\int e^{-2x}\sin(3x)^2 dx) + \sin(3x)(\int \sin(6x)e^{-2x} dx))}{3}$$

- Compute integrals

$$y_p(x) = \frac{3\cos(3x)}{5} + \frac{\sin(3x)}{5}$$

- Substitute particular solution into general solution to ODE

$$y = c_1 e^{2x} \cos(3x) + e^{2x} c_2 \sin(3x) + \frac{3\cos(3x)}{5} + \frac{\sin(3x)}{5}$$

- Check validity of solution $y = c_1 e^{2x} \cos(3x) + e^{2x} c_2 \sin(3x) + \frac{3\cos(3x)}{5} + \frac{\sin(3x)}{5}$

- Use initial condition $y(0) = 1$

$$1 = c_1 + \frac{3}{5}$$

- Compute derivative of the solution

$$y' = 2c_1 e^{2x} \cos(3x) - 3c_1 e^{2x} \sin(3x) + 2e^{2x} c_2 \sin(3x) + 3e^{2x} c_2 \cos(3x) - \frac{9\sin(3x)}{5} + \frac{3\cos(3x)}{5}$$

- Use the initial condition $y' \Big|_{\{x=0\}} = 2$

$$2 = 2c_1 + \frac{3}{5} + 3c_2$$

- Solve for c_1 and c_2

$$\{c_1 = \frac{2}{5}, c_2 = \frac{1}{5}\}$$

- Substitute constant values into general solution and simplify

$$y = \frac{(2e^{2x}+3)\cos(3x)}{5} + \frac{\sin(3x)(e^{2x}+1)}{5}$$

- Solution to the IVP

$$y = \frac{(2e^{2x}+3)\cos(3x)}{5} + \frac{\sin(3x)(e^{2x}+1)}{5}$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
trying a double symmetry of the form [xi=0, eta=F(x)]
-> Try solving first the homogeneous part of the ODE
    checking if the LODE has constant coefficients
    <- constant coefficients successful
<- solving first the homogeneous part of the ODE successful`

```

✓ Solution by Maple

Time used: 0.032 (sec). Leaf size: 31

```
dsolve([diff(y(x),x$2)-4*diff(y(x),x)+13*y(x)=8*sin(3*x),y(0) = 1, D(y)(0) = 2],y(x), singso
```

$$y(x) = \frac{(2e^{2x} + 3) \cos(3x)}{5} + \frac{\sin(3x)(e^{2x} + 1)}{5}$$

✓ Solution by Mathematica

Time used: 0.026 (sec). Leaf size: 36

```
DSolve[{y''[x]-4*y'[x]+13*y[x]==8*Sin[3*x]},{y[0]==1,y'[0]==2},y[x],x,IncludeSingularSolutio
```

$$y(x) \rightarrow \frac{1}{5}((e^{2x} + 1) \sin(3x) + (2e^{2x} + 3) \cos(3x))$$

11.34 problem 34

11.34.1 Existence and uniqueness analysis	2605
11.34.2 Solving as second order linear constant coeff ode	2606
11.34.3 Solving using Kovacic algorithm	2610
11.34.4 Maple step by step solution	2617

Internal problem ID [11808]

Internal file name [OUTPUT/11817_Thursday_April_11_2024_08_49_58_PM_20923427/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 34.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' - y' - 6y = 8e^{2x} - 5e^{3x}$$

With initial conditions

$$[y(0) = 3, y'(0) = 5]$$

11.34.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$p(x) = -1$$

$$q(x) = -6$$

$$F = 8e^{2x} - 5e^{3x}$$

Hence the ode is

$$y'' - y' - 6y = 8e^{2x} - 5e^{3x}$$

The domain of $p(x) = -1$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = -6$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. The domain of $F = 8e^{2x} - 5e^{3x}$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

11.34.2 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = -1, C = -6, f(x) = 8e^{2x} - 5e^{3x}$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' - y' - 6y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = -1, C = -6$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} - \lambda e^{\lambda x} - 6e^{\lambda x} = 0 \tag{1}$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 - \lambda - 6 = 0 \tag{2}$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = -1, C = -6$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{1}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{-1^2 - (4)(1)(-6)} \\ &= \frac{1}{2} \pm \frac{5}{2} \end{aligned}$$

Hence

$$\begin{aligned} \lambda_1 &= \frac{1}{2} + \frac{5}{2} \\ \lambda_2 &= \frac{1}{2} - \frac{5}{2} \end{aligned}$$

Which simplifies to

$$\begin{aligned} \lambda_1 &= 3 \\ \lambda_2 &= -2 \end{aligned}$$

Since roots are real and distinct, then the solution is

$$\begin{aligned} y &= c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x} \\ y &= c_1 e^{(3)x} + c_2 e^{(-2)x} \end{aligned}$$

Or

$$y = c_1 e^{3x} + c_2 e^{-2x}$$

Therefore the homogeneous solution y_h is

$$y_h = c_1 e^{3x} + c_2 e^{-2x}$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$8e^{2x} - 5e^{3x}$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{e^{2x}\}, \{e^{3x}\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^{-2x}, e^{3x}\}$$

Since e^{3x} is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[\{e^{2x}\}, \{x e^{3x}\}]$$

Since there was duplication between the basis functions in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis function in the above updated UC_set.

$$y_p = A_1 e^{2x} + A_2 x e^{3x}$$

The unknowns $\{A_1, A_2\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$-4A_1 e^{2x} + 5A_2 e^{3x} = 8e^{2x} - 5e^{3x}$$

Solving for the unknowns by comparing coefficients results in

$$[A_1 = -2, A_2 = -1]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = -2e^{2x} - x e^{3x}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 e^{3x} + c_2 e^{-2x}) + (-2e^{2x} - x e^{3x}) \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{3x} + c_2 e^{-2x} - 2e^{2x} - x e^{3x} \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 3$ and $x = 0$ in the above gives

$$3 = c_1 + c_2 - 2 \quad (1A)$$

Taking derivative of the solution gives

$$y' = 3c_1 e^{3x} - 2c_2 e^{-2x} - 4e^{2x} - e^{3x} - 3x e^{3x}$$

substituting $y' = 5$ and $x = 0$ in the above gives

$$5 = 3c_1 - 2c_2 - 5 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 4$$

$$c_2 = 1$$

Substituting these values back in above solution results in

$$y = -x e^{3x} - 2e^{2x} + 4e^{3x} + e^{-2x}$$

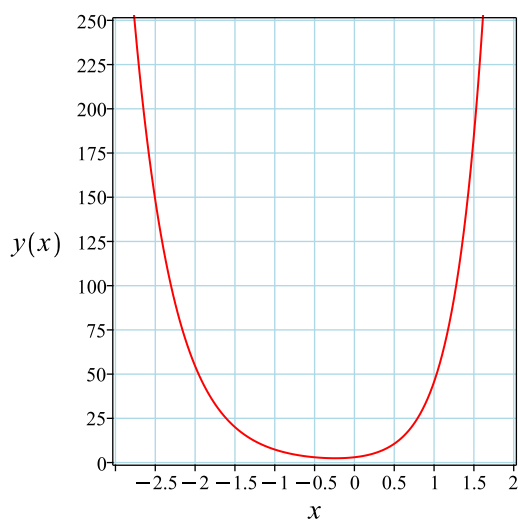
Which simplifies to

$$y = -((-4 + x) e^{5x} + 2e^{4x} - 1) e^{-2x}$$

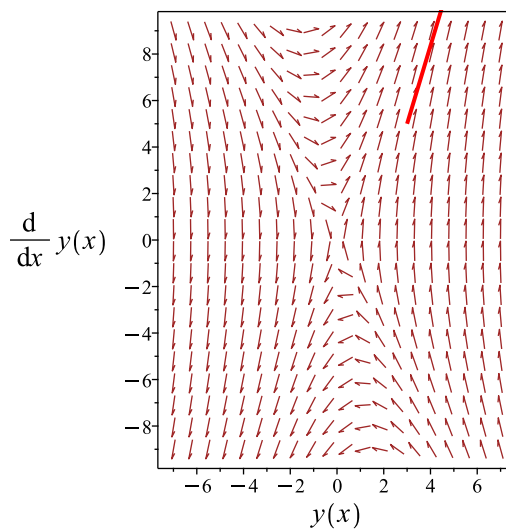
Summary

The solution(s) found are the following

$$y = -((-4 + x) e^{5x} + 2e^{4x} - 1) e^{-2x} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = -((-4 + x)e^{5x} + 2e^{4x} - 1)e^{-2x}$$

Verified OK.

11.34.3 Solving using Kovacic algorithm

Writing the ode as

$$y'' - y' - 6y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= -1 \\ C &= -6 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{25}{4} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 25 \\ t &= 4 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = \frac{25z(x)}{4} \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 397: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = \frac{25}{4}$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = e^{-\frac{5x}{2}}$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned}y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\&= z_1 e^{-\int \frac{1}{2} \frac{-1}{1} dx} \\&= z_1 e^{\frac{x}{2}} \\&= z_1 \left(e^{\frac{x}{2}} \right)\end{aligned}$$

Which simplifies to

$$y_1 = e^{-2x}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{-1}{1} dx}}{(y_1)^2} dx \\&= y_1 \int \frac{e^x}{(y_1)^2} dx \\&= y_1 \left(\frac{e^{5x}}{5} \right)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\&= c_1 (e^{-2x}) + c_2 \left(e^{-2x} \left(\frac{e^{5x}}{5} \right) \right)\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' - y' - 6y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1 e^{-2x} + \frac{e^{3x} c_2}{5}$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = e^{-2x}$$

$$y_2 = \frac{e^{3x}}{5}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \tag{2}$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \tag{3}$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} e^{-2x} & \frac{e^{3x}}{5} \\ \frac{d}{dx}(e^{-2x}) & \frac{d}{dx}\left(\frac{e^{3x}}{5}\right) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} e^{-2x} & \frac{e^{3x}}{5} \\ -2e^{-2x} & \frac{3e^{3x}}{5} \end{vmatrix}$$

Therefore

$$W = (e^{-2x}) \left(\frac{3e^{3x}}{5} \right) - \left(\frac{e^{3x}}{5} \right) (-2e^{-2x})$$

Which simplifies to

$$W = e^{3x} e^{-2x}$$

Which simplifies to

$$W = e^x$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{e^{3x}(8e^{2x} - 5e^{3x})}{e^x} dx$$

Which simplifies to

$$u_1 = - \int - \frac{e^{4x}(5e^x - 8)}{5} dx$$

Hence

$$u_1 = - \frac{2e^{4x}}{5} + \frac{e^{5x}}{5}$$

And Eq. (3) becomes

$$u_2 = \int \frac{e^{-2x}(8e^{2x} - 5e^{3x})}{e^x} dx$$

Which simplifies to

$$u_2 = \int (-5 + 8e^{-x}) dx$$

Hence

$$u_2 = -5x - 8e^{-x}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \left(-\frac{2e^{4x}}{5} + \frac{e^{5x}}{5} \right) e^{-2x} + \frac{(-5x - 8e^{-x})e^{3x}}{5}$$

Which simplifies to

$$y_p(x) = -2e^{2x} + \frac{e^{3x}}{5} - xe^{3x}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(c_1 e^{-2x} + \frac{e^{3x} c_2}{5} \right) + \left(-2e^{2x} + \frac{e^{3x}}{5} - xe^{3x} \right) \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{-2x} + \frac{e^{3x} c_2}{5} - 2e^{2x} + \frac{e^{3x}}{5} - xe^{3x} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 3$ and $x = 0$ in the above gives

$$3 = c_1 + \frac{c_2}{5} - \frac{9}{5} \quad (1A)$$

Taking derivative of the solution gives

$$y' = -2c_1 e^{-2x} + \frac{3e^{3x} c_2}{5} - 4e^{2x} - \frac{2e^{3x}}{5} - 3xe^{3x}$$

substituting $y' = 5$ and $x = 0$ in the above gives

$$5 = -2c_1 + \frac{3c_2}{5} - \frac{22}{5} \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 1$$

$$c_2 = 19$$

Substituting these values back in above solution results in

$$y = -x e^{3x} - 2 e^{2x} + 4 e^{3x} + e^{-2x}$$

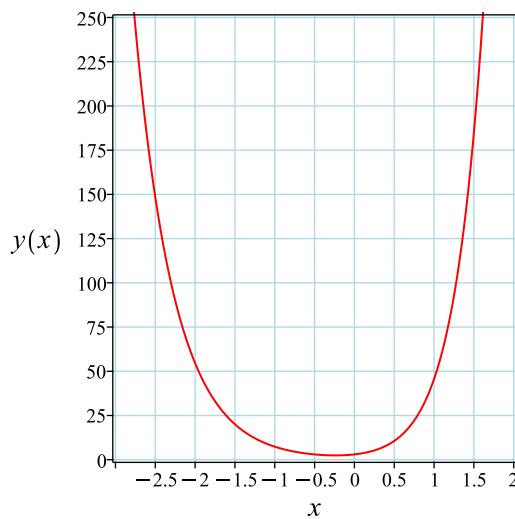
Which simplifies to

$$y = -((-4 + x) e^{5x} + 2 e^{4x} - 1) e^{-2x}$$

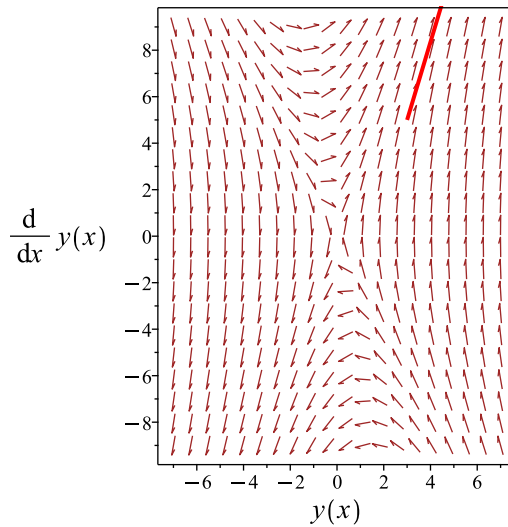
Summary

The solution(s) found are the following

$$y = -((-4 + x) e^{5x} + 2 e^{4x} - 1) e^{-2x} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = -((-4 + x) e^{5x} + 2 e^{4x} - 1) e^{-2x}$$

Verified OK.

11.34.4 Maple step by step solution

Let's solve

$$\left[y'' - y' - 6y = 8e^{2x} - 5e^{3x}, y(0) = 3, y'|_{\{x=0\}} = 5 \right]$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of homogeneous ODE

$$r^2 - r - 6 = 0$$

- Factor the characteristic polynomial

$$(r + 2)(r - 3) = 0$$

- Roots of the characteristic polynomial

$$r = (-2, 3)$$

- 1st solution of the homogeneous ODE

$$y_1(x) = e^{-2x}$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = e^{3x}$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = c_1 e^{-2x} + e^{3x} c_2 + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = 8e^{2x} - 5e^{3x} \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} e^{-2x} & e^{3x} \\ -2e^{-2x} & 3e^{3x} \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = 5e^x$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = \frac{(e^{5x}(\int(-5+8e^{-x})dx) + \int e^{4x}(5e^x-8)dx)e^{-2x}}{5}$$

- Compute integrals

$$y_p(x) = \frac{(-10+(-5x+1)e^x)e^{2x}}{5}$$

- Substitute particular solution into general solution to ODE

$$y = c_1e^{-2x} + e^{3x}c_2 + \frac{(-10+(-5x+1)e^x)e^{2x}}{5}$$

- Check validity of solution $y = c_1e^{-2x} + e^{3x}c_2 + \frac{(-10+(-5x+1)e^x)e^{2x}}{5}$

- Use initial condition $y(0) = 3$

$$3 = c_1 + c_2 - \frac{9}{5}$$

- Compute derivative of the solution

$$y' = -2c_1e^{-2x} + 3e^{3x}c_2 + \frac{(-5e^x+(-5x+1)e^x)e^{2x}}{5} + \frac{2(-10+(-5x+1)e^x)e^{2x}}{5}$$

- Use the initial condition $y' \Big|_{\{x=0\}} = 5$

$$5 = -2c_1 + 3c_2 - \frac{22}{5}$$

- Solve for c_1 and c_2

$$\{c_1 = 1, c_2 = \frac{19}{5}\}$$

- Substitute constant values into general solution and simplify

$$y = -((-4+x)e^{5x} + 2e^{4x} - 1)e^{-2x}$$

- Solution to the IVP

$$y = -((-4+x)e^{5x} + 2e^{4x} - 1)e^{-2x}$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
trying a double symmetry of the form [xi=0, eta=F(x)]
-> Try solving first the homogeneous part of the ODE
    checking if the LODE has constant coefficients
    <- constant coefficients successful
<- solving first the homogeneous part of the ODE successful`

```

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 28

```
dsolve([diff(y(x),x$2)-diff(y(x),x)-6*y(x)=8*exp(2*x)-5*exp(3*x),y(0) = 3, D(y)(0) = 5],y(x))
```

$$y(x) = -((-4 + x)e^{5x} + 2e^{4x} - 1)e^{-2x}$$

✓ Solution by Mathematica

Time used: 0.053 (sec). Leaf size: 28

```
DSolve[{y''[x]-y'[x]-6*y[x]==8*Exp[2*x]-5*Exp[3*x]},{y[0]==3,y'[0]==5}],y[x],x,IncludeSingularSolutions->True
```

$$y(x) \rightarrow -e^{3x}(x - 4) + e^{-2x} - 2e^{2x}$$

11.35 problem 35

11.35.1 Existence and uniqueness analysis	2621
11.35.2 Solving as second order linear constant coeff ode	2621
11.35.3 Solving as linear second order ode solved by an integrating factor ode	2625
11.35.4 Solving using Kovacic algorithm	2627
11.35.5 Maple step by step solution	2633

Internal problem ID [11809]

Internal file name [OUTPUT/11818_Thursday_April_11_2024_08_49_59_PM_2985471/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 35.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff", "linear_second_order_ode_solved_by_an_integrating_factor"

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' - 2y' + y = 2e^{2x}x + 6e^x$$

With initial conditions

$$[y(0) = 1, y'(0) = 0]$$

11.35.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$p(x) = -2$$

$$q(x) = 1$$

$$F = 2e^{2x}x + 6e^x$$

Hence the ode is

$$y'' - 2y' + y = 2e^{2x}x + 6e^x$$

The domain of $p(x) = -2$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = 1$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. The domain of $F = 2e^{2x}x + 6e^x$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

11.35.2 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = -2, C = 1, f(x) = 2e^{2x}x + 6e^x$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' - 2y' + y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = -2, C = 1$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} - 2\lambda e^{\lambda x} + e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 - 2\lambda + 1 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = -2, C = 1$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{2}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{(-2)^2 - (4)(1)(1)} \\ &= 1 \end{aligned}$$

Hence this is the case of a double root $\lambda_{1,2} = -1$. Therefore the solution is

$$y = c_1 e^x + c_2 x e^x \quad (1)$$

Therefore the homogeneous solution y_h is

$$y_h = e^x c_1 + c_2 x e^x$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$2e^{2x}x + 6e^x$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{e^x\}, \{e^{2x}x, e^{2x}\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{x e^x, e^x\}$$

Since e^x is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[\{x e^x\}, \{e^{2x}x, e^{2x}\}]$$

Since $x e^x$ is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[\{x^2 e^x\}, \{e^{2x}x, e^{2x}\}]$$

Since there was duplication between the basis functions in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis function in the above updated UC_set.

$$y_p = A_1 x^2 e^x + A_2 e^{2x} x + A_3 e^{2x}$$

The unknowns $\{A_1, A_2, A_3\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$2A_1 e^x + A_2 e^{2x} x + 2A_2 e^{2x} + A_3 e^{2x} = 2 e^{2x} x + 6 e^x$$

Solving for the unknowns by comparing coefficients results in

$$[A_1 = 3, A_2 = 2, A_3 = -4]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = 3x^2 e^x + 2 e^{2x} x - 4 e^{2x}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (e^x c_1 + c_2 x e^x) + (3x^2 e^x + 2 e^{2x} x - 4 e^{2x}) \end{aligned}$$

Which simplifies to

$$y = e^x (c_2 x + c_1) + 3x^2 e^x + 2 e^{2x} x - 4 e^{2x}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = e^x(c_2x + c_1) + 3x^2e^x + 2e^{2x}x - 4e^{2x} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 1$ and $x = 0$ in the above gives

$$1 = -4 + c_1 \quad (1A)$$

Taking derivative of the solution gives

$$y' = e^x(c_2x + c_1) + c_2e^x + 6xe^x + 3x^2e^x + 4e^{2x}x - 6e^{2x}$$

substituting $y' = 0$ and $x = 0$ in the above gives

$$0 = -6 + c_1 + c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 5$$

$$c_2 = 1$$

Substituting these values back in above solution results in

$$y = 3x^2e^x + 2e^{2x}x + xe^x - 4e^{2x} + 5e^x$$

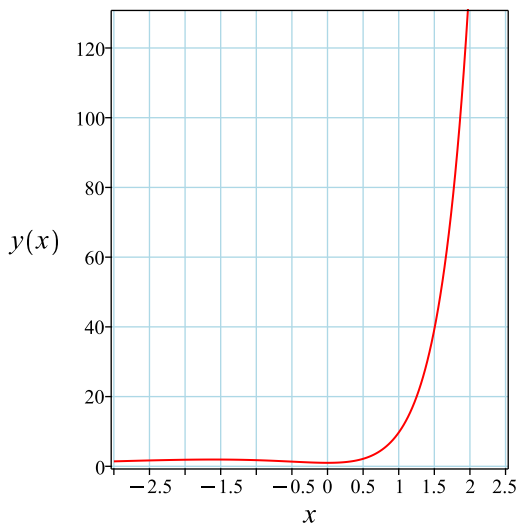
Which simplifies to

$$y = (2x - 4)e^{2x} + e^x(3x^2 + x + 5)$$

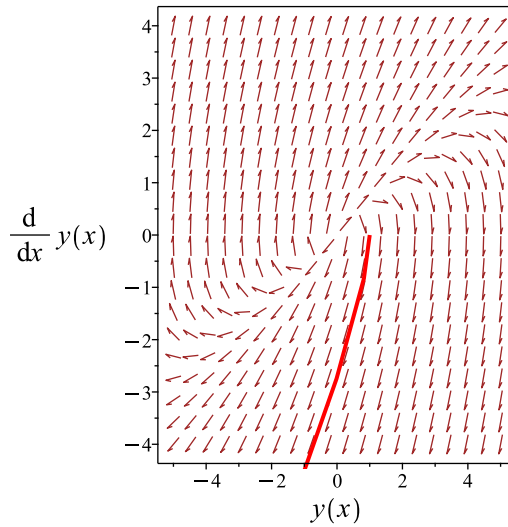
Summary

The solution(s) found are the following

$$y = (2x - 4)e^{2x} + e^x(3x^2 + x + 5) \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = (2x - 4) e^{2x} + e^x (3x^2 + x + 5)$$

Verified OK.

11.35.3 Solving as linear second order ode solved by an integrating factor ode

The ode satisfies this form

$$y'' + p(x) y' + \frac{(p(x)^2 + p'(x)) y}{2} = f(x)$$

Where $p(x) = -2$. Therefore, there is an integrating factor given by

$$\begin{aligned} M(x) &= e^{\frac{1}{2} \int p dx} \\ &= e^{\int -2 dx} \\ &= e^{-x} \end{aligned}$$

Multiplying both sides of the ODE by the integrating factor $M(x)$ makes the left side of the ODE a complete differential

$$\begin{aligned} (M(x)y)'' &= e^{-x} (2e^{2x}x + 6e^x) \\ (e^{-x}y)'' &= e^{-x} (2e^{2x}x + 6e^x) \end{aligned}$$

Integrating once gives

$$(e^{-x}y)' = (2x - 2)e^x + 6x + c_1$$

Integrating again gives

$$(e^{-x}y) = (2x - 4)e^x + 3x^2 + c_1x + c_2$$

Hence the solution is

$$y = \frac{(2x - 4)e^x + 3x^2 + c_1x + c_2}{e^{-x}}$$

Or

$$y = c_1x e^x + 3x^2 e^x + 2e^{2x}x + c_2e^x - 4e^{2x}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1x e^x + 3x^2 e^x + 2e^{2x}x + c_2e^x - 4e^{2x} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 1$ and $x = 0$ in the above gives

$$1 = -4 + c_2 \quad (1A)$$

Taking derivative of the solution gives

$$y' = e^x c_1 + c_1x e^x + 6x e^x + 3x^2 e^x - 6e^{2x} + 4e^{2x}x + c_2e^x$$

substituting $y' = 0$ and $x = 0$ in the above gives

$$0 = -6 + c_1 + c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 1$$

$$c_2 = 5$$

Substituting these values back in above solution results in

$$y = 3x^2 e^x + 2e^{2x}x + x e^x - 4e^{2x} + 5e^x$$

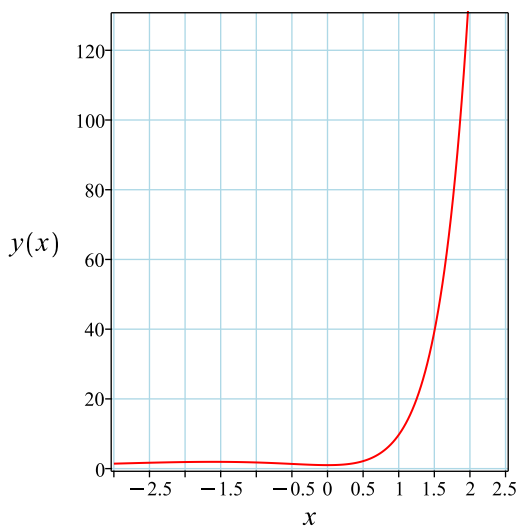
Which simplifies to

$$y = (2x - 4)e^{2x} + e^x(3x^2 + x + 5)$$

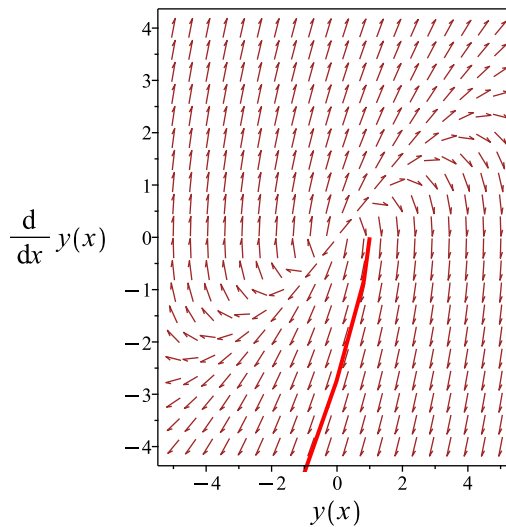
Summary

The solution(s) found are the following

$$y = (2x - 4)e^{2x} + e^x(3x^2 + x + 5) \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = (2x - 4)e^{2x} + e^x(3x^2 + x + 5)$$

Verified OK.

11.35.4 Solving using Kovacic algorithm

Writing the ode as

$$y'' - 2y' + y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= -2 \\ C &= 1 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$r = \frac{s}{t} = \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{0}{1} \tag{6}$$

Comparing the above to (5) shows that

$$s = 0 \\ t = 1$$

Therefore eq. (4) becomes

$$z''(x) = 0 \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 399: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned}O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - -\infty \\ &= \infty\end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is *infinity* then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = 0$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = 1$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned}y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-2}{1} dx} \\ &= z_1 e^x \\ &= z_1(e^x)\end{aligned}$$

Which simplifies to

$$y_1 = e^x$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{-2}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{2x}}{(y_1)^2} dx \\ &= y_1(x)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1(e^x) + c_2(e^x(x))\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' - 2y' + y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = e^x c_1 + c_2 x e^x$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$2e^{2x}x + 6e^x$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{e^x\}, \{e^{2x}x, e^{2x}\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{x e^x, e^x\}$$

Since e^x is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[\{x e^x\}, \{e^{2x}x, e^{2x}\}]$$

Since $x e^x$ is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[\{x^2 e^x\}, \{e^{2x}x, e^{2x}\}]$$

Since there was duplication between the basis functions in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis function in the above updated UC_set.

$$y_p = A_1 x^2 e^x + A_2 e^{2x} x + A_3 e^{2x}$$

The unknowns $\{A_1, A_2, A_3\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$2A_1 e^x + A_2 e^{2x} x + 2A_2 e^{2x} + A_3 e^{2x} = 2 e^{2x} x + 6 e^x$$

Solving for the unknowns by comparing coefficients results in

$$[A_1 = 3, A_2 = 2, A_3 = -4]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = 3x^2 e^x + 2 e^{2x} x - 4 e^{2x}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (e^x c_1 + c_2 x e^x) + (3x^2 e^x + 2 e^{2x} x - 4 e^{2x}) \end{aligned}$$

Which simplifies to

$$y = e^x (c_2 x + c_1) + 3x^2 e^x + 2 e^{2x} x - 4 e^{2x}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = e^x (c_2 x + c_1) + 3x^2 e^x + 2 e^{2x} x - 4 e^{2x} \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 1$ and $x = 0$ in the above gives

$$1 = -4 + c_1 \tag{1A}$$

Taking derivative of the solution gives

$$y' = e^x(c_2x + c_1) + c_2e^x + 6xe^x + 3x^2e^x + 4e^{2x}x - 6e^{2x}$$

substituting $y' = 0$ and $x = 0$ in the above gives

$$0 = -6 + c_1 + c_2 \tag{2A}$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 5$$

$$c_2 = 1$$

Substituting these values back in above solution results in

$$y = 3x^2e^x + 2e^{2x}x + xe^x - 4e^{2x} + 5e^x$$

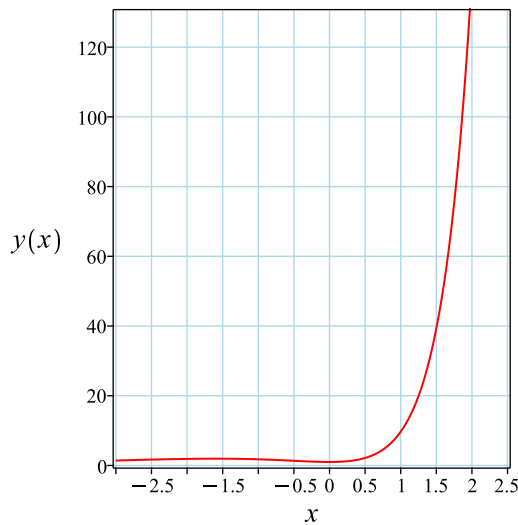
Which simplifies to

$$y = (2x - 4)e^{2x} + e^x(3x^2 + x + 5)$$

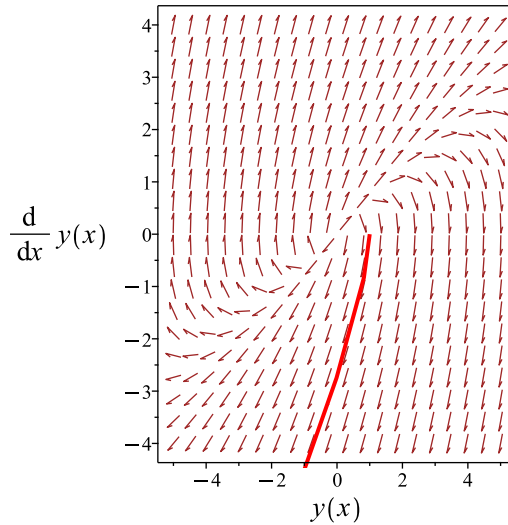
Summary

The solution(s) found are the following

$$y = (2x - 4)e^{2x} + e^x(3x^2 + x + 5) \tag{1}$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = (2x - 4)e^{2x} + e^x(3x^2 + x + 5)$$

Verified OK.

11.35.5 Maple step by step solution

Let's solve

$$\left[y'' - 2y' + y = 2e^{2x}x + 6e^x, y(0) = 1, y' \Big|_{\{x=0\}} = 0 \right]$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of homogeneous ODE

$$r^2 - 2r + 1 = 0$$

- Factor the characteristic polynomial

$$(r - 1)^2 = 0$$

- Root of the characteristic polynomial

$$r = 1$$

- 1st solution of the homogeneous ODE

$$y_1(x) = e^x$$

- Repeated root, multiply $y_1(x)$ by x to ensure linear independence

$$y_2(x) = x e^x$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = e^x c_1 + c_2 x e^x + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = 2e^{2x}x + 6e^x \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} e^x & x e^x \\ e^x & x e^x + e^x \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = e^{2x}$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = -2e^x \left(\int x(xe^x + 3) dx - \left(\int (xe^x + 3) dx \right) x \right)$$

- Compute integrals

$$y_p(x) = (2x - 4)(e^x)^2 + 3x^2e^x$$

- Substitute particular solution into general solution to ODE

$$y = e^x c_1 + c_2 x e^x + (2x - 4)(e^x)^2 + 3x^2 e^x$$

- Check validity of solution $y = e^x c_1 + c_2 x e^x + (2x - 4)(e^x)^2 + 3x^2 e^x$

- Use initial condition $y(0) = 1$

$$1 = -4 + c_1$$

- Compute derivative of the solution

$$y' = e^x c_1 + c_2 e^x + c_2 x e^x + 2(e^x)^2 + 2(2x - 4)(e^x)^2 + 6x e^x + 3x^2 e^x$$

- Use the initial condition $y' \Big|_{\{x=0\}} = 0$

$$0 = -6 + c_1 + c_2$$

- Solve for c_1 and c_2

$$\{c_1 = 5, c_2 = 1\}$$

- Substitute constant values into general solution and simplify

$$y = (2x - 4)e^{2x} + e^x(3x^2 + x + 5)$$

- Solution to the IVP

$$y = (2x - 4)e^{2x} + e^x(3x^2 + x + 5)$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
trying a double symmetry of the form [xi=0, eta=F(x)]
-> Try solving first the homogeneous part of the ODE
    checking if the LODE has constant coefficients
    <- constant coefficients successful
<- solving first the homogeneous part of the ODE successful`

```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 30

```
dsolve([diff(y(x),x$2)-2*diff(y(x),x)+y(x)=2*x*exp(2*x)+6*exp(x),y(0) = 1, D(y)(0) = 0],y(x))
```

$$y(x) = (2x - 4)e^{2x} + e^x(3x^2 + x + 5)$$

✓ Solution by Mathematica

Time used: 0.104 (sec). Leaf size: 25

```
DSolve[{y''[x]-2*y'[x]+y[x]==2*x*Exp[2*x]+6*Exp[x],{y[0]==1,y'[0]==0}},y[x],x,IncludeSingularSolutions->True]
```

$$y(x) \rightarrow e^x(3x^2 + x + 2e^x(x - 2) + 5)$$

11.36 problem 36

11.36.1 Existence and uniqueness analysis	2636
11.36.2 Solving as second order linear constant coeff ode	2637
11.36.3 Solving using Kovacic algorithm	2641
11.36.4 Maple step by step solution	2648

Internal problem ID [11810]

Internal file name [OUTPUT/11819_Thursday_April_11_2024_08_50_00_PM_59531729/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 36.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' - y = 3x^2e^x$$

With initial conditions

$$[y(0) = 1, y'(0) = 2]$$

11.36.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$\begin{aligned} p(x) &= 0 \\ q(x) &= -1 \\ F &= 3x^2e^x \end{aligned}$$

Hence the ode is

$$y'' - y = 3x^2e^x$$

The domain of $p(x) = 0$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = -1$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. The domain of $F = 3x^2e^x$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

11.36.2 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = 0, C = -1, f(x) = 3x^2e^x$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' - y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 0, C = -1$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} - e^{\lambda x} = 0 \tag{1}$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 - 1 = 0 \tag{2}$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 0, C = -1$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{0}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{0^2 - (4)(1)(-1)} \\ &= \pm 1 \end{aligned}$$

Hence

$$\lambda_1 = +1$$

$$\lambda_2 = -1$$

Which simplifies to

$$\lambda_1 = 1$$

$$\lambda_2 = -1$$

Since roots are real and distinct, then the solution is

$$y = c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x}$$

$$y = c_1 e^{(1)x} + c_2 e^{(-1)x}$$

Or

$$y = e^x c_1 + c_2 e^{-x}$$

Therefore the homogeneous solution y_h is

$$y_h = e^x c_1 + c_2 e^{-x}$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$3x^2 e^x$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{x e^x, x^2 e^x, e^x\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^x, e^{-x}\}$$

Since e^x is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[\{x e^x, x^2 e^x, x^3 e^x\}]$$

Since there was duplication between the basis functions in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis function in the above updated UC_set.

$$y_p = A_1 x e^x + A_2 x^2 e^x + A_3 x^3 e^x$$

The unknowns $\{A_1, A_2, A_3\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$2A_1 e^x + 2A_2 e^x + 4A_2 x e^x + 6A_3 x e^x + 6A_3 x^2 e^x = 3x^2 e^x$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = \frac{3}{4}, A_2 = -\frac{3}{4}, A_3 = \frac{1}{2} \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = \frac{3x e^x}{4} - \frac{3x^2 e^x}{4} + \frac{x^3 e^x}{2}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (e^x c_1 + c_2 e^{-x}) + \left(\frac{3x e^x}{4} - \frac{3x^2 e^x}{4} + \frac{x^3 e^x}{2} \right) \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = e^x c_1 + c_2 e^{-x} + \frac{3x e^x}{4} - \frac{3x^2 e^x}{4} + \frac{x^3 e^x}{2} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 1$ and $x = 0$ in the above gives

$$1 = c_1 + c_2 \quad (1A)$$

Taking derivative of the solution gives

$$y' = e^x c_1 - c_2 e^{-x} - \frac{3x e^x}{4} + \frac{3 e^x}{4} + \frac{3x^2 e^x}{4} + \frac{x^3 e^x}{2}$$

substituting $y' = 2$ and $x = 0$ in the above gives

$$2 = c_1 - c_2 + \frac{3}{4} \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = \frac{9}{8}$$

$$c_2 = -\frac{1}{8}$$

Substituting these values back in above solution results in

$$y = \frac{9 e^x}{8} - \frac{e^{-x}}{8} + \frac{3x e^x}{4} - \frac{3x^2 e^x}{4} + \frac{x^3 e^x}{2}$$

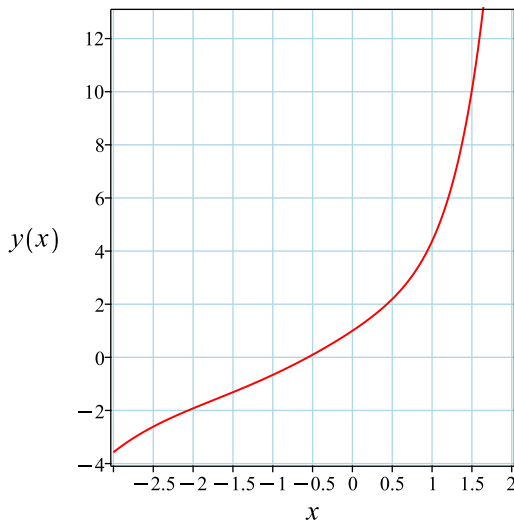
Which simplifies to

$$y = -\frac{e^{-x}}{8} + \frac{(4x^3 - 6x^2 + 6x + 9) e^x}{8}$$

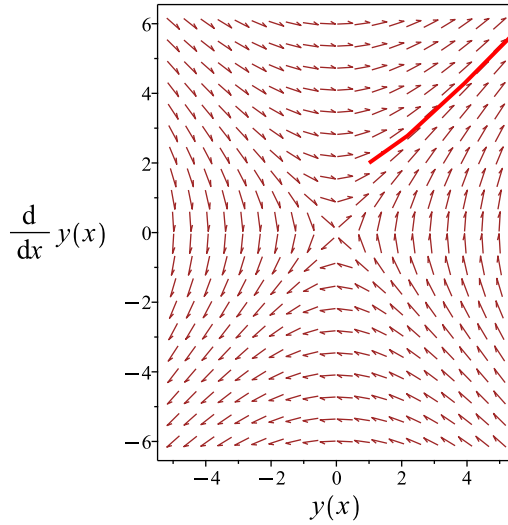
Summary

The solution(s) found are the following

$$y = -\frac{e^{-x}}{8} + \frac{(4x^3 - 6x^2 + 6x + 9) e^x}{8} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = -\frac{e^{-x}}{8} + \frac{(4x^3 - 6x^2 + 6x + 9)e^x}{8}$$

Verified OK.

11.36.3 Solving using Kovacic algorithm

Writing the ode as

$$y'' - y = 0 \tag{1}$$

$$Ay'' + By' + Cy = 0 \tag{2}$$

Comparing (1) and (2) shows that

$$A = 1$$

$$B = 0$$

$$C = -1$$

(3)

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$r = \frac{s}{t} \tag{5}$$

$$= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{1}{1} \tag{6}$$

Comparing the above to (5) shows that

$$s = 1$$

$$t = 1$$

Therefore eq. (4) becomes

$$z''(x) = z(x) \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 401: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = 1$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = e^{-x}$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$y_1 = z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx}$$

Since $B = 0$ then the above reduces to

$$\begin{aligned} y_1 &= z_1 \\ &= e^{-x} \end{aligned}$$

Which simplifies to

$$y_1 = e^{-x}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Since $B = 0$ then the above becomes

$$\begin{aligned} y_2 &= y_1 \int \frac{1}{y_1^2} dx \\ &= e^{-x} \int \frac{1}{e^{-2x}} dx \\ &= e^{-x} \left(\frac{e^{2x}}{2} \right) \end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1y_1 + c_2y_2 \\ &= c_1(e^{-x}) + c_2\left(e^{-x}\left(\frac{e^{2x}}{2}\right)\right)\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' - y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = \frac{c_2e^x}{2} + c_1e^{-x}$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1y_1 + u_2y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$\begin{aligned}y_1 &= e^{-x} \\ y_2 &= \frac{e^x}{2}\end{aligned}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2f(x)}{aW(x)} \tag{2}$$

$$u_2 = \int \frac{y_1f(x)}{aW(x)} \tag{3}$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} e^{-x} & \frac{e^x}{2} \\ \frac{d}{dx}(e^{-x}) & \frac{d}{dx}\left(\frac{e^x}{2}\right) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} e^{-x} & \frac{e^x}{2} \\ -e^{-x} & \frac{e^x}{2} \end{vmatrix}$$

Therefore

$$W = (e^{-x}) \left(\frac{e^x}{2}\right) - \left(\frac{e^x}{2}\right) (-e^{-x})$$

Which simplifies to

$$W = e^{-x}e^x$$

Which simplifies to

$$W = 1$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{3x^2e^{2x}}{1} dx$$

Which simplifies to

$$u_1 = - \int \frac{3x^2e^{2x}}{2} dx$$

Hence

$$u_1 = - \frac{3(2x^2 - 2x + 1)e^{2x}}{8}$$

And Eq. (3) becomes

$$u_2 = \int \frac{3e^{-x}x^2e^x}{1} dx$$

Which simplifies to

$$u_2 = \int 3x^2 dx$$

Hence

$$u_2 = x^3$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = -\frac{3(2x^2 - 2x + 1)e^{2x}e^{-x}}{8} + \frac{x^3e^x}{2}$$

Which simplifies to

$$y_p(x) = \frac{e^x(4x^3 - 6x^2 + 6x - 3)}{8}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(\frac{c_2 e^x}{2} + c_1 e^{-x} \right) + \left(\frac{e^x(4x^3 - 6x^2 + 6x - 3)}{8} \right) \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = \frac{c_2 e^x}{2} + c_1 e^{-x} + \frac{e^x(4x^3 - 6x^2 + 6x - 3)}{8} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 1$ and $x = 0$ in the above gives

$$1 = \frac{c_2}{2} + c_1 - \frac{3}{8} \quad (1A)$$

Taking derivative of the solution gives

$$y' = \frac{c_2 e^x}{2} - c_1 e^{-x} + \frac{e^x(4x^3 - 6x^2 + 6x - 3)}{8} + \frac{(12x^2 - 12x + 6)e^x}{8}$$

substituting $y' = 2$ and $x = 0$ in the above gives

$$2 = \frac{c_2}{2} - c_1 + \frac{3}{8} \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = -\frac{1}{8}$$

$$c_2 = 3$$

Substituting these values back in above solution results in

$$y = \frac{9e^x}{8} - \frac{e^{-x}}{8} + \frac{3xe^x}{4} - \frac{3x^2e^x}{4} + \frac{x^3e^x}{2}$$

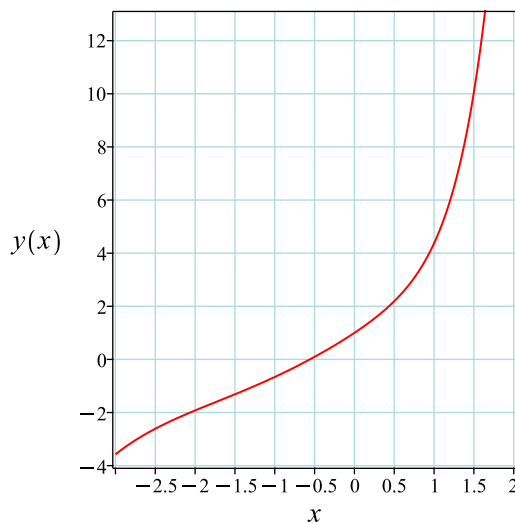
Which simplifies to

$$y = -\frac{e^{-x}}{8} + \frac{(4x^3 - 6x^2 + 6x + 9)e^x}{8}$$

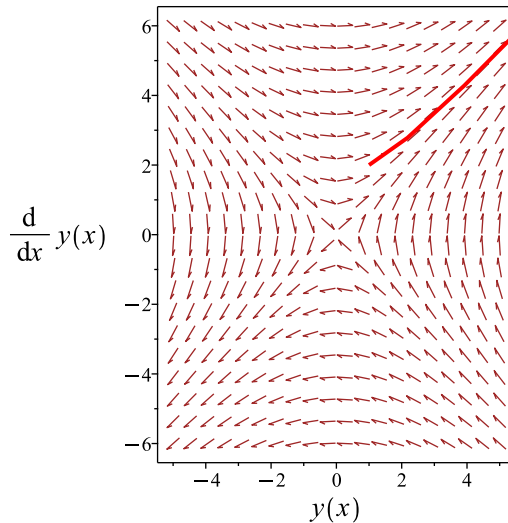
Summary

The solution(s) found are the following

$$y = -\frac{e^{-x}}{8} + \frac{(4x^3 - 6x^2 + 6x + 9)e^x}{8} \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = -\frac{e^{-x}}{8} + \frac{(4x^3 - 6x^2 + 6x + 9)e^x}{8}$$

Verified OK.

11.36.4 Maple step by step solution

Let's solve

$$\left[y'' - y = 3x^2e^x, y(0) = 1, y'|_{\{x=0\}} = 2 \right]$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of homogeneous ODE

$$r^2 - 1 = 0$$

- Factor the characteristic polynomial

$$(r - 1)(r + 1) = 0$$

- Roots of the characteristic polynomial

$$r = (-1, 1)$$

- 1st solution of the homogeneous ODE

$$y_1(x) = e^{-x}$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = e^x$$

- General solution of the ODE

$$y = c_1y_1(x) + c_2y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = c_1e^{-x} + c_2e^x + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = 3x^2e^x \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} e^{-x} & e^x \\ -e^{-x} & e^x \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = 2$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = -\frac{3e^{-x}(\int x^2 e^{2x} dx)}{2} + \frac{3e^x(\int x^2 dx)}{2}$$

- Compute integrals

$$y_p(x) = \frac{e^x(4x^3 - 6x^2 + 6x - 3)}{8}$$

- Substitute particular solution into general solution to ODE

$$y = c_1 e^{-x} + c_2 e^x + \frac{e^x(4x^3 - 6x^2 + 6x - 3)}{8}$$

- Check validity of solution $y = c_1 e^{-x} + c_2 e^x + \frac{e^x(4x^3 - 6x^2 + 6x - 3)}{8}$

- Use initial condition $y(0) = 1$

$$1 = c_1 + c_2 - \frac{3}{8}$$

- Compute derivative of the solution

$$y' = -c_1 e^{-x} + c_2 e^x + \frac{e^x(4x^3 - 6x^2 + 6x - 3)}{8} + \frac{(12x^2 - 12x + 6)e^x}{8}$$

- Use the initial condition $y'|_{\{x=0\}} = 2$

$$2 = -c_1 + c_2 + \frac{3}{8}$$

- Solve for c_1 and c_2

$$\left\{ c_1 = -\frac{1}{8}, c_2 = \frac{3}{2} \right\}$$

- Substitute constant values into general solution and simplify

$$y = -\frac{e^{-x}}{8} + \frac{(4x^3 - 6x^2 + 6x + 9)e^x}{8}$$

- Solution to the IVP

$$y = -\frac{e^{-x}}{8} + \frac{(4x^3 - 6x^2 + 6x + 9)e^x}{8}$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
trying a double symmetry of the form [xi=0, eta=F(x)]
-> Try solving first the homogeneous part of the ODE
    checking if the LODE has constant coefficients
    <- constant coefficients successful
<- solving first the homogeneous part of the ODE successful`

```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 30

```
dsolve([diff(y(x),x$2)-y(x)=3*x^2*exp(x),y(0) = 1, D(y)(0) = 2],y(x), singsol=all)
```

$$y(x) = -\frac{e^{-x}}{8} + \frac{(4x^3 - 6x^2 + 6x + 9)e^x}{8}$$

✓ Solution by Mathematica

Time used: 0.03 (sec). Leaf size: 37

```
DSolve[{y''[x]-y[x]==3*x^2*Exp[x],{y[0]==1,y'[0]==2}},y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{1}{8}e^{-x}(e^{2x}(4x^3 - 6x^2 + 6x + 9) - 1)$$

11.37 problem 37

11.37.1 Existence and uniqueness analysis	2651
11.37.2 Solving as second order linear constant coeff ode	2652
11.37.3 Solving using Kovacic algorithm	2656
11.37.4 Maple step by step solution	2661

Internal problem ID [11811]

Internal file name [OUTPUT/11820_Thursday_April_11_2024_08_50_01_PM_87746551/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 37.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"kovacic", "second_order_linear_constant_coeff"**

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' + y = 3x^2 - 4 \sin(x)$$

With initial conditions

$$[y(0) = 0, y'(0) = 1]$$

11.37.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$p(x) = 0$$

$$q(x) = 1$$

$$F = 3x^2 - 4 \sin(x)$$

Hence the ode is

$$y'' + y = 3x^2 - 4 \sin(x)$$

The domain of $p(x) = 0$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = 1$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. The domain of $F = 3x^2 - 4 \sin(x)$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

11.37.2 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = 0, C = 1, f(x) = 3x^2 - 4 \sin(x)$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 0, C = 1$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + e^{\lambda x} = 0 \tag{1}$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 1 = 0 \tag{2}$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 0, C = 1$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{0}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{0^2 - (4)(1)(1)} \\ &= \pm i \end{aligned}$$

Hence

$$\begin{aligned} \lambda_1 &= +i \\ \lambda_2 &= -i \end{aligned}$$

Which simplifies to

$$\begin{aligned} \lambda_1 &= i \\ \lambda_2 &= -i \end{aligned}$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = 0$ and $\beta = 1$. Therefore the final solution, when using Euler relation, can be written as

$$y = e^{\alpha x} (c_1 \cos(\beta x) + c_2 \sin(\beta x))$$

Which becomes

$$y = e^0 (c_1 \cos(x) + c_2 \sin(x))$$

Or

$$y = c_1 \cos(x) + c_2 \sin(x)$$

Therefore the homogeneous solution y_h is

$$y_h = c_1 \cos(x) + c_2 \sin(x)$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$3x^2 - 4 \sin(x)$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{\cos(x), \sin(x)\}, \{1, x, x^2\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{\cos(x), \sin(x)\}$$

Since $\cos(x)$ is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[\{x \sin(x), \cos(x)x\}, \{1, x, x^2\}]$$

Since there was duplication between the basis functions in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis function in the above updated UC_set.

$$y_p = A_1 x \sin(x) + A_2 \cos(x)x + A_3 + A_4 x + A_5 x^2$$

The unknowns $\{A_1, A_2, A_3, A_4, A_5\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$2A_1 \cos(x) - 2A_2 \sin(x) + 2A_5 + A_3 + A_4 x + A_5 x^2 = 3x^2 - 4 \sin(x)$$

Solving for the unknowns by comparing coefficients results in

$$[A_1 = 0, A_2 = 2, A_3 = -6, A_4 = 0, A_5 = 3]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = -6 + 2 \cos(x)x + 3x^2$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 \cos(x) + c_2 \sin(x)) + (-6 + 2 \cos(x)x + 3x^2) \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 \cos(x) + c_2 \sin(x) - 6 + 2 \cos(x)x + 3x^2 \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 0$ and $x = 0$ in the above gives

$$0 = c_1 - 6 \quad (1A)$$

Taking derivative of the solution gives

$$y' = -\sin(x) c_1 + c_2 \cos(x) - 2x \sin(x) + 2 \cos(x) + 6x$$

substituting $y' = 1$ and $x = 0$ in the above gives

$$1 = c_2 + 2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 6$$

$$c_2 = -1$$

Substituting these values back in above solution results in

$$y = -6 + 2 \cos(x) x + 3x^2 - \sin(x) + 6 \cos(x)$$

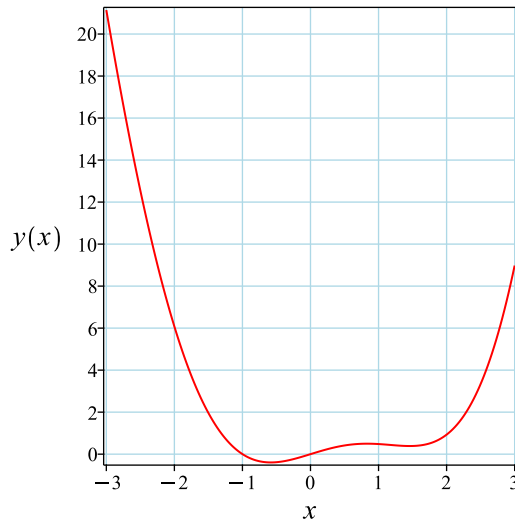
Which simplifies to

$$y = (2x + 6) \cos(x) + 3x^2 - \sin(x) - 6$$

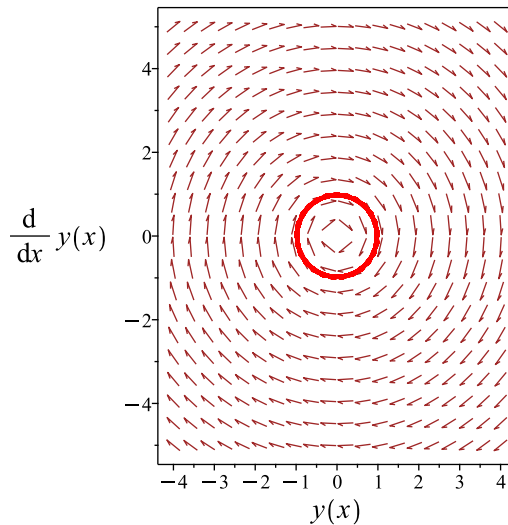
Summary

The solution(s) found are the following

$$y = (2x + 6) \cos(x) + 3x^2 - \sin(x) - 6 \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = (2x + 6) \cos(x) + 3x^2 - \sin(x) - 6$$

Verified OK.

11.37.3 Solving using Kovacic algorithm

Writing the ode as

$$y'' + y = 0 \tag{1}$$

$$Ay'' + By' + Cy = 0 \tag{2}$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= 0 \\ C &= 1 \end{aligned} \tag{3}$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-1}{1} \tag{6}$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= -1 \\ t &= 1 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = -z(x) \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 403: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = -1$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = \cos(x)$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$y_1 = z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx}$$

Since $B = 0$ then the above reduces to

$$\begin{aligned} y_1 &= z_1 \\ &= \cos(x) \end{aligned}$$

Which simplifies to

$$y_1 = \cos(x)$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Since $B = 0$ then the above becomes

$$\begin{aligned} y_2 &= y_1 \int \frac{1}{y_1^2} dx \\ &= \cos(x) \int \frac{1}{\cos(x)^2} dx \\ &= \cos(x) (\tan(x)) \end{aligned}$$

Therefore the solution is

$$\begin{aligned} y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (\cos(x)) + c_2 (\cos(x) (\tan(x))) \end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1 \cos(x) + c_2 \sin(x)$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$3x^2 - 4 \sin(x)$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{\cos(x), \sin(x)\}, \{1, x, x^2\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{\cos(x), \sin(x)\}$$

Since $\cos(x)$ is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[\{x \sin(x), \cos(x)x\}, \{1, x, x^2\}]$$

Since there was duplication between the basis functions in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis function in the above updated UC_set.

$$y_p = A_1 x \sin(x) + A_2 \cos(x)x + A_3 + A_4 x + A_5 x^2$$

The unknowns $\{A_1, A_2, A_3, A_4, A_5\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$2A_1 \cos(x) - 2A_2 \sin(x) + 2A_5 + A_3 + A_4 x + A_5 x^2 = 3x^2 - 4 \sin(x)$$

Solving for the unknowns by comparing coefficients results in

$$[A_1 = 0, A_2 = 2, A_3 = -6, A_4 = 0, A_5 = 3]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = -6 + 2 \cos(x)x + 3x^2$$

Therefore the general solution is

$$\begin{aligned}y &= y_h + y_p \\ &= (c_1 \cos(x) + c_2 \sin(x)) + (-6 + 2 \cos(x)x + 3x^2)\end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 \cos(x) + c_2 \sin(x) - 6 + 2 \cos(x)x + 3x^2 \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 0$ and $x = 0$ in the above gives

$$0 = c_1 - 6 \quad (1A)$$

Taking derivative of the solution gives

$$y' = -\sin(x)c_1 + c_2 \cos(x) - 2x \sin(x) + 2 \cos(x) + 6x$$

substituting $y' = 1$ and $x = 0$ in the above gives

$$1 = c_2 + 2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$\begin{aligned}c_1 &= 6 \\ c_2 &= -1\end{aligned}$$

Substituting these values back in above solution results in

$$y = -6 + 2 \cos(x)x + 3x^2 - \sin(x) + 6 \cos(x)$$

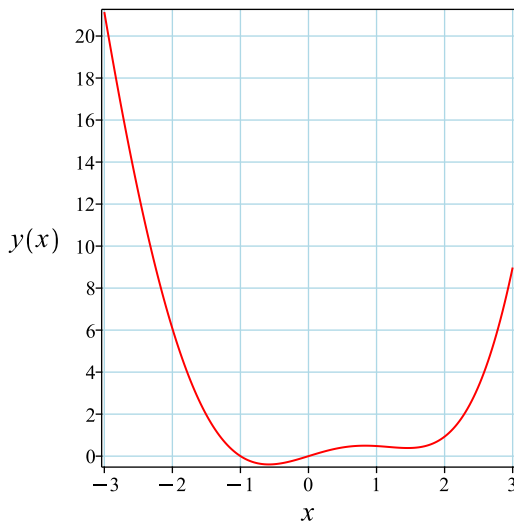
Which simplifies to

$$y = (2x + 6) \cos(x) + 3x^2 - \sin(x) - 6$$

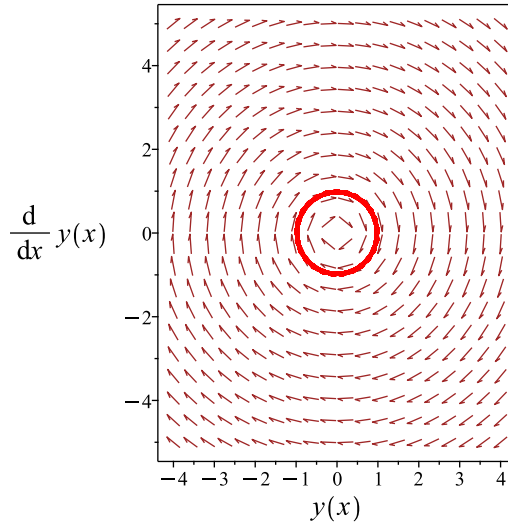
Summary

The solution(s) found are the following

$$y = (2x + 6) \cos(x) + 3x^2 - \sin(x) - 6 \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = (2x + 6) \cos(x) + 3x^2 - \sin(x) - 6$$

Verified OK.

11.37.4 Maple step by step solution

Let's solve

$$\left[y'' + y = 3x^2 - 4 \sin(x), y(0) = 0, y' \Big|_{\{x=0\}} = 1 \right]$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of homogeneous ODE

$$r^2 + 1 = 0$$

- Use quadratic formula to solve for r

$$r = \frac{0 \pm (\sqrt{-4})}{2}$$

- Roots of the characteristic polynomial

$$r = (-I, I)$$

- 1st solution of the homogeneous ODE

$$y_1(x) = \cos(x)$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = \sin(x)$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = c_1 \cos(x) + c_2 \sin(x) + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right) \right], f(x) = 3x^2 - 4 \sin(x)$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} \cos(x) & \sin(x) \\ -\sin(x) & \cos(x) \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = 1$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = \cos(x) \left(\int (4 \sin(x)^2 - 3 \sin(x) x^2) dx \right) - \sin(x) \left(\int \cos(x) (-3x^2 + 4 \sin(x)) dx \right)$$

- Compute integrals

$$y_p(x) = -6 + 2 \cos(x) x + 3x^2$$

- Substitute particular solution into general solution to ODE

$$y = c_1 \cos(x) + c_2 \sin(x) - 6 + 2 \cos(x) x + 3x^2$$

- Check validity of solution $y = c_1 \cos(x) + c_2 \sin(x) - 6 + 2 \cos(x) x + 3x^2$

- Use initial condition $y(0) = 0$

$$0 = c_1 - 6$$

- Compute derivative of the solution

$$y' = -\sin(x) c_1 + c_2 \cos(x) - 2x \sin(x) + 2 \cos(x) + 6x$$

- Use the initial condition $y' \Big|_{\{x=0\}} = 1$

$$1 = c_2 + 2$$

- Solve for c_1 and c_2

$$\{c_1 = 6, c_2 = -1\}$$
- Substitute constant values into general solution and simplify
$$y = (2x + 6) \cos(x) + 3x^2 - \sin(x) - 6$$
- Solution to the IVP
$$y = (2x + 6) \cos(x) + 3x^2 - \sin(x) - 6$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
trying a double symmetry of the form [xi=0, eta=F(x)]
-> Try solving first the homogeneous part of the ODE
    checking if the LODE has constant coefficients
    <- constant coefficients successful
<- solving first the homogeneous part of the ODE successful`

```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 24

```
dsolve([diff(y(x),x$2)+y(x)=3*x^2-4*sin(x),y(0) = 0, D(y)(0) = 1],y(x), singsol=all)
```

$$y(x) = (2x + 6) \cos(x) + 3x^2 - \sin(x) - 6$$

✓ Solution by Mathematica

Time used: 0.158 (sec). Leaf size: 23

```
DSolve[{y''[x]+y[x]==3*x^2-4*Sin[x],{y[0]==0,y'[0]==1}},y[x],x,IncludeSingularSolutions -> T
```

$$y(x) \rightarrow 3x^2 - \sin(x) + 2(x + 3) \cos(x) - 6$$

11.38 problem 38

11.38.1 Existence and uniqueness analysis	2664
11.38.2 Solving as second order linear constant coeff ode	2665
11.38.3 Solving using Kovacic algorithm	2669
11.38.4 Maple step by step solution	2674

Internal problem ID [11812]

Internal file name [OUTPUT/11821_Thursday_April_11_2024_08_50_01_PM_54548519/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 38.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' + 4y = 8 \sin(2x)$$

With initial conditions

$$[y(0) = 6, y'(0) = 8]$$

11.38.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$p(x) = 0$$

$$q(x) = 4$$

$$F = 8 \sin(2x)$$

Hence the ode is

$$y'' + 4y = 8 \sin(2x)$$

The domain of $p(x) = 0$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = 4$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. The domain of $F = 8 \sin(2x)$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

11.38.2 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = 0, C = 4, f(x) = 8 \sin(2x)$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 4y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 0, C = 4$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + 4 e^{\lambda x} = 0 \tag{1}$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 4 = 0 \tag{2}$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 0, C = 4$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{0}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{0^2 - (4)(1)(4)} \\ &= \pm 2i \end{aligned}$$

Hence

$$\lambda_1 = +2i$$

$$\lambda_2 = -2i$$

Which simplifies to

$$\lambda_1 = 2i$$

$$\lambda_2 = -2i$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = 0$ and $\beta = 2$. Therefore the final solution, when using Euler relation, can be written as

$$y = e^{\alpha x} (c_1 \cos(\beta x) + c_2 \sin(\beta x))$$

Which becomes

$$y = e^0 (c_1 \cos(2x) + c_2 \sin(2x))$$

Or

$$y = c_1 \cos(2x) + c_2 \sin(2x)$$

Therefore the homogeneous solution y_h is

$$y_h = c_1 \cos(2x) + c_2 \sin(2x)$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$8 \sin(2x)$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{\cos(2x), \sin(2x)\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{\cos(2x), \sin(2x)\}$$

Since $\cos(2x)$ is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[\{x \cos(2x), \sin(2x)x\}]$$

Since there was duplication between the basis functions in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis function in the above updated UC_set.

$$y_p = A_1 x \cos(2x) + A_2 \sin(2x)x$$

The unknowns $\{A_1, A_2\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$-4A_1 \sin(2x) + 4A_2 \cos(2x) = 8 \sin(2x)$$

Solving for the unknowns by comparing coefficients results in

$$[A_1 = -2, A_2 = 0]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = -2x \cos(2x)$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 \cos(2x) + c_2 \sin(2x)) + (-2x \cos(2x)) \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 \cos(2x) + c_2 \sin(2x) - 2x \cos(2x) \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 6$ and $x = 0$ in the above gives

$$6 = c_1 \quad (1A)$$

Taking derivative of the solution gives

$$y' = -2c_1 \sin(2x) + 2c_2 \cos(2x) - 2 \cos(2x) + 4 \sin(2x) x$$

substituting $y' = 8$ and $x = 0$ in the above gives

$$8 = -2 + 2c_2 \quad (2A)$$

Equations $\{1A, 2A\}$ are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 6$$

$$c_2 = 5$$

Substituting these values back in above solution results in

$$y = -2x \cos(2x) + 5 \sin(2x) + 6 \cos(2x)$$

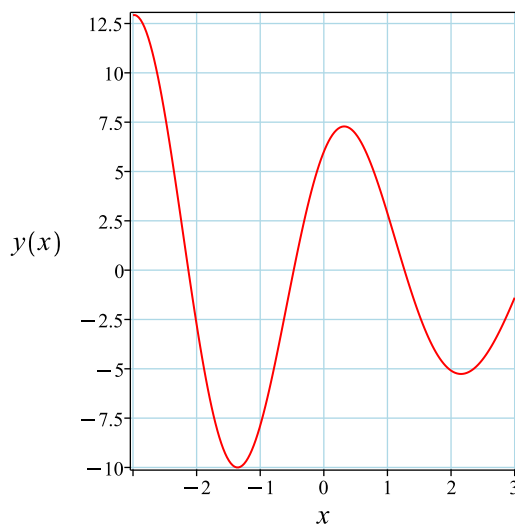
Which simplifies to

$$y = (-2x + 6) \cos(2x) + 5 \sin(2x)$$

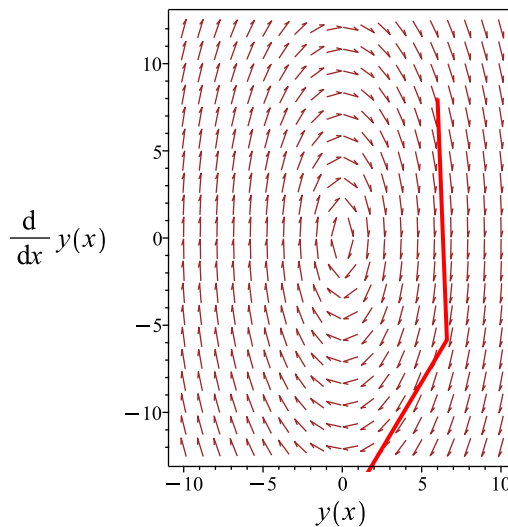
Summary

The solution(s) found are the following

$$y = (-2x + 6) \cos(2x) + 5 \sin(2x) \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = (-2x + 6) \cos(2x) + 5 \sin(2x)$$

Verified OK.

11.38.3 Solving using Kovacic algorithm

Writing the ode as

$$y'' + 4y = 0 \tag{1}$$

$$Ay'' + By' + Cy = 0 \tag{2}$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= 0 \\ C &= 4 \end{aligned} \tag{3}$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-4}{1} \tag{6}$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= -4 \\ t &= 1 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = -4z(x) \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
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Table 405: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = -4$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = \cos(2x)$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$y_1 = z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx}$$

Since $B = 0$ then the above reduces to

$$\begin{aligned} y_1 &= z_1 \\ &= \cos(2x) \end{aligned}$$

Which simplifies to

$$y_1 = \cos(2x)$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Since $B = 0$ then the above becomes

$$\begin{aligned} y_2 &= y_1 \int \frac{1}{y_1^2} dx \\ &= \cos(2x) \int \frac{1}{\cos(2x)^2} dx \\ &= \cos(2x) \left(\frac{\tan(2x)}{2} \right) \end{aligned}$$

Therefore the solution is

$$\begin{aligned} y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (\cos(2x)) + c_2 \left(\cos(2x) \left(\frac{\tan(2x)}{2} \right) \right) \end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

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Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

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The homogeneous solution is found using the Kovacic algorithm which results in

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While the set of the basis functions for the homogeneous solution found earlier is

$$\left\{ \frac{\sin(2x)}{2}, \cos(2x) \right\}$$

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The unknowns $\{A_1, A_2\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

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Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(c_1 \cos(2x) + \frac{c_2 \sin(2x)}{2} \right) + (-2x \cos(2x)) \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 \cos(2x) + \frac{c_2 \sin(2x)}{2} - 2x \cos(2x) \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 6$ and $x = 0$ in the above gives

$$6 = c_1 \quad (1A)$$

Taking derivative of the solution gives

$$y' = -2c_1 \sin(2x) + c_2 \cos(2x) - 2 \cos(2x) + 4 \sin(2x) x$$

substituting $y' = 8$ and $x = 0$ in the above gives

$$8 = c_2 - 2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 6$$

$$c_2 = 10$$

Substituting these values back in above solution results in

$$y = -2x \cos(2x) + 5 \sin(2x) + 6 \cos(2x)$$

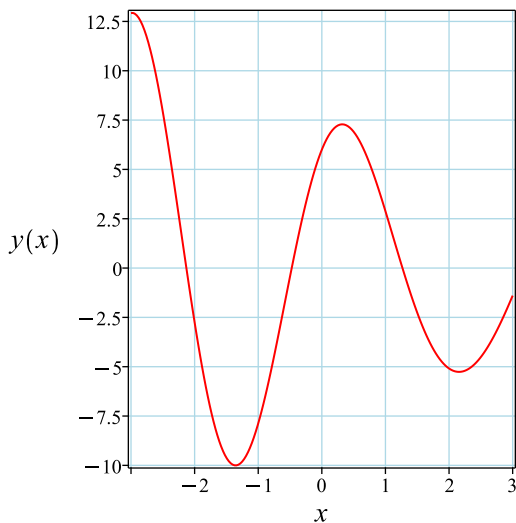
Which simplifies to

$$y = (-2x + 6) \cos(2x) + 5 \sin(2x)$$

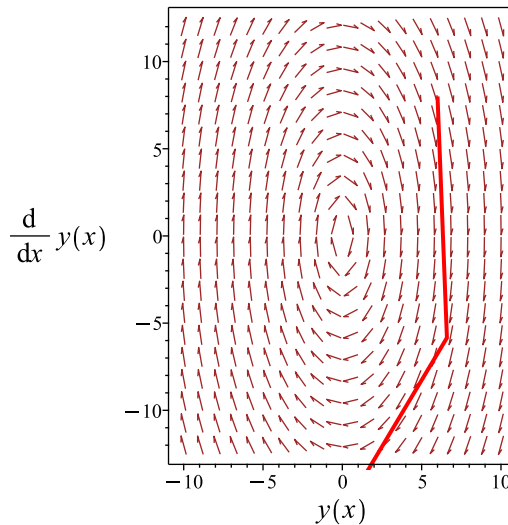
Summary

The solution(s) found are the following

$$y = (-2x + 6) \cos(2x) + 5 \sin(2x) \quad (1)$$



(a) Solution plot



(b) Slope field plot

Verification of solutions

$$y = (-2x + 6) \cos(2x) + 5 \sin(2x)$$

Verified OK.

11.38.4 Maple step by step solution

Let's solve

$$\left[y'' + 4y = 8 \sin(2x), y(0) = 6, y'|_{\{x=0\}} = 8 \right]$$

- Highest derivative means the order of the ODE is 2

y''

- Characteristic polynomial of homogeneous ODE

$$r^2 + 4 = 0$$

- Use quadratic formula to solve for r

$$r = \frac{0 \pm (\sqrt{-16})}{2}$$

- Roots of the characteristic polynomial
 $r = (-2I, 2I)$
- 1st solution of the homogeneous ODE
 $y_1(x) = \cos(2x)$
- 2nd solution of the homogeneous ODE
 $y_2(x) = \sin(2x)$
- General solution of the ODE
 $y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$
- Substitute in solutions of the homogeneous ODE
 $y = c_1 \cos(2x) + c_2 \sin(2x) + y_p(x)$
- Find a particular solution $y_p(x)$ of the ODE
 - Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = 8 \sin(2x) \right]$$
 - Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} \cos(2x) & \sin(2x) \\ -2 \sin(2x) & 2 \cos(2x) \end{bmatrix}$$
 - Compute Wronskian
 $W(y_1(x), y_2(x)) = 2$
 - Substitute functions into equation for $y_p(x)$
 $y_p(x) = -2 \cos(2x) \left(\int (1 - \cos(4x)) dx \right) + 2 \sin(2x) \left(\int \sin(4x) dx \right)$
 - Compute integrals
 $y_p(x) = \frac{\sin(2x)}{2} - 2x \cos(2x)$
- Substitute particular solution into general solution to ODE
 $y = c_1 \cos(2x) + c_2 \sin(2x) + \frac{\sin(2x)}{2} - 2x \cos(2x)$
- Check validity of solution $y = c_1 \cos(2x) + c_2 \sin(2x) + \frac{\sin(2x)}{2} - 2x \cos(2x)$
 - Use initial condition $y(0) = 6$
 $6 = c_1$
 - Compute derivative of the solution
 $y' = -2c_1 \sin(2x) + 2c_2 \cos(2x) - \cos(2x) + 4 \sin(2x) x$

- Use the initial condition $y' \Big|_{\{x=0\}} = 8$

$$8 = -1 + 2c_2$$
- Solve for c_1 and c_2

$$\{c_1 = 6, c_2 = \frac{9}{2}\}$$
- Substitute constant values into general solution and simplify
$$y = (-2x + 6) \cos(2x) + 5 \sin(2x)$$
- Solution to the IVP
$$y = (-2x + 6) \cos(2x) + 5 \sin(2x)$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
trying a double symmetry of the form [xi=0, eta=F(x)]
-> Try solving first the homogeneous part of the ODE
    checking if the LODE has constant coefficients
    <- constant coefficients successful
<- solving first the homogeneous part of the ODE successful`

```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 21

```
dsolve([diff(y(x),x$2)+4*y(x)=8*sin(2*x),y(0) = 6, D(y)(0) = 8],y(x), singsol=all)
```

$$y(x) = (-2x + 6) \cos(2x) + 5 \sin(2x)$$

✓ Solution by Mathematica

Time used: 0.108 (sec). Leaf size: 19

```
DSolve[{y''[x]+4*y[x]==8*Sin[2*x],{y[0]==0,y'[0]==1}},y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow 3 \sin(x) \cos(x) - 2x \cos(2x)$$

11.39 problem 39

11.39.1 Maple step by step solution 2681

Internal problem ID [11813]

Internal file name [OUTPUT/11822_Thursday_April_11_2024_08_50_02_PM_7433673/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 39.

ODE order: 3.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

`[[_3rd_order , _linear , _nonhomogeneous]]`

$$y''' - 4y'' + y' + 6y = 3x e^x + 2 e^x - \sin(x)$$

With initial conditions

$$\left[y(0) = \frac{33}{40}, y'(0) = 0, y''(0) = 0 \right]$$

This is higher order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE And y_p is a particular solution to the nonhomogeneous ODE. y_h is the solution to

$$y''' - 4y'' + y' + 6y = 0$$

The characteristic equation is

$$\lambda^3 - 4\lambda^2 + \lambda + 6 = 0$$

The roots of the above equation are

$$\lambda_1 = 2$$

$$\lambda_2 = 3$$

$$\lambda_3 = -1$$

Therefore the homogeneous solution is

$$y_h(x) = c_1 e^{-x} + c_2 e^{2x} + c_3 e^{3x}$$

The fundamental set of solutions for the homogeneous solution are the following

$$y_1 = e^{-x}$$

$$y_2 = e^{2x}$$

$$y_3 = e^{3x}$$

Now the particular solution to the given ODE is found

$$y''' - 4y'' + y' + 6y = 3x e^x + 2 e^x - \sin(x)$$

The particular solution is found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$3x e^x + 2 e^x - \sin(x)$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{x e^x, e^x\}, \{\cos(x), \sin(x)\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^{-x}, e^{2x}, e^{3x}\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1 x e^x + A_2 e^x + A_3 \cos(x) + A_4 \sin(x)$$

The unknowns $\{A_1, A_2, A_3, A_4\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$-4A_1 e^x + 4A_1 x e^x + 4A_2 e^x + 10A_3 \cos(x) + 10A_4 \sin(x) = 3x e^x + 2 e^x - \sin(x)$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = \frac{3}{4}, A_2 = \frac{5}{4}, A_3 = 0, A_4 = -\frac{1}{10} \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = \frac{3x e^x}{4} + \frac{5 e^x}{4} - \frac{\sin(x)}{10}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 e^{-x} + c_2 e^{2x} + c_3 e^{3x}) + \left(\frac{3x e^x}{4} + \frac{5 e^x}{4} - \frac{\sin(x)}{10} \right) \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 e^{-x} + c_2 e^{2x} + c_3 e^{3x} + \frac{3x e^x}{4} + \frac{5 e^x}{4} - \frac{\sin(x)}{10} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = \frac{33}{40}$ and $x = 0$ in the above gives

$$\frac{33}{40} = c_1 + c_2 + c_3 + \frac{5}{4} \quad (1A)$$

Taking derivative of the solution gives

$$y' = -c_1 e^{-x} + 2c_2 e^{2x} + 3c_3 e^{3x} + \frac{3x e^x}{4} + 2e^x - \frac{\cos(x)}{10}$$

substituting $y' = 0$ and $x = 0$ in the above gives

$$0 = -c_1 + 2c_2 + 3c_3 + \frac{19}{10} \quad (2A)$$

Taking two derivatives of the solution gives

$$y'' = c_1 e^{-x} + 4c_2 e^{2x} + 9c_3 e^{3x} + \frac{3x e^x}{4} + \frac{11 e^x}{4} + \frac{\sin(x)}{10}$$

substituting $y'' = 0$ and $x = 0$ in the above gives

$$0 = c_1 + 4c_2 + 9c_3 + \frac{11}{4} \quad (3A)$$

Equations {1A,2A,3A} are now solved for $\{c_1, c_2, c_3\}$. Solving for the constants gives

$$\begin{aligned}c_1 &= \frac{7}{20} \\c_2 &= -\frac{31}{40} \\c_3 &= 0\end{aligned}$$

Substituting these values back in above solution results in

$$y = \frac{7 e^{-x}}{20} - \frac{31 e^{2x}}{40} + \frac{3x e^x}{4} + \frac{5 e^x}{4} - \frac{\sin(x)}{10}$$

Summary

The solution(s) found are the following

$$y = \frac{7 e^{-x}}{20} - \frac{31 e^{2x}}{40} + \frac{3x e^x}{4} + \frac{5 e^x}{4} - \frac{\sin(x)}{10} \quad (1)$$

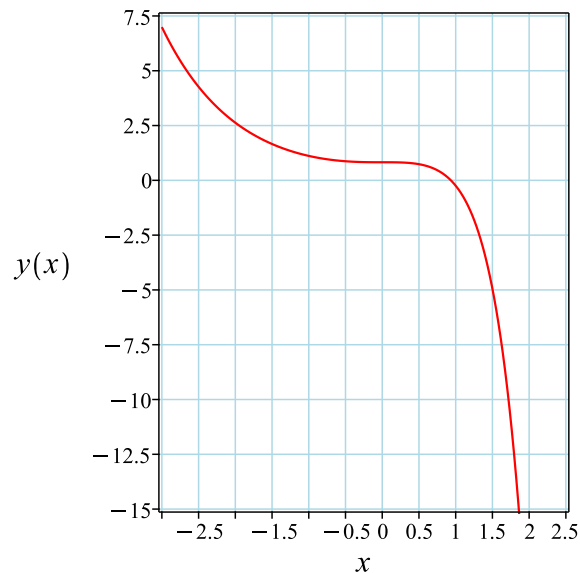


Figure 471: Solution plot

Verification of solutions

$$y = \frac{7 e^{-x}}{20} - \frac{31 e^{2x}}{40} + \frac{3x e^x}{4} + \frac{5 e^x}{4} - \frac{\sin(x)}{10}$$

Verified OK.

11.39.1 Maple step by step solution

Let's solve

$$\left[y''' - 4y'' + y' + 6y = 3x e^x + 2 e^x - \sin(x), y(0) = \frac{33}{40}, y'|_{\{x=0\}} = 0, y''|_{\{x=0\}} = 0 \right]$$

- Highest derivative means the order of the ODE is 3

y'''

- Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(x)$

$$y_1(x) = y$$

- Define new variable $y_2(x)$

$$y_2(x) = y'$$

- Define new variable $y_3(x)$

$$y_3(x) = y''$$

- Isolate for $y_3'(x)$ using original ODE

$$y_3'(x) = 3x e^x + 2 e^x - \sin(x) + 4y_3(x) - y_2(x) - 6y_1(x)$$

Convert linear ODE into a system of first order ODEs

$$[y_2(x) = y_1'(x), y_3(x) = y_2'(x), y_3'(x) = 3x e^x + 2 e^x - \sin(x) + 4y_3(x) - y_2(x) - 6y_1(x)]$$

- Define vector

$$\vec{y}(x) = \begin{bmatrix} y_1(x) \\ y_2(x) \\ y_3(x) \end{bmatrix}$$

- System to solve

$$\vec{y}'(x) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -6 & -1 & 4 \end{bmatrix} \cdot \vec{y}(x) + \begin{bmatrix} 0 \\ 0 \\ 3x e^x + 2 e^x - \sin(x) \end{bmatrix}$$

- Define the forcing function

$$\vec{f}(x) = \begin{bmatrix} 0 \\ 0 \\ 3x e^x + 2 e^x - \sin(x) \end{bmatrix}$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -6 & -1 & 4 \end{bmatrix}$$

- Rewrite the system as

$$\vec{y}'(x) = A \cdot \vec{y}(x) + \vec{f}$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[-1, \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \right], \left[2, \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right], \left[3, \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[-1, \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_1 = e^{-x} \cdot \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[2, \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_2 = e^{2x} \cdot \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[3, \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_3 = e^{3x} \cdot \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix}$$

- General solution of the system of ODEs can be written in terms of the particular solution $\vec{y}_p(x)$

$$\vec{y}(x) = c_1 \vec{y}_1 + c_2 \vec{y}_2 + c_3 \vec{y}_3 + \vec{y}_p(x)$$

- Fundamental matrix

- Let $\phi(x)$ be the matrix whose columns are the independent solutions of the homogeneous system

$$\phi(x) = \begin{bmatrix} e^{-x} & \frac{e^{2x}}{4} & \frac{e^{3x}}{9} \\ -e^{-x} & \frac{e^{2x}}{2} & \frac{e^{3x}}{3} \\ e^{-x} & e^{2x} & e^{3x} \end{bmatrix}$$

- The fundamental matrix, $\Phi(x)$ is a normalized version of $\phi(x)$ satisfying $\Phi(0) = I$ where I is the identity matrix

$$\Phi(x) = \phi(x) \cdot \frac{1}{\phi(0)}$$

- Substitute the value of $\phi(x)$ and $\phi(0)$

$$\Phi(x) = \begin{bmatrix} e^{-x} & \frac{e^{2x}}{4} & \frac{e^{3x}}{9} \\ -e^{-x} & \frac{e^{2x}}{2} & \frac{e^{3x}}{3} \\ e^{-x} & e^{2x} & e^{3x} \end{bmatrix} \cdot \frac{1}{\begin{bmatrix} 1 & \frac{1}{4} & \frac{1}{9} \\ -1 & \frac{1}{2} & \frac{1}{3} \\ 1 & 1 & 1 \end{bmatrix}}$$

- Evaluate and simplify to get the fundamental matrix

$$\Phi(x) = \begin{bmatrix} \frac{e^{-x}}{2} + e^{2x} - \frac{e^{3x}}{2} & -\frac{5e^{-x}}{12} + \frac{2e^{2x}}{3} - \frac{e^{3x}}{4} & \frac{e^{-x}}{12} - \frac{e^{2x}}{3} + \frac{e^{3x}}{4} \\ -\frac{e^{-x}}{2} + 2e^{2x} - \frac{3e^{3x}}{2} & \frac{5e^{-x}}{12} + \frac{4e^{2x}}{3} - \frac{3e^{3x}}{4} & -\frac{e^{-x}}{12} - \frac{2e^{2x}}{3} + \frac{3e^{3x}}{4} \\ \frac{e^{-x}}{2} + 4e^{2x} - \frac{9e^{3x}}{2} & -\frac{5e^{-x}}{12} + \frac{8e^{2x}}{3} - \frac{9e^{3x}}{4} & \frac{e^{-x}}{12} - \frac{4e^{2x}}{3} + \frac{9e^{3x}}{4} \end{bmatrix}$$

- Find a particular solution of the system of ODEs using variation of parameters

- Let the particular solution be the fundamental matrix multiplied by $\vec{v}(x)$ and solve for $\vec{v}(x)$

$$\vec{y}_p(x) = \Phi(x) \cdot \vec{v}(x)$$

- Take the derivative of the particular solution

$$\vec{y}'_p(x) = \Phi'(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x)$$

- Substitute particular solution and its derivative into the system of ODEs

$$\Phi'(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x) = A \cdot \Phi(x) \cdot \vec{v}(x) + \vec{f}(x)$$

- The fundamental matrix has columns that are solutions to the homogeneous system so its derivative is $A \cdot \Phi(x)$

$$A \cdot \Phi(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x) = A \cdot \Phi(x) \cdot \vec{v}(x) + \vec{f}(x)$$

- Cancel like terms

$$\Phi(x) \cdot \vec{v}'(x) = \vec{f}(x)$$

- Multiply by the inverse of the fundamental matrix

$$\vec{v}'(x) = \frac{1}{\Phi(x)} \cdot \vec{f}(x)$$

- Integrate to solve for $\vec{v}(x)$

$$\vec{v}(x) = \int_0^x \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds$$

- Plug $\vec{v}(x)$ into the equation for the particular solution

$$\vec{y}_p(x) = \Phi(x) \cdot \left(\int_0^x \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds \right)$$

- Plug in the fundamental matrix and the forcing function and compute

$$\vec{y}_p(x) = \begin{bmatrix} -\frac{e^{-x}}{16} - \frac{8e^{2x}}{5} + \frac{33e^{3x}}{80} + \frac{(3x+5)e^x}{4} - \frac{\sin(x)}{10} \\ \frac{99e^{3x}}{80} - \frac{16e^{2x}}{5} + \frac{3xe^x}{4} + 2e^x - \frac{\cos(x)}{10} + \frac{e^{-x}}{16} \\ -\frac{e^{-x}}{16} - \frac{32e^{2x}}{5} + \frac{297e^{3x}}{80} + \frac{(3x+11)e^x}{4} + \frac{\sin(x)}{10} \end{bmatrix}$$

- Plug particular solution back into general solution

$$\vec{y}(x) = c_1 \vec{y}_1 + c_2 \vec{y}_2 + c_3 \vec{y}_3 + \begin{bmatrix} -\frac{e^{-x}}{16} - \frac{8e^{2x}}{5} + \frac{33e^{3x}}{80} + \frac{(3x+5)e^x}{4} - \frac{\sin(x)}{10} \\ \frac{99e^{3x}}{80} - \frac{16e^{2x}}{5} + \frac{3xe^x}{4} + 2e^x - \frac{\cos(x)}{10} + \frac{e^{-x}}{16} \\ -\frac{e^{-x}}{16} - \frac{32e^{2x}}{5} + \frac{297e^{3x}}{80} + \frac{(3x+11)e^x}{4} + \frac{\sin(x)}{10} \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y = \frac{(720c_1 - 45)e^{-x}}{720} + \frac{(180c_2 - 1152)e^{2x}}{720} + \frac{(80c_3 + 297)e^{3x}}{720} + \frac{(540x + 900)e^x}{720} - \frac{\sin(x)}{10}$$

- Use the initial condition $y(0) = \frac{33}{40}$

$$\frac{33}{40} = c_1 + \frac{c_2}{4} + \frac{c_3}{9}$$

- Calculate the 1st derivative of the solution

$$y' = -\frac{(720c_1-45)e^{-x}}{720} + \frac{(180c_2-1152)e^{2x}}{360} + \frac{(80c_3+297)e^{3x}}{240} + \frac{3e^x}{4} + \frac{(540x+900)e^x}{720} - \frac{\cos(x)}{10}$$

- Use the initial condition $y'|_{\{x=0\}} = 0$

$$0 = -c_1 + \frac{c_2}{2} + \frac{c_3}{3}$$

- Calculate the 2nd derivative of the solution

$$y'' = \frac{(720c_1-45)e^{-x}}{720} + \frac{(180c_2-1152)e^{2x}}{180} + \frac{(80c_3+297)e^{3x}}{80} + \frac{3e^x}{2} + \frac{(540x+900)e^x}{720} + \frac{\sin(x)}{10}$$

- Use the initial condition $y''|_{\{x=0\}} = 0$

$$0 = c_1 + c_2 + c_3$$

- Solve for the unknown coefficients

$$\left\{ c_1 = \frac{33}{80}, c_2 = \frac{33}{10}, c_3 = -\frac{297}{80} \right\}$$

- Solution to the IVP

$$y = \frac{7e^{-x}}{20} - \frac{31e^{2x}}{40} + \frac{(3x+5)e^x}{4} - \frac{\sin(x)}{10}$$

Maple trace

```

`Methods for third order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 3; linear nonhomogeneous with symmetry [0,1]
trying high order linear exact nonhomogeneous
trying differential order: 3; missing the dependent variable
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.031 (sec). Leaf size: 30

```
dsolve([diff(y(x),x$3)-4*diff(y(x),x$2)+diff(y(x),x)+6*y(x)=3*x*exp(x)+2*exp(x)-sin(x),y(0)
```

$$y(x) = \frac{7e^{-x}}{20} - \frac{31e^{2x}}{40} + \frac{(3x+5)e^x}{4} - \frac{\sin(x)}{10}$$

✓ Solution by Mathematica

Time used: 0.285 (sec). Leaf size: 38

```
DSolve[{y'''[x]-4*y''[x]+y'[x]+6*y[x]==3*x*Exp[x]+2*Exp[x]-Sin[x],{y[0]==33/40,y'[0]==0,y''[0]==0}],y[x]]
```

$$y(x) \rightarrow \frac{1}{40}(10e^x(3x + 5) + 14e^{-x} - 31e^{2x} - 4\sin(x))$$

11.40 problem 40

11.40.1 Maple step by step solution 2691

Internal problem ID [11814]

Internal file name [OUTPUT/11823_Thursday_April_11_2024_08_50_03_PM_30210734/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 40.

ODE order: 3.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_3rd_order , _linear , _nonhomogeneous]]
```

$$y''' - 6y'' + 9y' - 4y = 8x^2 + 3 - 6e^{2x}$$

With initial conditions

$$[y(0) = 1, y'(0) = 7, y''(0) = 0]$$

This is higher order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE And y_p is a particular solution to the nonhomogeneous ODE. y_h is the solution to

$$y''' - 6y'' + 9y' - 4y = 0$$

The characteristic equation is

$$\lambda^3 - 6\lambda^2 + 9\lambda - 4 = 0$$

The roots of the above equation are

$$\lambda_1 = 4$$

$$\lambda_2 = 1$$

$$\lambda_3 = 1$$

Therefore the homogeneous solution is

$$y_h(x) = e^x c_1 + c_2 x e^x + e^{4x} c_3$$

The fundamental set of solutions for the homogeneous solution are the following

$$y_1 = e^x$$

$$y_2 = x e^x$$

$$y_3 = e^{4x}$$

Now the particular solution to the given ODE is found

$$y''' - 6y'' + 9y' - 4y = 8x^2 + 3 - 6e^{2x}$$

The particular solution is found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$8x^2 + 3 - 6e^{2x}$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{e^{2x}\}, \{1, x, x^2\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{x e^x, e^x, e^{4x}\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1 e^{2x} + A_2 + A_3 x + A_4 x^2$$

The unknowns $\{A_1, A_2, A_3, A_4\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$-2A_1 e^{2x} - 12A_4 + 9A_3 + 18A_4 x - 4A_2 - 4A_3 x - 4A_4 x^2 = 8x^2 + 3 - 6e^{2x}$$

Solving for the unknowns by comparing coefficients results in

$$[A_1 = 3, A_2 = -15, A_3 = -9, A_4 = -2]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = 3 e^{2x} - 15 - 9x - 2x^2$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (e^x c_1 + c_2 x e^x + e^{4x} c_3) + (3 e^{2x} - 15 - 9x - 2x^2) \end{aligned}$$

Which simplifies to

$$y = e^{4x} c_3 + e^x (c_2 x + c_1) + 3 e^{2x} - 15 - 9x - 2x^2$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = e^{4x} c_3 + e^x (c_2 x + c_1) + 3 e^{2x} - 15 - 9x - 2x^2 \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 1$ and $x = 0$ in the above gives

$$1 = -12 + c_3 + c_1 \quad (1A)$$

Taking derivative of the solution gives

$$y' = 4 e^{4x} c_3 + e^x (c_2 x + c_1) + c_2 e^x + 6 e^{2x} - 9 - 4x$$

substituting $y' = 7$ and $x = 0$ in the above gives

$$7 = -3 + 4c_3 + c_1 + c_2 \quad (2A)$$

Taking two derivatives of the solution gives

$$y'' = 16 e^{4x} c_3 + e^x (c_2 x + c_1) + 2c_2 e^x + 12 e^{2x} - 4$$

substituting $y'' = 0$ and $x = 0$ in the above gives

$$0 = 8 + 16c_3 + c_1 + 2c_2 \quad (3A)$$

Equations {1A,2A,3A} are now solved for $\{c_1, c_2, c_3\}$. Solving for the constants gives

$$c_1 = \frac{44}{3}$$

$$c_2 = 2$$

$$c_3 = -\frac{5}{3}$$

Substituting these values back in above solution results in

$$y = -15 - \frac{5e^{4x}}{3} + 2xe^x + \frac{44e^x}{3} + 3e^{2x} - 9x - 2x^2$$

Summary

The solution(s) found are the following

$$y = -15 - \frac{5e^{4x}}{3} + 2xe^x + \frac{44e^x}{3} + 3e^{2x} - 9x - 2x^2 \quad (1)$$

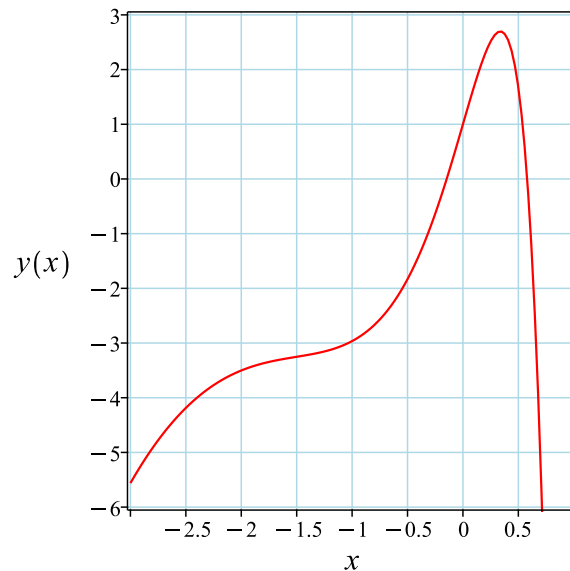


Figure 472: Solution plot

Verification of solutions

$$y = -15 - \frac{5e^{4x}}{3} + 2xe^x + \frac{44e^x}{3} + 3e^{2x} - 9x - 2x^2$$

Verified OK.

11.40.1 Maple step by step solution

Let's solve

$$\left[y''' - 6y'' + 9y' - 4y = 8x^2 + 3 - 6e^{2x}, y(0) = 1, y'|_{\{x=0\}} = 7, y''|_{\{x=0\}} = 0 \right]$$

- Highest derivative means the order of the ODE is 3

y'''

- Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(x)$

$$y_1(x) = y$$

- Define new variable $y_2(x)$

$$y_2(x) = y'$$

- Define new variable $y_3(x)$

$$y_3(x) = y''$$

- Isolate for $y_3'(x)$ using original ODE

$$y_3'(x) = 8x^2 - 6e^{2x} + 6y_3(x) - 9y_2(x) + 4y_1(x) + 3$$

Convert linear ODE into a system of first order ODEs

$$[y_2(x) = y_1'(x), y_3(x) = y_2'(x), y_3'(x) = 8x^2 - 6e^{2x} + 6y_3(x) - 9y_2(x) + 4y_1(x) + 3]$$

- Define vector

$$\vec{y}(x) = \begin{bmatrix} y_1(x) \\ y_2(x) \\ y_3(x) \end{bmatrix}$$

- System to solve

$$\vec{y}'(x) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 4 & -9 & 6 \end{bmatrix} \cdot \vec{y}(x) + \begin{bmatrix} 0 \\ 0 \\ 8x^2 + 3 - 6e^{2x} \end{bmatrix}$$

- Define the forcing function

$$\vec{f}(x) = \begin{bmatrix} 0 \\ 0 \\ 8x^2 + 3 - 6e^{2x} \end{bmatrix}$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 4 & -9 & 6 \end{bmatrix}$$

- Rewrite the system as

$$\vec{y}'(x) = A \cdot \vec{y}(x) + \vec{f}$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[1, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right], \left[1, \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \right], \left[4, \begin{bmatrix} \frac{1}{16} \\ \frac{1}{4} \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair, with eigenvalue of algebraic multiplicity 2

$$\left[1, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right]$$

- First solution from eigenvalue 1

$$\vec{y}_1(x) = e^x \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

- Form of the 2nd homogeneous solution where \vec{p} is to be solved for, $\lambda = 1$ is the eigenvalue, and

$$\vec{y}_2(x) = e^{\lambda x} (x\vec{v} + \vec{p})$$

- Note that the x multiplying \vec{v} makes this solution linearly independent to the 1st solution obtained

- Substitute $\vec{y}_2(x)$ into the homogeneous system

$$\lambda e^{\lambda x} (x\vec{v} + \vec{p}) + e^{\lambda x} \vec{v} = (e^{\lambda x} A) \cdot (x\vec{v} + \vec{p})$$

- Use the fact that \vec{v} is an eigenvector of A

$$\lambda e^{\lambda x} (x\vec{v} + \vec{p}) + e^{\lambda x} \vec{v} = e^{\lambda x} (\lambda x\vec{v} + A \cdot \vec{p})$$

- Simplify equation

$$\lambda \vec{p} + \vec{v} = A \cdot \vec{p}$$

- Make use of the identity matrix I

$$(\lambda \cdot I) \cdot \vec{p} + \vec{v} = A \cdot \vec{p}$$

- Condition \vec{p} must meet for $\vec{y}_2(x)$ to be a solution to the homogeneous system

$$(A - \lambda \cdot I) \cdot \vec{p} = \vec{v}$$

- Choose \vec{p} to use in the second solution to the homogeneous system from eigenvalue 1

$$\left(\begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 4 & -9 & 6 \end{bmatrix} - 1 \cdot \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \cdot \vec{p} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

- Choice of \vec{p}

$$\vec{p} = \begin{bmatrix} -1 \\ 0 \\ 0 \end{bmatrix}$$

- Second solution from eigenvalue 1

$$\vec{y}_2(x) = e^x \cdot \left(x \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + \begin{bmatrix} -1 \\ 0 \\ 0 \end{bmatrix} \right)$$

- Consider eigenpair

$$\left[4, \begin{bmatrix} \frac{1}{16} \\ \frac{1}{4} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_3 = e^{4x} \cdot \begin{bmatrix} \frac{1}{16} \\ \frac{1}{4} \\ 1 \end{bmatrix}$$

- General solution of the system of ODEs can be written in terms of the particular solution $\vec{y}_p(x)$

$$\vec{y}(x) = c_1 \vec{y}_1(x) + c_2 \vec{y}_2(x) + c_3 \vec{y}_3 + \vec{y}_p(x)$$

- Fundamental matrix

- Let $\phi(x)$ be the matrix whose columns are the independent solutions of the homogeneous system

$$\phi(x) = \begin{bmatrix} e^x & e^x(x-1) & \frac{e^{4x}}{16} \\ e^x & x e^x & \frac{e^{4x}}{4} \\ e^x & x e^x & e^{4x} \end{bmatrix}$$

- The fundamental matrix, $\Phi(x)$ is a normalized version of $\phi(x)$ satisfying $\Phi(0) = I$ where I is the identity matrix. $\Phi(x) = \phi(x) \cdot \frac{1}{\phi(0)}$

- Substitute the value of $\phi(x)$ and $\phi(0)$

$$\Phi(x) = \begin{bmatrix} e^x & e^x(x-1) & \frac{e^{4x}}{16} \\ e^x & x e^x & \frac{e^{4x}}{4} \\ e^x & x e^x & e^{4x} \end{bmatrix} \cdot \frac{1}{\begin{bmatrix} 1 & -1 & \frac{1}{16} \\ 1 & 0 & \frac{1}{4} \\ 1 & 0 & 1 \end{bmatrix}}$$

- Evaluate and simplify to get the fundamental matrix

$$\Phi(x) = \begin{bmatrix} -e^x(x-1) & -\frac{e^{4x}}{12} + \frac{(15x+1)e^x}{12} & \frac{e^{4x}}{12} + \frac{(-3x-1)e^x}{12} \\ -x e^x & \frac{4e^x}{3} + \frac{5x e^x}{4} - \frac{e^{4x}}{3} & \frac{e^{4x}}{3} + \frac{(-4-3x)e^x}{12} \\ -x e^x & \frac{4e^x}{3} + \frac{5x e^x}{4} - \frac{4e^{4x}}{3} & \frac{4e^{4x}}{3} + \frac{(-4-3x)e^x}{12} \end{bmatrix}$$

- Find a particular solution of the system of ODEs using variation of parameters

- Let the particular solution be the fundamental matrix multiplied by $\vec{v}(x)$ and solve for $\vec{v}(x)$

$$\vec{y}_p(x) = \Phi(x) \cdot \vec{v}(x)$$

- Take the derivative of the particular solution

$$\vec{y}'_p(x) = \Phi'(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x)$$

- Substitute particular solution and its derivative into the system of ODEs

$$\Phi'(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x) = A \cdot \Phi(x) \cdot \vec{v}(x) + \vec{f}(x)$$

- The fundamental matrix has columns that are solutions to the homogeneous system so its derivative is $A \cdot \Phi(x)$

$$A \cdot \Phi(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x) = A \cdot \Phi(x) \cdot \vec{v}(x) + \vec{f}(x)$$

- Cancel like terms

$$\Phi(x) \cdot \vec{v}'(x) = \vec{f}(x)$$

- Multiply by the inverse of the fundamental matrix

$$\vec{v}'(x) = \frac{1}{\Phi(x)} \cdot \vec{f}(x)$$

- o Integrate to solve for $\vec{v}(x)$

$$\vec{v}(x) = \int_0^x \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds$$

- o Plug $\vec{v}(x)$ into the equation for the particular solution

$$\vec{y}_p(x) = \Phi(x) \cdot \left(\int_0^x \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds \right)$$

- o Plug in the fundamental matrix and the forcing function and compute

$$\vec{y}_p(x) = \begin{bmatrix} -\frac{45}{4} + \frac{9e^{2x}}{4} - \frac{e^{4x}}{6} + \frac{5(22-15x)e^x}{12} - \frac{3x^2}{2} - \frac{27x}{4} \\ -\frac{27}{4} + \frac{9e^{2x}}{2} - \frac{2e^{4x}}{3} + \frac{5(7-15x)e^x}{12} - 3x \\ -\frac{31}{4} + \frac{15e^{2x}}{2} - \frac{8e^{4x}}{3} + \frac{5(7-15x)e^x}{12} - 2x^2 - 4x \end{bmatrix}$$

- Plug particular solution back into general solution

$$\vec{y}(x) = c_1 \vec{y}_1(x) + c_2 \vec{y}_2(x) + c_3 \vec{y}_3 + \begin{bmatrix} -\frac{45}{4} + \frac{9e^{2x}}{4} - \frac{e^{4x}}{6} + \frac{5(22-15x)e^x}{12} - \frac{3x^2}{2} - \frac{27x}{4} \\ -\frac{27}{4} + \frac{9e^{2x}}{2} - \frac{2e^{4x}}{3} + \frac{5(7-15x)e^x}{12} - 3x \\ -\frac{31}{4} + \frac{15e^{2x}}{2} - \frac{8e^{4x}}{3} + \frac{5(7-15x)e^x}{12} - 2x^2 - 4x \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y = \frac{(3c_3-8)e^{4x}}{48} + \frac{9e^{2x}}{4} + \frac{((48c_2-300)x+48c_1-48c_2+440)e^x}{48} - \frac{3x^2}{2} - \frac{27x}{4} - \frac{45}{4}$$

- Use the initial condition $y(0) = 1$

$$1 = \frac{c_3}{16} + c_1 - c_2$$

- Calculate the 1st derivative of the solution

$$y' = \frac{(3c_3-8)e^{4x}}{12} + \frac{9e^{2x}}{2} + \frac{(48c_2-300)e^x}{48} + \frac{((48c_2-300)x+48c_1-48c_2+440)e^x}{48} - 3x - \frac{27}{4}$$

- Use the initial condition $y'|_{\{x=0\}} = 7$

$$7 = \frac{c_3}{4} + c_1$$

- Calculate the 2nd derivative of the solution

$$y'' = \frac{(3c_3-8)e^{4x}}{3} + 9e^{2x} + \frac{(48c_2-300)e^x}{24} + \frac{((48c_2-300)x+48c_1-48c_2+440)e^x}{48} - 3$$

- Use the initial condition $y''|_{\{x=0\}} = 0$

$$0 = c_1 + c_2 + c_3$$

- Solve for the unknown coefficients

$$\left\{c_1 = \frac{115}{9}, c_2 = \frac{31}{3}, c_3 = -\frac{208}{9}\right\}$$

- Solution to the IVP

$$y = \frac{9e^{2x}}{4} - \frac{29e^{4x}}{18} + \frac{(147x+418)e^x}{36} - \frac{3x^2}{2} - \frac{27x}{4} - \frac{45}{4}$$

Maple trace

```

`Methods for third order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 3; linear nonhomogeneous with symmetry [0,1]
trying high order linear exact nonhomogeneous
trying differential order: 3; missing the dependent variable
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 35

```
dsolve([diff(y(x),x$3)-6*diff(y(x),x$2)+9*diff(y(x),x)-4*y(x)=8*x^2+3-6*exp(2*x),y(0) = 1, D
```

$$y(x) = -2x^2 - 9x + 3e^{2x} - 15 + \frac{44e^x}{3} - \frac{5e^{4x}}{3} + 2e^x x$$

✓ Solution by Mathematica

Time used: 0.21 (sec). Leaf size: 42

```
DSolve[{y'''[x]-6*y''[x]+9*y'[x]-4*y[x]==8*x^2+3-6*Exp[2*x],{y[0]==1,y'[0]==7,y''[0]==0}},y[x]
```

$$y(x) \rightarrow -2x^2 - 9x + 3e^{2x} - \frac{5e^{4x}}{3} + e^x \left(2x + \frac{44}{3}\right) - 15$$

11.41 problem 41

11.41.1 Solving as second order linear constant coeff ode	2697
11.41.2 Solving using Kovacic algorithm	2700
11.41.3 Maple step by step solution	2705

Internal problem ID [11815]

Internal file name [OUTPUT/11824_Thursday_April_11_2024_08_50_03_PM_64035439/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 41.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' - 6y' + 8y = x^3 + x + e^{-2x}$$

11.41.1 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = -6, C = 8, f(x) = x^3 + x + e^{-2x}$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' - 6y' + 8y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = -6, C = 8$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} - 6\lambda e^{\lambda x} + 8 e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 - 6\lambda + 8 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = -6, C = 8$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{6}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{-6^2 - (4)(1)(8)} \\ &= 3 \pm 1 \end{aligned}$$

Hence

$$\lambda_1 = 3 + 1$$

$$\lambda_2 = 3 - 1$$

Which simplifies to

$$\lambda_1 = 4$$

$$\lambda_2 = 2$$

Since roots are real and distinct, then the solution is

$$y = c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x}$$

$$y = c_1 e^{(4)x} + c_2 e^{(2)x}$$

Or

$$y = c_1 e^{4x} + c_2 e^{2x}$$

Therefore the homogeneous solution y_h is

$$y_h = c_1 e^{4x} + c_2 e^{2x}$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$x^3 + x + e^{-2x}$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{e^{-2x}\}, \{1, x, x^2, x^3\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^{2x}, e^{4x}\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1 e^{-2x} + A_2 + A_3 x + A_4 x^2 + A_5 x^3$$

The unknowns $\{A_1, A_2, A_3, A_4, A_5\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$\begin{aligned} 24A_1 e^{-2x} + 2A_4 + 6A_5 x - 6A_3 - 12A_4 x - 18A_5 x^2 + 8A_2 + 8A_3 x + 8A_4 x^2 + 8A_5 x^3 \\ = x^3 + x + e^{-2x} \end{aligned}$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = \frac{1}{24}, A_2 = \frac{69}{256}, A_3 = \frac{29}{64}, A_4 = \frac{9}{32}, A_5 = \frac{1}{8} \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = \frac{e^{-2x}}{24} + \frac{69}{256} + \frac{29x}{64} + \frac{9x^2}{32} + \frac{x^3}{8}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 e^{4x} + c_2 e^{2x}) + \left(\frac{e^{-2x}}{24} + \frac{69}{256} + \frac{29x}{64} + \frac{9x^2}{32} + \frac{x^3}{8} \right) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 e^{4x} + c_2 e^{2x} + \frac{e^{-2x}}{24} + \frac{69}{256} + \frac{29x}{64} + \frac{9x^2}{32} + \frac{x^3}{8} \quad (1)$$

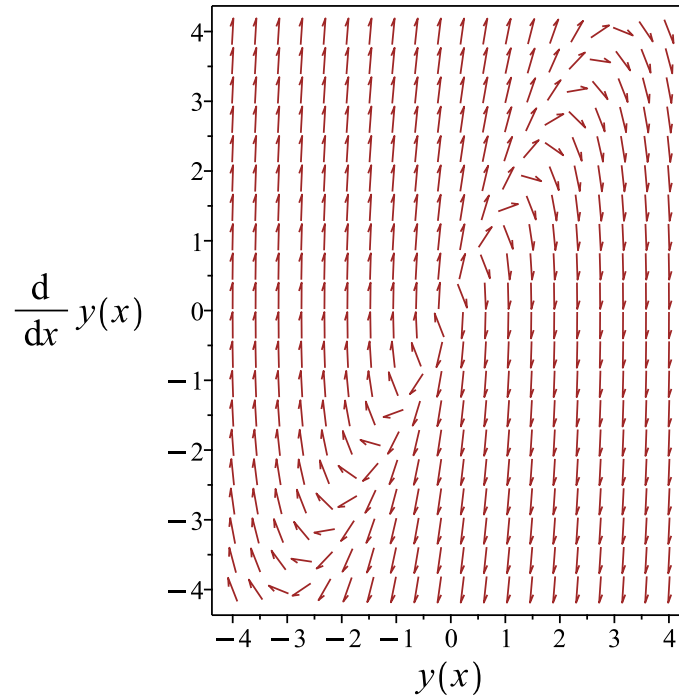


Figure 473: Slope field plot

Verification of solutions

$$y = c_1 e^{4x} + c_2 e^{2x} + \frac{e^{-2x}}{24} + \frac{69}{256} + \frac{29x}{64} + \frac{9x^2}{32} + \frac{x^3}{8}$$

Verified OK.

11.41.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' - 6y' + 8y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned}A &= 1 \\B &= -6 \\C &= 8\end{aligned}\tag{3}$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x)\tag{4}$$

Where r is given by

$$\begin{aligned}r &= \frac{s}{t} \\&= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2}\end{aligned}\tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{1}{1}\tag{6}$$

Comparing the above to (5) shows that

$$\begin{aligned}s &= 1 \\t &= 1\end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = z(x)\tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 409: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned}
 \mathcal{O}(\infty) &= \deg(t) - \deg(s) \\
 &= 0 - 0 \\
 &= 0
 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = 1$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = e^{-x}$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned}
 y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\
 &= z_1 e^{-\int \frac{1}{2} \frac{-6}{1} dx} \\
 &= z_1 e^{3x} \\
 &= z_1 (e^{3x})
 \end{aligned}$$

Which simplifies to

$$y_1 = e^{2x}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{6}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{6x}}{(y_1)^2} dx \\ &= y_1 \left(\frac{e^{2x}}{2} \right) \end{aligned}$$

Therefore the solution is

$$\begin{aligned} y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (e^{2x}) + c_2 \left(e^{2x} \left(\frac{e^{2x}}{2} \right) \right) \end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' - 6y' + 8y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1 e^{2x} + \frac{c_2 e^{4x}}{2}$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$x^3 + x + e^{-2x}$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{e^{-2x}\}, \{1, x, x^2, x^3\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\left\{ \frac{e^{4x}}{2}, e^{2x} \right\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1 e^{-2x} + A_2 + A_3 x + A_4 x^2 + A_5 x^3$$

The unknowns $\{A_1, A_2, A_3, A_4, A_5\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$24A_1 e^{-2x} + 2A_4 + 6A_5 x - 6A_3 - 12A_4 x - 18A_5 x^2 + 8A_2 + 8A_3 x + 8A_4 x^2 + 8A_5 x^3 = x^3 + x + e^{-2x}$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = \frac{1}{24}, A_2 = \frac{69}{256}, A_3 = \frac{29}{64}, A_4 = \frac{9}{32}, A_5 = \frac{1}{8} \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = \frac{e^{-2x}}{24} + \frac{69}{256} + \frac{29x}{64} + \frac{9x^2}{32} + \frac{x^3}{8}$$

Therefore the general solution is

$$y = y_h + y_p = \left(c_1 e^{2x} + \frac{c_2 e^{4x}}{2} \right) + \left(\frac{e^{-2x}}{24} + \frac{69}{256} + \frac{29x}{64} + \frac{9x^2}{32} + \frac{x^3}{8} \right)$$

Summary

The solution(s) found are the following

$$y = c_1 e^{2x} + \frac{c_2 e^{4x}}{2} + \frac{e^{-2x}}{24} + \frac{69}{256} + \frac{29x}{64} + \frac{9x^2}{32} + \frac{x^3}{8} \quad (1)$$

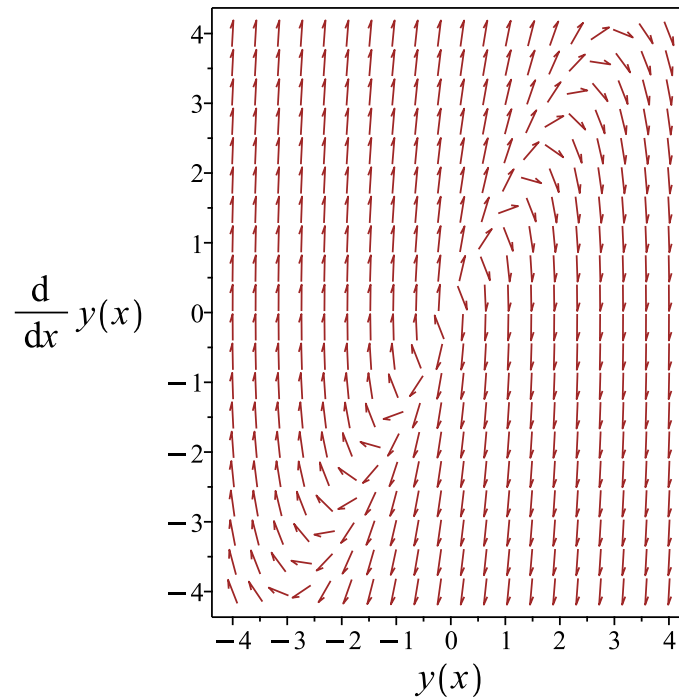


Figure 474: Slope field plot

Verification of solutions

$$y = c_1 e^{2x} + \frac{c_2 e^{4x}}{2} + \frac{e^{-2x}}{24} + \frac{69}{256} + \frac{29x}{64} + \frac{9x^2}{32} + \frac{x^3}{8}$$

Verified OK.

11.41.3 Maple step by step solution

Let's solve

$$y'' - 6y' + 8y = x^3 + x + e^{-2x}$$

- Highest derivative means the order of the ODE is 2
 y''
- Characteristic polynomial of homogeneous ODE

$$r^2 - 6r + 8 = 0$$

- Factor the characteristic polynomial

$$(r - 2)(r - 4) = 0$$

- Roots of the characteristic polynomial

$$r = (2, 4)$$

- 1st solution of the homogeneous ODE

$$y_1(x) = e^{2x}$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = e^{4x}$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = c_1 e^{2x} + c_2 e^{4x} + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x), y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x), y_2(x))} dx \right), f(x) = x^3 + x + e^{-2x} \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} e^{2x} & e^{4x} \\ 2e^{2x} & 4e^{4x} \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = 2e^{6x}$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = -\frac{e^{2x} \left(\int e^{-2x} (x^3 + x + e^{-2x}) dx \right)}{2} + \frac{e^{4x} \left(\int e^{-4x} (x^3 + x + e^{-2x}) dx \right)}{2}$$

- Compute integrals

$$y_p(x) = \frac{e^{-2x}}{24} + \frac{69}{256} + \frac{29x}{64} + \frac{9x^2}{32} + \frac{x^3}{8}$$

- Substitute particular solution into general solution to ODE

$$y = c_1 e^{2x} + c_2 e^{4x} + \frac{e^{-2x}}{24} + \frac{69}{256} + \frac{29x}{64} + \frac{9x^2}{32} + \frac{x^3}{8}$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]  
trying a double symmetry of the form [xi=0, eta=F(x)]  
<- double symmetry of the form [xi=0, eta=F(x)] successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 38

```
dsolve(diff(y(x),x$2)-6*diff(y(x),x)+8*y(x)=x^3+x+exp(-2*x),y(x), singsol=all)
```

$$y(x) = \frac{c_1 e^{4x}}{2} + \frac{e^{-2x}}{24} + \frac{69}{256} + \frac{29x}{64} + \frac{9x^2}{32} + \frac{x^3}{8} + c_2 e^{2x}$$

✓ Solution by Mathematica

Time used: 0.699 (sec). Leaf size: 50

```
DSolve[y''[x]-6*y'[x]+8*y[x]==x^3+x+Exp[-2*x],y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{1}{256} (32x^3 + 72x^2 + 116x + 69) + \frac{e^{-2x}}{24} + c_1 e^{2x} + c_2 e^{4x}$$

11.42 problem 42

11.42.1 Solving as second order linear constant coeff ode	2708
11.42.2 Solving using Kovacic algorithm	2712
11.42.3 Maple step by step solution	2717

Internal problem ID [11816]

Internal file name [OUTPUT/11825_Thursday_April_11_2024_08_50_04_PM_71030995/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 42.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' + 9y = e^{3x} + e^{-3x} + e^{3x} \sin(3x)$$

11.42.1 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = 0, C = 9, f(x) = e^{3x} + e^{-3x} + e^{3x} \sin(3x)$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 9y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 0, C = 9$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + 9 e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 9 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 0, C = 9$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{0}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{0^2 - (4)(1)(9)} \\ &= \pm 3i \end{aligned}$$

Hence

$$\lambda_1 = +3i$$

$$\lambda_2 = -3i$$

Which simplifies to

$$\lambda_1 = 3i$$

$$\lambda_2 = -3i$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = 0$ and $\beta = 3$. Therefore the final solution, when using Euler relation, can be written as

$$y = e^{\alpha x} (c_1 \cos(\beta x) + c_2 \sin(\beta x))$$

Which becomes

$$y = e^0 (c_1 \cos(3x) + c_2 \sin(3x))$$

Or

$$y = c_1 \cos(3x) + c_2 \sin(3x)$$

Therefore the homogeneous solution y_h is

$$y_h = c_1 \cos(3x) + c_2 \sin(3x)$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$e^{3x} + e^{-3x} + e^{3x} \sin(3x)$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{e^{-3x}\}, \{e^{3x}\}, \{e^{3x} \cos(3x)\}, \{e^{3x} \sin(3x)\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{\cos(3x), \sin(3x)\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1 e^{-3x} + A_2 e^{3x} + A_3 e^{3x} \cos(3x) + A_4 e^{3x} \sin(3x)$$

The unknowns $\{A_1, A_2, A_3, A_4\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$18A_1 e^{-3x} + 18A_2 e^{3x} - 18A_3 e^{3x} \sin(3x) + 18A_4 e^{3x} \cos(3x) + 9A_3 e^{3x} \cos(3x) + 9A_4 e^{3x} \sin(3x) = e^{3x} + e^{-3x} + e^{3x} \sin(3x)$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = \frac{1}{18}, A_2 = \frac{1}{18}, A_3 = -\frac{2}{45}, A_4 = \frac{1}{45} \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = \frac{e^{-3x}}{18} + \frac{e^{3x}}{18} - \frac{2e^{3x} \cos(3x)}{45} + \frac{e^{3x} \sin(3x)}{45}$$

Therefore the general solution is

$$y = y_h + y_p \\ = (c_1 \cos(3x) + c_2 \sin(3x)) + \left(\frac{e^{-3x}}{18} + \frac{e^{3x}}{18} - \frac{2e^{3x} \cos(3x)}{45} + \frac{e^{3x} \sin(3x)}{45} \right)$$

Summary

The solution(s) found are the following

$$y = c_1 \cos(3x) + c_2 \sin(3x) + \frac{e^{-3x}}{18} + \frac{e^{3x}}{18} - \frac{2e^{3x} \cos(3x)}{45} + \frac{e^{3x} \sin(3x)}{45} \quad (1)$$

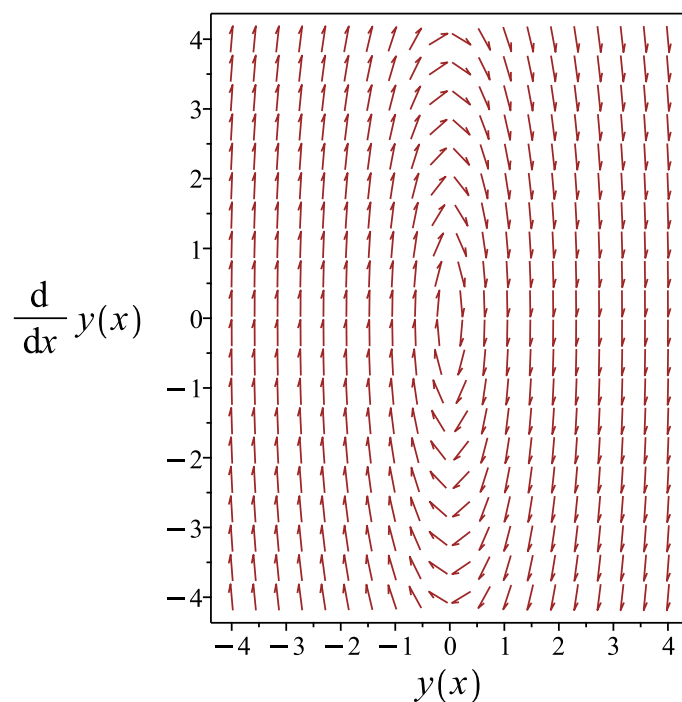


Figure 475: Slope field plot

Verification of solutions

$$y = c_1 \cos(3x) + c_2 \sin(3x) + \frac{e^{-3x}}{18} + \frac{e^{3x}}{18} - \frac{2e^{3x} \cos(3x)}{45} + \frac{e^{3x} \sin(3x)}{45}$$

Verified OK.

11.42.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' + 9y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= 0 \\ C &= 9 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-9}{1} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= -9 \\ t &= 1 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = -9z(x) \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 411: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} \mathcal{O}(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = -9$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = \cos(3x)$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$y_1 = z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx}$$

Since $B = 0$ then the above reduces to

$$\begin{aligned}y_1 &= z_1 \\ &= \cos(3x)\end{aligned}$$

Which simplifies to

$$y_1 = \cos(3x)$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Since $B = 0$ then the above becomes

$$\begin{aligned}y_2 &= y_1 \int \frac{1}{y_1^2} dx \\ &= \cos(3x) \int \frac{1}{\cos(3x)^2} dx \\ &= \cos(3x) \left(\frac{\tan(3x)}{3} \right)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1(\cos(3x)) + c_2 \left(\cos(3x) \left(\frac{\tan(3x)}{3} \right) \right)\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$.
 y_h is the solution to

$$y'' + 9y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1 \cos(3x) + \frac{c_2 \sin(3x)}{3}$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$e^{3x} + e^{-3x} + e^{3x} \sin(3x)$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$\{e^{-3x}, \{e^{3x}, \{e^{3x} \cos(3x), e^{3x} \sin(3x)\}\}$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\left\{ \frac{\sin(3x)}{3}, \cos(3x) \right\}$$

Since there is no duplication between the basis function in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis in the UC_set.

$$y_p = A_1 e^{-3x} + A_2 e^{3x} + A_3 e^{3x} \cos(3x) + A_4 e^{3x} \sin(3x)$$

The unknowns $\{A_1, A_2, A_3, A_4\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$18A_1 e^{-3x} + 18A_2 e^{3x} - 18A_3 e^{3x} \sin(3x) + 18A_4 e^{3x} \cos(3x) + 9A_3 e^{3x} \cos(3x) + 9A_4 e^{3x} \sin(3x) = e^{3x} + e^{-3x} + e^{3x} \sin(3x)$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = \frac{1}{18}, A_2 = \frac{1}{18}, A_3 = -\frac{2}{45}, A_4 = \frac{1}{45} \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = \frac{e^{-3x}}{18} + \frac{e^{3x}}{18} - \frac{2e^{3x} \cos(3x)}{45} + \frac{e^{3x} \sin(3x)}{45}$$

Therefore the general solution is

$$y = y_h + y_p$$

$$= \left(c_1 \cos(3x) + \frac{c_2 \sin(3x)}{3} \right) + \left(\frac{e^{-3x}}{18} + \frac{e^{3x}}{18} - \frac{2e^{3x} \cos(3x)}{45} + \frac{e^{3x} \sin(3x)}{45} \right)$$

Summary

The solution(s) found are the following

$$y = c_1 \cos(3x) + \frac{c_2 \sin(3x)}{3} + \frac{e^{-3x}}{18} + \frac{e^{3x}}{18} - \frac{2e^{3x} \cos(3x)}{45} + \frac{e^{3x} \sin(3x)}{45} \quad (1)$$

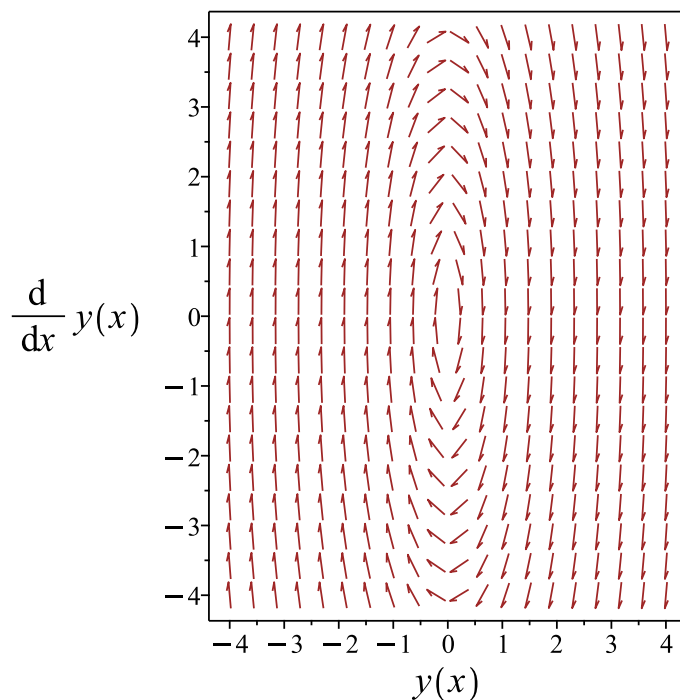


Figure 476: Slope field plot

Verification of solutions

$$y = c_1 \cos(3x) + \frac{c_2 \sin(3x)}{3} + \frac{e^{-3x}}{18} + \frac{e^{3x}}{18} - \frac{2e^{3x} \cos(3x)}{45} + \frac{e^{3x} \sin(3x)}{45}$$

Verified OK.

11.42.3 Maple step by step solution

Let's solve

$$y'' + 9y = e^{3x} + e^{-3x} + e^{3x} \sin(3x)$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of homogeneous ODE

$$r^2 + 9 = 0$$

- Use quadratic formula to solve for r

$$r = \frac{0 \pm (\sqrt{-36})}{2}$$

- Roots of the characteristic polynomial

$$r = (-3I, 3I)$$

- 1st solution of the homogeneous ODE

$$y_1(x) = \cos(3x)$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = \sin(3x)$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = c_1 \cos(3x) + c_2 \sin(3x) + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right) \right], f(x) = e^{3x} + e^{-3x} + e^{3x} \sin(3x)$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} \cos(3x) & \sin(3x) \\ -3 \sin(3x) & 3 \cos(3x) \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = 3$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = -\frac{\cos(3x)(\int \sin(3x)(e^{3x}+e^{-3x}+e^{3x}\sin(3x))dx)}{3} + \frac{\sin(3x)(\int \cos(3x)(e^{3x}+e^{-3x}+e^{3x}\sin(3x))dx)}{3}$$

- Compute integrals

$$y_p(x) = \frac{(5-4\cos(3x)+2\sin(3x))e^{3x}}{90} + \frac{e^{-3x}}{18}$$

- Substitute particular solution into general solution to ODE

$$y = \frac{(5-4\cos(3x)+2\sin(3x))e^{3x}}{90} + c_1 \cos(3x) + c_2 \sin(3x) + \frac{e^{-3x}}{18}$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
trying a double symmetry of the form [xi=0, eta=F(x)]
-> Try solving first the homogeneous part of the ODE
    checking if the LODE has constant coefficients
    <- constant coefficients successful
<- solving first the homogeneous part of the ODE successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 43

```
dsolve(diff(y(x), x$2)+9*y(x)=exp(3*x)+exp(-3*x)+exp(3*x)*sin(3*x), y(x), singsol=all)
```

$$y(x) = c_2 \sin(3x) + c_1 \cos(3x) + \frac{(2\sin(3x) - 4\cos(3x) + 5)e^{3x}}{90} + \frac{e^{-3x}}{18}$$

✓ Solution by Mathematica

Time used: 0.997 (sec). Leaf size: 57

```
DSolve[y''[x]+9*y[x]==Exp[3*x]+Exp[-3*x]+Exp[3*x]*Sin[3*x], y[x], x, IncludeSingularSolutions -
```

$$y(x) \rightarrow \frac{1}{90}(5e^{-3x}(e^{6x} + 1) + (-4e^{3x} + 90c_1) \cos(3x) + 2(e^{3x} + 45c_2) \sin(3x))$$

11.43 problem 43

11.43.1 Solving as second order linear constant coeff ode	2719
11.43.2 Solving using Kovacic algorithm	2722
11.43.3 Maple step by step solution	2728

Internal problem ID [11817]

Internal file name [OUTPUT/11826_Thursday_April_11_2024_08_50_05_PM_73129953/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 43.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' + 4y' + 5y = e^{-2x}(\cos(x) + 1)$$

11.43.1 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = 4, C = 5, f(x) = e^{-2x}(\cos(x) + 1)$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 4y' + 5y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 4, C = 5$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + 4\lambda e^{\lambda x} + 5 e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 4\lambda + 5 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 4, C = 5$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{-4}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{4^2 - (4)(1)(5)} \\ &= -2 \pm i \end{aligned}$$

Hence

$$\lambda_1 = -2 + i$$

$$\lambda_2 = -2 - i$$

Which simplifies to

$$\lambda_1 = -2 + i$$

$$\lambda_2 = -2 - i$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = -2$ and $\beta = 1$. Therefore the final solution, when using Euler relation, can be written as

$$y = e^{\alpha x} (c_1 \cos(\beta x) + c_2 \sin(\beta x))$$

Which becomes

$$y = e^{-2x} (c_1 \cos(x) + c_2 \sin(x))$$

Therefore the homogeneous solution y_h is

$$y_h = e^{-2x} (c_1 \cos(x) + c_2 \sin(x))$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$e^{-2x}(\cos(x) + 1)$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{e^{-2x}\}, \{\cos(x)e^{-2x}, e^{-2x}\sin(x)\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{\cos(x)e^{-2x}, e^{-2x}\sin(x)\}$$

Since $\cos(x)e^{-2x}$ is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[\{e^{-2x}\}, \{x\cos(x)e^{-2x}, xe^{-2x}\sin(x)\}]$$

Since there was duplication between the basis functions in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis function in the above updated UC_set.

$$y_p = A_1e^{-2x} + A_2x\cos(x)e^{-2x} + A_3xe^{-2x}\sin(x)$$

The unknowns $\{A_1, A_2, A_3\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$A_1e^{-2x} - 2A_2\sin(x)e^{-2x} + 2A_3e^{-2x}\cos(x) = e^{-2x}(\cos(x) + 1)$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = 1, A_2 = 0, A_3 = \frac{1}{2} \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = e^{-2x} + \frac{xe^{-2x}\sin(x)}{2}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (e^{-2x}(c_1\cos(x) + c_2\sin(x))) + \left(e^{-2x} + \frac{xe^{-2x}\sin(x)}{2} \right) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = e^{-2x}(c_1 \cos(x) + c_2 \sin(x)) + e^{-2x} + \frac{x e^{-2x} \sin(x)}{2} \quad (1)$$

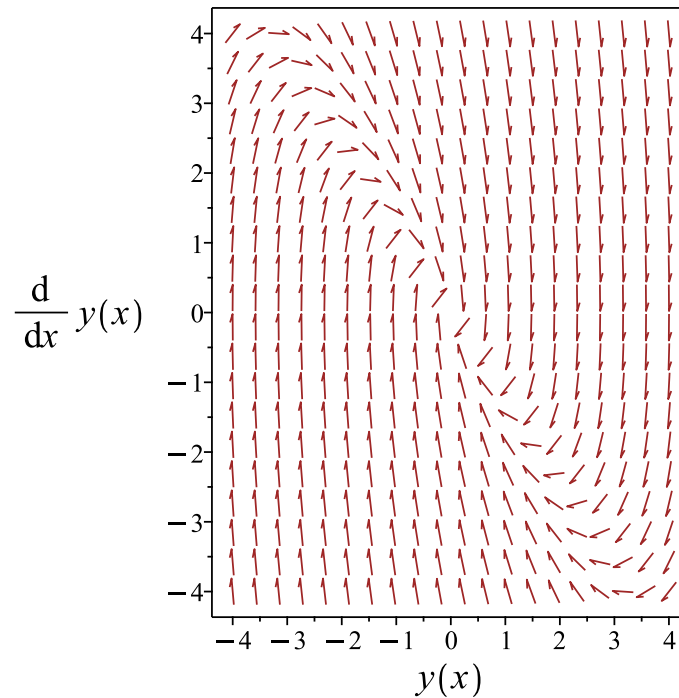


Figure 477: Slope field plot

Verification of solutions

$$y = e^{-2x}(c_1 \cos(x) + c_2 \sin(x)) + e^{-2x} + \frac{x e^{-2x} \sin(x)}{2}$$

Verified OK.

11.43.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' + 4y' + 5y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned}A &= 1 \\B &= 4 \\C &= 5\end{aligned}\tag{3}$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x)\tag{4}$$

Where r is given by

$$\begin{aligned}r &= \frac{s}{t} \\&= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2}\end{aligned}\tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-1}{1}\tag{6}$$

Comparing the above to (5) shows that

$$\begin{aligned}s &= -1 \\t &= 1\end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = -z(x)\tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 413: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned}
 \mathcal{O}(\infty) &= \deg(t) - \deg(s) \\
 &= 0 - 0 \\
 &= 0
 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = -1$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = \cos(x)$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned}
 y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\
 &= z_1 e^{-\int \frac{1}{2} \frac{4}{1} dx} \\
 &= z_1 e^{-2x} \\
 &= z_1 (e^{-2x})
 \end{aligned}$$

Which simplifies to

$$y_1 = \cos(x) e^{-2x}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{4}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{-4x}}{(y_1)^2} dx \\ &= y_1(\tan(x)) \end{aligned}$$

Therefore the solution is

$$\begin{aligned} y &= c_1 y_1 + c_2 y_2 \\ &= c_1(\cos(x) e^{-2x}) + c_2(\cos(x) e^{-2x}(\tan(x))) \end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 4y' + 5y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = \cos(x) e^{-2x} c_1 + c_2 e^{-2x} \sin(x)$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$e^{-2x}(\cos(x) + 1)$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{e^{-2x}\}, \{\cos(x)e^{-2x}, e^{-2x}\sin(x)\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{\cos(x)e^{-2x}, e^{-2x}\sin(x)\}$$

Since $\cos(x)e^{-2x}$ is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[\{e^{-2x}\}, \{xe^{-2x}\cos(x), xe^{-2x}\sin(x)\}]$$

Since there was duplication between the basis functions in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis function in the above updated UC_set.

$$y_p = A_1e^{-2x} + A_2xe^{-2x}\cos(x) + A_3xe^{-2x}\sin(x)$$

The unknowns $\{A_1, A_2, A_3\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$A_1e^{-2x} - 2A_2\sin(x)e^{-2x} + 2A_3e^{-2x}\cos(x) = e^{-2x}(\cos(x) + 1)$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = 1, A_2 = 0, A_3 = \frac{1}{2} \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = e^{-2x} + \frac{xe^{-2x}\sin(x)}{2}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (\cos(x)e^{-2x}c_1 + c_2e^{-2x}\sin(x)) + \left(e^{-2x} + \frac{xe^{-2x}\sin(x)}{2} \right) \end{aligned}$$

Which simplifies to

$$y = e^{-2x}(c_1 \cos(x) + c_2 \sin(x)) + e^{-2x} + \frac{x e^{-2x} \sin(x)}{2}$$

Summary

The solution(s) found are the following

$$y = e^{-2x}(c_1 \cos(x) + c_2 \sin(x)) + e^{-2x} + \frac{x e^{-2x} \sin(x)}{2} \quad (1)$$

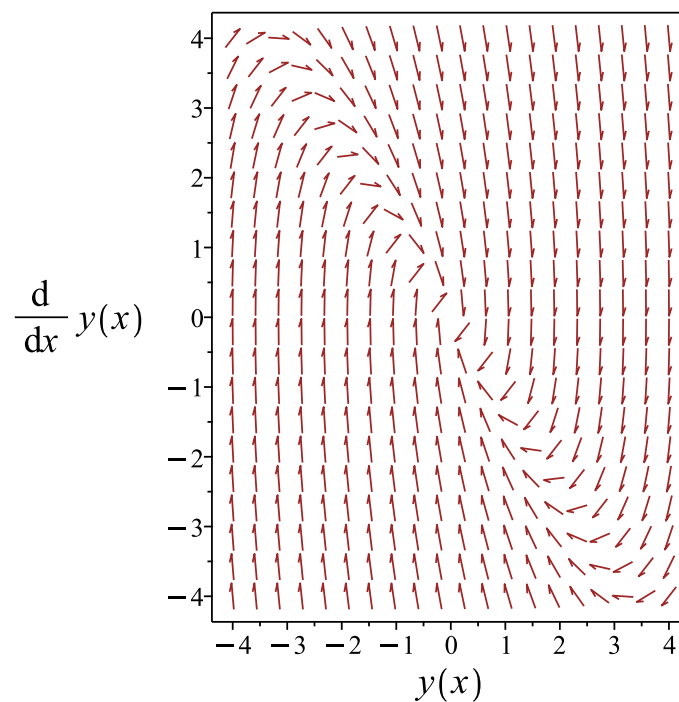


Figure 478: Slope field plot

Verification of solutions

$$y = e^{-2x}(c_1 \cos(x) + c_2 \sin(x)) + e^{-2x} + \frac{x e^{-2x} \sin(x)}{2}$$

Verified OK.

11.43.3 Maple step by step solution

Let's solve

$$y'' + 4y' + 5y = e^{-2x}(\cos(x) + 1)$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of homogeneous ODE

$$r^2 + 4r + 5 = 0$$

- Use quadratic formula to solve for r

$$r = \frac{(-4) \pm (\sqrt{-4})}{2}$$

- Roots of the characteristic polynomial

$$r = (-2 - I, -2 + I)$$

- 1st solution of the homogeneous ODE

$$y_1(x) = \cos(x) e^{-2x}$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = e^{-2x} \sin(x)$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = \cos(x) e^{-2x} c_1 + c_2 e^{-2x} \sin(x) + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = e^{-2x}(\cos(x) + 1) \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} \cos(x) e^{-2x} & e^{-2x} \sin(x) \\ -e^{-2x} \sin(x) - 2 \cos(x) e^{-2x} & -2 e^{-2x} \sin(x) + \cos(x) e^{-2x} \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = e^{-4x}$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = -e^{-2x} (\cos(x) (\int \sin(x) (\cos(x) + 1) dx) - \sin(x) (\int (\cos(x)^2 + \cos(x)) dx))$$

- Compute integrals

$$y_p(x) = \frac{(x \sin(x) + \cos(x) + 2)e^{-2x}}{2}$$

- Substitute particular solution into general solution to ODE

$$y = \cos(x) e^{-2x} c_1 + c_2 e^{-2x} \sin(x) + \frac{(x \sin(x) + \cos(x) + 2)e^{-2x}}{2}$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
trying a double symmetry of the form [xi=0, eta=F(x)]
-> Try solving first the homogeneous part of the ODE
    checking if the LODE has constant coefficients
    <- constant coefficients successful
<- solving first the homogeneous part of the ODE successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 28

```
dsolve(diff(y(x),x$2)+4*diff(y(x),x)+5*y(x)=exp(-2*x)*(1+cos(x)),y(x), singsol=all)
```

$$y(x) = \frac{((2c_1 + 1) \cos(x) + 2 + (2c_2 + x) \sin(x)) e^{-2x}}{2}$$

✓ Solution by Mathematica

Time used: 0.122 (sec). Leaf size: 35

```
DSolve[y''[x]+4*y'[x]+5*y[x]==Exp[-2*x]*(1+Cos[x]),y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{1}{4} e^{-2x} ((1 + 4c_2) \cos(x) + 2(x + 2c_1) \sin(x) + 4)$$

11.44 problem 44

11.44.1 Solving as second order linear constant coeff ode	2730
11.44.2 Solving as linear second order ode solved by an integrating factor ode	2734
11.44.3 Solving using Kovacic algorithm	2736
11.44.4 Maple step by step solution	2741

Internal problem ID [11818]

Internal file name [OUTPUT/11827_Thursday_April_11_2024_08_50_05_PM_44040111/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 44.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff", "linear_second_order_ode_solved_by_an_integrating_factor"

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' - 6y' + 9y = e^x x^4 + x^3 e^{2x} + e^{3x} x^2$$

11.44.1 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = -6, C = 9, f(x) = e^x x^2 (e^{2x} + x e^x + x^2)$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' - 6y' + 9y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = -6, C = 9$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} - 6\lambda e^{\lambda x} + 9 e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 - 6\lambda + 9 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = -6, C = 9$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{6}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{(-6)^2 - (4)(1)(9)} \\ &= 3 \end{aligned}$$

Hence this is the case of a double root $\lambda_{1,2} = -3$. Therefore the solution is

$$y = c_1 e^{3x} + c_2 x e^{3x} \quad (1)$$

Therefore the homogeneous solution y_h is

$$y_h = c_1 e^{3x} + e^{3x} c_2 x$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$e^x x^2 (e^{2x} + x e^x + x^2)$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{x e^{3x}, e^{3x} x^2, e^{3x}\}, \{x^2 e^{2x}, x^3 e^{2x}, e^{2x} x, e^{2x}\}, \{x e^x, x^2 e^x, x^3 e^x, e^x x^4, e^x\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{x e^{3x}, e^{3x}\}$$

Since e^{3x} is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[\{x e^{3x}, x^3 e^{3x}, e^{3x} x^2\}, \{x^2 e^{2x}, x^3 e^{2x}, e^{2x} x, e^{2x}\}, \{x e^x, x^2 e^x, x^3 e^x, e^x x^4, e^x\}]$$

Since $x e^{3x}$ is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[\{x^3 e^{3x}, x^4 e^{3x}, e^{3x} x^2\}, \{x^2 e^{2x}, x^3 e^{2x}, e^{2x} x, e^{2x}\}, \{x e^x, x^2 e^x, x^3 e^x, e^x x^4, e^x\}]$$

Since there was duplication between the basis functions in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis function in the above updated UC_set.

$$y_p = A_1 x^3 e^{3x} + A_2 x^4 e^{3x} + A_3 e^{3x} x^2 + A_4 x^2 e^{2x} + A_5 x^3 e^{2x} + A_6 e^{2x} x + A_7 e^{2x} + A_8 x e^x + A_9 x^2 e^x + A_{10} x^3 e^x + A_{11} e^x x^4 + A_{12} e^x$$

The unknowns $\{A_1, A_2, A_3, A_4, A_5, A_6, A_7, A_8, A_9, A_{10}, A_{11}, A_{12}\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$\begin{aligned} & -6A_5 x^2 e^{2x} - 8A_9 x e^x - 12A_{10} x^2 e^x - 16A_{11} e^x x^3 + 6A_1 x e^{3x} + 12A_2 x^2 e^{3x} \\ & + 6A_5 x e^{2x} + 6A_{10} x e^x + 12A_{11} e^x x^2 - 4A_4 x e^{2x} - 2A_6 e^{2x} - 4A_8 e^x \\ & + 4A_{11} e^x x^4 + A_4 x^2 e^{2x} + A_5 x^3 e^{2x} + A_6 e^{2x} x + 4A_8 x e^x + 4A_9 x^2 e^x + 4A_{10} x^3 e^x \\ & + 4A_{12} e^x + A_7 e^{2x} + 2A_3 e^{3x} + 2A_4 e^{2x} + 2A_9 e^x = e^x x^2 (e^{2x} + x e^x + x^2) \end{aligned}$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = 0, A_2 = \frac{1}{12}, A_3 = 0, A_4 = 6, A_5 = 1, A_6 = 18, A_7 = 24, A_8 = 3, A_9 = \frac{9}{4}, A_{10} = 1, A_{11} = \frac{1}{4}, A_{12} = \frac{15}{8} \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = \frac{x^4 e^{3x}}{12} + 6x^2 e^{2x} + x^3 e^{2x} + 18 e^{2x} x + 24 e^{2x} + 3x e^x + \frac{9x^2 e^x}{4} + x^3 e^x + \frac{e^x x^4}{4} + \frac{15 e^x}{8}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 e^{3x} + e^{3x} c_2 x) \\ &\quad + \left(\frac{x^4 e^{3x}}{12} + 6x^2 e^{2x} + x^3 e^{2x} + 18 e^{2x} x + 24 e^{2x} + 3x e^x + \frac{9x^2 e^x}{4} + x^3 e^x + \frac{e^x x^4}{4} + \frac{15 e^x}{8} \right) \end{aligned}$$

Which simplifies to

$$y = e^{3x}(c_2x + c_1) + \frac{x^4 e^{3x}}{12} + 6x^2 e^{2x} + x^3 e^{2x} + 18 e^{2x}x + 24 e^{2x} + 3x e^x + \frac{9x^2 e^x}{4} + x^3 e^x + \frac{e^x x^4}{4} + \frac{15 e^x}{8}$$

Summary

The solution(s) found are the following

$$y = e^{3x}(c_2x + c_1) + \frac{x^4 e^{3x}}{12} + 6x^2 e^{2x} + x^3 e^{2x} + 18 e^{2x}x + 24 e^{2x} + 3x e^x + \frac{9x^2 e^x}{4} + x^3 e^x + \frac{e^x x^4}{4} + \frac{15 e^x}{8} \quad (1)$$

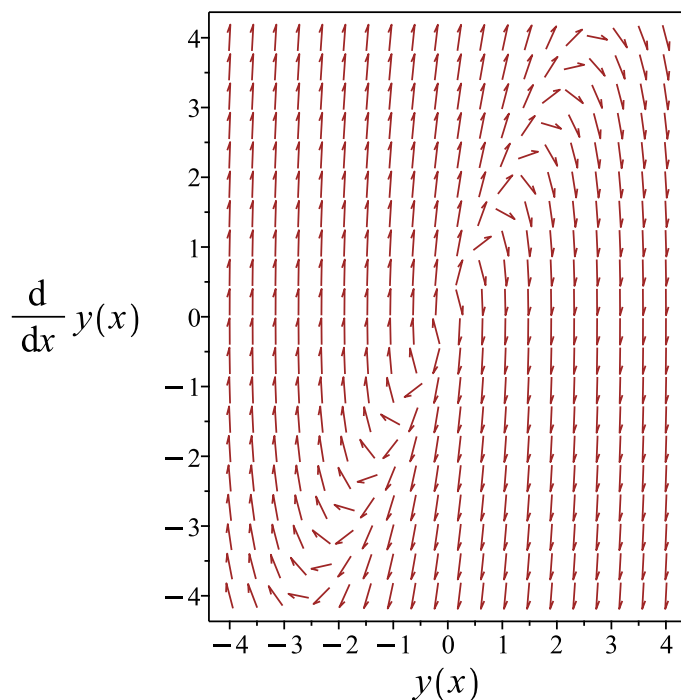


Figure 479: Slope field plot

Verification of solutions

$$y = e^{3x}(c_2x + c_1) + \frac{x^4 e^{3x}}{12} + 6x^2 e^{2x} + x^3 e^{2x} + 18 e^{2x}x + 24 e^{2x} + 3x e^x + \frac{9x^2 e^x}{4} + x^3 e^x + \frac{e^x x^4}{4} + \frac{15 e^x}{8}$$

Verified OK.

11.44.2 Solving as linear second order ode solved by an integrating factor ode

The ode satisfies this form

$$y'' + p(x)y' + \frac{(p(x)^2 + p'(x))y}{2} = f(x)$$

Where $p(x) = -6$. Therefore, there is an integrating factor given by

$$\begin{aligned} M(x) &= e^{\frac{1}{2} \int p dx} \\ &= e^{\int -6 dx} \\ &= e^{-3x} \end{aligned}$$

Multiplying both sides of the ODE by the integrating factor $M(x)$ makes the left side of the ODE a complete differential

$$\begin{aligned} (M(x)y)'' &= e^{-3x} e^x x^2 (e^{2x} + x e^x + x^2) \\ (e^{-3x}y)'' &= e^{-3x} e^x x^2 (e^{2x} + x e^x + x^2) \end{aligned}$$

Integrating once gives

$$(e^{-3x}y)' = \frac{(-2x^4 - 4x^3 - 6x^2 - 6x - 3)e^{-2x}}{4} + (-x^3 - 3x^2 - 6x - 6)e^{-x} + \frac{x^3}{3} + c_1$$

Integrating again gives

$$(e^{-3x}y) = \frac{(2x^4 + 8x^3 + 18x^2 + 24x + 15)e^{-2x}}{8} + (x^3 + 6x^2 + 18x + 24)e^{-x} + \frac{x^4}{12} + c_1x + c_2$$

Hence the solution is

$$y = \frac{(2x^4 + 8x^3 + 18x^2 + 24x + 15)e^{-2x}}{8} + (x^3 + 6x^2 + 18x + 24)e^{-x} + \frac{x^4}{12} + c_1x + c_2$$

Or

$$\begin{aligned} y &= \frac{x^4 e^{3x}}{12} + c_1 x e^{3x} + \frac{x^4 e^x}{4} + x^3 e^{2x} + e^{3x} c_2 + x^3 e^x \\ &\quad + 6x^2 e^{2x} + \frac{9x^2 e^x}{4} + 18 e^{2x} x + 3x e^x + 24 e^{2x} + \frac{15 e^x}{8} \end{aligned}$$

Summary

The solution(s) found are the following

$$y = \frac{x^4 e^{3x}}{12} + c_1 x e^{3x} + \frac{x^4 e^x}{4} + x^3 e^{2x} + e^{3x} c_2 + x^3 e^x + 6x^2 e^{2x} + \frac{9x^2 e^x}{4} + 18 e^{2x} x + 3x e^x + 24 e^{2x} + \frac{15 e^x}{8} \quad (1)$$

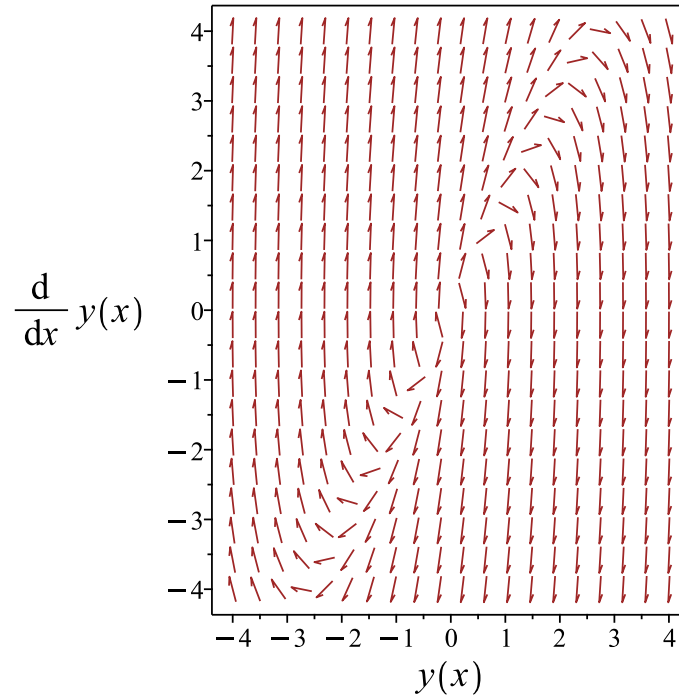


Figure 480: Slope field plot

Verification of solutions

$$y = \frac{x^4 e^{3x}}{12} + c_1 x e^{3x} + \frac{x^4 e^x}{4} + x^3 e^{2x} + e^{3x} c_2 + x^3 e^x + 6x^2 e^{2x} + \frac{9x^2 e^x}{4} + 18 e^{2x} x + 3x e^x + 24 e^{2x} + \frac{15 e^x}{8}$$

Verified OK.

11.44.3 Solving using Kovacic algorithm

Writing the ode as

$$y'' - 6y' + 9y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= -6 \\ C &= 9 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{0}{1} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 0 \\ t &= 1 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = 0 \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 415: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - -\infty \\ &= \infty \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is *infinity* then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = 0$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = 1$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-6}{1} dx} \end{aligned}$$

$$\begin{aligned}
&= z_1 e^{3x} \\
&= z_1 (e^{3x})
\end{aligned}$$

Which simplifies to

$$y_1 = e^{3x}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}
y_2 &= y_1 \int \frac{e^{\int -\frac{6}{1} dx}}{(y_1)^2} dx \\
&= y_1 \int \frac{e^{6x}}{(y_1)^2} dx \\
&= y_1(x)
\end{aligned}$$

Therefore the solution is

$$\begin{aligned}
y &= c_1 y_1 + c_2 y_2 \\
&= c_1 (e^{3x}) + c_2 (e^{3x}(x))
\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' - 6y' + 9y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1 e^{3x} + e^{3x} c_2 x$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$e^x x^2 (e^{2x} + x e^x + x^2)$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{x e^{3x}, e^{3x} x^2, e^{3x}\}, \{x^2 e^{2x}, x^3 e^{2x}, e^{2x} x, e^{2x}\}, \{x e^x, x^2 e^x, x^3 e^x, x^4 e^x, e^x\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{x e^{3x}, e^{3x}\}$$

Since e^{3x} is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[\{x^3 e^{3x}, x^4 e^{3x}, e^{3x} x^2\}, \{x^2 e^{2x}, x^3 e^{2x}, e^{2x} x, e^{2x}\}, \{x e^x, x^2 e^x, x^3 e^x, x^4 e^x, e^x\}]$$

Since $x e^{3x}$ is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[\{x^3 e^{3x}, x^4 e^{3x}, e^{3x} x^2\}, \{x^2 e^{2x}, x^3 e^{2x}, e^{2x} x, e^{2x}\}, \{x e^x, x^2 e^x, x^3 e^x, x^4 e^x, e^x\}]$$

Since there was duplication between the basis functions in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis function in the above updated UC_set.

$$y_p = A_1 x^3 e^{3x} + A_2 x^4 e^{3x} + A_3 e^{3x} x^2 + A_4 x^2 e^{2x} + A_5 x^3 e^{2x} + A_6 e^{2x} x + A_7 e^{2x} + A_8 x e^x + A_9 x^2 e^x + A_{10} x^3 e^x + A_{11} x^4 e^x + A_{12} e^x$$

The unknowns $\{A_1, A_2, A_3, A_4, A_5, A_6, A_7, A_8, A_9, A_{10}, A_{11}, A_{12}\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$\begin{aligned} & 2A_3 e^{3x} + 2A_4 e^{2x} + 2A_9 e^x - 2A_6 e^{2x} - 4A_8 e^x + A_7 e^{2x} + 4A_{12} e^x + A_6 e^{2x} x \\ & + 4A_8 x e^x + 4A_9 x^2 e^x + 4A_{10} x^3 e^x + 4A_{11} x^4 e^x + A_4 x^2 e^{2x} + A_5 x^3 e^{2x} \\ & - 6A_5 x^2 e^{2x} - 8A_9 x e^x - 12A_{10} x^2 e^x - 16A_{11} x^3 e^x + 6A_1 x e^{3x} + 12A_2 x^2 e^{3x} \\ & + 6A_5 x e^{2x} + 6A_{10} x e^x + 12A_{11} x^2 e^x - 4A_4 x e^{2x} = e^x x^2 (e^{2x} + x e^x + x^2) \end{aligned}$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = 0, A_2 = \frac{1}{12}, A_3 = 0, A_4 = 6, A_5 = 1, A_6 = 18, A_7 = 24, A_8 = 3, A_9 = \frac{9}{4}, A_{10} = 1, A_{11} = \frac{1}{4}, A_{12} = \frac{1}{8} \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = \frac{x^4 e^{3x}}{12} + 6x^2 e^{2x} + x^3 e^{2x} + 18e^{2x}x + 24e^{2x} + 3xe^x + \frac{9x^2 e^x}{4} + x^3 e^x + \frac{x^4 e^x}{4} + \frac{15e^x}{8}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 e^{3x} + e^{3x} c_2 x) \\ &\quad + \left(\frac{x^4 e^{3x}}{12} + 6x^2 e^{2x} + x^3 e^{2x} + 18e^{2x}x + 24e^{2x} + 3xe^x + \frac{9x^2 e^x}{4} + x^3 e^x + \frac{x^4 e^x}{4} + \frac{15e^x}{8} \right) \end{aligned}$$

Which simplifies to

$$\begin{aligned} y &= e^{3x}(c_2 x + c_1) + \frac{x^4 e^{3x}}{12} + 6x^2 e^{2x} + x^3 e^{2x} + 18e^{2x}x \\ &\quad + 24e^{2x} + 3xe^x + \frac{9x^2 e^x}{4} + x^3 e^x + \frac{x^4 e^x}{4} + \frac{15e^x}{8} \end{aligned}$$

Summary

The solution(s) found are the following

$$\begin{aligned} y &= e^{3x}(c_2 x + c_1) + \frac{x^4 e^{3x}}{12} + 6x^2 e^{2x} + x^3 e^{2x} + 18e^{2x}x \\ &\quad + 24e^{2x} + 3xe^x + \frac{9x^2 e^x}{4} + x^3 e^x + \frac{x^4 e^x}{4} + \frac{15e^x}{8} \end{aligned} \tag{1}$$

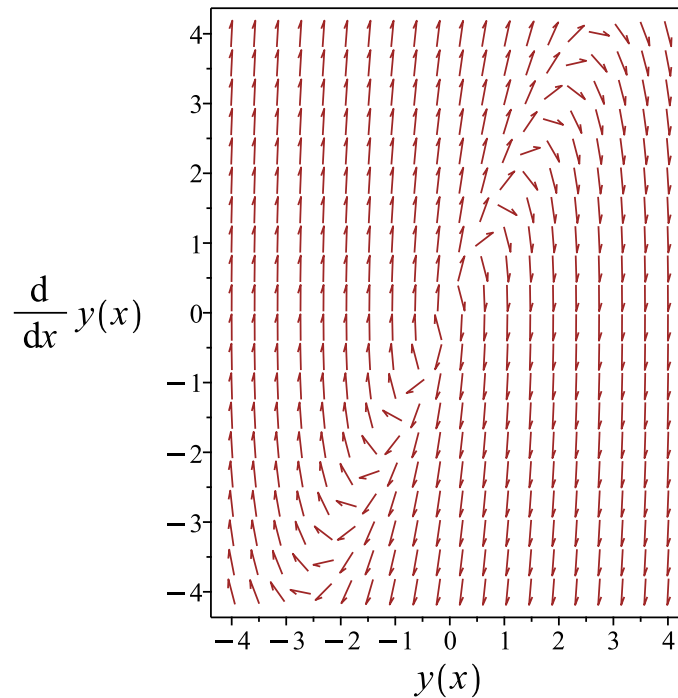


Figure 481: Slope field plot

Verification of solutions

$$y = e^{3x}(c_2x + c_1) + \frac{x^4 e^{3x}}{12} + 6x^2 e^{2x} + x^3 e^{2x} + 18e^{2x}x + 24e^{2x} + 3x e^x + \frac{9x^2 e^x}{4} + x^3 e^x + \frac{x^4 e^x}{4} + \frac{15e^x}{8}$$

Verified OK.

11.44.4 Maple step by step solution

Let's solve

$$y'' - 6y' + 9y = e^x x^2 (e^{2x} + x e^x + x^2)$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of homogeneous ODE

$$r^2 - 6r + 9 = 0$$

- Factor the characteristic polynomial

$$(r - 3)^2 = 0$$

- Root of the characteristic polynomial

$$r = 3$$

- 1st solution of the homogeneous ODE

$$y_1(x) = e^{3x}$$

- Repeated root, multiply $y_1(x)$ by x to ensure linear independence

$$y_2(x) = x e^{3x}$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = c_1 e^{3x} + e^{3x} c_2 x + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = e^x x^2 (e^{2x} + x e^x + x^2) \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} e^{3x} & x e^{3x} \\ 3 e^{3x} & e^{3x} + 3x e^{3x} \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = e^{6x}$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = e^{3x} \left(- \left(\int x^3 e^{-2x} (e^{2x} + x e^x + x^2) dx \right) + \left(\int x^2 e^{-2x} (e^{2x} + x e^x + x^2) dx \right) x \right)$$

- Compute integrals

$$y_p(x) = \frac{e^x \left(\frac{45}{2} + e^{2x} x^4 + 12(x^3 + 6x^2 + 18x + 24)e^x + 3x^4 + 12x^3 + 27x^2 + 36x \right)}{12}$$

- Substitute particular solution into general solution to ODE

$$y = c_1 e^{3x} + e^{3x} c_2 x + \frac{e^x \left(\frac{45}{2} + e^{2x} x^4 + 12(x^3 + 6x^2 + 18x + 24)e^x + 3x^4 + 12x^3 + 27x^2 + 36x \right)}{12}$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]  
trying a double symmetry of the form [xi=0, eta=F(x)]  
-> Try solving first the homogeneous part of the ODE  
    checking if the LODE has constant coefficients  
    <- constant coefficients successful  
<- solving first the homogeneous part of the ODE successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 62

```
dsolve(diff(y(x), x$2)-6*diff(y(x), x)+9*y(x)=x^4*exp(x)+x^3*exp(2*x)+x^2*exp(3*x), y(x), sings
```

$$y(x) = (x^3 + 6x^2 + 18x + 24) e^{2x} + \frac{(x^4 + 12c_1x + 12c_2) e^{3x}}{12} + \frac{(x^4 + 4x^3 + 9x^2 + 12x + \frac{15}{2}) e^x}{4}$$

✓ Solution by Mathematica

Time used: 1.391 (sec). Leaf size: 70

```
DSolve[y''[x]-6*y'[x]+9*y[x]==x^4*Exp[x]+x^3*Exp[2*x]+x^2*Exp[3*x], y[x], x, IncludeSingularSol
```

$$y(x) \rightarrow e^x \left(\frac{x^4}{4} + e^{2x} \left(\frac{x^4}{12} + c_2x + c_1 \right) + x^3 + \frac{9x^2}{4} + e^x (x^3 + 6x^2 + 18x + 24) + 3x + \frac{15}{8} \right)$$

11.45 problem 45

11.45.1 Solving as second order linear constant coeff ode	2744
11.45.2 Solving using Kovacic algorithm	2750
11.45.3 Maple step by step solution	2758

Internal problem ID [11819]

Internal file name [OUTPUT/11828_Thursday_April_11_2024_08_50_07_PM_24839565/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 45.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"kovacic", "second_order_linear_constant_coeff"**

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' + 6y' + 13y = x e^{-3x} \sin(2x) + x^2 e^{-2x} \sin(3x)$$

11.45.1 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = 6, C = 13, f(x) = x e^{-2x}(x \sin(3x) + e^{-x} \sin(2x))$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 6y' + 13y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 6, C = 13$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + 6\lambda e^{\lambda x} + 13 e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 6\lambda + 13 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 6, C = 13$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{-6}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{6^2 - (4)(1)(13)} \\ &= -3 \pm 2i \end{aligned}$$

Hence

$$\begin{aligned} \lambda_1 &= -3 + 2i \\ \lambda_2 &= -3 - 2i \end{aligned}$$

Which simplifies to

$$\begin{aligned} \lambda_1 &= -3 + 2i \\ \lambda_2 &= -3 - 2i \end{aligned}$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = -3$ and $\beta = 2$. Therefore the final solution, when using Euler relation, can be written as

$$y = e^{\alpha x} (c_1 \cos(\beta x) + c_2 \sin(\beta x))$$

Which becomes

$$y = e^{-3x} (c_1 \cos(2x) + c_2 \sin(2x))$$

Therefore the homogeneous solution y_h is

$$y_h = e^{-3x}(c_1 \cos(2x) + c_2 \sin(2x))$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = e^{-3x} \cos(2x)$$

$$y_2 = e^{-3x} \sin(2x)$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} e^{-3x} \cos(2x) & e^{-3x} \sin(2x) \\ \frac{d}{dx}(e^{-3x} \cos(2x)) & \frac{d}{dx}(e^{-3x} \sin(2x)) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} e^{-3x} \cos(2x) & e^{-3x} \sin(2x) \\ -3e^{-3x} \cos(2x) - 2e^{-3x} \sin(2x) & -3e^{-3x} \sin(2x) + 2e^{-3x} \cos(2x) \end{vmatrix}$$

Therefore

$$W = (e^{-3x} \cos(2x)) (-3e^{-3x} \sin(2x) + 2e^{-3x} \cos(2x)) \\ - (e^{-3x} \sin(2x)) (-3e^{-3x} \cos(2x) - 2e^{-3x} \sin(2x))$$

Which simplifies to

$$W = 2e^{-6x} \cos(2x)^2 + 2e^{-6x} \sin(2x)^2$$

Which simplifies to

$$W = 2e^{-6x}$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{e^{-3x} \sin(2x) x e^{-2x} (x \sin(3x) + e^{-x} \sin(2x))}{2e^{-6x}} dx$$

Which simplifies to

$$u_1 = - \int \frac{x \sin(2x) (\sin(3x) x e^x + \sin(2x))}{2} dx$$

Hence

$$u_1 = - \left(\frac{x^2}{2} - \frac{1}{2} \right) \frac{e^x \cos(x)}{4} + \frac{\left(-\frac{1}{2}x^2 + x - \frac{1}{2} \right) e^x \sin(x)}{4} \\ + \frac{\left(\frac{1}{26}x^2 + \frac{12}{169}x - \frac{37}{4394} \right) e^x \cos(5x)}{4} - \frac{\left(-\frac{5}{26}x^2 + \frac{5}{169}x + \frac{55}{4394} \right) e^x \sin(5x)}{4} \\ - 2x \left(-\frac{\cos(x) \sin(x)}{2} + \frac{x}{2} \right) + \frac{x^2}{8} - \frac{\sin(x)^2}{2} \\ + 2x \left(-\frac{\left(\sin(x)^3 + \frac{3 \sin(x)}{2} \right) \cos(x)}{4} + \frac{3x}{8} \right) + \frac{(2 \cos(x)^2 - 5)^2}{32}$$

And Eq. (3) becomes

$$u_2 = \int \frac{e^{-3x} \cos(2x) x e^{-2x} (x \sin(3x) + e^{-x} \sin(2x))}{2e^{-6x}} dx$$

Which simplifies to

$$u_2 = \int \frac{x \cos(2x) (\sin(3x) x e^x + \sin(2x))}{2} dx$$

Hence

$$\begin{aligned} u_2 = & \frac{\left(-\frac{5}{26}x^2 + \frac{5}{169}x + \frac{55}{4394}\right) e^x \cos(5x)}{4} + \frac{\left(\frac{1}{26}x^2 + \frac{12}{169}x - \frac{37}{4394}\right) e^x \sin(5x)}{4} \\ & + \frac{\left(-\frac{1}{2}x^2 + x - \frac{1}{2}\right) e^x \cos(x)}{4} + \frac{\left(\frac{x^2}{2} - \frac{1}{2}\right) e^x \sin(x)}{4} - \frac{x \cos(x)^4}{2} \\ & + \frac{\left(\cos(x)^3 + \frac{3\cos(x)}{2}\right) \sin(x)}{8} - \frac{x}{16} + \frac{\cos(x)^2 x}{2} - \frac{\cos(x) \sin(x)}{4} \end{aligned}$$

Which simplifies to

$$\begin{aligned} u_1 = & \frac{e^x \left(x^2 + \frac{24}{13}x - \frac{37}{169}\right) \cos(5x)}{104} + \frac{5 e^x \left(x^2 - \frac{2}{13}x - \frac{11}{169}\right) \sin(5x)}{104} \\ & - \frac{\left((1+x) \cos(x) + \sin(x)(x-1)\right) (x-1) e^x}{8} + \frac{\cos(x)^4}{8} \\ & - \frac{5 \cos(x)^2}{8} - \frac{x(\sin(x)^2 - \frac{1}{2}) \sin(x) \cos(x)}{2} - \frac{x^2}{8} - \frac{\sin(x)^2}{2} + \frac{25}{32} \\ u_2 = & -\frac{5 e^x \left(x^2 - \frac{2}{13}x - \frac{11}{169}\right) \cos(5x)}{104} + \frac{(338x^2 + 624x - 74) e^x \sin(5x)}{35152} \\ & - \frac{\left((x-1) \cos(x) - \sin(x)(1+x)\right) (x-1) e^x}{8} - \frac{x \cos(x)^4}{2} \\ & + \frac{\cos(x)^3 \sin(x)}{8} + \frac{\cos(x)^2 x}{2} - \frac{\cos(x) \sin(x)}{16} - \frac{x}{16} \end{aligned}$$

Therefore the particular solution, from equation (1) is

$$\begin{aligned}
 y_p(x) = & \left(\frac{e^x(x^2 + \frac{24}{13}x - \frac{37}{169}) \cos(5x)}{104} + \frac{5e^x(x^2 - \frac{2}{13}x - \frac{11}{169}) \sin(5x)}{104} \right. \\
 & - \frac{((1+x)\cos(x) + \sin(x)(x-1))(x-1)e^x}{8} + \frac{\cos(x)^4}{8} - \frac{5\cos(x)^2}{8} \\
 & \left. - \frac{x(\sin(x)^2 - \frac{1}{2})\sin(x)\cos(x)}{2} - \frac{x^2}{8} - \frac{\sin(x)^2}{2} + \frac{25}{32} \right) e^{-3x} \cos(2x) \\
 & + \left(-\frac{5e^x(x^2 - \frac{2}{13}x - \frac{11}{169}) \cos(5x)}{104} + \frac{(338x^2 + 624x - 74)e^x \sin(5x)}{35152} \right. \\
 & - \frac{((x-1)\cos(x) - \sin(x)(1+x))(x-1)e^x}{8} - \frac{x\cos(x)^4}{2} + \frac{\cos(x)^3 \sin(x)}{8} \\
 & \left. + \frac{\cos(x)^2 x}{2} - \frac{\cos(x)\sin(x)}{16} - \frac{x}{16} \right) e^{-3x} \sin(2x)
 \end{aligned}$$

Which simplifies to

$$\begin{aligned}
 y_p(x) = & \frac{6\left(e^x\left(x^2 - \frac{2}{13}x - \frac{180}{169}\right)\cos(x)^3 + \left(\frac{2\left(x^2 - \frac{41}{13}x + \frac{563}{338}\right)\sin(x)e^x}{3} + \frac{13x^2}{24} - \frac{39}{32}\right)\cos(x)^2 + \left(\left(-\frac{3}{4}x^2 + \frac{3}{26}x + \frac{135}{169}\right)e^x\right)}{13}
 \end{aligned}$$

Therefore the general solution is

$$\begin{aligned}
 y = & y_h + y_p \\
 = & (e^{-3x}(c_1 \cos(2x) + c_2 \sin(2x))) \\
 & + \left(-\frac{6\left(e^x\left(x^2 - \frac{2}{13}x - \frac{180}{169}\right)\cos(x)^3 + \left(\frac{2\left(x^2 - \frac{41}{13}x + \frac{563}{338}\right)\sin(x)e^x}{3} + \frac{13x^2}{24} - \frac{39}{32}\right)\cos(x)^2 + \left(\left(-\frac{3}{4}x^2 + \frac{3}{26}x + \frac{135}{169}\right)e^x\right)}{13} \right)
 \end{aligned}$$

Summary

The solution(s) found are the following

$$\begin{aligned}
 y = & e^{-3x}(c_1 \cos(2x) + c_2 \sin(2x)) \tag{1} \\
 & - \frac{6\left(e^x\left(x^2 - \frac{2}{13}x - \frac{180}{169}\right)\cos(x)^3 + \left(\frac{2\left(x^2 - \frac{41}{13}x + \frac{563}{338}\right)\sin(x)e^x}{3} + \frac{13x^2}{24} - \frac{39}{32}\right)\cos(x)^2 + \left(\left(-\frac{3}{4}x^2 + \frac{3}{26}x + \frac{135}{169}\right)e^x\right)}{13}
 \end{aligned}$$

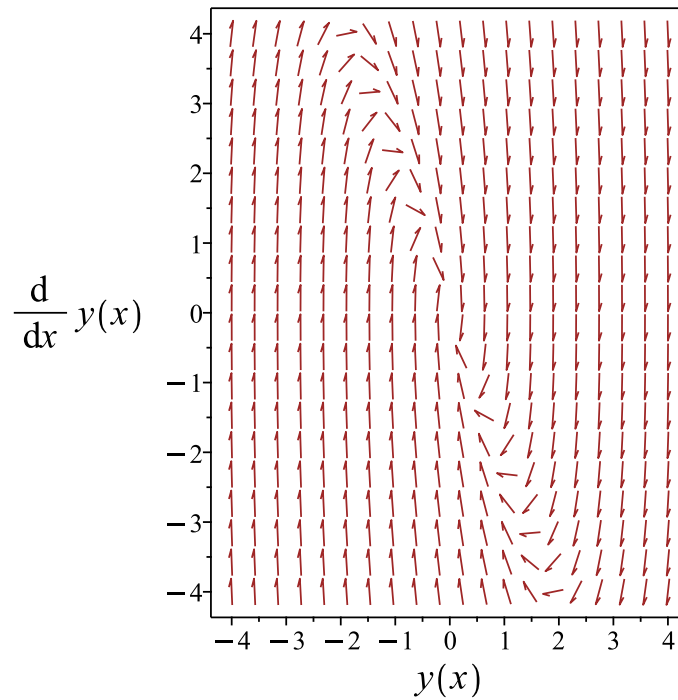


Figure 482: Slope field plot

Verification of solutions

$$y = e^{-3x}(c_1 \cos(2x) + c_2 \sin(2x))$$

$$6 \left(e^x \left(x^2 - \frac{2}{13}x - \frac{180}{169} \right) \cos(x)^3 + \left(\frac{2(x^2 - \frac{41}{13}x + \frac{563}{338}) \sin(x)e^x}{3} + \frac{13x^2}{24} - \frac{39}{32} \right) \cos(x)^2 + \left(\left(-\frac{3}{4}x^2 + \frac{3}{26}x + \frac{135}{169} \right) e^x \right) \right)$$

13

Verified OK.

11.45.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' + 6y' + 13y = 0 \tag{1}$$

$$Ay'' + By' + Cy = 0 \tag{2}$$

Comparing (1) and (2) shows that

$$A = 1$$

$$B = 6 \tag{3}$$

$$C = 13$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-4}{1} \tag{6}$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= -4 \\ t &= 1 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = -4z(x) \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 417: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned}
 \mathcal{O}(\infty) &= \deg(t) - \deg(s) \\
 &= 0 - 0 \\
 &= 0
 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = -4$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = \cos(2x)$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned}
 y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\
 &= z_1 e^{-\int \frac{1}{2} \frac{6}{1} dx} \\
 &= z_1 e^{-3x} \\
 &= z_1 (e^{-3x})
 \end{aligned}$$

Which simplifies to

$$y_1 = e^{-3x} \cos(2x)$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{6}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{-6x}}{(y_1)^2} dx \\ &= y_1 \left(\frac{\tan(2x)}{2} \right) \end{aligned}$$

Therefore the solution is

$$\begin{aligned} y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (e^{-3x} \cos(2x)) + c_2 \left(e^{-3x} \cos(2x) \left(\frac{\tan(2x)}{2} \right) \right) \end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 6y' + 13y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1 e^{-3x} \cos(2x) + \frac{e^{-3x} \sin(2x) c_2}{2}$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of

parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = e^{-3x} \cos(2x)$$

$$y_2 = \frac{e^{-3x} \sin(2x)}{2}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} e^{-3x} \cos(2x) & \frac{e^{-3x} \sin(2x)}{2} \\ \frac{d}{dx}(e^{-3x} \cos(2x)) & \frac{d}{dx}\left(\frac{e^{-3x} \sin(2x)}{2}\right) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} e^{-3x} \cos(2x) & \frac{e^{-3x} \sin(2x)}{2} \\ -3e^{-3x} \cos(2x) - 2e^{-3x} \sin(2x) & -\frac{3e^{-3x} \sin(2x)}{2} + e^{-3x} \cos(2x) \end{vmatrix}$$

Therefore

$$W = (e^{-3x} \cos(2x)) \left(-\frac{3e^{-3x} \sin(2x)}{2} + e^{-3x} \cos(2x) \right) - \left(\frac{e^{-3x} \sin(2x)}{2} \right) (-3e^{-3x} \cos(2x) - 2e^{-3x} \sin(2x))$$

Which simplifies to

$$W = e^{-6x} \cos(2x)^2 + e^{-6x} \sin(2x)^2$$

Which simplifies to

$$W = e^{-6x}$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{e^{-3x} \sin(2x) x e^{-2x} (x \sin(3x) + e^{-x} \sin(2x))}{e^{-6x}} dx$$

Which simplifies to

$$u_1 = - \int \frac{x \sin(2x) (\sin(3x) x e^x + \sin(2x))}{2} dx$$

Hence

$$\begin{aligned} u_1 = & - \frac{\left(\frac{x^2}{2} - \frac{1}{2}\right) e^x \cos(x)}{4} + \frac{\left(-\frac{1}{2}x^2 + x - \frac{1}{2}\right) e^x \sin(x)}{4} \\ & + \frac{\left(\frac{1}{26}x^2 + \frac{12}{169}x - \frac{37}{4394}\right) e^x \cos(5x)}{4} - \frac{\left(-\frac{5}{26}x^2 + \frac{5}{169}x + \frac{55}{4394}\right) e^x \sin(5x)}{4} \\ & - 2x \left(-\frac{\cos(x) \sin(x)}{2} + \frac{x}{2} \right) + \frac{x^2}{8} - \frac{\sin(x)^2}{2} \\ & + 2x \left(-\frac{\left(\sin(x)^3 + \frac{3\sin(x)}{2}\right) \cos(x)}{4} + \frac{3x}{8} \right) + \frac{(2 \cos(x)^2 - 5)^2}{32} \end{aligned}$$

And Eq. (3) becomes

$$u_2 = \int \frac{e^{-3x} \cos(2x) x e^{-2x} (x \sin(3x) + e^{-x} \sin(2x))}{e^{-6x}} dx$$

Which simplifies to

$$u_2 = \int x \cos(2x) (\sin(3x) x e^x + \sin(2x)) dx$$

Hence

$$\begin{aligned}
 u_2 = & \frac{\left(-\frac{5}{26}x^2 + \frac{5}{169}x + \frac{55}{4394}\right) e^x \cos(5x)}{2} + \frac{\left(\frac{1}{26}x^2 + \frac{12}{169}x - \frac{37}{4394}\right) e^x \sin(5x)}{2} \\
 & + \frac{\left(-\frac{1}{2}x^2 + x - \frac{1}{2}\right) e^x \cos(x)}{2} + \frac{\left(\frac{x^2}{2} - \frac{1}{2}\right) e^x \sin(x)}{2} - x \cos(x)^4 \\
 & + \frac{\left(\cos(x)^3 + \frac{3\cos(x)}{2}\right) \sin(x)}{4} - \frac{x}{8} + \cos(x)^2 x - \frac{\cos(x) \sin(x)}{2}
 \end{aligned}$$

Which simplifies to

$$\begin{aligned}
 u_1 = & \frac{e^x \left(x^2 + \frac{24}{13}x - \frac{37}{169}\right) \cos(5x)}{104} + \frac{5 e^x \left(x^2 - \frac{2}{13}x - \frac{11}{169}\right) \sin(5x)}{104} \\
 & - \frac{\left((1+x) \cos(x) + \sin(x)(x-1)\right)(x-1) e^x}{8} + \frac{\cos(x)^4}{8} \\
 & - \frac{5 \cos(x)^2}{8} - \frac{x(\sin(x)^2 - \frac{1}{2}) \sin(x) \cos(x)}{2} - \frac{x^2}{8} - \frac{\sin(x)^2}{2} + \frac{25}{32} \\
 u_2 = & -\frac{5 e^x \left(x^2 - \frac{2}{13}x - \frac{11}{169}\right) \cos(5x)}{52} + \frac{(169x^2 + 312x - 37) e^x \sin(5x)}{8788} \\
 & - \frac{\left((x-1) \cos(x) - \sin(x)(1+x)\right)(x-1) e^x}{4} - x \cos(x)^4 \\
 & + \frac{\cos(x)^3 \sin(x)}{4} + \cos(x)^2 x - \frac{\cos(x) \sin(x)}{8} - \frac{x}{8}
 \end{aligned}$$

Therefore the particular solution, from equation (1) is

$$\begin{aligned}
 y_p(x) = & \left(\frac{e^x \left(x^2 + \frac{24}{13}x - \frac{37}{169}\right) \cos(5x)}{104} + \frac{5 e^x \left(x^2 - \frac{2}{13}x - \frac{11}{169}\right) \sin(5x)}{104} \right. \\
 & - \frac{\left((1+x) \cos(x) + \sin(x)(x-1)\right)(x-1) e^x}{8} + \frac{\cos(x)^4}{8} - \frac{5 \cos(x)^2}{8} \\
 & \left. - \frac{x(\sin(x)^2 - \frac{1}{2}) \sin(x) \cos(x)}{2} - \frac{x^2}{8} - \frac{\sin(x)^2}{2} + \frac{25}{32} \right) e^{-3x} \cos(2x) \\
 & + \frac{\left(-\frac{5 e^x \left(x^2 - \frac{2}{13}x - \frac{11}{169}\right) \cos(5x)}{52} + \frac{(169x^2 + 312x - 37) e^x \sin(5x)}{8788} - \frac{\left((x-1) \cos(x) - \sin(x)(1+x)\right)(x-1) e^x}{4} - x \cos(x)^4 + \frac{\cos(x)^3 \sin(x)}{4} \right)}{2}
 \end{aligned}$$

Which simplifies to

$$y_p(x) = \frac{6 \left(e^x \left(x^2 - \frac{2}{13}x - \frac{180}{169}\right) \cos(x)^3 + \left(\frac{2 \left(x^2 - \frac{41}{13}x + \frac{563}{338}\right) \sin(x) e^x}{3} + \frac{13x^2}{24} - \frac{39}{32} \right) \cos(x)^2 + \left(\left(-\frac{3}{4}x^2 + \frac{3}{26}x + \frac{135}{169}\right) e^x \right)}{13}$$

Therefore the general solution is

$$y = y_h + y_p$$

$$= \left(c_1 e^{-3x} \cos(2x) + \frac{e^{-3x} \sin(2x) c_2}{2} \right)$$

$$+ \left(\frac{6 \left(e^x \left(x^2 - \frac{2}{13}x - \frac{180}{169} \right) \cos(x)^3 + \left(\frac{2 \left(x^2 - \frac{41}{13}x + \frac{563}{338} \right) \sin(x) e^x}{3} + \frac{13x^2}{24} - \frac{39}{32} \right) \cos(x)^2 + \left(\left(-\frac{3}{4}x^2 + \frac{3}{26}x + \frac{135}{169} \right) e^x \right)}{13} \right)$$

Summary

The solution(s) found are the following

$$y = c_1 e^{-3x} \cos(2x) + \frac{e^{-3x} \sin(2x) c_2}{2} \tag{1}$$

$$+ \frac{6 \left(e^x \left(x^2 - \frac{2}{13}x - \frac{180}{169} \right) \cos(x)^3 + \left(\frac{2 \left(x^2 - \frac{41}{13}x + \frac{563}{338} \right) \sin(x) e^x}{3} + \frac{13x^2}{24} - \frac{39}{32} \right) \cos(x)^2 + \left(\left(-\frac{3}{4}x^2 + \frac{3}{26}x + \frac{135}{169} \right) e^x \right)}{13}$$

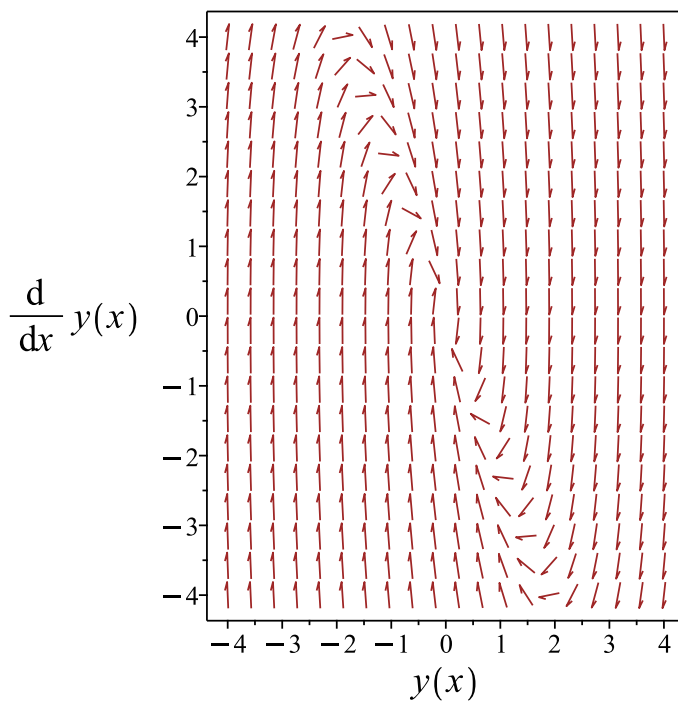


Figure 483: Slope field plot

Verification of solutions

$$y = c_1 e^{-3x} \cos(2x) + \frac{e^{-3x} \sin(2x) c_2}{2}$$

$$6 \left(e^x \left(x^2 - \frac{2}{13}x - \frac{180}{169} \right) \cos(x)^3 + \left(\frac{2(x^2 - \frac{41}{13}x + \frac{563}{338}) \sin(x) e^x}{3} + \frac{13x^2}{24} - \frac{39}{32} \right) \cos(x)^2 + \left(-\frac{3}{4}x^2 + \frac{3}{26}x + \frac{135}{169} \right) e^x \right)$$

13

Verified OK.

11.45.3 Maple step by step solution

Let's solve

$$y'' + 6y' + 13y = x e^{-2x} (x \sin(3x) + e^{-x} \sin(2x))$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of homogeneous ODE

$$r^2 + 6r + 13 = 0$$

- Use quadratic formula to solve for r

$$r = \frac{(-6) \pm (\sqrt{-16})}{2}$$

- Roots of the characteristic polynomial

$$r = (-3 - 2I, -3 + 2I)$$

- 1st solution of the homogeneous ODE

$$y_1(x) = e^{-3x} \cos(2x)$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = e^{-3x} \sin(2x)$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = c_1 e^{-3x} \cos(2x) + e^{-3x} \sin(2x) c_2 + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right) \right], f(x) = x e^{-2x} (x \sin(3x) + e^{-x})$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} e^{-3x} \cos(2x) & e^{-3x} \sin(2x) \\ -3e^{-3x} \cos(2x) - 2e^{-3x} \sin(2x) & -3e^{-3x} \sin(2x) + 2e^{-3x} \cos(2x) \end{bmatrix}$$

- o Compute Wronskian

$$W(y_1(x), y_2(x)) = 2e^{-6x}$$

- o Substitute functions into equation for $y_p(x)$

$$y_p(x) = -\frac{e^{-3x}(\cos(2x)(\int x \sin(2x)(\sin(3x)x e^x + \sin(2x))dx) - \sin(2x)(\int x \cos(2x)(\sin(3x)x e^x + \sin(2x))dx))}{2}$$

- o Compute integrals

$$y_p(x) = -\frac{6\left(e^x\left(x^2 - \frac{2}{13}x - \frac{180}{169}\right)\cos(x)^3 + \left(\frac{2\left(x^2 - \frac{41}{13}x + \frac{563}{338}\right)\sin(x)e^x}{3} + \frac{13x^2}{24} - \frac{39}{32}\right)\cos(x)^2 + \left(-\frac{3}{4}x^2 + \frac{3}{26}x + \frac{135}{169}\right)e^x - \frac{13x \sin(x)}{48}\right)}{13}$$

- Substitute particular solution into general solution to ODE

$$y = c_1 e^{-3x} \cos(2x) + e^{-3x} \sin(2x) c_2 - \frac{6\left(e^x\left(x^2 - \frac{2}{13}x - \frac{180}{169}\right)\cos(x)^3 + \left(\frac{2\left(x^2 - \frac{41}{13}x + \frac{563}{338}\right)\sin(x)e^x}{3} + \frac{13x^2}{24} - \frac{39}{32}\right)\cos(x)^2 + \left(-\frac{3}{4}x^2 + \frac{3}{26}x + \frac{135}{169}\right)e^x - \frac{13x \sin(x)}{48}\right)}{13}$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
trying a double symmetry of the form [xi=0, eta=F(x)]
-> Try solving first the homogeneous part of the ODE
    checking if the LODE has constant coefficients
    <- constant coefficients successful
<- solving first the homogeneous part of the ODE successful`

```

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 68

```
dsolve(diff(y(x), x$2)+6*diff(y(x), x)+13*y(x)=x*exp(-3*x)*sin(2*x)+x^2*exp(-2*x)*sin(3*x), y(x))
```

$y(x) =$

$$3\left(\left(\frac{13x^2}{12} - \frac{26c_1}{3} - \frac{39}{16}\right)\cos(2x) + e^x\left(x^2 - \frac{2}{13}x - \frac{180}{169}\right)\cos(3x) + \frac{2e^x\left(x^2 - \frac{41}{13}x + \frac{563}{338}\right)\sin(3x)}{3} - \frac{13\sin(2x)(x+16c_2)}{24}\right)$$

✓ Solution by Mathematica

Time used: 1.921 (sec). Leaf size: 82

```
DSolve[y''[x]+6*y'[x]+13*y[x]==x*Exp[-3*x]*Sin[2*x]+x^2*Exp[-2*x]*Sin[3*x],y[x],x,IncludeSins]
```

$$y(x) \rightarrow \frac{e^{-3x}(-32e^x(338x^2 - 1066x + 563)\sin(3x) - 96e^x(169x^2 - 26x - 180)\cos(3x) - 2197(8x^2 - 1 - 64c_2))}{140608}$$

11.46 problem 46

11.46.1 Maple step by step solution 2764

Internal problem ID [11820]

Internal file name [OUTPUT/11829_Thursday_April_11_2024_08_51_25_PM_72330630/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 46.

ODE order: 3.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_3rd_order , _missing_y]]
```

$$y''' - 3y'' + 2y' = x^2e^x + 3e^{2x}x + 5x^2$$

This is higher order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE And y_p is a particular solution to the nonhomogeneous ODE. y_h is the solution to

$$y''' - 3y'' + 2y' = 0$$

The characteristic equation is

$$\lambda^3 - 3\lambda^2 + 2\lambda = 0$$

The roots of the above equation are

$$\lambda_1 = 0$$

$$\lambda_2 = 2$$

$$\lambda_3 = 1$$

Therefore the homogeneous solution is

$$y_h(x) = c_1 + c_2 e^x + e^{2x} c_3$$

The fundamental set of solutions for the homogeneous solution are the following

$$y_1 = 1$$

$$y_2 = e^x$$

$$y_3 = e^{2x}$$

Now the particular solution to the given ODE is found

$$y''' - 3y'' + 2y' = x^2 e^x + 3 e^{2x} x + 5x^2$$

The particular solution is found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$x^2 e^x + 3 e^{2x} x + 5x^2$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{e^{2x} x, e^{2x}\}, \{1, x, x^2\}, \{x e^x, x^2 e^x, e^x\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{1, e^x, e^{2x}\}$$

Since 1 is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[\{e^{2x} x, e^{2x}\}, \{x, x^2, x^3\}, \{x e^x, x^2 e^x, e^x\}]$$

Since e^x is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[\{e^{2x} x, e^{2x}\}, \{x, x^2, x^3\}, \{x e^x, x^2 e^x, x^3 e^x\}]$$

Since e^{2x} is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[\{x^2 e^{2x}, e^{2x} x\}, \{x, x^2, x^3\}, \{x e^x, x^2 e^x, x^3 e^x\}]$$

Since there was duplication between the basis functions in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis function in the above updated UC_set.

$$y_p = A_1 x^2 e^{2x} + A_2 e^{2x} x + A_3 x + A_4 x^2 + A_5 x^3 + A_6 x e^x + A_7 x^2 e^x + A_8 x^3 e^x$$

The unknowns $\{A_1, A_2, A_3, A_4, A_5, A_6, A_7, A_8\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$4A_1x e^{2x} - 2A_7x e^x - 3A_8x^2 e^x + 2A_3 - 6A_4 + 6A_5 - 18A_5x + 4A_4x + 6A_5x^2 + 6A_8e^x + 6A_1e^{2x} + 2A_2e^{2x} - A_6e^x = x^2e^x + 3e^{2x}x + 5x^2$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = \frac{3}{4}, A_2 = -\frac{9}{4}, A_3 = \frac{35}{4}, A_4 = \frac{15}{4}, A_5 = \frac{5}{6}, A_6 = -2, A_7 = 0, A_8 = -\frac{1}{3} \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = \frac{3x^2e^{2x}}{4} - \frac{9e^{2x}x}{4} + \frac{35x}{4} + \frac{15x^2}{4} + \frac{5x^3}{6} - 2xe^x - \frac{x^3e^x}{3}$$

Therefore the general solution is

$$y = y_h + y_p = (c_1 + c_2e^x + e^{2x}c_3) + \left(\frac{3x^2e^{2x}}{4} - \frac{9e^{2x}x}{4} + \frac{35x}{4} + \frac{15x^2}{4} + \frac{5x^3}{6} - 2xe^x - \frac{x^3e^x}{3} \right)$$

Summary

The solution(s) found are the following

$$y = c_1 + c_2e^x + e^{2x}c_3 + \frac{3x^2e^{2x}}{4} - \frac{9e^{2x}x}{4} + \frac{35x}{4} + \frac{15x^2}{4} + \frac{5x^3}{6} - 2xe^x - \frac{x^3e^x}{3} \quad (1)$$

Verification of solutions

$$y = c_1 + c_2e^x + e^{2x}c_3 + \frac{3x^2e^{2x}}{4} - \frac{9e^{2x}x}{4} + \frac{35x}{4} + \frac{15x^2}{4} + \frac{5x^3}{6} - 2xe^x - \frac{x^3e^x}{3}$$

Verified OK.

11.46.1 Maple step by step solution

Let's solve

$$y''' - 3y'' + 2y' = x^2e^x + 3e^{2x}x + 5x^2$$

- Highest derivative means the order of the ODE is 3

$$y'''$$

- Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(x)$

$$y_1(x) = y$$

- Define new variable $y_2(x)$

$$y_2(x) = y'$$

- Define new variable $y_3(x)$

$$y_3(x) = y''$$

- Isolate for $y_3'(x)$ using original ODE

$$y_3'(x) = x^2e^x + 3e^{2x}x + 5x^2 + 3y_3(x) - 2y_2(x)$$

Convert linear ODE into a system of first order ODEs

$$[y_2(x) = y_1'(x), y_3(x) = y_2'(x), y_3'(x) = x^2e^x + 3e^{2x}x + 5x^2 + 3y_3(x) - 2y_2(x)]$$

- Define vector

$$\vec{y}(x) = \begin{bmatrix} y_1(x) \\ y_2(x) \\ y_3(x) \end{bmatrix}$$

- System to solve

$$\vec{y}'(x) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & -2 & 3 \end{bmatrix} \cdot \vec{y}(x) + \begin{bmatrix} 0 \\ 0 \\ x^2e^x + 3e^{2x}x + 5x^2 \end{bmatrix}$$

- Define the forcing function

$$\vec{f}(x) = \begin{bmatrix} 0 \\ 0 \\ x^2e^x + 3e^{2x}x + 5x^2 \end{bmatrix}$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & -2 & 3 \end{bmatrix}$$

- Rewrite the system as

$$\vec{y}'(x) = A \cdot \vec{y}(x) + \vec{f}$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[0, \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \right], \left[1, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right], \left[2, \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[0, \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

- Consider eigenpair

$$\left[1, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_2 = e^x \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[2, \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_3 = e^{2x} \cdot \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix}$$

- General solution of the system of ODEs can be written in terms of the particular solution $\vec{y}_p(x)$

$$\vec{y}(x) = c_1 \vec{y}_1 + c_2 \vec{y}_2 + c_3 \vec{y}_3 + \vec{y}_p(x)$$

- Fundamental matrix

- Let $\phi(x)$ be the matrix whose columns are the independent solutions of the homogeneous system

$$\phi(x) = \begin{bmatrix} 1 & e^x & \frac{e^{2x}}{4} \\ 0 & e^x & \frac{e^{2x}}{2} \\ 0 & e^x & e^{2x} \end{bmatrix}$$

- The fundamental matrix, $\Phi(x)$ is a normalized version of $\phi(x)$ satisfying $\Phi(0) = I$ where I is the identity matrix

$$\Phi(x) = \phi(x) \cdot \frac{1}{\phi(0)}$$

- Substitute the value of $\phi(x)$ and $\phi(0)$

$$\Phi(x) = \begin{bmatrix} 1 & e^x & \frac{e^{2x}}{4} \\ 0 & e^x & \frac{e^{2x}}{2} \\ 0 & e^x & e^{2x} \end{bmatrix} \cdot \frac{1}{\begin{bmatrix} 1 & 1 & \frac{1}{4} \\ 0 & 1 & \frac{1}{2} \\ 0 & 1 & 1 \end{bmatrix}}$$

- Evaluate and simplify to get the fundamental matrix

$$\Phi(x) = \begin{bmatrix} 1 & -\frac{3}{2} + 2e^x - \frac{e^{2x}}{2} & \frac{1}{2} - e^x + \frac{e^{2x}}{2} \\ 0 & 2e^x - e^{2x} & -e^x + e^{2x} \\ 0 & 2e^x - 2e^{2x} & -e^x + 2e^{2x} \end{bmatrix}$$

- Find a particular solution of the system of ODEs using variation of parameters

- Let the particular solution be the fundamental matrix multiplied by $\vec{v}(x)$ and solve for $\vec{v}(x)$

$$\vec{y}_p(x) = \Phi(x) \cdot \vec{v}(x)$$

- Take the derivative of the particular solution

$$\vec{y}'_p(x) = \Phi'(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x)$$

- Substitute particular solution and its derivative into the system of ODEs

$$\Phi'(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x) = A \cdot \Phi(x) \cdot \vec{v}(x) + \vec{f}(x)$$

- The fundamental matrix has columns that are solutions to the homogeneous system so its derivative is

$$A \cdot \Phi(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x) = A \cdot \Phi(x) \cdot \vec{v}(x) + \vec{f}(x)$$

- Cancel like terms

$$\Phi(x) \cdot \vec{v}'(x) = \vec{f}(x)$$

- Multiply by the inverse of the fundamental matrix

$$\vec{v}'(x) = \frac{1}{\Phi(x)} \cdot \vec{f}(x)$$

- Integrate to solve for $\vec{v}(x)$

$$\vec{v}(x) = \int_0^x \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds$$

- Plug $\vec{v}(x)$ into the equation for the particular solution

$$\vec{y}_p(x) = \Phi(x) \cdot \left(\int_0^x \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds \right)$$

- Plug in the fundamental matrix and the forcing function and compute

$$\vec{y}_p(x) = \begin{bmatrix} \frac{35}{4} + \frac{(3x^2-9x+17)e^{2x}}{4} + \frac{(-x^3-6x-39)e^x}{3} + \frac{5x^3}{6} + \frac{15x^2}{4} + \frac{35x}{4} \\ \frac{35}{4} + \frac{(6x^2-12x+25)e^{2x}}{4} + \frac{(-x^3-3x^2-6x-45)e^x}{3} + \frac{5x^2}{2} + \frac{15x}{2} \\ \frac{15}{2} + \frac{(6x^2-6x+19)e^{2x}}{2} + \frac{(-x^3-6x^2-12x-51)e^x}{3} + 5x \end{bmatrix}$$

- Plug particular solution back into general solution

$$\vec{y}(x) = c_1 \vec{y}_1 + c_2 \vec{y}_2 + c_3 \vec{y}_3 + \begin{bmatrix} \frac{35}{4} + \frac{(3x^2-9x+17)e^{2x}}{4} + \frac{(-x^3-6x-39)e^x}{3} + \frac{5x^3}{6} + \frac{15x^2}{4} + \frac{35x}{4} \\ \frac{35}{4} + \frac{(6x^2-12x+25)e^{2x}}{4} + \frac{(-x^3-3x^2-6x-45)e^x}{3} + \frac{5x^2}{2} + \frac{15x}{2} \\ \frac{15}{2} + \frac{(6x^2-6x+19)e^{2x}}{2} + \frac{(-x^3-6x^2-12x-51)e^x}{3} + 5x \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y = \frac{35}{4} + \frac{(3x^2+c_3-9x+17)e^{2x}}{4} + \frac{(-x^3+3c_2-6x-39)e^x}{3} + \frac{5x^3}{6} + \frac{15x^2}{4} + \frac{35x}{4} + c_1$$

Maple trace

```
`Methods for third order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 3; linear nonhomogeneous with symmetry [0,1]
-> Calling odsolve with the ODE`, diff(diff(_b(_a), _a), _a) = _a^2*exp(_a)+3*exp(2*_a)*_a+5
  Methods for second order ODEs:
  --- Trying classification methods ---
  trying a quadrature
  trying high order exact linear fully integrable
  trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
  trying a double symmetry of the form [xi=0, eta=F(x)]
  <- double symmetry of the form [xi=0, eta=F(x)] successful
<- differential order: 3; linear nonhomogeneous with symmetry [0,1] successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 55

```
dsolve(diff(y(x),x$3)-3*diff(y(x),x$2)+2*diff(y(x),x)=x^2*exp(x)+3*x*exp(2*x)+5*x^2,y(x), si
```

$$y(x) = \frac{(6x^2 + 4c_1 - 18x + 21)e^{2x}}{8} + \frac{(-x^3 + 3c_2 - 6x + 6)e^x}{3} + \frac{5x^3}{6} + \frac{15x^2}{4} + \frac{35x}{4} + c_3$$

✓ Solution by Mathematica

Time used: 0.885 (sec). Leaf size: 67

```
DSolve[y'''[x]-3*y''[x]+2*y'[x]==x^2*Exp[x]+3*x*Exp[2*x]+5*x^2,y[x],x,IncludeSingularSolutio
```

$$y(x) \rightarrow \frac{5x^3}{6} + e^x \left(-\frac{x^3}{3} - 2x + c_1 \right) + \frac{15x^2}{4} + \frac{1}{8}e^{2x}(6x^2 - 18x + 21 + 4c_2) + \frac{35x}{4} + c_3$$

11.47 problem 47

Internal problem ID [11821]

Internal file name [OUTPUT/11830_Thursday_April_11_2024_08_51_26_PM_89373344/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 47.

ODE order: 3.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_3rd_order , _linear , _nonhomogeneous]]
```

$$y''' - 6y'' + 12y' - 8y = e^{2x}x + e^{3x}x^2$$

This is higher order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE And y_p is a particular solution to the nonhomogeneous ODE. y_h is the solution to

$$y''' - 6y'' + 12y' - 8y = 0$$

The characteristic equation is

$$\lambda^3 - 6\lambda^2 + 12\lambda - 8 = 0$$

The roots of the above equation are

$$\lambda_1 = 2$$

$$\lambda_2 = 2$$

$$\lambda_3 = 2$$

Therefore the homogeneous solution is

$$y_h(x) = c_1 e^{2x} + c_2 e^{2x} x + x^2 e^{2x} c_3$$

The fundamental set of solutions for the homogeneous solution are the following

$$y_1 = e^{2x}$$

$$y_2 = e^{2x} x$$

$$y_3 = x^2 e^{2x}$$

Now the particular solution to the given ODE is found

$$y''' - 6y'' + 12y' - 8y = e^{2x} x + e^{3x} x^2$$

The particular solution is found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$e^{2x} x + e^{3x} x^2$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{e^{2x} x, e^{2x}\}, \{x e^{3x}, e^{3x} x^2, e^{3x}\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{x^2 e^{2x}, e^{2x} x, e^{2x}\}$$

Since e^{2x} is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[\{x^2 e^{2x}, e^{2x} x\}, \{x e^{3x}, e^{3x} x^2, e^{3x}\}]$$

Since $e^{2x} x$ is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[\{x^2 e^{2x}, x^3 e^{2x}\}, \{x e^{3x}, e^{3x} x^2, e^{3x}\}]$$

Since $x^2 e^{2x}$ is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[\{x^3 e^{2x}, e^{2x} x^4\}, \{x e^{3x}, e^{3x} x^2, e^{3x}\}]$$

Since there was duplication between the basis functions in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis function in the above updated UC_set.

$$y_p = A_1 x^3 e^{2x} + A_2 e^{2x} x^4 + A_3 x e^{3x} + A_4 e^{3x} x^2 + A_5 e^{3x}$$

The unknowns $\{A_1, A_2, A_3, A_4, A_5\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$6A_4e^{3x}x + 24A_2e^{2x}x + A_3xe^{3x} + A_4e^{3x}x^2 + A_5e^{3x} + 3A_3e^{3x} + 6A_4e^{3x} + 6A_1e^{2x} = e^{2x}x + e^{3x}x^2$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = 0, A_2 = \frac{1}{24}, A_3 = -6, A_4 = 1, A_5 = 12 \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = \frac{e^{2x}x^4}{24} - 6xe^{3x} + e^{3x}x^2 + 12e^{3x}$$

Therefore the general solution is

$$y = y_h + y_p = (c_1e^{2x} + c_2e^{2x}x + x^2e^{2x}c_3) + \left(\frac{e^{2x}x^4}{24} - 6xe^{3x} + e^{3x}x^2 + 12e^{3x} \right)$$

Which simplifies to

$$y = e^{2x}(c_3x^2 + c_2x + c_1) + \frac{e^{2x}x^4}{24} - 6xe^{3x} + e^{3x}x^2 + 12e^{3x}$$

Summary

The solution(s) found are the following

$$y = e^{2x}(c_3x^2 + c_2x + c_1) + \frac{e^{2x}x^4}{24} - 6xe^{3x} + e^{3x}x^2 + 12e^{3x} \quad (1)$$

Verification of solutions

$$y = e^{2x}(c_3x^2 + c_2x + c_1) + \frac{e^{2x}x^4}{24} - 6xe^{3x} + e^{3x}x^2 + 12e^{3x}$$

Verified OK.

Maple trace

```
`Methods for third order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
trying differential order: 3; linear nonhomogeneous with symmetry [0,1]  
trying high order linear exact nonhomogeneous  
trying differential order: 3; missing the dependent variable  
checking if the LODE has constant coefficients  
<- constant coefficients successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 41

```
dsolve(diff(y(x),x$3)-6*diff(y(x),x$2)+12*diff(y(x),x)-8*y(x)=x*exp(2*x)+x^2*exp(3*x),y(x),
```

$$y(x) = \frac{(x^4 + 24c_3x^2 + 24c_2x + 24c_1)e^{2x}}{24} + e^{3x}(x^2 - 6x + 12)$$

✓ Solution by Mathematica

Time used: 0.084 (sec). Leaf size: 47

```
DSolve[y'''[x]-6*y''[x]+12*y'[x]-8*y[x]==x*Exp[2*x]+x^2*Exp[3*x],y[x],x,IncludeSingularSolut
```

$$y(x) \rightarrow \frac{1}{24}e^{2x}(x^4 + 24e^x(x^2 - 6x + 12) + 24c_3x^2 + 24c_2x + 24c_1)$$

11.48 problem 48

11.48.1 Maple step by step solution 2780

Internal problem ID [11822]

Internal file name [OUTPUT/11831_Thursday_April_11_2024_08_51_27_PM_70264925/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 48.

ODE order: 4.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

`[[_high_order , _linear , _nonhomogeneous]]`

$$y'''' + 3y''' + 4y'' + 3y' + y = x^2e^{-x} + 3e^{-\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right)$$

This is higher order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE And y_p is a particular solution to the nonhomogeneous ODE. y_h is the solution to

$$y'''' + 3y''' + 4y'' + 3y' + y = 0$$

The characteristic equation is

$$\lambda^4 + 3\lambda^3 + 4\lambda^2 + 3\lambda + 1 = 0$$

The roots of the above equation are

$$\begin{aligned}\lambda_1 &= -\frac{1}{2} - \frac{i\sqrt{3}}{2} \\ \lambda_2 &= -\frac{1}{2} + \frac{i\sqrt{3}}{2} \\ \lambda_3 &= -1 \\ \lambda_4 &= -1\end{aligned}$$

Therefore the homogeneous solution is

$$y_h(x) = c_1 e^{-x} + x e^{-x} c_2 + e^{\left(-\frac{1}{2} - \frac{i\sqrt{3}}{2}\right)x} c_3 + e^{\left(-\frac{1}{2} + \frac{i\sqrt{3}}{2}\right)x} c_4$$

The fundamental set of solutions for the homogeneous solution are the following

$$\begin{aligned}y_1 &= e^{-x} \\ y_2 &= x e^{-x} \\ y_3 &= e^{\left(-\frac{1}{2} - \frac{i\sqrt{3}}{2}\right)x} \\ y_4 &= e^{\left(-\frac{1}{2} + \frac{i\sqrt{3}}{2}\right)x}\end{aligned}$$

Now the particular solution to the given ODE is found

$$y'''' + 3y''' + 4y'' + 3y' + y = x^2 e^{-x} + 3 e^{-\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right)$$

Let the particular solution be

$$y_p = U_1 y_1 + U_2 y_2 + U_3 y_3 + U_4 y_4$$

Where y_i are the basis solutions found above for the homogeneous solution y_h and $U_i(x)$ are functions to be determined as follows

$$U_i = (-1)^{n-i} \int \frac{F(x)W_i(x)}{aW(x)} dx$$

Where $W(x)$ is the Wronskian and $W_i(x)$ is the Wronskian that results after deleting the last row and the i -th column of the determinant and n is the order of the ODE or equivalently, the number of basis solutions, and a is the coefficient of the leading

derivative in the ODE, and $F(x)$ is the RHS of the ODE. Therefore, the first step is to find the Wronskian $W(x)$. This is given by

$$W(x) = \begin{vmatrix} y_1 & y_2 & y_3 & y_4 \\ y_1' & y_2' & y_3' & y_4' \\ y_1'' & y_2'' & y_3'' & y_4'' \\ y_1''' & y_2''' & y_3''' & y_4''' \end{vmatrix}$$

Substituting the fundamental set of solutions y_i found above in the Wronskian gives

$$W = \begin{bmatrix} e^{-x} & x e^{-x} & e^{-\frac{(1+i\sqrt{3})x}{2}} & e^{\frac{(i\sqrt{3}-1)x}{2}} \\ -e^{-x} & e^{-x}(1-x) & -\frac{(1+i\sqrt{3})e^{-\frac{(1+i\sqrt{3})x}{2}}}{2} & \frac{(i\sqrt{3}-1)e^{\frac{(i\sqrt{3}-1)x}{2}}}{2} \\ e^{-x} & e^{-x}(x-2) & \frac{(1+i\sqrt{3})^2 e^{-\frac{(1+i\sqrt{3})x}{2}}}{4} & \frac{(i\sqrt{3}-1)^2 e^{\frac{(i\sqrt{3}-1)x}{2}}}{4} \\ -e^{-x} & e^{-x}(-x+3) & e^{-\frac{(1+i\sqrt{3})x}{2}} & e^{\frac{(i\sqrt{3}-1)x}{2}} \end{bmatrix}$$

$$|W| = ie^{-2x}\sqrt{3}e^{\frac{(i\sqrt{3}-1)x}{2}}e^{-\frac{(1+i\sqrt{3})x}{2}}$$

The determinant simplifies to

$$|W| = i\sqrt{3}e^{-3x}$$

Now we determine W_i for each U_i .

$$W_1(x) = \det \begin{bmatrix} x e^{-x} & e^{-\frac{(1+i\sqrt{3})x}{2}} & e^{\frac{(i\sqrt{3}-1)x}{2}} \\ e^{-x}(1-x) & -\frac{(1+i\sqrt{3})e^{-\frac{(1+i\sqrt{3})x}{2}}}{2} & \frac{(i\sqrt{3}-1)e^{\frac{(i\sqrt{3}-1)x}{2}}}{2} \\ e^{-x}(x-2) & \frac{(1+i\sqrt{3})^2 e^{-\frac{(1+i\sqrt{3})x}{2}}}{4} & \frac{(i\sqrt{3}-1)^2 e^{\frac{(i\sqrt{3}-1)x}{2}}}{4} \end{bmatrix}$$

$$= i\sqrt{3}e^{-2x}(x-1)$$

$$W_2(x) = \det \begin{bmatrix} e^{-x} & e^{-\frac{(1+i\sqrt{3})x}{2}} & e^{\frac{(i\sqrt{3}-1)x}{2}} \\ -e^{-x} & -\frac{(1+i\sqrt{3})e^{-\frac{(1+i\sqrt{3})x}{2}}}{2} & \frac{(i\sqrt{3}-1)e^{\frac{(i\sqrt{3}-1)x}{2}}}{2} \\ e^{-x} & \frac{(1+i\sqrt{3})^2 e^{-\frac{(1+i\sqrt{3})x}{2}}}{4} & \frac{(i\sqrt{3}-1)^2 e^{\frac{(i\sqrt{3}-1)x}{2}}}{4} \end{bmatrix}$$

$$= i\sqrt{3}e^{-2x}$$

$$\begin{aligned}
W_3(x) &= \det \begin{bmatrix} e^{-x} & x e^{-x} & e^{\frac{(i\sqrt{3}-1)x}{2}} \\ -e^{-x} & e^{-x}(1-x) & \frac{(i\sqrt{3}-1)e^{\frac{(i\sqrt{3}-1)x}{2}}}{2} \\ e^{-x} & e^{-x}(x-2) & \frac{(i\sqrt{3}-1)^2 e^{\frac{(i\sqrt{3}-1)x}{2}}}{4} \end{bmatrix} \\
&= \frac{e^{\frac{x(i\sqrt{3}-5)}{2}} (i\sqrt{3}-1)}{2}
\end{aligned}$$

$$\begin{aligned}
W_4(x) &= \det \begin{bmatrix} e^{-x} & x e^{-x} & e^{-\frac{(1+i\sqrt{3})x}{2}} \\ -e^{-x} & e^{-x}(1-x) & -\frac{(1+i\sqrt{3})e^{-\frac{(1+i\sqrt{3})x}{2}}}{2} \\ e^{-x} & e^{-x}(x-2) & \frac{(1+i\sqrt{3})^2 e^{-\frac{(1+i\sqrt{3})x}{2}}}{4} \end{bmatrix} \\
&= -\frac{e^{-\frac{x(i\sqrt{3}+5)}{2}} (1+i\sqrt{3})}{2}
\end{aligned}$$

Now we are ready to evaluate each $U_i(x)$.

$$\begin{aligned}
U_1 &= (-1)^{4-1} \int \frac{F(x)W_1(x)}{aW(x)} dx \\
&= (-1)^3 \int \frac{\left(x^2 e^{-x} + 3e^{-\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right)\right) (i\sqrt{3} e^{-2x}(x-1))}{(1)(i\sqrt{3} e^{-3x})} dx \\
&= - \int \frac{i\left(x^2 e^{-x} + 3e^{-\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right)\right) \sqrt{3} e^{-2x}(x-1)}{i\sqrt{3} e^{-3x}} dx \\
&= - \int \left((x-1) \left(3e^{\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right) + x^2\right)\right) dx \\
&= -3\left(\frac{x}{2} + \frac{1}{2}\right) e^{\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right) + 3\left(-\frac{\sqrt{3}x}{2} + \frac{\sqrt{3}}{2}\right) e^{\frac{x}{2}} \sin\left(\frac{\sqrt{3}x}{2}\right) - \frac{x^4}{4} + \frac{3e^{\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right)}{2} + \frac{3\sqrt{3}e^{\frac{x}{2}} \sin\left(\frac{\sqrt{3}x}{2}\right)}{2} \\
&= -3\left(\frac{x}{2} + \frac{1}{2}\right) e^{\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right) + 3\left(-\frac{\sqrt{3}x}{2} + \frac{\sqrt{3}}{2}\right) e^{\frac{x}{2}} \sin\left(\frac{\sqrt{3}x}{2}\right) - \frac{x^4}{4} + \frac{3e^{\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right)}{2} + \frac{3\sqrt{3}e^{\frac{x}{2}} \sin\left(\frac{\sqrt{3}x}{2}\right)}{2}
\end{aligned}$$

$$\begin{aligned}
U_2 &= (-1)^{4-2} \int \frac{F(x)W_2(x)}{aW(x)} dx \\
&= (-1)^2 \int \frac{\left(x^2 e^{-x} + 3 e^{-\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right)\right) (i\sqrt{3} e^{-2x})}{(1) (i\sqrt{3} e^{-3x})} dx \\
&= \int \frac{i\left(x^2 e^{-x} + 3 e^{-\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right)\right) \sqrt{3} e^{-2x}}{i\sqrt{3} e^{-3x}} dx \\
&= \int \left(3 e^{\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right) + x^2\right) dx \\
&= \frac{x^3}{3} + \frac{3 e^{\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right)}{2} + \frac{3\sqrt{3} e^{\frac{x}{2}} \sin\left(\frac{\sqrt{3}x}{2}\right)}{2}
\end{aligned}$$

$$\begin{aligned}
U_3 &= (-1)^{4-3} \int \frac{F(x)W_3(x)}{aW(x)} dx \\
&= (-1)^1 \int \frac{\left(x^2 e^{-x} + 3 e^{-\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right)\right) \left(\frac{e^{\frac{x(i\sqrt{3}-5)}{2}} (i\sqrt{3}-1)}{2}\right)}{(1) (i\sqrt{3} e^{-3x})} dx \\
&= - \int \frac{\left(x^2 e^{-x} + 3 e^{-\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right)\right) e^{\frac{x(i\sqrt{3}-5)}{2}} (i\sqrt{3}-1)}{i\sqrt{3} e^{-3x}} dx \\
&= - \int \left(\frac{\sqrt{3} e^{\frac{i\sqrt{3}x}{2}} (\sqrt{3} + i) \left(e^{-\frac{x}{2}} x^2 + 3 \cos\left(\frac{\sqrt{3}x}{2}\right)\right)}{6}\right) dx \\
&= -\frac{3x}{4} - \frac{i\sqrt{3}x}{4} + \frac{ie^{i\sqrt{3}x}\sqrt{3}}{4} - \frac{e^{i\sqrt{3}x}}{4} + \frac{(i\sqrt{3}x + i\sqrt{3} + x^2 + x - 1) (1 + i\sqrt{3}) \sqrt{3} (\sqrt{3} + i) e^{\frac{(i\sqrt{3}-1)x}{2}}}{12} \\
&= -\frac{3x}{4} - \frac{i\sqrt{3}x}{4} + \frac{ie^{i\sqrt{3}x}\sqrt{3}}{4} - \frac{e^{i\sqrt{3}x}}{4} + \frac{(i\sqrt{3}x + i\sqrt{3} + x^2 + x - 1) (1 + i\sqrt{3}) \sqrt{3} (\sqrt{3} + i) e^{\frac{(i\sqrt{3}-1)x}{2}}}{12}
\end{aligned}$$

$$\begin{aligned}
U_4 &= (-1)^{4-4} \int \frac{F(x)W_4(x)}{aW(x)} dx \\
&= (-1)^0 \int \frac{\left(x^2 e^{-x} + 3 e^{-\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right)\right) \left(-\frac{e^{-\frac{x(i\sqrt{3}+5)}{2}}(1+i\sqrt{3})}{2}\right)}{(1)(i\sqrt{3}e^{-3x})} dx \\
&= \int \frac{\left(x^2 e^{-x} + 3 e^{-\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right)\right) e^{-\frac{x(i\sqrt{3}+5)}{2}}(1+i\sqrt{3})}{i\sqrt{3}e^{-3x}} dx \\
&= \int \left(-\frac{\sqrt{3}e^{-\frac{i\sqrt{3}x}{2}}(-i+\sqrt{3})\left(e^{-\frac{x}{2}}x^2 + 3\cos\left(\frac{\sqrt{3}x}{2}\right)\right)}{6}\right) dx \\
&= -\frac{(-i\sqrt{3}x - i\sqrt{3} + x^2 + x - 1)(i\sqrt{3} - 1)\sqrt{3}(-i + \sqrt{3})e^{-\frac{(1+i\sqrt{3})x}{2}}}{12} - \frac{3x}{4} + \frac{i\sqrt{3}x}{4} - \frac{ie^{-i\sqrt{3}x}\sqrt{3}}{4} \\
&= -\frac{(-i\sqrt{3}x - i\sqrt{3} + x^2 + x - 1)(i\sqrt{3} - 1)\sqrt{3}(-i + \sqrt{3})e^{-\frac{(1+i\sqrt{3})x}{2}}}{12} - \frac{3x}{4} + \frac{i\sqrt{3}x}{4} - \frac{ie^{-i\sqrt{3}x}\sqrt{3}}{4}
\end{aligned}$$

Now that all the U_i functions have been determined, the particular solution is found from

$$y_p = U_1y_1 + U_2y_2 + U_3y_3 + U_4y_4$$

Hence

$$\begin{aligned}
y_p &= \left(-3\left(\frac{x}{2} + \frac{1}{2}\right)e^{\frac{x}{2}}\cos\left(\frac{\sqrt{3}x}{2}\right) + 3\left(-\frac{\sqrt{3}x}{2} + \frac{\sqrt{3}}{2}\right)e^{\frac{x}{2}}\sin\left(\frac{\sqrt{3}x}{2}\right) - \frac{x^4}{4} + \frac{3e^{\frac{x}{2}}\cos\left(\frac{\sqrt{3}x}{2}\right)}{2} + \frac{3\sqrt{3}}{4}\right) \\
&+ \left(\frac{x^3}{3} + \frac{3e^{\frac{x}{2}}\cos\left(\frac{\sqrt{3}x}{2}\right)}{2} + \frac{3\sqrt{3}e^{\frac{x}{2}}\sin\left(\frac{\sqrt{3}x}{2}\right)}{2}\right)(xe^{-x}) \\
&+ \left(-\frac{3x}{4} - \frac{i\sqrt{3}x}{4} + \frac{ie^{i\sqrt{3}x}\sqrt{3}}{4} - \frac{e^{i\sqrt{3}x}}{4} + \frac{(i\sqrt{3}x + i\sqrt{3} + x^2 + x - 1)(1+i\sqrt{3})\sqrt{3}(\sqrt{3}+i)e^{\frac{(i\sqrt{3}-1)x}{2}}}{12}\right) \\
&+ \left(-\frac{(-i\sqrt{3}x - i\sqrt{3} + x^2 + x - 1)(i\sqrt{3} - 1)\sqrt{3}(-i + \sqrt{3})e^{-\frac{(1+i\sqrt{3})x}{2}}}{12} - \frac{3x}{4} + \frac{i\sqrt{3}x}{4} - \frac{ie^{-i\sqrt{3}x}\sqrt{3}}{4}\right)
\end{aligned}$$

Therefore the particular solution is

$$y_p = \frac{(-3x - 1)e^{-\frac{x}{2}}\cos\left(\frac{\sqrt{3}x}{2}\right)}{2} - \frac{\sqrt{3}e^{-\frac{x}{2}}(-5 + x)\sin\left(\frac{\sqrt{3}x}{2}\right)}{2} + \frac{e^{-x}(x^4 + 4x^3 - 24x - 24)}{12}$$

Therefore the general solution is

$$y = y_h + y_p$$

$$= \left(c_1 e^{-x} + x e^{-x} c_2 + e^{\left(-\frac{1}{2} - \frac{i\sqrt{3}}{2}\right)x} c_3 + e^{\left(-\frac{1}{2} + \frac{i\sqrt{3}}{2}\right)x} c_4 \right) + \left(\frac{(-3x - 1) e^{-\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right)}{2} - \frac{\sqrt{3} e^{-\frac{x}{2}} (-5 + x) \sin\left(\frac{\sqrt{3}x}{2}\right)}{2} + \frac{e^{-x}(x^4 + 4x^3 - 24x - 24)}{12} \right)$$

Which simplifies to

$$y = e^{-\frac{(1+i\sqrt{3})x}{2}} c_3 + e^{\frac{(i\sqrt{3}-1)x}{2}} c_4 + e^{-x}(c_2 x + c_1) + \frac{(-3x - 1) e^{-\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right)}{2} - \frac{\sqrt{3} e^{-\frac{x}{2}} (-5 + x) \sin\left(\frac{\sqrt{3}x}{2}\right)}{2} + \frac{e^{-x}(x^4 + 4x^3 - 24x - 24)}{12}$$

Summary

The solution(s) found are the following

$$y = e^{-\frac{(1+i\sqrt{3})x}{2}} c_3 + e^{\frac{(i\sqrt{3}-1)x}{2}} c_4 + e^{-x}(c_2 x + c_1) + \frac{(-3x - 1) e^{-\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right)}{2} - \frac{\sqrt{3} e^{-\frac{x}{2}} (-5 + x) \sin\left(\frac{\sqrt{3}x}{2}\right)}{2} + \frac{e^{-x}(x^4 + 4x^3 - 24x - 24)}{12} \quad (1)$$

Verification of solutions

$$y = e^{-\frac{(1+i\sqrt{3})x}{2}} c_3 + e^{\frac{(i\sqrt{3}-1)x}{2}} c_4 + e^{-x}(c_2 x + c_1) + \frac{(-3x - 1) e^{-\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right)}{2} - \frac{\sqrt{3} e^{-\frac{x}{2}} (-5 + x) \sin\left(\frac{\sqrt{3}x}{2}\right)}{2} + \frac{e^{-x}(x^4 + 4x^3 - 24x - 24)}{12}$$

Verified OK.

11.48.1 Maple step by step solution

Let's solve

$$y'''' + 3y''' + 4y'' + 3y' + y = x^2e^{-x} + 3e^{-\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right)$$

- Highest derivative means the order of the ODE is 4

$$y''''$$

- Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(x)$

$$y_1(x) = y$$

- Define new variable $y_2(x)$

$$y_2(x) = y'$$

- Define new variable $y_3(x)$

$$y_3(x) = y''$$

- Define new variable $y_4(x)$

$$y_4(x) = y'''$$

- Isolate for $y_4'(x)$ using original ODE

$$y_4'(x) = x^2e^{-x} + 3e^{-\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right) - 4y_3(x) - 3y_2(x) - y_1(x) - 3y_4(x)$$

Convert linear ODE into a system of first order ODEs

$$\left[y_2(x) = y_1'(x), y_3(x) = y_2'(x), y_4(x) = y_3'(x), y_4'(x) = x^2e^{-x} + 3e^{-\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right) - 4y_3(x) - 3y_2(x) - y_1(x) - 3y_4(x) \right]$$

- Define vector

$$\vec{y}(x) = \begin{bmatrix} y_1(x) \\ y_2(x) \\ y_3(x) \\ y_4(x) \end{bmatrix}$$

- System to solve

$$\vec{y}'(x) = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -1 & -3 & -4 & -3 \end{bmatrix} \cdot \vec{y}(x) + \begin{bmatrix} 0 \\ 0 \\ 0 \\ x^2 e^{-x} + 3e^{-\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right) \end{bmatrix}$$

- Define the forcing function

$$\vec{f}(x) = \begin{bmatrix} 0 \\ 0 \\ 0 \\ x^2 e^{-x} + 3e^{-\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right) \end{bmatrix}$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -1 & -3 & -4 & -3 \end{bmatrix}$$

- Rewrite the system as

$$\vec{y}'(x) = A \cdot \vec{y}(x) + \vec{f}$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\begin{bmatrix} -1, \begin{bmatrix} -1 \\ 1 \\ -1 \\ 1 \end{bmatrix} \end{bmatrix}, \begin{bmatrix} -1, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \end{bmatrix}, \begin{bmatrix} -\frac{1}{2} - \frac{i\sqrt{3}}{2}, \begin{bmatrix} \frac{1}{\left(-\frac{1}{2} - \frac{i\sqrt{3}}{2}\right)^3} \\ \frac{1}{\left(-\frac{1}{2} - \frac{i\sqrt{3}}{2}\right)^2} \\ \frac{1}{-\frac{1}{2} - \frac{i\sqrt{3}}{2}} \\ 1 \end{bmatrix} \end{bmatrix}, \begin{bmatrix} -\frac{1}{2} + \frac{i\sqrt{3}}{2}, \begin{bmatrix} \frac{1}{\left(-\frac{1}{2} + \frac{i\sqrt{3}}{2}\right)^3} \\ \frac{1}{\left(-\frac{1}{2} + \frac{i\sqrt{3}}{2}\right)^2} \\ \frac{1}{-\frac{1}{2} + \frac{i\sqrt{3}}{2}} \\ 1 \end{bmatrix} \end{bmatrix} \right]$$

- Consider eigenpair, with eigenvalue of algebraic multiplicity 2

$$\left[-1, \begin{bmatrix} -1 \\ 1 \\ -1 \\ 1 \end{bmatrix} \right]$$

- First solution from eigenvalue -1

$$\vec{y}_1(x) = e^{-x} \cdot \begin{bmatrix} -1 \\ 1 \\ -1 \\ 1 \end{bmatrix}$$

- Form of the 2nd homogeneous solution where \vec{p} is to be solved for, $\lambda = -1$ is the eigenvalue, and

$$\vec{y}_2(x) = e^{\lambda x} (x\vec{v} + \vec{p})$$

- Note that the x multiplying \vec{v} makes this solution linearly independent to the 1st solution obtained

- Substitute $\vec{y}_2(x)$ into the homogeneous system

$$\lambda e^{\lambda x} (x\vec{v} + \vec{p}) + e^{\lambda x} \vec{v} = (e^{\lambda x} A) \cdot (x\vec{v} + \vec{p})$$

- Use the fact that \vec{v} is an eigenvector of A

$$\lambda e^{\lambda x} (x\vec{v} + \vec{p}) + e^{\lambda x} \vec{v} = e^{\lambda x} (\lambda x\vec{v} + A \cdot \vec{p})$$

- Simplify equation

$$\lambda \vec{p} + \vec{v} = A \cdot \vec{p}$$

- Make use of the identity matrix I

$$(\lambda \cdot I) \cdot \vec{p} + \vec{v} = A \cdot \vec{p}$$

- Condition \vec{p} must meet for $\vec{y}_2(x)$ to be a solution to the homogeneous system

$$(A - \lambda \cdot I) \cdot \vec{p} = \vec{v}$$

- Choose \vec{p} to use in the second solution to the homogeneous system from eigenvalue -1

$$\left(\begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -1 & -3 & -4 & -3 \end{bmatrix} - (-1) \cdot \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \right) \cdot \vec{p} = \begin{bmatrix} -1 \\ 1 \\ -1 \\ 1 \end{bmatrix}$$

- Choice of \vec{p}

$$\vec{p} = \begin{bmatrix} -1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

- Second solution from eigenvalue -1

$$\vec{y}_2(x) = e^{-x} \cdot \left(x \cdot \begin{bmatrix} -1 \\ 1 \\ -1 \\ 1 \end{bmatrix} + \begin{bmatrix} -1 \\ 0 \\ 0 \\ 0 \end{bmatrix} \right)$$

- Consider complex eigenpair, complex conjugate eigenvalue can be ignored

$$\begin{bmatrix} -\frac{1}{2} - \frac{\text{I}\sqrt{3}}{2}, \\ \frac{1}{\left(-\frac{1}{2} - \frac{\text{I}\sqrt{3}}{2}\right)^3} \\ \frac{1}{\left(-\frac{1}{2} - \frac{\text{I}\sqrt{3}}{2}\right)^2} \\ \frac{1}{-\frac{1}{2} - \frac{\text{I}\sqrt{3}}{2}} \\ 1 \end{bmatrix}$$

- Solution from eigenpair

$$e^{\left(-\frac{1}{2} - \frac{\text{I}\sqrt{3}}{2}\right)x} \cdot \begin{bmatrix} \frac{1}{\left(-\frac{1}{2} - \frac{\text{I}\sqrt{3}}{2}\right)^3} \\ \frac{1}{\left(-\frac{1}{2} - \frac{\text{I}\sqrt{3}}{2}\right)^2} \\ \frac{1}{-\frac{1}{2} - \frac{\text{I}\sqrt{3}}{2}} \\ 1 \end{bmatrix}$$

- Use Euler identity to write solution in terms of sin and cos

$$e^{-\frac{x}{2}} \cdot \left(\cos\left(\frac{\sqrt{3}x}{2}\right) - \text{I} \sin\left(\frac{\sqrt{3}x}{2}\right) \right) \cdot \begin{bmatrix} \frac{1}{\left(-\frac{1}{2} - \frac{\text{I}\sqrt{3}}{2}\right)^3} \\ \frac{1}{\left(-\frac{1}{2} - \frac{\text{I}\sqrt{3}}{2}\right)^2} \\ \frac{1}{-\frac{1}{2} - \frac{\text{I}\sqrt{3}}{2}} \\ 1 \end{bmatrix}$$

- Simplify expression

$$e^{-\frac{x}{2}} \cdot \begin{bmatrix} \frac{\cos\left(\frac{\sqrt{3}x}{2}\right) - I \sin\left(\frac{\sqrt{3}x}{2}\right)}{\left(-\frac{1}{2} - \frac{I\sqrt{3}}{2}\right)^3} \\ \frac{\cos\left(\frac{\sqrt{3}x}{2}\right) - I \sin\left(\frac{\sqrt{3}x}{2}\right)}{\left(-\frac{1}{2} - \frac{I\sqrt{3}}{2}\right)^2} \\ \frac{\cos\left(\frac{\sqrt{3}x}{2}\right) - I \sin\left(\frac{\sqrt{3}x}{2}\right)}{-\frac{1}{2} - \frac{I\sqrt{3}}{2}} \\ \cos\left(\frac{\sqrt{3}x}{2}\right) - I \sin\left(\frac{\sqrt{3}x}{2}\right) \end{bmatrix}$$

- Both real and imaginary parts are solutions to the homogeneous system

$$\vec{y}_3(x) = e^{-\frac{x}{2}} \cdot \begin{bmatrix} \cos\left(\frac{\sqrt{3}x}{2}\right) \\ -\frac{\cos\left(\frac{\sqrt{3}x}{2}\right)}{2} - \frac{\sin\left(\frac{\sqrt{3}x}{2}\right)\sqrt{3}}{2} \\ \frac{\sin\left(\frac{\sqrt{3}x}{2}\right)\sqrt{3}}{2} - \frac{\cos\left(\frac{\sqrt{3}x}{2}\right)}{2} \\ \cos\left(\frac{\sqrt{3}x}{2}\right) \end{bmatrix}, \vec{y}_4(x) = e^{-\frac{x}{2}} \cdot \begin{bmatrix} -\sin\left(\frac{\sqrt{3}x}{2}\right) \\ -\frac{\sqrt{3}\cos\left(\frac{\sqrt{3}x}{2}\right)}{2} + \frac{\sin\left(\frac{\sqrt{3}x}{2}\right)}{2} \\ \frac{\sqrt{3}\cos\left(\frac{\sqrt{3}x}{2}\right)}{2} + \frac{\sin\left(\frac{\sqrt{3}x}{2}\right)}{2} \\ -\sin\left(\frac{\sqrt{3}x}{2}\right) \end{bmatrix}$$

- General solution of the system of ODEs can be written in terms of the particular solution $\vec{y}_p(x)$
 $\vec{y}(x) = c_1 \vec{y}_1(x) + c_2 \vec{y}_2(x) + c_3 \vec{y}_3(x) + c_4 \vec{y}_4(x) + \vec{y}_p(x)$

□ Fundamental matrix

- Let $\phi(x)$ be the matrix whose columns are the independent solutions of the homogeneous system

$$\phi(x) = \begin{bmatrix} -e^{-x} & e^{-x}(-x-1) & e^{-\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right) & -e^{-\frac{x}{2}} \sin\left(\frac{\sqrt{3}x}{2}\right) \\ e^{-x} & x e^{-x} & e^{-\frac{x}{2}} \left(-\frac{\cos\left(\frac{\sqrt{3}x}{2}\right)}{2} - \frac{\sin\left(\frac{\sqrt{3}x}{2}\right)\sqrt{3}}{2}\right) & e^{-\frac{x}{2}} \left(-\frac{\sqrt{3}\cos\left(\frac{\sqrt{3}x}{2}\right)}{2} + \frac{\sin\left(\frac{\sqrt{3}x}{2}\right)}{2}\right) \\ -e^{-x} & -x e^{-x} & e^{-\frac{x}{2}} \left(\frac{\sin\left(\frac{\sqrt{3}x}{2}\right)\sqrt{3}}{2} - \frac{\cos\left(\frac{\sqrt{3}x}{2}\right)}{2}\right) & e^{-\frac{x}{2}} \left(\frac{\sqrt{3}\cos\left(\frac{\sqrt{3}x}{2}\right)}{2} + \frac{\sin\left(\frac{\sqrt{3}x}{2}\right)}{2}\right) \\ e^{-x} & x e^{-x} & e^{-\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right) & -e^{-\frac{x}{2}} \sin\left(\frac{\sqrt{3}x}{2}\right) \end{bmatrix}$$

- The fundamental matrix, $\Phi(x)$ is a normalized version of $\phi(x)$ satisfying $\Phi(0) = I$ where I is the identity matrix
 $\Phi(x) = \phi(x) \cdot \frac{1}{\phi(0)}$
- Substitute the value of $\phi(x)$ and $\phi(0)$

$$\Phi(x) = \begin{bmatrix} -e^{-x} & e^{-x}(-x-1) & e^{-\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right) & -e^{-\frac{x}{2}} \sin\left(\frac{\sqrt{3}x}{2}\right) \\ e^{-x} & xe^{-x} & e^{-\frac{x}{2}} \left(-\frac{\cos\left(\frac{\sqrt{3}x}{2}\right)}{2} - \frac{\sin\left(\frac{\sqrt{3}x}{2}\right)\sqrt{3}}{2} \right) & e^{-\frac{x}{2}} \left(-\frac{\sqrt{3} \cos\left(\frac{\sqrt{3}x}{2}\right)}{2} + \frac{\sin\left(\frac{\sqrt{3}x}{2}\right)}{2} \right) \\ -e^{-x} & -xe^{-x} & e^{-\frac{x}{2}} \left(\frac{\sin\left(\frac{\sqrt{3}x}{2}\right)\sqrt{3}}{2} - \frac{\cos\left(\frac{\sqrt{3}x}{2}\right)}{2} \right) & e^{-\frac{x}{2}} \left(\frac{\sqrt{3} \cos\left(\frac{\sqrt{3}x}{2}\right)}{2} + \frac{\sin\left(\frac{\sqrt{3}x}{2}\right)}{2} \right) \\ e^{-x} & xe^{-x} & e^{-\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right) & -e^{-\frac{x}{2}} \sin\left(\frac{\sqrt{3}x}{2}\right) \end{bmatrix}$$

- o Evaluate and simplify to get the fundamental matrix

$$\Phi(x) = \begin{bmatrix} (1+x)e^{-x} & -\frac{e^{-\frac{x}{2}} \sin\left(\frac{\sqrt{3}x}{2}\right)\sqrt{3}}{3} + 2xe^{-x} - e^{-\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right) + e^{-x} & -e^{-\frac{x}{2}} \sin\left(\frac{\sqrt{3}x}{2}\right)\sqrt{3} + e^{-x} \\ -xe^{-x} & \frac{2e^{-\frac{x}{2}} \sin\left(\frac{\sqrt{3}x}{2}\right)\sqrt{3}}{3} - 2xe^{-x} + e^{-x} & -e^{-\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right) + e^{-x} \\ xe^{-x} & e^{-\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right) - \frac{e^{-\frac{x}{2}} \sin\left(\frac{\sqrt{3}x}{2}\right)\sqrt{3}}{3} + e^{-x}(2x-1) & 2e^{-\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right) - e^{-x} \\ -xe^{-x} & e^{-x} - 2xe^{-x} - e^{-\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right) - \frac{e^{-\frac{x}{2}} \sin\left(\frac{\sqrt{3}x}{2}\right)\sqrt{3}}{3} & e^{-x} - 2xe^{-x} - e^{-\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right) - \frac{e^{-\frac{x}{2}} \sin\left(\frac{\sqrt{3}x}{2}\right)\sqrt{3}}{3} \end{bmatrix}$$

- Find a particular solution of the system of ODEs using variation of parameters

- o Let the particular solution be the fundamental matrix multiplied by $\vec{v}(x)$ and solve for $\vec{v}(x)$

$$\vec{y}_p(x) = \Phi(x) \cdot \vec{v}(x)$$

- o Take the derivative of the particular solution

$$\vec{y}'_p(x) = \Phi'(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x)$$

- o Substitute particular solution and its derivative into the system of ODEs

$$\Phi'(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x) = A \cdot \Phi(x) \cdot \vec{v}(x) + \vec{f}(x)$$

- o The fundamental matrix has columns that are solutions to the homogeneous system so its derivative is $A \cdot \Phi(x)$

$$A \cdot \Phi(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x) = A \cdot \Phi(x) \cdot \vec{v}(x) + \vec{f}(x)$$

- o Cancel like terms

$$\Phi(x) \cdot \vec{v}'(x) = \vec{f}(x)$$

- o Multiply by the inverse of the fundamental matrix

$$\vec{v}'(x) = \frac{1}{\Phi(x)} \cdot \vec{f}(x)$$

- o Integrate to solve for $\vec{v}(x)$

$$\vec{v}(x) = \int_0^x \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds$$

- o Plug $\vec{v}(x)$ into the equation for the particular solution

$$\vec{y}_p(x) = \Phi(x) \cdot \left(\int_0^x \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds \right)$$

- o Plug in the fundamental matrix and the forcing function and compute

$$\vec{y}_p(x) = \begin{bmatrix} -\sqrt{3}e^{-\frac{x}{2}} \left(x - \frac{17}{6}\right) \sin\left(\frac{\sqrt{3}x}{2}\right) - \frac{3e^{-\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right)}{2} + \frac{e^{-x}(x^4 - 12x^2 - 42x + 18)}{12} \\ \frac{(-3x+10)e^{-\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right)}{2} + \frac{\sqrt{3}e^{-\frac{x}{2}} \left(x - \frac{10}{3}\right) \sin\left(\frac{\sqrt{3}x}{2}\right)}{2} - \frac{e^{-x}(x^4 - 4x^3 - 12x^2 - 18x + 60)}{12} \\ \frac{(3x-10)e^{-\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right)}{2} + \frac{\left(x + \frac{2}{3}\right)\sqrt{3}e^{-\frac{x}{2}} \sin\left(\frac{\sqrt{3}x}{2}\right)}{2} + \frac{e^{-x}(x^4 - 4x^3 + 6x + 60)}{12} \\ -\sqrt{3}e^{-\frac{x}{2}} \left(x - \frac{4}{3}\right) \sin\left(\frac{\sqrt{3}x}{2}\right) + 3e^{-\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right) - \frac{e^{-x}(x^4 - 4x^3 + 12x^2 + 6x + 36)}{12} \end{bmatrix}$$

- Plug particular solution back into general solution

$$\vec{y}(x) = c_1 \vec{y}_1(x) + c_2 \vec{y}_2(x) + c_3 \vec{y}_3(x) + c_4 \vec{y}_4(x) + \begin{bmatrix} -\sqrt{3}e^{-\frac{x}{2}} \left(x - \frac{17}{6}\right) \sin\left(\frac{\sqrt{3}x}{2}\right) - \frac{3e^{-\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right)}{2} + \frac{e^{-x}(x^4 - 12x^2 - 42x + 18)}{12} \\ \frac{(-3x+10)e^{-\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right)}{2} + \frac{\sqrt{3}e^{-\frac{x}{2}} \left(x - \frac{10}{3}\right) \sin\left(\frac{\sqrt{3}x}{2}\right)}{2} - \frac{e^{-x}(x^4 - 4x^3 - 12x^2 - 18x + 60)}{12} \\ \frac{(3x-10)e^{-\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right)}{2} + \frac{\left(x + \frac{2}{3}\right)\sqrt{3}e^{-\frac{x}{2}} \sin\left(\frac{\sqrt{3}x}{2}\right)}{2} + \frac{e^{-x}(x^4 - 4x^3 + 6x + 60)}{12} \\ -\sqrt{3}e^{-\frac{x}{2}} \left(x - \frac{4}{3}\right) \sin\left(\frac{\sqrt{3}x}{2}\right) + 3e^{-\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right) - \frac{e^{-x}(x^4 - 4x^3 + 12x^2 + 6x + 36)}{12} \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y = -\left(\left(x - \frac{17}{6}\right) \sqrt{3} + c_4\right) e^{-\frac{x}{2}} \sin\left(\frac{\sqrt{3}x}{2}\right) + \frac{(12c_3 - 18)e^{-\frac{x}{2}} \cos\left(\frac{\sqrt{3}x}{2}\right)}{12} + \frac{(x^4 - 12x^2 + (-12c_2 - 42)x - 12c_1 - 12c_2 + 18)}{12}$$

Maple trace

```

`Methods for high order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 4; linear nonhomogeneous with symmetry [0,1]
trying high order linear exact nonhomogeneous
trying differential order: 4; missing the dependent variable
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 73

`dsolve(diff(y(x),x$4)+3*diff(y(x),x$3)+4*diff(y(x),x$2)+3*diff(y(x),x)+y(x)=x^2*exp(-x)+3*exp(-x/2),y(x))`

$$y(x) = -\frac{3e^{-\frac{x}{2}}\left(x - \frac{2c_3}{3} + \frac{1}{3}\right)\cos\left(\frac{\sqrt{3}x}{2}\right) - e^{-\frac{x}{2}}\left((x-5)\sqrt{3} - 2c_4\right)\sin\left(\frac{\sqrt{3}x}{2}\right)}{2} + \frac{(-24 + x^4 + 4x^3 + 12(-2 + c_2)x + 12c_1)e^{-x}}{12}$$

✓ Solution by Mathematica

Time used: 2.054 (sec). Leaf size: 104

`DSolve[y''''[x]+3*y'''[x]+4*y''[x]+3*y'[x]+y[x]==x^2*Exp[-x]+3*Exp[-x/2]*Cos[Sqrt[3]/2*x],y[x]]`

$$y(x) \rightarrow \frac{1}{12}e^{-x}\left(x^4 + 4x^3 - 24x + 12c_4x - 6e^{x/2}(3x + 1 - 2c_2)\cos\left(\frac{\sqrt{3}x}{2}\right) - 6e^{x/2}\left(\sqrt{3}x - 5\sqrt{3} - 2c_1\right)\sin\left(\frac{\sqrt{3}x}{2}\right) - 24 + 12c_3\right)$$

11.49 problem 49

11.49.1 Maple step by step solution 2794

Internal problem ID [11823]

Internal file name [OUTPUT/11832_Thursday_April_11_2024_08_51_29_PM_74065651/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 49.

ODE order: 4.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_high_order , _linear , _nonhomogeneous]]
```

$$y'''' - 16y = x^2 \sin(2x) + e^{2x}x^4$$

This is higher order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE And y_p is a particular solution to the nonhomogeneous ODE. y_h is the solution to

$$y'''' - 16y = 0$$

The characteristic equation is

$$\lambda^4 - 16 = 0$$

The roots of the above equation are

$$\lambda_1 = 2$$

$$\lambda_2 = -2$$

$$\lambda_3 = 2i$$

$$\lambda_4 = -2i$$

Therefore the homogeneous solution is

$$y_h(x) = c_1 e^{-2x} + c_2 e^{2x} + e^{2ix} c_3 + e^{-2ix} c_4$$

The fundamental set of solutions for the homogeneous solution are the following

$$y_1 = e^{-2x}$$

$$y_2 = e^{2x}$$

$$y_3 = e^{2ix}$$

$$y_4 = e^{-2ix}$$

Now the particular solution to the given ODE is found

$$y'''' - 16y = x^2 \sin(2x) + e^{2x} x^4$$

Let the particular solution be

$$y_p = U_1 y_1 + U_2 y_2 + U_3 y_3 + U_4 y_4$$

Where y_i are the basis solutions found above for the homogeneous solution y_h and $U_i(x)$ are functions to be determined as follows

$$U_i = (-1)^{n-i} \int \frac{F(x)W_i(x)}{aW(x)} dx$$

Where $W(x)$ is the Wronskian and $W_i(x)$ is the Wronskian that results after deleting the last row and the i -th column of the determinant and n is the order of the ODE or equivalently, the number of basis solutions, and a is the coefficient of the leading derivative in the ODE, and $F(x)$ is the RHS of the ODE. Therefore, the first step is to find the Wronskian $W(x)$. This is given by

$$W(x) = \begin{vmatrix} y_1 & y_2 & y_3 & y_4 \\ y_1' & y_2' & y_3' & y_4' \\ y_1'' & y_2'' & y_3'' & y_4'' \\ y_1''' & y_2''' & y_3''' & y_4''' \end{vmatrix}$$

Substituting the fundamental set of solutions y_i found above in the Wronskian gives

$$W = \begin{bmatrix} e^{-2x} & e^{2x} & e^{2ix} & e^{-2ix} \\ -2e^{-2x} & 2e^{2x} & 2ie^{2ix} & -2ie^{-2ix} \\ 4e^{-2x} & 4e^{2x} & -4e^{2ix} & -4e^{-2ix} \\ -8e^{-2x} & 8e^{2x} & -8ie^{2ix} & 8ie^{-2ix} \end{bmatrix}$$

$$|W| = -1024ie^{-2x}e^{2x}e^{2ix}e^{-2ix}$$

The determinant simplifies to

$$|W| = -1024i$$

Now we determine W_i for each U_i .

$$\begin{aligned} W_1(x) &= \det \begin{bmatrix} e^{2x} & e^{2ix} & e^{-2ix} \\ 2e^{2x} & 2ie^{2ix} & -2ie^{-2ix} \\ 4e^{2x} & -4e^{2ix} & -4e^{-2ix} \end{bmatrix} \\ &= -32ie^{2x} \end{aligned}$$

$$\begin{aligned} W_2(x) &= \det \begin{bmatrix} e^{-2x} & e^{2ix} & e^{-2ix} \\ -2e^{-2x} & 2ie^{2ix} & -2ie^{-2ix} \\ 4e^{-2x} & -4e^{2ix} & -4e^{-2ix} \end{bmatrix} \\ &= -32ie^{-2x} \end{aligned}$$

$$\begin{aligned} W_3(x) &= \det \begin{bmatrix} e^{-2x} & e^{2x} & e^{-2ix} \\ -2e^{-2x} & 2e^{2x} & -2ie^{-2ix} \\ 4e^{-2x} & 4e^{2x} & -4e^{-2ix} \end{bmatrix} \\ &= -32e^{-2ix} \end{aligned}$$

$$\begin{aligned} W_4(x) &= \det \begin{bmatrix} e^{-2x} & e^{2x} & e^{2ix} \\ -2e^{-2x} & 2e^{2x} & 2ie^{2ix} \\ 4e^{-2x} & 4e^{2x} & -4e^{2ix} \end{bmatrix} \\ &= -32e^{2ix} \end{aligned}$$

Now we are ready to evaluate each $U_i(x)$.

$$\begin{aligned}
 U_1 &= (-1)^{4-1} \int \frac{F(x)W_1(x)}{aW(x)} dx \\
 &= (-1)^3 \int \frac{(x^2 \sin(2x) + e^{2x}x^4)(-32ie^{2x})}{(1)(-1024i)} dx \\
 &= - \int \frac{-32i(x^2 \sin(2x) + e^{2x}x^4) e^{2x}}{-1024i} dx \\
 &= - \int \left(\frac{x^2(x^2 e^{2x} + \sin(2x)) e^{2x}}{32} \right) dx \\
 &= - \frac{x^4 e^{4x}}{128} + \frac{x^3 e^{4x}}{128} - \frac{3x^2 e^{4x}}{512} + \frac{3x e^{4x}}{1024} - \frac{3 e^{4x}}{4096} - \frac{(-2x^2 + 2x - \frac{1}{2}) e^{2x} \cos(2x)}{256} - \frac{(2x^2 - \frac{1}{2}) e^{2x} \sin(2x)}{256} \\
 &= - \frac{x^4 e^{4x}}{128} + \frac{x^3 e^{4x}}{128} - \frac{3x^2 e^{4x}}{512} + \frac{3x e^{4x}}{1024} - \frac{3 e^{4x}}{4096} - \frac{(-2x^2 + 2x - \frac{1}{2}) e^{2x} \cos(2x)}{256} - \frac{(2x^2 - \frac{1}{2}) e^{2x} \sin(2x)}{256}
 \end{aligned}$$

$$\begin{aligned}
 U_2 &= (-1)^{4-2} \int \frac{F(x)W_2(x)}{aW(x)} dx \\
 &= (-1)^2 \int \frac{(x^2 \sin(2x) + e^{2x}x^4)(-32ie^{-2x})}{(1)(-1024i)} dx \\
 &= \int \frac{-32i(x^2 \sin(2x) + e^{2x}x^4) e^{-2x}}{-1024i} dx \\
 &= \int \left(\frac{x^2(x^2 + e^{-2x} \sin(2x))}{32} \right) dx \\
 &= \frac{x^5}{160} + \frac{(-\frac{1}{4}x^2 - \frac{1}{4}x - \frac{1}{16}) e^{-2x} \cos(2x)}{32} + \frac{(-\frac{x^2}{4} + \frac{1}{16}) e^{-2x} \sin(2x)}{32} \\
 &= \frac{x^5}{160} + \frac{(-\frac{1}{4}x^2 - \frac{1}{4}x - \frac{1}{16}) e^{-2x} \cos(2x)}{32} + \frac{(-\frac{x^2}{4} + \frac{1}{16}) e^{-2x} \sin(2x)}{32}
 \end{aligned}$$

$$\begin{aligned}
U_3 &= (-1)^{4-3} \int \frac{F(x)W_3(x)}{aW(x)} dx \\
&= (-1)^1 \int \frac{(x^2 \sin(2x) + e^{2x}x^4)(-32 e^{-2ix})}{(1)(-1024i)} dx \\
&= - \int \frac{-32(x^2 \sin(2x) + e^{2x}x^4) e^{-2ix}}{-1024i} dx \\
&= - \int \left(-\frac{ix^2(x^2 e^{2x} + \sin(2x)) e^{-2ix}}{32} \right) dx \\
&= \left(-\frac{1}{1024} + \frac{i}{1024} \right) (8x^4 - 8ix^3 - 8x^3 + 12ix^2 - 6ix + 6x - 3) e^{(2-2i)x} + \frac{x^3}{192} - \frac{i(8x^2 - 4ix - 1) e^{-4}}{2048} \\
&= \left(-\frac{1}{1024} + \frac{i}{1024} \right) (8x^4 - 8ix^3 - 8x^3 + 12ix^2 - 6ix + 6x - 3) e^{(2-2i)x} + \frac{x^3}{192} - \frac{i(8x^2 - 4ix - 1) e^{-4}}{2048}
\end{aligned}$$

$$\begin{aligned}
U_4 &= (-1)^{4-4} \int \frac{F(x)W_4(x)}{aW(x)} dx \\
&= (-1)^0 \int \frac{(x^2 \sin(2x) + e^{2x}x^4)(-32 e^{2ix})}{(1)(-1024i)} dx \\
&= \int \frac{-32(x^2 \sin(2x) + e^{2x}x^4) e^{2ix}}{-1024i} dx \\
&= \int \left(-\frac{ix^2(x^2 e^{2x} + \sin(2x)) e^{2ix}}{32} \right) dx \\
&= \frac{x^3}{192} - \frac{i(\frac{1}{64} - \frac{1}{16}ix - \frac{1}{8}x^2) e^{4ix}}{32} + \left(-\frac{1}{1024} - \frac{i}{1024} \right) (8x^4 + 8ix^3 - 8x^3 - 12ix^2 + 6ix + 6x - 3) e^{(2+i)x} \\
&= \frac{x^3}{192} - \frac{i(\frac{1}{64} - \frac{1}{16}ix - \frac{1}{8}x^2) e^{4ix}}{32} + \left(-\frac{1}{1024} - \frac{i}{1024} \right) (8x^4 + 8ix^3 - 8x^3 - 12ix^2 + 6ix + 6x - 3) e^{(2+i)x}
\end{aligned}$$

Now that all the U_i functions have been determined, the particular solution is found from

$$y_p = U_1y_1 + U_2y_2 + U_3y_3 + U_4y_4$$

Hence

$$\begin{aligned}
 y_p = & \left(-\frac{x^4 e^{4x}}{128} + \frac{x^3 e^{4x}}{128} - \frac{3x^2 e^{4x}}{512} + \frac{3x e^{4x}}{1024} - \frac{3 e^{4x}}{4096} - \frac{(-2x^2 + 2x - \frac{1}{2}) e^{2x} \cos(2x)}{256} - \frac{(2x^2 - \frac{1}{2}) e^{2x} \sin(2x)}{256} \right. \\
 & + \left. \left(\frac{x^5}{160} + \frac{(-\frac{1}{4}x^2 - \frac{1}{4}x - \frac{1}{16}) e^{-2x} \cos(2x)}{32} + \frac{(-\frac{x^2}{4} + \frac{1}{16}) e^{-2x} \sin(2x)}{32} \right) (e^{2x}) \right. \\
 & + \left(\left(-\frac{1}{1024} + \frac{i}{1024} \right) (8x^4 - 8ix^3 - 8x^3 + 12ix^2 - 6ix + 6x - 3) e^{(2-2i)x} + \frac{x^3}{192} - \frac{i(8x^2 - 4ix - 1) e^{-2x}}{2048} \right. \\
 & \left. + \left(\frac{x^3}{192} - \frac{i(\frac{1}{64} - \frac{1}{16}ix - \frac{1}{8}x^2) e^{4ix}}{32} + \left(-\frac{1}{1024} - \frac{i}{1024} \right) (8x^4 + 8ix^3 - 8x^3 - 12ix^2 + 6ix + 6x - 3) e^{(2+2i)x} \right) \right)
 \end{aligned}$$

Therefore the particular solution is

$$y_p = \frac{(128x^5 - 480x^4 + 800x^3 - 600x^2 + 60x + 105) e^{2x}}{20480} + \frac{(8x^3 - 15x) \cos(2x)}{768} + \frac{(-24x^2 + 5) \sin(2x)}{1024}$$

Therefore the general solution is

$$\begin{aligned}
 y = & y_h + y_p \\
 = & (c_1 e^{-2x} + c_2 e^{2x} + e^{2ix} c_3 + e^{-2ix} c_4) \\
 & + \left(\frac{(128x^5 - 480x^4 + 800x^3 - 600x^2 + 60x + 105) e^{2x}}{20480} + \frac{(8x^3 - 15x) \cos(2x)}{768} \right. \\
 & \left. + \frac{(-24x^2 + 5) \sin(2x)}{1024} \right)
 \end{aligned}$$

Summary

The solution(s) found are the following

$$\begin{aligned}
 y = & c_1 e^{-2x} + c_2 e^{2x} + e^{2ix} c_3 + e^{-2ix} c_4 \\
 & + \frac{(128x^5 - 480x^4 + 800x^3 - 600x^2 + 60x + 105) e^{2x}}{20480} \\
 & + \frac{(8x^3 - 15x) \cos(2x)}{768} + \frac{(-24x^2 + 5) \sin(2x)}{1024}
 \end{aligned} \tag{1}$$

Verification of solutions

$$\begin{aligned}
 y = & c_1 e^{-2x} + c_2 e^{2x} + e^{2ix} c_3 + e^{-2ix} c_4 + \frac{(128x^5 - 480x^4 + 800x^3 - 600x^2 + 60x + 105) e^{2x}}{20480} \\
 & + \frac{(8x^3 - 15x) \cos(2x)}{768} + \frac{(-24x^2 + 5) \sin(2x)}{1024}
 \end{aligned}$$

Verified OK.

11.49.1 Maple step by step solution

Let's solve

$$y'''' - 16y = x^2 \sin(2x) + e^{2x}x^4$$

- Highest derivative means the order of the ODE is 4

$$y''''$$

- Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(x)$

$$y_1(x) = y$$

- Define new variable $y_2(x)$

$$y_2(x) = y'$$

- Define new variable $y_3(x)$

$$y_3(x) = y''$$

- Define new variable $y_4(x)$

$$y_4(x) = y'''$$

- Isolate for $y_4'(x)$ using original ODE

$$y_4'(x) = e^{2x}x^4 + x^2 \sin(2x) + 16y_1(x)$$

Convert linear ODE into a system of first order ODEs

$$[y_2(x) = y_1'(x), y_3(x) = y_2'(x), y_4(x) = y_3'(x), y_4'(x) = e^{2x}x^4 + x^2 \sin(2x) + 16y_1(x)]$$

- Define vector

$$\vec{y}(x) = \begin{bmatrix} y_1(x) \\ y_2(x) \\ y_3(x) \\ y_4(x) \end{bmatrix}$$

- System to solve

$$\vec{y}'(x) = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 16 & 0 & 0 & 0 \end{bmatrix} \cdot \vec{y}(x) + \begin{bmatrix} 0 \\ 0 \\ 0 \\ x^2 \sin(2x) + e^{2x}x^4 \end{bmatrix}$$

- Define the forcing function

$$\vec{f}(x) = \begin{bmatrix} 0 \\ 0 \\ 0 \\ x^2 \sin(2x) + e^{2x}x^4 \end{bmatrix}$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 16 & 0 & 0 & 0 \end{bmatrix}$$

- Rewrite the system as

$$\vec{y}'(x) = A \cdot \vec{y}(x) + \vec{f}$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[\begin{array}{c} -2, \\ \begin{bmatrix} -\frac{1}{8} \\ \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix} \end{array} \right], \left[\begin{array}{c} 2, \\ \begin{bmatrix} \frac{1}{8} \\ \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \end{array} \right], \left[-2\mathbf{I}, \begin{bmatrix} -\frac{1}{8} \\ -\frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right], \left[2\mathbf{I}, \begin{bmatrix} \frac{1}{8} \\ -\frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[\begin{array}{c} -2, \\ \begin{bmatrix} -\frac{1}{8} \\ \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix} \end{array} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_1 = e^{-2x} \cdot \begin{bmatrix} -\frac{1}{8} \\ \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[2, \begin{bmatrix} \frac{1}{8} \\ \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_2 = e^{2x} \cdot \begin{bmatrix} \frac{1}{8} \\ \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix}$$

- Consider complex eigenpair, complex conjugate eigenvalue can be ignored

$$\left[-2I, \begin{bmatrix} -\frac{I}{8} \\ -\frac{1}{4} \\ \frac{I}{2} \\ 1 \end{bmatrix} \right]$$

- Solution from eigenpair

$$e^{-2Ix} \cdot \begin{bmatrix} -\frac{I}{8} \\ -\frac{1}{4} \\ \frac{I}{2} \\ 1 \end{bmatrix}$$

- Use Euler identity to write solution in terms of sin and cos

$$(\cos(2x) - I \sin(2x)) \cdot \begin{bmatrix} -\frac{I}{8} \\ -\frac{1}{4} \\ \frac{I}{2} \\ 1 \end{bmatrix}$$

- Simplify expression

$$\begin{bmatrix} -\frac{1}{8}(\cos(2x) - I \sin(2x)) \\ -\frac{\cos(2x)}{4} + \frac{I \sin(2x)}{4} \\ \frac{1}{2}(\cos(2x) - I \sin(2x)) \\ \cos(2x) - I \sin(2x) \end{bmatrix}$$

- Both real and imaginary parts are solutions to the homogeneous system

$$\vec{y}_3(x) = \begin{bmatrix} -\frac{\sin(2x)}{8} \\ -\frac{\cos(2x)}{4} \\ \frac{\sin(2x)}{2} \\ \cos(2x) \end{bmatrix}, \vec{y}_4(x) = \begin{bmatrix} -\frac{\cos(2x)}{8} \\ \frac{\sin(2x)}{4} \\ \frac{\cos(2x)}{2} \\ -\sin(2x) \end{bmatrix}$$

- General solution of the system of ODEs can be written in terms of the particular solution $\vec{y}_p(x)$
 $\vec{y}(x) = c_1 \vec{y}_1 + c_2 \vec{y}_2 + c_3 \vec{y}_3(x) + c_4 \vec{y}_4(x) + \vec{y}_p(x)$

□ Fundamental matrix

- Let $\phi(x)$ be the matrix whose columns are the independent solutions of the homogeneous system

$$\phi(x) = \begin{bmatrix} -\frac{e^{-2x}}{8} & \frac{e^{2x}}{8} & -\frac{\sin(2x)}{8} & -\frac{\cos(2x)}{8} \\ \frac{e^{-2x}}{4} & \frac{e^{2x}}{4} & -\frac{\cos(2x)}{4} & \frac{\sin(2x)}{4} \\ -\frac{e^{-2x}}{2} & \frac{e^{2x}}{2} & \frac{\sin(2x)}{2} & \frac{\cos(2x)}{2} \\ e^{-2x} & e^{2x} & \cos(2x) & -\sin(2x) \end{bmatrix}$$

- The fundamental matrix, $\Phi(x)$ is a normalized version of $\phi(x)$ satisfying $\Phi(0) = I$ where I is the identity matrix
 $\Phi(x) = \phi(x) \cdot \frac{1}{\phi(0)}$

- Substitute the value of $\phi(x)$ and $\phi(0)$

$$\Phi(x) = \begin{bmatrix} -\frac{e^{-2x}}{8} & \frac{e^{2x}}{8} & -\frac{\sin(2x)}{8} & -\frac{\cos(2x)}{8} \\ \frac{e^{-2x}}{4} & \frac{e^{2x}}{4} & -\frac{\cos(2x)}{4} & \frac{\sin(2x)}{4} \\ -\frac{e^{-2x}}{2} & \frac{e^{2x}}{2} & \frac{\sin(2x)}{2} & \frac{\cos(2x)}{2} \\ e^{-2x} & e^{2x} & \cos(2x) & -\sin(2x) \end{bmatrix} \cdot \frac{1}{\begin{bmatrix} -\frac{1}{8} & \frac{1}{8} & 0 & -\frac{1}{8} \\ \frac{1}{4} & \frac{1}{4} & -\frac{1}{4} & 0 \\ -\frac{1}{2} & \frac{1}{2} & 0 & \frac{1}{2} \\ 1 & 1 & 1 & 0 \end{bmatrix}}$$

- Evaluate and simplify to get the fundamental matrix

$$\Phi(x) = \begin{bmatrix} \frac{e^{-2x}}{4} + \frac{e^{2x}}{4} + \frac{\cos(2x)}{2} & -\frac{e^{-2x}}{8} + \frac{e^{2x}}{8} + \frac{\sin(2x)}{4} & \frac{e^{-2x}}{16} + \frac{e^{2x}}{16} - \frac{\cos(2x)}{8} & -\frac{e^{-2x}}{32} + \frac{e^{2x}}{32} + \frac{\sin(2x)}{16} \\ -\frac{e^{-2x}}{2} + \frac{e^{2x}}{2} - \sin(2x) & \frac{e^{-2x}}{4} + \frac{e^{2x}}{4} + \frac{\cos(2x)}{2} & -\frac{e^{-2x}}{8} + \frac{e^{2x}}{8} + \frac{\sin(2x)}{4} & \frac{e^{-2x}}{16} + \frac{e^{2x}}{16} - \frac{\cos(2x)}{8} \\ e^{-2x} + e^{2x} - 2\cos(2x) & -\frac{e^{-2x}}{2} + \frac{e^{2x}}{2} - \sin(2x) & \frac{e^{-2x}}{4} + \frac{e^{2x}}{4} + \frac{\cos(2x)}{2} & -\frac{e^{-2x}}{8} + \frac{e^{2x}}{8} - \frac{\sin(2x)}{4} \\ -2e^{-2x} + 2e^{2x} + 4\sin(2x) & e^{-2x} + e^{2x} - 2\cos(2x) & -\frac{e^{-2x}}{2} + \frac{e^{2x}}{2} - \sin(2x) & \frac{e^{-2x}}{4} + \frac{e^{2x}}{4} - \frac{\cos(2x)}{2} \end{bmatrix}$$

□

Find a particular solution of the system of ODEs using variation of parameters

- Let the particular solution be the fundamental matrix multiplied by $\vec{v}(x)$ and solve for $\vec{v}(x)$

$$\vec{y}_p(x) = \Phi(x) \cdot \vec{v}(x)$$

- Take the derivative of the particular solution

$$\vec{y}'_p(x) = \Phi'(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x)$$

- Substitute particular solution and its derivative into the system of ODEs

$$\Phi'(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x) = A \cdot \Phi(x) \cdot \vec{v}(x) + \vec{f}(x)$$

- The fundamental matrix has columns that are solutions to the homogeneous system so its derivative is $A \cdot \Phi(x)$

$$A \cdot \Phi(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x) = A \cdot \Phi(x) \cdot \vec{v}(x) + \vec{f}(x)$$

- Cancel like terms

$$\Phi(x) \cdot \vec{v}'(x) = \vec{f}(x)$$

- Multiply by the inverse of the fundamental matrix

$$\vec{v}'(x) = \frac{1}{\Phi(x)} \cdot \vec{f}(x)$$

- Integrate to solve for $\vec{v}(x)$

$$\vec{v}(x) = \int_0^x \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds$$

- Plug $\vec{v}(x)$ into the equation for the particular solution

$$\vec{y}_p(x) = \Phi(x) \cdot \left(\int_0^x \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds \right)$$

- Plug in the fundamental matrix and the forcing function and compute

$$\vec{y}_p(x) = \begin{bmatrix} \frac{3}{512} + \frac{(128x^5 - 480x^4 + 800x^3 - 600x^2 + 60x + 145)e^{2x}}{20480} - \frac{5e^{-2x}}{4096} + \frac{(16x^3 - 30x - 9)\cos(x)^2}{768} - \frac{3x^2 \cos(x) \sin(x)}{64} \\ \frac{5}{256} + \frac{(128x^5 - 160x^4 - 160x^3 + 600x^2 - 540x + 175)e^{2x}}{10240} + \frac{5e^{-2x}}{2048} + \frac{(-4x^2 - 5)\cos(x)^2}{128} + \frac{(-16x^3 - 6x + 9)\sin(x)}{384} \\ -\frac{3}{128} + \frac{(128x^5 + 160x^4 - 480x^3 + 360x^2 + 60x - 95)e^{2x}}{5120} - \frac{5e^{-2x}}{1024} + \frac{(-16x^3 - 18x + 9)\cos(x)^2}{192} + \frac{(-x^2 + 1)\sin(x)}{16} \\ -\frac{1}{64} + \frac{(128x^5 + 480x^4 - 160x^3 - 360x^2 + 420x - 65)e^{2x}}{2560} + \frac{5e^{-2x}}{512} + \frac{(-12x^2 + 1)\cos(x)^2}{32} + \frac{(16x^3 + 6x - 9)\sin(x)}{96} \end{bmatrix}$$

- Plug particular solution back into general solution

$$\vec{y}(x) = c_1 \vec{y}_1 + c_2 \vec{y}_2 + c_3 \vec{y}_3(x) + c_4 \vec{y}_4(x) + \begin{bmatrix} \frac{3}{512} + \frac{(128x^5 - 480x^4 + 800x^3 - 600x^2 + 60x + 145)e^{2x}}{20480} - \frac{5e^{-2x}}{4096} \\ \frac{5}{256} + \frac{(128x^5 - 160x^4 - 160x^3 + 600x^2 - 540x + 175)e^{2x}}{10240} + \frac{5e^{-2x}}{2048} \\ -\frac{3}{128} + \frac{(128x^5 + 160x^4 - 480x^3 + 360x^2 + 60x - 95)e^{2x}}{5120} - \frac{5e^{-2x}}{1024} \\ -\frac{1}{64} + \frac{(128x^5 + 480x^4 - 160x^3 - 360x^2 + 420x - 65)e^{2x}}{2560} + \frac{5e^{-2x}}{512} \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y = \frac{3}{512} + \frac{(128x^5 - 480x^4 + 800x^3 - 600x^2 + 2560c_2 + 60x + 145)e^{2x}}{20480} + \frac{(-5 - 512c_1)e^{-2x}}{4096} + \frac{(16x^3 - 192c_4 - 30x - 9) \cos(x)^2}{768} + \frac{3e^{-2x}}{512}$$

Maple trace

```

`Methods for high order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 4; linear nonhomogeneous with symmetry [0,1]
trying high order linear exact nonhomogeneous
trying differential order: 4; missing the dependent variable
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 79

```
dsolve(diff(y(x), x$4) - 16*y(x) = x^2*sin(2*x) + x^4*exp(2*x), y(x), singsol=all)
```

$$y(x) = \frac{(128x^5 - 480x^4 + 800x^3 - 600x^2 + 20480c_3 + 60x + 105)e^{2x}}{20480} + \frac{(8x^3 + 768c_1 - 15x) \cos(2x)}{768} + \frac{(-6x^2 + 256c_4 - 11) \sin(2x)}{256} + e^{-2x}c_2$$

✓ Solution by Mathematica

Time used: 0.562 (sec). Leaf size: 92

```
DSolve[y''''[x]-16*y[x]==x^2*Sin[2*x]+x^4*Exp[2*x],y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{1}{768}(8x^3 - 15x + 768c_2) \cos(2x) - \frac{1}{512}(24x^2 - 5 - 1024c_4) \sin(x) \cos(x) \\ + \frac{e^{2x}(128x^5 - 480x^4 + 800x^3 - 600x^2 + 60x + 105 + 20480c_1)}{20480} + c_3 e^{-2x}$$

11.50 problem 50

Internal problem ID [11824]

Internal file name [OUTPUT/11833_Thursday_April_11_2024_08_52_05_PM_42327415/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 50.

ODE order: 6.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_high_order , _missing_y]]
```

$$y^{(6)} + 2y^{(5)} + 5y'''' = x^3 + x^2e^{-x} + e^{-x} \sin(2x)$$

This is higher order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE And y_p is a particular solution to the nonhomogeneous ODE. y_h is the solution to

$$y^{(6)} + 2y^{(5)} + 5y'''' = 0$$

The characteristic equation is

$$\lambda^6 + 2\lambda^5 + 5\lambda^4 = 0$$

The roots of the above equation are

$$\lambda_1 = 0$$

$$\lambda_2 = 0$$

$$\lambda_3 = 0$$

$$\lambda_4 = 0$$

$$\lambda_5 = -1 + 2i$$

$$\lambda_6 = -1 - 2i$$

Therefore the homogeneous solution is

$$y_h(x) = x^3 c_4 + c_3 x^2 + c_2 x + c_1 + e^{(-1-2i)x} c_5 + e^{(-1+2i)x} c_6$$

The fundamental set of solutions for the homogeneous solution are the following

$$\begin{aligned} y_1 &= 1 \\ y_2 &= x \\ y_3 &= x^2 \\ y_4 &= x^3 \\ y_5 &= e^{(-1-2i)x} \\ y_6 &= e^{(-1+2i)x} \end{aligned}$$

Now the particular solution to the given ODE is found

$$y^{(6)} + 2y^{(5)} + 5y^{(4)} = x^3 + x^2 e^{-x} + e^{-x} \sin(2x)$$

Let the particular solution be

$$y_p = U_1 y_1 + U_2 y_2 + U_3 y_3 + U_4 y_4 + U_5 y_5 + U_6 y_6$$

Where y_i are the basis solutions found above for the homogeneous solution y_h and $U_i(x)$ are functions to be determined as follows

$$U_i = (-1)^{n-i} \int \frac{F(x)W_i(x)}{aW(x)} dx$$

Where $W(x)$ is the Wronskian and $W_i(x)$ is the Wronskian that results after deleting the last row and the i -th column of the determinant and n is the order of the ODE or equivalently, the number of basis solutions, and a is the coefficient of the leading derivative in the ODE, and $F(x)$ is the RHS of the ODE. Therefore, the first step is to find the Wronskian $W(x)$. This is given by

$$W(x) = \begin{vmatrix} y_1 & y_2 & y_3 & y_4 & y_5 & y_6 \\ y_1' & y_2' & y_3' & y_4' & y_5' & y_6' \\ y_1'' & y_2'' & y_3'' & y_4'' & y_5'' & y_6'' \\ y_1''' & y_2''' & y_3''' & y_4''' & y_5''' & y_6''' \\ y_1'''' & y_2'''' & y_3'''' & y_4'''' & y_5'''' & y_6'''' \\ y_1''''' & y_2''''' & y_3''''' & y_4''''' & y_5''''' & y_6''''' \end{vmatrix}$$

Substituting the fundamental set of solutions y_i found above in the Wronskian gives

$$W = \begin{bmatrix} 1 & x & x^2 & x^3 & e^{(-1-2i)x} & e^{(-1+2i)x} \\ 0 & 1 & 2x & 3x^2 & (-1-2i)e^{(-1-2i)x} & (-1+2i)e^{(-1+2i)x} \\ 0 & 0 & 2 & 6x & (-3+4i)e^{(-1-2i)x} & (-3-4i)e^{(-1+2i)x} \\ 0 & 0 & 0 & 6 & (11+2i)e^{(-1-2i)x} & (11-2i)e^{(-1+2i)x} \\ 0 & 0 & 0 & 0 & (-7-24i)e^{(-1-2i)x} & (-7+24i)e^{(-1+2i)x} \\ 0 & 0 & 0 & 0 & (-41+38i)e^{(-1-2i)x} & (-41-38i)e^{(-1+2i)x} \end{bmatrix}$$

$$|W| = 30000ie^{(-1-2i)x}e^{(-1+2i)x}$$

The determinant simplifies to

$$|W| = 30000ie^{-2x}$$

Now we determine W_i for each U_i .

$$W_1(x) = \det \begin{bmatrix} x & x^2 & x^3 & e^{(-1-2i)x} & e^{(-1+2i)x} \\ 1 & 2x & 3x^2 & (-1-2i)e^{(-1-2i)x} & (-1+2i)e^{(-1+2i)x} \\ 0 & 2 & 6x & (-3+4i)e^{(-1-2i)x} & (-3-4i)e^{(-1+2i)x} \\ 0 & 0 & 6 & (11+2i)e^{(-1-2i)x} & (11-2i)e^{(-1+2i)x} \\ 0 & 0 & 0 & (-7-24i)e^{(-1-2i)x} & (-7+24i)e^{(-1+2i)x} \end{bmatrix}$$

$$= 8ie^{-2x}(125x^3 + 150x^2 - 30x - 72)$$

$$W_2(x) = \det \begin{bmatrix} 1 & x^2 & x^3 & e^{(-1-2i)x} & e^{(-1+2i)x} \\ 0 & 2x & 3x^2 & (-1-2i)e^{(-1-2i)x} & (-1+2i)e^{(-1+2i)x} \\ 0 & 2 & 6x & (-3+4i)e^{(-1-2i)x} & (-3-4i)e^{(-1+2i)x} \\ 0 & 0 & 6 & (11+2i)e^{(-1-2i)x} & (11-2i)e^{(-1+2i)x} \\ 0 & 0 & 0 & (-7-24i)e^{(-1-2i)x} & (-7+24i)e^{(-1+2i)x} \end{bmatrix}$$

$$= 120ie^{-2x}(25x^2 + 20x - 2)$$

$$\begin{aligned}
W_3(x) &= \det \begin{bmatrix} 1 & x & x^3 & e^{(-1-2i)x} & e^{(-1+2i)x} \\ 0 & 1 & 3x^2 & (-1-2i)e^{(-1-2i)x} & (-1+2i)e^{(-1+2i)x} \\ 0 & 0 & 6x & (-3+4i)e^{(-1-2i)x} & (-3-4i)e^{(-1+2i)x} \\ 0 & 0 & 6 & (11+2i)e^{(-1-2i)x} & (11-2i)e^{(-1+2i)x} \\ 0 & 0 & 0 & (-7-24i)e^{(-1-2i)x} & (-7+24i)e^{(-1+2i)x} \end{bmatrix} \\
&= 600ie^{-2x}(2+5x)
\end{aligned}$$

$$\begin{aligned}
W_4(x) &= \det \begin{bmatrix} 1 & x & x^2 & e^{(-1-2i)x} & e^{(-1+2i)x} \\ 0 & 1 & 2x & (-1-2i)e^{(-1-2i)x} & (-1+2i)e^{(-1+2i)x} \\ 0 & 0 & 2 & (-3+4i)e^{(-1-2i)x} & (-3-4i)e^{(-1+2i)x} \\ 0 & 0 & 0 & (11+2i)e^{(-1-2i)x} & (11-2i)e^{(-1+2i)x} \\ 0 & 0 & 0 & (-7-24i)e^{(-1-2i)x} & (-7+24i)e^{(-1+2i)x} \end{bmatrix} \\
&= 1000ie^{-2x}
\end{aligned}$$

$$\begin{aligned}
W_5(x) &= \det \begin{bmatrix} 1 & x & x^2 & x^3 & e^{(-1+2i)x} \\ 0 & 1 & 2x & 3x^2 & (-1+2i)e^{(-1+2i)x} \\ 0 & 0 & 2 & 6x & (-3-4i)e^{(-1+2i)x} \\ 0 & 0 & 0 & 6 & (11-2i)e^{(-1+2i)x} \\ 0 & 0 & 0 & 0 & (-7+24i)e^{(-1+2i)x} \end{bmatrix} \\
&= (-84+288i)e^{(-1+2i)x}
\end{aligned}$$

$$\begin{aligned}
W_6(x) &= \det \begin{bmatrix} 1 & x & x^2 & x^3 & e^{(-1-2i)x} \\ 0 & 1 & 2x & 3x^2 & (-1-2i)e^{(-1-2i)x} \\ 0 & 0 & 2 & 6x & (-3+4i)e^{(-1-2i)x} \\ 0 & 0 & 0 & 6 & (11+2i)e^{(-1-2i)x} \\ 0 & 0 & 0 & 0 & (-7-24i)e^{(-1-2i)x} \end{bmatrix} \\
&= (-84-288i)e^{(-1-2i)x}
\end{aligned}$$

Now we are ready to evaluate each $U_i(x)$.

$$\begin{aligned}
 U_1 &= (-1)^{6-1} \int \frac{F(x)W_1(x)}{aW(x)} dx \\
 &= (-1)^5 \int \frac{(x^3 + x^2e^{-x} + e^{-x} \sin(2x)) (8ie^{-2x}(125x^3 + 150x^2 - 30x - 72))}{(1)(30000ie^{-2x})} dx \\
 &= - \int \frac{8i(x^3 + x^2e^{-x} + e^{-x} \sin(2x)) e^{-2x}(125x^3 + 150x^2 - 30x - 72)}{30000ie^{-2x}} dx \\
 &= - \int \left(\frac{(x^3 + x^2e^{-x} + e^{-x} \sin(2x)) (125x^3 + 150x^2 - 30x - 72)}{3750} \right) dx \\
 &= \frac{3x^4}{625} + \frac{12e^{-x}(-\sin(2x) - 2\cos(2x))}{3125} + \frac{3046e^{-x}}{625} + \frac{31x^4e^{-x}}{150} + \frac{307x^3e^{-x}}{375} + \frac{x^5}{625} + \frac{3046xe^{-x}}{625} - \frac{x^6}{150}
 \end{aligned}$$

$$\begin{aligned}
 U_2 &= (-1)^{6-2} \int \frac{F(x)W_2(x)}{aW(x)} dx \\
 &= (-1)^4 \int \frac{(x^3 + x^2e^{-x} + e^{-x} \sin(2x)) (120ie^{-2x}(25x^2 + 20x - 2))}{(1)(30000ie^{-2x})} dx \\
 &= \int \frac{120i(x^3 + x^2e^{-x} + e^{-x} \sin(2x)) e^{-2x}(25x^2 + 20x - 2)}{30000ie^{-2x}} dx \\
 &= \int \left(\frac{(x^3 + x^2e^{-x} + e^{-x} \sin(2x)) (25x^2 + 20x - 2)}{250} \right) dx \\
 &= \frac{x^6}{60} + \frac{2x^5}{125} - \frac{x^4}{500} - \frac{x^4e^{-x}}{10} - \frac{12x^3e^{-x}}{25} - \frac{179x^2e^{-x}}{125} - \frac{358xe^{-x}}{125} - \frac{358e^{-x}}{125} + \frac{(-\frac{2}{5}x^2 - \frac{8}{25}x + \frac{4}{125})e^{-x}}{10}
 \end{aligned}$$

$$\begin{aligned}
 U_3 &= (-1)^{6-3} \int \frac{F(x)W_3(x)}{aW(x)} dx \\
 &= (-1)^3 \int \frac{(x^3 + x^2e^{-x} + e^{-x} \sin(2x)) (600ie^{-2x}(2 + 5x))}{(1)(30000ie^{-2x})} dx \\
 &= - \int \frac{600i(x^3 + x^2e^{-x} + e^{-x} \sin(2x)) e^{-2x}(2 + 5x)}{30000ie^{-2x}} dx \\
 &= - \int \left(\frac{((x^2 + \sin(2x))e^{-x} + x^3) (\frac{2}{5} + x)}{10} \right) dx \\
 &= -\frac{x^4}{100} - \frac{x^5}{50} + \frac{17x^2e^{-x}}{50} + \frac{17xe^{-x}}{25} + \frac{17e^{-x}}{25} + \frac{x^3e^{-x}}{10} - \frac{e^{-x}(-\sin(2x) - 2\cos(2x))}{125} - \frac{(-\frac{2x}{5} - \frac{4}{25})e^{-x}}{10} \\
 &= -\frac{x^4}{100} - \frac{x^5}{50} + \frac{17x^2e^{-x}}{50} + \frac{17xe^{-x}}{25} + \frac{17e^{-x}}{25} + \frac{x^3e^{-x}}{10} - \frac{e^{-x}(-\sin(2x) - 2\cos(2x))}{125} - \frac{(-\frac{2x}{5} - \frac{4}{25})e^{-x}}{10}
 \end{aligned}$$

$$\begin{aligned}
U_4 &= (-1)^{6-4} \int \frac{F(x)W_4(x)}{aW(x)} dx \\
&= (-1)^2 \int \frac{(x^3 + x^2e^{-x} + e^{-x} \sin(2x)) (1000ie^{-2x})}{(1) (30000ie^{-2x})} dx \\
&= \int \frac{1000i(x^3 + x^2e^{-x} + e^{-x} \sin(2x)) e^{-2x}}{30000ie^{-2x}} dx \\
&= \int \left(\frac{(x^2 + \sin(2x)) e^{-x}}{30} + \frac{x^3}{30} \right) dx \\
&= \frac{x^4}{120} - \frac{x^2e^{-x}}{30} - \frac{x e^{-x}}{15} - \frac{e^{-x}}{15} + \frac{e^{-x}(-\sin(2x) - 2 \cos(2x))}{150} \\
&= \frac{x^4}{120} - \frac{x^2e^{-x}}{30} - \frac{x e^{-x}}{15} - \frac{e^{-x}}{15} + \frac{e^{-x}(-\sin(2x) - 2 \cos(2x))}{150}
\end{aligned}$$

$$\begin{aligned}
U_5 &= (-1)^{6-5} \int \frac{F(x)W_5(x)}{aW(x)} dx \\
&= (-1)^1 \int \frac{(x^3 + x^2e^{-x} + e^{-x} \sin(2x)) ((-84 + 288i) e^{(-1+2i)x})}{(1) (30000ie^{-2x})} dx \\
&= - \int \frac{(-84 + 288i) (x^3 + x^2e^{-x} + e^{-x} \sin(2x)) e^{(-1+2i)x}}{30000ie^{-2x}} dx \\
&= - \int \left(\left(\frac{6}{625} + \frac{7i}{2500} \right) ((x^2 + \sin(2x)) e^{-x} + x^3) e^{(1+2i)x} \right) dx \\
&= \left(-\frac{6}{625} - \frac{7i}{2500} \right) \left(\left(-\frac{7}{625} + \frac{24i}{625} \right) ((-11 - 2i) e^{(1+2i)x} x^3 + (9 - 12i) e^{(1+2i)x} x^2 + (6 + 12i) x e^{(1+2i)x}) \right) \\
&= \left(-\frac{6}{625} - \frac{7i}{2500} \right) \left(\left(-\frac{7}{625} + \frac{24i}{625} \right) ((-11 - 2i) e^{(1+2i)x} x^3 + (9 - 12i) e^{(1+2i)x} x^2 + (6 + 12i) x e^{(1+2i)x}) \right)
\end{aligned}$$

$$\begin{aligned}
U_6 &= (-1)^{6-6} \int \frac{F(x)W_6(x)}{aW(x)} dx \\
&= (-1)^0 \int \frac{(x^3 + x^2e^{-x} + e^{-x} \sin(2x)) ((-84 - 288i) e^{(-1-2i)x})}{(1)(30000ie^{-2x})} dx \\
&= \int \frac{(-84 - 288i)(x^3 + x^2e^{-x} + e^{-x} \sin(2x)) e^{(-1-2i)x}}{30000ie^{-2x}} dx \\
&= \int \left(\left(-\frac{6}{625} + \frac{7i}{2500} \right) ((x^2 + \sin(2x)) e^{-x} + x^3) e^{(1-2i)x} \right) dx \\
&= \left(-\frac{6}{625} + \frac{7i}{2500} \right) \left(\left(-\frac{7}{625} - \frac{24i}{625} \right) ((-11 + 2i) e^{(1-2i)x} x^3 + (9 + 12i) e^{(1-2i)x} x^2 + (6 - 12i) x e^{(1-2i)x}) \right) \\
&= \left(-\frac{6}{625} + \frac{7i}{2500} \right) \left(\left(-\frac{7}{625} - \frac{24i}{625} \right) ((-11 + 2i) e^{(1-2i)x} x^3 + (9 + 12i) e^{(1-2i)x} x^2 + (6 - 12i) x e^{(1-2i)x}) \right)
\end{aligned}$$

Now that all the U_i functions have been determined, the particular solution is found from

$$y_p = U_1y_1 + U_2y_2 + U_3y_3 + U_4y_4 + U_5y_5 + U_6y_6$$

Hence

$$\begin{aligned}
y_p &= \left(\frac{3x^4}{625} + \frac{12e^{-x}(-\sin(2x) - 2\cos(2x))}{3125} + \frac{3046e^{-x}}{625} + \frac{31x^4e^{-x}}{150} + \frac{307x^3e^{-x}}{375} + \frac{x^5}{625} + \frac{3046xe^{-x}}{625} - \frac{1}{1} \right) \\
&+ \left(\frac{x^6}{60} + \frac{2x^5}{125} - \frac{x^4}{500} - \frac{x^4e^{-x}}{10} - \frac{12x^3e^{-x}}{25} - \frac{179x^2e^{-x}}{125} - \frac{358xe^{-x}}{125} - \frac{358e^{-x}}{125} + \frac{(-\frac{2}{5}x^2 - \frac{8}{25}x + \frac{4}{125})e^{-x}}{10} \right) \\
&+ \left(-\frac{x^4}{100} - \frac{x^5}{50} + \frac{17x^2e^{-x}}{50} + \frac{17xe^{-x}}{25} + \frac{17e^{-x}}{25} + \frac{x^3e^{-x}}{10} - \frac{e^{-x}(-\sin(2x) - 2\cos(2x))}{125} - \frac{(-\frac{2x}{5} - \frac{4}{25})}{1} \right) \\
&+ \left(\frac{x^4}{120} - \frac{x^2e^{-x}}{30} - \frac{xe^{-x}}{15} - \frac{e^{-x}}{15} + \frac{e^{-x}(-\sin(2x) - 2\cos(2x))}{150} \right) (x^3) \\
&+ \left(\left(-\frac{6}{625} - \frac{7i}{2500} \right) \left(\left(-\frac{7}{625} + \frac{24i}{625} \right) ((-11 - 2i) e^{(1+2i)x} x^3 + (9 - 12i) e^{(1+2i)x} x^2 + (6 + 12i) x e^{(1+2i)x}) \right) \right) \\
&+ \left(\left(-\frac{6}{625} + \frac{7i}{2500} \right) \left(\left(-\frac{7}{625} - \frac{24i}{625} \right) ((-11 + 2i) e^{(1-2i)x} x^3 + (9 + 12i) e^{(1-2i)x} x^2 + (6 - 12i) x e^{(1-2i)x}) \right) \right)
\end{aligned}$$

Therefore the particular solution is

$$y_p = -\frac{1008}{390625} + \frac{(-448 - 339i + (70 - 240i)x) e^{(-1-2i)x}}{50000} + \frac{(-448 + 339i + (70 + 240i)x) e^{(-1+2i)x}}{50000} + \frac{(2x^2 - 1)}{1}$$

Which simplifies to

$$y_p = \frac{((183750x - 1176000) \cos(2x) + (-630000x - 889875) \sin(2x) + 16406250x^2 + 131250000x + 319900000)}{65625000}$$

Therefore the general solution is

$$y = y_h + y_p$$

$$= (x^3 c_4 + c_3 x^2 + c_2 x + c_1 + e^{(-1-2i)x} c_5 + e^{(-1+2i)x} c_6) + \left(\frac{((183750x - 1176000) \cos(2x) + (-630000x - 889875) \sin(2x) + 16406250x^2 + 131250000x + 31990000)}{65625000} + \frac{x^7}{4200} - \frac{x^6}{1500} - \frac{x^5}{2500} + \frac{3x^4}{625} - \frac{19x^3}{3125} - \frac{66x^2}{15625} + \frac{834x}{78125} - \frac{1008}{390625} \right)$$

Summary

The solution(s) found are the following

$$y = x^3 c_4 + c_3 x^2 + c_2 x + c_1 + e^{(-1-2i)x} c_5 + e^{(-1+2i)x} c_6 \quad (1) + \frac{((183750x - 1176000) \cos(2x) + (-630000x - 889875) \sin(2x) + 16406250x^2 + 131250000x + 31990000)}{65625000} + \frac{x^7}{4200} - \frac{x^6}{1500} - \frac{x^5}{2500} + \frac{3x^4}{625} - \frac{19x^3}{3125} - \frac{66x^2}{15625} + \frac{834x}{78125} - \frac{1008}{390625}$$

Verification of solutions

$$y = x^3 c_4 + c_3 x^2 + c_2 x + c_1 + e^{(-1-2i)x} c_5 + e^{(-1+2i)x} c_6 + \frac{((183750x - 1176000) \cos(2x) + (-630000x - 889875) \sin(2x) + 16406250x^2 + 131250000x + 31990000)}{65625000} + \frac{x^7}{4200} - \frac{x^6}{1500} - \frac{x^5}{2500} + \frac{3x^4}{625} - \frac{19x^3}{3125} - \frac{66x^2}{15625} + \frac{834x}{78125} - \frac{1008}{390625}$$

Verified OK.

Maple trace

```
`Methods for high order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 6; linear nonhomogeneous with symmetry [0,1]
-> Calling odsolve with the ODE`, diff(diff(_b(_a), _a), _a) = _a^2*exp(-_a)+_a^3+exp(-_a)*s
  Methods for second order ODEs:
  --- Trying classification methods ---
  trying a quadrature
  trying high order exact linear fully integrable
  trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
  trying a double symmetry of the form [xi=0, eta=F(x)]
  -> Try solving first the homogeneous part of the ODE
    checking if the LODE has constant coefficients
    <- constant coefficients successful
    <- solving first the homogeneous part of the ODE successful
  <- differential order: 6; linear nonhomogeneous with symmetry [0,1] successful`
```

✓ Solution by Maple

Time used: 0.031 (sec). Leaf size: 91

```
dsolve(diff(y(x),x$6)+2*diff(y(x),x$5)+5*diff(y(x),x$4)=x^3+x^2*exp(-x)+exp(-x)*sin(2*x),y(x)
```

$$y(x) = c_5x + c_6 + \frac{(\int (((-330x + 1320c_1 + 240c_2 + 69) \cos(2x) + (60x - 240c_1 + 1320c_2 + 567) \sin(2x) - 3750x^2 - 22)) dx)}{15000}$$

✓ Solution by Mathematica

Time used: 11.809 (sec). Leaf size: 119

```
DSolve[y''''''[x]+2*y''''''[x]+5*y''''[x]==x^3+x^2*Exp[-x]+Exp[-x]*Sin[2*x],y[x],x,IncludeSin
```

$$y(x) \rightarrow c_6x^3 + c_5x^2 + \frac{e^{-x}(10(25e^x x^7 - 70e^x x^6 - 42e^x x^5 + 504e^x x^4 + 26250x^2 + 210000x + 511875) + 84(35x - 2(97 + 24)) \sin(2x))}{1050000} + c_4x + c_3$$

11.51 problem 51

Internal problem ID [11825]

Internal file name [OUTPUT/11834_Thursday_April_11_2024_08_52_41_PM_58692852/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 51.

ODE order: 4.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_high_order , _linear , _nonhomogeneous]]
```

$$y'''' + 2y'' + y = \cos(x) x^2$$

This is higher order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE And y_p is a particular solution to the nonhomogeneous ODE. y_h is the solution to

$$y'''' + 2y'' + y = 0$$

The characteristic equation is

$$\lambda^4 + 2\lambda^2 + 1 = 0$$

The roots of the above equation are

$$\lambda_1 = i$$

$$\lambda_2 = -i$$

$$\lambda_3 = i$$

$$\lambda_4 = -i$$

Therefore the homogeneous solution is

$$y_h(x) = e^{ix} c_1 + x e^{ix} c_2 + e^{-ix} c_3 + x e^{-ix} c_4$$

The fundamental set of solutions for the homogeneous solution are the following

$$\begin{aligned} y_1 &= e^{ix} \\ y_2 &= x e^{ix} \\ y_3 &= e^{-ix} \\ y_4 &= x e^{-ix} \end{aligned}$$

Now the particular solution to the given ODE is found

$$y'''' + 2y'' + y = \cos(x) x^2$$

Let the particular solution be

$$y_p = U_1 y_1 + U_2 y_2 + U_3 y_3 + U_4 y_4$$

Where y_i are the basis solutions found above for the homogeneous solution y_h and $U_i(x)$ are functions to be determined as follows

$$U_i = (-1)^{n-i} \int \frac{F(x)W_i(x)}{aW(x)} dx$$

Where $W(x)$ is the Wronskian and $W_i(x)$ is the Wronskian that results after deleting the last row and the i -th column of the determinant and n is the order of the ODE or equivalently, the number of basis solutions, and a is the coefficient of the leading derivative in the ODE, and $F(x)$ is the RHS of the ODE. Therefore, the first step is to find the Wronskian $W(x)$. This is given by

$$W(x) = \begin{vmatrix} y_1 & y_2 & y_3 & y_4 \\ y_1' & y_2' & y_3' & y_4' \\ y_1'' & y_2'' & y_3'' & y_4'' \\ y_1''' & y_2''' & y_3''' & y_4''' \end{vmatrix}$$

Substituting the fundamental set of solutions y_i found above in the Wronskian gives

$$W = \begin{bmatrix} e^{ix} & x e^{ix} & e^{-ix} & x e^{-ix} \\ ie^{ix} & e^{ix}(ix + 1) & -ie^{-ix} & e^{-ix}(-ix + 1) \\ -e^{ix} & e^{ix}(2i - x) & -e^{-ix} & e^{-ix}(-2i - x) \\ -ie^{ix} & -e^{ix}(ix + 3) & ie^{-ix} & e^{-ix}(ix - 3) \end{bmatrix}$$

$$|W| = 16 e^{2ix} e^{-2ix}$$

The determinant simplifies to

$$|W| = 16$$

Now we determine W_i for each U_i .

$$\begin{aligned} W_1(x) &= \det \begin{bmatrix} x e^{ix} & e^{-ix} & x e^{-ix} \\ e^{ix}(ix+1) & -ie^{-ix} & e^{-ix}(-ix+1) \\ e^{ix}(2i-x) & -e^{-ix} & e^{-ix}(-2i-x) \end{bmatrix} \\ &= -4e^{-ix}(x-i) \end{aligned}$$

$$\begin{aligned} W_2(x) &= \det \begin{bmatrix} e^{ix} & e^{-ix} & x e^{-ix} \\ ie^{ix} & -ie^{-ix} & e^{-ix}(-ix+1) \\ -e^{ix} & -e^{-ix} & e^{-ix}(-2i-x) \end{bmatrix} \\ &= -4e^{-ix} \end{aligned}$$

$$\begin{aligned} W_3(x) &= \det \begin{bmatrix} e^{ix} & x e^{ix} & x e^{-ix} \\ ie^{ix} & e^{ix}(ix+1) & e^{-ix}(-ix+1) \\ -e^{ix} & e^{ix}(2i-x) & e^{-ix}(-2i-x) \end{bmatrix} \\ &= -4e^{ix}(x+i) \end{aligned}$$

$$\begin{aligned} W_4(x) &= \det \begin{bmatrix} e^{ix} & x e^{ix} & e^{-ix} \\ ie^{ix} & e^{ix}(ix+1) & -ie^{-ix} \\ -e^{ix} & e^{ix}(2i-x) & -e^{-ix} \end{bmatrix} \\ &= -4e^{ix} \end{aligned}$$

Now we are ready to evaluate each $U_i(x)$.

$$\begin{aligned} U_1 &= (-1)^{4-1} \int \frac{F(x)W_1(x)}{aW(x)} dx \\ &= (-1)^3 \int \frac{(\cos(x)x^2)(-4e^{-ix}(x-i))}{(1)(16)} dx \\ &= - \int \frac{-4 \cos(x)x^2 e^{-ix}(x-i)}{16} dx \\ &= - \int \left(-\frac{\cos(x)x^2 e^{-ix}(x-i)}{4} \right) dx \\ &= - \left(\int -\frac{\cos(x)x^2 e^{-ix}(x-i)}{4} dx \right) \end{aligned}$$

$$\begin{aligned}
U_2 &= (-1)^{4-2} \int \frac{F(x)W_2(x)}{aW(x)} dx \\
&= (-1)^2 \int \frac{(\cos(x) x^2) (-4 e^{-ix})}{(1)(16)} dx \\
&= \int \frac{-4 \cos(x) x^2 e^{-ix}}{16} dx \\
&= \int \left(-\frac{\cos(x) x^2 e^{-ix}}{4} \right) dx \\
&= \int -\frac{\cos(x) x^2 e^{-ix}}{4} dx
\end{aligned}$$

$$\begin{aligned}
U_3 &= (-1)^{4-3} \int \frac{F(x)W_3(x)}{aW(x)} dx \\
&= (-1)^1 \int \frac{(\cos(x) x^2) (-4 e^{ix}(x+i))}{(1)(16)} dx \\
&= - \int \frac{-4 \cos(x) x^2 e^{ix}(x+i)}{16} dx \\
&= - \int \left(-\frac{\cos(x) x^2 e^{ix}(x+i)}{4} \right) dx \\
&= \frac{x^4}{32} + \frac{ix^3}{24} - \frac{i(4x^3 + 10ix^2 - 10x - 5i) e^{2ix}}{64}
\end{aligned}$$

$$\begin{aligned}
U_4 &= (-1)^{4-4} \int \frac{F(x)W_4(x)}{aW(x)} dx \\
&= (-1)^0 \int \frac{(\cos(x) x^2) (-4 e^{ix})}{(1)(16)} dx \\
&= \int \frac{-4 \cos(x) x^2 e^{ix}}{16} dx \\
&= \int \left(-\frac{\cos(x) x^2 e^{ix}}{4} \right) dx \\
&= -\frac{x^3}{24} + \frac{i(2x^2 + 2ix - 1) e^{2ix}}{32}
\end{aligned}$$

Now that all the U_i functions have been determined, the particular solution is found from

$$y_p = U_1 y_1 + U_2 y_2 + U_3 y_3 + U_4 y_4$$

Hence

$$\begin{aligned}
 y_p &= \left(- \left(\int - \frac{\cos(x) x^2 e^{-ix} (x-i)}{4} dx \right) \right) (e^{ix}) \\
 &+ \left(\int - \frac{\cos(x) x^2 e^{-ix}}{4} dx \right) (x e^{ix}) \\
 &+ \left(\frac{x^4}{32} + \frac{ix^3}{24} - \frac{i(4x^3 + 10ix^2 - 10x - 5i) e^{2ix}}{64} \right) (e^{-ix}) \\
 &+ \left(-\frac{x^3}{24} + \frac{i(2x^2 + 2ix - 1) e^{2ix}}{32} \right) (x e^{-ix})
 \end{aligned}$$

Therefore the particular solution is

$$y_p = \frac{\cos(x) (-4x^4 + 36x^2 + 6ix - 45)}{192} - \frac{5 \sin(x) \left(-\frac{16}{15}x^3 + i + \frac{18}{5}x\right)}{64}$$

Which simplifies to

$$y_p = \frac{\cos(x) (-4x^4 + 36x^2 + 6ix - 45)}{192} - \frac{5 \sin(x) \left(-\frac{16}{15}x^3 + i + \frac{18}{5}x\right)}{64}$$

Therefore the general solution is

$$\begin{aligned}
 y &= y_h + y_p \\
 &= (e^{ix} c_1 + x e^{ix} c_2 + e^{-ix} c_3 + x e^{-ix} c_4) \\
 &+ \left(\frac{\cos(x) (-4x^4 + 36x^2 + 6ix - 45)}{192} - \frac{5 \sin(x) \left(-\frac{16}{15}x^3 + i + \frac{18}{5}x\right)}{64} \right)
 \end{aligned}$$

Which simplifies to

$$\begin{aligned}
 y &= (c_4 x + c_3) e^{-ix} + (c_2 x + c_1) e^{ix} \\
 &+ \frac{\cos(x) (-4x^4 + 36x^2 + 6ix - 45)}{192} - \frac{5 \sin(x) \left(-\frac{16}{15}x^3 + i + \frac{18}{5}x\right)}{64}
 \end{aligned}$$

Summary

The solution(s) found are the following

$$\begin{aligned}
 y &= (c_4 x + c_3) e^{-ix} + (c_2 x + c_1) e^{ix} \\
 &+ \frac{\cos(x) (-4x^4 + 36x^2 + 6ix - 45)}{192} - \frac{5 \sin(x) \left(-\frac{16}{15}x^3 + i + \frac{18}{5}x\right)}{64}
 \end{aligned} \tag{1}$$

Verification of solutions

$$y = (c_4x + c_3) e^{-ix} + (c_2x + c_1) e^{ix} + \frac{\cos(x)(-4x^4 + 36x^2 + 6ix - 45)}{192} - \frac{5 \sin(x) \left(-\frac{16}{15}x^3 + i + \frac{18}{5}x\right)}{64}$$

Verified OK.

Maple trace

```
`Methods for high order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
trying differential order: 4; linear nonhomogeneous with symmetry [0,1]  
trying high order linear exact nonhomogeneous  
trying differential order: 4; missing the dependent variable  
checking if the LODE has constant coefficients  
<- constant coefficients successful`
```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 46

```
dsolve(diff(y(x),x$4)+2*diff(y(x),x$2)+y(x)=x^2*cos(x),y(x), singsol=all)
```

$$y(x) = \frac{(-4x^4 + 192c_4x + 36x^2 + 192c_1 - 21) \cos(x)}{192} + \frac{(x^3 + (12c_3 - 3)x + 12c_2) \sin(x)}{12}$$

✓ Solution by Mathematica

Time used: 0.138 (sec). Leaf size: 56

```
DSolve[y''''[x]+2*y''[x]+y[x]==x^2*Cos[x],y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{1}{12}(x^3 + 3(-1 + 4c_4)x + 12c_3) \sin(x) + \left(-\frac{x^4}{48} + \frac{3x^2}{16} + c_2x - \frac{5}{32} + c_1\right) \cos(x)$$

11.52 problem 52

11.52.1 Maple step by step solution 2822

Internal problem ID [11826]

Internal file name [OUTPUT/11835_Thursday_April_11_2024_08_52_43_PM_27972420/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 52.

ODE order: 4.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_high_order , _linear , _nonhomogeneous]]
```

$$y'''' + 16y = x e^{\sqrt{2}x} \sin(\sqrt{2}x) + e^{-\sqrt{2}x} \cos(\sqrt{2}x)$$

This is higher order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE And y_p is a particular solution to the nonhomogeneous ODE. y_h is the solution to

$$y'''' + 16y = 0$$

The characteristic equation is

$$\lambda^4 + 16 = 0$$

The roots of the above equation are

$$\lambda_1 = \sqrt{2} + i\sqrt{2}$$

$$\lambda_2 = -\sqrt{2} + i\sqrt{2}$$

$$\lambda_3 = -\sqrt{2} - i\sqrt{2}$$

$$\lambda_4 = \sqrt{2} - i\sqrt{2}$$

Therefore the homogeneous solution is

$$y_h(x) = e^{(\sqrt{2}-i\sqrt{2})x} c_1 + e^{(-\sqrt{2}+i\sqrt{2})x} c_2 + e^{(-\sqrt{2}-i\sqrt{2})x} c_3 + e^{(\sqrt{2}+i\sqrt{2})x} c_4$$

The fundamental set of solutions for the homogeneous solution are the following

$$y_1 = e^{(\sqrt{2}-i\sqrt{2})x}$$

$$y_2 = e^{(-\sqrt{2}+i\sqrt{2})x}$$

$$y_3 = e^{(-\sqrt{2}-i\sqrt{2})x}$$

$$y_4 = e^{(\sqrt{2}+i\sqrt{2})x}$$

Now the particular solution to the given ODE is found

$$y'''' + 16y = x e^{\sqrt{2}x} \sin(\sqrt{2}x) + e^{-\sqrt{2}x} \cos(\sqrt{2}x)$$

Let the particular solution be

$$y_p = U_1 y_1 + U_2 y_2 + U_3 y_3 + U_4 y_4$$

Where y_i are the basis solutions found above for the homogeneous solution y_h and $U_i(x)$ are functions to be determined as follows

$$U_i = (-1)^{n-i} \int \frac{F(x)W_i(x)}{aW(x)} dx$$

Where $W(x)$ is the Wronskian and $W_i(x)$ is the Wronskian that results after deleting the last row and the i -th column of the determinant and n is the order of the ODE or equivalently, the number of basis solutions, and a is the coefficient of the leading derivative in the ODE, and $F(x)$ is the RHS of the ODE. Therefore, the first step is to find the Wronskian $W(x)$. This is given by

$$W(x) = \begin{vmatrix} y_1 & y_2 & y_3 & y_4 \\ y_1' & y_2' & y_3' & y_4' \\ y_1'' & y_2'' & y_3'' & y_4'' \\ y_1''' & y_2''' & y_3''' & y_4''' \end{vmatrix}$$

Substituting the fundamental set of solutions y_i found above in the Wronskian gives

$$W = \begin{bmatrix} e^{(1-i)\sqrt{2}x} & e^{(-1+i)\sqrt{2}x} & e^{(-1-i)\sqrt{2}x} & e^{(1+i)\sqrt{2}x} \\ (1-i)\sqrt{2}e^{(1-i)\sqrt{2}x} & (-1+i)\sqrt{2}e^{(-1+i)\sqrt{2}x} & (-1-i)\sqrt{2}e^{(-1-i)\sqrt{2}x} & (1+i)\sqrt{2}e^{(1+i)\sqrt{2}x} \\ -4ie^{(1-i)\sqrt{2}x} & -4ie^{(-1+i)\sqrt{2}x} & 4ie^{(-1-i)\sqrt{2}x} & 4ie^{(1+i)\sqrt{2}x} \\ (-4-4i)\sqrt{2}e^{(1-i)\sqrt{2}x} & (4+4i)\sqrt{2}e^{(-1+i)\sqrt{2}x} & (4-4i)\sqrt{2}e^{(-1-i)\sqrt{2}x} & (-4+4i)\sqrt{2}e^{(1+i)\sqrt{2}x} \end{bmatrix}$$

$$|W| = 1024 e^{(1-i)\sqrt{2}x} e^{(-1+i)\sqrt{2}x} e^{(-1-i)\sqrt{2}x} e^{(1+i)\sqrt{2}x}$$

The determinant simplifies to

$$|W| = 1024$$

Now we determine W_i for each U_i .

$$W_1(x) = \det \begin{bmatrix} e^{(-1+i)\sqrt{2}x} & e^{(-1-i)\sqrt{2}x} & e^{(1+i)\sqrt{2}x} \\ (-1+i)\sqrt{2}e^{(-1+i)\sqrt{2}x} & (-1-i)\sqrt{2}e^{(-1-i)\sqrt{2}x} & (1+i)\sqrt{2}e^{(1+i)\sqrt{2}x} \\ -4ie^{(-1+i)\sqrt{2}x} & 4ie^{(-1-i)\sqrt{2}x} & 4ie^{(1+i)\sqrt{2}x} \end{bmatrix}$$

$$= (16 - 16i)\sqrt{2}e^{(-1+i)\sqrt{2}x}$$

$$W_2(x) = \det \begin{bmatrix} e^{(1-i)\sqrt{2}x} & e^{(-1-i)\sqrt{2}x} & e^{(1+i)\sqrt{2}x} \\ (1-i)\sqrt{2}e^{(1-i)\sqrt{2}x} & (-1-i)\sqrt{2}e^{(-1-i)\sqrt{2}x} & (1+i)\sqrt{2}e^{(1+i)\sqrt{2}x} \\ -4ie^{(1-i)\sqrt{2}x} & 4ie^{(-1-i)\sqrt{2}x} & 4ie^{(1+i)\sqrt{2}x} \end{bmatrix}$$

$$= (16 - 16i)\sqrt{2}e^{(1-i)\sqrt{2}x}$$

$$W_3(x) = \det \begin{bmatrix} e^{(1-i)\sqrt{2}x} & e^{(-1+i)\sqrt{2}x} & e^{(1+i)\sqrt{2}x} \\ (1-i)\sqrt{2}e^{(1-i)\sqrt{2}x} & (-1+i)\sqrt{2}e^{(-1+i)\sqrt{2}x} & (1+i)\sqrt{2}e^{(1+i)\sqrt{2}x} \\ -4ie^{(1-i)\sqrt{2}x} & -4ie^{(-1+i)\sqrt{2}x} & 4ie^{(1+i)\sqrt{2}x} \end{bmatrix}$$

$$= (-16 - 16i)\sqrt{2}e^{(1+i)\sqrt{2}x}$$

$$W_4(x) = \det \begin{bmatrix} e^{(1-i)\sqrt{2}x} & e^{(-1+i)\sqrt{2}x} & e^{(-1-i)\sqrt{2}x} \\ (1-i)\sqrt{2}e^{(1-i)\sqrt{2}x} & (-1+i)\sqrt{2}e^{(-1+i)\sqrt{2}x} & (-1-i)\sqrt{2}e^{(-1-i)\sqrt{2}x} \\ -4ie^{(1-i)\sqrt{2}x} & -4ie^{(-1+i)\sqrt{2}x} & 4ie^{(-1-i)\sqrt{2}x} \end{bmatrix}$$

$$= (-16 - 16i)\sqrt{2}e^{(-1-i)\sqrt{2}x}$$

Now we are ready to evaluate each $U_i(x)$.

$$\begin{aligned}
U_1 &= (-1)^{4-1} \int \frac{F(x)W_1(x)}{aW(x)} dx \\
&= (-1)^3 \int \frac{\left(x e^{\sqrt{2}x} \sin(\sqrt{2}x) + e^{-\sqrt{2}x} \cos(\sqrt{2}x)\right) \left((16-16i)\sqrt{2}e^{(-1+i)\sqrt{2}x}\right)}{(1)(1024)} dx \\
&= - \int \frac{(16-16i) \left(x e^{\sqrt{2}x} \sin(\sqrt{2}x) + e^{-\sqrt{2}x} \cos(\sqrt{2}x)\right) \sqrt{2}e^{(-1+i)\sqrt{2}x}}{1024} dx \\
&= - \int \left(\left(\frac{1}{64} - \frac{i}{64}\right) \sqrt{2}e^{(-2+i)\sqrt{2}x} \left(x e^{2\sqrt{2}x} \sin(\sqrt{2}x) + \cos(\sqrt{2}x)\right)\right) dx \\
&= - \left(\int \left(\frac{1}{64} - \frac{i}{64}\right) \sqrt{2}e^{(-2+i)\sqrt{2}x} \left(x e^{2\sqrt{2}x} \sin(\sqrt{2}x) + \cos(\sqrt{2}x)\right) dx\right)
\end{aligned}$$

$$\begin{aligned}
U_2 &= (-1)^{4-2} \int \frac{F(x)W_2(x)}{aW(x)} dx \\
&= (-1)^2 \int \frac{\left(x e^{\sqrt{2}x} \sin(\sqrt{2}x) + e^{-\sqrt{2}x} \cos(\sqrt{2}x)\right) \left((16-16i)\sqrt{2}e^{(1-i)\sqrt{2}x}\right)}{(1)(1024)} dx \\
&= \int \frac{(16-16i) \left(x e^{\sqrt{2}x} \sin(\sqrt{2}x) + e^{-\sqrt{2}x} \cos(\sqrt{2}x)\right) \sqrt{2}e^{(1-i)\sqrt{2}x}}{1024} dx \\
&= \int \left(\left(\frac{1}{64} - \frac{i}{64}\right) \sqrt{2}e^{-i\sqrt{2}x} \left(x e^{2\sqrt{2}x} \sin(\sqrt{2}x) + \cos(\sqrt{2}x)\right)\right) dx \\
&= \int \left(\frac{1}{64} - \frac{i}{64}\right) \sqrt{2}e^{-i\sqrt{2}x} \left(x e^{2\sqrt{2}x} \sin(\sqrt{2}x) + \cos(\sqrt{2}x)\right) dx
\end{aligned}$$

$$\begin{aligned}
U_3 &= (-1)^{4-3} \int \frac{F(x)W_3(x)}{aW(x)} dx \\
&= (-1)^1 \int \frac{\left(x e^{\sqrt{2}x} \sin(\sqrt{2}x) + e^{-\sqrt{2}x} \cos(\sqrt{2}x)\right) \left((-16-16i)\sqrt{2}e^{(1+i)\sqrt{2}x}\right)}{(1)(1024)} dx \\
&= - \int \frac{(-16-16i) \left(x e^{\sqrt{2}x} \sin(\sqrt{2}x) + e^{-\sqrt{2}x} \cos(\sqrt{2}x)\right) \sqrt{2}e^{(1+i)\sqrt{2}x}}{1024} dx \\
&= - \int \left(\left(-\frac{1}{64} - \frac{i}{64}\right) \sqrt{2}e^{i\sqrt{2}x} \left(x e^{2\sqrt{2}x} \sin(\sqrt{2}x) + \cos(\sqrt{2}x)\right)\right) dx \\
&= \frac{\sqrt{2}x}{128} + \frac{i\sqrt{2}x}{128} + \frac{e^{2i\sqrt{2}x}}{256} - \frac{ie^{2i\sqrt{2}x}}{256} + \left(-\frac{1}{8192} - \frac{i}{8192}\right) \sqrt{2}(\sqrt{2} + i\sqrt{2}) \left(i\sqrt{2}e^{2i\sqrt{2}x} - \sqrt{2}e^{2i\sqrt{2}x} + \dots\right) \\
&= \frac{\sqrt{2}x}{128} + \frac{i\sqrt{2}x}{128} + \frac{e^{2i\sqrt{2}x}}{256} - \frac{ie^{2i\sqrt{2}x}}{256} + \left(-\frac{1}{8192} - \frac{i}{8192}\right) \sqrt{2}(\sqrt{2} + i\sqrt{2}) \left(i\sqrt{2}e^{2i\sqrt{2}x} - \sqrt{2}e^{2i\sqrt{2}x} + \dots\right)
\end{aligned}$$

$$\begin{aligned}
U_4 &= (-1)^{4-4} \int \frac{F(x)W_4(x)}{aW(x)} dx \\
&= (-1)^0 \int \frac{\left(x e^{\sqrt{2}x} \sin(\sqrt{2}x) + e^{-\sqrt{2}x} \cos(\sqrt{2}x)\right) \left((-16 - 16i) \sqrt{2} e^{(-1-i)\sqrt{2}x}\right)}{(1)(1024)} dx \\
&= \int \frac{(-16 - 16i) \left(x e^{\sqrt{2}x} \sin(\sqrt{2}x) + e^{-\sqrt{2}x} \cos(\sqrt{2}x)\right) \sqrt{2} e^{(-1-i)\sqrt{2}x}}{1024} dx \\
&= \int \left(\left(-\frac{1}{64} - \frac{i}{64}\right) \sqrt{2} e^{(-2-i)\sqrt{2}x} \left(x e^{2\sqrt{2}x} \sin(\sqrt{2}x) + \cos(\sqrt{2}x)\right)\right) dx \\
&= \int \left(-\frac{1}{64} - \frac{i}{64}\right) \sqrt{2} e^{(-2-i)\sqrt{2}x} \left(x e^{2\sqrt{2}x} \sin(\sqrt{2}x) + \cos(\sqrt{2}x)\right) dx
\end{aligned}$$

Now that all the U_i functions have been determined, the particular solution is found from

$$y_p = U_1 y_1 + U_2 y_2 + U_3 y_3 + U_4 y_4$$

Hence

$$\begin{aligned}
y_p &= \left(-\left(\int \left(\frac{1}{64} - \frac{i}{64}\right) \sqrt{2} e^{(-2+i)\sqrt{2}x} \left(x e^{2\sqrt{2}x} \sin(\sqrt{2}x) + \cos(\sqrt{2}x)\right) dx\right)\right) \left(e^{(\sqrt{2}-i\sqrt{2})x}\right) \\
&+ \left(\int \left(\frac{1}{64} - \frac{i}{64}\right) \sqrt{2} e^{-i\sqrt{2}x} \left(x e^{2\sqrt{2}x} \sin(\sqrt{2}x) + \cos(\sqrt{2}x)\right) dx\right) \left(e^{(-\sqrt{2}+i\sqrt{2})x}\right) \\
&+ \left(\frac{\sqrt{2}x}{128} + \frac{i\sqrt{2}x}{128} + \frac{e^{2i\sqrt{2}x}}{256} - \frac{ie^{2i\sqrt{2}x}}{256} + \left(-\frac{1}{8192} - \frac{i}{8192}\right) \sqrt{2} (\sqrt{2} + i\sqrt{2}) \left(i\sqrt{2} e^{2i\sqrt{2}x} - \sqrt{2} e^{2i\sqrt{2}x}\right)\right) \\
&+ \left(\int \left(-\frac{1}{64} - \frac{i}{64}\right) \sqrt{2} e^{(-2-i)\sqrt{2}x} \left(x e^{2\sqrt{2}x} \sin(\sqrt{2}x) + \cos(\sqrt{2}x)\right) dx\right) \left(e^{(\sqrt{2}+i\sqrt{2})x}\right)
\end{aligned}$$

Therefore the particular solution is

$$y_p = \frac{e^{-\sqrt{2}x} \left((4\sqrt{2}x - 1 + i) \sin(\sqrt{2}x) + \cos(\sqrt{2}x) (4\sqrt{2}x + 7 + i)\right)}{256} - \frac{\left(\left(\sqrt{2}x^2 - 3x + \frac{7\sqrt{2}}{8}\right) \sin(\sqrt{2}x)\right)}{128}$$

Which simplifies to

$$y_p = \frac{e^{-\sqrt{2}x} \left((4\sqrt{2}x - 1 + i) \sin(\sqrt{2}x) + \cos(\sqrt{2}x) (4\sqrt{2}x + 7 + i)\right)}{256} - \frac{\left(\left(\sqrt{2}x^2 - 3x + \frac{7\sqrt{2}}{8}\right) \sin(\sqrt{2}x)\right)}{128}$$

Therefore the general solution is

$$y = y_h + y_p$$

$$\begin{aligned}
&= \left(e^{(\sqrt{2}-i\sqrt{2})x} c_1 + e^{(-\sqrt{2}+i\sqrt{2})x} c_2 + e^{(-\sqrt{2}-i\sqrt{2})x} c_3 + e^{(\sqrt{2}+i\sqrt{2})x} c_4 \right) \\
&+ \left(\frac{e^{-\sqrt{2}x} \left((4\sqrt{2}x - 1 + i) \sin(\sqrt{2}x) + \cos(\sqrt{2}x) (4\sqrt{2}x + 7 + i) \right)}{256} \right. \\
&\quad \left. - \frac{\left(\left(\sqrt{2}x^2 - 3x + \frac{7\sqrt{2}}{8} \right) \sin(\sqrt{2}x) + \cos(\sqrt{2}x) \sqrt{2} \left(x^2 - \frac{3}{8} \right) \right) e^{\sqrt{2}x}}{128} \right)
\end{aligned}$$

Which simplifies to

$$\begin{aligned}
y &= e^{(1-i)\sqrt{2}x} c_1 + e^{(-1+i)\sqrt{2}x} c_2 + e^{(-1-i)\sqrt{2}x} c_3 + e^{(1+i)\sqrt{2}x} c_4 \\
&+ \frac{e^{-\sqrt{2}x} \left((4\sqrt{2}x - 1 + i) \sin(\sqrt{2}x) + \cos(\sqrt{2}x) (4\sqrt{2}x + 7 + i) \right)}{256} \\
&- \frac{\left(\left(\sqrt{2}x^2 - 3x + \frac{7\sqrt{2}}{8} \right) \sin(\sqrt{2}x) + \cos(\sqrt{2}x) \sqrt{2} \left(x^2 - \frac{3}{8} \right) \right) e^{\sqrt{2}x}}{128}
\end{aligned}$$

Summary

The solution(s) found are the following

$$\begin{aligned}
y &= e^{(1-i)\sqrt{2}x} c_1 + e^{(-1+i)\sqrt{2}x} c_2 + e^{(-1-i)\sqrt{2}x} c_3 + e^{(1+i)\sqrt{2}x} c_4 \\
&+ \frac{e^{-\sqrt{2}x} \left((4\sqrt{2}x - 1 + i) \sin(\sqrt{2}x) + \cos(\sqrt{2}x) (4\sqrt{2}x + 7 + i) \right)}{256} \\
&- \frac{\left(\left(\sqrt{2}x^2 - 3x + \frac{7\sqrt{2}}{8} \right) \sin(\sqrt{2}x) + \cos(\sqrt{2}x) \sqrt{2} \left(x^2 - \frac{3}{8} \right) \right) e^{\sqrt{2}x}}{128}
\end{aligned} \tag{1}$$

Verification of solutions

$$\begin{aligned}
y &= e^{(1-i)\sqrt{2}x} c_1 + e^{(-1+i)\sqrt{2}x} c_2 + e^{(-1-i)\sqrt{2}x} c_3 + e^{(1+i)\sqrt{2}x} c_4 \\
&+ \frac{e^{-\sqrt{2}x} \left((4\sqrt{2}x - 1 + i) \sin(\sqrt{2}x) + \cos(\sqrt{2}x) (4\sqrt{2}x + 7 + i) \right)}{256} \\
&- \frac{\left(\left(\sqrt{2}x^2 - 3x + \frac{7\sqrt{2}}{8} \right) \sin(\sqrt{2}x) + \cos(\sqrt{2}x) \sqrt{2} \left(x^2 - \frac{3}{8} \right) \right) e^{\sqrt{2}x}}{128}
\end{aligned}$$

Verified OK.

11.52.1 Maple step by step solution

Let's solve

$$y'''' + 16y = x e^{\sqrt{2}x} \sin(\sqrt{2}x) + e^{-\sqrt{2}x} \cos(\sqrt{2}x)$$

- Highest derivative means the order of the ODE is 4

$$y''''$$

- Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(x)$

$$y_1(x) = y$$

- Define new variable $y_2(x)$

$$y_2(x) = y'$$

- Define new variable $y_3(x)$

$$y_3(x) = y''$$

- Define new variable $y_4(x)$

$$y_4(x) = y'''$$

- Isolate for $y_4'(x)$ using original ODE

$$y_4'(x) = x e^{\sqrt{2}x} \sin(\sqrt{2}x) + e^{-\sqrt{2}x} \cos(\sqrt{2}x) - 16y_1(x)$$

Convert linear ODE into a system of first order ODEs

$$\left[y_2(x) = y_1'(x), y_3(x) = y_2'(x), y_4(x) = y_3'(x), y_4'(x) = x e^{\sqrt{2}x} \sin(\sqrt{2}x) + e^{-\sqrt{2}x} \cos(\sqrt{2}x) - 16y_1(x) \right]$$

- Define vector

$$\vec{y}(x) = \begin{bmatrix} y_1(x) \\ y_2(x) \\ y_3(x) \\ y_4(x) \end{bmatrix}$$

- System to solve

$$\vec{y}'(x) = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -16 & 0 & 0 & 0 \end{bmatrix} \cdot \vec{y}(x) + \begin{bmatrix} 0 \\ 0 \\ 0 \\ x e^{\sqrt{2}x} \sin(\sqrt{2}x) + e^{-\sqrt{2}x} \cos(\sqrt{2}x) \end{bmatrix}$$

- Define the forcing function

$$\vec{f}(x) = \begin{bmatrix} 0 \\ 0 \\ 0 \\ x e^{\sqrt{2}x} \sin(\sqrt{2}x) + e^{-\sqrt{2}x} \cos(\sqrt{2}x) \end{bmatrix}$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -16 & 0 & 0 & 0 \end{bmatrix}$$

- Rewrite the system as

$$\vec{y}'(x) = A \cdot \vec{y}(x) + \vec{f}$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[\begin{array}{c} -\sqrt{2} - I\sqrt{2}, \\ \frac{1}{(-\sqrt{2}-I\sqrt{2})^3} \\ \frac{1}{(-\sqrt{2}-I\sqrt{2})^2} \\ \frac{1}{-\sqrt{2}-I\sqrt{2}} \\ 1 \end{array} \right] \right], \left[\begin{array}{c} -\sqrt{2} + I\sqrt{2}, \\ \frac{1}{(-\sqrt{2}+I\sqrt{2})^3} \\ \frac{1}{(-\sqrt{2}+I\sqrt{2})^2} \\ \frac{1}{-\sqrt{2}+I\sqrt{2}} \\ 1 \end{array} \right] \right], \left[\begin{array}{c} \sqrt{2} - I\sqrt{2}, \\ \frac{1}{(\sqrt{2}-I\sqrt{2})^3} \\ \frac{1}{(\sqrt{2}-I\sqrt{2})^2} \\ \frac{1}{\sqrt{2}-I\sqrt{2}} \\ 1 \end{array} \right] \right]$$

- Consider complex eigenpair, complex conjugate eigenvalue can be ignored

$$\left[\begin{array}{c} -\sqrt{2} - I\sqrt{2}, \\ \frac{1}{(-\sqrt{2}-I\sqrt{2})^3} \\ \frac{1}{(-\sqrt{2}-I\sqrt{2})^2} \\ \frac{1}{-\sqrt{2}-I\sqrt{2}} \\ 1 \end{array} \right]$$

- Solution from eigenpair

$$e^{(-\sqrt{2}-I\sqrt{2})x} \cdot \begin{bmatrix} \frac{1}{(-\sqrt{2}-I\sqrt{2})^3} \\ \frac{1}{(-\sqrt{2}-I\sqrt{2})^2} \\ \frac{1}{-\sqrt{2}-I\sqrt{2}} \\ 1 \end{bmatrix}$$

- Use Euler identity to write solution in terms of sin and cos

$$e^{-\sqrt{2}x} \cdot (\cos(\sqrt{2}x) - I \sin(\sqrt{2}x)) \cdot \begin{bmatrix} \frac{1}{(-\sqrt{2}-I\sqrt{2})^3} \\ \frac{1}{(-\sqrt{2}-I\sqrt{2})^2} \\ \frac{1}{-\sqrt{2}-I\sqrt{2}} \\ 1 \end{bmatrix}$$

- Simplify expression

$$e^{-\sqrt{2}x} \cdot \begin{bmatrix} \frac{\cos(\sqrt{2}x) - I \sin(\sqrt{2}x)}{(-\sqrt{2}-I\sqrt{2})^3} \\ \frac{\cos(\sqrt{2}x) - I \sin(\sqrt{2}x)}{(-\sqrt{2}-I\sqrt{2})^2} \\ \frac{\cos(\sqrt{2}x) - I \sin(\sqrt{2}x)}{-\sqrt{2}-I\sqrt{2}} \\ \cos(\sqrt{2}x) - I \sin(\sqrt{2}x) \end{bmatrix}$$

- Both real and imaginary parts are solutions to the homogeneous system

$$\vec{y}_1(x) = e^{-\sqrt{2}x} \cdot \begin{bmatrix} \frac{\cos(\sqrt{2}x)\sqrt{2}}{16} + \frac{\sin(\sqrt{2}x)\sqrt{2}}{16} \\ -\frac{\sin(\sqrt{2}x)}{4} \\ -\frac{\cos(\sqrt{2}x)\sqrt{2}}{4} + \frac{\sin(\sqrt{2}x)\sqrt{2}}{4} \\ \cos(\sqrt{2}x) \end{bmatrix}, \vec{y}_2(x) = e^{-\sqrt{2}x} \cdot \begin{bmatrix} \frac{\cos(\sqrt{2}x)\sqrt{2}}{16} - \frac{\sin(\sqrt{2}x)\sqrt{2}}{16} \\ -\frac{\cos(\sqrt{2}x)}{4} \\ \frac{\cos(\sqrt{2}x)\sqrt{2}}{4} + \frac{\sin(\sqrt{2}x)\sqrt{2}}{4} \\ -\sin(\sqrt{2}x) \end{bmatrix}$$

- Consider complex eigenpair, complex conjugate eigenvalue can be ignored

$$\left[\sqrt{2} - I\sqrt{2}, \begin{bmatrix} \frac{1}{(\sqrt{2}-I\sqrt{2})^3} \\ \frac{1}{(\sqrt{2}-I\sqrt{2})^2} \\ \frac{1}{\sqrt{2}-I\sqrt{2}} \\ 1 \end{bmatrix} \right]$$

- Solution from eigenpair

$$e^{(\sqrt{2}-I\sqrt{2})x} \cdot \begin{bmatrix} \frac{1}{(\sqrt{2}-I\sqrt{2})^3} \\ \frac{1}{(\sqrt{2}-I\sqrt{2})^2} \\ \frac{1}{\sqrt{2}-I\sqrt{2}} \\ 1 \end{bmatrix}$$

- Use Euler identity to write solution in terms of sin and cos

$$e^{\sqrt{2}x} \cdot (\cos(\sqrt{2}x) - I \sin(\sqrt{2}x)) \cdot \begin{bmatrix} \frac{1}{(\sqrt{2}-I\sqrt{2})^3} \\ \frac{1}{(\sqrt{2}-I\sqrt{2})^2} \\ \frac{1}{\sqrt{2}-I\sqrt{2}} \\ 1 \end{bmatrix}$$

- Simplify expression

$$e^{\sqrt{2}x} \cdot \begin{bmatrix} \frac{\cos(\sqrt{2}x) - I \sin(\sqrt{2}x)}{(\sqrt{2}-I\sqrt{2})^3} \\ \frac{\cos(\sqrt{2}x) - I \sin(\sqrt{2}x)}{(\sqrt{2}-I\sqrt{2})^2} \\ \frac{\cos(\sqrt{2}x) - I \sin(\sqrt{2}x)}{\sqrt{2}-I\sqrt{2}} \\ \cos(\sqrt{2}x) - I \sin(\sqrt{2}x) \end{bmatrix}$$

- Both real and imaginary parts are solutions to the homogeneous system

$$\vec{y}_3(x) = e^{\sqrt{2}x} \cdot \begin{bmatrix} -\frac{\cos(\sqrt{2}x)\sqrt{2}}{16} + \frac{\sin(\sqrt{2}x)\sqrt{2}}{16} \\ \frac{\sin(\sqrt{2}x)}{4} \\ \frac{\cos(\sqrt{2}x)\sqrt{2}}{4} + \frac{\sin(\sqrt{2}x)\sqrt{2}}{4} \\ \cos(\sqrt{2}x) \end{bmatrix}, \vec{y}_4(x) = e^{\sqrt{2}x} \cdot \begin{bmatrix} \frac{\cos(\sqrt{2}x)\sqrt{2}}{16} + \frac{\sin(\sqrt{2}x)\sqrt{2}}{16} \\ \frac{\cos(\sqrt{2}x)}{4} \\ \frac{\cos(\sqrt{2}x)\sqrt{2}}{4} - \frac{\sin(\sqrt{2}x)\sqrt{2}}{4} \\ -\sin(\sqrt{2}x) \end{bmatrix}$$

- General solution of the system of ODEs can be written in terms of the particular solution $\vec{y}_p(x)$

$$\vec{y}(x) = c_1\vec{y}_1(x) + c_2\vec{y}_2(x) + c_3\vec{y}_3(x) + c_4\vec{y}_4(x) + \vec{y}_p(x)$$

□

Fundamental matrix

- Let $\phi(x)$ be the matrix whose columns are the independent solutions of the homogeneous system

$$\phi(x) = \begin{bmatrix} e^{-\sqrt{2}x} \left(\frac{\cos(\sqrt{2}x)\sqrt{2}}{16} + \frac{\sin(\sqrt{2}x)\sqrt{2}}{16} \right) & e^{-\sqrt{2}x} \left(\frac{\cos(\sqrt{2}x)\sqrt{2}}{16} - \frac{\sin(\sqrt{2}x)\sqrt{2}}{16} \right) & e^{\sqrt{2}x} \left(-\frac{\cos(\sqrt{2}x)\sqrt{2}}{4} + \frac{\sin(\sqrt{2}x)\sqrt{2}}{4} \right) \\ -\frac{e^{-\sqrt{2}x} \sin(\sqrt{2}x)}{4} & -\frac{e^{-\sqrt{2}x} \cos(\sqrt{2}x)}{4} & \frac{e^{\sqrt{2}x} \sin(\sqrt{2}x)}{4} \\ e^{-\sqrt{2}x} \left(-\frac{\cos(\sqrt{2}x)\sqrt{2}}{4} + \frac{\sin(\sqrt{2}x)\sqrt{2}}{4} \right) & e^{-\sqrt{2}x} \left(\frac{\cos(\sqrt{2}x)\sqrt{2}}{4} + \frac{\sin(\sqrt{2}x)\sqrt{2}}{4} \right) & e^{\sqrt{2}x} \left(\frac{\cos(\sqrt{2}x)\sqrt{2}}{4} + \frac{\sin(\sqrt{2}x)\sqrt{2}}{4} \right) \\ e^{-\sqrt{2}x} \cos(\sqrt{2}x) & -e^{-\sqrt{2}x} \sin(\sqrt{2}x) & e^{\sqrt{2}x} \cos(\sqrt{2}x) \end{bmatrix}$$

- The fundamental matrix, $\Phi(x)$ is a normalized version of $\phi(x)$ satisfying $\Phi(0) = I$ where I is the identity matrix

$$\Phi(x) = \phi(x) \cdot \frac{1}{\phi(0)}$$

- Substitute the value of $\phi(x)$ and $\phi(0)$

$$\Phi(x) = \begin{bmatrix} e^{-\sqrt{2}x} \left(\frac{\cos(\sqrt{2}x)\sqrt{2}}{16} + \frac{\sin(\sqrt{2}x)\sqrt{2}}{16} \right) & e^{-\sqrt{2}x} \left(\frac{\cos(\sqrt{2}x)\sqrt{2}}{16} - \frac{\sin(\sqrt{2}x)\sqrt{2}}{16} \right) & e^{\sqrt{2}x} \left(-\frac{\cos(\sqrt{2}x)\sqrt{2}}{4} + \frac{\sin(\sqrt{2}x)\sqrt{2}}{4} \right) \\ -\frac{e^{-\sqrt{2}x} \sin(\sqrt{2}x)}{4} & -\frac{e^{-\sqrt{2}x} \cos(\sqrt{2}x)}{4} & \frac{e^{\sqrt{2}x} \sin(\sqrt{2}x)}{4} \\ e^{-\sqrt{2}x} \left(-\frac{\cos(\sqrt{2}x)\sqrt{2}}{4} + \frac{\sin(\sqrt{2}x)\sqrt{2}}{4} \right) & e^{-\sqrt{2}x} \left(\frac{\cos(\sqrt{2}x)\sqrt{2}}{4} + \frac{\sin(\sqrt{2}x)\sqrt{2}}{4} \right) & e^{\sqrt{2}x} \left(\frac{\cos(\sqrt{2}x)\sqrt{2}}{4} + \frac{\sin(\sqrt{2}x)\sqrt{2}}{4} \right) \\ e^{-\sqrt{2}x} \cos(\sqrt{2}x) & -e^{-\sqrt{2}x} \sin(\sqrt{2}x) & e^{\sqrt{2}x} \cos(\sqrt{2}x) \end{bmatrix}$$

- Evaluate and simplify to get the fundamental matrix

$$\Phi(x) = \begin{bmatrix} \frac{\cos(\sqrt{2}x)(e^{-\sqrt{2}x} + e^{\sqrt{2}x})}{2} & \frac{\sqrt{2}(e^{-\sqrt{2}x} - e^{\sqrt{2}x})}{2} \\ \frac{((- \cos(\sqrt{2}x) - \sin(\sqrt{2}x))e^{-\sqrt{2}x} + e^{\sqrt{2}x}(-\sin(\sqrt{2}x) + \cos(\sqrt{2}x)))\sqrt{2}}{2} & \frac{\sqrt{2}(e^{-\sqrt{2}x} + e^{\sqrt{2}x})}{2} \\ -2\sin(\sqrt{2}x)(-e^{-\sqrt{2}x} + e^{\sqrt{2}x}) & \frac{\sqrt{2}(e^{-\sqrt{2}x} - e^{\sqrt{2}x})}{2} \\ -2\sqrt{2}(e^{-\sqrt{2}x}(-\cos(\sqrt{2}x) + \sin(\sqrt{2}x)) + e^{\sqrt{2}x}(\cos(\sqrt{2}x) + \sin(\sqrt{2}x))) & \frac{\sqrt{2}(e^{-\sqrt{2}x} + e^{\sqrt{2}x})}{2} \end{bmatrix}$$

- Find a particular solution of the system of ODEs using variation of parameters
- Let the particular solution be the fundamental matrix multiplied by $\vec{v}(x)$ and solve for $\vec{v}(x)$

$$\vec{y}_p(x) = \Phi(x) \cdot \vec{v}(x)$$
 - Take the derivative of the particular solution
$$\vec{y}'_p(x) = \Phi'(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x)$$
 - Substitute particular solution and its derivative into the system of ODEs
$$\Phi'(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x) = A \cdot \Phi(x) \cdot \vec{v}(x) + \vec{f}(x)$$
 - The fundamental matrix has columns that are solutions to the homogeneous system so its derivative is $A \cdot \Phi(x)$

$$A \cdot \Phi(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x) = A \cdot \Phi(x) \cdot \vec{v}(x) + \vec{f}(x)$$
 - Cancel like terms
$$\Phi(x) \cdot \vec{v}'(x) = \vec{f}(x)$$
 - Multiply by the inverse of the fundamental matrix
$$\vec{v}'(x) = \frac{1}{\Phi(x)} \cdot \vec{f}(x)$$
 - Integrate to solve for $\vec{v}(x)$

$$\vec{v}(x) = \int_0^x \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds$$
 - Plug $\vec{v}(x)$ into the equation for the particular solution
$$\vec{y}_p(x) = \Phi(x) \cdot \left(\int_0^x \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds \right)$$
 - Plug in the fundamental matrix and the forcing function and compute

$$\vec{y}_p(x) = \begin{bmatrix} \frac{\left(\left(8+(16x+1)\sqrt{2}\right)\sin(\sqrt{2}x)+16\cos(\sqrt{2}x)\left(1+(x-\frac{3}{16})\sqrt{2}\right)\right)e^{-\sqrt{2}x}}{1024} - \frac{\left(\left(\sqrt{2}x^2-3x+\frac{7\sqrt{2}}{8}-1\right)\sin(\sqrt{2}x)+\cos(\sqrt{2}x)\right)e^{\sqrt{2}x}}{128} \\ - \frac{e^{-\sqrt{2}x}\left(\left(\left(\frac{1}{4}+\frac{(1-x)\sqrt{2}}{4}+x^2\right)\cos(\sqrt{2}x)-\frac{\left(\frac{1}{2}+(x+3)\sqrt{2}\right)\sin(\sqrt{2}x)}{4}\right)\right)}{32} + \frac{\left(\left(-\sqrt{2}-1\right)\cos(\sqrt{2}x)\right)}{4} + 2\left(x+\frac{1}{2}\right) \\ \frac{\left(\left(-8+(-16x-1)\sqrt{2}\right)\cos(\sqrt{2}x)+16\sin(\sqrt{2}x)\left(-1+(x-\frac{3}{16})\sqrt{2}\right)\right)e^{-\sqrt{2}x}}{256} - \frac{\left(\left(\sqrt{2}x^2+x-\frac{\sqrt{2}}{8}-1\right)\cos(\sqrt{2}x)-\left(\frac{1}{2}+(x+3)\sqrt{2}\right)\sin(\sqrt{2}x)\right)e^{\sqrt{2}x}}{32} \\ \frac{\left(\left(16x-6\sqrt{2}-1\right)\cos(\sqrt{2}x)+\left(10\sqrt{2}+2\right)\sin(\sqrt{2}x)\right)e^{-\sqrt{2}x}}{64} + \frac{e^{\sqrt{2}x}\left(\left(\frac{1}{8}+\left(-\frac{3x}{4}+\frac{3}{4}\right)\sqrt{2}\right)\cos(\sqrt{2}x)+\left(\frac{3x}{4}+\frac{1}{2}\right)\sin(\sqrt{2}x)\right)}{8} \end{bmatrix}$$

- Plug particular solution back into general solution

$$\vec{y}(x) = c_1\vec{y}_1(x) + c_2\vec{y}_2(x) + c_3\vec{y}_3(x) + c_4\vec{y}_4(x) + \begin{bmatrix} \frac{\left(\left(8+(16x+1)\sqrt{2}\right)\sin(\sqrt{2}x)+16\cos(\sqrt{2}x)\left(1+(x-\frac{3}{16})\sqrt{2}\right)\right)e^{-\sqrt{2}x}}{1024} - \frac{\left(\left(\sqrt{2}x^2-3x+\frac{7\sqrt{2}}{8}-1\right)\sin(\sqrt{2}x)+\cos(\sqrt{2}x)\right)e^{\sqrt{2}x}}{128} \\ - \frac{e^{-\sqrt{2}x}\left(\left(\left(\frac{1}{4}+\frac{(1-x)\sqrt{2}}{4}+x^2\right)\cos(\sqrt{2}x)-\frac{\left(\frac{1}{2}+(x+3)\sqrt{2}\right)\sin(\sqrt{2}x)}{4}\right)\right)}{32} + \frac{\left(\left(-\sqrt{2}-1\right)\cos(\sqrt{2}x)\right)}{4} + 2\left(x+\frac{1}{2}\right) \\ \frac{\left(\left(-8+(-16x-1)\sqrt{2}\right)\cos(\sqrt{2}x)+16\sin(\sqrt{2}x)\left(-1+(x-\frac{3}{16})\sqrt{2}\right)\right)e^{-\sqrt{2}x}}{256} - \frac{\left(\left(\sqrt{2}x^2+x-\frac{\sqrt{2}}{8}-1\right)\cos(\sqrt{2}x)-\left(\frac{1}{2}+(x+3)\sqrt{2}\right)\sin(\sqrt{2}x)\right)e^{\sqrt{2}x}}{32} \\ \frac{\left(\left(16x-6\sqrt{2}-1\right)\cos(\sqrt{2}x)+\left(10\sqrt{2}+2\right)\sin(\sqrt{2}x)\right)e^{-\sqrt{2}x}}{64} + \frac{e^{\sqrt{2}x}\left(\left(\frac{1}{8}+\left(-\frac{3x}{4}+\frac{3}{4}\right)\sqrt{2}\right)\cos(\sqrt{2}x)+\left(\frac{3x}{4}+\frac{1}{2}\right)\sin(\sqrt{2}x)\right)}{8} \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y = \frac{\left(\left(8+(16x+64c_1-64c_2+1)\sqrt{2}\right)\sin(\sqrt{2}x)+16\left(1+(x+4c_1+4c_2-\frac{3}{16})\sqrt{2}\right)\cos(\sqrt{2}x)\right)e^{-\sqrt{2}x}}{1024} - \frac{e^{\sqrt{2}x}\left(\left(x^2-8c_3-8c_4+\frac{7}{8}\right)\sqrt{2}\sin(\sqrt{2}x)+\left(x^2-8c_3-8c_4+\frac{7}{8}\right)\cos(\sqrt{2}x)\right)}{128}$$

Maple trace

```

`Methods for high order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 4; linear nonhomogeneous with symmetry [0,1]
trying high order linear exact nonhomogeneous
trying differential order: 4; missing the dependent variable
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 108

```
dsolve(diff(y(x), x$4)+16*y(x)=x*exp(sqrt(2)*x)*sin(sqrt(2)*x)+exp(-sqrt(2)*x)*cos(sqrt(2)*x)
```

$$y(x) = \frac{\left((2x\sqrt{2} + 128c_3 + 3) \cos(x\sqrt{2}) + 2 \sin(x\sqrt{2}) (x\sqrt{2} + 64c_4) \right) e^{-x\sqrt{2}}}{128} - \frac{\left(\left(x^2\sqrt{2} - 128c_1 - \frac{5\sqrt{2}}{8} \right) \cos(x\sqrt{2}) + \sin(x\sqrt{2}) \left(x^2\sqrt{2} - 3x - 128c_2 + \frac{5\sqrt{2}}{8} \right) \right) e^{x\sqrt{2}}}{128}$$

✓ Solution by Mathematica

Time used: 2.857 (sec). Leaf size: 140

```
DSolve[y''''[x]+16*y[x]==x*Exp[Sqrt[2]*x]*Sin[Sqrt[2]*x]+Exp[-Sqrt[2]*x]*Cos[Sqrt[2]*x], y[x]
```

$$y(x) \rightarrow \frac{e^{-\sqrt{2}x} \left(\left(e^{2\sqrt{2}x} (-8\sqrt{2}x^2 + 5\sqrt{2} + 1024c_1) + 8(2\sqrt{2}x + 3 + 128c_2) \right) \cos(\sqrt{2}x) - \left(e^{2\sqrt{2}x} (8\sqrt{2}x^2 - 24x \right. \right.}{1024}$$

11.53 problem 53

11.53.1 Maple step by step solution 2835

Internal problem ID [11827]

Internal file name [OUTPUT/11836_Thursday_April_11_2024_08_52_46_PM_21129270/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 53.

ODE order: 4.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_high_order , _linear , _nonhomogeneous]]
```

$$y'''' + 3y'' - 4y = \cos(x)^2 - \cosh(x)$$

This is higher order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE And y_p is a particular solution to the nonhomogeneous ODE. y_h is the solution to

$$y'''' + 3y'' - 4y = 0$$

The characteristic equation is

$$\lambda^4 + 3\lambda^2 - 4 = 0$$

The roots of the above equation are

$$\lambda_1 = 2i$$

$$\lambda_2 = -2i$$

$$\lambda_3 = 1$$

$$\lambda_4 = -1$$

Therefore the homogeneous solution is

$$y_h(x) = c_1 e^{-x} + c_2 e^x + e^{2ix} c_3 + e^{-2ix} c_4$$

The fundamental set of solutions for the homogeneous solution are the following

$$\begin{aligned} y_1 &= e^{-x} \\ y_2 &= e^x \\ y_3 &= e^{2ix} \\ y_4 &= e^{-2ix} \end{aligned}$$

Now the particular solution to the given ODE is found

$$y'''' + 3y'' - 4y = \cos(x)^2 - \cosh(x)$$

Let the particular solution be

$$y_p = U_1 y_1 + U_2 y_2 + U_3 y_3 + U_4 y_4$$

Where y_i are the basis solutions found above for the homogeneous solution y_h and $U_i(x)$ are functions to be determined as follows

$$U_i = (-1)^{n-i} \int \frac{F(x)W_i(x)}{aW(x)} dx$$

Where $W(x)$ is the Wronskian and $W_i(x)$ is the Wronskian that results after deleting the last row and the i -th column of the determinant and n is the order of the ODE or equivalently, the number of basis solutions, and a is the coefficient of the leading derivative in the ODE, and $F(x)$ is the RHS of the ODE. Therefore, the first step is to find the Wronskian $W(x)$. This is given by

$$W(x) = \begin{vmatrix} y_1 & y_2 & y_3 & y_4 \\ y_1' & y_2' & y_3' & y_4' \\ y_1'' & y_2'' & y_3'' & y_4'' \\ y_1''' & y_2''' & y_3''' & y_4''' \end{vmatrix}$$

Substituting the fundamental set of solutions y_i found above in the Wronskian gives

$$W = \begin{bmatrix} e^{-x} & e^x & e^{2ix} & e^{-2ix} \\ -e^{-x} & e^x & 2ie^{2ix} & -2ie^{-2ix} \\ e^{-x} & e^x & -4e^{2ix} & -4e^{-2ix} \\ -e^{-x} & e^x & -8ie^{2ix} & 8ie^{-2ix} \end{bmatrix}$$

$$|W| = -200ie^{-x}e^xe^{2ix}e^{-2ix}$$

The determinant simplifies to

$$|W| = -200i$$

Now we determine W_i for each U_i .

$$\begin{aligned} W_1(x) &= \det \begin{bmatrix} e^x & e^{2ix} & e^{-2ix} \\ e^x & 2ie^{2ix} & -2ie^{-2ix} \\ e^x & -4e^{2ix} & -4e^{-2ix} \end{bmatrix} \\ &= -20ie^x \end{aligned}$$

$$\begin{aligned} W_2(x) &= \det \begin{bmatrix} e^{-x} & e^{2ix} & e^{-2ix} \\ -e^{-x} & 2ie^{2ix} & -2ie^{-2ix} \\ e^{-x} & -4e^{2ix} & -4e^{-2ix} \end{bmatrix} \\ &= -20ie^{-x} \end{aligned}$$

$$\begin{aligned} W_3(x) &= \det \begin{bmatrix} e^{-x} & e^x & e^{-2ix} \\ -e^{-x} & e^x & -2ie^{-2ix} \\ e^{-x} & e^x & -4e^{-2ix} \end{bmatrix} \\ &= -10e^{-2ix} \end{aligned}$$

$$\begin{aligned} W_4(x) &= \det \begin{bmatrix} e^{-x} & e^x & e^{2ix} \\ -e^{-x} & e^x & 2ie^{2ix} \\ e^{-x} & e^x & -4e^{2ix} \end{bmatrix} \\ &= -10e^{2ix} \end{aligned}$$

Now we are ready to evaluate each $U_i(x)$.

$$\begin{aligned} U_1 &= (-1)^{4-1} \int \frac{F(x)W_1(x)}{aW(x)} dx \\ &= (-1)^3 \int \frac{(\cos(x)^2 - \cosh(x))(-20ie^x)}{(1)(-200i)} dx \\ &= - \int \frac{-20i(\cos(x)^2 - \cosh(x))e^x}{-200i} dx \\ &= - \int \left(\frac{(\cos(x)^2 - \cosh(x))e^x}{10} \right) dx \\ &= \frac{x}{20} - \frac{(\cos(x) + 2\sin(x))e^x \cos(x)}{50} - \frac{e^x}{25} + \frac{e^{2x}}{40} \end{aligned}$$

$$\begin{aligned}
U_2 &= (-1)^{4-2} \int \frac{F(x)W_2(x)}{aW(x)} dx \\
&= (-1)^2 \int \frac{(\cos(x)^2 - \cosh(x))(-20ie^{-x})}{(1)(-200i)} dx \\
&= \int \frac{-20i(\cos(x)^2 - \cosh(x))e^{-x}}{-200i} dx \\
&= \int \left(\frac{(\cos(x)^2 - \cosh(x))e^{-x}}{10} \right) dx \\
&= \frac{(-\cos(x) + 2\sin(x))e^{-x}\cos(x)}{50} - \frac{e^{-x}}{25} - \frac{x}{20} + \frac{e^{-2x}}{40}
\end{aligned}$$

$$\begin{aligned}
U_3 &= (-1)^{4-3} \int \frac{F(x)W_3(x)}{aW(x)} dx \\
&= (-1)^1 \int \frac{(\cos(x)^2 - \cosh(x))(-10e^{-2ix})}{(1)(-200i)} dx \\
&= - \int \frac{-10(\cos(x)^2 - \cosh(x))e^{-2ix}}{-200i} dx \\
&= - \int \left(-\frac{i(\cos(x)^2 - \cosh(x))e^{-2ix}}{20} \right) dx \\
&= \frac{ie^{(-1-2i)x}}{200} - \frac{e^{-2ix}}{80} + \frac{e^{(1-2i)x}}{100} + \frac{e^{(-1-2i)x}}{100} - \frac{ie^{(1-2i)x}}{200} + \frac{ix}{80} - \frac{e^{-4ix}}{320}
\end{aligned}$$

$$\begin{aligned}
U_4 &= (-1)^{4-4} \int \frac{F(x)W_4(x)}{aW(x)} dx \\
&= (-1)^0 \int \frac{(\cos(x)^2 - \cosh(x))(-10e^{2ix})}{(1)(-200i)} dx \\
&= \int \frac{-10(\cos(x)^2 - \cosh(x))e^{2ix}}{-200i} dx \\
&= \int \left(-\frac{i(\cos(x)^2 - \cosh(x))e^{2ix}}{20} \right) dx \\
&= \int -\frac{i(\cos(x)^2 - \cosh(x))e^{2ix}}{20} dx
\end{aligned}$$

Now that all the U_i functions have been determined, the particular solution is found from

$$y_p = U_1y_1 + U_2y_2 + U_3y_3 + U_4y_4$$

Hence

$$\begin{aligned}
 y_p &= \left(\frac{x}{20} - \frac{(\cos(x) + 2\sin(x))e^x \cos(x)}{50} - \frac{e^x}{25} + \frac{e^{2x}}{40} \right) (e^{-x}) \\
 &+ \left(\frac{(-\cos(x) + 2\sin(x))e^{-x} \cos(x)}{50} - \frac{e^{-x}}{25} - \frac{x}{20} + \frac{e^{-2x}}{40} \right) (e^x) \\
 &+ \left(\frac{ie^{(-1-2i)x}}{200} - \frac{e^{-2ix}}{80} + \frac{e^{(1-2i)x}}{100} + \frac{e^{(-1-2i)x}}{100} - \frac{ie^{(1-2i)x}}{200} + \frac{ix}{80} - \frac{e^{-4ix}}{320} \right) (e^{2ix}) \\
 &+ \left(\int -\frac{i(\cos(x)^2 - \cosh(x))e^{2ix}}{20} dx \right) (e^{-2ix})
 \end{aligned}$$

Therefore the particular solution is

$$y_p = -\frac{1}{8} + \frac{(9+10x)e^{-x}}{200} - \frac{\sin(2x)(8x+i)}{320} - \frac{37\cos(2x)}{1600} + \frac{(9-10x)e^x}{200}$$

Which simplifies to

$$y_p = -\frac{1}{8} + \frac{(9+10x)e^{-x}}{200} - \frac{\sin(2x)(8x+i)}{320} - \frac{37\cos(2x)}{1600} + \frac{(9-10x)e^x}{200}$$

Therefore the general solution is

$$\begin{aligned}
 y &= y_h + y_p \\
 &= (c_1 e^{-x} + c_2 e^x + e^{2ix} c_3 + e^{-2ix} c_4) \\
 &+ \left(-\frac{1}{8} + \frac{(9+10x)e^{-x}}{200} - \frac{\sin(2x)(8x+i)}{320} - \frac{37\cos(2x)}{1600} + \frac{(9-10x)e^x}{200} \right)
 \end{aligned}$$

Summary

The solution(s) found are the following

$$\begin{aligned}
 y &= c_1 e^{-x} + c_2 e^x + e^{2ix} c_3 + e^{-2ix} c_4 - \frac{1}{8} + \frac{(9+10x)e^{-x}}{200} \\
 &- \frac{\sin(2x)(8x+i)}{320} - \frac{37\cos(2x)}{1600} + \frac{(9-10x)e^x}{200}
 \end{aligned} \tag{1}$$

Verification of solutions

$$\begin{aligned}
 y &= c_1 e^{-x} + c_2 e^x + e^{2ix} c_3 + e^{-2ix} c_4 - \frac{1}{8} + \frac{(9+10x)e^{-x}}{200} \\
 &- \frac{\sin(2x)(8x+i)}{320} - \frac{37\cos(2x)}{1600} + \frac{(9-10x)e^x}{200}
 \end{aligned}$$

Verified OK.

11.53.1 Maple step by step solution

Let's solve

$$y'''' + 3y'' - 4y = \cos(x)^2 - \cosh(x)$$

- Highest derivative means the order of the ODE is 4

$$y''''$$

- Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(x)$

$$y_1(x) = y$$

- Define new variable $y_2(x)$

$$y_2(x) = y'$$

- Define new variable $y_3(x)$

$$y_3(x) = y''$$

- Define new variable $y_4(x)$

$$y_4(x) = y'''$$

- Isolate for $y_4'(x)$ using original ODE

$$y_4'(x) = \cos(x)^2 - \cosh(x) - 3y_3(x) + 4y_1(x)$$

Convert linear ODE into a system of first order ODEs

$$[y_2(x) = y_1'(x), y_3(x) = y_2'(x), y_4(x) = y_3'(x), y_4'(x) = \cos(x)^2 - \cosh(x) - 3y_3(x) + 4y_1(x)]$$

- Define vector

$$\vec{y}(x) = \begin{bmatrix} y_1(x) \\ y_2(x) \\ y_3(x) \\ y_4(x) \end{bmatrix}$$

- System to solve

$$\vec{y}'(x) = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 4 & 0 & -3 & 0 \end{bmatrix} \cdot \vec{y}(x) + \begin{bmatrix} 0 \\ 0 \\ 0 \\ \cos(x)^2 - \cosh(x) \end{bmatrix}$$

- Define the forcing function

$$\vec{f}(x) = \begin{bmatrix} 0 \\ 0 \\ 0 \\ \cos(x)^2 - \cosh(x) \end{bmatrix}$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 4 & 0 & -3 & 0 \end{bmatrix}$$

- Rewrite the system as

$$\vec{y}'(x) = A \cdot \vec{y}(x) + \vec{f}$$

- To solve the system, find the eigenvalues and eigenvectors of A
- Eigenpairs of A

$$\left[\left[-1, \begin{bmatrix} -1 \\ 1 \\ -1 \\ 1 \end{bmatrix} \right], \left[1, \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} \right], \left[-2\text{I}, \begin{bmatrix} -\frac{1}{8} \\ -\frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right], \left[2\text{I}, \begin{bmatrix} \frac{1}{8} \\ -\frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[-1, \begin{bmatrix} -1 \\ 1 \\ -1 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_1 = e^{-x} \cdot \begin{bmatrix} -1 \\ 1 \\ -1 \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[1, \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_2 = e^x \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}$$

- Consider complex eigenpair, complex conjugate eigenvalue can be ignored

$$\left[-2I, \begin{bmatrix} -\frac{I}{8} \\ -\frac{1}{4} \\ \frac{I}{2} \\ 1 \end{bmatrix} \right]$$

- Solution from eigenpair

$$e^{-2Ix} \cdot \begin{bmatrix} -\frac{I}{8} \\ -\frac{1}{4} \\ \frac{I}{2} \\ 1 \end{bmatrix}$$

- Use Euler identity to write solution in terms of sin and cos

$$(\cos(2x) - I \sin(2x)) \cdot \begin{bmatrix} -\frac{I}{8} \\ -\frac{1}{4} \\ \frac{I}{2} \\ 1 \end{bmatrix}$$

- Simplify expression

$$\begin{bmatrix} -\frac{1}{8}(\cos(2x) - I \sin(2x)) \\ -\frac{\cos(2x)}{4} + \frac{I \sin(2x)}{4} \\ \frac{1}{2}(\cos(2x) - I \sin(2x)) \\ \cos(2x) - I \sin(2x) \end{bmatrix}$$

- Both real and imaginary parts are solutions to the homogeneous system

$$\vec{y}_3(x) = \begin{bmatrix} -\frac{\sin(2x)}{8} \\ -\frac{\cos(2x)}{4} \\ \frac{\sin(2x)}{2} \\ \cos(2x) \end{bmatrix}, \vec{y}_4(x) = \begin{bmatrix} -\frac{\cos(2x)}{8} \\ \frac{\sin(2x)}{4} \\ \frac{\cos(2x)}{2} \\ -\sin(2x) \end{bmatrix}$$

- General solution of the system of ODEs can be written in terms of the particular solution $\vec{y}_p(x)$
 $\vec{y}(x) = c_1 \vec{y}_1 + c_2 \vec{y}_2 + c_3 \vec{y}_3(x) + c_4 \vec{y}_4(x) + \vec{y}_p(x)$

□ Fundamental matrix

- Let $\phi(x)$ be the matrix whose columns are the independent solutions of the homogeneous system

$$\phi(x) = \begin{bmatrix} -e^{-x} & e^x & -\frac{\sin(2x)}{8} & -\frac{\cos(2x)}{8} \\ e^{-x} & e^x & -\frac{\cos(2x)}{4} & \frac{\sin(2x)}{4} \\ -e^{-x} & e^x & \frac{\sin(2x)}{2} & \frac{\cos(2x)}{2} \\ e^{-x} & e^x & \cos(2x) & -\sin(2x) \end{bmatrix}$$

- The fundamental matrix, $\Phi(x)$ is a normalized version of $\phi(x)$ satisfying $\Phi(0) = I$ where I is the identity matrix
 $\Phi(x) = \phi(x) \cdot \frac{1}{\phi(0)}$

- Substitute the value of $\phi(x)$ and $\phi(0)$

$$\Phi(x) = \begin{bmatrix} -e^{-x} & e^x & -\frac{\sin(2x)}{8} & -\frac{\cos(2x)}{8} \\ e^{-x} & e^x & -\frac{\cos(2x)}{4} & \frac{\sin(2x)}{4} \\ -e^{-x} & e^x & \frac{\sin(2x)}{2} & \frac{\cos(2x)}{2} \\ e^{-x} & e^x & \cos(2x) & -\sin(2x) \end{bmatrix} \cdot \frac{1}{\begin{bmatrix} -1 & 1 & 0 & -\frac{1}{8} \\ 1 & 1 & -\frac{1}{4} & 0 \\ -1 & 1 & 0 & \frac{1}{2} \\ 1 & 1 & 1 & 0 \end{bmatrix}}$$

- Evaluate and simplify to get the fundamental matrix

$$\Phi(x) = \begin{bmatrix} \frac{2e^{-x}}{5} + \frac{2e^x}{5} + \frac{\cos(2x)}{5} & -\frac{2e^{-x}}{5} + \frac{2e^x}{5} + \frac{\sin(2x)}{10} & \frac{e^{-x}}{10} + \frac{e^x}{10} - \frac{\cos(2x)}{5} & -\frac{e^{-x}}{10} + \frac{e^x}{10} - \frac{\sin(2x)}{10} \\ -\frac{2e^{-x}}{5} + \frac{2e^x}{5} - \frac{2\sin(2x)}{5} & \frac{2e^{-x}}{5} + \frac{2e^x}{5} + \frac{\cos(2x)}{5} & -\frac{e^{-x}}{10} + \frac{e^x}{10} + \frac{2\sin(2x)}{5} & \frac{e^{-x}}{10} + \frac{e^x}{10} - \frac{\cos(2x)}{5} \\ \frac{2e^{-x}}{5} + \frac{2e^x}{5} - \frac{4\cos(2x)}{5} & -\frac{2e^{-x}}{5} + \frac{2e^x}{5} - \frac{2\sin(2x)}{5} & \frac{e^{-x}}{10} + \frac{e^x}{10} + \frac{4\cos(2x)}{5} & -\frac{e^{-x}}{10} + \frac{e^x}{10} + \frac{2\sin(2x)}{5} \\ -\frac{2e^{-x}}{5} + \frac{2e^x}{5} + \frac{8\sin(2x)}{5} & \frac{2e^{-x}}{5} + \frac{2e^x}{5} - \frac{4\cos(2x)}{5} & -\frac{e^{-x}}{10} + \frac{e^x}{10} - \frac{8\sin(2x)}{5} & \frac{e^{-x}}{10} + \frac{e^x}{10} + \frac{4\cos(2x)}{5} \end{bmatrix}$$

□

Find a particular solution of the system of ODEs using variation of parameters

- Let the particular solution be the fundamental matrix multiplied by $\vec{v}(x)$ and solve for $\vec{v}(x)$

$$\vec{y}_p(x) = \Phi(x) \cdot \vec{v}(x)$$

- Take the derivative of the particular solution

$$\vec{y}'_p(x) = \Phi'(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x)$$

- Substitute particular solution and its derivative into the system of ODEs

$$\Phi'(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x) = A \cdot \Phi(x) \cdot \vec{v}(x) + \vec{f}(x)$$

- The fundamental matrix has columns that are solutions to the homogeneous system so its derivative is $A \cdot \Phi(x)$

$$A \cdot \Phi(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x) = A \cdot \Phi(x) \cdot \vec{v}(x) + \vec{f}(x)$$

- Cancel like terms

$$\Phi(x) \cdot \vec{v}'(x) = \vec{f}(x)$$

- Multiply by the inverse of the fundamental matrix

$$\vec{v}'(x) = \frac{1}{\Phi(x)} \cdot \vec{f}(x)$$

- Integrate to solve for $\vec{v}(x)$

$$\vec{v}(x) = \int_0^x \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds$$

- Plug $\vec{v}(x)$ into the equation for the particular solution

$$\vec{y}_p(x) = \Phi(x) \cdot \left(\int_0^x \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds \right)$$

- Plug in the fundamental matrix and the forcing function and compute

$$\vec{y}_p(x) = \begin{bmatrix} \frac{(5x+8)e^{-x}}{100} - \frac{7\cos(x)^2}{100} - \frac{\sin(x)\cos(x)x}{20} - \frac{9}{100} + \frac{(-5x+8)e^x}{100} \\ \frac{(-5x-3)e^{-x}}{100} - \frac{\cos(x)^2x}{10} + \frac{9\cos(x)\sin(x)}{100} + \frac{(-5x+3)e^x}{100} + \frac{x}{20} \\ \frac{(5x-2)e^{-x}}{100} + \frac{2\cos(x)^2}{25} + \frac{\sin(x)\cos(x)x}{5} - \frac{1}{25} + \frac{(-5x-2)e^x}{100} \\ \frac{(-5x+7)e^{-x}}{100} + \frac{x\cos(2x)}{5} + \frac{\sin(2x)}{50} + \frac{(-5x-7)e^x}{100} \end{bmatrix}$$

- Plug particular solution back into general solution

$$\vec{y}(x) = c_1 \vec{y}_1 + c_2 \vec{y}_2 + c_3 \vec{y}_3(x) + c_4 \vec{y}_4(x) + \begin{bmatrix} \frac{(5x+8)e^{-x}}{100} - \frac{7 \cos(x)^2}{100} - \frac{\sin(x) \cos(x)x}{20} - \frac{9}{100} + \frac{(-5x+8)e^x}{100} \\ \frac{(-5x-3)e^{-x}}{100} - \frac{\cos(x)^2 x}{10} + \frac{9 \cos(x) \sin(x)}{100} + \frac{(-5x+3)e^x}{100} + \frac{x}{20} \\ \frac{(5x-2)e^{-x}}{100} + \frac{2 \cos(x)^2}{25} + \frac{\sin(x) \cos(x)x}{5} - \frac{1}{25} + \frac{(-5x-2)e^x}{100} \\ \frac{(-5x+7)e^{-x}}{100} + \frac{x \cos(2x)}{5} + \frac{\sin(2x)}{50} + \frac{(-5x-7)e^x}{100} \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y = -\frac{9}{100} + \frac{(8+5x-100c_1)e^{-x}}{100} + \frac{(-7-25c_4) \cos(x)^2}{100} - \frac{\sin(x)(x+5c_3) \cos(x)}{20} + \frac{(8-5x+100c_2)e^x}{100} + \frac{c_4}{8}$$

Maple trace

```

`Methods for high order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 4; linear nonhomogeneous with symmetry [0,1]
trying high order linear exact nonhomogeneous
trying differential order: 4; missing the dependent variable
checking if the LODE has constant coefficients
<- constant coefficients successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 56

```
dsolve(diff(y(x),x$4)+3*diff(y(x),x$2)-4*y(x)=cos(x)^2-cosh(x),y(x), singsol=all)
```

$$y(x) = -\frac{1}{8} + \frac{(10x + 200c_3 + 9) e^{-x}}{200} + \frac{(200c_2 - 9) \cos(2x)}{200} + \frac{(-x + 40c_4) \sin(2x)}{40} + \frac{(-10x + 200c_1 + 9) e^x}{200}$$

✓ Solution by Mathematica

Time used: 0.21 (sec). Leaf size: 75

```
DSolve[y''''[x]+3*y''[x]-4*y[x]==Cos[x]^2-Cosh[x],y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{1}{400}e^{-x}((-13 + 400c_1)e^x \cos(2x) + 2(10x - 25e^x + e^{2x}(-10x + 9 + 200c_4) - 5e^x(x - 40c_2) \sin(2x) + 9 + 200c_3))$$

11.54 problem 54

11.54.1 Maple step by step solution 2847

Internal problem ID [11828]

Internal file name [OUTPUT/11837_Thursday_April_11_2024_08_52_48_PM_71487248/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.3. The method of undetermined coefficients. Exercises page 151

Problem number: 54.

ODE order: 4.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_high_order , _linear , _nonhomogeneous]]
```

$$y'''' + 10y'' + 9y = \sin(x) \sin(2x)$$

This is higher order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE And y_p is a particular solution to the nonhomogeneous ODE. y_h is the solution to

$$y'''' + 10y'' + 9y = 0$$

The characteristic equation is

$$\lambda^4 + 10\lambda^2 + 9 = 0$$

The roots of the above equation are

$$\lambda_1 = 3i$$

$$\lambda_2 = -3i$$

$$\lambda_3 = i$$

$$\lambda_4 = -i$$

Therefore the homogeneous solution is

$$y_h(x) = e^{ix}c_1 + e^{3ix}c_2 + e^{-ix}c_3 + e^{-3ix}c_4$$

The fundamental set of solutions for the homogeneous solution are the following

$$\begin{aligned} y_1 &= e^{ix} \\ y_2 &= e^{3ix} \\ y_3 &= e^{-ix} \\ y_4 &= e^{-3ix} \end{aligned}$$

Now the particular solution to the given ODE is found

$$y'''' + 10y'' + 9y = \sin(x)\sin(2x)$$

Let the particular solution be

$$y_p = U_1y_1 + U_2y_2 + U_3y_3 + U_4y_4$$

Where y_i are the basis solutions found above for the homogeneous solution y_h and $U_i(x)$ are functions to be determined as follows

$$U_i = (-1)^{n-i} \int \frac{F(x)W_i(x)}{aW(x)} dx$$

Where $W(x)$ is the Wronskian and $W_i(x)$ is the Wronskian that results after deleting the last row and the i -th column of the determinant and n is the order of the ODE or equivalently, the number of basis solutions, and a is the coefficient of the leading derivative in the ODE, and $F(x)$ is the RHS of the ODE. Therefore, the first step is to find the Wronskian $W(x)$. This is given by

$$W(x) = \begin{vmatrix} y_1 & y_2 & y_3 & y_4 \\ y_1' & y_2' & y_3' & y_4' \\ y_1'' & y_2'' & y_3'' & y_4'' \\ y_1''' & y_2''' & y_3''' & y_4''' \end{vmatrix}$$

Substituting the fundamental set of solutions y_i found above in the Wronskian gives

$$W = \begin{bmatrix} e^{ix} & e^{3ix} & e^{-ix} & e^{-3ix} \\ ie^{ix} & 3ie^{3ix} & -ie^{-ix} & -3ie^{-3ix} \\ -e^{ix} & -9e^{3ix} & -e^{-ix} & -9e^{-3ix} \\ -ie^{ix} & -27ie^{3ix} & ie^{-ix} & 27ie^{-3ix} \end{bmatrix}$$

$$|W| = 768 e^{ix} e^{3ix} e^{-ix} e^{-3ix}$$

The determinant simplifies to

$$|W| = 768$$

Now we determine W_i for each U_i .

$$\begin{aligned} W_1(x) &= \det \begin{bmatrix} e^{3ix} & e^{-ix} & e^{-3ix} \\ 3ie^{3ix} & -ie^{-ix} & -3ie^{-3ix} \\ -9e^{3ix} & -e^{-ix} & -9e^{-3ix} \end{bmatrix} \\ &= 48ie^{-ix} \end{aligned}$$

$$\begin{aligned} W_2(x) &= \det \begin{bmatrix} e^{ix} & e^{-ix} & e^{-3ix} \\ ie^{ix} & -ie^{-ix} & -3ie^{-3ix} \\ -e^{ix} & -e^{-ix} & -9e^{-3ix} \end{bmatrix} \\ &= 16ie^{-3ix} \end{aligned}$$

$$\begin{aligned} W_3(x) &= \det \begin{bmatrix} e^{ix} & e^{3ix} & e^{-3ix} \\ ie^{ix} & 3ie^{3ix} & -3ie^{-3ix} \\ -e^{ix} & -9e^{3ix} & -9e^{-3ix} \end{bmatrix} \\ &= -48ie^{ix} \end{aligned}$$

$$\begin{aligned} W_4(x) &= \det \begin{bmatrix} e^{ix} & e^{3ix} & e^{-ix} \\ ie^{ix} & 3ie^{3ix} & -ie^{-ix} \\ -e^{ix} & -9e^{3ix} & -e^{-ix} \end{bmatrix} \\ &= -16ie^{3ix} \end{aligned}$$

Now we are ready to evaluate each $U_i(x)$.

$$\begin{aligned} U_1 &= (-1)^{4-1} \int \frac{F(x)W_1(x)}{aW(x)} dx \\ &= (-1)^3 \int \frac{(\sin(x) \sin(2x)) (48ie^{-ix})}{(1)(768)} dx \\ &= - \int \frac{48i \sin(x) \sin(2x) e^{-ix}}{768} dx \\ &= - \int \left(\frac{i \sin(x) \sin(2x) e^{-ix}}{16} \right) dx \\ &= - \left(\int \frac{i \sin(x) \sin(2x) e^{-ix}}{16} dx \right) \end{aligned}$$

$$\begin{aligned}
U_2 &= (-1)^{4-2} \int \frac{F(x)W_2(x)}{aW(x)} dx \\
&= (-1)^2 \int \frac{(\sin(x) \sin(2x)) (16ie^{-3ix})}{(1)(768)} dx \\
&= \int \frac{16i \sin(x) \sin(2x) e^{-3ix}}{768} dx \\
&= \int \left(\frac{i \sin(x) \sin(2x) e^{-3ix}}{48} \right) dx \\
&= \int \frac{i \sin(x) \sin(2x) e^{-3ix}}{48} dx
\end{aligned}$$

$$\begin{aligned}
U_3 &= (-1)^{4-3} \int \frac{F(x)W_3(x)}{aW(x)} dx \\
&= (-1)^1 \int \frac{(\sin(x) \sin(2x)) (-48ie^{ix})}{(1)(768)} dx \\
&= - \int \frac{-48i \sin(x) \sin(2x) e^{ix}}{768} dx \\
&= - \int \left(-\frac{i \sin(x) \sin(2x) e^{ix}}{16} \right) dx \\
&= - \left(\int -\frac{i \sin(x) \sin(2x) e^{ix}}{16} dx \right)
\end{aligned}$$

$$\begin{aligned}
U_4 &= (-1)^{4-4} \int \frac{F(x)W_4(x)}{aW(x)} dx \\
&= (-1)^0 \int \frac{(\sin(x) \sin(2x)) (-16ie^{3ix})}{(1)(768)} dx \\
&= \int \frac{-16i \sin(x) \sin(2x) e^{3ix}}{768} dx \\
&= \int \left(-\frac{i \sin(x) \sin(2x) e^{3ix}}{48} \right) dx \\
&= \int -\frac{i \sin(x) \sin(2x) e^{3ix}}{48} dx
\end{aligned}$$

Now that all the U_i functions have been determined, the particular solution is found from

$$y_p = U_1y_1 + U_2y_2 + U_3y_3 + U_4y_4$$

Hence

$$\begin{aligned}
 y_p &= \left(- \left(\int \frac{i \sin(x) \sin(2x) e^{-ix}}{16} dx \right) \right) (e^{ix}) \\
 &+ \left(\int \frac{i \sin(x) \sin(2x) e^{-3ix}}{48} dx \right) (e^{3ix}) \\
 &+ \left(- \left(\int - \frac{i \sin(x) \sin(2x) e^{ix}}{16} dx \right) \right) (e^{-ix}) \\
 &+ \left(\int - \frac{i \sin(x) \sin(2x) e^{3ix}}{48} dx \right) (e^{-3ix})
 \end{aligned}$$

Therefore the particular solution is

$$y_p = \frac{i \left(\left(\int \sin(x) \sin(2x) e^{-3ix} dx \right) e^{3ix} - 3 \left(\int \sin(x) \sin(2x) e^{-ix} dx \right) e^{ix} + 3 \left(\int \sin(x) \sin(2x) e^{ix} dx \right) e^{-ix} - \left(\int \sin(x) \sin(2x) e^{3ix} dx \right) e^{-3ix} \right)}{48}$$

Which simplifies to

$$y_p = \frac{\left(\int \sin(x) \sin(2x) \sin(3x) dx \right) \cos(3x)}{24} - \frac{\left(\int \sin(x) \sin(2x) \cos(3x) dx \right) \sin(3x)}{24} - \frac{\left(\int \sin(x)^2 \sin(2x) dx \right) \cos(x)}{8} + \frac{\left(\int (1 - \cos(4x)) dx \right) \sin(x)}{32}$$

Therefore the general solution is

$$\begin{aligned}
 y &= y_h + y_p \\
 &= (e^{ix} c_1 + e^{3ix} c_2 + e^{-ix} c_3 + e^{-3ix} c_4) \\
 &+ \left(\frac{\left(\int \sin(x) \sin(2x) \sin(3x) dx \right) \cos(3x)}{24} - \frac{\left(\int \sin(x) \sin(2x) \cos(3x) dx \right) \sin(3x)}{24} \right. \\
 &\quad \left. - \frac{\left(\int \sin(x)^2 \sin(2x) dx \right) \cos(x)}{8} + \frac{\left(\int (1 - \cos(4x)) dx \right) \sin(x)}{32} \right)
 \end{aligned}$$

Summary

The solution(s) found are the following

$$\begin{aligned}
 y &= e^{ix} c_1 + e^{3ix} c_2 + e^{-ix} c_3 + e^{-3ix} c_4 + \frac{\left(\int \sin(x) \sin(2x) \sin(3x) dx \right) \cos(3x)}{24} \\
 &- \frac{\left(\int \sin(x) \sin(2x) \cos(3x) dx \right) \sin(3x)}{24} \\
 &- \frac{\left(\int \sin(x)^2 \sin(2x) dx \right) \cos(x)}{8} + \frac{\left(\int (1 - \cos(4x)) dx \right) \sin(x)}{32}
 \end{aligned} \tag{1}$$

Verification of solutions

$$y = e^{ix}c_1 + e^{3ix}c_2 + e^{-ix}c_3 + e^{-3ix}c_4 + \frac{(\int \sin(x) \sin(2x) \sin(3x) dx) \cos(3x)}{24} \\ - \frac{(\int \sin(x) \sin(2x) \cos(3x) dx) \sin(3x)}{24} \\ - \frac{(\int \sin(x)^2 \sin(2x) dx) \cos(x)}{8} + \frac{(\int (1 - \cos(4x)) dx) \sin(x)}{32}$$

Verified OK.

11.54.1 Maple step by step solution

Let's solve

$$y'''' + 10y'' + 9y = \sin(x) \sin(2x)$$

- Highest derivative means the order of the ODE is 4

$$y''''$$

- Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(x)$

$$y_1(x) = y$$

- Define new variable $y_2(x)$

$$y_2(x) = y'$$

- Define new variable $y_3(x)$

$$y_3(x) = y''$$

- Define new variable $y_4(x)$

$$y_4(x) = y'''$$

- Isolate for $y_4'(x)$ using original ODE

$$y_4'(x) = \sin(x) \sin(2x) - 10y_3(x) - 9y_1(x)$$

Convert linear ODE into a system of first order ODEs

$$[y_2(x) = y_1'(x), y_3(x) = y_2'(x), y_4(x) = y_3'(x), y_4'(x) = \sin(x) \sin(2x) - 10y_3(x) - 9y_1(x)]$$

- Define vector

$$\vec{y}(x) = \begin{bmatrix} y_1(x) \\ y_2(x) \\ y_3(x) \\ y_4(x) \end{bmatrix}$$

- System to solve

$$\vec{y}'(x) = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -9 & 0 & -10 & 0 \end{bmatrix} \cdot \vec{y}(x) + \begin{bmatrix} 0 \\ 0 \\ 0 \\ \sin(x) \sin(2x) \end{bmatrix}$$

- Define the forcing function

$$\vec{f}(x) = \begin{bmatrix} 0 \\ 0 \\ 0 \\ \sin(x) \sin(2x) \end{bmatrix}$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ -9 & 0 & -10 & 0 \end{bmatrix}$$

- Rewrite the system as

$$\vec{y}'(x) = A \cdot \vec{y}(x) + \vec{f}$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[\begin{bmatrix} -3\mathbf{I}, \begin{bmatrix} -\frac{1}{27} \\ -\frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix} \right] \right], \left[\begin{bmatrix} -\mathbf{I}, \begin{bmatrix} -\mathbf{I} \\ -1 \\ \mathbf{I} \\ 1 \end{bmatrix} \right] \right], \left[\begin{bmatrix} \mathbf{I}, \begin{bmatrix} \mathbf{I} \\ -1 \\ -\mathbf{I} \\ 1 \end{bmatrix} \right] \right], \left[\begin{bmatrix} 3\mathbf{I}, \begin{bmatrix} \frac{1}{27} \\ -\frac{1}{9} \\ -\frac{1}{3} \\ 1 \end{bmatrix} \right] \right]$$

- Consider complex eigenpair, complex conjugate eigenvalue can be ignored

$$\left[-3\mathbf{I}, \begin{bmatrix} -\frac{1}{27} \\ -\frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix} \right]$$

- Solution from eigenpair

$$e^{-3Ix} \cdot \begin{bmatrix} -\frac{1}{27} \\ -\frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix}$$

- Use Euler identity to write solution in terms of sin and cos

$$(\cos(3x) - I \sin(3x)) \cdot \begin{bmatrix} -\frac{1}{27} \\ -\frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix}$$

- Simplify expression

$$\begin{bmatrix} -\frac{1}{27}(\cos(3x) - I \sin(3x)) \\ -\frac{\cos(3x)}{9} + \frac{I \sin(3x)}{9} \\ \frac{1}{3}(\cos(3x) - I \sin(3x)) \\ \cos(3x) - I \sin(3x) \end{bmatrix}$$

- Both real and imaginary parts are solutions to the homogeneous system

$$\vec{y}_1(x) = \begin{bmatrix} -\frac{\sin(3x)}{27} \\ -\frac{\cos(3x)}{9} \\ \frac{\sin(3x)}{3} \\ \cos(3x) \end{bmatrix}, \vec{y}_2(x) = \begin{bmatrix} -\frac{\cos(3x)}{27} \\ \frac{\sin(3x)}{9} \\ \frac{\cos(3x)}{3} \\ -\sin(3x) \end{bmatrix}$$

- Consider complex eigenpair, complex conjugate eigenvalue can be ignored

$$\left[-\mathbf{I}, \begin{bmatrix} -\mathbf{I} \\ -1 \\ \mathbf{I} \\ 1 \end{bmatrix} \right]$$

- Solution from eigenpair

$$e^{-\mathbf{I}x} \cdot \begin{bmatrix} -\mathbf{I} \\ -1 \\ \mathbf{I} \\ 1 \end{bmatrix}$$

- Use Euler identity to write solution in terms of sin and cos

$$(\cos(x) - \mathbf{I} \sin(x)) \cdot \begin{bmatrix} -\mathbf{I} \\ -1 \\ \mathbf{I} \\ 1 \end{bmatrix}$$

- Simplify expression

$$\begin{bmatrix} -\mathbf{I}(\cos(x) - \mathbf{I} \sin(x)) \\ -\cos(x) + \mathbf{I} \sin(x) \\ \mathbf{I}(\cos(x) - \mathbf{I} \sin(x)) \\ \cos(x) - \mathbf{I} \sin(x) \end{bmatrix}$$

- Both real and imaginary parts are solutions to the homogeneous system

$$\left[\vec{y}_3(x) = \begin{bmatrix} -\sin(x) \\ -\cos(x) \\ \sin(x) \\ \cos(x) \end{bmatrix}, \vec{y}_4(x) = \begin{bmatrix} -\cos(x) \\ \sin(x) \\ \cos(x) \\ -\sin(x) \end{bmatrix} \right]$$

- General solution of the system of ODEs can be written in terms of the particular solution $\vec{y}_p(x)$

$$\vec{y}(x) = c_1 \vec{y}_1(x) + c_2 \vec{y}_2(x) + c_3 \vec{y}_3(x) + c_4 \vec{y}_4(x) + \vec{y}_p(x)$$

- Fundamental matrix

- Let $\phi(x)$ be the matrix whose columns are the independent solutions of the homogeneous system

$$\phi(x) = \begin{bmatrix} -\frac{\sin(3x)}{27} & -\frac{\cos(3x)}{27} & -\sin(x) & -\cos(x) \\ -\frac{\cos(3x)}{9} & \frac{\sin(3x)}{9} & -\cos(x) & \sin(x) \\ \frac{\sin(3x)}{3} & \frac{\cos(3x)}{3} & \sin(x) & \cos(x) \\ \cos(3x) & -\sin(3x) & \cos(x) & -\sin(x) \end{bmatrix}$$

- The fundamental matrix, $\Phi(x)$ is a normalized version of $\phi(x)$ satisfying $\Phi(0) = I$ where I is the identity matrix

$$\Phi(x) = \phi(x) \cdot \frac{1}{\phi(0)}$$

- Substitute the value of $\phi(x)$ and $\phi(0)$

$$\Phi(x) = \begin{bmatrix} -\frac{\sin(3x)}{27} & -\frac{\cos(3x)}{27} & -\sin(x) & -\cos(x) \\ -\frac{\cos(3x)}{9} & \frac{\sin(3x)}{9} & -\cos(x) & \sin(x) \\ \frac{\sin(3x)}{3} & \frac{\cos(3x)}{3} & \sin(x) & \cos(x) \\ \cos(3x) & -\sin(3x) & \cos(x) & -\sin(x) \end{bmatrix} \cdot \frac{1}{\begin{bmatrix} 0 & -\frac{1}{27} & 0 & -1 \\ -\frac{1}{9} & 0 & -1 & 0 \\ 0 & \frac{1}{3} & 0 & 1 \\ 1 & 0 & 1 & 0 \end{bmatrix}}$$

- Evaluate and simplify to get the fundamental matrix

$$\Phi(x) = \begin{bmatrix} -\frac{\cos(x)^3}{2} + \frac{3\cos(x)}{2} & -\frac{\sin(3x)}{24} + \frac{9\sin(x)}{8} & \frac{\sin(x)^2 \cos(x)}{2} & \frac{\sin(x)^3}{6} \\ -\frac{3\sin(x)^3}{2} & -\frac{\cos(x)^3}{2} + \frac{3\cos(x)}{2} & \frac{3\sin(3x)}{8} - \frac{\sin(x)}{8} & \frac{\sin(x)^2 \cos(x)}{2} \\ -\frac{9\sin(x)^2 \cos(x)}{2} & -\frac{3\sin(x)^3}{2} & \frac{9\cos(x)^3}{2} - \frac{7\cos(x)}{2} & \frac{3\sin(3x)}{8} - \frac{\sin(x)}{8} \\ -\frac{27\sin(3x)}{8} + \frac{9\sin(x)}{8} & -\frac{9\sin(x)^2 \cos(x)}{2} & -\frac{27\sin(3x)}{8} + \frac{\sin(x)}{8} & \frac{9\cos(x)^3}{2} - \frac{7\cos(x)}{2} \end{bmatrix}$$

- Find a particular solution of the system of ODEs using variation of parameters

- Let the particular solution be the fundamental matrix multiplied by $\vec{v}(x)$ and solve for $\vec{v}(x)$

$$\vec{y}_p(x) = \Phi(x) \cdot \vec{v}(x)$$

- Take the derivative of the particular solution

$$\vec{y}'_p(x) = \Phi'(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x)$$

- Substitute particular solution and its derivative into the system of ODEs

$$\Phi'(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x) = A \cdot \Phi(x) \cdot \vec{v}(x) + \vec{f}(x)$$

- The fundamental matrix has columns that are solutions to the homogeneous system so its derivative is $A \cdot \Phi(x)$

$$A \cdot \Phi(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x) = A \cdot \Phi(x) \cdot \vec{v}(x) + \vec{f}(x)$$

- Cancel like terms

$$\Phi(x) \cdot \vec{v}'(x) = \vec{f}(x)$$

- Multiply by the inverse of the fundamental matrix

$$\vec{v}'(x) = \frac{1}{\Phi(x)} \cdot \vec{f}(x)$$

- Integrate to solve for $\vec{v}(x)$

$$\vec{v}(x) = \int_0^x \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds$$

- Plug $\vec{v}(x)$ into the equation for the particular solution

$$\vec{y}_p(x) = \Phi(x) \cdot \left(\int_0^x \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds \right)$$

- Plug in the fundamental matrix and the forcing function and compute

$$\vec{y}_p(x) = \begin{bmatrix} \frac{\sin(x)(2 \cos(x)^2 x - 3 \cos(x) \sin(x) + x)}{48} \\ -\frac{7 \cos(x)^2 \sin(x)}{48} + \frac{\sin(x)}{12} + \frac{\cos(x)^3 x}{8} - \frac{\cos(x)x}{16} \\ -\frac{3 \cos(x)^2 \sin(x)x}{8} + \frac{5 \sin(x)^2 \cos(x)}{16} + \frac{x \sin(x)}{16} \\ \frac{9 \cos(x)^2 \sin(x)}{16} - \frac{\sin(x)}{4} - \frac{9 \cos(x)^3 x}{8} + \frac{13 \cos(x)x}{16} \end{bmatrix}$$

- Plug particular solution back into general solution

$$\vec{y}(x) = c_1 \vec{y}_1(x) + c_2 \vec{y}_2(x) + c_3 \vec{y}_3(x) + c_4 \vec{y}_4(x) + \begin{bmatrix} \frac{\sin(x)(2 \cos(x)^2 x - 3 \cos(x) \sin(x) + x)}{48} \\ -\frac{7 \cos(x)^2 \sin(x)}{48} + \frac{\sin(x)}{12} + \frac{\cos(x)^3 x}{8} - \frac{\cos(x)x}{16} \\ -\frac{3 \cos(x)^2 \sin(x)x}{8} + \frac{5 \sin(x)^2 \cos(x)}{16} + \frac{x \sin(x)}{16} \\ \frac{9 \cos(x)^2 \sin(x)}{16} - \frac{\sin(x)}{4} - \frac{9 \cos(x)^3 x}{8} + \frac{13 \cos(x)x}{16} \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y = -\frac{c_2 \cos(3x)}{27} - \frac{c_1 \sin(3x)}{27} - \frac{\sin(x)^2 \cos(x)}{16} + \frac{(2 \cos(x)^2 x + x - 48c_3) \sin(x)}{48} - c_4 \cos(x)$$

Maple trace

```
`Methods for high order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
trying differential order: 4; linear nonhomogeneous with symmetry [0,1]  
trying high order linear exact nonhomogeneous  
trying differential order: 4; missing the dependent variable  
checking if the LODE has constant coefficients  
<- constant coefficients successful`
```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 45

```
dsolve(diff(y(x),x$4)+10*diff(y(x),x$2)+9*y(x)=sin(x)*sin(2*x),y(x), singsol=all)
```

$$y(x) = \frac{(11 + 1152c_3) \cos(3x)}{1152} + \frac{(x + 96c_4) \sin(3x)}{96} \\ + \frac{(-1 + 64c_1) \cos(x)}{64} + \frac{\sin(x)(x + 32c_2)}{32}$$

✓ Solution by Mathematica

Time used: 0.079 (sec). Leaf size: 54

```
DSolve[y''''[x]+10*y''[x]+9*y[x]==Sin[x]*Sin[2*x],y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{1}{32}x \sin(x) + \frac{1}{96}x \sin(3x) + \left(-\frac{1}{64} + c_3\right) \cos(x) \\ + \left(\frac{13}{576} + c_1\right) \cos(3x) + c_4 \sin(x) + c_2 \sin(3x)$$

12 Chapter 4, Section 4.4. Variation of parameters.

Exercises page 162

12.1	problem 1	2855
12.2	problem 2	2868
12.3	problem 3	2881
12.4	problem 4	2894
12.5	problem 5	2907
12.6	problem 6	2920
12.7	problem 7	2933
12.8	problem 8	2946
12.9	problem 9	2959
12.10	problem 10	2974
12.11	problem 11	2989
12.12	problem 12	3002
12.13	problem 13	3016
12.14	problem 14	3028
12.15	problem 15	3040
12.16	problem 16	3053
12.17	problem 17	3068
12.18	problem 18	3080
12.19	problem 19	3095
12.20	problem 20	3123
12.21	problem 21	3146
12.22	problem 22	3165
12.23	problem 23	3183
12.24	problem 24	3200
12.25	problem 25	3225
12.26	problem 26	3231

12.1 problem 1

12.1.1 Solving as second order linear constant coeff ode	2855
12.1.2 Solving using Kovacic algorithm	2860
12.1.3 Maple step by step solution	2865

Internal problem ID [11829]

Internal file name [OUTPUT/11838_Thursday_April_11_2024_08_52_50_PM_83565124/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.4. Variation of parameters. Exercises page 162

Problem number: 1.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' + y = \cot(x)$$

12.1.1 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = 0, C = 1, f(x) = \cot(x)$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 0, C = 1$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 1 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 0, C = 1$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{0}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{0^2 - (4)(1)(1)} \\ &= \pm i \end{aligned}$$

Hence

$$\lambda_1 = +i$$

$$\lambda_2 = -i$$

Which simplifies to

$$\lambda_1 = i$$

$$\lambda_2 = -i$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = 0$ and $\beta = 1$. Therefore the final solution, when using Euler relation, can be written as

$$y = e^{\alpha x} (c_1 \cos(\beta x) + c_2 \sin(\beta x))$$

Which becomes

$$y = e^0 (c_1 \cos(x) + c_2 \sin(x))$$

Or

$$y = c_1 \cos(x) + c_2 \sin(x)$$

Therefore the homogeneous solution y_h is

$$y_h = c_1 \cos(x) + c_2 \sin(x)$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \cos(x)$$

$$y_2 = \sin(x)$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \cos(x) & \sin(x) \\ \frac{d}{dx}(\cos(x)) & \frac{d}{dx}(\sin(x)) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \cos(x) & \sin(x) \\ -\sin(x) & \cos(x) \end{vmatrix}$$

Therefore

$$W = (\cos(x))(\cos(x)) - (\sin(x))(-\sin(x))$$

Which simplifies to

$$W = \cos(x)^2 + \sin(x)^2$$

Which simplifies to

$$W = 1$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{\sin(x) \cot(x)}{1} dx$$

Which simplifies to

$$u_1 = - \int \cos(x) dx$$

Hence

$$u_1 = - \sin(x)$$

And Eq. (3) becomes

$$u_2 = \int \frac{\cos(x) \cot(x)}{1} dx$$

Which simplifies to

$$u_2 = \int \cos(x) \cot(x) dx$$

Hence

$$u_2 = \cos(x) + \ln(\csc(x) - \cot(x))$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = - \cos(x) \sin(x) + (\cos(x) + \ln(\csc(x) - \cot(x))) \sin(x)$$

Which simplifies to

$$y_p(x) = \sin(x) \ln(\csc(x) - \cot(x))$$

Therefore the general solution is

$$\begin{aligned}y &= y_h + y_p \\ &= (c_1 \cos(x) + c_2 \sin(x)) + (\sin(x) \ln(\csc(x) - \cot(x)))\end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 \cos(x) + c_2 \sin(x) + \sin(x) \ln(\csc(x) - \cot(x)) \quad (1)$$

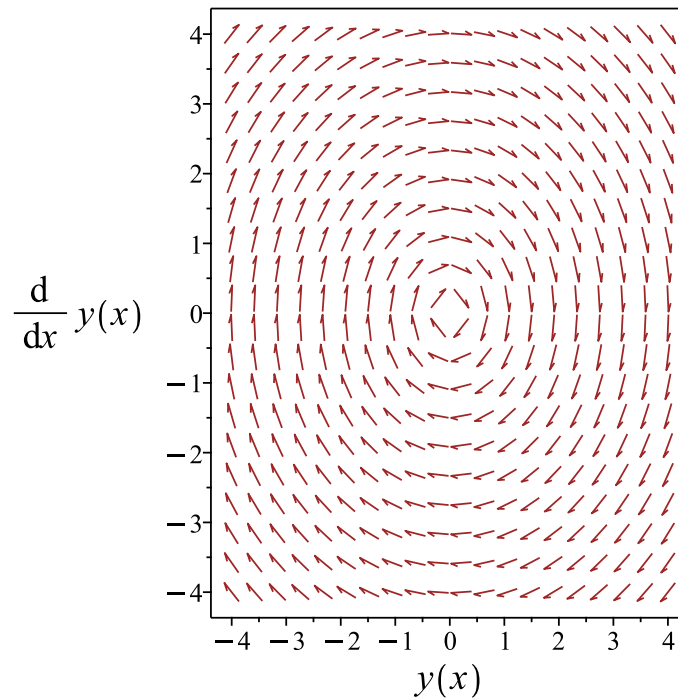


Figure 484: Slope field plot

Verification of solutions

$$y = c_1 \cos(x) + c_2 \sin(x) + \sin(x) \ln(\csc(x) - \cot(x))$$

Verified OK.

12.1.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' + y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= 0 \\ C &= 1 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-1}{1} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= -1 \\ t &= 1 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = -z(x) \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 425: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = -1$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = \cos(x)$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$y_1 = z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx}$$

Since $B = 0$ then the above reduces to

$$\begin{aligned}y_1 &= z_1 \\ &= \cos(x)\end{aligned}$$

Which simplifies to

$$y_1 = \cos(x)$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Since $B = 0$ then the above becomes

$$\begin{aligned}y_2 &= y_1 \int \frac{1}{y_1^2} dx \\ &= \cos(x) \int \frac{1}{\cos(x)^2} dx \\ &= \cos(x) (\tan(x))\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (\cos(x)) + c_2 (\cos(x) (\tan(x)))\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1 \cos(x) + c_2 \sin(x)$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \cos(x)$$

$$y_2 = \sin(x)$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \cos(x) & \sin(x) \\ \frac{d}{dx}(\cos(x)) & \frac{d}{dx}(\sin(x)) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \cos(x) & \sin(x) \\ -\sin(x) & \cos(x) \end{vmatrix}$$

Therefore

$$W = (\cos(x))(\cos(x)) - (\sin(x))(-\sin(x))$$

Which simplifies to

$$W = \cos(x)^2 + \sin(x)^2$$

Which simplifies to

$$W = 1$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{\sin(x) \cot(x)}{1} dx$$

Which simplifies to

$$u_1 = - \int \cos(x) dx$$

Hence

$$u_1 = - \sin(x)$$

And Eq. (3) becomes

$$u_2 = \int \frac{\cos(x) \cot(x)}{1} dx$$

Which simplifies to

$$u_2 = \int \cos(x) \cot(x) dx$$

Hence

$$u_2 = \cos(x) + \ln(\csc(x) - \cot(x))$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = -\cos(x) \sin(x) + (\cos(x) + \ln(\csc(x) - \cot(x))) \sin(x)$$

Which simplifies to

$$y_p(x) = \sin(x) \ln(\csc(x) - \cot(x))$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 \cos(x) + c_2 \sin(x)) + (\sin(x) \ln(\csc(x) - \cot(x))) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 \cos(x) + c_2 \sin(x) + \sin(x) \ln(\csc(x) - \cot(x)) \quad (1)$$

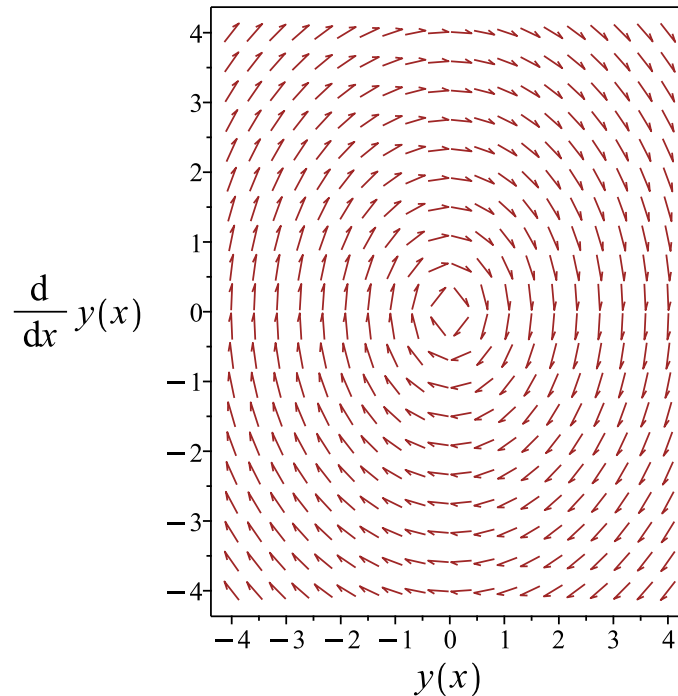


Figure 485: Slope field plot

Verification of solutions

$$y = c_1 \cos(x) + c_2 \sin(x) + \sin(x) \ln(\csc(x) - \cot(x))$$

Verified OK.

12.1.3 Maple step by step solution

Let's solve

$$y'' + y = \cot(x)$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of homogeneous ODE

$$r^2 + 1 = 0$$

- Use quadratic formula to solve for r

$$r = \frac{0 \pm (\sqrt{-4})}{2}$$
- Roots of the characteristic polynomial

$$r = (-I, I)$$
- 1st solution of the homogeneous ODE

$$y_1(x) = \cos(x)$$
- 2nd solution of the homogeneous ODE

$$y_2(x) = \sin(x)$$
- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$
- Substitute in solutions of the homogeneous ODE

$$y = c_1 \cos(x) + c_2 \sin(x) + y_p(x)$$
- Find a particular solution $y_p(x)$ of the ODE
 - Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x), y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x), y_2(x))} dx \right), f(x) = \cot(x) \right]$$
 - Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} \cos(x) & \sin(x) \\ -\sin(x) & \cos(x) \end{bmatrix}$$
 - Compute Wronskian

$$W(y_1(x), y_2(x)) = 1$$
 - Substitute functions into equation for $y_p(x)$

$$y_p(x) = -\cos(x) \left(\int \cos(x) dx \right) + \sin(x) \left(\int \cos(x) \cot(x) dx \right)$$
 - Compute integrals

$$y_p(x) = \sin(x) \ln(\csc(x) - \cot(x))$$
- Substitute particular solution into general solution to ODE

$$y = c_1 \cos(x) + c_2 \sin(x) + \sin(x) \ln(\csc(x) - \cot(x))$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]  
trying a double symmetry of the form [xi=0, eta=F(x)]  
-> Try solving first the homogeneous part of the ODE  
    checking if the LODE has constant coefficients  
    <- constant coefficients successful  
<- solving first the homogeneous part of the ODE successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 24

```
dsolve(diff(y(x),x$2)+y(x)=cot(x),y(x), singsol=all)
```

$$y(x) = \sin(x) c_2 + c_1 \cos(x) + \sin(x) \ln(\csc(x) - \cot(x))$$

✓ Solution by Mathematica

Time used: 0.052 (sec). Leaf size: 33

```
DSolve[y''[x]+y[x]==Cot[x],y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow c_1 \cos(x) + \sin(x) \left(\log\left(\sin\left(\frac{x}{2}\right)\right) - \log\left(\cos\left(\frac{x}{2}\right)\right) \right) + c_2$$

12.2 problem 2

12.2.1 Solving as second order linear constant coeff ode	2868
12.2.2 Solving using Kovacic algorithm	2873
12.2.3 Maple step by step solution	2879

Internal problem ID [11830]

Internal file name [OUTPUT/11839_Thursday_April_11_2024_08_52_51_PM_66482266/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.4. Variation of parameters. Exercises page 162

Problem number: 2.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' + y = \tan(x)^2$$

12.2.1 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = 0, C = 1, f(x) = \tan(x)^2$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 0, C = 1$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 1 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 0, C = 1$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{0}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{0^2 - (4)(1)(1)} \\ &= \pm i \end{aligned}$$

Hence

$$\lambda_1 = +i$$

$$\lambda_2 = -i$$

Which simplifies to

$$\lambda_1 = i$$

$$\lambda_2 = -i$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = 0$ and $\beta = 1$. Therefore the final solution, when using Euler relation, can be written as

$$y = e^{\alpha x} (c_1 \cos(\beta x) + c_2 \sin(\beta x))$$

Which becomes

$$y = e^0 (c_1 \cos(x) + c_2 \sin(x))$$

Or

$$y = c_1 \cos(x) + c_2 \sin(x)$$

Therefore the homogeneous solution y_h is

$$y_h = c_1 \cos(x) + c_2 \sin(x)$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \cos(x)$$

$$y_2 = \sin(x)$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \cos(x) & \sin(x) \\ \frac{d}{dx}(\cos(x)) & \frac{d}{dx}(\sin(x)) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \cos(x) & \sin(x) \\ -\sin(x) & \cos(x) \end{vmatrix}$$

Therefore

$$W = (\cos(x))(\cos(x)) - (\sin(x))(-\sin(x))$$

Which simplifies to

$$W = \cos(x)^2 + \sin(x)^2$$

Which simplifies to

$$W = 1$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{\sin(x) \tan(x)^2}{1} dx$$

Which simplifies to

$$u_1 = - \int \sin(x) \tan(x)^2 dx$$

Hence

$$u_1 = - \frac{\sin(x)^4}{\cos(x)} - (2 + \sin(x)^2) \cos(x)$$

And Eq. (3) becomes

$$u_2 = \int \frac{\cos(x) \tan(x)^2}{1} dx$$

Which simplifies to

$$u_2 = \int \sin(x) \tan(x) dx$$

Hence

$$u_2 = -\sin(x) + \ln(\sec(x) + \tan(x))$$

Which simplifies to

$$u_1 = -\cos(x) - \sec(x)$$

$$u_2 = -\sin(x) + \ln(\sec(x) + \tan(x))$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = (-\cos(x) - \sec(x)) \cos(x) + (-\sin(x) + \ln(\sec(x) + \tan(x))) \sin(x)$$

Which simplifies to

$$y_p(x) = -2 + \sin(x) \ln(\sec(x) + \tan(x))$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 \cos(x) + c_2 \sin(x)) + (-2 + \sin(x) \ln(\sec(x) + \tan(x))) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 \cos(x) + c_2 \sin(x) - 2 + \sin(x) \ln(\sec(x) + \tan(x)) \quad (1)$$

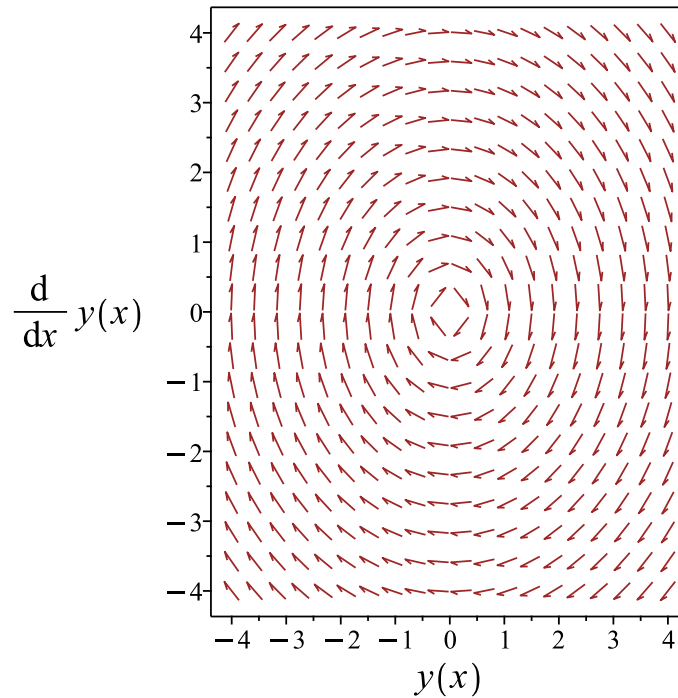


Figure 486: Slope field plot

Verification of solutions

$$y = c_1 \cos(x) + c_2 \sin(x) - 2 + \sin(x) \ln(\sec(x) + \tan(x))$$

Verified OK.

12.2.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' + y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= 0 \\ C &= 1 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-1}{1} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= -1 \\ t &= 1 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = -z(x) \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 427: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} \mathcal{O}(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = -1$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = \cos(x)$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$y_1 = z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx}$$

Since $B = 0$ then the above reduces to

$$\begin{aligned}y_1 &= z_1 \\ &= \cos(x)\end{aligned}$$

Which simplifies to

$$y_1 = \cos(x)$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Since $B = 0$ then the above becomes

$$\begin{aligned}y_2 &= y_1 \int \frac{1}{y_1^2} dx \\ &= \cos(x) \int \frac{1}{\cos(x)^2} dx \\ &= \cos(x) (\tan(x))\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (\cos(x)) + c_2 (\cos(x) (\tan(x)))\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1 \cos(x) + c_2 \sin(x)$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \cos(x)$$

$$y_2 = \sin(x)$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \cos(x) & \sin(x) \\ \frac{d}{dx}(\cos(x)) & \frac{d}{dx}(\sin(x)) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \cos(x) & \sin(x) \\ -\sin(x) & \cos(x) \end{vmatrix}$$

Therefore

$$W = (\cos(x))(\cos(x)) - (\sin(x))(-\sin(x))$$

Which simplifies to

$$W = \cos(x)^2 + \sin(x)^2$$

Which simplifies to

$$W = 1$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{\sin(x) \tan(x)^2}{1} dx$$

Which simplifies to

$$u_1 = - \int \sin(x) \tan(x)^2 dx$$

Hence

$$u_1 = - \frac{\sin(x)^4}{\cos(x)} - (2 + \sin(x)^2) \cos(x)$$

And Eq. (3) becomes

$$u_2 = \int \frac{\cos(x) \tan(x)^2}{1} dx$$

Which simplifies to

$$u_2 = \int \sin(x) \tan(x) dx$$

Hence

$$u_2 = - \sin(x) + \ln(\sec(x) + \tan(x))$$

Which simplifies to

$$u_1 = - \cos(x) - \sec(x)$$

$$u_2 = - \sin(x) + \ln(\sec(x) + \tan(x))$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = (- \cos(x) - \sec(x)) \cos(x) + (- \sin(x) + \ln(\sec(x) + \tan(x))) \sin(x)$$

Which simplifies to

$$y_p(x) = -2 + \sin(x) \ln(\sec(x) + \tan(x))$$

Therefore the general solution is

$$\begin{aligned}y &= y_h + y_p \\ &= (c_1 \cos(x) + c_2 \sin(x)) + (-2 + \sin(x) \ln(\sec(x) + \tan(x)))\end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 \cos(x) + c_2 \sin(x) - 2 + \sin(x) \ln(\sec(x) + \tan(x)) \quad (1)$$

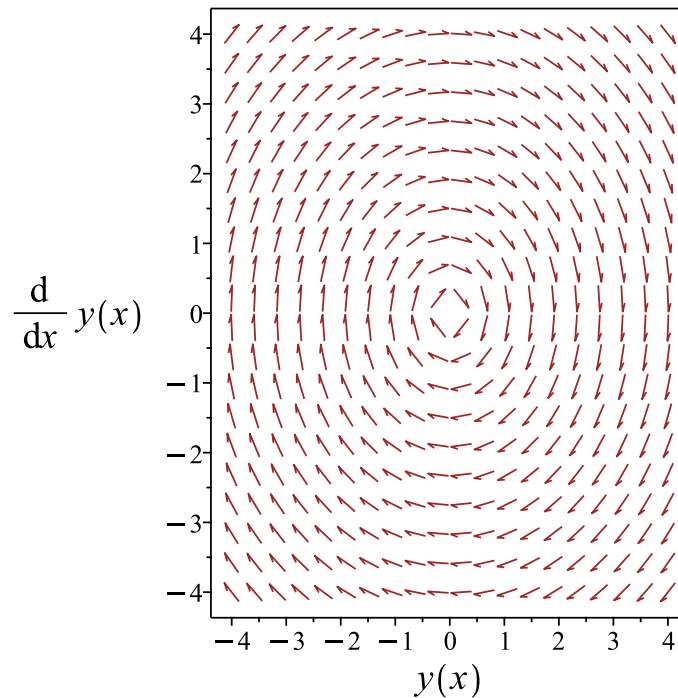


Figure 487: Slope field plot

Verification of solutions

$$y = c_1 \cos(x) + c_2 \sin(x) - 2 + \sin(x) \ln(\sec(x) + \tan(x))$$

Verified OK.

12.2.3 Maple step by step solution

Let's solve

$$y'' + y = \tan(x)^2$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of homogeneous ODE

$$r^2 + 1 = 0$$

- Use quadratic formula to solve for r

$$r = \frac{0 \pm (\sqrt{-4})}{2}$$

- Roots of the characteristic polynomial

$$r = (-I, I)$$

- 1st solution of the homogeneous ODE

$$y_1(x) = \cos(x)$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = \sin(x)$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = c_1 \cos(x) + c_2 \sin(x) + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = \tan(x)^2 \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} \cos(x) & \sin(x) \\ -\sin(x) & \cos(x) \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = 1$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = -\cos(x) \left(\int \sin(x) \tan(x)^2 dx \right) + \sin(x) \left(\int \sin(x) \tan(x) dx \right)$$

- Compute integrals

$$y_p(x) = -2 + \sin(x) \ln(\sec(x) + \tan(x))$$

- Substitute particular solution into general solution to ODE

$$y = c_1 \cos(x) + c_2 \sin(x) - 2 + \sin(x) \ln(\sec(x) + \tan(x))$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
trying a double symmetry of the form [xi=0, eta=F(x)]
-> Try solving first the homogeneous part of the ODE
    checking if the LODE has constant coefficients
    <- constant coefficients successful
<- solving first the homogeneous part of the ODE successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 23

```
dsolve(diff(y(x),x$2)+y(x)=tan(x)^2,y(x), singsol=all)
```

$$y(x) = \sin(x) c_2 + c_1 \cos(x) - 2 + \sin(x) \ln(\sec(x) + \tan(x))$$

✓ Solution by Mathematica

Time used: 0.124 (sec). Leaf size: 23

```
DSolve[y''[x]+y[x]==Tan[x]^2,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \sin(x) \operatorname{arctanh}(\sin(x)) + c_1 \cos(x) + c_2 \sin(x) - 2$$

12.3 problem 3

12.3.1 Solving as second order linear constant coeff ode	2881
12.3.2 Solving using Kovacic algorithm	2885
12.3.3 Maple step by step solution	2891

Internal problem ID [11831]

Internal file name [OUTPUT/11840_Thursday_April_11_2024_08_52_52_PM_64402138/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.4. Variation of parameters. Exercises page 162

Problem number: 3.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' + y = \sec(x)$$

12.3.1 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = 0, C = 1, f(x) = \sec(x)$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 0, C = 1$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 1 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 0, C = 1$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{0}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{0^2 - (4)(1)(1)} \\ &= \pm i \end{aligned}$$

Hence

$$\lambda_1 = +i$$

$$\lambda_2 = -i$$

Which simplifies to

$$\lambda_1 = i$$

$$\lambda_2 = -i$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = 0$ and $\beta = 1$. Therefore the final solution, when using Euler relation, can be written as

$$y = e^{\alpha x} (c_1 \cos(\beta x) + c_2 \sin(\beta x))$$

Which becomes

$$y = e^0 (c_1 \cos(x) + c_2 \sin(x))$$

Or

$$y = c_1 \cos(x) + c_2 \sin(x)$$

Therefore the homogeneous solution y_h is

$$y_h = c_1 \cos(x) + c_2 \sin(x)$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \cos(x)$$

$$y_2 = \sin(x)$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \cos(x) & \sin(x) \\ \frac{d}{dx}(\cos(x)) & \frac{d}{dx}(\sin(x)) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \cos(x) & \sin(x) \\ -\sin(x) & \cos(x) \end{vmatrix}$$

Therefore

$$W = (\cos(x))(\cos(x)) - (\sin(x))(-\sin(x))$$

Which simplifies to

$$W = \cos(x)^2 + \sin(x)^2$$

Which simplifies to

$$W = 1$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{\sin(x) \sec(x)}{1} dx$$

Which simplifies to

$$u_1 = - \int \tan(x) dx$$

Hence

$$u_1 = \ln(\cos(x))$$

And Eq. (3) becomes

$$u_2 = \int \frac{\cos(x) \sec(x)}{1} dx$$

Which simplifies to

$$u_2 = \int 1 dx$$

Hence

$$u_2 = x$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \ln(\cos(x)) \cos(x) + x \sin(x)$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 \cos(x) + c_2 \sin(x)) + (\ln(\cos(x)) \cos(x) + x \sin(x)) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 \cos(x) + c_2 \sin(x) + \ln(\cos(x)) \cos(x) + x \sin(x) \quad (1)$$

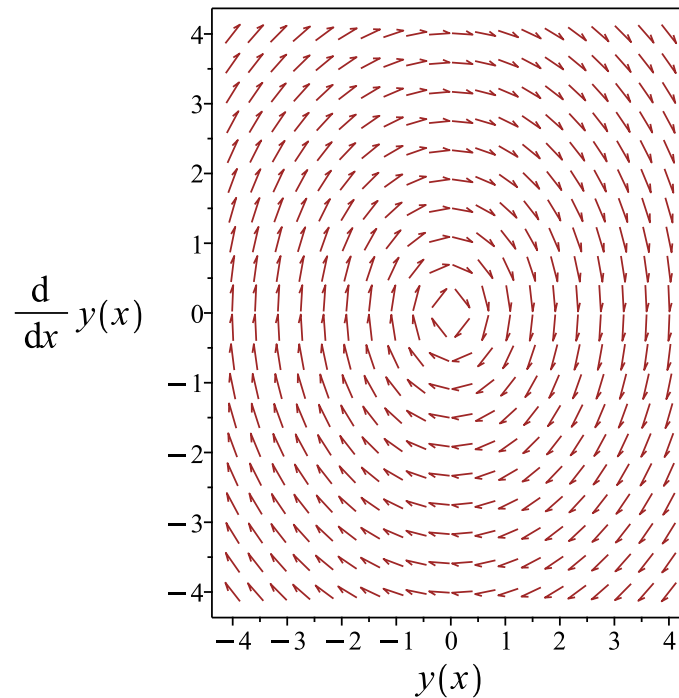


Figure 488: Slope field plot

Verification of solutions

$$y = c_1 \cos(x) + c_2 \sin(x) + \ln(\cos(x)) \cos(x) + x \sin(x)$$

Verified OK.

12.3.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' + y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$A = 1$$

$$B = 0 \quad (3)$$

$$C = 1$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-1}{1} \tag{6}$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= -1 \\ t &= 1 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = -z(x) \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 429: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned}
 \mathcal{O}(\infty) &= \deg(t) - \deg(s) \\
 &= 0 - 0 \\
 &= 0
 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = -1$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = \cos(x)$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$y_1 = z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx}$$

Since $B = 0$ then the above reduces to

$$\begin{aligned}
 y_1 &= z_1 \\
 &= \cos(x)
 \end{aligned}$$

Which simplifies to

$$y_1 = \cos(x)$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Since $B = 0$ then the above becomes

$$\begin{aligned} y_2 &= y_1 \int \frac{1}{y_1^2} dx \\ &= \cos(x) \int \frac{1}{\cos(x)^2} dx \\ &= \cos(x) (\tan(x)) \end{aligned}$$

Therefore the solution is

$$\begin{aligned} y &= c_1 y_1 + c_2 y_2 \\ &= c_1(\cos(x)) + c_2(\cos(x) (\tan(x))) \end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1 \cos(x) + c_2 \sin(x)$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of

parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \cos(x)$$

$$y_2 = \sin(x)$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \cos(x) & \sin(x) \\ \frac{d}{dx}(\cos(x)) & \frac{d}{dx}(\sin(x)) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \cos(x) & \sin(x) \\ -\sin(x) & \cos(x) \end{vmatrix}$$

Therefore

$$W = (\cos(x))(\cos(x)) - (\sin(x))(-\sin(x))$$

Which simplifies to

$$W = \cos(x)^2 + \sin(x)^2$$

Which simplifies to

$$W = 1$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{\sin(x) \sec(x)}{1} dx$$

Which simplifies to

$$u_1 = - \int \tan(x) dx$$

Hence

$$u_1 = \ln(\cos(x))$$

And Eq. (3) becomes

$$u_2 = \int \frac{\cos(x) \sec(x)}{1} dx$$

Which simplifies to

$$u_2 = \int 1 dx$$

Hence

$$u_2 = x$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \ln(\cos(x)) \cos(x) + x \sin(x)$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 \cos(x) + c_2 \sin(x)) + (\ln(\cos(x)) \cos(x) + x \sin(x)) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 \cos(x) + c_2 \sin(x) + \ln(\cos(x)) \cos(x) + x \sin(x) \quad (1)$$

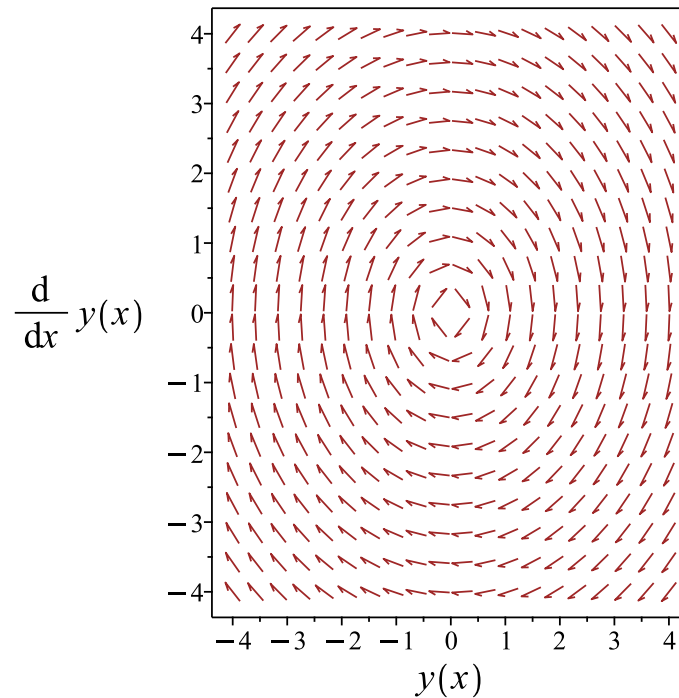


Figure 489: Slope field plot

Verification of solutions

$$y = c_1 \cos(x) + c_2 \sin(x) + \ln(\cos(x)) \cos(x) + x \sin(x)$$

Verified OK.

12.3.3 Maple step by step solution

Let's solve

$$y'' + y = \sec(x)$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of homogeneous ODE

$$r^2 + 1 = 0$$

- Use quadratic formula to solve for r

$$r = \frac{0 \pm (\sqrt{-4})}{2}$$

- Roots of the characteristic polynomial

$$r = (-I, I)$$

- 1st solution of the homogeneous ODE

$$y_1(x) = \cos(x)$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = \sin(x)$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = c_1 \cos(x) + c_2 \sin(x) + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x), y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x), y_2(x))} dx \right), f(x) = \sec(x) \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} \cos(x) & \sin(x) \\ -\sin(x) & \cos(x) \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = 1$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = -\cos(x) \left(\int \tan(x) dx \right) + \sin(x) \left(\int 1 dx \right)$$

- Compute integrals

$$y_p(x) = \ln(\cos(x)) \cos(x) + x \sin(x)$$

- Substitute particular solution into general solution to ODE

$$y = c_1 \cos(x) + c_2 \sin(x) + \ln(\cos(x)) \cos(x) + x \sin(x)$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]  
trying a double symmetry of the form [xi=0, eta=F(x)]  
-> Try solving first the homogeneous part of the ODE  
    checking if the LODE has constant coefficients  
    <- constant coefficients successful  
<- solving first the homogeneous part of the ODE successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 22

```
dsolve(diff(y(x),x$2)+y(x)=sec(x),y(x), singsol=all)
```

$$y(x) = -\ln(\sec(x)) \cos(x) + c_1 \cos(x) + \sin(x)(c_2 + x)$$

✓ Solution by Mathematica

Time used: 0.029 (sec). Leaf size: 22

```
DSolve[y''[x]+y[x]==Sec[x],y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow (x + c_2) \sin(x) + \cos(x)(\log(\cos(x)) + c_1)$$

12.4 problem 4

12.4.1 Solving as second order linear constant coeff ode	2894
12.4.2 Solving using Kovacic algorithm	2899
12.4.3 Maple step by step solution	2904

Internal problem ID [11832]

Internal file name [OUTPUT/11841_Thursday_April_11_2024_08_52_53_PM_17409633/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.4. Variation of parameters. Exercises page 162

Problem number: 4.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' + y = \sec(x)^3$$

12.4.1 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = 0, C = 1, f(x) = \sec(x)^3$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 0, C = 1$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 1 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 0, C = 1$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{0}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{0^2 - (4)(1)(1)} \\ &= \pm i \end{aligned}$$

Hence

$$\lambda_1 = +i$$

$$\lambda_2 = -i$$

Which simplifies to

$$\lambda_1 = i$$

$$\lambda_2 = -i$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = 0$ and $\beta = 1$. Therefore the final solution, when using Euler relation, can be written as

$$y = e^{\alpha x} (c_1 \cos(\beta x) + c_2 \sin(\beta x))$$

Which becomes

$$y = e^0 (c_1 \cos(x) + c_2 \sin(x))$$

Or

$$y = c_1 \cos(x) + c_2 \sin(x)$$

Therefore the homogeneous solution y_h is

$$y_h = c_1 \cos(x) + c_2 \sin(x)$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \cos(x)$$

$$y_2 = \sin(x)$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \cos(x) & \sin(x) \\ \frac{d}{dx}(\cos(x)) & \frac{d}{dx}(\sin(x)) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \cos(x) & \sin(x) \\ -\sin(x) & \cos(x) \end{vmatrix}$$

Therefore

$$W = (\cos(x))(\cos(x)) - (\sin(x))(-\sin(x))$$

Which simplifies to

$$W = \cos(x)^2 + \sin(x)^2$$

Which simplifies to

$$W = 1$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{\sin(x) \sec(x)^3}{1} dx$$

Which simplifies to

$$u_1 = - \int \tan(x) \sec(x)^2 dx$$

Hence

$$u_1 = - \frac{\sec(x)^2}{2}$$

And Eq. (3) becomes

$$u_2 = \int \frac{\cos(x) \sec(x)^3}{1} dx$$

Which simplifies to

$$u_2 = \int \sec(x)^2 dx$$

Hence

$$u_2 = \tan(x)$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = - \frac{\sec(x)^2 \cos(x)}{2} + \sin(x) \tan(x)$$

Which simplifies to

$$y_p(x) = - \cos(x) + \frac{\sec(x)}{2}$$

Therefore the general solution is

$$\begin{aligned}y &= y_h + y_p \\ &= (c_1 \cos(x) + c_2 \sin(x)) + \left(-\cos(x) + \frac{\sec(x)}{2}\right)\end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 \cos(x) + c_2 \sin(x) - \cos(x) + \frac{\sec(x)}{2} \quad (1)$$

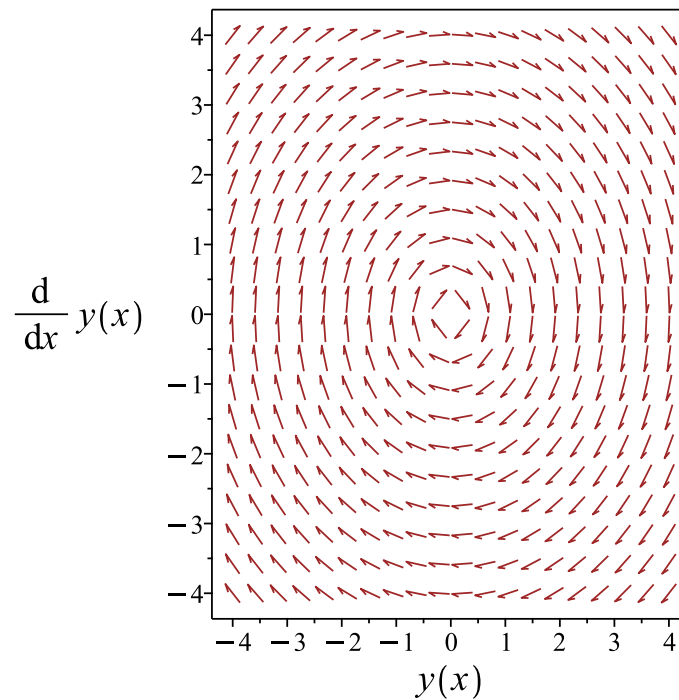


Figure 490: Slope field plot

Verification of solutions

$$y = c_1 \cos(x) + c_2 \sin(x) - \cos(x) + \frac{\sec(x)}{2}$$

Verified OK.

12.4.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' + y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= 0 \\ C &= 1 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-1}{1} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= -1 \\ t &= 1 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = -z(x) \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 431: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = -1$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = \cos(x)$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$y_1 = z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx}$$

Since $B = 0$ then the above reduces to

$$\begin{aligned}y_1 &= z_1 \\ &= \cos(x)\end{aligned}$$

Which simplifies to

$$y_1 = \cos(x)$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Since $B = 0$ then the above becomes

$$\begin{aligned}y_2 &= y_1 \int \frac{1}{y_1^2} dx \\ &= \cos(x) \int \frac{1}{\cos(x)^2} dx \\ &= \cos(x) (\tan(x))\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (\cos(x)) + c_2 (\cos(x) (\tan(x)))\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1 \cos(x) + c_2 \sin(x)$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \cos(x)$$

$$y_2 = \sin(x)$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \cos(x) & \sin(x) \\ \frac{d}{dx}(\cos(x)) & \frac{d}{dx}(\sin(x)) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \cos(x) & \sin(x) \\ -\sin(x) & \cos(x) \end{vmatrix}$$

Therefore

$$W = (\cos(x))(\cos(x)) - (\sin(x))(-\sin(x))$$

Which simplifies to

$$W = \cos(x)^2 + \sin(x)^2$$

Which simplifies to

$$W = 1$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{\sin(x) \sec(x)^3}{1} dx$$

Which simplifies to

$$u_1 = - \int \tan(x) \sec(x)^2 dx$$

Hence

$$u_1 = - \frac{\sec(x)^2}{2}$$

And Eq. (3) becomes

$$u_2 = \int \frac{\cos(x) \sec(x)^3}{1} dx$$

Which simplifies to

$$u_2 = \int \sec(x)^2 dx$$

Hence

$$u_2 = \tan(x)$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = - \frac{\sec(x)^2 \cos(x)}{2} + \sin(x) \tan(x)$$

Which simplifies to

$$y_p(x) = - \cos(x) + \frac{\sec(x)}{2}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 \cos(x) + c_2 \sin(x)) + \left(- \cos(x) + \frac{\sec(x)}{2} \right) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 \cos(x) + c_2 \sin(x) - \cos(x) + \frac{\sec(x)}{2} \quad (1)$$

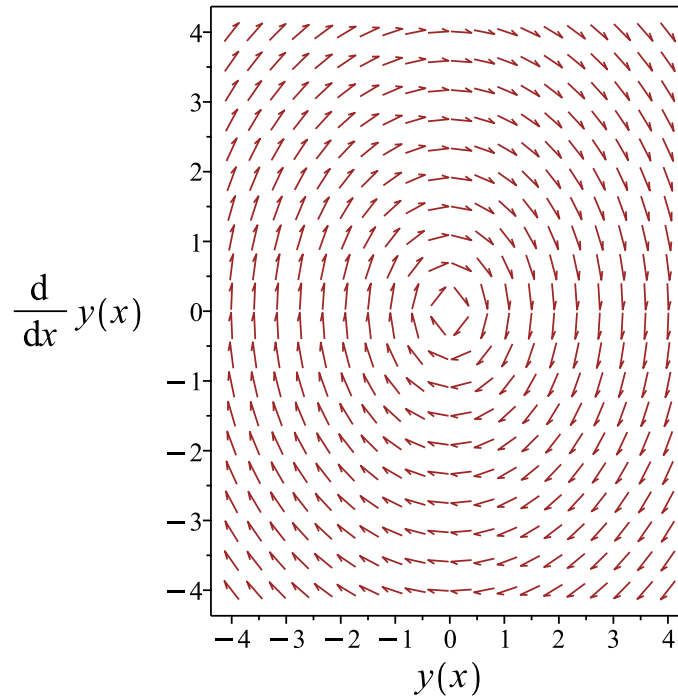


Figure 491: Slope field plot

Verification of solutions

$$y = c_1 \cos(x) + c_2 \sin(x) - \cos(x) + \frac{\sec(x)}{2}$$

Verified OK.

12.4.3 Maple step by step solution

Let's solve

$$y'' + y = \sec(x)^3$$

- Highest derivative means the order of the ODE is 2
- y''
- Characteristic polynomial of homogeneous ODE

$$r^2 + 1 = 0$$

- Use quadratic formula to solve for r

$$r = \frac{0 \pm (\sqrt{-4})}{2}$$

- Roots of the characteristic polynomial

$$r = (-I, I)$$

- 1st solution of the homogeneous ODE

$$y_1(x) = \cos(x)$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = \sin(x)$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = c_1 \cos(x) + c_2 \sin(x) + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x), y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x), y_2(x))} dx \right), f(x) = \sec(x)^3 \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} \cos(x) & \sin(x) \\ -\sin(x) & \cos(x) \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = 1$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = -\cos(x) \left(\int \tan(x) \sec(x)^2 dx \right) + \sin(x) \left(\int \sec(x)^2 dx \right)$$

- Compute integrals

$$y_p(x) = -\cos(x) + \frac{\sec(x)}{2}$$

- Substitute particular solution into general solution to ODE

$$y = c_1 \cos(x) + c_2 \sin(x) - \cos(x) + \frac{\sec(x)}{2}$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]  
trying a double symmetry of the form [xi=0, eta=F(x)]  
-> Try solving first the homogeneous part of the ODE  
    checking if the LODE has constant coefficients  
    <- constant coefficients successful  
<- solving first the homogeneous part of the ODE successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 19

```
dsolve(diff(y(x),x$2)+y(x)=sec(x)^3,y(x), singsol=all)
```

$$y(x) = (-1 + c_1) \cos(x) + \sin(x) c_2 + \frac{\sec(x)}{2}$$

✓ Solution by Mathematica

Time used: 0.065 (sec). Leaf size: 25

```
DSolve[y''[x]+y[x]==Sec[x]^3,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow -\frac{\sec(x)}{2} + c_1 \cos(x) + \sin(x)(\tan(x) + c_2)$$

12.5 problem 5

12.5.1 Solving as second order linear constant coeff ode	2907
12.5.2 Solving using Kovacic algorithm	2912
12.5.3 Maple step by step solution	2918

Internal problem ID [11833]

Internal file name [OUTPUT/11842_Thursday_April_11_2024_08_52_55_PM_82310885/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.4. Variation of parameters. Exercises page 162

Problem number: 5.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' + 4y = \sec(x)^2$$

12.5.1 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = 0, C = 4, f(x) = \sec(x)^2$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 4y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 0, C = 4$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + 4 e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 4 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 0, C = 4$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{0}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{0^2 - (4)(1)(4)} \\ &= \pm 2i \end{aligned}$$

Hence

$$\lambda_1 = +2i$$

$$\lambda_2 = -2i$$

Which simplifies to

$$\lambda_1 = 2i$$

$$\lambda_2 = -2i$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = 0$ and $\beta = 2$. Therefore the final solution, when using Euler relation, can be written as

$$y = e^{\alpha x} (c_1 \cos(\beta x) + c_2 \sin(\beta x))$$

Which becomes

$$y = e^0 (c_1 \cos(2x) + c_2 \sin(2x))$$

Or

$$y = c_1 \cos(2x) + c_2 \sin(2x)$$

Therefore the homogeneous solution y_h is

$$y_h = c_1 \cos(2x) + c_2 \sin(2x)$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \cos(2x)$$

$$y_2 = \sin(2x)$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \cos(2x) & \sin(2x) \\ \frac{d}{dx}(\cos(2x)) & \frac{d}{dx}(\sin(2x)) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \cos(2x) & \sin(2x) \\ -2 \sin(2x) & 2 \cos(2x) \end{vmatrix}$$

Therefore

$$W = (\cos(2x))(2 \cos(2x)) - (\sin(2x))(-2 \sin(2x))$$

Which simplifies to

$$W = 2 \cos (2x)^2 + 2 \sin (2x)^2$$

Which simplifies to

$$W = 2$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{\sin (2x) \sec (x)^2}{2} dx$$

Which simplifies to

$$u_1 = - \int \tan (x) dx$$

Hence

$$u_1 = \ln (\cos (x))$$

And Eq. (3) becomes

$$u_2 = \int \frac{\cos (2x) \sec (x)^2}{2} dx$$

Which simplifies to

$$u_2 = \int \frac{\cos (2x) \sec (x)^2}{2} dx$$

Hence

$$u_2 = x - \frac{\tan (x)}{2}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \ln (\cos (x)) \cos (2x) + \left(x - \frac{\tan (x)}{2} \right) \sin (2x)$$

Which simplifies to

$$y_p(x) = \ln (\cos (x)) (2 \cos (x)^2 - 1) + 2 \sin (x) \cos (x) x - \sin (x)^2$$

Therefore the general solution is

$$y = y_h + y_p \\ = (c_1 \cos(2x) + c_2 \sin(2x)) + (\ln(\cos(x))(2 \cos(x)^2 - 1) + 2 \sin(x) \cos(x)x - \sin(x)^2)$$

Summary

The solution(s) found are the following

$$y = c_1 \cos(2x) + c_2 \sin(2x) + \ln(\cos(x))(2 \cos(x)^2 - 1) + 2 \sin(x) \cos(x)x - \sin(x)^2 \quad (1)$$

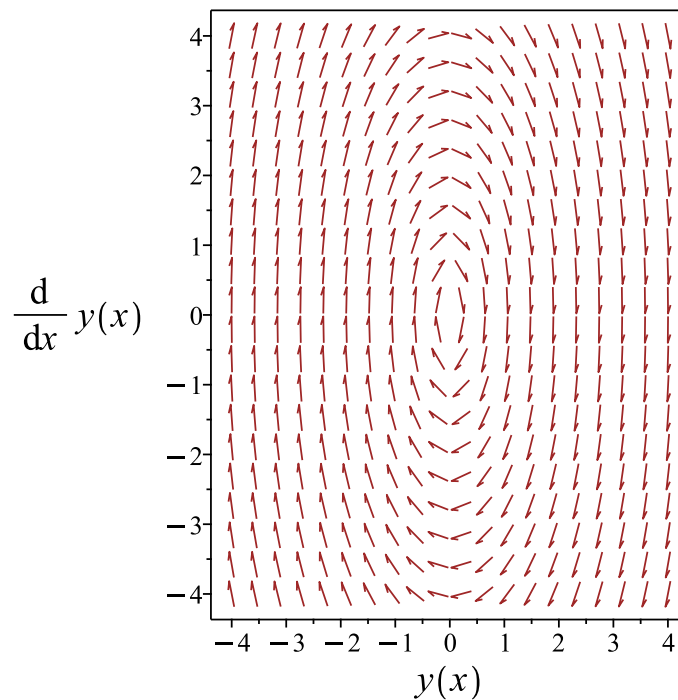


Figure 492: Slope field plot

Verification of solutions

$$y = c_1 \cos(2x) + c_2 \sin(2x) + \ln(\cos(x))(2 \cos(x)^2 - 1) + 2 \sin(x) \cos(x)x - \sin(x)^2$$

Verified OK.

12.5.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' + 4y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$A = 1$$

$$B = 0 \quad (3)$$

$$C = 4$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-4}{1} \quad (6)$$

Comparing the above to (5) shows that

$$s = -4$$

$$t = 1$$

Therefore eq. (4) becomes

$$z''(x) = -4z(x) \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 433: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = -4$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = \cos(2x)$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$y_1 = z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx}$$

Since $B = 0$ then the above reduces to

$$\begin{aligned}y_1 &= z_1 \\ &= \cos(2x)\end{aligned}$$

Which simplifies to

$$y_1 = \cos(2x)$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Since $B = 0$ then the above becomes

$$\begin{aligned}y_2 &= y_1 \int \frac{1}{y_1^2} dx \\ &= \cos(2x) \int \frac{1}{\cos(2x)^2} dx \\ &= \cos(2x) \left(\frac{\tan(2x)}{2} \right)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1(\cos(2x)) + c_2 \left(\cos(2x) \left(\frac{\tan(2x)}{2} \right) \right)\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$.
 y_h is the solution to

$$y'' + 4y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1 \cos(2x) + \frac{c_2 \sin(2x)}{2}$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \cos(2x)$$

$$y_2 = \frac{\sin(2x)}{2}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \cos(2x) & \frac{\sin(2x)}{2} \\ \frac{d}{dx}(\cos(2x)) & \frac{d}{dx}\left(\frac{\sin(2x)}{2}\right) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \cos(2x) & \frac{\sin(2x)}{2} \\ -2 \sin(2x) & \cos(2x) \end{vmatrix}$$

Therefore

$$W = (\cos(2x))(\cos(2x)) - \left(\frac{\sin(2x)}{2}\right)(-2\sin(2x))$$

Which simplifies to

$$W = \sin(2x)^2 + \cos(2x)^2$$

Which simplifies to

$$W = 1$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{\frac{\sin(2x)\sec(x)^2}{2}}{1} dx$$

Which simplifies to

$$u_1 = - \int \tan(x) dx$$

Hence

$$u_1 = \ln(\cos(x))$$

And Eq. (3) becomes

$$u_2 = \int \frac{\cos(2x)\sec(x)^2}{1} dx$$

Which simplifies to

$$u_2 = \int \cos(2x)\sec(x)^2 dx$$

Hence

$$u_2 = 2x - \tan(x)$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \ln(\cos(x))\cos(2x) + \frac{(2x - \tan(x))\sin(2x)}{2}$$

Which simplifies to

$$y_p(x) = \ln(\cos(x)) (2 \cos(x)^2 - 1) + 2 \sin(x) \cos(x) x - \sin(x)^2$$

Therefore the general solution is

$$y = y_h + y_p$$

$$= \left(c_1 \cos(2x) + \frac{c_2 \sin(2x)}{2} \right) + (\ln(\cos(x)) (2 \cos(x)^2 - 1) + 2 \sin(x) \cos(x) x - \sin(x)^2)$$

Summary

The solution(s) found are the following

$$y = c_1 \cos(2x) + \frac{c_2 \sin(2x)}{2} + \ln(\cos(x)) (2 \cos(x)^2 - 1) + 2 \sin(x) \cos(x) x - \sin(x)^2 \quad (1)$$

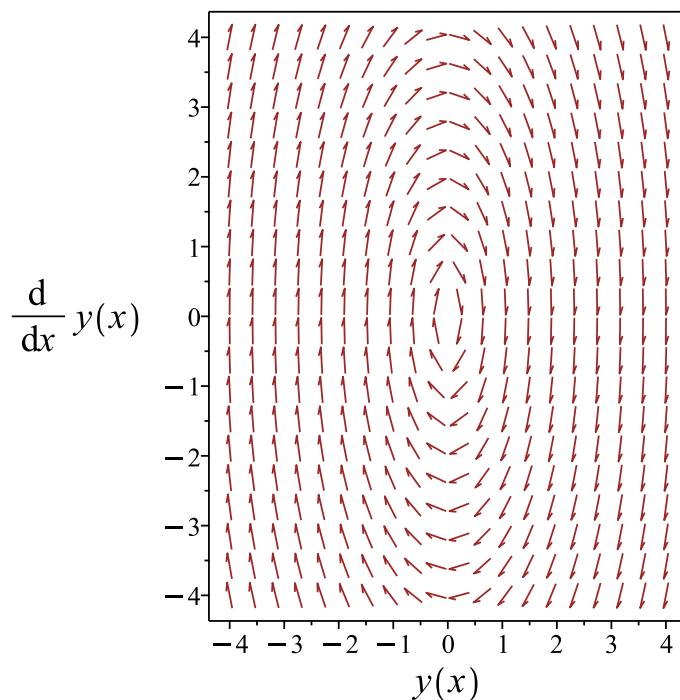


Figure 493: Slope field plot

Verification of solutions

$$y = c_1 \cos(2x) + \frac{c_2 \sin(2x)}{2} + \ln(\cos(x)) (2 \cos(x)^2 - 1) + 2 \sin(x) \cos(x) x - \sin(x)^2$$

Verified OK.

12.5.3 Maple step by step solution

Let's solve

$$y'' + 4y = \sec(x)^2$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of homogeneous ODE

$$r^2 + 4 = 0$$

- Use quadratic formula to solve for r

$$r = \frac{0 \pm (\sqrt{-16})}{2}$$

- Roots of the characteristic polynomial

$$r = (-2i, 2i)$$

- 1st solution of the homogeneous ODE

$$y_1(x) = \cos(2x)$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = \sin(2x)$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = c_1 \cos(2x) + c_2 \sin(2x) + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = \sec(x)^2 \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} \cos(2x) & \sin(2x) \\ -2\sin(2x) & 2\cos(2x) \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = 2$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = -\cos(2x) \left(\int \tan(x) dx \right) + \frac{\sin(2x) \left(\int \cos(2x) \sec(x)^2 dx \right)}{2}$$

- Compute integrals

$$y_p(x) = \ln(\cos(x)) (2 \cos(x)^2 - 1) + 2 \sin(x) \cos(x) x - \sin(x)^2$$

- Substitute particular solution into general solution to ODE

$$y = c_1 \cos(2x) + c_2 \sin(2x) + \ln(\cos(x)) (2 \cos(x)^2 - 1) + 2 \sin(x) \cos(x) x - \sin(x)^2$$

Maple trace

```

Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
trying a double symmetry of the form [xi=0, eta=F(x)]
-> Try solving first the homogeneous part of the ODE
    checking if the LODE has constant coefficients
    <- constant coefficients successful
<- solving first the homogeneous part of the ODE successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 42

```
dsolve(diff(y(x),x$2)+4*y(x)=sec(x)^2,y(x), singsol=all)
```

$$y(x) = (-2 \cos(x)^2 + 1) \ln(\sec(x)) + 2 \cos(x)^2 c_1 + 2 \sin(x) (c_2 + x) \cos(x) - \sin(x)^2 - c_1$$

✓ Solution by Mathematica

Time used: 0.098 (sec). Leaf size: 33

```
DSolve[y''[x]+4*y[x]==Sec[x]^2,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \cos(2x)(\log(\cos(x)) + c_1) + \sin(x)(-\sin(x) + 2(x + c_2) \cos(x))$$

12.6 problem 6

12.6.1 Solving as second order linear constant coeff ode	2920
12.6.2 Solving using Kovacic algorithm	2925
12.6.3 Maple step by step solution	2930

Internal problem ID [11834]

Internal file name [OUTPUT/11843_Thursday_April_11_2024_08_52_56_PM_90341025/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.4. Variation of parameters. Exercises page 162

Problem number: 6.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' + y = \sec(x) \tan(x)$$

12.6.1 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = 0, C = 1, f(x) = \sec(x) \tan(x)$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 0, C = 1$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 1 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 0, C = 1$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{0}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{0^2 - (4)(1)(1)} \\ &= \pm i \end{aligned}$$

Hence

$$\lambda_1 = +i$$

$$\lambda_2 = -i$$

Which simplifies to

$$\lambda_1 = i$$

$$\lambda_2 = -i$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = 0$ and $\beta = 1$. Therefore the final solution, when using Euler relation, can be written as

$$y = e^{\alpha x} (c_1 \cos(\beta x) + c_2 \sin(\beta x))$$

Which becomes

$$y = e^0 (c_1 \cos(x) + c_2 \sin(x))$$

Or

$$y = c_1 \cos(x) + c_2 \sin(x)$$

Therefore the homogeneous solution y_h is

$$y_h = c_1 \cos(x) + c_2 \sin(x)$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \cos(x)$$

$$y_2 = \sin(x)$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \cos(x) & \sin(x) \\ \frac{d}{dx}(\cos(x)) & \frac{d}{dx}(\sin(x)) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \cos(x) & \sin(x) \\ -\sin(x) & \cos(x) \end{vmatrix}$$

Therefore

$$W = (\cos(x))(\cos(x)) - (\sin(x))(-\sin(x))$$

Which simplifies to

$$W = \cos(x)^2 + \sin(x)^2$$

Which simplifies to

$$W = 1$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{\sin(x) \tan(x) \sec(x)}{1} dx$$

Which simplifies to

$$u_1 = - \int \tan(x)^2 dx$$

Hence

$$u_1 = - \tan(x) + x$$

And Eq. (3) becomes

$$u_2 = \int \frac{\cos(x) \sec(x) \tan(x)}{1} dx$$

Which simplifies to

$$u_2 = \int \tan(x) dx$$

Hence

$$u_2 = - \ln(\cos(x))$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = (- \tan(x) + x) \cos(x) - \ln(\cos(x)) \sin(x)$$

Which simplifies to

$$y_p(x) = - \ln(\cos(x)) \sin(x) - \sin(x) + \cos(x) x$$

Therefore the general solution is

$$\begin{aligned}y &= y_h + y_p \\ &= (c_1 \cos(x) + c_2 \sin(x)) + (-\ln(\cos(x)) \sin(x) - \sin(x) + \cos(x)x)\end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 \cos(x) + c_2 \sin(x) - \ln(\cos(x)) \sin(x) - \sin(x) + \cos(x)x \quad (1)$$

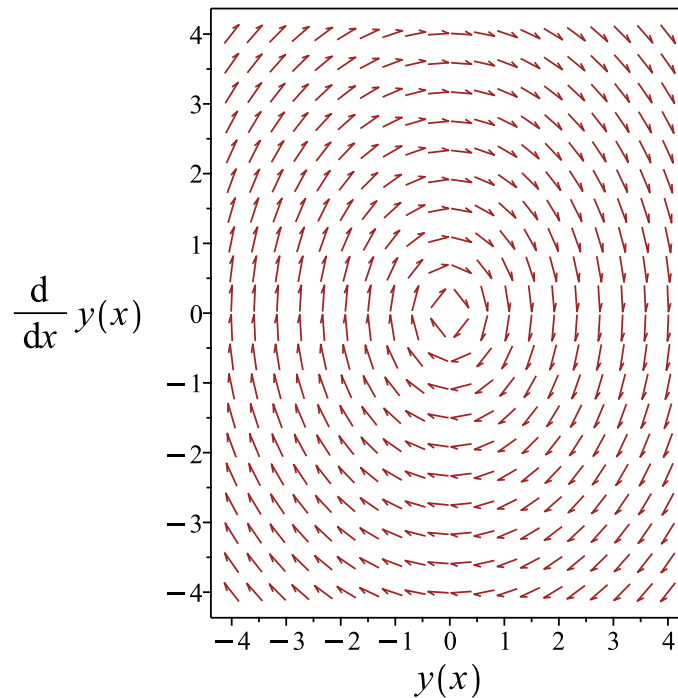


Figure 494: Slope field plot

Verification of solutions

$$y = c_1 \cos(x) + c_2 \sin(x) - \ln(\cos(x)) \sin(x) - \sin(x) + \cos(x)x$$

Verified OK.

12.6.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' + y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$A = 1$$

$$B = 0 \quad (3)$$

$$C = 1$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-1}{1} \quad (6)$$

Comparing the above to (5) shows that

$$s = -1$$

$$t = 1$$

Therefore eq. (4) becomes

$$z''(x) = -z(x) \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 435: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = -1$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = \cos(x)$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$y_1 = z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx}$$

Since $B = 0$ then the above reduces to

$$\begin{aligned}y_1 &= z_1 \\ &= \cos(x)\end{aligned}$$

Which simplifies to

$$y_1 = \cos(x)$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Since $B = 0$ then the above becomes

$$\begin{aligned}y_2 &= y_1 \int \frac{1}{y_1^2} dx \\ &= \cos(x) \int \frac{1}{\cos(x)^2} dx \\ &= \cos(x) (\tan(x))\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (\cos(x)) + c_2 (\cos(x) (\tan(x)))\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1 \cos(x) + c_2 \sin(x)$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \cos(x)$$

$$y_2 = \sin(x)$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \cos(x) & \sin(x) \\ \frac{d}{dx}(\cos(x)) & \frac{d}{dx}(\sin(x)) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \cos(x) & \sin(x) \\ -\sin(x) & \cos(x) \end{vmatrix}$$

Therefore

$$W = (\cos(x))(\cos(x)) - (\sin(x))(-\sin(x))$$

Which simplifies to

$$W = \cos(x)^2 + \sin(x)^2$$

Which simplifies to

$$W = 1$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{\sin(x) \tan(x) \sec(x)}{1} dx$$

Which simplifies to

$$u_1 = - \int \tan(x)^2 dx$$

Hence

$$u_1 = - \tan(x) + x$$

And Eq. (3) becomes

$$u_2 = \int \frac{\cos(x) \sec(x) \tan(x)}{1} dx$$

Which simplifies to

$$u_2 = \int \tan(x) dx$$

Hence

$$u_2 = - \ln(\cos(x))$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = (- \tan(x) + x) \cos(x) - \ln(\cos(x)) \sin(x)$$

Which simplifies to

$$y_p(x) = - \ln(\cos(x)) \sin(x) - \sin(x) + \cos(x) x$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 \cos(x) + c_2 \sin(x)) + (- \ln(\cos(x)) \sin(x) - \sin(x) + \cos(x) x) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 \cos(x) + c_2 \sin(x) - \ln(\cos(x)) \sin(x) - \sin(x) + \cos(x) x \quad (1)$$

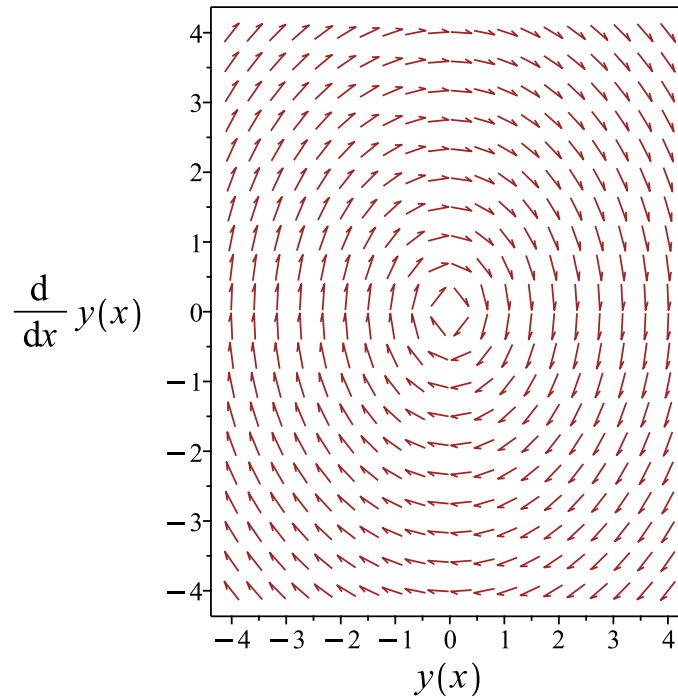


Figure 495: Slope field plot

Verification of solutions

$$y = c_1 \cos(x) + c_2 \sin(x) - \ln(\cos(x)) \sin(x) - \sin(x) + \cos(x) x$$

Verified OK.

12.6.3 Maple step by step solution

Let's solve

$$y'' + y = \sec(x) \tan(x)$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of homogeneous ODE

$$r^2 + 1 = 0$$

- Use quadratic formula to solve for r

$$r = \frac{0 \pm (\sqrt{-4})}{2}$$
- Roots of the characteristic polynomial

$$r = (-I, I)$$
- 1st solution of the homogeneous ODE

$$y_1(x) = \cos(x)$$
- 2nd solution of the homogeneous ODE

$$y_2(x) = \sin(x)$$
- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$
- Substitute in solutions of the homogeneous ODE

$$y = c_1 \cos(x) + c_2 \sin(x) + y_p(x)$$
- Find a particular solution $y_p(x)$ of the ODE
 - Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x), y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x), y_2(x))} dx \right), f(x) = \sec(x) \tan(x) \right]$$
 - Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} \cos(x) & \sin(x) \\ -\sin(x) & \cos(x) \end{bmatrix}$$
 - Compute Wronskian

$$W(y_1(x), y_2(x)) = 1$$
 - Substitute functions into equation for $y_p(x)$

$$y_p(x) = -\cos(x) \left(\int \tan(x)^2 dx \right) + \sin(x) \left(\int \tan(x) dx \right)$$
 - Compute integrals

$$y_p(x) = -\ln(\cos(x)) \sin(x) - \sin(x) + \cos(x) x$$
- Substitute particular solution into general solution to ODE

$$y = c_1 \cos(x) + c_2 \sin(x) - \ln(\cos(x)) \sin(x) - \sin(x) + \cos(x) x$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]  
trying a double symmetry of the form [xi=0, eta=F(x)]  
-> Try solving first the homogeneous part of the ODE  
    checking if the LODE has constant coefficients  
    <- constant coefficients successful  
<- solving first the homogeneous part of the ODE successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 23

```
dsolve(diff(y(x),x$2)+y(x)=tan(x)*sec(x),y(x), singsol=all)
```

$$y(x) = \ln(\sec(x)) \sin(x) + (c_2 - 1) \sin(x) + \cos(x) (c_1 + x)$$

✓ Solution by Mathematica

Time used: 0.039 (sec). Leaf size: 29

```
DSolve[y''[x]+y[x]==Tan[x]*Sec[x],y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \cos(x) \arctan(\tan(x)) + c_1 \cos(x) + \sin(x)(-\log(\cos(x)) - 1 + c_2)$$

12.7 problem 7

12.7.1 Solving as second order linear constant coeff ode	2933
12.7.2 Solving using Kovacic algorithm	2937
12.7.3 Maple step by step solution	2944

Internal problem ID [11835]

Internal file name [OUTPUT/11844_Thursday_April_11_2024_08_52_58_PM_35052809/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.4. Variation of parameters. Exercises page 162

Problem number: 7.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"kovacic", "second_order_linear_constant_coeff"**

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' + 4y' + 5y = e^{-2x} \sec(x)$$

12.7.1 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = 4, C = 5, f(x) = e^{-2x} \sec(x)$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 4y' + 5y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 4, C = 5$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + 4\lambda e^{\lambda x} + 5 e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 4\lambda + 5 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 4, C = 5$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{-4}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{4^2 - (4)(1)(5)} \\ &= -2 \pm i \end{aligned}$$

Hence

$$\lambda_1 = -2 + i$$

$$\lambda_2 = -2 - i$$

Which simplifies to

$$\lambda_1 = -2 + i$$

$$\lambda_2 = -2 - i$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = -2$ and $\beta = 1$. Therefore the final solution, when using Euler relation, can be written as

$$y = e^{\alpha x} (c_1 \cos(\beta x) + c_2 \sin(\beta x))$$

Which becomes

$$y = e^{-2x} (c_1 \cos(x) + c_2 \sin(x))$$

Therefore the homogeneous solution y_h is

$$y_h = e^{-2x} (c_1 \cos(x) + c_2 \sin(x))$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \cos(x) e^{-2x}$$

$$y_2 = e^{-2x} \sin(x)$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \cos(x) e^{-2x} & e^{-2x} \sin(x) \\ \frac{d}{dx}(\cos(x) e^{-2x}) & \frac{d}{dx}(e^{-2x} \sin(x)) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \cos(x) e^{-2x} & e^{-2x} \sin(x) \\ -e^{-2x} \sin(x) - 2 \cos(x) e^{-2x} & -2 e^{-2x} \sin(x) + \cos(x) e^{-2x} \end{vmatrix}$$

Therefore

$$W = (\cos(x) e^{-2x}) (-2 e^{-2x} \sin(x) + \cos(x) e^{-2x}) - (e^{-2x} \sin(x)) (-e^{-2x} \sin(x) - 2 \cos(x) e^{-2x})$$

Which simplifies to

$$W = e^{-4x} \cos(x)^2 + e^{-4x} \sin(x)^2$$

Which simplifies to

$$W = e^{-4x}$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{e^{-4x} \sin(x) \sec(x)}{e^{-4x}} dx$$

Which simplifies to

$$u_1 = - \int \tan(x) dx$$

Hence

$$u_1 = \ln(\cos(x))$$

And Eq. (3) becomes

$$u_2 = \int \frac{\cos(x) e^{-4x} \sec(x)}{e^{-4x}} dx$$

Which simplifies to

$$u_2 = \int 1 dx$$

Hence

$$u_2 = x$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \ln(\cos(x)) \cos(x) e^{-2x} + x e^{-2x} \sin(x)$$

Which simplifies to

$$y_p(x) = e^{-2x} (\ln(\cos(x)) \cos(x) + x \sin(x))$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (e^{-2x}(c_1 \cos(x) + c_2 \sin(x))) + (e^{-2x}(\ln(\cos(x)) \cos(x) + x \sin(x))) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = e^{-2x}(c_1 \cos(x) + c_2 \sin(x)) + e^{-2x}(\ln(\cos(x)) \cos(x) + x \sin(x)) \quad (1)$$

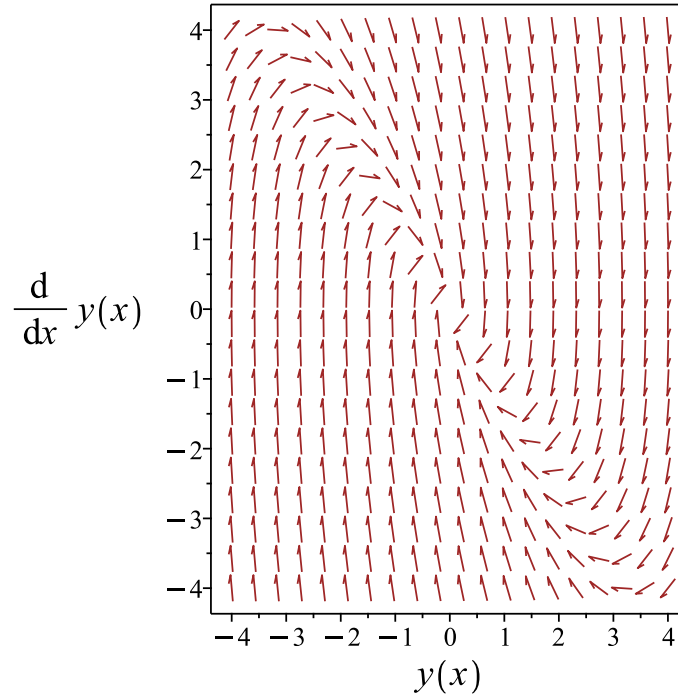


Figure 496: Slope field plot

Verification of solutions

$$y = e^{-2x}(c_1 \cos(x) + c_2 \sin(x)) + e^{-2x}(\ln(\cos(x)) \cos(x) + x \sin(x))$$

Verified OK.

12.7.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' + 4y' + 5y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$A = 1$$

$$B = 4 \quad (3)$$

$$C = 5$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-1}{1} \tag{6}$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= -1 \\ t &= 1 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = -z(x) \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 437: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned}
 \mathcal{O}(\infty) &= \deg(t) - \deg(s) \\
 &= 0 - 0 \\
 &= 0
 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = -1$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = \cos(x)$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned}
 y_1 &= z_1 e^{\int -\frac{1}{2} dx} \\
 &= z_1 e^{-\int \frac{1}{2} dx} \\
 &= z_1 e^{-2x} \\
 &= z_1 (e^{-2x})
 \end{aligned}$$

Which simplifies to

$$y_1 = \cos(x) e^{-2x}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{4}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{-4x}}{(y_1)^2} dx \\ &= y_1(\tan(x)) \end{aligned}$$

Therefore the solution is

$$\begin{aligned} y &= c_1 y_1 + c_2 y_2 \\ &= c_1(\cos(x) e^{-2x}) + c_2(\cos(x) e^{-2x}(\tan(x))) \end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 4y' + 5y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = e^{-2x} \cos(x) c_1 + c_2 e^{-2x} \sin(x)$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of

parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \cos(x) e^{-2x}$$

$$y_2 = e^{-2x} \sin(x)$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \cos(x) e^{-2x} & e^{-2x} \sin(x) \\ \frac{d}{dx}(\cos(x) e^{-2x}) & \frac{d}{dx}(e^{-2x} \sin(x)) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \cos(x) e^{-2x} & e^{-2x} \sin(x) \\ -e^{-2x} \sin(x) - 2 \cos(x) e^{-2x} & -2 e^{-2x} \sin(x) + \cos(x) e^{-2x} \end{vmatrix}$$

Therefore

$$W = (\cos(x) e^{-2x}) (-2 e^{-2x} \sin(x) + \cos(x) e^{-2x}) - (e^{-2x} \sin(x)) (-e^{-2x} \sin(x) - 2 \cos(x) e^{-2x})$$

Which simplifies to

$$W = e^{-4x} \cos(x)^2 + e^{-4x} \sin(x)^2$$

Which simplifies to

$$W = e^{-4x}$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{e^{-4x} \sin(x) \sec(x)}{e^{-4x}} dx$$

Which simplifies to

$$u_1 = - \int \tan(x) dx$$

Hence

$$u_1 = \ln(\cos(x))$$

And Eq. (3) becomes

$$u_2 = \int \frac{\cos(x) e^{-4x} \sec(x)}{e^{-4x}} dx$$

Which simplifies to

$$u_2 = \int 1 dx$$

Hence

$$u_2 = x$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \ln(\cos(x)) \cos(x) e^{-2x} + x e^{-2x} \sin(x)$$

Which simplifies to

$$y_p(x) = e^{-2x} (\ln(\cos(x)) \cos(x) + x \sin(x))$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (e^{-2x} \cos(x) c_1 + c_2 e^{-2x} \sin(x)) + (e^{-2x} (\ln(\cos(x)) \cos(x) + x \sin(x))) \end{aligned}$$

Which simplifies to

$$y = e^{-2x}(c_1 \cos(x) + c_2 \sin(x)) + e^{-2x}(\ln(\cos(x)) \cos(x) + x \sin(x))$$

Summary

The solution(s) found are the following

$$y = e^{-2x}(c_1 \cos(x) + c_2 \sin(x)) + e^{-2x}(\ln(\cos(x)) \cos(x) + x \sin(x)) \quad (1)$$

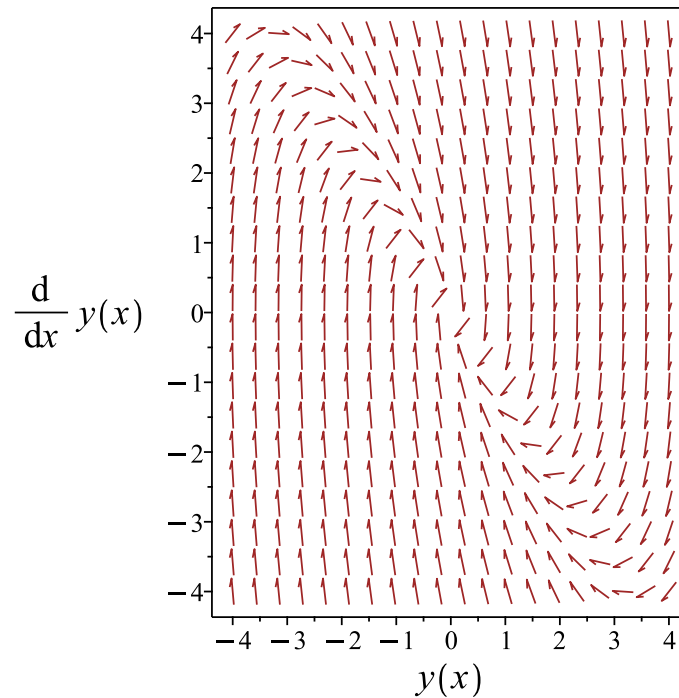


Figure 497: Slope field plot

Verification of solutions

$$y = e^{-2x}(c_1 \cos(x) + c_2 \sin(x)) + e^{-2x}(\ln(\cos(x)) \cos(x) + x \sin(x))$$

Verified OK.

12.7.3 Maple step by step solution

Let's solve

$$y'' + 4y' + 5y = e^{-2x} \sec(x)$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of homogeneous ODE

$$r^2 + 4r + 5 = 0$$

- Use quadratic formula to solve for r

$$r = \frac{(-4) \pm (\sqrt{-4})}{2}$$

- Roots of the characteristic polynomial

$$r = (-2 - I, -2 + I)$$

- 1st solution of the homogeneous ODE

$$y_1(x) = \cos(x) e^{-2x}$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = e^{-2x} \sin(x)$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = e^{-2x} \cos(x) c_1 + c_2 e^{-2x} \sin(x) + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = e^{-2x} \sec(x) \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} \cos(x) e^{-2x} & e^{-2x} \sin(x) \\ -e^{-2x} \sin(x) - 2 \cos(x) e^{-2x} & -2 e^{-2x} \sin(x) + \cos(x) e^{-2x} \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = e^{-4x}$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = -e^{-2x}(\cos(x) (\int \tan(x) dx) - \sin(x) (\int 1 dx))$$

- Compute integrals

$$y_p(x) = e^{-2x}(\ln(\cos(x)) \cos(x) + x \sin(x))$$

- Substitute particular solution into general solution to ODE

$$y = e^{-2x} \cos(x) c_1 + c_2 e^{-2x} \sin(x) + e^{-2x}(\ln(\cos(x)) \cos(x) + x \sin(x))$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
trying a double symmetry of the form [xi=0, eta=F(x)]
-> Try solving first the homogeneous part of the ODE
    checking if the LODE has constant coefficients
    <- constant coefficients successful
<- solving first the homogeneous part of the ODE successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 27

```
dsolve(diff(y(x),x$2)+4*diff(y(x),x)+5*y(x)=exp(-2*x)*sec(x),y(x), singsol=all)
```

$$y(x) = e^{-2x}(-\ln(\sec(x)) \cos(x) + c_1 \cos(x) + \sin(x)(c_2 + x))$$

✓ Solution by Mathematica

Time used: 0.048 (sec). Leaf size: 28

```
DSolve[y''[x]+4*y'[x]+5*y[x]==Exp[-2*x]*Sec[x],y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^{-2x}((x + c_1) \sin(x) + \cos(x)(\log(\cos(x)) + c_2))$$

12.8 problem 8

12.8.1 Solving as second order linear constant coeff ode	2946
12.8.2 Solving using Kovacic algorithm	2951
12.8.3 Maple step by step solution	2957

Internal problem ID [11836]

Internal file name [OUTPUT/11845_Thursday_April_11_2024_08_52_59_PM_69790256/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.4. Variation of parameters. Exercises page 162

Problem number: 8.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"kovacic", "second_order_linear_constant_coeff"**

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' - 2y' + 5y = e^x \tan(2x)$$

12.8.1 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = -2, C = 5, f(x) = e^x \tan(2x)$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' - 2y' + 5y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = -2, C = 5$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} - 2\lambda e^{\lambda x} + 5 e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 - 2\lambda + 5 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = -2, C = 5$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{2}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{-2^2 - (4)(1)(5)} \\ &= 1 \pm 2i \end{aligned}$$

Hence

$$\lambda_1 = 1 + 2i$$

$$\lambda_2 = 1 - 2i$$

Which simplifies to

$$\lambda_1 = 1 + 2i$$

$$\lambda_2 = 1 - 2i$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = 1$ and $\beta = 2$. Therefore the final solution, when using Euler relation, can be written as

$$y = e^{\alpha x} (c_1 \cos(\beta x) + c_2 \sin(\beta x))$$

Which becomes

$$y = e^x (c_1 \cos(2x) + c_2 \sin(2x))$$

Therefore the homogeneous solution y_h is

$$y_h = e^x (c_1 \cos(2x) + c_2 \sin(2x))$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = e^x \cos(2x)$$

$$y_2 = e^x \sin(2x)$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} e^x \cos(2x) & e^x \sin(2x) \\ \frac{d}{dx}(e^x \cos(2x)) & \frac{d}{dx}(e^x \sin(2x)) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} e^x \cos(2x) & e^x \sin(2x) \\ e^x \cos(2x) - 2e^x \sin(2x) & e^x \sin(2x) + 2e^x \cos(2x) \end{vmatrix}$$

Therefore

$$W = (e^x \cos(2x))(e^x \sin(2x) + 2e^x \cos(2x)) - (e^x \sin(2x))(e^x \cos(2x) - 2e^x \sin(2x))$$

Which simplifies to

$$W = 2e^{2x} \sin(2x)^2 + 2e^{2x} \cos(2x)^2$$

Which simplifies to

$$W = 2 e^{2x}$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{e^{2x} \sin(2x) \tan(2x)}{2 e^{2x}} dx$$

Which simplifies to

$$u_1 = - \int \frac{\sin(2x) \tan(2x)}{2} dx$$

Hence

$$u_1 = \frac{\sin(2x)}{4} - \frac{\ln(\sec(2x) + \tan(2x))}{4}$$

And Eq. (3) becomes

$$u_2 = \int \frac{e^{2x} \cos(2x) \tan(2x)}{2 e^{2x}} dx$$

Which simplifies to

$$u_2 = \int \frac{\sin(2x)}{2} dx$$

Hence

$$u_2 = -\frac{\cos(2x)}{4}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \left(\frac{\sin(2x)}{4} - \frac{\ln(\sec(2x) + \tan(2x))}{4} \right) e^x \cos(2x) - \frac{\cos(2x) e^x \sin(2x)}{4}$$

Which simplifies to

$$y_p(x) = -\frac{e^x \cos(2x) \ln(\sec(2x) + \tan(2x))}{4}$$

Therefore the general solution is

$$y = y_h + y_p$$

$$= (e^x(c_1 \cos(2x) + c_2 \sin(2x))) + \left(-\frac{e^x \cos(2x) \ln(\sec(2x) + \tan(2x))}{4} \right)$$

Summary

The solution(s) found are the following

$$y = e^x(c_1 \cos(2x) + c_2 \sin(2x)) - \frac{e^x \cos(2x) \ln(\sec(2x) + \tan(2x))}{4} \quad (1)$$

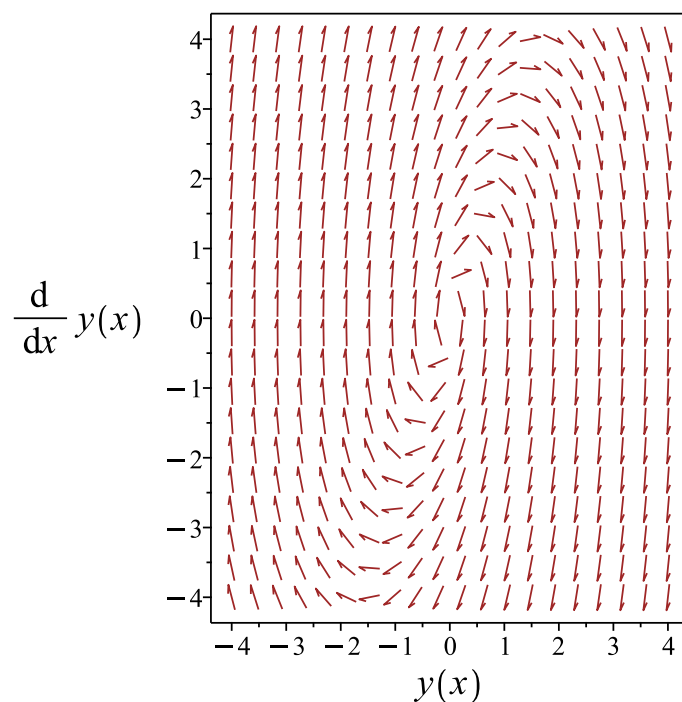


Figure 498: Slope field plot

Verification of solutions

$$y = e^x(c_1 \cos(2x) + c_2 \sin(2x)) - \frac{e^x \cos(2x) \ln(\sec(2x) + \tan(2x))}{4}$$

Verified OK.

12.8.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' - 2y' + 5y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= -2 \\ C &= 5 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-4}{1} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= -4 \\ t &= 1 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = -4z(x) \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 439: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = -4$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = \cos(2x)$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-2}{1} dx} \end{aligned}$$

$$\begin{aligned}
&= z_1 e^x \\
&= z_1 (e^x)
\end{aligned}$$

Which simplifies to

$$y_1 = e^x \cos(2x)$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}
y_2 &= y_1 \int \frac{e^{\int -\frac{-2}{1} dx}}{(y_1)^2} dx \\
&= y_1 \int \frac{e^{2x}}{(y_1)^2} dx \\
&= y_1 \left(\frac{\tan(2x)}{2} \right)
\end{aligned}$$

Therefore the solution is

$$\begin{aligned}
y &= c_1 y_1 + c_2 y_2 \\
&= c_1 (e^x \cos(2x)) + c_2 \left(e^x \cos(2x) \left(\frac{\tan(2x)}{2} \right) \right)
\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' - 2y' + 5y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = e^x \cos(2x) c_1 + \frac{e^x \sin(2x) c_2}{2}$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = e^x \cos(2x)$$

$$y_2 = \frac{e^x \sin(2x)}{2}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} e^x \cos(2x) & \frac{e^x \sin(2x)}{2} \\ \frac{d}{dx}(e^x \cos(2x)) & \frac{d}{dx}\left(\frac{e^x \sin(2x)}{2}\right) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} e^x \cos(2x) & \frac{e^x \sin(2x)}{2} \\ e^x \cos(2x) - 2e^x \sin(2x) & \frac{e^x \sin(2x)}{2} + e^x \cos(2x) \end{vmatrix}$$

Therefore

$$W = (e^x \cos(2x)) \left(\frac{e^x \sin(2x)}{2} + e^x \cos(2x) \right) - \left(\frac{e^x \sin(2x)}{2} \right) (e^x \cos(2x) - 2e^x \sin(2x))$$

Which simplifies to

$$W = e^{2x} \sin(2x)^2 + e^{2x} \cos(2x)^2$$

Which simplifies to

$$W = e^{2x}$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{\frac{e^{2x} \sin(2x) \tan(2x)}{2}}{e^{2x}} dx$$

Which simplifies to

$$u_1 = - \int \frac{\sin(2x) \tan(2x)}{2} dx$$

Hence

$$u_1 = \frac{\sin(2x)}{4} - \frac{\ln(\sec(2x) + \tan(2x))}{4}$$

And Eq. (3) becomes

$$u_2 = \int \frac{e^{2x} \cos(2x) \tan(2x)}{e^{2x}} dx$$

Which simplifies to

$$u_2 = \int \sin(2x) dx$$

Hence

$$u_2 = -\frac{\cos(2x)}{2}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \left(\frac{\sin(2x)}{4} - \frac{\ln(\sec(2x) + \tan(2x))}{4} \right) e^x \cos(2x) - \frac{\cos(2x) e^x \sin(2x)}{4}$$

Which simplifies to

$$y_p(x) = -\frac{e^x \cos(2x) \ln(\sec(2x) + \tan(2x))}{4}$$

Therefore the general solution is

$$y = y_h + y_p$$

$$= \left(e^x \cos(2x) c_1 + \frac{e^x \sin(2x) c_2}{2} \right) + \left(-\frac{e^x \cos(2x) \ln(\sec(2x) + \tan(2x))}{4} \right)$$

Summary

The solution(s) found are the following

$$y = e^x \cos(2x) c_1 + \frac{e^x \sin(2x) c_2}{2} - \frac{e^x \cos(2x) \ln(\sec(2x) + \tan(2x))}{4} \quad (1)$$

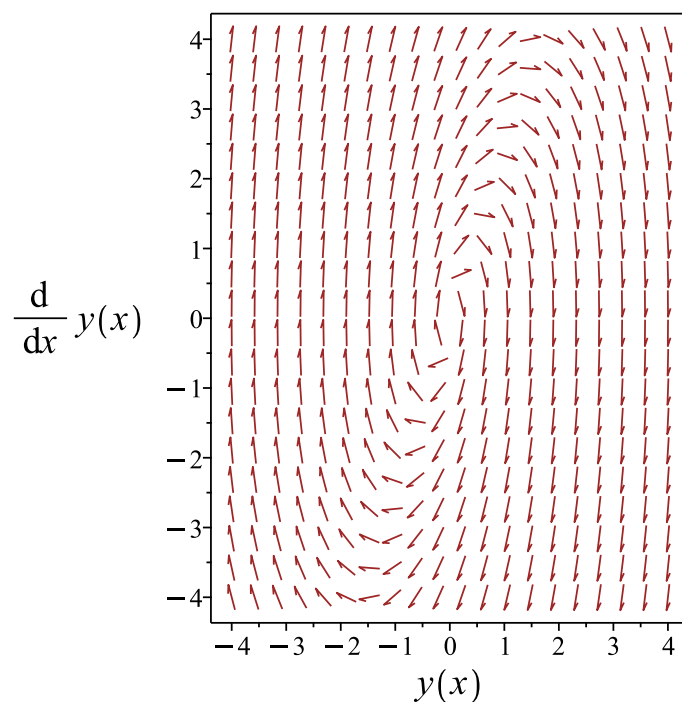


Figure 499: Slope field plot

Verification of solutions

$$y = e^x \cos(2x) c_1 + \frac{e^x \sin(2x) c_2}{2} - \frac{e^x \cos(2x) \ln(\sec(2x) + \tan(2x))}{4}$$

Verified OK.

12.8.3 Maple step by step solution

Let's solve

$$y'' - 2y' + 5y = e^x \tan(2x)$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of homogeneous ODE

$$r^2 - 2r + 5 = 0$$

- Use quadratic formula to solve for r

$$r = \frac{2 \pm (\sqrt{-16})}{2}$$

- Roots of the characteristic polynomial

$$r = (1 - 2i, 1 + 2i)$$

- 1st solution of the homogeneous ODE

$$y_1(x) = e^x \cos(2x)$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = e^x \sin(2x)$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = e^x \cos(2x) c_1 + e^x \sin(2x) c_2 + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = e^x \tan(2x) \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} e^x \cos(2x) & e^x \sin(2x) \\ e^x \cos(2x) - 2e^x \sin(2x) & e^x \sin(2x) + 2e^x \cos(2x) \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = 2e^{2x}$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = \frac{e^x(-\cos(2x)(\int \sin(2x) \tan(2x) dx) + \sin(2x)(\int \sin(2x) dx))}{2}$$

- Compute integrals

$$y_p(x) = -\frac{e^x \cos(2x) \ln(\sec(2x) + \tan(2x))}{4}$$

- Substitute particular solution into general solution to ODE

$$y = e^x \sin(2x) c_2 - \frac{e^x \cos(2x) \ln(\sec(2x) + \tan(2x))}{4} + e^x \cos(2x) c_1$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
trying a double symmetry of the form [xi=0, eta=F(x)]
-> Try solving first the homogeneous part of the ODE
    checking if the LODE has constant coefficients
    <- constant coefficients successful
<- solving first the homogeneous part of the ODE successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 39

```
dsolve(diff(y(x),x$2)-2*diff(y(x),x)+5*y(x)=exp(x)*tan(2*x),y(x), singsol=all)
```

$$y(x) = \frac{e^x(4c_2 \sin(2x) - \ln(\sec(2x) + \tan(2x)) \cos(2x) + 4 \cos(2x) c_1)}{4}$$

✓ Solution by Mathematica

Time used: 0.069 (sec). Leaf size: 42

```
DSolve[y''[x]-2*y'[x]+5*y[x]==Exp[x]*Tan[2*x],y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow -\frac{1}{4}e^x(\cos(2x)\operatorname{arctanh}(\sin(2x)) - 4c_2 \cos(2x) + (1 - 4c_1) \sin(2x))$$

12.9 problem 9

12.9.1 Solving as second order linear constant coeff ode	2959
12.9.2 Solving as linear second order ode solved by an integrating factor ode	2963
12.9.3 Solving using Kovacic algorithm	2965
12.9.4 Maple step by step solution	2971

Internal problem ID [11837]

Internal file name [OUTPUT/11846_Thursday_April_11_2024_08_53_00_PM_2401944/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.4. Variation of parameters. Exercises page 162

Problem number: 9.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff", "linear_second_order_ode_solved_by_an_integrating_factor"

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' + 6y' + 9y = \frac{e^{-3x}}{x^3}$$

12.9.1 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = 6, C = 9, f(x) = \frac{e^{-3x}}{x^3}$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 6y' + 9y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 6, C = 9$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + 6\lambda e^{\lambda x} + 9e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 6\lambda + 9 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 6, C = 9$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{-6}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{(6)^2 - (4)(1)(9)} \\ &= -3 \end{aligned}$$

Hence this is the case of a double root $\lambda_{1,2} = 3$. Therefore the solution is

$$y = c_1 e^{-3x} + c_2 x e^{-3x} \quad (1)$$

Therefore the homogeneous solution y_h is

$$y_h = c_1 e^{-3x} + c_2 x e^{-3x}$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$\begin{aligned} y_1 &= e^{-3x} \\ y_2 &= x e^{-3x} \end{aligned}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} e^{-3x} & x e^{-3x} \\ \frac{d}{dx}(e^{-3x}) & \frac{d}{dx}(x e^{-3x}) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} e^{-3x} & x e^{-3x} \\ -3e^{-3x} & e^{-3x} - 3x e^{-3x} \end{vmatrix}$$

Therefore

$$W = (e^{-3x})(e^{-3x} - 3x e^{-3x}) - (x e^{-3x})(-3e^{-3x})$$

Which simplifies to

$$W = e^{-6x}$$

Which simplifies to

$$W = e^{-6x}$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{\frac{e^{-6x}}{x^2}}{e^{-6x}} dx$$

Which simplifies to

$$u_1 = - \int \frac{1}{x^2} dx$$

Hence

$$u_1 = \frac{1}{x}$$

And Eq. (3) becomes

$$u_2 = \int \frac{\frac{e^{-6x}}{x^3}}{e^{-6x}} dx$$

Which simplifies to

$$u_2 = \int \frac{1}{x^3} dx$$

Hence

$$u_2 = -\frac{1}{2x^2}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \frac{e^{-3x}}{2x}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 e^{-3x} + c_2 x e^{-3x}) + \left(\frac{e^{-3x}}{2x} \right) \end{aligned}$$

Which simplifies to

$$y = e^{-3x}(c_2 x + c_1) + \frac{e^{-3x}}{2x}$$

Summary

The solution(s) found are the following

$$y = e^{-3x}(c_2 x + c_1) + \frac{e^{-3x}}{2x} \quad (1)$$

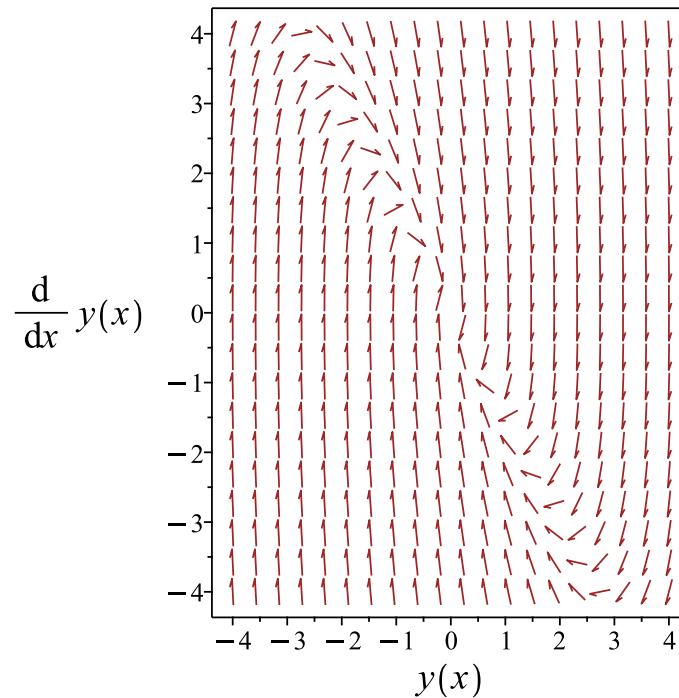


Figure 500: Slope field plot

Verification of solutions

$$y = e^{-3x}(c_2x + c_1) + \frac{e^{-3x}}{2x}$$

Verified OK.

12.9.2 Solving as linear second order ode solved by an integrating factor ode

The ode satisfies this form

$$y'' + p(x)y' + \frac{(p(x)^2 + p'(x))y}{2} = f(x)$$

Where $p(x) = 6$. Therefore, there is an integrating factor given by

$$\begin{aligned} M(x) &= e^{\frac{1}{2} \int p \, dx} \\ &= e^{\int 6 \, dx} \\ &= e^{3x} \end{aligned}$$

Multiplying both sides of the ODE by the integrating factor $M(x)$ makes the left side of the ODE a complete differential

$$(M(x)y)'' = \frac{e^{3x}e^{-3x}}{x^3}$$
$$(e^{3x}y)'' = \frac{e^{3x}e^{-3x}}{x^3}$$

Integrating once gives

$$(e^{3x}y)' = -\frac{1}{2x^2} + c_1$$

Integrating again gives

$$(e^{3x}y) = c_1x + \frac{1}{2x} + c_2$$

Hence the solution is

$$y = \frac{c_1x + \frac{1}{2x} + c_2}{e^{3x}}$$

Or

$$y = c_1x e^{-3x} + c_2e^{-3x} + \frac{e^{-3x}}{2x}$$

Summary

The solution(s) found are the following

$$y = c_1x e^{-3x} + c_2e^{-3x} + \frac{e^{-3x}}{2x} \quad (1)$$

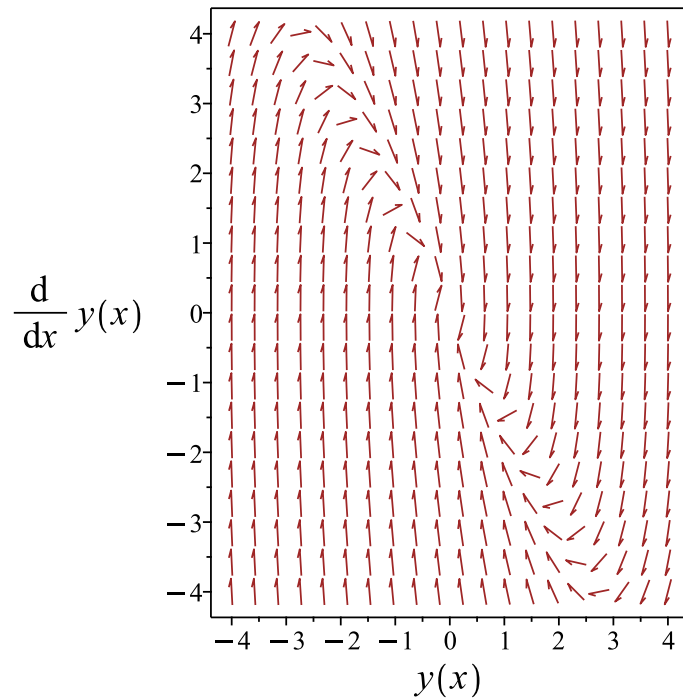


Figure 501: Slope field plot

Verification of solutions

$$y = c_1 x e^{-3x} + c_2 e^{-3x} + \frac{e^{-3x}}{2x}$$

Verified OK.

12.9.3 Solving using Kovacic algorithm

Writing the ode as

$$y'' + 6y' + 9y = 0 \tag{1}$$

$$Ay'' + By' + Cy = 0 \tag{2}$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= 6 \\ C &= 9 \end{aligned} \tag{3}$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$r = \frac{s}{t} = \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{0}{1} \tag{6}$$

Comparing the above to (5) shows that

$$s = 0$$

$$t = 1$$

Therefore eq. (4) becomes

$$z''(x) = 0 \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 441: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned}O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - -\infty \\ &= \infty\end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is *infinity* then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = 0$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = 1$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned}y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{6}{1} dx} \\ &= z_1 e^{-3x} \\ &= z_1 (e^{-3x})\end{aligned}$$

Which simplifies to

$$y_1 = e^{-3x}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{6}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{-6x}}{(y_1)^2} dx \\ &= y_1(x)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (e^{-3x}) + c_2 (e^{-3x}(x))\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 6y' + 9y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1 e^{-3x} + c_2 x e^{-3x}$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$\begin{aligned}y_1 &= e^{-3x} \\ y_2 &= x e^{-3x}\end{aligned}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \tag{2}$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \tag{3}$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} e^{-3x} & x e^{-3x} \\ \frac{d}{dx}(e^{-3x}) & \frac{d}{dx}(x e^{-3x}) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} e^{-3x} & x e^{-3x} \\ -3e^{-3x} & e^{-3x} - 3x e^{-3x} \end{vmatrix}$$

Therefore

$$W = (e^{-3x})(e^{-3x} - 3x e^{-3x}) - (x e^{-3x})(-3e^{-3x})$$

Which simplifies to

$$W = e^{-6x}$$

Which simplifies to

$$W = e^{-6x}$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{\frac{e^{-6x}}{x^2}}{e^{-6x}} dx$$

Which simplifies to

$$u_1 = - \int \frac{1}{x^2} dx$$

Hence

$$u_1 = \frac{1}{x}$$

And Eq. (3) becomes

$$u_2 = \int \frac{\frac{e^{-6x}}{x^3}}{e^{-6x}} dx$$

Which simplifies to

$$u_2 = \int \frac{1}{x^3} dx$$

Hence

$$u_2 = -\frac{1}{2x^2}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \frac{e^{-3x}}{2x}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 e^{-3x} + c_2 x e^{-3x}) + \left(\frac{e^{-3x}}{2x} \right) \end{aligned}$$

Which simplifies to

$$y = e^{-3x}(c_2 x + c_1) + \frac{e^{-3x}}{2x}$$

Summary

The solution(s) found are the following

$$y = e^{-3x}(c_2 x + c_1) + \frac{e^{-3x}}{2x} \quad (1)$$

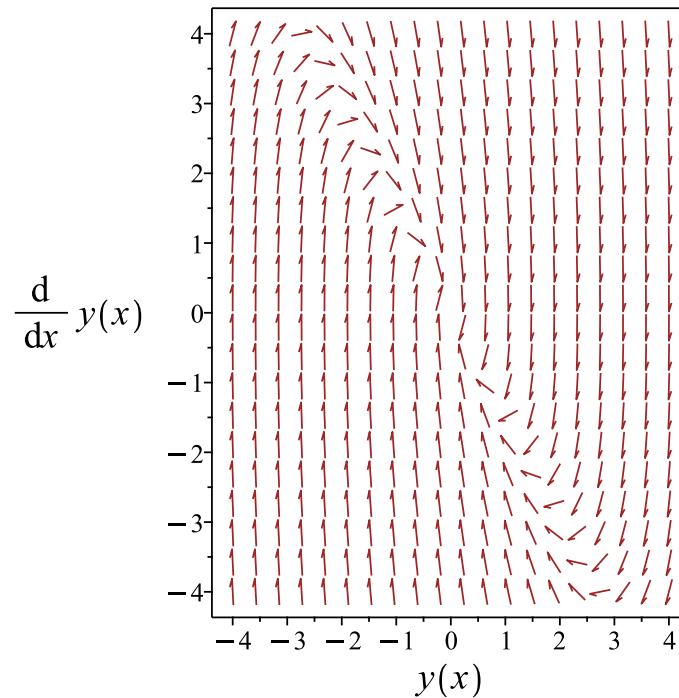


Figure 502: Slope field plot

Verification of solutions

$$y = e^{-3x}(c_2x + c_1) + \frac{e^{-3x}}{2x}$$

Verified OK.

12.9.4 Maple step by step solution

Let's solve

$$y'' + 6y' + 9y = \frac{e^{-3x}}{x^3}$$

- Highest derivative means the order of the ODE is 2
- $$y''$$
- Characteristic polynomial of homogeneous ODE
- $$r^2 + 6r + 9 = 0$$
- Factor the characteristic polynomial
- $$(r + 3)^2 = 0$$
- Root of the characteristic polynomial

$$r = -3$$

- 1st solution of the homogeneous ODE

$$y_1(x) = e^{-3x}$$

- Repeated root, multiply $y_1(x)$ by x to ensure linear independence

$$y_2(x) = x e^{-3x}$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = c_1 e^{-3x} + c_2 x e^{-3x} + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = \frac{e^{-3x}}{x^3} \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} e^{-3x} & x e^{-3x} \\ -3 e^{-3x} & e^{-3x} - 3x e^{-3x} \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = e^{-6x}$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = e^{-3x} \left(- \left(\int \frac{1}{x^2} dx \right) + \left(\int \frac{1}{x^3} dx \right) x \right)$$

- Compute integrals

$$y_p(x) = \frac{e^{-3x}}{2x}$$

- Substitute particular solution into general solution to ODE

$$y = c_1 e^{-3x} + c_2 x e^{-3x} + \frac{e^{-3x}}{2x}$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]  
trying a double symmetry of the form [xi=0, eta=F(x)]  
-> Try solving first the homogeneous part of the ODE  
    checking if the LODE has constant coefficients  
    <- constant coefficients successful  
<- solving first the homogeneous part of the ODE successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 25

```
dsolve(diff(y(x),x$2)+6*diff(y(x),x)+9*y(x)=exp(-3*x)/x^3,y(x), singsol=all)
```

$$y(x) = \frac{e^{-3x}(2c_1x^2 + 2c_2x + 1)}{2x}$$

✓ Solution by Mathematica

Time used: 0.03 (sec). Leaf size: 31

```
DSolve[y''[x]+6*y'[x]+9*y[x]==Exp[-3*x]/x^3,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{e^{-3x}(2c_2x^2 + 2c_1x + 1)}{2x}$$

12.10 problem 10

12.10.1 Solving as second order linear constant coeff ode	2974
12.10.2 Solving as linear second order ode solved by an integrating factor ode	2978
12.10.3 Solving using Kovacic algorithm	2980
12.10.4 Maple step by step solution	2986

Internal problem ID [11838]

Internal file name [OUTPUT/11847_Thursday_April_11_2024_08_53_01_PM_44895357/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.4. Variation of parameters. Exercises page 162

Problem number: 10.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff", "linear_second_order_ode_solved_by_an_integrating_factor"

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' - 2y' + y = x e^x \ln(x)$$

12.10.1 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = -2, C = 1, f(x) = x e^x \ln(x)$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' - 2y' + y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = -2, C = 1$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} - 2\lambda e^{\lambda x} + e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 - 2\lambda + 1 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = -2, C = 1$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{2}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{(-2)^2 - (4)(1)(1)} \\ &= 1 \end{aligned}$$

Hence this is the case of a double root $\lambda_{1,2} = -1$. Therefore the solution is

$$y = c_1 e^x + c_2 x e^x \quad (1)$$

Therefore the homogeneous solution y_h is

$$y_h = e^x c_1 + c_2 x e^x$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$\begin{aligned} y_1 &= e^x \\ y_2 &= x e^x \end{aligned}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} e^x & x e^x \\ \frac{d}{dx}(e^x) & \frac{d}{dx}(x e^x) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} e^x & x e^x \\ e^x & x e^x + e^x \end{vmatrix}$$

Therefore

$$W = (e^x)(x e^x + e^x) - (x e^x)(e^x)$$

Which simplifies to

$$W = e^{2x}$$

Which simplifies to

$$W = e^{2x}$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{x^2 e^{2x} \ln(x)}{e^{2x}} dx$$

Which simplifies to

$$u_1 = - \int x^2 \ln(x) dx$$

Hence

$$u_1 = -\frac{x^3 \ln(x)}{3} + \frac{x^3}{9}$$

And Eq. (3) becomes

$$u_2 = \int \frac{e^{2x} x \ln(x)}{e^{2x}} dx$$

Which simplifies to

$$u_2 = \int x \ln(x) dx$$

Hence

$$u_2 = \frac{x^2 \ln(x)}{2} - \frac{x^2}{4}$$

Which simplifies to

$$u_1 = -\frac{x^3(3 \ln(x) - 1)}{9}$$
$$u_2 = \frac{x^2(-1 + 2 \ln(x))}{4}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = -\frac{x^3(3 \ln(x) - 1) e^x}{9} + \frac{x^3(-1 + 2 \ln(x)) e^x}{4}$$

Which simplifies to

$$y_p(x) = \frac{x^3 e^x (-5 + 6 \ln(x))}{36}$$

Therefore the general solution is

$$y = y_h + y_p$$
$$= (e^x c_1 + c_2 x e^x) + \left(\frac{x^3 e^x (-5 + 6 \ln(x))}{36} \right)$$

Which simplifies to

$$y = e^x (c_2 x + c_1) + \frac{x^3 e^x (-5 + 6 \ln(x))}{36}$$

Summary

The solution(s) found are the following

$$y = e^x(c_2x + c_1) + \frac{x^3e^x(-5 + 6 \ln(x))}{36} \quad (1)$$

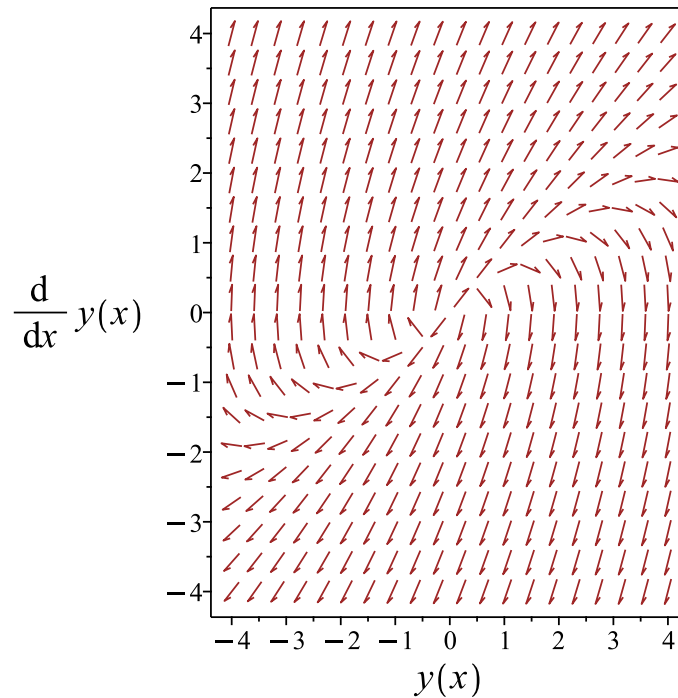


Figure 503: Slope field plot

Verification of solutions

$$y = e^x(c_2x + c_1) + \frac{x^3e^x(-5 + 6 \ln(x))}{36}$$

Verified OK.

12.10.2 Solving as linear second order ode solved by an integrating factor ode

The ode satisfies this form

$$y'' + p(x)y' + \frac{(p(x)^2 + p'(x))y}{2} = f(x)$$

Where $p(x) = -2$. Therefore, there is an integrating factor given by

$$\begin{aligned}M(x) &= e^{\frac{1}{2} \int p dx} \\ &= e^{\int -2 dx} \\ &= e^{-x}\end{aligned}$$

Multiplying both sides of the ODE by the integrating factor $M(x)$ makes the left side of the ODE a complete differential

$$\begin{aligned}(M(x)y)'' &= e^{-x} x e^x \ln(x) \\ (e^{-x}y)'' &= e^{-x} x e^x \ln(x)\end{aligned}$$

Integrating once gives

$$(e^{-x}y)' = \frac{x^2(-1 + 2 \ln(x))}{4} + c_1$$

Integrating again gives

$$(e^{-x}y) = -\frac{5x^3}{36} + \frac{x^3 \ln(x)}{6} + c_1x + c_2$$

Hence the solution is

$$y = \frac{-\frac{5x^3}{36} + \frac{x^3 \ln(x)}{6} + c_1x + c_2}{e^{-x}}$$

Or

$$y = \frac{x^3 e^x \ln(x)}{6} - \frac{5x^3 e^x}{36} + c_1 x e^x + c_2 e^x$$

Summary

The solution(s) found are the following

$$y = \frac{x^3 e^x \ln(x)}{6} - \frac{5x^3 e^x}{36} + c_1 x e^x + c_2 e^x \quad (1)$$

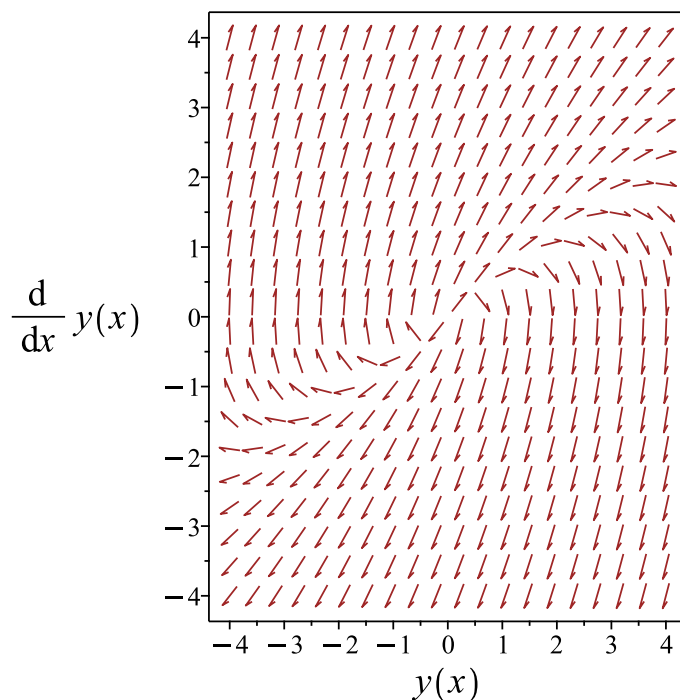


Figure 504: Slope field plot

Verification of solutions

$$y = \frac{x^3 e^x \ln(x)}{6} - \frac{5x^3 e^x}{36} + c_1 x e^x + c_2 e^x$$

Verified OK.

12.10.3 Solving using Kovacic algorithm

Writing the ode as

$$y'' - 2y' + y = 0 \tag{1}$$

$$Ay'' + By' + Cy = 0 \tag{2}$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= -2 \\ C &= 1 \end{aligned} \tag{3}$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$r = \frac{s}{t} \tag{5}$$

$$= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{0}{1} \tag{6}$$

Comparing the above to (5) shows that

$$s = 0$$

$$t = 1$$

Therefore eq. (4) becomes

$$z''(x) = 0 \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 443: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - -\infty \\ &= \infty \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is *infinity* then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = 0$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = 1$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-2}{1} dx} \\ &= z_1 e^x \\ &= z_1(e^x) \end{aligned}$$

Which simplifies to

$$y_1 = e^x$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{-2}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{2x}}{(y_1)^2} dx \\ &= y_1(x) \end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1(e^x) + c_2(e^x(x))\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' - 2y' + y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = e^x c_1 + c_2 x e^x$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$\begin{aligned}y_1 &= e^x \\ y_2 &= x e^x\end{aligned}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \tag{2}$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \tag{3}$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} e^x & x e^x \\ \frac{d}{dx}(e^x) & \frac{d}{dx}(x e^x) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} e^x & x e^x \\ e^x & x e^x + e^x \end{vmatrix}$$

Therefore

$$W = (e^x)(x e^x + e^x) - (x e^x)(e^x)$$

Which simplifies to

$$W = e^{2x}$$

Which simplifies to

$$W = e^{2x}$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{x^2 e^{2x} \ln(x)}{e^{2x}} dx$$

Which simplifies to

$$u_1 = - \int x^2 \ln(x) dx$$

Hence

$$u_1 = -\frac{x^3 \ln(x)}{3} + \frac{x^3}{9}$$

And Eq. (3) becomes

$$u_2 = \int \frac{e^{2x} x \ln(x)}{e^{2x}} dx$$

Which simplifies to

$$u_2 = \int x \ln(x) dx$$

Hence

$$u_2 = \frac{x^2 \ln(x)}{2} - \frac{x^2}{4}$$

Which simplifies to

$$u_1 = -\frac{x^3(3 \ln(x) - 1)}{9}$$
$$u_2 = \frac{x^2(-1 + 2 \ln(x))}{4}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = -\frac{x^3(3 \ln(x) - 1) e^x}{9} + \frac{x^3(-1 + 2 \ln(x)) e^x}{4}$$

Which simplifies to

$$y_p(x) = \frac{x^3 e^x (-5 + 6 \ln(x))}{36}$$

Therefore the general solution is

$$y = y_h + y_p$$
$$= (e^x c_1 + c_2 x e^x) + \left(\frac{x^3 e^x (-5 + 6 \ln(x))}{36} \right)$$

Which simplifies to

$$y = e^x (c_2 x + c_1) + \frac{x^3 e^x (-5 + 6 \ln(x))}{36}$$

Summary

The solution(s) found are the following

$$y = e^x (c_2 x + c_1) + \frac{x^3 e^x (-5 + 6 \ln(x))}{36} \quad (1)$$

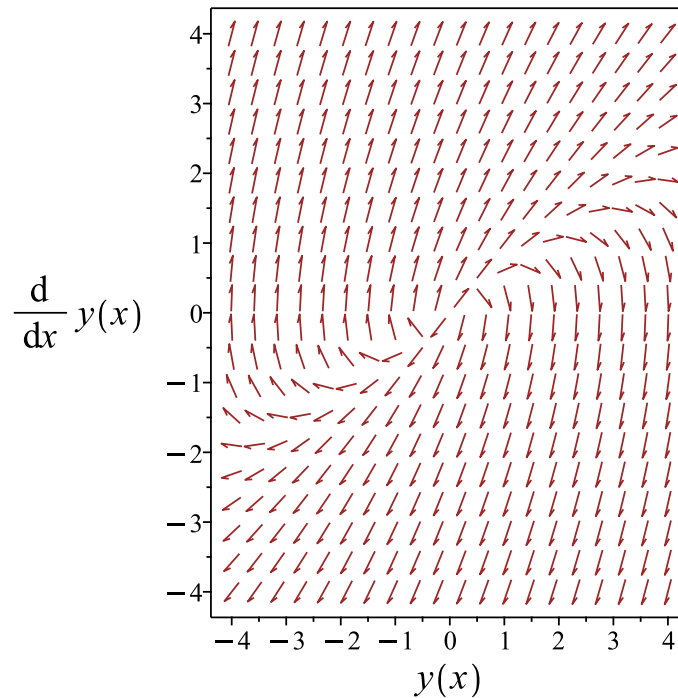


Figure 505: Slope field plot

Verification of solutions

$$y = e^x(c_2x + c_1) + \frac{x^3e^x(-5 + 6 \ln(x))}{36}$$

Verified OK.

12.10.4 Maple step by step solution

Let's solve

$$y'' - 2y' + y = xe^x \ln(x)$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of homogeneous ODE

$$r^2 - 2r + 1 = 0$$

- Factor the characteristic polynomial

$$(r - 1)^2 = 0$$

- Root of the characteristic polynomial

$$r = 1$$

- 1st solution of the homogeneous ODE

$$y_1(x) = e^x$$

- Repeated root, multiply $y_1(x)$ by x to ensure linear independence

$$y_2(x) = x e^x$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = e^x c_1 + c_2 x e^x + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = x e^x \ln(x) \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} e^x & x e^x \\ e^x & x e^x + e^x \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = e^{2x}$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = e^x \left(- \left(\int x^2 \ln(x) dx \right) + \left(\int x \ln(x) dx \right) x \right)$$

- Compute integrals

$$y_p(x) = \frac{x^3 e^x (-5 + 6 \ln(x))}{36}$$

- Substitute particular solution into general solution to ODE

$$y = e^x c_1 + c_2 x e^x + \frac{x^3 e^x (-5 + 6 \ln(x))}{36}$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]  
trying a double symmetry of the form [xi=0, eta=F(x)]  
-> Try solving first the homogeneous part of the ODE  
    checking if the LODE has constant coefficients  
    <- constant coefficients successful  
<- solving first the homogeneous part of the ODE successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 27

```
dsolve(diff(y(x),x$2)-2*diff(y(x),x)+y(x)=x*exp(x)*ln(x),y(x), singsol=all)
```

$$y(x) = \frac{\left(\ln(x) x^3 - \frac{5x^3}{6} + 6c_1x + 6c_2\right) e^x}{6}$$

✓ Solution by Mathematica

Time used: 0.028 (sec). Leaf size: 32

```
DSolve[y''[x]-2*y'[x]+y[x]==x*Exp[x]*Log[x],y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{1}{36} e^x (x^3(6 \log(x) - 5) + 36c_2x + 36c_1)$$

12.11 problem 11

12.11.1 Solving as second order linear constant coeff ode	2989
12.11.2 Solving using Kovacic algorithm	2993
12.11.3 Maple step by step solution	2999

Internal problem ID [11839]

Internal file name [OUTPUT/11848_Saturday_April_13_2024_01_12_48_AM_19754612/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.4. Variation of parameters. Exercises page 162

Problem number: 11.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"kovacic", "second_order_linear_constant_coeff"**

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' + y = \sec(x) \csc(x)$$

12.11.1 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = 0, C = 1, f(x) = \sec(x) \csc(x)$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 0, C = 1$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 1 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 0, C = 1$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{0}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{0^2 - (4)(1)(1)} \\ &= \pm i \end{aligned}$$

Hence

$$\lambda_1 = +i$$

$$\lambda_2 = -i$$

Which simplifies to

$$\lambda_1 = i$$

$$\lambda_2 = -i$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = 0$ and $\beta = 1$. Therefore the final solution, when using Euler relation, can be written as

$$y = e^{\alpha x} (c_1 \cos(\beta x) + c_2 \sin(\beta x))$$

Which becomes

$$y = e^0 (c_1 \cos(x) + c_2 \sin(x))$$

Or

$$y = c_1 \cos(x) + c_2 \sin(x)$$

Therefore the homogeneous solution y_h is

$$y_h = c_1 \cos(x) + c_2 \sin(x)$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \cos(x)$$

$$y_2 = \sin(x)$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \cos(x) & \sin(x) \\ \frac{d}{dx}(\cos(x)) & \frac{d}{dx}(\sin(x)) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \cos(x) & \sin(x) \\ -\sin(x) & \cos(x) \end{vmatrix}$$

Therefore

$$W = (\cos(x))(\cos(x)) - (\sin(x))(-\sin(x))$$

Which simplifies to

$$W = \cos(x)^2 + \sin(x)^2$$

Which simplifies to

$$W = 1$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{\sin(x) \sec(x) \csc(x)}{1} dx$$

Which simplifies to

$$u_1 = - \int \sec(x) dx$$

Hence

$$u_1 = - \ln(\sec(x) + \tan(x))$$

And Eq. (3) becomes

$$u_2 = \int \frac{\cos(x) \sec(x) \csc(x)}{1} dx$$

Which simplifies to

$$u_2 = \int \csc(x) dx$$

Hence

$$u_2 = - \ln(\csc(x) + \cot(x))$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = - \ln(\sec(x) + \tan(x)) \cos(x) - \ln(\csc(x) + \cot(x)) \sin(x)$$

Therefore the general solution is

$$y = y_h + y_p$$

$$= (c_1 \cos(x) + c_2 \sin(x)) + (- \ln(\sec(x) + \tan(x)) \cos(x) - \ln(\csc(x) + \cot(x)) \sin(x))$$

Summary

The solution(s) found are the following

$$y = c_1 \cos(x) + c_2 \sin(x) - \ln(\sec(x) + \tan(x)) \cos(x) - \ln(\csc(x) + \cot(x)) \sin(x)$$

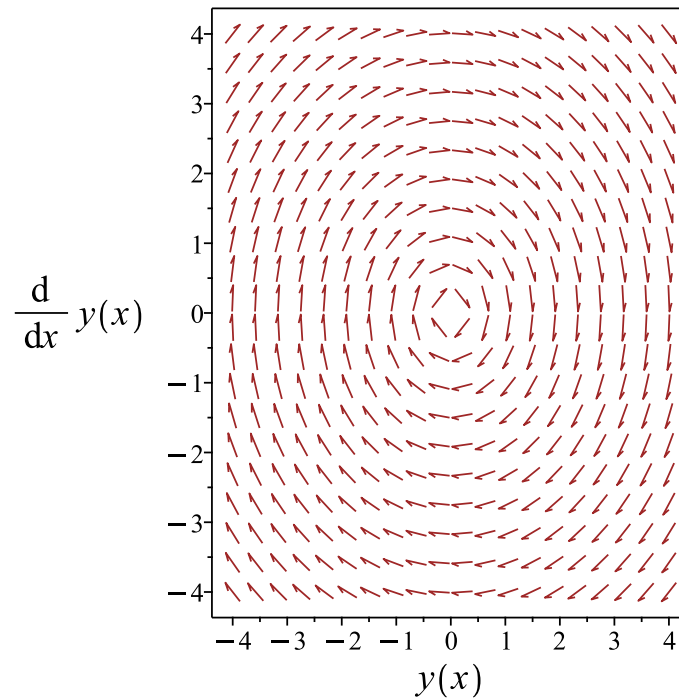


Figure 506: Slope field plot

Verification of solutions

$$y = c_1 \cos(x) + c_2 \sin(x) - \ln(\sec(x) + \tan(x)) \cos(x) - \ln(\csc(x) + \cot(x)) \sin(x)$$

Verified OK.

12.11.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' + y = 0 \tag{1}$$

$$Ay'' + By' + Cy = 0 \tag{2}$$

Comparing (1) and (2) shows that

$$A = 1$$

$$B = 0 \tag{3}$$

$$C = 1$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-1}{1} \tag{6}$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= -1 \\ t &= 1 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = -z(x) \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 445: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned}
 \mathcal{O}(\infty) &= \deg(t) - \deg(s) \\
 &= 0 - 0 \\
 &= 0
 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = -1$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = \cos(x)$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$y_1 = z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx}$$

Since $B = 0$ then the above reduces to

$$\begin{aligned}
 y_1 &= z_1 \\
 &= \cos(x)
 \end{aligned}$$

Which simplifies to

$$y_1 = \cos(x)$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Since $B = 0$ then the above becomes

$$\begin{aligned} y_2 &= y_1 \int \frac{1}{y_1^2} dx \\ &= \cos(x) \int \frac{1}{\cos(x)^2} dx \\ &= \cos(x) (\tan(x)) \end{aligned}$$

Therefore the solution is

$$\begin{aligned} y &= c_1 y_1 + c_2 y_2 \\ &= c_1(\cos(x)) + c_2(\cos(x) (\tan(x))) \end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1 \cos(x) + c_2 \sin(x)$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of

parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \cos(x)$$

$$y_2 = \sin(x)$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \cos(x) & \sin(x) \\ \frac{d}{dx}(\cos(x)) & \frac{d}{dx}(\sin(x)) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \cos(x) & \sin(x) \\ -\sin(x) & \cos(x) \end{vmatrix}$$

Therefore

$$W = (\cos(x))(\cos(x)) - (\sin(x))(-\sin(x))$$

Which simplifies to

$$W = \cos(x)^2 + \sin(x)^2$$

Which simplifies to

$$W = 1$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{\sin(x) \sec(x) \csc(x)}{1} dx$$

Which simplifies to

$$u_1 = - \int \sec(x) dx$$

Hence

$$u_1 = - \ln(\sec(x) + \tan(x))$$

And Eq. (3) becomes

$$u_2 = \int \frac{\cos(x) \sec(x) \csc(x)}{1} dx$$

Which simplifies to

$$u_2 = \int \csc(x) dx$$

Hence

$$u_2 = - \ln(\csc(x) + \cot(x))$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = - \ln(\sec(x) + \tan(x)) \cos(x) - \ln(\csc(x) + \cot(x)) \sin(x)$$

Therefore the general solution is

$$y = y_h + y_p$$

$$= (c_1 \cos(x) + c_2 \sin(x)) + (- \ln(\sec(x) + \tan(x)) \cos(x) - \ln(\csc(x) + \cot(x)) \sin(x))$$

Summary

The solution(s) found are the following

$$y = c_1 \cos(x) + c_2 \sin(x) - \ln(\sec(x) + \tan(x)) \cos(x) - \ln(\csc(x) + \cot(x)) \sin(x)$$

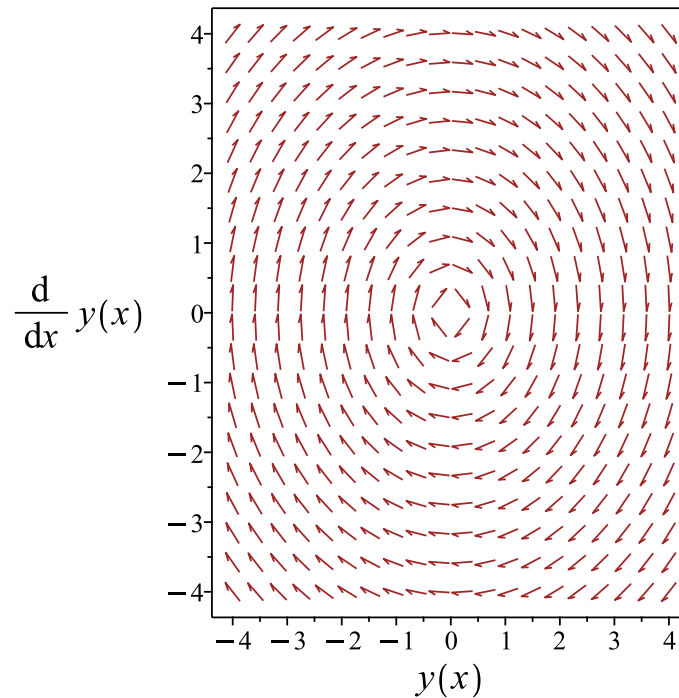


Figure 507: Slope field plot

Verification of solutions

$$y = c_1 \cos(x) + c_2 \sin(x) - \ln(\sec(x) + \tan(x)) \cos(x) - \ln(\csc(x) + \cot(x)) \sin(x)$$

Verified OK.

12.11.3 Maple step by step solution

Let's solve

$$y'' + y = \sec(x) \csc(x)$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of homogeneous ODE

$$r^2 + 1 = 0$$

- Use quadratic formula to solve for r

$$r = \frac{0 \pm (\sqrt{-4})}{2}$$

- Roots of the characteristic polynomial

$$r = (-I, I)$$

- 1st solution of the homogeneous ODE

$$y_1(x) = \cos(x)$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = \sin(x)$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = c_1 \cos(x) + c_2 \sin(x) + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = \sec(x) \csc(x) \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} \cos(x) & \sin(x) \\ -\sin(x) & \cos(x) \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = 1$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = -\cos(x) \left(\int \sec(x) dx \right) + \sin(x) \left(\int \csc(x) dx \right)$$

- Compute integrals

$$y_p(x) = -\ln(\sec(x) + \tan(x)) \cos(x) - \ln(\csc(x) + \cot(x)) \sin(x)$$

- Substitute particular solution into general solution to ODE

$$y = c_1 \cos(x) + c_2 \sin(x) - \ln(\sec(x) + \tan(x)) \cos(x) - \ln(\csc(x) + \cot(x)) \sin(x)$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]  
trying a double symmetry of the form [xi=0, eta=F(x)]  
-> Try solving first the homogeneous part of the ODE  
    checking if the LODE has constant coefficients  
    <- constant coefficients successful  
<- solving first the homogeneous part of the ODE successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 34

```
dsolve(diff(y(x),x$2)+y(x)=sec(x)*csc(x),y(x), singsol=all)
```

$$y(x) = \sin(x) c_2 + c_1 \cos(x) + \sin(x) \ln(\csc(x) - \cot(x)) - \cos(x) \ln(\sec(x) + \tan(x))$$

✓ Solution by Mathematica

Time used: 0.127 (sec). Leaf size: 30

```
DSolve[y''[x]+y[x]==Sec[x]*Csc[x],y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow -\sin(x) \operatorname{arctanh}(\cos(x)) + c_1 \cos(x) + c_2 \sin(x) + \cos(x) \left(-\operatorname{coth}^{-1}(\sin(x))\right)$$

12.12 problem 12

12.12.1 Solving as second order linear constant coeff ode	3002
12.12.2 Solving using Kovacic algorithm	3007
12.12.3 Maple step by step solution	3013

Internal problem ID [11840]

Internal file name [OUTPUT/11849_Saturday_April_13_2024_01_12_50_AM_16619352/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.4. Variation of parameters. Exercises page 162

Problem number: 12.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"kovacic", "second_order_linear_constant_coeff"**

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' + y = \tan(x)^3$$

12.12.1 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = 0, C = 1, f(x) = \tan(x)^3$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 0, C = 1$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 1 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 0, C = 1$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{0}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{0^2 - (4)(1)(1)} \\ &= \pm i \end{aligned}$$

Hence

$$\lambda_1 = +i$$

$$\lambda_2 = -i$$

Which simplifies to

$$\lambda_1 = i$$

$$\lambda_2 = -i$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = 0$ and $\beta = 1$. Therefore the final solution, when using Euler relation, can be written as

$$y = e^{\alpha x} (c_1 \cos(\beta x) + c_2 \sin(\beta x))$$

Which becomes

$$y = e^0 (c_1 \cos(x) + c_2 \sin(x))$$

Or

$$y = c_1 \cos(x) + c_2 \sin(x)$$

Therefore the homogeneous solution y_h is

$$y_h = c_1 \cos(x) + c_2 \sin(x)$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \cos(x)$$

$$y_2 = \sin(x)$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \cos(x) & \sin(x) \\ \frac{d}{dx}(\cos(x)) & \frac{d}{dx}(\sin(x)) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \cos(x) & \sin(x) \\ -\sin(x) & \cos(x) \end{vmatrix}$$

Therefore

$$W = (\cos(x))(\cos(x)) - (\sin(x))(-\sin(x))$$

Which simplifies to

$$W = \cos(x)^2 + \sin(x)^2$$

Which simplifies to

$$W = 1$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{\sin(x) \tan(x)^3}{1} dx$$

Which simplifies to

$$u_1 = - \int \sin(x) \tan(x)^3 dx$$

Hence

$$u_1 = -\frac{\sin(x)^5}{2 \cos(x)^2} - \frac{\sin(x)^3}{2} - \frac{3 \sin(x)}{2} + \frac{3 \ln(\sec(x) + \tan(x))}{2}$$

And Eq. (3) becomes

$$u_2 = \int \frac{\cos(x) \tan(x)^3}{1} dx$$

Which simplifies to

$$u_2 = \int \sin(x) \tan(x)^2 dx$$

Hence

$$u_2 = \frac{\sin(x)^4}{\cos(x)} + (2 + \sin(x)^2) \cos(x)$$

Which simplifies to

$$u_1 = -\sin(x) + \frac{3 \ln(\sec(x) + \tan(x))}{2} - \frac{\sec(x) \tan(x)}{2}$$

$$u_2 = \cos(x) + \sec(x)$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \left(-\sin(x) + \frac{3 \ln(\sec(x) + \tan(x))}{2} - \frac{\sec(x) \tan(x)}{2} \right) \cos(x) + (\cos(x) + \sec(x)) \sin(x)$$

Which simplifies to

$$y_p(x) = \frac{3 \ln(\sec(x) + \tan(x)) \cos(x)}{2} + \frac{\tan(x)}{2}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 \cos(x) + c_2 \sin(x)) + \left(\frac{3 \ln(\sec(x) + \tan(x)) \cos(x)}{2} + \frac{\tan(x)}{2} \right) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 \cos(x) + c_2 \sin(x) + \frac{3 \ln(\sec(x) + \tan(x)) \cos(x)}{2} + \frac{\tan(x)}{2} \quad (1)$$

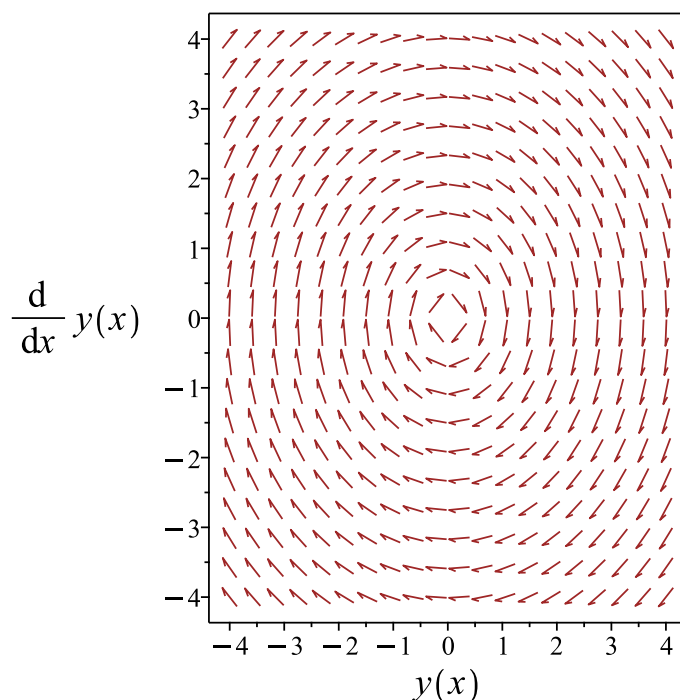


Figure 508: Slope field plot

Verification of solutions

$$y = c_1 \cos(x) + c_2 \sin(x) + \frac{3 \ln(\sec(x) + \tan(x)) \cos(x)}{2} + \frac{\tan(x)}{2}$$

Verified OK.

12.12.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' + y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= 0 \\ C &= 1 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-1}{1} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= -1 \\ t &= 1 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = -z(x) \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 447: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = -1$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = \cos(x)$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$y_1 = z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx}$$

Since $B = 0$ then the above reduces to

$$\begin{aligned} y_1 &= z_1 \\ &= \cos(x) \end{aligned}$$

Which simplifies to

$$y_1 = \cos(x)$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Since $B = 0$ then the above becomes

$$\begin{aligned} y_2 &= y_1 \int \frac{1}{y_1^2} dx \\ &= \cos(x) \int \frac{1}{\cos(x)^2} dx \\ &= \cos(x) (\tan(x)) \end{aligned}$$

Therefore the solution is

$$\begin{aligned} y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (\cos(x)) + c_2 (\cos(x) (\tan(x))) \end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1 \cos(x) + c_2 \sin(x)$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \cos(x)$$

$$y_2 = \sin(x)$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \cos(x) & \sin(x) \\ \frac{d}{dx}(\cos(x)) & \frac{d}{dx}(\sin(x)) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \cos(x) & \sin(x) \\ -\sin(x) & \cos(x) \end{vmatrix}$$

Therefore

$$W = (\cos(x))(\cos(x)) - (\sin(x))(-\sin(x))$$

Which simplifies to

$$W = \cos(x)^2 + \sin(x)^2$$

Which simplifies to

$$W = 1$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{\sin(x) \tan(x)^3}{1} dx$$

Which simplifies to

$$u_1 = - \int \sin(x) \tan(x)^3 dx$$

Hence

$$u_1 = -\frac{\sin(x)^5}{2 \cos(x)^2} - \frac{\sin(x)^3}{2} - \frac{3 \sin(x)}{2} + \frac{3 \ln(\sec(x) + \tan(x))}{2}$$

And Eq. (3) becomes

$$u_2 = \int \frac{\cos(x) \tan(x)^3}{1} dx$$

Which simplifies to

$$u_2 = \int \sin(x) \tan(x)^2 dx$$

Hence

$$u_2 = \frac{\sin(x)^4}{\cos(x)} + (2 + \sin(x)^2) \cos(x)$$

Which simplifies to

$$u_1 = -\sin(x) + \frac{3 \ln(\sec(x) + \tan(x))}{2} - \frac{\sec(x) \tan(x)}{2}$$

$$u_2 = \cos(x) + \sec(x)$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \left(-\sin(x) + \frac{3 \ln(\sec(x) + \tan(x))}{2} - \frac{\sec(x) \tan(x)}{2} \right) \cos(x) + (\cos(x) + \sec(x)) \sin(x)$$

Which simplifies to

$$y_p(x) = \frac{3 \ln(\sec(x) + \tan(x)) \cos(x)}{2} + \frac{\tan(x)}{2}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 \cos(x) + c_2 \sin(x)) + \left(\frac{3 \ln(\sec(x) + \tan(x)) \cos(x)}{2} + \frac{\tan(x)}{2} \right) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 \cos(x) + c_2 \sin(x) + \frac{3 \ln(\sec(x) + \tan(x)) \cos(x)}{2} + \frac{\tan(x)}{2} \quad (1)$$

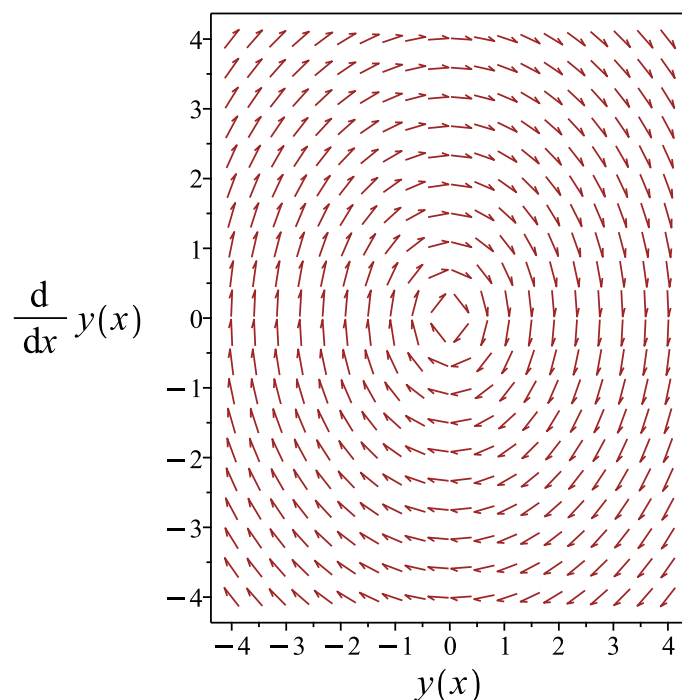


Figure 509: Slope field plot

Verification of solutions

$$y = c_1 \cos(x) + c_2 \sin(x) + \frac{3 \ln(\sec(x) + \tan(x)) \cos(x)}{2} + \frac{\tan(x)}{2}$$

Verified OK.

12.12.3 Maple step by step solution

Let's solve

$$y'' + y = \tan(x)^3$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of homogeneous ODE

$$r^2 + 1 = 0$$

- Use quadratic formula to solve for r

$$r = \frac{0 \pm (\sqrt{-4})}{2}$$

- Roots of the characteristic polynomial

$$r = (-I, I)$$

- 1st solution of the homogeneous ODE

$$y_1(x) = \cos(x)$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = \sin(x)$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = c_1 \cos(x) + c_2 \sin(x) + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = \tan(x)^3 \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} \cos(x) & \sin(x) \\ -\sin(x) & \cos(x) \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = 1$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = -\cos(x) \left(\int \sin(x) \tan(x)^3 dx \right) + \sin(x) \left(\int \sin(x) \tan(x)^2 dx \right)$$

- Compute integrals

$$y_p(x) = \frac{3 \ln(\sec(x) + \tan(x)) \cos(x)}{2} + \frac{\tan(x)}{2}$$

- Substitute particular solution into general solution to ODE

$$y = c_1 \cos(x) + c_2 \sin(x) + \frac{3 \ln(\sec(x) + \tan(x)) \cos(x)}{2} + \frac{\tan(x)}{2}$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
trying a double symmetry of the form [xi=0, eta=F(x)]
-> Try solving first the homogeneous part of the ODE
    checking if the LODE has constant coefficients
    <- constant coefficients successful
<- solving first the homogeneous part of the ODE successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 27

```
dsolve(diff(y(x), x$2)+y(x)=tan(x)^3, y(x), singsol=all)
```

$$y(x) = \sin(x) c_2 + c_1 \cos(x) + \frac{\tan(x)}{2} + \frac{3 \cos(x) \ln(\sec(x) + \tan(x))}{2}$$

✓ Solution by Mathematica

Time used: 0.078 (sec). Leaf size: 39

```
DSolve[y''[x]+y[x]==Tan[x]^3,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{1}{2} \sec(x) (3 \cos^2(x) \operatorname{arctanh}(\sin(x)) + \sin(x) + c_1 \cos(2x) + c_2 \sin(2x) + c_1)$$

12.13 problem 13

12.13.1 Solving as second order linear constant coeff ode	3016
12.13.2 Solving using Kovacic algorithm	3020
12.13.3 Maple step by step solution	3025

Internal problem ID [11841]

Internal file name [OUTPUT/11850_Saturday_April_13_2024_01_12_51_AM_33949059/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.4. Variation of parameters. Exercises page 162

Problem number: 13.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"kovacic", "second_order_linear_constant_coeff"**

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' + 3y' + 2y = \frac{1}{e^x + 1}$$

12.13.1 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = 3, C = 2, f(x) = \frac{1}{e^x + 1}$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 3y' + 2y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 3, C = 2$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + 3\lambda e^{\lambda x} + 2e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 3\lambda + 2 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 3, C = 2$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{-3}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{3^2 - (4)(1)(2)} \\ &= -\frac{3}{2} \pm \frac{1}{2} \end{aligned}$$

Hence

$$\begin{aligned} \lambda_1 &= -\frac{3}{2} + \frac{1}{2} \\ \lambda_2 &= -\frac{3}{2} - \frac{1}{2} \end{aligned}$$

Which simplifies to

$$\begin{aligned} \lambda_1 &= -1 \\ \lambda_2 &= -2 \end{aligned}$$

Since roots are real and distinct, then the solution is

$$\begin{aligned} y &= c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x} \\ y &= c_1 e^{(-1)x} + c_2 e^{(-2)x} \end{aligned}$$

Or

$$y = c_1 e^{-x} + c_2 e^{-2x}$$

Therefore the homogeneous solution y_h is

$$y_h = c_1 e^{-x} + c_2 e^{-2x}$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = e^{-x}$$

$$y_2 = e^{-2x}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} e^{-x} & e^{-2x} \\ \frac{d}{dx}(e^{-x}) & \frac{d}{dx}(e^{-2x}) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} e^{-x} & e^{-2x} \\ -e^{-x} & -2e^{-2x} \end{vmatrix}$$

Therefore

$$W = (e^{-x})(-2e^{-2x}) - (e^{-2x})(-e^{-x})$$

Which simplifies to

$$W = -e^{-x}e^{-2x}$$

Which simplifies to

$$W = -e^{-3x}$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{\frac{e^{-2x}}{e^x+1}}{-e^{-3x}} dx$$

Which simplifies to

$$u_1 = - \int -\frac{e^x}{e^x + 1} dx$$

Hence

$$u_1 = \ln(e^x + 1)$$

And Eq. (3) becomes

$$u_2 = \int \frac{\frac{e^{-x}}{e^x+1}}{-e^{-3x}} dx$$

Which simplifies to

$$u_2 = \int -\frac{e^{2x}}{e^x + 1} dx$$

Hence

$$u_2 = -e^x + \ln(e^x + 1)$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \ln(e^x + 1) e^{-x} + (-e^x + \ln(e^x + 1)) e^{-2x}$$

Which simplifies to

$$y_p(x) = (e^{-2x} + e^{-x}) \ln(e^x + 1) - e^{-x}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 e^{-x} + c_2 e^{-2x}) + ((e^{-2x} + e^{-x}) \ln(e^x + 1) - e^{-x}) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 e^{-x} + c_2 e^{-2x} + (e^{-2x} + e^{-x}) \ln(e^x + 1) - e^{-x} \quad (1)$$

Verification of solutions

$$y = c_1 e^{-x} + c_2 e^{-2x} + (e^{-2x} + e^{-x}) \ln(e^x + 1) - e^{-x}$$

Verified OK.

12.13.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' + 3y' + 2y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= 3 \\ C &= 2 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{1}{4} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 1 \\ t &= 4 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = \frac{z(x)}{4} \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 449: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} \mathcal{O}(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = \frac{1}{4}$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = e^{-\frac{x}{2}}$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned}y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\&= z_1 e^{-\int \frac{1}{2} \frac{3}{1} dx} \\&= z_1 e^{-\frac{3x}{2}} \\&= z_1 \left(e^{-\frac{3x}{2}} \right)\end{aligned}$$

Which simplifies to

$$y_1 = e^{-2x}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{3}{1} dx}}{(y_1)^2} dx \\&= y_1 \int \frac{e^{-3x}}{(y_1)^2} dx \\&= y_1 (e^x)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\&= c_1 (e^{-2x}) + c_2 (e^{-2x} (e^x))\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 3y' + 2y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1e^{-2x} + c_2e^{-x}$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1y_1 + u_2y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = e^{-2x}$$

$$y_2 = e^{-x}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} e^{-2x} & e^{-x} \\ \frac{d}{dx}(e^{-2x}) & \frac{d}{dx}(e^{-x}) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} e^{-2x} & e^{-x} \\ -2e^{-2x} & -e^{-x} \end{vmatrix}$$

Therefore

$$W = (e^{-2x})(-e^{-x}) - (e^{-x})(-2e^{-2x})$$

Which simplifies to

$$W = e^{-x}e^{-2x}$$

Which simplifies to

$$W = e^{-3x}$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{\frac{e^{-x}}{e^x+1}}{e^{-3x}} dx$$

Which simplifies to

$$u_1 = - \int \frac{e^{2x}}{e^x + 1} dx$$

Hence

$$u_1 = -e^x + \ln(e^x + 1)$$

And Eq. (3) becomes

$$u_2 = \int \frac{\frac{e^{-2x}}{e^x+1}}{e^{-3x}} dx$$

Which simplifies to

$$u_2 = \int \frac{e^x}{e^x + 1} dx$$

Hence

$$u_2 = \ln(e^x + 1)$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \ln(e^x + 1)e^{-x} + (-e^x + \ln(e^x + 1))e^{-2x}$$

Which simplifies to

$$y_p(x) = (e^{-2x} + e^{-x}) \ln(e^x + 1) - e^{-x}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 e^{-2x} + c_2 e^{-x}) + ((e^{-2x} + e^{-x}) \ln(e^x + 1) - e^{-x}) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 e^{-2x} + c_2 e^{-x} + (e^{-2x} + e^{-x}) \ln(e^x + 1) - e^{-x} \quad (1)$$

Verification of solutions

$$y = c_1 e^{-2x} + c_2 e^{-x} + (e^{-2x} + e^{-x}) \ln(e^x + 1) - e^{-x}$$

Verified OK.

12.13.3 Maple step by step solution

Let's solve

$$y'' + 3y' + 2y = \frac{1}{e^x + 1}$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of homogeneous ODE

$$r^2 + 3r + 2 = 0$$

- Factor the characteristic polynomial

$$(r + 2)(r + 1) = 0$$

- Roots of the characteristic polynomial

$$r = (-2, -1)$$

- 1st solution of the homogeneous ODE

$$y_1(x) = e^{-2x}$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = e^{-x}$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = c_1 e^{-2x} + c_2 e^{-x} + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = \frac{1}{e^x+1} \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} e^{-2x} & e^{-x} \\ -2e^{-2x} & -e^{-x} \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = e^{-3x}$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = -e^{-2x} \left(\int \frac{e^{2x}}{e^x+1} dx \right) + e^{-x} \left(\int \frac{e^x}{e^x+1} dx \right)$$

- Compute integrals

$$y_p(x) = (e^{-2x} + e^{-x}) \ln(e^x + 1) - e^{-x}$$

- Substitute particular solution into general solution to ODE

$$y = c_1 e^{-2x} + c_2 e^{-x} + (e^{-2x} + e^{-x}) \ln(e^x + 1) - e^{-x}$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
trying a double symmetry of the form [xi=0, eta=F(x)]
<- double symmetry of the form [xi=0, eta=F(x)] successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 36

```
dsolve(diff(y(x),x$2)+3*diff(y(x),x)+2*y(x)=1/(1+exp(x)),y(x), singsol=all)
```

$$y(x) = e^{-2x}(\ln(e^x + 1)(e^x + 1) - \ln(e^x)e^x + (c_2 + x)e^x - c_1)$$

✓ Solution by Mathematica

Time used: 0.074 (sec). Leaf size: 34

```
DSolve[y''[x]+3*y'[x]+2*y[x]==1/(1+Exp[x]),y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^{-2x}((e^x + 1) \log(e^x + 1) + (-1 + c_2)e^x + c_1)$$

12.14 problem 14

12.14.1 Solving as second order linear constant coeff ode	3028
12.14.2 Solving using Kovacic algorithm	3032
12.14.3 Maple step by step solution	3037

Internal problem ID [11842]

Internal file name [OUTPUT/11851_Saturday_April_13_2024_01_12_52_AM_47237680/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.4. Variation of parameters. Exercises page 162

Problem number: 14.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"kovacic", "second_order_linear_constant_coeff"**

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' + 3y' + 2y = \frac{1}{e^{2x} + 1}$$

12.14.1 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = 3, C = 2, f(x) = \frac{1}{e^{2x} + 1}$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 3y' + 2y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 3, C = 2$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + 3\lambda e^{\lambda x} + 2e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 3\lambda + 2 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 3, C = 2$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{-3}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{3^2 - (4)(1)(2)} \\ &= -\frac{3}{2} \pm \frac{1}{2} \end{aligned}$$

Hence

$$\begin{aligned} \lambda_1 &= -\frac{3}{2} + \frac{1}{2} \\ \lambda_2 &= -\frac{3}{2} - \frac{1}{2} \end{aligned}$$

Which simplifies to

$$\begin{aligned} \lambda_1 &= -1 \\ \lambda_2 &= -2 \end{aligned}$$

Since roots are real and distinct, then the solution is

$$\begin{aligned} y &= c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x} \\ y &= c_1 e^{(-1)x} + c_2 e^{(-2)x} \end{aligned}$$

Or

$$y = c_1 e^{-x} + c_2 e^{-2x}$$

Therefore the homogeneous solution y_h is

$$y_h = c_1 e^{-x} + c_2 e^{-2x}$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = e^{-x}$$

$$y_2 = e^{-2x}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} e^{-x} & e^{-2x} \\ \frac{d}{dx}(e^{-x}) & \frac{d}{dx}(e^{-2x}) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} e^{-x} & e^{-2x} \\ -e^{-x} & -2e^{-2x} \end{vmatrix}$$

Therefore

$$W = (e^{-x})(-2e^{-2x}) - (e^{-2x})(-e^{-x})$$

Which simplifies to

$$W = -e^{-x}e^{-2x}$$

Which simplifies to

$$W = -e^{-3x}$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{\frac{e^{-2x}}{e^{2x}+1}}{-e^{-3x}} dx$$

Which simplifies to

$$u_1 = - \int -\frac{e^x}{e^{2x} + 1} dx$$

Hence

$$u_1 = \arctan(e^x)$$

And Eq. (3) becomes

$$u_2 = \int \frac{\frac{e^{-x}}{e^{2x}+1}}{-e^{-3x}} dx$$

Which simplifies to

$$u_2 = \int -\frac{e^{2x}}{e^{2x} + 1} dx$$

Hence

$$u_2 = -\frac{\ln(e^{2x} + 1)}{2}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \arctan(e^x) e^{-x} - \frac{\ln(e^{2x} + 1) e^{-2x}}{2}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 e^{-x} + c_2 e^{-2x}) + \left(\arctan(e^x) e^{-x} - \frac{\ln(e^{2x} + 1) e^{-2x}}{2} \right) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 e^{-x} + c_2 e^{-2x} + \arctan(e^x) e^{-x} - \frac{\ln(e^{2x} + 1) e^{-2x}}{2} \quad (1)$$

Verification of solutions

$$y = c_1 e^{-x} + c_2 e^{-2x} + \arctan(e^x) e^{-x} - \frac{\ln(e^{2x} + 1) e^{-2x}}{2}$$

Verified OK.

12.14.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' + 3y' + 2y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= 3 \\ C &= 2 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{1}{4} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 1 \\ t &= 4 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = \frac{z(x)}{4} \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 451: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = \frac{1}{4}$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = e^{-\frac{x}{2}}$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{3}{1} dx} \\ &= z_1 e^{-\frac{3x}{2}} \\ &= z_1 \left(e^{-\frac{3x}{2}} \right) \end{aligned}$$

Which simplifies to

$$y_1 = e^{-2x}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{3}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{-3x}}{(y_1)^2} dx \\ &= y_1 (e^x) \end{aligned}$$

Therefore the solution is

$$\begin{aligned} y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (e^{-2x}) + c_2 (e^{-2x} (e^x)) \end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 3y' + 2y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1e^{-2x} + c_2e^{-x}$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1y_1 + u_2y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = e^{-2x}$$

$$y_2 = e^{-x}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} e^{-2x} & e^{-x} \\ \frac{d}{dx}(e^{-2x}) & \frac{d}{dx}(e^{-x}) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} e^{-2x} & e^{-x} \\ -2e^{-2x} & -e^{-x} \end{vmatrix}$$

Therefore

$$W = (e^{-2x})(-e^{-x}) - (e^{-x})(-2e^{-2x})$$

Which simplifies to

$$W = e^{-x}e^{-2x}$$

Which simplifies to

$$W = e^{-3x}$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{\frac{e^{-x}}{e^{2x}+1}}{e^{-3x}} dx$$

Which simplifies to

$$u_1 = - \int \frac{e^{2x}}{e^{2x} + 1} dx$$

Hence

$$u_1 = - \frac{\ln(e^{2x} + 1)}{2}$$

And Eq. (3) becomes

$$u_2 = \int \frac{\frac{e^{-2x}}{e^{2x}+1}}{e^{-3x}} dx$$

Which simplifies to

$$u_2 = \int \frac{e^x}{e^{2x} + 1} dx$$

Hence

$$u_2 = \arctan(e^x)$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \arctan(e^x) e^{-x} - \frac{\ln(e^{2x} + 1) e^{-2x}}{2}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 e^{-2x} + c_2 e^{-x}) + \left(\arctan(e^x) e^{-x} - \frac{\ln(e^{2x} + 1) e^{-2x}}{2} \right) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 e^{-2x} + c_2 e^{-x} + \arctan(e^x) e^{-x} - \frac{\ln(e^{2x} + 1) e^{-2x}}{2} \quad (1)$$

Verification of solutions

$$y = c_1 e^{-2x} + c_2 e^{-x} + \arctan(e^x) e^{-x} - \frac{\ln(e^{2x} + 1) e^{-2x}}{2}$$

Verified OK.

12.14.3 Maple step by step solution

Let's solve

$$y'' + 3y' + 2y = \frac{1}{e^{2x} + 1}$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of homogeneous ODE

$$r^2 + 3r + 2 = 0$$

- Factor the characteristic polynomial

$$(r + 2)(r + 1) = 0$$

- Roots of the characteristic polynomial

$$r = (-2, -1)$$

- 1st solution of the homogeneous ODE

$$y_1(x) = e^{-2x}$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = e^{-x}$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = c_1 e^{-2x} + c_2 e^{-x} + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = \frac{1}{e^{2x}+1} \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} e^{-2x} & e^{-x} \\ -2e^{-2x} & -e^{-x} \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = e^{-3x}$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = -e^{-2x} \left(\int \frac{e^{2x}}{e^{2x}+1} dx \right) + e^{-x} \left(\int \frac{e^x}{e^{2x}+1} dx \right)$$

- Compute integrals

$$y_p(x) = \arctan(e^x) e^{-x} - \frac{\ln(e^{2x}+1)e^{-2x}}{2}$$

- Substitute particular solution into general solution to ODE

$$y = c_1 e^{-2x} + c_2 e^{-x} + \arctan(e^x) e^{-x} - \frac{\ln(e^{2x}+1)e^{-2x}}{2}$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
trying a double symmetry of the form [xi=0, eta=F(x)]
<- double symmetry of the form [xi=0, eta=F(x)] successful`

```

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 38

```
dsolve(diff(y(x),x$2)+3*diff(y(x),x)+2*y(x)=1/(1+exp(2*x)),y(x), singsol=all)
```

$$y(x) = -\frac{(\ln(e^{2x} + 1)e^{-x} + 2c_1e^{-x} - 2\arctan(e^x) - 2c_2)e^{-x}}{2}$$

✓ Solution by Mathematica

Time used: 0.074 (sec). Leaf size: 45

```
DSolve[y''[x]+3*y'[x]+2*y[x]==1/(1+Exp[2*x]),y[x],x,IncludeSingularSolutions->True]
```

$$y(x) \rightarrow \frac{1}{2}e^{-2x}(2e^x \arctan(e^x) - \log(e^{2x} + 1) + 2(c_2e^x + c_1))$$

12.15 problem 15

12.15.1 Solving as second order linear constant coeff ode	3040
12.15.2 Solving using Kovacic algorithm	3045
12.15.3 Maple step by step solution	3050

Internal problem ID [11843]

Internal file name [OUTPUT/11852_Saturday_April_13_2024_01_12_52_AM_53610816/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.4. Variation of parameters. Exercises page 162

Problem number: 15.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff"

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' + y = \frac{1}{1 + \sin(x)}$$

12.15.1 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = 0, C = 1, f(x) = \frac{1}{1+\sin(x)}$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 0, C = 1$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 1 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 0, C = 1$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{0}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{0^2 - (4)(1)(1)} \\ &= \pm i \end{aligned}$$

Hence

$$\lambda_1 = +i$$

$$\lambda_2 = -i$$

Which simplifies to

$$\lambda_1 = i$$

$$\lambda_2 = -i$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = 0$ and $\beta = 1$. Therefore the final solution, when using Euler relation, can be written as

$$y = e^{\alpha x} (c_1 \cos(\beta x) + c_2 \sin(\beta x))$$

Which becomes

$$y = e^0 (c_1 \cos(x) + c_2 \sin(x))$$

Or

$$y = c_1 \cos(x) + c_2 \sin(x)$$

Therefore the homogeneous solution y_h is

$$y_h = c_1 \cos(x) + c_2 \sin(x)$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \cos(x)$$

$$y_2 = \sin(x)$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \cos(x) & \sin(x) \\ \frac{d}{dx}(\cos(x)) & \frac{d}{dx}(\sin(x)) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \cos(x) & \sin(x) \\ -\sin(x) & \cos(x) \end{vmatrix}$$

Therefore

$$W = (\cos(x))(\cos(x)) - (\sin(x))(-\sin(x))$$

Which simplifies to

$$W = \cos(x)^2 + \sin(x)^2$$

Which simplifies to

$$W = 1$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{\frac{\sin(x)}{1+\sin(x)}}{1} dx$$

Which simplifies to

$$u_1 = - \int \frac{\sin(x)}{1 + \sin(x)} dx$$

Hence

$$u_1 = - \frac{2}{\tan\left(\frac{x}{2}\right) + 1} - x$$

And Eq. (3) becomes

$$u_2 = \int \frac{\frac{\cos(x)}{1+\sin(x)}}{1} dx$$

Which simplifies to

$$u_2 = \int \frac{\cos(x)}{1 + \sin(x)} dx$$

Hence

$$u_2 = \ln(1 + \sin(x))$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \left(-\frac{2}{\tan\left(\frac{x}{2}\right) + 1} - x \right) \cos(x) + \ln(1 + \sin(x)) \sin(x)$$

Which simplifies to

$$y_p(x) = \ln(1 + \sin(x)) \sin(x) + (-x - 1) \cos(x) + \sin(x) - 1$$

Therefore the general solution is

$$\begin{aligned}y &= y_h + y_p \\ &= (c_1 \cos(x) + c_2 \sin(x)) + (\ln(1 + \sin(x)) \sin(x) + (-x - 1) \cos(x) + \sin(x) - 1)\end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 \cos(x) + c_2 \sin(x) + \ln(1 + \sin(x)) \sin(x) + (-x - 1) \cos(x) + \sin(x) - 1$$

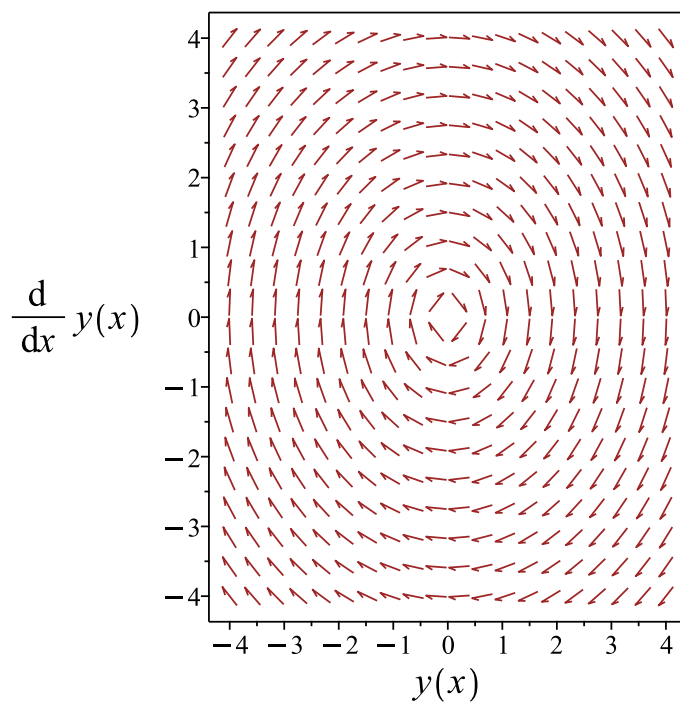


Figure 510: Slope field plot

Verification of solutions

$$y = c_1 \cos(x) + c_2 \sin(x) + \ln(1 + \sin(x)) \sin(x) + (-x - 1) \cos(x) + \sin(x) - 1$$

Verified OK.

12.15.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' + y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$A = 1$$

$$B = 0 \quad (3)$$

$$C = 1$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-1}{1} \quad (6)$$

Comparing the above to (5) shows that

$$s = -1$$

$$t = 1$$

Therefore eq. (4) becomes

$$z''(x) = -z(x) \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 453: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = -1$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = \cos(x)$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$y_1 = z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx}$$

Since $B = 0$ then the above reduces to

$$\begin{aligned}y_1 &= z_1 \\ &= \cos(x)\end{aligned}$$

Which simplifies to

$$y_1 = \cos(x)$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Since $B = 0$ then the above becomes

$$\begin{aligned}y_2 &= y_1 \int \frac{1}{y_1^2} dx \\ &= \cos(x) \int \frac{1}{\cos(x)^2} dx \\ &= \cos(x) (\tan(x))\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (\cos(x)) + c_2 (\cos(x) (\tan(x)))\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1 \cos(x) + c_2 \sin(x)$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \cos(x)$$

$$y_2 = \sin(x)$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \cos(x) & \sin(x) \\ \frac{d}{dx}(\cos(x)) & \frac{d}{dx}(\sin(x)) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \cos(x) & \sin(x) \\ -\sin(x) & \cos(x) \end{vmatrix}$$

Therefore

$$W = (\cos(x))(\cos(x)) - (\sin(x))(-\sin(x))$$

Which simplifies to

$$W = \cos(x)^2 + \sin(x)^2$$

Which simplifies to

$$W = 1$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{\frac{\sin(x)}{1+\sin(x)}}{1} dx$$

Which simplifies to

$$u_1 = - \int \frac{\sin(x)}{1 + \sin(x)} dx$$

Hence

$$u_1 = - \frac{2}{\tan\left(\frac{x}{2}\right) + 1} - x$$

And Eq. (3) becomes

$$u_2 = \int \frac{\frac{\cos(x)}{1+\sin(x)}}{1} dx$$

Which simplifies to

$$u_2 = \int \frac{\cos(x)}{1 + \sin(x)} dx$$

Hence

$$u_2 = \ln(1 + \sin(x))$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \left(-\frac{2}{\tan\left(\frac{x}{2}\right) + 1} - x \right) \cos(x) + \ln(1 + \sin(x)) \sin(x)$$

Which simplifies to

$$y_p(x) = \ln(1 + \sin(x)) \sin(x) + (-x - 1) \cos(x) + \sin(x) - 1$$

Therefore the general solution is

$$y = y_h + y_p$$

$$= (c_1 \cos(x) + c_2 \sin(x)) + (\ln(1 + \sin(x)) \sin(x) + (-x - 1) \cos(x) + \sin(x) - 1)$$

Summary

The solution(s) found are the following

$$y = c_1 \cos(x) + c_2 \sin(x) + \ln(1 + \sin(x)) \sin(x) + (-x - 1) \cos(x) + \sin(x) - 1(1)$$

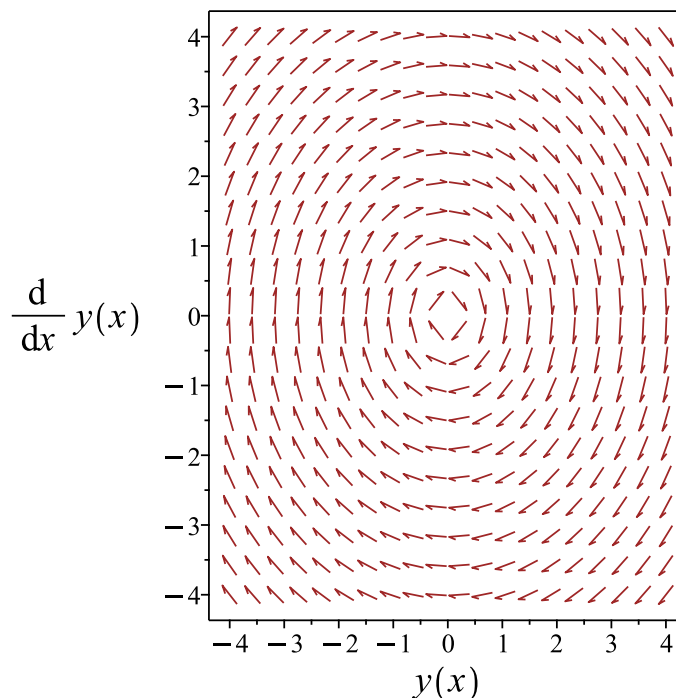


Figure 511: Slope field plot

Verification of solutions

$$y = c_1 \cos(x) + c_2 \sin(x) + \ln(1 + \sin(x)) \sin(x) + (-x - 1) \cos(x) + \sin(x) - 1$$

Verified OK.

12.15.3 Maple step by step solution

Let's solve

$$y'' + y = \frac{1}{1 + \sin(x)}$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of homogeneous ODE

$$r^2 + 1 = 0$$

- Use quadratic formula to solve for r

$$r = \frac{0 \pm (\sqrt{-4})}{2}$$
- Roots of the characteristic polynomial

$$r = (-I, I)$$
- 1st solution of the homogeneous ODE

$$y_1(x) = \cos(x)$$
- 2nd solution of the homogeneous ODE

$$y_2(x) = \sin(x)$$
- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$
- Substitute in solutions of the homogeneous ODE

$$y = c_1 \cos(x) + c_2 \sin(x) + y_p(x)$$
- Find a particular solution $y_p(x)$ of the ODE
 - Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = \frac{1}{1+\sin(x)} \right]$$
 - Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} \cos(x) & \sin(x) \\ -\sin(x) & \cos(x) \end{bmatrix}$$
 - Compute Wronskian

$$W(y_1(x), y_2(x)) = 1$$
 - Substitute functions into equation for $y_p(x)$

$$y_p(x) = -\cos(x) \left(\int \frac{\sin(x)}{1+\sin(x)} dx \right) + \sin(x) \left(\int \frac{\cos(x)}{1+\sin(x)} dx \right)$$
 - Compute integrals

$$y_p(x) = \ln(1 + \sin(x)) \sin(x) + (-x - 1) \cos(x) + \sin(x) - 1$$
- Substitute particular solution into general solution to ODE

$$y = c_1 \cos(x) + c_2 \sin(x) + \ln(1 + \sin(x)) \sin(x) + (-x - 1) \cos(x) + \sin(x) - 1$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]  
trying a double symmetry of the form [xi=0, eta=F(x)]  
-> Try solving first the homogeneous part of the ODE  
    checking if the LODE has constant coefficients  
    <- constant coefficients successful  
<- solving first the homogeneous part of the ODE successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 29

```
dsolve(diff(y(x),x$2)+y(x)=1/(1+sin(x)),y(x), singsol=all)
```

$$y(x) = \ln(1 + \sin(x)) \sin(x) + (-x + c_1 - 1) \cos(x) - 1 + (c_2 + 1) \sin(x)$$

✓ Solution by Mathematica

Time used: 0.188 (sec). Leaf size: 40

```
DSolve[y''[x]+y[x]==1/(1+Sin[x]),y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow (-x + 1 + c_1) \cos(x) + \sin(x) \left(2 \log \left(\sin \left(\frac{x}{2} \right) + \cos \left(\frac{x}{2} \right) \right) + 1 + c_2 \right) - 1$$

12.16 problem 16

12.16.1 Solving as second order linear constant coeff ode	3053
12.16.2 Solving as linear second order ode solved by an integrating factor ode	3057
12.16.3 Solving using Kovacic algorithm	3059
12.16.4 Maple step by step solution	3065

Internal problem ID [11844]

Internal file name [OUTPUT/11853_Saturday_April_13_2024_01_12_54_AM_97141954/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.4. Variation of parameters. Exercises page 162

Problem number: 16.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff", "linear_second_order_ode_solved_by_an_integrating_factor"

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' - 2y' + y = e^x \arcsin(x)$$

12.16.1 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = -2, C = 1, f(x) = e^x \arcsin(x)$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' - 2y' + y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = -2, C = 1$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} - 2\lambda e^{\lambda x} + e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 - 2\lambda + 1 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = -2, C = 1$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{2}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{(-2)^2 - (4)(1)(1)} \\ &= 1 \end{aligned}$$

Hence this is the case of a double root $\lambda_{1,2} = -1$. Therefore the solution is

$$y = c_1 e^x + c_2 x e^x \quad (1)$$

Therefore the homogeneous solution y_h is

$$y_h = e^x c_1 + c_2 x e^x$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$\begin{aligned} y_1 &= e^x \\ y_2 &= x e^x \end{aligned}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} e^x & x e^x \\ \frac{d}{dx}(e^x) & \frac{d}{dx}(x e^x) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} e^x & x e^x \\ e^x & x e^x + e^x \end{vmatrix}$$

Therefore

$$W = (e^x)(x e^x + e^x) - (x e^x)(e^x)$$

Which simplifies to

$$W = e^{2x}$$

Which simplifies to

$$W = e^{2x}$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{x e^{2x} \arcsin(x)}{e^{2x}} dx$$

Which simplifies to

$$u_1 = - \int x \arcsin(x) dx$$

Hence

$$u_1 = - \frac{x^2 \arcsin(x)}{2} - \frac{\sqrt{-x^2 + 1} x}{4} + \frac{\arcsin(x)}{4}$$

And Eq. (3) becomes

$$u_2 = \int \frac{e^{2x} \arcsin(x)}{e^{2x}} dx$$

Which simplifies to

$$u_2 = \int \arcsin(x) dx$$

Hence

$$u_2 = x \arcsin(x) + \sqrt{-x^2 + 1}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \left(-\frac{x^2 \arcsin(x)}{2} - \frac{\sqrt{-x^2 + 1} x}{4} + \frac{\arcsin(x)}{4} \right) e^x + \left(x \arcsin(x) + \sqrt{-x^2 + 1} \right) x e^x$$

Which simplifies to

$$y_p(x) = \frac{e^x (2x^2 \arcsin(x) + 3\sqrt{-x^2 + 1} x + \arcsin(x))}{4}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (e^x c_1 + c_2 x e^x) + \left(\frac{e^x (2x^2 \arcsin(x) + 3\sqrt{-x^2 + 1} x + \arcsin(x))}{4} \right) \end{aligned}$$

Which simplifies to

$$y = e^x (c_2 x + c_1) + \frac{e^x (2x^2 \arcsin(x) + 3\sqrt{-x^2 + 1} x + \arcsin(x))}{4}$$

Summary

The solution(s) found are the following

$$y = e^x (c_2 x + c_1) + \frac{e^x (2x^2 \arcsin(x) + 3\sqrt{-x^2 + 1} x + \arcsin(x))}{4} \quad (1)$$

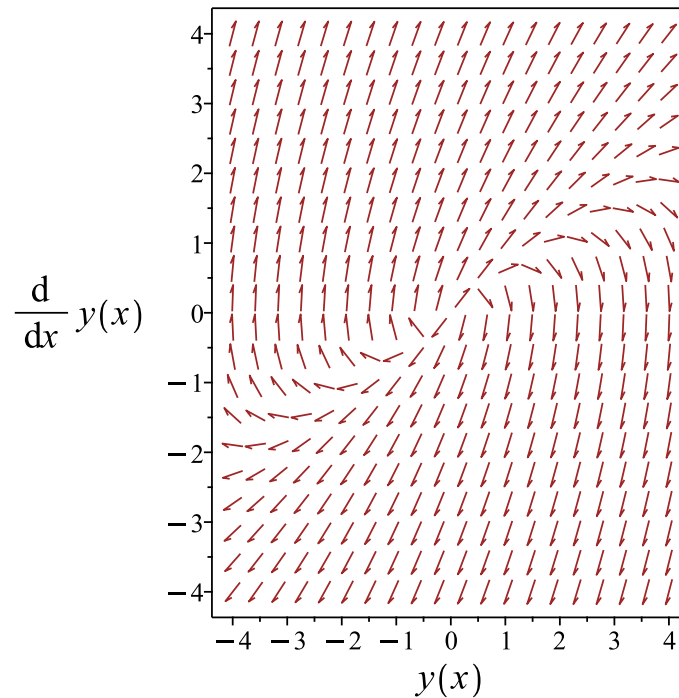


Figure 512: Slope field plot

Verification of solutions

$$y = e^x(c_2x + c_1) + \frac{e^x(2x^2 \arcsin(x) + 3\sqrt{-x^2 + 1}x + \arcsin(x))}{4}$$

Verified OK.

12.16.2 Solving as linear second order ode solved by an integrating factor ode

The ode satisfies this form

$$y'' + p(x)y' + \frac{(p(x)^2 + p'(x))y}{2} = f(x)$$

Where $p(x) = -2$. Therefore, there is an integrating factor given by

$$\begin{aligned} M(x) &= e^{\frac{1}{2} \int p dx} \\ &= e^{\int -2 dx} \\ &= e^{-x} \end{aligned}$$

Multiplying both sides of the ODE by the integrating factor $M(x)$ makes the left side of the ODE a complete differential

$$(M(x)y)'' = e^{-x}e^x \arcsin(x)$$

$$(e^{-x}y)'' = e^{-x}e^x \arcsin(x)$$

Integrating once gives

$$(e^{-x}y)' = x \arcsin(x) + \sqrt{-x^2 + 1} + c_1$$

Integrating again gives

$$(e^{-x}y) = c_1x + \frac{3\sqrt{-x^2 + 1}x}{4} + \frac{\arcsin(x)}{4} + \frac{x^2 \arcsin(x)}{2} + c_2$$

Hence the solution is

$$y = \frac{c_1x + \frac{3\sqrt{-x^2 + 1}x}{4} + \frac{\arcsin(x)}{4} + \frac{x^2 \arcsin(x)}{2} + c_2}{e^{-x}}$$

Or

$$y = \frac{x^2 \arcsin(x) e^x}{2} + c_1x e^x + c_2e^x + \frac{3\sqrt{-x^2 + 1}x e^x}{4} + \frac{\arcsin(x) e^x}{4}$$

Summary

The solution(s) found are the following

$$y = \frac{x^2 \arcsin(x) e^x}{2} + c_1x e^x + c_2e^x + \frac{3\sqrt{-x^2 + 1}x e^x}{4} + \frac{\arcsin(x) e^x}{4} \quad (1)$$

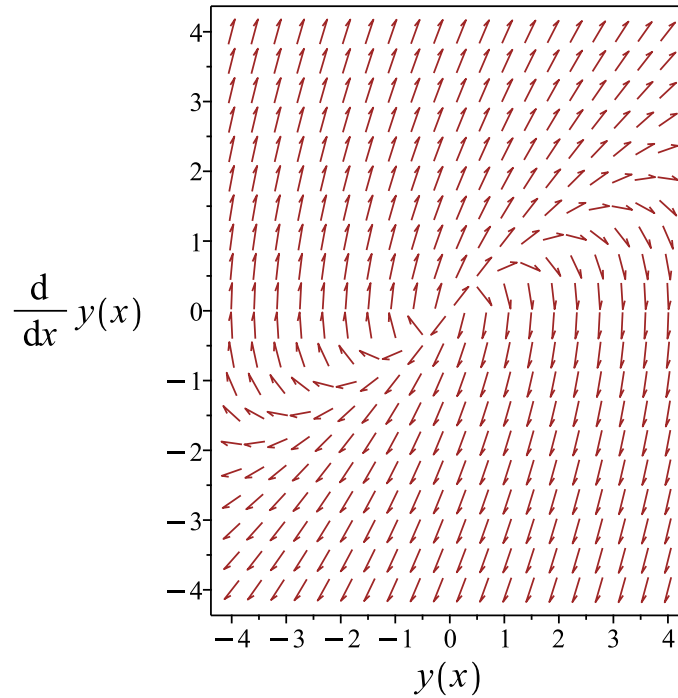


Figure 513: Slope field plot

Verification of solutions

$$y = \frac{x^2 \arcsin(x) e^x}{2} + c_1 x e^x + c_2 e^x + \frac{3\sqrt{-x^2 + 1} x e^x}{4} + \frac{\arcsin(x) e^x}{4}$$

Verified OK.

12.16.3 Solving using Kovacic algorithm

Writing the ode as

$$y'' - 2y' + y = 0 \tag{1}$$

$$Ay'' + By' + Cy = 0 \tag{2}$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= -2 \\ C &= 1 \end{aligned} \tag{3}$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$r = \frac{s}{t} \tag{5}$$

$$= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{0}{1} \tag{6}$$

Comparing the above to (5) shows that

$$s = 0$$

$$t = 1$$

Therefore eq. (4) becomes

$$z''(x) = 0 \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 455: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned}O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - -\infty \\ &= \infty\end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is *infinity* then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = 0$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = 1$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned}y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-2}{1} dx} \\ &= z_1 e^x \\ &= z_1(e^x)\end{aligned}$$

Which simplifies to

$$y_1 = e^x$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{-2}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{2x}}{(y_1)^2} dx \\ &= y_1(x)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1(e^x) + c_2(e^x(x))\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' - 2y' + y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = e^x c_1 + c_2 x e^x$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$\begin{aligned}y_1 &= e^x \\ y_2 &= x e^x\end{aligned}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \tag{2}$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \tag{3}$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} e^x & x e^x \\ \frac{d}{dx}(e^x) & \frac{d}{dx}(x e^x) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} e^x & x e^x \\ e^x & x e^x + e^x \end{vmatrix}$$

Therefore

$$W = (e^x)(x e^x + e^x) - (x e^x)(e^x)$$

Which simplifies to

$$W = e^{2x}$$

Which simplifies to

$$W = e^{2x}$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{x e^{2x} \arcsin(x)}{e^{2x}} dx$$

Which simplifies to

$$u_1 = - \int x \arcsin(x) dx$$

Hence

$$u_1 = - \frac{x^2 \arcsin(x)}{2} - \frac{\sqrt{-x^2 + 1} x}{4} + \frac{\arcsin(x)}{4}$$

And Eq. (3) becomes

$$u_2 = \int \frac{e^{2x} \arcsin(x)}{e^{2x}} dx$$

Which simplifies to

$$u_2 = \int \arcsin(x) dx$$

Hence

$$u_2 = x \arcsin(x) + \sqrt{-x^2 + 1}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \left(-\frac{x^2 \arcsin(x)}{2} - \frac{\sqrt{-x^2 + 1} x}{4} + \frac{\arcsin(x)}{4} \right) e^x + \left(x \arcsin(x) + \sqrt{-x^2 + 1} \right) x e^x$$

Which simplifies to

$$y_p(x) = \frac{e^x (2x^2 \arcsin(x) + 3\sqrt{-x^2 + 1} x + \arcsin(x))}{4}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (e^x c_1 + c_2 x e^x) + \left(\frac{e^x (2x^2 \arcsin(x) + 3\sqrt{-x^2 + 1} x + \arcsin(x))}{4} \right) \end{aligned}$$

Which simplifies to

$$y = e^x (c_2 x + c_1) + \frac{e^x (2x^2 \arcsin(x) + 3\sqrt{-x^2 + 1} x + \arcsin(x))}{4}$$

Summary

The solution(s) found are the following

$$y = e^x (c_2 x + c_1) + \frac{e^x (2x^2 \arcsin(x) + 3\sqrt{-x^2 + 1} x + \arcsin(x))}{4} \quad (1)$$

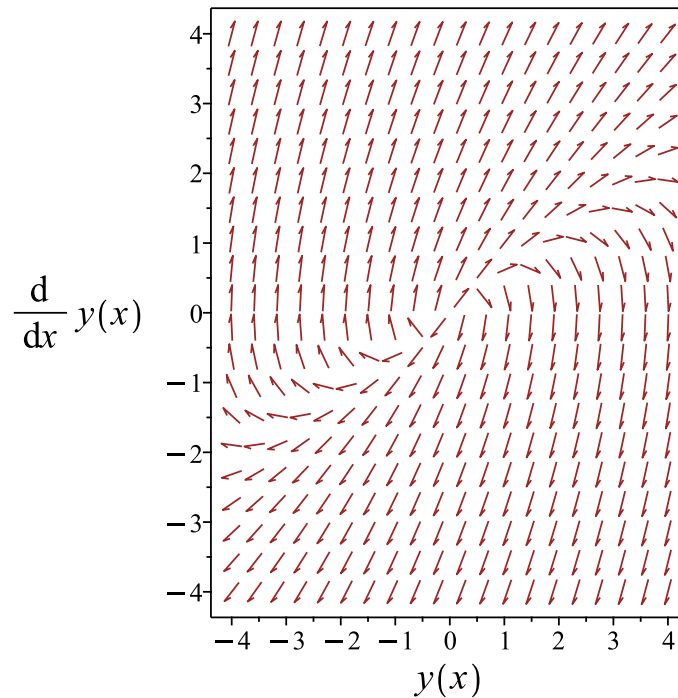


Figure 514: Slope field plot

Verification of solutions

$$y = e^x(c_2x + c_1) + \frac{e^x(2x^2 \arcsin(x) + 3\sqrt{-x^2 + 1}x + \arcsin(x))}{4}$$

Verified OK.

12.16.4 Maple step by step solution

Let's solve

$$y'' - 2y' + y = \arcsin(x) e^x$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of homogeneous ODE

$$r^2 - 2r + 1 = 0$$

- Factor the characteristic polynomial

$$(r - 1)^2 = 0$$

- Root of the characteristic polynomial

$$r = 1$$

- 1st solution of the homogeneous ODE

$$y_1(x) = e^x$$

- Repeated root, multiply $y_1(x)$ by x to ensure linear independence

$$y_2(x) = x e^x$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = e^x c_1 + c_2 x e^x + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = \arcsin(x) e^x \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} e^x & x e^x \\ e^x & x e^x + e^x \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = e^{2x}$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = e^x \left(- \left(\int x \arcsin(x) dx \right) + \left(\int \arcsin(x) dx \right) x \right)$$

- Compute integrals

$$y_p(x) = \frac{e^x \left(2x^2 \arcsin(x) + 3\sqrt{-x^2+1} x + \arcsin(x) \right)}{4}$$

- Substitute particular solution into general solution to ODE

$$y = e^x c_1 + c_2 x e^x + \frac{e^x \left(2x^2 \arcsin(x) + 3\sqrt{-x^2+1} x + \arcsin(x) \right)}{4}$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]  
trying a double symmetry of the form [xi=0, eta=F(x)]  
-> Try solving first the homogeneous part of the ODE  
    checking if the LODE has constant coefficients  
    <- constant coefficients successful  
<- solving first the homogeneous part of the ODE successful`
```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 37

```
dsolve(diff(y(x),x$2)-2*diff(y(x),x)+y(x)=exp(x)*arcsin(x),y(x), singsol=all)
```

$$y(x) = \frac{e^x (2x^2 \arcsin(x) + 3x\sqrt{-x^2 + 1} + 4c_1x + \arcsin(x) + 4c_2)}{4}$$

✓ Solution by Mathematica

Time used: 0.043 (sec). Leaf size: 45

```
DSolve[y''[x]-2*y'[x]+y[x]==Exp[x]*ArcSin[x],y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{1}{4}e^x \left(2x^2 \arcsin(x) + \arcsin(x) + 3\sqrt{1-x^2}x + 4c_2x + 4c_1 \right)$$

12.17 problem 17

12.17.1 Solving as second order linear constant coeff ode	3068
12.17.2 Solving using Kovacic algorithm	3072
12.17.3 Maple step by step solution	3078

Internal problem ID [11845]

Internal file name [OUTPUT/11854_Saturday_April_13_2024_01_12_55_AM_35752472/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.4. Variation of parameters. Exercises page 162

Problem number: 17.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"kovacic", "second_order_linear_constant_coeff"**

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' + 3y' + 2y = \frac{e^{-x}}{x}$$

12.17.1 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = 3, C = 2, f(x) = \frac{e^{-x}}{x}$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 3y' + 2y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = 3, C = 2$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} + 3\lambda e^{\lambda x} + 2e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 + 3\lambda + 2 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 3, C = 2$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{-3}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{3^2 - (4)(1)(2)} \\ &= -\frac{3}{2} \pm \frac{1}{2} \end{aligned}$$

Hence

$$\begin{aligned} \lambda_1 &= -\frac{3}{2} + \frac{1}{2} \\ \lambda_2 &= -\frac{3}{2} - \frac{1}{2} \end{aligned}$$

Which simplifies to

$$\begin{aligned} \lambda_1 &= -1 \\ \lambda_2 &= -2 \end{aligned}$$

Since roots are real and distinct, then the solution is

$$\begin{aligned} y &= c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x} \\ y &= c_1 e^{(-1)x} + c_2 e^{(-2)x} \end{aligned}$$

Or

$$y = c_1 e^{-x} + c_2 e^{-2x}$$

Therefore the homogeneous solution y_h is

$$y_h = c_1 e^{-x} + c_2 e^{-2x}$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = e^{-x}$$

$$y_2 = e^{-2x}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} e^{-x} & e^{-2x} \\ \frac{d}{dx}(e^{-x}) & \frac{d}{dx}(e^{-2x}) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} e^{-x} & e^{-2x} \\ -e^{-x} & -2e^{-2x} \end{vmatrix}$$

Therefore

$$W = (e^{-x})(-2e^{-2x}) - (e^{-2x})(-e^{-x})$$

Which simplifies to

$$W = -e^{-x}e^{-2x}$$

Which simplifies to

$$W = -e^{-3x}$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{\frac{e^{-2x}e^{-x}}{x}}{-e^{-3x}} dx$$

Which simplifies to

$$u_1 = - \int -\frac{1}{x} dx$$

Hence

$$u_1 = \ln(x)$$

And Eq. (3) becomes

$$u_2 = \int \frac{\frac{e^{-2x}}{x}}{-e^{-3x}} dx$$

Which simplifies to

$$u_2 = \int -\frac{e^x}{x} dx$$

Hence

$$u_2 = \text{expIntegral}_1(-x)$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \ln(x) e^{-x} + \text{expIntegral}_1(-x) e^{-2x}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 e^{-x} + c_2 e^{-2x}) + (\ln(x) e^{-x} + \text{expIntegral}_1(-x) e^{-2x}) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 e^{-x} + c_2 e^{-2x} + \ln(x) e^{-x} + \text{expIntegral}_1(-x) e^{-2x} \quad (1)$$

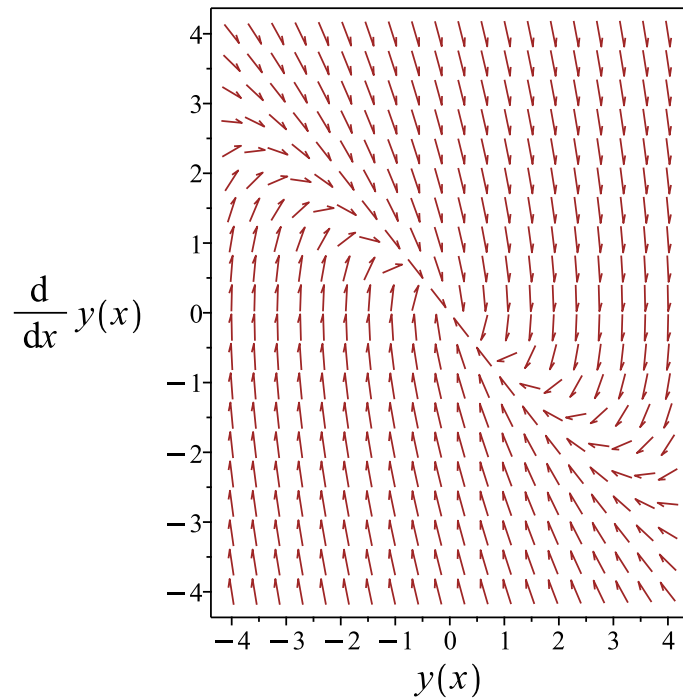


Figure 515: Slope field plot

Verification of solutions

$$y = c_1 e^{-x} + c_2 e^{-2x} + \ln(x) e^{-x} + \text{expIntegral}_1(-x) e^{-2x}$$

Verified OK.

12.17.2 Solving using Kovacic algorithm

Writing the ode as

$$y'' + 3y' + 2y = 0 \tag{1}$$

$$Ay'' + By' + Cy = 0 \tag{2}$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= 3 \\ C &= 2 \end{aligned} \tag{3}$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{1}{4} \tag{6}$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 1 \\ t &= 4 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = \frac{z(x)}{4} \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 457: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned}O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0\end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = \frac{1}{4}$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = e^{-\frac{x}{2}}$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned}y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{3}{1} dx} \\ &= z_1 e^{-\frac{3x}{2}} \\ &= z_1 \left(e^{-\frac{3x}{2}} \right)\end{aligned}$$

Which simplifies to

$$y_1 = e^{-2x}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{3}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{-3x}}{(y_1)^2} dx \\ &= y_1(e^x)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1y_1 + c_2y_2 \\ &= c_1(e^{-2x}) + c_2(e^{-2x}(e^x))\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' + 3y' + 2y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1e^{-2x} + c_2e^{-x}$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1y_1 + u_2y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = e^{-2x}$$

$$y_2 = e^{-x}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \tag{2}$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \tag{3}$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} e^{-2x} & e^{-x} \\ \frac{d}{dx}(e^{-2x}) & \frac{d}{dx}(e^{-x}) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} e^{-2x} & e^{-x} \\ -2e^{-2x} & -e^{-x} \end{vmatrix}$$

Therefore

$$W = (e^{-2x})(-e^{-x}) - (e^{-x})(-2e^{-2x})$$

Which simplifies to

$$W = e^{-x}e^{-2x}$$

Which simplifies to

$$W = e^{-3x}$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{e^{-2x}}{e^{-3x}} dx$$

Which simplifies to

$$u_1 = - \int \frac{e^x}{x} dx$$

Hence

$$u_1 = \exp \int_1 (-x)$$

And Eq. (3) becomes

$$u_2 = \int \frac{e^{-2x}e^{-x}}{e^{-3x}} dx$$

Which simplifies to

$$u_2 = \int \frac{1}{x} dx$$

Hence

$$u_2 = \ln(x)$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \ln(x) e^{-x} + \text{expIntegral}_1(-x) e^{-2x}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 e^{-2x} + c_2 e^{-x}) + (\ln(x) e^{-x} + \text{expIntegral}_1(-x) e^{-2x}) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 e^{-2x} + c_2 e^{-x} + \ln(x) e^{-x} + \text{expIntegral}_1(-x) e^{-2x} \quad (1)$$

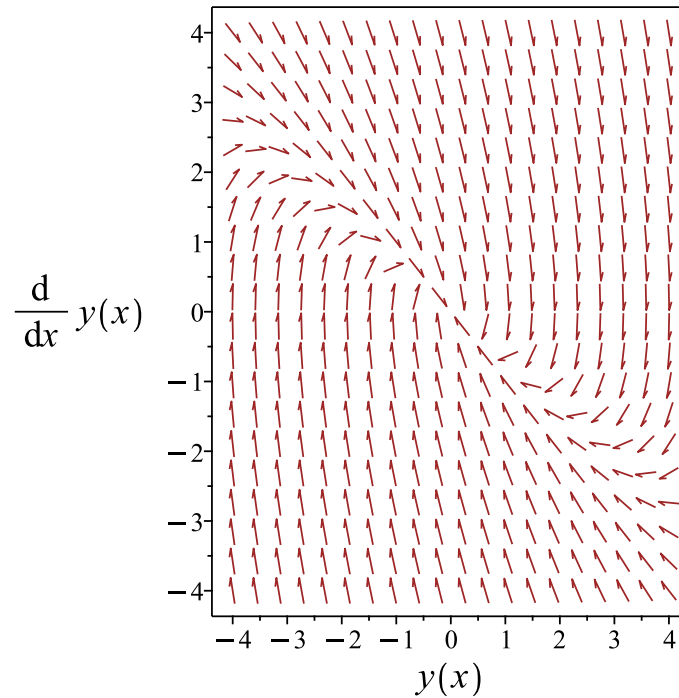


Figure 516: Slope field plot

Verification of solutions

$$y = c_1 e^{-2x} + c_2 e^{-x} + \ln(x) e^{-x} + \text{expIntegral}_1(-x) e^{-2x}$$

Verified OK.

12.17.3 Maple step by step solution

Let's solve

$$y'' + 3y' + 2y = \frac{e^{-x}}{x}$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of homogeneous ODE

$$r^2 + 3r + 2 = 0$$

- Factor the characteristic polynomial

$$(r + 2)(r + 1) = 0$$

- Roots of the characteristic polynomial

$$r = (-2, -1)$$

- 1st solution of the homogeneous ODE

$$y_1(x) = e^{-2x}$$

- 2nd solution of the homogeneous ODE

$$y_2(x) = e^{-x}$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = c_1 e^{-2x} + c_2 e^{-x} + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = \frac{e^{-x}}{x} \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} e^{-2x} & e^{-x} \\ -2e^{-2x} & -e^{-x} \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = e^{-3x}$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = -e^{-2x} \left(\int \frac{e^{-x}}{x} dx \right) + e^{-x} \left(\int \frac{1}{x} dx \right)$$

- Compute integrals

$$y_p(x) = \ln(x) e^{-x} + \text{Ei}_1(-x) e^{-2x}$$

- Substitute particular solution into general solution to ODE

$$y = c_1 e^{-2x} + c_2 e^{-x} + \ln(x) e^{-x} + \text{Ei}_1(-x) e^{-2x}$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
trying a double symmetry of the form [xi=0, eta=F(x)]
<- double symmetry of the form [xi=0, eta=F(x)] successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 29

```
dsolve(diff(y(x),x$2)+3*diff(y(x),x)+2*y(x)=exp(-x)/x,y(x), singsol=all)
```

$$y(x) = \left(- \left(\int e^{-x} (\text{expIntegral}_1(-x) - c_1) dx \right) + c_2 \right) e^{-x}$$

✓ Solution by Mathematica

Time used: 0.041 (sec). Leaf size: 30

```
DSolve[y''[x]+3*y'[x]+2*y[x]==Exp[-x]/x,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^{-2x} (-\text{ExpIntegralEi}(x) + e^x \log(x) + c_2 e^x + c_1)$$

12.18 problem 18

12.18.1 Solving as second order linear constant coeff ode	3080
12.18.2 Solving as linear second order ode solved by an integrating factor ode	3084
12.18.3 Solving using Kovacic algorithm	3086
12.18.4 Maple step by step solution	3092

Internal problem ID [11846]

Internal file name [OUTPUT/11855_Saturday_April_13_2024_01_12_55_AM_46328560/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.4. Variation of parameters. Exercises page 162

Problem number: 18.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_linear_constant_coeff", "linear_second_order_ode_solved_by_an_integrating_factor"

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$y'' - 2y' + y = x \ln(x)$$

12.18.1 Solving as second order linear constant coeff ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 1, B = -2, C = 1, f(x) = x \ln(x)$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' - 2y' + y = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = 0$$

Where in the above $A = 1, B = -2, C = 1$. Let the solution be $y = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} - 2\lambda e^{\lambda x} + e^{\lambda x} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 - 2\lambda + 1 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = -2, C = 1$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{2}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{(-2)^2 - (4)(1)(1)} \\ &= 1 \end{aligned}$$

Hence this is the case of a double root $\lambda_{1,2} = -1$. Therefore the solution is

$$y = c_1 e^x + c_2 x e^x \quad (1)$$

Therefore the homogeneous solution y_h is

$$y_h = e^x c_1 + c_2 x e^x$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$\begin{aligned} y_1 &= e^x \\ y_2 &= x e^x \end{aligned}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} e^x & x e^x \\ \frac{d}{dx}(e^x) & \frac{d}{dx}(x e^x) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} e^x & x e^x \\ e^x & x e^x + e^x \end{vmatrix}$$

Therefore

$$W = (e^x)(x e^x + e^x) - (x e^x)(e^x)$$

Which simplifies to

$$W = e^{2x}$$

Which simplifies to

$$W = e^{2x}$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{x^2 e^x \ln(x)}{e^{2x}} dx$$

Which simplifies to

$$u_1 = - \int x^2 \ln(x) e^{-x} dx$$

Hence

$$u_1 = -(-x^2 - 2x - 2) e^{-x} \ln(x) + 2 \text{expIntegral}_1(x) + x e^{-x} + 3 e^{-x}$$

And Eq. (3) becomes

$$u_2 = \int \frac{x e^x \ln(x)}{e^{2x}} dx$$

Which simplifies to

$$u_2 = \int x \ln(x) e^{-x} dx$$

Hence

$$u_2 = (-x - 1) e^{-x} \ln(x) - \expIntegral_1(x) - e^{-x}$$

Which simplifies to

$$u_1 = ((x^2 + 2x + 2) \ln(x) + x + 3) e^{-x} + 2 \expIntegral_1(x)$$

$$u_2 = (-1 + \ln(x)(-x - 1)) e^{-x} - \expIntegral_1(x)$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = (((x^2 + 2x + 2) \ln(x) + x + 3) e^{-x} + 2 \expIntegral_1(x)) e^x + ((-1 + \ln(x)(-x - 1)) e^{-x} - \expIntegral_1(x)) x e^x$$

Which simplifies to

$$y_p(x) = -e^x(x - 2) \expIntegral_1(x) + 3 + (x + 2) \ln(x)$$

Therefore the general solution is

$$y = y_h + y_p \\ = (e^x c_1 + c_2 x e^x) + (-e^x(x - 2) \expIntegral_1(x) + 3 + (x + 2) \ln(x))$$

Which simplifies to

$$y = e^x(c_2 x + c_1) - e^x(x - 2) \expIntegral_1(x) + 3 + (x + 2) \ln(x)$$

Summary

The solution(s) found are the following

$$y = e^x(c_2 x + c_1) - e^x(x - 2) \expIntegral_1(x) + 3 + (x + 2) \ln(x) \quad (1)$$

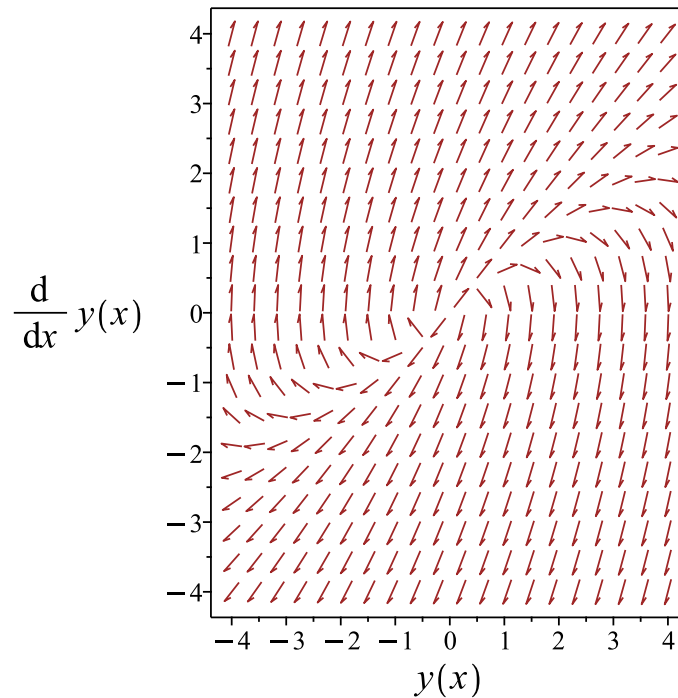


Figure 517: Slope field plot

Verification of solutions

$$y = e^x(c_2x + c_1) - e^x(x - 2) \expIntegral_1(x) + 3 + (x + 2) \ln(x)$$

Verified OK.

12.18.2 Solving as linear second order ode solved by an integrating factor ode

The ode satisfies this form

$$y'' + p(x)y' + \frac{(p(x)^2 + p'(x))y}{2} = f(x)$$

Where $p(x) = -2$. Therefore, there is an integrating factor given by

$$\begin{aligned} M(x) &= e^{\frac{1}{2} \int p dx} \\ &= e^{\int -2 dx} \\ &= e^{-x} \end{aligned}$$

Multiplying both sides of the ODE by the integrating factor $M(x)$ makes the left side of the ODE a complete differential

$$(M(x)y)'' = x \ln(x) e^{-x}$$

$$(e^{-x}y)'' = x \ln(x) e^{-x}$$

Integrating once gives

$$(e^{-x}y)' = (-1 + \ln(x)(-x - 1)) e^{-x} - \text{expIntegral}_1(x) + c_1$$

Integrating again gives

$$(e^{-x}y) = (3 + (x + 2) \ln(x)) e^{-x} + (-x + 2) \text{expIntegral}_1(x) + c_1x + c_2$$

Hence the solution is

$$y = \frac{(3 + (x + 2) \ln(x)) e^{-x} + (-x + 2) \text{expIntegral}_1(x) + c_1x + c_2}{e^{-x}}$$

Or

$$y = c_1x e^x - x \text{expIntegral}_1(x) e^x + c_2e^x + x \ln(x) + 2 \text{expIntegral}_1(x) e^x + 2 \ln(x) + 3$$

Summary

The solution(s) found are the following

$$y = c_1x e^x - x \text{expIntegral}_1(x) e^x + c_2e^x + x \ln(x) + 2 \text{expIntegral}_1(x) e^x + 2 \ln(x) + 3 \quad (1)$$

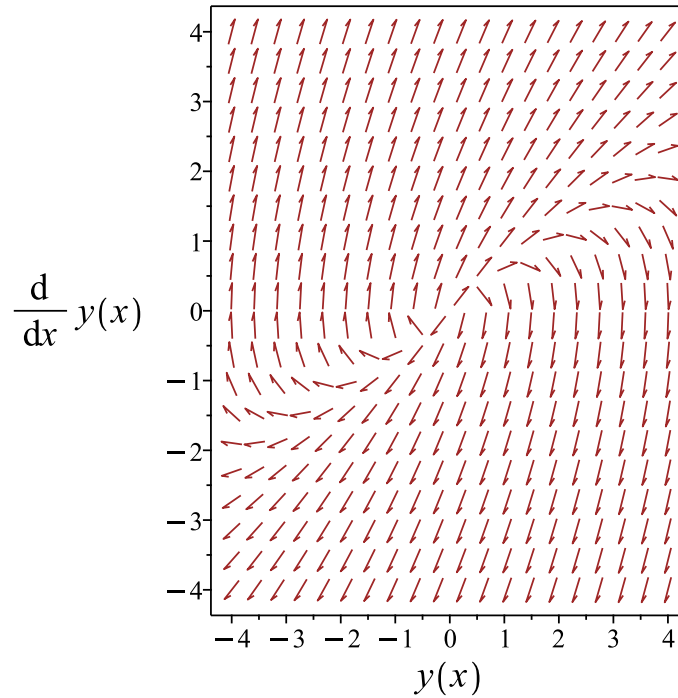


Figure 518: Slope field plot

Verification of solutions

$$y = c_1 x e^x - x \operatorname{expIntegral}_1(x) e^x + c_2 e^x + x \ln(x) + 2 \operatorname{expIntegral}_1(x) e^x + 2 \ln(x) + 3$$

Verified OK.

12.18.3 Solving using Kovacic algorithm

Writing the ode as

$$y'' - 2y' + y = 0 \tag{1}$$

$$Ay'' + By' + Cy = 0 \tag{2}$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 1 \\ B &= -2 \\ C &= 1 \end{aligned} \tag{3}$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$r = \frac{s}{t} = \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{0}{1} \tag{6}$$

Comparing the above to (5) shows that

$$s = 0$$

$$t = 1$$

Therefore eq. (4) becomes

$$z''(x) = 0 \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 459: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned}O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - -\infty \\ &= \infty\end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is *infinity* then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = 0$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = 1$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned}y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-2}{1} dx} \\ &= z_1 e^x \\ &= z_1(e^x)\end{aligned}$$

Which simplifies to

$$y_1 = e^x$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{-2}{1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{2x}}{(y_1)^2} dx \\ &= y_1(x)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1(e^x) + c_2(e^x(x))\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y'' - 2y' + y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = e^x c_1 + c_2 x e^x$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$\begin{aligned}y_1 &= e^x \\ y_2 &= x e^x\end{aligned}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \tag{2}$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \tag{3}$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} e^x & x e^x \\ \frac{d}{dx}(e^x) & \frac{d}{dx}(x e^x) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} e^x & x e^x \\ e^x & x e^x + e^x \end{vmatrix}$$

Therefore

$$W = (e^x)(x e^x + e^x) - (x e^x)(e^x)$$

Which simplifies to

$$W = e^{2x}$$

Which simplifies to

$$W = e^{2x}$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{x^2 e^x \ln(x)}{e^{2x}} dx$$

Which simplifies to

$$u_1 = - \int x^2 \ln(x) e^{-x} dx$$

Hence

$$u_1 = -(-x^2 - 2x - 2) e^{-x} \ln(x) + 2 \text{expIntegral}_1(x) + x e^{-x} + 3 e^{-x}$$

And Eq. (3) becomes

$$u_2 = \int \frac{x e^x \ln(x)}{e^{2x}} dx$$

Which simplifies to

$$u_2 = \int x \ln(x) e^{-x} dx$$

Hence

$$u_2 = (-x - 1) e^{-x} \ln(x) - \text{expIntegral}_1(x) - e^{-x}$$

Which simplifies to

$$u_1 = ((x^2 + 2x + 2) \ln(x) + x + 3) e^{-x} + 2 \text{expIntegral}_1(x)$$

$$u_2 = (-1 + \ln(x)(-x - 1)) e^{-x} - \text{expIntegral}_1(x)$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = (((x^2 + 2x + 2) \ln(x) + x + 3) e^{-x} + 2 \text{expIntegral}_1(x)) e^x \\ + ((-1 + \ln(x)(-x - 1)) e^{-x} - \text{expIntegral}_1(x)) x e^x$$

Which simplifies to

$$y_p(x) = -e^x(x - 2) \text{expIntegral}_1(x) + 3 + (x + 2) \ln(x)$$

Therefore the general solution is

$$y = y_h + y_p \\ = (e^x c_1 + c_2 x e^x) + (-e^x(x - 2) \text{expIntegral}_1(x) + 3 + (x + 2) \ln(x))$$

Which simplifies to

$$y = e^x(c_2 x + c_1) - e^x(x - 2) \text{expIntegral}_1(x) + 3 + (x + 2) \ln(x)$$

Summary

The solution(s) found are the following

$$y = e^x(c_2 x + c_1) - e^x(x - 2) \text{expIntegral}_1(x) + 3 + (x + 2) \ln(x) \quad (1)$$

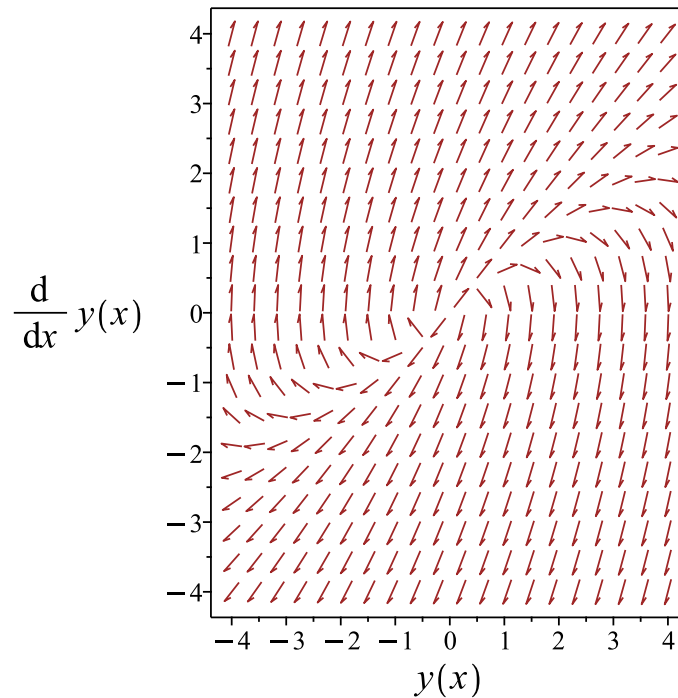


Figure 519: Slope field plot

Verification of solutions

$$y = e^x(c_2x + c_1) - e^x(x - 2) \text{expIntegral}_1(x) + 3 + (x + 2) \ln(x)$$

Verified OK.

12.18.4 Maple step by step solution

Let's solve

$$y'' - 2y' + y = x \ln(x)$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Characteristic polynomial of homogeneous ODE

$$r^2 - 2r + 1 = 0$$

- Factor the characteristic polynomial

$$(r - 1)^2 = 0$$

- Root of the characteristic polynomial

$$r = 1$$

- 1st solution of the homogeneous ODE

$$y_1(x) = e^x$$

- Repeated root, multiply $y_1(x)$ by x to ensure linear independence

$$y_2(x) = x e^x$$

- General solution of the ODE

$$y = c_1 y_1(x) + c_2 y_2(x) + y_p(x)$$

- Substitute in solutions of the homogeneous ODE

$$y = e^x c_1 + c_2 x e^x + y_p(x)$$

- Find a particular solution $y_p(x)$ of the ODE

- Use variation of parameters to find y_p here $f(x)$ is the forcing function

$$\left[y_p(x) = -y_1(x) \left(\int \frac{y_2(x)f(x)}{W(y_1(x),y_2(x))} dx \right) + y_2(x) \left(\int \frac{y_1(x)f(x)}{W(y_1(x),y_2(x))} dx \right), f(x) = x \ln(x) \right]$$

- Wronskian of solutions of the homogeneous equation

$$W(y_1(x), y_2(x)) = \begin{bmatrix} e^x & x e^x \\ e^x & x e^x + e^x \end{bmatrix}$$

- Compute Wronskian

$$W(y_1(x), y_2(x)) = e^{2x}$$

- Substitute functions into equation for $y_p(x)$

$$y_p(x) = e^x \left(- \left(\int x^2 \ln(x) e^{-x} dx \right) + \left(\int x \ln(x) e^{-x} dx \right) x \right)$$

- Compute integrals

$$y_p(x) = -e^x(x-2) \text{Ei}_1(x) + 3 + (x+2) \ln(x)$$

- Substitute particular solution into general solution to ODE

$$y = e^x c_1 + c_2 x e^x - e^x(x-2) \text{Ei}_1(x) + 3 + (x+2) \ln(x)$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]  
trying a double symmetry of the form [xi=0, eta=F(x)]  
-> Try solving first the homogeneous part of the ODE  
    checking if the LODE has constant coefficients  
    <- constant coefficients successful  
<- solving first the homogeneous part of the ODE successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 30

```
dsolve(diff(y(x),x$2)-2*diff(y(x),x)+y(x)=x*ln(x),y(x), singsol=all)
```

$$y(x) = -(x - 2) e^x \operatorname{ExpIntegralEi}_1(x) + (c_1 x + c_2) e^x + 3 + (x + 2) \ln(x)$$

✓ Solution by Mathematica

Time used: 0.059 (sec). Leaf size: 37

```
DSolve[y''[x]-2*y'[x]+y[x]==x*Log[x],y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^x(x - 2) \operatorname{ExpIntegralEi}(-x) + (x + 2) \log(x) + c_1 e^x + c_2 e^x x + 3$$

12.19 problem 19

12.19.1 Solving as second order euler ode ode	3095
12.19.2 Solving as second order change of variable on x method 2 ode .	3099
12.19.3 Solving as second order change of variable on x method 1 ode .	3104
12.19.4 Solving as second order change of variable on y method 2 ode .	3109
12.19.5 Solving using Kovacic algorithm	3114

Internal problem ID [11847]

Internal file name [OUTPUT/11856_Saturday_April_13_2024_01_12_56_AM_67587560/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.4. Variation of parameters. Exercises page 162

Problem number: 19.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_euler_ode", "second_order_change_of_variable_on_x_method_1", "second_order_change_of_variable_on_x_method_2", "second_order_change_of_variable_on_y_method_2"

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$x^2y'' - 6y'x + 10y = 3x^4 + 6x^3$$

12.19.1 Solving as second order euler ode ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = x^2, B = -6x, C = 10, f(x) = 3x^4 + 6x^3$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. Solving for y_h from

$$x^2y'' - 6y'x + 10y = 0$$

This is Euler second order ODE. Let the solution be $y = x^r$, then $y' = rx^{r-1}$ and $y'' = r(r-1)x^{r-2}$. Substituting these back into the given ODE gives

$$x^2(r(r-1))x^{r-2} - 6rxr^{r-1} + 10x^r = 0$$

Simplifying gives

$$r(r-1)x^r - 6rx^r + 10x^r = 0$$

Since $x^r \neq 0$ then dividing throughout by x^r gives

$$r(r-1) - 6r + 10 = 0$$

Or

$$r^2 - 7r + 10 = 0 \tag{1}$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = 2$$

$$r_2 = 5$$

Since the roots are real and distinct, then the general solution is

$$y = c_1y_1 + c_2y_2$$

Where $y_1 = x^{r_1}$ and $y_2 = x^{r_2}$. Hence

$$y = c_2x^5 + c_1x^2$$

Next, we find the particular solution to the ODE

$$x^2y'' - 6y'x + 10y = 3x^4 + 6x^3$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1y_1 + u_2y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = x^2$$

$$y_2 = x^5$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} x^2 & x^5 \\ \frac{d}{dx}(x^2) & \frac{d}{dx}(x^5) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} x^2 & x^5 \\ 2x & 5x^4 \end{vmatrix}$$

Therefore

$$W = (x^2)(5x^4) - (x^5)(2x)$$

Which simplifies to

$$W = 3x^6$$

Which simplifies to

$$W = 3x^6$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{x^5(3x^4 + 6x^3)}{3x^8} dx$$

Which simplifies to

$$u_1 = - \int (x + 2) dx$$

Hence

$$u_1 = -\frac{1}{2}x^2 - 2x$$

And Eq. (3) becomes

$$u_2 = \int \frac{x^2(3x^4 + 6x^3)}{3x^8} dx$$

Which simplifies to

$$u_2 = \int \frac{x + 2}{x^3} dx$$

Hence

$$u_2 = -\frac{1}{x^2} - \frac{1}{x}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \left(-\frac{1}{2}x^2 - 2x\right)x^2 + \left(-\frac{1}{x^2} - \frac{1}{x}\right)x^5$$

Which simplifies to

$$y_p(x) = -\frac{3x^3(x+2)}{2}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= -\frac{3}{2}x^4 - 3x^3 + c_2x^5 + c_1x^2 \end{aligned}$$

Summary

The solution(s) found are the following

$$y = -\frac{3}{2}x^4 - 3x^3 + c_2x^5 + c_1x^2 \quad (1)$$

Verification of solutions

$$y = -\frac{3}{2}x^4 - 3x^3 + c_2x^5 + c_1x^2$$

Verified OK.

12.19.2 Solving as second order change of variable on x method 2 ode

This is second order non-homogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$x^2y'' - 6y'x + 10y = 0$$

In normal form the ode

$$x^2y'' - 6y'x + 10y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = -\frac{6}{x}$$
$$q(x) = \frac{10}{x^2}$$

Applying change of variables $\tau = g(x)$ to (2) gives

$$\frac{d^2}{d\tau^2}y(\tau) + p_1\left(\frac{d}{d\tau}y(\tau)\right) + q_1y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $p_1 = 0$. Eq (4) simplifies to

$$\tau''(x) + p(x)\tau'(x) = 0$$

This ode is solved resulting in

$$\begin{aligned}
 \tau &= \int e^{-(\int p(x)dx)} dx \\
 &= \int e^{-(\int -\frac{6}{x} dx)} dx \\
 &= \int e^{6\ln(x)} dx \\
 &= \int x^6 dx \\
 &= \frac{x^7}{7}
 \end{aligned} \tag{6}$$

Using (6) to evaluate q_1 from (5) gives

$$\begin{aligned}
 q_1(\tau) &= \frac{q(x)}{\tau'(x)^2} \\
 &= \frac{\frac{10}{x^2}}{x^{12}} \\
 &= \frac{10}{x^{14}}
 \end{aligned} \tag{7}$$

Substituting the above in (3) and noting that now $p_1 = 0$ results in

$$\begin{aligned}
 \frac{d^2}{d\tau^2}y(\tau) + q_1y(\tau) &= 0 \\
 \frac{d^2}{d\tau^2}y(\tau) + \frac{10y(\tau)}{x^{14}} &= 0
 \end{aligned}$$

But in terms of τ

$$\frac{10}{x^{14}} = \frac{10}{49\tau^2}$$

Hence the above ode becomes

$$\frac{d^2}{d\tau^2}y(\tau) + \frac{10y(\tau)}{49\tau^2} = 0$$

The above ode is now solved for $y(\tau)$. The ode can be written as

$$49 \left(\frac{d^2}{d\tau^2}y(\tau) \right) \tau^2 + 10y(\tau) = 0$$

Which shows it is a Euler ODE. This is Euler second order ODE. Let the solution be $y(\tau) = \tau^r$, then $y' = r\tau^{r-1}$ and $y'' = r(r-1)\tau^{r-2}$. Substituting these back into the given ODE gives

$$49\tau^2(r(r-1))\tau^{r-2} + 0r\tau^{r-1} + 10\tau^r = 0$$

Simplifying gives

$$49r(r - 1)\tau^r + 0\tau^r + 10\tau^r = 0$$

Since $\tau^r \neq 0$ then dividing throughout by τ^r gives

$$49r(r - 1) + 0 + 10 = 0$$

Or

$$49r^2 - 49r + 10 = 0 \tag{1}$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = \frac{2}{7}$$
$$r_2 = \frac{5}{7}$$

Since the roots are real and distinct, then the general solution is

$$y(\tau) = c_1y_1 + c_2y_2$$

Where $y_1 = \tau^{r_1}$ and $y_2 = \tau^{r_2}$. Hence

$$y(\tau) = c_1\tau^{\frac{2}{7}} + c_2\tau^{\frac{5}{7}}$$

The above solution is now transformed back to y using (6) which results in

$$y = \frac{c_1 7^{\frac{5}{7}} (x^7)^{\frac{2}{7}}}{7} + \frac{c_2 7^{\frac{2}{7}} (x^7)^{\frac{5}{7}}}{7}$$

Therefore the homogeneous solution y_h is

$$y_h = \frac{c_1 7^{\frac{5}{7}} (x^7)^{\frac{2}{7}}}{7} + \frac{c_2 7^{\frac{2}{7}} (x^7)^{\frac{5}{7}}}{7}$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1y_1 + u_2y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = (x^7)^{\frac{2}{7}}$$

$$y_2 = (x^7)^{\frac{5}{7}}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} (x^7)^{\frac{2}{7}} & (x^7)^{\frac{5}{7}} \\ \frac{d}{dx} \left((x^7)^{\frac{2}{7}} \right) & \frac{d}{dx} \left((x^7)^{\frac{5}{7}} \right) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} (x^7)^{\frac{2}{7}} & (x^7)^{\frac{5}{7}} \\ \frac{2x^6}{(x^7)^{\frac{5}{7}}} & \frac{5x^6}{(x^7)^{\frac{2}{7}}} \end{vmatrix}$$

Therefore

$$W = \left((x^7)^{\frac{2}{7}} \right) \left(\frac{5x^6}{(x^7)^{\frac{2}{7}}} \right) - \left((x^7)^{\frac{5}{7}} \right) \left(\frac{2x^6}{(x^7)^{\frac{5}{7}}} \right)$$

Which simplifies to

$$W = 3x^6$$

Which simplifies to

$$W = 3x^6$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{(x^7)^{\frac{5}{7}} (3x^4 + 6x^3)}{3x^8} dx$$

Which simplifies to

$$u_1 = - \int \frac{(x^7)^{\frac{5}{7}} (x + 2)}{x^5} dx$$

Hence

$$u_1 = - \frac{(x + 4) (x^7)^{\frac{5}{7}}}{2x^4}$$

And Eq. (3) becomes

$$u_2 = \int \frac{(x^7)^{\frac{2}{7}} (3x^4 + 6x^3)}{3x^8} dx$$

Which simplifies to

$$u_2 = \int \frac{(x^7)^{\frac{2}{7}} (x + 2)}{x^5} dx$$

Hence

$$u_2 = - \frac{(1 + x) (x^7)^{\frac{2}{7}}}{x^4}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = - \frac{x^3(x + 4)}{2} - (1 + x) x^3$$

Which simplifies to

$$y_p(x) = - \frac{3}{2} x^4 - 3x^3$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(\frac{c_1 7^{\frac{5}{7}} (x^7)^{\frac{2}{7}}}{7} + \frac{c_2 7^{\frac{2}{7}} (x^7)^{\frac{5}{7}}}{7} \right) + \left(- \frac{3}{2} x^4 - 3x^3 \right) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = \frac{c_1 7^{\frac{5}{7}} (x^7)^{\frac{2}{7}}}{7} + \frac{c_2 7^{\frac{2}{7}} (x^7)^{\frac{5}{7}}}{7} - \frac{3x^4}{2} - 3x^3 \quad (1)$$

Verification of solutions

$$y = \frac{c_1 7^{\frac{5}{7}} (x^7)^{\frac{2}{7}}}{7} + \frac{c_2 7^{\frac{2}{7}} (x^7)^{\frac{5}{7}}}{7} - \frac{3x^4}{2} - 3x^3$$

Verified OK.

12.19.3 Solving as second order change of variable on x method 1 ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = x^2$, $B = -6x$, $C = 10$, $f(x) = 3x^4 + 6x^3$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. Solving for y_h from

$$x^2 y'' - 6y'x + 10y = 0$$

In normal form the ode

$$x^2 y'' - 6y'x + 10y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = -\frac{6}{x}$$
$$q(x) = \frac{10}{x^2}$$

Applying change of variables $\tau = g(x)$ to (2) results

$$\frac{d^2}{d\tau^2}y(\tau) + p_1\left(\frac{d}{d\tau}y(\tau)\right) + q_1y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x) \tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $q_1 = c^2$ where c is some constant. Therefore from (5)

$$\begin{aligned} \tau' &= \frac{1}{c} \sqrt{q} \\ &= \frac{\sqrt{10} \sqrt{\frac{1}{x^2}}}{c} \\ \tau'' &= -\frac{\sqrt{10}}{c \sqrt{\frac{1}{x^2}} x^3} \end{aligned} \quad (6)$$

Substituting the above into (4) results in

$$\begin{aligned} p_1(\tau) &= \frac{\tau''(x) + p(x) \tau'(x)}{\tau'(x)^2} \\ &= \frac{-\frac{\sqrt{10}}{c \sqrt{\frac{1}{x^2}} x^3} - \frac{6}{x} \frac{\sqrt{10} \sqrt{\frac{1}{x^2}}}{c}}{\left(\frac{\sqrt{10} \sqrt{\frac{1}{x^2}}}{c}\right)^2} \\ &= -\frac{7c\sqrt{10}}{10} \end{aligned}$$

Therefore ode (3) now becomes

$$\begin{aligned} y(\tau)'' + p_1 y(\tau)' + q_1 y(\tau) &= 0 \\ \frac{d^2}{d\tau^2} y(\tau) - \frac{7c\sqrt{10}}{10} \left(\frac{d}{d\tau} y(\tau)\right) + c^2 y(\tau) &= 0 \end{aligned} \quad (7)$$

The above ode is now solved for $y(\tau)$. Since the ode is now constant coefficients, it can be easily solved to give

$$y(\tau) = e^{\frac{7\sqrt{10}c\tau}{20}} \left(c_1 \cosh \left(\frac{3\sqrt{10}c\tau}{20} \right) + ic_2 \sinh \left(\frac{3\sqrt{10}c\tau}{20} \right) \right)$$

Now from (6)

$$\begin{aligned}\tau &= \int \frac{1}{c} \sqrt{q} dx \\ &= \frac{\int \sqrt{10} \sqrt{\frac{1}{x^2}} dx}{c} \\ &= \frac{\sqrt{10} \sqrt{\frac{1}{x^2}} x \ln(x)}{c}\end{aligned}$$

Substituting the above into the solution obtained gives

$$y = x^{\frac{7}{2}} \left(c_1 \cosh \left(\frac{3 \ln(x)}{2} \right) + i c_2 \sinh \left(\frac{3 \ln(x)}{2} \right) \right)$$

Now the particular solution to this ODE is found

$$x^2 y'' - 6y'x + 10y = 3x^4 + 6x^3$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = (x^7)^{\frac{2}{7}}$$

$$y_2 = (x^7)^{\frac{5}{7}}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \tag{2}$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \tag{3}$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} (x^7)^{\frac{2}{7}} & (x^7)^{\frac{5}{7}} \\ \frac{d}{dx} \left((x^7)^{\frac{2}{7}} \right) & \frac{d}{dx} \left((x^7)^{\frac{5}{7}} \right) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} (x^7)^{\frac{2}{7}} & (x^7)^{\frac{5}{7}} \\ \frac{2x^6}{(x^7)^{\frac{5}{7}}} & \frac{5x^6}{(x^7)^{\frac{2}{7}}} \end{vmatrix}$$

Therefore

$$W = \left((x^7)^{\frac{2}{7}} \right) \left(\frac{5x^6}{(x^7)^{\frac{2}{7}}} \right) - \left((x^7)^{\frac{5}{7}} \right) \left(\frac{2x^6}{(x^7)^{\frac{5}{7}}} \right)$$

Which simplifies to

$$W = 3x^6$$

Which simplifies to

$$W = 3x^6$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{(x^7)^{\frac{5}{7}} (3x^4 + 6x^3)}{3x^8} dx$$

Which simplifies to

$$u_1 = - \int \frac{(x^7)^{\frac{5}{7}} (x + 2)}{x^5} dx$$

Hence

$$u_1 = - \frac{(x + 4) (x^7)^{\frac{5}{7}}}{2x^4}$$

And Eq. (3) becomes

$$u_2 = \int \frac{(x^7)^{\frac{2}{7}} (3x^4 + 6x^3)}{3x^8} dx$$

Which simplifies to

$$u_2 = \int \frac{(x^7)^{\frac{2}{7}}(x+2)}{x^5} dx$$

Hence

$$u_2 = -\frac{(1+x)(x^7)^{\frac{2}{7}}}{x^4}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = -\frac{x^3(x+4)}{2} - (1+x)x^3$$

Which simplifies to

$$y_p(x) = -\frac{3}{2}x^4 - 3x^3$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(x^{\frac{7}{2}} \left(c_1 \cosh \left(\frac{3 \ln(x)}{2} \right) + i c_2 \sinh \left(\frac{3 \ln(x)}{2} \right) \right) \right) + \left(-\frac{3}{2}x^4 - 3x^3 \right) \\ &= -\frac{3x^4}{2} - 3x^3 + x^{\frac{7}{2}} \left(c_1 \cosh \left(\frac{3 \ln(x)}{2} \right) + i c_2 \sinh \left(\frac{3 \ln(x)}{2} \right) \right) \end{aligned}$$

Which simplifies to

$$y = i \sinh \left(\frac{3 \ln(x)}{2} \right) x^{\frac{7}{2}} c_2 + \cosh \left(\frac{3 \ln(x)}{2} \right) x^{\frac{7}{2}} c_1 - \frac{3x^4}{2} - 3x^3$$

Summary

The solution(s) found are the following

$$y = i \sinh \left(\frac{3 \ln(x)}{2} \right) x^{\frac{7}{2}} c_2 + \cosh \left(\frac{3 \ln(x)}{2} \right) x^{\frac{7}{2}} c_1 - \frac{3x^4}{2} - 3x^3 \quad (1)$$

Verification of solutions

$$y = i \sinh \left(\frac{3 \ln(x)}{2} \right) x^{\frac{7}{2}} c_2 + \cosh \left(\frac{3 \ln(x)}{2} \right) x^{\frac{7}{2}} c_1 - \frac{3x^4}{2} - 3x^3$$

Verified OK.

12.19.4 Solving as second order change of variable on y method 2 ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = x^2$, $B = -6x$, $C = 10$, $f(x) = 3x^4 + 6x^3$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. Solving for y_h from

$$x^2y'' - 6y'x + 10y = 0$$

In normal form the ode

$$x^2y'' - 6y'x + 10y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = -\frac{6}{x}$$
$$q(x) = \frac{10}{x^2}$$

Applying change of variables on the dependent variable $y = v(x)x^n$ to (2) gives the following ode where the dependent variable is $v(x)$ and not y .

$$v''(x) + \left(\frac{2n}{x} + p\right)v'(x) + \left(\frac{n(n-1)}{x^2} + \frac{np}{x} + q\right)v(x) = 0 \quad (3)$$

Let the coefficient of $v(x)$ above be zero. Hence

$$\frac{n(n-1)}{x^2} + \frac{np}{x} + q = 0 \quad (4)$$

Substituting the earlier values found for $p(x)$ and $q(x)$ into (4) gives

$$\frac{n(n-1)}{x^2} - \frac{6n}{x^2} + \frac{10}{x^2} = 0 \quad (5)$$

Solving (5) for n gives

$$n = 5 \tag{6}$$

Substituting this value in (3) gives

$$\begin{aligned} v''(x) + \frac{4v'(x)}{x} &= 0 \\ v''(x) + \frac{4v'(x)}{x} &= 0 \end{aligned} \tag{7}$$

Using the substitution

$$u(x) = v'(x)$$

Then (7) becomes

$$u'(x) + \frac{4u(x)}{x} = 0 \tag{8}$$

The above is now solved for $u(x)$. In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= -\frac{4u}{x} \end{aligned}$$

Where $f(x) = -\frac{4}{x}$ and $g(u) = u$. Integrating both sides gives

$$\begin{aligned} \frac{1}{u} du &= -\frac{4}{x} dx \\ \int \frac{1}{u} du &= \int -\frac{4}{x} dx \\ \ln(u) &= -4 \ln(x) + c_1 \\ u &= e^{-4 \ln(x) + c_1} \\ &= \frac{c_1}{x^4} \end{aligned}$$

Now that $u(x)$ is known, then

$$\begin{aligned} v'(x) &= u(x) \\ v(x) &= \int u(x) dx + c_2 \\ &= -\frac{c_1}{3x^3} + c_2 \end{aligned}$$

Hence

$$\begin{aligned}y &= v(x) x^n \\ &= \left(-\frac{c_1}{3x^3} + c_2\right) x^5 \\ &= c_2 x^5 - \frac{1}{3} c_1 x^2\end{aligned}$$

Now the particular solution to this ODE is found

$$x^2 y'' - 6y'x + 10y = 3x^4 + 6x^3$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$\begin{aligned}y_1 &= x^2 \\ y_2 &= x^5\end{aligned}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \tag{2}$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \tag{3}$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} x^2 & x^5 \\ \frac{d}{dx}(x^2) & \frac{d}{dx}(x^5) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} x^2 & x^5 \\ 2x & 5x^4 \end{vmatrix}$$

Therefore

$$W = (x^2)(5x^4) - (x^5)(2x)$$

Which simplifies to

$$W = 3x^6$$

Which simplifies to

$$W = 3x^6$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{x^5(3x^4 + 6x^3)}{3x^8} dx$$

Which simplifies to

$$u_1 = - \int (x + 2) dx$$

Hence

$$u_1 = -\frac{1}{2}x^2 - 2x$$

And Eq. (3) becomes

$$u_2 = \int \frac{x^2(3x^4 + 6x^3)}{3x^8} dx$$

Which simplifies to

$$u_2 = \int \frac{x + 2}{x^3} dx$$

Hence

$$u_2 = -\frac{1}{x^2} - \frac{1}{x}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \left(-\frac{1}{2}x^2 - 2x\right)x^2 + \left(-\frac{1}{x^2} - \frac{1}{x}\right)x^5$$

Which simplifies to

$$y_p(x) = -\frac{3x^3(x+2)}{2}$$

Therefore the general solution is

$$\begin{aligned}y &= y_h + y_p \\&= \left(\left(-\frac{c_1}{3x^3} + c_2\right)x^5\right) + \left(-\frac{3x^3(x+2)}{2}\right) \\&= -\frac{3x^3(x+2)}{2} + \left(-\frac{c_1}{3x^3} + c_2\right)x^5\end{aligned}$$

Which simplifies to

$$y = -\frac{x^2(-6c_2x^3 + 9x^2 + 2c_1 + 18x)}{6}$$

Summary

The solution(s) found are the following

$$y = -\frac{x^2(-6c_2x^3 + 9x^2 + 2c_1 + 18x)}{6} \tag{1}$$

Verification of solutions

$$y = -\frac{x^2(-6c_2x^3 + 9x^2 + 2c_1 + 18x)}{6}$$

Verified OK.

12.19.5 Solving using Kovacic algorithm

Writing the ode as

$$x^2 y'' - 6y'x + 10y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= x^2 \\ B &= -6x \\ C &= 10 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{2}{x^2} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 2 \\ t &= x^2 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = \left(\frac{2}{x^2}\right) z(x) \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 461: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 2 - 0 \\ &= 2 \end{aligned}$$

The poles of r in eq. (7) and the order of each pole are determined by solving for the roots of $t = x^2$. There is a pole at $x = 0$ of order 2. Since there is no odd order pole larger than 2 and the order at ∞ is 2 then the necessary conditions for case one are met. Since there is a pole of order 2 then necessary conditions for case two are met. Since pole order is not larger than 2 and the order at ∞ is 2 then the necessary conditions for case three are met. Therefore

$$L = [1, 2, 4, 6, 12]$$

Attempting to find a solution using case $n = 1$.

Looking at poles of order 2. The partial fractions decomposition of r is

$$r = \frac{2}{x^2}$$

For the pole at $x = 0$ let b be the coefficient of $\frac{1}{x^2}$ in the partial fractions decomposition of r given above. Therefore $b = 2$. Hence

$$\begin{aligned} [\sqrt{r}]_c &= 0 \\ \alpha_c^+ &= \frac{1}{2} + \sqrt{1 + 4b} = 2 \\ \alpha_c^- &= \frac{1}{2} - \sqrt{1 + 4b} = -1 \end{aligned}$$

Since the order of r at ∞ is 2 then $[\sqrt{r}]_\infty = 0$. Let b be the coefficient of $\frac{1}{x^2}$ in the Laurent series expansion of r at ∞ . which can be found by dividing the leading coefficient of s by the leading coefficient of t from

$$r = \frac{s}{t} = \frac{2}{x^2}$$

Since the $\gcd(s, t) = 1$. This gives $b = 2$. Hence

$$\begin{aligned} [\sqrt{r}]_\infty &= 0 \\ \alpha_\infty^+ &= \frac{1}{2} + \sqrt{1 + 4b} = 2 \\ \alpha_\infty^- &= \frac{1}{2} - \sqrt{1 + 4b} = -1 \end{aligned}$$

The following table summarizes the findings so far for poles and for the order of r at ∞ where r is

$$r = \frac{2}{x^2}$$

pole c location	pole order	$[\sqrt{r}]_c$	α_c^+	α_c^-
0	2	0	2	-1

Order of r at ∞	$[\sqrt{r}]_\infty$	α_∞^+	α_∞^-
2	0	2	-1

Now that the all $[\sqrt{r}]_c$ and its associated α_c^\pm have been determined for all the poles in the set Γ and $[\sqrt{r}]_\infty$ and its associated α_∞^\pm have also been found, the next step is to determine possible non negative integer d from these using

$$d = \alpha_\infty^{s(\infty)} - \sum_{c \in \Gamma} \alpha_c^{s(c)}$$

Where $s(c)$ is either $+$ or $-$ and $s(\infty)$ is the sign of α_∞^\pm . This is done by trial over all set of families $s = (s(c))_{c \in \Gamma \cup \infty}$ until such d is found to work in finding candidate ω .

Trying $\alpha_{\infty}^{-} = -1$ then

$$\begin{aligned} d &= \alpha_{\infty}^{-} - (\alpha_{c_1}^{-}) \\ &= -1 - (-1) \\ &= 0 \end{aligned}$$

Since d an integer and $d \geq 0$ then it can be used to find ω using

$$\omega = \sum_{c \in \Gamma} \left(s(c)[\sqrt{r}]_c + \frac{\alpha_c^{s(c)}}{x - c} \right) + s(\infty)[\sqrt{r}]_{\infty}$$

The above gives

$$\begin{aligned} \omega &= \left((-)[\sqrt{r}]_{c_1} + \frac{\alpha_{c_1}^{-}}{x - c_1} \right) + (-)[\sqrt{r}]_{\infty} \\ &= -\frac{1}{x} + (-)(0) \\ &= -\frac{1}{x} \\ &= -\frac{1}{x} \end{aligned}$$

Now that ω is determined, the next step is find a corresponding minimal polynomial $p(x)$ of degree $d = 0$ to solve the ode. The polynomial $p(x)$ needs to satisfy the equation

$$p'' + 2\omega p' + (\omega' + \omega^2 - r)p = 0 \quad (1A)$$

Let

$$p(x) = 1 \quad (2A)$$

Substituting the above in eq. (1A) gives

$$\begin{aligned} (0) + 2\left(-\frac{1}{x}\right)(0) + \left(\left(\frac{1}{x^2}\right) + \left(-\frac{1}{x}\right)^2 - \left(\frac{2}{x^2}\right)\right) &= 0 \\ 0 &= 0 \end{aligned}$$

The equation is satisfied since both sides are zero. Therefore the first solution to the ode $z'' = rz$ is

$$\begin{aligned} z_1(x) &= p e^{\int \omega dx} \\ &= e^{\int -\frac{1}{x} dx} \\ &= \frac{1}{x} \end{aligned}$$

The first solution to the original ode in y is found from

$$\begin{aligned}y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\&= z_1 e^{-\int \frac{1}{2} \frac{-6x}{x^2} dx} \\&= z_1 e^{3 \ln(x)} \\&= z_1 (x^3)\end{aligned}$$

Which simplifies to

$$y_1 = x^2$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{6x}{x^2} dx}}{(y_1)^2} dx \\&= y_1 \int \frac{e^{6 \ln(x)}}{(y_1)^2} dx \\&= y_1 \left(\frac{x^3}{3} \right)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\&= c_1 (x^2) + c_2 \left(x^2 \left(\frac{x^3}{3} \right) \right)\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$x^2 y'' - 6y'x + 10y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1x^2 + \frac{1}{3}c_2x^5$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1y_1 + u_2y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = x^2$$

$$y_2 = \frac{x^5}{3}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \tag{2}$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \tag{3}$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} x^2 & \frac{x^5}{3} \\ \frac{d}{dx}(x^2) & \frac{d}{dx}\left(\frac{x^5}{3}\right) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} x^2 & \frac{x^5}{3} \\ 2x & \frac{5x^4}{3} \end{vmatrix}$$

Therefore

$$W = (x^2) \left(\frac{5x^4}{3} \right) - \left(\frac{x^5}{3} \right) (2x)$$

Which simplifies to

$$W = x^6$$

Which simplifies to

$$W = x^6$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{\frac{x^5(3x^4+6x^3)}{3}}{x^8} dx$$

Which simplifies to

$$u_1 = - \int (x + 2) dx$$

Hence

$$u_1 = -\frac{1}{2}x^2 - 2x$$

And Eq. (3) becomes

$$u_2 = \int \frac{x^2(3x^4 + 6x^3)}{x^8} dx$$

Which simplifies to

$$u_2 = \int \frac{3x + 6}{x^3} dx$$

Hence

$$u_2 = -\frac{3}{x^2} - \frac{3}{x}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \left(-\frac{1}{2}x^2 - 2x \right) x^2 + \frac{\left(-\frac{3}{x^2} - \frac{3}{x} \right) x^5}{3}$$

Which simplifies to

$$y_p(x) = -\frac{3x^3(x+2)}{2}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(c_1x^2 + \frac{1}{3}c_2x^5 \right) + \left(-\frac{3x^3(x+2)}{2} \right) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1x^2 + \frac{c_2x^5}{3} - \frac{3x^3(x+2)}{2} \quad (1)$$

Verification of solutions

$$y = c_1x^2 + \frac{c_2x^5}{3} - \frac{3x^3(x+2)}{2}$$

Verified OK.

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]  
trying a double symmetry of the form [xi=0, eta=F(x)]  
<- double symmetry of the form [xi=0, eta=F(x)] successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 26

```
dsolve(x^2*diff(y(x),x$2)-6*x*diff(y(x),x)+10*y(x)=3*x^4+6*x^3,y(x), singsol=all)
```

$$y(x) = -\frac{3}{2}x^4 - 3x^3 + \frac{1}{3}c_1x^5 + c_2x^2$$

✓ Solution by Mathematica

Time used: 0.016 (sec). Leaf size: 28

```
DSolve[x^2*y'[x]-6*x*y'[x]+10*y[x]==3*x^4+6*x^3,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow c_2 x^5 - \frac{3}{2}(x+2)x^3 + c_1 x^2$$

12.20 problem 20

12.20.1 Solving as linear second order ode solved by an integrating factor ode	3123
12.20.2 Solving as second order change of variable on x method 2 ode .	3125
12.20.3 Solving as second order change of variable on x method 1 ode .	3130
12.20.4 Solving as second order ode non constant coeff transformation on B ode	3135
12.20.5 Solving using Kovacic algorithm	3139

Internal problem ID [11848]

Internal file name [OUTPUT/11857_Saturday_April_13_2024_01_12_59_AM_10005007/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.4. Variation of parameters. Exercises page 162

Problem number: 20.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_change_of_variable_on_x_method_1", "second_order_change_of_variable_on_x_method_2", "linear_second_order_ode_solved_by_an_integrating_factor", "second_order_ode_non_constant_coeff_transformation_on_B"

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$(1+x)^2 y'' - 2(1+x)y' + 2y = 1$$

12.20.1 Solving as linear second order ode solved by an integrating factor ode

The ode satisfies this form

$$y'' + p(x)y' + \frac{(p(x)^2 + p'(x))y}{2} = f(x)$$

Where $p(x) = -\frac{2}{1+x}$. Therefore, there is an integrating factor given by

$$\begin{aligned}M(x) &= e^{\frac{1}{2} \int p dx} \\&= e^{\int -\frac{2}{1+x} dx} \\&= \frac{1}{1+x}\end{aligned}$$

Multiplying both sides of the ODE by the integrating factor $M(x)$ makes the left side of the ODE a complete differential

$$\begin{aligned}(M(x)y)'' &= \frac{1}{(1+x)^3} \\ \left(\frac{y}{1+x}\right)'' &= \frac{1}{(1+x)^3}\end{aligned}$$

Integrating once gives

$$\left(\frac{y}{1+x}\right)' = -\frac{1}{2(1+x)^2} + c_1$$

Integrating again gives

$$\left(\frac{y}{1+x}\right) = c_1x + \frac{1}{2+2x} + c_2$$

Hence the solution is

$$y = \frac{c_1x + \frac{1}{2+2x} + c_2}{\frac{1}{1+x}}$$

Or

$$y = (x^2 + x)c_1 + (x + 1)c_2 + \frac{x}{2x + 2} + \frac{1}{2x + 2}$$

Summary

The solution(s) found are the following

$$y = (x^2 + x)c_1 + (x + 1)c_2 + \frac{x}{2x + 2} + \frac{1}{2x + 2} \quad (1)$$

Verification of solutions

$$y = (x^2 + x)c_1 + (x + 1)c_2 + \frac{x}{2x + 2} + \frac{1}{2x + 2}$$

Verified OK.

12.20.2 Solving as second order change of variable on x method 2 ode

This is second order non-homogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$(x + 1)^2 y'' + (-2x - 2) y' + 2y = 0$$

In normal form the ode

$$(x + 1)^2 y'' + (-2x - 2) y' + 2y = 0 \quad (1)$$

Becomes

$$y'' + p(x) y' + q(x) y = 0 \quad (2)$$

Where

$$p(x) = -\frac{2}{x + 1}$$
$$q(x) = \frac{2}{(x + 1)^2}$$

Applying change of variables $\tau = g(x)$ to (2) gives

$$\frac{d^2}{d\tau^2} y(\tau) + p_1 \left(\frac{d}{d\tau} y(\tau) \right) + q_1 y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x) \tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $p_1 = 0$. Eq (4) simplifies to

$$\tau''(x) + p(x) \tau'(x) = 0$$

This ode is solved resulting in

$$\begin{aligned}\tau &= \int e^{-(\int p(x)dx)} dx \\ &= \int e^{-\left(\int -\frac{2}{x+1} dx\right)} dx \\ &= \int e^{2\ln(x+1)} dx \\ &= \int (x+1)^2 dx \\ &= \frac{(x+1)^3}{3}\end{aligned}\tag{6}$$

Using (6) to evaluate q_1 from (5) gives

$$\begin{aligned}q_1(\tau) &= \frac{q(x)}{\tau'(x)^2} \\ &= \frac{\frac{2}{(x+1)^2}}{(x+1)^4} \\ &= \frac{2}{(x+1)^6}\end{aligned}\tag{7}$$

Substituting the above in (3) and noting that now $p_1 = 0$ results in

$$\begin{aligned}\frac{d^2}{d\tau^2}y(\tau) + q_1y(\tau) &= 0 \\ \frac{d^2}{d\tau^2}y(\tau) + \frac{2y(\tau)}{(x+1)^6} &= 0\end{aligned}$$

But in terms of τ

$$\frac{2}{(x+1)^6} = \frac{2}{9\tau^2}$$

Hence the above ode becomes

$$\frac{d^2}{d\tau^2}y(\tau) + \frac{2y(\tau)}{9\tau^2} = 0$$

The above ode is now solved for $y(\tau)$. The ode can be written as

$$9\left(\frac{d^2}{d\tau^2}y(\tau)\right)\tau^2 + 2y(\tau) = 0$$

Which shows it is a Euler ODE. This is Euler second order ODE. Let the solution be $y(\tau) = \tau^r$, then $y' = r\tau^{r-1}$ and $y'' = r(r-1)\tau^{r-2}$. Substituting these back into the given ODE gives

$$9\tau^2(r(r-1))\tau^{r-2} + 0r\tau^{r-1} + 2\tau^r = 0$$

Simplifying gives

$$9r(r-1)\tau^r + 0\tau^r + 2\tau^r = 0$$

Since $\tau^r \neq 0$ then dividing throughout by τ^r gives

$$9r(r-1) + 0 + 2 = 0$$

Or

$$9r^2 - 9r + 2 = 0 \tag{1}$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = \frac{1}{3}$$

$$r_2 = \frac{2}{3}$$

Since the roots are real and distinct, then the general solution is

$$y(\tau) = c_1y_1 + c_2y_2$$

Where $y_1 = \tau^{r_1}$ and $y_2 = \tau^{r_2}$. Hence

$$y(\tau) = c_1\tau^{\frac{1}{3}} + c_2\tau^{\frac{2}{3}}$$

The above solution is now transformed back to y using (6) which results in

$$y = \frac{c_1 3^{\frac{2}{3}} ((x+1)^3)^{\frac{1}{3}}}{3} + \frac{c_2 3^{\frac{1}{3}} ((x+1)^3)^{\frac{2}{3}}}{3}$$

Therefore the homogeneous solution y_h is

$$y_h = \frac{c_1 3^{\frac{2}{3}} ((x+1)^3)^{\frac{1}{3}}}{3} + \frac{c_2 3^{\frac{1}{3}} ((x+1)^3)^{\frac{2}{3}}}{3}$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1y_1 + u_2y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = (x^3 + 3x^2 + 3x + 1)^{\frac{1}{3}}$$

$$y_2 = (x^3 + 3x^2 + 3x + 1)^{\frac{2}{3}}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} (x^3 + 3x^2 + 3x + 1)^{\frac{1}{3}} & (x^3 + 3x^2 + 3x + 1)^{\frac{2}{3}} \\ \frac{d}{dx} \left((x^3 + 3x^2 + 3x + 1)^{\frac{1}{3}} \right) & \frac{d}{dx} \left((x^3 + 3x^2 + 3x + 1)^{\frac{2}{3}} \right) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} (x^3 + 3x^2 + 3x + 1)^{\frac{1}{3}} & (x^3 + 3x^2 + 3x + 1)^{\frac{2}{3}} \\ \frac{3x^2 + 6x + 3}{3(x^3 + 3x^2 + 3x + 1)^{\frac{2}{3}}} & \frac{2x^2 + 4x + 2}{(x^3 + 3x^2 + 3x + 1)^{\frac{1}{3}}} \end{vmatrix}$$

Therefore

$$\begin{aligned} W &= \left((x^3 + 3x^2 + 3x + 1)^{\frac{1}{3}} \right) \left(\frac{2x^2 + 4x + 2}{(x^3 + 3x^2 + 3x + 1)^{\frac{1}{3}}} \right) \\ &\quad - \left((x^3 + 3x^2 + 3x + 1)^{\frac{2}{3}} \right) \left(\frac{3x^2 + 6x + 3}{3(x^3 + 3x^2 + 3x + 1)^{\frac{2}{3}}} \right) \end{aligned}$$

Which simplifies to

$$W = x^2 + 2x + 1$$

Which simplifies to

$$W = (x + 1)^2$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{(x^3 + 3x^2 + 3x + 1)^{\frac{2}{3}}}{(x + 1)^4} dx$$

Which simplifies to

$$u_1 = - \int \frac{((x + 1)^3)^{\frac{2}{3}}}{(x + 1)^4} dx$$

Hence

$$u_1 = \frac{((x + 1)^3)^{\frac{2}{3}}}{(x + 1)^3}$$

And Eq. (3) becomes

$$u_2 = \int \frac{(x^3 + 3x^2 + 3x + 1)^{\frac{1}{3}}}{(x + 1)^4} dx$$

Which simplifies to

$$u_2 = \int \frac{((x + 1)^3)^{\frac{1}{3}}}{(x + 1)^4} dx$$

Hence

$$u_2 = - \frac{((x + 1)^3)^{\frac{1}{3}}}{2(x + 1)^3}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \frac{((x + 1)^3)^{\frac{2}{3}} (x^3 + 3x^2 + 3x + 1)^{\frac{1}{3}}}{(x + 1)^3} - \frac{((x + 1)^3)^{\frac{1}{3}} (x^3 + 3x^2 + 3x + 1)^{\frac{2}{3}}}{2(x + 1)^3}$$

Which simplifies to

$$y_p(x) = \frac{1}{2}$$

Therefore the general solution is

$$y = y_h + y_p = \left(\frac{c_1 3^{\frac{2}{3}} ((x+1)^3)^{\frac{1}{3}}}{3} + \frac{c_2 3^{\frac{1}{3}} ((x+1)^3)^{\frac{2}{3}}}{3} \right) + \left(\frac{1}{2} \right)$$

Summary

The solution(s) found are the following

$$y = \frac{c_1 3^{\frac{2}{3}} ((x+1)^3)^{\frac{1}{3}}}{3} + \frac{c_2 3^{\frac{1}{3}} ((x+1)^3)^{\frac{2}{3}}}{3} + \frac{1}{2} \quad (1)$$

Verification of solutions

$$y = \frac{c_1 3^{\frac{2}{3}} ((x+1)^3)^{\frac{1}{3}}}{3} + \frac{c_2 3^{\frac{1}{3}} ((x+1)^3)^{\frac{2}{3}}}{3} + \frac{1}{2}$$

Verified OK.

12.20.3 Solving as second order change of variable on x method 1 ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = (x+1)^2$, $B = -2x - 2$, $C = 2$, $f(x) = 1$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$.

Solving for y_h from

$$(x+1)^2 y'' + (-2x-2)y' + 2y = 0$$

In normal form the ode

$$(x+1)^2 y'' + (-2x-2)y' + 2y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = -\frac{2}{x+1}$$

$$q(x) = \frac{2}{(x+1)^2}$$

Applying change of variables $\tau = g(x)$ to (2) results

$$\frac{d^2}{d\tau^2}y(\tau) + p_1\left(\frac{d}{d\tau}y(\tau)\right) + q_1y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $q_1 = c^2$ where c is some constant. Therefore from (5)

$$\tau' = \frac{1}{c}\sqrt{q}$$

$$= \frac{\sqrt{2}\sqrt{\frac{1}{(x+1)^2}}}{c} \quad (6)$$

$$\tau'' = -\frac{\sqrt{2}}{c\sqrt{\frac{1}{(x+1)^2}}(x+1)^3}$$

Substituting the above into (4) results in

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2}$$

$$= \frac{-\frac{\sqrt{2}}{c\sqrt{\frac{1}{(x+1)^2}}(x+1)^3} - \frac{2}{x+1}\frac{\sqrt{2}\sqrt{\frac{1}{(x+1)^2}}}{c}}{\left(\frac{\sqrt{2}\sqrt{\frac{1}{(x+1)^2}}}{c}\right)^2}$$

$$= -\frac{3c\sqrt{2}}{2}$$

Therefore ode (3) now becomes

$$y(\tau)'' + p_1y(\tau)' + q_1y(\tau) = 0$$

$$\frac{d^2}{d\tau^2}y(\tau) - \frac{3c\sqrt{2}}{2}\left(\frac{d}{d\tau}y(\tau)\right) + c^2y(\tau) = 0 \quad (7)$$

The above ode is now solved for $y(\tau)$. Since the ode is now constant coefficients, it can be easily solved to give

$$y(\tau) = e^{\frac{3\sqrt{2}c\tau}{4}} \left(c_1 \cosh \left(\frac{\sqrt{2}c\tau}{4} \right) + ic_2 \sinh \left(\frac{\sqrt{2}c\tau}{4} \right) \right)$$

Now from (6)

$$\begin{aligned} \tau &= \int \frac{1}{c} \sqrt{q} dx \\ &= \frac{\int \sqrt{2} \sqrt{\frac{1}{(x+1)^2}} dx}{c} \\ &= \frac{\sqrt{2} \sqrt{\frac{1}{(x+1)^2}} (x+1) \ln(x+1)}{c} \end{aligned}$$

Substituting the above into the solution obtained gives

$$y = (x+1)^{\frac{3}{2}} \left(c_1 \cosh \left(\frac{\ln(x+1)}{2} \right) + ic_2 \sinh \left(\frac{\ln(x+1)}{2} \right) \right)$$

Now the particular solution to this ODE is found

$$(x+1)^2 y'' + (-2x-2)y' + 2y = 1$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = (x^3 + 3x^2 + 3x + 1)^{\frac{1}{3}}$$

$$y_2 = (x^3 + 3x^2 + 3x + 1)^{\frac{2}{3}}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \tag{2}$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \tag{3}$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} (x^3 + 3x^2 + 3x + 1)^{\frac{1}{3}} & (x^3 + 3x^2 + 3x + 1)^{\frac{2}{3}} \\ \frac{d}{dx} \left((x^3 + 3x^2 + 3x + 1)^{\frac{1}{3}} \right) & \frac{d}{dx} \left((x^3 + 3x^2 + 3x + 1)^{\frac{2}{3}} \right) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} (x^3 + 3x^2 + 3x + 1)^{\frac{1}{3}} & (x^3 + 3x^2 + 3x + 1)^{\frac{2}{3}} \\ \frac{3x^2 + 6x + 3}{3(x^3 + 3x^2 + 3x + 1)^{\frac{2}{3}}} & \frac{2x^2 + 4x + 2}{(x^3 + 3x^2 + 3x + 1)^{\frac{1}{3}}} \end{vmatrix}$$

Therefore

$$W = \left((x^3 + 3x^2 + 3x + 1)^{\frac{1}{3}} \right) \left(\frac{2x^2 + 4x + 2}{(x^3 + 3x^2 + 3x + 1)^{\frac{1}{3}}} \right) - \left((x^3 + 3x^2 + 3x + 1)^{\frac{2}{3}} \right) \left(\frac{3x^2 + 6x + 3}{3(x^3 + 3x^2 + 3x + 1)^{\frac{2}{3}}} \right)$$

Which simplifies to

$$W = x^2 + 2x + 1$$

Which simplifies to

$$W = (x + 1)^2$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{(x^3 + 3x^2 + 3x + 1)^{\frac{2}{3}}}{(x + 1)^4} dx$$

Which simplifies to

$$u_1 = - \int \frac{((x + 1)^3)^{\frac{2}{3}}}{(x + 1)^4} dx$$

Hence

$$u_1 = \frac{((x + 1)^3)^{\frac{2}{3}}}{(x + 1)^3}$$

And Eq. (3) becomes

$$u_2 = \int \frac{(x^3 + 3x^2 + 3x + 1)^{\frac{1}{3}}}{(x + 1)^4} dx$$

Which simplifies to

$$u_2 = \int \frac{((x + 1)^3)^{\frac{1}{3}}}{(x + 1)^4} dx$$

Hence

$$u_2 = -\frac{((x + 1)^3)^{\frac{1}{3}}}{2(x + 1)^3}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \frac{((x + 1)^3)^{\frac{2}{3}} (x^3 + 3x^2 + 3x + 1)^{\frac{1}{3}}}{(x + 1)^3} - \frac{((x + 1)^3)^{\frac{1}{3}} (x^3 + 3x^2 + 3x + 1)^{\frac{2}{3}}}{2(x + 1)^3}$$

Which simplifies to

$$y_p(x) = \frac{1}{2}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left((x + 1)^{\frac{3}{2}} \left(c_1 \cosh \left(\frac{\ln(x + 1)}{2} \right) + ic_2 \sinh \left(\frac{\ln(x + 1)}{2} \right) \right) \right) + \left(\frac{1}{2} \right) \\ &= \frac{1}{2} + (x + 1)^{\frac{3}{2}} \left(c_1 \cosh \left(\frac{\ln(x + 1)}{2} \right) + ic_2 \sinh \left(\frac{\ln(x + 1)}{2} \right) \right) \end{aligned}$$

Which simplifies to

$$y = \frac{1}{2} + (x + 1)^{\frac{3}{2}} \left(c_1 \cosh \left(\frac{\ln(x + 1)}{2} \right) + ic_2 \sinh \left(\frac{\ln(x + 1)}{2} \right) \right)$$

Summary

The solution(s) found are the following

$$y = \frac{1}{2} + (x + 1)^{\frac{3}{2}} \left(c_1 \cosh \left(\frac{\ln(x + 1)}{2} \right) + ic_2 \sinh \left(\frac{\ln(x + 1)}{2} \right) \right) \quad (1)$$

Verification of solutions

$$y = \frac{1}{2} + (x + 1)^{\frac{3}{2}} \left(c_1 \cosh \left(\frac{\ln(x + 1)}{2} \right) + ic_2 \sinh \left(\frac{\ln(x + 1)}{2} \right) \right)$$

Verified OK.

12.20.4 Solving as second order ode non constant coeff transformation on B ode

Given an ode of the form

$$Ay'' + By' + Cy = F(x)$$

This method reduces the order ode the ODE by one by applying the transformation

$$y = Bv$$

This results in

$$\begin{aligned} y' &= B'v + v'B \\ y'' &= B''v + B'v' + v''B + v'B' \\ &= v''B + 2v' + B' + B''v \end{aligned}$$

And now the original ode becomes

$$\begin{aligned} A(v''B + 2v'B' + B''v) + B(B'v + v'B) + CBv &= 0 \\ ABv'' + (2AB' + B^2)v' + (AB'' + BB' + CB)v &= 0 \end{aligned} \quad (1)$$

If the term $AB'' + BB' + CB$ is zero, then this method works and can be used to solve

$$ABv'' + (2AB' + B^2)v' = 0$$

By Using $u = v'$ which reduces the order of the above ode to one. The new ode is

$$ABu' + (2AB' + B^2)u = 0$$

The above ode is first order ode which is solved for u . Now a new ode $v' = u$ is solved for v as first order ode. Then the final solution is obtain from $y = Bv$.

This method works only if the term $AB'' + BB' + CB$ is zero. The given ODE shows that

$$\begin{aligned} A &= (x + 1)^2 \\ B &= -2x - 2 \\ C &= 2 \\ F &= 1 \end{aligned}$$

The above shows that for this ode

$$\begin{aligned} AB'' + BB' + CB &= ((x+1)^2)(0) + (-2x-2)(-2) + (2)(-2x-2) \\ &= 0 \end{aligned}$$

Hence the ode in v given in (1) now simplifies to

$$-2(x+1)^3 v'' + (0)v' = 0$$

Now by applying $v' = u$ the above becomes

$$-2(x+1)^3 u'(x) = 0$$

Which is now solved for u . Integrating both sides gives

$$\begin{aligned} u(x) &= \int 0 \, dx \\ &= c_1 \end{aligned}$$

The ode for v now becomes

$$\begin{aligned} v' &= u \\ &= c_1 \end{aligned}$$

Which is now solved for v . Integrating both sides gives

$$\begin{aligned} v(x) &= \int c_1 \, dx \\ &= c_1 x + c_2 \end{aligned}$$

Therefore the homogeneous solution is

$$\begin{aligned} y_h(x) &= Bv \\ &= (-2x-2)(c_1 x + c_2) \\ &= -2(x+1)(c_1 x + c_2) \end{aligned}$$

And now the particular solution $y_p(x)$ will be found. The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = -2x - 2$$

$$y_2 = -2x^2 - 2x$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} -2x - 2 & -2x^2 - 2x \\ \frac{d}{dx}(-2x - 2) & \frac{d}{dx}(-2x^2 - 2x) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} -2x - 2 & -2x^2 - 2x \\ -2 & -4x - 2 \end{vmatrix}$$

Therefore

$$W = (-2x - 2)(-4x - 2) - (-2x^2 - 2x)(-2)$$

Which simplifies to

$$W = 4x^2 + 8x + 4$$

Which simplifies to

$$W = 4(x + 1)^2$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{-2x^2 - 2x}{4(x + 1)^4} dx$$

Which simplifies to

$$u_1 = - \int -\frac{x}{2(x+1)^3} dx$$

Hence

$$u_1 = -\frac{1}{2(x+1)} + \frac{1}{4(x+1)^2}$$

And Eq. (3) becomes

$$u_2 = \int \frac{-2x-2}{4(x+1)^4} dx$$

Which simplifies to

$$u_2 = \int -\frac{1}{2(x+1)^3} dx$$

Hence

$$u_2 = \frac{1}{4(x+1)^2}$$

Which simplifies to

$$u_1 = \frac{-2x-1}{4(x+1)^2}$$

$$u_2 = \frac{1}{4(x+1)^2}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \frac{(-2x-1)(-2x-2)}{4(x+1)^2} + \frac{-2x^2-2x}{4(x+1)^2}$$

Which simplifies to

$$y_p(x) = \frac{1}{2}$$

Hence the complete solution is

$$\begin{aligned}y(x) &= y_h + y_p \\&= (-2(x+1)(c_1x + c_2)) + \left(\frac{1}{2}\right) \\&= \frac{1}{2} - 2c_1x^2 + 2(-c_1 - c_2)x - 2c_2\end{aligned}$$

Summary

The solution(s) found are the following

$$y = \frac{1}{2} - 2c_1x^2 + 2(-c_1 - c_2)x - 2c_2 \quad (1)$$

Verification of solutions

$$y = \frac{1}{2} - 2c_1x^2 + 2(-c_1 - c_2)x - 2c_2$$

Verified OK.

12.20.5 Solving using Kovacic algorithm

Writing the ode as

$$(x+1)^2 y'' + (-2x-2)y' + 2y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$A = (x+1)^2$$

$$B = -2x - 2 \quad (3)$$

$$C = 2$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned}r &= \frac{s}{t} \\&= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2}\end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{0}{1} \tag{6}$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 0 \\ t &= 1 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = 0 \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 462: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - -\infty \\ &= \infty \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is *infinity* then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = 0$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = 1$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-2x-2}{(x+1)^2} dx} \\ &= z_1 e^{\ln(x+1)} \\ &= z_1(x+1) \end{aligned}$$

Which simplifies to

$$y_1 = x + 1$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{-2x-2}{(x+1)^2} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{2\ln(x+1)}}{(y_1)^2} dx \\ &= y_1(x) \end{aligned}$$

Therefore the solution is

$$\begin{aligned} y &= c_1 y_1 + c_2 y_2 \\ &= c_1(x+1) + c_2(x+1(x)) \end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$(x + 1)^2 y'' + (-2x - 2)y' + 2y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1(x + 1) + c_2x(x + 1)$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1y_1 + u_2y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = x + 1$$

$$y_2 = x(x + 1)$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \tag{2}$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \tag{3}$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} x + 1 & x(x + 1) \\ \frac{d}{dx}(x + 1) & \frac{d}{dx}(x(x + 1)) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} x + 1 & x(x + 1) \\ 1 & 2x + 1 \end{vmatrix}$$

Therefore

$$W = (x + 1)(2x + 1) - (x(x + 1)) \quad (1)$$

Which simplifies to

$$W = x^2 + 2x + 1$$

Which simplifies to

$$W = (x + 1)^2$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{x(x + 1)}{(x + 1)^4} dx$$

Which simplifies to

$$u_1 = - \int \frac{x}{(x + 1)^3} dx$$

Hence

$$u_1 = \frac{1}{x + 1} - \frac{1}{2(x + 1)^2}$$

And Eq. (3) becomes

$$u_2 = \int \frac{x + 1}{(x + 1)^4} dx$$

Which simplifies to

$$u_2 = \int \frac{1}{(x + 1)^3} dx$$

Hence

$$u_2 = -\frac{1}{2(x + 1)^2}$$

Which simplifies to

$$u_1 = \frac{2x + 1}{2(x + 1)^2}$$
$$u_2 = -\frac{1}{2(x + 1)^2}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \frac{2x + 1}{2x + 2} - \frac{x}{2(x + 1)}$$

Which simplifies to

$$y_p(x) = \frac{1}{2}$$

Therefore the general solution is

$$y = y_h + y_p$$
$$= (c_1(x + 1) + c_2x(x + 1)) + \left(\frac{1}{2}\right)$$

Which simplifies to

$$y = (x + 1)(c_2x + c_1) + \frac{1}{2}$$

Summary

The solution(s) found are the following

$$y = (x + 1)(c_2x + c_1) + \frac{1}{2} \tag{1}$$

Verification of solutions

$$y = (x + 1)(c_2x + c_1) + \frac{1}{2}$$

Verified OK.

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]  
trying a double symmetry of the form [xi=0, eta=F(x)]  
-> Try solving first the homogeneous part of the ODE  
    checking if the LODE has constant coefficients  
    checking if the LODE is of Euler type  
    <- LODE of Euler type successful  
<- solving first the homogeneous part of the ODE successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 17

```
dsolve((x+1)^2*diff(y(x),x$2)-2*(x+1)*diff(y(x),x)+2*y(x)=1,y(x), singsol=all)
```

$$y(x) = (1 + x)^2 c_1 + c_2 x + c_2 + \frac{1}{2}$$

✓ Solution by Mathematica

Time used: 0.032 (sec). Leaf size: 23

```
DSolve[(x+1)^2*y'[x]-2*(x+1)*y'[x]+2*y[x]==1,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow c_2(x + 1)^2 + c_1(x + 1) + \frac{1}{2}$$

12.21 problem 21

- 12.21.1 Solving as second order change of variable on y method 2 ode . 3146
- 12.21.2 Solving as second order ode non constant coeff transformation
on B ode 3151
- 12.21.3 Solving using Kovacic algorithm 3155

Internal problem ID [11849]

Internal file name [OUTPUT/11858_Saturday_April_13_2024_01_13_01_AM_84043608/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.4. Variation of parameters. Exercises page 162

Problem number: 21.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "**kovacic**", "**second_order_change_of_variable_on_y_method_2**", "**second_order_ode_non_constant_coeff_transformation_on_B**"

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$(x^2 + 2x)y'' - 2(x + 1)y' + 2y = (x + 2)^2$$

12.21.1 Solving as second order change of variable on y method 2 ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = x^2 + 2x$, $B = -2x - 2$, $C = 2$, $f(x) = (x + 2)^2$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. Solving for y_h from

$$(x^2 + 2x)y'' + (-2x - 2)y' + 2y = 0$$

In normal form the ode

$$(x^2 + 2x)y'' + (-2x - 2)y' + 2y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = \frac{-2x - 2}{x(x + 2)}$$
$$q(x) = \frac{2}{x(x + 2)}$$

Applying change of variables on the dependent variable $y = v(x)x^n$ to (2) gives the following ode where the dependent variable is $v(x)$ and not y .

$$v''(x) + \left(\frac{2n}{x} + p\right)v'(x) + \left(\frac{n(n-1)}{x^2} + \frac{np}{x} + q\right)v(x) = 0 \quad (3)$$

Let the coefficient of $v(x)$ above be zero. Hence

$$\frac{n(n-1)}{x^2} + \frac{np}{x} + q = 0 \quad (4)$$

Substituting the earlier values found for $p(x)$ and $q(x)$ into (4) gives

$$\frac{n(n-1)}{x^2} + \frac{n(-2x-2)}{x^2(x+2)} + \frac{2}{x(x+2)} = 0 \quad (5)$$

Solving (5) for n gives

$$n = 2 \quad (6)$$

Substituting this value in (3) gives

$$v''(x) + \left(\frac{4}{x} + \frac{-2x-2}{x(x+2)}\right)v'(x) = 0$$
$$v''(x) + \frac{(2x+6)v'(x)}{x(x+2)} = 0 \quad (7)$$

Using the substitution

$$u(x) = v'(x)$$

Then (7) becomes

$$u'(x) + \frac{(2x+6)u(x)}{x(x+2)} = 0 \quad (8)$$

The above is now solved for $u(x)$. In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= -\frac{2u(x+3)}{x(x+2)} \end{aligned}$$

Where $f(x) = -\frac{2(x+3)}{x(x+2)}$ and $g(u) = u$. Integrating both sides gives

$$\begin{aligned} \frac{1}{u} du &= -\frac{2(x+3)}{x(x+2)} dx \\ \int \frac{1}{u} du &= \int -\frac{2(x+3)}{x(x+2)} dx \\ \ln(u) &= -3\ln(x) + \ln(x+2) + c_1 \\ u &= e^{-3\ln(x)+\ln(x+2)+c_1} \\ &= c_1 e^{-3\ln(x)+\ln(x+2)} \end{aligned}$$

Which simplifies to

$$u(x) = c_1 \left(\frac{1}{x^2} + \frac{2}{x^3} \right)$$

Now that $u(x)$ is known, then

$$\begin{aligned} v'(x) &= u(x) \\ v(x) &= \int u(x) dx + c_2 \\ &= c_1 \left(-\frac{1}{x^2} - \frac{1}{x} \right) + c_2 \end{aligned}$$

Hence

$$\begin{aligned} y &= v(x) x^n \\ &= \left(c_1 \left(-\frac{1}{x^2} - \frac{1}{x} \right) + c_2 \right) x^2 \\ &= (-x-1)c_1 + c_2 x^2 \end{aligned}$$

Now the particular solution to this ODE is found

$$(x^2 + 2x)y'' + (-2x - 2)y' + 2y = (x + 2)^2$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1y_1 + u_2y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$\begin{aligned} y_1 &= x^2 \\ y_2 &= -x - 1 \end{aligned}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} x^2 & -x - 1 \\ \frac{d}{dx}(x^2) & \frac{d}{dx}(-x - 1) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} x^2 & -x - 1 \\ 2x & -1 \end{vmatrix}$$

Therefore

$$W = (x^2)(-1) - (-x - 1)(2x)$$

Which simplifies to

$$W = x^2 + 2x$$

Which simplifies to

$$W = x^2 + 2x$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{(-x - 1)(x + 2)^2}{(x^2 + 2x)^2} dx$$

Which simplifies to

$$u_1 = - \int \frac{-x - 1}{x^2} dx$$

Hence

$$u_1 = -\frac{1}{x} + \ln(x)$$

And Eq. (3) becomes

$$u_2 = \int \frac{x^2(x + 2)^2}{(x^2 + 2x)^2} dx$$

Which simplifies to

$$u_2 = \int 1 dx$$

Hence

$$u_2 = x$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \left(-\frac{1}{x} + \ln(x)\right) x^2 + (-x - 1)x$$

Which simplifies to

$$y_p(x) = x(x \ln(x) - x - 2)$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(\left(c_1 \left(-\frac{1}{x^2} - \frac{1}{x} \right) + c_2 \right) x^2 \right) + (x(x \ln(x) - x - 2)) \\ &= x(x \ln(x) - x - 2) + \left(c_1 \left(-\frac{1}{x^2} - \frac{1}{x} \right) + c_2 \right) x^2 \end{aligned}$$

Which simplifies to

$$y = x^2 \ln(x) + c_2 x^2 - c_1 x - x^2 - c_1 - 2x$$

Summary

The solution(s) found are the following

$$y = x^2 \ln(x) + c_2 x^2 - c_1 x - x^2 - c_1 - 2x \quad (1)$$

Verification of solutions

$$y = x^2 \ln(x) + c_2 x^2 - c_1 x - x^2 - c_1 - 2x$$

Verified OK.

12.21.2 Solving as second order ode non constant coeff transformation on B ode

Given an ode of the form

$$Ay'' + By' + Cy = F(x)$$

This method reduces the order ode the ODE by one by applying the transformation

$$y = Bv$$

This results in

$$\begin{aligned} y' &= B'v + v'B \\ y'' &= B''v + B'v' + v''B + v'B' \\ &= v''B + 2v' + B' + B''v \end{aligned}$$

And now the original ode becomes

$$\begin{aligned} A(v''B + 2v'B' + B''v) + B(B'v + v'B) + CBv &= 0 \\ ABv'' + (2AB' + B^2)v' + (AB'' + BB' + CB)v &= 0 \end{aligned} \quad (1)$$

If the term $AB'' + BB' + CB$ is zero, then this method works and can be used to solve

$$ABv'' + (2AB' + B^2)v' = 0$$

By Using $u = v'$ which reduces the order of the above ode to one. The new ode is

$$ABu' + (2AB' + B^2)u = 0$$

The above ode is first order ode which is solved for u . Now a new ode $v' = u$ is solved for v as first order ode. Then the final solution is obtain from $y = Bv$.

This method works only if the term $AB'' + BB' + CB$ is zero. The given ODE shows that

$$A = x^2 + 2x$$

$$B = -2x - 2$$

$$C = 2$$

$$F = (x + 2)^2$$

The above shows that for this ode

$$\begin{aligned} AB'' + BB' + CB &= (x^2 + 2x)(0) + (-2x - 2)(-2) + (2)(-2x - 2) \\ &= 0 \end{aligned}$$

Hence the ode in v given in (1) now simplifies to

$$-2x(x + 2)(x + 1)v'' + (4)v' = 0$$

Now by applying $v' = u$ the above becomes

$$(-2x^3 - 6x^2 - 4x)u'(x) + 4u(x) = 0$$

Which is now solved for u . In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= \frac{2u}{x(x^2 + 3x + 2)} \end{aligned}$$

Where $f(x) = \frac{2}{x(x^2 + 3x + 2)}$ and $g(u) = u$. Integrating both sides gives

$$\begin{aligned} \frac{1}{u} du &= \frac{2}{x(x^2 + 3x + 2)} dx \\ \int \frac{1}{u} du &= \int \frac{2}{x(x^2 + 3x + 2)} dx \\ \ln(u) &= -2 \ln(x + 1) + \ln(x) + \ln(x + 2) + c_1 \\ u &= e^{-2 \ln(x+1) + \ln(x) + \ln(x+2) + c_1} \\ &= c_1 e^{-2 \ln(x+1) + \ln(x) + \ln(x+2)} \end{aligned}$$

Which simplifies to

$$u(x) = c_1 \left(\frac{x^2}{(x+1)^2} + \frac{2x}{(x+1)^2} \right)$$

The ode for v now becomes

$$\begin{aligned} v' &= u \\ &= c_1 \left(\frac{x^2}{(x+1)^2} + \frac{2x}{(x+1)^2} \right) \end{aligned}$$

Which is now solved for v . Integrating both sides gives

$$\begin{aligned} v(x) &= \int \frac{c_1 x(x+2)}{(x+1)^2} dx \\ &= c_1 \left(x + \frac{1}{x+1} \right) + c_2 \end{aligned}$$

Therefore the homogeneous solution is

$$\begin{aligned} y_h(x) &= Bv \\ &= (-2x - 2) \left(c_1 \left(x + \frac{1}{x+1} \right) + c_2 \right) \\ &= (-2x^2 - 2x - 2) c_1 - 2(x+1) c_2 \end{aligned}$$

And now the particular solution $y_p(x)$ will be found. The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$\begin{aligned} y_1 &= -2x - 2 \\ y_2 &= -2x^2 - 2x - 2 \end{aligned}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \tag{2}$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \tag{3}$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} -2x - 2 & -2x^2 - 2x - 2 \\ \frac{d}{dx}(-2x - 2) & \frac{d}{dx}(-2x^2 - 2x - 2) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} -2x - 2 & -2x^2 - 2x - 2 \\ -2 & -4x - 2 \end{vmatrix}$$

Therefore

$$W = (-2x - 2)(-4x - 2) - (-2x^2 - 2x - 2)(-2)$$

Which simplifies to

$$W = 4x^2 + 8x$$

Which simplifies to

$$W = 4x^2 + 8x$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{(-2x^2 - 2x - 2)(x + 2)^2}{(x^2 + 2x)(4x^2 + 8x)} dx$$

Which simplifies to

$$u_1 = - \int \frac{-x^2 - x - 1}{2x^2} dx$$

Hence

$$u_1 = \frac{x}{2} - \frac{1}{2x} + \frac{\ln(x)}{2}$$

And Eq. (3) becomes

$$u_2 = \int \frac{(-2x - 2)(x + 2)^2}{(x^2 + 2x)(4x^2 + 8x)} dx$$

Which simplifies to

$$u_2 = \int \frac{-x-1}{2x^2} dx$$

Hence

$$u_2 = \frac{1}{2x} - \frac{\ln(x)}{2}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \left(\frac{x}{2} - \frac{1}{2x} + \frac{\ln(x)}{2} \right) (-2x-2) + \left(\frac{1}{2x} - \frac{\ln(x)}{2} \right) (-2x^2-2x-2)$$

Which simplifies to

$$y_p(x) = x(x \ln(x) - x - 2)$$

Hence the complete solution is

$$\begin{aligned} y(x) &= y_h + y_p \\ &= ((-2x^2 - 2x - 2)c_1 - 2(x+1)c_2) + (x(x \ln(x) - x - 2)) \\ &= x^2 \ln(x) + (-2c_1 - 1)x^2 + (-2c_1 - 2c_2 - 2)x - 2c_1 - 2c_2 \end{aligned}$$

Summary

The solution(s) found are the following

$$y = x^2 \ln(x) + (-2c_1 - 1)x^2 + (-2c_1 - 2c_2 - 2)x - 2c_1 - 2c_2 \quad (1)$$

Verification of solutions

$$y = x^2 \ln(x) + (-2c_1 - 1)x^2 + (-2c_1 - 2c_2 - 2)x - 2c_1 - 2c_2$$

Verified OK.

12.21.3 Solving using Kovacic algorithm

Writing the ode as

$$(x^2 + 2x)y'' + (-2x - 2)y' + 2y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= x^2 + 2x \\ B &= -2x - 2 \\ C &= 2 \end{aligned} \tag{3}$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{3}{(x^2 + 2x)^2} \tag{6}$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 3 \\ t &= (x^2 + 2x)^2 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = \left(\frac{3}{(x^2 + 2x)^2} \right) z(x) \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 463: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned}
 \mathcal{O}(\infty) &= \deg(t) - \deg(s) \\
 &= 4 - 0 \\
 &= 4
 \end{aligned}$$

The poles of r in eq. (7) and the order of each pole are determined by solving for the roots of $t = (x^2 + 2x)^2$. There is a pole at $x = 0$ of order 2. There is a pole at $x = -2$ of order 2. Since there is no odd order pole larger than 2 and the order at ∞ is 4 then the necessary conditions for case one are met. Since there is a pole of order 2 then necessary conditions for case two are met. Since pole order is not larger than 2 and the order at ∞ is 4 then the necessary conditions for case three are met. Therefore

$$L = [1, 2, 4, 6, 12]$$

Attempting to find a solution using case $n = 1$.

Looking at poles of order 2. The partial fractions decomposition of r is

$$r = \frac{3}{4x^2} + \frac{3}{4(x+2)^2} + \frac{3}{4(x+2)} - \frac{3}{4x}$$

For the pole at $x = -2$ let b be the coefficient of $\frac{1}{(x+2)^2}$ in the partial fractions decom-

position of r given above. Therefore $b = \frac{3}{4}$. Hence

$$\begin{aligned} [\sqrt{r}]_c &= 0 \\ \alpha_c^+ &= \frac{1}{2} + \sqrt{1 + 4b} = \frac{3}{2} \\ \alpha_c^- &= \frac{1}{2} - \sqrt{1 + 4b} = -\frac{1}{2} \end{aligned}$$

For the pole at $x = 0$ let b be the coefficient of $\frac{1}{x^2}$ in the partial fractions decomposition of r given above. Therefore $b = \frac{3}{4}$. Hence

$$\begin{aligned} [\sqrt{r}]_c &= 0 \\ \alpha_c^+ &= \frac{1}{2} + \sqrt{1 + 4b} = \frac{3}{2} \\ \alpha_c^- &= \frac{1}{2} - \sqrt{1 + 4b} = -\frac{1}{2} \end{aligned}$$

Since the order of r at ∞ is $4 > 2$ then

$$\begin{aligned} [\sqrt{r}]_\infty &= 0 \\ \alpha_\infty^+ &= 0 \\ \alpha_\infty^- &= 1 \end{aligned}$$

The following table summarizes the findings so far for poles and for the order of r at ∞ where r is

$$r = \frac{3}{(x^2 + 2x)^2}$$

pole c location	pole order	$[\sqrt{r}]_c$	α_c^+	α_c^-
-2	2	0	$\frac{3}{2}$	$-\frac{1}{2}$
0	2	0	$\frac{3}{2}$	$-\frac{1}{2}$

Order of r at ∞	$[\sqrt{r}]_\infty$	α_∞^+	α_∞^-
4	0	0	1

Now that the all $[\sqrt{r}]_c$ and its associated α_c^\pm have been determined for all the poles in the set Γ and $[\sqrt{r}]_\infty$ and its associated α_∞^\pm have also been found, the next step is to determine possible non negative integer d from these using

$$d = \alpha_\infty^{s(\infty)} - \sum_{c \in \Gamma} \alpha_c^{s(c)}$$

Where $s(c)$ is either $+$ or $-$ and $s(\infty)$ is the sign of α_∞^\pm . This is done by trial over all set of families $s = (s(c))_{c \in \Gamma \cup \infty}$ until such d is found to work in finding candidate ω . Trying $\alpha_\infty^- = 1$ then

$$\begin{aligned} d &= \alpha_\infty^- - (\alpha_{c_1}^- + \alpha_{c_2}^+) \\ &= 1 - (1) \\ &= 0 \end{aligned}$$

Since d an integer and $d \geq 0$ then it can be used to find ω using

$$\omega = \sum_{c \in \Gamma} \left(s(c) [\sqrt{r}]_c + \frac{\alpha_c^{s(c)}}{x - c} \right) + s(\infty) [\sqrt{r}]_\infty$$

The above gives

$$\begin{aligned} \omega &= \left((-) [\sqrt{r}]_{c_1} + \frac{\alpha_{c_1}^-}{x - c_1} \right) + \left((+) [\sqrt{r}]_{c_2} + \frac{\alpha_{c_2}^+}{x - c_2} \right) + (-) [\sqrt{r}]_\infty \\ &= -\frac{1}{2(x+2)} + \frac{3}{2x} + (-)(0) \\ &= -\frac{1}{2(x+2)} + \frac{3}{2x} \\ &= \frac{x+3}{x(x+2)} \end{aligned}$$

Now that ω is determined, the next step is find a corresponding minimal polynomial $p(x)$ of degree $d = 0$ to solve the ode. The polynomial $p(x)$ needs to satisfy the equation

$$p'' + 2\omega p' + (\omega' + \omega^2 - r) p = 0 \quad (1A)$$

Let

$$p(x) = 1 \quad (2A)$$

Substituting the above in eq. (1A) gives

$$(0) + 2 \left(-\frac{1}{2(x+2)} + \frac{3}{2x} \right) (0) + \left(\left(\frac{1}{2(x+2)^2} - \frac{3}{2x^2} \right) + \left(-\frac{1}{2(x+2)} + \frac{3}{2x} \right)^2 - \left(\frac{3}{(x^2+2x)^2} \right) \right) = 0$$

$0 = 0$

The equation is satisfied since both sides are zero. Therefore the first solution to the ode $z'' = rz$ is

$$\begin{aligned} z_1(x) &= p e^{\int \omega dx} \\ &= e^{\int \left(-\frac{1}{2(x+2)} + \frac{3}{2x} \right) dx} \\ &= \frac{x^{\frac{3}{2}}}{\sqrt{x+2}} \end{aligned}$$

The first solution to the original ode in y is found from

$$\begin{aligned}y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\&= z_1 e^{-\int \frac{1}{2} \frac{-2x-2}{x^2+2x} dx} \\&= z_1 e^{\frac{\ln(x(x+2))}{2}} \\&= z_1 \left(\sqrt{x(x+2)} \right)\end{aligned}$$

Which simplifies to

$$y_1 = \frac{x^{\frac{3}{2}} \sqrt{x(x+2)}}{\sqrt{x+2}}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{-2x-2}{x^2+2x} dx}}{(y_1)^2} dx \\&= y_1 \int \frac{e^{\ln(x(x+2))}}{(y_1)^2} dx \\&= y_1 \left(\frac{-x-1}{x^2} \right)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\&= c_1 \left(\frac{x^{\frac{3}{2}} \sqrt{x(x+2)}}{\sqrt{x+2}} \right) + c_2 \left(\frac{x^{\frac{3}{2}} \sqrt{x(x+2)}}{\sqrt{x+2}} \left(\frac{-x-1}{x^2} \right) \right)\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$(x^2 + 2x)y'' + (-2x - 2)y' + 2y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = \frac{c_1 x^{\frac{3}{2}} \sqrt{x(x+2)}}{\sqrt{x+2}} + \frac{c_2 \sqrt{x(x+2)}(-x-1)}{\sqrt{x}\sqrt{x+2}}$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \frac{x^{\frac{3}{2}} \sqrt{x(x+2)}}{\sqrt{x+2}}$$

$$y_2 = \frac{\sqrt{x(x+2)}(-x-1)}{\sqrt{x}\sqrt{x+2}}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \tag{2}$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \tag{3}$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \frac{x^{\frac{3}{2}} \sqrt{x(x+2)}}{\sqrt{x+2}} & \frac{\sqrt{x(x+2)}(-x-1)}{\sqrt{x}\sqrt{x+2}} \\ \frac{d}{dx} \left(\frac{x^{\frac{3}{2}} \sqrt{x(x+2)}}{\sqrt{x+2}} \right) & \frac{d}{dx} \left(\frac{\sqrt{x(x+2)}(-x-1)}{\sqrt{x}\sqrt{x+2}} \right) \end{vmatrix}$$

Which gives

$$W = \left| \begin{array}{cccccc} \frac{x^{\frac{3}{2}} \sqrt{x(x+2)}}{\sqrt{x+2}} & & & & & \frac{\sqrt{x(x+2)}(-x-1)}{\sqrt{x}\sqrt{x+2}} \\ \frac{3\sqrt{x}\sqrt{x(x+2)}}{2\sqrt{x+2}} & -\frac{x^{\frac{3}{2}}\sqrt{x(x+2)}}{2(x+2)^{\frac{3}{2}}} & +\frac{x^{\frac{3}{2}}(2x+2)}{2\sqrt{x+2}\sqrt{x(x+2)}} & -\frac{\sqrt{x(x+2)}(-x-1)}{2x^{\frac{3}{2}}\sqrt{x+2}} & -\frac{\sqrt{x(x+2)}(-x-1)}{2\sqrt{x}(x+2)^{\frac{3}{2}}} & +\frac{(-x-1)(2x+2)}{2\sqrt{x}\sqrt{x+2}\sqrt{x(x+2)}} & -\frac{\sqrt{x}}{\sqrt{x}} \end{array} \right|$$

Therefore

$$W = \left(\frac{x^{\frac{3}{2}} \sqrt{x(x+2)}}{\sqrt{x+2}} \right) \left(-\frac{\sqrt{x(x+2)}(-x-1)}{2x^{\frac{3}{2}}\sqrt{x+2}} - \frac{\sqrt{x(x+2)}(-x-1)}{2\sqrt{x}(x+2)^{\frac{3}{2}}} \right. \\ \left. + \frac{(-x-1)(2x+2)}{2\sqrt{x}\sqrt{x+2}\sqrt{x(x+2)}} - \frac{\sqrt{x(x+2)}}{\sqrt{x}\sqrt{x+2}} \right) \\ - \left(\frac{\sqrt{x(x+2)}(-x-1)}{\sqrt{x}\sqrt{x+2}} \right) \left(\frac{3\sqrt{x}\sqrt{x(x+2)}}{2\sqrt{x+2}} - \frac{x^{\frac{3}{2}}\sqrt{x(x+2)}}{2(x+2)^{\frac{3}{2}}} \right. \\ \left. + \frac{x^{\frac{3}{2}}(2x+2)}{2\sqrt{x+2}\sqrt{x(x+2)}} \right)$$

Which simplifies to

$$W = x(x+2)$$

Which simplifies to

$$W = x(x+2)$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{(x+2)^{\frac{3}{2}} \sqrt{x(x+2)}(-x-1)}{\frac{\sqrt{x}}{(x^2+2x)x(x+2)}} dx$$

Which simplifies to

$$u_1 = - \int \frac{(-x-1)\sqrt{x(x+2)}}{\sqrt{x+2}x^{\frac{5}{2}}} dx$$

Hence

$$u_1 = \frac{\sqrt{x(x+2)}(x \ln(x) - 1)}{\sqrt{x+2}x^{\frac{3}{2}}}$$

And Eq. (3) becomes

$$u_2 = \int \frac{x^{\frac{3}{2}}(x+2)^{\frac{3}{2}} \sqrt{x(x+2)}}{(x^2+2x)x(x+2)} dx$$

Which simplifies to

$$u_2 = \int \frac{\sqrt{x(x+2)}}{\sqrt{x}\sqrt{x+2}} dx$$

Hence

$$u_2 = \frac{\sqrt{x}\sqrt{x(x+2)}}{\sqrt{x+2}}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = x(x \ln(x) - 1) + (-x - 1)x$$

Which simplifies to

$$y_p(x) = x(x \ln(x) - x - 2)$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(\frac{c_1 x^{\frac{3}{2}} \sqrt{x(x+2)}}{\sqrt{x+2}} + \frac{c_2 \sqrt{x(x+2)}(-x-1)}{\sqrt{x}\sqrt{x+2}} \right) + (x(x \ln(x) - x - 2)) \end{aligned}$$

Which simplifies to

$$y = \frac{\sqrt{x(x+2)}((-x-1)c_2 + c_1 x^2)}{\sqrt{x+2}\sqrt{x}} + x(x \ln(x) - x - 2)$$

Summary

The solution(s) found are the following

$$y = \frac{\sqrt{x(x+2)}((-x-1)c_2 + c_1 x^2)}{\sqrt{x+2}\sqrt{x}} + x(x \ln(x) - x - 2) \quad (1)$$

Verification of solutions

$$y = \frac{\sqrt{x(x+2)}((-x-1)c_2 + c_1x^2)}{\sqrt{x+2}\sqrt{x}} + x(x \ln(x) - x - 2)$$

Verified OK.

Maple trace Kovacic algorithm successful

```
`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
trying a double symmetry of the form [xi=0, eta=F(x)]
-> Try solving first the homogeneous part of the ODE
    checking if the LODE has constant coefficients
    checking if the LODE is of Euler type
    trying a symmetry of the form [xi=0, eta=F(x)]
    checking if the LODE is missing y
-> Trying a Liouvillian solution using Kovacics algorithm
    A Liouvillian solution exists
    Reducible group (found an exponential solution)
<- Kovacics algorithm successful
<- solving first the homogeneous part of the ODE successful`
```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 24

```
dsolve((x^2+2*x)*diff(y(x),x$2)-2*(x+1)*diff(y(x),x)+2*y(x)=(x+2)^2,y(x), singsol=all)
```

$$y(x) = \ln(x)x^2 + (c_2 - 1)x^2 + (-2 + c_1)x + c_1$$

✓ Solution by Mathematica

Time used: 0.056 (sec). Leaf size: 31

```
DSolve[(x^2+2*x)*y'[x]-2*(x+1)*y'[x]+2*y[x]==(x+2)^2,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow x^2 \log(x) + (-1 + c_1)x^2 - (2 + c_2)x - c_2$$

12.22 problem 22

12.22.1 Solving as second order change of variable on y method 1 ode .	3165
12.22.2 Solving as second order change of variable on y method 2 ode .	3172
12.22.3 Solving using Kovacic algorithm	3176

Internal problem ID [11850]

Internal file name [OUTPUT/11859_Saturday_April_13_2024_01_13_03_AM_82095675/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.4. Variation of parameters. Exercises page 162

Problem number: 22.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_change_of_variable_on_y_method_1", "second_order_change_of_variable_on_y_method_2"

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$x^2y'' - x(x+2)y' + (x+2)y = x^3$$

12.22.1 Solving as second order change of variable on y method 1 ode

This is second order non-homogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$x^2y'' + (-x^2 - 2x)y' + (x+2)y = 0$$

In normal form the given ode is written as

$$y'' + p(x)y' + q(x)y = 0 \tag{2}$$

Where

$$p(x) = \frac{-x^2 - 2x}{x^2}$$

$$q(x) = \frac{x + 2}{x^2}$$

Calculating the Liouville ode invariant Q given by

$$\begin{aligned} Q &= q - \frac{p'}{2} - \frac{p^2}{4} \\ &= \frac{x + 2}{x^2} - \frac{\left(\frac{-x^2 - 2x}{x^2}\right)'}{2} - \frac{\left(\frac{-x^2 - 2x}{x^2}\right)^2}{4} \\ &= \frac{x + 2}{x^2} - \frac{\left(\frac{-2x - 2}{x^2} - \frac{2(-x^2 - 2x)}{x^3}\right)}{2} - \frac{\left(\frac{(-x^2 - 2x)^2}{x^4}\right)}{4} \\ &= \frac{x + 2}{x^2} - \left(\frac{-2x - 2}{2x^2} - \frac{-x^2 - 2x}{x^3}\right) - \frac{(-x^2 - 2x)^2}{4x^4} \\ &= -\frac{1}{4} \end{aligned}$$

Since the Liouville ode invariant does not depend on the independent variable x then the transformation

$$y = v(x) z(x) \tag{3}$$

is used to change the original ode to a constant coefficients ode in v . In (3) the term $z(x)$ is given by

$$\begin{aligned} z(x) &= e^{-\left(\int \frac{p(x)}{2} dx\right)} \\ &= e^{-\int \frac{-x^2 - 2x}{2} dx} \\ &= e^{\frac{x}{2}} x \end{aligned} \tag{5}$$

Hence (3) becomes

$$y = v(x) e^{\frac{x}{2}} x \tag{4}$$

Applying this change of variable to the original ode results in

$$e^{\frac{x}{2}}(4v''(x) - v(x)) = 4$$

Which is now solved for $v(x)$ Simplifying the ode gives

$$v''(x) - \frac{v(x)}{4} = e^{-\frac{x}{2}}$$

This is second order non-homogeneous ODE. In standard form the ODE is

$$Av''(x) + Bv'(x) + Cv(x) = f(x)$$

Where $A = 1, B = 0, C = -\frac{1}{4}, f(x) = e^{-\frac{x}{2}}$. Let the solution be

$$v(x) = v_h + v_p$$

Where v_h is the solution to the homogeneous ODE $Av''(x) + Bv'(x) + Cv(x) = 0$, and v_p is a particular solution to the non-homogeneous ODE $Av''(x) + Bv'(x) + Cv(x) = f(x)$. v_h is the solution to

$$v''(x) - \frac{v(x)}{4} = 0$$

This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Av''(x) + Bv'(x) + Cv(x) = 0$$

Where in the above $A = 1, B = 0, C = -\frac{1}{4}$. Let the solution be $v(x) = e^{\lambda x}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda x} - \frac{e^{\lambda x}}{4} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda x}$ gives

$$\lambda^2 - \frac{1}{4} = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 0, C = -\frac{1}{4}$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{0}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{0^2 - (4)(1) \left(-\frac{1}{4}\right)} \\ &= \pm \frac{1}{2} \end{aligned}$$

Hence

$$\lambda_1 = +\frac{1}{2}$$

$$\lambda_2 = -\frac{1}{2}$$

Which simplifies to

$$\lambda_1 = \frac{1}{2}$$

$$\lambda_2 = -\frac{1}{2}$$

Since roots are real and distinct, then the solution is

$$v(x) = c_1 e^{\lambda_1 x} + c_2 e^{\lambda_2 x}$$

$$v(x) = c_1 e^{(\frac{1}{2})x} + c_2 e^{(-\frac{1}{2})x}$$

Or

$$v(x) = c_1 e^{\frac{x}{2}} + c_2 e^{-\frac{x}{2}}$$

Therefore the homogeneous solution v_h is

$$v_h = c_1 e^{\frac{x}{2}} + c_2 e^{-\frac{x}{2}}$$

The particular solution is now found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$e^{-\frac{x}{2}}$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{e^{-\frac{x}{2}}\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^{-\frac{x}{2}}, e^{\frac{x}{2}}\}$$

Since $e^{-\frac{x}{2}}$ is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[\{x e^{-\frac{x}{2}}\}]$$

Since there was duplication between the basis functions in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis function in the above updated UC_set.

$$v_p = A_1 x e^{-\frac{x}{2}}$$

The unknowns $\{A_1\}$ are found by substituting the above trial solution v_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$-A_1 e^{-\frac{x}{2}} = e^{-\frac{x}{2}}$$

Solving for the unknowns by comparing coefficients results in

$$[A_1 = -1]$$

Substituting the above back in the above trial solution v_p , gives the particular solution

$$v_p = -x e^{-\frac{x}{2}}$$

Therefore the general solution is

$$\begin{aligned} v &= v_h + v_p \\ &= (c_1 e^{\frac{x}{2}} + c_2 e^{-\frac{x}{2}}) + (-x e^{-\frac{x}{2}}) \end{aligned}$$

Now that $v(x)$ is known, then

$$\begin{aligned} y &= v(x) z(x) \\ &= (c_1 e^{\frac{x}{2}} + c_2 e^{-\frac{x}{2}} - x e^{-\frac{x}{2}}) (z(x)) \end{aligned} \tag{7}$$

But from (5)

$$z(x) = e^{\frac{x}{2}} x$$

Hence (7) becomes

$$y = (c_1 e^{\frac{x}{2}} + c_2 e^{-\frac{x}{2}} - x e^{-\frac{x}{2}}) e^{\frac{x}{2}} x$$

Therefore the homogeneous solution y_h is

$$y_h = (c_1 e^{\frac{x}{2}} + c_2 e^{-\frac{x}{2}} - x e^{-\frac{x}{2}}) e^{\frac{x}{2}} x$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = x e^x$$

$$y_2 = e^{-\frac{x}{2}} e^{\frac{x}{2}} x$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} x e^x & e^{-\frac{x}{2}} e^{\frac{x}{2}} x \\ \frac{d}{dx}(x e^x) & \frac{d}{dx}(e^{-\frac{x}{2}} e^{\frac{x}{2}} x) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} x e^x & e^{-\frac{x}{2}} e^{\frac{x}{2}} x \\ x e^x + e^x & e^{-\frac{x}{2}} e^{\frac{x}{2}} \end{vmatrix}$$

Therefore

$$W = (x e^x) (e^{-\frac{x}{2}} e^{\frac{x}{2}}) - (e^{-\frac{x}{2}} e^{\frac{x}{2}} x) (x e^x + e^x)$$

Which simplifies to

$$W = -e^{\frac{3x}{2}} e^{-\frac{x}{2}} x^2$$

Which simplifies to

$$W = -x^2 e^x$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{e^{-\frac{x}{2}} e^{\frac{x}{2}} x^4}{-x^4 e^x} dx$$

Which simplifies to

$$u_1 = - \int -e^{-x} dx$$

Hence

$$u_1 = -e^{-x}$$

And Eq. (3) becomes

$$u_2 = \int \frac{x^4 e^x}{-x^4 e^x} dx$$

Which simplifies to

$$u_2 = \int (-1) dx$$

Hence

$$u_2 = -x$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = -e^{-x} e^x x - x^2 e^{-\frac{x}{2}} e^{\frac{x}{2}}$$

Which simplifies to

$$y_p(x) = -x^2 - x$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= ((c_1 e^{\frac{x}{2}} + c_2 e^{-\frac{x}{2}} - x e^{-\frac{x}{2}}) e^{\frac{x}{2}} x) + (-x^2 - x) \end{aligned}$$

Which simplifies to

$$y = x(e^x c_1 + c_2 - x) - x^2 - x$$

Summary

The solution(s) found are the following

$$y = x(e^x c_1 + c_2 - x) - x^2 - x \tag{1}$$

Verification of solutions

$$y = x(e^x c_1 + c_2 - x) - x^2 - x$$

Verified OK.

12.22.2 Solving as second order change of variable on y method 2 ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = x^2$, $B = -x^2 - 2x$, $C = x + 2$, $f(x) = x^3$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. Solving for y_h from

$$x^2y'' + (-x^2 - 2x)y' + (x + 2)y = 0$$

In normal form the ode

$$x^2y'' + (-x^2 - 2x)y' + (x + 2)y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = \frac{-x - 2}{x}$$
$$q(x) = \frac{x + 2}{x^2}$$

Applying change of variables on the dependent variable $y = v(x)x^n$ to (2) gives the following ode where the dependent variable is $v(x)$ and not y .

$$v''(x) + \left(\frac{2n}{x} + p\right)v'(x) + \left(\frac{n(n-1)}{x^2} + \frac{np}{x} + q\right)v(x) = 0 \quad (3)$$

Let the coefficient of $v(x)$ above be zero. Hence

$$\frac{n(n-1)}{x^2} + \frac{np}{x} + q = 0 \quad (4)$$

Substituting the earlier values found for $p(x)$ and $q(x)$ into (4) gives

$$\frac{n(n-1)}{x^2} + \frac{n(-x-2)}{x^2} + \frac{x+2}{x^2} = 0 \quad (5)$$

Solving (5) for n gives

$$n = 1 \tag{6}$$

Substituting this value in (3) gives

$$\begin{aligned} v''(x) + \left(\frac{2}{x} + \frac{-x-2}{x} \right) v'(x) &= 0 \\ v''(x) - v'(x) &= 0 \end{aligned} \tag{7}$$

Using the substitution

$$u(x) = v'(x)$$

Then (7) becomes

$$u'(x) - u(x) = 0 \tag{8}$$

The above is now solved for $u(x)$. Integrating both sides gives

$$\begin{aligned} \int \frac{1}{u} du &= x + c_1 \\ \ln(u) &= x + c_1 \\ u &= e^{x+c_1} \\ u &= e^x c_1 \end{aligned}$$

Now that $u(x)$ is known, then

$$\begin{aligned} v'(x) &= u(x) \\ v(x) &= \int u(x) dx + c_2 \\ &= e^x c_1 + c_2 \end{aligned}$$

Hence

$$\begin{aligned} y &= v(x) x^n \\ &= (e^x c_1 + c_2) x \\ &= (e^x c_1 + c_2) x \end{aligned}$$

Now the particular solution to this ODE is found

$$x^2 y'' + (-x^2 - 2x) y' + (x + 2) y = x^3$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$\begin{aligned} y_1 &= x \\ y_2 &= x e^x \end{aligned}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} x & x e^x \\ \frac{d}{dx}(x) & \frac{d}{dx}(x e^x) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} x & x e^x \\ 1 & x e^x + e^x \end{vmatrix}$$

Therefore

$$W = (x)(x e^x + e^x) - (x e^x)(1)$$

Which simplifies to

$$W = x^2 e^x$$

Which simplifies to

$$W = x^2 e^x$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{x^4 e^x}{x^4 e^x} dx$$

Which simplifies to

$$u_1 = - \int 1 dx$$

Hence

$$u_1 = -x$$

And Eq. (3) becomes

$$u_2 = \int \frac{x^4}{x^4 e^x} dx$$

Which simplifies to

$$u_2 = \int e^{-x} dx$$

Hence

$$u_2 = -e^{-x}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = -x^2 - e^{-x} e^x x$$

Which simplifies to

$$y_p(x) = -x^2 - x$$

Therefore the general solution is

$$\begin{aligned}y &= y_h + y_p \\&= ((e^x c_1 + c_2) x) + (-x^2 - x) \\&= -x^2 - x + (e^x c_1 + c_2) x\end{aligned}$$

Which simplifies to

$$y = x(e^x c_1 + c_2 - x - 1)$$

Summary

The solution(s) found are the following

$$y = x(e^x c_1 + c_2 - x - 1) \quad (1)$$

Verification of solutions

$$y = x(e^x c_1 + c_2 - x - 1)$$

Verified OK.

12.22.3 Solving using Kovacic algorithm

Writing the ode as

$$x^2 y'' + (-x^2 - 2x) y' + (x + 2) y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned}A &= x^2 \\B &= -x^2 - 2x \\C &= x + 2\end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$r = \frac{s}{t} \tag{5}$$

$$= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{1}{4} \tag{6}$$

Comparing the above to (5) shows that

$$s = 1$$

$$t = 4$$

Therefore eq. (4) becomes

$$z''(x) = \frac{z(x)}{4} \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 464: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - 0 \\ &= 0 \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = \frac{1}{4}$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = e^{-\frac{x}{2}}$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-x^2-2x}{x^2} dx} \\ &= z_1 e^{\frac{x}{2} + \ln(x)} \\ &= z_1 (e^{\frac{x}{2}} x) \end{aligned}$$

Which simplifies to

$$y_1 = x$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{-x^2-2x}{x^2} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{x+2\ln(x)}}{(y_1)^2} dx \\ &= y_1 (e^x) \end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1(x) + c_2(x e^x)\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$x^2 y'' + (-x^2 - 2x) y' + (x + 2) y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1 x + c_2 x e^x$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$\begin{aligned}y_1 &= x \\ y_2 &= x e^x\end{aligned}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \tag{2}$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \tag{3}$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} x & x e^x \\ \frac{d}{dx}(x) & \frac{d}{dx}(x e^x) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} x & x e^x \\ 1 & x e^x + e^x \end{vmatrix}$$

Therefore

$$W = (x)(x e^x + e^x) - (x e^x)(1)$$

Which simplifies to

$$W = x^2 e^x$$

Which simplifies to

$$W = x^2 e^x$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{x^4 e^x}{x^4 e^x} dx$$

Which simplifies to

$$u_1 = - \int 1 dx$$

Hence

$$u_1 = -x$$

And Eq. (3) becomes

$$u_2 = \int \frac{x^4}{x^4 e^x} dx$$

Which simplifies to

$$u_2 = \int e^{-x} dx$$

Hence

$$u_2 = -e^{-x}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = -x^2 - e^{-x}e^x x$$

Which simplifies to

$$y_p(x) = -x^2 - x$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1x + c_2xe^x) + (-x^2 - x) \end{aligned}$$

Which simplifies to

$$y = x(c_1 + c_2e^x) - x^2 - x$$

Summary

The solution(s) found are the following

$$y = x(c_1 + c_2e^x) - x^2 - x \tag{1}$$

Verification of solutions

$$y = x(c_1 + c_2e^x) - x^2 - x$$

Verified OK.

Maple trace Kovacic algorithm successful

```
`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
trying a double symmetry of the form [xi=0, eta=F(x)]
-> Try solving first the homogeneous part of the ODE
    checking if the LODE has constant coefficients
    checking if the LODE is of Euler type
    trying a symmetry of the form [xi=0, eta=F(x)]
    checking if the LODE is missing y
-> Trying a Liouvillian solution using Kovacics algorithm
    A Liouvillian solution exists
    Reducible group (found an exponential solution)
    Reducible group (found another exponential solution)
<- Kovacics algorithm successful
<- solving first the homogeneous part of the ODE successful`
```

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 15

```
dsolve(x^2*diff(y(x),x$2)-x*(x+2)*diff(y(x),x)+(x+2)*y(x)=x^3,y(x), singsol=all)
```

$$y(x) = x(-x + c_1 e^x + c_2)$$

✓ Solution by Mathematica

Time used: 0.035 (sec). Leaf size: 22

```
DSolve[x^2*y''[x]-x*(x+2)*y'[x]+(x+2)*y[x]==x^3,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow -x(x - c_2 e^x + 1 - c_1)$$

12.23 problem 23

12.23.1 Solving as second order change of variable on y method 2 ode . 3183

12.23.2 Solving using Kovacic algorithm 3188

Internal problem ID [11851]

Internal file name [OUTPUT/11860_Saturday_April_13_2024_01_13_04_AM_25656480/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.4. Variation of parameters. Exercises page 162

Problem number: 23.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_change_of_variable_on_y_method_2"

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$x(x-2)y'' - (x^2-2)y' + 2y(x-1) = 3x^2(x-2)^2 e^x$$

12.23.1 Solving as second order change of variable on y method 2 ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = x^2 - 2x$, $B = -x^2 + 2$, $C = 2x - 2$, $f(x) = 3x^2(x-2)^2 e^x$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. Solving for y_h from

$$(x^2 - 2x)y'' + (-x^2 + 2)y' + (2x - 2)y = 0$$

In normal form the ode

$$(x^2 - 2x)y'' + (-x^2 + 2)y' + (2x - 2)y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = \frac{-x^2 + 2}{x(x - 2)}$$
$$q(x) = \frac{2x - 2}{x(x - 2)}$$

Applying change of variables on the dependent variable $y = v(x)x^n$ to (2) gives the following ode where the dependent variables is $v(x)$ and not y .

$$v''(x) + \left(\frac{2n}{x} + p\right)v'(x) + \left(\frac{n(n-1)}{x^2} + \frac{np}{x} + q\right)v(x) = 0 \quad (3)$$

Let the coefficient of $v(x)$ above be zero. Hence

$$\frac{n(n-1)}{x^2} + \frac{np}{x} + q = 0 \quad (4)$$

Substituting the earlier values found for $p(x)$ and $q(x)$ into (4) gives

$$\frac{n(n-1)}{x^2} + \frac{n(-x^2 + 2)}{x^2(x-2)} + \frac{2x-2}{x(x-2)} = 0 \quad (5)$$

Solving (5) for n gives

$$n = 2 \quad (6)$$

Substituting this value in (3) gives

$$v''(x) + \left(\frac{4}{x} + \frac{-x^2 + 2}{x(x-2)}\right)v'(x) = 0$$
$$v''(x) + \frac{(-x^2 + 4x - 6)v'(x)}{x(x-2)} = 0 \quad (7)$$

Using the substitution

$$u(x) = v'(x)$$

Then (7) becomes

$$u'(x) + \frac{(-x^2 + 4x - 6)u(x)}{x(x-2)} = 0 \quad (8)$$

The above is now solved for $u(x)$. In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= \frac{u(x^2 - 4x + 6)}{x(x-2)} \end{aligned}$$

Where $f(x) = \frac{x^2 - 4x + 6}{x(x-2)}$ and $g(u) = u$. Integrating both sides gives

$$\begin{aligned} \frac{1}{u} du &= \frac{x^2 - 4x + 6}{x(x-2)} dx \\ \int \frac{1}{u} du &= \int \frac{x^2 - 4x + 6}{x(x-2)} dx \\ \ln(u) &= x + \ln(x-2) - 3 \ln(x) + c_1 \\ u &= e^{x + \ln(x-2) - 3 \ln(x) + c_1} \\ &= c_1 e^{x + \ln(x-2) - 3 \ln(x)} \end{aligned}$$

Which simplifies to

$$u(x) = c_1 \left(\frac{e^x}{x^2} - \frac{2e^x}{x^3} \right)$$

Now that $u(x)$ is known, then

$$\begin{aligned} v'(x) &= u(x) \\ v(x) &= \int u(x) dx + c_2 \\ &= \frac{e^x c_1}{x^2} + c_2 \end{aligned}$$

Hence

$$\begin{aligned} y &= v(x) x^n \\ &= \left(\frac{e^x c_1}{x^2} + c_2 \right) x^2 \\ &= c_2 x^2 + e^x c_1 \end{aligned}$$

Now the particular solution to this ODE is found

$$(x^2 - 2x) y'' + (-x^2 + 2) y' + (2x - 2) y = 3x^2(x - 2)^2 e^x$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = x^2$$

$$y_2 = e^x$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} x^2 & e^x \\ \frac{d}{dx}(x^2) & \frac{d}{dx}(e^x) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} x^2 & e^x \\ 2x & e^x \end{vmatrix}$$

Therefore

$$W = (x^2)(e^x) - (e^x)(2x)$$

Which simplifies to

$$W = x^2 e^x - 2x e^x$$

Which simplifies to

$$W = e^x(x - 2)x$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{3e^{2x}(x-2)^2 x^2}{(x^2-2x)e^x(x-2)x} dx$$

Which simplifies to

$$u_1 = - \int 3e^x dx$$

Hence

$$u_1 = -3e^x$$

And Eq. (3) becomes

$$u_2 = \int \frac{3x^4(x-2)^2 e^x}{(x^2-2x)e^x(x-2)x} dx$$

Which simplifies to

$$u_2 = \int 3x^2 dx$$

Hence

$$u_2 = x^3$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = -3x^2 e^x + x^3 e^x$$

Which simplifies to

$$y_p(x) = e^x x^2(x - 3)$$

Therefore the general solution is

$$\begin{aligned}y &= y_h + y_p \\&= \left(\left(\frac{e^x c_1}{x^2} + c_2 \right) x^2 \right) + (e^x x^2 (x - 3)) \\&= e^x x^2 (x - 3) + \left(\frac{e^x c_1}{x^2} + c_2 \right) x^2\end{aligned}$$

Which simplifies to

$$y = (x^3 - 3x^2 + c_1) e^x + c_2 x^2$$

Summary

The solution(s) found are the following

$$y = (x^3 - 3x^2 + c_1) e^x + c_2 x^2 \quad (1)$$

Verification of solutions

$$y = (x^3 - 3x^2 + c_1) e^x + c_2 x^2$$

Verified OK.

12.23.2 Solving using Kovacic algorithm

Writing the ode as

$$(x^2 - 2x) y'' + (-x^2 + 2) y' + (2x - 2) y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned}A &= x^2 - 2x \\B &= -x^2 + 2 \\C &= 2x - 2\end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$r = \frac{s}{t} \tag{5}$$

$$= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{x^4 - 8x^3 + 24x^2 - 24x + 12}{4(x^2 - 2x)^2} \tag{6}$$

Comparing the above to (5) shows that

$$s = x^4 - 8x^3 + 24x^2 - 24x + 12$$

$$t = 4(x^2 - 2x)^2$$

Therefore eq. (4) becomes

$$z''(x) = \left(\frac{x^4 - 8x^3 + 24x^2 - 24x + 12}{4(x^2 - 2x)^2} \right) z(x) \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 465: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 4 - 4 \\ &= 0 \end{aligned}$$

The poles of r in eq. (7) and the order of each pole are determined by solving for the roots of $t = 4(x^2 - 2x)^2$. There is a pole at $x = 2$ of order 2. There is a pole at $x = 0$ of order 2. Since there is no odd order pole larger than 2 and the order at ∞ is 0 then the necessary conditions for case one are met. Since there is a pole of order 2 then necessary conditions for case two are met. Therefore

$$L = [1, 2]$$

Attempting to find a solution using case $n = 1$.

Looking at poles of order 2. The partial fractions decomposition of r is

$$r = \frac{1}{4} + \frac{3}{4x^2} - \frac{1}{4(x-2)} + \frac{3}{4(x-2)^2} - \frac{3}{4x}$$

For the pole at $x = 0$ let b be the coefficient of $\frac{1}{x^2}$ in the partial fractions decomposition of r given above. Therefore $b = \frac{3}{4}$. Hence

$$\begin{aligned} [\sqrt{r}]_c &= 0 \\ \alpha_c^+ &= \frac{1}{2} + \sqrt{1 + 4b} = \frac{3}{2} \\ \alpha_c^- &= \frac{1}{2} - \sqrt{1 + 4b} = -\frac{1}{2} \end{aligned}$$

For the pole at $x = 2$ let b be the coefficient of $\frac{1}{(x-2)^2}$ in the partial fractions decomposition of r given above. Therefore $b = \frac{3}{4}$. Hence

$$\begin{aligned} [\sqrt{r}]_c &= 0 \\ \alpha_c^+ &= \frac{1}{2} + \sqrt{1 + 4b} = \frac{3}{2} \\ \alpha_c^- &= \frac{1}{2} - \sqrt{1 + 4b} = -\frac{1}{2} \end{aligned}$$

Since the order of r at ∞ is $O_r(\infty) = 0$ then

$$v = \frac{-O_r(\infty)}{2} = \frac{0}{2} = 0$$

$[\sqrt{r}]_\infty$ is the sum of terms involving x^i for $0 \leq i \leq v$ in the Laurent series for \sqrt{r} at ∞ . Therefore

$$\begin{aligned} [\sqrt{r}]_\infty &= \sum_{i=0}^v a_i x^i \\ &= \sum_{i=0}^0 a_i x^i \end{aligned} \tag{8}$$

Let a be the coefficient of $x^v = x^0$ in the above sum. The Laurent series of \sqrt{r} at ∞ is

$$\sqrt{r} \approx \frac{1}{2} - \frac{1}{x} + \frac{2}{x^3} + \frac{11}{x^4} + \frac{42}{x^5} + \frac{132}{x^6} + \frac{348}{x^7} + \frac{711}{x^8} + \dots \tag{9}$$

Comparing Eq. (9) with Eq. (8) shows that

$$a = \frac{1}{2}$$

From Eq. (9) the sum up to $v = 0$ gives

$$\begin{aligned} [\sqrt{r}]_\infty &= \sum_{i=0}^0 a_i x^i \\ &= \frac{1}{2} \end{aligned} \tag{10}$$

Now we need to find b , where b be the coefficient of $x^{v-1} = x^{-1} = \frac{1}{x}$ in r minus the coefficient of same term but in $([\sqrt{r}]_\infty)^2$ where $[\sqrt{r}]_\infty$ was found above in Eq (10). Hence

$$([\sqrt{r}]_\infty)^2 = \frac{1}{4}$$

This shows that the coefficient of $\frac{1}{x}$ in the above is 0. Now we need to find the coefficient of $\frac{1}{x}$ in r . How this is done depends on if $v = 0$ or not. Since $v = 0$ then starting from $r = \frac{s}{t}$ and doing long division in the form

$$r = Q + \frac{R}{t}$$

Where Q is the quotient and R is the remainder. Then the coefficient of $\frac{1}{x}$ in r will be the coefficient in R of the term in x of degree of t minus one, divided by the leading

coefficient in t . Doing long division gives

$$\begin{aligned}
 r &= \frac{s}{t} \\
 &= \frac{x^4 - 8x^3 + 24x^2 - 24x + 12}{4x^4 - 16x^3 + 16x^2} \\
 &= Q + \frac{R}{4x^4 - 16x^3 + 16x^2} \\
 &= \left(\frac{1}{4}\right) + \left(\frac{-4x^3 + 20x^2 - 24x + 12}{4x^4 - 16x^3 + 16x^2}\right) \\
 &= \frac{1}{4} + \frac{-4x^3 + 20x^2 - 24x + 12}{4x^4 - 16x^3 + 16x^2}
 \end{aligned}$$

Since the degree of t is 4, then we see that the coefficient of the term x^3 in the remainder R is -4 . Dividing this by leading coefficient in t which is 4 gives -1 . Now b can be found.

$$\begin{aligned}
 b &= (-1) - (0) \\
 &= -1
 \end{aligned}$$

Hence

$$\begin{aligned}
 [\sqrt{r}]_\infty &= \frac{1}{2} \\
 \alpha_\infty^+ &= \frac{1}{2} \left(\frac{b}{a} - v \right) = \frac{1}{2} \left(\frac{-1}{\frac{1}{2}} - 0 \right) = -1 \\
 \alpha_\infty^- &= \frac{1}{2} \left(-\frac{b}{a} - v \right) = \frac{1}{2} \left(-\frac{-1}{\frac{1}{2}} - 0 \right) = 1
 \end{aligned}$$

The following table summarizes the findings so far for poles and for the order of r at ∞ where r is

$$r = \frac{x^4 - 8x^3 + 24x^2 - 24x + 12}{4(x^2 - 2x)^2}$$

pole c location	pole order	$[\sqrt{r}]_c$	α_c^+	α_c^-
0	2	0	$\frac{3}{2}$	$-\frac{1}{2}$
2	2	0	$\frac{3}{2}$	$-\frac{1}{2}$

Order of r at ∞	$[\sqrt{r}]_\infty$	α_∞^+	α_∞^-
0	$\frac{1}{2}$	-1	1

Now that the all $[\sqrt{r}]_c$ and its associated α_c^\pm have been determined for all the poles in the set Γ and $[\sqrt{r}]_\infty$ and its associated α_∞^\pm have also been found, the next step is to

determine possible non negative integer d from these using

$$d = \alpha_{\infty}^{s(\infty)} - \sum_{c \in \Gamma} \alpha_c^{s(c)}$$

Where $s(c)$ is either $+$ or $-$ and $s(\infty)$ is the sign of α_{∞}^{\pm} . This is done by trial over all set of families $s = (s(c))_{c \in \Gamma \cup \infty}$ until such d is found to work in finding candidate ω . Trying $\alpha_{\infty}^+ = -1$ then

$$\begin{aligned} d &= \alpha_{\infty}^+ - (\alpha_{c_1}^- + \alpha_{c_2}^-) \\ &= -1 - (-1) \\ &= 0 \end{aligned}$$

Since d an integer and $d \geq 0$ then it can be used to find ω using

$$\omega = \sum_{c \in \Gamma} \left(s(c) [\sqrt{r}]_c + \frac{\alpha_c^{s(c)}}{x - c} \right) + s(\infty) [\sqrt{r}]_{\infty}$$

Substituting the above values in the above results in

$$\begin{aligned} \omega &= \left((-) [\sqrt{r}]_{c_1} + \frac{\alpha_{c_1}^-}{x - c_1} \right) + \left((-) [\sqrt{r}]_{c_2} + \frac{\alpha_{c_2}^-}{x - c_2} \right) + (+) [\sqrt{r}]_{\infty} \\ &= -\frac{1}{2x} - \frac{1}{2(x-2)} + \left(\frac{1}{2} \right) \\ &= -\frac{1}{2x} - \frac{1}{2(x-2)} + \frac{1}{2} \\ &= -\frac{1}{2x} - \frac{1}{2x-4} + \frac{1}{2} \end{aligned}$$

Now that ω is determined, the next step is find a corresponding minimal polynomial $p(x)$ of degree $d = 0$ to solve the ode. The polynomial $p(x)$ needs to satisfy the equation

$$p'' + 2\omega p' + (\omega' + \omega^2 - r) p = 0 \quad (1A)$$

Let

$$p(x) = 1 \quad (2A)$$

Substituting the above in eq. (1A) gives

$$(0) + 2 \left(-\frac{1}{2x} - \frac{1}{2(x-2)} + \frac{1}{2} \right) (0) + \left(\left(\frac{1}{2x^2} + \frac{1}{2(x-2)^2} \right) + \left(-\frac{1}{2x} - \frac{1}{2(x-2)} + \frac{1}{2} \right)^2 - \left(\frac{x^4 - 8x^3 + \dots}{4} \right) \right) (0) = 0$$

The equation is satisfied since both sides are zero. Therefore the first solution to the ode $z'' = rz$ is

$$\begin{aligned} z_1(x) &= pe^{\int \omega dx} \\ &= e^{\int \left(-\frac{1}{2x} - \frac{1}{2(x-2)} + \frac{1}{2}\right) dx} \\ &= \frac{e^{\frac{x}{2}}}{\sqrt{x} \sqrt{x-2}} \end{aligned}$$

The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-x^2+2}{x^2-2x} dx} \\ &= z_1 e^{\frac{x}{2} + \frac{\ln(x-2)}{2} + \frac{\ln(x)}{2}} \\ &= z_1 (\sqrt{x} \sqrt{x-2} e^{\frac{x}{2}}) \end{aligned}$$

Which simplifies to

$$y_1 = \frac{e^x \sqrt{x} \sqrt{x-2}}{\sqrt{x} (x-2)}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{x^2+2}{x^2-2x} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{x+\ln(x-2)+\ln(x)}}{(y_1)^2} dx \\ &= y_1 (-x^2 e^{-x}) \end{aligned}$$

Therefore the solution is

$$\begin{aligned} y &= c_1 y_1 + c_2 y_2 \\ &= c_1 \left(\frac{e^x \sqrt{x} \sqrt{x-2}}{\sqrt{x} (x-2)} \right) + c_2 \left(\frac{e^x \sqrt{x} \sqrt{x-2}}{\sqrt{x} (x-2)} (-x^2 e^{-x}) \right) \end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$(x^2 - 2x) y'' + (-x^2 + 2) y' + (2x - 2) y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = \frac{c_1 e^x \sqrt{x} \sqrt{x-2}}{\sqrt{x(x-2)}} - \frac{c_2 x^{\frac{5}{2}} \sqrt{x-2}}{\sqrt{x(x-2)}}$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \frac{e^x \sqrt{x} \sqrt{x-2}}{\sqrt{x(x-2)}}$$

$$y_2 = -\frac{x^{\frac{5}{2}} \sqrt{x-2}}{\sqrt{x(x-2)}}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = -\int \frac{y_2 f(x)}{aW(x)} \tag{2}$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \tag{3}$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \frac{e^x \sqrt{x} \sqrt{x-2}}{\sqrt{x(x-2)}} & -\frac{x^{\frac{5}{2}} \sqrt{x-2}}{\sqrt{x(x-2)}} \\ \frac{d}{dx} \left(\frac{e^x \sqrt{x} \sqrt{x-2}}{\sqrt{x(x-2)}} \right) & \frac{d}{dx} \left(-\frac{x^{\frac{5}{2}} \sqrt{x-2}}{\sqrt{x(x-2)}} \right) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \frac{e^x \sqrt{x} \sqrt{x-2}}{\sqrt{x(x-2)}} & -\frac{x^{\frac{5}{2}} \sqrt{x-2}}{\sqrt{x(x-2)}} \\ \frac{e^x \sqrt{x} \sqrt{x-2}}{\sqrt{x(x-2)}} - \frac{e^x \sqrt{x} \sqrt{x-2} (2x-2)}{2(x(x-2))^{\frac{3}{2}}} + \frac{e^x \sqrt{x-2}}{2\sqrt{x(x-2)}\sqrt{x}} + \frac{e^x \sqrt{x}}{2\sqrt{x(x-2)}\sqrt{x-2}} & -\frac{5x^{\frac{3}{2}} \sqrt{x-2}}{2\sqrt{x(x-2)}} - \frac{x^{\frac{5}{2}}}{2\sqrt{x-2}\sqrt{x(x-2)}} + \frac{x^{\frac{5}{2}} \sqrt{x-2} (2x-2)}{2(x(x-2))^{\frac{3}{2}}} \end{vmatrix}$$

Therefore

$$W = \left(\frac{e^x \sqrt{x} \sqrt{x-2}}{\sqrt{x(x-2)}} \right) \left(-\frac{5x^{\frac{3}{2}} \sqrt{x-2}}{2\sqrt{x(x-2)}} - \frac{x^{\frac{5}{2}}}{2\sqrt{x-2}\sqrt{x(x-2)}} + \frac{x^{\frac{5}{2}} \sqrt{x-2} (2x-2)}{2(x(x-2))^{\frac{3}{2}}} \right) - \left(-\frac{x^{\frac{5}{2}} \sqrt{x-2}}{\sqrt{x(x-2)}} \right) \left(\frac{e^x \sqrt{x} \sqrt{x-2}}{\sqrt{x(x-2)}} - \frac{e^x \sqrt{x} \sqrt{x-2} (2x-2)}{2(x(x-2))^{\frac{3}{2}}} + \frac{e^x \sqrt{x-2}}{2\sqrt{x(x-2)}\sqrt{x}} + \frac{e^x \sqrt{x}}{2\sqrt{x(x-2)}\sqrt{x-2}} \right)$$

Which simplifies to

$$W = e^x (x-2) x$$

Which simplifies to

$$W = e^x (x-2) x$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{-\frac{3x^{\frac{9}{2}}(x-2)^{\frac{5}{2}} e^x}{\sqrt{x(x-2)}}}{(x^2 - 2x) e^x (x-2) x} dx$$

Which simplifies to

$$u_1 = - \int -\frac{3x^{\frac{5}{2}} \sqrt{x-2}}{\sqrt{x(x-2)}} dx$$

Hence

$$u_1 = \frac{x^{\frac{7}{2}} \sqrt{x-2}}{\sqrt{x(x-2)}}$$

And Eq. (3) becomes

$$u_2 = \int \frac{\frac{3e^{2x} x^{\frac{5}{2}} (x-2)^{\frac{5}{2}}}{\sqrt{x(x-2)}}}{(x^2 - 2x) e^x (x-2) x} dx$$

Which simplifies to

$$u_2 = \int \frac{3e^x \sqrt{x} \sqrt{x-2}}{\sqrt{x(x-2)}} dx$$

Hence

$$u_2 = \frac{3e^x \sqrt{x} \sqrt{x-2}}{\sqrt{x(x-2)}}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = -3x^2 e^x + x^3 e^x$$

Which simplifies to

$$y_p(x) = e^x x^2 (x - 3)$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(\frac{c_1 e^x \sqrt{x} \sqrt{x-2}}{\sqrt{x(x-2)}} - \frac{c_2 x^{\frac{5}{2}} \sqrt{x-2}}{\sqrt{x(x-2)}} \right) + (e^x x^2 (x - 3)) \end{aligned}$$

Which simplifies to

$$y = \frac{\sqrt{x} \sqrt{x-2} (-c_2 x^2 + e^x c_1)}{\sqrt{x(x-2)}} + e^x x^2 (x - 3)$$

Summary

The solution(s) found are the following

$$y = \frac{\sqrt{x} \sqrt{x-2} (-c_2 x^2 + e^x c_1)}{\sqrt{x} (x-2)} + e^x x^2 (x-3) \quad (1)$$

Verification of solutions

$$y = \frac{\sqrt{x} \sqrt{x-2} (-c_2 x^2 + e^x c_1)}{\sqrt{x} (x-2)} + e^x x^2 (x-3)$$

Verified OK.

Maple trace **Kovacic algorithm successful**

```
`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
trying a double symmetry of the form [xi=0, eta=F(x)]
-> Try solving first the homogeneous part of the ODE
    checking if the LODE has constant coefficients
    checking if the LODE is of Euler type
    trying a symmetry of the form [xi=0, eta=F(x)]
    checking if the LODE is missing y
-> Trying a Liouvillian solution using Kovacics algorithm
    A Liouvillian solution exists
    Reducible group (found an exponential solution)
    Reducible group (found another exponential solution)
<- Kovacics algorithm successful
<- solving first the homogeneous part of the ODE successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 23

```
dsolve(x*(x-2)*diff(y(x),x$2)-(x^2-2)*diff(y(x),x)+2*(x-1)*y(x)=3*x^2*(x-2)^2*exp(x),y(x), s
```

$$y(x) = (x^3 - 3x^2 + c_1) e^x + c_2 x^2$$

✓ Solution by Mathematica

Time used: 0.1 (sec). Leaf size: 27

```
DSolve[x*(x-2)*y'[x]-(x^2-2)*y'[x]+2*(x-1)*y[x]==3*x^2*(x-2)^2*Exp[x],y[x],x,IncludeSingularSolutions->True]
```

$$y(x) \rightarrow c_2 x^2 + e^x (x^3 - 3x^2 + c_1)$$

12.24 problem 24

12.24.1 Solving as second order change of variable on y method 2 ode .	3200
12.24.2 Solving as second order integrable as is ode	3206
12.24.3 Solving as second order ode non constant coeff transformation on B ode	3207
12.24.4 Solving as type second_order_integrable_as_is (not using ABC version)	3212
12.24.5 Solving using Kovacic algorithm	3214
12.24.6 Solving as exact linear second order ode ode	3221

Internal problem ID [11852]

Internal file name [OUTPUT/11861_Saturday_April_13_2024_01_13_06_AM_59685877/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.4. Variation of parameters. Exercises page 162

Problem number: 24.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "exact linear second order ode", "second_order_integrable_as_is", "second_order_change_of_variable_on_y_method_2", "second_order_ode_non_constant_coeff_transformation_on_B"

Maple gives the following as the ode type

```
[[_2nd_order, _exact, _linear, _nonhomogeneous]]
```

$$(2x + 1)(x + 1)y'' + 2y'x - 2y = (2x + 1)^2$$

12.24.1 Solving as second order change of variable on y method 2 ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = 2x^2 + 3x + 1$, $B = 2x$, $C = -2$, $f(x) = 4(x + \frac{1}{2})^2$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. Solving for y_h from

$$y''(2x^2 + 3x + 1) + 2y'x - 2y = 0$$

In normal form the ode

$$y''(2x^2 + 3x + 1) + 2y'x - 2y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = \frac{2x}{2x^2 + 3x + 1}$$

$$q(x) = -\frac{2}{2x^2 + 3x + 1}$$

Applying change of variables on the dependent variable $y = v(x)x^n$ to (2) gives the following ode where the dependent variables is $v(x)$ and not y .

$$v''(x) + \left(\frac{2n}{x} + p\right)v'(x) + \left(\frac{n(n-1)}{x^2} + \frac{np}{x} + q\right)v(x) = 0 \quad (3)$$

Let the coefficient of $v(x)$ above be zero. Hence

$$\frac{n(n-1)}{x^2} + \frac{np}{x} + q = 0 \quad (4)$$

Substituting the earlier values found for $p(x)$ and $q(x)$ into (4) gives

$$\frac{n(n-1)}{x^2} + \frac{2n}{2x^2 + 3x + 1} - \frac{2}{2x^2 + 3x + 1} = 0 \quad (5)$$

Solving (5) for n gives

$$n = 1 \quad (6)$$

Substituting this value in (3) gives

$$v''(x) + \left(\frac{2}{x} + \frac{2x}{2x^2 + 3x + 1}\right)v'(x) = 0$$

$$v''(x) + \left(\frac{2}{x} + \frac{2x}{2x^2 + 3x + 1}\right)v'(x) = 0 \quad (7)$$

Using the substitution

$$u(x) = v'(x)$$

Then (7) becomes

$$u'(x) + \left(\frac{2}{x} + \frac{2x}{2x^2 + 3x + 1} \right) u(x) = 0 \quad (8)$$

The above is now solved for $u(x)$. In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= -\frac{2u(3x^2 + 3x + 1)}{x(2x^2 + 3x + 1)} \end{aligned}$$

Where $f(x) = -\frac{2(3x^2+3x+1)}{x(2x^2+3x+1)}$ and $g(u) = u$. Integrating both sides gives

$$\begin{aligned} \frac{1}{u} du &= -\frac{2(3x^2 + 3x + 1)}{x(2x^2 + 3x + 1)} dx \\ \int \frac{1}{u} du &= \int -\frac{2(3x^2 + 3x + 1)}{x(2x^2 + 3x + 1)} dx \\ \ln(u) &= -2 \ln(x+1) - 2 \ln(x) + \ln(2x+1) + c_1 \\ u &= e^{-2 \ln(x+1) - 2 \ln(x) + \ln(2x+1) + c_1} \\ &= c_1 e^{-2 \ln(x+1) - 2 \ln(x) + \ln(2x+1)} \end{aligned}$$

Which simplifies to

$$u(x) = c_1 \left(\frac{2}{(x+1)^2 x} + \frac{1}{(x+1)^2 x^2} \right)$$

Now that $u(x)$ is known, then

$$\begin{aligned} v'(x) &= u(x) \\ v(x) &= \int u(x) dx + c_2 \\ &= c_1 \left(\frac{1}{x+1} - \frac{1}{x} \right) + c_2 \end{aligned}$$

Hence

$$\begin{aligned}y &= v(x) x^n \\ &= \left(c_1 \left(\frac{1}{x+1} - \frac{1}{x} \right) + c_2 \right) x \\ &= \frac{(x^2 + x) c_2 - c_1}{x + 1}\end{aligned}$$

Now the particular solution to this ODE is found

$$y''(2x^2 + 3x + 1) + 2y'x - 2y = 4\left(x + \frac{1}{2}\right)^2$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$\begin{aligned}y_1 &= x \\ y_2 &= \frac{x}{x+1} - 1\end{aligned}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} x & \frac{x}{x+1} - 1 \\ \frac{d}{dx}(x) & \frac{d}{dx}\left(\frac{x}{x+1} - 1\right) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} x & \frac{x}{x+1} - 1 \\ 1 & \frac{1}{x+1} - \frac{x}{(x+1)^2} \end{vmatrix}$$

Therefore

$$W = (x) \left(\frac{1}{x+1} - \frac{x}{(x+1)^2} \right) - \left(\frac{x}{x+1} - 1 \right) \quad (1)$$

Which simplifies to

$$W = \frac{2x+1}{(x+1)^2}$$

Which simplifies to

$$W = \frac{2x+1}{(x+1)^2}$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{4 \left(\frac{x}{x+1} - 1 \right) \left(x + \frac{1}{2} \right)^2}{\frac{(2x^2+3x+1)(2x+1)}{(x+1)^2}} dx$$

Which simplifies to

$$u_1 = - \int (-1) dx$$

Hence

$$u_1 = x$$

And Eq. (3) becomes

$$u_2 = \int \frac{4x \left(x + \frac{1}{2} \right)^2}{\frac{(2x^2+3x+1)(2x+1)}{(x+1)^2}} dx$$

Which simplifies to

$$u_2 = \int x(x+1) dx$$

Hence

$$u_2 = \frac{1}{3}x^3 + \frac{1}{2}x^2$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = x^2 + \left(\frac{1}{3}x^3 + \frac{1}{2}x^2\right) \left(\frac{x}{x+1} - 1\right)$$

Which simplifies to

$$y_p(x) = \frac{x^2(4x+3)}{6x+6}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(\left(c_1 \left(\frac{1}{x+1} - \frac{1}{x} \right) + c_2 \right) x \right) + \left(\frac{x^2(4x+3)}{6x+6} \right) \\ &= \frac{x^2(4x+3)}{6x+6} + \left(c_1 \left(\frac{1}{x+1} - \frac{1}{x} \right) + c_2 \right) x \end{aligned}$$

Which simplifies to

$$y = \frac{4x^3 + (6c_2 + 3)x^2 + 6c_2x - 6c_1}{6x+6}$$

Summary

The solution(s) found are the following

$$y = \frac{4x^3 + (6c_2 + 3)x^2 + 6c_2x - 6c_1}{6x+6} \quad (1)$$

Verification of solutions

$$y = \frac{4x^3 + (6c_2 + 3)x^2 + 6c_2x - 6c_1}{6x+6}$$

Verified OK.

12.24.2 Solving as second order integrable as is ode

Integrating both sides of the ODE w.r.t x gives

$$\int (y''(2x^2 + 3x + 1) + 2y'x - 2y) dx = \int 4\left(x + \frac{1}{2}\right)^2 dx$$
$$(-2x - 3)y + (2x^2 + 3x + 1)y' = \frac{4\left(x + \frac{1}{2}\right)^3}{3} + c_1$$

Which is now solved for y .

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = -\frac{3 + 2x}{2x^2 + 3x + 1}$$
$$q(x) = \frac{8x^3 + 12x^2 + 6c_1 + 6x + 1}{12x^2 + 18x + 6}$$

Hence the ode is

$$y' - \frac{(3 + 2x)y}{2x^2 + 3x + 1} = \frac{8x^3 + 12x^2 + 6c_1 + 6x + 1}{12x^2 + 18x + 6}$$

The integrating factor μ is

$$\mu = e^{\int -\frac{3+2x}{2x^2+3x+1} dx}$$
$$= e^{\ln(x+1) - 2\ln(2x+1)}$$

Which simplifies to

$$\mu = \frac{x + 1}{(2x + 1)^2}$$

The ode becomes

$$\frac{d}{dx}(\mu y) = (\mu) \left(\frac{8x^3 + 12x^2 + 6c_1 + 6x + 1}{12x^2 + 18x + 6} \right)$$
$$\frac{d}{dx} \left(\frac{(x + 1)y}{(2x + 1)^2} \right) = \left(\frac{x + 1}{(2x + 1)^2} \right) \left(\frac{8x^3 + 12x^2 + 6c_1 + 6x + 1}{12x^2 + 18x + 6} \right)$$
$$d \left(\frac{(x + 1)y}{(2x + 1)^2} \right) = \left(\frac{8x^3 + 12x^2 + 6c_1 + 6x + 1}{6(2x + 1)^3} \right) dx$$

Integrating gives

$$\frac{(x+1)y}{(2x+1)^2} = \int \frac{8x^3 + 12x^2 + 6c_1 + 6x + 1}{6(2x+1)^3} dx$$
$$\frac{(x+1)y}{(2x+1)^2} = \frac{x}{6} - \frac{c_1}{4(2x+1)^2} + c_2$$

Dividing both sides by the integrating factor $\mu = \frac{x+1}{(2x+1)^2}$ results in

$$y = \frac{(2x+1)^2 \left(\frac{x}{6} - \frac{c_1}{4(2x+1)^2} \right)}{x+1} + \frac{c_2(2x+1)^2}{x+1}$$

which simplifies to

$$y = \frac{8x^3 + (48c_2 + 8)x^2 + (48c_2 + 2)x - 3c_1 + 12c_2}{12x + 12}$$

Summary

The solution(s) found are the following

$$y = \frac{8x^3 + (48c_2 + 8)x^2 + (48c_2 + 2)x - 3c_1 + 12c_2}{12x + 12} \quad (1)$$

Verification of solutions

$$y = \frac{8x^3 + (48c_2 + 8)x^2 + (48c_2 + 2)x - 3c_1 + 12c_2}{12x + 12}$$

Verified OK.

12.24.3 Solving as second order ode non constant coeff transformation on B ode

Given an ode of the form

$$Ay'' + By' + Cy = F(x)$$

This method reduces the order ode the ODE by one by applying the transformation

$$y = Bv$$

This results in

$$y' = B'v + v'B$$
$$y'' = B''v + B'v' + v''B + v'B'$$
$$= v''B + 2v' + B' + B''v$$

And now the original ode becomes

$$\begin{aligned} A(v''B + 2v'B' + B''v) + B(B'v + v'B) + CBv &= 0 \\ ABv'' + (2AB' + B^2)v' + (AB'' + BB' + CB)v &= 0 \end{aligned} \quad (1)$$

If the term $AB'' + BB' + CB$ is zero, then this method works and can be used to solve

$$ABv'' + (2AB' + B^2)v' = 0$$

By Using $u = v'$ which reduces the order of the above ode to one. The new ode is

$$ABu' + (2AB' + B^2)u = 0$$

The above ode is first order ode which is solved for u . Now a new ode $v' = u$ is solved for v as first order ode. Then the final solution is obtain from $y = Bv$.

This method works only if the term $AB'' + BB' + CB$ is zero. The given ODE shows that

$$A = 2x^2 + 3x + 1$$

$$B = 2x$$

$$C = -2$$

$$F = 4\left(x + \frac{1}{2}\right)^2$$

The above shows that for this ode

$$\begin{aligned} AB'' + BB' + CB &= (2x^2 + 3x + 1)(0) + (2x)(2) + (-2)(2x) \\ &= 0 \end{aligned}$$

Hence the ode in v given in (1) now simplifies to

$$4x^3 + 6x^2 + 2xv'' + (12x^2 + 12x + 4)v' = 0$$

Now by applying $v' = u$ the above becomes

$$(4x^3 + 6x^2 + 2x)u'(x) + 12u(x)\left(x^2 + x + \frac{1}{3}\right) = 0$$

Which is now solved for u . In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= -\frac{2u(3x^2 + 3x + 1)}{x(2x^2 + 3x + 1)} \end{aligned}$$

Where $f(x) = -\frac{2(3x^2+3x+1)}{x(2x^2+3x+1)}$ and $g(u) = u$. Integrating both sides gives

$$\begin{aligned}\frac{1}{u} du &= -\frac{2(3x^2 + 3x + 1)}{x(2x^2 + 3x + 1)} dx \\ \int \frac{1}{u} du &= \int -\frac{2(3x^2 + 3x + 1)}{x(2x^2 + 3x + 1)} dx \\ \ln(u) &= -2 \ln(x + 1) - 2 \ln(x) + \ln(2x + 1) + c_1 \\ u &= e^{-2 \ln(x+1) - 2 \ln(x) + \ln(2x+1) + c_1} \\ &= c_1 e^{-2 \ln(x+1) - 2 \ln(x) + \ln(2x+1)}\end{aligned}$$

Which simplifies to

$$u(x) = c_1 \left(\frac{2}{(x+1)^2 x} + \frac{1}{(x+1)^2 x^2} \right)$$

The ode for v now becomes

$$\begin{aligned}v' &= u \\ &= c_1 \left(\frac{2}{(x+1)^2 x} + \frac{1}{(x+1)^2 x^2} \right)\end{aligned}$$

Which is now solved for v . Integrating both sides gives

$$\begin{aligned}v(x) &= \int \frac{c_1(2x+1)}{x^2(x+1)^2} dx \\ &= c_1 \left(\frac{1}{x+1} - \frac{1}{x} \right) + c_2\end{aligned}$$

Therefore the homogeneous solution is

$$\begin{aligned}y_h(x) &= Bv \\ &= (2x) \left(c_1 \left(\frac{1}{x+1} - \frac{1}{x} \right) + c_2 \right) \\ &= \frac{2c_2x^2 + 2c_2x - 2c_1}{x+1}\end{aligned}$$

And now the particular solution $y_p(x)$ will be found. The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1y_1 + u_2y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \frac{1}{x+1}$$

$$y_2 = \frac{2x^2}{x+1} + \frac{2x}{x+1}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \frac{1}{x+1} & \frac{2x^2}{x+1} + \frac{2x}{x+1} \\ \frac{d}{dx} \left(\frac{1}{x+1} \right) & \frac{d}{dx} \left(\frac{2x^2}{x+1} + \frac{2x}{x+1} \right) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \frac{1}{x+1} & \frac{2x^2}{x+1} + \frac{2x}{x+1} \\ -\frac{1}{(x+1)^2} & -\frac{2x^2}{(x+1)^2} + \frac{4x}{x+1} + \frac{2}{x+1} - \frac{2x}{(x+1)^2} \end{vmatrix}$$

Therefore

$$W = \left(\frac{1}{x+1} \right) \left(-\frac{2x^2}{(x+1)^2} + \frac{4x}{x+1} + \frac{2}{x+1} - \frac{2x}{(x+1)^2} \right) - \left(\frac{2x^2}{x+1} + \frac{2x}{x+1} \right) \left(-\frac{1}{(x+1)^2} \right)$$

Which simplifies to

$$W = \frac{4x+2}{(x+1)^2}$$

Which simplifies to

$$W = \frac{4x + 2}{(x + 1)^2}$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{4 \left(\frac{2x^2}{x+1} + \frac{2x}{x+1} \right) \left(x + \frac{1}{2} \right)^2}{\frac{(2x^2+3x+1)(4x+2)}{(x+1)^2}} dx$$

Which simplifies to

$$u_1 = - \int x(x + 1) dx$$

Hence

$$u_1 = -\frac{1}{3}x^3 - \frac{1}{2}x^2$$

And Eq. (3) becomes

$$u_2 = \int \frac{\frac{4(x+\frac{1}{2})^2}{x+1}}{\frac{(2x^2+3x+1)(4x+2)}{(x+1)^2}} dx$$

Which simplifies to

$$u_2 = \int \frac{1}{2} dx$$

Hence

$$u_2 = \frac{x}{2}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \frac{-\frac{1}{3}x^3 - \frac{1}{2}x^2}{x + 1} + \frac{x \left(\frac{2x^2}{x+1} + \frac{2x}{x+1} \right)}{2}$$

Which simplifies to

$$y_p(x) = \frac{x^2(4x + 3)}{6x + 6}$$

Hence the complete solution is

$$\begin{aligned}y(x) &= y_h + y_p \\&= \left(\frac{2c_2x^2 + 2c_2x - 2c_1}{x + 1} \right) + \left(\frac{x^2(4x + 3)}{6x + 6} \right) \\&= \frac{4x^3 + (12c_2 + 3)x^2 + 12c_2x - 12c_1}{6x + 6}\end{aligned}$$

Summary

The solution(s) found are the following

$$y = \frac{4x^3 + (12c_2 + 3)x^2 + 12c_2x - 12c_1}{6x + 6} \quad (1)$$

Verification of solutions

$$y = \frac{4x^3 + (12c_2 + 3)x^2 + 12c_2x - 12c_1}{6x + 6}$$

Verified OK.

12.24.4 Solving as type second_order_integrable_as_is (not using ABC version)

Writing the ode as

$$y''(2x^2 + 3x + 1) + 2y'x - 2y = 4\left(x + \frac{1}{2}\right)^2$$

Integrating both sides of the ODE w.r.t x gives

$$\begin{aligned}\int (y''(2x^2 + 3x + 1) + 2y'x - 2y) dx &= \int 4\left(x + \frac{1}{2}\right)^2 dx \\(-2x - 3)y + (2x^2 + 3x + 1)y' &= \frac{4\left(x + \frac{1}{2}\right)^3}{3} + c_1\end{aligned}$$

Which is now solved for y .

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$\begin{aligned}p(x) &= -\frac{3 + 2x}{2x^2 + 3x + 1} \\q(x) &= \frac{8x^3 + 12x^2 + 6c_1 + 6x + 1}{12x^2 + 18x + 6}\end{aligned}$$

Hence the ode is

$$y' - \frac{(3 + 2x)y}{2x^2 + 3x + 1} = \frac{8x^3 + 12x^2 + 6c_1 + 6x + 1}{12x^2 + 18x + 6}$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int -\frac{3+2x}{2x^2+3x+1} dx} \\ &= e^{\ln(x+1) - 2\ln(2x+1)}\end{aligned}$$

Which simplifies to

$$\mu = \frac{x + 1}{(2x + 1)^2}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu y) &= (\mu) \left(\frac{8x^3 + 12x^2 + 6c_1 + 6x + 1}{12x^2 + 18x + 6} \right) \\ \frac{d}{dx} \left(\frac{(x + 1)y}{(2x + 1)^2} \right) &= \left(\frac{x + 1}{(2x + 1)^2} \right) \left(\frac{8x^3 + 12x^2 + 6c_1 + 6x + 1}{12x^2 + 18x + 6} \right) \\ d \left(\frac{(x + 1)y}{(2x + 1)^2} \right) &= \left(\frac{8x^3 + 12x^2 + 6c_1 + 6x + 1}{6(2x + 1)^3} \right) dx\end{aligned}$$

Integrating gives

$$\begin{aligned}\frac{(x + 1)y}{(2x + 1)^2} &= \int \frac{8x^3 + 12x^2 + 6c_1 + 6x + 1}{6(2x + 1)^3} dx \\ \frac{(x + 1)y}{(2x + 1)^2} &= \frac{x}{6} - \frac{c_1}{4(2x + 1)^2} + c_2\end{aligned}$$

Dividing both sides by the integrating factor $\mu = \frac{x+1}{(2x+1)^2}$ results in

$$y = \frac{(2x + 1)^2 \left(\frac{x}{6} - \frac{c_1}{4(2x+1)^2} \right)}{x + 1} + \frac{c_2(2x + 1)^2}{x + 1}$$

which simplifies to

$$y = \frac{8x^3 + (48c_2 + 8)x^2 + (48c_2 + 2)x - 3c_1 + 12c_2}{12x + 12}$$

Summary

The solution(s) found are the following

$$y = \frac{8x^3 + (48c_2 + 8)x^2 + (48c_2 + 2)x - 3c_1 + 12c_2}{12x + 12} \quad (1)$$

Verification of solutions

$$y = \frac{8x^3 + (48c_2 + 8)x^2 + (48c_2 + 2)x - 3c_1 + 12c_2}{12x + 12}$$

Verified OK.

12.24.5 Solving using Kovacic algorithm

Writing the ode as

$$y''(2x^2 + 3x + 1) + 2y'x - 2y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 2x^2 + 3x + 1 \\ B &= 2x \\ C &= -2 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{3}{(2x + 1)^2} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 3 \\ t &= (2x + 1)^2 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = \left(\frac{3}{(2x+1)^2} \right) z(x) \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 466: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} \mathcal{O}(\infty) &= \deg(t) - \deg(s) \\ &= 2 - 0 \\ &= 2 \end{aligned}$$

The poles of r in eq. (7) and the order of each pole are determined by solving for the roots of $t = (2x+1)^2$. There is a pole at $x = -\frac{1}{2}$ of order 2. Since there is no odd order pole larger than 2 and the order at ∞ is 2 then the necessary conditions for case one are met. Since there is a pole of order 2 then necessary conditions for case two are met. Since pole order is not larger than 2 and the order at ∞ is 2 then the necessary conditions for case three are met. Therefore

$$L = [1, 2, 4, 6, 12]$$

Attempting to find a solution using case $n = 1$.

Looking at poles of order 2. The partial fractions decomposition of r is

$$r = \frac{3}{4\left(x + \frac{1}{2}\right)^2}$$

For the pole at $x = -\frac{1}{2}$ let b be the coefficient of $\frac{1}{(x+\frac{1}{2})^2}$ in the partial fractions decomposition of r given above. Therefore $b = \frac{3}{4}$. Hence

$$\begin{aligned} [\sqrt{r}]_c &= 0 \\ \alpha_c^+ &= \frac{1}{2} + \sqrt{1 + 4b} = \frac{3}{2} \\ \alpha_c^- &= \frac{1}{2} - \sqrt{1 + 4b} = -\frac{1}{2} \end{aligned}$$

Since the order of r at ∞ is 2 then $[\sqrt{r}]_\infty = 0$. Let b be the coefficient of $\frac{1}{x^2}$ in the Laurent series expansion of r at ∞ , which can be found by dividing the leading coefficient of s by the leading coefficient of t from

$$r = \frac{s}{t} = \frac{3}{(2x + 1)^2}$$

Since the $\gcd(s, t) = 1$. This gives $b = \frac{3}{4}$. Hence

$$\begin{aligned} [\sqrt{r}]_\infty &= 0 \\ \alpha_\infty^+ &= \frac{1}{2} + \sqrt{1 + 4b} = \frac{3}{2} \\ \alpha_\infty^- &= \frac{1}{2} - \sqrt{1 + 4b} = -\frac{1}{2} \end{aligned}$$

The following table summarizes the findings so far for poles and for the order of r at ∞ where r is

$$r = \frac{3}{(2x + 1)^2}$$

pole c location	pole order	$[\sqrt{r}]_c$	α_c^+	α_c^-
$-\frac{1}{2}$	2	0	$\frac{3}{2}$	$-\frac{1}{2}$

Order of r at ∞	$[\sqrt{r}]_\infty$	α_∞^+	α_∞^-
2	0	$\frac{3}{2}$	$-\frac{1}{2}$

Now that the all $[\sqrt{r}]_c$ and its associated α_c^\pm have been determined for all the poles in the set Γ and $[\sqrt{r}]_\infty$ and its associated α_∞^\pm have also been found, the next step is to determine possible non negative integer d from these using

$$d = \alpha_\infty^{s(\infty)} - \sum_{c \in \Gamma} \alpha_c^{s(c)}$$

Where $s(c)$ is either $+$ or $-$ and $s(\infty)$ is the sign of α_∞^\pm . This is done by trial over all set of families $s = (s(c))_{c \in \Gamma \cup \infty}$ until such d is found to work in finding candidate ω . Trying $\alpha_\infty^- = -\frac{1}{2}$ then

$$\begin{aligned} d &= \alpha_\infty^- - (\alpha_{c_1}^-) \\ &= -\frac{1}{2} - \left(-\frac{1}{2}\right) \\ &= 0 \end{aligned}$$

Since d an integer and $d \geq 0$ then it can be used to find ω using

$$\omega = \sum_{c \in \Gamma} \left(s(c)[\sqrt{r}]_c + \frac{\alpha_c^{s(c)}}{x - c} \right) + s(\infty)[\sqrt{r}]_\infty$$

The above gives

$$\begin{aligned} \omega &= \left((-)[\sqrt{r}]_{c_1} + \frac{\alpha_{c_1}^-}{x - c_1} \right) + (-)[\sqrt{r}]_\infty \\ &= -\frac{1}{2(x + \frac{1}{2})} + (-)(0) \\ &= -\frac{1}{2(x + \frac{1}{2})} \\ &= -\frac{1}{2x + 1} \end{aligned}$$

Now that ω is determined, the next step is find a corresponding minimal polynomial $p(x)$ of degree $d = 0$ to solve the ode. The polynomial $p(x)$ needs to satisfy the equation

$$p'' + 2\omega p' + (\omega' + \omega^2 - r) p = 0 \quad (1A)$$

Let

$$p(x) = 1 \quad (2A)$$

Substituting the above in eq. (1A) gives

$$(0) + 2 \left(-\frac{1}{2(x + \frac{1}{2})} \right) (0) + \left(\left(\frac{1}{2(x + \frac{1}{2})} \right)^2 + \left(-\frac{1}{2(x + \frac{1}{2})} \right)^2 - \left(\frac{3}{(2x + 1)^2} \right) \right) = 0$$

$0 = 0$

The equation is satisfied since both sides are zero. Therefore the first solution to the ode $z'' = rz$ is

$$\begin{aligned} z_1(x) &= pe^{\int \omega dx} \\ &= e^{\int -\frac{1}{2(x+\frac{1}{2})} dx} \\ &= \frac{1}{\sqrt{2x+1}} \end{aligned}$$

The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{2x}{2x^2+3x+1} dx} \\ &= z_1 e^{-\ln(x+1) + \frac{\ln(2x+1)}{2}} \\ &= z_1 \left(\frac{\sqrt{2x+1}}{x+1} \right) \end{aligned}$$

Which simplifies to

$$y_1 = \frac{1}{x+1}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{2x}{2x^2+3x+1} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{-2\ln(x+1) + \ln(2x+1)}}{(y_1)^2} dx \\ &= y_1(x(x+1)) \end{aligned}$$

Therefore the solution is

$$\begin{aligned} y &= c_1 y_1 + c_2 y_2 \\ &= c_1 \left(\frac{1}{x+1} \right) + c_2 \left(\frac{1}{x+1} (x(x+1)) \right) \end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$y''(2x^2 + 3x + 1) + 2y'x - 2y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = \frac{c_1}{x+1} + c_2x$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1y_1 + u_2y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \frac{1}{x+1}$$

$$y_2 = x$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \tag{2}$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \tag{3}$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \frac{1}{x+1} & x \\ \frac{d}{dx}\left(\frac{1}{x+1}\right) & \frac{d}{dx}(x) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \frac{1}{x+1} & x \\ -\frac{1}{(x+1)^2} & 1 \end{vmatrix}$$

Therefore

$$W = \left(\frac{1}{x+1}\right)(1) - (x)\left(-\frac{1}{(x+1)^2}\right)$$

Which simplifies to

$$W = \frac{2x+1}{(x+1)^2}$$

Which simplifies to

$$W = \frac{2x+1}{(x+1)^2}$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{4x\left(x + \frac{1}{2}\right)^2}{\frac{(2x^2+3x+1)(2x+1)}{(x+1)^2}} dx$$

Which simplifies to

$$u_1 = - \int x(x+1) dx$$

Hence

$$u_1 = -\frac{1}{3}x^3 - \frac{1}{2}x^2$$

And Eq. (3) becomes

$$u_2 = \int \frac{\frac{4\left(x + \frac{1}{2}\right)^2}{x+1}}{\frac{(2x^2+3x+1)(2x+1)}{(x+1)^2}} dx$$

Which simplifies to

$$u_2 = \int 1 dx$$

Hence

$$u_2 = x$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \frac{-\frac{1}{3}x^3 - \frac{1}{2}x^2}{x+1} + x^2$$

Which simplifies to

$$y_p(x) = \frac{x^2(4x+3)}{6x+6}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(\frac{c_1}{x+1} + c_2x \right) + \left(\frac{x^2(4x+3)}{6x+6} \right) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = \frac{c_1}{x+1} + c_2x + \frac{x^2(4x+3)}{6x+6} \quad (1)$$

Verification of solutions

$$y = \frac{c_1}{x+1} + c_2x + \frac{x^2(4x+3)}{6x+6}$$

Verified OK.

12.24.6 Solving as exact linear second order ode ode

An ode of the form

$$p(x)y'' + q(x)y' + r(x)y = s(x)$$

is exact if

$$p''(x) - q'(x) + r(x) = 0 \quad (1)$$

For the given ode we have

$$p(x) = 2x^2 + 3x + 1$$

$$q(x) = 2x$$

$$r(x) = -2$$

$$s(x) = 4\left(x + \frac{1}{2}\right)^2$$

Hence

$$p''(x) = 4$$

$$q'(x) = 2$$

Therefore (1) becomes

$$4 - (2) + (-2) = 0$$

Hence the ode is exact. Since we now know the ode is exact, it can be written as

$$(p(x)y' + (q(x) - p'(x))y)' = s(x)$$

Integrating gives

$$p(x)y' + (q(x) - p'(x))y = \int s(x) dx$$

Substituting the above values for p, q, r, s gives

$$(-2x - 3)y + (2x^2 + 3x + 1)y' = \int 4\left(x + \frac{1}{2}\right)^2 dx$$

We now have a first order ode to solve which is

$$(-2x - 3)y + (2x^2 + 3x + 1)y' = \frac{4\left(x + \frac{1}{2}\right)^3}{3} + c_1$$

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = -\frac{3 + 2x}{2x^2 + 3x + 1}$$
$$q(x) = \frac{8x^3 + 12x^2 + 6c_1 + 6x + 1}{12x^2 + 18x + 6}$$

Hence the ode is

$$y' - \frac{(3 + 2x)y}{2x^2 + 3x + 1} = \frac{8x^3 + 12x^2 + 6c_1 + 6x + 1}{12x^2 + 18x + 6}$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int -\frac{3+2x}{2x^2+3x+1} dx} \\ &= e^{\ln(x+1) - 2\ln(2x+1)}\end{aligned}$$

Which simplifies to

$$\mu = \frac{x + 1}{(2x + 1)^2}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu y) &= (\mu) \left(\frac{8x^3 + 12x^2 + 6c_1 + 6x + 1}{12x^2 + 18x + 6} \right) \\ \frac{d}{dx} \left(\frac{(x + 1)y}{(2x + 1)^2} \right) &= \left(\frac{x + 1}{(2x + 1)^2} \right) \left(\frac{8x^3 + 12x^2 + 6c_1 + 6x + 1}{12x^2 + 18x + 6} \right) \\ d \left(\frac{(x + 1)y}{(2x + 1)^2} \right) &= \left(\frac{8x^3 + 12x^2 + 6c_1 + 6x + 1}{6(2x + 1)^3} \right) dx\end{aligned}$$

Integrating gives

$$\begin{aligned}\frac{(x + 1)y}{(2x + 1)^2} &= \int \frac{8x^3 + 12x^2 + 6c_1 + 6x + 1}{6(2x + 1)^3} dx \\ \frac{(x + 1)y}{(2x + 1)^2} &= \frac{x}{6} - \frac{c_1}{4(2x + 1)^2} + c_2\end{aligned}$$

Dividing both sides by the integrating factor $\mu = \frac{x+1}{(2x+1)^2}$ results in

$$y = \frac{(2x + 1)^2 \left(\frac{x}{6} - \frac{c_1}{4(2x+1)^2} \right)}{x + 1} + \frac{c_2(2x + 1)^2}{x + 1}$$

which simplifies to

$$y = \frac{8x^3 + (48c_2 + 8)x^2 + (48c_2 + 2)x - 3c_1 + 12c_2}{12x + 12}$$

Summary

The solution(s) found are the following

$$y = \frac{8x^3 + (48c_2 + 8)x^2 + (48c_2 + 2)x - 3c_1 + 12c_2}{12x + 12} \quad (1)$$

Verification of solutions

$$y = \frac{8x^3 + (48c_2 + 8)x^2 + (48c_2 + 2)x - 3c_1 + 12c_2}{12x + 12}$$

Verified OK.

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
<- high order exact linear fully integrable successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 43

```
dsolve((2*x+1)*(x+1)*diff(y(x),x$2)+2*x*diff(y(x),x)-2*y(x)=(2*x+1)^2,y(x), singsol=all)
```

$$y(x) = \frac{4x^3 + (6c_1 + 24c_2 + 4)x^2 + (6c_1 + 24c_2 + 1)x + 6c_2}{6x + 6}$$

✓ Solution by Mathematica

Time used: 1.049 (sec). Leaf size: 72

```
DSolve[(2*x+1)*(x+1)*y'[x]+2*x*y'[x]-2*y[x]==(2*x+1)^2,y[x],x,IncludeSingularSolutions -> T
```

$$y(x) \rightarrow \frac{\sqrt{-2x-1}(4x+3)x^2 - 6c_2(x+1)\sqrt{2x+1}x + 6c_1\sqrt{2x+1}}{6\sqrt{-2x-1}(x+1)}$$

12.25 problem 25

12.25.1 Solving as second order change of variable on y method 1 ode . 3225

Internal problem ID [11853]

Internal file name [OUTPUT/11862_Saturday_April_13_2024_01_13_09_AM_37230/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.4. Variation of parameters. Exercises page 162

Problem number: 25.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "second_order_change_of_variable_on_y_method_1"

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$\sin(x)^2 y'' - 2 \sin(x) \cos(x) y' + (\cos(x)^2 + 1) y = \sin(x)^3$$

12.25.1 Solving as second order change of variable on y method 1 ode

This is second order non-homogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$\sin(x)^2 y'' - y' \sin(2x) + (\cos(x)^2 + 1) y = 0$$

In normal form the given ode is written as

$$y'' + p(x) y' + q(x) y = 0 \tag{2}$$

Where

$$p(x) = -\frac{\sin(2x)}{\sin(x)^2}$$

$$q(x) = \frac{\cos(x)^2 + 1}{\sin(x)^2}$$

Calculating the Liouville ode invariant Q given by

$$\begin{aligned} Q &= q - \frac{p'}{2} - \frac{p^2}{4} \\ &= \frac{\cos(x)^2 + 1}{\sin(x)^2} - \frac{\left(-\frac{\sin(2x)}{\sin(x)^2}\right)'}{2} - \frac{\left(-\frac{\sin(2x)}{\sin(x)^2}\right)^2}{4} \\ &= \frac{\cos(x)^2 + 1}{\sin(x)^2} - \frac{\left(\frac{2\sin(2x)\cos(x)}{\sin(x)^3} - \frac{2\cos(2x)}{\sin(x)^2}\right)}{2} - \frac{\left(\frac{\sin(2x)^2}{\sin(x)^4}\right)}{4} \\ &= \frac{\cos(x)^2 + 1}{\sin(x)^2} - \left(\frac{\sin(2x)\cos(x)}{\sin(x)^3} - \frac{\cos(2x)}{\sin(x)^2}\right) - \frac{\sin(2x)^2}{4\sin(x)^4} \\ &= 0 \end{aligned}$$

Since the Liouville ode invariant does not depend on the independent variable x then the transformation

$$y = v(x)z(x) \tag{3}$$

is used to change the original ode to a constant coefficients ode in v . In (3) the term $z(x)$ is given by

$$\begin{aligned} z(x) &= e^{-\left(\int \frac{p(x)}{2} dx\right)} \\ &= e^{-\int \frac{-\frac{\sin(2x)}{\sin(x)^2}}{2}} \\ &= \sin(x) \end{aligned} \tag{5}$$

Hence (3) becomes

$$y = v(x)\sin(x) \tag{4}$$

Applying this change of variable to the original ode results in

$$v''(x) = 1$$

Which is now solved for $v(x)$ The ODE can be written as

$$v''(x) = 1$$

Integrating once gives

$$v'(x) = x + c_1$$

Integrating again gives

$$v(x) = \frac{x^2}{2} + c_1x + c_2$$

Now that $v(x)$ is known, then

$$\begin{aligned} y &= v(x) z(x) \\ &= \left(\frac{1}{2}x^2 + c_1x + c_2 \right) (z(x)) \end{aligned} \quad (7)$$

But from (5)

$$z(x) = \sin(x)$$

Hence (7) becomes

$$y = \left(\frac{1}{2}x^2 + c_1x + c_2 \right) \sin(x)$$

Therefore the homogeneous solution y_h is

$$y_h = \left(\frac{1}{2}x^2 + c_1x + c_2 \right) \sin(x)$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1y_1 + u_2y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \sin(x)$$

$$y_2 = x \sin(x)$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \sin(x) & x \sin(x) \\ \frac{d}{dx}(\sin(x)) & \frac{d}{dx}(x \sin(x)) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \sin(x) & x \sin(x) \\ \cos(x) & \sin(x) + \cos(x)x \end{vmatrix}$$

Therefore

$$W = (\sin(x))(\sin(x) + \cos(x)x) - (x \sin(x))(\cos(x))$$

Which simplifies to

$$W = \sin(x)^2$$

Which simplifies to

$$W = \sin(x)^2$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{x \sin(x)^4}{\sin(x)^4} dx$$

Which simplifies to

$$u_1 = - \int x dx$$

Hence

$$u_1 = -\frac{x^2}{2}$$

And Eq. (3) becomes

$$u_2 = \int \frac{\sin(x)^4}{\sin(x)^4} dx$$

Which simplifies to

$$u_2 = \int 1 dx$$

Hence

$$u_2 = x$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \frac{\sin(x) x^2}{2}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(\left(\frac{1}{2}x^2 + c_1x + c_2 \right) \sin(x) \right) + \left(\frac{\sin(x) x^2}{2} \right) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = \left(\frac{1}{2}x^2 + c_1x + c_2 \right) \sin(x) + \frac{\sin(x) x^2}{2} \quad (1)$$

Verification of solutions

$$y = \left(\frac{1}{2}x^2 + c_1x + c_2 \right) \sin(x) + \frac{\sin(x) x^2}{2}$$

Verified OK.

Maple trace Kovacic algorithm successful

```
`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
trying a double symmetry of the form [xi=0, eta=F(x)]
trying symmetries linear in x and y(x)
-> Try solving first the homogeneous part of the ODE
    trying a symmetry of the form [xi=0, eta=F(x)]
    checking if the LODE is missing y
    -> Trying a Liouvillian solution using Kovacics algorithm
        A Liouvillian solution exists
        Reducible group (found an exponential solution)
    <- Kovacics algorithm successful
<- solving first the homogeneous part of the ODE successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 17

```
dsolve(sin(x)^2*diff(y(x),x$2)-2*sin(x)*cos(x)*diff(y(x),x)+(cos(x)^2+1)*y(x)=sin(x)^3,y(x),
```

$$y(x) = \sin(x) \left(c_2 + c_1 x + \frac{1}{2} x^2 \right)$$

✓ Solution by Mathematica

Time used: 0.092 (sec). Leaf size: 24

```
DSolve[Sin[x]^2*y''[x]-2*Sin[x]*Cos[x]*y'[x]+(Cos[x]^2+1)*y[x]==Sin[x]^3,y[x],x,IncludeSingu
```

$$y(x) \rightarrow \frac{1}{2}(x^2 + 2c_2 x + 2c_1) \sin(x)$$

12.26 problem 26

12.26.1 Maple step by step solution 3233

Internal problem ID [11854]

Internal file name [OUTPUT/11863_Saturday_April_13_2024_01_13_10_AM_74535894/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.4. Variation of parameters. Exercises page 162

Problem number: 26.

ODE order: 3.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_linear_constant_coefficients_ODE**"

Maple gives the following as the ode type

```
[[_3rd_order , _linear , _nonhomogeneous]]
```

$$y''' - 3y'' - y' + 3y = x^2 e^x$$

This is higher order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE And y_p is a particular solution to the nonhomogeneous ODE. y_h is the solution to

$$y''' - 3y'' - y' + 3y = 0$$

The characteristic equation is

$$\lambda^3 - 3\lambda^2 - \lambda + 3 = 0$$

The roots of the above equation are

$$\lambda_1 = 1$$

$$\lambda_2 = 3$$

$$\lambda_3 = -1$$

Therefore the homogeneous solution is

$$y_h(x) = c_1 e^{-x} + c_2 e^x + c_3 e^{3x}$$

The fundamental set of solutions for the homogeneous solution are the following

$$y_1 = e^{-x}$$

$$y_2 = e^x$$

$$y_3 = e^{3x}$$

Now the particular solution to the given ODE is found

$$y''' - 3y'' - y' + 3y = x^2 e^x$$

The particular solution is found using the method of undetermined coefficients. Looking at the RHS of the ode, which is

$$x^2 e^x$$

Shows that the corresponding undetermined set of the basis functions (UC_set) for the trial solution is

$$[\{x e^x, x^2 e^x, e^x\}]$$

While the set of the basis functions for the homogeneous solution found earlier is

$$\{e^x, e^{-x}, e^{3x}\}$$

Since e^x is duplicated in the UC_set, then this basis is multiplied by extra x . The UC_set becomes

$$[\{x e^x, x^2 e^x, x^3 e^x\}]$$

Since there was duplication between the basis functions in the UC_set and the basis functions of the homogeneous solution, the trial solution is a linear combination of all the basis function in the above updated UC_set.

$$y_p = A_1 x e^x + A_2 x^2 e^x + A_3 x^3 e^x$$

The unknowns $\{A_1, A_2, A_3\}$ are found by substituting the above trial solution y_p into the ODE and comparing coefficients. Substituting the trial solution into the ODE and simplifying gives

$$-8A_2 x e^x - 12A_3 x^2 e^x - 4A_1 e^x + 6A_3 e^x = x^2 e^x$$

Solving for the unknowns by comparing coefficients results in

$$\left[A_1 = -\frac{1}{8}, A_2 = 0, A_3 = -\frac{1}{12} \right]$$

Substituting the above back in the above trial solution y_p , gives the particular solution

$$y_p = -\frac{x e^x}{8} - \frac{x^3 e^x}{12}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 e^{-x} + c_2 e^x + c_3 e^{3x}) + \left(-\frac{x e^x}{8} - \frac{x^3 e^x}{12} \right) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 e^{-x} + c_2 e^x + c_3 e^{3x} - \frac{x e^x}{8} - \frac{x^3 e^x}{12} \quad (1)$$

Verification of solutions

$$y = c_1 e^{-x} + c_2 e^x + c_3 e^{3x} - \frac{x e^x}{8} - \frac{x^3 e^x}{12}$$

Verified OK.

12.26.1 Maple step by step solution

Let's solve

$$y''' - 3y'' - y' + 3y = x^2 e^x$$

- Highest derivative means the order of the ODE is 3

$$y'''$$

- Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(x)$

$$y_1(x) = y$$

- Define new variable $y_2(x)$

$$y_2(x) = y'$$

- Define new variable $y_3(x)$

$$y_3(x) = y''$$

- Isolate for $y_3'(x)$ using original ODE

$$y_3'(x) = x^2 e^x + 3y_3(x) + y_2(x) - 3y_1(x)$$

Convert linear ODE into a system of first order ODEs

$$[y_2(x) = y_1'(x), y_3(x) = y_2'(x), y_3'(x) = x^2 e^x + 3y_3(x) + y_2(x) - 3y_1(x)]$$

- Define vector

$$\vec{y}(x) = \begin{bmatrix} y_1(x) \\ y_2(x) \\ y_3(x) \end{bmatrix}$$

- System to solve

$$\vec{y}'(x) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -3 & 1 & 3 \end{bmatrix} \cdot \vec{y}(x) + \begin{bmatrix} 0 \\ 0 \\ x^2 e^x \end{bmatrix}$$

- Define the forcing function

$$\vec{f}(x) = \begin{bmatrix} 0 \\ 0 \\ x^2 e^x \end{bmatrix}$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -3 & 1 & 3 \end{bmatrix}$$

- Rewrite the system as

$$\vec{y}'(x) = A \cdot \vec{y}(x) + \vec{f}$$

- To solve the system, find the eigenvalues and eigenvectors of A
- Eigenpairs of A

$$\left[\left[-1, \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \right], \left[1, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right], \left[3, \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[-1, \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_1 = e^{-x} \cdot \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[1, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_2 = e^x \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[3, \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_3 = e^{3x} \cdot \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix}$$

- General solution of the system of ODEs can be written in terms of the particular solution $\vec{y}_p(x)$

$$\vec{y}(x) = c_1 \vec{y}_1 + c_2 \vec{y}_2 + c_3 \vec{y}_3 + \vec{y}_p(x)$$

□ Fundamental matrix

- Let $\phi(x)$ be the matrix whose columns are the independent solutions of the homogeneous system

$$\phi(x) = \begin{bmatrix} e^{-x} & e^x & \frac{e^{3x}}{9} \\ -e^{-x} & e^x & \frac{e^{3x}}{3} \\ e^{-x} & e^x & e^{3x} \end{bmatrix}$$

- The fundamental matrix, $\Phi(x)$ is a normalized version of $\phi(x)$ satisfying $\Phi(0) = I$ where I is the identity matrix

$$\Phi(x) = \phi(x) \cdot \frac{1}{\phi(0)}$$

- Substitute the value of $\phi(x)$ and $\phi(0)$

$$\Phi(x) = \begin{bmatrix} e^{-x} & e^x & \frac{e^{3x}}{9} \\ -e^{-x} & e^x & \frac{e^{3x}}{3} \\ e^{-x} & e^x & e^{3x} \end{bmatrix} \cdot \frac{1}{\begin{bmatrix} 1 & 1 & \frac{1}{9} \\ -1 & 1 & \frac{1}{3} \\ 1 & 1 & 1 \end{bmatrix}}$$

- Evaluate and simplify to get the fundamental matrix

$$\Phi(x) = \begin{bmatrix} \frac{3e^{-x}}{8} + \frac{3e^x}{4} - \frac{e^{3x}}{8} & -\frac{e^{-x}}{2} + \frac{e^x}{2} & \frac{e^{-x}}{8} - \frac{e^x}{4} + \frac{e^{3x}}{8} \\ -\frac{3e^{-x}}{8} + \frac{3e^x}{4} - \frac{3e^{3x}}{8} & \frac{e^{-x}}{2} + \frac{e^x}{2} & -\frac{e^{-x}}{8} - \frac{e^x}{4} + \frac{3e^{3x}}{8} \\ \frac{3e^{-x}}{8} + \frac{3e^x}{4} - \frac{9e^{3x}}{8} & -\frac{e^{-x}}{2} + \frac{e^x}{2} & \frac{e^{-x}}{8} - \frac{e^x}{4} + \frac{9e^{3x}}{8} \end{bmatrix}$$

□ Find a particular solution of the system of ODEs using variation of parameters

- Let the particular solution be the fundamental matrix multiplied by $\vec{v}(x)$ and solve for $\vec{v}(x)$

$$\vec{y}_p(x) = \Phi(x) \cdot \vec{v}(x)$$

- Take the derivative of the particular solution

$$\vec{y}'_p(x) = \Phi'(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x)$$

- Substitute particular solution and its derivative into the system of ODEs

$$\Phi'(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x) = A \cdot \Phi(x) \cdot \vec{v}(x) + \vec{f}(x)$$

- The fundamental matrix has columns that are solutions to the homogeneous system so its derivative is $A \cdot \Phi(x)$

$$A \cdot \Phi(x) \cdot \vec{v}(x) + \Phi(x) \cdot \vec{v}'(x) = A \cdot \Phi(x) \cdot \vec{v}(x) + \vec{f}(x)$$

- Cancel like terms

$$\Phi(x) \cdot \vec{v}'(x) = \vec{f}(x)$$

- Multiply by the inverse of the fundamental matrix

$$\vec{v}'(x) = \frac{1}{\Phi(x)} \cdot \vec{f}(x)$$

- Integrate to solve for $\vec{v}(x)$

$$\vec{v}(x) = \int_0^x \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds$$

- Plug $\vec{v}(x)$ into the equation for the particular solution

$$\vec{y}_p(x) = \Phi(x) \cdot \left(\int_0^x \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds \right)$$

- Plug in the fundamental matrix and the forcing function and compute

$$\vec{y}_p(x) = \begin{bmatrix} -\frac{e^{-x}}{32} + \frac{e^{3x}}{32} + \frac{(-2x^3-3x)e^x}{24} \\ \frac{e^{-x}}{32} + \frac{3e^{3x}}{32} + \frac{(-2x^3-6x^2-3x-3)e^x}{24} \\ -\frac{e^{-x}}{32} + \frac{9e^{3x}}{32} + \frac{(-2x^3-12x^2-15x-6)e^x}{24} \end{bmatrix}$$

- Plug particular solution back into general solution

$$\vec{y}(x) = c_1 \vec{y}_1 + c_2 \vec{y}_2 + c_3 \vec{y}_3 + \begin{bmatrix} -\frac{e^{-x}}{32} + \frac{e^{3x}}{32} + \frac{(-2x^3-3x)e^x}{24} \\ \frac{e^{-x}}{32} + \frac{3e^{3x}}{32} + \frac{(-2x^3-6x^2-3x-3)e^x}{24} \\ -\frac{e^{-x}}{32} + \frac{9e^{3x}}{32} + \frac{(-2x^3-12x^2-15x-6)e^x}{24} \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y = \frac{(-1+32c_1)e^{-x}}{32} + \frac{(32c_3+9)e^{3x}}{288} - \frac{e^x(x^3+\frac{3}{2}x-12c_2)}{12}$$

Maple trace

```
`Methods for third order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
trying differential order: 3; linear nonhomogeneous with symmetry [0,1]  
trying high order linear exact nonhomogeneous  
trying differential order: 3; missing the dependent variable  
checking if the LODE has constant coefficients  
<- constant coefficients successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 31

```
dsolve(diff(y(x),x$3)-3*diff(y(x),x$2)-diff(y(x),x)+3*y(x)=x^2*exp(x),y(x), singsol=all)
```

$$y(x) = c_2 e^{-x} + c_3 e^{3x} - \frac{(x^3 + \frac{3}{2}x - 12c_1) e^x}{12}$$

✓ Solution by Mathematica

Time used: 0.038 (sec). Leaf size: 41

```
DSolve[y'''[x]-3*y''[x]-y'[x]+3*y[x]==x^2*Exp[x],y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow e^x \left(-\frac{x^3}{12} - \frac{x}{8} + c_2 \right) + c_1 e^{-x} + c_3 e^{3x}$$

13 Chapter 4, Section 4.5. The Cauchy-Euler Equation. Exercises page 169

13.1 problem 1	3240
13.2 problem 2	3259
13.3 problem 3	3275
13.4 problem 4	3292
13.5 problem 5	3308
13.6 problem 6	3325
13.7 problem 7	3342
13.8 problem 8	3359
13.9 problem 9	3376
13.10 problem 10	3392
13.11 problem 11	3409
13.12 problem 12	3416
13.13 problem 13	3423
13.14 problem 14	3430
13.15 problem 15	3460
13.16 problem 16	3487
13.17 problem 17	3524
13.18 problem 18	3554
13.19 problem 19	3582
13.20 problem 20	3589
13.21 problem 21	3609
13.22 problem 22	3635
13.23 problem 23	3665
13.24 problem 24	3690
13.25 problem 25	3731
13.26 problem 26	3759
13.27 problem 27	3793
13.28 problem 28	3809
13.29 problem 29	3823

13.1 problem 1

13.1.1 Solving as second order euler ode	3241
13.1.2 Solving as second order change of variable on x method 2 ode .	3242
13.1.3 Solving as second order change of variable on x method 1 ode .	3244
13.1.4 Solving as second order change of variable on y method 2 ode .	3246
13.1.5 Solving as second order ode non constant coeff transformation on B ode	3248
13.1.6 Solving using Kovacic algorithm	3251
13.1.7 Maple step by step solution	3256

Internal problem ID [11855]

Internal file name [OUTPUT/11864_Saturday_April_13_2024_01_13_10_AM_73858456/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.5. The Cauchy-Euler Equation. Exercises page 169

Problem number: 1.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_euler_ode", "second_order_change_of_variable_on_x_method_1", "second_order_change_of_variable_on_x_method_2", "second_order_change_of_variable_on_y_method_2", "second_order_ode_non_constant_coeff_transformation_on_B"

Maple gives the following as the ode type

```
[[_Emden, _Fowler]]
```

$$x^2y'' - 3y'x + 3y = 0$$

13.1.1 Solving as second order euler ode ode

This is Euler second order ODE. Let the solution be $y = x^r$, then $y' = rx^{r-1}$ and $y'' = r(r-1)x^{r-2}$. Substituting these back into the given ODE gives

$$x^2(r(r-1))x^{r-2} - 3rxr^{r-1} + 3x^r = 0$$

Simplifying gives

$$r(r-1)x^r - 3rx^r + 3x^r = 0$$

Since $x^r \neq 0$ then dividing throughout by x^r gives

$$r(r-1) - 3r + 3 = 0$$

Or

$$r^2 - 4r + 3 = 0 \tag{1}$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = 1$$

$$r_2 = 3$$

Since the roots are real and distinct, then the general solution is

$$y = c_1y_1 + c_2y_2$$

Where $y_1 = x^{r_1}$ and $y_2 = x^{r_2}$. Hence

$$y = c_2x^3 + c_1x$$

Summary

The solution(s) found are the following

$$y = c_2x^3 + c_1x \tag{1}$$

Verification of solutions

$$y = c_2x^3 + c_1x$$

Verified OK.

13.1.2 Solving as second order change of variable on x method 2 ode

In normal form the ode

$$x^2 y'' - 3y'x + 3y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = -\frac{3}{x}$$
$$q(x) = \frac{3}{x^2}$$

Applying change of variables $\tau = g(x)$ to (2) gives

$$\frac{d^2}{d\tau^2}y(\tau) + p_1\left(\frac{d}{d\tau}y(\tau)\right) + q_1y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $p_1 = 0$. Eq (4) simplifies to

$$\tau''(x) + p(x)\tau'(x) = 0$$

This ode is solved resulting in

$$\begin{aligned} \tau &= \int e^{-(\int p(x)dx)} dx \\ &= \int e^{-(\int -\frac{3}{x}dx)} dx \\ &= \int e^{3\ln(x)} dx \\ &= \int x^3 dx \\ &= \frac{x^4}{4} \end{aligned} \quad (6)$$

Using (6) to evaluate q_1 from (5) gives

$$\begin{aligned} q_1(\tau) &= \frac{q(x)}{\tau'(x)^2} \\ &= \frac{\frac{3}{x^2}}{x^6} \\ &= \frac{3}{x^8} \end{aligned} \tag{7}$$

Substituting the above in (3) and noting that now $p_1 = 0$ results in

$$\begin{aligned} \frac{d^2}{d\tau^2}y(\tau) + q_1y(\tau) &= 0 \\ \frac{d^2}{d\tau^2}y(\tau) + \frac{3y(\tau)}{x^8} &= 0 \end{aligned}$$

But in terms of τ

$$\frac{3}{x^8} = \frac{3}{16\tau^2}$$

Hence the above ode becomes

$$\frac{d^2}{d\tau^2}y(\tau) + \frac{3y(\tau)}{16\tau^2} = 0$$

The above ode is now solved for $y(\tau)$. The ode can be written as

$$16 \left(\frac{d^2}{d\tau^2}y(\tau) \right) \tau^2 + 3y(\tau) = 0$$

Which shows it is a Euler ODE. This is Euler second order ODE. Let the solution be $y(\tau) = \tau^r$, then $y' = r\tau^{r-1}$ and $y'' = r(r-1)\tau^{r-2}$. Substituting these back into the given ODE gives

$$16\tau^2(r(r-1))\tau^{r-2} + 0r\tau^{r-1} + 3\tau^r = 0$$

Simplifying gives

$$16r(r-1)\tau^r + 0\tau^r + 3\tau^r = 0$$

Since $\tau^r \neq 0$ then dividing throughout by τ^r gives

$$16r(r-1) + 0 + 3 = 0$$

Or

$$16r^2 - 16r + 3 = 0 \tag{1}$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = \frac{1}{4}$$

$$r_2 = \frac{3}{4}$$

Since the roots are real and distinct, then the general solution is

$$y(\tau) = c_1 y_1 + c_2 y_2$$

Where $y_1 = \tau^{r_1}$ and $y_2 = \tau^{r_2}$. Hence

$$y(\tau) = c_1 \tau^{\frac{1}{4}} + c_2 \tau^{\frac{3}{4}}$$

The above solution is now transformed back to y using (6) which results in

$$y = \frac{\sqrt{2} (x^4)^{\frac{1}{4}} (c_2 \sqrt{x^4} + 2c_1)}{4}$$

Summary

The solution(s) found are the following

$$y = \frac{\sqrt{2} (x^4)^{\frac{1}{4}} (c_2 \sqrt{x^4} + 2c_1)}{4} \quad (1)$$

Verification of solutions

$$y = \frac{\sqrt{2} (x^4)^{\frac{1}{4}} (c_2 \sqrt{x^4} + 2c_1)}{4}$$

Verified OK.

13.1.3 Solving as second order change of variable on x method 1 ode

In normal form the ode

$$x^2 y'' - 3y'x + 3y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = -\frac{3}{x}$$

$$q(x) = \frac{3}{x^2}$$

Applying change of variables $\tau = g(x)$ to (2) results

$$\frac{d^2}{d\tau^2}y(\tau) + p_1\left(\frac{d}{d\tau}y(\tau)\right) + q_1y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $q_1 = c^2$ where c is some constant. Therefore from (5)

$$\begin{aligned} \tau' &= \frac{1}{c}\sqrt{q} \\ &= \frac{\sqrt{3}\sqrt{\frac{1}{x^2}}}{c} \\ \tau'' &= -\frac{\sqrt{3}}{c\sqrt{\frac{1}{x^2}}x^3} \end{aligned} \quad (6)$$

Substituting the above into (4) results in

$$\begin{aligned} p_1(\tau) &= \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \\ &= \frac{-\frac{\sqrt{3}}{c\sqrt{\frac{1}{x^2}}x^3} - \frac{3}{x}\frac{\sqrt{3}\sqrt{\frac{1}{x^2}}}{c}}{\left(\frac{\sqrt{3}\sqrt{\frac{1}{x^2}}}{c}\right)^2} \\ &= -\frac{4c\sqrt{3}}{3} \end{aligned}$$

Therefore ode (3) now becomes

$$\begin{aligned} y(\tau)'' + p_1y(\tau)' + q_1y(\tau) &= 0 \\ \frac{d^2}{d\tau^2}y(\tau) - \frac{4c\sqrt{3}}{3}\left(\frac{d}{d\tau}y(\tau)\right) + c^2y(\tau) &= 0 \end{aligned} \quad (7)$$

The above ode is now solved for $y(\tau)$. Since the ode is now constant coefficients, it can be easily solved to give

$$y(\tau) = e^{\frac{2\sqrt{3}c\tau}{3}} \left(c_1 \cosh\left(\frac{\sqrt{3}c\tau}{3}\right) + ic_2 \sinh\left(\frac{\sqrt{3}c\tau}{3}\right) \right)$$

Now from (6)

$$\begin{aligned}\tau &= \int \frac{1}{c} \sqrt{q} dx \\ &= \frac{\int \sqrt{3} \sqrt{\frac{1}{x^2}} dx}{c} \\ &= \frac{\sqrt{3} \sqrt{\frac{1}{x^2}} x \ln(x)}{c}\end{aligned}$$

Substituting the above into the solution obtained gives

$$y = \frac{x((ic_2 + c_1)x^2 - ic_2 + c_1)}{2}$$

Summary

The solution(s) found are the following

$$y = \frac{x((ic_2 + c_1)x^2 - ic_2 + c_1)}{2} \quad (1)$$

Verification of solutions

$$y = \frac{x((ic_2 + c_1)x^2 - ic_2 + c_1)}{2}$$

Verified OK.

13.1.4 Solving as second order change of variable on y method 2 ode

In normal form the ode

$$x^2 y'' - 3y'x + 3y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$\begin{aligned}p(x) &= -\frac{3}{x} \\ q(x) &= \frac{3}{x^2}\end{aligned}$$

Applying change of variables on the dependent variable $y = v(x)x^n$ to (2) gives the following ode where the dependent variables is $v(x)$ and not y .

$$v''(x) + \left(\frac{2n}{x} + p\right)v'(x) + \left(\frac{n(n-1)}{x^2} + \frac{np}{x} + q\right)v(x) = 0 \quad (3)$$

Let the coefficient of $v(x)$ above be zero. Hence

$$\frac{n(n-1)}{x^2} + \frac{np}{x} + q = 0 \quad (4)$$

Substituting the earlier values found for $p(x)$ and $q(x)$ into (4) gives

$$\frac{n(n-1)}{x^2} - \frac{3n}{x^2} + \frac{3}{x^2} = 0 \quad (5)$$

Solving (5) for n gives

$$n = 3 \quad (6)$$

Substituting this value in (3) gives

$$\begin{aligned} v''(x) + \frac{3v'(x)}{x} &= 0 \\ v''(x) + \frac{3v'(x)}{x} &= 0 \end{aligned} \quad (7)$$

Using the substitution

$$u(x) = v'(x)$$

Then (7) becomes

$$u'(x) + \frac{3u(x)}{x} = 0 \quad (8)$$

The above is now solved for $u(x)$. In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= -\frac{3u}{x} \end{aligned}$$

Where $f(x) = -\frac{3}{x}$ and $g(u) = u$. Integrating both sides gives

$$\begin{aligned} \frac{1}{u} du &= -\frac{3}{x} dx \\ \int \frac{1}{u} du &= \int -\frac{3}{x} dx \\ \ln(u) &= -3 \ln(x) + c_1 \\ u &= e^{-3 \ln(x) + c_1} \\ &= \frac{c_1}{x^3} \end{aligned}$$

Now that $u(x)$ is known, then

$$\begin{aligned}v'(x) &= u(x) \\v(x) &= \int u(x) dx + c_2 \\&= -\frac{c_1}{2x^2} + c_2\end{aligned}$$

Hence

$$\begin{aligned}y &= v(x) x^n \\&= \left(-\frac{c_1}{2x^2} + c_2\right) x^3 \\&= c_2 x^3 - \frac{1}{2} c_1 x\end{aligned}$$

Summary

The solution(s) found are the following

$$y = \left(-\frac{c_1}{2x^2} + c_2\right) x^3 \quad (1)$$

Verification of solutions

$$y = \left(-\frac{c_1}{2x^2} + c_2\right) x^3$$

Verified OK.

13.1.5 Solving as second order ode non constant coeff transformation on B ode

Given an ode of the form

$$Ay'' + By' + Cy = F(x)$$

This method reduces the order ode the ODE by one by applying the transformation

$$y = Bv$$

This results in

$$\begin{aligned}y' &= B'v + v'B \\y'' &= B''v + B'v' + v''B + v'B' \\&= v''B + 2v' + B' + B''v\end{aligned}$$

And now the original ode becomes

$$\begin{aligned} A(v''B + 2v'B' + B''v) + B(B'v + v'B) + CBv &= 0 \\ ABv'' + (2AB' + B^2)v' + (AB'' + BB' + CB)v &= 0 \end{aligned} \quad (1)$$

If the term $AB'' + BB' + CB$ is zero, then this method works and can be used to solve

$$ABv'' + (2AB' + B^2)v' = 0$$

By Using $u = v'$ which reduces the order of the above ode to one. The new ode is

$$ABu' + (2AB' + B^2)u = 0$$

The above ode is first order ode which is solved for u . Now a new ode $v' = u$ is solved for v as first order ode. Then the final solution is obtain from $y = Bv$.

This method works only if the term $AB'' + BB' + CB$ is zero. The given ODE shows that

$$\begin{aligned} A &= x^2 \\ B &= -3x \\ C &= 3 \\ F &= 0 \end{aligned}$$

The above shows that for this ode

$$\begin{aligned} AB'' + BB' + CB &= (x^2)(0) + (-3x)(-3) + (3)(-3x) \\ &= 0 \end{aligned}$$

Hence the ode in v given in (1) now simplifies to

$$-3x^3v'' + (3x^2)v' = 0$$

Now by applying $v' = u$ the above becomes

$$-3x^2(u'(x)x - u(x)) = 0$$

Which is now solved for u . In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= \frac{u}{x} \end{aligned}$$

Where $f(x) = \frac{1}{x}$ and $g(u) = u$. Integrating both sides gives

$$\begin{aligned}\frac{1}{u} du &= \frac{1}{x} dx \\ \int \frac{1}{u} du &= \int \frac{1}{x} dx \\ \ln(u) &= \ln(x) + c_1 \\ u &= e^{\ln(x)+c_1} \\ &= c_1 x\end{aligned}$$

The ode for v now becomes

$$\begin{aligned}v' &= u \\ &= c_1 x\end{aligned}$$

Which is now solved for v . Integrating both sides gives

$$\begin{aligned}v(x) &= \int c_1 x \, dx \\ &= \frac{c_1 x^2}{2} + c_2\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y(x) &= Bv \\ &= (-3x) \left(\frac{c_1 x^2}{2} + c_2 \right) \\ &= -\frac{3x(c_1 x^2 + 2c_2)}{2}\end{aligned}$$

Summary

The solution(s) found are the following

$$y = -\frac{3x(c_1 x^2 + 2c_2)}{2} \tag{1}$$

Verification of solutions

$$y = -\frac{3x(c_1 x^2 + 2c_2)}{2}$$

Verified OK.

13.1.6 Solving using Kovacic algorithm

Writing the ode as

$$x^2y'' - 3y'x + 3y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= x^2 \\ B &= -3x \\ C &= 3 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{3}{4x^2} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 3 \\ t &= 4x^2 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = \left(\frac{3}{4x^2} \right) z(x) \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 468: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 2 - 0 \\ &= 2 \end{aligned}$$

The poles of r in eq. (7) and the order of each pole are determined by solving for the roots of $t = 4x^2$. There is a pole at $x = 0$ of order 2. Since there is no odd order pole larger than 2 and the order at ∞ is 2 then the necessary conditions for case one are met. Since there is a pole of order 2 then necessary conditions for case two are met. Since pole order is not larger than 2 and the order at ∞ is 2 then the necessary conditions for case three are met. Therefore

$$L = [1, 2, 4, 6, 12]$$

Attempting to find a solution using case $n = 1$.

Looking at poles of order 2. The partial fractions decomposition of r is

$$r = \frac{3}{4x^2}$$

For the pole at $x = 0$ let b be the coefficient of $\frac{1}{x^2}$ in the partial fractions decomposition of r given above. Therefore $b = \frac{3}{4}$. Hence

$$\begin{aligned} [\sqrt{r}]_c &= 0 \\ \alpha_c^+ &= \frac{1}{2} + \sqrt{1 + 4b} = \frac{3}{2} \\ \alpha_c^- &= \frac{1}{2} - \sqrt{1 + 4b} = -\frac{1}{2} \end{aligned}$$

Since the order of r at ∞ is 2 then $[\sqrt{r}]_\infty = 0$. Let b be the coefficient of $\frac{1}{x^2}$ in the Laurent series expansion of r at ∞ , which can be found by dividing the leading coefficient of s by the leading coefficient of t from

$$r = \frac{s}{t} = \frac{3}{4x^2}$$

Since the $\gcd(s, t) = 1$. This gives $b = \frac{3}{4}$. Hence

$$\begin{aligned} [\sqrt{r}]_\infty &= 0 \\ \alpha_\infty^+ &= \frac{1}{2} + \sqrt{1 + 4b} = \frac{3}{2} \\ \alpha_\infty^- &= \frac{1}{2} - \sqrt{1 + 4b} = -\frac{1}{2} \end{aligned}$$

The following table summarizes the findings so far for poles and for the order of r at ∞ where r is

$$r = \frac{3}{4x^2}$$

pole c location	pole order	$[\sqrt{r}]_c$	α_c^+	α_c^-
0	2	0	$\frac{3}{2}$	$-\frac{1}{2}$

Order of r at ∞	$[\sqrt{r}]_\infty$	α_∞^+	α_∞^-
2	0	$\frac{3}{2}$	$-\frac{1}{2}$

Now that the all $[\sqrt{r}]_c$ and its associated α_c^\pm have been determined for all the poles in the set Γ and $[\sqrt{r}]_\infty$ and its associated α_∞^\pm have also been found, the next step is to determine possible non negative integer d from these using

$$d = \alpha_\infty^{s(\infty)} - \sum_{c \in \Gamma} \alpha_c^{s(c)}$$

Where $s(c)$ is either $+$ or $-$ and $s(\infty)$ is the sign of α_∞^\pm . This is done by trial over all set of families $s = (s(c))_{c \in \Gamma \cup \infty}$ until such d is found to work in finding candidate ω .

Trying $\alpha_{\infty}^{-} = -\frac{1}{2}$ then

$$\begin{aligned} d &= \alpha_{\infty}^{-} - (\alpha_{c_1}^{-}) \\ &= -\frac{1}{2} - \left(-\frac{1}{2}\right) \\ &= 0 \end{aligned}$$

Since d an integer and $d \geq 0$ then it can be used to find ω using

$$\omega = \sum_{c \in \Gamma} \left(s(c)[\sqrt{r}]_c + \frac{\alpha_c^{s(c)}}{x - c} \right) + s(\infty)[\sqrt{r}]_{\infty}$$

The above gives

$$\begin{aligned} \omega &= \left((-)[\sqrt{r}]_{c_1} + \frac{\alpha_{c_1}^{-}}{x - c_1} \right) + (-)[\sqrt{r}]_{\infty} \\ &= -\frac{1}{2x} + (-)(0) \\ &= -\frac{1}{2x} \\ &= -\frac{1}{2x} \end{aligned}$$

Now that ω is determined, the next step is find a corresponding minimal polynomial $p(x)$ of degree $d = 0$ to solve the ode. The polynomial $p(x)$ needs to satisfy the equation

$$p'' + 2\omega p' + (\omega' + \omega^2 - r)p = 0 \quad (1A)$$

Let

$$p(x) = 1 \quad (2A)$$

Substituting the above in eq. (1A) gives

$$\begin{aligned} (0) + 2\left(-\frac{1}{2x}\right)(0) + \left(\left(\frac{1}{2x^2}\right) + \left(-\frac{1}{2x}\right)^2 - \left(\frac{3}{4x^2}\right)\right) &= 0 \\ 0 &= 0 \end{aligned}$$

The equation is satisfied since both sides are zero. Therefore the first solution to the ode $z'' = rz$ is

$$\begin{aligned} z_1(x) &= pe^{\int \omega dx} \\ &= e^{\int -\frac{1}{2x} dx} \\ &= \frac{1}{\sqrt{x}} \end{aligned}$$

The first solution to the original ode in y is found from

$$\begin{aligned}y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\&= z_1 e^{-\int \frac{1}{2} \frac{-3x}{x^2} dx} \\&= z_1 e^{\frac{3 \ln(x)}{2}} \\&= z_1 \left(x^{\frac{3}{2}} \right)\end{aligned}$$

Which simplifies to

$$y_1 = x$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{-3x}{x^2} dx}}{(y_1)^2} dx \\&= y_1 \int \frac{e^{3 \ln(x)}}{(y_1)^2} dx \\&= y_1 \left(\frac{x^2}{2} \right)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\&= c_1(x) + c_2 \left(x \left(\frac{x^2}{2} \right) \right)\end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 x + \frac{1}{2} c_2 x^3 \tag{1}$$

Verification of solutions

$$y = c_1 x + \frac{1}{2} c_2 x^3$$

Verified OK.

13.1.7 Maple step by step solution

Let's solve

$$y''x^2 - 3y'x + 3y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = \frac{3y'}{x} - \frac{3y}{x^2}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' - \frac{3y'}{x} + \frac{3y}{x^2} = 0$$

- Multiply by denominators of the ODE

$$y''x^2 - 3y'x + 3y = 0$$

- Make a change of variables

$$t = \ln(x)$$

- Substitute the change of variables back into the ODE

- Calculate the 1st derivative of y with respect to x , using the chain rule

$$y' = \left(\frac{d}{dt}y(t)\right) t'(x)$$

- Compute derivative

$$y' = \frac{\frac{d}{dt}y(t)}{x}$$

- Calculate the 2nd derivative of y with respect to x , using the chain rule

$$y'' = \left(\frac{d^2}{dt^2}y(t)\right) t'(x)^2 + t''(x) \left(\frac{d}{dt}y(t)\right)$$

- Compute derivative

$$y'' = \frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2}$$

Substitute the change of variables back into the ODE

$$\left(\frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2}\right) x^2 - 3\frac{d}{dt}y(t) + 3y(t) = 0$$

- Simplify

$$\frac{d^2}{dt^2}y(t) - 4\frac{d}{dt}y(t) + 3y(t) = 0$$

- Characteristic polynomial of ODE

$$r^2 - 4r + 3 = 0$$

- Factor the characteristic polynomial
 $(r - 1)(r - 3) = 0$
- Roots of the characteristic polynomial
 $r = (1, 3)$
- 1st solution of the ODE
 $y_1(t) = e^t$
- 2nd solution of the ODE
 $y_2(t) = e^{3t}$
- General solution of the ODE
 $y(t) = c_1 y_1(t) + c_2 y_2(t)$
- Substitute in solutions
 $y(t) = c_1 e^t + c_2 e^{3t}$
- Change variables back using $t = \ln(x)$
 $y = c_2 x^3 + c_1 x$
- Simplify
 $y = x(c_2 x^2 + c_1)$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
<- LODE of Euler type successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 13

```
dsolve(x^2*diff(y(x),x$2)-3*x*diff(y(x),x)+3*y(x)=0,y(x), singsol=all)
```

$$y(x) = x(c_2 x^2 + c_1)$$

✓ Solution by Mathematica

Time used: 0.011 (sec). Leaf size: 16

```
DSolve[x^2*y'[x]-3*x*y'[x]+3*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow x(c_2x^2 + c_1)$$

13.2 problem 2

13.2.1 Solving as second order euler ode ode	3259
13.2.2 Solving as second order change of variable on x method 2 ode .	3260
13.2.3 Solving as second order change of variable on x method 1 ode .	3263
13.2.4 Solving as second order change of variable on y method 2 ode .	3265
13.2.5 Solving using Kovacic algorithm	3267
13.2.6 Maple step by step solution	3272

Internal problem ID [11856]

Internal file name [OUTPUT/11865_Saturday_April_13_2024_01_13_12_AM_22950223/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.5. The Cauchy-Euler Equation. Exercises page 169

Problem number: 2.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_euler_ode", "second_order_change_of_variable_on_x_method_1", "second_order_change_of_variable_on_x_method_2", "second_order_change_of_variable_on_y_method_2"

Maple gives the following as the ode type

```
[[_Emden, _Fowler], [_2nd_order, _linear, `_with_symmetry_[0,F(x)]`]]
```

$$x^2y'' + y'x - 4y = 0$$

13.2.1 Solving as second order euler ode ode

This is Euler second order ODE. Let the solution be $y = x^r$, then $y' = rx^{r-1}$ and $y'' = r(r-1)x^{r-2}$. Substituting these back into the given ODE gives

$$x^2(r(r-1))x^{r-2} + xrx^{r-1} - 4x^r = 0$$

Simplifying gives

$$r(r-1)x^r + rx^r - 4x^r = 0$$

Since $x^r \neq 0$ then dividing throughout by x^r gives

$$r(r - 1) + r - 4 = 0$$

Or

$$r^2 - 4 = 0 \tag{1}$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = -2$$

$$r_2 = 2$$

Since the roots are real and distinct, then the general solution is

$$y = c_1y_1 + c_2y_2$$

Where $y_1 = x^{r_1}$ and $y_2 = x^{r_2}$. Hence

$$y = \frac{c_1}{x^2} + c_2x^2$$

Summary

The solution(s) found are the following

$$y = \frac{c_1}{x^2} + c_2x^2 \tag{1}$$

Verification of solutions

$$y = \frac{c_1}{x^2} + c_2x^2$$

Verified OK.

13.2.2 Solving as second order change of variable on x method 2 ode

In normal form the ode

$$x^2y'' + y'x - 4y = 0 \tag{1}$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \tag{2}$$

Where

$$p(x) = \frac{1}{x}$$
$$q(x) = -\frac{4}{x^2}$$

Applying change of variables $\tau = g(x)$ to (2) gives

$$\frac{d^2}{d\tau^2}y(\tau) + p_1\left(\frac{d}{d\tau}y(\tau)\right) + q_1y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $p_1 = 0$. Eq (4) simplifies to

$$\tau''(x) + p(x)\tau'(x) = 0$$

This ode is solved resulting in

$$\begin{aligned} \tau &= \int e^{-(\int p(x)dx)} dx \\ &= \int e^{-(\int \frac{1}{x}dx)} dx \\ &= \int e^{-\ln(x)} dx \\ &= \int \frac{1}{x} dx \\ &= \ln(x) \end{aligned} \quad (6)$$

Using (6) to evaluate q_1 from (5) gives

$$\begin{aligned} q_1(\tau) &= \frac{q(x)}{\tau'(x)^2} \\ &= \frac{-\frac{4}{x^2}}{\frac{1}{x^2}} \\ &= -4 \end{aligned} \quad (7)$$

Substituting the above in (3) and noting that now $p_1 = 0$ results in

$$\begin{aligned} \frac{d^2}{d\tau^2}y(\tau) + q_1y(\tau) &= 0 \\ \frac{d^2}{d\tau^2}y(\tau) - 4y(\tau) &= 0 \end{aligned}$$

The above ode is now solved for $y(\tau)$. This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(\tau) + By'(\tau) + Cy(\tau) = 0$$

Where in the above $A = 1, B = 0, C = -4$. Let the solution be $y(\tau) = e^{\lambda\tau}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda\tau} - 4 e^{\lambda\tau} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda\tau}$ gives

$$\lambda^2 - 4 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 0, C = -4$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{0}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{0^2 - (4)(1)(-4)} \\ &= \pm 2 \end{aligned}$$

Hence

$$\lambda_1 = +2$$

$$\lambda_2 = -2$$

Which simplifies to

$$\lambda_1 = 2$$

$$\lambda_2 = -2$$

Since roots are real and distinct, then the solution is

$$y(\tau) = c_1 e^{\lambda_1 \tau} + c_2 e^{\lambda_2 \tau}$$

$$y(\tau) = c_1 e^{(2)\tau} + c_2 e^{(-2)\tau}$$

Or

$$y(\tau) = c_1 e^{2\tau} + c_2 e^{-2\tau}$$

The above solution is now transformed back to y using (6) which results in

$$y = \frac{c_1 x^4 + c_2}{x^2}$$

Summary

The solution(s) found are the following

$$y = \frac{c_1 x^4 + c_2}{x^2} \quad (1)$$

Verification of solutions

$$y = \frac{c_1 x^4 + c_2}{x^2}$$

Verified OK.

13.2.3 Solving as second order change of variable on x method 1 ode

In normal form the ode

$$x^2 y'' + y' x - 4y = 0 \quad (1)$$

Becomes

$$y'' + p(x) y' + q(x) y = 0 \quad (2)$$

Where

$$p(x) = \frac{1}{x}$$
$$q(x) = -\frac{4}{x^2}$$

Applying change of variables $\tau = g(x)$ to (2) results

$$\frac{d^2}{d\tau^2} y(\tau) + p_1 \left(\frac{d}{d\tau} y(\tau) \right) + q_1 y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x) \tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $q_1 = c^2$ where c is some constant. Therefore from (5)

$$\begin{aligned}\tau' &= \frac{1}{c}\sqrt{q} \\ &= \frac{2\sqrt{-\frac{1}{x^2}}}{c} \\ \tau'' &= \frac{2}{c\sqrt{-\frac{1}{x^2}}x^3}\end{aligned}\tag{6}$$

Substituting the above into (4) results in

$$\begin{aligned}p_1(\tau) &= \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \\ &= \frac{\frac{2}{c\sqrt{-\frac{1}{x^2}}x^3} + \frac{1}{x}\frac{2\sqrt{-\frac{1}{x^2}}}{c}}{\left(\frac{2\sqrt{-\frac{1}{x^2}}}{c}\right)^2} \\ &= 0\end{aligned}$$

Therefore ode (3) now becomes

$$\begin{aligned}y(\tau)'' + p_1y(\tau)' + q_1y(\tau) &= 0 \\ \frac{d^2}{d\tau^2}y(\tau) + c^2y(\tau) &= 0\end{aligned}\tag{7}$$

The above ode is now solved for $y(\tau)$. Since the ode is now constant coefficients, it can be easily solved to give

$$y(\tau) = c_1 \cos(c\tau) + c_2 \sin(c\tau)$$

Now from (6)

$$\begin{aligned}\tau &= \int \frac{1}{c}\sqrt{q} dx \\ &= \frac{\int 2\sqrt{-\frac{1}{x^2}} dx}{c} \\ &= \frac{2\sqrt{-\frac{1}{x^2}}x \ln(x)}{c}\end{aligned}$$

Substituting the above into the solution obtained gives

$$y = c_1 \cosh(2 \ln(x)) + ic_2 \sinh(2 \ln(x))$$

Summary

The solution(s) found are the following

$$y = c_1 \cosh(2 \ln(x)) + ic_2 \sinh(2 \ln(x)) \quad (1)$$

Verification of solutions

$$y = c_1 \cosh(2 \ln(x)) + ic_2 \sinh(2 \ln(x))$$

Verified OK.

13.2.4 Solving as second order change of variable on y method 2 ode

In normal form the ode

$$x^2 y'' + y'x - 4y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = \frac{1}{x}$$
$$q(x) = -\frac{4}{x^2}$$

Applying change of variables on the dependent variable $y = v(x)x^n$ to (2) gives the following ode where the dependent variables is $v(x)$ and not y .

$$v''(x) + \left(\frac{2n}{x} + p\right)v'(x) + \left(\frac{n(n-1)}{x^2} + \frac{np}{x} + q\right)v(x) = 0 \quad (3)$$

Let the coefficient of $v(x)$ above be zero. Hence

$$\frac{n(n-1)}{x^2} + \frac{np}{x} + q = 0 \quad (4)$$

Substituting the earlier values found for $p(x)$ and $q(x)$ into (4) gives

$$\frac{n(n-1)}{x^2} + \frac{n}{x^2} - \frac{4}{x^2} = 0 \quad (5)$$

Solving (5) for n gives

$$n = 2 \quad (6)$$

Substituting this value in (3) gives

$$\begin{aligned}v''(x) + \frac{5v'(x)}{x} &= 0 \\v''(x) + \frac{5v'(x)}{x} &= 0\end{aligned}\tag{7}$$

Using the substitution

$$u(x) = v'(x)$$

Then (7) becomes

$$u'(x) + \frac{5u(x)}{x} = 0\tag{8}$$

The above is now solved for $u(x)$. In canonical form the ODE is

$$\begin{aligned}u' &= F(x, u) \\&= f(x)g(u) \\&= -\frac{5u}{x}\end{aligned}$$

Where $f(x) = -\frac{5}{x}$ and $g(u) = u$. Integrating both sides gives

$$\begin{aligned}\frac{1}{u} du &= -\frac{5}{x} dx \\ \int \frac{1}{u} du &= \int -\frac{5}{x} dx \\ \ln(u) &= -5 \ln(x) + c_1 \\ u &= e^{-5 \ln(x) + c_1} \\ &= \frac{c_1}{x^5}\end{aligned}$$

Now that $u(x)$ is known, then

$$\begin{aligned}v'(x) &= u(x) \\ v(x) &= \int u(x) dx + c_2 \\ &= -\frac{c_1}{4x^4} + c_2\end{aligned}$$

Hence

$$\begin{aligned}y &= v(x) x^n \\ &= \left(-\frac{c_1}{4x^4} + c_2\right) x^2 \\ &= \frac{4c_2x^4 - c_1}{4x^2}\end{aligned}$$

Summary

The solution(s) found are the following

$$y = \left(-\frac{c_1}{4x^4} + c_2\right) x^2 \quad (1)$$

Verification of solutions

$$y = \left(-\frac{c_1}{4x^4} + c_2\right) x^2$$

Verified OK.

13.2.5 Solving using Kovacic algorithm

Writing the ode as

$$x^2y'' + y'x - 4y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned}A &= x^2 \\ B &= x \\ C &= -4\end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned}r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2}\end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{15}{4x^2} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 15 \\ t &= 4x^2 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = \left(\frac{15}{4x^2} \right) z(x) \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 470: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 2 - 0 \\ &= 2 \end{aligned}$$

The poles of r in eq. (7) and the order of each pole are determined by solving for the roots of $t = 4x^2$. There is a pole at $x = 0$ of order 2. Since there is no odd order pole larger than 2 and the order at ∞ is 2 then the necessary conditions for case one are met. Since there is a pole of order 2 then necessary conditions for case two are met. Since pole order is not larger than 2 and the order at ∞ is 2 then the necessary conditions for case three are met. Therefore

$$L = [1, 2, 4, 6, 12]$$

Attempting to find a solution using case $n = 1$.

Looking at poles of order 2. The partial fractions decomposition of r is

$$r = \frac{15}{4x^2}$$

For the pole at $x = 0$ let b be the coefficient of $\frac{1}{x^2}$ in the partial fractions decomposition of r given above. Therefore $b = \frac{15}{4}$. Hence

$$\begin{aligned} [\sqrt{r}]_c &= 0 \\ \alpha_c^+ &= \frac{1}{2} + \sqrt{1 + 4b} = \frac{5}{2} \\ \alpha_c^- &= \frac{1}{2} - \sqrt{1 + 4b} = -\frac{3}{2} \end{aligned}$$

Since the order of r at ∞ is 2 then $[\sqrt{r}]_\infty = 0$. Let b be the coefficient of $\frac{1}{x^2}$ in the Laurent series expansion of r at ∞ . which can be found by dividing the leading coefficient of s by the leading coefficient of t from

$$r = \frac{s}{t} = \frac{15}{4x^2}$$

Since the $\gcd(s, t) = 1$. This gives $b = \frac{15}{4}$. Hence

$$\begin{aligned} [\sqrt{r}]_\infty &= 0 \\ \alpha_\infty^+ &= \frac{1}{2} + \sqrt{1 + 4b} = \frac{5}{2} \\ \alpha_\infty^- &= \frac{1}{2} - \sqrt{1 + 4b} = -\frac{3}{2} \end{aligned}$$

The following table summarizes the findings so far for poles and for the order of r at ∞ where r is

$$r = \frac{15}{4x^2}$$

pole c location	pole order	$[\sqrt{r}]_c$	α_c^+	α_c^-
0	2	0	$\frac{5}{2}$	$-\frac{3}{2}$

Order of r at ∞	$[\sqrt{r}]_\infty$	α_∞^+	α_∞^-
2	0	$\frac{5}{2}$	$-\frac{3}{2}$

Now that the all $[\sqrt{r}]_c$ and its associated α_c^\pm have been determined for all the poles in the set Γ and $[\sqrt{r}]_\infty$ and its associated α_∞^\pm have also been found, the next step is to determine possible non negative integer d from these using

$$d = \alpha_\infty^{s(\infty)} - \sum_{c \in \Gamma} \alpha_c^{s(c)}$$

Where $s(c)$ is either $+$ or $-$ and $s(\infty)$ is the sign of α_∞^\pm . This is done by trial over all set of families $s = (s(c))_{c \in \Gamma \cup \infty}$ until such d is found to work in finding candidate ω . Trying $\alpha_\infty^- = -\frac{3}{2}$ then

$$\begin{aligned} d &= \alpha_\infty^- - (\alpha_{c_1}^-) \\ &= -\frac{3}{2} - \left(-\frac{3}{2}\right) \\ &= 0 \end{aligned}$$

Since d an integer and $d \geq 0$ then it can be used to find ω using

$$\omega = \sum_{c \in \Gamma} \left(s(c) [\sqrt{r}]_c + \frac{\alpha_c^{s(c)}}{x - c} \right) + s(\infty) [\sqrt{r}]_\infty$$

The above gives

$$\begin{aligned} \omega &= \left((-) [\sqrt{r}]_{c_1} + \frac{\alpha_{c_1}^-}{x - c_1} \right) + (-) [\sqrt{r}]_\infty \\ &= -\frac{3}{2x} + (-) (0) \\ &= -\frac{3}{2x} \\ &= -\frac{3}{2x} \end{aligned}$$

Now that ω is determined, the next step is find a corresponding minimal polynomial $p(x)$ of degree $d = 0$ to solve the ode. The polynomial $p(x)$ needs to satisfy the equation

$$p'' + 2\omega p' + (\omega' + \omega^2 - r) p = 0 \quad (1A)$$

Let

$$p(x) = 1 \quad (2A)$$

Substituting the above in eq. (1A) gives

$$(0) + 2\left(-\frac{3}{2x}\right)(0) + \left(\left(\frac{3}{2x^2}\right) + \left(-\frac{3}{2x}\right)^2 - \left(\frac{15}{4x^2}\right)\right) = 0$$
$$0 = 0$$

The equation is satisfied since both sides are zero. Therefore the first solution to the ode $z'' = rz$ is

$$z_1(x) = pe^{\int \omega dx}$$
$$= e^{\int -\frac{3}{2x} dx}$$
$$= \frac{1}{x^{\frac{3}{2}}}$$

The first solution to the original ode in y is found from

$$y_1 = z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx}$$
$$= z_1 e^{-\int \frac{1}{2} \frac{x}{x^2} dx}$$
$$= z_1 e^{-\frac{\ln(x)}{2}}$$
$$= z_1 \left(\frac{1}{\sqrt{x}}\right)$$

Which simplifies to

$$y_1 = \frac{1}{x^2}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$y_2 = y_1 \int \frac{e^{\int -\frac{x}{x^2} dx}}{(y_1)^2} dx$$
$$= y_1 \int \frac{e^{-\ln(x)}}{(y_1)^2} dx$$
$$= y_1 \left(\frac{x^4}{4}\right)$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1 \left(\frac{1}{x^2} \right) + c_2 \left(\frac{1}{x^2} \left(\frac{x^4}{4} \right) \right)\end{aligned}$$

Summary

The solution(s) found are the following

$$y = \frac{c_1}{x^2} + \frac{c_2 x^2}{4} \quad (1)$$

Verification of solutions

$$y = \frac{c_1}{x^2} + \frac{c_2 x^2}{4}$$

Verified OK.

13.2.6 Maple step by step solution

Let's solve

$$y'' x^2 + y' x - 4y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = -\frac{y'}{x} + \frac{4y}{x^2}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + \frac{y'}{x} - \frac{4y}{x^2} = 0$$

- Multiply by denominators of the ODE

$$y'' x^2 + y' x - 4y = 0$$

- Make a change of variables

$$t = \ln(x)$$

- Substitute the change of variables back into the ODE

- Calculate the 1st derivative of y with respect to x , using the chain rule

$$y' = \left(\frac{d}{dt} y(t) \right) t'(x)$$

- Compute derivative

$$y' = \frac{\frac{d}{dt}y(t)}{x}$$

- Calculate the 2nd derivative of y with respect to x , using the chain rule

$$y'' = \left(\frac{d^2}{dt^2}y(t) \right) t'(x)^2 + t''(x) \left(\frac{d}{dt}y(t) \right)$$

- Compute derivative

$$y'' = \frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2}$$

Substitute the change of variables back into the ODE

$$\left(\frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2} \right) x^2 + \frac{d}{dt}y(t) - 4y(t) = 0$$

- Simplify

$$\frac{d^2}{dt^2}y(t) - 4y(t) = 0$$

- Characteristic polynomial of ODE

$$r^2 - 4 = 0$$

- Factor the characteristic polynomial

$$(r - 2)(r + 2) = 0$$

- Roots of the characteristic polynomial

$$r = (-2, 2)$$

- 1st solution of the ODE

$$y_1(t) = e^{-2t}$$

- 2nd solution of the ODE

$$y_2(t) = e^{2t}$$

- General solution of the ODE

$$y(t) = c_1y_1(t) + c_2y_2(t)$$

- Substitute in solutions

$$y(t) = c_1e^{-2t} + c_2e^{2t}$$

- Change variables back using $t = \ln(x)$

$$y = \frac{c_1}{x^2} + c_2x^2$$

- Simplify

$$y = \frac{c_1}{x^2} + c_2x^2$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
checking if the LODE is of Euler type  
<- LODE of Euler type successful`
```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 15

```
dsolve(x^2*diff(y(x),x$2)+x*diff(y(x),x)-4*y(x)=0,y(x), singsol=all)
```

$$y(x) = \frac{x^4 c_1 + c_2}{x^2}$$

✓ Solution by Mathematica

Time used: 0.01 (sec). Leaf size: 18

```
DSolve[x^2*y''[x]+x*y'[x]-4*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{c_2 x^4 + c_1}{x^2}$$

13.3 problem 3

13.3.1 Solving as second order euler ode	3276
13.3.2 Solving as linear second order ode solved by an integrating factor ode	3277
13.3.3 Solving as second order change of variable on x method 2 ode	3278
13.3.4 Solving as second order change of variable on x method 1 ode	3280
13.3.5 Solving as second order change of variable on y method 1 ode	3282
13.3.6 Solving as second order change of variable on y method 2 ode	3284
13.3.7 Solving using Kovacic algorithm	3286
13.3.8 Maple step by step solution	3289

Internal problem ID [11857]

Internal file name [OUTPUT/11866_Saturday_April_13_2024_01_13_13_AM_53292417/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.5. The Cauchy-Euler Equation. Exercises page 169

Problem number: 3.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_euler_ode", "second_order_change_of_variable_on_x_method_1", "second_order_change_of_variable_on_x_method_2", "second_order_change_of_variable_on_y_method_1", "second_order_change_of_variable_on_y_method_2", "linear_second_order_ode_solved_by_an_integrating_factor"

Maple gives the following as the ode type

```
[[_Emden, _Fowler], [_2nd_order, _linear, `_with_symmetry_[0,F(x)]`]]
```

$$4x^2y'' - 4y'x + 3y = 0$$

13.3.1 Solving as second order euler ode ode

This is Euler second order ODE. Let the solution be $y = x^r$, then $y' = rx^{r-1}$ and $y'' = r(r-1)x^{r-2}$. Substituting these back into the given ODE gives

$$4x^2(r(r-1))x^{r-2} - 4xx^{r-1} + 3x^r = 0$$

Simplifying gives

$$4r(r-1)x^r - 4rx^r + 3x^r = 0$$

Since $x^r \neq 0$ then dividing throughout by x^r gives

$$4r(r-1) - 4r + 3 = 0$$

Or

$$4r^2 - 8r + 3 = 0 \tag{1}$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = \frac{1}{2}$$
$$r_2 = \frac{3}{2}$$

Since the roots are real and distinct, then the general solution is

$$y = c_1y_1 + c_2y_2$$

Where $y_1 = x^{r_1}$ and $y_2 = x^{r_2}$. Hence

$$y = c_1\sqrt{x} + c_2x^{\frac{3}{2}}$$

Summary

The solution(s) found are the following

$$y = c_1\sqrt{x} + c_2x^{\frac{3}{2}} \tag{1}$$

Verification of solutions

$$y = c_1\sqrt{x} + c_2x^{\frac{3}{2}}$$

Verified OK.

13.3.2 Solving as linear second order ode solved by an integrating factor ode

The ode satisfies this form

$$y'' + p(x)y' + \frac{(p(x)^2 + p'(x))y}{2} = f(x)$$

Where $p(x) = -\frac{1}{x}$. Therefore, there is an integrating factor given by

$$\begin{aligned}M(x) &= e^{\frac{1}{2} \int p dx} \\ &= e^{\int -\frac{1}{x} dx} \\ &= \frac{1}{\sqrt{x}}\end{aligned}$$

Multiplying both sides of the ODE by the integrating factor $M(x)$ makes the left side of the ODE a complete differential

$$\begin{aligned}(M(x)y)'' &= 0 \\ \left(\frac{y}{\sqrt{x}}\right)'' &= 0\end{aligned}$$

Integrating once gives

$$\left(\frac{y}{\sqrt{x}}\right)' = c_1$$

Integrating again gives

$$\left(\frac{y}{\sqrt{x}}\right) = c_1x + c_2$$

Hence the solution is

$$y = \frac{c_1x + c_2}{\frac{1}{\sqrt{x}}}$$

Or

$$y = c_1x^{\frac{3}{2}} + c_2\sqrt{x}$$

Summary

The solution(s) found are the following

$$y = c_1x^{\frac{3}{2}} + c_2\sqrt{x} \tag{1}$$

Verification of solutions

$$y = c_1x^{\frac{3}{2}} + c_2\sqrt{x}$$

Verified OK.

13.3.3 Solving as second order change of variable on x method 2 ode

In normal form the ode

$$4x^2y'' - 4y'x + 3y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = -\frac{1}{x}$$
$$q(x) = \frac{3}{4x^2}$$

Applying change of variables $\tau = g(x)$ to (2) gives

$$\frac{d^2}{d\tau^2}y(\tau) + p_1\left(\frac{d}{d\tau}y(\tau)\right) + q_1y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $p_1 = 0$. Eq (4) simplifies to

$$\tau''(x) + p(x)\tau'(x) = 0$$

This ode is solved resulting in

$$\begin{aligned} \tau &= \int e^{-(\int p(x)dx)} dx \\ &= \int e^{-(\int -\frac{1}{x}dx)} dx \\ &= \int e^{\ln(x)} dx \\ &= \int x dx \\ &= \frac{x^2}{2} \end{aligned} \quad (6)$$

Using (6) to evaluate q_1 from (5) gives

$$\begin{aligned} q_1(\tau) &= \frac{q(x)}{\tau'(x)^2} \\ &= \frac{\frac{3}{4x^2}}{x^2} \\ &= \frac{3}{4x^4} \end{aligned} \tag{7}$$

Substituting the above in (3) and noting that now $p_1 = 0$ results in

$$\begin{aligned} \frac{d^2}{d\tau^2}y(\tau) + q_1y(\tau) &= 0 \\ \frac{d^2}{d\tau^2}y(\tau) + \frac{3y(\tau)}{4x^4} &= 0 \end{aligned}$$

But in terms of τ

$$\frac{3}{4x^4} = \frac{3}{16\tau^2}$$

Hence the above ode becomes

$$\frac{d^2}{d\tau^2}y(\tau) + \frac{3y(\tau)}{16\tau^2} = 0$$

The above ode is now solved for $y(\tau)$. The ode can be written as

$$16 \left(\frac{d^2}{d\tau^2}y(\tau) \right) \tau^2 + 3y(\tau) = 0$$

Which shows it is a Euler ODE. This is Euler second order ODE. Let the solution be $y(\tau) = \tau^r$, then $y' = r\tau^{r-1}$ and $y'' = r(r-1)\tau^{r-2}$. Substituting these back into the given ODE gives

$$16\tau^2(r(r-1))\tau^{r-2} + 0r\tau^{r-1} + 3\tau^r = 0$$

Simplifying gives

$$16r(r-1)\tau^r + 0\tau^r + 3\tau^r = 0$$

Since $\tau^r \neq 0$ then dividing throughout by τ^r gives

$$16r(r-1) + 0 + 3 = 0$$

Or

$$16r^2 - 16r + 3 = 0 \tag{1}$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = \frac{1}{4}$$

$$r_2 = \frac{3}{4}$$

Since the roots are real and distinct, then the general solution is

$$y(\tau) = c_1 y_1 + c_2 y_2$$

Where $y_1 = \tau^{r_1}$ and $y_2 = \tau^{r_2}$. Hence

$$y(\tau) = c_1 \tau^{\frac{1}{4}} + c_2 \tau^{\frac{3}{4}}$$

The above solution is now transformed back to y using (6) which results in

$$y = \frac{c_1 2^{\frac{3}{4}} (x^2)^{\frac{1}{4}}}{2} + \frac{c_2 2^{\frac{1}{4}} (x^2)^{\frac{3}{4}}}{2}$$

Summary

The solution(s) found are the following

$$y = \frac{c_1 2^{\frac{3}{4}} (x^2)^{\frac{1}{4}}}{2} + \frac{c_2 2^{\frac{1}{4}} (x^2)^{\frac{3}{4}}}{2} \quad (1)$$

Verification of solutions

$$y = \frac{c_1 2^{\frac{3}{4}} (x^2)^{\frac{1}{4}}}{2} + \frac{c_2 2^{\frac{1}{4}} (x^2)^{\frac{3}{4}}}{2}$$

Verified OK.

13.3.4 Solving as second order change of variable on x method 1 ode

In normal form the ode

$$4x^2 y'' - 4y'x + 3y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = -\frac{1}{x}$$

$$q(x) = \frac{3}{4x^2}$$

Applying change of variables $\tau = g(x)$ to (2) results

$$\frac{d^2}{d\tau^2}y(\tau) + p_1\left(\frac{d}{d\tau}y(\tau)\right) + q_1y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $q_1 = c^2$ where c is some constant. Therefore from (5)

$$\begin{aligned} \tau' &= \frac{1}{c}\sqrt{q} \\ &= \frac{\sqrt{3}\sqrt{\frac{1}{x^2}}}{2c} \\ \tau'' &= -\frac{\sqrt{3}}{2c\sqrt{\frac{1}{x^2}}x^3} \end{aligned} \quad (6)$$

Substituting the above into (4) results in

$$\begin{aligned} p_1(\tau) &= \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \\ &= \frac{-\frac{\sqrt{3}}{2c\sqrt{\frac{1}{x^2}}x^3} - \frac{1}{x}\frac{\sqrt{3}\sqrt{\frac{1}{x^2}}}{2c}}{\left(\frac{\sqrt{3}\sqrt{\frac{1}{x^2}}}{2c}\right)^2} \\ &= -\frac{4c\sqrt{3}}{3} \end{aligned}$$

Therefore ode (3) now becomes

$$\begin{aligned} y(\tau)'' + p_1y(\tau)' + q_1y(\tau) &= 0 \\ \frac{d^2}{d\tau^2}y(\tau) - \frac{4c\sqrt{3}}{3}\left(\frac{d}{d\tau}y(\tau)\right) + c^2y(\tau) &= 0 \end{aligned} \quad (7)$$

The above ode is now solved for $y(\tau)$. Since the ode is now constant coefficients, it can be easily solved to give

$$y(\tau) = e^{\frac{2\sqrt{3}c\tau}{3}} \left(c_1 \cosh\left(\frac{\sqrt{3}c\tau}{3}\right) + ic_2 \sinh\left(\frac{\sqrt{3}c\tau}{3}\right) \right)$$

Now from (6)

$$\begin{aligned}\tau &= \int \frac{1}{c} \sqrt{q} dx \\ &= \frac{\int \frac{\sqrt{3} \sqrt{\frac{1}{x^2}} dx}{2}}{c} \\ &= \frac{\sqrt{3} \sqrt{\frac{1}{x^2}} x \ln(x)}{2c}\end{aligned}$$

Substituting the above into the solution obtained gives

$$y = x \left(c_1 \cosh \left(\frac{\ln(x)}{2} \right) + ic_2 \sinh \left(\frac{\ln(x)}{2} \right) \right)$$

Summary

The solution(s) found are the following

$$y = x \left(c_1 \cosh \left(\frac{\ln(x)}{2} \right) + ic_2 \sinh \left(\frac{\ln(x)}{2} \right) \right) \quad (1)$$

Verification of solutions

$$y = x \left(c_1 \cosh \left(\frac{\ln(x)}{2} \right) + ic_2 \sinh \left(\frac{\ln(x)}{2} \right) \right)$$

Verified OK.

13.3.5 Solving as second order change of variable on y method 1 ode

In normal form the given ode is written as

$$y'' + p(x) y' + q(x) y = 0 \quad (2)$$

Where

$$\begin{aligned}p(x) &= -\frac{1}{x} \\ q(x) &= \frac{3}{4x^2}\end{aligned}$$

Calculating the Liouville ode invariant Q given by

$$\begin{aligned}
 Q &= q - \frac{p'}{2} - \frac{p^2}{4} \\
 &= \frac{3}{4x^2} - \frac{\left(-\frac{1}{x}\right)'}{2} - \frac{\left(-\frac{1}{x}\right)^2}{4} \\
 &= \frac{3}{4x^2} - \frac{\left(\frac{1}{x^2}\right)}{2} - \frac{\left(\frac{1}{x^2}\right)}{4} \\
 &= \frac{3}{4x^2} - \left(\frac{1}{2x^2}\right) - \frac{1}{4x^2} \\
 &= 0
 \end{aligned}$$

Since the Liouville ode invariant does not depend on the independent variable x then the transformation

$$y = v(x) z(x) \quad (3)$$

is used to change the original ode to a constant coefficients ode in v . In (3) the term $z(x)$ is given by

$$\begin{aligned}
 z(x) &= e^{-\left(\int \frac{p(x)}{2} dx\right)} \\
 &= e^{-\int \frac{-1}{2x}} \\
 &= \sqrt{x}
 \end{aligned} \quad (5)$$

Hence (3) becomes

$$y = v(x) \sqrt{x} \quad (4)$$

Applying this change of variable to the original ode results in

$$4x^{\frac{5}{2}} v''(x) = 0$$

Which is now solved for $v(x)$ Integrating twice gives the solution

$$v(x) = c_1 x + c_2$$

Now that $v(x)$ is known, then

$$\begin{aligned}
 y &= v(x) z(x) \\
 &= (c_1 x + c_2) (z(x))
 \end{aligned} \quad (7)$$

But from (5)

$$z(x) = \sqrt{x}$$

Hence (7) becomes

$$y = (c_1x + c_2)\sqrt{x}$$

Summary

The solution(s) found are the following

$$y = (c_1x + c_2)\sqrt{x} \quad (1)$$

Verification of solutions

$$y = (c_1x + c_2)\sqrt{x}$$

Verified OK.

13.3.6 Solving as second order change of variable on y method 2 ode

In normal form the ode

$$4x^2y'' - 4y'x + 3y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = -\frac{1}{x}$$
$$q(x) = \frac{3}{4x^2}$$

Applying change of variables on the dependent variable $y = v(x)x^n$ to (2) gives the following ode where the dependent variables is $v(x)$ and not y .

$$v''(x) + \left(\frac{2n}{x} + p\right)v'(x) + \left(\frac{n(n-1)}{x^2} + \frac{np}{x} + q\right)v(x) = 0 \quad (3)$$

Let the coefficient of $v(x)$ above be zero. Hence

$$\frac{n(n-1)}{x^2} + \frac{np}{x} + q = 0 \quad (4)$$

Substituting the earlier values found for $p(x)$ and $q(x)$ into (4) gives

$$\frac{n(n-1)}{x^2} - \frac{n}{x^2} + \frac{3}{4x^2} = 0 \quad (5)$$

Solving (5) for n gives

$$n = \frac{3}{2} \tag{6}$$

Substituting this value in (3) gives

$$\begin{aligned} v''(x) + \frac{2v'(x)}{x} &= 0 \\ v''(x) + \frac{2v'(x)}{x} &= 0 \end{aligned} \tag{7}$$

Using the substitution

$$u(x) = v'(x)$$

Then (7) becomes

$$u'(x) + \frac{2u(x)}{x} = 0 \tag{8}$$

The above is now solved for $u(x)$. In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= -\frac{2u}{x} \end{aligned}$$

Where $f(x) = -\frac{2}{x}$ and $g(u) = u$. Integrating both sides gives

$$\begin{aligned} \frac{1}{u} du &= -\frac{2}{x} dx \\ \int \frac{1}{u} du &= \int -\frac{2}{x} dx \\ \ln(u) &= -2 \ln(x) + c_1 \\ u &= e^{-2 \ln(x) + c_1} \\ &= \frac{c_1}{x^2} \end{aligned}$$

Now that $u(x)$ is known, then

$$\begin{aligned} v'(x) &= u(x) \\ v(x) &= \int u(x) dx + c_2 \\ &= -\frac{c_1}{x} + c_2 \end{aligned}$$

Hence

$$\begin{aligned}y &= v(x) x^n \\ &= \left(-\frac{c_1}{x} + c_2\right) x^{\frac{3}{2}} \\ &= (c_2 x - c_1) \sqrt{x}\end{aligned}$$

Summary

The solution(s) found are the following

$$y = \left(-\frac{c_1}{x} + c_2\right) x^{\frac{3}{2}} \quad (1)$$

Verification of solutions

$$y = \left(-\frac{c_1}{x} + c_2\right) x^{\frac{3}{2}}$$

Verified OK.

13.3.7 Solving using Kovacic algorithm

Writing the ode as

$$4x^2 y'' - 4y'x + 3y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned}A &= 4x^2 \\ B &= -4x \\ C &= 3\end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned}r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2}\end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{0}{1} \tag{6}$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 0 \\ t &= 1 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = 0 \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 472: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - -\infty \\ &= \infty \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is *infinity* then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = 0$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = 1$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-4x}{4x^2} dx} \\ &= z_1 e^{\frac{\ln(x)}{2}} \\ &= z_1 (\sqrt{x}) \end{aligned}$$

Which simplifies to

$$y_1 = \sqrt{x}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{-4x}{4x^2} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{\ln(x)}}{(y_1)^2} dx \\ &= y_1(x) \end{aligned}$$

Therefore the solution is

$$\begin{aligned} y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (\sqrt{x}) + c_2 (\sqrt{x}(x)) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1\sqrt{x} + c_2x^{\frac{3}{2}} \quad (1)$$

Verification of solutions

$$y = c_1\sqrt{x} + c_2x^{\frac{3}{2}}$$

Verified OK.

13.3.8 Maple step by step solution

Let's solve

$$4y''x^2 - 4y'x + 3y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = \frac{y'}{x} - \frac{3y}{4x^2}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' - \frac{y'}{x} + \frac{3y}{4x^2} = 0$$

- Multiply by denominators of the ODE

$$4y''x^2 - 4y'x + 3y = 0$$

- Make a change of variables

$$t = \ln(x)$$

- Substitute the change of variables back into the ODE

- Calculate the 1st derivative of y with respect to x , using the chain rule

$$y' = \left(\frac{d}{dt}y(t)\right) t'(x)$$

- Compute derivative

$$y' = \frac{\frac{d}{dt}y(t)}{x}$$

- Calculate the 2nd derivative of y with respect to x , using the chain rule

$$y'' = \left(\frac{d^2}{dt^2}y(t)\right) t'(x)^2 + t''(x) \left(\frac{d}{dt}y(t)\right)$$

- Compute derivative

$$y'' = \frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2}$$

Substitute the change of variables back into the ODE

$$4\left(\frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2}\right)x^2 - 4\frac{d}{dt}y(t) + 3y(t) = 0$$

- Simplify

$$4\frac{d^2}{dt^2}y(t) - 8\frac{d}{dt}y(t) + 3y(t) = 0$$

- Isolate 2nd derivative

$$\frac{d^2}{dt^2}y(t) = 2\frac{d}{dt}y(t) - \frac{3y(t)}{4}$$

- Group terms with $y(t)$ on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$\frac{d^2}{dt^2}y(t) - 2\frac{d}{dt}y(t) + \frac{3y(t)}{4} = 0$$

- Characteristic polynomial of ODE

$$r^2 - 2r + \frac{3}{4} = 0$$

- Factor the characteristic polynomial

$$\frac{(2r-1)(2r-3)}{4} = 0$$

- Roots of the characteristic polynomial

$$r = \left(\frac{1}{2}, \frac{3}{2}\right)$$

- 1st solution of the ODE

$$y_1(t) = e^{\frac{t}{2}}$$

- 2nd solution of the ODE

$$y_2(t) = e^{\frac{3t}{2}}$$

- General solution of the ODE

$$y(t) = c_1y_1(t) + c_2y_2(t)$$

- Substitute in solutions

$$y(t) = c_1e^{\frac{t}{2}} + c_2e^{\frac{3t}{2}}$$

- Change variables back using $t = \ln(x)$

$$y = c_1\sqrt{x} + c_2x^{\frac{3}{2}}$$

- Simplify

$$y = \sqrt{x}(c_2x + c_1)$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
checking if the LODE is of Euler type  
<- LODE of Euler type successful`
```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 13

```
dsolve(4*x^2*diff(y(x),x$2)-4*x*diff(y(x),x)+3*y(x)=0,y(x), singsol=all)
```

$$y(x) = \sqrt{x}(c_2x + c_1)$$

✓ Solution by Mathematica

Time used: 0.012 (sec). Leaf size: 18

```
DSolve[4*x^2*y'[x]-4*x*y'[x]+3*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \sqrt{x}(c_2x + c_1)$$

13.4 problem 4

13.4.1 Solving as second order euler ode ode	3292
13.4.2 Solving as second order change of variable on x method 2 ode .	3293
13.4.3 Solving as second order change of variable on x method 1 ode .	3296
13.4.4 Solving as second order change of variable on y method 2 ode .	3298
13.4.5 Solving using Kovacic algorithm	3300
13.4.6 Maple step by step solution	3305

Internal problem ID [11858]

Internal file name [OUTPUT/11867_Saturday_April_13_2024_01_13_15_AM_60726113/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.5. The Cauchy-Euler Equation. Exercises page 169

Problem number: 4.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_euler_ode", "second_order_change_of_variable_on_x_method_1", "second_order_change_of_variable_on_x_method_2", "second_order_change_of_variable_on_y_method_2"

Maple gives the following as the ode type

```
[[_Emden, _Fowler], [_2nd_order, _linear, `_with_symmetry_[0,F(x)]`]]
```

$$x^2y'' - 3y'x + 4y = 0$$

13.4.1 Solving as second order euler ode ode

This is Euler second order ODE. Let the solution be $y = x^r$, then $y' = rx^{r-1}$ and $y'' = r(r-1)x^{r-2}$. Substituting these back into the given ODE gives

$$x^2(r(r-1))x^{r-2} - 3rx^{r-1} + 4x^r = 0$$

Simplifying gives

$$r(r-1)x^r - 3rx^r + 4x^r = 0$$

Since $x^r \neq 0$ then dividing throughout by x^r gives

$$r(r - 1) - 3r + 4 = 0$$

Or

$$r^2 - 4r + 4 = 0 \quad (1)$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = 2$$

$$r_2 = 2$$

Since the roots are equal, then the general solution is

$$y = c_1 y_1 + c_2 y_2$$

Where $y_1 = x^r$ and $y_2 = x^r \ln(x)$. Hence

$$y = c_1 x^2 + c_2 x^2 \ln(x)$$

Summary

The solution(s) found are the following

$$y = c_1 x^2 + c_2 x^2 \ln(x) \quad (1)$$

Verification of solutions

$$y = c_1 x^2 + c_2 x^2 \ln(x)$$

Verified OK.

13.4.2 Solving as second order change of variable on x method 2 ode

In normal form the ode

$$x^2 y'' - 3y'x + 4y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = -\frac{3}{x}$$
$$q(x) = \frac{4}{x^2}$$

Applying change of variables $\tau = g(x)$ to (2) gives

$$\frac{d^2}{d\tau^2}y(\tau) + p_1\left(\frac{d}{d\tau}y(\tau)\right) + q_1y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $p_1 = 0$. Eq (4) simplifies to

$$\tau''(x) + p(x)\tau'(x) = 0$$

This ode is solved resulting in

$$\begin{aligned} \tau &= \int e^{-(\int p(x)dx)} dx \\ &= \int e^{-(\int -\frac{3}{x}dx)} dx \\ &= \int e^{3\ln(x)} dx \\ &= \int x^3 dx \\ &= \frac{x^4}{4} \end{aligned} \quad (6)$$

Using (6) to evaluate q_1 from (5) gives

$$\begin{aligned} q_1(\tau) &= \frac{q(x)}{\tau'(x)^2} \\ &= \frac{4}{x^6} \\ &= \frac{4}{x^8} \end{aligned} \quad (7)$$

Substituting the above in (3) and noting that now $p_1 = 0$ results in

$$\begin{aligned} \frac{d^2}{d\tau^2}y(\tau) + q_1y(\tau) &= 0 \\ \frac{d^2}{d\tau^2}y(\tau) + \frac{4y(\tau)}{x^8} &= 0 \end{aligned}$$

But in terms of τ

$$\frac{4}{x^8} = \frac{1}{4\tau^2}$$

Hence the above ode becomes

$$\frac{d^2}{d\tau^2}y(\tau) + \frac{y(\tau)}{4\tau^2} = 0$$

The above ode is now solved for $y(\tau)$. The ode can be written as

$$4\left(\frac{d^2}{d\tau^2}y(\tau)\right)\tau^2 + y(\tau) = 0$$

Which shows it is a Euler ODE. This is Euler second order ODE. Let the solution be $y(\tau) = \tau^r$, then $y' = r\tau^{r-1}$ and $y'' = r(r-1)\tau^{r-2}$. Substituting these back into the given ODE gives

$$4\tau^2(r(r-1))\tau^{r-2} + 0r\tau^{r-1} + \tau^r = 0$$

Simplifying gives

$$4r(r-1)\tau^r + 0\tau^r + \tau^r = 0$$

Since $\tau^r \neq 0$ then dividing throughout by τ^r gives

$$4r(r-1) + 0 + 1 = 0$$

Or

$$4r^2 - 4r + 1 = 0 \tag{1}$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = \frac{1}{2}$$
$$r_2 = \frac{1}{2}$$

Since the roots are equal, then the general solution is

$$y(\tau) = c_1y_1 + c_2y_2$$

Where $y_1 = \tau^r$ and $y_2 = \tau^r \ln(\tau)$. Hence

$$y(\tau) = c_1\sqrt{\tau} + c_2\sqrt{\tau} \ln(\tau)$$

The above solution is now transformed back to y using (6) which results in

$$y = \frac{(c_2 \ln(x^4) - 2c_2 \ln(2) + c_1) \sqrt{x^4}}{2}$$

Summary

The solution(s) found are the following

$$y = \frac{(c_2 \ln(x^4) - 2c_2 \ln(2) + c_1) \sqrt{x^4}}{2} \quad (1)$$

Verification of solutions

$$y = \frac{(c_2 \ln(x^4) - 2c_2 \ln(2) + c_1) \sqrt{x^4}}{2}$$

Verified OK.

13.4.3 Solving as second order change of variable on x method 1 ode

In normal form the ode

$$x^2 y'' - 3y'x + 4y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = -\frac{3}{x}$$

$$q(x) = \frac{4}{x^2}$$

Applying change of variables $\tau = g(x)$ to (2) results

$$\frac{d^2}{d\tau^2}y(\tau) + p_1\left(\frac{d}{d\tau}y(\tau)\right) + q_1y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $q_1 = c^2$ where c is some constant. Therefore from (5)

$$\begin{aligned} \tau' &= \frac{1}{c}\sqrt{q} \\ &= \frac{2\sqrt{\frac{1}{x^2}}}{c} \\ \tau'' &= -\frac{2}{c\sqrt{\frac{1}{x^2}}x^3} \end{aligned} \quad (6)$$

Substituting the above into (4) results in

$$\begin{aligned}
 p_1(\tau) &= \frac{\tau''(x) + p(x) \tau'(x)}{\tau'(x)^2} \\
 &= \frac{-\frac{2}{c\sqrt{\frac{1}{x^2}}x^3} - \frac{3}{x} \frac{2\sqrt{\frac{1}{x^2}}}{c}}{\left(\frac{2\sqrt{\frac{1}{x^2}}}{c}\right)^2} \\
 &= -2c
 \end{aligned}$$

Therefore ode (3) now becomes

$$\begin{aligned}
 y(\tau)'' + p_1 y(\tau)' + q_1 y(\tau) &= 0 \\
 \frac{d^2}{d\tau^2} y(\tau) - 2c \left(\frac{d}{d\tau} y(\tau) \right) + c^2 y(\tau) &= 0 \tag{7}
 \end{aligned}$$

The above ode is now solved for $y(\tau)$. Since the ode is now constant coefficients, it can be easily solved to give

$$y(\tau) = e^{c\tau} c_1$$

Now from (6)

$$\begin{aligned}
 \tau &= \int \frac{1}{c} \sqrt{q} dx \\
 &= \frac{\int 2\sqrt{\frac{1}{x^2}} dx}{c} \\
 &= \frac{2\sqrt{\frac{1}{x^2}} x \ln(x)}{c}
 \end{aligned}$$

Substituting the above into the solution obtained gives

$$y = c_1 x^2$$

Summary

The solution(s) found are the following

$$y = c_1 x^2 \tag{1}$$

Verification of solutions

$$y = c_1 x^2$$

Verified OK.

13.4.4 Solving as second order change of variable on y method 2 ode

In normal form the ode

$$x^2y'' - 3y'x + 4y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = -\frac{3}{x}$$
$$q(x) = \frac{4}{x^2}$$

Applying change of variables on the dependent variable $y = v(x)x^n$ to (2) gives the following ode where the dependent variables is $v(x)$ and not y .

$$v''(x) + \left(\frac{2n}{x} + p\right)v'(x) + \left(\frac{n(n-1)}{x^2} + \frac{np}{x} + q\right)v(x) = 0 \quad (3)$$

Let the coefficient of $v(x)$ above be zero. Hence

$$\frac{n(n-1)}{x^2} + \frac{np}{x} + q = 0 \quad (4)$$

Substituting the earlier values found for $p(x)$ and $q(x)$ into (4) gives

$$\frac{n(n-1)}{x^2} - \frac{3n}{x^2} + \frac{4}{x^2} = 0 \quad (5)$$

Solving (5) for n gives

$$n = 2 \quad (6)$$

Substituting this value in (3) gives

$$v''(x) + \frac{v'(x)}{x} = 0$$
$$v''(x) + \frac{v'(x)}{x} = 0 \quad (7)$$

Using the substitution

$$u(x) = v'(x)$$

Then (7) becomes

$$u'(x) + \frac{u(x)}{x} = 0 \quad (8)$$

The above is now solved for $u(x)$. In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= -\frac{u}{x} \end{aligned}$$

Where $f(x) = -\frac{1}{x}$ and $g(u) = u$. Integrating both sides gives

$$\begin{aligned} \frac{1}{u} du &= -\frac{1}{x} dx \\ \int \frac{1}{u} du &= \int -\frac{1}{x} dx \\ \ln(u) &= -\ln(x) + c_1 \\ u &= e^{-\ln(x)+c_1} \\ &= \frac{c_1}{x} \end{aligned}$$

Now that $u(x)$ is known, then

$$\begin{aligned} v'(x) &= u(x) \\ v(x) &= \int u(x) dx + c_2 \\ &= c_1 \ln(x) + c_2 \end{aligned}$$

Hence

$$\begin{aligned} y &= v(x) x^n \\ &= (c_1 \ln(x) + c_2) x^2 \\ &= (c_1 \ln(x) + c_2) x^2 \end{aligned}$$

Summary

The solution(s) found are the following

$$y = (c_1 \ln(x) + c_2) x^2 \quad (1)$$

Verification of solutions

$$y = (c_1 \ln(x) + c_2) x^2$$

Verified OK.

13.4.5 Solving using Kovacic algorithm

Writing the ode as

$$x^2y'' - 3y'x + 4y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= x^2 \\ B &= -3x \\ C &= 4 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-1}{4x^2} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= -1 \\ t &= 4x^2 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = \left(-\frac{1}{4x^2}\right) z(x) \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 474: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 2 - 0 \\ &= 2 \end{aligned}$$

The poles of r in eq. (7) and the order of each pole are determined by solving for the roots of $t = 4x^2$. There is a pole at $x = 0$ of order 2. Since there is no odd order pole larger than 2 and the order at ∞ is 2 then the necessary conditions for case one are met. Since there is a pole of order 2 then necessary conditions for case two are met. Since pole order is not larger than 2 and the order at ∞ is 2 then the necessary conditions for case three are met. Therefore

$$L = [1, 2, 4, 6, 12]$$

Attempting to find a solution using case $n = 1$.

Looking at poles of order 2. The partial fractions decomposition of r is

$$r = -\frac{1}{4x^2}$$

For the pole at $x = 0$ let b be the coefficient of $\frac{1}{x^2}$ in the partial fractions decomposition of r given above. Therefore $b = -\frac{1}{4}$. Hence

$$\begin{aligned} [\sqrt{r}]_c &= 0 \\ \alpha_c^+ &= \frac{1}{2} + \sqrt{1 + 4b} = \frac{1}{2} \\ \alpha_c^- &= \frac{1}{2} - \sqrt{1 + 4b} = \frac{1}{2} \end{aligned}$$

Since the order of r at ∞ is 2 then $[\sqrt{r}]_\infty = 0$. Let b be the coefficient of $\frac{1}{x^2}$ in the Laurent series expansion of r at ∞ , which can be found by dividing the leading coefficient of s by the leading coefficient of t from

$$r = \frac{s}{t} = -\frac{1}{4x^2}$$

Since the $\gcd(s, t) = 1$. This gives $b = -\frac{1}{4}$. Hence

$$\begin{aligned} [\sqrt{r}]_\infty &= 0 \\ \alpha_\infty^+ &= \frac{1}{2} + \sqrt{1 + 4b} = \frac{1}{2} \\ \alpha_\infty^- &= \frac{1}{2} - \sqrt{1 + 4b} = \frac{1}{2} \end{aligned}$$

The following table summarizes the findings so far for poles and for the order of r at ∞ where r is

$$r = -\frac{1}{4x^2}$$

pole c location	pole order	$[\sqrt{r}]_c$	α_c^+	α_c^-
0	2	0	$\frac{1}{2}$	$\frac{1}{2}$

Order of r at ∞	$[\sqrt{r}]_\infty$	α_∞^+	α_∞^-
2	0	$\frac{1}{2}$	$\frac{1}{2}$

Now that the all $[\sqrt{r}]_c$ and its associated α_c^\pm have been determined for all the poles in the set Γ and $[\sqrt{r}]_\infty$ and its associated α_∞^\pm have also been found, the next step is to determine possible non negative integer d from these using

$$d = \alpha_\infty^{s(\infty)} - \sum_{c \in \Gamma} \alpha_c^{s(c)}$$

Where $s(c)$ is either $+$ or $-$ and $s(\infty)$ is the sign of α_∞^\pm . This is done by trial over all set of families $s = (s(c))_{c \in \Gamma \cup \infty}$ until such d is found to work in finding candidate ω .

Trying $\alpha_{\infty}^{-} = \frac{1}{2}$ then

$$\begin{aligned} d &= \alpha_{\infty}^{-} - (\alpha_{c_1}^{-}) \\ &= \frac{1}{2} - \left(\frac{1}{2}\right) \\ &= 0 \end{aligned}$$

Since d an integer and $d \geq 0$ then it can be used to find ω using

$$\omega = \sum_{c \in \Gamma} \left(s(c)[\sqrt{r}]_c + \frac{\alpha_c^{s(c)}}{x - c} \right) + s(\infty)[\sqrt{r}]_{\infty}$$

The above gives

$$\begin{aligned} \omega &= \left((-)[\sqrt{r}]_{c_1} + \frac{\alpha_{c_1}^{-}}{x - c_1} \right) + (-)[\sqrt{r}]_{\infty} \\ &= \frac{1}{2x} + (-)(0) \\ &= \frac{1}{2x} \\ &= \frac{1}{2x} \end{aligned}$$

Now that ω is determined, the next step is find a corresponding minimal polynomial $p(x)$ of degree $d = 0$ to solve the ode. The polynomial $p(x)$ needs to satisfy the equation

$$p'' + 2\omega p' + (\omega' + \omega^2 - r)p = 0 \quad (1A)$$

Let

$$p(x) = 1 \quad (2A)$$

Substituting the above in eq. (1A) gives

$$\begin{aligned} (0) + 2\left(\frac{1}{2x}\right)(0) + \left(\left(-\frac{1}{2x^2}\right) + \left(\frac{1}{2x}\right)^2 - \left(-\frac{1}{4x^2}\right) \right) &= 0 \\ 0 &= 0 \end{aligned}$$

The equation is satisfied since both sides are zero. Therefore the first solution to the ode $z'' = rz$ is

$$\begin{aligned} z_1(x) &= p e^{\int \omega dx} \\ &= e^{\int \frac{1}{2x} dx} \\ &= \sqrt{x} \end{aligned}$$

The first solution to the original ode in y is found from

$$\begin{aligned}y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\&= z_1 e^{-\int \frac{1}{2} \frac{-3x}{x^2} dx} \\&= z_1 e^{\frac{3 \ln(x)}{2}} \\&= z_1 \left(x^{\frac{3}{2}} \right)\end{aligned}$$

Which simplifies to

$$y_1 = x^2$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{-3x}{x^2} dx}}{(y_1)^2} dx \\&= y_1 \int \frac{e^{3 \ln(x)}}{(y_1)^2} dx \\&= y_1 (\ln(x))\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\&= c_1 (x^2) + c_2 (x^2 (\ln(x)))\end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 x^2 + c_2 x^2 \ln(x) \tag{1}$$

Verification of solutions

$$y = c_1 x^2 + c_2 x^2 \ln(x)$$

Verified OK.

13.4.6 Maple step by step solution

Let's solve

$$y''x^2 - 3y'x + 4y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = \frac{3y'}{x} - \frac{4y}{x^2}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' - \frac{3y'}{x} + \frac{4y}{x^2} = 0$$

- Multiply by denominators of the ODE

$$y''x^2 - 3y'x + 4y = 0$$

- Make a change of variables

$$t = \ln(x)$$

- Substitute the change of variables back into the ODE

- Calculate the 1st derivative of y with respect to x , using the chain rule

$$y' = \left(\frac{d}{dt}y(t)\right) t'(x)$$

- Compute derivative

$$y' = \frac{\frac{d}{dt}y(t)}{x}$$

- Calculate the 2nd derivative of y with respect to x , using the chain rule

$$y'' = \left(\frac{d^2}{dt^2}y(t)\right) t'(x)^2 + t''(x) \left(\frac{d}{dt}y(t)\right)$$

- Compute derivative

$$y'' = \frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2}$$

Substitute the change of variables back into the ODE

$$\left(\frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2}\right) x^2 - 3\frac{d}{dt}y(t) + 4y(t) = 0$$

- Simplify

$$\frac{d^2}{dt^2}y(t) - 4\frac{d}{dt}y(t) + 4y(t) = 0$$

- Characteristic polynomial of ODE

$$r^2 - 4r + 4 = 0$$

- Factor the characteristic polynomial
 $(r - 2)^2 = 0$
- Root of the characteristic polynomial
 $r = 2$
- 1st solution of the ODE
 $y_1(t) = e^{2t}$
- Repeated root, multiply $y_1(t)$ by t to ensure linear independence
 $y_2(t) = t e^{2t}$
- General solution of the ODE
 $y(t) = c_1 y_1(t) + c_2 y_2(t)$
- Substitute in solutions
 $y(t) = c_1 e^{2t} + c_2 t e^{2t}$
- Change variables back using $t = \ln(x)$
 $y = c_1 x^2 + c_2 x^2 \ln(x)$
- Simplify
 $y = x^2(c_1 + \ln(x) c_2)$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
<- LODE of Euler type successful`

```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 14

```
dsolve(x^2*diff(y(x),x$2)-3*x*diff(y(x),x)+4*y(x)=0,y(x), singsol=all)
```

$$y(x) = x^2(c_1 + c_2 \ln(x))$$

✓ Solution by Mathematica

Time used: 0.018 (sec). Leaf size: 18

```
DSolve[x^2*y'[x]-3*x*y'[x]+4*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow x^2(2c_2 \log(x) + c_1)$$

13.5 problem 5

13.5.1 Solving as second order euler ode ode	3308
13.5.2 Solving as second order change of variable on x method 2 ode .	3310
13.5.3 Solving as second order change of variable on x method 1 ode .	3312
13.5.4 Solving as second order change of variable on y method 2 ode .	3314
13.5.5 Solving using Kovacic algorithm	3317
13.5.6 Maple step by step solution	3322

Internal problem ID [11859]

Internal file name [OUTPUT/11868_Saturday_April_13_2024_01_13_16_AM_62882544/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.5. The Cauchy-Euler Equation. Exercises page 169

Problem number: 5.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_euler_ode", "second_order_change_of_variable_on_x_method_1", "second_order_change_of_variable_on_x_method_2", "second_order_change_of_variable_on_y_method_2"

Maple gives the following as the ode type

```
[[_Emden, _Fowler], [_2nd_order, _linear, `_with_symmetry_[0,F(x)]`]]
```

$$x^2y'' + y'x + 4y = 0$$

13.5.1 Solving as second order euler ode ode

This is Euler second order ODE. Let the solution be $y = x^r$, then $y' = rx^{r-1}$ and $y'' = r(r-1)x^{r-2}$. Substituting these back into the given ODE gives

$$x^2(r(r-1))x^{r-2} + xrx^{r-1} + 4x^r = 0$$

Simplifying gives

$$r(r-1)x^r + rx^r + 4x^r = 0$$

Since $x^r \neq 0$ then dividing throughout by x^r gives

$$r(r - 1) + r + 4 = 0$$

Or

$$r^2 + 4 = 0 \tag{1}$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = -2i$$

$$r_2 = 2i$$

The roots are complex conjugate of each others. Let the roots be

$$r_1 = \alpha + i\beta$$

$$r_2 = \alpha - i\beta$$

Where in this case $\alpha = 0$ and $\beta = -2$. Hence the solution becomes

$$\begin{aligned} y &= c_1 x^{r_1} + c_2 x^{r_2} \\ &= c_1 x^{\alpha+i\beta} + c_2 x^{\alpha-i\beta} \\ &= x^\alpha (c_1 x^{i\beta} + c_2 x^{-i\beta}) \\ &= x^\alpha (c_1 e^{\ln(x^{i\beta})} + c_2 e^{\ln(x^{-i\beta})}) \\ &= x^\alpha (c_1 e^{i(\beta \ln x)} + c_2 e^{-i(\beta \ln x)}) \end{aligned}$$

Using the values for $\alpha = 0, \beta = -2$, the above becomes

$$y = x^0 (c_1 e^{-2i \ln(x)} + c_2 e^{2i \ln(x)})$$

Using Euler relation, the expression $c_1 e^{iA} + c_2 e^{-iA}$ is transformed to $c_1 \cos A + c_1 \sin A$ where the constants are free to change. Applying this to the above result gives

$$y = c_1 \cos(2 \ln(x)) + c_2 \sin(2 \ln(x))$$

Summary

The solution(s) found are the following

$$y = c_1 \cos(2 \ln(x)) + c_2 \sin(2 \ln(x)) \tag{1}$$

Verification of solutions

$$y = c_1 \cos(2 \ln(x)) + c_2 \sin(2 \ln(x))$$

Verified OK.

13.5.2 Solving as second order change of variable on x method 2 ode

In normal form the ode

$$x^2 y'' + y' x + 4y = 0 \quad (1)$$

Becomes

$$y'' + p(x) y' + q(x) y = 0 \quad (2)$$

Where

$$p(x) = \frac{1}{x}$$
$$q(x) = \frac{4}{x^2}$$

Applying change of variables $\tau = g(x)$ to (2) gives

$$\frac{d^2}{d\tau^2} y(\tau) + p_1 \left(\frac{d}{d\tau} y(\tau) \right) + q_1 y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x) \tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $p_1 = 0$. Eq (4) simplifies to

$$\tau''(x) + p(x) \tau'(x) = 0$$

This ode is solved resulting in

$$\begin{aligned} \tau &= \int e^{-(\int p(x) dx)} dx \\ &= \int e^{-(\int \frac{1}{x} dx)} dx \\ &= \int e^{-\ln(x)} dx \\ &= \int \frac{1}{x} dx \\ &= \ln(x) \end{aligned} \quad (6)$$

Using (6) to evaluate q_1 from (5) gives

$$\begin{aligned} q_1(\tau) &= \frac{q(x)}{\tau'(x)^2} \\ &= \frac{\frac{4}{x^2}}{\frac{1}{x^2}} \\ &= 4 \end{aligned} \tag{7}$$

Substituting the above in (3) and noting that now $p_1 = 0$ results in

$$\begin{aligned} \frac{d^2}{d\tau^2}y(\tau) + q_1y(\tau) &= 0 \\ \frac{d^2}{d\tau^2}y(\tau) + 4y(\tau) &= 0 \end{aligned}$$

The above ode is now solved for $y(\tau)$. This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(\tau) + By'(\tau) + Cy(\tau) = 0$$

Where in the above $A = 1, B = 0, C = 4$. Let the solution be $y(\tau) = e^{\lambda\tau}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda\tau} + 4 e^{\lambda\tau} = 0 \tag{1}$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda\tau}$ gives

$$\lambda^2 + 4 = 0 \tag{2}$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 0, C = 4$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{0}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{0^2 - (4)(1)(4)} \\ &= \pm 2i \end{aligned}$$

Hence

$$\lambda_1 = +2i$$

$$\lambda_2 = -2i$$

Which simplifies to

$$\lambda_1 = 2i$$

$$\lambda_2 = -2i$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = 0$ and $\beta = 2$. Therefore the final solution, when using Euler relation, can be written as

$$y(\tau) = e^{\alpha\tau}(c_1 \cos(\beta\tau) + c_2 \sin(\beta\tau))$$

Which becomes

$$y(\tau) = e^0(c_1 \cos(2\tau) + c_2 \sin(2\tau))$$

Or

$$y(\tau) = c_1 \cos(2\tau) + c_2 \sin(2\tau)$$

The above solution is now transformed back to y using (6) which results in

$$y = c_1 \cos(2 \ln(x)) + c_2 \sin(2 \ln(x))$$

Summary

The solution(s) found are the following

$$y = c_1 \cos(2 \ln(x)) + c_2 \sin(2 \ln(x)) \quad (1)$$

Verification of solutions

$$y = c_1 \cos(2 \ln(x)) + c_2 \sin(2 \ln(x))$$

Verified OK.

13.5.3 Solving as second order change of variable on x method 1 ode

In normal form the ode

$$x^2 y'' + y'x + 4y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = \frac{1}{x}$$

$$q(x) = \frac{4}{x^2}$$

Applying change of variables $\tau = g(x)$ to (2) results

$$\frac{d^2}{d\tau^2}y(\tau) + p_1\left(\frac{d}{d\tau}y(\tau)\right) + q_1y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $q_1 = c^2$ where c is some constant. Therefore from (5)

$$\tau' = \frac{1}{c}\sqrt{q}$$

$$= \frac{2\sqrt{\frac{1}{x^2}}}{c} \quad (6)$$

$$\tau'' = -\frac{2}{c\sqrt{\frac{1}{x^2}}x^3}$$

Substituting the above into (4) results in

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2}$$

$$= \frac{-\frac{2}{c\sqrt{\frac{1}{x^2}}x^3} + \frac{1}{x}\frac{2\sqrt{\frac{1}{x^2}}}{c}}{\left(\frac{2\sqrt{\frac{1}{x^2}}}{c}\right)^2}$$

$$= 0$$

Therefore ode (3) now becomes

$$y(\tau)'' + p_1y(\tau)' + q_1y(\tau) = 0$$

$$\frac{d^2}{d\tau^2}y(\tau) + c^2y(\tau) = 0 \quad (7)$$

The above ode is now solved for $y(\tau)$. Since the ode is now constant coefficients, it can be easily solved to give

$$y(\tau) = c_1 \cos(c\tau) + c_2 \sin(c\tau)$$

Now from (6)

$$\begin{aligned} \tau &= \int \frac{1}{c} \sqrt{q} dx \\ &= \frac{\int 2\sqrt{\frac{1}{x^2}} dx}{c} \\ &= \frac{2\sqrt{\frac{1}{x^2}} x \ln(x)}{c} \end{aligned}$$

Substituting the above into the solution obtained gives

$$y = c_1 \cos(2 \ln(x)) + c_2 \sin(2 \ln(x))$$

Summary

The solution(s) found are the following

$$y = c_1 \cos(2 \ln(x)) + c_2 \sin(2 \ln(x)) \quad (1)$$

Verification of solutions

$$y = c_1 \cos(2 \ln(x)) + c_2 \sin(2 \ln(x))$$

Verified OK.

13.5.4 Solving as second order change of variable on y method 2 ode

In normal form the ode

$$x^2 y'' + y' x + 4y = 0 \quad (1)$$

Becomes

$$y'' + p(x) y' + q(x) y = 0 \quad (2)$$

Where

$$\begin{aligned} p(x) &= \frac{1}{x} \\ q(x) &= \frac{4}{x^2} \end{aligned}$$

Applying change of variables on the dependent variable $y = v(x)x^n$ to (2) gives the following ode where the dependent variables is $v(x)$ and not y .

$$v''(x) + \left(\frac{2n}{x} + p\right)v'(x) + \left(\frac{n(n-1)}{x^2} + \frac{np}{x} + q\right)v(x) = 0 \quad (3)$$

Let the coefficient of $v(x)$ above be zero. Hence

$$\frac{n(n-1)}{x^2} + \frac{np}{x} + q = 0 \quad (4)$$

Substituting the earlier values found for $p(x)$ and $q(x)$ into (4) gives

$$\frac{n(n-1)}{x^2} + \frac{n}{x^2} + \frac{4}{x^2} = 0 \quad (5)$$

Solving (5) for n gives

$$n = 2i \quad (6)$$

Substituting this value in (3) gives

$$\begin{aligned} v''(x) + \left(\frac{4i}{x} + \frac{1}{x}\right)v'(x) &= 0 \\ v''(x) + \frac{(1+4i)v'(x)}{x} &= 0 \end{aligned} \quad (7)$$

Using the substitution

$$u(x) = v'(x)$$

Then (7) becomes

$$u'(x) + \frac{(1+4i)u(x)}{x} = 0 \quad (8)$$

The above is now solved for $u(x)$. In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= \frac{(-1-4i)u}{x} \end{aligned}$$

Where $f(x) = \frac{-1-4i}{x}$ and $g(u) = u$. Integrating both sides gives

$$\begin{aligned}\frac{1}{u} du &= \frac{-1-4i}{x} dx \\ \int \frac{1}{u} du &= \int \frac{-1-4i}{x} dx \\ \ln(u) &= (-1-4i) \ln(x) + c_1 \\ u &= e^{(-1-4i) \ln(x) + c_1} \\ &= c_1 e^{(-1-4i) \ln(x)}\end{aligned}$$

Which simplifies to

$$u(x) = \frac{c_1 x^{-4i}}{x}$$

Now that $u(x)$ is known, then

$$\begin{aligned}v'(x) &= u(x) \\ v(x) &= \int u(x) dx + c_2 \\ &= \frac{ic_1 x^{-4i}}{4} + c_2\end{aligned}$$

Hence

$$\begin{aligned}y &= v(x) x^n \\ &= \left(\frac{ic_1 x^{-4i}}{4} + c_2 \right) x^{2i} \\ &= x^{2i} c_2 + \frac{ix^{-2i} c_1}{4}\end{aligned}$$

Summary

The solution(s) found are the following

$$y = \left(\frac{ic_1 x^{-4i}}{4} + c_2 \right) x^{2i} \tag{1}$$

Verification of solutions

$$y = \left(\frac{ic_1 x^{-4i}}{4} + c_2 \right) x^{2i}$$

Verified OK.

13.5.5 Solving using Kovacic algorithm

Writing the ode as

$$x^2 y'' + y' x + 4y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= x^2 \\ B &= x \\ C &= 4 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-17}{4x^2} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= -17 \\ t &= 4x^2 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = \left(-\frac{17}{4x^2} \right) z(x) \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 476: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 2 - 0 \\ &= 2 \end{aligned}$$

The poles of r in eq. (7) and the order of each pole are determined by solving for the roots of $t = 4x^2$. There is a pole at $x = 0$ of order 2. Since there is no odd order pole larger than 2 and the order at ∞ is 2 then the necessary conditions for case one are met. Since there is a pole of order 2 then necessary conditions for case two are met. Since pole order is not larger than 2 and the order at ∞ is 2 then the necessary conditions for case three are met. Therefore

$$L = [1, 2, 4, 6, 12]$$

Attempting to find a solution using case $n = 1$.

Looking at poles of order 2. The partial fractions decomposition of r is

$$r = -\frac{17}{4x^2}$$

For the pole at $x = 0$ let b be the coefficient of $\frac{1}{x^2}$ in the partial fractions decomposition of r given above. Therefore $b = -\frac{17}{4}$. Hence

$$\begin{aligned} [\sqrt{r}]_c &= 0 \\ \alpha_c^+ &= \frac{1}{2} + \sqrt{1 + 4b} = \frac{1}{2} + 2i \\ \alpha_c^- &= \frac{1}{2} - \sqrt{1 + 4b} = \frac{1}{2} - 2i \end{aligned}$$

Since the order of r at ∞ is 2 then $[\sqrt{r}]_\infty = 0$. Let b be the coefficient of $\frac{1}{x^2}$ in the Laurent series expansion of r at ∞ , which can be found by dividing the leading coefficient of s by the leading coefficient of t from

$$r = \frac{s}{t} = -\frac{17}{4x^2}$$

Since the $\gcd(s, t) = 1$. This gives $b = -\frac{17}{4}$. Hence

$$\begin{aligned} [\sqrt{r}]_\infty &= 0 \\ \alpha_\infty^+ &= \frac{1}{2} + \sqrt{1 + 4b} = \frac{1}{2} + 2i \\ \alpha_\infty^- &= \frac{1}{2} - \sqrt{1 + 4b} = \frac{1}{2} - 2i \end{aligned}$$

The following table summarizes the findings so far for poles and for the order of r at ∞ where r is

$$r = -\frac{17}{4x^2}$$

pole c location	pole order	$[\sqrt{r}]_c$	α_c^+	α_c^-
0	2	0	$\frac{1}{2} + 2i$	$\frac{1}{2} - 2i$

Order of r at ∞	$[\sqrt{r}]_\infty$	α_∞^+	α_∞^-
2	0	$\frac{1}{2} + 2i$	$\frac{1}{2} - 2i$

Now that the all $[\sqrt{r}]_c$ and its associated α_c^\pm have been determined for all the poles in the set Γ and $[\sqrt{r}]_\infty$ and its associated α_∞^\pm have also been found, the next step is to determine possible non negative integer d from these using

$$d = \alpha_\infty^{s(\infty)} - \sum_{c \in \Gamma} \alpha_c^{s(c)}$$

Where $s(c)$ is either $+$ or $-$ and $s(\infty)$ is the sign of α_∞^\pm . This is done by trial over all set of families $s = (s(c))_{c \in \Gamma \cup \infty}$ until such d is found to work in finding candidate ω .

Trying $\alpha_{\infty}^{-} = \frac{1}{2} - 2i$ then

$$\begin{aligned} d &= \alpha_{\infty}^{-} - (\alpha_{c_1}^{-}) \\ &= \frac{1}{2} - 2i - \left(\frac{1}{2} - 2i\right) \\ &= 0 \end{aligned}$$

Since d an integer and $d \geq 0$ then it can be used to find ω using

$$\omega = \sum_{c \in \Gamma} \left(s(c)[\sqrt{r}]_c + \frac{\alpha_c^{s(c)}}{x - c} \right) + s(\infty)[\sqrt{r}]_{\infty}$$

The above gives

$$\begin{aligned} \omega &= \left((-)[\sqrt{r}]_{c_1} + \frac{\alpha_{c_1}^{-}}{x - c_1} \right) + (-)[\sqrt{r}]_{\infty} \\ &= \frac{\frac{1}{2} - 2i}{x} + (-)(0) \\ &= \frac{\frac{1}{2} - 2i}{x} \\ &= \frac{\frac{1}{2} - 2i}{x} \end{aligned}$$

Now that ω is determined, the next step is find a corresponding minimal polynomial $p(x)$ of degree $d = 0$ to solve the ode. The polynomial $p(x)$ needs to satisfy the equation

$$p'' + 2\omega p' + (\omega' + \omega^2 - r)p = 0 \quad (1A)$$

Let

$$p(x) = 1 \quad (2A)$$

Substituting the above in eq. (1A) gives

$$\begin{aligned} (0) + 2\left(\frac{\frac{1}{2} - 2i}{x}\right)(0) + \left(\left(\frac{-\frac{1}{2} + 2i}{x^2}\right) + \left(\frac{\frac{1}{2} - 2i}{x}\right)^2 - \left(-\frac{17}{4x^2}\right)\right) &= 0 \\ 0 &= 0 \end{aligned}$$

The equation is satisfied since both sides are zero. Therefore the first solution to the ode $z'' = rz$ is

$$\begin{aligned} z_1(x) &= pe^{\int \omega dx} \\ &= e^{\int \frac{\frac{1}{2} - 2i}{x} dx} \\ &= x^{\frac{1}{2} - 2i} \end{aligned}$$

The first solution to the original ode in y is found from

$$\begin{aligned}y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\&= z_1 e^{-\int \frac{1}{2} \frac{x}{x^2} dx} \\&= z_1 e^{-\frac{\ln(x)}{2}} \\&= z_1 \left(\frac{1}{\sqrt{x}} \right)\end{aligned}$$

Which simplifies to

$$y_1 = x^{-2i}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{x}{x^2} dx}}{(y_1)^2} dx \\&= y_1 \int \frac{e^{-\ln(x)}}{(y_1)^2} dx \\&= y_1 \left(-\frac{ix^{4i}}{4} \right)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\&= c_1 (x^{-2i}) + c_2 \left(x^{-2i} \left(-\frac{ix^{4i}}{4} \right) \right)\end{aligned}$$

Summary

The solution(s) found are the following

$$y = x^{-2i} c_1 - \frac{ic_2 x^{2i}}{4} \tag{1}$$

Verification of solutions

$$y = x^{-2i} c_1 - \frac{ic_2 x^{2i}}{4}$$

Verified OK.

13.5.6 Maple step by step solution

Let's solve

$$y''x^2 + y'x + 4y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = -\frac{y'}{x} - \frac{4y}{x^2}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + \frac{y'}{x} + \frac{4y}{x^2} = 0$$

- Multiply by denominators of the ODE

$$y''x^2 + y'x + 4y = 0$$

- Make a change of variables

$$t = \ln(x)$$

- Substitute the change of variables back into the ODE

- Calculate the 1st derivative of y with respect to x , using the chain rule

$$y' = \left(\frac{d}{dt}y(t)\right) t'(x)$$

- Compute derivative

$$y' = \frac{\frac{d}{dt}y(t)}{x}$$

- Calculate the 2nd derivative of y with respect to x , using the chain rule

$$y'' = \left(\frac{d^2}{dt^2}y(t)\right) t'(x)^2 + t''(x) \left(\frac{d}{dt}y(t)\right)$$

- Compute derivative

$$y'' = \frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2}$$

Substitute the change of variables back into the ODE

$$\left(\frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2}\right) x^2 + \frac{d}{dt}y(t) + 4y(t) = 0$$

- Simplify

$$\frac{d^2}{dt^2}y(t) + 4y(t) = 0$$

- Characteristic polynomial of ODE

$$r^2 + 4 = 0$$

- Use quadratic formula to solve for r

$$r = \frac{0 \pm (\sqrt{-16})}{2}$$
- Roots of the characteristic polynomial

$$r = (-2i, 2i)$$
- 1st solution of the ODE

$$y_1(t) = \cos(2t)$$
- 2nd solution of the ODE

$$y_2(t) = \sin(2t)$$
- General solution of the ODE

$$y(t) = c_1 y_1(t) + c_2 y_2(t)$$
- Substitute in solutions

$$y(t) = c_1 \cos(2t) + c_2 \sin(2t)$$
- Change variables back using $t = \ln(x)$

$$y = c_1 \cos(2 \ln(x)) + c_2 \sin(2 \ln(x))$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
<- LODE of Euler type successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 19

```
dsolve(x^2*diff(y(x),x$2)+x*diff(y(x),x)+4*y(x)=0,y(x), singsol=all)
```

$$y(x) = c_1 \sin(2 \ln(x)) + c_2 \cos(2 \ln(x))$$

✓ Solution by Mathematica

Time used: 0.021 (sec). Leaf size: 22

```
DSolve[x^2*y''[x]+x*y'[x]+4*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow c_1 \cos(2 \log(x)) + c_2 \sin(2 \log(x))$$

13.6 problem 6

13.6.1 Solving as second order euler ode ode	3325
13.6.2 Solving as second order change of variable on x method 2 ode .	3327
13.6.3 Solving as second order change of variable on x method 1 ode .	3330
13.6.4 Solving as second order change of variable on y method 2 ode .	3332
13.6.5 Solving using Kovacic algorithm	3334
13.6.6 Maple step by step solution	3339

Internal problem ID [11860]

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Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.5. The Cauchy-Euler Equation. Exercises page 169

Problem number: 6.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_euler_ode", "second_order_change_of_variable_on_x_method_1", "second_order_change_of_variable_on_x_method_2", "second_order_change_of_variable_on_y_method_2"

Maple gives the following as the ode type

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[[_Emden, _Fowler]]
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$$x^2y'' - 3y'x + 13y = 0$$

13.6.1 Solving as second order euler ode ode

This is Euler second order ODE. Let the solution be $y = x^r$, then $y' = rx^{r-1}$ and $y'' = r(r-1)x^{r-2}$. Substituting these back into the given ODE gives

$$x^2(r(r-1))x^{r-2} - 3rx^{r-1} + 13x^r = 0$$

Simplifying gives

$$r(r-1)x^r - 3rx^r + 13x^r = 0$$

Since $x^r \neq 0$ then dividing throughout by x^r gives

$$r(r-1) - 3r + 13 = 0$$

Or

$$r^2 - 4r + 13 = 0 \quad (1)$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = 2 - 3i$$

$$r_2 = 2 + 3i$$

The roots are complex conjugate of each others. Let the roots be

$$r_1 = \alpha + i\beta$$

$$r_2 = \alpha - i\beta$$

Where in this case $\alpha = 2$ and $\beta = -3$. Hence the solution becomes

$$\begin{aligned} y &= c_1 x^{r_1} + c_2 x^{r_2} \\ &= c_1 x^{\alpha+i\beta} + c_2 x^{\alpha-i\beta} \\ &= x^\alpha (c_1 x^{i\beta} + c_2 x^{-i\beta}) \\ &= x^\alpha (c_1 e^{\ln(x^{i\beta})} + c_2 e^{\ln(x^{-i\beta})}) \\ &= x^\alpha (c_1 e^{i(\beta \ln x)} + c_2 e^{-i(\beta \ln x)}) \end{aligned}$$

Using the values for $\alpha = 2, \beta = -3$, the above becomes

$$y = x^2 (c_1 e^{-3i \ln(x)} + c_2 e^{3i \ln(x)})$$

Using Euler relation, the expression $c_1 e^{iA} + c_2 e^{-iA}$ is transformed to $c_1 \cos A + c_1 \sin A$ where the constants are free to change. Applying this to the above result gives

$$y = x^2 (c_1 \cos(3 \ln(x)) + c_2 \sin(3 \ln(x)))$$

Summary

The solution(s) found are the following

$$y = x^2 (c_1 \cos(3 \ln(x)) + c_2 \sin(3 \ln(x))) \quad (1)$$

Verification of solutions

$$y = x^2 (c_1 \cos(3 \ln(x)) + c_2 \sin(3 \ln(x)))$$

Verified OK.

13.6.2 Solving as second order change of variable on x method 2 ode

In normal form the ode

$$x^2 y'' - 3y'x + 13y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = -\frac{3}{x}$$
$$q(x) = \frac{13}{x^2}$$

Applying change of variables $\tau = g(x)$ to (2) gives

$$\frac{d^2}{d\tau^2}y(\tau) + p_1\left(\frac{d}{d\tau}y(\tau)\right) + q_1y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $p_1 = 0$. Eq (4) simplifies to

$$\tau''(x) + p(x)\tau'(x) = 0$$

This ode is solved resulting in

$$\begin{aligned} \tau &= \int e^{-(\int p(x)dx)} dx \\ &= \int e^{-(\int -\frac{3}{x}dx)} dx \\ &= \int e^{3\ln(x)} dx \\ &= \int x^3 dx \\ &= \frac{x^4}{4} \end{aligned} \quad (6)$$

Using (6) to evaluate q_1 from (5) gives

$$\begin{aligned} q_1(\tau) &= \frac{q(x)}{\tau'(x)^2} \\ &= \frac{\frac{13}{x^2}}{x^6} \\ &= \frac{13}{x^8} \end{aligned} \tag{7}$$

Substituting the above in (3) and noting that now $p_1 = 0$ results in

$$\begin{aligned} \frac{d^2}{d\tau^2}y(\tau) + q_1y(\tau) &= 0 \\ \frac{d^2}{d\tau^2}y(\tau) + \frac{13y(\tau)}{x^8} &= 0 \end{aligned}$$

But in terms of τ

$$\frac{13}{x^8} = \frac{13}{16\tau^2}$$

Hence the above ode becomes

$$\frac{d^2}{d\tau^2}y(\tau) + \frac{13y(\tau)}{16\tau^2} = 0$$

The above ode is now solved for $y(\tau)$. The ode can be written as

$$16\left(\frac{d^2}{d\tau^2}y(\tau)\right)\tau^2 + 13y(\tau) = 0$$

Which shows it is a Euler ODE. This is Euler second order ODE. Let the solution be $y(\tau) = \tau^r$, then $y' = r\tau^{r-1}$ and $y'' = r(r-1)\tau^{r-2}$. Substituting these back into the given ODE gives

$$16\tau^2(r(r-1))\tau^{r-2} + 0r\tau^{r-1} + 13\tau^r = 0$$

Simplifying gives

$$16r(r-1)\tau^r + 0\tau^r + 13\tau^r = 0$$

Since $\tau^r \neq 0$ then dividing throughout by τ^r gives

$$16r(r-1) + 0 + 13 = 0$$

Or

$$16r^2 - 16r + 13 = 0 \tag{1}$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = \frac{1}{2} - \frac{3i}{4}$$

$$r_2 = \frac{1}{2} + \frac{3i}{4}$$

The roots are complex conjugate of each others. Let the roots be

$$r_1 = \alpha + i\beta$$

$$r_2 = \alpha - i\beta$$

Where in this case $\alpha = \frac{1}{2}$ and $\beta = -\frac{3}{4}$. Hence the solution becomes

$$y(\tau) = c_1\tau^{r_1} + c_2\tau^{r_2}$$

$$= c_1\tau^{\alpha+i\beta} + c_2\tau^{\alpha-i\beta}$$

$$= \tau^\alpha(c_1\tau^{i\beta} + c_2\tau^{-i\beta})$$

$$= \tau^\alpha(c_1e^{\ln(\tau^{i\beta})} + c_2e^{\ln(\tau^{-i\beta})})$$

$$= \tau^\alpha(c_1e^{i(\beta \ln \tau)} + c_2e^{-i(\beta \ln \tau)})$$

Using the values for $\alpha = \frac{1}{2}, \beta = -\frac{3}{4}$, the above becomes

$$y(\tau) = \tau^{\frac{1}{2}} \left(c_1 e^{-\frac{3i \ln(\tau)}{4}} + c_2 e^{\frac{3i \ln(\tau)}{4}} \right)$$

Using Euler relation, the expression $c_1 e^{iA} + c_2 e^{-iA}$ is transformed to $c_1 \cos A + c_1 \sin A$ where the constants are free to change. Applying this to the above result gives

$$y(\tau) = \sqrt{\tau} \left(c_1 \cos \left(\frac{3 \ln(\tau)}{4} \right) + c_2 \sin \left(\frac{3 \ln(\tau)}{4} \right) \right)$$

The above solution is now transformed back to y using (6) which results in

$$y = \frac{\left(c_1 \cos \left(-\frac{3 \ln(2)}{2} + 3 \ln(x) \right) + c_2 \sin \left(-\frac{3 \ln(2)}{2} + 3 \ln(x) \right) \right) x^2}{2}$$

Summary

The solution(s) found are the following

$$y = \frac{\left(c_1 \cos \left(-\frac{3 \ln(2)}{2} + 3 \ln(x) \right) + c_2 \sin \left(-\frac{3 \ln(2)}{2} + 3 \ln(x) \right) \right) x^2}{2} \quad (1)$$

Verification of solutions

$$y = \frac{\left(c_1 \cos \left(-\frac{3 \ln(2)}{2} + 3 \ln(x) \right) + c_2 \sin \left(-\frac{3 \ln(2)}{2} + 3 \ln(x) \right) \right) x^2}{2}$$

Verified OK.

13.6.3 Solving as second order change of variable on x method 1 ode

In normal form the ode

$$x^2 y'' - 3y'x + 13y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = -\frac{3}{x}$$

$$q(x) = \frac{13}{x^2}$$

Applying change of variables $\tau = g(x)$ to (2) results

$$\frac{d^2}{d\tau^2}y(\tau) + p_1 \left(\frac{d}{d\tau}y(\tau) \right) + q_1 y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $q_1 = c^2$ where c is some constant. Therefore from (5)

$$\begin{aligned} \tau' &= \frac{1}{c} \sqrt{q} \\ &= \frac{\sqrt{13} \sqrt{\frac{1}{x^2}}}{c} \\ \tau'' &= -\frac{\sqrt{13}}{c \sqrt{\frac{1}{x^2}} x^3} \end{aligned} \quad (6)$$

Substituting the above into (4) results in

$$\begin{aligned}
 p_1(\tau) &= \frac{\tau''(x) + p(x) \tau'(x)}{\tau'(x)^2} \\
 &= \frac{-\frac{\sqrt{13}}{c\sqrt{\frac{1}{x^2}}x^3} - \frac{3}{x} \frac{\sqrt{13}\sqrt{\frac{1}{x^2}}}{c}}{\left(\frac{\sqrt{13}\sqrt{\frac{1}{x^2}}}{c}\right)^2} \\
 &= -\frac{4c\sqrt{13}}{13}
 \end{aligned}$$

Therefore ode (3) now becomes

$$\begin{aligned}
 y(\tau)'' + p_1 y(\tau)' + q_1 y(\tau) &= 0 \\
 \frac{d^2}{d\tau^2} y(\tau) - \frac{4c\sqrt{13}}{13} \left(\frac{d}{d\tau} y(\tau)\right) + c^2 y(\tau) &= 0 \tag{7}
 \end{aligned}$$

The above ode is now solved for $y(\tau)$. Since the ode is now constant coefficients, it can be easily solved to give

$$y(\tau) = e^{\frac{2\sqrt{13}c\tau}{13}} \left(c_1 \cos\left(\frac{3\sqrt{13}c\tau}{13}\right) + c_2 \sin\left(\frac{3\sqrt{13}c\tau}{13}\right) \right)$$

Now from (6)

$$\begin{aligned}
 \tau &= \int \frac{1}{c} \sqrt{q} dx \\
 &= \frac{\int \sqrt{13} \sqrt{\frac{1}{x^2}} dx}{c} \\
 &= \frac{\sqrt{13} \sqrt{\frac{1}{x^2}} x \ln(x)}{c}
 \end{aligned}$$

Substituting the above into the solution obtained gives

$$y = x^2 (c_1 \cos(3 \ln(x)) + c_2 \sin(3 \ln(x)))$$

Summary

The solution(s) found are the following

$$y = x^2 (c_1 \cos(3 \ln(x)) + c_2 \sin(3 \ln(x))) \tag{1}$$

Verification of solutions

$$y = x^2 (c_1 \cos(3 \ln(x)) + c_2 \sin(3 \ln(x)))$$

Verified OK.

13.6.4 Solving as second order change of variable on y method 2 ode

In normal form the ode

$$x^2 y'' - 3y'x + 13y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = -\frac{3}{x}$$
$$q(x) = \frac{13}{x^2}$$

Applying change of variables on the dependent variable $y = v(x)x^n$ to (2) gives the following ode where the dependent variables is $v(x)$ and not y .

$$v''(x) + \left(\frac{2n}{x} + p\right)v'(x) + \left(\frac{n(n-1)}{x^2} + \frac{np}{x} + q\right)v(x) = 0 \quad (3)$$

Let the coefficient of $v(x)$ above be zero. Hence

$$\frac{n(n-1)}{x^2} + \frac{np}{x} + q = 0 \quad (4)$$

Substituting the earlier values found for $p(x)$ and $q(x)$ into (4) gives

$$\frac{n(n-1)}{x^2} - \frac{3n}{x^2} + \frac{13}{x^2} = 0 \quad (5)$$

Solving (5) for n gives

$$n = 2 + 3i \quad (6)$$

Substituting this value in (3) gives

$$v''(x) + \left(\frac{4+6i}{x} - \frac{3}{x}\right)v'(x) = 0$$
$$v''(x) + \frac{(1+6i)v'(x)}{x} = 0 \quad (7)$$

Using the substitution

$$u(x) = v'(x)$$

Then (7) becomes

$$u'(x) + \frac{(1 + 6i)u(x)}{x} = 0 \quad (8)$$

The above is now solved for $u(x)$. In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= \frac{(-1 - 6i)u}{x} \end{aligned}$$

Where $f(x) = \frac{-1-6i}{x}$ and $g(u) = u$. Integrating both sides gives

$$\begin{aligned} \frac{1}{u} du &= \frac{-1 - 6i}{x} dx \\ \int \frac{1}{u} du &= \int \frac{-1 - 6i}{x} dx \\ \ln(u) &= (-1 - 6i) \ln(x) + c_1 \\ u &= e^{(-1-6i)\ln(x)+c_1} \\ &= c_1 e^{(-1-6i)\ln(x)} \end{aligned}$$

Which simplifies to

$$u(x) = \frac{c_1 x^{-6i}}{x}$$

Now that $u(x)$ is known, then

$$\begin{aligned} v'(x) &= u(x) \\ v(x) &= \int u(x) dx + c_2 \\ &= \frac{ic_1 x^{-6i}}{6} + c_2 \end{aligned}$$

Hence

$$\begin{aligned} y &= v(x) x^n \\ &= \left(\frac{ic_1 x^{-6i}}{6} + c_2 \right) x^{2+3i} \\ &= c_2 x^{2+3i} + \frac{ic_1 x^{2-3i}}{6} \end{aligned}$$

Summary

The solution(s) found are the following

$$y = \left(\frac{ic_1 x^{-6i}}{6} + c_2 \right) x^{2+3i} \quad (1)$$

Verification of solutions

$$y = \left(\frac{ic_1 x^{-6i}}{6} + c_2 \right) x^{2+3i}$$

Verified OK.

13.6.5 Solving using Kovacic algorithm

Writing the ode as

$$x^2 y'' - 3y'x + 13y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= x^2 \\ B &= -3x \\ C &= 13 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-37}{4x^2} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= -37 \\ t &= 4x^2 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = \left(-\frac{37}{4x^2} \right) z(x) \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 478: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 2 - 0 \\ &= 2 \end{aligned}$$

The poles of r in eq. (7) and the order of each pole are determined by solving for the roots of $t = 4x^2$. There is a pole at $x = 0$ of order 2. Since there is no odd order pole

larger than 2 and the order at ∞ is 2 then the necessary conditions for case one are met. Since there is a pole of order 2 then necessary conditions for case two are met. Since pole order is not larger than 2 and the order at ∞ is 2 then the necessary conditions for case three are met. Therefore

$$L = [1, 2, 4, 6, 12]$$

Attempting to find a solution using case $n = 1$.

Looking at poles of order 2. The partial fractions decomposition of r is

$$r = -\frac{37}{4x^2}$$

For the pole at $x = 0$ let b be the coefficient of $\frac{1}{x^2}$ in the partial fractions decomposition of r given above. Therefore $b = -\frac{37}{4}$. Hence

$$\begin{aligned} [\sqrt{r}]_c &= 0 \\ \alpha_c^+ &= \frac{1}{2} + \sqrt{1 + 4b} = \frac{1}{2} + 3i \\ \alpha_c^- &= \frac{1}{2} - \sqrt{1 + 4b} = \frac{1}{2} - 3i \end{aligned}$$

Since the order of r at ∞ is 2 then $[\sqrt{r}]_\infty = 0$. Let b be the coefficient of $\frac{1}{x^2}$ in the Laurent series expansion of r at ∞ . which can be found by dividing the leading coefficient of s by the leading coefficient of t from

$$r = \frac{s}{t} = -\frac{37}{4x^2}$$

Since the $\gcd(s, t) = 1$. This gives $b = -\frac{37}{4}$. Hence

$$\begin{aligned} [\sqrt{r}]_\infty &= 0 \\ \alpha_\infty^+ &= \frac{1}{2} + \sqrt{1 + 4b} = \frac{1}{2} + 3i \\ \alpha_\infty^- &= \frac{1}{2} - \sqrt{1 + 4b} = \frac{1}{2} - 3i \end{aligned}$$

The following table summarizes the findings so far for poles and for the order of r at ∞ where r is

$$r = -\frac{37}{4x^2}$$

pole c location	pole order	$[\sqrt{r}]_c$	α_c^+	α_c^-
0	2	0	$\frac{1}{2} + 3i$	$\frac{1}{2} - 3i$

Order of r at ∞	$[\sqrt{r}]_\infty$	α_∞^+	α_∞^-
2	0	$\frac{1}{2} + 3i$	$\frac{1}{2} - 3i$

Now that the all $[\sqrt{r}]_c$ and its associated α_c^\pm have been determined for all the poles in the set Γ and $[\sqrt{r}]_\infty$ and its associated α_∞^\pm have also been found, the next step is to determine possible non negative integer d from these using

$$d = \alpha_\infty^{s(\infty)} - \sum_{c \in \Gamma} \alpha_c^{s(c)}$$

Where $s(c)$ is either $+$ or $-$ and $s(\infty)$ is the sign of α_∞^\pm . This is done by trial over all set of families $s = (s(c))_{c \in \Gamma \cup \infty}$ until such d is found to work in finding candidate ω . Trying $\alpha_\infty^- = \frac{1}{2} - 3i$ then

$$\begin{aligned} d &= \alpha_\infty^- - (\alpha_{c_1}^-) \\ &= \frac{1}{2} - 3i - \left(\frac{1}{2} - 3i \right) \\ &= 0 \end{aligned}$$

Since d an integer and $d \geq 0$ then it can be used to find ω using

$$\omega = \sum_{c \in \Gamma} \left(s(c)[\sqrt{r}]_c + \frac{\alpha_c^{s(c)}}{x - c} \right) + s(\infty)[\sqrt{r}]_\infty$$

The above gives

$$\begin{aligned} \omega &= \left((-)[\sqrt{r}]_{c_1} + \frac{\alpha_{c_1}^-}{x - c_1} \right) + (-)[\sqrt{r}]_\infty \\ &= \frac{\frac{1}{2} - 3i}{x} + (-)(0) \\ &= \frac{\frac{1}{2} - 3i}{x} \\ &= \frac{\frac{1}{2} - 3i}{x} \end{aligned}$$

Now that ω is determined, the next step is find a corresponding minimal polynomial $p(x)$ of degree $d = 0$ to solve the ode. The polynomial $p(x)$ needs to satisfy the equation

$$p'' + 2\omega p' + (\omega' + \omega^2 - r) p = 0 \tag{1A}$$

Let

$$p(x) = 1 \tag{2A}$$

Substituting the above in eq. (1A) gives

$$(0) + 2\left(\frac{\frac{1}{2} - 3i}{x}\right)(0) + \left(\left(\frac{-\frac{1}{2} + 3i}{x^2}\right) + \left(\frac{\frac{1}{2} - 3i}{x}\right)^2 - \left(-\frac{37}{4x^2}\right)\right) = 0$$

$$0 = 0$$

The equation is satisfied since both sides are zero. Therefore the first solution to the ode $z'' = rz$ is

$$\begin{aligned} z_1(x) &= pe^{\int \omega dx} \\ &= e^{\int \frac{\frac{1}{2} - 3i}{x} dx} \\ &= x^{\frac{1}{2} - 3i} \end{aligned}$$

The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-3x}{x^2} dx} \\ &= z_1 e^{\frac{3 \ln(x)}{2}} \\ &= z_1 \left(x^{\frac{3}{2}}\right) \end{aligned}$$

Which simplifies to

$$y_1 = x^{2-3i}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{-3x}{x^2} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{3 \ln(x)}}{(y_1)^2} dx \\ &= y_1 \left(-\frac{ix^{6i}}{6}\right) \end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (x^{2-3i}) + c_2 \left(x^{2-3i} \left(-\frac{i x^{6i}}{6} \right) \right)\end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 x^{2-3i} - \frac{i c_2 x^{2+3i}}{6} \quad (1)$$

Verification of solutions

$$y = c_1 x^{2-3i} - \frac{i c_2 x^{2+3i}}{6}$$

Verified OK.

13.6.6 Maple step by step solution

Let's solve

$$y'' x^2 - 3y' x + 13y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = \frac{3y'}{x} - \frac{13y}{x^2}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' - \frac{3y'}{x} + \frac{13y}{x^2} = 0$$

- Multiply by denominators of the ODE

$$y'' x^2 - 3y' x + 13y = 0$$

- Make a change of variables

$$t = \ln(x)$$

- Substitute the change of variables back into the ODE

- Calculate the 1st derivative of y with respect to x , using the chain rule

$$y' = \left(\frac{d}{dt} y(t) \right) t'(x)$$

- Compute derivative

$$y' = \frac{d}{dt} y(t)$$

- Calculate the 2nd derivative of y with respect to x , using the chain rule

$$y'' = \left(\frac{d^2}{dt^2} y(t) \right) t'(x)^2 + t''(x) \left(\frac{d}{dt} y(t) \right)$$

- Compute derivative

$$y'' = \frac{\frac{d^2}{dt^2} y(t)}{x^2} - \frac{\frac{d}{dt} y(t)}{x^2}$$

Substitute the change of variables back into the ODE

$$\left(\frac{\frac{d^2}{dt^2} y(t)}{x^2} - \frac{\frac{d}{dt} y(t)}{x^2} \right) x^2 - 3 \frac{d}{dt} y(t) + 13y(t) = 0$$

- Simplify

$$\frac{d^2}{dt^2} y(t) - 4 \frac{d}{dt} y(t) + 13y(t) = 0$$

- Characteristic polynomial of ODE

$$r^2 - 4r + 13 = 0$$

- Use quadratic formula to solve for r

$$r = \frac{4 \pm (\sqrt{-36})}{2}$$

- Roots of the characteristic polynomial

$$r = (2 - 3I, 2 + 3I)$$

- 1st solution of the ODE

$$y_1(t) = e^{2t} \cos(3t)$$

- 2nd solution of the ODE

$$y_2(t) = e^{2t} \sin(3t)$$

- General solution of the ODE

$$y(t) = c_1 y_1(t) + c_2 y_2(t)$$

- Substitute in solutions

$$y(t) = c_1 e^{2t} \cos(3t) + c_2 e^{2t} \sin(3t)$$

- Change variables back using $t = \ln(x)$

$$y = c_1 x^2 \cos(3 \ln(x)) + c_2 x^2 \sin(3 \ln(x))$$

- Simplify

$$y = x^2 (c_1 \cos(3 \ln(x)) + c_2 \sin(3 \ln(x)))$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
checking if the LODE is of Euler type  
<- LODE of Euler type successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 23

```
dsolve(x^2*diff(y(x),x$2)-3*x*diff(y(x),x)+13*y(x)=0,y(x), singsol=all)
```

$$y(x) = x^2(c_1 \sin(3 \ln(x)) + c_2 \cos(3 \ln(x)))$$

✓ Solution by Mathematica

Time used: 0.028 (sec). Leaf size: 26

```
DSolve[x^2*y'[x]-3*x*y'[x]+13*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow x^2(c_2 \cos(3 \log(x)) + c_1 \sin(3 \log(x)))$$

13.7 problem 7

13.7.1 Solving as second order euler ode ode	3342
13.7.2 Solving as second order change of variable on x method 2 ode .	3343
13.7.3 Solving as second order change of variable on x method 1 ode .	3346
13.7.4 Solving as second order change of variable on y method 2 ode .	3348
13.7.5 Solving using Kovacic algorithm	3350
13.7.6 Maple step by step solution	3356

Internal problem ID [11861]

Internal file name [OUTPUT/11870_Saturday_April_13_2024_01_13_19_AM_34740163/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.5. The Cauchy-Euler Equation. Exercises page 169

Problem number: 7.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_euler_ode", "second_order_change_of_variable_on_x_method_1", "second_order_change_of_variable_on_x_method_2", "second_order_change_of_variable_on_y_method_2"

Maple gives the following as the ode type

```
[[_Emden, _Fowler], [_2nd_order, _linear, `_with_symmetry_[0,F(x)]`]]
```

$$3x^2y'' - 4y'x + 2y = 0$$

13.7.1 Solving as second order euler ode ode

This is Euler second order ODE. Let the solution be $y = x^r$, then $y' = rx^{r-1}$ and $y'' = r(r-1)x^{r-2}$. Substituting these back into the given ODE gives

$$3x^2(r(r-1))x^{r-2} - 4rx^{r-1} + 2x^r = 0$$

Simplifying gives

$$3r(r-1)x^r - 4rx^r + 2x^r = 0$$

Since $x^r \neq 0$ then dividing throughout by x^r gives

$$3r(r - 1) - 4r + 2 = 0$$

Or

$$3r^2 - 7r + 2 = 0 \quad (1)$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$\begin{aligned} r_1 &= 2 \\ r_2 &= \frac{1}{3} \end{aligned}$$

Since the roots are real and distinct, then the general solution is

$$y = c_1 y_1 + c_2 y_2$$

Where $y_1 = x^{r_1}$ and $y_2 = x^{r_2}$. Hence

$$y = c_1 x^2 + c_2 x^{\frac{1}{3}}$$

Summary

The solution(s) found are the following

$$y = c_1 x^2 + c_2 x^{\frac{1}{3}} \quad (1)$$

Verification of solutions

$$y = c_1 x^2 + c_2 x^{\frac{1}{3}}$$

Verified OK.

13.7.2 Solving as second order change of variable on x method 2 ode

In normal form the ode

$$3x^2 y'' - 4y'x + 2y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$\begin{aligned} p(x) &= -\frac{4}{3x} \\ q(x) &= \frac{2}{3x^2} \end{aligned}$$

Applying change of variables $\tau = g(x)$ to (2) gives

$$\frac{d^2}{d\tau^2}y(\tau) + p_1\left(\frac{d}{d\tau}y(\tau)\right) + q_1y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $p_1 = 0$. Eq (4) simplifies to

$$\tau''(x) + p(x)\tau'(x) = 0$$

This ode is solved resulting in

$$\begin{aligned} \tau &= \int e^{-(\int p(x)dx)} dx \\ &= \int e^{-(\int -\frac{4}{3x}dx)} dx \\ &= \int e^{\frac{4\ln(x)}{3}} dx \\ &= \int x^{\frac{4}{3}} dx \\ &= \frac{3x^{\frac{7}{3}}}{7} \end{aligned} \quad (6)$$

Using (6) to evaluate q_1 from (5) gives

$$\begin{aligned} q_1(\tau) &= \frac{q(x)}{\tau'(x)^2} \\ &= \frac{\frac{2}{3x^2}}{x^{\frac{8}{3}}} \\ &= \frac{2}{3x^{\frac{14}{3}}} \end{aligned} \quad (7)$$

Substituting the above in (3) and noting that now $p_1 = 0$ results in

$$\begin{aligned} \frac{d^2}{d\tau^2}y(\tau) + q_1y(\tau) &= 0 \\ \frac{d^2}{d\tau^2}y(\tau) + \frac{2y(\tau)}{3x^{\frac{14}{3}}} &= 0 \end{aligned}$$

But in terms of τ

$$\frac{2}{3x^{\frac{14}{3}}} = \frac{6}{49\tau^2}$$

Hence the above ode becomes

$$\frac{d^2}{d\tau^2}y(\tau) + \frac{6y(\tau)}{49\tau^2} = 0$$

The above ode is now solved for $y(\tau)$. The ode can be written as

$$49\left(\frac{d^2}{d\tau^2}y(\tau)\right)\tau^2 + 6y(\tau) = 0$$

Which shows it is a Euler ODE. This is Euler second order ODE. Let the solution be $y(\tau) = \tau^r$, then $y' = r\tau^{r-1}$ and $y'' = r(r-1)\tau^{r-2}$. Substituting these back into the given ODE gives

$$49\tau^2(r(r-1))\tau^{r-2} + 0r\tau^{r-1} + 6\tau^r = 0$$

Simplifying gives

$$49r(r-1)\tau^r + 0\tau^r + 6\tau^r = 0$$

Since $\tau^r \neq 0$ then dividing throughout by τ^r gives

$$49r(r-1) + 0 + 6 = 0$$

Or

$$49r^2 - 49r + 6 = 0 \tag{1}$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = \frac{1}{7}$$
$$r_2 = \frac{6}{7}$$

Since the roots are real and distinct, then the general solution is

$$y(\tau) = c_1y_1 + c_2y_2$$

Where $y_1 = \tau^{r_1}$ and $y_2 = \tau^{r_2}$. Hence

$$y(\tau) = c_1\tau^{\frac{1}{7}} + c_2\tau^{\frac{6}{7}}$$

The above solution is now transformed back to y using (6) which results in

$$y = \frac{c_1 3^{\frac{1}{7}} 7^{\frac{6}{7}} \left(x^{\frac{7}{3}}\right)^{\frac{1}{7}}}{7} + \frac{c_2 3^{\frac{6}{7}} 7^{\frac{1}{7}} \left(x^{\frac{7}{3}}\right)^{\frac{6}{7}}}{7}$$

Summary

The solution(s) found are the following

$$y = \frac{c_1 3^{\frac{1}{7}} 7^{\frac{6}{7}} \left(x^{\frac{7}{3}}\right)^{\frac{1}{7}}}{7} + \frac{c_2 3^{\frac{6}{7}} 7^{\frac{1}{7}} \left(x^{\frac{7}{3}}\right)^{\frac{6}{7}}}{7} \quad (1)$$

Verification of solutions

$$y = \frac{c_1 3^{\frac{1}{7}} 7^{\frac{6}{7}} \left(x^{\frac{7}{3}}\right)^{\frac{1}{7}}}{7} + \frac{c_2 3^{\frac{6}{7}} 7^{\frac{1}{7}} \left(x^{\frac{7}{3}}\right)^{\frac{6}{7}}}{7}$$

Verified OK.

13.7.3 Solving as second order change of variable on x method 1 ode

In normal form the ode

$$3x^2 y'' - 4y'x + 2y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = -\frac{4}{3x}$$
$$q(x) = \frac{2}{3x^2}$$

Applying change of variables $\tau = g(x)$ to (2) results

$$\frac{d^2}{d\tau^2}y(\tau) + p_1\left(\frac{d}{d\tau}y(\tau)\right) + q_1y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $q_1 = c^2$ where c is some constant. Therefore from (5)

$$\begin{aligned}\tau' &= \frac{1}{c} \sqrt{q} \\ &= \frac{\sqrt{6} \sqrt{\frac{1}{x^2}}}{3c} \\ \tau'' &= -\frac{\sqrt{6}}{3c \sqrt{\frac{1}{x^2}} x^3}\end{aligned}\tag{6}$$

Substituting the above into (4) results in

$$\begin{aligned}p_1(\tau) &= \frac{\tau''(x) + p(x) \tau'(x)}{\tau'(x)^2} \\ &= \frac{-\frac{\sqrt{6}}{3c \sqrt{\frac{1}{x^2}} x^3} - \frac{4}{3x} \frac{\sqrt{6} \sqrt{\frac{1}{x^2}}}{3c}}{\left(\frac{\sqrt{6} \sqrt{\frac{1}{x^2}}}{3c}\right)^2} \\ &= -\frac{7c\sqrt{6}}{6}\end{aligned}$$

Therefore ode (3) now becomes

$$\begin{aligned}y(\tau)'' + p_1 y(\tau)' + q_1 y(\tau) &= 0 \\ \frac{d^2}{d\tau^2} y(\tau) - \frac{7c\sqrt{6}}{6} \left(\frac{d}{d\tau} y(\tau)\right) + c^2 y(\tau) &= 0\end{aligned}\tag{7}$$

The above ode is now solved for $y(\tau)$. Since the ode is now constant coefficients, it can be easily solved to give

$$y(\tau) = e^{\frac{7\sqrt{6} c\tau}{12}} \left(c_1 \cosh \left(\frac{5\sqrt{6} c\tau}{12} \right) + i c_2 \sinh \left(\frac{5\sqrt{6} c\tau}{12} \right) \right)$$

Now from (6)

$$\begin{aligned}\tau &= \int \frac{1}{c} \sqrt{q} dx \\ &= \frac{\int \frac{\sqrt{6} \sqrt{\frac{1}{x^2}}}{3} dx}{c} \\ &= \frac{\sqrt{6} \sqrt{\frac{1}{x^2}} x \ln(x)}{3c}\end{aligned}$$

Substituting the above into the solution obtained gives

$$y = x^{\frac{7}{6}} \left(c_1 \cosh \left(\frac{5 \ln(x)}{6} \right) + ic_2 \sinh \left(\frac{5 \ln(x)}{6} \right) \right)$$

Summary

The solution(s) found are the following

$$y = x^{\frac{7}{6}} \left(c_1 \cosh \left(\frac{5 \ln(x)}{6} \right) + ic_2 \sinh \left(\frac{5 \ln(x)}{6} \right) \right) \quad (1)$$

Verification of solutions

$$y = x^{\frac{7}{6}} \left(c_1 \cosh \left(\frac{5 \ln(x)}{6} \right) + ic_2 \sinh \left(\frac{5 \ln(x)}{6} \right) \right)$$

Verified OK.

13.7.4 Solving as second order change of variable on y method 2 ode

In normal form the ode

$$3x^2y'' - 4y'x + 2y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = -\frac{4}{3x}$$
$$q(x) = \frac{2}{3x^2}$$

Applying change of variables on the dependent variable $y = v(x)x^n$ to (2) gives the following ode where the dependent variables is $v(x)$ and not y .

$$v''(x) + \left(\frac{2n}{x} + p \right) v'(x) + \left(\frac{n(n-1)}{x^2} + \frac{np}{x} + q \right) v(x) = 0 \quad (3)$$

Let the coefficient of $v(x)$ above be zero. Hence

$$\frac{n(n-1)}{x^2} + \frac{np}{x} + q = 0 \quad (4)$$

Substituting the earlier values found for $p(x)$ and $q(x)$ into (4) gives

$$\frac{n(n-1)}{x^2} - \frac{4n}{3x^2} + \frac{2}{3x^2} = 0 \quad (5)$$

Solving (5) for n gives

$$n = 2 \quad (6)$$

Substituting this value in (3) gives

$$\begin{aligned} v''(x) + \frac{8v'(x)}{3x} &= 0 \\ v''(x) + \frac{8v'(x)}{3x} &= 0 \end{aligned} \quad (7)$$

Using the substitution

$$u(x) = v'(x)$$

Then (7) becomes

$$u'(x) + \frac{8u(x)}{3x} = 0 \quad (8)$$

The above is now solved for $u(x)$. In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= -\frac{8u}{3x} \end{aligned}$$

Where $f(x) = -\frac{8}{3x}$ and $g(u) = u$. Integrating both sides gives

$$\begin{aligned} \frac{1}{u} du &= -\frac{8}{3x} dx \\ \int \frac{1}{u} du &= \int -\frac{8}{3x} dx \\ \ln(u) &= -\frac{8 \ln(x)}{3} + c_1 \\ u &= e^{-\frac{8 \ln(x)}{3} + c_1} \\ &= \frac{c_1}{x^{\frac{8}{3}}} \end{aligned}$$

Now that $u(x)$ is known, then

$$\begin{aligned}v'(x) &= u(x) \\v(x) &= \int u(x) dx + c_2 \\&= -\frac{3c_1}{5x^{\frac{5}{3}}} + c_2\end{aligned}$$

Hence

$$\begin{aligned}y &= v(x) x^n \\&= \left(-\frac{3c_1}{5x^{\frac{5}{3}}} + c_2\right) x^2 \\&= c_2 x^2 - \frac{3x^{\frac{1}{3}} c_1}{5}\end{aligned}$$

Summary

The solution(s) found are the following

$$y = \left(-\frac{3c_1}{5x^{\frac{5}{3}}} + c_2\right) x^2 \quad (1)$$

Verification of solutions

$$y = \left(-\frac{3c_1}{5x^{\frac{5}{3}}} + c_2\right) x^2$$

Verified OK.

13.7.5 Solving using Kovacic algorithm

Writing the ode as

$$3x^2 y'' - 4y'x + 2y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned}A &= 3x^2 \\B &= -4x \\C &= 2\end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{4}{9x^2} \tag{6}$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 4 \\ t &= 9x^2 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = \left(\frac{4}{9x^2} \right) z(x) \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 480: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 2 - 0 \\ &= 2 \end{aligned}$$

The poles of r in eq. (7) and the order of each pole are determined by solving for the roots of $t = 9x^2$. There is a pole at $x = 0$ of order 2. Since there is no odd order pole larger than 2 and the order at ∞ is 2 then the necessary conditions for case one are met. Since there is a pole of order 2 then necessary conditions for case two are met. Since pole order is not larger than 2 and the order at ∞ is 2 then the necessary conditions for case three are met. Therefore

$$L = [1, 2, 4, 6, 12]$$

Attempting to find a solution using case $n = 1$.

Looking at poles of order 2. The partial fractions decomposition of r is

$$r = \frac{4}{9x^2}$$

For the pole at $x = 0$ let b be the coefficient of $\frac{1}{x^2}$ in the partial fractions decomposition

of r given above. Therefore $b = \frac{4}{9}$. Hence

$$\begin{aligned} [\sqrt{r}]_c &= 0 \\ \alpha_c^+ &= \frac{1}{2} + \sqrt{1 + 4b} = \frac{4}{3} \\ \alpha_c^- &= \frac{1}{2} - \sqrt{1 + 4b} = -\frac{1}{3} \end{aligned}$$

Since the order of r at ∞ is 2 then $[\sqrt{r}]_\infty = 0$. Let b be the coefficient of $\frac{1}{x^2}$ in the Laurent series expansion of r at ∞ , which can be found by dividing the leading coefficient of s by the leading coefficient of t from

$$r = \frac{s}{t} = \frac{4}{9x^2}$$

Since the $\gcd(s, t) = 1$. This gives $b = \frac{4}{9}$. Hence

$$\begin{aligned} [\sqrt{r}]_\infty &= 0 \\ \alpha_\infty^+ &= \frac{1}{2} + \sqrt{1 + 4b} = \frac{4}{3} \\ \alpha_\infty^- &= \frac{1}{2} - \sqrt{1 + 4b} = -\frac{1}{3} \end{aligned}$$

The following table summarizes the findings so far for poles and for the order of r at ∞ where r is

$$r = \frac{4}{9x^2}$$

pole c location	pole order	$[\sqrt{r}]_c$	α_c^+	α_c^-
0	2	0	$\frac{4}{3}$	$-\frac{1}{3}$

Order of r at ∞	$[\sqrt{r}]_\infty$	α_∞^+	α_∞^-
2	0	$\frac{4}{3}$	$-\frac{1}{3}$

Now that the all $[\sqrt{r}]_c$ and its associated α_c^\pm have been determined for all the poles in the set Γ and $[\sqrt{r}]_\infty$ and its associated α_∞^\pm have also been found, the next step is to determine possible non negative integer d from these using

$$d = \alpha_\infty^{s(\infty)} - \sum_{c \in \Gamma} \alpha_c^{s(c)}$$

Where $s(c)$ is either $+$ or $-$ and $s(\infty)$ is the sign of α_∞^\pm . This is done by trial over all set of families $s = (s(c))_{c \in \Gamma \cup \infty}$ until such d is found to work in finding candidate ω .

Trying $\alpha_{\infty}^{-} = -\frac{1}{3}$ then

$$\begin{aligned} d &= \alpha_{\infty}^{-} - (\alpha_{c_1}^{-}) \\ &= -\frac{1}{3} - \left(-\frac{1}{3}\right) \\ &= 0 \end{aligned}$$

Since d an integer and $d \geq 0$ then it can be used to find ω using

$$\omega = \sum_{c \in \Gamma} \left(s(c)[\sqrt{r}]_c + \frac{\alpha_c^{s(c)}}{x - c} \right) + s(\infty)[\sqrt{r}]_{\infty}$$

The above gives

$$\begin{aligned} \omega &= \left((-)[\sqrt{r}]_{c_1} + \frac{\alpha_{c_1}^{-}}{x - c_1} \right) + (-)[\sqrt{r}]_{\infty} \\ &= -\frac{1}{3x} + (-)(0) \\ &= -\frac{1}{3x} \\ &= -\frac{1}{3x} \end{aligned}$$

Now that ω is determined, the next step is find a corresponding minimal polynomial $p(x)$ of degree $d = 0$ to solve the ode. The polynomial $p(x)$ needs to satisfy the equation

$$p'' + 2\omega p' + (\omega' + \omega^2 - r)p = 0 \quad (1A)$$

Let

$$p(x) = 1 \quad (2A)$$

Substituting the above in eq. (1A) gives

$$\begin{aligned} (0) + 2\left(-\frac{1}{3x}\right)(0) + \left(\left(\frac{1}{3x^2}\right) + \left(-\frac{1}{3x}\right)^2 - \left(\frac{4}{9x^2}\right)\right) &= 0 \\ 0 &= 0 \end{aligned}$$

The equation is satisfied since both sides are zero. Therefore the first solution to the ode $z'' = rz$ is

$$\begin{aligned} z_1(x) &= pe^{\int \omega dx} \\ &= e^{\int -\frac{1}{3x} dx} \\ &= \frac{1}{x^{\frac{1}{3}}} \end{aligned}$$

The first solution to the original ode in y is found from

$$\begin{aligned}y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\&= z_1 e^{-\int \frac{1}{2} \frac{-4x}{3x^2} dx} \\&= z_1 e^{\frac{2 \ln(x)}{3}} \\&= z_1 \left(x^{\frac{2}{3}} \right)\end{aligned}$$

Which simplifies to

$$y_1 = x^{\frac{1}{3}}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{-4x}{3x^2} dx}}{(y_1)^2} dx \\&= y_1 \int \frac{e^{\frac{4 \ln(x)}{3}}}{(y_1)^2} dx \\&= y_1 \left(\frac{3x^{\frac{5}{3}}}{5} \right)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\&= c_1 \left(x^{\frac{1}{3}} \right) + c_2 \left(x^{\frac{1}{3}} \left(\frac{3x^{\frac{5}{3}}}{5} \right) \right)\end{aligned}$$

Summary

The solution(s) found are the following

$$y = x^{\frac{1}{3}} c_1 + \frac{3c_2 x^2}{5} \tag{1}$$

Verification of solutions

$$y = x^{\frac{1}{3}}c_1 + \frac{3c_2x^2}{5}$$

Verified OK.

13.7.6 Maple step by step solution

Let's solve

$$3y''x^2 - 4y'x + 2y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = \frac{4y'}{3x} - \frac{2y}{3x^2}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' - \frac{4y'}{3x} + \frac{2y}{3x^2} = 0$$

- Multiply by denominators of the ODE

$$3y''x^2 - 4y'x + 2y = 0$$

- Make a change of variables

$$t = \ln(x)$$

- Substitute the change of variables back into the ODE

- Calculate the 1st derivative of y with respect to x , using the chain rule

$$y' = \left(\frac{d}{dt}y(t)\right) t'(x)$$

- Compute derivative

$$y' = \frac{\frac{d}{dt}y(t)}{x}$$

- Calculate the 2nd derivative of y with respect to x , using the chain rule

$$y'' = \left(\frac{d^2}{dt^2}y(t)\right) t'(x)^2 + t''(x) \left(\frac{d}{dt}y(t)\right)$$

- Compute derivative

$$y'' = \frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2}$$

Substitute the change of variables back into the ODE

$$3\left(\frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2}\right) x^2 - 4\frac{d}{dt}y(t) + 2y(t) = 0$$

- Simplify

$$3 \frac{d^2}{dt^2} y(t) - 7 \frac{d}{dt} y(t) + 2y(t) = 0$$
- Isolate 2nd derivative

$$\frac{d^2}{dt^2} y(t) = \frac{7 \frac{d}{dt} y(t)}{3} - \frac{2y(t)}{3}$$
- Group terms with $y(t)$ on the lhs of the ODE and the rest on the rhs of the ODE; ODE is lin

$$\frac{d^2}{dt^2} y(t) - \frac{7 \frac{d}{dt} y(t)}{3} + \frac{2y(t)}{3} = 0$$
- Characteristic polynomial of ODE

$$r^2 - \frac{7}{3}r + \frac{2}{3} = 0$$
- Factor the characteristic polynomial

$$\frac{(3r-1)(r-2)}{3} = 0$$
- Roots of the characteristic polynomial

$$r = \left(2, \frac{1}{3}\right)$$
- 1st solution of the ODE

$$y_1(t) = e^{2t}$$
- 2nd solution of the ODE

$$y_2(t) = e^{\frac{t}{3}}$$
- General solution of the ODE

$$y(t) = c_1 y_1(t) + c_2 y_2(t)$$
- Substitute in solutions

$$y(t) = c_1 e^{2t} + c_2 e^{\frac{t}{3}}$$
- Change variables back using $t = \ln(x)$

$$y = c_1 x^2 + c_2 x^{\frac{1}{3}}$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
<- LODE of Euler type successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 15

```
dsolve(3*x^2*diff(y(x),x$2)-4*x*diff(y(x),x)+2*y(x)=0,y(x), singsol=all)
```

$$y(x) = c_1x^2 + c_2x^{\frac{1}{3}}$$

✓ Solution by Mathematica

Time used: 0.015 (sec). Leaf size: 20

```
DSolve[3*x^2*y'[x]-4*x*y'[x]+2*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow c_2x^2 + c_1\sqrt[3]{x}$$

13.8 problem 8

13.8.1 Solving as second order euler ode ode	3359
13.8.2 Solving as second order change of variable on x method 2 ode .	3361
13.8.3 Solving as second order change of variable on x method 1 ode .	3363
13.8.4 Solving as second order change of variable on y method 2 ode .	3365
13.8.5 Solving using Kovacic algorithm	3368
13.8.6 Maple step by step solution	3373

Internal problem ID [11862]

Internal file name [OUTPUT/11871_Saturday_April_13_2024_01_13_20_AM_491032/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.5. The Cauchy-Euler Equation. Exercises page 169

Problem number: 8.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_euler_ode", "second_order_change_of_variable_on_x_method_1", "second_order_change_of_variable_on_x_method_2", "second_order_change_of_variable_on_y_method_2"

Maple gives the following as the ode type

```
[[_Emden, _Fowler], [_2nd_order, _linear, `_with_symmetry_[0,F(x)]`]]
```

$$x^2y'' + y'x + 9y = 0$$

13.8.1 Solving as second order euler ode ode

This is Euler second order ODE. Let the solution be $y = x^r$, then $y' = rx^{r-1}$ and $y'' = r(r-1)x^{r-2}$. Substituting these back into the given ODE gives

$$x^2(r(r-1))x^{r-2} + xrx^{r-1} + 9x^r = 0$$

Simplifying gives

$$r(r-1)x^r + rx^r + 9x^r = 0$$

Since $x^r \neq 0$ then dividing throughout by x^r gives

$$r(r - 1) + r + 9 = 0$$

Or

$$r^2 + 9 = 0 \tag{1}$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = -3i$$

$$r_2 = 3i$$

The roots are complex conjugate of each others. Let the roots be

$$r_1 = \alpha + i\beta$$

$$r_2 = \alpha - i\beta$$

Where in this case $\alpha = 0$ and $\beta = -3$. Hence the solution becomes

$$\begin{aligned} y &= c_1 x^{r_1} + c_2 x^{r_2} \\ &= c_1 x^{\alpha+i\beta} + c_2 x^{\alpha-i\beta} \\ &= x^\alpha (c_1 x^{i\beta} + c_2 x^{-i\beta}) \\ &= x^\alpha (c_1 e^{\ln(x^{i\beta})} + c_2 e^{\ln(x^{-i\beta})}) \\ &= x^\alpha (c_1 e^{i(\beta \ln x)} + c_2 e^{-i(\beta \ln x)}) \end{aligned}$$

Using the values for $\alpha = 0, \beta = -3$, the above becomes

$$y = x^0 (c_1 e^{-3i \ln(x)} + c_2 e^{3i \ln(x)})$$

Using Euler relation, the expression $c_1 e^{iA} + c_2 e^{-iA}$ is transformed to $c_1 \cos A + c_1 \sin A$ where the constants are free to change. Applying this to the above result gives

$$y = c_1 \cos(3 \ln(x)) + c_2 \sin(3 \ln(x))$$

Summary

The solution(s) found are the following

$$y = c_1 \cos(3 \ln(x)) + c_2 \sin(3 \ln(x)) \tag{1}$$

Verification of solutions

$$y = c_1 \cos(3 \ln(x)) + c_2 \sin(3 \ln(x))$$

Verified OK.

13.8.2 Solving as second order change of variable on x method 2 ode

In normal form the ode

$$x^2 y'' + y' x + 9y = 0 \quad (1)$$

Becomes

$$y'' + p(x) y' + q(x) y = 0 \quad (2)$$

Where

$$p(x) = \frac{1}{x}$$
$$q(x) = \frac{9}{x^2}$$

Applying change of variables $\tau = g(x)$ to (2) gives

$$\frac{d^2}{d\tau^2} y(\tau) + p_1 \left(\frac{d}{d\tau} y(\tau) \right) + q_1 y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x) \tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $p_1 = 0$. Eq (4) simplifies to

$$\tau''(x) + p(x) \tau'(x) = 0$$

This ode is solved resulting in

$$\begin{aligned} \tau &= \int e^{-(\int p(x) dx)} dx \\ &= \int e^{-(\int \frac{1}{x} dx)} dx \\ &= \int e^{-\ln(x)} dx \\ &= \int \frac{1}{x} dx \\ &= \ln(x) \end{aligned} \quad (6)$$

Using (6) to evaluate q_1 from (5) gives

$$\begin{aligned} q_1(\tau) &= \frac{q(x)}{\tau'(x)^2} \\ &= \frac{\frac{9}{x^2}}{\frac{1}{x^2}} \\ &= 9 \end{aligned} \tag{7}$$

Substituting the above in (3) and noting that now $p_1 = 0$ results in

$$\begin{aligned} \frac{d^2}{d\tau^2}y(\tau) + q_1y(\tau) &= 0 \\ \frac{d^2}{d\tau^2}y(\tau) + 9y(\tau) &= 0 \end{aligned}$$

The above ode is now solved for $y(\tau)$. This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(\tau) + By'(\tau) + Cy(\tau) = 0$$

Where in the above $A = 1, B = 0, C = 9$. Let the solution be $y(\tau) = e^{\lambda\tau}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda\tau} + 9e^{\lambda\tau} = 0 \tag{1}$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda\tau}$ gives

$$\lambda^2 + 9 = 0 \tag{2}$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 0, C = 9$ into the above gives

$$\begin{aligned} \lambda_{1,2} &= \frac{0}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{0^2 - (4)(1)(9)} \\ &= \pm 3i \end{aligned}$$

Hence

$$\lambda_1 = +3i$$

$$\lambda_2 = -3i$$

Which simplifies to

$$\lambda_1 = 3i$$

$$\lambda_2 = -3i$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = 0$ and $\beta = 3$. Therefore the final solution, when using Euler relation, can be written as

$$y(\tau) = e^{\alpha\tau}(c_1 \cos(\beta\tau) + c_2 \sin(\beta\tau))$$

Which becomes

$$y(\tau) = e^0(c_1 \cos(3\tau) + c_2 \sin(3\tau))$$

Or

$$y(\tau) = c_1 \cos(3\tau) + c_2 \sin(3\tau)$$

The above solution is now transformed back to y using (6) which results in

$$y = c_1 \cos(3 \ln(x)) + c_2 \sin(3 \ln(x))$$

Summary

The solution(s) found are the following

$$y = c_1 \cos(3 \ln(x)) + c_2 \sin(3 \ln(x)) \quad (1)$$

Verification of solutions

$$y = c_1 \cos(3 \ln(x)) + c_2 \sin(3 \ln(x))$$

Verified OK.

13.8.3 Solving as second order change of variable on x method 1 ode

In normal form the ode

$$x^2 y'' + y' x + 9y = 0 \quad (1)$$

Becomes

$$y'' + p(x) y' + q(x) y = 0 \quad (2)$$

Where

$$p(x) = \frac{1}{x}$$

$$q(x) = \frac{9}{x^2}$$

Applying change of variables $\tau = g(x)$ to (2) results

$$\frac{d^2}{d\tau^2}y(\tau) + p_1\left(\frac{d}{d\tau}y(\tau)\right) + q_1y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $q_1 = c^2$ where c is some constant. Therefore from (5)

$$\tau' = \frac{1}{c}\sqrt{q}$$

$$= \frac{3\sqrt{\frac{1}{x^2}}}{c} \quad (6)$$

$$\tau'' = -\frac{3}{c\sqrt{\frac{1}{x^2}}x^3}$$

Substituting the above into (4) results in

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2}$$

$$= \frac{-\frac{3}{c\sqrt{\frac{1}{x^2}}x^3} + \frac{1}{x}\frac{3\sqrt{\frac{1}{x^2}}}{c}}{\left(\frac{3\sqrt{\frac{1}{x^2}}}{c}\right)^2}$$

$$= 0$$

Therefore ode (3) now becomes

$$y(\tau)'' + p_1y(\tau)' + q_1y(\tau) = 0$$

$$\frac{d^2}{d\tau^2}y(\tau) + c^2y(\tau) = 0 \quad (7)$$

The above ode is now solved for $y(\tau)$. Since the ode is now constant coefficients, it can be easily solved to give

$$y(\tau) = c_1 \cos(c\tau) + c_2 \sin(c\tau)$$

Now from (6)

$$\begin{aligned} \tau &= \int \frac{1}{c} \sqrt{q} dx \\ &= \frac{\int 3\sqrt{\frac{1}{x^2}} dx}{c} \\ &= \frac{3\sqrt{\frac{1}{x^2}} x \ln(x)}{c} \end{aligned}$$

Substituting the above into the solution obtained gives

$$y = c_1 \cos(3 \ln(x)) + c_2 \sin(3 \ln(x))$$

Summary

The solution(s) found are the following

$$y = c_1 \cos(3 \ln(x)) + c_2 \sin(3 \ln(x)) \quad (1)$$

Verification of solutions

$$y = c_1 \cos(3 \ln(x)) + c_2 \sin(3 \ln(x))$$

Verified OK.

13.8.4 Solving as second order change of variable on y method 2 ode

In normal form the ode

$$x^2 y'' + y' x + 9y = 0 \quad (1)$$

Becomes

$$y'' + p(x) y' + q(x) y = 0 \quad (2)$$

Where

$$\begin{aligned} p(x) &= \frac{1}{x} \\ q(x) &= \frac{9}{x^2} \end{aligned}$$

Applying change of variables on the dependent variable $y = v(x)x^n$ to (2) gives the following ode where the dependent variables is $v(x)$ and not y .

$$v''(x) + \left(\frac{2n}{x} + p\right)v'(x) + \left(\frac{n(n-1)}{x^2} + \frac{np}{x} + q\right)v(x) = 0 \quad (3)$$

Let the coefficient of $v(x)$ above be zero. Hence

$$\frac{n(n-1)}{x^2} + \frac{np}{x} + q = 0 \quad (4)$$

Substituting the earlier values found for $p(x)$ and $q(x)$ into (4) gives

$$\frac{n(n-1)}{x^2} + \frac{n}{x^2} + \frac{9}{x^2} = 0 \quad (5)$$

Solving (5) for n gives

$$n = 3i \quad (6)$$

Substituting this value in (3) gives

$$\begin{aligned} v''(x) + \left(\frac{6i}{x} + \frac{1}{x}\right)v'(x) &= 0 \\ v''(x) + \frac{(1+6i)v'(x)}{x} &= 0 \end{aligned} \quad (7)$$

Using the substitution

$$u(x) = v'(x)$$

Then (7) becomes

$$u'(x) + \frac{(1+6i)u(x)}{x} = 0 \quad (8)$$

The above is now solved for $u(x)$. In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= \frac{(-1-6i)u}{x} \end{aligned}$$

Where $f(x) = \frac{-1-6i}{x}$ and $g(u) = u$. Integrating both sides gives

$$\begin{aligned}\frac{1}{u} du &= \frac{-1-6i}{x} dx \\ \int \frac{1}{u} du &= \int \frac{-1-6i}{x} dx \\ \ln(u) &= (-1-6i) \ln(x) + c_1 \\ u &= e^{(-1-6i) \ln(x) + c_1} \\ &= c_1 e^{(-1-6i) \ln(x)}\end{aligned}$$

Which simplifies to

$$u(x) = \frac{c_1 x^{-6i}}{x}$$

Now that $u(x)$ is known, then

$$\begin{aligned}v'(x) &= u(x) \\ v(x) &= \int u(x) dx + c_2 \\ &= \frac{ic_1 x^{-6i}}{6} + c_2\end{aligned}$$

Hence

$$\begin{aligned}y &= v(x) x^n \\ &= \left(\frac{ic_1 x^{-6i}}{6} + c_2 \right) x^{3i} \\ &= x^{3i} c_2 + \frac{ix^{-3i} c_1}{6}\end{aligned}$$

Summary

The solution(s) found are the following

$$y = \left(\frac{ic_1 x^{-6i}}{6} + c_2 \right) x^{3i} \tag{1}$$

Verification of solutions

$$y = \left(\frac{ic_1 x^{-6i}}{6} + c_2 \right) x^{3i}$$

Verified OK.

13.8.5 Solving using Kovacic algorithm

Writing the ode as

$$x^2 y'' + y'x + 9y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= x^2 \\ B &= x \\ C &= 9 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-37}{4x^2} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= -37 \\ t &= 4x^2 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = \left(-\frac{37}{4x^2} \right) z(x) \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 482: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 2 - 0 \\ &= 2 \end{aligned}$$

The poles of r in eq. (7) and the order of each pole are determined by solving for the roots of $t = 4x^2$. There is a pole at $x = 0$ of order 2. Since there is no odd order pole larger than 2 and the order at ∞ is 2 then the necessary conditions for case one are met. Since there is a pole of order 2 then necessary conditions for case two are met. Since pole order is not larger than 2 and the order at ∞ is 2 then the necessary conditions for case three are met. Therefore

$$L = [1, 2, 4, 6, 12]$$

Attempting to find a solution using case $n = 1$.

Looking at poles of order 2. The partial fractions decomposition of r is

$$r = -\frac{37}{4x^2}$$

For the pole at $x = 0$ let b be the coefficient of $\frac{1}{x^2}$ in the partial fractions decomposition of r given above. Therefore $b = -\frac{37}{4}$. Hence

$$\begin{aligned} [\sqrt{r}]_c &= 0 \\ \alpha_c^+ &= \frac{1}{2} + \sqrt{1 + 4b} = \frac{1}{2} + 3i \\ \alpha_c^- &= \frac{1}{2} - \sqrt{1 + 4b} = \frac{1}{2} - 3i \end{aligned}$$

Since the order of r at ∞ is 2 then $[\sqrt{r}]_\infty = 0$. Let b be the coefficient of $\frac{1}{x^2}$ in the Laurent series expansion of r at ∞ , which can be found by dividing the leading coefficient of s by the leading coefficient of t from

$$r = \frac{s}{t} = -\frac{37}{4x^2}$$

Since the $\gcd(s, t) = 1$. This gives $b = -\frac{37}{4}$. Hence

$$\begin{aligned} [\sqrt{r}]_\infty &= 0 \\ \alpha_\infty^+ &= \frac{1}{2} + \sqrt{1 + 4b} = \frac{1}{2} + 3i \\ \alpha_\infty^- &= \frac{1}{2} - \sqrt{1 + 4b} = \frac{1}{2} - 3i \end{aligned}$$

The following table summarizes the findings so far for poles and for the order of r at ∞ where r is

$$r = -\frac{37}{4x^2}$$

pole c location	pole order	$[\sqrt{r}]_c$	α_c^+	α_c^-
0	2	0	$\frac{1}{2} + 3i$	$\frac{1}{2} - 3i$

Order of r at ∞	$[\sqrt{r}]_\infty$	α_∞^+	α_∞^-
2	0	$\frac{1}{2} + 3i$	$\frac{1}{2} - 3i$

Now that the all $[\sqrt{r}]_c$ and its associated α_c^\pm have been determined for all the poles in the set Γ and $[\sqrt{r}]_\infty$ and its associated α_∞^\pm have also been found, the next step is to determine possible non negative integer d from these using

$$d = \alpha_\infty^{s(\infty)} - \sum_{c \in \Gamma} \alpha_c^{s(c)}$$

Where $s(c)$ is either $+$ or $-$ and $s(\infty)$ is the sign of α_∞^\pm . This is done by trial over all set of families $s = (s(c))_{c \in \Gamma \cup \infty}$ until such d is found to work in finding candidate ω .

Trying $\alpha_{\infty}^{-} = \frac{1}{2} - 3i$ then

$$\begin{aligned} d &= \alpha_{\infty}^{-} - (\alpha_{c_1}^{-}) \\ &= \frac{1}{2} - 3i - \left(\frac{1}{2} - 3i\right) \\ &= 0 \end{aligned}$$

Since d an integer and $d \geq 0$ then it can be used to find ω using

$$\omega = \sum_{c \in \Gamma} \left(s(c)[\sqrt{r}]_c + \frac{\alpha_c^{s(c)}}{x - c} \right) + s(\infty)[\sqrt{r}]_{\infty}$$

The above gives

$$\begin{aligned} \omega &= \left((-)[\sqrt{r}]_{c_1} + \frac{\alpha_{c_1}^{-}}{x - c_1} \right) + (-)[\sqrt{r}]_{\infty} \\ &= \frac{\frac{1}{2} - 3i}{x} + (-)(0) \\ &= \frac{\frac{1}{2} - 3i}{x} \\ &= \frac{\frac{1}{2} - 3i}{x} \end{aligned}$$

Now that ω is determined, the next step is find a corresponding minimal polynomial $p(x)$ of degree $d = 0$ to solve the ode. The polynomial $p(x)$ needs to satisfy the equation

$$p'' + 2\omega p' + (\omega' + \omega^2 - r)p = 0 \quad (1A)$$

Let

$$p(x) = 1 \quad (2A)$$

Substituting the above in eq. (1A) gives

$$\begin{aligned} (0) + 2\left(\frac{\frac{1}{2} - 3i}{x}\right)(0) + \left(\left(\frac{-\frac{1}{2} + 3i}{x^2}\right) + \left(\frac{\frac{1}{2} - 3i}{x}\right)^2 - \left(-\frac{37}{4x^2}\right)\right) &= 0 \\ 0 &= 0 \end{aligned}$$

The equation is satisfied since both sides are zero. Therefore the first solution to the ode $z'' = rz$ is

$$\begin{aligned} z_1(x) &= pe^{\int \omega dx} \\ &= e^{\int \frac{\frac{1}{2} - 3i}{x} dx} \\ &= x^{\frac{1}{2} - 3i} \end{aligned}$$

The first solution to the original ode in y is found from

$$\begin{aligned}y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\&= z_1 e^{-\int \frac{1}{2} \frac{x}{x^2} dx} \\&= z_1 e^{-\frac{\ln(x)}{2}} \\&= z_1 \left(\frac{1}{\sqrt{x}} \right)\end{aligned}$$

Which simplifies to

$$y_1 = x^{-3i}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{x}{x^2} dx}}{(y_1)^2} dx \\&= y_1 \int \frac{e^{-\ln(x)}}{(y_1)^2} dx \\&= y_1 \left(-\frac{ix^{6i}}{6} \right)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\&= c_1 (x^{-3i}) + c_2 \left(x^{-3i} \left(-\frac{ix^{6i}}{6} \right) \right)\end{aligned}$$

Summary

The solution(s) found are the following

$$y = x^{-3i} c_1 - \frac{ic_2 x^{3i}}{6} \tag{1}$$

Verification of solutions

$$y = x^{-3i} c_1 - \frac{ic_2 x^{3i}}{6}$$

Verified OK.

13.8.6 Maple step by step solution

Let's solve

$$y''x^2 + y'x + 9y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = -\frac{y'}{x} - \frac{9y}{x^2}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + \frac{y'}{x} + \frac{9y}{x^2} = 0$$

- Multiply by denominators of the ODE

$$y''x^2 + y'x + 9y = 0$$

- Make a change of variables

$$t = \ln(x)$$

- Substitute the change of variables back into the ODE

- Calculate the 1st derivative of y with respect to x , using the chain rule

$$y' = \left(\frac{d}{dt}y(t)\right) t'(x)$$

- Compute derivative

$$y' = \frac{\frac{d}{dt}y(t)}{x}$$

- Calculate the 2nd derivative of y with respect to x , using the chain rule

$$y'' = \left(\frac{d^2}{dt^2}y(t)\right) t'(x)^2 + t''(x) \left(\frac{d}{dt}y(t)\right)$$

- Compute derivative

$$y'' = \frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2}$$

Substitute the change of variables back into the ODE

$$\left(\frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2}\right) x^2 + \frac{d}{dt}y(t) + 9y(t) = 0$$

- Simplify

$$\frac{d^2}{dt^2}y(t) + 9y(t) = 0$$

- Characteristic polynomial of ODE

$$r^2 + 9 = 0$$

- Use quadratic formula to solve for r

$$r = \frac{0 \pm (\sqrt{-36})}{2}$$
- Roots of the characteristic polynomial

$$r = (-3I, 3I)$$
- 1st solution of the ODE

$$y_1(t) = \cos(3t)$$
- 2nd solution of the ODE

$$y_2(t) = \sin(3t)$$
- General solution of the ODE

$$y(t) = c_1 y_1(t) + c_2 y_2(t)$$
- Substitute in solutions

$$y(t) = c_1 \cos(3t) + c_2 \sin(3t)$$
- Change variables back using $t = \ln(x)$

$$y = c_1 \cos(3 \ln(x)) + c_2 \sin(3 \ln(x))$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
<- LODE of Euler type successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 19

```
dsolve(x^2*diff(y(x),x$2)+x*diff(y(x),x)+9*y(x)=0,y(x), singsol=all)
```

$$y(x) = c_1 \sin(3 \ln(x)) + c_2 \cos(3 \ln(x))$$

✓ Solution by Mathematica

Time used: 0.021 (sec). Leaf size: 22

```
DSolve[x^2*y''[x]+x*y'[x]+9*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow c_1 \cos(3 \log(x)) + c_2 \sin(3 \log(x))$$

13.9 problem 9

13.9.1 Solving as second order euler ode ode	3376
13.9.2 Solving as second order change of variable on x method 2 ode .	3377
13.9.3 Solving as second order change of variable on x method 1 ode .	3380
13.9.4 Solving as second order change of variable on y method 2 ode .	3382
13.9.5 Solving using Kovacic algorithm	3384
13.9.6 Maple step by step solution	3389

Internal problem ID [11863]

Internal file name [OUTPUT/11872_Saturday_April_13_2024_01_13_22_AM_68095640/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.5. The Cauchy-Euler Equation. Exercises page 169

Problem number: 9.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_euler_ode", "second_order_change_of_variable_on_x_method_1", "second_order_change_of_variable_on_x_method_2", "second_order_change_of_variable_on_y_method_2"

Maple gives the following as the ode type

```
[[_Emden, _Fowler], [_2nd_order, _linear, `_with_symmetry_[0,F(x)]`]]
```

$$9x^2y'' + 3y'x + y = 0$$

13.9.1 Solving as second order euler ode ode

This is Euler second order ODE. Let the solution be $y = x^r$, then $y' = rx^{r-1}$ and $y'' = r(r-1)x^{r-2}$. Substituting these back into the given ODE gives

$$9x^2(r(r-1))x^{r-2} + 3rx^{r-1} + x^r = 0$$

Simplifying gives

$$9r(r-1)x^r + 3rx^r + x^r = 0$$

Since $x^r \neq 0$ then dividing throughout by x^r gives

$$9r(r - 1) + 3r + 1 = 0$$

Or

$$9r^2 - 6r + 1 = 0 \quad (1)$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = \frac{1}{3}$$
$$r_2 = \frac{1}{3}$$

Since the roots are equal, then the general solution is

$$y = c_1 y_1 + c_2 y_2$$

Where $y_1 = x^r$ and $y_2 = x^r \ln(x)$. Hence

$$y = x^{\frac{1}{3}} c_1 + c_2 x^{\frac{1}{3}} \ln(x)$$

Summary

The solution(s) found are the following

$$y = x^{\frac{1}{3}} c_1 + c_2 x^{\frac{1}{3}} \ln(x) \quad (1)$$

Verification of solutions

$$y = x^{\frac{1}{3}} c_1 + c_2 x^{\frac{1}{3}} \ln(x)$$

Verified OK.

13.9.2 Solving as second order change of variable on x method 2 ode

In normal form the ode

$$9x^2 y'' + 3y'x + y = 0 \quad (1)$$

Becomes

$$y'' + p(x) y' + q(x) y = 0 \quad (2)$$

Where

$$p(x) = \frac{1}{3x}$$
$$q(x) = \frac{1}{9x^2}$$

Applying change of variables $\tau = g(x)$ to (2) gives

$$\frac{d^2}{d\tau^2}y(\tau) + p_1\left(\frac{d}{d\tau}y(\tau)\right) + q_1y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $p_1 = 0$. Eq (4) simplifies to

$$\tau''(x) + p(x)\tau'(x) = 0$$

This ode is solved resulting in

$$\begin{aligned} \tau &= \int e^{-(\int p(x)dx)} dx \\ &= \int e^{-(\int \frac{1}{3x} dx)} dx \\ &= \int e^{-\frac{\ln(x)}{3}} dx \\ &= \int \frac{1}{x^{\frac{1}{3}}} dx \\ &= \frac{3x^{\frac{2}{3}}}{2} \end{aligned} \quad (6)$$

Using (6) to evaluate q_1 from (5) gives

$$\begin{aligned} q_1(\tau) &= \frac{q(x)}{\tau'(x)^2} \\ &= \frac{\frac{1}{9x^2}}{\frac{1}{x^{\frac{2}{3}}}} \\ &= \frac{1}{9x^{\frac{4}{3}}} \end{aligned} \quad (7)$$

Substituting the above in (3) and noting that now $p_1 = 0$ results in

$$\begin{aligned} \frac{d^2}{d\tau^2}y(\tau) + q_1y(\tau) &= 0 \\ \frac{d^2}{d\tau^2}y(\tau) + \frac{y(\tau)}{9x^{\frac{4}{3}}} &= 0 \end{aligned}$$

But in terms of τ

$$\frac{1}{9x^{\frac{4}{3}}} = \frac{1}{4\tau^2}$$

Hence the above ode becomes

$$\frac{d^2}{d\tau^2}y(\tau) + \frac{y(\tau)}{4\tau^2} = 0$$

The above ode is now solved for $y(\tau)$. The ode can be written as

$$4\left(\frac{d^2}{d\tau^2}y(\tau)\right)\tau^2 + y(\tau) = 0$$

Which shows it is a Euler ODE. This is Euler second order ODE. Let the solution be $y(\tau) = \tau^r$, then $y' = r\tau^{r-1}$ and $y'' = r(r-1)\tau^{r-2}$. Substituting these back into the given ODE gives

$$4\tau^2(r(r-1))\tau^{r-2} + 0r\tau^{r-1} + \tau^r = 0$$

Simplifying gives

$$4r(r-1)\tau^r + 0\tau^r + \tau^r = 0$$

Since $\tau^r \neq 0$ then dividing throughout by τ^r gives

$$4r(r-1) + 0 + 1 = 0$$

Or

$$4r^2 - 4r + 1 = 0 \tag{1}$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = \frac{1}{2}$$

$$r_2 = \frac{1}{2}$$

Since the roots are equal, then the general solution is

$$y(\tau) = c_1y_1 + c_2y_2$$

Where $y_1 = \tau^r$ and $y_2 = \tau^r \ln(\tau)$. Hence

$$y(\tau) = c_1\sqrt{\tau} + c_2\sqrt{\tau} \ln(\tau)$$

The above solution is now transformed back to y using (6) which results in

$$y = \frac{\sqrt{6}x^{\frac{1}{3}}(2\ln(x)c_2 - 3c_2\ln(2) + 3c_2\ln(3) + 3c_1)}{6}$$

Summary

The solution(s) found are the following

$$y = \frac{\sqrt{6} x^{\frac{1}{3}} (2 \ln(x) c_2 - 3c_2 \ln(2) + 3c_2 \ln(3) + 3c_1)}{6} \quad (1)$$

Verification of solutions

$$y = \frac{\sqrt{6} x^{\frac{1}{3}} (2 \ln(x) c_2 - 3c_2 \ln(2) + 3c_2 \ln(3) + 3c_1)}{6}$$

Verified OK.

13.9.3 Solving as second order change of variable on x method 1 ode

In normal form the ode

$$9x^2 y'' + 3y'x + y = 0 \quad (1)$$

Becomes

$$y'' + p(x) y' + q(x) y = 0 \quad (2)$$

Where

$$p(x) = \frac{1}{3x}$$
$$q(x) = \frac{1}{9x^2}$$

Applying change of variables $\tau = g(x)$ to (2) results

$$\frac{d^2}{d\tau^2} y(\tau) + p_1 \left(\frac{d}{d\tau} y(\tau) \right) + q_1 y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x) \tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $q_1 = c^2$ where c is some constant. Therefore from (5)

$$\tau' = \frac{1}{c} \sqrt{q}$$
$$= \frac{\sqrt{\frac{1}{x^2}}}{3c} \quad (6)$$
$$\tau'' = -\frac{1}{3c \sqrt{\frac{1}{x^2}} x^3}$$

Substituting the above into (4) results in

$$\begin{aligned}
 p_1(\tau) &= \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \\
 &= \frac{-\frac{1}{3c\sqrt{\frac{1}{x^2}}x^3} + \frac{1}{3x}\frac{\sqrt{\frac{1}{x^2}}}{3c}}{\left(\frac{\sqrt{\frac{1}{x^2}}}{3c}\right)^2} \\
 &= -2c
 \end{aligned}$$

Therefore ode (3) now becomes

$$\begin{aligned}
 y(\tau)'' + p_1y(\tau)' + q_1y(\tau) &= 0 \\
 \frac{d^2}{d\tau^2}y(\tau) - 2c\left(\frac{d}{d\tau}y(\tau)\right) + c^2y(\tau) &= 0 \tag{7}
 \end{aligned}$$

The above ode is now solved for $y(\tau)$. Since the ode is now constant coefficients, it can be easily solved to give

$$y(\tau) = e^{c\tau}c_1$$

Now from (6)

$$\begin{aligned}
 \tau &= \int \frac{1}{c}\sqrt{q} dx \\
 &= \frac{\int \frac{\sqrt{\frac{1}{x^2}}}{3} dx}{c} \\
 &= \frac{\sqrt{\frac{1}{x^2}} x \ln(x)}{3c}
 \end{aligned}$$

Substituting the above into the solution obtained gives

$$y = x^{\frac{1}{3}}c_1$$

Summary

The solution(s) found are the following

$$y = x^{\frac{1}{3}}c_1 \tag{1}$$

Verification of solutions

$$y = x^{\frac{1}{3}}c_1$$

Verified OK.

13.9.4 Solving as second order change of variable on y method 2 ode

In normal form the ode

$$9x^2y'' + 3y'x + y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = \frac{1}{3x}$$
$$q(x) = \frac{1}{9x^2}$$

Applying change of variables on the dependent variable $y = v(x)x^n$ to (2) gives the following ode where the dependent variable is $v(x)$ and not y .

$$v''(x) + \left(\frac{2n}{x} + p\right)v'(x) + \left(\frac{n(n-1)}{x^2} + \frac{np}{x} + q\right)v(x) = 0 \quad (3)$$

Let the coefficient of $v(x)$ above be zero. Hence

$$\frac{n(n-1)}{x^2} + \frac{np}{x} + q = 0 \quad (4)$$

Substituting the earlier values found for $p(x)$ and $q(x)$ into (4) gives

$$\frac{n(n-1)}{x^2} + \frac{n}{3x^2} + \frac{1}{9x^2} = 0 \quad (5)$$

Solving (5) for n gives

$$n = \frac{1}{3} \quad (6)$$

Substituting this value in (3) gives

$$v''(x) + \frac{v'(x)}{x} = 0$$
$$v''(x) + \frac{v'(x)}{x} = 0 \quad (7)$$

Using the substitution

$$u(x) = v'(x)$$

Then (7) becomes

$$u'(x) + \frac{u(x)}{x} = 0 \quad (8)$$

The above is now solved for $u(x)$. In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= -\frac{u}{x} \end{aligned}$$

Where $f(x) = -\frac{1}{x}$ and $g(u) = u$. Integrating both sides gives

$$\begin{aligned} \frac{1}{u} du &= -\frac{1}{x} dx \\ \int \frac{1}{u} du &= \int -\frac{1}{x} dx \\ \ln(u) &= -\ln(x) + c_1 \\ u &= e^{-\ln(x)+c_1} \\ &= \frac{c_1}{x} \end{aligned}$$

Now that $u(x)$ is known, then

$$\begin{aligned} v'(x) &= u(x) \\ v(x) &= \int u(x) dx + c_2 \\ &= c_1 \ln(x) + c_2 \end{aligned}$$

Hence

$$\begin{aligned} y &= v(x) x^n \\ &= (c_1 \ln(x) + c_2) x^{\frac{1}{3}} \\ &= (c_1 \ln(x) + c_2) x^{\frac{1}{3}} \end{aligned}$$

Summary

The solution(s) found are the following

$$y = (c_1 \ln(x) + c_2) x^{\frac{1}{3}} \quad (1)$$

Verification of solutions

$$y = (c_1 \ln(x) + c_2) x^{\frac{1}{3}}$$

Verified OK.

13.9.5 Solving using Kovacic algorithm

Writing the ode as

$$9x^2y'' + 3y'x + y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= 9x^2 \\ B &= 3x \\ C &= 1 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-1}{4x^2} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= -1 \\ t &= 4x^2 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = \left(-\frac{1}{4x^2}\right) z(x) \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 484: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 2 - 0 \\ &= 2 \end{aligned}$$

The poles of r in eq. (7) and the order of each pole are determined by solving for the roots of $t = 4x^2$. There is a pole at $x = 0$ of order 2. Since there is no odd order pole larger than 2 and the order at ∞ is 2 then the necessary conditions for case one are met. Since there is a pole of order 2 then necessary conditions for case two are met. Since pole order is not larger than 2 and the order at ∞ is 2 then the necessary conditions for case three are met. Therefore

$$L = [1, 2, 4, 6, 12]$$

Attempting to find a solution using case $n = 1$.

Looking at poles of order 2. The partial fractions decomposition of r is

$$r = -\frac{1}{4x^2}$$

For the pole at $x = 0$ let b be the coefficient of $\frac{1}{x^2}$ in the partial fractions decomposition of r given above. Therefore $b = -\frac{1}{4}$. Hence

$$\begin{aligned} [\sqrt{r}]_c &= 0 \\ \alpha_c^+ &= \frac{1}{2} + \sqrt{1 + 4b} = \frac{1}{2} \\ \alpha_c^- &= \frac{1}{2} - \sqrt{1 + 4b} = \frac{1}{2} \end{aligned}$$

Since the order of r at ∞ is 2 then $[\sqrt{r}]_\infty = 0$. Let b be the coefficient of $\frac{1}{x^2}$ in the Laurent series expansion of r at ∞ , which can be found by dividing the leading coefficient of s by the leading coefficient of t from

$$r = \frac{s}{t} = -\frac{1}{4x^2}$$

Since the $\gcd(s, t) = 1$. This gives $b = -\frac{1}{4}$. Hence

$$\begin{aligned} [\sqrt{r}]_\infty &= 0 \\ \alpha_\infty^+ &= \frac{1}{2} + \sqrt{1 + 4b} = \frac{1}{2} \\ \alpha_\infty^- &= \frac{1}{2} - \sqrt{1 + 4b} = \frac{1}{2} \end{aligned}$$

The following table summarizes the findings so far for poles and for the order of r at ∞ where r is

$$r = -\frac{1}{4x^2}$$

pole c location	pole order	$[\sqrt{r}]_c$	α_c^+	α_c^-
0	2	0	$\frac{1}{2}$	$\frac{1}{2}$

Order of r at ∞	$[\sqrt{r}]_\infty$	α_∞^+	α_∞^-
2	0	$\frac{1}{2}$	$\frac{1}{2}$

Now that the all $[\sqrt{r}]_c$ and its associated α_c^\pm have been determined for all the poles in the set Γ and $[\sqrt{r}]_\infty$ and its associated α_∞^\pm have also been found, the next step is to determine possible non negative integer d from these using

$$d = \alpha_\infty^{s(\infty)} - \sum_{c \in \Gamma} \alpha_c^{s(c)}$$

Where $s(c)$ is either $+$ or $-$ and $s(\infty)$ is the sign of α_∞^\pm . This is done by trial over all set of families $s = (s(c))_{c \in \Gamma \cup \infty}$ until such d is found to work in finding candidate ω .

Trying $\alpha_{\infty}^{-} = \frac{1}{2}$ then

$$\begin{aligned} d &= \alpha_{\infty}^{-} - (\alpha_{c_1}^{-}) \\ &= \frac{1}{2} - \left(\frac{1}{2}\right) \\ &= 0 \end{aligned}$$

Since d an integer and $d \geq 0$ then it can be used to find ω using

$$\omega = \sum_{c \in \Gamma} \left(s(c)[\sqrt{r}]_c + \frac{\alpha_c^{s(c)}}{x - c} \right) + s(\infty)[\sqrt{r}]_{\infty}$$

The above gives

$$\begin{aligned} \omega &= \left((-)[\sqrt{r}]_{c_1} + \frac{\alpha_{c_1}^{-}}{x - c_1} \right) + (-)[\sqrt{r}]_{\infty} \\ &= \frac{1}{2x} + (-)(0) \\ &= \frac{1}{2x} \\ &= \frac{1}{2x} \end{aligned}$$

Now that ω is determined, the next step is find a corresponding minimal polynomial $p(x)$ of degree $d = 0$ to solve the ode. The polynomial $p(x)$ needs to satisfy the equation

$$p'' + 2\omega p' + (\omega' + \omega^2 - r)p = 0 \quad (1A)$$

Let

$$p(x) = 1 \quad (2A)$$

Substituting the above in eq. (1A) gives

$$\begin{aligned} (0) + 2\left(\frac{1}{2x}\right)(0) + \left(\left(-\frac{1}{2x^2}\right) + \left(\frac{1}{2x}\right)^2 - \left(-\frac{1}{4x^2}\right) \right) &= 0 \\ 0 &= 0 \end{aligned}$$

The equation is satisfied since both sides are zero. Therefore the first solution to the ode $z'' = rz$ is

$$\begin{aligned} z_1(x) &= p e^{\int \omega dx} \\ &= e^{\int \frac{1}{2x} dx} \\ &= \sqrt{x} \end{aligned}$$

The first solution to the original ode in y is found from

$$\begin{aligned}y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\&= z_1 e^{-\int \frac{1}{2} \frac{3x}{9x^2} dx} \\&= z_1 e^{-\frac{\ln(x)}{6}} \\&= z_1 \left(\frac{1}{x^{\frac{1}{6}}} \right)\end{aligned}$$

Which simplifies to

$$y_1 = x^{\frac{1}{3}}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{3x}{9x^2} dx}}{(y_1)^2} dx \\&= y_1 \int \frac{e^{-\frac{\ln(x)}{3}}}{(y_1)^2} dx \\&= y_1 (\ln(x))\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\&= c_1 \left(x^{\frac{1}{3}} \right) + c_2 \left(x^{\frac{1}{3}} (\ln(x)) \right)\end{aligned}$$

Summary

The solution(s) found are the following

$$y = x^{\frac{1}{3}} c_1 + c_2 x^{\frac{1}{3}} \ln(x) \tag{1}$$

Verification of solutions

$$y = x^{\frac{1}{3}} c_1 + c_2 x^{\frac{1}{3}} \ln(x)$$

Verified OK.

13.9.6 Maple step by step solution

Let's solve

$$9y''x^2 + 3y'x + y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = -\frac{y'}{3x} - \frac{y}{9x^2}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + \frac{y'}{3x} + \frac{y}{9x^2} = 0$$

- Multiply by denominators of the ODE

$$9y''x^2 + 3y'x + y = 0$$

- Make a change of variables

$$t = \ln(x)$$

- Substitute the change of variables back into the ODE

- Calculate the 1st derivative of y with respect to x , using the chain rule

$$y' = \left(\frac{d}{dt}y(t)\right) t'(x)$$

- Compute derivative

$$y' = \frac{\frac{d}{dt}y(t)}{x}$$

- Calculate the 2nd derivative of y with respect to x , using the chain rule

$$y'' = \left(\frac{d^2}{dt^2}y(t)\right) t'(x)^2 + t''(x) \left(\frac{d}{dt}y(t)\right)$$

- Compute derivative

$$y'' = \frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2}$$

Substitute the change of variables back into the ODE

$$9\left(\frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2}\right) x^2 + 3\frac{d}{dt}y(t) + y(t) = 0$$

- Simplify

$$9\frac{d^2}{dt^2}y(t) - 6\frac{d}{dt}y(t) + y(t) = 0$$

- Isolate 2nd derivative

$$\frac{d^2}{dt^2}y(t) = \frac{2\frac{d}{dt}y(t)}{3} - \frac{y(t)}{9}$$

- Group terms with $y(t)$ on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$\frac{d^2}{dt^2}y(t) - \frac{2\frac{d}{dt}y(t)}{3} + \frac{y(t)}{9} = 0$$

- Characteristic polynomial of ODE

$$r^2 - \frac{2}{3}r + \frac{1}{9} = 0$$

- Factor the characteristic polynomial

$$\frac{(3r-1)^2}{9} = 0$$

- Root of the characteristic polynomial

$$r = \frac{1}{3}$$

- 1st solution of the ODE

$$y_1(t) = e^{\frac{t}{3}}$$

- Repeated root, multiply $y_1(t)$ by t to ensure linear independence

$$y_2(t) = t e^{\frac{t}{3}}$$

- General solution of the ODE

$$y(t) = c_1 y_1(t) + c_2 y_2(t)$$

- Substitute in solutions

$$y(t) = c_1 e^{\frac{t}{3}} + c_2 t e^{\frac{t}{3}}$$

- Change variables back using $t = \ln(x)$

$$y = x^{\frac{1}{3}} c_1 + c_2 x^{\frac{1}{3}} \ln(x)$$

- Simplify

$$y = (c_1 + \ln(x) c_2) x^{\frac{1}{3}}$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
<- LODE of Euler type successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 14

```
dsolve(9*x^2*diff(y(x),x$2)+3*x*diff(y(x),x)+y(x)=0,y(x), singsol=all)
```

$$y(x) = (c_1 + c_2 \ln(x)) x^{\frac{1}{3}}$$

✓ Solution by Mathematica

Time used: 0.017 (sec). Leaf size: 24

```
DSolve[9*x^2*y''[x]+3*x*y'[x]+y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{1}{3} \sqrt[3]{x} (c_2 \log(x) + 3c_1)$$

13.10 problem 10

13.10.1 Solving as second order euler ode ode	3392
13.10.2 Solving as second order change of variable on x method 2 ode .	3394
13.10.3 Solving as second order change of variable on x method 1 ode .	3397
13.10.4 Solving as second order change of variable on y method 2 ode .	3399
13.10.5 Solving using Kovacic algorithm	3401
13.10.6 Maple step by step solution	3406

Internal problem ID [11864]

Internal file name [OUTPUT/11873_Saturday_April_13_2024_01_13_23_AM_97187487/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.5. The Cauchy-Euler Equation. Exercises page 169

Problem number: 10.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_euler_ode", "second_order_change_of_variable_on_x_method_1", "second_order_change_of_variable_on_x_method_2", "second_order_change_of_variable_on_y_method_2"

Maple gives the following as the ode type

```
[[_Emden, _Fowler]]
```

$$x^2y'' - 5y'x + 10y = 0$$

13.10.1 Solving as second order euler ode ode

This is Euler second order ODE. Let the solution be $y = x^r$, then $y' = rx^{r-1}$ and $y'' = r(r-1)x^{r-2}$. Substituting these back into the given ODE gives

$$x^2(r(r-1))x^{r-2} - 5rx^{r-1} + 10x^r = 0$$

Simplifying gives

$$r(r-1)x^r - 5rx^r + 10x^r = 0$$

Since $x^r \neq 0$ then dividing throughout by x^r gives

$$r(r-1) - 5r + 10 = 0$$

Or

$$r^2 - 6r + 10 = 0 \quad (1)$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = 3 - i$$

$$r_2 = 3 + i$$

The roots are complex conjugate of each others. Let the roots be

$$r_1 = \alpha + i\beta$$

$$r_2 = \alpha - i\beta$$

Where in this case $\alpha = 3$ and $\beta = -1$. Hence the solution becomes

$$\begin{aligned} y &= c_1 x^{r_1} + c_2 x^{r_2} \\ &= c_1 x^{\alpha+i\beta} + c_2 x^{\alpha-i\beta} \\ &= x^\alpha (c_1 x^{i\beta} + c_2 x^{-i\beta}) \\ &= x^\alpha (c_1 e^{\ln(x^{i\beta})} + c_2 e^{\ln(x^{-i\beta})}) \\ &= x^\alpha (c_1 e^{i(\beta \ln x)} + c_2 e^{-i(\beta \ln x)}) \end{aligned}$$

Using the values for $\alpha = 3, \beta = -1$, the above becomes

$$y = x^3 (c_1 e^{-i \ln(x)} + c_2 e^{i \ln(x)})$$

Using Euler relation, the expression $c_1 e^{iA} + c_2 e^{-iA}$ is transformed to $c_1 \cos A + c_1 \sin A$ where the constants are free to change. Applying this to the above result gives

$$y = x^3 (c_1 \cos (\ln (x)) + c_2 \sin (\ln (x)))$$

Summary

The solution(s) found are the following

$$y = x^3 (c_1 \cos (\ln (x)) + c_2 \sin (\ln (x))) \quad (1)$$

Verification of solutions

$$y = x^3 (c_1 \cos (\ln (x)) + c_2 \sin (\ln (x)))$$

Verified OK.

13.10.2 Solving as second order change of variable on x method 2 ode

In normal form the ode

$$x^2 y'' - 5y'x + 10y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = -\frac{5}{x}$$
$$q(x) = \frac{10}{x^2}$$

Applying change of variables $\tau = g(x)$ to (2) gives

$$\frac{d^2}{d\tau^2}y(\tau) + p_1\left(\frac{d}{d\tau}y(\tau)\right) + q_1y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $p_1 = 0$. Eq (4) simplifies to

$$\tau''(x) + p(x)\tau'(x) = 0$$

This ode is solved resulting in

$$\begin{aligned} \tau &= \int e^{-(\int p(x)dx)} dx \\ &= \int e^{-(\int -\frac{5}{x}dx)} dx \\ &= \int e^{5 \ln(x)} dx \\ &= \int x^5 dx \\ &= \frac{x^6}{6} \end{aligned} \quad (6)$$

Using (6) to evaluate q_1 from (5) gives

$$\begin{aligned} q_1(\tau) &= \frac{q(x)}{\tau'(x)^2} \\ &= \frac{\frac{10}{x^2}}{x^{10}} \\ &= \frac{10}{x^{12}} \end{aligned} \tag{7}$$

Substituting the above in (3) and noting that now $p_1 = 0$ results in

$$\begin{aligned} \frac{d^2}{d\tau^2}y(\tau) + q_1y(\tau) &= 0 \\ \frac{d^2}{d\tau^2}y(\tau) + \frac{10y(\tau)}{x^{12}} &= 0 \end{aligned}$$

But in terms of τ

$$\frac{10}{x^{12}} = \frac{5}{18\tau^2}$$

Hence the above ode becomes

$$\frac{d^2}{d\tau^2}y(\tau) + \frac{5y(\tau)}{18\tau^2} = 0$$

The above ode is now solved for $y(\tau)$. The ode can be written as

$$18 \left(\frac{d^2}{d\tau^2}y(\tau) \right) \tau^2 + 5y(\tau) = 0$$

Which shows it is a Euler ODE. This is Euler second order ODE. Let the solution be $y(\tau) = \tau^r$, then $y' = r\tau^{r-1}$ and $y'' = r(r-1)\tau^{r-2}$. Substituting these back into the given ODE gives

$$18\tau^2(r(r-1))\tau^{r-2} + 0r\tau^{r-1} + 5\tau^r = 0$$

Simplifying gives

$$18r(r-1)\tau^r + 0\tau^r + 5\tau^r = 0$$

Since $\tau^r \neq 0$ then dividing throughout by τ^r gives

$$18r(r-1) + 0 + 5 = 0$$

Or

$$18r^2 - 18r + 5 = 0 \tag{1}$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = \frac{1}{2} - \frac{i}{6}$$

$$r_2 = \frac{1}{2} + \frac{i}{6}$$

The roots are complex conjugate of each others. Let the roots be

$$r_1 = \alpha + i\beta$$

$$r_2 = \alpha - i\beta$$

Where in this case $\alpha = \frac{1}{2}$ and $\beta = -\frac{1}{6}$. Hence the solution becomes

$$\begin{aligned} y(\tau) &= c_1\tau^{r_1} + c_2\tau^{r_2} \\ &= c_1\tau^{\alpha+i\beta} + c_2\tau^{\alpha-i\beta} \\ &= \tau^\alpha(c_1\tau^{i\beta} + c_2\tau^{-i\beta}) \\ &= \tau^\alpha(c_1e^{\ln(\tau^{i\beta})} + c_2e^{\ln(\tau^{-i\beta})}) \\ &= \tau^\alpha(c_1e^{i(\beta \ln \tau)} + c_2e^{-i(\beta \ln \tau)}) \end{aligned}$$

Using the values for $\alpha = \frac{1}{2}, \beta = -\frac{1}{6}$, the above becomes

$$y(\tau) = \tau^{\frac{1}{2}} \left(c_1 e^{-\frac{i \ln(\tau)}{6}} + c_2 e^{\frac{i \ln(\tau)}{6}} \right)$$

Using Euler relation, the expression $c_1 e^{iA} + c_2 e^{-iA}$ is transformed to $c_1 \cos A + c_1 \sin A$ where the constants are free to change. Applying this to the above result gives

$$y(\tau) = \sqrt{\tau} \left(c_1 \cos \left(\frac{\ln(\tau)}{6} \right) + c_2 \sin \left(\frac{\ln(\tau)}{6} \right) \right)$$

The above solution is now transformed back to y using (6) which results in

$$y = \frac{\sqrt{6} \sqrt{x^6} \left(c_1 \cos \left(-\frac{\ln(2)}{6} - \frac{\ln(3)}{6} + \frac{\ln(x^6)}{6} \right) + c_2 \sin \left(-\frac{\ln(2)}{6} - \frac{\ln(3)}{6} + \frac{\ln(x^6)}{6} \right) \right)}{6}$$

Summary

The solution(s) found are the following

$$y = \frac{\sqrt{6} \sqrt{x^6} \left(c_1 \cos \left(-\frac{\ln(2)}{6} - \frac{\ln(3)}{6} + \frac{\ln(x^6)}{6} \right) + c_2 \sin \left(-\frac{\ln(2)}{6} - \frac{\ln(3)}{6} + \frac{\ln(x^6)}{6} \right) \right)}{6} \quad (1)$$

Verification of solutions

$$y = \frac{\sqrt{6} \sqrt{x^6} \left(c_1 \cos \left(-\frac{\ln(2)}{6} - \frac{\ln(3)}{6} + \frac{\ln(x^6)}{6} \right) + c_2 \sin \left(-\frac{\ln(2)}{6} - \frac{\ln(3)}{6} + \frac{\ln(x^6)}{6} \right) \right)}{6}$$

Verified OK.

13.10.3 Solving as second order change of variable on x method 1 ode

In normal form the ode

$$x^2 y'' - 5y'x + 10y = 0 \quad (1)$$

Becomes

$$y'' + p(x) y' + q(x) y = 0 \quad (2)$$

Where

$$p(x) = -\frac{5}{x}$$
$$q(x) = \frac{10}{x^2}$$

Applying change of variables $\tau = g(x)$ to (2) results

$$\frac{d^2}{d\tau^2} y(\tau) + p_1 \left(\frac{d}{d\tau} y(\tau) \right) + q_1 y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x) \tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $q_1 = c^2$ where c is some constant. Therefore from (5)

$$\tau' = \frac{1}{c} \sqrt{q}$$
$$= \frac{\sqrt{10} \sqrt{\frac{1}{x^2}}}{c} \quad (6)$$
$$\tau'' = -\frac{\sqrt{10}}{c \sqrt{\frac{1}{x^2}} x^3}$$

Substituting the above into (4) results in

$$\begin{aligned}
 p_1(\tau) &= \frac{\tau''(x) + p(x) \tau'(x)}{\tau'(x)^2} \\
 &= \frac{-\frac{\sqrt{10}}{c\sqrt{\frac{1}{x^2}}x^3} - \frac{5}{x} \frac{\sqrt{10}\sqrt{\frac{1}{x^2}}}{c}}{\left(\frac{\sqrt{10}\sqrt{\frac{1}{x^2}}}{c}\right)^2} \\
 &= -\frac{3c\sqrt{10}}{5}
 \end{aligned}$$

Therefore ode (3) now becomes

$$\begin{aligned}
 y(\tau)'' + p_1y(\tau)' + q_1y(\tau) &= 0 \\
 \frac{d^2}{d\tau^2}y(\tau) - \frac{3c\sqrt{10}}{5}\left(\frac{d}{d\tau}y(\tau)\right) + c^2y(\tau) &= 0 \tag{7}
 \end{aligned}$$

The above ode is now solved for $y(\tau)$. Since the ode is now constant coefficients, it can be easily solved to give

$$y(\tau) = e^{\frac{3\sqrt{10}c\tau}{10}} \left(c_1 \cos\left(\frac{\sqrt{10}c\tau}{10}\right) + c_2 \sin\left(\frac{\sqrt{10}c\tau}{10}\right) \right)$$

Now from (6)

$$\begin{aligned}
 \tau &= \int \frac{1}{c} \sqrt{q} dx \\
 &= \frac{\int \sqrt{10} \sqrt{\frac{1}{x^2}} dx}{c} \\
 &= \frac{\sqrt{10} \sqrt{\frac{1}{x^2}} x \ln(x)}{c}
 \end{aligned}$$

Substituting the above into the solution obtained gives

$$y = x^3(c_1 \cos(\ln(x)) + c_2 \sin(\ln(x)))$$

Summary

The solution(s) found are the following

$$y = x^3(c_1 \cos(\ln(x)) + c_2 \sin(\ln(x))) \tag{1}$$

Verification of solutions

$$y = x^3(c_1 \cos(\ln(x)) + c_2 \sin(\ln(x)))$$

Verified OK.

13.10.4 Solving as second order change of variable on y method 2 ode

In normal form the ode

$$x^2 y'' - 5y'x + 10y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = -\frac{5}{x}$$
$$q(x) = \frac{10}{x^2}$$

Applying change of variables on the dependent variable $y = v(x)x^n$ to (2) gives the following ode where the dependent variables is $v(x)$ and not y .

$$v''(x) + \left(\frac{2n}{x} + p\right)v'(x) + \left(\frac{n(n-1)}{x^2} + \frac{np}{x} + q\right)v(x) = 0 \quad (3)$$

Let the coefficient of $v(x)$ above be zero. Hence

$$\frac{n(n-1)}{x^2} + \frac{np}{x} + q = 0 \quad (4)$$

Substituting the earlier values found for $p(x)$ and $q(x)$ into (4) gives

$$\frac{n(n-1)}{x^2} - \frac{5n}{x^2} + \frac{10}{x^2} = 0 \quad (5)$$

Solving (5) for n gives

$$n = 3 + i \quad (6)$$

Substituting this value in (3) gives

$$v''(x) + \left(\frac{6+2i}{x} - \frac{5}{x}\right)v'(x) = 0$$
$$v''(x) + \frac{(1+2i)v'(x)}{x} = 0 \quad (7)$$

Using the substitution

$$u(x) = v'(x)$$

Then (7) becomes

$$u'(x) + \frac{(1 + 2i)u(x)}{x} = 0 \quad (8)$$

The above is now solved for $u(x)$. In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= \frac{(-1 - 2i)u}{x} \end{aligned}$$

Where $f(x) = \frac{-1-2i}{x}$ and $g(u) = u$. Integrating both sides gives

$$\begin{aligned} \frac{1}{u} du &= \frac{-1 - 2i}{x} dx \\ \int \frac{1}{u} du &= \int \frac{-1 - 2i}{x} dx \\ \ln(u) &= (-1 - 2i) \ln(x) + c_1 \\ u &= e^{(-1-2i)\ln(x)+c_1} \\ &= c_1 e^{(-1-2i)\ln(x)} \end{aligned}$$

Which simplifies to

$$u(x) = \frac{c_1 x^{-2i}}{x}$$

Now that $u(x)$ is known, then

$$\begin{aligned} v'(x) &= u(x) \\ v(x) &= \int u(x) dx + c_2 \\ &= \frac{ix^{-2i}c_1}{2} + c_2 \end{aligned}$$

Hence

$$\begin{aligned} y &= v(x) x^n \\ &= \left(\frac{ix^{-2i}c_1}{2} + c_2 \right) x^{3+i} \\ &= c_2 x^{3+i} + \frac{ic_1 x^{3-i}}{2} \end{aligned}$$

Summary

The solution(s) found are the following

$$y = \left(\frac{ix^{-2i}c_1}{2} + c_2 \right) x^{3+i} \quad (1)$$

Verification of solutions

$$y = \left(\frac{ix^{-2i}c_1}{2} + c_2 \right) x^{3+i}$$

Verified OK.

13.10.5 Solving using Kovacic algorithm

Writing the ode as

$$x^2y'' - 5y'x + 10y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= x^2 \\ B &= -5x \\ C &= 10 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-5}{4x^2} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= -5 \\ t &= 4x^2 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = \left(-\frac{5}{4x^2}\right) z(x) \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 486: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 2 - 0 \\ &= 2 \end{aligned}$$

The poles of r in eq. (7) and the order of each pole are determined by solving for the roots of $t = 4x^2$. There is a pole at $x = 0$ of order 2. Since there is no odd order pole

larger than 2 and the order at ∞ is 2 then the necessary conditions for case one are met. Since there is a pole of order 2 then necessary conditions for case two are met. Since pole order is not larger than 2 and the order at ∞ is 2 then the necessary conditions for case three are met. Therefore

$$L = [1, 2, 4, 6, 12]$$

Attempting to find a solution using case $n = 1$.

Looking at poles of order 2. The partial fractions decomposition of r is

$$r = -\frac{5}{4x^2}$$

For the pole at $x = 0$ let b be the coefficient of $\frac{1}{x^2}$ in the partial fractions decomposition of r given above. Therefore $b = -\frac{5}{4}$. Hence

$$\begin{aligned} [\sqrt{r}]_c &= 0 \\ \alpha_c^+ &= \frac{1}{2} + \sqrt{1 + 4b} = \frac{1}{2} + i \\ \alpha_c^- &= \frac{1}{2} - \sqrt{1 + 4b} = \frac{1}{2} - i \end{aligned}$$

Since the order of r at ∞ is 2 then $[\sqrt{r}]_\infty = 0$. Let b be the coefficient of $\frac{1}{x^2}$ in the Laurent series expansion of r at ∞ . which can be found by dividing the leading coefficient of s by the leading coefficient of t from

$$r = \frac{s}{t} = -\frac{5}{4x^2}$$

Since the $\gcd(s, t) = 1$. This gives $b = -\frac{5}{4}$. Hence

$$\begin{aligned} [\sqrt{r}]_\infty &= 0 \\ \alpha_\infty^+ &= \frac{1}{2} + \sqrt{1 + 4b} = \frac{1}{2} + i \\ \alpha_\infty^- &= \frac{1}{2} - \sqrt{1 + 4b} = \frac{1}{2} - i \end{aligned}$$

The following table summarizes the findings so far for poles and for the order of r at ∞ where r is

$$r = -\frac{5}{4x^2}$$

pole c location	pole order	$[\sqrt{r}]_c$	α_c^+	α_c^-
0	2	0	$\frac{1}{2} + i$	$\frac{1}{2} - i$

Order of r at ∞	$[\sqrt{r}]_\infty$	α_∞^+	α_∞^-
2	0	$\frac{1}{2} + i$	$\frac{1}{2} - i$

Now that the all $[\sqrt{r}]_c$ and its associated α_c^\pm have been determined for all the poles in the set Γ and $[\sqrt{r}]_\infty$ and its associated α_∞^\pm have also been found, the next step is to determine possible non negative integer d from these using

$$d = \alpha_\infty^{s(\infty)} - \sum_{c \in \Gamma} \alpha_c^{s(c)}$$

Where $s(c)$ is either $+$ or $-$ and $s(\infty)$ is the sign of α_∞^\pm . This is done by trial over all set of families $s = (s(c))_{c \in \Gamma \cup \infty}$ until such d is found to work in finding candidate ω . Trying $\alpha_\infty^- = \frac{1}{2} - i$ then

$$\begin{aligned} d &= \alpha_\infty^- - (\alpha_{c_1}^-) \\ &= \frac{1}{2} - i - \left(\frac{1}{2} - i \right) \\ &= 0 \end{aligned}$$

Since d an integer and $d \geq 0$ then it can be used to find ω using

$$\omega = \sum_{c \in \Gamma} \left(s(c) [\sqrt{r}]_c + \frac{\alpha_c^{s(c)}}{x - c} \right) + s(\infty) [\sqrt{r}]_\infty$$

The above gives

$$\begin{aligned} \omega &= \left((-) [\sqrt{r}]_{c_1} + \frac{\alpha_{c_1}^-}{x - c_1} \right) + (-) [\sqrt{r}]_\infty \\ &= \frac{\frac{1}{2} - i}{x} + (-) (0) \\ &= \frac{\frac{1}{2} - i}{x} \\ &= \frac{\frac{1}{2} - i}{x} \end{aligned}$$

Now that ω is determined, the next step is find a corresponding minimal polynomial $p(x)$ of degree $d = 0$ to solve the ode. The polynomial $p(x)$ needs to satisfy the equation

$$p'' + 2\omega p' + (\omega' + \omega^2 - r) p = 0 \tag{1A}$$

Let

$$p(x) = 1 \tag{2A}$$

Substituting the above in eq. (1A) gives

$$(0) + 2\left(\frac{\frac{1}{2} - i}{x}\right)(0) + \left(\left(\frac{-\frac{1}{2} + i}{x^2}\right) + \left(\frac{\frac{1}{2} - i}{x}\right)^2 - \left(-\frac{5}{4x^2}\right)\right) = 0$$

$$0 = 0$$

The equation is satisfied since both sides are zero. Therefore the first solution to the ode $z'' = rz$ is

$$z_1(x) = pe^{\int \omega dx}$$

$$= e^{\int \frac{\frac{1}{2} - i}{x} dx}$$

$$= x^{\frac{1}{2} - i}$$

The first solution to the original ode in y is found from

$$y_1 = z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx}$$

$$= z_1 e^{-\int \frac{1}{2} \frac{-5x}{x^2} dx}$$

$$= z_1 e^{\frac{5 \ln(x)}{2}}$$

$$= z_1 \left(x^{\frac{5}{2}}\right)$$

Which simplifies to

$$y_1 = x^{3-i}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$y_2 = y_1 \int \frac{e^{\int -\frac{-5x}{x^2} dx}}{(y_1)^2} dx$$

$$= y_1 \int \frac{e^{5 \ln(x)}}{(y_1)^2} dx$$

$$= y_1 \left(-\frac{ix^{2i}}{2}\right)$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (x^{3-i}) + c_2 \left(x^{3-i} \left(-\frac{ix^{2i}}{2} \right) \right)\end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 x^{3-i} - \frac{ic_2 x^{3+i}}{2} \quad (1)$$

Verification of solutions

$$y = c_1 x^{3-i} - \frac{ic_2 x^{3+i}}{2}$$

Verified OK.

13.10.6 Maple step by step solution

Let's solve

$$y''x^2 - 5y'x + 10y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = \frac{5y'}{x} - \frac{10y}{x^2}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' - \frac{5y'}{x} + \frac{10y}{x^2} = 0$$

- Multiply by denominators of the ODE

$$y''x^2 - 5y'x + 10y = 0$$

- Make a change of variables

$$t = \ln(x)$$

- Substitute the change of variables back into the ODE

- Calculate the 1st derivative of y with respect to x , using the chain rule

$$y' = \left(\frac{d}{dt} y(t) \right) t'(x)$$

- Compute derivative

$$y' = \frac{\frac{d}{dt}y(t)}{x}$$

- Calculate the 2nd derivative of y with respect to x , using the chain rule

$$y'' = \left(\frac{d^2}{dt^2}y(t) \right) t'(x)^2 + t''(x) \left(\frac{d}{dt}y(t) \right)$$

- Compute derivative

$$y'' = \frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2}$$

Substitute the change of variables back into the ODE

$$\left(\frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2} \right) x^2 - 5 \frac{d}{dt}y(t) + 10y(t) = 0$$

- Simplify

$$\frac{d^2}{dt^2}y(t) - 6 \frac{d}{dt}y(t) + 10y(t) = 0$$

- Characteristic polynomial of ODE

$$r^2 - 6r + 10 = 0$$

- Use quadratic formula to solve for r

$$r = \frac{6 \pm (\sqrt{-4})}{2}$$

- Roots of the characteristic polynomial

$$r = (3 - I, 3 + I)$$

- 1st solution of the ODE

$$y_1(t) = e^{3t} \cos(t)$$

- 2nd solution of the ODE

$$y_2(t) = e^{3t} \sin(t)$$

- General solution of the ODE

$$y(t) = c_1 y_1(t) + c_2 y_2(t)$$

- Substitute in solutions

$$y(t) = c_1 e^{3t} \cos(t) + c_2 e^{3t} \sin(t)$$

- Change variables back using $t = \ln(x)$

$$y = c_1 x^3 \cos(\ln(x)) + c_2 x^3 \sin(\ln(x))$$

- Simplify

$$y = x^3 (c_1 \cos(\ln(x)) + c_2 \sin(\ln(x)))$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
checking if the LODE is of Euler type  
<- LODE of Euler type successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 19

```
dsolve(x^2*diff(y(x),x$2)-5*x*diff(y(x),x)+10*y(x)=0,y(x), singsol=all)
```

$$y(x) = x^3(c_1 \sin(\ln(x)) + \cos(\ln(x)) c_2)$$

✓ Solution by Mathematica

Time used: 0.024 (sec). Leaf size: 22

```
DSolve[x^2*y'[x]-5*x*y'[x]+10*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow x^3(c_2 \cos(\log(x)) + c_1 \sin(\log(x)))$$

13.11 problem 11

13.11.1 Maple step by step solution 3411

Internal problem ID [11865]

Internal file name [OUTPUT/11874_Saturday_April_13_2024_01_13_24_AM_53887226/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.5. The Cauchy-Euler Equation. Exercises page 169

Problem number: 11.

ODE order: 3.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_ODE_non_constant_coefficients_of_type_Euler**"

Maple gives the following as the ode type

```
[[_3rd_order , _with_linear_symmetries]]
```

$$x^3 y''' - 3x^2 y'' + 6y'x - 6y = 0$$

This is Euler ODE of higher order. Let $y = x^\lambda$. Hence

$$y' = \lambda x^{\lambda-1}$$

$$y'' = \lambda(\lambda - 1) x^{\lambda-2}$$

$$y''' = \lambda(\lambda - 1)(\lambda - 2) x^{\lambda-3}$$

Substituting these back into

$$x^3 y''' - 3x^2 y'' + 6y'x - 6y = 0$$

gives

$$6x\lambda x^{\lambda-1} - 3x^2\lambda(\lambda - 1) x^{\lambda-2} + x^3\lambda(\lambda - 1)(\lambda - 2) x^{\lambda-3} - 6x^\lambda = 0$$

Which simplifies to

$$6\lambda x^\lambda - 3\lambda(\lambda - 1) x^\lambda + \lambda(\lambda - 1)(\lambda - 2) x^\lambda - 6x^\lambda = 0$$

And since $x^\lambda \neq 0$ then dividing through by x^λ , the above becomes

$$6\lambda - 3\lambda(\lambda - 1) + \lambda(\lambda - 1)(\lambda - 2) - 6 = 0$$

Simplifying gives the characteristic equation as

$$\lambda^3 - 6\lambda^2 + 11\lambda - 6 = 0$$

Solving the above gives the following roots

$$\lambda_1 = 1$$

$$\lambda_2 = 2$$

$$\lambda_3 = 3$$

This table summarises the result

root	multiplicity	type of root
1	1	real root
2	1	real root
3	1	real root

The solution is generated by going over the above table. For each real root λ of multiplicity one generates a c_1x^λ basis solution. Each real root of multiplicity two, generates c_1x^λ and $c_2x^\lambda \ln(x)$ basis solutions. Each real root of multiplicity three, generates c_1x^λ and $c_2x^\lambda \ln(x)$ and $c_3x^\lambda \ln(x)^2$ basis solutions, and so on. Each complex root $\alpha \pm i\beta$ of multiplicity one generates $x^\alpha(c_1 \cos(\beta \ln(x)) + c_2 \sin(\beta \ln(x)))$ basis solutions. And each complex root $\alpha \pm i\beta$ of multiplicity two generates $\ln(x) x^\alpha(c_1 \cos(\beta \ln(x)) + c_2 \sin(\beta \ln(x)))$ basis solutions. And each complex root $\alpha \pm i\beta$ of multiplicity three generates $\ln(x)^2 x^\alpha(c_1 \cos(\beta \ln(x)) + c_2 \sin(\beta \ln(x)))$ basis solutions. And so on. Using the above show that the solution is

$$y = c_3x^3 + c_2x^2 + c_1x$$

The fundamental set of solutions for the homogeneous solution are the following

$$y_1 = x$$

$$y_2 = x^2$$

$$y_3 = x^3$$

Summary

The solution(s) found are the following

$$y = c_3x^3 + c_2x^2 + c_1x \tag{1}$$

Verification of solutions

$$y = c_3x^3 + c_2x^2 + c_1x$$

Verified OK.

13.11.1 Maple step by step solution

Let's solve

$$x^3y''' - 3y''x^2 + 6y'x - 6y = 0$$

- Highest derivative means the order of the ODE is 3

$$y'''$$

- Isolate 3rd derivative

$$y''' = \frac{6y}{x^3} + \frac{3(y''x - 2y')}{x^2}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y''' - \frac{3y''}{x} + \frac{6y'}{x^2} - \frac{6y}{x^3} = 0$$

- Multiply by denominators of the ODE

$$x^3y''' - 3y''x^2 + 6y'x - 6y = 0$$

- Make a change of variables

$$t = \ln(x)$$

- Substitute the change of variables back into the ODE

- Calculate the 1st derivative of y with respect to x , using the chain rule

$$y' = \left(\frac{d}{dt}y(t)\right) t'(x)$$

- Compute derivative

$$y' = \frac{\frac{d}{dt}y(t)}{x}$$

- Calculate the 2nd derivative of y with respect to x , using the chain rule

$$y'' = \left(\frac{d^2}{dt^2}y(t)\right) t'(x)^2 + t''(x) \left(\frac{d}{dt}y(t)\right)$$

- Compute derivative

$$y'' = \frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2}$$

- Calculate the 3rd derivative of y with respect to x , using the chain rule

$$y''' = \left(\frac{d^3}{dt^3}y(t)\right) t'(x)^3 + 3t'(x)t''(x) \left(\frac{d^2}{dt^2}y(t)\right) + t'''(x) \left(\frac{d}{dt}y(t)\right)$$

- Compute derivative

$$y''' = \frac{\frac{d^3}{dt^3}y(t)}{x^3} - \frac{3\left(\frac{d^2}{dt^2}y(t)\right)}{x^3} + \frac{2\left(\frac{d}{dt}y(t)\right)}{x^3}$$

Substitute the change of variables back into the ODE

$$x^3 \left(\frac{\frac{d^3}{dt^3}y(t)}{x^3} - \frac{3\left(\frac{d^2}{dt^2}y(t)\right)}{x^3} + \frac{2\left(\frac{d}{dt}y(t)\right)}{x^3} \right) - 3 \left(\frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2} \right) x^2 + 6 \frac{d}{dt}y(t) - 6y(t) = 0$$

- Simplify

$$\frac{d^3}{dt^3}y(t) - 6 \frac{d^2}{dt^2}y(t) + 11 \frac{d}{dt}y(t) - 6y(t) = 0$$

- Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(t)$

$$y_1(t) = y(t)$$

- Define new variable $y_2(t)$

$$y_2(t) = \frac{d}{dt}y(t)$$

- Define new variable $y_3(t)$

$$y_3(t) = \frac{d^2}{dt^2}y(t)$$

- Isolate for $\frac{d}{dt}y_3(t)$ using original ODE

$$\frac{d}{dt}y_3(t) = 6y_3(t) - 11y_2(t) + 6y_1(t)$$

Convert linear ODE into a system of first order ODEs

$$\left[y_2(t) = \frac{d}{dt}y_1(t), y_3(t) = \frac{d}{dt}y_2(t), \frac{d}{dt}y_3(t) = 6y_3(t) - 11y_2(t) + 6y_1(t) \right]$$

- Define vector

$$\vec{y}(t) = \begin{bmatrix} y_1(t) \\ y_2(t) \\ y_3(t) \end{bmatrix}$$

- System to solve

$$\frac{d}{dt}\vec{y}(t) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 6 & -11 & 6 \end{bmatrix} \cdot \vec{y}(t)$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 6 & -11 & 6 \end{bmatrix}$$

- Rewrite the system as

$$\frac{d}{dt}\vec{y}(t) = A \cdot \vec{y}(t)$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[1, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right], \left[2, \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right], \left[3, \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[1, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_1 = e^t \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[2, \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_2 = e^{2t} \cdot \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[3, \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_3 = e^{3t} \cdot \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix}$$

- General solution to the system of ODEs

$$\vec{y} = c_1 \vec{y}_1 + c_2 \vec{y}_2 + c_3 \vec{y}_3$$

- Substitute solutions into the general solution

$$\vec{y} = c_1 e^t \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + c_2 e^{2t} \cdot \begin{bmatrix} \frac{1}{4} \\ \frac{1}{2} \\ 1 \end{bmatrix} + c_3 e^{3t} \cdot \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y(t) = c_1 e^t + \frac{c_2 e^{2t}}{4} + \frac{c_3 e^{3t}}{9}$$

- Change variables back using $t = \ln(x)$

$$y = c_1 x + \frac{1}{4} c_2 x^2 + \frac{1}{9} c_3 x^3$$

Maple trace

```

`Methods for third order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
<- LODE of Euler type successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 16

```
dsolve(x^3*diff(y(x),x$3)-3*x^2*diff(y(x),x$2)+6*x*diff(y(x),x)-6*y(x)=0,y(x), singsol=all)
```

$$y(x) = x(c_3x^2 + c_2x + c_1)$$

✓ Solution by Mathematica

Time used: 0.004 (sec). Leaf size: 19

```
DSolve[x^3*y'''[x]-3*x^2*y''[x]+6*x*y'[x]-6*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow x(x(c_3x + c_2) + c_1)$$

13.12 problem 12

13.12.1 Maple step by step solution 3418

Internal problem ID [11866]

Internal file name [OUTPUT/11875_Saturday_April_13_2024_01_13_25_AM_90650534/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.5. The Cauchy-Euler Equation. Exercises page 169

Problem number: 12.

ODE order: 3.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_ODE_non_constant_coefficients_of_type_Euler**"

Maple gives the following as the ode type

[[_3rd_order , _fully , _exact , _linear]]

$$x^3 y''' + 2x^2 y'' - 10y'x - 8y = 0$$

This is Euler ODE of higher order. Let $y = x^\lambda$. Hence

$$y' = \lambda x^{\lambda-1}$$

$$y'' = \lambda(\lambda - 1) x^{\lambda-2}$$

$$y''' = \lambda(\lambda - 1)(\lambda - 2) x^{\lambda-3}$$

Substituting these back into

$$x^3 y''' + 2x^2 y'' - 10y'x - 8y = 0$$

gives

$$-10\lambda x^\lambda + 2x^2 \lambda(\lambda - 1) x^{\lambda-2} + x^3 \lambda(\lambda - 1)(\lambda - 2) x^{\lambda-3} - 8x^\lambda = 0$$

Which simplifies to

$$-10\lambda x^\lambda + 2\lambda(\lambda - 1) x^\lambda + \lambda(\lambda - 1)(\lambda - 2) x^\lambda - 8x^\lambda = 0$$

And since $x^\lambda \neq 0$ then dividing through by x^λ , the above becomes

$$-10\lambda + 2\lambda(\lambda - 1) + \lambda(\lambda - 1)(\lambda - 2) - 8 = 0$$

Simplifying gives the characteristic equation as

$$\lambda^3 - \lambda^2 - 10\lambda - 8 = 0$$

Solving the above gives the following roots

$$\lambda_1 = 4$$

$$\lambda_2 = -2$$

$$\lambda_3 = -1$$

This table summarises the result

root	multiplicity	type of root
-1	1	real root
-2	1	real root
4	1	real root

The solution is generated by going over the above table. For each real root λ of multiplicity one generates a $c_1 x^\lambda$ basis solution. Each real root of multiplicity two, generates $c_1 x^\lambda$ and $c_2 x^\lambda \ln(x)$ basis solutions. Each real root of multiplicity three, generates $c_1 x^\lambda$ and $c_2 x^\lambda \ln(x)$ and $c_3 x^\lambda \ln(x)^2$ basis solutions, and so on. Each complex root $\alpha \pm i\beta$ of multiplicity one generates $x^\alpha (c_1 \cos(\beta \ln(x)) + c_2 \sin(\beta \ln(x)))$ basis solutions. And each complex root $\alpha \pm i\beta$ of multiplicity two generates $\ln(x) x^\alpha (c_1 \cos(\beta \ln(x)) + c_2 \sin(\beta \ln(x)))$ basis solutions. And each complex root $\alpha \pm i\beta$ of multiplicity three generates $\ln(x)^2 x^\alpha (c_1 \cos(\beta \ln(x)) + c_2 \sin(\beta \ln(x)))$ basis solutions. And so on. Using the above show that the solution is

$$y = \frac{c_1}{x} + \frac{c_2}{x^2} + c_3 x^4$$

The fundamental set of solutions for the homogeneous solution are the following

$$y_1 = \frac{1}{x}$$

$$y_2 = \frac{1}{x^2}$$

$$y_3 = x^4$$

Summary

The solution(s) found are the following

$$y = \frac{c_1}{x} + \frac{c_2}{x^2} + c_3x^4 \quad (1)$$

Verification of solutions

$$y = \frac{c_1}{x} + \frac{c_2}{x^2} + c_3x^4$$

Verified OK.

13.12.1 Maple step by step solution

Let's solve

$$x^3y''' + 2y''x^2 - 10y'x - 8y = 0$$

- Highest derivative means the order of the ODE is 3

$$y'''$$

- Isolate 3rd derivative

$$y''' = \frac{8y}{x^3} - \frac{2(y''x - 5y')}{x^2}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y''' + \frac{2y''}{x} - \frac{10y'}{x^2} - \frac{8y}{x^3} = 0$$

- Multiply by denominators of the ODE

$$x^3y''' + 2y''x^2 - 10y'x - 8y = 0$$

- Make a change of variables

$$t = \ln(x)$$

- Substitute the change of variables back into the ODE

- Calculate the 1st derivative of y with respect to x , using the chain rule

$$y' = \left(\frac{d}{dt}y(t)\right) t'(x)$$

- Compute derivative

$$y' = \frac{\frac{d}{dt}y(t)}{x}$$

- Calculate the 2nd derivative of y with respect to x , using the chain rule

$$y'' = \left(\frac{d^2}{dt^2}y(t)\right) t'(x)^2 + t''(x) \left(\frac{d}{dt}y(t)\right)$$

- Compute derivative

$$y'' = \frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2}$$

- Calculate the 3rd derivative of y with respect to x , using the chain rule

$$y''' = \left(\frac{d^3}{dt^3}y(t) \right) t'(x)^3 + 3t'(x)t''(x) \left(\frac{d^2}{dt^2}y(t) \right) + t'''(x) \left(\frac{d}{dt}y(t) \right)$$

- Compute derivative

$$y''' = \frac{\frac{d^3}{dt^3}y(t)}{x^3} - \frac{3\left(\frac{d^2}{dt^2}y(t)\right)}{x^3} + \frac{2\left(\frac{d}{dt}y(t)\right)}{x^3}$$

Substitute the change of variables back into the ODE

$$x^3 \left(\frac{\frac{d^3}{dt^3}y(t)}{x^3} - \frac{3\left(\frac{d^2}{dt^2}y(t)\right)}{x^3} + \frac{2\left(\frac{d}{dt}y(t)\right)}{x^3} \right) + 2 \left(\frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2} \right) x^2 - 10 \frac{d}{dt}y(t) - 8y(t) = 0$$

- Simplify

$$\frac{d^3}{dt^3}y(t) - \frac{d^2}{dt^2}y(t) - 10 \frac{d}{dt}y(t) - 8y(t) = 0$$

- Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(t)$

$$y_1(t) = y(t)$$

- Define new variable $y_2(t)$

$$y_2(t) = \frac{d}{dt}y(t)$$

- Define new variable $y_3(t)$

$$y_3(t) = \frac{d^2}{dt^2}y(t)$$

- Isolate for $\frac{d}{dt}y_3(t)$ using original ODE

$$\frac{d}{dt}y_3(t) = y_3(t) + 10y_2(t) + 8y_1(t)$$

Convert linear ODE into a system of first order ODEs

$$\left[y_2(t) = \frac{d}{dt}y_1(t), y_3(t) = \frac{d}{dt}y_2(t), \frac{d}{dt}y_3(t) = y_3(t) + 10y_2(t) + 8y_1(t) \right]$$

- Define vector

$$\vec{y}(t) = \begin{bmatrix} y_1(t) \\ y_2(t) \\ y_3(t) \end{bmatrix}$$

- System to solve

$$\frac{d}{dt} \vec{y}(t) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 8 & 10 & 1 \end{bmatrix} \cdot \vec{y}(t)$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 8 & 10 & 1 \end{bmatrix}$$

- Rewrite the system as

$$\frac{d}{dt} \vec{y}(t) = A \cdot \vec{y}(t)$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[-2, \begin{bmatrix} \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix} \right], \left[-1, \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \right], \left[4, \begin{bmatrix} \frac{1}{16} \\ \frac{1}{4} \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[-2, \begin{bmatrix} \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_1 = e^{-2t} \cdot \begin{bmatrix} \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[-1, \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_2 = e^{-t} \cdot \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[4, \begin{bmatrix} \frac{1}{16} \\ \frac{1}{4} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_3 = e^{4t} \cdot \begin{bmatrix} \frac{1}{16} \\ \frac{1}{4} \\ 1 \end{bmatrix}$$

- General solution to the system of ODEs

$$\vec{y} = c_1 \vec{y}_1 + c_2 \vec{y}_2 + c_3 \vec{y}_3$$

- Substitute solutions into the general solution

$$\vec{y} = c_1 e^{-2t} \cdot \begin{bmatrix} \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix} + c_2 e^{-t} \cdot \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} + c_3 e^{4t} \cdot \begin{bmatrix} \frac{1}{16} \\ \frac{1}{4} \\ 1 \end{bmatrix}$$

- First component of the vector is the solution to the ODE

$$y(t) = \frac{(c_3 e^{6t} + 16c_2 e^t + 4c_1) e^{-2t}}{16}$$

- Change variables back using $t = \ln(x)$

$$y = \frac{c_3 x^6 + 16c_2 x + 4c_1}{16x^2}$$

Maple trace

```
`Methods for third order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
checking if the LODE is of Euler type  
<- LODE of Euler type successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 18

```
dsolve(x^3*diff(y(x),x$3)+2*x^2*diff(y(x),x$2)-10*x*diff(y(x),x)-8*y(x)=0,y(x), singsol=all)
```

$$y(x) = \frac{c_1 x^6 + c_2 x + c_3}{x^2}$$

✓ Solution by Mathematica

Time used: 0.004 (sec). Leaf size: 22

```
DSolve[x^3*y'''[x]+2*x^2*y''[x]-10*x*y'[x]-8*y[x]==0,y[x],x,IncludeSingularSolutions -> True
```

$$y(x) \rightarrow \frac{c_3 x^6 + c_2 x + c_1}{x^2}$$

13.13 problem 13

13.13.1 Maple step by step solution 3425

Internal problem ID [11867]

Internal file name [OUTPUT/11876_Saturday_April_13_2024_01_13_25_AM_68307060/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.5. The Cauchy-Euler Equation. Exercises page 169

Problem number: 13.

ODE order: 3.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_ODE_non_constant_coefficients_of_type_Euler**"

Maple gives the following as the ode type

```
[[_3rd_order , _with_linear_symmetries]]
```

$$x^3y''' - x^2y'' - 6y'x + 18y = 0$$

This is Euler ODE of higher order. Let $y = x^\lambda$. Hence

$$y' = \lambda x^{\lambda-1}$$

$$y'' = \lambda(\lambda - 1) x^{\lambda-2}$$

$$y''' = \lambda(\lambda - 1)(\lambda - 2) x^{\lambda-3}$$

Substituting these back into

$$x^3y''' - x^2y'' - 6y'x + 18y = 0$$

gives

$$-6x\lambda x^{\lambda-1} - x^2\lambda(\lambda - 1) x^{\lambda-2} + x^3\lambda(\lambda - 1)(\lambda - 2) x^{\lambda-3} + 18x^\lambda = 0$$

Which simplifies to

$$-6\lambda x^\lambda - \lambda(\lambda - 1) x^\lambda + \lambda(\lambda - 1)(\lambda - 2) x^\lambda + 18x^\lambda = 0$$

And since $x^\lambda \neq 0$ then dividing through by x^λ , the above becomes

$$-6\lambda - \lambda(\lambda - 1) + \lambda(\lambda - 1)(\lambda - 2) + 18 = 0$$

Simplifying gives the characteristic equation as

$$(\lambda + 2)(\lambda - 3)^2 = 0$$

Solving the above gives the following roots

$$\lambda_1 = -2$$

$$\lambda_2 = 3$$

$$\lambda_3 = 3$$

This table summarises the result

root	multiplicity	type of root
-2	1	real root
3	2	real root

The solution is generated by going over the above table. For each real root λ of multiplicity one generates a c_1x^λ basis solution. Each real root of multiplicity two, generates c_1x^λ and $c_2x^\lambda \ln(x)$ basis solutions. Each real root of multiplicity three, generates c_1x^λ and $c_2x^\lambda \ln(x)$ and $c_3x^\lambda \ln(x)^2$ basis solutions, and so on. Each complex root $\alpha \pm i\beta$ of multiplicity one generates $x^\alpha(c_1 \cos(\beta \ln(x)) + c_2 \sin(\beta \ln(x)))$ basis solutions. And each complex root $\alpha \pm i\beta$ of multiplicity two generates $\ln(x) x^\alpha(c_1 \cos(\beta \ln(x)) + c_2 \sin(\beta \ln(x)))$ basis solutions. And each complex root $\alpha \pm i\beta$ of multiplicity three generates $\ln(x)^2 x^\alpha(c_1 \cos(\beta \ln(x)) + c_2 \sin(\beta \ln(x)))$ basis solutions. And so on. Using the above show that the solution is

$$y = \frac{c_1}{x^2} + c_2x^3 + c_3 \ln(x) x^3$$

The fundamental set of solutions for the homogeneous solution are the following

$$y_1 = \frac{1}{x^2}$$

$$y_2 = x^3$$

$$y_3 = x^3 \ln(x)$$

Summary

The solution(s) found are the following

$$y = \frac{c_1}{x^2} + c_2x^3 + c_3 \ln(x) x^3 \tag{1}$$

Verification of solutions

$$y = \frac{c_1}{x^2} + c_2 x^3 + c_3 \ln(x) x^3$$

Verified OK.

13.13.1 Maple step by step solution

Let's solve

$$x^3 y''' - y'' x^2 - 6y' x + 18y = 0$$

- Highest derivative means the order of the ODE is 3

$$y'''$$

- Isolate 3rd derivative

$$y''' = -\frac{18y}{x^3} + \frac{y'' x + 6y'}{x^2}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y''' - \frac{y''}{x} - \frac{6y'}{x^2} + \frac{18y}{x^3} = 0$$

- Multiply by denominators of the ODE

$$x^3 y''' - y'' x^2 - 6y' x + 18y = 0$$

- Make a change of variables

$$t = \ln(x)$$

- Substitute the change of variables back into the ODE

- Calculate the 1st derivative of y with respect to x , using the chain rule

$$y' = \left(\frac{d}{dt} y(t)\right) t'(x)$$

- Compute derivative

$$y' = \frac{\frac{d}{dt} y(t)}{x}$$

- Calculate the 2nd derivative of y with respect to x , using the chain rule

$$y'' = \left(\frac{d^2}{dt^2} y(t)\right) t'(x)^2 + t''(x) \left(\frac{d}{dt} y(t)\right)$$

- Compute derivative

$$y'' = \frac{\frac{d^2}{dt^2} y(t)}{x^2} - \frac{\frac{d}{dt} y(t)}{x^2}$$

- Calculate the 3rd derivative of y with respect to x , using the chain rule

$$y''' = \left(\frac{d^3}{dt^3} y(t)\right) t'(x)^3 + 3t'(x) t''(x) \left(\frac{d^2}{dt^2} y(t)\right) + t'''(x) \left(\frac{d}{dt} y(t)\right)$$

- Compute derivative

$$y''' = \frac{\frac{d^3}{dt^3}y(t)}{x^3} - \frac{3\left(\frac{d^2}{dt^2}y(t)\right)}{x^3} + \frac{2\left(\frac{d}{dt}y(t)\right)}{x^3}$$

Substitute the change of variables back into the ODE

$$x^3 \left(\frac{\frac{d^3}{dt^3}y(t)}{x^3} - \frac{3\left(\frac{d^2}{dt^2}y(t)\right)}{x^3} + \frac{2\left(\frac{d}{dt}y(t)\right)}{x^3} \right) - \left(\frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2} \right) x^2 - 6\frac{d}{dt}y(t) + 18y(t) = 0$$

- Simplify

$$\frac{d^3}{dt^3}y(t) - 4\frac{d^2}{dt^2}y(t) - 3\frac{d}{dt}y(t) + 18y(t) = 0$$

- Convert linear ODE into a system of first order ODEs

- Define new variable $y_1(t)$

$$y_1(t) = y(t)$$

- Define new variable $y_2(t)$

$$y_2(t) = \frac{d}{dt}y(t)$$

- Define new variable $y_3(t)$

$$y_3(t) = \frac{d^2}{dt^2}y(t)$$

- Isolate for $\frac{d}{dt}y_3(t)$ using original ODE

$$\frac{d}{dt}y_3(t) = 4y_3(t) + 3y_2(t) - 18y_1(t)$$

Convert linear ODE into a system of first order ODEs

$$\left[y_2(t) = \frac{d}{dt}y_1(t), y_3(t) = \frac{d}{dt}y_2(t), \frac{d}{dt}y_3(t) = 4y_3(t) + 3y_2(t) - 18y_1(t) \right]$$

- Define vector

$$\vec{y}(t) = \begin{bmatrix} y_1(t) \\ y_2(t) \\ y_3(t) \end{bmatrix}$$

- System to solve

$$\frac{d}{dt}\vec{y}(t) = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -18 & 3 & 4 \end{bmatrix} \cdot \vec{y}(t)$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -18 & 3 & 4 \end{bmatrix}$$

- Rewrite the system as

$$\frac{d}{dt}\vec{y}(t) = A \cdot \vec{y}(t)$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[-2, \begin{bmatrix} \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix} \right], \left[3, \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix} \right], \left[3, \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[-2, \begin{bmatrix} \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{y}_1 = e^{-2t} \cdot \begin{bmatrix} \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix}$$

- Consider eigenpair, with eigenvalue of algebraic multiplicity 2

$$\left[3, \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix} \right]$$

- First solution from eigenvalue 3

$$\vec{y}_2(t) = e^{3t} \cdot \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix}$$

- Form of the 2nd homogeneous solution where \vec{p} is to be solved for, $\lambda = 3$ is the eigenvalue, and

$$\vec{y}_3(t) = e^{\lambda t} (t\vec{v} + \vec{p})$$

- Note that the t multiplying \vec{v} makes this solution linearly independent to the 1st solution obtained

- Substitute $\vec{y}_3(t)$ into the homogeneous system

$$\lambda e^{\lambda t} (t\vec{v} + \vec{p}) + e^{\lambda t} \vec{v} = (e^{\lambda t} A) \cdot (t\vec{v} + \vec{p})$$

- Use the fact that \vec{v} is an eigenvector of A

$$\lambda e^{\lambda t} (t\vec{v} + \vec{p}) + e^{\lambda t} \vec{v} = e^{\lambda t} (\lambda t\vec{v} + A \cdot \vec{p})$$

- Simplify equation

$$\lambda \vec{p} + \vec{v} = A \cdot \vec{p}$$

- Make use of the identity matrix I

$$(\lambda \cdot I) \cdot \vec{p} + \vec{v} = A \cdot \vec{p}$$

- Condition \vec{p} must meet for $\vec{y}_3(t)$ to be a solution to the homogeneous system

$$(A - \lambda \cdot I) \cdot \vec{p} = -\vec{v}$$

- Choose \vec{p} to use in the second solution to the homogeneous system from eigenvalue 3

$$\left(\begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -18 & 3 & 4 \end{bmatrix} - 3 \cdot \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \cdot \vec{p} = \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix}$$

- Choice of \vec{p}

$$\vec{p} = \begin{bmatrix} -\frac{1}{27} \\ 0 \\ 0 \end{bmatrix}$$

- Second solution from eigenvalue 3

$$\vec{y}_3(t) = e^{3t} \cdot \left(t \cdot \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix} + \begin{bmatrix} -\frac{1}{27} \\ 0 \\ 0 \end{bmatrix} \right)$$

- General solution to the system of ODEs

$$\vec{y} = c_1 \vec{y}_1 + c_2 \vec{y}_2(t) + c_3 \vec{y}_3(t)$$

- Substitute solutions into the general solution

$$\vec{y} = c_1 e^{-2t} \cdot \begin{bmatrix} \frac{1}{4} \\ -\frac{1}{2} \\ 1 \end{bmatrix} + c_2 e^{3t} \cdot \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix} + c_3 e^{3t} \cdot \left(t \cdot \begin{bmatrix} \frac{1}{9} \\ \frac{1}{3} \\ 1 \end{bmatrix} + \begin{bmatrix} -\frac{1}{27} \\ 0 \\ 0 \end{bmatrix} \right)$$

- First component of the vector is the solution to the ODE

$$y(t) = \frac{e^{-2t} \left(\left(t - \frac{1}{3} \right) c_3 + c_2 \right) e^{5t} + \frac{9c_1}{4}}{9}$$

- Change variables back using $t = \ln(x)$

$$y = \frac{\left((\ln(x) - \frac{1}{3}) c_3 + c_2 \right) x^5 + \frac{9c_1}{4}}{9x^2}$$

- Simplify

$$y = \frac{c_3 \ln(x) x^3}{9} + \frac{c_2 x^3}{9} - \frac{c_3 x^3}{27} + \frac{c_1}{4x^2}$$

Maple trace

```

`Methods for third order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
<- LODE of Euler type successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 22

```
dsolve(x^3*diff(y(x),x$3)-x^2*diff(y(x),x$2)-6*x*diff(y(x),x)+18*y(x)=0,y(x), singsol=all)
```

$$y(x) = \frac{c_3 x^5 \ln(x) + c_2 x^5 + c_1}{x^2}$$

✓ Solution by Mathematica

Time used: 0.004 (sec). Leaf size: 26

```
DSolve[x^3*y'''[x]-x^2*y''[x]-6*x*y'[x]+18*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{c_2 x^5 + c_3 x^5 \log(x) + c_1}{x^2}$$

13.14 problem 14

13.14.1 Solving as second order euler ode	3431
13.14.2 Solving as linear second order ode solved by an integrating factor ode	3434
13.14.3 Solving as second order change of variable on x method 2 ode .	3435
13.14.4 Solving as second order change of variable on x method 1 ode .	3440
13.14.5 Solving as second order change of variable on y method 1 ode .	3445
13.14.6 Solving as second order change of variable on y method 2 ode .	3449
13.14.7 Solving using Kovacic algorithm	3454

Internal problem ID [11868]

Internal file name [OUTPUT/11877_Saturday_April_13_2024_01_13_26_AM_73878653/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.5. The Cauchy-Euler Equation. Exercises page 169

Problem number: 14.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_euler_ode", "second_order_change_of_variable_on_x_method_1", "second_order_change_of_variable_on_x_method_2", "second_order_change_of_variable_on_y_method_1", "second_order_change_of_variable_on_y_method_2", "linear_second_order_ode_solved_by_an_integrating_factor"

Maple gives the following as the ode type

```
[[_2nd_order, _with_linear_symmetries]]
```

$$x^2y'' - 4y'x + 6y = 4x - 6$$

13.14.1 Solving as second order euler ode ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = x^2$, $B = -4x$, $C = 6$, $f(x) = 4x - 6$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. Solving for y_h from

$$x^2y'' - 4y'x + 6y = 0$$

This is Euler second order ODE. Let the solution be $y = x^r$, then $y' = rx^{r-1}$ and $y'' = r(r-1)x^{r-2}$. Substituting these back into the given ODE gives

$$x^2(r(r-1))x^{r-2} - 4rx^{r-1} + 6x^r = 0$$

Simplifying gives

$$r(r-1)x^r - 4rx^r + 6x^r = 0$$

Since $x^r \neq 0$ then dividing throughout by x^r gives

$$r(r-1) - 4r + 6 = 0$$

Or

$$r^2 - 5r + 6 = 0 \tag{1}$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = 2$$

$$r_2 = 3$$

Since the roots are real and distinct, then the general solution is

$$y = c_1y_1 + c_2y_2$$

Where $y_1 = x^{r_1}$ and $y_2 = x^{r_2}$. Hence

$$y = c_2x^3 + c_1x^2$$

Next, we find the particular solution to the ODE

$$x^2y'' - 4y'x + 6y = 4x - 6$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = x^2$$

$$y_2 = x^3$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} x^2 & x^3 \\ \frac{d}{dx}(x^2) & \frac{d}{dx}(x^3) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} x^2 & x^3 \\ 2x & 3x^2 \end{vmatrix}$$

Therefore

$$W = (x^2)(3x^2) - (x^3)(2x)$$

Which simplifies to

$$W = x^4$$

Which simplifies to

$$W = x^4$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{x^3(4x - 6)}{x^6} dx$$

Which simplifies to

$$u_1 = - \int \frac{4x - 6}{x^3} dx$$

Hence

$$u_1 = -\frac{3}{x^2} + \frac{4}{x}$$

And Eq. (3) becomes

$$u_2 = \int \frac{x^2(4x - 6)}{x^6} dx$$

Which simplifies to

$$u_2 = \int \frac{4x - 6}{x^4} dx$$

Hence

$$u_2 = -\frac{2}{x^2} + \frac{2}{x^3}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \left(-\frac{3}{x^2} + \frac{4}{x}\right)x^2 + \left(-\frac{2}{x^2} + \frac{2}{x^3}\right)x^3$$

Which simplifies to

$$y_p(x) = 2x - 1$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= c_2x^3 + c_1x^2 + 2x - 1 \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_2x^3 + c_1x^2 + 2x - 1 \quad (1)$$

Verification of solutions

$$y = c_2x^3 + c_1x^2 + 2x - 1$$

Verified OK.

13.14.2 Solving as linear second order ode solved by an integrating factor ode

The ode satisfies this form

$$y'' + p(x)y' + \frac{(p(x)^2 + p'(x))y}{2} = f(x)$$

Where $p(x) = -\frac{4}{x}$. Therefore, there is an integrating factor given by

$$\begin{aligned} M(x) &= e^{\frac{1}{2} \int p dx} \\ &= e^{\int -\frac{4}{x} dx} \\ &= \frac{1}{x^2} \end{aligned}$$

Multiplying both sides of the ODE by the integrating factor $M(x)$ makes the left side of the ODE a complete differential

$$\begin{aligned} (M(x)y)'' &= \frac{4x - 6}{x^4} \\ \left(\frac{y}{x^2}\right)'' &= \frac{4x - 6}{x^4} \end{aligned}$$

Integrating once gives

$$\left(\frac{y}{x^2}\right)' = \frac{-2x + 2}{x^3} + c_1$$

Integrating again gives

$$\left(\frac{y}{x^2}\right) = \frac{c_1x^3 + 2x - 1}{x^2} + c_2$$

Hence the solution is

$$y = \frac{\frac{c_1x^3 + 2x - 1}{x^2} + c_2}{\frac{1}{x^2}}$$

Or

$$y = c_1x^3 + c_2x^2 + 2x - 1$$

Summary

The solution(s) found are the following

$$y = c_1x^3 + c_2x^2 + 2x - 1 \quad (1)$$

Verification of solutions

$$y = c_1x^3 + c_2x^2 + 2x - 1$$

Verified OK.

13.14.3 Solving as second order change of variable on x method 2 ode

This is second order non-homogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$.
 y_h is the solution to

$$x^2y'' - 4y'x + 6y = 0$$

In normal form the ode

$$x^2y'' - 4y'x + 6y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = -\frac{4}{x}$$
$$q(x) = \frac{6}{x^2}$$

Applying change of variables $\tau = g(x)$ to (2) gives

$$\frac{d^2}{d\tau^2}y(\tau) + p_1\left(\frac{d}{d\tau}y(\tau)\right) + q_1y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $p_1 = 0$. Eq (4) simplifies to

$$\tau''(x) + p(x)\tau'(x) = 0$$

This ode is solved resulting in

$$\begin{aligned} \tau &= \int e^{-(\int p(x)dx)} dx \\ &= \int e^{-(\int -\frac{4}{x}dx)} dx \\ &= \int e^{4\ln(x)} dx \\ &= \int x^4 dx \\ &= \frac{x^5}{5} \end{aligned} \quad (6)$$

Using (6) to evaluate q_1 from (5) gives

$$\begin{aligned} q_1(\tau) &= \frac{q(x)}{\tau'(x)^2} \\ &= \frac{6}{x^2} \\ &= \frac{6}{x^{10}} \end{aligned} \quad (7)$$

Substituting the above in (3) and noting that now $p_1 = 0$ results in

$$\begin{aligned} \frac{d^2}{d\tau^2}y(\tau) + q_1y(\tau) &= 0 \\ \frac{d^2}{d\tau^2}y(\tau) + \frac{6y(\tau)}{x^{10}} &= 0 \end{aligned}$$

But in terms of τ

$$\frac{6}{x^{10}} = \frac{6}{25\tau^2}$$

Hence the above ode becomes

$$\frac{d^2}{d\tau^2}y(\tau) + \frac{6y(\tau)}{25\tau^2} = 0$$

The above ode is now solved for $y(\tau)$. The ode can be written as

$$25\left(\frac{d^2}{d\tau^2}y(\tau)\right)\tau^2 + 6y(\tau) = 0$$

Which shows it is a Euler ODE. This is Euler second order ODE. Let the solution be $y(\tau) = \tau^r$, then $y' = r\tau^{r-1}$ and $y'' = r(r-1)\tau^{r-2}$. Substituting these back into the given ODE gives

$$25\tau^2(r(r-1))\tau^{r-2} + 0r\tau^{r-1} + 6\tau^r = 0$$

Simplifying gives

$$25r(r-1)\tau^r + 0\tau^r + 6\tau^r = 0$$

Since $\tau^r \neq 0$ then dividing throughout by τ^r gives

$$25r(r-1) + 0 + 6 = 0$$

Or

$$25r^2 - 25r + 6 = 0 \tag{1}$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = \frac{2}{5}$$
$$r_2 = \frac{3}{5}$$

Since the roots are real and distinct, then the general solution is

$$y(\tau) = c_1y_1 + c_2y_2$$

Where $y_1 = \tau^{r_1}$ and $y_2 = \tau^{r_2}$. Hence

$$y(\tau) = c_1\tau^{\frac{2}{5}} + c_2\tau^{\frac{3}{5}}$$

The above solution is now transformed back to y using (6) which results in

$$y = \frac{c_15^{\frac{3}{5}}(x^5)^{\frac{2}{5}}}{5} + \frac{c_25^{\frac{2}{5}}(x^5)^{\frac{3}{5}}}{5}$$

Therefore the homogeneous solution y_h is

$$y_h = \frac{c_1 5^{\frac{3}{5}} (x^5)^{\frac{2}{5}}}{5} + \frac{c_2 5^{\frac{2}{5}} (x^5)^{\frac{3}{5}}}{5}$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = (x^5)^{\frac{2}{5}}$$

$$y_2 = (x^5)^{\frac{3}{5}}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} (x^5)^{\frac{2}{5}} & (x^5)^{\frac{3}{5}} \\ \frac{d}{dx} \left((x^5)^{\frac{2}{5}} \right) & \frac{d}{dx} \left((x^5)^{\frac{3}{5}} \right) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} (x^5)^{\frac{2}{5}} & (x^5)^{\frac{3}{5}} \\ \frac{2x^4}{(x^5)^{\frac{3}{5}}} & \frac{3x^4}{(x^5)^{\frac{2}{5}}} \end{vmatrix}$$

Therefore

$$W = \left((x^5)^{\frac{2}{5}} \right) \left(\frac{3x^4}{(x^5)^{\frac{2}{5}}} \right) - \left((x^5)^{\frac{3}{5}} \right) \left(\frac{2x^4}{(x^5)^{\frac{3}{5}}} \right)$$

Which simplifies to

$$W = x^4$$

Which simplifies to

$$W = x^4$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{(x^5)^{\frac{3}{5}} (4x - 6)}{x^6} dx$$

Which simplifies to

$$u_1 = - \int \frac{(x^5)^{\frac{3}{5}} (4x - 6)}{x^6} dx$$

Hence

$$u_1 = \frac{(x^5)^{\frac{3}{5}} (-3 + 4x)}{x^5}$$

And Eq. (3) becomes

$$u_2 = \int \frac{(x^5)^{\frac{2}{5}} (4x - 6)}{x^6} dx$$

Which simplifies to

$$u_2 = \int \frac{(x^5)^{\frac{2}{5}} (4x - 6)}{x^6} dx$$

Hence

$$u_2 = - \frac{2(x^5)^{\frac{2}{5}} (x - 1)}{x^5}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = 2x - 1$$

Therefore the general solution is

$$y = y_h + y_p \\ = \left(\frac{c_1 5^{\frac{3}{5}} (x^5)^{\frac{2}{5}}}{5} + \frac{c_2 5^{\frac{2}{5}} (x^5)^{\frac{3}{5}}}{5} \right) + (2x - 1)$$

Summary

The solution(s) found are the following

$$y = \frac{c_1 5^{\frac{3}{5}} (x^5)^{\frac{2}{5}}}{5} + \frac{c_2 5^{\frac{2}{5}} (x^5)^{\frac{3}{5}}}{5} + 2x - 1 \quad (1)$$

Verification of solutions

$$y = \frac{c_1 5^{\frac{3}{5}} (x^5)^{\frac{2}{5}}}{5} + \frac{c_2 5^{\frac{2}{5}} (x^5)^{\frac{3}{5}}}{5} + 2x - 1$$

Verified OK.

13.14.4 Solving as second order change of variable on x method 1 ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = x^2$, $B = -4x$, $C = 6$, $f(x) = 4x - 6$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. Solving for y_h from

$$x^2 y'' - 4y'x + 6y = 0$$

In normal form the ode

$$x^2 y'' - 4y'x + 6y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = -\frac{4}{x} \\ q(x) = \frac{6}{x^2}$$

Applying change of variables $\tau = g(x)$ to (2) results

$$\frac{d^2}{d\tau^2}y(\tau) + p_1\left(\frac{d}{d\tau}y(\tau)\right) + q_1y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $q_1 = c^2$ where c is some constant. Therefore from (5)

$$\begin{aligned} \tau' &= \frac{1}{c}\sqrt{q} \\ &= \frac{\sqrt{6}\sqrt{\frac{1}{x^2}}}{c} \\ \tau'' &= -\frac{\sqrt{6}}{c\sqrt{\frac{1}{x^2}}x^3} \end{aligned} \quad (6)$$

Substituting the above into (4) results in

$$\begin{aligned} p_1(\tau) &= \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \\ &= \frac{-\frac{\sqrt{6}}{c\sqrt{\frac{1}{x^2}}x^3} - \frac{4}{x}\frac{\sqrt{6}\sqrt{\frac{1}{x^2}}}{c}}{\left(\frac{\sqrt{6}\sqrt{\frac{1}{x^2}}}{c}\right)^2} \\ &= -\frac{5c\sqrt{6}}{6} \end{aligned}$$

Therefore ode (3) now becomes

$$\begin{aligned} y(\tau)'' + p_1y(\tau)' + q_1y(\tau) &= 0 \\ \frac{d^2}{d\tau^2}y(\tau) - \frac{5c\sqrt{6}}{6}\left(\frac{d}{d\tau}y(\tau)\right) + c^2y(\tau) &= 0 \end{aligned} \quad (7)$$

The above ode is now solved for $y(\tau)$. Since the ode is now constant coefficients, it can be easily solved to give

$$y(\tau) = e^{\frac{5\sqrt{6}c\tau}{12}} \left(c_1 \cosh\left(\frac{\sqrt{6}c\tau}{12}\right) + ic_2 \sinh\left(\frac{\sqrt{6}c\tau}{12}\right) \right)$$

Now from (6)

$$\begin{aligned}\tau &= \int \frac{1}{c} \sqrt{q} dx \\ &= \frac{\int \sqrt{6} \sqrt{\frac{1}{x^2}} dx}{c} \\ &= \frac{\sqrt{6} \sqrt{\frac{1}{x^2}} x \ln(x)}{c}\end{aligned}$$

Substituting the above into the solution obtained gives

$$y = x^{\frac{5}{2}} \left(c_1 \cosh \left(\frac{\ln(x)}{2} \right) + ic_2 \sinh \left(\frac{\ln(x)}{2} \right) \right)$$

Now the particular solution to this ODE is found

$$x^2 y'' - 4y'x + 6y = 4x - 6$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = (x^5)^{\frac{2}{5}}$$

$$y_2 = (x^5)^{\frac{3}{5}}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \tag{2}$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \tag{3}$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} (x^5)^{\frac{2}{5}} & (x^5)^{\frac{3}{5}} \\ \frac{d}{dx} \left((x^5)^{\frac{2}{5}} \right) & \frac{d}{dx} \left((x^5)^{\frac{3}{5}} \right) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} (x^5)^{\frac{2}{5}} & (x^5)^{\frac{3}{5}} \\ \frac{2x^4}{(x^5)^{\frac{3}{5}}} & \frac{3x^4}{(x^5)^{\frac{2}{5}}} \end{vmatrix}$$

Therefore

$$W = \left((x^5)^{\frac{2}{5}} \right) \left(\frac{3x^4}{(x^5)^{\frac{2}{5}}} \right) - \left((x^5)^{\frac{3}{5}} \right) \left(\frac{2x^4}{(x^5)^{\frac{3}{5}}} \right)$$

Which simplifies to

$$W = x^4$$

Which simplifies to

$$W = x^4$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{(x^5)^{\frac{3}{5}} (4x - 6)}{x^6} dx$$

Which simplifies to

$$u_1 = - \int \frac{(x^5)^{\frac{3}{5}} (4x - 6)}{x^6} dx$$

Hence

$$u_1 = \frac{(x^5)^{\frac{3}{5}} (-3 + 4x)}{x^5}$$

And Eq. (3) becomes

$$u_2 = \int \frac{(x^5)^{\frac{2}{5}} (4x - 6)}{x^6} dx$$

Which simplifies to

$$u_2 = \int \frac{(x^5)^{\frac{2}{5}} (4x - 6)}{x^6} dx$$

Hence

$$u_2 = -\frac{2(x^5)^{\frac{2}{5}} (x - 1)}{x^5}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = 2x - 1$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(x^{\frac{5}{2}} \left(c_1 \cosh \left(\frac{\ln(x)}{2} \right) + i c_2 \sinh \left(\frac{\ln(x)}{2} \right) \right) \right) + (2x - 1) \\ &= 2x - 1 + x^{\frac{5}{2}} \left(c_1 \cosh \left(\frac{\ln(x)}{2} \right) + i c_2 \sinh \left(\frac{\ln(x)}{2} \right) \right) \end{aligned}$$

Which simplifies to

$$y = i x^{\frac{5}{2}} \sinh \left(\frac{\ln(x)}{2} \right) c_2 + x^{\frac{5}{2}} \cosh \left(\frac{\ln(x)}{2} \right) c_1 + 2x - 1$$

Summary

The solution(s) found are the following

$$y = i x^{\frac{5}{2}} \sinh \left(\frac{\ln(x)}{2} \right) c_2 + x^{\frac{5}{2}} \cosh \left(\frac{\ln(x)}{2} \right) c_1 + 2x - 1 \quad (1)$$

Verification of solutions

$$y = i x^{\frac{5}{2}} \sinh \left(\frac{\ln(x)}{2} \right) c_2 + x^{\frac{5}{2}} \cosh \left(\frac{\ln(x)}{2} \right) c_1 + 2x - 1$$

Verified OK.

13.14.5 Solving as second order change of variable on y method 1 ode

This is second order non-homogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$x^2y'' - 4y'x + 6y = 0$$

In normal form the given ode is written as

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = -\frac{4}{x}$$
$$q(x) = \frac{6}{x^2}$$

Calculating the Liouville ode invariant Q given by

$$\begin{aligned} Q &= q - \frac{p'}{2} - \frac{p^2}{4} \\ &= \frac{6}{x^2} - \frac{\left(-\frac{4}{x}\right)'}{2} - \frac{\left(-\frac{4}{x}\right)^2}{4} \\ &= \frac{6}{x^2} - \frac{\left(\frac{4}{x^2}\right)}{2} - \frac{\left(\frac{16}{x^2}\right)}{4} \\ &= \frac{6}{x^2} - \left(\frac{2}{x^2}\right) - \frac{4}{x^2} \\ &= 0 \end{aligned}$$

Since the Liouville ode invariant does not depend on the independent variable x then the transformation

$$y = v(x)z(x) \quad (3)$$

is used to change the original ode to a constant coefficients ode in v . In (3) the term $z(x)$ is given by

$$\begin{aligned} z(x) &= e^{-\left(\int \frac{p(x)}{2} dx\right)} \\ &= e^{-\int \frac{-4}{2x} dx} \\ &= x^2 \end{aligned} \quad (5)$$

Hence (3) becomes

$$y = v(x) x^2 \quad (4)$$

Applying this change of variable to the original ode results in

$$x^4 v''(x) = 4x - 6$$

Which is now solved for $v(x)$ Simplifying the ode gives

$$v''(x) = \frac{4x - 6}{x^4}$$

Integrating once gives

$$v'(x) = -\frac{2}{x^2} + \frac{2}{x^3} + c_1$$

Integrating again gives

$$v(x) = \frac{2}{x} - \frac{1}{x^2} + c_1 x + c_2$$

Now that $v(x)$ is known, then

$$\begin{aligned} y &= v(x) z(x) \\ &= \left(c_1 x + \frac{2}{x} - \frac{1}{x^2} + c_2 \right) (z(x)) \end{aligned} \quad (7)$$

But from (5)

$$z(x) = x^2$$

Hence (7) becomes

$$y = \left(c_1 x + \frac{2}{x} - \frac{1}{x^2} + c_2 \right) x^2$$

Therefore the homogeneous solution y_h is

$$y_h = \left(c_1 x + \frac{2}{x} - \frac{1}{x^2} + c_2 \right) x^2$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = (x^5)^{\frac{2}{5}}$$

$$y_2 = (x^5)^{\frac{3}{5}}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} (x^5)^{\frac{2}{5}} & (x^5)^{\frac{3}{5}} \\ \frac{d}{dx} \left((x^5)^{\frac{2}{5}} \right) & \frac{d}{dx} \left((x^5)^{\frac{3}{5}} \right) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} (x^5)^{\frac{2}{5}} & (x^5)^{\frac{3}{5}} \\ \frac{2x^4}{(x^5)^{\frac{3}{5}}} & \frac{3x^4}{(x^5)^{\frac{2}{5}}} \end{vmatrix}$$

Therefore

$$W = \left((x^5)^{\frac{2}{5}} \right) \left(\frac{3x^4}{(x^5)^{\frac{2}{5}}} \right) - \left((x^5)^{\frac{3}{5}} \right) \left(\frac{2x^4}{(x^5)^{\frac{3}{5}}} \right)$$

Which simplifies to

$$W = x^4$$

Which simplifies to

$$W = x^4$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{(x^5)^{\frac{3}{5}} (4x - 6)}{x^6} dx$$

Which simplifies to

$$u_1 = - \int \frac{(x^5)^{\frac{3}{5}} (4x - 6)}{x^6} dx$$

Hence

$$u_1 = \frac{(x^5)^{\frac{3}{5}} (-3 + 4x)}{x^5}$$

And Eq. (3) becomes

$$u_2 = \int \frac{(x^5)^{\frac{2}{5}} (4x - 6)}{x^6} dx$$

Which simplifies to

$$u_2 = \int \frac{(x^5)^{\frac{2}{5}} (4x - 6)}{x^6} dx$$

Hence

$$u_2 = - \frac{2(x^5)^{\frac{2}{5}} (x - 1)}{x^5}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = 2x - 1$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(\left(c_1 x + \frac{2}{x} - \frac{1}{x^2} + c_2 \right) x^2 \right) + (2x - 1) \end{aligned}$$

Which simplifies to

$$y = c_1 x^3 + c_2 x^2 + 4x - 2$$

Summary

The solution(s) found are the following

$$y = c_1x^3 + c_2x^2 + 4x - 2 \quad (1)$$

Verification of solutions

$$y = c_1x^3 + c_2x^2 + 4x - 2$$

Verified OK.

13.14.6 Solving as second order change of variable on y method 2 ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = x^2$, $B = -4x$, $C = 6$, $f(x) = 4x - 6$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. Solving for y_h from

$$x^2y'' - 4y'x + 6y = 0$$

In normal form the ode

$$x^2y'' - 4y'x + 6y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = -\frac{4}{x}$$
$$q(x) = \frac{6}{x^2}$$

Applying change of variables on the dependent variable $y = v(x)x^n$ to (2) gives the following ode where the dependent variables is $v(x)$ and not y .

$$v''(x) + \left(\frac{2n}{x} + p\right)v'(x) + \left(\frac{n(n-1)}{x^2} + \frac{np}{x} + q\right)v(x) = 0 \quad (3)$$

Let the coefficient of $v(x)$ above be zero. Hence

$$\frac{n(n-1)}{x^2} + \frac{np}{x} + q = 0 \quad (4)$$

Substituting the earlier values found for $p(x)$ and $q(x)$ into (4) gives

$$\frac{n(n-1)}{x^2} - \frac{4n}{x^2} + \frac{6}{x^2} = 0 \quad (5)$$

Solving (5) for n gives

$$n = 3 \quad (6)$$

Substituting this value in (3) gives

$$\begin{aligned} v''(x) + \frac{2v'(x)}{x} &= 0 \\ v''(x) + \frac{2v'(x)}{x} &= 0 \end{aligned} \quad (7)$$

Using the substitution

$$u(x) = v'(x)$$

Then (7) becomes

$$u'(x) + \frac{2u(x)}{x} = 0 \quad (8)$$

The above is now solved for $u(x)$. In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= -\frac{2u}{x} \end{aligned}$$

Where $f(x) = -\frac{2}{x}$ and $g(u) = u$. Integrating both sides gives

$$\begin{aligned} \frac{1}{u} du &= -\frac{2}{x} dx \\ \int \frac{1}{u} du &= \int -\frac{2}{x} dx \\ \ln(u) &= -2 \ln(x) + c_1 \\ u &= e^{-2 \ln(x) + c_1} \\ &= \frac{c_1}{x^2} \end{aligned}$$

Now that $u(x)$ is known, then

$$\begin{aligned}v'(x) &= u(x) \\v(x) &= \int u(x) dx + c_2 \\&= -\frac{c_1}{x} + c_2\end{aligned}$$

Hence

$$\begin{aligned}y &= v(x) x^n \\&= \left(-\frac{c_1}{x} + c_2\right) x^3 \\&= x^2(c_2x - c_1)\end{aligned}$$

Now the particular solution to this ODE is found

$$x^2y'' - 4y'x + 6y = 4x - 6$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1y_1 + u_2y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$\begin{aligned}y_1 &= x^2 \\y_2 &= x^3\end{aligned}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \tag{2}$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \tag{3}$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} x^2 & x^3 \\ \frac{d}{dx}(x^2) & \frac{d}{dx}(x^3) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} x^2 & x^3 \\ 2x & 3x^2 \end{vmatrix}$$

Therefore

$$W = (x^2)(3x^2) - (x^3)(2x)$$

Which simplifies to

$$W = x^4$$

Which simplifies to

$$W = x^4$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{x^3(4x - 6)}{x^6} dx$$

Which simplifies to

$$u_1 = - \int \frac{4x - 6}{x^3} dx$$

Hence

$$u_1 = -\frac{3}{x^2} + \frac{4}{x}$$

And Eq. (3) becomes

$$u_2 = \int \frac{x^2(4x - 6)}{x^6} dx$$

Which simplifies to

$$u_2 = \int \frac{4x - 6}{x^4} dx$$

Hence

$$u_2 = -\frac{2}{x^2} + \frac{2}{x^3}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \left(-\frac{3}{x^2} + \frac{4}{x}\right)x^2 + \left(-\frac{2}{x^2} + \frac{2}{x^3}\right)x^3$$

Which simplifies to

$$y_p(x) = 2x - 1$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(\left(-\frac{c_1}{x} + c_2\right)x^3\right) + (2x - 1) \\ &= 2x - 1 + \left(-\frac{c_1}{x} + c_2\right)x^3 \end{aligned}$$

Which simplifies to

$$y = c_2x^3 - c_1x^2 + 2x - 1$$

Summary

The solution(s) found are the following

$$y = c_2x^3 - c_1x^2 + 2x - 1 \tag{1}$$

Verification of solutions

$$y = c_2x^3 - c_1x^2 + 2x - 1$$

Verified OK.

13.14.7 Solving using Kovacic algorithm

Writing the ode as

$$x^2 y'' - 4y'x + 6y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= x^2 \\ B &= -4x \\ C &= 6 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{0}{1} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 0 \\ t &= 1 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = 0 \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 491: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - -\infty \\ &= \infty \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is *infinity* then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = 0$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = 1$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-4x}{x^2} dx} \end{aligned}$$

$$\begin{aligned}
&= z_1 e^{2\ln(x)} \\
&= z_1 (x^2)
\end{aligned}$$

Which simplifies to

$$y_1 = x^2$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}
y_2 &= y_1 \int \frac{e^{\int -\frac{-4x}{x^2} dx}}{(y_1)^2} dx \\
&= y_1 \int \frac{e^{4\ln(x)}}{(y_1)^2} dx \\
&= y_1(x)
\end{aligned}$$

Therefore the solution is

$$\begin{aligned}
y &= c_1 y_1 + c_2 y_2 \\
&= c_1 (x^2) + c_2 (x^2(x))
\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$x^2 y'' - 4y'x + 6y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_2 x^3 + c_1 x^2$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = x^2$$

$$y_2 = x^3$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} x^2 & x^3 \\ \frac{d}{dx}(x^2) & \frac{d}{dx}(x^3) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} x^2 & x^3 \\ 2x & 3x^2 \end{vmatrix}$$

Therefore

$$W = (x^2)(3x^2) - (x^3)(2x)$$

Which simplifies to

$$W = x^4$$

Which simplifies to

$$W = x^4$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{x^3(4x - 6)}{x^6} dx$$

Which simplifies to

$$u_1 = - \int \frac{4x - 6}{x^3} dx$$

Hence

$$u_1 = -\frac{3}{x^2} + \frac{4}{x}$$

And Eq. (3) becomes

$$u_2 = \int \frac{x^2(4x - 6)}{x^6} dx$$

Which simplifies to

$$u_2 = \int \frac{4x - 6}{x^4} dx$$

Hence

$$u_2 = -\frac{2}{x^2} + \frac{2}{x^3}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \left(-\frac{3}{x^2} + \frac{4}{x}\right)x^2 + \left(-\frac{2}{x^2} + \frac{2}{x^3}\right)x^3$$

Which simplifies to

$$y_p(x) = 2x - 1$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_2x^3 + c_1x^2) + (2x - 1) \end{aligned}$$

Which simplifies to

$$y = x^2(c_2x + c_1) + 2x - 1$$

Summary

The solution(s) found are the following

$$y = x^2(c_2x + c_1) + 2x - 1 \quad (1)$$

Verification of solutions

$$y = x^2(c_2x + c_1) + 2x - 1$$

Verified OK.

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]  
trying a double symmetry of the form [xi=0, eta=F(x)]  
-> Try solving first the homogeneous part of the ODE  
    checking if the LODE has constant coefficients  
    checking if the LODE is of Euler type  
    <- LODE of Euler type successful  
<- solving first the homogeneous part of the ODE successful`
```

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 19

```
dsolve(x^2*diff(y(x),x$2)-4*x*diff(y(x),x)+6*y(x)=4*x-6,y(x), singsol=all)
```

$$y(x) = c_1x^3 + c_2x^2 + 2x - 1$$

✓ Solution by Mathematica

Time used: 0.02 (sec). Leaf size: 22

```
DSolve[x^2*y''[x]-4*x*y'[x]+6*y[x]==4*x-6,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow c_2x^3 + c_1x^2 + 2x - 1$$

13.15 problem 15

13.15.1 Solving as second order euler ode ode	3460
13.15.2 Solving as second order change of variable on x method 2 ode .	3463
13.15.3 Solving as second order change of variable on x method 1 ode .	3468
13.15.4 Solving as second order change of variable on y method 2 ode .	3473
13.15.5 Solving using Kovacic algorithm	3478

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Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.5. The Cauchy-Euler Equation. Exercises page 169

Problem number: 15.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_euler_ode", "second_order_change_of_variable_on_x_method_1", "second_order_change_of_variable_on_x_method_2", "second_order_change_of_variable_on_y_method_2"

Maple gives the following as the ode type

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[[_2nd_order , _with_linear_symmetries]]
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$$x^2y'' - 5y'x + 8y = 2x^3$$

13.15.1 Solving as second order euler ode ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = x^2, B = -5x, C = 8, f(x) = 2x^3$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. Solving for y_h from

$$x^2y'' - 5y'x + 8y = 0$$

This is Euler second order ODE. Let the solution be $y = x^r$, then $y' = rx^{r-1}$ and $y'' = r(r-1)x^{r-2}$. Substituting these back into the given ODE gives

$$x^2(r(r-1))x^{r-2} - 5rxr^{r-1} + 8x^r = 0$$

Simplifying gives

$$r(r-1)x^r - 5rx^r + 8x^r = 0$$

Since $x^r \neq 0$ then dividing throughout by x^r gives

$$r(r-1) - 5r + 8 = 0$$

Or

$$r^2 - 6r + 8 = 0 \tag{1}$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = 2$$

$$r_2 = 4$$

Since the roots are real and distinct, then the general solution is

$$y = c_1y_1 + c_2y_2$$

Where $y_1 = x^{r_1}$ and $y_2 = x^{r_2}$. Hence

$$y = c_2x^4 + c_1x^2$$

Next, we find the particular solution to the ODE

$$x^2y'' - 5y'x + 8y = 2x^3$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1y_1 + u_2y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = x^2$$

$$y_2 = x^4$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} x^2 & x^4 \\ \frac{d}{dx}(x^2) & \frac{d}{dx}(x^4) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} x^2 & x^4 \\ 2x & 4x^3 \end{vmatrix}$$

Therefore

$$W = (x^2)(4x^3) - (x^4)(2x)$$

Which simplifies to

$$W = 2x^5$$

Which simplifies to

$$W = 2x^5$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{2x^7}{2x^5} dx$$

Which simplifies to

$$u_1 = - \int 1 dx$$

Hence

$$u_1 = -x$$

And Eq. (3) becomes

$$u_2 = \int \frac{2x^5}{2x^7} dx$$

Which simplifies to

$$u_2 = \int \frac{1}{x^2} dx$$

Hence

$$u_2 = -\frac{1}{x}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = -2x^3$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= x^2(c_2x^2 + c_1 - 2x) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = x^2(c_2x^2 + c_1 - 2x) \quad (1)$$

Verification of solutions

$$y = x^2(c_2x^2 + c_1 - 2x)$$

Verified OK.

13.15.2 Solving as second order change of variable on x method 2 ode

This is second order non-homogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$.
 y_h is the solution to

$$x^2y'' - 5y'x + 8y = 0$$

In normal form the ode

$$x^2 y'' - 5y'x + 8y = 0 \quad (1)$$

Becomes

$$y'' + p(x) y' + q(x) y = 0 \quad (2)$$

Where

$$p(x) = -\frac{5}{x}$$
$$q(x) = \frac{8}{x^2}$$

Applying change of variables $\tau = g(x)$ to (2) gives

$$\frac{d^2}{d\tau^2} y(\tau) + p_1 \left(\frac{d}{d\tau} y(\tau) \right) + q_1 y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x) \tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $p_1 = 0$. Eq (4) simplifies to

$$\tau''(x) + p(x) \tau'(x) = 0$$

This ode is solved resulting in

$$\begin{aligned} \tau &= \int e^{-(\int p(x) dx)} dx \\ &= \int e^{-(\int -\frac{5}{x} dx)} dx \\ &= \int e^{5 \ln(x)} dx \\ &= \int x^5 dx \\ &= \frac{x^6}{6} \end{aligned} \quad (6)$$

Using (6) to evaluate q_1 from (5) gives

$$\begin{aligned} q_1(\tau) &= \frac{q(x)}{\tau'(x)^2} \\ &= \frac{\frac{8}{x^2}}{x^{10}} \\ &= \frac{8}{x^{12}} \end{aligned} \tag{7}$$

Substituting the above in (3) and noting that now $p_1 = 0$ results in

$$\begin{aligned} \frac{d^2}{d\tau^2}y(\tau) + q_1y(\tau) &= 0 \\ \frac{d^2}{d\tau^2}y(\tau) + \frac{8y(\tau)}{x^{12}} &= 0 \end{aligned}$$

But in terms of τ

$$\frac{8}{x^{12}} = \frac{2}{9\tau^2}$$

Hence the above ode becomes

$$\frac{d^2}{d\tau^2}y(\tau) + \frac{2y(\tau)}{9\tau^2} = 0$$

The above ode is now solved for $y(\tau)$. The ode can be written as

$$9\left(\frac{d^2}{d\tau^2}y(\tau)\right)\tau^2 + 2y(\tau) = 0$$

Which shows it is a Euler ODE. This is Euler second order ODE. Let the solution be $y(\tau) = \tau^r$, then $y' = r\tau^{r-1}$ and $y'' = r(r-1)\tau^{r-2}$. Substituting these back into the given ODE gives

$$9\tau^2(r(r-1))\tau^{r-2} + 0r\tau^{r-1} + 2\tau^r = 0$$

Simplifying gives

$$9r(r-1)\tau^r + 0\tau^r + 2\tau^r = 0$$

Since $\tau^r \neq 0$ then dividing throughout by τ^r gives

$$9r(r-1) + 0 + 2 = 0$$

Or

$$9r^2 - 9r + 2 = 0 \tag{1}$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = \frac{1}{3}$$

$$r_2 = \frac{2}{3}$$

Since the roots are real and distinct, then the general solution is

$$y(\tau) = c_1 y_1 + c_2 y_2$$

Where $y_1 = \tau^{r_1}$ and $y_2 = \tau^{r_2}$. Hence

$$y(\tau) = c_1 \tau^{\frac{1}{3}} + c_2 \tau^{\frac{2}{3}}$$

The above solution is now transformed back to y using (6) which results in

$$y = \frac{c_1 6^{\frac{2}{3}} (x^6)^{\frac{1}{3}}}{6} + \frac{c_2 6^{\frac{1}{3}} (x^6)^{\frac{2}{3}}}{6}$$

Therefore the homogeneous solution y_h is

$$y_h = \frac{c_1 6^{\frac{2}{3}} (x^6)^{\frac{1}{3}}}{6} + \frac{c_2 6^{\frac{1}{3}} (x^6)^{\frac{2}{3}}}{6}$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = (x^6)^{\frac{1}{3}}$$

$$y_2 = (x^6)^{\frac{2}{3}}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \tag{2}$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \tag{3}$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} (x^6)^{\frac{1}{3}} & (x^6)^{\frac{2}{3}} \\ \frac{d}{dx} \left((x^6)^{\frac{1}{3}} \right) & \frac{d}{dx} \left((x^6)^{\frac{2}{3}} \right) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} (x^6)^{\frac{1}{3}} & (x^6)^{\frac{2}{3}} \\ \frac{2x^5}{(x^6)^{\frac{2}{3}}} & \frac{4x^5}{(x^6)^{\frac{1}{3}}} \end{vmatrix}$$

Therefore

$$W = \left((x^6)^{\frac{1}{3}} \right) \left(\frac{4x^5}{(x^6)^{\frac{1}{3}}} \right) - \left((x^6)^{\frac{2}{3}} \right) \left(\frac{2x^5}{(x^6)^{\frac{2}{3}}} \right)$$

Which simplifies to

$$W = 2x^5$$

Which simplifies to

$$W = 2x^5$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{2(x^6)^{\frac{2}{3}} x^3}{2x^7} dx$$

Which simplifies to

$$u_1 = - \int \frac{(x^6)^{\frac{2}{3}}}{x^4} dx$$

Hence

$$u_1 = - \frac{(x^6)^{\frac{2}{3}}}{x^3}$$

And Eq. (3) becomes

$$u_2 = \int \frac{2(x^6)^{\frac{1}{3}} x^3}{2x^7} dx$$

Which simplifies to

$$u_2 = \int \frac{(x^6)^{\frac{1}{3}}}{x^4} dx$$

Hence

$$u_2 = -\frac{(x^6)^{\frac{1}{3}}}{x^3}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = -2x^3$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(\frac{c_1 6^{\frac{2}{3}} (x^6)^{\frac{1}{3}}}{6} + \frac{c_2 6^{\frac{1}{3}} (x^6)^{\frac{2}{3}}}{6} \right) + (-2x^3) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = \frac{c_1 6^{\frac{2}{3}} (x^6)^{\frac{1}{3}}}{6} + \frac{c_2 6^{\frac{1}{3}} (x^6)^{\frac{2}{3}}}{6} - 2x^3 \quad (1)$$

Verification of solutions

$$y = \frac{c_1 6^{\frac{2}{3}} (x^6)^{\frac{1}{3}}}{6} + \frac{c_2 6^{\frac{1}{3}} (x^6)^{\frac{2}{3}}}{6} - 2x^3$$

Verified OK.

13.15.3 Solving as second order change of variable on x method 1 ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = x^2$, $B = -5x$, $C = 8$, $f(x) = 2x^3$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. Solving for y_h from

$$x^2y'' - 5y'x + 8y = 0$$

In normal form the ode

$$x^2y'' - 5y'x + 8y = 0 \tag{1}$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \tag{2}$$

Where

$$p(x) = -\frac{5}{x}$$

$$q(x) = \frac{8}{x^2}$$

Applying change of variables $\tau = g(x)$ to (2) results

$$\frac{d^2}{d\tau^2}y(\tau) + p_1\left(\frac{d}{d\tau}y(\tau)\right) + q_1y(\tau) = 0 \tag{3}$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \tag{4}$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \tag{5}$$

Let $q_1 = c^2$ where c is some constant. Therefore from (5)

$$\tau' = \frac{1}{c}\sqrt{q}$$

$$= \frac{2\sqrt{2}\sqrt{\frac{1}{x^2}}}{c} \tag{6}$$

$$\tau'' = -\frac{2\sqrt{2}}{c\sqrt{\frac{1}{x^2}}x^3}$$

Substituting the above into (4) results in

$$\begin{aligned}
 p_1(\tau) &= \frac{\tau''(x) + p(x) \tau'(x)}{\tau'(x)^2} \\
 &= \frac{-\frac{2\sqrt{2}}{c\sqrt{\frac{1}{x^2}} x^3} - \frac{5}{x} \frac{2\sqrt{2}\sqrt{\frac{1}{x^2}}}{c}}{\left(\frac{2\sqrt{2}\sqrt{\frac{1}{x^2}}}{c}\right)^2} \\
 &= -\frac{3c\sqrt{2}}{2}
 \end{aligned}$$

Therefore ode (3) now becomes

$$\begin{aligned}
 y(\tau)'' + p_1 y(\tau)' + q_1 y(\tau) &= 0 \\
 \frac{d^2}{d\tau^2} y(\tau) - \frac{3c\sqrt{2}}{2} \left(\frac{d}{d\tau} y(\tau)\right) + c^2 y(\tau) &= 0
 \end{aligned} \tag{7}$$

The above ode is now solved for $y(\tau)$. Since the ode is now constant coefficients, it can be easily solved to give

$$y(\tau) = e^{\frac{3\sqrt{2}c\tau}{4}} \left(c_1 \cosh\left(\frac{\sqrt{2}c\tau}{4}\right) + ic_2 \sinh\left(\frac{\sqrt{2}c\tau}{4}\right) \right)$$

Now from (6)

$$\begin{aligned}
 \tau &= \int \frac{1}{c} \sqrt{q} dx \\
 &= \frac{\int 2\sqrt{2} \sqrt{\frac{1}{x^2}} dx}{c} \\
 &= \frac{2\sqrt{2} \sqrt{\frac{1}{x^2}} x \ln(x)}{c}
 \end{aligned}$$

Substituting the above into the solution obtained gives

$$y = \frac{((ic_2 + c_1) x^2 - ic_2 + c_1) x^2}{2}$$

Now the particular solution to this ODE is found

$$x^2 y'' - 5y'x + 8y = 2x^3$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of

parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = (x^6)^{\frac{1}{3}}$$

$$y_2 = (x^6)^{\frac{2}{3}}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} (x^6)^{\frac{1}{3}} & (x^6)^{\frac{2}{3}} \\ \frac{d}{dx} \left((x^6)^{\frac{1}{3}} \right) & \frac{d}{dx} \left((x^6)^{\frac{2}{3}} \right) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} (x^6)^{\frac{1}{3}} & (x^6)^{\frac{2}{3}} \\ \frac{2x^5}{(x^6)^{\frac{2}{3}}} & \frac{4x^5}{(x^6)^{\frac{1}{3}}} \end{vmatrix}$$

Therefore

$$W = \left((x^6)^{\frac{1}{3}} \right) \left(\frac{4x^5}{(x^6)^{\frac{1}{3}}} \right) - \left((x^6)^{\frac{2}{3}} \right) \left(\frac{2x^5}{(x^6)^{\frac{2}{3}}} \right)$$

Which simplifies to

$$W = 2x^5$$

Which simplifies to

$$W = 2x^5$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{2(x^6)^{\frac{2}{3}} x^3}{2x^7} dx$$

Which simplifies to

$$u_1 = - \int \frac{(x^6)^{\frac{2}{3}}}{x^4} dx$$

Hence

$$u_1 = - \frac{(x^6)^{\frac{2}{3}}}{x^3}$$

And Eq. (3) becomes

$$u_2 = \int \frac{2(x^6)^{\frac{1}{3}} x^3}{2x^7} dx$$

Which simplifies to

$$u_2 = \int \frac{(x^6)^{\frac{1}{3}}}{x^4} dx$$

Hence

$$u_2 = - \frac{(x^6)^{\frac{1}{3}}}{x^3}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = -2x^3$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(\frac{((ic_2 + c_1)x^2 - ic_2 + c_1)x^2}{2} \right) + (-2x^3) \\ &= -2x^3 + \frac{((ic_2 + c_1)x^2 - ic_2 + c_1)x^2}{2} \end{aligned}$$

Which simplifies to

$$y = \frac{x^2((ic_2 + c_1)x^2 - 4x - ic_2 + c_1)}{2}$$

Summary

The solution(s) found are the following

$$y = \frac{x^2((ic_2 + c_1)x^2 - 4x - ic_2 + c_1)}{2} \quad (1)$$

Verification of solutions

$$y = \frac{x^2((ic_2 + c_1)x^2 - 4x - ic_2 + c_1)}{2}$$

Verified OK.

13.15.4 Solving as second order change of variable on y method 2 ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = x^2$, $B = -5x$, $C = 8$, $f(x) = 2x^3$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. Solving for y_h from

$$x^2y'' - 5y'x + 8y = 0$$

In normal form the ode

$$x^2y'' - 5y'x + 8y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = -\frac{5}{x}$$
$$q(x) = \frac{8}{x^2}$$

Applying change of variables on the dependent variable $y = v(x)x^n$ to (2) gives the following ode where the dependent variables is $v(x)$ and not y .

$$v''(x) + \left(\frac{2n}{x} + p\right)v'(x) + \left(\frac{n(n-1)}{x^2} + \frac{np}{x} + q\right)v(x) = 0 \quad (3)$$

Let the coefficient of $v(x)$ above be zero. Hence

$$\frac{n(n-1)}{x^2} + \frac{np}{x} + q = 0 \quad (4)$$

Substituting the earlier values found for $p(x)$ and $q(x)$ into (4) gives

$$\frac{n(n-1)}{x^2} - \frac{5n}{x^2} + \frac{8}{x^2} = 0 \quad (5)$$

Solving (5) for n gives

$$n = 4 \quad (6)$$

Substituting this value in (3) gives

$$\begin{aligned} v''(x) + \frac{3v'(x)}{x} &= 0 \\ v''(x) + \frac{3v'(x)}{x} &= 0 \end{aligned} \quad (7)$$

Using the substitution

$$u(x) = v'(x)$$

Then (7) becomes

$$u'(x) + \frac{3u(x)}{x} = 0 \quad (8)$$

The above is now solved for $u(x)$. In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= -\frac{3u}{x} \end{aligned}$$

Where $f(x) = -\frac{3}{x}$ and $g(u) = u$. Integrating both sides gives

$$\begin{aligned}\frac{1}{u} du &= -\frac{3}{x} dx \\ \int \frac{1}{u} du &= \int -\frac{3}{x} dx \\ \ln(u) &= -3 \ln(x) + c_1 \\ u &= e^{-3 \ln(x) + c_1} \\ &= \frac{c_1}{x^3}\end{aligned}$$

Now that $u(x)$ is known, then

$$\begin{aligned}v'(x) &= u(x) \\ v(x) &= \int u(x) dx + c_2 \\ &= -\frac{c_1}{2x^2} + c_2\end{aligned}$$

Hence

$$\begin{aligned}y &= v(x) x^n \\ &= \left(-\frac{c_1}{2x^2} + c_2\right) x^4 \\ &= c_2 x^4 - \frac{1}{2} c_1 x^2\end{aligned}$$

Now the particular solution to this ODE is found

$$x^2 y'' - 5y'x + 8y = 2x^3$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$\begin{aligned}y_1 &= x^2 \\ y_2 &= x^4\end{aligned}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} x^2 & x^4 \\ \frac{d}{dx}(x^2) & \frac{d}{dx}(x^4) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} x^2 & x^4 \\ 2x & 4x^3 \end{vmatrix}$$

Therefore

$$W = (x^2)(4x^3) - (x^4)(2x)$$

Which simplifies to

$$W = 2x^5$$

Which simplifies to

$$W = 2x^5$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{2x^7}{2x^5} dx$$

Which simplifies to

$$u_1 = - \int 1 dx$$

Hence

$$u_1 = -x$$

And Eq. (3) becomes

$$u_2 = \int \frac{2x^5}{2x^7} dx$$

Which simplifies to

$$u_2 = \int \frac{1}{x^2} dx$$

Hence

$$u_2 = -\frac{1}{x}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = -2x^3$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(\left(-\frac{c_1}{2x^2} + c_2 \right) x^4 \right) + (-2x^3) \\ &= -2x^3 + \left(-\frac{c_1}{2x^2} + c_2 \right) x^4 \end{aligned}$$

Which simplifies to

$$y = -\frac{x^2(-2c_2x^2 + c_1 + 4x)}{2}$$

Summary

The solution(s) found are the following

$$y = -\frac{x^2(-2c_2x^2 + c_1 + 4x)}{2} \tag{1}$$

Verification of solutions

$$y = -\frac{x^2(-2c_2x^2 + c_1 + 4x)}{2}$$

Verified OK.

13.15.5 Solving using Kovacic algorithm

Writing the ode as

$$x^2y'' - 5y'x + 8y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= x^2 \\ B &= -5x \\ C &= 8 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{3}{4x^2} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 3 \\ t &= 4x^2 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = \left(\frac{3}{4x^2} \right) z(x) \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 492: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 2 - 0 \\ &= 2 \end{aligned}$$

The poles of r in eq. (7) and the order of each pole are determined by solving for the roots of $t = 4x^2$. There is a pole at $x = 0$ of order 2. Since there is no odd order pole larger than 2 and the order at ∞ is 2 then the necessary conditions for case one are met. Since there is a pole of order 2 then necessary conditions for case two are met. Since pole order is not larger than 2 and the order at ∞ is 2 then the necessary conditions for case three are met. Therefore

$$L = [1, 2, 4, 6, 12]$$

Attempting to find a solution using case $n = 1$.

Looking at poles of order 2. The partial fractions decomposition of r is

$$r = \frac{3}{4x^2}$$

For the pole at $x = 0$ let b be the coefficient of $\frac{1}{x^2}$ in the partial fractions decomposition of r given above. Therefore $b = \frac{3}{4}$. Hence

$$\begin{aligned} [\sqrt{r}]_c &= 0 \\ \alpha_c^+ &= \frac{1}{2} + \sqrt{1 + 4b} = \frac{3}{2} \\ \alpha_c^- &= \frac{1}{2} - \sqrt{1 + 4b} = -\frac{1}{2} \end{aligned}$$

Since the order of r at ∞ is 2 then $[\sqrt{r}]_\infty = 0$. Let b be the coefficient of $\frac{1}{x^2}$ in the Laurent series expansion of r at ∞ , which can be found by dividing the leading coefficient of s by the leading coefficient of t from

$$r = \frac{s}{t} = \frac{3}{4x^2}$$

Since the $\gcd(s, t) = 1$. This gives $b = \frac{3}{4}$. Hence

$$\begin{aligned} [\sqrt{r}]_\infty &= 0 \\ \alpha_\infty^+ &= \frac{1}{2} + \sqrt{1 + 4b} = \frac{3}{2} \\ \alpha_\infty^- &= \frac{1}{2} - \sqrt{1 + 4b} = -\frac{1}{2} \end{aligned}$$

The following table summarizes the findings so far for poles and for the order of r at ∞ where r is

$$r = \frac{3}{4x^2}$$

pole c location	pole order	$[\sqrt{r}]_c$	α_c^+	α_c^-
0	2	0	$\frac{3}{2}$	$-\frac{1}{2}$

Order of r at ∞	$[\sqrt{r}]_\infty$	α_∞^+	α_∞^-
2	0	$\frac{3}{2}$	$-\frac{1}{2}$

Now that the all $[\sqrt{r}]_c$ and its associated α_c^\pm have been determined for all the poles in the set Γ and $[\sqrt{r}]_\infty$ and its associated α_∞^\pm have also been found, the next step is to determine possible non negative integer d from these using

$$d = \alpha_\infty^{s(\infty)} - \sum_{c \in \Gamma} \alpha_c^{s(c)}$$

Where $s(c)$ is either $+$ or $-$ and $s(\infty)$ is the sign of α_∞^\pm . This is done by trial over all set of families $s = (s(c))_{c \in \Gamma \cup \infty}$ until such d is found to work in finding candidate ω .

Trying $\alpha_{\infty}^{-} = -\frac{1}{2}$ then

$$\begin{aligned} d &= \alpha_{\infty}^{-} - (\alpha_{c_1}^{-}) \\ &= -\frac{1}{2} - \left(-\frac{1}{2}\right) \\ &= 0 \end{aligned}$$

Since d an integer and $d \geq 0$ then it can be used to find ω using

$$\omega = \sum_{c \in \Gamma} \left(s(c)[\sqrt{r}]_c + \frac{\alpha_c^{s(c)}}{x - c} \right) + s(\infty)[\sqrt{r}]_{\infty}$$

The above gives

$$\begin{aligned} \omega &= \left((-)[\sqrt{r}]_{c_1} + \frac{\alpha_{c_1}^{-}}{x - c_1} \right) + (-)[\sqrt{r}]_{\infty} \\ &= -\frac{1}{2x} + (-)(0) \\ &= -\frac{1}{2x} \\ &= -\frac{1}{2x} \end{aligned}$$

Now that ω is determined, the next step is find a corresponding minimal polynomial $p(x)$ of degree $d = 0$ to solve the ode. The polynomial $p(x)$ needs to satisfy the equation

$$p'' + 2\omega p' + (\omega' + \omega^2 - r) p = 0 \quad (1A)$$

Let

$$p(x) = 1 \quad (2A)$$

Substituting the above in eq. (1A) gives

$$\begin{aligned} (0) + 2\left(-\frac{1}{2x}\right)(0) + \left(\left(\frac{1}{2x^2}\right) + \left(-\frac{1}{2x}\right)^2 - \left(\frac{3}{4x^2}\right)\right) &= 0 \\ 0 &= 0 \end{aligned}$$

The equation is satisfied since both sides are zero. Therefore the first solution to the ode $z'' = rz$ is

$$\begin{aligned} z_1(x) &= p e^{\int \omega dx} \\ &= e^{\int -\frac{1}{2x} dx} \\ &= \frac{1}{\sqrt{x}} \end{aligned}$$

The first solution to the original ode in y is found from

$$\begin{aligned}y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\&= z_1 e^{-\int \frac{1}{2} \frac{-5x}{x^2} dx} \\&= z_1 e^{\frac{5 \ln(x)}{2}} \\&= z_1 \left(x^{\frac{5}{2}} \right)\end{aligned}$$

Which simplifies to

$$y_1 = x^2$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{-5x}{x^2} dx}}{(y_1)^2} dx \\&= y_1 \int \frac{e^{5 \ln(x)}}{(y_1)^2} dx \\&= y_1 \left(\frac{x^2}{2} \right)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\&= c_1 (x^2) + c_2 \left(x^2 \left(\frac{x^2}{2} \right) \right)\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$.
 y_h is the solution to

$$x^2 y'' - 5y'x + 8y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1x^2 + \frac{1}{2}c_2x^4$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1y_1 + u_2y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = x^2$$
$$y_2 = \frac{x^4}{2}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} x^2 & \frac{x^4}{2} \\ \frac{d}{dx}(x^2) & \frac{d}{dx}\left(\frac{x^4}{2}\right) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} x^2 & \frac{x^4}{2} \\ 2x & 2x^3 \end{vmatrix}$$

Therefore

$$W = (x^2)(2x^3) - \left(\frac{x^4}{2}\right)(2x)$$

Which simplifies to

$$W = x^5$$

Which simplifies to

$$W = x^5$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{x^7}{x^7} dx$$

Which simplifies to

$$u_1 = - \int 1 dx$$

Hence

$$u_1 = -x$$

And Eq. (3) becomes

$$u_2 = \int \frac{2x^5}{x^7} dx$$

Which simplifies to

$$u_2 = \int \frac{2}{x^2} dx$$

Hence

$$u_2 = -\frac{2}{x}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = -2x^3$$

Therefore the general solution is

$$\begin{aligned}y &= y_h + y_p \\ &= \left(c_1 x^2 + \frac{1}{2} c_2 x^4 \right) + (-2x^3)\end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 x^2 + \frac{1}{2} c_2 x^4 - 2x^3 \quad (1)$$

Verification of solutions

$$y = c_1 x^2 + \frac{1}{2} c_2 x^4 - 2x^3$$

Verified OK.

Maple trace

```
`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
trying a double symmetry of the form [xi=0, eta=F(x)]
-> Try solving first the homogeneous part of the ODE
    checking if the LODE has constant coefficients
    checking if the LODE is of Euler type
    <- LODE of Euler type successful
<- solving first the homogeneous part of the ODE successful`
```

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 18

```
dsolve(x^2*diff(y(x),x$2)-5*x*diff(y(x),x)+8*y(x)=2*x^3,y(x), singsol=all)
```

$$y(x) = x^2(c_2 x^2 + c_1 - 2x)$$

✓ Solution by Mathematica

Time used: 0.015 (sec). Leaf size: 21

```
DSolve[x^2*y'[x]-5*x*y'[x]+8*y[x]==2*x^3,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow x^2(c_2x^2 - 2x + c_1)$$

13.16 problem 16

13.16.1 Solving as second order euler ode ode	3488
13.16.2 Solving as linear second order ode solved by an integrating factor ode	3491
13.16.3 Solving as second order change of variable on x method 2 ode .	3492
13.16.4 Solving as second order change of variable on x method 1 ode .	3497
13.16.5 Solving as second order change of variable on y method 1 ode .	3502
13.16.6 Solving as second order change of variable on y method 2 ode .	3507
13.16.7 Solving as second order integrable as is ode	3512
13.16.8 Solving as type second_order_integrable_as_is (not using ABC version)	3513
13.16.9 Solving using Kovacic algorithm	3515
13.16.10 Solving as exact linear second order ode ode	3520

Internal problem ID [11870]

Internal file name [OUTPUT/11879_Saturday_April_13_2024_01_13_30_AM_60665861/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.5. The Cauchy-Euler Equation. Exercises page 169

Problem number: 16.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_euler_ode", "exact linear second order ode", "second_order_integrable_as_is", "second_order_change_of_variable_on_x_method_1", "second_order_change_of_variable_on_x_method_2", "second_order_change_of_variable_on_y_method_1", "second_order_change_of_variable_on_y_method_2", "linear_second_order_ode_solved_by_an_integrating_factor"

Maple gives the following as the ode type

```
[[_2nd_order, _exact, _linear, _nonhomogeneous]]
```

$$x^2y'' + 4y'x + 2y = 4 \ln(x)$$

13.16.1 Solving as second order euler ode ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = x^2$, $B = 4x$, $C = 2$, $f(x) = 4 \ln(x)$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. Solving for y_h from

$$x^2y'' + 4y'x + 2y = 0$$

This is Euler second order ODE. Let the solution be $y = x^r$, then $y' = rx^{r-1}$ and $y'' = r(r-1)x^{r-2}$. Substituting these back into the given ODE gives

$$x^2(r(r-1))x^{r-2} + 4rxr^{r-1} + 2x^r = 0$$

Simplifying gives

$$r(r-1)x^r + 4rx^r + 2x^r = 0$$

Since $x^r \neq 0$ then dividing throughout by x^r gives

$$r(r-1) + 4r + 2 = 0$$

Or

$$r^2 + 3r + 2 = 0 \tag{1}$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = -2$$

$$r_2 = -1$$

Since the roots are real and distinct, then the general solution is

$$y = c_1y_1 + c_2y_2$$

Where $y_1 = x^{r_1}$ and $y_2 = x^{r_2}$. Hence

$$y = \frac{c_1}{x^2} + \frac{c_2}{x}$$

Next, we find the particular solution to the ODE

$$x^2y'' + 4y'x + 2y = 4 \ln(x)$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \frac{1}{x^2}$$

$$y_2 = \frac{1}{x}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \frac{1}{x^2} & \frac{1}{x} \\ \frac{d}{dx} \left(\frac{1}{x^2} \right) & \frac{d}{dx} \left(\frac{1}{x} \right) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \frac{1}{x^2} & \frac{1}{x} \\ -\frac{2}{x^3} & -\frac{1}{x^2} \end{vmatrix}$$

Therefore

$$W = \left(\frac{1}{x^2} \right) \left(-\frac{1}{x^2} \right) - \left(\frac{1}{x} \right) \left(-\frac{2}{x^3} \right)$$

Which simplifies to

$$W = \frac{1}{x^4}$$

Which simplifies to

$$W = \frac{1}{x^4}$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{\frac{4 \ln(x)}{x}}{\frac{1}{x^2}} dx$$

Which simplifies to

$$u_1 = - \int 4x \ln(x) dx$$

Hence

$$u_1 = -2x^2 \ln(x) + x^2$$

And Eq. (3) becomes

$$u_2 = \int \frac{\frac{4 \ln(x)}{x^2}}{\frac{1}{x^2}} dx$$

Which simplifies to

$$u_2 = \int 4 \ln(x) dx$$

Hence

$$u_2 = 4x \ln(x) - 4x$$

Which simplifies to

$$u_1 = x^2(1 - 2 \ln(x))$$

$$u_2 = 4x \ln(x) - 4x$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = 1 - 2 \ln(x) + \frac{4x \ln(x) - 4x}{x}$$

Which simplifies to

$$y_p(x) = -3 + 2 \ln(x)$$

Therefore the general solution is

$$\begin{aligned}y &= y_h + y_p \\ &= -3 + 2 \ln(x) + \frac{c_1}{x^2} + \frac{c_2}{x}\end{aligned}$$

Summary

The solution(s) found are the following

$$y = -3 + 2 \ln(x) + \frac{c_1}{x^2} + \frac{c_2}{x} \quad (1)$$

Verification of solutions

$$y = -3 + 2 \ln(x) + \frac{c_1}{x^2} + \frac{c_2}{x}$$

Verified OK.

13.16.2 Solving as linear second order ode solved by an integrating factor ode

The ode satisfies this form

$$y'' + p(x)y' + \frac{(p(x)^2 + p'(x))y}{2} = f(x)$$

Where $p(x) = \frac{4}{x}$. Therefore, there is an integrating factor given by

$$\begin{aligned}M(x) &= e^{\frac{1}{2} \int p dx} \\ &= e^{\int \frac{4}{x} dx} \\ &= x^2\end{aligned}$$

Multiplying both sides of the ODE by the integrating factor $M(x)$ makes the left side of the ODE a complete differential

$$\begin{aligned}(M(x)y)'' &= 4 \ln(x) \\ (x^2y)'' &= 4 \ln(x)\end{aligned}$$

Integrating once gives

$$(x^2y)' = 4x \ln(x) - 4x + c_1$$

Integrating again gives

$$(x^2y) = x(2x \ln(x) + c_1 - 3x) + c_2$$

Hence the solution is

$$y = \frac{x(2x \ln(x) + c_1 - 3x) + c_2}{x^2}$$

Or

$$y = 2 \ln(x) + \frac{c_1}{x} + \frac{c_2}{x^2} - 3$$

Summary

The solution(s) found are the following

$$y = 2 \ln(x) + \frac{c_1}{x} + \frac{c_2}{x^2} - 3 \quad (1)$$

Verification of solutions

$$y = 2 \ln(x) + \frac{c_1}{x} + \frac{c_2}{x^2} - 3$$

Verified OK.

13.16.3 Solving as second order change of variable on x method 2 ode

This is second order non-homogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$x^2y'' + 4y'x + 2y = 0$$

In normal form the ode

$$x^2y'' + 4y'x + 2y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = \frac{4}{x}$$
$$q(x) = \frac{2}{x^2}$$

Applying change of variables $\tau = g(x)$ to (2) gives

$$\frac{d^2}{d\tau^2}y(\tau) + p_1\left(\frac{d}{d\tau}y(\tau)\right) + q_1y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $p_1 = 0$. Eq (4) simplifies to

$$\tau''(x) + p(x)\tau'(x) = 0$$

This ode is solved resulting in

$$\begin{aligned} \tau &= \int e^{-(\int p(x)dx)} dx \\ &= \int e^{-(\int \frac{4}{x} dx)} dx \\ &= \int e^{-4\ln(x)} dx \\ &= \int \frac{1}{x^4} dx \\ &= -\frac{1}{3x^3} \end{aligned} \quad (6)$$

Using (6) to evaluate q_1 from (5) gives

$$\begin{aligned} q_1(\tau) &= \frac{q(x)}{\tau'(x)^2} \\ &= \frac{\frac{2}{x^2}}{\frac{1}{x^8}} \\ &= 2x^6 \end{aligned} \quad (7)$$

Substituting the above in (3) and noting that now $p_1 = 0$ results in

$$\begin{aligned} \frac{d^2}{d\tau^2}y(\tau) + q_1y(\tau) &= 0 \\ \frac{d^2}{d\tau^2}y(\tau) + 2x^6y(\tau) &= 0 \end{aligned}$$

But in terms of τ

$$2x^6 = \frac{2}{9\tau^2}$$

Hence the above ode becomes

$$\frac{d^2}{d\tau^2}y(\tau) + \frac{2y(\tau)}{9\tau^2} = 0$$

The above ode is now solved for $y(\tau)$. The ode can be written as

$$9\left(\frac{d^2}{d\tau^2}y(\tau)\right)\tau^2 + 2y(\tau) = 0$$

Which shows it is a Euler ODE. This is Euler second order ODE. Let the solution be $y(\tau) = \tau^r$, then $y' = r\tau^{r-1}$ and $y'' = r(r-1)\tau^{r-2}$. Substituting these back into the given ODE gives

$$9\tau^2(r(r-1))\tau^{r-2} + 0r\tau^{r-1} + 2\tau^r = 0$$

Simplifying gives

$$9r(r-1)\tau^r + 0\tau^r + 2\tau^r = 0$$

Since $\tau^r \neq 0$ then dividing throughout by τ^r gives

$$9r(r-1) + 0 + 2 = 0$$

Or

$$9r^2 - 9r + 2 = 0 \tag{1}$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = \frac{1}{3}$$
$$r_2 = \frac{2}{3}$$

Since the roots are real and distinct, then the general solution is

$$y(\tau) = c_1y_1 + c_2y_2$$

Where $y_1 = \tau^{r_1}$ and $y_2 = \tau^{r_2}$. Hence

$$y(\tau) = c_1\tau^{\frac{1}{3}} + c_2\tau^{\frac{2}{3}}$$

The above solution is now transformed back to y using (6) which results in

$$y = \frac{c_1 3^{\frac{2}{3}} \left(-\frac{1}{x^3}\right)^{\frac{1}{3}}}{3} + \frac{c_2 3^{\frac{1}{3}} \left(-\frac{1}{x^3}\right)^{\frac{2}{3}}}{3}$$

Therefore the homogeneous solution y_h is

$$y_h = \frac{c_1 \mathfrak{I}^{\frac{2}{3}} \left(-\frac{1}{x^3}\right)^{\frac{1}{3}}}{3} + \frac{c_2 \mathfrak{I}^{\frac{1}{3}} \left(-\frac{1}{x^3}\right)^{\frac{2}{3}}}{3}$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \left(-\frac{1}{x^3}\right)^{\frac{1}{3}}$$

$$y_2 = \left(-\frac{1}{x^3}\right)^{\frac{2}{3}}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \left(-\frac{1}{x^3}\right)^{\frac{1}{3}} & \left(-\frac{1}{x^3}\right)^{\frac{2}{3}} \\ \frac{d}{dx} \left(\left(-\frac{1}{x^3}\right)^{\frac{1}{3}}\right) & \frac{d}{dx} \left(\left(-\frac{1}{x^3}\right)^{\frac{2}{3}}\right) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \left(-\frac{1}{x^3}\right)^{\frac{1}{3}} & \left(-\frac{1}{x^3}\right)^{\frac{2}{3}} \\ \frac{1}{\left(-\frac{1}{x^3}\right)^{\frac{2}{3}} x^4} & \frac{2}{\left(-\frac{1}{x^3}\right)^{\frac{1}{3}} x^4} \end{vmatrix}$$

Therefore

$$W = \left(\left(-\frac{1}{x^3} \right)^{\frac{1}{3}} \right) \left(\frac{2}{\left(-\frac{1}{x^3} \right)^{\frac{1}{3}} x^4} \right) - \left(\left(-\frac{1}{x^3} \right)^{\frac{2}{3}} \right) \left(\frac{1}{\left(-\frac{1}{x^3} \right)^{\frac{2}{3}} x^4} \right)$$

Which simplifies to

$$W = \frac{1}{x^4}$$

Which simplifies to

$$W = \frac{1}{x^4}$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{4 \left(-\frac{1}{x^3} \right)^{\frac{2}{3}} \ln(x)}{\frac{1}{x^2}} dx$$

Which simplifies to

$$u_1 = - \int 4 \left(-\frac{1}{x^3} \right)^{\frac{2}{3}} \ln(x) x^2 dx$$

Hence

$$u_1 = -4 \left(-\frac{1}{x^3} \right)^{\frac{2}{3}} x^3 \ln(x) + 4 \left(-\frac{1}{x^3} \right)^{\frac{2}{3}} x^3$$

And Eq. (3) becomes

$$u_2 = \int \frac{4 \left(-\frac{1}{x^3} \right)^{\frac{1}{3}} \ln(x)}{\frac{1}{x^2}} dx$$

Which simplifies to

$$u_2 = \int 4 \left(-\frac{1}{x^3} \right)^{\frac{1}{3}} \ln(x) x^2 dx$$

Hence

$$u_2 = 2 \left(-\frac{1}{x^3} \right)^{\frac{1}{3}} x^3 \ln(x) - \left(-\frac{1}{x^3} \right)^{\frac{1}{3}} x^3$$

Which simplifies to

$$u_1 = -4 \left(-\frac{1}{x^3} \right)^{\frac{2}{3}} x^3 (\ln(x) - 1)$$

$$u_2 = \left(-\frac{1}{x^3} \right)^{\frac{1}{3}} x^3 (-1 + 2 \ln(x))$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = -3 + 2 \ln(x)$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(\frac{c_1 3^{\frac{2}{3}} \left(-\frac{1}{x^3} \right)^{\frac{1}{3}}}{3} + \frac{c_2 3^{\frac{1}{3}} \left(-\frac{1}{x^3} \right)^{\frac{2}{3}}}{3} \right) + (-3 + 2 \ln(x)) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = \frac{c_1 3^{\frac{2}{3}} \left(-\frac{1}{x^3} \right)^{\frac{1}{3}}}{3} + \frac{c_2 3^{\frac{1}{3}} \left(-\frac{1}{x^3} \right)^{\frac{2}{3}}}{3} - 3 + 2 \ln(x) \quad (1)$$

Verification of solutions

$$y = \frac{c_1 3^{\frac{2}{3}} \left(-\frac{1}{x^3} \right)^{\frac{1}{3}}}{3} + \frac{c_2 3^{\frac{1}{3}} \left(-\frac{1}{x^3} \right)^{\frac{2}{3}}}{3} - 3 + 2 \ln(x)$$

Verified OK.

13.16.4 Solving as second order change of variable on x method 1 ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = x^2$, $B = 4x$, $C = 2$, $f(x) = 4 \ln(x)$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. Solving for y_h from

$$x^2y'' + 4y'x + 2y = 0$$

In normal form the ode

$$x^2y'' + 4y'x + 2y = 0 \tag{1}$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \tag{2}$$

Where

$$p(x) = \frac{4}{x}$$

$$q(x) = \frac{2}{x^2}$$

Applying change of variables $\tau = g(x)$ to (2) results

$$\frac{d^2}{d\tau^2}y(\tau) + p_1\left(\frac{d}{d\tau}y(\tau)\right) + q_1y(\tau) = 0 \tag{3}$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \tag{4}$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \tag{5}$$

Let $q_1 = c^2$ where c is some constant. Therefore from (5)

$$\tau' = \frac{1}{c}\sqrt{q}$$

$$= \frac{\sqrt{2}\sqrt{\frac{1}{x^2}}}{c} \tag{6}$$

$$\tau'' = -\frac{\sqrt{2}}{c\sqrt{\frac{1}{x^2}}x^3}$$

Substituting the above into (4) results in

$$\begin{aligned}
 p_1(\tau) &= \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \\
 &= \frac{-\frac{\sqrt{2}}{c\sqrt{\frac{1}{x^2}}x^3} + \frac{4}{x}\frac{\sqrt{2}\sqrt{\frac{1}{x^2}}}{c}}{\left(\frac{\sqrt{2}\sqrt{\frac{1}{x^2}}}{c}\right)^2} \\
 &= \frac{3c\sqrt{2}}{2}
 \end{aligned}$$

Therefore ode (3) now becomes

$$\begin{aligned}
 y(\tau)'' + p_1y(\tau)' + q_1y(\tau) &= 0 \\
 \frac{d^2}{d\tau^2}y(\tau) + \frac{3c\sqrt{2}}{2}\left(\frac{d}{d\tau}y(\tau)\right) + c^2y(\tau) &= 0 \tag{7}
 \end{aligned}$$

The above ode is now solved for $y(\tau)$. Since the ode is now constant coefficients, it can be easily solved to give

$$y(\tau) = e^{-\frac{3\sqrt{2}c\tau}{4}} \left(c_1 \cosh\left(\frac{\sqrt{2}c\tau}{4}\right) + ic_2 \sinh\left(\frac{\sqrt{2}c\tau}{4}\right) \right)$$

Now from (6)

$$\begin{aligned}
 \tau &= \int \frac{1}{c}\sqrt{q} dx \\
 &= \frac{\int \sqrt{2}\sqrt{\frac{1}{x^2}} dx}{c} \\
 &= \frac{\sqrt{2}\sqrt{\frac{1}{x^2}} x \ln(x)}{c}
 \end{aligned}$$

Substituting the above into the solution obtained gives

$$y = \frac{c_1 \cosh\left(\frac{\ln(x)}{2}\right) + ic_2 \sinh\left(\frac{\ln(x)}{2}\right)}{x^{\frac{3}{2}}}$$

Now the particular solution to this ODE is found

$$x^2y'' + 4y'x + 2y = 4 \ln(x)$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \left(-\frac{1}{x^3}\right)^{\frac{1}{3}}$$

$$y_2 = \left(-\frac{1}{x^3}\right)^{\frac{2}{3}}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \left(-\frac{1}{x^3}\right)^{\frac{1}{3}} & \left(-\frac{1}{x^3}\right)^{\frac{2}{3}} \\ \frac{d}{dx} \left(\left(-\frac{1}{x^3}\right)^{\frac{1}{3}}\right) & \frac{d}{dx} \left(\left(-\frac{1}{x^3}\right)^{\frac{2}{3}}\right) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \left(-\frac{1}{x^3}\right)^{\frac{1}{3}} & \left(-\frac{1}{x^3}\right)^{\frac{2}{3}} \\ \frac{1}{\left(-\frac{1}{x^3}\right)^{\frac{2}{3}} x^4} & \frac{2}{\left(-\frac{1}{x^3}\right)^{\frac{1}{3}} x^4} \end{vmatrix}$$

Therefore

$$W = \left(\left(-\frac{1}{x^3}\right)^{\frac{1}{3}}\right) \left(\frac{2}{\left(-\frac{1}{x^3}\right)^{\frac{1}{3}} x^4}\right) - \left(\left(-\frac{1}{x^3}\right)^{\frac{2}{3}}\right) \left(\frac{1}{\left(-\frac{1}{x^3}\right)^{\frac{2}{3}} x^4}\right)$$

Which simplifies to

$$W = \frac{1}{x^4}$$

Which simplifies to

$$W = \frac{1}{x^4}$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{4\left(-\frac{1}{x^3}\right)^{\frac{2}{3}} \ln(x)}{\frac{1}{x^2}} dx$$

Which simplifies to

$$u_1 = - \int 4\left(-\frac{1}{x^3}\right)^{\frac{2}{3}} \ln(x) x^2 dx$$

Hence

$$u_1 = -4\left(-\frac{1}{x^3}\right)^{\frac{2}{3}} x^3 \ln(x) + 4\left(-\frac{1}{x^3}\right)^{\frac{2}{3}} x^3$$

And Eq. (3) becomes

$$u_2 = \int \frac{4\left(-\frac{1}{x^3}\right)^{\frac{1}{3}} \ln(x)}{\frac{1}{x^2}} dx$$

Which simplifies to

$$u_2 = \int 4\left(-\frac{1}{x^3}\right)^{\frac{1}{3}} \ln(x) x^2 dx$$

Hence

$$u_2 = 2\left(-\frac{1}{x^3}\right)^{\frac{1}{3}} x^3 \ln(x) - \left(-\frac{1}{x^3}\right)^{\frac{1}{3}} x^3$$

Which simplifies to

$$u_1 = -4\left(-\frac{1}{x^3}\right)^{\frac{2}{3}} x^3 (\ln(x) - 1)$$

$$u_2 = \left(-\frac{1}{x^3}\right)^{\frac{1}{3}} x^3 (-1 + 2 \ln(x))$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = -3 + 2 \ln(x)$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(\frac{c_1 \cosh\left(\frac{\ln(x)}{2}\right) + ic_2 \sinh\left(\frac{\ln(x)}{2}\right)}{x^{\frac{3}{2}}} \right) + (-3 + 2 \ln(x)) \\ &= -3 + 2 \ln(x) + \frac{c_1 \cosh\left(\frac{\ln(x)}{2}\right) + ic_2 \sinh\left(\frac{\ln(x)}{2}\right)}{x^{\frac{3}{2}}} \end{aligned}$$

Which simplifies to

$$y = -3 + 2 \ln(x) + \frac{c_1 \cosh\left(\frac{\ln(x)}{2}\right) + ic_2 \sinh\left(\frac{\ln(x)}{2}\right)}{x^{\frac{3}{2}}}$$

Summary

The solution(s) found are the following

$$y = -3 + 2 \ln(x) + \frac{c_1 \cosh\left(\frac{\ln(x)}{2}\right) + ic_2 \sinh\left(\frac{\ln(x)}{2}\right)}{x^{\frac{3}{2}}} \quad (1)$$

Verification of solutions

$$y = -3 + 2 \ln(x) + \frac{c_1 \cosh\left(\frac{\ln(x)}{2}\right) + ic_2 \sinh\left(\frac{\ln(x)}{2}\right)}{x^{\frac{3}{2}}}$$

Verified OK.

13.16.5 Solving as second order change of variable on y method 1 ode

This is second order non-homogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$.
 y_h is the solution to

$$x^2 y'' + 4y'x + 2y = 0$$

In normal form the given ode is written as

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = \frac{4}{x}$$
$$q(x) = \frac{2}{x^2}$$

Calculating the Liouville ode invariant Q given by

$$\begin{aligned} Q &= q - \frac{p'}{2} - \frac{p^2}{4} \\ &= \frac{2}{x^2} - \frac{\left(\frac{4}{x}\right)'}{2} - \frac{\left(\frac{4}{x}\right)^2}{4} \\ &= \frac{2}{x^2} - \frac{\left(-\frac{4}{x^2}\right)}{2} - \frac{\left(\frac{16}{x^2}\right)}{4} \\ &= \frac{2}{x^2} - \left(-\frac{2}{x^2}\right) - \frac{4}{x^2} \\ &= 0 \end{aligned}$$

Since the Liouville ode invariant does not depend on the independent variable x then the transformation

$$y = v(x)z(x) \quad (3)$$

is used to change the original ode to a constant coefficients ode in v . In (3) the term $z(x)$ is given by

$$\begin{aligned} z(x) &= e^{-\left(\int \frac{p(x)}{2} dx\right)} \\ &= e^{-\int \frac{4}{2} dx} \\ &= \frac{1}{x^2} \end{aligned} \quad (5)$$

Hence (3) becomes

$$y = \frac{v(x)}{x^2} \quad (4)$$

Applying this change of variable to the original ode results in

$$v''(x) = 4 \ln(x)$$

Which is now solved for $v(x)$ Integrating once gives

$$v'(x) = 4x \ln(x) - 4x + c_1$$

Integrating again gives

$$v(x) = 2x^2 \ln(x) - 3x^2 + c_1x + c_2$$

Now that $v(x)$ is known, then

$$\begin{aligned} y &= v(x) z(x) \\ &= (-3x^2 + c_1x + 2x^2 \ln(x) + c_2) (z(x)) \end{aligned} \tag{7}$$

But from (5)

$$z(x) = \frac{1}{x^2}$$

Hence (7) becomes

$$y = \frac{-3x^2 + c_1x + 2x^2 \ln(x) + c_2}{x^2}$$

Therefore the homogeneous solution y_h is

$$y_h = \frac{-3x^2 + c_1x + 2x^2 \ln(x) + c_2}{x^2}$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1y_1 + u_2y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \left(-\frac{1}{x^3}\right)^{\frac{1}{3}}$$

$$y_2 = \left(-\frac{1}{x^3}\right)^{\frac{2}{3}}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \left(-\frac{1}{x^3}\right)^{\frac{1}{3}} & \left(-\frac{1}{x^3}\right)^{\frac{2}{3}} \\ \frac{d}{dx} \left(\left(-\frac{1}{x^3}\right)^{\frac{1}{3}}\right) & \frac{d}{dx} \left(\left(-\frac{1}{x^3}\right)^{\frac{2}{3}}\right) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \left(-\frac{1}{x^3}\right)^{\frac{1}{3}} & \left(-\frac{1}{x^3}\right)^{\frac{2}{3}} \\ \frac{1}{\left(-\frac{1}{x^3}\right)^{\frac{2}{3}} x^4} & \frac{2}{\left(-\frac{1}{x^3}\right)^{\frac{1}{3}} x^4} \end{vmatrix}$$

Therefore

$$W = \left(\left(-\frac{1}{x^3}\right)^{\frac{1}{3}} \right) \left(\frac{2}{\left(-\frac{1}{x^3}\right)^{\frac{1}{3}} x^4} \right) - \left(\left(-\frac{1}{x^3}\right)^{\frac{2}{3}} \right) \left(\frac{1}{\left(-\frac{1}{x^3}\right)^{\frac{2}{3}} x^4} \right)$$

Which simplifies to

$$W = \frac{1}{x^4}$$

Which simplifies to

$$W = \frac{1}{x^4}$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{4 \left(-\frac{1}{x^3}\right)^{\frac{2}{3}} \ln(x)}{\frac{1}{x^4}} dx$$

Which simplifies to

$$u_1 = - \int 4 \left(-\frac{1}{x^3} \right)^{\frac{2}{3}} \ln(x) x^2 dx$$

Hence

$$u_1 = -4 \left(-\frac{1}{x^3} \right)^{\frac{2}{3}} x^3 \ln(x) + 4 \left(-\frac{1}{x^3} \right)^{\frac{2}{3}} x^3$$

And Eq. (3) becomes

$$u_2 = \int \frac{4 \left(-\frac{1}{x^3} \right)^{\frac{1}{3}} \ln(x)}{\frac{1}{x^2}} dx$$

Which simplifies to

$$u_2 = \int 4 \left(-\frac{1}{x^3} \right)^{\frac{1}{3}} \ln(x) x^2 dx$$

Hence

$$u_2 = 2 \left(-\frac{1}{x^3} \right)^{\frac{1}{3}} x^3 \ln(x) - \left(-\frac{1}{x^3} \right)^{\frac{1}{3}} x^3$$

Which simplifies to

$$u_1 = -4 \left(-\frac{1}{x^3} \right)^{\frac{2}{3}} x^3 (\ln(x) - 1)$$

$$u_2 = \left(-\frac{1}{x^3} \right)^{\frac{1}{3}} x^3 (-1 + 2 \ln(x))$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = -3 + 2 \ln(x)$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(\frac{-3x^2 + c_1x + 2x^2 \ln(x) + c_2}{x^2} \right) + (-3 + 2 \ln(x)) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = \frac{-3x^2 + c_1x + 2x^2 \ln(x) + c_2}{x^2} - 3 + 2 \ln(x) \quad (1)$$

Verification of solutions

$$y = \frac{-3x^2 + c_1x + 2x^2 \ln(x) + c_2}{x^2} - 3 + 2 \ln(x)$$

Verified OK.

13.16.6 Solving as second order change of variable on y method 2 ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = x^2$, $B = 4x$, $C = 2$, $f(x) = 4 \ln(x)$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. Solving for y_h from

$$x^2y'' + 4y'x + 2y = 0$$

In normal form the ode

$$x^2y'' + 4y'x + 2y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = \frac{4}{x}$$
$$q(x) = \frac{2}{x^2}$$

Applying change of variables on the dependent variable $y = v(x)x^n$ to (2) gives the following ode where the dependent variables is $v(x)$ and not y .

$$v''(x) + \left(\frac{2n}{x} + p\right)v'(x) + \left(\frac{n(n-1)}{x^2} + \frac{np}{x} + q\right)v(x) = 0 \quad (3)$$

Let the coefficient of $v(x)$ above be zero. Hence

$$\frac{n(n-1)}{x^2} + \frac{np}{x} + q = 0 \quad (4)$$

Substituting the earlier values found for $p(x)$ and $q(x)$ into (4) gives

$$\frac{n(n-1)}{x^2} + \frac{4n}{x^2} + \frac{2}{x^2} = 0 \quad (5)$$

Solving (5) for n gives

$$n = -1 \quad (6)$$

Substituting this value in (3) gives

$$\begin{aligned} v''(x) + \frac{2v'(x)}{x} &= 0 \\ v''(x) + \frac{2v'(x)}{x} &= 0 \end{aligned} \quad (7)$$

Using the substitution

$$u(x) = v'(x)$$

Then (7) becomes

$$u'(x) + \frac{2u(x)}{x} = 0 \quad (8)$$

The above is now solved for $u(x)$. In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= -\frac{2u}{x} \end{aligned}$$

Where $f(x) = -\frac{2}{x}$ and $g(u) = u$. Integrating both sides gives

$$\begin{aligned} \frac{1}{u} du &= -\frac{2}{x} dx \\ \int \frac{1}{u} du &= \int -\frac{2}{x} dx \\ \ln(u) &= -2 \ln(x) + c_1 \\ u &= e^{-2 \ln(x) + c_1} \\ &= \frac{c_1}{x^2} \end{aligned}$$

Now that $u(x)$ is known, then

$$\begin{aligned}v'(x) &= u(x) \\v(x) &= \int u(x) dx + c_2 \\&= -\frac{c_1}{x} + c_2\end{aligned}$$

Hence

$$\begin{aligned}y &= v(x) x^n \\&= \frac{-\frac{c_1}{x} + c_2}{x} \\&= \frac{c_2 x - c_1}{x^2}\end{aligned}$$

Now the particular solution to this ODE is found

$$x^2 y'' + 4y'x + 2y = 4 \ln(x)$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$\begin{aligned}y_1 &= \frac{1}{x^2} \\y_2 &= \frac{1}{x}\end{aligned}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \tag{2}$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \tag{3}$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \frac{1}{x^2} & \frac{1}{x} \\ \frac{d}{dx} \left(\frac{1}{x^2} \right) & \frac{d}{dx} \left(\frac{1}{x} \right) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \frac{1}{x^2} & \frac{1}{x} \\ -\frac{2}{x^3} & -\frac{1}{x^2} \end{vmatrix}$$

Therefore

$$W = \left(\frac{1}{x^2} \right) \left(-\frac{1}{x^2} \right) - \left(\frac{1}{x} \right) \left(-\frac{2}{x^3} \right)$$

Which simplifies to

$$W = \frac{1}{x^4}$$

Which simplifies to

$$W = \frac{1}{x^4}$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{\frac{4 \ln(x)}{x}}{\frac{1}{x^2}} dx$$

Which simplifies to

$$u_1 = - \int 4x \ln(x) dx$$

Hence

$$u_1 = -2x^2 \ln(x) + x^2$$

And Eq. (3) becomes

$$u_2 = \int \frac{\frac{4 \ln(x)}{x^2}}{\frac{1}{x^2}} dx$$

Which simplifies to

$$u_2 = \int 4 \ln(x) dx$$

Hence

$$u_2 = 4x \ln(x) - 4x$$

Which simplifies to

$$u_1 = x^2(1 - 2 \ln(x))$$

$$u_2 = 4x \ln(x) - 4x$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = 1 - 2 \ln(x) + \frac{4x \ln(x) - 4x}{x}$$

Which simplifies to

$$y_p(x) = -3 + 2 \ln(x)$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(\frac{-\frac{c_1}{x} + c_2}{x} \right) + (-3 + 2 \ln(x)) \\ &= -3 + 2 \ln(x) + \frac{-\frac{c_1}{x} + c_2}{x} \end{aligned}$$

Which simplifies to

$$y = -3 + 2 \ln(x) + \frac{-\frac{c_1}{x} + c_2}{x}$$

Summary

The solution(s) found are the following

$$y = -3 + 2 \ln(x) + \frac{-\frac{c_1}{x} + c_2}{x} \tag{1}$$

Verification of solutions

$$y = -3 + 2 \ln(x) + \frac{-\frac{c_1}{x} + c_2}{x}$$

Verified OK.

13.16.7 Solving as second order integrable as is ode

Integrating both sides of the ODE w.r.t x gives

$$\int (x^2 y'' + 4y'x + 2y) dx = \int 4 \ln(x) dx$$
$$x^2 y' + 2yx = 4x \ln(x) - 4x + c_1$$

Which is now solved for y .

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = \frac{2}{x}$$
$$q(x) = \frac{4x \ln(x) - 4x + c_1}{x^2}$$

Hence the ode is

$$y' + \frac{2y}{x} = \frac{4x \ln(x) - 4x + c_1}{x^2}$$

The integrating factor μ is

$$\mu = e^{\int \frac{2}{x} dx}$$
$$= x^2$$

The ode becomes

$$\frac{d}{dx}(\mu y) = (\mu) \left(\frac{4x \ln(x) - 4x + c_1}{x^2} \right)$$
$$\frac{d}{dx}(x^2 y) = (x^2) \left(\frac{4x \ln(x) - 4x + c_1}{x^2} \right)$$
$$d(x^2 y) = (4x \ln(x) - 4x + c_1) dx$$

Integrating gives

$$x^2 y = \int 4x \ln(x) - 4x + c_1 dx$$
$$x^2 y = -3x^2 + c_1 x + 2x^2 \ln(x) + c_2$$

Dividing both sides by the integrating factor $\mu = x^2$ results in

$$y = \frac{-3x^2 + c_1 x + 2x^2 \ln(x)}{x^2} + \frac{c_2}{x^2}$$

which simplifies to

$$y = \frac{-3x^2 + c_1x + 2x^2 \ln(x) + c_2}{x^2}$$

Summary

The solution(s) found are the following

$$y = \frac{-3x^2 + c_1x + 2x^2 \ln(x) + c_2}{x^2} \quad (1)$$

Verification of solutions

$$y = \frac{-3x^2 + c_1x + 2x^2 \ln(x) + c_2}{x^2}$$

Verified OK.

13.16.8 Solving as type second_order_integrable_as_is (not using ABC version)

Writing the ode as

$$x^2y'' + 4y'x + 2y = 4 \ln(x)$$

Integrating both sides of the ODE w.r.t x gives

$$\int (x^2y'' + 4y'x + 2y) dx = \int 4 \ln(x) dx$$
$$x^2y' + 2yx = 4x \ln(x) - 4x + c_1$$

Which is now solved for y .

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = \frac{2}{x}$$
$$q(x) = \frac{4x \ln(x) - 4x + c_1}{x^2}$$

Hence the ode is

$$y' + \frac{2y}{x} = \frac{4x \ln(x) - 4x + c_1}{x^2}$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int \frac{2}{x} dx} \\ &= x^2\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu y) &= (\mu) \left(\frac{4x \ln(x) - 4x + c_1}{x^2} \right) \\ \frac{d}{dx}(x^2 y) &= (x^2) \left(\frac{4x \ln(x) - 4x + c_1}{x^2} \right) \\ d(x^2 y) &= (4x \ln(x) - 4x + c_1) dx\end{aligned}$$

Integrating gives

$$\begin{aligned}x^2 y &= \int 4x \ln(x) - 4x + c_1 dx \\ x^2 y &= -3x^2 + c_1 x + 2x^2 \ln(x) + c_2\end{aligned}$$

Dividing both sides by the integrating factor $\mu = x^2$ results in

$$y = \frac{-3x^2 + c_1 x + 2x^2 \ln(x)}{x^2} + \frac{c_2}{x^2}$$

which simplifies to

$$y = \frac{-3x^2 + c_1 x + 2x^2 \ln(x) + c_2}{x^2}$$

Summary

The solution(s) found are the following

$$y = \frac{-3x^2 + c_1 x + 2x^2 \ln(x) + c_2}{x^2} \tag{1}$$

Verification of solutions

$$y = \frac{-3x^2 + c_1 x + 2x^2 \ln(x) + c_2}{x^2}$$

Verified OK.

13.16.9 Solving using Kovacic algorithm

Writing the ode as

$$x^2 y'' + 4y'x + 2y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= x^2 \\ B &= 4x \\ C &= 2 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{0}{1} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 0 \\ t &= 1 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = 0 \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 493: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - -\infty \\ &= \infty \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is *infinity* then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = 0$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = 1$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{4x}{x^2} dx} \end{aligned}$$

$$\begin{aligned}
&= z_1 e^{-2\ln(x)} \\
&= z_1 \left(\frac{1}{x^2} \right)
\end{aligned}$$

Which simplifies to

$$y_1 = \frac{1}{x^2}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}
y_2 &= y_1 \int \frac{e^{\int -\frac{4x}{x^2} dx}}{(y_1)^2} dx \\
&= y_1 \int \frac{e^{-4\ln(x)}}{(y_1)^2} dx \\
&= y_1(x)
\end{aligned}$$

Therefore the solution is

$$\begin{aligned}
y &= c_1 y_1 + c_2 y_2 \\
&= c_1 \left(\frac{1}{x^2} \right) + c_2 \left(\frac{1}{x^2}(x) \right)
\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$x^2 y'' + 4y'x + 2y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = \frac{c_1}{x^2} + \frac{c_2}{x}$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \frac{1}{x^2}$$

$$y_2 = \frac{1}{x}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \frac{1}{x^2} & \frac{1}{x} \\ \frac{d}{dx} \left(\frac{1}{x^2} \right) & \frac{d}{dx} \left(\frac{1}{x} \right) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \frac{1}{x^2} & \frac{1}{x} \\ -\frac{2}{x^3} & -\frac{1}{x^2} \end{vmatrix}$$

Therefore

$$W = \left(\frac{1}{x^2} \right) \left(-\frac{1}{x^2} \right) - \left(\frac{1}{x} \right) \left(-\frac{2}{x^3} \right)$$

Which simplifies to

$$W = \frac{1}{x^4}$$

Which simplifies to

$$W = \frac{1}{x^4}$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{\frac{4 \ln(x)}{x}}{\frac{1}{x^2}} dx$$

Which simplifies to

$$u_1 = - \int 4x \ln(x) dx$$

Hence

$$u_1 = -2x^2 \ln(x) + x^2$$

And Eq. (3) becomes

$$u_2 = \int \frac{\frac{4 \ln(x)}{x^2}}{\frac{1}{x^2}} dx$$

Which simplifies to

$$u_2 = \int 4 \ln(x) dx$$

Hence

$$u_2 = 4x \ln(x) - 4x$$

Which simplifies to

$$u_1 = x^2(1 - 2 \ln(x))$$

$$u_2 = 4x \ln(x) - 4x$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = 1 - 2 \ln(x) + \frac{4x \ln(x) - 4x}{x}$$

Which simplifies to

$$y_p(x) = -3 + 2 \ln(x)$$

Therefore the general solution is

$$\begin{aligned}y &= y_h + y_p \\ &= \left(\frac{c_1}{x^2} + \frac{c_2}{x} \right) + (-3 + 2 \ln(x))\end{aligned}$$

Which simplifies to

$$y = \frac{c_2x + c_1}{x^2} - 3 + 2 \ln(x)$$

Summary

The solution(s) found are the following

$$y = \frac{c_2x + c_1}{x^2} - 3 + 2 \ln(x) \quad (1)$$

Verification of solutions

$$y = \frac{c_2x + c_1}{x^2} - 3 + 2 \ln(x)$$

Verified OK.

13.16.10 Solving as exact linear second order ode ode

An ode of the form

$$p(x) y'' + q(x) y' + r(x) y = s(x)$$

is exact if

$$p''(x) - q'(x) + r(x) = 0 \quad (1)$$

For the given ode we have

$$\begin{aligned}p(x) &= x^2 \\ q(x) &= 4x \\ r(x) &= 2 \\ s(x) &= 4 \ln(x)\end{aligned}$$

Hence

$$\begin{aligned}p''(x) &= 2 \\ q'(x) &= 4\end{aligned}$$

Therefore (1) becomes

$$2 - (4) + (2) = 0$$

Hence the ode is exact. Since we now know the ode is exact, it can be written as

$$(p(x)y' + (q(x) - p'(x))y)' = s(x)$$

Integrating gives

$$p(x)y' + (q(x) - p'(x))y = \int s(x) dx$$

Substituting the above values for p, q, r, s gives

$$x^2y' + 2yx = \int 4 \ln(x) dx$$

We now have a first order ode to solve which is

$$x^2y' + 2yx = 4x \ln(x) - 4x + c_1$$

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = \frac{2}{x}$$
$$q(x) = \frac{4x \ln(x) - 4x + c_1}{x^2}$$

Hence the ode is

$$y' + \frac{2y}{x} = \frac{4x \ln(x) - 4x + c_1}{x^2}$$

The integrating factor μ is

$$\mu = e^{\int \frac{2}{x} dx}$$
$$= x^2$$

The ode becomes

$$\frac{d}{dx}(\mu y) = (\mu) \left(\frac{4x \ln(x) - 4x + c_1}{x^2} \right)$$
$$\frac{d}{dx}(x^2 y) = (x^2) \left(\frac{4x \ln(x) - 4x + c_1}{x^2} \right)$$
$$d(x^2 y) = (4x \ln(x) - 4x + c_1) dx$$

Integrating gives

$$\begin{aligned}x^2 y &= \int 4x \ln(x) - 4x + c_1 dx \\x^2 y &= -3x^2 + c_1 x + 2x^2 \ln(x) + c_2\end{aligned}$$

Dividing both sides by the integrating factor $\mu = x^2$ results in

$$y = \frac{-3x^2 + c_1 x + 2x^2 \ln(x)}{x^2} + \frac{c_2}{x^2}$$

which simplifies to

$$y = \frac{-3x^2 + c_1 x + 2x^2 \ln(x) + c_2}{x^2}$$

Summary

The solution(s) found are the following

$$y = \frac{-3x^2 + c_1 x + 2x^2 \ln(x) + c_2}{x^2} \quad (1)$$

Verification of solutions

$$y = \frac{-3x^2 + c_1 x + 2x^2 \ln(x) + c_2}{x^2}$$

Verified OK.

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
<- high order exact linear fully integrable successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 20

```
dsolve(x^2*diff(y(x),x$2)+4*x*diff(y(x),x)+2*y(x)=4*ln(x),y(x), singsol=all)
```

$$y(x) = 2 \ln(x) + \frac{c_1}{x} - 3 + \frac{c_2}{x^2}$$

✓ Solution by Mathematica

Time used: 0.022 (sec). Leaf size: 23

```
DSolve[x^2*y''[x]+4*x*y'[x]+2*y[x]==4*Log[x],y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{c_1}{x^2} + 2 \log(x) + \frac{c_2}{x} - 3$$

13.17 problem 17

13.17.1 Solving as second order euler ode ode	3524
13.17.2 Solving as second order change of variable on x method 2 ode .	3528
13.17.3 Solving as second order change of variable on x method 1 ode .	3534
13.17.4 Solving as second order change of variable on y method 2 ode .	3539
13.17.5 Solving using Kovacic algorithm	3545

Internal problem ID [11871]

Internal file name [OUTPUT/11880_Saturday_April_13_2024_01_13_34_AM_96256138/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.5. The Cauchy-Euler Equation. Exercises page 169

Problem number: 17.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_euler_ode", "second_order_change_of_variable_on_x_method_1", "second_order_change_of_variable_on_x_method_2", "second_order_change_of_variable_on_y_method_2"

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$x^2y'' + y'x + 4y = 2x \ln(x)$$

13.17.1 Solving as second order euler ode ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = x^2, B = x, C = 4, f(x) = 2x \ln(x)$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. Solving for y_h from

$$x^2y'' + y'x + 4y = 0$$

This is Euler second order ODE. Let the solution be $y = x^r$, then $y' = rx^{r-1}$ and $y'' = r(r-1)x^{r-2}$. Substituting these back into the given ODE gives

$$x^2(r(r-1))x^{r-2} + xrx^{r-1} + 4x^r = 0$$

Simplifying gives

$$r(r-1)x^r + rx^r + 4x^r = 0$$

Since $x^r \neq 0$ then dividing throughout by x^r gives

$$r(r-1) + r + 4 = 0$$

Or

$$r^2 + 4 = 0 \tag{1}$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = -2i$$

$$r_2 = 2i$$

The roots are complex conjugate of each others. Let the roots be

$$r_1 = \alpha + i\beta$$

$$r_2 = \alpha - i\beta$$

Where in this case $\alpha = 0$ and $\beta = -2$. Hence the solution becomes

$$\begin{aligned} y &= c_1x^{r_1} + c_2x^{r_2} \\ &= c_1x^{\alpha+i\beta} + c_2x^{\alpha-i\beta} \\ &= x^\alpha (c_1x^{i\beta} + c_2x^{-i\beta}) \\ &= x^\alpha (c_1e^{\ln(x^{i\beta})} + c_2e^{\ln(x^{-i\beta})}) \\ &= x^\alpha (c_1e^{i(\beta \ln x)} + c_2e^{-i(\beta \ln x)}) \end{aligned}$$

Using the values for $\alpha = 0$, $\beta = -2$, the above becomes

$$y = x^0 (c_1e^{-2i \ln(x)} + c_2e^{2i \ln(x)})$$

Using Euler relation, the expression $c_1e^{iA} + c_2e^{-iA}$ is transformed to $c_1 \cos A + c_1 \sin A$ where the constants are free to change. Applying this to the above result gives

$$y = c_1 \cos (2 \ln (x)) + c_2 \sin (2 \ln (x))$$

Next, we find the particular solution to the ODE

$$x^2 y'' + y'x + 4y = 2x \ln(x)$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \cos(2 \ln(x))$$

$$y_2 = -\sin(2 \ln(x))$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \cos(2 \ln(x)) & -\sin(2 \ln(x)) \\ \frac{d}{dx}(\cos(2 \ln(x))) & \frac{d}{dx}(-\sin(2 \ln(x))) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \cos(2 \ln(x)) & -\sin(2 \ln(x)) \\ -\frac{2 \sin(2 \ln(x))}{x} & -\frac{2 \cos(2 \ln(x))}{x} \end{vmatrix}$$

Therefore

$$W = (\cos(2 \ln(x))) \left(-\frac{2 \cos(2 \ln(x))}{x} \right) - (-\sin(2 \ln(x))) \left(-\frac{2 \sin(2 \ln(x))}{x} \right)$$

Which simplifies to

$$W = -\frac{2(\cos(2 \ln(x))^2 + \sin(2 \ln(x))^2)}{x}$$

Which simplifies to

$$W = -\frac{2}{x}$$

Therefore Eq. (2) becomes

$$u_1 = -\int \frac{-2 \sin(2 \ln(x)) x \ln(x)}{-2x} dx$$

Which simplifies to

$$u_1 = -\int \sin(2 \ln(x)) \ln(x) dx$$

Hence

$$u_1 = -\left(-\frac{2 \ln(x)}{5} + \frac{4}{25}\right) x \cos(2 \ln(x)) - \left(\frac{\ln(x)}{5} + \frac{3}{25}\right) x \sin(2 \ln(x))$$

And Eq. (3) becomes

$$u_2 = \int \frac{2 \cos(2 \ln(x)) x \ln(x)}{-2x} dx$$

Which simplifies to

$$u_2 = \int -\cos(2 \ln(x)) \ln(x) dx$$

Hence

$$u_2 = -\left(\frac{\ln(x)}{5} + \frac{3}{25}\right) x \cos(2 \ln(x)) + \left(-\frac{2 \ln(x)}{5} + \frac{4}{25}\right) x \sin(2 \ln(x))$$

Which simplifies to

$$u_1 = \left(-\frac{2\left(\frac{2}{5} - \ln(x)\right) \cos(2 \ln(x))}{5} - \frac{\left(\frac{3}{5} + \ln(x)\right) \sin(2 \ln(x))}{5} \right) x$$
$$u_2 = \left(-\frac{\left(\frac{3}{5} + \ln(x)\right) \cos(2 \ln(x))}{5} + \frac{2\left(\frac{2}{5} - \ln(x)\right) \sin(2 \ln(x))}{5} \right) x$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \left(-\frac{2\left(\frac{2}{5} - \ln(x)\right) \cos(2 \ln(x)) - \left(\frac{3}{5} + \ln(x)\right) \sin(2 \ln(x))}{5} \right) x \cos(2 \ln(x)) \\ - \left(-\frac{\left(\frac{3}{5} + \ln(x)\right) \cos(2 \ln(x)) + 2\left(\frac{2}{5} - \ln(x)\right) \sin(2 \ln(x))}{5} \right) x \sin(2 \ln(x))$$

Which simplifies to

$$y_p(x) = \frac{2x \ln(x)}{5} - \frac{4x}{25}$$

Therefore the general solution is

$$y = y_h + y_p \\ = \frac{2x \ln(x)}{5} - \frac{4x}{25} + c_1 \cos(2 \ln(x)) + c_2 \sin(2 \ln(x))$$

Summary

The solution(s) found are the following

$$y = \frac{2x \ln(x)}{5} - \frac{4x}{25} + c_1 \cos(2 \ln(x)) + c_2 \sin(2 \ln(x)) \quad (1)$$

Verification of solutions

$$y = \frac{2x \ln(x)}{5} - \frac{4x}{25} + c_1 \cos(2 \ln(x)) + c_2 \sin(2 \ln(x))$$

Verified OK.

13.17.2 Solving as second order change of variable on x method 2 ode

This is second order non-homogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$x^2 y'' + y'x + 4y = 0$$

In normal form the ode

$$x^2 y'' + y'x + 4y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = \frac{1}{x}$$
$$q(x) = \frac{4}{x^2}$$

Applying change of variables $\tau = g(x)$ to (2) gives

$$\frac{d^2}{d\tau^2}y(\tau) + p_1\left(\frac{d}{d\tau}y(\tau)\right) + q_1y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $p_1 = 0$. Eq (4) simplifies to

$$\tau''(x) + p(x)\tau'(x) = 0$$

This ode is solved resulting in

$$\begin{aligned} \tau &= \int e^{-(\int p(x)dx)} dx \\ &= \int e^{-(\int \frac{1}{x} dx)} dx \\ &= \int e^{-\ln(x)} dx \\ &= \int \frac{1}{x} dx \\ &= \ln(x) \end{aligned} \quad (6)$$

Using (6) to evaluate q_1 from (5) gives

$$\begin{aligned} q_1(\tau) &= \frac{q(x)}{\tau'(x)^2} \\ &= \frac{\frac{4}{x^2}}{\frac{1}{x^2}} \\ &= 4 \end{aligned} \quad (7)$$

Substituting the above in (3) and noting that now $p_1 = 0$ results in

$$\begin{aligned}\frac{d^2}{d\tau^2}y(\tau) + q_1y(\tau) &= 0 \\ \frac{d^2}{d\tau^2}y(\tau) + 4y(\tau) &= 0\end{aligned}$$

The above ode is now solved for $y(\tau)$. This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(\tau) + By'(\tau) + Cy(\tau) = 0$$

Where in the above $A = 1, B = 0, C = 4$. Let the solution be $y(\tau) = e^{\lambda\tau}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda\tau} + 4e^{\lambda\tau} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda\tau}$ gives

$$\lambda^2 + 4 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 0, C = 4$ into the above gives

$$\begin{aligned}\lambda_{1,2} &= \frac{0}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{0^2 - (4)(1)(4)} \\ &= \pm 2i\end{aligned}$$

Hence

$$\lambda_1 = +2i$$

$$\lambda_2 = -2i$$

Which simplifies to

$$\lambda_1 = 2i$$

$$\lambda_2 = -2i$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = 0$ and $\beta = 2$. Therefore the final solution, when using Euler relation, can be written as

$$y(\tau) = e^{\alpha\tau}(c_1 \cos(\beta\tau) + c_2 \sin(\beta\tau))$$

Which becomes

$$y(\tau) = e^0(c_1 \cos(2\tau) + c_2 \sin(2\tau))$$

Or

$$y(\tau) = c_1 \cos(2\tau) + c_2 \sin(2\tau)$$

The above solution is now transformed back to y using (6) which results in

$$y = c_1 \cos(2 \ln(x)) + c_2 \sin(2 \ln(x))$$

Therefore the homogeneous solution y_h is

$$y_h = c_1 \cos(2 \ln(x)) + c_2 \sin(2 \ln(x))$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \sin(\ln(x)) \cos(\ln(x))$$

$$y_2 = 2 \cos(\ln(x))^2 - 1$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \tag{2}$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \tag{3}$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \sin(\ln(x)) \cos(\ln(x)) & 2 \cos(\ln(x))^2 - 1 \\ \frac{d}{dx}(\sin(\ln(x)) \cos(\ln(x))) & \frac{d}{dx}(2 \cos(\ln(x))^2 - 1) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \sin(\ln(x)) \cos(\ln(x)) & 2 \cos(\ln(x))^2 - 1 \\ \frac{\cos(\ln(x))^2}{x} - \frac{\sin(\ln(x))^2}{x} & -\frac{4 \cos(\ln(x)) \sin(\ln(x))}{x} \end{vmatrix}$$

Therefore

$$W = (\sin(\ln(x)) \cos(\ln(x))) \left(-\frac{4 \cos(\ln(x)) \sin(\ln(x))}{x} \right) - (2 \cos(\ln(x))^2 - 1) \left(\frac{\cos(\ln(x))^2}{x} - \frac{\sin(\ln(x))^2}{x} \right)$$

Which simplifies to

$$W = -\frac{2 \sin(\ln(x))^2 \cos(\ln(x))^2 + 2 \cos(\ln(x))^4 + \sin(\ln(x))^2 - \cos(\ln(x))^2}{x}$$

Which simplifies to

$$W = -\frac{1}{x}$$

Therefore Eq. (2) becomes

$$u_1 = -\int \frac{2(2 \cos(\ln(x))^2 - 1) x \ln(x)}{-x} dx$$

Which simplifies to

$$u_1 = -\int -2 \cos(2 \ln(x)) \ln(x) dx$$

Hence

$$u_1 = 2 \left(\frac{\ln(x)}{5} + \frac{3}{25} \right) x \cos(2 \ln(x)) - 2 \left(-\frac{2 \ln(x)}{5} + \frac{4}{25} \right) x \sin(2 \ln(x))$$

And Eq. (3) becomes

$$u_2 = \int \frac{2 \sin(\ln(x)) \cos(\ln(x)) x \ln(x)}{-x} dx$$

Which simplifies to

$$u_2 = \int -\sin(2 \ln(x)) \ln(x) dx$$

Hence

$$u_2 = -\left(-\frac{2 \ln(x)}{5} + \frac{4}{25}\right) x \cos(2 \ln(x)) - \left(\frac{\ln(x)}{5} + \frac{3}{25}\right) x \sin(2 \ln(x))$$

Which simplifies to

$$u_1 = \left(\frac{2\left(\frac{3}{5} + \ln(x)\right) \cos(2 \ln(x))}{5} - \frac{4\left(\frac{2}{5} - \ln(x)\right) \sin(2 \ln(x))}{5}\right) x$$

$$u_2 = \left(-\frac{2\left(\frac{2}{5} - \ln(x)\right) \cos(2 \ln(x))}{5} - \frac{\left(\frac{3}{5} + \ln(x)\right) \sin(2 \ln(x))}{5}\right) x$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \left(\frac{2\left(\frac{3}{5} + \ln(x)\right) \cos(2 \ln(x))}{5} - \frac{4\left(\frac{2}{5} - \ln(x)\right) \sin(2 \ln(x))}{5}\right) x \sin(\ln(x)) \cos(\ln(x))$$

$$+ \left(-\frac{2\left(\frac{2}{5} - \ln(x)\right) \cos(2 \ln(x))}{5} - \frac{\left(\frac{3}{5} + \ln(x)\right) \sin(2 \ln(x))}{5}\right) x (2 \cos(\ln(x)))^2 - 1)$$

Which simplifies to

$$y_p(x) = \frac{2x \ln(x)}{5} - \frac{4x}{25}$$

Therefore the general solution is

$$\begin{aligned}y &= y_h + y_p \\ &= (c_1 \cos(2 \ln(x)) + c_2 \sin(2 \ln(x))) + \left(\frac{2x \ln(x)}{5} - \frac{4x}{25}\right)\end{aligned}$$

Summary

The solution(s) found are the following

$$y = \frac{2x \ln(x)}{5} - \frac{4x}{25} + c_1 \cos(2 \ln(x)) + c_2 \sin(2 \ln(x)) \quad (1)$$

Verification of solutions

$$y = \frac{2x \ln(x)}{5} - \frac{4x}{25} + c_1 \cos(2 \ln(x)) + c_2 \sin(2 \ln(x))$$

Verified OK.

13.17.3 Solving as second order change of variable on x method 1 ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = x^2$, $B = x$, $C = 4$, $f(x) = 2x \ln(x)$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. Solving for y_h from

$$x^2 y'' + y' x + 4y = 0$$

In normal form the ode

$$x^2 y'' + y' x + 4y = 0 \quad (1)$$

Becomes

$$y'' + p(x) y' + q(x) y = 0 \quad (2)$$

Where

$$\begin{aligned}p(x) &= \frac{1}{x} \\ q(x) &= \frac{4}{x^2}\end{aligned}$$

Applying change of variables $\tau = g(x)$ to (2) results

$$\frac{d^2}{d\tau^2}y(\tau) + p_1\left(\frac{d}{d\tau}y(\tau)\right) + q_1y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $q_1 = c^2$ where c is some constant. Therefore from (5)

$$\begin{aligned} \tau' &= \frac{1}{c}\sqrt{q} \\ &= \frac{2\sqrt{\frac{1}{x^2}}}{c} \\ \tau'' &= -\frac{2}{c\sqrt{\frac{1}{x^2}}x^3} \end{aligned} \quad (6)$$

Substituting the above into (4) results in

$$\begin{aligned} p_1(\tau) &= \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \\ &= \frac{-\frac{2}{c\sqrt{\frac{1}{x^2}}x^3} + \frac{1}{x}\frac{2\sqrt{\frac{1}{x^2}}}{c}}{\left(\frac{2\sqrt{\frac{1}{x^2}}}{c}\right)^2} \\ &= 0 \end{aligned}$$

Therefore ode (3) now becomes

$$\begin{aligned} y(\tau)'' + p_1y(\tau)' + q_1y(\tau) &= 0 \\ \frac{d^2}{d\tau^2}y(\tau) + c^2y(\tau) &= 0 \end{aligned} \quad (7)$$

The above ode is now solved for $y(\tau)$. Since the ode is now constant coefficients, it can be easily solved to give

$$y(\tau) = c_1 \cos(c\tau) + c_2 \sin(c\tau)$$

Now from (6)

$$\begin{aligned}\tau &= \int \frac{1}{c} \sqrt{q} dx \\ &= \frac{\int 2\sqrt{\frac{1}{x^2}} dx}{c} \\ &= \frac{2\sqrt{\frac{1}{x^2}} x \ln(x)}{c}\end{aligned}$$

Substituting the above into the solution obtained gives

$$y = c_1 \cos(2 \ln(x)) + c_2 \sin(2 \ln(x))$$

Now the particular solution to this ODE is found

$$x^2 y'' + y'x + 4y = 2x \ln(x)$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \sin(\ln(x)) \cos(\ln(x))$$

$$y_2 = 2 \cos(\ln(x))^2 - 1$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \tag{2}$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \tag{3}$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \sin(\ln(x)) \cos(\ln(x)) & 2 \cos(\ln(x))^2 - 1 \\ \frac{d}{dx}(\sin(\ln(x)) \cos(\ln(x))) & \frac{d}{dx}(2 \cos(\ln(x))^2 - 1) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \sin(\ln(x)) \cos(\ln(x)) & 2 \cos(\ln(x))^2 - 1 \\ \frac{\cos(\ln(x))^2}{x} - \frac{\sin(\ln(x))^2}{x} & -\frac{4 \cos(\ln(x)) \sin(\ln(x))}{x} \end{vmatrix}$$

Therefore

$$W = (\sin(\ln(x)) \cos(\ln(x))) \left(-\frac{4 \cos(\ln(x)) \sin(\ln(x))}{x} \right) - (2 \cos(\ln(x))^2 - 1) \left(\frac{\cos(\ln(x))^2}{x} - \frac{\sin(\ln(x))^2}{x} \right)$$

Which simplifies to

$$W = -\frac{2 \sin(\ln(x))^2 \cos(\ln(x))^2 + 2 \cos(\ln(x))^4 + \sin(\ln(x))^2 - \cos(\ln(x))^2}{x}$$

Which simplifies to

$$W = -\frac{1}{x}$$

Therefore Eq. (2) becomes

$$u_1 = -\int \frac{2(2 \cos(\ln(x))^2 - 1) x \ln(x)}{-x} dx$$

Which simplifies to

$$u_1 = -\int -2 \cos(2 \ln(x)) \ln(x) dx$$

Hence

$$u_1 = 2 \left(\frac{\ln(x)}{5} + \frac{3}{25} \right) x \cos(2 \ln(x)) - 2 \left(-\frac{2 \ln(x)}{5} + \frac{4}{25} \right) x \sin(2 \ln(x))$$

And Eq. (3) becomes

$$u_2 = \int \frac{2 \sin(\ln(x)) \cos(\ln(x)) x \ln(x)}{-x} dx$$

Which simplifies to

$$u_2 = \int -\sin(2 \ln(x)) \ln(x) dx$$

Hence

$$u_2 = -\left(-\frac{2 \ln(x)}{5} + \frac{4}{25}\right) x \cos(2 \ln(x)) - \left(\frac{\ln(x)}{5} + \frac{3}{25}\right) x \sin(2 \ln(x))$$

Which simplifies to

$$u_1 = \left(\frac{2\left(\frac{3}{5} + \ln(x)\right) \cos(2 \ln(x))}{5} - \frac{4\left(\frac{2}{5} - \ln(x)\right) \sin(2 \ln(x))}{5}\right) x$$

$$u_2 = \left(-\frac{2\left(\frac{2}{5} - \ln(x)\right) \cos(2 \ln(x))}{5} - \frac{\left(\frac{3}{5} + \ln(x)\right) \sin(2 \ln(x))}{5}\right) x$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \left(\frac{2\left(\frac{3}{5} + \ln(x)\right) \cos(2 \ln(x))}{5} - \frac{4\left(\frac{2}{5} - \ln(x)\right) \sin(2 \ln(x))}{5}\right) x \sin(\ln(x)) \cos(\ln(x))$$

$$+ \left(-\frac{2\left(\frac{2}{5} - \ln(x)\right) \cos(2 \ln(x))}{5} - \frac{\left(\frac{3}{5} + \ln(x)\right) \sin(2 \ln(x))}{5}\right) x (2 \cos(\ln(x)))^2 - 1)$$

Which simplifies to

$$y_p(x) = \frac{2x \ln(x)}{5} - \frac{4x}{25}$$

Therefore the general solution is

$$\begin{aligned}y &= y_h + y_p \\&= (c_1 \cos(2 \ln(x)) + c_2 \sin(2 \ln(x))) + \left(\frac{2x \ln(x)}{5} - \frac{4x}{25} \right) \\&= \frac{2x \ln(x)}{5} - \frac{4x}{25} + c_1 \cos(2 \ln(x)) + c_2 \sin(2 \ln(x))\end{aligned}$$

Which simplifies to

$$y = \frac{2x \ln(x)}{5} - \frac{4x}{25} + c_1 \cos(2 \ln(x)) + c_2 \sin(2 \ln(x))$$

Summary

The solution(s) found are the following

$$y = \frac{2x \ln(x)}{5} - \frac{4x}{25} + c_1 \cos(2 \ln(x)) + c_2 \sin(2 \ln(x)) \quad (1)$$

Verification of solutions

$$y = \frac{2x \ln(x)}{5} - \frac{4x}{25} + c_1 \cos(2 \ln(x)) + c_2 \sin(2 \ln(x))$$

Verified OK.

13.17.4 Solving as second order change of variable on y method 2 ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = x^2$, $B = x$, $C = 4$, $f(x) = 2x \ln(x)$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. Solving for y_h from

$$x^2 y'' + y' x + 4y = 0$$

In normal form the ode

$$x^2 y'' + y' x + 4y = 0 \quad (1)$$

Becomes

$$y'' + p(x) y' + q(x) y = 0 \quad (2)$$

Where

$$p(x) = \frac{1}{x}$$
$$q(x) = \frac{4}{x^2}$$

Applying change of variables on the dependent variable $y = v(x) x^n$ to (2) gives the following ode where the dependent variables is $v(x)$ and not y .

$$v''(x) + \left(\frac{2n}{x} + p \right) v'(x) + \left(\frac{n(n-1)}{x^2} + \frac{np}{x} + q \right) v(x) = 0 \quad (3)$$

Let the coefficient of $v(x)$ above be zero. Hence

$$\frac{n(n-1)}{x^2} + \frac{np}{x} + q = 0 \quad (4)$$

Substituting the earlier values found for $p(x)$ and $q(x)$ into (4) gives

$$\frac{n(n-1)}{x^2} + \frac{n}{x^2} + \frac{4}{x^2} = 0 \quad (5)$$

Solving (5) for n gives

$$n = 2i \quad (6)$$

Substituting this value in (3) gives

$$v''(x) + \left(\frac{4i}{x} + \frac{1}{x} \right) v'(x) = 0$$
$$v''(x) + \frac{(1+4i)v'(x)}{x} = 0 \quad (7)$$

Using the substitution

$$u(x) = v'(x)$$

Then (7) becomes

$$u'(x) + \frac{(1 + 4i)u(x)}{x} = 0 \quad (8)$$

The above is now solved for $u(x)$. In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= \frac{(-1 - 4i)u}{x} \end{aligned}$$

Where $f(x) = \frac{-1-4i}{x}$ and $g(u) = u$. Integrating both sides gives

$$\begin{aligned} \frac{1}{u} du &= \frac{-1 - 4i}{x} dx \\ \int \frac{1}{u} du &= \int \frac{-1 - 4i}{x} dx \\ \ln(u) &= (-1 - 4i) \ln(x) + c_1 \\ u &= e^{(-1-4i)\ln(x)+c_1} \\ &= c_1 e^{(-1-4i)\ln(x)} \end{aligned}$$

Which simplifies to

$$u(x) = \frac{c_1 x^{-4i}}{x}$$

Now that $u(x)$ is known, then

$$\begin{aligned} v'(x) &= u(x) \\ v(x) &= \int u(x) dx + c_2 \\ &= \frac{ic_1 x^{-4i}}{4} + c_2 \end{aligned}$$

Hence

$$\begin{aligned} y &= v(x) x^n \\ &= \left(\frac{ic_1 x^{-4i}}{4} + c_2 \right) x^{2i} \\ &= x^{2i} c_2 + \frac{ix^{-2i} c_1}{4} \end{aligned}$$

Now the particular solution to this ODE is found

$$x^2 y'' + y'x + 4y = 2x \ln(x)$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = x^{2i}$$

$$y_2 = x^{2i} x^{-4i}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} x^{2i} & x^{2i} x^{-4i} \\ \frac{d}{dx}(x^{2i}) & \frac{d}{dx}(x^{2i} x^{-4i}) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} x^{2i} & x^{2i} x^{-4i} \\ \frac{2ix^{2i}}{x} & -\frac{2ix^{2i} x^{-4i}}{x} \end{vmatrix}$$

Therefore

$$W = (x^{2i}) \left(-\frac{2ix^{2i} x^{-4i}}{x} \right) - (x^{2i} x^{-4i}) \left(\frac{2ix^{2i}}{x} \right)$$

Which simplifies to

$$W = -\frac{4ix^{4i}x^{-4i}}{x}$$

Which simplifies to

$$W = -\frac{4i}{x}$$

Therefore Eq. (2) becomes

$$u_1 = -\int \frac{2x^{2i}x^{-4i}x \ln(x)}{-4ix} dx$$

Which simplifies to

$$u_1 = -\int \frac{ix^{-2i} \ln(x)}{2} dx$$

Hence

$$u_1 = -\frac{(4 + 3i + (-10 + 5i) \ln(x)) x^{1-2i}}{50}$$

And Eq. (3) becomes

$$u_2 = \int \frac{2x^{2i}x \ln(x)}{-4ix} dx$$

Which simplifies to

$$u_2 = \int \frac{ix^{2i} \ln(x)}{2} dx$$

Hence

$$u_2 = \frac{(-4 + 3i + (10 + 5i) \ln(x)) x^{1+2i}}{50}$$

Which simplifies to

$$u_1 = -\frac{x^{1-2i} \left(\frac{4}{5} + \frac{3i}{5} + (-2 + i) \ln(x) \right)}{10}$$
$$u_2 = \frac{(-4 + 3i + (10 + 5i) \ln(x)) x^{1+2i}}{50}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = -\frac{x^{1-2i}\left(\frac{4}{5} + \frac{3i}{5} + (-2+i)\ln(x)\right)x^{2i}}{10} + \frac{(-4+3i+(10+5i)\ln(x))x^{1+2i}x^{2i}x^{-4i}}{50}$$

Which simplifies to

$$y_p(x) = \frac{2x \ln(x)}{5} - \frac{4x}{25}$$

Therefore the general solution is

$$\begin{aligned}y &= y_h + y_p \\&= \left(\left(\frac{ic_1 x^{-4i}}{4} + c_2 \right) x^{2i} \right) + \left(\frac{2x \ln(x)}{5} - \frac{4x}{25} \right) \\&= \frac{2x \ln(x)}{5} - \frac{4x}{25} + \left(\frac{ic_1 x^{-4i}}{4} + c_2 \right) x^{2i}\end{aligned}$$

Which simplifies to

$$y = \frac{2x \ln(x)}{5} + x^{2i} c_2 - \frac{4x}{25} + \frac{ix^{-2i} c_1}{4}$$

Summary

The solution(s) found are the following

$$y = \frac{2x \ln(x)}{5} + x^{2i} c_2 - \frac{4x}{25} + \frac{ix^{-2i} c_1}{4} \quad (1)$$

Verification of solutions

$$y = \frac{2x \ln(x)}{5} + x^{2i} c_2 - \frac{4x}{25} + \frac{ix^{-2i} c_1}{4}$$

Verified OK.

13.17.5 Solving using Kovacic algorithm

Writing the ode as

$$x^2 y'' + y' x + 4y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= x^2 \\ B &= x \\ C &= 4 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-17}{4x^2} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= -17 \\ t &= 4x^2 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = \left(-\frac{17}{4x^2} \right) z(x) \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 494: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 2 - 0 \\ &= 2 \end{aligned}$$

The poles of r in eq. (7) and the order of each pole are determined by solving for the roots of $t = 4x^2$. There is a pole at $x = 0$ of order 2. Since there is no odd order pole larger than 2 and the order at ∞ is 2 then the necessary conditions for case one are met. Since there is a pole of order 2 then necessary conditions for case two are met. Since pole order is not larger than 2 and the order at ∞ is 2 then the necessary conditions for case three are met. Therefore

$$L = [1, 2, 4, 6, 12]$$

Attempting to find a solution using case $n = 1$.

Looking at poles of order 2. The partial fractions decomposition of r is

$$r = -\frac{17}{4x^2}$$

For the pole at $x = 0$ let b be the coefficient of $\frac{1}{x^2}$ in the partial fractions decomposition of r given above. Therefore $b = -\frac{17}{4}$. Hence

$$\begin{aligned} [\sqrt{r}]_c &= 0 \\ \alpha_c^+ &= \frac{1}{2} + \sqrt{1 + 4b} = \frac{1}{2} + 2i \\ \alpha_c^- &= \frac{1}{2} - \sqrt{1 + 4b} = \frac{1}{2} - 2i \end{aligned}$$

Since the order of r at ∞ is 2 then $[\sqrt{r}]_\infty = 0$. Let b be the coefficient of $\frac{1}{x^2}$ in the Laurent series expansion of r at ∞ , which can be found by dividing the leading coefficient of s by the leading coefficient of t from

$$r = \frac{s}{t} = -\frac{17}{4x^2}$$

Since the $\gcd(s, t) = 1$. This gives $b = -\frac{17}{4}$. Hence

$$\begin{aligned} [\sqrt{r}]_\infty &= 0 \\ \alpha_\infty^+ &= \frac{1}{2} + \sqrt{1 + 4b} = \frac{1}{2} + 2i \\ \alpha_\infty^- &= \frac{1}{2} - \sqrt{1 + 4b} = \frac{1}{2} - 2i \end{aligned}$$

The following table summarizes the findings so far for poles and for the order of r at ∞ where r is

$$r = -\frac{17}{4x^2}$$

pole c location	pole order	$[\sqrt{r}]_c$	α_c^+	α_c^-
0	2	0	$\frac{1}{2} + 2i$	$\frac{1}{2} - 2i$

Order of r at ∞	$[\sqrt{r}]_\infty$	α_∞^+	α_∞^-
2	0	$\frac{1}{2} + 2i$	$\frac{1}{2} - 2i$

Now that the all $[\sqrt{r}]_c$ and its associated α_c^\pm have been determined for all the poles in the set Γ and $[\sqrt{r}]_\infty$ and its associated α_∞^\pm have also been found, the next step is to determine possible non negative integer d from these using

$$d = \alpha_\infty^{s(\infty)} - \sum_{c \in \Gamma} \alpha_c^{s(c)}$$

Where $s(c)$ is either $+$ or $-$ and $s(\infty)$ is the sign of α_∞^\pm . This is done by trial over all set of families $s = (s(c))_{c \in \Gamma \cup \infty}$ until such d is found to work in finding candidate ω .

Trying $\alpha_{\infty}^{-} = \frac{1}{2} - 2i$ then

$$\begin{aligned} d &= \alpha_{\infty}^{-} - (\alpha_{c_1}^{-}) \\ &= \frac{1}{2} - 2i - \left(\frac{1}{2} - 2i\right) \\ &= 0 \end{aligned}$$

Since d an integer and $d \geq 0$ then it can be used to find ω using

$$\omega = \sum_{c \in \Gamma} \left(s(c)[\sqrt{r}]_c + \frac{\alpha_c^{s(c)}}{x - c} \right) + s(\infty)[\sqrt{r}]_{\infty}$$

The above gives

$$\begin{aligned} \omega &= \left((-)[\sqrt{r}]_{c_1} + \frac{\alpha_{c_1}^{-}}{x - c_1} \right) + (-)[\sqrt{r}]_{\infty} \\ &= \frac{\frac{1}{2} - 2i}{x} + (-)(0) \\ &= \frac{\frac{1}{2} - 2i}{x} \\ &= \frac{\frac{1}{2} - 2i}{x} \end{aligned}$$

Now that ω is determined, the next step is find a corresponding minimal polynomial $p(x)$ of degree $d = 0$ to solve the ode. The polynomial $p(x)$ needs to satisfy the equation

$$p'' + 2\omega p' + (\omega' + \omega^2 - r)p = 0 \quad (1A)$$

Let

$$p(x) = 1 \quad (2A)$$

Substituting the above in eq. (1A) gives

$$\begin{aligned} (0) + 2\left(\frac{\frac{1}{2} - 2i}{x}\right)(0) + \left(\left(\frac{-\frac{1}{2} + 2i}{x^2}\right) + \left(\frac{\frac{1}{2} - 2i}{x}\right)^2 - \left(-\frac{17}{4x^2}\right)\right) &= 0 \\ 0 &= 0 \end{aligned}$$

The equation is satisfied since both sides are zero. Therefore the first solution to the ode $z'' = rz$ is

$$\begin{aligned} z_1(x) &= pe^{\int \omega dx} \\ &= e^{\int \frac{\frac{1}{2} - 2i}{x} dx} \\ &= x^{\frac{1}{2} - 2i} \end{aligned}$$

The first solution to the original ode in y is found from

$$\begin{aligned}y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\&= z_1 e^{-\int \frac{1}{2} \frac{x}{x^2} dx} \\&= z_1 e^{-\frac{\ln(x)}{2}} \\&= z_1 \left(\frac{1}{\sqrt{x}} \right)\end{aligned}$$

Which simplifies to

$$y_1 = x^{-2i}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{x}{x^2} dx}}{(y_1)^2} dx \\&= y_1 \int \frac{e^{-\ln(x)}}{(y_1)^2} dx \\&= y_1 \left(-\frac{ix^{4i}}{4} \right)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\&= c_1 (x^{-2i}) + c_2 \left(x^{-2i} \left(-\frac{ix^{4i}}{4} \right) \right)\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$x^2y'' + y'x + 4y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = x^{-2i}c_1 - \frac{ic_2x^{2i}}{4}$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1y_1 + u_2y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = x^{-2i}$$

$$y_2 = -\frac{ix^{2i}}{4}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = -\int \frac{y_2f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} x^{-2i} & -\frac{ix^{2i}}{4} \\ \frac{d}{dx}(x^{-2i}) & \frac{d}{dx}\left(-\frac{ix^{2i}}{4}\right) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} x^{-2i} & -\frac{ix^{2i}}{4} \\ -\frac{2ix^{-2i}}{x} & \frac{x^{2i}}{2x} \end{vmatrix}$$

Therefore

$$W = (x^{-2i}) \left(\frac{x^{2i}}{2x} \right) - \left(-\frac{ix^{2i}}{4} \right) \left(-\frac{2ix^{-2i}}{x} \right)$$

Which simplifies to

$$W = \frac{x^{-2i} x^{2i}}{x}$$

Which simplifies to

$$W = \frac{1}{x}$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{-\frac{ix^{2i} x \ln(x)}{2}}{x} dx$$

Which simplifies to

$$u_1 = - \int -\frac{ix^{2i} \ln(x)}{2} dx$$

Hence

$$u_1 = \frac{x^{1+2i} \left(-\frac{4}{5} + \frac{3i}{5} + (2+i) \ln(x) \right)}{10}$$

And Eq. (3) becomes

$$u_2 = \int \frac{2x \ln(x) x^{-2i}}{x} dx$$

Which simplifies to

$$u_2 = \int 2x^{-2i} \ln(x) dx$$

Hence

$$u_2 = \frac{2x^{1-2i} (3 - 4i + (5 + 10i) \ln(x))}{25}$$

Which simplifies to

$$u_1 = \frac{(-4 + 3i + (10 + 5i) \ln(x)) x^{1+2i}}{50}$$
$$u_2 = \frac{2x^{1-2i}(3 - 4i + (5 + 10i) \ln(x))}{25}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \frac{(-4 + 3i + (10 + 5i) \ln(x)) x^{1+2i} x^{-2i}}{50} - \frac{ix^{1-2i}(3 - 4i + (5 + 10i) \ln(x)) x^{2i}}{50}$$

Which simplifies to

$$y_p(x) = \frac{2x \ln(x)}{5} - \frac{4x}{25}$$

Therefore the general solution is

$$y = y_h + y_p$$
$$= \left(x^{-2i} c_1 - \frac{ic_2 x^{2i}}{4} \right) + \left(\frac{2x \ln(x)}{5} - \frac{4x}{25} \right)$$

Summary

The solution(s) found are the following

$$y = x^{-2i} c_1 - \frac{ic_2 x^{2i}}{4} + \frac{2x \ln(x)}{5} - \frac{4x}{25} \quad (1)$$

Verification of solutions

$$y = x^{-2i} c_1 - \frac{ic_2 x^{2i}}{4} + \frac{2x \ln(x)}{5} - \frac{4x}{25}$$

Verified OK.

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]  
trying a double symmetry of the form [xi=0, eta=F(x)]  
-> Try solving first the homogeneous part of the ODE  
    checking if the LODE has constant coefficients  
    checking if the LODE is of Euler type  
    <- LODE of Euler type successful  
<- solving first the homogeneous part of the ODE successful`
```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 27

```
dsolve(x^2*diff(y(x),x$2)+x*diff(y(x),x)+4*y(x)=2*x*ln(x),y(x), singsol=all)
```

$$y(x) = \sin(2 \ln(x)) c_2 + \cos(2 \ln(x)) c_1 + \frac{2 \ln(x) x}{5} - \frac{4x}{25}$$

✓ Solution by Mathematica

Time used: 0.11 (sec). Leaf size: 33

```
DSolve[x^2*y''[x]+x*y'[x]+4*y[x]==2*x*Log[x],y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{2}{25}x(5 \log(x) - 2) + c_1 \cos(2 \log(x)) + c_2 \sin(2 \log(x))$$

13.18 problem 18

13.18.1 Solving as second order euler ode ode	3554
13.18.2 Solving as second order change of variable on x method 2 ode .	3558
13.18.3 Solving as second order change of variable on x method 1 ode .	3564
13.18.4 Solving as second order change of variable on y method 2 ode .	3568
13.18.5 Solving using Kovacic algorithm	3573

Internal problem ID [11872]

Internal file name [OUTPUT/11881_Saturday_April_13_2024_01_13_37_AM_23588908/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.5. The Cauchy-Euler Equation. Exercises page 169

Problem number: 18.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_euler_ode", "second_order_change_of_variable_on_x_method_1", "second_order_change_of_variable_on_x_method_2", "second_order_change_of_variable_on_y_method_2"

Maple gives the following as the ode type

```
[[_2nd_order , _linear , _nonhomogeneous]]
```

$$x^2y'' + y'x + 4y = 4 \sin(\ln(x))$$

13.18.1 Solving as second order euler ode ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = x^2, B = x, C = 4, f(x) = 4 \sin(\ln(x))$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. Solving for y_h from

$$x^2y'' + y'x + 4y = 0$$

This is Euler second order ODE. Let the solution be $y = x^r$, then $y' = rx^{r-1}$ and $y'' = r(r-1)x^{r-2}$. Substituting these back into the given ODE gives

$$x^2(r(r-1))x^{r-2} + xrx^{r-1} + 4x^r = 0$$

Simplifying gives

$$r(r-1)x^r + rx^r + 4x^r = 0$$

Since $x^r \neq 0$ then dividing throughout by x^r gives

$$r(r-1) + r + 4 = 0$$

Or

$$r^2 + 4 = 0 \tag{1}$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = -2i$$

$$r_2 = 2i$$

The roots are complex conjugate of each others. Let the roots be

$$r_1 = \alpha + i\beta$$

$$r_2 = \alpha - i\beta$$

Where in this case $\alpha = 0$ and $\beta = -2$. Hence the solution becomes

$$\begin{aligned} y &= c_1x^{r_1} + c_2x^{r_2} \\ &= c_1x^{\alpha+i\beta} + c_2x^{\alpha-i\beta} \\ &= x^\alpha (c_1x^{i\beta} + c_2x^{-i\beta}) \\ &= x^\alpha (c_1e^{\ln(x^{i\beta})} + c_2e^{\ln(x^{-i\beta})}) \\ &= x^\alpha (c_1e^{i(\beta \ln x)} + c_2e^{-i(\beta \ln x)}) \end{aligned}$$

Using the values for $\alpha = 0$, $\beta = -2$, the above becomes

$$y = x^0 (c_1e^{-2i \ln(x)} + c_2e^{2i \ln(x)})$$

Using Euler relation, the expression $c_1e^{iA} + c_2e^{-iA}$ is transformed to $c_1 \cos A + c_1 \sin A$ where the constants are free to change. Applying this to the above result gives

$$y = c_1 \cos (2 \ln (x)) + c_2 \sin (2 \ln (x))$$

Next, we find the particular solution to the ODE

$$x^2 y'' + y'x + 4y = 4 \sin(\ln(x))$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \cos(2 \ln(x))$$

$$y_2 = -\sin(2 \ln(x))$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \cos(2 \ln(x)) & -\sin(2 \ln(x)) \\ \frac{d}{dx}(\cos(2 \ln(x))) & \frac{d}{dx}(-\sin(2 \ln(x))) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \cos(2 \ln(x)) & -\sin(2 \ln(x)) \\ -\frac{2 \sin(2 \ln(x))}{x} & -\frac{2 \cos(2 \ln(x))}{x} \end{vmatrix}$$

Therefore

$$W = (\cos(2 \ln(x))) \left(-\frac{2 \cos(2 \ln(x))}{x} \right) - (-\sin(2 \ln(x))) \left(-\frac{2 \sin(2 \ln(x))}{x} \right)$$

Which simplifies to

$$W = -\frac{2(\cos(2 \ln(x))^2 + \sin(2 \ln(x))^2)}{x}$$

Which simplifies to

$$W = -\frac{2}{x}$$

Therefore Eq. (2) becomes

$$u_1 = -\int \frac{-4 \sin(2 \ln(x)) \sin(\ln(x))}{-2x} dx$$

Which simplifies to

$$u_1 = -\int \frac{\cos(\ln(x)) - \cos(3 \ln(x))}{x} dx$$

Hence

$$u_1 = \frac{\sin(3 \ln(x))}{3} - \sin(\ln(x))$$

And Eq. (3) becomes

$$u_2 = \int \frac{4 \cos(2 \ln(x)) \sin(\ln(x))}{-2x} dx$$

Which simplifies to

$$u_2 = \int \frac{-\sin(3 \ln(x)) + \sin(\ln(x))}{x} dx$$

Hence

$$u_2 = \frac{\cos(3 \ln(x))}{3} - \cos(\ln(x))$$

Which simplifies to

$$u_1 = -\frac{4 \sin(\ln(x))^3}{3}$$
$$u_2 = \frac{4 \cos(\ln(x))^3}{3} - 2 \cos(\ln(x))$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = -\frac{4 \sin(\ln(x))^3 \cos(2 \ln(x))}{3} - \left(\frac{4 \cos(\ln(x))^3}{3} - 2 \cos(\ln(x)) \right) \sin(2 \ln(x))$$

Which simplifies to

$$y_p(x) = \frac{4 \sin(\ln(x))}{3}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \frac{4 \sin(\ln(x))}{3} + c_1 \cos(2 \ln(x)) + c_2 \sin(2 \ln(x)) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = \frac{4 \sin(\ln(x))}{3} + c_1 \cos(2 \ln(x)) + c_2 \sin(2 \ln(x)) \quad (1)$$

Verification of solutions

$$y = \frac{4 \sin(\ln(x))}{3} + c_1 \cos(2 \ln(x)) + c_2 \sin(2 \ln(x))$$

Verified OK.

13.18.2 Solving as second order change of variable on x method 2 ode

This is second order non-homogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$.
 y_h is the solution to

$$x^2 y'' + y' x + 4y = 0$$

In normal form the ode

$$x^2 y'' + y' x + 4y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = \frac{1}{x}$$
$$q(x) = \frac{4}{x^2}$$

Applying change of variables $\tau = g(x)$ to (2) gives

$$\frac{d^2}{d\tau^2}y(\tau) + p_1\left(\frac{d}{d\tau}y(\tau)\right) + q_1y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $p_1 = 0$. Eq (4) simplifies to

$$\tau''(x) + p(x)\tau'(x) = 0$$

This ode is solved resulting in

$$\begin{aligned} \tau &= \int e^{-(\int p(x)dx)} dx \\ &= \int e^{-(\int \frac{1}{x} dx)} dx \\ &= \int e^{-\ln(x)} dx \\ &= \int \frac{1}{x} dx \\ &= \ln(x) \end{aligned} \quad (6)$$

Using (6) to evaluate q_1 from (5) gives

$$\begin{aligned} q_1(\tau) &= \frac{q(x)}{\tau'(x)^2} \\ &= \frac{\frac{4}{x^2}}{\frac{1}{x^2}} \\ &= 4 \end{aligned} \quad (7)$$

Substituting the above in (3) and noting that now $p_1 = 0$ results in

$$\begin{aligned}\frac{d^2}{d\tau^2}y(\tau) + q_1y(\tau) &= 0 \\ \frac{d^2}{d\tau^2}y(\tau) + 4y(\tau) &= 0\end{aligned}$$

The above ode is now solved for $y(\tau)$. This is second order with constant coefficients homogeneous ODE. In standard form the ODE is

$$Ay''(\tau) + By'(\tau) + Cy(\tau) = 0$$

Where in the above $A = 1, B = 0, C = 4$. Let the solution be $y(\tau) = e^{\lambda\tau}$. Substituting this into the ODE gives

$$\lambda^2 e^{\lambda\tau} + 4e^{\lambda\tau} = 0 \quad (1)$$

Since exponential function is never zero, then dividing Eq(2) throughout by $e^{\lambda\tau}$ gives

$$\lambda^2 + 4 = 0 \quad (2)$$

Equation (2) is the characteristic equation of the ODE. Its roots determine the general solution form. Using the quadratic formula

$$\lambda_{1,2} = \frac{-B}{2A} \pm \frac{1}{2A} \sqrt{B^2 - 4AC}$$

Substituting $A = 1, B = 0, C = 4$ into the above gives

$$\begin{aligned}\lambda_{1,2} &= \frac{0}{(2)(1)} \pm \frac{1}{(2)(1)} \sqrt{0^2 - (4)(1)(4)} \\ &= \pm 2i\end{aligned}$$

Hence

$$\lambda_1 = +2i$$

$$\lambda_2 = -2i$$

Which simplifies to

$$\lambda_1 = 2i$$

$$\lambda_2 = -2i$$

Since roots are complex conjugate of each others, then let the roots be

$$\lambda_{1,2} = \alpha \pm i\beta$$

Where $\alpha = 0$ and $\beta = 2$. Therefore the final solution, when using Euler relation, can be written as

$$y(\tau) = e^{\alpha\tau}(c_1 \cos(\beta\tau) + c_2 \sin(\beta\tau))$$

Which becomes

$$y(\tau) = e^0(c_1 \cos(2\tau) + c_2 \sin(2\tau))$$

Or

$$y(\tau) = c_1 \cos(2\tau) + c_2 \sin(2\tau)$$

The above solution is now transformed back to y using (6) which results in

$$y = c_1 \cos(2 \ln(x)) + c_2 \sin(2 \ln(x))$$

Therefore the homogeneous solution y_h is

$$y_h = c_1 \cos(2 \ln(x)) + c_2 \sin(2 \ln(x))$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \sin(\ln(x)) \cos(\ln(x))$$

$$y_2 = 2 \cos(\ln(x))^2 - 1$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \tag{2}$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \tag{3}$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \sin(\ln(x)) \cos(\ln(x)) & 2 \cos(\ln(x))^2 - 1 \\ \frac{d}{dx}(\sin(\ln(x)) \cos(\ln(x))) & \frac{d}{dx}(2 \cos(\ln(x))^2 - 1) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \sin(\ln(x)) \cos(\ln(x)) & 2 \cos(\ln(x))^2 - 1 \\ \frac{\cos(\ln(x))^2}{x} - \frac{\sin(\ln(x))^2}{x} & -\frac{4 \cos(\ln(x)) \sin(\ln(x))}{x} \end{vmatrix}$$

Therefore

$$W = (\sin(\ln(x)) \cos(\ln(x))) \left(-\frac{4 \cos(\ln(x)) \sin(\ln(x))}{x} \right) - (2 \cos(\ln(x))^2 - 1) \left(\frac{\cos(\ln(x))^2}{x} - \frac{\sin(\ln(x))^2}{x} \right)$$

Which simplifies to

$$W = -\frac{2 \sin(\ln(x))^2 \cos(\ln(x))^2 + 2 \cos(\ln(x))^4 + \sin(\ln(x))^2 - \cos(\ln(x))^2}{x}$$

Which simplifies to

$$W = -\frac{1}{x}$$

Therefore Eq. (2) becomes

$$u_1 = -\int \frac{4(2 \cos(\ln(x))^2 - 1) \sin(\ln(x))}{-x} dx$$

Which simplifies to

$$u_1 = -\int \frac{-8 \sin(\ln(x)) \cos(\ln(x))^2 + 4 \sin(\ln(x))}{x} dx$$

Hence

$$u_1 = -\frac{8 \cos(\ln(x))^3}{3} + 4 \cos(\ln(x))$$

And Eq. (3) becomes

$$u_2 = \int \frac{4 \sin(\ln(x))^2 \cos(\ln(x))}{-x} dx$$

Which simplifies to

$$u_2 = \int -\frac{4 \sin(\ln(x))^2 \cos(\ln(x))}{x} dx$$

Hence

$$u_2 = -\frac{4 \sin(\ln(x))^3}{3}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \left(-\frac{8 \cos(\ln(x))^3}{3} + 4 \cos(\ln(x)) \right) \sin(\ln(x)) \cos(\ln(x)) - \frac{4 \sin(\ln(x))^3 (2 \cos(\ln(x))^2 - 1)}{3}$$

Which simplifies to

$$y_p(x) = \frac{4 \sin(\ln(x))}{3}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 \cos(2 \ln(x)) + c_2 \sin(2 \ln(x))) + \left(\frac{4 \sin(\ln(x))}{3} \right) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = \frac{4 \sin(\ln(x))}{3} + c_1 \cos(2 \ln(x)) + c_2 \sin(2 \ln(x)) \quad (1)$$

Verification of solutions

$$y = \frac{4 \sin(\ln(x))}{3} + c_1 \cos(2 \ln(x)) + c_2 \sin(2 \ln(x))$$

Verified OK.

13.18.3 Solving as second order change of variable on x method 1 ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = x^2$, $B = x$, $C = 4$, $f(x) = 4 \sin(\ln(x))$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. Solving for y_h from

$$x^2y'' + y'x + 4y = 0$$

In normal form the ode

$$x^2y'' + y'x + 4y = 0 \tag{1}$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \tag{2}$$

Where

$$p(x) = \frac{1}{x}$$
$$q(x) = \frac{4}{x^2}$$

Applying change of variables $\tau = g(x)$ to (2) results

$$\frac{d^2}{d\tau^2}y(\tau) + p_1\left(\frac{d}{d\tau}y(\tau)\right) + q_1y(\tau) = 0 \tag{3}$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \tag{4}$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \tag{5}$$

Let $q_1 = c^2$ where c is some constant. Therefore from (5)

$$\tau' = \frac{1}{c}\sqrt{q}$$
$$= \frac{2\sqrt{\frac{1}{x^2}}}{c} \tag{6}$$
$$\tau'' = -\frac{2}{c\sqrt{\frac{1}{x^2}}x^3}$$

Substituting the above into (4) results in

$$\begin{aligned}
 p_1(\tau) &= \frac{\tau''(x) + p(x) \tau'(x)}{\tau'(x)^2} \\
 &= \frac{-\frac{2}{c\sqrt{\frac{1}{x^2}}x^3} + \frac{1}{x} \frac{2\sqrt{\frac{1}{x^2}}}{c}}{\left(\frac{2\sqrt{\frac{1}{x^2}}}{c}\right)^2} \\
 &= 0
 \end{aligned}$$

Therefore ode (3) now becomes

$$\begin{aligned}
 y(\tau)'' + p_1 y(\tau)' + q_1 y(\tau) &= 0 \\
 \frac{d^2}{d\tau^2} y(\tau) + c^2 y(\tau) &= 0 \tag{7}
 \end{aligned}$$

The above ode is now solved for $y(\tau)$. Since the ode is now constant coefficients, it can be easily solved to give

$$y(\tau) = c_1 \cos(c\tau) + c_2 \sin(c\tau)$$

Now from (6)

$$\begin{aligned}
 \tau &= \int \frac{1}{c} \sqrt{q} dx \\
 &= \frac{\int 2\sqrt{\frac{1}{x^2}} dx}{c} \\
 &= \frac{2\sqrt{\frac{1}{x^2}} x \ln(x)}{c}
 \end{aligned}$$

Substituting the above into the solution obtained gives

$$y = c_1 \cos(2 \ln(x)) + c_2 \sin(2 \ln(x))$$

Now the particular solution to this ODE is found

$$x^2 y'' + y' x + 4y = 4 \sin(\ln(x))$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of

parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \sin(\ln(x)) \cos(\ln(x))$$

$$y_2 = 2 \cos(\ln(x))^2 - 1$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \sin(\ln(x)) \cos(\ln(x)) & 2 \cos(\ln(x))^2 - 1 \\ \frac{d}{dx}(\sin(\ln(x)) \cos(\ln(x))) & \frac{d}{dx}(2 \cos(\ln(x))^2 - 1) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \sin(\ln(x)) \cos(\ln(x)) & 2 \cos(\ln(x))^2 - 1 \\ \frac{\cos(\ln(x))^2}{x} - \frac{\sin(\ln(x))^2}{x} & -\frac{4 \cos(\ln(x)) \sin(\ln(x))}{x} \end{vmatrix}$$

Therefore

$$W = (\sin(\ln(x)) \cos(\ln(x))) \left(-\frac{4 \cos(\ln(x)) \sin(\ln(x))}{x} \right) - (2 \cos(\ln(x))^2 - 1) \left(\frac{\cos(\ln(x))^2}{x} - \frac{\sin(\ln(x))^2}{x} \right)$$

Which simplifies to

$$W = -\frac{2 \sin(\ln(x))^2 \cos(\ln(x))^2 + 2 \cos(\ln(x))^4 + \sin(\ln(x))^2 - \cos(\ln(x))^2}{x}$$

Which simplifies to

$$W = -\frac{1}{x}$$

Therefore Eq. (2) becomes

$$u_1 = -\int \frac{4(2 \cos(\ln(x))^2 - 1) \sin(\ln(x))}{-x} dx$$

Which simplifies to

$$u_1 = -\int \frac{-8 \sin(\ln(x)) \cos(\ln(x))^2 + 4 \sin(\ln(x))}{x} dx$$

Hence

$$u_1 = -\frac{8 \cos(\ln(x))^3}{3} + 4 \cos(\ln(x))$$

And Eq. (3) becomes

$$u_2 = \int \frac{4 \sin(\ln(x))^2 \cos(\ln(x))}{-x} dx$$

Which simplifies to

$$u_2 = \int -\frac{4 \sin(\ln(x))^2 \cos(\ln(x))}{x} dx$$

Hence

$$u_2 = -\frac{4 \sin(\ln(x))^3}{3}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \left(-\frac{8 \cos(\ln(x))^3}{3} + 4 \cos(\ln(x)) \right) \sin(\ln(x)) \cos(\ln(x)) - \frac{4 \sin(\ln(x))^3 (2 \cos(\ln(x))^2 - 1)}{3}$$

Which simplifies to

$$y_p(x) = \frac{4 \sin(\ln(x))}{3}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= (c_1 \cos(2 \ln(x)) + c_2 \sin(2 \ln(x))) + \left(\frac{4 \sin(\ln(x))}{3} \right) \\ &= \frac{4 \sin(\ln(x))}{3} + c_1 \cos(2 \ln(x)) + c_2 \sin(2 \ln(x)) \end{aligned}$$

Which simplifies to

$$y = \frac{4 \sin(\ln(x))}{3} + c_1 \cos(2 \ln(x)) + c_2 \sin(2 \ln(x))$$

Summary

The solution(s) found are the following

$$y = \frac{4 \sin(\ln(x))}{3} + c_1 \cos(2 \ln(x)) + c_2 \sin(2 \ln(x)) \quad (1)$$

Verification of solutions

$$y = \frac{4 \sin(\ln(x))}{3} + c_1 \cos(2 \ln(x)) + c_2 \sin(2 \ln(x))$$

Verified OK.

13.18.4 Solving as second order change of variable on y method 2 ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = x^2$, $B = x$, $C = 4$, $f(x) = 4 \sin(\ln(x))$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. Solving for y_h from

$$x^2 y'' + y' x + 4y = 0$$

In normal form the ode

$$x^2 y'' + y' x + 4y = 0 \quad (1)$$

Becomes

$$y'' + p(x) y' + q(x) y = 0 \quad (2)$$

Where

$$p(x) = \frac{1}{x}$$
$$q(x) = \frac{4}{x^2}$$

Applying change of variables on the dependent variable $y = v(x) x^n$ to (2) gives the following ode where the dependent variables is $v(x)$ and not y .

$$v''(x) + \left(\frac{2n}{x} + p \right) v'(x) + \left(\frac{n(n-1)}{x^2} + \frac{np}{x} + q \right) v(x) = 0 \quad (3)$$

Let the coefficient of $v(x)$ above be zero. Hence

$$\frac{n(n-1)}{x^2} + \frac{np}{x} + q = 0 \quad (4)$$

Substituting the earlier values found for $p(x)$ and $q(x)$ into (4) gives

$$\frac{n(n-1)}{x^2} + \frac{n}{x^2} + \frac{4}{x^2} = 0 \quad (5)$$

Solving (5) for n gives

$$n = 2i \quad (6)$$

Substituting this value in (3) gives

$$v''(x) + \left(\frac{4i}{x} + \frac{1}{x} \right) v'(x) = 0$$
$$v''(x) + \frac{(1+4i)v'(x)}{x} = 0 \quad (7)$$

Using the substitution

$$u(x) = v'(x)$$

Then (7) becomes

$$u'(x) + \frac{(1 + 4i)u(x)}{x} = 0 \quad (8)$$

The above is now solved for $u(x)$. In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= \frac{(-1 - 4i)u}{x} \end{aligned}$$

Where $f(x) = \frac{-1-4i}{x}$ and $g(u) = u$. Integrating both sides gives

$$\begin{aligned} \frac{1}{u} du &= \frac{-1 - 4i}{x} dx \\ \int \frac{1}{u} du &= \int \frac{-1 - 4i}{x} dx \\ \ln(u) &= (-1 - 4i) \ln(x) + c_1 \\ u &= e^{(-1-4i)\ln(x)+c_1} \\ &= c_1 e^{(-1-4i)\ln(x)} \end{aligned}$$

Which simplifies to

$$u(x) = \frac{c_1 x^{-4i}}{x}$$

Now that $u(x)$ is known, then

$$\begin{aligned} v'(x) &= u(x) \\ v(x) &= \int u(x) dx + c_2 \\ &= \frac{ic_1 x^{-4i}}{4} + c_2 \end{aligned}$$

Hence

$$\begin{aligned} y &= v(x) x^n \\ &= \left(\frac{ic_1 x^{-4i}}{4} + c_2 \right) x^{2i} \\ &= x^{2i} c_2 + \frac{ix^{-2i} c_1}{4} \end{aligned}$$

Now the particular solution to this ODE is found

$$x^2y'' + y'x + 4y = 4 \sin(\ln(x))$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1y_1 + u_2y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = x^{2i}$$

$$y_2 = x^{2i}x^{-4i}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} x^{2i} & x^{2i}x^{-4i} \\ \frac{d}{dx}(x^{2i}) & \frac{d}{dx}(x^{2i}x^{-4i}) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} x^{2i} & x^{2i}x^{-4i} \\ \frac{2ix^{2i}}{x} & -\frac{2ix^{2i}x^{-4i}}{x} \end{vmatrix}$$

Therefore

$$W = (x^{2i}) \left(-\frac{2ix^{2i}x^{-4i}}{x} \right) - (x^{2i}x^{-4i}) \left(\frac{2ix^{2i}}{x} \right)$$

Which simplifies to

$$W = -\frac{4ix^{4i}x^{-4i}}{x}$$

Which simplifies to

$$W = -\frac{4i}{x}$$

Therefore Eq. (2) becomes

$$u_1 = -\int \frac{4x^{2i}x^{-4i} \sin(\ln(x))}{-4ix} dx$$

Which simplifies to

$$u_1 = -\int ix^{-1-2i} \sin(\ln(x)) dx$$

Hence

$$u_1 = \text{undefined}$$

And Eq. (3) becomes

$$u_2 = \int \frac{4x^{2i} \sin(\ln(x))}{-4ix} dx$$

Which simplifies to

$$u_2 = \int ix^{-1+2i} \sin(\ln(x)) dx$$

Hence

$$u_2 = \text{undefined}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \text{undefined } x^{2i} + \text{undefined } x^{2i}x^{-4i}$$

Which simplifies to

$$y_p(x) = \text{undefined } (x^{2i} + x^{-2i})$$

Therefore the general solution is

$$\begin{aligned}
 y &= y_h + y_p \\
 &= \left(\left(\frac{ic_1 x^{-4i}}{4} + c_2 \right) x^{2i} \right) + (\text{undefined} (x^{2i} + x^{-2i})) \\
 &= \text{undefined} (x^{2i} + x^{-2i}) + \left(\frac{ic_1 x^{-4i}}{4} + c_2 \right) x^{2i}
 \end{aligned}$$

Which simplifies to

$$y = \frac{(ic_1 + \text{undefined}) x^{-2i}}{4} + (\text{undefined} + c_2) x^{2i}$$

Summary

The solution(s) found are the following

$$y = \frac{(ic_1 + \text{undefined}) x^{-2i}}{4} + (\text{undefined} + c_2) x^{2i} \quad (1)$$

Verification of solutions

$$y = \frac{(ic_1 + \text{undefined}) x^{-2i}}{4} + (\text{undefined} + c_2) x^{2i}$$

Verified OK.

13.18.5 Solving using Kovacic algorithm

Writing the ode as

$$x^2 y'' + y' x + 4y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned}
 A &= x^2 \\
 B &= x \\
 C &= 4
 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{-17}{4x^2} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= -17 \\ t &= 4x^2 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = \left(-\frac{17}{4x^2}\right) z(x) \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 495: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 2 - 0 \\ &= 2 \end{aligned}$$

The poles of r in eq. (7) and the order of each pole are determined by solving for the roots of $t = 4x^2$. There is a pole at $x = 0$ of order 2. Since there is no odd order pole larger than 2 and the order at ∞ is 2 then the necessary conditions for case one are met. Since there is a pole of order 2 then necessary conditions for case two are met. Since pole order is not larger than 2 and the order at ∞ is 2 then the necessary conditions for case three are met. Therefore

$$L = [1, 2, 4, 6, 12]$$

Attempting to find a solution using case $n = 1$.

Looking at poles of order 2. The partial fractions decomposition of r is

$$r = -\frac{17}{4x^2}$$

For the pole at $x = 0$ let b be the coefficient of $\frac{1}{x^2}$ in the partial fractions decomposition of r given above. Therefore $b = -\frac{17}{4}$. Hence

$$\begin{aligned} [\sqrt{r}]_c &= 0 \\ \alpha_c^+ &= \frac{1}{2} + \sqrt{1 + 4b} = \frac{1}{2} + 2i \\ \alpha_c^- &= \frac{1}{2} - \sqrt{1 + 4b} = \frac{1}{2} - 2i \end{aligned}$$

Since the order of r at ∞ is 2 then $[\sqrt{r}]_\infty = 0$. Let b be the coefficient of $\frac{1}{x^2}$ in the Laurent series expansion of r at ∞ , which can be found by dividing the leading coefficient of s by the leading coefficient of t from

$$r = \frac{s}{t} = -\frac{17}{4x^2}$$

Since the $\gcd(s, t) = 1$. This gives $b = -\frac{17}{4}$. Hence

$$\begin{aligned} [\sqrt{r}]_\infty &= 0 \\ \alpha_\infty^+ &= \frac{1}{2} + \sqrt{1 + 4b} = \frac{1}{2} + 2i \\ \alpha_\infty^- &= \frac{1}{2} - \sqrt{1 + 4b} = \frac{1}{2} - 2i \end{aligned}$$

The following table summarizes the findings so far for poles and for the order of r at ∞ where r is

$$r = -\frac{17}{4x^2}$$

pole c location	pole order	$[\sqrt{r}]_c$	α_c^+	α_c^-
0	2	0	$\frac{1}{2} + 2i$	$\frac{1}{2} - 2i$

Order of r at ∞	$[\sqrt{r}]_\infty$	α_∞^+	α_∞^-
2	0	$\frac{1}{2} + 2i$	$\frac{1}{2} - 2i$

Now that the all $[\sqrt{r}]_c$ and its associated α_c^\pm have been determined for all the poles in the set Γ and $[\sqrt{r}]_\infty$ and its associated α_∞^\pm have also been found, the next step is to determine possible non negative integer d from these using

$$d = \alpha_\infty^{s(\infty)} - \sum_{c \in \Gamma} \alpha_c^{s(c)}$$

Where $s(c)$ is either $+$ or $-$ and $s(\infty)$ is the sign of α_∞^\pm . This is done by trial over all set of families $s = (s(c))_{c \in \Gamma \cup \infty}$ until such d is found to work in finding candidate ω . Trying $\alpha_\infty^- = \frac{1}{2} - 2i$ then

$$\begin{aligned} d &= \alpha_\infty^- - (\alpha_{c_1}^-) \\ &= \frac{1}{2} - 2i - \left(\frac{1}{2} - 2i\right) \\ &= 0 \end{aligned}$$

Since d an integer and $d \geq 0$ then it can be used to find ω using

$$\omega = \sum_{c \in \Gamma} \left(s(c) [\sqrt{r}]_c + \frac{\alpha_c^{s(c)}}{x - c} \right) + s(\infty) [\sqrt{r}]_\infty$$

The above gives

$$\begin{aligned} \omega &= \left((-) [\sqrt{r}]_{c_1} + \frac{\alpha_{c_1}^-}{x - c_1} \right) + (-) [\sqrt{r}]_\infty \\ &= \frac{\frac{1}{2} - 2i}{x} + (-) (0) \\ &= \frac{\frac{1}{2} - 2i}{x} \\ &= \frac{\frac{1}{2} - 2i}{x} \end{aligned}$$

Now that ω is determined, the next step is find a corresponding minimal polynomial $p(x)$ of degree $d = 0$ to solve the ode. The polynomial $p(x)$ needs to satisfy the equation

$$p'' + 2\omega p' + (\omega' + \omega^2 - r) p = 0 \quad (1A)$$

Let

$$p(x) = 1 \quad (2A)$$

Substituting the above in eq. (1A) gives

$$(0) + 2\left(\frac{\frac{1}{2} - 2i}{x}\right) (0) + \left(\left(\frac{-\frac{1}{2} + 2i}{x^2}\right) + \left(\frac{\frac{1}{2} - 2i}{x}\right)^2 - \left(-\frac{17}{4x^2}\right)\right) = 0$$

$$0 = 0$$

The equation is satisfied since both sides are zero. Therefore the first solution to the ode $z'' = rz$ is

$$\begin{aligned} z_1(x) &= pe^{\int \omega dx} \\ &= e^{\int \frac{\frac{1}{2} - 2i}{x} dx} \\ &= x^{\frac{1}{2} - 2i} \end{aligned}$$

The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{x}{x^2} dx} \\ &= z_1 e^{-\frac{\ln(x)}{2}} \\ &= z_1 \left(\frac{1}{\sqrt{x}}\right) \end{aligned}$$

Which simplifies to

$$y_1 = x^{-2i}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{x}{x^2} dx}}{(y_1)^2} dx \\&= y_1 \int \frac{e^{-\ln(x)}}{(y_1)^2} dx \\&= y_1 \left(-\frac{ix^{4i}}{4} \right)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\&= c_1 (x^{-2i}) + c_2 \left(x^{-2i} \left(-\frac{ix^{4i}}{4} \right) \right)\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$x^2 y'' + y' x + 4y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = x^{-2i} c_1 - \frac{ic_2 x^{2i}}{4}$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = x^{-2i}$$

$$y_2 = -\frac{ix^{2i}}{4}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = -\int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} x^{-2i} & -\frac{ix^{2i}}{4} \\ \frac{d}{dx}(x^{-2i}) & \frac{d}{dx}\left(-\frac{ix^{2i}}{4}\right) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} x^{-2i} & -\frac{ix^{2i}}{4} \\ -\frac{2ix^{-2i}}{x} & \frac{x^{2i}}{2x} \end{vmatrix}$$

Therefore

$$W = (x^{-2i}) \left(\frac{x^{2i}}{2x}\right) - \left(-\frac{ix^{2i}}{4}\right) \left(-\frac{2ix^{-2i}}{x}\right)$$

Which simplifies to

$$W = \frac{x^{-2i} x^{2i}}{x}$$

Which simplifies to

$$W = \frac{1}{x}$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{-ix^{2i} \sin(\ln(x))}{x} dx$$

Which simplifies to

$$u_1 = - \int -ix^{-1+2i} \sin(\ln(x)) dx$$

Hence

$$u_1 = \text{undefined}$$

And Eq. (3) becomes

$$u_2 = \int \frac{4x^{-2i} \sin(\ln(x))}{x} dx$$

Which simplifies to

$$u_2 = \int 4x^{-1-2i} \sin(\ln(x)) dx$$

Hence

$$u_2 = \text{undefined}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \text{undefined } x^{-2i} - i \text{undefined } x^{2i}$$

Which simplifies to

$$y_p(x) = (ix^{2i} + x^{-2i}) \text{undefined}$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(x^{-2i} c_1 - \frac{ic_2 x^{2i}}{4} \right) + ((ix^{2i} + x^{-2i}) \text{undefined}) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = x^{-2i} c_1 - \frac{ic_2 x^{2i}}{4} + (ix^{2i} + x^{-2i}) \text{undefined} \quad (1)$$

Verification of solutions

$$y = x^{-2i} c_1 - \frac{ic_2 x^{2i}}{4} + (ix^{2i} + x^{-2i}) \text{ undefined}$$

Verified OK.

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]  
trying a double symmetry of the form [xi=0, eta=F(x)]  
-> Try solving first the homogeneous part of the ODE  
    checking if the LODE has constant coefficients  
    checking if the LODE is of Euler type  
    <- LODE of Euler type successful  
<- solving first the homogeneous part of the ODE successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 24

```
dsolve(x^2*diff(y(x),x$2)+x*diff(y(x),x)+4*y(x)=4*sin(ln(x)),y(x), singsol=all)
```

$$y(x) = \sin(2 \ln(x)) c_2 + \cos(2 \ln(x)) c_1 + \frac{4 \sin(\ln(x))}{3}$$

✓ Solution by Mathematica

Time used: 0.176 (sec). Leaf size: 29

```
DSolve[x^2*y''[x]+x*y'[x]+4*y[x]==4*Sin[Log[x]],y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{4}{3} \sin(\log(x)) + c_1 \cos(2 \log(x)) + c_2 \sin(2 \log(x))$$

13.19 problem 19

13.19.1 Maple step by step solution 3587

Internal problem ID [11873]

Internal file name [OUTPUT/11882_Saturday_April_13_2024_01_13_53_AM_23825213/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.5. The Cauchy-Euler Equation. Exercises page 169

Problem number: 19.

ODE order: 3.

ODE degree: 1.

The type(s) of ODE detected by this program : "**higher_order_ODE_non_constant_coefficients_of_type_Euler**"

Maple gives the following as the ode type

```
[[_3rd_order , _with_linear_symmetries]]
```

$$x^3y''' - x^2y'' + 2y'x - 2y = x^3$$

This is higher order nonhomogeneous Euler type ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous Euler ODE And y_p is a particular solution to the nonhomogeneous Euler ODE. y_h is the solution to

$$x^3y''' - x^2y'' + 2y'x - 2y = 0$$

This is Euler ODE of higher order. Let $y = x^\lambda$. Hence

$$y' = \lambda x^{\lambda-1}$$

$$y'' = \lambda(\lambda - 1) x^{\lambda-2}$$

$$y''' = \lambda(\lambda - 1)(\lambda - 2) x^{\lambda-3}$$

Substituting these back into

$$x^3y''' - x^2y'' + 2y'x - 2y = x^3$$

gives

$$2x\lambda x^{\lambda-1} - x^2\lambda(\lambda-1)x^{\lambda-2} + x^3\lambda(\lambda-1)(\lambda-2)x^{\lambda-3} - 2x^\lambda = 0$$

Which simplifies to

$$2\lambda x^\lambda - \lambda(\lambda-1)x^\lambda + \lambda(\lambda-1)(\lambda-2)x^\lambda - 2x^\lambda = 0$$

And since $x^\lambda \neq 0$ then dividing through by x^λ , the above becomes

$$2\lambda - \lambda(\lambda-1) + \lambda(\lambda-1)(\lambda-2) - 2 = 0$$

Simplifying gives the characteristic equation as

$$(\lambda-2)(\lambda-1)^2 = 0$$

Solving the above gives the following roots

$$\lambda_1 = 2$$

$$\lambda_2 = 1$$

$$\lambda_3 = 1$$

This table summarises the result

root	multiplicity	type of root
1	2	real root
2	1	real root

The solution is generated by going over the above table. For each real root λ of multiplicity one generates a c_1x^λ basis solution. Each real root of multiplicity two, generates c_1x^λ and $c_2x^\lambda \ln(x)$ basis solutions. Each real root of multiplicity three, generates c_1x^λ and $c_2x^\lambda \ln(x)$ and $c_3x^\lambda \ln(x)^2$ basis solutions, and so on. Each complex root $\alpha \pm i\beta$ of multiplicity one generates $x^\alpha(c_1 \cos(\beta \ln(x)) + c_2 \sin(\beta \ln(x)))$ basis solutions. And each complex root $\alpha \pm i\beta$ of multiplicity two generates $\ln(x)x^\alpha(c_1 \cos(\beta \ln(x)) + c_2 \sin(\beta \ln(x)))$ basis solutions. And each complex root $\alpha \pm i\beta$ of multiplicity three generates $\ln(x)^2 x^\alpha(c_1 \cos(\beta \ln(x)) + c_2 \sin(\beta \ln(x)))$ basis solutions. And so on. Using the above show that the solution is

$$y = c_1x + c_2 \ln(x)x + c_3x^2$$

The fundamental set of solutions for the homogeneous solution are the following

$$y_1 = x$$

$$y_2 = x \ln(x)$$

$$y_3 = x^2$$

Now the particular solution to the given ODE is found

$$x^3 y''' - x^2 y'' + 2y'x - 2y = x^3$$

Let the particular solution be

$$y_p = U_1 y_1 + U_2 y_2 + U_3 y_3$$

Where y_i are the basis solutions found above for the homogeneous solution y_h and $U_i(x)$ are functions to be determined as follows

$$U_i = (-1)^{n-i} \int \frac{F(x)W_i(x)}{aW(x)} dx$$

Where $W(x)$ is the Wronskian and $W_i(x)$ is the Wronskian that results after deleting the last row and the i -th column of the determinant and n is the order of the ODE or equivalently, the number of basis solutions, and a is the coefficient of the leading derivative in the ODE, and $F(x)$ is the RHS of the ODE. Therefore, the first step is to find the Wronskian $W(x)$. This is given by

$$W(x) = \begin{vmatrix} y_1 & y_2 & y_3 \\ y_1' & y_2' & y_3' \\ y_1'' & y_2'' & y_3'' \end{vmatrix}$$

Substituting the fundamental set of solutions y_i found above in the Wronskian gives

$$W = \begin{bmatrix} x & x \ln(x) & x^2 \\ 1 & \ln(x) + 1 & 2x \\ 0 & \frac{1}{x} & 2 \end{bmatrix}$$

$$|W| = x$$

The determinant simplifies to

$$|W| = x$$

Now we determine W_i for each U_i .

$$\begin{aligned}W_1(x) &= \det \begin{bmatrix} x \ln(x) & x^2 \\ \ln(x) + 1 & 2x \end{bmatrix} \\ &= x^2(\ln(x) - 1)\end{aligned}$$

$$\begin{aligned}W_2(x) &= \det \begin{bmatrix} x & x^2 \\ 1 & 2x \end{bmatrix} \\ &= x^2\end{aligned}$$

$$\begin{aligned}W_3(x) &= \det \begin{bmatrix} x & x \ln(x) \\ 1 & \ln(x) + 1 \end{bmatrix} \\ &= x\end{aligned}$$

Now we are ready to evaluate each $U_i(x)$.

$$\begin{aligned}U_1 &= (-1)^{3-1} \int \frac{F(x)W_1(x)}{aW(x)} dx \\ &= (-1)^2 \int \frac{(x^3)(x^2(\ln(x) - 1))}{(x^3)(x)} dx \\ &= \int \frac{x^5(\ln(x) - 1)}{x^4} dx \\ &= \int (x(\ln(x) - 1)) dx \\ &= \frac{x^2 \ln(x)}{2} - \frac{3x^2}{4}\end{aligned}$$

$$\begin{aligned}U_2 &= (-1)^{3-2} \int \frac{F(x)W_2(x)}{aW(x)} dx \\ &= (-1)^1 \int \frac{(x^3)(x^2)}{(x^3)(x)} dx \\ &= - \int \frac{x^5}{x^4} dx \\ &= - \int (x) dx \\ &= -\frac{x^2}{2}\end{aligned}$$

$$\begin{aligned}
U_3 &= (-1)^{3-3} \int \frac{F(x)W_3(x)}{aW(x)} dx \\
&= (-1)^0 \int \frac{(x^3)(x)}{(x^3)(x)} dx \\
&= \int \frac{x^4}{x^4} dx \\
&= \int (1) dx \\
&= x
\end{aligned}$$

Now that all the U_i functions have been determined, the particular solution is found from

$$y_p = U_1y_1 + U_2y_2 + U_3y_3$$

Hence

$$\begin{aligned}
y_p &= \left(\frac{x^2 \ln(x)}{2} - \frac{3x^2}{4} \right) (x) \\
&\quad + \left(-\frac{x^2}{2} \right) (x \ln(x)) \\
&\quad + (x) (x^2)
\end{aligned}$$

Therefore the particular solution is

$$y_p = \frac{x^3}{4}$$

Therefore the general solution is

$$\begin{aligned}
y &= y_h + y_p \\
&= (c_1x + c_2 \ln(x)x + c_3x^2) + \left(\frac{x^3}{4} \right)
\end{aligned}$$

Which simplifies to

$$y = x(\ln(x)c_2 + c_3x + c_1) + \frac{x^3}{4}$$

Summary

The solution(s) found are the following

$$y = x(\ln(x)c_2 + c_3x + c_1) + \frac{x^3}{4} \tag{1}$$

Verification of solutions

$$y = x(\ln(x) c_2 + c_3 x + c_1) + \frac{x^3}{4}$$

Verified OK.

13.19.1 Maple step by step solution

Let's solve

$$x^3 y''' - y'' x^2 + 2y' x - 2y = x^3$$

- Highest derivative means the order of the ODE is 3

$$y'''$$

Maple trace

```
`Methods for third order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
trying differential order: 3; linear nonhomogeneous with symmetry [0,1]  
trying high order linear exact nonhomogeneous  
trying differential order: 3; missing the dependent variable  
checking if the LODE is of Euler type  
<- LODE of Euler type successful  
Euler equation successful`
```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 23

```
dsolve(x^3*diff(y(x),x$3)-x^2*diff(y(x),x$2)+2*x*diff(y(x),x)-2*y(x)=x^3,y(x), singsol=all)
```

$$y(x) = \frac{x(4c_3 \ln(x) + 4c_2 x + x^2 + 4c_1)}{4}$$

✓ Solution by Mathematica

Time used: 0.005 (sec). Leaf size: 29

```
DSolve[x^3*y'''[x]-x^2*y''[x]+2*x*y'[x]-2*y[x]==x^3,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow \frac{1}{4}x(x^2 + 4c_3x + 4c_2 \log(x) + 4c_1)$$

13.20 problem 20

13.20.1 Existence and uniqueness analysis	3590
13.20.2 Solving as second order euler ode ode	3590
13.20.3 Solving as second order change of variable on x method 2 ode .	3592
13.20.4 Solving as second order change of variable on y method 2 ode .	3596
13.20.5 Solving using Kovacic algorithm	3599
13.20.6 Maple step by step solution	3606

Internal problem ID [11874]

Internal file name [OUTPUT/11883_Saturday_April_13_2024_01_13_54_AM_33597945/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.5. The Cauchy-Euler Equation. Exercises page 169

Problem number: 20.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_euler_ode", "second_order_change_of_variable_on_x_method_2", "second_order_change_of_variable_on_y_method_2"

Maple gives the following as the ode type

```
[[_Emden, _Fowler], [_2nd_order, _linear, `_with_symmetry_[0,F(x)]`]]
```

$$x^2y'' - 2y'x - 10y = 0$$

With initial conditions

$$[y(1) = 5, y'(1) = 4]$$

13.20.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$\begin{aligned}p(x) &= -\frac{2}{x} \\q(x) &= -\frac{10}{x^2} \\F &= 0\end{aligned}$$

Hence the ode is

$$y'' - \frac{2y'}{x} - \frac{10y}{x^2} = 0$$

The domain of $p(x) = -\frac{2}{x}$ is

$$\{x < 0 \vee 0 < x\}$$

And the point $x_0 = 1$ is inside this domain. The domain of $q(x) = -\frac{10}{x^2}$ is

$$\{x < 0 \vee 0 < x\}$$

And the point $x_0 = 1$ is also inside this domain. Hence solution exists and is unique.

13.20.2 Solving as second order euler ode

This is Euler second order ODE. Let the solution be $y = x^r$, then $y' = rx^{r-1}$ and $y'' = r(r-1)x^{r-2}$. Substituting these back into the given ODE gives

$$x^2(r(r-1))x^{r-2} - 2rx^{r-1} - 10x^r = 0$$

Simplifying gives

$$r(r-1)x^r - 2rx^r - 10x^r = 0$$

Since $x^r \neq 0$ then dividing throughout by x^r gives

$$r(r-1) - 2r - 10 = 0$$

Or

$$r^2 - 3r - 10 = 0 \tag{1}$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = -2$$

$$r_2 = 5$$

Since the roots are real and distinct, then the general solution is

$$y = c_1 y_1 + c_2 y_2$$

Where $y_1 = x^{r_1}$ and $y_2 = x^{r_2}$. Hence

$$y = \frac{c_1}{x^2} + c_2 x^5$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = \frac{c_1}{x^2} + c_2 x^5 \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 5$ and $x = 1$ in the above gives

$$5 = c_1 + c_2 \quad (1A)$$

Taking derivative of the solution gives

$$y' = -\frac{2c_1}{x^3} + 5c_2 x^4$$

substituting $y' = 4$ and $x = 1$ in the above gives

$$4 = -2c_1 + 5c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 3$$

$$c_2 = 2$$

Substituting these values back in above solution results in

$$y = \frac{2x^7 + 3}{x^2}$$

Summary

The solution(s) found are the following

$$y = \frac{2x^7 + 3}{x^2} \quad (1)$$

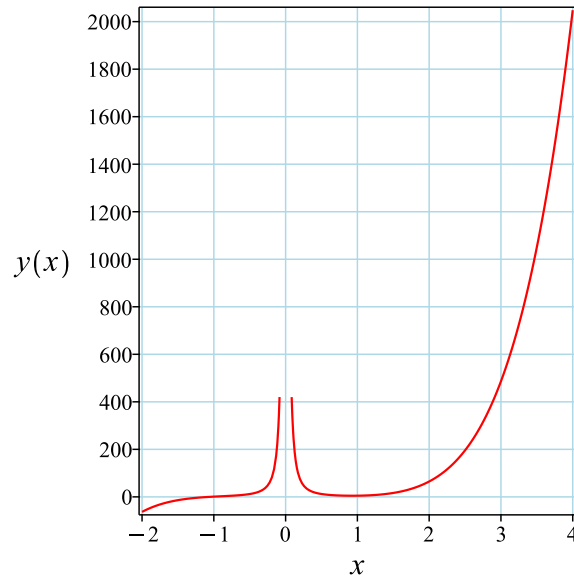


Figure 520: Solution plot

Verification of solutions

$$y = \frac{2x^7 + 3}{x^2}$$

Verified OK.

13.20.3 Solving as second order change of variable on x method 2 ode

In normal form the ode

$$x^2 y'' - 2y'x - 10y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = -\frac{2}{x}$$
$$q(x) = -\frac{10}{x^2}$$

Applying change of variables $\tau = g(x)$ to (2) gives

$$\frac{d^2}{d\tau^2}y(\tau) + p_1\left(\frac{d}{d\tau}y(\tau)\right) + q_1y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $p_1 = 0$. Eq (4) simplifies to

$$\tau''(x) + p(x)\tau'(x) = 0$$

This ode is solved resulting in

$$\begin{aligned} \tau &= \int e^{-(\int p(x)dx)} dx \\ &= \int e^{-(\int -\frac{2}{x}dx)} dx \\ &= \int e^{2\ln(x)} dx \\ &= \int x^2 dx \\ &= \frac{x^3}{3} \end{aligned} \quad (6)$$

Using (6) to evaluate q_1 from (5) gives

$$\begin{aligned} q_1(\tau) &= \frac{q(x)}{\tau'(x)^2} \\ &= \frac{-\frac{10}{x^2}}{x^4} \\ &= -\frac{10}{x^6} \end{aligned} \quad (7)$$

Substituting the above in (3) and noting that now $p_1 = 0$ results in

$$\begin{aligned} \frac{d^2}{d\tau^2}y(\tau) + q_1y(\tau) &= 0 \\ \frac{d^2}{d\tau^2}y(\tau) - \frac{10y(\tau)}{x^6} &= 0 \end{aligned}$$

But in terms of τ

$$-\frac{10}{x^6} = -\frac{10}{9\tau^2}$$

Hence the above ode becomes

$$\frac{d^2}{d\tau^2}y(\tau) - \frac{10y(\tau)}{9\tau^2} = 0$$

The above ode is now solved for $y(\tau)$. The ode can be written as

$$9\left(\frac{d^2}{d\tau^2}y(\tau)\right)\tau^2 - 10y(\tau) = 0$$

Which shows it is a Euler ODE. This is Euler second order ODE. Let the solution be $y(\tau) = \tau^r$, then $y' = r\tau^{r-1}$ and $y'' = r(r-1)\tau^{r-2}$. Substituting these back into the given ODE gives

$$9\tau^2(r(r-1))\tau^{r-2} + 0r\tau^{r-1} - 10\tau^r = 0$$

Simplifying gives

$$9r(r-1)\tau^r + 0\tau^r - 10\tau^r = 0$$

Since $\tau^r \neq 0$ then dividing throughout by τ^r gives

$$9r(r-1) + 0 - 10 = 0$$

Or

$$9r^2 - 9r - 10 = 0 \tag{1}$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = -\frac{2}{3}$$
$$r_2 = \frac{5}{3}$$

Since the roots are real and distinct, then the general solution is

$$y(\tau) = c_1y_1 + c_2y_2$$

Where $y_1 = \tau^{r_1}$ and $y_2 = \tau^{r_2}$. Hence

$$y(\tau) = \frac{c_1}{\tau^{\frac{2}{3}}} + c_2\tau^{\frac{5}{3}}$$

The above solution is now transformed back to y using (6) which results in

$$y = \frac{3^{\frac{1}{3}}\left(c_2x^6(x^3)^{\frac{1}{3}} + 9c_13^{\frac{1}{3}}\right)}{9(x^3)^{\frac{2}{3}}}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = \frac{3^{\frac{1}{3}} \left(c_2 x^6 (x^3)^{\frac{1}{3}} + 9c_1 3^{\frac{1}{3}} \right)}{9 (x^3)^{\frac{2}{3}}} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 5$ and $x = 1$ in the above gives

$$5 = 3^{\frac{2}{3}} c_1 + \frac{3^{\frac{1}{3}} c_2}{9} \quad (1A)$$

Taking derivative of the solution gives

$$y' = \frac{3^{\frac{1}{3}} \left(6c_2 x^5 (x^3)^{\frac{1}{3}} + \frac{c_2 x^8}{(x^3)^{\frac{2}{3}}} \right)}{9 (x^3)^{\frac{2}{3}}} - \frac{2 \cdot 3^{\frac{1}{3}} \left(c_2 x^6 (x^3)^{\frac{1}{3}} + 9c_1 3^{\frac{1}{3}} \right) x^2}{9 (x^3)^{\frac{5}{3}}}$$

substituting $y' = 4$ and $x = 1$ in the above gives

$$4 = -2 \cdot 3^{\frac{2}{3}} c_1 + \frac{5 \cdot 3^{\frac{1}{3}} c_2}{9} \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 3^{\frac{1}{3}}$$

$$c_2 = 6 \cdot 3^{\frac{2}{3}}$$

Substituting these values back in above solution results in

$$y = \frac{2x^6 (x^3)^{\frac{1}{3}} + 3}{(x^3)^{\frac{2}{3}}}$$

Summary

The solution(s) found are the following

$$y = \frac{2x^6 (x^3)^{\frac{1}{3}} + 3}{(x^3)^{\frac{2}{3}}} \quad (1)$$

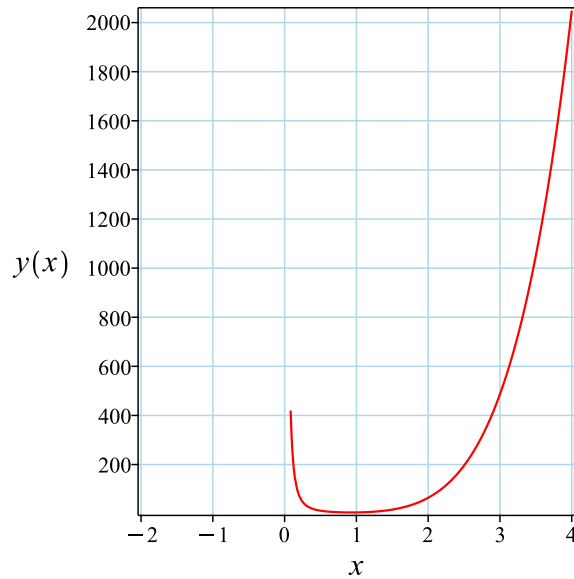


Figure 521: Solution plot

Verification of solutions

$$y = \frac{2x^6(x^3)^{\frac{1}{3}} + 3}{(x^3)^{\frac{2}{3}}}$$

Verified OK.

13.20.4 Solving as second order change of variable on y method 2 ode

In normal form the ode

$$x^2y'' - 2y'x - 10y = 0 \tag{1}$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \tag{2}$$

Where

$$p(x) = -\frac{2}{x}$$

$$q(x) = -\frac{10}{x^2}$$

Applying change of variables on the dependent variable $y = v(x)x^n$ to (2) gives the following ode where the dependent variables is $v(x)$ and not y .

$$v''(x) + \left(\frac{2n}{x} + p\right)v'(x) + \left(\frac{n(n-1)}{x^2} + \frac{np}{x} + q\right)v(x) = 0 \tag{3}$$

Let the coefficient of $v(x)$ above be zero. Hence

$$\frac{n(n-1)}{x^2} + \frac{np}{x} + q = 0 \quad (4)$$

Substituting the earlier values found for $p(x)$ and $q(x)$ into (4) gives

$$\frac{n(n-1)}{x^2} - \frac{2n}{x^2} - \frac{10}{x^2} = 0 \quad (5)$$

Solving (5) for n gives

$$n = 5 \quad (6)$$

Substituting this value in (3) gives

$$\begin{aligned} v''(x) + \frac{8v'(x)}{x} &= 0 \\ v''(x) + \frac{8v'(x)}{x} &= 0 \end{aligned} \quad (7)$$

Using the substitution

$$u(x) = v'(x)$$

Then (7) becomes

$$u'(x) + \frac{8u(x)}{x} = 0 \quad (8)$$

The above is now solved for $u(x)$. In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= -\frac{8u}{x} \end{aligned}$$

Where $f(x) = -\frac{8}{x}$ and $g(u) = u$. Integrating both sides gives

$$\begin{aligned} \frac{1}{u} du &= -\frac{8}{x} dx \\ \int \frac{1}{u} du &= \int -\frac{8}{x} dx \\ \ln(u) &= -8 \ln(x) + c_1 \\ u &= e^{-8 \ln(x) + c_1} \\ &= \frac{c_1}{x^8} \end{aligned}$$

Now that $u(x)$ is known, then

$$\begin{aligned}v'(x) &= u(x) \\v(x) &= \int u(x) dx + c_2 \\&= -\frac{c_1}{7x^7} + c_2\end{aligned}$$

Hence

$$\begin{aligned}y &= v(x) x^n \\&= \left(-\frac{c_1}{7x^7} + c_2\right) x^5 \\&= \frac{7c_2x^7 - c_1}{7x^2}\end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = \left(-\frac{c_1}{7x^7} + c_2\right) x^5 \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 5$ and $x = 1$ in the above gives

$$5 = -\frac{c_1}{7} + c_2 \quad (1A)$$

Taking derivative of the solution gives

$$y' = \frac{c_1}{x^3} + 5\left(-\frac{c_1}{7x^7} + c_2\right) x^4$$

substituting $y' = 4$ and $x = 1$ in the above gives

$$4 = \frac{2c_1}{7} + 5c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$\begin{aligned}c_1 &= -21 \\c_2 &= 2\end{aligned}$$

Substituting these values back in above solution results in

$$y = \frac{2x^7 + 3}{x^2}$$

Summary

The solution(s) found are the following

$$y = \frac{2x^7 + 3}{x^2} \quad (1)$$

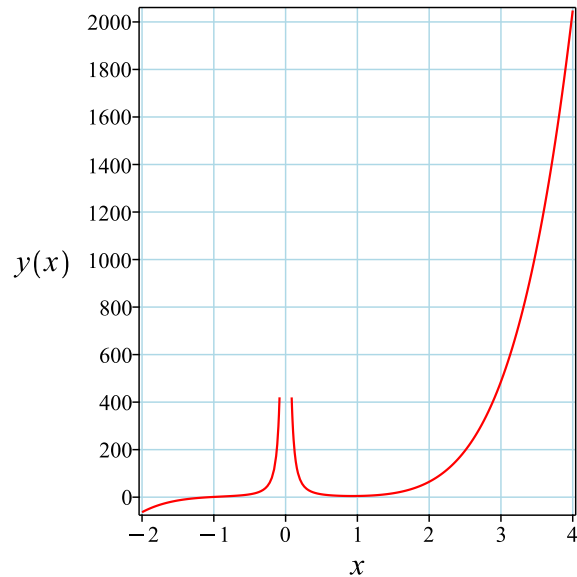


Figure 522: Solution plot

Verification of solutions

$$y = \frac{2x^7 + 3}{x^2}$$

Verified OK.

13.20.5 Solving using Kovacic algorithm

Writing the ode as

$$x^2 y'' - 2y'x - 10y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= x^2 \\ B &= -2x \\ C &= -10 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{12}{x^2} \tag{6}$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 12 \\ t &= x^2 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = \left(\frac{12}{x^2}\right) z(x) \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 497: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned}
 \mathcal{O}(\infty) &= \deg(t) - \deg(s) \\
 &= 2 - 0 \\
 &= 2
 \end{aligned}$$

The poles of r in eq. (7) and the order of each pole are determined by solving for the roots of $t = x^2$. There is a pole at $x = 0$ of order 2. Since there is no odd order pole larger than 2 and the order at ∞ is 2 then the necessary conditions for case one are met. Since there is a pole of order 2 then necessary conditions for case two are met. Since pole order is not larger than 2 and the order at ∞ is 2 then the necessary conditions for case three are met. Therefore

$$L = [1, 2, 4, 6, 12]$$

Attempting to find a solution using case $n = 1$.

Looking at poles of order 2. The partial fractions decomposition of r is

$$r = \frac{12}{x^2}$$

For the pole at $x = 0$ let b be the coefficient of $\frac{1}{x^2}$ in the partial fractions decomposition

of r given above. Therefore $b = 12$. Hence

$$\begin{aligned} [\sqrt{r}]_c &= 0 \\ \alpha_c^+ &= \frac{1}{2} + \sqrt{1 + 4b} = 4 \\ \alpha_c^- &= \frac{1}{2} - \sqrt{1 + 4b} = -3 \end{aligned}$$

Since the order of r at ∞ is 2 then $[\sqrt{r}]_\infty = 0$. Let b be the coefficient of $\frac{1}{x^2}$ in the Laurent series expansion of r at ∞ , which can be found by dividing the leading coefficient of s by the leading coefficient of t from

$$r = \frac{s}{t} = \frac{12}{x^2}$$

Since the $\gcd(s, t) = 1$. This gives $b = 12$. Hence

$$\begin{aligned} [\sqrt{r}]_\infty &= 0 \\ \alpha_\infty^+ &= \frac{1}{2} + \sqrt{1 + 4b} = 4 \\ \alpha_\infty^- &= \frac{1}{2} - \sqrt{1 + 4b} = -3 \end{aligned}$$

The following table summarizes the findings so far for poles and for the order of r at ∞ where r is

$$r = \frac{12}{x^2}$$

pole c location	pole order	$[\sqrt{r}]_c$	α_c^+	α_c^-
0	2	0	4	-3

Order of r at ∞	$[\sqrt{r}]_\infty$	α_∞^+	α_∞^-
2	0	4	-3

Now that the all $[\sqrt{r}]_c$ and its associated α_c^\pm have been determined for all the poles in the set Γ and $[\sqrt{r}]_\infty$ and its associated α_∞^\pm have also been found, the next step is to determine possible non negative integer d from these using

$$d = \alpha_\infty^{s(\infty)} - \sum_{c \in \Gamma} \alpha_c^{s(c)}$$

Where $s(c)$ is either $+$ or $-$ and $s(\infty)$ is the sign of α_∞^\pm . This is done by trial over all set of families $s = (s(c))_{c \in \Gamma \cup \infty}$ until such d is found to work in finding candidate ω .

Trying $\alpha_{\infty}^{-} = -3$ then

$$\begin{aligned} d &= \alpha_{\infty}^{-} - (\alpha_{c_1}^{-}) \\ &= -3 - (-3) \\ &= 0 \end{aligned}$$

Since d an integer and $d \geq 0$ then it can be used to find ω using

$$\omega = \sum_{c \in \Gamma} \left(s(c)[\sqrt{r}]_c + \frac{\alpha_c^{s(c)}}{x - c} \right) + s(\infty)[\sqrt{r}]_{\infty}$$

The above gives

$$\begin{aligned} \omega &= \left((-)[\sqrt{r}]_{c_1} + \frac{\alpha_{c_1}^{-}}{x - c_1} \right) + (-)[\sqrt{r}]_{\infty} \\ &= -\frac{3}{x} + (-)(0) \\ &= -\frac{3}{x} \\ &= -\frac{3}{x} \end{aligned}$$

Now that ω is determined, the next step is find a corresponding minimal polynomial $p(x)$ of degree $d = 0$ to solve the ode. The polynomial $p(x)$ needs to satisfy the equation

$$p'' + 2\omega p' + (\omega' + \omega^2 - r)p = 0 \quad (1A)$$

Let

$$p(x) = 1 \quad (2A)$$

Substituting the above in eq. (1A) gives

$$\begin{aligned} (0) + 2\left(-\frac{3}{x}\right)(0) + \left(\left(\frac{3}{x^2}\right) + \left(-\frac{3}{x}\right)^2 - \left(\frac{12}{x^2}\right)\right) &= 0 \\ 0 &= 0 \end{aligned}$$

The equation is satisfied since both sides are zero. Therefore the first solution to the ode $z'' = rz$ is

$$\begin{aligned} z_1(x) &= pe^{\int \omega dx} \\ &= e^{\int -\frac{3}{x} dx} \\ &= \frac{1}{x^3} \end{aligned}$$

The first solution to the original ode in y is found from

$$\begin{aligned}y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\&= z_1 e^{-\int \frac{1}{2} \frac{-2x}{x^2} dx} \\&= z_1 e^{\ln(x)} \\&= z_1(x)\end{aligned}$$

Which simplifies to

$$y_1 = \frac{1}{x^2}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{-2x}{x^2} dx}}{(y_1)^2} dx \\&= y_1 \int \frac{e^{2\ln(x)}}{(y_1)^2} dx \\&= y_1 \left(\frac{x^7}{7} \right)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\&= c_1 \left(\frac{1}{x^2} \right) + c_2 \left(\frac{1}{x^2} \left(\frac{x^7}{7} \right) \right)\end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = \frac{c_1}{x^2} + \frac{c_2 x^5}{7} \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 5$ and $x = 1$ in the above gives

$$5 = c_1 + \frac{c_2}{7} \quad (1A)$$

Taking derivative of the solution gives

$$y' = -\frac{2c_1}{x^3} + \frac{5c_2x^4}{7}$$

substituting $y' = 4$ and $x = 1$ in the above gives

$$4 = -2c_1 + \frac{5c_2}{7} \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 3$$

$$c_2 = 14$$

Substituting these values back in above solution results in

$$y = \frac{2x^7 + 3}{x^2}$$

Summary

The solution(s) found are the following

$$y = \frac{2x^7 + 3}{x^2} \quad (1)$$

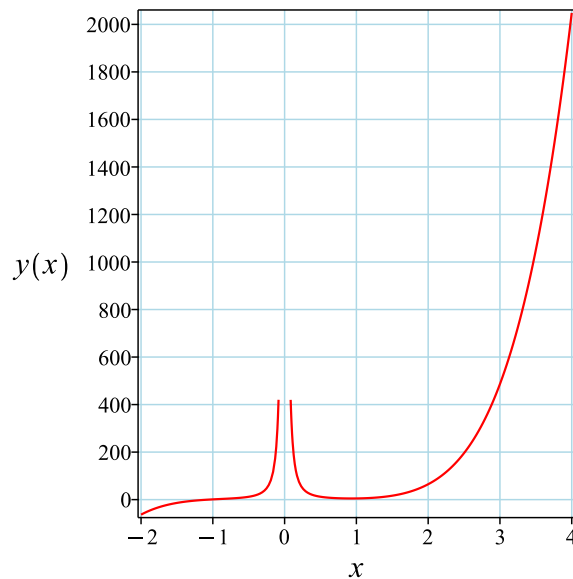


Figure 523: Solution plot

Verification of solutions

$$y = \frac{2x^7 + 3}{x^2}$$

Verified OK.

13.20.6 Maple step by step solution

Let's solve

$$\left[y''x^2 - 2y'x - 10y = 0, y(1) = 5, y'|_{\{x=1\}} = 4 \right]$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = \frac{2y'}{x} + \frac{10y}{x^2}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' - \frac{2y'}{x} - \frac{10y}{x^2} = 0$$

- Multiply by denominators of the ODE

$$y''x^2 - 2y'x - 10y = 0$$

- Make a change of variables

$$t = \ln(x)$$

- Substitute the change of variables back into the ODE

- Calculate the 1st derivative of y with respect to x , using the chain rule

$$y' = \left(\frac{d}{dt}y(t) \right) t'(x)$$

- Compute derivative

$$y' = \frac{\frac{d}{dt}y(t)}{x}$$

- Calculate the 2nd derivative of y with respect to x , using the chain rule

$$y'' = \left(\frac{d^2}{dt^2}y(t) \right) t'(x)^2 + t''(x) \left(\frac{d}{dt}y(t) \right)$$

- Compute derivative

$$y'' = \frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2}$$

Substitute the change of variables back into the ODE

$$\left(\frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2} \right) x^2 - 2 \frac{d}{dt}y(t) - 10y(t) = 0$$

- Simplify

$$\frac{d^2}{dt^2}y(t) - 3 \frac{d}{dt}y(t) - 10y(t) = 0$$

- Characteristic polynomial of ODE

$$r^2 - 3r - 10 = 0$$

- Factor the characteristic polynomial

$$(r + 2)(r - 5) = 0$$

- Roots of the characteristic polynomial

$$r = (-2, 5)$$

- 1st solution of the ODE

$$y_1(t) = e^{-2t}$$

- 2nd solution of the ODE

$$y_2(t) = e^{5t}$$

- General solution of the ODE

$$y(t) = c_1 y_1(t) + c_2 y_2(t)$$

- Substitute in solutions

$$y(t) = c_1 e^{-2t} + c_2 e^{5t}$$

- Change variables back using $t = \ln(x)$

$$y = \frac{c_1}{x^2} + c_2 x^5$$

- Simplify

$$y = \frac{c_1}{x^2} + c_2 x^5$$

- Check validity of solution $y = \frac{c_1}{x^2} + c_2 x^5$

- Use initial condition $y(1) = 5$

$$5 = c_1 + c_2$$

- Compute derivative of the solution

$$y' = -\frac{2c_1}{x^3} + 5c_2 x^4$$

- Use the initial condition $y' \Big|_{\{x=1\}} = 4$

$$4 = -2c_1 + 5c_2$$

- Solve for c_1 and c_2
- Substitute constant values into general solution and simplify

$$y = \frac{3}{x^2} + 2x^5$$

- Solution to the IVP

$$y = \frac{3}{x^2} + 2x^5$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
<- LODE of Euler type successful`

```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 15

```
dsolve([x^2*diff(y(x),x$2)-2*x*diff(y(x),x)-10*y(x)=0,y(1) = 5, D(y)(1) = 4],y(x), singsol=a
```

$$y(x) = 2x^5 + \frac{3}{x^2}$$

✓ Solution by Mathematica

Time used: 0.02 (sec). Leaf size: 16

```
DSolve[{x^2*y'[x]-2*x*y'[x]-10*y[x]==0,{y[1]==5,y'[1]==4}},y[x],x,IncludeSingularSolutions
```

$$y(x) \rightarrow \frac{2x^7 + 3}{x^2}$$

13.21 problem 21

13.21.1 Existence and uniqueness analysis	3610
13.21.2 Solving as second order euler ode	3610
13.21.3 Solving as linear second order ode solved by an integrating factor ode	3612
13.21.4 Solving as second order change of variable on x method 2 ode .	3615
13.21.5 Solving as second order change of variable on x method 1 ode .	3619
13.21.6 Solving as second order change of variable on y method 1 ode .	3622
13.21.7 Solving as second order change of variable on y method 2 ode .	3625
13.21.8 Solving using Kovacic algorithm	3628
13.21.9 Maple step by step solution	3632

Internal problem ID [11875]

Internal file name [OUTPUT/11884_Saturday_April_13_2024_01_13_56_AM_26227055/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.5. The Cauchy-Euler Equation. Exercises page 169

Problem number: 21.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_euler_ode", "second_order_change_of_variable_on_x_method_1", "second_order_change_of_variable_on_x_method_2", "second_order_change_of_variable_on_y_method_1", "second_order_change_of_variable_on_y_method_2", "linear_second_order_ode_solved_by_an_integrating_factor"

Maple gives the following as the ode type

```
[[_Emden, _Fowler], [_2nd_order, _linear, `_with_symmetry_[0,F(x)]`]]
```

$$x^2y'' - 4y'x + 6y = 0$$

With initial conditions

$$[y(2) = 0, y'(2) = 4]$$

13.21.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$\begin{aligned}p(x) &= -\frac{4}{x} \\q(x) &= \frac{6}{x^2} \\F &= 0\end{aligned}$$

Hence the ode is

$$y'' - \frac{4y'}{x} + \frac{6y}{x^2} = 0$$

The domain of $p(x) = -\frac{4}{x}$ is

$$\{x < 0 \vee 0 < x\}$$

And the point $x_0 = 2$ is inside this domain. The domain of $q(x) = \frac{6}{x^2}$ is

$$\{x < 0 \vee 0 < x\}$$

And the point $x_0 = 2$ is also inside this domain. Hence solution exists and is unique.

13.21.2 Solving as second order euler ode

This is Euler second order ODE. Let the solution be $y = x^r$, then $y' = rx^{r-1}$ and $y'' = r(r-1)x^{r-2}$. Substituting these back into the given ODE gives

$$x^2(r(r-1))x^{r-2} - 4rx^{r-1} + 6x^r = 0$$

Simplifying gives

$$r(r-1)x^r - 4rx^r + 6x^r = 0$$

Since $x^r \neq 0$ then dividing throughout by x^r gives

$$r(r-1) - 4r + 6 = 0$$

Or

$$r^2 - 5r + 6 = 0 \tag{1}$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = 2$$

$$r_2 = 3$$

Since the roots are real and distinct, then the general solution is

$$y = c_1 y_1 + c_2 y_2$$

Where $y_1 = x^{r_1}$ and $y_2 = x^{r_2}$. Hence

$$y = c_2 x^3 + c_1 x^2$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_2 x^3 + c_1 x^2 \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 0$ and $x = 2$ in the above gives

$$0 = 8c_2 + 4c_1 \tag{1A}$$

Taking derivative of the solution gives

$$y' = 3c_2 x^2 + 2c_1 x$$

substituting $y' = 4$ and $x = 2$ in the above gives

$$4 = 12c_2 + 4c_1 \tag{2A}$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = -2$$

$$c_2 = 1$$

Substituting these values back in above solution results in

$$y = x^3 - 2x^2$$

Which simplifies to

$$y = (x - 2) x^2$$

Summary

The solution(s) found are the following

$$y = (x - 2) x^2 \quad (1)$$

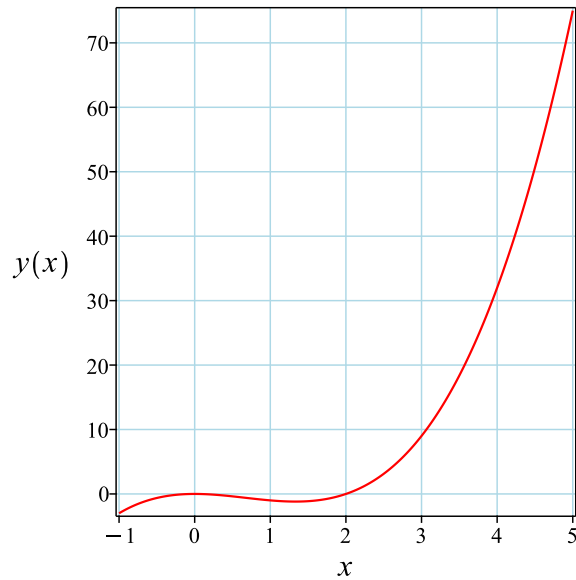


Figure 524: Solution plot

Verification of solutions

$$y = (x - 2) x^2$$

Verified OK.

13.21.3 Solving as linear second order ode solved by an integrating factor ode

The ode satisfies this form

$$y'' + p(x) y' + \frac{(p(x)^2 + p'(x)) y}{2} = f(x)$$

Where $p(x) = -\frac{4}{x}$. Therefore, there is an integrating factor given by

$$\begin{aligned} M(x) &= e^{\frac{1}{2} \int p dx} \\ &= e^{\int -\frac{4}{x} dx} \\ &= \frac{1}{x^2} \end{aligned}$$

Multiplying both sides of the ODE by the integrating factor $M(x)$ makes the left side of the ODE a complete differential

$$(M(x)y)'' = 0$$
$$\left(\frac{y}{x^2}\right)'' = 0$$

Integrating once gives

$$\left(\frac{y}{x^2}\right)' = c_1$$

Integrating again gives

$$\left(\frac{y}{x^2}\right) = c_1x + c_2$$

Hence the solution is

$$y = \frac{c_1x + c_2}{\frac{1}{x^2}}$$

Or

$$y = c_1x^3 + c_2x^2$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1x^3 + c_2x^2 \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 0$ and $x = 2$ in the above gives

$$0 = 8c_1 + 4c_2 \tag{1A}$$

Taking derivative of the solution gives

$$y' = 3c_1x^2 + 2c_2x$$

substituting $y' = 4$ and $x = 2$ in the above gives

$$4 = 12c_1 + 4c_2 \tag{2A}$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 1$$
$$c_2 = -2$$

Substituting these values back in above solution results in

$$y = x^3 - 2x^2$$

Which simplifies to

$$y = (x - 2) x^2$$

Summary

The solution(s) found are the following

$$y = (x - 2) x^2 \tag{1}$$

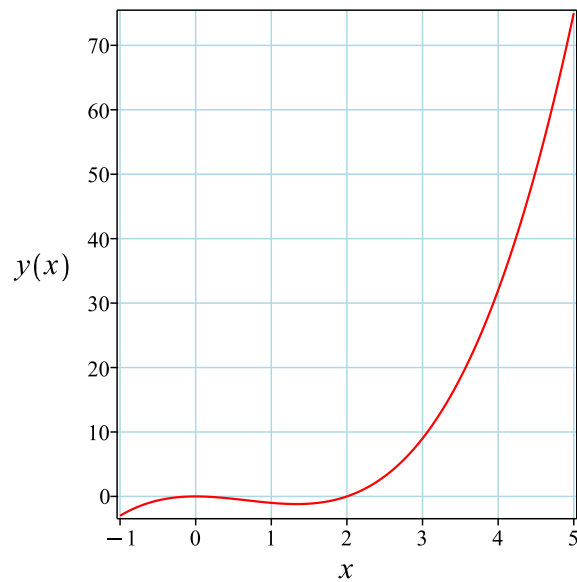


Figure 525: Solution plot

Verification of solutions

$$y = (x - 2) x^2$$

Verified OK.

13.21.4 Solving as second order change of variable on x method 2 ode

In normal form the ode

$$x^2 y'' - 4y'x + 6y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = -\frac{4}{x}$$
$$q(x) = \frac{6}{x^2}$$

Applying change of variables $\tau = g(x)$ to (2) gives

$$\frac{d^2}{d\tau^2}y(\tau) + p_1\left(\frac{d}{d\tau}y(\tau)\right) + q_1y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $p_1 = 0$. Eq (4) simplifies to

$$\tau''(x) + p(x)\tau'(x) = 0$$

This ode is solved resulting in

$$\begin{aligned} \tau &= \int e^{-(\int p(x)dx)} dx \\ &= \int e^{-(\int -\frac{4}{x}dx)} dx \\ &= \int e^{4\ln(x)} dx \\ &= \int x^4 dx \\ &= \frac{x^5}{5} \end{aligned} \quad (6)$$

Using (6) to evaluate q_1 from (5) gives

$$\begin{aligned} q_1(\tau) &= \frac{q(x)}{\tau'(x)^2} \\ &= \frac{\frac{6}{x^2}}{x^8} \\ &= \frac{6}{x^{10}} \end{aligned} \tag{7}$$

Substituting the above in (3) and noting that now $p_1 = 0$ results in

$$\begin{aligned} \frac{d^2}{d\tau^2}y(\tau) + q_1y(\tau) &= 0 \\ \frac{d^2}{d\tau^2}y(\tau) + \frac{6y(\tau)}{x^{10}} &= 0 \end{aligned}$$

But in terms of τ

$$\frac{6}{x^{10}} = \frac{6}{25\tau^2}$$

Hence the above ode becomes

$$\frac{d^2}{d\tau^2}y(\tau) + \frac{6y(\tau)}{25\tau^2} = 0$$

The above ode is now solved for $y(\tau)$. The ode can be written as

$$25 \left(\frac{d^2}{d\tau^2}y(\tau) \right) \tau^2 + 6y(\tau) = 0$$

Which shows it is a Euler ODE. This is Euler second order ODE. Let the solution be $y(\tau) = \tau^r$, then $y' = r\tau^{r-1}$ and $y'' = r(r-1)\tau^{r-2}$. Substituting these back into the given ODE gives

$$25\tau^2(r(r-1))\tau^{r-2} + 0r\tau^{r-1} + 6\tau^r = 0$$

Simplifying gives

$$25r(r-1)\tau^r + 0\tau^r + 6\tau^r = 0$$

Since $\tau^r \neq 0$ then dividing throughout by τ^r gives

$$25r(r-1) + 0 + 6 = 0$$

Or

$$25r^2 - 25r + 6 = 0 \tag{1}$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = \frac{2}{5}$$

$$r_2 = \frac{3}{5}$$

Since the roots are real and distinct, then the general solution is

$$y(\tau) = c_1 y_1 + c_2 y_2$$

Where $y_1 = \tau^{r_1}$ and $y_2 = \tau^{r_2}$. Hence

$$y(\tau) = c_1 \tau^{\frac{2}{5}} + c_2 \tau^{\frac{3}{5}}$$

The above solution is now transformed back to y using (6) which results in

$$y = \frac{c_1 5^{\frac{3}{5}} (x^5)^{\frac{2}{5}}}{5} + \frac{c_2 5^{\frac{2}{5}} (x^5)^{\frac{3}{5}}}{5}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = \frac{c_1 5^{\frac{3}{5}} (x^5)^{\frac{2}{5}}}{5} + \frac{c_2 5^{\frac{2}{5}} (x^5)^{\frac{3}{5}}}{5} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 0$ and $x = 2$ in the above gives

$$0 = \frac{4 \cdot 5^{\frac{2}{5}} \left(5^{\frac{1}{5}} c_1 + 2c_2 \right)}{5} \quad (1A)$$

Taking derivative of the solution gives

$$y' = \frac{2c_1 5^{\frac{3}{5}} x^4}{5 (x^5)^{\frac{3}{5}}} + \frac{3c_2 5^{\frac{2}{5}} x^4}{5 (x^5)^{\frac{2}{5}}}$$

substituting $y' = 4$ and $x = 2$ in the above gives

$$4 = \frac{4 \left(5^{\frac{1}{5}} c_1 + 3c_2 \right) 5^{\frac{2}{5}}}{5} \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = -2 \cdot 5^{\frac{2}{5}}$$
$$c_2 = 5^{\frac{3}{5}}$$

Substituting these values back in above solution results in

$$y = (x^5)^{\frac{3}{5}} - 2(x^5)^{\frac{2}{5}}$$

Summary

The solution(s) found are the following

$$y = (x^5)^{\frac{3}{5}} - 2(x^5)^{\frac{2}{5}} \quad (1)$$

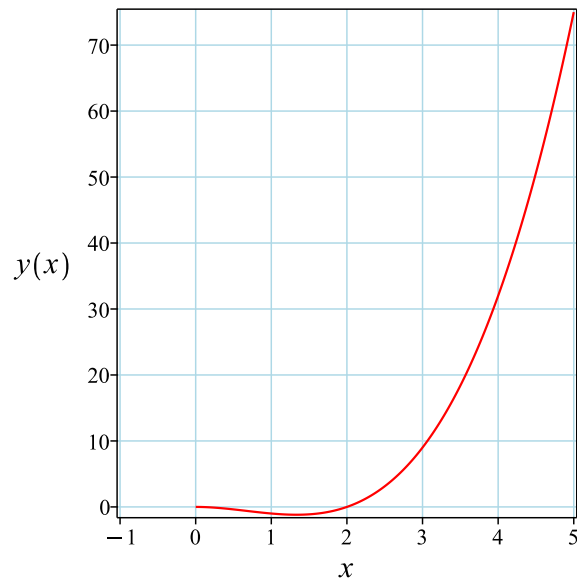


Figure 526: Solution plot

Verification of solutions

$$y = (x^5)^{\frac{3}{5}} - 2(x^5)^{\frac{2}{5}}$$

Verified OK.

13.21.5 Solving as second order change of variable on x method 1 ode

In normal form the ode

$$x^2 y'' - 4y'x + 6y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = -\frac{4}{x}$$

$$q(x) = \frac{6}{x^2}$$

Applying change of variables $\tau = g(x)$ to (2) results

$$\frac{d^2}{d\tau^2}y(\tau) + p_1\left(\frac{d}{d\tau}y(\tau)\right) + q_1y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $q_1 = c^2$ where c is some constant. Therefore from (5)

$$\begin{aligned} \tau' &= \frac{1}{c}\sqrt{q} \\ &= \frac{\sqrt{6}\sqrt{\frac{1}{x^2}}}{c} \\ \tau'' &= -\frac{\sqrt{6}}{c\sqrt{\frac{1}{x^2}}x^3} \end{aligned} \quad (6)$$

Substituting the above into (4) results in

$$\begin{aligned} p_1(\tau) &= \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \\ &= \frac{-\frac{\sqrt{6}}{c\sqrt{\frac{1}{x^2}}x^3} - \frac{4}{x}\frac{\sqrt{6}\sqrt{\frac{1}{x^2}}}{c}}{\left(\frac{\sqrt{6}\sqrt{\frac{1}{x^2}}}{c}\right)^2} \\ &= -\frac{5c\sqrt{6}}{6} \end{aligned}$$

Therefore ode (3) now becomes

$$\begin{aligned} y(\tau)'' + p_1 y(\tau)' + q_1 y(\tau) &= 0 \\ \frac{d^2}{d\tau^2} y(\tau) - \frac{5c\sqrt{6}}{6} \left(\frac{d}{d\tau} y(\tau) \right) + c^2 y(\tau) &= 0 \end{aligned} \quad (7)$$

The above ode is now solved for $y(\tau)$. Since the ode is now constant coefficients, it can be easily solved to give

$$y(\tau) = e^{\frac{5\sqrt{6}c\tau}{12}} \left(c_1 \cosh \left(\frac{\sqrt{6}c\tau}{12} \right) + ic_2 \sinh \left(\frac{\sqrt{6}c\tau}{12} \right) \right)$$

Now from (6)

$$\begin{aligned} \tau &= \int \frac{1}{c} \sqrt{q} dx \\ &= \frac{\int \sqrt{6} \sqrt{\frac{1}{x^2}} dx}{c} \\ &= \frac{\sqrt{6} \sqrt{\frac{1}{x^2}} x \ln(x)}{c} \end{aligned}$$

Substituting the above into the solution obtained gives

$$y = x^{\frac{5}{2}} \left(c_1 \cosh \left(\frac{\ln(x)}{2} \right) + ic_2 \sinh \left(\frac{\ln(x)}{2} \right) \right)$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = x^{\frac{5}{2}} \left(c_1 \cosh \left(\frac{\ln(x)}{2} \right) + ic_2 \sinh \left(\frac{\ln(x)}{2} \right) \right) \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 0$ and $x = 2$ in the above gives

$$0 = 2ic_2 + 6c_1 \quad (1A)$$

Taking derivative of the solution gives

$$y' = \frac{5x^{\frac{3}{2}} \left(c_1 \cosh \left(\frac{\ln(x)}{2} \right) + ic_2 \sinh \left(\frac{\ln(x)}{2} \right) \right)}{2} + x^{\frac{5}{2}} \left(\frac{c_1 \sinh \left(\frac{\ln(x)}{2} \right)}{2x} + \frac{ic_2 \cosh \left(\frac{\ln(x)}{2} \right)}{2x} \right)$$

substituting $y' = 4$ and $x = 2$ in the above gives

$$4 = 4ic_2 + 8c_1 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = -1$$

$$c_2 = -3i$$

Substituting these values back in above solution results in

$$y = 3x^{\frac{5}{2}} \sinh\left(\frac{\ln(x)}{2}\right) - x^{\frac{5}{2}} \cosh\left(\frac{\ln(x)}{2}\right)$$

Which simplifies to

$$y = -\left(\cosh\left(\frac{\ln(x)}{2}\right) - 3\sinh\left(\frac{\ln(x)}{2}\right)\right) x^{\frac{5}{2}}$$

Summary

The solution(s) found are the following

$$y = -\left(\cosh\left(\frac{\ln(x)}{2}\right) - 3\sinh\left(\frac{\ln(x)}{2}\right)\right) x^{\frac{5}{2}} \quad (1)$$

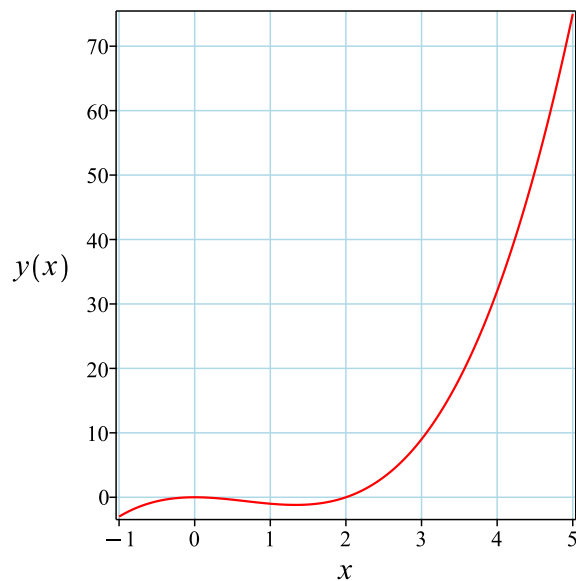


Figure 527: Solution plot

Verification of solutions

$$y = -\left(\cosh\left(\frac{\ln(x)}{2}\right) - 3\sinh\left(\frac{\ln(x)}{2}\right)\right) x^{\frac{5}{2}}$$

Verified OK.

13.21.6 Solving as second order change of variable on y method 1 ode

In normal form the given ode is written as

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = -\frac{4}{x}$$
$$q(x) = \frac{6}{x^2}$$

Calculating the Liouville ode invariant Q given by

$$\begin{aligned} Q &= q - \frac{p'}{2} - \frac{p^2}{4} \\ &= \frac{6}{x^2} - \frac{\left(-\frac{4}{x}\right)'}{2} - \frac{\left(-\frac{4}{x}\right)^2}{4} \\ &= \frac{6}{x^2} - \frac{\left(\frac{4}{x^2}\right)}{2} - \frac{\left(\frac{16}{x^2}\right)}{4} \\ &= \frac{6}{x^2} - \left(\frac{2}{x^2}\right) - \frac{4}{x^2} \\ &= 0 \end{aligned}$$

Since the Liouville ode invariant does not depend on the independent variable x then the transformation

$$y = v(x)z(x) \quad (3)$$

is used to change the original ode to a constant coefficients ode in v . In (3) the term $z(x)$ is given by

$$\begin{aligned} z(x) &= e^{-\left(\int \frac{p(x)}{2} dx\right)} \\ &= e^{-\int \frac{-4}{2} dx} \\ &= x^2 \end{aligned} \quad (5)$$

Hence (3) becomes

$$y = v(x) x^2 \quad (4)$$

Applying this change of variable to the original ode results in

$$x^4 v''(x) = 0$$

Which is now solved for $v(x)$ Integrating twice gives the solution

$$v(x) = c_1 x + c_2$$

Now that $v(x)$ is known, then

$$\begin{aligned} y &= v(x) z(x) \\ &= (c_1 x + c_2) (z(x)) \end{aligned} \quad (7)$$

But from (5)

$$z(x) = x^2$$

Hence (7) becomes

$$y = (c_1 x + c_2) x^2$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = (c_1 x + c_2) x^2 \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 0$ and $x = 2$ in the above gives

$$0 = 8c_1 + 4c_2 \quad (1A)$$

Taking derivative of the solution gives

$$y' = c_1 x^2 + 2(c_1 x + c_2) x$$

substituting $y' = 4$ and $x = 2$ in the above gives

$$4 = 12c_1 + 4c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$\begin{aligned}c_1 &= 1 \\c_2 &= -2\end{aligned}$$

Substituting these values back in above solution results in

$$y = (x - 2) x^2$$

Summary

The solution(s) found are the following

$$y = (x - 2) x^2 \tag{1}$$

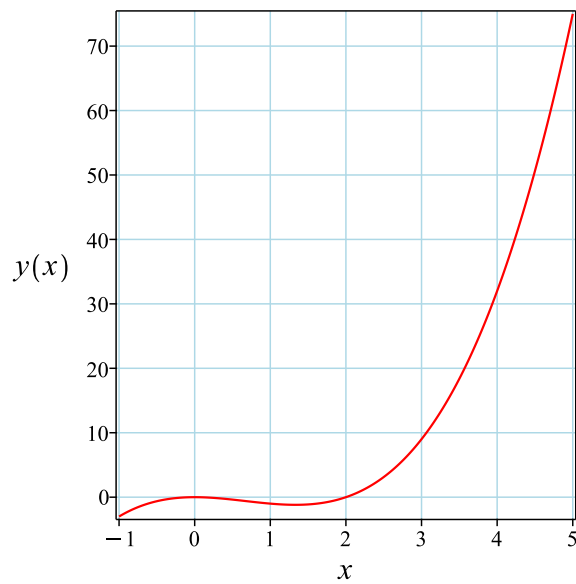


Figure 528: Solution plot

Verification of solutions

$$y = (x - 2) x^2$$

Verified OK.

13.21.7 Solving as second order change of variable on y method 2 ode

In normal form the ode

$$x^2 y'' - 4y'x + 6y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = -\frac{4}{x}$$
$$q(x) = \frac{6}{x^2}$$

Applying change of variables on the dependent variable $y = v(x)x^n$ to (2) gives the following ode where the dependent variables is $v(x)$ and not y .

$$v''(x) + \left(\frac{2n}{x} + p\right)v'(x) + \left(\frac{n(n-1)}{x^2} + \frac{np}{x} + q\right)v(x) = 0 \quad (3)$$

Let the coefficient of $v(x)$ above be zero. Hence

$$\frac{n(n-1)}{x^2} + \frac{np}{x} + q = 0 \quad (4)$$

Substituting the earlier values found for $p(x)$ and $q(x)$ into (4) gives

$$\frac{n(n-1)}{x^2} - \frac{4n}{x^2} + \frac{6}{x^2} = 0 \quad (5)$$

Solving (5) for n gives

$$n = 3 \quad (6)$$

Substituting this value in (3) gives

$$v''(x) + \frac{2v'(x)}{x} = 0$$
$$v''(x) + \frac{2v'(x)}{x} = 0 \quad (7)$$

Using the substitution

$$u(x) = v'(x)$$

Then (7) becomes

$$u'(x) + \frac{2u(x)}{x} = 0 \quad (8)$$

The above is now solved for $u(x)$. In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= -\frac{2u}{x} \end{aligned}$$

Where $f(x) = -\frac{2}{x}$ and $g(u) = u$. Integrating both sides gives

$$\begin{aligned} \frac{1}{u} du &= -\frac{2}{x} dx \\ \int \frac{1}{u} du &= \int -\frac{2}{x} dx \\ \ln(u) &= -2 \ln(x) + c_1 \\ u &= e^{-2 \ln(x) + c_1} \\ &= \frac{c_1}{x^2} \end{aligned}$$

Now that $u(x)$ is known, then

$$\begin{aligned} v'(x) &= u(x) \\ v(x) &= \int u(x) dx + c_2 \\ &= -\frac{c_1}{x} + c_2 \end{aligned}$$

Hence

$$\begin{aligned} y &= v(x) x^n \\ &= \left(-\frac{c_1}{x} + c_2\right) x^3 \\ &= (c_2 x - c_1) x^2 \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = \left(-\frac{c_1}{x} + c_2\right) x^3 \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 0$ and $x = 2$ in the above gives

$$0 = -4c_1 + 8c_2 \quad (1A)$$

Taking derivative of the solution gives

$$y' = c_1x + 3\left(-\frac{c_1}{x} + c_2\right)x^2$$

substituting $y' = 4$ and $x = 2$ in the above gives

$$4 = -4c_1 + 12c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 2$$

$$c_2 = 1$$

Substituting these values back in above solution results in

$$y = (x - 2)x^2$$

Summary

The solution(s) found are the following

$$y = (x - 2)x^2 \quad (1)$$

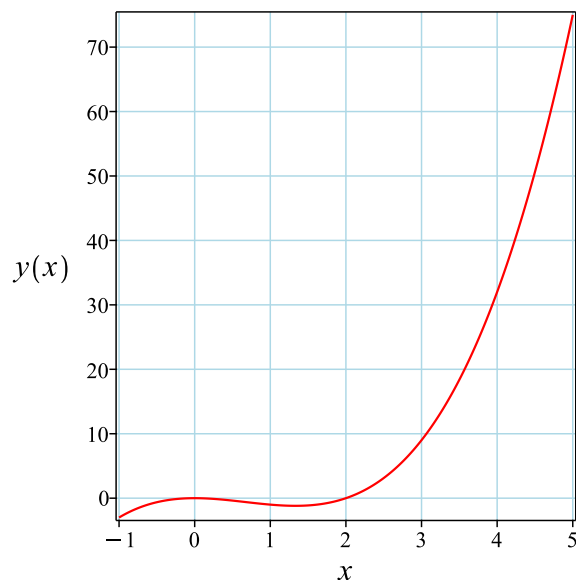


Figure 529: Solution plot

Verification of solutions

$$y = (x - 2)x^2$$

Verified OK.

13.21.8 Solving using Kovacic algorithm

Writing the ode as

$$x^2y'' - 4y'x + 6y = 0 \tag{1}$$

$$Ay'' + By' + Cy = 0 \tag{2}$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= x^2 \\ B &= -4x \\ C &= 6 \end{aligned} \tag{3}$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{0}{1} \tag{6}$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 0 \\ t &= 1 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = 0 \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 499: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 0 - -\infty \\ &= \infty \end{aligned}$$

There are no poles in r . Therefore the set of poles Γ is empty. Since there is no odd order pole larger than 2 and the order at ∞ is *infinity* then the necessary conditions for case one are met. Therefore

$$L = [1]$$

Since $r = 0$ is not a function of x , then there is no need run Kovacic algorithm to obtain a solution for transformed ode $z'' = rz$ as one solution is

$$z_1(x) = 1$$

Using the above, the solution for the original ode can now be found. The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-4x}{x^2} dx} \\ &= z_1 e^{2 \ln(x)} \\ &= z_1 (x^2) \end{aligned}$$

Which simplifies to

$$y_1 = x^2$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned} y_2 &= y_1 \int \frac{e^{\int -\frac{-4x}{x^2} dx}}{(y_1)^2} dx \\ &= y_1 \int \frac{e^{4 \ln(x)}}{(y_1)^2} dx \\ &= y_1(x) \end{aligned}$$

Therefore the solution is

$$\begin{aligned} y &= c_1 y_1 + c_2 y_2 \\ &= c_1 (x^2) + c_2 (x^2(x)) \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_2 x^3 + c_1 x^2 \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 0$ and $x = 2$ in the above gives

$$0 = 8c_2 + 4c_1 \tag{1A}$$

Taking derivative of the solution gives

$$y' = 3c_2x^2 + 2c_1x$$

substituting $y' = 4$ and $x = 2$ in the above gives

$$4 = 12c_2 + 4c_1 \tag{2A}$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = -2$$

$$c_2 = 1$$

Substituting these values back in above solution results in

$$y = x^3 - 2x^2$$

Which simplifies to

$$y = (x - 2) x^2$$

Summary

The solution(s) found are the following

$$y = (x - 2) x^2 \tag{1}$$

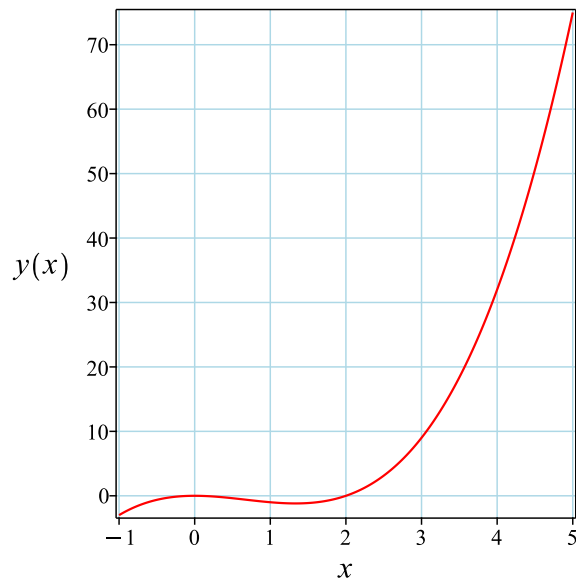


Figure 530: Solution plot

Verification of solutions

$$y = (x - 2) x^2$$

Verified OK.

13.21.9 Maple step by step solution

Let's solve

$$\left[y''x^2 - 4y'x + 6y = 0, y(2) = 0, y'|_{\{x=2\}} = 4 \right]$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = \frac{4y'}{x} - \frac{6y}{x^2}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' - \frac{4y'}{x} + \frac{6y}{x^2} = 0$$

- Multiply by denominators of the ODE

$$y''x^2 - 4y'x + 6y = 0$$

- Make a change of variables

$$t = \ln(x)$$

- Substitute the change of variables back into the ODE

- Calculate the 1st derivative of y with respect to x , using the chain rule

$$y' = \left(\frac{d}{dt} y(t) \right) t'(x)$$

- Compute derivative

$$y' = \frac{\frac{d}{dt} y(t)}{x}$$

- Calculate the 2nd derivative of y with respect to x , using the chain rule

$$y'' = \left(\frac{d^2}{dt^2} y(t) \right) t'(x)^2 + t''(x) \left(\frac{d}{dt} y(t) \right)$$

- Compute derivative

$$y'' = \frac{\frac{d^2}{dt^2} y(t)}{x^2} - \frac{\frac{d}{dt} y(t)}{x^2}$$

Substitute the change of variables back into the ODE

$$\left(\frac{\frac{d^2}{dt^2} y(t)}{x^2} - \frac{\frac{d}{dt} y(t)}{x^2} \right) x^2 - 4 \frac{d}{dt} y(t) + 6y(t) = 0$$

- Simplify

$$\frac{d^2}{dt^2} y(t) - 5 \frac{d}{dt} y(t) + 6y(t) = 0$$

- Characteristic polynomial of ODE

$$r^2 - 5r + 6 = 0$$

- Factor the characteristic polynomial

$$(r - 2)(r - 3) = 0$$

- Roots of the characteristic polynomial

$$r = (2, 3)$$

- 1st solution of the ODE

$$y_1(t) = e^{2t}$$

- 2nd solution of the ODE

$$y_2(t) = e^{3t}$$

- General solution of the ODE

$$y(t) = c_1 y_1(t) + c_2 y_2(t)$$

- Substitute in solutions

$$y(t) = c_1 e^{2t} + c_2 e^{3t}$$

- Change variables back using $t = \ln(x)$

$$y = c_2 x^3 + c_1 x^2$$

- Simplify

$$y = x^2(c_2 x + c_1)$$

- Check validity of solution $y = x^2(c_2 x + c_1)$

- Use initial condition $y(2) = 0$

$$0 = 8c_2 + 4c_1$$

- Compute derivative of the solution

$$y' = 2x(c_2 x + c_1) + c_2 x^2$$

- Use the initial condition $y' \Big|_{\{x=2\}} = 4$

$$4 = 12c_2 + 4c_1$$

- Solve for c_1 and c_2

$$\{c_1 = -2, c_2 = 1\}$$

- Substitute constant values into general solution and simplify

$$y = (x - 2)x^2$$

- Solution to the IVP

$$y = (x - 2)x^2$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
checking if the LODE is of Euler type  
<- LODE of Euler type successful`
```

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 11

```
dsolve([x^2*diff(y(x),x$2)-4*x*diff(y(x),x)+6*y(x)=0,y(2) = 0, D(y)(2) = 4],y(x), singsol=all)
```

$$y(x) = x^2(x - 2)$$

✓ Solution by Mathematica

Time used: 0.011 (sec). Leaf size: 12

```
DSolve[{x^2*y''[x]-4*x*y'[x]+6*y[x]==0,{y[2]==0,y'[2]==4}},y[x],x,IncludeSingularSolutions->True]
```

$$y(x) \rightarrow (x - 2)x^2$$

13.22 problem 22

13.22.1 Existence and uniqueness analysis	3636
13.22.2 Solving as second order euler ode ode	3636
13.22.3 Solving as second order change of variable on x method 2 ode .	3638
13.22.4 Solving as second order change of variable on x method 1 ode .	3642
13.22.5 Solving as second order change of variable on y method 2 ode .	3645
13.22.6 Solving as second order integrable as is ode	3648
13.22.7 Solving as type second_order_integrable_as_is (not using ABC version)	3650
13.22.8 Solving using Kovacic algorithm	3653
13.22.9 Solving as exact linear second order ode ode	3659
13.22.10 Maple step by step solution	3662

Internal problem ID [11876]

Internal file name [OUTPUT/11885_Saturday_April_13_2024_01_13_58_AM_6549318/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.5. The Cauchy-Euler Equation. Exercises page 169

Problem number: 22.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_euler_ode", "exact linear second order ode", "second_order_integrable_as_is", "second_order_change_of_variable_on_x_method_1", "second_order_change_of_variable_on_x_method_2", "second_order_change_of_variable_on_y_method_2"

Maple gives the following as the ode type

```
[[_2nd_order, _exact, _linear, _homogeneous]]
```

$$x^2y'' + 5y'x + 3y = 0$$

With initial conditions

$$[y(1) = 1, y'(1) = -5]$$

13.22.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$\begin{aligned}p(x) &= \frac{5}{x} \\q(x) &= \frac{3}{x^2} \\F &= 0\end{aligned}$$

Hence the ode is

$$y'' + \frac{5y'}{x} + \frac{3y}{x^2} = 0$$

The domain of $p(x) = \frac{5}{x}$ is

$$\{x < 0 \vee 0 < x\}$$

And the point $x_0 = 1$ is inside this domain. The domain of $q(x) = \frac{3}{x^2}$ is

$$\{x < 0 \vee 0 < x\}$$

And the point $x_0 = 1$ is also inside this domain. Hence solution exists and is unique.

13.22.2 Solving as second order euler ode

This is Euler second order ODE. Let the solution be $y = x^r$, then $y' = rx^{r-1}$ and $y'' = r(r-1)x^{r-2}$. Substituting these back into the given ODE gives

$$x^2(r(r-1))x^{r-2} + 5rx^{r-1} + 3x^r = 0$$

Simplifying gives

$$r(r-1)x^r + 5rx^r + 3x^r = 0$$

Since $x^r \neq 0$ then dividing throughout by x^r gives

$$r(r-1) + 5r + 3 = 0$$

Or

$$r^2 + 4r + 3 = 0 \tag{1}$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = -3$$

$$r_2 = -1$$

Since the roots are real and distinct, then the general solution is

$$y = c_1 y_1 + c_2 y_2$$

Where $y_1 = x^{r_1}$ and $y_2 = x^{r_2}$. Hence

$$y = \frac{c_1}{x^3} + \frac{c_2}{x}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = \frac{c_1}{x^3} + \frac{c_2}{x} \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 1$ and $x = 1$ in the above gives

$$1 = c_1 + c_2 \tag{1A}$$

Taking derivative of the solution gives

$$y' = -\frac{3c_1}{x^4} - \frac{c_2}{x^2}$$

substituting $y' = -5$ and $x = 1$ in the above gives

$$-5 = -3c_1 - c_2 \tag{2A}$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 2$$

$$c_2 = -1$$

Substituting these values back in above solution results in

$$y = -\frac{x^2 - 2}{x^3}$$

Summary

The solution(s) found are the following

$$y = -\frac{x^2 - 2}{x^3} \quad (1)$$

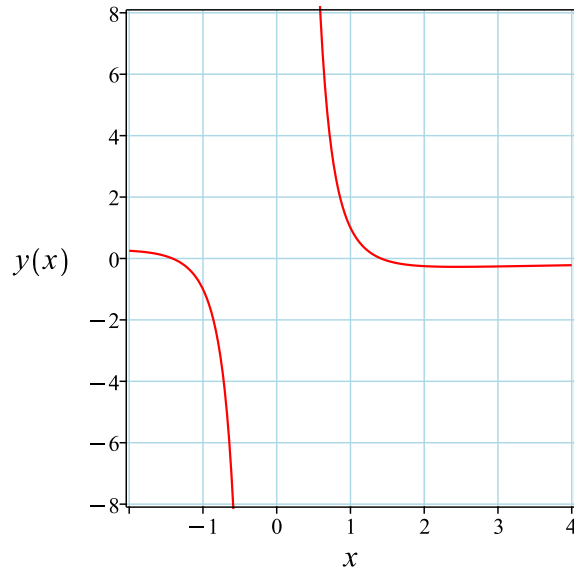


Figure 531: Solution plot

Verification of solutions

$$y = -\frac{x^2 - 2}{x^3}$$

Verified OK.

13.22.3 Solving as second order change of variable on x method 2 ode

In normal form the ode

$$x^2 y'' + 5y'x + 3y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = \frac{5}{x}$$
$$q(x) = \frac{3}{x^2}$$

Applying change of variables $\tau = g(x)$ to (2) gives

$$\frac{d^2}{d\tau^2}y(\tau) + p_1\left(\frac{d}{d\tau}y(\tau)\right) + q_1y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $p_1 = 0$. Eq (4) simplifies to

$$\tau''(x) + p(x)\tau'(x) = 0$$

This ode is solved resulting in

$$\begin{aligned} \tau &= \int e^{-(\int p(x)dx)} dx \\ &= \int e^{-(\int \frac{5}{x} dx)} dx \\ &= \int e^{-5\ln(x)} dx \\ &= \int \frac{1}{x^5} dx \\ &= -\frac{1}{4x^4} \end{aligned} \quad (6)$$

Using (6) to evaluate q_1 from (5) gives

$$\begin{aligned} q_1(\tau) &= \frac{q(x)}{\tau'(x)^2} \\ &= \frac{\frac{3}{x^2}}{\frac{1}{x^{10}}} \\ &= 3x^8 \end{aligned} \quad (7)$$

Substituting the above in (3) and noting that now $p_1 = 0$ results in

$$\begin{aligned} \frac{d^2}{d\tau^2}y(\tau) + q_1y(\tau) &= 0 \\ \frac{d^2}{d\tau^2}y(\tau) + 3x^8y(\tau) &= 0 \end{aligned}$$

But in terms of τ

$$3x^8 = \frac{3}{16\tau^2}$$

Hence the above ode becomes

$$\frac{d^2}{d\tau^2}y(\tau) + \frac{3y(\tau)}{16\tau^2} = 0$$

The above ode is now solved for $y(\tau)$. The ode can be written as

$$16\left(\frac{d^2}{d\tau^2}y(\tau)\right)\tau^2 + 3y(\tau) = 0$$

Which shows it is a Euler ODE. This is Euler second order ODE. Let the solution be $y(\tau) = \tau^r$, then $y' = r\tau^{r-1}$ and $y'' = r(r-1)\tau^{r-2}$. Substituting these back into the given ODE gives

$$16\tau^2(r(r-1))\tau^{r-2} + 0r\tau^{r-1} + 3\tau^r = 0$$

Simplifying gives

$$16r(r-1)\tau^r + 0\tau^r + 3\tau^r = 0$$

Since $\tau^r \neq 0$ then dividing throughout by τ^r gives

$$16r(r-1) + 0 + 3 = 0$$

Or

$$16r^2 - 16r + 3 = 0 \tag{1}$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = \frac{1}{4}$$
$$r_2 = \frac{3}{4}$$

Since the roots are real and distinct, then the general solution is

$$y(\tau) = c_1y_1 + c_2y_2$$

Where $y_1 = \tau^{r_1}$ and $y_2 = \tau^{r_2}$. Hence

$$y(\tau) = c_1\tau^{\frac{1}{4}} + c_2\tau^{\frac{3}{4}}$$

The above solution is now transformed back to y using (6) which results in

$$y = \frac{\sqrt{2}\left(-\frac{1}{x^4}\right)^{\frac{1}{4}}\left(c_2\sqrt{-\frac{1}{x^4}} + 2c_1\right)}{4}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = \frac{\sqrt{2} \left(-\frac{1}{x^4}\right)^{\frac{1}{4}} \left(c_2 \sqrt{-\frac{1}{x^4}} + 2c_1\right)}{4} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 1$ and $x = 1$ in the above gives

$$1 = \left(\frac{1}{2} + \frac{i}{2}\right) c_1 + \left(-\frac{1}{4} + \frac{i}{4}\right) c_2 \quad (1A)$$

Taking derivative of the solution gives

$$y' = \frac{\sqrt{2} \left(c_2 \sqrt{-\frac{1}{x^4}} + 2c_1\right)}{4 \left(-\frac{1}{x^4}\right)^{\frac{3}{4}} x^5} + \frac{\sqrt{2} c_2}{2 \left(-\frac{1}{x^4}\right)^{\frac{1}{4}} x^5}$$

substituting $y' = -5$ and $x = 1$ in the above gives

$$-5 = \left(-\frac{1}{2} - \frac{i}{2}\right) c_1 + \left(\frac{3}{4} - \frac{3i}{4}\right) c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$\begin{aligned} c_1 &= -1 + i \\ c_2 &= -4 - 4i \end{aligned}$$

Substituting these values back in above solution results in

$$y = -i\sqrt{2} \left(-\frac{1}{x^4}\right)^{\frac{3}{4}} + \frac{i\sqrt{2} \left(-\frac{1}{x^4}\right)^{\frac{1}{4}}}{2} - \sqrt{2} \left(-\frac{1}{x^4}\right)^{\frac{3}{4}} - \frac{\sqrt{2} \left(-\frac{1}{x^4}\right)^{\frac{1}{4}}}{2}$$

Summary

The solution(s) found are the following

$$y = -\left((1+i) \sqrt{-\frac{1}{x^4}} + \frac{1}{2} - \frac{i}{2}\right) \sqrt{2} \left(-\frac{1}{x^4}\right)^{\frac{1}{4}} \quad (1)$$

Verification of solutions

$$y = -\left((1+i) \sqrt{-\frac{1}{x^4}} + \frac{1}{2} - \frac{i}{2}\right) \sqrt{2} \left(-\frac{1}{x^4}\right)^{\frac{1}{4}}$$

Verified OK.

13.22.4 Solving as second order change of variable on x method 1 ode

In normal form the ode

$$x^2 y'' + 5y'x + 3y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = \frac{5}{x}$$
$$q(x) = \frac{3}{x^2}$$

Applying change of variables $\tau = g(x)$ to (2) results

$$\frac{d^2}{d\tau^2}y(\tau) + p_1\left(\frac{d}{d\tau}y(\tau)\right) + q_1y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $q_1 = c^2$ where c is some constant. Therefore from (5)

$$\tau' = \frac{1}{c}\sqrt{q}$$
$$= \frac{\sqrt{3}\sqrt{\frac{1}{x^2}}}{c} \quad (6)$$
$$\tau'' = -\frac{\sqrt{3}}{c\sqrt{\frac{1}{x^2}}x^3}$$

Substituting the above into (4) results in

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2}$$
$$= \frac{-\frac{\sqrt{3}}{c\sqrt{\frac{1}{x^2}}x^3} + \frac{5}{x}\frac{\sqrt{3}\sqrt{\frac{1}{x^2}}}{c}}{\left(\frac{\sqrt{3}\sqrt{\frac{1}{x^2}}}{c}\right)^2}$$
$$= \frac{4c\sqrt{3}}{3}$$

Therefore ode (3) now becomes

$$\begin{aligned}
 y(\tau)'' + p_1 y(\tau)' + q_1 y(\tau) &= 0 \\
 \frac{d^2}{d\tau^2} y(\tau) + \frac{4c\sqrt{3}}{3} \left(\frac{d}{d\tau} y(\tau) \right) + c^2 y(\tau) &= 0
 \end{aligned} \tag{7}$$

The above ode is now solved for $y(\tau)$. Since the ode is now constant coefficients, it can be easily solved to give

$$y(\tau) = e^{-\frac{2\sqrt{3}c\tau}{3}} \left(c_1 \cosh \left(\frac{\sqrt{3}c\tau}{3} \right) + ic_2 \sinh \left(\frac{\sqrt{3}c\tau}{3} \right) \right)$$

Now from (6)

$$\begin{aligned}
 \tau &= \int \frac{1}{c} \sqrt{q} dx \\
 &= \frac{\int \sqrt{3} \sqrt{\frac{1}{x^2}} dx}{c} \\
 &= \frac{\sqrt{3} \sqrt{\frac{1}{x^2}} x \ln(x)}{c}
 \end{aligned}$$

Substituting the above into the solution obtained gives

$$y = \frac{(ic_2 + c_1) x^2 - ic_2 + c_1}{2x^3}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = \frac{(ic_2 + c_1) x^2 - ic_2 + c_1}{2x^3} \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 1$ and $x = 1$ in the above gives

$$1 = c_1 \tag{1A}$$

Taking derivative of the solution gives

$$y' = \frac{ic_2 + c_1}{x^2} - \frac{3((ic_2 + c_1) x^2 - ic_2 + c_1)}{2x^4}$$

substituting $y' = -5$ and $x = 1$ in the above gives

$$-5 = ic_2 - 2c_1 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 1$$

$$c_2 = 3i$$

Substituting these values back in above solution results in

$$y = \frac{-x^2 + 2}{x^3}$$

Summary

The solution(s) found are the following

$$y = \frac{-x^2 + 2}{x^3} \quad (1)$$

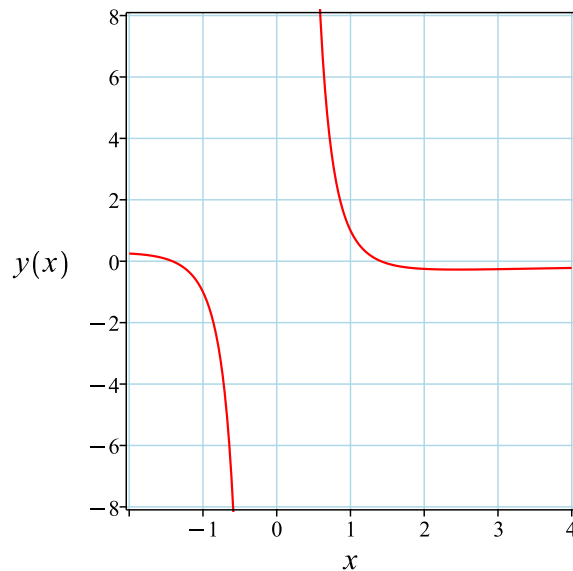


Figure 532: Solution plot

Verification of solutions

$$y = \frac{-x^2 + 2}{x^3}$$

Verified OK.

13.22.5 Solving as second order change of variable on y method 2 ode

In normal form the ode

$$x^2 y'' + 5y'x + 3y = 0 \quad (1)$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = \frac{5}{x}$$
$$q(x) = \frac{3}{x^2}$$

Applying change of variables on the dependent variable $y = v(x)x^n$ to (2) gives the following ode where the dependent variables is $v(x)$ and not y .

$$v''(x) + \left(\frac{2n}{x} + p\right)v'(x) + \left(\frac{n(n-1)}{x^2} + \frac{np}{x} + q\right)v(x) = 0 \quad (3)$$

Let the coefficient of $v(x)$ above be zero. Hence

$$\frac{n(n-1)}{x^2} + \frac{np}{x} + q = 0 \quad (4)$$

Substituting the earlier values found for $p(x)$ and $q(x)$ into (4) gives

$$\frac{n(n-1)}{x^2} + \frac{5n}{x^2} + \frac{3}{x^2} = 0 \quad (5)$$

Solving (5) for n gives

$$n = -1 \quad (6)$$

Substituting this value in (3) gives

$$v''(x) + \frac{3v'(x)}{x} = 0$$
$$v''(x) + \frac{3v'(x)}{x} = 0 \quad (7)$$

Using the substitution

$$u(x) = v'(x)$$

Then (7) becomes

$$u'(x) + \frac{3u(x)}{x} = 0 \quad (8)$$

The above is now solved for $u(x)$. In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= -\frac{3u}{x} \end{aligned}$$

Where $f(x) = -\frac{3}{x}$ and $g(u) = u$. Integrating both sides gives

$$\begin{aligned} \frac{1}{u} du &= -\frac{3}{x} dx \\ \int \frac{1}{u} du &= \int -\frac{3}{x} dx \\ \ln(u) &= -3 \ln(x) + c_1 \\ u &= e^{-3 \ln(x) + c_1} \\ &= \frac{c_1}{x^3} \end{aligned}$$

Now that $u(x)$ is known, then

$$\begin{aligned} v'(x) &= u(x) \\ v(x) &= \int u(x) dx + c_2 \\ &= -\frac{c_1}{2x^2} + c_2 \end{aligned}$$

Hence

$$\begin{aligned} y &= v(x) x^n \\ &= \frac{-\frac{c_1}{2x^2} + c_2}{x} \\ &= \frac{2c_2x^2 - c_1}{2x^3} \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = \frac{-\frac{c_1}{2x^2} + c_2}{x} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 1$ and $x = 1$ in the above gives

$$1 = -\frac{c_1}{2} + c_2 \quad (1A)$$

Taking derivative of the solution gives

$$y' = \frac{c_1}{x^4} - \frac{-\frac{c_1}{2x^2} + c_2}{x^2}$$

substituting $y' = -5$ and $x = 1$ in the above gives

$$-5 = \frac{3c_1}{2} - c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = -4$$

$$c_2 = -1$$

Substituting these values back in above solution results in

$$y = -\frac{x^2 - 2}{x^3}$$

Summary

The solution(s) found are the following

$$y = -\frac{x^2 - 2}{x^3} \quad (1)$$

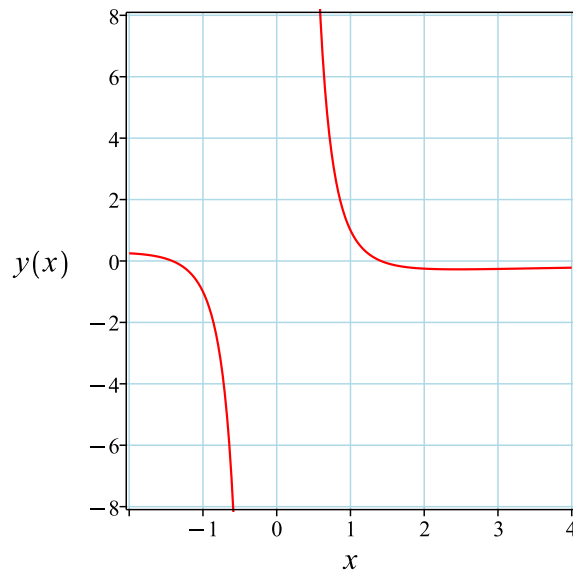


Figure 533: Solution plot

Verification of solutions

$$y = -\frac{x^2 - 2}{x^3}$$

Verified OK.

13.22.6 Solving as second order integrable as is ode

Integrating both sides of the ODE w.r.t x gives

$$\int (x^2 y'' + 5y'x + 3y) dx = 0$$
$$x^2 y' + 3yx = c_1$$

Which is now solved for y .

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = \frac{3}{x}$$
$$q(x) = \frac{c_1}{x^2}$$

Hence the ode is

$$y' + \frac{3y}{x} = \frac{c_1}{x^2}$$

The integrating factor μ is

$$\mu = e^{\int \frac{3}{x} dx}$$
$$= x^3$$

The ode becomes

$$\frac{d}{dx}(\mu y) = (\mu) \left(\frac{c_1}{x^2} \right)$$
$$\frac{d}{dx}(y x^3) = (x^3) \left(\frac{c_1}{x^2} \right)$$
$$d(y x^3) = (c_1 x) dx$$

Integrating gives

$$y x^3 = \int c_1 x dx$$
$$y x^3 = \frac{c_1 x^2}{2} + c_2$$

Dividing both sides by the integrating factor $\mu = x^3$ results in

$$y = \frac{c_1}{2x} + \frac{c_2}{x^3}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = \frac{c_1}{2x} + \frac{c_2}{x^3} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 1$ and $x = 1$ in the above gives

$$1 = c_2 + \frac{c_1}{2} \quad (1A)$$

Taking derivative of the solution gives

$$y' = -\frac{c_1}{2x^2} - \frac{3c_2}{x^4}$$

substituting $y' = -5$ and $x = 1$ in the above gives

$$-5 = -\frac{c_1}{2} - 3c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = -2$$

$$c_2 = 2$$

Substituting these values back in above solution results in

$$y = -\frac{x^2 - 2}{x^3}$$

Summary

The solution(s) found are the following

$$y = -\frac{x^2 - 2}{x^3} \quad (1)$$

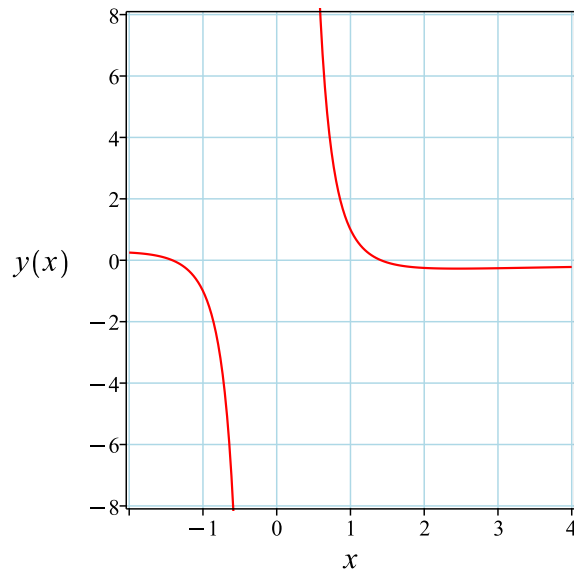


Figure 534: Solution plot

Verification of solutions

$$y = -\frac{x^2 - 2}{x^3}$$

Verified OK.

13.22.7 Solving as type second_order_integrable_as_is (not using ABC version)

Writing the ode as

$$x^2y'' + 5y'x + 3y = 0$$

Integrating both sides of the ODE w.r.t x gives

$$\int (x^2y'' + 5y'x + 3y) dx = 0$$

$$x^2y' + 3yx = c_1$$

Which is now solved for y .

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = \frac{3}{x}$$
$$q(x) = \frac{c_1}{x^2}$$

Hence the ode is

$$y' + \frac{3y}{x} = \frac{c_1}{x^2}$$

The integrating factor μ is

$$\mu = e^{\int \frac{3}{x} dx}$$
$$= x^3$$

The ode becomes

$$\frac{d}{dx}(\mu y) = (\mu) \left(\frac{c_1}{x^2} \right)$$
$$\frac{d}{dx}(y x^3) = (x^3) \left(\frac{c_1}{x^2} \right)$$
$$d(y x^3) = (c_1 x) dx$$

Integrating gives

$$y x^3 = \int c_1 x dx$$
$$y x^3 = \frac{c_1 x^2}{2} + c_2$$

Dividing both sides by the integrating factor $\mu = x^3$ results in

$$y = \frac{c_1}{2x} + \frac{c_2}{x^3}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = \frac{c_1}{2x} + \frac{c_2}{x^3} \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 1$ and $x = 1$ in the above gives

$$1 = c_2 + \frac{c_1}{2} \tag{1A}$$

Taking derivative of the solution gives

$$y' = -\frac{c_1}{2x^2} - \frac{3c_2}{x^4}$$

substituting $y' = -5$ and $x = 1$ in the above gives

$$-5 = -\frac{c_1}{2} - 3c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = -2$$

$$c_2 = 2$$

Substituting these values back in above solution results in

$$y = -\frac{x^2 - 2}{x^3}$$

Summary

The solution(s) found are the following

$$y = -\frac{x^2 - 2}{x^3} \quad (1)$$

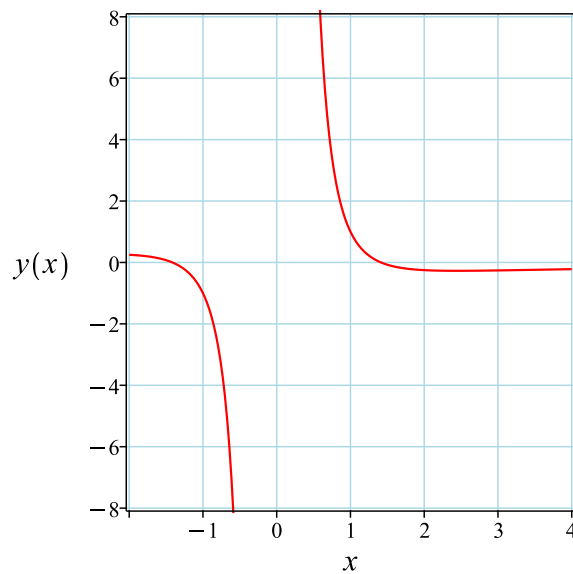


Figure 535: Solution plot

Verification of solutions

$$y = -\frac{x^2 - 2}{x^3}$$

Verified OK.

13.22.8 Solving using Kovacic algorithm

Writing the ode as

$$x^2y'' + 5y'x + 3y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= x^2 \\ B &= 5x \\ C &= 3 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{3}{4x^2} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 3 \\ t &= 4x^2 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = \left(\frac{3}{4x^2} \right) z(x) \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 501: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 2 - 0 \\ &= 2 \end{aligned}$$

The poles of r in eq. (7) and the order of each pole are determined by solving for the roots of $t = 4x^2$. There is a pole at $x = 0$ of order 2. Since there is no odd order pole larger than 2 and the order at ∞ is 2 then the necessary conditions for case one are met. Since there is a pole of order 2 then necessary conditions for case two are met. Since pole order is not larger than 2 and the order at ∞ is 2 then the necessary conditions for case three are met. Therefore

$$L = [1, 2, 4, 6, 12]$$

Attempting to find a solution using case $n = 1$.

Looking at poles of order 2. The partial fractions decomposition of r is

$$r = \frac{3}{4x^2}$$

For the pole at $x = 0$ let b be the coefficient of $\frac{1}{x^2}$ in the partial fractions decomposition of r given above. Therefore $b = \frac{3}{4}$. Hence

$$\begin{aligned} [\sqrt{r}]_c &= 0 \\ \alpha_c^+ &= \frac{1}{2} + \sqrt{1 + 4b} = \frac{3}{2} \\ \alpha_c^- &= \frac{1}{2} - \sqrt{1 + 4b} = -\frac{1}{2} \end{aligned}$$

Since the order of r at ∞ is 2 then $[\sqrt{r}]_\infty = 0$. Let b be the coefficient of $\frac{1}{x^2}$ in the Laurent series expansion of r at ∞ , which can be found by dividing the leading coefficient of s by the leading coefficient of t from

$$r = \frac{s}{t} = \frac{3}{4x^2}$$

Since the $\text{gcd}(s, t) = 1$. This gives $b = \frac{3}{4}$. Hence

$$\begin{aligned} [\sqrt{r}]_\infty &= 0 \\ \alpha_\infty^+ &= \frac{1}{2} + \sqrt{1 + 4b} = \frac{3}{2} \\ \alpha_\infty^- &= \frac{1}{2} - \sqrt{1 + 4b} = -\frac{1}{2} \end{aligned}$$

The following table summarizes the findings so far for poles and for the order of r at ∞ where r is

$$r = \frac{3}{4x^2}$$

pole c location	pole order	$[\sqrt{r}]_c$	α_c^+	α_c^-
0	2	0	$\frac{3}{2}$	$-\frac{1}{2}$

Order of r at ∞	$[\sqrt{r}]_\infty$	α_∞^+	α_∞^-
2	0	$\frac{3}{2}$	$-\frac{1}{2}$

Now that the all $[\sqrt{r}]_c$ and its associated α_c^\pm have been determined for all the poles in the set Γ and $[\sqrt{r}]_\infty$ and its associated α_∞^\pm have also been found, the next step is to determine possible non negative integer d from these using

$$d = \alpha_\infty^{s(\infty)} - \sum_{c \in \Gamma} \alpha_c^{s(c)}$$

Where $s(c)$ is either $+$ or $-$ and $s(\infty)$ is the sign of α_∞^\pm . This is done by trial over all set of families $s = (s(c))_{c \in \Gamma \cup \infty}$ until such d is found to work in finding candidate ω .

Trying $\alpha_{\infty}^{-} = -\frac{1}{2}$ then

$$\begin{aligned} d &= \alpha_{\infty}^{-} - (\alpha_{c_1}^{-}) \\ &= -\frac{1}{2} - \left(-\frac{1}{2}\right) \\ &= 0 \end{aligned}$$

Since d an integer and $d \geq 0$ then it can be used to find ω using

$$\omega = \sum_{c \in \Gamma} \left(s(c)[\sqrt{r}]_c + \frac{\alpha_c^{s(c)}}{x - c} \right) + s(\infty)[\sqrt{r}]_{\infty}$$

The above gives

$$\begin{aligned} \omega &= \left((-)[\sqrt{r}]_{c_1} + \frac{\alpha_{c_1}^{-}}{x - c_1} \right) + (-)[\sqrt{r}]_{\infty} \\ &= -\frac{1}{2x} + (-)(0) \\ &= -\frac{1}{2x} \\ &= -\frac{1}{2x} \end{aligned}$$

Now that ω is determined, the next step is find a corresponding minimal polynomial $p(x)$ of degree $d = 0$ to solve the ode. The polynomial $p(x)$ needs to satisfy the equation

$$p'' + 2\omega p' + (\omega' + \omega^2 - r) p = 0 \quad (1A)$$

Let

$$p(x) = 1 \quad (2A)$$

Substituting the above in eq. (1A) gives

$$\begin{aligned} (0) + 2\left(-\frac{1}{2x}\right)(0) + \left(\left(\frac{1}{2x^2}\right) + \left(-\frac{1}{2x}\right)^2 - \left(\frac{3}{4x^2}\right)\right) &= 0 \\ 0 &= 0 \end{aligned}$$

The equation is satisfied since both sides are zero. Therefore the first solution to the ode $z'' = rz$ is

$$\begin{aligned} z_1(x) &= p e^{\int \omega dx} \\ &= e^{\int -\frac{1}{2x} dx} \\ &= \frac{1}{\sqrt{x}} \end{aligned}$$

The first solution to the original ode in y is found from

$$\begin{aligned}y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\&= z_1 e^{-\int \frac{1}{2} \frac{5x}{x^2} dx} \\&= z_1 e^{-\frac{5 \ln(x)}{2}} \\&= z_1 \left(\frac{1}{x^{\frac{5}{2}}} \right)\end{aligned}$$

Which simplifies to

$$y_1 = \frac{1}{x^3}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{5x}{x^2} dx}}{(y_1)^2} dx \\&= y_1 \int \frac{e^{-5 \ln(x)}}{(y_1)^2} dx \\&= y_1 \left(\frac{x^2}{2} \right)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\&= c_1 \left(\frac{1}{x^3} \right) + c_2 \left(\frac{1}{x^3} \left(\frac{x^2}{2} \right) \right)\end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = \frac{c_1}{x^3} + \frac{c_2}{2x} \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 1$ and $x = 1$ in the above gives

$$1 = c_1 + \frac{c_2}{2} \quad (1A)$$

Taking derivative of the solution gives

$$y' = -\frac{3c_1}{x^4} - \frac{c_2}{2x^2}$$

substituting $y' = -5$ and $x = 1$ in the above gives

$$-5 = -3c_1 - \frac{c_2}{2} \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 2$$

$$c_2 = -2$$

Substituting these values back in above solution results in

$$y = -\frac{x^2 - 2}{x^3}$$

Summary

The solution(s) found are the following

$$y = -\frac{x^2 - 2}{x^3} \quad (1)$$

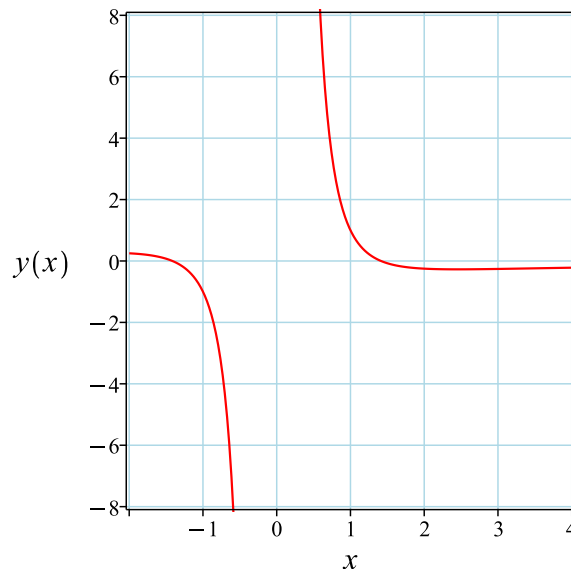


Figure 536: Solution plot

Verification of solutions

$$y = -\frac{x^2 - 2}{x^3}$$

Verified OK.

13.22.9 Solving as exact linear second order ode ode

An ode of the form

$$p(x)y'' + q(x)y' + r(x)y = s(x)$$

is exact if

$$p''(x) - q'(x) + r(x) = 0 \tag{1}$$

For the given ode we have

$$\begin{aligned} p(x) &= x^2 \\ q(x) &= 5x \\ r(x) &= 3 \\ s(x) &= 0 \end{aligned}$$

Hence

$$\begin{aligned} p''(x) &= 2 \\ q'(x) &= 5 \end{aligned}$$

Therefore (1) becomes

$$2 - (5) + (3) = 0$$

Hence the ode is exact. Since we now know the ode is exact, it can be written as

$$(p(x)y' + (q(x) - p'(x))y)' = s(x)$$

Integrating gives

$$p(x)y' + (q(x) - p'(x))y = \int s(x) dx$$

Substituting the above values for p, q, r, s gives

$$x^2y' + 3yx = c_1$$

We now have a first order ode to solve which is

$$x^2 y' + 3yx = c_1$$

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = \frac{3}{x}$$
$$q(x) = \frac{c_1}{x^2}$$

Hence the ode is

$$y' + \frac{3y}{x} = \frac{c_1}{x^2}$$

The integrating factor μ is

$$\mu = e^{\int \frac{3}{x} dx}$$
$$= x^3$$

The ode becomes

$$\frac{d}{dx}(\mu y) = (\mu) \left(\frac{c_1}{x^2} \right)$$
$$\frac{d}{dx}(y x^3) = (x^3) \left(\frac{c_1}{x^2} \right)$$
$$d(y x^3) = (c_1 x) dx$$

Integrating gives

$$y x^3 = \int c_1 x dx$$
$$y x^3 = \frac{c_1 x^2}{2} + c_2$$

Dividing both sides by the integrating factor $\mu = x^3$ results in

$$y = \frac{c_1}{2x} + \frac{c_2}{x^3}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = \frac{c_1}{2x} + \frac{c_2}{x^3} \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 1$ and $x = 1$ in the above gives

$$1 = c_2 + \frac{c_1}{2} \quad (1A)$$

Taking derivative of the solution gives

$$y' = -\frac{c_1}{2x^2} - \frac{3c_2}{x^4}$$

substituting $y' = -5$ and $x = 1$ in the above gives

$$-5 = -\frac{c_1}{2} - 3c_2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = -2$$

$$c_2 = 2$$

Substituting these values back in above solution results in

$$y = -\frac{x^2 - 2}{x^3}$$

Summary

The solution(s) found are the following

$$y = -\frac{x^2 - 2}{x^3} \quad (1)$$

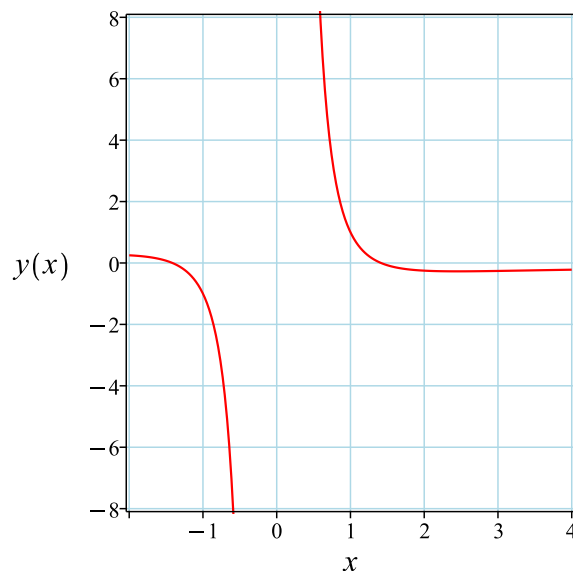


Figure 537: Solution plot

Verification of solutions

$$y = -\frac{x^2 - 2}{x^3}$$

Verified OK.

13.22.10 Maple step by step solution

Let's solve

$$\left[y''x^2 + 5y'x + 3y = 0, y(1) = 1, y'|_{\{x=1\}} = -5 \right]$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = -\frac{5y'}{x} - \frac{3y}{x^2}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + \frac{5y'}{x} + \frac{3y}{x^2} = 0$$

- Multiply by denominators of the ODE

$$y''x^2 + 5y'x + 3y = 0$$

- Make a change of variables

$$t = \ln(x)$$

- Substitute the change of variables back into the ODE

- Calculate the 1st derivative of y with respect to x , using the chain rule

$$y' = \left(\frac{d}{dt}y(t) \right) t'(x)$$

- Compute derivative

$$y' = \frac{\frac{d}{dt}y(t)}{x}$$

- Calculate the 2nd derivative of y with respect to x , using the chain rule

$$y'' = \left(\frac{d^2}{dt^2}y(t) \right) t'(x)^2 + t''(x) \left(\frac{d}{dt}y(t) \right)$$

- Compute derivative

$$y'' = \frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2}$$

Substitute the change of variables back into the ODE

$$\left(\frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2} \right) x^2 + 5 \frac{d}{dt}y(t) + 3y(t) = 0$$

- Simplify

$$\frac{d^2}{dt^2}y(t) + 4 \frac{d}{dt}y(t) + 3y(t) = 0$$

- Characteristic polynomial of ODE

$$r^2 + 4r + 3 = 0$$

- Factor the characteristic polynomial

$$(r + 3)(r + 1) = 0$$

- Roots of the characteristic polynomial

$$r = (-3, -1)$$

- 1st solution of the ODE

$$y_1(t) = e^{-3t}$$

- 2nd solution of the ODE

$$y_2(t) = e^{-t}$$

- General solution of the ODE

$$y(t) = c_1 y_1(t) + c_2 y_2(t)$$

- Substitute in solutions

$$y(t) = c_1 e^{-3t} + c_2 e^{-t}$$

- Change variables back using $t = \ln(x)$

$$y = \frac{c_1}{x^3} + \frac{c_2}{x}$$

- Simplify

$$y = \frac{c_1}{x^3} + \frac{c_2}{x}$$

- Check validity of solution $y = \frac{c_1}{x^3} + \frac{c_2}{x}$

- Use initial condition $y(1) = 1$

$$1 = c_1 + c_2$$

- Compute derivative of the solution

$$y' = -\frac{3c_1}{x^4} - \frac{c_2}{x^2}$$

- Use the initial condition $y' \Big|_{\{x=1\}} = -5$

$$-5 = -3c_1 - c_2$$

- Solve for c_1 and c_2

$$\{c_1 = 2, c_2 = -1\}$$

- Substitute constant values into general solution and simplify

$$y = \frac{-x^2+2}{x^3}$$

- Solution to the IVP

$$y = \frac{-x^2+2}{x^3}$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
<- LODE of Euler type successful`

```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 15

```
dsolve([x^2*diff(y(x),x$2)+5*x*diff(y(x),x)+3*y(x)=0,y(1) = 1, D(y)(1) = -5],y(x), singsol=a
```

$$y(x) = \frac{-x^2 + 2}{x^3}$$

✓ Solution by Mathematica

Time used: 0.011 (sec). Leaf size: 16

```
DSolve[{x^2*y'[x]+5*x*y'[x]+3*y[x]==0,{y[1]==1,y'[1]==-5}},y[x],x,IncludeSingularSolutions
```

$$y(x) \rightarrow \frac{2 - x^2}{x^3}$$

13.23 problem 23

13.23.1 Existence and uniqueness analysis	3666
13.23.2 Solving as second order euler ode ode	3666
13.23.3 Solving as second order integrable as is ode	3671
13.23.4 Solving as type second_order_integrable_as_is (not using ABC version)	3673
13.23.5 Solving using Kovacic algorithm	3676
13.23.6 Solving as exact linear second order ode ode	3685

Internal problem ID [11877]

Internal file name [OUTPUT/11886_Saturday_April_13_2024_01_14_01_AM_52727080/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.5. The Cauchy-Euler Equation. Exercises page 169

Problem number: 23.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_euler_ode", "exact linear second order ode", "second_order_integrable_as_is"

Maple gives the following as the ode type

```
[[_2nd_order , _exact , _linear , _nonhomogeneous]]
```

$$x^2y'' - 2y = 4x - 8$$

With initial conditions

$$[y(1) = 4, y'(1) = -1]$$

13.23.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$\begin{aligned}p(x) &= 0 \\q(x) &= -\frac{2}{x^2} \\F &= \frac{4x - 8}{x^2}\end{aligned}$$

Hence the ode is

$$y'' - \frac{2y}{x^2} = \frac{4x - 8}{x^2}$$

The domain of $p(x) = 0$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 1$ is inside this domain. The domain of $q(x) = -\frac{2}{x^2}$ is

$$\{x < 0 \vee 0 < x\}$$

And the point $x_0 = 1$ is also inside this domain. The domain of $F = \frac{4x-8}{x^2}$ is

$$\{x < 0 \vee 0 < x\}$$

And the point $x_0 = 1$ is also inside this domain. Hence solution exists and is unique.

13.23.2 Solving as second order euler ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = x^2, B = 0, C = -2, f(x) = 4x - 8$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. Solving for y_h from

$$x^2y'' - 2y = 0$$

This is Euler second order ODE. Let the solution be $y = x^r$, then $y' = rx^{r-1}$ and $y'' = r(r-1)x^{r-2}$. Substituting these back into the given ODE gives

$$x^2(r(r-1))x^{r-2} + 0rx^{r-1} - 2x^r = 0$$

Simplifying gives

$$r(r-1)x^r + 0x^r - 2x^r = 0$$

Since $x^r \neq 0$ then dividing throughout by x^r gives

$$r(r-1) + 0 - 2 = 0$$

Or

$$r^2 - r - 2 = 0 \tag{1}$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = -1$$

$$r_2 = 2$$

Since the roots are real and distinct, then the general solution is

$$y = c_1y_1 + c_2y_2$$

Where $y_1 = x^{r_1}$ and $y_2 = x^{r_2}$. Hence

$$y = \frac{c_1}{x} + c_2x^2$$

Next, we find the particular solution to the ODE

$$x^2y'' - 2y = 4x - 8$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1y_1 + u_2y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \frac{1}{x}$$

$$y_2 = x^2$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \frac{1}{x} & x^2 \\ \frac{d}{dx}\left(\frac{1}{x}\right) & \frac{d}{dx}(x^2) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \frac{1}{x} & x^2 \\ -\frac{1}{x^2} & 2x \end{vmatrix}$$

Therefore

$$W = \left(\frac{1}{x}\right)(2x) - (x^2)\left(-\frac{1}{x^2}\right)$$

Which simplifies to

$$W = 3$$

Which simplifies to

$$W = 3$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{x^2(4x - 8)}{3x^2} dx$$

Which simplifies to

$$u_1 = - \int \left(\frac{4x}{3} - \frac{8}{3}\right) dx$$

Hence

$$u_1 = -\frac{2}{3}x^2 + \frac{8}{3}x$$

And Eq. (3) becomes

$$u_2 = \int \frac{\frac{4x-8}{x}}{3x^2} dx$$

Which simplifies to

$$u_2 = \int \frac{4x-8}{3x^3} dx$$

Hence

$$u_2 = \frac{4}{3x^2} - \frac{4}{3x}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \frac{-\frac{2}{3}x^2 + \frac{8}{3}x}{x} + \left(\frac{4}{3x^2} - \frac{4}{3x} \right) x^2$$

Which simplifies to

$$y_p(x) = -2x + 4$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= -2x + 4 + \frac{c_1}{x} + c_2x^2 \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = -2x + 4 + \frac{c_1}{x} + c_2x^2 \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 4$ and $x = 1$ in the above gives

$$4 = c_1 + c_2 + 2 \tag{1A}$$

Taking derivative of the solution gives

$$y' = -2 - \frac{c_1}{x^2} + 2c_2x$$

substituting $y' = -1$ and $x = 1$ in the above gives

$$-1 = -2 - c_1 + 2c_2 \tag{2A}$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 1$$

$$c_2 = 1$$

Substituting these values back in above solution results in

$$y = \frac{x^3 - 2x^2 + 4x + 1}{x}$$

Summary

The solution(s) found are the following

$$y = \frac{x^3 - 2x^2 + 4x + 1}{x} \tag{1}$$

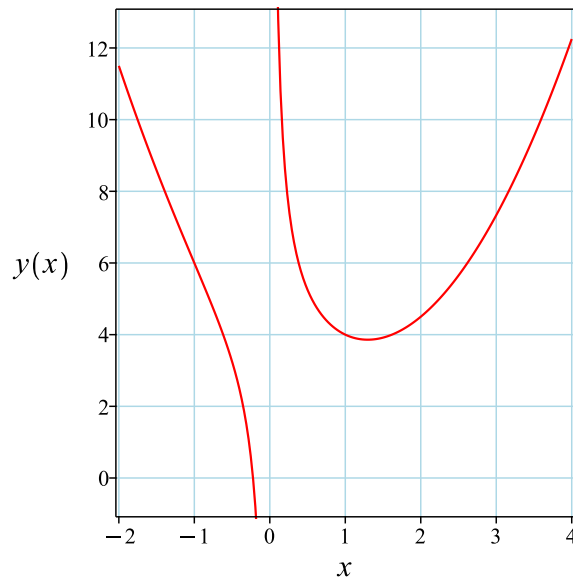


Figure 538: Solution plot

Verification of solutions

$$y = \frac{x^3 - 2x^2 + 4x + 1}{x}$$

Verified OK.

13.23.3 Solving as second order integrable as is ode

Integrating both sides of the ODE w.r.t x gives

$$\int (x^2 y'' - 2y) dx = \int (4x - 8) dx$$
$$x^2 y' - 2yx = 2x^2 - 8x + c_1$$

Which is now solved for y .

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = -\frac{2}{x}$$
$$q(x) = \frac{2x^2 + c_1 - 8x}{x^2}$$

Hence the ode is

$$y' - \frac{2y}{x} = \frac{2x^2 + c_1 - 8x}{x^2}$$

The integrating factor μ is

$$\mu = e^{\int -\frac{2}{x} dx}$$
$$= \frac{1}{x^2}$$

The ode becomes

$$\frac{d}{dx}(\mu y) = (\mu) \left(\frac{2x^2 + c_1 - 8x}{x^2} \right)$$
$$\frac{d}{dx} \left(\frac{y}{x^2} \right) = \left(\frac{1}{x^2} \right) \left(\frac{2x^2 + c_1 - 8x}{x^2} \right)$$
$$d \left(\frac{y}{x^2} \right) = \left(\frac{2x^2 + c_1 - 8x}{x^4} \right) dx$$

Integrating gives

$$\frac{y}{x^2} = \int \frac{2x^2 + c_1 - 8x}{x^4} dx$$
$$\frac{y}{x^2} = \frac{4}{x^2} - \frac{c_1}{3x^3} - \frac{2}{x} + c_2$$

Dividing both sides by the integrating factor $\mu = \frac{1}{x^2}$ results in

$$y = x^2 \left(\frac{4}{x^2} - \frac{c_1}{3x^3} - \frac{2}{x} \right) + c_2 x^2$$

which simplifies to

$$y = \frac{3c_2 x^3 - 6x^2 - c_1 + 12x}{3x}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = \frac{3c_2 x^3 - 6x^2 - c_1 + 12x}{3x} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 4$ and $x = 1$ in the above gives

$$4 = -\frac{c_1}{3} + c_2 + 2 \quad (1A)$$

Taking derivative of the solution gives

$$y' = \frac{9c_2 x^2 - 12x + 12}{3x} - \frac{3c_2 x^3 - 6x^2 - c_1 + 12x}{3x^2}$$

substituting $y' = -1$ and $x = 1$ in the above gives

$$-1 = \frac{c_1}{3} + 2c_2 - 2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = -3$$

$$c_2 = 1$$

Substituting these values back in above solution results in

$$y = \frac{x^3 - 2x^2 + 4x + 1}{x}$$

Summary

The solution(s) found are the following

$$y = \frac{x^3 - 2x^2 + 4x + 1}{x} \quad (1)$$

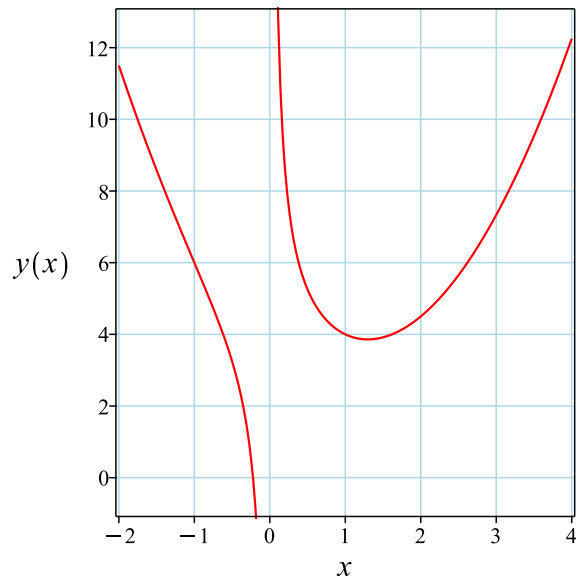


Figure 539: Solution plot

Verification of solutions

$$y = \frac{x^3 - 2x^2 + 4x + 1}{x}$$

Verified OK.

13.23.4 Solving as type second_order_integrable_as_is (not using ABC version)

Writing the ode as

$$x^2 y'' - 2y = 4x - 8$$

Integrating both sides of the ODE w.r.t x gives

$$\int (x^2 y'' - 2y) dx = \int (4x - 8) dx$$

$$x^2 y' - 2yx = 2x^2 - 8x + c_1$$

Which is now solved for y .

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = -\frac{2}{x}$$
$$q(x) = \frac{2x^2 + c_1 - 8x}{x^2}$$

Hence the ode is

$$y' - \frac{2y}{x} = \frac{2x^2 + c_1 - 8x}{x^2}$$

The integrating factor μ is

$$\mu = e^{\int -\frac{2}{x} dx}$$
$$= \frac{1}{x^2}$$

The ode becomes

$$\frac{d}{dx}(\mu y) = (\mu) \left(\frac{2x^2 + c_1 - 8x}{x^2} \right)$$
$$\frac{d}{dx} \left(\frac{y}{x^2} \right) = \left(\frac{1}{x^2} \right) \left(\frac{2x^2 + c_1 - 8x}{x^2} \right)$$
$$d \left(\frac{y}{x^2} \right) = \left(\frac{2x^2 + c_1 - 8x}{x^4} \right) dx$$

Integrating gives

$$\frac{y}{x^2} = \int \frac{2x^2 + c_1 - 8x}{x^4} dx$$
$$\frac{y}{x^2} = \frac{4}{x^2} - \frac{c_1}{3x^3} - \frac{2}{x} + c_2$$

Dividing both sides by the integrating factor $\mu = \frac{1}{x^2}$ results in

$$y = x^2 \left(\frac{4}{x^2} - \frac{c_1}{3x^3} - \frac{2}{x} \right) + c_2 x^2$$

which simplifies to

$$y = \frac{3c_2 x^3 - 6x^2 - c_1 + 12x}{3x}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = \frac{3c_2 x^3 - 6x^2 - c_1 + 12x}{3x} \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 4$ and $x = 1$ in the above gives

$$4 = -\frac{c_1}{3} + c_2 + 2 \quad (1A)$$

Taking derivative of the solution gives

$$y' = \frac{9c_2x^2 - 12x + 12}{3x} - \frac{3c_2x^3 - 6x^2 - c_1 + 12x}{3x^2}$$

substituting $y' = -1$ and $x = 1$ in the above gives

$$-1 = \frac{c_1}{3} + 2c_2 - 2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = -3$$

$$c_2 = 1$$

Substituting these values back in above solution results in

$$y = \frac{x^3 - 2x^2 + 4x + 1}{x}$$

Summary

The solution(s) found are the following

$$y = \frac{x^3 - 2x^2 + 4x + 1}{x} \quad (1)$$

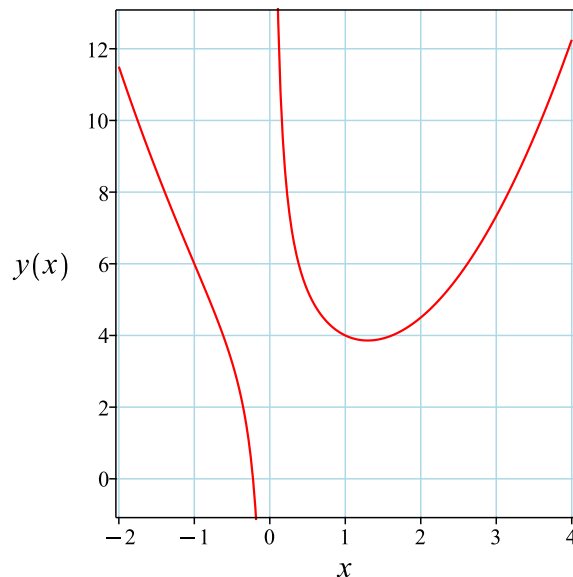


Figure 540: Solution plot

Verification of solutions

$$y = \frac{x^3 - 2x^2 + 4x + 1}{x}$$

Verified OK.

13.23.5 Solving using Kovacic algorithm

Writing the ode as

$$x^2 y'' - 2y = 0 \tag{1}$$

$$Ay'' + By' + Cy = 0 \tag{2}$$

Comparing (1) and (2) shows that

$$A = x^2$$

$$B = 0 \tag{3}$$

$$C = -2$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$r = \frac{s}{t} \tag{5}$$
$$= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{2}{x^2} \tag{6}$$

Comparing the above to (5) shows that

$$s = 2$$

$$t = x^2$$

Therefore eq. (4) becomes

$$z''(x) = \left(\frac{2}{x^2}\right) z(x) \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 503: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 2 - 0 \\ &= 2 \end{aligned}$$

The poles of r in eq. (7) and the order of each pole are determined by solving for the roots of $t = x^2$. There is a pole at $x = 0$ of order 2. Since there is no odd order pole larger than 2 and the order at ∞ is 2 then the necessary conditions for case one are met. Since there is a pole of order 2 then necessary conditions for case two are met. Since pole order is not larger than 2 and the order at ∞ is 2 then the necessary conditions for case three are met. Therefore

$$L = [1, 2, 4, 6, 12]$$

Attempting to find a solution using case $n = 1$.

Looking at poles of order 2. The partial fractions decomposition of r is

$$r = \frac{2}{x^2}$$

For the pole at $x = 0$ let b be the coefficient of $\frac{1}{x^2}$ in the partial fractions decomposition of r given above. Therefore $b = 2$. Hence

$$\begin{aligned} [\sqrt{r}]_c &= 0 \\ \alpha_c^+ &= \frac{1}{2} + \sqrt{1 + 4b} = 2 \\ \alpha_c^- &= \frac{1}{2} - \sqrt{1 + 4b} = -1 \end{aligned}$$

Since the order of r at ∞ is 2 then $[\sqrt{r}]_\infty = 0$. Let b be the coefficient of $\frac{1}{x^2}$ in the Laurent series expansion of r at ∞ . which can be found by dividing the leading coefficient of s by the leading coefficient of t from

$$r = \frac{s}{t} = \frac{2}{x^2}$$

Since the $\gcd(s, t) = 1$. This gives $b = 2$. Hence

$$\begin{aligned} [\sqrt{r}]_\infty &= 0 \\ \alpha_\infty^+ &= \frac{1}{2} + \sqrt{1 + 4b} = 2 \\ \alpha_\infty^- &= \frac{1}{2} - \sqrt{1 + 4b} = -1 \end{aligned}$$

The following table summarizes the findings so far for poles and for the order of r at ∞ where r is

$$r = \frac{2}{x^2}$$

pole c location	pole order	$[\sqrt{r}]_c$	α_c^+	α_c^-
0	2	0	2	-1

Order of r at ∞	$[\sqrt{r}]_\infty$	α_∞^+	α_∞^-
2	0	2	-1

Now that the all $[\sqrt{r}]_c$ and its associated α_c^\pm have been determined for all the poles in the set Γ and $[\sqrt{r}]_\infty$ and its associated α_∞^\pm have also been found, the next step is to

determine possible non negative integer d from these using

$$d = \alpha_{\infty}^{s(\infty)} - \sum_{c \in \Gamma} \alpha_c^{s(c)}$$

Where $s(c)$ is either $+$ or $-$ and $s(\infty)$ is the sign of α_{∞}^{\pm} . This is done by trial over all set of families $s = (s(c))_{c \in \Gamma \cup \infty}$ until such d is found to work in finding candidate ω . Trying $\alpha_{\infty}^{-} = -1$ then

$$\begin{aligned} d &= \alpha_{\infty}^{-} - (\alpha_{c_1}^{-}) \\ &= -1 - (-1) \\ &= 0 \end{aligned}$$

Since d an integer and $d \geq 0$ then it can be used to find ω using

$$\omega = \sum_{c \in \Gamma} \left(s(c)[\sqrt{r}]_c + \frac{\alpha_c^{s(c)}}{x - c} \right) + s(\infty)[\sqrt{r}]_{\infty}$$

The above gives

$$\begin{aligned} \omega &= \left((-)[\sqrt{r}]_{c_1} + \frac{\alpha_{c_1}^{-}}{x - c_1} \right) + (-)[\sqrt{r}]_{\infty} \\ &= -\frac{1}{x} + (-)(0) \\ &= -\frac{1}{x} \\ &= -\frac{1}{x} \end{aligned}$$

Now that ω is determined, the next step is find a corresponding minimal polynomial $p(x)$ of degree $d = 0$ to solve the ode. The polynomial $p(x)$ needs to satisfy the equation

$$p'' + 2\omega p' + (\omega' + \omega^2 - r) p = 0 \quad (1A)$$

Let

$$p(x) = 1 \quad (2A)$$

Substituting the above in eq. (1A) gives

$$\begin{aligned} (0) + 2\left(-\frac{1}{x}\right)(0) + \left(\left(\frac{1}{x^2}\right) + \left(-\frac{1}{x}\right)^2 - \left(\frac{2}{x^2}\right)\right) &= 0 \\ 0 &= 0 \end{aligned}$$

The equation is satisfied since both sides are zero. Therefore the first solution to the ode $z'' = rz$ is

$$\begin{aligned}z_1(x) &= pe^{\int \omega dx} \\ &= e^{\int -\frac{1}{x} dx} \\ &= \frac{1}{x}\end{aligned}$$

The first solution to the original ode in y is found from

$$y_1 = z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx}$$

Since $B = 0$ then the above reduces to

$$\begin{aligned}y_1 &= z_1 \\ &= \frac{1}{x}\end{aligned}$$

Which simplifies to

$$y_1 = \frac{1}{x}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Since $B = 0$ then the above becomes

$$\begin{aligned}y_2 &= y_1 \int \frac{1}{y_1^2} dx \\ &= \frac{1}{x} \int \frac{1}{\frac{1}{x^2}} dx \\ &= \frac{1}{x} \left(\frac{x^3}{3} \right)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\ &= c_1 \left(\frac{1}{x} \right) + c_2 \left(\frac{1}{x} \left(\frac{x^3}{3} \right) \right)\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$x^2y'' - 2y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = \frac{c_1}{x} + \frac{c_2x^2}{3}$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1y_1 + u_2y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \frac{1}{x}$$
$$y_2 = \frac{x^2}{3}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2f(x)}{aW(x)} \tag{2}$$

$$u_2 = \int \frac{y_1f(x)}{aW(x)} \tag{3}$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \frac{1}{x} & \frac{x^2}{3} \\ \frac{d}{dx}\left(\frac{1}{x}\right) & \frac{d}{dx}\left(\frac{x^2}{3}\right) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \frac{1}{x} & \frac{x^2}{3} \\ -\frac{1}{x^2} & \frac{2x}{3} \end{vmatrix}$$

Therefore

$$W = \left(\frac{1}{x}\right)\left(\frac{2x}{3}\right) - \left(\frac{x^2}{3}\right)\left(-\frac{1}{x^2}\right)$$

Which simplifies to

$$W = 1$$

Which simplifies to

$$W = 1$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{x^2(4x-8)}{3x^2} dx$$

Which simplifies to

$$u_1 = - \int \left(\frac{4x}{3} - \frac{8}{3}\right) dx$$

Hence

$$u_1 = -\frac{2}{3}x^2 + \frac{8}{3}x$$

And Eq. (3) becomes

$$u_2 = \int \frac{4x-8}{x^2} dx$$

Which simplifies to

$$u_2 = \int \frac{4x - 8}{x^3} dx$$

Hence

$$u_2 = \frac{4}{x^2} - \frac{4}{x}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \frac{-\frac{2}{3}x^2 + \frac{8}{3}x}{x} + \frac{\left(\frac{4}{x^2} - \frac{4}{x}\right)x^2}{3}$$

Which simplifies to

$$y_p(x) = -2x + 4$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(\frac{c_1}{x} + \frac{c_2 x^2}{3} \right) + (-2x + 4) \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = \frac{c_1}{x} + \frac{c_2 x^2}{3} - 2x + 4 \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 4$ and $x = 1$ in the above gives

$$4 = c_1 + \frac{c_2}{3} + 2 \quad (1A)$$

Taking derivative of the solution gives

$$y' = -\frac{c_1}{x^2} + \frac{2c_2 x}{3} - 2$$

substituting $y' = -1$ and $x = 1$ in the above gives

$$-1 = -c_1 + \frac{2c_2}{3} - 2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 1$$

$$c_2 = 3$$

Substituting these values back in above solution results in

$$y = \frac{x^3 - 2x^2 + 4x + 1}{x}$$

Summary

The solution(s) found are the following

$$y = \frac{x^3 - 2x^2 + 4x + 1}{x} \tag{1}$$

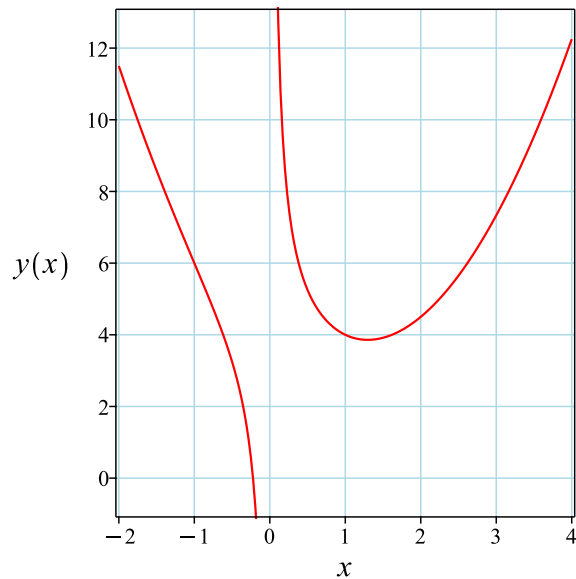


Figure 541: Solution plot

Verification of solutions

$$y = \frac{x^3 - 2x^2 + 4x + 1}{x}$$

Verified OK.

13.23.6 Solving as exact linear second order ode

An ode of the form

$$p(x)y'' + q(x)y' + r(x)y = s(x)$$

is exact if

$$p''(x) - q'(x) + r(x) = 0 \tag{1}$$

For the given ode we have

$$p(x) = x^2$$

$$q(x) = 0$$

$$r(x) = -2$$

$$s(x) = 4x - 8$$

Hence

$$p''(x) = 2$$

$$q'(x) = 0$$

Therefore (1) becomes

$$2 - (0) + (-2) = 0$$

Hence the ode is exact. Since we now know the ode is exact, it can be written as

$$(p(x)y' + (q(x) - p'(x))y)' = s(x)$$

Integrating gives

$$p(x)y' + (q(x) - p'(x))y = \int s(x) dx$$

Substituting the above values for p, q, r, s gives

$$x^2y' - 2yx = \int 4x - 8 dx$$

We now have a first order ode to solve which is

$$x^2y' - 2yx = 2x^2 + c_1 - 8x$$

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = -\frac{2}{x}$$
$$q(x) = \frac{2x^2 + c_1 - 8x}{x^2}$$

Hence the ode is

$$y' - \frac{2y}{x} = \frac{2x^2 + c_1 - 8x}{x^2}$$

The integrating factor μ is

$$\mu = e^{\int -\frac{2}{x} dx}$$
$$= \frac{1}{x^2}$$

The ode becomes

$$\frac{d}{dx}(\mu y) = (\mu) \left(\frac{2x^2 + c_1 - 8x}{x^2} \right)$$
$$\frac{d}{dx} \left(\frac{y}{x^2} \right) = \left(\frac{1}{x^2} \right) \left(\frac{2x^2 + c_1 - 8x}{x^2} \right)$$
$$d \left(\frac{y}{x^2} \right) = \left(\frac{2x^2 + c_1 - 8x}{x^4} \right) dx$$

Integrating gives

$$\frac{y}{x^2} = \int \frac{2x^2 + c_1 - 8x}{x^4} dx$$
$$\frac{y}{x^2} = \frac{4}{x^2} - \frac{c_1}{3x^3} - \frac{2}{x} + c_2$$

Dividing both sides by the integrating factor $\mu = \frac{1}{x^2}$ results in

$$y = x^2 \left(\frac{4}{x^2} - \frac{c_1}{3x^3} - \frac{2}{x} \right) + c_2 x^2$$

which simplifies to

$$y = \frac{3c_2 x^3 - 6x^2 - c_1 + 12x}{3x}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = \frac{3c_2x^3 - 6x^2 - c_1 + 12x}{3x} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 4$ and $x = 1$ in the above gives

$$4 = -\frac{c_1}{3} + c_2 + 2 \quad (1A)$$

Taking derivative of the solution gives

$$y' = \frac{9c_2x^2 - 12x + 12}{3x} - \frac{3c_2x^3 - 6x^2 - c_1 + 12x}{3x^2}$$

substituting $y' = -1$ and $x = 1$ in the above gives

$$-1 = \frac{c_1}{3} + 2c_2 - 2 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$\begin{aligned} c_1 &= -3 \\ c_2 &= 1 \end{aligned}$$

Substituting these values back in above solution results in

$$y = \frac{x^3 - 2x^2 + 4x + 1}{x}$$

Summary

The solution(s) found are the following

$$y = \frac{x^3 - 2x^2 + 4x + 1}{x} \quad (1)$$

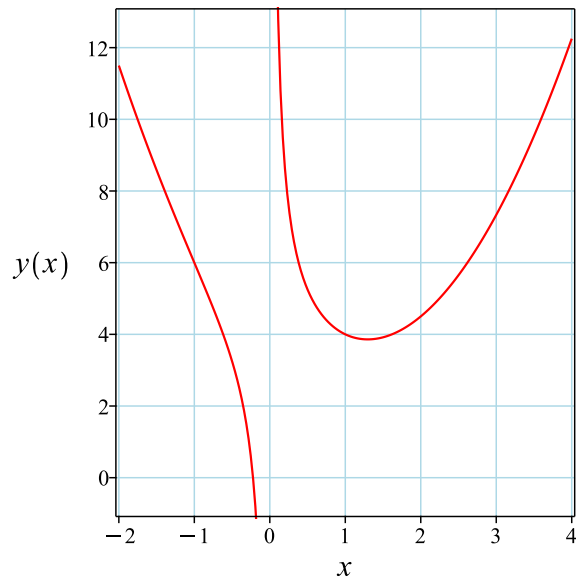


Figure 542: Solution plot

Verification of solutions

$$y = \frac{x^3 - 2x^2 + 4x + 1}{x}$$

Verified OK.

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
<- high order exact linear fully integrable successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 15

```
dsolve([x^2*diff(y(x),x$2)-2*y(x)=4*x-8,y(1) = 4, D(y)(1) = -1],y(x), singsol=all)
```

$$y(x) = x^2 + 4 - 2x + \frac{1}{x}$$

✓ Solution by Mathematica

Time used: 0.016 (sec). Leaf size: 16

```
DSolve[{x^2*y'[x]-2*y[x]==4*x-8,{y[1]==4,y'[1]==-1}},y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow x^2 - 2x + \frac{1}{x} + 4$$

13.24 problem 24

13.24.1 Existence and uniqueness analysis	3691
13.24.2 Solving as second order euler ode	3691
13.24.3 Solving as second order change of variable on x method 2 ode .	3696
13.24.4 Solving as second order change of variable on x method 1 ode .	3703
13.24.5 Solving as second order change of variable on y method 2 ode .	3709
13.24.6 Solving as second order ode non constant coeff transformation on B ode	3715
13.24.7 Solving using Kovacic algorithm	3720

Internal problem ID [11878]

Internal file name [OUTPUT/11887_Saturday_April_13_2024_01_14_03_AM_90411466/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.5. The Cauchy-Euler Equation. Exercises page 169

Problem number: 24.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_euler_ode", "second_order_change_of_variable_on_x_method_1", "second_order_change_of_variable_on_x_method_2", "second_order_change_of_variable_on_y_method_2", "second_order_ode_non_constant_coeff_transformation_on_B"

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$x^2y'' - 4y'x + 4y = -6x^3 + 4x^2$$

With initial conditions

$$[y(2) = 4, y'(2) = -1]$$

13.24.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$\begin{aligned} p(x) &= -\frac{4}{x} \\ q(x) &= \frac{4}{x^2} \\ F &= \frac{-6x^3 + 4x^2}{x^2} \end{aligned}$$

Hence the ode is

$$y'' - \frac{4y'}{x} + \frac{4y}{x^2} = \frac{-6x^3 + 4x^2}{x^2}$$

The domain of $p(x) = -\frac{4}{x}$ is

$$\{x < 0 \vee 0 < x\}$$

And the point $x_0 = 2$ is inside this domain. The domain of $q(x) = \frac{4}{x^2}$ is

$$\{x < 0 \vee 0 < x\}$$

And the point $x_0 = 2$ is also inside this domain. The domain of $F = \frac{-6x^3 + 4x^2}{x^2}$ is

$$\{x < 0 \vee 0 < x\}$$

And the point $x_0 = 2$ is also inside this domain. Hence solution exists and is unique.

13.24.2 Solving as second order euler ode ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = x^2, B = -4x, C = 4, f(x) = -6x^3 + 4x^2$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. Solving for y_h from

$$x^2y'' - 4y'x + 4y = 0$$

This is Euler second order ODE. Let the solution be $y = x^r$, then $y' = rx^{r-1}$ and $y'' = r(r-1)x^{r-2}$. Substituting these back into the given ODE gives

$$x^2(r(r-1))x^{r-2} - 4rxr^{r-1} + 4x^r = 0$$

Simplifying gives

$$r(r-1)x^r - 4rx^r + 4x^r = 0$$

Since $x^r \neq 0$ then dividing throughout by x^r gives

$$r(r-1) - 4r + 4 = 0$$

Or

$$r^2 - 5r + 4 = 0 \tag{1}$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = 1$$

$$r_2 = 4$$

Since the roots are real and distinct, then the general solution is

$$y = c_1y_1 + c_2y_2$$

Where $y_1 = x^{r_1}$ and $y_2 = x^{r_2}$. Hence

$$y = c_2x^4 + c_1x$$

Next, we find the particular solution to the ODE

$$x^2y'' - 4y'x + 4y = -6x^3 + 4x^2$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1y_1 + u_2y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = x$$

$$y_2 = x^4$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} x & x^4 \\ \frac{d}{dx}(x) & \frac{d}{dx}(x^4) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} x & x^4 \\ 1 & 4x^3 \end{vmatrix}$$

Therefore

$$W = (x)(4x^3) - (x^4)(1) \quad (1)$$

Which simplifies to

$$W = 3x^4$$

Which simplifies to

$$W = 3x^4$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{x^4(-6x^3 + 4x^2)}{3x^6} dx$$

Which simplifies to

$$u_1 = - \int \left(-2x + \frac{4}{3} \right) dx$$

Hence

$$u_1 = x^2 - \frac{4}{3}x$$

And Eq. (3) becomes

$$u_2 = \int \frac{x(-6x^3 + 4x^2)}{3x^6} dx$$

Which simplifies to

$$u_2 = \int \frac{-6x + 4}{3x^3} dx$$

Hence

$$u_2 = -\frac{2}{3x^2} + \frac{2}{x}$$

Which simplifies to

$$u_1 = x^2 - \frac{4}{3}x$$

$$u_2 = \frac{6x - 2}{3x^2}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \left(x^2 - \frac{4}{3}x \right) x + \frac{(6x - 2)x^2}{3}$$

Which simplifies to

$$y_p(x) = 3x^3 - 2x^2$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= x(c_2x^3 + 3x^2 + c_1 - 2x) \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = x(c_2x^3 + 3x^2 + c_1 - 2x) \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 4$ and $x = 2$ in the above gives

$$4 = 16c_2 + 16 + 2c_1 \quad (1A)$$

Taking derivative of the solution gives

$$y' = c_2x^3 + 3x^2 + c_1 - 2x + x(3c_2x^2 + 6x - 2)$$

substituting $y' = -1$ and $x = 2$ in the above gives

$$-1 = 32c_2 + 28 + c_1 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = \frac{5}{3}$$
$$c_2 = -\frac{23}{24}$$

Substituting these values back in above solution results in

$$y = -\frac{x(23x^3 - 72x^2 + 48x - 40)}{24}$$

Summary

The solution(s) found are the following

$$y = -\frac{x(23x^3 - 72x^2 + 48x - 40)}{24} \quad (1)$$

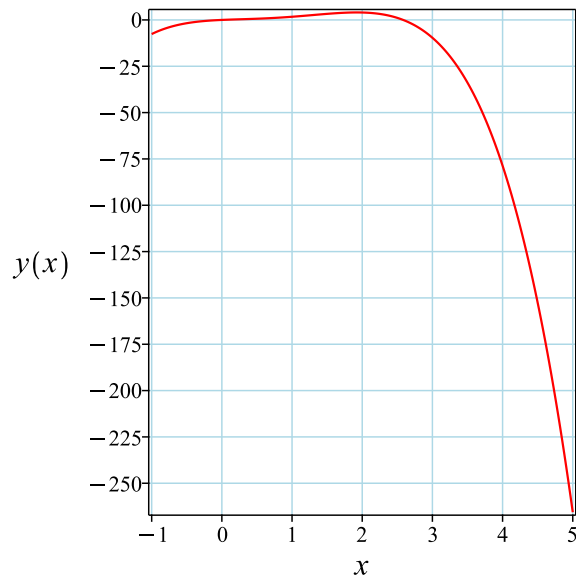


Figure 543: Solution plot

Verification of solutions

$$y = -\frac{x(23x^3 - 72x^2 + 48x - 40)}{24}$$

Verified OK.

13.24.3 Solving as second order change of variable on x method 2 ode

This is second order non-homogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$x^2y'' - 4y'x + 4y = 0$$

In normal form the ode

$$x^2y'' - 4y'x + 4y = 0 \tag{1}$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \tag{2}$$

Where

$$p(x) = -\frac{4}{x}$$
$$q(x) = \frac{4}{x^2}$$

Applying change of variables $\tau = g(x)$ to (2) gives

$$\frac{d^2}{d\tau^2}y(\tau) + p_1\left(\frac{d}{d\tau}y(\tau)\right) + q_1y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $p_1 = 0$. Eq (4) simplifies to

$$\tau''(x) + p(x)\tau'(x) = 0$$

This ode is solved resulting in

$$\begin{aligned} \tau &= \int e^{-(\int p(x)dx)} dx \\ &= \int e^{-(\int -\frac{4}{x}dx)} dx \\ &= \int e^{4\ln(x)} dx \\ &= \int x^4 dx \\ &= \frac{x^5}{5} \end{aligned} \quad (6)$$

Using (6) to evaluate q_1 from (5) gives

$$\begin{aligned} q_1(\tau) &= \frac{q(x)}{\tau'(x)^2} \\ &= \frac{\frac{4}{x^2}}{x^8} \\ &= \frac{4}{x^{10}} \end{aligned} \quad (7)$$

Substituting the above in (3) and noting that now $p_1 = 0$ results in

$$\begin{aligned}\frac{d^2}{d\tau^2}y(\tau) + q_1y(\tau) &= 0 \\ \frac{d^2}{d\tau^2}y(\tau) + \frac{4y(\tau)}{x^{10}} &= 0\end{aligned}$$

But in terms of τ

$$\frac{4}{x^{10}} = \frac{4}{25\tau^2}$$

Hence the above ode becomes

$$\frac{d^2}{d\tau^2}y(\tau) + \frac{4y(\tau)}{25\tau^2} = 0$$

The above ode is now solved for $y(\tau)$. The ode can be written as

$$25\left(\frac{d^2}{d\tau^2}y(\tau)\right)\tau^2 + 4y(\tau) = 0$$

Which shows it is a Euler ODE. This is Euler second order ODE. Let the solution be $y(\tau) = \tau^r$, then $y' = r\tau^{r-1}$ and $y'' = r(r-1)\tau^{r-2}$. Substituting these back into the given ODE gives

$$25\tau^2(r(r-1))\tau^{r-2} + 0r\tau^{r-1} + 4\tau^r = 0$$

Simplifying gives

$$25r(r-1)\tau^r + 0\tau^r + 4\tau^r = 0$$

Since $\tau^r \neq 0$ then dividing throughout by τ^r gives

$$25r(r-1) + 0 + 4 = 0$$

Or

$$25r^2 - 25r + 4 = 0 \tag{1}$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$\begin{aligned}r_1 &= \frac{1}{5} \\ r_2 &= \frac{4}{5}\end{aligned}$$

Since the roots are real and distinct, then the general solution is

$$y(\tau) = c_1y_1 + c_2y_2$$

Where $y_1 = \tau^{r_1}$ and $y_2 = \tau^{r_2}$. Hence

$$y(\tau) = c_1\tau^{\frac{1}{5}} + c_2\tau^{\frac{4}{5}}$$

The above solution is now transformed back to y using (6) which results in

$$y = \frac{c_1 5^{\frac{4}{5}} (x^5)^{\frac{1}{5}}}{5} + \frac{c_2 5^{\frac{1}{5}} (x^5)^{\frac{4}{5}}}{5}$$

Therefore the homogeneous solution y_h is

$$y_h = \frac{c_1 5^{\frac{4}{5}} (x^5)^{\frac{1}{5}}}{5} + \frac{c_2 5^{\frac{1}{5}} (x^5)^{\frac{4}{5}}}{5}$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = (x^5)^{\frac{1}{5}}$$

$$y_2 = (x^5)^{\frac{4}{5}}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} (x^5)^{\frac{1}{5}} & (x^5)^{\frac{4}{5}} \\ \frac{d}{dx} \left((x^5)^{\frac{1}{5}} \right) & \frac{d}{dx} \left((x^5)^{\frac{4}{5}} \right) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} (x^5)^{\frac{1}{5}} & (x^5)^{\frac{4}{5}} \\ \frac{x^4}{(x^5)^{\frac{4}{5}}} & \frac{4x^4}{(x^5)^{\frac{1}{5}}} \end{vmatrix}$$

Therefore

$$W = \left((x^5)^{\frac{1}{5}} \right) \left(\frac{4x^4}{(x^5)^{\frac{1}{5}}} \right) - \left((x^5)^{\frac{4}{5}} \right) \left(\frac{x^4}{(x^5)^{\frac{4}{5}}} \right)$$

Which simplifies to

$$W = 3x^4$$

Which simplifies to

$$W = 3x^4$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{(x^5)^{\frac{4}{5}} (-6x^3 + 4x^2)}{3x^6} dx$$

Which simplifies to

$$u_1 = - \int - \frac{2(x^5)^{\frac{4}{5}} (3x - 2)}{3x^4} dx$$

Hence

$$u_1 = \frac{(3x - 4)(x^5)^{\frac{4}{5}}}{3x^3}$$

And Eq. (3) becomes

$$u_2 = \int \frac{(x^5)^{\frac{1}{5}} (-6x^3 + 4x^2)}{3x^6} dx$$

Which simplifies to

$$u_2 = \int - \frac{2(x^5)^{\frac{1}{5}} (3x - 2)}{3x^4} dx$$

Hence

$$u_2 = \frac{2(3x-1)(x^5)^{\frac{1}{5}}}{3x^3}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \frac{x^2(3x-4)}{3} + \frac{2(3x-1)x^2}{3}$$

Which simplifies to

$$y_p(x) = 3x^3 - 2x^2$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(\frac{c_1 5^{\frac{4}{5}} (x^5)^{\frac{1}{5}}}{5} + \frac{c_2 5^{\frac{1}{5}} (x^5)^{\frac{4}{5}}}{5} \right) + (3x^3 - 2x^2) \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = \frac{c_1 5^{\frac{4}{5}} (x^5)^{\frac{1}{5}}}{5} + \frac{c_2 5^{\frac{1}{5}} (x^5)^{\frac{4}{5}}}{5} + 3x^3 - 2x^2 \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 4$ and $x = 2$ in the above gives

$$4 = \frac{2c_1 5^{\frac{4}{5}}}{5} + \frac{16c_2 5^{\frac{1}{5}}}{5} + 16 \quad (1A)$$

Taking derivative of the solution gives

$$y' = \frac{c_1 5^{\frac{4}{5}} x^4}{5 (x^5)^{\frac{4}{5}}} + \frac{4c_2 5^{\frac{1}{5}} x^4}{5 (x^5)^{\frac{1}{5}}} + 9x^2 - 4x$$

substituting $y' = -1$ and $x = 2$ in the above gives

$$-1 = \frac{c_1 5^{\frac{4}{5}}}{5} + \frac{32c_2 5^{\frac{1}{5}}}{5} + 28 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = \frac{5 \cdot 5^{\frac{1}{5}}}{3}$$
$$c_2 = -\frac{23 \cdot 5^{\frac{4}{5}}}{24}$$

Substituting these values back in above solution results in

$$y = \frac{5(x^5)^{\frac{1}{5}}}{3} - \frac{23(x^5)^{\frac{4}{5}}}{24} + 3x^3 - 2x^2$$

Summary

The solution(s) found are the following

$$y = \frac{5(x^5)^{\frac{1}{5}}}{3} - \frac{23(x^5)^{\frac{4}{5}}}{24} + 3x^3 - 2x^2 \quad (1)$$

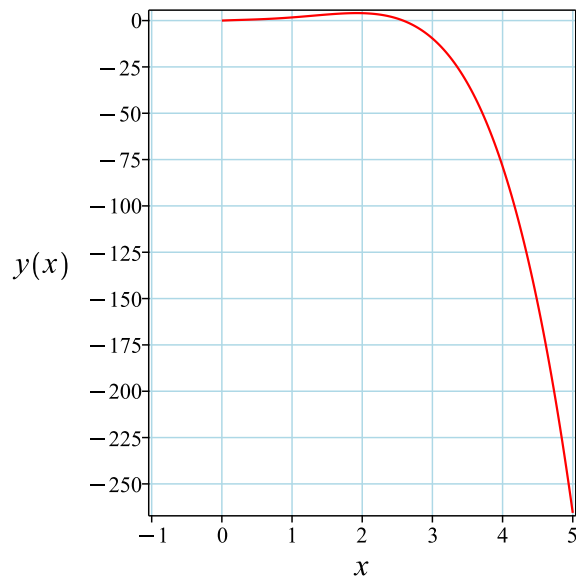


Figure 544: Solution plot

Verification of solutions

$$y = \frac{5(x^5)^{\frac{1}{5}}}{3} - \frac{23(x^5)^{\frac{4}{5}}}{24} + 3x^3 - 2x^2$$

Verified OK.

13.24.4 Solving as second order change of variable on x method 1 ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = x^2$, $B = -4x$, $C = 4$, $f(x) = -6x^3 + 4x^2$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. Solving for y_h from

$$x^2y'' - 4y'x + 4y = 0$$

In normal form the ode

$$x^2y'' - 4y'x + 4y = 0 \tag{1}$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \tag{2}$$

Where

$$p(x) = -\frac{4}{x}$$
$$q(x) = \frac{4}{x^2}$$

Applying change of variables $\tau = g(x)$ to (2) results

$$\frac{d^2}{d\tau^2}y(\tau) + p_1\left(\frac{d}{d\tau}y(\tau)\right) + q_1y(\tau) = 0 \tag{3}$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \tag{4}$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \tag{5}$$

Let $q_1 = c^2$ where c is some constant. Therefore from (5)

$$\tau' = \frac{1}{c}\sqrt{q}$$
$$= \frac{2\sqrt{\frac{1}{x^2}}}{c} \tag{6}$$
$$\tau'' = -\frac{2}{c\sqrt{\frac{1}{x^2}}x^3}$$

Substituting the above into (4) results in

$$\begin{aligned}
 p_1(\tau) &= \frac{\tau''(x) + p(x) \tau'(x)}{\tau'(x)^2} \\
 &= \frac{-\frac{2}{c\sqrt{\frac{1}{x^2}}x^3} - \frac{4}{x} \frac{2\sqrt{\frac{1}{x^2}}}{c}}{\left(\frac{2\sqrt{\frac{1}{x^2}}}{c}\right)^2} \\
 &= -\frac{5c}{2}
 \end{aligned}$$

Therefore ode (3) now becomes

$$\begin{aligned}
 y(\tau)'' + p_1 y(\tau)' + q_1 y(\tau) &= 0 \\
 \frac{d^2}{d\tau^2} y(\tau) - \frac{5c \left(\frac{d}{d\tau} y(\tau)\right)}{2} + c^2 y(\tau) &= 0 \tag{7}
 \end{aligned}$$

The above ode is now solved for $y(\tau)$. Since the ode is now constant coefficients, it can be easily solved to give

$$y(\tau) = e^{\frac{5c\tau}{4}} \left(c_1 \cosh\left(\frac{3c\tau}{4}\right) + ic_2 \sinh\left(\frac{3c\tau}{4}\right) \right)$$

Now from (6)

$$\begin{aligned}
 \tau &= \int \frac{1}{c} \sqrt{q} dx \\
 &= \frac{\int 2\sqrt{\frac{1}{x^2}} dx}{c} \\
 &= \frac{2\sqrt{\frac{1}{x^2}} x \ln(x)}{c}
 \end{aligned}$$

Substituting the above into the solution obtained gives

$$y = x^{\frac{5}{2}} \left(c_1 \cosh\left(\frac{3 \ln(x)}{2}\right) + ic_2 \sinh\left(\frac{3 \ln(x)}{2}\right) \right)$$

Now the particular solution to this ODE is found

$$x^2 y'' - 4y'x + 4y = -6x^3 + 4x^2$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of

parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = (x^5)^{\frac{1}{5}}$$

$$y_2 = (x^5)^{\frac{4}{5}}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} (x^5)^{\frac{1}{5}} & (x^5)^{\frac{4}{5}} \\ \frac{d}{dx} \left((x^5)^{\frac{1}{5}} \right) & \frac{d}{dx} \left((x^5)^{\frac{4}{5}} \right) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} (x^5)^{\frac{1}{5}} & (x^5)^{\frac{4}{5}} \\ \frac{x^4}{(x^5)^{\frac{4}{5}}} & \frac{4x^4}{(x^5)^{\frac{1}{5}}} \end{vmatrix}$$

Therefore

$$W = \left((x^5)^{\frac{1}{5}} \right) \left(\frac{4x^4}{(x^5)^{\frac{1}{5}}} \right) - \left((x^5)^{\frac{4}{5}} \right) \left(\frac{x^4}{(x^5)^{\frac{4}{5}}} \right)$$

Which simplifies to

$$W = 3x^4$$

Which simplifies to

$$W = 3x^4$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{(x^5)^{\frac{4}{5}} (-6x^3 + 4x^2)}{3x^6} dx$$

Which simplifies to

$$u_1 = - \int - \frac{2(x^5)^{\frac{4}{5}} (3x - 2)}{3x^4} dx$$

Hence

$$u_1 = \frac{(3x - 4) (x^5)^{\frac{4}{5}}}{3x^3}$$

And Eq. (3) becomes

$$u_2 = \int \frac{(x^5)^{\frac{1}{5}} (-6x^3 + 4x^2)}{3x^6} dx$$

Which simplifies to

$$u_2 = \int - \frac{2(x^5)^{\frac{1}{5}} (3x - 2)}{3x^4} dx$$

Hence

$$u_2 = \frac{2(3x - 1) (x^5)^{\frac{1}{5}}}{3x^3}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \frac{x^2(3x - 4)}{3} + \frac{2(3x - 1) x^2}{3}$$

Which simplifies to

$$y_p(x) = 3x^3 - 2x^2$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(x^{\frac{5}{2}} \left(c_1 \cosh \left(\frac{3 \ln(x)}{2} \right) + i c_2 \sinh \left(\frac{3 \ln(x)}{2} \right) \right) \right) + (3x^3 - 2x^2) \\ &= 3x^3 - 2x^2 + x^{\frac{5}{2}} \left(c_1 \cosh \left(\frac{3 \ln(x)}{2} \right) + i c_2 \sinh \left(\frac{3 \ln(x)}{2} \right) \right) \end{aligned}$$

Which simplifies to

$$y = i \sinh \left(\frac{3 \ln(x)}{2} \right) x^{\frac{5}{2}} c_2 + \cosh \left(\frac{3 \ln(x)}{2} \right) x^{\frac{5}{2}} c_1 + 3x^3 - 2x^2$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = i \sinh \left(\frac{3 \ln(x)}{2} \right) x^{\frac{5}{2}} c_2 + \cosh \left(\frac{3 \ln(x)}{2} \right) x^{\frac{5}{2}} c_1 + 3x^3 - 2x^2 \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 4$ and $x = 2$ in the above gives

$$4 = 7ic_2 + 9c_1 + 16 \quad (1A)$$

Taking derivative of the solution gives

$$y' = \frac{3ix^{\frac{3}{2}} \cosh \left(\frac{3 \ln(x)}{2} \right) c_2}{2} + \frac{5i \sinh \left(\frac{3 \ln(x)}{2} \right) x^{\frac{3}{2}} c_2}{2} + \frac{3x^{\frac{3}{2}} \sinh \left(\frac{3 \ln(x)}{2} \right) c_1}{2} + \frac{5 \cosh \left(\frac{3 \ln(x)}{2} \right) x^{\frac{3}{2}} c_1}{2} + 9x^2 - 4$$

substituting $y' = -1$ and $x = 2$ in the above gives

$$-1 = \frac{31ic_2}{2} + \frac{33c_1}{2} + 28 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$\begin{aligned} c_1 &= \frac{17}{24} \\ c_2 &= \frac{21i}{8} \end{aligned}$$

Substituting these values back in above solution results in

$$y = -\frac{21 \sinh\left(\frac{3\ln(x)}{2}\right) x^{\frac{5}{2}}}{8} + \frac{17 \cosh\left(\frac{3\ln(x)}{2}\right) x^{\frac{5}{2}}}{24} + 3x^3 - 2x^2$$

Summary

The solution(s) found are the following

$$y = -\frac{21 \sinh\left(\frac{3\ln(x)}{2}\right) x^{\frac{5}{2}}}{8} + \frac{17 \cosh\left(\frac{3\ln(x)}{2}\right) x^{\frac{5}{2}}}{24} + 3x^3 - 2x^2 \quad (1)$$

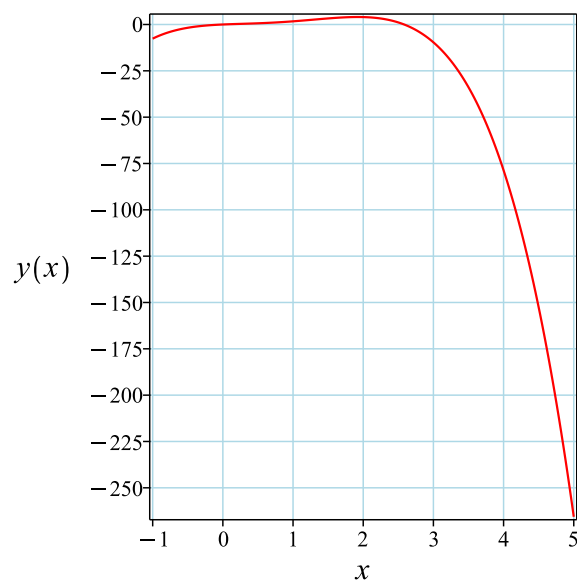


Figure 545: Solution plot

Verification of solutions

$$y = -\frac{21 \sinh\left(\frac{3\ln(x)}{2}\right) x^{\frac{5}{2}}}{8} + \frac{17 \cosh\left(\frac{3\ln(x)}{2}\right) x^{\frac{5}{2}}}{24} + 3x^3 - 2x^2$$

Verified OK.

13.24.5 Solving as second order change of variable on y method 2 ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = x^2$, $B = -4x$, $C = 4$, $f(x) = -6x^3 + 4x^2$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. Solving for y_h from

$$x^2y'' - 4y'x + 4y = 0$$

In normal form the ode

$$x^2y'' - 4y'x + 4y = 0 \tag{1}$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \tag{2}$$

Where

$$p(x) = -\frac{4}{x}$$
$$q(x) = \frac{4}{x^2}$$

Applying change of variables on the dependent variable $y = v(x)x^n$ to (2) gives the following ode where the dependent variable is $v(x)$ and not y .

$$v''(x) + \left(\frac{2n}{x} + p\right)v'(x) + \left(\frac{n(n-1)}{x^2} + \frac{np}{x} + q\right)v(x) = 0 \tag{3}$$

Let the coefficient of $v(x)$ above be zero. Hence

$$\frac{n(n-1)}{x^2} + \frac{np}{x} + q = 0 \tag{4}$$

Substituting the earlier values found for $p(x)$ and $q(x)$ into (4) gives

$$\frac{n(n-1)}{x^2} - \frac{4n}{x^2} + \frac{4}{x^2} = 0 \tag{5}$$

Solving (5) for n gives

$$n = 4 \tag{6}$$

Substituting this value in (3) gives

$$\begin{aligned} v''(x) + \frac{4v'(x)}{x} &= 0 \\ v''(x) + \frac{4v'(x)}{x} &= 0 \end{aligned} \tag{7}$$

Using the substitution

$$u(x) = v'(x)$$

Then (7) becomes

$$u'(x) + \frac{4u(x)}{x} = 0 \tag{8}$$

The above is now solved for $u(x)$. In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= -\frac{4u}{x} \end{aligned}$$

Where $f(x) = -\frac{4}{x}$ and $g(u) = u$. Integrating both sides gives

$$\begin{aligned} \frac{1}{u} du &= -\frac{4}{x} dx \\ \int \frac{1}{u} du &= \int -\frac{4}{x} dx \\ \ln(u) &= -4 \ln(x) + c_1 \\ u &= e^{-4 \ln(x) + c_1} \\ &= \frac{c_1}{x^4} \end{aligned}$$

Now that $u(x)$ is known, then

$$\begin{aligned} v'(x) &= u(x) \\ v(x) &= \int u(x) dx + c_2 \\ &= -\frac{c_1}{3x^3} + c_2 \end{aligned}$$

Hence

$$\begin{aligned}y &= v(x) x^n \\ &= \left(-\frac{c_1}{3x^3} + c_2\right) x^4 \\ &= c_2 x^4 - \frac{1}{3} c_1 x\end{aligned}$$

Now the particular solution to this ODE is found

$$x^2 y'' - 4y'x + 4y = -6x^3 + 4x^2$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$\begin{aligned}y_1 &= x \\ y_2 &= x^4\end{aligned}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} x & x^4 \\ \frac{d}{dx}(x) & \frac{d}{dx}(x^4) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} x & x^4 \\ 1 & 4x^3 \end{vmatrix}$$

Therefore

$$W = (x)(4x^3) - (x^4)(1)$$

Which simplifies to

$$W = 3x^4$$

Which simplifies to

$$W = 3x^4$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{x^4(-6x^3 + 4x^2)}{3x^6} dx$$

Which simplifies to

$$u_1 = - \int \left(-2x + \frac{4}{3} \right) dx$$

Hence

$$u_1 = x^2 - \frac{4}{3}x$$

And Eq. (3) becomes

$$u_2 = \int \frac{x(-6x^3 + 4x^2)}{3x^6} dx$$

Which simplifies to

$$u_2 = \int \frac{-6x + 4}{3x^3} dx$$

Hence

$$u_2 = -\frac{2}{3x^2} + \frac{2}{x}$$

Which simplifies to

$$u_1 = x^2 - \frac{4}{3}x$$
$$u_2 = \frac{6x - 2}{3x^2}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \left(x^2 - \frac{4}{3}x\right)x + \frac{(6x - 2)x^2}{3}$$

Which simplifies to

$$y_p(x) = 3x^3 - 2x^2$$

Therefore the general solution is

$$y = y_h + y_p$$
$$= \left(\left(-\frac{c_1}{3x^3} + c_2\right)x^4\right) + (3x^3 - 2x^2)$$
$$= 3x^3 - 2x^2 + \left(-\frac{c_1}{3x^3} + c_2\right)x^4$$

Which simplifies to

$$y = -\frac{x(-3c_2x^3 - 9x^2 + c_1 + 6x)}{3}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = -\frac{x(-3c_2x^3 - 9x^2 + c_1 + 6x)}{3} \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 4$ and $x = 2$ in the above gives

$$4 = 16c_2 + 16 - \frac{2c_1}{3} \tag{1A}$$

Taking derivative of the solution gives

$$y' = c_2x^3 + 3x^2 - \frac{c_1}{3} - 2x - \frac{x(-9c_2x^2 - 18x + 6)}{3}$$

substituting $y' = -1$ and $x = 2$ in the above gives

$$-1 = 32c_2 + 28 - \frac{c_1}{3} \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = -5$$
$$c_2 = -\frac{23}{24}$$

Substituting these values back in above solution results in

$$y = -\frac{x(23x^3 - 72x^2 + 48x - 40)}{24}$$

Summary

The solution(s) found are the following

$$y = -\frac{x(23x^3 - 72x^2 + 48x - 40)}{24} \quad (1)$$

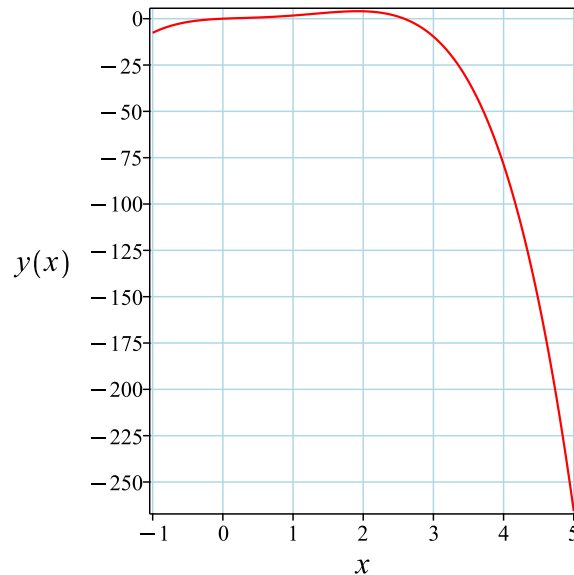


Figure 546: Solution plot

Verification of solutions

$$y = -\frac{x(23x^3 - 72x^2 + 48x - 40)}{24}$$

Verified OK.

13.24.6 Solving as second order ode non constant coeff transformation on B ode

Given an ode of the form

$$Ay'' + By' + Cy = F(x)$$

This method reduces the order ode the ODE by one by applying the transformation

$$y = Bv$$

This results in

$$\begin{aligned}y' &= B'v + v'B \\y'' &= B''v + B'v' + v''B + v'B' \\&= v''B + 2v' + B' + B''v\end{aligned}$$

And now the original ode becomes

$$\begin{aligned}A(v''B + 2v'B' + B''v) + B(B'v + v'B) + CBv &= 0 \\ABv'' + (2AB' + B^2)v' + (AB'' + BB' + CB)v &= 0\end{aligned}\tag{1}$$

If the term $AB'' + BB' + CB$ is zero, then this method works and can be used to solve

$$ABv'' + (2AB' + B^2)v' = 0$$

By Using $u = v'$ which reduces the order of the above ode to one. The new ode is

$$ABu' + (2AB' + B^2)u = 0$$

The above ode is first order ode which is solved for u . Now a new ode $v' = u$ is solved for v as first order ode. Then the final solution is obtain from $y = Bv$.

This method works only if the term $AB'' + BB' + CB$ is zero. The given ODE shows that

$$\begin{aligned}A &= x^2 \\B &= -4x \\C &= 4 \\F &= -6x^3 + 4x^2\end{aligned}$$

The above shows that for this ode

$$\begin{aligned}AB'' + BB' + CB &= (x^2)(0) + (-4x)(-4) + (4)(-4x) \\&= 0\end{aligned}$$

Hence the ode in v given in (1) now simplifies to

$$-4x^3v'' + (8x^2)v' = 0$$

Now by applying $v' = u$ the above becomes

$$-4x^2(u'(x)x - 2u(x)) = 0$$

Which is now solved for u . In canonical form the ODE is

$$\begin{aligned}u' &= F(x, u) \\ &= f(x)g(u) \\ &= \frac{2u}{x}\end{aligned}$$

Where $f(x) = \frac{2}{x}$ and $g(u) = u$. Integrating both sides gives

$$\begin{aligned}\frac{1}{u} du &= \frac{2}{x} dx \\ \int \frac{1}{u} du &= \int \frac{2}{x} dx \\ \ln(u) &= 2 \ln(x) + c_1 \\ u &= e^{2 \ln(x) + c_1} \\ &= c_1 x^2\end{aligned}$$

The ode for v now becomes

$$\begin{aligned}v' &= u \\ &= c_1 x^2\end{aligned}$$

Which is now solved for v . Integrating both sides gives

$$\begin{aligned}v(x) &= \int c_1 x^2 dx \\ &= \frac{c_1 x^3}{3} + c_2\end{aligned}$$

Therefore the homogeneous solution is

$$\begin{aligned}y_h(x) &= Bv \\ &= (-4x) \left(\frac{c_1 x^3}{3} + c_2 \right) \\ &= -\frac{4x(c_1 x^3 + 3c_2)}{3}\end{aligned}$$

And now the particular solution $y_p(x)$ will be found. The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1y_1 + u_2y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = x$$

$$y_2 = x^4$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} x & x^4 \\ \frac{d}{dx}(x) & \frac{d}{dx}(x^4) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} x & x^4 \\ 1 & 4x^3 \end{vmatrix}$$

Therefore

$$W = (x)(4x^3) - (x^4)(1)$$

Which simplifies to

$$W = 3x^4$$

Which simplifies to

$$W = 3x^4$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{x^4(-6x^3 + 4x^2)}{3x^6} dx$$

Which simplifies to

$$u_1 = - \int \left(-2x + \frac{4}{3} \right) dx$$

Hence

$$u_1 = x^2 - \frac{4}{3}x$$

And Eq. (3) becomes

$$u_2 = \int \frac{x(-6x^3 + 4x^2)}{3x^6} dx$$

Which simplifies to

$$u_2 = \int \frac{-6x + 4}{3x^3} dx$$

Hence

$$u_2 = -\frac{2}{3x^2} + \frac{2}{x}$$

Which simplifies to

$$u_1 = x^2 - \frac{4}{3}x$$

$$u_2 = \frac{6x - 2}{3x^2}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \left(x^2 - \frac{4}{3}x \right) x + \frac{(6x - 2)x^2}{3}$$

Which simplifies to

$$y_p(x) = 3x^3 - 2x^2$$

Hence the complete solution is

$$\begin{aligned} y(x) &= y_h + y_p \\ &= \left(-\frac{4x(c_1x^3 + 3c_2)}{3} \right) + (3x^3 - 2x^2) \\ &= -\frac{4}{3}c_1x^4 - 4c_2x + 3x^3 - 2x^2 \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = -\frac{4}{3}c_1x^4 - 4c_2x + 3x^3 - 2x^2 \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 4$ and $x = 2$ in the above gives

$$4 = -\frac{64c_1}{3} - 8c_2 + 16 \quad (1A)$$

Taking derivative of the solution gives

$$y' = -\frac{16}{3}c_1x^3 - 4c_2 + 9x^2 - 4x$$

substituting $y' = -1$ and $x = 2$ in the above gives

$$-1 = -\frac{128c_1}{3} - 4c_2 + 28 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$\begin{aligned} c_1 &= \frac{23}{32} \\ c_2 &= -\frac{5}{12} \end{aligned}$$

Substituting these values back in above solution results in

$$y = -\frac{23}{24}x^4 + 3x^3 - 2x^2 + \frac{5}{3}x$$

Summary

The solution(s) found are the following

$$y = -\frac{23}{24}x^4 + 3x^3 - 2x^2 + \frac{5}{3}x \quad (1)$$

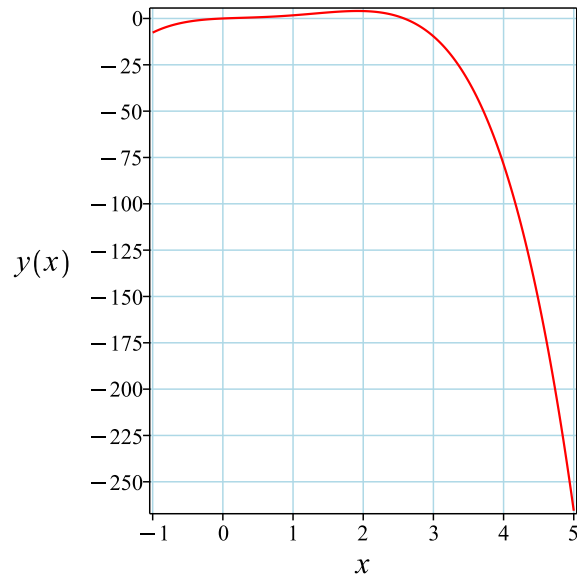


Figure 547: Solution plot

Verification of solutions

$$y = -\frac{23}{24}x^4 + 3x^3 - 2x^2 + \frac{5}{3}x$$

Verified OK.

13.24.7 Solving using Kovacic algorithm

Writing the ode as

$$x^2 y'' - 4y'x + 4y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= x^2 \\ B &= -4x \\ C &= 4 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{2}{x^2} \tag{6}$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 2 \\ t &= x^2 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = \left(\frac{2}{x^2}\right) z(x) \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 504: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 2 - 0 \\ &= 2 \end{aligned}$$

The poles of r in eq. (7) and the order of each pole are determined by solving for the roots of $t = x^2$. There is a pole at $x = 0$ of order 2. Since there is no odd order pole larger than 2 and the order at ∞ is 2 then the necessary conditions for case one are met. Since there is a pole of order 2 then necessary conditions for case two are met. Since pole order is not larger than 2 and the order at ∞ is 2 then the necessary conditions for case three are met. Therefore

$$L = [1, 2, 4, 6, 12]$$

Attempting to find a solution using case $n = 1$.

Looking at poles of order 2. The partial fractions decomposition of r is

$$r = \frac{2}{x^2}$$

For the pole at $x = 0$ let b be the coefficient of $\frac{1}{x^2}$ in the partial fractions decomposition

of r given above. Therefore $b = 2$. Hence

$$\begin{aligned} [\sqrt{r}]_c &= 0 \\ \alpha_c^+ &= \frac{1}{2} + \sqrt{1 + 4b} = 2 \\ \alpha_c^- &= \frac{1}{2} - \sqrt{1 + 4b} = -1 \end{aligned}$$

Since the order of r at ∞ is 2 then $[\sqrt{r}]_\infty = 0$. Let b be the coefficient of $\frac{1}{x^2}$ in the Laurent series expansion of r at ∞ . which can be found by dividing the leading coefficient of s by the leading coefficient of t from

$$r = \frac{s}{t} = \frac{2}{x^2}$$

Since the $\gcd(s, t) = 1$. This gives $b = 2$. Hence

$$\begin{aligned} [\sqrt{r}]_\infty &= 0 \\ \alpha_\infty^+ &= \frac{1}{2} + \sqrt{1 + 4b} = 2 \\ \alpha_\infty^- &= \frac{1}{2} - \sqrt{1 + 4b} = -1 \end{aligned}$$

The following table summarizes the findings so far for poles and for the order of r at ∞ where r is

$$r = \frac{2}{x^2}$$

pole c location	pole order	$[\sqrt{r}]_c$	α_c^+	α_c^-
0	2	0	2	-1

Order of r at ∞	$[\sqrt{r}]_\infty$	α_∞^+	α_∞^-
2	0	2	-1

Now that the all $[\sqrt{r}]_c$ and its associated α_c^\pm have been determined for all the poles in the set Γ and $[\sqrt{r}]_\infty$ and its associated α_∞^\pm have also been found, the next step is to determine possible non negative integer d from these using

$$d = \alpha_\infty^{s(\infty)} - \sum_{c \in \Gamma} \alpha_c^{s(c)}$$

Where $s(c)$ is either $+$ or $-$ and $s(\infty)$ is the sign of α_∞^\pm . This is done by trial over all set of families $s = (s(c))_{c \in \Gamma \cup \infty}$ until such d is found to work in finding candidate ω .

Trying $\alpha_{\infty}^{-} = -1$ then

$$\begin{aligned} d &= \alpha_{\infty}^{-} - (\alpha_{c_1}^{-}) \\ &= -1 - (-1) \\ &= 0 \end{aligned}$$

Since d an integer and $d \geq 0$ then it can be used to find ω using

$$\omega = \sum_{c \in \Gamma} \left(s(c)[\sqrt{r}]_c + \frac{\alpha_c^{s(c)}}{x - c} \right) + s(\infty)[\sqrt{r}]_{\infty}$$

The above gives

$$\begin{aligned} \omega &= \left((-)[\sqrt{r}]_{c_1} + \frac{\alpha_{c_1}^{-}}{x - c_1} \right) + (-)[\sqrt{r}]_{\infty} \\ &= -\frac{1}{x} + (-)(0) \\ &= -\frac{1}{x} \\ &= -\frac{1}{x} \end{aligned}$$

Now that ω is determined, the next step is find a corresponding minimal polynomial $p(x)$ of degree $d = 0$ to solve the ode. The polynomial $p(x)$ needs to satisfy the equation

$$p'' + 2\omega p' + (\omega' + \omega^2 - r)p = 0 \quad (1A)$$

Let

$$p(x) = 1 \quad (2A)$$

Substituting the above in eq. (1A) gives

$$\begin{aligned} (0) + 2\left(-\frac{1}{x}\right)(0) + \left(\left(\frac{1}{x^2}\right) + \left(-\frac{1}{x}\right)^2 - \left(\frac{2}{x^2}\right)\right) &= 0 \\ 0 &= 0 \end{aligned}$$

The equation is satisfied since both sides are zero. Therefore the first solution to the ode $z'' = rz$ is

$$\begin{aligned} z_1(x) &= pe^{\int \omega dx} \\ &= e^{\int -\frac{1}{x} dx} \\ &= \frac{1}{x} \end{aligned}$$

The first solution to the original ode in y is found from

$$\begin{aligned}y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\&= z_1 e^{-\int \frac{1}{2} \frac{-4x}{x^2} dx} \\&= z_1 e^{2 \ln(x)} \\&= z_1 (x^2)\end{aligned}$$

Which simplifies to

$$y_1 = x$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{-4x}{x^2} dx}}{(y_1)^2} dx \\&= y_1 \int \frac{e^{4 \ln(x)}}{(y_1)^2} dx \\&= y_1 \left(\frac{x^3}{3} \right)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\&= c_1 (x) + c_2 \left(x \left(\frac{x^3}{3} \right) \right)\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$.
 y_h is the solution to

$$x^2 y'' - 4y'x + 4y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1x + \frac{1}{3}c_2x^4$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1y_1 + u_2y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = x$$

$$y_2 = \frac{x^4}{3}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2f(x)}{aW(x)} \tag{2}$$

$$u_2 = \int \frac{y_1f(x)}{aW(x)} \tag{3}$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} x & \frac{x^4}{3} \\ \frac{d}{dx}(x) & \frac{d}{dx}\left(\frac{x^4}{3}\right) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} x & \frac{x^4}{3} \\ 1 & \frac{4x^3}{3} \end{vmatrix}$$

Therefore

$$W = (x) \left(\frac{4x^3}{3} \right) - \left(\frac{x^4}{3} \right) \quad (1)$$

Which simplifies to

$$W = x^4$$

Which simplifies to

$$W = x^4$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{x^4(-6x^3+4x^2)}{\frac{3}{x^6}} dx$$

Which simplifies to

$$u_1 = - \int \left(-2x + \frac{4}{3} \right) dx$$

Hence

$$u_1 = x^2 - \frac{4}{3}x$$

And Eq. (3) becomes

$$u_2 = \int \frac{x(-6x^3 + 4x^2)}{x^6} dx$$

Which simplifies to

$$u_2 = \int \frac{-6x + 4}{x^3} dx$$

Hence

$$u_2 = -\frac{2}{x^2} + \frac{6}{x}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \left(x^2 - \frac{4}{3}x \right) x + \frac{\left(-\frac{2}{x^2} + \frac{6}{x} \right) x^4}{3}$$

Which simplifies to

$$y_p(x) = 3x^3 - 2x^2$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(c_1x + \frac{1}{3}c_2x^4 \right) + (3x^3 - 2x^2) \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1x + \frac{1}{3}c_2x^4 + 3x^3 - 2x^2 \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 4$ and $x = 2$ in the above gives

$$4 = 2c_1 + \frac{16c_2}{3} + 16 \quad (1A)$$

Taking derivative of the solution gives

$$y' = c_1 + \frac{4}{3}c_2x^3 + 9x^2 - 4x$$

substituting $y' = -1$ and $x = 2$ in the above gives

$$-1 = c_1 + \frac{32c_2}{3} + 28 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$\begin{aligned} c_1 &= \frac{5}{3} \\ c_2 &= -\frac{23}{8} \end{aligned}$$

Substituting these values back in above solution results in

$$y = -\frac{23}{24}x^4 + 3x^3 - 2x^2 + \frac{5}{3}x$$

Summary

The solution(s) found are the following

$$y = -\frac{23}{24}x^4 + 3x^3 - 2x^2 + \frac{5}{3}x \quad (1)$$

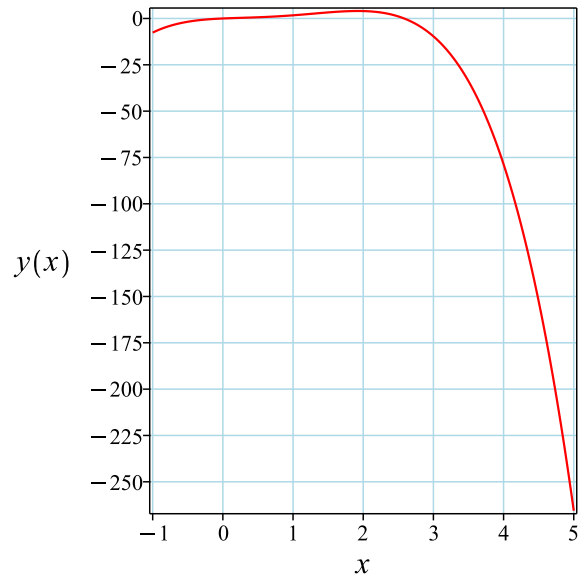


Figure 548: Solution plot

Verification of solutions

$$y = -\frac{23}{24}x^4 + 3x^3 - 2x^2 + \frac{5}{3}x$$

Verified OK.

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]  
trying a double symmetry of the form [xi=0, eta=F(x)]  
-> Try solving first the homogeneous part of the ODE  
    checking if the LODE has constant coefficients  
    checking if the LODE is of Euler type  
    <- LODE of Euler type successful  
<- solving first the homogeneous part of the ODE successful`
```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 23

```
dsolve([x^2*diff(y(x),x$2)-4*x*diff(y(x),x)+4*y(x)=4*x^2-6*x^3,y(2) = 4, D(y)(2) = -1],y(x),
```

$$y(x) = -\frac{23}{24}x^4 + 3x^3 - 2x^2 + \frac{5}{3}x$$

✓ Solution by Mathematica

Time used: 0.02 (sec). Leaf size: 28

```
DSolve[{x^2*y'[x]-4*x*y'[x]+4*y[x]==4*x^2-6*x^3,{y[2]==4,y'[2]==-1}},y[x],x,IncludeSingular
```

$$y(x) \rightarrow -\frac{23x^4}{24} + 3x^3 - 2x^2 + \frac{5x}{3}$$

13.25 problem 25

13.25.1 Existence and uniqueness analysis	3731
13.25.2 Solving as second order euler ode ode	3732
13.25.3 Solving as second order change of variable on x method 2 ode .	3736
13.25.4 Solving as second order change of variable on y method 2 ode .	3742
13.25.5 Solving using Kovacic algorithm	3748

Internal problem ID [11879]

Internal file name [OUTPUT/11888_Saturday_April_13_2024_01_14_07_AM_57165022/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.5. The Cauchy-Euler Equation. Exercises page 169

Problem number: 25.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_euler_ode", "second_order_change_of_variable_on_x_method_2", "second_order_change_of_variable_on_y_method_2"

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$x^2y'' + 2y'x - 6y = 10x^2$$

With initial conditions

$$[y(1) = 1, y'(1) = -6]$$

13.25.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$p(x) = \frac{2}{x}$$
$$q(x) = -\frac{6}{x^2}$$
$$F = 10$$

Hence the ode is

$$y'' + \frac{2y'}{x} - \frac{6y}{x^2} = 10$$

The domain of $p(x) = \frac{2}{x}$ is

$$\{x < 0 \vee 0 < x\}$$

And the point $x_0 = 1$ is inside this domain. The domain of $q(x) = -\frac{6}{x^2}$ is

$$\{x < 0 \vee 0 < x\}$$

And the point $x_0 = 1$ is also inside this domain. The domain of $F = 10$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 1$ is also inside this domain. Hence solution exists and is unique.

13.25.2 Solving as second order euler ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = x^2$, $B = 2x$, $C = -6$, $f(x) = 10x^2$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. Solving for y_h from

$$x^2y'' + 2y'x - 6y = 0$$

This is Euler second order ODE. Let the solution be $y = x^r$, then $y' = rx^{r-1}$ and $y'' = r(r-1)x^{r-2}$. Substituting these back into the given ODE gives

$$x^2(r(r-1))x^{r-2} + 2rx^{r-1} - 6x^r = 0$$

Simplifying gives

$$r(r-1)x^r + 2rx^r - 6x^r = 0$$

Since $x^r \neq 0$ then dividing throughout by x^r gives

$$r(r-1) + 2r - 6 = 0$$

Or

$$r^2 + r - 6 = 0 \quad (1)$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = -3$$

$$r_2 = 2$$

Since the roots are real and distinct, then the general solution is

$$y = c_1 y_1 + c_2 y_2$$

Where $y_1 = x^{r_1}$ and $y_2 = x^{r_2}$. Hence

$$y = \frac{c_1}{x^3} + c_2 x^2$$

Next, we find the particular solution to the ODE

$$x^2 y'' + 2y'x - 6y = 10x^2$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \frac{1}{x^3}$$

$$y_2 = x^2$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \frac{1}{x^3} & x^2 \\ \frac{d}{dx}\left(\frac{1}{x^3}\right) & \frac{d}{dx}(x^2) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \frac{1}{x^3} & x^2 \\ -\frac{3}{x^4} & 2x \end{vmatrix}$$

Therefore

$$W = \left(\frac{1}{x^3}\right)(2x) - (x^2)\left(-\frac{3}{x^4}\right)$$

Which simplifies to

$$W = \frac{5}{x^2}$$

Which simplifies to

$$W = \frac{5}{x^2}$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{10x^4}{5} dx$$

Which simplifies to

$$u_1 = - \int 2x^4 dx$$

Hence

$$u_1 = -\frac{2x^5}{5}$$

And Eq. (3) becomes

$$u_2 = \int \frac{10}{5} dx$$

Which simplifies to

$$u_2 = \int \frac{2}{x} dx$$

Hence

$$u_2 = 2 \ln(x)$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = -\frac{2x^2}{5} + 2x^2 \ln(x)$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= -\frac{2x^2}{5} + 2x^2 \ln(x) + \frac{c_1}{x^3} + c_2 x^2 \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = -\frac{2x^2}{5} + 2x^2 \ln(x) + \frac{c_1}{x^3} + c_2 x^2 \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 1$ and $x = 1$ in the above gives

$$1 = c_1 + c_2 - \frac{2}{5} \quad (1A)$$

Taking derivative of the solution gives

$$y' = \frac{6x}{5} + 4x \ln(x) - \frac{3c_1}{x^4} + 2c_2 x$$

substituting $y' = -6$ and $x = 1$ in the above gives

$$-6 = -3c_1 + 2c_2 + \frac{6}{5} \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$\begin{aligned} c_1 &= 2 \\ c_2 &= -\frac{3}{5} \end{aligned}$$

Substituting these values back in above solution results in

$$y = \frac{2x^5 \ln(x) - x^5 + 2}{x^3}$$

Summary

The solution(s) found are the following

$$y = \frac{2x^5 \ln(x) - x^5 + 2}{x^3} \tag{1}$$

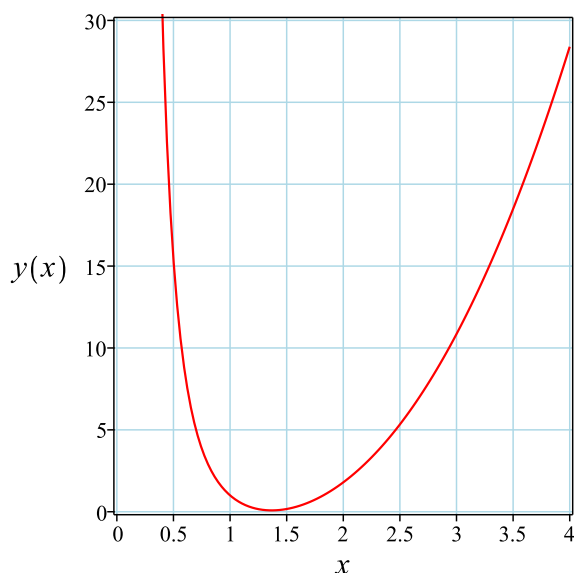


Figure 549: Solution plot

Verification of solutions

$$y = \frac{2x^5 \ln(x) - x^5 + 2}{x^3}$$

Verified OK.

13.25.3 Solving as second order change of variable on x method 2 ode

This is second order non-homogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$x^2 y'' + 2y'x - 6y = 0$$

In normal form the ode

$$x^2 y'' + 2y'x - 6y = 0 \quad (1)$$

Becomes

$$y'' + p(x) y' + q(x) y = 0 \quad (2)$$

Where

$$p(x) = \frac{2}{x}$$
$$q(x) = -\frac{6}{x^2}$$

Applying change of variables $\tau = g(x)$ to (2) gives

$$\frac{d^2}{d\tau^2} y(\tau) + p_1 \left(\frac{d}{d\tau} y(\tau) \right) + q_1 y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x) \tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $p_1 = 0$. Eq (4) simplifies to

$$\tau''(x) + p(x) \tau'(x) = 0$$

This ode is solved resulting in

$$\begin{aligned} \tau &= \int e^{-(\int p(x) dx)} dx \\ &= \int e^{-(\int \frac{2}{x} dx)} dx \\ &= \int e^{-2 \ln(x)} dx \\ &= \int \frac{1}{x^2} dx \\ &= -\frac{1}{x} \end{aligned} \quad (6)$$

Using (6) to evaluate q_1 from (5) gives

$$\begin{aligned}q_1(\tau) &= \frac{q(x)}{\tau'(x)^2} \\ &= \frac{-\frac{6}{x^2}}{\frac{1}{x^4}} \\ &= -6x^2\end{aligned}\tag{7}$$

Substituting the above in (3) and noting that now $p_1 = 0$ results in

$$\begin{aligned}\frac{d^2}{d\tau^2}y(\tau) + q_1y(\tau) &= 0 \\ \frac{d^2}{d\tau^2}y(\tau) - 6x^2y(\tau) &= 0\end{aligned}$$

But in terms of τ

$$-6x^2 = -\frac{6}{\tau^2}$$

Hence the above ode becomes

$$\frac{d^2}{d\tau^2}y(\tau) - \frac{6y(\tau)}{\tau^2} = 0$$

The above ode is now solved for $y(\tau)$. The ode can be written as

$$\left(\frac{d^2}{d\tau^2}y(\tau)\right)\tau^2 - 6y(\tau) = 0$$

Which shows it is a Euler ODE. This is Euler second order ODE. Let the solution be $y(\tau) = \tau^r$, then $y' = r\tau^{r-1}$ and $y'' = r(r-1)\tau^{r-2}$. Substituting these back into the given ODE gives

$$\tau^2(r(r-1))\tau^{r-2} + 0r\tau^{r-1} - 6\tau^r = 0$$

Simplifying gives

$$r(r-1)\tau^r + 0\tau^r - 6\tau^r = 0$$

Since $\tau^r \neq 0$ then dividing throughout by τ^r gives

$$r(r-1) + 0 - 6 = 0$$

Or

$$r^2 - r - 6 = 0\tag{1}$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = -2$$

$$r_2 = 3$$

Since the roots are real and distinct, then the general solution is

$$y(\tau) = c_1 y_1 + c_2 y_2$$

Where $y_1 = \tau^{r_1}$ and $y_2 = \tau^{r_2}$. Hence

$$y(\tau) = \frac{c_1}{\tau^2} + c_2 \tau^3$$

The above solution is now transformed back to y using (6) which results in

$$y = \frac{c_1 x^5 - c_2}{x^3}$$

Therefore the homogeneous solution y_h is

$$y_h = \frac{c_1 x^5 - c_2}{x^3}$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \frac{1}{x^3}$$

$$y_2 = x^2$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \tag{2}$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \tag{3}$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \frac{1}{x^3} & x^2 \\ \frac{d}{dx}\left(\frac{1}{x^3}\right) & \frac{d}{dx}(x^2) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \frac{1}{x^3} & x^2 \\ -\frac{3}{x^4} & 2x \end{vmatrix}$$

Therefore

$$W = \left(\frac{1}{x^3}\right)(2x) - (x^2)\left(-\frac{3}{x^4}\right)$$

Which simplifies to

$$W = \frac{5}{x^2}$$

Which simplifies to

$$W = \frac{5}{x^2}$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{10x^4}{5} dx$$

Which simplifies to

$$u_1 = - \int 2x^4 dx$$

Hence

$$u_1 = -\frac{2x^5}{5}$$

And Eq. (3) becomes

$$u_2 = \int \frac{10}{5} dx$$

Which simplifies to

$$u_2 = \int \frac{2}{x} dx$$

Hence

$$u_2 = 2 \ln(x)$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = -\frac{2x^2}{5} + 2x^2 \ln(x)$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(\frac{c_1 x^5 - c_2}{x^3} \right) + \left(-\frac{2x^2}{5} + 2x^2 \ln(x) \right) \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = \frac{c_1 x^5 - c_2}{x^3} - \frac{2x^2}{5} + 2x^2 \ln(x) \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 1$ and $x = 1$ in the above gives

$$1 = c_1 - c_2 - \frac{2}{5} \quad (1A)$$

Taking derivative of the solution gives

$$y' = 5c_1 x - \frac{3(c_1 x^5 - c_2)}{x^4} + \frac{6x}{5} + 4x \ln(x)$$

substituting $y' = -6$ and $x = 1$ in the above gives

$$-6 = 2c_1 + 3c_2 + \frac{6}{5} \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$\begin{aligned} c_1 &= -\frac{3}{5} \\ c_2 &= -2 \end{aligned}$$

Substituting these values back in above solution results in

$$y = \frac{2x^5 \ln(x) - x^5 + 2}{x^3}$$

Summary

The solution(s) found are the following

$$y = \frac{2x^5 \ln(x) - x^5 + 2}{x^3} \tag{1}$$

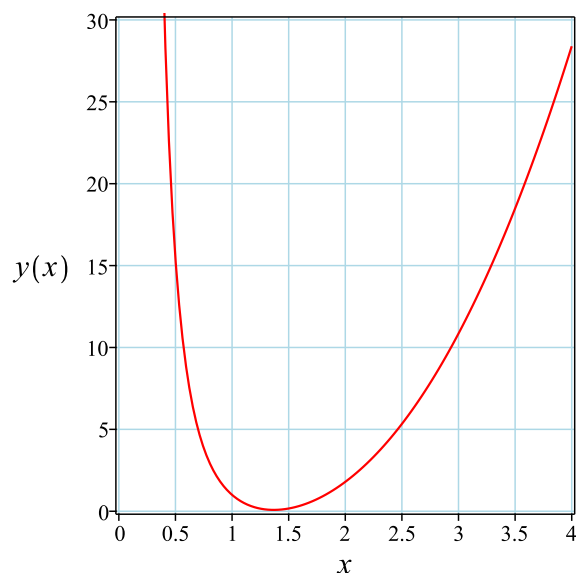


Figure 550: Solution plot

Verification of solutions

$$y = \frac{2x^5 \ln(x) - x^5 + 2}{x^3}$$

Verified OK.

13.25.4 Solving as second order change of variable on y method 2 ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = x^2$, $B = 2x$, $C = -6$, $f(x) = 10x^2$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. Solving for y_h from

$$x^2y'' + 2y'x - 6y = 0$$

In normal form the ode

$$x^2y'' + 2y'x - 6y = 0 \tag{1}$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \tag{2}$$

Where

$$p(x) = \frac{2}{x}$$

$$q(x) = -\frac{6}{x^2}$$

Applying change of variables on the dependent variable $y = v(x)x^n$ to (2) gives the following ode where the dependent variable is $v(x)$ and not y .

$$v''(x) + \left(\frac{2n}{x} + p\right)v'(x) + \left(\frac{n(n-1)}{x^2} + \frac{np}{x} + q\right)v(x) = 0 \tag{3}$$

Let the coefficient of $v(x)$ above be zero. Hence

$$\frac{n(n-1)}{x^2} + \frac{np}{x} + q = 0 \tag{4}$$

Substituting the earlier values found for $p(x)$ and $q(x)$ into (4) gives

$$\frac{n(n-1)}{x^2} + \frac{2n}{x^2} - \frac{6}{x^2} = 0 \tag{5}$$

Solving (5) for n gives

$$n = 2 \tag{6}$$

Substituting this value in (3) gives

$$v''(x) + \frac{6v'(x)}{x} = 0$$

$$v''(x) + \frac{6v'(x)}{x} = 0 \tag{7}$$

Using the substitution

$$u(x) = v'(x)$$

Then (7) becomes

$$u'(x) + \frac{6u(x)}{x} = 0 \quad (8)$$

The above is now solved for $u(x)$. In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= -\frac{6u}{x} \end{aligned}$$

Where $f(x) = -\frac{6}{x}$ and $g(u) = u$. Integrating both sides gives

$$\begin{aligned} \frac{1}{u} du &= -\frac{6}{x} dx \\ \int \frac{1}{u} du &= \int -\frac{6}{x} dx \\ \ln(u) &= -6 \ln(x) + c_1 \\ u &= e^{-6 \ln(x) + c_1} \\ &= \frac{c_1}{x^6} \end{aligned}$$

Now that $u(x)$ is known, then

$$\begin{aligned} v'(x) &= u(x) \\ v(x) &= \int u(x) dx + c_2 \\ &= -\frac{c_1}{5x^5} + c_2 \end{aligned}$$

Hence

$$\begin{aligned} y &= v(x) x^n \\ &= \left(-\frac{c_1}{5x^5} + c_2 \right) x^2 \\ &= \frac{5c_2x^5 - c_1}{5x^3} \end{aligned}$$

Now the particular solution to this ODE is found

$$x^2y'' + 2y'x - 6y = 10x^2$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1y_1 + u_2y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \frac{1}{x^3}$$

$$y_2 = x^2$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \frac{1}{x^3} & x^2 \\ \frac{d}{dx}\left(\frac{1}{x^3}\right) & \frac{d}{dx}(x^2) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \frac{1}{x^3} & x^2 \\ -\frac{3}{x^4} & 2x \end{vmatrix}$$

Therefore

$$W = \left(\frac{1}{x^3}\right)(2x) - (x^2)\left(-\frac{3}{x^4}\right)$$

Which simplifies to

$$W = \frac{5}{x^2}$$

Which simplifies to

$$W = \frac{5}{x^2}$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{10x^4}{5} dx$$

Which simplifies to

$$u_1 = - \int 2x^4 dx$$

Hence

$$u_1 = -\frac{2x^5}{5}$$

And Eq. (3) becomes

$$u_2 = \int \frac{10}{x} dx$$

Which simplifies to

$$u_2 = \int \frac{2}{x} dx$$

Hence

$$u_2 = 2 \ln(x)$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = -\frac{2x^2}{5} + 2x^2 \ln(x)$$

Therefore the general solution is

$$\begin{aligned}y &= y_h + y_p \\&= \left(\left(-\frac{c_1}{5x^5} + c_2 \right) x^2 \right) + \left(-\frac{2x^2}{5} + 2x^2 \ln(x) \right) \\&= -\frac{2x^2}{5} + 2x^2 \ln(x) + \left(-\frac{c_1}{5x^5} + c_2 \right) x^2\end{aligned}$$

Which simplifies to

$$y = \frac{10x^5 \ln(x) + 5c_2x^5 - 2x^5 - c_1}{5x^3}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = \frac{10x^5 \ln(x) + 5c_2x^5 - 2x^5 - c_1}{5x^3} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 1$ and $x = 1$ in the above gives

$$1 = -\frac{c_1}{5} + c_2 - \frac{2}{5} \quad (1A)$$

Taking derivative of the solution gives

$$y' = \frac{50x^4 \ln(x) + 25c_2x^4}{5x^3} - \frac{3(10x^5 \ln(x) + 5c_2x^5 - 2x^5 - c_1)}{5x^4}$$

substituting $y' = -6$ and $x = 1$ in the above gives

$$-6 = \frac{3c_1}{5} + 2c_2 + \frac{6}{5} \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$\begin{aligned}c_1 &= -10 \\c_2 &= -\frac{3}{5}\end{aligned}$$

Substituting these values back in above solution results in

$$y = \frac{2x^5 \ln(x) - x^5 + 2}{x^3}$$

Summary

The solution(s) found are the following

$$y = \frac{2x^5 \ln(x) - x^5 + 2}{x^3} \quad (1)$$

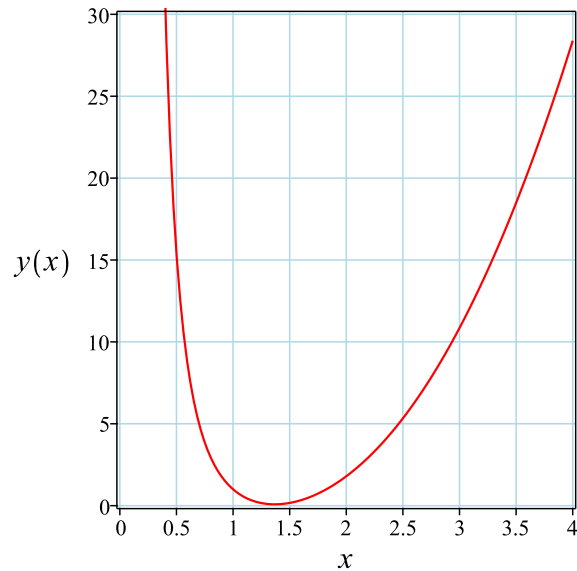


Figure 551: Solution plot

Verification of solutions

$$y = \frac{2x^5 \ln(x) - x^5 + 2}{x^3}$$

Verified OK.

13.25.5 Solving using Kovacic algorithm

Writing the ode as

$$x^2 y'' + 2y'x - 6y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= x^2 \\ B &= 2x \\ C &= -6 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \tag{4}$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \tag{5}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{6}{x^2} \tag{6}$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 6 \\ t &= x^2 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = \left(\frac{6}{x^2}\right) z(x) \tag{7}$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 505: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned}
 \mathcal{O}(\infty) &= \deg(t) - \deg(s) \\
 &= 2 - 0 \\
 &= 2
 \end{aligned}$$

The poles of r in eq. (7) and the order of each pole are determined by solving for the roots of $t = x^2$. There is a pole at $x = 0$ of order 2. Since there is no odd order pole larger than 2 and the order at ∞ is 2 then the necessary conditions for case one are met. Since there is a pole of order 2 then necessary conditions for case two are met. Since pole order is not larger than 2 and the order at ∞ is 2 then the necessary conditions for case three are met. Therefore

$$L = [1, 2, 4, 6, 12]$$

Attempting to find a solution using case $n = 1$.

Looking at poles of order 2. The partial fractions decomposition of r is

$$r = \frac{6}{x^2}$$

For the pole at $x = 0$ let b be the coefficient of $\frac{1}{x^2}$ in the partial fractions decomposition

of r given above. Therefore $b = 6$. Hence

$$\begin{aligned} [\sqrt{r}]_c &= 0 \\ \alpha_c^+ &= \frac{1}{2} + \sqrt{1 + 4b} = 3 \\ \alpha_c^- &= \frac{1}{2} - \sqrt{1 + 4b} = -2 \end{aligned}$$

Since the order of r at ∞ is 2 then $[\sqrt{r}]_\infty = 0$. Let b be the coefficient of $\frac{1}{x^2}$ in the Laurent series expansion of r at ∞ , which can be found by dividing the leading coefficient of s by the leading coefficient of t from

$$r = \frac{s}{t} = \frac{6}{x^2}$$

Since the $\gcd(s, t) = 1$. This gives $b = 6$. Hence

$$\begin{aligned} [\sqrt{r}]_\infty &= 0 \\ \alpha_\infty^+ &= \frac{1}{2} + \sqrt{1 + 4b} = 3 \\ \alpha_\infty^- &= \frac{1}{2} - \sqrt{1 + 4b} = -2 \end{aligned}$$

The following table summarizes the findings so far for poles and for the order of r at ∞ where r is

$$r = \frac{6}{x^2}$$

pole c location	pole order	$[\sqrt{r}]_c$	α_c^+	α_c^-
0	2	0	3	-2

Order of r at ∞	$[\sqrt{r}]_\infty$	α_∞^+	α_∞^-
2	0	3	-2

Now that the all $[\sqrt{r}]_c$ and its associated α_c^\pm have been determined for all the poles in the set Γ and $[\sqrt{r}]_\infty$ and its associated α_∞^\pm have also been found, the next step is to determine possible non negative integer d from these using

$$d = \alpha_\infty^{s(\infty)} - \sum_{c \in \Gamma} \alpha_c^{s(c)}$$

Where $s(c)$ is either $+$ or $-$ and $s(\infty)$ is the sign of α_∞^\pm . This is done by trial over all set of families $s = (s(c))_{c \in \Gamma \cup \infty}$ until such d is found to work in finding candidate ω .

Trying $\alpha_{\infty}^{-} = -2$ then

$$\begin{aligned} d &= \alpha_{\infty}^{-} - (\alpha_{c_1}^{-}) \\ &= -2 - (-2) \\ &= 0 \end{aligned}$$

Since d an integer and $d \geq 0$ then it can be used to find ω using

$$\omega = \sum_{c \in \Gamma} \left(s(c)[\sqrt{r}]_c + \frac{\alpha_c^{s(c)}}{x - c} \right) + s(\infty)[\sqrt{r}]_{\infty}$$

The above gives

$$\begin{aligned} \omega &= \left((-)[\sqrt{r}]_{c_1} + \frac{\alpha_{c_1}^{-}}{x - c_1} \right) + (-)[\sqrt{r}]_{\infty} \\ &= -\frac{2}{x} + (-)(0) \\ &= -\frac{2}{x} \\ &= -\frac{2}{x} \end{aligned}$$

Now that ω is determined, the next step is find a corresponding minimal polynomial $p(x)$ of degree $d = 0$ to solve the ode. The polynomial $p(x)$ needs to satisfy the equation

$$p'' + 2\omega p' + (\omega' + \omega^2 - r)p = 0 \quad (1A)$$

Let

$$p(x) = 1 \quad (2A)$$

Substituting the above in eq. (1A) gives

$$\begin{aligned} (0) + 2\left(-\frac{2}{x}\right)(0) + \left(\left(\frac{2}{x^2}\right) + \left(-\frac{2}{x}\right)^2 - \left(\frac{6}{x^2}\right)\right) &= 0 \\ 0 &= 0 \end{aligned}$$

The equation is satisfied since both sides are zero. Therefore the first solution to the ode $z'' = rz$ is

$$\begin{aligned} z_1(x) &= pe^{\int \omega dx} \\ &= e^{\int -\frac{2}{x} dx} \\ &= \frac{1}{x^2} \end{aligned}$$

The first solution to the original ode in y is found from

$$\begin{aligned}y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\&= z_1 e^{-\int \frac{1}{2} \frac{2x}{x^2} dx} \\&= z_1 e^{-\ln(x)} \\&= z_1 \left(\frac{1}{x} \right)\end{aligned}$$

Which simplifies to

$$y_1 = \frac{1}{x^3}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{2x}{x^2} dx}}{(y_1)^2} dx \\&= y_1 \int \frac{e^{-2\ln(x)}}{(y_1)^2} dx \\&= y_1 \left(\frac{x^5}{5} \right)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\&= c_1 \left(\frac{1}{x^3} \right) + c_2 \left(\frac{1}{x^3} \left(\frac{x^5}{5} \right) \right)\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$x^2y'' + 2y'x - 6y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = \frac{c_1}{x^3} + \frac{c_2x^2}{5}$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1y_1 + u_2y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \frac{1}{x^3}$$

$$y_2 = \frac{x^2}{5}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \frac{1}{x^3} & \frac{x^2}{5} \\ \frac{d}{dx} \left(\frac{1}{x^3} \right) & \frac{d}{dx} \left(\frac{x^2}{5} \right) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \frac{1}{x^3} & \frac{x^2}{5} \\ -\frac{3}{x^4} & \frac{2x}{5} \end{vmatrix}$$

Therefore

$$W = \left(\frac{1}{x^3}\right) \left(\frac{2x}{5}\right) - \left(\frac{x^2}{5}\right) \left(-\frac{3}{x^4}\right)$$

Which simplifies to

$$W = \frac{1}{x^2}$$

Which simplifies to

$$W = \frac{1}{x^2}$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{2x^4}{1} dx$$

Which simplifies to

$$u_1 = - \int 2x^4 dx$$

Hence

$$u_1 = -\frac{2x^5}{5}$$

And Eq. (3) becomes

$$u_2 = \int \frac{\frac{10}{x}}{1} dx$$

Which simplifies to

$$u_2 = \int \frac{10}{x} dx$$

Hence

$$u_2 = 10 \ln(x)$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = -\frac{2x^2}{5} + 2x^2 \ln(x)$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(\frac{c_1}{x^3} + \frac{c_2 x^2}{5} \right) + \left(-\frac{2x^2}{5} + 2x^2 \ln(x) \right) \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = \frac{c_1}{x^3} + \frac{c_2 x^2}{5} - \frac{2x^2}{5} + 2x^2 \ln(x) \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 1$ and $x = 1$ in the above gives

$$1 = c_1 + \frac{c_2}{5} - \frac{2}{5} \quad (1A)$$

Taking derivative of the solution gives

$$y' = -\frac{3c_1}{x^4} + \frac{2c_2 x}{5} + \frac{6x}{5} + 4x \ln(x)$$

substituting $y' = -6$ and $x = 1$ in the above gives

$$-6 = -3c_1 + \frac{2c_2}{5} + \frac{6}{5} \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$\begin{aligned} c_1 &= 2 \\ c_2 &= -3 \end{aligned}$$

Substituting these values back in above solution results in

$$y = \frac{2x^5 \ln(x) - x^5 + 2}{x^3}$$

Summary

The solution(s) found are the following

$$y = \frac{2x^5 \ln(x) - x^5 + 2}{x^3} \quad (1)$$

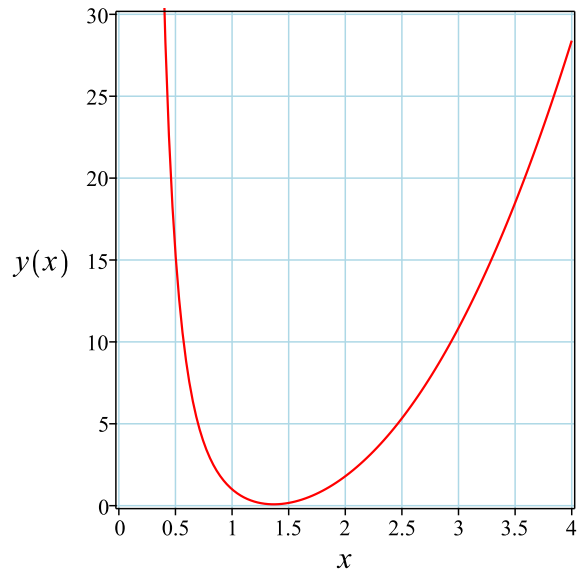


Figure 552: Solution plot

Verification of solutions

$$y = \frac{2x^5 \ln(x) - x^5 + 2}{x^3}$$

Verified OK.

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]  
trying a double symmetry of the form [xi=0, eta=F(x)]  
-> Try solving first the homogeneous part of the ODE  
    checking if the LODE has constant coefficients  
    checking if the LODE is of Euler type  
    <- LODE of Euler type successful  
<- solving first the homogeneous part of the ODE successful`
```

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 22

```
dsolve([x^2*diff(y(x),x$2)+2*x*diff(y(x),x)-6*y(x)=10*x^2,y(1) = 1, D(y)(1) = -6],y(x), sing
```

$$y(x) = \frac{2x^5 \ln(x) - x^5 + 2}{x^3}$$

✓ Solution by Mathematica

Time used: 0.018 (sec). Leaf size: 23

```
DSolve[{x^2*y'[x]+2*x*y'[x]-6*y[x]==10*x^2,{y[1]==1,y'[1]==-6}},y[x],x,IncludeSingularSolut
```

$$y(x) \rightarrow \frac{-x^5 + 2x^5 \log(x) + 2}{x^3}$$

13.26 problem 26

13.26.1 Existence and uniqueness analysis	3760
13.26.2 Solving as second order euler ode	3760
13.26.3 Solving as second order change of variable on x method 2 ode .	3765
13.26.4 Solving as second order change of variable on x method 1 ode .	3771
13.26.5 Solving as second order change of variable on y method 2 ode .	3777
13.26.6 Solving using Kovacic algorithm	3783

Internal problem ID [11880]

Internal file name [OUTPUT/11889_Saturday_April_13_2024_01_14_09_AM_33480691/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.5. The Cauchy-Euler Equation. Exercises page 169

Problem number: 26.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_euler_ode", "second_order_change_of_variable_on_x_method_1", "second_order_change_of_variable_on_x_method_2", "second_order_change_of_variable_on_y_method_2"

Maple gives the following as the ode type

```
[[_2nd_order, _with_linear_symmetries]]
```

$$x^2y'' - 5y'x + 8y = 2x^3$$

With initial conditions

$$[y(2) = 0, y'(2) = -8]$$

13.26.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$\begin{aligned}p(x) &= -\frac{5}{x} \\q(x) &= \frac{8}{x^2} \\F &= 2x\end{aligned}$$

Hence the ode is

$$y'' - \frac{5y'}{x} + \frac{8y}{x^2} = 2x$$

The domain of $p(x) = -\frac{5}{x}$ is

$$\{x < 0 \vee 0 < x\}$$

And the point $x_0 = 2$ is inside this domain. The domain of $q(x) = \frac{8}{x^2}$ is

$$\{x < 0 \vee 0 < x\}$$

And the point $x_0 = 2$ is also inside this domain. The domain of $F = 2x$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 2$ is also inside this domain. Hence solution exists and is unique.

13.26.2 Solving as second order euler ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = x^2, B = -5x, C = 8, f(x) = 2x^3$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. Solving for y_h from

$$x^2y'' - 5y'x + 8y = 0$$

This is Euler second order ODE. Let the solution be $y = x^r$, then $y' = rx^{r-1}$ and $y'' = r(r-1)x^{r-2}$. Substituting these back into the given ODE gives

$$x^2(r(r-1))x^{r-2} - 5rxr^{r-1} + 8x^r = 0$$

Simplifying gives

$$r(r-1)x^r - 5rx^r + 8x^r = 0$$

Since $x^r \neq 0$ then dividing throughout by x^r gives

$$r(r-1) - 5r + 8 = 0$$

Or

$$r^2 - 6r + 8 = 0 \tag{1}$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = 2$$

$$r_2 = 4$$

Since the roots are real and distinct, then the general solution is

$$y = c_1y_1 + c_2y_2$$

Where $y_1 = x^{r_1}$ and $y_2 = x^{r_2}$. Hence

$$y = c_2x^4 + c_1x^2$$

Next, we find the particular solution to the ODE

$$x^2y'' - 5y'x + 8y = 2x^3$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1y_1 + u_2y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = x^2$$

$$y_2 = x^4$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} x^2 & x^4 \\ \frac{d}{dx}(x^2) & \frac{d}{dx}(x^4) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} x^2 & x^4 \\ 2x & 4x^3 \end{vmatrix}$$

Therefore

$$W = (x^2)(4x^3) - (x^4)(2x)$$

Which simplifies to

$$W = 2x^5$$

Which simplifies to

$$W = 2x^5$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{2x^7}{2x^5} dx$$

Which simplifies to

$$u_1 = - \int 1 dx$$

Hence

$$u_1 = -x$$

And Eq. (3) becomes

$$u_2 = \int \frac{2x^5}{2x^7} dx$$

Which simplifies to

$$u_2 = \int \frac{1}{x^2} dx$$

Hence

$$u_2 = -\frac{1}{x}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = -2x^3$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= x^2(c_2x^2 + c_1 - 2x) \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = x^2(c_2x^2 + c_1 - 2x) \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 0$ and $x = 2$ in the above gives

$$0 = 16c_2 + 4c_1 - 16 \tag{1A}$$

Taking derivative of the solution gives

$$y' = 2x(c_2x^2 + c_1 - 2x) + x^2(2c_2x - 2)$$

substituting $y' = -8$ and $x = 2$ in the above gives

$$-8 = 32c_2 + 4c_1 - 24 \tag{2A}$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 4$$

$$c_2 = 0$$

Substituting these values back in above solution results in

$$y = -2(x - 2)x^2$$

Summary

The solution(s) found are the following

$$y = -2(x - 2)x^2 \tag{1}$$

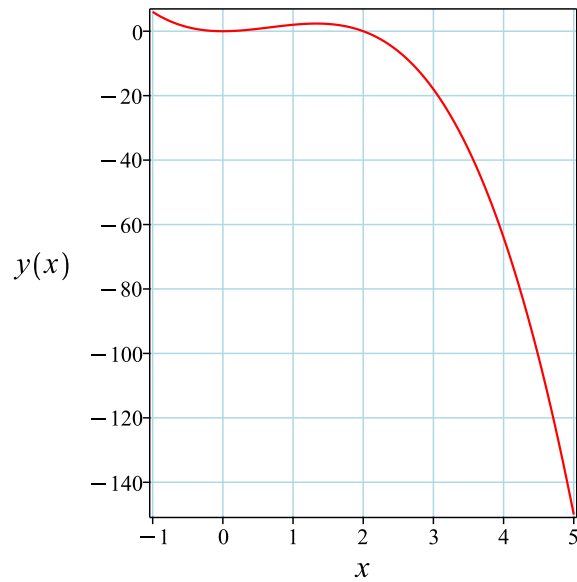


Figure 553: Solution plot

Verification of solutions

$$y = -2(x - 2)x^2$$

Verified OK.

13.26.3 Solving as second order change of variable on x method 2 ode

This is second order non-homogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$x^2y'' - 5y'x + 8y = 0$$

In normal form the ode

$$x^2y'' - 5y'x + 8y = 0 \tag{1}$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \tag{2}$$

Where

$$p(x) = -\frac{5}{x}$$
$$q(x) = \frac{8}{x^2}$$

Applying change of variables $\tau = g(x)$ to (2) gives

$$\frac{d^2}{d\tau^2}y(\tau) + p_1\left(\frac{d}{d\tau}y(\tau)\right) + q_1y(\tau) = 0 \tag{3}$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \tag{4}$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \tag{5}$$

Let $p_1 = 0$. Eq (4) simplifies to

$$\tau''(x) + p(x)\tau'(x) = 0$$

This ode is solved resulting in

$$\begin{aligned}
 \tau &= \int e^{-(\int p(x)dx)} dx \\
 &= \int e^{-(\int -\frac{5}{x} dx)} dx \\
 &= \int e^{5 \ln(x)} dx \\
 &= \int x^5 dx \\
 &= \frac{x^6}{6}
 \end{aligned} \tag{6}$$

Using (6) to evaluate q_1 from (5) gives

$$\begin{aligned}
 q_1(\tau) &= \frac{q(x)}{\tau'(x)^2} \\
 &= \frac{\frac{8}{x^2}}{x^{10}} \\
 &= \frac{8}{x^{12}}
 \end{aligned} \tag{7}$$

Substituting the above in (3) and noting that now $p_1 = 0$ results in

$$\begin{aligned}
 \frac{d^2}{d\tau^2}y(\tau) + q_1y(\tau) &= 0 \\
 \frac{d^2}{d\tau^2}y(\tau) + \frac{8y(\tau)}{x^{12}} &= 0
 \end{aligned}$$

But in terms of τ

$$\frac{8}{x^{12}} = \frac{2}{9\tau^2}$$

Hence the above ode becomes

$$\frac{d^2}{d\tau^2}y(\tau) + \frac{2y(\tau)}{9\tau^2} = 0$$

The above ode is now solved for $y(\tau)$. The ode can be written as

$$9 \left(\frac{d^2}{d\tau^2}y(\tau) \right) \tau^2 + 2y(\tau) = 0$$

Which shows it is a Euler ODE. This is Euler second order ODE. Let the solution be $y(\tau) = \tau^r$, then $y' = r\tau^{r-1}$ and $y'' = r(r-1)\tau^{r-2}$. Substituting these back into the given ODE gives

$$9\tau^2(r(r-1))\tau^{r-2} + 0r\tau^{r-1} + 2\tau^r = 0$$

Simplifying gives

$$9r(r - 1)\tau^r + 0\tau^r + 2\tau^r = 0$$

Since $\tau^r \neq 0$ then dividing throughout by τ^r gives

$$9r(r - 1) + 0 + 2 = 0$$

Or

$$9r^2 - 9r + 2 = 0 \tag{1}$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = \frac{1}{3}$$
$$r_2 = \frac{2}{3}$$

Since the roots are real and distinct, then the general solution is

$$y(\tau) = c_1y_1 + c_2y_2$$

Where $y_1 = \tau^{r_1}$ and $y_2 = \tau^{r_2}$. Hence

$$y(\tau) = c_1\tau^{\frac{1}{3}} + c_2\tau^{\frac{2}{3}}$$

The above solution is now transformed back to y using (6) which results in

$$y = \frac{c_1 6^{\frac{2}{3}} (x^6)^{\frac{1}{3}}}{6} + \frac{c_2 6^{\frac{1}{3}} (x^6)^{\frac{2}{3}}}{6}$$

Therefore the homogeneous solution y_h is

$$y_h = \frac{c_1 6^{\frac{2}{3}} (x^6)^{\frac{1}{3}}}{6} + \frac{c_2 6^{\frac{1}{3}} (x^6)^{\frac{2}{3}}}{6}$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1y_1 + u_2y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = (x^6)^{\frac{1}{3}}$$

$$y_2 = (x^6)^{\frac{2}{3}}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} (x^6)^{\frac{1}{3}} & (x^6)^{\frac{2}{3}} \\ \frac{d}{dx} \left((x^6)^{\frac{1}{3}} \right) & \frac{d}{dx} \left((x^6)^{\frac{2}{3}} \right) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} (x^6)^{\frac{1}{3}} & (x^6)^{\frac{2}{3}} \\ \frac{2x^5}{(x^6)^{\frac{2}{3}}} & \frac{4x^5}{(x^6)^{\frac{1}{3}}} \end{vmatrix}$$

Therefore

$$W = \left((x^6)^{\frac{1}{3}} \right) \left(\frac{4x^5}{(x^6)^{\frac{1}{3}}} \right) - \left((x^6)^{\frac{2}{3}} \right) \left(\frac{2x^5}{(x^6)^{\frac{2}{3}}} \right)$$

Which simplifies to

$$W = 2x^5$$

Which simplifies to

$$W = 2x^5$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{2(x^6)^{\frac{2}{3}} x^3}{2x^7} dx$$

Which simplifies to

$$u_1 = - \int \frac{(x^6)^{\frac{2}{3}}}{x^4} dx$$

Hence

$$u_1 = - \frac{(x^6)^{\frac{2}{3}}}{x^3}$$

And Eq. (3) becomes

$$u_2 = \int \frac{2(x^6)^{\frac{1}{3}} x^3}{2x^7} dx$$

Which simplifies to

$$u_2 = \int \frac{(x^6)^{\frac{1}{3}}}{x^4} dx$$

Hence

$$u_2 = - \frac{(x^6)^{\frac{1}{3}}}{x^3}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = -2x^3$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(\frac{c_1 6^{\frac{2}{3}} (x^6)^{\frac{1}{3}}}{6} + \frac{c_2 6^{\frac{1}{3}} (x^6)^{\frac{2}{3}}}{6} \right) + (-2x^3) \end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = \frac{c_1 6^{\frac{2}{3}} (x^6)^{\frac{1}{3}}}{6} + \frac{c_2 6^{\frac{1}{3}} (x^6)^{\frac{2}{3}}}{6} - 2x^3 \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 0$ and $x = 2$ in the above gives

$$0 = \frac{2c_1 6^{\frac{2}{3}}}{3} + \frac{8c_2 6^{\frac{1}{3}}}{3} - 16 \quad (1A)$$

Taking derivative of the solution gives

$$y' = \frac{c_1 6^{\frac{2}{3}} x^5}{3 (x^6)^{\frac{2}{3}}} + \frac{2c_2 6^{\frac{1}{3}} x^5}{3 (x^6)^{\frac{1}{3}}} - 6x^2$$

substituting $y' = -8$ and $x = 2$ in the above gives

$$-8 = \frac{2c_1 6^{\frac{2}{3}}}{3} + \frac{16c_2 6^{\frac{1}{3}}}{3} - 24 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 4 6^{\frac{1}{3}}$$
$$c_2 = 0$$

Substituting these values back in above solution results in

$$y = 4(x^6)^{\frac{1}{3}} - 2x^3$$

Summary

The solution(s) found are the following

$$y = 4(x^6)^{\frac{1}{3}} - 2x^3 \quad (1)$$

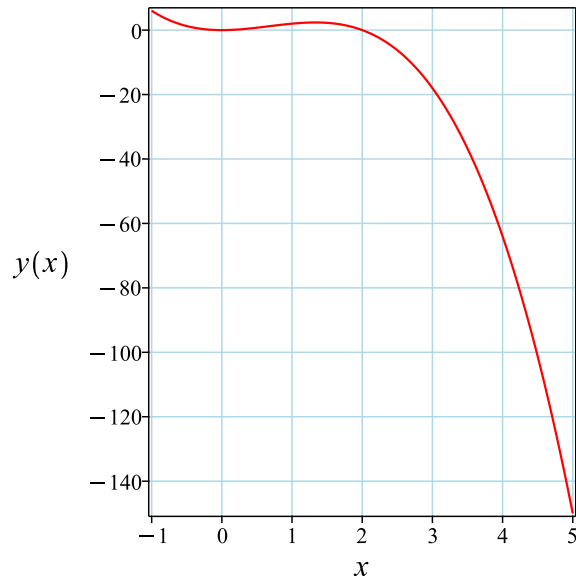


Figure 554: Solution plot

Verification of solutions

$$y = 4(x^6)^{\frac{1}{3}} - 2x^3$$

Verified OK.

13.26.4 Solving as second order change of variable on x method 1 ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = x^2$, $B = -5x$, $C = 8$, $f(x) = 2x^3$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. Solving for y_h from

$$x^2y'' - 5y'x + 8y = 0$$

In normal form the ode

$$x^2y'' - 5y'x + 8y = 0 \tag{1}$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \quad (2)$$

Where

$$p(x) = -\frac{5}{x}$$
$$q(x) = \frac{8}{x^2}$$

Applying change of variables $\tau = g(x)$ to (2) results

$$\frac{d^2}{d\tau^2}y(\tau) + p_1\left(\frac{d}{d\tau}y(\tau)\right) + q_1y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $q_1 = c^2$ where c is some constant. Therefore from (5)

$$\tau' = \frac{1}{c}\sqrt{q}$$
$$= \frac{2\sqrt{2}\sqrt{\frac{1}{x^2}}}{c} \quad (6)$$
$$\tau'' = -\frac{2\sqrt{2}}{c\sqrt{\frac{1}{x^2}}x^3}$$

Substituting the above into (4) results in

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2}$$
$$= \frac{-\frac{2\sqrt{2}}{c\sqrt{\frac{1}{x^2}}x^3} - \frac{5}{x}\frac{2\sqrt{2}\sqrt{\frac{1}{x^2}}}{c}}{\left(\frac{2\sqrt{2}\sqrt{\frac{1}{x^2}}}{c}\right)^2}$$
$$= -\frac{3c\sqrt{2}}{2}$$

Therefore ode (3) now becomes

$$\begin{aligned} y(\tau)'' + p_1 y(\tau)' + q_1 y(\tau) &= 0 \\ \frac{d^2}{d\tau^2} y(\tau) - \frac{3c\sqrt{2}}{2} \left(\frac{d}{d\tau} y(\tau) \right) + c^2 y(\tau) &= 0 \end{aligned} \quad (7)$$

The above ode is now solved for $y(\tau)$. Since the ode is now constant coefficients, it can be easily solved to give

$$y(\tau) = e^{\frac{3\sqrt{2}c\tau}{4}} \left(c_1 \cosh \left(\frac{\sqrt{2}c\tau}{4} \right) + ic_2 \sinh \left(\frac{\sqrt{2}c\tau}{4} \right) \right)$$

Now from (6)

$$\begin{aligned} \tau &= \int \frac{1}{c} \sqrt{q} dx \\ &= \frac{\int 2\sqrt{2} \sqrt{\frac{1}{x^2}} dx}{c} \\ &= \frac{2\sqrt{2} \sqrt{\frac{1}{x^2}} x \ln(x)}{c} \end{aligned}$$

Substituting the above into the solution obtained gives

$$y = \frac{x^2((ic_2 + c_1)x^2 - ic_2 + c_1)}{2}$$

Now the particular solution to this ODE is found

$$x^2 y'' - 5y'x + 8y = 2x^3$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$\begin{aligned} y_1 &= (x^6)^{\frac{1}{3}} \\ y_2 &= (x^6)^{\frac{2}{3}} \end{aligned}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} (x^6)^{\frac{1}{3}} & (x^6)^{\frac{2}{3}} \\ \frac{d}{dx} \left((x^6)^{\frac{1}{3}} \right) & \frac{d}{dx} \left((x^6)^{\frac{2}{3}} \right) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} (x^6)^{\frac{1}{3}} & (x^6)^{\frac{2}{3}} \\ \frac{2x^5}{(x^6)^{\frac{2}{3}}} & \frac{4x^5}{(x^6)^{\frac{1}{3}}} \end{vmatrix}$$

Therefore

$$W = \left((x^6)^{\frac{1}{3}} \right) \left(\frac{4x^5}{(x^6)^{\frac{1}{3}}} \right) - \left((x^6)^{\frac{2}{3}} \right) \left(\frac{2x^5}{(x^6)^{\frac{2}{3}}} \right)$$

Which simplifies to

$$W = 2x^5$$

Which simplifies to

$$W = 2x^5$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{2(x^6)^{\frac{2}{3}} x^3}{2x^7} dx$$

Which simplifies to

$$u_1 = - \int \frac{(x^6)^{\frac{2}{3}}}{x^4} dx$$

Hence

$$u_1 = -\frac{(x^6)^{\frac{2}{3}}}{x^3}$$

And Eq. (3) becomes

$$u_2 = \int \frac{2(x^6)^{\frac{1}{3}} x^3}{2x^7} dx$$

Which simplifies to

$$u_2 = \int \frac{(x^6)^{\frac{1}{3}}}{x^4} dx$$

Hence

$$u_2 = -\frac{(x^6)^{\frac{1}{3}}}{x^3}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = -2x^3$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(\frac{x^2((ic_2 + c_1)x^2 - ic_2 + c_1)}{2} \right) + (-2x^3) \\ &= -2x^3 + \frac{x^2((ic_2 + c_1)x^2 - ic_2 + c_1)}{2} \end{aligned}$$

Which simplifies to

$$y = \frac{x^2((ic_2 + c_1)x^2 - 4x - ic_2 + c_1)}{2}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = \frac{x^2((ic_2 + c_1)x^2 - 4x - ic_2 + c_1)}{2} \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 0$ and $x = 2$ in the above gives

$$0 = 6ic_2 + 10c_1 - 16 \quad (1A)$$

Taking derivative of the solution gives

$$y' = x((ic_2 + c_1)x^2 - 4x - ic_2 + c_1) + \frac{x^2(2(ic_2 + c_1)x - 4)}{2}$$

substituting $y' = -8$ and $x = 2$ in the above gives

$$-8 = 14ic_2 + 18c_1 - 24 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 4$$

$$c_2 = 4i$$

Substituting these values back in above solution results in

$$y = -2x^3 + 4x^2$$

Summary

The solution(s) found are the following

$$y = -2x^3 + 4x^2 \quad (1)$$

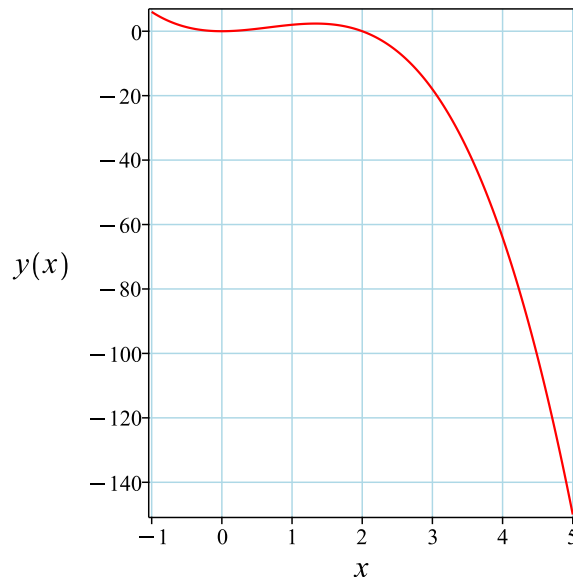


Figure 555: Solution plot

Verification of solutions

$$y = -2x^3 + 4x^2$$

Verified OK.

13.26.5 Solving as second order change of variable on y method 2 ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = x^2$, $B = -5x$, $C = 8$, $f(x) = 2x^3$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. Solving for y_h from

$$x^2y'' - 5y'x + 8y = 0$$

In normal form the ode

$$x^2y'' - 5y'x + 8y = 0 \tag{1}$$

Becomes

$$y'' + p(x)y' + q(x)y = 0 \tag{2}$$

Where

$$p(x) = -\frac{5}{x}$$
$$q(x) = \frac{8}{x^2}$$

Applying change of variables on the dependent variable $y = v(x)x^n$ to (2) gives the following ode where the dependent variable is $v(x)$ and not y .

$$v''(x) + \left(\frac{2n}{x} + p\right)v'(x) + \left(\frac{n(n-1)}{x^2} + \frac{np}{x} + q\right)v(x) = 0 \tag{3}$$

Let the coefficient of $v(x)$ above be zero. Hence

$$\frac{n(n-1)}{x^2} + \frac{np}{x} + q = 0 \tag{4}$$

Substituting the earlier values found for $p(x)$ and $q(x)$ into (4) gives

$$\frac{n(n-1)}{x^2} - \frac{5n}{x^2} + \frac{8}{x^2} = 0 \quad (5)$$

Solving (5) for n gives

$$n = 4 \quad (6)$$

Substituting this value in (3) gives

$$\begin{aligned} v''(x) + \frac{3v'(x)}{x} &= 0 \\ v''(x) + \frac{3v'(x)}{x} &= 0 \end{aligned} \quad (7)$$

Using the substitution

$$u(x) = v'(x)$$

Then (7) becomes

$$u'(x) + \frac{3u(x)}{x} = 0 \quad (8)$$

The above is now solved for $u(x)$. In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= -\frac{3u}{x} \end{aligned}$$

Where $f(x) = -\frac{3}{x}$ and $g(u) = u$. Integrating both sides gives

$$\begin{aligned} \frac{1}{u} du &= -\frac{3}{x} dx \\ \int \frac{1}{u} du &= \int -\frac{3}{x} dx \\ \ln(u) &= -3 \ln(x) + c_1 \\ u &= e^{-3 \ln(x) + c_1} \\ &= \frac{c_1}{x^3} \end{aligned}$$

Now that $u(x)$ is known, then

$$\begin{aligned}v'(x) &= u(x) \\v(x) &= \int u(x) dx + c_2 \\&= -\frac{c_1}{2x^2} + c_2\end{aligned}$$

Hence

$$\begin{aligned}y &= v(x) x^n \\&= \left(-\frac{c_1}{2x^2} + c_2\right) x^4 \\&= c_2 x^4 - \frac{1}{2} c_1 x^2\end{aligned}$$

Now the particular solution to this ODE is found

$$x^2 y'' - 5y'x + 8y = 2x^3$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \tag{1}$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$\begin{aligned}y_1 &= x^2 \\y_2 &= x^4\end{aligned}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \tag{2}$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \tag{3}$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} x^2 & x^4 \\ \frac{d}{dx}(x^2) & \frac{d}{dx}(x^4) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} x^2 & x^4 \\ 2x & 4x^3 \end{vmatrix}$$

Therefore

$$W = (x^2)(4x^3) - (x^4)(2x)$$

Which simplifies to

$$W = 2x^5$$

Which simplifies to

$$W = 2x^5$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{2x^7}{2x^7} dx$$

Which simplifies to

$$u_1 = - \int 1 dx$$

Hence

$$u_1 = -x$$

And Eq. (3) becomes

$$u_2 = \int \frac{2x^5}{2x^7} dx$$

Which simplifies to

$$u_2 = \int \frac{1}{x^2} dx$$

Hence

$$u_2 = -\frac{1}{x}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = -2x^3$$

Therefore the general solution is

$$\begin{aligned} y &= y_h + y_p \\ &= \left(\left(-\frac{c_1}{2x^2} + c_2 \right) x^4 \right) + (-2x^3) \\ &= -2x^3 + \left(-\frac{c_1}{2x^2} + c_2 \right) x^4 \end{aligned}$$

Which simplifies to

$$y = -\frac{x^2(-2c_2x^2 + c_1 + 4x)}{2}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = -\frac{x^2(-2c_2x^2 + c_1 + 4x)}{2} \tag{1}$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 0$ and $x = 2$ in the above gives

$$0 = 16c_2 - 2c_1 - 16 \tag{1A}$$

Taking derivative of the solution gives

$$y' = -x(-2c_2x^2 + c_1 + 4x) - \frac{x^2(-4c_2x + 4)}{2}$$

substituting $y' = -8$ and $x = 2$ in the above gives

$$-8 = 32c_2 - 2c_1 - 24 \tag{2A}$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = -8$$

$$c_2 = 0$$

Substituting these values back in above solution results in

$$y = -2(x - 2)x^2$$

Summary

The solution(s) found are the following

$$y = -2(x - 2)x^2 \tag{1}$$

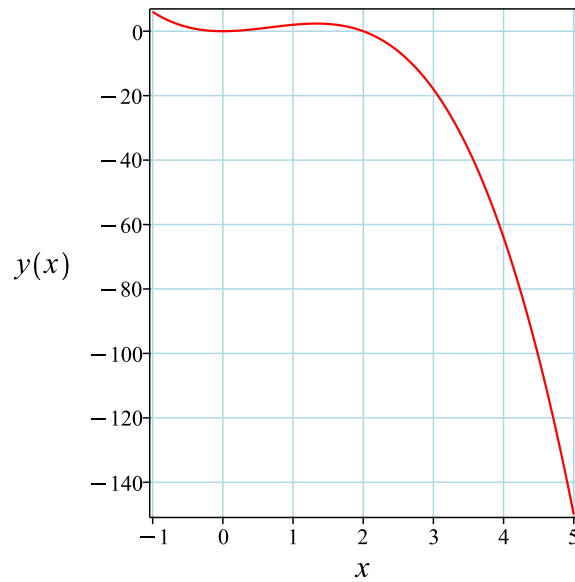


Figure 556: Solution plot

Verification of solutions

$$y = -2(x - 2)x^2$$

Verified OK.

13.26.6 Solving using Kovacic algorithm

Writing the ode as

$$x^2y'' - 5y'x + 8y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned} A &= x^2 \\ B &= -5x \\ C &= 8 \end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{3}{4x^2} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 3 \\ t &= 4x^2 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = \left(\frac{3}{4x^2} \right) z(x) \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 506: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 2 - 0 \\ &= 2 \end{aligned}$$

The poles of r in eq. (7) and the order of each pole are determined by solving for the roots of $t = 4x^2$. There is a pole at $x = 0$ of order 2. Since there is no odd order pole larger than 2 and the order at ∞ is 2 then the necessary conditions for case one are met. Since there is a pole of order 2 then necessary conditions for case two are met. Since pole order is not larger than 2 and the order at ∞ is 2 then the necessary conditions for case three are met. Therefore

$$L = [1, 2, 4, 6, 12]$$

Attempting to find a solution using case $n = 1$.

Looking at poles of order 2. The partial fractions decomposition of r is

$$r = \frac{3}{4x^2}$$

For the pole at $x = 0$ let b be the coefficient of $\frac{1}{x^2}$ in the partial fractions decomposition of r given above. Therefore $b = \frac{3}{4}$. Hence

$$\begin{aligned} [\sqrt{r}]_c &= 0 \\ \alpha_c^+ &= \frac{1}{2} + \sqrt{1 + 4b} = \frac{3}{2} \\ \alpha_c^- &= \frac{1}{2} - \sqrt{1 + 4b} = -\frac{1}{2} \end{aligned}$$

Since the order of r at ∞ is 2 then $[\sqrt{r}]_\infty = 0$. Let b be the coefficient of $\frac{1}{x^2}$ in the Laurent series expansion of r at ∞ , which can be found by dividing the leading coefficient of s by the leading coefficient of t from

$$r = \frac{s}{t} = \frac{3}{4x^2}$$

Since the $\gcd(s, t) = 1$. This gives $b = \frac{3}{4}$. Hence

$$\begin{aligned} [\sqrt{r}]_\infty &= 0 \\ \alpha_\infty^+ &= \frac{1}{2} + \sqrt{1 + 4b} = \frac{3}{2} \\ \alpha_\infty^- &= \frac{1}{2} - \sqrt{1 + 4b} = -\frac{1}{2} \end{aligned}$$

The following table summarizes the findings so far for poles and for the order of r at ∞ where r is

$$r = \frac{3}{4x^2}$$

pole c location	pole order	$[\sqrt{r}]_c$	α_c^+	α_c^-
0	2	0	$\frac{3}{2}$	$-\frac{1}{2}$

Order of r at ∞	$[\sqrt{r}]_\infty$	α_∞^+	α_∞^-
2	0	$\frac{3}{2}$	$-\frac{1}{2}$

Now that the all $[\sqrt{r}]_c$ and its associated α_c^\pm have been determined for all the poles in the set Γ and $[\sqrt{r}]_\infty$ and its associated α_∞^\pm have also been found, the next step is to determine possible non negative integer d from these using

$$d = \alpha_\infty^{s(\infty)} - \sum_{c \in \Gamma} \alpha_c^{s(c)}$$

Where $s(c)$ is either $+$ or $-$ and $s(\infty)$ is the sign of α_∞^\pm . This is done by trial over all set of families $s = (s(c))_{c \in \Gamma \cup \infty}$ until such d is found to work in finding candidate ω .

Trying $\alpha_{\infty}^{-} = -\frac{1}{2}$ then

$$\begin{aligned} d &= \alpha_{\infty}^{-} - (\alpha_{c_1}^{-}) \\ &= -\frac{1}{2} - \left(-\frac{1}{2}\right) \\ &= 0 \end{aligned}$$

Since d an integer and $d \geq 0$ then it can be used to find ω using

$$\omega = \sum_{c \in \Gamma} \left(s(c)[\sqrt{r}]_c + \frac{\alpha_c^{s(c)}}{x - c} \right) + s(\infty)[\sqrt{r}]_{\infty}$$

The above gives

$$\begin{aligned} \omega &= \left((-)[\sqrt{r}]_{c_1} + \frac{\alpha_{c_1}^{-}}{x - c_1} \right) + (-)[\sqrt{r}]_{\infty} \\ &= -\frac{1}{2x} + (-)(0) \\ &= -\frac{1}{2x} \\ &= -\frac{1}{2x} \end{aligned}$$

Now that ω is determined, the next step is find a corresponding minimal polynomial $p(x)$ of degree $d = 0$ to solve the ode. The polynomial $p(x)$ needs to satisfy the equation

$$p'' + 2\omega p' + (\omega' + \omega^2 - r)p = 0 \quad (1A)$$

Let

$$p(x) = 1 \quad (2A)$$

Substituting the above in eq. (1A) gives

$$\begin{aligned} (0) + 2\left(-\frac{1}{2x}\right)(0) + \left(\left(\frac{1}{2x^2}\right) + \left(-\frac{1}{2x}\right)^2 - \left(\frac{3}{4x^2}\right)\right) &= 0 \\ 0 &= 0 \end{aligned}$$

The equation is satisfied since both sides are zero. Therefore the first solution to the ode $z'' = rz$ is

$$\begin{aligned} z_1(x) &= pe^{\int \omega dx} \\ &= e^{\int -\frac{1}{2x} dx} \\ &= \frac{1}{\sqrt{x}} \end{aligned}$$

The first solution to the original ode in y is found from

$$\begin{aligned}y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\&= z_1 e^{-\int \frac{1}{2} \frac{-5x}{x^2} dx} \\&= z_1 e^{\frac{5 \ln(x)}{2}} \\&= z_1 \left(x^{\frac{5}{2}} \right)\end{aligned}$$

Which simplifies to

$$y_1 = x^2$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{-5x}{x^2} dx}}{(y_1)^2} dx \\&= y_1 \int \frac{e^{5 \ln(x)}}{(y_1)^2} dx \\&= y_1 \left(\frac{x^2}{2} \right)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\&= c_1 (x^2) + c_2 \left(x^2 \left(\frac{x^2}{2} \right) \right)\end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$.
 y_h is the solution to

$$x^2 y'' - 5y'x + 8y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = c_1x^2 + \frac{1}{2}c_2x^4$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1y_1 + u_2y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = x^2$$
$$y_2 = \frac{x^4}{2}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} x^2 & \frac{x^4}{2} \\ \frac{d}{dx}(x^2) & \frac{d}{dx}\left(\frac{x^4}{2}\right) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} x^2 & \frac{x^4}{2} \\ 2x & 2x^3 \end{vmatrix}$$

Therefore

$$W = (x^2)(2x^3) - \left(\frac{x^4}{2}\right)(2x)$$

Which simplifies to

$$W = x^5$$

Which simplifies to

$$W = x^5$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{x^7}{x^7} dx$$

Which simplifies to

$$u_1 = - \int 1 dx$$

Hence

$$u_1 = -x$$

And Eq. (3) becomes

$$u_2 = \int \frac{2x^5}{x^7} dx$$

Which simplifies to

$$u_2 = \int \frac{2}{x^2} dx$$

Hence

$$u_2 = -\frac{2}{x}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = -2x^3$$

Therefore the general solution is

$$\begin{aligned}y &= y_h + y_p \\ &= \left(c_1 x^2 + \frac{1}{2} c_2 x^4 \right) + (-2x^3)\end{aligned}$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = c_1 x^2 + \frac{1}{2} c_2 x^4 - 2x^3 \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = 0$ and $x = 2$ in the above gives

$$0 = 4c_1 + 8c_2 - 16 \quad (1A)$$

Taking derivative of the solution gives

$$y' = 2c_2 x^3 + 2c_1 x - 6x^2$$

substituting $y' = -8$ and $x = 2$ in the above gives

$$-8 = 16c_2 + 4c_1 - 24 \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = 4$$

$$c_2 = 0$$

Substituting these values back in above solution results in

$$y = -2x^3 + 4x^2$$

Summary

The solution(s) found are the following

$$y = -2x^3 + 4x^2 \quad (1)$$

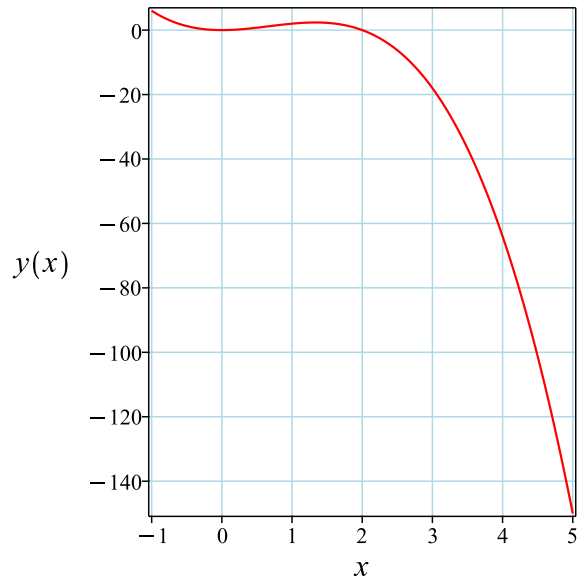


Figure 557: Solution plot

Verification of solutions

$$y = -2x^3 + 4x^2$$

Verified OK.

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
trying high order exact linear fully integrable
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]
trying a double symmetry of the form [xi=0, eta=F(x)]
-> Try solving first the homogeneous part of the ODE
    checking if the LODE has constant coefficients
    checking if the LODE is of Euler type
    <- LODE of Euler type successful
<- solving first the homogeneous part of the ODE successful`

```


✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 15

```
dsolve([x^2*diff(y(x),x$2)-5*x*diff(y(x),x)+8*y(x)=2*x^3,y(2) = 0, D(y)(2) = -8],y(x), sings
```

$$y(x) = -2x^3 + 4x^2$$

✓ Solution by Mathematica

Time used: 0.013 (sec). Leaf size: 13

```
DSolve[{x^2*y''[x]-5*x*y'[x]+8*y[x]==2*x^3,{y[2]==0,y'[2]==-8}},y[x],x,IncludeSingularSoluti
```

$$y(x) \rightarrow -2(x - 2)x^2$$

13.27 problem 27

13.27.1 Existence and uniqueness analysis	3793
13.27.2 Solving as second order euler ode ode	3794
13.27.3 Solving using Kovacic algorithm	3799

Internal problem ID [11881]

Internal file name [OUTPUT/11890_Saturday_April_13_2024_01_14_12_AM_12077989/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.5. The Cauchy-Euler Equation. Exercises page 169

Problem number: 27.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_euler_ode"

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$x^2y'' - 6y = \ln(x)$$

With initial conditions

$$\left[y(1) = \frac{1}{6}, y'(1) = -\frac{1}{6} \right]$$

13.27.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$\begin{aligned} p(x) &= 0 \\ q(x) &= -\frac{6}{x^2} \\ F &= \frac{\ln(x)}{x^2} \end{aligned}$$

Hence the ode is

$$y'' - \frac{6y}{x^2} = \frac{\ln(x)}{x^2}$$

The domain of $p(x) = 0$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 1$ is inside this domain. The domain of $q(x) = -\frac{6}{x^2}$ is

$$\{x < 0 \vee 0 < x\}$$

And the point $x_0 = 1$ is also inside this domain. The domain of $F = \frac{\ln(x)}{x^2}$ is

$$\{0 < x\}$$

And the point $x_0 = 1$ is also inside this domain. Hence solution exists and is unique.

13.27.2 Solving as second order euler ode

This is second order non-homogeneous ODE. In standard form the ODE is

$$Ay''(x) + By'(x) + Cy(x) = f(x)$$

Where $A = x^2, B = 0, C = -6, f(x) = \ln(x)$. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the non-homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. Solving for y_h from

$$x^2y'' - 6y = 0$$

This is Euler second order ODE. Let the solution be $y = x^r$, then $y' = rx^{r-1}$ and $y'' = r(r-1)x^{r-2}$. Substituting these back into the given ODE gives

$$x^2(r(r-1))x^{r-2} + 0rx^{r-1} - 6x^r = 0$$

Simplifying gives

$$r(r-1)x^r + 0x^r - 6x^r = 0$$

Since $x^r \neq 0$ then dividing throughout by x^r gives

$$r(r-1) + 0 - 6 = 0$$

Or

$$r^2 - r - 6 = 0 \quad (1)$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = -2$$

$$r_2 = 3$$

Since the roots are real and distinct, then the general solution is

$$y = c_1 y_1 + c_2 y_2$$

Where $y_1 = x^{r_1}$ and $y_2 = x^{r_2}$. Hence

$$y = \frac{c_1}{x^2} + c_2 x^3$$

Next, we find the particular solution to the ODE

$$x^2 y'' - 6y = \ln(x)$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1 y_1 + u_2 y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \frac{1}{x^2}$$

$$y_2 = x^3$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2 f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1 f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \frac{1}{x^2} & x^3 \\ \frac{d}{dx}\left(\frac{1}{x^2}\right) & \frac{d}{dx}(x^3) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \frac{1}{x^2} & x^3 \\ -\frac{2}{x^3} & 3x^2 \end{vmatrix}$$

Therefore

$$W = \left(\frac{1}{x^2}\right)(3x^2) - (x^3)\left(-\frac{2}{x^3}\right)$$

Which simplifies to

$$W = 5$$

Which simplifies to

$$W = 5$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{x^3 \ln(x)}{5x^2} dx$$

Which simplifies to

$$u_1 = - \int \frac{x \ln(x)}{5} dx$$

Hence

$$u_1 = -\frac{x^2 \ln(x)}{10} + \frac{x^2}{20}$$

And Eq. (3) becomes

$$u_2 = \int \frac{\ln(x)}{5x^2} dx$$

Which simplifies to

$$u_2 = \int \frac{\ln(x)}{5x^4} dx$$

Hence

$$u_2 = -\frac{\ln(x)}{15x^3} - \frac{1}{45x^3}$$

Which simplifies to

$$u_1 = -\frac{x^2(-1 + 2 \ln(x))}{20}$$
$$u_2 = \frac{-1 - 3 \ln(x)}{45x^3}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \frac{1}{36} - \frac{\ln(x)}{6}$$

Therefore the general solution is

$$y = y_h + y_p$$
$$= \frac{1}{36} - \frac{\ln(x)}{6} + \frac{c_1}{x^2} + c_2x^3$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = \frac{1}{36} - \frac{\ln(x)}{6} + \frac{c_1}{x^2} + c_2x^3 \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = \frac{1}{6}$ and $x = 1$ in the above gives

$$\frac{1}{6} = c_1 + c_2 + \frac{1}{36} \quad (1A)$$

Taking derivative of the solution gives

$$y' = -\frac{1}{6x} - \frac{2c_1}{x^3} + 3c_2x^2$$

substituting $y' = -\frac{1}{6}$ and $x = 1$ in the above gives

$$-\frac{1}{6} = -2c_1 + 3c_2 - \frac{1}{6} \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = \frac{1}{12}$$
$$c_2 = \frac{1}{18}$$

Substituting these values back in above solution results in

$$y = \frac{2x^5 - 6x^2 \ln(x) + x^2 + 3}{36x^2}$$

Summary

The solution(s) found are the following

$$y = \frac{2x^5 - 6x^2 \ln(x) + x^2 + 3}{36x^2} \quad (1)$$

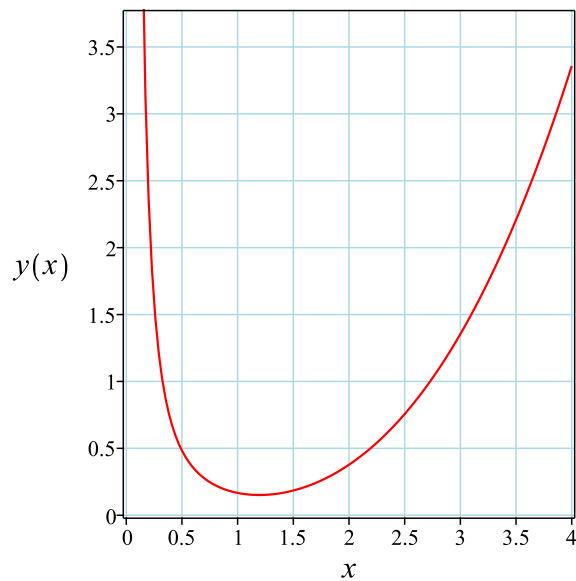


Figure 558: Solution plot

Verification of solutions

$$y = \frac{2x^5 - 6x^2 \ln(x) + x^2 + 3}{36x^2}$$

Verified OK.

13.27.3 Solving using Kovacic algorithm

Writing the ode as

$$x^2 y'' - 6y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$A = x^2$$

$$B = 0 \quad (3)$$

$$C = -6$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$r = \frac{s}{t} \quad (5)$$
$$= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2}$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{6}{x^2} \quad (6)$$

Comparing the above to (5) shows that

$$s = 6$$

$$t = x^2$$

Therefore eq. (4) becomes

$$z''(x) = \left(\frac{6}{x^2}\right) z(x) \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 507: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 2 - 0 \\ &= 2 \end{aligned}$$

The poles of r in eq. (7) and the order of each pole are determined by solving for the roots of $t = x^2$. There is a pole at $x = 0$ of order 2. Since there is no odd order pole larger than 2 and the order at ∞ is 2 then the necessary conditions for case one are met. Since there is a pole of order 2 then necessary conditions for case two are met. Since pole order is not larger than 2 and the order at ∞ is 2 then the necessary conditions for case three are met. Therefore

$$L = [1, 2, 4, 6, 12]$$

Attempting to find a solution using case $n = 1$.

Looking at poles of order 2. The partial fractions decomposition of r is

$$r = \frac{6}{x^2}$$

For the pole at $x = 0$ let b be the coefficient of $\frac{1}{x^2}$ in the partial fractions decomposition of r given above. Therefore $b = 6$. Hence

$$\begin{aligned} [\sqrt{r}]_c &= 0 \\ \alpha_c^+ &= \frac{1}{2} + \sqrt{1 + 4b} = 3 \\ \alpha_c^- &= \frac{1}{2} - \sqrt{1 + 4b} = -2 \end{aligned}$$

Since the order of r at ∞ is 2 then $[\sqrt{r}]_\infty = 0$. Let b be the coefficient of $\frac{1}{x^2}$ in the Laurent series expansion of r at ∞ . which can be found by dividing the leading coefficient of s by the leading coefficient of t from

$$r = \frac{s}{t} = \frac{6}{x^2}$$

Since the $\gcd(s, t) = 1$. This gives $b = 6$. Hence

$$\begin{aligned} [\sqrt{r}]_\infty &= 0 \\ \alpha_\infty^+ &= \frac{1}{2} + \sqrt{1 + 4b} = 3 \\ \alpha_\infty^- &= \frac{1}{2} - \sqrt{1 + 4b} = -2 \end{aligned}$$

The following table summarizes the findings so far for poles and for the order of r at ∞ where r is

$$r = \frac{6}{x^2}$$

pole c location	pole order	$[\sqrt{r}]_c$	α_c^+	α_c^-
0	2	0	3	-2

Order of r at ∞	$[\sqrt{r}]_\infty$	α_∞^+	α_∞^-
2	0	3	-2

Now that the all $[\sqrt{r}]_c$ and its associated α_c^\pm have been determined for all the poles in the set Γ and $[\sqrt{r}]_\infty$ and its associated α_∞^\pm have also been found, the next step is to determine possible non negative integer d from these using

$$d = \alpha_\infty^{s(\infty)} - \sum_{c \in \Gamma} \alpha_c^{s(c)}$$

Where $s(c)$ is either $+$ or $-$ and $s(\infty)$ is the sign of α_∞^\pm . This is done by trial over all set of families $s = (s(c))_{c \in \Gamma \cup \infty}$ until such d is found to work in finding candidate ω .

Trying $\alpha_{\infty}^- = -2$ then

$$\begin{aligned} d &= \alpha_{\infty}^- - (\alpha_{c_1}^-) \\ &= -2 - (-2) \\ &= 0 \end{aligned}$$

Since d an integer and $d \geq 0$ then it can be used to find ω using

$$\omega = \sum_{c \in \Gamma} \left(s(c)[\sqrt{r}]_c + \frac{\alpha_c^{s(c)}}{x - c} \right) + s(\infty)[\sqrt{r}]_{\infty}$$

The above gives

$$\begin{aligned} \omega &= \left((-)[\sqrt{r}]_{c_1} + \frac{\alpha_{c_1}^-}{x - c_1} \right) + (-)[\sqrt{r}]_{\infty} \\ &= -\frac{2}{x} + (-)(0) \\ &= -\frac{2}{x} \\ &= -\frac{2}{x} \end{aligned}$$

Now that ω is determined, the next step is find a corresponding minimal polynomial $p(x)$ of degree $d = 0$ to solve the ode. The polynomial $p(x)$ needs to satisfy the equation

$$p'' + 2\omega p' + (\omega' + \omega^2 - r)p = 0 \quad (1A)$$

Let

$$p(x) = 1 \quad (2A)$$

Substituting the above in eq. (1A) gives

$$\begin{aligned} (0) + 2\left(-\frac{2}{x}\right)(0) + \left(\left(\frac{2}{x^2}\right) + \left(-\frac{2}{x}\right)^2 - \left(\frac{6}{x^2}\right)\right) &= 0 \\ 0 &= 0 \end{aligned}$$

The equation is satisfied since both sides are zero. Therefore the first solution to the ode $z'' = rz$ is

$$\begin{aligned} z_1(x) &= p e^{\int \omega dx} \\ &= e^{\int -\frac{2}{x} dx} \\ &= \frac{1}{x^2} \end{aligned}$$

The first solution to the original ode in y is found from

$$y_1 = z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx}$$

Since $B = 0$ then the above reduces to

$$\begin{aligned} y_1 &= z_1 \\ &= \frac{1}{x^2} \end{aligned}$$

Which simplifies to

$$y_1 = \frac{1}{x^2}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Since $B = 0$ then the above becomes

$$\begin{aligned} y_2 &= y_1 \int \frac{1}{y_1^2} dx \\ &= \frac{1}{x^2} \int \frac{1}{\frac{1}{x^4}} dx \\ &= \frac{1}{x^2} \left(\frac{x^5}{5} \right) \end{aligned}$$

Therefore the solution is

$$\begin{aligned} y &= c_1 y_1 + c_2 y_2 \\ &= c_1 \left(\frac{1}{x^2} \right) + c_2 \left(\frac{1}{x^2} \left(\frac{x^5}{5} \right) \right) \end{aligned}$$

This is second order nonhomogeneous ODE. Let the solution be

$$y = y_h + y_p$$

Where y_h is the solution to the homogeneous ODE $Ay''(x) + By'(x) + Cy(x) = 0$, and y_p is a particular solution to the nonhomogeneous ODE $Ay''(x) + By'(x) + Cy(x) = f(x)$. y_h is the solution to

$$x^2y'' - 6y = 0$$

The homogeneous solution is found using the Kovacic algorithm which results in

$$y_h = \frac{c_1}{x^2} + \frac{c_2x^3}{5}$$

The particular solution y_p can be found using either the method of undetermined coefficients, or the method of variation of parameters. The method of variation of parameters will be used as it is more general and can be used when the coefficients of the ODE depend on x as well. Let

$$y_p(x) = u_1y_1 + u_2y_2 \quad (1)$$

Where u_1, u_2 to be determined, and y_1, y_2 are the two basis solutions (the two linearly independent solutions of the homogeneous ODE) found earlier when solving the homogeneous ODE as

$$y_1 = \frac{1}{x^2}$$

$$y_2 = \frac{x^3}{5}$$

In the Variation of parameters u_1, u_2 are found using

$$u_1 = - \int \frac{y_2f(x)}{aW(x)} \quad (2)$$

$$u_2 = \int \frac{y_1f(x)}{aW(x)} \quad (3)$$

Where $W(x)$ is the Wronskian and a is the coefficient in front of y'' in the given ODE.

The Wronskian is given by $W = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}$. Hence

$$W = \begin{vmatrix} \frac{1}{x^2} & \frac{x^3}{5} \\ \frac{d}{dx} \left(\frac{1}{x^2} \right) & \frac{d}{dx} \left(\frac{x^3}{5} \right) \end{vmatrix}$$

Which gives

$$W = \begin{vmatrix} \frac{1}{x^2} & \frac{x^3}{5} \\ -\frac{2}{x^3} & \frac{3x^2}{5} \end{vmatrix}$$

Therefore

$$W = \left(\frac{1}{x^2}\right) \left(\frac{3x^2}{5}\right) - \left(\frac{x^3}{5}\right) \left(-\frac{2}{x^3}\right)$$

Which simplifies to

$$W = 1$$

Which simplifies to

$$W = 1$$

Therefore Eq. (2) becomes

$$u_1 = - \int \frac{\frac{x^3 \ln(x)}{5}}{x^2} dx$$

Which simplifies to

$$u_1 = - \int \frac{x \ln(x)}{5} dx$$

Hence

$$u_1 = -\frac{x^2 \ln(x)}{10} + \frac{x^2}{20}$$

And Eq. (3) becomes

$$u_2 = \int \frac{\frac{\ln(x)}{x^2}}{x^2} dx$$

Which simplifies to

$$u_2 = \int \frac{\ln(x)}{x^4} dx$$

Hence

$$u_2 = -\frac{\ln(x)}{3x^3} - \frac{1}{9x^3}$$

Which simplifies to

$$u_1 = -\frac{x^2(-1 + 2 \ln(x))}{20}$$
$$u_2 = \frac{-1 - 3 \ln(x)}{9x^3}$$

Therefore the particular solution, from equation (1) is

$$y_p(x) = \frac{1}{36} - \frac{\ln(x)}{6}$$

Therefore the general solution is

$$y = y_h + y_p$$
$$= \left(\frac{c_1}{x^2} + \frac{c_2 x^3}{5} \right) + \left(\frac{1}{36} - \frac{\ln(x)}{6} \right)$$

Initial conditions are used to solve for the constants of integration.

Looking at the above solution

$$y = \frac{c_1}{x^2} + \frac{c_2 x^3}{5} + \frac{1}{36} - \frac{\ln(x)}{6} \quad (1)$$

Initial conditions are now substituted in the above solution. This will generate the required equations to solve for the integration constants. substituting $y = \frac{1}{6}$ and $x = 1$ in the above gives

$$\frac{1}{6} = c_1 + \frac{c_2}{5} + \frac{1}{36} \quad (1A)$$

Taking derivative of the solution gives

$$y' = -\frac{2c_1}{x^3} + \frac{3c_2 x^2}{5} - \frac{1}{6x}$$

substituting $y' = -\frac{1}{6}$ and $x = 1$ in the above gives

$$-\frac{1}{6} = -2c_1 + \frac{3c_2}{5} - \frac{1}{6} \quad (2A)$$

Equations {1A,2A} are now solved for $\{c_1, c_2\}$. Solving for the constants gives

$$c_1 = \frac{1}{12}$$
$$c_2 = \frac{5}{18}$$

Substituting these values back in above solution results in

$$y = \frac{2x^5 - 6x^2 \ln(x) + x^2 + 3}{36x^2}$$

Summary

The solution(s) found are the following

$$y = \frac{2x^5 - 6x^2 \ln(x) + x^2 + 3}{36x^2} \quad (1)$$

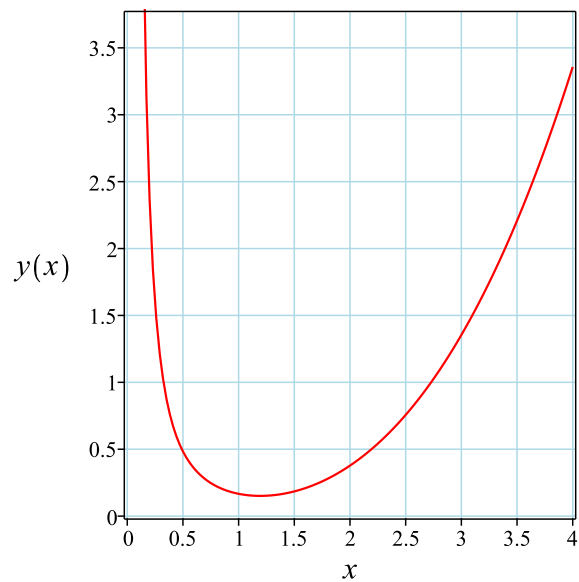


Figure 559: Solution plot

Verification of solutions

$$y = \frac{2x^5 - 6x^2 \ln(x) + x^2 + 3}{36x^2}$$

Verified OK.

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
trying high order exact linear fully integrable  
trying differential order: 2; linear nonhomogeneous with symmetry [0,1]  
trying a double symmetry of the form [xi=0, eta=F(x)]  
-> Try solving first the homogeneous part of the ODE  
    checking if the LODE has constant coefficients  
    checking if the LODE is of Euler type  
    <- LODE of Euler type successful  
<- solving first the homogeneous part of the ODE successful`
```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 20

```
dsolve([x^2*diff(y(x),x$2)-6*y(x)=ln(x),y(1) = 1/6, D(y)(1) = -1/6],y(x), singsol=all)
```

$$y(x) = \frac{1}{12x^2} + \frac{x^3}{18} - \frac{\ln(x)}{6} + \frac{1}{36}$$

✓ Solution by Mathematica

Time used: 0.019 (sec). Leaf size: 29

```
DSolve[{x^2*y'[x]-6*y[x]==Log[x],{y[1]==1/6,y'[1]==-1/6}},y[x],x,IncludeSingularSolutions -
```

$$y(x) \rightarrow \frac{2x^5 + x^2 - 6x^2 \log(x) + 3}{36x^2}$$

13.28 problem 28

13.28.1 Solving as second order integrable as is ode	3809
13.28.2 Solving as type second_order_integrable_as_is (not using ABC version)	3811
13.28.3 Solving using Kovacic algorithm	3812
13.28.4 Solving as exact linear second order ode ode	3817
13.28.5 Maple step by step solution	3819

Internal problem ID [11882]

Internal file name [OUTPUT/11891_Saturday_April_13_2024_01_14_13_AM_67873546/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 4, Section 4.5. The Cauchy-Euler Equation. Exercises page 169

Problem number: 28.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "exact linear second order ode", "second_order_integrable_as_is"

Maple gives the following as the ode type

```
[[_2nd_order , _exact , _linear , _homogeneous]]
```

$$(x + 2)^2 y'' - (x + 2) y' - 3y = 0$$

13.28.1 Solving as second order integrable as is ode

Integrating both sides of the ODE w.r.t x gives

$$\int ((x + 2)^2 y'' + (-x - 2) y' - 3y) dx = 0$$
$$(-3x - 6) y + (x^2 + 4x + 4) y' = c_1$$

Which is now solved for y .

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = -\frac{3}{x+2}$$
$$q(x) = \frac{c_1}{(x+2)^2}$$

Hence the ode is

$$y' - \frac{3y}{x+2} = \frac{c_1}{(x+2)^2}$$

The integrating factor μ is

$$\mu = e^{\int -\frac{3}{x+2} dx}$$
$$= \frac{1}{(x+2)^3}$$

The ode becomes

$$\frac{d}{dx}(\mu y) = (\mu) \left(\frac{c_1}{(x+2)^2} \right)$$
$$\frac{d}{dx} \left(\frac{y}{(x+2)^3} \right) = \left(\frac{1}{(x+2)^3} \right) \left(\frac{c_1}{(x+2)^2} \right)$$
$$d \left(\frac{y}{(x+2)^3} \right) = \left(\frac{c_1}{(x+2)^5} \right) dx$$

Integrating gives

$$\frac{y}{(x+2)^3} = \int \frac{c_1}{(x+2)^5} dx$$
$$\frac{y}{(x+2)^3} = -\frac{c_1}{4(x+2)^4} + c_2$$

Dividing both sides by the integrating factor $\mu = \frac{1}{(x+2)^3}$ results in

$$y = -\frac{c_1}{4(x+2)} + c_2(x+2)^3$$

Summary

The solution(s) found are the following

$$y = -\frac{c_1}{4(x+2)} + c_2(x+2)^3 \quad (1)$$

Verification of solutions

$$y = -\frac{c_1}{4(x+2)} + c_2(x+2)^3$$

Verified OK.

13.28.2 Solving as type second_order_integrable_as_is (not using ABC version)

Writing the ode as

$$(x + 2)^2 y'' + (-x - 2) y' - 3y = 0$$

Integrating both sides of the ODE w.r.t x gives

$$\int ((x + 2)^2 y'' + (-x - 2) y' - 3y) dx = 0$$
$$(-3x - 6)y + (x^2 + 4x + 4) y' = c_1$$

Which is now solved for y .

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$p(x) = -\frac{3}{x + 2}$$
$$q(x) = \frac{c_1}{(x + 2)^2}$$

Hence the ode is

$$y' - \frac{3y}{x + 2} = \frac{c_1}{(x + 2)^2}$$

The integrating factor μ is

$$\mu = e^{\int -\frac{3}{x+2} dx}$$
$$= \frac{1}{(x + 2)^3}$$

The ode becomes

$$\frac{d}{dx}(\mu y) = (\mu) \left(\frac{c_1}{(x + 2)^2} \right)$$
$$\frac{d}{dx} \left(\frac{y}{(x + 2)^3} \right) = \left(\frac{1}{(x + 2)^3} \right) \left(\frac{c_1}{(x + 2)^2} \right)$$
$$d \left(\frac{y}{(x + 2)^3} \right) = \left(\frac{c_1}{(x + 2)^5} \right) dx$$

Integrating gives

$$\frac{y}{(x+2)^3} = \int \frac{c_1}{(x+2)^5} dx$$
$$\frac{y}{(x+2)^3} = -\frac{c_1}{4(x+2)^4} + c_2$$

Dividing both sides by the integrating factor $\mu = \frac{1}{(x+2)^3}$ results in

$$y = -\frac{c_1}{4(x+2)} + c_2(x+2)^3$$

Summary

The solution(s) found are the following

$$y = -\frac{c_1}{4(x+2)} + c_2(x+2)^3 \quad (1)$$

Verification of solutions

$$y = -\frac{c_1}{4(x+2)} + c_2(x+2)^3$$

Verified OK.

13.28.3 Solving using Kovacic algorithm

Writing the ode as

$$(x+2)^2 y'' + (-x-2)y' - 3y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$A = (x+2)^2$$
$$B = -x-2$$
$$C = -3 \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$r = \frac{s}{t} = \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{15}{4(x+2)^2} \quad (6)$$

Comparing the above to (5) shows that

$$s = 15$$

$$t = 4(x+2)^2$$

Therefore eq. (4) becomes

$$z''(x) = \left(\frac{15}{4(x+2)^2} \right) z(x) \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 508: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 2 - 0 \\ &= 2 \end{aligned}$$

The poles of r in eq. (7) and the order of each pole are determined by solving for the roots of $t = 4(x + 2)^2$. There is a pole at $x = -2$ of order 2. Since there is no odd order pole larger than 2 and the order at ∞ is 2 then the necessary conditions for case one are met. Since there is a pole of order 2 then necessary conditions for case two are met. Since pole order is not larger than 2 and the order at ∞ is 2 then the necessary conditions for case three are met. Therefore

$$L = [1, 2, 4, 6, 12]$$

Attempting to find a solution using case $n = 1$.

Looking at poles of order 2. The partial fractions decomposition of r is

$$r = \frac{15}{4(x+2)^2}$$

For the pole at $x = -2$ let b be the coefficient of $\frac{1}{(x+2)^2}$ in the partial fractions decomposition of r given above. Therefore $b = \frac{15}{4}$. Hence

$$\begin{aligned} [\sqrt{r}]_c &= 0 \\ \alpha_c^+ &= \frac{1}{2} + \sqrt{1 + 4b} = \frac{5}{2} \\ \alpha_c^- &= \frac{1}{2} - \sqrt{1 + 4b} = -\frac{3}{2} \end{aligned}$$

Since the order of r at ∞ is 2 then $[\sqrt{r}]_\infty = 0$. Let b be the coefficient of $\frac{1}{x^2}$ in the Laurent series expansion of r at ∞ . which can be found by dividing the leading coefficient of s by the leading coefficient of t from

$$r = \frac{s}{t} = \frac{15}{4(x+2)^2}$$

Since the $\gcd(s, t) = 1$. This gives $b = \frac{15}{4}$. Hence

$$\begin{aligned} [\sqrt{r}]_\infty &= 0 \\ \alpha_\infty^+ &= \frac{1}{2} + \sqrt{1 + 4b} = \frac{5}{2} \\ \alpha_\infty^- &= \frac{1}{2} - \sqrt{1 + 4b} = -\frac{3}{2} \end{aligned}$$

The following table summarizes the findings so far for poles and for the order of r at ∞ where r is

$$r = \frac{15}{4(x+2)^2}$$

pole c location	pole order	$[\sqrt{r}]_c$	α_c^+	α_c^-
-2	2	0	$\frac{5}{2}$	$-\frac{3}{2}$

Order of r at ∞	$[\sqrt{r}]_\infty$	α_∞^+	α_∞^-
2	0	$\frac{5}{2}$	$-\frac{3}{2}$

Now that the all $[\sqrt{r}]_c$ and its associated α_c^\pm have been determined for all the poles in the set Γ and $[\sqrt{r}]_\infty$ and its associated α_∞^\pm have also been found, the next step is to determine possible non negative integer d from these using

$$d = \alpha_\infty^{s(\infty)} - \sum_{c \in \Gamma} \alpha_c^{s(c)}$$

Where $s(c)$ is either $+$ or $-$ and $s(\infty)$ is the sign of α_∞^\pm . This is done by trial over all set of families $s = (s(c))_{c \in \Gamma \cup \infty}$ until such d is found to work in finding candidate ω . Trying $\alpha_\infty^- = -\frac{3}{2}$ then

$$\begin{aligned} d &= \alpha_\infty^- - (\alpha_{c_1}^-) \\ &= -\frac{3}{2} - \left(-\frac{3}{2}\right) \\ &= 0 \end{aligned}$$

Since d an integer and $d \geq 0$ then it can be used to find ω using

$$\omega = \sum_{c \in \Gamma} \left(s(c)[\sqrt{r}]_c + \frac{\alpha_c^{s(c)}}{x-c} \right) + s(\infty)[\sqrt{r}]_\infty$$

The above gives

$$\begin{aligned} \omega &= \left((-)[\sqrt{r}]_{c_1} + \frac{\alpha_{c_1}^-}{x-c_1} \right) + (-)[\sqrt{r}]_\infty \\ &= -\frac{3}{2(x+2)} + (-)(0) \\ &= -\frac{3}{2(x+2)} \\ &= -\frac{3}{2(x+2)} \end{aligned}$$

Now that ω is determined, the next step is find a corresponding minimal polynomial $p(x)$ of degree $d = 0$ to solve the ode. The polynomial $p(x)$ needs to satisfy the equation

$$p'' + 2\omega p' + (\omega' + \omega^2 - r) p = 0 \quad (1A)$$

Let

$$p(x) = 1 \quad (2A)$$

Substituting the above in eq. (1A) gives

$$(0) + 2\left(-\frac{3}{2(x+2)}\right)(0) + \left(\left(\frac{3}{2(x+2)^2}\right) + \left(-\frac{3}{2(x+2)}\right)^2 - \left(\frac{15}{4(x+2)^2}\right)\right) = 0$$

$$0 = 0$$

The equation is satisfied since both sides are zero. Therefore the first solution to the ode $z'' = rz$ is

$$\begin{aligned} z_1(x) &= p e^{\int \omega dx} \\ &= e^{\int -\frac{3}{2(x+2)} dx} \\ &= \frac{1}{(x+2)^{\frac{3}{2}}} \end{aligned}$$

The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-x-2}{(x+2)^2} dx} \\ &= z_1 e^{\frac{\ln(x+2)}{2}} \\ &= z_1 (\sqrt{x+2}) \end{aligned}$$

Which simplifies to

$$y_1 = \frac{1}{x+2}$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{-x-2}{(x+2)^2} dx}}{(y_1)^2} dx \\&= y_1 \int \frac{e^{\ln(x+2)}}{(y_1)^2} dx \\&= y_1 \left(\frac{(x+2)^4}{4} \right)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\&= c_1 \left(\frac{1}{x+2} \right) + c_2 \left(\frac{1}{x+2} \left(\frac{(x+2)^4}{4} \right) \right)\end{aligned}$$

Summary

The solution(s) found are the following

$$y = \frac{c_1}{x+2} + \frac{c_2(x+2)^3}{4} \quad (1)$$

Verification of solutions

$$y = \frac{c_1}{x+2} + \frac{c_2(x+2)^3}{4}$$

Verified OK.

13.28.4 Solving as exact linear second order ode

An ode of the form

$$p(x)y'' + q(x)y' + r(x)y = s(x)$$

is exact if

$$p''(x) - q'(x) + r(x) = 0 \quad (1)$$

For the given ode we have

$$\begin{aligned}p(x) &= (x+2)^2 \\q(x) &= -x-2 \\r(x) &= -3 \\s(x) &= 0\end{aligned}$$

Hence

$$\begin{aligned}p''(x) &= 2 \\q'(x) &= -1\end{aligned}$$

Therefore (1) becomes

$$2 - (-1) + (-3) = 0$$

Hence the ode is exact. Since we now know the ode is exact, it can be written as

$$(p(x)y' + (q(x) - p'(x))y)' = s(x)$$

Integrating gives

$$p(x)y' + (q(x) - p'(x))y = \int s(x) dx$$

Substituting the above values for p, q, r, s gives

$$(x + 2)^2 y' + (-3x - 6)y = c_1$$

We now have a first order ode to solve which is

$$(x + 2)^2 y' + (-3x - 6)y = c_1$$

Entering Linear first order ODE solver. In canonical form a linear first order is

$$y' + p(x)y = q(x)$$

Where here

$$\begin{aligned}p(x) &= -\frac{3}{x+2} \\q(x) &= \frac{c_1}{(x+2)^2}\end{aligned}$$

Hence the ode is

$$y' - \frac{3y}{x+2} = \frac{c_1}{(x+2)^2}$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int -\frac{3}{x+2} dx} \\&= \frac{1}{(x+2)^3}\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dx}(\mu y) &= (\mu) \left(\frac{c_1}{(x+2)^2} \right) \\ \frac{d}{dx} \left(\frac{y}{(x+2)^3} \right) &= \left(\frac{1}{(x+2)^3} \right) \left(\frac{c_1}{(x+2)^2} \right) \\ d \left(\frac{y}{(x+2)^3} \right) &= \left(\frac{c_1}{(x+2)^5} \right) dx\end{aligned}$$

Integrating gives

$$\begin{aligned}\frac{y}{(x+2)^3} &= \int \frac{c_1}{(x+2)^5} dx \\ \frac{y}{(x+2)^3} &= -\frac{c_1}{4(x+2)^4} + c_2\end{aligned}$$

Dividing both sides by the integrating factor $\mu = \frac{1}{(x+2)^3}$ results in

$$y = -\frac{c_1}{4(x+2)} + c_2(x+2)^3$$

Summary

The solution(s) found are the following

$$y = -\frac{c_1}{4(x+2)} + c_2(x+2)^3 \quad (1)$$

Verification of solutions

$$y = -\frac{c_1}{4(x+2)} + c_2(x+2)^3$$

Verified OK.

13.28.5 Maple step by step solution

Let's solve

$$(x+2)^2 y'' + (-x-2)y' - 3y = 0$$

- Highest derivative means the order of the ODE is 2

y''

- Isolate 2nd derivative

$$y'' = \frac{y'}{x+2} + \frac{3y}{(x+2)^2}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' - \frac{y'}{x+2} - \frac{3y}{(x+2)^2} = 0$$

- Check to see if $x_0 = -2$ is a regular singular point

- Define functions

$$\left[P_2(x) = -\frac{1}{x+2}, P_3(x) = -\frac{3}{(x+2)^2} \right]$$

- $(x+2) \cdot P_2(x)$ is analytic at $x = -2$

$$\left. ((x+2) \cdot P_2(x)) \right|_{x=-2} = -1$$

- $(x+2)^2 \cdot P_3(x)$ is analytic at $x = -2$

$$\left. ((x+2)^2 \cdot P_3(x)) \right|_{x=-2} = -3$$

- $x = -2$ is a regular singular point

Check to see if $x_0 = -2$ is a regular singular point

$$x_0 = -2$$

- Multiply by denominators

$$(x+2)^2 y'' + (-x-2)y' - 3y = 0$$

- Change variables using $x = u - 2$ so that the regular singular point is at $u = 0$

$$u^2 \left(\frac{d^2}{du^2} y(u) \right) - u \left(\frac{d}{du} y(u) \right) - 3y(u) = 0$$

- Assume series solution for $y(u)$

$$y(u) = \sum_{k=0}^{\infty} a_k u^{k+r}$$

- Rewrite DE with series expansions

- Convert $u \cdot \left(\frac{d}{du} y(u) \right)$ to series expansion

$$u \cdot \left(\frac{d}{du} y(u) \right) = \sum_{k=0}^{\infty} a_k (k+r) u^{k+r}$$

- Convert $u^2 \cdot \left(\frac{d^2}{du^2} y(u) \right)$ to series expansion

$$u^2 \cdot \left(\frac{d^2}{du^2} y(u) \right) = \sum_{k=0}^{\infty} a_k (k+r)(k+r-1) u^{k+r}$$

Rewrite DE with series expansions

$$\sum_{k=0}^{\infty} a_k (k+r+1)(k+r-3) u^{k+r} = 0$$

- a_0 cannot be 0 by assumption, giving the indicial equation
 $r = 0$
- Each term in the series must be 0, giving the recursion relation
 $a_k(k+1)(k-3) = 0$
- Recursion relation that defines series solution to ODE
 $a_k = 0$
- Recursion relation for $r = 0$
 $a_k = 0$
- Solution for $r = 0$
 $\left[y(u) = \sum_{k=0}^{\infty} a_k u^k, a_k = 0 \right]$
- Revert the change of variables $u = x + 2$
 $\left[y = \sum_{k=0}^{\infty} a_k (x + 2)^k, a_k = 0 \right]$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
<- LODE of Euler type successful`

```

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 19

```
dsolve((x+2)^2*diff(y(x),x$2)-(x+2)*diff(y(x),x)-3*y(x)=0,y(x), singsol=all)
```

$$y(x) = \frac{c_1 + c_2(x+2)^4}{x+2}$$

✓ Solution by Mathematica

Time used: 0.031 (sec). Leaf size: 22

```
DSolve[(x+2)^2*y'[x]-(x+2)*y'[x]-3*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow c_1(x+2)^3 + \frac{c_2}{x+2}$$

13.29 problem 29

13.29.1 Solving as second order change of variable on x method 2 ode .	3823
13.29.2 Solving as second order ode non constant coeff transformation on B ode	3826
13.29.3 Solving using Kovacic algorithm	3828
13.29.4 Maple step by step solution	3833

Internal problem ID [11883]

Internal file name [OUTPUT/11892_Saturday_April_13_2024_01_14_14_AM_480238/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 4, Section 4.5. The Cauchy-Euler Equation. Exercises page 169

Problem number: 29.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "kovacic", "second_order_change_of_variable_on_x_method_2", "second_order_ode_non_constant_coeff_transformation_on_B"

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$(2x - 3)^2 y'' - 6(2x - 3) y' + 12y = 0$$

13.29.1 Solving as second order change of variable on x method 2 ode

In normal form the ode

$$4 \left(x - \frac{3}{2} \right)^2 y'' + (-12x + 18) y' + 12y = 0 \quad (1)$$

Becomes

$$y'' + p(x) y' + q(x) y = 0 \quad (2)$$

Where

$$p(x) = \frac{6}{-2x + 3}$$
$$q(x) = \frac{12}{(2x - 3)^2}$$

Applying change of variables $\tau = g(x)$ to (2) gives

$$\frac{d^2}{d\tau^2}y(\tau) + p_1\left(\frac{d}{d\tau}y(\tau)\right) + q_1y(\tau) = 0 \quad (3)$$

Where τ is the new independent variable, and

$$p_1(\tau) = \frac{\tau''(x) + p(x)\tau'(x)}{\tau'(x)^2} \quad (4)$$

$$q_1(\tau) = \frac{q(x)}{\tau'(x)^2} \quad (5)$$

Let $p_1 = 0$. Eq (4) simplifies to

$$\tau''(x) + p(x)\tau'(x) = 0$$

This ode is solved resulting in

$$\begin{aligned} \tau &= \int e^{-\left(\int p(x)dx\right)} dx \\ &= \int e^{-\left(\int \frac{6}{-2x+3} dx\right)} dx \\ &= \int e^{3\ln(-2x+3)} dx \\ &= \int (-2x+3)^3 dx \\ &= -\frac{(-2x+3)^4}{8} \end{aligned} \quad (6)$$

Using (6) to evaluate q_1 from (5) gives

$$\begin{aligned} q_1(\tau) &= \frac{q(x)}{\tau'(x)^2} \\ &= \frac{12}{(2x-3)^2} \\ &= \frac{12}{(-2x+3)^6} \\ &= \frac{12}{(2x-3)^8} \end{aligned} \quad (7)$$

Substituting the above in (3) and noting that now $p_1 = 0$ results in

$$\begin{aligned} \frac{d^2}{d\tau^2}y(\tau) + q_1y(\tau) &= 0 \\ \frac{d^2}{d\tau^2}y(\tau) + \frac{12y(\tau)}{(2x-3)^8} &= 0 \end{aligned}$$

But in terms of τ

$$\frac{12}{(2x-3)^8} = \frac{3}{16\tau^2}$$

Hence the above ode becomes

$$\frac{d^2}{d\tau^2}y(\tau) + \frac{3y(\tau)}{16\tau^2} = 0$$

The above ode is now solved for $y(\tau)$. The ode can be written as

$$16\left(\frac{d^2}{d\tau^2}y(\tau)\right)\tau^2 + 3y(\tau) = 0$$

Which shows it is a Euler ODE. This is Euler second order ODE. Let the solution be $y(\tau) = \tau^r$, then $y' = r\tau^{r-1}$ and $y'' = r(r-1)\tau^{r-2}$. Substituting these back into the given ODE gives

$$16\tau^2(r(r-1))\tau^{r-2} + 0r\tau^{r-1} + 3\tau^r = 0$$

Simplifying gives

$$16r(r-1)\tau^r + 0\tau^r + 3\tau^r = 0$$

Since $\tau^r \neq 0$ then dividing throughout by τ^r gives

$$16r(r-1) + 0 + 3 = 0$$

Or

$$16r^2 - 16r + 3 = 0 \tag{1}$$

Equation (1) is the characteristic equation. Its roots determine the form of the general solution. Using the quadratic equation the roots are

$$r_1 = \frac{1}{4}$$

$$r_2 = \frac{3}{4}$$

Since the roots are real and distinct, then the general solution is

$$y(\tau) = c_1y_1 + c_2y_2$$

Where $y_1 = \tau^{r_1}$ and $y_2 = \tau^{r_2}$. Hence

$$y(\tau) = c_1\tau^{\frac{1}{4}} + c_2\tau^{\frac{3}{4}}$$

The above solution is now transformed back to y using (6) which results in

$$y = \frac{2^{\frac{1}{4}}(-(2x-3)^4)^{\frac{1}{4}}\left(c_2\sqrt{2}\sqrt{-(2x-3)^4+4c_1}\right)}{8}$$

Summary

The solution(s) found are the following

$$y = \frac{2^{\frac{1}{4}}(-(2x-3)^4)^{\frac{1}{4}} \left(c_2\sqrt{2} \sqrt{-(2x-3)^4 + 4c_1} \right)}{8} \quad (1)$$

Verification of solutions

$$y = \frac{2^{\frac{1}{4}}(-(2x-3)^4)^{\frac{1}{4}} \left(c_2\sqrt{2} \sqrt{-(2x-3)^4 + 4c_1} \right)}{8}$$

Verified OK.

13.29.2 Solving as second order ode non constant coeff transformation on B ode

Given an ode of the form

$$Ay'' + By' + Cy = F(x)$$

This method reduces the order ode the ODE by one by applying the transformation

$$y = Bv$$

This results in

$$\begin{aligned} y' &= B'v + v'B \\ y'' &= B''v + B'v' + v''B + v'B' \\ &= v''B + 2v' + B' + B''v \end{aligned}$$

And now the original ode becomes

$$\begin{aligned} A(v''B + 2v'B' + B''v) + B(B'v + v'B) + CBv &= 0 \\ ABv'' + (2AB' + B^2)v' + (AB'' + BB' + CB)v &= 0 \end{aligned} \quad (1)$$

If the term $AB'' + BB' + CB$ is zero, then this method works and can be used to solve

$$ABv'' + (2AB' + B^2)v' = 0$$

By Using $u = v'$ which reduces the order of the above ode to one. The new ode is

$$ABu' + (2AB' + B^2)u = 0$$

The above ode is first order ode which is solved for u . Now a new ode $v' = u$ is solved for v as first order ode. Then the final solution is obtain from $y = Bv$.

This method works only if the term $AB'' + BB' + CB$ is zero. The given ODE shows that

$$\begin{aligned} A &= 4\left(x - \frac{3}{2}\right)^2 \\ B &= -12x + 18 \\ C &= 12 \\ F &= 0 \end{aligned}$$

The above shows that for this ode

$$\begin{aligned} AB'' + BB' + CB &= \left(4\left(x - \frac{3}{2}\right)^2\right) (0) + (-12x + 18) (-12) + (12) (-12x + 18) \\ &= 0 \end{aligned}$$

Hence the ode in v given in (1) now simplifies to

$$-6(2x - 3)^3 v'' + (12(2x - 3)^2) v' = 0$$

Now by applying $v' = u$ the above becomes

$$-6(2x - 3)^3 u'(x) + 12u(x) (2x - 3)^2 = 0$$

Which is now solved for u . In canonical form the ODE is

$$\begin{aligned} u' &= F(x, u) \\ &= f(x)g(u) \\ &= \frac{2u}{2x - 3} \end{aligned}$$

Where $f(x) = \frac{2}{2x-3}$ and $g(u) = u$. Integrating both sides gives

$$\begin{aligned} \frac{1}{u} du &= \frac{2}{2x - 3} dx \\ \int \frac{1}{u} du &= \int \frac{2}{2x - 3} dx \\ \ln(u) &= \ln(2x - 3) + c_1 \\ u &= e^{\ln(2x-3)+c_1} \\ &= c_1(2x - 3) \end{aligned}$$

The ode for v now becomes

$$\begin{aligned} v' &= u \\ &= c_1(2x - 3) \end{aligned}$$

Which is now solved for v . Integrating both sides gives

$$\begin{aligned}v(x) &= \int c_1(2x - 3) dx \\ &= c_1(x^2 - 3x) + c_2\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y(x) &= Bv \\ &= (-12x + 18)(c_1(x^2 - 3x) + c_2) \\ &= -12(c_1x^2 - 3c_1x + c_2)\left(x - \frac{3}{2}\right)\end{aligned}$$

Summary

The solution(s) found are the following

$$y = -12(c_1x^2 - 3c_1x + c_2)\left(x - \frac{3}{2}\right) \quad (1)$$

Verification of solutions

$$y = -12(c_1x^2 - 3c_1x + c_2)\left(x - \frac{3}{2}\right)$$

Verified OK.

13.29.3 Solving using Kovacic algorithm

Writing the ode as

$$4\left(x - \frac{3}{2}\right)^2 y'' + (-12x + 18)y' + 12y = 0 \quad (1)$$

$$Ay'' + By' + Cy = 0 \quad (2)$$

Comparing (1) and (2) shows that

$$\begin{aligned}A &= 4\left(x - \frac{3}{2}\right)^2 \\ B &= -12x + 18 \\ C &= 12\end{aligned} \quad (3)$$

Applying the Liouville transformation on the dependent variable gives

$$z(x) = ye^{\int \frac{B}{2A} dx}$$

Then (2) becomes

$$z''(x) = rz(x) \quad (4)$$

Where r is given by

$$\begin{aligned} r &= \frac{s}{t} \\ &= \frac{2AB' - 2BA' + B^2 - 4AC}{4A^2} \end{aligned} \quad (5)$$

Substituting the values of A, B, C from (3) in the above and simplifying gives

$$r = \frac{3}{(2x - 3)^2} \quad (6)$$

Comparing the above to (5) shows that

$$\begin{aligned} s &= 3 \\ t &= (2x - 3)^2 \end{aligned}$$

Therefore eq. (4) becomes

$$z''(x) = \left(\frac{3}{(2x - 3)^2} \right) z(x) \quad (7)$$

Equation (7) is now solved. After finding $z(x)$ then y is found using the inverse transformation

$$y = z(x) e^{-\int \frac{B}{2A} dx}$$

The first step is to determine the case of Kovacic algorithm this ode belongs to. There are 3 cases depending on the order of poles of r and the order of r at ∞ . The following table summarizes these cases.

Case	Allowed pole order for r	Allowed value for $\mathcal{O}(\infty)$
1	$\{0, 1, 2, 4, 6, 8, \dots\}$	$\{\dots, -6, -4, -2, 0, 2, 3, 4, 5, 6, \dots\}$
2	Need to have at least one pole that is either order 2 or odd order greater than 2. Any other pole order is allowed as long as the above condition is satisfied. Hence the following set of pole orders are all allowed. $\{1, 2\}, \{1, 3\}, \{2\}, \{3\}, \{3, 4\}, \{1, 2, 5\}$.	no condition
3	$\{1, 2\}$	$\{2, 3, 4, 5, 6, 7, \dots\}$

Table 510: Necessary conditions for each Kovacic case

The order of r at ∞ is the degree of t minus the degree of s . Therefore

$$\begin{aligned} O(\infty) &= \deg(t) - \deg(s) \\ &= 2 - 0 \\ &= 2 \end{aligned}$$

The poles of r in eq. (7) and the order of each pole are determined by solving for the roots of $t = (2x - 3)^2$. There is a pole at $x = \frac{3}{2}$ of order 2. Since there is no odd order pole larger than 2 and the order at ∞ is 2 then the necessary conditions for case one are met. Since there is a pole of order 2 then necessary conditions for case two are met. Since pole order is not larger than 2 and the order at ∞ is 2 then the necessary conditions for case three are met. Therefore

$$L = [1, 2, 4, 6, 12]$$

Attempting to find a solution using case $n = 1$.

Looking at poles of order 2. The partial fractions decomposition of r is

$$r = \frac{3}{4(x - \frac{3}{2})^2}$$

For the pole at $x = \frac{3}{2}$ let b be the coefficient of $\frac{1}{(x - \frac{3}{2})^2}$ in the partial fractions decomposition of r given above. Therefore $b = \frac{3}{4}$. Hence

$$\begin{aligned} [\sqrt{r}]_c &= 0 \\ \alpha_c^+ &= \frac{1}{2} + \sqrt{1 + 4b} = \frac{3}{2} \\ \alpha_c^- &= \frac{1}{2} - \sqrt{1 + 4b} = -\frac{1}{2} \end{aligned}$$

Since the order of r at ∞ is 2 then $[\sqrt{r}]_\infty = 0$. Let b be the coefficient of $\frac{1}{x^2}$ in the Laurent series expansion of r at ∞ , which can be found by dividing the leading coefficient of s by the leading coefficient of t from

$$r = \frac{s}{t} = \frac{3}{(2x - 3)^2}$$

Since the $\gcd(s, t) = 1$. This gives $b = \frac{3}{4}$. Hence

$$\begin{aligned} [\sqrt{r}]_\infty &= 0 \\ \alpha_\infty^+ &= \frac{1}{2} + \sqrt{1 + 4b} = \frac{3}{2} \\ \alpha_\infty^- &= \frac{1}{2} - \sqrt{1 + 4b} = -\frac{1}{2} \end{aligned}$$

The following table summarizes the findings so far for poles and for the order of r at ∞ where r is

$$r = \frac{3}{(2x - 3)^2}$$

pole c location	pole order	$[\sqrt{r}]_c$	α_c^+	α_c^-
$\frac{3}{2}$	2	0	$\frac{3}{2}$	$-\frac{1}{2}$

Order of r at ∞	$[\sqrt{r}]_\infty$	α_∞^+	α_∞^-
2	0	$\frac{3}{2}$	$-\frac{1}{2}$

Now that the all $[\sqrt{r}]_c$ and its associated α_c^\pm have been determined for all the poles in the set Γ and $[\sqrt{r}]_\infty$ and its associated α_∞^\pm have also been found, the next step is to determine possible non negative integer d from these using

$$d = \alpha_\infty^{s(\infty)} - \sum_{c \in \Gamma} \alpha_c^{s(c)}$$

Where $s(c)$ is either $+$ or $-$ and $s(\infty)$ is the sign of α_∞^\pm . This is done by trial over all set of families $s = (s(c))_{c \in \Gamma \cup \infty}$ until such d is found to work in finding candidate ω . Trying $\alpha_\infty^- = -\frac{1}{2}$ then

$$\begin{aligned} d &= \alpha_\infty^- - (\alpha_{c_1}^-) \\ &= -\frac{1}{2} - \left(-\frac{1}{2}\right) \\ &= 0 \end{aligned}$$

Since d an integer and $d \geq 0$ then it can be used to find ω using

$$\omega = \sum_{c \in \Gamma} \left(s(c) [\sqrt{r}]_c + \frac{\alpha_c^{s(c)}}{x - c} \right) + s(\infty) [\sqrt{r}]_\infty$$

The above gives

$$\begin{aligned} \omega &= \left((-) [\sqrt{r}]_{c_1} + \frac{\alpha_{c_1}^-}{x - c_1} \right) + (-) [\sqrt{r}]_\infty \\ &= -\frac{1}{2 \left(x - \frac{3}{2}\right)} + (-) (0) \\ &= -\frac{1}{2 \left(x - \frac{3}{2}\right)} \\ &= -\frac{1}{2x - 3} \end{aligned}$$

Now that ω is determined, the next step is find a corresponding minimal polynomial $p(x)$ of degree $d = 0$ to solve the ode. The polynomial $p(x)$ needs to satisfy the equation

$$p'' + 2\omega p' + (\omega' + \omega^2 - r) p = 0 \quad (1A)$$

Let

$$p(x) = 1 \quad (2A)$$

Substituting the above in eq. (1A) gives

$$(0) + 2\left(-\frac{1}{2\left(x - \frac{3}{2}\right)}\right)(0) + \left(\left(\frac{1}{2\left(x - \frac{3}{2}\right)^2}\right) + \left(-\frac{1}{2\left(x - \frac{3}{2}\right)}\right)^2 - \left(\frac{3}{(2x - 3)^2}\right)\right) = 0$$

$$0 = 0$$

The equation is satisfied since both sides are zero. Therefore the first solution to the ode $z'' = rz$ is

$$\begin{aligned} z_1(x) &= pe^{\int \omega dx} \\ &= e^{\int -\frac{1}{2\left(x - \frac{3}{2}\right)} dx} \\ &= \frac{1}{\sqrt{2x - 3}} \end{aligned}$$

The first solution to the original ode in y is found from

$$\begin{aligned} y_1 &= z_1 e^{\int -\frac{1}{2} \frac{B}{A} dx} \\ &= z_1 e^{-\int \frac{1}{2} \frac{-12x + 18}{4\left(x - \frac{3}{2}\right)^2} dx} \\ &= z_1 e^{\frac{3 \ln(2x - 3)}{2}} \\ &= z_1 \left((2x - 3)^{\frac{3}{2}}\right) \end{aligned}$$

Which simplifies to

$$y_1 = 2x - 3$$

The second solution y_2 to the original ode is found using reduction of order

$$y_2 = y_1 \int \frac{e^{\int -\frac{B}{A} dx}}{y_1^2} dx$$

Substituting gives

$$\begin{aligned}y_2 &= y_1 \int \frac{e^{\int -\frac{-12x+18}{4(x-\frac{3}{2})^2} dx}}{(y_1)^2} dx \\&= y_1 \int \frac{e^{3 \ln(2x-3)}}{(y_1)^2} dx \\&= y_1(x^2 - 3x)\end{aligned}$$

Therefore the solution is

$$\begin{aligned}y &= c_1 y_1 + c_2 y_2 \\&= c_1(2x - 3) + c_2(2x - 3)(x^2 - 3x)\end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1(2x - 3) + c_2(2x^3 - 9x^2 + 9x) \quad (1)$$

Verification of solutions

$$y = c_1(2x - 3) + c_2(2x^3 - 9x^2 + 9x)$$

Verified OK.

13.29.4 Maple step by step solution

Let's solve

$$4\left(x - \frac{3}{2}\right)^2 y'' + (-12x + 18)y' + 12y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = \frac{6y'}{2x-3} - \frac{12y}{(2x-3)^2}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' - \frac{6y'}{2x-3} + \frac{12y}{(2x-3)^2} = 0$$

- Check to see if $x_0 = \frac{3}{2}$ is a regular singular point

- Define functions

$$\left[P_2(x) = -\frac{6}{2x-3}, P_3(x) = \frac{12}{(2x-3)^2} \right]$$

- $(x - \frac{3}{2}) \cdot P_2(x)$ is analytic at $x = \frac{3}{2}$

$$\left. \left((x - \frac{3}{2}) \cdot P_2(x) \right) \right|_{x=\frac{3}{2}} = -3$$

- $(x - \frac{3}{2})^2 \cdot P_3(x)$ is analytic at $x = \frac{3}{2}$

$$\left. \left((x - \frac{3}{2})^2 \cdot P_3(x) \right) \right|_{x=\frac{3}{2}} = 3$$

- $x = \frac{3}{2}$ is a regular singular point

Check to see if $x_0 = \frac{3}{2}$ is a regular singular point

$$x_0 = \frac{3}{2}$$

- Multiply by denominators

$$(2x - 3)^2 y'' + (-12x + 18) y' + 12y = 0$$

- Change variables using $x = u + \frac{3}{2}$ so that the regular singular point is at $u = 0$

$$4u^2 \left(\frac{d^2}{du^2} y(u) \right) - 12u \left(\frac{d}{du} y(u) \right) + 12y(u) = 0$$

- Assume series solution for $y(u)$

$$y(u) = \sum_{k=0}^{\infty} a_k u^{k+r}$$

- Rewrite DE with series expansions

- Convert $u \cdot \left(\frac{d}{du} y(u) \right)$ to series expansion

$$u \cdot \left(\frac{d}{du} y(u) \right) = \sum_{k=0}^{\infty} a_k (k+r) u^{k+r}$$

- Convert $u^2 \cdot \left(\frac{d^2}{du^2} y(u) \right)$ to series expansion

$$u^2 \cdot \left(\frac{d^2}{du^2} y(u) \right) = \sum_{k=0}^{\infty} a_k (k+r)(k+r-1) u^{k+r}$$

Rewrite DE with series expansions

$$\sum_{k=0}^{\infty} 4a_k (k+r-1)(k+r-3) u^{k+r} = 0$$

- a_0 cannot be 0 by assumption, giving the indicial equation

$$r = 0$$

- Each term in the series must be 0, giving the recursion relation

$$4a_k(k-1)(k-3) = 0$$

- Recursion relation that defines series solution to ODE

$$a_k = 0$$

- Recursion relation for $r = 0$

$$a_k = 0$$

- Solution for $r = 0$

$$\left[y(u) = \sum_{k=0}^{\infty} a_k u^k, a_k = 0 \right]$$

- Revert the change of variables $u = x - \frac{3}{2}$

$$\left[y = \sum_{k=0}^{\infty} a_k \left(x - \frac{3}{2}\right)^k, a_k = 0 \right]$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
<- LODE of Euler type successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 17

```
dsolve((2*x-3)^2*diff(y(x),x$2)-6*(2*x-3)*diff(y(x),x)+12*y(x)=0,y(x), singsol=all)
```

$$y(x) = \left(x - \frac{3}{2}\right) \left(c_1 + c_2 \left(x - \frac{3}{2}\right)^2\right)$$

✓ Solution by Mathematica

Time used: 0.034 (sec). Leaf size: 24

```
DSolve[(2*x-3)^2*y''[x]-6*(2*x-3)*y'[x]+12*y[x]==0,y[x],x,IncludeSingularSolutions -> True]
```

$$y(x) \rightarrow c_2(3 - 2x)^3 + c_1(3 - 2x)$$

14 Chapter 6, Series solutions of linear differential equations. Section 6.1. Exercises page 232

14.1 problem 1	3837
14.2 problem 2	3846
14.3 problem 3	3855
14.4 problem 4	3865
14.5 problem 5	3875
14.6 problem 6	3886
14.7 problem 7	3897
14.8 problem 8	3906
14.9 problem 9	3918
14.10 problem 10	3929
14.11 problem 11	3940
14.12 problem 12	3950
14.13 problem 13	3961
14.14 problem 14	3972
14.15 problem 15	3981
14.16 problem 16	3992
14.17 problem 17	4003
14.18 problem 18	4015

14.1 problem 1

14.1.1 Maple step by step solution 3844

Internal problem ID [11884]

Internal file name [OUTPUT/11893_Saturday_April_13_2024_01_14_15_AM_40632902/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.1. Exercises page 232

Problem number: 1.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"exact linear second order ode", "second_order_integrable_as_is", "second order series method. Ordinary point", "second order series method. Taylor series method"**

Maple gives the following as the ode type

```
[[_2nd_order , _exact , _linear , _homogeneous]]
```

$$y'' + y'x + y = 0$$

With the expansion point for the power series method at $x = 0$.

Solving ode using Taylor series method. This gives review on how the Taylor series method works for solving second order ode.

Let

$$y'' = f(x, y, y')$$

Assuming expansion is at $x_0 = 0$ (we can always shift the actual expansion point to 0 by change of variables) and assuming $f(x, y, y')$ is analytic at x_0 which must be the case for an ordinary point. Let initial conditions be $y(x_0) = y_0$ and $y'(x_0) = y'_0$. Using

Taylor series gives

$$\begin{aligned}
 y(x) &= y(x_0) + (x - x_0)y'(x_0) + \frac{(x - x_0)^2}{2}y''(x_0) + \frac{(x - x_0)^3}{3!}y'''(x_0) + \dots \\
 &= y_0 + xy'_0 + \frac{x^2}{2}f|_{x_0, y_0, y'_0} + \frac{x^3}{3!}f'|_{x_0, y_0, y'_0} + \dots \\
 &= y_0 + xy'_0 + \sum_{n=0}^{\infty} \frac{x^{n+2}}{(n+2)!} \frac{d^n f}{dx^n} \Big|_{x_0, y_0, y'_0}
 \end{aligned}$$

But

$$\frac{df}{dx} = \frac{\partial f}{\partial x} \frac{dx}{dx} + \frac{\partial f}{\partial y} \frac{dy}{dx} + \frac{\partial f}{\partial y'} \frac{dy'}{dx} \tag{1}$$

$$= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} y'' \tag{783}$$

$$= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} f \tag{784}$$

$$\begin{aligned}
 \frac{d^2 f}{dx^2} &= \frac{d}{dx} \left(\frac{df}{dx} \right) \\
 &= \frac{\partial}{\partial x} \left(\frac{df}{dx} \right) + \frac{\partial}{\partial y} \left(\frac{df}{dx} \right) y' + \frac{\partial}{\partial y'} \left(\frac{df}{dx} \right) f \tag{2}
 \end{aligned}$$

$$\begin{aligned}
 \frac{d^3 f}{dx^3} &= \frac{d}{dx} \left(\frac{d^2 f}{dx^2} \right) \\
 &= \frac{\partial}{\partial x} \left(\frac{d^2 f}{dx^2} \right) + \left(\frac{\partial}{\partial y} \frac{d^2 f}{dx^2} \right) y' + \frac{\partial}{\partial y'} \left(\frac{d^2 f}{dx^2} \right) f \tag{3}
 \end{aligned}$$

⋮

And so on. Hence if we name $F_0 = f(x, y, y')$ then the above can be written as

$$F_0 = f(x, y, y') \quad (4)$$

$$\begin{aligned} F_1 &= \frac{df}{dx} \\ &= \frac{dF_0}{dx} \\ &= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y}y' + \frac{\partial f}{\partial y'}y'' \\ &= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y}y' + \frac{\partial f}{\partial y'}f \\ &= \frac{\partial F_0}{\partial x} + \frac{\partial F_0}{\partial y}y' + \frac{\partial F_0}{\partial y'}F_0 \end{aligned} \quad (5)$$

$$\begin{aligned} F_2 &= \frac{d}{dx} \left(\frac{d}{dx} f \right) \\ &= \frac{d}{dx} (F_1) \\ &= \frac{\partial}{\partial x} F_1 + \left(\frac{\partial F_1}{\partial y} \right) y' + \left(\frac{\partial F_1}{\partial y'} \right) y'' \\ &= \frac{\partial}{\partial x} F_1 + \left(\frac{\partial F_1}{\partial y} \right) y' + \left(\frac{\partial F_1}{\partial y'} \right) F_0 \\ &\vdots \\ F_n &= \frac{d}{dx} (F_{n-1}) \\ &= \frac{\partial}{\partial x} F_{n-1} + \left(\frac{\partial F_{n-1}}{\partial y} \right) y' + \left(\frac{\partial F_{n-1}}{\partial y'} \right) y'' \\ &= \frac{\partial}{\partial x} F_{n-1} + \left(\frac{\partial F_{n-1}}{\partial y} \right) y' + \left(\frac{\partial F_{n-1}}{\partial y'} \right) F_0 \end{aligned} \quad (6)$$

Therefore (6) can be used from now on along with

$$y(x) = y_0 + xy'_0 + \sum_{n=0}^{\infty} \frac{x^{n+2}}{(n+2)!} F_n|_{x_0, y_0, y'_0} \quad (7)$$

To find $y(x)$ series solution around $x = 0$. Hence

$$\begin{aligned}
 F_0 &= -y'x - y \\
 F_1 &= \frac{dF_0}{dx} \\
 &= \frac{\partial F_0}{\partial x} + \frac{\partial F_0}{\partial y} y' + \frac{\partial F_0}{\partial y'} F_0 \\
 &= x^2 y' + yx - 2y' \\
 F_2 &= \frac{dF_1}{dx} \\
 &= \frac{\partial F_1}{\partial x} + \frac{\partial F_1}{\partial y} y' + \frac{\partial F_1}{\partial y'} F_1 \\
 &= -y'x^3 - x^2 y + 5y'x + 3y \\
 F_3 &= \frac{dF_2}{dx} \\
 &= \frac{\partial F_2}{\partial x} + \frac{\partial F_2}{\partial y} y' + \frac{\partial F_2}{\partial y'} F_2 \\
 &= (x^4 - 9x^2 + 8) y' + xy(x^2 - 7) \\
 F_4 &= \frac{dF_3}{dx} \\
 &= \frac{\partial F_3}{\partial x} + \frac{\partial F_3}{\partial y} y' + \frac{\partial F_3}{\partial y'} F_3 \\
 &= (-x^5 + 14x^3 - 33x) y' - y(x^4 - 12x^2 + 15)
 \end{aligned}$$

And so on. Evaluating all the above at initial conditions $x = 0$ and $y(0) = y(0)$ and $y'(0) = y'(0)$ gives

$$\begin{aligned}
 F_0 &= -y(0) \\
 F_1 &= -2y'(0) \\
 F_2 &= 3y(0) \\
 F_3 &= 8y'(0) \\
 F_4 &= -15y(0)
 \end{aligned}$$

Substituting all the above in (7) and simplifying gives the solution as

$$y = \left(1 - \frac{1}{2}x^2 + \frac{1}{8}x^4 - \frac{1}{48}x^6\right) y(0) + \left(x - \frac{1}{3}x^3 + \frac{1}{15}x^5\right) y'(0) + O(x^6)$$

Since the expansion point $x = 0$ is an ordinary, we can also solve this using standard

power series Let the solution be represented as power series of the form

$$y = \sum_{n=0}^{\infty} a_n x^n$$

Then

$$y' = \sum_{n=1}^{\infty} n a_n x^{n-1}$$

$$y'' = \sum_{n=2}^{\infty} n(n-1) a_n x^{n-2}$$

Substituting the above back into the ode gives

$$\sum_{n=2}^{\infty} n(n-1) a_n x^{n-2} = - \left(\sum_{n=1}^{\infty} n a_n x^{n-1} \right) x - \left(\sum_{n=0}^{\infty} a_n x^n \right) \quad (1)$$

Which simplifies to

$$\left(\sum_{n=2}^{\infty} n(n-1) a_n x^{n-2} \right) + \left(\sum_{n=1}^{\infty} n x^n a_n \right) + \left(\sum_{n=0}^{\infty} a_n x^n \right) = 0 \quad (2)$$

The next step is to make all powers of x be n in each summation term. Going over each summation term above with power of x in it which is not already x^n and adjusting the power and the corresponding index gives

$$\sum_{n=2}^{\infty} n(n-1) a_n x^{n-2} = \sum_{n=0}^{\infty} (n+2) a_{n+2} (n+1) x^n$$

Substituting all the above in Eq (2) gives the following equation where now all powers of x are the same and equal to n .

$$\left(\sum_{n=0}^{\infty} (n+2) a_{n+2} (n+1) x^n \right) + \left(\sum_{n=1}^{\infty} n x^n a_n \right) + \left(\sum_{n=0}^{\infty} a_n x^n \right) = 0 \quad (3)$$

$n = 0$ gives

$$2a_2 + a_0 = 0$$

$$a_2 = -\frac{a_0}{2}$$

For $1 \leq n$, the recurrence equation is

$$(n + 2) a_{n+2}(n + 1) + na_n + a_n = 0 \quad (4)$$

Solving for a_{n+2} , gives

$$a_{n+2} = -\frac{a_n}{n + 2} \quad (5)$$

For $n = 1$ the recurrence equation gives

$$6a_3 + 2a_1 = 0$$

Which after substituting the earlier terms found becomes

$$a_3 = -\frac{a_1}{3}$$

For $n = 2$ the recurrence equation gives

$$12a_4 + 3a_2 = 0$$

Which after substituting the earlier terms found becomes

$$a_4 = \frac{a_0}{8}$$

For $n = 3$ the recurrence equation gives

$$20a_5 + 4a_3 = 0$$

Which after substituting the earlier terms found becomes

$$a_5 = \frac{a_1}{15}$$

For $n = 4$ the recurrence equation gives

$$30a_6 + 5a_4 = 0$$

Which after substituting the earlier terms found becomes

$$a_6 = -\frac{a_0}{48}$$

For $n = 5$ the recurrence equation gives

$$42a_7 + 6a_5 = 0$$

Which after substituting the earlier terms found becomes

$$a_7 = -\frac{a_1}{105}$$

And so on. Therefore the solution is

$$\begin{aligned} y &= \sum_{n=0}^{\infty} a_n x^n \\ &= a_3 x^3 + a_2 x^2 + a_1 x + a_0 + \dots \end{aligned}$$

Substituting the values for a_n found above, the solution becomes

$$y = a_0 + a_1 x - \frac{1}{2} a_0 x^2 - \frac{1}{3} a_1 x^3 + \frac{1}{8} a_0 x^4 + \frac{1}{15} a_1 x^5 + \dots$$

Collecting terms, the solution becomes

$$y = \left(1 - \frac{1}{2}x^2 + \frac{1}{8}x^4\right) a_0 + \left(x - \frac{1}{3}x^3 + \frac{1}{15}x^5\right) a_1 + O(x^6) \quad (3)$$

At $x = 0$ the solution above becomes

$$y = \left(1 - \frac{1}{2}x^2 + \frac{1}{8}x^4\right) c_1 + \left(x - \frac{1}{3}x^3 + \frac{1}{15}x^5\right) c_2 + O(x^6)$$

Summary

The solution(s) found are the following

$$y = \left(1 - \frac{1}{2}x^2 + \frac{1}{8}x^4 - \frac{1}{48}x^6\right) y(0) + \left(x - \frac{1}{3}x^3 + \frac{1}{15}x^5\right) y'(0) + O(x^6) \quad (1)$$

$$y = \left(1 - \frac{1}{2}x^2 + \frac{1}{8}x^4\right) c_1 + \left(x - \frac{1}{3}x^3 + \frac{1}{15}x^5\right) c_2 + O(x^6) \quad (2)$$

Verification of solutions

$$y = \left(1 - \frac{1}{2}x^2 + \frac{1}{8}x^4 - \frac{1}{48}x^6\right) y(0) + \left(x - \frac{1}{3}x^3 + \frac{1}{15}x^5\right) y'(0) + O(x^6)$$

Verified OK.

$$y = \left(1 - \frac{1}{2}x^2 + \frac{1}{8}x^4\right) c_1 + \left(x - \frac{1}{3}x^3 + \frac{1}{15}x^5\right) c_2 + O(x^6)$$

Verified OK.

14.1.1 Maple step by step solution

Let's solve

$$y'' = -y'x - y$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + y'x + y = 0$$

- Assume series solution for y

$$y = \sum_{k=0}^{\infty} a_k x^k$$

- Rewrite DE with series expansions

- Convert $x \cdot y'$ to series expansion

$$x \cdot y' = \sum_{k=0}^{\infty} a_k k x^k$$

- Convert y'' to series expansion

$$y'' = \sum_{k=2}^{\infty} a_k k(k-1) x^{k-2}$$

- Shift index using $k- > k+2$

$$y'' = \sum_{k=0}^{\infty} a_{k+2}(k+2)(k+1) x^k$$

Rewrite DE with series expansions

$$\sum_{k=0}^{\infty} (a_{k+2}(k+2)(k+1) + a_k(k+1)) x^k = 0$$

- Each term in the series must be 0, giving the recursion relation

$$(k+1)(a_{k+2}(k+2) + a_k) = 0$$

- Recursion relation that defines the series solution to the ODE

$$\left[y = \sum_{k=0}^{\infty} a_k x^k, a_{k+2} = -\frac{a_k}{k+2} \right]$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
checking if the LODE is of Euler type  
trying a symmetry of the form [xi=0, eta=F(x)]  
<- linear_1 successful`
```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 34

```
Order:=6;  
dsolve(diff(y(x),x$2)+x*diff(y(x),x)+y(x)=0,y(x),type='series',x=0);
```

$$y(x) = \left(1 - \frac{1}{2}x^2 + \frac{1}{8}x^4\right) y(0) + \left(x - \frac{1}{3}x^3 + \frac{1}{15}x^5\right) D(y)(0) + O(x^6)$$

✓ Solution by Mathematica

Time used: 0.007 (sec). Leaf size: 42

```
AsymptoticDSolveValue[y''[x]+x*y'[x]+y[x]==0,y[x],{x,0,5}]
```

$$y(x) \rightarrow c_2 \left(\frac{x^5}{15} - \frac{x^3}{3} + x \right) + c_1 \left(\frac{x^4}{8} - \frac{x^2}{2} + 1 \right)$$

14.2 problem 2

14.2.1 Maple step by step solution 3853

Internal problem ID [11885]

Internal file name [OUTPUT/11894_Saturday_April_13_2024_01_14_16_AM_16203133/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.1. Exercises page 232

Problem number: 2.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"second order series method. Ordinary point", "second order series method. Taylor series method"**

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$y'' + 8y'x - 4y = 0$$

With the expansion point for the power series method at $x = 0$.

Solving ode using Taylor series method. This gives review on how the Taylor series method works for solving second order ode.

Let

$$y'' = f(x, y, y')$$

Assuming expansion is at $x_0 = 0$ (we can always shift the actual expansion point to 0 by change of variables) and assuming $f(x, y, y')$ is analytic at x_0 which must be the case for an ordinary point. Let initial conditions be $y(x_0) = y_0$ and $y'(x_0) = y'_0$. Using Taylor series gives

$$\begin{aligned} y(x) &= y(x_0) + (x - x_0)y'(x_0) + \frac{(x - x_0)^2}{2}y''(x_0) + \frac{(x - x_0)^3}{3!}y'''(x_0) + \cdots \\ &= y_0 + xy'_0 + \frac{x^2}{2}f|_{x_0, y_0, y'_0} + \frac{x^3}{3!}f'|_{x_0, y_0, y'_0} + \cdots \\ &= y_0 + xy'_0 + \sum_{n=0}^{\infty} \frac{x^{n+2}}{(n+2)!} \frac{d^n f}{dx^n} \Big|_{x_0, y_0, y'_0} \end{aligned}$$

But

$$\frac{df}{dx} = \frac{\partial f}{\partial x} \frac{dx}{dx} + \frac{\partial f}{\partial y} \frac{dy}{dx} + \frac{\partial f}{\partial y'} \frac{dy'}{dx} \quad (1)$$

$$= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} y'' \quad (786)$$

$$= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} f \quad (787)$$

$$\begin{aligned} \frac{d^2 f}{dx^2} &= \frac{d}{dx} \left(\frac{df}{dx} \right) \\ &= \frac{\partial}{\partial x} \left(\frac{df}{dx} \right) + \frac{\partial}{\partial y} \left(\frac{df}{dx} \right) y' + \frac{\partial}{\partial y'} \left(\frac{df}{dx} \right) f \end{aligned} \quad (2)$$

$$\begin{aligned} \frac{d^3 f}{dx^3} &= \frac{d}{dx} \left(\frac{d^2 f}{dx^2} \right) \\ &= \frac{\partial}{\partial x} \left(\frac{d^2 f}{dx^2} \right) + \left(\frac{\partial}{\partial y} \frac{d^2 f}{dx^2} \right) y' + \frac{\partial}{\partial y'} \left(\frac{d^2 f}{dx^2} \right) f \end{aligned} \quad (3)$$

⋮

And so on. Hence if we name $F_0 = f(x, y, y')$ then the above can be written as

$$F_0 = f(x, y, y') \quad (4)$$

$$\begin{aligned} F_1 &= \frac{df}{dx} \\ &= \frac{dF_0}{dx} \\ &= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} y'' \\ &= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} f \\ &= \frac{\partial F_0}{\partial x} + \frac{\partial F_0}{\partial y} y' + \frac{\partial F_0}{\partial y'} F_0 \end{aligned} \quad (5)$$

$$\begin{aligned} F_2 &= \frac{d}{dx} \left(\frac{d}{dx} f \right) \\ &= \frac{d}{dx} (F_1) \\ &= \frac{\partial}{\partial x} F_1 + \left(\frac{\partial F_1}{\partial y} \right) y' + \left(\frac{\partial F_1}{\partial y'} \right) y'' \\ &= \frac{\partial}{\partial x} F_1 + \left(\frac{\partial F_1}{\partial y} \right) y' + \left(\frac{\partial F_1}{\partial y'} \right) F_0 \\ &\vdots \\ F_n &= \frac{d}{dx} (F_{n-1}) \\ &= \frac{\partial}{\partial x} F_{n-1} + \left(\frac{\partial F_{n-1}}{\partial y} \right) y' + \left(\frac{\partial F_{n-1}}{\partial y'} \right) y'' \\ &= \frac{\partial}{\partial x} F_{n-1} + \left(\frac{\partial F_{n-1}}{\partial y} \right) y' + \left(\frac{\partial F_{n-1}}{\partial y'} \right) F_0 \end{aligned} \quad (6)$$

Therefore (6) can be used from now on along with

$$y(x) = y_0 + xy'_0 + \sum_{n=0}^{\infty} \frac{x^{n+2}}{(n+2)!} F_n|_{x_0, y_0, y'_0} \quad (7)$$

To find $y(x)$ series solution around $x = 0$. Hence

$$\begin{aligned}
 F_0 &= -8y'x + 4y \\
 F_1 &= \frac{dF_0}{dx} \\
 &= \frac{\partial F_0}{\partial x} + \frac{\partial F_0}{\partial y}y' + \frac{\partial F_0}{\partial y'}F_0 \\
 &= 64x^2y' - 32yx - 4y' \\
 F_2 &= \frac{dF_1}{dx} \\
 &= \frac{\partial F_1}{\partial x} + \frac{\partial F_1}{\partial y}y' + \frac{\partial F_1}{\partial y'}F_1 \\
 &= 128(-4x^3 + x)y' + 16y(16x^2 - 3) \\
 F_3 &= \frac{dF_2}{dx} \\
 &= \frac{\partial F_2}{\partial x} + \frac{\partial F_2}{\partial y}y' + \frac{\partial F_2}{\partial y'}F_2 \\
 &= (4096x^4 - 2304x^2 + 80)y' - 2048x\left(x^2 - \frac{1}{2}\right)y \\
 F_4 &= \frac{dF_3}{dx} \\
 &= \frac{\partial F_3}{\partial x} + \frac{\partial F_3}{\partial y}y' + \frac{\partial F_3}{\partial y'}F_3 \\
 &= (-32768x^5 + 32768x^3 - 4224x)y' + (16384x^4 - 15360x^2 + 1344)y
 \end{aligned}$$

And so on. Evaluating all the above at initial conditions $x = 0$ and $y(0) = y(0)$ and $y'(0) = y'(0)$ gives

$$\begin{aligned}
 F_0 &= 4y(0) \\
 F_1 &= -4y'(0) \\
 F_2 &= -48y(0) \\
 F_3 &= 80y'(0) \\
 F_4 &= 1344y(0)
 \end{aligned}$$

Substituting all the above in (7) and simplifying gives the solution as

$$y = \left(1 + 2x^2 - 2x^4 + \frac{28}{15}x^6\right)y(0) + \left(x - \frac{2}{3}x^3 + \frac{2}{3}x^5\right)y'(0) + O(x^6)$$

Since the expansion point $x = 0$ is an ordinary, we can also solve this using standard

power series Let the solution be represented as power series of the form

$$y = \sum_{n=0}^{\infty} a_n x^n$$

Then

$$y' = \sum_{n=1}^{\infty} n a_n x^{n-1}$$

$$y'' = \sum_{n=2}^{\infty} n(n-1) a_n x^{n-2}$$

Substituting the above back into the ode gives

$$\sum_{n=2}^{\infty} n(n-1) a_n x^{n-2} = -8 \left(\sum_{n=1}^{\infty} n a_n x^{n-1} \right) x + 4 \left(\sum_{n=0}^{\infty} a_n x^n \right) \quad (1)$$

Which simplifies to

$$\left(\sum_{n=2}^{\infty} n(n-1) a_n x^{n-2} \right) + \left(\sum_{n=1}^{\infty} 8n x^n a_n \right) + \sum_{n=0}^{\infty} (-4a_n x^n) = 0 \quad (2)$$

The next step is to make all powers of x be n in each summation term. Going over each summation term above with power of x in it which is not already x^n and adjusting the power and the corresponding index gives

$$\sum_{n=2}^{\infty} n(n-1) a_n x^{n-2} = \sum_{n=0}^{\infty} (n+2) a_{n+2} (n+1) x^n$$

Substituting all the above in Eq (2) gives the following equation where now all powers of x are the same and equal to n .

$$\left(\sum_{n=0}^{\infty} (n+2) a_{n+2} (n+1) x^n \right) + \left(\sum_{n=1}^{\infty} 8n x^n a_n \right) + \sum_{n=0}^{\infty} (-4a_n x^n) = 0 \quad (3)$$

$n = 0$ gives

$$2a_2 - 4a_0 = 0$$

$$a_2 = 2a_0$$

For $1 \leq n$, the recurrence equation is

$$(n + 2) a_{n+2}(n + 1) + 8na_n - 4a_n = 0 \quad (4)$$

Solving for a_{n+2} , gives

$$a_{n+2} = -\frac{4a_n(2n - 1)}{(n + 2)(n + 1)} \quad (5)$$

For $n = 1$ the recurrence equation gives

$$6a_3 + 4a_1 = 0$$

Which after substituting the earlier terms found becomes

$$a_3 = -\frac{2a_1}{3}$$

For $n = 2$ the recurrence equation gives

$$12a_4 + 12a_2 = 0$$

Which after substituting the earlier terms found becomes

$$a_4 = -2a_0$$

For $n = 3$ the recurrence equation gives

$$20a_5 + 20a_3 = 0$$

Which after substituting the earlier terms found becomes

$$a_5 = \frac{2a_1}{3}$$

For $n = 4$ the recurrence equation gives

$$30a_6 + 28a_4 = 0$$

Which after substituting the earlier terms found becomes

$$a_6 = \frac{28a_0}{15}$$

For $n = 5$ the recurrence equation gives

$$42a_7 + 36a_5 = 0$$

Which after substituting the earlier terms found becomes

$$a_7 = -\frac{4a_1}{7}$$

And so on. Therefore the solution is

$$\begin{aligned} y &= \sum_{n=0}^{\infty} a_n x^n \\ &= a_3 x^3 + a_2 x^2 + a_1 x + a_0 + \dots \end{aligned}$$

Substituting the values for a_n found above, the solution becomes

$$y = a_0 + a_1 x + 2a_0 x^2 - \frac{2}{3} a_1 x^3 - 2a_0 x^4 + \frac{2}{3} a_1 x^5 + \dots$$

Collecting terms, the solution becomes

$$y = (-2x^4 + 2x^2 + 1) a_0 + \left(x - \frac{2}{3}x^3 + \frac{2}{3}x^5 \right) a_1 + O(x^6) \quad (3)$$

At $x = 0$ the solution above becomes

$$y = (-2x^4 + 2x^2 + 1) c_1 + \left(x - \frac{2}{3}x^3 + \frac{2}{3}x^5 \right) c_2 + O(x^6)$$

Summary

The solution(s) found are the following

$$y = \left(1 + 2x^2 - 2x^4 + \frac{28}{15}x^6 \right) y(0) + \left(x - \frac{2}{3}x^3 + \frac{2}{3}x^5 \right) y'(0) + O(x^6) \quad (1)$$

$$y = (-2x^4 + 2x^2 + 1) c_1 + \left(x - \frac{2}{3}x^3 + \frac{2}{3}x^5 \right) c_2 + O(x^6) \quad (2)$$

Verification of solutions

$$y = \left(1 + 2x^2 - 2x^4 + \frac{28}{15}x^6 \right) y(0) + \left(x - \frac{2}{3}x^3 + \frac{2}{3}x^5 \right) y'(0) + O(x^6)$$

Verified OK.

$$y = (-2x^4 + 2x^2 + 1) c_1 + \left(x - \frac{2}{3}x^3 + \frac{2}{3}x^5 \right) c_2 + O(x^6)$$

Verified OK.

14.2.1 Maple step by step solution

Let's solve

$$y'' = -8y'x + 4y$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + 8y'x - 4y = 0$$

- Assume series solution for y

$$y = \sum_{k=0}^{\infty} a_k x^k$$

- Rewrite DE with series expansions

- Convert $x \cdot y'$ to series expansion

$$x \cdot y' = \sum_{k=0}^{\infty} a_k k x^k$$

- Convert y'' to series expansion

$$y'' = \sum_{k=2}^{\infty} a_k k(k-1) x^{k-2}$$

- Shift index using $k- > k+2$

$$y'' = \sum_{k=0}^{\infty} a_{k+2}(k+2)(k+1) x^k$$

Rewrite DE with series expansions

$$\sum_{k=0}^{\infty} (a_{k+2}(k+2)(k+1) + 4a_k(2k-1)) x^k = 0$$

- Each term in the series must be 0, giving the recursion relation

$$(k^2 + 3k + 2) a_{k+2} + 8a_k k - 4a_k = 0$$

- Recursion relation that defines the series solution to the ODE

$$\left[y = \sum_{k=0}^{\infty} a_k x^k, a_{k+2} = -\frac{4a_k(2k-1)}{k^2+3k+2} \right]$$

Maple trace

```
`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
trying a symmetry of the form [xi=0, eta=F(x)]
checking if the LODE is missing y
-> Trying a Liouvillian solution using Kovacic's algorithm
<- No Liouvillian solutions exist
-> Trying a solution in terms of special functions:
    -> Bessel
    -> elliptic
    -> Legendre
    <- Kummer successful
<- special function solution successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 34

```
Order:=6;
dsolve(diff(y(x),x$2)+8*x*diff(y(x),x)-4*y(x)=0,y(x),type='series',x=0);
```

$$y(x) = (-2x^4 + 2x^2 + 1) y(0) + \left(x - \frac{2}{3}x^3 + \frac{2}{3}x^5 \right) D(y)(0) + O(x^6)$$

✓ Solution by Mathematica

Time used: 0.001 (sec). Leaf size: 38

```
AsymptoticDSolveValue[y''[x]+8*x*y'[x]-4*y[x]==0,y[x],{x,0,5}]
```

$$y(x) \rightarrow c_2 \left(\frac{2x^5}{3} - \frac{2x^3}{3} + x \right) + c_1 (-2x^4 + 2x^2 + 1)$$

14.3 problem 3

14.3.1 Maple step by step solution 3862

Internal problem ID [11886]

Internal file name [OUTPUT/11895_Saturday_April_13_2024_01_14_17_AM_52170285/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.1. Exercises page 232

Problem number: 3.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"second order series method. Ordinary point", "second order series method. Taylor series method"**

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$y'' + y'x + (2x^2 + 1)y = 0$$

With the expansion point for the power series method at $x = 0$.

Solving ode using Taylor series method. This gives review on how the Taylor series method works for solving second order ode.

Let

$$y'' = f(x, y, y')$$

Assuming expansion is at $x_0 = 0$ (we can always shift the actual expansion point to 0 by change of variables) and assuming $f(x, y, y')$ is analytic at x_0 which must be the case for an ordinary point. Let initial conditions be $y(x_0) = y_0$ and $y'(x_0) = y'_0$. Using Taylor series gives

$$\begin{aligned} y(x) &= y(x_0) + (x - x_0)y'(x_0) + \frac{(x - x_0)^2}{2}y''(x_0) + \frac{(x - x_0)^3}{3!}y'''(x_0) + \cdots \\ &= y_0 + xy'_0 + \frac{x^2}{2}f|_{x_0, y_0, y'_0} + \frac{x^3}{3!}f'|_{x_0, y_0, y'_0} + \cdots \\ &= y_0 + xy'_0 + \sum_{n=0}^{\infty} \frac{x^{n+2}}{(n+2)!} \frac{d^n f}{dx^n} \Big|_{x_0, y_0, y'_0} \end{aligned}$$

But

$$\frac{df}{dx} = \frac{\partial f}{\partial x} \frac{dx}{dx} + \frac{\partial f}{\partial y} \frac{dy}{dx} + \frac{\partial f}{\partial y'} \frac{dy'}{dx} \quad (1)$$

$$= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} y'' \quad (789)$$

$$= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} f \quad (790)$$

$$\begin{aligned} \frac{d^2 f}{dx^2} &= \frac{d}{dx} \left(\frac{df}{dx} \right) \\ &= \frac{\partial}{\partial x} \left(\frac{df}{dx} \right) + \frac{\partial}{\partial y} \left(\frac{df}{dx} \right) y' + \frac{\partial}{\partial y'} \left(\frac{df}{dx} \right) f \end{aligned} \quad (2)$$

$$\begin{aligned} \frac{d^3 f}{dx^3} &= \frac{d}{dx} \left(\frac{d^2 f}{dx^2} \right) \\ &= \frac{\partial}{\partial x} \left(\frac{d^2 f}{dx^2} \right) + \left(\frac{\partial}{\partial y} \frac{d^2 f}{dx^2} \right) y' + \frac{\partial}{\partial y'} \left(\frac{d^2 f}{dx^2} \right) f \end{aligned} \quad (3)$$

⋮

And so on. Hence if we name $F_0 = f(x, y, y')$ then the above can be written as

$$F_0 = f(x, y, y') \tag{4}$$

$$\begin{aligned} F_1 &= \frac{df}{dx} \\ &= \frac{dF_0}{dx} \\ &= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y}y' + \frac{\partial f}{\partial y'}y'' \\ &= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y}y' + \frac{\partial f}{\partial y'}f \\ &= \frac{\partial F_0}{\partial x} + \frac{\partial F_0}{\partial y}y' + \frac{\partial F_0}{\partial y'}F_0 \end{aligned} \tag{5}$$

$$\begin{aligned} F_2 &= \frac{d}{dx} \left(\frac{d}{dx} f \right) \\ &= \frac{d}{dx} (F_1) \\ &= \frac{\partial}{\partial x} F_1 + \left(\frac{\partial F_1}{\partial y} \right) y' + \left(\frac{\partial F_1}{\partial y'} \right) y'' \\ &= \frac{\partial}{\partial x} F_1 + \left(\frac{\partial F_1}{\partial y} \right) y' + \left(\frac{\partial F_1}{\partial y'} \right) F_0 \end{aligned}$$

⋮

$$\begin{aligned} F_n &= \frac{d}{dx} (F_{n-1}) \\ &= \frac{\partial}{\partial x} F_{n-1} + \left(\frac{\partial F_{n-1}}{\partial y} \right) y' + \left(\frac{\partial F_{n-1}}{\partial y'} \right) y'' \\ &= \frac{\partial}{\partial x} F_{n-1} + \left(\frac{\partial F_{n-1}}{\partial y} \right) y' + \left(\frac{\partial F_{n-1}}{\partial y'} \right) F_0 \end{aligned} \tag{6}$$

Therefore (6) can be used from now on along with

$$y(x) = y_0 + xy'_0 + \sum_{n=0}^{\infty} \frac{x^{n+2}}{(n+2)!} F_n|_{x_0, y_0, y'_0} \tag{7}$$

To find $y(x)$ series solution around $x = 0$. Hence

$$\begin{aligned}
 F_0 &= -2x^2y - y'x - y \\
 F_1 &= \frac{dF_0}{dx} \\
 &= \frac{\partial F_0}{\partial x} + \frac{\partial F_0}{\partial y}y' + \frac{\partial F_0}{\partial y'}F_0 \\
 &= 2yx^3 - x^2y' - 3yx - 2y' \\
 F_2 &= \frac{dF_1}{dx} \\
 &= \frac{\partial F_1}{\partial x} + \frac{\partial F_1}{\partial y}y' + \frac{\partial F_1}{\partial y'}F_1 \\
 &= (3x^3 - 3x)y' + y(2x^4 + 11x^2 - 1) \\
 F_3 &= \frac{dF_2}{dx} \\
 &= \frac{\partial F_2}{\partial x} + \frac{\partial F_2}{\partial y}y' + \frac{\partial F_2}{\partial y'}F_2 \\
 &= (-x^4 + 23x^2 - 4)y' - 6xy\left(x^4 - \frac{11}{6}x^2 - \frac{25}{6}\right) \\
 F_4 &= \frac{dF_3}{dx} \\
 &= \frac{\partial F_3}{\partial x} + \frac{\partial F_3}{\partial y}y' + \frac{\partial F_3}{\partial y'}F_3 \\
 &= (-5x^5 - 16x^3 + 75x)y' + 2\left(x^6 - \frac{75}{2}x^4 + 9x^2 + \frac{29}{2}\right)y
 \end{aligned}$$

And so on. Evaluating all the above at initial conditions $x = 0$ and $y(0) = y(0)$ and $y'(0) = y'(0)$ gives

$$\begin{aligned}
 F_0 &= -y(0) \\
 F_1 &= -2y'(0) \\
 F_2 &= -y(0) \\
 F_3 &= -4y'(0) \\
 F_4 &= 29y(0)
 \end{aligned}$$

Substituting all the above in (7) and simplifying gives the solution as

$$y = \left(1 - \frac{1}{2}x^2 - \frac{1}{24}x^4 + \frac{29}{720}x^6\right)y(0) + \left(x - \frac{1}{3}x^3 - \frac{1}{30}x^5\right)y'(0) + O(x^6)$$

Since the expansion point $x = 0$ is an ordinary, we can also solve this using standard power series. Let the solution be represented as power series of the form

$$y = \sum_{n=0}^{\infty} a_n x^n$$

Then

$$y' = \sum_{n=1}^{\infty} n a_n x^{n-1}$$

$$y'' = \sum_{n=2}^{\infty} n(n-1) a_n x^{n-2}$$

Substituting the above back into the ode gives

$$\sum_{n=2}^{\infty} n(n-1) a_n x^{n-2} = -2x^2 \left(\sum_{n=0}^{\infty} a_n x^n \right) - \left(\sum_{n=1}^{\infty} n a_n x^{n-1} \right) x - \left(\sum_{n=0}^{\infty} a_n x^n \right) \quad (1)$$

Which simplifies to

$$\left(\sum_{n=2}^{\infty} n(n-1) a_n x^{n-2} \right) + \left(\sum_{n=1}^{\infty} n x^n a_n \right) + \left(\sum_{n=0}^{\infty} 2x^{n+2} a_n \right) + \left(\sum_{n=0}^{\infty} a_n x^n \right) = 0 \quad (2)$$

The next step is to make all powers of x be n in each summation term. Going over each summation term above with power of x in it which is not already x^n and adjusting the power and the corresponding index gives

$$\sum_{n=2}^{\infty} n(n-1) a_n x^{n-2} = \sum_{n=0}^{\infty} (n+2) a_{n+2} (n+1) x^n$$

$$\sum_{n=0}^{\infty} 2x^{n+2} a_n = \sum_{n=2}^{\infty} 2a_{n-2} x^n$$

Substituting all the above in Eq (2) gives the following equation where now all powers of x are the same and equal to n .

$$\left(\sum_{n=0}^{\infty} (n+2) a_{n+2} (n+1) x^n \right) + \left(\sum_{n=1}^{\infty} n x^n a_n \right) + \left(\sum_{n=2}^{\infty} 2a_{n-2} x^n \right) + \left(\sum_{n=0}^{\infty} a_n x^n \right) = 0 \quad (3)$$

$n = 0$ gives

$$2a_2 + a_0 = 0$$

$$a_2 = -\frac{a_0}{2}$$

$n = 1$ gives

$$6a_3 + 2a_1 = 0$$

Which after substituting earlier equations, simplifies to

$$a_3 = -\frac{a_1}{3}$$

For $2 \leq n$, the recurrence equation is

$$(n + 2) a_{n+2}(n + 1) + na_n + 2a_{n-2} + a_n = 0 \quad (4)$$

Solving for a_{n+2} , gives

$$\begin{aligned} a_{n+2} &= -\frac{na_n + a_n + 2a_{n-2}}{(n + 2)(n + 1)} \\ (5) \quad &= -\frac{a_n}{n + 2} - \frac{2a_{n-2}}{(n + 2)(n + 1)} \end{aligned}$$

For $n = 2$ the recurrence equation gives

$$12a_4 + 3a_2 + 2a_0 = 0$$

Which after substituting the earlier terms found becomes

$$a_4 = -\frac{a_0}{24}$$

For $n = 3$ the recurrence equation gives

$$20a_5 + 4a_3 + 2a_1 = 0$$

Which after substituting the earlier terms found becomes

$$a_5 = -\frac{a_1}{30}$$

For $n = 4$ the recurrence equation gives

$$30a_6 + 5a_4 + 2a_2 = 0$$

Which after substituting the earlier terms found becomes

$$a_6 = \frac{29a_0}{720}$$

For $n = 5$ the recurrence equation gives

$$42a_7 + 6a_5 + 2a_3 = 0$$

Which after substituting the earlier terms found becomes

$$a_7 = \frac{13a_1}{630}$$

And so on. Therefore the solution is

$$\begin{aligned} y &= \sum_{n=0}^{\infty} a_n x^n \\ &= a_3 x^3 + a_2 x^2 + a_1 x + a_0 + \dots \end{aligned}$$

Substituting the values for a_n found above, the solution becomes

$$y = a_0 + a_1 x - \frac{1}{2} a_0 x^2 - \frac{1}{3} a_1 x^3 - \frac{1}{24} a_0 x^4 - \frac{1}{30} a_1 x^5 + \dots$$

Collecting terms, the solution becomes

$$y = \left(1 - \frac{1}{2}x^2 - \frac{1}{24}x^4\right) a_0 + \left(x - \frac{1}{3}x^3 - \frac{1}{30}x^5\right) a_1 + O(x^6) \quad (3)$$

At $x = 0$ the solution above becomes

$$y = \left(1 - \frac{1}{2}x^2 - \frac{1}{24}x^4\right) c_1 + \left(x - \frac{1}{3}x^3 - \frac{1}{30}x^5\right) c_2 + O(x^6)$$

Summary

The solution(s) found are the following

$$y = \left(1 - \frac{1}{2}x^2 - \frac{1}{24}x^4 + \frac{29}{720}x^6\right) y(0) + \left(x - \frac{1}{3}x^3 - \frac{1}{30}x^5\right) y'(0) + O(x^6) \quad (1)$$

$$y = \left(1 - \frac{1}{2}x^2 - \frac{1}{24}x^4\right) c_1 + \left(x - \frac{1}{3}x^3 - \frac{1}{30}x^5\right) c_2 + O(x^6) \quad (2)$$

Verification of solutions

$$y = \left(1 - \frac{1}{2}x^2 - \frac{1}{24}x^4 + \frac{29}{720}x^6\right) y(0) + \left(x - \frac{1}{3}x^3 - \frac{1}{30}x^5\right) y'(0) + O(x^6)$$

Verified OK.

$$y = \left(1 - \frac{1}{2}x^2 - \frac{1}{24}x^4\right) c_1 + \left(x - \frac{1}{3}x^3 - \frac{1}{30}x^5\right) c_2 + O(x^6)$$

Verified OK.

14.3.1 Maple step by step solution

Let's solve

$$y'' = -2x^2y - y'x - y$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = (-2x^2 - 1)y - y'x$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + y'x + (2x^2 + 1)y = 0$$

- Assume series solution for y

$$y = \sum_{k=0}^{\infty} a_k x^k$$

- Rewrite ODE with series expansions

- Convert $x^m \cdot y$ to series expansion for $m = 0..2$

$$x^m \cdot y = \sum_{k=\max(0,-m)}^{\infty} a_k x^{k+m}$$

- Shift index using $k- > k - m$

$$x^m \cdot y = \sum_{k=\max(0,-m)+m}^{\infty} a_{k-m} x^k$$

- Convert $x \cdot y'$ to series expansion

$$x \cdot y' = \sum_{k=0}^{\infty} a_k k x^k$$

- Convert y'' to series expansion

$$y'' = \sum_{k=2}^{\infty} a_k k(k-1) x^{k-2}$$

- Shift index using $k- > k+2$

$$y'' = \sum_{k=0}^{\infty} a_{k+2}(k+2)(k+1) x^k$$

Rewrite ODE with series expansions

$$2a_2 + a_0 + (6a_3 + 2a_1)x + \left(\sum_{k=2}^{\infty} (a_{k+2}(k+2)(k+1) + a_k(k+1) + 2a_{k-2}) x^k \right) = 0$$

- The coefficients of each power of x must be 0
 $[2a_2 + a_0 = 0, 6a_3 + 2a_1 = 0]$
- Solve for the dependent coefficient(s)
 $\{a_2 = -\frac{a_0}{2}, a_3 = -\frac{a_1}{3}\}$
- Each term in the series must be 0, giving the recursion relation
 $(k^2 + 3k + 2) a_{k+2} + a_k k + a_k + 2a_{k-2} = 0$
- Shift index using $k- > k+2$
 $((k+2)^2 + 3k + 8) a_{k+4} + a_{k+2}(k+2) + a_{k+2} + 2a_k = 0$
- Recursion relation that defines the series solution to the ODE

$$\left[y = \sum_{k=0}^{\infty} a_k x^k, a_{k+4} = -\frac{ka_{k+2} + 2a_k + 3a_{k+2}}{k^2 + 7k + 12}, a_2 = -\frac{a_0}{2}, a_3 = -\frac{a_1}{3} \right]$$

Maple trace

```
`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
trying a symmetry of the form [xi=0, eta=F(x)]
checking if the LODE is missing y
-> Trying a Liouvillian solution using Kovacic's algorithm
<- No Liouvillian solutions exist
-> Trying a solution in terms of special functions:
  -> Bessel
  -> elliptic
  -> Legendre
  -> Kummer
      -> hyper3: Equivalence to 1F1 under a power @ Moebius
      <- hyper3 successful: received ODE is equivalent to the 1F1 ODE
      <- Kummer successful
<- special function solution successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 34

```
Order:=6;
dsolve(diff(y(x),x$2)+x*diff(y(x),x)+(2*x^2+1)*y(x)=0,y(x),type='series',x=0);
```

$$y(x) = \left(1 - \frac{1}{2}x^2 - \frac{1}{24}x^4\right) y(0) + \left(x - \frac{1}{3}x^3 - \frac{1}{30}x^5\right) D(y)(0) + O(x^6)$$

✓ Solution by Mathematica

Time used: 0.001 (sec). Leaf size: 42

```
AsymptoticDSolveValue[y''[x]+x*y'[x]+(2*x^2+1)*y[x]==0,y[x],{x,0,5}]
```

$$y(x) \rightarrow c_2 \left(-\frac{x^5}{30} - \frac{x^3}{3} + x \right) + c_1 \left(-\frac{x^4}{24} - \frac{x^2}{2} + 1 \right)$$

14.4 problem 4

14.4.1 Maple step by step solution 3872

Internal problem ID [11887]

Internal file name [OUTPUT/11896_Saturday_April_13_2024_01_14_18_AM_24910550/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.1. Exercises page 232

Problem number: 4.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"second order series method. Ordinary point", "second order series method. Taylor series method"**

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$y'' + y'x + (x^2 - 4)y = 0$$

With the expansion point for the power series method at $x = 0$.

Solving ode using Taylor series method. This gives review on how the Taylor series method works for solving second order ode.

Let

$$y'' = f(x, y, y')$$

Assuming expansion is at $x_0 = 0$ (we can always shift the actual expansion point to 0 by change of variables) and assuming $f(x, y, y')$ is analytic at x_0 which must be the case for an ordinary point. Let initial conditions be $y(x_0) = y_0$ and $y'(x_0) = y'_0$. Using Taylor series gives

$$\begin{aligned} y(x) &= y(x_0) + (x - x_0)y'(x_0) + \frac{(x - x_0)^2}{2}y''(x_0) + \frac{(x - x_0)^3}{3!}y'''(x_0) + \cdots \\ &= y_0 + xy'_0 + \frac{x^2}{2}f|_{x_0, y_0, y'_0} + \frac{x^3}{3!}f'|_{x_0, y_0, y'_0} + \cdots \\ &= y_0 + xy'_0 + \sum_{n=0}^{\infty} \frac{x^{n+2}}{(n+2)!} \frac{d^n f}{dx^n} \Big|_{x_0, y_0, y'_0} \end{aligned}$$

But

$$\frac{df}{dx} = \frac{\partial f}{\partial x} \frac{dx}{dx} + \frac{\partial f}{\partial y} \frac{dy}{dx} + \frac{\partial f}{\partial y'} \frac{dy'}{dx} \quad (1)$$

$$= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} y'' \quad (792)$$

$$= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} f \quad (793)$$

$$\begin{aligned} \frac{d^2 f}{dx^2} &= \frac{d}{dx} \left(\frac{df}{dx} \right) \\ &= \frac{\partial}{\partial x} \left(\frac{df}{dx} \right) + \frac{\partial}{\partial y} \left(\frac{df}{dx} \right) y' + \frac{\partial}{\partial y'} \left(\frac{df}{dx} \right) f \end{aligned} \quad (2)$$

$$\begin{aligned} \frac{d^3 f}{dx^3} &= \frac{d}{dx} \left(\frac{d^2 f}{dx^2} \right) \\ &= \frac{\partial}{\partial x} \left(\frac{d^2 f}{dx^2} \right) + \left(\frac{\partial}{\partial y} \frac{d^2 f}{dx^2} \right) y' + \frac{\partial}{\partial y'} \left(\frac{d^2 f}{dx^2} \right) f \end{aligned} \quad (3)$$

⋮

And so on. Hence if we name $F_0 = f(x, y, y')$ then the above can be written as

$$F_0 = f(x, y, y') \quad (4)$$

$$\begin{aligned} F_1 &= \frac{df}{dx} \\ &= \frac{dF_0}{dx} \\ &= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y}y' + \frac{\partial f}{\partial y'}y'' \\ &= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y}y' + \frac{\partial f}{\partial y'}f \\ &= \frac{\partial F_0}{\partial x} + \frac{\partial F_0}{\partial y}y' + \frac{\partial F_0}{\partial y'}F_0 \end{aligned} \quad (5)$$

$$\begin{aligned} F_2 &= \frac{d}{dx} \left(\frac{d}{dx} f \right) \\ &= \frac{d}{dx} (F_1) \\ &= \frac{\partial}{\partial x} F_1 + \left(\frac{\partial F_1}{\partial y} \right) y' + \left(\frac{\partial F_1}{\partial y'} \right) y'' \\ &= \frac{\partial}{\partial x} F_1 + \left(\frac{\partial F_1}{\partial y} \right) y' + \left(\frac{\partial F_1}{\partial y'} \right) F_0 \\ &\vdots \\ F_n &= \frac{d}{dx} (F_{n-1}) \\ &= \frac{\partial}{\partial x} F_{n-1} + \left(\frac{\partial F_{n-1}}{\partial y} \right) y' + \left(\frac{\partial F_{n-1}}{\partial y'} \right) y'' \\ &= \frac{\partial}{\partial x} F_{n-1} + \left(\frac{\partial F_{n-1}}{\partial y} \right) y' + \left(\frac{\partial F_{n-1}}{\partial y'} \right) F_0 \end{aligned} \quad (6)$$

Therefore (6) can be used from now on along with

$$y(x) = y_0 + xy'_0 + \sum_{n=0}^{\infty} \frac{x^{n+2}}{(n+2)!} F_n|_{x_0, y_0, y'_0} \quad (7)$$

To find $y(x)$ series solution around $x = 0$. Hence

$$\begin{aligned}
 F_0 &= -x^2y - y'x + 4y \\
 F_1 &= \frac{dF_0}{dx} \\
 &= \frac{\partial F_0}{\partial x} + \frac{\partial F_0}{\partial y}y' + \frac{\partial F_0}{\partial y'}F_0 \\
 &= 3y' + (x^3 - 6x)y \\
 F_2 &= \frac{dF_1}{dx} \\
 &= \frac{\partial F_1}{\partial x} + \frac{\partial F_1}{\partial y}y' + \frac{\partial F_1}{\partial y'}F_1 \\
 &= (x^3 - 9x)y' + 6y \\
 F_3 &= \frac{dF_2}{dx} \\
 &= \frac{\partial F_2}{\partial x} + \frac{\partial F_2}{\partial y}y' + \frac{\partial F_2}{\partial y'}F_2 \\
 &= (-x^4 + 12x^2 - 3)y' + (-x^5 + 13x^3 - 36x)y \\
 F_4 &= \frac{dF_3}{dx} \\
 &= \frac{\partial F_3}{\partial x} + \frac{\partial F_3}{\partial y}y' + \frac{\partial F_3}{\partial y'}F_3 \\
 &= (-3x^3 - 9x)y' + y(x^6 - 21x^4 + 90x^2 - 48)
 \end{aligned}$$

And so on. Evaluating all the above at initial conditions $x = 0$ and $y(0) = y(0)$ and $y'(0) = y'(0)$ gives

$$\begin{aligned}
 F_0 &= 4y(0) \\
 F_1 &= 3y'(0) \\
 F_2 &= 6y(0) \\
 F_3 &= -3y'(0) \\
 F_4 &= -48y(0)
 \end{aligned}$$

Substituting all the above in (7) and simplifying gives the solution as

$$y = \left(1 + 2x^2 + \frac{1}{4}x^4 - \frac{1}{15}x^6\right)y(0) + \left(x + \frac{1}{2}x^3 - \frac{1}{40}x^5\right)y'(0) + O(x^6)$$

Since the expansion point $x = 0$ is an ordinary, we can also solve this using standard

power series Let the solution be represented as power series of the form

$$y = \sum_{n=0}^{\infty} a_n x^n$$

Then

$$y' = \sum_{n=1}^{\infty} n a_n x^{n-1}$$

$$y'' = \sum_{n=2}^{\infty} n(n-1) a_n x^{n-2}$$

Substituting the above back into the ode gives

$$\sum_{n=2}^{\infty} n(n-1) a_n x^{n-2} = -x^2 \left(\sum_{n=0}^{\infty} a_n x^n \right) - \left(\sum_{n=1}^{\infty} n a_n x^{n-1} \right) x + 4 \left(\sum_{n=0}^{\infty} a_n x^n \right) \quad (1)$$

Which simplifies to

$$\left(\sum_{n=2}^{\infty} n(n-1) a_n x^{n-2} \right) + \left(\sum_{n=1}^{\infty} n x^n a_n \right) + \left(\sum_{n=0}^{\infty} x^{n+2} a_n \right) + \sum_{n=0}^{\infty} (-4a_n x^n) = 0 \quad (2)$$

The next step is to make all powers of x be n in each summation term. Going over each summation term above with power of x in it which is not already x^n and adjusting the power and the corresponding index gives

$$\sum_{n=2}^{\infty} n(n-1) a_n x^{n-2} = \sum_{n=0}^{\infty} (n+2) a_{n+2} (n+1) x^n$$

$$\sum_{n=0}^{\infty} x^{n+2} a_n = \sum_{n=2}^{\infty} a_{n-2} x^n$$

Substituting all the above in Eq (2) gives the following equation where now all powers of x are the same and equal to n .

$$\left(\sum_{n=0}^{\infty} (n+2) a_{n+2} (n+1) x^n \right) + \left(\sum_{n=1}^{\infty} n x^n a_n \right) + \left(\sum_{n=2}^{\infty} a_{n-2} x^n \right) + \sum_{n=0}^{\infty} (-4a_n x^n) = 0 \quad (3)$$

$n = 0$ gives

$$2a_2 - 4a_0 = 0$$

$$a_2 = 2a_0$$

$n = 1$ gives

$$6a_3 - 3a_1 = 0$$

Which after substituting earlier equations, simplifies to

$$a_3 = \frac{a_1}{2}$$

For $2 \leq n$, the recurrence equation is

$$(n + 2) a_{n+2}(n + 1) + na_n + a_{n-2} - 4a_n = 0 \quad (4)$$

Solving for a_{n+2} , gives

$$\begin{aligned} a_{n+2} &= -\frac{na_n - 4a_n + a_{n-2}}{(n + 2)(n + 1)} \\ (5) \quad &= -\frac{(n - 4)a_n}{(n + 2)(n + 1)} - \frac{a_{n-2}}{(n + 2)(n + 1)} \end{aligned}$$

For $n = 2$ the recurrence equation gives

$$12a_4 - 2a_2 + a_0 = 0$$

Which after substituting the earlier terms found becomes

$$a_4 = \frac{a_0}{4}$$

For $n = 3$ the recurrence equation gives

$$20a_5 - a_3 + a_1 = 0$$

Which after substituting the earlier terms found becomes

$$a_5 = -\frac{a_1}{40}$$

For $n = 4$ the recurrence equation gives

$$30a_6 + a_2 = 0$$

Which after substituting the earlier terms found becomes

$$a_6 = -\frac{a_0}{15}$$

For $n = 5$ the recurrence equation gives

$$42a_7 + a_5 + a_3 = 0$$

Which after substituting the earlier terms found becomes

$$a_7 = -\frac{19a_1}{1680}$$

And so on. Therefore the solution is

$$\begin{aligned} y &= \sum_{n=0}^{\infty} a_n x^n \\ &= a_3 x^3 + a_2 x^2 + a_1 x + a_0 + \dots \end{aligned}$$

Substituting the values for a_n found above, the solution becomes

$$y = a_0 + a_1 x + 2a_0 x^2 + \frac{1}{2} a_1 x^3 + \frac{1}{4} a_0 x^4 - \frac{1}{40} a_1 x^5 + \dots$$

Collecting terms, the solution becomes

$$y = \left(1 + 2x^2 + \frac{1}{4}x^4\right) a_0 + \left(x + \frac{1}{2}x^3 - \frac{1}{40}x^5\right) a_1 + O(x^6) \quad (3)$$

At $x = 0$ the solution above becomes

$$y = \left(1 + 2x^2 + \frac{1}{4}x^4\right) c_1 + \left(x + \frac{1}{2}x^3 - \frac{1}{40}x^5\right) c_2 + O(x^6)$$

Summary

The solution(s) found are the following

$$y = \left(1 + 2x^2 + \frac{1}{4}x^4 - \frac{1}{15}x^6\right) y(0) + \left(x + \frac{1}{2}x^3 - \frac{1}{40}x^5\right) y'(0) + O(x^6) \quad (1)$$

$$y = \left(1 + 2x^2 + \frac{1}{4}x^4\right) c_1 + \left(x + \frac{1}{2}x^3 - \frac{1}{40}x^5\right) c_2 + O(x^6) \quad (2)$$

Verification of solutions

$$y = \left(1 + 2x^2 + \frac{1}{4}x^4 - \frac{1}{15}x^6\right) y(0) + \left(x + \frac{1}{2}x^3 - \frac{1}{40}x^5\right) y'(0) + O(x^6)$$

Verified OK.

$$y = \left(1 + 2x^2 + \frac{1}{4}x^4\right) c_1 + \left(x + \frac{1}{2}x^3 - \frac{1}{40}x^5\right) c_2 + O(x^6)$$

Verified OK.

14.4.1 Maple step by step solution

Let's solve

$$y'' = -x^2y - y'x + 4y$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = (-x^2 + 4)y - y'x$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + y'x + (x^2 - 4)y = 0$$

- Assume series solution for y

$$y = \sum_{k=0}^{\infty} a_k x^k$$

- Rewrite ODE with series expansions

- Convert $x^m \cdot y$ to series expansion for $m = 0..2$

$$x^m \cdot y = \sum_{k=\max(0,-m)}^{\infty} a_k x^{k+m}$$

- Shift index using $k- \rightarrow k - m$

$$x^m \cdot y = \sum_{k=\max(0,-m)+m}^{\infty} a_{k-m} x^k$$

- Convert $x \cdot y'$ to series expansion

$$x \cdot y' = \sum_{k=0}^{\infty} a_k k x^k$$

- Convert y'' to series expansion

$$y'' = \sum_{k=2}^{\infty} a_k k(k-1) x^{k-2}$$

- Shift index using $k \rightarrow k+2$

$$y'' = \sum_{k=0}^{\infty} a_{k+2}(k+2)(k+1) x^k$$

Rewrite ODE with series expansions

$$2a_2 - 4a_0 + (6a_3 - 3a_1)x + \left(\sum_{k=2}^{\infty} (a_{k+2}(k+2)(k+1) + a_k(k-4) + a_{k-2}) x^k \right) = 0$$

- The coefficients of each power of x must be 0
 $[2a_2 - 4a_0 = 0, 6a_3 - 3a_1 = 0]$
- Solve for the dependent coefficient(s)
 $\{a_2 = 2a_0, a_3 = \frac{a_1}{2}\}$
- Each term in the series must be 0, giving the recursion relation
 $(k^2 + 3k + 2) a_{k+2} + a_k k - 4a_k + a_{k-2} = 0$
- Shift index using $k \rightarrow k+2$
 $((k+2)^2 + 3k + 8) a_{k+4} + a_{k+2}(k+2) - 4a_{k+2} + a_k = 0$
- Recursion relation that defines the series solution to the ODE

$$\left[y = \sum_{k=0}^{\infty} a_k x^k, a_{k+4} = -\frac{ka_{k+2} + a_k - 2a_{k+2}}{k^2 + 7k + 12}, a_2 = 2a_0, a_3 = \frac{a_1}{2} \right]$$

Maple trace

```
`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
trying a symmetry of the form [xi=0, eta=F(x)]
checking if the LODE is missing y
-> Trying a Liouvillian solution using Kovacic's algorithm
<- No Liouvillian solutions exist
-> Trying a solution in terms of special functions:
  -> Bessel
  -> elliptic
  -> Legendre
  -> Kummer
      -> hyper3: Equivalence to 1F1 under a power @ Moebius
      <- hyper3 successful: received ODE is equivalent to the 1F1 ODE
      <- Kummer successful
<- special function solution successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 34

```
Order:=6;
dsolve(diff(y(x),x$2)+x*diff(y(x),x)+(x^2-4)*y(x)=0,y(x),type='series',x=0);
```

$$y(x) = \left(1 + 2x^2 + \frac{1}{4}x^4\right) y(0) + \left(x + \frac{1}{2}x^3 - \frac{1}{40}x^5\right) D(y)(0) + O(x^6)$$

✓ Solution by Mathematica

Time used: 0.001 (sec). Leaf size: 40

```
AsymptoticDSolveValue[y'[x]+x*y'[x]+(x^2-4)*y[x]==0,y[x],{x,0,5}]
```

$$y(x) \rightarrow c_2 \left(-\frac{x^5}{40} + \frac{x^3}{2} + x \right) + c_1 \left(\frac{x^4}{4} + 2x^2 + 1 \right)$$

14.5 problem 5

14.5.1 Maple step by step solution 3882

Internal problem ID [11888]

Internal file name [OUTPUT/11897_Saturday_April_13_2024_01_14_19_AM_78059033/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.1. Exercises page 232

Problem number: 5.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"second order series method. Ordinary point", "second order series method. Taylor series method"**

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$y'' + y'x + (3x + 2)y = 0$$

With the expansion point for the power series method at $x = 0$.

Solving ode using Taylor series method. This gives review on how the Taylor series method works for solving second order ode.

Let

$$y'' = f(x, y, y')$$

Assuming expansion is at $x_0 = 0$ (we can always shift the actual expansion point to 0 by change of variables) and assuming $f(x, y, y')$ is analytic at x_0 which must be the case for an ordinary point. Let initial conditions be $y(x_0) = y_0$ and $y'(x_0) = y'_0$. Using Taylor series gives

$$\begin{aligned} y(x) &= y(x_0) + (x - x_0)y'(x_0) + \frac{(x - x_0)^2}{2}y''(x_0) + \frac{(x - x_0)^3}{3!}y'''(x_0) + \cdots \\ &= y_0 + xy'_0 + \frac{x^2}{2}f|_{x_0, y_0, y'_0} + \frac{x^3}{3!}f'|_{x_0, y_0, y'_0} + \cdots \\ &= y_0 + xy'_0 + \sum_{n=0}^{\infty} \frac{x^{n+2}}{(n+2)!} \frac{d^n f}{dx^n} \Big|_{x_0, y_0, y'_0} \end{aligned}$$

But

$$\frac{df}{dx} = \frac{\partial f}{\partial x} \frac{dx}{dx} + \frac{\partial f}{\partial y} \frac{dy}{dx} + \frac{\partial f}{\partial y'} \frac{dy'}{dx} \quad (1)$$

$$= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} y'' \quad (795)$$

$$= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} f \quad (796)$$

$$\begin{aligned} \frac{d^2 f}{dx^2} &= \frac{d}{dx} \left(\frac{df}{dx} \right) \\ &= \frac{\partial}{\partial x} \left(\frac{df}{dx} \right) + \frac{\partial}{\partial y} \left(\frac{df}{dx} \right) y' + \frac{\partial}{\partial y'} \left(\frac{df}{dx} \right) f \end{aligned} \quad (2)$$

$$\begin{aligned} \frac{d^3 f}{dx^3} &= \frac{d}{dx} \left(\frac{d^2 f}{dx^2} \right) \\ &= \frac{\partial}{\partial x} \left(\frac{d^2 f}{dx^2} \right) + \left(\frac{\partial}{\partial y} \frac{d^2 f}{dx^2} \right) y' + \frac{\partial}{\partial y'} \left(\frac{d^2 f}{dx^2} \right) f \end{aligned} \quad (3)$$

⋮

And so on. Hence if we name $F_0 = f(x, y, y')$ then the above can be written as

$$F_0 = f(x, y, y') \quad (4)$$

$$\begin{aligned} F_1 &= \frac{df}{dx} \\ &= \frac{dF_0}{dx} \\ &= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} y'' \\ &= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} f \\ &= \frac{\partial F_0}{\partial x} + \frac{\partial F_0}{\partial y} y' + \frac{\partial F_0}{\partial y'} F_0 \end{aligned} \quad (5)$$

$$\begin{aligned} F_2 &= \frac{d}{dx} \left(\frac{d}{dx} f \right) \\ &= \frac{d}{dx} (F_1) \\ &= \frac{\partial}{\partial x} F_1 + \left(\frac{\partial F_1}{\partial y} \right) y' + \left(\frac{\partial F_1}{\partial y'} \right) y'' \\ &= \frac{\partial}{\partial x} F_1 + \left(\frac{\partial F_1}{\partial y} \right) y' + \left(\frac{\partial F_1}{\partial y'} \right) F_0 \\ &\vdots \\ F_n &= \frac{d}{dx} (F_{n-1}) \\ &= \frac{\partial}{\partial x} F_{n-1} + \left(\frac{\partial F_{n-1}}{\partial y} \right) y' + \left(\frac{\partial F_{n-1}}{\partial y'} \right) y'' \\ &= \frac{\partial}{\partial x} F_{n-1} + \left(\frac{\partial F_{n-1}}{\partial y} \right) y' + \left(\frac{\partial F_{n-1}}{\partial y'} \right) F_0 \end{aligned} \quad (6)$$

Therefore (6) can be used from now on along with

$$y(x) = y_0 + xy'_0 + \sum_{n=0}^{\infty} \frac{x^{n+2}}{(n+2)!} F_n|_{x_0, y_0, y'_0} \quad (7)$$

To find $y(x)$ series solution around $x = 0$. Hence

$$F_0 = -y'x - 3yx - 2y$$

$$\begin{aligned} F_1 &= \frac{dF_0}{dx} \\ &= \frac{\partial F_0}{\partial x} + \frac{\partial F_0}{\partial y} y' + \frac{\partial F_0}{\partial y'} F_0 \\ &= (x^2 - 3x - 3) y' + 3 \left(x^2 + \frac{2}{3}x - 1 \right) y \end{aligned}$$

$$\begin{aligned} F_2 &= \frac{dF_1}{dx} \\ &= \frac{\partial F_1}{\partial x} + \frac{\partial F_1}{\partial y} y' + \frac{\partial F_1}{\partial y'} F_1 \\ &= (-x^3 + 6x^2 + 7x - 6) y' - 3 \left(x^3 - \frac{7}{3}x^2 - 7x - \frac{8}{3} \right) y \end{aligned}$$

$$\begin{aligned} F_3 &= \frac{dF_2}{dx} \\ &= \frac{\partial F_2}{\partial x} + \frac{\partial F_2}{\partial y} y' + \frac{\partial F_2}{\partial y'} F_2 \\ &= (x^4 - 9x^3 - 3x^2 + 39x + 15) y' + 3 \left(x^4 - \frac{16}{3}x^3 - 14x^2 + 6x + 11 \right) y \end{aligned}$$

$$\begin{aligned} F_4 &= \frac{dF_3}{dx} \\ &= \frac{\partial F_3}{\partial x} + \frac{\partial F_3}{\partial y} y' + \frac{\partial F_3}{\partial y'} F_3 \\ &= (-x^5 + 12x^4 - 9x^3 - 108x^2 - 3x + 72) y' - 3 \left(x^5 - \frac{25}{3}x^4 - 13x^3 + 53x^2 + 69x + 4 \right) y \end{aligned}$$

And so on. Evaluating all the above at initial conditions $x = 0$ and $y(0) = y(0)$ and $y'(0) = y'(0)$ gives

$$F_0 = -2y(0)$$

$$F_1 = -3y'(0) - 3y(0)$$

$$F_2 = -6y'(0) + 8y(0)$$

$$F_3 = 15y'(0) + 33y(0)$$

$$F_4 = 72y'(0) - 12y(0)$$

Substituting all the above in (7) and simplifying gives the solution as

$$y = \left(1 - x^2 - \frac{1}{2}x^3 + \frac{1}{3}x^4 + \frac{11}{40}x^5 - \frac{1}{60}x^6\right) y(0) \\ + \left(x - \frac{1}{2}x^3 - \frac{1}{4}x^4 + \frac{1}{8}x^5 + \frac{1}{10}x^6\right) y'(0) + O(x^6)$$

Since the expansion point $x = 0$ is an ordinary, we can also solve this using standard power series. Let the solution be represented as power series of the form

$$y = \sum_{n=0}^{\infty} a_n x^n$$

Then

$$y' = \sum_{n=1}^{\infty} n a_n x^{n-1} \\ y'' = \sum_{n=2}^{\infty} n(n-1) a_n x^{n-2}$$

Substituting the above back into the ode gives

$$\sum_{n=2}^{\infty} n(n-1) a_n x^{n-2} = - \left(\sum_{n=1}^{\infty} n a_n x^{n-1} \right) x - 3 \left(\sum_{n=0}^{\infty} a_n x^n \right) x - 2 \left(\sum_{n=0}^{\infty} a_n x^n \right) \quad (1)$$

Which simplifies to

$$\left(\sum_{n=2}^{\infty} n(n-1) a_n x^{n-2} \right) + \left(\sum_{n=1}^{\infty} n x^n a_n \right) + \left(\sum_{n=0}^{\infty} 3x^{1+n} a_n \right) + \left(\sum_{n=0}^{\infty} 2a_n x^n \right) = 0 \quad (2)$$

The next step is to make all powers of x be n in each summation term. Going over each summation term above with power of x in it which is not already x^n and adjusting the power and the corresponding index gives

$$\sum_{n=2}^{\infty} n(n-1) a_n x^{n-2} = \sum_{n=0}^{\infty} (n+2) a_{n+2} (1+n) x^n \\ \sum_{n=0}^{\infty} 3x^{1+n} a_n = \sum_{n=1}^{\infty} 3a_{n-1} x^n$$

Substituting all the above in Eq (2) gives the following equation where now all powers of x are the same and equal to n .

$$\left(\sum_{n=0}^{\infty} (n+2) a_{n+2} (1+n) x^n \right) + \left(\sum_{n=1}^{\infty} n x^n a_n \right) + \left(\sum_{n=1}^{\infty} 3a_{n-1} x^n \right) + \left(\sum_{n=0}^{\infty} 2a_n x^n \right) = 0 \quad (3)$$

$n = 0$ gives

$$2a_2 + 2a_0 = 0$$

$$a_2 = -a_0$$

For $1 \leq n$, the recurrence equation is

$$(n+2) a_{n+2} (1+n) + n a_n + 3a_{n-1} + 2a_n = 0 \quad (4)$$

Solving for a_{n+2} , gives

$$\begin{aligned} a_{n+2} &= -\frac{na_n + 2a_n + 3a_{n-1}}{(n+2)(1+n)} \\ (5) \quad &= -\frac{a_n}{1+n} - \frac{3a_{n-1}}{(n+2)(1+n)} \end{aligned}$$

For $n = 1$ the recurrence equation gives

$$6a_3 + 3a_1 + 3a_0 = 0$$

Which after substituting the earlier terms found becomes

$$a_3 = -\frac{a_1}{2} - \frac{a_0}{2}$$

For $n = 2$ the recurrence equation gives

$$12a_4 + 4a_2 + 3a_1 = 0$$

Which after substituting the earlier terms found becomes

$$a_4 = \frac{a_0}{3} - \frac{a_1}{4}$$

For $n = 3$ the recurrence equation gives

$$20a_5 + 5a_3 + 3a_2 = 0$$

Which after substituting the earlier terms found becomes

$$a_5 = \frac{a_1}{8} + \frac{11a_0}{40}$$

For $n = 4$ the recurrence equation gives

$$30a_6 + 6a_4 + 3a_3 = 0$$

Which after substituting the earlier terms found becomes

$$a_6 = -\frac{a_0}{60} + \frac{a_1}{10}$$

For $n = 5$ the recurrence equation gives

$$42a_7 + 7a_5 + 3a_4 = 0$$

Which after substituting the earlier terms found becomes

$$a_7 = -\frac{a_1}{336} - \frac{39a_0}{560}$$

And so on. Therefore the solution is

$$\begin{aligned} y &= \sum_{n=0}^{\infty} a_n x^n \\ &= a_3 x^3 + a_2 x^2 + a_1 x + a_0 + \dots \end{aligned}$$

Substituting the values for a_n found above, the solution becomes

$$y = a_0 + a_1 x - a_0 x^2 + \left(-\frac{a_1}{2} - \frac{a_0}{2}\right) x^3 + \left(\frac{a_0}{3} - \frac{a_1}{4}\right) x^4 + \left(\frac{a_1}{8} + \frac{11a_0}{40}\right) x^5 + \dots$$

Collecting terms, the solution becomes

$$y = \left(1 - x^2 - \frac{1}{2}x^3 + \frac{1}{3}x^4 + \frac{11}{40}x^5\right) a_0 + \left(x - \frac{1}{2}x^3 - \frac{1}{4}x^4 + \frac{1}{8}x^5\right) a_1 + O(x^6) \quad (3)$$

At $x = 0$ the solution above becomes

$$y = \left(1 - x^2 - \frac{1}{2}x^3 + \frac{1}{3}x^4 + \frac{11}{40}x^5\right) c_1 + \left(x - \frac{1}{2}x^3 - \frac{1}{4}x^4 + \frac{1}{8}x^5\right) c_2 + O(x^6)$$

Summary

The solution(s) found are the following

$$y = \left(1 - x^2 - \frac{1}{2}x^3 + \frac{1}{3}x^4 + \frac{11}{40}x^5 - \frac{1}{60}x^6\right) y(0) + \left(x - \frac{1}{2}x^3 - \frac{1}{4}x^4 + \frac{1}{8}x^5 + \frac{1}{10}x^6\right) y'(0) + O(x^6) \quad (1)$$

$$y = \left(1 - x^2 - \frac{1}{2}x^3 + \frac{1}{3}x^4 + \frac{11}{40}x^5\right) c_1 + \left(x - \frac{1}{2}x^3 - \frac{1}{4}x^4 + \frac{1}{8}x^5\right) c_2 + O(x^6) \quad (2)$$

Verification of solutions

$$y = \left(1 - x^2 - \frac{1}{2}x^3 + \frac{1}{3}x^4 + \frac{11}{40}x^5 - \frac{1}{60}x^6\right) y(0) + \left(x - \frac{1}{2}x^3 - \frac{1}{4}x^4 + \frac{1}{8}x^5 + \frac{1}{10}x^6\right) y'(0) + O(x^6)$$

Verified OK.

$$y = \left(1 - x^2 - \frac{1}{2}x^3 + \frac{1}{3}x^4 + \frac{11}{40}x^5\right) c_1 + \left(x - \frac{1}{2}x^3 - \frac{1}{4}x^4 + \frac{1}{8}x^5\right) c_2 + O(x^6)$$

Verified OK.

14.5.1 Maple step by step solution

Let's solve

$$y'' = -y'x - 3yx - 2y$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = (-3x - 2)y - y'x$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + y'x + (3x + 2)y = 0$$

- Assume series solution for y

$$y = \sum_{k=0}^{\infty} a_k x^k$$

□ Rewrite ODE with series expansions

- Convert $x^m \cdot y$ to series expansion for $m = 0..1$

$$x^m \cdot y = \sum_{k=\max(0,-m)}^{\infty} a_k x^{k+m}$$

- Shift index using $k \rightarrow k - m$

$$x^m \cdot y = \sum_{k=\max(0,-m)+m}^{\infty} a_{k-m} x^k$$

- Convert $x \cdot y'$ to series expansion

$$x \cdot y' = \sum_{k=0}^{\infty} a_k k x^k$$

- Convert y'' to series expansion

$$y'' = \sum_{k=2}^{\infty} a_k k(k-1) x^{k-2}$$

- Shift index using $k \rightarrow k + 2$

$$y'' = \sum_{k=0}^{\infty} a_{k+2} (k+2)(k+1) x^k$$

Rewrite ODE with series expansions

$$2a_2 + 2a_0 + \left(\sum_{k=1}^{\infty} (a_{k+2}(k+2)(k+1) + a_k(k+2) + 3a_{k-1}) x^k \right) = 0$$

- Each term must be 0

$$2a_2 + 2a_0 = 0$$

- Each term in the series must be 0, giving the recursion relation

$$(k^2 + 3k + 2) a_{k+2} + a_k k + 2a_k + 3a_{k-1} = 0$$

- Shift index using $k \rightarrow k + 1$

$$((k+1)^2 + 3k + 5) a_{k+3} + a_{k+1}(k+1) + 2a_{k+1} + 3a_k = 0$$

- Recursion relation that defines the series solution to the ODE

$$\left[y = \sum_{k=0}^{\infty} a_k x^k, a_{k+3} = -\frac{ka_{k+1} + 3a_k + 3a_{k+1}}{k^2 + 5k + 6}, 2a_2 + 2a_0 = 0 \right]$$

Maple trace Kovacic algorithm successful

```
`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
trying a symmetry of the form [xi=0, eta=F(x)]
checking if the LODE is missing y
-> Trying a Liouvillian solution using Kovacics algorithm
  A Liouvillian solution exists
  Reducible group (found an exponential solution)
  Group is reducible, not completely reducible
  Solution has integrals. Trying a special function solution free of integrals...
-> Trying a solution in terms of special functions:
  -> Bessel
  -> elliptic
  -> Legendre
  -> Kummer
    -> hyper3: Equivalence to 1F1 under a power @ Moebius
  -> hypergeometric
    -> heuristic approach
      <- heuristic approach successful
    <- hypergeometric successful
  <- special function solution successful
    -> Trying to convert hypergeometric functions to elementary form...
      <- elementary form could result into a too large expression - returning special functi
  <- Kovacics algorithm successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 49

```
Order:=6;
dsolve(diff(y(x),x$2)+x*diff(y(x),x)+(3*x+2)*y(x)=0,y(x),type='series',x=0);
```

$$y(x) = \left(1 - x^2 - \frac{1}{2}x^3 + \frac{1}{3}x^4 + \frac{11}{40}x^5\right) y(0) + \left(x - \frac{1}{2}x^3 - \frac{1}{4}x^4 + \frac{1}{8}x^5\right) D(y)(0) + O(x^6)$$

✓ Solution by Mathematica

Time used: 0.001 (sec). Leaf size: 61

```
AsymptoticDSolveValue[y''[x]+x*y'[x]+(3*x+2)*y[x]==0,y[x],{x,0,5}]
```

$$y(x) \rightarrow c_2 \left(\frac{x^5}{8} - \frac{x^4}{4} - \frac{x^3}{2} + x \right) + c_1 \left(\frac{11x^5}{40} + \frac{x^4}{3} - \frac{x^3}{2} - x^2 + 1 \right)$$

14.6 problem 6

14.6.1 Maple step by step solution 3893

Internal problem ID [11889]

Internal file name [OUTPUT/11898_Saturday_April_13_2024_01_14_20_AM_85922392/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.1. Exercises page 232

Problem number: 6.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"second order series method. Ordinary point", "second order series method. Taylor series method"**

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$y'' - y'x + (3x - 2)y = 0$$

With the expansion point for the power series method at $x = 0$.

Solving ode using Taylor series method. This gives review on how the Taylor series method works for solving second order ode.

Let

$$y'' = f(x, y, y')$$

Assuming expansion is at $x_0 = 0$ (we can always shift the actual expansion point to 0 by change of variables) and assuming $f(x, y, y')$ is analytic at x_0 which must be the case for an ordinary point. Let initial conditions be $y(x_0) = y_0$ and $y'(x_0) = y'_0$. Using Taylor series gives

$$\begin{aligned} y(x) &= y(x_0) + (x - x_0)y'(x_0) + \frac{(x - x_0)^2}{2}y''(x_0) + \frac{(x - x_0)^3}{3!}y'''(x_0) + \cdots \\ &= y_0 + xy'_0 + \frac{x^2}{2}f|_{x_0, y_0, y'_0} + \frac{x^3}{3!}f'|_{x_0, y_0, y'_0} + \cdots \\ &= y_0 + xy'_0 + \sum_{n=0}^{\infty} \frac{x^{n+2}}{(n+2)!} \frac{d^n f}{dx^n} \Big|_{x_0, y_0, y'_0} \end{aligned}$$

But

$$\frac{df}{dx} = \frac{\partial f}{\partial x} \frac{dx}{dx} + \frac{\partial f}{\partial y} \frac{dy}{dx} + \frac{\partial f}{\partial y'} \frac{dy'}{dx} \quad (1)$$

$$= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} y'' \quad (798)$$

$$= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} f \quad (799)$$

$$\begin{aligned} \frac{d^2 f}{dx^2} &= \frac{d}{dx} \left(\frac{df}{dx} \right) \\ &= \frac{\partial}{\partial x} \left(\frac{df}{dx} \right) + \frac{\partial}{\partial y} \left(\frac{df}{dx} \right) y' + \frac{\partial}{\partial y'} \left(\frac{df}{dx} \right) f \end{aligned} \quad (2)$$

$$\begin{aligned} \frac{d^3 f}{dx^3} &= \frac{d}{dx} \left(\frac{d^2 f}{dx^2} \right) \\ &= \frac{\partial}{\partial x} \left(\frac{d^2 f}{dx^2} \right) + \left(\frac{\partial}{\partial y} \frac{d^2 f}{dx^2} \right) y' + \frac{\partial}{\partial y'} \left(\frac{d^2 f}{dx^2} \right) f \end{aligned} \quad (3)$$

⋮

And so on. Hence if we name $F_0 = f(x, y, y')$ then the above can be written as

$$F_0 = f(x, y, y') \tag{4}$$

$$\begin{aligned} F_1 &= \frac{df}{dx} \\ &= \frac{dF_0}{dx} \\ &= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y}y' + \frac{\partial f}{\partial y'}y'' \\ &= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y}y' + \frac{\partial f}{\partial y'}f \\ &= \frac{\partial F_0}{\partial x} + \frac{\partial F_0}{\partial y}y' + \frac{\partial F_0}{\partial y'}F_0 \end{aligned} \tag{5}$$

$$\begin{aligned} F_2 &= \frac{d}{dx} \left(\frac{d}{dx} f \right) \\ &= \frac{d}{dx} (F_1) \\ &= \frac{\partial}{\partial x} F_1 + \left(\frac{\partial F_1}{\partial y} \right) y' + \left(\frac{\partial F_1}{\partial y'} \right) y'' \\ &= \frac{\partial}{\partial x} F_1 + \left(\frac{\partial F_1}{\partial y} \right) y' + \left(\frac{\partial F_1}{\partial y'} \right) F_0 \end{aligned}$$

⋮

$$\begin{aligned} F_n &= \frac{d}{dx} (F_{n-1}) \\ &= \frac{\partial}{\partial x} F_{n-1} + \left(\frac{\partial F_{n-1}}{\partial y} \right) y' + \left(\frac{\partial F_{n-1}}{\partial y'} \right) y'' \\ &= \frac{\partial}{\partial x} F_{n-1} + \left(\frac{\partial F_{n-1}}{\partial y} \right) y' + \left(\frac{\partial F_{n-1}}{\partial y'} \right) F_0 \end{aligned} \tag{6}$$

Therefore (6) can be used from now on along with

$$y(x) = y_0 + xy'_0 + \sum_{n=0}^{\infty} \frac{x^{n+2}}{(n+2)!} F_n|_{x_0, y_0, y'_0} \tag{7}$$

To find $y(x)$ series solution around $x = 0$. Hence

$$F_0 = -3yx + y'x + 2y$$

$$\begin{aligned} F_1 &= \frac{dF_0}{dx} \\ &= \frac{\partial F_0}{\partial x} + \frac{\partial F_0}{\partial y} y' + \frac{\partial F_0}{\partial y'} F_0 \\ &= (x^2 - 3x + 3) y' - 3 \left(x^2 - \frac{2}{3}x + 1 \right) y \end{aligned}$$

$$\begin{aligned} F_2 &= \frac{dF_1}{dx} \\ &= \frac{\partial F_1}{\partial x} + \frac{\partial F_1}{\partial y} y' + \frac{\partial F_1}{\partial y'} F_1 \\ &= (x^3 - 6x^2 + 7x - 6) y' - 3y \left(x^3 - \frac{11}{3}x^2 + 7x - \frac{8}{3} \right) \end{aligned}$$

$$\begin{aligned} F_3 &= \frac{dF_2}{dx} \\ &= \frac{\partial F_2}{\partial x} + \frac{\partial F_2}{\partial y} y' + \frac{\partial F_2}{\partial y'} F_2 \\ &= (x^4 - 9x^3 + 21x^2 - 39x + 15) y' - 3y \left(x^4 - \frac{20}{3}x^3 + 14x^2 - 18x + 11 \right) \end{aligned}$$

$$\begin{aligned} F_4 &= \frac{dF_3}{dx} \\ &= \frac{\partial F_3}{\partial x} + \frac{\partial F_3}{\partial y} y' + \frac{\partial F_3}{\partial y'} F_3 \\ &= (x^5 - 12x^4 + 45x^3 - 108x^2 + 111x - 72) y' - 3 \left(x^5 - \frac{29}{3}x^4 + 31x^3 - 73x^2 + 69x - 28 \right) y \end{aligned}$$

And so on. Evaluating all the above at initial conditions $x = 0$ and $y(0) = y(0)$ and $y'(0) = y'(0)$ gives

$$F_0 = 2y(0)$$

$$F_1 = 3y'(0) - 3y(0)$$

$$F_2 = -6y'(0) + 8y(0)$$

$$F_3 = 15y'(0) - 33y(0)$$

$$F_4 = -72y'(0) + 84y(0)$$

Substituting all the above in (7) and simplifying gives the solution as

$$y = \left(1 + x^2 - \frac{1}{2}x^3 + \frac{1}{3}x^4 - \frac{11}{40}x^5 + \frac{7}{60}x^6\right) y(0) \\ + \left(x + \frac{1}{2}x^3 - \frac{1}{4}x^4 + \frac{1}{8}x^5 - \frac{1}{10}x^6\right) y'(0) + O(x^6)$$

Since the expansion point $x = 0$ is an ordinary, we can also solve this using standard power series. Let the solution be represented as power series of the form

$$y = \sum_{n=0}^{\infty} a_n x^n$$

Then

$$y' = \sum_{n=1}^{\infty} n a_n x^{n-1} \\ y'' = \sum_{n=2}^{\infty} n(n-1) a_n x^{n-2}$$

Substituting the above back into the ode gives

$$\sum_{n=2}^{\infty} n(n-1) a_n x^{n-2} = -3 \left(\sum_{n=0}^{\infty} a_n x^n \right) x + \left(\sum_{n=1}^{\infty} n a_n x^{n-1} \right) x + 2 \left(\sum_{n=0}^{\infty} a_n x^n \right) \quad (1)$$

Which simplifies to

$$\left(\sum_{n=2}^{\infty} n(n-1) a_n x^{n-2} \right) + \sum_{n=1}^{\infty} (-n x^n a_n) + \left(\sum_{n=0}^{\infty} 3x^{1+n} a_n \right) + \sum_{n=0}^{\infty} (-2a_n x^n) = 0 \quad (2)$$

The next step is to make all powers of x be n in each summation term. Going over each summation term above with power of x in it which is not already x^n and adjusting the power and the corresponding index gives

$$\sum_{n=2}^{\infty} n(n-1) a_n x^{n-2} = \sum_{n=0}^{\infty} (n+2) a_{n+2} (1+n) x^n \\ \sum_{n=0}^{\infty} 3x^{1+n} a_n = \sum_{n=1}^{\infty} 3a_{n-1} x^n$$

Substituting all the above in Eq (2) gives the following equation where now all powers of x are the same and equal to n .

$$\left(\sum_{n=0}^{\infty} (n+2) a_{n+2} (1+n) x^n \right) + \sum_{n=1}^{\infty} (-n x^n a_n) + \left(\sum_{n=1}^{\infty} 3a_{n-1} x^n \right) + \sum_{n=0}^{\infty} (-2a_n x^n) = 0 \quad (3)$$

$n = 0$ gives

$$2a_2 - 2a_0 = 0$$

$$a_2 = a_0$$

For $1 \leq n$, the recurrence equation is

$$(n+2) a_{n+2} (1+n) - n a_n + 3a_{n-1} - 2a_n = 0 \quad (4)$$

Solving for a_{n+2} , gives

$$\begin{aligned} a_{n+2} &= \frac{n a_n + 2a_n - 3a_{n-1}}{(n+2)(1+n)} \\ (5) \quad &= \frac{a_n}{1+n} - \frac{3a_{n-1}}{(n+2)(1+n)} \end{aligned}$$

For $n = 1$ the recurrence equation gives

$$6a_3 - 3a_1 + 3a_0 = 0$$

Which after substituting the earlier terms found becomes

$$a_3 = \frac{a_1}{2} - \frac{a_0}{2}$$

For $n = 2$ the recurrence equation gives

$$12a_4 - 4a_2 + 3a_1 = 0$$

Which after substituting the earlier terms found becomes

$$a_4 = \frac{a_0}{3} - \frac{a_1}{4}$$

For $n = 3$ the recurrence equation gives

$$20a_5 - 5a_3 + 3a_2 = 0$$

Which after substituting the earlier terms found becomes

$$a_5 = \frac{a_1}{8} - \frac{11a_0}{40}$$

For $n = 4$ the recurrence equation gives

$$30a_6 - 6a_4 + 3a_3 = 0$$

Which after substituting the earlier terms found becomes

$$a_6 = \frac{7a_0}{60} - \frac{a_1}{10}$$

For $n = 5$ the recurrence equation gives

$$42a_7 - 7a_5 + 3a_4 = 0$$

Which after substituting the earlier terms found becomes

$$a_7 = \frac{13a_1}{336} - \frac{39a_0}{560}$$

And so on. Therefore the solution is

$$\begin{aligned} y &= \sum_{n=0}^{\infty} a_n x^n \\ &= a_3 x^3 + a_2 x^2 + a_1 x + a_0 + \dots \end{aligned}$$

Substituting the values for a_n found above, the solution becomes

$$y = a_0 + a_1 x + a_0 x^2 + \left(\frac{a_1}{2} - \frac{a_0}{2}\right) x^3 + \left(\frac{a_0}{3} - \frac{a_1}{4}\right) x^4 + \left(\frac{a_1}{8} - \frac{11a_0}{40}\right) x^5 + \dots$$

Collecting terms, the solution becomes

$$y = \left(1 + x^2 - \frac{1}{2}x^3 + \frac{1}{3}x^4 - \frac{11}{40}x^5\right) a_0 + \left(x + \frac{1}{2}x^3 - \frac{1}{4}x^4 + \frac{1}{8}x^5\right) a_1 + O(x^6) \quad (3)$$

At $x = 0$ the solution above becomes

$$y = \left(1 + x^2 - \frac{1}{2}x^3 + \frac{1}{3}x^4 - \frac{11}{40}x^5\right) c_1 + \left(x + \frac{1}{2}x^3 - \frac{1}{4}x^4 + \frac{1}{8}x^5\right) c_2 + O(x^6)$$

Summary

The solution(s) found are the following

$$y = \left(1 + x^2 - \frac{1}{2}x^3 + \frac{1}{3}x^4 - \frac{11}{40}x^5 + \frac{7}{60}x^6\right) y(0) + \left(x + \frac{1}{2}x^3 - \frac{1}{4}x^4 + \frac{1}{8}x^5 - \frac{1}{10}x^6\right) y'(0) + O(x^6) \quad (1)$$

$$y = \left(1 + x^2 - \frac{1}{2}x^3 + \frac{1}{3}x^4 - \frac{11}{40}x^5\right) c_1 + \left(x + \frac{1}{2}x^3 - \frac{1}{4}x^4 + \frac{1}{8}x^5\right) c_2 + O(x^6) \quad (2)$$

Verification of solutions

$$y = \left(1 + x^2 - \frac{1}{2}x^3 + \frac{1}{3}x^4 - \frac{11}{40}x^5 + \frac{7}{60}x^6\right) y(0) + \left(x + \frac{1}{2}x^3 - \frac{1}{4}x^4 + \frac{1}{8}x^5 - \frac{1}{10}x^6\right) y'(0) + O(x^6)$$

Verified OK.

$$y = \left(1 + x^2 - \frac{1}{2}x^3 + \frac{1}{3}x^4 - \frac{11}{40}x^5\right) c_1 + \left(x + \frac{1}{2}x^3 - \frac{1}{4}x^4 + \frac{1}{8}x^5\right) c_2 + O(x^6)$$

Verified OK.

14.6.1 Maple step by step solution

Let's solve

$$y'' = -3yx + y'x + 2y$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = (-3x + 2)y + y'x$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' - y'x + (3x - 2)y = 0$$

- Assume series solution for y

$$y = \sum_{k=0}^{\infty} a_k x^k$$

□ Rewrite ODE with series expansions

- Convert $x^m \cdot y$ to series expansion for $m = 0..1$

$$x^m \cdot y = \sum_{k=\max(0,-m)}^{\infty} a_k x^{k+m}$$

- Shift index using $k \rightarrow k - m$

$$x^m \cdot y = \sum_{k=\max(0,-m)+m}^{\infty} a_{k-m} x^k$$

- Convert $x \cdot y'$ to series expansion

$$x \cdot y' = \sum_{k=0}^{\infty} a_k k x^k$$

- Convert y'' to series expansion

$$y'' = \sum_{k=2}^{\infty} a_k k(k-1) x^{k-2}$$

- Shift index using $k \rightarrow k + 2$

$$y'' = \sum_{k=0}^{\infty} a_{k+2} (k+2)(k+1) x^k$$

Rewrite ODE with series expansions

$$2a_2 - 2a_0 + \left(\sum_{k=1}^{\infty} (a_{k+2}(k+2)(k+1) - a_k(k+2) + 3a_{k-1}) x^k \right) = 0$$

- Each term must be 0

$$2a_2 - 2a_0 = 0$$

- Each term in the series must be 0, giving the recursion relation

$$(k^2 + 3k + 2) a_{k+2} - a_k k - 2a_k + 3a_{k-1} = 0$$

- Shift index using $k \rightarrow k + 1$

$$((k+1)^2 + 3k + 5) a_{k+3} - a_{k+1}(k+1) - 2a_{k+1} + 3a_k = 0$$

- Recursion relation that defines the series solution to the ODE

$$\left[y = \sum_{k=0}^{\infty} a_k x^k, a_{k+3} = \frac{ka_{k+1} - 3a_k + 3a_{k+1}}{k^2 + 5k + 6}, 2a_2 - 2a_0 = 0 \right]$$

Maple trace Kovacic algorithm successful

```
`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
trying a symmetry of the form [xi=0, eta=F(x)]
checking if the LODE is missing y
-> Trying a Liouvillian solution using Kovacics algorithm
  A Liouvillian solution exists
  Reducible group (found an exponential solution)
  Group is reducible, not completely reducible
  Solution has integrals. Trying a special function solution free of integrals...
-> Trying a solution in terms of special functions:
  -> Bessel
  -> elliptic
  -> Legendre
  -> Kummer
    -> hyper3: Equivalence to 1F1 under a power @ Moebius
  -> hypergeometric
    -> heuristic approach
      <- heuristic approach successful
    <- hypergeometric successful
  <- special function solution successful
    -> Trying to convert hypergeometric functions to elementary form...
      <- elementary form could result into a too large expression - returning special functi
  <- Kovacics algorithm successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 47

```
Order:=6;
dsolve(diff(y(x),x$2)-x*diff(y(x),x)+(3*x-2)*y(x)=0,y(x),type='series',x=0);
```

$$y(x) = \left(1 + x^2 - \frac{1}{2}x^3 + \frac{1}{3}x^4 - \frac{11}{40}x^5\right) y(0) + \left(x + \frac{1}{2}x^3 - \frac{1}{4}x^4 + \frac{1}{8}x^5\right) D(y)(0) + O(x^6)$$

✓ Solution by Mathematica

Time used: 0.001 (sec). Leaf size: 59

```
AsymptoticDSolveValue[y''[x]-x*y'[x]+(3*x-2)*y[x]==0,y[x],{x,0,5}]
```

$$y(x) \rightarrow c_2 \left(\frac{x^5}{8} - \frac{x^4}{4} + \frac{x^3}{2} + x \right) + c_1 \left(-\frac{11x^5}{40} + \frac{x^4}{3} - \frac{x^3}{2} + x^2 + 1 \right)$$

14.7 problem 7

Internal problem ID [11890]

Internal file name [OUTPUT/11899_Saturday_April_13_2024_01_14_21_AM_32507608/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.1. Exercises page 232

Problem number: 7.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"second order series method. Ordinary point", "second order series method. Taylor series method"**

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$(x^2 + 1)y'' + y'x + yx = 0$$

With the expansion point for the power series method at $x = 0$.

Solving ode using Taylor series method. This gives review on how the Taylor series method works for solving second order ode.

Let

$$y'' = f(x, y, y')$$

Assuming expansion is at $x_0 = 0$ (we can always shift the actual expansion point to 0 by change of variables) and assuming $f(x, y, y')$ is analytic at x_0 which must be the case for an ordinary point. Let initial conditions be $y(x_0) = y_0$ and $y'(x_0) = y'_0$. Using Taylor series gives

$$\begin{aligned} y(x) &= y(x_0) + (x - x_0)y'(x_0) + \frac{(x - x_0)^2}{2}y''(x_0) + \frac{(x - x_0)^3}{3!}y'''(x_0) + \cdots \\ &= y_0 + xy'_0 + \frac{x^2}{2}f|_{x_0, y_0, y'_0} + \frac{x^3}{3!}f'|_{x_0, y_0, y'_0} + \cdots \\ &= y_0 + xy'_0 + \sum_{n=0}^{\infty} \frac{x^{n+2}}{(n+2)!} \frac{d^n f}{dx^n} \Big|_{x_0, y_0, y'_0} \end{aligned}$$

But

$$\frac{df}{dx} = \frac{\partial f}{\partial x} \frac{dx}{dx} + \frac{\partial f}{\partial y} \frac{dy}{dx} + \frac{\partial f}{\partial y'} \frac{dy'}{dx} \quad (1)$$

$$= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} y'' \quad (801)$$

$$= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} f \quad (802)$$

$$\begin{aligned} \frac{d^2 f}{dx^2} &= \frac{d}{dx} \left(\frac{df}{dx} \right) \\ &= \frac{\partial}{\partial x} \left(\frac{df}{dx} \right) + \frac{\partial}{\partial y} \left(\frac{df}{dx} \right) y' + \frac{\partial}{\partial y'} \left(\frac{df}{dx} \right) f \end{aligned} \quad (2)$$

$$\begin{aligned} \frac{d^3 f}{dx^3} &= \frac{d}{dx} \left(\frac{d^2 f}{dx^2} \right) \\ &= \frac{\partial}{\partial x} \left(\frac{d^2 f}{dx^2} \right) + \left(\frac{\partial}{\partial y} \frac{d^2 f}{dx^2} \right) y' + \frac{\partial}{\partial y'} \left(\frac{d^2 f}{dx^2} \right) f \end{aligned} \quad (3)$$

⋮

And so on. Hence if we name $F_0 = f(x, y, y')$ then the above can be written as

$$F_0 = f(x, y, y') \quad (4)$$

$$\begin{aligned} F_1 &= \frac{df}{dx} \\ &= \frac{dF_0}{dx} \\ &= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y}y' + \frac{\partial f}{\partial y'}y'' \\ &= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y}y' + \frac{\partial f}{\partial y'}f \\ &= \frac{\partial F_0}{\partial x} + \frac{\partial F_0}{\partial y}y' + \frac{\partial F_0}{\partial y'}F_0 \end{aligned} \quad (5)$$

$$\begin{aligned} F_2 &= \frac{d}{dx} \left(\frac{d}{dx} f \right) \\ &= \frac{d}{dx} (F_1) \\ &= \frac{\partial}{\partial x} F_1 + \left(\frac{\partial F_1}{\partial y} \right) y' + \left(\frac{\partial F_1}{\partial y'} \right) y'' \\ &= \frac{\partial}{\partial x} F_1 + \left(\frac{\partial F_1}{\partial y} \right) y' + \left(\frac{\partial F_1}{\partial y'} \right) F_0 \\ &\vdots \\ F_n &= \frac{d}{dx} (F_{n-1}) \\ &= \frac{\partial}{\partial x} F_{n-1} + \left(\frac{\partial F_{n-1}}{\partial y} \right) y' + \left(\frac{\partial F_{n-1}}{\partial y'} \right) y'' \\ &= \frac{\partial}{\partial x} F_{n-1} + \left(\frac{\partial F_{n-1}}{\partial y} \right) y' + \left(\frac{\partial F_{n-1}}{\partial y'} \right) F_0 \end{aligned} \quad (6)$$

Therefore (6) can be used from now on along with

$$y(x) = y_0 + xy'_0 + \sum_{n=0}^{\infty} \frac{x^{n+2}}{(n+2)!} F_n|_{x_0, y_0, y'_0} \quad (7)$$

To find $y(x)$ series solution around $x = 0$. Hence

$$F_0 = -\frac{x(y' + y)}{x^2 + 1}$$

$$\begin{aligned} F_1 &= \frac{dF_0}{dx} \\ &= \frac{\partial F_0}{\partial x} + \frac{\partial F_0}{\partial y} y' + \frac{\partial F_0}{\partial y'} F_0 \\ &= \frac{(-x^3 + 2x^2 - x - 1)y' + y(2x^2 - 1)}{(x^2 + 1)^2} \end{aligned}$$

$$\begin{aligned} F_2 &= \frac{dF_1}{dx} \\ &= \frac{\partial F_1}{\partial x} + \frac{\partial F_1}{\partial y} y' + \frac{\partial F_1}{\partial y'} F_1 \\ &= \frac{(4x^4 - 6x^3 + 2x^2 + 9x - 2)y' + xy(x^3 - 6x^2 + x + 9)}{(x^2 + 1)^3} \end{aligned}$$

$$\begin{aligned} F_3 &= \frac{dF_2}{dx} \\ &= \frac{\partial F_2}{\partial x} + \frac{\partial F_2}{\partial y} y' + \frac{\partial F_2}{\partial y'} F_2 \\ &= \frac{(x^6 - 18x^5 + 26x^4 + 9x^3 - 71x^2 + 27x + 9)y' - 6y(x^5 - 4x^4 + \frac{1}{3}x^3 + 12x^2 - \frac{2}{3}x - \frac{3}{2})}{(x^2 + 1)^4} \end{aligned}$$

$$\begin{aligned} F_4 &= \frac{dF_3}{dx} \\ &= \frac{\partial F_3}{\partial x} + \frac{\partial F_3}{\partial y} y' + \frac{\partial F_3}{\partial y'} F_3 \\ &= \frac{(-9x^7 + 96x^6 - 132x^5 - 192x^4 + 603x^3 - 252x^2 - 219x + 36)y' - y(x^7 - 36x^6 + 122x^5 + 29x^4 - 5)}{(x^2 + 1)^5} \end{aligned}$$

And so on. Evaluating all the above at initial conditions $x = 0$ and $y(0) = y(0)$ and $y'(0) = y'(0)$ gives

$$\begin{aligned} F_0 &= 0 \\ F_1 &= -y'(0) - y(0) \\ F_2 &= -2y'(0) \\ F_3 &= 9y(0) + 9y'(0) \\ F_4 &= 4y(0) + 36y'(0) \end{aligned}$$

Substituting all the above in (7) and simplifying gives the solution as

$$y = \left(1 - \frac{1}{6}x^3 + \frac{3}{40}x^5 + \frac{1}{180}x^6\right)y(0) + \left(x - \frac{1}{6}x^3 - \frac{1}{12}x^4 + \frac{3}{40}x^5 + \frac{1}{20}x^6\right)y'(0) + O(x^6)$$

Since the expansion point $x = 0$ is an ordinary, we can also solve this using standard power series. The ode is normalized to be

$$(x^2 + 1)y'' + y'x + yx = 0$$

Let the solution be represented as power series of the form

$$y = \sum_{n=0}^{\infty} a_n x^n$$

Then

$$y' = \sum_{n=1}^{\infty} n a_n x^{n-1}$$

$$y'' = \sum_{n=2}^{\infty} n(n-1) a_n x^{n-2}$$

Substituting the above back into the ode gives

$$(x^2 + 1) \left(\sum_{n=2}^{\infty} n(n-1) a_n x^{n-2} \right) + \left(\sum_{n=1}^{\infty} n a_n x^{n-1} \right) x + \left(\sum_{n=0}^{\infty} a_n x^n \right) x = 0 \quad (1)$$

Which simplifies to

$$\left(\sum_{n=2}^{\infty} x^n a_n n(n-1) \right) + \left(\sum_{n=2}^{\infty} n(n-1) a_n x^{n-2} \right) + \left(\sum_{n=1}^{\infty} n a_n x^n \right) + \left(\sum_{n=0}^{\infty} x^{1+n} a_n \right) = 0 \quad (2)$$

The next step is to make all powers of x be n in each summation term. Going over each summation term above with power of x in it which is not already x^n and adjusting the power and the corresponding index gives

$$\sum_{n=2}^{\infty} n(n-1) a_n x^{n-2} = \sum_{n=0}^{\infty} (n+2) a_{n+2} (1+n) x^n$$

$$\sum_{n=0}^{\infty} x^{1+n} a_n = \sum_{n=1}^{\infty} a_{n-1} x^n$$

Substituting all the above in Eq (2) gives the following equation where now all powers of x are the same and equal to n .

$$\left(\sum_{n=2}^{\infty} x^n a_n n(n-1) \right) + \left(\sum_{n=0}^{\infty} (n+2) a_{n+2} (1+n) x^n \right) + \left(\sum_{n=1}^{\infty} n a_n x^n \right) + \left(\sum_{n=1}^{\infty} a_{n-1} x^n \right) = 0 \quad (3)$$

$n = 1$ gives

$$6a_3 + a_1 + a_0 = 0$$

Which after substituting earlier equations, simplifies to

$$a_3 = -\frac{a_0}{6} - \frac{a_1}{6}$$

For $2 \leq n$, the recurrence equation is

$$na_n(n-1) + (n+2)a_{n+2}(1+n) + na_n + a_{n-1} = 0 \quad (4)$$

Solving for a_{n+2} , gives

$$\begin{aligned} a_{n+2} &= -\frac{n^2a_n + a_{n-1}}{(n+2)(1+n)} \\ (5) \quad &= -\frac{n^2a_n}{(n+2)(1+n)} - \frac{a_{n-1}}{(n+2)(1+n)} \end{aligned}$$

For $n = 2$ the recurrence equation gives

$$4a_2 + 12a_4 + a_1 = 0$$

Which after substituting the earlier terms found becomes

$$a_4 = -\frac{a_1}{12}$$

For $n = 3$ the recurrence equation gives

$$9a_3 + 20a_5 + a_2 = 0$$

Which after substituting the earlier terms found becomes

$$a_5 = \frac{3a_0}{40} + \frac{3a_1}{40}$$

For $n = 4$ the recurrence equation gives

$$16a_4 + 30a_6 + a_3 = 0$$

Which after substituting the earlier terms found becomes

$$a_6 = \frac{a_1}{20} + \frac{a_0}{180}$$

For $n = 5$ the recurrence equation gives

$$25a_5 + 42a_7 + a_4 = 0$$

Which after substituting the earlier terms found becomes

$$a_7 = -\frac{5a_0}{112} - \frac{43a_1}{1008}$$

And so on. Therefore the solution is

$$\begin{aligned} y &= \sum_{n=0}^{\infty} a_n x^n \\ &= a_3 x^3 + a_2 x^2 + a_1 x + a_0 + \dots \end{aligned}$$

Substituting the values for a_n found above, the solution becomes

$$y = a_0 + a_1 x + \left(-\frac{a_0}{6} - \frac{a_1}{6}\right) x^3 - \frac{a_1 x^4}{12} + \left(\frac{3a_0}{40} + \frac{3a_1}{40}\right) x^5 + \dots$$

Collecting terms, the solution becomes

$$y = \left(1 - \frac{1}{6}x^3 + \frac{3}{40}x^5\right) a_0 + \left(x - \frac{1}{6}x^3 - \frac{1}{12}x^4 + \frac{3}{40}x^5\right) a_1 + O(x^6) \quad (3)$$

At $x = 0$ the solution above becomes

$$y = \left(1 - \frac{1}{6}x^3 + \frac{3}{40}x^5\right) c_1 + \left(x - \frac{1}{6}x^3 - \frac{1}{12}x^4 + \frac{3}{40}x^5\right) c_2 + O(x^6)$$

Summary

The solution(s) found are the following

$$\begin{aligned} y &= \left(1 - \frac{1}{6}x^3 + \frac{3}{40}x^5 + \frac{1}{180}x^6\right) y(0) \\ &\quad + \left(x - \frac{1}{6}x^3 - \frac{1}{12}x^4 + \frac{3}{40}x^5 + \frac{1}{20}x^6\right) y'(0) + O(x^6) \end{aligned} \quad (1)$$

$$y = \left(1 - \frac{1}{6}x^3 + \frac{3}{40}x^5\right) c_1 + \left(x - \frac{1}{6}x^3 - \frac{1}{12}x^4 + \frac{3}{40}x^5\right) c_2 + O(x^6) \quad (2)$$

Verification of solutions

$$y = \left(1 - \frac{1}{6}x^3 + \frac{3}{40}x^5 + \frac{1}{180}x^6\right) y(0) + \left(x - \frac{1}{6}x^3 - \frac{1}{12}x^4 + \frac{3}{40}x^5 + \frac{1}{20}x^6\right) y'(0) + O(x^6)$$

Verified OK.

$$y = \left(1 - \frac{1}{6}x^3 + \frac{3}{40}x^5\right) c_1 + \left(x - \frac{1}{6}x^3 - \frac{1}{12}x^4 + \frac{3}{40}x^5\right) c_2 + O(x^6)$$

Verified OK.

Maple trace

```
`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
trying a symmetry of the form [xi=0, eta=F(x)]
checking if the LODE is missing y
-> Trying a Liouvillian solution using Kovacic's algorithm
<- No Liouvillian solutions exist
-> Trying a solution in terms of special functions:
  -> Bessel
  -> elliptic
  -> Legendre
  -> Kummer
    -> hyper3: Equivalence to 1F1 under a power @ Moebius
  -> hypergeometric
    -> heuristic approach
    -> hyper3: Equivalence to 2F1, 1F1 or 0F1 under a power @ Moebius
  -> Mathieu
    -> Equivalence to the rational form of Mathieu ODE under a power @ Moebius
trying a solution in terms of MeijerG functions
-> Heun: Equivalence to the GHE or one of its 4 confluent cases under a power @ Moebius
<- Heun successful: received ODE is equivalent to the HeunC ODE, case a <> 0, e <> 0, c =
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 39

```
Order:=6;  
dsolve((x^2+1)*diff(y(x),x$2)+x*diff(y(x),x)+x*y(x)=0,y(x),type='series',x=0);
```

$$y(x) = \left(1 - \frac{1}{6}x^3 + \frac{3}{40}x^5\right) y(0) + \left(x - \frac{1}{6}x^3 - \frac{1}{12}x^4 + \frac{3}{40}x^5\right) D(y)(0) + O(x^6)$$

✓ Solution by Mathematica

Time used: 0.001 (sec). Leaf size: 49

```
AsymptoticDSolveValue[(x^2+1)*y''[x]+x*y'[x]+x*y[x]==0,y[x],{x,0,5}]
```

$$y(x) \rightarrow c_1 \left(\frac{3x^5}{40} - \frac{x^3}{6} + 1 \right) + c_2 \left(\frac{3x^5}{40} - \frac{x^4}{12} - \frac{x^3}{6} + x \right)$$

14.8 problem 8

14.8.1 Maple step by step solution 3914

Internal problem ID [11891]

Internal file name [OUTPUT/11900_Saturday_April_13_2024_01_14_21_AM_74726995/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.1. Exercises page 232

Problem number: 8.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"second order series method. Ordinary point", "second order series method. Taylor series method"**

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$(x - 1)y'' - (3x - 2)y' + 2yx = 0$$

With the expansion point for the power series method at $x = 0$.

Solving ode using Taylor series method. This gives review on how the Taylor series method works for solving second order ode.

Let

$$y'' = f(x, y, y')$$

Assuming expansion is at $x_0 = 0$ (we can always shift the actual expansion point to 0 by change of variables) and assuming $f(x, y, y')$ is analytic at x_0 which must be the case for an ordinary point. Let initial conditions be $y(x_0) = y_0$ and $y'(x_0) = y'_0$. Using Taylor series gives

$$\begin{aligned} y(x) &= y(x_0) + (x - x_0)y'(x_0) + \frac{(x - x_0)^2}{2}y''(x_0) + \frac{(x - x_0)^3}{3!}y'''(x_0) + \cdots \\ &= y_0 + xy'_0 + \frac{x^2}{2}f|_{x_0, y_0, y'_0} + \frac{x^3}{3!}f'|_{x_0, y_0, y'_0} + \cdots \\ &= y_0 + xy'_0 + \sum_{n=0}^{\infty} \frac{x^{n+2}}{(n+2)!} \frac{d^n f}{dx^n} \Big|_{x_0, y_0, y'_0} \end{aligned}$$

But

$$\frac{df}{dx} = \frac{\partial f}{\partial x} \frac{dx}{dx} + \frac{\partial f}{\partial y} \frac{dy}{dx} + \frac{\partial f}{\partial y'} \frac{dy'}{dx} \quad (1)$$

$$= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} y'' \quad (804)$$

$$= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} f \quad (805)$$

$$\begin{aligned} \frac{d^2 f}{dx^2} &= \frac{d}{dx} \left(\frac{df}{dx} \right) \\ &= \frac{\partial}{\partial x} \left(\frac{df}{dx} \right) + \frac{\partial}{\partial y} \left(\frac{df}{dx} \right) y' + \frac{\partial}{\partial y'} \left(\frac{df}{dx} \right) f \end{aligned} \quad (2)$$

$$\begin{aligned} \frac{d^3 f}{dx^3} &= \frac{d}{dx} \left(\frac{d^2 f}{dx^2} \right) \\ &= \frac{\partial}{\partial x} \left(\frac{d^2 f}{dx^2} \right) + \left(\frac{\partial}{\partial y} \frac{d^2 f}{dx^2} \right) y' + \frac{\partial}{\partial y'} \left(\frac{d^2 f}{dx^2} \right) f \end{aligned} \quad (3)$$

⋮

And so on. Hence if we name $F_0 = f(x, y, y')$ then the above can be written as

$$F_0 = f(x, y, y') \quad (4)$$

$$\begin{aligned} F_1 &= \frac{df}{dx} \\ &= \frac{dF_0}{dx} \\ &= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} y'' \\ &= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} f \\ &= \frac{\partial F_0}{\partial x} + \frac{\partial F_0}{\partial y} y' + \frac{\partial F_0}{\partial y'} F_0 \end{aligned} \quad (5)$$

$$\begin{aligned} F_2 &= \frac{d}{dx} \left(\frac{d}{dx} f \right) \\ &= \frac{d}{dx} (F_1) \\ &= \frac{\partial}{\partial x} F_1 + \left(\frac{\partial F_1}{\partial y} \right) y' + \left(\frac{\partial F_1}{\partial y'} \right) y'' \\ &= \frac{\partial}{\partial x} F_1 + \left(\frac{\partial F_1}{\partial y} \right) y' + \left(\frac{\partial F_1}{\partial y'} \right) F_0 \\ &\vdots \\ F_n &= \frac{d}{dx} (F_{n-1}) \\ &= \frac{\partial}{\partial x} F_{n-1} + \left(\frac{\partial F_{n-1}}{\partial y} \right) y' + \left(\frac{\partial F_{n-1}}{\partial y'} \right) y'' \\ &= \frac{\partial}{\partial x} F_{n-1} + \left(\frac{\partial F_{n-1}}{\partial y} \right) y' + \left(\frac{\partial F_{n-1}}{\partial y'} \right) F_0 \end{aligned} \quad (6)$$

Therefore (6) can be used from now on along with

$$y(x) = y_0 + xy'_0 + \sum_{n=0}^{\infty} \frac{x^{n+2}}{(n+2)!} F_n|_{x_0, y_0, y'_0} \quad (7)$$

To find $y(x)$ series solution around $x = 0$. Hence

$$\begin{aligned}
 F_0 &= \frac{3y'x - 2yx - 2y'}{x - 1} \\
 F_1 &= \frac{dF_0}{dx} \\
 &= \frac{\partial F_0}{\partial x} + \frac{\partial F_0}{\partial y}y' + \frac{\partial F_0}{\partial y'}F_0 \\
 &= \frac{(7x - 3)y' + (-6x - 2)y}{x - 1} \\
 F_2 &= \frac{dF_1}{dx} \\
 &= \frac{\partial F_1}{\partial x} + \frac{\partial F_1}{\partial y}y' + \frac{\partial F_1}{\partial y'}F_1 \\
 &= \frac{(15x - 4)y' + (-14x - 8)y}{x - 1} \\
 F_3 &= \frac{dF_2}{dx} \\
 &= \frac{\partial F_2}{\partial x} + \frac{\partial F_2}{\partial y}y' + \frac{\partial F_2}{\partial y'}F_2 \\
 &= \frac{(31x - 5)y' + (-30x - 22)y}{x - 1} \\
 F_4 &= \frac{dF_3}{dx} \\
 &= \frac{\partial F_3}{\partial x} + \frac{\partial F_3}{\partial y}y' + \frac{\partial F_3}{\partial y'}F_3 \\
 &= \frac{(63x - 6)y' + (-62x - 52)y}{x - 1}
 \end{aligned}$$

And so on. Evaluating all the above at initial conditions $x = 0$ and $y(0) = y(0)$ and $y'(0) = y'(0)$ gives

$$\begin{aligned}
 F_0 &= 2y'(0) \\
 F_1 &= 2y(0) + 3y'(0) \\
 F_2 &= 8y(0) + 4y'(0) \\
 F_3 &= 22y(0) + 5y'(0) \\
 F_4 &= 52y(0) + 6y'(0)
 \end{aligned}$$

Substituting all the above in (7) and simplifying gives the solution as

$$y = \left(1 + \frac{1}{3}x^3 + \frac{1}{3}x^4 + \frac{11}{60}x^5 + \frac{13}{180}x^6\right) y(0) + \left(x + x^2 + \frac{1}{2}x^3 + \frac{1}{6}x^4 + \frac{1}{24}x^5 + \frac{1}{120}x^6\right) y'(0) + O(x^6)$$

Since the expansion point $x = 0$ is an ordinary, we can also solve this using standard power series The ode is normalized to be

$$(x - 1)y'' + (-3x + 2)y' + 2yx = 0$$

Let the solution be represented as power series of the form

$$y = \sum_{n=0}^{\infty} a_n x^n$$

Then

$$y' = \sum_{n=1}^{\infty} n a_n x^{n-1}$$

$$y'' = \sum_{n=2}^{\infty} n(n-1) a_n x^{n-2}$$

Substituting the above back into the ode gives

$$(x - 1) \left(\sum_{n=2}^{\infty} n(n-1) a_n x^{n-2} \right) + (-3x + 2) \left(\sum_{n=1}^{\infty} n a_n x^{n-1} \right) + 2 \left(\sum_{n=0}^{\infty} a_n x^n \right) x = 0 \quad (1)$$

Which simplifies to

$$\left(\sum_{n=2}^{\infty} n x^{n-1} a_n (n-1) \right) + \sum_{n=2}^{\infty} (-n(n-1) a_n x^{n-2}) + \sum_{n=1}^{\infty} (-3n a_n x^n) + \left(\sum_{n=1}^{\infty} 2n a_n x^{n-1} \right) + \left(\sum_{n=0}^{\infty} 2x^{1+n} a_n \right) = 0 \quad (2)$$

The next step is to make all powers of x be n in each summation term. Going over each summation term above with power of x in it which is not already x^n and adjusting the

power and the corresponding index gives

$$\begin{aligned}\sum_{n=2}^{\infty} n x^{n-1} a_n (n-1) &= \sum_{n=1}^{\infty} (1+n) a_{1+n} n x^n \\ \sum_{n=2}^{\infty} (-n(n-1) a_n x^{n-2}) &= \sum_{n=0}^{\infty} (-(n+2) a_{n+2} (1+n) x^n) \\ \sum_{n=1}^{\infty} 2n a_n x^{n-1} &= \sum_{n=0}^{\infty} 2(1+n) a_{1+n} x^n \\ \sum_{n=0}^{\infty} 2x^{1+n} a_n &= \sum_{n=1}^{\infty} 2a_{n-1} x^n\end{aligned}$$

Substituting all the above in Eq (2) gives the following equation where now all powers of x are the same and equal to n .

$$\begin{aligned}\left(\sum_{n=1}^{\infty} (1+n) a_{1+n} n x^n \right) + \sum_{n=0}^{\infty} (-(n+2) a_{n+2} (1+n) x^n) \\ + \sum_{n=1}^{\infty} (-3n a_n x^n) + \left(\sum_{n=0}^{\infty} 2(1+n) a_{1+n} x^n \right) + \left(\sum_{n=1}^{\infty} 2a_{n-1} x^n \right) = 0\end{aligned}\tag{3}$$

$n = 0$ gives

$$-2a_2 + 2a_1 = 0$$

$$a_2 = a_1$$

For $1 \leq n$, the recurrence equation is

$$(1+n) a_{1+n} n - (n+2) a_{n+2} (1+n) - 3n a_n + 2(1+n) a_{1+n} + 2a_{n-1} = 0\tag{4}$$

Solving for a_{n+2} , gives

$$\begin{aligned}a_{n+2} &= \frac{n^2 a_{1+n} - 3n a_n + 3n a_{1+n} + 2a_{1+n} + 2a_{n-1}}{(n+2)(1+n)} \\ (5) \quad &= -\frac{3n a_n}{(n+2)(1+n)} + \frac{(n^2 + 3n + 2) a_{1+n}}{(n+2)(1+n)} + \frac{2a_{n-1}}{(n+2)(1+n)}\end{aligned}$$

For $n = 1$ the recurrence equation gives

$$6a_2 - 6a_3 - 3a_1 + 2a_0 = 0$$

Which after substituting the earlier terms found becomes

$$a_3 = \frac{a_1}{2} + \frac{a_0}{3}$$

For $n = 2$ the recurrence equation gives

$$12a_3 - 12a_4 - 6a_2 + 2a_1 = 0$$

Which after substituting the earlier terms found becomes

$$a_4 = \frac{a_1}{6} + \frac{a_0}{3}$$

For $n = 3$ the recurrence equation gives

$$20a_4 - 20a_5 - 9a_3 + 2a_2 = 0$$

Which after substituting the earlier terms found becomes

$$a_5 = \frac{a_1}{24} + \frac{11a_0}{60}$$

For $n = 4$ the recurrence equation gives

$$30a_5 - 30a_6 - 12a_4 + 2a_3 = 0$$

Which after substituting the earlier terms found becomes

$$a_6 = \frac{a_1}{120} + \frac{13a_0}{180}$$

For $n = 5$ the recurrence equation gives

$$42a_6 - 42a_7 - 15a_5 + 2a_4 = 0$$

Which after substituting the earlier terms found becomes

$$a_7 = \frac{a_1}{720} + \frac{19a_0}{840}$$

And so on. Therefore the solution is

$$\begin{aligned} y &= \sum_{n=0}^{\infty} a_n x^n \\ &= a_3 x^3 + a_2 x^2 + a_1 x + a_0 + \dots \end{aligned}$$

Substituting the values for a_n found above, the solution becomes

$$y = a_0 + a_1 x + a_1 x^2 + \left(\frac{a_1}{2} + \frac{a_0}{3}\right) x^3 + \left(\frac{a_1}{6} + \frac{a_0}{3}\right) x^4 + \left(\frac{a_1}{24} + \frac{11a_0}{60}\right) x^5 + \dots$$

Collecting terms, the solution becomes

$$y = \left(1 + \frac{1}{3}x^3 + \frac{1}{3}x^4 + \frac{11}{60}x^5\right) a_0 + \left(x + x^2 + \frac{1}{2}x^3 + \frac{1}{6}x^4 + \frac{1}{24}x^5\right) a_1 + O(x^6) \quad (3)$$

At $x = 0$ the solution above becomes

$$y = \left(1 + \frac{1}{3}x^3 + \frac{1}{3}x^4 + \frac{11}{60}x^5\right) c_1 + \left(x + x^2 + \frac{1}{2}x^3 + \frac{1}{6}x^4 + \frac{1}{24}x^5\right) c_2 + O(x^6)$$

Summary

The solution(s) found are the following

$$\begin{aligned} y &= \left(1 + \frac{1}{3}x^3 + \frac{1}{3}x^4 + \frac{11}{60}x^5 + \frac{13}{180}x^6\right) y(0) \\ &\quad + \left(x + x^2 + \frac{1}{2}x^3 + \frac{1}{6}x^4 + \frac{1}{24}x^5 + \frac{1}{120}x^6\right) y'(0) + O(x^6) \end{aligned} \quad (1)$$

$$y = \left(1 + \frac{1}{3}x^3 + \frac{1}{3}x^4 + \frac{11}{60}x^5\right) c_1 + \left(x + x^2 + \frac{1}{2}x^3 + \frac{1}{6}x^4 + \frac{1}{24}x^5\right) c_2 + O(x^6) \quad (2)$$

Verification of solutions

$$\begin{aligned} y &= \left(1 + \frac{1}{3}x^3 + \frac{1}{3}x^4 + \frac{11}{60}x^5 + \frac{13}{180}x^6\right) y(0) \\ &\quad + \left(x + x^2 + \frac{1}{2}x^3 + \frac{1}{6}x^4 + \frac{1}{24}x^5 + \frac{1}{120}x^6\right) y'(0) + O(x^6) \end{aligned}$$

Verified OK.

$$y = \left(1 + \frac{1}{3}x^3 + \frac{1}{3}x^4 + \frac{11}{60}x^5\right) c_1 + \left(x + x^2 + \frac{1}{2}x^3 + \frac{1}{6}x^4 + \frac{1}{24}x^5\right) c_2 + O(x^6)$$

Verified OK.

14.8.1 Maple step by step solution

Let's solve

$$(x - 1) y'' + (-3x + 2) y' + 2yx = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = -\frac{2xy}{x-1} + \frac{(3x-2)y'}{x-1}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' - \frac{(3x-2)y'}{x-1} + \frac{2xy}{x-1} = 0$$

- Check to see if $x_0 = 1$ is a regular singular point

- Define functions

$$[P_2(x) = -\frac{3x-2}{x-1}, P_3(x) = \frac{2x}{x-1}]$$

- $(x - 1) \cdot P_2(x)$ is analytic at $x = 1$

$$((x - 1) \cdot P_2(x)) \Big|_{x=1} = -1$$

- $(x - 1)^2 \cdot P_3(x)$ is analytic at $x = 1$

$$((x - 1)^2 \cdot P_3(x)) \Big|_{x=1} = 0$$

- $x = 1$ is a regular singular point

Check to see if $x_0 = 1$ is a regular singular point

$$x_0 = 1$$

- Multiply by denominators

$$(x - 1) y'' + (-3x + 2) y' + 2yx = 0$$

- Change variables using $x = u + 1$ so that the regular singular point is at $u = 0$

$$u \left(\frac{d^2}{du^2} y(u) \right) + (-3u - 1) \left(\frac{d}{du} y(u) \right) + (2u + 2) y(u) = 0$$

- Assume series solution for $y(u)$

$$y(u) = \sum_{k=0}^{\infty} a_k u^{k+r}$$

- Rewrite ODE with series expansions

- Convert $u^m \cdot y(u)$ to series expansion for $m = 0..1$

$$u^m \cdot y(u) = \sum_{k=0}^{\infty} a_k u^{k+r+m}$$

- Shift index using $k \rightarrow k - m$

$$u^m \cdot y(u) = \sum_{k=m}^{\infty} a_{k-m} u^{k+r}$$

- Convert $u^m \cdot \left(\frac{d}{du}y(u)\right)$ to series expansion for $m = 0..1$

$$u^m \cdot \left(\frac{d}{du}y(u)\right) = \sum_{k=0}^{\infty} a_k (k+r) u^{k+r-1+m}$$

- Shift index using $k \rightarrow k + 1 - m$

$$u^m \cdot \left(\frac{d}{du}y(u)\right) = \sum_{k=-1+m}^{\infty} a_{k+1-m} (k+1-m+r) u^{k+r}$$

- Convert $u \cdot \left(\frac{d^2}{du^2}y(u)\right)$ to series expansion

$$u \cdot \left(\frac{d^2}{du^2}y(u)\right) = \sum_{k=0}^{\infty} a_k (k+r)(k+r-1) u^{k+r-1}$$

- Shift index using $k \rightarrow k + 1$

$$u \cdot \left(\frac{d^2}{du^2}y(u)\right) = \sum_{k=-1}^{\infty} a_{k+1} (k+1+r)(k+r) u^{k+r}$$

Rewrite ODE with series expansions

$$a_0 r(-2+r) u^{-1+r} + (a_1(1+r)(-1+r) - a_0(-2+3r)) u^r + \left(\sum_{k=1}^{\infty} (a_{k+1}(k+1+r)(k+r-1) - a_k(-3k-3r+2) + 2a_{k-1}) u^{k+r}\right) = 0$$

- a_0 cannot be 0 by assumption, giving the indicial equation

$$r(-2+r) = 0$$

- Values of r that satisfy the indicial equation

$$r \in \{0, 2\}$$

- Each term must be 0

$$a_1(1+r)(-1+r) - a_0(-2+3r) = 0$$

- Each term in the series must be 0, giving the recursion relation

$$a_{k+1}(k+1+r)(k+r-1) + a_k(-3k-3r+2) + 2a_{k-1} = 0$$

- Shift index using $k \rightarrow k + 1$

$$a_{k+2}(k+2+r)(k+r) + a_{k+1}(-3k-1-3r) + 2a_k = 0$$

- Recursion relation that defines series solution to ODE

$$a_{k+2} = \frac{3ka_{k+1} + 3ra_{k+1} - 2a_k + a_{k+1}}{(k+2+r)(k+r)}$$

- Recursion relation for $r = 0$

$$a_{k+2} = \frac{3ka_{k+1} - 2a_k + a_{k+1}}{(k+2)k}$$

- Series not valid for $r = 0$, division by 0 in the recursion relation at $k = 0$

$$a_{k+2} = \frac{3ka_{k+1} - 2a_k + a_{k+1}}{(k+2)k}$$

- Recursion relation for $r = 2$

$$a_{k+2} = \frac{3ka_{k+1} - 2a_k + 7a_{k+1}}{(k+4)(k+2)}$$

- Solution for $r = 2$

$$\left[y(u) = \sum_{k=0}^{\infty} a_k u^{k+2}, a_{k+2} = \frac{3ka_{k+1} - 2a_k + 7a_{k+1}}{(k+4)(k+2)}, 3a_1 - 4a_0 = 0 \right]$$

- Revert the change of variables $u = x - 1$

$$\left[y = \sum_{k=0}^{\infty} a_k (x - 1)^{k+2}, a_{k+2} = \frac{3ka_{k+1} - 2a_k + 7a_{k+1}}{(k+4)(k+2)}, 3a_1 - 4a_0 = 0 \right]$$

Maple trace Kovacic algorithm successful

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
trying a symmetry of the form [xi=0, eta=F(x)]
checking if the LODE is missing y
-> Trying a Liouvillian solution using Kovacics algorithm
    A Liouvillian solution exists
    Reducible group (found an exponential solution)
    Reducible group (found another exponential solution)
<- Kovacics algorithm successful`

```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 47

```

Order:=6;
dsolve((x-1)*diff(y(x),x$2)-(3*x-2)*diff(y(x),x)+2*x*y(x)=0,y(x),type='series',x=0);

```

$$y(x) = \left(1 + \frac{1}{3}x^3 + \frac{1}{3}x^4 + \frac{11}{60}x^5\right) y(0) + \left(x + x^2 + \frac{1}{2}x^3 + \frac{1}{6}x^4 + \frac{1}{24}x^5\right) D(y)(0) + O(x^6)$$

✓ Solution by Mathematica

Time used: 0.001 (sec). Leaf size: 59

```
AsymptoticDSolveValue[(x-1)*y''[x]-(3*x-2)*y'[x]+2*x*y[x]==0,y[x],{x,0,5}]
```

$$y(x) \rightarrow c_1 \left(\frac{11x^5}{60} + \frac{x^4}{3} + \frac{x^3}{3} + 1 \right) + c_2 \left(\frac{x^5}{24} + \frac{x^4}{6} + \frac{x^3}{2} + x^2 + x \right)$$

14.9 problem 9

14.9.1 Maple step by step solution 3925

Internal problem ID [11892]

Internal file name [OUTPUT/11901_Saturday_April_13_2024_01_14_22_AM_46985098/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.1. Exercises page 232

Problem number: 9.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"second order series method. Ordinary point", "second order series method. Taylor series method"**

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$(x^3 - 1)y'' + x^2y' + yx = 0$$

With the expansion point for the power series method at $x = 0$.

Solving ode using Taylor series method. This gives review on how the Taylor series method works for solving second order ode.

Let

$$y'' = f(x, y, y')$$

Assuming expansion is at $x_0 = 0$ (we can always shift the actual expansion point to 0 by change of variables) and assuming $f(x, y, y')$ is analytic at x_0 which must be the case for an ordinary point. Let initial conditions be $y(x_0) = y_0$ and $y'(x_0) = y'_0$. Using Taylor series gives

$$\begin{aligned} y(x) &= y(x_0) + (x - x_0)y'(x_0) + \frac{(x - x_0)^2}{2}y''(x_0) + \frac{(x - x_0)^3}{3!}y'''(x_0) + \cdots \\ &= y_0 + xy'_0 + \frac{x^2}{2}f|_{x_0, y_0, y'_0} + \frac{x^3}{3!}f'|_{x_0, y_0, y'_0} + \cdots \\ &= y_0 + xy'_0 + \sum_{n=0}^{\infty} \frac{x^{n+2}}{(n+2)!} \frac{d^n f}{dx^n} \Big|_{x_0, y_0, y'_0} \end{aligned}$$

But

$$\frac{df}{dx} = \frac{\partial f}{\partial x} \frac{dx}{dx} + \frac{\partial f}{\partial y} \frac{dy}{dx} + \frac{\partial f}{\partial y'} \frac{dy'}{dx} \quad (1)$$

$$= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} y'' \quad (807)$$

$$= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} f \quad (808)$$

$$\begin{aligned} \frac{d^2 f}{dx^2} &= \frac{d}{dx} \left(\frac{df}{dx} \right) \\ &= \frac{\partial}{\partial x} \left(\frac{df}{dx} \right) + \frac{\partial}{\partial y} \left(\frac{df}{dx} \right) y' + \frac{\partial}{\partial y'} \left(\frac{df}{dx} \right) f \end{aligned} \quad (2)$$

$$\begin{aligned} \frac{d^3 f}{dx^3} &= \frac{d}{dx} \left(\frac{d^2 f}{dx^2} \right) \\ &= \frac{\partial}{\partial x} \left(\frac{d^2 f}{dx^2} \right) + \left(\frac{\partial}{\partial y} \frac{d^2 f}{dx^2} \right) y' + \frac{\partial}{\partial y'} \left(\frac{d^2 f}{dx^2} \right) f \end{aligned} \quad (3)$$

⋮

And so on. Hence if we name $F_0 = f(x, y, y')$ then the above can be written as

$$F_0 = f(x, y, y') \tag{4}$$

$$\begin{aligned} F_1 &= \frac{df}{dx} \\ &= \frac{dF_0}{dx} \\ &= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y}y' + \frac{\partial f}{\partial y'}y'' \\ &= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y}y' + \frac{\partial f}{\partial y'}f \\ &= \frac{\partial F_0}{\partial x} + \frac{\partial F_0}{\partial y}y' + \frac{\partial F_0}{\partial y'}F_0 \end{aligned} \tag{5}$$

$$\begin{aligned} F_2 &= \frac{d}{dx} \left(\frac{d}{dx} f \right) \\ &= \frac{d}{dx} (F_1) \\ &= \frac{\partial}{\partial x} F_1 + \left(\frac{\partial F_1}{\partial y} \right) y' + \left(\frac{\partial F_1}{\partial y'} \right) y'' \\ &= \frac{\partial}{\partial x} F_1 + \left(\frac{\partial F_1}{\partial y} \right) y' + \left(\frac{\partial F_1}{\partial y'} \right) F_0 \end{aligned}$$

⋮

$$\begin{aligned} F_n &= \frac{d}{dx} (F_{n-1}) \\ &= \frac{\partial}{\partial x} F_{n-1} + \left(\frac{\partial F_{n-1}}{\partial y} \right) y' + \left(\frac{\partial F_{n-1}}{\partial y'} \right) y'' \\ &= \frac{\partial}{\partial x} F_{n-1} + \left(\frac{\partial F_{n-1}}{\partial y} \right) y' + \left(\frac{\partial F_{n-1}}{\partial y'} \right) F_0 \end{aligned} \tag{6}$$

Therefore (6) can be used from now on along with

$$y(x) = y_0 + xy'_0 + \sum_{n=0}^{\infty} \frac{x^{n+2}}{(n+2)!} F_n|_{x_0, y_0, y'_0} \tag{7}$$

To find $y(x)$ series solution around $x = 0$. Hence

$$\begin{aligned}
 F_0 &= -\frac{x(y'x + y)}{x^3 - 1} \\
 F_1 &= \frac{dF_0}{dx} \\
 &= \frac{\partial F_0}{\partial x} + \frac{\partial F_0}{\partial y}y' + \frac{\partial F_0}{\partial y'}F_0 \\
 &= \frac{x^4y' + 3yx^3 + 3y'x + y}{(x^3 - 1)^2} \\
 F_2 &= \frac{dF_1}{dx} \\
 &= \frac{\partial F_1}{\partial x} + \frac{\partial F_1}{\partial y}y' + \frac{\partial F_1}{\partial y'}F_1 \\
 &= \frac{-10yx^5 - 24y'x^3 - 18x^2y - 4y'}{(x^3 - 1)^3} \\
 F_3 &= \frac{dF_2}{dx} \\
 &= \frac{\partial F_2}{\partial x} + \frac{\partial F_2}{\partial y}y' + \frac{\partial F_2}{\partial y'}F_2 \\
 &= -\frac{10x((x^7 - 16x^4 - 13x)y' - 4y(x^6 + 5x^3 + 1))}{(x^3 - 1)^4} \\
 F_4 &= \frac{dF_3}{dx} \\
 &= \frac{\partial F_3}{\partial x} + \frac{\partial F_3}{\partial y}y' + \frac{\partial F_3}{\partial y'}F_3 \\
 &= \frac{(90x^{10} - 1040x^7 - 2390x^4 - 300x)y' - 190(x^9 + \frac{204}{19}x^6 + \frac{137}{19}x^3 + \frac{4}{19})y}{(x^3 - 1)^5}
 \end{aligned}$$

And so on. Evaluating all the above at initial conditions $x = 0$ and $y(0) = y(0)$ and $y'(0) = y'(0)$ gives

$$\begin{aligned}
 F_0 &= 0 \\
 F_1 &= y(0) \\
 F_2 &= 4y'(0) \\
 F_3 &= 0 \\
 F_4 &= 40y(0)
 \end{aligned}$$

Substituting all the above in (7) and simplifying gives the solution as

$$y = \left(1 + \frac{1}{6}x^3 + \frac{1}{18}x^6\right)y(0) + \left(x + \frac{1}{6}x^4\right)y'(0) + O(x^6)$$

Since the expansion point $x = 0$ is an ordinary, we can also solve this using standard power series. The ode is normalized to be

$$(x^3 - 1)y'' + x^2y' + yx = 0$$

Let the solution be represented as power series of the form

$$y = \sum_{n=0}^{\infty} a_n x^n$$

Then

$$y' = \sum_{n=1}^{\infty} n a_n x^{n-1}$$

$$y'' = \sum_{n=2}^{\infty} n(n-1) a_n x^{n-2}$$

Substituting the above back into the ode gives

$$(x^3 - 1) \left(\sum_{n=2}^{\infty} n(n-1) a_n x^{n-2} \right) + x^2 \left(\sum_{n=1}^{\infty} n a_n x^{n-1} \right) + \left(\sum_{n=0}^{\infty} a_n x^n \right) x = 0 \quad (1)$$

Which simplifies to

$$\left(\sum_{n=2}^{\infty} n x^{1+n} a_n (n-1) \right) + \sum_{n=2}^{\infty} (-n(n-1) a_n x^{n-2}) + \left(\sum_{n=1}^{\infty} n x^{1+n} a_n \right) + \left(\sum_{n=0}^{\infty} x^{1+n} a_n \right) = 0 \quad (2)$$

The next step is to make all powers of x be n in each summation term. Going over each summation term above with power of x in it which is not already x^n and adjusting the power and the corresponding index gives

$$\sum_{n=2}^{\infty} n x^{1+n} a_n (n-1) = \sum_{n=3}^{\infty} (n-1) a_{n-1} (n-2) x^n$$

$$\sum_{n=2}^{\infty} (-n(n-1) a_n x^{n-2}) = \sum_{n=0}^{\infty} (-(n+2) a_{n+2} (1+n) x^n)$$

$$\sum_{n=1}^{\infty} n x^{1+n} a_n = \sum_{n=2}^{\infty} (n-1) a_{n-1} x^n$$

$$\sum_{n=0}^{\infty} x^{1+n} a_n = \sum_{n=1}^{\infty} a_{n-1} x^n$$

Substituting all the above in Eq (2) gives the following equation where now all powers of x are the same and equal to n .

$$\begin{aligned} & \left(\sum_{n=3}^{\infty} (n-1) a_{n-1} (n-2) x^n \right) + \sum_{n=0}^{\infty} (-(n+2) a_{n+2} (1+n) x^n) \\ & + \left(\sum_{n=2}^{\infty} (n-1) a_{n-1} x^n \right) + \left(\sum_{n=1}^{\infty} a_{n-1} x^n \right) = 0 \end{aligned} \quad (3)$$

$n = 1$ gives

$$-6a_3 + a_0 = 0$$

Which after substituting earlier equations, simplifies to

$$a_3 = \frac{a_0}{6}$$

$n = 2$ gives

$$-12a_4 + 2a_1 = 0$$

Which after substituting earlier equations, simplifies to

$$a_4 = \frac{a_1}{6}$$

For $3 \leq n$, the recurrence equation is

$$(n-1) a_{n-1} (n-2) - (n+2) a_{n+2} (1+n) + (n-1) a_{n-1} + a_{n-1} = 0 \quad (4)$$

Solving for a_{n+2} , gives

$$a_{n+2} = \frac{a_{n-1} (n^2 - 2n + 2)}{(n+2) (1+n)} \quad (5)$$

For $n = 3$ the recurrence equation gives

$$5a_2 - 20a_5 = 0$$

Which after substituting the earlier terms found becomes

$$a_5 = 0$$

For $n = 4$ the recurrence equation gives

$$10a_3 - 30a_6 = 0$$

Which after substituting the earlier terms found becomes

$$a_6 = \frac{a_0}{18}$$

For $n = 5$ the recurrence equation gives

$$17a_4 - 42a_7 = 0$$

Which after substituting the earlier terms found becomes

$$a_7 = \frac{17a_1}{252}$$

And so on. Therefore the solution is

$$\begin{aligned} y &= \sum_{n=0}^{\infty} a_n x^n \\ &= a_3 x^3 + a_2 x^2 + a_1 x + a_0 + \dots \end{aligned}$$

Substituting the values for a_n found above, the solution becomes

$$y = a_0 + a_1 x + \frac{1}{6} a_0 x^3 + \frac{1}{6} a_1 x^4 + \dots$$

Collecting terms, the solution becomes

$$y = \left(1 + \frac{x^3}{6}\right) a_0 + \left(x + \frac{1}{6} x^4\right) a_1 + O(x^6) \quad (3)$$

At $x = 0$ the solution above becomes

$$y = \left(1 + \frac{x^3}{6}\right) c_1 + \left(x + \frac{1}{6} x^4\right) c_2 + O(x^6)$$

Summary

The solution(s) found are the following

$$y = \left(1 + \frac{1}{6} x^3 + \frac{1}{18} x^6\right) y(0) + \left(x + \frac{1}{6} x^4\right) y'(0) + O(x^6) \quad (1)$$

$$y = \left(1 + \frac{x^3}{6}\right) c_1 + \left(x + \frac{1}{6} x^4\right) c_2 + O(x^6) \quad (2)$$

Verification of solutions

$$y = \left(1 + \frac{1}{6}x^3 + \frac{1}{18}x^6\right) y(0) + \left(x + \frac{1}{6}x^4\right) y'(0) + O(x^6)$$

Verified OK.

$$y = \left(1 + \frac{x^3}{6}\right) c_1 + \left(x + \frac{1}{6}x^4\right) c_2 + O(x^6)$$

Verified OK.

14.9.1 Maple step by step solution

Let's solve

$$(x^3 - 1)y'' + x^2y' + yx = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = -\frac{x^2y'}{x^3-1} - \frac{xy}{x^3-1}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + \frac{x^2y'}{x^3-1} + \frac{xy}{x^3-1} = 0$$

- Check to see if x_0 is a regular singular point

- Define functions

$$\left[P_2(x) = \frac{x^2}{x^3-1}, P_3(x) = \frac{x}{x^3-1} \right]$$

- $(x-1) \cdot P_2(x)$ is analytic at $x = 1$

$$\left. ((x-1) \cdot P_2(x)) \right|_{x=1} = \frac{1}{3}$$

- $(x-1)^2 \cdot P_3(x)$ is analytic at $x = 1$

$$\left. ((x-1)^2 \cdot P_3(x)) \right|_{x=1} = 0$$

- $x = 1$ is a regular singular point

Check to see if x_0 is a regular singular point

$$x_0 = 1$$

- Multiply by denominators

$$(x^3 - 1)y'' + x^2y' + yx = 0$$

- Change variables using $x = u + 1$ so that the regular singular point is at $u = 0$

$$(u^3 + 3u^2 + 3u) \left(\frac{d^2}{du^2} y(u) \right) + (u^2 + 2u + 1) \left(\frac{d}{du} y(u) \right) + (u + 1) y(u) = 0$$

- Assume series solution for $y(u)$

$$y(u) = \sum_{k=0}^{\infty} a_k u^{k+r}$$

- Rewrite ODE with series expansions

- Convert $u^m \cdot y(u)$ to series expansion for $m = 0..1$

$$u^m \cdot y(u) = \sum_{k=0}^{\infty} a_k u^{k+r+m}$$

- Shift index using $k- > k - m$

$$u^m \cdot y(u) = \sum_{k=m}^{\infty} a_{k-m} u^{k+r}$$

- Convert $u^m \cdot \left(\frac{d}{du} y(u) \right)$ to series expansion for $m = 0..2$

$$u^m \cdot \left(\frac{d}{du} y(u) \right) = \sum_{k=0}^{\infty} a_k (k+r) u^{k+r-1+m}$$

- Shift index using $k- > k + 1 - m$

$$u^m \cdot \left(\frac{d}{du} y(u) \right) = \sum_{k=-1+m}^{\infty} a_{k+1-m} (k+1-m+r) u^{k+r}$$

- Convert $u^m \cdot \left(\frac{d^2}{du^2} y(u) \right)$ to series expansion for $m = 1..3$

$$u^m \cdot \left(\frac{d^2}{du^2} y(u) \right) = \sum_{k=0}^{\infty} a_k (k+r)(k+r-1) u^{k+r-2+m}$$

- Shift index using $k- > k + 2 - m$

$$u^m \cdot \left(\frac{d^2}{du^2} y(u) \right) = \sum_{k=-2+m}^{\infty} a_{k+2-m} (k+2-m+r)(k+1-m+r) u^{k+r}$$

Rewrite ODE with series expansions

$$a_0 r(-2+3r) u^{-1+r} + (a_1(1+r)(1+3r) + a_0(3r^2 - r + 1)) u^r + \left(\sum_{k=1}^{\infty} (a_{k+1}(k+1+r)(3k+1) \right.$$

- a_0 cannot be 0 by assumption, giving the indicial equation

$$r(-2+3r) = 0$$

- Values of r that satisfy the indicial equation

$$r \in \left\{ 0, \frac{2}{3} \right\}$$

- Each term must be 0

$$a_1(1+r)(1+3r) + a_0(3r^2 - r + 1) = 0$$

- Each term in the series must be 0, giving the recursion relation

$$(3a_k + a_{k-1} + 3a_{k+1})k^2 + ((6a_k + 2a_{k-1} + 6a_{k+1})r - a_k - 2a_{k-1} + 4a_{k+1})k + (3a_k + a_{k-1} + 3a_{k+1}) = 0$$

- Shift index using $k \rightarrow k+1$

$$(3a_{k+1} + a_k + 3a_{k+2})(k+1)^2 + ((6a_{k+1} + 2a_k + 6a_{k+2})r - a_{k+1} - 2a_k + 4a_{k+2})(k+1) + (3a_{k+1} + a_k + 3a_{k+2}) = 0$$

- Recursion relation that defines series solution to ODE

$$a_{k+2} = -\frac{k^2 a_k + 3k^2 a_{k+1} + 2kra_k + 6kra_{k+1} + r^2 a_k + 3r^2 a_{k+1} + 5ka_{k+1} + 5ra_{k+1} + a_k + 3a_{k+1}}{3k^2 + 6kr + 3r^2 + 10k + 10r + 8}$$

- Recursion relation for $r = 0$

$$a_{k+2} = -\frac{k^2 a_k + 3k^2 a_{k+1} + 5ka_{k+1} + a_k + 3a_{k+1}}{3k^2 + 10k + 8}$$

- Solution for $r = 0$

$$\left[y(u) = \sum_{k=0}^{\infty} a_k u^k, a_{k+2} = -\frac{k^2 a_k + 3k^2 a_{k+1} + 5ka_{k+1} + a_k + 3a_{k+1}}{3k^2 + 10k + 8}, a_1 + a_0 = 0 \right]$$

- Revert the change of variables $u = x - 1$

$$\left[y = \sum_{k=0}^{\infty} a_k (x-1)^k, a_{k+2} = -\frac{k^2 a_k + 3k^2 a_{k+1} + 5ka_{k+1} + a_k + 3a_{k+1}}{3k^2 + 10k + 8}, a_1 + a_0 = 0 \right]$$

- Recursion relation for $r = \frac{2}{3}$

$$a_{k+2} = -\frac{k^2 a_k + 3k^2 a_{k+1} + \frac{4}{3}ka_k + 9ka_{k+1} + \frac{13}{9}a_k + \frac{23}{3}a_{k+1}}{3k^2 + 14k + 16}$$

- Solution for $r = \frac{2}{3}$

$$\left[y(u) = \sum_{k=0}^{\infty} a_k u^{k+\frac{2}{3}}, a_{k+2} = -\frac{k^2 a_k + 3k^2 a_{k+1} + \frac{4}{3}ka_k + 9ka_{k+1} + \frac{13}{9}a_k + \frac{23}{3}a_{k+1}}{3k^2 + 14k + 16}, 5a_1 + \frac{5a_0}{3} = 0 \right]$$

- Revert the change of variables $u = x - 1$

$$\left[y = \sum_{k=0}^{\infty} a_k (x-1)^{k+\frac{2}{3}}, a_{k+2} = -\frac{k^2 a_k + 3k^2 a_{k+1} + \frac{4}{3}ka_k + 9ka_{k+1} + \frac{13}{9}a_k + \frac{23}{3}a_{k+1}}{3k^2 + 14k + 16}, 5a_1 + \frac{5a_0}{3} = 0 \right]$$

- Combine solutions and rename parameters

$$\left[y = \left(\sum_{k=0}^{\infty} a_k (x-1)^k \right) + \left(\sum_{k=0}^{\infty} b_k (x-1)^{k+\frac{2}{3}} \right), a_{k+2} = -\frac{k^2 a_k + 3k^2 a_{k+1} + 5ka_{k+1} + a_k + 3a_{k+1}}{3k^2 + 10k + 8}, a_1 + a_0 = 0 \right]$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
checking if the LODE is of Euler type  
trying a symmetry of the form [xi=0, eta=F(x)]  
checking if the LODE is missing y  
-> Trying a Liouvillian solution using Kovacic's algorithm  
<- No Liouvillian solutions exist  
-> Trying a solution in terms of special functions:  
  -> Bessel  
  -> elliptic  
  -> Legendre  
  -> Kummer  
    -> hyper3: Equivalence to 1F1 under a power @ Moebius  
  -> hypergeometric  
    -> heuristic approach  
      <- heuristic approach successful  
    <- hypergeometric successful  
<- special function solution successful`
```

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 24

```
Order:=6;
```

```
dsolve((x^3-1)*diff(y(x),x$2)+x^2*diff(y(x),x)+x*y(x)=0,y(x),type='series',x=0);
```

$$y(x) = \left(1 + \frac{x^3}{6}\right) y(0) + \left(x + \frac{1}{6}x^4\right) D(y)(0) + O(x^6)$$

✓ Solution by Mathematica

Time used: 0.001 (sec). Leaf size: 28

```
AsymptoticDSolveValue[(x^3-1)*y''[x]+x^2*y'[x]+x*y[x]==0,y[x],{x,0,5}]
```

$$y(x) \rightarrow c_2 \left(\frac{x^4}{6} + x\right) + c_1 \left(\frac{x^3}{6} + 1\right)$$

14.10 problem 10

14.10.1 Maple step by step solution 3937

Internal problem ID [11893]

Internal file name [OUTPUT/11902_Saturday_April_13_2024_01_14_23_AM_37826173/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.1. Exercises page 232

Problem number: 10.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"exact linear second order ode", "second_order_integrable_as_is", "second order series method. Ordinary point", "second order series method. Taylor series method"**

Maple gives the following as the ode type

```
[[_2nd_order , _exact , _linear , _homogeneous]]
```

$$(x + 3)y'' + (x + 2)y' + y = 0$$

With the expansion point for the power series method at $x = 0$.

Solving ode using Taylor series method. This gives review on how the Taylor series method works for solving second order ode.

Let

$$y'' = f(x, y, y')$$

Assuming expansion is at $x_0 = 0$ (we can always shift the actual expansion point to 0 by change of variables) and assuming $f(x, y, y')$ is analytic at x_0 which must be the case for an ordinary point. Let initial conditions be $y(x_0) = y_0$ and $y'(x_0) = y'_0$. Using

Taylor series gives

$$\begin{aligned}
 y(x) &= y(x_0) + (x - x_0)y'(x_0) + \frac{(x - x_0)^2}{2}y''(x_0) + \frac{(x - x_0)^3}{3!}y'''(x_0) + \cdots \\
 &= y_0 + xy'_0 + \frac{x^2}{2}f|_{x_0, y_0, y'_0} + \frac{x^3}{3!}f'|_{x_0, y_0, y'_0} + \cdots \\
 &= y_0 + xy'_0 + \sum_{n=0}^{\infty} \frac{x^{n+2}}{(n+2)!} \frac{d^n f}{dx^n} \Big|_{x_0, y_0, y'_0}
 \end{aligned}$$

But

$$\frac{df}{dx} = \frac{\partial f}{\partial x} \frac{dx}{dx} + \frac{\partial f}{\partial y} \frac{dy}{dx} + \frac{\partial f}{\partial y'} \frac{dy'}{dx} \tag{1}$$

$$= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} y'' \tag{810}$$

$$= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} f \tag{811}$$

$$\begin{aligned}
 \frac{d^2 f}{dx^2} &= \frac{d}{dx} \left(\frac{df}{dx} \right) \\
 &= \frac{\partial}{\partial x} \left(\frac{df}{dx} \right) + \frac{\partial}{\partial y} \left(\frac{df}{dx} \right) y' + \frac{\partial}{\partial y'} \left(\frac{df}{dx} \right) f \tag{2}
 \end{aligned}$$

$$\begin{aligned}
 \frac{d^3 f}{dx^3} &= \frac{d}{dx} \left(\frac{d^2 f}{dx^2} \right) \\
 &= \frac{\partial}{\partial x} \left(\frac{d^2 f}{dx^2} \right) + \left(\frac{\partial}{\partial y} \frac{d^2 f}{dx^2} \right) y' + \frac{\partial}{\partial y'} \left(\frac{d^2 f}{dx^2} \right) f \tag{3}
 \end{aligned}$$

⋮

And so on. Hence if we name $F_0 = f(x, y, y')$ then the above can be written as

$$F_0 = f(x, y, y') \quad (4)$$

$$\begin{aligned} F_1 &= \frac{df}{dx} \\ &= \frac{dF_0}{dx} \\ &= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y}y' + \frac{\partial f}{\partial y'}y'' \\ &= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y}y' + \frac{\partial f}{\partial y'}f \\ &= \frac{\partial F_0}{\partial x} + \frac{\partial F_0}{\partial y}y' + \frac{\partial F_0}{\partial y'}F_0 \end{aligned} \quad (5)$$

$$\begin{aligned} F_2 &= \frac{d}{dx} \left(\frac{d}{dx} f \right) \\ &= \frac{d}{dx} (F_1) \\ &= \frac{\partial}{\partial x} F_1 + \left(\frac{\partial F_1}{\partial y} \right) y' + \left(\frac{\partial F_1}{\partial y'} \right) y'' \\ &= \frac{\partial}{\partial x} F_1 + \left(\frac{\partial F_1}{\partial y} \right) y' + \left(\frac{\partial F_1}{\partial y'} \right) F_0 \\ &\vdots \\ F_n &= \frac{d}{dx} (F_{n-1}) \\ &= \frac{\partial}{\partial x} F_{n-1} + \left(\frac{\partial F_{n-1}}{\partial y} \right) y' + \left(\frac{\partial F_{n-1}}{\partial y'} \right) y'' \\ &= \frac{\partial}{\partial x} F_{n-1} + \left(\frac{\partial F_{n-1}}{\partial y} \right) y' + \left(\frac{\partial F_{n-1}}{\partial y'} \right) F_0 \end{aligned} \quad (6)$$

Therefore (6) can be used from now on along with

$$y(x) = y_0 + xy'_0 + \sum_{n=0}^{\infty} \frac{x^{n+2}}{(n+2)!} F_n|_{x_0, y_0, y'_0} \quad (7)$$

To find $y(x)$ series solution around $x = 0$. Hence

$$\begin{aligned}
 F_0 &= -\frac{y'x + 2y' + y}{x + 3} \\
 F_1 &= \frac{dF_0}{dx} \\
 &= \frac{\partial F_0}{\partial x} + \frac{\partial F_0}{\partial y}y' + \frac{\partial F_0}{\partial y'}F_0 \\
 &= \frac{y'x + y}{x + 3} \\
 F_2 &= \frac{dF_1}{dx} \\
 &= \frac{\partial F_1}{\partial x} + \frac{\partial F_1}{\partial y}y' + \frac{\partial F_1}{\partial y'}F_1 \\
 &= \frac{(-x^2 - x + 6)y' - y(x + 1)}{(x + 3)^2} \\
 F_3 &= \frac{dF_2}{dx} \\
 &= \frac{\partial F_2}{\partial x} + \frac{\partial F_2}{\partial y}y' + \frac{\partial F_2}{\partial y'}F_2 \\
 &= \frac{(x^3 + 2x^2 - 13x - 30)y' + y(x^2 + 2x - 7)}{(x + 3)^3} \\
 F_4 &= \frac{dF_3}{dx} \\
 &= \frac{\partial F_3}{\partial x} + \frac{\partial F_3}{\partial y}y' + \frac{\partial F_3}{\partial y'}F_3 \\
 &= \frac{-(x + 3)(x^3 - 21x - 30)y' - y(x^3 + 3x^2 - 15x - 57)}{(x + 3)^4}
 \end{aligned}$$

And so on. Evaluating all the above at initial conditions $x = 0$ and $y(0) = y(0)$ and $y'(0) = y'(0)$ gives

$$\begin{aligned}
 F_0 &= -\frac{y(0)}{3} - \frac{2y'(0)}{3} \\
 F_1 &= \frac{y(0)}{3} \\
 F_2 &= -\frac{y(0)}{9} + \frac{2y'(0)}{3} \\
 F_3 &= -\frac{7y(0)}{27} - \frac{10y'(0)}{9} \\
 F_4 &= \frac{19y(0)}{27} + \frac{10y'(0)}{9}
 \end{aligned}$$

Substituting all the above in (7) and simplifying gives the solution as

$$y = \left(1 - \frac{1}{6}x^2 + \frac{1}{18}x^3 - \frac{1}{216}x^4 - \frac{7}{3240}x^5 + \frac{19}{19440}x^6\right) y(0) \\ + \left(x - \frac{1}{3}x^2 + \frac{1}{36}x^4 - \frac{1}{108}x^5 + \frac{1}{648}x^6\right) y'(0) + O(x^6)$$

Since the expansion point $x = 0$ is an ordinary, we can also solve this using standard power series. The ode is normalized to be

$$(x + 3)y'' + (x + 2)y' + y = 0$$

Let the solution be represented as power series of the form

$$y = \sum_{n=0}^{\infty} a_n x^n$$

Then

$$y' = \sum_{n=1}^{\infty} n a_n x^{n-1} \\ y'' = \sum_{n=2}^{\infty} n(n-1) a_n x^{n-2}$$

Substituting the above back into the ode gives

$$(x + 3) \left(\sum_{n=2}^{\infty} n(n-1) a_n x^{n-2} \right) + (x + 2) \left(\sum_{n=1}^{\infty} n a_n x^{n-1} \right) + \left(\sum_{n=0}^{\infty} a_n x^n \right) = 0 \quad (1)$$

Which simplifies to

$$\left(\sum_{n=2}^{\infty} n x^{n-1} a_n (n-1) \right) + \left(\sum_{n=2}^{\infty} 3n(n-1) a_n x^{n-2} \right) \\ + \left(\sum_{n=1}^{\infty} n a_n x^n \right) + \left(\sum_{n=1}^{\infty} 2n a_n x^{n-1} \right) + \left(\sum_{n=0}^{\infty} a_n x^n \right) = 0 \quad (2)$$

The next step is to make all powers of x be n in each summation term. Going over each summation term above with power of x in it which is not already x^n and adjusting the

power and the corresponding index gives

$$\begin{aligned}\sum_{n=2}^{\infty} n x^{n-1} a_n (n-1) &= \sum_{n=1}^{\infty} (n+1) a_{n+1} n x^n \\ \sum_{n=2}^{\infty} 3n(n-1) a_n x^{n-2} &= \sum_{n=0}^{\infty} 3(n+2) a_{n+2} (n+1) x^n \\ \sum_{n=1}^{\infty} 2n a_n x^{n-1} &= \sum_{n=0}^{\infty} 2(n+1) a_{n+1} x^n\end{aligned}$$

Substituting all the above in Eq (2) gives the following equation where now all powers of x are the same and equal to n .

$$\begin{aligned}\left(\sum_{n=1}^{\infty} (n+1) a_{n+1} n x^n\right) &+ \left(\sum_{n=0}^{\infty} 3(n+2) a_{n+2} (n+1) x^n\right) \\ + \left(\sum_{n=1}^{\infty} n a_n x^n\right) &+ \left(\sum_{n=0}^{\infty} 2(n+1) a_{n+1} x^n\right) + \left(\sum_{n=0}^{\infty} a_n x^n\right) = 0\end{aligned}\tag{3}$$

$n = 0$ gives

$$6a_2 + 2a_1 + a_0 = 0$$

$$a_2 = -\frac{a_0}{6} - \frac{a_1}{3}$$

For $1 \leq n$, the recurrence equation is

$$(n+1) a_{n+1} n + 3(n+2) a_{n+2} (n+1) + n a_n + 2(n+1) a_{n+1} + a_n = 0\tag{4}$$

Solving for a_{n+2} , gives

$$\begin{aligned}a_{n+2} &= -\frac{n a_{n+1} + a_n + 2 a_{n+1}}{3(n+2)} \\ (5) \quad &= -\frac{a_n}{3(n+2)} - \frac{a_{n+1}}{3}\end{aligned}$$

For $n = 1$ the recurrence equation gives

$$6a_2 + 18a_3 + 2a_1 = 0$$

Which after substituting the earlier terms found becomes

$$a_3 = \frac{a_0}{18}$$

For $n = 2$ the recurrence equation gives

$$12a_3 + 36a_4 + 3a_2 = 0$$

Which after substituting the earlier terms found becomes

$$a_4 = -\frac{a_0}{216} + \frac{a_1}{36}$$

For $n = 3$ the recurrence equation gives

$$20a_4 + 60a_5 + 4a_3 = 0$$

Which after substituting the earlier terms found becomes

$$a_5 = -\frac{7a_0}{3240} - \frac{a_1}{108}$$

For $n = 4$ the recurrence equation gives

$$30a_5 + 90a_6 + 5a_4 = 0$$

Which after substituting the earlier terms found becomes

$$a_6 = \frac{19a_0}{19440} + \frac{a_1}{648}$$

For $n = 5$ the recurrence equation gives

$$42a_6 + 126a_7 + 6a_5 = 0$$

Which after substituting the earlier terms found becomes

$$a_7 = -\frac{13a_0}{58320} - \frac{a_1}{13608}$$

And so on. Therefore the solution is

$$y = \sum_{n=0}^{\infty} a_n x^n$$

$$= a_3 x^3 + a_2 x^2 + a_1 x + a_0 + \dots$$

Substituting the values for a_n found above, the solution becomes

$$y = a_0 + a_1 x + \left(-\frac{a_0}{6} - \frac{a_1}{3}\right) x^2 + \frac{a_0 x^3}{18} + \left(-\frac{a_0}{216} + \frac{a_1}{36}\right) x^4 + \left(-\frac{7a_0}{3240} - \frac{a_1}{108}\right) x^5 + \dots$$

Collecting terms, the solution becomes

$$y = \left(1 - \frac{1}{6}x^2 + \frac{1}{18}x^3 - \frac{1}{216}x^4 - \frac{7}{3240}x^5\right) a_0 + \left(x - \frac{1}{3}x^2 + \frac{1}{36}x^4 - \frac{1}{108}x^5\right) a_1 + O(x^6)$$
(3)

At $x = 0$ the solution above becomes

$$y = \left(1 - \frac{1}{6}x^2 + \frac{1}{18}x^3 - \frac{1}{216}x^4 - \frac{7}{3240}x^5\right) c_1 + \left(x - \frac{1}{3}x^2 + \frac{1}{36}x^4 - \frac{1}{108}x^5\right) c_2 + O(x^6)$$

Summary

The solution(s) found are the following

$$y = \left(1 - \frac{1}{6}x^2 + \frac{1}{18}x^3 - \frac{1}{216}x^4 - \frac{7}{3240}x^5 + \frac{19}{19440}x^6\right) y(0)$$

$$+ \left(x - \frac{1}{3}x^2 + \frac{1}{36}x^4 - \frac{1}{108}x^5 + \frac{1}{648}x^6\right) y'(0) + O(x^6)$$
(1)

$$y = \left(1 - \frac{1}{6}x^2 + \frac{1}{18}x^3 - \frac{1}{216}x^4 - \frac{7}{3240}x^5\right) c_1 + \left(x - \frac{1}{3}x^2 + \frac{1}{36}x^4 - \frac{1}{108}x^5\right) c_2 + O(x^6)$$
(2)

Verification of solutions

$$y = \left(1 - \frac{1}{6}x^2 + \frac{1}{18}x^3 - \frac{1}{216}x^4 - \frac{7}{3240}x^5 + \frac{19}{19440}x^6\right) y(0)$$

$$+ \left(x - \frac{1}{3}x^2 + \frac{1}{36}x^4 - \frac{1}{108}x^5 + \frac{1}{648}x^6\right) y'(0) + O(x^6)$$

Verified OK.

$$y = \left(1 - \frac{1}{6}x^2 + \frac{1}{18}x^3 - \frac{1}{216}x^4 - \frac{7}{3240}x^5\right) c_1 + \left(x - \frac{1}{3}x^2 + \frac{1}{36}x^4 - \frac{1}{108}x^5\right) c_2 + O(x^6)$$

Verified OK.

14.10.1 Maple step by step solution

Let's solve

$$(x + 3)y'' + (x + 2)y' + y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = -\frac{y}{x+3} - \frac{(x+2)y'}{x+3}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + \frac{(x+2)y'}{x+3} + \frac{y}{x+3} = 0$$

- Check to see if $x_0 = -3$ is a regular singular point

- Define functions

$$[P_2(x) = \frac{x+2}{x+3}, P_3(x) = \frac{1}{x+3}]$$

- $(x + 3) \cdot P_2(x)$ is analytic at $x = -3$

$$((x + 3) \cdot P_2(x)) \Big|_{x=-3} = -1$$

- $(x + 3)^2 \cdot P_3(x)$ is analytic at $x = -3$

$$((x + 3)^2 \cdot P_3(x)) \Big|_{x=-3} = 0$$

- $x = -3$ is a regular singular point

Check to see if $x_0 = -3$ is a regular singular point

$$x_0 = -3$$

- Multiply by denominators

$$(x + 3)y'' + (x + 2)y' + y = 0$$

- Change variables using $x = u - 3$ so that the regular singular point is at $u = 0$

$$u \left(\frac{d^2}{du^2} y(u) \right) + (u - 1) \left(\frac{d}{du} y(u) \right) + y(u) = 0$$

- Assume series solution for $y(u)$

$$y(u) = \sum_{k=0}^{\infty} a_k u^{k+r}$$

- Rewrite ODE with series expansions

- Convert $u^m \cdot \left(\frac{d}{du} y(u) \right)$ to series expansion for $m = 0..1$

$$u^m \cdot \left(\frac{d}{du} y(u) \right) = \sum_{k=0}^{\infty} a_k (k+r) u^{k+r-1+m}$$

- Shift index using $k \rightarrow k+1-m$

$$u^m \cdot \left(\frac{d}{du} y(u) \right) = \sum_{k=-1+m}^{\infty} a_{k+1-m} (k+1-m+r) u^{k+r}$$

- Convert $u \cdot \left(\frac{d^2}{du^2} y(u) \right)$ to series expansion

$$u \cdot \left(\frac{d^2}{du^2} y(u) \right) = \sum_{k=0}^{\infty} a_k (k+r) (k+r-1) u^{k+r-1}$$

- Shift index using $k \rightarrow k+1$

$$u \cdot \left(\frac{d^2}{du^2} y(u) \right) = \sum_{k=-1}^{\infty} a_{k+1} (k+1+r) (k+r) u^{k+r}$$

Rewrite ODE with series expansions

$$a_0 r (-2+r) u^{-1+r} + \left(\sum_{k=0}^{\infty} (a_{k+1} (k+1+r) (k+r-1) + a_k (k+1+r)) u^{k+r} \right) = 0$$

- a_0 cannot be 0 by assumption, giving the indicial equation

$$r(-2+r) = 0$$

- Values of r that satisfy the indicial equation

$$r \in \{0, 2\}$$

- Each term in the series must be 0, giving the recursion relation

$$(k+1+r) (a_{k+1} (k+r-1) + a_k) = 0$$

- Recursion relation that defines series solution to ODE

$$a_{k+1} = -\frac{a_k}{k+r-1}$$

- Recursion relation for $r = 0$

$$a_{k+1} = -\frac{a_k}{k-1}$$

- Series not valid for $r = 0$, division by 0 in the recursion relation at $k = 1$

$$a_{k+1} = -\frac{a_k}{k-1}$$

- Recursion relation for $r = 2$

$$a_{k+1} = -\frac{a_k}{k+1}$$

- Solution for $r = 2$

$$\left[y(u) = \sum_{k=0}^{\infty} a_k u^{k+2}, a_{k+1} = -\frac{a_k}{k+1} \right]$$

- Revert the change of variables $u = x + 3$

$$\left[y = \sum_{k=0}^{\infty} a_k (x + 3)^{k+2}, a_{k+1} = -\frac{a_k}{k+1} \right]$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
trying a symmetry of the form [xi=0, eta=F(x)]
<- linear_1 successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 49

```

Order:=6;
dsolve((x+3)*diff(y(x),x$2)+(x+2)*diff(y(x),x)+y(x)=0,y(x),type='series',x=0);

```

$$y(x) = \left(1 - \frac{1}{6}x^2 + \frac{1}{18}x^3 - \frac{1}{216}x^4 - \frac{7}{3240}x^5 \right) y(0) + \left(x - \frac{1}{3}x^2 + \frac{1}{36}x^4 - \frac{1}{108}x^5 \right) D(y)(0) + O(x^6)$$

✓ Solution by Mathematica

Time used: 0.001 (sec). Leaf size: 63

```

AsymptoticDSolveValue[(x+3)*y''[x]+(x+2)*y'[x]+y[x]==0,y[x],{x,0,5}]

```

$$y(x) \rightarrow c_2 \left(-\frac{x^5}{108} + \frac{x^4}{36} - \frac{x^2}{3} + x \right) + c_1 \left(-\frac{7x^5}{3240} - \frac{x^4}{216} + \frac{x^3}{18} - \frac{x^2}{6} + 1 \right)$$

14.11 problem 11

14.11.1 Existence and uniqueness analysis	3940
14.11.2 Maple step by step solution	3948

Internal problem ID [11894]

Internal file name [OUTPUT/11903_Saturday_April_13_2024_01_14_24_AM_94254307/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.1. Exercises page 232

Problem number: 11.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "exact linear second order ode", "second_order_integrable_as_is", "second order series method. Ordinary point", "second order series method. Taylor series method"

Maple gives the following as the ode type

```
[[_2nd_order , _exact , _linear , _homogeneous]]
```

$$y'' - y'x - y = 0$$

With initial conditions

$$[y(0) = 1, y'(0) = 0]$$

With the expansion point for the power series method at $x = 0$.

14.11.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$p(x) = -x$$

$$q(x) = -1$$

$$F = 0$$

Hence the ode is

$$y'' - y'x - y = 0$$

The domain of $p(x) = -x$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = -1$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

Solving ode using Taylor series method. This gives review on how the Taylor series method works for solving second order ode.

Let

$$y'' = f(x, y, y')$$

Assuming expansion is at $x_0 = 0$ (we can always shift the actual expansion point to 0 by change of variables) and assuming $f(x, y, y')$ is analytic at x_0 which must be the case for an ordinary point. Let initial conditions be $y(x_0) = y_0$ and $y'(x_0) = y'_0$. Using Taylor series gives

$$\begin{aligned} y(x) &= y(x_0) + (x - x_0)y'(x_0) + \frac{(x - x_0)^2}{2}y''(x_0) + \frac{(x - x_0)^3}{3!}y'''(x_0) + \dots \\ &= y_0 + xy'_0 + \frac{x^2}{2}f|_{x_0, y_0, y'_0} + \frac{x^3}{3!}f'|_{x_0, y_0, y'_0} + \dots \\ &= y_0 + xy'_0 + \sum_{n=0}^{\infty} \frac{x^{n+2}}{(n+2)!} \left. \frac{d^n f}{dx^n} \right|_{x_0, y_0, y'_0} \end{aligned}$$

But

$$\frac{df}{dx} = \frac{\partial f}{\partial x} \frac{dx}{dx} + \frac{\partial f}{\partial y} \frac{dy}{dx} + \frac{\partial f}{\partial y'} \frac{dy'}{dx} \quad (1)$$

$$= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} y'' \quad (813)$$

$$= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} f \quad (814)$$

$$\begin{aligned} \frac{d^2 f}{dx^2} &= \frac{d}{dx} \left(\frac{df}{dx} \right) \\ &= \frac{\partial}{\partial x} \left(\frac{df}{dx} \right) + \frac{\partial}{\partial y} \left(\frac{df}{dx} \right) y' + \frac{\partial}{\partial y'} \left(\frac{df}{dx} \right) f \end{aligned} \quad (2)$$

$$\begin{aligned} \frac{d^3 f}{dx^3} &= \frac{d}{dx} \left(\frac{d^2 f}{dx^2} \right) \\ &= \frac{\partial}{\partial x} \left(\frac{d^2 f}{dx^2} \right) + \left(\frac{\partial}{\partial y} \frac{d^2 f}{dx^2} \right) y' + \frac{\partial}{\partial y'} \left(\frac{d^2 f}{dx^2} \right) f \end{aligned} \quad (3)$$

⋮

And so on. Hence if we name $F_0 = f(x, y, y')$ then the above can be written as

$$F_0 = f(x, y, y') \tag{4}$$

$$\begin{aligned} F_1 &= \frac{df}{dx} \\ &= \frac{dF_0}{dx} \\ &= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y}y' + \frac{\partial f}{\partial y'}y'' \\ &= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y}y' + \frac{\partial f}{\partial y'}f \\ &= \frac{\partial F_0}{\partial x} + \frac{\partial F_0}{\partial y}y' + \frac{\partial F_0}{\partial y'}F_0 \end{aligned} \tag{5}$$

$$\begin{aligned} F_2 &= \frac{d}{dx} \left(\frac{d}{dx} f \right) \\ &= \frac{d}{dx} (F_1) \\ &= \frac{\partial}{\partial x} F_1 + \left(\frac{\partial F_1}{\partial y} \right) y' + \left(\frac{\partial F_1}{\partial y'} \right) y'' \\ &= \frac{\partial}{\partial x} F_1 + \left(\frac{\partial F_1}{\partial y} \right) y' + \left(\frac{\partial F_1}{\partial y'} \right) F_0 \end{aligned}$$

⋮

$$\begin{aligned} F_n &= \frac{d}{dx} (F_{n-1}) \\ &= \frac{\partial}{\partial x} F_{n-1} + \left(\frac{\partial F_{n-1}}{\partial y} \right) y' + \left(\frac{\partial F_{n-1}}{\partial y'} \right) y'' \\ &= \frac{\partial}{\partial x} F_{n-1} + \left(\frac{\partial F_{n-1}}{\partial y} \right) y' + \left(\frac{\partial F_{n-1}}{\partial y'} \right) F_0 \end{aligned} \tag{6}$$

Therefore (6) can be used from now on along with

$$y(x) = y_0 + xy'_0 + \sum_{n=0}^{\infty} \frac{x^{n+2}}{(n+2)!} F_n|_{x_0, y_0, y'_0} \tag{7}$$

To find $y(x)$ series solution around $x = 0$. Hence

$$\begin{aligned}
 F_0 &= y'x + y \\
 F_1 &= \frac{dF_0}{dx} \\
 &= \frac{\partial F_0}{\partial x} + \frac{\partial F_0}{\partial y}y' + \frac{\partial F_0}{\partial y'}F_0 \\
 &= x^2y' + yx + 2y' \\
 F_2 &= \frac{dF_1}{dx} \\
 &= \frac{\partial F_1}{\partial x} + \frac{\partial F_1}{\partial y}y' + \frac{\partial F_1}{\partial y'}F_1 \\
 &= (x^3 + 5x)y' + y(x^2 + 3) \\
 F_3 &= \frac{dF_2}{dx} \\
 &= \frac{\partial F_2}{\partial x} + \frac{\partial F_2}{\partial y}y' + \frac{\partial F_2}{\partial y'}F_2 \\
 &= (x^4 + 9x^2 + 8)y' + xy(x^2 + 7) \\
 F_4 &= \frac{dF_3}{dx} \\
 &= \frac{\partial F_3}{\partial x} + \frac{\partial F_3}{\partial y}y' + \frac{\partial F_3}{\partial y'}F_3 \\
 &= (x^5 + 14x^3 + 33x)y' + y(x^4 + 12x^2 + 15)
 \end{aligned}$$

And so on. Evaluating all the above at initial conditions $x = 0$ and $y(0) = 1$ and $y'(0) = 0$ gives

$$\begin{aligned}
 F_0 &= 1 \\
 F_1 &= 0 \\
 F_2 &= 3 \\
 F_3 &= 0 \\
 F_4 &= 15
 \end{aligned}$$

Substituting all the above in (7) and simplifying gives the solution as

$$y = 1 + \frac{x^2}{2} + \frac{x^4}{8} + \frac{x^6}{48} + O(x^6)$$

$$y = 1 + \frac{x^2}{2} + \frac{x^4}{8} + \frac{x^6}{48} + O(x^6)$$

Since the expansion point $x = 0$ is an ordinary, we can also solve this using standard power series. Let the solution be represented as power series of the form

$$y = \sum_{n=0}^{\infty} a_n x^n$$

Then

$$y' = \sum_{n=1}^{\infty} n a_n x^{n-1}$$

$$y'' = \sum_{n=2}^{\infty} n(n-1) a_n x^{n-2}$$

Substituting the above back into the ode gives

$$\sum_{n=2}^{\infty} n(n-1) a_n x^{n-2} = \left(\sum_{n=1}^{\infty} n a_n x^{n-1} \right) x + \left(\sum_{n=0}^{\infty} a_n x^n \right) \quad (1)$$

Which simplifies to

$$\left(\sum_{n=2}^{\infty} n(n-1) a_n x^{n-2} \right) + \sum_{n=1}^{\infty} (-n x^n a_n) + \sum_{n=0}^{\infty} (-a_n x^n) = 0 \quad (2)$$

The next step is to make all powers of x be n in each summation term. Going over each summation term above with power of x in it which is not already x^n and adjusting the power and the corresponding index gives

$$\sum_{n=2}^{\infty} n(n-1) a_n x^{n-2} = \sum_{n=0}^{\infty} (n+2) a_{n+2} (n+1) x^n$$

Substituting all the above in Eq (2) gives the following equation where now all powers of x are the same and equal to n .

$$\left(\sum_{n=0}^{\infty} (n+2) a_{n+2} (n+1) x^n \right) + \sum_{n=1}^{\infty} (-n x^n a_n) + \sum_{n=0}^{\infty} (-a_n x^n) = 0 \quad (3)$$

$n = 0$ gives

$$2a_2 - a_0 = 0$$

$$a_2 = \frac{a_0}{2}$$

For $1 \leq n$, the recurrence equation is

$$(n + 2) a_{n+2}(n + 1) - n a_n - a_n = 0 \quad (4)$$

Solving for a_{n+2} , gives

$$a_{n+2} = \frac{a_n}{n + 2} \quad (5)$$

For $n = 1$ the recurrence equation gives

$$6a_3 - 2a_1 = 0$$

Which after substituting the earlier terms found becomes

$$a_3 = \frac{a_1}{3}$$

For $n = 2$ the recurrence equation gives

$$12a_4 - 3a_2 = 0$$

Which after substituting the earlier terms found becomes

$$a_4 = \frac{a_0}{8}$$

For $n = 3$ the recurrence equation gives

$$20a_5 - 4a_3 = 0$$

Which after substituting the earlier terms found becomes

$$a_5 = \frac{a_1}{15}$$

For $n = 4$ the recurrence equation gives

$$30a_6 - 5a_4 = 0$$

Which after substituting the earlier terms found becomes

$$a_6 = \frac{a_0}{48}$$

For $n = 5$ the recurrence equation gives

$$42a_7 - 6a_5 = 0$$

Which after substituting the earlier terms found becomes

$$a_7 = \frac{a_1}{105}$$

And so on. Therefore the solution is

$$\begin{aligned} y &= \sum_{n=0}^{\infty} a_n x^n \\ &= a_3 x^3 + a_2 x^2 + a_1 x + a_0 + \dots \end{aligned}$$

Substituting the values for a_n found above, the solution becomes

$$y = a_0 + a_1 x + \frac{1}{2} a_0 x^2 + \frac{1}{3} a_1 x^3 + \frac{1}{8} a_0 x^4 + \frac{1}{15} a_1 x^5 + \dots$$

Collecting terms, the solution becomes

$$y = \left(1 + \frac{1}{2}x^2 + \frac{1}{8}x^4\right) a_0 + \left(x + \frac{1}{3}x^3 + \frac{1}{15}x^5\right) a_1 + O(x^6) \quad (3)$$

At $x = 0$ the solution above becomes

$$y = \left(1 + \frac{1}{2}x^2 + \frac{1}{8}x^4\right) c_1 + \left(x + \frac{1}{3}x^3 + \frac{1}{15}x^5\right) c_2 + O(x^6)$$

$$y = 1 + \frac{x^2}{2} + \frac{x^4}{8} + O(x^6)$$

Summary

The solution(s) found are the following

$$y = 1 + \frac{x^2}{2} + \frac{x^4}{8} + \frac{x^6}{48} + O(x^6) \quad (1)$$

$$y = 1 + \frac{x^2}{2} + \frac{x^4}{8} + O(x^6) \quad (2)$$

Verification of solutions

$$y = 1 + \frac{x^2}{2} + \frac{x^4}{8} + \frac{x^6}{48} + O(x^6)$$

Verified OK.

$$y = 1 + \frac{x^2}{2} + \frac{x^4}{8} + O(x^6)$$

Verified OK.

14.11.2 Maple step by step solution

Let's solve

$$\left[y'' = y'x + y, y(0) = 1, y'|_{\{x=0\}} = 0 \right]$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' - y'x - y = 0$$

- Assume series solution for y

$$y = \sum_{k=0}^{\infty} a_k x^k$$

- Rewrite DE with series expansions

- Convert $x \cdot y'$ to series expansion

$$x \cdot y' = \sum_{k=0}^{\infty} a_k k x^k$$

- Convert y'' to series expansion

$$y'' = \sum_{k=2}^{\infty} a_k k(k-1) x^{k-2}$$

- Shift index using $k- > k+2$

$$y'' = \sum_{k=0}^{\infty} a_{k+2} (k+2)(k+1) x^k$$

Rewrite DE with series expansions

$$\sum_{k=0}^{\infty} (a_{k+2}(k+2)(k+1) - a_k(k+1)) x^k = 0$$

- Each term in the series must be 0, giving the recursion relation

$$(k+1)(a_{k+2}(k+2) - a_k) = 0$$

- Recursion relation that defines the series solution to the ODE

$$\left[y = \sum_{k=0}^{\infty} a_k x^k, a_{k+2} = \frac{a_k}{k+2} \right]$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
trying a symmetry of the form [xi=0, eta=F(x)]
<- linear_1 successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 14

```

Order:=6;
dsolve([diff(y(x),x$2)-x*diff(y(x),x)-y(x)=0,y(0) = 1, D(y)(0) = 0],y(x),type='series',x=0);

```

$$y(x) = 1 + \frac{1}{2}x^2 + \frac{1}{8}x^4 + O(x^6)$$

✓ Solution by Mathematica

Time used: 0.001 (sec). Leaf size: 19

```

AsymptoticDSolveValue[{y'[x]-x*y'[x]-y[x]==0,{y[0]==1,y'[0]==0}},y[x],{x,0,5}]

```

$$y(x) \rightarrow \frac{x^4}{8} + \frac{x^2}{2} + 1$$

14.12 problem 12

14.12.1 Existence and uniqueness analysis	3950
14.12.2 Maple step by step solution	3958

Internal problem ID [11895]

Internal file name [OUTPUT/11904_Saturday_April_13_2024_01_14_26_AM_92243548/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.1. Exercises page 232

Problem number: 12.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"second order series method. Ordinary point", "second order series method. Taylor series method"**

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$y'' + y'x - 2y = 0$$

With initial conditions

$$[y(0) = 0, y'(0) = 1]$$

With the expansion point for the power series method at $x = 0$.

14.12.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$p(x) = x$$

$$q(x) = -2$$

$$F = 0$$

Hence the ode is

$$y'' + y'x - 2y = 0$$

The domain of $p(x) = x$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = -2$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

Solving ode using Taylor series method. This gives review on how the Taylor series method works for solving second order ode.

Let

$$y'' = f(x, y, y')$$

Assuming expansion is at $x_0 = 0$ (we can always shift the actual expansion point to 0 by change of variables) and assuming $f(x, y, y')$ is analytic at x_0 which must be the case for an ordinary point. Let initial conditions be $y(x_0) = y_0$ and $y'(x_0) = y'_0$. Using Taylor series gives

$$\begin{aligned} y(x) &= y(x_0) + (x - x_0)y'(x_0) + \frac{(x - x_0)^2}{2}y''(x_0) + \frac{(x - x_0)^3}{3!}y'''(x_0) + \dots \\ &= y_0 + xy'_0 + \frac{x^2}{2}f|_{x_0, y_0, y'_0} + \frac{x^3}{3!}f'|_{x_0, y_0, y'_0} + \dots \\ &= y_0 + xy'_0 + \sum_{n=0}^{\infty} \frac{x^{n+2}}{(n+2)!} \left. \frac{d^n f}{dx^n} \right|_{x_0, y_0, y'_0} \end{aligned}$$

But

$$\frac{df}{dx} = \frac{\partial f}{\partial x} \frac{dx}{dx} + \frac{\partial f}{\partial y} \frac{dy}{dx} + \frac{\partial f}{\partial y'} \frac{dy'}{dx} \quad (1)$$

$$= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} y'' \quad (816)$$

$$= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} f \quad (817)$$

$$\begin{aligned} \frac{d^2 f}{dx^2} &= \frac{d}{dx} \left(\frac{df}{dx} \right) \\ &= \frac{\partial}{\partial x} \left(\frac{df}{dx} \right) + \frac{\partial}{\partial y} \left(\frac{df}{dx} \right) y' + \frac{\partial}{\partial y'} \left(\frac{df}{dx} \right) f \end{aligned} \quad (2)$$

$$\begin{aligned} \frac{d^3 f}{dx^3} &= \frac{d}{dx} \left(\frac{d^2 f}{dx^2} \right) \\ &= \frac{\partial}{\partial x} \left(\frac{d^2 f}{dx^2} \right) + \left(\frac{\partial}{\partial y} \frac{d^2 f}{dx^2} \right) y' + \frac{\partial}{\partial y'} \left(\frac{d^2 f}{dx^2} \right) f \end{aligned} \quad (3)$$

⋮

And so on. Hence if we name $F_0 = f(x, y, y')$ then the above can be written as

$$F_0 = f(x, y, y') \tag{4}$$

$$\begin{aligned} F_1 &= \frac{df}{dx} \\ &= \frac{dF_0}{dx} \\ &= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y}y' + \frac{\partial f}{\partial y'}y'' \\ &= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y}y' + \frac{\partial f}{\partial y'}f \\ &= \frac{\partial F_0}{\partial x} + \frac{\partial F_0}{\partial y}y' + \frac{\partial F_0}{\partial y'}F_0 \end{aligned} \tag{5}$$

$$\begin{aligned} F_2 &= \frac{d}{dx} \left(\frac{d}{dx} f \right) \\ &= \frac{d}{dx} (F_1) \\ &= \frac{\partial}{\partial x} F_1 + \left(\frac{\partial F_1}{\partial y} \right) y' + \left(\frac{\partial F_1}{\partial y'} \right) y'' \\ &= \frac{\partial}{\partial x} F_1 + \left(\frac{\partial F_1}{\partial y} \right) y' + \left(\frac{\partial F_1}{\partial y'} \right) F_0 \end{aligned}$$

⋮

$$\begin{aligned} F_n &= \frac{d}{dx} (F_{n-1}) \\ &= \frac{\partial}{\partial x} F_{n-1} + \left(\frac{\partial F_{n-1}}{\partial y} \right) y' + \left(\frac{\partial F_{n-1}}{\partial y'} \right) y'' \\ &= \frac{\partial}{\partial x} F_{n-1} + \left(\frac{\partial F_{n-1}}{\partial y} \right) y' + \left(\frac{\partial F_{n-1}}{\partial y'} \right) F_0 \end{aligned} \tag{6}$$

Therefore (6) can be used from now on along with

$$y(x) = y_0 + xy'_0 + \sum_{n=0}^{\infty} \frac{x^{n+2}}{(n+2)!} F_n|_{x_0, y_0, y'_0} \tag{7}$$

To find $y(x)$ series solution around $x = 0$. Hence

$$\begin{aligned}
 F_0 &= -y'x + 2y \\
 F_1 &= \frac{dF_0}{dx} \\
 &= \frac{\partial F_0}{\partial x} + \frac{\partial F_0}{\partial y}y' + \frac{\partial F_0}{\partial y'}F_0 \\
 &= x^2y' - 2yx + y' \\
 F_2 &= \frac{dF_1}{dx} \\
 &= \frac{\partial F_1}{\partial x} + \frac{\partial F_1}{\partial y}y' + \frac{\partial F_1}{\partial y'}F_1 \\
 &= -x(x^2 + 1)y' + 2x^2y \\
 F_3 &= \frac{dF_2}{dx} \\
 &= \frac{\partial F_2}{\partial x} + \frac{\partial F_2}{\partial y}y' + \frac{\partial F_2}{\partial y'}F_2 \\
 &= (x^4 - 1)y' + (-2x^3 + 2x)y \\
 F_4 &= \frac{dF_3}{dx} \\
 &= \frac{\partial F_3}{\partial x} + \frac{\partial F_3}{\partial y}y' + \frac{\partial F_3}{\partial y'}F_3 \\
 &= -(x^2 - 3)x((x^2 + 1)y' - 2yx)
 \end{aligned}$$

And so on. Evaluating all the above at initial conditions $x = 0$ and $y(0) = 0$ and $y'(0) = 1$ gives

$$\begin{aligned}
 F_0 &= 0 \\
 F_1 &= 1 \\
 F_2 &= 0 \\
 F_3 &= -1 \\
 F_4 &= 0
 \end{aligned}$$

Substituting all the above in (7) and simplifying gives the solution as

$$y = x + \frac{x^3}{6} - \frac{x^5}{120} + O(x^6)$$

$$y = x + \frac{x^3}{6} - \frac{x^5}{120} + O(x^6)$$

Since the expansion point $x = 0$ is an ordinary, we can also solve this using standard power series. Let the solution be represented as power series of the form

$$y = \sum_{n=0}^{\infty} a_n x^n$$

Then

$$y' = \sum_{n=1}^{\infty} n a_n x^{n-1}$$

$$y'' = \sum_{n=2}^{\infty} n(n-1) a_n x^{n-2}$$

Substituting the above back into the ode gives

$$\sum_{n=2}^{\infty} n(n-1) a_n x^{n-2} = - \left(\sum_{n=1}^{\infty} n a_n x^{n-1} \right) x + 2 \left(\sum_{n=0}^{\infty} a_n x^n \right) \quad (1)$$

Which simplifies to

$$\left(\sum_{n=2}^{\infty} n(n-1) a_n x^{n-2} \right) + \left(\sum_{n=1}^{\infty} n x^n a_n \right) + \sum_{n=0}^{\infty} (-2a_n x^n) = 0 \quad (2)$$

The next step is to make all powers of x be n in each summation term. Going over each summation term above with power of x in it which is not already x^n and adjusting the power and the corresponding index gives

$$\sum_{n=2}^{\infty} n(n-1) a_n x^{n-2} = \sum_{n=0}^{\infty} (n+2) a_{n+2} (n+1) x^n$$

Substituting all the above in Eq (2) gives the following equation where now all powers of x are the same and equal to n .

$$\left(\sum_{n=0}^{\infty} (n+2) a_{n+2} (n+1) x^n \right) + \left(\sum_{n=1}^{\infty} n x^n a_n \right) + \sum_{n=0}^{\infty} (-2a_n x^n) = 0 \quad (3)$$

$n = 0$ gives

$$2a_2 - 2a_0 = 0$$

$$a_2 = a_0$$

For $1 \leq n$, the recurrence equation is

$$(n + 2) a_{n+2}(n + 1) + n a_n - 2a_n = 0 \quad (4)$$

Solving for a_{n+2} , gives

$$a_{n+2} = -\frac{a_n(n - 2)}{(n + 2)(n + 1)} \quad (5)$$

For $n = 1$ the recurrence equation gives

$$6a_3 - a_1 = 0$$

Which after substituting the earlier terms found becomes

$$a_3 = \frac{a_1}{6}$$

For $n = 2$ the recurrence equation gives

$$12a_4 = 0$$

Which after substituting the earlier terms found becomes

$$a_4 = 0$$

For $n = 3$ the recurrence equation gives

$$20a_5 + a_3 = 0$$

Which after substituting the earlier terms found becomes

$$a_5 = -\frac{a_1}{120}$$

For $n = 4$ the recurrence equation gives

$$30a_6 + 2a_4 = 0$$

Which after substituting the earlier terms found becomes

$$a_6 = 0$$

For $n = 5$ the recurrence equation gives

$$42a_7 + 3a_5 = 0$$

Which after substituting the earlier terms found becomes

$$a_7 = \frac{a_1}{1680}$$

And so on. Therefore the solution is

$$\begin{aligned} y &= \sum_{n=0}^{\infty} a_n x^n \\ &= a_3 x^3 + a_2 x^2 + a_1 x + a_0 + \dots \end{aligned}$$

Substituting the values for a_n found above, the solution becomes

$$y = a_0 + a_1 x + a_0 x^2 + \frac{1}{6} a_1 x^3 - \frac{1}{120} a_1 x^5 + \dots$$

Collecting terms, the solution becomes

$$y = (x^2 + 1) a_0 + \left(x + \frac{1}{6} x^3 - \frac{1}{120} x^5 \right) a_1 + O(x^6) \quad (3)$$

At $x = 0$ the solution above becomes

$$y = (x^2 + 1) c_1 + \left(x + \frac{1}{6} x^3 - \frac{1}{120} x^5 \right) c_2 + O(x^6)$$

$$y = x + \frac{x^3}{6} - \frac{x^5}{120} + O(x^6)$$

Summary

The solution(s) found are the following

$$y = x + \frac{x^3}{6} - \frac{x^5}{120} + O(x^6) \quad (1)$$

$$y = x + \frac{x^3}{6} - \frac{x^5}{120} + O(x^6) \quad (2)$$

Verification of solutions

$$y = x + \frac{x^3}{6} - \frac{x^5}{120} + O(x^6)$$

Verified OK.

$$y = x + \frac{x^3}{6} - \frac{x^5}{120} + O(x^6)$$

Verified OK.

14.12.2 Maple step by step solution

Let's solve

$$\left[y'' = -y'x + 2y, y(0) = 0, y'|_{\{x=0\}} = 1 \right]$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + y'x - 2y = 0$$

- Assume series solution for y

$$y = \sum_{k=0}^{\infty} a_k x^k$$

- Rewrite DE with series expansions

- Convert $x \cdot y'$ to series expansion

$$x \cdot y' = \sum_{k=0}^{\infty} a_k k x^k$$

- Convert y'' to series expansion

$$y'' = \sum_{k=2}^{\infty} a_k k(k-1) x^{k-2}$$

- Shift index using $k- > k+2$

$$y'' = \sum_{k=0}^{\infty} a_{k+2} (k+2)(k+1) x^k$$

Rewrite DE with series expansions

$$\sum_{k=0}^{\infty} (a_{k+2}(k+2)(k+1) + a_k(k-2)) x^k = 0$$

- Each term in the series must be 0, giving the recursion relation

$$(k^2 + 3k + 2) a_{k+2} + a_k(k - 2) = 0$$
- Recursion relation; series terminates at $k = 2$

$$a_{k+2} = -\frac{a_k(k-2)}{k^2+3k+2}$$
- Apply recursion relation for $k = 0$

$$a_2 = a_0$$
- Terminating series solution of the ODE. Use reduction of order to find the second linearly independent solution

$$y = A_2x^2 + A_1x + a_0$$

Maple trace Kovacic algorithm successful

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
trying a symmetry of the form [xi=0, eta=F(x)]
checking if the LODE is missing y
-> Trying a Liouvillian solution using Kovacics algorithm
  A Liouvillian solution exists
  Reducible group (found an exponential solution)
  Group is reducible, not completely reducible
  Solution has integrals. Trying a special function solution free of integrals...
-> Trying a solution in terms of special functions:
  -> Bessel
  -> elliptic
  -> Legendre
  <- Kummer successful
<- special function solution successful
  -> Trying to convert hypergeometric functions to elementary form...
  <- elementary form is not straightforward to achieve - returning special function solution
<- Kovacics algorithm successful`

```


✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 14

Order:=6;

```
dsolve([diff(y(x),x$2)+x*diff(y(x),x)-2*y(x)=0,y(0) = 0, D(y)(0) = 1],y(x),type='series',x=0
```

$$y(x) = x + \frac{1}{6}x^3 - \frac{1}{120}x^5 + O(x^6)$$

✓ Solution by Mathematica

Time used: 0.001 (sec). Leaf size: 19

```
AsymptoticDSolveValue[{y'[x]+x*y'[x]-2*y[x]==0,{y[0]==0,y'[0]==1}},y[x],{x,0,5}]
```

$$y(x) \rightarrow -\frac{x^5}{120} + \frac{x^3}{6} + x$$

14.13 problem 13

14.13.1 Existence and uniqueness analysis 3961

Internal problem ID [11896]

Internal file name [OUTPUT/11905_Saturday_April_13_2024_01_14_28_AM_24219364/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.1. Exercises page 232

Problem number: 13.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"second order series method. Ordinary point", "second order series method. Taylor series method"**

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$(x^2 + 1)y'' + y'x + 2yx = 0$$

With initial conditions

$$[y(0) = 2, y'(0) = 3]$$

With the expansion point for the power series method at $x = 0$.

14.13.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$p(x) = \frac{x}{x^2 + 1}$$
$$q(x) = \frac{2x}{x^2 + 1}$$
$$F = 0$$

Hence the ode is

$$y'' + \frac{xy'}{x^2 + 1} + \frac{2xy}{x^2 + 1} = 0$$

The domain of $p(x) = \frac{x}{x^2+1}$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is inside this domain. The domain of $q(x) = \frac{2x}{x^2+1}$ is

$$\{-\infty < x < \infty\}$$

And the point $x_0 = 0$ is also inside this domain. Hence solution exists and is unique.

Solving ode using Taylor series method. This gives review on how the Taylor series method works for solving second order ode.

Let

$$y'' = f(x, y, y')$$

Assuming expansion is at $x_0 = 0$ (we can always shift the actual expansion point to 0 by change of variables) and assuming $f(x, y, y')$ is analytic at x_0 which must be the case for an ordinary point. Let initial conditions be $y(x_0) = y_0$ and $y'(x_0) = y'_0$. Using Taylor series gives

$$\begin{aligned} y(x) &= y(x_0) + (x - x_0)y'(x_0) + \frac{(x - x_0)^2}{2}y''(x_0) + \frac{(x - x_0)^3}{3!}y'''(x_0) + \cdots \\ &= y_0 + xy'_0 + \frac{x^2}{2}f|_{x_0, y_0, y'_0} + \frac{x^3}{3!}f'|_{x_0, y_0, y'_0} + \cdots \\ &= y_0 + xy'_0 + \sum_{n=0}^{\infty} \frac{x^{n+2}}{(n+2)!} \left. \frac{d^n f}{dx^n} \right|_{x_0, y_0, y'_0} \end{aligned}$$

But

$$\frac{df}{dx} = \frac{\partial f}{\partial x} \frac{dx}{dx} + \frac{\partial f}{\partial y} \frac{dy}{dx} + \frac{\partial f}{\partial y'} \frac{dy'}{dx} \quad (1)$$

$$= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} y'' \quad (819)$$

$$= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} f \quad (820)$$

$$\begin{aligned} \frac{d^2 f}{dx^2} &= \frac{d}{dx} \left(\frac{df}{dx} \right) \\ &= \frac{\partial}{\partial x} \left(\frac{df}{dx} \right) + \frac{\partial}{\partial y} \left(\frac{df}{dx} \right) y' + \frac{\partial}{\partial y'} \left(\frac{df}{dx} \right) f \end{aligned} \quad (2)$$

$$\begin{aligned} \frac{d^3 f}{dx^3} &= \frac{d}{dx} \left(\frac{d^2 f}{dx^2} \right) \\ &= \frac{\partial}{\partial x} \left(\frac{d^2 f}{dx^2} \right) + \left(\frac{\partial}{\partial y} \frac{d^2 f}{dx^2} \right) y' + \frac{\partial}{\partial y'} \left(\frac{d^2 f}{dx^2} \right) f \end{aligned} \quad (3)$$

⋮

And so on. Hence if we name $F_0 = f(x, y, y')$ then the above can be written as

$$F_0 = f(x, y, y') \tag{4}$$

$$\begin{aligned} F_1 &= \frac{df}{dx} \\ &= \frac{dF_0}{dx} \\ &= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y}y' + \frac{\partial f}{\partial y'}y'' \\ &= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y}y' + \frac{\partial f}{\partial y'}f \\ &= \frac{\partial F_0}{\partial x} + \frac{\partial F_0}{\partial y}y' + \frac{\partial F_0}{\partial y'}F_0 \end{aligned} \tag{5}$$

$$\begin{aligned} F_2 &= \frac{d}{dx} \left(\frac{d}{dx} f \right) \\ &= \frac{d}{dx} (F_1) \\ &= \frac{\partial}{\partial x} F_1 + \left(\frac{\partial F_1}{\partial y} \right) y' + \left(\frac{\partial F_1}{\partial y'} \right) y'' \\ &= \frac{\partial}{\partial x} F_1 + \left(\frac{\partial F_1}{\partial y} \right) y' + \left(\frac{\partial F_1}{\partial y'} \right) F_0 \end{aligned}$$

⋮

$$\begin{aligned} F_n &= \frac{d}{dx} (F_{n-1}) \\ &= \frac{\partial}{\partial x} F_{n-1} + \left(\frac{\partial F_{n-1}}{\partial y} \right) y' + \left(\frac{\partial F_{n-1}}{\partial y'} \right) y'' \\ &= \frac{\partial}{\partial x} F_{n-1} + \left(\frac{\partial F_{n-1}}{\partial y} \right) y' + \left(\frac{\partial F_{n-1}}{\partial y'} \right) F_0 \end{aligned} \tag{6}$$

Therefore (6) can be used from now on along with

$$y(x) = y_0 + xy'_0 + \sum_{n=0}^{\infty} \frac{x^{n+2}}{(n+2)!} F_n|_{x_0, y_0, y'_0} \tag{7}$$

To find $y(x)$ series solution around $x = 0$. Hence

$$F_0 = -\frac{x(2y + y')}{x^2 + 1}$$

$$\begin{aligned} F_1 &= \frac{dF_0}{dx} \\ &= \frac{\partial F_0}{\partial x} + \frac{\partial F_0}{\partial y} y' + \frac{\partial F_0}{\partial y'} F_0 \\ &= \frac{(-2x^3 + 2x^2 - 2x - 1)y' + (4x^2 - 2)y}{(x^2 + 1)^2} \end{aligned}$$

$$\begin{aligned} F_2 &= \frac{dF_1}{dx} \\ &= \frac{\partial F_1}{\partial x} + \frac{\partial F_1}{\partial y} y' + \frac{\partial F_1}{\partial y'} F_1 \\ &= \frac{(8x^4 - 6x^3 + 4x^2 + 9x - 4)y' + 4xy(x^3 - 3x^2 + x + \frac{9}{2})}{(x^2 + 1)^3} \end{aligned}$$

$$\begin{aligned} F_3 &= \frac{dF_2}{dx} \\ &= \frac{\partial F_2}{\partial x} + \frac{\partial F_2}{\partial y} y' + \frac{\partial F_2}{\partial y'} F_2 \\ &= \frac{(4x^6 - 36x^5 + 32x^4 + 18x^3 - 68x^2 + 54x + 9)y' - 24(x^5 - 2x^4 + \frac{1}{3}x^3 + 6x^2 - \frac{2}{3}x - \frac{3}{4})y}{(x^2 + 1)^4} \end{aligned}$$

$$\begin{aligned} F_4 &= \frac{dF_3}{dx} \\ &= \frac{\partial F_3}{\partial x} + \frac{\partial F_3}{\partial y} y' + \frac{\partial F_3}{\partial y'} F_3 \\ &= \frac{(-36x^7 + 192x^6 - 168x^5 - 384x^4 + 612x^3 - 504x^2 - 201x + 72)y' - 8(x^7 - 18x^6 + 32x^5 + \frac{29}{2}x^4 - \dots)}{(x^2 + 1)^5} \end{aligned}$$

And so on. Evaluating all the above at initial conditions $x = 0$ and $y(0) = 2$ and $y'(0) = 3$ gives

$$F_0 = 0$$

$$F_1 = -7$$

$$F_2 = -12$$

$$F_3 = 63$$

$$F_4 = 248$$

Substituting all the above in (7) and simplifying gives the solution as

$$y = 3x + 2 - \frac{7x^3}{6} - \frac{x^4}{2} + \frac{21x^5}{40} + \frac{31x^6}{90} + O(x^6)$$

$$y = 3x + 2 - \frac{7x^3}{6} - \frac{x^4}{2} + \frac{21x^5}{40} + \frac{31x^6}{90} + O(x^6)$$

Since the expansion point $x = 0$ is an ordinary, we can also solve this using standard power series. The ode is normalized to be

$$(x^2 + 1)y'' + y'x + 2yx = 0$$

Let the solution be represented as power series of the form

$$y = \sum_{n=0}^{\infty} a_n x^n$$

Then

$$y' = \sum_{n=1}^{\infty} n a_n x^{n-1}$$

$$y'' = \sum_{n=2}^{\infty} n(n-1) a_n x^{n-2}$$

Substituting the above back into the ode gives

$$(x^2 + 1) \left(\sum_{n=2}^{\infty} n(n-1) a_n x^{n-2} \right) + \left(\sum_{n=1}^{\infty} n a_n x^{n-1} \right) x + 2 \left(\sum_{n=0}^{\infty} a_n x^n \right) x = 0 \quad (1)$$

Which simplifies to

$$\left(\sum_{n=2}^{\infty} x^n a_n n(n-1) \right) + \left(\sum_{n=2}^{\infty} n(n-1) a_n x^{n-2} \right) + \left(\sum_{n=1}^{\infty} n a_n x^n \right) + \left(\sum_{n=0}^{\infty} 2x^{1+n} a_n \right) = 0 \quad (2)$$

The next step is to make all powers of x be n in each summation term. Going over each summation term above with power of x in it which is not already x^n and adjusting the power and the corresponding index gives

$$\sum_{n=2}^{\infty} n(n-1) a_n x^{n-2} = \sum_{n=0}^{\infty} (n+2) a_{n+2} (1+n) x^n$$

$$\sum_{n=0}^{\infty} 2x^{1+n} a_n = \sum_{n=1}^{\infty} 2a_{n-1} x^n$$

Substituting all the above in Eq (2) gives the following equation where now all powers of x are the same and equal to n .

$$\begin{aligned} & \left(\sum_{n=2}^{\infty} x^n a_n n(n-1) \right) + \left(\sum_{n=0}^{\infty} (n+2) a_{n+2} (1+n) x^n \right) \\ & + \left(\sum_{n=1}^{\infty} n a_n x^n \right) + \left(\sum_{n=1}^{\infty} 2a_{n-1} x^n \right) = 0 \end{aligned} \quad (3)$$

$n = 1$ gives

$$6a_3 + a_1 + 2a_0 = 0$$

Which after substituting earlier equations, simplifies to

$$a_3 = -\frac{a_0}{3} - \frac{a_1}{6}$$

For $2 \leq n$, the recurrence equation is

$$na_n(n-1) + (n+2)a_{n+2}(1+n) + na_n + 2a_{n-1} = 0 \quad (4)$$

Solving for a_{n+2} , gives

$$\begin{aligned} a_{n+2} &= -\frac{n^2 a_n + 2a_{n-1}}{(n+2)(1+n)} \\ (5) \quad &= -\frac{n^2 a_n}{(n+2)(1+n)} - \frac{2a_{n-1}}{(n+2)(1+n)} \end{aligned}$$

For $n = 2$ the recurrence equation gives

$$4a_2 + 12a_4 + 2a_1 = 0$$

Which after substituting the earlier terms found becomes

$$a_4 = -\frac{a_1}{6}$$

For $n = 3$ the recurrence equation gives

$$9a_3 + 20a_5 + 2a_2 = 0$$

Which after substituting the earlier terms found becomes

$$a_5 = \frac{3a_0}{20} + \frac{3a_1}{40}$$

For $n = 4$ the recurrence equation gives

$$16a_4 + 30a_6 + 2a_3 = 0$$

Which after substituting the earlier terms found becomes

$$a_6 = \frac{a_1}{10} + \frac{a_0}{45}$$

For $n = 5$ the recurrence equation gives

$$25a_5 + 42a_7 + 2a_4 = 0$$

Which after substituting the earlier terms found becomes

$$a_7 = -\frac{5a_0}{56} - \frac{37a_1}{1008}$$

And so on. Therefore the solution is

$$\begin{aligned} y &= \sum_{n=0}^{\infty} a_n x^n \\ &= a_3 x^3 + a_2 x^2 + a_1 x + a_0 + \dots \end{aligned}$$

Substituting the values for a_n found above, the solution becomes

$$y = a_0 + a_1 x + \left(-\frac{a_0}{3} - \frac{a_1}{6}\right) x^3 - \frac{a_1 x^4}{6} + \left(\frac{3a_0}{20} + \frac{3a_1}{40}\right) x^5 + \dots$$

Collecting terms, the solution becomes

$$y = \left(1 - \frac{1}{3}x^3 + \frac{3}{20}x^5\right) a_0 + \left(x - \frac{1}{6}x^3 - \frac{1}{6}x^4 + \frac{3}{40}x^5\right) a_1 + O(x^6) \quad (3)$$

At $x = 0$ the solution above becomes

$$y = \left(1 - \frac{1}{3}x^3 + \frac{3}{20}x^5\right) c_1 + \left(x - \frac{1}{6}x^3 - \frac{1}{6}x^4 + \frac{3}{40}x^5\right) c_2 + O(x^6)$$

$$y = 2 - \frac{7x^3}{6} + \frac{21x^5}{40} + 3x - \frac{x^4}{2} + O(x^6)$$

Summary

The solution(s) found are the following

$$y = 3x + 2 - \frac{7x^3}{6} - \frac{x^4}{2} + \frac{21x^5}{40} + \frac{31x^6}{90} + O(x^6) \quad (1)$$

$$y = 2 - \frac{7x^3}{6} + \frac{21x^5}{40} + 3x - \frac{x^4}{2} + O(x^6) \quad (2)$$

Verification of solutions

$$y = 3x + 2 - \frac{7x^3}{6} - \frac{x^4}{2} + \frac{21x^5}{40} + \frac{31x^6}{90} + O(x^6)$$

Verified OK.

$$y = 2 - \frac{7x^3}{6} + \frac{21x^5}{40} + 3x - \frac{x^4}{2} + O(x^6)$$

Verified OK.

Maple trace

```
`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
trying a symmetry of the form [xi=0, eta=F(x)]
checking if the LODE is missing y
-> Trying a Liouvillian solution using Kovacic's algorithm
<- No Liouvillian solutions exist
-> Trying a solution in terms of special functions:
  -> Bessel
  -> elliptic
  -> Legendre
  -> Kummer
    -> hyper3: Equivalence to 1F1 under a power @ Moebius
  -> hypergeometric
    -> heuristic approach
    -> hyper3: Equivalence to 2F1, 1F1 or 0F1 under a power @ Moebius
  -> Mathieu
    -> Equivalence to the rational form of Mathieu ODE under a power @ Moebius
trying a solution in terms of MeijerG functions
-> Heun: Equivalence to the GHE or one of its 4 confluent cases under a power @ Moebius
<- Heun successful: received ODE is equivalent to the HeunC ODE, case a <> 0, e <> 0, c =
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 18

```
Order:=6;
dsolve([(x^2+1)*diff(y(x),x$2)+x*diff(y(x),x)+2*x*y(x)=0,y(0) = 2, D(y)(0) = 3],y(x),type='s
```

$$y(x) = 2 + 3x - \frac{7}{6}x^3 - \frac{1}{2}x^4 + \frac{21}{40}x^5 + O(x^6)$$

✓ Solution by Mathematica

Time used: 0.002 (sec). Leaf size: 29

```
AsymptoticDSolveValue[{(x^2+1)*y'[x]+x*y'[x]+2*x*y[x]==0,{y[0]==2,y'[0]==3}},y[x],{x,0,5}]
```

$$y(x) \rightarrow \frac{21x^5}{40} - \frac{x^4}{2} - \frac{7x^3}{6} + 3x + 2$$

14.14 problem 14

Internal problem ID [11897]

Internal file name [OUTPUT/11906_Saturday_April_13_2024_01_14_29_AM_59679552/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.1. Exercises page 232

Problem number: 14.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"second order series method. Ordinary point", "second order series method. Taylor series method"**

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$(2x^2 - 3)y'' - 2y'x + y = 0$$

With initial conditions

$$[y(0) = -1, y'(0) = 5]$$

With the expansion point for the power series method at $x = 0$.

Solving ode using Taylor series method. This gives review on how the Taylor series method works for solving second order ode.

Let

$$y'' = f(x, y, y')$$

Assuming expansion is at $x_0 = 0$ (we can always shift the actual expansion point to 0 by change of variables) and assuming $f(x, y, y')$ is analytic at x_0 which must be the case for an ordinary point. Let initial conditions be $y(x_0) = y_0$ and $y'(x_0) = y'_0$. Using

Taylor series gives

$$\begin{aligned}
 y(x) &= y(x_0) + (x - x_0)y'(x_0) + \frac{(x - x_0)^2}{2}y''(x_0) + \frac{(x - x_0)^3}{3!}y'''(x_0) + \dots \\
 &= y_0 + xy'_0 + \frac{x^2}{2}f|_{x_0, y_0, y'_0} + \frac{x^3}{3!}f'|_{x_0, y_0, y'_0} + \dots \\
 &= y_0 + xy'_0 + \sum_{n=0}^{\infty} \frac{x^{n+2}}{(n+2)!} \frac{d^n f}{dx^n} \Big|_{x_0, y_0, y'_0}
 \end{aligned}$$

But

$$\frac{df}{dx} = \frac{\partial f}{\partial x} \frac{dx}{dx} + \frac{\partial f}{\partial y} \frac{dy}{dx} + \frac{\partial f}{\partial y'} \frac{dy'}{dx} \tag{1}$$

$$= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} y'' \tag{822}$$

$$= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} f \tag{823}$$

$$\begin{aligned}
 \frac{d^2 f}{dx^2} &= \frac{d}{dx} \left(\frac{df}{dx} \right) \\
 &= \frac{\partial}{\partial x} \left(\frac{df}{dx} \right) + \frac{\partial}{\partial y} \left(\frac{df}{dx} \right) y' + \frac{\partial}{\partial y'} \left(\frac{df}{dx} \right) f \tag{2}
 \end{aligned}$$

$$\begin{aligned}
 \frac{d^3 f}{dx^3} &= \frac{d}{dx} \left(\frac{d^2 f}{dx^2} \right) \\
 &= \frac{\partial}{\partial x} \left(\frac{d^2 f}{dx^2} \right) + \left(\frac{\partial}{\partial y} \frac{d^2 f}{dx^2} \right) y' + \frac{\partial}{\partial y'} \left(\frac{d^2 f}{dx^2} \right) f \tag{3}
 \end{aligned}$$

⋮

And so on. Hence if we name $F_0 = f(x, y, y')$ then the above can be written as

$$F_0 = f(x, y, y') \tag{4}$$

$$\begin{aligned} F_1 &= \frac{df}{dx} \\ &= \frac{dF_0}{dx} \\ &= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y}y' + \frac{\partial f}{\partial y'}y'' \\ &= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y}y' + \frac{\partial f}{\partial y'}f \\ &= \frac{\partial F_0}{\partial x} + \frac{\partial F_0}{\partial y}y' + \frac{\partial F_0}{\partial y'}F_0 \end{aligned} \tag{5}$$

$$\begin{aligned} F_2 &= \frac{d}{dx} \left(\frac{d}{dx} f \right) \\ &= \frac{d}{dx} (F_1) \\ &= \frac{\partial}{\partial x} F_1 + \left(\frac{\partial F_1}{\partial y} \right) y' + \left(\frac{\partial F_1}{\partial y'} \right) y'' \\ &= \frac{\partial}{\partial x} F_1 + \left(\frac{\partial F_1}{\partial y} \right) y' + \left(\frac{\partial F_1}{\partial y'} \right) F_0 \end{aligned}$$

⋮

$$\begin{aligned} F_n &= \frac{d}{dx} (F_{n-1}) \\ &= \frac{\partial}{\partial x} F_{n-1} + \left(\frac{\partial F_{n-1}}{\partial y} \right) y' + \left(\frac{\partial F_{n-1}}{\partial y'} \right) y'' \\ &= \frac{\partial}{\partial x} F_{n-1} + \left(\frac{\partial F_{n-1}}{\partial y} \right) y' + \left(\frac{\partial F_{n-1}}{\partial y'} \right) F_0 \end{aligned} \tag{6}$$

Therefore (6) can be used from now on along with

$$y(x) = y_0 + xy'_0 + \sum_{n=0}^{\infty} \frac{x^{n+2}}{(n+2)!} F_n|_{x_0, y_0, y'_0} \tag{7}$$

To find $y(x)$ series solution around $x = 0$. Hence

$$\begin{aligned}
 F_0 &= \frac{2y'x - y}{2x^2 - 3} \\
 F_1 &= \frac{dF_0}{dx} \\
 &= \frac{\partial F_0}{\partial x} + \frac{\partial F_0}{\partial y}y' + \frac{\partial F_0}{\partial y'}F_0 \\
 &= \frac{-2x^2y' + 2yx - 3y'}{(2x^2 - 3)^2} \\
 F_2 &= \frac{dF_1}{dx} \\
 &= \frac{\partial F_1}{\partial x} + \frac{\partial F_1}{\partial y}y' + \frac{\partial F_1}{\partial y'}F_1 \\
 &= \frac{8(x^3 + 3x)y' + (-10x^2 - 3)y}{(2x^2 - 3)^3} \\
 F_3 &= \frac{dF_2}{dx} \\
 &= \frac{\partial F_2}{\partial x} + \frac{\partial F_2}{\partial y}y' + \frac{\partial F_2}{\partial y'}F_2 \\
 &= \frac{(-52x^4 - 240x^2 - 63)y' + 72xy(x^2 + 1)}{(2x^2 - 3)^4} \\
 F_4 &= \frac{dF_3}{dx} \\
 &= \frac{\partial F_3}{\partial x} + \frac{\partial F_3}{\partial y}y' + \frac{\partial F_3}{\partial y'}F_3 \\
 &= \frac{(456x^5 + 2952x^3 + 2106x)y' + (-668x^4 - 1416x^2 - 153)y}{(2x^2 - 3)^5}
 \end{aligned}$$

And so on. Evaluating all the above at initial conditions $x = 0$ and $y(0) = -1$ and $y'(0) = 5$ gives

$$\begin{aligned}
 F_0 &= -\frac{1}{3} \\
 F_1 &= -\frac{5}{3} \\
 F_2 &= -\frac{1}{9} \\
 F_3 &= -\frac{35}{9} \\
 F_4 &= -\frac{17}{27}
 \end{aligned}$$

Substituting all the above in (7) and simplifying gives the solution as

$$y = 5x - 1 - \frac{x^2}{6} - \frac{5x^3}{18} - \frac{x^4}{216} - \frac{7x^5}{216} - \frac{17x^6}{19440} + O(x^6)$$

$$y = 5x - 1 - \frac{x^2}{6} - \frac{5x^3}{18} - \frac{x^4}{216} - \frac{7x^5}{216} - \frac{17x^6}{19440} + O(x^6)$$

Since the expansion point $x = 0$ is an ordinary, we can also solve this using standard power series The ode is normalized to be

$$(2x^2 - 3)y'' - 2y'x + y = 0$$

Let the solution be represented as power series of the form

$$y = \sum_{n=0}^{\infty} a_n x^n$$

Then

$$y' = \sum_{n=1}^{\infty} n a_n x^{n-1}$$

$$y'' = \sum_{n=2}^{\infty} n(n-1) a_n x^{n-2}$$

Substituting the above back into the ode gives

$$(2x^2 - 3) \left(\sum_{n=2}^{\infty} n(n-1) a_n x^{n-2} \right) - 2 \left(\sum_{n=1}^{\infty} n a_n x^{n-1} \right) x + \left(\sum_{n=0}^{\infty} a_n x^n \right) = 0 \quad (1)$$

Which simplifies to

$$\left(\sum_{n=2}^{\infty} 2x^n a_n n(n-1) \right) + \sum_{n=2}^{\infty} (-3n(n-1) a_n x^{n-2}) + \sum_{n=1}^{\infty} (-2n a_n x^n) + \left(\sum_{n=0}^{\infty} a_n x^n \right) = 0 \quad (2)$$

The next step is to make all powers of x be n in each summation term. Going over each summation term above with power of x in it which is not already x^n and adjusting the power and the corresponding index gives

$$\sum_{n=2}^{\infty} (-3n(n-1) a_n x^{n-2}) = \sum_{n=0}^{\infty} (-3(n+2) a_{n+2} (n+1) x^n)$$

Substituting all the above in Eq (2) gives the following equation where now all powers of x are the same and equal to n .

$$\begin{aligned} & \left(\sum_{n=2}^{\infty} 2x^n a_n n(n-1) \right) + \sum_{n=0}^{\infty} (-3(n+2) a_{n+2}(n+1) x^n) \\ & + \sum_{n=1}^{\infty} (-2na_n x^n) + \left(\sum_{n=0}^{\infty} a_n x^n \right) = 0 \end{aligned} \quad (3)$$

$n = 0$ gives

$$-6a_2 + a_0 = 0$$

$$a_2 = \frac{a_0}{6}$$

$n = 1$ gives

$$-18a_3 - a_1 = 0$$

Which after substituting earlier equations, simplifies to

$$a_3 = -\frac{a_1}{18}$$

For $2 \leq n$, the recurrence equation is

$$2na_n(n-1) - 3(n+2)a_{n+2}(n+1) - 2na_n + a_n = 0 \quad (4)$$

Solving for a_{n+2} , gives

$$a_{n+2} = \frac{a_n(2n^2 - 4n + 1)}{3(n+2)(n+1)} \quad (5)$$

For $n = 2$ the recurrence equation gives

$$a_2 - 36a_4 = 0$$

Which after substituting the earlier terms found becomes

$$a_4 = \frac{a_0}{216}$$

For $n = 3$ the recurrence equation gives

$$7a_3 - 60a_5 = 0$$

Which after substituting the earlier terms found becomes

$$a_5 = -\frac{7a_1}{1080}$$

For $n = 4$ the recurrence equation gives

$$17a_4 - 90a_6 = 0$$

Which after substituting the earlier terms found becomes

$$a_6 = \frac{17a_0}{19440}$$

For $n = 5$ the recurrence equation gives

$$31a_5 - 126a_7 = 0$$

Which after substituting the earlier terms found becomes

$$a_7 = -\frac{31a_1}{19440}$$

And so on. Therefore the solution is

$$\begin{aligned} y &= \sum_{n=0}^{\infty} a_n x^n \\ &= a_3 x^3 + a_2 x^2 + a_1 x + a_0 + \dots \end{aligned}$$

Substituting the values for a_n found above, the solution becomes

$$y = a_0 + a_1 x + \frac{1}{6} a_0 x^2 - \frac{1}{18} a_1 x^3 + \frac{1}{216} a_0 x^4 - \frac{7}{1080} a_1 x^5 + \dots$$

Collecting terms, the solution becomes

$$y = \left(1 + \frac{1}{6}x^2 + \frac{1}{216}x^4\right) a_0 + \left(x - \frac{1}{18}x^3 - \frac{7}{1080}x^5\right) a_1 + O(x^6) \quad (3)$$

At $x = 0$ the solution above becomes

$$y = \left(1 + \frac{1}{6}x^2 + \frac{1}{216}x^4\right) c_1 + \left(x - \frac{1}{18}x^3 - \frac{7}{1080}x^5\right) c_2 + O(x^6)$$

$$y = -1 - \frac{x^2}{6} - \frac{x^4}{216} + 5x - \frac{5x^3}{18} - \frac{7x^5}{216} + O(x^6)$$

Summary

The solution(s) found are the following

$$y = 5x - 1 - \frac{x^2}{6} - \frac{5x^3}{18} - \frac{x^4}{216} - \frac{7x^5}{216} - \frac{17x^6}{19440} + O(x^6) \quad (1)$$

$$y = -1 - \frac{x^2}{6} - \frac{x^4}{216} + 5x - \frac{5x^3}{18} - \frac{7x^5}{216} + O(x^6) \quad (2)$$

Verification of solutions

$$y = 5x - 1 - \frac{x^2}{6} - \frac{5x^3}{18} - \frac{x^4}{216} - \frac{7x^5}{216} - \frac{17x^6}{19440} + O(x^6)$$

Verified OK.

$$y = -1 - \frac{x^2}{6} - \frac{x^4}{216} + 5x - \frac{5x^3}{18} - \frac{7x^5}{216} + O(x^6)$$

Verified OK.

Maple trace **Kovacic algorithm successful**

```
`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
trying a symmetry of the form [xi=0, eta=F(x)]
checking if the LODE is missing y
-> Trying a Liouvillian solution using Kovacics algorithm
    A Liouvillian solution exists
    Group is reducible or imprimitive
<- Kovacics algorithm successful`
```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 20

Order:=6;

```
dsolve([(2*x^2-3)*diff(y(x),x$2)-2*x*diff(y(x),x)+y(x)=0,y(0) = -1, D(y)(0) = 5],y(x),type='
```

$$y(x) = -1 + 5x - \frac{1}{6}x^2 - \frac{5}{18}x^3 - \frac{1}{216}x^4 - \frac{7}{216}x^5 + O(x^6)$$

✓ Solution by Mathematica

Time used: 0.001 (sec). Leaf size: 36

```
AsymptoticDSolveValue[{(2*x^2-3)*y'[x]-2*x*y'[x]+y[x]==0,{y[0]==-1,y'[0]==5}},y[x],{x,0,5}]
```

$$y(x) \rightarrow -\frac{7x^5}{216} - \frac{x^4}{216} - \frac{5x^3}{18} - \frac{x^2}{6} + 5x - 1$$

14.15 problem 15

14.15.1 Maple step by step solution 3989

Internal problem ID [11898]

Internal file name [OUTPUT/11907_Saturday_April_13_2024_01_14_31_AM_97603693/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.1. Exercises page 232

Problem number: 15.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "second order series method. Ordinary point", "second_order_change_of_variable_on_x_method_1", "second_order_change_of_variable_on_x_method_2", "second order series method. Taylor series method"

Maple gives the following as the ode type

```
[[_Emden, _Fowler], [_2nd_order, _linear, `_with_symmetry_[0,F(x)]`]]
```

$$x^2y'' + y'x + y = 0$$

With the expansion point for the power series method at $x = 1$.

The ode does not have its expansion point at $x = 0$, therefore to simplify the computation of power series expansion, change of variable is made on the independent variable to shift the initial conditions and the expansion point back to zero. The new ode is then solved more easily since the expansion point is now at zero. The solution converted back to the original independent variable. Let

$$t = x - 1$$

The ode is converted to be in terms of the new independent variable t . This results in

$$\left(\frac{d^2}{dt^2}y(t)\right)(1+t)^2 + \left(\frac{d}{dt}y(t)\right)(1+t) + y(t) = 0$$

With its expansion point and initial conditions now at $t = 0$. The transformed ODE is now solved. Solving ode using Taylor series method. This gives review on how the Taylor series method works for solving second order ode.

Let

$$y'' = f(x, y, y')$$

Assuming expansion is at $x_0 = 0$ (we can always shift the actual expansion point to 0 by change of variables) and assuming $f(x, y, y')$ is analytic at x_0 which must be the case for an ordinary point. Let initial conditions be $y(x_0) = y_0$ and $y'(x_0) = y'_0$. Using Taylor series gives

$$\begin{aligned} y(x) &= y(x_0) + (x - x_0)y'(x_0) + \frac{(x - x_0)^2}{2}y''(x_0) + \frac{(x - x_0)^3}{3!}y'''(x_0) + \dots \\ &= y_0 + xy'_0 + \frac{x^2}{2}f|_{x_0, y_0, y'_0} + \frac{x^3}{3!}f'|_{x_0, y_0, y'_0} + \dots \\ &= y_0 + xy'_0 + \sum_{n=0}^{\infty} \frac{x^{n+2}}{(n+2)!} \left. \frac{d^n f}{dx^n} \right|_{x_0, y_0, y'_0} \end{aligned}$$

But

$$\frac{df}{dx} = \frac{\partial f}{\partial x} \frac{dx}{dx} + \frac{\partial f}{\partial y} \frac{dy}{dx} + \frac{\partial f}{\partial y'} \frac{dy'}{dx} \quad (1)$$

$$= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} y'' \quad (825)$$

$$= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} f \quad (826)$$

$$\begin{aligned} \frac{d^2 f}{dx^2} &= \frac{d}{dx} \left(\frac{df}{dx} \right) \\ &= \frac{\partial}{\partial x} \left(\frac{df}{dx} \right) + \frac{\partial}{\partial y} \left(\frac{df}{dx} \right) y' + \frac{\partial}{\partial y'} \left(\frac{df}{dx} \right) f \end{aligned} \quad (2)$$

$$\begin{aligned} \frac{d^3 f}{dx^3} &= \frac{d}{dx} \left(\frac{d^2 f}{dx^2} \right) \\ &= \frac{\partial}{\partial x} \left(\frac{d^2 f}{dx^2} \right) + \left(\frac{\partial}{\partial y} \frac{d^2 f}{dx^2} \right) y' + \frac{\partial}{\partial y'} \left(\frac{d^2 f}{dx^2} \right) f \end{aligned} \quad (3)$$

⋮

And so on. Hence if we name $F_0 = f(x, y, y')$ then the above can be written as

$$F_0 = f(x, y, y') \tag{4}$$

$$\begin{aligned} F_1 &= \frac{df}{dx} \\ &= \frac{dF_0}{dx} \\ &= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y}y' + \frac{\partial f}{\partial y'}y'' \\ &= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y}y' + \frac{\partial f}{\partial y'}f \\ &= \frac{\partial F_0}{\partial x} + \frac{\partial F_0}{\partial y}y' + \frac{\partial F_0}{\partial y'}F_0 \end{aligned} \tag{5}$$

$$\begin{aligned} F_2 &= \frac{d}{dx} \left(\frac{d}{dx} f \right) \\ &= \frac{d}{dx} (F_1) \\ &= \frac{\partial}{\partial x} F_1 + \left(\frac{\partial F_1}{\partial y} \right) y' + \left(\frac{\partial F_1}{\partial y'} \right) y'' \\ &= \frac{\partial}{\partial x} F_1 + \left(\frac{\partial F_1}{\partial y} \right) y' + \left(\frac{\partial F_1}{\partial y'} \right) F_0 \end{aligned}$$

⋮

$$\begin{aligned} F_n &= \frac{d}{dx} (F_{n-1}) \\ &= \frac{\partial}{\partial x} F_{n-1} + \left(\frac{\partial F_{n-1}}{\partial y} \right) y' + \left(\frac{\partial F_{n-1}}{\partial y'} \right) y'' \\ &= \frac{\partial}{\partial x} F_{n-1} + \left(\frac{\partial F_{n-1}}{\partial y} \right) y' + \left(\frac{\partial F_{n-1}}{\partial y'} \right) F_0 \end{aligned} \tag{6}$$

Therefore (6) can be used from now on along with

$$y(x) = y_0 + xy'_0 + \sum_{n=0}^{\infty} \frac{x^{n+2}}{(n+2)!} F_n|_{x_0, y_0, y'_0} \tag{7}$$

To find $y(x)$ series solution around $x = 0$. Hence

$$\begin{aligned}
 F_0 &= -\frac{\left(\frac{d}{dt}y(t)\right)t + \frac{d}{dt}y(t) + y(t)}{(1+t)^2} \\
 F_1 &= \frac{dF_0}{dt} \\
 &= \frac{\partial F_0}{\partial t} + \frac{\partial F_0}{\partial y} \frac{d}{dt}y(t) + \frac{\partial F_0}{\partial \frac{d}{dt}y(t)} F_0 \\
 &= \frac{\left(\frac{d}{dt}y(t)\right)(1+t) + 3y(t)}{(1+t)^3} \\
 F_2 &= \frac{dF_1}{dt} \\
 &= \frac{\partial F_1}{\partial t} + \frac{\partial F_1}{\partial y} \frac{d}{dt}y(t) + \frac{\partial F_1}{\partial \frac{d}{dt}y(t)} F_1 \\
 &= -\frac{10y(t)}{(1+t)^4} \\
 F_3 &= \frac{dF_2}{dt} \\
 &= \frac{\partial F_2}{\partial t} + \frac{\partial F_2}{\partial y} \frac{d}{dt}y(t) + \frac{\partial F_2}{\partial \frac{d}{dt}y(t)} F_2 \\
 &= \frac{(-10t - 10)\left(\frac{d}{dt}y(t)\right) + 40y(t)}{(1+t)^5} \\
 F_4 &= \frac{dF_3}{dt} \\
 &= \frac{\partial F_3}{\partial t} + \frac{\partial F_3}{\partial y} \frac{d}{dt}y(t) + \frac{\partial F_3}{\partial \frac{d}{dt}y(t)} F_3 \\
 &= \frac{(90t + 90)\left(\frac{d}{dt}y(t)\right) - 190y(t)}{(1+t)^6}
 \end{aligned}$$

And so on. Evaluating all the above at initial conditions $t = 0$ and $y(0) = y(0)$ and $y'(0) = y'(0)$ gives

$$\begin{aligned}
 F_0 &= -y'(0) - y(0) \\
 F_1 &= y'(0) + 3y(0) \\
 F_2 &= -10y(0) \\
 F_3 &= 40y(0) - 10y'(0) \\
 F_4 &= -190y(0) + 90y'(0)
 \end{aligned}$$

Substituting all the above in (7) and simplifying gives the solution as

$$y(t) = \left(1 - \frac{1}{2}t^2 + \frac{1}{2}t^3 - \frac{5}{12}t^4 + \frac{1}{3}t^5 - \frac{19}{72}t^6\right) y(0) + \left(t - \frac{1}{2}t^2 + \frac{1}{6}t^3 - \frac{1}{12}t^5 + \frac{1}{8}t^6\right) y'(0) + O(t^6)$$

Since the expansion point $t = 0$ is an ordinary, we can also solve this using standard power series. The ode is normalized to be

$$(t^2 + 2t + 1) \left(\frac{d^2}{dt^2}y(t)\right) + \left(\frac{d}{dt}y(t)\right) (1 + t) + y(t) = 0$$

Let the solution be represented as power series of the form

$$y(t) = \sum_{n=0}^{\infty} a_n t^n$$

Then

$$\begin{aligned} \frac{d}{dt}y(t) &= \sum_{n=1}^{\infty} n a_n t^{n-1} \\ \frac{d^2}{dt^2}y(t) &= \sum_{n=2}^{\infty} n(n-1) a_n t^{n-2} \end{aligned}$$

Substituting the above back into the ode gives

$$(t^2 + 2t + 1) \left(\sum_{n=2}^{\infty} n(n-1) a_n t^{n-2}\right) + \left(\sum_{n=1}^{\infty} n a_n t^{n-1}\right) (1 + t) + \left(\sum_{n=0}^{\infty} a_n t^n\right) = 0 \quad (1)$$

Which simplifies to

$$\begin{aligned} &\left(\sum_{n=2}^{\infty} t^n a_n n(n-1)\right) + \left(\sum_{n=2}^{\infty} 2n t^{n-1} a_n (n-1)\right) + \left(\sum_{n=2}^{\infty} n(n-1) a_n t^{n-2}\right) \\ &+ \left(\sum_{n=1}^{\infty} n a_n t^{n-1}\right) + \left(\sum_{n=1}^{\infty} n a_n t^n\right) + \left(\sum_{n=0}^{\infty} a_n t^n\right) = 0 \end{aligned} \quad (2)$$

The next step is to make all powers of t be n in each summation term. Going over each summation term above with power of t in it which is not already t^n and adjusting the

power and the corresponding index gives

$$\begin{aligned}\sum_{n=2}^{\infty} 2n t^{n-1} a_n (n-1) &= \sum_{n=1}^{\infty} 2(n+1) a_{n+1} n t^n \\ \sum_{n=2}^{\infty} n(n-1) a_n t^{n-2} &= \sum_{n=0}^{\infty} (n+2) a_{n+2} (n+1) t^n \\ \sum_{n=1}^{\infty} n a_n t^{n-1} &= \sum_{n=0}^{\infty} (n+1) a_{n+1} t^n\end{aligned}$$

Substituting all the above in Eq (2) gives the following equation where now all powers of t are the same and equal to n .

$$\begin{aligned}\left(\sum_{n=2}^{\infty} t^n a_n n(n-1)\right) + \left(\sum_{n=1}^{\infty} 2(n+1) a_{n+1} n t^n\right) + \left(\sum_{n=0}^{\infty} (n+2) a_{n+2} (n+1) t^n\right) \\ + \left(\sum_{n=0}^{\infty} (n+1) a_{n+1} t^n\right) + \left(\sum_{n=1}^{\infty} n a_n t^n\right) + \left(\sum_{n=0}^{\infty} a_n t^n\right) = 0\end{aligned}\quad (3)$$

$n = 0$ gives

$$2a_2 + a_1 + a_0 = 0$$

$$a_2 = -\frac{a_0}{2} - \frac{a_1}{2}$$

$n = 1$ gives

$$6a_2 + 6a_3 + 2a_1 = 0$$

Which after substituting earlier equations, simplifies to

$$a_3 = \frac{a_0}{2} + \frac{a_1}{6}$$

For $2 \leq n$, the recurrence equation is

$$n a_n (n-1) + 2(n+1) a_{n+1} n + (n+2) a_{n+2} (n+1) + (n+1) a_{n+1} + n a_n + a_n = 0 \quad (4)$$

Solving for a_{n+2} , gives

$$\begin{aligned} a_{n+2} &= -\frac{n^2 a_n + 2n^2 a_{n+1} + 3n a_{n+1} + a_n + a_{n+1}}{(n+2)(n+1)} \\ (5) \qquad &= -\frac{(n^2+1)a_n}{(n+2)(n+1)} - \frac{(2n^2+3n+1)a_{n+1}}{(n+2)(n+1)} \end{aligned}$$

For $n = 2$ the recurrence equation gives

$$5a_2 + 15a_3 + 12a_4 = 0$$

Which after substituting the earlier terms found becomes

$$a_4 = -\frac{5a_0}{12}$$

For $n = 3$ the recurrence equation gives

$$10a_3 + 28a_4 + 20a_5 = 0$$

Which after substituting the earlier terms found becomes

$$a_5 = \frac{a_0}{3} - \frac{a_1}{12}$$

For $n = 4$ the recurrence equation gives

$$17a_4 + 45a_5 + 30a_6 = 0$$

Which after substituting the earlier terms found becomes

$$a_6 = -\frac{19a_0}{72} + \frac{a_1}{8}$$

For $n = 5$ the recurrence equation gives

$$26a_5 + 66a_6 + 42a_7 = 0$$

Which after substituting the earlier terms found becomes

$$a_7 = \frac{5a_0}{24} - \frac{73a_1}{504}$$

And so on. Therefore the solution is

$$\begin{aligned} y(t) &= \sum_{n=0}^{\infty} a_n t^n \\ &= a_3 t^3 + a_2 t^2 + a_1 t + a_0 + \dots \end{aligned}$$

Substituting the values for a_n found above, the solution becomes

$$y(t) = a_0 + a_1 t + \left(-\frac{a_0}{2} - \frac{a_1}{2}\right) t^2 + \left(\frac{a_0}{2} + \frac{a_1}{6}\right) t^3 - \frac{5a_0 t^4}{12} + \left(\frac{a_0}{3} - \frac{a_1}{12}\right) t^5 + \dots$$

Collecting terms, the solution becomes

$$y(t) = \left(1 - \frac{1}{2}t^2 + \frac{1}{2}t^3 - \frac{5}{12}t^4 + \frac{1}{3}t^5\right) a_0 + \left(t - \frac{1}{2}t^2 + \frac{1}{6}t^3 - \frac{1}{12}t^5\right) a_1 + O(t^6) \quad (3)$$

At $t = 0$ the solution above becomes

$$y(t) = \left(1 - \frac{1}{2}t^2 + \frac{1}{2}t^3 - \frac{5}{12}t^4 + \frac{1}{3}t^5\right) c_1 + \left(t - \frac{1}{2}t^2 + \frac{1}{6}t^3 - \frac{1}{12}t^5\right) c_2 + O(t^6)$$

Replacing t in the above with the original independent variable x using $t = x - 1$ results in

$$\begin{aligned} y &= \left(1 - \frac{(x-1)^2}{2} + \frac{(x-1)^3}{2} - \frac{5(x-1)^4}{12} + \frac{(x-1)^5}{3} - \frac{19(x-1)^6}{72}\right) y(1) \\ &+ \left(x-1 - \frac{(x-1)^2}{2} + \frac{(x-1)^3}{6} - \frac{(x-1)^5}{12} + \frac{(x-1)^6}{8}\right) y'(1) + O((x-1)^6) \end{aligned}$$

Summary

The solution(s) found are the following

$$\begin{aligned} y &= \left(1 - \frac{(x-1)^2}{2} + \frac{(x-1)^3}{2} - \frac{5(x-1)^4}{12} + \frac{(x-1)^5}{3} - \frac{19(x-1)^6}{72}\right) y(1) \\ &+ \left(x-1 - \frac{(x-1)^2}{2} + \frac{(x-1)^3}{6} - \frac{(x-1)^5}{12} + \frac{(x-1)^6}{8}\right) y'(1) + O((x-1)^6) \end{aligned} \quad (1)$$

Verification of solutions

$$y = \left(1 - \frac{(x-1)^2}{2} + \frac{(x-1)^3}{2} - \frac{5(x-1)^4}{12} + \frac{(x-1)^5}{3} - \frac{19(x-1)^6}{72} \right) y(1) \\ + \left(x-1 - \frac{(x-1)^2}{2} + \frac{(x-1)^3}{6} - \frac{(x-1)^5}{12} + \frac{(x-1)^6}{8} \right) y'(1) + O((x-1)^6)$$

Verified OK.

14.15.1 Maple step by step solution

Let's solve

$$y''x^2 + y'x + y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = -\frac{y'}{x} - \frac{y}{x^2}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + \frac{y'}{x} + \frac{y}{x^2} = 0$$

- Multiply by denominators of the ODE

$$y''x^2 + y'x + y = 0$$

- Make a change of variables

$$t = \ln(x)$$

- Substitute the change of variables back into the ODE

- Calculate the 1st derivative of y with respect to x , using the chain rule

$$y' = \left(\frac{d}{dt} y(t) \right) t'(x)$$

- Compute derivative

$$y' = \frac{\frac{d}{dt} y(t)}{x}$$

- Calculate the 2nd derivative of y with respect to x , using the chain rule

$$y'' = \left(\frac{d^2}{dt^2} y(t) \right) t'(x)^2 + t''(x) \left(\frac{d}{dt} y(t) \right)$$

- Compute derivative

$$y'' = \frac{\frac{d^2}{dt^2} y(t)}{x^2} - \frac{\frac{d}{dt} y(t)}{x^2}$$

Substitute the change of variables back into the ODE

$$\left(\frac{d^2 y(t)}{dt^2} - \frac{d y(t)}{dt} \right) x^2 + \frac{d y(t)}{dt} + y(t) = 0$$

- Simplify
$$\frac{d^2}{dt^2} y(t) + y(t) = 0$$
- Characteristic polynomial of ODE
$$r^2 + 1 = 0$$
- Use quadratic formula to solve for r
$$r = \frac{0 \pm (\sqrt{-4})}{2}$$
- Roots of the characteristic polynomial
$$r = (-I, I)$$
- 1st solution of the ODE
$$y_1(t) = \cos(t)$$
- 2nd solution of the ODE
$$y_2(t) = \sin(t)$$
- General solution of the ODE
$$y(t) = c_1 y_1(t) + c_2 y_2(t)$$
- Substitute in solutions
$$y(t) = c_1 \cos(t) + c_2 \sin(t)$$
- Change variables back using $t = \ln(x)$
$$y = c_1 \cos(\ln(x)) + c_2 \sin(\ln(x))$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
checking if the LODE is of Euler type  
<- LODE of Euler type successful`
```

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 49

Order:=6;

```
dsolve(x^2*diff(y(x),x$2)+x*diff(y(x),x)+y(x)=0,y(x),type='series',x=1);
```

$$y(x) = \left(1 - \frac{(-1+x)^2}{2} + \frac{(-1+x)^3}{2} - \frac{5(-1+x)^4}{12} + \frac{(-1+x)^5}{3}\right) y(1) \\ + \left(-1+x - \frac{(-1+x)^2}{2} + \frac{(-1+x)^3}{6} - \frac{(-1+x)^5}{12}\right) D(y)(1) + O(x^6)$$

✓ Solution by Mathematica

Time used: 0.001 (sec). Leaf size: 78

```
AsymptoticDSolveValue[x^2*y''[x]+x*y'[x]+y[x]==0,y[x],{x,1,5}]
```

$$y(x) \rightarrow c_1 \left(\frac{1}{3}(x-1)^5 - \frac{5}{12}(x-1)^4 + \frac{1}{2}(x-1)^3 - \frac{1}{2}(x-1)^2 + 1 \right) \\ + c_2 \left(-\frac{1}{12}(x-1)^5 + \frac{1}{6}(x-1)^3 - \frac{1}{2}(x-1)^2 + x - 1 \right)$$

14.16 problem 16

14.16.1 Maple step by step solution 4000

Internal problem ID [11899]

Internal file name [OUTPUT/11908_Saturday_April_13_2024_01_14_32_AM_9598584/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.1. Exercises page 232

Problem number: 16.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : "second order series method. Ordinary point", "second_order_change_of_variable_on_x_method_2", "second order series method. Taylor series method"

Maple gives the following as the ode type

```
[[_Emden, _Fowler]]
```

$$x^2y'' + 3y'x - y = 0$$

With the expansion point for the power series method at $x = 1$.

The ode does not have its expansion point at $x = 0$, therefore to simplify the computation of power series expansion, change of variable is made on the independent variable to shift the initial conditions and the expansion point back to zero. The new ode is then solved more easily since the expansion point is now at zero. The solution converted back to the original independent variable. Let

$$t = x - 1$$

The ode is converted to be in terms of the new independent variable t . This results in

$$\left(\frac{d^2}{dt^2}y(t)\right)(1+t)^2 + 3\left(\frac{d}{dt}y(t)\right)(1+t) - y(t) = 0$$

With its expansion point and initial conditions now at $t = 0$. The transformed ODE is now solved. Solving ode using Taylor series method. This gives review on how the Taylor series method works for solving second order ode.

Let

$$y'' = f(x, y, y')$$

Assuming expansion is at $x_0 = 0$ (we can always shift the actual expansion point to 0 by change of variables) and assuming $f(x, y, y')$ is analytic at x_0 which must be the case for an ordinary point. Let initial conditions be $y(x_0) = y_0$ and $y'(x_0) = y'_0$. Using Taylor series gives

$$\begin{aligned} y(x) &= y(x_0) + (x - x_0)y'(x_0) + \frac{(x - x_0)^2}{2}y''(x_0) + \frac{(x - x_0)^3}{3!}y'''(x_0) + \cdots \\ &= y_0 + xy'_0 + \frac{x^2}{2}f|_{x_0, y_0, y'_0} + \frac{x^3}{3!}f'|_{x_0, y_0, y'_0} + \cdots \\ &= y_0 + xy'_0 + \sum_{n=0}^{\infty} \frac{x^{n+2}}{(n+2)!} \frac{d^n f}{dx^n} \Big|_{x_0, y_0, y'_0} \end{aligned}$$

But

$$\frac{df}{dx} = \frac{\partial f}{\partial x} \frac{dx}{dx} + \frac{\partial f}{\partial y} \frac{dy}{dx} + \frac{\partial f}{\partial y'} \frac{dy'}{dx} \quad (1)$$

$$= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} y'' \quad (828)$$

$$= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} f \quad (829)$$

$$\begin{aligned} \frac{d^2 f}{dx^2} &= \frac{d}{dx} \left(\frac{df}{dx} \right) \\ &= \frac{\partial}{\partial x} \left(\frac{df}{dx} \right) + \frac{\partial}{\partial y} \left(\frac{df}{dx} \right) y' + \frac{\partial}{\partial y'} \left(\frac{df}{dx} \right) f \end{aligned} \quad (2)$$

$$\begin{aligned} \frac{d^3 f}{dx^3} &= \frac{d}{dx} \left(\frac{d^2 f}{dx^2} \right) \\ &= \frac{\partial}{\partial x} \left(\frac{d^2 f}{dx^2} \right) + \left(\frac{\partial}{\partial y} \frac{d^2 f}{dx^2} \right) y' + \frac{\partial}{\partial y'} \left(\frac{d^2 f}{dx^2} \right) f \end{aligned} \quad (3)$$

⋮

And so on. Hence if we name $F_0 = f(x, y, y')$ then the above can be written as

$$F_0 = f(x, y, y') \tag{4}$$

$$\begin{aligned} F_1 &= \frac{df}{dx} \\ &= \frac{dF_0}{dx} \\ &= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y}y' + \frac{\partial f}{\partial y'}y'' \\ &= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y}y' + \frac{\partial f}{\partial y'}f \\ &= \frac{\partial F_0}{\partial x} + \frac{\partial F_0}{\partial y}y' + \frac{\partial F_0}{\partial y'}F_0 \end{aligned} \tag{5}$$

$$\begin{aligned} F_2 &= \frac{d}{dx} \left(\frac{d}{dx} f \right) \\ &= \frac{d}{dx} (F_1) \\ &= \frac{\partial}{\partial x} F_1 + \left(\frac{\partial F_1}{\partial y} \right) y' + \left(\frac{\partial F_1}{\partial y'} \right) y'' \\ &= \frac{\partial}{\partial x} F_1 + \left(\frac{\partial F_1}{\partial y} \right) y' + \left(\frac{\partial F_1}{\partial y'} \right) F_0 \end{aligned}$$

⋮

$$\begin{aligned} F_n &= \frac{d}{dx} (F_{n-1}) \\ &= \frac{\partial}{\partial x} F_{n-1} + \left(\frac{\partial F_{n-1}}{\partial y} \right) y' + \left(\frac{\partial F_{n-1}}{\partial y'} \right) y'' \\ &= \frac{\partial}{\partial x} F_{n-1} + \left(\frac{\partial F_{n-1}}{\partial y} \right) y' + \left(\frac{\partial F_{n-1}}{\partial y'} \right) F_0 \end{aligned} \tag{6}$$

Therefore (6) can be used from now on along with

$$y(x) = y_0 + xy'_0 + \sum_{n=0}^{\infty} \frac{x^{n+2}}{(n+2)!} F_n|_{x_0, y_0, y'_0} \tag{7}$$

To find $y(x)$ series solution around $x = 0$. Hence

$$\begin{aligned}
 F_0 &= -\frac{3\left(\frac{d}{dt}y(t)\right)t + 3\frac{d}{dt}y(t) - y(t)}{(1+t)^2} \\
 F_1 &= \frac{dF_0}{dt} \\
 &= \frac{\partial F_0}{\partial t} + \frac{\partial F_0}{\partial y} \frac{d}{dt}y(t) + \frac{\partial F_0}{\partial \frac{d}{dt}y(t)} F_0 \\
 &= \frac{13\left(\frac{d}{dt}y(t)\right)(1+t) - 5y(t)}{(1+t)^3} \\
 F_2 &= \frac{dF_1}{dt} \\
 &= \frac{\partial F_1}{\partial t} + \frac{\partial F_1}{\partial y} \frac{d}{dt}y(t) + \frac{\partial F_1}{\partial \frac{d}{dt}y(t)} F_1 \\
 &= \frac{(-70t - 70)\left(\frac{d}{dt}y(t)\right) + 28y(t)}{(1+t)^4} \\
 F_3 &= \frac{dF_2}{dt} \\
 &= \frac{\partial F_2}{\partial t} + \frac{\partial F_2}{\partial y} \frac{d}{dt}y(t) + \frac{\partial F_2}{\partial \frac{d}{dt}y(t)} F_2 \\
 &= \frac{(448t + 448)\left(\frac{d}{dt}y(t)\right) - 182y(t)}{(1+t)^5} \\
 F_4 &= \frac{dF_3}{dt} \\
 &= \frac{\partial F_3}{\partial t} + \frac{\partial F_3}{\partial y} \frac{d}{dt}y(t) + \frac{\partial F_3}{\partial \frac{d}{dt}y(t)} F_3 \\
 &= \frac{(-3318t - 3318)\left(\frac{d}{dt}y(t)\right) + 1358y(t)}{(1+t)^6}
 \end{aligned}$$

And so on. Evaluating all the above at initial conditions $t = 0$ and $y(0) = y(0)$ and $y'(0) = y'(0)$ gives

$$\begin{aligned}
 F_0 &= y(0) - 3y'(0) \\
 F_1 &= -5y(0) + 13y'(0) \\
 F_2 &= 28y(0) - 70y'(0) \\
 F_3 &= -182y(0) + 448y'(0) \\
 F_4 &= 1358y(0) - 3318y'(0)
 \end{aligned}$$

Substituting all the above in (7) and simplifying gives the solution as

$$y(t) = \left(1 + \frac{1}{2}t^2 - \frac{5}{6}t^3 + \frac{7}{6}t^4 - \frac{91}{60}t^5 + \frac{679}{360}t^6\right)y(0) \\ + \left(t - \frac{3}{2}t^2 + \frac{13}{6}t^3 - \frac{35}{12}t^4 + \frac{56}{15}t^5 - \frac{553}{120}t^6\right)y'(0) + O(t^6)$$

Since the expansion point $t = 0$ is an ordinary, we can also solve this using standard power series. The ode is normalized to be

$$(t^2 + 2t + 1) \left(\frac{d^2}{dt^2}y(t)\right) + (3t + 3) \left(\frac{d}{dt}y(t)\right) - y(t) = 0$$

Let the solution be represented as power series of the form

$$y(t) = \sum_{n=0}^{\infty} a_n t^n$$

Then

$$\frac{d}{dt}y(t) = \sum_{n=1}^{\infty} n a_n t^{n-1} \\ \frac{d^2}{dt^2}y(t) = \sum_{n=2}^{\infty} n(n-1) a_n t^{n-2}$$

Substituting the above back into the ode gives

$$(t^2 + 2t + 1) \left(\sum_{n=2}^{\infty} n(n-1) a_n t^{n-2}\right) + (3t + 3) \left(\sum_{n=1}^{\infty} n a_n t^{n-1}\right) - \left(\sum_{n=0}^{\infty} a_n t^n\right) = 0 \quad (1)$$

Which simplifies to

$$\left(\sum_{n=2}^{\infty} t^n a_n n(n-1)\right) + \left(\sum_{n=2}^{\infty} 2n t^{n-1} a_n (n-1)\right) + \left(\sum_{n=2}^{\infty} n(n-1) a_n t^{n-2}\right) \\ + \left(\sum_{n=1}^{\infty} 3n a_n t^n\right) + \left(\sum_{n=1}^{\infty} 3n a_n t^{n-1}\right) + \sum_{n=0}^{\infty} (-a_n t^n) = 0 \quad (2)$$

The next step is to make all powers of t be n in each summation term. Going over each summation term above with power of t in it which is not already t^n and adjusting the

power and the corresponding index gives

$$\begin{aligned}\sum_{n=2}^{\infty} 2n t^{n-1} a_n (n-1) &= \sum_{n=1}^{\infty} 2(n+1) a_{n+1} n t^n \\ \sum_{n=2}^{\infty} n(n-1) a_n t^{n-2} &= \sum_{n=0}^{\infty} (n+2) a_{n+2} (n+1) t^n \\ \sum_{n=1}^{\infty} 3n a_n t^{n-1} &= \sum_{n=0}^{\infty} 3(n+1) a_{n+1} t^n\end{aligned}$$

Substituting all the above in Eq (2) gives the following equation where now all powers of t are the same and equal to n .

$$\begin{aligned}\left(\sum_{n=2}^{\infty} t^n a_n n(n-1) \right) + \left(\sum_{n=1}^{\infty} 2(n+1) a_{n+1} n t^n \right) + \left(\sum_{n=0}^{\infty} (n+2) a_{n+2} (n+1) t^n \right) \\ + \left(\sum_{n=1}^{\infty} 3n a_n t^n \right) + \left(\sum_{n=0}^{\infty} 3(n+1) a_{n+1} t^n \right) + \sum_{n=0}^{\infty} (-a_n t^n) = 0\end{aligned} \quad (3)$$

$n = 0$ gives

$$2a_2 + 3a_1 - a_0 = 0$$

$$a_2 = \frac{a_0}{2} - \frac{3a_1}{2}$$

$n = 1$ gives

$$10a_2 + 6a_3 + 2a_1 = 0$$

Which after substituting earlier equations, simplifies to

$$a_3 = -\frac{5a_0}{6} + \frac{13a_1}{6}$$

For $2 \leq n$, the recurrence equation is

$$n a_n (n-1) + 2(n+1) a_{n+1} n + (n+2) a_{n+2} (n+1) + 3n a_n + 3(n+1) a_{n+1} - a_n = 0 \quad (4)$$

Solving for a_{n+2} , gives

$$\begin{aligned} a_{n+2} &= -\frac{n^2 a_n + 2n^2 a_{n+1} + 2n a_n + 5n a_{n+1} - a_n + 3a_{n+1}}{(n+2)(n+1)} \\ (5) \quad &= -\frac{(n^2 + 2n - 1) a_n}{(n+2)(n+1)} - \frac{(2n^2 + 5n + 3) a_{n+1}}{(n+2)(n+1)} \end{aligned}$$

For $n = 2$ the recurrence equation gives

$$7a_2 + 21a_3 + 12a_4 = 0$$

Which after substituting the earlier terms found becomes

$$a_4 = \frac{7a_0}{6} - \frac{35a_1}{12}$$

For $n = 3$ the recurrence equation gives

$$14a_3 + 36a_4 + 20a_5 = 0$$

Which after substituting the earlier terms found becomes

$$a_5 = -\frac{91a_0}{60} + \frac{56a_1}{15}$$

For $n = 4$ the recurrence equation gives

$$23a_4 + 55a_5 + 30a_6 = 0$$

Which after substituting the earlier terms found becomes

$$a_6 = \frac{679a_0}{360} - \frac{553a_1}{120}$$

For $n = 5$ the recurrence equation gives

$$34a_5 + 78a_6 + 42a_7 = 0$$

Which after substituting the earlier terms found becomes

$$a_7 = -\frac{91a_0}{40} + \frac{1993a_1}{360}$$

And so on. Therefore the solution is

$$\begin{aligned} y(t) &= \sum_{n=0}^{\infty} a_n t^n \\ &= a_3 t^3 + a_2 t^2 + a_1 t + a_0 + \dots \end{aligned}$$

Substituting the values for a_n found above, the solution becomes

$$\begin{aligned} y(t) &= a_0 + a_1 t + \left(\frac{a_0}{2} - \frac{3a_1}{2} \right) t^2 + \left(-\frac{5a_0}{6} + \frac{13a_1}{6} \right) t^3 \\ &\quad + \left(\frac{7a_0}{6} - \frac{35a_1}{12} \right) t^4 + \left(-\frac{91a_0}{60} + \frac{56a_1}{15} \right) t^5 + \dots \end{aligned}$$

Collecting terms, the solution becomes

$$y(t) = \left(1 + \frac{1}{2}t^2 - \frac{5}{6}t^3 + \frac{7}{6}t^4 - \frac{91}{60}t^5 \right) a_0 + \left(t - \frac{3}{2}t^2 + \frac{13}{6}t^3 - \frac{35}{12}t^4 + \frac{56}{15}t^5 \right) a_1 + O(t^6) \quad (3)$$

At $t = 0$ the solution above becomes

$$y(t) = \left(1 + \frac{1}{2}t^2 - \frac{5}{6}t^3 + \frac{7}{6}t^4 - \frac{91}{60}t^5 \right) c_1 + \left(t - \frac{3}{2}t^2 + \frac{13}{6}t^3 - \frac{35}{12}t^4 + \frac{56}{15}t^5 \right) c_2 + O(t^6)$$

Replacing t in the above with the original independent variable x using $t = x - 1$ results in

$$\begin{aligned} y &= \left(1 + \frac{(x-1)^2}{2} - \frac{5(x-1)^3}{6} + \frac{7(x-1)^4}{6} - \frac{91(x-1)^5}{60} + \frac{679(x-1)^6}{360} \right) y(1) \\ &\quad + \left(x-1 - \frac{3(x-1)^2}{2} + \frac{13(x-1)^3}{6} - \frac{35(x-1)^4}{12} + \frac{56(x-1)^5}{15} - \frac{553(x-1)^6}{120} \right) y'(1) \\ &\quad + O((x-1)^6) \end{aligned}$$

Summary

The solution(s) found are the following

$$\begin{aligned} y &= \left(1 + \frac{(x-1)^2}{2} - \frac{5(x-1)^3}{6} + \frac{7(x-1)^4}{6} - \frac{91(x-1)^5}{60} + \frac{679(x-1)^6}{360} \right) y(1) \\ &\quad + \left(x-1 - \frac{3(x-1)^2}{2} + \frac{13(x-1)^3}{6} - \frac{35(x-1)^4}{12} + \frac{56(x-1)^5}{15} \right. \\ &\quad \left. - \frac{553(x-1)^6}{120} \right) y'(1) + O((x-1)^6) \end{aligned} \quad (1)$$

Verification of solutions

$$y = \left(1 + \frac{(x-1)^2}{2} - \frac{5(x-1)^3}{6} + \frac{7(x-1)^4}{6} - \frac{91(x-1)^5}{60} + \frac{679(x-1)^6}{360} \right) y(1) \\ + \left(x-1 - \frac{3(x-1)^2}{2} + \frac{13(x-1)^3}{6} - \frac{35(x-1)^4}{12} + \frac{56(x-1)^5}{15} - \frac{553(x-1)^6}{120} \right) y'(1) \\ + O((x-1)^6)$$

Verified OK.

14.16.1 Maple step by step solution

Let's solve

$$y''x^2 + 3y'x - y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = -\frac{3y'}{x} + \frac{y}{x^2}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + \frac{3y'}{x} - \frac{y}{x^2} = 0$$

- Multiply by denominators of the ODE

$$y''x^2 + 3y'x - y = 0$$

- Make a change of variables

$$t = \ln(x)$$

- Substitute the change of variables back into the ODE

- Calculate the 1st derivative of y with respect to x , using the chain rule

$$y' = \left(\frac{d}{dt} y(t) \right) t'(x)$$

- Compute derivative

$$y' = \frac{\frac{d}{dt} y(t)}{x}$$

- Calculate the 2nd derivative of y with respect to x , using the chain rule

$$y'' = \left(\frac{d^2}{dt^2} y(t) \right) t'(x)^2 + t''(x) \left(\frac{d}{dt} y(t) \right)$$

- Compute derivative

$$y'' = \frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2}$$

Substitute the change of variables back into the ODE

$$\left(\frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2} \right) x^2 + 3 \frac{d}{dt}y(t) - y(t) = 0$$

- Simplify

$$\frac{d^2}{dt^2}y(t) + 2 \frac{d}{dt}y(t) - y(t) = 0$$

- Characteristic polynomial of ODE

$$r^2 + 2r - 1 = 0$$

- Use quadratic formula to solve for r

$$r = \frac{(-2) \pm (\sqrt{8})}{2}$$

- Roots of the characteristic polynomial

$$r = (-\sqrt{2} - 1, \sqrt{2} - 1)$$

- 1st solution of the ODE

$$y_1(t) = e^{(-\sqrt{2}-1)t}$$

- 2nd solution of the ODE

$$y_2(t) = e^{(\sqrt{2}-1)t}$$

- General solution of the ODE

$$y(t) = c_1 y_1(t) + c_2 y_2(t)$$

- Substitute in solutions

$$y(t) = c_1 e^{(-\sqrt{2}-1)t} + c_2 e^{(\sqrt{2}-1)t}$$

- Change variables back using $t = \ln(x)$

$$y = c_1 e^{(-\sqrt{2}-1)\ln(x)} + c_2 e^{(\sqrt{2}-1)\ln(x)}$$

- Simplify

$$y = \frac{c_1 x^{-\sqrt{2}}}{x} + \frac{c_2 x^{\sqrt{2}}}{x}$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
checking if the LODE is of Euler type  
<- LODE of Euler type successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 54

```
Order:=6;  
dsolve(x^2*diff(y(x),x$2)+3*x*diff(y(x),x)-y(x)=0,y(x),type='series',x=1);
```

$$y(x) = \left(1 + \frac{(-1+x)^2}{2} - \frac{5(-1+x)^3}{6} + \frac{7(-1+x)^4}{6} - \frac{91(-1+x)^5}{60}\right) y(1) \\ + \left(-1+x - \frac{3(-1+x)^2}{2} + \frac{13(-1+x)^3}{6} - \frac{35(-1+x)^4}{12} + \frac{56(-1+x)^5}{15}\right) D(y)(1) \\ + O(x^6)$$

✓ Solution by Mathematica

Time used: 0.001 (sec). Leaf size: 87

```
AsymptoticDSolveValue[x^2*y''[x]+3*x*y'[x]-y[x]==0,y[x],{x,1,5}]
```

$$y(x) \rightarrow c_1 \left(-\frac{91}{60}(x-1)^5 + \frac{7}{6}(x-1)^4 - \frac{5}{6}(x-1)^3 + \frac{1}{2}(x-1)^2 + 1 \right) \\ + c_2 \left(\frac{56}{15}(x-1)^5 - \frac{35}{12}(x-1)^4 + \frac{13}{6}(x-1)^3 - \frac{3}{2}(x-1)^2 + x - 1 \right)$$

14.17 problem 17

14.17.1 Existence and uniqueness analysis	4003
14.17.2 Maple step by step solution	4012

Internal problem ID [11900]

Internal file name [OUTPUT/11909_Saturday_April_13_2024_01_14_33_AM_53322424/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.1. Exercises page 232

Problem number: 17.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"second order series method. Ordinary point", "second order series method. Taylor series method"**

Maple gives the following as the ode type

```
[[_Emden , _Fowler]]
```

$$xy'' + y' + 2y = 0$$

With initial conditions

$$[y(1) = 2, y'(1) = 4]$$

With the expansion point for the power series method at $x = 1$.

14.17.1 Existence and uniqueness analysis

This is a linear ODE. In canonical form it is written as

$$y'' + p(x)y' + q(x)y = F$$

Where here

$$p(x) = \frac{1}{x}$$
$$q(x) = \frac{2}{x}$$
$$F = 0$$

Hence the ode is

$$y'' + \frac{y'}{x} + \frac{2y}{x} = 0$$

The domain of $p(x) = \frac{1}{x}$ is

$$\{x < 0 \vee 0 < x\}$$

And the point $x_0 = 1$ is inside this domain. The domain of $q(x) = \frac{2}{x}$ is

$$\{x < 0 \vee 0 < x\}$$

And the point $x_0 = 1$ is also inside this domain. Hence solution exists and is unique.

The ode does not have its expansion point at $x = 0$, therefore to simplify the computation of power series expansion, change of variable is made on the independent variable to shift the initial conditions and the expansion point back to zero. The new ode is then solved more easily since the expansion point is now at zero. The solution converted back to the original independent variable. Let

$$t = x - 1$$

The ode is converted to be in terms of the new independent variable t . This results in

$$\left(\frac{d^2}{dt^2}y(t)\right)(1+t) + \frac{d}{dt}y(t) + 2y(t) = 0$$

With its expansion point and initial conditions now at $t = 0$. With initial conditions now becoming

$$y(0) = 2$$

$$y'(0) = 4$$

The transformed ODE is now solved. Solving ode using Taylor series method. This gives review on how the Taylor series method works for solving second order ode.

Let

$$y'' = f(x, y, y')$$

Assuming expansion is at $x_0 = 0$ (we can always shift the actual expansion point to 0 by change of variables) and assuming $f(x, y, y')$ is analytic at x_0 which must be the

case for an ordinary point. Let initial conditions be $y(x_0) = y_0$ and $y'(x_0) = y'_0$. Using Taylor series gives

$$\begin{aligned}
 y(x) &= y(x_0) + (x - x_0)y'(x_0) + \frac{(x - x_0)^2}{2}y''(x_0) + \frac{(x - x_0)^3}{3!}y'''(x_0) + \cdots \\
 &= y_0 + xy'_0 + \frac{x^2}{2}f|_{x_0, y_0, y'_0} + \frac{x^3}{3!}f'|_{x_0, y_0, y'_0} + \cdots \\
 &= y_0 + xy'_0 + \sum_{n=0}^{\infty} \frac{x^{n+2}}{(n+2)!} \frac{d^n f}{dx^n} \Big|_{x_0, y_0, y'_0}
 \end{aligned}$$

But

$$\frac{df}{dx} = \frac{\partial f}{\partial x} \frac{dx}{dx} + \frac{\partial f}{\partial y} \frac{dy}{dx} + \frac{\partial f}{\partial y'} \frac{dy'}{dx} \tag{1}$$

$$= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} y'' \tag{831}$$

$$= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} f \tag{832}$$

$$\begin{aligned}
 \frac{d^2 f}{dx^2} &= \frac{d}{dx} \left(\frac{df}{dx} \right) \\
 &= \frac{\partial}{\partial x} \left(\frac{df}{dx} \right) + \frac{\partial}{\partial y} \left(\frac{df}{dx} \right) y' + \frac{\partial}{\partial y'} \left(\frac{df}{dx} \right) f \tag{2}
 \end{aligned}$$

$$\begin{aligned}
 \frac{d^3 f}{dx^3} &= \frac{d}{dx} \left(\frac{d^2 f}{dx^2} \right) \\
 &= \frac{\partial}{\partial x} \left(\frac{d^2 f}{dx^2} \right) + \left(\frac{\partial}{\partial y} \frac{d^2 f}{dx^2} \right) y' + \frac{\partial}{\partial y'} \left(\frac{d^2 f}{dx^2} \right) f \tag{3}
 \end{aligned}$$

⋮

And so on. Hence if we name $F_0 = f(x, y, y')$ then the above can be written as

$$F_0 = f(x, y, y') \quad (4)$$

$$\begin{aligned} F_1 &= \frac{df}{dx} \\ &= \frac{dF_0}{dx} \\ &= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y}y' + \frac{\partial f}{\partial y'}y'' \\ &= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y}y' + \frac{\partial f}{\partial y'}f \\ &= \frac{\partial F_0}{\partial x} + \frac{\partial F_0}{\partial y}y' + \frac{\partial F_0}{\partial y'}F_0 \end{aligned} \quad (5)$$

$$\begin{aligned} F_2 &= \frac{d}{dx} \left(\frac{d}{dx} f \right) \\ &= \frac{d}{dx} (F_1) \\ &= \frac{\partial}{\partial x} F_1 + \left(\frac{\partial F_1}{\partial y} \right) y' + \left(\frac{\partial F_1}{\partial y'} \right) y'' \\ &= \frac{\partial}{\partial x} F_1 + \left(\frac{\partial F_1}{\partial y} \right) y' + \left(\frac{\partial F_1}{\partial y'} \right) F_0 \\ &\vdots \\ F_n &= \frac{d}{dx} (F_{n-1}) \\ &= \frac{\partial}{\partial x} F_{n-1} + \left(\frac{\partial F_{n-1}}{\partial y} \right) y' + \left(\frac{\partial F_{n-1}}{\partial y'} \right) y'' \\ &= \frac{\partial}{\partial x} F_{n-1} + \left(\frac{\partial F_{n-1}}{\partial y} \right) y' + \left(\frac{\partial F_{n-1}}{\partial y'} \right) F_0 \end{aligned} \quad (6)$$

Therefore (6) can be used from now on along with

$$y(x) = y_0 + xy'_0 + \sum_{n=0}^{\infty} \frac{x^{n+2}}{(n+2)!} F_n|_{x_0, y_0, y'_0} \quad (7)$$

To find $y(x)$ series solution around $x = 0$. Hence

$$\begin{aligned}
 F_0 &= -\frac{\frac{d}{dt}y(t) + 2y(t)}{1+t} \\
 F_1 &= \frac{dF_0}{dt} \\
 &= \frac{\partial F_0}{\partial t} + \frac{\partial F_0}{\partial y} \frac{d}{dt}y(t) + \frac{\partial F_0}{\partial \frac{d}{dt}y(t)} F_0 \\
 &= \frac{-2\left(\frac{d}{dt}y(t)\right)t + 4y(t)}{(1+t)^2} \\
 F_2 &= \frac{dF_1}{dt} \\
 &= \frac{\partial F_1}{\partial t} + \frac{\partial F_1}{\partial y} \frac{d}{dt}y(t) + \frac{\partial F_1}{\partial \frac{d}{dt}y(t)} F_1 \\
 &= \frac{(8t+2)\left(\frac{d}{dt}y(t)\right) + 4y(t)(-2+t)}{(1+t)^3} \\
 F_3 &= \frac{dF_2}{dt} \\
 &= \frac{\partial F_2}{\partial t} + \frac{\partial F_2}{\partial y} \frac{d}{dt}y(t) + \frac{\partial F_2}{\partial \frac{d}{dt}y(t)} F_2 \\
 &= \frac{(4t^2 - 28t - 8)\left(\frac{d}{dt}y(t)\right) - 24y(t)(t-1)}{(1+t)^4} \\
 F_4 &= \frac{dF_3}{dt} \\
 &= \frac{\partial F_3}{\partial t} + \frac{\partial F_3}{\partial y} \frac{d}{dt}y(t) + \frac{\partial F_3}{\partial \frac{d}{dt}y(t)} F_3 \\
 &= \frac{(-36t^2 + 120t + 36)\left(\frac{d}{dt}y(t)\right) - 8y(t)(t^2 - 16t + 13)}{(1+t)^5}
 \end{aligned}$$

And so on. Evaluating all the above at initial conditions $t = 0$ and $y(0) = 2$ and $y'(0) = 4$ gives

$$F_0 = -8$$

$$F_1 = 8$$

$$F_2 = -8$$

$$F_3 = 16$$

$$F_4 = -64$$

Substituting all the above in (7) and simplifying gives the solution as

$$y(t) = -4t^2 + 4t + 2 + \frac{4t^3}{3} - \frac{t^4}{3} + \frac{2t^5}{15} - \frac{4t^6}{45} + O(t^6)$$

$$y(t) = -4t^2 + 4t + 2 + \frac{4t^3}{3} - \frac{t^4}{3} + \frac{2t^5}{15} - \frac{4t^6}{45} + O(t^6)$$

Since the expansion point $t = 0$ is an ordinary, we can also solve this using standard power series. The ode is normalized to be

$$\left(\frac{d^2}{dt^2}y(t)\right)(1+t) + \frac{d}{dt}y(t) + 2y(t) = 0$$

Let the solution be represented as power series of the form

$$y(t) = \sum_{n=0}^{\infty} a_n t^n$$

Then

$$\begin{aligned} \frac{d}{dt}y(t) &= \sum_{n=1}^{\infty} n a_n t^{n-1} \\ \frac{d^2}{dt^2}y(t) &= \sum_{n=2}^{\infty} n(n-1) a_n t^{n-2} \end{aligned}$$

Substituting the above back into the ode gives

$$\left(\sum_{n=2}^{\infty} n(n-1) a_n t^{n-2}\right)(1+t) + \left(\sum_{n=1}^{\infty} n a_n t^{n-1}\right) + 2\left(\sum_{n=0}^{\infty} a_n t^n\right) = 0 \quad (1)$$

Which simplifies to

$$\left(\sum_{n=2}^{\infty} n t^{n-1} a_n (n-1)\right) + \left(\sum_{n=2}^{\infty} n(n-1) a_n t^{n-2}\right) + \left(\sum_{n=1}^{\infty} n a_n t^{n-1}\right) + \left(\sum_{n=0}^{\infty} 2 a_n t^n\right) = 0 \quad (2)$$

The next step is to make all powers of t be n in each summation term. Going over each summation term above with power of t in it which is not already t^n and adjusting the

power and the corresponding index gives

$$\begin{aligned}\sum_{n=2}^{\infty} n t^{n-1} a_n (n-1) &= \sum_{n=1}^{\infty} (n+1) a_{n+1} n t^n \\ \sum_{n=2}^{\infty} n(n-1) a_n t^{n-2} &= \sum_{n=0}^{\infty} (n+2) a_{n+2} (n+1) t^n \\ \sum_{n=1}^{\infty} n a_n t^{n-1} &= \sum_{n=0}^{\infty} (n+1) a_{n+1} t^n\end{aligned}$$

Substituting all the above in Eq (2) gives the following equation where now all powers of t are the same and equal to n .

$$\begin{aligned}\left(\sum_{n=1}^{\infty} (n+1) a_{n+1} n t^n \right) + \left(\sum_{n=0}^{\infty} (n+2) a_{n+2} (n+1) t^n \right) \\ + \left(\sum_{n=0}^{\infty} (n+1) a_{n+1} t^n \right) + \left(\sum_{n=0}^{\infty} 2a_n t^n \right) = 0\end{aligned}\tag{3}$$

$n = 0$ gives

$$2a_2 + a_1 + 2a_0 = 0$$

$$a_2 = -a_0 - \frac{a_1}{2}$$

For $1 \leq n$, the recurrence equation is

$$(n+1) a_{n+1} n + (n+2) a_{n+2} (n+1) + (n+1) a_{n+1} + 2a_n = 0\tag{4}$$

Solving for a_{n+2} , gives

$$\begin{aligned}a_{n+2} &= -\frac{n^2 a_{n+1} + 2n a_{n+1} + 2a_n + a_{n+1}}{(n+2)(n+1)} \\ &= -\frac{2a_n}{(n+2)(n+1)} - \frac{(n^2 + 2n + 1) a_{n+1}}{(n+2)(n+1)}\end{aligned}\tag{5}$$

For $n = 1$ the recurrence equation gives

$$4a_2 + 6a_3 + 2a_1 = 0$$

Which after substituting the earlier terms found becomes

$$a_3 = \frac{2a_0}{3}$$

For $n = 2$ the recurrence equation gives

$$9a_3 + 12a_4 + 2a_2 = 0$$

Which after substituting the earlier terms found becomes

$$a_4 = -\frac{a_0}{3} + \frac{a_1}{12}$$

For $n = 3$ the recurrence equation gives

$$16a_4 + 20a_5 + 2a_3 = 0$$

Which after substituting the earlier terms found becomes

$$a_5 = \frac{a_0}{5} - \frac{a_1}{15}$$

For $n = 4$ the recurrence equation gives

$$25a_5 + 30a_6 + 2a_4 = 0$$

Which after substituting the earlier terms found becomes

$$a_6 = -\frac{13a_0}{90} + \frac{a_1}{20}$$

For $n = 5$ the recurrence equation gives

$$36a_6 + 42a_7 + 2a_5 = 0$$

Which after substituting the earlier terms found becomes

$$a_7 = \frac{4a_0}{35} - \frac{5a_1}{126}$$

And so on. Therefore the solution is

$$\begin{aligned} y(t) &= \sum_{n=0}^{\infty} a_n t^n \\ &= a_3 t^3 + a_2 t^2 + a_1 t + a_0 + \dots \end{aligned}$$

Substituting the values for a_n found above, the solution becomes

$$y(t) = a_0 + a_1 t + \left(-a_0 - \frac{a_1}{2}\right) t^2 + \frac{2a_0 t^3}{3} + \left(-\frac{a_0}{3} + \frac{a_1}{12}\right) t^4 + \left(\frac{a_0}{5} - \frac{a_1}{15}\right) t^5 + \dots$$

Collecting terms, the solution becomes

$$y(t) = \left(1 - t^2 + \frac{2}{3}t^3 - \frac{1}{3}t^4 + \frac{1}{5}t^5\right) a_0 + \left(t - \frac{1}{2}t^2 + \frac{1}{12}t^4 - \frac{1}{15}t^5\right) a_1 + O(t^6) \quad (3)$$

At $t = 0$ the solution above becomes

$$y(t) = \left(1 - t^2 + \frac{2}{3}t^3 - \frac{1}{3}t^4 + \frac{1}{5}t^5\right) c_1 + \left(t - \frac{1}{2}t^2 + \frac{1}{12}t^4 - \frac{1}{15}t^5\right) c_2 + O(t^6)$$

$$y(t) = 2 - 4t^2 + \frac{4t^3}{3} - \frac{t^4}{3} + \frac{2t^5}{15} + 4t + O(t^6)$$

Replacing t in the above with the original independent variable x using $t = x - 1$ results in

$$y = -4(x-1)^2 + 4x - 2 + \frac{4(x-1)^3}{3} - \frac{(x-1)^4}{3} + \frac{2(x-1)^5}{15} - \frac{4(x-1)^6}{45} + O((x-1)^6)$$

Summary

The solution(s) found are the following

$$y = -4(x-1)^2 + 4x - 2 + \frac{4(x-1)^3}{3} - \frac{(x-1)^4}{3} + \frac{2(x-1)^5}{15} - \frac{4(x-1)^6}{45} + O((x-1)^6) \quad (1)$$

Verification of solutions

$$y = -4(x-1)^2 + 4x - 2 + \frac{4(x-1)^3}{3} - \frac{(x-1)^4}{3} + \frac{2(x-1)^5}{15} - \frac{4(x-1)^6}{45} + O((x-1)^6)$$

Verified OK.

14.17.2 Maple step by step solution

Let's solve

$$\left[y''x + y' + 2y = 0, y(1) = 2, y'|_{\{x=1\}} = 4 \right]$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = -\frac{2y}{x} - \frac{y'}{x}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + \frac{y'}{x} + \frac{2y}{x} = 0$$

- Check to see if $x_0 = 0$ is a regular singular point

- Define functions

$$\left[P_2(x) = \frac{1}{x}, P_3(x) = \frac{2}{x} \right]$$

- $x \cdot P_2(x)$ is analytic at $x = 0$

$$(x \cdot P_2(x)) \Big|_{x=0} = 1$$

- $x^2 \cdot P_3(x)$ is analytic at $x = 0$

$$(x^2 \cdot P_3(x)) \Big|_{x=0} = 0$$

- $x = 0$ is a regular singular point

Check to see if $x_0 = 0$ is a regular singular point

$$x_0 = 0$$

- Multiply by denominators

$$y''x + y' + 2y = 0$$

- Assume series solution for y

$$y = \sum_{k=0}^{\infty} a_k x^{k+r}$$

- Rewrite ODE with series expansions

- Convert y' to series expansion

$$y' = \sum_{k=0}^{\infty} a_k (k+r) x^{k+r-1}$$

- Shift index using $k \rightarrow k + 1$

$$y' = \sum_{k=-1}^{\infty} a_{k+1}(k+1+r)x^{k+r}$$

- Convert $x \cdot y''$ to series expansion

$$x \cdot y'' = \sum_{k=0}^{\infty} a_k(k+r)(k+r-1)x^{k+r-1}$$

- Shift index using $k \rightarrow k + 1$

$$x \cdot y'' = \sum_{k=-1}^{\infty} a_{k+1}(k+1+r)(k+r)x^{k+r}$$

Rewrite ODE with series expansions

$$a_0 r^2 x^{-1+r} + \left(\sum_{k=0}^{\infty} (a_{k+1}(k+1+r)^2 + 2a_k) x^{k+r} \right) = 0$$

- a_0 cannot be 0 by assumption, giving the indicial equation
 $r^2 = 0$
- Values of r that satisfy the indicial equation
 $r = 0$
- Each term in the series must be 0, giving the recursion relation
 $a_{k+1}(k+1)^2 + 2a_k = 0$
- Recursion relation that defines series solution to ODE
 $a_{k+1} = -\frac{2a_k}{(k+1)^2}$
- Recursion relation for $r = 0$
 $a_{k+1} = -\frac{2a_k}{(k+1)^2}$
- Solution for $r = 0$

$$\left[y = \sum_{k=0}^{\infty} a_k x^k, a_{k+1} = -\frac{2a_k}{(k+1)^2} \right]$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
checking if the LODE is of Euler type  
trying a symmetry of the form [xi=0, eta=F(x)]  
checking if the LODE is missing y  
-> Trying a Liouvillian solution using Kovacic's algorithm  
<- No Liouvillian solutions exists  
-> Trying a solution in terms of special functions:  
  -> Bessel  
  <- Bessel successful  
<- special function solution successful`
```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 20

```
Order:=6;  
dsolve([x*diff(y(x),x$2)+diff(y(x),x)+2*y(x)=0,y(1) = 2, D(y)(1) = 4],y(x),type='series',x=1
```

$$y(x) = 2 + 4(-1 + x) - 4(-1 + x)^2 + \frac{4}{3}(-1 + x)^3 - \frac{1}{3}(-1 + x)^4 + \frac{2}{15}(-1 + x)^5 + O((-1 + x)^6)$$

✓ Solution by Mathematica

Time used: 0.001 (sec). Leaf size: 44

```
AsymptoticDSolveValue[{x*y''[x]+y'[x]+2*y[x]==0,{y[1]==2,y'[1]==4}},y[x],{x,1,5}]
```

$$y(x) \rightarrow \frac{2}{15}(x-1)^5 - \frac{1}{3}(x-1)^4 + \frac{4}{3}(x-1)^3 - 4(x-1)^2 + 4(x-1) + 2$$

14.18 problem 18

14.18.1 Maple step by step solution 4023

Internal problem ID [11901]

Internal file name [OUTPUT/11910_Saturday_April_13_2024_01_14_35_AM_36640186/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.1. Exercises page 232

Problem number: 18.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"second order series method. Ordinary point", "second order series method. Taylor series method"**

Maple gives the following as the ode type

[_Gegenbauer]

$$\boxed{(-x^2 + 1)y'' - 2y'x + n(n + 1)y = 0}$$

With the expansion point for the power series method at $x = 0$.

Solving ode using Taylor series method. This gives review on how the Taylor series method works for solving second order ode.

Let

$$y'' = f(x, y, y')$$

Assuming expansion is at $x_0 = 0$ (we can always shift the actual expansion point to 0 by change of variables) and assuming $f(x, y, y')$ is analytic at x_0 which must be the case for an ordinary point. Let initial conditions be $y(x_0) = y_0$ and $y'(x_0) = y'_0$. Using Taylor series gives

$$\begin{aligned} y(x) &= y(x_0) + (x - x_0)y'(x_0) + \frac{(x - x_0)^2}{2}y''(x_0) + \frac{(x - x_0)^3}{3!}y'''(x_0) + \cdots \\ &= y_0 + xy'_0 + \frac{x^2}{2}f|_{x_0, y_0, y'_0} + \frac{x^3}{3!}f'|_{x_0, y_0, y'_0} + \cdots \\ &= y_0 + xy'_0 + \sum_{n=0}^{\infty} \frac{x^{n+2}}{(n+2)!} \frac{d^n f}{dx^n} \Big|_{x_0, y_0, y'_0} \end{aligned}$$

But

$$\frac{df}{dx} = \frac{\partial f}{\partial x} \frac{dx}{dx} + \frac{\partial f}{\partial y} \frac{dy}{dx} + \frac{\partial f}{\partial y'} \frac{dy'}{dx} \quad (1)$$

$$= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} y'' \quad (834)$$

$$= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} f \quad (835)$$

$$\begin{aligned} \frac{d^2 f}{dx^2} &= \frac{d}{dx} \left(\frac{df}{dx} \right) \\ &= \frac{\partial}{\partial x} \left(\frac{df}{dx} \right) + \frac{\partial}{\partial y} \left(\frac{df}{dx} \right) y' + \frac{\partial}{\partial y'} \left(\frac{df}{dx} \right) f \end{aligned} \quad (2)$$

$$\begin{aligned} \frac{d^3 f}{dx^3} &= \frac{d}{dx} \left(\frac{d^2 f}{dx^2} \right) \\ &= \frac{\partial}{\partial x} \left(\frac{d^2 f}{dx^2} \right) + \left(\frac{\partial}{\partial y} \frac{d^2 f}{dx^2} \right) y' + \frac{\partial}{\partial y'} \left(\frac{d^2 f}{dx^2} \right) f \end{aligned} \quad (3)$$

⋮

And so on. Hence if we name $F_0 = f(x, y, y')$ then the above can be written as

$$F_0 = f(x, y, y') \quad (4)$$

$$\begin{aligned} F_1 &= \frac{df}{dx} \\ &= \frac{dF_0}{dx} \\ &= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} y'' \\ &= \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} y' + \frac{\partial f}{\partial y'} f \\ &= \frac{\partial F_0}{\partial x} + \frac{\partial F_0}{\partial y} y' + \frac{\partial F_0}{\partial y'} F_0 \end{aligned} \quad (5)$$

$$\begin{aligned} F_2 &= \frac{d}{dx} \left(\frac{d}{dx} f \right) \\ &= \frac{d}{dx} (F_1) \\ &= \frac{\partial}{\partial x} F_1 + \left(\frac{\partial F_1}{\partial y} \right) y' + \left(\frac{\partial F_1}{\partial y'} \right) y'' \\ &= \frac{\partial}{\partial x} F_1 + \left(\frac{\partial F_1}{\partial y} \right) y' + \left(\frac{\partial F_1}{\partial y'} \right) F_0 \end{aligned}$$

⋮

$$\begin{aligned} F_n &= \frac{d}{dx} (F_{n-1}) \\ &= \frac{\partial}{\partial x} F_{n-1} + \left(\frac{\partial F_{n-1}}{\partial y} \right) y' + \left(\frac{\partial F_{n-1}}{\partial y'} \right) y'' \\ &= \frac{\partial}{\partial x} F_{n-1} + \left(\frac{\partial F_{n-1}}{\partial y} \right) y' + \left(\frac{\partial F_{n-1}}{\partial y'} \right) F_0 \end{aligned} \quad (6)$$

Therefore (6) can be used from now on along with

$$y(x) = y_0 + xy'_0 + \sum_{n=0}^{\infty} \frac{x^{n+2}}{(n+2)!} F_n|_{x_0, y_0, y'_0} \quad (7)$$

To find $y(x)$ series solution around $x = 0$. Hence

$$F_0 = \frac{yn^2 + yn - 2y'x}{x^2 - 1}$$

$$\begin{aligned} F_1 &= \frac{dF_0}{dx} \\ &= \frac{\partial F_0}{\partial x} + \frac{\partial F_0}{\partial y}y' + \frac{\partial F_0}{\partial y'}F_0 \\ &= \frac{(n^2x^2 + nx^2 - n^2 + 6x^2 - n + 2)y' - 4ynx(n+1)}{(x^2 - 1)^2} \end{aligned}$$

$$\begin{aligned} F_2 &= \frac{dF_1}{dx} \\ &= \frac{\partial F_1}{\partial x} + \frac{\partial F_1}{\partial y}y' + \frac{\partial F_1}{\partial y'}F_1 \\ &= \frac{(x-1)(-8((n^2+n+3)x^2 - n^2 - n + 3)xy' + yn(n+1)((n^2+n+18)x^2 - n^2 - n + 6))(x+1)}{(x^2 - 1)^4} \end{aligned}$$

$$\begin{aligned} F_3 &= \frac{dF_2}{dx} \\ &= \frac{\partial F_2}{\partial x} + \frac{\partial F_2}{\partial y}y' + \frac{\partial F_2}{\partial y'}F_2 \\ &= \frac{(((n^4 + 2n^3 + 59n^2 + 58n + 120)x^4 + (-2n^4 - 4n^3 - 46n^2 - 44n + 240)x^2 + n^4 + 2n^3 - 13n^2 - 14n)x + 1)}{(x^2 - 1)^5} \end{aligned}$$

$$\begin{aligned} F_4 &= \frac{dF_3}{dx} \\ &= \frac{\partial F_3}{\partial x} + \frac{\partial F_3}{\partial y}y' + \frac{\partial F_3}{\partial y'}F_3 \\ &= \frac{(-18((n^4 + 2n^3 + \frac{77}{3}n^2 + \frac{74}{3}n + 40)x^4 - 2(n^2 + n + 10)(n^2 + n - \frac{20}{3})x^2 + n^4 + 2n^3 - 17n^2 - 18n)x + 1)}{(x^2 - 1)^6} \end{aligned}$$

And so on. Evaluating all the above at initial conditions $x = 0$ and $y(0) = y(0)$ and $y'(0) = y'(0)$ gives

$$F_0 = -y(0)n(n+1)$$

$$F_1 = -y'(0)n^2 - y'(0)n + 2y'(0)$$

$$F_2 = y(0)n^4 + 2y(0)n^3 - 5y(0)n^2 - 6y(0)n$$

$$F_3 = y'(0)n^4 + 2y'(0)n^3 - 13y'(0)n^2 - 14y'(0)n + 24y'(0)$$

$$F_4 = -y(0)n^6 - 3y(0)n^5 + 23y(0)n^4 + 51y(0)n^3 - 94y(0)n^2 - 120y(0)n$$

Substituting all the above in (7) and simplifying gives the solution as

$$\begin{aligned}
 y = & \left(1 - \frac{1}{2}n^2x^2 - \frac{1}{2}nx^2 + \frac{1}{24}n^4x^4 + \frac{1}{12}x^4n^3 - \frac{5}{24}n^2x^4 - \frac{1}{4}nx^4 - \frac{1}{720}x^6n^6 - \frac{1}{240}n^5x^6 \right. \\
 & \left. + \frac{23}{720}n^4x^6 + \frac{17}{240}n^3x^6 - \frac{47}{360}n^2x^6 - \frac{1}{6}x^6n \right) y(0) \\
 & + \left(x - \frac{1}{6}n^2x^3 - \frac{1}{6}nx^3 + \frac{1}{3}x^3 + \frac{1}{120}x^5n^4 + \frac{1}{60}x^5n^3 - \frac{13}{120}x^5n^2 - \frac{7}{60}x^5n + \frac{1}{5}x^5 \right) y'(0) \\
 & + O(x^6)
 \end{aligned}$$

Since the expansion point $x = 0$ is an ordinary, we can also solve this using standard power series The ode is normalized to be

$$(-x^2 + 1)y'' - 2y'x + (n^2 + n)y = 0$$

Let the solution be represented as power series of the form

$$y = \sum_{n=0}^{\infty} a_n x^n$$

Then

$$\begin{aligned}
 y' &= \sum_{n=1}^{\infty} n a_n x^{n-1} \\
 y'' &= \sum_{n=2}^{\infty} n(n-1) a_n x^{n-2}
 \end{aligned}$$

Substituting the above back into the ode gives

$$(-x^2 + 1) \left(\sum_{n=2}^{\infty} n(n-1) a_n x^{n-2} \right) - 2 \left(\sum_{n=1}^{\infty} n a_n x^{n-1} \right) x + (n^2 + n) \left(\sum_{n=0}^{\infty} a_n x^n \right) = 0 \quad (1)$$

Which simplifies to

$$\begin{aligned}
 & \sum_{n=2}^{\infty} (-x^n a_n n(n-1)) + \left(\sum_{n=2}^{\infty} n(n-1) a_n x^{n-2} \right) \\
 & + \sum_{n=1}^{\infty} (-2n a_n x^n) + \left(\sum_{n=0}^{\infty} (n^2 + n) a_n x^n \right) = 0
 \end{aligned} \quad (2)$$

The next step is to make all powers of x be n in each summation term. Going over each summation term above with power of x in it which is not already x^n and adjusting the power and the corresponding index gives

$$\sum_{n=2}^{\infty} n(n-1) a_n x^{n-2} = \sum_{n=0}^{\infty} (n+2) a_{n+2} (n+1) x^n$$

Substituting all the above in Eq (2) gives the following equation where now all powers of x are the same and equal to n .

$$\begin{aligned} \sum_{n=2}^{\infty} (-x^n a_n n(n-1)) + \left(\sum_{n=0}^{\infty} (n+2) a_{n+2} (n+1) x^n \right) \\ + \sum_{n=1}^{\infty} (-2n a_n x^n) + \left(\sum_{n=0}^{\infty} (n^2 + n) a_n x^n \right) = 0 \end{aligned} \quad (3)$$

$n = 0$ gives

$$2a_2 + a_0 n(n+1) = 0$$

$$a_2 = -\frac{1}{2} a_0 n^2 - \frac{1}{2} a_0 n$$

$n = 1$ gives

$$6a_3 - 2a_1 + a_1 n(n+1) = 0$$

Which after substituting earlier equations, simplifies to

$$a_3 = -\frac{1}{6} a_1 n^2 - \frac{1}{6} a_1 n + \frac{1}{3} a_1$$

For $2 \leq n$, the recurrence equation is

$$-n a_n (n-1) + (n+2) a_{n+2} (n+1) - 2n a_n + a_n n(n+1) = 0 \quad (4)$$

Solving for a_{n+2} , gives

$$a_{n+2} = -\frac{a_n (n^2 - n^2 + n - n)}{(n+2)(n+1)} \quad (5)$$

For $n = 2$ the recurrence equation gives

$$-6a_2 + 12a_4 + a_2n(n + 1) = 0$$

Which after substituting the earlier terms found becomes

$$a_4 = -\frac{5}{24}a_0n^2 - \frac{1}{4}a_0n + \frac{1}{24}a_0n^4 + \frac{1}{12}a_0n^3$$

For $n = 3$ the recurrence equation gives

$$-12a_3 + 20a_5 + a_3n(n + 1) = 0$$

Which after substituting the earlier terms found becomes

$$a_5 = -\frac{13}{120}a_1n^2 - \frac{7}{60}a_1n + \frac{1}{5}a_1 + \frac{1}{120}a_1n^4 + \frac{1}{60}a_1n^3$$

For $n = 4$ the recurrence equation gives

$$-20a_4 + 30a_6 + a_4n(n + 1) = 0$$

Which after substituting the earlier terms found becomes

$$a_6 = -\frac{47}{360}a_0n^2 - \frac{1}{6}a_0n + \frac{23}{720}a_0n^4 + \frac{17}{240}a_0n^3 - \frac{1}{720}a_0n^6 - \frac{1}{240}a_0n^5$$

For $n = 5$ the recurrence equation gives

$$-30a_5 + 42a_7 + a_5n(n + 1) = 0$$

Which after substituting the earlier terms found becomes

$$a_7 = -\frac{5}{63}a_1n^2 - \frac{37}{420}a_1n + \frac{1}{7}a_1 + \frac{41}{5040}a_1n^4 + \frac{29}{1680}a_1n^3 - \frac{1}{5040}a_1n^6 - \frac{1}{1680}a_1n^5$$

And so on. Therefore the solution is

$$\begin{aligned} y &= \sum_{n=0}^{\infty} a_n x^n \\ &= a_3 x^3 + a_2 x^2 + a_1 x + a_0 + \dots \end{aligned}$$

Substituting the values for a_n found above, the solution becomes

$$\begin{aligned}
 y = & a_0 + a_1x + \left(-\frac{1}{2}a_0n^2 - \frac{1}{2}a_0n\right)x^2 + \left(-\frac{1}{6}a_1n^2 - \frac{1}{6}a_1n + \frac{1}{3}a_1\right)x^3 \\
 & + \left(-\frac{5}{24}a_0n^2 - \frac{1}{4}a_0n + \frac{1}{24}a_0n^4 + \frac{1}{12}a_0n^3\right)x^4 \\
 & + \left(-\frac{13}{120}a_1n^2 - \frac{7}{60}a_1n + \frac{1}{5}a_1 + \frac{1}{120}a_1n^4 + \frac{1}{60}a_1n^3\right)x^5 + \dots
 \end{aligned}$$

Collecting terms, the solution becomes

$$\begin{aligned}
 y = & \left(1 + \left(-\frac{1}{2}n^2 - \frac{1}{2}n\right)x^2 + \left(-\frac{5}{24}n^2 - \frac{1}{4}n + \frac{1}{24}n^4 + \frac{1}{12}n^3\right)x^4\right)a_0 \\
 & + \left(x + \left(-\frac{1}{6}n^2 - \frac{1}{6}n + \frac{1}{3}\right)x^3 + \left(-\frac{13}{120}n^2 - \frac{7}{60}n + \frac{1}{5} + \frac{1}{120}n^4 + \frac{1}{60}n^3\right)x^5\right)a_1 + O(x^6)
 \end{aligned} \tag{3}$$

At $x = 0$ the solution above becomes

$$\begin{aligned}
 y = & \left(1 + \left(-\frac{1}{2}n^2 - \frac{1}{2}n\right)x^2 + \left(-\frac{5}{24}n^2 - \frac{1}{4}n + \frac{1}{24}n^4 + \frac{1}{12}n^3\right)x^4\right)c_1 \\
 & + \left(x + \left(-\frac{1}{6}n^2 - \frac{1}{6}n + \frac{1}{3}\right)x^3 + \left(-\frac{13}{120}n^2 - \frac{7}{60}n + \frac{1}{5} + \frac{1}{120}n^4 + \frac{1}{60}n^3\right)x^5\right)c_2 + O(x^6)
 \end{aligned}$$

Summary

The solution(s) found are the following

$$\begin{aligned}
 y = & \left(1 - \frac{1}{2}n^2x^2 - \frac{1}{2}nx^2 + \frac{1}{24}n^4x^4 + \frac{1}{12}x^4n^3 - \frac{5}{24}n^2x^4 - \frac{1}{4}nx^4 - \frac{1}{720}x^6n^6 - \frac{1}{240}n^5x^6\right. \\
 & + \left.\frac{23}{720}n^4x^6 + \frac{17}{240}n^3x^6 - \frac{47}{360}n^2x^6 - \frac{1}{6}x^6n\right)y(0) + \left(x - \frac{1}{6}n^2x^3 - \frac{1}{6}nx^3 + \frac{1}{3}\right. \\
 & \left. + \frac{1}{120}x^5n^4 + \frac{1}{60}x^5n^3 - \frac{13}{120}x^5n^2 - \frac{7}{60}x^5n + \frac{1}{5}x^5\right)y'(0) + O(x^6)
 \end{aligned}$$

$$\begin{aligned}
 y = & \left(1 + \left(-\frac{1}{2}n^2 - \frac{1}{2}n\right)x^2 + \left(-\frac{5}{24}n^2 - \frac{1}{4}n + \frac{1}{24}n^4 + \frac{1}{12}n^3\right)x^4\right)c_1 \\
 & + \left(x + \left(-\frac{1}{6}n^2 - \frac{1}{6}n + \frac{1}{3}\right)x^3 + \left(-\frac{13}{120}n^2 - \frac{7}{60}n + \frac{1}{5} + \frac{1}{120}n^4 + \frac{1}{60}n^3\right)x^5\right)c_2 \\
 & + O(x^6)
 \end{aligned}$$

Verification of solutions

$$y = \left(1 - \frac{1}{2}n^2x^2 - \frac{1}{2}nx^2 + \frac{1}{24}n^4x^4 + \frac{1}{12}x^4n^3 - \frac{5}{24}n^2x^4 - \frac{1}{4}nx^4 - \frac{1}{720}x^6n^6 - \frac{1}{240}n^5x^6 \right. \\ \left. + \frac{23}{720}n^4x^6 + \frac{17}{240}n^3x^6 - \frac{47}{360}n^2x^6 - \frac{1}{6}x^6n \right) y(0) \\ + \left(x - \frac{1}{6}n^2x^3 - \frac{1}{6}nx^3 + \frac{1}{3}x^3 + \frac{1}{120}x^5n^4 + \frac{1}{60}x^5n^3 - \frac{13}{120}x^5n^2 - \frac{7}{60}x^5n + \frac{1}{5}x^5 \right) y'(0) \\ + O(x^6)$$

Verified OK.

$$y = \left(1 + \left(-\frac{1}{2}n^2 - \frac{1}{2}n \right) x^2 + \left(-\frac{5}{24}n^2 - \frac{1}{4}n + \frac{1}{24}n^4 + \frac{1}{12}n^3 \right) x^4 \right) c_1 \\ + \left(x + \left(-\frac{1}{6}n^2 - \frac{1}{6}n + \frac{1}{3} \right) x^3 + \left(-\frac{13}{120}n^2 - \frac{7}{60}n + \frac{1}{5} + \frac{1}{120}n^4 + \frac{1}{60}n^3 \right) x^5 \right) c_2 + O(x^6)$$

Verified OK.

14.18.1 Maple step by step solution

Let's solve

$$(-x^2 + 1)y'' - 2y'x + (n^2 + n)y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = \frac{n(n+1)y}{x^2-1} - \frac{2xy'}{x^2-1}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + \frac{2xy'}{x^2-1} - \frac{n(n+1)y}{x^2-1} = 0$$

- Check to see if x_0 is a regular singular point

- Define functions

$$\left[P_2(x) = \frac{2x}{x^2-1}, P_3(x) = -\frac{n(n+1)}{x^2-1} \right]$$

- $(x+1) \cdot P_2(x)$ is analytic at $x = -1$

$$\left. ((x+1) \cdot P_2(x)) \right|_{x=-1} = 1$$

- $(x+1)^2 \cdot P_3(x)$ is analytic at $x = -1$

$$\left. ((x+1)^2 \cdot P_3(x)) \right|_{x=-1} = 0$$

- $x = -1$ is a regular singular point

Check to see if x_0 is a regular singular point

$$x_0 = -1$$

- Multiply by denominators

$$y''(x^2 - 1) + 2y'x - n(n+1)y = 0$$

- Change variables using $x = u - 1$ so that the regular singular point is at $u = 0$

$$(u^2 - 2u) \left(\frac{d^2}{du^2} y(u) \right) + (2u - 2) \left(\frac{d}{du} y(u) \right) + (-n^2 - n) y(u) = 0$$

- Assume series solution for $y(u)$

$$y(u) = \sum_{k=0}^{\infty} a_k u^{k+r}$$

- Rewrite ODE with series expansions

- Convert $u^m \cdot \left(\frac{d}{du} y(u) \right)$ to series expansion for $m = 0.1$

$$u^m \cdot \left(\frac{d}{du} y(u) \right) = \sum_{k=0}^{\infty} a_k (k+r) u^{k+r-1+m}$$

- Shift index using $k \rightarrow k+1-m$

$$u^m \cdot \left(\frac{d}{du} y(u) \right) = \sum_{k=-1+m}^{\infty} a_{k+1-m} (k+1-m+r) u^{k+r}$$

- Convert $u^m \cdot \left(\frac{d^2}{du^2} y(u) \right)$ to series expansion for $m = 1.2$

$$u^m \cdot \left(\frac{d^2}{du^2} y(u) \right) = \sum_{k=0}^{\infty} a_k (k+r)(k+r-1) u^{k+r-2+m}$$

- Shift index using $k \rightarrow k+2-m$

$$u^m \cdot \left(\frac{d^2}{du^2} y(u) \right) = \sum_{k=-2+m}^{\infty} a_{k+2-m} (k+2-m+r)(k+1-m+r) u^{k+r}$$

Rewrite ODE with series expansions

$$-2a_0 r^2 u^{-1+r} + \left(\sum_{k=0}^{\infty} (-2a_{k+1} (k+1+r)^2 + a_k (r+1+n+k)(r-n+k)) u^{k+r} \right) = 0$$

- a_0 cannot be 0 by assumption, giving the indicial equation

$$-2r^2 = 0$$

- Values of r that satisfy the indicial equation

$$r = 0$$

- Each term in the series must be 0, giving the recursion relation

$$-2a_{k+1}(k+1)^2 + a_k(1+n+k)(-n+k) = 0$$

- Recursion relation that defines series solution to ODE

$$a_{k+1} = \frac{a_k(1+n+k)(-n+k)}{2(k+1)^2}$$

- Recursion relation for $r = 0$

$$a_{k+1} = \frac{a_k(1+n+k)(-n+k)}{2(k+1)^2}$$

- Solution for $r = 0$

$$\left[y(u) = \sum_{k=0}^{\infty} a_k u^k, a_{k+1} = \frac{a_k(1+n+k)(-n+k)}{2(k+1)^2} \right]$$

- Revert the change of variables $u = x + 1$

$$\left[y = \sum_{k=0}^{\infty} a_k (x+1)^k, a_{k+1} = \frac{a_k(1+n+k)(-n+k)}{2(k+1)^2} \right]$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
trying a symmetry of the form [xi=0, eta=F(x)]
checking if the LODE is missing y
-> Trying a Liouvillian solution using Kovacic's algorithm
<- No Liouvillian solutions exist
-> Trying a solution in terms of special functions:
    -> Bessel
    -> elliptic
    -> Legendre
    <- Legendre successful
<- special function solution successful`

```

✓ Solution by Maple

Time used: 0.0 (sec). Leaf size: 101

Order:=6;

```
dsolve((1-x^2)*diff(y(x),x$2)-2*x*diff(y(x),x)+n*(n+1)*y(x)=0,y(x),type='series',x=0);
```

$$y(x) = \left(1 - \frac{n(n+1)x^2}{2} + \frac{n(n^3 + 2n^2 - 5n - 6)x^4}{24}\right) y(0) \\ + \left(x - \frac{(n^2 + n - 2)x^3}{6} + \frac{(n^4 + 2n^3 - 13n^2 - 14n + 24)x^5}{120}\right) D(y)(0) + O(x^6)$$

✓ Solution by Mathematica

Time used: 0.001 (sec). Leaf size: 120

```
AsymptoticDSolveValue[(1-x^2)*y'[x]-2*x*y'[x]+n*(n+1)*y[x]==0,y[x],{x,0,5}]
```

$$y(x) \rightarrow c_2 \left(\frac{1}{120} (n^2 + n)^2 x^5 + \frac{7}{60} (-n^2 - n) x^5 + \frac{1}{6} (-n^2 - n) x^3 + \frac{x^5}{5} + \frac{x^3}{3} + x \right) \\ + c_1 \left(\frac{1}{24} (n^2 + n)^2 x^4 + \frac{1}{4} (-n^2 - n) x^4 + \frac{1}{2} (-n^2 - n) x^2 + 1 \right)$$

15 Chapter 6, Series solutions of linear differential equations. Section 6.2 (Frobenius). Exercises
page 251

15.1 problem 1	4028
15.2 problem 2	4043
15.3 problem 3	4058
15.4 problem 4	4064
15.5 problem 5	4070
15.6 problem 6	4082
15.7 problem 7	4094
15.8 problem 8	4107
15.9 problem 9	4120
15.10 problem 10	4133
15.11 problem 11	4146
15.12 problem 12	4160
15.13 problem 13	4173
15.14 problem 14	4186
15.15 problem 15	4199
15.16 problem 16	4212
15.17 problem 17	4226
15.18 problem 18	4241
15.19 problem 19	4253
15.20 problem 20	4269
15.21 problem 21	4284
15.22 problem 22	4300
15.23 problem 23	4316
15.24 problem 24	4327
15.25 problem 25	4343
15.26 problem 26	4354

15.1 problem 1

15.1.1 Maple step by step solution 4039

Internal problem ID [11902]

Internal file name [OUTPUT/11911_Saturday_April_13_2024_01_14_37_AM_31651573/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.2 (Frobenius). Exercises page 251

Problem number: 1.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"second order series method. Regular singular point. Difference not integer"**

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$(x^2 - 3x)y'' + (x + 2)y' + y = 0$$

With the expansion point for the power series method at $x = 0$.

The type of the expansion point is first determined. This is done on the homogeneous part of the ODE.

$$(x^2 - 3x)y'' + (x + 2)y' + y = 0$$

The following is summary of singularities for the above ode. Writing the ode as

$$y'' + p(x)y' + q(x)y = 0$$

Where

$$p(x) = \frac{x + 2}{x(x - 3)}$$
$$q(x) = \frac{1}{x(x - 3)}$$

Table 527: Table $p(x), q(x)$ singularities.

$p(x) = \frac{x+2}{x(x-3)}$		$q(x) = \frac{1}{x(x-3)}$	
singularity	type	singularity	type
$x = 0$	“regular”	$x = 0$	“regular”
$x = 3$	“regular”	$x = 3$	“regular”

Combining everything together gives the following summary of singularities for the ode as

Regular singular points : $[0, 3, \infty]$

Irregular singular points : $[\]$

Since $x = 0$ is regular singular point, then Frobenius power series is used. The ode is normalized to be

$$y''x(x-3) + (x+2)y' + y = 0$$

Let the solution be represented as Frobenius power series of the form

$$y = \sum_{n=0}^{\infty} a_n x^{n+r}$$

Then

$$y' = \sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1}$$

$$y'' = \sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2}$$

Substituting the above back into the ode gives

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2} \right) x(x-3) \\ & + (x+2) \left(\sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1} \right) + \left(\sum_{n=0}^{\infty} a_n x^{n+r} \right) = 0 \end{aligned} \tag{1}$$

Which simplifies to

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} x^{n+r} a_n (n+r) (n+r-1) \right) + \sum_{n=0}^{\infty} (-3x^{n+r-1} a_n (n+r) (n+r-1)) \\ & + \left(\sum_{n=0}^{\infty} x^{n+r} a_n (n+r) \right) + \left(\sum_{n=0}^{\infty} 2(n+r) a_n x^{n+r-1} \right) + \left(\sum_{n=0}^{\infty} a_n x^{n+r} \right) = 0 \end{aligned} \quad (2A)$$

The next step is to make all powers of x be $n+r-1$ in each summation term. Going over each summation term above with power of x in it which is not already x^{n+r-1} and adjusting the power and the corresponding index gives

$$\begin{aligned} \sum_{n=0}^{\infty} x^{n+r} a_n (n+r) (n+r-1) &= \sum_{n=1}^{\infty} a_{n-1} (n+r-1) (n+r-2) x^{n+r-1} \\ \sum_{n=0}^{\infty} x^{n+r} a_n (n+r) &= \sum_{n=1}^{\infty} a_{n-1} (n+r-1) x^{n+r-1} \\ \sum_{n=0}^{\infty} a_n x^{n+r} &= \sum_{n=1}^{\infty} a_{n-1} x^{n+r-1} \end{aligned}$$

Substituting all the above in Eq (2A) gives the following equation where now all powers of x are the same and equal to $n+r-1$.

$$\begin{aligned} & \left(\sum_{n=1}^{\infty} a_{n-1} (n+r-1) (n+r-2) x^{n+r-1} \right) \\ & + \sum_{n=0}^{\infty} (-3x^{n+r-1} a_n (n+r) (n+r-1)) + \left(\sum_{n=1}^{\infty} a_{n-1} (n+r-1) x^{n+r-1} \right) \\ & + \left(\sum_{n=0}^{\infty} 2(n+r) a_n x^{n+r-1} \right) + \left(\sum_{n=1}^{\infty} a_{n-1} x^{n+r-1} \right) = 0 \end{aligned} \quad (2B)$$

The indicial equation is obtained from $n=0$. From Eq (2B) this gives

$$-3x^{n+r-1} a_n (n+r) (n+r-1) + 2(n+r) a_n x^{n+r-1} = 0$$

When $n=0$ the above becomes

$$-3x^{-1+r} a_0 r (-1+r) + 2r a_0 x^{-1+r} = 0$$

Or

$$(-3x^{-1+r}r(-1+r) + 2rx^{-1+r})a_0 = 0$$

Since $a_0 \neq 0$ then the above simplifies to

$$(-3r^2 + 5r)x^{-1+r} = 0$$

Since the above is true for all x then the indicial equation becomes

$$-3r^2 + 5r = 0$$

Solving for r gives the roots of the indicial equation as

$$r_1 = \frac{5}{3}$$
$$r_2 = 0$$

Since $a_0 \neq 0$ then the indicial equation becomes

$$(-3r^2 + 5r)x^{-1+r} = 0$$

Solving for r gives the roots of the indicial equation as Since $r_1 - r_2 = \frac{5}{3}$ is not an integer, then we can construct two linearly independent solutions

$$y_1(x) = x^{r_1} \left(\sum_{n=0}^{\infty} a_n x^n \right)$$
$$y_2(x) = x^{r_2} \left(\sum_{n=0}^{\infty} b_n x^n \right)$$

Or

$$y_1(x) = \sum_{n=0}^{\infty} a_n x^{n+\frac{5}{3}}$$
$$y_2(x) = \sum_{n=0}^{\infty} b_n x^n$$

We start by finding $y_1(x)$. Eq (2B) derived above is now used to find all a_n coefficients. The case $n = 0$ is skipped since it was used to find the roots of the indicial equation. a_0 is arbitrary and taken as $a_0 = 1$. For $1 \leq n$ the recursive equation is

$$a_{n-1}(n+r-1)(n+r-2) - 3a_n(n+r)(n+r-1) + a_{n-1}(n+r-1) + 2a_n(n+r) + a_{n-1} = 0 \quad (3)$$

Solving for a_n from recursive equation (4) gives

$$a_n = \frac{a_{n-1}(n^2 + 2nr + r^2 - 2n - 2r + 2)}{3n^2 + 6nr + 3r^2 - 5n - 5r} \quad (4)$$

Which for the root $r = \frac{5}{3}$ becomes

$$a_n = \frac{a_{n-1}(9n^2 + 12n + 13)}{27n^2 + 45n} \quad (5)$$

At this point, it is a good idea to keep track of a_n in a table both before substituting $r = \frac{5}{3}$ and after as more terms are found using the above recursive equation.

n	$a_{n,r}$	a_n
a_0	1	1

For $n = 1$, using the above recursive equation gives

$$a_1 = \frac{r^2 + 1}{3r^2 + r - 2}$$

Which for the root $r = \frac{5}{3}$ becomes

$$a_1 = \frac{17}{36}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$\frac{r^2+1}{3r^2+r-2}$	$\frac{17}{36}$

For $n = 2$, using the above recursive equation gives

$$a_2 = \frac{(r^2 + 1)(r^2 + 2r + 2)}{9r^4 + 24r^3 + 7r^2 - 12r - 4}$$

Which for the root $r = \frac{5}{3}$ becomes

$$a_2 = \frac{1241}{7128}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$\frac{r^2+1}{3r^2+r-2}$	$\frac{17}{36}$
a_2	$\frac{(r^2+1)(r^2+2r+2)}{9r^4+24r^3+7r^2-12r-4}$	$\frac{1241}{7128}$

For $n = 3$, using the above recursive equation gives

$$a_3 = \frac{(r^2 + 1)(r^2 + 2r + 2)(r^2 + 4r + 5)}{27r^6 + 189r^5 + 441r^4 + 343r^3 - 84r^2 - 196r - 48}$$

Which for the root $r = \frac{5}{3}$ becomes

$$a_3 = \frac{80665}{1347192}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$\frac{r^2+1}{3r^2+r-2}$	$\frac{17}{36}$
a_2	$\frac{(r^2+1)(r^2+2r+2)}{9r^4+24r^3+7r^2-12r-4}$	$\frac{1241}{7128}$
a_3	$\frac{(r^2+1)(r^2+2r+2)(r^2+4r+5)}{27r^6+189r^5+441r^4+343r^3-84r^2-196r-48}$	$\frac{80665}{1347192}$

For $n = 4$, using the above recursive equation gives

$$a_4 = \frac{(r^2 + 1)(r^2 + 2r + 2)(r^2 + 4r + 5)(r^2 + 6r + 10)}{81r^8 + 1080r^7 + 5670r^6 + 14700r^5 + 18613r^4 + 7420r^3 - 6220r^2 - 6400r - 1344}$$

Which for the root $r = \frac{5}{3}$ becomes

$$a_4 = \frac{972725}{48498912}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$\frac{r^2+1}{3r^2+r-2}$	$\frac{17}{36}$
a_2	$\frac{(r^2+1)(r^2+2r+2)}{9r^4+24r^3+7r^2-12r-4}$	$\frac{1241}{7128}$
a_3	$\frac{(r^2+1)(r^2+2r+2)(r^2+4r+5)}{27r^6+189r^5+441r^4+343r^3-84r^2-196r-48}$	$\frac{80665}{1347192}$
a_4	$\frac{(r^2+1)(r^2+2r+2)(r^2+4r+5)(r^2+6r+10)}{81r^8+1080r^7+5670r^6+14700r^5+18613r^4+7420r^3-6220r^2-6400r-1344}$	$\frac{972725}{48498912}$

For $n = 5$, using the above recursive equation gives

$$a_5 = \frac{(r^2 + 1)(r^2 + 2r + 2)(r^2 + 4r + 5)(r^2 + 6r + 10)(r^2 + 8r + 17)}{(81r^8 + 1080r^7 + 5670r^6 + 14700r^5 + 18613r^4 + 7420r^3 - 6220r^2 - 6400r - 1344)(3r^2 + 25r + 50)}$$

Which for the root $r = \frac{5}{3}$ becomes

$$a_5 = \frac{5797441}{872980416}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$\frac{r^2+1}{3r^2+r-2}$	$\frac{17}{36}$
a_2	$\frac{(r^2+1)(r^2+2r+2)}{9r^4+24r^3+7r^2-12r-4}$	$\frac{1241}{7128}$
a_3	$\frac{(r^2+1)(r^2+2r+2)(r^2+4r+5)}{27r^6+189r^5+441r^4+343r^3-84r^2-196r-48}$	$\frac{80665}{1347192}$
a_4	$\frac{(r^2+1)(r^2+2r+2)(r^2+4r+5)(r^2+6r+10)}{81r^8+1080r^7+5670r^6+14700r^5+18613r^4+7420r^3-6220r^2-6400r-1344}$	$\frac{972725}{48498912}$
a_5	$\frac{(r^2+1)(r^2+2r+2)(r^2+4r+5)(r^2+6r+10)(r^2+8r+17)}{(81r^8+1080r^7+5670r^6+14700r^5+18613r^4+7420r^3-6220r^2-6400r-1344)(3r^2+25r+50)}$	$\frac{5797441}{872980416}$

Using the above table, then the solution $y_1(x)$ is

$$\begin{aligned} y_1(x) &= x^{\frac{5}{3}}(a_0 + a_1x + a_2x^2 + a_3x^3 + a_4x^4 + a_5x^5 + a_6x^6 \dots) \\ &= x^{\frac{5}{3}} \left(1 + \frac{17x}{36} + \frac{1241x^2}{7128} + \frac{80665x^3}{1347192} + \frac{972725x^4}{48498912} + \frac{5797441x^5}{872980416} + O(x^6) \right) \end{aligned}$$

Now the second solution $y_2(x)$ is found. Eq (2B) derived above is now used to find all b_n coefficients. The case $n = 0$ is skipped since it was used to find the roots of the

indicial equation. b_0 is arbitrary and taken as $b_0 = 1$. For $1 \leq n$ the recursive equation is

$$b_{n-1}(n+r-1)(n+r-2) - 3b_n(n+r)(n+r-1) + b_{n-1}(n+r-1) + 2(n+r)b_n + b_{n-1} = 0 \quad (3)$$

Solving for b_n from recursive equation (4) gives

$$b_n = \frac{b_{n-1}(n^2 + 2nr + r^2 - 2n - 2r + 2)}{3n^2 + 6nr + 3r^2 - 5n - 5r} \quad (4)$$

Which for the root $r = 0$ becomes

$$b_n = \frac{b_{n-1}(n^2 - 2n + 2)}{n(3n - 5)} \quad (5)$$

At this point, it is a good idea to keep track of b_n in a table both before substituting $r = 0$ and after as more terms are found using the above recursive equation.

n	$b_{n,r}$	b_n
b_0	1	1

For $n = 1$, using the above recursive equation gives

$$b_1 = \frac{r^2 + 1}{3r^2 + r - 2}$$

Which for the root $r = 0$ becomes

$$b_1 = -\frac{1}{2}$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	$\frac{r^2+1}{3r^2+r-2}$	$-\frac{1}{2}$

For $n = 2$, using the above recursive equation gives

$$b_2 = \frac{(r^2 + 1)(r^2 + 2r + 2)}{9r^4 + 24r^3 + 7r^2 - 12r - 4}$$

Which for the root $r = 0$ becomes

$$b_2 = -\frac{1}{2}$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	$\frac{r^2+1}{3r^2+r-2}$	$-\frac{1}{2}$
b_2	$\frac{(r^2+1)(r^2+2r+2)}{9r^4+24r^3+7r^2-12r-4}$	$-\frac{1}{2}$

For $n = 3$, using the above recursive equation gives

$$b_3 = \frac{(r^2 + 1)(r^2 + 2r + 2)(r^2 + 4r + 5)}{27r^6 + 189r^5 + 441r^4 + 343r^3 - 84r^2 - 196r - 48}$$

Which for the root $r = 0$ becomes

$$b_3 = -\frac{5}{24}$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	$\frac{r^2+1}{3r^2+r-2}$	$-\frac{1}{2}$
b_2	$\frac{(r^2+1)(r^2+2r+2)}{9r^4+24r^3+7r^2-12r-4}$	$-\frac{1}{2}$
b_3	$\frac{(r^2+1)(r^2+2r+2)(r^2+4r+5)}{27r^6+189r^5+441r^4+343r^3-84r^2-196r-48}$	$-\frac{5}{24}$

For $n = 4$, using the above recursive equation gives

$$b_4 = \frac{(r^2 + 1)(r^2 + 2r + 2)(r^2 + 4r + 5)(r^2 + 6r + 10)}{81r^8 + 1080r^7 + 5670r^6 + 14700r^5 + 18613r^4 + 7420r^3 - 6220r^2 - 6400r - 1344}$$

Which for the root $r = 0$ becomes

$$b_4 = -\frac{25}{336}$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	$\frac{r^2+1}{3r^2+r-2}$	$-\frac{1}{2}$
b_2	$\frac{(r^2+1)(r^2+2r+2)}{9r^4+24r^3+7r^2-12r-4}$	$-\frac{1}{2}$
b_3	$\frac{(r^2+1)(r^2+2r+2)(r^2+4r+5)}{27r^6+189r^5+441r^4+343r^3-84r^2-196r-48}$	$-\frac{5}{24}$
b_4	$\frac{(r^2+1)(r^2+2r+2)(r^2+4r+5)(r^2+6r+10)}{81r^8+1080r^7+5670r^6+14700r^5+18613r^4+7420r^3-6220r^2-6400r-1344}$	$-\frac{25}{336}$

For $n = 5$, using the above recursive equation gives

$$b_5 = \frac{(r^2 + 1)(r^2 + 2r + 2)(r^2 + 4r + 5)(r^2 + 6r + 10)(r^2 + 8r + 17)}{(81r^8 + 1080r^7 + 5670r^6 + 14700r^5 + 18613r^4 + 7420r^3 - 6220r^2 - 6400r - 1344)(3r^2 + 25r + 50)}$$

Which for the root $r = 0$ becomes

$$b_5 = -\frac{17}{672}$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	$\frac{r^2+1}{3r^2+r-2}$	$-\frac{1}{2}$
b_2	$\frac{(r^2+1)(r^2+2r+2)}{9r^4+24r^3+7r^2-12r-4}$	$-\frac{1}{2}$
b_3	$\frac{(r^2+1)(r^2+2r+2)(r^2+4r+5)}{27r^6+189r^5+441r^4+343r^3-84r^2-196r-48}$	$-\frac{5}{24}$
b_4	$\frac{(r^2+1)(r^2+2r+2)(r^2+4r+5)(r^2+6r+10)}{81r^8+1080r^7+5670r^6+14700r^5+18613r^4+7420r^3-6220r^2-6400r-1344}$	$-\frac{25}{336}$
b_5	$\frac{(r^2+1)(r^2+2r+2)(r^2+4r+5)(r^2+6r+10)(r^2+8r+17)}{(81r^8+1080r^7+5670r^6+14700r^5+18613r^4+7420r^3-6220r^2-6400r-1344)(3r^2+25r+50)}$	$-\frac{17}{672}$

Using the above table, then the solution $y_2(x)$ is

$$\begin{aligned} y_2(x) &= b_0 + b_1x + b_2x^2 + b_3x^3 + b_4x^4 + b_5x^5 + b_6x^6 \dots \\ &= 1 - \frac{x}{2} - \frac{x^2}{2} - \frac{5x^3}{24} - \frac{25x^4}{336} - \frac{17x^5}{672} + O(x^6) \end{aligned}$$

Therefore the homogeneous solution is

$$\begin{aligned}y_h(x) &= c_1 y_1(x) + c_2 y_2(x) \\&= c_1 x^{\frac{5}{3}} \left(1 + \frac{17x}{36} + \frac{1241x^2}{7128} + \frac{80665x^3}{1347192} + \frac{972725x^4}{48498912} + \frac{5797441x^5}{872980416} + O(x^6) \right) \\&\quad + c_2 \left(1 - \frac{x}{2} - \frac{x^2}{2} - \frac{5x^3}{24} - \frac{25x^4}{336} - \frac{17x^5}{672} + O(x^6) \right)\end{aligned}$$

Hence the final solution is

$$\begin{aligned}y &= y_h \\&= c_1 x^{\frac{5}{3}} \left(1 + \frac{17x}{36} + \frac{1241x^2}{7128} + \frac{80665x^3}{1347192} + \frac{972725x^4}{48498912} + \frac{5797441x^5}{872980416} + O(x^6) \right) \\&\quad + c_2 \left(1 - \frac{x}{2} - \frac{x^2}{2} - \frac{5x^3}{24} - \frac{25x^4}{336} - \frac{17x^5}{672} + O(x^6) \right)\end{aligned}$$

Summary

The solution(s) found are the following

$$\begin{aligned}y &= c_1 x^{\frac{5}{3}} \left(1 + \frac{17x}{36} + \frac{1241x^2}{7128} + \frac{80665x^3}{1347192} + \frac{972725x^4}{48498912} + \frac{5797441x^5}{872980416} + O(x^6) \right) \\&\quad + c_2 \left(1 - \frac{x}{2} - \frac{x^2}{2} - \frac{5x^3}{24} - \frac{25x^4}{336} - \frac{17x^5}{672} + O(x^6) \right)\end{aligned} \quad (1)$$

Verification of solutions

$$\begin{aligned}y &= c_1 x^{\frac{5}{3}} \left(1 + \frac{17x}{36} + \frac{1241x^2}{7128} + \frac{80665x^3}{1347192} + \frac{972725x^4}{48498912} + \frac{5797441x^5}{872980416} + O(x^6) \right) \\&\quad + c_2 \left(1 - \frac{x}{2} - \frac{x^2}{2} - \frac{5x^3}{24} - \frac{25x^4}{336} - \frac{17x^5}{672} + O(x^6) \right)\end{aligned}$$

Verified OK.

15.1.1 Maple step by step solution

Let's solve

$$y''x(x-3) + (x+2)y' + y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = -\frac{y}{x(x-3)} - \frac{(x+2)y'}{x(x-3)}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + \frac{(x+2)y'}{x(x-3)} + \frac{y}{x(x-3)} = 0$$

- Check to see if x_0 is a regular singular point

- Define functions

$$\left[P_2(x) = \frac{x+2}{x(x-3)}, P_3(x) = \frac{1}{x(x-3)} \right]$$

- $x \cdot P_2(x)$ is analytic at $x = 0$

$$(x \cdot P_2(x)) \Big|_{x=0} = -\frac{2}{3}$$

- $x^2 \cdot P_3(x)$ is analytic at $x = 0$

$$(x^2 \cdot P_3(x)) \Big|_{x=0} = 0$$

- $x = 0$ is a regular singular point

Check to see if x_0 is a regular singular point

$$x_0 = 0$$

- Multiply by denominators

$$y''x(x-3) + (x+2)y' + y = 0$$

- Assume series solution for y

$$y = \sum_{k=0}^{\infty} a_k x^{k+r}$$

- Rewrite ODE with series expansions

- Convert $x^m \cdot y'$ to series expansion for $m = 0..1$

$$x^m \cdot y' = \sum_{k=0}^{\infty} a_k (k+r) x^{k+r-1+m}$$

- Shift index using $k \rightarrow k + 1 - m$

$$x^m \cdot y' = \sum_{k=-1+m}^{\infty} a_{k+1-m}(k+1-m+r)x^{k+r}$$

- Convert $x^m \cdot y''$ to series expansion for $m = 1..2$

$$x^m \cdot y'' = \sum_{k=0}^{\infty} a_k(k+r)(k+r-1)x^{k+r-2+m}$$

- Shift index using $k \rightarrow k + 2 - m$

$$x^m \cdot y'' = \sum_{k=-2+m}^{\infty} a_{k+2-m}(k+2-m+r)(k+1-m+r)x^{k+r}$$

Rewrite ODE with series expansions

$$-a_0r(-5+3r)x^{-1+r} + \left(\sum_{k=0}^{\infty} (-a_{k+1}(k+1+r)(3k-2+3r) + a_k(k^2+2kr+r^2+1))x^{k+r} \right) =$$

- a_0 cannot be 0 by assumption, giving the indicial equation

$$-r(-5+3r) = 0$$
- Values of r that satisfy the indicial equation

$$r \in \left\{ 0, \frac{5}{3} \right\}$$
- Each term in the series must be 0, giving the recursion relation

$$-3\left(k - \frac{2}{3} + r\right)(k+1+r)a_{k+1} + a_k(k^2+2kr+r^2+1) = 0$$
- Recursion relation that defines series solution to ODE

$$a_{k+1} = \frac{a_k(k^2+2kr+r^2+1)}{(3k-2+3r)(k+1+r)}$$
- Recursion relation for $r = 0$

$$a_{k+1} = \frac{a_k(k^2+1)}{(3k-2)(k+1)}$$
- Solution for $r = 0$

$$\left[y = \sum_{k=0}^{\infty} a_k x^k, a_{k+1} = \frac{a_k(k^2+1)}{(3k-2)(k+1)} \right]$$
- Recursion relation for $r = \frac{5}{3}$

$$a_{k+1} = \frac{a_k(k^2 + \frac{10}{3}k + \frac{34}{9})}{(3k+3)(k + \frac{8}{3})}$$
- Solution for $r = \frac{5}{3}$

$$\left[y = \sum_{k=0}^{\infty} a_k x^{k + \frac{5}{3}}, a_{k+1} = \frac{a_k(k^2 + \frac{10}{3}k + \frac{34}{9})}{(3k+3)(k + \frac{8}{3})} \right]$$
- Combine solutions and rename parameters

$$\left[y = \left(\sum_{k=0}^{\infty} a_k x^k \right) + \left(\sum_{k=0}^{\infty} b_k x^{k+\frac{5}{3}} \right), a_{1+k} = \frac{a_k(k^2+1)}{(3k-2)(1+k)}, b_{1+k} = \frac{b_k(k^2+\frac{10}{3}k+\frac{34}{9})}{(3k+3)(k+\frac{8}{3})} \right]$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
trying a symmetry of the form [xi=0, eta=F(x)]
checking if the LODE is missing y
-> Trying a Liouvillian solution using Kovacic's algorithm
<- No Liouvillian solutions exist
-> Trying a solution in terms of special functions:
  -> Bessel
  -> elliptic
  -> Legendre
  -> Kummer
    -> hyper3: Equivalence to 1F1 under a power @ Moebius
  -> hypergeometric
    -> heuristic approach
      <- heuristic approach successful
    <- hypergeometric successful
  <- special function solution successful`

```

✓ Solution by Maple

Time used: 0.032 (sec). Leaf size: 44

```

Order:=6;
dsolve((x^2-3*x)*diff(y(x),x$2)+(x+2)*diff(y(x),x)+y(x)=0,y(x),type='series',x=0);

```

$$y(x) = c_1 x^{\frac{5}{3}} \left(1 + \frac{17}{36}x + \frac{1241}{7128}x^2 + \frac{80665}{1347192}x^3 + \frac{972725}{48498912}x^4 + \frac{5797441}{872980416}x^5 + O(x^6) \right) \\ + c_2 \left(1 - \frac{1}{2}x - \frac{1}{2}x^2 - \frac{5}{24}x^3 - \frac{25}{336}x^4 - \frac{17}{672}x^5 + O(x^6) \right)$$

✓ Solution by Mathematica

Time used: 0.011 (sec). Leaf size: 85

```
AsymptoticDSolveValue[(x^2-3*x)*y'[x]+(x+2)*y'[x]+y[x]==0,y[x],{x,0,5}]
```

$$y(x) \rightarrow c_2 \left(-\frac{17x^5}{672} - \frac{25x^4}{336} - \frac{5x^3}{24} - \frac{x^2}{2} - \frac{x}{2} + 1 \right) + c_1 \left(\frac{5797441x^5}{872980416} + \frac{972725x^4}{48498912} + \frac{80665x^3}{1347192} + \frac{1241x^2}{7128} + \frac{17x}{36} + 1 \right) x^{5/3}$$

15.2 problem 2

15.2.1 Maple step by step solution 4053

Internal problem ID [11903]

Internal file name [OUTPUT/11912_Saturday_April_13_2024_10_26_13_PM_19754612/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.2 (Frobenius). Exercises page 251

Problem number: 2.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"second order series method. Regular singular point. Complex roots"**

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$(x^3 + x^2) y'' + (x^2 - 2x) y' + 4y = 0$$

With the expansion point for the power series method at $x = 0$.

The type of the expansion point is first determined. This is done on the homogeneous part of the ODE.

$$(x^3 + x^2) y'' + (x^2 - 2x) y' + 4y = 0$$

The following is summary of singularities for the above ode. Writing the ode as

$$y'' + p(x)y' + q(x)y = 0$$

Where

$$p(x) = \frac{x - 2}{x(x + 1)}$$
$$q(x) = \frac{4}{x^2(x + 1)}$$

Table 529: Table $p(x), q(x)$ singularities.

$p(x) = \frac{x-2}{x(x+1)}$		$q(x) = \frac{4}{x^2(x+1)}$	
singularity	type	singularity	type
$x = -1$	“regular”	$x = -1$	“regular”
$x = 0$	“regular”	$x = 0$	“regular”

Combining everything together gives the following summary of singularities for the ode as

Regular singular points : $[-1, 0, \infty]$

Irregular singular points : $[\]$

Since $x = 0$ is regular singular point, then Frobenius power series is used. The ode is normalized to be

$$y''x^2(x+1) + (x^2 - 2x)y' + 4y = 0$$

Let the solution be represented as Frobenius power series of the form

$$y = \sum_{n=0}^{\infty} a_n x^{n+r}$$

Then

$$y' = \sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1}$$

$$y'' = \sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2}$$

Substituting the above back into the ode gives

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2} \right) x^2(x+1) \\ & + (x^2 - 2x) \left(\sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1} \right) + 4 \left(\sum_{n=0}^{\infty} a_n x^{n+r} \right) = 0 \end{aligned} \tag{1}$$

Which simplifies to

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} x^{1+n+r} a_n (n+r) (n+r-1) \right) + \left(\sum_{n=0}^{\infty} x^{n+r} a_n (n+r) (n+r-1) \right) \\ & + \left(\sum_{n=0}^{\infty} x^{1+n+r} a_n (n+r) \right) + \sum_{n=0}^{\infty} (-2x^{n+r} a_n (n+r)) + \left(\sum_{n=0}^{\infty} 4a_n x^{n+r} \right) = 0 \end{aligned} \quad (2A)$$

The next step is to make all powers of x be $n+r$ in each summation term. Going over each summation term above with power of x in it which is not already x^{n+r} and adjusting the power and the corresponding index gives

$$\begin{aligned} \sum_{n=0}^{\infty} x^{1+n+r} a_n (n+r) (n+r-1) &= \sum_{n=1}^{\infty} a_{n-1} (n+r-1) (n+r-2) x^{n+r} \\ \sum_{n=0}^{\infty} x^{1+n+r} a_n (n+r) &= \sum_{n=1}^{\infty} a_{n-1} (n+r-1) x^{n+r} \end{aligned}$$

Substituting all the above in Eq (2A) gives the following equation where now all powers of x are the same and equal to $n+r$.

$$\begin{aligned} & \left(\sum_{n=1}^{\infty} a_{n-1} (n+r-1) (n+r-2) x^{n+r} \right) + \left(\sum_{n=0}^{\infty} x^{n+r} a_n (n+r) (n+r-1) \right) \\ & + \left(\sum_{n=1}^{\infty} a_{n-1} (n+r-1) x^{n+r} \right) + \sum_{n=0}^{\infty} (-2x^{n+r} a_n (n+r)) + \left(\sum_{n=0}^{\infty} 4a_n x^{n+r} \right) = 0 \end{aligned} \quad (2B)$$

The indicial equation is obtained from $n=0$. From Eq (2B) this gives

$$x^{n+r} a_n (n+r) (n+r-1) - 2x^{n+r} a_n (n+r) + 4a_n x^{n+r} = 0$$

When $n=0$ the above becomes

$$x^r a_0 r (-1+r) - 2x^r a_0 r + 4a_0 x^r = 0$$

Or

$$(x^r r (-1+r) - 2x^r r + 4x^r) a_0 = 0$$

Since $a_0 \neq 0$ then the above simplifies to

$$(r^2 - 3r + 4) x^r = 0$$

Since the above is true for all x then the indicial equation becomes

$$r^2 - 3r + 4 = 0$$

Solving for r gives the roots of the indicial equation as

$$r_1 = \frac{3}{2} + \frac{i\sqrt{7}}{2}$$

$$r_2 = \frac{3}{2} - \frac{i\sqrt{7}}{2}$$

Since $a_0 \neq 0$ then the indicial equation becomes

$$(r^2 - 3r + 4) x^r = 0$$

Solving for r gives the roots of the indicial equation as Since the roots are complex conjugates, then two linearly independent solutions can be constructed using

$$y_1(x) = x^{r_1} \left(\sum_{n=0}^{\infty} a_n x^n \right)$$

$$y_2(x) = x^{r_2} \left(\sum_{n=0}^{\infty} b_n x^n \right)$$

Or

$$y_1(x) = \sum_{n=0}^{\infty} a_n x^{n + \frac{3}{2} + \frac{i\sqrt{7}}{2}}$$

$$y_2(x) = \sum_{n=0}^{\infty} b_n x^{n + \frac{3}{2} - \frac{i\sqrt{7}}{2}}$$

$y_1(x)$ is found first. Eq (2B) derived above is now used to find all a_n coefficients. The case $n = 0$ is skipped since it was used to find the roots of the indicial equation. a_0 is arbitrary and taken as $a_0 = 1$. For $1 \leq n$ the recursive equation is

$$a_{n-1}(n+r-1)(n+r-2) + a_n(n+r)(n+r-1) + a_{n-1}(n+r-1) - 2a_n(n+r) + 4a_n = 0 \quad (3)$$

Solving for a_n from recursive equation (4) gives

$$a_n = -\frac{a_{n-1}(n^2 + 2nr + r^2 - 2n - 2r + 1)}{n^2 + 2nr + r^2 - 3n - 3r + 4} \quad (4)$$

Which for the root $r = \frac{3}{2} + \frac{i\sqrt{7}}{2}$ becomes

$$a_n = -\frac{a_{n-1}((in + \frac{1}{2}i)\sqrt{7} + n^2 + n - \frac{3}{2})}{n(i\sqrt{7} + n)} \quad (5)$$

At this point, it is a good idea to keep track of a_n in a table both before substituting $r = \frac{3}{2} + \frac{i\sqrt{7}}{2}$ and after as more terms are found using the above recursive equation.

n	$a_{n,r}$	a_n
a_0	1	1

For $n = 1$, using the above recursive equation gives

$$a_1 = -\frac{r^2}{r^2 - r + 2}$$

Which for the root $r = \frac{3}{2} + \frac{i\sqrt{7}}{2}$ becomes

$$a_1 = -\frac{(3 + i\sqrt{7})^2}{4 + 4i\sqrt{7}}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$-\frac{r^2}{r^2 - r + 2}$	$-\frac{(3+i\sqrt{7})^2}{4+4i\sqrt{7}}$

For $n = 2$, using the above recursive equation gives

$$a_2 = \frac{r^2(r+1)^2}{(r^2 - r + 2)(r^2 + r + 2)}$$

Which for the root $r = \frac{3}{2} + \frac{i\sqrt{7}}{2}$ becomes

$$a_2 = \frac{-4\sqrt{7} - 12i}{(-\sqrt{7} + i)(i\sqrt{7} + 2)}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$-\frac{r^2}{r^2-r+2}$	$-\frac{(3+i\sqrt{7})^2}{4+4i\sqrt{7}}$
a_2	$\frac{r^2(r+1)^2}{(r^2-r+2)(r^2+r+2)}$	$\frac{-4\sqrt{7}-12i}{(-\sqrt{7}+i)(i\sqrt{7}+2)}$

For $n = 3$, using the above recursive equation gives

$$a_3 = -\frac{r^2(r+1)^2(r+2)^2}{(r^2-r+2)(r^2+r+2)(r^2+3r+4)}$$

Which for the root $r = \frac{3}{2} + \frac{i\sqrt{7}}{2}$ becomes

$$a_3 = \frac{7(3i - \sqrt{7})^2 (i\sqrt{7} + 5)^2}{576i\sqrt{7} - 960}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$-\frac{r^2}{r^2-r+2}$	$-\frac{(3+i\sqrt{7})^2}{4+4i\sqrt{7}}$
a_2	$\frac{r^2(r+1)^2}{(r^2-r+2)(r^2+r+2)}$	$\frac{-4\sqrt{7}-12i}{(-\sqrt{7}+i)(i\sqrt{7}+2)}$
a_3	$-\frac{r^2(r+1)^2(r+2)^2}{(r^2-r+2)(r^2+r+2)(r^2+3r+4)}$	$\frac{7(3i-\sqrt{7})^2(i\sqrt{7}+5)^2}{576i\sqrt{7}-960}$

For $n = 4$, using the above recursive equation gives

$$a_4 = \frac{r^2(r+1)^2(r+2)^2(r+3)^2}{(r^2-r+2)(r^2+r+2)(r^2+3r+4)(r^2+5r+8)}$$

Which for the root $r = \frac{3}{2} + \frac{i\sqrt{7}}{2}$ becomes

$$a_4 = \frac{(3i - \sqrt{7})(i\sqrt{7} + 7)^2 (i\sqrt{7} + 5)^2 (9i\sqrt{7} + 37)}{3072 (i\sqrt{7} + 4) (-\sqrt{7} + i) (i\sqrt{7} + 2)}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$-\frac{r^2}{r^2-r+2}$	$-\frac{(3+i\sqrt{7})^2}{4+4i\sqrt{7}}$
a_2	$\frac{r^2(r+1)^2}{(r^2-r+2)(r^2+r+2)}$	$\frac{-4\sqrt{7}-12i}{(-\sqrt{7}+i)(i\sqrt{7}+2)}$
a_3	$-\frac{r^2(r+1)^2(r+2)^2}{(r^2-r+2)(r^2+r+2)(r^2+3r+4)}$	$\frac{7(3i-\sqrt{7})^2(i\sqrt{7}+5)^2}{576i\sqrt{7}-960}$
a_4	$\frac{r^2(r+1)^2(r+2)^2(r+3)^2}{(r^2-r+2)(r^2+r+2)(r^2+3r+4)(r^2+5r+8)}$	$\frac{(3i-\sqrt{7})(i\sqrt{7}+7)^2(i\sqrt{7}+5)^2(9i\sqrt{7}+37)}{3072(i\sqrt{7}+4)(-\sqrt{7}+i)(i\sqrt{7}+2)}$

For $n = 5$, using the above recursive equation gives

$$a_5 = -\frac{r^2(r+1)^2(r+2)^2(r+3)^2(r+4)^2}{(r^2-r+2)(r^2+r+2)(r^2+3r+4)(r^2+5r+8)(r^2+7r+14)}$$

Which for the root $r = \frac{3}{2} + \frac{i\sqrt{7}}{2}$ becomes

$$a_5 = \frac{11(3i-\sqrt{7})(i\sqrt{7}+7)^2(i\sqrt{7}+5)(i\sqrt{7}+\frac{57}{11})(i\sqrt{7}+9)^2}{61440(i\sqrt{7}+4)(\sqrt{7}-i)(i\sqrt{7}+2)}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$-\frac{r^2}{r^2-r+2}$	$-\frac{(3+i\sqrt{7})^2}{4+4i\sqrt{7}}$
a_2	$\frac{r^2(r+1)^2}{(r^2-r+2)(r^2+r+2)}$	$\frac{-4\sqrt{7}-12i}{(-\sqrt{7}+i)(i\sqrt{7}+2)}$
a_3	$-\frac{r^2(r+1)^2(r+2)^2}{(r^2-r+2)(r^2+r+2)(r^2+3r+4)}$	$\frac{7(3i-\sqrt{7})^2(i\sqrt{7}+5)^2}{576i\sqrt{7}-960}$
a_4	$\frac{r^2(r+1)^2(r+2)^2(r+3)^2}{(r^2-r+2)(r^2+r+2)(r^2+3r+4)(r^2+5r+8)}$	$\frac{(3i-\sqrt{7})(i\sqrt{7}+7)^2(i\sqrt{7}+5)^2(9i\sqrt{7}+37)}{3072(i\sqrt{7}+4)(-\sqrt{7}+i)(i\sqrt{7}+2)}$
a_5	$-\frac{r^2(r+1)^2(r+2)^2(r+3)^2(r+4)^2}{(r^2-r+2)(r^2+r+2)(r^2+3r+4)(r^2+5r+8)(r^2+7r+14)}$	$\frac{11(3i-\sqrt{7})(i\sqrt{7}+7)^2(i\sqrt{7}+5)(i\sqrt{7}+\frac{57}{11})(i\sqrt{7}+9)^2}{61440(i\sqrt{7}+4)(\sqrt{7}-i)(i\sqrt{7}+2)}$

Using the above table, then the solution $y_1(x)$ is

$$\begin{aligned}
 y_1(x) &= x^{\frac{3}{2} + \frac{i\sqrt{7}}{2}} (a_0 + a_1x + a_2x^2 + a_3x^3 + a_4x^4 + a_5x^5 + a_6x^6 \dots) \\
 &= x^{\frac{3}{2} + \frac{i\sqrt{7}}{2}} \left(1 - \frac{(3 + i\sqrt{7})^2 x}{4 + 4i\sqrt{7}} + \frac{(-4\sqrt{7} - 12i)x^2}{(-\sqrt{7} + i)(i\sqrt{7} + 2)} + \frac{7(3i - \sqrt{7})^2 (i\sqrt{7} + 5)^2 x^3}{576i\sqrt{7} - 960} \right. \\
 &\quad + \frac{(3i - \sqrt{7})(i\sqrt{7} + 7)^2 (i\sqrt{7} + 5)^2 (9i\sqrt{7} + 37)x^4}{3072(i\sqrt{7} + 4)(-\sqrt{7} + i)(i\sqrt{7} + 2)} \\
 &\quad \left. + \frac{11(3i - \sqrt{7})(i\sqrt{7} + 7)^2 (i\sqrt{7} + 5)(i\sqrt{7} + \frac{57}{11})(i\sqrt{7} + 9)^2 x^5}{61440(i\sqrt{7} + 4)(\sqrt{7} - i)(i\sqrt{7} + 2)} + O(x^6) \right)
 \end{aligned}$$

The second solution $y_2(x)$ is found by taking the complex conjugate of $y_1(x)$ which gives

$$\begin{aligned}
 y_2(x) &= x^{\frac{3}{2} - \frac{i\sqrt{7}}{2}} \left(1 - \frac{(3 - i\sqrt{7})^2 x}{4 - 4i\sqrt{7}} + \frac{(-4\sqrt{7} + 12i)x^2}{(-\sqrt{7} - i)(-i\sqrt{7} + 2)} \right. \\
 &\quad + \frac{7(-3i - \sqrt{7})^2 (-i\sqrt{7} + 5)^2 x^3}{-576i\sqrt{7} - 960} \\
 &\quad + \frac{(-3i - \sqrt{7})(-i\sqrt{7} + 7)^2 (-i\sqrt{7} + 5)^2 (-9i\sqrt{7} + 37)x^4}{3072(-i\sqrt{7} + 4)(-\sqrt{7} - i)(-i\sqrt{7} + 2)} \\
 &\quad \left. + \frac{11(-3i - \sqrt{7})(-i\sqrt{7} + 7)^2 (-i\sqrt{7} + 5)(-i\sqrt{7} + \frac{57}{11})(-i\sqrt{7} + 9)^2 x^5}{61440(-i\sqrt{7} + 4)(\sqrt{7} + i)(-i\sqrt{7} + 2)} \right. \\
 &\quad \left. + O(x^6) \right)
 \end{aligned}$$

Therefore the homogeneous solution is

$$y_h(x) = c_1 y_1(x) + c_2 y_2(x)$$

$$\begin{aligned}
&= c_1 x^{\frac{3}{2} + \frac{i\sqrt{7}}{2}} \left(1 - \frac{(3 + i\sqrt{7})^2 x}{4 + 4i\sqrt{7}} + \frac{(-4\sqrt{7} - 12i) x^2}{(-\sqrt{7} + i)(i\sqrt{7} + 2)} + \frac{7(3i - \sqrt{7})^2 (i\sqrt{7} + 5)^2 x^3}{576i\sqrt{7} - 960} \right. \\
&\quad + \frac{(3i - \sqrt{7})(i\sqrt{7} + 7)^2 (i\sqrt{7} + 5)^2 (9i\sqrt{7} + 37) x^4}{3072(i\sqrt{7} + 4)(-\sqrt{7} + i)(i\sqrt{7} + 2)} \\
&\quad \left. + \frac{11(3i - \sqrt{7})(i\sqrt{7} + 7)^2 (i\sqrt{7} + 5)(i\sqrt{7} + \frac{57}{11})(i\sqrt{7} + 9)^2 x^5}{61440(i\sqrt{7} + 4)(\sqrt{7} - i)(i\sqrt{7} + 2)} + O(x^6) \right) \\
&+ c_2 x^{\frac{3}{2} - \frac{i\sqrt{7}}{2}} \left(1 - \frac{(3 - i\sqrt{7})^2 x}{4 - 4i\sqrt{7}} + \frac{(-4\sqrt{7} + 12i) x^2}{(-\sqrt{7} - i)(-i\sqrt{7} + 2)} \right. \\
&\quad + \frac{7(-3i - \sqrt{7})^2 (-i\sqrt{7} + 5)^2 x^3}{-576i\sqrt{7} - 960} \\
&\quad + \frac{(-3i - \sqrt{7})(-i\sqrt{7} + 7)^2 (-i\sqrt{7} + 5)^2 (-9i\sqrt{7} + 37) x^4}{3072(-i\sqrt{7} + 4)(-\sqrt{7} - i)(-i\sqrt{7} + 2)} \\
&\quad \left. + \frac{11(-3i - \sqrt{7})(-i\sqrt{7} + 7)^2 (-i\sqrt{7} + 5)(-i\sqrt{7} + \frac{57}{11})(-i\sqrt{7} + 9)^2 x^5}{61440(-i\sqrt{7} + 4)(\sqrt{7} + i)(-i\sqrt{7} + 2)} \right) \\
&\quad \quad \quad + O(x^6)
\end{aligned}$$

Hence the final solution is

$$y = y_h$$

$$\begin{aligned}
&= c_1 x^{\frac{3}{2} + \frac{i\sqrt{7}}{2}} \left(1 - \frac{(3 + i\sqrt{7})^2 x}{4 + 4i\sqrt{7}} + \frac{(-4\sqrt{7} - 12i) x^2}{(-\sqrt{7} + i)(i\sqrt{7} + 2)} + \frac{7(3i - \sqrt{7})^2 (i\sqrt{7} + 5)^2 x^3}{576i\sqrt{7} - 960} \right. \\
&\quad + \frac{(3i - \sqrt{7})(i\sqrt{7} + 7)^2 (i\sqrt{7} + 5)^2 (9i\sqrt{7} + 37) x^4}{3072(i\sqrt{7} + 4)(-\sqrt{7} + i)(i\sqrt{7} + 2)} \\
&\quad \left. + \frac{11(3i - \sqrt{7})(i\sqrt{7} + 7)^2 (i\sqrt{7} + 5)(i\sqrt{7} + \frac{57}{11})(i\sqrt{7} + 9)^2 x^5}{61440(i\sqrt{7} + 4)(\sqrt{7} - i)(i\sqrt{7} + 2)} + O(x^6) \right) \\
&+ c_2 x^{\frac{3}{2} - \frac{i\sqrt{7}}{2}} \left(1 - \frac{(3 - i\sqrt{7})^2 x}{4 - 4i\sqrt{7}} + \frac{(-4\sqrt{7} + 12i) x^2}{(-\sqrt{7} - i)(-i\sqrt{7} + 2)} \right. \\
&\quad + \frac{7(-3i - \sqrt{7})^2 (-i\sqrt{7} + 5)^2 x^3}{-576i\sqrt{7} - 960} \\
&\quad + \frac{(-3i - \sqrt{7})(-i\sqrt{7} + 7)^2 (-i\sqrt{7} + 5)^2 (-9i\sqrt{7} + 37) x^4}{3072(-i\sqrt{7} + 4)(-\sqrt{7} - i)(-i\sqrt{7} + 2)} \\
&\quad \left. + \frac{11(-3i - \sqrt{7})(-i\sqrt{7} + 7)^2 (-i\sqrt{7} + 5)(-i\sqrt{7} + \frac{57}{11})(-i\sqrt{7} + 9)^2 x^5}{61440(-i\sqrt{7} + 4)(\sqrt{7} + i)(-i\sqrt{7} + 2)} + O(x^6) \right)
\end{aligned}$$

Summary

The solution(s) found are the following

$$\begin{aligned}
y &= c_1 x^{\frac{3}{2} + \frac{i\sqrt{7}}{2}} \left(1 - \frac{(3 + i\sqrt{7})^2 x}{4 + 4i\sqrt{7}} + \frac{(-4\sqrt{7} - 12i) x^2}{(-\sqrt{7} + i)(i\sqrt{7} + 2)} + \frac{7(3i - \sqrt{7})^2 (i\sqrt{7} + 5)^2 x^3}{576i\sqrt{7} - 960} \right. \\
&\quad + \frac{(3i - \sqrt{7})(i\sqrt{7} + 7)^2 (i\sqrt{7} + 5)^2 (9i\sqrt{7} + 37) x^4}{3072(i\sqrt{7} + 4)(-\sqrt{7} + i)(i\sqrt{7} + 2)} \\
&\quad \left. + \frac{11(3i - \sqrt{7})(i\sqrt{7} + 7)^2 (i\sqrt{7} + 5)(i\sqrt{7} + \frac{57}{11})(i\sqrt{7} + 9)^2 x^5}{61440(i\sqrt{7} + 4)(\sqrt{7} - i)(i\sqrt{7} + 2)} + O(x^6) \right) \\
&+ c_2 x^{\frac{3}{2} - \frac{i\sqrt{7}}{2}} \left(1 - \frac{(3 - i\sqrt{7})^2 x}{4 - 4i\sqrt{7}} + \frac{(-4\sqrt{7} + 12i) x^2}{(-\sqrt{7} - i)(-i\sqrt{7} + 2)} \right. \\
&\quad + \frac{7(-3i - \sqrt{7})^2 (-i\sqrt{7} + 5)^2 x^3}{-576i\sqrt{7} - 960} \\
&\quad + \frac{(-3i - \sqrt{7})(-i\sqrt{7} + 7)^2 (-i\sqrt{7} + 5)^2 (-9i\sqrt{7} + 37) x^4}{3072(-i\sqrt{7} + 4)(-\sqrt{7} - i)(-i\sqrt{7} + 2)} \\
&\quad \left. + \frac{11(-3i - \sqrt{7})(-i\sqrt{7} + 7)^2 (-i\sqrt{7} + 5)(-i\sqrt{7} + \frac{57}{11})(-i\sqrt{7} + 9)^2 x^5}{61440(-i\sqrt{7} + 4)(\sqrt{7} + i)(-i\sqrt{7} + 2)} + O(x^6) \right)
\end{aligned} \tag{1}$$

Verification of solutions

$$\begin{aligned}
 y = c_1 x^{\frac{3}{2} + \frac{i\sqrt{7}}{2}} & \left(1 - \frac{(3 + i\sqrt{7})^2 x}{4 + 4i\sqrt{7}} + \frac{(-4\sqrt{7} - 12i) x^2}{(-\sqrt{7} + i)(i\sqrt{7} + 2)} + \frac{7(3i - \sqrt{7})^2 (i\sqrt{7} + 5)^2 x^3}{576i\sqrt{7} - 960} \right. \\
 & + \frac{(3i - \sqrt{7})(i\sqrt{7} + 7)^2 (i\sqrt{7} + 5)^2 (9i\sqrt{7} + 37) x^4}{3072(i\sqrt{7} + 4)(-\sqrt{7} + i)(i\sqrt{7} + 2)} \\
 & \left. + \frac{11(3i - \sqrt{7})(i\sqrt{7} + 7)^2 (i\sqrt{7} + 5)(i\sqrt{7} + \frac{57}{11})(i\sqrt{7} + 9)^2 x^5}{61440(i\sqrt{7} + 4)(\sqrt{7} - i)(i\sqrt{7} + 2)} + O(x^6) \right) \\
 + c_2 x^{\frac{3}{2} - \frac{i\sqrt{7}}{2}} & \left(1 - \frac{(3 - i\sqrt{7})^2 x}{4 - 4i\sqrt{7}} + \frac{(-4\sqrt{7} + 12i) x^2}{(-\sqrt{7} - i)(-i\sqrt{7} + 2)} \right. \\
 & + \frac{7(-3i - \sqrt{7})^2 (-i\sqrt{7} + 5)^2 x^3}{-576i\sqrt{7} - 960} \\
 & + \frac{(-3i - \sqrt{7})(-i\sqrt{7} + 7)^2 (-i\sqrt{7} + 5)^2 (-9i\sqrt{7} + 37) x^4}{3072(-i\sqrt{7} + 4)(-\sqrt{7} - i)(-i\sqrt{7} + 2)} \\
 & \left. + \frac{11(-3i - \sqrt{7})(-i\sqrt{7} + 7)^2 (-i\sqrt{7} + 5)(-i\sqrt{7} + \frac{57}{11})(-i\sqrt{7} + 9)^2 x^5}{61440(-i\sqrt{7} + 4)(\sqrt{7} + i)(-i\sqrt{7} + 2)} + O(x^6) \right)
 \end{aligned}$$

Verified OK.

15.2.1 Maple step by step solution

Let's solve

$$y''x^2(x+1) + (x^2 - 2x)y' + 4y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = -\frac{4y}{x^2(x+1)} - \frac{(x-2)y'}{x(x+1)}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + \frac{(x-2)y'}{x(x+1)} + \frac{4y}{x^2(x+1)} = 0$$

- Check to see if x_0 is a regular singular point

- Define functions

$$\left[P_2(x) = \frac{x-2}{x(x+1)}, P_3(x) = \frac{4}{x^2(x+1)} \right]$$

- $(x+1) \cdot P_2(x)$ is analytic at $x = -1$

$$((x+1) \cdot P_2(x)) \Big|_{x=-1} = 3$$

- $(x+1)^2 \cdot P_3(x)$ is analytic at $x = -1$

$$((x+1)^2 \cdot P_3(x)) \Big|_{x=-1} = 0$$

- $x = -1$ is a regular singular point

Check to see if x_0 is a regular singular point

$$x_0 = -1$$

- Multiply by denominators

$$y''x^2(x+1) + x(x-2)y' + 4y = 0$$

- Change variables using $x = u - 1$ so that the regular singular point is at $u = 0$

$$(u^3 - 2u^2 + u) \left(\frac{d^2}{du^2} y(u) \right) + (u^2 - 4u + 3) \left(\frac{d}{du} y(u) \right) + 4y(u) = 0$$

- Assume series solution for $y(u)$

$$y(u) = \sum_{k=0}^{\infty} a_k u^{k+r}$$

- Rewrite ODE with series expansions

- Convert $u^m \cdot \left(\frac{d}{du} y(u) \right)$ to series expansion for $m = 0..2$

$$u^m \cdot \left(\frac{d}{du} y(u) \right) = \sum_{k=0}^{\infty} a_k (k+r) u^{k+r-1+m}$$

- Shift index using $k \rightarrow k+1-m$

$$u^m \cdot \left(\frac{d}{du} y(u) \right) = \sum_{k=-1+m}^{\infty} a_{k+1-m} (k+1-m+r) u^{k+r}$$

- Convert $u^m \cdot \left(\frac{d^2}{du^2} y(u) \right)$ to series expansion for $m = 1..3$

$$u^m \cdot \left(\frac{d^2}{du^2} y(u) \right) = \sum_{k=0}^{\infty} a_k (k+r)(k+r-1) u^{k+r-2+m}$$

- Shift index using $k \rightarrow k+2-m$

$$u^m \cdot \left(\frac{d^2}{du^2} y(u) \right) = \sum_{k=-2+m}^{\infty} a_{k+2-m} (k+2-m+r)(k+1-m+r) u^{k+r}$$

Rewrite ODE with series expansions

$$a_0 r(2+r) u^{-1+r} + (a_1(1+r)(3+r) - 2a_0(2+r)(-1+r)) u^r + \left(\sum_{k=1}^{\infty} (a_{k+1}(k+1+r)(k+3+r) - 2a_k(k+r)(k+r-1)) u^{k+r} \right)$$

- a_0 cannot be 0 by assumption, giving the indicial equation

$$r(2+r) = 0$$

- Values of r that satisfy the indicial equation

$$r \in \{-2, 0\}$$

- Each term must be 0

$$a_1(1+r)(3+r) - 2a_0(2+r)(-1+r) = 0$$

- Each term in the series must be 0, giving the recursion relation

$$a_{k+1}(k+1+r)(k+3+r) - 2a_k(k+r+2)(k+r-1) + a_{k-1}(k+r-1)^2 = 0$$

- Shift index using $k \rightarrow k+1$

$$a_{k+2}(k+r+2)(k+4+r) - 2a_{k+1}(k+3+r)(k+r) + a_k(k+r)^2 = 0$$

- Recursion relation that defines series solution to ODE

$$a_{k+2} = -\frac{k^2 a_k - 2k^2 a_{k+1} + 2k r a_k - 4k r a_{k+1} + r^2 a_k - 2r^2 a_{k+1} - 6k a_{k+1} - 6r a_{k+1}}{(k+r+2)(k+4+r)}$$

- Recursion relation for $r = -2$; series terminates at $k = 2$

$$a_{k+2} = -\frac{k^2 a_k - 2k^2 a_{k+1} - 4k a_k + 2k a_{k+1} + 4a_k + 4a_{k+1}}{k(k+2)}$$

- Series not valid for $r = -2$, division by 0 in the recursion relation at $k = 0$

$$a_{k+2} = -\frac{k^2 a_k - 2k^2 a_{k+1} - 4k a_k + 2k a_{k+1} + 4a_k + 4a_{k+1}}{k(k+2)}$$

- Recursion relation for $r = 0$; series terminates at $k = 0$

$$a_{k+2} = -\frac{k^2 a_k - 2k^2 a_{k+1} - 6k a_{k+1}}{(k+2)(k+4)}$$

- Solution for $r = 0$

$$\left[y(u) = \sum_{k=0}^{\infty} a_k u^k, a_{k+2} = -\frac{k^2 a_k - 2k^2 a_{k+1} - 6k a_{k+1}}{(k+2)(k+4)}, 3a_1 + 4a_0 = 0 \right]$$

- Revert the change of variables $u = x + 1$

$$\left[y = \sum_{k=0}^{\infty} a_k (x+1)^k, a_{k+2} = -\frac{k^2 a_k - 2k^2 a_{k+1} - 6k a_{k+1}}{(k+2)(k+4)}, 3a_1 + 4a_0 = 0 \right]$$

Maple trace

```
`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
trying a symmetry of the form [xi=0, eta=F(x)]
checking if the LODE is missing y
-> Trying a Liouvillian solution using Kovacic's algorithm
<- No Liouvillian solutions exist
-> Trying a solution in terms of special functions:
  -> Bessel
  -> elliptic
  -> Legendre
  -> Kummer
    -> hyper3: Equivalence to 1F1 under a power @ Moebius
  -> hypergeometric
    -> heuristic approach
    -> hyper3: Equivalence to 2F1, 1F1 or 0F1 under a power @ Moebius
      <- hyper3 successful: received ODE is equivalent to the 2F1 ODE
      <- hypergeometric successful
<- special function solution successful`
```

✓ Solution by Maple

Time used: 0.031 (sec). Leaf size: 1227

Order:=6;

dsolve((x^3+x^2)*diff(y(x),x\$2)+(x^2-2*x)*diff(y(x),x)+4*y(x)=0,y(x),type='series',x=0);

$$\begin{aligned}
 y(x) = x^{\frac{3}{2}} & \left(c_2 x^{\frac{i\sqrt{7}}{2}} \left(1 + \frac{3\sqrt{7}-i}{-2\sqrt{7}+2i} x + \frac{-4\sqrt{7}-12i}{(-\sqrt{7}+i)(i\sqrt{7}+2)} x^2 \right. \right. \\
 & + \frac{224}{3} \frac{1}{(\sqrt{7}-2i)(-\sqrt{7}+i)(3+i\sqrt{7})} x^3 \\
 & + \frac{84\sqrt{7}-\frac{1036i}{3}}{(-\sqrt{7}+i)(i\sqrt{7}+2)(3+i\sqrt{7})(4+i\sqrt{7})} x^4 \\
 & \left. \left. + \frac{\frac{2576i\sqrt{7}}{3} + \frac{6608}{5}}{(-4i+\sqrt{7})(-\sqrt{7}+i)(i\sqrt{7}+2)(3+i\sqrt{7})(i\sqrt{7}+5)} x^5 + O(x^6) \right) \right. \\
 & + c_1 x^{-\frac{i\sqrt{7}}{2}} \left(1 + \frac{-3\sqrt{7}-i}{2\sqrt{7}+2i} x + \frac{12+4i\sqrt{7}}{5+3i\sqrt{7}} x^2 \right. \\
 & + \frac{224}{3} \frac{1}{(i\sqrt{7}-2)(\sqrt{7}+3i)(\sqrt{7}+i)} x^3 + \frac{63i\sqrt{7}-259}{15i\sqrt{7}-129} x^4 \\
 & \left. \left. + \frac{-1239i-805\sqrt{7}}{675i+255\sqrt{7}} x^5 + O(x^6) \right) \right)
 \end{aligned}$$

✓ Solution by Mathematica

Time used: 0.006 (sec). Leaf size: 5834

AsymptoticDSolveValue[(x^3+x^2)*y'[x]+(x^2-2*x)*y'[x]+4*y[x]==0,y[x],{x,0,5}]

Too large to display

15.3 problem 3

15.3.1 Maple step by step solution 4059

Internal problem ID [11904]

Internal file name [OUTPUT/11913_Saturday_April_13_2024_10_26_15_PM_27176372/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.2 (Frobenius). Exercises page 251

Problem number: 3.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"second order series method. Irregular singular point"**

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

Unable to solve or complete the solution.

$$(x^4 - 2x^3 + x^2) y'' + 2(x - 1) y' + x^2 y = 0$$

With the expansion point for the power series method at $x = 0$.

The type of the expansion point is first determined. This is done on the homogeneous part of the ODE.

$$(x^4 - 2x^3 + x^2) y'' + (2x - 2) y' + x^2 y = 0$$

The following is summary of singularities for the above ode. Writing the ode as

$$y'' + p(x)y' + q(x)y = 0$$

Where

$$p(x) = \frac{2}{x^2(x-1)}$$
$$q(x) = \frac{1}{(x-1)^2}$$

Table 531: Table $p(x), q(x)$ singularities.

$p(x) = \frac{2}{x^2(x-1)}$	
singularity	type
$x = 0$	“irregular”
$x = 1$	“regular”

$q(x) = \frac{1}{(x-1)^2}$	
singularity	type
$x = 1$	“regular”

Combining everything together gives the following summary of singularities for the ode as

Regular singular points : $[1, \infty]$

Irregular singular points : $[0]$

Since $x = 0$ is not an ordinary point, then we will now check if it is a regular singular point. Unable to solve since $x = 0$ is not regular singular point. Terminating.

Verification of solutions N/A

15.3.1 Maple step by step solution

Let's solve

$$y''x^2(x-1)^2 + (2x-2)y' + x^2y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = -\frac{2y'}{(x-1)x^2} - \frac{y}{(x-1)^2}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + \frac{2y'}{(x-1)x^2} + \frac{y}{(x-1)^2} = 0$$

- Check to see if x_0 is a regular singular point

- Define functions

$$\left[P_2(x) = \frac{2}{x^2(x-1)}, P_3(x) = \frac{1}{(x-1)^2} \right]$$

- $(x-1) \cdot P_2(x)$ is analytic at $x = 1$

$$\left. ((x-1) \cdot P_2(x)) \right|_{x=1} = 2$$

- $(x - 1)^2 \cdot P_3(x)$ is analytic at $x = 1$

$$\left. ((x - 1)^2 \cdot P_3(x)) \right|_{x=1} = 1$$

- $x = 1$ is a regular singular point

Check to see if x_0 is a regular singular point

$$x_0 = 1$$

- Multiply by denominators

$$y''x^2(x - 1)^2 + (2x - 2)y' + x^2y = 0$$

- Change variables using $x = u + 1$ so that the regular singular point is at $u = 0$

$$(u^4 + 2u^3 + u^2) \left(\frac{d^2}{du^2} y(u) \right) + 2u \left(\frac{d}{du} y(u) \right) + (u^2 + 2u + 1) y(u) = 0$$

- Assume series solution for $y(u)$

$$y(u) = \sum_{k=0}^{\infty} a_k u^{k+r}$$

- Rewrite ODE with series expansions

- Convert $u^m \cdot y(u)$ to series expansion for $m = 0..2$

$$u^m \cdot y(u) = \sum_{k=0}^{\infty} a_k u^{k+r+m}$$

- Shift index using $k \rightarrow k - m$

$$u^m \cdot y(u) = \sum_{k=m}^{\infty} a_{k-m} u^{k+r}$$

- Convert $u \cdot \left(\frac{d}{du} y(u) \right)$ to series expansion

$$u \cdot \left(\frac{d}{du} y(u) \right) = \sum_{k=0}^{\infty} a_k (k + r) u^{k+r}$$

- Convert $u^m \cdot \left(\frac{d^2}{du^2} y(u) \right)$ to series expansion for $m = 2..4$

$$u^m \cdot \left(\frac{d^2}{du^2} y(u) \right) = \sum_{k=0}^{\infty} a_k (k + r) (k + r - 1) u^{k+r-2+m}$$

- Shift index using $k \rightarrow k + 2 - m$

$$u^m \cdot \left(\frac{d^2}{du^2} y(u) \right) = \sum_{k=-2+m}^{\infty} a_{k+2-m} (k + 2 - m + r) (k + 1 - m + r) u^{k+r}$$

Rewrite ODE with series expansions

$$a_0(r^2 + r + 1) u^r + ((r^2 + 3r + 3) a_1 + 2a_0(r^2 - r + 1)) u^{1+r} + \left(\sum_{k=2}^{\infty} (a_k(k^2 + 2kr + r^2 + k + r + 1)) \right) u^{k+r}$$

- a_0 cannot be 0 by assumption, giving the indicial equation

$$r^2 + r + 1 = 0$$

- Values of r that satisfy the indicial equation

$$r \in \left\{ -\frac{1}{2} - \frac{i\sqrt{3}}{2}, -\frac{1}{2} + \frac{i\sqrt{3}}{2} \right\}$$

- Each term must be 0

$$(r^2 + 3r + 3) a_1 + 2a_0(r^2 - r + 1) = 0$$

- Solve for the dependent coefficient(s)

$$a_1 = -\frac{2a_0(r^2 - r + 1)}{r^2 + 3r + 3}$$

- Each term in the series must be 0, giving the recursion relation

$$(a_k + a_{k-2} + 2a_{k-1}) k^2 + ((2a_k + 2a_{k-2} + 4a_{k-1}) r + a_k - 5a_{k-2} - 6a_{k-1}) k + (a_k + a_{k-2} + 2a_{k-1}) = 0$$

- Shift index using $k \rightarrow k + 2$

$$(a_{k+2} + a_k + 2a_{k+1}) (k + 2)^2 + ((2a_{k+2} + 2a_k + 4a_{k+1}) r + a_{k+2} - 5a_k - 6a_{k+1}) (k + 2) + (a_{k+2} + a_k + 2a_{k+1}) = 0$$

- Recursion relation that defines series solution to ODE

$$a_{k+2} = -\frac{k^2 a_k + 2k^2 a_{k+1} + 2kr a_k + 4kra_{k+1} + r^2 a_k + 2r^2 a_{k+1} - k a_k + 2k a_{k+1} - r a_k + 2r a_{k+1} + a_k + 2a_{k+1}}{k^2 + 2kr + r^2 + 5k + 5r + 7}$$

- Recursion relation for $r = -\frac{1}{2} - \frac{i\sqrt{3}}{2}$

$$a_{k+2} = -\frac{k^2 a_k + 2k^2 a_{k+1} + 2k \left(-\frac{1}{2} - \frac{i\sqrt{3}}{2}\right) a_k + 4k \left(-\frac{1}{2} - \frac{i\sqrt{3}}{2}\right) a_{k+1} + \left(-\frac{1}{2} - \frac{i\sqrt{3}}{2}\right)^2 a_k + 2 \left(-\frac{1}{2} - \frac{i\sqrt{3}}{2}\right)^2 a_{k+1} - k a_k + 2k a_{k+1} - \left(-\frac{1}{2} - \frac{i\sqrt{3}}{2}\right) a_k + 2 \left(-\frac{1}{2} - \frac{i\sqrt{3}}{2}\right) a_{k+1}}{k^2 + 2k \left(-\frac{1}{2} - \frac{i\sqrt{3}}{2}\right) + \left(-\frac{1}{2} - \frac{i\sqrt{3}}{2}\right)^2 + 5k + \frac{9}{2} - \frac{5i\sqrt{3}}{2}}$$

- Solution for $r = -\frac{1}{2} - \frac{i\sqrt{3}}{2}$

$$\left[y(u) = \sum_{k=0}^{\infty} a_k u^{k - \frac{1}{2} - \frac{i\sqrt{3}}{2}}, a_{k+2} = -\frac{k^2 a_k + 2k^2 a_{k+1} + 2k \left(-\frac{1}{2} - \frac{i\sqrt{3}}{2}\right) a_k + 4k \left(-\frac{1}{2} - \frac{i\sqrt{3}}{2}\right) a_{k+1} + \left(-\frac{1}{2} - \frac{i\sqrt{3}}{2}\right)^2 a_k + 2 \left(-\frac{1}{2} - \frac{i\sqrt{3}}{2}\right)^2 a_{k+1} - k a_k + 2k a_{k+1} - \left(-\frac{1}{2} - \frac{i\sqrt{3}}{2}\right) a_k + 2 \left(-\frac{1}{2} - \frac{i\sqrt{3}}{2}\right) a_{k+1}}{k^2 + 2k \left(-\frac{1}{2} - \frac{i\sqrt{3}}{2}\right) + \left(-\frac{1}{2} - \frac{i\sqrt{3}}{2}\right)^2 + 5k + \frac{9}{2} - \frac{5i\sqrt{3}}{2}} \right]$$

- Revert the change of variables $u = x - 1$

$$\left[y = \sum_{k=0}^{\infty} a_k (x - 1)^{k - \frac{1}{2} - \frac{i\sqrt{3}}{2}}, a_{k+2} = -\frac{k^2 a_k + 2k^2 a_{k+1} + 2k \left(-\frac{1}{2} - \frac{i\sqrt{3}}{2}\right) a_k + 4k \left(-\frac{1}{2} - \frac{i\sqrt{3}}{2}\right) a_{k+1} + \left(-\frac{1}{2} - \frac{i\sqrt{3}}{2}\right)^2 a_k + 2 \left(-\frac{1}{2} - \frac{i\sqrt{3}}{2}\right)^2 a_{k+1} - k a_k + 2k a_{k+1} - \left(-\frac{1}{2} - \frac{i\sqrt{3}}{2}\right) a_k + 2 \left(-\frac{1}{2} - \frac{i\sqrt{3}}{2}\right) a_{k+1}}{k^2 + 2k \left(-\frac{1}{2} - \frac{i\sqrt{3}}{2}\right) + \left(-\frac{1}{2} - \frac{i\sqrt{3}}{2}\right)^2 + 5k + \frac{9}{2} - \frac{5i\sqrt{3}}{2}} \right]$$

- Recursion relation for $r = -\frac{1}{2} + \frac{i\sqrt{3}}{2}$

$$a_{k+2} = -\frac{k^2 a_k + 2k^2 a_{k+1} + 2k \left(-\frac{1}{2} + \frac{i\sqrt{3}}{2}\right) a_k + 4k \left(-\frac{1}{2} + \frac{i\sqrt{3}}{2}\right) a_{k+1} + \left(-\frac{1}{2} + \frac{i\sqrt{3}}{2}\right)^2 a_k + 2 \left(-\frac{1}{2} + \frac{i\sqrt{3}}{2}\right)^2 a_{k+1} - k a_k + 2k a_{k+1} - \left(-\frac{1}{2} + \frac{i\sqrt{3}}{2}\right) a_k + 2 \left(-\frac{1}{2} + \frac{i\sqrt{3}}{2}\right) a_{k+1}}{k^2 + 2k \left(-\frac{1}{2} + \frac{i\sqrt{3}}{2}\right) + \left(-\frac{1}{2} + \frac{i\sqrt{3}}{2}\right)^2 + 5k + \frac{9}{2} + \frac{5i\sqrt{3}}{2}}$$

- Solution for $r = -\frac{1}{2} + \frac{i\sqrt{3}}{2}$

$$\left[y(u) = \sum_{k=0}^{\infty} a_k u^{k - \frac{1}{2} + \frac{i\sqrt{3}}{2}}, a_{k+2} = -\frac{k^2 a_k + 2k^2 a_{k+1} + 2k \left(-\frac{1}{2} + \frac{i\sqrt{3}}{2}\right) a_k + 4k \left(-\frac{1}{2} + \frac{i\sqrt{3}}{2}\right) a_{k+1} + \left(-\frac{1}{2} + \frac{i\sqrt{3}}{2}\right)^2 a_k + 2 \left(-\frac{1}{2} + \frac{i\sqrt{3}}{2}\right)^2 a_{k+1} - k a_k + 2k a_{k+1} - \left(-\frac{1}{2} + \frac{i\sqrt{3}}{2}\right) a_k + 2 \left(-\frac{1}{2} + \frac{i\sqrt{3}}{2}\right) a_{k+1}}{k^2 + 2k \left(-\frac{1}{2} + \frac{i\sqrt{3}}{2}\right) + \left(-\frac{1}{2} + \frac{i\sqrt{3}}{2}\right)^2 + 5k + \frac{9}{2} + \frac{5i\sqrt{3}}{2}} \right]$$

- Revert the change of variables $u = x - 1$

$$\left[y = \sum_{k=0}^{\infty} a_k (x-1)^{k-\frac{1}{2}+\frac{i\sqrt{3}}{2}}, a_{k+2} = -\frac{k^2 a_k + 2k^2 a_{k+1} + 2k\left(-\frac{1}{2}+\frac{i\sqrt{3}}{2}\right)a_k + 4k\left(-\frac{1}{2}+\frac{i\sqrt{3}}{2}\right)a_{k+1} + \left(-\frac{1}{2}+\frac{i\sqrt{3}}{2}\right)^2 a_k + 2\left(-\frac{1}{2}+\frac{i\sqrt{3}}{2}\right)a_{k+1}}{k^2 + 2k\left(-\frac{1}{2}+\frac{i\sqrt{3}}{2}\right) + \left(-\frac{1}{2}+\frac{i\sqrt{3}}{2}\right)^2} \right]$$

- Combine solutions and rename parameters


$$\left[y = \left(\sum_{k=0}^{\infty} a_k (x-1)^{k-\frac{1}{2}-\frac{i\sqrt{3}}{2}} \right) + \left(\sum_{k=0}^{\infty} b_k (x-1)^{k-\frac{1}{2}+\frac{i\sqrt{3}}{2}} \right), a_{k+2} = -\frac{k^2 a_k + 2k^2 a_{k+1} + 2k\left(-\frac{1}{2}-\frac{i\sqrt{3}}{2}\right)a_k + 4k\left(-\frac{1}{2}-\frac{i\sqrt{3}}{2}\right)a_{k+1} + \left(-\frac{1}{2}-\frac{i\sqrt{3}}{2}\right)^2 a_k + 2\left(-\frac{1}{2}-\frac{i\sqrt{3}}{2}\right)a_{k+1}}{k^2 + 2k\left(-\frac{1}{2}-\frac{i\sqrt{3}}{2}\right) + \left(-\frac{1}{2}-\frac{i\sqrt{3}}{2}\right)^2} \right]$$

Maple trace

```


`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
trying a symmetry of the form [xi=0, eta=F(x)]
checking if the LODE is missing y
-> Trying a Liouvillian solution using Kovacic's algorithm
<- No Liouvillian solutions exist
-> Trying a solution in terms of special functions:
  -> Bessel
  -> elliptic
  -> Legendre
  -> Kummer
    -> hyper3: Equivalence to 1F1 under a power @ Moebius
  -> hypergeometric
    -> heuristic approach
    -> hyper3: Equivalence to 2F1, 1F1 or 0F1 under a power @ Moebius
  -> Mathieu
    -> Equivalence to the rational form of Mathieu ODE under a power @ Moebius
trying a solution in terms of MeijerG functions
-> Heun: Equivalence to the GHE or one of its 4 confluent cases under a power @ Moebius
<- Heun successful: received ODE is equivalent to the HeunC ODE, case a = 0, e <> 0, c <> 0

```

 Solution by Maple

```
Order:=6;  
dsolve((x^4-2*x^3+x^2)*diff(y(x),x$2)+2*(x-1)*diff(y(x),x)+x^2*y(x)=0,y(x),type='series',x=0
```

No solution found

 Solution by Mathematica

Time used: 0.047 (sec). Leaf size: 71

```
AsymptoticDSolveValue[(x^4-2*x^3+x^2)*y'[x]+2*(x-1)*y'[x]+x^2*y[x]==0,y[x],{x,0,5}]
```

$$y(x) \rightarrow c_1 \left(\frac{3x^5}{10} + \frac{x^4}{4} + \frac{x^3}{6} + 1 \right) + c_2 e^{-2/x} \left(-\frac{429x^5}{5} + \frac{91x^4}{4} - \frac{31x^3}{6} + 3x^2 + 1 \right) x^4$$

15.4 problem 4

15.4.1 Maple step by step solution 4065

Internal problem ID [11905]

Internal file name [OUTPUT/11914_Saturday_April_13_2024_10_26_15_PM_30461767/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.2 (Frobenius). Exercises page 251

Problem number: 4.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"second order series method. Irregular singular point"**

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

Unable to solve or complete the solution.

$$(x^5 + x^4 - 6x^3) y'' + x^2 y' + y(x - 2) = 0$$

With the expansion point for the power series method at $x = 0$.

The type of the expansion point is first determined. This is done on the homogeneous part of the ODE.

$$(x^5 + x^4 - 6x^3) y'' + x^2 y' + y(x - 2) = 0$$

The following is summary of singularities for the above ode. Writing the ode as

$$y'' + p(x)y' + q(x)y = 0$$

Where

$$p(x) = \frac{1}{x(x^2 + x - 6)}$$
$$q(x) = \frac{1}{x^3(x + 3)}$$

Table 533: Table $p(x), q(x)$ singularities.

$p(x) = \frac{1}{x(x^2+x-6)}$	
singularity	type
$x = -3$	“regular”
$x = 0$	“regular”
$x = 2$	“regular”

$q(x) = \frac{1}{x^3(x+3)}$	
singularity	type
$x = -3$	“regular”
$x = 0$	“irregular”

Combining everything together gives the following summary of singularities for the ode as

Regular singular points : $[-3, 2, \infty]$

Irregular singular points : $[0]$

Since $x = 0$ is not an ordinary point, then we will now check if it is a regular singular point. Unable to solve since $x = 0$ is not regular singular point. Terminating.

Verification of solutions N/A

15.4.1 Maple step by step solution

Let's solve

$$(x^5 + x^4 - 6x^3)y'' + x^2y' + y(x - 2) = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = -\frac{y}{x^3(x+3)} - \frac{y'}{x(x^2+x-6)}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + \frac{y'}{x(x^2+x-6)} + \frac{y}{x^3(x+3)} = 0$$

- Check to see if x_0 is a regular singular point

- Define functions

$$\left[P_2(x) = \frac{1}{x(x^2+x-6)}, P_3(x) = \frac{1}{x^3(x+3)} \right]$$

- $(x + 3) \cdot P_2(x)$ is analytic at $x = -3$

$$((x+3) \cdot P_2(x)) \Big|_{x=-3} = \frac{1}{15}$$

- $(x+3)^2 \cdot P_3(x)$ is analytic at $x = -3$

$$((x+3)^2 \cdot P_3(x)) \Big|_{x=-3} = 0$$

- $x = -3$ is a regular singular point

Check to see if x_0 is a regular singular point

$$x_0 = -3$$

- Multiply by denominators

$$y''x^3(x^2+x-6)(x+3) + y'x^2(x+3) + y(x^2+x-6) = 0$$

- Change variables using $x = u - 3$ so that the regular singular point is at $u = 0$

$$(u^6 - 14u^5 + 72u^4 - 162u^3 + 135u^2) \left(\frac{d^2}{du^2} y(u) \right) + (u^3 - 6u^2 + 9u) \left(\frac{d}{du} y(u) \right) + (u^2 - 5u) y(u) = 0$$

- Assume series solution for $y(u)$

$$y(u) = \sum_{k=0}^{\infty} a_k u^{k+r}$$

- Rewrite ODE with series expansions

- Convert $u^m \cdot y(u)$ to series expansion for $m = 1..2$

$$u^m \cdot y(u) = \sum_{k=0}^{\infty} a_k u^{k+r+m}$$

- Shift index using $k \rightarrow k - m$

$$u^m \cdot y(u) = \sum_{k=m}^{\infty} a_{k-m} u^{k+r}$$

- Convert $u^m \cdot \left(\frac{d}{du} y(u) \right)$ to series expansion for $m = 1..3$

$$u^m \cdot \left(\frac{d}{du} y(u) \right) = \sum_{k=0}^{\infty} a_k (k+r) u^{k+r-1+m}$$

- Shift index using $k \rightarrow k + 1 - m$

$$u^m \cdot \left(\frac{d}{du} y(u) \right) = \sum_{k=-1+m}^{\infty} a_{k+1-m} (k+1-m+r) u^{k+r}$$

- Convert $u^m \cdot \left(\frac{d^2}{du^2} y(u) \right)$ to series expansion for $m = 2..6$

$$u^m \cdot \left(\frac{d^2}{du^2} y(u) \right) = \sum_{k=0}^{\infty} a_k (k+r)(k+r-1) u^{k+r-2+m}$$

- Shift index using $k \rightarrow k + 2 - m$

$$u^m \cdot \left(\frac{d^2}{du^2} y(u) \right) = \sum_{k=-2+m}^{\infty} a_{k+2-m} (k+2-m+r) (k+1-m+r) u^{k+r}$$

Rewrite ODE with series expansions

$$9a_0 r(-14+15r) u^r + (9a_1(1+r)(1+15r) - a_0(162r^2 - 156r + 5)) u^{1+r} + (9a_2(2+r)(16+15r) - a_1(162r^2 - 156r + 5)) u^{2+r} + \dots$$

- a_0 cannot be 0 by assumption, giving the indicial equation

$$9r(-14+15r) = 0$$

- Values of r that satisfy the indicial equation

$$r \in \left\{ 0, \frac{14}{15} \right\}$$

- The coefficients of each power of u must be 0

$$[9a_1(1+r)(1+15r) - a_0(162r^2 - 156r + 5)] = 0, [9a_2(2+r)(16+15r) - a_1(162r^2 - 156r + 5)] = 0, \dots$$

- Solve for the dependent coefficient(s)

$$\left\{ a_1 = \frac{a_0(162r^2 - 156r + 5)}{9(15r^2 + 16r + 1)}, a_2 = \frac{a_0(16524r^4 + 1161r^3 - 14175r^2 - 381r + 46)}{81(225r^4 + 930r^3 + 1231r^2 + 558r + 32)}, a_3 = \frac{a_0(1357398r^6 + 4208274r^5 + 2090772r^4 - 3111111r^3 + 1111111r^2 - 111111r + 11111)}{729(3375r^6 + 31050r^5 + 110070r^4 + 18480r^3 + 111111r^2 - 111111r + 11111)} \right.$$

- Each term in the series must be 0, giving the recursion relation

$$(135a_k + a_{k-4} - 14a_{k-3} + 72a_{k-2} - 162a_{k-1}) k^2 + (2(135a_k + a_{k-4} - 14a_{k-3} + 72a_{k-2} - 162a_{k-1}) k + 14a_{k-3} - 72a_{k-2} + 162a_{k-1} - 135a_k) k + 14a_{k-3} - 72a_{k-2} + 162a_{k-1} - 135a_k = 0$$

- Shift index using $k \rightarrow k+4$

$$(135a_{k+4} + a_k - 14a_{k+1} + 72a_{k+2} - 162a_{k+3}) (k+4)^2 + (2(135a_{k+4} + a_k - 14a_{k+1} + 72a_{k+2} - 162a_{k+3}) (k+4) + 14a_{k+1} - 72a_{k+2} + 162a_{k+3} - 135a_{k+4}) (k+4) + 14a_{k+1} - 72a_{k+2} + 162a_{k+3} - 135a_{k+4} = 0$$

- Recursion relation that defines series solution to ODE

$$a_{k+4} = - \frac{k^2 a_k - 14k^2 a_{k+1} + 72k^2 a_{k+2} - 162k^2 a_{k+3} + 2k r a_k - 28k r a_{k+1} + 144k r a_{k+2} - 324k r a_{k+3} + r^2 a_k - 14r^2 a_{k+1} + 72r^2 a_{k+2} - 162r^2 a_{k+3}}{9(15k^2 + 30kr + 15r^2 + 106k + 184)}$$

- Recursion relation for $r = 0$

$$a_{k+4} = - \frac{k^2 a_k - 14k^2 a_{k+1} + 72k^2 a_{k+2} - 162k^2 a_{k+3} - k a_k - 14k a_{k+1} + 217k a_{k+2} - 816k a_{k+3} + 147a_{k+2} - 995a_{k+3}}{9(15k^2 + 106k + 184)}$$

- Solution for $r = 0$

$$\left[y(u) = \sum_{k=0}^{\infty} a_k u^k, a_{k+4} = - \frac{k^2 a_k - 14k^2 a_{k+1} + 72k^2 a_{k+2} - 162k^2 a_{k+3} - k a_k - 14k a_{k+1} + 217k a_{k+2} - 816k a_{k+3} + 147a_{k+2} - 995a_{k+3}}{9(15k^2 + 106k + 184)} \right]$$

- Revert the change of variables $u = x + 3$

$$\left[y = \sum_{k=0}^{\infty} a_k (x+3)^k, a_{k+4} = - \frac{k^2 a_k - 14k^2 a_{k+1} + 72k^2 a_{k+2} - 162k^2 a_{k+3} - k a_k - 14k a_{k+1} + 217k a_{k+2} - 816k a_{k+3} + 147a_{k+2} - 995a_{k+3}}{9(15k^2 + 106k + 184)} \right]$$

- Recursion relation for $r = \frac{14}{15}$

$$a_{k+4} = - \frac{k^2 a_k - 14k^2 a_{k+1} + 72k^2 a_{k+2} - 162k^2 a_{k+3} + \frac{13}{15} k a_k - \frac{602}{15} k a_{k+1} + \frac{1757}{5} k a_{k+2} - \frac{5592}{5} k a_{k+3} - \frac{14}{225} a_k - \frac{5684}{225} a_{k+1} + \frac{30919}{75} a_{k+2} - \frac{10991}{75} a_{k+3}}{9(15k^2 + 134k + 296)}$$

- Solution for $r = \frac{14}{15}$

$$\left[y(u) = \sum_{k=0}^{\infty} a_k u^{k+\frac{14}{15}}, a_{k+4} = -\frac{k^2 a_k - 14k^2 a_{k+1} + 72k^2 a_{k+2} - 162k^2 a_{k+3} + \frac{13}{15} k a_k - \frac{602}{15} k a_{k+1} + \frac{1757}{5} k a_{k+2} - \frac{5592}{5} k a_{k+3} - \frac{1}{2}}{9(15k^2 + 134k + 296)} \right.$$

- Revert the change of variables $u = x + 3$

$$\left[y = \sum_{k=0}^{\infty} a_k (x + 3)^{k+\frac{14}{15}}, a_{k+4} = -\frac{k^2 a_k - 14k^2 a_{k+1} + 72k^2 a_{k+2} - 162k^2 a_{k+3} + \frac{13}{15} k a_k - \frac{602}{15} k a_{k+1} + \frac{1757}{5} k a_{k+2} - \frac{5592}{5} k a_{k+3} - \frac{1}{2}}{9(15k^2 + 134k + 296)} \right.$$

- Combine solutions and rename parameters

$$\left[y = \left(\sum_{k=0}^{\infty} a_k (x + 3)^k \right) + \left(\sum_{k=0}^{\infty} b_k (x + 3)^{k+\frac{14}{15}} \right), a_{k+4} = -\frac{k^2 a_k - 14k^2 a_{1+k} + 72k^2 a_{k+2} - 162k^2 a_{k+3} - k a_k - 14k a_{k+1} + 72k a_{k+2} - 162k a_{k+3} - \frac{13}{15} k a_k + \frac{602}{15} k a_{k+1} - \frac{1757}{5} k a_{k+2} + \frac{5592}{5} k a_{k+3} - \frac{1}{2}}{9(15k^2 + 106k + 100)} \right.$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
trying a symmetry of the form [xi=0, eta=F(x)]
checking if the LODE is missing y
-> Trying a Liouvillian solution using Kovacic's algorithm
<- No Liouvillian solutions exist
-> Trying a solution in terms of special functions:
  -> Bessel
  -> elliptic
  -> Legendre
  -> Kummer
    -> hyper3: Equivalence to 1F1 under a power @ Moebius
  -> hypergeometric
    -> heuristic approach
    -> hyper3: Equivalence to 2F1, 1F1 or 0F1 under a power @ Moebius
  -> Mathieu
    -> Equivalence to the rational form of Mathieu ODE under a power @ Moebius
trying a solution in terms of MeijerG functions
-> Heun: Equivalence to the GHE or one of its 4 confluent cases under a power @ Moebius
<- Heun successful: received ODE is equivalent to the HeunC ODE, case a <> 0, e <> 0, c <> 0

```

X Solution by Maple

Order:=6;

dsolve((x^5+x^4-6*x^3)*diff(y(x),x\$2)+x^2*diff(y(x),x)+(x-2)*y(x)=0,y(x),type='series',x=0);

No solution found

✓ Solution by Mathematica

Time used: 0.226 (sec). Leaf size: 282

AsymptoticDSolveValue[(x^5+x^4-6*x^3)*y'[x]+x^2*y'[x]+(x-2)*y[x]==0,y[x],{x,0,5}]

$$y(x) \rightarrow c_1 e^{-\frac{2i}{\sqrt{3}\sqrt{x}}x^{5/6}} \left(-\frac{70670717962217ix^{9/2}}{8463329722368\sqrt{3}} + \frac{454703707ix^{7/2}}{544195584\sqrt{3}} - \frac{287057ix^{5/2}}{1679616\sqrt{3}} + \frac{22ix^{3/2}}{243\sqrt{3}} \right. \\ \left. + \frac{28128149072197063x^5}{1523399350026240} - \frac{222818846149x^4}{156728328192} + \frac{35197783x^3}{181398528} - \frac{14123x^2}{279936} + \frac{17x}{216} - \frac{7i\sqrt{x}}{6\sqrt{3}} \right. \\ \left. + 1 \right) + c_2 e^{\frac{2i}{\sqrt{3}\sqrt{x}}x^{5/6}} \left(\frac{70670717962217ix^{9/2}}{8463329722368\sqrt{3}} - \frac{454703707ix^{7/2}}{544195584\sqrt{3}} + \frac{287057ix^{5/2}}{1679616\sqrt{3}} - \frac{22ix^{3/2}}{243\sqrt{3}} + \frac{28128149072197}{152339935002} \right)$$

15.5 problem 5

15.5.1 Maple step by step solution 4078

Internal problem ID [11906]

Internal file name [OUTPUT/11915_Saturday_April_13_2024_10_26_16_PM_34342693/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.2 (Frobenius). Exercises page 251

Problem number: 5.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"second order series method. Regular singular point. Difference not integer"**

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$2x^2y'' + y'x + y(x^2 - 1) = 0$$

With the expansion point for the power series method at $x = 0$.

The type of the expansion point is first determined. This is done on the homogeneous part of the ODE.

$$2x^2y'' + y'x + y(x^2 - 1) = 0$$

The following is summary of singularities for the above ode. Writing the ode as

$$y'' + p(x)y' + q(x)y = 0$$

Where

$$p(x) = \frac{1}{2x}$$
$$q(x) = \frac{x^2 - 1}{2x^2}$$

Table 535: Table $p(x), q(x)$ singularities.

$p(x) = \frac{1}{2x}$	
singularity	type
$x = 0$	“regular”

$q(x) = \frac{x^2-1}{2x^2}$	
singularity	type
$x = 0$	“regular”

Combining everything together gives the following summary of singularities for the ode as

Regular singular points : $[0]$

Irregular singular points : $[\infty]$

Since $x = 0$ is regular singular point, then Frobenius power series is used. The ode is normalized to be

$$2x^2y'' + y'x + y(x^2 - 1) = 0$$

Let the solution be represented as Frobenius power series of the form

$$y = \sum_{n=0}^{\infty} a_n x^{n+r}$$

Then

$$y' = \sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1}$$

$$y'' = \sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2}$$

Substituting the above back into the ode gives

$$2 \left(\sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2} \right) x^2 + \left(\sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1} \right) x + \left(\sum_{n=0}^{\infty} a_n x^{n+r} \right) (x^2 - 1) = 0 \quad (1)$$

Which simplifies to

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} 2x^{n+r} a_n (n+r) (n+r-1) \right) + \left(\sum_{n=0}^{\infty} x^{n+r} a_n (n+r) \right) \\ & + \left(\sum_{n=0}^{\infty} x^{n+r+2} a_n \right) + \sum_{n=0}^{\infty} (-a_n x^{n+r}) = 0 \end{aligned} \quad (2A)$$

The next step is to make all powers of x be $n+r$ in each summation term. Going over each summation term above with power of x in it which is not already x^{n+r} and adjusting the power and the corresponding index gives

$$\sum_{n=0}^{\infty} x^{n+r+2} a_n = \sum_{n=2}^{\infty} a_{n-2} x^{n+r}$$

Substituting all the above in Eq (2A) gives the following equation where now all powers of x are the same and equal to $n+r$.

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} 2x^{n+r} a_n (n+r) (n+r-1) \right) + \left(\sum_{n=0}^{\infty} x^{n+r} a_n (n+r) \right) \\ & + \left(\sum_{n=2}^{\infty} a_{n-2} x^{n+r} \right) + \sum_{n=0}^{\infty} (-a_n x^{n+r}) = 0 \end{aligned} \quad (2B)$$

The indicial equation is obtained from $n=0$. From Eq (2B) this gives

$$2x^{n+r} a_n (n+r) (n+r-1) + x^{n+r} a_n (n+r) - a_n x^{n+r} = 0$$

When $n=0$ the above becomes

$$2x^r a_0 r (-1+r) + x^r a_0 r - a_0 x^r = 0$$

Or

$$(2x^r r (-1+r) + x^r r - x^r) a_0 = 0$$

Since $a_0 \neq 0$ then the above simplifies to

$$(2r^2 - r - 1) x^r = 0$$

Since the above is true for all x then the indicial equation becomes

$$2r^2 - r - 1 = 0$$

Solving for r gives the roots of the indicial equation as

$$\begin{aligned} r_1 &= 1 \\ r_2 &= -\frac{1}{2} \end{aligned}$$

Since $a_0 \neq 0$ then the indicial equation becomes

$$(2r^2 - r - 1) x^r = 0$$

Solving for r gives the roots of the indicial equation as Since $r_1 - r_2 = \frac{3}{2}$ is not an integer, then we can construct two linearly independent solutions

$$\begin{aligned} y_1(x) &= x^{r_1} \left(\sum_{n=0}^{\infty} a_n x^n \right) \\ y_2(x) &= x^{r_2} \left(\sum_{n=0}^{\infty} b_n x^n \right) \end{aligned}$$

Or

$$\begin{aligned} y_1(x) &= \sum_{n=0}^{\infty} a_n x^{n+1} \\ y_2(x) &= \sum_{n=0}^{\infty} b_n x^{n-\frac{1}{2}} \end{aligned}$$

We start by finding $y_1(x)$. Eq (2B) derived above is now used to find all a_n coefficients. The case $n = 0$ is skipped since it was used to find the roots of the indicial equation. a_0 is arbitrary and taken as $a_0 = 1$. Substituting $n = 1$ in Eq. (2B) gives

$$a_1 = 0$$

For $2 \leq n$ the recursive equation is

$$2a_n(n+r)(n+r-1) + a_n(n+r) + a_{n-2} - a_n = 0 \quad (3)$$

Solving for a_n from recursive equation (4) gives

$$a_n = -\frac{a_{n-2}}{2n^2 + 4nr + 2r^2 - n - r - 1} \quad (4)$$

Which for the root $r = 1$ becomes

$$a_n = -\frac{a_{n-2}}{n(2n+3)} \quad (5)$$

At this point, it is a good idea to keep track of a_n in a table both before substituting $r = 1$ and after as more terms are found using the above recursive equation.

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0

For $n = 2$, using the above recursive equation gives

$$a_2 = -\frac{1}{2r^2 + 7r + 5}$$

Which for the root $r = 1$ becomes

$$a_2 = -\frac{1}{14}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{1}{2r^2+7r+5}$	$-\frac{1}{14}$

For $n = 3$, using the above recursive equation gives

$$a_3 = 0$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{1}{2r^2+7r+5}$	$-\frac{1}{14}$
a_3	0	0

For $n = 4$, using the above recursive equation gives

$$a_4 = \frac{1}{4r^4 + 44r^3 + 169r^2 + 264r + 135}$$

Which for the root $r = 1$ becomes

$$a_4 = \frac{1}{616}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{1}{2r^2+7r+5}$	$-\frac{1}{14}$
a_3	0	0
a_4	$\frac{1}{4r^4+44r^3+169r^2+264r+135}$	$\frac{1}{616}$

For $n = 5$, using the above recursive equation gives

$$a_5 = 0$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{1}{2r^2+7r+5}$	$-\frac{1}{14}$
a_3	0	0
a_4	$\frac{1}{4r^4+44r^3+169r^2+264r+135}$	$\frac{1}{616}$
a_5	0	0

Using the above table, then the solution $y_1(x)$ is

$$\begin{aligned} y_1(x) &= x(a_0 + a_1x + a_2x^2 + a_3x^3 + a_4x^4 + a_5x^5 + a_6x^6 \dots) \\ &= x\left(1 - \frac{x^2}{14} + \frac{x^4}{616} + O(x^6)\right) \end{aligned}$$

Now the second solution $y_2(x)$ is found. Eq (2B) derived above is now used to find all b_n coefficients. The case $n = 0$ is skipped since it was used to find the roots of the indicial equation. b_0 is arbitrary and taken as $b_0 = 1$. Substituting $n = 1$ in Eq. (2B) gives

$$b_1 = 0$$

For $2 \leq n$ the recursive equation is

$$2b_n(n+r)(n+r-1) + b_n(n+r) + b_{n-2} - b_n = 0 \quad (3)$$

Solving for b_n from recursive equation (4) gives

$$b_n = -\frac{b_{n-2}}{2n^2 + 4nr + 2r^2 - n - r - 1} \quad (4)$$

Which for the root $r = -\frac{1}{2}$ becomes

$$b_n = -\frac{b_{n-2}}{n(2n-3)} \quad (5)$$

At this point, it is a good idea to keep track of b_n in a table both before substituting $r = -\frac{1}{2}$ and after as more terms are found using the above recursive equation.

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0

For $n = 2$, using the above recursive equation gives

$$b_2 = -\frac{1}{2r^2 + 7r + 5}$$

Which for the root $r = -\frac{1}{2}$ becomes

$$b_2 = -\frac{1}{2}$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0
b_2	$-\frac{1}{2r^2+7r+5}$	$-\frac{1}{2}$

For $n = 3$, using the above recursive equation gives

$$b_3 = 0$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0
b_2	$-\frac{1}{2r^2+7r+5}$	$-\frac{1}{2}$
b_3	0	0

For $n = 4$, using the above recursive equation gives

$$b_4 = \frac{1}{4r^4 + 44r^3 + 169r^2 + 264r + 135}$$

Which for the root $r = -\frac{1}{2}$ becomes

$$b_4 = \frac{1}{40}$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0
b_2	$-\frac{1}{2r^2+7r+5}$	$-\frac{1}{2}$
b_3	0	0
b_4	$\frac{1}{4r^4+44r^3+169r^2+264r+135}$	$\frac{1}{40}$

For $n = 5$, using the above recursive equation gives

$$b_5 = 0$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0
b_2	$-\frac{1}{2r^2+7r+5}$	$-\frac{1}{2}$
b_3	0	0
b_4	$\frac{1}{4r^4+44r^3+169r^2+264r+135}$	$\frac{1}{40}$
b_5	0	0

Using the above table, then the solution $y_2(x)$ is

$$\begin{aligned} y_2(x) &= x(b_0 + b_1x + b_2x^2 + b_3x^3 + b_4x^4 + b_5x^5 + b_6x^6 \dots) \\ &= \frac{1 - \frac{x^2}{2} + \frac{x^4}{40} + O(x^6)}{\sqrt{x}} \end{aligned}$$

Therefore the homogeneous solution is

$$\begin{aligned} y_h(x) &= c_1y_1(x) + c_2y_2(x) \\ &= c_1x \left(1 - \frac{x^2}{14} + \frac{x^4}{616} + O(x^6) \right) + \frac{c_2 \left(1 - \frac{x^2}{2} + \frac{x^4}{40} + O(x^6) \right)}{\sqrt{x}} \end{aligned}$$

Hence the final solution is

$$\begin{aligned} y &= y_h \\ &= c_1x \left(1 - \frac{x^2}{14} + \frac{x^4}{616} + O(x^6) \right) + \frac{c_2 \left(1 - \frac{x^2}{2} + \frac{x^4}{40} + O(x^6) \right)}{\sqrt{x}} \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1x \left(1 - \frac{x^2}{14} + \frac{x^4}{616} + O(x^6) \right) + \frac{c_2 \left(1 - \frac{x^2}{2} + \frac{x^4}{40} + O(x^6) \right)}{\sqrt{x}} \quad (1)$$

Verification of solutions

$$y = c_1x \left(1 - \frac{x^2}{14} + \frac{x^4}{616} + O(x^6) \right) + \frac{c_2 \left(1 - \frac{x^2}{2} + \frac{x^4}{40} + O(x^6) \right)}{\sqrt{x}}$$

Verified OK.

15.5.1 Maple step by step solution

Let's solve

$$2y''x^2 + y'x + y(x^2 - 1) = 0$$

- Highest derivative means the order of the ODE is 2

y''

- Isolate 2nd derivative

$$y'' = -\frac{(x^2-1)y}{2x^2} - \frac{y'}{2x}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + \frac{y'}{2x} + \frac{(x^2-1)y}{2x^2} = 0$$

- Check to see if $x_0 = 0$ is a regular singular point

- Define functions

$$\left[P_2(x) = \frac{1}{2x}, P_3(x) = \frac{x^2-1}{2x^2} \right]$$

- $x \cdot P_2(x)$ is analytic at $x = 0$

$$(x \cdot P_2(x)) \Big|_{x=0} = \frac{1}{2}$$

- $x^2 \cdot P_3(x)$ is analytic at $x = 0$

$$(x^2 \cdot P_3(x)) \Big|_{x=0} = -\frac{1}{2}$$

- $x = 0$ is a regular singular point

Check to see if $x_0 = 0$ is a regular singular point

$$x_0 = 0$$

- Multiply by denominators

$$2y''x^2 + y'x + y(x^2 - 1) = 0$$

- Assume series solution for y

$$y = \sum_{k=0}^{\infty} a_k x^{k+r}$$

- Rewrite ODE with series expansions

- Convert $x^m \cdot y$ to series expansion for $m = 0..2$

$$x^m \cdot y = \sum_{k=0}^{\infty} a_k x^{k+r+m}$$

- Shift index using $k \rightarrow k - m$

$$x^m \cdot y = \sum_{k=m}^{\infty} a_{k-m} x^{k+r}$$

- Convert $x \cdot y'$ to series expansion

$$x \cdot y' = \sum_{k=0}^{\infty} a_k (k+r) x^{k+r}$$

- Convert $x^2 \cdot y''$ to series expansion

$$x^2 \cdot y'' = \sum_{k=0}^{\infty} a_k (k+r)(k+r-1) x^{k+r}$$

Rewrite ODE with series expansions

$$a_0(1+2r)(-1+r)x^r + a_1(3+2r)rx^{1+r} + \left(\sum_{k=2}^{\infty} (a_k(2k+2r+1)(k+r-1) + a_{k-2})x^{k+r} \right) =$$

- a_0 cannot be 0 by assumption, giving the indicial equation
 $(1+2r)(-1+r) = 0$
- Values of r that satisfy the indicial equation
 $r \in \{1, -\frac{1}{2}\}$
- Each term must be 0
 $a_1(3+2r)r = 0$
- Solve for the dependent coefficient(s)
 $a_1 = 0$
- Each term in the series must be 0, giving the recursion relation
 $2(k+r-1)(k+r+\frac{1}{2})a_k + a_{k-2} = 0$
- Shift index using $k- > k+2$
 $2(k+1+r)(k+\frac{5}{2}+r)a_{k+2} + a_k = 0$
- Recursion relation that defines series solution to ODE
 $a_{k+2} = -\frac{a_k}{(k+1+r)(2k+5+2r)}$
- Recursion relation for $r = 1$
 $a_{k+2} = -\frac{a_k}{(k+2)(2k+7)}$
- Solution for $r = 1$
 $\left[y = \sum_{k=0}^{\infty} a_k x^{k+1}, a_{k+2} = -\frac{a_k}{(k+2)(2k+7)}, a_1 = 0 \right]$
- Recursion relation for $r = -\frac{1}{2}$
 $a_{k+2} = -\frac{a_k}{(k+\frac{1}{2})(2k+4)}$
- Solution for $r = -\frac{1}{2}$
 $\left[y = \sum_{k=0}^{\infty} a_k x^{k-\frac{1}{2}}, a_{k+2} = -\frac{a_k}{(k+\frac{1}{2})(2k+4)}, a_1 = 0 \right]$
- Combine solutions and rename parameters

$$\left[y = \left(\sum_{k=0}^{\infty} a_k x^{1+k} \right) + \left(\sum_{k=0}^{\infty} b_k x^{k-\frac{1}{2}} \right), a_{k+2} = -\frac{a_k}{(k+2)(2k+7)}, a_1 = 0, b_{k+2} = -\frac{b_k}{(k+\frac{1}{2})(2k+4)}, b_1 = 0 \right]$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
trying a symmetry of the form [xi=0, eta=F(x)]
checking if the LODE is missing y
-> Trying a Liouvillian solution using Kovacic's algorithm
<- No Liouvillian solutions exist
-> Trying a solution in terms of special functions:
    -> Bessel
    <- Bessel successful
<- special function solution successful`

```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 33

```

Order:=6;
dsolve(2*x^2*diff(y(x),x^2)+x*diff(y(x),x)+(x^2-1)*y(x)=0,y(x),type='series',x=0);

```

$$y(x) = \frac{c_1 \left(1 - \frac{1}{2}x^2 + \frac{1}{40}x^4 + O(x^6) \right)}{\sqrt{x}} + c_2 x \left(1 - \frac{1}{14}x^2 + \frac{1}{616}x^4 + O(x^6) \right)$$

✓ Solution by Mathematica

Time used: 0.002 (sec). Leaf size: 48

```

AsymptoticDSolveValue[2*x^2*y'[x]+x*y'[x]+(x^2-1)*y[x]==0,y[x],{x,0,5}]

```

$$y(x) \rightarrow c_1 x \left(\frac{x^4}{616} - \frac{x^2}{14} + 1 \right) + \frac{c_2 \left(\frac{x^4}{40} - \frac{x^2}{2} + 1 \right)}{\sqrt{x}}$$

15.6 problem 6

15.6.1 Maple step by step solution 4090

Internal problem ID [11907]

Internal file name [OUTPUT/11916_Saturday_April_13_2024_10_26_17_PM_79930221/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.2 (Frobenius). Exercises page 251

Problem number: 6.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"second order series method. Regular singular point. Difference not integer"**

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$2x^2y'' + y'x + (2x^2 - 3)y = 0$$

With the expansion point for the power series method at $x = 0$.

The type of the expansion point is first determined. This is done on the homogeneous part of the ODE.

$$2x^2y'' + y'x + (2x^2 - 3)y = 0$$

The following is summary of singularities for the above ode. Writing the ode as

$$y'' + p(x)y' + q(x)y = 0$$

Where

$$p(x) = \frac{1}{2x}$$
$$q(x) = \frac{2x^2 - 3}{2x^2}$$

Table 537: Table $p(x), q(x)$ singularities.

$p(x) = \frac{1}{2x}$	
singularity	type
$x = 0$	“regular”

$q(x) = \frac{2x^2-3}{2x^2}$	
singularity	type
$x = 0$	“regular”

Combining everything together gives the following summary of singularities for the ode as

Regular singular points : $[0]$

Irregular singular points : $[\infty]$

Since $x = 0$ is regular singular point, then Frobenius power series is used. The ode is normalized to be

$$2x^2y'' + y'x + (2x^2 - 3)y = 0$$

Let the solution be represented as Frobenius power series of the form

$$y = \sum_{n=0}^{\infty} a_n x^{n+r}$$

Then

$$y' = \sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1}$$

$$y'' = \sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2}$$

Substituting the above back into the ode gives

$$2 \left(\sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2} \right) x^2 + \left(\sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1} \right) x + (2x^2 - 3) \left(\sum_{n=0}^{\infty} a_n x^{n+r} \right) = 0 \quad (1)$$

Which simplifies to

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} 2x^{n+r} a_n (n+r) (n+r-1) \right) + \left(\sum_{n=0}^{\infty} x^{n+r} a_n (n+r) \right) \\ & + \left(\sum_{n=0}^{\infty} 2x^{n+r+2} a_n \right) + \sum_{n=0}^{\infty} (-3a_n x^{n+r}) = 0 \end{aligned} \quad (2A)$$

The next step is to make all powers of x be $n+r$ in each summation term. Going over each summation term above with power of x in it which is not already x^{n+r} and adjusting the power and the corresponding index gives

$$\sum_{n=0}^{\infty} 2x^{n+r+2} a_n = \sum_{n=2}^{\infty} 2a_{n-2} x^{n+r}$$

Substituting all the above in Eq (2A) gives the following equation where now all powers of x are the same and equal to $n+r$.

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} 2x^{n+r} a_n (n+r) (n+r-1) \right) + \left(\sum_{n=0}^{\infty} x^{n+r} a_n (n+r) \right) \\ & + \left(\sum_{n=2}^{\infty} 2a_{n-2} x^{n+r} \right) + \sum_{n=0}^{\infty} (-3a_n x^{n+r}) = 0 \end{aligned} \quad (2B)$$

The indicial equation is obtained from $n=0$. From Eq (2B) this gives

$$2x^{n+r} a_n (n+r) (n+r-1) + x^{n+r} a_n (n+r) - 3a_n x^{n+r} = 0$$

When $n=0$ the above becomes

$$2x^r a_0 r(-1+r) + x^r a_0 r - 3a_0 x^r = 0$$

Or

$$(2x^r r(-1+r) + x^r r - 3x^r) a_0 = 0$$

Since $a_0 \neq 0$ then the above simplifies to

$$(2r^2 - r - 3) x^r = 0$$

Since the above is true for all x then the indicial equation becomes

$$2r^2 - r - 3 = 0$$

Solving for r gives the roots of the indicial equation as

$$\begin{aligned} r_1 &= \frac{3}{2} \\ r_2 &= -1 \end{aligned}$$

Since $a_0 \neq 0$ then the indicial equation becomes

$$(2r^2 - r - 3)x^r = 0$$

Solving for r gives the roots of the indicial equation as Since $r_1 - r_2 = \frac{5}{2}$ is not an integer, then we can construct two linearly independent solutions

$$\begin{aligned} y_1(x) &= x^{r_1} \left(\sum_{n=0}^{\infty} a_n x^n \right) \\ y_2(x) &= x^{r_2} \left(\sum_{n=0}^{\infty} b_n x^n \right) \end{aligned}$$

Or

$$\begin{aligned} y_1(x) &= \sum_{n=0}^{\infty} a_n x^{n+\frac{3}{2}} \\ y_2(x) &= \sum_{n=0}^{\infty} b_n x^{n-1} \end{aligned}$$

We start by finding $y_1(x)$. Eq (2B) derived above is now used to find all a_n coefficients. The case $n = 0$ is skipped since it was used to find the roots of the indicial equation. a_0 is arbitrary and taken as $a_0 = 1$. Substituting $n = 1$ in Eq. (2B) gives

$$a_1 = 0$$

For $2 \leq n$ the recursive equation is

$$2a_n(n+r)(n+r-1) + a_n(n+r) + 2a_{n-2} - 3a_n = 0 \quad (3)$$

Solving for a_n from recursive equation (4) gives

$$a_n = -\frac{2a_{n-2}}{2n^2 + 4nr + 2r^2 - n - r - 3} \quad (4)$$

Which for the root $r = \frac{3}{2}$ becomes

$$a_n = -\frac{2a_{n-2}}{n(2n+5)} \quad (5)$$

At this point, it is a good idea to keep track of a_n in a table both before substituting $r = \frac{3}{2}$ and after as more terms are found using the above recursive equation.

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0

For $n = 2$, using the above recursive equation gives

$$a_2 = -\frac{2}{2r^2 + 7r + 3}$$

Which for the root $r = \frac{3}{2}$ becomes

$$a_2 = -\frac{1}{9}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{2}{2r^2+7r+3}$	$-\frac{1}{9}$

For $n = 3$, using the above recursive equation gives

$$a_3 = 0$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{2}{2r^2+7r+3}$	$-\frac{1}{9}$
a_3	0	0

For $n = 4$, using the above recursive equation gives

$$a_4 = \frac{4}{(2r^2 + 7r + 3)(2r^2 + 15r + 25)}$$

Which for the root $r = \frac{3}{2}$ becomes

$$a_4 = \frac{1}{234}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{2}{2r^2+7r+3}$	$-\frac{1}{9}$
a_3	0	0
a_4	$\frac{4}{(2r^2+7r+3)(2r^2+15r+25)}$	$\frac{1}{234}$

For $n = 5$, using the above recursive equation gives

$$a_5 = 0$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{2}{2r^2+7r+3}$	$-\frac{1}{9}$
a_3	0	0
a_4	$\frac{4}{(2r^2+7r+3)(2r^2+15r+25)}$	$\frac{1}{234}$
a_5	0	0

Using the above table, then the solution $y_1(x)$ is

$$\begin{aligned} y_1(x) &= x^{\frac{3}{2}}(a_0 + a_1x + a_2x^2 + a_3x^3 + a_4x^4 + a_5x^5 + a_6x^6 \dots) \\ &= x^{\frac{3}{2}}\left(1 - \frac{x^2}{9} + \frac{x^4}{234} + O(x^6)\right) \end{aligned}$$

Now the second solution $y_2(x)$ is found. Eq (2B) derived above is now used to find all b_n coefficients. The case $n = 0$ is skipped since it was used to find the roots of the indicial equation. b_0 is arbitrary and taken as $b_0 = 1$. Substituting $n = 1$ in Eq. (2B) gives

$$b_1 = 0$$

For $2 \leq n$ the recursive equation is

$$2b_n(n+r)(n+r-1) + b_n(n+r) + 2b_{n-2} - 3b_n = 0 \quad (3)$$

Solving for b_n from recursive equation (4) gives

$$b_n = -\frac{2b_{n-2}}{2n^2 + 4nr + 2r^2 - n - r - 3} \quad (4)$$

Which for the root $r = -1$ becomes

$$b_n = -\frac{2b_{n-2}}{n(2n-5)} \quad (5)$$

At this point, it is a good idea to keep track of b_n in a table both before substituting $r = -1$ and after as more terms are found using the above recursive equation.

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0

For $n = 2$, using the above recursive equation gives

$$b_2 = -\frac{2}{2r^2 + 7r + 3}$$

Which for the root $r = -1$ becomes

$$b_2 = 1$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0
b_2	$-\frac{2}{2r^2+7r+3}$	1

For $n = 3$, using the above recursive equation gives

$$b_3 = 0$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0
b_2	$-\frac{2}{2r^2+7r+3}$	1
b_3	0	0

For $n = 4$, using the above recursive equation gives

$$b_4 = \frac{4}{(2r^2 + 7r + 3)(2r^2 + 15r + 25)}$$

Which for the root $r = -1$ becomes

$$b_4 = -\frac{1}{6}$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0
b_2	$-\frac{2}{2r^2+7r+3}$	1
b_3	0	0
b_4	$\frac{4}{(2r^2+7r+3)(2r^2+15r+25)}$	$-\frac{1}{6}$

For $n = 5$, using the above recursive equation gives

$$b_5 = 0$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0
b_2	$-\frac{2}{2r^2+7r+3}$	1
b_3	0	0
b_4	$\frac{4}{(2r^2+7r+3)(2r^2+15r+25)}$	$-\frac{1}{6}$
b_5	0	0

Using the above table, then the solution $y_2(x)$ is

$$\begin{aligned} y_2(x) &= x^{\frac{3}{2}}(b_0 + b_1x + b_2x^2 + b_3x^3 + b_4x^4 + b_5x^5 + b_6x^6 \dots) \\ &= \frac{1 + x^2 - \frac{x^4}{6} + O(x^6)}{x} \end{aligned}$$

Therefore the homogeneous solution is

$$\begin{aligned} y_h(x) &= c_1y_1(x) + c_2y_2(x) \\ &= c_1x^{\frac{3}{2}}\left(1 - \frac{x^2}{9} + \frac{x^4}{234} + O(x^6)\right) + \frac{c_2\left(1 + x^2 - \frac{x^4}{6} + O(x^6)\right)}{x} \end{aligned}$$

Hence the final solution is

$$\begin{aligned} y &= y_h \\ &= c_1x^{\frac{3}{2}}\left(1 - \frac{x^2}{9} + \frac{x^4}{234} + O(x^6)\right) + \frac{c_2\left(1 + x^2 - \frac{x^4}{6} + O(x^6)\right)}{x} \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1x^{\frac{3}{2}}\left(1 - \frac{x^2}{9} + \frac{x^4}{234} + O(x^6)\right) + \frac{c_2\left(1 + x^2 - \frac{x^4}{6} + O(x^6)\right)}{x} \quad (1)$$

Verification of solutions

$$y = c_1x^{\frac{3}{2}}\left(1 - \frac{x^2}{9} + \frac{x^4}{234} + O(x^6)\right) + \frac{c_2\left(1 + x^2 - \frac{x^4}{6} + O(x^6)\right)}{x}$$

Verified OK.

15.6.1 Maple step by step solution

Let's solve

$$2y''x^2 + y'x + (2x^2 - 3)y = 0$$

- Highest derivative means the order of the ODE is 2

y''

- Isolate 2nd derivative

$$y'' = -\frac{(2x^2-3)y}{2x^2} - \frac{y'}{2x}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + \frac{y'}{2x} + \frac{(2x^2-3)y}{2x^2} = 0$$

- Check to see if $x_0 = 0$ is a regular singular point

- Define functions

$$\left[P_2(x) = \frac{1}{2x}, P_3(x) = \frac{2x^2-3}{2x^2} \right]$$

- $x \cdot P_2(x)$ is analytic at $x = 0$

$$(x \cdot P_2(x)) \Big|_{x=0} = \frac{1}{2}$$

- $x^2 \cdot P_3(x)$ is analytic at $x = 0$

$$(x^2 \cdot P_3(x)) \Big|_{x=0} = -\frac{3}{2}$$

- $x = 0$ is a regular singular point

Check to see if $x_0 = 0$ is a regular singular point

$$x_0 = 0$$

- Multiply by denominators

$$2y''x^2 + y'x + (2x^2 - 3)y = 0$$

- Assume series solution for y

$$y = \sum_{k=0}^{\infty} a_k x^{k+r}$$

- Rewrite ODE with series expansions

- Convert $x^m \cdot y$ to series expansion for $m = 0..2$

$$x^m \cdot y = \sum_{k=0}^{\infty} a_k x^{k+r+m}$$

- Shift index using $k \rightarrow k - m$

$$x^m \cdot y = \sum_{k=m}^{\infty} a_{k-m} x^{k+r}$$

- Convert $x \cdot y'$ to series expansion

$$x \cdot y' = \sum_{k=0}^{\infty} a_k (k+r) x^{k+r}$$

- Convert $x^2 \cdot y''$ to series expansion

$$x^2 \cdot y'' = \sum_{k=0}^{\infty} a_k (k+r)(k+r-1) x^{k+r}$$

Rewrite ODE with series expansions

$$a_0(1+r)(-3+2r)x^r + a_1(2+r)(-1+2r)x^{1+r} + \left(\sum_{k=2}^{\infty} (a_k(k+r+1)(2k+2r-3) + 2a_{k-2}) \right) x^{k+r}$$

- a_0 cannot be 0 by assumption, giving the indicial equation

$$(1+r)(-3+2r) = 0$$
- Values of r that satisfy the indicial equation

$$r \in \left\{ -1, \frac{3}{2} \right\}$$
- Each term must be 0

$$a_1(2+r)(-1+2r) = 0$$
- Solve for the dependent coefficient(s)

$$a_1 = 0$$
- Each term in the series must be 0, giving the recursion relation

$$2\left(k+r-\frac{3}{2}\right)(k+r+1)a_k + 2a_{k-2} = 0$$
- Shift index using $k \rightarrow k+2$

$$2\left(k+\frac{1}{2}+r\right)(k+3+r)a_{k+2} + 2a_k = 0$$
- Recursion relation that defines series solution to ODE

$$a_{k+2} = -\frac{2a_k}{(2k+1+2r)(k+3+r)}$$
- Recursion relation for $r = -1$

$$a_{k+2} = -\frac{2a_k}{(2k-1)(k+2)}$$
- Solution for $r = -1$

$$\left[y = \sum_{k=0}^{\infty} a_k x^{k-1}, a_{k+2} = -\frac{2a_k}{(2k-1)(k+2)}, a_1 = 0 \right]$$
- Recursion relation for $r = \frac{3}{2}$

$$a_{k+2} = -\frac{2a_k}{(2k+4)\left(k+\frac{9}{2}\right)}$$
- Solution for $r = \frac{3}{2}$

$$\left[y = \sum_{k=0}^{\infty} a_k x^{k+\frac{3}{2}}, a_{k+2} = -\frac{2a_k}{(2k+4)\left(k+\frac{9}{2}\right)}, a_1 = 0 \right]$$
- Combine solutions and rename parameters

$$\left[y = \left(\sum_{k=0}^{\infty} a_k x^{k-1} \right) + \left(\sum_{k=0}^{\infty} b_k x^{k+\frac{3}{2}} \right), a_{k+2} = -\frac{2a_k}{(2k-1)(k+2)}, a_1 = 0, b_{k+2} = -\frac{2b_k}{(2k+4)(k+\frac{9}{2})}, b_1 = 0 \right]$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
trying a symmetry of the form [xi=0, eta=F(x)]
checking if the LODE is missing y
-> Trying a Liouvillian solution using Kovacic's algorithm
<- No Liouvillian solutions exist
-> Trying a solution in terms of special functions:
  -> Bessel
  <- Bessel successful
<- special function solution successful`

```

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 35

```

Order:=6;
dsolve(2*x^2*diff(y(x),x^2)+x*diff(y(x),x)+(2*x^2-3)*y(x)=0,y(x),type='series',x=0);

```

$$y(x) = \frac{c_2 x^{\frac{5}{2}} \left(1 - \frac{1}{9} x^2 + \frac{1}{234} x^4 + O(x^6) \right) + c_1 \left(1 + x^2 - \frac{1}{6} x^4 + O(x^6) \right)}{x}$$

✓ Solution by Mathematica

Time used: 0.003 (sec). Leaf size: 46

```

AsymptoticDSolveValue[2*x^2*y'[x]+x*y'[x]+(2*x^2-3)*y[x]==0,y[x],{x,0,5}]

```

$$y(x) \rightarrow \frac{c_2 \left(-\frac{x^4}{6} + x^2 + 1 \right)}{x} + c_1 \left(\frac{x^4}{234} - \frac{x^2}{9} + 1 \right) x^{3/2}$$

15.7 problem 7

15.7.1 Maple step by step solution 4103

Internal problem ID [11908]

Internal file name [OUTPUT/11917_Saturday_April_13_2024_10_26_18_PM_80034732/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.2 (Frobenius). Exercises page 251

Problem number: 7.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"second order series method. Regular singular point. Difference not integer"**

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$x^2y'' - y'x + \left(x^2 + \frac{8}{9}\right)y = 0$$

With the expansion point for the power series method at $x = 0$.

The type of the expansion point is first determined. This is done on the homogeneous part of the ODE.

$$x^2y'' - y'x + \left(x^2 + \frac{8}{9}\right)y = 0$$

The following is summary of singularities for the above ode. Writing the ode as

$$y'' + p(x)y' + q(x)y = 0$$

Where

$$p(x) = -\frac{1}{x}$$
$$q(x) = \frac{9x^2 + 8}{9x^2}$$

Table 539: Table $p(x), q(x)$ singularities.

$p(x) = -\frac{1}{x}$	
singularity	type
$x = 0$	“regular”

$q(x) = \frac{9x^2+8}{9x^2}$	
singularity	type
$x = 0$	“regular”

Combining everything together gives the following summary of singularities for the ode as

Regular singular points : $[0]$

Irregular singular points : $[\infty]$

Since $x = 0$ is regular singular point, then Frobenius power series is used. The ode is normalized to be

$$x^2 y'' - y'x + \left(x^2 + \frac{8}{9}\right) y = 0$$

Let the solution be represented as Frobenius power series of the form

$$y = \sum_{n=0}^{\infty} a_n x^{n+r}$$

Then

$$y' = \sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1}$$

$$y'' = \sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2}$$

Substituting the above back into the ode gives

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2} \right) x^2 \\ & - \left(\sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1} \right) x + \left(x^2 + \frac{8}{9} \right) \left(\sum_{n=0}^{\infty} a_n x^{n+r} \right) = 0 \end{aligned} \tag{1}$$

Which simplifies to

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} x^{n+r} a_n (n+r) (n+r-1) \right) + \sum_{n=0}^{\infty} (-x^{n+r} a_n (n+r)) \\ & + \left(\sum_{n=0}^{\infty} x^{n+r+2} a_n \right) + \left(\sum_{n=0}^{\infty} \frac{8a_n x^{n+r}}{9} \right) = 0 \end{aligned} \quad (2A)$$

The next step is to make all powers of x be $n+r$ in each summation term. Going over each summation term above with power of x in it which is not already x^{n+r} and adjusting the power and the corresponding index gives

$$\sum_{n=0}^{\infty} x^{n+r+2} a_n = \sum_{n=2}^{\infty} a_{n-2} x^{n+r}$$

Substituting all the above in Eq (2A) gives the following equation where now all powers of x are the same and equal to $n+r$.

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} x^{n+r} a_n (n+r) (n+r-1) \right) + \sum_{n=0}^{\infty} (-x^{n+r} a_n (n+r)) \\ & + \left(\sum_{n=2}^{\infty} a_{n-2} x^{n+r} \right) + \left(\sum_{n=0}^{\infty} \frac{8a_n x^{n+r}}{9} \right) = 0 \end{aligned} \quad (2B)$$

The indicial equation is obtained from $n=0$. From Eq (2B) this gives

$$x^{n+r} a_n (n+r) (n+r-1) - x^{n+r} a_n (n+r) + \frac{8a_n x^{n+r}}{9} = 0$$

When $n=0$ the above becomes

$$x^r a_0 r (-1+r) - x^r a_0 r + \frac{8a_0 x^r}{9} = 0$$

Or

$$\left(x^r r (-1+r) - x^r r + \frac{8x^r}{9} \right) a_0 = 0$$

Since $a_0 \neq 0$ then the above simplifies to

$$\frac{(9r^2 - 18r + 8) x^r}{9} = 0$$

Since the above is true for all x then the indicial equation becomes

$$r^2 - 2r + \frac{8}{9} = 0$$

Solving for r gives the roots of the indicial equation as

$$r_1 = \frac{4}{3}$$

$$r_2 = \frac{2}{3}$$

Since $a_0 \neq 0$ then the indicial equation becomes

$$\frac{(9r^2 - 18r + 8)x^r}{9} = 0$$

Solving for r gives the roots of the indicial equation as Since $r_1 - r_2 = \frac{2}{3}$ is not an integer, then we can construct two linearly independent solutions

$$y_1(x) = x^{r_1} \left(\sum_{n=0}^{\infty} a_n x^n \right)$$

$$y_2(x) = x^{r_2} \left(\sum_{n=0}^{\infty} b_n x^n \right)$$

Or

$$y_1(x) = \sum_{n=0}^{\infty} a_n x^{n+\frac{4}{3}}$$

$$y_2(x) = \sum_{n=0}^{\infty} b_n x^{n+\frac{2}{3}}$$

We start by finding $y_1(x)$. Eq (2B) derived above is now used to find all a_n coefficients. The case $n = 0$ is skipped since it was used to find the roots of the indicial equation. a_0 is arbitrary and taken as $a_0 = 1$. Substituting $n = 1$ in Eq. (2B) gives

$$a_1 = 0$$

For $2 \leq n$ the recursive equation is

$$a_n(n+r)(n+r-1) - a_n(n+r) + a_{n-2} + \frac{8a_n}{9} = 0 \quad (3)$$

Solving for a_n from recursive equation (4) gives

$$a_n = -\frac{9a_{n-2}}{9n^2 + 18nr + 9r^2 - 18n - 18r + 8} \quad (4)$$

Which for the root $r = \frac{4}{3}$ becomes

$$a_n = -\frac{3a_{n-2}}{n(3n+2)} \quad (5)$$

At this point, it is a good idea to keep track of a_n in a table both before substituting $r = \frac{4}{3}$ and after as more terms are found using the above recursive equation.

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0

For $n = 2$, using the above recursive equation gives

$$a_2 = -\frac{9}{9r^2 + 18r + 8}$$

Which for the root $r = \frac{4}{3}$ becomes

$$a_2 = -\frac{3}{16}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{9}{9r^2+18r+8}$	$-\frac{3}{16}$

For $n = 3$, using the above recursive equation gives

$$a_3 = 0$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{9}{9r^2+18r+8}$	$-\frac{3}{16}$
a_3	0	0

For $n = 4$, using the above recursive equation gives

$$a_4 = \frac{81}{(9r^2 + 18r + 8)(9r^2 + 54r + 80)}$$

Which for the root $r = \frac{4}{3}$ becomes

$$a_4 = \frac{9}{896}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{9}{9r^2+18r+8}$	$-\frac{3}{16}$
a_3	0	0
a_4	$\frac{81}{(9r^2+18r+8)(9r^2+54r+80)}$	$\frac{9}{896}$

For $n = 5$, using the above recursive equation gives

$$a_5 = 0$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{9}{9r^2+18r+8}$	$-\frac{3}{16}$
a_3	0	0
a_4	$\frac{81}{(9r^2+18r+8)(9r^2+54r+80)}$	$\frac{9}{896}$
a_5	0	0

Using the above table, then the solution $y_1(x)$ is

$$\begin{aligned} y_1(x) &= x^{\frac{4}{3}}(a_0 + a_1x + a_2x^2 + a_3x^3 + a_4x^4 + a_5x^5 + a_6x^6 \dots) \\ &= x^{\frac{4}{3}}\left(1 - \frac{3x^2}{16} + \frac{9x^4}{896} + O(x^6)\right) \end{aligned}$$

Now the second solution $y_2(x)$ is found. Eq (2B) derived above is now used to find all b_n coefficients. The case $n = 0$ is skipped since it was used to find the roots of the indicial equation. b_0 is arbitrary and taken as $b_0 = 1$. Substituting $n = 1$ in Eq. (2B) gives

$$b_1 = 0$$

For $2 \leq n$ the recursive equation is

$$b_n(n+r)(n+r-1) - b_n(n+r) + b_{n-2} + \frac{8b_n}{9} = 0 \quad (3)$$

Solving for b_n from recursive equation (4) gives

$$b_n = -\frac{9b_{n-2}}{9n^2 + 18nr + 9r^2 - 18n - 18r + 8} \quad (4)$$

Which for the root $r = \frac{2}{3}$ becomes

$$b_n = -\frac{3b_{n-2}}{n(3n-2)} \quad (5)$$

At this point, it is a good idea to keep track of b_n in a table both before substituting $r = \frac{2}{3}$ and after as more terms are found using the above recursive equation.

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0

For $n = 2$, using the above recursive equation gives

$$b_2 = -\frac{9}{9r^2 + 18r + 8}$$

Which for the root $r = \frac{2}{3}$ becomes

$$b_2 = -\frac{3}{8}$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0
b_2	$-\frac{9}{9r^2+18r+8}$	$-\frac{3}{8}$

For $n = 3$, using the above recursive equation gives

$$b_3 = 0$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0
b_2	$-\frac{9}{9r^2+18r+8}$	$-\frac{3}{8}$
b_3	0	0

For $n = 4$, using the above recursive equation gives

$$b_4 = \frac{81}{(9r^2 + 18r + 8)(9r^2 + 54r + 80)}$$

Which for the root $r = \frac{2}{3}$ becomes

$$b_4 = \frac{9}{320}$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0
b_2	$-\frac{9}{9r^2+18r+8}$	$-\frac{3}{8}$
b_3	0	0
b_4	$\frac{81}{(9r^2+18r+8)(9r^2+54r+80)}$	$\frac{9}{320}$

For $n = 5$, using the above recursive equation gives

$$b_5 = 0$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0
b_2	$-\frac{9}{9r^2+18r+8}$	$-\frac{3}{8}$
b_3	0	0
b_4	$\frac{81}{(9r^2+18r+8)(9r^2+54r+80)}$	$\frac{9}{320}$
b_5	0	0

Using the above table, then the solution $y_2(x)$ is

$$\begin{aligned} y_2(x) &= x^{\frac{4}{3}}(b_0 + b_1x + b_2x^2 + b_3x^3 + b_4x^4 + b_5x^5 + b_6x^6 \dots) \\ &= x^{\frac{2}{3}}\left(1 - \frac{3x^2}{8} + \frac{9x^4}{320} + O(x^6)\right) \end{aligned}$$

Therefore the homogeneous solution is

$$\begin{aligned} y_h(x) &= c_1y_1(x) + c_2y_2(x) \\ &= c_1x^{\frac{4}{3}}\left(1 - \frac{3x^2}{16} + \frac{9x^4}{896} + O(x^6)\right) + c_2x^{\frac{2}{3}}\left(1 - \frac{3x^2}{8} + \frac{9x^4}{320} + O(x^6)\right) \end{aligned}$$

Hence the final solution is

$$\begin{aligned} y &= y_h \\ &= c_1x^{\frac{4}{3}}\left(1 - \frac{3x^2}{16} + \frac{9x^4}{896} + O(x^6)\right) + c_2x^{\frac{2}{3}}\left(1 - \frac{3x^2}{8} + \frac{9x^4}{320} + O(x^6)\right) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1x^{\frac{4}{3}}\left(1 - \frac{3x^2}{16} + \frac{9x^4}{896} + O(x^6)\right) + c_2x^{\frac{2}{3}}\left(1 - \frac{3x^2}{8} + \frac{9x^4}{320} + O(x^6)\right) \quad (1)$$

Verification of solutions

$$y = c_1x^{\frac{4}{3}}\left(1 - \frac{3x^2}{16} + \frac{9x^4}{896} + O(x^6)\right) + c_2x^{\frac{2}{3}}\left(1 - \frac{3x^2}{8} + \frac{9x^4}{320} + O(x^6)\right)$$

Verified OK.

15.7.1 Maple step by step solution

Let's solve

$$y''x^2 - y'x + \left(x^2 + \frac{8}{9}\right)y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = -\frac{(9x^2+8)y}{9x^2} + \frac{y'}{x}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' - \frac{y'}{x} + \frac{(9x^2+8)y}{9x^2} = 0$$

- Check to see if $x_0 = 0$ is a regular singular point

- Define functions

$$\left[P_2(x) = -\frac{1}{x}, P_3(x) = \frac{9x^2+8}{9x^2} \right]$$

- $x \cdot P_2(x)$ is analytic at $x = 0$

$$(x \cdot P_2(x)) \Big|_{x=0} = -1$$

- $x^2 \cdot P_3(x)$ is analytic at $x = 0$

$$(x^2 \cdot P_3(x)) \Big|_{x=0} = \frac{8}{9}$$

- $x = 0$ is a regular singular point

Check to see if $x_0 = 0$ is a regular singular point

$$x_0 = 0$$

- Multiply by denominators

$$9y''x^2 - 9y'x + (9x^2 + 8)y = 0$$

- Assume series solution for y

$$y = \sum_{k=0}^{\infty} a_k x^{k+r}$$

- Rewrite ODE with series expansions

- Convert $x^m \cdot y$ to series expansion for $m = 0..2$

$$x^m \cdot y = \sum_{k=0}^{\infty} a_k x^{k+r+m}$$

- Shift index using $k \rightarrow k - m$

$$x^m \cdot y = \sum_{k=m}^{\infty} a_{k-m} x^{k+r}$$

- Convert $x \cdot y'$ to series expansion

$$x \cdot y' = \sum_{k=0}^{\infty} a_k (k+r) x^{k+r}$$

- Convert $x^2 \cdot y''$ to series expansion

$$x^2 \cdot y'' = \sum_{k=0}^{\infty} a_k (k+r)(k+r-1) x^{k+r}$$

Rewrite ODE with series expansions

$$a_0(-2+3r)(-4+3r)x^r + a_1(1+3r)(-1+3r)x^{1+r} + \left(\sum_{k=2}^{\infty} (a_k(3k+3r-2)(3k+3r-4) + 9a_{k-2}) \right) x^{k+r} = 0$$

- a_0 cannot be 0 by assumption, giving the indicial equation

$$(-2+3r)(-4+3r) = 0$$
- Values of r that satisfy the indicial equation

$$r \in \left\{ \frac{2}{3}, \frac{4}{3} \right\}$$
- Each term must be 0

$$a_1(1+3r)(-1+3r) = 0$$
- Solve for the dependent coefficient(s)

$$a_1 = 0$$
- Each term in the series must be 0, giving the recursion relation

$$9\left(k - \frac{2}{3} + r\right)\left(k + r - \frac{4}{3}\right)a_k + 9a_{k-2} = 0$$
- Shift index using $k \rightarrow k + 2$

$$9\left(k + \frac{4}{3} + r\right)\left(k + \frac{2}{3} + r\right)a_{k+2} + 9a_k = 0$$
- Recursion relation that defines series solution to ODE

$$a_{k+2} = -\frac{9a_k}{(3k+4+3r)(3k+2+3r)}$$
- Recursion relation for $r = \frac{2}{3}$

$$a_{k+2} = -\frac{9a_k}{(3k+6)(3k+4)}$$
- Solution for $r = \frac{2}{3}$

$$\left[y = \sum_{k=0}^{\infty} a_k x^{k+\frac{2}{3}}, a_{k+2} = -\frac{9a_k}{(3k+6)(3k+4)}, a_1 = 0 \right]$$

- Recursion relation for $r = \frac{4}{3}$

$$a_{k+2} = -\frac{9a_k}{(3k+8)(3k+6)}$$

- Solution for $r = \frac{4}{3}$

$$\left[y = \sum_{k=0}^{\infty} a_k x^{k+\frac{4}{3}}, a_{k+2} = -\frac{9a_k}{(3k+8)(3k+6)}, a_1 = 0 \right]$$

- Combine solutions and rename parameters

$$\left[y = \left(\sum_{k=0}^{\infty} a_k x^{k+\frac{2}{3}} \right) + \left(\sum_{k=0}^{\infty} b_k x^{k+\frac{4}{3}} \right), a_{k+2} = -\frac{9a_k}{(3k+6)(3k+4)}, a_1 = 0, b_{k+2} = -\frac{9b_k}{(3k+8)(3k+6)}, b_1 = 0 \right]$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
trying a symmetry of the form [xi=0, eta=F(x)]
checking if the LODE is missing y
-> Trying a Liouvillian solution using Kovacic's algorithm
<- No Liouvillian solutions exist
-> Trying a solution in terms of special functions:
    -> Bessel
    <- Bessel successful
<- special function solution successful`

```

✓ Solution by Maple

Time used: 0.031 (sec). Leaf size: 35

```

Order:=6;
dsolve(x^2*diff(y(x),x$2)-x*diff(y(x),x)+(x^2+8/9)*y(x)=0,y(x),type='series',x=0);

```

$$y(x) = c_1 x^{\frac{2}{3}} \left(1 - \frac{3}{8} x^2 + \frac{9}{320} x^4 + O(x^6) \right) + c_2 x^{\frac{4}{3}} \left(1 - \frac{3}{16} x^2 + \frac{9}{896} x^4 + O(x^6) \right)$$

✓ Solution by Mathematica

Time used: 0.002 (sec). Leaf size: 52

```
AsymptoticDSolveValue[x^2*y''[x]-x*y'[x]+(x^2+8/9)*y[x]==0,y[x],{x,0,5}]
```

$$y(x) \rightarrow c_1 \left(\frac{9x^4}{896} - \frac{3x^2}{16} + 1 \right) x^{4/3} + c_2 \left(\frac{9x^4}{320} - \frac{3x^2}{8} + 1 \right) x^{2/3}$$

15.8 problem 8

15.8.1 Maple step by step solution 4116

Internal problem ID [11909]

Internal file name [OUTPUT/11918_Saturday_April_13_2024_10_26_19_PM_67683918/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.2 (Frobenius). Exercises page 251

Problem number: 8.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"second order series method. Regular singular point. Difference not integer"**

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$x^2y'' - y'x + \left(2x^2 + \frac{5}{9}\right)y = 0$$

With the expansion point for the power series method at $x = 0$.

The type of the expansion point is first determined. This is done on the homogeneous part of the ODE.

$$x^2y'' - y'x + \left(2x^2 + \frac{5}{9}\right)y = 0$$

The following is summary of singularities for the above ode. Writing the ode as

$$y'' + p(x)y' + q(x)y = 0$$

Where

$$p(x) = -\frac{1}{x}$$
$$q(x) = \frac{18x^2 + 5}{9x^2}$$

Table 541: Table $p(x), q(x)$ singularities.

$p(x) = -\frac{1}{x}$	
singularity	type
$x = 0$	“regular”

$q(x) = \frac{18x^2+5}{9x^2}$	
singularity	type
$x = 0$	“regular”

Combining everything together gives the following summary of singularities for the ode as

Regular singular points : $[0]$

Irregular singular points : $[\infty]$

Since $x = 0$ is regular singular point, then Frobenius power series is used. The ode is normalized to be

$$x^2 y'' - y' x + \left(2x^2 + \frac{5}{9}\right) y = 0$$

Let the solution be represented as Frobenius power series of the form

$$y = \sum_{n=0}^{\infty} a_n x^{n+r}$$

Then

$$y' = \sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1}$$

$$y'' = \sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2}$$

Substituting the above back into the ode gives

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2} \right) x^2 \\ & - \left(\sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1} \right) x + \left(2x^2 + \frac{5}{9} \right) \left(\sum_{n=0}^{\infty} a_n x^{n+r} \right) = 0 \end{aligned} \tag{1}$$

Which simplifies to

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} x^{n+r} a_n (n+r) (n+r-1) \right) + \sum_{n=0}^{\infty} (-x^{n+r} a_n (n+r)) \\ & + \left(\sum_{n=0}^{\infty} 2x^{n+r+2} a_n \right) + \left(\sum_{n=0}^{\infty} \frac{5a_n x^{n+r}}{9} \right) = 0 \end{aligned} \quad (2A)$$

The next step is to make all powers of x be $n+r$ in each summation term. Going over each summation term above with power of x in it which is not already x^{n+r} and adjusting the power and the corresponding index gives

$$\sum_{n=0}^{\infty} 2x^{n+r+2} a_n = \sum_{n=2}^{\infty} 2a_{n-2} x^{n+r}$$

Substituting all the above in Eq (2A) gives the following equation where now all powers of x are the same and equal to $n+r$.

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} x^{n+r} a_n (n+r) (n+r-1) \right) + \sum_{n=0}^{\infty} (-x^{n+r} a_n (n+r)) \\ & + \left(\sum_{n=2}^{\infty} 2a_{n-2} x^{n+r} \right) + \left(\sum_{n=0}^{\infty} \frac{5a_n x^{n+r}}{9} \right) = 0 \end{aligned} \quad (2B)$$

The indicial equation is obtained from $n=0$. From Eq (2B) this gives

$$x^{n+r} a_n (n+r) (n+r-1) - x^{n+r} a_n (n+r) + \frac{5a_n x^{n+r}}{9} = 0$$

When $n=0$ the above becomes

$$x^r a_0 r (-1+r) - x^r a_0 r + \frac{5a_0 x^r}{9} = 0$$

Or

$$\left(x^r r (-1+r) - x^r r + \frac{5x^r}{9} \right) a_0 = 0$$

Since $a_0 \neq 0$ then the above simplifies to

$$\frac{(9r^2 - 18r + 5) x^r}{9} = 0$$

Since the above is true for all x then the indicial equation becomes

$$r^2 - 2r + \frac{5}{9} = 0$$

Solving for r gives the roots of the indicial equation as

$$r_1 = \frac{5}{3}$$

$$r_2 = \frac{1}{3}$$

Since $a_0 \neq 0$ then the indicial equation becomes

$$\frac{(9r^2 - 18r + 5)x^r}{9} = 0$$

Solving for r gives the roots of the indicial equation as Since $r_1 - r_2 = \frac{4}{3}$ is not an integer, then we can construct two linearly independent solutions

$$y_1(x) = x^{r_1} \left(\sum_{n=0}^{\infty} a_n x^n \right)$$

$$y_2(x) = x^{r_2} \left(\sum_{n=0}^{\infty} b_n x^n \right)$$

Or

$$y_1(x) = \sum_{n=0}^{\infty} a_n x^{n+\frac{5}{3}}$$

$$y_2(x) = \sum_{n=0}^{\infty} b_n x^{n+\frac{1}{3}}$$

We start by finding $y_1(x)$. Eq (2B) derived above is now used to find all a_n coefficients. The case $n = 0$ is skipped since it was used to find the roots of the indicial equation. a_0 is arbitrary and taken as $a_0 = 1$. Substituting $n = 1$ in Eq. (2B) gives

$$a_1 = 0$$

For $2 \leq n$ the recursive equation is

$$a_n(n+r)(n+r-1) - a_n(n+r) + 2a_{n-2} + \frac{5a_n}{9} = 0 \quad (3)$$

Solving for a_n from recursive equation (4) gives

$$a_n = -\frac{18a_{n-2}}{9n^2 + 18nr + 9r^2 - 18n - 18r + 5} \quad (4)$$

Which for the root $r = \frac{5}{3}$ becomes

$$a_n = -\frac{6a_{n-2}}{n(3n+4)} \quad (5)$$

At this point, it is a good idea to keep track of a_n in a table both before substituting $r = \frac{5}{3}$ and after as more terms are found using the above recursive equation.

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0

For $n = 2$, using the above recursive equation gives

$$a_2 = -\frac{18}{9r^2 + 18r + 5}$$

Which for the root $r = \frac{5}{3}$ becomes

$$a_2 = -\frac{3}{10}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{18}{9r^2+18r+5}$	$-\frac{3}{10}$

For $n = 3$, using the above recursive equation gives

$$a_3 = 0$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{18}{9r^2+18r+5}$	$-\frac{3}{10}$
a_3	0	0

For $n = 4$, using the above recursive equation gives

$$a_4 = \frac{324}{(9r^2 + 18r + 5)(9r^2 + 54r + 77)}$$

Which for the root $r = \frac{5}{3}$ becomes

$$a_4 = \frac{9}{320}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{18}{9r^2+18r+5}$	$-\frac{3}{10}$
a_3	0	0
a_4	$\frac{324}{(9r^2+18r+5)(9r^2+54r+77)}$	$\frac{9}{320}$

For $n = 5$, using the above recursive equation gives

$$a_5 = 0$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{18}{9r^2+18r+5}$	$-\frac{3}{10}$
a_3	0	0
a_4	$\frac{324}{(9r^2+18r+5)(9r^2+54r+77)}$	$\frac{9}{320}$
a_5	0	0

Using the above table, then the solution $y_1(x)$ is

$$\begin{aligned} y_1(x) &= x^{\frac{5}{3}}(a_0 + a_1x + a_2x^2 + a_3x^3 + a_4x^4 + a_5x^5 + a_6x^6 \dots) \\ &= x^{\frac{5}{3}}\left(1 - \frac{3x^2}{10} + \frac{9x^4}{320} + O(x^6)\right) \end{aligned}$$

Now the second solution $y_2(x)$ is found. Eq (2B) derived above is now used to find all b_n coefficients. The case $n = 0$ is skipped since it was used to find the roots of the indicial equation. b_0 is arbitrary and taken as $b_0 = 1$. Substituting $n = 1$ in Eq. (2B) gives

$$b_1 = 0$$

For $2 \leq n$ the recursive equation is

$$b_n(n+r)(n+r-1) - b_n(n+r) + 2b_{n-2} + \frac{5b_n}{9} = 0 \quad (3)$$

Solving for b_n from recursive equation (4) gives

$$b_n = -\frac{18b_{n-2}}{9n^2 + 18nr + 9r^2 - 18n - 18r + 5} \quad (4)$$

Which for the root $r = \frac{1}{3}$ becomes

$$b_n = -\frac{6b_{n-2}}{n(3n-4)} \quad (5)$$

At this point, it is a good idea to keep track of b_n in a table both before substituting $r = \frac{1}{3}$ and after as more terms are found using the above recursive equation.

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0

For $n = 2$, using the above recursive equation gives

$$b_2 = -\frac{18}{9r^2 + 18r + 5}$$

Which for the root $r = \frac{1}{3}$ becomes

$$b_2 = -\frac{3}{2}$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0
b_2	$-\frac{18}{9r^2+18r+5}$	$-\frac{3}{2}$

For $n = 3$, using the above recursive equation gives

$$b_3 = 0$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0
b_2	$-\frac{18}{9r^2+18r+5}$	$-\frac{3}{2}$
b_3	0	0

For $n = 4$, using the above recursive equation gives

$$b_4 = \frac{324}{(9r^2 + 18r + 5)(9r^2 + 54r + 77)}$$

Which for the root $r = \frac{1}{3}$ becomes

$$b_4 = \frac{9}{32}$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0
b_2	$-\frac{18}{9r^2+18r+5}$	$-\frac{3}{2}$
b_3	0	0
b_4	$\frac{324}{(9r^2+18r+5)(9r^2+54r+77)}$	$\frac{9}{32}$

For $n = 5$, using the above recursive equation gives

$$b_5 = 0$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0
b_2	$-\frac{18}{9r^2+18r+5}$	$-\frac{3}{2}$
b_3	0	0
b_4	$\frac{324}{(9r^2+18r+5)(9r^2+54r+77)}$	$\frac{9}{32}$
b_5	0	0

Using the above table, then the solution $y_2(x)$ is

$$\begin{aligned} y_2(x) &= x^{\frac{5}{3}}(b_0 + b_1x + b_2x^2 + b_3x^3 + b_4x^4 + b_5x^5 + b_6x^6 \dots) \\ &= x^{\frac{1}{3}}\left(1 - \frac{3x^2}{2} + \frac{9x^4}{32} + O(x^6)\right) \end{aligned}$$

Therefore the homogeneous solution is

$$\begin{aligned} y_h(x) &= c_1y_1(x) + c_2y_2(x) \\ &= c_1x^{\frac{5}{3}}\left(1 - \frac{3x^2}{10} + \frac{9x^4}{320} + O(x^6)\right) + c_2x^{\frac{1}{3}}\left(1 - \frac{3x^2}{2} + \frac{9x^4}{32} + O(x^6)\right) \end{aligned}$$

Hence the final solution is

$$\begin{aligned} y &= y_h \\ &= c_1x^{\frac{5}{3}}\left(1 - \frac{3x^2}{10} + \frac{9x^4}{320} + O(x^6)\right) + c_2x^{\frac{1}{3}}\left(1 - \frac{3x^2}{2} + \frac{9x^4}{32} + O(x^6)\right) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1x^{\frac{5}{3}}\left(1 - \frac{3x^2}{10} + \frac{9x^4}{320} + O(x^6)\right) + c_2x^{\frac{1}{3}}\left(1 - \frac{3x^2}{2} + \frac{9x^4}{32} + O(x^6)\right) \quad (1)$$

Verification of solutions

$$y = c_1x^{\frac{5}{3}}\left(1 - \frac{3x^2}{10} + \frac{9x^4}{320} + O(x^6)\right) + c_2x^{\frac{1}{3}}\left(1 - \frac{3x^2}{2} + \frac{9x^4}{32} + O(x^6)\right)$$

Verified OK.

15.8.1 Maple step by step solution

Let's solve

$$y''x^2 - y'x + \left(2x^2 + \frac{5}{9}\right)y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = -\frac{(18x^2+5)y}{9x^2} + \frac{y'}{x}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' - \frac{y'}{x} + \frac{(18x^2+5)y}{9x^2} = 0$$

- Check to see if $x_0 = 0$ is a regular singular point

- Define functions

$$\left[P_2(x) = -\frac{1}{x}, P_3(x) = \frac{18x^2+5}{9x^2} \right]$$

- $x \cdot P_2(x)$ is analytic at $x = 0$

$$(x \cdot P_2(x)) \Big|_{x=0} = -1$$

- $x^2 \cdot P_3(x)$ is analytic at $x = 0$

$$(x^2 \cdot P_3(x)) \Big|_{x=0} = \frac{5}{9}$$

- $x = 0$ is a regular singular point

Check to see if $x_0 = 0$ is a regular singular point

$$x_0 = 0$$

- Multiply by denominators

$$9y''x^2 - 9y'x + (18x^2 + 5)y = 0$$

- Assume series solution for y

$$y = \sum_{k=0}^{\infty} a_k x^{k+r}$$

- Rewrite ODE with series expansions

- Convert $x^m \cdot y$ to series expansion for $m = 0..2$

$$x^m \cdot y = \sum_{k=0}^{\infty} a_k x^{k+r+m}$$

- Shift index using $k \rightarrow k - m$

$$x^m \cdot y = \sum_{k=m}^{\infty} a_{k-m} x^{k+r}$$

- Convert $x \cdot y'$ to series expansion

$$x \cdot y' = \sum_{k=0}^{\infty} a_k (k+r) x^{k+r}$$

- Convert $x^2 \cdot y''$ to series expansion

$$x^2 \cdot y'' = \sum_{k=0}^{\infty} a_k (k+r)(k+r-1) x^{k+r}$$

Rewrite ODE with series expansions

$$a_0(-1+3r)(-5+3r)x^r + a_1(2+3r)(-2+3r)x^{1+r} + \left(\sum_{k=2}^{\infty} (a_k(3k+3r-1)(3k+3r-5) + 18a_{k-2}) \right) x^{k+r} = 0$$

- a_0 cannot be 0 by assumption, giving the indicial equation

$$(-1+3r)(-5+3r) = 0$$
- Values of r that satisfy the indicial equation

$$r \in \left\{ \frac{1}{3}, \frac{5}{3} \right\}$$
- Each term must be 0

$$a_1(2+3r)(-2+3r) = 0$$
- Solve for the dependent coefficient(s)

$$a_1 = 0$$
- Each term in the series must be 0, giving the recursion relation

$$9\left(k+r-\frac{1}{3}\right)\left(k+r-\frac{5}{3}\right)a_k + 18a_{k-2} = 0$$
- Shift index using $k \rightarrow k+2$

$$9\left(k+\frac{5}{3}+r\right)\left(k+\frac{1}{3}+r\right)a_{k+2} + 18a_k = 0$$
- Recursion relation that defines series solution to ODE

$$a_{k+2} = -\frac{18a_k}{(3k+5+3r)(3k+1+3r)}$$
- Recursion relation for $r = \frac{1}{3}$

$$a_{k+2} = -\frac{18a_k}{(3k+6)(3k+2)}$$
- Solution for $r = \frac{1}{3}$

$$\left[y = \sum_{k=0}^{\infty} a_k x^{k+\frac{1}{3}}, a_{k+2} = -\frac{18a_k}{(3k+6)(3k+2)}, a_1 = 0 \right]$$

- Recursion relation for $r = \frac{5}{3}$

$$a_{k+2} = -\frac{18a_k}{(3k+10)(3k+6)}$$

- Solution for $r = \frac{5}{3}$

$$\left[y = \sum_{k=0}^{\infty} a_k x^{k+\frac{5}{3}}, a_{k+2} = -\frac{18a_k}{(3k+10)(3k+6)}, a_1 = 0 \right]$$

- Combine solutions and rename parameters

$$\left[y = \left(\sum_{k=0}^{\infty} a_k x^{k+\frac{1}{3}} \right) + \left(\sum_{k=0}^{\infty} b_k x^{k+\frac{5}{3}} \right), a_{k+2} = -\frac{18a_k}{(3k+6)(3k+2)}, a_1 = 0, b_{k+2} = -\frac{18b_k}{(3k+10)(3k+6)}, b_1 = 0 \right]$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
trying a symmetry of the form [xi=0, eta=F(x)]
checking if the LODE is missing y
-> Trying a Liouvillian solution using Kovacic's algorithm
<- No Liouvillian solutions exist
-> Trying a solution in terms of special functions:
    -> Bessel
    <- Bessel successful
<- special function solution successful`

```

✓ Solution by Maple

Time used: 0.031 (sec). Leaf size: 35

```

Order:=6;
dsolve(x^2*diff(y(x),x$2)-x*diff(y(x),x)+(2*x^2+5/9)*y(x)=0,y(x),type='series',x=0);

```

$$y(x) = c_1 x^{\frac{1}{3}} \left(1 - \frac{3}{2}x^2 + \frac{9}{32}x^4 + O(x^6) \right) + c_2 x^{\frac{5}{3}} \left(1 - \frac{3}{10}x^2 + \frac{9}{320}x^4 + O(x^6) \right)$$

✓ Solution by Mathematica

Time used: 0.003 (sec). Leaf size: 52

```
AsymptoticDSolveValue[x^2*y''[x]-x*y'[x]+(2*x^2+5/9)*y[x]==0,y[x],{x,0,5}]
```

$$y(x) \rightarrow c_2 \left(\frac{9x^4}{32} - \frac{3x^2}{2} + 1 \right) \sqrt[3]{x} + c_1 \left(\frac{9x^4}{320} - \frac{3x^2}{10} + 1 \right) x^{5/3}$$

15.9 problem 9

15.9.1 Maple step by step solution 4129

Internal problem ID [11910]

Internal file name [OUTPUT/11919_Saturday_April_13_2024_10_26_19_PM_61469210/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.2 (Frobenius). Exercises page 251

Problem number: 9.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"second order series method. Regular singular point. Difference not integer"**

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$x^2y'' + y'x + \left(x^2 - \frac{1}{9}\right)y = 0$$

With the expansion point for the power series method at $x = 0$.

The type of the expansion point is first determined. This is done on the homogeneous part of the ODE.

$$x^2y'' + y'x + \left(x^2 - \frac{1}{9}\right)y = 0$$

The following is summary of singularities for the above ode. Writing the ode as

$$y'' + p(x)y' + q(x)y = 0$$

Where

$$p(x) = \frac{1}{x}$$
$$q(x) = \frac{9x^2 - 1}{9x^2}$$

Table 543: Table $p(x), q(x)$ singularities.

$p(x) = \frac{1}{x}$	
singularity	type
$x = 0$	“regular”

$q(x) = \frac{9x^2-1}{9x^2}$	
singularity	type
$x = 0$	“regular”

Combining everything together gives the following summary of singularities for the ode as

Regular singular points : $[0]$

Irregular singular points : $[\infty]$

Since $x = 0$ is regular singular point, then Frobenius power series is used. The ode is normalized to be

$$x^2 y'' + y'x + \left(x^2 - \frac{1}{9}\right) y = 0$$

Let the solution be represented as Frobenius power series of the form

$$y = \sum_{n=0}^{\infty} a_n x^{n+r}$$

Then

$$y' = \sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1}$$

$$y'' = \sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2}$$

Substituting the above back into the ode gives

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2} \right) x^2 \\ & + \left(\sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1} \right) x + \left(x^2 - \frac{1}{9} \right) \left(\sum_{n=0}^{\infty} a_n x^{n+r} \right) = 0 \end{aligned} \tag{1}$$

Which simplifies to

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} x^{n+r} a_n (n+r) (n+r-1) \right) + \left(\sum_{n=0}^{\infty} x^{n+r} a_n (n+r) \right) \\ & + \left(\sum_{n=0}^{\infty} x^{n+r+2} a_n \right) + \sum_{n=0}^{\infty} \left(-\frac{a_n x^{n+r}}{9} \right) = 0 \end{aligned} \quad (2A)$$

The next step is to make all powers of x be $n+r$ in each summation term. Going over each summation term above with power of x in it which is not already x^{n+r} and adjusting the power and the corresponding index gives

$$\sum_{n=0}^{\infty} x^{n+r+2} a_n = \sum_{n=2}^{\infty} a_{n-2} x^{n+r}$$

Substituting all the above in Eq (2A) gives the following equation where now all powers of x are the same and equal to $n+r$.

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} x^{n+r} a_n (n+r) (n+r-1) \right) + \left(\sum_{n=0}^{\infty} x^{n+r} a_n (n+r) \right) \\ & + \left(\sum_{n=2}^{\infty} a_{n-2} x^{n+r} \right) + \sum_{n=0}^{\infty} \left(-\frac{a_n x^{n+r}}{9} \right) = 0 \end{aligned} \quad (2B)$$

The indicial equation is obtained from $n=0$. From Eq (2B) this gives

$$x^{n+r} a_n (n+r) (n+r-1) + x^{n+r} a_n (n+r) - \frac{a_n x^{n+r}}{9} = 0$$

When $n=0$ the above becomes

$$x^r a_0 r (-1+r) + x^r a_0 r - \frac{a_0 x^r}{9} = 0$$

Or

$$\left(x^r r (-1+r) + x^r r - \frac{x^r}{9} \right) a_0 = 0$$

Since $a_0 \neq 0$ then the above simplifies to

$$\frac{(9r^2 - 1) x^r}{9} = 0$$

Since the above is true for all x then the indicial equation becomes

$$r^2 - \frac{1}{9} = 0$$

Solving for r gives the roots of the indicial equation as

$$r_1 = \frac{1}{3}$$

$$r_2 = -\frac{1}{3}$$

Since $a_0 \neq 0$ then the indicial equation becomes

$$\frac{(9r^2 - 1)x^r}{9} = 0$$

Solving for r gives the roots of the indicial equation as Since $r_1 - r_2 = \frac{2}{3}$ is not an integer, then we can construct two linearly independent solutions

$$y_1(x) = x^{r_1} \left(\sum_{n=0}^{\infty} a_n x^n \right)$$

$$y_2(x) = x^{r_2} \left(\sum_{n=0}^{\infty} b_n x^n \right)$$

Or

$$y_1(x) = \sum_{n=0}^{\infty} a_n x^{n+\frac{1}{3}}$$

$$y_2(x) = \sum_{n=0}^{\infty} b_n x^{n-\frac{1}{3}}$$

We start by finding $y_1(x)$. Eq (2B) derived above is now used to find all a_n coefficients. The case $n = 0$ is skipped since it was used to find the roots of the indicial equation. a_0 is arbitrary and taken as $a_0 = 1$. Substituting $n = 1$ in Eq. (2B) gives

$$a_1 = 0$$

For $2 \leq n$ the recursive equation is

$$a_n(n+r)(n+r-1) + a_n(n+r) + a_{n-2} - \frac{a_n}{9} = 0 \quad (3)$$

Solving for a_n from recursive equation (4) gives

$$a_n = -\frac{9a_{n-2}}{9n^2 + 18nr + 9r^2 - 1} \quad (4)$$

Which for the root $r = \frac{1}{3}$ becomes

$$a_n = -\frac{3a_{n-2}}{n(3n+2)} \quad (5)$$

At this point, it is a good idea to keep track of a_n in a table both before substituting $r = \frac{1}{3}$ and after as more terms are found using the above recursive equation.

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0

For $n = 2$, using the above recursive equation gives

$$a_2 = -\frac{9}{9r^2 + 36r + 35}$$

Which for the root $r = \frac{1}{3}$ becomes

$$a_2 = -\frac{3}{16}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{9}{9r^2+36r+35}$	$-\frac{3}{16}$

For $n = 3$, using the above recursive equation gives

$$a_3 = 0$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{9}{9r^2+36r+35}$	$-\frac{3}{16}$
a_3	0	0

For $n = 4$, using the above recursive equation gives

$$a_4 = \frac{81}{(9r^2 + 36r + 35)(9r^2 + 72r + 143)}$$

Which for the root $r = \frac{1}{3}$ becomes

$$a_4 = \frac{9}{896}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{9}{9r^2+36r+35}$	$-\frac{3}{16}$
a_3	0	0
a_4	$\frac{81}{(9r^2+36r+35)(9r^2+72r+143)}$	$\frac{9}{896}$

For $n = 5$, using the above recursive equation gives

$$a_5 = 0$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{9}{9r^2+36r+35}$	$-\frac{3}{16}$
a_3	0	0
a_4	$\frac{81}{(9r^2+36r+35)(9r^2+72r+143)}$	$\frac{9}{896}$
a_5	0	0

Using the above table, then the solution $y_1(x)$ is

$$\begin{aligned} y_1(x) &= x^{\frac{1}{3}}(a_0 + a_1x + a_2x^2 + a_3x^3 + a_4x^4 + a_5x^5 + a_6x^6 \dots) \\ &= x^{\frac{1}{3}}\left(1 - \frac{3x^2}{16} + \frac{9x^4}{896} + O(x^6)\right) \end{aligned}$$

Now the second solution $y_2(x)$ is found. Eq (2B) derived above is now used to find all b_n coefficients. The case $n = 0$ is skipped since it was used to find the roots of the indicial equation. b_0 is arbitrary and taken as $b_0 = 1$. Substituting $n = 1$ in Eq. (2B) gives

$$b_1 = 0$$

For $2 \leq n$ the recursive equation is

$$b_n(n+r)(n+r-1) + b_n(n+r) + b_{n-2} - \frac{b_n}{9} = 0 \quad (3)$$

Solving for b_n from recursive equation (4) gives

$$b_n = -\frac{9b_{n-2}}{9n^2 + 18nr + 9r^2 - 1} \quad (4)$$

Which for the root $r = -\frac{1}{3}$ becomes

$$b_n = -\frac{3b_{n-2}}{n(3n-2)} \quad (5)$$

At this point, it is a good idea to keep track of b_n in a table both before substituting $r = -\frac{1}{3}$ and after as more terms are found using the above recursive equation.

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0

For $n = 2$, using the above recursive equation gives

$$b_2 = -\frac{9}{9r^2 + 36r + 35}$$

Which for the root $r = -\frac{1}{3}$ becomes

$$b_2 = -\frac{3}{8}$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0
b_2	$-\frac{9}{9r^2+36r+35}$	$-\frac{3}{8}$

For $n = 3$, using the above recursive equation gives

$$b_3 = 0$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0
b_2	$-\frac{9}{9r^2+36r+35}$	$-\frac{3}{8}$
b_3	0	0

For $n = 4$, using the above recursive equation gives

$$b_4 = \frac{81}{(9r^2 + 36r + 35)(9r^2 + 72r + 143)}$$

Which for the root $r = -\frac{1}{3}$ becomes

$$b_4 = \frac{9}{320}$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0
b_2	$-\frac{9}{9r^2+36r+35}$	$-\frac{3}{8}$
b_3	0	0
b_4	$\frac{81}{(9r^2+36r+35)(9r^2+72r+143)}$	$\frac{9}{320}$

For $n = 5$, using the above recursive equation gives

$$b_5 = 0$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0
b_2	$-\frac{9}{9r^2+36r+35}$	$-\frac{3}{8}$
b_3	0	0
b_4	$\frac{81}{(9r^2+36r+35)(9r^2+72r+143)}$	$\frac{9}{320}$
b_5	0	0

Using the above table, then the solution $y_2(x)$ is

$$\begin{aligned} y_2(x) &= x^{\frac{1}{3}}(b_0 + b_1x + b_2x^2 + b_3x^3 + b_4x^4 + b_5x^5 + b_6x^6 \dots) \\ &= \frac{1 - \frac{3x^2}{8} + \frac{9x^4}{320} + O(x^6)}{x^{\frac{1}{3}}} \end{aligned}$$

Therefore the homogeneous solution is

$$\begin{aligned} y_h(x) &= c_1y_1(x) + c_2y_2(x) \\ &= c_1x^{\frac{1}{3}}\left(1 - \frac{3x^2}{16} + \frac{9x^4}{896} + O(x^6)\right) + \frac{c_2\left(1 - \frac{3x^2}{8} + \frac{9x^4}{320} + O(x^6)\right)}{x^{\frac{1}{3}}} \end{aligned}$$

Hence the final solution is

$$\begin{aligned} y &= y_h \\ &= c_1x^{\frac{1}{3}}\left(1 - \frac{3x^2}{16} + \frac{9x^4}{896} + O(x^6)\right) + \frac{c_2\left(1 - \frac{3x^2}{8} + \frac{9x^4}{320} + O(x^6)\right)}{x^{\frac{1}{3}}} \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1x^{\frac{1}{3}}\left(1 - \frac{3x^2}{16} + \frac{9x^4}{896} + O(x^6)\right) + \frac{c_2\left(1 - \frac{3x^2}{8} + \frac{9x^4}{320} + O(x^6)\right)}{x^{\frac{1}{3}}} \quad (1)$$

Verification of solutions

$$y = c_1x^{\frac{1}{3}}\left(1 - \frac{3x^2}{16} + \frac{9x^4}{896} + O(x^6)\right) + \frac{c_2\left(1 - \frac{3x^2}{8} + \frac{9x^4}{320} + O(x^6)\right)}{x^{\frac{1}{3}}}$$

Verified OK.

15.9.1 Maple step by step solution

Let's solve

$$y''x^2 + y'x + \left(x^2 - \frac{1}{9}\right)y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = -\frac{(9x^2-1)y}{9x^2} - \frac{y'}{x}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + \frac{y'}{x} + \frac{(9x^2-1)y}{9x^2} = 0$$

- Check to see if $x_0 = 0$ is a regular singular point

- Define functions

$$\left[P_2(x) = \frac{1}{x}, P_3(x) = \frac{9x^2-1}{9x^2} \right]$$

- $x \cdot P_2(x)$ is analytic at $x = 0$

$$(x \cdot P_2(x)) \Big|_{x=0} = 1$$

- $x^2 \cdot P_3(x)$ is analytic at $x = 0$

$$(x^2 \cdot P_3(x)) \Big|_{x=0} = -\frac{1}{9}$$

- $x = 0$ is a regular singular point

Check to see if $x_0 = 0$ is a regular singular point

$$x_0 = 0$$

- Multiply by denominators

$$9y''x^2 + 9y'x + (9x^2 - 1)y = 0$$

- Assume series solution for y

$$y = \sum_{k=0}^{\infty} a_k x^{k+r}$$

- Rewrite ODE with series expansions

- Convert $x^m \cdot y$ to series expansion for $m = 0..2$

$$x^m \cdot y = \sum_{k=0}^{\infty} a_k x^{k+r+m}$$

- Shift index using $k \rightarrow k - m$

$$x^m \cdot y = \sum_{k=m}^{\infty} a_{k-m} x^{k+r}$$

- Convert $x \cdot y'$ to series expansion

$$x \cdot y' = \sum_{k=0}^{\infty} a_k (k+r) x^{k+r}$$

- Convert $x^2 \cdot y''$ to series expansion

$$x^2 \cdot y'' = \sum_{k=0}^{\infty} a_k (k+r)(k+r-1) x^{k+r}$$

Rewrite ODE with series expansions

$$a_0(1+3r)(-1+3r)x^r + a_1(4+3r)(2+3r)x^{1+r} + \left(\sum_{k=2}^{\infty} (a_k(3k+3r+1)(3k+3r-1) + 9a_{k-2}) \right) x^{k+r}$$

- a_0 cannot be 0 by assumption, giving the indicial equation

$$(1+3r)(-1+3r) = 0$$
- Values of r that satisfy the indicial equation

$$r \in \left\{ -\frac{1}{3}, \frac{1}{3} \right\}$$
- Each term must be 0

$$a_1(4+3r)(2+3r) = 0$$
- Solve for the dependent coefficient(s)

$$a_1 = 0$$
- Each term in the series must be 0, giving the recursion relation

$$a_k(3k+3r+1)(3k+3r-1) + 9a_{k-2} = 0$$
- Shift index using $k \rightarrow k+2$

$$a_{k+2}(3k+7+3r)(3k+5+3r) + 9a_k = 0$$
- Recursion relation that defines series solution to ODE

$$a_{k+2} = -\frac{9a_k}{(3k+7+3r)(3k+5+3r)}$$
- Recursion relation for $r = -\frac{1}{3}$

$$a_{k+2} = -\frac{9a_k}{(3k+6)(3k+4)}$$
- Solution for $r = -\frac{1}{3}$

$$\left[y = \sum_{k=0}^{\infty} a_k x^{k-\frac{1}{3}}, a_{k+2} = -\frac{9a_k}{(3k+6)(3k+4)}, a_1 = 0 \right]$$

- Recursion relation for $r = \frac{1}{3}$

$$a_{k+2} = -\frac{9a_k}{(3k+8)(3k+6)}$$

- Solution for $r = \frac{1}{3}$

$$\left[y = \sum_{k=0}^{\infty} a_k x^{k+\frac{1}{3}}, a_{k+2} = -\frac{9a_k}{(3k+8)(3k+6)}, a_1 = 0 \right]$$

- Combine solutions and rename parameters

$$\left[y = \left(\sum_{k=0}^{\infty} a_k x^{k-\frac{1}{3}} \right) + \left(\sum_{k=0}^{\infty} b_k x^{k+\frac{1}{3}} \right), a_{k+2} = -\frac{9a_k}{(3k+6)(3k+4)}, a_1 = 0, b_{k+2} = -\frac{9b_k}{(3k+8)(3k+6)}, b_1 = 0 \right]$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
trying a symmetry of the form [xi=0, eta=F(x)]
checking if the LODE is missing y
-> Trying a Liouvillian solution using Kovacic's algorithm
<- No Liouvillian solutions exist
-> Trying a solution in terms of special functions:
    -> Bessel
    <- Bessel successful
<- special function solution successful`

```

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 35

```

Order:=6;
dsolve(x^2*diff(y(x),x$2)+x*diff(y(x),x)+(x^2-1/9)*y(x)=0,y(x),type='series',x=0);

```

$$y(x) = \frac{x^{\frac{2}{3}} \left(1 - \frac{3}{16}x^2 + \frac{9}{896}x^4 + O(x^6) \right) c_2 + \left(1 - \frac{3}{8}x^2 + \frac{9}{320}x^4 + O(x^6) \right) c_1}{x^{\frac{1}{3}}}$$

✓ Solution by Mathematica

Time used: 0.002 (sec). Leaf size: 52

```
AsymptoticDSolveValue[x^2*y''[x]+x*y'[x]+(x^2-1/9)*y[x]==0,y[x],{x,0,5}]
```

$$y(x) \rightarrow c_1 \sqrt[3]{x} \left(\frac{9x^4}{896} - \frac{3x^2}{16} + 1 \right) + \frac{c_2 \left(\frac{9x^4}{320} - \frac{3x^2}{8} + 1 \right)}{\sqrt[3]{x}}$$

15.10 problem 10

15.10.1 Maple step by step solution 4142

Internal problem ID [11911]

Internal file name [OUTPUT/11920_Saturday_April_13_2024_10_26_20_PM_53141073/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.2 (Frobenius). Exercises page 251

Problem number: 10.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"second order series method. Regular singular point. Difference not integer"**

Maple gives the following as the ode type

```
[[_Emden, _Fowler], [_2nd_order, _linear, `_with_symmetry_[0,F(x)]]`]]
```

$$2xy'' + y' + 2y = 0$$

With the expansion point for the power series method at $x = 0$.

The type of the expansion point is first determined. This is done on the homogeneous part of the ODE.

$$2xy'' + y' + 2y = 0$$

The following is summary of singularities for the above ode. Writing the ode as

$$y'' + p(x)y' + q(x)y = 0$$

Where

$$p(x) = \frac{1}{2x}$$
$$q(x) = \frac{1}{x}$$

Table 545: Table $p(x), q(x)$ singularities.

$p(x) = \frac{1}{2x}$	
singularity	type
$x = 0$	“regular”

$q(x) = \frac{1}{x}$	
singularity	type
$x = 0$	“regular”

Combining everything together gives the following summary of singularities for the ode as

Regular singular points : $[0]$

Irregular singular points : $[\infty]$

Since $x = 0$ is regular singular point, then Frobenius power series is used. The ode is normalized to be

$$2xy'' + y' + 2y = 0$$

Let the solution be represented as Frobenius power series of the form

$$y = \sum_{n=0}^{\infty} a_n x^{n+r}$$

Then

$$y' = \sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1}$$

$$y'' = \sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2}$$

Substituting the above back into the ode gives

$$2 \left(\sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2} \right) x + \left(\sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1} \right) + 2 \left(\sum_{n=0}^{\infty} a_n x^{n+r} \right) = 0 \quad (1)$$

Which simplifies to

$$\left(\sum_{n=0}^{\infty} 2x^{n+r-1} a_n (n+r)(n+r-1) \right) + \left(\sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1} \right) + \left(\sum_{n=0}^{\infty} 2a_n x^{n+r} \right) = 0 \quad (2A)$$

The next step is to make all powers of x be $n + r - 1$ in each summation term. Going over each summation term above with power of x in it which is not already x^{n+r-1} and adjusting the power and the corresponding index gives

$$\sum_{n=0}^{\infty} 2a_n x^{n+r} = \sum_{n=1}^{\infty} 2a_{n-1} x^{n+r-1}$$

Substituting all the above in Eq (2A) gives the following equation where now all powers of x are the same and equal to $n + r - 1$.

$$\left(\sum_{n=0}^{\infty} 2x^{n+r-1} a_n (n+r) (n+r-1) \right) + \left(\sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1} \right) + \left(\sum_{n=1}^{\infty} 2a_{n-1} x^{n+r-1} \right) = 0 \quad (2B)$$

The indicial equation is obtained from $n = 0$. From Eq (2B) this gives

$$2x^{n+r-1} a_n (n+r) (n+r-1) + (n+r) a_n x^{n+r-1} = 0$$

When $n = 0$ the above becomes

$$2x^{-1+r} a_0 r (-1+r) + r a_0 x^{-1+r} = 0$$

Or

$$(2x^{-1+r} r (-1+r) + r x^{-1+r}) a_0 = 0$$

Since $a_0 \neq 0$ then the above simplifies to

$$r x^{-1+r} (-1+2r) = 0$$

Since the above is true for all x then the indicial equation becomes

$$2r^2 - r = 0$$

Solving for r gives the roots of the indicial equation as

$$r_1 = \frac{1}{2}$$

$$r_2 = 0$$

Since $a_0 \neq 0$ then the indicial equation becomes

$$r x^{-1+r} (-1+2r) = 0$$

Solving for r gives the roots of the indicial equation as Since $r_1 - r_2 = \frac{1}{2}$ is not an integer, then we can construct two linearly independent solutions

$$y_1(x) = x^{r_1} \left(\sum_{n=0}^{\infty} a_n x^n \right)$$

$$y_2(x) = x^{r_2} \left(\sum_{n=0}^{\infty} b_n x^n \right)$$

Or

$$y_1(x) = \sum_{n=0}^{\infty} a_n x^{n+\frac{1}{2}}$$

$$y_2(x) = \sum_{n=0}^{\infty} b_n x^n$$

We start by finding $y_1(x)$. Eq (2B) derived above is now used to find all a_n coefficients. The case $n = 0$ is skipped since it was used to find the roots of the indicial equation. a_0 is arbitrary and taken as $a_0 = 1$. For $1 \leq n$ the recursive equation is

$$2a_n(n+r)(n+r-1) + a_n(n+r) + 2a_{n-1} = 0 \quad (3)$$

Solving for a_n from recursive equation (4) gives

$$a_n = -\frac{2a_{n-1}}{2n^2 + 4nr + 2r^2 - n - r} \quad (4)$$

Which for the root $r = \frac{1}{2}$ becomes

$$a_n = -\frac{2a_{n-1}}{2n^2 + n} \quad (5)$$

At this point, it is a good idea to keep track of a_n in a table both before substituting $r = \frac{1}{2}$ and after as more terms are found using the above recursive equation.

n	$a_{n,r}$	a_n
a_0	1	1

For $n = 1$, using the above recursive equation gives

$$a_1 = -\frac{2}{2r^2 + 3r + 1}$$

Which for the root $r = \frac{1}{2}$ becomes

$$a_1 = -\frac{2}{3}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$-\frac{2}{2r^2+3r+1}$	$-\frac{2}{3}$

For $n = 2$, using the above recursive equation gives

$$a_2 = \frac{4}{4r^4 + 20r^3 + 35r^2 + 25r + 6}$$

Which for the root $r = \frac{1}{2}$ becomes

$$a_2 = \frac{2}{15}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$-\frac{2}{2r^2+3r+1}$	$-\frac{2}{3}$
a_2	$\frac{4}{4r^4+20r^3+35r^2+25r+6}$	$\frac{2}{15}$

For $n = 3$, using the above recursive equation gives

$$a_3 = -\frac{8}{8r^6 + 84r^5 + 350r^4 + 735r^3 + 812r^2 + 441r + 90}$$

Which for the root $r = \frac{1}{2}$ becomes

$$a_3 = -\frac{4}{315}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$-\frac{2}{2r^2+3r+1}$	$-\frac{2}{3}$
a_2	$\frac{4}{4r^4+20r^3+35r^2+25r+6}$	$\frac{2}{15}$
a_3	$-\frac{8}{8r^6+84r^5+350r^4+735r^3+812r^2+441r+90}$	$-\frac{4}{315}$

For $n = 4$, using the above recursive equation gives

$$a_4 = \frac{16}{16r^8 + 288r^7 + 2184r^6 + 9072r^5 + 22449r^4 + 33642r^3 + 29531r^2 + 13698r + 2520}$$

Which for the root $r = \frac{1}{2}$ becomes

$$a_4 = \frac{2}{2835}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$-\frac{2}{2r^2+3r+1}$	$-\frac{2}{3}$
a_2	$\frac{4}{4r^4+20r^3+35r^2+25r+6}$	$\frac{2}{15}$
a_3	$-\frac{8}{8r^6+84r^5+350r^4+735r^3+812r^2+441r+90}$	$-\frac{4}{315}$
a_4	$\frac{16}{16r^8+288r^7+2184r^6+9072r^5+22449r^4+33642r^3+29531r^2+13698r+2520}$	$\frac{2}{2835}$

For $n = 5$, using the above recursive equation gives

$$a_5 = -\frac{32}{32r^{10} + 880r^9 + 10560r^8 + 72600r^7 + 315546r^6 + 902055r^5 + 1708465r^4 + 2102375r^3 + 1594197r^2 + 664290r + 113400}$$

Which for the root $r = \frac{1}{2}$ becomes

$$a_5 = -\frac{4}{155925}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$-\frac{2}{2r^2+3r+1}$	$-\frac{2}{3}$
a_2	$\frac{4}{4r^4+20r^3+35r^2+25r+6}$	$\frac{2}{15}$
a_3	$-\frac{8}{8r^6+84r^5+350r^4+735r^3+812r^2+441r+90}$	$-\frac{4}{315}$
a_4	$\frac{16}{16r^8+288r^7+2184r^6+9072r^5+22449r^4+33642r^3+29531r^2+13698r+2520}$	$\frac{2}{2835}$
a_5	$-\frac{32}{32r^{10}+880r^9+10560r^8+72600r^7+315546r^6+902055r^5+1708465r^4+2102375r^3+1594197r^2+664290r+113400}$	$-\frac{4}{155925}$

Using the above table, then the solution $y_1(x)$ is

$$\begin{aligned} y_1(x) &= \sqrt{x}(a_0 + a_1x + a_2x^2 + a_3x^3 + a_4x^4 + a_5x^5 + a_6x^6 \dots) \\ &= \sqrt{x} \left(1 - \frac{2x}{3} + \frac{2x^2}{15} - \frac{4x^3}{315} + \frac{2x^4}{2835} - \frac{4x^5}{155925} + O(x^6) \right) \end{aligned}$$

Now the second solution $y_2(x)$ is found. Eq (2B) derived above is now used to find all b_n coefficients. The case $n = 0$ is skipped since it was used to find the roots of the indicial equation. b_0 is arbitrary and taken as $b_0 = 1$. For $1 \leq n$ the recursive equation is

$$2b_n(n+r)(n+r-1) + (n+r)b_n + 2b_{n-1} = 0 \quad (3)$$

Solving for b_n from recursive equation (4) gives

$$b_n = -\frac{2b_{n-1}}{2n^2 + 4nr + 2r^2 - n - r} \quad (4)$$

Which for the root $r = 0$ becomes

$$b_n = -\frac{2b_{n-1}}{n(2n-1)} \quad (5)$$

At this point, it is a good idea to keep track of b_n in a table both before substituting $r = 0$ and after as more terms are found using the above recursive equation.

n	$b_{n,r}$	b_n
b_0	1	1

For $n = 1$, using the above recursive equation gives

$$b_1 = -\frac{2}{2r^2 + 3r + 1}$$

Which for the root $r = 0$ becomes

$$b_1 = -2$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	$-\frac{2}{2r^2+3r+1}$	-2

For $n = 2$, using the above recursive equation gives

$$b_2 = \frac{4}{4r^4 + 20r^3 + 35r^2 + 25r + 6}$$

Which for the root $r = 0$ becomes

$$b_2 = \frac{2}{3}$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	$-\frac{2}{2r^2+3r+1}$	-2
b_2	$\frac{4}{4r^4+20r^3+35r^2+25r+6}$	$\frac{2}{3}$

For $n = 3$, using the above recursive equation gives

$$b_3 = -\frac{8}{8r^6 + 84r^5 + 350r^4 + 735r^3 + 812r^2 + 441r + 90}$$

Which for the root $r = 0$ becomes

$$b_3 = -\frac{4}{45}$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	$-\frac{2}{2r^2+3r+1}$	-2
b_2	$\frac{4}{4r^4+20r^3+35r^2+25r+6}$	$\frac{2}{3}$
b_3	$-\frac{8}{8r^6+84r^5+350r^4+735r^3+812r^2+441r+90}$	$-\frac{4}{45}$

For $n = 4$, using the above recursive equation gives

$$b_4 = \frac{16}{16r^8 + 288r^7 + 2184r^6 + 9072r^5 + 22449r^4 + 33642r^3 + 29531r^2 + 13698r + 2520}$$

Which for the root $r = 0$ becomes

$$b_4 = \frac{2}{315}$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	$-\frac{2}{2r^2+3r+1}$	-2
b_2	$\frac{4}{4r^4+20r^3+35r^2+25r+6}$	$\frac{2}{3}$
b_3	$-\frac{8}{8r^6+84r^5+350r^4+735r^3+812r^2+441r+90}$	$-\frac{4}{45}$
b_4	$\frac{16}{16r^8+288r^7+2184r^6+9072r^5+22449r^4+33642r^3+29531r^2+13698r+2520}$	$\frac{2}{315}$

For $n = 5$, using the above recursive equation gives

$$b_5 = -\frac{32}{32r^{10} + 880r^9 + 10560r^8 + 72600r^7 + 315546r^6 + 902055r^5 + 1708465r^4 + 2102375r^3 + 1594197r^2 + 664290r + 113400}$$

Which for the root $r = 0$ becomes

$$b_5 = -\frac{4}{14175}$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	$-\frac{2}{2r^2+3r+1}$	-2
b_2	$\frac{4}{4r^4+20r^3+35r^2+25r+6}$	$\frac{2}{3}$
b_3	$-\frac{8}{8r^6+84r^5+350r^4+735r^3+812r^2+441r+90}$	$-\frac{4}{45}$
b_4	$\frac{16}{16r^8+288r^7+2184r^6+9072r^5+22449r^4+33642r^3+29531r^2+13698r+2520}$	$\frac{2}{315}$
b_5	$-\frac{32}{32r^{10}+880r^9+10560r^8+72600r^7+315546r^6+902055r^5+1708465r^4+2102375r^3+1594197r^2+664290r+113400}$	$-\frac{4}{14175}$

Using the above table, then the solution $y_2(x)$ is

$$\begin{aligned} y_2(x) &= b_0 + b_1x + b_2x^2 + b_3x^3 + b_4x^4 + b_5x^5 + b_6x^6 \dots \\ &= 1 - 2x + \frac{2x^2}{3} - \frac{4x^3}{45} + \frac{2x^4}{315} - \frac{4x^5}{14175} + O(x^6) \end{aligned}$$

Therefore the homogeneous solution is

$$\begin{aligned} y_h(x) &= c_1y_1(x) + c_2y_2(x) \\ &= c_1\sqrt{x} \left(1 - \frac{2x}{3} + \frac{2x^2}{15} - \frac{4x^3}{315} + \frac{2x^4}{2835} - \frac{4x^5}{155925} + O(x^6) \right) \\ &\quad + c_2 \left(1 - 2x + \frac{2x^2}{3} - \frac{4x^3}{45} + \frac{2x^4}{315} - \frac{4x^5}{14175} + O(x^6) \right) \end{aligned}$$

Hence the final solution is

$$\begin{aligned}
 y &= y_h \\
 &= c_1 \sqrt{x} \left(1 - \frac{2x}{3} + \frac{2x^2}{15} - \frac{4x^3}{315} + \frac{2x^4}{2835} - \frac{4x^5}{155925} + O(x^6) \right) \\
 &\quad + c_2 \left(1 - 2x + \frac{2x^2}{3} - \frac{4x^3}{45} + \frac{2x^4}{315} - \frac{4x^5}{14175} + O(x^6) \right)
 \end{aligned}$$

Summary

The solution(s) found are the following

$$\begin{aligned}
 y &= c_1 \sqrt{x} \left(1 - \frac{2x}{3} + \frac{2x^2}{15} - \frac{4x^3}{315} + \frac{2x^4}{2835} - \frac{4x^5}{155925} + O(x^6) \right) \\
 &\quad + c_2 \left(1 - 2x + \frac{2x^2}{3} - \frac{4x^3}{45} + \frac{2x^4}{315} - \frac{4x^5}{14175} + O(x^6) \right)
 \end{aligned} \tag{1}$$

Verification of solutions

$$\begin{aligned}
 y &= c_1 \sqrt{x} \left(1 - \frac{2x}{3} + \frac{2x^2}{15} - \frac{4x^3}{315} + \frac{2x^4}{2835} - \frac{4x^5}{155925} + O(x^6) \right) \\
 &\quad + c_2 \left(1 - 2x + \frac{2x^2}{3} - \frac{4x^3}{45} + \frac{2x^4}{315} - \frac{4x^5}{14175} + O(x^6) \right)
 \end{aligned}$$

Verified OK.

15.10.1 Maple step by step solution

Let's solve

$$2y''x + y' + 2y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = -\frac{y'}{2x} - \frac{y}{x}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + \frac{y'}{2x} + \frac{y}{x} = 0$$

- Check to see if $x_0 = 0$ is a regular singular point

- Define functions

$$[P_2(x) = \frac{1}{2x}, P_3(x) = \frac{1}{x}]$$

- $x \cdot P_2(x)$ is analytic at $x = 0$

$$(x \cdot P_2(x)) \Big|_{x=0} = \frac{1}{2}$$

- $x^2 \cdot P_3(x)$ is analytic at $x = 0$

$$(x^2 \cdot P_3(x)) \Big|_{x=0} = 0$$

- $x = 0$ is a regular singular point

Check to see if $x_0 = 0$ is a regular singular point

$$x_0 = 0$$

- Multiply by denominators

$$2y''x + y' + 2y = 0$$

- Assume series solution for y

$$y = \sum_{k=0}^{\infty} a_k x^{k+r}$$

- Rewrite ODE with series expansions

- Convert y' to series expansion

$$y' = \sum_{k=0}^{\infty} a_k (k+r) x^{k+r-1}$$

- Shift index using $k- > k+1$

$$y' = \sum_{k=-1}^{\infty} a_{k+1} (k+1+r) x^{k+r}$$

- Convert $x \cdot y''$ to series expansion

$$x \cdot y'' = \sum_{k=0}^{\infty} a_k (k+r)(k+r-1) x^{k+r-1}$$

- Shift index using $k- > k+1$

$$x \cdot y'' = \sum_{k=-1}^{\infty} a_{k+1} (k+1+r)(k+r) x^{k+r}$$

Rewrite ODE with series expansions

$$a_0 r(-1+2r) x^{-1+r} + \left(\sum_{k=0}^{\infty} (a_{k+1} (k+1+r)(2k+1+2r) + 2a_k) x^{k+r} \right) = 0$$

- a_0 cannot be 0 by assumption, giving the indicial equation

$$r(-1+2r) = 0$$

- Values of r that satisfy the indicial equation

$$r \in \left\{0, \frac{1}{2}\right\}$$

- Each term in the series must be 0, giving the recursion relation

$$2\left(k+r+\frac{1}{2}\right)(k+1+r)a_{k+1}+2a_k=0$$

- Recursion relation that defines series solution to ODE

$$a_{k+1} = -\frac{2a_k}{(2k+1+2r)(k+1+r)}$$

- Recursion relation for $r = 0$

$$a_{k+1} = -\frac{2a_k}{(2k+1)(k+1)}$$

- Solution for $r = 0$

$$\left[y = \sum_{k=0}^{\infty} a_k x^k, a_{k+1} = -\frac{2a_k}{(2k+1)(k+1)} \right]$$

- Recursion relation for $r = \frac{1}{2}$

$$a_{k+1} = -\frac{2a_k}{(2k+2)\left(k+\frac{3}{2}\right)}$$

- Solution for $r = \frac{1}{2}$

$$\left[y = \sum_{k=0}^{\infty} a_k x^{k+\frac{1}{2}}, a_{k+1} = -\frac{2a_k}{(2k+2)\left(k+\frac{3}{2}\right)} \right]$$

- Combine solutions and rename parameters

$$\left[y = \left(\sum_{k=0}^{\infty} a_k x^k \right) + \left(\sum_{k=0}^{\infty} b_k x^{k+\frac{1}{2}} \right), a_{1+k} = -\frac{2a_k}{(2k+1)(1+k)}, b_{1+k} = -\frac{2b_k}{(2k+2)\left(k+\frac{3}{2}\right)} \right]$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
trying a symmetry of the form [xi=0, eta=F(x)]
<- linear_1 successful`

```

✓ Solution by Maple

Time used: 0.032 (sec). Leaf size: 44

Order:=6;

```
dsolve(2*x*diff(y(x),x$2)+diff(y(x),x)+2*y(x)=0,y(x),type='series',x=0);
```

$$y(x) = c_1 \sqrt{x} \left(1 - \frac{2}{3}x + \frac{2}{15}x^2 - \frac{4}{315}x^3 + \frac{2}{2835}x^4 - \frac{4}{155925}x^5 + O(x^6) \right) \\ + c_2 \left(1 - 2x + \frac{2}{3}x^2 - \frac{4}{45}x^3 + \frac{2}{315}x^4 - \frac{4}{14175}x^5 + O(x^6) \right)$$

✓ Solution by Mathematica

Time used: 0.002 (sec). Leaf size: 83

```
AsymptoticDSolveValue[2*x*y'[x]+y'[x]+2*y[x]==0,y[x],{x,0,5}]
```

$$y(x) \rightarrow c_1 \sqrt{x} \left(-\frac{4x^5}{155925} + \frac{2x^4}{2835} - \frac{4x^3}{315} + \frac{2x^2}{15} - \frac{2x}{3} + 1 \right) \\ + c_2 \left(-\frac{4x^5}{14175} + \frac{2x^4}{315} - \frac{4x^3}{45} + \frac{2x^2}{3} - 2x + 1 \right)$$

15.11 problem 11

15.11.1 Maple step by step solution 4156

Internal problem ID [11912]

Internal file name [OUTPUT/11921_Saturday_April_13_2024_10_26_21_PM_33879010/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.2 (Frobenius). Exercises page 251

Problem number: 11.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"second order series method. Regular singular point. Difference not integer"**

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$3xy'' - (x - 2)y' - 2y = 0$$

With the expansion point for the power series method at $x = 0$.

The type of the expansion point is first determined. This is done on the homogeneous part of the ODE.

$$3xy'' + (-x + 2)y' - 2y = 0$$

The following is summary of singularities for the above ode. Writing the ode as

$$y'' + p(x)y' + q(x)y = 0$$

Where

$$p(x) = -\frac{x-2}{3x}$$
$$q(x) = -\frac{2}{3x}$$

Table 547: Table $p(x), q(x)$ singularities.

$p(x) = -\frac{x-2}{3x}$	
singularity	type
$x = 0$	“regular”

$q(x) = -\frac{2}{3x}$	
singularity	type
$x = 0$	“regular”

Combining everything together gives the following summary of singularities for the ode as

Regular singular points : $[0]$

Irregular singular points : $[\infty]$

Since $x = 0$ is regular singular point, then Frobenius power series is used. The ode is normalized to be

$$3xy'' + (-x + 2)y' - 2y = 0$$

Let the solution be represented as Frobenius power series of the form

$$y = \sum_{n=0}^{\infty} a_n x^{n+r}$$

Then

$$y' = \sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1}$$

$$y'' = \sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2}$$

Substituting the above back into the ode gives

$$3 \left(\sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2} \right) x + (-x+2) \left(\sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1} \right) - 2 \left(\sum_{n=0}^{\infty} a_n x^{n+r} \right) = 0 \quad (1)$$

Which simplifies to

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} 3x^{n+r-1} a_n (n+r) (n+r-1) \right) + \sum_{n=0}^{\infty} (-x^{n+r} a_n (n+r)) \\ & + \left(\sum_{n=0}^{\infty} 2(n+r) a_n x^{n+r-1} \right) + \sum_{n=0}^{\infty} (-2a_n x^{n+r}) = 0 \end{aligned} \quad (2A)$$

The next step is to make all powers of x be $n+r-1$ in each summation term. Going over each summation term above with power of x in it which is not already x^{n+r-1} and adjusting the power and the corresponding index gives

$$\begin{aligned} \sum_{n=0}^{\infty} (-x^{n+r} a_n (n+r)) &= \sum_{n=1}^{\infty} (-a_{n-1} (n+r-1) x^{n+r-1}) \\ \sum_{n=0}^{\infty} (-2a_n x^{n+r}) &= \sum_{n=1}^{\infty} (-2a_{n-1} x^{n+r-1}) \end{aligned}$$

Substituting all the above in Eq (2A) gives the following equation where now all powers of x are the same and equal to $n+r-1$.

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} 3x^{n+r-1} a_n (n+r) (n+r-1) \right) + \sum_{n=1}^{\infty} (-a_{n-1} (n+r-1) x^{n+r-1}) \\ & + \left(\sum_{n=0}^{\infty} 2(n+r) a_n x^{n+r-1} \right) + \sum_{n=1}^{\infty} (-2a_{n-1} x^{n+r-1}) = 0 \end{aligned} \quad (2B)$$

The indicial equation is obtained from $n=0$. From Eq (2B) this gives

$$3x^{n+r-1} a_n (n+r) (n+r-1) + 2(n+r) a_n x^{n+r-1} = 0$$

When $n=0$ the above becomes

$$3x^{-1+r} a_0 r (-1+r) + 2r a_0 x^{-1+r} = 0$$

Or

$$(3x^{-1+r} r (-1+r) + 2r x^{-1+r}) a_0 = 0$$

Since $a_0 \neq 0$ then the above simplifies to

$$r x^{-1+r} (-1+3r) = 0$$

Since the above is true for all x then the indicial equation becomes

$$3r^2 - r = 0$$

Solving for r gives the roots of the indicial equation as

$$r_1 = \frac{1}{3}$$

$$r_2 = 0$$

Since $a_0 \neq 0$ then the indicial equation becomes

$$r x^{-1+r}(-1 + 3r) = 0$$

Solving for r gives the roots of the indicial equation as Since $r_1 - r_2 = \frac{1}{3}$ is not an integer, then we can construct two linearly independent solutions

$$y_1(x) = x^{r_1} \left(\sum_{n=0}^{\infty} a_n x^n \right)$$

$$y_2(x) = x^{r_2} \left(\sum_{n=0}^{\infty} b_n x^n \right)$$

Or

$$y_1(x) = \sum_{n=0}^{\infty} a_n x^{n+\frac{1}{3}}$$

$$y_2(x) = \sum_{n=0}^{\infty} b_n x^n$$

We start by finding $y_1(x)$. Eq (2B) derived above is now used to find all a_n coefficients. The case $n = 0$ is skipped since it was used to find the roots of the indicial equation. a_0 is arbitrary and taken as $a_0 = 1$. For $1 \leq n$ the recursive equation is

$$3a_n(n+r)(n+r-1) - a_{n-1}(n+r-1) + 2a_n(n+r) - 2a_{n-1} = 0 \quad (3)$$

Solving for a_n from recursive equation (4) gives

$$a_n = \frac{a_{n-1}(n+r+1)}{3n^2 + 6nr + 3r^2 - n - r} \quad (4)$$

Which for the root $r = \frac{1}{3}$ becomes

$$a_n = \frac{3na_{n-1} + 4a_{n-1}}{9n^2 + 3n} \quad (5)$$

At this point, it is a good idea to keep track of a_n in a table both before substituting $r = \frac{1}{3}$ and after as more terms are found using the above recursive equation.

n	$a_{n,r}$	a_n
a_0	1	1

For $n = 1$, using the above recursive equation gives

$$a_1 = \frac{2 + r}{3r^2 + 5r + 2}$$

Which for the root $r = \frac{1}{3}$ becomes

$$a_1 = \frac{7}{12}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$\frac{2+r}{3r^2+5r+2}$	$\frac{7}{12}$

For $n = 2$, using the above recursive equation gives

$$a_2 = \frac{3 + r}{9r^3 + 30r^2 + 31r + 10}$$

Which for the root $r = \frac{1}{3}$ becomes

$$a_2 = \frac{5}{36}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$\frac{2+r}{3r^2+5r+2}$	$\frac{7}{12}$
a_2	$\frac{3+r}{9r^3+30r^2+31r+10}$	$\frac{5}{36}$

For $n = 3$, using the above recursive equation gives

$$a_3 = \frac{4 + r}{27r^4 + 162r^3 + 333r^2 + 278r + 80}$$

Which for the root $r = \frac{1}{3}$ becomes

$$a_3 = \frac{13}{648}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$\frac{2+r}{3r^2+5r+2}$	$\frac{7}{12}$
a_2	$\frac{3+r}{9r^3+30r^2+31r+10}$	$\frac{5}{36}$
a_3	$\frac{4+r}{27r^4+162r^3+333r^2+278r+80}$	$\frac{13}{648}$

For $n = 4$, using the above recursive equation gives

$$a_4 = \frac{5+r}{81r^5+783r^4+2781r^3+4497r^2+3298r+880}$$

Which for the root $r = \frac{1}{3}$ becomes

$$a_4 = \frac{1}{486}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$\frac{2+r}{3r^2+5r+2}$	$\frac{7}{12}$
a_2	$\frac{3+r}{9r^3+30r^2+31r+10}$	$\frac{5}{36}$
a_3	$\frac{4+r}{27r^4+162r^3+333r^2+278r+80}$	$\frac{13}{648}$
a_4	$\frac{5+r}{81r^5+783r^4+2781r^3+4497r^2+3298r+880}$	$\frac{1}{486}$

For $n = 5$, using the above recursive equation gives

$$a_5 = \frac{6+r}{243r^6+3483r^5+19305r^4+52425r^3+72852r^2+48812r+12320}$$

Which for the root $r = \frac{1}{3}$ becomes

$$a_5 = \frac{19}{116640}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$\frac{2+r}{3r^2+5r+2}$	$\frac{7}{12}$
a_2	$\frac{3+r}{9r^3+30r^2+31r+10}$	$\frac{5}{36}$
a_3	$\frac{4+r}{27r^4+162r^3+333r^2+278r+80}$	$\frac{13}{648}$
a_4	$\frac{5+r}{81r^5+783r^4+2781r^3+4497r^2+3298r+880}$	$\frac{1}{486}$
a_5	$\frac{6+r}{243r^6+3483r^5+19305r^4+52425r^3+72852r^2+48812r+12320}$	$\frac{19}{116640}$

Using the above table, then the solution $y_1(x)$ is

$$\begin{aligned}
 y_1(x) &= x^{\frac{1}{3}}(a_0 + a_1x + a_2x^2 + a_3x^3 + a_4x^4 + a_5x^5 + a_6x^6 \dots) \\
 &= x^{\frac{1}{3}}\left(1 + \frac{7x}{12} + \frac{5x^2}{36} + \frac{13x^3}{648} + \frac{x^4}{486} + \frac{19x^5}{116640} + O(x^6)\right)
 \end{aligned}$$

Now the second solution $y_2(x)$ is found. Eq (2B) derived above is now used to find all b_n coefficients. The case $n = 0$ is skipped since it was used to find the roots of the indicial equation. b_0 is arbitrary and taken as $b_0 = 1$. For $1 \leq n$ the recursive equation is

$$3b_n(n+r)(n+r-1) - b_{n-1}(n+r-1) + 2(n+r)b_n - 2b_{n-1} = 0 \quad (3)$$

Solving for b_n from recursive equation (4) gives

$$b_n = \frac{b_{n-1}(n+r+1)}{3n^2 + 6nr + 3r^2 - n - r} \quad (4)$$

Which for the root $r = 0$ becomes

$$b_n = \frac{b_{n-1}(n+1)}{n(3n-1)} \quad (5)$$

At this point, it is a good idea to keep track of b_n in a table both before substituting $r = 0$ and after as more terms are found using the above recursive equation.

n	$b_{n,r}$	b_n
b_0	1	1

For $n = 1$, using the above recursive equation gives

$$b_1 = \frac{2+r}{3r^2+5r+2}$$

Which for the root $r = 0$ becomes

$$b_1 = 1$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	$\frac{2+r}{3r^2+5r+2}$	1

For $n = 2$, using the above recursive equation gives

$$b_2 = \frac{3+r}{9r^3+30r^2+31r+10}$$

Which for the root $r = 0$ becomes

$$b_2 = \frac{3}{10}$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	$\frac{2+r}{3r^2+5r+2}$	1
b_2	$\frac{3+r}{9r^3+30r^2+31r+10}$	$\frac{3}{10}$

For $n = 3$, using the above recursive equation gives

$$b_3 = \frac{4+r}{27r^4+162r^3+333r^2+278r+80}$$

Which for the root $r = 0$ becomes

$$b_3 = \frac{1}{20}$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	$\frac{2+r}{3r^2+5r+2}$	1
b_2	$\frac{3+r}{9r^3+30r^2+31r+10}$	$\frac{3}{10}$
b_3	$\frac{4+r}{27r^4+162r^3+333r^2+278r+80}$	$\frac{1}{20}$

For $n = 4$, using the above recursive equation gives

$$b_4 = \frac{5+r}{81r^5 + 783r^4 + 2781r^3 + 4497r^2 + 3298r + 880}$$

Which for the root $r = 0$ becomes

$$b_4 = \frac{1}{176}$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	$\frac{2+r}{3r^2+5r+2}$	1
b_2	$\frac{3+r}{9r^3+30r^2+31r+10}$	$\frac{3}{10}$
b_3	$\frac{4+r}{27r^4+162r^3+333r^2+278r+80}$	$\frac{1}{20}$
b_4	$\frac{5+r}{81r^5+783r^4+2781r^3+4497r^2+3298r+880}$	$\frac{1}{176}$

For $n = 5$, using the above recursive equation gives

$$b_5 = \frac{6+r}{243r^6 + 3483r^5 + 19305r^4 + 52425r^3 + 72852r^2 + 48812r + 12320}$$

Which for the root $r = 0$ becomes

$$b_5 = \frac{3}{6160}$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	$\frac{2+r}{3r^2+5r+2}$	1
b_2	$\frac{3+r}{9r^3+30r^2+31r+10}$	$\frac{3}{10}$
b_3	$\frac{4+r}{27r^4+162r^3+333r^2+278r+80}$	$\frac{1}{20}$
b_4	$\frac{5+r}{81r^5+783r^4+2781r^3+4497r^2+3298r+880}$	$\frac{1}{176}$
b_5	$\frac{6+r}{243r^6+3483r^5+19305r^4+52425r^3+72852r^2+48812r+12320}$	$\frac{3}{6160}$

Using the above table, then the solution $y_2(x)$ is

$$\begin{aligned} y_2(x) &= b_0 + b_1x + b_2x^2 + b_3x^3 + b_4x^4 + b_5x^5 + b_6x^6 \dots \\ &= 1 + x + \frac{3x^2}{10} + \frac{x^3}{20} + \frac{x^4}{176} + \frac{3x^5}{6160} + O(x^6) \end{aligned}$$

Therefore the homogeneous solution is

$$\begin{aligned}y_h(x) &= c_1 y_1(x) + c_2 y_2(x) \\&= c_1 x^{\frac{1}{3}} \left(1 + \frac{7x}{12} + \frac{5x^2}{36} + \frac{13x^3}{648} + \frac{x^4}{486} + \frac{19x^5}{116640} + O(x^6) \right) \\&\quad + c_2 \left(1 + x + \frac{3x^2}{10} + \frac{x^3}{20} + \frac{x^4}{176} + \frac{3x^5}{6160} + O(x^6) \right)\end{aligned}$$

Hence the final solution is

$$\begin{aligned}y &= y_h \\&= c_1 x^{\frac{1}{3}} \left(1 + \frac{7x}{12} + \frac{5x^2}{36} + \frac{13x^3}{648} + \frac{x^4}{486} + \frac{19x^5}{116640} + O(x^6) \right) \\&\quad + c_2 \left(1 + x + \frac{3x^2}{10} + \frac{x^3}{20} + \frac{x^4}{176} + \frac{3x^5}{6160} + O(x^6) \right)\end{aligned}$$

Summary

The solution(s) found are the following

$$\begin{aligned}y &= c_1 x^{\frac{1}{3}} \left(1 + \frac{7x}{12} + \frac{5x^2}{36} + \frac{13x^3}{648} + \frac{x^4}{486} + \frac{19x^5}{116640} + O(x^6) \right) \\&\quad + c_2 \left(1 + x + \frac{3x^2}{10} + \frac{x^3}{20} + \frac{x^4}{176} + \frac{3x^5}{6160} + O(x^6) \right)\end{aligned} \tag{1}$$

Verification of solutions

$$\begin{aligned}y &= c_1 x^{\frac{1}{3}} \left(1 + \frac{7x}{12} + \frac{5x^2}{36} + \frac{13x^3}{648} + \frac{x^4}{486} + \frac{19x^5}{116640} + O(x^6) \right) \\&\quad + c_2 \left(1 + x + \frac{3x^2}{10} + \frac{x^3}{20} + \frac{x^4}{176} + \frac{3x^5}{6160} + O(x^6) \right)\end{aligned}$$

Verified OK.

15.11.1 Maple step by step solution

Let's solve

$$3y''x + (-x + 2)y' - 2y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = \frac{2y}{3x} + \frac{(x-2)y'}{3x}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' - \frac{(x-2)y'}{3x} - \frac{2y}{3x} = 0$$

- Check to see if $x_0 = 0$ is a regular singular point

- Define functions

$$\left[P_2(x) = -\frac{x-2}{3x}, P_3(x) = -\frac{2}{3x} \right]$$

- $x \cdot P_2(x)$ is analytic at $x = 0$

$$(x \cdot P_2(x)) \Big|_{x=0} = \frac{2}{3}$$

- $x^2 \cdot P_3(x)$ is analytic at $x = 0$

$$(x^2 \cdot P_3(x)) \Big|_{x=0} = 0$$

- $x = 0$ is a regular singular point

Check to see if $x_0 = 0$ is a regular singular point

$$x_0 = 0$$

- Multiply by denominators

$$3y''x + (-x + 2)y' - 2y = 0$$

- Assume series solution for y

$$y = \sum_{k=0}^{\infty} a_k x^{k+r}$$

- Rewrite ODE with series expansions

- Convert $x^m \cdot y'$ to series expansion for $m = 0..1$

$$x^m \cdot y' = \sum_{k=0}^{\infty} a_k (k+r) x^{k+r-1+m}$$

- Shift index using $k- \rightarrow k+1-m$

$$x^m \cdot y' = \sum_{k=-1+m}^{\infty} a_{k+1-m}(k+1-m+r) x^{k+r}$$

- Convert $x \cdot y''$ to series expansion

$$x \cdot y'' = \sum_{k=0}^{\infty} a_k(k+r)(k+r-1) x^{k+r-1}$$

- Shift index using $k- > k+1$

$$x \cdot y'' = \sum_{k=-1}^{\infty} a_{k+1}(k+1+r)(k+r) x^{k+r}$$

Rewrite ODE with series expansions

$$a_0 r(-1+3r) x^{-1+r} + \left(\sum_{k=0}^{\infty} (a_{k+1}(k+1+r)(3k+2+3r) - a_k(k+r+2)) x^{k+r} \right) = 0$$

- a_0 cannot be 0 by assumption, giving the indicial equation

$$r(-1+3r) = 0$$

- Values of r that satisfy the indicial equation

$$r \in \left\{ 0, \frac{1}{3} \right\}$$

- Each term in the series must be 0, giving the recursion relation

$$3\left(k + \frac{2}{3} + r\right)(k+1+r)a_{k+1} - a_k(k+r+2) = 0$$

- Recursion relation that defines series solution to ODE

$$a_{k+1} = \frac{a_k(k+r+2)}{(3k+2+3r)(k+1+r)}$$

- Recursion relation for $r = 0$

$$a_{k+1} = \frac{a_k(k+2)}{(3k+2)(k+1)}$$

- Solution for $r = 0$

$$\left[y = \sum_{k=0}^{\infty} a_k x^k, a_{k+1} = \frac{a_k(k+2)}{(3k+2)(k+1)} \right]$$

- Recursion relation for $r = \frac{1}{3}$

$$a_{k+1} = \frac{a_k\left(k + \frac{7}{3}\right)}{(3k+3)\left(k + \frac{4}{3}\right)}$$

- Solution for $r = \frac{1}{3}$

$$\left[y = \sum_{k=0}^{\infty} a_k x^{k+\frac{1}{3}}, a_{k+1} = \frac{a_k\left(k + \frac{7}{3}\right)}{(3k+3)\left(k + \frac{4}{3}\right)} \right]$$

- Combine solutions and rename parameters

$$\left[y = \left(\sum_{k=0}^{\infty} a_k x^k \right) + \left(\sum_{k=0}^{\infty} b_k x^{k+\frac{1}{3}} \right), a_{1+k} = \frac{a_k(k+2)}{(3k+2)(1+k)}, b_{1+k} = \frac{b_k(k+\frac{7}{3})}{(3k+3)(k+\frac{4}{3})} \right]$$

Maple trace Kovacic algorithm successful

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
trying a symmetry of the form [xi=0, eta=F(x)]
checking if the LODE is missing y
-> Trying a Liouvillian solution using Kovacics algorithm
  A Liouvillian solution exists
  Reducible group (found an exponential solution)
  Group is reducible, not completely reducible
  Solution has integrals. Trying a special function solution free of integrals...
-> Trying a solution in terms of special functions:
  -> Bessel
  -> elliptic
  -> Legendre
  <- Kummer successful
<- special function solution successful
  Solution using Kummer functions still has integrals. Trying a hypergeometric solution.
  -> hyper3: Equivalence to 2F1, 1F1 or 0F1 under a power @ Moebius
  <- hyper3 successful: received ODE is equivalent to the 1F1 ODE
  -> Trying to convert hypergeometric functions to elementary form...
  <- elementary form for at least one hypergeometric solution is achieved - returning wi
<- Kovacics algorithm successful`

```

✓ Solution by Maple

Time used: 0.031 (sec). Leaf size: 44

```

Order:=6;
dsolve(3*x*diff(y(x),x$2)-(x-2)*diff(y(x),x)-2*y(x)=0,y(x),type='series',x=0);

```

$$y(x) = c_1 x^{\frac{1}{3}} \left(1 + \frac{7}{12}x + \frac{5}{36}x^2 + \frac{13}{648}x^3 + \frac{1}{486}x^4 + \frac{19}{116640}x^5 + O(x^6) \right) + c_2 \left(1 + x + \frac{3}{10}x^2 + \frac{1}{20}x^3 + \frac{1}{176}x^4 + \frac{3}{6160}x^5 + O(x^6) \right)$$

✓ Solution by Mathematica

Time used: 0.002 (sec). Leaf size: 81

```
AsymptoticDSolveValue[3*x*y''[x]-(x-2)*y'[x]-2*y[x]==0,y[x],{x,0,5}]
```

$$y(x) \rightarrow c_1 \sqrt[3]{x} \left(\frac{19x^5}{116640} + \frac{x^4}{486} + \frac{13x^3}{648} + \frac{5x^2}{36} + \frac{7x}{12} + 1 \right) + c_2 \left(\frac{3x^5}{6160} + \frac{x^4}{176} + \frac{x^3}{20} + \frac{3x^2}{10} + x + 1 \right)$$

15.12 problem 12

15.12.1 Maple step by step solution 4169

Internal problem ID [11913]

Internal file name [OUTPUT/11922_Saturday_April_13_2024_10_26_22_PM_18318295/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.2 (Frobenius). Exercises page 251

Problem number: 12.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"second order series method. Regular singular point. Difference is integer"**

Maple gives the following as the ode type

[_Lienard]

$$xy'' + 2y' + yx = 0$$

With the expansion point for the power series method at $x = 0$.

The type of the expansion point is first determined. This is done on the homogeneous part of the ODE.

$$xy'' + 2y' + yx = 0$$

The following is summary of singularities for the above ode. Writing the ode as

$$y'' + p(x)y' + q(x)y = 0$$

Where

$$p(x) = \frac{2}{x}$$
$$q(x) = 1$$

Table 549: Table $p(x), q(x)$ singularities.

$p(x) = \frac{2}{x}$	
singularity	type
$x = 0$	“regular”

$q(x) = 1$	
singularity	type

Combining everything together gives the following summary of singularities for the ode as

Regular singular points : $[0]$

Irregular singular points : $[\infty]$

Since $x = 0$ is regular singular point, then Frobenius power series is used. The ode is normalized to be

$$xy'' + 2y' + yx = 0$$

Let the solution be represented as Frobenius power series of the form

$$y = \sum_{n=0}^{\infty} a_n x^{n+r}$$

Then

$$y' = \sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1}$$

$$y'' = \sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2}$$

Substituting the above back into the ode gives

$$\left(\sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2} \right) x + 2 \left(\sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1} \right) + \left(\sum_{n=0}^{\infty} a_n x^{n+r} \right) x = 0 \quad (1)$$

Which simplifies to

$$\left(\sum_{n=0}^{\infty} x^{n+r-1} a_n (n+r)(n+r-1) \right) + \left(\sum_{n=0}^{\infty} 2(n+r) a_n x^{n+r-1} \right) + \left(\sum_{n=0}^{\infty} x^{1+n+r} a_n \right) = 0 \quad (2A)$$

The next step is to make all powers of x be $n + r - 1$ in each summation term. Going over each summation term above with power of x in it which is not already x^{n+r-1} and adjusting the power and the corresponding index gives

$$\sum_{n=0}^{\infty} x^{1+n+r} a_n = \sum_{n=2}^{\infty} a_{n-2} x^{n+r-1}$$

Substituting all the above in Eq (2A) gives the following equation where now all powers of x are the same and equal to $n + r - 1$.

$$\left(\sum_{n=0}^{\infty} x^{n+r-1} a_n (n+r) (n+r-1) \right) + \left(\sum_{n=0}^{\infty} 2(n+r) a_n x^{n+r-1} \right) + \left(\sum_{n=2}^{\infty} a_{n-2} x^{n+r-1} \right) = 0 \quad (2B)$$

The indicial equation is obtained from $n = 0$. From Eq (2B) this gives

$$x^{n+r-1} a_n (n+r) (n+r-1) + 2(n+r) a_n x^{n+r-1} = 0$$

When $n = 0$ the above becomes

$$x^{-1+r} a_0 r (-1+r) + 2r a_0 x^{-1+r} = 0$$

Or

$$(x^{-1+r} r (-1+r) + 2r x^{-1+r}) a_0 = 0$$

Since $a_0 \neq 0$ then the above simplifies to

$$r x^{-1+r} (1+r) = 0$$

Since the above is true for all x then the indicial equation becomes

$$r(1+r) = 0$$

Solving for r gives the roots of the indicial equation as

$$r_1 = 0$$

$$r_2 = -1$$

Since $a_0 \neq 0$ then the indicial equation becomes

$$r x^{-1+r} (1+r) = 0$$

Solving for r gives the roots of the indicial equation as Since $r_1 - r_2 = 1$ is an integer, then we can construct two linearly independent solutions

$$y_1(x) = x^{r_1} \left(\sum_{n=0}^{\infty} a_n x^n \right)$$

$$y_2(x) = C y_1(x) \ln(x) + x^{r_2} \left(\sum_{n=0}^{\infty} b_n x^n \right)$$

Or

$$y_1(x) = \sum_{n=0}^{\infty} a_n x^n$$

$$y_2(x) = C y_1(x) \ln(x) + \frac{\sum_{n=0}^{\infty} b_n x^n}{x}$$

Or

$$y_1(x) = \sum_{n=0}^{\infty} a_n x^n$$

$$y_2(x) = C y_1(x) \ln(x) + \left(\sum_{n=0}^{\infty} b_n x^{n-1} \right)$$

Where C above can be zero. We start by finding y_1 . Eq (2B) derived above is now used to find all a_n coefficients. The case $n = 0$ is skipped since it was used to find the roots of the indicial equation. a_0 is arbitrary and taken as $a_0 = 1$. Substituting $n = 1$ in Eq. (2B) gives

$$a_1 = 0$$

For $2 \leq n$ the recursive equation is

$$a_n(n+r)(n+r-1) + 2a_n(n+r) + a_{n-2} = 0 \quad (3)$$

Solving for a_n from recursive equation (4) gives

$$a_n = -\frac{a_{n-2}}{n^2 + 2nr + r^2 + n + r} \quad (4)$$

Which for the root $r = 0$ becomes

$$a_n = -\frac{a_{n-2}}{n(1+n)} \quad (5)$$

At this point, it is a good idea to keep track of a_n in a table both before substituting $r = 0$ and after as more terms are found using the above recursive equation.

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0

For $n = 2$, using the above recursive equation gives

$$a_2 = -\frac{1}{r^2 + 5r + 6}$$

Which for the root $r = 0$ becomes

$$a_2 = -\frac{1}{6}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{1}{r^2+5r+6}$	$-\frac{1}{6}$

For $n = 3$, using the above recursive equation gives

$$a_3 = 0$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{1}{r^2+5r+6}$	$-\frac{1}{6}$
a_3	0	0

For $n = 4$, using the above recursive equation gives

$$a_4 = \frac{1}{r^4 + 14r^3 + 71r^2 + 154r + 120}$$

Which for the root $r = 0$ becomes

$$a_4 = \frac{1}{120}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{1}{r^2+5r+6}$	$-\frac{1}{6}$
a_3	0	0
a_4	$\frac{1}{r^4+14r^3+71r^2+154r+120}$	$\frac{1}{120}$

For $n = 5$, using the above recursive equation gives

$$a_5 = 0$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{1}{r^2+5r+6}$	$-\frac{1}{6}$
a_3	0	0
a_4	$\frac{1}{r^4+14r^3+71r^2+154r+120}$	$\frac{1}{120}$
a_5	0	0

Using the above table, then the solution $y_1(x)$ is

$$\begin{aligned} y_1(x) &= a_0 + a_1x + a_2x^2 + a_3x^3 + a_4x^4 + a_5x^5 + a_6x^6 \dots \\ &= 1 - \frac{x^2}{6} + \frac{x^4}{120} + O(x^6) \end{aligned}$$

Now the second solution $y_2(x)$ is found. Let

$$r_1 - r_2 = N$$

Where N is positive integer which is the difference between the two roots. r_1 is taken as the larger root. Hence for this problem we have $N = 1$. Now we need to determine if

C is zero or not. This is done by finding $\lim_{r \rightarrow r_2} a_1(r)$. If this limit exists, then $C = 0$, else we need to keep the log term and $C \neq 0$. The above table shows that

$$\begin{aligned} a_N &= a_1 \\ &= 0 \end{aligned}$$

Therefore

$$\begin{aligned} \lim_{r \rightarrow r_2} 0 &= \lim_{r \rightarrow -1} 0 \\ &= 0 \end{aligned}$$

The limit is 0. Since the limit exists then the log term is not needed and we can set $C = 0$. Therefore the second solution has the form

$$\begin{aligned} y_2(x) &= \sum_{n=0}^{\infty} b_n x^{n+r} \\ &= \sum_{n=0}^{\infty} b_n x^{n-1} \end{aligned}$$

Eq (3) derived above is used to find all b_n coefficients. The case $n = 0$ is skipped since it was used to find the roots of the indicial equation. b_0 is arbitrary and taken as $b_0 = 1$. Substituting $n = 1$ in Eq(3) gives

$$b_1 = 0$$

For $2 \leq n$ the recursive equation is

$$b_n(n+r)(n+r-1) + 2(n+r)b_n + b_{n-2} = 0 \quad (4)$$

Which for the root $r = -1$ becomes

$$b_n(n-1)(n-2) + 2(n-1)b_n + b_{n-2} = 0 \quad (4A)$$

Solving for b_n from the recursive equation (4) gives

$$b_n = -\frac{b_{n-2}}{n^2 + 2nr + r^2 + n + r} \quad (5)$$

Which for the root $r = -1$ becomes

$$b_n = -\frac{b_{n-2}}{n^2 - n} \quad (6)$$

At this point, it is a good idea to keep track of b_n in a table both before substituting $r = -1$ and after as more terms are found using the above recursive equation.

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0

For $n = 2$, using the above recursive equation gives

$$b_2 = -\frac{1}{r^2 + 5r + 6}$$

Which for the root $r = -1$ becomes

$$b_2 = -\frac{1}{2}$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0
b_2	$-\frac{1}{r^2+5r+6}$	$-\frac{1}{2}$

For $n = 3$, using the above recursive equation gives

$$b_3 = 0$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0
b_2	$-\frac{1}{r^2+5r+6}$	$-\frac{1}{2}$
b_3	0	0

For $n = 4$, using the above recursive equation gives

$$b_4 = \frac{1}{(r^2 + 5r + 6)(r^2 + 9r + 20)}$$

Which for the root $r = -1$ becomes

$$b_4 = \frac{1}{24}$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0
b_2	$-\frac{1}{r^2+5r+6}$	$-\frac{1}{2}$
b_3	0	0
b_4	$\frac{1}{r^4+14r^3+71r^2+154r+120}$	$\frac{1}{24}$

For $n = 5$, using the above recursive equation gives

$$b_5 = 0$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0
b_2	$-\frac{1}{r^2+5r+6}$	$-\frac{1}{2}$
b_3	0	0
b_4	$\frac{1}{r^4+14r^3+71r^2+154r+120}$	$\frac{1}{24}$
b_5	0	0

Using the above table, then the solution $y_2(x)$ is

$$\begin{aligned} y_2(x) &= 1(b_0 + b_1x + b_2x^2 + b_3x^3 + b_4x^4 + b_5x^5 + b_6x^6 \dots) \\ &= \frac{1 - \frac{x^2}{2} + \frac{x^4}{24} + O(x^6)}{x} \end{aligned}$$

Therefore the homogeneous solution is

$$\begin{aligned} y_h(x) &= c_1y_1(x) + c_2y_2(x) \\ &= c_1\left(1 - \frac{x^2}{6} + \frac{x^4}{120} + O(x^6)\right) + \frac{c_2\left(1 - \frac{x^2}{2} + \frac{x^4}{24} + O(x^6)\right)}{x} \end{aligned}$$

Hence the final solution is

$$\begin{aligned}y &= y_h \\ &= c_1 \left(1 - \frac{x^2}{6} + \frac{x^4}{120} + O(x^6) \right) + \frac{c_2 \left(1 - \frac{x^2}{2} + \frac{x^4}{24} + O(x^6) \right)}{x}\end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 \left(1 - \frac{x^2}{6} + \frac{x^4}{120} + O(x^6) \right) + \frac{c_2 \left(1 - \frac{x^2}{2} + \frac{x^4}{24} + O(x^6) \right)}{x} \quad (1)$$

Verification of solutions

$$y = c_1 \left(1 - \frac{x^2}{6} + \frac{x^4}{120} + O(x^6) \right) + \frac{c_2 \left(1 - \frac{x^2}{2} + \frac{x^4}{24} + O(x^6) \right)}{x}$$

Verified OK.

15.12.1 Maple step by step solution

Let's solve

$$y''x + 2y' + yx = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = -\frac{2y'}{x} - y$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + \frac{2y'}{x} + y = 0$$

- Check to see if $x_0 = 0$ is a regular singular point

- Define functions

$$[P_2(x) = \frac{2}{x}, P_3(x) = 1]$$

- $x \cdot P_2(x)$ is analytic at $x = 0$

$$(x \cdot P_2(x)) \Big|_{x=0} = 2$$

- $x^2 \cdot P_3(x)$ is analytic at $x = 0$

$$(x^2 \cdot P_3(x)) \Big|_{x=0} = 0$$

- $x = 0$ is a regular singular point

Check to see if $x_0 = 0$ is a regular singular point

$$x_0 = 0$$

- Multiply by denominators

$$y''x + 2y' + yx = 0$$

- Assume series solution for y

$$y = \sum_{k=0}^{\infty} a_k x^{k+r}$$

- Rewrite ODE with series expansions

- Convert $x \cdot y$ to series expansion

$$x \cdot y = \sum_{k=0}^{\infty} a_k x^{k+r+1}$$

- Shift index using $k \rightarrow k - 1$

$$x \cdot y = \sum_{k=1}^{\infty} a_{k-1} x^{k+r}$$

- Convert y' to series expansion

$$y' = \sum_{k=0}^{\infty} a_k (k+r) x^{k+r-1}$$

- Shift index using $k \rightarrow k + 1$

$$y' = \sum_{k=-1}^{\infty} a_{k+1} (k+r+1) x^{k+r}$$

- Convert $x \cdot y''$ to series expansion

$$x \cdot y'' = \sum_{k=0}^{\infty} a_k (k+r)(k+r-1) x^{k+r-1}$$

- Shift index using $k \rightarrow k + 1$

$$x \cdot y'' = \sum_{k=-1}^{\infty} a_{k+1} (k+r+1)(k+r) x^{k+r}$$

Rewrite ODE with series expansions

$$a_0 r(1+r) x^{-1+r} + a_1 (1+r)(2+r) x^r + \left(\sum_{k=1}^{\infty} (a_{k+1} (k+r+1)(k+2+r) + a_{k-1}) x^{k+r} \right) = 0$$

- a_0 cannot be 0 by assumption, giving the indicial equation

$$r(1+r) = 0$$

- Values of r that satisfy the indicial equation

$$r \in \{-1, 0\}$$

- Each term must be 0

$$a_1(1+r)(2+r) = 0$$

- Each term in the series must be 0, giving the recursion relation

$$a_{k+1}(k+r+1)(k+2+r) + a_{k-1} = 0$$

- Shift index using $k \rightarrow k+1$

$$a_{k+2}(k+2+r)(k+3+r) + a_k = 0$$

- Recursion relation that defines series solution to ODE

$$a_{k+2} = -\frac{a_k}{(k+2+r)(k+3+r)}$$

- Recursion relation for $r = -1$

$$a_{k+2} = -\frac{a_k}{(k+1)(k+2)}$$

- Solution for $r = -1$

$$\left[y = \sum_{k=0}^{\infty} a_k x^{k-1}, a_{k+2} = -\frac{a_k}{(k+1)(k+2)}, 0 = 0 \right]$$

- Recursion relation for $r = 0$

$$a_{k+2} = -\frac{a_k}{(k+2)(k+3)}$$

- Solution for $r = 0$

$$\left[y = \sum_{k=0}^{\infty} a_k x^k, a_{k+2} = -\frac{a_k}{(k+2)(k+3)}, 2a_1 = 0 \right]$$

- Combine solutions and rename parameters

$$\left[y = \left(\sum_{k=0}^{\infty} a_k x^{k-1} \right) + \left(\sum_{k=0}^{\infty} b_k x^k \right), a_{k+2} = -\frac{a_k}{(1+k)(k+2)}, 0 = 0, b_{k+2} = -\frac{b_k}{(k+2)(k+3)}, 2b_1 = 0 \right]$$

Maple trace Kovacic algorithm successful

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
checking if the LODE is of Euler type  
trying a symmetry of the form [xi=0, eta=F(x)]  
checking if the LODE is missing y  
-> Trying a Liouvillian solution using Kovacics algorithm  
    A Liouvillian solution exists  
    Group is reducible or imprimitive  
<- Kovacics algorithm successful`
```

✓ Solution by Maple

Time used: 0.031 (sec). Leaf size: 32

```
Order:=6;  
dsolve(x*diff(y(x),x$2)+2*diff(y(x),x)+x*y(x)=0,y(x),type='series',x=0);
```

$$y(x) = c_1 \left(1 - \frac{1}{6}x^2 + \frac{1}{120}x^4 + O(x^6) \right) + \frac{c_2 \left(1 - \frac{1}{2}x^2 + \frac{1}{24}x^4 + O(x^6) \right)}{x}$$

✓ Solution by Mathematica

Time used: 0.008 (sec). Leaf size: 42

```
AsymptoticDSolveValue[x*y''[x]+2*y'[x]+x*y[x]==0,y[x],{x,0,5}]
```

$$y(x) \rightarrow c_1 \left(\frac{x^3}{24} - \frac{x}{2} + \frac{1}{x} \right) + c_2 \left(\frac{x^4}{120} - \frac{x^2}{6} + 1 \right)$$

15.13 problem 13

15.13.1 Maple step by step solution 4182

Internal problem ID [11914]

Internal file name [OUTPUT/11923_Saturday_April_13_2024_10_26_23_PM_34633178/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.2 (Frobenius). Exercises page 251

Problem number: 13.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"second order series method. Regular singular point. Difference is integer"**

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$x^2y'' + y'x + \left(x^2 - \frac{1}{4}\right)y = 0$$

With the expansion point for the power series method at $x = 0$.

The type of the expansion point is first determined. This is done on the homogeneous part of the ODE.

$$x^2y'' + y'x + \left(x^2 - \frac{1}{4}\right)y = 0$$

The following is summary of singularities for the above ode. Writing the ode as

$$y'' + p(x)y' + q(x)y = 0$$

Where

$$p(x) = \frac{1}{x}$$
$$q(x) = \frac{4x^2 - 1}{4x^2}$$

Table 551: Table $p(x), q(x)$ singularities.

$p(x) = \frac{1}{x}$	
singularity	type
$x = 0$	“regular”

$q(x) = \frac{4x^2-1}{4x^2}$	
singularity	type
$x = 0$	“regular”

Combining everything together gives the following summary of singularities for the ode as

Regular singular points : $[0]$

Irregular singular points : $[\infty]$

Since $x = 0$ is regular singular point, then Frobenius power series is used. The ode is normalized to be

$$x^2 y'' + y'x + \left(x^2 - \frac{1}{4}\right) y = 0$$

Let the solution be represented as Frobenius power series of the form

$$y = \sum_{n=0}^{\infty} a_n x^{n+r}$$

Then

$$y' = \sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1}$$

$$y'' = \sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2}$$

Substituting the above back into the ode gives

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2} \right) x^2 \\ & + \left(\sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1} \right) x + \left(x^2 - \frac{1}{4} \right) \left(\sum_{n=0}^{\infty} a_n x^{n+r} \right) = 0 \end{aligned} \tag{1}$$

Which simplifies to

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} x^{n+r} a_n (n+r) (n+r-1) \right) + \left(\sum_{n=0}^{\infty} x^{n+r} a_n (n+r) \right) \\ & + \left(\sum_{n=0}^{\infty} x^{n+r+2} a_n \right) + \sum_{n=0}^{\infty} \left(-\frac{a_n x^{n+r}}{4} \right) = 0 \end{aligned} \quad (2A)$$

The next step is to make all powers of x be $n+r$ in each summation term. Going over each summation term above with power of x in it which is not already x^{n+r} and adjusting the power and the corresponding index gives

$$\sum_{n=0}^{\infty} x^{n+r+2} a_n = \sum_{n=2}^{\infty} a_{n-2} x^{n+r}$$

Substituting all the above in Eq (2A) gives the following equation where now all powers of x are the same and equal to $n+r$.

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} x^{n+r} a_n (n+r) (n+r-1) \right) + \left(\sum_{n=0}^{\infty} x^{n+r} a_n (n+r) \right) \\ & + \left(\sum_{n=2}^{\infty} a_{n-2} x^{n+r} \right) + \sum_{n=0}^{\infty} \left(-\frac{a_n x^{n+r}}{4} \right) = 0 \end{aligned} \quad (2B)$$

The indicial equation is obtained from $n=0$. From Eq (2B) this gives

$$x^{n+r} a_n (n+r) (n+r-1) + x^{n+r} a_n (n+r) - \frac{a_n x^{n+r}}{4} = 0$$

When $n=0$ the above becomes

$$x^r a_0 r (-1+r) + x^r a_0 r - \frac{a_0 x^r}{4} = 0$$

Or

$$\left(x^r r (-1+r) + x^r r - \frac{x^r}{4} \right) a_0 = 0$$

Since $a_0 \neq 0$ then the above simplifies to

$$\frac{(4r^2 - 1) x^r}{4} = 0$$

Since the above is true for all x then the indicial equation becomes

$$r^2 - \frac{1}{4} = 0$$

Solving for r gives the roots of the indicial equation as

$$r_1 = \frac{1}{2}$$

$$r_2 = -\frac{1}{2}$$

Since $a_0 \neq 0$ then the indicial equation becomes

$$\frac{(4r^2 - 1)x^r}{4} = 0$$

Solving for r gives the roots of the indicial equation as Since $r_1 - r_2 = 1$ is an integer, then we can construct two linearly independent solutions

$$y_1(x) = x^{r_1} \left(\sum_{n=0}^{\infty} a_n x^n \right)$$

$$y_2(x) = C y_1(x) \ln(x) + x^{r_2} \left(\sum_{n=0}^{\infty} b_n x^n \right)$$

Or

$$y_1(x) = \sqrt{x} \left(\sum_{n=0}^{\infty} a_n x^n \right)$$

$$y_2(x) = C y_1(x) \ln(x) + \frac{\sum_{n=0}^{\infty} b_n x^n}{\sqrt{x}}$$

Or

$$y_1(x) = \sum_{n=0}^{\infty} a_n x^{n+\frac{1}{2}}$$

$$y_2(x) = C y_1(x) \ln(x) + \left(\sum_{n=0}^{\infty} b_n x^{n-\frac{1}{2}} \right)$$

Where C above can be zero. We start by finding y_1 . Eq (2B) derived above is now used to find all a_n coefficients. The case $n = 0$ is skipped since it was used to find the roots of the indicial equation. a_0 is arbitrary and taken as $a_0 = 1$. Substituting $n = 1$ in Eq. (2B) gives

$$a_1 = 0$$

For $2 \leq n$ the recursive equation is

$$a_n(n+r)(n+r-1) + a_n(n+r) + a_{n-2} - \frac{a_n}{4} = 0 \quad (3)$$

Solving for a_n from recursive equation (4) gives

$$a_n = -\frac{4a_{n-2}}{4n^2 + 8nr + 4r^2 - 1} \quad (4)$$

Which for the root $r = \frac{1}{2}$ becomes

$$a_n = -\frac{a_{n-2}}{n(n+1)} \quad (5)$$

At this point, it is a good idea to keep track of a_n in a table both before substituting $r = \frac{1}{2}$ and after as more terms are found using the above recursive equation.

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0

For $n = 2$, using the above recursive equation gives

$$a_2 = -\frac{4}{4r^2 + 16r + 15}$$

Which for the root $r = \frac{1}{2}$ becomes

$$a_2 = -\frac{1}{6}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{4}{4r^2+16r+15}$	$-\frac{1}{6}$

For $n = 3$, using the above recursive equation gives

$$a_3 = 0$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{4}{4r^2+16r+15}$	$-\frac{1}{6}$
a_3	0	0

For $n = 4$, using the above recursive equation gives

$$a_4 = \frac{16}{(4r^2 + 16r + 15)(4r^2 + 32r + 63)}$$

Which for the root $r = \frac{1}{2}$ becomes

$$a_4 = \frac{1}{120}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{4}{4r^2+16r+15}$	$-\frac{1}{6}$
a_3	0	0
a_4	$\frac{16}{(4r^2+16r+15)(4r^2+32r+63)}$	$\frac{1}{120}$

For $n = 5$, using the above recursive equation gives

$$a_5 = 0$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{4}{4r^2+16r+15}$	$-\frac{1}{6}$
a_3	0	0
a_4	$\frac{16}{(4r^2+16r+15)(4r^2+32r+63)}$	$\frac{1}{120}$
a_5	0	0

Using the above table, then the solution $y_1(x)$ is

$$\begin{aligned} y_1(x) &= \sqrt{x}(a_0 + a_1x + a_2x^2 + a_3x^3 + a_4x^4 + a_5x^5 + a_6x^6 \dots) \\ &= \sqrt{x} \left(1 - \frac{x^2}{6} + \frac{x^4}{120} + O(x^6) \right) \end{aligned}$$

Now the second solution $y_2(x)$ is found. Let

$$r_1 - r_2 = N$$

Where N is positive integer which is the difference between the two roots. r_1 is taken as the larger root. Hence for this problem we have $N = 1$. Now we need to determine if C is zero or not. This is done by finding $\lim_{r \rightarrow r_2} a_1(r)$. If this limit exists, then $C = 0$, else we need to keep the log term and $C \neq 0$. The above table shows that

$$\begin{aligned} a_N &= a_1 \\ &= 0 \end{aligned}$$

Therefore

$$\begin{aligned} \lim_{r \rightarrow r_2} 0 &= \lim_{r \rightarrow -\frac{1}{2}} 0 \\ &= 0 \end{aligned}$$

The limit is 0. Since the limit exists then the log term is not needed and we can set $C = 0$. Therefore the second solution has the form

$$\begin{aligned} y_2(x) &= \sum_{n=0}^{\infty} b_n x^{n+r} \\ &= \sum_{n=0}^{\infty} b_n x^{n-\frac{1}{2}} \end{aligned}$$

Eq (3) derived above is used to find all b_n coefficients. The case $n = 0$ is skipped since it was used to find the roots of the indicial equation. b_0 is arbitrary and taken as $b_0 = 1$. Substituting $n = 1$ in Eq(3) gives

$$b_1 = 0$$

For $2 \leq n$ the recursive equation is

$$b_n(n+r)(n+r-1) + b_n(n+r) + b_{n-2} - \frac{b_n}{4} = 0 \quad (4)$$

Which for the root $r = -\frac{1}{2}$ becomes

$$b_n \left(n - \frac{1}{2} \right) \left(n - \frac{3}{2} \right) + b_n \left(n - \frac{1}{2} \right) + b_{n-2} - \frac{b_n}{4} = 0 \quad (4A)$$

Solving for b_n from the recursive equation (4) gives

$$b_n = -\frac{4b_{n-2}}{4n^2 + 8nr + 4r^2 - 1} \quad (5)$$

Which for the root $r = -\frac{1}{2}$ becomes

$$b_n = -\frac{4b_{n-2}}{4n^2 - 4n} \quad (6)$$

At this point, it is a good idea to keep track of b_n in a table both before substituting $r = -\frac{1}{2}$ and after as more terms are found using the above recursive equation.

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0

For $n = 2$, using the above recursive equation gives

$$b_2 = -\frac{4}{4r^2 + 16r + 15}$$

Which for the root $r = -\frac{1}{2}$ becomes

$$b_2 = -\frac{1}{2}$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0
b_2	$-\frac{4}{4r^2+16r+15}$	$-\frac{1}{2}$

For $n = 3$, using the above recursive equation gives

$$b_3 = 0$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0
b_2	$-\frac{4}{4r^2+16r+15}$	$-\frac{1}{2}$
b_3	0	0

For $n = 4$, using the above recursive equation gives

$$b_4 = \frac{16}{(4r^2 + 16r + 15)(4r^2 + 32r + 63)}$$

Which for the root $r = -\frac{1}{2}$ becomes

$$b_4 = \frac{1}{24}$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0
b_2	$-\frac{4}{4r^2+16r+15}$	$-\frac{1}{2}$
b_3	0	0
b_4	$\frac{16}{(4r^2+16r+15)(4r^2+32r+63)}$	$\frac{1}{24}$

For $n = 5$, using the above recursive equation gives

$$b_5 = 0$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0
b_2	$-\frac{4}{4r^2+16r+15}$	$-\frac{1}{2}$
b_3	0	0
b_4	$\frac{16}{(4r^2+16r+15)(4r^2+32r+63)}$	$\frac{1}{24}$
b_5	0	0

Using the above table, then the solution $y_2(x)$ is

$$\begin{aligned} y_2(x) &= \sqrt{x}(b_0 + b_1x + b_2x^2 + b_3x^3 + b_4x^4 + b_5x^5 + b_6x^6 \dots) \\ &= \frac{1 - \frac{x^2}{2} + \frac{x^4}{24} + O(x^6)}{\sqrt{x}} \end{aligned}$$

Therefore the homogeneous solution is

$$\begin{aligned} y_h(x) &= c_1y_1(x) + c_2y_2(x) \\ &= c_1\sqrt{x} \left(1 - \frac{x^2}{6} + \frac{x^4}{120} + O(x^6) \right) + \frac{c_2 \left(1 - \frac{x^2}{2} + \frac{x^4}{24} + O(x^6) \right)}{\sqrt{x}} \end{aligned}$$

Hence the final solution is

$$\begin{aligned} y &= y_h \\ &= c_1\sqrt{x} \left(1 - \frac{x^2}{6} + \frac{x^4}{120} + O(x^6) \right) + \frac{c_2 \left(1 - \frac{x^2}{2} + \frac{x^4}{24} + O(x^6) \right)}{\sqrt{x}} \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1\sqrt{x} \left(1 - \frac{x^2}{6} + \frac{x^4}{120} + O(x^6) \right) + \frac{c_2 \left(1 - \frac{x^2}{2} + \frac{x^4}{24} + O(x^6) \right)}{\sqrt{x}} \quad (1)$$

Verification of solutions

$$y = c_1\sqrt{x} \left(1 - \frac{x^2}{6} + \frac{x^4}{120} + O(x^6) \right) + \frac{c_2 \left(1 - \frac{x^2}{2} + \frac{x^4}{24} + O(x^6) \right)}{\sqrt{x}}$$

Verified OK.

15.13.1 Maple step by step solution

Let's solve

$$y''x^2 + y'x + \left(x^2 - \frac{1}{4}\right)y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = -\frac{(4x^2-1)y}{4x^2} - \frac{y'}{x}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + \frac{y'}{x} + \frac{(4x^2-1)y}{4x^2} = 0$$

- Check to see if $x_0 = 0$ is a regular singular point

- Define functions

$$\left[P_2(x) = \frac{1}{x}, P_3(x) = \frac{4x^2-1}{4x^2} \right]$$

- $x \cdot P_2(x)$ is analytic at $x = 0$

$$(x \cdot P_2(x)) \Big|_{x=0} = 1$$

- $x^2 \cdot P_3(x)$ is analytic at $x = 0$

$$(x^2 \cdot P_3(x)) \Big|_{x=0} = -\frac{1}{4}$$

- $x = 0$ is a regular singular point

Check to see if $x_0 = 0$ is a regular singular point

$$x_0 = 0$$

- Multiply by denominators

$$4y''x^2 + 4y'x + (4x^2 - 1)y = 0$$

- Assume series solution for y

$$y = \sum_{k=0}^{\infty} a_k x^{k+r}$$

- Rewrite ODE with series expansions

- Convert $x^m \cdot y$ to series expansion for $m = 0..2$

$$x^m \cdot y = \sum_{k=0}^{\infty} a_k x^{k+r+m}$$

- Shift index using $k \rightarrow k - m$

$$x^m \cdot y = \sum_{k=m}^{\infty} a_{k-m} x^{k+r}$$

- Convert $x \cdot y'$ to series expansion

$$x \cdot y' = \sum_{k=0}^{\infty} a_k (k+r) x^{k+r}$$

- Convert $x^2 \cdot y''$ to series expansion

$$x^2 \cdot y'' = \sum_{k=0}^{\infty} a_k (k+r)(k+r-1) x^{k+r}$$

Rewrite ODE with series expansions

$$a_0(1+2r)(-1+2r)x^r + a_1(3+2r)(1+2r)x^{1+r} + \left(\sum_{k=2}^{\infty} (a_k(2k+2r+1)(2k+2r-1) + 4a_{k-2}) \right) x^{k+r} = 0$$

- a_0 cannot be 0 by assumption, giving the indicial equation

$$(1+2r)(-1+2r) = 0$$
- Values of r that satisfy the indicial equation

$$r \in \left\{ -\frac{1}{2}, \frac{1}{2} \right\}$$
- Each term must be 0

$$a_1(3+2r)(1+2r) = 0$$
- Solve for the dependent coefficient(s)

$$a_1 = 0$$
- Each term in the series must be 0, giving the recursion relation

$$a_k(4k^2 + 8kr + 4r^2 - 1) + 4a_{k-2} = 0$$
- Shift index using $k- > k+2$

$$a_{k+2}(4(k+2)^2 + 8(k+2)r + 4r^2 - 1) + 4a_k = 0$$
- Recursion relation that defines series solution to ODE

$$a_{k+2} = -\frac{4a_k}{4k^2 + 8kr + 4r^2 + 16k + 16r + 15}$$
- Recursion relation for $r = -\frac{1}{2}$

$$a_{k+2} = -\frac{4a_k}{4k^2 + 12k + 8}$$
- Solution for $r = -\frac{1}{2}$

$$\left[y = \sum_{k=0}^{\infty} a_k x^{k-\frac{1}{2}}, a_{k+2} = -\frac{4a_k}{4k^2 + 12k + 8}, a_1 = 0 \right]$$
- Recursion relation for $r = \frac{1}{2}$

$$a_{k+2} = -\frac{4a_k}{4k^2 + 20k + 24}$$
- Solution for $r = \frac{1}{2}$

$$\left[y = \sum_{k=0}^{\infty} a_k x^{k+\frac{1}{2}}, a_{k+2} = -\frac{4a_k}{4k^2 + 20k + 24}, a_1 = 0 \right]$$
- Combine solutions and rename parameters

$$\left[y = \left(\sum_{k=0}^{\infty} a_k x^{k-\frac{1}{2}} \right) + \left(\sum_{k=0}^{\infty} b_k x^{k+\frac{1}{2}} \right), a_{k+2} = -\frac{4a_k}{4k^2+12k+8}, a_1 = 0, b_{k+2} = -\frac{4b_k}{4k^2+20k+24}, b_1 = 0 \right]$$

Maple trace Kovacic algorithm successful

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
trying a symmetry of the form [xi=0, eta=F(x)]
checking if the LODE is missing y
-> Trying a Liouvillian solution using Kovacics algorithm
    A Liouvillian solution exists
    Group is reducible or imprimitive
<- Kovacics algorithm successful`

```

✓ Solution by Maple

Time used: 0.047 (sec). Leaf size: 35

```

Order:=6;
dsolve(x^2*diff(y(x),x$2)+x*diff(y(x),x)+(x^2-1/4)*y(x)=0,y(x),type='series',x=0);

```

$$y(x) = \frac{c_1 \left(1 - \frac{1}{6}x^2 + \frac{1}{120}x^4 + O(x^6) \right) x + c_2 \left(1 - \frac{1}{2}x^2 + \frac{1}{24}x^4 + O(x^6) \right)}{\sqrt{x}}$$

✓ Solution by Mathematica

Time used: 0.01 (sec). Leaf size: 58

```

AsymptoticDSolveValue[x^2*y''[x]+x*y'[x]+(x^2-1/4)*y[x]==0,y[x],{x,0,5}]

```

$$y(x) \rightarrow c_1 \left(\frac{x^{7/2}}{24} - \frac{x^{3/2}}{2} + \frac{1}{\sqrt{x}} \right) + c_2 \left(\frac{x^{9/2}}{120} - \frac{x^{5/2}}{6} + \sqrt{x} \right)$$

15.14 problem 14

15.14.1 Maple step by step solution 4195

Internal problem ID [11915]

Internal file name [OUTPUT/11924_Saturday_April_13_2024_10_26_24_PM_10607916/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.2 (Frobenius). Exercises page 251

Problem number: 14.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"second order series method. Regular singular point. Difference is integer"**

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$x^2y'' + (x^4 + x)y' - y = 0$$

With the expansion point for the power series method at $x = 0$.

The type of the expansion point is first determined. This is done on the homogeneous part of the ODE.

$$x^2y'' + (x^4 + x)y' - y = 0$$

The following is summary of singularities for the above ode. Writing the ode as

$$y'' + p(x)y' + q(x)y = 0$$

Where

$$p(x) = \frac{x^3 + 1}{x}$$
$$q(x) = -\frac{1}{x^2}$$

Table 553: Table $p(x), q(x)$ singularities.

$p(x) = \frac{x^3+1}{x}$	
singularity	type
$x = 0$	“regular”
$x = \infty$	“regular”
$x = -\infty$	“regular”

$q(x) = -\frac{1}{x^2}$	
singularity	type
$x = 0$	“regular”

Combining everything together gives the following summary of singularities for the ode as

Regular singular points : $[0, \infty, -\infty]$

Irregular singular points : $[\infty]$

Since $x = 0$ is regular singular point, then Frobenius power series is used. The ode is normalized to be

$$x^2 y'' + (x^4 + x) y' - y = 0$$

Let the solution be represented as Frobenius power series of the form

$$y = \sum_{n=0}^{\infty} a_n x^{n+r}$$

Then

$$y' = \sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1}$$

$$y'' = \sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2}$$

Substituting the above back into the ode gives

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2} \right) x^2 \\ & + (x^4 + x) \left(\sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1} \right) - \left(\sum_{n=0}^{\infty} a_n x^{n+r} \right) = 0 \end{aligned} \tag{1}$$

Which simplifies to

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} x^{n+r} a_n (n+r) (n+r-1) \right) + \left(\sum_{n=0}^{\infty} x^{n+r+3} a_n (n+r) \right) \\ & + \left(\sum_{n=0}^{\infty} x^{n+r} a_n (n+r) \right) + \sum_{n=0}^{\infty} (-a_n x^{n+r}) = 0 \end{aligned} \quad (2A)$$

The next step is to make all powers of x be $n+r$ in each summation term. Going over each summation term above with power of x in it which is not already x^{n+r} and adjusting the power and the corresponding index gives

$$\sum_{n=0}^{\infty} x^{n+r+3} a_n (n+r) = \sum_{n=3}^{\infty} a_{n-3} (n-3+r) x^{n+r}$$

Substituting all the above in Eq (2A) gives the following equation where now all powers of x are the same and equal to $n+r$.

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} x^{n+r} a_n (n+r) (n+r-1) \right) + \left(\sum_{n=3}^{\infty} a_{n-3} (n-3+r) x^{n+r} \right) \\ & + \left(\sum_{n=0}^{\infty} x^{n+r} a_n (n+r) \right) + \sum_{n=0}^{\infty} (-a_n x^{n+r}) = 0 \end{aligned} \quad (2B)$$

The indicial equation is obtained from $n=0$. From Eq (2B) this gives

$$x^{n+r} a_n (n+r) (n+r-1) + x^{n+r} a_n (n+r) - a_n x^{n+r} = 0$$

When $n=0$ the above becomes

$$x^r a_0 r (-1+r) + x^r a_0 r - a_0 x^r = 0$$

Or

$$(x^r r (-1+r) + x^r r - x^r) a_0 = 0$$

Since $a_0 \neq 0$ then the above simplifies to

$$(r^2 - 1) x^r = 0$$

Since the above is true for all x then the indicial equation becomes

$$r^2 - 1 = 0$$

Solving for r gives the roots of the indicial equation as

$$\begin{aligned} r_1 &= 1 \\ r_2 &= -1 \end{aligned}$$

Since $a_0 \neq 0$ then the indicial equation becomes

$$(r^2 - 1) x^r = 0$$

Solving for r gives the roots of the indicial equation as Since $r_1 - r_2 = 2$ is an integer, then we can construct two linearly independent solutions

$$\begin{aligned} y_1(x) &= x^{r_1} \left(\sum_{n=0}^{\infty} a_n x^n \right) \\ y_2(x) &= C y_1(x) \ln(x) + x^{r_2} \left(\sum_{n=0}^{\infty} b_n x^n \right) \end{aligned}$$

Or

$$\begin{aligned} y_1(x) &= x \left(\sum_{n=0}^{\infty} a_n x^n \right) \\ y_2(x) &= C y_1(x) \ln(x) + \frac{\sum_{n=0}^{\infty} b_n x^n}{x} \end{aligned}$$

Or

$$\begin{aligned} y_1(x) &= \sum_{n=0}^{\infty} a_n x^{n+1} \\ y_2(x) &= C y_1(x) \ln(x) + \left(\sum_{n=0}^{\infty} b_n x^{n-1} \right) \end{aligned}$$

Where C above can be zero. We start by finding y_1 . Eq (2B) derived above is now used to find all a_n coefficients. The case $n = 0$ is skipped since it was used to find the roots of the indicial equation. a_0 is arbitrary and taken as $a_0 = 1$. Substituting $n = 1$ in Eq. (2B) gives

$$a_1 = 0$$

Substituting $n = 2$ in Eq. (2B) gives

$$a_2 = 0$$

For $3 \leq n$ the recursive equation is

$$a_n(n+r)(n+r-1) + a_{n-3}(n-3+r) + a_n(n+r) - a_n = 0 \quad (3)$$

Solving for a_n from recursive equation (4) gives

$$a_n = -\frac{a_{n-3}(n-3+r)}{n^2 + 2nr + r^2 - 1} \quad (4)$$

Which for the root $r = 1$ becomes

$$a_n = -\frac{a_{n-3}(n-2)}{n(n+2)} \quad (5)$$

At this point, it is a good idea to keep track of a_n in a table both before substituting $r = 1$ and after as more terms are found using the above recursive equation.

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	0	0

For $n = 3$, using the above recursive equation gives

$$a_3 = -\frac{r}{r^2 + 6r + 8}$$

Which for the root $r = 1$ becomes

$$a_3 = -\frac{1}{15}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	0	0
a_3	$-\frac{r}{r^2+6r+8}$	$-\frac{1}{15}$

For $n = 4$, using the above recursive equation gives

$$a_4 = 0$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	0	0
a_3	$-\frac{r}{r^2+6r+8}$	$-\frac{1}{15}$
a_4	0	0

For $n = 5$, using the above recursive equation gives

$$a_5 = 0$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	0	0
a_3	$-\frac{r}{r^2+6r+8}$	$-\frac{1}{15}$
a_4	0	0
a_5	0	0

Using the above table, then the solution $y_1(x)$ is

$$\begin{aligned} y_1(x) &= x(a_0 + a_1x + a_2x^2 + a_3x^3 + a_4x^4 + a_5x^5 + a_6x^6 \dots) \\ &= x\left(1 - \frac{x^3}{15} + O(x^6)\right) \end{aligned}$$

Now the second solution $y_2(x)$ is found. Let

$$r_1 - r_2 = N$$

Where N is positive integer which is the difference between the two roots. r_1 is taken as the larger root. Hence for this problem we have $N = 2$. Now we need to determine if C is zero or not. This is done by finding $\lim_{r \rightarrow r_2} a_2(r)$. If this limit exists, then $C = 0$, else we need to keep the log term and $C \neq 0$. The above table shows that

$$\begin{aligned} a_N &= a_2 \\ &= 0 \end{aligned}$$

Therefore

$$\begin{aligned}\lim_{r \rightarrow r_2} 0 &= \lim_{r \rightarrow -1} 0 \\ &= 0\end{aligned}$$

The limit is 0. Since the limit exists then the log term is not needed and we can set $C = 0$. Therefore the second solution has the form

$$\begin{aligned}y_2(x) &= \sum_{n=0}^{\infty} b_n x^{n+r} \\ &= \sum_{n=0}^{\infty} b_n x^{n-1}\end{aligned}$$

Eq (3) derived above is used to find all b_n coefficients. The case $n = 0$ is skipped since it was used to find the roots of the indicial equation. b_0 is arbitrary and taken as $b_0 = 1$. Substituting $n = 1$ in Eq(3) gives

$$b_1 = 0$$

Substituting $n = 2$ in Eq(3) gives

$$b_2 = 0$$

For $3 \leq n$ the recursive equation is

$$b_n(n+r)(n+r-1) + b_{n-3}(n-3+r) + b_n(n+r) - b_n = 0 \quad (4)$$

Which for the root $r = -1$ becomes

$$b_n(n-1)(n-2) + b_{n-3}(n-4) + b_n(n-1) - b_n = 0 \quad (4A)$$

Solving for b_n from the recursive equation (4) gives

$$b_n = -\frac{b_{n-3}(n-3+r)}{n^2 + 2nr + r^2 - 1} \quad (5)$$

Which for the root $r = -1$ becomes

$$b_n = -\frac{b_{n-3}(n-4)}{n^2 - 2n} \quad (6)$$

At this point, it is a good idea to keep track of b_n in a table both before substituting $r = -1$ and after as more terms are found using the above recursive equation.

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0
b_2	0	0

For $n = 3$, using the above recursive equation gives

$$b_3 = -\frac{r}{r^2 + 6r + 8}$$

Which for the root $r = -1$ becomes

$$b_3 = \frac{1}{3}$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0
b_2	0	0
b_3	$-\frac{r}{r^2+6r+8}$	$\frac{1}{3}$

For $n = 4$, using the above recursive equation gives

$$b_4 = 0$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0
b_2	0	0
b_3	$-\frac{r}{r^2+6r+8}$	$\frac{1}{3}$
b_4	0	0

For $n = 5$, using the above recursive equation gives

$$b_5 = 0$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0
b_2	0	0
b_3	$-\frac{r}{r^2+6r+8}$	$\frac{1}{3}$
b_4	0	0
b_5	0	0

Using the above table, then the solution $y_2(x)$ is

$$\begin{aligned} y_2(x) &= x(b_0 + b_1x + b_2x^2 + b_3x^3 + b_4x^4 + b_5x^5 + b_6x^6 \dots) \\ &= \frac{1 + \frac{x^3}{3} + O(x^6)}{x} \end{aligned}$$

Therefore the homogeneous solution is

$$\begin{aligned} y_h(x) &= c_1y_1(x) + c_2y_2(x) \\ &= c_1x \left(1 - \frac{x^3}{15} + O(x^6) \right) + \frac{c_2 \left(1 + \frac{x^3}{3} + O(x^6) \right)}{x} \end{aligned}$$

Hence the final solution is

$$\begin{aligned} y &= y_h \\ &= c_1x \left(1 - \frac{x^3}{15} + O(x^6) \right) + \frac{c_2 \left(1 + \frac{x^3}{3} + O(x^6) \right)}{x} \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1x \left(1 - \frac{x^3}{15} + O(x^6) \right) + \frac{c_2 \left(1 + \frac{x^3}{3} + O(x^6) \right)}{x} \quad (1)$$

Verification of solutions

$$y = c_1x \left(1 - \frac{x^3}{15} + O(x^6) \right) + \frac{c_2 \left(1 + \frac{x^3}{3} + O(x^6) \right)}{x}$$

Verified OK.

15.14.1 Maple step by step solution

Let's solve

$$y''x^2 + (x^4 + x)y' - y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = \frac{y}{x^2} - \frac{(x^3+1)y'}{x}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + \frac{(x^3+1)y'}{x} - \frac{y}{x^2} = 0$$

- Check to see if $x_0 = 0$ is a regular singular point

- Define functions

$$\left[P_2(x) = \frac{x^3+1}{x}, P_3(x) = -\frac{1}{x^2} \right]$$

- $x \cdot P_2(x)$ is analytic at $x = 0$

$$(x \cdot P_2(x)) \Big|_{x=0} = 1$$

- $x^2 \cdot P_3(x)$ is analytic at $x = 0$

$$(x^2 \cdot P_3(x)) \Big|_{x=0} = -1$$

- $x = 0$ is a regular singular point

Check to see if $x_0 = 0$ is a regular singular point

$$x_0 = 0$$

- Multiply by denominators

$$y''x^2 + x(x^3 + 1)y' - y = 0$$

- Assume series solution for y

$$y = \sum_{k=0}^{\infty} a_k x^{k+r}$$

- Rewrite ODE with series expansions

- Convert $x^m \cdot y'$ to series expansion for $m = 1..4$

$$x^m \cdot y' = \sum_{k=0}^{\infty} a_k (k+r) x^{k+r-1+m}$$

- Shift index using $k \rightarrow k + 1 - m$

$$x^m \cdot y' = \sum_{k=-1+m}^{\infty} a_{k+1-m}(k+1-m+r)x^{k+r}$$

- Convert $x^2 \cdot y''$ to series expansion

$$x^2 \cdot y'' = \sum_{k=0}^{\infty} a_k(k+r)(k+r-1)x^{k+r}$$

Rewrite ODE with series expansions

$$a_0(1+r)(-1+r)x^r + a_1(2+r)r x^{1+r} + a_2(3+r)(1+r)x^{2+r} + \left(\sum_{k=3}^{\infty} (a_k(k+r+1)(k+r-1) - a_{k-3}(k-3+r))x^{k+r} \right)$$

- a_0 cannot be 0 by assumption, giving the indicial equation

$$(1+r)(-1+r) = 0$$
- Values of r that satisfy the indicial equation

$$r \in \{-1, 1\}$$
- The coefficients of each power of x must be 0

$$[a_1(2+r)r = 0, a_2(3+r)(1+r) = 0]$$
- Solve for the dependent coefficient(s)

$$\{a_1 = 0, a_2 = 0\}$$
- Each term in the series must be 0, giving the recursion relation

$$a_k(k+r+1)(k+r-1) + a_{k-3}(k-3+r) = 0$$
- Shift index using $k \rightarrow k + 3$

$$a_{k+3}(k+4+r)(k+2+r) + a_k(k+r) = 0$$
- Recursion relation that defines series solution to ODE

$$a_{k+3} = -\frac{a_k(k+r)}{(k+4+r)(k+2+r)}$$
- Recursion relation for $r = -1$

$$a_{k+3} = -\frac{a_k(k-1)}{(k+3)(k+1)}$$
- Solution for $r = -1$

$$\left[y = \sum_{k=0}^{\infty} a_k x^{k-1}, a_{k+3} = -\frac{a_k(k-1)}{(k+3)(k+1)}, a_1 = 0, a_2 = 0 \right]$$
- Recursion relation for $r = 1$

$$a_{k+3} = -\frac{a_k(k+1)}{(k+5)(k+3)}$$
- Solution for $r = 1$

$$\left[y = \sum_{k=0}^{\infty} a_k x^{k+1}, a_{k+3} = -\frac{a_k(k+1)}{(k+5)(k+3)}, a_1 = 0, a_2 = 0 \right]$$

- Combine solutions and rename parameters

$$\left[y = \left(\sum_{k=0}^{\infty} a_k x^{k-1} \right) + \left(\sum_{k=0}^{\infty} b_k x^{1+k} \right), a_{k+3} = -\frac{a_k(k-1)}{(k+3)(1+k)}, a_1 = 0, a_2 = 0, b_{k+3} = -\frac{b_k(1+k)}{(k+5)(k+3)}, b_1 = \dots \right]$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
trying a symmetry of the form [xi=0, eta=F(x)]
checking if the LODE is missing y
-> Trying a Liouvillian solution using Kovacic's algorithm
<- No Liouvillian solutions exist
-> Trying a solution in terms of special functions:
  -> Bessel
  -> elliptic
  -> Legendre
  <- Kummer successful
<- special function solution successful`

```

✓ Solution by Maple

Time used: 0.031 (sec). Leaf size: 29

```

Order:=6;
dsolve(x^2*diff(y(x),x$2)+(x^4+x)*diff(y(x),x)-y(x)=0,y(x),type='series',x=0);

```

$$y(x) = c_1 x \left(1 - \frac{1}{15} x^3 + O(x^6) \right) + \frac{c_2 \left(-2 - \frac{2}{3} x^3 + O(x^6) \right)}{x}$$

✓ Solution by Mathematica

Time used: 0.007 (sec). Leaf size: 30

```
AsymptoticDSolveValue[x^2*y''[x]+(x^4+x)*y'[x]-y[x]==0,y[x],{x,0,5}]
```

$$y(x) \rightarrow c_2 \left(x - \frac{x^4}{15} \right) + c_1 \left(\frac{x^2}{3} + \frac{1}{x} \right)$$

15.15 problem 15

15.15.1 Maple step by step solution 4208

Internal problem ID [11916]

Internal file name [OUTPUT/11925_Saturday_April_13_2024_10_26_24_PM_69209561/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.2 (Frobenius). Exercises page 251

Problem number: 15.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"second order series method. Regular singular point. Difference is integer"**

Maple gives the following as the ode type

[_Lienard]

$$xy'' - (x^2 + 2)y' + yx = 0$$

With the expansion point for the power series method at $x = 0$.

The type of the expansion point is first determined. This is done on the homogeneous part of the ODE.

$$xy'' + (-x^2 - 2)y' + yx = 0$$

The following is summary of singularities for the above ode. Writing the ode as

$$y'' + p(x)y' + q(x)y = 0$$

Where

$$p(x) = -\frac{x^2 + 2}{x}$$

$$q(x) = 1$$

Table 555: Table $p(x), q(x)$ singularities.

$p(x) = -\frac{x^2+2}{x}$	
singularity	type
$x = 0$	“regular”
$x = \infty$	“regular”
$x = -\infty$	“regular”

$q(x) = 1$	
singularity	type

Combining everything together gives the following summary of singularities for the ode as

Regular singular points : $[0, \infty, -\infty]$

Irregular singular points : $[\infty]$

Since $x = 0$ is regular singular point, then Frobenius power series is used. The ode is normalized to be

$$xy'' + (-x^2 - 2)y' + yx = 0$$

Let the solution be represented as Frobenius power series of the form

$$y = \sum_{n=0}^{\infty} a_n x^{n+r}$$

Then

$$y' = \sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1}$$

$$y'' = \sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2}$$

Substituting the above back into the ode gives

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2} \right) x \\ & + (-x^2 - 2) \left(\sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1} \right) + \left(\sum_{n=0}^{\infty} a_n x^{n+r} \right) x = 0 \end{aligned} \tag{1}$$

Which simplifies to

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} x^{n+r-1} a_n (n+r) (n+r-1) \right) + \sum_{n=0}^{\infty} (-x^{1+n+r} a_n (n+r)) \\ & + \sum_{n=0}^{\infty} (-2(n+r) a_n x^{n+r-1}) + \left(\sum_{n=0}^{\infty} x^{1+n+r} a_n \right) = 0 \end{aligned} \quad (2A)$$

The next step is to make all powers of x be $n+r-1$ in each summation term. Going over each summation term above with power of x in it which is not already x^{n+r-1} and adjusting the power and the corresponding index gives

$$\begin{aligned} \sum_{n=0}^{\infty} (-x^{1+n+r} a_n (n+r)) &= \sum_{n=2}^{\infty} (-a_{n-2} (n+r-2) x^{n+r-1}) \\ \sum_{n=0}^{\infty} x^{1+n+r} a_n &= \sum_{n=2}^{\infty} a_{n-2} x^{n+r-1} \end{aligned}$$

Substituting all the above in Eq (2A) gives the following equation where now all powers of x are the same and equal to $n+r-1$.

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} x^{n+r-1} a_n (n+r) (n+r-1) \right) + \sum_{n=2}^{\infty} (-a_{n-2} (n+r-2) x^{n+r-1}) \\ & + \sum_{n=0}^{\infty} (-2(n+r) a_n x^{n+r-1}) + \left(\sum_{n=2}^{\infty} a_{n-2} x^{n+r-1} \right) = 0 \end{aligned} \quad (2B)$$

The indicial equation is obtained from $n=0$. From Eq (2B) this gives

$$x^{n+r-1} a_n (n+r) (n+r-1) - 2(n+r) a_n x^{n+r-1} = 0$$

When $n=0$ the above becomes

$$x^{-1+r} a_0 r (-1+r) - 2r a_0 x^{-1+r} = 0$$

Or

$$(x^{-1+r} r (-1+r) - 2r x^{-1+r}) a_0 = 0$$

Since $a_0 \neq 0$ then the above simplifies to

$$r x^{-1+r} (-3+r) = 0$$

Since the above is true for all x then the indicial equation becomes

$$r(-3 + r) = 0$$

Solving for r gives the roots of the indicial equation as

$$r_1 = 3$$

$$r_2 = 0$$

Since $a_0 \neq 0$ then the indicial equation becomes

$$r x^{-1+r}(-3 + r) = 0$$

Solving for r gives the roots of the indicial equation as Since $r_1 - r_2 = 3$ is an integer, then we can construct two linearly independent solutions

$$y_1(x) = x^{r_1} \left(\sum_{n=0}^{\infty} a_n x^n \right)$$

$$y_2(x) = C y_1(x) \ln(x) + x^{r_2} \left(\sum_{n=0}^{\infty} b_n x^n \right)$$

Or

$$y_1(x) = x^3 \left(\sum_{n=0}^{\infty} a_n x^n \right)$$

$$y_2(x) = C y_1(x) \ln(x) + \left(\sum_{n=0}^{\infty} b_n x^n \right)$$

Or

$$y_1(x) = \sum_{n=0}^{\infty} a_n x^{n+3}$$

$$y_2(x) = C y_1(x) \ln(x) + \left(\sum_{n=0}^{\infty} b_n x^n \right)$$

Where C above can be zero. We start by finding y_1 . Eq (2B) derived above is now used to find all a_n coefficients. The case $n = 0$ is skipped since it was used to find the roots of the indicial equation. a_0 is arbitrary and taken as $a_0 = 1$. Substituting $n = 1$ in Eq. (2B) gives

$$a_1 = 0$$

For $2 \leq n$ the recursive equation is

$$a_n(n+r)(n+r-1) - a_{n-2}(n+r-2) - 2a_n(n+r) + a_{n-2} = 0 \quad (3)$$

Solving for a_n from recursive equation (4) gives

$$a_n = \frac{a_{n-2}}{n+r} \quad (4)$$

Which for the root $r = 3$ becomes

$$a_n = \frac{a_{n-2}}{n+3} \quad (5)$$

At this point, it is a good idea to keep track of a_n in a table both before substituting $r = 3$ and after as more terms are found using the above recursive equation.

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0

For $n = 2$, using the above recursive equation gives

$$a_2 = \frac{1}{2+r}$$

Which for the root $r = 3$ becomes

$$a_2 = \frac{1}{5}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$\frac{1}{2+r}$	$\frac{1}{5}$

For $n = 3$, using the above recursive equation gives

$$a_3 = 0$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$\frac{1}{2+r}$	$\frac{1}{5}$
a_3	0	0

For $n = 4$, using the above recursive equation gives

$$a_4 = \frac{1}{(2+r)(4+r)}$$

Which for the root $r = 3$ becomes

$$a_4 = \frac{1}{35}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$\frac{1}{2+r}$	$\frac{1}{5}$
a_3	0	0
a_4	$\frac{1}{(2+r)(4+r)}$	$\frac{1}{35}$

For $n = 5$, using the above recursive equation gives

$$a_5 = 0$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$\frac{1}{2+r}$	$\frac{1}{5}$
a_3	0	0
a_4	$\frac{1}{(2+r)(4+r)}$	$\frac{1}{35}$
a_5	0	0

Using the above table, then the solution $y_1(x)$ is

$$\begin{aligned} y_1(x) &= x^3(a_0 + a_1x + a_2x^2 + a_3x^3 + a_4x^4 + a_5x^5 + a_6x^6 \dots) \\ &= x^3\left(1 + \frac{x^2}{5} + \frac{x^4}{35} + O(x^6)\right) \end{aligned}$$

Now the second solution $y_2(x)$ is found. Let

$$r_1 - r_2 = N$$

Where N is positive integer which is the difference between the two roots. r_1 is taken as the larger root. Hence for this problem we have $N = 3$. Now we need to determine if C is zero or not. This is done by finding $\lim_{r \rightarrow r_2} a_3(r)$. If this limit exists, then $C = 0$, else we need to keep the log term and $C \neq 0$. The above table shows that

$$\begin{aligned} a_N &= a_3 \\ &= 0 \end{aligned}$$

Therefore

$$\begin{aligned} \lim_{r \rightarrow r_2} 0 &= \lim_{r \rightarrow 0} 0 \\ &= 0 \end{aligned}$$

The limit is 0. Since the limit exists then the log term is not needed and we can set $C = 0$. Therefore the second solution has the form

$$\begin{aligned} y_2(x) &= \sum_{n=0}^{\infty} b_n x^{n+r} \\ &= \sum_{n=0}^{\infty} b_n x^n \end{aligned}$$

Eq (3) derived above is used to find all b_n coefficients. The case $n = 0$ is skipped since it was used to find the roots of the indicial equation. b_0 is arbitrary and taken as $b_0 = 1$. Substituting $n = 1$ in Eq(3) gives

$$b_1 = 0$$

For $2 \leq n$ the recursive equation is

$$b_n(n+r)(n+r-1) - b_{n-2}(n+r-2) - 2(n+r)b_n + b_{n-2} = 0 \quad (4)$$

Which for for the root $r = 0$ becomes

$$b_n n(n-1) - b_{n-2}(n-2) - 2nb_n + b_{n-2} = 0 \quad (4A)$$

Solving for b_n from the recursive equation (4) gives

$$b_n = \frac{b_{n-2}}{n+r} \quad (5)$$

Which for the root $r = 0$ becomes

$$b_n = \frac{b_{n-2}}{n} \quad (6)$$

At this point, it is a good idea to keep track of b_n in a table both before substituting $r = 0$ and after as more terms are found using the above recursive equation.

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0

For $n = 2$, using the above recursive equation gives

$$b_2 = \frac{1}{2+r}$$

Which for the root $r = 0$ becomes

$$b_2 = \frac{1}{2}$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0
b_2	$\frac{1}{2+r}$	$\frac{1}{2}$

For $n = 3$, using the above recursive equation gives

$$b_3 = 0$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0
b_2	$\frac{1}{2+r}$	$\frac{1}{2}$
b_3	0	0

For $n = 4$, using the above recursive equation gives

$$b_4 = \frac{1}{(2+r)(4+r)}$$

Which for the root $r = 0$ becomes

$$b_4 = \frac{1}{8}$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0
b_2	$\frac{1}{2+r}$	$\frac{1}{2}$
b_3	0	0
b_4	$\frac{1}{(2+r)(4+r)}$	$\frac{1}{8}$

For $n = 5$, using the above recursive equation gives

$$b_5 = 0$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0
b_2	$\frac{1}{2+r}$	$\frac{1}{2}$
b_3	0	0
b_4	$\frac{1}{(2+r)(4+r)}$	$\frac{1}{8}$
b_5	0	0

Using the above table, then the solution $y_2(x)$ is

$$\begin{aligned} y_2(x) &= b_0 + b_1x + b_2x^2 + b_3x^3 + b_4x^4 + b_5x^5 + b_6x^6 \dots \\ &= 1 + \frac{x^2}{2} + \frac{x^4}{8} + O(x^6) \end{aligned}$$

Therefore the homogeneous solution is

$$\begin{aligned}y_h(x) &= c_1 y_1(x) + c_2 y_2(x) \\ &= c_1 x^3 \left(1 + \frac{x^2}{5} + \frac{x^4}{35} + O(x^6) \right) + c_2 \left(1 + \frac{x^2}{2} + \frac{x^4}{8} + O(x^6) \right)\end{aligned}$$

Hence the final solution is

$$\begin{aligned}y &= y_h \\ &= c_1 x^3 \left(1 + \frac{x^2}{5} + \frac{x^4}{35} + O(x^6) \right) + c_2 \left(1 + \frac{x^2}{2} + \frac{x^4}{8} + O(x^6) \right)\end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 x^3 \left(1 + \frac{x^2}{5} + \frac{x^4}{35} + O(x^6) \right) + c_2 \left(1 + \frac{x^2}{2} + \frac{x^4}{8} + O(x^6) \right) \quad (1)$$

Verification of solutions

$$y = c_1 x^3 \left(1 + \frac{x^2}{5} + \frac{x^4}{35} + O(x^6) \right) + c_2 \left(1 + \frac{x^2}{2} + \frac{x^4}{8} + O(x^6) \right)$$

Verified OK.

15.15.1 Maple step by step solution

Let's solve

$$y''x + (-x^2 - 2)y' + yx = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = \frac{(x^2+2)y'}{x} - y$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' - \frac{(x^2+2)y'}{x} + y = 0$$

- Check to see if $x_0 = 0$ is a regular singular point

- Define functions

$$\left[P_2(x) = -\frac{x^2+2}{x}, P_3(x) = 1 \right]$$

- $x \cdot P_2(x)$ is analytic at $x = 0$

$$(x \cdot P_2(x)) \Big|_{x=0} = -2$$

- $x^2 \cdot P_3(x)$ is analytic at $x = 0$

$$(x^2 \cdot P_3(x)) \Big|_{x=0} = 0$$

- $x = 0$ is a regular singular point

Check to see if $x_0 = 0$ is a regular singular point

$$x_0 = 0$$

- Multiply by denominators

$$y''x + (-x^2 - 2)y' + yx = 0$$

- Assume series solution for y

$$y = \sum_{k=0}^{\infty} a_k x^{k+r}$$

- Rewrite ODE with series expansions

- Convert $x \cdot y$ to series expansion

$$x \cdot y = \sum_{k=0}^{\infty} a_k x^{k+r+1}$$

- Shift index using $k- > k - 1$

$$x \cdot y = \sum_{k=1}^{\infty} a_{k-1} x^{k+r}$$

- Convert $x^m \cdot y'$ to series expansion for $m = 0..2$

$$x^m \cdot y' = \sum_{k=0}^{\infty} a_k (k+r) x^{k+r-1+m}$$

- Shift index using $k- > k + 1 - m$

$$x^m \cdot y' = \sum_{k=-1+m}^{\infty} a_{k+1-m} (k+1-m+r) x^{k+r}$$

- Convert $x \cdot y''$ to series expansion

$$x \cdot y'' = \sum_{k=0}^{\infty} a_k (k+r)(k+r-1) x^{k+r-1}$$

- Shift index using $k- > k + 1$

$$x \cdot y'' = \sum_{k=-1}^{\infty} a_{k+1}(k+r+1)(k+r)x^{k+r}$$

Rewrite ODE with series expansions

$$a_0r(-3+r)x^{-1+r} + a_1(1+r)(-2+r)x^r + \left(\sum_{k=1}^{\infty} (a_{k+1}(k+r+1)(k-2+r) - a_{k-1}(k-2+r))x^{k+r} \right)$$

- a_0 cannot be 0 by assumption, giving the indicial equation

$$r(-3+r) = 0$$

- Values of r that satisfy the indicial equation

$$r \in \{0, 3\}$$

- Each term must be 0

$$a_1(1+r)(-2+r) = 0$$

- Each term in the series must be 0, giving the recursion relation

$$(k-2+r)(a_{k+1}(k+r+1) - a_{k-1}) = 0$$

- Shift index using $k- \rightarrow k+1$

$$(k+r-1)(a_{k+2}(k+2+r) - a_k) = 0$$

- Recursion relation that defines series solution to ODE

$$a_{k+2} = \frac{a_k}{k+2+r}$$

- Recursion relation for $r = 0$

$$a_{k+2} = \frac{a_k}{k+2}$$

- Solution for $r = 0$

$$\left[y = \sum_{k=0}^{\infty} a_k x^k, a_{k+2} = \frac{a_k}{k+2}, -2a_1 = 0 \right]$$

- Recursion relation for $r = 3$

$$a_{k+2} = \frac{a_k}{k+5}$$

- Solution for $r = 3$

$$\left[y = \sum_{k=0}^{\infty} a_k x^{k+3}, a_{k+2} = \frac{a_k}{k+5}, 4a_1 = 0 \right]$$

- Combine solutions and rename parameters

$$\left[y = \left(\sum_{k=0}^{\infty} a_k x^k \right) + \left(\sum_{k=0}^{\infty} b_k x^{k+3} \right), a_{k+2} = \frac{a_k}{k+2}, -2a_1 = 0, b_{k+2} = \frac{b_k}{k+5}, 4b_1 = 0 \right]$$

Maple trace Kovacic algorithm successful

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
checking if the LODE is of Euler type  
trying a symmetry of the form [xi=0, eta=F(x)]  
checking if the LODE is missing y  
-> Trying a Liouvillian solution using Kovacics algorithm  
  A Liouvillian solution exists  
  Reducible group (found an exponential solution)  
  Group is reducible, not completely reducible  
<- Kovacics algorithm successful`
```

✓ Solution by Maple

Time used: 0.032 (sec). Leaf size: 32

```
Order:=6;  
dsolve(x*diff(y(x),x$2)-(x^2+2)*diff(y(x),x)+x*y(x)=0,y(x),type='series',x=0);
```

$$y(x) = c_1 x^3 \left(1 + \frac{1}{5} x^2 + \frac{1}{35} x^4 + O(x^6) \right) + c_2 \left(12 + 6x^2 + \frac{3}{2} x^4 + O(x^6) \right)$$

✓ Solution by Mathematica

Time used: 0.009 (sec). Leaf size: 44

```
AsymptoticDSolveValue[x*y''[x]-(x^2+2)*y'[x]+x*y[x]==0,y[x],{x,0,5}]
```

$$y(x) \rightarrow c_1 \left(\frac{x^4}{8} + \frac{x^2}{2} + 1 \right) + c_2 \left(\frac{x^7}{35} + \frac{x^5}{5} + x^3 \right)$$

15.16 problem 16

15.16.1 Maple step by step solution 4222

Internal problem ID [11917]

Internal file name [OUTPUT/11926_Saturday_April_13_2024_10_26_25_PM_53530479/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.2 (Frobenius). Exercises page 251

Problem number: 16.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"second order series method. Regular singular point. Difference is integer"**

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$x^2y'' + x^2y' - 2y = 0$$

With the expansion point for the power series method at $x = 0$.

The type of the expansion point is first determined. This is done on the homogeneous part of the ODE.

$$x^2y'' + x^2y' - 2y = 0$$

The following is summary of singularities for the above ode. Writing the ode as

$$y'' + p(x)y' + q(x)y = 0$$

Where

$$p(x) = 1$$

$$q(x) = -\frac{2}{x^2}$$

Table 557: Table $p(x), q(x)$ singularities.

$p(x) = 1$	
singularity	type

$q(x) = -\frac{2}{x^2}$	
singularity	type
$x = 0$	“regular”

Combining everything together gives the following summary of singularities for the ode as

Regular singular points : $[0]$

Irregular singular points : $[\infty]$

Since $x = 0$ is regular singular point, then Frobenius power series is used. The ode is normalized to be

$$x^2 y'' + x^2 y' - 2y = 0$$

Let the solution be represented as Frobenius power series of the form

$$y = \sum_{n=0}^{\infty} a_n x^{n+r}$$

Then

$$y' = \sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1}$$

$$y'' = \sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2}$$

Substituting the above back into the ode gives

$$\left(\sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2} \right) x^2 + x^2 \left(\sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1} \right) - 2 \left(\sum_{n=0}^{\infty} a_n x^{n+r} \right) = 0 \quad (1)$$

Which simplifies to

$$\left(\sum_{n=0}^{\infty} x^{n+r} a_n (n+r)(n+r-1) \right) + \left(\sum_{n=0}^{\infty} x^{1+n+r} a_n (n+r) \right) + \sum_{n=0}^{\infty} (-2a_n x^{n+r}) = 0 \quad (2A)$$

The next step is to make all powers of x be $n + r$ in each summation term. Going over each summation term above with power of x in it which is not already x^{n+r} and adjusting the power and the corresponding index gives

$$\sum_{n=0}^{\infty} x^{1+n+r} a_n (n+r) = \sum_{n=1}^{\infty} a_{n-1} (n+r-1) x^{n+r}$$

Substituting all the above in Eq (2A) gives the following equation where now all powers of x are the same and equal to $n + r$.

$$\left(\sum_{n=0}^{\infty} x^{n+r} a_n (n+r) (n+r-1) \right) + \left(\sum_{n=1}^{\infty} a_{n-1} (n+r-1) x^{n+r} \right) + \sum_{n=0}^{\infty} (-2a_n x^{n+r}) = 0 \quad (2B)$$

The indicial equation is obtained from $n = 0$. From Eq (2B) this gives

$$x^{n+r} a_n (n+r) (n+r-1) - 2a_n x^{n+r} = 0$$

When $n = 0$ the above becomes

$$x^r a_0 r (-1+r) - 2a_0 x^r = 0$$

Or

$$(x^r r (-1+r) - 2x^r) a_0 = 0$$

Since $a_0 \neq 0$ then the above simplifies to

$$(r^2 - r - 2) x^r = 0$$

Since the above is true for all x then the indicial equation becomes

$$r^2 - r - 2 = 0$$

Solving for r gives the roots of the indicial equation as

$$r_1 = 2$$

$$r_2 = -1$$

Since $a_0 \neq 0$ then the indicial equation becomes

$$(r^2 - r - 2) x^r = 0$$

Solving for r gives the roots of the indicial equation as Since $r_1 - r_2 = 3$ is an integer, then we can construct two linearly independent solutions

$$y_1(x) = x^{r_1} \left(\sum_{n=0}^{\infty} a_n x^n \right)$$

$$y_2(x) = C y_1(x) \ln(x) + x^{r_2} \left(\sum_{n=0}^{\infty} b_n x^n \right)$$

Or

$$y_1(x) = x^2 \left(\sum_{n=0}^{\infty} a_n x^n \right)$$

$$y_2(x) = C y_1(x) \ln(x) + \frac{\sum_{n=0}^{\infty} b_n x^n}{x}$$

Or

$$y_1(x) = \sum_{n=0}^{\infty} a_n x^{n+2}$$

$$y_2(x) = C y_1(x) \ln(x) + \left(\sum_{n=0}^{\infty} b_n x^{n-1} \right)$$

Where C above can be zero. We start by finding y_1 . Eq (2B) derived above is now used to find all a_n coefficients. The case $n = 0$ is skipped since it was used to find the roots of the indicial equation. a_0 is arbitrary and taken as $a_0 = 1$. For $1 \leq n$ the recursive equation is

$$a_n(n+r)(n+r-1) + a_{n-1}(n+r-1) - 2a_n = 0 \quad (3)$$

Solving for a_n from recursive equation (4) gives

$$a_n = -\frac{a_{n-1}(n+r-1)}{n^2 + 2nr + r^2 - n - r - 2} \quad (4)$$

Which for the root $r = 2$ becomes

$$a_n = -\frac{a_{n-1}(1+n)}{n(n+3)} \quad (5)$$

At this point, it is a good idea to keep track of a_n in a table both before substituting $r = 2$ and after as more terms are found using the above recursive equation.

n	$a_{n,r}$	a_n
a_0	1	1

For $n = 1$, using the above recursive equation gives

$$a_1 = -\frac{r}{r^2 + r - 2}$$

Which for the root $r = 2$ becomes

$$a_1 = -\frac{1}{2}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$-\frac{r}{r^2+r-2}$	$-\frac{1}{2}$

For $n = 2$, using the above recursive equation gives

$$a_2 = \frac{1 + r}{r^3 + 4r^2 + r - 6}$$

Which for the root $r = 2$ becomes

$$a_2 = \frac{3}{20}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$-\frac{r}{r^2+r-2}$	$-\frac{1}{2}$
a_2	$\frac{1+r}{r^3+4r^2+r-6}$	$\frac{3}{20}$

For $n = 3$, using the above recursive equation gives

$$a_3 = -\frac{1}{r^3 + 6r^2 + 5r - 12}$$

Which for the root $r = 2$ becomes

$$a_3 = -\frac{1}{30}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$-\frac{r}{r^2+r-2}$	$-\frac{1}{2}$
a_2	$\frac{1+r}{r^3+4r^2+r-6}$	$\frac{3}{20}$
a_3	$-\frac{1}{r^3+6r^2+5r-12}$	$-\frac{1}{30}$

For $n = 4$, using the above recursive equation gives

$$a_4 = \frac{1}{r^4 + 10r^3 + 27r^2 + 2r - 40}$$

Which for the root $r = 2$ becomes

$$a_4 = \frac{1}{168}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$-\frac{r}{r^2+r-2}$	$-\frac{1}{2}$
a_2	$\frac{1+r}{r^3+4r^2+r-6}$	$\frac{3}{20}$
a_3	$-\frac{1}{r^3+6r^2+5r-12}$	$-\frac{1}{30}$
a_4	$\frac{1}{r^4+10r^3+27r^2+2r-40}$	$\frac{1}{168}$

For $n = 5$, using the above recursive equation gives

$$a_5 = -\frac{1}{(r^2 + 9r + 18)(r^3 + 6r^2 + 3r - 10)}$$

Which for the root $r = 2$ becomes

$$a_5 = -\frac{1}{1120}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$-\frac{r}{r^2+r-2}$	$-\frac{1}{2}$
a_2	$\frac{1+r}{r^3+4r^2+r-6}$	$\frac{3}{20}$
a_3	$-\frac{1}{r^3+6r^2+5r-12}$	$-\frac{1}{30}$
a_4	$\frac{1}{r^4+10r^3+27r^2+2r-40}$	$\frac{1}{168}$
a_5	$-\frac{1}{(r^2+9r+18)(r^3+6r^2+3r-10)}$	$-\frac{1}{1120}$

Using the above table, then the solution $y_1(x)$ is

$$\begin{aligned}
 y_1(x) &= x^2(a_0 + a_1x + a_2x^2 + a_3x^3 + a_4x^4 + a_5x^5 + a_6x^6 \dots) \\
 &= x^2\left(1 - \frac{x}{2} + \frac{3x^2}{20} - \frac{x^3}{30} + \frac{x^4}{168} - \frac{x^5}{1120} + O(x^6)\right)
 \end{aligned}$$

Now the second solution $y_2(x)$ is found. Let

$$r_1 - r_2 = N$$

Where N is positive integer which is the difference between the two roots. r_1 is taken as the larger root. Hence for this problem we have $N = 3$. Now we need to determine if C is zero or not. This is done by finding $\lim_{r \rightarrow r_2} a_3(r)$. If this limit exists, then $C = 0$, else we need to keep the log term and $C \neq 0$. The above table shows that

$$\begin{aligned}
 a_N &= a_3 \\
 &= -\frac{1}{r^3 + 6r^2 + 5r - 12}
 \end{aligned}$$

Therefore

$$\begin{aligned}
 \lim_{r \rightarrow r_2} -\frac{1}{r^3 + 6r^2 + 5r - 12} &= \lim_{r \rightarrow -1} -\frac{1}{r^3 + 6r^2 + 5r - 12} \\
 &= \frac{1}{12}
 \end{aligned}$$

The limit is $\frac{1}{12}$. Since the limit exists then the log term is not needed and we can set $C = 0$. Therefore the second solution has the form

$$\begin{aligned}
 y_2(x) &= \sum_{n=0}^{\infty} b_n x^{n+r} \\
 &= \sum_{n=0}^{\infty} b_n x^{n-1}
 \end{aligned}$$

Eq (3) derived above is used to find all b_n coefficients. The case $n = 0$ is skipped since it was used to find the roots of the indicial equation. b_0 is arbitrary and taken as $b_0 = 1$. For $1 \leq n$ the recursive equation is

$$b_n(n+r)(n+r-1) + b_{n-1}(n+r-1) - 2b_n = 0 \quad (4)$$

Which for the root $r = -1$ becomes

$$b_n(n-1)(n-2) + b_{n-1}(n-2) - 2b_n = 0 \quad (4A)$$

Solving for b_n from the recursive equation (4) gives

$$b_n = -\frac{b_{n-1}(n+r-1)}{n^2 + 2nr + r^2 - n - r - 2} \quad (5)$$

Which for the root $r = -1$ becomes

$$b_n = -\frac{b_{n-1}(n-2)}{n^2 - 3n} \quad (6)$$

At this point, it is a good idea to keep track of b_n in a table both before substituting $r = -1$ and after as more terms are found using the above recursive equation.

n	$b_{n,r}$	b_n
b_0	1	1

For $n = 1$, using the above recursive equation gives

$$b_1 = -\frac{r}{r^2 + r - 2}$$

Which for the root $r = -1$ becomes

$$b_1 = -\frac{1}{2}$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	$-\frac{r}{r^2+r-2}$	$-\frac{1}{2}$

For $n = 2$, using the above recursive equation gives

$$b_2 = \frac{1+r}{(r^2+r-2)(r+3)}$$

Which for the root $r = -1$ becomes

$$b_2 = 0$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	$-\frac{r}{r^2+r-2}$	$-\frac{1}{2}$
b_2	$\frac{1+r}{r^3+4r^2+r-6}$	0

For $n = 3$, using the above recursive equation gives

$$b_3 = -\frac{1}{(r+4)(r+3)(-1+r)}$$

Which for the root $r = -1$ becomes

$$b_3 = \frac{1}{12}$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	$-\frac{r}{r^2+r-2}$	$-\frac{1}{2}$
b_2	$\frac{1+r}{r^3+4r^2+r-6}$	0
b_3	$-\frac{1}{(r+4)(r+3)(-1+r)}$	$\frac{1}{12}$

For $n = 4$, using the above recursive equation gives

$$b_4 = \frac{1}{(r+4)(-1+r)(r^2+7r+10)}$$

Which for the root $r = -1$ becomes

$$b_4 = -\frac{1}{24}$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	$-\frac{r}{r^2+r-2}$	$-\frac{1}{2}$
b_2	$\frac{1+r}{r^3+4r^2+r-6}$	0
b_3	$-\frac{1}{(r+4)(r+3)(-1+r)}$	$\frac{1}{12}$
b_4	$\frac{1}{(5+r)(2+r)(r+4)(-1+r)}$	$-\frac{1}{24}$

For $n = 5$, using the above recursive equation gives

$$b_5 = -\frac{1}{(-1+r)(r^2+7r+10)(r^2+9r+18)}$$

Which for the root $r = -1$ becomes

$$b_5 = \frac{1}{80}$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	$-\frac{r}{r^2+r-2}$	$-\frac{1}{2}$
b_2	$\frac{1+r}{r^3+4r^2+r-6}$	0
b_3	$-\frac{1}{(r+4)(r+3)(-1+r)}$	$\frac{1}{12}$
b_4	$\frac{1}{(5+r)(2+r)(r+4)(-1+r)}$	$-\frac{1}{24}$
b_5	$-\frac{1}{(r+6)(r+3)(5+r)(-1+r)(2+r)}$	$\frac{1}{80}$

Using the above table, then the solution $y_2(x)$ is

$$\begin{aligned} y_2(x) &= x^2(b_0 + b_1x + b_2x^2 + b_3x^3 + b_4x^4 + b_5x^5 + b_6x^6 \dots) \\ &= \frac{1 - \frac{x}{2} + \frac{x^3}{12} - \frac{x^4}{24} + \frac{x^5}{80} + O(x^6)}{x} \end{aligned}$$

Therefore the homogeneous solution is

$$y_h(x) = c_1y_1(x) + c_2y_2(x)$$

$$= c_1x^2 \left(1 - \frac{x}{2} + \frac{3x^2}{20} - \frac{x^3}{30} + \frac{x^4}{168} - \frac{x^5}{1120} + O(x^6) \right) + \frac{c_2 \left(1 - \frac{x}{2} + \frac{x^3}{12} - \frac{x^4}{24} + \frac{x^5}{80} + O(x^6) \right)}{x}$$

Hence the final solution is

$$y = y_h$$

$$= c_1 x^2 \left(1 - \frac{x}{2} + \frac{3x^2}{20} - \frac{x^3}{30} + \frac{x^4}{168} - \frac{x^5}{1120} + O(x^6) \right) + \frac{c_2 \left(1 - \frac{x}{2} + \frac{x^3}{12} - \frac{x^4}{24} + \frac{x^5}{80} + O(x^6) \right)}{x}$$

Summary

The solution(s) found are the following

$$y = c_1 x^2 \left(1 - \frac{x}{2} + \frac{3x^2}{20} - \frac{x^3}{30} + \frac{x^4}{168} - \frac{x^5}{1120} + O(x^6) \right) + \frac{c_2 \left(1 - \frac{x}{2} + \frac{x^3}{12} - \frac{x^4}{24} + \frac{x^5}{80} + O(x^6) \right)}{x} \quad (1)$$

Verification of solutions

$$y = c_1 x^2 \left(1 - \frac{x}{2} + \frac{3x^2}{20} - \frac{x^3}{30} + \frac{x^4}{168} - \frac{x^5}{1120} + O(x^6) \right) + \frac{c_2 \left(1 - \frac{x}{2} + \frac{x^3}{12} - \frac{x^4}{24} + \frac{x^5}{80} + O(x^6) \right)}{x}$$

Verified OK.

15.16.1 Maple step by step solution

Let's solve

$$y'' x^2 + x^2 y' - 2y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = -y' + \frac{2y}{x^2}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + y' - \frac{2y}{x^2} = 0$$

- Check to see if $x_0 = 0$ is a regular singular point

- Define functions

$$\left[P_2(x) = 1, P_3(x) = -\frac{2}{x^2} \right]$$

- $x \cdot P_2(x)$ is analytic at $x = 0$

$$(x \cdot P_2(x)) \Big|_{x=0} = 0$$

- $x^2 \cdot P_3(x)$ is analytic at $x = 0$

$$(x^2 \cdot P_3(x)) \Big|_{x=0} = -2$$

- $x = 0$ is a regular singular point

Check to see if $x_0 = 0$ is a regular singular point

$$x_0 = 0$$

- Multiply by denominators

$$y''x^2 + x^2y' - 2y = 0$$

- Assume series solution for y

$$y = \sum_{k=0}^{\infty} a_k x^{k+r}$$

- Rewrite ODE with series expansions

- Convert $x^2 \cdot y'$ to series expansion

$$x^2 \cdot y' = \sum_{k=0}^{\infty} a_k (k+r) x^{k+r+1}$$

- Shift index using $k- > k-1$

$$x^2 \cdot y' = \sum_{k=1}^{\infty} a_{k-1} (k-1+r) x^{k+r}$$

- Convert $x^2 \cdot y''$ to series expansion

$$x^2 \cdot y'' = \sum_{k=0}^{\infty} a_k (k+r)(k-1+r) x^{k+r}$$

Rewrite ODE with series expansions

$$a_0(1+r)(-2+r)x^r + \left(\sum_{k=1}^{\infty} (a_k(k+r+1)(k+r-2) + a_{k-1}(k-1+r)) x^{k+r} \right) = 0$$

- a_0 cannot be 0 by assumption, giving the indicial equation

$$(1+r)(-2+r) = 0$$

- Values of r that satisfy the indicial equation

$$r \in \{-1, 2\}$$

- Each term in the series must be 0, giving the recursion relation

$$a_k(k+r+1)(k+r-2) + a_{k-1}(k-1+r) = 0$$

- Shift index using $k \rightarrow k + 1$

$$a_{k+1}(k + 2 + r)(k - 1 + r) + a_k(k + r) = 0$$
- Recursion relation that defines series solution to ODE

$$a_{k+1} = -\frac{a_k(k+r)}{(k+2+r)(k-1+r)}$$
- Recursion relation for $r = -1$; series terminates at $k = 1$

$$a_{k+1} = -\frac{a_k(k-1)}{(k+1)(k-2)}$$
- Apply recursion relation for $k = 0$

$$a_1 = -\frac{a_0}{2}$$
- Terminating series solution of the ODE for $r = -1$. Use reduction of order to find the second

$$y = a_0 \cdot \left(-\frac{x}{2} + 1\right)$$
- Recursion relation for $r = 2$

$$a_{k+1} = -\frac{a_k(k+2)}{(k+4)(k+1)}$$
- Solution for $r = 2$

$$\left[y = \sum_{k=0}^{\infty} a_k x^{k+2}, a_{k+1} = -\frac{a_k(k+2)}{(k+4)(k+1)} \right]$$
- Combine solutions and rename parameters

$$\left[y = a_0 \cdot \left(-\frac{x}{2} + 1\right) + \left(\sum_{k=0}^{\infty} b_k x^{k+2} \right), b_{1+k} = -\frac{b_k(k+2)}{(k+4)(1+k)} \right]$$

Maple trace Kovacic algorithm successful

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
trying a symmetry of the form [xi=0, eta=F(x)]
checking if the LODE is missing y
-> Trying a Liouvillian solution using Kovacics algorithm
    A Liouvillian solution exists
    Reducible group (found an exponential solution)
    Reducible group (found another exponential solution)
<- Kovacics algorithm successful`

```

✓ Solution by Maple

Time used: 0.031 (sec). Leaf size: 45

Order:=6;

```
dsolve(x^2*diff(y(x),x$2)+x^2*diff(y(x),x)-2*y(x)=0,y(x),type='series',x=0);
```

$$y(x) = c_1 x^2 \left(1 - \frac{1}{2}x + \frac{3}{20}x^2 - \frac{1}{30}x^3 + \frac{1}{168}x^4 - \frac{1}{1120}x^5 + O(x^6) \right) + \frac{c_2 (12 - 6x + x^3 - \frac{1}{2}x^4 + \frac{3}{20}x^5 + O(x^6))}{x}$$

✓ Solution by Mathematica

Time used: 0.019 (sec). Leaf size: 63

```
AsymptoticDSolveValue[x^2*y''[x]+x^2*y'[x]-2*y[x]==0,y[x],{x,0,5}]
```

$$y(x) \rightarrow c_1 \left(-\frac{x^3}{24} + \frac{x^2}{12} + \frac{1}{x} - \frac{1}{2} \right) + c_2 \left(\frac{x^6}{168} - \frac{x^5}{30} + \frac{3x^4}{20} - \frac{x^3}{2} + x^2 \right)$$

15.17 problem 17

15.17.1 Maple step by step solution 4236

Internal problem ID [11918]

Internal file name [OUTPUT/11927_Saturday_April_13_2024_10_26_26_PM_76951881/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.2 (Frobenius). Exercises page 251

Problem number: 17.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"second order series method. Regular singular point. Difference is integer"**

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$(2x^2 - x)y'' + (2x - 2)y' + (-2x^2 + 3x - 2)y = 0$$

With the expansion point for the power series method at $x = 0$.

The type of the expansion point is first determined. This is done on the homogeneous part of the ODE.

$$(2x^2 - x)y'' + (2x - 2)y' + (-2x^2 + 3x - 2)y = 0$$

The following is summary of singularities for the above ode. Writing the ode as

$$y'' + p(x)y' + q(x)y = 0$$

Where

$$p(x) = \frac{2x - 2}{x(2x - 1)}$$
$$q(x) = -\frac{2x^2 - 3x + 2}{x(2x - 1)}$$

Table 559: Table $p(x), q(x)$ singularities.

$p(x) = \frac{2x-2}{x(2x-1)}$		$q(x) = -\frac{2x^2-3x+2}{x(2x-1)}$	
singularity	type	singularity	type
$x = 0$	“regular”	$x = 0$	“regular”
$x = \frac{1}{2}$	“regular”	$x = \frac{1}{2}$	“regular”

Combining everything together gives the following summary of singularities for the ode as

Regular singular points : $[0, \frac{1}{2}]$

Irregular singular points : $[\infty]$

Since $x = 0$ is regular singular point, then Frobenius power series is used. The ode is normalized to be

$$y''x(2x-1) + (2x-2)y' + (-2x^2 + 3x - 2)y = 0$$

Let the solution be represented as Frobenius power series of the form

$$y = \sum_{n=0}^{\infty} a_n x^{n+r}$$

Then

$$y' = \sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1}$$

$$y'' = \sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2}$$

Substituting the above back into the ode gives

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2} \right) x(2x-1) \\ & + (2x-2) \left(\sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1} \right) + (-2x^2 + 3x - 2) \left(\sum_{n=0}^{\infty} a_n x^{n+r} \right) = 0 \end{aligned} \quad (1)$$

Which simplifies to

$$\begin{aligned}
& \left(\sum_{n=0}^{\infty} 2x^{n+r} a_n (n+r) (n+r-1) \right) + \sum_{n=0}^{\infty} (-x^{n+r-1} a_n (n+r) (n+r-1)) \\
& + \left(\sum_{n=0}^{\infty} 2x^{n+r} a_n (n+r) \right) + \sum_{n=0}^{\infty} (-2(n+r) a_n x^{n+r-1}) \\
& + \sum_{n=0}^{\infty} (-2x^{n+r+2} a_n) + \left(\sum_{n=0}^{\infty} 3x^{1+n+r} a_n \right) + \sum_{n=0}^{\infty} (-2a_n x^{n+r}) = 0
\end{aligned} \tag{2A}$$

The next step is to make all powers of x be $n+r-1$ in each summation term. Going over each summation term above with power of x in it which is not already x^{n+r-1} and adjusting the power and the corresponding index gives

$$\begin{aligned}
\sum_{n=0}^{\infty} 2x^{n+r} a_n (n+r) (n+r-1) &= \sum_{n=1}^{\infty} 2a_{n-1} (n+r-1) (n+r-2) x^{n+r-1} \\
\sum_{n=0}^{\infty} 2x^{n+r} a_n (n+r) &= \sum_{n=1}^{\infty} 2a_{n-1} (n+r-1) x^{n+r-1} \\
\sum_{n=0}^{\infty} (-2x^{n+r+2} a_n) &= \sum_{n=3}^{\infty} (-2a_{n-3} x^{n+r-1}) \\
\sum_{n=0}^{\infty} 3x^{1+n+r} a_n &= \sum_{n=2}^{\infty} 3a_{n-2} x^{n+r-1} \\
\sum_{n=0}^{\infty} (-2a_n x^{n+r}) &= \sum_{n=1}^{\infty} (-2a_{n-1} x^{n+r-1})
\end{aligned}$$

Substituting all the above in Eq (2A) gives the following equation where now all powers

of x are the same and equal to $n + r - 1$.

$$\begin{aligned}
& \left(\sum_{n=1}^{\infty} 2a_{n-1}(n+r-1)(n+r-2)x^{n+r-1} \right) \\
& + \sum_{n=0}^{\infty} (-x^{n+r-1}a_n(n+r)(n+r-1)) + \left(\sum_{n=1}^{\infty} 2a_{n-1}(n+r-1)x^{n+r-1} \right) \quad (2B) \\
& + \sum_{n=0}^{\infty} (-2(n+r)a_nx^{n+r-1}) + \sum_{n=3}^{\infty} (-2a_{n-3}x^{n+r-1}) \\
& + \left(\sum_{n=2}^{\infty} 3a_{n-2}x^{n+r-1} \right) + \sum_{n=1}^{\infty} (-2a_{n-1}x^{n+r-1}) = 0
\end{aligned}$$

The indicial equation is obtained from $n = 0$. From Eq (2B) this gives

$$-x^{n+r-1}a_n(n+r)(n+r-1) - 2(n+r)a_nx^{n+r-1} = 0$$

When $n = 0$ the above becomes

$$-x^{-1+r}a_0r(-1+r) - 2ra_0x^{-1+r} = 0$$

Or

$$(-x^{-1+r}r(-1+r) - 2rx^{-1+r})a_0 = 0$$

Since $a_0 \neq 0$ then the above simplifies to

$$rx^{-1+r}(-1-r) = 0$$

Since the above is true for all x then the indicial equation becomes

$$-r(1+r) = 0$$

Solving for r gives the roots of the indicial equation as

$$r_1 = 0$$

$$r_2 = -1$$

Since $a_0 \neq 0$ then the indicial equation becomes

$$rx^{-1+r}(-1-r) = 0$$

Solving for r gives the roots of the indicial equation as Since $r_1 - r_2 = 1$ is an integer, then we can construct two linearly independent solutions

$$y_1(x) = x^{r_1} \left(\sum_{n=0}^{\infty} a_n x^n \right)$$

$$y_2(x) = C y_1(x) \ln(x) + x^{r_2} \left(\sum_{n=0}^{\infty} b_n x^n \right)$$

Or

$$y_1(x) = \sum_{n=0}^{\infty} a_n x^n$$

$$y_2(x) = C y_1(x) \ln(x) + \frac{\sum_{n=0}^{\infty} b_n x^n}{x}$$

Or

$$y_1(x) = \sum_{n=0}^{\infty} a_n x^n$$

$$y_2(x) = C y_1(x) \ln(x) + \left(\sum_{n=0}^{\infty} b_n x^{n-1} \right)$$

Where C above can be zero. We start by finding y_1 . Eq (2B) derived above is now used to find all a_n coefficients. The case $n = 0$ is skipped since it was used to find the roots of the indicial equation. a_0 is arbitrary and taken as $a_0 = 1$. Substituting $n = 1$ in Eq. (2B) gives

$$a_1 = \frac{-2 + 2r}{r + 2}$$

Substituting $n = 2$ in Eq. (2B) gives

$$a_2 = \frac{4r^2 - 4r + 3}{r^2 + 5r + 6}$$

For $3 \leq n$ the recursive equation is

$$2a_{n-1}(n+r-1)(n+r-2) - a_n(n+r)(n+r-1) + 2a_{n-1}(n+r-1) - 2a_n(n+r) - 2a_{n-3} + 3a_{n-2} - 2a_{n-1} = 0 \quad (3)$$

Solving for a_n from recursive equation (4) gives

$$a_n = \frac{2n^2 a_{n-1} + 4nra_{n-1} + 2r^2 a_{n-1} - 4na_{n-1} - 4ra_{n-1} - 2a_{n-3} + 3a_{n-2}}{n^2 + 2nr + r^2 + n + r} \quad (4)$$

Which for the root $r = 0$ becomes

$$a_n = \frac{2n^2 a_{n-1} - 4n a_{n-1} - 2a_{n-3} + 3a_{n-2}}{n(1+n)} \quad (5)$$

At this point, it is a good idea to keep track of a_n in a table both before substituting $r = 0$ and after as more terms are found using the above recursive equation.

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$\frac{-2+2r}{r+2}$	-1
a_2	$\frac{4r^2-4r+3}{r^2+5r+6}$	$\frac{1}{2}$

For $n = 3$, using the above recursive equation gives

$$a_3 = \frac{8r^3 + 2r - 4}{(r+4)(r+3)(r+2)}$$

Which for the root $r = 0$ becomes

$$a_3 = -\frac{1}{6}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$\frac{-2+2r}{r+2}$	-1
a_2	$\frac{4r^2-4r+3}{r^2+5r+6}$	$\frac{1}{2}$
a_3	$\frac{8r^3+2r-4}{(r+4)(r+3)(r+2)}$	$-\frac{1}{6}$

For $n = 4$, using the above recursive equation gives

$$a_4 = \frac{16r^4 + 32r^3 + 12r^2 - 20r + 5}{(r^2 + 5r + 6)(r^2 + 9r + 20)}$$

Which for the root $r = 0$ becomes

$$a_4 = \frac{1}{24}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$\frac{-2+2r}{r+2}$	-1
a_2	$\frac{4r^2-4r+3}{r^2+5r+6}$	$\frac{1}{2}$
a_3	$\frac{8r^3+2r-4}{(r+4)(r+3)(r+2)}$	$-\frac{1}{6}$
a_4	$\frac{16r^4+32r^3+12r^2-20r+5}{(r^2+5r+6)(r^2+9r+20)}$	$\frac{1}{24}$

For $n = 5$, using the above recursive equation gives

$$a_5 = \frac{32r^5 + 160r^4 + 232r^3 + 8r^2 - 78r - 6}{(r+6)(r+5)(r+4)(r+3)(r+2)}$$

Which for the root $r = 0$ becomes

$$a_5 = -\frac{1}{120}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$\frac{-2+2r}{r+2}$	-1
a_2	$\frac{4r^2-4r+3}{r^2+5r+6}$	$\frac{1}{2}$
a_3	$\frac{8r^3+2r-4}{(r+4)(r+3)(r+2)}$	$-\frac{1}{6}$
a_4	$\frac{16r^4+32r^3+12r^2-20r+5}{(r^2+5r+6)(r^2+9r+20)}$	$\frac{1}{24}$
a_5	$\frac{32r^5+160r^4+232r^3+8r^2-78r-6}{(r+6)(r+5)(r+4)(r+3)(r+2)}$	$-\frac{1}{120}$

Using the above table, then the solution $y_1(x)$ is

$$\begin{aligned} y_1(x) &= a_0 + a_1x + a_2x^2 + a_3x^3 + a_4x^4 + a_5x^5 + a_6x^6 \dots \\ &= 1 - x + \frac{x^2}{2} - \frac{x^3}{6} + \frac{x^4}{24} - \frac{x^5}{120} + O(x^6) \end{aligned}$$

Now the second solution $y_2(x)$ is found. Let

$$r_1 - r_2 = N$$

Where N is positive integer which is the difference between the two roots. r_1 is taken as the larger root. Hence for this problem we have $N = 1$. Now we need to determine if C is zero or not. This is done by finding $\lim_{r \rightarrow r_2} a_1(r)$. If this limit exists, then $C = 0$, else we need to keep the log term and $C \neq 0$. The above table shows that

$$\begin{aligned} a_N &= a_1 \\ &= \frac{-2 + 2r}{r + 2} \end{aligned}$$

Therefore

$$\begin{aligned} \lim_{r \rightarrow r_2} \frac{-2 + 2r}{r + 2} &= \lim_{r \rightarrow -1} \frac{-2 + 2r}{r + 2} \\ &= -4 \end{aligned}$$

The limit is -4 . Since the limit exists then the log term is not needed and we can set $C = 0$. Therefore the second solution has the form

$$\begin{aligned} y_2(x) &= \sum_{n=0}^{\infty} b_n x^{n+r} \\ &= \sum_{n=0}^{\infty} b_n x^{n-1} \end{aligned}$$

Eq (3) derived above is used to find all b_n coefficients. The case $n = 0$ is skipped since it was used to find the roots of the indicial equation. b_0 is arbitrary and taken as $b_0 = 1$. Substituting $n = 1$ in Eq(3) gives

$$b_1 = \frac{-2 + 2r}{r + 2}$$

Substituting $n = 2$ in Eq(3) gives

$$b_2 = \frac{4r^2 - 4r + 3}{r^2 + 5r + 6}$$

For $3 \leq n$ the recursive equation is

$$\begin{aligned} 2b_{n-1}(n+r-1)(n+r-2) - b_n(n+r)(n+r-1) \\ + 2b_{n-1}(n+r-1) - 2(n+r)b_n - 2b_{n-3} + 3b_{n-2} - 2b_{n-1} = 0 \end{aligned} \quad (4)$$

Which for for the root $r = -1$ becomes

$$\begin{aligned} 2b_{n-1}(n-2)(n-3) - b_n(n-1)(n-2) + 2b_{n-1}(n-2) \\ - 2(n-1)b_n - 2b_{n-3} + 3b_{n-2} - 2b_{n-1} = 0 \end{aligned} \quad (4A)$$

Solving for b_n from the recursive equation (4) gives

$$b_n = \frac{2n^2b_{n-1} + 4nr b_{n-1} + 2r^2b_{n-1} - 4nb_{n-1} - 4rb_{n-1} - 2b_{n-3} + 3b_{n-2}}{n^2 + 2nr + r^2 + n + r} \quad (5)$$

Which for the root $r = -1$ becomes

$$b_n = \frac{2n^2b_{n-1} - 8nb_{n-1} - 2b_{n-3} + 3b_{n-2} + 6b_{n-1}}{n^2 - n} \quad (6)$$

At this point, it is a good idea to keep track of b_n in a table both before substituting $r = -1$ and after as more terms are found using the above recursive equation.

n	$b_{n,r}$	b_n
b_0	1	1
b_1	$\frac{-2+2r}{r+2}$	-4
b_2	$\frac{4r^2-4r+3}{r^2+5r+6}$	$\frac{11}{2}$

For $n = 3$, using the above recursive equation gives

$$b_3 = \frac{8r^3 + 2r - 4}{(r^2 + 7r + 12)(r + 2)}$$

Which for the root $r = -1$ becomes

$$b_3 = -\frac{7}{3}$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	$\frac{-2+2r}{r+2}$	-4
b_2	$\frac{4r^2-4r+3}{r^2+5r+6}$	$\frac{11}{2}$
b_3	$\frac{8r^3+2r-4}{(r+4)(r+3)(r+2)}$	$-\frac{7}{3}$

For $n = 4$, using the above recursive equation gives

$$b_4 = \frac{16r^4 + 32r^3 + 12r^2 - 20r + 5}{(r + 3)(r + 2)(r^2 + 9r + 20)}$$

Which for the root $r = -1$ becomes

$$b_4 = \frac{7}{8}$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	$\frac{-2+2r}{r+2}$	-4
b_2	$\frac{4r^2-4r+3}{r^2+5r+6}$	$\frac{11}{2}$
b_3	$\frac{8r^3+2r-4}{(r+4)(r+3)(r+2)}$	$-\frac{7}{3}$
b_4	$\frac{16r^4+32r^3+12r^2-20r+5}{(r+5)(r+4)(r+3)(r+2)}$	$\frac{7}{8}$

For $n = 5$, using the above recursive equation gives

$$b_5 = \frac{32r^5 + 160r^4 + 232r^3 + 8r^2 - 78r - 6}{(r^2 + 7r + 12)(r + 2)(r^2 + 11r + 30)}$$

Which for the root $r = -1$ becomes

$$b_5 = -\frac{1}{5}$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	$\frac{-2+2r}{r+2}$	-4
b_2	$\frac{4r^2-4r+3}{r^2+5r+6}$	$\frac{11}{2}$
b_3	$\frac{8r^3+2r-4}{(r+4)(r+3)(r+2)}$	$-\frac{7}{3}$
b_4	$\frac{16r^4+32r^3+12r^2-20r+5}{(r+5)(r+4)(r+3)(r+2)}$	$\frac{7}{8}$
b_5	$\frac{32r^5+160r^4+232r^3+8r^2-78r-6}{(r+6)(r+5)(r+4)(r+3)(r+2)}$	$-\frac{1}{5}$

Using the above table, then the solution $y_2(x)$ is

$$\begin{aligned} y_2(x) &= 1(b_0 + b_1x + b_2x^2 + b_3x^3 + b_4x^4 + b_5x^5 + b_6x^6 \dots) \\ &= \frac{1 - 4x + \frac{11x^2}{2} - \frac{7x^3}{3} + \frac{7x^4}{8} - \frac{x^5}{5} + O(x^6)}{x} \end{aligned}$$

Therefore the homogeneous solution is

$$y_h(x) = c_1 y_1(x) + c_2 y_2(x)$$

$$= c_1 \left(1 - x + \frac{x^2}{2} - \frac{x^3}{6} + \frac{x^4}{24} - \frac{x^5}{120} + O(x^6) \right) + \frac{c_2 \left(1 - 4x + \frac{11x^2}{2} - \frac{7x^3}{3} + \frac{7x^4}{8} - \frac{x^5}{5} + O(x^6) \right)}{x}$$

Hence the final solution is

$$y = y_h$$

$$= c_1 \left(1 - x + \frac{x^2}{2} - \frac{x^3}{6} + \frac{x^4}{24} - \frac{x^5}{120} + O(x^6) \right) + \frac{c_2 \left(1 - 4x + \frac{11x^2}{2} - \frac{7x^3}{3} + \frac{7x^4}{8} - \frac{x^5}{5} + O(x^6) \right)}{x}$$

Summary

The solution(s) found are the following

$$y = c_1 \left(1 - x + \frac{x^2}{2} - \frac{x^3}{6} + \frac{x^4}{24} - \frac{x^5}{120} + O(x^6) \right) + \frac{c_2 \left(1 - 4x + \frac{11x^2}{2} - \frac{7x^3}{3} + \frac{7x^4}{8} - \frac{x^5}{5} + O(x^6) \right)}{x} \quad (1)$$

Verification of solutions

$$y = c_1 \left(1 - x + \frac{x^2}{2} - \frac{x^3}{6} + \frac{x^4}{24} - \frac{x^5}{120} + O(x^6) \right) + \frac{c_2 \left(1 - 4x + \frac{11x^2}{2} - \frac{7x^3}{3} + \frac{7x^4}{8} - \frac{x^5}{5} + O(x^6) \right)}{x}$$

Verified OK.

15.17.1 Maple step by step solution

Let's solve

$$y''x(2x - 1) + (2x - 2)y' + (-2x^2 + 3x - 2)y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = \frac{(2x^2 - 3x + 2)y}{x(2x - 1)} - \frac{2(x - 1)y'}{x(2x - 1)}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + \frac{2(x-1)y'}{x(2x-1)} - \frac{(2x^2-3x+2)y}{x(2x-1)} = 0$$

- Check to see if x_0 is a regular singular point

- Define functions

$$\left[P_2(x) = \frac{2(x-1)}{x(2x-1)}, P_3(x) = -\frac{2x^2-3x+2}{x(2x-1)} \right]$$

- $x \cdot P_2(x)$ is analytic at $x = 0$

$$(x \cdot P_2(x)) \Big|_{x=0} = 2$$

- $x^2 \cdot P_3(x)$ is analytic at $x = 0$

$$(x^2 \cdot P_3(x)) \Big|_{x=0} = 0$$

- $x = 0$ is a regular singular point

Check to see if x_0 is a regular singular point

$$x_0 = 0$$

- Multiply by denominators

$$y''x(2x-1) + (2x-2)y' + (-2x^2+3x-2)y = 0$$

- Assume series solution for y

$$y = \sum_{k=0}^{\infty} a_k x^{k+r}$$

- Rewrite ODE with series expansions

- Convert $x^m \cdot y$ to series expansion for $m = 0..2$

$$x^m \cdot y = \sum_{k=0}^{\infty} a_k x^{k+r+m}$$

- Shift index using $k \rightarrow k - m$

$$x^m \cdot y = \sum_{k=m}^{\infty} a_{k-m} x^{k+r}$$

- Convert $x^m \cdot y'$ to series expansion for $m = 0..1$

$$x^m \cdot y' = \sum_{k=0}^{\infty} a_k (k+r) x^{k+r-1+m}$$

- Shift index using $k \rightarrow k + 1 - m$

$$x^m \cdot y' = \sum_{k=-1+m}^{\infty} a_{k+1-m} (k+1-m+r) x^{k+r}$$

- Convert $x^m \cdot y''$ to series expansion for $m = 1..2$

$$x^m \cdot y'' = \sum_{k=0}^{\infty} a_k(k+r)(k+r-1)x^{k+r-2+m}$$

- Shift index using $k \rightarrow k+2-m$

$$x^m \cdot y'' = \sum_{k=-2+m}^{\infty} a_{k+2-m}(k+2-m+r)(k+1-m+r)x^{k+r}$$

Rewrite ODE with series expansions

$$-a_0r(1+r)x^{-1+r} + (-a_1(1+r)(2+r) + 2a_0(1+r)(-1+r))x^r + (-a_2(2+r)(3+r) + 2a_1(2+r)r + 3a_0) = 0$$

- a_0 cannot be 0 by assumption, giving the indicial equation

$$-r(1+r) = 0$$

- Values of r that satisfy the indicial equation

$$r \in \{-1, 0\}$$

- The coefficients of each power of x must be 0

$$[-a_1(1+r)(2+r) + 2a_0(1+r)(-1+r) = 0, -a_2(2+r)(3+r) + 2a_1(2+r)r + 3a_0 = 0]$$

- Solve for the dependent coefficient(s)

$$\left\{ a_1 = \frac{2a_0(-1+r)}{2+r}, a_2 = \frac{a_0(4r^2-4r+3)}{r^2+5r+6} \right\}$$

- Each term in the series must be 0, giving the recursion relation

$$-a_{k+1}(k+r+1)(k+2+r) + 2k^2a_k + 4kra_k + 2r^2a_k - 2a_k - 2a_{k-2} + 3a_{k-1} = 0$$

- Shift index using $k \rightarrow k+2$

$$-a_{k+3}(k+3+r)(k+4+r) + 2(k+2)^2a_{k+2} + 4(k+2)ra_{k+2} + 2r^2a_{k+2} - 2a_{k+2} - 2a_k + 3a_{k+1} = 0$$

- Recursion relation that defines series solution to ODE

$$a_{k+3} = \frac{2k^2a_{k+2} + 4kra_{k+2} + 2r^2a_{k+2} + 8ka_{k+2} + 8ra_{k+2} - 2a_k + 3a_{k+1} + 6a_{k+2}}{(k+3+r)(k+4+r)}$$

- Recursion relation for $r = -1$

$$a_{k+3} = \frac{2k^2a_{k+2} + 4ka_{k+2} - 2a_k + 3a_{k+1}}{(k+2)(k+3)}$$

- Solution for $r = -1$

$$\left[y = \sum_{k=0}^{\infty} a_k x^{k-1}, a_{k+3} = \frac{2k^2a_{k+2} + 4ka_{k+2} - 2a_k + 3a_{k+1}}{(k+2)(k+3)}, a_1 = -4a_0, a_2 = \frac{11a_0}{2} \right]$$

- Recursion relation for $r = 0$

$$a_{k+3} = \frac{2k^2a_{k+2} + 8ka_{k+2} - 2a_k + 3a_{k+1} + 6a_{k+2}}{(k+3)(k+4)}$$

- Solution for $r = 0$

$$\left[y = \sum_{k=0}^{\infty} a_k x^k, a_{k+3} = \frac{2k^2 a_{k+2} + 8k a_{k+2} - 2a_k + 3a_{k+1} + 6a_{k+2}}{(k+3)(k+4)}, a_1 = -a_0, a_2 = \frac{a_0}{2} \right]$$

- Combine solutions and rename parameters

$$\left[y = \left(\sum_{k=0}^{\infty} a_k x^{k-1} \right) + \left(\sum_{k=0}^{\infty} b_k x^k \right), a_{k+3} = \frac{2k^2 a_{k+2} + 4k a_{k+2} - 2a_k + 3a_{k+1}}{(k+2)(k+3)}, a_1 = -4a_0, a_2 = \frac{11a_0}{2}, b_{k+3} = \right]$$

Maple trace Kovacic algorithm successful

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
trying a symmetry of the form [xi=0, eta=F(x)]
checking if the LODE is missing y
-> Trying a Liouvillian solution using Kovacics algorithm
    A Liouvillian solution exists
    Reducible group (found an exponential solution)
    Reducible group (found another exponential solution)
<- Kovacics algorithm successful`

```

✓ Solution by Maple

Time used: 0.047 (sec). Leaf size: 44

```

Order:=6;
dsolve((2*x^2-x)*diff(y(x),x$2)+(2*x-2)*diff(y(x),x)+(-2*x^2+3*x-2)*y(x)=0,y(x),type='series

```

$$y(x) = c_1 \left(1 - x + \frac{1}{2}x^2 - \frac{1}{6}x^3 + \frac{1}{24}x^4 - \frac{1}{120}x^5 + O(x^6) \right) + \frac{c_2 \left(1 - 2x + \frac{7}{2}x^2 - \frac{4}{3}x^3 + \frac{13}{24}x^4 - \frac{7}{60}x^5 + O(x^6) \right)}{x}$$

✓ Solution by Mathematica

Time used: 0.033 (sec). Leaf size: 60

```
AsymptoticDSolveValue[(2*x^2-x)*y'[x]+(2*x-2)*y'[x]+(-2*x^2+3*x-2)*y[x]==0,y[x],{x,0,5}]
```

$$y(x) \rightarrow c_1 \left(\frac{7x^3}{8} - \frac{7x^2}{3} + \frac{11x}{2} + \frac{1}{x} - 4 \right) + c_2 \left(\frac{x^4}{24} - \frac{x^3}{6} + \frac{x^2}{2} - x + 1 \right)$$

15.18 problem 18

15.18.1 Maple step by step solution 4250

Internal problem ID [11919]

Internal file name [OUTPUT/11928_Saturday_April_13_2024_10_26_27_PM_76458216/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.2 (Frobenius). Exercises page 251

Problem number: 18.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"second order series method. Regular singular point. Difference is integer"**

Maple gives the following as the ode type

```
[[_Emden, _Fowler], [_2nd_order, _linear, `_with_symmetry_[0,F(x)]`]]
```

$$x^2y'' - y'x + \frac{3y}{4} = 0$$

With the expansion point for the power series method at $x = 0$.

The ode can be written as

$$4x^2y'' - 4y'x + 3y = 0$$

Which shows it is a Euler ODE. The type of the expansion point is first determined. This is done on the homogeneous part of the ODE.

$$4x^2y'' - 4y'x + 3y = 0$$

The following is summary of singularities for the above ode. Writing the ode as

$$y'' + p(x)y' + q(x)y = 0$$

Where

$$p(x) = -\frac{1}{x}$$

$$q(x) = \frac{3}{4x^2}$$

Table 561: Table $p(x), q(x)$ singularities.

$p(x) = -\frac{1}{x}$	
singularity	type
$x = 0$	“regular”

$q(x) = \frac{3}{4x^2}$	
singularity	type
$x = 0$	“regular”

Combining everything together gives the following summary of singularities for the ode as

Regular singular points : $[0, \infty]$

Irregular singular points : $[\]$

Since $x = 0$ is regular singular point, then Frobenius power series is used. The ode is normalized to be

$$4x^2y'' - 4y'x + 3y = 0$$

Let the solution be represented as Frobenius power series of the form

$$y = \sum_{n=0}^{\infty} a_n x^{n+r}$$

Then

$$y' = \sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1}$$

$$y'' = \sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2}$$

Substituting the above back into the ode gives

$$4 \left(\sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2} \right) x^2 - 4 \left(\sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1} \right) x + 3 \left(\sum_{n=0}^{\infty} a_n x^{n+r} \right) = 0 \quad (1)$$

Which simplifies to

$$\left(\sum_{n=0}^{\infty} 4x^{n+r} a_n (n+r)(n+r-1) \right) + \sum_{n=0}^{\infty} (-4x^{n+r} a_n (n+r)) + \left(\sum_{n=0}^{\infty} 3a_n x^{n+r} \right) = 0 \quad (2A)$$

The next step is to make all powers of x be $n+r$ in each summation term. Going over each summation term above with power of x in it which is not already x^{n+r} and adjusting the power and the corresponding index gives Substituting all the above in Eq (2A) gives the following equation where now all powers of x are the same and equal to $n+r$.

$$\left(\sum_{n=0}^{\infty} 4x^{n+r} a_n (n+r)(n+r-1) \right) + \sum_{n=0}^{\infty} (-4x^{n+r} a_n (n+r)) + \left(\sum_{n=0}^{\infty} 3a_n x^{n+r} \right) = 0 \quad (2B)$$

The indicial equation is obtained from $n=0$. From Eq (2B) this gives

$$4x^{n+r} a_n (n+r)(n+r-1) - 4x^{n+r} a_n (n+r) + 3a_n x^{n+r} = 0$$

When $n=0$ the above becomes

$$4x^r a_0 r(-1+r) - 4x^r a_0 r + 3a_0 x^r = 0$$

Or

$$(4x^r r(-1+r) - 4x^r r + 3x^r) a_0 = 0$$

Since $a_0 \neq 0$ then the above simplifies to

$$(4r^2 - 8r + 3) x^r = 0$$

Since the above is true for all x then the indicial equation becomes

$$4r^2 - 8r + 3 = 0$$

Solving for r gives the roots of the indicial equation as

$$r_1 = \frac{3}{2}$$

$$r_2 = \frac{1}{2}$$

Since $a_0 \neq 0$ then the indicial equation becomes

$$(4r^2 - 8r + 3) x^r = 0$$

Solving for r gives the roots of the indicial equation as Since $r_1 - r_2 = 1$ is an integer, then we can construct two linearly independent solutions

$$y_1(x) = x^{r_1} \left(\sum_{n=0}^{\infty} a_n x^n \right)$$

$$y_2(x) = C y_1(x) \ln(x) + x^{r_2} \left(\sum_{n=0}^{\infty} b_n x^n \right)$$

Or

$$y_1(x) = x^{\frac{3}{2}} \left(\sum_{n=0}^{\infty} a_n x^n \right)$$

$$y_2(x) = C y_1(x) \ln(x) + \sqrt{x} \left(\sum_{n=0}^{\infty} b_n x^n \right)$$

Or

$$y_1(x) = \sum_{n=0}^{\infty} a_n x^{n+\frac{3}{2}}$$

$$y_2(x) = C y_1(x) \ln(x) + \left(\sum_{n=0}^{\infty} b_n x^{n+\frac{1}{2}} \right)$$

Where C above can be zero. We start by finding y_1 . Eq (2B) derived above is now used to find all a_n coefficients. The case $n = 0$ is skipped since it was used to find the roots of the indicial equation. a_0 is arbitrary and taken as $a_0 = 1$. For $0 \leq n$ the recursive equation is

$$4a_n(n+r)(n+r-1) - 4a_n(n+r) + 3a_n = 0 \quad (3)$$

Solving for a_n from recursive equation (4) gives

$$a_n = 0 \quad (4)$$

Which for the root $r = \frac{3}{2}$ becomes

$$a_n = 0 \tag{5}$$

At this point, it is a good idea to keep track of a_n in a table both before substituting $r = \frac{3}{2}$ and after as more terms are found using the above recursive equation.

n	$a_{n,r}$	a_n
a_0	1	1

For $n = 1$, using the above recursive equation gives

$$a_1 = 0$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0

For $n = 2$, using the above recursive equation gives

$$a_2 = 0$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	0	0

For $n = 3$, using the above recursive equation gives

$$a_3 = 0$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	0	0
a_3	0	0

For $n = 4$, using the above recursive equation gives

$$a_4 = 0$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	0	0
a_3	0	0
a_4	0	0

For $n = 5$, using the above recursive equation gives

$$a_5 = 0$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	0	0
a_3	0	0
a_4	0	0
a_5	0	0

Using the above table, then the solution $y_1(x)$ is

$$\begin{aligned} y_1(x) &= x^{\frac{3}{2}}(a_0 + a_1x + a_2x^2 + a_3x^3 + a_4x^4 + a_5x^5 + a_6x^6 \dots) \\ &= x^{\frac{3}{2}}(1 + O(x^6)) \end{aligned}$$

Now the second solution $y_2(x)$ is found. Let

$$r_1 - r_2 = N$$

Where N is positive integer which is the difference between the two roots. r_1 is taken as the larger root. Hence for this problem we have $N = 1$. Now we need to determine if

C is zero or not. This is done by finding $\lim_{r \rightarrow r_2} a_1(r)$. If this limit exists, then $C = 0$, else we need to keep the log term and $C \neq 0$. The above table shows that

$$\begin{aligned} a_N &= a_1 \\ &= 0 \end{aligned}$$

Therefore

$$\begin{aligned} \lim_{r \rightarrow r_2} 0 &= \lim_{r \rightarrow \frac{1}{2}} 0 \\ &= 0 \end{aligned}$$

The limit is 0. Since the limit exists then the log term is not needed and we can set $C = 0$. Therefore the second solution has the form

$$\begin{aligned} y_2(x) &= \sum_{n=0}^{\infty} b_n x^{n+r} \\ &= \sum_{n=0}^{\infty} b_n x^{n+\frac{1}{2}} \end{aligned}$$

Eq (3) derived above is used to find all b_n coefficients. The case $n = 0$ is skipped since it was used to find the roots of the indicial equation. b_0 is arbitrary and taken as $b_0 = 1$. For $0 \leq n$ the recursive equation is

$$4b_n(n+r)(n+r-1) - 4b_n(n+r) + 3b_n = 0 \quad (4)$$

Which for the root $r = \frac{1}{2}$ becomes

$$4b_n \left(n + \frac{1}{2} \right) \left(n - \frac{1}{2} \right) - 4b_n \left(n + \frac{1}{2} \right) + 3b_n = 0 \quad (4A)$$

Solving for b_n from the recursive equation (4) gives

$$b_n = 0 \quad (5)$$

Which for the root $r = \frac{1}{2}$ becomes

$$b_n = 0 \quad (6)$$

At this point, it is a good idea to keep track of b_n in a table both before substituting $r = \frac{1}{2}$ and after as more terms are found using the above recursive equation.

n	$b_{n,r}$	b_n
b_0	1	1

For $n = 1$, using the above recursive equation gives

$$b_1 = 0$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0

For $n = 2$, using the above recursive equation gives

$$b_2 = 0$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0
b_2	0	0

For $n = 3$, using the above recursive equation gives

$$b_3 = 0$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0
b_2	0	0
b_3	0	0

For $n = 4$, using the above recursive equation gives

$$b_4 = 0$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0
b_2	0	0
b_3	0	0
b_4	0	0

For $n = 5$, using the above recursive equation gives

$$b_5 = 0$$

And the table now becomes

n	$b_{n,r}$	b_n
b_0	1	1
b_1	0	0
b_2	0	0
b_3	0	0
b_4	0	0
b_5	0	0

Using the above table, then the solution $y_2(x)$ is

$$\begin{aligned} y_2(x) &= x^{\frac{3}{2}}(b_0 + b_1x + b_2x^2 + b_3x^3 + b_4x^4 + b_5x^5 + b_6x^6 \dots) \\ &= \sqrt{x}(1 + O(x^6)) \end{aligned}$$

Therefore the homogeneous solution is

$$\begin{aligned} y_h(x) &= c_1y_1(x) + c_2y_2(x) \\ &= c_1x^{\frac{3}{2}}(1 + O(x^6)) + c_2\sqrt{x}(1 + O(x^6)) \end{aligned}$$

Hence the final solution is

$$\begin{aligned} y &= y_h \\ &= c_1x^{\frac{3}{2}}(1 + O(x^6)) + c_2\sqrt{x}(1 + O(x^6)) \end{aligned}$$

Summary

The solution(s) found are the following

$$y = c_1 x^{\frac{3}{2}} (1 + O(x^6)) + c_2 \sqrt{x} (1 + O(x^6)) \quad (1)$$

Verification of solutions

$$y = c_1 x^{\frac{3}{2}} (1 + O(x^6)) + c_2 \sqrt{x} (1 + O(x^6))$$

Verified OK.

15.18.1 Maple step by step solution

Let's solve

$$4y''x^2 - 4y'x + 3y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = \frac{y'}{x} - \frac{3y}{4x^2}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' - \frac{y'}{x} + \frac{3y}{4x^2} = 0$$

- Multiply by denominators of the ODE

$$4y''x^2 - 4y'x + 3y = 0$$

- Make a change of variables

$$t = \ln(x)$$

- Substitute the change of variables back into the ODE

- Calculate the 1st derivative of y with respect to x , using the chain rule

$$y' = \left(\frac{d}{dt}y(t)\right) t'(x)$$

- Compute derivative

$$y' = \frac{\frac{d}{dt}y(t)}{x}$$

- Calculate the 2nd derivative of y with respect to x , using the chain rule

$$y'' = \left(\frac{d^2}{dt^2}y(t)\right) t'(x)^2 + t''(x) \left(\frac{d}{dt}y(t)\right)$$

- Compute derivative

$$y'' = \frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2}$$

Substitute the change of variables back into the ODE

$$4\left(\frac{\frac{d^2}{dt^2}y(t)}{x^2} - \frac{\frac{d}{dt}y(t)}{x^2}\right)x^2 - 4\frac{d}{dt}y(t) + 3y(t) = 0$$

- Simplify

$$4\frac{d^2}{dt^2}y(t) - 8\frac{d}{dt}y(t) + 3y(t) = 0$$

- Isolate 2nd derivative

$$\frac{d^2}{dt^2}y(t) = 2\frac{d}{dt}y(t) - \frac{3y(t)}{4}$$

- Group terms with $y(t)$ on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$\frac{d^2}{dt^2}y(t) - 2\frac{d}{dt}y(t) + \frac{3y(t)}{4} = 0$$

- Characteristic polynomial of ODE

$$r^2 - 2r + \frac{3}{4} = 0$$

- Factor the characteristic polynomial

$$\frac{(2r-1)(2r-3)}{4} = 0$$

- Roots of the characteristic polynomial

$$r = \left(\frac{1}{2}, \frac{3}{2}\right)$$

- 1st solution of the ODE

$$y_1(t) = e^{\frac{t}{2}}$$

- 2nd solution of the ODE

$$y_2(t) = e^{\frac{3t}{2}}$$

- General solution of the ODE

$$y(t) = c_1y_1(t) + c_2y_2(t)$$

- Substitute in solutions

$$y(t) = c_1e^{\frac{t}{2}} + c_2e^{\frac{3t}{2}}$$

- Change variables back using $t = \ln(x)$

$$y = c_1\sqrt{x} + c_2x^{\frac{3}{2}}$$

- Simplify

$$y = \sqrt{x}(c_2x + c_1)$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
checking if the LODE is of Euler type  
<- LODE of Euler type successful`
```

✓ Solution by Maple

Time used: 0.032 (sec). Leaf size: 27

```
Order:=6;  
dsolve(x^2*diff(y(x),x$2)-x*diff(y(x),x)+3/4*y(x)=0,y(x),type='series',x=0);
```

$$y(x) = \sqrt{x} (c_1 x + c_2) + O(x^6)$$

✓ Solution by Mathematica

Time used: 0.004 (sec). Leaf size: 20

```
AsymptoticDSolveValue[x^2*y'[x]-x*y'[x]+3/4*y[x]==0,y[x],{x,0,5}]
```

$$y(x) \rightarrow c_2 x^{3/2} + c_1 \sqrt{x}$$

15.19 problem 19

15.19.1 Maple step by step solution 4265

Internal problem ID [11920]

Internal file name [OUTPUT/11929_Saturday_April_13_2024_10_26_28_PM_82600808/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.2 (Frobenius). Exercises page 251

Problem number: 19.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"second order series method. Regular singular point. Difference is integer"**

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$x^2y'' + y'x + y(x - 1) = 0$$

With the expansion point for the power series method at $x = 0$.

The type of the expansion point is first determined. This is done on the homogeneous part of the ODE.

$$x^2y'' + y'x + y(x - 1) = 0$$

The following is summary of singularities for the above ode. Writing the ode as

$$y'' + p(x)y' + q(x)y = 0$$

Where

$$p(x) = \frac{1}{x}$$
$$q(x) = \frac{x - 1}{x^2}$$

Table 563: Table $p(x), q(x)$ singularities.

$p(x) = \frac{1}{x}$	
singularity	type
$x = 0$	“regular”

$q(x) = \frac{x-1}{x^2}$	
singularity	type
$x = 0$	“regular”

Combining everything together gives the following summary of singularities for the ode as

Regular singular points : $[0]$

Irregular singular points : $[\infty]$

Since $x = 0$ is regular singular point, then Frobenius power series is used. The ode is normalized to be

$$x^2 y'' + y'x + y(x - 1) = 0$$

Let the solution be represented as Frobenius power series of the form

$$y = \sum_{n=0}^{\infty} a_n x^{n+r}$$

Then

$$y' = \sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1}$$

$$y'' = \sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2}$$

Substituting the above back into the ode gives

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2} \right) x^2 \\ & + \left(\sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1} \right) x + \left(\sum_{n=0}^{\infty} a_n x^{n+r} \right) (x-1) = 0 \end{aligned} \tag{1}$$

Which simplifies to

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} x^{n+r} a_n (n+r) (n+r-1) \right) + \left(\sum_{n=0}^{\infty} x^{n+r} a_n (n+r) \right) \\ & + \left(\sum_{n=0}^{\infty} x^{1+n+r} a_n \right) + \sum_{n=0}^{\infty} (-a_n x^{n+r}) = 0 \end{aligned} \quad (2A)$$

The next step is to make all powers of x be $n+r$ in each summation term. Going over each summation term above with power of x in it which is not already x^{n+r} and adjusting the power and the corresponding index gives

$$\sum_{n=0}^{\infty} x^{1+n+r} a_n = \sum_{n=1}^{\infty} a_{n-1} x^{n+r}$$

Substituting all the above in Eq (2A) gives the following equation where now all powers of x are the same and equal to $n+r$.

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} x^{n+r} a_n (n+r) (n+r-1) \right) + \left(\sum_{n=0}^{\infty} x^{n+r} a_n (n+r) \right) \\ & + \left(\sum_{n=1}^{\infty} a_{n-1} x^{n+r} \right) + \sum_{n=0}^{\infty} (-a_n x^{n+r}) = 0 \end{aligned} \quad (2B)$$

The indicial equation is obtained from $n=0$. From Eq (2B) this gives

$$x^{n+r} a_n (n+r) (n+r-1) + x^{n+r} a_n (n+r) - a_n x^{n+r} = 0$$

When $n=0$ the above becomes

$$x^r a_0 r(-1+r) + x^r a_0 r - a_0 x^r = 0$$

Or

$$(x^r r(-1+r) + x^r r - x^r) a_0 = 0$$

Since $a_0 \neq 0$ then the above simplifies to

$$(r^2 - 1) x^r = 0$$

Since the above is true for all x then the indicial equation becomes

$$r^2 - 1 = 0$$

Solving for r gives the roots of the indicial equation as

$$\begin{aligned} r_1 &= 1 \\ r_2 &= -1 \end{aligned}$$

Since $a_0 \neq 0$ then the indicial equation becomes

$$(r^2 - 1) x^r = 0$$

Solving for r gives the roots of the indicial equation as Since $r_1 - r_2 = 2$ is an integer, then we can construct two linearly independent solutions

$$\begin{aligned} y_1(x) &= x^{r_1} \left(\sum_{n=0}^{\infty} a_n x^n \right) \\ y_2(x) &= C y_1(x) \ln(x) + x^{r_2} \left(\sum_{n=0}^{\infty} b_n x^n \right) \end{aligned}$$

Or

$$\begin{aligned} y_1(x) &= x \left(\sum_{n=0}^{\infty} a_n x^n \right) \\ y_2(x) &= C y_1(x) \ln(x) + \frac{\sum_{n=0}^{\infty} b_n x^n}{x} \end{aligned}$$

Or

$$\begin{aligned} y_1(x) &= \sum_{n=0}^{\infty} a_n x^{1+n} \\ y_2(x) &= C y_1(x) \ln(x) + \left(\sum_{n=0}^{\infty} b_n x^{n-1} \right) \end{aligned}$$

Where C above can be zero. We start by finding y_1 . Eq (2B) derived above is now used to find all a_n coefficients. The case $n = 0$ is skipped since it was used to find the roots of the indicial equation. a_0 is arbitrary and taken as $a_0 = 1$. For $1 \leq n$ the recursive equation is

$$a_n(n+r)(n+r-1) + a_n(n+r) + a_{n-1} - a_n = 0 \quad (3)$$

Solving for a_n from recursive equation (4) gives

$$a_n = -\frac{a_{n-1}}{n^2 + 2nr + r^2 - 1} \quad (4)$$

Which for the root $r = 1$ becomes

$$a_n = -\frac{a_{n-1}}{n(n+2)} \quad (5)$$

At this point, it is a good idea to keep track of a_n in a table both before substituting $r = 1$ and after as more terms are found using the above recursive equation.

n	$a_{n,r}$	a_n
a_0	1	1

For $n = 1$, using the above recursive equation gives

$$a_1 = -\frac{1}{r(r+2)}$$

Which for the root $r = 1$ becomes

$$a_1 = -\frac{1}{3}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$-\frac{1}{r(r+2)}$	$-\frac{1}{3}$

For $n = 2$, using the above recursive equation gives

$$a_2 = \frac{1}{r(r+2)(r+3)(r+1)}$$

Which for the root $r = 1$ becomes

$$a_2 = \frac{1}{24}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$-\frac{1}{r(r+2)}$	$-\frac{1}{3}$
a_2	$\frac{1}{r(r+2)(r+3)(r+1)}$	$\frac{1}{24}$

For $n = 3$, using the above recursive equation gives

$$a_3 = -\frac{1}{r(r+2)^2(r+3)(r+1)(r+4)}$$

Which for the root $r = 1$ becomes

$$a_3 = -\frac{1}{360}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$-\frac{1}{r(r+2)}$	$-\frac{1}{3}$
a_2	$\frac{1}{r(r+2)(r+3)(r+1)}$	$\frac{1}{24}$
a_3	$-\frac{1}{r(r+2)^2(r+3)(r+1)(r+4)}$	$-\frac{1}{360}$

For $n = 4$, using the above recursive equation gives

$$a_4 = \frac{1}{r(r+2)^2(r+3)^2(r+1)(r+4)(r+5)}$$

Which for the root $r = 1$ becomes

$$a_4 = \frac{1}{8640}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$-\frac{1}{r(r+2)}$	$-\frac{1}{3}$
a_2	$\frac{1}{r(r+2)(r+3)(r+1)}$	$\frac{1}{24}$
a_3	$-\frac{1}{r(r+2)^2(r+3)(r+1)(r+4)}$	$-\frac{1}{360}$
a_4	$\frac{1}{r(r+2)^2(r+3)^2(r+1)(r+4)(r+5)}$	$\frac{1}{8640}$

For $n = 5$, using the above recursive equation gives

$$a_5 = -\frac{1}{r(r+2)^2(r+3)^2(r+1)(r+4)^2(r+5)(r+6)}$$

Which for the root $r = 1$ becomes

$$a_5 = -\frac{1}{302400}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$-\frac{1}{r(r+2)}$	$-\frac{1}{3}$
a_2	$\frac{1}{r(r+2)(r+3)(r+1)}$	$\frac{1}{24}$
a_3	$-\frac{1}{r(r+2)^2(r+3)(r+1)(r+4)}$	$-\frac{1}{360}$
a_4	$\frac{1}{r(r+2)^2(r+3)^2(r+1)(r+4)(r+5)}$	$\frac{1}{8640}$
a_5	$-\frac{1}{r(r+2)^2(r+3)^2(r+1)(r+4)^2(r+5)(r+6)}$	$-\frac{1}{302400}$

Using the above table, then the solution $y_1(x)$ is

$$\begin{aligned} y_1(x) &= x(a_0 + a_1x + a_2x^2 + a_3x^3 + a_4x^4 + a_5x^5 + a_6x^6 \dots) \\ &= x\left(1 - \frac{x}{3} + \frac{x^2}{24} - \frac{x^3}{360} + \frac{x^4}{8640} - \frac{x^5}{302400} + O(x^6)\right) \end{aligned}$$

Now the second solution $y_2(x)$ is found. Let

$$r_1 - r_2 = N$$

Where N is positive integer which is the difference between the two roots. r_1 is taken as the larger root. Hence for this problem we have $N = 2$. Now we need to determine if C is zero or not. This is done by finding $\lim_{r \rightarrow r_2} a_2(r)$. If this limit exists, then $C = 0$, else we need to keep the log term and $C \neq 0$. The above table shows that

$$\begin{aligned} a_N &= a_2 \\ &= \frac{1}{r(r+2)(r+3)(r+1)} \end{aligned}$$

Therefore

$$\begin{aligned} \lim_{r \rightarrow r_2} \frac{1}{r(r+2)(r+3)(r+1)} &= \lim_{r \rightarrow -1} \frac{1}{r(r+2)(r+3)(r+1)} \\ &= \text{undefined} \end{aligned}$$

Since the limit does not exist then the log term is needed. Therefore the second solution has the form

$$y_2(x) = Cy_1(x) \ln(x) + \left(\sum_{n=0}^{\infty} b_n x^{n+r_2} \right)$$

Therefore

$$\begin{aligned} \frac{d}{dx} y_2(x) &= Cy_1'(x) \ln(x) + \frac{Cy_1(x)}{x} + \left(\sum_{n=0}^{\infty} \frac{b_n x^{n+r_2} (n+r_2)}{x} \right) \\ &= Cy_1'(x) \ln(x) + \frac{Cy_1(x)}{x} + \left(\sum_{n=0}^{\infty} x^{-1+n+r_2} b_n (n+r_2) \right) \\ \frac{d^2}{dx^2} y_2(x) &= Cy_1''(x) \ln(x) + \frac{2Cy_1'(x)}{x} - \frac{Cy_1(x)}{x^2} \\ &\quad + \sum_{n=0}^{\infty} \left(\frac{b_n x^{n+r_2} (n+r_2)^2}{x^2} - \frac{b_n x^{n+r_2} (n+r_2)}{x^2} \right) \\ &= Cy_1''(x) \ln(x) + \frac{2Cy_1'(x)}{x} - \frac{Cy_1(x)}{x^2} + \left(\sum_{n=0}^{\infty} x^{-2+n+r_2} b_n (n+r_2) (-1+n+r_2) \right) \end{aligned}$$

Substituting these back into the given ode $x^2 y'' + y'x + y(x-1) = 0$ gives

$$\begin{aligned} &\left(Cy_1''(x) \ln(x) + \frac{2Cy_1'(x)}{x} - \frac{Cy_1(x)}{x^2} \right. \\ &\quad \left. + \sum_{n=0}^{\infty} \left(\frac{b_n x^{n+r_2} (n+r_2)^2}{x^2} - \frac{b_n x^{n+r_2} (n+r_2)}{x^2} \right) \right) x^2 \\ &\quad + \left(Cy_1'(x) \ln(x) + \frac{Cy_1(x)}{x} + \left(\sum_{n=0}^{\infty} \frac{b_n x^{n+r_2} (n+r_2)}{x} \right) \right) x \\ &\quad + \left(Cy_1(x) \ln(x) + \left(\sum_{n=0}^{\infty} b_n x^{n+r_2} \right) \right) (x-1) = 0 \end{aligned}$$

Which can be written as

$$\begin{aligned} & \left((y_1''(x)x^2 + y_1'(x)x + y_1(x)(x-1)) \ln(x) + \left(\frac{2y_1'(x)}{x} - \frac{y_1(x)}{x^2} \right) x^2 + y_1(x) \right) C \\ & + \left(\sum_{n=0}^{\infty} \left(\frac{b_n x^{n+r_2}(n+r_2)^2}{x^2} - \frac{b_n x^{n+r_2}(n+r_2)}{x^2} \right) \right) x^2 \\ & + \left(\sum_{n=0}^{\infty} \frac{b_n x^{n+r_2}(n+r_2)}{x} \right) x + \left(\sum_{n=0}^{\infty} b_n x^{n+r_2} \right) (x-1) = 0 \end{aligned} \quad (7)$$

But since $y_1(x)$ is a solution to the ode, then

$$y_1''(x)x^2 + y_1'(x)x + y_1(x)(x-1) = 0$$

Eq (7) simplifies to

$$\begin{aligned} & \left(\left(\frac{2y_1'(x)}{x} - \frac{y_1(x)}{x^2} \right) x^2 + y_1(x) \right) C \\ & + \left(\sum_{n=0}^{\infty} \left(\frac{b_n x^{n+r_2}(n+r_2)^2}{x^2} - \frac{b_n x^{n+r_2}(n+r_2)}{x^2} \right) \right) x^2 \\ & + \left(\sum_{n=0}^{\infty} \frac{b_n x^{n+r_2}(n+r_2)}{x} \right) x + \left(\sum_{n=0}^{\infty} b_n x^{n+r_2} \right) (x-1) = 0 \end{aligned} \quad (8)$$

Substituting $y_1 = \sum_{n=0}^{\infty} a_n x^{n+r_1}$ into the above gives

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} x^{-2+n+r_2} b_n (n+r_2) (-1+n+r_2) \right) x^2 + 2x \left(\sum_{n=0}^{\infty} x^{-1+n+r_1} a_n (n+r_1) \right) C \\ & + \left(\sum_{n=0}^{\infty} x^{-1+n+r_2} b_n (n+r_2) \right) x + \left(\sum_{n=0}^{\infty} b_n x^{n+r_2} \right) (x-1) = 0 \end{aligned} \quad (9)$$

Since $r_1 = 1$ and $r_2 = -1$ then the above becomes

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} x^{-3+n} b_n (n-1) (-2+n) \right) x^2 + 2x \left(\sum_{n=0}^{\infty} x^n a_n (1+n) \right) C \\ & + \left(\sum_{n=0}^{\infty} x^{-2+n} b_n (n-1) \right) x + \left(\sum_{n=0}^{\infty} b_n x^{n-1} \right) (x-1) = 0 \end{aligned} \quad (10)$$

Which simplifies to

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} x^{n-1} b_n (n^2 - 3n + 2) \right) + \left(\sum_{n=0}^{\infty} 2C x^{1+n} a_n (1 + n) \right) \\ & + \left(\sum_{n=0}^{\infty} x^{n-1} b_n (n - 1) \right) + \left(\sum_{n=0}^{\infty} b_n x^n \right) + \sum_{n=0}^{\infty} (-b_n x^{n-1}) = 0 \end{aligned} \quad (2A)$$

The next step is to make all powers of x be $n - 1$ in each summation term. Going over each summation term above with power of x in it which is not already x^{n-1} and adjusting the power and the corresponding index gives

$$\begin{aligned} \sum_{n=0}^{\infty} 2C x^{1+n} a_n (1 + n) &= \sum_{n=2}^{\infty} 2C a_{-2+n} (n - 1) x^{n-1} \\ \sum_{n=0}^{\infty} b_n x^n &= \sum_{n=1}^{\infty} b_{n-1} x^{n-1} \end{aligned}$$

Substituting all the above in Eq (2A) gives the following equation where now all powers of x are the same and equal to $n - 1$.

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} x^{n-1} b_n (n^2 - 3n + 2) \right) + \left(\sum_{n=2}^{\infty} 2C a_{-2+n} (n - 1) x^{n-1} \right) \\ & + \left(\sum_{n=0}^{\infty} x^{n-1} b_n (n - 1) \right) + \left(\sum_{n=1}^{\infty} b_{n-1} x^{n-1} \right) + \sum_{n=0}^{\infty} (-b_n x^{n-1}) = 0 \end{aligned} \quad (2B)$$

For $n = 0$ in Eq. (2B), we choose arbitrary value for b_0 as $b_0 = 1$. For $n = 1$, Eq (2B) gives

$$b_0 - b_1 = 0$$

Which when replacing the above values found already for b_n and the values found earlier for a_n and for C , gives

$$1 - b_1 = 0$$

Solving the above for b_1 gives

$$b_1 = 1$$

For $n = N$, where $N = 2$ which is the difference between the two roots, we are free to choose $b_2 = 0$. Hence for $n = 2$, Eq (2B) gives

$$2C + 1 = 0$$

Which is solved for C . Solving for C gives

$$C = -\frac{1}{2}$$

For $n = 3$, Eq (2B) gives

$$4Ca_1 + b_2 + 3b_3 = 0$$

Which when replacing the above values found already for b_n and the values found earlier for a_n and for C , gives

$$3b_3 + \frac{2}{3} = 0$$

Solving the above for b_3 gives

$$b_3 = -\frac{2}{9}$$

For $n = 4$, Eq (2B) gives

$$6Ca_2 + b_3 + 8b_4 = 0$$

Which when replacing the above values found already for b_n and the values found earlier for a_n and for C , gives

$$8b_4 - \frac{25}{72} = 0$$

Solving the above for b_4 gives

$$b_4 = \frac{25}{576}$$

For $n = 5$, Eq (2B) gives

$$8Ca_3 + b_4 + 15b_5 = 0$$

Which when replacing the above values found already for b_n and the values found earlier for a_n and for C , gives

$$15b_5 + \frac{157}{2880} = 0$$

Solving the above for b_5 gives

$$b_5 = -\frac{157}{43200}$$

Now that we found all b_n and C , we can calculate the second solution from

$$y_2(x) = Cy_1(x) \ln(x) + \left(\sum_{n=0}^{\infty} b_n x^{n+r_2} \right)$$

Using the above value found for $C = -\frac{1}{2}$ and all b_n , then the second solution becomes

$$y_2(x) = -\frac{1}{2} \left(x \left(1 - \frac{x}{3} + \frac{x^2}{24} - \frac{x^3}{360} + \frac{x^4}{8640} - \frac{x^5}{302400} + O(x^6) \right) \right) \ln(x) \\ + \frac{1 + x - \frac{2x^3}{9} + \frac{25x^4}{576} - \frac{157x^5}{43200} + O(x^6)}{x}$$

Therefore the homogeneous solution is

$$\begin{aligned}
 y_h(x) &= c_1 y_1(x) + c_2 y_2(x) \\
 &= c_1 x \left(1 - \frac{x}{3} + \frac{x^2}{24} - \frac{x^3}{360} + \frac{x^4}{8640} - \frac{x^5}{302400} + O(x^6) \right) \\
 &\quad + c_2 \left(-\frac{1}{2} \left(x \left(1 - \frac{x}{3} + \frac{x^2}{24} - \frac{x^3}{360} + \frac{x^4}{8640} - \frac{x^5}{302400} + O(x^6) \right) \right) \ln(x) \right. \\
 &\quad \left. + \frac{1 + x - \frac{2x^3}{9} + \frac{25x^4}{576} - \frac{157x^5}{43200} + O(x^6)}{x} \right)
 \end{aligned}$$

Hence the final solution is

$$\begin{aligned}
 y &= y_h \\
 &= c_1 x \left(1 - \frac{x}{3} + \frac{x^2}{24} - \frac{x^3}{360} + \frac{x^4}{8640} - \frac{x^5}{302400} + O(x^6) \right) \\
 &\quad + c_2 \left(-\frac{x \left(1 - \frac{x}{3} + \frac{x^2}{24} - \frac{x^3}{360} + \frac{x^4}{8640} - \frac{x^5}{302400} + O(x^6) \right) \ln(x)}{2} \right. \\
 &\quad \left. + \frac{1 + x - \frac{2x^3}{9} + \frac{25x^4}{576} - \frac{157x^5}{43200} + O(x^6)}{x} \right)
 \end{aligned}$$

Summary

The solution(s) found are the following

$$\begin{aligned}
 y &= c_1 x \left(1 - \frac{x}{3} + \frac{x^2}{24} - \frac{x^3}{360} + \frac{x^4}{8640} - \frac{x^5}{302400} + O(x^6) \right) \\
 &\quad + c_2 \left(-\frac{x \left(1 - \frac{x}{3} + \frac{x^2}{24} - \frac{x^3}{360} + \frac{x^4}{8640} - \frac{x^5}{302400} + O(x^6) \right) \ln(x)}{2} \right. \\
 &\quad \left. + \frac{1 + x - \frac{2x^3}{9} + \frac{25x^4}{576} - \frac{157x^5}{43200} + O(x^6)}{x} \right) \tag{1}
 \end{aligned}$$

Verification of solutions

$$y = c_1 x \left(1 - \frac{x}{3} + \frac{x^2}{24} - \frac{x^3}{360} + \frac{x^4}{8640} - \frac{x^5}{302400} + O(x^6) \right) \\ + c_2 \left(-\frac{x \left(1 - \frac{x}{3} + \frac{x^2}{24} - \frac{x^3}{360} + \frac{x^4}{8640} - \frac{x^5}{302400} + O(x^6) \right) \ln(x)}{2} \right. \\ \left. + \frac{1 + x - \frac{2x^3}{9} + \frac{25x^4}{576} - \frac{157x^5}{43200} + O(x^6)}{x} \right)$$

Verified OK.

15.19.1 Maple step by step solution

Let's solve

$$y''x^2 + y'x + y(x-1) = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = -\frac{y'}{x} - \frac{(x-1)y}{x^2}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + \frac{y'}{x} + \frac{(x-1)y}{x^2} = 0$$

- Check to see if $x_0 = 0$ is a regular singular point

- Define functions

$$[P_2(x) = \frac{1}{x}, P_3(x) = \frac{x-1}{x^2}]$$

- $x \cdot P_2(x)$ is analytic at $x = 0$

$$(x \cdot P_2(x)) \Big|_{x=0} = 1$$

- $x^2 \cdot P_3(x)$ is analytic at $x = 0$

$$(x^2 \cdot P_3(x)) \Big|_{x=0} = -1$$

- $x = 0$ is a regular singular point

Check to see if $x_0 = 0$ is a regular singular point

$$x_0 = 0$$

- Multiply by denominators

$$y''x^2 + y'x + y(x - 1) = 0$$

- Assume series solution for y

$$y = \sum_{k=0}^{\infty} a_k x^{k+r}$$

- Rewrite ODE with series expansions

- Convert $x^m \cdot y$ to series expansion for $m = 0..1$

$$x^m \cdot y = \sum_{k=0}^{\infty} a_k x^{k+r+m}$$

- Shift index using $k \rightarrow k - m$

$$x^m \cdot y = \sum_{k=m}^{\infty} a_{k-m} x^{k+r}$$

- Convert $x \cdot y'$ to series expansion

$$x \cdot y' = \sum_{k=0}^{\infty} a_k (k+r) x^{k+r}$$

- Convert $x^2 \cdot y''$ to series expansion

$$x^2 \cdot y'' = \sum_{k=0}^{\infty} a_k (k+r)(k+r-1) x^{k+r}$$

Rewrite ODE with series expansions

$$a_0(1+r)(-1+r)x^r + \left(\sum_{k=1}^{\infty} (a_k(k+r+1)(k+r-1) + a_{k-1}) x^{k+r} \right) = 0$$

- a_0 cannot be 0 by assumption, giving the indicial equation

$$(1+r)(-1+r) = 0$$

- Values of r that satisfy the indicial equation

$$r \in \{-1, 1\}$$

- Each term in the series must be 0, giving the recursion relation

$$a_k(k+r+1)(k+r-1) + a_{k-1} = 0$$

- Shift index using $k \rightarrow k + 1$

$$a_{k+1}(k+2+r)(k+r) + a_k = 0$$

- Recursion relation that defines series solution to ODE

$$a_{k+1} = -\frac{a_k}{(k+2+r)(k+r)}$$

- Recursion relation for $r = -1$

$$a_{k+1} = -\frac{a_k}{(k+1)(k-1)}$$

- Series not valid for $r = -1$, division by 0 in the recursion relation at $k = 1$

$$a_{k+1} = -\frac{a_k}{(k+1)(k-1)}$$

- Recursion relation for $r = 1$

$$a_{k+1} = -\frac{a_k}{(k+3)(k+1)}$$

- Solution for $r = 1$

$$\left[y = \sum_{k=0}^{\infty} a_k x^{k+1}, a_{k+1} = -\frac{a_k}{(k+3)(k+1)} \right]$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
trying a symmetry of the form [xi=0, eta=F(x)]
checking if the LODE is missing y
-> Trying a Liouvillian solution using Kovacic's algorithm
<- No Liouvillian solutions exist
-> Trying a solution in terms of special functions:
    -> Bessel
    <- Bessel successful
<- special function solution successful`

```

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 63

```

Order:=6;
dsolve(x^2*diff(y(x),x$2)+x*diff(y(x),x)+(x-1)*y(x)=0,y(x),type='series',x=0);

```

$$y(x) = \frac{c_1 x^2 \left(1 - \frac{1}{3}x + \frac{1}{24}x^2 - \frac{1}{360}x^3 + \frac{1}{8640}x^4 - \frac{1}{302400}x^5 + O(x^6) \right) + c_2 (\ln(x) \left(x^2 - \frac{1}{3}x^3 + \frac{1}{24}x^4 - \frac{1}{360}x^5 + O(x^6) \right))}{x}$$

✓ Solution by Mathematica

Time used: 0.017 (sec). Leaf size: 83

```
AsymptoticDSolveValue[x^2*y''[x]+x*y'[x]+(x-1)*y[x]==0,y[x],{x,0,5}]
```

$$y(x) \rightarrow c_1 \left(\frac{31x^4 - 176x^3 + 144x^2 + 576x + 576}{576x} - \frac{1}{48}x(x^2 - 8x + 24) \log(x) \right) + c_2 \left(\frac{x^5}{8640} - \frac{x^4}{360} + \frac{x^3}{24} - \frac{x^2}{3} + x \right)$$

15.20 problem 20

15.20.1 Maple step by step solution 4281

Internal problem ID [11921]

Internal file name [OUTPUT/11930_Saturday_April_13_2024_10_26_29_PM_87387057/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.2 (Frobenius). Exercises page 251

Problem number: 20.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"second order series method. Regular singular point. Difference is integer"**

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$x^2y'' + (x^3 - x)y' - 3y = 0$$

With the expansion point for the power series method at $x = 0$.

The type of the expansion point is first determined. This is done on the homogeneous part of the ODE.

$$x^2y'' + (x^3 - x)y' - 3y = 0$$

The following is summary of singularities for the above ode. Writing the ode as

$$y'' + p(x)y' + q(x)y = 0$$

Where

$$p(x) = \frac{x^2 - 1}{x}$$
$$q(x) = -\frac{3}{x^2}$$

Table 565: Table $p(x), q(x)$ singularities.

$p(x) = \frac{x^2-1}{x}$	
singularity	type
$x = 0$	“regular”
$x = \infty$	“regular”
$x = -\infty$	“regular”

$q(x) = -\frac{3}{x^2}$	
singularity	type
$x = 0$	“regular”

Combining everything together gives the following summary of singularities for the ode as

Regular singular points : $[0, \infty, -\infty]$

Irregular singular points : $[\infty]$

Since $x = 0$ is regular singular point, then Frobenius power series is used. The ode is normalized to be

$$x^2 y'' + (x^3 - x) y' - 3y = 0$$

Let the solution be represented as Frobenius power series of the form

$$y = \sum_{n=0}^{\infty} a_n x^{n+r}$$

Then

$$y' = \sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1}$$

$$y'' = \sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2}$$

Substituting the above back into the ode gives

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2} \right) x^2 \\ & + (x^3 - x) \left(\sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1} \right) - 3 \left(\sum_{n=0}^{\infty} a_n x^{n+r} \right) = 0 \end{aligned} \tag{1}$$

Which simplifies to

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} x^{n+r} a_n (n+r) (n+r-1) \right) + \left(\sum_{n=0}^{\infty} x^{n+r+2} a_n (n+r) \right) \\ & + \sum_{n=0}^{\infty} (-x^{n+r} a_n (n+r)) + \sum_{n=0}^{\infty} (-3a_n x^{n+r}) = 0 \end{aligned} \quad (2A)$$

The next step is to make all powers of x be $n+r$ in each summation term. Going over each summation term above with power of x in it which is not already x^{n+r} and adjusting the power and the corresponding index gives

$$\sum_{n=0}^{\infty} x^{n+r+2} a_n (n+r) = \sum_{n=2}^{\infty} a_{n-2} (n+r-2) x^{n+r}$$

Substituting all the above in Eq (2A) gives the following equation where now all powers of x are the same and equal to $n+r$.

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} x^{n+r} a_n (n+r) (n+r-1) \right) + \left(\sum_{n=2}^{\infty} a_{n-2} (n+r-2) x^{n+r} \right) \\ & + \sum_{n=0}^{\infty} (-x^{n+r} a_n (n+r)) + \sum_{n=0}^{\infty} (-3a_n x^{n+r}) = 0 \end{aligned} \quad (2B)$$

The indicial equation is obtained from $n=0$. From Eq (2B) this gives

$$x^{n+r} a_n (n+r) (n+r-1) - x^{n+r} a_n (n+r) - 3a_n x^{n+r} = 0$$

When $n=0$ the above becomes

$$x^r a_0 r (-1+r) - x^r a_0 r - 3a_0 x^r = 0$$

Or

$$(x^r r (-1+r) - x^r r - 3x^r) a_0 = 0$$

Since $a_0 \neq 0$ then the above simplifies to

$$(r^2 - 2r - 3) x^r = 0$$

Since the above is true for all x then the indicial equation becomes

$$r^2 - 2r - 3 = 0$$

Solving for r gives the roots of the indicial equation as

$$\begin{aligned} r_1 &= 3 \\ r_2 &= -1 \end{aligned}$$

Since $a_0 \neq 0$ then the indicial equation becomes

$$(r^2 - 2r - 3) x^r = 0$$

Solving for r gives the roots of the indicial equation as Since $r_1 - r_2 = 4$ is an integer, then we can construct two linearly independent solutions

$$\begin{aligned} y_1(x) &= x^{r_1} \left(\sum_{n=0}^{\infty} a_n x^n \right) \\ y_2(x) &= C y_1(x) \ln(x) + x^{r_2} \left(\sum_{n=0}^{\infty} b_n x^n \right) \end{aligned}$$

Or

$$\begin{aligned} y_1(x) &= x^3 \left(\sum_{n=0}^{\infty} a_n x^n \right) \\ y_2(x) &= C y_1(x) \ln(x) + \frac{\sum_{n=0}^{\infty} b_n x^n}{x} \end{aligned}$$

Or

$$\begin{aligned} y_1(x) &= \sum_{n=0}^{\infty} a_n x^{n+3} \\ y_2(x) &= C y_1(x) \ln(x) + \left(\sum_{n=0}^{\infty} b_n x^{n-1} \right) \end{aligned}$$

Where C above can be zero. We start by finding y_1 . Eq (2B) derived above is now used to find all a_n coefficients. The case $n = 0$ is skipped since it was used to find the roots of the indicial equation. a_0 is arbitrary and taken as $a_0 = 1$. Substituting $n = 1$ in Eq. (2B) gives

$$a_1 = 0$$

For $2 \leq n$ the recursive equation is

$$a_n(n+r)(n+r-1) + a_{n-2}(n+r-2) - a_n(n+r) - 3a_n = 0 \quad (3)$$

Solving for a_n from recursive equation (4) gives

$$a_n = -\frac{a_{n-2}(n+r-2)}{n^2+2nr+r^2-2n-2r-3} \quad (4)$$

Which for the root $r = 3$ becomes

$$a_n = -\frac{a_{n-2}(n+1)}{n(n+4)} \quad (5)$$

At this point, it is a good idea to keep track of a_n in a table both before substituting $r = 3$ and after as more terms are found using the above recursive equation.

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0

For $n = 2$, using the above recursive equation gives

$$a_2 = -\frac{r}{r^2+2r-3}$$

Which for the root $r = 3$ becomes

$$a_2 = -\frac{1}{4}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{r}{r^2+2r-3}$	$-\frac{1}{4}$

For $n = 3$, using the above recursive equation gives

$$a_3 = 0$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{r}{r^2+2r-3}$	$-\frac{1}{4}$
a_3	0	0

For $n = 4$, using the above recursive equation gives

$$a_4 = \frac{r(2+r)}{r^4 + 8r^3 + 14r^2 - 8r - 15}$$

Which for the root $r = 3$ becomes

$$a_4 = \frac{5}{128}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{r}{r^2+2r-3}$	$-\frac{1}{4}$
a_3	0	0
a_4	$\frac{r(2+r)}{r^4+8r^3+14r^2-8r-15}$	$\frac{5}{128}$

For $n = 5$, using the above recursive equation gives

$$a_5 = 0$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{r}{r^2+2r-3}$	$-\frac{1}{4}$
a_3	0	0
a_4	$\frac{r(2+r)}{r^4+8r^3+14r^2-8r-15}$	$\frac{5}{128}$
a_5	0	0

Using the above table, then the solution $y_1(x)$ is

$$\begin{aligned} y_1(x) &= x^3(a_0 + a_1x + a_2x^2 + a_3x^3 + a_4x^4 + a_5x^5 + a_6x^6 \dots) \\ &= x^3\left(1 - \frac{x^2}{4} + \frac{5x^4}{128} + O(x^6)\right) \end{aligned}$$

Now the second solution $y_2(x)$ is found. Let

$$r_1 - r_2 = N$$

Where N is positive integer which is the difference between the two roots. r_1 is taken as the larger root. Hence for this problem we have $N = 4$. Now we need to determine if C is zero or not. This is done by finding $\lim_{r \rightarrow r_2} a_4(r)$. If this limit exists, then $C = 0$, else we need to keep the log term and $C \neq 0$. The above table shows that

$$\begin{aligned} a_N &= a_4 \\ &= \frac{r(2+r)}{r^4 + 8r^3 + 14r^2 - 8r - 15} \end{aligned}$$

Therefore

$$\begin{aligned} \lim_{r \rightarrow r_2} \frac{r(2+r)}{r^4 + 8r^3 + 14r^2 - 8r - 15} &= \lim_{r \rightarrow -1} \frac{r(2+r)}{r^4 + 8r^3 + 14r^2 - 8r - 15} \\ &= \text{undefined} \end{aligned}$$

Since the limit does not exist then the log term is needed. Therefore the second solution has the form

$$y_2(x) = Cy_1(x) \ln(x) + \left(\sum_{n=0}^{\infty} b_n x^{n+r_2} \right)$$

Therefore

$$\begin{aligned} \frac{d}{dx} y_2(x) &= Cy_1'(x) \ln(x) + \frac{Cy_1(x)}{x} + \left(\sum_{n=0}^{\infty} \frac{b_n x^{n+r_2} (n+r_2)}{x} \right) \\ &= Cy_1'(x) \ln(x) + \frac{Cy_1(x)}{x} + \left(\sum_{n=0}^{\infty} x^{-1+n+r_2} b_n (n+r_2) \right) \\ \frac{d^2}{dx^2} y_2(x) &= Cy_1''(x) \ln(x) + \frac{2Cy_1'(x)}{x} - \frac{Cy_1(x)}{x^2} \\ &\quad + \sum_{n=0}^{\infty} \left(\frac{b_n x^{n+r_2} (n+r_2)^2}{x^2} - \frac{b_n x^{n+r_2} (n+r_2)}{x^2} \right) \\ &= Cy_1''(x) \ln(x) + \frac{2Cy_1'(x)}{x} - \frac{Cy_1(x)}{x^2} + \left(\sum_{n=0}^{\infty} x^{-2+n+r_2} b_n (n+r_2) (-1+n+r_2) \right) \end{aligned}$$

Substituting these back into the given ode $x^2y'' + (x^3 - x)y' - 3y = 0$ gives

$$\begin{aligned} & \left(Cy_1''(x) \ln(x) + \frac{2Cy_1'(x)}{x} - \frac{Cy_1(x)}{x^2} \right. \\ & \left. + \sum_{n=0}^{\infty} \left(\frac{b_n x^{n+r_2}(n+r_2)^2}{x^2} - \frac{b_n x^{n+r_2}(n+r_2)}{x^2} \right) \right) x^2 \\ & + (x^3 - x) \left(Cy_1'(x) \ln(x) + \frac{Cy_1(x)}{x} + \left(\sum_{n=0}^{\infty} \frac{b_n x^{n+r_2}(n+r_2)}{x} \right) \right) \\ & - 3Cy_1(x) \ln(x) - 3 \left(\sum_{n=0}^{\infty} b_n x^{n+r_2} \right) = 0 \end{aligned}$$

Which can be written as

$$\begin{aligned} & \left((y_1''(x) x^2 + (x^3 - x) y_1'(x) - 3y_1(x)) \ln(x) + \left(\frac{2y_1'(x)}{x} - \frac{y_1(x)}{x^2} \right) x^2 \right. \\ & \left. + \frac{(x^3 - x) y_1(x)}{x} \right) C + \left(\sum_{n=0}^{\infty} \left(\frac{b_n x^{n+r_2}(n+r_2)^2}{x^2} - \frac{b_n x^{n+r_2}(n+r_2)}{x^2} \right) \right) x^2 \quad (7) \\ & + (x^3 - x) \left(\sum_{n=0}^{\infty} \frac{b_n x^{n+r_2}(n+r_2)}{x} \right) - 3 \left(\sum_{n=0}^{\infty} b_n x^{n+r_2} \right) = 0 \end{aligned}$$

But since $y_1(x)$ is a solution to the ode, then

$$y_1''(x) x^2 + (x^3 - x) y_1'(x) - 3y_1(x) = 0$$

Eq (7) simplifies to

$$\begin{aligned} & \left(\left(\frac{2y_1'(x)}{x} - \frac{y_1(x)}{x^2} \right) x^2 + \frac{(x^3 - x) y_1(x)}{x} \right) C \\ & + \left(\sum_{n=0}^{\infty} \left(\frac{b_n x^{n+r_2}(n+r_2)^2}{x^2} - \frac{b_n x^{n+r_2}(n+r_2)}{x^2} \right) \right) x^2 \quad (8) \\ & + (x^3 - x) \left(\sum_{n=0}^{\infty} \frac{b_n x^{n+r_2}(n+r_2)}{x} \right) - 3 \left(\sum_{n=0}^{\infty} b_n x^{n+r_2} \right) = 0 \end{aligned}$$

Substituting $y_1 = \sum_{n=0}^{\infty} a_n x^{n+r_1}$ into the above gives

$$\begin{aligned} & \left(2 \left(\sum_{n=0}^{\infty} x^{-1+n+r_1} a_n (n+r_1) \right) x + (x^2 - 2) \left(\sum_{n=0}^{\infty} a_n x^{n+r_1} \right) \right) C \\ & + \left(\sum_{n=0}^{\infty} x^{-2+n+r_2} b_n (n+r_2) (-1+n+r_2) \right) x^2 \\ & + (x^3 - x) \left(\sum_{n=0}^{\infty} x^{-1+n+r_2} b_n (n+r_2) \right) - 3 \left(\sum_{n=0}^{\infty} b_n x^{n+r_2} \right) = 0 \end{aligned} \quad (9)$$

Since $r_1 = 3$ and $r_2 = -1$ then the above becomes

$$\begin{aligned} & \left(2 \left(\sum_{n=0}^{\infty} x^{2+n} a_n (n+3) \right) x + (x^2 - 2) \left(\sum_{n=0}^{\infty} a_n x^{n+3} \right) \right) C \\ & + \left(\sum_{n=0}^{\infty} x^{-3+n} b_n (n-1) (n-2) \right) x^2 \\ & + (x^3 - x) \left(\sum_{n=0}^{\infty} x^{n-2} b_n (n-1) \right) - 3 \left(\sum_{n=0}^{\infty} b_n x^{n-1} \right) = 0 \end{aligned} \quad (10)$$

Which simplifies to

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} 2C x^{n+3} a_n (n+3) \right) + \left(\sum_{n=0}^{\infty} C x^{n+5} a_n \right) + \sum_{n=0}^{\infty} (-2C x^{n+3} a_n) \\ & + \left(\sum_{n=0}^{\infty} x^{n-1} b_n (n^2 - 3n + 2) \right) + \left(\sum_{n=0}^{\infty} x^{n+1} b_n (n-1) \right) \\ & + \sum_{n=0}^{\infty} (-x^{n-1} b_n (n-1)) + \sum_{n=0}^{\infty} (-3b_n x^{n-1}) = 0 \end{aligned} \quad (2A)$$

The next step is to make all powers of x be $n-1$ in each summation term. Going over each summation term above with power of x in it which is not already x^{n-1} and

adjusting the power and the corresponding index gives

$$\begin{aligned} \sum_{n=0}^{\infty} 2C x^{n+3} a_n (n+3) &= \sum_{n=4}^{\infty} 2C a_{n-4} (n-1) x^{n-1} \\ \sum_{n=0}^{\infty} C x^{n+5} a_n &= \sum_{n=6}^{\infty} C a_{n-6} x^{n-1} \\ \sum_{n=0}^{\infty} (-2C x^{n+3} a_n) &= \sum_{n=4}^{\infty} (-2C a_{n-4} x^{n-1}) \\ \sum_{n=0}^{\infty} x^{n+1} b_n (n-1) &= \sum_{n=2}^{\infty} b_{n-2} (-3+n) x^{n-1} \end{aligned}$$

Substituting all the above in Eq (2A) gives the following equation where now all powers of x are the same and equal to $n - 1$.

$$\begin{aligned} &\left(\sum_{n=4}^{\infty} 2C a_{n-4} (n-1) x^{n-1} \right) + \left(\sum_{n=6}^{\infty} C a_{n-6} x^{n-1} \right) + \sum_{n=4}^{\infty} (-2C a_{n-4} x^{n-1}) \\ &+ \left(\sum_{n=0}^{\infty} x^{n-1} b_n (n^2 - 3n + 2) \right) + \left(\sum_{n=2}^{\infty} b_{n-2} (-3+n) x^{n-1} \right) \quad (2B) \\ &+ \sum_{n=0}^{\infty} (-x^{n-1} b_n (n-1)) + \sum_{n=0}^{\infty} (-3b_n x^{n-1}) = 0 \end{aligned}$$

For $n = 0$ in Eq. (2B), we choose arbitrary value for b_0 as $b_0 = 1$. For $n = 1$, Eq (2B) gives

$$-3b_1 = 0$$

Which when replacing the above values found already for b_n and the values found earlier for a_n and for C , gives

$$-3b_1 = 0$$

Solving the above for b_1 gives

$$b_1 = 0$$

For $n = 2$, Eq (2B) gives

$$-b_0 - 4b_2 = 0$$

Which when replacing the above values found already for b_n and the values found earlier for a_n and for C , gives

$$-1 - 4b_2 = 0$$

Solving the above for b_2 gives

$$b_2 = -\frac{1}{4}$$

For $n = 3$, Eq (2B) gives

$$-3b_3 = 0$$

Which when replacing the above values found already for b_n and the values found earlier for a_n and for C , gives

$$-3b_3 = 0$$

Solving the above for b_3 gives

$$b_3 = 0$$

For $n = N$, where $N = 4$ which is the difference between the two roots, we are free to choose $b_4 = 0$. Hence for $n = 4$, Eq (2B) gives

$$4C - \frac{1}{4} = 0$$

Which is solved for C . Solving for C gives

$$C = \frac{1}{16}$$

For $n = 5$, Eq (2B) gives

$$6Ca_1 + 2b_3 + 5b_5 = 0$$

Which when replacing the above values found already for b_n and the values found earlier for a_n and for C , gives

$$5b_5 = 0$$

Solving the above for b_5 gives

$$b_5 = 0$$

Now that we found all b_n and C , we can calculate the second solution from

$$y_2(x) = Cy_1(x) \ln(x) + \left(\sum_{n=0}^{\infty} b_n x^{n+r_2} \right)$$

Using the above value found for $C = \frac{1}{16}$ and all b_n , then the second solution becomes

$$y_2(x) = \frac{1}{16} \left(x^3 \left(1 - \frac{x^2}{4} + \frac{5x^4}{128} + O(x^6) \right) \right) \ln(x) + \frac{1 - \frac{x^2}{4} + O(x^6)}{x}$$

Therefore the homogeneous solution is

$$\begin{aligned}y_h(x) &= c_1 y_1(x) + c_2 y_2(x) \\&= c_1 x^3 \left(1 - \frac{x^2}{4} + \frac{5x^4}{128} + O(x^6) \right) \\&\quad + c_2 \left(\frac{1}{16} \left(x^3 \left(1 - \frac{x^2}{4} + \frac{5x^4}{128} + O(x^6) \right) \right) \ln(x) + \frac{1 - \frac{x^2}{4} + O(x^6)}{x} \right)\end{aligned}$$

Hence the final solution is

$$\begin{aligned}y &= y_h \\&= c_1 x^3 \left(1 - \frac{x^2}{4} + \frac{5x^4}{128} + O(x^6) \right) \\&\quad + c_2 \left(\frac{x^3 \left(1 - \frac{x^2}{4} + \frac{5x^4}{128} + O(x^6) \right) \ln(x)}{16} + \frac{1 - \frac{x^2}{4} + O(x^6)}{x} \right)\end{aligned}$$

Summary

The solution(s) found are the following

$$\begin{aligned}y &= c_1 x^3 \left(1 - \frac{x^2}{4} + \frac{5x^4}{128} + O(x^6) \right) \\&\quad + c_2 \left(\frac{x^3 \left(1 - \frac{x^2}{4} + \frac{5x^4}{128} + O(x^6) \right) \ln(x)}{16} + \frac{1 - \frac{x^2}{4} + O(x^6)}{x} \right)\end{aligned}\tag{1}$$

Verification of solutions

$$\begin{aligned}y &= c_1 x^3 \left(1 - \frac{x^2}{4} + \frac{5x^4}{128} + O(x^6) \right) \\&\quad + c_2 \left(\frac{x^3 \left(1 - \frac{x^2}{4} + \frac{5x^4}{128} + O(x^6) \right) \ln(x)}{16} + \frac{1 - \frac{x^2}{4} + O(x^6)}{x} \right)\end{aligned}$$

Verified OK.

15.20.1 Maple step by step solution

Let's solve

$$y''x^2 + (x^3 - x)y' - 3y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = \frac{3y}{x^2} - \frac{(x^2-1)y'}{x}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + \frac{(x^2-1)y'}{x} - \frac{3y}{x^2} = 0$$

- Check to see if $x_0 = 0$ is a regular singular point

- Define functions

$$\left[P_2(x) = \frac{x^2-1}{x}, P_3(x) = -\frac{3}{x^2} \right]$$

- $x \cdot P_2(x)$ is analytic at $x = 0$

$$(x \cdot P_2(x)) \Big|_{x=0} = -1$$

- $x^2 \cdot P_3(x)$ is analytic at $x = 0$

$$(x^2 \cdot P_3(x)) \Big|_{x=0} = -3$$

- $x = 0$ is a regular singular point

Check to see if $x_0 = 0$ is a regular singular point

$$x_0 = 0$$

- Multiply by denominators

$$y''x^2 + (x^2 - 1)xy' - 3y = 0$$

- Assume series solution for y

$$y = \sum_{k=0}^{\infty} a_k x^{k+r}$$

- Rewrite ODE with series expansions

- Convert $x^m \cdot y'$ to series expansion for $m = 1..3$

$$x^m \cdot y' = \sum_{k=0}^{\infty} a_k (k+r) x^{k+r-1+m}$$

- Shift index using $k \rightarrow k + 1 - m$

$$x^m \cdot y' = \sum_{k=-1+m}^{\infty} a_{k+1-m}(k+1-m+r)x^{k+r}$$

- Convert $x^2 \cdot y''$ to series expansion

$$x^2 \cdot y'' = \sum_{k=0}^{\infty} a_k(k+r)(k+r-1)x^{k+r}$$

Rewrite ODE with series expansions

$$a_0(1+r)(-3+r)x^r + a_1(2+r)(-2+r)x^{1+r} + \left(\sum_{k=2}^{\infty} (a_k(k+r+1)(k+r-3) + a_{k-2}(k-2+r)(k+r-1)) \right) x^{k+r} = 0$$

- a_0 cannot be 0 by assumption, giving the indicial equation

$$(1+r)(-3+r) = 0$$

- Values of r that satisfy the indicial equation

$$r \in \{-1, 3\}$$

- Each term must be 0

$$a_1(2+r)(-2+r) = 0$$

- Solve for the dependent coefficient(s)

$$a_1 = 0$$

- Each term in the series must be 0, giving the recursion relation

$$a_k(k+r+1)(k+r-3) + a_{k-2}(k-2+r)(k+r-1) = 0$$

- Shift index using $k \rightarrow k + 2$

$$a_{k+2}(k+3+r)(k+r-1) + a_k(k+r) = 0$$

- Recursion relation that defines series solution to ODE

$$a_{k+2} = -\frac{a_k(k+r)}{(k+3+r)(k+r-1)}$$

- Recursion relation for $r = -1$

$$a_{k+2} = -\frac{a_k(k-1)}{(k+2)(k-2)}$$

- Series not valid for $r = -1$, division by 0 in the recursion relation at $k = 2$

$$a_{k+2} = -\frac{a_k(k-1)}{(k+2)(k-2)}$$

- Recursion relation for $r = 3$

$$a_{k+2} = -\frac{a_k(k+3)}{(k+6)(k+2)}$$

- Solution for $r = 3$

$$\left[y = \sum_{k=0}^{\infty} a_k x^{k+3}, a_{k+2} = -\frac{a_k(k+3)}{(k+6)(k+2)}, a_1 = 0 \right]$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
trying a symmetry of the form [xi=0, eta=F(x)]
checking if the LODE is missing y
-> Trying a Liouvillian solution using Kovacic's algorithm
<- No Liouvillian solutions exists
-> Trying a solution in terms of special functions:
    -> Bessel
    <- Bessel successful
<- special function solution successful`

```

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 47

```

Order:=6;
dsolve(x^2*diff(y(x),x$2)+(x^3-x)*diff(y(x),x)-3*y(x)=0,y(x),type='series',x=0);

```

$$y(x) = \frac{c_1 x^4 \left(1 - \frac{1}{4}x^2 + \frac{5}{128}x^4 + O(x^6)\right) + c_2 (\ln(x) ((-9)x^4 + O(x^6)) + (-144 + 36x^2 + O(x^6)))}{x}$$

✓ Solution by Mathematica

Time used: 0.01 (sec). Leaf size: 55

```

AsymptoticDSolveValue[x^2*y''[x]+(x^3-x)*y'[x]-3*y[x]==0,y[x],{x,0,5}]

```

$$y(x) \rightarrow c_2 \left(\frac{5x^7}{128} - \frac{x^5}{4} + x^3 \right) + c_1 \left(\frac{1}{16} x^3 \log(x) - \frac{x^4 + 16x^2 - 64}{64x} \right)$$

15.21 problem 21

15.21.1 Maple step by step solution 4296

Internal problem ID [11922]

Internal file name [OUTPUT/11931_Saturday_April_13_2024_10_26_30_PM_98169401/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.2 (Frobenius). Exercises page 251

Problem number: 21.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"second order series method. Regular singular point. Difference is integer"**

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$x^2y'' - y'x + 8y(x^2 - 1) = 0$$

With the expansion point for the power series method at $x = 0$.

The type of the expansion point is first determined. This is done on the homogeneous part of the ODE.

$$x^2y'' - y'x + (8x^2 - 8)y = 0$$

The following is summary of singularities for the above ode. Writing the ode as

$$y'' + p(x)y' + q(x)y = 0$$

Where

$$p(x) = -\frac{1}{x}$$
$$q(x) = \frac{8x^2 - 8}{x^2}$$

Table 567: Table $p(x), q(x)$ singularities.

$p(x) = -\frac{1}{x}$	
singularity	type
$x = 0$	“regular”

$q(x) = \frac{8x^2-8}{x^2}$	
singularity	type
$x = 0$	“regular”

Combining everything together gives the following summary of singularities for the ode as

Regular singular points : $[0]$

Irregular singular points : $[\infty]$

Since $x = 0$ is regular singular point, then Frobenius power series is used. The ode is normalized to be

$$x^2 y'' - y'x + (8x^2 - 8)y = 0$$

Let the solution be represented as Frobenius power series of the form

$$y = \sum_{n=0}^{\infty} a_n x^{n+r}$$

Then

$$y' = \sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1}$$

$$y'' = \sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2}$$

Substituting the above back into the ode gives

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2} \right) x^2 \\ & - \left(\sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1} \right) x + (8x^2 - 8) \left(\sum_{n=0}^{\infty} a_n x^{n+r} \right) = 0 \end{aligned} \tag{1}$$

Which simplifies to

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} x^{n+r} a_n (n+r) (n+r-1) \right) + \sum_{n=0}^{\infty} (-x^{n+r} a_n (n+r)) \\ & + \left(\sum_{n=0}^{\infty} 8x^{n+r+2} a_n \right) + \sum_{n=0}^{\infty} (-8a_n x^{n+r}) = 0 \end{aligned} \quad (2A)$$

The next step is to make all powers of x be $n+r$ in each summation term. Going over each summation term above with power of x in it which is not already x^{n+r} and adjusting the power and the corresponding index gives

$$\sum_{n=0}^{\infty} 8x^{n+r+2} a_n = \sum_{n=2}^{\infty} 8a_{n-2} x^{n+r}$$

Substituting all the above in Eq (2A) gives the following equation where now all powers of x are the same and equal to $n+r$.

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} x^{n+r} a_n (n+r) (n+r-1) \right) + \sum_{n=0}^{\infty} (-x^{n+r} a_n (n+r)) \\ & + \left(\sum_{n=2}^{\infty} 8a_{n-2} x^{n+r} \right) + \sum_{n=0}^{\infty} (-8a_n x^{n+r}) = 0 \end{aligned} \quad (2B)$$

The indicial equation is obtained from $n=0$. From Eq (2B) this gives

$$x^{n+r} a_n (n+r) (n+r-1) - x^{n+r} a_n (n+r) - 8a_n x^{n+r} = 0$$

When $n=0$ the above becomes

$$x^r a_0 r(-1+r) - x^r a_0 r - 8a_0 x^r = 0$$

Or

$$(x^r r(-1+r) - x^r r - 8x^r) a_0 = 0$$

Since $a_0 \neq 0$ then the above simplifies to

$$(r^2 - 2r - 8) x^r = 0$$

Since the above is true for all x then the indicial equation becomes

$$r^2 - 2r - 8 = 0$$

Solving for r gives the roots of the indicial equation as

$$\begin{aligned} r_1 &= 4 \\ r_2 &= -2 \end{aligned}$$

Since $a_0 \neq 0$ then the indicial equation becomes

$$(r^2 - 2r - 8) x^r = 0$$

Solving for r gives the roots of the indicial equation as Since $r_1 - r_2 = 6$ is an integer, then we can construct two linearly independent solutions

$$\begin{aligned} y_1(x) &= x^{r_1} \left(\sum_{n=0}^{\infty} a_n x^n \right) \\ y_2(x) &= C y_1(x) \ln(x) + x^{r_2} \left(\sum_{n=0}^{\infty} b_n x^n \right) \end{aligned}$$

Or

$$\begin{aligned} y_1(x) &= x^4 \left(\sum_{n=0}^{\infty} a_n x^n \right) \\ y_2(x) &= C y_1(x) \ln(x) + \frac{\sum_{n=0}^{\infty} b_n x^n}{x^2} \end{aligned}$$

Or

$$\begin{aligned} y_1(x) &= \sum_{n=0}^{\infty} a_n x^{n+4} \\ y_2(x) &= C y_1(x) \ln(x) + \left(\sum_{n=0}^{\infty} b_n x^{n-2} \right) \end{aligned}$$

Where C above can be zero. We start by finding y_1 . Eq (2B) derived above is now used to find all a_n coefficients. The case $n = 0$ is skipped since it was used to find the roots of the indicial equation. a_0 is arbitrary and taken as $a_0 = 1$. Substituting $n = 1$ in Eq. (2B) gives

$$a_1 = 0$$

For $2 \leq n$ the recursive equation is

$$a_n(n+r)(n+r-1) - a_n(n+r) + 8a_{n-2} - 8a_n = 0 \quad (3)$$

Solving for a_n from recursive equation (4) gives

$$a_n = -\frac{8a_{n-2}}{n^2 + 2nr + r^2 - 2n - 2r - 8} \quad (4)$$

Which for the root $r = 4$ becomes

$$a_n = -\frac{8a_{n-2}}{n(n+6)} \quad (5)$$

At this point, it is a good idea to keep track of a_n in a table both before substituting $r = 4$ and after as more terms are found using the above recursive equation.

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0

For $n = 2$, using the above recursive equation gives

$$a_2 = -\frac{8}{r^2 + 2r - 8}$$

Which for the root $r = 4$ becomes

$$a_2 = -\frac{1}{2}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{8}{r^2+2r-8}$	$-\frac{1}{2}$

For $n = 3$, using the above recursive equation gives

$$a_3 = 0$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{8}{r^2+2r-8}$	$-\frac{1}{2}$
a_3	0	0

For $n = 4$, using the above recursive equation gives

$$a_4 = \frac{64}{(r+4)(r-2)r(r+6)}$$

Which for the root $r = 4$ becomes

$$a_4 = \frac{1}{10}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{8}{r^2+2r-8}$	$-\frac{1}{2}$
a_3	0	0
a_4	$\frac{64}{(r+4)(r-2)r(r+6)}$	$\frac{1}{10}$

For $n = 5$, using the above recursive equation gives

$$a_5 = 0$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{8}{r^2+2r-8}$	$-\frac{1}{2}$
a_3	0	0
a_4	$\frac{64}{(r+4)(r-2)r(r+6)}$	$\frac{1}{10}$
a_5	0	0

For $n = 6$, using the above recursive equation gives

$$a_6 = -\frac{512}{(r+4)(r-2)r(r+6)(r+8)(r+2)}$$

Which for the root $r = 4$ becomes

$$a_6 = -\frac{1}{90}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{8}{r^2+2r-8}$	$-\frac{1}{2}$
a_3	0	0
a_4	$\frac{64}{(r+4)(r-2)r(r+6)}$	$\frac{1}{10}$
a_5	0	0
a_6	$-\frac{512}{(r+4)(r-2)r(r+6)(r+8)(r+2)}$	$-\frac{1}{90}$

Using the above table, then the solution $y_1(x)$ is

$$\begin{aligned} y_1(x) &= x^4(a_0 + a_1x + a_2x^2 + a_3x^3 + a_4x^4 + a_5x^5 + a_6x^6 + a_7x^7 \dots) \\ &= x^4\left(1 - \frac{x^2}{2} + \frac{x^4}{10} - \frac{x^6}{90} + O(x^7)\right) \end{aligned}$$

Now the second solution $y_2(x)$ is found. Let

$$r_1 - r_2 = N$$

Where N is positive integer which is the difference between the two roots. r_1 is taken as the larger root. Hence for this problem we have $N = 6$. Now we need to determine if C is zero or not. This is done by finding $\lim_{r \rightarrow r_2} a_6(r)$. If this limit exists, then $C = 0$, else we need to keep the log term and $C \neq 0$. The above table shows that

$$\begin{aligned} a_N &= a_6 \\ &= -\frac{512}{(r+4)(r-2)r(r+6)(r+8)(r+2)} \end{aligned}$$

Therefore

$$\begin{aligned} \lim_{r \rightarrow r_2} -\frac{512}{(r+4)(r-2)r(r+6)(r+8)(r+2)} &= \lim_{r \rightarrow -2} -\frac{512}{(r+4)(r-2)r(r+6)(r+8)(r+2)} \\ &= \text{undefined} \end{aligned}$$

Since the limit does not exist then the log term is needed. Therefore the second solution has the form

$$y_2(x) = Cy_1(x) \ln(x) + \left(\sum_{n=0}^{\infty} b_n x^{n+r_2} \right)$$

Therefore

$$\begin{aligned} \frac{d}{dx}y_2(x) &= Cy_1'(x) \ln(x) + \frac{Cy_1(x)}{x} + \left(\sum_{n=0}^{\infty} \frac{b_n x^{n+r_2}(n+r_2)}{x} \right) \\ &= Cy_1'(x) \ln(x) + \frac{Cy_1(x)}{x} + \left(\sum_{n=0}^{\infty} x^{-1+n+r_2} b_n (n+r_2) \right) \\ \frac{d^2}{dx^2}y_2(x) &= Cy_1''(x) \ln(x) + \frac{2Cy_1'(x)}{x} - \frac{Cy_1(x)}{x^2} \\ &\quad + \sum_{n=0}^{\infty} \left(\frac{b_n x^{n+r_2}(n+r_2)^2}{x^2} - \frac{b_n x^{n+r_2}(n+r_2)}{x^2} \right) \\ &= Cy_1''(x) \ln(x) + \frac{2Cy_1'(x)}{x} - \frac{Cy_1(x)}{x^2} + \left(\sum_{n=0}^{\infty} x^{-2+n+r_2} b_n (n+r_2) (-1+n+r_2) \right) \end{aligned}$$

Substituting these back into the given ode $x^2y'' - y'x + (8x^2 - 8)y = 0$ gives

$$\begin{aligned} &\left(Cy_1''(x) \ln(x) + \frac{2Cy_1'(x)}{x} - \frac{Cy_1(x)}{x^2} \right. \\ &\quad \left. + \sum_{n=0}^{\infty} \left(\frac{b_n x^{n+r_2}(n+r_2)^2}{x^2} - \frac{b_n x^{n+r_2}(n+r_2)}{x^2} \right) \right) x^2 \\ &\quad - \left(Cy_1'(x) \ln(x) + \frac{Cy_1(x)}{x} + \left(\sum_{n=0}^{\infty} \frac{b_n x^{n+r_2}(n+r_2)}{x} \right) \right) x \\ &\quad + (8x^2 - 8) \left(Cy_1(x) \ln(x) + \left(\sum_{n=0}^{\infty} b_n x^{n+r_2} \right) \right) = 0 \end{aligned}$$

Which can be written as

$$\begin{aligned} &\left((y_1''(x) x^2 - y_1'(x) x + (8x^2 - 8) y_1(x)) \ln(x) + \left(\frac{2y_1'(x)}{x} - \frac{y_1(x)}{x^2} \right) x^2 \right. \\ &\quad \left. - y_1(x) \right) C + \left(\sum_{n=0}^{\infty} \left(\frac{b_n x^{n+r_2}(n+r_2)^2}{x^2} - \frac{b_n x^{n+r_2}(n+r_2)}{x^2} \right) \right) x^2 \quad (7) \\ &\quad - \left(\sum_{n=0}^{\infty} \frac{b_n x^{n+r_2}(n+r_2)}{x} \right) x + (8x^2 - 8) \left(\sum_{n=0}^{\infty} b_n x^{n+r_2} \right) = 0 \end{aligned}$$

But since $y_1(x)$ is a solution to the ode, then

$$y_1''(x) x^2 - y_1'(x) x + (8x^2 - 8) y_1(x) = 0$$

Eq (7) simplifies to

$$\begin{aligned} & \left(\left(\frac{2y_1'(x)}{x} - \frac{y_1(x)}{x^2} \right) x^2 - y_1(x) \right) C \\ & + \left(\sum_{n=0}^{\infty} \left(\frac{b_n x^{n+r_2} (n+r_2)^2}{x^2} - \frac{b_n x^{n+r_2} (n+r_2)}{x^2} \right) \right) x^2 \\ & - \left(\sum_{n=0}^{\infty} \frac{b_n x^{n+r_2} (n+r_2)}{x} \right) x + (8x^2 - 8) \left(\sum_{n=0}^{\infty} b_n x^{n+r_2} \right) = 0 \end{aligned} \quad (8)$$

Substituting $y_1 = \sum_{n=0}^{\infty} a_n x^{n+r_1}$ into the above gives

$$\begin{aligned} & \left(2 \left(\sum_{n=0}^{\infty} x^{-1+n+r_1} a_n (n+r_1) \right) x - 2 \left(\sum_{n=0}^{\infty} a_n x^{n+r_1} \right) \right) C \\ & + \left(\sum_{n=0}^{\infty} x^{-2+n+r_2} b_n (n+r_2) (-1+n+r_2) \right) x^2 + 8 \left(\sum_{n=0}^{\infty} b_n x^{n+r_2} \right) x^2 \\ & - \left(\sum_{n=0}^{\infty} x^{-1+n+r_2} b_n (n+r_2) \right) x - 8 \left(\sum_{n=0}^{\infty} b_n x^{n+r_2} \right) = 0 \end{aligned} \quad (9)$$

Since $r_1 = 4$ and $r_2 = -2$ then the above becomes

$$\begin{aligned} & \left(2 \left(\sum_{n=0}^{\infty} x^{3+n} a_n (n+4) \right) x - 2 \left(\sum_{n=0}^{\infty} a_n x^{n+4} \right) \right) C \\ & + \left(\sum_{n=0}^{\infty} x^{-4+n} b_n (n-2) (-3+n) \right) x^2 + 8 \left(\sum_{n=0}^{\infty} b_n x^{n-2} \right) x^2 \\ & - \left(\sum_{n=0}^{\infty} x^{-3+n} b_n (n-2) \right) x - 8 \left(\sum_{n=0}^{\infty} b_n x^{n-2} \right) = 0 \end{aligned} \quad (10)$$

Which simplifies to

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} 2C x^{n+4} a_n (n+4) \right) + \sum_{n=0}^{\infty} (-2C a_n x^{n+4}) + \left(\sum_{n=0}^{\infty} x^{n-2} b_n (n^2 - 5n + 6) \right) \\ & + \left(\sum_{n=0}^{\infty} 8b_n x^n \right) + \sum_{n=0}^{\infty} (-x^{n-2} b_n (n-2)) + \sum_{n=0}^{\infty} (-8b_n x^{n-2}) = 0 \end{aligned} \quad (2A)$$

The next step is to make all powers of x be $n - 2$ in each summation term. Going over each summation term above with power of x in it which is not already x^{n-2} and adjusting the power and the corresponding index gives

$$\begin{aligned} \sum_{n=0}^{\infty} 2C x^{n+4} a_n (n+4) &= \sum_{n=6}^{\infty} 2C a_{n-6} (n-2) x^{n-2} \\ \sum_{n=0}^{\infty} (-2C a_n x^{n+4}) &= \sum_{n=6}^{\infty} (-2C a_{n-6} x^{n-2}) \\ \sum_{n=0}^{\infty} 8b_n x^n &= \sum_{n=2}^{\infty} 8b_{n-2} x^{n-2} \end{aligned}$$

Substituting all the above in Eq (2A) gives the following equation where now all powers of x are the same and equal to $n - 2$.

$$\begin{aligned} & \left(\sum_{n=6}^{\infty} 2C a_{n-6} (n-2) x^{n-2} \right) + \sum_{n=6}^{\infty} (-2C a_{n-6} x^{n-2}) \\ & + \left(\sum_{n=0}^{\infty} x^{n-2} b_n (n^2 - 5n + 6) \right) + \left(\sum_{n=2}^{\infty} 8b_{n-2} x^{n-2} \right) \\ & + \sum_{n=0}^{\infty} (-x^{n-2} b_n (n-2)) + \sum_{n=0}^{\infty} (-8b_n x^{n-2}) = 0 \end{aligned} \quad (2B)$$

For $n = 0$ in Eq. (2B), we choose arbitrary value for b_0 as $b_0 = 1$. For $n = 1$, Eq (2B) gives

$$-5b_1 = 0$$

Which when replacing the above values found already for b_n and the values found earlier for a_n and for C , gives

$$-5b_1 = 0$$

Solving the above for b_1 gives

$$b_1 = 0$$

For $n = 2$, Eq (2B) gives

$$8b_0 - 8b_2 = 0$$

Which when replacing the above values found already for b_n and the values found earlier for a_n and for C , gives

$$8 - 8b_2 = 0$$

Solving the above for b_2 gives

$$b_2 = 1$$

For $n = 3$, Eq (2B) gives

$$8b_1 - 9b_3 = 0$$

Which when replacing the above values found already for b_n and the values found earlier for a_n and for C , gives

$$-9b_3 = 0$$

Solving the above for b_3 gives

$$b_3 = 0$$

For $n = 4$, Eq (2B) gives

$$8b_2 - 8b_4 = 0$$

Which when replacing the above values found already for b_n and the values found earlier for a_n and for C , gives

$$8 - 8b_4 = 0$$

Solving the above for b_4 gives

$$b_4 = 1$$

For $n = 5$, Eq (2B) gives

$$-5b_5 + 8b_3 = 0$$

Which when replacing the above values found already for b_n and the values found earlier for a_n and for C , gives

$$-5b_5 = 0$$

Solving the above for b_5 gives

$$b_5 = 0$$

For $n = N$, where $N = 6$ which is the difference between the two roots, we are free to choose $b_6 = 0$. Hence for $n = 6$, Eq (2B) gives

$$6C + 8 = 0$$

Which is solved for C . Solving for C gives

$$C = -\frac{4}{3}$$

Now that we found all b_n and C , we can calculate the second solution from

$$y_2(x) = Cy_1(x) \ln(x) + \left(\sum_{n=0}^{\infty} b_n x^{n+r_2} \right)$$

Using the above value found for $C = -\frac{4}{3}$ and all b_n , then the second solution becomes

$$y_2(x) = -\frac{4}{3} \left(x^4 \left(1 - \frac{x^2}{2} + \frac{x^4}{10} - \frac{x^6}{90} + O(x^7) \right) \right) \ln(x) + \frac{1 + x^2 + x^4 + O(x^7)}{x^2}$$

Therefore the homogeneous solution is

$$\begin{aligned} y_h(x) &= c_1 y_1(x) + c_2 y_2(x) \\ &= c_1 x^4 \left(1 - \frac{x^2}{2} + \frac{x^4}{10} - \frac{x^6}{90} + O(x^7) \right) \\ &\quad + c_2 \left(-\frac{4}{3} \left(x^4 \left(1 - \frac{x^2}{2} + \frac{x^4}{10} - \frac{x^6}{90} + O(x^7) \right) \right) \ln(x) + \frac{1 + x^2 + x^4 + O(x^7)}{x^2} \right) \end{aligned}$$

Hence the final solution is

$$\begin{aligned} y &= y_h \\ &= c_1 x^4 \left(1 - \frac{x^2}{2} + \frac{x^4}{10} - \frac{x^6}{90} + O(x^7) \right) \\ &\quad + c_2 \left(-\frac{4x^4 \left(1 - \frac{x^2}{2} + \frac{x^4}{10} - \frac{x^6}{90} + O(x^7) \right) \ln(x)}{3} + \frac{1 + x^2 + x^4 + O(x^7)}{x^2} \right) \end{aligned}$$

Summary

The solution(s) found are the following

$$\begin{aligned} y &= c_1 x^4 \left(1 - \frac{x^2}{2} + \frac{x^4}{10} - \frac{x^6}{90} + O(x^7) \right) \\ &\quad + c_2 \left(-\frac{4x^4 \left(1 - \frac{x^2}{2} + \frac{x^4}{10} - \frac{x^6}{90} + O(x^7) \right) \ln(x)}{3} + \frac{1 + x^2 + x^4 + O(x^7)}{x^2} \right) \end{aligned} \quad (1)$$

Verification of solutions

$$y = c_1 x^4 \left(1 - \frac{x^2}{2} + \frac{x^4}{10} - \frac{x^6}{90} + O(x^7) \right) + c_2 \left(-\frac{4x^4 \left(1 - \frac{x^2}{2} + \frac{x^4}{10} - \frac{x^6}{90} + O(x^7) \right) \ln(x)}{3} + \frac{1 + x^2 + x^4 + O(x^7)}{x^2} \right)$$

Verified OK.

15.21.1 Maple step by step solution

Let's solve

$$y''x^2 - y'x + (8x^2 - 8)y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = -\frac{8(x^2-1)y}{x^2} + \frac{y'}{x}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' - \frac{y'}{x} + \frac{8(x^2-1)y}{x^2} = 0$$

- Check to see if $x_0 = 0$ is a regular singular point

- Define functions

$$\left[P_2(x) = -\frac{1}{x}, P_3(x) = \frac{8(x^2-1)}{x^2} \right]$$

- $x \cdot P_2(x)$ is analytic at $x = 0$

$$(x \cdot P_2(x)) \Big|_{x=0} = -1$$

- $x^2 \cdot P_3(x)$ is analytic at $x = 0$

$$(x^2 \cdot P_3(x)) \Big|_{x=0} = -8$$

- $x = 0$ is a regular singular point

Check to see if $x_0 = 0$ is a regular singular point

$$x_0 = 0$$

- Multiply by denominators

$$y''x^2 - y'x + (8x^2 - 8)y = 0$$

- Assume series solution for y

$$y = \sum_{k=0}^{\infty} a_k x^{k+r}$$

- Rewrite ODE with series expansions

- Convert $x^m \cdot y$ to series expansion for $m = 0..2$

$$x^m \cdot y = \sum_{k=0}^{\infty} a_k x^{k+r+m}$$

- Shift index using $k \rightarrow k - m$

$$x^m \cdot y = \sum_{k=m}^{\infty} a_{k-m} x^{k+r}$$

- Convert $x \cdot y'$ to series expansion

$$x \cdot y' = \sum_{k=0}^{\infty} a_k (k+r) x^{k+r}$$

- Convert $x^2 \cdot y''$ to series expansion

$$x^2 \cdot y'' = \sum_{k=0}^{\infty} a_k (k+r)(k+r-1) x^{k+r}$$

Rewrite ODE with series expansions

$$a_0(2+r)(-4+r)x^r + a_1(3+r)(-3+r)x^{1+r} + \left(\sum_{k=2}^{\infty} (a_k(k+r+2)(k+r-4) + 8a_{k-2}) x^{k+r} \right)$$

- a_0 cannot be 0 by assumption, giving the indicial equation

$$(2+r)(-4+r) = 0$$

- Values of r that satisfy the indicial equation

$$r \in \{-2, 4\}$$

- Each term must be 0

$$a_1(3+r)(-3+r) = 0$$

- Solve for the dependent coefficient(s)

$$a_1 = 0$$

- Each term in the series must be 0, giving the recursion relation

$$a_k(k+r+2)(k+r-4) + 8a_{k-2} = 0$$

- Shift index using $k \rightarrow k + 2$

$$a_{k+2}(k+4+r)(k-2+r) + 8a_k = 0$$

- Recursion relation that defines series solution to ODE

$$a_{k+2} = -\frac{8a_k}{(k+4+r)(k-2+r)}$$

- Recursion relation for $r = -2$

$$a_{k+2} = -\frac{8a_k}{(k+2)(k-4)}$$

- Series not valid for $r = -2$, division by 0 in the recursion relation at $k = 4$

$$a_{k+2} = -\frac{8a_k}{(k+2)(k-4)}$$

- Recursion relation for $r = 4$

$$a_{k+2} = -\frac{8a_k}{(k+8)(k+2)}$$

- Solution for $r = 4$

$$\left[y = \sum_{k=0}^{\infty} a_k x^{k+4}, a_{k+2} = -\frac{8a_k}{(k+8)(k+2)}, a_1 = 0 \right]$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
trying a symmetry of the form [xi=0, eta=F(x)]
checking if the LODE is missing y
-> Trying a Liouvillian solution using Kovacic's algorithm
<- No Liouvillian solutions exist
-> Trying a solution in terms of special functions:
    -> Bessel
    <- Bessel successful
<- special function solution successful`

```

✓ Solution by Maple

Time used: 0.031 (sec). Leaf size: 35

```

Order:=6;
dsolve(x^2*diff(y(x),x$2)-x*diff(y(x),x)+8*(x^2-1)*y(x)=0,y(x),type='series',x=0);

```

$$y(x) = c_1 x^4 \left(1 - \frac{1}{2} x^2 + \frac{1}{10} x^4 + O(x^6) \right) + \frac{c_2 (-86400 - 86400 x^2 - 86400 x^4 + O(x^6))}{x^2}$$

✓ Solution by Mathematica

Time used: 0.009 (sec). Leaf size: 36

```
AsymptoticDSolveValue[x^2*y''[x]-x*y'[x]+8*(x^2-1)*y[x]==0,y[x],{x,0,5}]
```

$$y(x) \rightarrow c_1 \left(x^2 + \frac{1}{x^2} + 1 \right) + c_2 \left(\frac{x^8}{10} - \frac{x^6}{2} + x^4 \right)$$

15.22 problem 22

15.22.1 Maple step by step solution 4313

Internal problem ID [11923]

Internal file name [OUTPUT/11932_Saturday_April_13_2024_10_26_32_PM_53853751/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.2 (Frobenius). Exercises page 251

Problem number: 22.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"second order series method. Regular singular point. Difference is integer"**

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$x^2y'' + x^2y' - \frac{3y}{4} = 0$$

With the expansion point for the power series method at $x = 0$.

The type of the expansion point is first determined. This is done on the homogeneous part of the ODE.

$$x^2y'' + x^2y' - \frac{3y}{4} = 0$$

The following is summary of singularities for the above ode. Writing the ode as

$$y'' + p(x)y' + q(x)y = 0$$

Where

$$p(x) = 1$$

$$q(x) = -\frac{3}{4x^2}$$

Table 569: Table $p(x), q(x)$ singularities.

$p(x) = 1$	
singularity	type

$q(x) = -\frac{3}{4x^2}$	
singularity	type
$x = 0$	“regular”

Combining everything together gives the following summary of singularities for the ode as

Regular singular points : $[0]$

Irregular singular points : $[\infty]$

Since $x = 0$ is regular singular point, then Frobenius power series is used. The ode is normalized to be

$$x^2 y'' + x^2 y' - \frac{3y}{4} = 0$$

Let the solution be represented as Frobenius power series of the form

$$y = \sum_{n=0}^{\infty} a_n x^{n+r}$$

Then

$$y' = \sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1}$$

$$y'' = \sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2}$$

Substituting the above back into the ode gives

$$\left(\sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2} \right) x^2 + x^2 \left(\sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1} \right) - \frac{3 \left(\sum_{n=0}^{\infty} a_n x^{n+r} \right)}{4} = 0 \quad (1)$$

Which simplifies to

$$\left(\sum_{n=0}^{\infty} x^{n+r} a_n (n+r)(n+r-1) \right) + \left(\sum_{n=0}^{\infty} x^{1+n+r} a_n (n+r) \right) + \sum_{n=0}^{\infty} \left(-\frac{3a_n x^{n+r}}{4} \right) = 0 \quad (2A)$$

The next step is to make all powers of x be $n + r$ in each summation term. Going over each summation term above with power of x in it which is not already x^{n+r} and adjusting the power and the corresponding index gives

$$\sum_{n=0}^{\infty} x^{1+n+r} a_n (n+r) = \sum_{n=1}^{\infty} a_{n-1} (n+r-1) x^{n+r}$$

Substituting all the above in Eq (2A) gives the following equation where now all powers of x are the same and equal to $n + r$.

$$\left(\sum_{n=0}^{\infty} x^{n+r} a_n (n+r) (n+r-1) \right) + \left(\sum_{n=1}^{\infty} a_{n-1} (n+r-1) x^{n+r} \right) + \sum_{n=0}^{\infty} \left(-\frac{3a_n x^{n+r}}{4} \right) = 0 \quad (2B)$$

The indicial equation is obtained from $n = 0$. From Eq (2B) this gives

$$x^{n+r} a_n (n+r) (n+r-1) - \frac{3a_n x^{n+r}}{4} = 0$$

When $n = 0$ the above becomes

$$x^r a_0 r (-1+r) - \frac{3a_0 x^r}{4} = 0$$

Or

$$\left(x^r r (-1+r) - \frac{3x^r}{4} \right) a_0 = 0$$

Since $a_0 \neq 0$ then the above simplifies to

$$\frac{(4r^2 - 4r - 3) x^r}{4} = 0$$

Since the above is true for all x then the indicial equation becomes

$$r^2 - r - \frac{3}{4} = 0$$

Solving for r gives the roots of the indicial equation as

$$r_1 = \frac{3}{2}$$

$$r_2 = -\frac{1}{2}$$

Since $a_0 \neq 0$ then the indicial equation becomes

$$\frac{(4r^2 - 4r - 3)x^r}{4} = 0$$

Solving for r gives the roots of the indicial equation as Since $r_1 - r_2 = 2$ is an integer, then we can construct two linearly independent solutions

$$y_1(x) = x^{r_1} \left(\sum_{n=0}^{\infty} a_n x^n \right)$$

$$y_2(x) = C y_1(x) \ln(x) + x^{r_2} \left(\sum_{n=0}^{\infty} b_n x^n \right)$$

Or

$$y_1(x) = x^{\frac{3}{2}} \left(\sum_{n=0}^{\infty} a_n x^n \right)$$

$$y_2(x) = C y_1(x) \ln(x) + \frac{\sum_{n=0}^{\infty} b_n x^n}{\sqrt{x}}$$

Or

$$y_1(x) = \sum_{n=0}^{\infty} a_n x^{n+\frac{3}{2}}$$

$$y_2(x) = C y_1(x) \ln(x) + \left(\sum_{n=0}^{\infty} b_n x^{n-\frac{1}{2}} \right)$$

Where C above can be zero. We start by finding y_1 . Eq (2B) derived above is now used to find all a_n coefficients. The case $n = 0$ is skipped since it was used to find the roots of the indicial equation. a_0 is arbitrary and taken as $a_0 = 1$. For $1 \leq n$ the recursive equation is

$$a_n(n+r)(n+r-1) + a_{n-1}(n+r-1) - \frac{3a_n}{4} = 0 \quad (3)$$

Solving for a_n from recursive equation (4) gives

$$a_n = -\frac{4a_{n-1}(n+r-1)}{4n^2 + 8nr + 4r^2 - 4n - 4r - 3} \quad (4)$$

Which for the root $r = \frac{3}{2}$ becomes

$$a_n = -\frac{a_{n-1}(2n+1)}{2n(n+2)} \quad (5)$$

At this point, it is a good idea to keep track of a_n in a table both before substituting $r = \frac{3}{2}$ and after as more terms are found using the above recursive equation.

n	$a_{n,r}$	a_n
a_0	1	1

For $n = 1$, using the above recursive equation gives

$$a_1 = -\frac{4r}{4r^2 + 4r - 3}$$

Which for the root $r = \frac{3}{2}$ becomes

$$a_1 = -\frac{1}{2}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$-\frac{4r}{4r^2+4r-3}$	$-\frac{1}{2}$

For $n = 2$, using the above recursive equation gives

$$a_2 = \frac{16r(1+r)}{(4r^2 + 4r - 3)(4r^2 + 12r + 5)}$$

Which for the root $r = \frac{3}{2}$ becomes

$$a_2 = \frac{5}{32}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$-\frac{4r}{4r^2+4r-3}$	$-\frac{1}{2}$
a_2	$\frac{16r(1+r)}{(4r^2+4r-3)(4r^2+12r+5)}$	$\frac{5}{32}$

For $n = 3$, using the above recursive equation gives

$$a_3 = -\frac{64r(1+r)(2+r)}{(4r^2 + 4r - 3)(4r^2 + 12r + 5)(4r^2 + 20r + 21)}$$

Which for the root $r = \frac{3}{2}$ becomes

$$a_3 = -\frac{7}{192}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$-\frac{4r}{4r^2+4r-3}$	$-\frac{1}{2}$
a_2	$\frac{16r(1+r)}{(4r^2+4r-3)(4r^2+12r+5)}$	$\frac{5}{32}$
a_3	$-\frac{64r(1+r)(2+r)}{(4r^2+4r-3)(4r^2+12r+5)(4r^2+20r+21)}$	$-\frac{7}{192}$

For $n = 4$, using the above recursive equation gives

$$a_4 = \frac{256r(1+r)(2+r)(3+r)}{(4r^2+4r-3)(4r^2+12r+5)(4r^2+20r+21)(4r^2+28r+45)}$$

Which for the root $r = \frac{3}{2}$ becomes

$$a_4 = \frac{7}{1024}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$-\frac{4r}{4r^2+4r-3}$	$-\frac{1}{2}$
a_2	$\frac{16r(1+r)}{(4r^2+4r-3)(4r^2+12r+5)}$	$\frac{5}{32}$
a_3	$-\frac{64r(1+r)(2+r)}{(4r^2+4r-3)(4r^2+12r+5)(4r^2+20r+21)}$	$-\frac{7}{192}$
a_4	$\frac{256r(1+r)(2+r)(3+r)}{(4r^2+4r-3)(4r^2+12r+5)(4r^2+20r+21)(4r^2+28r+45)}$	$\frac{7}{1024}$

For $n = 5$, using the above recursive equation gives

$$a_5 = -\frac{1024r(1+r)(2+r)(3+r)(4+r)}{(2r+9)(2r-1)(2r+11)(2r+3)^2(2r+1)(2r+7)^2(2r+5)^2}$$

Which for the root $r = \frac{3}{2}$ becomes

$$a_5 = -\frac{11}{10240}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$-\frac{4r}{4r^2+4r-3}$	$-\frac{1}{2}$
a_2	$\frac{16r(1+r)}{(4r^2+4r-3)(4r^2+12r+5)}$	$\frac{5}{32}$
a_3	$-\frac{64r(1+r)(2+r)}{(4r^2+4r-3)(4r^2+12r+5)(4r^2+20r+21)}$	$-\frac{7}{192}$
a_4	$\frac{256r(1+r)(2+r)(3+r)}{(4r^2+4r-3)(4r^2+12r+5)(4r^2+20r+21)(4r^2+28r+45)}$	$\frac{7}{1024}$
a_5	$-\frac{1024r(1+r)(2+r)(3+r)(4+r)}{(2r+9)(2r-1)(2r+11)(2r+3)^2(2r+1)(2r+7)^2(2r+5)^2}$	$-\frac{11}{10240}$

Using the above table, then the solution $y_1(x)$ is

$$\begin{aligned} y_1(x) &= x^{\frac{3}{2}} (a_0 + a_1x + a_2x^2 + a_3x^3 + a_4x^4 + a_5x^5 + a_6x^6 \dots) \\ &= x^{\frac{3}{2}} \left(1 - \frac{x}{2} + \frac{5x^2}{32} - \frac{7x^3}{192} + \frac{7x^4}{1024} - \frac{11x^5}{10240} + O(x^6) \right) \end{aligned}$$

Now the second solution $y_2(x)$ is found. Let

$$r_1 - r_2 = N$$

Where N is positive integer which is the difference between the two roots. r_1 is taken as the larger root. Hence for this problem we have $N = 2$. Now we need to determine if C is zero or not. This is done by finding $\lim_{r \rightarrow r_2} a_2(r)$. If this limit exists, then $C = 0$, else we need to keep the log term and $C \neq 0$. The above table shows that

$$\begin{aligned} a_N &= a_2 \\ &= \frac{16r(1+r)}{(4r^2+4r-3)(4r^2+12r+5)} \end{aligned}$$

Therefore

$$\begin{aligned} \lim_{r \rightarrow r_2} \frac{16r(1+r)}{(4r^2+4r-3)(4r^2+12r+5)} &= \lim_{r \rightarrow -\frac{1}{2}} \frac{16r(1+r)}{(4r^2+4r-3)(4r^2+12r+5)} \\ &= \text{undefined} \end{aligned}$$

Since the limit does not exist then the log term is needed. Therefore the second solution has the form

$$y_2(x) = Cy_1(x) \ln(x) + \left(\sum_{n=0}^{\infty} b_n x^{n+r_2} \right)$$

Therefore

$$\begin{aligned} \frac{d}{dx}y_2(x) &= Cy_1'(x) \ln(x) + \frac{Cy_1(x)}{x} + \left(\sum_{n=0}^{\infty} \frac{b_n x^{n+r_2}(n+r_2)}{x} \right) \\ &= Cy_1'(x) \ln(x) + \frac{Cy_1(x)}{x} + \left(\sum_{n=0}^{\infty} x^{-1+n+r_2} b_n(n+r_2) \right) \\ \frac{d^2}{dx^2}y_2(x) &= Cy_1''(x) \ln(x) + \frac{2Cy_1'(x)}{x} - \frac{Cy_1(x)}{x^2} \\ &\quad + \sum_{n=0}^{\infty} \left(\frac{b_n x^{n+r_2}(n+r_2)^2}{x^2} - \frac{b_n x^{n+r_2}(n+r_2)}{x^2} \right) \\ &= Cy_1''(x) \ln(x) + \frac{2Cy_1'(x)}{x} - \frac{Cy_1(x)}{x^2} + \left(\sum_{n=0}^{\infty} x^{-2+n+r_2} b_n(n+r_2)(-1+n+r_2) \right) \end{aligned}$$

Substituting these back into the given ode $x^2y'' + x^2y' - \frac{3y}{4} = 0$ gives

$$\begin{aligned} &\left(Cy_1''(x) \ln(x) + \frac{2Cy_1'(x)}{x} - \frac{Cy_1(x)}{x^2} \right. \\ &\quad \left. + \sum_{n=0}^{\infty} \left(\frac{b_n x^{n+r_2}(n+r_2)^2}{x^2} - \frac{b_n x^{n+r_2}(n+r_2)}{x^2} \right) \right) x^2 \\ &\quad + x^2 \left(Cy_1'(x) \ln(x) + \frac{Cy_1(x)}{x} + \left(\sum_{n=0}^{\infty} \frac{b_n x^{n+r_2}(n+r_2)}{x} \right) \right) \\ &\quad - \frac{3Cy_1(x) \ln(x)}{4} - \frac{3 \left(\sum_{n=0}^{\infty} b_n x^{n+r_2} \right)}{4} = 0 \end{aligned}$$

Which can be written as

$$\begin{aligned} &\left(\left(y_1''(x) x^2 + x^2 y_1'(x) - \frac{3y_1(x)}{4} \right) \ln(x) + \left(\frac{2y_1'(x)}{x} - \frac{y_1(x)}{x^2} \right) x^2 + y_1(x) x \right) C \\ &\quad + \left(\sum_{n=0}^{\infty} \left(\frac{b_n x^{n+r_2}(n+r_2)^2}{x^2} - \frac{b_n x^{n+r_2}(n+r_2)}{x^2} \right) \right) x^2 \\ &\quad + x^2 \left(\sum_{n=0}^{\infty} \frac{b_n x^{n+r_2}(n+r_2)}{x} \right) - \frac{3 \left(\sum_{n=0}^{\infty} b_n x^{n+r_2} \right)}{4} = 0 \end{aligned} \tag{7}$$

But since $y_1(x)$ is a solution to the ode, then

$$y_1''(x)x^2 + x^2y_1'(x) - \frac{3y_1(x)}{4} = 0$$

Eq (7) simplifies to

$$\begin{aligned} & \left(\left(\frac{2y_1'(x)}{x} - \frac{y_1(x)}{x^2} \right) x^2 + y_1(x)x \right) C \\ & + \left(\sum_{n=0}^{\infty} \left(\frac{b_n x^{n+r_2}(n+r_2)^2}{x^2} - \frac{b_n x^{n+r_2}(n+r_2)}{x^2} \right) \right) x^2 \\ & + x^2 \left(\sum_{n=0}^{\infty} \frac{b_n x^{n+r_2}(n+r_2)}{x} \right) - \frac{3 \left(\sum_{n=0}^{\infty} b_n x^{n+r_2} \right)}{4} = 0 \end{aligned} \quad (8)$$

Substituting $y_1 = \sum_{n=0}^{\infty} a_n x^{n+r_1}$ into the above gives

$$\begin{aligned} & \left(2 \left(\sum_{n=0}^{\infty} x^{-1+n+r_1} a_n (n+r_1) \right) x + (x-1) \left(\sum_{n=0}^{\infty} a_n x^{n+r_1} \right) \right) C \\ & + \left(\sum_{n=0}^{\infty} x^{-2+n+r_2} b_n (n+r_2) (-1+n+r_2) \right) x^2 \\ & + x^2 \left(\sum_{n=0}^{\infty} x^{-1+n+r_2} b_n (n+r_2) \right) - \frac{3 \left(\sum_{n=0}^{\infty} b_n x^{n+r_2} \right)}{4} = 0 \end{aligned} \quad (9)$$

Since $r_1 = \frac{3}{2}$ and $r_2 = -\frac{1}{2}$ then the above becomes

$$\begin{aligned} & \left(2 \left(\sum_{n=0}^{\infty} x^{n+\frac{1}{2}} a_n \left(n + \frac{3}{2} \right) \right) x + (x-1) \left(\sum_{n=0}^{\infty} a_n x^{n+\frac{3}{2}} \right) \right) C \\ & + \left(\sum_{n=0}^{\infty} x^{-\frac{5}{2}+n} b_n \left(n - \frac{1}{2} \right) \left(-\frac{3}{2} + n \right) \right) x^2 \\ & + x^2 \left(\sum_{n=0}^{\infty} x^{-\frac{3}{2}+n} b_n \left(n - \frac{1}{2} \right) \right) - \frac{3 \left(\sum_{n=0}^{\infty} b_n x^{n-\frac{1}{2}} \right)}{4} = 0 \end{aligned} \quad (10)$$

Expanding $Cx^{\frac{5}{2}}$ as Taylor series around $x = 0$ and keeping only the first 6 terms gives

$$\begin{aligned} Cx^{\frac{5}{2}} &= Cx^{\frac{5}{2}} + \dots \\ &= Cx^{\frac{5}{2}} \end{aligned}$$

Expanding $-Cx^{\frac{3}{2}}$ as Taylor series around $x = 0$ and keeping only the first 6 terms gives

$$\begin{aligned} -Cx^{\frac{3}{2}} &= -Cx^{\frac{3}{2}} + \dots \\ &= -Cx^{\frac{3}{2}} \end{aligned}$$

Which simplifies to

$$\begin{aligned} &\left(\sum_{n=0}^{\infty} Cx^{n+\frac{3}{2}}a_n(2n+3) \right) + \left(\sum_{n=0}^{\infty} Cx^{n+\frac{5}{2}}a_n \right) \\ &+ \sum_{n=0}^{\infty} \left(-Cx^{n+\frac{3}{2}}a_n \right) + \left(\sum_{n=0}^{\infty} \frac{x^{n-\frac{1}{2}}b_n(4n^2-8n+3)}{4} \right) \\ &+ \left(\sum_{n=0}^{\infty} \frac{x^{n+\frac{1}{2}}b_n(2n-1)}{2} \right) + \sum_{n=0}^{\infty} \left(-\frac{3b_nx^{n-\frac{1}{2}}}{4} \right) = 0 \end{aligned} \quad (2A)$$

The next step is to make all powers of x be $n - \frac{1}{2}$ in each summation term. Going over each summation term above with power of x in it which is not already $x^{n-\frac{1}{2}}$ and adjusting the power and the corresponding index gives

$$\begin{aligned} \sum_{n=0}^{\infty} Cx^{n+\frac{3}{2}}a_n(2n+3) &= \sum_{n=2}^{\infty} Ca_{n-2}(2n-1)x^{n-\frac{1}{2}} \\ \sum_{n=0}^{\infty} Cx^{n+\frac{5}{2}}a_n &= \sum_{n=3}^{\infty} Ca_{n-3}x^{n-\frac{1}{2}} \\ \sum_{n=0}^{\infty} \left(-Cx^{n+\frac{3}{2}}a_n \right) &= \sum_{n=2}^{\infty} \left(-Ca_{n-2}x^{n-\frac{1}{2}} \right) \\ \sum_{n=0}^{\infty} \frac{x^{n+\frac{1}{2}}b_n(2n-1)}{2} &= \sum_{n=1}^{\infty} \frac{b_{n-1}(-3+2n)x^{n-\frac{1}{2}}}{2} \end{aligned}$$

Substituting all the above in Eq (2A) gives the following equation where now all powers of x are the same and equal to $n - \frac{1}{2}$.

$$\begin{aligned} & \left(\sum_{n=2}^{\infty} C a_{n-2} (2n-1) x^{n-\frac{1}{2}} \right) + \left(\sum_{n=3}^{\infty} C a_{n-3} x^{n-\frac{1}{2}} \right) \\ & + \sum_{n=2}^{\infty} \left(-C a_{n-2} x^{n-\frac{1}{2}} \right) + \left(\sum_{n=0}^{\infty} \frac{x^{n-\frac{1}{2}} b_n (4n^2 - 8n + 3)}{4} \right) \\ & + \left(\sum_{n=1}^{\infty} \frac{b_{n-1} (-3 + 2n) x^{n-\frac{1}{2}}}{2} \right) + \sum_{n=0}^{\infty} \left(-\frac{3b_n x^{n-\frac{1}{2}}}{4} \right) = 0 \end{aligned} \quad (2B)$$

For $n = 0$ in Eq. (2B), we choose arbitray value for b_0 as $b_0 = 1$. For $n = 1$, Eq (2B) gives

$$-b_1 - \frac{b_0}{2} = 0$$

Which when replacing the above values found already for b_n and the values found earlier for a_n and for C , gives

$$-b_1 - \frac{1}{2} = 0$$

Solving the above for b_1 gives

$$b_1 = -\frac{1}{2}$$

For $n = N$, where $N = 2$ which is the difference between the two roots, we are free to choose $b_2 = 0$. Hence for $n = 2$, Eq (2B) gives

$$2C - \frac{1}{4} = 0$$

Which is solved for C . Solving for C gives

$$C = \frac{1}{8}$$

For $n = 3$, Eq (2B) gives

$$(a_0 + 4a_1) C + \frac{3b_2}{2} + 3b_3 = 0$$

Which when replacing the above values found already for b_n and the values found earlier for a_n and for C , gives

$$-\frac{1}{8} + 3b_3 = 0$$

Solving the above for b_3 gives

$$b_3 = \frac{1}{24}$$

For $n = 4$, Eq (2B) gives

$$(a_1 + 6a_2)C + \frac{5b_3}{2} + 8b_4 = 0$$

Which when replacing the above values found already for b_n and the values found earlier for a_n and for C , gives

$$\frac{61}{384} + 8b_4 = 0$$

Solving the above for b_4 gives

$$b_4 = -\frac{61}{3072}$$

For $n = 5$, Eq (2B) gives

$$(a_2 + 8a_3)C + \frac{7b_4}{2} + 15b_5 = 0$$

Which when replacing the above values found already for b_n and the values found earlier for a_n and for C , gives

$$-\frac{177}{2048} + 15b_5 = 0$$

Solving the above for b_5 gives

$$b_5 = \frac{59}{10240}$$

Now that we found all b_n and C , we can calculate the second solution from

$$y_2(x) = Cy_1(x) \ln(x) + \left(\sum_{n=0}^{\infty} b_n x^{n+r_2} \right)$$

Using the above value found for $C = \frac{1}{8}$ and all b_n , then the second solution becomes

$$y_2(x) = \frac{1}{8} \left(x^{\frac{3}{2}} \left(1 - \frac{x}{2} + \frac{5x^2}{32} - \frac{7x^3}{192} + \frac{7x^4}{1024} - \frac{11x^5}{10240} + O(x^6) \right) \right) \ln(x) + \frac{1 - \frac{x}{2} + \frac{x^3}{24} - \frac{61x^4}{3072} + \frac{59x^5}{10240} + O(x^6)}{\sqrt{x}}$$

Therefore the homogeneous solution is

$$\begin{aligned} y_h(x) &= c_1 y_1(x) + c_2 y_2(x) \\ &= c_1 x^{\frac{3}{2}} \left(1 - \frac{x}{2} + \frac{5x^2}{32} - \frac{7x^3}{192} + \frac{7x^4}{1024} - \frac{11x^5}{10240} + O(x^6) \right) \\ &\quad + c_2 \left(\frac{1}{8} \left(x^{\frac{3}{2}} \left(1 - \frac{x}{2} + \frac{5x^2}{32} - \frac{7x^3}{192} + \frac{7x^4}{1024} - \frac{11x^5}{10240} + O(x^6) \right) \right) \ln(x) \right. \\ &\quad \left. + \frac{1 - \frac{x}{2} + \frac{x^3}{24} - \frac{61x^4}{3072} + \frac{59x^5}{10240} + O(x^6)}{\sqrt{x}} \right) \end{aligned}$$

Hence the final solution is

$$\begin{aligned}
 y &= y_h \\
 &= c_1 x^{\frac{3}{2}} \left(1 - \frac{x}{2} + \frac{5x^2}{32} - \frac{7x^3}{192} + \frac{7x^4}{1024} - \frac{11x^5}{10240} + O(x^6) \right) \\
 &\quad + c_2 \left(\frac{x^{\frac{3}{2}} \left(1 - \frac{x}{2} + \frac{5x^2}{32} - \frac{7x^3}{192} + \frac{7x^4}{1024} - \frac{11x^5}{10240} + O(x^6) \right) \ln(x)}{8} \right. \\
 &\quad \left. + \frac{1 - \frac{x}{2} + \frac{x^3}{24} - \frac{61x^4}{3072} + \frac{59x^5}{10240} + O(x^6)}{\sqrt{x}} \right)
 \end{aligned}$$

Summary

The solution(s) found are the following

$$\begin{aligned}
 y &= c_1 x^{\frac{3}{2}} \left(1 - \frac{x}{2} + \frac{5x^2}{32} - \frac{7x^3}{192} + \frac{7x^4}{1024} - \frac{11x^5}{10240} + O(x^6) \right) \\
 &\quad + c_2 \left(\frac{x^{\frac{3}{2}} \left(1 - \frac{x}{2} + \frac{5x^2}{32} - \frac{7x^3}{192} + \frac{7x^4}{1024} - \frac{11x^5}{10240} + O(x^6) \right) \ln(x)}{8} \right. \\
 &\quad \left. + \frac{1 - \frac{x}{2} + \frac{x^3}{24} - \frac{61x^4}{3072} + \frac{59x^5}{10240} + O(x^6)}{\sqrt{x}} \right) \tag{1}
 \end{aligned}$$

Verification of solutions

$$\begin{aligned}
 y &= c_1 x^{\frac{3}{2}} \left(1 - \frac{x}{2} + \frac{5x^2}{32} - \frac{7x^3}{192} + \frac{7x^4}{1024} - \frac{11x^5}{10240} + O(x^6) \right) \\
 &\quad + c_2 \left(\frac{x^{\frac{3}{2}} \left(1 - \frac{x}{2} + \frac{5x^2}{32} - \frac{7x^3}{192} + \frac{7x^4}{1024} - \frac{11x^5}{10240} + O(x^6) \right) \ln(x)}{8} \right. \\
 &\quad \left. + \frac{1 - \frac{x}{2} + \frac{x^3}{24} - \frac{61x^4}{3072} + \frac{59x^5}{10240} + O(x^6)}{\sqrt{x}} \right)
 \end{aligned}$$

Verified OK.

15.22.1 Maple step by step solution

Let's solve

$$y''x^2 + x^2y' - \frac{3y}{4} = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = -y' + \frac{3y}{4x^2}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + y' - \frac{3y}{4x^2} = 0$$

- Check to see if $x_0 = 0$ is a regular singular point

- Define functions

$$[P_2(x) = 1, P_3(x) = -\frac{3}{4x^2}]$$

- $x \cdot P_2(x)$ is analytic at $x = 0$

$$(x \cdot P_2(x)) \Big|_{x=0} = 0$$

- $x^2 \cdot P_3(x)$ is analytic at $x = 0$

$$(x^2 \cdot P_3(x)) \Big|_{x=0} = -\frac{3}{4}$$

- $x = 0$ is a regular singular point

Check to see if $x_0 = 0$ is a regular singular point

$$x_0 = 0$$

- Multiply by denominators

$$4x^2y' + 4y''x^2 - 3y = 0$$

- Assume series solution for y

$$y = \sum_{k=0}^{\infty} a_k x^{k+r}$$

- Rewrite ODE with series expansions

- Convert $x^2 \cdot y'$ to series expansion

$$x^2 \cdot y' = \sum_{k=0}^{\infty} a_k (k+r) x^{k+r+1}$$

- Shift index using $k \rightarrow k-1$

$$x^2 \cdot y' = \sum_{k=1}^{\infty} a_{k-1} (k-1+r) x^{k+r}$$

- Convert $x^2 \cdot y''$ to series expansion

$$x^2 \cdot y'' = \sum_{k=0}^{\infty} a_k (k+r) (k-1+r) x^{k+r}$$

Rewrite ODE with series expansions

$$a_0(1+2r)(-3+2r)x^r + \left(\sum_{k=1}^{\infty} (a_k(2k+2r+1)(2k+2r-3) + 4a_{k-1}(k-1+r)) x^{k+r} \right) = 0$$

- a_0 cannot be 0 by assumption, giving the indicial equation

$$(1+2r)(-3+2r) = 0$$

- Values of r that satisfy the indicial equation

$$r \in \left\{ -\frac{1}{2}, \frac{3}{2} \right\}$$

- Each term in the series must be 0, giving the recursion relation

$$4\left(k+r-\frac{3}{2}\right)\left(k+r+\frac{1}{2}\right)a_k + 4a_{k-1}(k-1+r) = 0$$

- Shift index using $k- > k+1$

$$4\left(k-\frac{1}{2}+r\right)\left(k+\frac{3}{2}+r\right)a_{k+1} + 4a_k(k+r) = 0$$

- Recursion relation that defines series solution to ODE

$$a_{k+1} = -\frac{4a_k(k+r)}{(2k-1+2r)(2k+3+2r)}$$

- Recursion relation for $r = -\frac{1}{2}$

$$a_{k+1} = -\frac{4a_k\left(k-\frac{1}{2}\right)}{(2k-2)(2k+2)}$$

- Series not valid for $r = -\frac{1}{2}$, division by 0 in the recursion relation at $k = 1$

$$a_{k+1} = -\frac{4a_k\left(k-\frac{1}{2}\right)}{(2k-2)(2k+2)}$$

- Recursion relation for $r = \frac{3}{2}$

$$a_{k+1} = -\frac{4a_k\left(k+\frac{3}{2}\right)}{(2k+2)(2k+6)}$$

- Solution for $r = \frac{3}{2}$

$$\left[y = \sum_{k=0}^{\infty} a_k x^{k+\frac{3}{2}}, a_{k+1} = -\frac{4a_k\left(k+\frac{3}{2}\right)}{(2k+2)(2k+6)} \right]$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
checking if the LODE is of Euler type  
trying a symmetry of the form [xi=0, eta=F(x)]  
checking if the LODE is missing y  
-> Trying a Liouvillian solution using Kovacic's algorithm  
<- No Liouvillian solutions exist  
-> Trying a solution in terms of special functions:  
  -> Bessel  
  <- Bessel successful  
<- special function solution successful`
```

✓ Solution by Maple

Time used: 0.031 (sec). Leaf size: 65

```
Order:=6;  
dsolve(x^2*diff(y(x),x$2)+x^2*diff(y(x),x)-3/4*y(x)=0,y(x),type='series',x=0);
```

$$y(x) = \frac{c_1 x^2 \left(1 - \frac{1}{2}x + \frac{5}{32}x^2 - \frac{7}{192}x^3 + \frac{7}{1024}x^4 - \frac{11}{10240}x^5 + O(x^6)\right) + c_2 \left(\ln(x) \left(-\frac{1}{4}x^2 + \frac{1}{8}x^3 - \frac{5}{128}x^4 + \frac{7}{768}x^5 + O(x^6)\right)\right)}{\sqrt{x}}$$

✓ Solution by Mathematica

Time used: 0.026 (sec). Leaf size: 103

```
AsymptoticDSolveValue[x^2*y''[x]+x^2*y'[x]-3/4*y[x]==0,y[x],{x,0,5}]
```

$$y(x) \rightarrow c_2 \left(\frac{7x^{11/2}}{1024} - \frac{7x^{9/2}}{192} + \frac{5x^{7/2}}{32} - \frac{x^{5/2}}{2} + x^{3/2} \right) + c_1 \left(\frac{1}{256} x^{3/2} (5x^2 - 16x + 32) \log(x) - \frac{91x^4 - 224x^3 + 192x^2 + 1536x - 3072}{3072\sqrt{x}} \right)$$

15.23 problem 23

15.23.1 Maple step by step solution 4324

Internal problem ID [11924]

Internal file name [OUTPUT/11933_Saturday_April_13_2024_10_26_33_PM_41898295/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.2 (Frobenius). Exercises page 251

Problem number: 23.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"second order series method. Regular singular point. Repeated root"**

Maple gives the following as the ode type

[[_Emden , _Fowler]]

$$xy'' + y' + 2y = 0$$

With the expansion point for the power series method at $x = 0$.

The type of the expansion point is first determined. This is done on the homogeneous part of the ODE.

$$xy'' + y' + 2y = 0$$

The following is summary of singularities for the above ode. Writing the ode as

$$y'' + p(x)y' + q(x)y = 0$$

Where

$$p(x) = \frac{1}{x}$$
$$q(x) = \frac{2}{x}$$

Table 571: Table $p(x), q(x)$ singularities.

$p(x) = \frac{1}{x}$	
singularity	type
$x = 0$	“regular”

$q(x) = \frac{2}{x}$	
singularity	type
$x = 0$	“regular”

Combining everything together gives the following summary of singularities for the ode as

Regular singular points : $[0]$

Irregular singular points : $[\infty]$

Since $x = 0$ is regular singular point, then Frobenius power series is used. The ode is normalized to be

$$xy'' + y' + 2y = 0$$

Let the solution be represented as Frobenius power series of the form

$$y = \sum_{n=0}^{\infty} a_n x^{n+r}$$

Then

$$y' = \sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1}$$

$$y'' = \sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2}$$

Substituting the above back into the ode gives

$$\left(\sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2} \right) x + \left(\sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1} \right) + 2 \left(\sum_{n=0}^{\infty} a_n x^{n+r} \right) = 0 \quad (1)$$

Which simplifies to

$$\left(\sum_{n=0}^{\infty} x^{n+r-1} a_n (n+r)(n+r-1) \right) + \left(\sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1} \right) + \left(\sum_{n=0}^{\infty} 2a_n x^{n+r} \right) = 0 \quad (2A)$$

The next step is to make all powers of x be $n + r - 1$ in each summation term. Going over each summation term above with power of x in it which is not already x^{n+r-1} and adjusting the power and the corresponding index gives

$$\sum_{n=0}^{\infty} 2a_n x^{n+r} = \sum_{n=1}^{\infty} 2a_{n-1} x^{n+r-1}$$

Substituting all the above in Eq (2A) gives the following equation where now all powers of x are the same and equal to $n + r - 1$.

$$\left(\sum_{n=0}^{\infty} x^{n+r-1} a_n (n+r) (n+r-1) \right) + \left(\sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1} \right) + \left(\sum_{n=1}^{\infty} 2a_{n-1} x^{n+r-1} \right) = 0 \quad (2B)$$

The indicial equation is obtained from $n = 0$. From Eq (2B) this gives

$$x^{n+r-1} a_n (n+r) (n+r-1) + (n+r) a_n x^{n+r-1} = 0$$

When $n = 0$ the above becomes

$$x^{-1+r} a_0 r (-1+r) + r a_0 x^{-1+r} = 0$$

Or

$$(x^{-1+r} r (-1+r) + r x^{-1+r}) a_0 = 0$$

Since $a_0 \neq 0$ then the above simplifies to

$$x^{-1+r} r^2 = 0$$

Since the above is true for all x then the indicial equation becomes

$$r^2 = 0$$

Solving for r gives the roots of the indicial equation as

$$r_1 = 0$$

$$r_2 = 0$$

Since $a_0 \neq 0$ then the indicial equation becomes

$$x^{-1+r} r^2 = 0$$

Solving for r gives the roots of the indicial equation as Since the root of the indicial equation is repeated, then we can construct two linearly independent solutions. The first solution has the form

$$y_1(x) = \sum_{n=0}^{\infty} a_n x^{n+r} \quad (1A)$$

Now the second solution y_2 is found using

$$y_2(x) = y_1(x) \ln(x) + \left(\sum_{n=1}^{\infty} b_n x^{n+r} \right) \quad (1B)$$

Then the general solution will be

$$y = c_1 y_1(x) + c_2 y_2(x)$$

In Eq (1B) the sum starts from 1 and not zero. In Eq (1A), a_0 is never zero, and is arbitrary and is typically taken as $a_0 = 1$, and $\{c_1, c_2\}$ are two arbitrary constants of integration which can be found from initial conditions. We start by finding the first solution $y_1(x)$. Eq (2B) derived above is now used to find all a_n coefficients. The case $n = 0$ is skipped since it was used to find the roots of the indicial equation. a_0 is arbitrary and taken as $a_0 = 1$. For $1 \leq n$ the recursive equation is

$$a_n(n+r)(n+r-1) + a_n(n+r) + 2a_{n-1} = 0 \quad (3)$$

Solving for a_n from recursive equation (4) gives

$$a_n = -\frac{2a_{n-1}}{n^2 + 2nr + r^2} \quad (4)$$

Which for the root $r = 0$ becomes

$$a_n = -\frac{2a_{n-1}}{n^2} \quad (5)$$

At this point, it is a good idea to keep track of a_n in a table both before substituting $r = 0$ and after as more terms are found using the above recursive equation.

n	$a_{n,r}$	a_n
a_0	1	1

For $n = 1$, using the above recursive equation gives

$$a_1 = -\frac{2}{(r+1)^2}$$

Which for the root $r = 0$ becomes

$$a_1 = -2$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$-\frac{2}{(r+1)^2}$	-2

For $n = 2$, using the above recursive equation gives

$$a_2 = \frac{4}{(r+1)^2(r+2)^2}$$

Which for the root $r = 0$ becomes

$$a_2 = 1$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$-\frac{2}{(r+1)^2}$	-2
a_2	$\frac{4}{(r+1)^2(r+2)^2}$	1

For $n = 3$, using the above recursive equation gives

$$a_3 = -\frac{8}{(r+1)^2(r+2)^2(r+3)^2}$$

Which for the root $r = 0$ becomes

$$a_3 = -\frac{2}{9}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$-\frac{2}{(r+1)^2}$	-2
a_2	$\frac{4}{(r+1)^2(r+2)^2}$	1
a_3	$-\frac{8}{(r+1)^2(r+2)^2(r+3)^2}$	$-\frac{2}{9}$

For $n = 4$, using the above recursive equation gives

$$a_4 = \frac{16}{(r+1)^2 (r+2)^2 (r+3)^2 (r+4)^2}$$

Which for the root $r = 0$ becomes

$$a_4 = \frac{1}{36}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$-\frac{2}{(r+1)^2}$	-2
a_2	$\frac{4}{(r+1)^2(r+2)^2}$	1
a_3	$-\frac{8}{(r+1)^2(r+2)^2(r+3)^2}$	$-\frac{2}{9}$
a_4	$\frac{16}{(r+1)^2(r+2)^2(r+3)^2(r+4)^2}$	$\frac{1}{36}$

For $n = 5$, using the above recursive equation gives

$$a_5 = -\frac{32}{(r+1)^2 (r+2)^2 (r+3)^2 (r+4)^2 (r+5)^2}$$

Which for the root $r = 0$ becomes

$$a_5 = -\frac{1}{450}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$-\frac{2}{(r+1)^2}$	-2
a_2	$\frac{4}{(r+1)^2(r+2)^2}$	1
a_3	$-\frac{8}{(r+1)^2(r+2)^2(r+3)^2}$	$-\frac{2}{9}$
a_4	$\frac{16}{(r+1)^2(r+2)^2(r+3)^2(r+4)^2}$	$\frac{1}{36}$
a_5	$-\frac{32}{(r+1)^2(r+2)^2(r+3)^2(r+4)^2(r+5)^2}$	$-\frac{1}{450}$

Using the above table, then the first solution $y_1(x)$ becomes

$$\begin{aligned} y_1(x) &= a_0 + a_1x + a_2x^2 + a_3x^3 + a_4x^4 + a_5x^5 + a_6x^6 \dots \\ &= x^2 - 2x + 1 - \frac{2x^3}{9} + \frac{x^4}{36} - \frac{x^5}{450} + O(x^6) \end{aligned}$$

Now the second solution is found. The second solution is given by

$$y_2(x) = y_1(x) \ln(x) + \left(\sum_{n=1}^{\infty} b_n x^{n+r} \right)$$

Where b_n is found using

$$b_n = \frac{d}{dr} a_{n,r}$$

And the above is then evaluated at $r = 0$. The above table for $a_{n,r}$ is used for this purpose. Computing the derivatives gives the following table

n	$b_{n,r}$	a_n	$b_{n,r} = \frac{d}{dr} a_{n,r}$	$b_n(r = 0)$
b_0	1	1	N/A since b_n starts from 1	N/A
b_1	$-\frac{2}{(r+1)^2}$	-2	$\frac{4}{(r+1)^3}$	4
b_2	$\frac{4}{(r+1)^2(r+2)^2}$	1	$\frac{-16r-24}{(r+1)^3(r+2)^3}$	-3
b_3	$-\frac{8}{(r+1)^2(r+2)^2(r+3)^2}$	$-\frac{2}{9}$	$\frac{48r^2+192r+176}{(r+1)^3(r+2)^3(r+3)^3}$	$\frac{22}{27}$
b_4	$\frac{16}{(r+1)^2(r+2)^2(r+3)^2(r+4)^2}$	$\frac{1}{36}$	$-\frac{64(2r^3+15r^2+35r+25)}{(r+1)^3(r+2)^3(r+3)^3(r+4)^3}$	$-\frac{25}{216}$
b_5	$-\frac{32}{(r+1)^2(r+2)^2(r+3)^2(r+4)^2(r+5)^2}$	$-\frac{1}{450}$	$\frac{320r^4+3840r^3+16320r^2+28800r+17536}{(r+1)^3(r+2)^3(r+3)^3(r+4)^3(r+5)^3}$	$\frac{137}{13500}$

The above table gives all values of b_n needed. Hence the second solution is

$$\begin{aligned} y_2(x) &= y_1(x) \ln(x) + b_0 + b_1x + b_2x^2 + b_3x^3 + b_4x^4 + b_5x^5 + b_6x^6 \dots \\ &= \left(x^2 - 2x + 1 - \frac{2x^3}{9} + \frac{x^4}{36} - \frac{x^5}{450} + O(x^6) \right) \ln(x) - 3x^2 + 4x + \frac{22x^3}{27} - \frac{25x^4}{216} + \frac{137x^5}{13500} \\ &\quad + O(x^6) \end{aligned}$$

Therefore the homogeneous solution is

$$\begin{aligned}
 y_h(x) &= c_1 y_1(x) + c_2 y_2(x) \\
 &= c_1 \left(x^2 - 2x + 1 - \frac{2x^3}{9} + \frac{x^4}{36} - \frac{x^5}{450} + O(x^6) \right) \\
 &\quad + c_2 \left(\left(x^2 - 2x + 1 - \frac{2x^3}{9} + \frac{x^4}{36} - \frac{x^5}{450} + O(x^6) \right) \ln(x) - 3x^2 + 4x + \frac{22x^3}{27} \right. \\
 &\qquad \qquad \qquad \left. - \frac{25x^4}{216} + \frac{137x^5}{13500} + O(x^6) \right)
 \end{aligned}$$

Hence the final solution is

$$\begin{aligned}
 y &= y_h \\
 &= c_1 \left(x^2 - 2x + 1 - \frac{2x^3}{9} + \frac{x^4}{36} - \frac{x^5}{450} + O(x^6) \right) \\
 &\quad + c_2 \left(\left(x^2 - 2x + 1 - \frac{2x^3}{9} + \frac{x^4}{36} - \frac{x^5}{450} + O(x^6) \right) \ln(x) - 3x^2 + 4x + \frac{22x^3}{27} - \frac{25x^4}{216} \right. \\
 &\qquad \qquad \qquad \left. + \frac{137x^5}{13500} + O(x^6) \right)
 \end{aligned}$$

Summary

The solution(s) found are the following

$$\begin{aligned}
 y &= c_1 \left(x^2 - 2x + 1 - \frac{2x^3}{9} + \frac{x^4}{36} - \frac{x^5}{450} + O(x^6) \right) \\
 &\quad + c_2 \left(\left(x^2 - 2x + 1 - \frac{2x^3}{9} + \frac{x^4}{36} - \frac{x^5}{450} + O(x^6) \right) \ln(x) - 3x^2 + 4x + \frac{22x^3}{27} \right. \\
 &\qquad \qquad \qquad \left. - \frac{25x^4}{216} + \frac{137x^5}{13500} + O(x^6) \right) \quad (1)
 \end{aligned}$$

Verification of solutions

$$\begin{aligned}
 y &= c_1 \left(x^2 - 2x + 1 - \frac{2x^3}{9} + \frac{x^4}{36} - \frac{x^5}{450} + O(x^6) \right) \\
 &\quad + c_2 \left(\left(x^2 - 2x + 1 - \frac{2x^3}{9} + \frac{x^4}{36} - \frac{x^5}{450} + O(x^6) \right) \ln(x) - 3x^2 + 4x + \frac{22x^3}{27} - \frac{25x^4}{216} \right. \\
 &\qquad \qquad \qquad \left. + \frac{137x^5}{13500} + O(x^6) \right)
 \end{aligned}$$

Verified OK.

15.23.1 Maple step by step solution

Let's solve

$$y''x + y' + 2y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = -\frac{2y}{x} - \frac{y'}{x}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + \frac{y'}{x} + \frac{2y}{x} = 0$$

- Check to see if $x_0 = 0$ is a regular singular point

- Define functions

$$[P_2(x) = \frac{1}{x}, P_3(x) = \frac{2}{x}]$$

- $x \cdot P_2(x)$ is analytic at $x = 0$

$$(x \cdot P_2(x)) \Big|_{x=0} = 1$$

- $x^2 \cdot P_3(x)$ is analytic at $x = 0$

$$(x^2 \cdot P_3(x)) \Big|_{x=0} = 0$$

- $x = 0$ is a regular singular point

Check to see if $x_0 = 0$ is a regular singular point

$$x_0 = 0$$

- Multiply by denominators

$$y''x + y' + 2y = 0$$

- Assume series solution for y

$$y = \sum_{k=0}^{\infty} a_k x^{k+r}$$

- Rewrite ODE with series expansions

- Convert y' to series expansion

$$y' = \sum_{k=0}^{\infty} a_k (k+r) x^{k+r-1}$$

- Shift index using $k \rightarrow k+1$

$$y' = \sum_{k=-1}^{\infty} a_{k+1}(k+1+r)x^{k+r}$$

- Convert $x \cdot y''$ to series expansion

$$x \cdot y'' = \sum_{k=0}^{\infty} a_k(k+r)(k+r-1)x^{k+r-1}$$

- Shift index using $k- > k+1$

$$x \cdot y'' = \sum_{k=-1}^{\infty} a_{k+1}(k+1+r)(k+r)x^{k+r}$$

Rewrite ODE with series expansions

$$a_0 r^2 x^{-1+r} + \left(\sum_{k=0}^{\infty} (a_{k+1}(k+1+r)^2 + 2a_k) x^{k+r} \right) = 0$$

- a_0 cannot be 0 by assumption, giving the indicial equation

$$r^2 = 0$$

- Values of r that satisfy the indicial equation

$$r = 0$$

- Each term in the series must be 0, giving the recursion relation

$$a_{k+1}(k+1)^2 + 2a_k = 0$$

- Recursion relation that defines series solution to ODE

$$a_{k+1} = -\frac{2a_k}{(k+1)^2}$$

- Recursion relation for $r = 0$

$$a_{k+1} = -\frac{2a_k}{(k+1)^2}$$

- Solution for $r = 0$

$$\left[y = \sum_{k=0}^{\infty} a_k x^k, a_{k+1} = -\frac{2a_k}{(k+1)^2} \right]$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
checking if the LODE is of Euler type  
trying a symmetry of the form [xi=0, eta=F(x)]  
checking if the LODE is missing y  
-> Trying a Liouvillian solution using Kovacic's algorithm  
<- No Liouvillian solutions exist  
-> Trying a solution in terms of special functions:  
  -> Bessel  
  <- Bessel successful  
<- special function solution successful`
```

✓ Solution by Maple

Time used: 0.032 (sec). Leaf size: 59

```
Order:=6;  
dsolve(x*difff(y(x),x$2)+difff(y(x),x)+2*y(x)=0,y(x),type='series',x=0);
```

$$y(x) = (c_1 + c_2 \ln(x)) \left(1 - 2x + x^2 - \frac{2}{9}x^3 + \frac{1}{36}x^4 - \frac{1}{450}x^5 + O(x^6) \right) \\ + \left(4x - 3x^2 + \frac{22}{27}x^3 - \frac{25}{216}x^4 + \frac{137}{13500}x^5 + O(x^6) \right) c_2$$

✓ Solution by Mathematica

Time used: 0.003 (sec). Leaf size: 101

```
AsymptoticDSolveValue[x*y''[x]+y'[x]+2*y[x]==0,y[x],{x,0,5}]
```

$$y(x) \rightarrow c_1 \left(-\frac{x^5}{450} + \frac{x^4}{36} - \frac{2x^3}{9} + x^2 - 2x + 1 \right) \\ + c_2 \left(\frac{137x^5}{13500} - \frac{25x^4}{216} + \frac{22x^3}{27} - 3x^2 + \left(-\frac{x^5}{450} + \frac{x^4}{36} - \frac{2x^3}{9} + x^2 - 2x + 1 \right) \log(x) + 4x \right)$$

15.24 problem 24

15.24.1 Maple step by step solution 4339

Internal problem ID [11925]

Internal file name [OUTPUT/11934_Saturday_April_13_2024_10_26_34_PM_44280382/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.2 (Frobenius). Exercises page 251

Problem number: 24.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"second order series method. Regular singular point. Difference is integer"**

Maple gives the following as the ode type

```
[[_Emden , _Fowler]]
```

$$2xy'' + 6y' + y = 0$$

With the expansion point for the power series method at $x = 0$.

The type of the expansion point is first determined. This is done on the homogeneous part of the ODE.

$$2xy'' + 6y' + y = 0$$

The following is summary of singularities for the above ode. Writing the ode as

$$y'' + p(x)y' + q(x)y = 0$$

Where

$$p(x) = \frac{3}{x}$$
$$q(x) = \frac{1}{2x}$$

Table 573: Table $p(x), q(x)$ singularities.

$p(x) = \frac{3}{x}$	
singularity	type
$x = 0$	“regular”

$q(x) = \frac{1}{2x}$	
singularity	type
$x = 0$	“regular”

Combining everything together gives the following summary of singularities for the ode as

Regular singular points : $[0]$

Irregular singular points : $[\infty]$

Since $x = 0$ is regular singular point, then Frobenius power series is used. The ode is normalized to be

$$2xy'' + 6y' + y = 0$$

Let the solution be represented as Frobenius power series of the form

$$y = \sum_{n=0}^{\infty} a_n x^{n+r}$$

Then

$$y' = \sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1}$$

$$y'' = \sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2}$$

Substituting the above back into the ode gives

$$2 \left(\sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2} \right) x + 6 \left(\sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1} \right) + \left(\sum_{n=0}^{\infty} a_n x^{n+r} \right) = 0 \quad (1)$$

Which simplifies to

$$\left(\sum_{n=0}^{\infty} 2x^{n+r-1} a_n (n+r)(n+r-1) \right) + \left(\sum_{n=0}^{\infty} 6(n+r) a_n x^{n+r-1} \right) + \left(\sum_{n=0}^{\infty} a_n x^{n+r} \right) = 0 \quad (2A)$$

The next step is to make all powers of x be $n + r - 1$ in each summation term. Going over each summation term above with power of x in it which is not already x^{n+r-1} and adjusting the power and the corresponding index gives

$$\sum_{n=0}^{\infty} a_n x^{n+r} = \sum_{n=1}^{\infty} a_{n-1} x^{n+r-1}$$

Substituting all the above in Eq (2A) gives the following equation where now all powers of x are the same and equal to $n + r - 1$.

$$\left(\sum_{n=0}^{\infty} 2x^{n+r-1} a_n (n+r) (n+r-1) \right) + \left(\sum_{n=0}^{\infty} 6(n+r) a_n x^{n+r-1} \right) + \left(\sum_{n=1}^{\infty} a_{n-1} x^{n+r-1} \right) = 0 \quad (2B)$$

The indicial equation is obtained from $n = 0$. From Eq (2B) this gives

$$2x^{n+r-1} a_n (n+r) (n+r-1) + 6(n+r) a_n x^{n+r-1} = 0$$

When $n = 0$ the above becomes

$$2x^{-1+r} a_0 r(-1+r) + 6r a_0 x^{-1+r} = 0$$

Or

$$(2x^{-1+r} r(-1+r) + 6r x^{-1+r}) a_0 = 0$$

Since $a_0 \neq 0$ then the above simplifies to

$$2r x^{-1+r} (2+r) = 0$$

Since the above is true for all x then the indicial equation becomes

$$2r(2+r) = 0$$

Solving for r gives the roots of the indicial equation as

$$r_1 = 0$$

$$r_2 = -2$$

Since $a_0 \neq 0$ then the indicial equation becomes

$$2r x^{-1+r} (2+r) = 0$$

Solving for r gives the roots of the indicial equation as Since $r_1 - r_2 = 2$ is an integer, then we can construct two linearly independent solutions

$$y_1(x) = x^{r_1} \left(\sum_{n=0}^{\infty} a_n x^n \right)$$

$$y_2(x) = C y_1(x) \ln(x) + x^{r_2} \left(\sum_{n=0}^{\infty} b_n x^n \right)$$

Or

$$y_1(x) = \sum_{n=0}^{\infty} a_n x^n$$

$$y_2(x) = C y_1(x) \ln(x) + \frac{\sum_{n=0}^{\infty} b_n x^n}{x^2}$$

Or

$$y_1(x) = \sum_{n=0}^{\infty} a_n x^n$$

$$y_2(x) = C y_1(x) \ln(x) + \left(\sum_{n=0}^{\infty} b_n x^{n-2} \right)$$

Where C above can be zero. We start by finding y_1 . Eq (2B) derived above is now used to find all a_n coefficients. The case $n = 0$ is skipped since it was used to find the roots of the indicial equation. a_0 is arbitrary and taken as $a_0 = 1$. For $1 \leq n$ the recursive equation is

$$2a_n(n+r)(n+r-1) + 6a_n(n+r) + a_{n-1} = 0 \quad (3)$$

Solving for a_n from recursive equation (4) gives

$$a_n = -\frac{a_{n-1}}{2(n^2 + 2nr + r^2 + 2n + 2r)} \quad (4)$$

Which for the root $r = 0$ becomes

$$a_n = -\frac{a_{n-1}}{2n(n+2)} \quad (5)$$

At this point, it is a good idea to keep track of a_n in a table both before substituting $r = 0$ and after as more terms are found using the above recursive equation.

n	$a_{n,r}$	a_n
a_0	1	1

For $n = 1$, using the above recursive equation gives

$$a_1 = -\frac{1}{2r^2 + 8r + 6}$$

Which for the root $r = 0$ becomes

$$a_1 = -\frac{1}{6}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$-\frac{1}{2r^2+8r+6}$	$-\frac{1}{6}$

For $n = 2$, using the above recursive equation gives

$$a_2 = \frac{1}{4r^4 + 40r^3 + 140r^2 + 200r + 96}$$

Which for the root $r = 0$ becomes

$$a_2 = \frac{1}{96}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$-\frac{1}{2r^2+8r+6}$	$-\frac{1}{6}$
a_2	$\frac{1}{4r^4+40r^3+140r^2+200r+96}$	$\frac{1}{96}$

For $n = 3$, using the above recursive equation gives

$$a_3 = -\frac{1}{8(r+3)^2(r+1)(r+4)(2+r)(r+5)}$$

Which for the root $r = 0$ becomes

$$a_3 = -\frac{1}{2880}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$-\frac{1}{2r^2+8r+6}$	$-\frac{1}{6}$
a_2	$\frac{1}{4r^4+40r^3+140r^2+200r+96}$	$\frac{1}{96}$
a_3	$-\frac{1}{8(r+3)^2(r+1)(r+4)(2+r)(r+5)}$	$-\frac{1}{2880}$

For $n = 4$, using the above recursive equation gives

$$a_4 = \frac{1}{16(r+3)^2(r+1)(r+4)^2(2+r)(r+5)(r+6)}$$

Which for the root $r = 0$ becomes

$$a_4 = \frac{1}{138240}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$-\frac{1}{2r^2+8r+6}$	$-\frac{1}{6}$
a_2	$\frac{1}{4r^4+40r^3+140r^2+200r+96}$	$\frac{1}{96}$
a_3	$-\frac{1}{8(r+3)^2(r+1)(r+4)(2+r)(r+5)}$	$-\frac{1}{2880}$
a_4	$\frac{1}{16(r+3)^2(r+1)(r+4)^2(2+r)(r+5)(r+6)}$	$\frac{1}{138240}$

For $n = 5$, using the above recursive equation gives

$$a_5 = -\frac{1}{32(r+3)^2(r+1)(r+4)^2(2+r)(r+5)^2(r+6)(r+7)}$$

Which for the root $r = 0$ becomes

$$a_5 = -\frac{1}{9676800}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	$-\frac{1}{2r^2+8r+6}$	$-\frac{1}{6}$
a_2	$\frac{1}{4r^4+40r^3+140r^2+200r+96}$	$\frac{1}{96}$
a_3	$-\frac{1}{8(r+3)^2(r+1)(r+4)(2+r)(r+5)}$	$-\frac{1}{2880}$
a_4	$\frac{1}{16(r+3)^2(r+1)(r+4)^2(2+r)(r+5)(r+6)}$	$\frac{1}{138240}$
a_5	$-\frac{1}{32(r+3)^2(r+1)(r+4)^2(2+r)(r+5)^2(r+6)(r+7)}$	$-\frac{1}{9676800}$

Using the above table, then the solution $y_1(x)$ is

$$\begin{aligned}
 y_1(x) &= a_0 + a_1x + a_2x^2 + a_3x^3 + a_4x^4 + a_5x^5 + a_6x^6 \dots \\
 &= 1 - \frac{x}{6} + \frac{x^2}{96} - \frac{x^3}{2880} + \frac{x^4}{138240} - \frac{x^5}{9676800} + O(x^6)
 \end{aligned}$$

Now the second solution $y_2(x)$ is found. Let

$$r_1 - r_2 = N$$

Where N is positive integer which is the difference between the two roots. r_1 is taken as the larger root. Hence for this problem we have $N = 2$. Now we need to determine if C is zero or not. This is done by finding $\lim_{r \rightarrow r_2} a_2(r)$. If this limit exists, then $C = 0$, else we need to keep the log term and $C \neq 0$. The above table shows that

$$\begin{aligned}
 a_N &= a_2 \\
 &= \frac{1}{4r^4 + 40r^3 + 140r^2 + 200r + 96}
 \end{aligned}$$

Therefore

$$\begin{aligned}
 \lim_{r \rightarrow r_2} \frac{1}{4r^4 + 40r^3 + 140r^2 + 200r + 96} &= \lim_{r \rightarrow -2} \frac{1}{4r^4 + 40r^3 + 140r^2 + 200r + 96} \\
 &= \text{undefined}
 \end{aligned}$$

Since the limit does not exist then the log term is needed. Therefore the second solution has the form

$$y_2(x) = Cy_1(x) \ln(x) + \left(\sum_{n=0}^{\infty} b_n x^{n+r_2} \right)$$

Therefore

$$\begin{aligned}
\frac{d}{dx}y_2(x) &= Cy_1'(x) \ln(x) + \frac{Cy_1(x)}{x} + \left(\sum_{n=0}^{\infty} \frac{b_n x^{n+r_2}(n+r_2)}{x} \right) \\
&= Cy_1'(x) \ln(x) + \frac{Cy_1(x)}{x} + \left(\sum_{n=0}^{\infty} x^{-1+n+r_2} b_n (n+r_2) \right) \\
\frac{d^2}{dx^2}y_2(x) &= Cy_1''(x) \ln(x) + \frac{2Cy_1'(x)}{x} - \frac{Cy_1(x)}{x^2} \\
&\quad + \sum_{n=0}^{\infty} \left(\frac{b_n x^{n+r_2}(n+r_2)^2}{x^2} - \frac{b_n x^{n+r_2}(n+r_2)}{x^2} \right) \\
&= Cy_1''(x) \ln(x) + \frac{2Cy_1'(x)}{x} - \frac{Cy_1(x)}{x^2} + \left(\sum_{n=0}^{\infty} x^{-2+n+r_2} b_n (n+r_2) (-1+n+r_2) \right)
\end{aligned}$$

Substituting these back into the given ode $2xy'' + 6y' + y = 0$ gives

$$\begin{aligned}
&2 \left(Cy_1''(x) \ln(x) + \frac{2Cy_1'(x)}{x} - \frac{Cy_1(x)}{x^2} \right. \\
&\quad \left. + \sum_{n=0}^{\infty} \left(\frac{b_n x^{n+r_2}(n+r_2)^2}{x^2} - \frac{b_n x^{n+r_2}(n+r_2)}{x^2} \right) \right) x + 6Cy_1'(x) \ln(x) \\
&\quad + \frac{6Cy_1(x)}{x} + 6 \left(\sum_{n=0}^{\infty} \frac{b_n x^{n+r_2}(n+r_2)}{x} \right) + Cy_1(x) \ln(x) + \left(\sum_{n=0}^{\infty} b_n x^{n+r_2} \right) = 0
\end{aligned}$$

Which can be written as

$$\begin{aligned}
&\left((2y_1''(x)x + y_1(x) + 6y_1'(x)) \ln(x) + 2 \left(\frac{2y_1'(x)}{x} - \frac{y_1(x)}{x^2} \right) x + \frac{6y_1(x)}{x} \right) C \\
&\quad + 2 \left(\sum_{n=0}^{\infty} \left(\frac{b_n x^{n+r_2}(n+r_2)^2}{x^2} - \frac{b_n x^{n+r_2}(n+r_2)}{x^2} \right) \right) x \\
&\quad + 6 \left(\sum_{n=0}^{\infty} \frac{b_n x^{n+r_2}(n+r_2)}{x} \right) + \left(\sum_{n=0}^{\infty} b_n x^{n+r_2} \right) = 0
\end{aligned} \tag{7}$$

But since $y_1(x)$ is a solution to the ode, then

$$2y_1''(x)x + y_1(x) + 6y_1'(x) = 0$$

Eq (7) simplifies to

$$\begin{aligned} & \left(2 \left(\frac{2y_1'(x)}{x} - \frac{y_1(x)}{x^2} \right) x + \frac{6y_1(x)}{x} \right) C \\ & + 2 \left(\sum_{n=0}^{\infty} \left(\frac{b_n x^{n+r_2} (n+r_2)^2}{x^2} - \frac{b_n x^{n+r_2} (n+r_2)}{x^2} \right) \right) x \\ & + 6 \left(\sum_{n=0}^{\infty} \frac{b_n x^{n+r_2} (n+r_2)}{x} \right) + \left(\sum_{n=0}^{\infty} b_n x^{n+r_2} \right) = 0 \end{aligned} \quad (8)$$

Substituting $y_1 = \sum_{n=0}^{\infty} a_n x^{n+r_1}$ into the above gives

$$\begin{aligned} & \frac{\left(4 \left(\sum_{n=0}^{\infty} x^{-1+n+r_1} a_n (n+r_1) \right) x + 4 \left(\sum_{n=0}^{\infty} a_n x^{n+r_1} \right) \right) C}{x} \\ & + \frac{2 \left(\sum_{n=0}^{\infty} x^{-2+n+r_2} b_n (n+r_2) (-1+n+r_2) \right) x^2 + \left(\sum_{n=0}^{\infty} b_n x^{n+r_2} \right) x + 6 \left(\sum_{n=0}^{\infty} x^{-1+n+r_2} b_n (n+r_2) \right) x}{x} \\ & = 0 \end{aligned} \quad (9)$$

Since $r_1 = 0$ and $r_2 = -2$ then the above becomes

$$\begin{aligned} & \frac{\left(4 \left(\sum_{n=0}^{\infty} x^{n-1} a_n n \right) x + 4 \left(\sum_{n=0}^{\infty} a_n x^n \right) \right) C}{x} \\ & + \frac{2 \left(\sum_{n=0}^{\infty} x^{-4+n} b_n (n-2) (-3+n) \right) x^2 + \left(\sum_{n=0}^{\infty} b_n x^{n-2} \right) x + 6 \left(\sum_{n=0}^{\infty} x^{-3+n} b_n (n-2) \right) x}{x} \\ & = 0 \end{aligned} \quad (10)$$

Which simplifies to

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} 4C x^{n-1} a_n n \right) + \left(\sum_{n=0}^{\infty} 4C x^{n-1} a_n \right) + \left(\sum_{n=0}^{\infty} 2x^{-3+n} b_n (n-2) (-3+n) \right) \\ & + \left(\sum_{n=0}^{\infty} b_n x^{n-2} \right) + \left(\sum_{n=0}^{\infty} 6x^{-3+n} b_n (n-2) \right) = 0 \end{aligned} \quad (2A)$$

The next step is to make all powers of x be $-3 + n$ in each summation term. Going over each summation term above with power of x in it which is not already x^{-3+n} and adjusting the power and the corresponding index gives

$$\begin{aligned}\sum_{n=0}^{\infty} 4C x^{n-1} a_n n &= \sum_{n=2}^{\infty} 4C(n-2) a_{n-2} x^{-3+n} \\ \sum_{n=0}^{\infty} 4C x^{n-1} a_n &= \sum_{n=2}^{\infty} 4C a_{n-2} x^{-3+n} \\ \sum_{n=0}^{\infty} b_n x^{n-2} &= \sum_{n=1}^{\infty} b_{n-1} x^{-3+n}\end{aligned}$$

Substituting all the above in Eq (2A) gives the following equation where now all powers of x are the same and equal to $-3 + n$.

$$\begin{aligned}&\left(\sum_{n=2}^{\infty} 4C(n-2) a_{n-2} x^{-3+n}\right) + \left(\sum_{n=2}^{\infty} 4C a_{n-2} x^{-3+n}\right) \\ &+ \left(\sum_{n=0}^{\infty} 2x^{-3+n} b_n (n-2) (-3+n)\right) \\ &+ \left(\sum_{n=1}^{\infty} b_{n-1} x^{-3+n}\right) + \left(\sum_{n=0}^{\infty} 6x^{-3+n} b_n (n-2)\right) = 0\end{aligned}\tag{2B}$$

For $n = 0$ in Eq. (2B), we choose arbitray value for b_0 as $b_0 = 1$. For $n = 1$, Eq (2B) gives

$$-2b_1 + b_0 = 0$$

Which when replacing the above values found already for b_n and the values found earlier for a_n and for C , gives

$$-2b_1 + 1 = 0$$

Solving the above for b_1 gives

$$b_1 = \frac{1}{2}$$

For $n = N$, where $N = 2$ which is the difference between the two roots, we are free to choose $b_2 = 0$. Hence for $n = 2$, Eq (2B) gives

$$4C + \frac{1}{2} = 0$$

Which is solved for C . Solving for C gives

$$C = -\frac{1}{8}$$

For $n = 3$, Eq (2B) gives

$$8Ca_1 + b_2 + 6b_3 = 0$$

Which when replacing the above values found already for b_n and the values found earlier for a_n and for C , gives

$$6b_3 + \frac{1}{6} = 0$$

Solving the above for b_3 gives

$$b_3 = -\frac{1}{36}$$

For $n = 4$, Eq (2B) gives

$$12Ca_2 + b_3 + 16b_4 = 0$$

Which when replacing the above values found already for b_n and the values found earlier for a_n and for C , gives

$$16b_4 - \frac{25}{576} = 0$$

Solving the above for b_4 gives

$$b_4 = \frac{25}{9216}$$

For $n = 5$, Eq (2B) gives

$$16Ca_3 + b_4 + 30b_5 = 0$$

Which when replacing the above values found already for b_n and the values found earlier for a_n and for C , gives

$$30b_5 + \frac{157}{46080} = 0$$

Solving the above for b_5 gives

$$b_5 = -\frac{157}{1382400}$$

Now that we found all b_n and C , we can calculate the second solution from

$$y_2(x) = Cy_1(x) \ln(x) + \left(\sum_{n=0}^{\infty} b_n x^{n+r_2} \right)$$

Using the above value found for $C = -\frac{1}{8}$ and all b_n , then the second solution becomes

$$y_2(x) = -\frac{1}{8} \left(1 - \frac{x}{6} + \frac{x^2}{96} - \frac{x^3}{2880} + \frac{x^4}{138240} - \frac{x^5}{9676800} + O(x^6) \right) \ln(x) \\ + \frac{1 + \frac{x}{2} - \frac{x^3}{36} + \frac{25x^4}{9216} - \frac{157x^5}{1382400} + O(x^6)}{x^2}$$

Therefore the homogeneous solution is

$$\begin{aligned}
 y_h(x) &= c_1 y_1(x) + c_2 y_2(x) \\
 &= c_1 \left(1 - \frac{x}{6} + \frac{x^2}{96} - \frac{x^3}{2880} + \frac{x^4}{138240} - \frac{x^5}{9676800} + O(x^6) \right) \\
 &\quad + c_2 \left(-\frac{1}{8} \left(1 - \frac{x}{6} + \frac{x^2}{96} - \frac{x^3}{2880} + \frac{x^4}{138240} - \frac{x^5}{9676800} + O(x^6) \right) \ln(x) \right. \\
 &\quad \left. + \frac{1 + \frac{x}{2} - \frac{x^3}{36} + \frac{25x^4}{9216} - \frac{157x^5}{1382400} + O(x^6)}{x^2} \right)
 \end{aligned}$$

Hence the final solution is

$$\begin{aligned}
 y &= y_h \\
 &= c_1 \left(1 - \frac{x}{6} + \frac{x^2}{96} - \frac{x^3}{2880} + \frac{x^4}{138240} - \frac{x^5}{9676800} + O(x^6) \right) \\
 &\quad + c_2 \left(\left(-\frac{1}{8} + \frac{x}{48} - \frac{x^2}{768} + \frac{x^3}{23040} - \frac{x^4}{1105920} + \frac{x^5}{77414400} - \frac{O(x^6)}{8} \right) \ln(x) \right. \\
 &\quad \left. + \frac{1 + \frac{x}{2} - \frac{x^3}{36} + \frac{25x^4}{9216} - \frac{157x^5}{1382400} + O(x^6)}{x^2} \right)
 \end{aligned}$$

Summary

The solution(s) found are the following

$$\begin{aligned}
 y &= c_1 \left(1 - \frac{x}{6} + \frac{x^2}{96} - \frac{x^3}{2880} + \frac{x^4}{138240} - \frac{x^5}{9676800} + O(x^6) \right) \\
 &\quad + c_2 \left(\left(-\frac{1}{8} + \frac{x}{48} - \frac{x^2}{768} + \frac{x^3}{23040} - \frac{x^4}{1105920} + \frac{x^5}{77414400} - \frac{O(x^6)}{8} \right) \ln(x) \right. \\
 &\quad \left. + \frac{1 + \frac{x}{2} - \frac{x^3}{36} + \frac{25x^4}{9216} - \frac{157x^5}{1382400} + O(x^6)}{x^2} \right) \quad (1)
 \end{aligned}$$

Verification of solutions

$$y = c_1 \left(1 - \frac{x}{6} + \frac{x^2}{96} - \frac{x^3}{2880} + \frac{x^4}{138240} - \frac{x^5}{9676800} + O(x^6) \right) \\ + c_2 \left(\left(-\frac{1}{8} + \frac{x}{48} - \frac{x^2}{768} + \frac{x^3}{23040} - \frac{x^4}{1105920} + \frac{x^5}{77414400} - \frac{O(x^6)}{8} \right) \ln(x) \right. \\ \left. + \frac{1 + \frac{x}{2} - \frac{x^3}{36} + \frac{25x^4}{9216} - \frac{157x^5}{1382400} + O(x^6)}{x^2} \right)$$

Verified OK.

15.24.1 Maple step by step solution

Let's solve

$$2y''x + 6y' + y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = -\frac{3y'}{x} - \frac{y}{2x}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' + \frac{3y'}{x} + \frac{y}{2x} = 0$$

- Check to see if $x_0 = 0$ is a regular singular point

- Define functions

$$[P_2(x) = \frac{3}{x}, P_3(x) = \frac{1}{2x}]$$

- $x \cdot P_2(x)$ is analytic at $x = 0$

$$(x \cdot P_2(x)) \Big|_{x=0} = 3$$

- $x^2 \cdot P_3(x)$ is analytic at $x = 0$

$$(x^2 \cdot P_3(x)) \Big|_{x=0} = 0$$

- $x = 0$ is a regular singular point

Check to see if $x_0 = 0$ is a regular singular point

$$x_0 = 0$$

- Multiply by denominators

$$2y''x + 6y' + y = 0$$

- Assume series solution for y

$$y = \sum_{k=0}^{\infty} a_k x^{k+r}$$

- Rewrite ODE with series expansions

- Convert y' to series expansion

$$y' = \sum_{k=0}^{\infty} a_k (k+r) x^{k+r-1}$$

- Shift index using $k- > k+1$

$$y' = \sum_{k=-1}^{\infty} a_{k+1} (k+1+r) x^{k+r}$$

- Convert $x \cdot y''$ to series expansion

$$x \cdot y'' = \sum_{k=0}^{\infty} a_k (k+r)(k+r-1) x^{k+r-1}$$

- Shift index using $k- > k+1$

$$x \cdot y'' = \sum_{k=-1}^{\infty} a_{k+1} (k+1+r)(k+r) x^{k+r}$$

Rewrite ODE with series expansions

$$2a_0 r(2+r) x^{-1+r} + \left(\sum_{k=0}^{\infty} (2a_{k+1} (k+1+r)(k+3+r) + a_k) x^{k+r} \right) = 0$$

- a_0 cannot be 0 by assumption, giving the indicial equation

$$2r(2+r) = 0$$

- Values of r that satisfy the indicial equation

$$r \in \{-2, 0\}$$

- Each term in the series must be 0, giving the recursion relation

$$2a_{k+1} (k+1+r)(k+3+r) + a_k = 0$$

- Recursion relation that defines series solution to ODE

$$a_{k+1} = -\frac{a_k}{2(k+1+r)(k+3+r)}$$

- Recursion relation for $r = -2$

$$a_{k+1} = -\frac{a_k}{2(k-1)(k+1)}$$

- Series not valid for $r = -2$, division by 0 in the recursion relation at $k = 1$

$$a_{k+1} = -\frac{a_k}{2(k-1)(k+1)}$$

- Recursion relation for $r = 0$

$$a_{k+1} = -\frac{a_k}{2(k+1)(k+3)}$$

- Solution for $r = 0$

$$\left[y = \sum_{k=0}^{\infty} a_k x^k, a_{k+1} = -\frac{a_k}{2(k+1)(k+3)} \right]$$

Maple trace

```

`Methods for second order ODEs:
--- Trying classification methods ---
trying a quadrature
checking if the LODE has constant coefficients
checking if the LODE is of Euler type
trying a symmetry of the form [xi=0, eta=F(x)]
checking if the LODE is missing y
-> Trying a Liouvillian solution using Kovacic's algorithm
<- No Liouvillian solutions exist
-> Trying a solution in terms of special functions:
    -> Bessel
    <- Bessel successful
<- special function solution successful`

```

✓ Solution by Maple

Time used: 0.031 (sec). Leaf size: 62

```

Order:=6;
dsolve(2*x*diff(y(x),x$2)+6*diff(y(x),x)+y(x)=0,y(x),type='series',x=0);

```

$$y(x) = \frac{c_1 \left(1 - \frac{1}{6}x + \frac{1}{96}x^2 - \frac{1}{2880}x^3 + \frac{1}{138240}x^4 - \frac{1}{9676800}x^5 + O(x^6) \right) x^2 + c_2 (\ln(x) \left(\frac{1}{4}x^2 - \frac{1}{24}x^3 + \frac{1}{384}x^4 - \frac{1}{11520}x^5 + O(x^6) \right))}{x^2}$$

✓ Solution by Mathematica

Time used: 0.018 (sec). Leaf size: 80

```
AsymptoticDSolveValue[2*x*y'[x]+6*y'[x]+y[x]==0,y[x],{x,0,5}]
```

$$y(x) \rightarrow c_2 \left(\frac{x^4}{138240} - \frac{x^3}{2880} + \frac{x^2}{96} - \frac{x}{6} + 1 \right) + c_1 \left(\frac{31x^4 - 352x^3 + 576x^2 + 4608x + 9216}{9216x^2} - \frac{1}{768} (x^2 - 16x + 96) \log(x) \right)$$

15.25 problem 25

15.25.1 Maple step by step solution 4350

Internal problem ID [11926]

Internal file name [OUTPUT/11935_Saturday_April_13_2024_10_26_35_PM_62176316/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.2 (Frobenius). Exercises page 251

Problem number: 25.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"second order series method. Regular singular point. Repeated root"**

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$x^2 y'' - y'x + (x^2 + 1)y = 0$$

With the expansion point for the power series method at $x = 0$.

The type of the expansion point is first determined. This is done on the homogeneous part of the ODE.

$$x^2 y'' - y'x + (x^2 + 1)y = 0$$

The following is summary of singularities for the above ode. Writing the ode as

$$y'' + p(x)y' + q(x)y = 0$$

Where

$$p(x) = -\frac{1}{x}$$
$$q(x) = \frac{x^2 + 1}{x^2}$$

Table 575: Table $p(x), q(x)$ singularities.

$p(x) = -\frac{1}{x}$	
singularity	type
$x = 0$	“regular”

$q(x) = \frac{x^2+1}{x^2}$	
singularity	type
$x = 0$	“regular”

Combining everything together gives the following summary of singularities for the ode as

Regular singular points : $[0]$

Irregular singular points : $[\infty]$

Since $x = 0$ is regular singular point, then Frobenius power series is used. The ode is normalized to be

$$x^2 y'' - y' x + (x^2 + 1) y = 0$$

Let the solution be represented as Frobenius power series of the form

$$y = \sum_{n=0}^{\infty} a_n x^{n+r}$$

Then

$$y' = \sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1}$$

$$y'' = \sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2}$$

Substituting the above back into the ode gives

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2} \right) x^2 \\ & - \left(\sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1} \right) x + (x^2 + 1) \left(\sum_{n=0}^{\infty} a_n x^{n+r} \right) = 0 \end{aligned} \tag{1}$$

Which simplifies to

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} x^{n+r} a_n (n+r) (n+r-1) \right) + \sum_{n=0}^{\infty} (-x^{n+r} a_n (n+r)) \\ & + \left(\sum_{n=0}^{\infty} x^{n+r+2} a_n \right) + \left(\sum_{n=0}^{\infty} a_n x^{n+r} \right) = 0 \end{aligned} \quad (2A)$$

The next step is to make all powers of x be $n+r$ in each summation term. Going over each summation term above with power of x in it which is not already x^{n+r} and adjusting the power and the corresponding index gives

$$\sum_{n=0}^{\infty} x^{n+r+2} a_n = \sum_{n=2}^{\infty} a_{n-2} x^{n+r}$$

Substituting all the above in Eq (2A) gives the following equation where now all powers of x are the same and equal to $n+r$.

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} x^{n+r} a_n (n+r) (n+r-1) \right) + \sum_{n=0}^{\infty} (-x^{n+r} a_n (n+r)) \\ & + \left(\sum_{n=2}^{\infty} a_{n-2} x^{n+r} \right) + \left(\sum_{n=0}^{\infty} a_n x^{n+r} \right) = 0 \end{aligned} \quad (2B)$$

The indicial equation is obtained from $n=0$. From Eq (2B) this gives

$$x^{n+r} a_n (n+r) (n+r-1) - x^{n+r} a_n (n+r) + a_n x^{n+r} = 0$$

When $n=0$ the above becomes

$$x^r a_0 r (-1+r) - x^r a_0 r + a_0 x^r = 0$$

Or

$$(x^r r (-1+r) - x^r r + x^r) a_0 = 0$$

Since $a_0 \neq 0$ then the above simplifies to

$$(-1+r)^2 x^r = 0$$

Since the above is true for all x then the indicial equation becomes

$$(-1+r)^2 = 0$$

Solving for r gives the roots of the indicial equation as

$$r_1 = 1$$

$$r_2 = 1$$

Since $a_0 \neq 0$ then the indicial equation becomes

$$(-1 + r)^2 x^r = 0$$

Solving for r gives the roots of the indicial equation as Since the root of the indicial equation is repeated, then we can construct two linearly independent solutions. The first solution has the form

$$y_1(x) = \sum_{n=0}^{\infty} a_n x^{n+r} \quad (1A)$$

Now the second solution y_2 is found using

$$y_2(x) = y_1(x) \ln(x) + \left(\sum_{n=1}^{\infty} b_n x^{n+r} \right) \quad (1B)$$

Then the general solution will be

$$y = c_1 y_1(x) + c_2 y_2(x)$$

In Eq (1B) the sum starts from 1 and not zero. In Eq (1A), a_0 is never zero, and is arbitrary and is typically taken as $a_0 = 1$, and $\{c_1, c_2\}$ are two arbitrary constants of integration which can be found from initial conditions. Using the value of the indicial root found earlier, $r = 1$, Eqs (1A,1B) become

$$y_1(x) = \sum_{n=0}^{\infty} a_n x^{n+1}$$

$$y_2(x) = y_1(x) \ln(x) + \left(\sum_{n=1}^{\infty} b_n x^{n+1} \right)$$

We start by finding the first solution $y_1(x)$. Eq (2B) derived above is now used to find all a_n coefficients. The case $n = 0$ is skipped since it was used to find the roots of the indicial equation. a_0 is arbitrary and taken as $a_0 = 1$. Substituting $n = 1$ in Eq. (2B) gives

$$a_1 = 0$$

For $2 \leq n$ the recursive equation is

$$a_n(n+r)(n+r-1) - a_n(n+r) + a_{n-2} + a_n = 0 \quad (3)$$

Solving for a_n from recursive equation (4) gives

$$a_n = -\frac{a_{n-2}}{n^2 + 2nr + r^2 - 2n - 2r + 1} \quad (4)$$

Which for the root $r = 1$ becomes

$$a_n = -\frac{a_{n-2}}{n^2} \quad (5)$$

At this point, it is a good idea to keep track of a_n in a table both before substituting $r = 1$ and after as more terms are found using the above recursive equation.

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0

For $n = 2$, using the above recursive equation gives

$$a_2 = -\frac{1}{(1+r)^2}$$

Which for the root $r = 1$ becomes

$$a_2 = -\frac{1}{4}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{1}{(1+r)^2}$	$-\frac{1}{4}$

For $n = 3$, using the above recursive equation gives

$$a_3 = 0$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{1}{(1+r)^2}$	$-\frac{1}{4}$
a_3	0	0

For $n = 4$, using the above recursive equation gives

$$a_4 = \frac{1}{(1+r)^2(r+3)^2}$$

Which for the root $r = 1$ becomes

$$a_4 = \frac{1}{64}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{1}{(1+r)^2}$	$-\frac{1}{4}$
a_3	0	0
a_4	$\frac{1}{(1+r)^2(r+3)^2}$	$\frac{1}{64}$

For $n = 5$, using the above recursive equation gives

$$a_5 = 0$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{1}{(1+r)^2}$	$-\frac{1}{4}$
a_3	0	0
a_4	$\frac{1}{(1+r)^2(r+3)^2}$	$\frac{1}{64}$
a_5	0	0

Using the above table, then the first solution $y_1(x)$ is

$$\begin{aligned} y_1(x) &= x(a_0 + a_1x + a_2x^2 + a_3x^3 + a_4x^4 + a_5x^5 + a_6x^6 \dots) \\ &= x\left(1 - \frac{x^2}{4} + \frac{x^4}{64} + O(x^6)\right) \end{aligned}$$

Now the second solution is found. The second solution is given by

$$y_2(x) = y_1(x) \ln(x) + \left(\sum_{n=1}^{\infty} b_n x^{n+r} \right)$$

Where b_n is found using

$$b_n = \frac{d}{dr} a_{n,r}$$

And the above is then evaluated at $r = 1$. The above table for $a_{n,r}$ is used for this purpose. Computing the derivatives gives the following table

n	$b_{n,r}$	a_n	$b_{n,r} = \frac{d}{dr} a_{n,r}$	$b_n(r = 1)$
b_0	1	1	N/A since b_n starts from 1	N/A
b_1	0	0	0	0
b_2	$-\frac{1}{(1+r)^2}$	$-\frac{1}{4}$	$\frac{2}{(1+r)^3}$	$\frac{1}{4}$
b_3	0	0	0	0
b_4	$\frac{1}{(1+r)^2(r+3)^2}$	$\frac{1}{64}$	$\frac{-4r-8}{(1+r)^3(r+3)^3}$	$-\frac{3}{128}$
b_5	0	0	0	0

The above table gives all values of b_n needed. Hence the second solution is

$$\begin{aligned} y_2(x) &= y_1(x) \ln(x) + b_0 + b_1 x + b_2 x^2 + b_3 x^3 + b_4 x^4 + b_5 x^5 + b_6 x^6 \dots \\ &= x \left(1 - \frac{x^2}{4} + \frac{x^4}{64} + O(x^6) \right) \ln(x) + x \left(\frac{x^2}{4} - \frac{3x^4}{128} + O(x^6) \right) \end{aligned}$$

Therefore the homogeneous solution is

$$\begin{aligned} y_h(x) &= c_1 y_1(x) + c_2 y_2(x) \\ &= c_1 x \left(1 - \frac{x^2}{4} + \frac{x^4}{64} + O(x^6) \right) \\ &\quad + c_2 \left(x \left(1 - \frac{x^2}{4} + \frac{x^4}{64} + O(x^6) \right) \ln(x) + x \left(\frac{x^2}{4} - \frac{3x^4}{128} + O(x^6) \right) \right) \end{aligned}$$

Hence the final solution is

$$\begin{aligned}
 y &= y_h \\
 &= c_1 x \left(1 - \frac{x^2}{4} + \frac{x^4}{64} + O(x^6) \right) \\
 &\quad + c_2 \left(x \left(1 - \frac{x^2}{4} + \frac{x^4}{64} + O(x^6) \right) \ln(x) + x \left(\frac{x^2}{4} - \frac{3x^4}{128} + O(x^6) \right) \right)
 \end{aligned}$$

Summary

The solution(s) found are the following

$$\begin{aligned}
 y &= c_1 x \left(1 - \frac{x^2}{4} + \frac{x^4}{64} + O(x^6) \right) \\
 &\quad + c_2 \left(x \left(1 - \frac{x^2}{4} + \frac{x^4}{64} + O(x^6) \right) \ln(x) + x \left(\frac{x^2}{4} - \frac{3x^4}{128} + O(x^6) \right) \right)
 \end{aligned} \tag{1}$$

Verification of solutions

$$\begin{aligned}
 y &= c_1 x \left(1 - \frac{x^2}{4} + \frac{x^4}{64} + O(x^6) \right) \\
 &\quad + c_2 \left(x \left(1 - \frac{x^2}{4} + \frac{x^4}{64} + O(x^6) \right) \ln(x) + x \left(\frac{x^2}{4} - \frac{3x^4}{128} + O(x^6) \right) \right)
 \end{aligned}$$

Verified OK.

15.25.1 Maple step by step solution

Let's solve

$$y''x^2 - y'x + (x^2 + 1)y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = -\frac{(x^2+1)y}{x^2} + \frac{y'}{x}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' - \frac{y'}{x} + \frac{(x^2+1)y}{x^2} = 0$$

- Check to see if $x_0 = 0$ is a regular singular point

- Define functions

$$\left[P_2(x) = -\frac{1}{x}, P_3(x) = \frac{x^2+1}{x^2} \right]$$

- $x \cdot P_2(x)$ is analytic at $x = 0$

$$(x \cdot P_2(x)) \Big|_{x=0} = -1$$

- $x^2 \cdot P_3(x)$ is analytic at $x = 0$

$$(x^2 \cdot P_3(x)) \Big|_{x=0} = 1$$

- $x = 0$ is a regular singular point

Check to see if $x_0 = 0$ is a regular singular point

$$x_0 = 0$$

- Multiply by denominators

$$y''x^2 - y'x + (x^2 + 1)y = 0$$

- Assume series solution for y

$$y = \sum_{k=0}^{\infty} a_k x^{k+r}$$

- Rewrite ODE with series expansions

- Convert $x^m \cdot y$ to series expansion for $m = 0..2$

$$x^m \cdot y = \sum_{k=0}^{\infty} a_k x^{k+r+m}$$

- Shift index using $k- > k - m$

$$x^m \cdot y = \sum_{k=m}^{\infty} a_{k-m} x^{k+r}$$

- Convert $x \cdot y'$ to series expansion

$$x \cdot y' = \sum_{k=0}^{\infty} a_k (k+r) x^{k+r}$$

- Convert $x^2 \cdot y''$ to series expansion

$$x^2 \cdot y'' = \sum_{k=0}^{\infty} a_k (k+r)(k+r-1) x^{k+r}$$

Rewrite ODE with series expansions

$$a_0(-1+r)^2 x^r + a_1 r^2 x^{1+r} + \left(\sum_{k=2}^{\infty} (a_k (k+r-1)^2 + a_{k-2}) x^{k+r} \right) = 0$$

- a_0 cannot be 0 by assumption, giving the indicial equation

$$(-1 + r)^2 = 0$$

- Values of r that satisfy the indicial equation

$$r = 1$$

- Each term must be 0

$$a_1 r^2 = 0$$

- Solve for the dependent coefficient(s)

$$a_1 = 0$$

- Each term in the series must be 0, giving the recursion relation

$$a_k(k + r - 1)^2 + a_{k-2} = 0$$

- Shift index using $k \rightarrow k + 2$

$$a_{k+2}(k + 1 + r)^2 + a_k = 0$$

- Recursion relation that defines series solution to ODE

$$a_{k+2} = -\frac{a_k}{(k+1+r)^2}$$

- Recursion relation for $r = 1$

$$a_{k+2} = -\frac{a_k}{(k+2)^2}$$

- Solution for $r = 1$

$$\left[y = \sum_{k=0}^{\infty} a_k x^{k+1}, a_{k+2} = -\frac{a_k}{(k+2)^2}, a_1 = 0 \right]$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
checking if the LODE is of Euler type  
trying a symmetry of the form [xi=0, eta=F(x)]  
checking if the LODE is missing y  
-> Trying a Liouvillian solution using Kovacic's algorithm  
<- No Liouvillian solutions exist  
-> Trying a solution in terms of special functions:  
  -> Bessel  
  <- Bessel successful  
<- special function solution successful`
```

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 45

```
Order:=6;  
dsolve(x^2*diff(y(x),x$2)-x*diff(y(x),x)+(x^2+1)*y(x)=0,y(x),type='series',x=0);
```

$$y(x) = \left((c_1 + c_2 \ln(x)) \left(1 - \frac{1}{4}x^2 + \frac{1}{64}x^4 + O(x^6) \right) + \left(\frac{1}{4}x^2 - \frac{3}{128}x^4 + O(x^6) \right) c_2 \right) x$$

✓ Solution by Mathematica

Time used: 0.002 (sec). Leaf size: 65

```
AsymptoticDSolveValue[x^2*y'[x]-x*y'[x]+(x^2+1)*y[x]==0,y[x],{x,0,5}]
```

$$y(x) \rightarrow c_1 x \left(\frac{x^4}{64} - \frac{x^2}{4} + 1 \right) + c_2 \left(x \left(\frac{x^2}{4} - \frac{3x^4}{128} \right) + x \left(\frac{x^4}{64} - \frac{x^2}{4} + 1 \right) \log(x) \right)$$

15.26 problem 26

15.26.1 Maple step by step solution 4365

Internal problem ID [11927]

Internal file name [OUTPUT/11936_Saturday_April_13_2024_10_26_36_PM_90976062/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 6, Series solutions of linear differential equations. Section 6.2 (Frobenius). Exercises page 251

Problem number: 26.

ODE order: 2.

ODE degree: 1.

The type(s) of ODE detected by this program : **"second order series method. Regular singular point. Difference is integer"**

Maple gives the following as the ode type

```
[[_2nd_order , _with_linear_symmetries]]
```

$$x^2 y'' - y'x + (x^2 - 3)y = 0$$

With the expansion point for the power series method at $x = 0$.

The type of the expansion point is first determined. This is done on the homogeneous part of the ODE.

$$x^2 y'' - y'x + (x^2 - 3)y = 0$$

The following is summary of singularities for the above ode. Writing the ode as

$$y'' + p(x)y' + q(x)y = 0$$

Where

$$p(x) = -\frac{1}{x}$$
$$q(x) = \frac{x^2 - 3}{x^2}$$

Table 577: Table $p(x), q(x)$ singularities.

$p(x) = -\frac{1}{x}$	
singularity	type
$x = 0$	“regular”

$q(x) = \frac{x^2-3}{x^2}$	
singularity	type
$x = 0$	“regular”

Combining everything together gives the following summary of singularities for the ode as

Regular singular points : $[0]$

Irregular singular points : $[\infty]$

Since $x = 0$ is regular singular point, then Frobenius power series is used. The ode is normalized to be

$$x^2 y'' - y' x + (x^2 - 3) y = 0$$

Let the solution be represented as Frobenius power series of the form

$$y = \sum_{n=0}^{\infty} a_n x^{n+r}$$

Then

$$y' = \sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1}$$

$$y'' = \sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2}$$

Substituting the above back into the ode gives

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} (n+r)(n+r-1) a_n x^{n+r-2} \right) x^2 \\ & - \left(\sum_{n=0}^{\infty} (n+r) a_n x^{n+r-1} \right) x + (x^2 - 3) \left(\sum_{n=0}^{\infty} a_n x^{n+r} \right) = 0 \end{aligned} \tag{1}$$

Which simplifies to

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} x^{n+r} a_n (n+r) (n+r-1) \right) + \sum_{n=0}^{\infty} (-x^{n+r} a_n (n+r)) \\ & + \left(\sum_{n=0}^{\infty} x^{n+r+2} a_n \right) + \sum_{n=0}^{\infty} (-3a_n x^{n+r}) = 0 \end{aligned} \quad (2A)$$

The next step is to make all powers of x be $n+r$ in each summation term. Going over each summation term above with power of x in it which is not already x^{n+r} and adjusting the power and the corresponding index gives

$$\sum_{n=0}^{\infty} x^{n+r+2} a_n = \sum_{n=2}^{\infty} a_{n-2} x^{n+r}$$

Substituting all the above in Eq (2A) gives the following equation where now all powers of x are the same and equal to $n+r$.

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} x^{n+r} a_n (n+r) (n+r-1) \right) + \sum_{n=0}^{\infty} (-x^{n+r} a_n (n+r)) \\ & + \left(\sum_{n=2}^{\infty} a_{n-2} x^{n+r} \right) + \sum_{n=0}^{\infty} (-3a_n x^{n+r}) = 0 \end{aligned} \quad (2B)$$

The indicial equation is obtained from $n=0$. From Eq (2B) this gives

$$x^{n+r} a_n (n+r) (n+r-1) - x^{n+r} a_n (n+r) - 3a_n x^{n+r} = 0$$

When $n=0$ the above becomes

$$x^r a_0 r(-1+r) - x^r a_0 r - 3a_0 x^r = 0$$

Or

$$(x^r r(-1+r) - x^r r - 3x^r) a_0 = 0$$

Since $a_0 \neq 0$ then the above simplifies to

$$(r^2 - 2r - 3) x^r = 0$$

Since the above is true for all x then the indicial equation becomes

$$r^2 - 2r - 3 = 0$$

Solving for r gives the roots of the indicial equation as

$$\begin{aligned} r_1 &= 3 \\ r_2 &= -1 \end{aligned}$$

Since $a_0 \neq 0$ then the indicial equation becomes

$$(r^2 - 2r - 3) x^r = 0$$

Solving for r gives the roots of the indicial equation as Since $r_1 - r_2 = 4$ is an integer, then we can construct two linearly independent solutions

$$\begin{aligned} y_1(x) &= x^{r_1} \left(\sum_{n=0}^{\infty} a_n x^n \right) \\ y_2(x) &= C y_1(x) \ln(x) + x^{r_2} \left(\sum_{n=0}^{\infty} b_n x^n \right) \end{aligned}$$

Or

$$\begin{aligned} y_1(x) &= x^3 \left(\sum_{n=0}^{\infty} a_n x^n \right) \\ y_2(x) &= C y_1(x) \ln(x) + \frac{\sum_{n=0}^{\infty} b_n x^n}{x} \end{aligned}$$

Or

$$\begin{aligned} y_1(x) &= \sum_{n=0}^{\infty} a_n x^{n+3} \\ y_2(x) &= C y_1(x) \ln(x) + \left(\sum_{n=0}^{\infty} b_n x^{n-1} \right) \end{aligned}$$

Where C above can be zero. We start by finding y_1 . Eq (2B) derived above is now used to find all a_n coefficients. The case $n = 0$ is skipped since it was used to find the roots of the indicial equation. a_0 is arbitrary and taken as $a_0 = 1$. Substituting $n = 1$ in Eq. (2B) gives

$$a_1 = 0$$

For $2 \leq n$ the recursive equation is

$$a_n(n+r)(n+r-1) - a_n(n+r) + a_{n-2} - 3a_n = 0 \quad (3)$$

Solving for a_n from recursive equation (4) gives

$$a_n = -\frac{a_{n-2}}{n^2 + 2nr + r^2 - 2n - 2r - 3} \quad (4)$$

Which for the root $r = 3$ becomes

$$a_n = -\frac{a_{n-2}}{n(n+4)} \quad (5)$$

At this point, it is a good idea to keep track of a_n in a table both before substituting $r = 3$ and after as more terms are found using the above recursive equation.

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0

For $n = 2$, using the above recursive equation gives

$$a_2 = -\frac{1}{r^2 + 2r - 3}$$

Which for the root $r = 3$ becomes

$$a_2 = -\frac{1}{12}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{1}{r^2+2r-3}$	$-\frac{1}{12}$

For $n = 3$, using the above recursive equation gives

$$a_3 = 0$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{1}{r^2+2r-3}$	$-\frac{1}{12}$
a_3	0	0

For $n = 4$, using the above recursive equation gives

$$a_4 = \frac{1}{r^4 + 8r^3 + 14r^2 - 8r - 15}$$

Which for the root $r = 3$ becomes

$$a_4 = \frac{1}{384}$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{1}{r^2+2r-3}$	$-\frac{1}{12}$
a_3	0	0
a_4	$\frac{1}{r^4+8r^3+14r^2-8r-15}$	$\frac{1}{384}$

For $n = 5$, using the above recursive equation gives

$$a_5 = 0$$

And the table now becomes

n	$a_{n,r}$	a_n
a_0	1	1
a_1	0	0
a_2	$-\frac{1}{r^2+2r-3}$	$-\frac{1}{12}$
a_3	0	0
a_4	$\frac{1}{r^4+8r^3+14r^2-8r-15}$	$\frac{1}{384}$
a_5	0	0

Using the above table, then the solution $y_1(x)$ is

$$\begin{aligned} y_1(x) &= x^3(a_0 + a_1x + a_2x^2 + a_3x^3 + a_4x^4 + a_5x^5 + a_6x^6 \dots) \\ &= x^3\left(1 - \frac{x^2}{12} + \frac{x^4}{384} + O(x^6)\right) \end{aligned}$$

Now the second solution $y_2(x)$ is found. Let

$$r_1 - r_2 = N$$

Where N is positive integer which is the difference between the two roots. r_1 is taken as the larger root. Hence for this problem we have $N = 4$. Now we need to determine if C is zero or not. This is done by finding $\lim_{r \rightarrow r_2} a_4(r)$. If this limit exists, then $C = 0$, else we need to keep the log term and $C \neq 0$. The above table shows that

$$\begin{aligned} a_N &= a_4 \\ &= \frac{1}{r^4 + 8r^3 + 14r^2 - 8r - 15} \end{aligned}$$

Therefore

$$\begin{aligned} \lim_{r \rightarrow r_2} \frac{1}{r^4 + 8r^3 + 14r^2 - 8r - 15} &= \lim_{r \rightarrow -1} \frac{1}{r^4 + 8r^3 + 14r^2 - 8r - 15} \\ &= \text{undefined} \end{aligned}$$

Since the limit does not exist then the log term is needed. Therefore the second solution has the form

$$y_2(x) = Cy_1(x) \ln(x) + \left(\sum_{n=0}^{\infty} b_n x^{n+r_2} \right)$$

Therefore

$$\begin{aligned} \frac{d}{dx} y_2(x) &= Cy_1'(x) \ln(x) + \frac{Cy_1(x)}{x} + \left(\sum_{n=0}^{\infty} \frac{b_n x^{n+r_2} (n+r_2)}{x} \right) \\ &= Cy_1'(x) \ln(x) + \frac{Cy_1(x)}{x} + \left(\sum_{n=0}^{\infty} x^{-1+n+r_2} b_n (n+r_2) \right) \\ \frac{d^2}{dx^2} y_2(x) &= Cy_1''(x) \ln(x) + \frac{2Cy_1'(x)}{x} - \frac{Cy_1(x)}{x^2} \\ &\quad + \sum_{n=0}^{\infty} \left(\frac{b_n x^{n+r_2} (n+r_2)^2}{x^2} - \frac{b_n x^{n+r_2} (n+r_2)}{x^2} \right) \\ &= Cy_1''(x) \ln(x) + \frac{2Cy_1'(x)}{x} - \frac{Cy_1(x)}{x^2} + \left(\sum_{n=0}^{\infty} x^{-2+n+r_2} b_n (n+r_2) (-1+n+r_2) \right) \end{aligned}$$

Substituting these back into the given ode $x^2y'' - y'x + (x^2 - 3)y = 0$ gives

$$\begin{aligned} & \left(Cy_1''(x) \ln(x) + \frac{2Cy_1'(x)}{x} - \frac{Cy_1(x)}{x^2} \right. \\ & \left. + \sum_{n=0}^{\infty} \left(\frac{b_n x^{n+r_2}(n+r_2)^2}{x^2} - \frac{b_n x^{n+r_2}(n+r_2)}{x^2} \right) \right) x^2 \\ & - \left(Cy_1'(x) \ln(x) + \frac{Cy_1(x)}{x} + \left(\sum_{n=0}^{\infty} \frac{b_n x^{n+r_2}(n+r_2)}{x} \right) \right) x \\ & + (x^2 - 3) \left(Cy_1(x) \ln(x) + \left(\sum_{n=0}^{\infty} b_n x^{n+r_2} \right) \right) = 0 \end{aligned}$$

Which can be written as

$$\begin{aligned} & \left((y_1''(x)x^2 - y_1'(x)x + (x^2 - 3)y_1(x)) \ln(x) + \left(\frac{2y_1'(x)}{x} - \frac{y_1(x)}{x^2} \right) x^2 \right. \\ & \left. - y_1(x) \right) C + \left(\sum_{n=0}^{\infty} \left(\frac{b_n x^{n+r_2}(n+r_2)^2}{x^2} - \frac{b_n x^{n+r_2}(n+r_2)}{x^2} \right) \right) x^2 \\ & - \left(\sum_{n=0}^{\infty} \frac{b_n x^{n+r_2}(n+r_2)}{x} \right) x + (x^2 - 3) \left(\sum_{n=0}^{\infty} b_n x^{n+r_2} \right) = 0 \end{aligned} \quad (7)$$

But since $y_1(x)$ is a solution to the ode, then

$$y_1''(x)x^2 - y_1'(x)x + (x^2 - 3)y_1(x) = 0$$

Eq (7) simplifies to

$$\begin{aligned} & \left(\left(\frac{2y_1'(x)}{x} - \frac{y_1(x)}{x^2} \right) x^2 - y_1(x) \right) C \\ & + \left(\sum_{n=0}^{\infty} \left(\frac{b_n x^{n+r_2}(n+r_2)^2}{x^2} - \frac{b_n x^{n+r_2}(n+r_2)}{x^2} \right) \right) x^2 \\ & - \left(\sum_{n=0}^{\infty} \frac{b_n x^{n+r_2}(n+r_2)}{x} \right) x + (x^2 - 3) \left(\sum_{n=0}^{\infty} b_n x^{n+r_2} \right) = 0 \end{aligned} \quad (8)$$

Substituting $y_1 = \sum_{n=0}^{\infty} a_n x^{n+r_1}$ into the above gives

$$\begin{aligned} & \left(2 \left(\sum_{n=0}^{\infty} x^{-1+n+r_1} a_n (n+r_1) \right) x - 2 \left(\sum_{n=0}^{\infty} a_n x^{n+r_1} \right) \right) C \\ & + \left(\sum_{n=0}^{\infty} b_n x^{n+r_2} \right) x^2 + \left(\sum_{n=0}^{\infty} x^{-2+n+r_2} b_n (n+r_2) (-1+n+r_2) \right) x^2 \\ & - \left(\sum_{n=0}^{\infty} x^{-1+n+r_2} b_n (n+r_2) \right) x - 3 \left(\sum_{n=0}^{\infty} b_n x^{n+r_2} \right) = 0 \end{aligned} \quad (9)$$

Since $r_1 = 3$ and $r_2 = -1$ then the above becomes

$$\begin{aligned} & \left(2 \left(\sum_{n=0}^{\infty} x^{2+n} a_n (n+3) \right) x - 2 \left(\sum_{n=0}^{\infty} a_n x^{n+3} \right) \right) C \\ & + \left(\sum_{n=0}^{\infty} b_n x^{n-1} \right) x^2 + \left(\sum_{n=0}^{\infty} x^{-3+n} b_n (n-1) (n-2) \right) x^2 \\ & - \left(\sum_{n=0}^{\infty} x^{n-2} b_n (n-1) \right) x - 3 \left(\sum_{n=0}^{\infty} b_n x^{n-1} \right) = 0 \end{aligned} \quad (10)$$

Which simplifies to

$$\begin{aligned} & \left(\sum_{n=0}^{\infty} 2C x^{n+3} a_n (n+3) \right) + \sum_{n=0}^{\infty} (-2C a_n x^{n+3}) \\ & + \left(\sum_{n=0}^{\infty} x^{1+n} b_n \right) + \left(\sum_{n=0}^{\infty} x^{n-1} b_n (n^2 - 3n + 2) \right) \\ & + \sum_{n=0}^{\infty} (-x^{n-1} b_n (n-1)) + \sum_{n=0}^{\infty} (-3b_n x^{n-1}) = 0 \end{aligned} \quad (2A)$$

The next step is to make all powers of x be $n-1$ in each summation term. Going over each summation term above with power of x in it which is not already x^{n-1} and

adjusting the power and the corresponding index gives

$$\begin{aligned}\sum_{n=0}^{\infty} 2C x^{n+3} a_n (n+3) &= \sum_{n=4}^{\infty} 2C a_{n-4} (n-1) x^{n-1} \\ \sum_{n=0}^{\infty} (-2C a_n x^{n+3}) &= \sum_{n=4}^{\infty} (-2C a_{n-4} x^{n-1}) \\ \sum_{n=0}^{\infty} x^{1+n} b_n &= \sum_{n=2}^{\infty} b_{n-2} x^{n-1}\end{aligned}$$

Substituting all the above in Eq (2A) gives the following equation where now all powers of x are the same and equal to $n - 1$.

$$\begin{aligned}\left(\sum_{n=4}^{\infty} 2C a_{n-4} (n-1) x^{n-1} \right) + \sum_{n=4}^{\infty} (-2C a_{n-4} x^{n-1}) \\ + \left(\sum_{n=2}^{\infty} b_{n-2} x^{n-1} \right) + \left(\sum_{n=0}^{\infty} x^{n-1} b_n (n^2 - 3n + 2) \right) \\ + \sum_{n=0}^{\infty} (-x^{n-1} b_n (n-1)) + \sum_{n=0}^{\infty} (-3b_n x^{n-1}) = 0\end{aligned}\tag{2B}$$

For $n = 0$ in Eq. (2B), we choose arbitray value for b_0 as $b_0 = 1$. For $n = 1$, Eq (2B) gives

$$-3b_1 = 0$$

Which when replacing the above values found already for b_n and the values found earlier for a_n and for C , gives

$$-3b_1 = 0$$

Solving the above for b_1 gives

$$b_1 = 0$$

For $n = 2$, Eq (2B) gives

$$b_0 - 4b_2 = 0$$

Which when replacing the above values found already for b_n and the values found earlier for a_n and for C , gives

$$1 - 4b_2 = 0$$

Solving the above for b_2 gives

$$b_2 = \frac{1}{4}$$

For $n = 3$, Eq (2B) gives

$$b_1 - 3b_3 = 0$$

Which when replacing the above values found already for b_n and the values found earlier for a_n and for C , gives

$$-3b_3 = 0$$

Solving the above for b_3 gives

$$b_3 = 0$$

For $n = N$, where $N = 4$ which is the difference between the two roots, we are free to choose $b_4 = 0$. Hence for $n = 4$, Eq (2B) gives

$$4C + \frac{1}{4} = 0$$

Which is solved for C . Solving for C gives

$$C = -\frac{1}{16}$$

For $n = 5$, Eq (2B) gives

$$6Ca_1 + b_3 + 5b_5 = 0$$

Which when replacing the above values found already for b_n and the values found earlier for a_n and for C , gives

$$5b_5 = 0$$

Solving the above for b_5 gives

$$b_5 = 0$$

Now that we found all b_n and C , we can calculate the second solution from

$$y_2(x) = Cy_1(x) \ln(x) + \left(\sum_{n=0}^{\infty} b_n x^{n+r_2} \right)$$

Using the above value found for $C = -\frac{1}{16}$ and all b_n , then the second solution becomes

$$y_2(x) = -\frac{1}{16} \left(x^3 \left(1 - \frac{x^2}{12} + \frac{x^4}{384} + O(x^6) \right) \right) \ln(x) + \frac{1 + \frac{x^2}{4} + O(x^6)}{x}$$

Therefore the homogeneous solution is

$$\begin{aligned} y_h(x) &= c_1 y_1(x) + c_2 y_2(x) \\ &= c_1 x^3 \left(1 - \frac{x^2}{12} + \frac{x^4}{384} + O(x^6) \right) \\ &\quad + c_2 \left(-\frac{1}{16} \left(x^3 \left(1 - \frac{x^2}{12} + \frac{x^4}{384} + O(x^6) \right) \right) \ln(x) + \frac{1 + \frac{x^2}{4} + O(x^6)}{x} \right) \end{aligned}$$

Hence the final solution is

$$\begin{aligned}
 y &= y_h \\
 &= c_1 x^3 \left(1 - \frac{x^2}{12} + \frac{x^4}{384} + O(x^6) \right) \\
 &\quad + c_2 \left(-\frac{x^3 \left(1 - \frac{x^2}{12} + \frac{x^4}{384} + O(x^6) \right) \ln(x)}{16} + \frac{1 + \frac{x^2}{4} + O(x^6)}{x} \right)
 \end{aligned}$$

Summary

The solution(s) found are the following

$$\begin{aligned}
 y &= c_1 x^3 \left(1 - \frac{x^2}{12} + \frac{x^4}{384} + O(x^6) \right) \\
 &\quad + c_2 \left(-\frac{x^3 \left(1 - \frac{x^2}{12} + \frac{x^4}{384} + O(x^6) \right) \ln(x)}{16} + \frac{1 + \frac{x^2}{4} + O(x^6)}{x} \right) \tag{1}
 \end{aligned}$$

Verification of solutions

$$\begin{aligned}
 y &= c_1 x^3 \left(1 - \frac{x^2}{12} + \frac{x^4}{384} + O(x^6) \right) \\
 &\quad + c_2 \left(-\frac{x^3 \left(1 - \frac{x^2}{12} + \frac{x^4}{384} + O(x^6) \right) \ln(x)}{16} + \frac{1 + \frac{x^2}{4} + O(x^6)}{x} \right)
 \end{aligned}$$

Verified OK.

15.26.1 Maple step by step solution

Let's solve

$$y''x^2 - y'x + (x^2 - 3)y = 0$$

- Highest derivative means the order of the ODE is 2

$$y''$$

- Isolate 2nd derivative

$$y'' = -\frac{(x^2-3)y}{x^2} + \frac{y'}{x}$$

- Group terms with y on the lhs of the ODE and the rest on the rhs of the ODE; ODE is linear

$$y'' - \frac{y'}{x} + \frac{(x^2-3)y}{x^2} = 0$$

□ Check to see if $x_0 = 0$ is a regular singular point

○ Define functions

$$\left[P_2(x) = -\frac{1}{x}, P_3(x) = \frac{x^2-3}{x^2} \right]$$

○ $x \cdot P_2(x)$ is analytic at $x = 0$

$$(x \cdot P_2(x)) \Big|_{x=0} = -1$$

○ $x^2 \cdot P_3(x)$ is analytic at $x = 0$

$$(x^2 \cdot P_3(x)) \Big|_{x=0} = -3$$

○ $x = 0$ is a regular singular point

Check to see if $x_0 = 0$ is a regular singular point

$$x_0 = 0$$

• Multiply by denominators

$$y''x^2 - y'x + (x^2 - 3)y = 0$$

• Assume series solution for y

$$y = \sum_{k=0}^{\infty} a_k x^{k+r}$$

□ Rewrite ODE with series expansions

○ Convert $x^m \cdot y$ to series expansion for $m = 0..2$

$$x^m \cdot y = \sum_{k=0}^{\infty} a_k x^{k+r+m}$$

○ Shift index using $k \rightarrow k - m$

$$x^m \cdot y = \sum_{k=m}^{\infty} a_{k-m} x^{k+r}$$

○ Convert $x \cdot y'$ to series expansion

$$x \cdot y' = \sum_{k=0}^{\infty} a_k (k+r) x^{k+r}$$

○ Convert $x^2 \cdot y''$ to series expansion

$$x^2 \cdot y'' = \sum_{k=0}^{\infty} a_k (k+r)(k+r-1) x^{k+r}$$

Rewrite ODE with series expansions

$$a_0(1+r)(-3+r)x^r + a_1(2+r)(-2+r)x^{1+r} + \left(\sum_{k=2}^{\infty} (a_k(k+r+1)(k+r-3) + a_{k-2})x^{k+r} \right)$$

- a_0 cannot be 0 by assumption, giving the indicial equation

$$(1+r)(-3+r) = 0$$

- Values of r that satisfy the indicial equation

$$r \in \{-1, 3\}$$

- Each term must be 0

$$a_1(2+r)(-2+r) = 0$$

- Solve for the dependent coefficient(s)

$$a_1 = 0$$

- Each term in the series must be 0, giving the recursion relation

$$a_k(k+r+1)(k+r-3) + a_{k-2} = 0$$

- Shift index using $k \rightarrow k+2$

$$a_{k+2}(k+3+r)(k+r-1) + a_k = 0$$

- Recursion relation that defines series solution to ODE

$$a_{k+2} = -\frac{a_k}{(k+3+r)(k+r-1)}$$

- Recursion relation for $r = -1$

$$a_{k+2} = -\frac{a_k}{(k+2)(k-2)}$$

- Series not valid for $r = -1$, division by 0 in the recursion relation at $k = 2$

$$a_{k+2} = -\frac{a_k}{(k+2)(k-2)}$$

- Recursion relation for $r = 3$

$$a_{k+2} = -\frac{a_k}{(k+6)(k+2)}$$

- Solution for $r = 3$

$$\left[y = \sum_{k=0}^{\infty} a_k x^{k+3}, a_{k+2} = -\frac{a_k}{(k+6)(k+2)}, a_1 = 0 \right]$$

Maple trace

```
`Methods for second order ODEs:  
--- Trying classification methods ---  
trying a quadrature  
checking if the LODE has constant coefficients  
checking if the LODE is of Euler type  
trying a symmetry of the form [xi=0, eta=F(x)]  
checking if the LODE is missing y  
-> Trying a Liouvillian solution using Kovacic's algorithm  
<- No Liouvillian solutions exist  
-> Trying a solution in terms of special functions:  
  -> Bessel  
  <- Bessel successful  
<- special function solution successful`
```

✓ Solution by Maple

Time used: 0.031 (sec). Leaf size: 47

```
Order:=6;  
dsolve(x^2*diff(y(x),x$2)-x*diff(y(x),x)+(x^2-3)*y(x)=0,y(x),type='series',x=0);
```

$$y(x) = \frac{c_1 x^4 \left(1 - \frac{1}{12}x^2 + \frac{1}{384}x^4 + O(x^6)\right) + c_2 (\ln(x) (9x^4 + O(x^6)) + (-144 - 36x^2 + O(x^6)))}{x}$$

✓ Solution by Mathematica

Time used: 0.008 (sec). Leaf size: 52

```
AsymptoticDSolveValue[x^2*y'[x]-x*y'[x]+(x^2-3)*y[x]==0,y[x],{x,0,5}]
```

$$y(x) \rightarrow c_1 \left(\frac{(x^2 + 8)^2}{64x} - \frac{1}{16}x^3 \log(x) \right) + c_2 \left(\frac{x^7}{384} - \frac{x^5}{12} + x^3 \right)$$

16 Chapter 7, Systems of linear differential equations. Section 7.1. Exercises page 277

16.1 problem 1	4370
16.2 problem 2	4372
16.3 problem 3	4374
16.4 problem 4	4377
16.5 problem 5	4379
16.6 problem 6	4389
16.7 problem 7	4401
16.8 problem 8	4413
16.9 problem 9	4425
16.10 problem 10	4428
16.11 problem 11	4440
16.12 problem 12	4452
16.13 problem 13	4465
16.14 problem 14	4477
16.15 problem 15	4489
16.16 problem 16	4501
16.17 problem 17	4512

16.1 problem 1

Internal problem ID [11928]

Internal file name [OUTPUT/11937_Saturday_April_13_2024_10_26_37_PM_64304397/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 7, Systems of linear differential equations. Section 7.1. Exercises page 277

Problem number: 1.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "system of linear ODEs"

Solve

$$\begin{aligned}x'(t) + y'(t) &= 2x(t) + 4y(t) + e^t \\x'(t) + y'(t) &= y(t) + e^{4t}\end{aligned}$$

The system is

$$x'(t) + y'(t) = 2x(t) + 4y(t) + e^t \quad (1)$$

$$x'(t) + y'(t) = y(t) + e^{4t} \quad (2)$$

Since the left side is the same, this implies

$$\begin{aligned}2x(t) + 4y(t) + e^t &= y(t) + e^{4t} \\y(t) &= \frac{e^{4t}}{3} - \frac{2x(t)}{3} - \frac{e^t}{3}\end{aligned} \quad (3)$$

Taking derivative of the above w.r.t. t gives

$$y'(t) = \frac{4e^{4t}}{3} - \frac{2x'(t)}{3} - \frac{e^t}{3} \quad (4)$$

Substituting (3,4) in (1) to eliminate $y(t)$, $y'(t)$ gives

$$\begin{aligned}\frac{x'(t)}{3} + \frac{4e^{4t}}{3} - \frac{e^t}{3} &= -\frac{2x(t)}{3} + \frac{4e^{4t}}{3} - \frac{e^t}{3} \\x'(t) &= -2x(t)\end{aligned} \quad (5)$$

Which is now solved for $x(t)$. Integrating both sides gives

$$\begin{aligned}\int -\frac{1}{2x} dx &= \int dt \\-\frac{\ln(x)}{2} &= t + c_1\end{aligned}$$

Raising both side to exponential gives

$$\frac{1}{\sqrt{x}} = e^{t+c_1}$$

Which simplifies to

$$\frac{1}{\sqrt{x}} = c_2 e^t$$

Given now that we have the solution

$$x(t) = \frac{e^{-2t}}{c_2^2} \quad (6)$$

Then substituting (6) into (3) gives

$$y(t) = \frac{(e^{6t}c_2^2 - c_2^2e^{3t} - 2) e^{-2t}}{3c_2^2} \quad (7)$$

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 32

```
dsolve([diff(x(t),t)+diff(y(t),t)-2*x(t)-4*y(t)=exp(t),diff(x(t),t)+diff(y(t),t)-y(t)=exp(4*t))],t)
```

$$x(t) = c_1 e^{-2t}$$

$$y(t) = \frac{e^{4t}}{3} - \frac{e^t}{3} - \frac{2c_1 e^{-2t}}{3}$$

✓ Solution by Mathematica

Time used: 0.055 (sec). Leaf size: 52

```
DSolve[{x'[t]+y'[t]-2*x[t]-4*y[t]==Exp[t],x'[t]+y'[t]-y[t]==Exp[4*t]},{x[t],y[t]},t,IncludeS
```

$$x(t) \rightarrow \frac{1}{12}(3 + 4c_1)e^{-2t}$$

$$y(t) \rightarrow \frac{1}{18}e^{-2t}(-6e^{3t} + 6e^{6t} - 3 - 4c_1)$$

16.2 problem 2

Internal problem ID [11929]

Internal file name [OUTPUT/11938_Saturday_April_13_2024_10_26_37_PM_14908028/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 7, Systems of linear differential equations. Section 7.1. Exercises page 277

Problem number: 2.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "system of linear ODEs"

Solve

$$\begin{aligned}x'(t) + y'(t) &= x(t) - 2t \\x'(t) + y'(t) &= t^2 + 3x(t) + y(t)\end{aligned}$$

The system is

$$x'(t) + y'(t) = x(t) - 2t \quad (1)$$

$$x'(t) + y'(t) = t^2 + 3x(t) + y(t) \quad (2)$$

Since the left side is the same, this implies

$$\begin{aligned}x(t) - 2t &= t^2 + 3x(t) + y(t) \\y(t) &= -t^2 - 2x(t) - 2t\end{aligned} \quad (3)$$

Taking derivative of the above w.r.t. t gives

$$y'(t) = -2t - 2x'(t) - 2 \quad (4)$$

Substituting (3,4) in (1) to eliminate $y(t)$, $y'(t)$ gives

$$\begin{aligned}-x'(t) - 2t - 2 &= x(t) - 2t \\x'(t) &= -x(t) - 2\end{aligned} \quad (5)$$

Which is now solved for $x(t)$. Integrating both sides gives

$$\begin{aligned}\int \frac{1}{-x-2} dx &= \int dt \\-\ln(-x-2) &= t + c_1\end{aligned}$$

Raising both side to exponential gives

$$\frac{1}{-x-2} = e^{t+c_1}$$

Which simplifies to

$$\frac{1}{-x-2} = c_2 e^t$$

Given now that we have the solution

$$x(t) = -\frac{e^{-t}}{c_2} - 2 \quad (6)$$

Then substituting (6) into (3) gives

$$y(t) = -\frac{(t^2 c_2 e^t + 2c_2 t e^t - 4c_2 e^t - 2) e^{-t}}{c_2} \quad (7)$$

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 33

```
dsolve([diff(x(t),t)+diff(y(t),t)-x(t)=-2*t,diff(x(t),t)+diff(y(t),t)-3*x(t)-y(t)=t^2],sings
```

$$\begin{aligned} x(t) &= -2 + e^{-t}c_1 \\ y(t) &= -t^2 + 4 - 2e^{-t}c_1 - 2t \end{aligned}$$

✓ Solution by Mathematica

Time used: 0.056 (sec). Leaf size: 42

```
DSolve[{x'[t]+y'[t]-x[t]==-2*t,x'[t]+y'[t]-3*x[t]-y[t]==t^2},{x[t],y[t]},t,IncludeSingularSo
```

$$\begin{aligned} x(t) &\rightarrow -2 - \frac{1}{4}c_1 e^{-t} \\ y(t) &\rightarrow -t^2 - 2t + \frac{c_1 e^{-t}}{2} + 4 \end{aligned}$$

16.3 problem 3

Internal problem ID [11930]

Internal file name [OUTPUT/11939_Saturday_April_13_2024_10_26_38_PM_48022610/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 7, Systems of linear differential equations. Section 7.1. Exercises page 277

Problem number: 3.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "system of linear ODEs"

Solve

$$\begin{aligned}x'(t) + y'(t) &= x(t) + 3y(t) + e^t \\x'(t) + y'(t) &= -x(t) + e^{3t}\end{aligned}$$

The system is

$$x'(t) + y'(t) = x(t) + 3y(t) + e^t \quad (1)$$

$$x'(t) + y'(t) = -x(t) + e^{3t} \quad (2)$$

Since the left side is the same, this implies

$$\begin{aligned}x(t) + 3y(t) + e^t &= -x(t) + e^{3t} \\y(t) &= \frac{e^{3t}}{3} - \frac{2x(t)}{3} - \frac{e^t}{3}\end{aligned} \quad (3)$$

Taking derivative of the above w.r.t. t gives

$$y'(t) = e^{3t} - \frac{2x'(t)}{3} - \frac{e^t}{3} \quad (4)$$

Substituting (3,4) in (1) to eliminate $y(t)$, $y'(t)$ gives

$$\begin{aligned}\frac{x'(t)}{3} + e^{3t} - \frac{e^t}{3} &= -x(t) + e^{3t} \\x'(t) &= -3x(t) + e^t\end{aligned} \quad (5)$$

Which is now solved for $x(t)$.

Entering Linear first order ODE solver. In canonical form a linear first order is

$$x'(t) + p(t)x(t) = q(t)$$

Where here

$$\begin{aligned}p(t) &= 3 \\q(t) &= e^t\end{aligned}$$

Hence the ode is

$$x'(t) + 3x(t) = e^t$$

The integrating factor μ is

$$\begin{aligned}\mu &= e^{\int 3dt} \\ &= e^{3t}\end{aligned}$$

The ode becomes

$$\begin{aligned}\frac{d}{dt}(\mu x) &= (\mu)(e^t) \\ \frac{d}{dt}(e^{3t}x) &= (e^{3t})(e^t) \\ d(e^{3t}x) &= e^{4t} dt\end{aligned}$$

Integrating gives

$$\begin{aligned}e^{3t}x &= \int e^{4t} dt \\ e^{3t}x &= \frac{e^{4t}}{4} + c_1\end{aligned}$$

Dividing both sides by the integrating factor $\mu = e^{3t}$ results in

$$x(t) = \frac{e^{-3t}e^{4t}}{4} + e^{-3t}c_1$$

which simplifies to

$$x(t) = \frac{(e^{4t} + 4c_1)e^{-3t}}{4}$$

Given now that we have the solution

$$x(t) = \frac{(e^{4t} + 4c_1)e^{-3t}}{4} \tag{6}$$

Then substituting (6) into (3) gives

$$y(t) = \frac{e^{3t}}{3} - \frac{e^{-3t}e^{4t}}{6} - \frac{2e^{-3t}c_1}{3} - \frac{e^t}{3} \tag{7}$$

✓ Solution by Maple

Time used: 0.032 (sec). Leaf size: 37

```
dsolve([diff(x(t),t)+diff(y(t),t)-x(t)-3*y(t)=exp(t),diff(x(t),t)+diff(y(t),t)+x(t)=exp(3*t))
```

$$x(t) = \frac{e^t}{4} + c_1 e^{-3t}$$
$$y(t) = \frac{e^{3t}}{3} - \frac{e^t}{2} - \frac{2c_1 e^{-3t}}{3}$$

✓ Solution by Mathematica

Time used: 0.043 (sec). Leaf size: 55

```
DSolve[{x'[t]+y'[t]-x[t]-3*y[t]==Exp[t],x'[t]+y'[t]+x[t]==Exp[3*t]},{x[t],y[t]},t,IncludeSin
```

$$x(t) \rightarrow \frac{e^t}{4} + \frac{3}{16}c_1 e^{-3t}$$
$$y(t) \rightarrow -\frac{e^t}{2} + \frac{e^{3t}}{3} - \frac{1}{8}c_1 e^{-3t}$$

16.4 problem 4

Internal problem ID [11931]

Internal file name [OUTPUT/11940_Saturday_April_13_2024_10_26_38_PM_75029156/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 7, Systems of linear differential equations. Section 7.1. Exercises page 277

Problem number: 4.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "system of linear ODEs"

Solve

$$x'(t) + y'(t) = x(t) + 2y(t) + 2e^t$$

$$x'(t) + y'(t) = 3x(t) + 4y(t) + e^{2t}$$

The system is

$$x'(t) + y'(t) = x(t) + 2y(t) + 2e^t \quad (1)$$

$$x'(t) + y'(t) = 3x(t) + 4y(t) + e^{2t} \quad (2)$$

Since the left side is the same, this implies

$$\begin{aligned} x(t) + 2y(t) + 2e^t &= 3x(t) + 4y(t) + e^{2t} \\ y(t) &= -\frac{e^{2t}}{2} - x(t) + e^t \end{aligned} \quad (3)$$

Taking derivative of the above w.r.t. t gives

$$y'(t) = -e^{2t} - x'(t) + e^t \quad (4)$$

Substituting (3,4) in (1) to eliminate $y(t), y'(t)$ gives

$$\begin{aligned} -e^{2t} + e^t &= -x(t) - e^{2t} + 4e^t \\ x(t) &= 3e^t \end{aligned} \quad (5)$$

Substituting (5) into (3) gives

$$y(t) = -\frac{e^{2t}}{2} - 2e^t \quad (7)$$

Since $x(t) = 3e^t$, is missing derivative in x then it is an algebraic equation. Solving for $x(t)$.

$$x(t) = 3e^t$$

Given now that we have the solution

$$x(t) = 3e^t \tag{6}$$

Then substituting (6) into (3) gives

$$y(t) = -\frac{e^{2t}}{2} - 2e^t \tag{7}$$

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 23

```
dsolve([diff(x(t),t)+diff(y(t),t)-x(t)-2*y(t)=2*exp(t),diff(x(t),t)+diff(y(t),t)-3*x(t)-4*y(t)
```

$$x(t) = 3e^t$$

$$y(t) = -\frac{e^{2t}}{2} - 2e^t$$

✓ Solution by Mathematica

Time used: 0.013 (sec). Leaf size: 25

```
DSolve[{x'[t]+y'[t]-x[t]-2*y[t]==2*Exp[t],x'[t]+y'[t]-3*x[t]-4*y[t]==Exp[2*t]},{x[t],y[t]},t
```

$$x(t) \rightarrow 3e^t$$

$$y(t) \rightarrow -\frac{1}{2}e^t(e^t + 4)$$

16.5 problem 5

- 16.5.1 Solution using Matrix exponential method 4379
- 16.5.2 Solution using explicit Eigenvalue and Eigenvector method . . . 4381
- 16.5.3 Maple step by step solution 4386

Internal problem ID [11932]

Internal file name [OUTPUT/11941_Saturday_April_13_2024_10_26_39_PM_92028239/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 7, Systems of linear differential equations. Section 7.1. Exercises page 277

Problem number: 5.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**system of linear ODEs**"

Solve

$$\begin{aligned}x'(t) &= 3x(t) + 2y(t) - e^t + e^{-t} \\y'(t) &= -5x(t) - 3y(t) + 2e^t - e^{-t}\end{aligned}$$

16.5.1 Solution using Matrix exponential method

In this method, we will assume we have found the matrix exponential e^{At} already. There are different methods to determine this but will not be shown here. This is a system of linear ODE's given as

$$\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} 3 & 2 \\ -5 & -3 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} + \begin{bmatrix} -e^t + e^{-t} \\ 2e^t - e^{-t} \end{bmatrix}$$

Since the system is nonhomogeneous, then the solution is given by

$$\vec{x}(t) = \vec{x}_h(t) + \vec{x}_p(t)$$

Where $\vec{x}_h(t)$ is the homogeneous solution to $\vec{x}'(t) = A\vec{x}(t)$ and $\vec{x}_p(t)$ is a particular solution to $\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$. The particular solution will be found using variation

of parameters method applied to the fundamental matrix. For the above matrix A , the matrix exponential can be found to be

$$e^{At} = \begin{bmatrix} \cos(t) + 3 \sin(t) & 2 \sin(t) \\ -5 \sin(t) & \cos(t) - 3 \sin(t) \end{bmatrix}$$

Therefore the homogeneous solution is

$$\begin{aligned} \vec{x}_h(t) &= e^{At} \vec{c} \\ &= \begin{bmatrix} \cos(t) + 3 \sin(t) & 2 \sin(t) \\ -5 \sin(t) & \cos(t) - 3 \sin(t) \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} \\ &= \begin{bmatrix} (\cos(t) + 3 \sin(t)) c_1 + 2 \sin(t) c_2 \\ -5 \sin(t) c_1 + (\cos(t) - 3 \sin(t)) c_2 \end{bmatrix} \\ &= \begin{bmatrix} (3c_1 + 2c_2) \sin(t) + c_1 \cos(t) \\ (-5c_1 - 3c_2) \sin(t) + c_2 \cos(t) \end{bmatrix} \end{aligned}$$

The particular solution given by

$$\vec{x}_p(t) = e^{At} \int e^{-At} \vec{G}(t) dt$$

But

$$\begin{aligned} e^{-At} &= (e^{At})^{-1} \\ &= \begin{bmatrix} \cos(t) - 3 \sin(t) & -2 \sin(t) \\ 5 \sin(t) & \cos(t) + 3 \sin(t) \end{bmatrix} \end{aligned}$$

Hence

$$\begin{aligned} \vec{x}_p(t) &= \begin{bmatrix} \cos(t) + 3 \sin(t) & 2 \sin(t) \\ -5 \sin(t) & \cos(t) - 3 \sin(t) \end{bmatrix} \int \begin{bmatrix} \cos(t) - 3 \sin(t) & -2 \sin(t) \\ 5 \sin(t) & \cos(t) + 3 \sin(t) \end{bmatrix} \begin{bmatrix} -e^t + e^{-t} \\ 2e^t - e^{-t} \end{bmatrix} dt \\ &= \begin{bmatrix} \cos(t) + 3 \sin(t) & 2 \sin(t) \\ -5 \sin(t) & \cos(t) - 3 \sin(t) \end{bmatrix} \begin{bmatrix} -\sin(t) (e^t - e^{-t}) \\ \frac{(\cos(t) + 3 \sin(t))(e^t - e^{-t})}{2} \end{bmatrix} \\ &= \begin{bmatrix} 0 \\ \frac{e^t}{2} - \frac{e^{-t}}{2} \end{bmatrix} \end{aligned}$$

Hence the complete solution is

$$\begin{aligned}\vec{x}(t) &= \vec{x}_h(t) + \vec{x}_p(t) \\ &= \begin{bmatrix} (3c_1 + 2c_2) \sin(t) + c_1 \cos(t) \\ (-5c_1 - 3c_2) \sin(t) + c_2 \cos(t) + \frac{e^t}{2} - \frac{e^{-t}}{2} \end{bmatrix}\end{aligned}$$

16.5.2 Solution using explicit Eigenvalue and Eigenvector method

This is a system of linear ODE's given as

$$\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} 3 & 2 \\ -5 & -3 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} + \begin{bmatrix} -e^t + e^{-t} \\ 2e^t - e^{-t} \end{bmatrix}$$

Since the system is nonhomogeneous, then the solution is given by

$$\vec{x}(t) = \vec{x}_h(t) + \vec{x}_p(t)$$

Where $\vec{x}_h(t)$ is the homogeneous solution to $\vec{x}'(t) = A\vec{x}(t)$ and $\vec{x}_p(t)$ is a particular solution to $\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$. The particular solution will be found using variation of parameters method applied to the fundamental matrix.

The first step is find the homogeneous solution. We start by finding the eigenvalues of A . This is done by solving the following equation for the eigenvalues λ

$$\det(A - \lambda I) = 0$$

Expanding gives

$$\det \left(\begin{bmatrix} 3 & 2 \\ -5 & -3 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) = 0$$

Therefore

$$\det \left(\begin{bmatrix} 3 - \lambda & 2 \\ -5 & -3 - \lambda \end{bmatrix} \right) = 0$$

Which gives the characteristic equation

$$\lambda^2 + 1 = 0$$

The roots of the above are the eigenvalues.

$$\lambda_1 = i$$

$$\lambda_2 = -i$$

This table summarises the above result

eigenvalue	algebraic multiplicity	type of eigenvalue
i	1	complex eigenvalue
$-i$	1	complex eigenvalue

Now the eigenvector for each eigenvalue are found.

Considering the eigenvalue $\lambda_1 = -i$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} 3 & 2 \\ -5 & -3 \end{bmatrix} - (-i) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 3+i & 2 \\ -5 & -3+i \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{cc|c} 3+i & 2 & 0 \\ -5 & -3+i & 0 \end{array} \right]$$

$$R_2 = R_2 + \left(\frac{3}{2} - \frac{i}{2} \right) R_1 \implies \left[\begin{array}{cc|c} 3+i & 2 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} 3+i & 2 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = (-\frac{3}{5} + \frac{i}{5})t\}$

Hence the solution is

$$\begin{bmatrix} \left(-\frac{3}{5} + \frac{i}{5}\right)t \\ t \end{bmatrix} = \begin{bmatrix} \left(-\frac{3}{5} + \frac{i}{5}\right)t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} \left(-\frac{3}{5} + \frac{i}{5}\right)t \\ t \end{bmatrix} = t \begin{bmatrix} -\frac{3}{5} + \frac{i}{5} \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} \left(-\frac{3}{5} + \frac{i}{5}\right)t \\ t \end{bmatrix} = \begin{bmatrix} -\frac{3}{5} + \frac{i}{5} \\ 1 \end{bmatrix}$$

Which is normalized to

$$\begin{bmatrix} \left(-\frac{3}{5} + \frac{i}{5}\right)t \\ t \end{bmatrix} = \begin{bmatrix} -3 + i \\ 5 \end{bmatrix}$$

Considering the eigenvalue $\lambda_2 = i$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} 3 & 2 \\ -5 & -3 \end{bmatrix} - (i) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 3-i & 2 \\ -5 & -3-i \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{cc|c} 3-i & 2 & 0 \\ -5 & -3-i & 0 \end{array} \right]$$

$$R_2 = R_2 + \left(\frac{3}{2} + \frac{i}{2}\right) R_1 \implies \left[\begin{array}{cc|c} 3-i & 2 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} 3-i & 2 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = (-\frac{3}{5} - \frac{i}{5})t\}$

Hence the solution is

$$\begin{bmatrix} (-\frac{3}{5} - \frac{i}{5})t \\ t \end{bmatrix} = \begin{bmatrix} (-\frac{3}{5} - \frac{i}{5})t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} (-\frac{3}{5} - \frac{i}{5})t \\ t \end{bmatrix} = t \begin{bmatrix} -\frac{3}{5} - \frac{i}{5} \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} (-\frac{3}{5} - \frac{i}{5})t \\ t \end{bmatrix} = \begin{bmatrix} -\frac{3}{5} - \frac{i}{5} \\ 1 \end{bmatrix}$$

Which is normalized to

$$\begin{bmatrix} (-\frac{3}{5} - \frac{i}{5})t \\ t \end{bmatrix} = \begin{bmatrix} -3 - i \\ 5 \end{bmatrix}$$

The following table gives a summary of this result. It shows for each eigenvalue the algebraic multiplicity m , and its geometric multiplicity k and the eigenvectors associated with the eigenvalue. If $m > k$ then the eigenvalue is defective which means the number of normal linearly independent eigenvectors associated with this eigenvalue (called the geometric multiplicity k) does not equal the algebraic multiplicity m , and we need to determine an additional $m - k$ generalized eigenvectors for this eigenvalue.

eigenvalue	multiplicity		defective?	eigenvectors
	algebraic m	geometric k		
i	1	1	No	$\begin{bmatrix} -\frac{3}{5} - \frac{i}{5} \\ 1 \end{bmatrix}$
$-i$	1	1	No	$\begin{bmatrix} -\frac{3}{5} + \frac{i}{5} \\ 1 \end{bmatrix}$

Now that we found the eigenvalues and associated eigenvectors, we will go over each eigenvalue and generate the solution basis. The only problem we need to take care of is if the eigenvalue is defective. Therefore the homogeneous solution is

$$\vec{x}_h(t) = c_1 \vec{x}_1(t) + c_2 \vec{x}_2(t)$$

Which is written as

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = c_1 \begin{bmatrix} \left(-\frac{3}{5} - \frac{i}{5}\right) e^{it} \\ e^{it} \end{bmatrix} + c_2 \begin{bmatrix} \left(-\frac{3}{5} + \frac{i}{5}\right) e^{-it} \\ e^{-it} \end{bmatrix}$$

Now that we found homogeneous solution above, we need to find a particular solution $\vec{x}_p(t)$. We will use Variation of parameters. The fundamental matrix is

$$\Phi = \begin{bmatrix} \vec{x}_1 & \vec{x}_2 & \dots \end{bmatrix}$$

Where \vec{x}_i are the solution basis found above. Therefore the fundamental matrix is

$$\Phi(t) = \begin{bmatrix} \left(-\frac{3}{5} - \frac{i}{5}\right) e^{it} & \left(-\frac{3}{5} + \frac{i}{5}\right) e^{-it} \\ e^{it} & e^{-it} \end{bmatrix}$$

The particular solution is then given by

$$\vec{x}_p(t) = \Phi \int \Phi^{-1} \vec{G}(t) dt$$

But

$$\Phi^{-1} = \begin{bmatrix} \frac{5ie^{-it}}{2} & \left(\frac{1}{2} + \frac{3i}{2}\right) e^{-it} \\ -\frac{5ie^{it}}{2} & \left(\frac{1}{2} - \frac{3i}{2}\right) e^{it} \end{bmatrix}$$

Hence

$$\begin{aligned} \vec{x}_p(t) &= \begin{bmatrix} \left(-\frac{3}{5} - \frac{i}{5}\right) e^{it} & \left(-\frac{3}{5} + \frac{i}{5}\right) e^{-it} \\ e^{it} & e^{-it} \end{bmatrix} \int \begin{bmatrix} \frac{5ie^{-it}}{2} & \left(\frac{1}{2} + \frac{3i}{2}\right) e^{-it} \\ -\frac{5ie^{it}}{2} & \left(\frac{1}{2} - \frac{3i}{2}\right) e^{it} \end{bmatrix} \begin{bmatrix} -e^t + e^{-t} \\ 2e^t - e^{-t} \end{bmatrix} dt \\ &= \begin{bmatrix} \left(-\frac{3}{5} - \frac{i}{5}\right) e^{it} & \left(-\frac{3}{5} + \frac{i}{5}\right) e^{-it} \\ e^{it} & e^{-it} \end{bmatrix} \int \begin{bmatrix} \left(-\frac{1}{2} + i\right) e^{(-1-i)t} + \left(1 + \frac{i}{2}\right) e^{(1-i)t} \\ \left(-\frac{1}{2} - i\right) e^{(-1+i)t} + \left(1 - \frac{i}{2}\right) e^{(1+i)t} \end{bmatrix} dt \\ &= \begin{bmatrix} \left(-\frac{3}{5} - \frac{i}{5}\right) e^{it} & \left(-\frac{3}{5} + \frac{i}{5}\right) e^{-it} \\ e^{it} & e^{-it} \end{bmatrix} \begin{bmatrix} \left(\frac{1}{4} + \frac{3i}{4}\right) \left(-e^{(-1-i)t} + e^{(1-i)t}\right) \\ \left(\frac{1}{4} - \frac{3i}{4}\right) \left(-e^{(-1+i)t} + e^{(1+i)t}\right) \end{bmatrix} \\ &= \begin{bmatrix} 0 \\ \frac{e^t}{2} - \frac{e^{-t}}{2} \end{bmatrix} \end{aligned}$$

Now that we found particular solution, the final solution is

$$\vec{x}(t) = \vec{x}_h(t) + \vec{x}_p(t)$$

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} (-\frac{3}{5} - \frac{i}{5}) c_1 e^{it} \\ c_1 e^{it} \end{bmatrix} + \begin{bmatrix} (-\frac{3}{5} + \frac{i}{5}) c_2 e^{-it} \\ c_2 e^{-it} \end{bmatrix} + \begin{bmatrix} 0 \\ \frac{e^t}{2} - \frac{e^{-t}}{2} \end{bmatrix}$$

Which becomes

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} (-\frac{3}{5} - \frac{i}{5}) c_1 e^{it} + (-\frac{3}{5} + \frac{i}{5}) c_2 e^{-it} \\ c_1 e^{it} + c_2 e^{-it} + \frac{e^t}{2} - \frac{e^{-t}}{2} \end{bmatrix}$$

16.5.3 Maple step by step solution

Let's solve

$$[x'(t) = 3x(t) + 2y(t) - e^t + \frac{1}{e^t}, y'(t) = -5x(t) - 3y(t) + 2e^t - \frac{1}{e^t}]$$

- Define vector

$$\vec{x}(t) = \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}$$

- Convert system into a vector equation

$$\vec{x}'(t) = \begin{bmatrix} 3 & 2 \\ -5 & -3 \end{bmatrix} \cdot \vec{x}(t) + \begin{bmatrix} \frac{3x(t)e^t + 2y(t)e^t - (e^t)^2 + 1}{e^t} - 3x(t) - 2y(t) \\ -\frac{5x(t)e^t + 3y(t)e^t - 2(e^t)^2 + 1}{e^t} + 5x(t) + 3y(t) \end{bmatrix}$$

- System to solve

$$\vec{x}'(t) = \begin{bmatrix} 3 & 2 \\ -5 & -3 \end{bmatrix} \cdot \vec{x}(t)$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 3 & 2 \\ -5 & -3 \end{bmatrix}$$

- Rewrite the system as

$$\vec{x}'(t) = A \cdot \vec{x}(t)$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[-\mathbf{I}, \begin{bmatrix} -\frac{3}{5} + \frac{\mathbf{I}}{5} \\ 1 \end{bmatrix} \right], \left[\mathbf{I}, \begin{bmatrix} -\frac{3}{5} - \frac{\mathbf{I}}{5} \\ 1 \end{bmatrix} \right] \right]$$

- Consider complex eigenpair, complex conjugate eigenvalue can be ignored

$$\left[-\mathbf{I}, \begin{bmatrix} -\frac{3}{5} + \frac{\mathbf{I}}{5} \\ 1 \end{bmatrix} \right]$$

- Solution from eigenpair

$$e^{-\mathbf{I}t} \cdot \begin{bmatrix} -\frac{3}{5} + \frac{\mathbf{I}}{5} \\ 1 \end{bmatrix}$$

- Use Euler identity to write solution in terms of sin and cos

$$(\cos(t) - \mathbf{I} \sin(t)) \cdot \begin{bmatrix} -\frac{3}{5} + \frac{\mathbf{I}}{5} \\ 1 \end{bmatrix}$$

- Simplify expression

$$\begin{bmatrix} \left(-\frac{3}{5} + \frac{\mathbf{I}}{5}\right) (\cos(t) - \mathbf{I} \sin(t)) \\ \cos(t) - \mathbf{I} \sin(t) \end{bmatrix}$$

- Both real and imaginary parts are solutions to the homogeneous system

$$\left[\vec{x}_1(t) = \begin{bmatrix} -\frac{3 \cos(t)}{5} + \frac{\sin(t)}{5} \\ \cos(t) \end{bmatrix}, \vec{x}_2(t) = \begin{bmatrix} \frac{3 \sin(t)}{5} + \frac{\cos(t)}{5} \\ -\sin(t) \end{bmatrix} \right]$$

- General solution to the system of ODEs

$$\vec{x} = c_1 \vec{x}_1(t) + c_2 \vec{x}_2(t)$$

- Substitute solutions into the general solution

$$\vec{x} = \begin{bmatrix} c_2 \left(\frac{3 \sin(t)}{5} + \frac{\cos(t)}{5} \right) + c_1 \left(-\frac{3 \cos(t)}{5} + \frac{\sin(t)}{5} \right) \\ c_1 \cos(t) - c_2 \sin(t) \end{bmatrix}$$

- Substitute in vector of dependent variables

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} \frac{(-3c_1 + c_2) \cos(t)}{5} + \frac{\sin(t)(c_1 + 3c_2)}{5} \\ c_1 \cos(t) - c_2 \sin(t) \end{bmatrix}$$

- Solution to the system of ODEs

$$\left\{ x(t) = \frac{(-3c_1 + c_2) \cos(t)}{5} + \frac{\sin(t)(c_1 + 3c_2)}{5}, y(t) = c_1 \cos(t) - c_2 \sin(t) \right\}$$

✓ Solution by Maple

Time used: 0.031 (sec). Leaf size: 48

```
dsolve([2*diff(x(t),t)+diff(y(t),t)-x(t)-y(t)=exp(-t),diff(x(t),t)+diff(y(t),t)+2*x(t)+y(t)=
```

$$x(t) = c_1 \sin(t) + c_2 \cos(t)$$

$$y(t) = \frac{c_1 \cos(t)}{2} - \frac{3c_2 \cos(t)}{2} - \frac{3c_1 \sin(t)}{2} - \frac{c_2 \sin(t)}{2} + \frac{e^t}{2} - \frac{e^{-t}}{2}$$

✓ Solution by Mathematica

Time used: 0.229 (sec). Leaf size: 60

```
DSolve[{2*x'[t]+y'[t]-x[t]-y[t]==Exp[-t],x'[t]+y'[t]+2*x[t]+y[t]==Exp[t]},{x[t],y[t]},t,Incl
```

$$x(t) \rightarrow c_1 \cos(t) + (3c_1 + 2c_2) \sin(t)$$

$$y(t) \rightarrow \frac{1}{2}(-e^{-t} + e^t + 2c_2 \cos(t) - 2(5c_1 + 3c_2) \sin(t))$$

16.6 problem 6

- 16.6.1 Solution using Matrix exponential method 4389
- 16.6.2 Solution using explicit Eigenvalue and Eigenvector method . . . 4391
- 16.6.3 Maple step by step solution 4396

Internal problem ID [11933]

Internal file name [OUTPUT/11942_Sunday_April_14_2024_02_31_02_AM_19754612/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 7, Systems of linear differential equations. Section 7.1. Exercises page 277

Problem number: 6.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**system of linear ODEs**"

Solve

$$\begin{aligned}x'(t) &= -x(t) + t - e^t \\y'(t) &= 5x(t) + y(t) - t + 2e^t\end{aligned}$$

16.6.1 Solution using Matrix exponential method

In this method, we will assume we have found the matrix exponential e^{At} already. There are different methods to determine this but will not be shown here. This is a system of linear ODE's given as

$$\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} -1 & 0 \\ 5 & 1 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} + \begin{bmatrix} t - e^t \\ -t + 2e^t \end{bmatrix}$$

Since the system is nonhomogeneous, then the solution is given by

$$\vec{x}(t) = \vec{x}_h(t) + \vec{x}_p(t)$$

Where $\vec{x}_h(t)$ is the homogeneous solution to $\vec{x}'(t) = A\vec{x}(t)$ and $\vec{x}_p(t)$ is a particular solution to $\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$. The particular solution will be found using variation

of parameters method applied to the fundamental matrix. For the above matrix A , the matrix exponential can be found to be

$$e^{At} = \begin{bmatrix} e^{-t} & 0 \\ \frac{5e^t}{2} - \frac{5e^{-t}}{2} & e^t \end{bmatrix}$$

Therefore the homogeneous solution is

$$\begin{aligned} \vec{x}_h(t) &= e^{At} \vec{c} \\ &= \begin{bmatrix} e^{-t} & 0 \\ \frac{5e^t}{2} - \frac{5e^{-t}}{2} & e^t \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} \\ &= \begin{bmatrix} e^{-t}c_1 \\ \left(\frac{5e^t}{2} - \frac{5e^{-t}}{2}\right)c_1 + e^tc_2 \end{bmatrix} \end{aligned}$$

The particular solution given by

$$\vec{x}_p(t) = e^{At} \int e^{-At} \vec{G}(t) dt$$

But

$$\begin{aligned} e^{-At} &= (e^{At})^{-1} \\ &= \begin{bmatrix} e^t & 0 \\ -\frac{5e^t}{2} + \frac{5e^{-t}}{2} & e^{-t} \end{bmatrix} \end{aligned}$$

Hence

$$\begin{aligned} \vec{x}_p(t) &= \begin{bmatrix} e^{-t} & 0 \\ \frac{5e^t}{2} - \frac{5e^{-t}}{2} & e^t \end{bmatrix} \int \begin{bmatrix} e^t & 0 \\ -\frac{5e^t}{2} + \frac{5e^{-t}}{2} & e^{-t} \end{bmatrix} \begin{bmatrix} t - e^t \\ -t + 2e^t \end{bmatrix} dt \\ &= \begin{bmatrix} e^{-t} & 0 \\ \frac{5e^t}{2} - \frac{5e^{-t}}{2} & e^t \end{bmatrix} \begin{bmatrix} -\frac{e^{2t}}{2} + e^t(t-1) \\ \frac{3(-1-t)e^{-t}}{2} + \frac{5e^{2t}}{4} + \frac{5e^t(1-t)}{2} - \frac{t}{2} \end{bmatrix} \\ &= \begin{bmatrix} t - 1 - \frac{e^t}{2} \\ \frac{(-2t+5)e^t}{4} - 4t + 1 \end{bmatrix} \end{aligned}$$

Hence the complete solution is

$$\begin{aligned} \vec{x}(t) &= \vec{x}_h(t) + \vec{x}_p(t) \\ &= \begin{bmatrix} e^{-t}c_1 + t - 1 - \frac{e^t}{2} \\ -\frac{5e^{-t}c_1}{2} + \frac{(-2t+10c_1+4c_2+5)e^t}{4} - 4t + 1 \end{bmatrix} \end{aligned}$$

16.6.2 Solution using explicit Eigenvalue and Eigenvector method

This is a system of linear ODE's given as

$$\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} -1 & 0 \\ 5 & 1 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} + \begin{bmatrix} t - e^t \\ -t + 2e^t \end{bmatrix}$$

Since the system is nonhomogeneous, then the solution is given by

$$\vec{x}(t) = \vec{x}_h(t) + \vec{x}_p(t)$$

Where $\vec{x}_h(t)$ is the homogeneous solution to $\vec{x}'(t) = A\vec{x}(t)$ and $\vec{x}_p(t)$ is a particular solution to $\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$. The particular solution will be found using variation of parameters method applied to the fundamental matrix.

The first step is find the homogeneous solution. We start by finding the eigenvalues of A . This is done by solving the following equation for the eigenvalues λ

$$\det(A - \lambda I) = 0$$

Expanding gives

$$\det\left(\begin{bmatrix} -1 & 0 \\ 5 & 1 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}\right) = 0$$

Therefore

$$\det\left(\begin{bmatrix} -1 - \lambda & 0 \\ 5 & 1 - \lambda \end{bmatrix}\right) = 0$$

Since the matrix A is triangular matrix, then the determinant is the product of the elements along the diagonal. Therefore the above becomes

$$(-1 - \lambda)(1 - \lambda) = 0$$

The roots of the above are the eigenvalues.

$$\lambda_1 = 1$$

$$\lambda_2 = -1$$

This table summarises the above result

eigenvalue	algebraic multiplicity	type of eigenvalue
-1	1	real eigenvalue
1	1	real eigenvalue

Now the eigenvector for each eigenvalue are found.

Considering the eigenvalue $\lambda_1 = -1$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} -1 & 0 \\ 5 & 1 \end{bmatrix} - (-1) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 0 \\ 5 & 2 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{cc|c} 0 & 0 & 0 \\ 5 & 2 & 0 \end{array} \right]$$

Since the current pivot $A(1,1)$ is zero, then the current pivot row is replaced with a row with a non-zero pivot. Swapping row 1 and row 2 gives

$$\left[\begin{array}{cc|c} 5 & 2 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} 5 & 2 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = -\frac{2t}{5}\}$

Hence the solution is

$$\begin{bmatrix} -\frac{2t}{5} \\ t \end{bmatrix} = \begin{bmatrix} -\frac{2t}{5} \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} -\frac{2t}{5} \\ t \end{bmatrix} = t \begin{bmatrix} -\frac{2}{5} \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} -\frac{2}{5} \\ 1 \end{bmatrix} = \begin{bmatrix} -\frac{2}{5} \\ 1 \end{bmatrix}$$

Which is normalized to

$$\begin{bmatrix} -\frac{2t}{5} \\ t \end{bmatrix} = \begin{bmatrix} -2 \\ 5 \end{bmatrix}$$

Considering the eigenvalue $\lambda_2 = 1$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} -1 & 0 \\ 5 & 1 \end{bmatrix} - (1) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -2 & 0 \\ 5 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{cc|c} -2 & 0 & 0 \\ 5 & 0 & 0 \end{array} \right]$$

$$R_2 = R_2 + \frac{5R_1}{2} \implies \left[\begin{array}{cc|c} -2 & 0 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} -2 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = 0\}$

Hence the solution is

$$\begin{bmatrix} 0 \\ t \end{bmatrix} = \begin{bmatrix} 0 \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} 0 \\ t \end{bmatrix} = t \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} 0 \\ t \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

The following table gives a summary of this result. It shows for each eigenvalue the algebraic multiplicity m , and its geometric multiplicity k and the eigenvectors associated with the eigenvalue. If $m > k$ then the eigenvalue is defective which means the number of normal linearly independent eigenvectors associated with this eigenvalue (called the geometric multiplicity k) does not equal the algebraic multiplicity m , and we need to determine an additional $m - k$ generalized eigenvectors for this eigenvalue.

eigenvalue	multiplicity		defective?	eigenvectors
	algebraic m	geometric k		
1	1	1	No	$\begin{bmatrix} 0 \\ 1 \end{bmatrix}$
-1	1	1	No	$\begin{bmatrix} -\frac{2}{5} \\ 1 \end{bmatrix}$

Now that we found the eigenvalues and associated eigenvectors, we will go over each eigenvalue and generate the solution basis. The only problem we need to take care of is if the eigenvalue is defective. Since eigenvalue 1 is real and distinct then the corresponding eigenvector solution is

$$\begin{aligned} \vec{x}_1(t) &= \vec{v}_1 e^t \\ &= \begin{bmatrix} 0 \\ 1 \end{bmatrix} e^t \end{aligned}$$

Since eigenvalue -1 is real and distinct then the corresponding eigenvector solution is

$$\begin{aligned}\vec{x}_2(t) &= \vec{v}_2 e^{-t} \\ &= \begin{bmatrix} -\frac{2}{5} \\ 1 \end{bmatrix} e^{-t}\end{aligned}$$

Therefore the homogeneous solution is

$$\vec{x}_h(t) = c_1 \vec{x}_1(t) + c_2 \vec{x}_2(t)$$

Which is written as

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = c_1 \begin{bmatrix} 0 \\ e^t \end{bmatrix} + c_2 \begin{bmatrix} -\frac{2e^{-t}}{5} \\ e^{-t} \end{bmatrix}$$

Now that we found homogeneous solution above, we need to find a particular solution $\vec{x}_p(t)$. We will use Variation of parameters. The fundamental matrix is

$$\Phi = \begin{bmatrix} \vec{x}_1 & \vec{x}_2 & \cdots \end{bmatrix}$$

Where \vec{x}_i are the solution basis found above. Therefore the fundamental matrix is

$$\Phi(t) = \begin{bmatrix} 0 & -\frac{2e^{-t}}{5} \\ e^t & e^{-t} \end{bmatrix}$$

The particular solution is then given by

$$\vec{x}_p(t) = \Phi \int \Phi^{-1} \vec{G}(t) dt$$

But

$$\Phi^{-1} = \begin{bmatrix} \frac{5e^{-t}}{2} & e^{-t} \\ -\frac{5e^t}{2} & 0 \end{bmatrix}$$

Hence

$$\begin{aligned}
 \vec{x}_p(t) &= \begin{bmatrix} 0 & -\frac{2e^{-t}}{5} \\ e^t & e^{-t} \end{bmatrix} \int \begin{bmatrix} \frac{5e^{-t}}{2} & e^{-t} \\ -\frac{5e^t}{2} & 0 \end{bmatrix} \begin{bmatrix} t - e^t \\ -t + 2e^t \end{bmatrix} dt \\
 &= \begin{bmatrix} 0 & -\frac{2e^{-t}}{5} \\ e^t & e^{-t} \end{bmatrix} \int \begin{bmatrix} -\frac{1}{2} + \frac{3te^{-t}}{2} \\ \frac{5e^t(-t+e^t)}{2} \end{bmatrix} dt \\
 &= \begin{bmatrix} 0 & -\frac{2e^{-t}}{5} \\ e^t & e^{-t} \end{bmatrix} \begin{bmatrix} \frac{(-3t-3)e^{-t}}{2} - \frac{t}{2} \\ \frac{5e^{2t}}{4} + \frac{5e^t(1-t)}{2} \end{bmatrix} \\
 &= \begin{bmatrix} t - 1 - \frac{e^t}{2} \\ \frac{(-2t+5)e^t}{4} - 4t + 1 \end{bmatrix}
 \end{aligned}$$

Now that we found particular solution, the final solution is

$$\begin{aligned}
 \vec{x}(t) &= \vec{x}_h(t) + \vec{x}_p(t) \\
 \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} &= \begin{bmatrix} 0 \\ c_1 e^t \end{bmatrix} + \begin{bmatrix} -\frac{2c_2 e^{-t}}{5} \\ c_2 e^{-t} \end{bmatrix} + \begin{bmatrix} t - 1 - \frac{e^t}{2} \\ \frac{(-2t+5)e^t}{4} - 4t + 1 \end{bmatrix}
 \end{aligned}$$

Which becomes

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} -\frac{2c_2 e^{-t}}{5} + t - 1 - \frac{e^t}{2} \\ c_2 e^{-t} + \frac{(-2t+4c_1+5)e^t}{4} - 4t + 1 \end{bmatrix}$$

16.6.3 Maple step by step solution

Let's solve

$$[x'(t) = -x(t) + t - e^t, y'(t) = 5x(t) + y(t) - t + 2e^t]$$

- Define vector

$$\vec{x}(t) = \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}$$

- Convert system into a vector equation

$$\vec{x}'(t) = \begin{bmatrix} -1 & 0 \\ 5 & 1 \end{bmatrix} \cdot \vec{x}(t) + \begin{bmatrix} t - e^t \\ -t + 2e^t \end{bmatrix}$$

- System to solve

$$\vec{x}'(t) = \begin{bmatrix} -1 & 0 \\ 5 & 1 \end{bmatrix} \cdot \vec{x}(t) + \begin{bmatrix} t - e^t \\ -t + 2e^t \end{bmatrix}$$

- Define the forcing function

$$\vec{f}(t) = \begin{bmatrix} t - e^t \\ -t + 2e^t \end{bmatrix}$$

- Define the coefficient matrix

$$A = \begin{bmatrix} -1 & 0 \\ 5 & 1 \end{bmatrix}$$

- Rewrite the system as

$$\vec{x}'(t) = A \cdot \vec{x}(t) + \vec{f}$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[-1, \begin{bmatrix} -\frac{2}{5} \\ 1 \end{bmatrix} \right], \left[1, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[-1, \begin{bmatrix} -\frac{2}{5} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{x}_1 = e^{-t} \cdot \begin{bmatrix} -\frac{2}{5} \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[1, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{x}_2 = e^t \cdot \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

- General solution of the system of ODEs can be written in terms of the particular solution $\vec{x}_p(t)$

$$\vec{x}(t) = c_1 \vec{x}_1 + c_2 \vec{x}_2 + \vec{x}_p(t)$$

□ Fundamental matrix

- Let $\phi(t)$ be the matrix whose columns are the independent solutions of the homogeneous system

$$\phi(t) = \begin{bmatrix} -\frac{2e^{-t}}{5} & 0 \\ e^{-t} & e^t \end{bmatrix}$$

- The fundamental matrix, $\Phi(t)$ is a normalized version of $\phi(t)$ satisfying $\Phi(0) = I$ where I is the identity matrix

$$\Phi(t) = \phi(t) \cdot \frac{1}{\phi(0)}$$

- Substitute the value of $\phi(t)$ and $\phi(0)$

$$\Phi(t) = \begin{bmatrix} -\frac{2e^{-t}}{5} & 0 \\ e^{-t} & e^t \end{bmatrix} \cdot \frac{1}{\begin{bmatrix} -\frac{2}{5} & 0 \\ 1 & 1 \end{bmatrix}}$$

- Evaluate and simplify to get the fundamental matrix

$$\Phi(t) = \begin{bmatrix} e^{-t} & 0 \\ \frac{5e^t}{2} - \frac{5e^{-t}}{2} & e^t \end{bmatrix}$$

□ Find a particular solution of the system of ODEs using variation of parameters

- Let the particular solution be the fundamental matrix multiplied by $\vec{v}(t)$ and solve for $\vec{v}(t)$

$$\vec{x}_p(t) = \Phi(t) \cdot \vec{v}(t)$$

- Take the derivative of the particular solution

$$\vec{x}'_p(t) = \Phi'(t) \cdot \vec{v}(t) + \Phi(t) \cdot \vec{v}'(t)$$

- Substitute particular solution and its derivative into the system of ODEs

$$\Phi'(t) \cdot \vec{v}(t) + \Phi(t) \cdot \vec{v}'(t) = A \cdot \Phi(t) \cdot \vec{v}(t) + \vec{f}(t)$$

- The fundamental matrix has columns that are solutions to the homogeneous system so its derivative is $A \cdot \Phi(t)$

$$A \cdot \Phi(t) \cdot \vec{v}(t) + \Phi(t) \cdot \vec{v}'(t) = A \cdot \Phi(t) \cdot \vec{v}(t) + \vec{f}(t)$$

- Cancel like terms

$$\Phi(t) \cdot \vec{v}'(t) = \vec{f}(t)$$

- Multiply by the inverse of the fundamental matrix

$$\vec{v}'(t) = \frac{1}{\Phi(t)} \cdot \vec{f}(t)$$

- Integrate to solve for $\vec{v}(t)$

$$\vec{v}(t) = \int_0^t \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds$$

- Plug $\vec{v}(t)$ into the equation for the particular solution

$$\vec{x}_p(t) = \Phi(t) \cdot \left(\int_0^t \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds \right)$$

- Plug in the fundamental matrix and the forcing function and compute

$$\vec{x}_p(t) = \begin{bmatrix} -\frac{e^t}{2} + t - 1 + \frac{3e^{-t}}{2} \\ -\frac{15e^{-t}}{4} + \frac{(-2t+11)e^t}{4} - 4t + 1 \end{bmatrix}$$

- Plug particular solution back into general solution

$$\vec{x}(t) = c_1 \vec{x}_1 + c_2 \vec{x}_2 + \begin{bmatrix} -\frac{e^t}{2} + t - 1 + \frac{3e^{-t}}{2} \\ -\frac{15e^{-t}}{4} + \frac{(-2t+11)e^t}{4} - 4t + 1 \end{bmatrix}$$

- Substitute in vector of dependent variables

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} -\frac{2c_1 e^{-t}}{5} - \frac{e^t}{2} + t - 1 + \frac{3e^{-t}}{2} \\ \frac{(4c_1-15)e^{-t}}{4} + \frac{(-2t+4c_2+11)e^t}{4} - 4t + 1 \end{bmatrix}$$

- Solution to the system of ODEs

$$\left\{ x(t) = -\frac{2c_1 e^{-t}}{5} - \frac{e^t}{2} + t - 1 + \frac{3e^{-t}}{2}, y(t) = \frac{(4c_1-15)e^{-t}}{4} + \frac{(-2t+4c_2+11)e^t}{4} - 4t + 1 \right\}$$

✓ Solution by Maple

Time used: 0.031 (sec). Leaf size: 42

```
dsolve([2*diff(x(t),t)+diff(y(t),t)-3*x(t)-y(t)=t,diff(x(t),t)+diff(y(t),t)-4*x(t)-y(t)=exp(t)
```

$$x(t) = t - 1 - \frac{e^t}{2} + c_2 e^{-t}$$

$$y(t) = -\frac{5c_2 e^{-t}}{2} - 4t + 1 + c_1 e^t - \frac{e^t t}{2}$$

✓ Solution by Mathematica

Time used: 0.665 (sec). Leaf size: 72

```
DSolve[{2*x'[t]+y'[t]-3*x[t]-y[t]==t,x'[t]+y'[t]+4*x[t]-y[t]==Exp[t]},{x[t],y[t]},t,IncludeS
```

$$x(t) \rightarrow -\frac{t}{7} + \frac{e^t}{6} + c_1 e^{7t} - \frac{1}{49}$$
$$y(t) \rightarrow -\frac{4t}{7} - \frac{11}{6} c_1 e^{7t} + \frac{1}{36} e^t (6t - 11 + 66c_1 + 36c_2) - \frac{39}{49}$$

16.7 problem 7

16.7.1 Solution using Matrix exponential method	4401
16.7.2 Solution using explicit Eigenvalue and Eigenvector method . . .	4403
16.7.3 Maple step by step solution	4408

Internal problem ID [11934]

Internal file name [OUTPUT/11943_Sunday_April_14_2024_02_31_04_AM_22296256/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 7, Systems of linear differential equations. Section 7.1. Exercises page 277

Problem number: 7.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**system of linear ODEs**"

Solve

$$\begin{aligned}x'(t) &= -t + 2e^{3t} + 6y(t) \\y'(t) &= x(t) + t - e^{3t}\end{aligned}$$

16.7.1 Solution using Matrix exponential method

In this method, we will assume we have found the matrix exponential e^{At} already. There are different methods to determine this but will not be shown here. This is a system of linear ODE's given as

$$\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} 0 & 6 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} + \begin{bmatrix} 2e^{3t} - t \\ -e^{3t} + t \end{bmatrix}$$

Since the system is nonhomogeneous, then the solution is given by

$$\vec{x}(t) = \vec{x}_h(t) + \vec{x}_p(t)$$

Where $\vec{x}_h(t)$ is the homogeneous solution to $\vec{x}'(t) = A\vec{x}(t)$ and $\vec{x}_p(t)$ is a particular solution to $\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$. The particular solution will be found using variation

of parameters method applied to the fundamental matrix. For the above matrix A , the matrix exponential can be found to be

$$e^{At} = \begin{bmatrix} \frac{e^{\sqrt{6}t} + e^{-\sqrt{6}t}}{2} & \frac{(-e^{-\sqrt{6}t} + e^{\sqrt{6}t})\sqrt{6}}{2} \\ \frac{(-e^{-\sqrt{6}t} + e^{\sqrt{6}t})\sqrt{6}}{12} & \frac{e^{\sqrt{6}t} + e^{-\sqrt{6}t}}{2} \end{bmatrix}$$

Therefore the homogeneous solution is

$$\begin{aligned} \vec{x}_h(t) &= e^{At} \vec{c} \\ &= \begin{bmatrix} \frac{e^{\sqrt{6}t} + e^{-\sqrt{6}t}}{2} & \frac{(-e^{-\sqrt{6}t} + e^{\sqrt{6}t})\sqrt{6}}{2} \\ \frac{(-e^{-\sqrt{6}t} + e^{\sqrt{6}t})\sqrt{6}}{12} & \frac{e^{\sqrt{6}t} + e^{-\sqrt{6}t}}{2} \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} \\ &= \begin{bmatrix} \left(\frac{e^{\sqrt{6}t} + e^{-\sqrt{6}t}}{2}\right) c_1 + \frac{(-e^{-\sqrt{6}t} + e^{\sqrt{6}t})\sqrt{6} c_2}{2} \\ \frac{(-e^{-\sqrt{6}t} + e^{\sqrt{6}t})\sqrt{6} c_1}{12} + \left(\frac{e^{\sqrt{6}t} + e^{-\sqrt{6}t}}{2}\right) c_2 \end{bmatrix} \\ &= \begin{bmatrix} \frac{(-c_2\sqrt{6} + c_1)e^{-\sqrt{6}t}}{2} + \frac{e^{\sqrt{6}t}(c_2\sqrt{6} + c_1)}{2} \\ \frac{(-c_1\sqrt{6} + 6c_2)e^{-\sqrt{6}t}}{12} + \frac{e^{\sqrt{6}t}(c_1\sqrt{6} + 6c_2)}{12} \end{bmatrix} \end{aligned}$$

The particular solution given by

$$\vec{x}_p(t) = e^{At} \int e^{-At} \vec{G}(t) dt$$

But

$$\begin{aligned} e^{-At} &= (e^{At})^{-1} \\ &= \begin{bmatrix} \frac{e^{\sqrt{6}t} + e^{-\sqrt{6}t}}{2} & -\frac{(-e^{-\sqrt{6}t} + e^{\sqrt{6}t})\sqrt{6}}{2} \\ -\frac{(-e^{-\sqrt{6}t} + e^{\sqrt{6}t})\sqrt{6}}{12} & \frac{e^{\sqrt{6}t} + e^{-\sqrt{6}t}}{2} \end{bmatrix} \end{aligned}$$

Hence

$$\begin{aligned}
 \vec{x}_p(t) &= \begin{bmatrix} \frac{e^{\sqrt{6}t} + e^{-\sqrt{6}t}}{2} & \frac{(-e^{-\sqrt{6}t} + e^{\sqrt{6}t})\sqrt{6}}{2} \\ \frac{(-e^{-\sqrt{6}t} + e^{\sqrt{6}t})\sqrt{6}}{12} & \frac{e^{\sqrt{6}t} + e^{-\sqrt{6}t}}{2} \end{bmatrix} \int \begin{bmatrix} \frac{e^{\sqrt{6}t} + e^{-\sqrt{6}t}}{2} & -\frac{(-e^{-\sqrt{6}t} + e^{\sqrt{6}t})\sqrt{6}}{2} \\ -\frac{(-e^{-\sqrt{6}t} + e^{\sqrt{6}t})\sqrt{6}}{12} & \frac{e^{\sqrt{6}t} + e^{-\sqrt{6}t}}{2} \end{bmatrix} \begin{bmatrix} 2e^{3t} - t \\ -e^{3t} + t \end{bmatrix} \\
 &= \begin{bmatrix} \frac{e^{\sqrt{6}t} + e^{-\sqrt{6}t}}{2} & \frac{(-e^{-\sqrt{6}t} + e^{\sqrt{6}t})\sqrt{6}}{2} \\ \frac{(-e^{-\sqrt{6}t} + e^{\sqrt{6}t})\sqrt{6}}{12} & \frac{e^{\sqrt{6}t} + e^{-\sqrt{6}t}}{2} \end{bmatrix} \begin{bmatrix} -\frac{\sqrt{6}e^{-t(\sqrt{6}-3)}}{6} + \frac{(\sqrt{6}(t-1)-6t+1)e^{-\sqrt{6}t}}{12} + \frac{\sqrt{6}e^{t(\sqrt{6}+3)}}{6} - \frac{e^{\sqrt{6}t}}{6} \\ -\frac{e^{-t(\sqrt{6}-3)}}{6} + \frac{((-6t+1)\sqrt{6}+6t-6)e^{-\sqrt{6}t}}{72} - \frac{e^{t(\sqrt{6}+3)}}{6} + \frac{(6t-1)\sqrt{6}}{6} \end{bmatrix} \\
 &= \begin{bmatrix} -t + \frac{1}{6} \\ \frac{t}{6} - \frac{e^{3t}}{3} - \frac{1}{6} \end{bmatrix}
 \end{aligned}$$

Hence the complete solution is

$$\begin{aligned}
 \vec{x}(t) &= \vec{x}_h(t) + \vec{x}_p(t) \\
 &= \begin{bmatrix} \frac{(-3c_2\sqrt{6}+3c_1)e^{-\sqrt{6}t}}{6} + \frac{(3c_2\sqrt{6}+3c_1)e^{\sqrt{6}t}}{6} - t + \frac{1}{6} \\ \frac{(-c_1\sqrt{6}+6c_2)e^{-\sqrt{6}t}}{12} + \frac{e^{\sqrt{6}t}(c_1\sqrt{6}+6c_2)}{12} + \frac{t}{6} - \frac{e^{3t}}{3} - \frac{1}{6} \end{bmatrix}
 \end{aligned}$$

16.7.2 Solution using explicit Eigenvalue and Eigenvector method

This is a system of linear ODE's given as

$$\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} 0 & 6 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} + \begin{bmatrix} 2e^{3t} - t \\ -e^{3t} + t \end{bmatrix}$$

Since the system is nonhomogeneous, then the solution is given by

$$\vec{x}(t) = \vec{x}_h(t) + \vec{x}_p(t)$$

Where $\vec{x}_h(t)$ is the homogeneous solution to $\vec{x}'(t) = A\vec{x}(t)$ and $\vec{x}_p(t)$ is a particular solution to $\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$. The particular solution will be found using variation of parameters method applied to the fundamental matrix.

The first step is find the homogeneous solution. We start by finding the eigenvalues of A . This is done by solving the following equation for the eigenvalues λ

$$\det(A - \lambda I) = 0$$

Expanding gives

$$\det \left(\begin{bmatrix} 0 & 6 \\ 1 & 0 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) = 0$$

Therefore

$$\det \left(\begin{bmatrix} -\lambda & 6 \\ 1 & -\lambda \end{bmatrix} \right) = 0$$

Which gives the characteristic equation

$$\lambda^2 - 6 = 0$$

The roots of the above are the eigenvalues.

$$\begin{aligned} \lambda_1 &= \sqrt{6} \\ \lambda_2 &= -\sqrt{6} \end{aligned}$$

This table summarises the above result

eigenvalue	algebraic multiplicity	type of eigenvalue
$\sqrt{6}$	1	real eigenvalue
$-\sqrt{6}$	1	real eigenvalue

Now the eigenvector for each eigenvalue are found.

Considering the eigenvalue $\lambda_1 = \sqrt{6}$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\begin{aligned} \left(\begin{bmatrix} 0 & 6 \\ 1 & 0 \end{bmatrix} - (\sqrt{6}) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix} \\ \begin{bmatrix} -\sqrt{6} & 6 \\ 1 & -\sqrt{6} \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix} \end{aligned}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{cc|c} -\sqrt{6} & 6 & 0 \\ 1 & -\sqrt{6} & 0 \end{array} \right]$$

$$R_2 = R_2 + \frac{\sqrt{6} R_1}{6} \implies \left[\begin{array}{cc|c} -\sqrt{6} & 6 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\left[\begin{array}{cc} -\sqrt{6} & 6 \\ 0 & 0 \end{array} \right] \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = t\sqrt{6}\}$

Hence the solution is

$$\begin{bmatrix} t\sqrt{6} \\ t \end{bmatrix} = \begin{bmatrix} t\sqrt{6} \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} t\sqrt{6} \\ t \end{bmatrix} = t \begin{bmatrix} \sqrt{6} \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} t\sqrt{6} \\ t \end{bmatrix} = \begin{bmatrix} \sqrt{6} \\ 1 \end{bmatrix}$$

Considering the eigenvalue $\lambda_2 = -\sqrt{6}$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} 0 & 6 \\ 1 & 0 \end{bmatrix} - (-\sqrt{6}) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} \sqrt{6} & 6 \\ 1 & \sqrt{6} \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{cc|c} \sqrt{6} & 6 & 0 \\ 1 & \sqrt{6} & 0 \end{array} \right]$$

$$R_2 = R_2 - \frac{\sqrt{6} R_1}{6} \implies \left[\begin{array}{cc|c} \sqrt{6} & 6 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} \sqrt{6} & 6 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = -t\sqrt{6}\}$

Hence the solution is

$$\begin{bmatrix} -t\sqrt{6} \\ t \end{bmatrix} = \begin{bmatrix} -t\sqrt{6} \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} -t\sqrt{6} \\ t \end{bmatrix} = t \begin{bmatrix} -\sqrt{6} \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} -t\sqrt{6} \\ t \end{bmatrix} = \begin{bmatrix} -\sqrt{6} \\ 1 \end{bmatrix}$$

The following table gives a summary of this result. It shows for each eigenvalue the algebraic multiplicity m , and its geometric multiplicity k and the eigenvectors associated with the eigenvalue. If $m > k$ then the eigenvalue is defective which means the number of normal linearly independent eigenvectors associated with this eigenvalue (called the geometric multiplicity k) does not equal the algebraic multiplicity m , and we need to determine an additional $m - k$ generalized eigenvectors for this eigenvalue.

eigenvalue	multiplicity		defective?	eigenvectors
	algebraic m	geometric k		
$\sqrt{6}$	1	1	No	$\begin{bmatrix} \sqrt{6} \\ 1 \end{bmatrix}$
$-\sqrt{6}$	1	1	No	$\begin{bmatrix} -\sqrt{6} \\ 1 \end{bmatrix}$

Now that we found the eigenvalues and associated eigenvectors, we will go over each eigenvalue and generate the solution basis. The only problem we need to take care of is if the eigenvalue is defective. Since eigenvalue $\sqrt{6}$ is real and distinct then the corresponding eigenvector solution is

$$\begin{aligned}\vec{x}_1(t) &= \vec{v}_1 e^{\sqrt{6}t} \\ &= \begin{bmatrix} \sqrt{6} \\ 1 \end{bmatrix} e^{\sqrt{6}t}\end{aligned}$$

Since eigenvalue $-\sqrt{6}$ is real and distinct then the corresponding eigenvector solution is

$$\begin{aligned}\vec{x}_2(t) &= \vec{v}_2 e^{-\sqrt{6}t} \\ &= \begin{bmatrix} -\sqrt{6} \\ 1 \end{bmatrix} e^{-\sqrt{6}t}\end{aligned}$$

Therefore the homogeneous solution is

$$\vec{x}_h(t) = c_1 \vec{x}_1(t) + c_2 \vec{x}_2(t)$$

Which is written as

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = c_1 \begin{bmatrix} \sqrt{6} e^{\sqrt{6}t} \\ e^{\sqrt{6}t} \end{bmatrix} + c_2 \begin{bmatrix} -\sqrt{6} e^{-\sqrt{6}t} \\ e^{-\sqrt{6}t} \end{bmatrix}$$

Now that we found homogeneous solution above, we need to find a particular solution $\vec{x}_p(t)$. We will use Variation of parameters. The fundamental matrix is

$$\Phi = \begin{bmatrix} \vec{x}_1 & \vec{x}_2 & \cdots \end{bmatrix}$$

Where \vec{x}_i are the solution basis found above. Therefore the fundamental matrix is

$$\Phi(t) = \begin{bmatrix} \sqrt{6} e^{\sqrt{6}t} & -\sqrt{6} e^{-\sqrt{6}t} \\ e^{\sqrt{6}t} & e^{-\sqrt{6}t} \end{bmatrix}$$

The particular solution is then given by

$$\vec{x}_p(t) = \Phi \int \Phi^{-1} \vec{G}(t) dt$$

But

$$\Phi^{-1} = \begin{bmatrix} \frac{\sqrt{6}e^{-\sqrt{6}t}}{12} & \frac{e^{-\sqrt{6}t}}{2} \\ -\frac{\sqrt{6}e^{\sqrt{6}t}}{12} & \frac{e^{\sqrt{6}t}}{2} \end{bmatrix}$$

Hence

$$\begin{aligned} \vec{x}_p(t) &= \begin{bmatrix} \sqrt{6}e^{\sqrt{6}t} & -\sqrt{6}e^{-\sqrt{6}t} \\ e^{\sqrt{6}t} & e^{-\sqrt{6}t} \end{bmatrix} \int \begin{bmatrix} \frac{\sqrt{6}e^{-\sqrt{6}t}}{12} & \frac{e^{-\sqrt{6}t}}{2} \\ -\frac{\sqrt{6}e^{\sqrt{6}t}}{12} & \frac{e^{\sqrt{6}t}}{2} \end{bmatrix} \begin{bmatrix} 2e^{3t} - t \\ -e^{3t} + t \end{bmatrix} dt \\ &= \begin{bmatrix} \sqrt{6}e^{\sqrt{6}t} & -\sqrt{6}e^{-\sqrt{6}t} \\ e^{\sqrt{6}t} & e^{-\sqrt{6}t} \end{bmatrix} \int \begin{bmatrix} \frac{(\sqrt{6}-3)e^{-t(\sqrt{6}-3)}}{6} - \frac{te^{-\sqrt{6}t}(\sqrt{6}-6)}{12} \\ \frac{(-\sqrt{6}-3)e^{t(\sqrt{6}+3)}}{6} + \frac{te^{\sqrt{6}t}(\sqrt{6}+6)}{12} \end{bmatrix} dt \\ &= \begin{bmatrix} \sqrt{6}e^{\sqrt{6}t} & -\sqrt{6}e^{-\sqrt{6}t} \\ e^{\sqrt{6}t} & e^{-\sqrt{6}t} \end{bmatrix} \begin{bmatrix} -\frac{(2e^{3t} + (t-\frac{1}{6})\sqrt{6}-t+1)e^{-\sqrt{6}t}}{12} \\ -\frac{e^{t(\sqrt{6}+3)}}{6} + \frac{((6t-1)\sqrt{6}+6t-6)e^{\sqrt{6}t}}{72} \end{bmatrix} \\ &= \begin{bmatrix} -t + \frac{1}{6} \\ \frac{t}{6} - \frac{e^{3t}}{3} - \frac{1}{6} \end{bmatrix} \end{aligned}$$

Now that we found particular solution, the final solution is

$$\begin{aligned} \vec{x}(t) &= \vec{x}_h(t) + \vec{x}_p(t) \\ \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} &= \begin{bmatrix} c_1\sqrt{6}e^{\sqrt{6}t} \\ c_1e^{\sqrt{6}t} \end{bmatrix} + \begin{bmatrix} -c_2\sqrt{6}e^{-\sqrt{6}t} \\ c_2e^{-\sqrt{6}t} \end{bmatrix} + \begin{bmatrix} -t + \frac{1}{6} \\ \frac{t}{6} - \frac{e^{3t}}{3} - \frac{1}{6} \end{bmatrix} \end{aligned}$$

Which becomes

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} c_1\sqrt{6}e^{\sqrt{6}t} - c_2\sqrt{6}e^{-\sqrt{6}t} - t + \frac{1}{6} \\ c_1e^{\sqrt{6}t} + c_2e^{-\sqrt{6}t} + \frac{t}{6} - \frac{e^{3t}}{3} - \frac{1}{6} \end{bmatrix}$$

16.7.3 Maple step by step solution

Let's solve

$$\left[x'(t) = -t + 2(e^t)^3 + 6y(t), y'(t) = x(t) + t - (e^t)^3 \right]$$

- Define vector

$$\vec{x}(t) = \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}$$

- Convert system into a vector equation

$$\vec{x}'(t) = \begin{bmatrix} 0 & 6 \\ 1 & 0 \end{bmatrix} \cdot \vec{x}(t) + \begin{bmatrix} 2(e^t)^3 - t \\ -(e^t)^3 + t \end{bmatrix}$$

- System to solve

$$\vec{x}'(t) = \begin{bmatrix} 0 & 6 \\ 1 & 0 \end{bmatrix} \cdot \vec{x}(t) + \begin{bmatrix} 2(e^t)^3 - t \\ -(e^t)^3 + t \end{bmatrix}$$

- Define the forcing function

$$\vec{f}(t) = \begin{bmatrix} 2(e^t)^3 - t \\ -(e^t)^3 + t \end{bmatrix}$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 6 \\ 1 & 0 \end{bmatrix}$$

- Rewrite the system as

$$\vec{x}'(t) = A \cdot \vec{x}(t) + \vec{f}$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[\sqrt{6}, \begin{bmatrix} \sqrt{6} \\ 1 \end{bmatrix} \right], \left[-\sqrt{6}, \begin{bmatrix} -\sqrt{6} \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[\sqrt{6}, \begin{bmatrix} \sqrt{6} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{x}_1 = e^{\sqrt{6}t} \cdot \begin{bmatrix} \sqrt{6} \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[-\sqrt{6}, \begin{bmatrix} -\sqrt{6} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{x}_2 = e^{-\sqrt{6}t} \cdot \begin{bmatrix} -\sqrt{6} \\ 1 \end{bmatrix}$$

- General solution of the system of ODEs can be written in terms of the particular solution $\vec{x}_p(t)$
 $\vec{x}(t) = c_1 \vec{x}_1 + c_2 \vec{x}_2 + \vec{x}_p(t)$

□ Fundamental matrix

- Let $\phi(t)$ be the matrix whose columns are the independent solutions of the homogeneous system

$$\phi(t) = \begin{bmatrix} \sqrt{6}e^{\sqrt{6}t} & -\sqrt{6}e^{-\sqrt{6}t} \\ e^{\sqrt{6}t} & e^{-\sqrt{6}t} \end{bmatrix}$$

- The fundamental matrix, $\Phi(t)$ is a normalized version of $\phi(t)$ satisfying $\Phi(0) = I$ where I is the identity matrix

$$\Phi(t) = \phi(t) \cdot \frac{1}{\phi(0)}$$

- Substitute the value of $\phi(t)$ and $\phi(0)$

$$\Phi(t) = \begin{bmatrix} \sqrt{6}e^{\sqrt{6}t} & -\sqrt{6}e^{-\sqrt{6}t} \\ e^{\sqrt{6}t} & e^{-\sqrt{6}t} \end{bmatrix} \cdot \frac{1}{\begin{bmatrix} \sqrt{6} & -\sqrt{6} \\ 1 & 1 \end{bmatrix}}$$

- Evaluate and simplify to get the fundamental matrix

$$\Phi(t) = \begin{bmatrix} \frac{e^{\sqrt{6}t}}{2} + \frac{e^{-\sqrt{6}t}}{2} & \frac{(-e^{-\sqrt{6}t} + e^{\sqrt{6}t})\sqrt{6}}{2} \\ \frac{(-e^{-\sqrt{6}t} + e^{\sqrt{6}t})\sqrt{6}}{12} & \frac{e^{\sqrt{6}t}}{2} + \frac{e^{-\sqrt{6}t}}{2} \end{bmatrix}$$

□ Find a particular solution of the system of ODEs using variation of parameters

- Let the particular solution be the fundamental matrix multiplied by $\vec{v}(t)$ and solve for $\vec{v}(t)$

$$\vec{x}_p(t) = \Phi(t) \cdot \vec{v}(t)$$

- Take the derivative of the particular solution

$$\vec{x}'_p(t) = \Phi'(t) \cdot \vec{v}(t) + \Phi(t) \cdot \vec{v}'(t)$$

- Substitute particular solution and its derivative into the system of ODEs

$$\Phi'(t) \cdot \vec{v}(t) + \Phi(t) \cdot \vec{v}'(t) = A \cdot \Phi(t) \cdot \vec{v}(t) + \vec{f}(t)$$

- The fundamental matrix has columns that are solutions to the homogeneous system so its derivative is $A \cdot \Phi(t) \cdot \vec{v}(t) + \Phi(t) \cdot \vec{v}'(t) = A \cdot \Phi(t) \cdot \vec{v}(t) + \vec{f}(t)$

$$A \cdot \Phi(t) \cdot \vec{v}(t) + \Phi(t) \cdot \vec{v}'(t) = A \cdot \Phi(t) \cdot \vec{v}(t) + \vec{f}(t)$$

- Cancel like terms

$$\Phi(t) \cdot \vec{v}'(t) = \vec{f}(t)$$

- Multiply by the inverse of the fundamental matrix

$$\vec{v}'(t) = \frac{1}{\Phi(t)} \cdot \vec{f}(t)$$

- Integrate to solve for $\vec{v}(t)$

$$\vec{v}(t) = \int_0^t \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds$$

- Plug $\vec{v}(t)$ into the equation for the particular solution

$$\vec{x}_p(t) = \Phi(t) \cdot \left(\int_0^t \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds \right)$$

- Plug in the fundamental matrix and the forcing function and compute

$$\vec{x}_p(t) = \begin{bmatrix} \frac{(-3\sqrt{6}-1)e^{-\sqrt{6}t}}{12} + \frac{(3\sqrt{6}-1)e^{\sqrt{6}t}}{12} - t + \frac{1}{6} \\ \frac{(\sqrt{6}+18)e^{-\sqrt{6}t}}{72} + \frac{(-\sqrt{6}+18)e^{\sqrt{6}t}}{72} + \frac{t}{6} - \frac{e^{3t}}{3} - \frac{1}{6} \end{bmatrix}$$

- Plug particular solution back into general solution

$$\vec{x}(t) = c_1 \vec{x}_1 + c_2 \vec{x}_2 + \begin{bmatrix} \frac{(-3\sqrt{6}-1)e^{-\sqrt{6}t}}{12} + \frac{(3\sqrt{6}-1)e^{\sqrt{6}t}}{12} - t + \frac{1}{6} \\ \frac{(\sqrt{6}+18)e^{-\sqrt{6}t}}{72} + \frac{(-\sqrt{6}+18)e^{\sqrt{6}t}}{72} + \frac{t}{6} - \frac{e^{3t}}{3} - \frac{1}{6} \end{bmatrix}$$

- Substitute in vector of dependent variables

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} \frac{(-1+(-12c_2-3)\sqrt{6})e^{-\sqrt{6}t}}{12} + \frac{(-1+(12c_1+3)\sqrt{6})e^{\sqrt{6}t}}{12} - t + \frac{1}{6} \\ \frac{(72c_2+\sqrt{6}+18)e^{-\sqrt{6}t}}{72} + \frac{(72c_1-\sqrt{6}+18)e^{\sqrt{6}t}}{72} + \frac{t}{6} - \frac{e^{3t}}{3} - \frac{1}{6} \end{bmatrix}$$

- Solution to the system of ODEs

$$\begin{cases} x(t) = \frac{(-1+(-12c_2-3)\sqrt{6})e^{-\sqrt{6}t}}{12} + \frac{(-1+(12c_1+3)\sqrt{6})e^{\sqrt{6}t}}{12} - t + \frac{1}{6}, y(t) = \frac{(72c_2+\sqrt{6}+18)e^{-\sqrt{6}t}}{72} + \frac{(72c_1-\sqrt{6}+18)e^{\sqrt{6}t}}{72} + \frac{t}{6} - \frac{e^{3t}}{3} - \frac{1}{6} \end{cases}$$

✓ Solution by Maple

Time used: 0.031 (sec). Leaf size: 66

```
dsolve([diff(x(t),t)+diff(y(t),t)-x(t)-6*y(t)=exp(3*t),diff(x(t),t)+2*diff(y(t),t)-2*x(t)-6*y(t)=t),{x(t),y(t)},t,Incl
```

$$x(t) = e^{\sqrt{6}t}c_2 + e^{-\sqrt{6}t}c_1 - t + \frac{1}{6}$$
$$y(t) = \frac{\sqrt{6}e^{\sqrt{6}t}c_2}{6} - \frac{\sqrt{6}e^{-\sqrt{6}t}c_1}{6} - \frac{1}{6} + \frac{t}{6} - \frac{e^{3t}}{3}$$

✓ Solution by Mathematica

Time used: 8.119 (sec). Leaf size: 142

```
DSolve[{x'[t]+y'[t]-x[t]-6*y[t]==Exp[3*t],x'[t]+2*y'[t]-2*x[t]-6*y[t]==t},{x[t],y[t]},t,Incl
```

$$x(t) \rightarrow \frac{1}{6} \left(-6t + 3(c_1 - \sqrt{6}c_2) e^{-\sqrt{6}t} + 3(c_1 + \sqrt{6}c_2) e^{\sqrt{6}t} + 1 \right)$$
$$y(t) \rightarrow \frac{1}{12} e^{-\sqrt{6}t} \left(2e^{\sqrt{6}t}(t-1) - 4e^{(3+\sqrt{6})t} + (\sqrt{6}c_1 + 6c_2) e^{2\sqrt{6}t} - \sqrt{6}c_1 + 6c_2 \right)$$

16.8 problem 8

16.8.1 Solution using Matrix exponential method	4413
16.8.2 Solution using explicit Eigenvalue and Eigenvector method . . .	4415
16.8.3 Maple step by step solution	4420

Internal problem ID [11935]

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Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 7, Systems of linear differential equations. Section 7.1. Exercises page 277

Problem number: 8.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**system of linear ODEs**"

Solve

$$\begin{aligned}x'(t) &= 6t - 1 + 3y(t) \\y'(t) &= x(t) - 3t + 1\end{aligned}$$

16.8.1 Solution using Matrix exponential method

In this method, we will assume we have found the matrix exponential e^{At} already. There are different methods to determine this but will not be shown here. This is a system of linear ODE's given as

$$\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} 0 & 3 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} + \begin{bmatrix} 6t - 1 \\ 1 - 3t \end{bmatrix}$$

Since the system is nonhomogeneous, then the solution is given by

$$\vec{x}(t) = \vec{x}_h(t) + \vec{x}_p(t)$$

Where $\vec{x}_h(t)$ is the homogeneous solution to $\vec{x}'(t) = A\vec{x}(t)$ and $\vec{x}_p(t)$ is a particular solution to $\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$. The particular solution will be found using variation

of parameters method applied to the fundamental matrix. For the above matrix A , the matrix exponential can be found to be

$$e^{At} = \begin{bmatrix} \frac{e^{\sqrt{3}t} + e^{-\sqrt{3}t}}{2} & \frac{(-e^{-\sqrt{3}t} + e^{\sqrt{3}t})\sqrt{3}}{2} \\ \frac{(-e^{-\sqrt{3}t} + e^{\sqrt{3}t})\sqrt{3}}{6} & \frac{e^{\sqrt{3}t} + e^{-\sqrt{3}t}}{2} \end{bmatrix}$$

Therefore the homogeneous solution is

$$\begin{aligned} \vec{x}_h(t) &= e^{At} \vec{c} \\ &= \begin{bmatrix} \frac{e^{\sqrt{3}t} + e^{-\sqrt{3}t}}{2} & \frac{(-e^{-\sqrt{3}t} + e^{\sqrt{3}t})\sqrt{3}}{2} \\ \frac{(-e^{-\sqrt{3}t} + e^{\sqrt{3}t})\sqrt{3}}{6} & \frac{e^{\sqrt{3}t} + e^{-\sqrt{3}t}}{2} \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} \\ &= \begin{bmatrix} \left(\frac{e^{\sqrt{3}t} + e^{-\sqrt{3}t}}{2}\right) c_1 + \frac{(-e^{-\sqrt{3}t} + e^{\sqrt{3}t})\sqrt{3} c_2}{2} \\ \frac{(-e^{-\sqrt{3}t} + e^{\sqrt{3}t})\sqrt{3} c_1}{6} + \left(\frac{e^{\sqrt{3}t} + e^{-\sqrt{3}t}}{2}\right) c_2 \end{bmatrix} \\ &= \begin{bmatrix} \frac{(-c_2\sqrt{3} + c_1)e^{-\sqrt{3}t}}{2} + \frac{e^{\sqrt{3}t}(c_2\sqrt{3} + c_1)}{2} \\ \frac{(-c_1\sqrt{3} + 3c_2)e^{-\sqrt{3}t}}{6} + \frac{e^{\sqrt{3}t}(c_1\sqrt{3} + 3c_2)}{6} \end{bmatrix} \end{aligned}$$

The particular solution given by

$$\vec{x}_p(t) = e^{At} \int e^{-At} \vec{G}(t) dt$$

But

$$\begin{aligned} e^{-At} &= (e^{At})^{-1} \\ &= \begin{bmatrix} \frac{e^{\sqrt{3}t} + e^{-\sqrt{3}t}}{2} & -\frac{(-e^{-\sqrt{3}t} + e^{\sqrt{3}t})\sqrt{3}}{2} \\ -\frac{(-e^{-\sqrt{3}t} + e^{\sqrt{3}t})\sqrt{3}}{6} & \frac{e^{\sqrt{3}t} + e^{-\sqrt{3}t}}{2} \end{bmatrix} \end{aligned}$$

Hence

$$\begin{aligned}
 \vec{x}_p(t) &= \begin{bmatrix} \frac{e^{\sqrt{3}t} + e^{-\sqrt{3}t}}{2} & \frac{(-e^{-\sqrt{3}t} + e^{\sqrt{3}t})\sqrt{3}}{2} \\ \frac{(-e^{-\sqrt{3}t} + e^{\sqrt{3}t})\sqrt{3}}{6} & \frac{e^{\sqrt{3}t} + e^{-\sqrt{3}t}}{2} \end{bmatrix} \int \begin{bmatrix} \frac{e^{\sqrt{3}t} + e^{-\sqrt{3}t}}{2} & -\frac{(-e^{-\sqrt{3}t} + e^{\sqrt{3}t})\sqrt{3}}{2} \\ -\frac{(-e^{-\sqrt{3}t} + e^{\sqrt{3}t})\sqrt{3}}{6} & \frac{e^{\sqrt{3}t} + e^{-\sqrt{3}t}}{2} \end{bmatrix} \begin{bmatrix} 6t - 1 \\ 1 - 3t \end{bmatrix} \\
 &= \begin{bmatrix} \frac{e^{\sqrt{3}t} + e^{-\sqrt{3}t}}{2} & \frac{(-e^{-\sqrt{3}t} + e^{\sqrt{3}t})\sqrt{3}}{2} \\ \frac{(-e^{-\sqrt{3}t} + e^{\sqrt{3}t})\sqrt{3}}{6} & \frac{e^{\sqrt{3}t} + e^{-\sqrt{3}t}}{2} \end{bmatrix} \begin{bmatrix} \frac{((4-6t)\sqrt{3}+9t-9)e^{-\sqrt{3}t}}{6} + e^{\sqrt{3}t}\left(\left(t - \frac{2}{3}\right)\sqrt{3} + \frac{3t}{2} - \frac{3}{2}\right) \\ \frac{((3t-3)\sqrt{3}-6t+4)e^{-\sqrt{3}t}}{6} - \frac{e^{\sqrt{3}t}(\sqrt{3}(t-1)+2t-\frac{4}{3})}{2} \end{bmatrix} \\
 &= \begin{bmatrix} 3t - 3 \\ -2t + \frac{4}{3} \end{bmatrix}
 \end{aligned}$$

Hence the complete solution is

$$\begin{aligned}
 \vec{x}(t) &= \vec{x}_h(t) + \vec{x}_p(t) \\
 &= \begin{bmatrix} \frac{(-c_2\sqrt{3}+c_1)e^{-\sqrt{3}t}}{2} + \frac{e^{\sqrt{3}t}(c_2\sqrt{3}+c_1)}{2} + 3t - 3 \\ \frac{(-c_1\sqrt{3}+3c_2)e^{-\sqrt{3}t}}{6} + \frac{e^{\sqrt{3}t}(c_1\sqrt{3}+3c_2)}{6} - 2t + \frac{4}{3} \end{bmatrix}
 \end{aligned}$$

16.8.2 Solution using explicit Eigenvalue and Eigenvector method

This is a system of linear ODE's given as

$$\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} 0 & 3 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} + \begin{bmatrix} 6t - 1 \\ 1 - 3t \end{bmatrix}$$

Since the system is nonhomogeneous, then the solution is given by

$$\vec{x}(t) = \vec{x}_h(t) + \vec{x}_p(t)$$

Where $\vec{x}_h(t)$ is the homogeneous solution to $\vec{x}'(t) = A\vec{x}(t)$ and $\vec{x}_p(t)$ is a particular solution to $\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$. The particular solution will be found using variation of parameters method applied to the fundamental matrix.

The first step is find the homogeneous solution. We start by finding the eigenvalues of A . This is done by solving the following equation for the eigenvalues λ

$$\det(A - \lambda I) = 0$$

Expanding gives

$$\det \left(\begin{bmatrix} 0 & 3 \\ 1 & 0 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) = 0$$

Therefore

$$\det \left(\begin{bmatrix} -\lambda & 3 \\ 1 & -\lambda \end{bmatrix} \right) = 0$$

Which gives the characteristic equation

$$\lambda^2 - 3 = 0$$

The roots of the above are the eigenvalues.

$$\lambda_1 = \sqrt{3}$$
$$\lambda_2 = -\sqrt{3}$$

This table summarises the above result

eigenvalue	algebraic multiplicity	type of eigenvalue
$\sqrt{3}$	1	real eigenvalue
$-\sqrt{3}$	1	real eigenvalue

Now the eigenvector for each eigenvalue are found.

Considering the eigenvalue $\lambda_1 = \sqrt{3}$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} 0 & 3 \\ 1 & 0 \end{bmatrix} - (\sqrt{3}) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$
$$\begin{bmatrix} -\sqrt{3} & 3 \\ 1 & -\sqrt{3} \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{cc|c} -\sqrt{3} & 3 & 0 \\ 1 & -\sqrt{3} & 0 \end{array} \right]$$

$$R_2 = R_2 + \frac{\sqrt{3} R_1}{3} \implies \left[\begin{array}{cc|c} -\sqrt{3} & 3 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\left[\begin{array}{cc} -\sqrt{3} & 3 \\ 0 & 0 \end{array} \right] \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = t\sqrt{3}\}$

Hence the solution is

$$\begin{bmatrix} t\sqrt{3} \\ t \end{bmatrix} = \begin{bmatrix} t\sqrt{3} \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} t\sqrt{3} \\ t \end{bmatrix} = t \begin{bmatrix} \sqrt{3} \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} t\sqrt{3} \\ t \end{bmatrix} = \begin{bmatrix} \sqrt{3} \\ 1 \end{bmatrix}$$

Considering the eigenvalue $\lambda_2 = -\sqrt{3}$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} 0 & 3 \\ 1 & 0 \end{bmatrix} - (-\sqrt{3}) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} \sqrt{3} & 3 \\ 1 & \sqrt{3} \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{cc|c} \sqrt{3} & 3 & 0 \\ 1 & \sqrt{3} & 0 \end{array} \right]$$

$$R_2 = R_2 - \frac{\sqrt{3} R_1}{3} \implies \left[\begin{array}{cc|c} \sqrt{3} & 3 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} \sqrt{3} & 3 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = -t\sqrt{3}\}$

Hence the solution is

$$\begin{bmatrix} -t\sqrt{3} \\ t \end{bmatrix} = \begin{bmatrix} -t\sqrt{3} \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} -t\sqrt{3} \\ t \end{bmatrix} = t \begin{bmatrix} -\sqrt{3} \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} -t\sqrt{3} \\ t \end{bmatrix} = \begin{bmatrix} -\sqrt{3} \\ 1 \end{bmatrix}$$

The following table gives a summary of this result. It shows for each eigenvalue the algebraic multiplicity m , and its geometric multiplicity k and the eigenvectors associated with the eigenvalue. If $m > k$ then the eigenvalue is defective which means the number of normal linearly independent eigenvectors associated with this eigenvalue (called the geometric multiplicity k) does not equal the algebraic multiplicity m , and we need to determine an additional $m - k$ generalized eigenvectors for this eigenvalue.

eigenvalue	multiplicity		defective?	eigenvectors
	algebraic m	geometric k		
$\sqrt{3}$	1	1	No	$\begin{bmatrix} \sqrt{3} \\ 1 \end{bmatrix}$
$-\sqrt{3}$	1	1	No	$\begin{bmatrix} -\sqrt{3} \\ 1 \end{bmatrix}$

Now that we found the eigenvalues and associated eigenvectors, we will go over each eigenvalue and generate the solution basis. The only problem we need to take care of is if the eigenvalue is defective. Since eigenvalue $\sqrt{3}$ is real and distinct then the corresponding eigenvector solution is

$$\begin{aligned}\vec{x}_1(t) &= \vec{v}_1 e^{\sqrt{3}t} \\ &= \begin{bmatrix} \sqrt{3} \\ 1 \end{bmatrix} e^{\sqrt{3}t}\end{aligned}$$

Since eigenvalue $-\sqrt{3}$ is real and distinct then the corresponding eigenvector solution is

$$\begin{aligned}\vec{x}_2(t) &= \vec{v}_2 e^{-\sqrt{3}t} \\ &= \begin{bmatrix} -\sqrt{3} \\ 1 \end{bmatrix} e^{-\sqrt{3}t}\end{aligned}$$

Therefore the homogeneous solution is

$$\vec{x}_h(t) = c_1 \vec{x}_1(t) + c_2 \vec{x}_2(t)$$

Which is written as

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = c_1 \begin{bmatrix} \sqrt{3} e^{\sqrt{3}t} \\ e^{\sqrt{3}t} \end{bmatrix} + c_2 \begin{bmatrix} -\sqrt{3} e^{-\sqrt{3}t} \\ e^{-\sqrt{3}t} \end{bmatrix}$$

Now that we found homogeneous solution above, we need to find a particular solution $\vec{x}_p(t)$. We will use Variation of parameters. The fundamental matrix is

$$\Phi = \begin{bmatrix} \vec{x}_1 & \vec{x}_2 & \cdots \end{bmatrix}$$

Where \vec{x}_i are the solution basis found above. Therefore the fundamental matrix is

$$\Phi(t) = \begin{bmatrix} \sqrt{3} e^{\sqrt{3}t} & -\sqrt{3} e^{-\sqrt{3}t} \\ e^{\sqrt{3}t} & e^{-\sqrt{3}t} \end{bmatrix}$$

The particular solution is then given by

$$\vec{x}_p(t) = \Phi \int \Phi^{-1} \vec{G}(t) dt$$

But

$$\Phi^{-1} = \begin{bmatrix} \frac{\sqrt{3}e^{-\sqrt{3}t}}{6} & \frac{e^{-\sqrt{3}t}}{2} \\ -\frac{\sqrt{3}e^{\sqrt{3}t}}{6} & \frac{e^{\sqrt{3}t}}{2} \end{bmatrix}$$

Hence

$$\begin{aligned} \vec{x}_p(t) &= \begin{bmatrix} \sqrt{3}e^{\sqrt{3}t} & -\sqrt{3}e^{-\sqrt{3}t} \\ e^{\sqrt{3}t} & e^{-\sqrt{3}t} \end{bmatrix} \int \begin{bmatrix} \frac{\sqrt{3}e^{-\sqrt{3}t}}{6} & \frac{e^{-\sqrt{3}t}}{2} \\ -\frac{\sqrt{3}e^{\sqrt{3}t}}{6} & \frac{e^{\sqrt{3}t}}{2} \end{bmatrix} \begin{bmatrix} 6t-1 \\ 1-3t \end{bmatrix} dt \\ &= \begin{bmatrix} \sqrt{3}e^{\sqrt{3}t} & -\sqrt{3}e^{-\sqrt{3}t} \\ e^{\sqrt{3}t} & e^{-\sqrt{3}t} \end{bmatrix} \int \begin{bmatrix} \frac{(\sqrt{3}(6t-1)-9t+3)e^{-\sqrt{3}t}}{6} \\ \frac{((-6t+1)\sqrt{3}-9t+3)e^{\sqrt{3}t}}{6} \end{bmatrix} dt \\ &= \begin{bmatrix} \sqrt{3}e^{\sqrt{3}t} & -\sqrt{3}e^{-\sqrt{3}t} \\ e^{\sqrt{3}t} & e^{-\sqrt{3}t} \end{bmatrix} \begin{bmatrix} -\frac{(3\sqrt{3}t+\sqrt{3}+6)e^{-\sqrt{3}t}(6\sqrt{3}t-\sqrt{3}-9t+3)}{54t+18+18\sqrt{3}} \\ \frac{(3\sqrt{3}t+\sqrt{3}-6)e^{\sqrt{3}t}(6\sqrt{3}t-\sqrt{3}+9t-3)}{-54t-18+18\sqrt{3}} \end{bmatrix} \\ &= \begin{bmatrix} \frac{27t^3-9t^2-24t+6}{9t^2+6t-2} \\ \frac{-54t^3+36t-8}{-9+3(3t+1)^2} \end{bmatrix} \end{aligned}$$

Now that we found particular solution, the final solution is

$$\begin{aligned} \vec{x}(t) &= \vec{x}_h(t) + \vec{x}_p(t) \\ \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} &= \begin{bmatrix} c_1\sqrt{3}e^{\sqrt{3}t} \\ c_1e^{\sqrt{3}t} \end{bmatrix} + \begin{bmatrix} -c_2\sqrt{3}e^{-\sqrt{3}t} \\ c_2e^{-\sqrt{3}t} \end{bmatrix} + \begin{bmatrix} \frac{27t^3-9t^2-24t+6}{9t^2+6t-2} \\ \frac{-54t^3+36t-8}{-9+3(3t+1)^2} \end{bmatrix} \end{aligned}$$

Which becomes

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} c_1\sqrt{3}e^{\sqrt{3}t} - c_2\sqrt{3}e^{-\sqrt{3}t} + 3t - 3 \\ c_1e^{\sqrt{3}t} + c_2e^{-\sqrt{3}t} - 2t + \frac{4}{3} \end{bmatrix}$$

16.8.3 Maple step by step solution

Let's solve

$$[x'(t) = 6t - 1 + 3y(t), y'(t) = x(t) - 3t + 1]$$

- Define vector

$$\vec{x}(t) = \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}$$

- Convert system into a vector equation

$$\vec{x}'(t) = \begin{bmatrix} 0 & 3 \\ 1 & 0 \end{bmatrix} \cdot \vec{x}(t) + \begin{bmatrix} 6t - 1 \\ 1 - 3t \end{bmatrix}$$

- System to solve

$$\vec{x}'(t) = \begin{bmatrix} 0 & 3 \\ 1 & 0 \end{bmatrix} \cdot \vec{x}(t) + \begin{bmatrix} 6t - 1 \\ 1 - 3t \end{bmatrix}$$

- Define the forcing function

$$\vec{f}(t) = \begin{bmatrix} 6t - 1 \\ 1 - 3t \end{bmatrix}$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & 3 \\ 1 & 0 \end{bmatrix}$$

- Rewrite the system as

$$\vec{x}'(t) = A \cdot \vec{x}(t) + \vec{f}$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[\sqrt{3}, \begin{bmatrix} \sqrt{3} \\ 1 \end{bmatrix} \right], \left[-\sqrt{3}, \begin{bmatrix} -\sqrt{3} \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[\sqrt{3}, \begin{bmatrix} \sqrt{3} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{x}_1 = e^{\sqrt{3}t} \cdot \begin{bmatrix} \sqrt{3} \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[-\sqrt{3}, \begin{bmatrix} -\sqrt{3} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{x}_2 = e^{-\sqrt{3}t} \cdot \begin{bmatrix} -\sqrt{3} \\ 1 \end{bmatrix}$$

- General solution of the system of ODEs can be written in terms of the particular solution $\vec{x}_p(t)$

$$\vec{x}(t) = c_1 \vec{x}_1 + c_2 \vec{x}_2 + \vec{x}_p(t)$$

- Fundamental matrix

- Let $\phi(t)$ be the matrix whose columns are the independent solutions of the homogeneous system

$$\phi(t) = \begin{bmatrix} \sqrt{3}e^{\sqrt{3}t} & -\sqrt{3}e^{-\sqrt{3}t} \\ e^{\sqrt{3}t} & e^{-\sqrt{3}t} \end{bmatrix}$$

- The fundamental matrix, $\Phi(t)$ is a normalized version of $\phi(t)$ satisfying $\Phi(0) = I$ where I is the identity matrix

$$\Phi(t) = \phi(t) \cdot \frac{1}{\phi(0)}$$

- Substitute the value of $\phi(t)$ and $\phi(0)$

$$\Phi(t) = \begin{bmatrix} \sqrt{3}e^{\sqrt{3}t} & -\sqrt{3}e^{-\sqrt{3}t} \\ e^{\sqrt{3}t} & e^{-\sqrt{3}t} \end{bmatrix} \cdot \frac{1}{\begin{bmatrix} \sqrt{3} & -\sqrt{3} \\ 1 & 1 \end{bmatrix}}$$

- Evaluate and simplify to get the fundamental matrix

$$\Phi(t) = \begin{bmatrix} \frac{e^{\sqrt{3}t}}{2} + \frac{e^{-\sqrt{3}t}}{2} & \frac{(-e^{-\sqrt{3}t} + e^{\sqrt{3}t})\sqrt{3}}{2} \\ \frac{(-e^{-\sqrt{3}t} + e^{\sqrt{3}t})\sqrt{3}}{6} & \frac{e^{\sqrt{3}t}}{2} + \frac{e^{-\sqrt{3}t}}{2} \end{bmatrix}$$

- Find a particular solution of the system of ODEs using variation of parameters

- Let the particular solution be the fundamental matrix multiplied by $\vec{v}(t)$ and solve for $\vec{v}(t)$

$$\vec{x}_p(t) = \Phi(t) \cdot \vec{v}(t)$$

- Take the derivative of the particular solution

$$\vec{x}'_p(t) = \Phi'(t) \cdot \vec{v}(t) + \Phi(t) \cdot \vec{v}'(t)$$

- Substitute particular solution and its derivative into the system of ODEs

$$\Phi'(t) \cdot \vec{v}(t) + \Phi(t) \cdot \vec{v}'(t) = A \cdot \Phi(t) \cdot \vec{v}(t) + \vec{f}(t)$$

- The fundamental matrix has columns that are solutions to the homogeneous system so its derivative is $A \cdot \Phi(t) \cdot \vec{v}(t) + \Phi(t) \cdot \vec{v}'(t) = A \cdot \Phi(t) \cdot \vec{v}(t) + \vec{f}(t)$

$$A \cdot \Phi(t) \cdot \vec{v}(t) + \Phi(t) \cdot \vec{v}'(t) = A \cdot \Phi(t) \cdot \vec{v}(t) + \vec{f}(t)$$

- Cancel like terms

$$\Phi(t) \cdot \vec{v}'(t) = \vec{f}(t)$$

- Multiply by the inverse of the fundamental matrix

$$\vec{v}'(t) = \frac{1}{\Phi(t)} \cdot \vec{f}(t)$$

- Integrate to solve for $\vec{v}(t)$

$$\vec{v}(t) = \int_0^t \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds$$

- Plug $\vec{v}(t)$ into the equation for the particular solution

$$\vec{x}_p(t) = \Phi(t) \cdot \left(\int_0^t \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds \right)$$

- Plug in the fundamental matrix and the forcing function and compute

$$\vec{x}_p(t) = \begin{bmatrix} \frac{(4\sqrt{3}+9)e^{-\sqrt{3}t}}{6} + \frac{(-4\sqrt{3}+9)e^{\sqrt{3}t}}{6} + 3t - 3 \\ \frac{(-3\sqrt{3}-4)e^{-\sqrt{3}t}}{6} + \frac{(3\sqrt{3}-4)e^{\sqrt{3}t}}{6} - 2t + \frac{4}{3} \end{bmatrix}$$

- Plug particular solution back into general solution

$$\vec{x}(t) = c_1 \vec{x}_1 + c_2 \vec{x}_2 + \begin{bmatrix} \frac{(4\sqrt{3}+9)e^{-\sqrt{3}t}}{6} + \frac{(-4\sqrt{3}+9)e^{\sqrt{3}t}}{6} + 3t - 3 \\ \frac{(-3\sqrt{3}-4)e^{-\sqrt{3}t}}{6} + \frac{(3\sqrt{3}-4)e^{\sqrt{3}t}}{6} - 2t + \frac{4}{3} \end{bmatrix}$$

- Substitute in vector of dependent variables

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} \frac{(9+(-6c_2+4)\sqrt{3})e^{-\sqrt{3}t}}{6} + \frac{(9+(-4+6c_1)\sqrt{3})e^{\sqrt{3}t}}{6} + 3t - 3 \\ \frac{(6c_2-3\sqrt{3}-4)e^{-\sqrt{3}t}}{6} + \frac{(6c_1+3\sqrt{3}-4)e^{\sqrt{3}t}}{6} - 2t + \frac{4}{3} \end{bmatrix}$$

- Solution to the system of ODEs

$$\begin{cases} x(t) = \frac{(9+(-6c_2+4)\sqrt{3})e^{-\sqrt{3}t}}{6} + \frac{(9+(-4+6c_1)\sqrt{3})e^{\sqrt{3}t}}{6} + 3t - 3, \\ y(t) = \frac{(6c_2-3\sqrt{3}-4)e^{-\sqrt{3}t}}{6} + \frac{(6c_1+3\sqrt{3}-4)e^{\sqrt{3}t}}{6} - 2t + \frac{4}{3} \end{cases}$$

✓ Solution by Maple

Time used: 0.032 (sec). Leaf size: 60

```
dsolve([diff(x(t),t)+diff(y(t),t)-x(t)-3*y(t)=3*t,diff(x(t),t)+2*diff(y(t),t)-2*x(t)-3*y(t)=
```

$$\begin{aligned}x(t) &= e^{\sqrt{3}t}c_2 + e^{-\sqrt{3}t}c_1 + 3t - 3 \\y(t) &= \frac{\sqrt{3}e^{\sqrt{3}t}c_2}{3} - \frac{\sqrt{3}e^{-\sqrt{3}t}c_1}{3} + \frac{4}{3} - 2t\end{aligned}$$

✓ Solution by Mathematica

Time used: 6.866 (sec). Leaf size: 137

```
DSolve[{x'[t]+y'[t]-x[t]-3*y[t]==3*t,x'[t]+2*y'[t]-2*x[t]-3*y[t]==1},{x[t],y[t]},t,IncludeSi
```

$$\begin{aligned}x(t) &\rightarrow \frac{1}{2}e^{-\sqrt{3}t}\left(6e^{\sqrt{3}t}(t-1) + (c_1 + \sqrt{3}c_2)e^{2\sqrt{3}t} + c_1 - \sqrt{3}c_2\right) \\y(t) &\rightarrow \frac{1}{6}e^{-\sqrt{3}t}\left(e^{\sqrt{3}t}(8-12t) + (\sqrt{3}c_1 + 3c_2)e^{2\sqrt{3}t} - \sqrt{3}c_1 + 3c_2\right)\end{aligned}$$

16.9 problem 9

Internal problem ID [11936]

Internal file name [OUTPUT/11945_Sunday_April_14_2024_02_31_07_AM_5011505/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 7, Systems of linear differential equations. Section 7.1. Exercises page 277

Problem number: 9.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "system of linear ODEs"

Solve

$$x'(t) + y'(t) = -2y(t) + \sin(t)$$

$$x'(t) + y'(t) = x(t) + y(t)$$

The system is

$$x'(t) + y'(t) = -2y(t) + \sin(t) \quad (1)$$

$$x'(t) + y'(t) = x(t) + y(t) \quad (2)$$

Since the left side is the same, this implies

$$\begin{aligned} -2y(t) + \sin(t) &= x(t) + y(t) \\ y(t) &= -\frac{x(t)}{3} + \frac{\sin(t)}{3} \end{aligned} \quad (3)$$

Taking derivative of the above w.r.t. t gives

$$y'(t) = -\frac{x'(t)}{3} + \frac{\cos(t)}{3} \quad (4)$$

Substituting (3,4) in (1) to eliminate $y(t)$, $y'(t)$ gives

$$\begin{aligned} \frac{2x'(t)}{3} + \frac{\cos(t)}{3} &= \frac{2x(t)}{3} + \frac{\sin(t)}{3} \\ x'(t) &= x(t) + \frac{\sin(t)}{2} - \frac{\cos(t)}{2} \end{aligned} \quad (5)$$

Which is now solved for $x(t)$.

Entering Linear first order ODE solver. In canonical form a linear first order is

$$x'(t) + p(t)x(t) = q(t)$$

Where here

$$p(t) = -1$$
$$q(t) = \frac{\sin(t)}{2} - \frac{\cos(t)}{2}$$

Hence the ode is

$$-x(t) + x'(t) = \frac{\sin(t)}{2} - \frac{\cos(t)}{2}$$

The integrating factor μ is

$$\mu = e^{\int(-1)dt}$$
$$= e^{-t}$$

The ode becomes

$$\frac{d}{dt}(\mu x) = (\mu) \left(\frac{\sin(t)}{2} - \frac{\cos(t)}{2} \right)$$
$$\frac{d}{dt}(e^{-t}x) = (e^{-t}) \left(\frac{\sin(t)}{2} - \frac{\cos(t)}{2} \right)$$
$$d(e^{-t}x) = \left(\frac{(\sin(t) - \cos(t)) e^{-t}}{2} \right) dt$$

Integrating gives

$$e^{-t}x = \int \frac{(\sin(t) - \cos(t)) e^{-t}}{2} dt$$
$$e^{-t}x = -\frac{e^{-t} \sin(t)}{2} + c_1$$

Dividing both sides by the integrating factor $\mu = e^{-t}$ results in

$$x(t) = -\frac{e^t e^{-t} \sin(t)}{2} + c_1 e^t$$

which simplifies to

$$x(t) = c_1 e^t - \frac{\sin(t)}{2}$$

Given now that we have the solution

$$x(t) = c_1 e^t - \frac{\sin(t)}{2} \quad (6)$$

Then substituting (6) into (3) gives

$$y(t) = -\frac{c_1 e^t}{3} + \frac{\sin(t)}{2} \quad (7)$$

✓ Solution by Maple

Time used: 0.062 (sec). Leaf size: 27

```
dsolve([diff(x(t),t)+diff(y(t),t)+2*y(t)=sin(t),diff(x(t),t)+diff(y(t),t)-x(t)-y(t)=0],sings
```

$$x(t) = c_1 e^t - \frac{\sin(t)}{2}$$
$$y(t) = -\frac{c_1 e^t}{3} + \frac{\sin(t)}{2}$$

✓ Solution by Mathematica

Time used: 0.02 (sec). Leaf size: 38

```
DSolve[{x'[t]+y'[t]+2*y[t]==Sin[t],x'[t]+y'[t]-x[t]-y[t]==0},{x[t],y[t]},t,IncludeSingularSo
```

$$x(t) \rightarrow \frac{1}{2}(-\sin(t) + 3c_1 e^t)$$
$$y(t) \rightarrow \frac{1}{2}(\sin(t) - c_1 e^t)$$

16.10 problem 10

16.10.1 Solution using Matrix exponential method	4428
16.10.2 Solution using explicit Eigenvalue and Eigenvector method . . .	4430
16.10.3 Maple step by step solution	4435

Internal problem ID [11937]

Internal file name [OUTPUT/11946_Sunday_April_14_2024_02_31_07_AM_84888398/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 7, Systems of linear differential equations. Section 7.1. Exercises page 277

Problem number: 10.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "system of linear ODEs"

Solve

$$\begin{aligned}x'(t) &= \frac{3x(t)}{2} - \frac{3y(t)}{2} + \frac{t}{2} + \frac{1}{2} \\y'(t) &= -\frac{x(t)}{2} + \frac{5y(t)}{2} - \frac{t}{2} + \frac{1}{2}\end{aligned}$$

16.10.1 Solution using Matrix exponential method

In this method, we will assume we have found the matrix exponential e^{At} already. There are different methods to determine this but will not be shown here. This is a system of linear ODE's given as

$$\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} \frac{3}{2} & -\frac{3}{2} \\ -\frac{1}{2} & \frac{5}{2} \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} + \begin{bmatrix} \frac{t}{2} + \frac{1}{2} \\ -\frac{t}{2} + \frac{1}{2} \end{bmatrix}$$

Since the system is nonhomogeneous, then the solution is given by

$$\vec{x}(t) = \vec{x}_h(t) + \vec{x}_p(t)$$

Where $\vec{x}_h(t)$ is the homogeneous solution to $\vec{x}'(t) = A\vec{x}(t)$ and $\vec{x}_p(t)$ is a particular solution to $\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$. The particular solution will be found using variation

of parameters method applied to the fundamental matrix. For the above matrix A , the matrix exponential can be found to be

$$e^{At} = \begin{bmatrix} \frac{3e^t}{4} + \frac{e^{3t}}{4} & -\frac{3e^{3t}}{4} + \frac{3e^t}{4} \\ -\frac{e^{3t}}{4} + \frac{e^t}{4} & \frac{e^t}{4} + \frac{3e^{3t}}{4} \end{bmatrix}$$

Therefore the homogeneous solution is

$$\begin{aligned} \vec{x}_h(t) &= e^{At} \vec{c} \\ &= \begin{bmatrix} \frac{3e^t}{4} + \frac{e^{3t}}{4} & -\frac{3e^{3t}}{4} + \frac{3e^t}{4} \\ -\frac{e^{3t}}{4} + \frac{e^t}{4} & \frac{e^t}{4} + \frac{3e^{3t}}{4} \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} \\ &= \begin{bmatrix} \left(\frac{3e^t}{4} + \frac{e^{3t}}{4}\right) c_1 + \left(-\frac{3e^{3t}}{4} + \frac{3e^t}{4}\right) c_2 \\ \left(-\frac{e^{3t}}{4} + \frac{e^t}{4}\right) c_1 + \left(\frac{e^t}{4} + \frac{3e^{3t}}{4}\right) c_2 \end{bmatrix} \\ &= \begin{bmatrix} \frac{(c_1 - 3c_2)e^{3t}}{4} + \frac{3e^t(c_1 + c_2)}{4} \\ \frac{(-c_1 + 3c_2)e^{3t}}{4} + \frac{e^t(c_1 + c_2)}{4} \end{bmatrix} \end{aligned}$$

The particular solution given by

$$\vec{x}_p(t) = e^{At} \int e^{-At} \vec{G}(t) dt$$

But

$$\begin{aligned} e^{-At} &= (e^{At})^{-1} \\ &= \begin{bmatrix} \frac{e^{-3t}(3e^{2t}+1)}{4} & \frac{3e^{-3t}(e^{2t}-1)}{4} \\ \frac{e^{-3t}(e^{2t}-1)}{4} & \frac{e^{-3t}(e^{2t}+3)}{4} \end{bmatrix} \end{aligned}$$

Hence

$$\begin{aligned} \vec{x}_p(t) &= \begin{bmatrix} \frac{3e^t}{4} + \frac{e^{3t}}{4} & -\frac{3e^{3t}}{4} + \frac{3e^t}{4} \\ -\frac{e^{3t}}{4} + \frac{e^t}{4} & \frac{e^t}{4} + \frac{3e^{3t}}{4} \end{bmatrix} \int \begin{bmatrix} \frac{e^{-3t}(3e^{2t}+1)}{4} & \frac{3e^{-3t}(e^{2t}-1)}{4} \\ \frac{e^{-3t}(e^{2t}-1)}{4} & \frac{e^{-3t}(e^{2t}+3)}{4} \end{bmatrix} \begin{bmatrix} \frac{t}{2} + \frac{1}{2} \\ -\frac{t}{2} + \frac{1}{2} \end{bmatrix} dt \\ &= \begin{bmatrix} \frac{3e^t}{4} + \frac{e^{3t}}{4} & -\frac{3e^{3t}}{4} + \frac{3e^t}{4} \\ -\frac{e^{3t}}{4} + \frac{e^t}{4} & \frac{e^t}{4} + \frac{3e^{3t}}{4} \end{bmatrix} \begin{bmatrix} \frac{(-6t+1)e^{-3t}}{36} - \frac{3e^{-t}}{4} \\ \frac{(6t-1)e^{-3t}}{36} - \frac{e^{-t}}{4} \end{bmatrix} \\ &= \begin{bmatrix} -\frac{13}{18} - \frac{t}{6} \\ -\frac{5}{18} + \frac{t}{6} \end{bmatrix} \end{aligned}$$

Hence the complete solution is

$$\begin{aligned}\vec{x}(t) &= \vec{x}_h(t) + \vec{x}_p(t) \\ &= \begin{bmatrix} \frac{(c_1-3c_2)e^{3t}}{4} + \frac{3e^t(c_1+c_2)}{4} - \frac{13}{18} - \frac{t}{6} \\ \frac{(-c_1+3c_2)e^{3t}}{4} + \frac{e^t(c_1+c_2)}{4} - \frac{5}{18} + \frac{t}{6} \end{bmatrix}\end{aligned}$$

16.10.2 Solution using explicit Eigenvalue and Eigenvector method

This is a system of linear ODE's given as

$$\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} \frac{3}{2} & -\frac{3}{2} \\ -\frac{1}{2} & \frac{5}{2} \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} + \begin{bmatrix} \frac{t}{2} + \frac{1}{2} \\ -\frac{t}{2} + \frac{1}{2} \end{bmatrix}$$

Since the system is nonhomogeneous, then the solution is given by

$$\vec{x}(t) = \vec{x}_h(t) + \vec{x}_p(t)$$

Where $\vec{x}_h(t)$ is the homogeneous solution to $\vec{x}'(t) = A\vec{x}(t)$ and $\vec{x}_p(t)$ is a particular solution to $\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$. The particular solution will be found using variation of parameters method applied to the fundamental matrix.

The first step is find the homogeneous solution. We start by finding the eigenvalues of A . This is done by solving the following equation for the eigenvalues λ

$$\det(A - \lambda I) = 0$$

Expanding gives

$$\det\left(\begin{bmatrix} \frac{3}{2} & -\frac{3}{2} \\ -\frac{1}{2} & \frac{5}{2} \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}\right) = 0$$

Therefore

$$\det\left(\begin{bmatrix} \frac{3}{2} - \lambda & -\frac{3}{2} \\ -\frac{1}{2} & \frac{5}{2} - \lambda \end{bmatrix}\right) = 0$$

Which gives the characteristic equation

$$\lambda^2 - 4\lambda + 3 = 0$$

The roots of the above are the eigenvalues.

$$\lambda_1 = 3$$

$$\lambda_2 = 1$$

This table summarises the above result

eigenvalue	algebraic multiplicity	type of eigenvalue
1	1	real eigenvalue
3	1	real eigenvalue

Now the eigenvector for each eigenvalue are found.

Considering the eigenvalue $\lambda_1 = 1$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} \frac{3}{2} & -\frac{3}{2} \\ -\frac{1}{2} & \frac{5}{2} \end{bmatrix} - (1) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} \frac{1}{2} & -\frac{3}{2} \\ -\frac{1}{2} & \frac{3}{2} \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{cc|c} \frac{1}{2} & -\frac{3}{2} & 0 \\ -\frac{1}{2} & \frac{3}{2} & 0 \end{array} \right]$$

$$R_2 = R_2 + R_1 \implies \left[\begin{array}{cc|c} \frac{1}{2} & -\frac{3}{2} & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} \frac{1}{2} & -\frac{3}{2} \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = 3t\}$

Hence the solution is

$$\begin{bmatrix} 3t \\ t \end{bmatrix} = \begin{bmatrix} 3t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} 3t \\ t \end{bmatrix} = t \begin{bmatrix} 3 \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} 3t \\ t \end{bmatrix} = \begin{bmatrix} 3 \\ 1 \end{bmatrix}$$

Considering the eigenvalue $\lambda_2 = 3$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} \frac{3}{2} & -\frac{3}{2} \\ -\frac{1}{2} & \frac{5}{2} \end{bmatrix} - (3) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -\frac{3}{2} & -\frac{3}{2} \\ -\frac{1}{2} & -\frac{1}{2} \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{cc|c} -\frac{3}{2} & -\frac{3}{2} & 0 \\ -\frac{1}{2} & -\frac{1}{2} & 0 \end{array} \right]$$

$$R_2 = R_2 - \frac{R_1}{3} \implies \left[\begin{array}{cc|c} -\frac{3}{2} & -\frac{3}{2} & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} -\frac{3}{2} & -\frac{3}{2} \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = -t\}$

Hence the solution is

$$\begin{bmatrix} -t \\ t \end{bmatrix} = \begin{bmatrix} -t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} -t \\ t \end{bmatrix} = t \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

The following table gives a summary of this result. It shows for each eigenvalue the algebraic multiplicity m , and its geometric multiplicity k and the eigenvectors associated with the eigenvalue. If $m > k$ then the eigenvalue is defective which means the number of normal linearly independent eigenvectors associated with this eigenvalue (called the geometric multiplicity k) does not equal the algebraic multiplicity m , and we need to determine an additional $m - k$ generalized eigenvectors for this eigenvalue.

eigenvalue	multiplicity		defective?	eigenvectors
	algebraic m	geometric k		
3	1	1	No	$\begin{bmatrix} -1 \\ 1 \end{bmatrix}$
1	1	1	No	$\begin{bmatrix} 3 \\ 1 \end{bmatrix}$

Now that we found the eigenvalues and associated eigenvectors, we will go over each eigenvalue and generate the solution basis. The only problem we need to take care of is if the eigenvalue is defective. Since eigenvalue 3 is real and distinct then the corresponding eigenvector solution is

$$\begin{aligned} \vec{x}_1(t) &= \vec{v}_1 e^{3t} \\ &= \begin{bmatrix} -1 \\ 1 \end{bmatrix} e^{3t} \end{aligned}$$

Since eigenvalue 1 is real and distinct then the corresponding eigenvector solution is

$$\begin{aligned}\vec{x}_2(t) &= \vec{v}_2 e^t \\ &= \begin{bmatrix} 3 \\ 1 \end{bmatrix} e^t\end{aligned}$$

Therefore the homogeneous solution is

$$\vec{x}_h(t) = c_1 \vec{x}_1(t) + c_2 \vec{x}_2(t)$$

Which is written as

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = c_1 \begin{bmatrix} -e^{3t} \\ e^{3t} \end{bmatrix} + c_2 \begin{bmatrix} 3e^t \\ e^t \end{bmatrix}$$

Now that we found homogeneous solution above, we need to find a particular solution $\vec{x}_p(t)$. We will use Variation of parameters. The fundamental matrix is

$$\Phi = \begin{bmatrix} \vec{x}_1 & \vec{x}_2 & \cdots \end{bmatrix}$$

Where \vec{x}_i are the solution basis found above. Therefore the fundamental matrix is

$$\Phi(t) = \begin{bmatrix} -e^{3t} & 3e^t \\ e^{3t} & e^t \end{bmatrix}$$

The particular solution is then given by

$$\vec{x}_p(t) = \Phi \int \Phi^{-1} \vec{G}(t) dt$$

But

$$\Phi^{-1} = \begin{bmatrix} -\frac{e^{-3t}}{4} & \frac{3e^{-3t}}{4} \\ \frac{e^{-t}}{4} & \frac{e^{-t}}{4} \end{bmatrix}$$

Hence

$$\begin{aligned}
 \vec{x}_p(t) &= \begin{bmatrix} -e^{3t} & 3e^t \\ e^{3t} & e^t \end{bmatrix} \int \begin{bmatrix} -\frac{e^{-3t}}{4} & \frac{3e^{-3t}}{4} \\ \frac{e^{-t}}{4} & \frac{e^{-t}}{4} \end{bmatrix} \begin{bmatrix} \frac{t}{2} + \frac{1}{2} \\ -\frac{t}{2} + \frac{1}{2} \end{bmatrix} dt \\
 &= \begin{bmatrix} -e^{3t} & 3e^t \\ e^{3t} & e^t \end{bmatrix} \int \begin{bmatrix} -\frac{e^{-3t}(2t-1)}{4} \\ \frac{e^{-t}}{4} \end{bmatrix} dt \\
 &= \begin{bmatrix} -e^{3t} & 3e^t \\ e^{3t} & e^t \end{bmatrix} \begin{bmatrix} \frac{(6t-1)e^{-3t}}{36} \\ -\frac{e^{-t}}{4} \end{bmatrix} \\
 &= \begin{bmatrix} -\frac{13}{18} - \frac{t}{6} \\ -\frac{5}{18} + \frac{t}{6} \end{bmatrix}
 \end{aligned}$$

Now that we found particular solution, the final solution is

$$\begin{aligned}
 \vec{x}(t) &= \vec{x}_h(t) + \vec{x}_p(t) \\
 \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} &= \begin{bmatrix} -c_1 e^{3t} \\ c_1 e^{3t} \end{bmatrix} + \begin{bmatrix} 3c_2 e^t \\ c_2 e^t \end{bmatrix} + \begin{bmatrix} -\frac{13}{18} - \frac{t}{6} \\ -\frac{5}{18} + \frac{t}{6} \end{bmatrix}
 \end{aligned}$$

Which becomes

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} -c_1 e^{3t} + 3c_2 e^t - \frac{13}{18} - \frac{t}{6} \\ c_1 e^{3t} + c_2 e^t - \frac{5}{18} + \frac{t}{6} \end{bmatrix}$$

16.10.3 Maple step by step solution

Let's solve

$$\left[x'(t) = \frac{3x(t)}{2} - \frac{3y(t)}{2} + \frac{t}{2} + \frac{1}{2}, y'(t) = -\frac{x(t)}{2} + \frac{5y(t)}{2} - \frac{t}{2} + \frac{1}{2} \right]$$

- Define vector

$$\vec{x}(t) = \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}$$

- Convert system into a vector equation

$$\vec{x}'(t) = \begin{bmatrix} \frac{3}{2} & -\frac{3}{2} \\ -\frac{1}{2} & \frac{5}{2} \end{bmatrix} \cdot \vec{x}(t) + \begin{bmatrix} \frac{t}{2} + \frac{1}{2} \\ -\frac{t}{2} + \frac{1}{2} \end{bmatrix}$$

- System to solve

$$\vec{x}'(t) = \begin{bmatrix} \frac{3}{2} & -\frac{3}{2} \\ -\frac{1}{2} & \frac{5}{2} \end{bmatrix} \cdot \vec{x}(t) + \begin{bmatrix} \frac{t}{2} + \frac{1}{2} \\ -\frac{t}{2} + \frac{1}{2} \end{bmatrix}$$

- Define the forcing function

$$\vec{f}(t) = \begin{bmatrix} \frac{t}{2} + \frac{1}{2} \\ -\frac{t}{2} + \frac{1}{2} \end{bmatrix}$$

- Define the coefficient matrix

$$A = \begin{bmatrix} \frac{3}{2} & -\frac{3}{2} \\ -\frac{1}{2} & \frac{5}{2} \end{bmatrix}$$

- Rewrite the system as

$$\vec{x}'(t) = A \cdot \vec{x}(t) + \vec{f}$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[1, \begin{bmatrix} 3 \\ 1 \end{bmatrix} \right], \left[3, \begin{bmatrix} -1 \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[1, \begin{bmatrix} 3 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{x}_1 = e^t \cdot \begin{bmatrix} 3 \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[3, \begin{bmatrix} -1 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{x}_2 = e^{3t} \cdot \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

- General solution of the system of ODEs can be written in terms of the particular solution $\vec{x}_p(t)$

$$\vec{x}(t) = c_1 \vec{x}_1 + c_2 \vec{x}_2 + \vec{x}_p(t)$$

□ Fundamental matrix

- Let $\phi(t)$ be the matrix whose columns are the independent solutions of the homogeneous system

$$\phi(t) = \begin{bmatrix} 3e^t & -e^{3t} \\ e^t & e^{3t} \end{bmatrix}$$

- The fundamental matrix, $\Phi(t)$ is a normalized version of $\phi(t)$ satisfying $\Phi(0) = I$ where I is the identity matrix

$$\Phi(t) = \phi(t) \cdot \frac{1}{\phi(0)}$$

- Substitute the value of $\phi(t)$ and $\phi(0)$

$$\Phi(t) = \begin{bmatrix} 3e^t & -e^{3t} \\ e^t & e^{3t} \end{bmatrix} \cdot \frac{1}{\begin{bmatrix} 3 & -1 \\ 1 & 1 \end{bmatrix}}$$

- Evaluate and simplify to get the fundamental matrix

$$\Phi(t) = \begin{bmatrix} \frac{3e^t}{4} + \frac{e^{3t}}{4} & -\frac{3e^{3t}}{4} + \frac{3e^t}{4} \\ -\frac{e^{3t}}{4} + \frac{e^t}{4} & \frac{e^t}{4} + \frac{3e^{3t}}{4} \end{bmatrix}$$

□ Find a particular solution of the system of ODEs using variation of parameters

- Let the particular solution be the fundamental matrix multiplied by $\vec{v}(t)$ and solve for $\vec{v}(t)$

$$\vec{x}_p(t) = \Phi(t) \cdot \vec{v}(t)$$

- Take the derivative of the particular solution

$$\vec{x}'_p(t) = \Phi'(t) \cdot \vec{v}(t) + \Phi(t) \cdot \vec{v}'(t)$$

- Substitute particular solution and its derivative into the system of ODEs

$$\Phi'(t) \cdot \vec{v}(t) + \Phi(t) \cdot \vec{v}'(t) = A \cdot \Phi(t) \cdot \vec{v}(t) + \vec{f}(t)$$

- The fundamental matrix has columns that are solutions to the homogeneous system so its derivative is $A \cdot \Phi(t)$

$$A \cdot \Phi(t) \cdot \vec{v}(t) + \Phi(t) \cdot \vec{v}'(t) = A \cdot \Phi(t) \cdot \vec{v}(t) + \vec{f}(t)$$

- Cancel like terms

$$\Phi(t) \cdot \vec{v}'(t) = \vec{f}(t)$$

- Multiply by the inverse of the fundamental matrix

$$\vec{v}'(t) = \frac{1}{\Phi(t)} \cdot \vec{f}(t)$$

- Integrate to solve for $\vec{v}(t)$

$$\vec{v}(t) = \int_0^t \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds$$

- Plug $\vec{v}(t)$ into the equation for the particular solution

$$\vec{x}_p(t) = \Phi(t) \cdot \left(\int_0^t \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds \right)$$

- Plug in the fundamental matrix and the forcing function and compute

$$\vec{x}_p(t) = \begin{bmatrix} \frac{3e^t}{4} - \frac{13}{18} - \frac{e^{3t}}{36} - \frac{t}{6} \\ \frac{e^{3t}}{36} + \frac{t}{6} - \frac{5}{18} + \frac{e^t}{4} \end{bmatrix}$$

- Plug particular solution back into general solution

$$\vec{x}(t) = c_1 \vec{x}_1 + c_2 \vec{x}_2 + \begin{bmatrix} \frac{3e^t}{4} - \frac{13}{18} - \frac{e^{3t}}{36} - \frac{t}{6} \\ \frac{e^{3t}}{36} + \frac{t}{6} - \frac{5}{18} + \frac{e^t}{4} \end{bmatrix}$$

- Substitute in vector of dependent variables

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} 3c_1 e^t - c_2 e^{3t} + \frac{3e^t}{4} - \frac{13}{18} - \frac{e^{3t}}{36} - \frac{t}{6} \\ c_1 e^t + c_2 e^{3t} + \frac{e^{3t}}{36} + \frac{t}{6} - \frac{5}{18} + \frac{e^t}{4} \end{bmatrix}$$

- Solution to the system of ODEs

$$\left\{ x(t) = 3c_1 e^t - c_2 e^{3t} + \frac{3e^t}{4} - \frac{13}{18} - \frac{e^{3t}}{36} - \frac{t}{6}, y(t) = c_1 e^t + c_2 e^{3t} + \frac{e^{3t}}{36} + \frac{t}{6} - \frac{5}{18} + \frac{e^t}{4} \right\}$$

✓ Solution by Maple

Time used: 0.031 (sec). Leaf size: 40

```
dsolve([diff(x(t),t)-diff(y(t),t)-2*x(t)+4*y(t)=t,diff(x(t),t)+diff(y(t),t)-x(t)-y(t)=1],sin
```

$$x(t) = c_2 e^t + c_1 e^{3t} - \frac{t}{6} - \frac{13}{18}$$

$$y(t) = \frac{c_2 e^t}{3} - c_1 e^{3t} - \frac{5}{18} + \frac{t}{6}$$

✓ Solution by Mathematica

Time used: 0.083 (sec). Leaf size: 74

```
DSolve[{x'[t]-y'[t]-2*x[t]+4*y[t]==t,x'[t]+y'[t]-x[t]-y[t]==1},{x[t],y[t]},t,IncludeSingular
```

$$x(t) \rightarrow \frac{1}{36}(-6t + 9(c_1 - 3c_2)e^{3t} + 27(c_1 + c_2)e^t - 26)$$

$$y(t) \rightarrow \frac{1}{36}(6t - 9(c_1 - 3c_2)e^{3t} + 9(c_1 + c_2)e^t - 10)$$

16.11 problem 11

16.11.1 Solution using Matrix exponential method 4440

16.11.2 Solution using explicit Eigenvalue and Eigenvector method . . . 4442

16.11.3 Maple step by step solution 4447

Internal problem ID [11938]

Internal file name [OUTPUT/11947_Sunday_April_14_2024_02_31_09_AM_68378690/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 7, Systems of linear differential equations. Section 7.1. Exercises page 277

Problem number: 11.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "system of linear ODEs"

Solve

$$x'(t) = -2 + x(t) - 3y(t) + 4t$$

$$y'(t) = 4 - 3x(t) + y(t) - 4t$$

16.11.1 Solution using Matrix exponential method

In this method, we will assume we have found the matrix exponential e^{At} already. There are different methods to determine this but will not be shown here. This is a system of linear ODE's given as

$$\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} 1 & -3 \\ -3 & 1 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} + \begin{bmatrix} 4t - 2 \\ 4 - 4t \end{bmatrix}$$

Since the system is nonhomogeneous, then the solution is given by

$$\vec{x}(t) = \vec{x}_h(t) + \vec{x}_p(t)$$

Where $\vec{x}_h(t)$ is the homogeneous solution to $\vec{x}'(t) = A\vec{x}(t)$ and $\vec{x}_p(t)$ is a particular solution to $\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$. The particular solution will be found using variation

of parameters method applied to the fundamental matrix. For the above matrix A , the matrix exponential can be found to be

$$e^{At} = \begin{bmatrix} \frac{e^{-2t}}{2} + \frac{e^{4t}}{2} & -\frac{e^{4t}}{2} + \frac{e^{-2t}}{2} \\ -\frac{e^{4t}}{2} + \frac{e^{-2t}}{2} & \frac{e^{-2t}}{2} + \frac{e^{4t}}{2} \end{bmatrix}$$

Therefore the homogeneous solution is

$$\begin{aligned} \vec{x}_h(t) &= e^{At} \vec{c} \\ &= \begin{bmatrix} \frac{e^{-2t}}{2} + \frac{e^{4t}}{2} & -\frac{e^{4t}}{2} + \frac{e^{-2t}}{2} \\ -\frac{e^{4t}}{2} + \frac{e^{-2t}}{2} & \frac{e^{-2t}}{2} + \frac{e^{4t}}{2} \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} \\ &= \begin{bmatrix} \left(\frac{e^{-2t}}{2} + \frac{e^{4t}}{2}\right) c_1 + \left(-\frac{e^{4t}}{2} + \frac{e^{-2t}}{2}\right) c_2 \\ \left(-\frac{e^{4t}}{2} + \frac{e^{-2t}}{2}\right) c_1 + \left(\frac{e^{-2t}}{2} + \frac{e^{4t}}{2}\right) c_2 \end{bmatrix} \\ &= \begin{bmatrix} \frac{e^{-2t}(c_1+c_2)}{2} + \frac{e^{4t}(c_1-c_2)}{2} \\ \frac{e^{-2t}(c_1+c_2)}{2} - \frac{e^{4t}(c_1-c_2)}{2} \end{bmatrix} \end{aligned}$$

The particular solution given by

$$\vec{x}_p(t) = e^{At} \int e^{-At} \vec{G}(t) dt$$

But

$$\begin{aligned} e^{-At} &= (e^{At})^{-1} \\ &= \begin{bmatrix} \frac{(e^{6t}+1)e^{-4t}}{2} & \frac{(e^{6t}-1)e^{-4t}}{2} \\ \frac{(e^{6t}-1)e^{-4t}}{2} & \frac{(e^{6t}+1)e^{-4t}}{2} \end{bmatrix} \end{aligned}$$

Hence

$$\begin{aligned} \vec{x}_p(t) &= \begin{bmatrix} \frac{e^{-2t}}{2} + \frac{e^{4t}}{2} & -\frac{e^{4t}}{2} + \frac{e^{-2t}}{2} \\ -\frac{e^{4t}}{2} + \frac{e^{-2t}}{2} & \frac{e^{-2t}}{2} + \frac{e^{4t}}{2} \end{bmatrix} \int \begin{bmatrix} \frac{(e^{6t}+1)e^{-4t}}{2} & \frac{(e^{6t}-1)e^{-4t}}{2} \\ \frac{(e^{6t}-1)e^{-4t}}{2} & \frac{(e^{6t}+1)e^{-4t}}{2} \end{bmatrix} \begin{bmatrix} 4t-2 \\ 4-4t \end{bmatrix} dt \\ &= \begin{bmatrix} \frac{e^{-2t}}{2} + \frac{e^{4t}}{2} & -\frac{e^{4t}}{2} + \frac{e^{-2t}}{2} \\ -\frac{e^{4t}}{2} + \frac{e^{-2t}}{2} & \frac{e^{-2t}}{2} + \frac{e^{4t}}{2} \end{bmatrix} \begin{bmatrix} \frac{(e^{6t}-2t+1)e^{-4t}}{2} \\ \frac{(e^{6t}+2t-1)e^{-4t}}{2} \end{bmatrix} \\ &= \begin{bmatrix} 1-t \\ t \end{bmatrix} \end{aligned}$$

Hence the complete solution is

$$\begin{aligned}\vec{x}(t) &= \vec{x}_h(t) + \vec{x}_p(t) \\ &= \begin{bmatrix} \frac{e^{-2t}(c_1+c_2)}{2} + \frac{e^{4t}(c_1-c_2)}{2} + 1 - t \\ \frac{e^{-2t}(c_1+c_2)}{2} + \frac{(-c_1+c_2)e^{4t}}{2} + t \end{bmatrix}\end{aligned}$$

16.11.2 Solution using explicit Eigenvalue and Eigenvector method

This is a system of linear ODE's given as

$$\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} 1 & -3 \\ -3 & 1 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} + \begin{bmatrix} 4t - 2 \\ 4 - 4t \end{bmatrix}$$

Since the system is nonhomogeneous, then the solution is given by

$$\vec{x}(t) = \vec{x}_h(t) + \vec{x}_p(t)$$

Where $\vec{x}_h(t)$ is the homogeneous solution to $\vec{x}'(t) = A\vec{x}(t)$ and $\vec{x}_p(t)$ is a particular solution to $\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$. The particular solution will be found using variation of parameters method applied to the fundamental matrix.

The first step is find the homogeneous solution. We start by finding the eigenvalues of A . This is done by solving the following equation for the eigenvalues λ

$$\det(A - \lambda I) = 0$$

Expanding gives

$$\det\left(\begin{bmatrix} 1 & -3 \\ -3 & 1 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}\right) = 0$$

Therefore

$$\det\left(\begin{bmatrix} 1 - \lambda & -3 \\ -3 & 1 - \lambda \end{bmatrix}\right) = 0$$

Which gives the characteristic equation

$$\lambda^2 - 2\lambda - 8 = 0$$

The roots of the above are the eigenvalues.

$$\lambda_1 = -2$$

$$\lambda_2 = 4$$

This table summarises the above result

eigenvalue	algebraic multiplicity	type of eigenvalue
-2	1	real eigenvalue
4	1	real eigenvalue

Now the eigenvector for each eigenvalue are found.

Considering the eigenvalue $\lambda_1 = -2$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} 1 & -3 \\ -3 & 1 \end{bmatrix} - (-2) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 3 & -3 \\ -3 & 3 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{cc|c} 3 & -3 & 0 \\ -3 & 3 & 0 \end{array} \right]$$

$$R_2 = R_2 + R_1 \implies \left[\begin{array}{cc|c} 3 & -3 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} 3 & -3 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = t\}$

Hence the solution is

$$\begin{bmatrix} t \\ t \end{bmatrix} = \begin{bmatrix} t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} t \\ t \end{bmatrix} = t \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} t \\ t \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

Considering the eigenvalue $\lambda_2 = 4$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} 1 & -3 \\ -3 & 1 \end{bmatrix} - (4) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -3 & -3 \\ -3 & -3 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{cc|c} -3 & -3 & 0 \\ -3 & -3 & 0 \end{array} \right]$$

$$R_2 = R_2 - R_1 \implies \left[\begin{array}{cc|c} -3 & -3 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} -3 & -3 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = -t\}$

Hence the solution is

$$\begin{bmatrix} -t \\ t \end{bmatrix} = \begin{bmatrix} -t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} -t \\ t \end{bmatrix} = t \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} -t \\ t \end{bmatrix} = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

The following table gives a summary of this result. It shows for each eigenvalue the algebraic multiplicity m , and its geometric multiplicity k and the eigenvectors associated with the eigenvalue. If $m > k$ then the eigenvalue is defective which means the number of normal linearly independent eigenvectors associated with this eigenvalue (called the geometric multiplicity k) does not equal the algebraic multiplicity m , and we need to determine an additional $m - k$ generalized eigenvectors for this eigenvalue.

eigenvalue	multiplicity		defective?	eigenvectors
	algebraic m	geometric k		
-2	1	1	No	$\begin{bmatrix} 1 \\ 1 \end{bmatrix}$
4	1	1	No	$\begin{bmatrix} -1 \\ 1 \end{bmatrix}$

Now that we found the eigenvalues and associated eigenvectors, we will go over each eigenvalue and generate the solution basis. The only problem we need to take care of is if the eigenvalue is defective. Since eigenvalue -2 is real and distinct then the corresponding eigenvector solution is

$$\begin{aligned} \vec{x}_1(t) &= \vec{v}_1 e^{-2t} \\ &= \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{-2t} \end{aligned}$$

Since eigenvalue 4 is real and distinct then the corresponding eigenvector solution is

$$\begin{aligned}\vec{x}_2(t) &= \vec{v}_2 e^{4t} \\ &= \begin{bmatrix} -1 \\ 1 \end{bmatrix} e^{4t}\end{aligned}$$

Therefore the homogeneous solution is

$$\vec{x}_h(t) = c_1 \vec{x}_1(t) + c_2 \vec{x}_2(t)$$

Which is written as

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = c_1 \begin{bmatrix} e^{-2t} \\ e^{-2t} \end{bmatrix} + c_2 \begin{bmatrix} -e^{4t} \\ e^{4t} \end{bmatrix}$$

Now that we found homogeneous solution above, we need to find a particular solution $\vec{x}_p(t)$. We will use Variation of parameters. The fundamental matrix is

$$\Phi = \begin{bmatrix} \vec{x}_1 & \vec{x}_2 & \cdots \end{bmatrix}$$

Where \vec{x}_i are the solution basis found above. Therefore the fundamental matrix is

$$\Phi(t) = \begin{bmatrix} e^{-2t} & -e^{4t} \\ e^{-2t} & e^{4t} \end{bmatrix}$$

The particular solution is then given by

$$\vec{x}_p(t) = \Phi \int \Phi^{-1} \vec{G}(t) dt$$

But

$$\Phi^{-1} = \begin{bmatrix} \frac{e^{2t}}{2} & \frac{e^{2t}}{2} \\ -\frac{e^{-4t}}{2} & \frac{e^{-4t}}{2} \end{bmatrix}$$

Hence

$$\begin{aligned}
 \vec{x}_p(t) &= \begin{bmatrix} e^{-2t} & -e^{4t} \\ e^{-2t} & e^{4t} \end{bmatrix} \int \begin{bmatrix} \frac{e^{2t}}{2} & \frac{e^{2t}}{2} \\ -\frac{e^{-4t}}{2} & \frac{e^{-4t}}{2} \end{bmatrix} \begin{bmatrix} 4t - 2 \\ 4 - 4t \end{bmatrix} dt \\
 &= \begin{bmatrix} e^{-2t} & -e^{4t} \\ e^{-2t} & e^{4t} \end{bmatrix} \int \begin{bmatrix} e^{2t} \\ e^{-4t}(-4t + 3) \end{bmatrix} dt \\
 &= \begin{bmatrix} e^{-2t} & -e^{4t} \\ e^{-2t} & e^{4t} \end{bmatrix} \begin{bmatrix} \frac{e^{2t}}{2} \\ \frac{e^{-4t}(2t-1)}{2} \end{bmatrix} \\
 &= \begin{bmatrix} 1 - t \\ t \end{bmatrix}
 \end{aligned}$$

Now that we found particular solution, the final solution is

$$\begin{aligned}
 \vec{x}(t) &= \vec{x}_h(t) + \vec{x}_p(t) \\
 \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} &= \begin{bmatrix} c_1 e^{-2t} \\ c_1 e^{-2t} \end{bmatrix} + \begin{bmatrix} -c_2 e^{4t} \\ c_2 e^{4t} \end{bmatrix} + \begin{bmatrix} 1 - t \\ t \end{bmatrix}
 \end{aligned}$$

Which becomes

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} c_1 e^{-2t} - c_2 e^{4t} + 1 - t \\ c_1 e^{-2t} + c_2 e^{4t} + t \end{bmatrix}$$

16.11.3 Maple step by step solution

Let's solve

$$[x'(t) = -2 + x(t) - 3y(t) + 4t, y'(t) = 4 - 3x(t) + y(t) - 4t]$$

- Define vector

$$\vec{x}(t) = \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}$$

- Convert system into a vector equation

$$\vec{x}'(t) = \begin{bmatrix} 1 & -3 \\ -3 & 1 \end{bmatrix} \cdot \vec{x}(t) + \begin{bmatrix} 4t - 2 \\ 4 - 4t \end{bmatrix}$$

- System to solve

$$\vec{x}'(t) = \begin{bmatrix} 1 & -3 \\ -3 & 1 \end{bmatrix} \cdot \vec{x}(t) + \begin{bmatrix} 4t - 2 \\ 4 - 4t \end{bmatrix}$$

- Define the forcing function

$$\vec{f}(t) = \begin{bmatrix} 4t - 2 \\ 4 - 4t \end{bmatrix}$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 1 & -3 \\ -3 & 1 \end{bmatrix}$$

- Rewrite the system as

$$\vec{x}'(t) = A \cdot \vec{x}(t) + \vec{f}$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[-2, \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right], \left[4, \begin{bmatrix} -1 \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[-2, \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{x}_1 = e^{-2t} \cdot \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[4, \begin{bmatrix} -1 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{x}_2 = e^{4t} \cdot \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

- General solution of the system of ODEs can be written in terms of the particular solution $\vec{x}_p(t)$

$$\vec{x}(t) = c_1 \vec{x}_1 + c_2 \vec{x}_2 + \vec{x}_p(t)$$

□ Fundamental matrix

- Let $\phi(t)$ be the matrix whose columns are the independent solutions of the homogeneous system

$$\phi(t) = \begin{bmatrix} e^{-2t} & -e^{4t} \\ e^{-2t} & e^{4t} \end{bmatrix}$$

- The fundamental matrix, $\Phi(t)$ is a normalized version of $\phi(t)$ satisfying $\Phi(0) = I$ where I is the identity matrix

$$\Phi(t) = \phi(t) \cdot \frac{1}{\phi(0)}$$

- Substitute the value of $\phi(t)$ and $\phi(0)$

$$\Phi(t) = \begin{bmatrix} e^{-2t} & -e^{4t} \\ e^{-2t} & e^{4t} \end{bmatrix} \cdot \frac{1}{\begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}}$$

- Evaluate and simplify to get the fundamental matrix

$$\Phi(t) = \begin{bmatrix} \frac{e^{-2t}}{2} + \frac{e^{4t}}{2} & -\frac{e^{4t}}{2} + \frac{e^{-2t}}{2} \\ -\frac{e^{4t}}{2} + \frac{e^{-2t}}{2} & \frac{e^{-2t}}{2} + \frac{e^{4t}}{2} \end{bmatrix}$$

□ Find a particular solution of the system of ODEs using variation of parameters

- Let the particular solution be the fundamental matrix multiplied by $\vec{v}(t)$ and solve for $\vec{v}(t)$

$$\vec{x}_p(t) = \Phi(t) \cdot \vec{v}(t)$$

- Take the derivative of the particular solution

$$\vec{x}'_p(t) = \Phi'(t) \cdot \vec{v}(t) + \Phi(t) \cdot \vec{v}'(t)$$

- Substitute particular solution and its derivative into the system of ODEs

$$\Phi'(t) \cdot \vec{v}(t) + \Phi(t) \cdot \vec{v}'(t) = A \cdot \Phi(t) \cdot \vec{v}(t) + \vec{f}(t)$$

- The fundamental matrix has columns that are solutions to the homogeneous system so its derivative is $A \cdot \Phi(t)$

$$A \cdot \Phi(t) \cdot \vec{v}(t) + \Phi(t) \cdot \vec{v}'(t) = A \cdot \Phi(t) \cdot \vec{v}(t) + \vec{f}(t)$$

- Cancel like terms

$$\Phi(t) \cdot \vec{v}'(t) = \vec{f}(t)$$

- Multiply by the inverse of the fundamental matrix

$$\vec{v}'(t) = \frac{1}{\Phi(t)} \cdot \vec{f}(t)$$

- Integrate to solve for $\vec{v}(t)$

$$\vec{v}(t) = \int_0^t \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds$$

- Plug $\vec{v}(t)$ into the equation for the particular solution

$$\vec{x}_p(t) = \Phi(t) \cdot \left(\int_0^t \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds \right)$$

- Plug in the fundamental matrix and the forcing function and compute

$$\vec{x}_p(t) = \begin{bmatrix} 1 - \frac{e^{-2t}}{2} - \frac{e^{4t}}{2} - t \\ \frac{e^{4t}}{2} + t - \frac{e^{-2t}}{2} \end{bmatrix}$$

- Plug particular solution back into general solution

$$\vec{x}(t) = c_1 \vec{x}_1 + c_2 \vec{x}_2 + \begin{bmatrix} 1 - \frac{e^{-2t}}{2} - \frac{e^{4t}}{2} - t \\ \frac{e^{4t}}{2} + t - \frac{e^{-2t}}{2} \end{bmatrix}$$

- Substitute in vector of dependent variables

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} \frac{(2c_1-1)e^{-2t}}{2} + \frac{(-2c_2-1)e^{4t}}{2} - t + 1 \\ \frac{(2c_1-1)e^{-2t}}{2} + \frac{(2c_2+1)e^{4t}}{2} + t \end{bmatrix}$$

- Solution to the system of ODEs

$$\left\{ x(t) = \frac{(2c_1-1)e^{-2t}}{2} + \frac{(-2c_2-1)e^{4t}}{2} - t + 1, y(t) = \frac{(2c_1-1)e^{-2t}}{2} + \frac{(2c_2+1)e^{4t}}{2} + t \right\}$$

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 40

```
dsolve([2*diff(x(t),t)+diff(y(t),t)+x(t)+5*y(t)=4*t,diff(x(t),t)+diff(y(t),t)+2*x(t)+2*y(t)=
```

$$x(t) = c_2 e^{4t} + c_1 e^{-2t} - t + 1$$

$$y(t) = -c_2 e^{4t} + c_1 e^{-2t} + t$$

✓ Solution by Mathematica

Time used: 0.078 (sec). Leaf size: 80

```
DSolve[{2*x'[t]+y'[t]+x[t]+5*y[t]==4*t,x'[t]+y'[t]+2*x[t]+2*y[t]==2},{x[t],y[t]},t,IncludeSi
```

$$x(t) \rightarrow \frac{1}{2}e^{-2t}(-2e^{2t}(t-1) + (c_1 - c_2)e^{6t} + c_1 + c_2)$$
$$y(t) \rightarrow \frac{1}{2}e^{-2t}(2e^{2t}t + (c_2 - c_1)e^{6t} + c_1 + c_2)$$

16.12 problem 12

16.12.1 Solution using Matrix exponential method	4452
16.12.2 Solution using explicit Eigenvalue and Eigenvector method . . .	4454
16.12.3 Maple step by step solution	4460

Internal problem ID [11939]

Internal file name [OUTPUT/11948_Sunday_April_14_2024_02_31_09_AM_49739451/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 7, Systems of linear differential equations. Section 7.1. Exercises page 277

Problem number: 12.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**system of linear ODEs**"

Solve

$$\begin{aligned}x'(t) &= 2t^2 - 6y(t) - 2t - 1 \\y'(t) &= -t^2 + x(t) + y(t) + 2t + 1\end{aligned}$$

16.12.1 Solution using Matrix exponential method

In this method, we will assume we have found the matrix exponential e^{At} already. There are different methods to determine this but will not be shown here. This is a system of linear ODE's given as

$$\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} 0 & -6 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} + \begin{bmatrix} 2t^2 - 2t - 1 \\ -t^2 + 2t + 1 \end{bmatrix}$$

Since the system is nonhomogeneous, then the solution is given by

$$\vec{x}(t) = \vec{x}_h(t) + \vec{x}_p(t)$$

Where $\vec{x}_h(t)$ is the homogeneous solution to $\vec{x}'(t) = A\vec{x}(t)$ and $\vec{x}_p(t)$ is a particular solution to $\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$. The particular solution will be found using variation

of parameters method applied to the fundamental matrix. For the above matrix A , the matrix exponential can be found to be

$$e^{At} = \begin{bmatrix} e^{\frac{t}{2}} \cos\left(\frac{\sqrt{23}t}{2}\right) - \frac{\sqrt{23}e^{\frac{t}{2}} \sin\left(\frac{\sqrt{23}t}{2}\right)}{23} & -\frac{12\sqrt{23}e^{\frac{t}{2}} \sin\left(\frac{\sqrt{23}t}{2}\right)}{23} \\ \frac{2\sqrt{23}e^{\frac{t}{2}} \sin\left(\frac{\sqrt{23}t}{2}\right)}{23} & e^{\frac{t}{2}} \cos\left(\frac{\sqrt{23}t}{2}\right) + \frac{\sqrt{23}e^{\frac{t}{2}} \sin\left(\frac{\sqrt{23}t}{2}\right)}{23} \end{bmatrix}$$

$$= \begin{bmatrix} -\frac{e^{\frac{t}{2}}\left(\sqrt{23} \sin\left(\frac{\sqrt{23}t}{2}\right) - 23 \cos\left(\frac{\sqrt{23}t}{2}\right)\right)}{23} & -\frac{12\sqrt{23}e^{\frac{t}{2}} \sin\left(\frac{\sqrt{23}t}{2}\right)}{23} \\ \frac{2\sqrt{23}e^{\frac{t}{2}} \sin\left(\frac{\sqrt{23}t}{2}\right)}{23} & \frac{e^{\frac{t}{2}}\left(\sqrt{23} \sin\left(\frac{\sqrt{23}t}{2}\right) + 23 \cos\left(\frac{\sqrt{23}t}{2}\right)\right)}{23} \end{bmatrix}$$

Therefore the homogeneous solution is

$$\vec{x}_h(t) = e^{At} \vec{c}$$

$$= \begin{bmatrix} -\frac{e^{\frac{t}{2}}\left(\sqrt{23} \sin\left(\frac{\sqrt{23}t}{2}\right) - 23 \cos\left(\frac{\sqrt{23}t}{2}\right)\right)}{23} & -\frac{12\sqrt{23}e^{\frac{t}{2}} \sin\left(\frac{\sqrt{23}t}{2}\right)}{23} \\ \frac{2\sqrt{23}e^{\frac{t}{2}} \sin\left(\frac{\sqrt{23}t}{2}\right)}{23} & \frac{e^{\frac{t}{2}}\left(\sqrt{23} \sin\left(\frac{\sqrt{23}t}{2}\right) + 23 \cos\left(\frac{\sqrt{23}t}{2}\right)\right)}{23} \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix}$$

$$= \begin{bmatrix} -\frac{e^{\frac{t}{2}}\left(\sqrt{23} \sin\left(\frac{\sqrt{23}t}{2}\right) - 23 \cos\left(\frac{\sqrt{23}t}{2}\right)\right)c_1}{23} & -\frac{12\sqrt{23}e^{\frac{t}{2}} \sin\left(\frac{\sqrt{23}t}{2}\right)c_2}{23} \\ \frac{2\sqrt{23}e^{\frac{t}{2}} \sin\left(\frac{\sqrt{23}t}{2}\right)c_1}{23} & + \frac{e^{\frac{t}{2}}\left(\sqrt{23} \sin\left(\frac{\sqrt{23}t}{2}\right) + 23 \cos\left(\frac{\sqrt{23}t}{2}\right)\right)c_2}{23} \end{bmatrix}$$

$$= \begin{bmatrix} -\frac{e^{\frac{t}{2}}\left(\sqrt{23}(c_1 + 12c_2) \sin\left(\frac{\sqrt{23}t}{2}\right) - 23 \cos\left(\frac{\sqrt{23}t}{2}\right)c_1\right)}{23} \\ \frac{2\left(\sqrt{23}(c_1 + \frac{c_2}{2}) \sin\left(\frac{\sqrt{23}t}{2}\right) + \frac{23 \cos\left(\frac{\sqrt{23}t}{2}\right)c_2}{2}\right)e^{\frac{t}{2}}}{23} \end{bmatrix}$$

The particular solution given by

$$\vec{x}_p(t) = e^{At} \int e^{-At} \vec{G}(t) dt$$

But

$$e^{-At} = (e^{At})^{-1}$$

$$= \begin{bmatrix} \frac{\left(\sqrt{23} \sin\left(\frac{\sqrt{23}t}{2}\right) + 23 \cos\left(\frac{\sqrt{23}t}{2}\right)\right)e^{-\frac{t}{2}}}{23} & \frac{12 \sin\left(\frac{\sqrt{23}t}{2}\right)\sqrt{23}e^{-\frac{t}{2}}}{23} \\ -\frac{2 \sin\left(\frac{\sqrt{23}t}{2}\right)\sqrt{23}e^{-\frac{t}{2}}}{23} & -\frac{\left(\sqrt{23} \sin\left(\frac{\sqrt{23}t}{2}\right) - 23 \cos\left(\frac{\sqrt{23}t}{2}\right)\right)e^{-\frac{t}{2}}}{23} \end{bmatrix}$$

Hence

$$\begin{aligned}
\vec{x}_p(t) &= \begin{bmatrix} \frac{e^{\frac{t}{2}}(\sqrt{23}\sin(\frac{\sqrt{23}t}{2}) - 23\cos(\frac{\sqrt{23}t}{2}))}{23} & -\frac{12\sqrt{23}e^{\frac{t}{2}}\sin(\frac{\sqrt{23}t}{2})}{23} \\ \frac{2\sqrt{23}e^{\frac{t}{2}}\sin(\frac{\sqrt{23}t}{2})}{23} & \frac{e^{\frac{t}{2}}(\sqrt{23}\sin(\frac{\sqrt{23}t}{2}) + 23\cos(\frac{\sqrt{23}t}{2}))}{23} \end{bmatrix} \int \begin{bmatrix} \frac{(\sqrt{23}\sin(\frac{\sqrt{23}t}{2}) + 23\cos(\frac{\sqrt{23}t}{2}))e^{-\frac{t}{2}}}{23} \\ -\frac{2\sin(\frac{\sqrt{23}t}{2})\sqrt{23}e^{-\frac{t}{2}}}{23} \end{bmatrix} \\
&= \begin{bmatrix} \frac{e^{\frac{t}{2}}(\sqrt{23}\sin(\frac{\sqrt{23}t}{2}) - 23\cos(\frac{\sqrt{23}t}{2}))}{23} & -\frac{12\sqrt{23}e^{\frac{t}{2}}\sin(\frac{\sqrt{23}t}{2})}{23} \\ \frac{2\sqrt{23}e^{\frac{t}{2}}\sin(\frac{\sqrt{23}t}{2})}{23} & \frac{e^{\frac{t}{2}}(\sqrt{23}\sin(\frac{\sqrt{23}t}{2}) + 23\cos(\frac{\sqrt{23}t}{2}))}{23} \end{bmatrix} \begin{bmatrix} \frac{14e^{-\frac{t}{2}}((\frac{23}{7}t^2 - \frac{23}{6}t - \frac{943}{126})\cos(\frac{\sqrt{23}t}{2}) + \frac{14}{69})}{69} \\ -\frac{5e^{-\frac{t}{2}}((-\frac{23}{5}t^2 + \frac{23}{3}t + \frac{23}{45})\cos(\frac{\sqrt{23}t}{2}) + \frac{5}{69})}{69} \end{bmatrix} \\
&= \begin{bmatrix} \frac{2}{3}t^2 - \frac{7}{9}t - \frac{41}{27} \\ \frac{1}{3}t^2 - \frac{5}{9}t - \frac{1}{27} \end{bmatrix}
\end{aligned}$$

Hence the complete solution is

$$\begin{aligned}
\vec{x}(t) &= \vec{x}_h(t) + \vec{x}_p(t) \\
&= \begin{bmatrix} -\frac{e^{\frac{t}{2}}\sqrt{23}(c_1 + 12c_2)\sin(\frac{\sqrt{23}t}{2})}{23} + e^{\frac{t}{2}}\cos(\frac{\sqrt{23}t}{2})c_1 + \frac{2t^2}{3} - \frac{7t}{9} - \frac{41}{27} \\ \frac{2e^{\frac{t}{2}}\sqrt{23}(c_1 + \frac{c_2}{2})\sin(\frac{\sqrt{23}t}{2})}{23} + e^{\frac{t}{2}}\cos(\frac{\sqrt{23}t}{2})c_2 + \frac{t^2}{3} - \frac{5t}{9} - \frac{1}{27} \end{bmatrix}
\end{aligned}$$

16.12.2 Solution using explicit Eigenvalue and Eigenvector method

This is a system of linear ODE's given as

$$\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} 0 & -6 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} + \begin{bmatrix} 2t^2 - 2t - 1 \\ -t^2 + 2t + 1 \end{bmatrix}$$

Since the system is nonhomogeneous, then the solution is given by

$$\vec{x}(t) = \vec{x}_h(t) + \vec{x}_p(t)$$

Where $\vec{x}_h(t)$ is the homogeneous solution to $\vec{x}'(t) = A\vec{x}(t)$ and $\vec{x}_p(t)$ is a particular solution to $\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$. The particular solution will be found using variation of parameters method applied to the fundamental matrix.

The first step is find the homogeneous solution. We start by finding the eigenvalues of A . This is done by solving the following equation for the eigenvalues λ

$$\det(A - \lambda I) = 0$$

Expanding gives

$$\det \left(\begin{bmatrix} 0 & -6 \\ 1 & 1 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) = 0$$

Therefore

$$\det \left(\begin{bmatrix} -\lambda & -6 \\ 1 & 1 - \lambda \end{bmatrix} \right) = 0$$

Which gives the characteristic equation

$$\lambda^2 - \lambda + 6 = 0$$

The roots of the above are the eigenvalues.

$$\lambda_1 = \frac{1}{2} + \frac{i\sqrt{23}}{2}$$

$$\lambda_2 = \frac{1}{2} - \frac{i\sqrt{23}}{2}$$

This table summarises the above result

eigenvalue	algebraic multiplicity	type of eigenvalue
$\frac{1}{2} - \frac{i\sqrt{23}}{2}$	1	complex eigenvalue
$\frac{1}{2} + \frac{i\sqrt{23}}{2}$	1	complex eigenvalue

Now the eigenvector for each eigenvalue are found.

Considering the eigenvalue $\lambda_1 = \frac{1}{2} - \frac{i\sqrt{23}}{2}$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} 0 & -6 \\ 1 & 1 \end{bmatrix} - \left(\frac{1}{2} - \frac{i\sqrt{23}}{2} \right) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -\frac{1}{2} + \frac{i\sqrt{23}}{2} & -6 \\ 1 & \frac{1}{2} + \frac{i\sqrt{23}}{2} \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{cc|c} -\frac{1}{2} + \frac{i\sqrt{23}}{2} & -6 & 0 \\ 1 & \frac{1}{2} + \frac{i\sqrt{23}}{2} & 0 \end{array} \right]$$

$$R_2 = R_2 - \frac{R_1}{-\frac{1}{2} + \frac{i\sqrt{23}}{2}} \Rightarrow \left[\begin{array}{cc|c} -\frac{1}{2} + \frac{i\sqrt{23}}{2} & -6 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\left[\begin{array}{cc} -\frac{1}{2} + \frac{i\sqrt{23}}{2} & -6 \\ 0 & 0 \end{array} \right] \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\left\{ v_1 = \frac{12t}{i\sqrt{23}-1} \right\}$

Hence the solution is

$$\begin{bmatrix} \frac{12t}{i\sqrt{23}-1} \\ t \end{bmatrix} = \begin{bmatrix} \frac{12t}{i\sqrt{23}-1} \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} \frac{12t}{i\sqrt{23}-1} \\ t \end{bmatrix} = t \begin{bmatrix} \frac{12}{i\sqrt{23}-1} \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} \frac{12t}{i\sqrt{23}-1} \\ t \end{bmatrix} = \begin{bmatrix} \frac{12}{i\sqrt{23}-1} \\ 1 \end{bmatrix}$$

Which is normalized to

$$\begin{bmatrix} \frac{12t}{i\sqrt{23}-1} \\ t \end{bmatrix} = \begin{bmatrix} \frac{12}{i\sqrt{23}-1} \\ 1 \end{bmatrix}$$

Considering the eigenvalue $\lambda_2 = \frac{1}{2} + \frac{i\sqrt{23}}{2}$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\left[\begin{array}{cc} 0 & -6 \\ 1 & 1 \end{array} \right] - \left(\frac{1}{2} + \frac{i\sqrt{23}}{2} \right) \left[\begin{array}{cc} 1 & 0 \\ 0 & 1 \end{array} \right] \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\left[\begin{array}{cc} -\frac{1}{2} - \frac{i\sqrt{23}}{2} & -6 \\ 1 & \frac{1}{2} - \frac{i\sqrt{23}}{2} \end{array} \right] \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{cc|c} -\frac{1}{2} - \frac{i\sqrt{23}}{2} & -6 & 0 \\ 1 & \frac{1}{2} - \frac{i\sqrt{23}}{2} & 0 \end{array} \right]$$

$$R_2 = R_2 - \frac{R_1}{-\frac{1}{2} - \frac{i\sqrt{23}}{2}} \implies \left[\begin{array}{cc|c} -\frac{1}{2} - \frac{i\sqrt{23}}{2} & -6 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\left[\begin{array}{cc} -\frac{1}{2} - \frac{i\sqrt{23}}{2} & -6 \\ 0 & 0 \end{array} \right] \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\left\{ v_1 = -\frac{12t}{1+i\sqrt{23}} \right\}$

Hence the solution is

$$\begin{bmatrix} -\frac{12t}{1+i\sqrt{23}} \\ t \end{bmatrix} = \begin{bmatrix} -\frac{12t}{1+i\sqrt{23}} \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} -\frac{12t}{1+i\sqrt{23}} \\ t \end{bmatrix} = t \begin{bmatrix} -\frac{12}{1+i\sqrt{23}} \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} -\frac{12t}{1+i\sqrt{23}} \\ t \end{bmatrix} = \begin{bmatrix} -\frac{12}{1+i\sqrt{23}} \\ 1 \end{bmatrix}$$

Which is normalized to

$$\begin{bmatrix} -\frac{12t}{1+i\sqrt{23}} \\ t \end{bmatrix} = \begin{bmatrix} -\frac{12}{1+i\sqrt{23}} \\ 1 \end{bmatrix}$$

The following table gives a summary of this result. It shows for each eigenvalue the algebraic multiplicity m , and its geometric multiplicity k and the eigenvectors associated with the eigenvalue. If $m > k$ then the eigenvalue is defective which means the number

of normal linearly independent eigenvectors associated with this eigenvalue (called the geometric multiplicity k) does not equal the algebraic multiplicity m , and we need to determine an additional $m - k$ generalized eigenvectors for this eigenvalue.

eigenvalue	multiplicity		defective?	eigenvectors
	algebraic m	geometric k		
$\frac{1}{2} + \frac{i\sqrt{23}}{2}$	1	1	No	$\begin{bmatrix} -\frac{6}{\frac{1}{2} + \frac{i\sqrt{23}}{2}} \\ 1 \end{bmatrix}$
$\frac{1}{2} - \frac{i\sqrt{23}}{2}$	1	1	No	$\begin{bmatrix} -\frac{6}{\frac{1}{2} - \frac{i\sqrt{23}}{2}} \\ 1 \end{bmatrix}$

Now that we found the eigenvalues and associated eigenvectors, we will go over each eigenvalue and generate the solution basis. The only problem we need to take care of is if the eigenvalue is defective. Therefore the homogeneous solution is

$$\vec{x}_h(t) = c_1 \vec{x}_1(t) + c_2 \vec{x}_2(t)$$

Which is written as

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = c_1 \begin{bmatrix} -\frac{6e^{\left(\frac{1}{2} + \frac{i\sqrt{23}}{2}\right)t}}{\frac{1}{2} + \frac{i\sqrt{23}}{2}} \\ e^{\left(\frac{1}{2} + \frac{i\sqrt{23}}{2}\right)t} \end{bmatrix} + c_2 \begin{bmatrix} -\frac{6e^{\left(\frac{1}{2} - \frac{i\sqrt{23}}{2}\right)t}}{\frac{1}{2} - \frac{i\sqrt{23}}{2}} \\ e^{\left(\frac{1}{2} - \frac{i\sqrt{23}}{2}\right)t} \end{bmatrix}$$

Now that we found homogeneous solution above, we need to find a particular solution $\vec{x}_p(t)$. We will use Variation of parameters. The fundamental matrix is

$$\Phi = \begin{bmatrix} \vec{x}_1 & \vec{x}_2 & \dots \end{bmatrix}$$

Where \vec{x}_i are the solution basis found above. Therefore the fundamental matrix is

$$\Phi(t) = \begin{bmatrix} -\frac{6e^{\left(\frac{1}{2} + \frac{i\sqrt{23}}{2}\right)t}}{\frac{1}{2} + \frac{i\sqrt{23}}{2}} & -\frac{6e^{\left(\frac{1}{2} - \frac{i\sqrt{23}}{2}\right)t}}{\frac{1}{2} - \frac{i\sqrt{23}}{2}} \\ e^{\left(\frac{1}{2} + \frac{i\sqrt{23}}{2}\right)t} & e^{\left(\frac{1}{2} - \frac{i\sqrt{23}}{2}\right)t} \end{bmatrix}$$

The particular solution is then given by

$$\vec{x}_p(t) = \Phi \int \Phi^{-1} \vec{G}(t) dt$$

But

$$\Phi^{-1} = \begin{bmatrix} -\frac{i\sqrt{23}e^{-\frac{(1+i\sqrt{23})t}{2}}}{23} & -\frac{\sqrt{23}e^{-\frac{(1+i\sqrt{23})t}{2}}(i-\sqrt{23})}{46} \\ \frac{i\sqrt{23}e^{\frac{(i\sqrt{23}-1)t}{2}}}{23} & \frac{\sqrt{23}e^{\frac{(i\sqrt{23}-1)t}{2}}(\sqrt{23}+i)}{46} \end{bmatrix}$$

Hence

$$\begin{aligned} \vec{x}_p(t) &= \begin{bmatrix} -\frac{6e^{\left(\frac{1}{2}+\frac{i\sqrt{23}}{2}\right)t}}{\frac{1}{2}+\frac{i\sqrt{23}}{2}} & -\frac{6e^{\left(\frac{1}{2}-\frac{i\sqrt{23}}{2}\right)t}}{\frac{1}{2}-\frac{i\sqrt{23}}{2}} \\ e^{\left(\frac{1}{2}+\frac{i\sqrt{23}}{2}\right)t} & e^{\left(\frac{1}{2}-\frac{i\sqrt{23}}{2}\right)t} \end{bmatrix} \int \begin{bmatrix} -\frac{i\sqrt{23}e^{-\frac{(1+i\sqrt{23})t}{2}}}{23} & -\frac{\sqrt{23}e^{-\frac{(1+i\sqrt{23})t}{2}}(i-\sqrt{23})}{46} \\ \frac{i\sqrt{23}e^{\frac{(i\sqrt{23}-1)t}{2}}}{23} & \frac{\sqrt{23}e^{\frac{(i\sqrt{23}-1)t}{2}}(\sqrt{23}+i)}{46} \end{bmatrix} \begin{bmatrix} 2t^2 - 2t - 1 \\ -t^2 + 2t + 1 \end{bmatrix} \\ &= \begin{bmatrix} -\frac{6e^{\left(\frac{1}{2}+\frac{i\sqrt{23}}{2}\right)t}}{\frac{1}{2}+\frac{i\sqrt{23}}{2}} & -\frac{6e^{\left(\frac{1}{2}-\frac{i\sqrt{23}}{2}\right)t}}{\frac{1}{2}-\frac{i\sqrt{23}}{2}} \\ e^{\left(\frac{1}{2}+\frac{i\sqrt{23}}{2}\right)t} & e^{\left(\frac{1}{2}-\frac{i\sqrt{23}}{2}\right)t} \end{bmatrix} \int \begin{bmatrix} -\frac{3e^{-\frac{(1+i\sqrt{23})t}{2}}\left(i\left(t+\frac{1}{3}\right)(t-1)\sqrt{23}+\frac{23t^2}{3}-\frac{46t}{3}-\frac{23}{3}\right)}{46} \\ \frac{3e^{\frac{(i\sqrt{23}-1)t}{2}}\left(i\left(t+\frac{1}{3}\right)(t-1)\sqrt{23}-\frac{23t^2}{3}+\frac{46t}{3}+\frac{23}{3}\right)}{46} \end{bmatrix} dt \\ &= \begin{bmatrix} -\frac{6e^{\left(\frac{1}{2}+\frac{i\sqrt{23}}{2}\right)t}}{\frac{1}{2}+\frac{i\sqrt{23}}{2}} & -\frac{6e^{\left(\frac{1}{2}-\frac{i\sqrt{23}}{2}\right)t}}{\frac{1}{2}-\frac{i\sqrt{23}}{2}} \\ e^{\left(\frac{1}{2}+\frac{i\sqrt{23}}{2}\right)t} & e^{\left(\frac{1}{2}-\frac{i\sqrt{23}}{2}\right)t} \end{bmatrix} \begin{bmatrix} \frac{\sqrt{23}e^{-\frac{(1+i\sqrt{23})t}{2}}\left(-36i\sqrt{23}t^2+51i\sqrt{23}t+43i\sqrt{23}+36t^2-87t+113\right)\left(-3it^2-\sqrt{23}t^2\right)}{16146-1242i(2t+1)\sqrt{23}-19872t^2+32292t} \\ -\frac{\sqrt{23}e^{\frac{(i\sqrt{23}-1)t}{2}}\left(-36\sqrt{23}t^2+51\sqrt{23}t+43\sqrt{23}+36it^2-87it+113i\right)\left(3it^2-\sqrt{23}t^2\right)}{(2484t+1242)\sqrt{23}+19872it^2-32292it-16146i} \end{bmatrix} \\ &= \begin{bmatrix} \frac{-\frac{128}{3}t^6+\frac{1696}{9}t^5-\frac{3328}{27}t^4-\frac{10136}{27}t^3+\frac{6776}{27}t^2+\frac{2960}{9}t+\frac{656}{9}}{\left(-\frac{13}{2}+i\left(t+\frac{1}{2}\right)\sqrt{23}+8t^2-13t\right)\left(\frac{13}{2}+i\left(t+\frac{1}{2}\right)\sqrt{23}-8t^2+13t\right)} \\ \frac{-\frac{64}{3}t^6+\frac{944}{9}t^5-\frac{3848}{27}t^4-\frac{616}{27}t^3+\frac{2536}{27}t^2+\frac{304}{9}t+\frac{16}{9}}{\left(-\frac{13}{2}+i\left(t+\frac{1}{2}\right)\sqrt{23}+8t^2-13t\right)\left(\frac{13}{2}+i\left(t+\frac{1}{2}\right)\sqrt{23}-8t^2+13t\right)} \end{bmatrix} \end{aligned}$$

Now that we found particular solution, the final solution is

$$\begin{aligned} \vec{x}(t) &= \vec{x}_h(t) + \vec{x}_p(t) \\ \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} &= \begin{bmatrix} -\frac{6c_1e^{\left(\frac{1}{2}+\frac{i\sqrt{23}}{2}\right)t}}{\frac{1}{2}+\frac{i\sqrt{23}}{2}} \\ c_1e^{\left(\frac{1}{2}+\frac{i\sqrt{23}}{2}\right)t} \end{bmatrix} + \begin{bmatrix} -\frac{6c_2e^{\left(\frac{1}{2}-\frac{i\sqrt{23}}{2}\right)t}}{\frac{1}{2}-\frac{i\sqrt{23}}{2}} \\ c_2e^{\left(\frac{1}{2}-\frac{i\sqrt{23}}{2}\right)t} \end{bmatrix} + \begin{bmatrix} \frac{-\frac{128}{3}t^6+\frac{1696}{9}t^5-\frac{3328}{27}t^4-\frac{10136}{27}t^3+\frac{6776}{27}t^2+\frac{2960}{9}t+\frac{656}{9}}{\left(-\frac{13}{2}+i\left(t+\frac{1}{2}\right)\sqrt{23}+8t^2-13t\right)\left(\frac{13}{2}+i\left(t+\frac{1}{2}\right)\sqrt{23}-8t^2+13t\right)} \\ \frac{-\frac{64}{3}t^6+\frac{944}{9}t^5-\frac{3848}{27}t^4-\frac{616}{27}t^3+\frac{2536}{27}t^2+\frac{304}{9}t+\frac{16}{9}}{\left(-\frac{13}{2}+i\left(t+\frac{1}{2}\right)\sqrt{23}+8t^2-13t\right)\left(\frac{13}{2}+i\left(t+\frac{1}{2}\right)\sqrt{23}-8t^2+13t\right)} \end{bmatrix} \end{aligned}$$

Which becomes

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} \frac{32(-t^4 + \frac{13}{4}t^3 - \frac{11}{8}t^2 - 3t - \frac{3}{4}) \left(-\frac{82}{27} + (i\sqrt{23}-1)c_1 e^{\frac{(1+i\sqrt{23})t}{2}} + c_2(-1-i\sqrt{23})e^{-\frac{(i\sqrt{23}-1)t}{2}} + \frac{4t^2}{3} - \frac{14t}{9} \right)}{\left(-\frac{13}{2} + i(t+\frac{1}{2})\sqrt{23}+8t^2-13t \right) \left(\frac{13}{2} + i(t+\frac{1}{2})\sqrt{23}-8t^2+13t \right)} \\ \frac{8(-8t^4+26t^3-11t^2-24t-6) \left(27c_2 e^{-\frac{(i\sqrt{23}-1)t}{2}} + 27c_1 e^{\frac{(1+i\sqrt{23})t}{2}} + 9t^2 - 15t - 1 \right)}{27 \left(-\frac{13}{2} + i(t+\frac{1}{2})\sqrt{23}+8t^2-13t \right) \left(\frac{13}{2} + i(t+\frac{1}{2})\sqrt{23}-8t^2+13t \right)} \end{bmatrix}$$

16.12.3 Maple step by step solution

Let's solve

$$[x'(t) = 2t^2 - 6y(t) - 2t - 1, y'(t) = -t^2 + x(t) + y(t) + 2t + 1]$$

- Define vector

$$\vec{x}(t) = \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}$$

- Convert system into a vector equation

$$\vec{x}'(t) = \begin{bmatrix} 0 & -6 \\ 1 & 1 \end{bmatrix} \cdot \vec{x}(t) + \begin{bmatrix} 2t^2 - 2t - 1 \\ -t^2 + 2t + 1 \end{bmatrix}$$

- System to solve

$$\vec{x}'(t) = \begin{bmatrix} 0 & -6 \\ 1 & 1 \end{bmatrix} \cdot \vec{x}(t) + \begin{bmatrix} 2t^2 - 2t - 1 \\ -t^2 + 2t + 1 \end{bmatrix}$$

- Define the forcing function

$$\vec{f}(t) = \begin{bmatrix} 2t^2 - 2t - 1 \\ -t^2 + 2t + 1 \end{bmatrix}$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 0 & -6 \\ 1 & 1 \end{bmatrix}$$

- Rewrite the system as

$$\vec{x}'(t) = A \cdot \vec{x}(t) + \vec{f}$$

- To solve the system, find the eigenvalues and eigenvectors of A

Eigenpairs of A

$$\left[\left[\frac{1}{2} - \frac{I\sqrt{23}}{2}, \begin{bmatrix} -\frac{6}{\frac{1}{2} - \frac{I\sqrt{23}}{2}} \\ 1 \end{bmatrix} \right], \left[\frac{1}{2} + \frac{I\sqrt{23}}{2}, \begin{bmatrix} -\frac{6}{\frac{1}{2} + \frac{I\sqrt{23}}{2}} \\ 1 \end{bmatrix} \right] \right]$$

- Consider complex eigenpair, complex conjugate eigenvalue can be ignored

$$\left[\frac{1}{2} - \frac{I\sqrt{23}}{2}, \begin{bmatrix} -\frac{6}{\frac{1}{2} - \frac{I\sqrt{23}}{2}} \\ 1 \end{bmatrix} \right]$$

- Solution from eigenpair

$$e^{\left(\frac{1}{2} - \frac{I\sqrt{23}}{2}\right)t} \cdot \begin{bmatrix} -\frac{6}{\frac{1}{2} - \frac{I\sqrt{23}}{2}} \\ 1 \end{bmatrix}$$

- Use Euler identity to write solution in terms of \sin and \cos

$$e^{\frac{t}{2}} \cdot \left(\cos\left(\frac{\sqrt{23}t}{2}\right) - I \sin\left(\frac{\sqrt{23}t}{2}\right) \right) \cdot \begin{bmatrix} -\frac{6}{\frac{1}{2} - \frac{I\sqrt{23}}{2}} \\ 1 \end{bmatrix}$$

- Simplify expression

$$e^{\frac{t}{2}} \cdot \begin{bmatrix} -\frac{6\left(\cos\left(\frac{\sqrt{23}t}{2}\right) - I \sin\left(\frac{\sqrt{23}t}{2}\right)\right)}{\frac{1}{2} - \frac{I\sqrt{23}}{2}} \\ \cos\left(\frac{\sqrt{23}t}{2}\right) - I \sin\left(\frac{\sqrt{23}t}{2}\right) \end{bmatrix}$$

- Both real and imaginary parts are solutions to the homogeneous system

$$\left[\vec{x}_1(t) = e^{\frac{t}{2}} \cdot \begin{bmatrix} -\frac{\cos\left(\frac{\sqrt{23}t}{2}\right)}{2} - \frac{\sqrt{23} \sin\left(\frac{\sqrt{23}t}{2}\right)}{2} \\ \cos\left(\frac{\sqrt{23}t}{2}\right) \end{bmatrix}, \vec{x}_2(t) = e^{\frac{t}{2}} \cdot \begin{bmatrix} -\frac{\sqrt{23} \cos\left(\frac{\sqrt{23}t}{2}\right)}{2} + \frac{\sin\left(\frac{\sqrt{23}t}{2}\right)}{2} \\ -\sin\left(\frac{\sqrt{23}t}{2}\right) \end{bmatrix} \right]$$

- General solution of the system of ODEs can be written in terms of the particular solution $\vec{x}_p(t)$

$$\vec{x}(t) = c_1 \vec{x}_1(t) + c_2 \vec{x}_2(t) + \vec{x}_p(t)$$

□ Fundamental matrix

- Let $\phi(t)$ be the matrix whose columns are the independent solutions of the homogeneous system

$$\phi(t) = \begin{bmatrix} e^{\frac{t}{2}} \left(-\frac{\cos\left(\frac{\sqrt{23}t}{2}\right)}{2} - \frac{\sqrt{23} \sin\left(\frac{\sqrt{23}t}{2}\right)}{2} \right) & e^{\frac{t}{2}} \left(-\frac{\sqrt{23} \cos\left(\frac{\sqrt{23}t}{2}\right)}{2} + \frac{\sin\left(\frac{\sqrt{23}t}{2}\right)}{2} \right) \\ e^{\frac{t}{2}} \cos\left(\frac{\sqrt{23}t}{2}\right) & -e^{\frac{t}{2}} \sin\left(\frac{\sqrt{23}t}{2}\right) \end{bmatrix}$$

- The fundamental matrix, $\Phi(t)$ is a normalized version of $\phi(t)$ satisfying $\Phi(0) = I$ where I is the identity matrix

$$\Phi(t) = \phi(t) \cdot \frac{1}{\phi(0)}$$

- Substitute the value of $\phi(t)$ and $\phi(0)$

$$\Phi(t) = \begin{bmatrix} e^{\frac{t}{2}} \left(-\frac{\cos\left(\frac{\sqrt{23}t}{2}\right)}{2} - \frac{\sqrt{23} \sin\left(\frac{\sqrt{23}t}{2}\right)}{2} \right) & e^{\frac{t}{2}} \left(-\frac{\sqrt{23} \cos\left(\frac{\sqrt{23}t}{2}\right)}{2} + \frac{\sin\left(\frac{\sqrt{23}t}{2}\right)}{2} \right) \\ e^{\frac{t}{2}} \cos\left(\frac{\sqrt{23}t}{2}\right) & -e^{\frac{t}{2}} \sin\left(\frac{\sqrt{23}t}{2}\right) \end{bmatrix} \cdot \begin{bmatrix} 1 & \\ -\frac{1}{2} & -\frac{\sqrt{23}}{2} \\ 1 & 0 \end{bmatrix}$$

- Evaluate and simplify to get the fundamental matrix

$$\Phi(t) = \begin{bmatrix} \frac{(\sqrt{23} \cos\left(\frac{\sqrt{23}t}{2}\right) - \sin\left(\frac{\sqrt{23}t}{2}\right))\sqrt{23} e^{\frac{t}{2}}}{23} & -\frac{12\sqrt{23} e^{\frac{t}{2}} \sin\left(\frac{\sqrt{23}t}{2}\right)}{23} \\ \frac{2\sqrt{23} e^{\frac{t}{2}} \sin\left(\frac{\sqrt{23}t}{2}\right)}{23} & \frac{e^{\frac{t}{2}} (\sqrt{23} \sin\left(\frac{\sqrt{23}t}{2}\right) + 23 \cos\left(\frac{\sqrt{23}t}{2}\right))}{23} \end{bmatrix}$$

- Find a particular solution of the system of ODEs using variation of parameters

- Let the particular solution be the fundamental matrix multiplied by $\vec{v}(t)$ and solve for $\vec{v}(t)$

$$\vec{x}_p(t) = \Phi(t) \cdot \vec{v}(t)$$

- Take the derivative of the particular solution

$$\vec{x}'_p(t) = \Phi'(t) \cdot \vec{v}(t) + \Phi(t) \cdot \vec{v}'(t)$$

- Substitute particular solution and its derivative into the system of ODEs

$$\Phi'(t) \cdot \vec{v}(t) + \Phi(t) \cdot \vec{v}'(t) = A \cdot \Phi(t) \cdot \vec{v}(t) + \vec{f}(t)$$

- The fundamental matrix has columns that are solutions to the homogeneous system so its derivative is $A \cdot \Phi(t)$

$$A \cdot \Phi(t) \cdot \vec{v}(t) + \Phi(t) \cdot \vec{v}'(t) = A \cdot \Phi(t) \cdot \vec{v}(t) + \vec{f}(t)$$

- Cancel like terms

$$\Phi(t) \cdot \vec{v}'(t) = \vec{f}(t)$$

- Multiply by the inverse of the fundamental matrix

$$\vec{v}'(t) = \frac{1}{\Phi(t)} \cdot \vec{f}(t)$$

- Integrate to solve for $\vec{v}(t)$

$$\vec{v}(t) = \int_0^t \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds$$

- o Plug $\vec{v}(t)$ into the equation for the particular solution

$$\vec{x}_p(t) = \Phi(t) \cdot \left(\int_0^t \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds \right)$$

- o Plug in the fundamental matrix and the forcing function and compute

$$\vec{x}_p(t) = \begin{bmatrix} -\frac{53\sqrt{23}e^{\frac{t}{2}}\sin\left(\frac{\sqrt{23}t}{2}\right)}{621} + \frac{41e^{\frac{t}{2}}\cos\left(\frac{\sqrt{23}t}{2}\right)}{27} + \frac{2t^2}{3} - \frac{7t}{9} - \frac{41}{27} \\ \frac{83\sqrt{23}e^{\frac{t}{2}}\sin\left(\frac{\sqrt{23}t}{2}\right)}{621} + \frac{e^{\frac{t}{2}}\cos\left(\frac{\sqrt{23}t}{2}\right)}{27} + \frac{t^2}{3} - \frac{5t}{9} - \frac{1}{27} \end{bmatrix}$$

- Plug particular solution back into general solution

$$\vec{x}(t) = c_1 \vec{x}_1(t) + c_2 \vec{x}_2(t) + \begin{bmatrix} -\frac{53\sqrt{23}e^{\frac{t}{2}}\sin\left(\frac{\sqrt{23}t}{2}\right)}{621} + \frac{41e^{\frac{t}{2}}\cos\left(\frac{\sqrt{23}t}{2}\right)}{27} + \frac{2t^2}{3} - \frac{7t}{9} - \frac{41}{27} \\ \frac{83\sqrt{23}e^{\frac{t}{2}}\sin\left(\frac{\sqrt{23}t}{2}\right)}{621} + \frac{e^{\frac{t}{2}}\cos\left(\frac{\sqrt{23}t}{2}\right)}{27} + \frac{t^2}{3} - \frac{5t}{9} - \frac{1}{27} \end{bmatrix}$$

- Substitute in vector of dependent variables

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} -\frac{e^{\frac{t}{2}}(c_2\sqrt{23}+c_1-\frac{82}{27})\cos\left(\frac{\sqrt{23}t}{2}\right)}{2} - \frac{e^{\frac{t}{2}}((c_1+\frac{106}{621})\sqrt{23}-c_2)\sin\left(\frac{\sqrt{23}t}{2}\right)}{2} + \frac{2t^2}{3} - \frac{7t}{9} - \frac{41}{27} \\ -\frac{1}{27} + \frac{(27c_1+1)e^{\frac{t}{2}}\cos\left(\frac{\sqrt{23}t}{2}\right)}{27} - e^{\frac{t}{2}}\left(c_2 - \frac{83\sqrt{23}}{621}\right)\sin\left(\frac{\sqrt{23}t}{2}\right) + \frac{t^2}{3} - \frac{5t}{9} \end{bmatrix}$$

- Solution to the system of ODEs

$$\begin{cases} x(t) = -\frac{e^{\frac{t}{2}}(c_2\sqrt{23}+c_1-\frac{82}{27})\cos\left(\frac{\sqrt{23}t}{2}\right)}{2} - \frac{e^{\frac{t}{2}}((c_1+\frac{106}{621})\sqrt{23}-c_2)\sin\left(\frac{\sqrt{23}t}{2}\right)}{2} + \frac{2t^2}{3} - \frac{7t}{9} - \frac{41}{27}, y(t) = -\frac{1}{27} + \frac{(27c_1+1)e^{\frac{t}{2}}\cos\left(\frac{\sqrt{23}t}{2}\right)}{27} - e^{\frac{t}{2}}\left(c_2 - \frac{83\sqrt{23}}{621}\right)\sin\left(\frac{\sqrt{23}t}{2}\right) + \frac{t^2}{3} - \frac{5t}{9} \end{cases}$$

✓ Solution by Maple

Time used: 0.031 (sec). Leaf size: 116

```
dsolve([diff(x(t),t)+diff(y(t),t)-x(t)+5*y(t)=t^2,diff(x(t),t)+2*diff(y(t),t)-2*x(t)+4*y(t)=
```

$$x(t) = e^{\frac{t}{2}} \sin\left(\frac{\sqrt{23}t}{2}\right) c_2 + e^{\frac{t}{2}} \cos\left(\frac{\sqrt{23}t}{2}\right) c_1 + \frac{2t^2}{3} - \frac{7t}{9} - \frac{41}{27}$$

$$y(t) = \frac{t^2}{3} - \frac{e^{\frac{t}{2}} \sin\left(\frac{\sqrt{23}t}{2}\right) c_2}{12} - \frac{e^{\frac{t}{2}} \sqrt{23} \cos\left(\frac{\sqrt{23}t}{2}\right) c_2}{12}$$

$$- \frac{e^{\frac{t}{2}} \cos\left(\frac{\sqrt{23}t}{2}\right) c_1}{12} + \frac{e^{\frac{t}{2}} \sqrt{23} \sin\left(\frac{\sqrt{23}t}{2}\right) c_1}{12} - \frac{5t}{9} - \frac{1}{27}$$

✓ Solution by Mathematica

Time used: 11.178 (sec). Leaf size: 143

```
DSolve[{x'[t]+y'[t]-x[t]+5*y[t]==t^2,x'[t]+2*y'[t]-2*x[t]+4*y[t]==2*t+1},{x[t],y[t]},t,Inclu
```

$$x(t) \rightarrow \frac{1}{27}(18t^2 - 21t - 41) + c_1 e^{t/2} \cos\left(\frac{\sqrt{23}t}{2}\right) - \frac{(c_1 + 12c_2)e^{t/2} \sin\left(\frac{\sqrt{23}t}{2}\right)}{\sqrt{23}}$$

$$y(t) \rightarrow \frac{1}{27}(9t^2 - 15t - 1) + c_2 e^{t/2} \cos\left(\frac{\sqrt{23}t}{2}\right) + \frac{(2c_1 + c_2)e^{t/2} \sin\left(\frac{\sqrt{23}t}{2}\right)}{\sqrt{23}}$$

16.13 problem 13

16.13.1 Solution using Matrix exponential method	4465
16.13.2 Solution using explicit Eigenvalue and Eigenvector method . . .	4467
16.13.3 Maple step by step solution	4472

Internal problem ID [11940]

Internal file name [OUTPUT/11949_Sunday_April_14_2024_02_31_12_AM_27299389/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 7, Systems of linear differential equations. Section 7.1. Exercises page 277

Problem number: 13.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**system of linear ODEs**"

Solve

$$\begin{aligned}x'(t) &= -t^2 + x(t) + y(t) + 6t \\y'(t) &= 3t^2 - 3x(t) - 3y(t) - 8t\end{aligned}$$

16.13.1 Solution using Matrix exponential method

In this method, we will assume we have found the matrix exponential e^{At} already. There are different methods to determine this but will not be shown here. This is a system of linear ODE's given as

$$\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ -3 & -3 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} + \begin{bmatrix} -t^2 + 6t \\ 3t^2 - 8t \end{bmatrix}$$

Since the system is nonhomogeneous, then the solution is given by

$$\vec{x}(t) = \vec{x}_h(t) + \vec{x}_p(t)$$

Where $\vec{x}_h(t)$ is the homogeneous solution to $\vec{x}'(t) = A\vec{x}(t)$ and $\vec{x}_p(t)$ is a particular solution to $\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$. The particular solution will be found using variation

of parameters method applied to the fundamental matrix. For the above matrix A , the matrix exponential can be found to be

$$e^{At} = \begin{bmatrix} -\frac{e^{-2t}}{2} + \frac{3}{2} & \frac{1}{2} - \frac{e^{-2t}}{2} \\ -\frac{3}{2} + \frac{3e^{-2t}}{2} & \frac{3e^{-2t}}{2} - \frac{1}{2} \end{bmatrix}$$

Therefore the homogeneous solution is

$$\begin{aligned} \vec{x}_h(t) &= e^{At} \vec{c} \\ &= \begin{bmatrix} -\frac{e^{-2t}}{2} + \frac{3}{2} & \frac{1}{2} - \frac{e^{-2t}}{2} \\ -\frac{3}{2} + \frac{3e^{-2t}}{2} & \frac{3e^{-2t}}{2} - \frac{1}{2} \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} \\ &= \begin{bmatrix} \left(-\frac{e^{-2t}}{2} + \frac{3}{2}\right) c_1 + \left(\frac{1}{2} - \frac{e^{-2t}}{2}\right) c_2 \\ \left(-\frac{3}{2} + \frac{3e^{-2t}}{2}\right) c_1 + \left(\frac{3e^{-2t}}{2} - \frac{1}{2}\right) c_2 \end{bmatrix} \\ &= \begin{bmatrix} \frac{(-c_1 - c_2)e^{-2t}}{2} + \frac{3c_1}{2} + \frac{c_2}{2} \\ \frac{(3c_1 + 3c_2)e^{-2t}}{2} - \frac{3c_1}{2} - \frac{c_2}{2} \end{bmatrix} \end{aligned}$$

The particular solution given by

$$\vec{x}_p(t) = e^{At} \int e^{-At} \vec{G}(t) dt$$

But

$$\begin{aligned} e^{-At} &= (e^{At})^{-1} \\ &= \begin{bmatrix} \frac{3}{2} - \frac{e^{2t}}{2} & -\frac{e^{2t}}{2} + \frac{1}{2} \\ \frac{3e^{2t}}{2} - \frac{3}{2} & -\frac{1}{2} + \frac{3e^{2t}}{2} \end{bmatrix} \end{aligned}$$

Hence

$$\begin{aligned} \vec{x}_p(t) &= \begin{bmatrix} -\frac{e^{-2t}}{2} + \frac{3}{2} & \frac{1}{2} - \frac{e^{-2t}}{2} \\ -\frac{3}{2} + \frac{3e^{-2t}}{2} & \frac{3e^{-2t}}{2} - \frac{1}{2} \end{bmatrix} \int \begin{bmatrix} \frac{3}{2} - \frac{e^{2t}}{2} & -\frac{e^{2t}}{2} + \frac{1}{2} \\ \frac{3e^{2t}}{2} - \frac{3}{2} & -\frac{1}{2} + \frac{3e^{2t}}{2} \end{bmatrix} \begin{bmatrix} -t^2 + 6t \\ 3t^2 - 8t \end{bmatrix} dt \\ &= \begin{bmatrix} -\frac{e^{-2t}}{2} + \frac{3}{2} & \frac{1}{2} - \frac{e^{-2t}}{2} \\ -\frac{3}{2} + \frac{3e^{-2t}}{2} & \frac{3e^{-2t}}{2} - \frac{1}{2} \end{bmatrix} \begin{bmatrix} -\frac{(t-1)^2 e^{2t}}{2} + \frac{5t^2}{2} \\ \frac{3(t-1)^2 e^{2t}}{2} - \frac{5t^2}{2} \end{bmatrix} \\ &= \begin{bmatrix} 2t^2 + t - \frac{1}{2} \\ -t^2 - 3t + \frac{3}{2} \end{bmatrix} \end{aligned}$$

Hence the complete solution is

$$\begin{aligned}\vec{x}(t) &= \vec{x}_h(t) + \vec{x}_p(t) \\ &= \begin{bmatrix} \frac{(-c_1 - c_2)e^{-2t}}{2} + \frac{3c_1}{2} + \frac{c_2}{2} + 2t^2 + t - \frac{1}{2} \\ \frac{(3c_1 + 3c_2)e^{-2t}}{2} - \frac{3c_1}{2} - \frac{c_2}{2} - t^2 - 3t + \frac{3}{2} \end{bmatrix}\end{aligned}$$

16.13.2 Solution using explicit Eigenvalue and Eigenvector method

This is a system of linear ODE's given as

$$\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ -3 & -3 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} + \begin{bmatrix} -t^2 + 6t \\ 3t^2 - 8t \end{bmatrix}$$

Since the system is nonhomogeneous, then the solution is given by

$$\vec{x}(t) = \vec{x}_h(t) + \vec{x}_p(t)$$

Where $\vec{x}_h(t)$ is the homogeneous solution to $\vec{x}'(t) = A\vec{x}(t)$ and $\vec{x}_p(t)$ is a particular solution to $\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$. The particular solution will be found using variation of parameters method applied to the fundamental matrix.

The first step is find the homogeneous solution. We start by finding the eigenvalues of A . This is done by solving the following equation for the eigenvalues λ

$$\det(A - \lambda I) = 0$$

Expanding gives

$$\det\left(\begin{bmatrix} 1 & 1 \\ -3 & -3 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}\right) = 0$$

Therefore

$$\det\left(\begin{bmatrix} 1 - \lambda & 1 \\ -3 & -3 - \lambda \end{bmatrix}\right) = 0$$

Which gives the characteristic equation

$$\lambda^2 + 2\lambda = 0$$

The roots of the above are the eigenvalues.

$$\lambda_1 = -2$$

$$\lambda_2 = 0$$

This table summarises the above result

eigenvalue	algebraic multiplicity	type of eigenvalue
0	1	real eigenvalue
-2	1	real eigenvalue

Now the eigenvector for each eigenvalue are found.

Considering the eigenvalue $\lambda_1 = -2$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} 1 & 1 \\ -3 & -3 \end{bmatrix} - (-2) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 3 & 1 \\ -3 & -1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{cc|c} 3 & 1 & 0 \\ -3 & -1 & 0 \end{array} \right]$$

$$R_2 = R_2 + R_1 \implies \left[\begin{array}{cc|c} 3 & 1 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} 3 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = -\frac{t}{3}\}$

Hence the solution is

$$\begin{bmatrix} -\frac{t}{3} \\ t \end{bmatrix} = \begin{bmatrix} -\frac{t}{3} \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} -\frac{t}{3} \\ t \end{bmatrix} = t \begin{bmatrix} -\frac{1}{3} \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} -\frac{1}{3} \\ 1 \end{bmatrix} = \begin{bmatrix} -\frac{1}{3} \\ 1 \end{bmatrix}$$

Which is normalized to

$$\begin{bmatrix} -\frac{1}{3} \\ 1 \end{bmatrix} = \begin{bmatrix} -1 \\ 3 \end{bmatrix}$$

Considering the eigenvalue $\lambda_2 = 0$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} 1 & 1 \\ -3 & -3 \end{bmatrix} - (0) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 \\ -3 & -3 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{cc|c} 1 & 1 & 0 \\ -3 & -3 & 0 \end{array} \right]$$

$$R_2 = R_2 + 3R_1 \implies \left[\begin{array}{cc|c} 1 & 1 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = -t\}$

Hence the solution is

$$\begin{bmatrix} -t \\ t \end{bmatrix} = \begin{bmatrix} -t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} -t \\ t \end{bmatrix} = t \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

The following table gives a summary of this result. It shows for each eigenvalue the algebraic multiplicity m , and its geometric multiplicity k and the eigenvectors associated with the eigenvalue. If $m > k$ then the eigenvalue is defective which means the number of normal linearly independent eigenvectors associated with this eigenvalue (called the geometric multiplicity k) does not equal the algebraic multiplicity m , and we need to determine an additional $m - k$ generalized eigenvectors for this eigenvalue.

eigenvalue	multiplicity		defective?	eigenvectors
	algebraic m	geometric k		
-2	1	1	No	$\begin{bmatrix} -\frac{1}{3} \\ 1 \end{bmatrix}$
0	1	1	No	$\begin{bmatrix} -1 \\ 1 \end{bmatrix}$

Now that we found the eigenvalues and associated eigenvectors, we will go over each eigenvalue and generate the solution basis. The only problem we need to take care of is if the eigenvalue is defective. Since eigenvalue -2 is real and distinct then the

corresponding eigenvector solution is

$$\begin{aligned}\vec{x}_1(t) &= \vec{v}_1 e^{-2t} \\ &= \begin{bmatrix} -\frac{1}{3} \\ 1 \end{bmatrix} e^{-2t}\end{aligned}$$

Since eigenvalue 0 is real and distinct then the corresponding eigenvector solution is

$$\begin{aligned}\vec{x}_2(t) &= \vec{v}_2 e^0 \\ &= \begin{bmatrix} -1 \\ 1 \end{bmatrix} e^0\end{aligned}$$

Therefore the homogeneous solution is

$$\vec{x}_h(t) = c_1 \vec{x}_1(t) + c_2 \vec{x}_2(t)$$

Which is written as

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = c_1 \begin{bmatrix} -\frac{e^{-2t}}{3} \\ e^{-2t} \end{bmatrix} + c_2 \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

Now that we found homogeneous solution above, we need to find a particular solution $\vec{x}_p(t)$. We will use Variation of parameters. The fundamental matrix is

$$\Phi = \begin{bmatrix} \vec{x}_1 & \vec{x}_2 & \cdots \end{bmatrix}$$

Where \vec{x}_i are the solution basis found above. Therefore the fundamental matrix is

$$\Phi(t) = \begin{bmatrix} -\frac{e^{-2t}}{3} & -1 \\ e^{-2t} & 1 \end{bmatrix}$$

The particular solution is then given by

$$\vec{x}_p(t) = \Phi \int \Phi^{-1} \vec{G}(t) dt$$

But

$$\Phi^{-1} = \begin{bmatrix} \frac{3e^{2t}}{2} & \frac{3e^{2t}}{2} \\ -\frac{3}{2} & -\frac{1}{2} \end{bmatrix}$$

Hence

$$\begin{aligned}
 \vec{x}_p(t) &= \begin{bmatrix} -\frac{e^{-2t}}{3} & -1 \\ e^{-2t} & 1 \end{bmatrix} \int \begin{bmatrix} \frac{3e^{2t}}{2} & \frac{3e^{2t}}{2} \\ -\frac{3}{2} & -\frac{1}{2} \end{bmatrix} \begin{bmatrix} -t^2 + 6t \\ 3t^2 - 8t \end{bmatrix} dt \\
 &= \begin{bmatrix} -\frac{e^{-2t}}{3} & -1 \\ e^{-2t} & 1 \end{bmatrix} \int \begin{bmatrix} 3e^{2t}t(t-1) \\ -5t \end{bmatrix} dt \\
 &= \begin{bmatrix} -\frac{e^{-2t}}{3} & -1 \\ e^{-2t} & 1 \end{bmatrix} \begin{bmatrix} \frac{3(t-1)^2 e^{2t}}{2} \\ -\frac{5t^2}{2} \end{bmatrix} \\
 &= \begin{bmatrix} 2t^2 + t - \frac{1}{2} \\ -t^2 - 3t + \frac{3}{2} \end{bmatrix}
 \end{aligned}$$

Now that we found particular solution, the final solution is

$$\begin{aligned}
 \vec{x}(t) &= \vec{x}_h(t) + \vec{x}_p(t) \\
 \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} &= \begin{bmatrix} -\frac{c_1 e^{-2t}}{3} \\ c_1 e^{-2t} \end{bmatrix} + \begin{bmatrix} -c_2 \\ c_2 \end{bmatrix} + \begin{bmatrix} 2t^2 + t - \frac{1}{2} \\ -t^2 - 3t + \frac{3}{2} \end{bmatrix}
 \end{aligned}$$

Which becomes

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} -\frac{c_1 e^{-2t}}{3} - c_2 + 2t^2 + t - \frac{1}{2} \\ c_1 e^{-2t} + c_2 - t^2 - 3t + \frac{3}{2} \end{bmatrix}$$

16.13.3 Maple step by step solution

Let's solve

$$[x'(t) = -t^2 + x(t) + y(t) + 6t, y'(t) = 3t^2 - 3x(t) - 3y(t) - 8t]$$

- Define vector

$$\vec{x}(t) = \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}$$

- Convert system into a vector equation

$$\vec{x}'(t) = \begin{bmatrix} 1 & 1 \\ -3 & -3 \end{bmatrix} \cdot \vec{x}(t) + \begin{bmatrix} -t^2 + 6t \\ 3t^2 - 8t \end{bmatrix}$$

- System to solve

$$\vec{x}'(t) = \begin{bmatrix} 1 & 1 \\ -3 & -3 \end{bmatrix} \cdot \vec{x}(t) + \begin{bmatrix} -t^2 + 6t \\ 3t^2 - 8t \end{bmatrix}$$

- Define the forcing function

$$\vec{f}(t) = \begin{bmatrix} -t^2 + 6t \\ 3t^2 - 8t \end{bmatrix}$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 1 & 1 \\ -3 & -3 \end{bmatrix}$$

- Rewrite the system as

$$\vec{x}'(t) = A \cdot \vec{x}(t) + \vec{f}$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[-2, \begin{bmatrix} -\frac{1}{3} \\ 1 \end{bmatrix} \right], \left[0, \begin{bmatrix} -1 \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[-2, \begin{bmatrix} -\frac{1}{3} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{x}_1 = e^{-2t} \cdot \begin{bmatrix} -\frac{1}{3} \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[0, \begin{bmatrix} -1 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{x}_2 = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

- General solution of the system of ODEs can be written in terms of the particular solution $\vec{x}_p(t)$

$$\vec{x}(t) = c_1 \vec{x}_1 + c_2 \vec{x}_2 + \vec{x}_p(t)$$

□ Fundamental matrix

- Let $\phi(t)$ be the matrix whose columns are the independent solutions of the homogeneous system

$$\phi(t) = \begin{bmatrix} -\frac{e^{-2t}}{3} & -1 \\ e^{-2t} & 1 \end{bmatrix}$$

- The fundamental matrix, $\Phi(t)$ is a normalized version of $\phi(t)$ satisfying $\Phi(0) = I$ where I is the identity matrix

$$\Phi(t) = \phi(t) \cdot \frac{1}{\phi(0)}$$

- Substitute the value of $\phi(t)$ and $\phi(0)$

$$\Phi(t) = \begin{bmatrix} -\frac{e^{-2t}}{3} & -1 \\ e^{-2t} & 1 \end{bmatrix} \cdot \frac{1}{\begin{bmatrix} -\frac{1}{3} & -1 \\ 1 & 1 \end{bmatrix}}$$

- Evaluate and simplify to get the fundamental matrix

$$\Phi(t) = \begin{bmatrix} -\frac{e^{-2t}}{2} + \frac{3}{2} & \frac{1}{2} - \frac{e^{-2t}}{2} \\ -\frac{3}{2} + \frac{3e^{-2t}}{2} & \frac{3e^{-2t}}{2} - \frac{1}{2} \end{bmatrix}$$

□ Find a particular solution of the system of ODEs using variation of parameters

- Let the particular solution be the fundamental matrix multiplied by $\vec{v}(t)$ and solve for $\vec{v}(t)$

$$\vec{x}_p(t) = \Phi(t) \cdot \vec{v}(t)$$

- Take the derivative of the particular solution

$$\vec{x}'_p(t) = \Phi'(t) \cdot \vec{v}(t) + \Phi(t) \cdot \vec{v}'(t)$$

- Substitute particular solution and its derivative into the system of ODEs

$$\Phi'(t) \cdot \vec{v}(t) + \Phi(t) \cdot \vec{v}'(t) = A \cdot \Phi(t) \cdot \vec{v}(t) + \vec{f}(t)$$

- The fundamental matrix has columns that are solutions to the homogeneous system so its derivative is $A \cdot \Phi(t)$

$$A \cdot \Phi(t) \cdot \vec{v}(t) + \Phi(t) \cdot \vec{v}'(t) = A \cdot \Phi(t) \cdot \vec{v}(t) + \vec{f}(t)$$

- Cancel like terms

$$\Phi(t) \cdot \vec{v}'(t) = \vec{f}(t)$$

- Multiply by the inverse of the fundamental matrix

$$\vec{v}'(t) = \frac{1}{\Phi(t)} \cdot \vec{f}(t)$$

- Integrate to solve for $\vec{v}(t)$

$$\vec{v}(t) = \int_0^t \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds$$

- Plug $\vec{v}(t)$ into the equation for the particular solution

$$\vec{x}_p(t) = \Phi(t) \cdot \left(\int_0^t \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds \right)$$

- Plug in the fundamental matrix and the forcing function and compute

$$\vec{x}_p(t) = \begin{bmatrix} 2t^2 + \frac{e^{-2t}}{2} + t - \frac{1}{2} \\ -t^2 + \frac{3}{2} - \frac{3e^{-2t}}{2} - 3t \end{bmatrix}$$

- Plug particular solution back into general solution

$$\vec{x}(t) = c_1 \vec{x}_1 + c_2 \vec{x}_2 + \begin{bmatrix} 2t^2 + \frac{e^{-2t}}{2} + t - \frac{1}{2} \\ -t^2 + \frac{3}{2} - \frac{3e^{-2t}}{2} - 3t \end{bmatrix}$$

- Substitute in vector of dependent variables

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} \frac{(-2c_1+3)e^{-2t}}{6} + 2t^2 + t - c_2 - \frac{1}{2} \\ c_1 e^{-2t} - t^2 + \frac{3}{2} - \frac{3e^{-2t}}{2} - 3t + c_2 \end{bmatrix}$$

- Solution to the system of ODEs

$$\left\{ x(t) = \frac{(-2c_1+3)e^{-2t}}{6} + 2t^2 + t - c_2 - \frac{1}{2}, y(t) = c_1 e^{-2t} - t^2 + \frac{3}{2} - \frac{3e^{-2t}}{2} - 3t + c_2 \right\}$$

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 43

```
dsolve([2*diff(x(t),t)+diff(y(t),t)+x(t)+y(t)=t^2+4*t,diff(x(t),t)+diff(y(t),t)+2*x(t)+2*y(t)
```

$$x(t) = -\frac{c_1 e^{-2t}}{2} + 2t^2 + t + c_2$$

$$y(t) = -t^2 + \frac{3c_1 e^{-2t}}{2} - 3t + 1 - c_2$$

✓ Solution by Mathematica

Time used: 0.101 (sec). Leaf size: 82

```
DSolve[{2*x'[t]+y'[t]+x[t]+y[t]==t^2+4*t,x'[t]+y'[t]+2*x[t]+2*y[t]==2*t^2-2*t},{x[t],y[t]},t
```

$$x(t) \rightarrow \frac{1}{2}e^{-2t}(e^{2t}(4t^2 + 2t - 1 + 3c_1 + c_2) - c_1 - c_2)$$

$$y(t) \rightarrow \frac{1}{2}(-2t^2 - 6t + 3(c_1 + c_2)e^{-2t} + 3 - 3c_1 - c_2)$$

16.14 problem 14

16.14.1 Solution using Matrix exponential method	4477
16.14.2 Solution using explicit Eigenvalue and Eigenvector method . . .	4479
16.14.3 Maple step by step solution	4484

Internal problem ID [11941]

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Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 7, Systems of linear differential equations. Section 7.1. Exercises page 277

Problem number: 14.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**system of linear ODEs**"

Solve

$$\begin{aligned}x'(t) &= -5 - x(t) - t - y(t) \\y'(t) &= 7 + 2x(t) + 2t + y(t)\end{aligned}$$

16.14.1 Solution using Matrix exponential method

In this method, we will assume we have found the matrix exponential e^{At} already. There are different methods to determine this but will not be shown here. This is a system of linear ODE's given as

$$\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} -1 & -1 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} + \begin{bmatrix} -5 - t \\ 2t + 7 \end{bmatrix}$$

Since the system is nonhomogeneous, then the solution is given by

$$\vec{x}(t) = \vec{x}_h(t) + \vec{x}_p(t)$$

Where $\vec{x}_h(t)$ is the homogeneous solution to $\vec{x}'(t) = A\vec{x}(t)$ and $\vec{x}_p(t)$ is a particular solution to $\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$. The particular solution will be found using variation

of parameters method applied to the fundamental matrix. For the above matrix A , the matrix exponential can be found to be

$$e^{At} = \begin{bmatrix} \cos(t) - \sin(t) & -\sin(t) \\ 2\sin(t) & \cos(t) + \sin(t) \end{bmatrix}$$

Therefore the homogeneous solution is

$$\begin{aligned} \vec{x}_h(t) &= e^{At} \vec{c} \\ &= \begin{bmatrix} \cos(t) - \sin(t) & -\sin(t) \\ 2\sin(t) & \cos(t) + \sin(t) \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} \\ &= \begin{bmatrix} (\cos(t) - \sin(t))c_1 - \sin(t)c_2 \\ 2\sin(t)c_1 + (\cos(t) + \sin(t))c_2 \end{bmatrix} \\ &= \begin{bmatrix} (-c_1 - c_2)\sin(t) + c_1\cos(t) \\ (2c_1 + c_2)\sin(t) + c_2\cos(t) \end{bmatrix} \end{aligned}$$

The particular solution given by

$$\vec{x}_p(t) = e^{At} \int e^{-At} \vec{G}(t) dt$$

But

$$\begin{aligned} e^{-At} &= (e^{At})^{-1} \\ &= \begin{bmatrix} \cos(t) + \sin(t) & \sin(t) \\ -2\sin(t) & \cos(t) - \sin(t) \end{bmatrix} \end{aligned}$$

Hence

$$\begin{aligned} \vec{x}_p(t) &= \begin{bmatrix} \cos(t) - \sin(t) & -\sin(t) \\ 2\sin(t) & \cos(t) + \sin(t) \end{bmatrix} \int \begin{bmatrix} \cos(t) + \sin(t) & \sin(t) \\ -2\sin(t) & \cos(t) - \sin(t) \end{bmatrix} \begin{bmatrix} -5 - t \\ 2t + 7 \end{bmatrix} dt \\ &= \begin{bmatrix} \cos(t) - \sin(t) & -\sin(t) \\ 2\sin(t) & \cos(t) + \sin(t) \end{bmatrix} \begin{bmatrix} (-3 - t)\cos(t) - \sin(t)(t + 4) \\ \sin(t)(2t + 7) - \cos(t) \end{bmatrix} \\ &= \begin{bmatrix} -3 - t \\ -1 \end{bmatrix} \end{aligned}$$

Hence the complete solution is

$$\begin{aligned}\vec{x}(t) &= \vec{x}_h(t) + \vec{x}_p(t) \\ &= \begin{bmatrix} (-c_1 - c_2) \sin(t) + c_1 \cos(t) - 3 - t \\ (2c_1 + c_2) \sin(t) + c_2 \cos(t) - 1 \end{bmatrix}\end{aligned}$$

16.14.2 Solution using explicit Eigenvalue and Eigenvector method

This is a system of linear ODE's given as

$$\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} -1 & -1 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} + \begin{bmatrix} -5 - t \\ 2t + 7 \end{bmatrix}$$

Since the system is nonhomogeneous, then the solution is given by

$$\vec{x}(t) = \vec{x}_h(t) + \vec{x}_p(t)$$

Where $\vec{x}_h(t)$ is the homogeneous solution to $\vec{x}'(t) = A\vec{x}(t)$ and $\vec{x}_p(t)$ is a particular solution to $\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$. The particular solution will be found using variation of parameters method applied to the fundamental matrix.

The first step is find the homogeneous solution. We start by finding the eigenvalues of A . This is done by solving the following equation for the eigenvalues λ

$$\det(A - \lambda I) = 0$$

Expanding gives

$$\det\left(\begin{bmatrix} -1 & -1 \\ 2 & 1 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}\right) = 0$$

Therefore

$$\det\left(\begin{bmatrix} -1 - \lambda & -1 \\ 2 & 1 - \lambda \end{bmatrix}\right) = 0$$

Which gives the characteristic equation

$$\lambda^2 + 1 = 0$$

The roots of the above are the eigenvalues.

$$\lambda_1 = i$$

$$\lambda_2 = -i$$

This table summarises the above result

eigenvalue	algebraic multiplicity	type of eigenvalue
i	1	complex eigenvalue
$-i$	1	complex eigenvalue

Now the eigenvector for each eigenvalue are found.

Considering the eigenvalue $\lambda_1 = -i$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} -1 & -1 \\ 2 & 1 \end{bmatrix} - (-i) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -1+i & -1 \\ 2 & 1+i \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{cc|c} -1+i & -1 & 0 \\ 2 & 1+i & 0 \end{array} \right]$$

$$R_2 = R_2 + (1+i)R_1 \implies \left[\begin{array}{cc|c} -1+i & -1 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} -1+i & -1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = (-\frac{1}{2} - \frac{i}{2})t\}$

Hence the solution is

$$\begin{bmatrix} (-\frac{1}{2} - \frac{i}{2})t \\ t \end{bmatrix} = \begin{bmatrix} (-\frac{1}{2} - \frac{i}{2})t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} (-\frac{1}{2} - \frac{i}{2})t \\ t \end{bmatrix} = t \begin{bmatrix} -\frac{1}{2} - \frac{i}{2} \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} (-\frac{1}{2} - \frac{i}{2}) \\ 1 \end{bmatrix} = \begin{bmatrix} -\frac{1}{2} - \frac{i}{2} \\ 1 \end{bmatrix}$$

Which is normalized to

$$\begin{bmatrix} (-\frac{1}{2} - \frac{i}{2}) \\ 1 \end{bmatrix} = \begin{bmatrix} -1 - i \\ 2 \end{bmatrix}$$

Considering the eigenvalue $\lambda_2 = i$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} -1 & -1 \\ 2 & 1 \end{bmatrix} - (i) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -1 - i & -1 \\ 2 & 1 - i \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{cc|c} -1 - i & -1 & 0 \\ 2 & 1 - i & 0 \end{array} \right]$$

$$R_2 = R_2 + (1 - i)R_1 \implies \left[\begin{array}{cc|c} -1 - i & -1 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} -1 - i & -1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = (-\frac{1}{2} + \frac{i}{2})t\}$

Hence the solution is

$$\begin{bmatrix} (-\frac{1}{2} + \frac{i}{2})t \\ t \end{bmatrix} = \begin{bmatrix} (-\frac{1}{2} + \frac{i}{2})t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} (-\frac{1}{2} + \frac{i}{2})t \\ t \end{bmatrix} = t \begin{bmatrix} -\frac{1}{2} + \frac{i}{2} \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} (-\frac{1}{2} + \frac{i}{2})t \\ t \end{bmatrix} = \begin{bmatrix} -\frac{1}{2} + \frac{i}{2} \\ 1 \end{bmatrix}$$

Which is normalized to

$$\begin{bmatrix} (-\frac{1}{2} + \frac{i}{2})t \\ t \end{bmatrix} = \begin{bmatrix} -1 + i \\ 2 \end{bmatrix}$$

The following table gives a summary of this result. It shows for each eigenvalue the algebraic multiplicity m , and its geometric multiplicity k and the eigenvectors associated with the eigenvalue. If $m > k$ then the eigenvalue is defective which means the number of normal linearly independent eigenvectors associated with this eigenvalue (called the geometric multiplicity k) does not equal the algebraic multiplicity m , and we need to determine an additional $m - k$ generalized eigenvectors for this eigenvalue.

eigenvalue	multiplicity		defective?	eigenvectors
	algebraic m	geometric k		
i	1	1	No	$\begin{bmatrix} -\frac{1}{2} + \frac{i}{2} \\ 1 \end{bmatrix}$
$-i$	1	1	No	$\begin{bmatrix} -\frac{1}{2} - \frac{i}{2} \\ 1 \end{bmatrix}$

Now that we found the eigenvalues and associated eigenvectors, we will go over each eigenvalue and generate the solution basis. The only problem we need to take care of is if the eigenvalue is defective. Therefore the homogeneous solution is

$$\vec{x}_h(t) = c_1 \vec{x}_1(t) + c_2 \vec{x}_2(t)$$

Which is written as

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = c_1 \begin{bmatrix} \left(-\frac{1}{2} + \frac{i}{2}\right) e^{it} \\ e^{it} \end{bmatrix} + c_2 \begin{bmatrix} \left(-\frac{1}{2} - \frac{i}{2}\right) e^{-it} \\ e^{-it} \end{bmatrix}$$

Now that we found homogeneous solution above, we need to find a particular solution $\vec{x}_p(t)$. We will use Variation of parameters. The fundamental matrix is

$$\Phi = \begin{bmatrix} \vec{x}_1 & \vec{x}_2 & \dots \end{bmatrix}$$

Where \vec{x}_i are the solution basis found above. Therefore the fundamental matrix is

$$\Phi(t) = \begin{bmatrix} \left(-\frac{1}{2} + \frac{i}{2}\right) e^{it} & \left(-\frac{1}{2} - \frac{i}{2}\right) e^{-it} \\ e^{it} & e^{-it} \end{bmatrix}$$

The particular solution is then given by

$$\vec{x}_p(t) = \Phi \int \Phi^{-1} \vec{G}(t) dt$$

But

$$\Phi^{-1} = \begin{bmatrix} -ie^{-it} & \left(\frac{1}{2} - \frac{i}{2}\right) e^{-it} \\ ie^{it} & \left(\frac{1}{2} + \frac{i}{2}\right) e^{it} \end{bmatrix}$$

Hence

$$\begin{aligned}
 \vec{x}_p(t) &= \begin{bmatrix} \left(-\frac{1}{2} + \frac{i}{2}\right) e^{it} & \left(-\frac{1}{2} - \frac{i}{2}\right) e^{-it} \\ e^{it} & e^{-it} \end{bmatrix} \int \begin{bmatrix} -ie^{-it} & \left(\frac{1}{2} - \frac{i}{2}\right) e^{-it} \\ ie^{it} & \left(\frac{1}{2} + \frac{i}{2}\right) e^{it} \end{bmatrix} \begin{bmatrix} -5 - t \\ 2t + 7 \end{bmatrix} dt \\
 &= \begin{bmatrix} \left(-\frac{1}{2} + \frac{i}{2}\right) e^{it} & \left(-\frac{1}{2} - \frac{i}{2}\right) e^{-it} \\ e^{it} & e^{-it} \end{bmatrix} \int \begin{bmatrix} \frac{e^{-it}(7+3i+2t)}{2} \\ -\frac{e^{it}(-7+3i-2t)}{2} \end{bmatrix} dt \\
 &= \begin{bmatrix} \left(-\frac{1}{2} + \frac{i}{2}\right) e^{it} & \left(-\frac{1}{2} - \frac{i}{2}\right) e^{-it} \\ e^{it} & e^{-it} \end{bmatrix} \begin{bmatrix} \frac{e^{-it}(2it+7i-1)}{2} \\ -\frac{e^{it}(2it+7i+1)}{2} \end{bmatrix} \\
 &= \begin{bmatrix} -3 - t \\ -1 \end{bmatrix}
 \end{aligned}$$

Now that we found particular solution, the final solution is

$$\begin{aligned}
 \vec{x}(t) &= \vec{x}_h(t) + \vec{x}_p(t) \\
 \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} &= \begin{bmatrix} \left(-\frac{1}{2} + \frac{i}{2}\right) c_1 e^{it} \\ c_1 e^{it} \end{bmatrix} + \begin{bmatrix} \left(-\frac{1}{2} - \frac{i}{2}\right) c_2 e^{-it} \\ c_2 e^{-it} \end{bmatrix} + \begin{bmatrix} -3 - t \\ -1 \end{bmatrix}
 \end{aligned}$$

Which becomes

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} \left(-\frac{1}{2} + \frac{i}{2}\right) c_1 e^{it} + \left(-\frac{1}{2} - \frac{i}{2}\right) c_2 e^{-it} - 3 - t \\ c_1 e^{it} + c_2 e^{-it} - 1 \end{bmatrix}$$

16.14.3 Maple step by step solution

Let's solve

$$[x'(t) = -5 - x(t) - t - y(t), y'(t) = 7 + 2x(t) + 2t + y(t)]$$

- Define vector

$$\vec{x}(t) = \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}$$

- Convert system into a vector equation

$$\vec{x}'(t) = \begin{bmatrix} -1 & -1 \\ 2 & 1 \end{bmatrix} \cdot \vec{x}(t) + \begin{bmatrix} -5 - t \\ 2t + 7 \end{bmatrix}$$

- System to solve

$$\vec{x}'(t) = \begin{bmatrix} -1 & -1 \\ 2 & 1 \end{bmatrix} \cdot \vec{x}(t) + \begin{bmatrix} -5 - t \\ 2t + 7 \end{bmatrix}$$

- Define the forcing function

$$\vec{f}(t) = \begin{bmatrix} -5 - t \\ 2t + 7 \end{bmatrix}$$

- Define the coefficient matrix

$$A = \begin{bmatrix} -1 & -1 \\ 2 & 1 \end{bmatrix}$$

- Rewrite the system as

$$\vec{x}'(t) = A \cdot \vec{x}(t) + \vec{f}$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[-I, \begin{bmatrix} -\frac{1}{2} - \frac{I}{2} \\ 1 \end{bmatrix} \right], \left[I, \begin{bmatrix} -\frac{1}{2} + \frac{I}{2} \\ 1 \end{bmatrix} \right] \right]$$

- Consider complex eigenpair, complex conjugate eigenvalue can be ignored

$$\left[-I, \begin{bmatrix} -\frac{1}{2} - \frac{I}{2} \\ 1 \end{bmatrix} \right]$$

- Solution from eigenpair

$$e^{-It} \cdot \begin{bmatrix} -\frac{1}{2} - \frac{I}{2} \\ 1 \end{bmatrix}$$

- Use Euler identity to write solution in terms of sin and cos

$$(\cos(t) - I \sin(t)) \cdot \begin{bmatrix} -\frac{1}{2} - \frac{I}{2} \\ 1 \end{bmatrix}$$

- Simplify expression

$$\begin{bmatrix} \left(-\frac{1}{2} - \frac{I}{2}\right) (\cos(t) - I \sin(t)) \\ \cos(t) - I \sin(t) \end{bmatrix}$$

- Both real and imaginary parts are solutions to the homogeneous system

$$\left[\begin{array}{l} \vec{x}_1(t) = \left[\begin{array}{c} -\frac{\cos(t)}{2} - \frac{\sin(t)}{2} \\ \cos(t) \end{array} \right], \vec{x}_2(t) = \left[\begin{array}{c} \frac{\sin(t)}{2} - \frac{\cos(t)}{2} \\ -\sin(t) \end{array} \right] \end{array} \right]$$

- General solution of the system of ODEs can be written in terms of the particular solution $\vec{x}_p(t)$
- $$\vec{x}(t) = c_1 \vec{x}_1(t) + c_2 \vec{x}_2(t) + \vec{x}_p(t)$$

□ Fundamental matrix

- Let $\phi(t)$ be the matrix whose columns are the independent solutions of the homogeneous system

$$\phi(t) = \left[\begin{array}{cc} -\frac{\cos(t)}{2} - \frac{\sin(t)}{2} & \frac{\sin(t)}{2} - \frac{\cos(t)}{2} \\ \cos(t) & -\sin(t) \end{array} \right]$$

- The fundamental matrix, $\Phi(t)$ is a normalized version of $\phi(t)$ satisfying $\Phi(0) = I$ where I is the identity matrix

$$\Phi(t) = \phi(t) \cdot \frac{1}{\phi(0)}$$

- Substitute the value of $\phi(t)$ and $\phi(0)$

$$\Phi(t) = \left[\begin{array}{cc} -\frac{\cos(t)}{2} - \frac{\sin(t)}{2} & \frac{\sin(t)}{2} - \frac{\cos(t)}{2} \\ \cos(t) & -\sin(t) \end{array} \right] \cdot \frac{1}{\left[\begin{array}{cc} -\frac{1}{2} & -\frac{1}{2} \\ 1 & 0 \end{array} \right]}$$

- Evaluate and simplify to get the fundamental matrix

$$\Phi(t) = \left[\begin{array}{cc} \cos(t) - \sin(t) & -\sin(t) \\ 2 \sin(t) & \cos(t) + \sin(t) \end{array} \right]$$

□ Find a particular solution of the system of ODEs using variation of parameters

- Let the particular solution be the fundamental matrix multiplied by $\vec{v}(t)$ and solve for $\vec{v}(t)$

$$\vec{x}_p(t) = \Phi(t) \cdot \vec{v}(t)$$

- Take the derivative of the particular solution

$$\vec{x}'_p(t) = \Phi'(t) \cdot \vec{v}(t) + \Phi(t) \cdot \vec{v}'(t)$$

- Substitute particular solution and its derivative into the system of ODEs

$$\Phi'(t) \cdot \vec{v}(t) + \Phi(t) \cdot \vec{v}'(t) = A \cdot \Phi(t) \cdot \vec{v}(t) + \vec{f}(t)$$

- The fundamental matrix has columns that are solutions to the homogeneous system so its derivative is $A \cdot \Phi(t)$

$$A \cdot \Phi(t) \cdot \vec{v}(t) + \Phi(t) \cdot \vec{v}'(t) = A \cdot \Phi(t) \cdot \vec{v}(t) + \vec{f}(t)$$

- Cancel like terms

$$\Phi(t) \cdot \vec{v}'(t) = \vec{f}(t)$$

- Multiply by the inverse of the fundamental matrix

$$\vec{v}'(t) = \frac{1}{\Phi(t)} \cdot \vec{f}(t)$$

- Integrate to solve for $\vec{v}(t)$

$$\vec{v}(t) = \int_0^t \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds$$

- Plug $\vec{v}(t)$ into the equation for the particular solution

$$\vec{x}_p(t) = \Phi(t) \cdot \left(\int_0^t \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds \right)$$

- Plug in the fundamental matrix and the forcing function and compute

$$\vec{x}_p(t) = \begin{bmatrix} -t - 3 + 3 \cos(t) - 4 \sin(t) \\ -1 + \cos(t) + 7 \sin(t) \end{bmatrix}$$

- Plug particular solution back into general solution

$$\vec{x}(t) = c_1 \vec{x}_1(t) + c_2 \vec{x}_2(t) + \begin{bmatrix} -t - 3 + 3 \cos(t) - 4 \sin(t) \\ -1 + \cos(t) + 7 \sin(t) \end{bmatrix}$$

- Substitute in vector of dependent variables

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} \frac{(6-c_1-c_2) \cos(t)}{2} + \frac{(-c_1+c_2-8) \sin(t)}{2} - t - 3 \\ (1+c_1) \cos(t) - 1 + (-c_2+7) \sin(t) \end{bmatrix}$$

- Solution to the system of ODEs

$$\left\{ x(t) = \frac{(6-c_1-c_2) \cos(t)}{2} + \frac{(-c_1+c_2-8) \sin(t)}{2} - t - 3, y(t) = (1+c_1) \cos(t) - 1 + (-c_2+7) \sin(t) \right\}$$

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 42

```
dsolve([3*diff(x(t),t)+2*diff(y(t),t)-x(t)+y(t)=t-1,diff(x(t),t)+diff(y(t),t)-x(t)=t+2],sing
```

$$\begin{aligned} x(t) &= c_2 \sin(t) + c_1 \cos(t) - 3 - t \\ y(t) &= -c_2 \cos(t) + c_1 \sin(t) - 1 - c_2 \sin(t) - c_1 \cos(t) \end{aligned}$$

✓ Solution by Mathematica

Time used: 0.106 (sec). Leaf size: 44

```
DSolve[{3*x'[t]+2*y'[t]-x[t]+y[t]==t-1,x'[t]+y'[t]-x[t]==t+2},{x[t],y[t]},t,IncludeSingularS
```

$$\begin{aligned}x(t) &\rightarrow -t + c_1 \cos(t) - (c_1 + c_2) \sin(t) - 3 \\y(t) &\rightarrow c_2 \cos(t) + (2c_1 + c_2) \sin(t) - 1\end{aligned}$$

16.15 problem 15

16.15.1 Solution using Matrix exponential method 4489

16.15.2 Solution using explicit Eigenvalue and Eigenvector method . . . 4491

16.15.3 Maple step by step solution 4496

Internal problem ID [11942]

Internal file name [OUTPUT/11951_Sunday_April_14_2024_02_31_14_AM_14031841/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 7, Systems of linear differential equations. Section 7.1. Exercises page 277

Problem number: 15.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "system of linear ODEs"

Solve

$$\begin{aligned}x'(t) &= -\frac{7x(t)}{2} - \frac{9y(t)}{2} + \frac{e^t}{2} \\y'(t) &= \frac{3x(t)}{2} + \frac{5y(t)}{2} + \frac{e^t}{2}\end{aligned}$$

16.15.1 Solution using Matrix exponential method

In this method, we will assume we have found the matrix exponential e^{At} already. There are different methods to determine this but will not be shown here. This is a system of linear ODE's given as

$$\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} -\frac{7}{2} & -\frac{9}{2} \\ \frac{3}{2} & \frac{5}{2} \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} + \begin{bmatrix} \frac{e^t}{2} \\ \frac{e^t}{2} \end{bmatrix}$$

Since the system is nonhomogeneous, then the solution is given by

$$\vec{x}(t) = \vec{x}_h(t) + \vec{x}_p(t)$$

Where $\vec{x}_h(t)$ is the homogeneous solution to $\vec{x}'(t) = A\vec{x}(t)$ and $\vec{x}_p(t)$ is a particular solution to $\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$. The particular solution will be found using variation

of parameters method applied to the fundamental matrix. For the above matrix A , the matrix exponential can be found to be

$$e^{At} = \begin{bmatrix} -\frac{(e^{3t}-3)e^{-2t}}{2} & -\frac{3(e^{3t}-1)e^{-2t}}{2} \\ \frac{(e^{3t}-1)e^{-2t}}{2} & \frac{(3e^{3t}-1)e^{-2t}}{2} \end{bmatrix}$$

Therefore the homogeneous solution is

$$\begin{aligned} \vec{x}_h(t) &= e^{At} \vec{c} \\ &= \begin{bmatrix} -\frac{(e^{3t}-3)e^{-2t}}{2} & -\frac{3(e^{3t}-1)e^{-2t}}{2} \\ \frac{(e^{3t}-1)e^{-2t}}{2} & \frac{(3e^{3t}-1)e^{-2t}}{2} \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} \\ &= \begin{bmatrix} -\frac{(e^{3t}-3)e^{-2t}c_1}{2} - \frac{3(e^{3t}-1)e^{-2t}c_2}{2} \\ \frac{(e^{3t}-1)e^{-2t}c_1}{2} + \frac{(3e^{3t}-1)e^{-2t}c_2}{2} \end{bmatrix} \\ &= \begin{bmatrix} -\frac{((c_1+3c_2)e^{3t}-3c_1-3c_2)e^{-2t}}{2} \\ \frac{((c_1+3c_2)e^{3t}-c_1-c_2)e^{-2t}}{2} \end{bmatrix} \end{aligned}$$

The particular solution given by

$$\vec{x}_p(t) = e^{At} \int e^{-At} \vec{G}(t) dt$$

But

$$\begin{aligned} e^{-At} &= (e^{At})^{-1} \\ &= \begin{bmatrix} \frac{3e^{2t}}{2} - \frac{e^{-t}}{2} & \frac{3e^{2t}}{2} - \frac{3e^{-t}}{2} \\ -\frac{e^{2t}}{2} + \frac{e^{-t}}{2} & -\frac{e^{2t}}{2} + \frac{3e^{-t}}{2} \end{bmatrix} \end{aligned}$$

Hence

$$\begin{aligned} \vec{x}_p(t) &= \begin{bmatrix} -\frac{(e^{3t}-3)e^{-2t}}{2} & -\frac{3(e^{3t}-1)e^{-2t}}{2} \\ \frac{(e^{3t}-1)e^{-2t}}{2} & \frac{(3e^{3t}-1)e^{-2t}}{2} \end{bmatrix} \int \begin{bmatrix} \frac{3e^{2t}}{2} - \frac{e^{-t}}{2} & \frac{3e^{2t}}{2} - \frac{3e^{-t}}{2} \\ -\frac{e^{2t}}{2} + \frac{e^{-t}}{2} & -\frac{e^{2t}}{2} + \frac{3e^{-t}}{2} \end{bmatrix} \begin{bmatrix} \frac{e^t}{2} \\ \frac{e^t}{2} \end{bmatrix} dt \\ &= \begin{bmatrix} -\frac{(e^{3t}-3)e^{-2t}}{2} & -\frac{3(e^{3t}-1)e^{-2t}}{2} \\ \frac{(e^{3t}-1)e^{-2t}}{2} & \frac{(3e^{3t}-1)e^{-2t}}{2} \end{bmatrix} \begin{bmatrix} -t + \frac{e^{3t}}{2} \\ t - \frac{e^{3t}}{6} \end{bmatrix} \\ &= \begin{bmatrix} e^t \left(\frac{1}{2} - t \right) \\ e^t \left(t - \frac{1}{6} \right) \end{bmatrix} \end{aligned}$$

Hence the complete solution is

$$\begin{aligned}\vec{x}(t) &= \vec{x}_h(t) + \vec{x}_p(t) \\ &= \begin{bmatrix} -\left(t + \frac{c_1}{2} + \frac{3c_2}{2} - \frac{1}{2}\right) e^{3t} - \frac{3c_1}{2} - \frac{3c_2}{2} e^{-2t} \\ \left(\frac{c_1}{2} + \frac{3c_2}{2} + t - \frac{1}{6}\right) e^{3t} - \frac{c_1}{2} - \frac{c_2}{2} e^{-2t} \end{bmatrix}\end{aligned}$$

16.15.2 Solution using explicit Eigenvalue and Eigenvector method

This is a system of linear ODE's given as

$$\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} -\frac{7}{2} & -\frac{9}{2} \\ \frac{3}{2} & \frac{5}{2} \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} + \begin{bmatrix} \frac{e^t}{2} \\ \frac{e^t}{2} \end{bmatrix}$$

Since the system is nonhomogeneous, then the solution is given by

$$\vec{x}(t) = \vec{x}_h(t) + \vec{x}_p(t)$$

Where $\vec{x}_h(t)$ is the homogeneous solution to $\vec{x}'(t) = A\vec{x}(t)$ and $\vec{x}_p(t)$ is a particular solution to $\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$. The particular solution will be found using variation of parameters method applied to the fundamental matrix.

The first step is find the homogeneous solution. We start by finding the eigenvalues of A . This is done by solving the following equation for the eigenvalues λ

$$\det(A - \lambda I) = 0$$

Expanding gives

$$\det\left(\begin{bmatrix} -\frac{7}{2} & -\frac{9}{2} \\ \frac{3}{2} & \frac{5}{2} \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}\right) = 0$$

Therefore

$$\det\left(\begin{bmatrix} -\frac{7}{2} - \lambda & -\frac{9}{2} \\ \frac{3}{2} & \frac{5}{2} - \lambda \end{bmatrix}\right) = 0$$

Which gives the characteristic equation

$$\lambda^2 + \lambda - 2 = 0$$

The roots of the above are the eigenvalues.

$$\lambda_1 = -2$$

$$\lambda_2 = 1$$

This table summarises the above result

eigenvalue	algebraic multiplicity	type of eigenvalue
-2	1	real eigenvalue
1	1	real eigenvalue

Now the eigenvector for each eigenvalue are found.

Considering the eigenvalue $\lambda_1 = -2$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} -\frac{7}{2} & -\frac{9}{2} \\ \frac{3}{2} & \frac{5}{2} \end{bmatrix} - (-2) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -\frac{3}{2} & -\frac{9}{2} \\ \frac{3}{2} & \frac{9}{2} \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{cc|c} -\frac{3}{2} & -\frac{9}{2} & 0 \\ \frac{3}{2} & \frac{9}{2} & 0 \end{array} \right]$$

$$R_2 = R_2 + R_1 \implies \left[\begin{array}{cc|c} -\frac{3}{2} & -\frac{9}{2} & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} -\frac{3}{2} & -\frac{9}{2} \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = -3t\}$

Hence the solution is

$$\begin{bmatrix} -3t \\ t \end{bmatrix} = \begin{bmatrix} -3t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} -3t \\ t \end{bmatrix} = t \begin{bmatrix} -3 \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} -3 \\ 1 \end{bmatrix}$$

Considering the eigenvalue $\lambda_2 = 1$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} -\frac{7}{2} & -\frac{9}{2} \\ \frac{3}{2} & \frac{5}{2} \end{bmatrix} - (1) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -\frac{9}{2} & -\frac{9}{2} \\ \frac{3}{2} & \frac{3}{2} \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{cc|c} -\frac{9}{2} & -\frac{9}{2} & 0 \\ \frac{3}{2} & \frac{3}{2} & 0 \end{array} \right]$$

$$R_2 = R_2 + \frac{R_1}{3} \implies \left[\begin{array}{cc|c} -\frac{9}{2} & -\frac{9}{2} & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} -\frac{9}{2} & -\frac{9}{2} \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = -t\}$

Hence the solution is

$$\begin{bmatrix} -t \\ t \end{bmatrix} = \begin{bmatrix} -t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} -t \\ t \end{bmatrix} = t \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} -t \\ t \end{bmatrix} = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

The following table gives a summary of this result. It shows for each eigenvalue the algebraic multiplicity m , and its geometric multiplicity k and the eigenvectors associated with the eigenvalue. If $m > k$ then the eigenvalue is defective which means the number of normal linearly independent eigenvectors associated with this eigenvalue (called the geometric multiplicity k) does not equal the algebraic multiplicity m , and we need to determine an additional $m - k$ generalized eigenvectors for this eigenvalue.

eigenvalue	multiplicity		defective?	eigenvectors
	algebraic m	geometric k		
-2	1	1	No	$\begin{bmatrix} -3 \\ 1 \end{bmatrix}$
1	1	1	No	$\begin{bmatrix} -1 \\ 1 \end{bmatrix}$

Now that we found the eigenvalues and associated eigenvectors, we will go over each eigenvalue and generate the solution basis. The only problem we need to take care of is if the eigenvalue is defective. Since eigenvalue -2 is real and distinct then the corresponding eigenvector solution is

$$\begin{aligned} \vec{x}_1(t) &= \vec{v}_1 e^{-2t} \\ &= \begin{bmatrix} -3 \\ 1 \end{bmatrix} e^{-2t} \end{aligned}$$

Since eigenvalue 1 is real and distinct then the corresponding eigenvector solution is

$$\begin{aligned}\vec{x}_2(t) &= \vec{v}_2 e^t \\ &= \begin{bmatrix} -1 \\ 1 \end{bmatrix} e^t\end{aligned}$$

Therefore the homogeneous solution is

$$\vec{x}_h(t) = c_1 \vec{x}_1(t) + c_2 \vec{x}_2(t)$$

Which is written as

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = c_1 \begin{bmatrix} -3e^{-2t} \\ e^{-2t} \end{bmatrix} + c_2 \begin{bmatrix} -e^t \\ e^t \end{bmatrix}$$

Now that we found homogeneous solution above, we need to find a particular solution $\vec{x}_p(t)$. We will use Variation of parameters. The fundamental matrix is

$$\Phi = \begin{bmatrix} \vec{x}_1 & \vec{x}_2 & \dots \end{bmatrix}$$

Where \vec{x}_i are the solution basis found above. Therefore the fundamental matrix is

$$\Phi(t) = \begin{bmatrix} -3e^{-2t} & -e^t \\ e^{-2t} & e^t \end{bmatrix}$$

The particular solution is then given by

$$\vec{x}_p(t) = \Phi \int \Phi^{-1} \vec{G}(t) dt$$

But

$$\Phi^{-1} = \begin{bmatrix} -\frac{e^{2t}}{2} & -\frac{e^{2t}}{2} \\ \frac{e^{-t}}{2} & \frac{3e^{-t}}{2} \end{bmatrix}$$

Hence

$$\begin{aligned}
 \vec{x}_p(t) &= \begin{bmatrix} -3e^{-2t} & -e^t \\ e^{-2t} & e^t \end{bmatrix} \int \begin{bmatrix} -\frac{e^{2t}}{2} & -\frac{e^{2t}}{2} \\ \frac{e^{-t}}{2} & \frac{3e^{-t}}{2} \end{bmatrix} \begin{bmatrix} \frac{e^t}{2} \\ \frac{e^t}{2} \end{bmatrix} dt \\
 &= \begin{bmatrix} -3e^{-2t} & -e^t \\ e^{-2t} & e^t \end{bmatrix} \int \begin{bmatrix} -\frac{e^{3t}}{2} \\ 1 \end{bmatrix} dt \\
 &= \begin{bmatrix} -3e^{-2t} & -e^t \\ e^{-2t} & e^t \end{bmatrix} \begin{bmatrix} -\frac{e^{3t}}{6} \\ t \end{bmatrix} \\
 &= \begin{bmatrix} e^t(\frac{1}{2} - t) \\ e^t(t - \frac{1}{6}) \end{bmatrix}
 \end{aligned}$$

Now that we found particular solution, the final solution is

$$\begin{aligned}
 \vec{x}(t) &= \vec{x}_h(t) + \vec{x}_p(t) \\
 \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} &= \begin{bmatrix} -3c_1e^{-2t} \\ c_1e^{-2t} \end{bmatrix} + \begin{bmatrix} -c_2e^t \\ c_2e^t \end{bmatrix} + \begin{bmatrix} e^t(\frac{1}{2} - t) \\ e^t(t - \frac{1}{6}) \end{bmatrix}
 \end{aligned}$$

Which becomes

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} -((t + c_2 - \frac{1}{2})e^{3t} + 3c_1)e^{-2t} \\ e^{-2t}((c_2 + t - \frac{1}{6})e^{3t} + c_1) \end{bmatrix}$$

16.15.3 Maple step by step solution

Let's solve

$$\left[x'(t) = -\frac{7x(t)}{2} - \frac{9y(t)}{2} + \frac{e^t}{2}, y'(t) = \frac{3x(t)}{2} + \frac{5y(t)}{2} + \frac{e^t}{2} \right]$$

- Define vector

$$\vec{x}(t) = \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}$$

- Convert system into a vector equation

$$\vec{x}'(t) = \begin{bmatrix} -\frac{7}{2} & -\frac{9}{2} \\ \frac{3}{2} & \frac{5}{2} \end{bmatrix} \cdot \vec{x}(t) + \begin{bmatrix} \frac{e^t}{2} \\ \frac{e^t}{2} \end{bmatrix}$$

- System to solve

$$\vec{x}'(t) = \begin{bmatrix} -\frac{7}{2} & -\frac{9}{2} \\ \frac{3}{2} & \frac{5}{2} \end{bmatrix} \cdot \vec{x}(t) + \begin{bmatrix} \frac{e^t}{2} \\ \frac{e^t}{2} \end{bmatrix}$$

- Define the forcing function

$$\vec{f}(t) = \begin{bmatrix} \frac{e^t}{2} \\ \frac{e^t}{2} \end{bmatrix}$$

- Define the coefficient matrix

$$A = \begin{bmatrix} -\frac{7}{2} & -\frac{9}{2} \\ \frac{3}{2} & \frac{5}{2} \end{bmatrix}$$

- Rewrite the system as

$$\vec{x}'(t) = A \cdot \vec{x}(t) + \vec{f}$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[-2, \begin{bmatrix} -3 \\ 1 \end{bmatrix} \right], \left[1, \begin{bmatrix} -1 \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[-2, \begin{bmatrix} -3 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{x}_1 = e^{-2t} \cdot \begin{bmatrix} -3 \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[1, \begin{bmatrix} -1 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{x}_2 = e^t \cdot \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

- General solution of the system of ODEs can be written in terms of the particular solution $\vec{x}_p(t)$

$$\vec{x}(t) = c_1 \vec{x}_1 + c_2 \vec{x}_2 + \vec{x}_p(t)$$

□ Fundamental matrix

- Let $\phi(t)$ be the matrix whose columns are the independent solutions of the homogeneous system

$$\phi(t) = \begin{bmatrix} -3e^{-2t} & -e^t \\ e^{-2t} & e^t \end{bmatrix}$$

- The fundamental matrix, $\Phi(t)$ is a normalized version of $\phi(t)$ satisfying $\Phi(0) = I$ where I is the identity matrix

$$\Phi(t) = \phi(t) \cdot \frac{1}{\phi(0)}$$

- Substitute the value of $\phi(t)$ and $\phi(0)$

$$\Phi(t) = \begin{bmatrix} -3e^{-2t} & -e^t \\ e^{-2t} & e^t \end{bmatrix} \cdot \frac{1}{\begin{bmatrix} -3 & -1 \\ 1 & 1 \end{bmatrix}}$$

- Evaluate and simplify to get the fundamental matrix

$$\Phi(t) = \begin{bmatrix} -\frac{(e^{3t}-3)e^{-2t}}{2} & -\frac{3(e^{3t}-1)e^{-2t}}{2} \\ \frac{(e^{3t}-1)e^{-2t}}{2} & \frac{(3e^{3t}-1)e^{-2t}}{2} \end{bmatrix}$$

□ Find a particular solution of the system of ODEs using variation of parameters

- Let the particular solution be the fundamental matrix multiplied by $\vec{v}(t)$ and solve for $\vec{v}(t)$

$$\vec{x}_p(t) = \Phi(t) \cdot \vec{v}(t)$$

- Take the derivative of the particular solution

$$\vec{x}'_p(t) = \Phi'(t) \cdot \vec{v}(t) + \Phi(t) \cdot \vec{v}'(t)$$

- Substitute particular solution and its derivative into the system of ODEs

$$\Phi'(t) \cdot \vec{v}(t) + \Phi(t) \cdot \vec{v}'(t) = A \cdot \Phi(t) \cdot \vec{v}(t) + \vec{f}(t)$$

- The fundamental matrix has columns that are solutions to the homogeneous system so its derivative is $A \cdot \Phi(t)$

$$A \cdot \Phi(t) \cdot \vec{v}(t) + \Phi(t) \cdot \vec{v}'(t) = A \cdot \Phi(t) \cdot \vec{v}(t) + \vec{f}(t)$$

- Cancel like terms

$$\Phi(t) \cdot \vec{v}'(t) = \vec{f}(t)$$

- Multiply by the inverse of the fundamental matrix

$$\vec{v}'(t) = \frac{1}{\Phi(t)} \cdot \vec{f}(t)$$

- Integrate to solve for $\vec{v}(t)$

$$\vec{v}(t) = \int_0^t \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds$$

- Plug $\vec{v}(t)$ into the equation for the particular solution

$$\vec{x}_p(t) = \Phi(t) \cdot \left(\int_0^t \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds \right)$$

- Plug in the fundamental matrix and the forcing function and compute

$$\vec{x}_p(t) = \begin{bmatrix} \frac{(1-2t)e^{-2t}e^{3t}}{2} - \frac{e^{-2t}}{2} \\ \frac{(6t-1)e^{-2t}e^{3t}}{6} + \frac{e^{-2t}}{6} \end{bmatrix}$$

- Plug particular solution back into general solution

$$\vec{x}(t) = c_1 \vec{x}_1 + c_2 \vec{x}_2 + \begin{bmatrix} \frac{(1-2t)e^{-2t}e^{3t}}{2} - \frac{e^{-2t}}{2} \\ \frac{(6t-1)e^{-2t}e^{3t}}{6} + \frac{e^{-2t}}{6} \end{bmatrix}$$

- Substitute in vector of dependent variables

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} -\left((t + c_2 - \frac{1}{2})e^{3t} + 3c_1 + \frac{1}{2}\right)e^{-2t} \\ \left((c_2 + t - \frac{1}{6})e^{3t} + c_1 + \frac{1}{6}\right)e^{-2t} \end{bmatrix}$$

- Solution to the system of ODEs

$$\{x(t) = -\left((t + c_2 - \frac{1}{2})e^{3t} + 3c_1 + \frac{1}{2}\right)e^{-2t}, y(t) = \left((c_2 + t - \frac{1}{6})e^{3t} + c_1 + \frac{1}{6}\right)e^{-2t}\}$$

✓ Solution by Maple

Time used: 0.032 (sec). Leaf size: 45

```
dsolve([2*dif(x(t),t)+4*dif(y(t),t)+x(t)-y(t)=3*exp(t),dif(x(t),t)+dif(y(t),t)+2*x(t)+2*
```

$$x(t) = c_2 e^t + c_1 e^{-2t} - e^t t$$

$$y(t) = -c_2 e^t - \frac{c_1 e^{-2t}}{3} + e^t t + \frac{e^t}{3}$$

✓ Solution by Mathematica

Time used: 0.014 (sec). Leaf size: 76

```
DSolve[{2*x'[t]+4*y'[t]+x[t]-y[t]==3*Exp[t],x'[t]+y'[t]+2*x[t]+2*y[t]==Exp[t]},{x[t],y[t]},t
```

$$x(t) \rightarrow \frac{3}{2}(c_1 + c_2)e^{-2t} - \frac{1}{2}e^t(2t - 1 + c_1 + 3c_2)$$

$$y(t) \rightarrow \frac{1}{6}e^t(6t - 1 + 3c_1 + 9c_2) - \frac{1}{2}(c_1 + c_2)e^{-2t}$$

16.16 problem 16

16.16.1 Solution using Matrix exponential method	4501
16.16.2 Solution using explicit Eigenvalue and Eigenvector method . . .	4503
16.16.3 Maple step by step solution	4508

Internal problem ID [11943]

Internal file name [OUTPUT/11952_Sunday_April_14_2024_02_31_15_AM_15795806/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 7, Systems of linear differential equations. Section 7.1. Exercises page 277

Problem number: 16.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**system of linear ODEs**"

Solve

$$\begin{aligned}x'(t) &= 2x(t) - 2t - t^2 \\y'(t) &= -3x(t) + y(t) + 2t + 2t^2\end{aligned}$$

16.16.1 Solution using Matrix exponential method

In this method, we will assume we have found the matrix exponential e^{At} already. There are different methods to determine this but will not be shown here. This is a system of linear ODE's given as

$$\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} 2 & 0 \\ -3 & 1 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} + \begin{bmatrix} -t^2 - 2t \\ 2t^2 + 2t \end{bmatrix}$$

Since the system is nonhomogeneous, then the solution is given by

$$\vec{x}(t) = \vec{x}_h(t) + \vec{x}_p(t)$$

Where $\vec{x}_h(t)$ is the homogeneous solution to $\vec{x}'(t) = A\vec{x}(t)$ and $\vec{x}_p(t)$ is a particular solution to $\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$. The particular solution will be found using variation

of parameters method applied to the fundamental matrix. For the above matrix A , the matrix exponential can be found to be

$$e^{At} = \begin{bmatrix} e^{2t} & 0 \\ -3e^{2t} + 3e^t & e^t \end{bmatrix}$$

Therefore the homogeneous solution is

$$\begin{aligned} \vec{x}_h(t) &= e^{At} \vec{c} \\ &= \begin{bmatrix} e^{2t} & 0 \\ -3e^{2t} + 3e^t & e^t \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} \\ &= \begin{bmatrix} e^{2t}c_1 \\ (-3e^{2t} + 3e^t)c_1 + e^t c_2 \end{bmatrix} \end{aligned}$$

The particular solution given by

$$\vec{x}_p(t) = e^{At} \int e^{-At} \vec{G}(t) dt$$

But

$$\begin{aligned} e^{-At} &= (e^{At})^{-1} \\ &= \begin{bmatrix} e^{-2t} & 0 \\ 3e^{-2t}(e^t - 1) & e^{-t} \end{bmatrix} \end{aligned}$$

Hence

$$\begin{aligned} \vec{x}_p(t) &= \begin{bmatrix} e^{2t} & 0 \\ -3e^{2t} + 3e^t & e^t \end{bmatrix} \int \begin{bmatrix} e^{-2t} & 0 \\ 3e^{-2t}(e^t - 1) & e^{-t} \end{bmatrix} \begin{bmatrix} -t^2 - 2t \\ 2t^2 + 2t \end{bmatrix} dt \\ &= \begin{bmatrix} e^{2t} & 0 \\ -3e^{2t} + 3e^t & e^t \end{bmatrix} \begin{bmatrix} \frac{e^{-2t}(2t^2+6t+3)}{4} \\ \frac{3(-2t^2-6t-3)e^{-2t}}{4} + e^{-t}(t^2 + 6t + 6) \end{bmatrix} \\ &= \begin{bmatrix} \frac{1}{2}t^2 + \frac{3}{2}t + \frac{3}{4} \\ -\frac{1}{2}t^2 + \frac{3}{2}t + \frac{15}{4} \end{bmatrix} \end{aligned}$$

Hence the complete solution is

$$\begin{aligned} \vec{x}(t) &= \vec{x}_h(t) + \vec{x}_p(t) \\ &= \begin{bmatrix} e^{2t}c_1 + \frac{t^2}{2} + \frac{3t}{2} + \frac{3}{4} \\ \frac{15}{4} - 3e^{2t}c_1 + e^t(3c_1 + c_2) - \frac{t^2}{2} + \frac{3t}{2} \end{bmatrix} \end{aligned}$$

16.16.2 Solution using explicit Eigenvalue and Eigenvector method

This is a system of linear ODE's given as

$$\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} 2 & 0 \\ -3 & 1 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} + \begin{bmatrix} -t^2 - 2t \\ 2t^2 + 2t \end{bmatrix}$$

Since the system is nonhomogeneous, then the solution is given by

$$\vec{x}(t) = \vec{x}_h(t) + \vec{x}_p(t)$$

Where $\vec{x}_h(t)$ is the homogeneous solution to $\vec{x}'(t) = A\vec{x}(t)$ and $\vec{x}_p(t)$ is a particular solution to $\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$. The particular solution will be found using variation of parameters method applied to the fundamental matrix.

The first step is find the homogeneous solution. We start by finding the eigenvalues of A . This is done by solving the following equation for the eigenvalues λ

$$\det(A - \lambda I) = 0$$

Expanding gives

$$\det \left(\begin{bmatrix} 2 & 0 \\ -3 & 1 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) = 0$$

Therefore

$$\det \left(\begin{bmatrix} 2 - \lambda & 0 \\ -3 & 1 - \lambda \end{bmatrix} \right) = 0$$

Since the matrix A is triangular matrix, then the determinant is the product of the elements along the diagonal. Therefore the above becomes

$$(2 - \lambda)(1 - \lambda) = 0$$

The roots of the above are the eigenvalues.

$$\lambda_1 = 2$$

$$\lambda_2 = 1$$

This table summarises the above result

eigenvalue	algebraic multiplicity	type of eigenvalue
1	1	real eigenvalue
2	1	real eigenvalue

Now the eigenvector for each eigenvalue are found.

Considering the eigenvalue $\lambda_1 = 1$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} 2 & 0 \\ -3 & 1 \end{bmatrix} - (1) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 \\ -3 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{cc|c} 1 & 0 & 0 \\ -3 & 0 & 0 \end{array} \right]$$

$$R_2 = R_2 + 3R_1 \implies \left[\begin{array}{cc|c} 1 & 0 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = 0\}$

Hence the solution is

$$\begin{bmatrix} 0 \\ t \end{bmatrix} = \begin{bmatrix} 0 \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} 0 \\ t \end{bmatrix} = t \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} 0 \\ t \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

Considering the eigenvalue $\lambda_2 = 2$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} 2 & 0 \\ -3 & 1 \end{bmatrix} - (2) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$
$$\begin{bmatrix} 0 & 0 \\ -3 & -1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{cc|c} 0 & 0 & 0 \\ -3 & -1 & 0 \end{array} \right]$$

Since the current pivot $A(1,1)$ is zero, then the current pivot row is replaced with a row with a non-zero pivot. Swapping row 1 and row 2 gives

$$\left[\begin{array}{cc|c} -3 & -1 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} -3 & -1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = -\frac{t}{3}\}$

Hence the solution is

$$\begin{bmatrix} -\frac{t}{3} \\ t \end{bmatrix} = \begin{bmatrix} -\frac{t}{3} \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} -\frac{t}{3} \\ t \end{bmatrix} = t \begin{bmatrix} -\frac{1}{3} \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} -\frac{t}{3} \\ t \end{bmatrix} = \begin{bmatrix} -\frac{1}{3} \\ 1 \end{bmatrix}$$

Which is normalized to

$$\begin{bmatrix} -\frac{t}{3} \\ t \end{bmatrix} = \begin{bmatrix} -1 \\ 3 \end{bmatrix}$$

The following table gives a summary of this result. It shows for each eigenvalue the algebraic multiplicity m , and its geometric multiplicity k and the eigenvectors associated with the eigenvalue. If $m > k$ then the eigenvalue is defective which means the number of normal linearly independent eigenvectors associated with this eigenvalue (called the geometric multiplicity k) does not equal the algebraic multiplicity m , and we need to determine an additional $m - k$ generalized eigenvectors for this eigenvalue.

eigenvalue	multiplicity		defective?	eigenvectors
	algebraic m	geometric k		
2	1	1	No	$\begin{bmatrix} -\frac{1}{3} \\ 1 \end{bmatrix}$
1	1	1	No	$\begin{bmatrix} 0 \\ 1 \end{bmatrix}$

Now that we found the eigenvalues and associated eigenvectors, we will go over each eigenvalue and generate the solution basis. The only problem we need to take care of is if the eigenvalue is defective. Since eigenvalue 2 is real and distinct then the corresponding eigenvector solution is

$$\begin{aligned} \vec{x}_1(t) &= \vec{v}_1 e^{2t} \\ &= \begin{bmatrix} -\frac{1}{3} \\ 1 \end{bmatrix} e^{2t} \end{aligned}$$

Since eigenvalue 1 is real and distinct then the corresponding eigenvector solution is

$$\begin{aligned} \vec{x}_2(t) &= \vec{v}_2 e^t \\ &= \begin{bmatrix} 0 \\ 1 \end{bmatrix} e^t \end{aligned}$$

Therefore the homogeneous solution is

$$\vec{x}_h(t) = c_1 \vec{x}_1(t) + c_2 \vec{x}_2(t)$$

Which is written as

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = c_1 \begin{bmatrix} -\frac{e^{2t}}{3} \\ e^{2t} \end{bmatrix} + c_2 \begin{bmatrix} 0 \\ e^t \end{bmatrix}$$

Now that we found homogeneous solution above, we need to find a particular solution $\vec{x}_p(t)$. We will use Variation of parameters. The fundamental matrix is

$$\Phi = \begin{bmatrix} \vec{x}_1 & \vec{x}_2 & \cdots \end{bmatrix}$$

Where \vec{x}_i are the solution basis found above. Therefore the fundamental matrix is

$$\Phi(t) = \begin{bmatrix} -\frac{e^{2t}}{3} & 0 \\ e^{2t} & e^t \end{bmatrix}$$

The particular solution is then given by

$$\vec{x}_p(t) = \Phi \int \Phi^{-1} \vec{G}(t) dt$$

But

$$\Phi^{-1} = \begin{bmatrix} -3e^{-2t} & 0 \\ 3e^{-t} & e^{-t} \end{bmatrix}$$

Hence

$$\begin{aligned} \vec{x}_p(t) &= \begin{bmatrix} -\frac{e^{2t}}{3} & 0 \\ e^{2t} & e^t \end{bmatrix} \int \begin{bmatrix} -3e^{-2t} & 0 \\ 3e^{-t} & e^{-t} \end{bmatrix} \begin{bmatrix} -t^2 - 2t \\ 2t^2 + 2t \end{bmatrix} dt \\ &= \begin{bmatrix} -\frac{e^{2t}}{3} & 0 \\ e^{2t} & e^t \end{bmatrix} \int \begin{bmatrix} 3e^{-2t}t(t+2) \\ -e^{-t}t(t+4) \end{bmatrix} dt \\ &= \begin{bmatrix} -\frac{e^{2t}}{3} & 0 \\ e^{2t} & e^t \end{bmatrix} \begin{bmatrix} -\frac{3e^{-2t}(2t^2+6t+3)}{4} \\ e^{-t}(t^2+6t+6) \end{bmatrix} \\ &= \begin{bmatrix} \frac{1}{2}t^2 + \frac{3}{2}t + \frac{3}{4} \\ -\frac{1}{2}t^2 + \frac{3}{2}t + \frac{15}{4} \end{bmatrix} \end{aligned}$$

Now that we found particular solution, the final solution is

$$\vec{x}(t) = \vec{x}_h(t) + \vec{x}_p(t)$$

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} -\frac{c_1 e^{2t}}{3} \\ c_1 e^{2t} \end{bmatrix} + \begin{bmatrix} 0 \\ c_2 e^t \end{bmatrix} + \begin{bmatrix} \frac{1}{2}t^2 + \frac{3}{2}t + \frac{3}{4} \\ -\frac{1}{2}t^2 + \frac{3}{2}t + \frac{15}{4} \end{bmatrix}$$

Which becomes

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} -\frac{c_1 e^{2t}}{3} + \frac{t^2}{2} + \frac{3t}{2} + \frac{3}{4} \\ c_1 e^{2t} + c_2 e^t - \frac{t^2}{2} + \frac{3t}{2} + \frac{15}{4} \end{bmatrix}$$

16.16.3 Maple step by step solution

Let's solve

$$[x'(t) = 2x(t) - 2t - t^2, y'(t) = -3x(t) + y(t) + 2t + 2t^2]$$

- Define vector

$$\vec{x}(t) = \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}$$

- Convert system into a vector equation

$$\vec{x}'(t) = \begin{bmatrix} 2 & 0 \\ -3 & 1 \end{bmatrix} \cdot \vec{x}(t) + \begin{bmatrix} -t^2 - 2t \\ 2t^2 + 2t \end{bmatrix}$$

- System to solve

$$\vec{x}'(t) = \begin{bmatrix} 2 & 0 \\ -3 & 1 \end{bmatrix} \cdot \vec{x}(t) + \begin{bmatrix} -t^2 - 2t \\ 2t^2 + 2t \end{bmatrix}$$

- Define the forcing function

$$\vec{f}(t) = \begin{bmatrix} -t^2 - 2t \\ 2t^2 + 2t \end{bmatrix}$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 2 & 0 \\ -3 & 1 \end{bmatrix}$$

- Rewrite the system as

$$\vec{x}'(t) = A \cdot \vec{x}(t) + \vec{f}$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[1, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right], \left[2, \begin{bmatrix} -\frac{1}{3} \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[1, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{x}_1 = e^t \cdot \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[2, \begin{bmatrix} -\frac{1}{3} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{x}_2 = e^{2t} \cdot \begin{bmatrix} -\frac{1}{3} \\ 1 \end{bmatrix}$$

- General solution of the system of ODEs can be written in terms of the particular solution $\vec{x}_p(t)$

$$\vec{x}(t) = c_1 \vec{x}_1 + c_2 \vec{x}_2 + \vec{x}_p(t)$$

- Fundamental matrix

- Let $\phi(t)$ be the matrix whose columns are the independent solutions of the homogeneous system

$$\phi(t) = \begin{bmatrix} 0 & -\frac{e^{2t}}{3} \\ e^t & e^{2t} \end{bmatrix}$$

- The fundamental matrix, $\Phi(t)$ is a normalized version of $\phi(t)$ satisfying $\Phi(0) = I$ where I is the identity matrix

$$\Phi(t) = \phi(t) \cdot \frac{1}{\phi(0)}$$

- Substitute the value of $\phi(t)$ and $\phi(0)$

$$\Phi(t) = \begin{bmatrix} 0 & -\frac{e^{2t}}{3} \\ e^t & e^{2t} \end{bmatrix} \cdot \frac{1}{\begin{bmatrix} 0 & -\frac{1}{3} \\ 1 & 1 \end{bmatrix}}$$

- Evaluate and simplify to get the fundamental matrix

$$\Phi(t) = \begin{bmatrix} e^{2t} & 0 \\ -3e^{2t} + 3e^t & e^t \end{bmatrix}$$

- Find a particular solution of the system of ODEs using variation of parameters

- Let the particular solution be the fundamental matrix multiplied by $\vec{v}(t)$ and solve for $\vec{v}(t)$

$$\vec{x}_p(t) = \Phi(t) \cdot \vec{v}(t)$$

- Take the derivative of the particular solution

$$\vec{x}'_p(t) = \Phi'(t) \cdot \vec{v}(t) + \Phi(t) \cdot \vec{v}'(t)$$

- Substitute particular solution and its derivative into the system of ODEs

$$\Phi'(t) \cdot \vec{v}(t) + \Phi(t) \cdot \vec{v}'(t) = A \cdot \Phi(t) \cdot \vec{v}(t) + \vec{f}(t)$$

- The fundamental matrix has columns that are solutions to the homogeneous system so its derivative is $A \cdot \Phi(t) \cdot \vec{v}(t)$

$$A \cdot \Phi(t) \cdot \vec{v}(t) + \Phi(t) \cdot \vec{v}'(t) = A \cdot \Phi(t) \cdot \vec{v}(t) + \vec{f}(t)$$

- Cancel like terms

$$\Phi(t) \cdot \vec{v}'(t) = \vec{f}(t)$$

- Multiply by the inverse of the fundamental matrix

$$\vec{v}'(t) = \frac{1}{\Phi(t)} \cdot \vec{f}(t)$$

- Integrate to solve for $\vec{v}(t)$

$$\vec{v}(t) = \int_0^t \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds$$

- Plug $\vec{v}(t)$ into the equation for the particular solution

$$\vec{x}_p(t) = \Phi(t) \cdot \left(\int_0^t \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds \right)$$

- Plug in the fundamental matrix and the forcing function and compute

$$\vec{x}_p(t) = \begin{bmatrix} \frac{t^2}{2} - \frac{3e^{2t}}{4} + \frac{3t}{2} + \frac{3}{4} \\ -\frac{t^2}{2} + \frac{9e^{2t}}{4} - 6e^t + \frac{3t}{2} + \frac{15}{4} \end{bmatrix}$$

- Plug particular solution back into general solution

$$\vec{x}(t) = c_1 \vec{x}_1 + c_2 \vec{x}_2 + \begin{bmatrix} \frac{t^2}{2} - \frac{3e^{2t}}{4} + \frac{3t}{2} + \frac{3}{4} \\ -\frac{t^2}{2} + \frac{9e^{2t}}{4} - 6e^t + \frac{3t}{2} + \frac{15}{4} \end{bmatrix}$$

- Substitute in vector of dependent variables

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} \frac{(-4c_2-9)e^{2t}}{12} + \frac{t^2}{2} + \frac{3t}{2} + \frac{3}{4} \\ \frac{15}{4} + \frac{(4c_2+9)e^{2t}}{4} + (c_1-6)e^t - \frac{t^2}{2} + \frac{3t}{2} \end{bmatrix}$$

- Solution to the system of ODEs

$$\left\{ x(t) = \frac{(-4c_2-9)e^{2t}}{12} + \frac{t^2}{2} + \frac{3t}{2} + \frac{3}{4}, y(t) = \frac{15}{4} + \frac{(4c_2+9)e^{2t}}{4} + (c_1-6)e^t - \frac{t^2}{2} + \frac{3t}{2} \right\}$$

✓ Solution by Maple

Time used: 0.031 (sec). Leaf size: 45

```
dsolve([2*diff(x(t),t)+diff(y(t),t)-x(t)-y(t)=-2*t,diff(x(t),t)+diff(y(t),t)+x(t)-y(t)=t^2],
```

$$x(t) = \frac{t^2}{2} + \frac{3t}{2} + \frac{3}{4} + c_2 e^{2t}$$

$$y(t) = \frac{15}{4} - 3c_2 e^{2t} + \frac{3t}{2} - \frac{t^2}{2} + c_1 e^t$$

✓ Solution by Mathematica

Time used: 0.215 (sec). Leaf size: 67

```
DSolve[{2*x'[t]+y'[t]-x[t]-y[t]==-2*t,x'[t]+y'[t]+x[t]-y[t]==t^2},{x[t],y[t]},t,IncludeSingu
```

$$x(t) \rightarrow \frac{1}{4}(2t^2 + 6t + 4c_1 e^{2t} + 3)$$

$$y(t) \rightarrow -\frac{t^2}{2} + \frac{3t}{2} - 3c_1 e^{2t} + (3c_1 + c_2)e^t + \frac{15}{4}$$

16.17 problem 17

16.17.1 Solution using Matrix exponential method	4512
16.17.2 Solution using explicit Eigenvalue and Eigenvector method . . .	4514
16.17.3 Maple step by step solution	4519

Internal problem ID [11944]

Internal file name [OUTPUT/11953_Sunday_April_14_2024_02_31_16_AM_41821047/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 7, Systems of linear differential equations. Section 7.1. Exercises page 277

Problem number: 17.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**system of linear ODEs**"

Solve

$$\begin{aligned}x'(t) &= 3x(t) - t + 1 \\y'(t) &= -5x(t) + y(t) + 2t - 1\end{aligned}$$

16.17.1 Solution using Matrix exponential method

In this method, we will assume we have found the matrix exponential e^{At} already. There are different methods to determine this but will not be shown here. This is a system of linear ODE's given as

$$\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} 3 & 0 \\ -5 & 1 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} + \begin{bmatrix} 1 - t \\ 2t - 1 \end{bmatrix}$$

Since the system is nonhomogeneous, then the solution is given by

$$\vec{x}(t) = \vec{x}_h(t) + \vec{x}_p(t)$$

Where $\vec{x}_h(t)$ is the homogeneous solution to $\vec{x}'(t) = A\vec{x}(t)$ and $\vec{x}_p(t)$ is a particular solution to $\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$. The particular solution will be found using variation

of parameters method applied to the fundamental matrix. For the above matrix A , the matrix exponential can be found to be

$$e^{At} = \begin{bmatrix} e^{3t} & 0 \\ -\frac{5e^{3t}}{2} + \frac{5e^t}{2} & e^t \end{bmatrix}$$

Therefore the homogeneous solution is

$$\begin{aligned} \vec{x}_h(t) &= e^{At} \vec{c} \\ &= \begin{bmatrix} e^{3t} & 0 \\ -\frac{5e^{3t}}{2} + \frac{5e^t}{2} & e^t \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} \\ &= \begin{bmatrix} e^{3t}c_1 \\ \left(-\frac{5e^{3t}}{2} + \frac{5e^t}{2}\right)c_1 + e^t c_2 \end{bmatrix} \end{aligned}$$

The particular solution given by

$$\vec{x}_p(t) = e^{At} \int e^{-At} \vec{G}(t) dt$$

But

$$\begin{aligned} e^{-At} &= (e^{At})^{-1} \\ &= \begin{bmatrix} e^{-3t} & 0 \\ \frac{5e^{-3t}(e^{2t}-1)}{2} & e^{-t} \end{bmatrix} \end{aligned}$$

Hence

$$\begin{aligned} \vec{x}_p(t) &= \begin{bmatrix} e^{3t} & 0 \\ -\frac{5e^{3t}}{2} + \frac{5e^t}{2} & e^t \end{bmatrix} \int \begin{bmatrix} e^{-3t} & 0 \\ \frac{5e^{-3t}(e^{2t}-1)}{2} & e^{-t} \end{bmatrix} \begin{bmatrix} 1-t \\ 2t-1 \end{bmatrix} dt \\ &= \begin{bmatrix} e^{3t} & 0 \\ -\frac{5e^{3t}}{2} + \frac{5e^t}{2} & e^t \end{bmatrix} \begin{bmatrix} \frac{e^{-3t}(-2+3t)}{9} \\ \frac{5(2-3t)e^{-3t}}{18} + \frac{e^{-t}(-2+t)}{2} \end{bmatrix} \\ &= \begin{bmatrix} -\frac{2}{9} + \frac{t}{3} \\ -\frac{4}{9} - \frac{t}{3} \end{bmatrix} \end{aligned}$$

Hence the complete solution is

$$\begin{aligned} \vec{x}(t) &= \vec{x}_h(t) + \vec{x}_p(t) \\ &= \begin{bmatrix} e^{3t}c_1 - \frac{2}{9} + \frac{t}{3} \\ -\frac{4}{9} - \frac{5e^{3t}c_1}{2} + \frac{e^t(5c_1+2c_2)}{2} - \frac{t}{3} \end{bmatrix} \end{aligned}$$

16.17.2 Solution using explicit Eigenvalue and Eigenvector method

This is a system of linear ODE's given as

$$\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} 3 & 0 \\ -5 & 1 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} + \begin{bmatrix} 1-t \\ 2t-1 \end{bmatrix}$$

Since the system is nonhomogeneous, then the solution is given by

$$\vec{x}(t) = \vec{x}_h(t) + \vec{x}_p(t)$$

Where $\vec{x}_h(t)$ is the homogeneous solution to $\vec{x}'(t) = A\vec{x}(t)$ and $\vec{x}_p(t)$ is a particular solution to $\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$. The particular solution will be found using variation of parameters method applied to the fundamental matrix.

The first step is find the homogeneous solution. We start by finding the eigenvalues of A . This is done by solving the following equation for the eigenvalues λ

$$\det(A - \lambda I) = 0$$

Expanding gives

$$\det \left(\begin{bmatrix} 3 & 0 \\ -5 & 1 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) = 0$$

Therefore

$$\det \left(\begin{bmatrix} 3-\lambda & 0 \\ -5 & 1-\lambda \end{bmatrix} \right) = 0$$

Since the matrix A is triangular matrix, then the determinant is the product of the elements along the diagonal. Therefore the above becomes

$$(3 - \lambda)(1 - \lambda) = 0$$

The roots of the above are the eigenvalues.

$$\lambda_1 = 3$$

$$\lambda_2 = 1$$

This table summarises the above result

eigenvalue	algebraic multiplicity	type of eigenvalue
1	1	real eigenvalue
3	1	real eigenvalue

Now the eigenvector for each eigenvalue are found.

Considering the eigenvalue $\lambda_1 = 1$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} 3 & 0 \\ -5 & 1 \end{bmatrix} - (1) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 2 & 0 \\ -5 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{cc|c} 2 & 0 & 0 \\ -5 & 0 & 0 \end{array} \right]$$

$$R_2 = R_2 + \frac{5R_1}{2} \implies \left[\begin{array}{cc|c} 2 & 0 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} 2 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = 0\}$

Hence the solution is

$$\begin{bmatrix} 0 \\ t \end{bmatrix} = \begin{bmatrix} 0 \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} 0 \\ t \end{bmatrix} = t \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} 0 \\ t \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

Considering the eigenvalue $\lambda_2 = 3$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} 3 & 0 \\ -5 & 1 \end{bmatrix} - (3) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 0 \\ -5 & -2 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{cc|c} 0 & 0 & 0 \\ -5 & -2 & 0 \end{array} \right]$$

Since the current pivot $A(1,1)$ is zero, then the current pivot row is replaced with a row with a non-zero pivot. Swapping row 1 and row 2 gives

$$\left[\begin{array}{cc|c} -5 & -2 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} -5 & -2 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = -\frac{2t}{5}\}$

Hence the solution is

$$\begin{bmatrix} -\frac{2t}{5} \\ t \end{bmatrix} = \begin{bmatrix} -\frac{2t}{5} \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} -\frac{2t}{5} \\ t \end{bmatrix} = t \begin{bmatrix} -\frac{2}{5} \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} -\frac{2t}{5} \\ t \end{bmatrix} = \begin{bmatrix} -\frac{2}{5} \\ 1 \end{bmatrix}$$

Which is normalized to

$$\begin{bmatrix} -\frac{2t}{5} \\ t \end{bmatrix} = \begin{bmatrix} -2 \\ 5 \end{bmatrix}$$

The following table gives a summary of this result. It shows for each eigenvalue the algebraic multiplicity m , and its geometric multiplicity k and the eigenvectors associated with the eigenvalue. If $m > k$ then the eigenvalue is defective which means the number of normal linearly independent eigenvectors associated with this eigenvalue (called the geometric multiplicity k) does not equal the algebraic multiplicity m , and we need to determine an additional $m - k$ generalized eigenvectors for this eigenvalue.

eigenvalue	multiplicity		defective?	eigenvectors
	algebraic m	geometric k		
3	1	1	No	$\begin{bmatrix} -\frac{2}{5} \\ 1 \end{bmatrix}$
1	1	1	No	$\begin{bmatrix} 0 \\ 1 \end{bmatrix}$

Now that we found the eigenvalues and associated eigenvectors, we will go over each eigenvalue and generate the solution basis. The only problem we need to take care of is if the eigenvalue is defective. Since eigenvalue 3 is real and distinct then the corresponding eigenvector solution is

$$\begin{aligned} \vec{x}_1(t) &= \vec{v}_1 e^{3t} \\ &= \begin{bmatrix} -\frac{2}{5} \\ 1 \end{bmatrix} e^{3t} \end{aligned}$$

Since eigenvalue 1 is real and distinct then the corresponding eigenvector solution is

$$\begin{aligned} \vec{x}_2(t) &= \vec{v}_2 e^t \\ &= \begin{bmatrix} 0 \\ 1 \end{bmatrix} e^t \end{aligned}$$

Therefore the homogeneous solution is

$$\vec{x}_h(t) = c_1 \vec{x}_1(t) + c_2 \vec{x}_2(t)$$

Which is written as

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = c_1 \begin{bmatrix} -\frac{2e^{3t}}{5} \\ e^{3t} \end{bmatrix} + c_2 \begin{bmatrix} 0 \\ e^t \end{bmatrix}$$

Now that we found homogeneous solution above, we need to find a particular solution $\vec{x}_p(t)$. We will use Variation of parameters. The fundamental matrix is

$$\Phi = \begin{bmatrix} \vec{x}_1 & \vec{x}_2 & \cdots \end{bmatrix}$$

Where \vec{x}_i are the solution basis found above. Therefore the fundamental matrix is

$$\Phi(t) = \begin{bmatrix} -\frac{2e^{3t}}{5} & 0 \\ e^{3t} & e^t \end{bmatrix}$$

The particular solution is then given by

$$\vec{x}_p(t) = \Phi \int \Phi^{-1} \vec{G}(t) dt$$

But

$$\Phi^{-1} = \begin{bmatrix} -\frac{5e^{-3t}}{2} & 0 \\ \frac{5e^{-t}}{2} & e^{-t} \end{bmatrix}$$

Hence

$$\begin{aligned} \vec{x}_p(t) &= \begin{bmatrix} -\frac{2e^{3t}}{5} & 0 \\ e^{3t} & e^t \end{bmatrix} \int \begin{bmatrix} -\frac{5e^{-3t}}{2} & 0 \\ \frac{5e^{-t}}{2} & e^{-t} \end{bmatrix} \begin{bmatrix} 1-t \\ 2t-1 \end{bmatrix} dt \\ &= \begin{bmatrix} -\frac{2e^{3t}}{5} & 0 \\ e^{3t} & e^t \end{bmatrix} \int \begin{bmatrix} \frac{5e^{-3t}(t-1)}{2} \\ -\frac{e^{-t}(-3+t)}{2} \end{bmatrix} dt \\ &= \begin{bmatrix} -\frac{2e^{3t}}{5} & 0 \\ e^{3t} & e^t \end{bmatrix} \begin{bmatrix} -\frac{5e^{-3t}(-2+3t)}{18} \\ \frac{e^{-t}(-2+t)}{2} \end{bmatrix} \\ &= \begin{bmatrix} -\frac{2}{9} + \frac{t}{3} \\ -\frac{4}{9} - \frac{t}{3} \end{bmatrix} \end{aligned}$$

Now that we found particular solution, the final solution is

$$\vec{x}(t) = \vec{x}_h(t) + \vec{x}_p(t)$$

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} -\frac{2c_1 e^{3t}}{5} \\ c_1 e^{3t} \end{bmatrix} + \begin{bmatrix} 0 \\ c_2 e^t \end{bmatrix} + \begin{bmatrix} -\frac{2}{9} + \frac{t}{3} \\ -\frac{4}{9} - \frac{t}{3} \end{bmatrix}$$

Which becomes

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} -\frac{2c_1 e^{3t}}{5} - \frac{2}{9} + \frac{t}{3} \\ c_1 e^{3t} + c_2 e^t - \frac{4}{9} - \frac{t}{3} \end{bmatrix}$$

16.17.3 Maple step by step solution

Let's solve

$$[x'(t) = 3x(t) - t + 1, y'(t) = -5x(t) + y(t) + 2t - 1]$$

- Define vector

$$\vec{x}(t) = \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}$$

- Convert system into a vector equation

$$\vec{x}'(t) = \begin{bmatrix} 3 & 0 \\ -5 & 1 \end{bmatrix} \cdot \vec{x}(t) + \begin{bmatrix} 1 - t \\ 2t - 1 \end{bmatrix}$$

- System to solve

$$\vec{x}'(t) = \begin{bmatrix} 3 & 0 \\ -5 & 1 \end{bmatrix} \cdot \vec{x}(t) + \begin{bmatrix} 1 - t \\ 2t - 1 \end{bmatrix}$$

- Define the forcing function

$$\vec{f}(t) = \begin{bmatrix} 1 - t \\ 2t - 1 \end{bmatrix}$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 3 & 0 \\ -5 & 1 \end{bmatrix}$$

- Rewrite the system as

$$\vec{x}'(t) = A \cdot \vec{x}(t) + \vec{f}$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[1, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right], \left[3, \begin{bmatrix} -\frac{2}{5} \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[1, \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{x}_1 = e^t \cdot \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[3, \begin{bmatrix} -\frac{2}{5} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{x}_2 = e^{3t} \cdot \begin{bmatrix} -\frac{2}{5} \\ 1 \end{bmatrix}$$

- General solution of the system of ODEs can be written in terms of the particular solution $\vec{x}_p(t)$

$$\vec{x}(t) = c_1 \vec{x}_1 + c_2 \vec{x}_2 + \vec{x}_p(t)$$

- Fundamental matrix

- Let $\phi(t)$ be the matrix whose columns are the independent solutions of the homogeneous system

$$\phi(t) = \begin{bmatrix} 0 & -\frac{2e^{3t}}{5} \\ e^t & e^{3t} \end{bmatrix}$$

- The fundamental matrix, $\Phi(t)$ is a normalized version of $\phi(t)$ satisfying $\Phi(0) = I$ where I is the identity matrix

$$\Phi(t) = \phi(t) \cdot \frac{1}{\phi(0)}$$

- Substitute the value of $\phi(t)$ and $\phi(0)$

$$\Phi(t) = \begin{bmatrix} 0 & -\frac{2e^{3t}}{5} \\ e^t & e^{3t} \end{bmatrix} \cdot \frac{1}{\begin{bmatrix} 0 & -\frac{2}{5} \\ 1 & 1 \end{bmatrix}}$$

- Evaluate and simplify to get the fundamental matrix

$$\Phi(t) = \begin{bmatrix} e^{3t} & 0 \\ -\frac{5e^{3t}}{2} + \frac{5e^t}{2} & e^t \end{bmatrix}$$

- Find a particular solution of the system of ODEs using variation of parameters

- Let the particular solution be the fundamental matrix multiplied by $\vec{v}(t)$ and solve for $\vec{v}(t)$

$$\vec{x}_p(t) = \Phi(t) \cdot \vec{v}(t)$$

- Take the derivative of the particular solution

$$\vec{x}'_p(t) = \Phi'(t) \cdot \vec{v}(t) + \Phi(t) \cdot \vec{v}'(t)$$

- Substitute particular solution and its derivative into the system of ODEs

$$\Phi'(t) \cdot \vec{v}(t) + \Phi(t) \cdot \vec{v}'(t) = A \cdot \Phi(t) \cdot \vec{v}(t) + \vec{f}(t)$$

- The fundamental matrix has columns that are solutions to the homogeneous system so its derivative is $A \cdot \Phi(t)$

$$A \cdot \Phi(t) \cdot \vec{v}(t) + \Phi(t) \cdot \vec{v}'(t) = A \cdot \Phi(t) \cdot \vec{v}(t) + \vec{f}(t)$$

- Cancel like terms

$$\Phi(t) \cdot \vec{v}'(t) = \vec{f}(t)$$

- Multiply by the inverse of the fundamental matrix

$$\vec{v}'(t) = \frac{1}{\Phi(t)} \cdot \vec{f}(t)$$

- Integrate to solve for $\vec{v}(t)$

$$\vec{v}(t) = \int_0^t \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds$$

- Plug $\vec{v}(t)$ into the equation for the particular solution

$$\vec{x}_p(t) = \Phi(t) \cdot \left(\int_0^t \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds \right)$$

- Plug in the fundamental matrix and the forcing function and compute

$$\vec{x}_p(t) = \begin{bmatrix} \frac{2e^{3t}}{9} - \frac{2}{9} + \frac{t}{3} \\ -\frac{5e^{3t}}{9} - \frac{4}{9} - \frac{t}{3} + e^t \end{bmatrix}$$

- Plug particular solution back into general solution

$$\vec{x}(t) = c_1 \vec{x}_1 + c_2 \vec{x}_2 + \begin{bmatrix} \frac{2e^{3t}}{9} - \frac{2}{9} + \frac{t}{3} \\ -\frac{5e^{3t}}{9} - \frac{4}{9} - \frac{t}{3} + e^t \end{bmatrix}$$

- Substitute in vector of dependent variables

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} -\frac{2}{9} + \frac{2(5-9c_2)e^{3t}}{45} + \frac{t}{3} \\ c_1 e^t + c_2 e^{3t} - \frac{5e^{3t}}{9} - \frac{4}{9} - \frac{t}{3} + e^t \end{bmatrix}$$

- Solution to the system of ODEs

$$\left\{ x(t) = -\frac{2}{9} + \frac{2(5-9c_2)e^{3t}}{45} + \frac{t}{3}, y(t) = c_1 e^t + c_2 e^{3t} - \frac{5e^{3t}}{9} - \frac{4}{9} - \frac{t}{3} + e^t \right\}$$

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 35

```
dsolve([2*diff(x(t),t)+diff(y(t),t)-x(t)-y(t)=1,diff(x(t),t)+diff(y(t),t)+2*x(t)-y(t)=t],sin
```

$$x(t) = \frac{t}{3} - \frac{2}{9} + c_2 e^{3t}$$

$$y(t) = -\frac{4}{9} - \frac{5c_2 e^{3t}}{2} - \frac{t}{3} + c_1 e^t$$

✓ Solution by Mathematica

Time used: 0.147 (sec). Leaf size: 58

```
DSolve[{2*x'[t]+y'[t]-x[t]-y[t]==1,x'[t]+y'[t]+2*x[t]-y[t]==t},{x[t],y[t]},t,IncludeSingular
```

$$x(t) \rightarrow \frac{t}{3} + c_1 e^{3t} - \frac{2}{9}$$

$$y(t) \rightarrow -\frac{t}{3} - \frac{5}{2} c_1 e^{3t} + \left(\frac{5c_1}{2} + c_2 \right) e^t - \frac{4}{9}$$

17 Chapter 7, Systems of linear differential equations. Section 7.3. Exercises page 299

17.1 problem 1	4524
17.2 problem 2	4532
17.3 problem 3	4540

17.1 problem 1

17.1.1 Solution using Matrix exponential method 4524

17.1.2 Solution using explicit Eigenvalue and Eigenvector method . . . 4525

Internal problem ID [11945]

Internal file name [OUTPUT/11954_Sunday_April_14_2024_02_31_17_AM_22819234/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 7, Systems of linear differential equations. Section 7.3. Exercises page 299

Problem number: 1.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**system of linear ODEs**"

Solve

$$x'(t) = 3x(t) + 4y(t)$$

$$y'(t) = 2x(t) + y(t)$$

With initial conditions

$$[x(0) = 1, y(0) = 2]$$

17.1.1 Solution using Matrix exponential method

In this method, we will assume we have found the matrix exponential e^{At} already. There are different methods to determine this but will not be shown here. This is a system of linear ODE's given as

$$\vec{x}'(t) = A\vec{x}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} 3 & 4 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}$$

For the above matrix A , the matrix exponential can be found to be

$$e^{At} = \begin{bmatrix} \frac{e^{-t}}{3} + \frac{2e^{5t}}{3} & \frac{2e^{5t}}{3} - \frac{2e^{-t}}{3} \\ \frac{e^{5t}}{3} - \frac{e^{-t}}{3} & \frac{2e^{-t}}{3} + \frac{e^{5t}}{3} \end{bmatrix}$$

Therefore the homogeneous solution is

$$\begin{aligned}\vec{x}_h(t) &= e^{At}\vec{x}_0 \\ &= \begin{bmatrix} \frac{e^{-t}}{3} + \frac{2e^{5t}}{3} & \frac{2e^{5t}}{3} - \frac{2e^{-t}}{3} \\ \frac{e^{5t}}{3} - \frac{e^{-t}}{3} & \frac{2e^{-t}}{3} + \frac{e^{5t}}{3} \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix} \\ &= \begin{bmatrix} -e^{-t} + 2e^{5t} \\ e^{5t} + e^{-t} \end{bmatrix}\end{aligned}$$

Since no forcing function is given, then the final solution is $\vec{x}_h(t)$ above.

17.1.2 Solution using explicit Eigenvalue and Eigenvector method

This is a system of linear ODE's given as

$$\vec{x}'(t) = A\vec{x}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} 3 & 4 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}$$

The first step is find the homogeneous solution. We start by finding the eigenvalues of A . This is done by solving the following equation for the eigenvalues λ

$$\det(A - \lambda I) = 0$$

Expanding gives

$$\det\left(\begin{bmatrix} 3 & 4 \\ 2 & 1 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}\right) = 0$$

Therefore

$$\det\left(\begin{bmatrix} 3 - \lambda & 4 \\ 2 & 1 - \lambda \end{bmatrix}\right) = 0$$

Which gives the characteristic equation

$$\lambda^2 - 4\lambda - 5 = 0$$

The roots of the above are the eigenvalues.

$$\lambda_1 = -1$$

$$\lambda_2 = 5$$

This table summarises the above result

eigenvalue	algebraic multiplicity	type of eigenvalue
-1	1	real eigenvalue
5	1	real eigenvalue

Now the eigenvector for each eigenvalue are found.

Considering the eigenvalue $\lambda_1 = -1$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} 3 & 4 \\ 2 & 1 \end{bmatrix} - (-1) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 4 & 4 \\ 2 & 2 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{cc|c} 4 & 4 & 0 \\ 2 & 2 & 0 \end{array} \right]$$

$$R_2 = R_2 - \frac{R_1}{2} \implies \left[\begin{array}{cc|c} 4 & 4 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} 4 & 4 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = -t\}$

Hence the solution is

$$\begin{bmatrix} -t \\ t \end{bmatrix} = \begin{bmatrix} -t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} -t \\ t \end{bmatrix} = t \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} -t \\ t \end{bmatrix} = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

Considering the eigenvalue $\lambda_2 = 5$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} 3 & 4 \\ 2 & 1 \end{bmatrix} - (5) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$
$$\begin{bmatrix} -2 & 4 \\ 2 & -4 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{cc|c} -2 & 4 & 0 \\ 2 & -4 & 0 \end{array} \right]$$

$$R_2 = R_2 + R_1 \implies \left[\begin{array}{cc|c} -2 & 4 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} -2 & 4 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = 2t\}$

Hence the solution is

$$\begin{bmatrix} 2t \\ t \end{bmatrix} = \begin{bmatrix} 2t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} 2t \\ t \end{bmatrix} = t \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} 2t \\ t \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

The following table gives a summary of this result. It shows for each eigenvalue the algebraic multiplicity m , and its geometric multiplicity k and the eigenvectors associated with the eigenvalue. If $m > k$ then the eigenvalue is defective which means the number of normal linearly independent eigenvectors associated with this eigenvalue (called the geometric multiplicity k) does not equal the algebraic multiplicity m , and we need to determine an additional $m - k$ generalized eigenvectors for this eigenvalue.

eigenvalue	multiplicity		defective?	eigenvectors
	algebraic m	geometric k		
-1	1	1	No	$\begin{bmatrix} -1 \\ 1 \end{bmatrix}$
5	1	1	No	$\begin{bmatrix} 2 \\ 1 \end{bmatrix}$

Now that we found the eigenvalues and associated eigenvectors, we will go over each eigenvalue and generate the solution basis. The only problem we need to take care of is if the eigenvalue is defective. Since eigenvalue -1 is real and distinct then the corresponding eigenvector solution is

$$\begin{aligned} \vec{x}_1(t) &= \vec{v}_1 e^{-t} \\ &= \begin{bmatrix} -1 \\ 1 \end{bmatrix} e^{-t} \end{aligned}$$

Since eigenvalue 5 is real and distinct then the corresponding eigenvector solution is

$$\begin{aligned}\vec{x}_2(t) &= \vec{v}_2 e^{5t} \\ &= \begin{bmatrix} 2 \\ 1 \end{bmatrix} e^{5t}\end{aligned}$$

Therefore the final solution is

$$\vec{x}_h(t) = c_1 \vec{x}_1(t) + c_2 \vec{x}_2(t)$$

Which is written as

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = c_1 \begin{bmatrix} -e^{-t} \\ e^{-t} \end{bmatrix} + c_2 \begin{bmatrix} 2e^{5t} \\ e^{5t} \end{bmatrix}$$

Which becomes

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} -c_1 e^{-t} + 2c_2 e^{5t} \\ c_1 e^{-t} + c_2 e^{5t} \end{bmatrix}$$

Since initial conditions are given, the solution above needs to be updated by solving for the constants of integrations using the given initial conditions

$$\begin{bmatrix} x(0) = 1 \\ y(0) = 2 \end{bmatrix} \tag{1}$$

Substituting initial conditions into the above solution at $t = 0$ gives

$$\begin{bmatrix} 1 \\ 2 \end{bmatrix} = \begin{bmatrix} -c_1 + 2c_2 \\ c_1 + c_2 \end{bmatrix}$$

Solving for the constants of integrations gives

$$\begin{bmatrix} c_1 = 1 \\ c_2 = 1 \end{bmatrix}$$

Substituting these constants back in original solution in Eq. (1) gives

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} -e^{-t} + 2e^{5t} \\ e^{5t} + e^{-t} \end{bmatrix}$$

The following is the phase plot of the system.

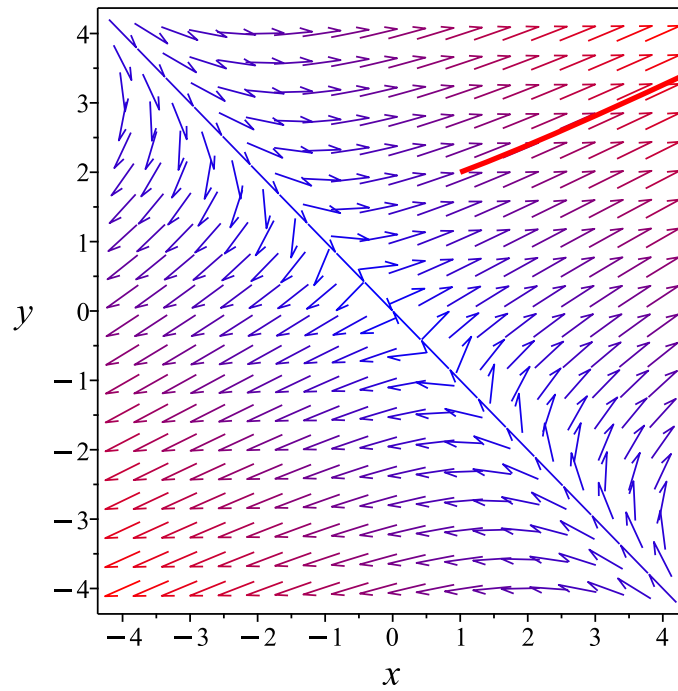
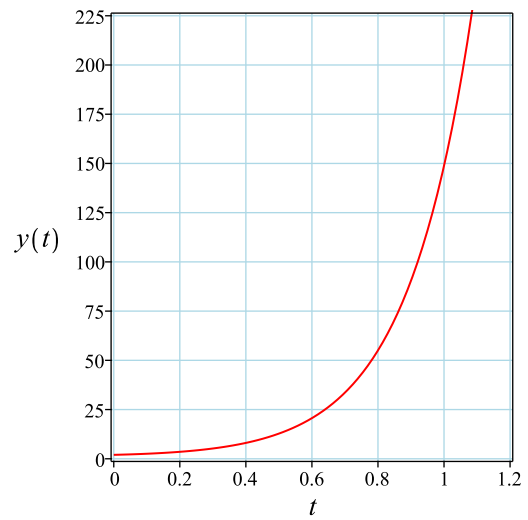
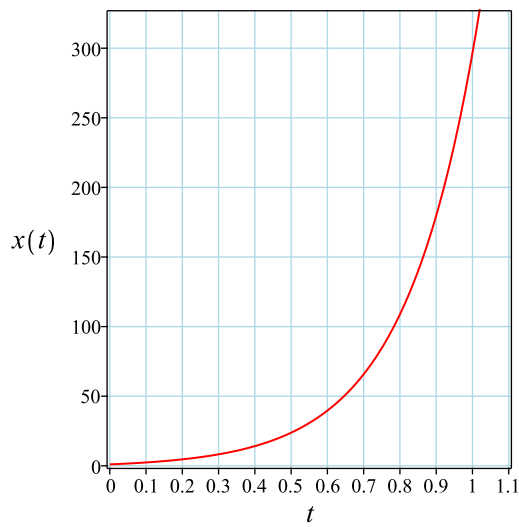


Figure 560: Phase plot

The following are plots of each solution.



✓ Solution by Maple

Time used: 0.032 (sec). Leaf size: 30

```
dsolve([diff(x(t),t) = 3*x(t)+4*y(t), diff(y(t),t) = 2*x(t)+y(t), x(0) = 1, y(0) = 2], sings
```

$$\begin{aligned}x(t) &= 2e^{5t} - e^{-t} \\ y(t) &= e^{5t} + e^{-t}\end{aligned}$$

✓ Solution by Mathematica

Time used: 0.008 (sec). Leaf size: 34

```
DSolve[{x'[t]==3*x[t]+4*y[t],y'[t]==2*x[t]+y[t]},{x[0]==1,y[0]==2},{x[t],y[t]},t,IncludeSing
```

$$\begin{aligned}x(t) &\rightarrow e^{-t}(2e^{6t} - 1) \\ y(t) &\rightarrow e^{-t} + e^{5t}\end{aligned}$$

17.2 problem 2

17.2.1 Solution using Matrix exponential method 4532

17.2.2 Solution using explicit Eigenvalue and Eigenvector method . . . 4533

Internal problem ID [11946]

Internal file name [OUTPUT/11955_Sunday_April_14_2024_02_31_18_AM_92513105/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 7, Systems of linear differential equations. Section 7.3. Exercises page 299

Problem number: 2.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**system of linear ODEs**"

Solve

$$x'(t) = 5x(t) + 3y(t)$$

$$y'(t) = 4x(t) + y(t)$$

With initial conditions

$$[x(0) = 0, y(0) = 8]$$

17.2.1 Solution using Matrix exponential method

In this method, we will assume we have found the matrix exponential e^{At} already. There are different methods to determine this but will not be shown here. This is a system of linear ODE's given as

$$\vec{x}'(t) = A \vec{x}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} 5 & 3 \\ 4 & 1 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}$$

For the above matrix A , the matrix exponential can be found to be

$$e^{At} = \begin{bmatrix} \frac{e^{-t}}{4} + \frac{3e^{7t}}{4} & \frac{3e^{7t}}{8} - \frac{3e^{-t}}{8} \\ \frac{e^{7t}}{2} - \frac{e^{-t}}{2} & \frac{3e^{-t}}{4} + \frac{e^{7t}}{4} \end{bmatrix}$$

Therefore the homogeneous solution is

$$\begin{aligned}\vec{x}_h(t) &= e^{At}\vec{x}_0 \\ &= \begin{bmatrix} \frac{e^{-t}}{4} + \frac{3e^{7t}}{4} & \frac{3e^{7t}}{8} - \frac{3e^{-t}}{8} \\ \frac{e^{7t}}{2} - \frac{e^{-t}}{2} & \frac{3e^{-t}}{4} + \frac{e^{7t}}{4} \end{bmatrix} \begin{bmatrix} 0 \\ 8 \end{bmatrix} \\ &= \begin{bmatrix} 3e^{7t} - 3e^{-t} \\ 6e^{-t} + 2e^{7t} \end{bmatrix}\end{aligned}$$

Since no forcing function is given, then the final solution is $\vec{x}_h(t)$ above.

17.2.2 Solution using explicit Eigenvalue and Eigenvector method

This is a system of linear ODE's given as

$$\vec{x}'(t) = A\vec{x}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} 5 & 3 \\ 4 & 1 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}$$

The first step is find the homogeneous solution. We start by finding the eigenvalues of A . This is done by solving the following equation for the eigenvalues λ

$$\det(A - \lambda I) = 0$$

Expanding gives

$$\det\left(\begin{bmatrix} 5 & 3 \\ 4 & 1 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}\right) = 0$$

Therefore

$$\det\left(\begin{bmatrix} 5 - \lambda & 3 \\ 4 & 1 - \lambda \end{bmatrix}\right) = 0$$

Which gives the characteristic equation

$$\lambda^2 - 6\lambda - 7 = 0$$

The roots of the above are the eigenvalues.

$$\lambda_1 = -1$$

$$\lambda_2 = 7$$

This table summarises the above result

eigenvalue	algebraic multiplicity	type of eigenvalue
-1	1	real eigenvalue
7	1	real eigenvalue

Now the eigenvector for each eigenvalue are found.

Considering the eigenvalue $\lambda_1 = -1$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} 5 & 3 \\ 4 & 1 \end{bmatrix} - (-1) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 6 & 3 \\ 4 & 2 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{cc|c} 6 & 3 & 0 \\ 4 & 2 & 0 \end{array} \right]$$

$$R_2 = R_2 - \frac{2R_1}{3} \implies \left[\begin{array}{cc|c} 6 & 3 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} 6 & 3 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = -\frac{t}{2}\}$

Hence the solution is

$$\begin{bmatrix} -\frac{t}{2} \\ t \end{bmatrix} = \begin{bmatrix} -\frac{t}{2} \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} -\frac{t}{2} \\ t \end{bmatrix} = t \begin{bmatrix} -\frac{1}{2} \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} -\frac{1}{2} \\ 1 \end{bmatrix} = \begin{bmatrix} -\frac{1}{2} \\ 1 \end{bmatrix}$$

Which is normalized to

$$\begin{bmatrix} -\frac{1}{2} \\ 1 \end{bmatrix} = \begin{bmatrix} -1 \\ 2 \end{bmatrix}$$

Considering the eigenvalue $\lambda_2 = 7$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} 5 & 3 \\ 4 & 1 \end{bmatrix} - (7) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -2 & 3 \\ 4 & -6 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{cc|c} -2 & 3 & 0 \\ 4 & -6 & 0 \end{array} \right]$$

$$R_2 = R_2 + 2R_1 \implies \left[\begin{array}{cc|c} -2 & 3 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} -2 & 3 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = \frac{3t}{2}\}$

Hence the solution is

$$\begin{bmatrix} \frac{3t}{2} \\ t \end{bmatrix} = \begin{bmatrix} \frac{3t}{2} \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} \frac{3t}{2} \\ t \end{bmatrix} = t \begin{bmatrix} \frac{3}{2} \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} \frac{3t}{2} \\ t \end{bmatrix} = \begin{bmatrix} \frac{3}{2} \\ 1 \end{bmatrix}$$

Which is normalized to

$$\begin{bmatrix} \frac{3t}{2} \\ t \end{bmatrix} = \begin{bmatrix} 3 \\ 2 \end{bmatrix}$$

The following table gives a summary of this result. It shows for each eigenvalue the algebraic multiplicity m , and its geometric multiplicity k and the eigenvectors associated with the eigenvalue. If $m > k$ then the eigenvalue is defective which means the number of normal linearly independent eigenvectors associated with this eigenvalue (called the geometric multiplicity k) does not equal the algebraic multiplicity m , and we need to determine an additional $m - k$ generalized eigenvectors for this eigenvalue.

eigenvalue	multiplicity		defective?	eigenvectors
	algebraic m	geometric k		
-1	1	1	No	$\begin{bmatrix} -\frac{1}{2} \\ 1 \end{bmatrix}$
7	1	1	No	$\begin{bmatrix} \frac{3}{2} \\ 1 \end{bmatrix}$

Now that we found the eigenvalues and associated eigenvectors, we will go over each eigenvalue and generate the solution basis. The only problem we need to take care of is if the eigenvalue is defective. Since eigenvalue -1 is real and distinct then the corresponding eigenvector solution is

$$\begin{aligned}\vec{x}_1(t) &= \vec{v}_1 e^{-t} \\ &= \begin{bmatrix} -\frac{1}{2} \\ 1 \end{bmatrix} e^{-t}\end{aligned}$$

Since eigenvalue 7 is real and distinct then the corresponding eigenvector solution is

$$\begin{aligned}\vec{x}_2(t) &= \vec{v}_2 e^{7t} \\ &= \begin{bmatrix} \frac{3}{2} \\ 1 \end{bmatrix} e^{7t}\end{aligned}$$

Therefore the final solution is

$$\vec{x}_h(t) = c_1 \vec{x}_1(t) + c_2 \vec{x}_2(t)$$

Which is written as

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = c_1 \begin{bmatrix} -\frac{e^{-t}}{2} \\ e^{-t} \end{bmatrix} + c_2 \begin{bmatrix} \frac{3e^{7t}}{2} \\ e^{7t} \end{bmatrix}$$

Which becomes

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} -\frac{c_1 e^{-t}}{2} + \frac{3c_2 e^{7t}}{2} \\ c_1 e^{-t} + c_2 e^{7t} \end{bmatrix}$$

Since initial conditions are given, the solution above needs to be updated by solving for the constants of integrations using the given initial conditions

$$\begin{bmatrix} x(0) = 0 \\ y(0) = 8 \end{bmatrix} \tag{1}$$

Substituting initial conditions into the above solution at $t = 0$ gives

$$\begin{bmatrix} 0 \\ 8 \end{bmatrix} = \begin{bmatrix} -\frac{c_1}{2} + \frac{3c_2}{2} \\ c_1 + c_2 \end{bmatrix}$$

Solving for the constants of integrations gives

$$\begin{bmatrix} c_1 = 6 \\ c_2 = 2 \end{bmatrix}$$

Substituting these constants back in original solution in Eq. (1) gives

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} 3e^{7t} - 3e^{-t} \\ 6e^{-t} + 2e^{7t} \end{bmatrix}$$

The following is the phase plot of the system.

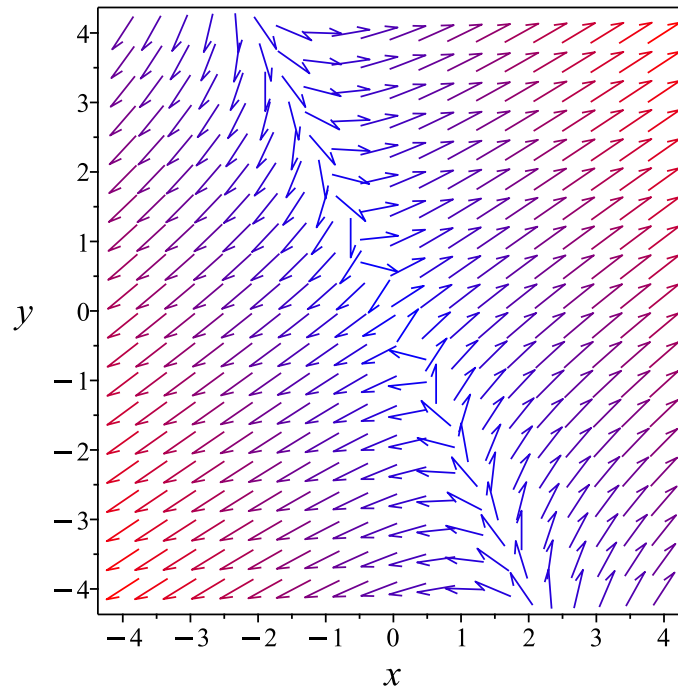
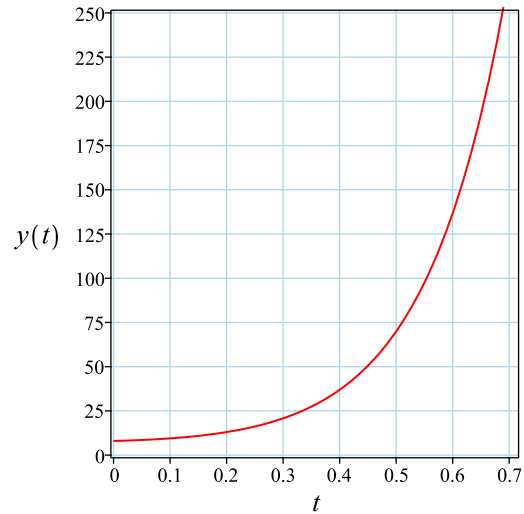
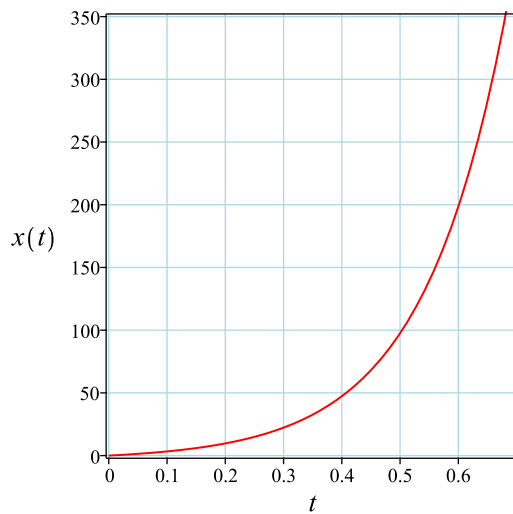


Figure 561: Phase plot

The following are plots of each solution.



✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 34

```
dsolve([diff(x(t),t) = 5*x(t)+3*y(t), diff(y(t),t) = 4*x(t)+y(t), x(0) = 0, y(0) = 8], sings
```

$$\begin{aligned}x(t) &= 3e^{7t} - 3e^{-t} \\y(t) &= 2e^{7t} + 6e^{-t}\end{aligned}$$

✓ Solution by Mathematica

Time used: 0.005 (sec). Leaf size: 36

```
DSolve[{x'[t]==5*x[t]+3*y[t],y'[t]==4*x[t]+y[t]},{x[0]==0,y[0]==8},{x[t],y[t]},t,IncludeSing
```

$$\begin{aligned}x(t) &\rightarrow 3e^{-t}(e^{8t} - 1) \\y(t) &\rightarrow 2e^{-t}(e^{8t} + 3)\end{aligned}$$

17.3 problem 3

17.3.1 Solution using Matrix exponential method	4540
17.3.2 Solution using explicit Eigenvalue and Eigenvector method . . .	4542
17.3.3 Maple step by step solution	4547

Internal problem ID [11947]

Internal file name [OUTPUT/11956_Sunday_April_14_2024_02_31_19_AM_54968245/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 7, Systems of linear differential equations. Section 7.3. Exercises page 299

Problem number: 3.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "system of linear ODEs"

Solve

$$\begin{aligned}x'(t) &= 5x(t) + 2y(t) + 5t \\y'(t) &= 3x(t) + 4y(t) + 17t\end{aligned}$$

17.3.1 Solution using Matrix exponential method

In this method, we will assume we have found the matrix exponential e^{At} already. There are different methods to determine this but will not be shown here. This is a system of linear ODE's given as

$$\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} 5 & 2 \\ 3 & 4 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} + \begin{bmatrix} 5t \\ 17t \end{bmatrix}$$

Since the system is nonhomogeneous, then the solution is given by

$$\vec{x}(t) = \vec{x}_h(t) + \vec{x}_p(t)$$

Where $\vec{x}_h(t)$ is the homogeneous solution to $\vec{x}'(t) = A\vec{x}(t)$ and $\vec{x}_p(t)$ is a particular solution to $\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$. The particular solution will be found using variation

of parameters method applied to the fundamental matrix. For the above matrix A , the matrix exponential can be found to be

$$e^{At} = \begin{bmatrix} \frac{2e^{2t}}{5} + \frac{3e^{7t}}{5} & \frac{2e^{7t}}{5} - \frac{2e^{2t}}{5} \\ \frac{3e^{7t}}{5} - \frac{3e^{2t}}{5} & \frac{3e^{2t}}{5} + \frac{2e^{7t}}{5} \end{bmatrix}$$

Therefore the homogeneous solution is

$$\begin{aligned} \vec{x}_h(t) &= e^{At} \vec{c} \\ &= \begin{bmatrix} \frac{2e^{2t}}{5} + \frac{3e^{7t}}{5} & \frac{2e^{7t}}{5} - \frac{2e^{2t}}{5} \\ \frac{3e^{7t}}{5} - \frac{3e^{2t}}{5} & \frac{3e^{2t}}{5} + \frac{2e^{7t}}{5} \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} \\ &= \begin{bmatrix} \left(\frac{2e^{2t}}{5} + \frac{3e^{7t}}{5}\right) c_1 + \left(\frac{2e^{7t}}{5} - \frac{2e^{2t}}{5}\right) c_2 \\ \left(\frac{3e^{7t}}{5} - \frac{3e^{2t}}{5}\right) c_1 + \left(\frac{3e^{2t}}{5} + \frac{2e^{7t}}{5}\right) c_2 \end{bmatrix} \\ &= \begin{bmatrix} \frac{(2c_1 - 2c_2)e^{2t}}{5} + \frac{3e^{7t}(c_1 + \frac{2c_2}{3})}{5} \\ \frac{(-3c_1 + 3c_2)e^{2t}}{5} + \frac{3e^{7t}(c_1 + \frac{2c_2}{3})}{5} \end{bmatrix} \end{aligned}$$

The particular solution given by

$$\vec{x}_p(t) = e^{At} \int e^{-At} \vec{G}(t) dt$$

But

$$\begin{aligned} e^{-At} &= (e^{At})^{-1} \\ &= \begin{bmatrix} \frac{e^{-7t}(2e^{5t}+3)}{5} & -\frac{2e^{-7t}(e^{5t}-1)}{5} \\ -\frac{3e^{-7t}(e^{5t}-1)}{5} & \frac{e^{-7t}(3e^{5t}+2)}{5} \end{bmatrix} \end{aligned}$$

Hence

$$\begin{aligned} \vec{x}_p(t) &= \begin{bmatrix} \frac{2e^{2t}}{5} + \frac{3e^{7t}}{5} & \frac{2e^{7t}}{5} - \frac{2e^{2t}}{5} \\ \frac{3e^{7t}}{5} - \frac{3e^{2t}}{5} & \frac{3e^{2t}}{5} + \frac{2e^{7t}}{5} \end{bmatrix} \int \begin{bmatrix} \frac{e^{-7t}(2e^{5t}+3)}{5} & -\frac{2e^{-7t}(e^{5t}-1)}{5} \\ -\frac{3e^{-7t}(e^{5t}-1)}{5} & \frac{e^{-7t}(3e^{5t}+2)}{5} \end{bmatrix} \begin{bmatrix} 5t \\ 17t \end{bmatrix} dt \\ &= \begin{bmatrix} \frac{2e^{2t}}{5} + \frac{3e^{7t}}{5} & \frac{2e^{7t}}{5} - \frac{2e^{2t}}{5} \\ \frac{3e^{7t}}{5} - \frac{3e^{2t}}{5} & \frac{3e^{2t}}{5} + \frac{2e^{7t}}{5} \end{bmatrix} \begin{bmatrix} \frac{(-7t-1)e^{-7t}}{5} + \frac{6(2t+1)e^{-2t}}{5} \\ \frac{(-7t-1)e^{-7t}}{5} + \frac{9(-2t-1)e^{-2t}}{5} \end{bmatrix} \\ &= \begin{bmatrix} 1+t \\ -5t-2 \end{bmatrix} \end{aligned}$$

Hence the complete solution is

$$\begin{aligned}\vec{x}(t) &= \vec{x}_h(t) + \vec{x}_p(t) \\ &= \begin{bmatrix} \frac{(2c_1 - 2c_2)e^{2t}}{5} + \frac{e^{7t}(3c_1 + 2c_2)}{5} + t + 1 \\ \frac{(-3c_1 + 3c_2)e^{2t}}{5} + \frac{e^{7t}(3c_1 + 2c_2)}{5} - 5t - 2 \end{bmatrix}\end{aligned}$$

17.3.2 Solution using explicit Eigenvalue and Eigenvector method

This is a system of linear ODE's given as

$$\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} 5 & 2 \\ 3 & 4 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} + \begin{bmatrix} 5t \\ 17t \end{bmatrix}$$

Since the system is nonhomogeneous, then the solution is given by

$$\vec{x}(t) = \vec{x}_h(t) + \vec{x}_p(t)$$

Where $\vec{x}_h(t)$ is the homogeneous solution to $\vec{x}'(t) = A\vec{x}(t)$ and $\vec{x}_p(t)$ is a particular solution to $\vec{x}'(t) = A\vec{x}(t) + \vec{G}(t)$. The particular solution will be found using variation of parameters method applied to the fundamental matrix.

The first step is find the homogeneous solution. We start by finding the eigenvalues of A . This is done by solving the following equation for the eigenvalues λ

$$\det(A - \lambda I) = 0$$

Expanding gives

$$\det\left(\begin{bmatrix} 5 & 2 \\ 3 & 4 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}\right) = 0$$

Therefore

$$\det\left(\begin{bmatrix} 5 - \lambda & 2 \\ 3 & 4 - \lambda \end{bmatrix}\right) = 0$$

Which gives the characteristic equation

$$\lambda^2 - 9\lambda + 14 = 0$$

The roots of the above are the eigenvalues.

$$\lambda_1 = 2$$

$$\lambda_2 = 7$$

This table summarises the above result

eigenvalue	algebraic multiplicity	type of eigenvalue
2	1	real eigenvalue
7	1	real eigenvalue

Now the eigenvector for each eigenvalue are found.

Considering the eigenvalue $\lambda_1 = 2$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} 5 & 2 \\ 3 & 4 \end{bmatrix} - (2) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 3 & 2 \\ 3 & 2 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{cc|c} 3 & 2 & 0 \\ 3 & 2 & 0 \end{array} \right]$$

$$R_2 = R_2 - R_1 \implies \left[\begin{array}{cc|c} 3 & 2 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} 3 & 2 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = -\frac{2t}{3}\}$

Hence the solution is

$$\begin{bmatrix} -\frac{2t}{3} \\ t \end{bmatrix} = \begin{bmatrix} -\frac{2t}{3} \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} -\frac{2t}{3} \\ t \end{bmatrix} = t \begin{bmatrix} -\frac{2}{3} \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} -\frac{2}{3} \\ 1 \end{bmatrix} = \begin{bmatrix} -\frac{2}{3} \\ 1 \end{bmatrix}$$

Which is normalized to

$$\begin{bmatrix} -\frac{2}{3} \\ 1 \end{bmatrix} = \begin{bmatrix} -2 \\ 3 \end{bmatrix}$$

Considering the eigenvalue $\lambda_2 = 7$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} 5 & 2 \\ 3 & 4 \end{bmatrix} - (7) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -2 & 2 \\ 3 & -3 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{cc|c} -2 & 2 & 0 \\ 3 & -3 & 0 \end{array} \right]$$

$$R_2 = R_2 + \frac{3R_1}{2} \implies \left[\begin{array}{cc|c} -2 & 2 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} -2 & 2 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = t\}$

Hence the solution is

$$\begin{bmatrix} t \\ t \end{bmatrix} = \begin{bmatrix} t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} t \\ t \end{bmatrix} = t \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} t \\ t \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

The following table gives a summary of this result. It shows for each eigenvalue the algebraic multiplicity m , and its geometric multiplicity k and the eigenvectors associated with the eigenvalue. If $m > k$ then the eigenvalue is defective which means the number of normal linearly independent eigenvectors associated with this eigenvalue (called the geometric multiplicity k) does not equal the algebraic multiplicity m , and we need to determine an additional $m - k$ generalized eigenvectors for this eigenvalue.

eigenvalue	multiplicity		defective?	eigenvectors
	algebraic m	geometric k		
2	1	1	No	$\begin{bmatrix} -\frac{2}{3} \\ 1 \end{bmatrix}$
7	1	1	No	$\begin{bmatrix} 1 \\ 1 \end{bmatrix}$

Now that we found the eigenvalues and associated eigenvectors, we will go over each eigenvalue and generate the solution basis. The only problem we need to take care of is if the eigenvalue is defective. Since eigenvalue 2 is real and distinct then the

corresponding eigenvector solution is

$$\begin{aligned}\vec{x}_1(t) &= \vec{v}_1 e^{2t} \\ &= \begin{bmatrix} -\frac{2}{3} \\ 1 \end{bmatrix} e^{2t}\end{aligned}$$

Since eigenvalue 7 is real and distinct then the corresponding eigenvector solution is

$$\begin{aligned}\vec{x}_2(t) &= \vec{v}_2 e^{7t} \\ &= \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{7t}\end{aligned}$$

Therefore the homogeneous solution is

$$\vec{x}_h(t) = c_1 \vec{x}_1(t) + c_2 \vec{x}_2(t)$$

Which is written as

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = c_1 \begin{bmatrix} -\frac{2e^{2t}}{3} \\ e^{2t} \end{bmatrix} + c_2 \begin{bmatrix} e^{7t} \\ e^{7t} \end{bmatrix}$$

Now that we found homogeneous solution above, we need to find a particular solution $\vec{x}_p(t)$. We will use Variation of parameters. The fundamental matrix is

$$\Phi = \begin{bmatrix} \vec{x}_1 & \vec{x}_2 & \cdots \end{bmatrix}$$

Where \vec{x}_i are the solution basis found above. Therefore the fundamental matrix is

$$\Phi(t) = \begin{bmatrix} -\frac{2e^{2t}}{3} & e^{7t} \\ e^{2t} & e^{7t} \end{bmatrix}$$

The particular solution is then given by

$$\vec{x}_p(t) = \Phi \int \Phi^{-1} \vec{G}(t) dt$$

But

$$\Phi^{-1} = \begin{bmatrix} -\frac{3e^{-2t}}{5} & \frac{3e^{-2t}}{5} \\ \frac{3e^{-7t}}{5} & \frac{2e^{-7t}}{5} \end{bmatrix}$$

Hence

$$\begin{aligned}
 \vec{x}_p(t) &= \begin{bmatrix} -\frac{2e^{2t}}{3} & e^{7t} \\ e^{2t} & e^{7t} \end{bmatrix} \int \begin{bmatrix} -\frac{3e^{-2t}}{5} & \frac{3e^{-2t}}{5} \\ \frac{3e^{-7t}}{5} & \frac{2e^{-7t}}{5} \end{bmatrix} \begin{bmatrix} 5t \\ 17t \end{bmatrix} dt \\
 &= \begin{bmatrix} -\frac{2e^{2t}}{3} & e^{7t} \\ e^{2t} & e^{7t} \end{bmatrix} \int \begin{bmatrix} \frac{36te^{-2t}}{5} \\ \frac{49e^{-7t}t}{5} \end{bmatrix} dt \\
 &= \begin{bmatrix} -\frac{2e^{2t}}{3} & e^{7t} \\ e^{2t} & e^{7t} \end{bmatrix} \begin{bmatrix} -\frac{9(2t+1)e^{-2t}}{5} \\ -\frac{(7t+1)e^{-7t}}{5} \end{bmatrix} \\
 &= \begin{bmatrix} 1+t \\ -5t-2 \end{bmatrix}
 \end{aligned}$$

Now that we found particular solution, the final solution is

$$\begin{aligned}
 \vec{x}(t) &= \vec{x}_h(t) + \vec{x}_p(t) \\
 \begin{bmatrix} x(t) \\ y(t) \end{bmatrix} &= \begin{bmatrix} -\frac{2c_1e^{2t}}{3} \\ c_1e^{2t} \end{bmatrix} + \begin{bmatrix} c_2e^{7t} \\ c_2e^{7t} \end{bmatrix} + \begin{bmatrix} 1+t \\ -5t-2 \end{bmatrix}
 \end{aligned}$$

Which becomes

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} -\frac{2c_1e^{2t}}{3} + c_2e^{7t} + 1+t \\ c_1e^{2t} + c_2e^{7t} - 5t - 2 \end{bmatrix}$$

17.3.3 Maple step by step solution

Let's solve

$$[x'(t) = 5x(t) + 2y(t) + 5t, y'(t) = 3x(t) + 4y(t) + 17t]$$

- Define vector

$$\vec{x}(t) = \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}$$

- Convert system into a vector equation

$$\vec{x}'(t) = \begin{bmatrix} 5 & 2 \\ 3 & 4 \end{bmatrix} \cdot \vec{x}(t) + \begin{bmatrix} 5t \\ 17t \end{bmatrix}$$

- System to solve

$$\vec{x}'(t) = \begin{bmatrix} 5 & 2 \\ 3 & 4 \end{bmatrix} \cdot \vec{x}(t) + \begin{bmatrix} 5t \\ 17t \end{bmatrix}$$

- Define the forcing function

$$\vec{f}(t) = \begin{bmatrix} 5t \\ 17t \end{bmatrix}$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 5 & 2 \\ 3 & 4 \end{bmatrix}$$

- Rewrite the system as

$$\vec{x}'(t) = A \cdot \vec{x}(t) + \vec{f}$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[2, \begin{bmatrix} -\frac{2}{3} \\ 1 \end{bmatrix} \right], \left[7, \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[2, \begin{bmatrix} -\frac{2}{3} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{x}_1 = e^{2t} \cdot \begin{bmatrix} -\frac{2}{3} \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[7, \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{x}_2 = e^{7t} \cdot \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

- General solution of the system of ODEs can be written in terms of the particular solution $\vec{x}_p(t)$

$$\vec{x}(t) = c_1 \vec{x}_1 + c_2 \vec{x}_2 + \vec{x}_p(t)$$

□ Fundamental matrix

- Let $\phi(t)$ be the matrix whose columns are the independent solutions of the homogeneous system

$$\phi(t) = \begin{bmatrix} -\frac{2e^{2t}}{3} & e^{7t} \\ e^{2t} & e^{7t} \end{bmatrix}$$

- The fundamental matrix, $\Phi(t)$ is a normalized version of $\phi(t)$ satisfying $\Phi(0) = I$ where I is the identity matrix

$$\Phi(t) = \phi(t) \cdot \frac{1}{\phi(0)}$$

- Substitute the value of $\phi(t)$ and $\phi(0)$

$$\Phi(t) = \begin{bmatrix} -\frac{2e^{2t}}{3} & e^{7t} \\ e^{2t} & e^{7t} \end{bmatrix} \cdot \frac{1}{\begin{bmatrix} -\frac{2}{3} & 1 \\ 1 & 1 \end{bmatrix}}$$

- Evaluate and simplify to get the fundamental matrix

$$\Phi(t) = \begin{bmatrix} \frac{2e^{2t}}{5} + \frac{3e^{7t}}{5} & \frac{2e^{7t}}{5} - \frac{2e^{2t}}{5} \\ \frac{3e^{7t}}{5} - \frac{3e^{2t}}{5} & \frac{3e^{2t}}{5} + \frac{2e^{7t}}{5} \end{bmatrix}$$

□ Find a particular solution of the system of ODEs using variation of parameters

- Let the particular solution be the fundamental matrix multiplied by $\vec{v}(t)$ and solve for $\vec{v}(t)$

$$\vec{x}_p(t) = \Phi(t) \cdot \vec{v}(t)$$

- Take the derivative of the particular solution

$$\vec{x}'_p(t) = \Phi'(t) \cdot \vec{v}(t) + \Phi(t) \cdot \vec{v}'(t)$$

- Substitute particular solution and its derivative into the system of ODEs

$$\Phi'(t) \cdot \vec{v}(t) + \Phi(t) \cdot \vec{v}'(t) = A \cdot \Phi(t) \cdot \vec{v}(t) + \vec{f}(t)$$

- The fundamental matrix has columns that are solutions to the homogeneous system so its derivative is $A \cdot \Phi(t)$

$$A \cdot \Phi(t) \cdot \vec{v}(t) + \Phi(t) \cdot \vec{v}'(t) = A \cdot \Phi(t) \cdot \vec{v}(t) + \vec{f}(t)$$

- Cancel like terms

$$\Phi(t) \cdot \vec{v}'(t) = \vec{f}(t)$$

- Multiply by the inverse of the fundamental matrix

$$\vec{v}'(t) = \frac{1}{\Phi(t)} \cdot \vec{f}(t)$$

- Integrate to solve for $\vec{v}(t)$

$$\vec{v}(t) = \int_0^t \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds$$

- Plug $\vec{v}(t)$ into the equation for the particular solution

$$\vec{x}_p(t) = \Phi(t) \cdot \left(\int_0^t \frac{1}{\Phi(s)} \cdot \vec{f}(s) ds \right)$$

- Plug in the fundamental matrix and the forcing function and compute

$$\vec{x}_p(t) = \begin{bmatrix} t + 1 - \frac{6e^{2t}}{5} + \frac{e^{7t}}{5} \\ \frac{e^{7t}}{5} - 5t - 2 + \frac{9e^{2t}}{5} \end{bmatrix}$$

- Plug particular solution back into general solution

$$\vec{x}(t) = c_1 \vec{x}_1 + c_2 \vec{x}_2 + \begin{bmatrix} t + 1 - \frac{6e^{2t}}{5} + \frac{e^{7t}}{5} \\ \frac{e^{7t}}{5} - 5t - 2 + \frac{9e^{2t}}{5} \end{bmatrix}$$

- Substitute in vector of dependent variables

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} \frac{(-10c_1-18)e^{2t}}{15} + \frac{(15c_2+3)e^{7t}}{15} + t + 1 \\ \frac{(9+5c_1)e^{2t}}{5} + \frac{(1+5c_2)e^{7t}}{5} - 5t - 2 \end{bmatrix}$$

- Solution to the system of ODEs

$$\left\{ x(t) = \frac{(-10c_1-18)e^{2t}}{15} + \frac{(15c_2+3)e^{7t}}{15} + t + 1, y(t) = \frac{(9+5c_1)e^{2t}}{5} + \frac{(1+5c_2)e^{7t}}{5} - 5t - 2 \right\}$$

✓ Solution by Maple

Time used: 0.031 (sec). Leaf size: 41

```
dsolve([diff(x(t),t)=5*x(t)+2*y(t)+5*t,diff(y(t),t)=3*x(t)+4*y(t)+17*t],singsol=all)
```

$$x(t) = c_2 e^{7t} + c_1 e^{2t} + t + 1$$

$$y(t) = c_2 e^{7t} - \frac{3c_1 e^{2t}}{2} - 2 - 5t$$

✓ Solution by Mathematica

Time used: 0.086 (sec). Leaf size: 84

```
DSolve[{x'[t]==5*x[t]+2*y[t]+5*t,y'[t]==3*x[t]+4*y[t]+17*t},{x[t],y[t]},t,IncludeSingularSol
```

$$x(t) \rightarrow t + \frac{1}{5}(2(c_1 - c_2)e^{2t} + (3c_1 + 2c_2)e^{7t} + 5)$$

$$y(t) \rightarrow -5t - \frac{3}{5}(c_1 - c_2)e^{2t} + \frac{1}{5}(3c_1 + 2c_2)e^{7t} - 2$$

18 Chapter 7, Systems of linear differential equations. Section 7.4. Exercises page 309

18.1 problem 1	4553
18.2 problem 2	4562
18.3 problem 23	4571
18.4 problem 24	4579

18.1 problem 1

- 18.1.1 Solution using Matrix exponential method 4553
- 18.1.2 Solution using explicit Eigenvalue and Eigenvector method . . . 4554
- 18.1.3 Maple step by step solution 4559

Internal problem ID [11948]

Internal file name [OUTPUT/11957_Sunday_April_14_2024_02_31_20_AM_21165008/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 7, Systems of linear differential equations. Section 7.4. Exercises page 309

Problem number: 1.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**system of linear ODEs**"

Solve

$$\begin{aligned}x'(t) &= 5x(t) - 2y(t) \\y'(t) &= 4x(t) - y(t)\end{aligned}$$

18.1.1 Solution using Matrix exponential method

In this method, we will assume we have found the matrix exponential e^{At} already. There are different methods to determine this but will not be shown here. This is a system of linear ODE's given as

$$\vec{x}'(t) = A \vec{x}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} 5 & -2 \\ 4 & -1 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}$$

For the above matrix A , the matrix exponential can be found to be

$$e^{At} = \begin{bmatrix} -e^t + 2e^{3t} & -e^{3t} + e^t \\ 2e^{3t} - 2e^t & 2e^t - e^{3t} \end{bmatrix}$$

Therefore the homogeneous solution is

$$\begin{aligned}
 \vec{x}_h(t) &= e^{At} \vec{c} \\
 &= \begin{bmatrix} -e^t + 2e^{3t} & -e^{3t} + e^t \\ 2e^{3t} - 2e^t & 2e^t - e^{3t} \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} \\
 &= \begin{bmatrix} (-e^t + 2e^{3t})c_1 + (-e^{3t} + e^t)c_2 \\ (2e^{3t} - 2e^t)c_1 + (2e^t - e^{3t})c_2 \end{bmatrix} \\
 &= \begin{bmatrix} (2c_1 - c_2)e^{3t} - (c_1 - c_2)e^t \\ (2c_1 - c_2)e^{3t} - 2(c_1 - c_2)e^t \end{bmatrix}
 \end{aligned}$$

Since no forcing function is given, then the final solution is $\vec{x}_h(t)$ above.

18.1.2 Solution using explicit Eigenvalue and Eigenvector method

This is a system of linear ODE's given as

$$\vec{x}'(t) = A\vec{x}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} 5 & -2 \\ 4 & -1 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}$$

The first step is find the homogeneous solution. We start by finding the eigenvalues of A . This is done by solving the following equation for the eigenvalues λ

$$\det(A - \lambda I) = 0$$

Expanding gives

$$\det \left(\begin{bmatrix} 5 & -2 \\ 4 & -1 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) = 0$$

Therefore

$$\det \left(\begin{bmatrix} 5 - \lambda & -2 \\ 4 & -1 - \lambda \end{bmatrix} \right) = 0$$

Which gives the characteristic equation

$$\lambda^2 - 4\lambda + 3 = 0$$

The roots of the above are the eigenvalues.

$$\lambda_1 = 1$$

$$\lambda_2 = 3$$

This table summarises the above result

eigenvalue	algebraic multiplicity	type of eigenvalue
1	1	real eigenvalue
3	1	real eigenvalue

Now the eigenvector for each eigenvalue are found.

Considering the eigenvalue $\lambda_1 = 1$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} 5 & -2 \\ 4 & -1 \end{bmatrix} - (1) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$
$$\begin{bmatrix} 4 & -2 \\ 4 & -2 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{cc|c} 4 & -2 & 0 \\ 4 & -2 & 0 \end{array} \right]$$

$$R_2 = R_2 - R_1 \implies \left[\begin{array}{cc|c} 4 & -2 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} 4 & -2 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = \frac{t}{2}\}$

Hence the solution is

$$\begin{bmatrix} \frac{t}{2} \\ t \end{bmatrix} = \begin{bmatrix} \frac{t}{2} \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} \frac{t}{2} \\ t \end{bmatrix} = t \begin{bmatrix} \frac{1}{2} \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} \frac{1}{2} \\ 1 \end{bmatrix} = \begin{bmatrix} \frac{1}{2} \\ 1 \end{bmatrix}$$

Which is normalized to

$$\begin{bmatrix} \frac{1}{\sqrt{5}} \\ \frac{2}{\sqrt{5}} \end{bmatrix} = \begin{bmatrix} \frac{1}{\sqrt{5}} \\ \frac{2}{\sqrt{5}} \end{bmatrix}$$

Considering the eigenvalue $\lambda_2 = 3$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} 5 & -2 \\ 4 & -1 \end{bmatrix} - (3) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 2 & -2 \\ 4 & -4 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{cc|c} 2 & -2 & 0 \\ 4 & -4 & 0 \end{array} \right]$$

$$R_2 = R_2 - 2R_1 \implies \left[\begin{array}{cc|c} 2 & -2 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} 2 & -2 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = t\}$

Hence the solution is

$$\begin{bmatrix} t \\ t \end{bmatrix} = \begin{bmatrix} t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} t \\ t \end{bmatrix} = t \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} t \\ t \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

The following table gives a summary of this result. It shows for each eigenvalue the algebraic multiplicity m , and its geometric multiplicity k and the eigenvectors associated with the eigenvalue. If $m > k$ then the eigenvalue is defective which means the number of normal linearly independent eigenvectors associated with this eigenvalue (called the geometric multiplicity k) does not equal the algebraic multiplicity m , and we need to determine an additional $m - k$ generalized eigenvectors for this eigenvalue.

eigenvalue	multiplicity		defective?	eigenvectors
	algebraic m	geometric k		
1	1	1	No	$\begin{bmatrix} \frac{1}{2} \\ 1 \end{bmatrix}$
3	1	1	No	$\begin{bmatrix} 1 \\ 1 \end{bmatrix}$

Now that we found the eigenvalues and associated eigenvectors, we will go over each eigenvalue and generate the solution basis. The only problem we need to take care of is if the eigenvalue is defective. Since eigenvalue 1 is real and distinct then the corresponding eigenvector solution is

$$\begin{aligned}\vec{x}_1(t) &= \vec{v}_1 e^t \\ &= \begin{bmatrix} \frac{1}{2} \\ 1 \end{bmatrix} e^t\end{aligned}$$

Since eigenvalue 3 is real and distinct then the corresponding eigenvector solution is

$$\begin{aligned}\vec{x}_2(t) &= \vec{v}_2 e^{3t} \\ &= \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{3t}\end{aligned}$$

Therefore the final solution is

$$\vec{x}_h(t) = c_1 \vec{x}_1(t) + c_2 \vec{x}_2(t)$$

Which is written as

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = c_1 \begin{bmatrix} \frac{e^t}{2} \\ e^t \end{bmatrix} + c_2 \begin{bmatrix} e^{3t} \\ e^{3t} \end{bmatrix}$$

Which becomes

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} \frac{c_1 e^t}{2} + c_2 e^{3t} \\ c_1 e^t + c_2 e^{3t} \end{bmatrix}$$

The following is the phase plot of the system.

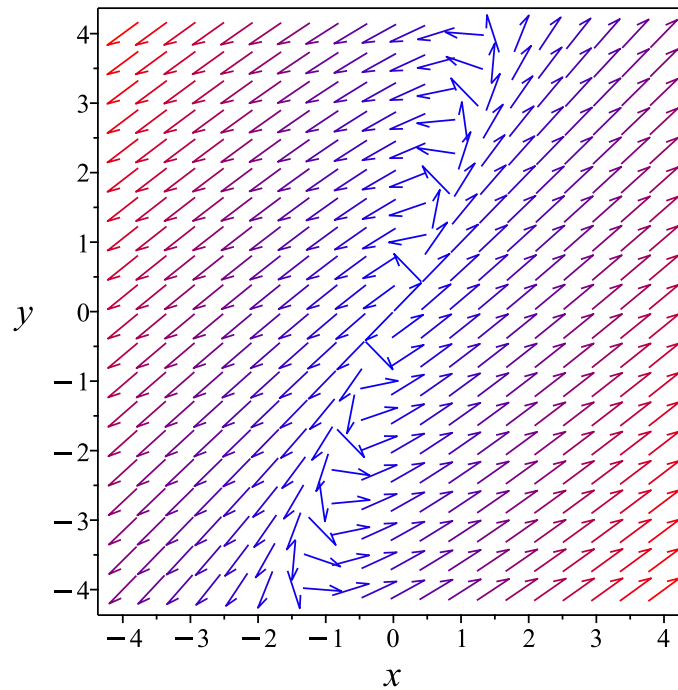


Figure 562: Phase plot

18.1.3 Maple step by step solution

Let's solve

$$[x'(t) = 5x(t) - 2y(t), y'(t) = 4x(t) - y(t)]$$

- Define vector

$$\vec{x}(t) = \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}$$

- Convert system into a vector equation

$$\vec{x}'(t) = \begin{bmatrix} 5 & -2 \\ 4 & -1 \end{bmatrix} \cdot \vec{x}(t) + \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

- System to solve

$$\vec{x}'(t) = \begin{bmatrix} 5 & -2 \\ 4 & -1 \end{bmatrix} \cdot \vec{x}(t)$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 5 & -2 \\ 4 & -1 \end{bmatrix}$$

- Rewrite the system as

$$\vec{x}'(t) = A \cdot \vec{x}(t)$$

- To solve the system, find the eigenvalues and eigenvectors of A
- Eigenpairs of A

$$\left[\left[1, \begin{bmatrix} \frac{1}{2} \\ 1 \end{bmatrix} \right], \left[3, \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[1, \begin{bmatrix} \frac{1}{2} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{x}_1 = e^t \cdot \begin{bmatrix} \frac{1}{2} \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[3, \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{x}_2 = e^{3t} \cdot \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

- General solution to the system of ODEs

$$\vec{x} = c_1 \vec{x}_1 + c_2 \vec{x}_2$$

- Substitute solutions into the general solution

$$\vec{x} = c_1 e^t \cdot \begin{bmatrix} \frac{1}{2} \\ 1 \end{bmatrix} + c_2 e^{3t} \cdot \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

- Substitute in vector of dependent variables

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} \frac{c_1 e^t}{2} + c_2 e^{3t} \\ c_1 e^t + c_2 e^{3t} \end{bmatrix}$$

- Solution to the system of ODEs

$$\left\{ x(t) = \frac{c_1 e^t}{2} + c_2 e^{3t}, y(t) = c_1 e^t + c_2 e^{3t} \right\}$$

✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 31

```
dsolve([diff(x(t),t)=5*x(t)-2*y(t),diff(y(t),t)=4*x(t)-y(t)],singsol=all)
```

$$\begin{aligned} x(t) &= c_1 e^t + c_2 e^{3t} \\ y(t) &= 2c_1 e^t + c_2 e^{3t} \end{aligned}$$

✓ Solution by Mathematica

Time used: 0.003 (sec). Leaf size: 63

```
DSolve[{x'[t]==5*x[t]-2*y[t],y'[t]==4*x[t]-y[t]},{x[t],y[t]},t,IncludeSingularSolutions -> T
```

$$\begin{aligned} x(t) &\rightarrow e^t (c_1 (2e^{2t} - 1) - c_2 (e^{2t} - 1)) \\ y(t) &\rightarrow e^t (2c_1 (e^{2t} - 1) - c_2 (e^{2t} - 2)) \end{aligned}$$

18.2 problem 2

- 18.2.1 Solution using Matrix exponential method 4562
- 18.2.2 Solution using explicit Eigenvalue and Eigenvector method . . . 4563
- 18.2.3 Maple step by step solution 4568

Internal problem ID [11949]

Internal file name [OUTPUT/11958_Sunday_April_14_2024_02_31_20_AM_33601750/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 7, Systems of linear differential equations. Section 7.4. Exercises page 309

Problem number: 2.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**system of linear ODEs**"

Solve

$$x'(t) = 5x(t) - y(t)$$

$$y'(t) = 3x(t) + y(t)$$

18.2.1 Solution using Matrix exponential method

In this method, we will assume we have found the matrix exponential e^{At} already. There are different methods to determine this but will not be shown here. This is a system of linear ODE's given as

$$\vec{x}'(t) = A \vec{x}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} 5 & -1 \\ 3 & 1 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}$$

For the above matrix A , the matrix exponential can be found to be

$$e^{At} = \begin{bmatrix} -\frac{e^{2t}}{2} + \frac{3e^{4t}}{2} & -\frac{e^{4t}}{2} + \frac{e^{2t}}{2} \\ \frac{3e^{4t}}{2} - \frac{3e^{2t}}{2} & \frac{3e^{2t}}{2} - \frac{e^{4t}}{2} \end{bmatrix}$$

Therefore the homogeneous solution is

$$\begin{aligned}
 \vec{x}_h(t) &= e^{At} \vec{c} \\
 &= \begin{bmatrix} -\frac{e^{2t}}{2} + \frac{3e^{4t}}{2} & -\frac{e^{4t}}{2} + \frac{e^{2t}}{2} \\ \frac{3e^{4t}}{2} - \frac{3e^{2t}}{2} & \frac{3e^{2t}}{2} - \frac{e^{4t}}{2} \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \end{bmatrix} \\
 &= \begin{bmatrix} \left(-\frac{e^{2t}}{2} + \frac{3e^{4t}}{2}\right) c_1 + \left(-\frac{e^{4t}}{2} + \frac{e^{2t}}{2}\right) c_2 \\ \left(\frac{3e^{4t}}{2} - \frac{3e^{2t}}{2}\right) c_1 + \left(\frac{3e^{2t}}{2} - \frac{e^{4t}}{2}\right) c_2 \end{bmatrix} \\
 &= \begin{bmatrix} \frac{(c_2 - c_1)e^{2t}}{2} + \frac{3e^{4t}(-\frac{c_2}{3} + c_1)}{2} \\ \frac{(-3c_1 + 3c_2)e^{2t}}{2} + \frac{3e^{4t}(-\frac{c_2}{3} + c_1)}{2} \end{bmatrix}
 \end{aligned}$$

Since no forcing function is given, then the final solution is $\vec{x}_h(t)$ above.

18.2.2 Solution using explicit Eigenvalue and Eigenvector method

This is a system of linear ODE's given as

$$\vec{x}'(t) = A \vec{x}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} 5 & -1 \\ 3 & 1 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}$$

The first step is find the homogeneous solution. We start by finding the eigenvalues of A . This is done by solving the following equation for the eigenvalues λ

$$\det(A - \lambda I) = 0$$

Expanding gives

$$\det \left(\begin{bmatrix} 5 & -1 \\ 3 & 1 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) = 0$$

Therefore

$$\det \left(\begin{bmatrix} 5 - \lambda & -1 \\ 3 & 1 - \lambda \end{bmatrix} \right) = 0$$

Which gives the characteristic equation

$$\lambda^2 - 6\lambda + 8 = 0$$

The roots of the above are the eigenvalues.

$$\lambda_1 = 2$$

$$\lambda_2 = 4$$

This table summarises the above result

eigenvalue	algebraic multiplicity	type of eigenvalue
2	1	real eigenvalue
4	1	real eigenvalue

Now the eigenvector for each eigenvalue are found.

Considering the eigenvalue $\lambda_1 = 2$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} 5 & -1 \\ 3 & 1 \end{bmatrix} - (2) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$
$$\begin{bmatrix} 3 & -1 \\ 3 & -1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{cc|c} 3 & -1 & 0 \\ 3 & -1 & 0 \end{array} \right]$$

$$R_2 = R_2 - R_1 \implies \left[\begin{array}{cc|c} 3 & -1 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} 3 & -1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = \frac{t}{3}\}$

Hence the solution is

$$\begin{bmatrix} \frac{t}{3} \\ t \end{bmatrix} = \begin{bmatrix} \frac{t}{3} \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} \frac{t}{3} \\ t \end{bmatrix} = t \begin{bmatrix} \frac{1}{3} \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} \frac{1}{3} \\ 1 \end{bmatrix} = \begin{bmatrix} \frac{1}{3} \\ 1 \end{bmatrix}$$

Which is normalized to

$$\begin{bmatrix} \frac{1}{3} \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$$

Considering the eigenvalue $\lambda_2 = 4$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} 5 & -1 \\ 3 & 1 \end{bmatrix} - (4) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -1 \\ 3 & -3 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{cc|c} 1 & -1 & 0 \\ 3 & -3 & 0 \end{array} \right]$$

$$R_2 = R_2 - 3R_1 \implies \left[\begin{array}{cc|c} 1 & -1 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} 1 & -1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = t\}$

Hence the solution is

$$\begin{bmatrix} t \\ t \end{bmatrix} = \begin{bmatrix} t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} t \\ t \end{bmatrix} = t \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} t \\ t \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

The following table gives a summary of this result. It shows for each eigenvalue the algebraic multiplicity m , and its geometric multiplicity k and the eigenvectors associated with the eigenvalue. If $m > k$ then the eigenvalue is defective which means the number of normal linearly independent eigenvectors associated with this eigenvalue (called the geometric multiplicity k) does not equal the algebraic multiplicity m , and we need to determine an additional $m - k$ generalized eigenvectors for this eigenvalue.

eigenvalue	multiplicity		defective?	eigenvectors
	algebraic m	geometric k		
2	1	1	No	$\begin{bmatrix} \frac{1}{3} \\ 1 \end{bmatrix}$
4	1	1	No	$\begin{bmatrix} 1 \\ 1 \end{bmatrix}$

Now that we found the eigenvalues and associated eigenvectors, we will go over each eigenvalue and generate the solution basis. The only problem we need to take care of is if the eigenvalue is defective. Since eigenvalue 2 is real and distinct then the corresponding eigenvector solution is

$$\begin{aligned}\vec{x}_1(t) &= \vec{v}_1 e^{2t} \\ &= \begin{bmatrix} \frac{1}{3} \\ 1 \end{bmatrix} e^{2t}\end{aligned}$$

Since eigenvalue 4 is real and distinct then the corresponding eigenvector solution is

$$\begin{aligned}\vec{x}_2(t) &= \vec{v}_2 e^{4t} \\ &= \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{4t}\end{aligned}$$

Therefore the final solution is

$$\vec{x}_h(t) = c_1 \vec{x}_1(t) + c_2 \vec{x}_2(t)$$

Which is written as

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = c_1 \begin{bmatrix} \frac{e^{2t}}{3} \\ e^{2t} \end{bmatrix} + c_2 \begin{bmatrix} e^{4t} \\ e^{4t} \end{bmatrix}$$

Which becomes

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} \frac{c_1 e^{2t}}{3} + c_2 e^{4t} \\ c_1 e^{2t} + c_2 e^{4t} \end{bmatrix}$$

The following is the phase plot of the system.

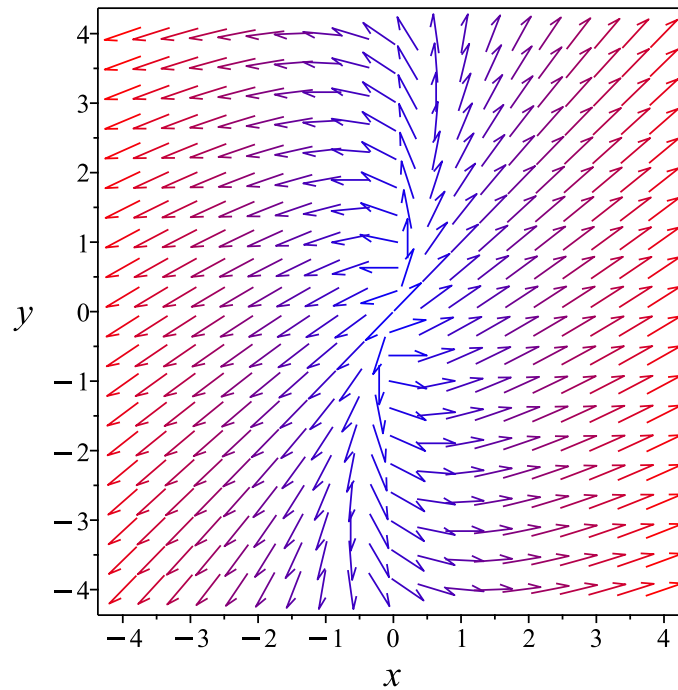


Figure 563: Phase plot

18.2.3 Maple step by step solution

Let's solve

$$[x'(t) = 5x(t) - y(t), y'(t) = 3x(t) + y(t)]$$

- Define vector

$$\vec{x}(t) = \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}$$

- Convert system into a vector equation

$$\vec{x}'(t) = \begin{bmatrix} 5 & -1 \\ 3 & 1 \end{bmatrix} \cdot \vec{x}(t) + \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

- System to solve

$$\vec{x}'(t) = \begin{bmatrix} 5 & -1 \\ 3 & 1 \end{bmatrix} \cdot \vec{x}(t)$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 5 & -1 \\ 3 & 1 \end{bmatrix}$$

- Rewrite the system as

$$\vec{x}'(t) = A \cdot \vec{x}(t)$$

- To solve the system, find the eigenvalues and eigenvectors of A
- Eigenpairs of A

$$\left[\left[2, \begin{bmatrix} \frac{1}{3} \\ 1 \end{bmatrix} \right], \left[4, \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[2, \begin{bmatrix} \frac{1}{3} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{x}_1 = e^{2t} \cdot \begin{bmatrix} \frac{1}{3} \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[4, \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{x}_2 = e^{4t} \cdot \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

- General solution to the system of ODEs

$$\vec{x} = c_1 \vec{x}_1 + c_2 \vec{x}_2$$

- Substitute solutions into the general solution

$$\vec{x} = c_1 e^{2t} \cdot \begin{bmatrix} \frac{1}{3} \\ 1 \end{bmatrix} + c_2 e^{4t} \cdot \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

- Substitute in vector of dependent variables

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} \frac{c_1 e^{2t}}{3} + c_2 e^{4t} \\ c_1 e^{2t} + c_2 e^{4t} \end{bmatrix}$$

- Solution to the system of ODEs

$$\left\{ x(t) = \frac{c_1 e^{2t}}{3} + c_2 e^{4t}, y(t) = c_1 e^{2t} + c_2 e^{4t} \right\}$$

✓ Solution by Maple

Time used: 0.016 (sec). Leaf size: 35

```
dsolve([diff(x(t),t)=5*x(t)-y(t),diff(y(t),t)=3*x(t)+y(t)],singsol=all)
```

$$\begin{aligned} x(t) &= c_1 e^{4t} + c_2 e^{2t} \\ y(t) &= c_1 e^{4t} + 3c_2 e^{2t} \end{aligned}$$

✓ Solution by Mathematica

Time used: 0.003 (sec). Leaf size: 73

```
DSolve[{x'[t]==5*x[t]-y[t],y'[t]==3*x[t]+y[t]},{x[t],y[t]},t,IncludeSingularSolutions -> True]
```

$$\begin{aligned} x(t) &\rightarrow \frac{1}{2} e^{2t} (c_1 (3e^{2t} - 1) - c_2 (e^{2t} - 1)) \\ y(t) &\rightarrow \frac{1}{2} e^{2t} (3c_1 (e^{2t} - 1) - c_2 (e^{2t} - 3)) \end{aligned}$$

18.3 problem 23

18.3.1 Solution using Matrix exponential method 4571

18.3.2 Solution using explicit Eigenvalue and Eigenvector method . . . 4572

Internal problem ID [11950]

Internal file name [OUTPUT/11959_Sunday_April_14_2024_02_31_21_AM_78993495/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 7, Systems of linear differential equations. Section 7.4. Exercises page 309

Problem number: 23.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "**system of linear ODEs**"

Solve

$$x'(t) = -2x(t) + 7y(t)$$

$$y'(t) = 3x(t) + 2y(t)$$

With initial conditions

$$[x(0) = 9, y(0) = -1]$$

18.3.1 Solution using Matrix exponential method

In this method, we will assume we have found the matrix exponential e^{At} already. There are different methods to determine this but will not be shown here. This is a system of linear ODE's given as

$$\vec{x}'(t) = A \vec{x}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} -2 & 7 \\ 3 & 2 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}$$

For the above matrix A , the matrix exponential can be found to be

$$e^{At} = \begin{bmatrix} \frac{7e^{-5t}}{10} + \frac{3e^{5t}}{10} & \frac{7e^{5t}}{10} - \frac{7e^{-5t}}{10} \\ \frac{3e^{5t}}{10} - \frac{3e^{-5t}}{10} & \frac{3e^{-5t}}{10} + \frac{7e^{5t}}{10} \end{bmatrix}$$

Therefore the homogeneous solution is

$$\begin{aligned}\vec{x}_h(t) &= e^{At}\vec{x}_0 \\ &= \begin{bmatrix} \frac{7e^{-5t}}{10} + \frac{3e^{5t}}{10} & \frac{7e^{5t}}{10} - \frac{7e^{-5t}}{10} \\ \frac{3e^{5t}}{10} - \frac{3e^{-5t}}{10} & \frac{3e^{-5t}}{10} + \frac{7e^{5t}}{10} \end{bmatrix} \begin{bmatrix} 9 \\ -1 \end{bmatrix} \\ &= \begin{bmatrix} 7e^{-5t} + 2e^{5t} \\ 2e^{5t} - 3e^{-5t} \end{bmatrix}\end{aligned}$$

Since no forcing function is given, then the final solution is $\vec{x}_h(t)$ above.

18.3.2 Solution using explicit Eigenvalue and Eigenvector method

This is a system of linear ODE's given as

$$\vec{x}'(t) = A\vec{x}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} -2 & 7 \\ 3 & 2 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}$$

The first step is find the homogeneous solution. We start by finding the eigenvalues of A . This is done by solving the following equation for the eigenvalues λ

$$\det(A - \lambda I) = 0$$

Expanding gives

$$\det\left(\begin{bmatrix} -2 & 7 \\ 3 & 2 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}\right) = 0$$

Therefore

$$\det\left(\begin{bmatrix} -2 - \lambda & 7 \\ 3 & 2 - \lambda \end{bmatrix}\right) = 0$$

Which gives the characteristic equation

$$\lambda^2 - 25 = 0$$

The roots of the above are the eigenvalues.

$$\lambda_1 = 5$$

$$\lambda_2 = -5$$

This table summarises the above result

eigenvalue	algebraic multiplicity	type of eigenvalue
-5	1	real eigenvalue
5	1	real eigenvalue

Now the eigenvector for each eigenvalue are found.

Considering the eigenvalue $\lambda_1 = -5$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} -2 & 7 \\ 3 & 2 \end{bmatrix} - (-5) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 3 & 7 \\ 3 & 7 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{cc|c} 3 & 7 & 0 \\ 3 & 7 & 0 \end{array} \right]$$

$$R_2 = R_2 - R_1 \implies \left[\begin{array}{cc|c} 3 & 7 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} 3 & 7 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = -\frac{7t}{3}\}$

Hence the solution is

$$\begin{bmatrix} -\frac{7t}{3} \\ t \end{bmatrix} = \begin{bmatrix} -\frac{7t}{3} \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} -\frac{7t}{3} \\ t \end{bmatrix} = t \begin{bmatrix} -\frac{7}{3} \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} -\frac{7}{3} \\ 1 \end{bmatrix} = \begin{bmatrix} -\frac{7}{3} \\ 1 \end{bmatrix}$$

Which is normalized to

$$\begin{bmatrix} -\frac{7}{3} \\ 1 \end{bmatrix} = \begin{bmatrix} -7 \\ 3 \end{bmatrix}$$

Considering the eigenvalue $\lambda_2 = 5$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} -2 & 7 \\ 3 & 2 \end{bmatrix} - (5) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -7 & 7 \\ 3 & -3 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{cc|c} -7 & 7 & 0 \\ 3 & -3 & 0 \end{array} \right]$$

$$R_2 = R_2 + \frac{3R_1}{7} \implies \left[\begin{array}{cc|c} -7 & 7 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} -7 & 7 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = t\}$

Hence the solution is

$$\begin{bmatrix} t \\ t \end{bmatrix} = \begin{bmatrix} t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} t \\ t \end{bmatrix} = t \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} t \\ t \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

The following table gives a summary of this result. It shows for each eigenvalue the algebraic multiplicity m , and its geometric multiplicity k and the eigenvectors associated with the eigenvalue. If $m > k$ then the eigenvalue is defective which means the number of normal linearly independent eigenvectors associated with this eigenvalue (called the geometric multiplicity k) does not equal the algebraic multiplicity m , and we need to determine an additional $m - k$ generalized eigenvectors for this eigenvalue.

eigenvalue	multiplicity		defective?	eigenvectors
	algebraic m	geometric k		
5	1	1	No	$\begin{bmatrix} 1 \\ 1 \end{bmatrix}$
-5	1	1	No	$\begin{bmatrix} -\frac{7}{3} \\ 1 \end{bmatrix}$

Now that we found the eigenvalues and associated eigenvectors, we will go over each eigenvalue and generate the solution basis. The only problem we need to take care of is if the eigenvalue is defective. Since eigenvalue 5 is real and distinct then the

corresponding eigenvector solution is

$$\begin{aligned}\vec{x}_1(t) &= \vec{v}_1 e^{5t} \\ &= \begin{bmatrix} 1 \\ 1 \end{bmatrix} e^{5t}\end{aligned}$$

Since eigenvalue -5 is real and distinct then the corresponding eigenvector solution is

$$\begin{aligned}\vec{x}_2(t) &= \vec{v}_2 e^{-5t} \\ &= \begin{bmatrix} -\frac{7}{3} \\ 1 \end{bmatrix} e^{-5t}\end{aligned}$$

Therefore the final solution is

$$\vec{x}_h(t) = c_1 \vec{x}_1(t) + c_2 \vec{x}_2(t)$$

Which is written as

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = c_1 \begin{bmatrix} e^{5t} \\ e^{5t} \end{bmatrix} + c_2 \begin{bmatrix} -\frac{7e^{-5t}}{3} \\ e^{-5t} \end{bmatrix}$$

Which becomes

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} c_1 e^{5t} - \frac{7c_2 e^{-5t}}{3} \\ c_1 e^{5t} + c_2 e^{-5t} \end{bmatrix}$$

Since initial conditions are given, the solution above needs to be updated by solving for the constants of integrations using the given initial conditions

$$\begin{bmatrix} x(0) = 9 \\ y(0) = -1 \end{bmatrix} \tag{1}$$

Substituting initial conditions into the above solution at $t = 0$ gives

$$\begin{bmatrix} 9 \\ -1 \end{bmatrix} = \begin{bmatrix} c_1 - \frac{7c_2}{3} \\ c_1 + c_2 \end{bmatrix}$$

Solving for the constants of integrations gives

$$\begin{bmatrix} c_1 = 2 \\ c_2 = -3 \end{bmatrix}$$

Substituting these constants back in original solution in Eq. (1) gives

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} 7e^{-5t} + 2e^{5t} \\ 2e^{5t} - 3e^{-5t} \end{bmatrix}$$

The following is the phase plot of the system.

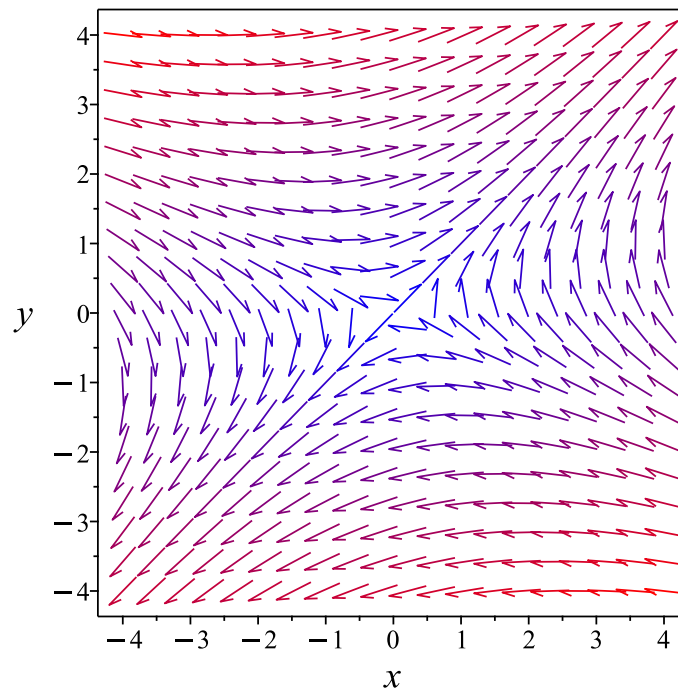
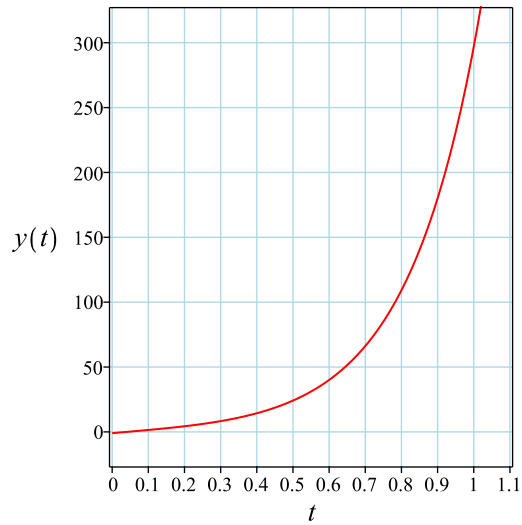
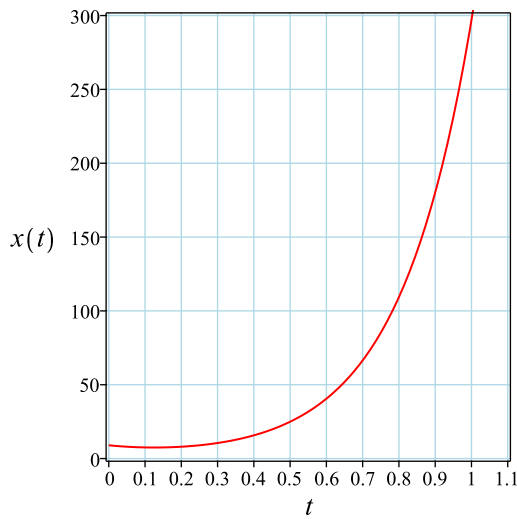


Figure 564: Phase plot

The following are plots of each solution.



✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 34

```
dsolve([diff(x(t),t) = -2*x(t)+7*y(t), diff(y(t),t) = 3*x(t)+2*y(t), x(0) = 9, y(0) = -1], s
```

$$\begin{aligned}x(t) &= 2e^{5t} + 7e^{-5t} \\y(t) &= 2e^{5t} - 3e^{-5t}\end{aligned}$$

✓ Solution by Mathematica

Time used: 0.004 (sec). Leaf size: 38

```
DSolve[{x'[t]==-2*x[t]+7*y[t],y'[t]==3*x[t]+2*y[t]},{x[0]==9,y[0]==-1},{x[t],y[t]},t,Include
```

$$\begin{aligned}x(t) &\rightarrow 7e^{-5t} + 2e^{5t} \\y(t) &\rightarrow 2e^{5t} - 3e^{-5t}\end{aligned}$$

18.4 problem 24

18.4.1 Solution using Matrix exponential method 4579

18.4.2 Solution using explicit Eigenvalue and Eigenvector method . . . 4580

Internal problem ID [11951]

Internal file name [OUTPUT/11960_Sunday_April_14_2024_02_31_22_AM_81973480/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 7, Systems of linear differential equations. Section 7.4. Exercises page 309

Problem number: 24.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"system of linear ODEs"**

Solve

$$x'(t) = -2x(t) + y(t)$$

$$y'(t) = 7x(t) + 4y(t)$$

With initial conditions

$$[x(0) = 6, y(0) = 2]$$

18.4.1 Solution using Matrix exponential method

In this method, we will assume we have found the matrix exponential e^{At} already. There are different methods to determine this but will not be shown here. This is a system of linear ODE's given as

$$\vec{x}'(t) = A \vec{x}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} -2 & 1 \\ 7 & 4 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}$$

For the above matrix A , the matrix exponential can be found to be

$$e^{At} = \begin{bmatrix} \frac{(e^{8t}+7)e^{-3t}}{8} & \frac{(e^{8t}-1)e^{-3t}}{8} \\ \frac{7(e^{8t}-1)e^{-3t}}{8} & \frac{(7e^{8t}+1)e^{-3t}}{8} \end{bmatrix}$$

Therefore the homogeneous solution is

$$\begin{aligned}
 \vec{x}_h(t) &= e^{At} \vec{x}_0 \\
 &= \begin{bmatrix} \frac{(e^{8t}+7)e^{-3t}}{8} & \frac{(e^{8t}-1)e^{-3t}}{8} \\ \frac{7(e^{8t}-1)e^{-3t}}{8} & \frac{(7e^{8t}+1)e^{-3t}}{8} \end{bmatrix} \begin{bmatrix} 6 \\ 2 \end{bmatrix} \\
 &= \begin{bmatrix} \frac{3(e^{8t}+7)e^{-3t}}{4} + \frac{(e^{8t}-1)e^{-3t}}{4} \\ \frac{21(e^{8t}-1)e^{-3t}}{4} + \frac{(7e^{8t}+1)e^{-3t}}{4} \end{bmatrix} \\
 &= \begin{bmatrix} (e^{8t} + 5)e^{-3t} \\ (7e^{8t} - 5)e^{-3t} \end{bmatrix}
 \end{aligned}$$

Since no forcing function is given, then the final solution is $\vec{x}_h(t)$ above.

18.4.2 Solution using explicit Eigenvalue and Eigenvector method

This is a system of linear ODE's given as

$$\vec{x}'(t) = A \vec{x}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \end{bmatrix} = \begin{bmatrix} -2 & 1 \\ 7 & 4 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \end{bmatrix}$$

The first step is find the homogeneous solution. We start by finding the eigenvalues of A . This is done by solving the following equation for the eigenvalues λ

$$\det(A - \lambda I) = 0$$

Expanding gives

$$\det \left(\begin{bmatrix} -2 & 1 \\ 7 & 4 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) = 0$$

Therefore

$$\det \left(\begin{bmatrix} -2 - \lambda & 1 \\ 7 & 4 - \lambda \end{bmatrix} \right) = 0$$

Which gives the characteristic equation

$$\lambda^2 - 2\lambda - 15 = 0$$

The roots of the above are the eigenvalues.

$$\lambda_1 = 5$$

$$\lambda_2 = -3$$

This table summarises the above result

eigenvalue	algebraic multiplicity	type of eigenvalue
-3	1	real eigenvalue
5	1	real eigenvalue

Now the eigenvector for each eigenvalue are found.

Considering the eigenvalue $\lambda_1 = -3$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} -2 & 1 \\ 7 & 4 \end{bmatrix} - (-3) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 \\ 7 & 7 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{cc|c} 1 & 1 & 0 \\ 7 & 7 & 0 \end{array} \right]$$

$$R_2 = R_2 - 7R_1 \implies \left[\begin{array}{cc|c} 1 & 1 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = -t\}$

Hence the solution is

$$\begin{bmatrix} -t \\ t \end{bmatrix} = \begin{bmatrix} -t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} -t \\ t \end{bmatrix} = t \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} -t \\ t \end{bmatrix} = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

Considering the eigenvalue $\lambda_2 = 5$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} -2 & 1 \\ 7 & 4 \end{bmatrix} - (5) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -7 & 1 \\ 7 & -1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{cc|c} -7 & 1 & 0 \\ 7 & -1 & 0 \end{array} \right]$$

$$R_2 = R_2 + R_1 \implies \left[\begin{array}{cc|c} -7 & 1 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} -7 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = \frac{t}{7}\}$

Hence the solution is

$$\begin{bmatrix} \frac{t}{7} \\ t \end{bmatrix} = \begin{bmatrix} \frac{t}{7} \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} \frac{t}{7} \\ t \end{bmatrix} = t \begin{bmatrix} \frac{1}{7} \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} \frac{1}{7} \\ 1 \end{bmatrix} = \begin{bmatrix} \frac{1}{7} \\ 1 \end{bmatrix}$$

Which is normalized to

$$\begin{bmatrix} \frac{1}{7} \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 7 \end{bmatrix}$$

The following table gives a summary of this result. It shows for each eigenvalue the algebraic multiplicity m , and its geometric multiplicity k and the eigenvectors associated with the eigenvalue. If $m > k$ then the eigenvalue is defective which means the number of normal linearly independent eigenvectors associated with this eigenvalue (called the geometric multiplicity k) does not equal the algebraic multiplicity m , and we need to determine an additional $m - k$ generalized eigenvectors for this eigenvalue.

eigenvalue	multiplicity		defective?	eigenvectors
	algebraic m	geometric k		
5	1	1	No	$\begin{bmatrix} \frac{1}{7} \\ 1 \end{bmatrix}$
-3	1	1	No	$\begin{bmatrix} -1 \\ 1 \end{bmatrix}$

Now that we found the eigenvalues and associated eigenvectors, we will go over each eigenvalue and generate the solution basis. The only problem we need to take care of is if the eigenvalue is defective. Since eigenvalue 5 is real and distinct then the corresponding eigenvector solution is

$$\begin{aligned}\vec{x}_1(t) &= \vec{v}_1 e^{5t} \\ &= \begin{bmatrix} \frac{1}{7} \\ 1 \end{bmatrix} e^{5t}\end{aligned}$$

Since eigenvalue -3 is real and distinct then the corresponding eigenvector solution is

$$\begin{aligned}\vec{x}_2(t) &= \vec{v}_2 e^{-3t} \\ &= \begin{bmatrix} -1 \\ 1 \end{bmatrix} e^{-3t}\end{aligned}$$

Therefore the final solution is

$$\vec{x}_h(t) = c_1 \vec{x}_1(t) + c_2 \vec{x}_2(t)$$

Which is written as

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = c_1 \begin{bmatrix} \frac{e^{5t}}{7} \\ e^{5t} \end{bmatrix} + c_2 \begin{bmatrix} -e^{-3t} \\ e^{-3t} \end{bmatrix}$$

Which becomes

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} \frac{(c_1 e^{8t} - 7c_2) e^{-3t}}{7} \\ (c_1 e^{8t} + c_2) e^{-3t} \end{bmatrix}$$

Since initial conditions are given, the solution above needs to be updated by solving for the constants of integrations using the given initial conditions

$$\begin{bmatrix} x(0) = 6 \\ y(0) = 2 \end{bmatrix} \tag{1}$$

Substituting initial conditions into the above solution at $t = 0$ gives

$$\begin{bmatrix} 6 \\ 2 \end{bmatrix} = \begin{bmatrix} \frac{c_1}{7} - c_2 \\ c_1 + c_2 \end{bmatrix}$$

Solving for the constants of integrations gives

$$\begin{bmatrix} c_1 = 7 \\ c_2 = -5 \end{bmatrix}$$

Substituting these constants back in original solution in Eq. (1) gives

$$\begin{bmatrix} x(t) \\ y(t) \end{bmatrix} = \begin{bmatrix} \frac{(7e^{8t}+35)e^{-3t}}{7} \\ (7e^{8t}-5)e^{-3t} \end{bmatrix}$$

The following is the phase plot of the system.

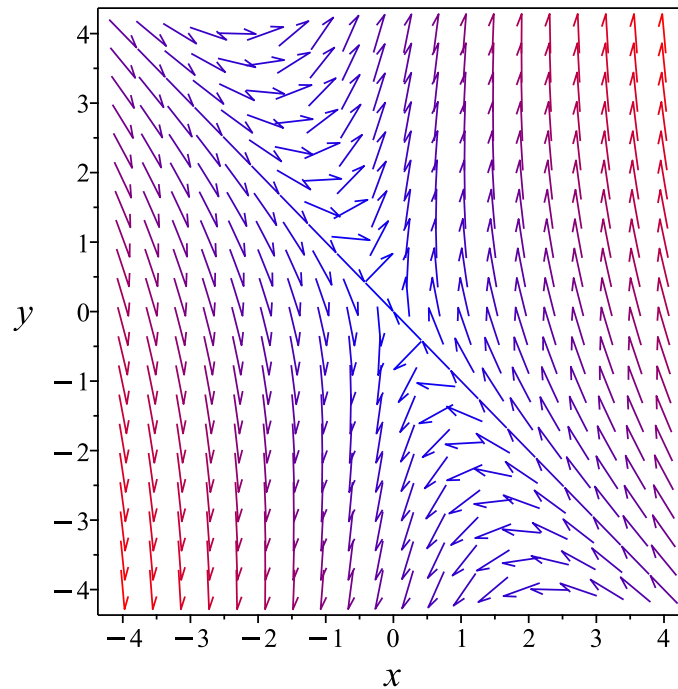
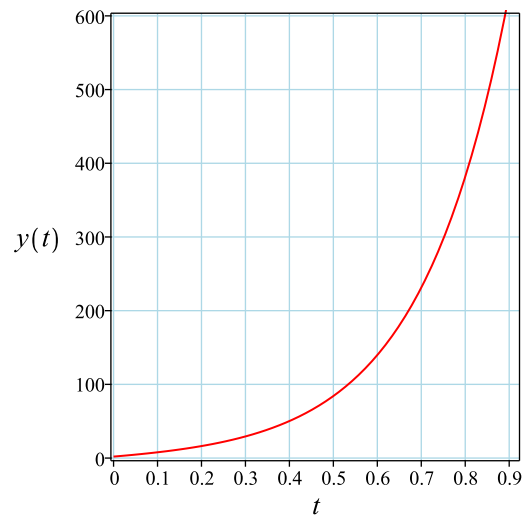
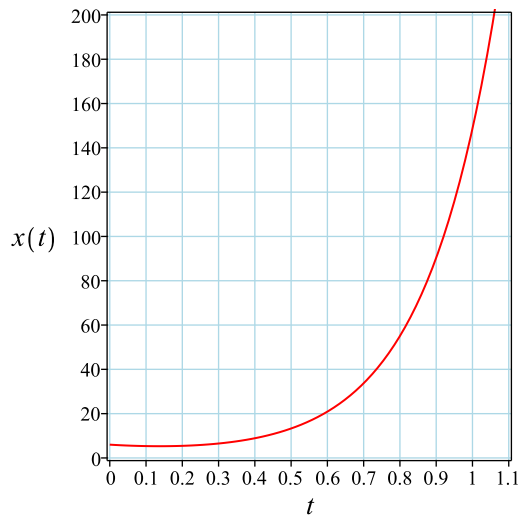


Figure 565: Phase plot

The following are plots of each solution.



✓ Solution by Maple

Time used: 0.015 (sec). Leaf size: 32

```
dsolve([diff(x(t),t) = -2*x(t)+y(t), diff(y(t),t) = 7*x(t)+4*y(t), x(0) = 6, y(0) = 2], sing
```

$$\begin{aligned}x(t) &= e^{5t} + 5e^{-3t} \\y(t) &= 7e^{5t} - 5e^{-3t}\end{aligned}$$

✓ Solution by Mathematica

Time used: 0.004 (sec). Leaf size: 36

```
DSolve[{x'[t]==-2*x[t]+y[t],y'[t]==7*x[t]+4*y[t]},{x[0]==6,y[0]==2},{x[t],y[t]},t,IncludeSin
```

$$\begin{aligned}x(t) &\rightarrow e^{-3t}(e^{8t} + 5) \\y(t) &\rightarrow e^{-3t}(7e^{8t} - 5)\end{aligned}$$

19 Chapter 7, Systems of linear differential equations. Section 7.5. Matrices and vectors.

Exercises page 345

19.1 problem 1	4588
19.2 problem 2	4593
19.3 problem 3	4598
19.4 problem 4	4603
19.5 problem 5	4608
19.6 problem 6	4613
19.7 problem 7	4618
19.8 problem 8	4626
19.9 problem 9	4634
19.10problem 10	4642
19.11problem 11	4650
19.12problem 12	4657
19.13problem 13	4665
19.14problem 14	4673

19.1 problem 1

Internal problem ID [11952]

Internal file name [OUTPUT/11961_Sunday_April_14_2024_02_31_23_AM_64925071/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 7, Systems of linear differential equations. Section 7.5. Matrices and vectors. Exercises page 345

Problem number: 1.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"find eigenvalues and eigenvectors"**

Find the eigenvalues and associated eigenvectors of the matrix

$$\begin{bmatrix} 1 & 2 \\ 3 & 2 \end{bmatrix}$$

The first step is to determine the characteristic polynomial of the matrix in order to find the eigenvalues of the matrix A . This is given by

$$\begin{aligned} \det(A - \lambda I) &= 0 \\ \det\left(\begin{bmatrix} 1 & 2 \\ 3 & 2 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}\right) &= 0 \\ \det\begin{bmatrix} 1 - \lambda & 2 \\ 3 & 2 - \lambda \end{bmatrix} &= 0 \\ \lambda^2 - 3\lambda - 4 &= 0 \end{aligned}$$

The eigenvalues are the roots of the above characteristic polynomial. Solving for the roots gives

$$\lambda_1 = 4$$

$$\lambda_2 = -1$$

This table summarises the above result

eigenvalue	algebraic multiplicity	type of eigenvalue
-1	1	real eigenvalue
4	1	real eigenvalue

For each eigenvalue λ found above, we now find the corresponding eigenvector. Considering $\lambda = -1$

We need now to determine the eigenvector \mathbf{v} where

$$\begin{aligned}
 A\mathbf{v} &= \lambda\mathbf{v} \\
 A\mathbf{v} - \lambda\mathbf{v} &= \mathbf{0} \\
 (A - \lambda I)\mathbf{v} &= \mathbf{0} \\
 \left(\begin{bmatrix} 1 & 2 \\ 3 & 2 \end{bmatrix} - (-1) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix} \\
 \left(\begin{bmatrix} 1 & 2 \\ 3 & 2 \end{bmatrix} - \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix} \\
 \begin{bmatrix} 2 & 2 \\ 3 & 3 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix}
 \end{aligned}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\left[\begin{array}{cc|c} 2 & 2 & 0 \\ 3 & 3 & 0 \end{array} \right]$$

$$R_2 = R_2 - \frac{3R_1}{2} \implies \left[\begin{array}{cc|c} 2 & 2 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} 2 & 2 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = -t\}$

Hence the solution is

$$\begin{bmatrix} -t \\ t \end{bmatrix} = \begin{bmatrix} -t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} -t \\ t \end{bmatrix} = t \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

Considering $\lambda = 4$

We need now to determine the eigenvector \mathbf{v} where

$$\begin{aligned} A\mathbf{v} &= \lambda\mathbf{v} \\ A\mathbf{v} - \lambda\mathbf{v} &= \mathbf{0} \\ (A - \lambda I)\mathbf{v} &= \mathbf{0} \\ \left(\begin{bmatrix} 1 & 2 \\ 3 & 2 \end{bmatrix} - (4) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix} \\ \left(\begin{bmatrix} 1 & 2 \\ 3 & 2 \end{bmatrix} - \begin{bmatrix} 4 & 0 \\ 0 & 4 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix} \\ \begin{bmatrix} -3 & 2 \\ 3 & -2 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix} \end{aligned}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\left[\begin{array}{cc|c} -3 & 2 & 0 \\ 3 & -2 & 0 \end{array} \right]$$

$$R_2 = R_2 + R_1 \implies \left[\begin{array}{cc|c} -3 & 2 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} -3 & 2 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = \frac{2t}{3}\}$

Hence the solution is

$$\begin{bmatrix} \frac{2t}{3} \\ t \end{bmatrix} = \begin{bmatrix} \frac{2t}{3} \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} \frac{2t}{3} \\ t \end{bmatrix} = t \begin{bmatrix} \frac{2}{3} \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} \frac{2t}{3} \\ t \end{bmatrix} = \begin{bmatrix} \frac{2}{3} \\ 1 \end{bmatrix}$$

Which can be normalized to

$$\begin{bmatrix} \frac{2t}{3} \\ t \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$$

The following table summarises the result found above.

λ	algebraic multiplicity	geometric multiplicity	defective eigenvalue?	associated eigenvectors
-1	1	2	No	$\begin{bmatrix} -1 \\ 1 \end{bmatrix}$
4	1	2	No	$\begin{bmatrix} 2 \\ 3 \end{bmatrix}$

Since the matrix is not defective, then it is diagonalizable. Let P the matrix whose columns are the eigenvectors found, and let D be diagonal matrix with the eigenvalues at its diagonal. Then we can write

$$A = PDP^{-1}$$

Where

$$D = \begin{bmatrix} -1 & 0 \\ 0 & 4 \end{bmatrix}$$

$$P = \begin{bmatrix} -1 & 2 \\ 1 & 3 \end{bmatrix}$$

Therefore

$$\begin{bmatrix} 1 & 2 \\ 3 & 2 \end{bmatrix} = \begin{bmatrix} -1 & 2 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} -1 & 0 \\ 0 & 4 \end{bmatrix} \begin{bmatrix} -1 & 2 \\ 1 & 3 \end{bmatrix}^{-1}$$

19.2 problem 2

Internal problem ID [11953]

Internal file name [OUTPUT/11962_Sunday_April_14_2024_02_31_23_AM_658154/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 7, Systems of linear differential equations. Section 7.5. Matrices and vectors. Exercises page 345

Problem number: 2.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"find eigenvalues and eigenvectors"**

Find the eigenvalues and associated eigenvectors of the matrix

$$\begin{bmatrix} 3 & 2 \\ 6 & -1 \end{bmatrix}$$

The first step is to determine the characteristic polynomial of the matrix in order to find the eigenvalues of the matrix A . This is given by

$$\begin{aligned} \det(A - \lambda I) &= 0 \\ \det\left(\begin{bmatrix} 3 & 2 \\ 6 & -1 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}\right) &= 0 \\ \det\begin{bmatrix} 3 - \lambda & 2 \\ 6 & -1 - \lambda \end{bmatrix} &= 0 \\ \lambda^2 - 2\lambda - 15 &= 0 \end{aligned}$$

The eigenvalues are the roots of the above characteristic polynomial. Solving for the roots gives

$$\lambda_1 = 5$$

$$\lambda_2 = -3$$

This table summarises the above result

eigenvalue	algebraic multiplicity	type of eigenvalue
-3	1	real eigenvalue
5	1	real eigenvalue

For each eigenvalue λ found above, we now find the corresponding eigenvector. Considering $\lambda = -3$

We need now to determine the eigenvector \mathbf{v} where

$$\begin{aligned}
 A\mathbf{v} &= \lambda\mathbf{v} \\
 A\mathbf{v} - \lambda\mathbf{v} &= \mathbf{0} \\
 (A - \lambda I)\mathbf{v} &= \mathbf{0} \\
 \left(\begin{bmatrix} 3 & 2 \\ 6 & -1 \end{bmatrix} - (-3) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix} \\
 \left(\begin{bmatrix} 3 & 2 \\ 6 & -1 \end{bmatrix} - \begin{bmatrix} -3 & 0 \\ 0 & -3 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix} \\
 \begin{bmatrix} 6 & 2 \\ 6 & 2 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix}
 \end{aligned}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\left[\begin{array}{cc|c} 6 & 2 & 0 \\ 6 & 2 & 0 \end{array} \right]$$

$$R_2 = R_2 - R_1 \implies \left[\begin{array}{cc|c} 6 & 2 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} 6 & 2 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = -\frac{t}{3}\}$

Hence the solution is

$$\begin{bmatrix} -\frac{t}{3} \\ t \end{bmatrix} = \begin{bmatrix} -\frac{t}{3} \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} -\frac{t}{3} \\ t \end{bmatrix} = t \begin{bmatrix} -\frac{1}{3} \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} -\frac{1}{3} \\ 1 \end{bmatrix} = \begin{bmatrix} -\frac{1}{3} \\ 1 \end{bmatrix}$$

Which can be normalized to

$$\begin{bmatrix} -\frac{1}{3} \\ 1 \end{bmatrix} = \begin{bmatrix} -1 \\ 3 \end{bmatrix}$$

Considering $\lambda = 5$

We need now to determine the eigenvector \mathbf{v} where

$$A\mathbf{v} = \lambda\mathbf{v}$$

$$A\mathbf{v} - \lambda\mathbf{v} = \mathbf{0}$$

$$(A - \lambda I)\mathbf{v} = \mathbf{0}$$

$$\left(\begin{bmatrix} 3 & 2 \\ 6 & -1 \end{bmatrix} - (5) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\left(\begin{bmatrix} 3 & 2 \\ 6 & -1 \end{bmatrix} - \begin{bmatrix} 5 & 0 \\ 0 & 5 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -2 & 2 \\ 6 & -6 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\left[\begin{array}{cc|c} -2 & 2 & 0 \\ 6 & -6 & 0 \end{array} \right]$$

$$R_2 = R_2 + 3R_1 \implies \left[\begin{array}{cc|c} -2 & 2 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} -2 & 2 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = t\}$

Hence the solution is

$$\begin{bmatrix} t \\ t \end{bmatrix} = \begin{bmatrix} t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} t \\ t \end{bmatrix} = t \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} t \\ t \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

The following table summarises the result found above.

λ	algebraic multiplicity	geometric multiplicity	defective eigenvalue?	associated eigenvectors
-3	1	2	No	$\begin{bmatrix} -1 \\ 3 \end{bmatrix}$
5	1	2	No	$\begin{bmatrix} 1 \\ 1 \end{bmatrix}$

Since the matrix is not defective, then it is diagonalizable. Let P the matrix whose columns are the eigenvectors found, and let D be diagonal matrix with the eigenvalues at its diagonal. Then we can write

$$A = PDP^{-1}$$

Where

$$D = \begin{bmatrix} -3 & 0 \\ 0 & 5 \end{bmatrix}$$

$$P = \begin{bmatrix} -1 & 1 \\ 3 & 1 \end{bmatrix}$$

Therefore

$$\begin{bmatrix} 3 & 2 \\ 6 & -1 \end{bmatrix} = \begin{bmatrix} -1 & 1 \\ 3 & 1 \end{bmatrix} \begin{bmatrix} -3 & 0 \\ 0 & 5 \end{bmatrix} \begin{bmatrix} -1 & 1 \\ 3 & 1 \end{bmatrix}^{-1}$$

19.3 problem 3

Internal problem ID [11954]

Internal file name [OUTPUT/11963_Sunday_April_14_2024_02_31_24_AM_18998694/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 7, Systems of linear differential equations. Section 7.5. Matrices and vectors. Exercises page 345

Problem number: 3.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"find eigenvalues and eigenvectors"**

Find the eigenvalues and associated eigenvectors of the matrix

$$\begin{bmatrix} 3 & 1 \\ 12 & 2 \end{bmatrix}$$

The first step is to determine the characteristic polynomial of the matrix in order to find the eigenvalues of the matrix A . This is given by

$$\begin{aligned} \det(A - \lambda I) &= 0 \\ \det\left(\begin{bmatrix} 3 & 1 \\ 12 & 2 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}\right) &= 0 \\ \det\begin{bmatrix} 3 - \lambda & 1 \\ 12 & 2 - \lambda \end{bmatrix} &= 0 \\ \lambda^2 - 5\lambda - 6 &= 0 \end{aligned}$$

The eigenvalues are the roots of the above characteristic polynomial. Solving for the roots gives

$$\lambda_1 = 6$$

$$\lambda_2 = -1$$

This table summarises the above result

eigenvalue	algebraic multiplicity	type of eigenvalue
-1	1	real eigenvalue
6	1	real eigenvalue

For each eigenvalue λ found above, we now find the corresponding eigenvector. Considering $\lambda = -1$

We need now to determine the eigenvector \mathbf{v} where

$$\begin{aligned}
 A\mathbf{v} &= \lambda\mathbf{v} \\
 A\mathbf{v} - \lambda\mathbf{v} &= \mathbf{0} \\
 (A - \lambda I)\mathbf{v} &= \mathbf{0} \\
 \left(\begin{bmatrix} 3 & 1 \\ 12 & 2 \end{bmatrix} - (-1) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix} \\
 \left(\begin{bmatrix} 3 & 1 \\ 12 & 2 \end{bmatrix} - \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix} \\
 \begin{bmatrix} 4 & 1 \\ 12 & 3 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix}
 \end{aligned}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\left[\begin{array}{cc|c} 4 & 1 & 0 \\ 12 & 3 & 0 \end{array} \right]$$

$$R_2 = R_2 - 3R_1 \implies \left[\begin{array}{cc|c} 4 & 1 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} 4 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = -\frac{t}{4}\}$

Hence the solution is

$$\begin{bmatrix} -\frac{t}{4} \\ t \end{bmatrix} = \begin{bmatrix} -\frac{t}{4} \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} -\frac{t}{4} \\ t \end{bmatrix} = t \begin{bmatrix} -\frac{1}{4} \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} -\frac{1}{4} \\ 1 \end{bmatrix} = \begin{bmatrix} -\frac{1}{4} \\ 1 \end{bmatrix}$$

Which can be normalized to

$$\begin{bmatrix} -\frac{1}{4} \\ 1 \end{bmatrix} = \begin{bmatrix} -1 \\ 4 \end{bmatrix}$$

Considering $\lambda = 6$

We need now to determine the eigenvector \mathbf{v} where

$$A\mathbf{v} = \lambda\mathbf{v}$$

$$A\mathbf{v} - \lambda\mathbf{v} = \mathbf{0}$$

$$(A - \lambda I)\mathbf{v} = \mathbf{0}$$

$$\left(\begin{bmatrix} 3 & 1 \\ 12 & 2 \end{bmatrix} - (6) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\left(\begin{bmatrix} 3 & 1 \\ 12 & 2 \end{bmatrix} - \begin{bmatrix} 6 & 0 \\ 0 & 6 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -3 & 1 \\ 12 & -4 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\left[\begin{array}{cc|c} -3 & 1 & 0 \\ 12 & -4 & 0 \end{array} \right]$$

$$R_2 = R_2 + 4R_1 \implies \left[\begin{array}{cc|c} -3 & 1 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} -3 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = \frac{t}{3}\}$

Hence the solution is

$$\begin{bmatrix} \frac{t}{3} \\ t \end{bmatrix} = \begin{bmatrix} \frac{t}{3} \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} \frac{t}{3} \\ t \end{bmatrix} = t \begin{bmatrix} \frac{1}{3} \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} \frac{1}{3} \\ 1 \end{bmatrix} = \begin{bmatrix} \frac{1}{3} \\ 1 \end{bmatrix}$$

Which can be normalized to

$$\begin{bmatrix} \frac{1}{3} \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$$

The following table summarises the result found above.

λ	algebraic multiplicity	geometric multiplicity	defective eigenvalue?	associated eigenvectors
-1	1	2	No	$\begin{bmatrix} -1 \\ 4 \end{bmatrix}$
6	1	2	No	$\begin{bmatrix} 1 \\ 3 \end{bmatrix}$

Since the matrix is not defective, then it is diagonalizable. Let P the matrix whose columns are the eigenvectors found, and let D be diagonal matrix with the eigenvalues at its diagonal. Then we can write

$$A = PDP^{-1}$$

Where

$$D = \begin{bmatrix} -1 & 0 \\ 0 & 6 \end{bmatrix}$$
$$P = \begin{bmatrix} -1 & 1 \\ 4 & 3 \end{bmatrix}$$

Therefore

$$\begin{bmatrix} 3 & 1 \\ 12 & 2 \end{bmatrix} = \begin{bmatrix} -1 & 1 \\ 4 & 3 \end{bmatrix} \begin{bmatrix} -1 & 0 \\ 0 & 6 \end{bmatrix} \begin{bmatrix} -1 & 1 \\ 4 & 3 \end{bmatrix}^{-1}$$

19.4 problem 4

Internal problem ID [11955]

Internal file name [OUTPUT/11964_Sunday_April_14_2024_02_31_24_AM_23223417/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 7, Systems of linear differential equations. Section 7.5. Matrices and vectors. Exercises page 345

Problem number: 4.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"find eigenvalues and eigenvectors"**

Find the eigenvalues and associated eigenvectors of the matrix

$$\begin{bmatrix} -2 & 7 \\ 3 & 2 \end{bmatrix}$$

The first step is to determine the characteristic polynomial of the matrix in order to find the eigenvalues of the matrix A . This is given by

$$\begin{aligned} \det(A - \lambda I) &= 0 \\ \det\left(\begin{bmatrix} -2 & 7 \\ 3 & 2 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}\right) &= 0 \\ \det\begin{bmatrix} -2 - \lambda & 7 \\ 3 & 2 - \lambda \end{bmatrix} &= 0 \\ \lambda^2 - 25 &= 0 \end{aligned}$$

The eigenvalues are the roots of the above characteristic polynomial. Solving for the roots gives

$$\begin{aligned} \lambda_1 &= 5 \\ \lambda_2 &= -5 \end{aligned}$$

This table summarises the above result

eigenvalue	algebraic multiplicity	type of eigenvalue
-5	1	real eigenvalue
5	1	real eigenvalue

For each eigenvalue λ found above, we now find the corresponding eigenvector. Considering $\lambda = -5$

We need now to determine the eigenvector \mathbf{v} where

$$\begin{aligned}
 A\mathbf{v} &= \lambda\mathbf{v} \\
 A\mathbf{v} - \lambda\mathbf{v} &= \mathbf{0} \\
 (A - \lambda I)\mathbf{v} &= \mathbf{0} \\
 \left(\begin{bmatrix} -2 & 7 \\ 3 & 2 \end{bmatrix} - (-5) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix} \\
 \left(\begin{bmatrix} -2 & 7 \\ 3 & 2 \end{bmatrix} - \begin{bmatrix} -5 & 0 \\ 0 & -5 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix} \\
 \begin{bmatrix} 3 & 7 \\ 3 & 7 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix}
 \end{aligned}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\left[\begin{array}{cc|c} 3 & 7 & 0 \\ 3 & 7 & 0 \end{array} \right]$$

$$R_2 = R_2 - R_1 \implies \left[\begin{array}{cc|c} 3 & 7 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} 3 & 7 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = -\frac{7t}{3}\}$

Hence the solution is

$$\begin{bmatrix} -\frac{7t}{3} \\ t \end{bmatrix} = \begin{bmatrix} -\frac{7t}{3} \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} -\frac{7t}{3} \\ t \end{bmatrix} = t \begin{bmatrix} -\frac{7}{3} \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} -\frac{7}{3} \\ 1 \end{bmatrix} = \begin{bmatrix} -\frac{7}{3} \\ 1 \end{bmatrix}$$

Which can be normalized to

$$\begin{bmatrix} -\frac{7t}{3} \\ t \end{bmatrix} = \begin{bmatrix} -7 \\ 3 \end{bmatrix}$$

Considering $\lambda = 5$

We need now to determine the eigenvector \mathbf{v} where

$$A\mathbf{v} = \lambda\mathbf{v}$$

$$A\mathbf{v} - \lambda\mathbf{v} = \mathbf{0}$$

$$(A - \lambda I)\mathbf{v} = \mathbf{0}$$

$$\left(\begin{bmatrix} -2 & 7 \\ 3 & 2 \end{bmatrix} - (5) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\left(\begin{bmatrix} -2 & 7 \\ 3 & 2 \end{bmatrix} - \begin{bmatrix} 5 & 0 \\ 0 & 5 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -7 & 7 \\ 3 & -3 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\left[\begin{array}{cc|c} -7 & 7 & 0 \\ 3 & -3 & 0 \end{array} \right]$$

$$R_2 = R_2 + \frac{3R_1}{7} \implies \left[\begin{array}{cc|c} -7 & 7 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} -7 & 7 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = t\}$

Hence the solution is

$$\begin{bmatrix} t \\ t \end{bmatrix} = \begin{bmatrix} t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} t \\ t \end{bmatrix} = t \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} t \\ t \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

The following table summarises the result found above.

λ	algebraic multiplicity	geometric multiplicity	defective eigenvalue?	associated eigenvectors
-5	1	2	No	$\begin{bmatrix} -7 \\ 3 \end{bmatrix}$
5	1	2	No	$\begin{bmatrix} 1 \\ 1 \end{bmatrix}$

Since the matrix is not defective, then it is diagonalizable. Let P the matrix whose columns are the eigenvectors found, and let D be diagonal matrix with the eigenvalues at its diagonal. Then we can write

$$A = PDP^{-1}$$

Where

$$D = \begin{bmatrix} -5 & 0 \\ 0 & 5 \end{bmatrix}$$

$$P = \begin{bmatrix} -7 & 1 \\ 3 & 1 \end{bmatrix}$$

Therefore

$$\begin{bmatrix} -2 & 7 \\ 3 & 2 \end{bmatrix} = \begin{bmatrix} -7 & 1 \\ 3 & 1 \end{bmatrix} \begin{bmatrix} -5 & 0 \\ 0 & 5 \end{bmatrix} \begin{bmatrix} -7 & 1 \\ 3 & 1 \end{bmatrix}^{-1}$$

19.5 problem 5

Internal problem ID [11956]

Internal file name [OUTPUT/11965_Sunday_April_14_2024_02_31_25_AM_38090367/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 7, Systems of linear differential equations. Section 7.5. Matrices and vectors. Exercises page 345

Problem number: 5.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"find eigenvalues and eigenvectors"**

Find the eigenvalues and associated eigenvectors of the matrix

$$\begin{bmatrix} 3 & 4 \\ 5 & 2 \end{bmatrix}$$

The first step is to determine the characteristic polynomial of the matrix in order to find the eigenvalues of the matrix A . This is given by

$$\begin{aligned} \det(A - \lambda I) &= 0 \\ \det\left(\begin{bmatrix} 3 & 4 \\ 5 & 2 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}\right) &= 0 \\ \det\begin{bmatrix} 3 - \lambda & 4 \\ 5 & 2 - \lambda \end{bmatrix} &= 0 \\ \lambda^2 - 5\lambda - 14 &= 0 \end{aligned}$$

The eigenvalues are the roots of the above characteristic polynomial. Solving for the roots gives

$$\lambda_1 = 7$$

$$\lambda_2 = -2$$

This table summarises the above result

eigenvalue	algebraic multiplicity	type of eigenvalue
-2	1	real eigenvalue
7	1	real eigenvalue

For each eigenvalue λ found above, we now find the corresponding eigenvector. Considering $\lambda = -2$

We need now to determine the eigenvector \mathbf{v} where

$$\begin{aligned}
 A\mathbf{v} &= \lambda\mathbf{v} \\
 A\mathbf{v} - \lambda\mathbf{v} &= \mathbf{0} \\
 (A - \lambda I)\mathbf{v} &= \mathbf{0} \\
 \left(\begin{bmatrix} 3 & 4 \\ 5 & 2 \end{bmatrix} - (-2) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix} \\
 \left(\begin{bmatrix} 3 & 4 \\ 5 & 2 \end{bmatrix} - \begin{bmatrix} -2 & 0 \\ 0 & -2 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix} \\
 \begin{bmatrix} 5 & 4 \\ 5 & 4 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix}
 \end{aligned}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\left[\begin{array}{cc|c} 5 & 4 & 0 \\ 5 & 4 & 0 \end{array} \right]$$

$$R_2 = R_2 - R_1 \implies \left[\begin{array}{cc|c} 5 & 4 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} 5 & 4 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = -\frac{4t}{5}\}$

Hence the solution is

$$\begin{bmatrix} -\frac{4t}{5} \\ t \end{bmatrix} = \begin{bmatrix} -\frac{4t}{5} \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} -\frac{4t}{5} \\ t \end{bmatrix} = t \begin{bmatrix} -\frac{4}{5} \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} -\frac{4}{5} \\ 1 \end{bmatrix} = \begin{bmatrix} -\frac{4}{5} \\ 1 \end{bmatrix}$$

Which can be normalized to

$$\begin{bmatrix} -\frac{4}{5} \\ 1 \end{bmatrix} = \begin{bmatrix} -4 \\ 5 \end{bmatrix}$$

Considering $\lambda = 7$

We need now to determine the eigenvector \mathbf{v} where

$$A\mathbf{v} = \lambda\mathbf{v}$$

$$A\mathbf{v} - \lambda\mathbf{v} = \mathbf{0}$$

$$(A - \lambda I)\mathbf{v} = \mathbf{0}$$

$$\left(\begin{bmatrix} 3 & 4 \\ 5 & 2 \end{bmatrix} - (7) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\left(\begin{bmatrix} 3 & 4 \\ 5 & 2 \end{bmatrix} - \begin{bmatrix} 7 & 0 \\ 0 & 7 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -4 & 4 \\ 5 & -5 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\left[\begin{array}{cc|c} -4 & 4 & 0 \\ 5 & -5 & 0 \end{array} \right]$$

$$R_2 = R_2 + \frac{5R_1}{4} \implies \left[\begin{array}{cc|c} -4 & 4 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} -4 & 4 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = t\}$

Hence the solution is

$$\begin{bmatrix} t \\ t \end{bmatrix} = \begin{bmatrix} t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} t \\ t \end{bmatrix} = t \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} t \\ t \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

The following table summarises the result found above.

λ	algebraic multiplicity	geometric multiplicity	defective eigenvalue?	associated eigenvectors
-2	1	2	No	$\begin{bmatrix} -4 \\ 5 \end{bmatrix}$
7	1	2	No	$\begin{bmatrix} 1 \\ 1 \end{bmatrix}$

Since the matrix is not defective, then it is diagonalizable. Let P the matrix whose columns are the eigenvectors found, and let D be diagonal matrix with the eigenvalues at its diagonal. Then we can write

$$A = PDP^{-1}$$

Where

$$D = \begin{bmatrix} -2 & 0 \\ 0 & 7 \end{bmatrix}$$

$$P = \begin{bmatrix} -4 & 1 \\ 5 & 1 \end{bmatrix}$$

Therefore

$$\begin{bmatrix} 3 & 4 \\ 5 & 2 \end{bmatrix} = \begin{bmatrix} -4 & 1 \\ 5 & 1 \end{bmatrix} \begin{bmatrix} -2 & 0 \\ 0 & 7 \end{bmatrix} \begin{bmatrix} -4 & 1 \\ 5 & 1 \end{bmatrix}^{-1}$$

19.6 problem 6

Internal problem ID [11957]

Internal file name [OUTPUT/11966_Sunday_April_14_2024_02_31_25_AM_34181949/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 7, Systems of linear differential equations. Section 7.5. Matrices and vectors. Exercises page 345

Problem number: 6.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"find eigenvalues and eigenvectors"**

Find the eigenvalues and associated eigenvectors of the matrix

$$\begin{bmatrix} 3 & -5 \\ -4 & 2 \end{bmatrix}$$

The first step is to determine the characteristic polynomial of the matrix in order to find the eigenvalues of the matrix A . This is given by

$$\begin{aligned} \det(A - \lambda I) &= 0 \\ \det\left(\begin{bmatrix} 3 & -5 \\ -4 & 2 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}\right) &= 0 \\ \det\begin{bmatrix} 3 - \lambda & -5 \\ -4 & 2 - \lambda \end{bmatrix} &= 0 \\ \lambda^2 - 5\lambda - 14 &= 0 \end{aligned}$$

The eigenvalues are the roots of the above characteristic polynomial. Solving for the roots gives

$$\lambda_1 = 7$$

$$\lambda_2 = -2$$

This table summarises the above result

eigenvalue	algebraic multiplicity	type of eigenvalue
-2	1	real eigenvalue
7	1	real eigenvalue

For each eigenvalue λ found above, we now find the corresponding eigenvector. Considering $\lambda = -2$

We need now to determine the eigenvector \mathbf{v} where

$$\begin{aligned}
 A\mathbf{v} &= \lambda\mathbf{v} \\
 A\mathbf{v} - \lambda\mathbf{v} &= \mathbf{0} \\
 (A - \lambda I)\mathbf{v} &= \mathbf{0} \\
 \left(\begin{bmatrix} 3 & -5 \\ -4 & 2 \end{bmatrix} - (-2) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix} \\
 \left(\begin{bmatrix} 3 & -5 \\ -4 & 2 \end{bmatrix} - \begin{bmatrix} -2 & 0 \\ 0 & -2 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix} \\
 \begin{bmatrix} 5 & -5 \\ -4 & 4 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \end{bmatrix}
 \end{aligned}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\left[\begin{array}{cc|c} 5 & -5 & 0 \\ -4 & 4 & 0 \end{array} \right]$$

$$R_2 = R_2 + \frac{4R_1}{5} \implies \left[\begin{array}{cc|c} 5 & -5 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} 5 & -5 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = t\}$

Hence the solution is

$$\begin{bmatrix} t \\ t \end{bmatrix} = \begin{bmatrix} t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} t \\ t \end{bmatrix} = t \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} t \\ t \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

Considering $\lambda = 7$

We need now to determine the eigenvector \mathbf{v} where

$$\begin{aligned} A\mathbf{v} &= \lambda\mathbf{v} \\ A\mathbf{v} - \lambda\mathbf{v} &= \mathbf{0} \\ (A - \lambda I)\mathbf{v} &= \mathbf{0} \end{aligned}$$

$$\left(\begin{bmatrix} 3 & -5 \\ -4 & 2 \end{bmatrix} - (7) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\left(\begin{bmatrix} 3 & -5 \\ -4 & 2 \end{bmatrix} - \begin{bmatrix} 7 & 0 \\ 0 & 7 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -4 & -5 \\ -4 & -5 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\left[\begin{array}{cc|c} -4 & -5 & 0 \\ -4 & -5 & 0 \end{array} \right]$$

$$R_2 = R_2 - R_1 \implies \left[\begin{array}{cc|c} -4 & -5 & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} -4 & -5 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = -\frac{5t}{4}\}$

Hence the solution is

$$\begin{bmatrix} -\frac{5t}{4} \\ t \end{bmatrix} = \begin{bmatrix} -\frac{5t}{4} \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} -\frac{5t}{4} \\ t \end{bmatrix} = t \begin{bmatrix} -\frac{5}{4} \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} -\frac{5t}{4} \\ t \end{bmatrix} = \begin{bmatrix} -\frac{5}{4} \\ 1 \end{bmatrix}$$

Which can be normalized to

$$\begin{bmatrix} -\frac{5t}{4} \\ t \end{bmatrix} = \begin{bmatrix} -5 \\ 4 \end{bmatrix}$$

The following table summarises the result found above.

λ	algebraic multiplicity	geometric multiplicity	defective eigenvalue?	associated eigenvectors
-2	1	2	No	$\begin{bmatrix} 1 \\ 1 \end{bmatrix}$
7	1	2	No	$\begin{bmatrix} -5 \\ 4 \end{bmatrix}$

Since the matrix is not defective, then it is diagonalizable. Let P the matrix whose columns are the eigenvectors found, and let D be diagonal matrix with the eigenvalues at its diagonal. Then we can write

$$A = PDP^{-1}$$

Where

$$D = \begin{bmatrix} -2 & 0 \\ 0 & 7 \end{bmatrix}$$

$$P = \begin{bmatrix} 1 & -5 \\ 1 & 4 \end{bmatrix}$$

Therefore

$$\begin{bmatrix} 3 & -5 \\ -4 & 2 \end{bmatrix} = \begin{bmatrix} 1 & -5 \\ 1 & 4 \end{bmatrix} \begin{bmatrix} -2 & 0 \\ 0 & 7 \end{bmatrix} \begin{bmatrix} 1 & -5 \\ 1 & 4 \end{bmatrix}^{-1}$$

19.7 problem 7

Internal problem ID [11958]

Internal file name [OUTPUT/11967_Sunday_April_14_2024_02_31_26_AM_18554227/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 7, Systems of linear differential equations. Section 7.5. Matrices and vectors. Exercises page 345

Problem number: 7.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"find eigenvalues and eigenvectors"**

Find the eigenvalues and associated eigenvectors of the matrix

$$\begin{bmatrix} 1 & 1 & -1 \\ 2 & 3 & -4 \\ 4 & 1 & -4 \end{bmatrix}$$

The first step is to determine the characteristic polynomial of the matrix in order to find the eigenvalues of the matrix A . This is given by

$$\begin{aligned} \det(A - \lambda I) &= 0 \\ \det \left(\begin{bmatrix} 1 & 1 & -1 \\ 2 & 3 & -4 \\ 4 & 1 & -4 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) &= 0 \\ \det \begin{bmatrix} 1 - \lambda & 1 & -1 \\ 2 & 3 - \lambda & -4 \\ 4 & 1 & -4 - \lambda \end{bmatrix} &= 0 \\ -\lambda^3 + 7\lambda - 6 &= 0 \end{aligned}$$

The eigenvalues are the roots of the above characteristic polynomial. Solving for the roots gives

$$\lambda_1 = 1$$

$$\lambda_2 = 2$$

$$\lambda_3 = -3$$

This table summarises the above result

eigenvalue	algebraic multiplicity	type of eigenvalue
1	1	real eigenvalue
-3	1	real eigenvalue
2	1	real eigenvalue

For each eigenvalue λ found above, we now find the corresponding eigenvector. Considering $\lambda = 1$

We need now to determine the eigenvector \mathbf{v} where

$$\begin{aligned}
 A\mathbf{v} &= \lambda\mathbf{v} \\
 A\mathbf{v} - \lambda\mathbf{v} &= \mathbf{0} \\
 (A - \lambda I)\mathbf{v} &= \mathbf{0}
 \end{aligned}$$

$$\left(\begin{bmatrix} 1 & 1 & -1 \\ 2 & 3 & -4 \\ 4 & 1 & -4 \end{bmatrix} - (1) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\left(\begin{bmatrix} 1 & 1 & -1 \\ 2 & 3 & -4 \\ 4 & 1 & -4 \end{bmatrix} - \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 1 & -1 \\ 2 & 2 & -4 \\ 4 & 1 & -5 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\left[\begin{array}{ccc|c} 0 & 1 & -1 & 0 \\ 2 & 2 & -4 & 0 \\ 4 & 1 & -5 & 0 \end{array} \right]$$

Since the current pivot $A(1,1)$ is zero, then the current pivot row is replaced with a row with a non-zero pivot. Swapping row 1 and row 2 gives

$$\left[\begin{array}{ccc|c} 2 & 2 & -4 & 0 \\ 0 & 1 & -1 & 0 \\ 4 & 1 & -5 & 0 \end{array} \right]$$

$$R_3 = R_3 - 2R_1 \implies \left[\begin{array}{ccc|c} 2 & 2 & -4 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & -3 & 3 & 0 \end{array} \right]$$

$$R_3 = R_3 + 3R_2 \implies \left[\begin{array}{ccc|c} 2 & 2 & -4 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} 2 & 2 & -4 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_3\}$ and the leading variables are $\{v_1, v_2\}$. Let $v_3 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = t, v_2 = t\}$

Hence the solution is

$$\begin{bmatrix} t \\ t \\ t \end{bmatrix} = \begin{bmatrix} t \\ t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} t \\ t \\ t \end{bmatrix} = t \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} t \\ t \\ t \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

Considering $\lambda = -3$

We need now to determine the eigenvector \mathbf{v} where

$$\begin{aligned}
 A\mathbf{v} &= \lambda\mathbf{v} \\
 A\mathbf{v} - \lambda\mathbf{v} &= \mathbf{0} \\
 (A - \lambda I)\mathbf{v} &= \mathbf{0}
 \end{aligned}$$

$$\left(\begin{bmatrix} 1 & 1 & -1 \\ 2 & 3 & -4 \\ 4 & 1 & -4 \end{bmatrix} - (-3) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\left(\begin{bmatrix} 1 & 1 & -1 \\ 2 & 3 & -4 \\ 4 & 1 & -4 \end{bmatrix} - \begin{bmatrix} -3 & 0 & 0 \\ 0 & -3 & 0 \\ 0 & 0 & -3 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 4 & 1 & -1 \\ 2 & 6 & -4 \\ 4 & 1 & -1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\left[\begin{array}{ccc|c} 4 & 1 & -1 & 0 \\ 2 & 6 & -4 & 0 \\ 4 & 1 & -1 & 0 \end{array} \right]$$

$$R_2 = R_2 - \frac{R_1}{2} \implies \left[\begin{array}{ccc|c} 4 & 1 & -1 & 0 \\ 0 & \frac{11}{2} & -\frac{7}{2} & 0 \\ 4 & 1 & -1 & 0 \end{array} \right]$$

$$R_3 = R_3 - R_1 \implies \left[\begin{array}{ccc|c} 4 & 1 & -1 & 0 \\ 0 & \frac{11}{2} & -\frac{7}{2} & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} 4 & 1 & -1 \\ 0 & \frac{11}{2} & -\frac{7}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_3\}$ and the leading variables are $\{v_1, v_2\}$. Let $v_3 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = \frac{t}{11}, v_2 = \frac{7t}{11}\}$

Hence the solution is

$$\begin{bmatrix} \frac{t}{11} \\ \frac{7t}{11} \\ t \end{bmatrix} = \begin{bmatrix} \frac{t}{11} \\ \frac{7t}{11} \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} \frac{t}{11} \\ \frac{7t}{11} \\ t \end{bmatrix} = t \begin{bmatrix} \frac{1}{11} \\ \frac{7}{11} \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} \frac{1}{11} \\ \frac{7}{11} \\ 1 \end{bmatrix} = \begin{bmatrix} \frac{1}{11} \\ \frac{7}{11} \\ 1 \end{bmatrix}$$

Which can be normalized to

$$\begin{bmatrix} \frac{1}{11} \\ \frac{7}{11} \\ 1 \end{bmatrix} = \begin{bmatrix} 1 \\ 7 \\ 11 \end{bmatrix}$$

Considering $\lambda = 2$

We need now to determine the eigenvector \mathbf{v} where

$$\begin{aligned}
 A\mathbf{v} &= \lambda\mathbf{v} \\
 A\mathbf{v} - \lambda\mathbf{v} &= \mathbf{0} \\
 (A - \lambda I)\mathbf{v} &= \mathbf{0}
 \end{aligned}$$

$$\left(\begin{bmatrix} 1 & 1 & -1 \\ 2 & 3 & -4 \\ 4 & 1 & -4 \end{bmatrix} - (2) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\left(\begin{bmatrix} 1 & 1 & -1 \\ 2 & 3 & -4 \\ 4 & 1 & -4 \end{bmatrix} - \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -1 & 1 & -1 \\ 2 & 1 & -4 \\ 4 & 1 & -6 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\left[\begin{array}{ccc|c} -1 & 1 & -1 & 0 \\ 2 & 1 & -4 & 0 \\ 4 & 1 & -6 & 0 \end{array} \right]$$

$$R_2 = R_2 + 2R_1 \implies \left[\begin{array}{ccc|c} -1 & 1 & -1 & 0 \\ 0 & 3 & -6 & 0 \\ 4 & 1 & -6 & 0 \end{array} \right]$$

$$R_3 = R_3 + 4R_1 \implies \left[\begin{array}{ccc|c} -1 & 1 & -1 & 0 \\ 0 & 3 & -6 & 0 \\ 0 & 5 & -10 & 0 \end{array} \right]$$

$$R_3 = R_3 - \frac{5R_2}{3} \implies \left[\begin{array}{ccc|c} -1 & 1 & -1 & 0 \\ 0 & 3 & -6 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} -1 & 1 & -1 \\ 0 & 3 & -6 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_3\}$ and the leading variables are $\{v_1, v_2\}$. Let $v_3 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = t, v_2 = 2t\}$

Hence the solution is

$$\begin{bmatrix} t \\ 2t \\ t \end{bmatrix} = \begin{bmatrix} t \\ 2t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} t \\ 2t \\ t \end{bmatrix} = t \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} t \\ 2t \\ t \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$$

The following table summarises the result found above.

λ	algebraic multiplicity	geometric multiplicity	defective eigenvalue?	associated eigenvectors
1	1	3	No	$\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$
-3	1	3	No	$\begin{bmatrix} 1 \\ 7 \\ 11 \end{bmatrix}$
2	1	3	No	$\begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$

Since the matrix is not defective, then it is diagonalizable. Let P the matrix whose columns are the eigenvectors found, and let D be diagonal matrix with the eigenvalues at its diagonal. Then we can write

$$A = PDP^{-1}$$

Where

$$D = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -3 & 0 \\ 0 & 0 & 2 \end{bmatrix}$$

$$P = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 7 & 2 \\ 1 & 11 & 1 \end{bmatrix}$$

Therefore

$$\begin{bmatrix} 1 & 1 & -1 \\ 2 & 3 & -4 \\ 4 & 1 & -4 \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 7 & 2 \\ 1 & 11 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & -3 & 0 \\ 0 & 0 & 2 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \\ 1 & 7 & 2 \\ 1 & 11 & 1 \end{bmatrix}^{-1}$$

19.8 problem 8

Internal problem ID [11959]

Internal file name [OUTPUT/11968_Sunday_April_14_2024_02_31_26_AM_33178477/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 7, Systems of linear differential equations. Section 7.5. Matrices and vectors. Exercises page 345

Problem number: 8.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"find eigenvalues and eigenvectors"**

Find the eigenvalues and associated eigenvectors of the matrix

$$\begin{bmatrix} 1 & -1 & -1 \\ 1 & 3 & 1 \\ -3 & -6 & 6 \end{bmatrix}$$

The first step is to determine the characteristic polynomial of the matrix in order to find the eigenvalues of the matrix A . This is given by

$$\begin{aligned} \det(A - \lambda I) &= 0 \\ \det \left(\begin{bmatrix} 1 & -1 & -1 \\ 1 & 3 & 1 \\ -3 & -6 & 6 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) &= 0 \\ \det \begin{bmatrix} 1 - \lambda & -1 & -1 \\ 1 & 3 - \lambda & 1 \\ -3 & -6 & 6 - \lambda \end{bmatrix} &= 0 \\ -\lambda^3 + 10\lambda^2 - 31\lambda + 30 &= 0 \end{aligned}$$

The eigenvalues are the roots of the above characteristic polynomial. Solving for the roots gives

$$\lambda_1 = 5$$

$$\lambda_2 = 2$$

$$\lambda_3 = 3$$

This table summarises the above result

eigenvalue	algebraic multiplicity	type of eigenvalue
2	1	real eigenvalue
3	1	real eigenvalue
5	1	real eigenvalue

For each eigenvalue λ found above, we now find the corresponding eigenvector. Considering $\lambda = 2$

We need now to determine the eigenvector \mathbf{v} where

$$\begin{aligned}
 A\mathbf{v} &= \lambda\mathbf{v} \\
 A\mathbf{v} - \lambda\mathbf{v} &= \mathbf{0} \\
 (A - \lambda I)\mathbf{v} &= \mathbf{0}
 \end{aligned}$$

$$\left(\begin{pmatrix} \begin{bmatrix} 1 & -1 & -1 \\ 1 & 3 & 1 \\ -3 & -6 & 6 \end{bmatrix} - (2) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \end{pmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \right)$$

$$\left(\begin{pmatrix} \begin{bmatrix} 1 & -1 & -1 \\ 1 & 3 & 1 \\ -3 & -6 & 6 \end{bmatrix} - \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix} \end{pmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \right)$$

$$\begin{bmatrix} -1 & -1 & -1 \\ 1 & 1 & 1 \\ -3 & -6 & 4 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\left[\begin{array}{ccc|c} -1 & -1 & -1 & 0 \\ 1 & 1 & 1 & 0 \\ -3 & -6 & 4 & 0 \end{array} \right]$$

$$R_2 = R_2 + R_1 \implies \left[\begin{array}{ccc|c} -1 & -1 & -1 & 0 \\ 0 & 0 & 0 & 0 \\ -3 & -6 & 4 & 0 \end{array} \right]$$

$$R_3 = R_3 - 3R_1 \implies \left[\begin{array}{ccc|c} -1 & -1 & -1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & -3 & 7 & 0 \end{array} \right]$$

Since the current pivot $A(2,2)$ is zero, then the current pivot row is replaced with a row with a non-zero pivot. Swapping row 2 and row 3 gives

$$\left[\begin{array}{ccc|c} -1 & -1 & -1 & 0 \\ 0 & -3 & 7 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\left[\begin{array}{ccc} -1 & -1 & -1 \\ 0 & -3 & 7 \\ 0 & 0 & 0 \end{array} \right] \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_3\}$ and the leading variables are $\{v_1, v_2\}$. Let $v_3 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = -\frac{10t}{3}, v_2 = \frac{7t}{3}\}$

Hence the solution is

$$\begin{bmatrix} -\frac{10t}{3} \\ \frac{7t}{3} \\ t \end{bmatrix} = \begin{bmatrix} -\frac{10t}{3} \\ \frac{7t}{3} \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} -\frac{10t}{3} \\ \frac{7t}{3} \\ t \end{bmatrix} = t \begin{bmatrix} -\frac{10}{3} \\ \frac{7}{3} \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} -\frac{10t}{3} \\ \frac{7t}{3} \\ t \end{bmatrix} = \begin{bmatrix} -\frac{10}{3} \\ \frac{7}{3} \\ 1 \end{bmatrix}$$

Which can be normalized to

$$\begin{bmatrix} -\frac{10t}{3} \\ \frac{7t}{3} \\ t \end{bmatrix} = \begin{bmatrix} -10 \\ 7 \\ 3 \end{bmatrix}$$

Considering $\lambda = 3$

We need now to determine the eigenvector \mathbf{v} where

$$A\mathbf{v} = \lambda\mathbf{v}$$

$$A\mathbf{v} - \lambda\mathbf{v} = \mathbf{0}$$

$$(A - \lambda I)\mathbf{v} = \mathbf{0}$$

$$\left(\begin{bmatrix} 1 & -1 & -1 \\ 1 & 3 & 1 \\ -3 & -6 & 6 \end{bmatrix} - (3) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\left(\begin{bmatrix} 1 & -1 & -1 \\ 1 & 3 & 1 \\ -3 & -6 & 6 \end{bmatrix} - \begin{bmatrix} 3 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 3 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -2 & -1 & -1 \\ 1 & 0 & 1 \\ -3 & -6 & 3 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\left[\begin{array}{ccc|c} -2 & -1 & -1 & 0 \\ 1 & 0 & 1 & 0 \\ -3 & -6 & 3 & 0 \end{array} \right]$$

$$R_2 = R_2 + \frac{R_1}{2} \implies \left[\begin{array}{ccc|c} -2 & -1 & -1 & 0 \\ 0 & -\frac{1}{2} & \frac{1}{2} & 0 \\ -3 & -6 & 3 & 0 \end{array} \right]$$

$$R_3 = R_3 - \frac{3R_1}{2} \implies \left[\begin{array}{ccc|c} -2 & -1 & -1 & 0 \\ 0 & -\frac{1}{2} & \frac{1}{2} & 0 \\ 0 & -\frac{9}{2} & \frac{9}{2} & 0 \end{array} \right]$$

$$R_3 = R_3 - 9R_2 \implies \left[\begin{array}{ccc|c} -2 & -1 & -1 & 0 \\ 0 & -\frac{1}{2} & \frac{1}{2} & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\left[\begin{array}{ccc} -2 & -1 & -1 \\ 0 & -\frac{1}{2} & \frac{1}{2} \\ 0 & 0 & 0 \end{array} \right] \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_3\}$ and the leading variables are $\{v_1, v_2\}$. Let $v_3 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = -t, v_2 = t\}$

Hence the solution is

$$\begin{bmatrix} -t \\ t \\ t \end{bmatrix} = \begin{bmatrix} -t \\ t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} -t \\ t \\ t \end{bmatrix} = t \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} -t \\ t \\ t \end{bmatrix} = \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}$$

Considering $\lambda = 5$

We need now to determine the eigenvector \mathbf{v} where

$$\begin{aligned}
 A\mathbf{v} &= \lambda\mathbf{v} \\
 A\mathbf{v} - \lambda\mathbf{v} &= \mathbf{0} \\
 (A - \lambda I)\mathbf{v} &= \mathbf{0}
 \end{aligned}$$

$$\left(\begin{bmatrix} 1 & -1 & -1 \\ 1 & 3 & 1 \\ -3 & -6 & 6 \end{bmatrix} - (5) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\left(\begin{bmatrix} 1 & -1 & -1 \\ 1 & 3 & 1 \\ -3 & -6 & 6 \end{bmatrix} - \begin{bmatrix} 5 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 5 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -4 & -1 & -1 \\ 1 & -2 & 1 \\ -3 & -6 & 1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\left[\begin{array}{ccc|c} -4 & -1 & -1 & 0 \\ 1 & -2 & 1 & 0 \\ -3 & -6 & 1 & 0 \end{array} \right]$$

$$R_2 = R_2 + \frac{R_1}{4} \implies \left[\begin{array}{ccc|c} -4 & -1 & -1 & 0 \\ 0 & -\frac{9}{4} & \frac{3}{4} & 0 \\ -3 & -6 & 1 & 0 \end{array} \right]$$

$$R_3 = R_3 - \frac{3R_1}{4} \implies \left[\begin{array}{ccc|c} -4 & -1 & -1 & 0 \\ 0 & -\frac{9}{4} & \frac{3}{4} & 0 \\ 0 & -\frac{21}{4} & \frac{7}{4} & 0 \end{array} \right]$$

$$R_3 = R_3 - \frac{7R_2}{3} \implies \left[\begin{array}{ccc|c} -4 & -1 & -1 & 0 \\ 0 & -\frac{9}{4} & \frac{3}{4} & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} -4 & -1 & -1 \\ 0 & -\frac{9}{4} & \frac{3}{4} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_3\}$ and the leading variables are $\{v_1, v_2\}$. Let $v_3 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = -\frac{t}{3}, v_2 = \frac{t}{3}\}$

Hence the solution is

$$\begin{bmatrix} -\frac{t}{3} \\ \frac{t}{3} \\ t \end{bmatrix} = \begin{bmatrix} -\frac{t}{3} \\ \frac{t}{3} \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} -\frac{t}{3} \\ \frac{t}{3} \\ t \end{bmatrix} = t \begin{bmatrix} -\frac{1}{3} \\ \frac{1}{3} \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} -\frac{t}{3} \\ \frac{t}{3} \\ t \end{bmatrix} = \begin{bmatrix} -\frac{1}{3} \\ \frac{1}{3} \\ 1 \end{bmatrix}$$

Which can be normalized to

$$\begin{bmatrix} -\frac{t}{3} \\ \frac{t}{3} \\ t \end{bmatrix} = \begin{bmatrix} -1 \\ 1 \\ 3 \end{bmatrix}$$

The following table summarises the result found above.

λ	algebraic multiplicity	geometric multiplicity	defective eigenvalue?	associated eigenvectors
2	1	3	No	$\begin{bmatrix} -10 \\ 7 \\ 3 \end{bmatrix}$
3	1	3	No	$\begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}$
5	1	3	No	$\begin{bmatrix} -1 \\ 1 \\ 3 \end{bmatrix}$

Since the matrix is not defective, then it is diagonalizable. Let P the matrix whose columns are the eigenvectors found, and let D be diagonal matrix with the eigenvalues at its diagonal. Then we can write

$$A = PDP^{-1}$$

Where

$$D = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 5 \end{bmatrix}$$

$$P = \begin{bmatrix} -10 & -1 & -1 \\ 7 & 1 & 1 \\ 3 & 1 & 3 \end{bmatrix}$$

Therefore

$$\begin{bmatrix} 1 & -1 & -1 \\ 1 & 3 & 1 \\ -3 & -6 & 6 \end{bmatrix} = \begin{bmatrix} -10 & -1 & -1 \\ 7 & 1 & 1 \\ 3 & 1 & 3 \end{bmatrix} \begin{bmatrix} 2 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 5 \end{bmatrix} \begin{bmatrix} -10 & -1 & -1 \\ 7 & 1 & 1 \\ 3 & 1 & 3 \end{bmatrix}^{-1}$$

19.9 problem 9

Internal problem ID [11960]

Internal file name [OUTPUT/11969_Sunday_April_14_2024_02_31_27_AM_2632022/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 7, Systems of linear differential equations. Section 7.5. Matrices and vectors. Exercises page 345

Problem number: 9.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"find eigenvalues and eigenvectors"**

Find the eigenvalues and associated eigenvectors of the matrix

$$\begin{bmatrix} 1 & -1 & -1 \\ 1 & 3 & 1 \\ -3 & 1 & -1 \end{bmatrix}$$

The first step is to determine the characteristic polynomial of the matrix in order to find the eigenvalues of the matrix A . This is given by

$$\begin{aligned} \det(A - \lambda I) &= 0 \\ \det \left(\begin{bmatrix} 1 & -1 & -1 \\ 1 & 3 & 1 \\ -3 & 1 & -1 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) &= 0 \\ \det \begin{bmatrix} 1 - \lambda & -1 & -1 \\ 1 & 3 - \lambda & 1 \\ -3 & 1 & -1 - \lambda \end{bmatrix} &= 0 \\ -\lambda^3 + 3\lambda^2 + 4\lambda - 12 &= 0 \end{aligned}$$

The eigenvalues are the roots of the above characteristic polynomial. Solving for the roots gives

$$\lambda_1 = 2$$

$$\lambda_2 = 3$$

$$\lambda_3 = -2$$

This table summarises the above result

eigenvalue	algebraic multiplicity	type of eigenvalue
-2	1	real eigenvalue
2	1	real eigenvalue
3	1	real eigenvalue

For each eigenvalue λ found above, we now find the corresponding eigenvector. Considering $\lambda = -2$

We need now to determine the eigenvector \mathbf{v} where

$$\begin{aligned}
 A\mathbf{v} &= \lambda\mathbf{v} \\
 A\mathbf{v} - \lambda\mathbf{v} &= \mathbf{0} \\
 (A - \lambda I)\mathbf{v} &= \mathbf{0}
 \end{aligned}$$

$$\left(\begin{bmatrix} 1 & -1 & -1 \\ 1 & 3 & 1 \\ -3 & 1 & -1 \end{bmatrix} - (-2) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\left(\begin{bmatrix} 1 & -1 & -1 \\ 1 & 3 & 1 \\ -3 & 1 & -1 \end{bmatrix} - \begin{bmatrix} -2 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & -2 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 3 & -1 & -1 \\ 1 & 5 & 1 \\ -3 & 1 & 1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\left[\begin{array}{ccc|c} 3 & -1 & -1 & 0 \\ 1 & 5 & 1 & 0 \\ -3 & 1 & 1 & 0 \end{array} \right]$$

$$R_2 = R_2 - \frac{R_1}{3} \implies \left[\begin{array}{ccc|c} 3 & -1 & -1 & 0 \\ 0 & \frac{16}{3} & \frac{4}{3} & 0 \\ -3 & 1 & 1 & 0 \end{array} \right]$$

$$R_3 = R_3 + R_1 \implies \left[\begin{array}{ccc|c} 3 & -1 & -1 & 0 \\ 0 & \frac{16}{3} & \frac{4}{3} & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\left[\begin{array}{ccc} 3 & -1 & -1 \\ 0 & \frac{16}{3} & \frac{4}{3} \\ 0 & 0 & 0 \end{array} \right] \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_3\}$ and the leading variables are $\{v_1, v_2\}$. Let $v_3 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = \frac{t}{4}, v_2 = -\frac{t}{4}\}$

Hence the solution is

$$\begin{bmatrix} \frac{t}{4} \\ -\frac{t}{4} \\ t \end{bmatrix} = \begin{bmatrix} \frac{t}{4} \\ -\frac{t}{4} \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} \frac{t}{4} \\ -\frac{t}{4} \\ t \end{bmatrix} = t \begin{bmatrix} \frac{1}{4} \\ -\frac{1}{4} \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} \frac{t}{4} \\ -\frac{t}{4} \\ t \end{bmatrix} = \begin{bmatrix} \frac{1}{4} \\ -\frac{1}{4} \\ 1 \end{bmatrix}$$

Which can be normalized to

$$\begin{bmatrix} \frac{t}{4} \\ -\frac{t}{4} \\ t \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \\ 4 \end{bmatrix}$$

Considering $\lambda = 2$

We need now to determine the eigenvector \mathbf{v} where

$$\begin{aligned}
 A\mathbf{v} &= \lambda\mathbf{v} \\
 A\mathbf{v} - \lambda\mathbf{v} &= \mathbf{0} \\
 (A - \lambda I)\mathbf{v} &= \mathbf{0}
 \end{aligned}$$

$$\left(\begin{bmatrix} 1 & -1 & -1 \\ 1 & 3 & 1 \\ -3 & 1 & -1 \end{bmatrix} - (2) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\left(\begin{bmatrix} 1 & -1 & -1 \\ 1 & 3 & 1 \\ -3 & 1 & -1 \end{bmatrix} - \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -1 & -1 & -1 \\ 1 & 1 & 1 \\ -3 & 1 & -3 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\left[\begin{array}{ccc|c} -1 & -1 & -1 & 0 \\ 1 & 1 & 1 & 0 \\ -3 & 1 & -3 & 0 \end{array} \right]$$

$$R_2 = R_2 + R_1 \implies \left[\begin{array}{ccc|c} -1 & -1 & -1 & 0 \\ 0 & 0 & 0 & 0 \\ -3 & 1 & -3 & 0 \end{array} \right]$$

$$R_3 = R_3 - 3R_1 \implies \left[\begin{array}{ccc|c} -1 & -1 & -1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 4 & 0 & 0 \end{array} \right]$$

Since the current pivot $A(2,2)$ is zero, then the current pivot row is replaced with a row with a non-zero pivot. Swapping row 2 and row 3 gives

$$\left[\begin{array}{ccc|c} -1 & -1 & -1 & 0 \\ 0 & 4 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} -1 & -1 & -1 \\ 0 & 4 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_3\}$ and the leading variables are $\{v_1, v_2\}$. Let $v_3 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = -t, v_2 = 0\}$

Hence the solution is

$$\begin{bmatrix} -t \\ 0 \\ t \end{bmatrix} = \begin{bmatrix} -t \\ 0 \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} -t \\ 0 \\ t \end{bmatrix} = t \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} -t \\ 0 \\ t \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$$

Considering $\lambda = 3$

We need now to determine the eigenvector \mathbf{v} where

$$\begin{aligned}
 A\mathbf{v} &= \lambda\mathbf{v} \\
 A\mathbf{v} - \lambda\mathbf{v} &= \mathbf{0} \\
 (A - \lambda I)\mathbf{v} &= \mathbf{0}
 \end{aligned}$$

$$\left(\begin{bmatrix} 1 & -1 & -1 \\ 1 & 3 & 1 \\ -3 & 1 & -1 \end{bmatrix} - (3) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\left(\begin{bmatrix} 1 & -1 & -1 \\ 1 & 3 & 1 \\ -3 & 1 & -1 \end{bmatrix} - \begin{bmatrix} 3 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 3 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -2 & -1 & -1 \\ 1 & 0 & 1 \\ -3 & 1 & -4 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\left[\begin{array}{ccc|c} -2 & -1 & -1 & 0 \\ 1 & 0 & 1 & 0 \\ -3 & 1 & -4 & 0 \end{array} \right]$$

$$R_2 = R_2 + \frac{R_1}{2} \implies \left[\begin{array}{ccc|c} -2 & -1 & -1 & 0 \\ 0 & -\frac{1}{2} & \frac{1}{2} & 0 \\ -3 & 1 & -4 & 0 \end{array} \right]$$

$$R_3 = R_3 - \frac{3R_1}{2} \implies \left[\begin{array}{ccc|c} -2 & -1 & -1 & 0 \\ 0 & -\frac{1}{2} & \frac{1}{2} & 0 \\ 0 & \frac{5}{2} & -\frac{5}{2} & 0 \end{array} \right]$$

$$R_3 = R_3 + 5R_2 \implies \left[\begin{array}{ccc|c} -2 & -1 & -1 & 0 \\ 0 & -\frac{1}{2} & \frac{1}{2} & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} -2 & -1 & -1 \\ 0 & -\frac{1}{2} & \frac{1}{2} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_3\}$ and the leading variables are $\{v_1, v_2\}$. Let $v_3 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = -t, v_2 = t\}$

Hence the solution is

$$\begin{bmatrix} -t \\ t \\ t \end{bmatrix} = \begin{bmatrix} -t \\ t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} -t \\ t \\ t \end{bmatrix} = t \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} -t \\ t \\ t \end{bmatrix} = \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}$$

The following table summarises the result found above.

λ	algebraic multiplicity	geometric multiplicity	defective eigenvalue?	associated eigenvectors
-2	1	3	No	$\begin{bmatrix} 1 \\ -1 \\ 4 \end{bmatrix}$
2	1	3	No	$\begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$
3	1	3	No	$\begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}$

Since the matrix is not defective, then it is diagonalizable. Let P the matrix whose columns are the eigenvectors found, and let D be diagonal matrix with the eigenvalues at its diagonal. Then we can write

$$A = PDP^{-1}$$

Where

$$D = \begin{bmatrix} -2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$

$$P = \begin{bmatrix} 1 & -1 & -1 \\ -1 & 0 & 1 \\ 4 & 1 & 1 \end{bmatrix}$$

Therefore

$$\begin{bmatrix} 1 & -1 & -1 \\ 1 & 3 & 1 \\ -3 & 1 & -1 \end{bmatrix} = \begin{bmatrix} 1 & -1 & -1 \\ -1 & 0 & 1 \\ 4 & 1 & 1 \end{bmatrix} \begin{bmatrix} -2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix} \begin{bmatrix} 1 & -1 & -1 \\ -1 & 0 & 1 \\ 4 & 1 & 1 \end{bmatrix}^{-1}$$

19.10 problem 10

Internal problem ID [11961]

Internal file name [OUTPUT/11970_Sunday_April_14_2024_02_31_28_AM_40149345/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 7, Systems of linear differential equations. Section 7.5. Matrices and vectors. Exercises page 345

Problem number: 10.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"find eigenvalues and eigenvectors"**

Find the eigenvalues and associated eigenvectors of the matrix

$$\begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}$$

The first step is to determine the characteristic polynomial of the matrix in order to find the eigenvalues of the matrix A . This is given by

$$\begin{aligned} \det(A - \lambda I) &= 0 \\ \det \left(\begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) &= 0 \\ \det \begin{bmatrix} 1 - \lambda & 1 & 0 \\ 1 & -\lambda & 1 \\ 0 & 1 & 1 - \lambda \end{bmatrix} &= 0 \\ -\lambda^3 + 2\lambda^2 + \lambda - 2 &= 0 \end{aligned}$$

The eigenvalues are the roots of the above characteristic polynomial. Solving for the roots gives

$$\begin{aligned} \lambda_1 &= 1 \\ \lambda_2 &= 2 \\ \lambda_3 &= -1 \end{aligned}$$

This table summarises the above result

eigenvalue	algebraic multiplicity	type of eigenvalue
-1	1	real eigenvalue
1	1	real eigenvalue
2	1	real eigenvalue

For each eigenvalue λ found above, we now find the corresponding eigenvector. Considering $\lambda = -1$

We need now to determine the eigenvector \mathbf{v} where

$$\begin{aligned}
 A\mathbf{v} &= \lambda\mathbf{v} \\
 A\mathbf{v} - \lambda\mathbf{v} &= \mathbf{0} \\
 (A - \lambda I)\mathbf{v} &= \mathbf{0} \\
 \left(\begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} - (-1) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \\
 \left(\begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} - \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \\
 \begin{bmatrix} 2 & 1 & 0 \\ 1 & 1 & 1 \\ 0 & 1 & 2 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}
 \end{aligned}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\begin{bmatrix} 2 & 1 & 0 & | & 0 \\ 1 & 1 & 1 & | & 0 \\ 0 & 1 & 2 & | & 0 \end{bmatrix}$$

$$R_2 = R_2 - \frac{R_1}{2} \implies \begin{bmatrix} 2 & 1 & 0 & | & 0 \\ 0 & \frac{1}{2} & 1 & | & 0 \\ 0 & 1 & 2 & | & 0 \end{bmatrix}$$

$$R_3 = R_3 - 2R_2 \implies \left[\begin{array}{ccc|c} 2 & 1 & 0 & 0 \\ 0 & \frac{1}{2} & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\left[\begin{array}{ccc} 2 & 1 & 0 \\ 0 & \frac{1}{2} & 1 \\ 0 & 0 & 0 \end{array} \right] \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_3\}$ and the leading variables are $\{v_1, v_2\}$. Let $v_3 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = t, v_2 = -2t\}$

Hence the solution is

$$\begin{bmatrix} t \\ -2t \\ t \end{bmatrix} = \begin{bmatrix} t \\ -2t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} t \\ -2t \\ t \end{bmatrix} = t \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} t \\ -2t \\ t \end{bmatrix} = \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}$$

Considering $\lambda = 1$

We need now to determine the eigenvector \mathbf{v} where

$$\begin{aligned}
 A\mathbf{v} &= \lambda\mathbf{v} \\
 A\mathbf{v} - \lambda\mathbf{v} &= \mathbf{0} \\
 (A - \lambda I)\mathbf{v} &= \mathbf{0} \\
 \left(\begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} - (1) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \\
 \left(\begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} - \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \\
 \begin{bmatrix} 0 & 1 & 0 \\ 1 & -1 & 1 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}
 \end{aligned}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\left[\begin{array}{ccc|c} 0 & 1 & 0 & 0 \\ 1 & -1 & 1 & 0 \\ 0 & 1 & 0 & 0 \end{array} \right]$$

Since the current pivot $A(1,1)$ is zero, then the current pivot row is replaced with a row with a non-zero pivot. Swapping row 1 and row 2 gives

$$\left[\begin{array}{ccc|c} 1 & -1 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{array} \right]$$

$$R_3 = R_3 - R_2 \implies \left[\begin{array}{ccc|c} 1 & -1 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} 1 & -1 & 1 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_3\}$ and the leading variables are $\{v_1, v_2\}$. Let $v_3 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = -t, v_2 = 0\}$

Hence the solution is

$$\begin{bmatrix} -t \\ 0 \\ t \end{bmatrix} = \begin{bmatrix} -t \\ 0 \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} -t \\ 0 \\ t \end{bmatrix} = t \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$$

Considering $\lambda = 2$

We need now to determine the eigenvector \mathbf{v} where

$$A\mathbf{v} = \lambda\mathbf{v}$$

$$A\mathbf{v} - \lambda\mathbf{v} = \mathbf{0}$$

$$(A - \lambda I)\mathbf{v} = \mathbf{0}$$

$$\left(\begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} - (2) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\left(\begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} - \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -1 & 1 & 0 \\ 1 & -2 & 1 \\ 0 & 1 & -1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\left[\begin{array}{ccc|c} -1 & 1 & 0 & 0 \\ 1 & -2 & 1 & 0 \\ 0 & 1 & -1 & 0 \end{array} \right]$$

$$R_2 = R_2 + R_1 \implies \left[\begin{array}{ccc|c} -1 & 1 & 0 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & 1 & -1 & 0 \end{array} \right]$$

$$R_3 = R_3 + R_2 \implies \left[\begin{array}{ccc|c} -1 & 1 & 0 & 0 \\ 0 & -1 & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} -1 & 1 & 0 \\ 0 & -1 & 1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_3\}$ and the leading variables are $\{v_1, v_2\}$. Let $v_3 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = t, v_2 = t\}$

Hence the solution is

$$\begin{bmatrix} t \\ t \\ t \end{bmatrix} = \begin{bmatrix} t \\ t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} t \\ t \\ t \end{bmatrix} = t \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} t \\ t \\ t \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

The following table summarises the result found above.

λ	algebraic multiplicity	geometric multiplicity	defective eigenvalue?	associated eigenvectors
-1	1	3	No	$\begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}$
1	1	3	No	$\begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$
2	1	3	No	$\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$

Since the matrix is not defective, then it is diagonalizable. Let P the matrix whose columns are the eigenvectors found, and let D be diagonal matrix with the eigenvalues at its diagonal. Then we can write

$$A = PDP^{-1}$$

Where

$$D = \begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix}$$

$$P = \begin{bmatrix} 1 & -1 & 1 \\ -2 & 0 & 1 \\ 1 & 1 & 1 \end{bmatrix}$$

Therefore

$$\begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & -1 & 1 \\ -2 & 0 & 1 \\ 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix} \begin{bmatrix} 1 & -1 & 1 \\ -2 & 0 & 1 \\ 1 & 1 & 1 \end{bmatrix}^{-1}$$

19.11 problem 11

Internal problem ID [11962]

Internal file name [OUTPUT/11971_Sunday_April_14_2024_02_31_28_AM_20775540/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 7, Systems of linear differential equations. Section 7.5. Matrices and vectors. Exercises page 345

Problem number: 11.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"find eigenvalues and eigenvectors"**

Find the eigenvalues and associated eigenvectors of the matrix

$$\begin{bmatrix} 1 & 3 & -6 \\ 0 & 2 & 2 \\ 0 & -1 & 5 \end{bmatrix}$$

The first step is to determine the characteristic polynomial of the matrix in order to find the eigenvalues of the matrix A . This is given by

$$\begin{aligned} \det(A - \lambda I) &= 0 \\ \det \left(\begin{bmatrix} 1 & 3 & -6 \\ 0 & 2 & 2 \\ 0 & -1 & 5 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) &= 0 \\ \det \begin{bmatrix} 1 - \lambda & 3 & -6 \\ 0 & 2 - \lambda & 2 \\ 0 & -1 & 5 - \lambda \end{bmatrix} &= 0 \\ -(-1 + \lambda) (\lambda^2 - 7\lambda + 12) &= 0 \end{aligned}$$

The eigenvalues are the roots of the above characteristic polynomial. Solving for the roots gives

$$\lambda_1 = 1$$

$$\lambda_2 = 4$$

$$\lambda_3 = 3$$

This table summarises the above result

eigenvalue	algebraic multiplicity	type of eigenvalue
1	1	real eigenvalue
3	1	real eigenvalue
4	1	real eigenvalue

For each eigenvalue λ found above, we now find the corresponding eigenvector. Considering $\lambda = 1$

We need now to determine the eigenvector \mathbf{v} where

$$\begin{aligned}
 A\mathbf{v} &= \lambda\mathbf{v} \\
 A\mathbf{v} - \lambda\mathbf{v} &= \mathbf{0} \\
 (A - \lambda I)\mathbf{v} &= \mathbf{0} \\
 \left(\begin{bmatrix} 1 & 3 & -6 \\ 0 & 2 & 2 \\ 0 & -1 & 5 \end{bmatrix} - (1) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \\
 \left(\begin{bmatrix} 1 & 3 & -6 \\ 0 & 2 & 2 \\ 0 & -1 & 5 \end{bmatrix} - \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \\
 \begin{bmatrix} 0 & 3 & -6 \\ 0 & 1 & 2 \\ 0 & -1 & 4 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}
 \end{aligned}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\begin{bmatrix} 0 & 3 & -6 & | & 0 \\ 0 & 1 & 2 & | & 0 \\ 0 & -1 & 4 & | & 0 \end{bmatrix}$$

$$R_2 = R_2 - \frac{R_1}{3} \implies \begin{bmatrix} 0 & 3 & -6 & | & 0 \\ 0 & 0 & 4 & | & 0 \\ 0 & -1 & 4 & | & 0 \end{bmatrix}$$

$$R_3 = R_3 + \frac{R_1}{3} \implies \left[\begin{array}{ccc|c} 0 & 3 & -6 & 0 \\ 0 & 0 & 4 & 0 \\ 0 & 0 & 2 & 0 \end{array} \right]$$

$$R_3 = R_3 - \frac{R_2}{2} \implies \left[\begin{array}{ccc|c} 0 & 3 & -6 & 0 \\ 0 & 0 & 4 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\left[\begin{array}{ccc} 0 & 3 & -6 \\ 0 & 0 & 4 \\ 0 & 0 & 0 \end{array} \right] \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_1\}$ and the leading variables are $\{v_2, v_3\}$. Let $v_1 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_2 = 0, v_3 = 0\}$

Hence the solution is

$$\begin{bmatrix} t \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} t \\ 0 \\ 0 \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} t \\ 0 \\ 0 \end{bmatrix} = t \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} t \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

Considering $\lambda = 3$

We need now to determine the eigenvector \mathbf{v} where

$$\begin{aligned}
 A\mathbf{v} &= \lambda\mathbf{v} \\
 A\mathbf{v} - \lambda\mathbf{v} &= \mathbf{0} \\
 (A - \lambda I)\mathbf{v} &= \mathbf{0} \\
 \left(\begin{bmatrix} 1 & 3 & -6 \\ 0 & 2 & 2 \\ 0 & -1 & 5 \end{bmatrix} - (3) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \\
 \left(\begin{bmatrix} 1 & 3 & -6 \\ 0 & 2 & 2 \\ 0 & -1 & 5 \end{bmatrix} - \begin{bmatrix} 3 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 3 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \\
 \begin{bmatrix} -2 & 3 & -6 \\ 0 & -1 & 2 \\ 0 & -1 & 2 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}
 \end{aligned}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\left[\begin{array}{ccc|c} -2 & 3 & -6 & 0 \\ 0 & -1 & 2 & 0 \\ 0 & -1 & 2 & 0 \end{array} \right]$$

$$R_3 = R_3 - R_2 \implies \left[\begin{array}{ccc|c} -2 & 3 & -6 & 0 \\ 0 & -1 & 2 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} -2 & 3 & -6 \\ 0 & -1 & 2 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_3\}$ and the leading variables are $\{v_1, v_2\}$. Let $v_3 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = 0, v_2 = 2t\}$

Hence the solution is

$$\begin{bmatrix} 0 \\ 2t \\ t \end{bmatrix} = \begin{bmatrix} 0 \\ 2t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} 0 \\ 2t \\ t \end{bmatrix} = t \begin{bmatrix} 0 \\ 2 \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} 0 \\ 2t \\ t \end{bmatrix} = \begin{bmatrix} 0 \\ 2 \\ 1 \end{bmatrix}$$

Considering $\lambda = 4$

We need now to determine the eigenvector \mathbf{v} where

$$A\mathbf{v} = \lambda\mathbf{v}$$

$$A\mathbf{v} - \lambda\mathbf{v} = \mathbf{0}$$

$$(A - \lambda I)\mathbf{v} = \mathbf{0}$$

$$\left(\begin{bmatrix} 1 & 3 & -6 \\ 0 & 2 & 2 \\ 0 & -1 & 5 \end{bmatrix} - (4) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\left(\begin{bmatrix} 1 & 3 & -6 \\ 0 & 2 & 2 \\ 0 & -1 & 5 \end{bmatrix} - \begin{bmatrix} 4 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 4 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -3 & 3 & -6 \\ 0 & -2 & 2 \\ 0 & -1 & 1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\left[\begin{array}{ccc|c} -3 & 3 & -6 & 0 \\ 0 & -2 & 2 & 0 \\ 0 & -1 & 1 & 0 \end{array} \right]$$

$$R_3 = R_3 - \frac{R_2}{2} \implies \left[\begin{array}{ccc|c} -3 & 3 & -6 & 0 \\ 0 & -2 & 2 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\left[\begin{array}{ccc} -3 & 3 & -6 \\ 0 & -2 & 2 \\ 0 & 0 & 0 \end{array} \right] \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_3\}$ and the leading variables are $\{v_1, v_2\}$. Let $v_3 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = -t, v_2 = t\}$

Hence the solution is

$$\begin{bmatrix} -t \\ t \\ t \end{bmatrix} = \begin{bmatrix} -t \\ t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} -t \\ t \\ t \end{bmatrix} = t \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} -t \\ t \\ t \end{bmatrix} = \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}$$

The following table summarises the result found above.

λ	algebraic multiplicity	geometric multiplicity	defective eigenvalue?	associated eigenvectors
1	1	3	No	$\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$
3	1	3	No	$\begin{bmatrix} 0 \\ 2 \\ 1 \end{bmatrix}$
4	1	3	No	$\begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}$

Since the matrix is not defective, then it is diagonalizable. Let P the matrix whose columns are the eigenvectors found, and let D be diagonal matrix with the eigenvalues at its diagonal. Then we can write

$$A = PDP^{-1}$$

Where

$$D = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 4 \end{bmatrix}$$

$$P = \begin{bmatrix} 1 & 0 & -1 \\ 0 & 2 & 1 \\ 0 & 1 & 1 \end{bmatrix}$$

Therefore

$$\begin{bmatrix} 1 & 3 & -6 \\ 0 & 2 & 2 \\ 0 & -1 & 5 \end{bmatrix} = \begin{bmatrix} 1 & 0 & -1 \\ 0 & 2 & 1 \\ 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 4 \end{bmatrix} \begin{bmatrix} 1 & 0 & -1 \\ 0 & 2 & 1 \\ 0 & 1 & 1 \end{bmatrix}^{-1}$$

19.12 problem 12

Internal problem ID [11963]

Internal file name [OUTPUT/11972_Sunday_April_14_2024_02_31_29_AM_78741034/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 7, Systems of linear differential equations. Section 7.5. Matrices and vectors. Exercises page 345

Problem number: 12.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"find eigenvalues and eigenvectors"**

Find the eigenvalues and associated eigenvectors of the matrix

$$\begin{bmatrix} -5 & -12 & 6 \\ 1 & 5 & -1 \\ -7 & -10 & 8 \end{bmatrix}$$

The first step is to determine the characteristic polynomial of the matrix in order to find the eigenvalues of the matrix A . This is given by

$$\begin{aligned} \det(A - \lambda I) &= 0 \\ \det \left(\begin{bmatrix} -5 & -12 & 6 \\ 1 & 5 & -1 \\ -7 & -10 & 8 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) &= 0 \\ \det \begin{bmatrix} -5 - \lambda & -12 & 6 \\ 1 & 5 - \lambda & -1 \\ -7 & -10 & 8 - \lambda \end{bmatrix} &= 0 \\ -\lambda^3 + 8\lambda^2 - 19\lambda + 12 &= 0 \end{aligned}$$

The eigenvalues are the roots of the above characteristic polynomial. Solving for the roots gives

$$\lambda_1 = 1$$

$$\lambda_2 = 3$$

$$\lambda_3 = 4$$

This table summarises the above result

eigenvalue	algebraic multiplicity	type of eigenvalue
1	1	real eigenvalue
3	1	real eigenvalue
4	1	real eigenvalue

For each eigenvalue λ found above, we now find the corresponding eigenvector. Considering $\lambda = 1$

We need now to determine the eigenvector \mathbf{v} where

$$\begin{aligned}
 A\mathbf{v} &= \lambda\mathbf{v} \\
 A\mathbf{v} - \lambda\mathbf{v} &= \mathbf{0} \\
 (A - \lambda I)\mathbf{v} &= \mathbf{0} \\
 \left(\begin{bmatrix} -5 & -12 & 6 \\ 1 & 5 & -1 \\ -7 & -10 & 8 \end{bmatrix} - (1) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \\
 \left(\begin{bmatrix} -5 & -12 & 6 \\ 1 & 5 & -1 \\ -7 & -10 & 8 \end{bmatrix} - \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \\
 \begin{bmatrix} -6 & -12 & 6 \\ 1 & 4 & -1 \\ -7 & -10 & 7 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}
 \end{aligned}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\begin{bmatrix} -6 & -12 & 6 & | & 0 \\ 1 & 4 & -1 & | & 0 \\ -7 & -10 & 7 & | & 0 \end{bmatrix}$$

$$R_2 = R_2 + \frac{R_1}{6} \implies \begin{bmatrix} -6 & -12 & 6 & | & 0 \\ 0 & 2 & 0 & | & 0 \\ -7 & -10 & 7 & | & 0 \end{bmatrix}$$

$$R_3 = R_3 - \frac{7R_1}{6} \implies \left[\begin{array}{ccc|c} -6 & -12 & 6 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 4 & 0 & 0 \end{array} \right]$$

$$R_3 = R_3 - 2R_2 \implies \left[\begin{array}{ccc|c} -6 & -12 & 6 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\left[\begin{array}{ccc} -6 & -12 & 6 \\ 0 & 2 & 0 \\ 0 & 0 & 0 \end{array} \right] \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_3\}$ and the leading variables are $\{v_1, v_2\}$. Let $v_3 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = t, v_2 = 0\}$

Hence the solution is

$$\begin{bmatrix} t \\ 0 \\ t \end{bmatrix} = \begin{bmatrix} t \\ 0 \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} t \\ 0 \\ t \end{bmatrix} = t \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} t \\ 0 \\ t \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

Considering $\lambda = 3$

We need now to determine the eigenvector \mathbf{v} where

$$\begin{aligned}
 A\mathbf{v} &= \lambda\mathbf{v} \\
 A\mathbf{v} - \lambda\mathbf{v} &= \mathbf{0} \\
 (A - \lambda I)\mathbf{v} &= \mathbf{0}
 \end{aligned}$$

$$\left(\begin{bmatrix} -5 & -12 & 6 \\ 1 & 5 & -1 \\ -7 & -10 & 8 \end{bmatrix} - (3) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\left(\begin{bmatrix} -5 & -12 & 6 \\ 1 & 5 & -1 \\ -7 & -10 & 8 \end{bmatrix} - \begin{bmatrix} 3 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 3 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -8 & -12 & 6 \\ 1 & 2 & -1 \\ -7 & -10 & 5 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\left[\begin{array}{ccc|c} -8 & -12 & 6 & 0 \\ 1 & 2 & -1 & 0 \\ -7 & -10 & 5 & 0 \end{array} \right]$$

$$R_2 = R_2 + \frac{R_1}{8} \implies \left[\begin{array}{ccc|c} -8 & -12 & 6 & 0 \\ 0 & \frac{1}{2} & -\frac{1}{4} & 0 \\ -7 & -10 & 5 & 0 \end{array} \right]$$

$$R_3 = R_3 - \frac{7R_1}{8} \implies \left[\begin{array}{ccc|c} -8 & -12 & 6 & 0 \\ 0 & \frac{1}{2} & -\frac{1}{4} & 0 \\ 0 & \frac{1}{2} & -\frac{1}{4} & 0 \end{array} \right]$$

$$R_3 = R_3 - R_2 \implies \left[\begin{array}{ccc|c} -8 & -12 & 6 & 0 \\ 0 & \frac{1}{2} & -\frac{1}{4} & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} -8 & -12 & 6 \\ 0 & \frac{1}{2} & -\frac{1}{4} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_3\}$ and the leading variables are $\{v_1, v_2\}$. Let $v_3 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = 0, v_2 = \frac{t}{2}\}$

Hence the solution is

$$\begin{bmatrix} 0 \\ \frac{t}{2} \\ t \end{bmatrix} = \begin{bmatrix} 0 \\ \frac{t}{2} \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} 0 \\ \frac{t}{2} \\ t \end{bmatrix} = t \begin{bmatrix} 0 \\ \frac{1}{2} \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} 0 \\ \frac{t}{2} \\ t \end{bmatrix} = \begin{bmatrix} 0 \\ \frac{1}{2} \\ 1 \end{bmatrix}$$

Which can be normalized to

$$\begin{bmatrix} 0 \\ \frac{t}{2} \\ t \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}$$

Considering $\lambda = 4$

We need now to determine the eigenvector \mathbf{v} where

$$\begin{aligned}
 A\mathbf{v} &= \lambda\mathbf{v} \\
 A\mathbf{v} - \lambda\mathbf{v} &= \mathbf{0} \\
 (A - \lambda I)\mathbf{v} &= \mathbf{0}
 \end{aligned}$$

$$\left(\begin{bmatrix} -5 & -12 & 6 \\ 1 & 5 & -1 \\ -7 & -10 & 8 \end{bmatrix} - (4) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\left(\begin{bmatrix} -5 & -12 & 6 \\ 1 & 5 & -1 \\ -7 & -10 & 8 \end{bmatrix} - \begin{bmatrix} 4 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 4 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -9 & -12 & 6 \\ 1 & 1 & -1 \\ -7 & -10 & 4 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\left[\begin{array}{ccc|c} -9 & -12 & 6 & 0 \\ 1 & 1 & -1 & 0 \\ -7 & -10 & 4 & 0 \end{array} \right]$$

$$R_2 = R_2 + \frac{R_1}{9} \implies \left[\begin{array}{ccc|c} -9 & -12 & 6 & 0 \\ 0 & -\frac{1}{3} & -\frac{1}{3} & 0 \\ -7 & -10 & 4 & 0 \end{array} \right]$$

$$R_3 = R_3 - \frac{7R_1}{9} \implies \left[\begin{array}{ccc|c} -9 & -12 & 6 & 0 \\ 0 & -\frac{1}{3} & -\frac{1}{3} & 0 \\ 0 & -\frac{2}{3} & -\frac{2}{3} & 0 \end{array} \right]$$

$$R_3 = R_3 - 2R_2 \implies \left[\begin{array}{ccc|c} -9 & -12 & 6 & 0 \\ 0 & -\frac{1}{3} & -\frac{1}{3} & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} -9 & -12 & 6 \\ 0 & -\frac{1}{3} & -\frac{1}{3} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_3\}$ and the leading variables are $\{v_1, v_2\}$. Let $v_3 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = 2t, v_2 = -t\}$

Hence the solution is

$$\begin{bmatrix} 2t \\ -t \\ t \end{bmatrix} = \begin{bmatrix} 2t \\ -t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} 2t \\ -t \\ t \end{bmatrix} = t \begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} 2t \\ -t \\ t \end{bmatrix} = \begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix}$$

The following table summarises the result found above.

λ	algebraic multiplicity	geometric multiplicity	defective eigenvalue?	associated eigenvectors
1	1	3	No	$\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$
3	1	3	No	$\begin{bmatrix} 0 \\ 1 \\ 2 \end{bmatrix}$
4	1	3	No	$\begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix}$

Since the matrix is not defective, then it is diagonalizable. Let P the matrix whose columns are the eigenvectors found, and let D be diagonal matrix with the eigenvalues at its diagonal. Then we can write

$$A = PDP^{-1}$$

Where

$$D = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 4 \end{bmatrix}$$

$$P = \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & -1 \\ 1 & 2 & 1 \end{bmatrix}$$

Therefore

$$\begin{bmatrix} -5 & -12 & 6 \\ 1 & 5 & -1 \\ -7 & -10 & 8 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & -1 \\ 1 & 2 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 4 \end{bmatrix} \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & -1 \\ 1 & 2 & 1 \end{bmatrix}^{-1}$$

19.13 problem 13

Internal problem ID [11964]

Internal file name [OUTPUT/11973_Sunday_April_14_2024_02_31_30_AM_38495058/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 7, Systems of linear differential equations. Section 7.5. Matrices and vectors. Exercises page 345

Problem number: 13.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"find eigenvalues and eigenvectors"**

Find the eigenvalues and associated eigenvectors of the matrix

$$\begin{bmatrix} -2 & 5 & 5 \\ -1 & 4 & 5 \\ 3 & -3 & 2 \end{bmatrix}$$

The first step is to determine the characteristic polynomial of the matrix in order to find the eigenvalues of the matrix A . This is given by

$$\begin{aligned} \det(A - \lambda I) &= 0 \\ \det \left(\begin{bmatrix} -2 & 5 & 5 \\ -1 & 4 & 5 \\ 3 & -3 & 2 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) &= 0 \\ \det \begin{bmatrix} -2 - \lambda & 5 & 5 \\ -1 & 4 - \lambda & 5 \\ 3 & -3 & 2 - \lambda \end{bmatrix} &= 0 \\ -\lambda^3 + 4\lambda^2 - \lambda - 6 &= 0 \end{aligned}$$

The eigenvalues are the roots of the above characteristic polynomial. Solving for the roots gives

$$\lambda_1 = 2$$

$$\lambda_2 = 3$$

$$\lambda_3 = -1$$

This table summarises the above result

eigenvalue	algebraic multiplicity	type of eigenvalue
-1	1	real eigenvalue
2	1	real eigenvalue
3	1	real eigenvalue

For each eigenvalue λ found above, we now find the corresponding eigenvector. Considering $\lambda = -1$

We need now to determine the eigenvector \mathbf{v} where

$$\begin{aligned}
 A\mathbf{v} &= \lambda\mathbf{v} \\
 A\mathbf{v} - \lambda\mathbf{v} &= \mathbf{0} \\
 (A - \lambda I)\mathbf{v} &= \mathbf{0}
 \end{aligned}$$

$$\left(\begin{bmatrix} -2 & 5 & 5 \\ -1 & 4 & 5 \\ 3 & -3 & 2 \end{bmatrix} - (-1) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\left(\begin{bmatrix} -2 & 5 & 5 \\ -1 & 4 & 5 \\ 3 & -3 & 2 \end{bmatrix} - \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -1 & 5 & 5 \\ -1 & 5 & 5 \\ 3 & -3 & 3 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\left[\begin{array}{ccc|c} -1 & 5 & 5 & 0 \\ -1 & 5 & 5 & 0 \\ 3 & -3 & 3 & 0 \end{array} \right]$$

$$R_2 = R_2 - R_1 \implies \left[\begin{array}{ccc|c} -1 & 5 & 5 & 0 \\ 0 & 0 & 0 & 0 \\ 3 & -3 & 3 & 0 \end{array} \right]$$

$$R_3 = R_3 + 3R_1 \implies \left[\begin{array}{ccc|c} -1 & 5 & 5 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 12 & 18 & 0 \end{array} \right]$$

Since the current pivot $A(2,2)$ is zero, then the current pivot row is replaced with a row with a non-zero pivot. Swapping row 2 and row 3 gives

$$\left[\begin{array}{ccc|c} -1 & 5 & 5 & 0 \\ 0 & 12 & 18 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} -1 & 5 & 5 \\ 0 & 12 & 18 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_3\}$ and the leading variables are $\{v_1, v_2\}$. Let $v_3 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = -\frac{5t}{2}, v_2 = -\frac{3t}{2}\}$

Hence the solution is

$$\begin{bmatrix} -\frac{5t}{2} \\ -\frac{3t}{2} \\ t \end{bmatrix} = \begin{bmatrix} -\frac{5t}{2} \\ -\frac{3t}{2} \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} -\frac{5t}{2} \\ -\frac{3t}{2} \\ t \end{bmatrix} = t \begin{bmatrix} -\frac{5}{2} \\ -\frac{3}{2} \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} -\frac{5t}{2} \\ -\frac{3t}{2} \\ t \end{bmatrix} = \begin{bmatrix} -\frac{5}{2} \\ -\frac{3}{2} \\ 1 \end{bmatrix}$$

Which can be normalized to

$$\begin{bmatrix} -\frac{5t}{2} \\ -\frac{3t}{2} \\ t \end{bmatrix} = \begin{bmatrix} -5 \\ -3 \\ 2 \end{bmatrix}$$

Considering $\lambda = 2$

We need now to determine the eigenvector \mathbf{v} where

$$A\mathbf{v} = \lambda\mathbf{v}$$

$$A\mathbf{v} - \lambda\mathbf{v} = \mathbf{0}$$

$$(A - \lambda I)\mathbf{v} = \mathbf{0}$$

$$\left(\begin{bmatrix} -2 & 5 & 5 \\ -1 & 4 & 5 \\ 3 & -3 & 2 \end{bmatrix} - (2) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\left(\begin{bmatrix} -2 & 5 & 5 \\ -1 & 4 & 5 \\ 3 & -3 & 2 \end{bmatrix} - \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -4 & 5 & 5 \\ -1 & 2 & 5 \\ 3 & -3 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\left[\begin{array}{ccc|c} -4 & 5 & 5 & 0 \\ -1 & 2 & 5 & 0 \\ 3 & -3 & 0 & 0 \end{array} \right]$$

$$R_2 = R_2 - \frac{R_1}{4} \implies \left[\begin{array}{ccc|c} -4 & 5 & 5 & 0 \\ 0 & \frac{3}{4} & \frac{15}{4} & 0 \\ 3 & -3 & 0 & 0 \end{array} \right]$$

$$R_3 = R_3 + \frac{3R_1}{4} \implies \left[\begin{array}{ccc|c} -4 & 5 & 5 & 0 \\ 0 & \frac{3}{4} & \frac{15}{4} & 0 \\ 0 & \frac{3}{4} & \frac{15}{4} & 0 \end{array} \right]$$

$$R_3 = R_3 - R_2 \implies \left[\begin{array}{ccc|c} -4 & 5 & 5 & 0 \\ 0 & \frac{3}{4} & \frac{15}{4} & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\left[\begin{array}{ccc} -4 & 5 & 5 \\ 0 & \frac{3}{4} & \frac{15}{4} \\ 0 & 0 & 0 \end{array} \right] \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_3\}$ and the leading variables are $\{v_1, v_2\}$. Let $v_3 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = -5t, v_2 = -5t\}$

Hence the solution is

$$\begin{bmatrix} -5t \\ -5t \\ t \end{bmatrix} = \begin{bmatrix} -5t \\ -5t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} -5t \\ -5t \\ t \end{bmatrix} = t \begin{bmatrix} -5 \\ -5 \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} -5t \\ -5t \\ t \end{bmatrix} = \begin{bmatrix} -5 \\ -5 \\ 1 \end{bmatrix}$$

Considering $\lambda = 3$

We need now to determine the eigenvector \mathbf{v} where

$$\begin{aligned}
 A\mathbf{v} &= \lambda\mathbf{v} \\
 A\mathbf{v} - \lambda\mathbf{v} &= \mathbf{0} \\
 (A - \lambda I)\mathbf{v} &= \mathbf{0}
 \end{aligned}$$

$$\left(\begin{bmatrix} -2 & 5 & 5 \\ -1 & 4 & 5 \\ 3 & -3 & 2 \end{bmatrix} - (3) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\left(\begin{bmatrix} -2 & 5 & 5 \\ -1 & 4 & 5 \\ 3 & -3 & 2 \end{bmatrix} - \begin{bmatrix} 3 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 3 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -5 & 5 & 5 \\ -1 & 1 & 5 \\ 3 & -3 & -1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\left[\begin{array}{ccc|c} -5 & 5 & 5 & 0 \\ -1 & 1 & 5 & 0 \\ 3 & -3 & -1 & 0 \end{array} \right]$$

$$R_2 = R_2 - \frac{R_1}{5} \implies \left[\begin{array}{ccc|c} -5 & 5 & 5 & 0 \\ 0 & 0 & 4 & 0 \\ 3 & -3 & -1 & 0 \end{array} \right]$$

$$R_3 = R_3 + \frac{3R_1}{5} \implies \left[\begin{array}{ccc|c} -5 & 5 & 5 & 0 \\ 0 & 0 & 4 & 0 \\ 0 & 0 & 2 & 0 \end{array} \right]$$

$$R_3 = R_3 - \frac{R_2}{2} \implies \left[\begin{array}{ccc|c} -5 & 5 & 5 & 0 \\ 0 & 0 & 4 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} -5 & 5 & 5 \\ 0 & 0 & 4 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1, v_3\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = t, v_3 = 0\}$

Hence the solution is

$$\begin{bmatrix} t \\ t \\ 0 \end{bmatrix} = \begin{bmatrix} t \\ t \\ 0 \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} t \\ t \\ 0 \end{bmatrix} = t \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} t \\ t \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$$

The following table summarises the result found above.

λ	algebraic multiplicity	geometric multiplicity	defective eigenvalue?	associated eigenvectors
-1	1	3	No	$\begin{bmatrix} -5 \\ -3 \\ 2 \end{bmatrix}$
2	1	3	No	$\begin{bmatrix} -5 \\ -5 \\ 1 \end{bmatrix}$
3	1	3	No	$\begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$

Since the matrix is not defective, then it is diagonalizable. Let P the matrix whose columns are the eigenvectors found, and let D be diagonal matrix with the eigenvalues at its diagonal. Then we can write

$$A = PDP^{-1}$$

Where

$$D = \begin{bmatrix} -1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$

$$P = \begin{bmatrix} -5 & -5 & 1 \\ -3 & -5 & 1 \\ 2 & 1 & 0 \end{bmatrix}$$

Therefore

$$\begin{bmatrix} -2 & 5 & 5 \\ -1 & 4 & 5 \\ 3 & -3 & 2 \end{bmatrix} = \begin{bmatrix} -5 & -5 & 1 \\ -3 & -5 & 1 \\ 2 & 1 & 0 \end{bmatrix} \begin{bmatrix} -1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{bmatrix} \begin{bmatrix} -5 & -5 & 1 \\ -3 & -5 & 1 \\ 2 & 1 & 0 \end{bmatrix}^{-1}$$

19.14 problem 14

Internal problem ID [11965]

Internal file name [OUTPUT/11974_Sunday_April_14_2024_02_31_31_AM_74535894/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Willey. New Delhi. 2004.

Section: Chapter 7, Systems of linear differential equations. Section 7.5. Matrices and vectors. Exercises page 345

Problem number: 14.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : **"find eigenvalues and eigenvectors"**

Find the eigenvalues and associated eigenvectors of the matrix

$$\begin{bmatrix} -2 & 6 & -18 \\ 12 & -23 & 66 \\ 5 & -10 & 29 \end{bmatrix}$$

The first step is to determine the characteristic polynomial of the matrix in order to find the eigenvalues of the matrix A . This is given by

$$\begin{aligned} \det(A - \lambda I) &= 0 \\ \det \left(\begin{bmatrix} -2 & 6 & -18 \\ 12 & -23 & 66 \\ 5 & -10 & 29 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) &= 0 \\ \det \begin{bmatrix} -2 - \lambda & 6 & -18 \\ 12 & -23 - \lambda & 66 \\ 5 & -10 & 29 - \lambda \end{bmatrix} &= 0 \\ -\lambda^3 + 4\lambda^2 + \lambda - 4 &= 0 \end{aligned}$$

The eigenvalues are the roots of the above characteristic polynomial. Solving for the roots gives

$$\begin{aligned} \lambda_1 &= 1 \\ \lambda_2 &= 4 \\ \lambda_3 &= -1 \end{aligned}$$

This table summarises the above result

eigenvalue	algebraic multiplicity	type of eigenvalue
-1	1	real eigenvalue
1	1	real eigenvalue
4	1	real eigenvalue

For each eigenvalue λ found above, we now find the corresponding eigenvector. Considering $\lambda = -1$

We need now to determine the eigenvector \mathbf{v} where

$$\begin{aligned}
 A\mathbf{v} &= \lambda\mathbf{v} \\
 A\mathbf{v} - \lambda\mathbf{v} &= \mathbf{0} \\
 (A - \lambda I)\mathbf{v} &= \mathbf{0} \\
 \left(\begin{bmatrix} -2 & 6 & -18 \\ 12 & -23 & 66 \\ 5 & -10 & 29 \end{bmatrix} - (-1) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \\
 \left(\begin{bmatrix} -2 & 6 & -18 \\ 12 & -23 & 66 \\ 5 & -10 & 29 \end{bmatrix} - \begin{bmatrix} -1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & -1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \\
 \begin{bmatrix} -1 & 6 & -18 \\ 12 & -22 & 66 \\ 5 & -10 & 30 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} &= \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}
 \end{aligned}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\begin{bmatrix} -1 & 6 & -18 & | & 0 \\ 12 & -22 & 66 & | & 0 \\ 5 & -10 & 30 & | & 0 \end{bmatrix}$$

$$R_2 = R_2 + 12R_1 \implies \begin{bmatrix} -1 & 6 & -18 & | & 0 \\ 0 & 50 & -150 & | & 0 \\ 5 & -10 & 30 & | & 0 \end{bmatrix}$$

$$R_3 = R_3 + 5R_1 \implies \left[\begin{array}{ccc|c} -1 & 6 & -18 & 0 \\ 0 & 50 & -150 & 0 \\ 0 & 20 & -60 & 0 \end{array} \right]$$

$$R_3 = R_3 - \frac{2R_2}{5} \implies \left[\begin{array}{ccc|c} -1 & 6 & -18 & 0 \\ 0 & 50 & -150 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\left[\begin{array}{ccc} -1 & 6 & -18 \\ 0 & 50 & -150 \\ 0 & 0 & 0 \end{array} \right] \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_3\}$ and the leading variables are $\{v_1, v_2\}$. Let $v_3 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = 0, v_2 = 3t\}$

Hence the solution is

$$\begin{bmatrix} 0 \\ 3t \\ t \end{bmatrix} = \begin{bmatrix} 0 \\ 3t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} 0 \\ 3t \\ t \end{bmatrix} = t \begin{bmatrix} 0 \\ 3 \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} 0 \\ 3t \\ t \end{bmatrix} = \begin{bmatrix} 0 \\ 3 \\ 1 \end{bmatrix}$$

Considering $\lambda = 1$

We need now to determine the eigenvector \mathbf{v} where

$$\begin{aligned}
 A\mathbf{v} &= \lambda\mathbf{v} \\
 A\mathbf{v} - \lambda\mathbf{v} &= \mathbf{0} \\
 (A - \lambda I)\mathbf{v} &= \mathbf{0}
 \end{aligned}$$

$$\left(\begin{bmatrix} -2 & 6 & -18 \\ 12 & -23 & 66 \\ 5 & -10 & 29 \end{bmatrix} - (1) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\left(\begin{bmatrix} -2 & 6 & -18 \\ 12 & -23 & 66 \\ 5 & -10 & 29 \end{bmatrix} - \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -3 & 6 & -18 \\ 12 & -24 & 66 \\ 5 & -10 & 28 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\left[\begin{array}{ccc|c} -3 & 6 & -18 & 0 \\ 12 & -24 & 66 & 0 \\ 5 & -10 & 28 & 0 \end{array} \right]$$

$$R_2 = R_2 + 4R_1 \implies \left[\begin{array}{ccc|c} -3 & 6 & -18 & 0 \\ 0 & 0 & -6 & 0 \\ 5 & -10 & 28 & 0 \end{array} \right]$$

$$R_3 = R_3 + \frac{5R_1}{3} \implies \left[\begin{array}{ccc|c} -3 & 6 & -18 & 0 \\ 0 & 0 & -6 & 0 \\ 0 & 0 & -2 & 0 \end{array} \right]$$

$$R_3 = R_3 - \frac{R_2}{3} \implies \left[\begin{array}{ccc|c} -3 & 6 & -18 & 0 \\ 0 & 0 & -6 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} -3 & 6 & -18 \\ 0 & 0 & -6 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_2\}$ and the leading variables are $\{v_1, v_3\}$. Let $v_2 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = 2t, v_3 = 0\}$

Hence the solution is

$$\begin{bmatrix} 2t \\ t \\ 0 \end{bmatrix} = \begin{bmatrix} 2t \\ t \\ 0 \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} 2t \\ t \\ 0 \end{bmatrix} = t \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} 2t \\ t \\ 0 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}$$

Considering $\lambda = 4$

We need now to determine the eigenvector \mathbf{v} where

$$\begin{aligned}
 A\mathbf{v} &= \lambda\mathbf{v} \\
 A\mathbf{v} - \lambda\mathbf{v} &= \mathbf{0} \\
 (A - \lambda I)\mathbf{v} &= \mathbf{0}
 \end{aligned}$$

$$\left(\begin{bmatrix} -2 & 6 & -18 \\ 12 & -23 & 66 \\ 5 & -10 & 29 \end{bmatrix} - (4) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\left(\begin{bmatrix} -2 & 6 & -18 \\ 12 & -23 & 66 \\ 5 & -10 & 29 \end{bmatrix} - \begin{bmatrix} 4 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 4 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -6 & 6 & -18 \\ 12 & -27 & 66 \\ 5 & -10 & 25 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

We will now do Gaussian elimination in order to solve for the eigenvector. The augmented matrix is

$$\left[\begin{array}{ccc|c} -6 & 6 & -18 & 0 \\ 12 & -27 & 66 & 0 \\ 5 & -10 & 25 & 0 \end{array} \right]$$

$$R_2 = R_2 + 2R_1 \implies \left[\begin{array}{ccc|c} -6 & 6 & -18 & 0 \\ 0 & -15 & 30 & 0 \\ 5 & -10 & 25 & 0 \end{array} \right]$$

$$R_3 = R_3 + \frac{5R_1}{6} \implies \left[\begin{array}{ccc|c} -6 & 6 & -18 & 0 \\ 0 & -15 & 30 & 0 \\ 0 & -5 & 10 & 0 \end{array} \right]$$

$$R_3 = R_3 - \frac{R_2}{3} \implies \left[\begin{array}{ccc|c} -6 & 6 & -18 & 0 \\ 0 & -15 & 30 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} -6 & 6 & -18 \\ 0 & -15 & 30 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_3\}$ and the leading variables are $\{v_1, v_2\}$. Let $v_3 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = -t, v_2 = 2t\}$

Hence the solution is

$$\begin{bmatrix} -t \\ 2t \\ t \end{bmatrix} = \begin{bmatrix} -t \\ 2t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} -t \\ 2t \\ t \end{bmatrix} = t \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix}$$

Or, by letting $t = 1$ then the eigenvector is

$$\begin{bmatrix} -t \\ 2t \\ t \end{bmatrix} = \begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix}$$

The following table summarises the result found above.

λ	algebraic multiplicity	geometric multiplicity	defective eigenvalue?	associated eigenvectors
-1	1	3	No	$\begin{bmatrix} 0 \\ 3 \\ 1 \end{bmatrix}$
1	1	3	No	$\begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}$
4	1	3	No	$\begin{bmatrix} -1 \\ 2 \\ 1 \end{bmatrix}$

Since the matrix is not defective, then it is diagonalizable. Let P the matrix whose columns are the eigenvectors found, and let D be diagonal matrix with the eigenvalues at its diagonal. Then we can write

$$A = PDP^{-1}$$

Where

$$D = \begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 4 \end{bmatrix}$$

$$P = \begin{bmatrix} 0 & 2 & -1 \\ 3 & 1 & 2 \\ 1 & 0 & 1 \end{bmatrix}$$

Therefore

$$\begin{bmatrix} -2 & 6 & -18 \\ 12 & -23 & 66 \\ 5 & -10 & 29 \end{bmatrix} = \begin{bmatrix} 0 & 2 & -1 \\ 3 & 1 & 2 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} -1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 4 \end{bmatrix} \begin{bmatrix} 0 & 2 & -1 \\ 3 & 1 & 2 \\ 1 & 0 & 1 \end{bmatrix}^{-1}$$

20 Chapter 7, Systems of linear differential equations. Section 7.7. Exercises page 375

20.1 problem 1	4682
20.2 problem 2	4694

20.1 problem 1

- 20.1.1 Solution using Matrix exponential method 4682
- 20.1.2 Solution using explicit Eigenvalue and Eigenvector method . . . 4683
- 20.1.3 Maple step by step solution 4690

Internal problem ID [11966]

Internal file name [OUTPUT/11975_Sunday_April_14_2024_02_31_32_AM_73858456/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 7, Systems of linear differential equations. Section 7.7. Exercises page 375

Problem number: 1.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "system of linear ODEs"

Solve

$$\begin{aligned}x'(t) &= x(t) + y(t) - z(t) \\y'(t) &= 2x(t) + 3y(t) - 4z(t) \\z'(t) &= 4x(t) + y(t) - 4z(t)\end{aligned}$$

20.1.1 Solution using Matrix exponential method

In this method, we will assume we have found the matrix exponential e^{At} already. There are different methods to determine this but will not be shown here. This is a system of linear ODE's given as

$$\vec{x}'(t) = A \vec{x}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \\ z'(t) \end{bmatrix} = \begin{bmatrix} 1 & 1 & -1 \\ 2 & 3 & -4 \\ 4 & 1 & -4 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \\ z(t) \end{bmatrix}$$

For the above matrix A , the matrix exponential can be found to be

$$e^{At} = \begin{bmatrix} \frac{(-4e^{5t} + 15e^{4t} - 1)e^{-3t}}{10} & e^{2t} - e^t & \frac{(-6e^{5t} + 5e^{4t} + 1)e^{-3t}}{10} \\ \frac{(-8e^{5t} + 15e^{4t} - 7)e^{-3t}}{10} & -e^t + 2e^{2t} & \frac{(-12e^{5t} + 5e^{4t} + 7)e^{-3t}}{10} \\ \frac{(-4e^{5t} + 15e^{4t} - 11)e^{-3t}}{10} & e^{2t} - e^t & \frac{(-6e^{5t} + 5e^{4t} + 11)e^{-3t}}{10} \end{bmatrix}$$

Therefore the homogeneous solution is

$$\begin{aligned}
 \vec{x}_h(t) &= e^{At} \vec{c} \\
 &= \begin{bmatrix} \frac{(-4e^{5t}+15e^{4t}-1)e^{-3t}}{10} & e^{2t} - e^t & \frac{(-6e^{5t}+5e^{4t}+1)e^{-3t}}{10} \\ \frac{(-8e^{5t}+15e^{4t}-7)e^{-3t}}{10} & -e^t + 2e^{2t} & \frac{(-12e^{5t}+5e^{4t}+7)e^{-3t}}{10} \\ \frac{(-4e^{5t}+15e^{4t}-11)e^{-3t}}{10} & e^{2t} - e^t & \frac{(-6e^{5t}+5e^{4t}+11)e^{-3t}}{10} \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} \\
 &= \begin{bmatrix} \frac{(-4e^{5t}+15e^{4t}-1)e^{-3t}c_1}{10} + (e^{2t} - e^t)c_2 + \frac{(-6e^{5t}+5e^{4t}+1)e^{-3t}c_3}{10} \\ \frac{(-8e^{5t}+15e^{4t}-7)e^{-3t}c_1}{10} + (-e^t + 2e^{2t})c_2 + \frac{(-12e^{5t}+5e^{4t}+7)e^{-3t}c_3}{10} \\ \frac{(-4e^{5t}+15e^{4t}-11)e^{-3t}c_1}{10} + (e^{2t} - e^t)c_2 + \frac{(-6e^{5t}+5e^{4t}+11)e^{-3t}c_3}{10} \end{bmatrix} \\
 &= \begin{bmatrix} \frac{3\left(\left(c_1 - \frac{2c_2}{3} + \frac{c_3}{3}\right)e^{4t} + \left(-\frac{4c_1}{15} + \frac{2c_2}{3} - \frac{2c_3}{5}\right)e^{5t} - \frac{c_1}{15} + \frac{c_3}{15}\right)e^{-3t}}{2} \\ \frac{3\left(\left(c_1 - \frac{2c_2}{3} + \frac{c_3}{3}\right)e^{4t} + \left(-\frac{8c_1}{15} + \frac{4c_2}{3} - \frac{4c_3}{5}\right)e^{5t} - \frac{7c_1}{15} + \frac{7c_3}{15}\right)e^{-3t}}{2} \\ \frac{3e^{-3t}\left(\left(c_1 - \frac{2c_2}{3} + \frac{c_3}{3}\right)e^{4t} + \left(-\frac{4c_1}{15} + \frac{2c_2}{3} - \frac{2c_3}{5}\right)e^{5t} - \frac{11c_1}{15} + \frac{11c_3}{15}\right)}{2} \end{bmatrix}
 \end{aligned}$$

Since no forcing function is given, then the final solution is $\vec{x}_h(t)$ above.

20.1.2 Solution using explicit Eigenvalue and Eigenvector method

This is a system of linear ODE's given as

$$\vec{x}'(t) = A\vec{x}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \\ z'(t) \end{bmatrix} = \begin{bmatrix} 1 & 1 & -1 \\ 2 & 3 & -4 \\ 4 & 1 & -4 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \\ z(t) \end{bmatrix}$$

The first step is find the homogeneous solution. We start by finding the eigenvalues of A . This is done by solving the following equation for the eigenvalues λ

$$\det(A - \lambda I) = 0$$

Expanding gives

$$\det \left(\begin{bmatrix} 1 & 1 & -1 \\ 2 & 3 & -4 \\ 4 & 1 & -4 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) = 0$$

Therefore

$$\det \left(\begin{bmatrix} 1 - \lambda & 1 & -1 \\ 2 & 3 - \lambda & -4 \\ 4 & 1 & -4 - \lambda \end{bmatrix} \right) = 0$$

Which gives the characteristic equation

$$\lambda^3 - 7\lambda + 6 = 0$$

The roots of the above are the eigenvalues.

$$\lambda_1 = -3$$

$$\lambda_2 = 1$$

$$\lambda_3 = 2$$

This table summarises the above result

eigenvalue	algebraic multiplicity	type of eigenvalue
1	1	real eigenvalue
-3	1	real eigenvalue
2	1	real eigenvalue

Now the eigenvector for each eigenvalue are found.

Considering the eigenvalue $\lambda_1 = -3$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} 1 & 1 & -1 \\ 2 & 3 & -4 \\ 4 & 1 & -4 \end{bmatrix} - (-3) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 4 & 1 & -1 \\ 2 & 6 & -4 \\ 4 & 1 & -1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{ccc|c} 4 & 1 & -1 & 0 \\ 2 & 6 & -4 & 0 \\ 4 & 1 & -1 & 0 \end{array} \right]$$

$$R_2 = R_2 - \frac{R_1}{2} \implies \left[\begin{array}{ccc|c} 4 & 1 & -1 & 0 \\ 0 & \frac{11}{2} & -\frac{7}{2} & 0 \\ 4 & 1 & -1 & 0 \end{array} \right]$$

$$R_3 = R_3 - R_1 \implies \left[\begin{array}{ccc|c} 4 & 1 & -1 & 0 \\ 0 & \frac{11}{2} & -\frac{7}{2} & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\left[\begin{array}{ccc} 4 & 1 & -1 \\ 0 & \frac{11}{2} & -\frac{7}{2} \\ 0 & 0 & 0 \end{array} \right] \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_3\}$ and the leading variables are $\{v_1, v_2\}$. Let $v_3 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = \frac{t}{11}, v_2 = \frac{7t}{11}\}$

Hence the solution is

$$\begin{bmatrix} \frac{t}{11} \\ \frac{7t}{11} \\ t \end{bmatrix} = \begin{bmatrix} \frac{t}{11} \\ \frac{7t}{11} \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} \frac{t}{11} \\ \frac{7t}{11} \\ t \end{bmatrix} = t \begin{bmatrix} \frac{1}{11} \\ \frac{7}{11} \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} \frac{t}{11} \\ \frac{7t}{11} \\ t \end{bmatrix} = \begin{bmatrix} \frac{1}{11} \\ \frac{7}{11} \\ 1 \end{bmatrix}$$

Which is normalized to

$$\begin{bmatrix} \frac{t}{11} \\ \frac{7t}{11} \\ t \end{bmatrix} = \begin{bmatrix} 1 \\ 7 \\ 11 \end{bmatrix}$$

Considering the eigenvalue $\lambda_2 = 1$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} 1 & 1 & -1 \\ 2 & 3 & -4 \\ 4 & 1 & -4 \end{bmatrix} - (1) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 0 & 1 & -1 \\ 2 & 2 & -4 \\ 4 & 1 & -5 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{ccc|c} 0 & 1 & -1 & 0 \\ 2 & 2 & -4 & 0 \\ 4 & 1 & -5 & 0 \end{array} \right]$$

Since the current pivot $A(1,1)$ is zero, then the current pivot row is replaced with a row with a non-zero pivot. Swapping row 1 and row 2 gives

$$\left[\begin{array}{ccc|c} 2 & 2 & -4 & 0 \\ 0 & 1 & -1 & 0 \\ 4 & 1 & -5 & 0 \end{array} \right]$$

$$R_3 = R_3 - 2R_1 \implies \left[\begin{array}{ccc|c} 2 & 2 & -4 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & -3 & 3 & 0 \end{array} \right]$$

$$R_3 = R_3 + 3R_2 \implies \left[\begin{array}{ccc|c} 2 & 2 & -4 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} 2 & 2 & -4 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_3\}$ and the leading variables are $\{v_1, v_2\}$. Let $v_3 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = t, v_2 = t\}$

Hence the solution is

$$\begin{bmatrix} t \\ t \\ t \end{bmatrix} = \begin{bmatrix} t \\ t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} t \\ t \\ t \end{bmatrix} = t \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} t \\ t \\ t \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

Considering the eigenvalue $\lambda_3 = 2$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} 1 & 1 & -1 \\ 2 & 3 & -4 \\ 4 & 1 & -4 \end{bmatrix} - (2) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -1 & 1 & -1 \\ 2 & 1 & -4 \\ 4 & 1 & -6 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{ccc|c} -1 & 1 & -1 & 0 \\ 2 & 1 & -4 & 0 \\ 4 & 1 & -6 & 0 \end{array} \right]$$

$$R_2 = R_2 + 2R_1 \implies \left[\begin{array}{ccc|c} -1 & 1 & -1 & 0 \\ 0 & 3 & -6 & 0 \\ 4 & 1 & -6 & 0 \end{array} \right]$$

$$R_3 = R_3 + 4R_1 \implies \left[\begin{array}{ccc|c} -1 & 1 & -1 & 0 \\ 0 & 3 & -6 & 0 \\ 0 & 5 & -10 & 0 \end{array} \right]$$

$$R_3 = R_3 - \frac{5R_2}{3} \implies \left[\begin{array}{ccc|c} -1 & 1 & -1 & 0 \\ 0 & 3 & -6 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} -1 & 1 & -1 \\ 0 & 3 & -6 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_3\}$ and the leading variables are $\{v_1, v_2\}$. Let $v_3 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = t, v_2 = 2t\}$

Hence the solution is

$$\begin{bmatrix} t \\ 2t \\ t \end{bmatrix} = \begin{bmatrix} t \\ 2t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} t \\ 2t \\ t \end{bmatrix} = t \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} t \\ 2t \\ t \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$$

The following table gives a summary of this result. It shows for each eigenvalue the algebraic multiplicity m , and its geometric multiplicity k and the eigenvectors associated with the eigenvalue. If $m > k$ then the eigenvalue is defective which means the number of normal linearly independent eigenvectors associated with this eigenvalue (called the geometric multiplicity k) does not equal the algebraic multiplicity m , and we need to determine an additional $m - k$ generalized eigenvectors for this eigenvalue.

eigenvalue	multiplicity		defective?	eigenvectors
	algebraic m	geometric k		
-3	1	1	No	$\begin{bmatrix} \frac{1}{11} \\ \frac{7}{11} \\ 1 \end{bmatrix}$
1	1	1	No	$\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$
2	1	1	No	$\begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$

Now that we found the eigenvalues and associated eigenvectors, we will go over each eigenvalue and generate the solution basis. The only problem we need to take care of is if the eigenvalue is defective. Since eigenvalue -3 is real and distinct then the corresponding eigenvector solution is

$$\begin{aligned} \vec{x}_1(t) &= \vec{v}_1 e^{-3t} \\ &= \begin{bmatrix} \frac{1}{11} \\ \frac{7}{11} \\ 1 \end{bmatrix} e^{-3t} \end{aligned}$$

Since eigenvalue 1 is real and distinct then the corresponding eigenvector solution is

$$\begin{aligned}\vec{x}_2(t) &= \vec{v}_2 e^t \\ &= \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} e^t\end{aligned}$$

Since eigenvalue 2 is real and distinct then the corresponding eigenvector solution is

$$\begin{aligned}\vec{x}_3(t) &= \vec{v}_3 e^{2t} \\ &= \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} e^{2t}\end{aligned}$$

Therefore the final solution is

$$\vec{x}_h(t) = c_1 \vec{x}_1(t) + c_2 \vec{x}_2(t) + c_3 \vec{x}_3(t)$$

Which is written as

$$\begin{bmatrix} x(t) \\ y(t) \\ z(t) \end{bmatrix} = c_1 \begin{bmatrix} \frac{e^{-3t}}{11} \\ \frac{7e^{-3t}}{11} \\ e^{-3t} \end{bmatrix} + c_2 \begin{bmatrix} e^t \\ e^t \\ e^t \end{bmatrix} + c_3 \begin{bmatrix} e^{2t} \\ 2e^{2t} \\ e^{2t} \end{bmatrix}$$

Which becomes

$$\begin{bmatrix} x(t) \\ y(t) \\ z(t) \end{bmatrix} = \begin{bmatrix} \frac{(11c_3 e^{5t} + 11c_2 e^{4t} + c_1) e^{-3t}}{11} \\ \frac{(22c_3 e^{5t} + 11c_2 e^{4t} + 7c_1) e^{-3t}}{11} \\ (c_3 e^{5t} + c_2 e^{4t} + c_1) e^{-3t} \end{bmatrix}$$

20.1.3 Maple step by step solution

Let's solve

$$[x'(t) = x(t) + y(t) - z(t), y'(t) = 2x(t) + 3y(t) - 4z(t), z'(t) = 4x(t) + y(t) - 4z(t)]$$

- Define vector

$$\vec{x}(t) = \begin{bmatrix} x(t) \\ y(t) \\ z(t) \end{bmatrix}$$

- Convert system into a vector equation

$$\vec{x}'(t) = \begin{bmatrix} 1 & 1 & -1 \\ 2 & 3 & -4 \\ 4 & 1 & -4 \end{bmatrix} \cdot \vec{x}(t) + \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

- System to solve

$$\vec{x}'(t) = \begin{bmatrix} 1 & 1 & -1 \\ 2 & 3 & -4 \\ 4 & 1 & -4 \end{bmatrix} \cdot \vec{x}(t)$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 1 & 1 & -1 \\ 2 & 3 & -4 \\ 4 & 1 & -4 \end{bmatrix}$$

- Rewrite the system as

$$\vec{x}'(t) = A \cdot \vec{x}(t)$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[-3, \begin{bmatrix} \frac{1}{11} \\ \frac{7}{11} \\ 1 \end{bmatrix} \right], \left[1, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right], \left[2, \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[-3, \begin{bmatrix} \frac{1}{11} \\ \frac{7}{11} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{x}_1 = e^{-3t} \cdot \begin{bmatrix} \frac{1}{11} \\ \frac{7}{11} \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[1, \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{x}_2 = e^t \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[2, \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{x}_3 = e^{2t} \cdot \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$$

- General solution to the system of ODEs

$$\vec{x} = c_1 \vec{x}_1 + c_2 \vec{x}_2 + c_3 \vec{x}_3$$

- Substitute solutions into the general solution

$$\vec{x} = e^{-3t} c_1 \cdot \begin{bmatrix} \frac{1}{11} \\ \frac{7}{11} \\ 1 \end{bmatrix} + c_2 e^t \cdot \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + c_3 e^{2t} \cdot \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$$

- Substitute in vector of dependent variables

$$\begin{bmatrix} x(t) \\ y(t) \\ z(t) \end{bmatrix} = \begin{bmatrix} \frac{(11c_3e^{5t} + 11c_2e^{4t} + c_1)e^{-3t}}{11} \\ \frac{(22c_3e^{5t} + 11c_2e^{4t} + 7c_1)e^{-3t}}{11} \\ (c_3e^{5t} + c_2e^{4t} + c_1)e^{-3t} \end{bmatrix}$$

- Solution to the system of ODEs

$$\left\{ x(t) = \frac{(11c_3e^{5t} + 11c_2e^{4t} + c_1)e^{-3t}}{11}, y(t) = \frac{(22c_3e^{5t} + 11c_2e^{4t} + 7c_1)e^{-3t}}{11}, z(t) = (c_3e^{5t} + c_2e^{4t} + c_1)e^{-3t} \right\}$$

✓ Solution by Maple

Time used: 0.031 (sec). Leaf size: 65

```
dsolve([diff(x(t),t)=x(t)+y(t)-z(t),diff(y(t),t)=2*x(t)+3*y(t)-4*z(t),diff(z(t),t)=4*x(t)+y(t)-4*z(t)},{x(t),y(t),z(t)}
```

$$\begin{aligned} x(t) &= c_1e^t + c_2e^{2t} + c_3e^{-3t} \\ y(t) &= c_1e^t + 2c_2e^{2t} + 7c_3e^{-3t} \\ z(t) &= c_1e^t + c_2e^{2t} + 11c_3e^{-3t} \end{aligned}$$

✓ Solution by Mathematica

Time used: 0.012 (sec). Leaf size: 198

```
DSolve[{x'[t]==x[t]+y[t]-z[t],y'[t]==2*x[t]+3*y[t]-4*z[t],z'[t]==4*x[t]+y[t]-4*z[t]},{x[t],y[t],z[t]}
```

$$\begin{aligned} x(t) &\rightarrow \frac{1}{10}e^{-3t}(c_1(15e^{4t} - 4e^{5t} - 1) + 2(5c_2 - 3c_3)e^{5t} + 5(c_3 - 2c_2)e^{4t} + c_3) \\ y(t) &\rightarrow \frac{1}{10}e^{-3t}(c_1(15e^{4t} - 8e^{5t} - 7) + 4(5c_2 - 3c_3)e^{5t} + 5(c_3 - 2c_2)e^{4t} + 7c_3) \\ z(t) &\rightarrow \frac{1}{10}e^{-3t}(c_1(15e^{4t} - 4e^{5t} - 11) + 2(5c_2 - 3c_3)e^{5t} + 5(c_3 - 2c_2)e^{4t} + 11c_3) \end{aligned}$$

20.2 problem 2

20.2.1 Solution using Matrix exponential method	4694
20.2.2 Solution using explicit Eigenvalue and Eigenvector method . . .	4695
20.2.3 Maple step by step solution	4703

Internal problem ID [11967]

Internal file name [OUTPUT/11976_Sunday_April_14_2024_02_31_33_AM_94077692/index.tex]

Book: Differential Equations by Shepley L. Ross. Third edition. John Wiley. New Delhi. 2004.

Section: Chapter 7, Systems of linear differential equations. Section 7.7. Exercises page 375

Problem number: 2.

ODE order: 1.

ODE degree: 1.

The type(s) of ODE detected by this program : "system of linear ODEs"

Solve

$$\begin{aligned}x'(t) &= x(t) - y(t) - z(t) \\y'(t) &= x(t) + 3y(t) + z(t) \\z'(t) &= -3x(t) - 6y(t) + 6z(t)\end{aligned}$$

20.2.1 Solution using Matrix exponential method

In this method, we will assume we have found the matrix exponential e^{At} already. There are different methods to determine this but will not be shown here. This is a system of linear ODE's given as

$$\vec{x}'(t) = A\vec{x}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \\ z'(t) \end{bmatrix} = \begin{bmatrix} 1 & -1 & -1 \\ 1 & 3 & 1 \\ -3 & -6 & 6 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \\ z(t) \end{bmatrix}$$

For the above matrix A , the matrix exponential can be found to be

$$e^{At} = \begin{bmatrix} \frac{10e^{2t}}{3} - 3e^{3t} + \frac{2e^{5t}}{3} & \frac{7e^{5t}}{6} - \frac{9e^{3t}}{2} + \frac{10e^{2t}}{3} & -\frac{e^{5t}}{2} + \frac{e^{3t}}{2} \\ 3e^{3t} - \frac{7e^{2t}}{3} - \frac{2e^{5t}}{3} & -\frac{7e^{2t}}{3} - \frac{7e^{5t}}{6} + \frac{9e^{3t}}{2} & \frac{e^{5t}}{2} - \frac{e^{3t}}{2} \\ 3e^{3t} - e^{2t} - 2e^{5t} & -\frac{7e^{5t}}{2} + \frac{9e^{3t}}{2} - e^{2t} & \frac{3e^{5t}}{2} - \frac{e^{3t}}{2} \end{bmatrix}$$

Therefore the homogeneous solution is

$$\begin{aligned}
 \vec{x}_h(t) &= e^{At} \vec{c} \\
 &= \begin{bmatrix} \frac{10e^{2t}}{3} - 3e^{3t} + \frac{2e^{5t}}{3} & \frac{7e^{5t}}{6} - \frac{9e^{3t}}{2} + \frac{10e^{2t}}{3} & -\frac{e^{5t}}{2} + \frac{e^{3t}}{2} \\ 3e^{3t} - \frac{7e^{2t}}{3} - \frac{2e^{5t}}{3} & -\frac{7e^{2t}}{3} - \frac{7e^{5t}}{6} + \frac{9e^{3t}}{2} & \frac{e^{5t}}{2} - \frac{e^{3t}}{2} \\ 3e^{3t} - e^{2t} - 2e^{5t} & -\frac{7e^{5t}}{2} + \frac{9e^{3t}}{2} - e^{2t} & \frac{3e^{5t}}{2} - \frac{e^{3t}}{2} \end{bmatrix} \begin{bmatrix} c_1 \\ c_2 \\ c_3 \end{bmatrix} \\
 &= \begin{bmatrix} \left(\frac{10e^{2t}}{3} - 3e^{3t} + \frac{2e^{5t}}{3}\right) c_1 + \left(\frac{7e^{5t}}{6} - \frac{9e^{3t}}{2} + \frac{10e^{2t}}{3}\right) c_2 + \left(-\frac{e^{5t}}{2} + \frac{e^{3t}}{2}\right) c_3 \\ \left(3e^{3t} - \frac{7e^{2t}}{3} - \frac{2e^{5t}}{3}\right) c_1 + \left(-\frac{7e^{2t}}{3} - \frac{7e^{5t}}{6} + \frac{9e^{3t}}{2}\right) c_2 + \left(\frac{e^{5t}}{2} - \frac{e^{3t}}{2}\right) c_3 \\ \left(3e^{3t} - e^{2t} - 2e^{5t}\right) c_1 + \left(-\frac{7e^{5t}}{2} + \frac{9e^{3t}}{2} - e^{2t}\right) c_2 + \left(\frac{3e^{5t}}{2} - \frac{e^{3t}}{2}\right) c_3 \end{bmatrix} \\
 &= \begin{bmatrix} \frac{(-6c_1 - 9c_2 + c_3)e^{3t}}{2} + \frac{(4c_1 + 7c_2 - 3c_3)e^{5t}}{6} + \frac{10e^{2t}(c_1 + c_2)}{3} \\ \frac{(6c_1 + 9c_2 - c_3)e^{3t}}{2} + \frac{(-4c_1 - 7c_2 + 3c_3)e^{5t}}{6} - \frac{7e^{2t}(c_1 + c_2)}{3} \\ \frac{(6c_1 + 9c_2 - c_3)e^{3t}}{2} + \frac{(-4c_1 - 7c_2 + 3c_3)e^{5t}}{2} - e^{2t}(c_1 + c_2) \end{bmatrix}
 \end{aligned}$$

Since no forcing function is given, then the final solution is $\vec{x}_h(t)$ above.

20.2.2 Solution using explicit Eigenvalue and Eigenvector method

This is a system of linear ODE's given as

$$\vec{x}'(t) = A \vec{x}(t)$$

Or

$$\begin{bmatrix} x'(t) \\ y'(t) \\ z'(t) \end{bmatrix} = \begin{bmatrix} 1 & -1 & -1 \\ 1 & 3 & 1 \\ -3 & -6 & 6 \end{bmatrix} \begin{bmatrix} x(t) \\ y(t) \\ z(t) \end{bmatrix}$$

The first step is find the homogeneous solution. We start by finding the eigenvalues of A . This is done by solving the following equation for the eigenvalues λ

$$\det(A - \lambda I) = 0$$

Expanding gives

$$\det \left(\begin{bmatrix} 1 & -1 & -1 \\ 1 & 3 & 1 \\ -3 & -6 & 6 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) = 0$$

Therefore

$$\det \left(\begin{bmatrix} 1 - \lambda & -1 & -1 \\ 1 & 3 - \lambda & 1 \\ -3 & -6 & 6 - \lambda \end{bmatrix} \right) = 0$$

Which gives the characteristic equation

$$\lambda^3 - 10\lambda^2 + 31\lambda - 30 = 0$$

The roots of the above are the eigenvalues.

$$\lambda_1 = 3$$

$$\lambda_2 = 5$$

$$\lambda_3 = 2$$

This table summarises the above result

eigenvalue	algebraic multiplicity	type of eigenvalue
2	1	real eigenvalue
3	1	real eigenvalue
5	1	real eigenvalue

Now the eigenvector for each eigenvalue are found.

Considering the eigenvalue $\lambda_1 = 2$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} 1 & -1 & -1 \\ 1 & 3 & 1 \\ -3 & -6 & 6 \end{bmatrix} - (2) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -1 & -1 & -1 \\ 1 & 1 & 1 \\ -3 & -6 & 4 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{ccc|c} -1 & -1 & -1 & 0 \\ 1 & 1 & 1 & 0 \\ -3 & -6 & 4 & 0 \end{array} \right]$$

$$R_2 = R_2 + R_1 \implies \left[\begin{array}{ccc|c} -1 & -1 & -1 & 0 \\ 0 & 0 & 0 & 0 \\ -3 & -6 & 4 & 0 \end{array} \right]$$

$$R_3 = R_3 - 3R_1 \implies \left[\begin{array}{ccc|c} -1 & -1 & -1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & -3 & 7 & 0 \end{array} \right]$$

Since the current pivot $A(2,2)$ is zero, then the current pivot row is replaced with a row with a non-zero pivot. Swapping row 2 and row 3 gives

$$\left[\begin{array}{ccc|c} -1 & -1 & -1 & 0 \\ 0 & -3 & 7 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} -1 & -1 & -1 \\ 0 & -3 & 7 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_3\}$ and the leading variables are $\{v_1, v_2\}$. Let $v_3 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = -\frac{10t}{3}, v_2 = \frac{7t}{3}\}$

Hence the solution is

$$\begin{bmatrix} -\frac{10t}{3} \\ \frac{7t}{3} \\ t \end{bmatrix} = \begin{bmatrix} -\frac{10t}{3} \\ \frac{7t}{3} \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} -\frac{10t}{3} \\ \frac{7t}{3} \\ t \end{bmatrix} = t \begin{bmatrix} -\frac{10}{3} \\ \frac{7}{3} \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} -\frac{10t}{3} \\ \frac{7t}{3} \\ t \end{bmatrix} = \begin{bmatrix} -\frac{10}{3} \\ \frac{7}{3} \\ 1 \end{bmatrix}$$

Which is normalized to

$$\begin{bmatrix} -\frac{10t}{3} \\ \frac{7t}{3} \\ t \end{bmatrix} = \begin{bmatrix} -10 \\ 7 \\ 3 \end{bmatrix}$$

Considering the eigenvalue $\lambda_2 = 3$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} 1 & -1 & -1 \\ 1 & 3 & 1 \\ -3 & -6 & 6 \end{bmatrix} - (3) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -2 & -1 & -1 \\ 1 & 0 & 1 \\ -3 & -6 & 3 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{ccc|c} -2 & -1 & -1 & 0 \\ 1 & 0 & 1 & 0 \\ -3 & -6 & 3 & 0 \end{array} \right]$$

$$R_2 = R_2 + \frac{R_1}{2} \implies \left[\begin{array}{ccc|c} -2 & -1 & -1 & 0 \\ 0 & -\frac{1}{2} & \frac{1}{2} & 0 \\ -3 & -6 & 3 & 0 \end{array} \right]$$

$$R_3 = R_3 - \frac{3R_1}{2} \implies \left[\begin{array}{ccc|c} -2 & -1 & -1 & 0 \\ 0 & -\frac{1}{2} & \frac{1}{2} & 0 \\ 0 & -\frac{9}{2} & \frac{9}{2} & 0 \end{array} \right]$$

$$R_3 = R_3 - 9R_2 \implies \left[\begin{array}{ccc|c} -2 & -1 & -1 & 0 \\ 0 & -\frac{1}{2} & \frac{1}{2} & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\left[\begin{array}{ccc} -2 & -1 & -1 \\ 0 & -\frac{1}{2} & \frac{1}{2} \\ 0 & 0 & 0 \end{array} \right] \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_3\}$ and the leading variables are $\{v_1, v_2\}$. Let $v_3 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = -t, v_2 = t\}$

Hence the solution is

$$\begin{bmatrix} -t \\ t \\ t \end{bmatrix} = \begin{bmatrix} -t \\ t \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} -t \\ t \\ t \end{bmatrix} = t \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} -t \\ t \\ t \end{bmatrix} = \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}$$

Considering the eigenvalue $\lambda_3 = 5$

We need to solve $A\vec{v} = \lambda\vec{v}$ or $(A - \lambda I)\vec{v} = \vec{0}$ which becomes

$$\left(\begin{bmatrix} 1 & -1 & -1 \\ 1 & 3 & 1 \\ -3 & -6 & 6 \end{bmatrix} - (5) \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -4 & -1 & -1 \\ 1 & -2 & 1 \\ -3 & -6 & 1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

Now forward elimination is applied to solve for the eigenvector \vec{v} . The augmented matrix is

$$\left[\begin{array}{ccc|c} -4 & -1 & -1 & 0 \\ 1 & -2 & 1 & 0 \\ -3 & -6 & 1 & 0 \end{array} \right]$$

$$R_2 = R_2 + \frac{R_1}{4} \implies \left[\begin{array}{ccc|c} -4 & -1 & -1 & 0 \\ 0 & -\frac{9}{4} & \frac{3}{4} & 0 \\ -3 & -6 & 1 & 0 \end{array} \right]$$

$$R_3 = R_3 - \frac{3R_1}{4} \implies \left[\begin{array}{ccc|c} -4 & -1 & -1 & 0 \\ 0 & -\frac{9}{4} & \frac{3}{4} & 0 \\ 0 & -\frac{21}{4} & \frac{7}{4} & 0 \end{array} \right]$$

$$R_3 = R_3 - \frac{7R_2}{3} \implies \left[\begin{array}{ccc|c} -4 & -1 & -1 & 0 \\ 0 & -\frac{9}{4} & \frac{3}{4} & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

Therefore the system in Echelon form is

$$\begin{bmatrix} -4 & -1 & -1 \\ 0 & -\frac{9}{4} & \frac{3}{4} \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The free variables are $\{v_3\}$ and the leading variables are $\{v_1, v_2\}$. Let $v_3 = t$. Now we start back substitution. Solving the above equation for the leading variables in terms of free variables gives equation $\{v_1 = -\frac{t}{3}, v_2 = \frac{t}{3}\}$

Hence the solution is

$$\begin{bmatrix} -\frac{t}{3} \\ \frac{t}{3} \\ t \end{bmatrix} = \begin{bmatrix} -\frac{t}{3} \\ \frac{t}{3} \\ t \end{bmatrix}$$

Since there is one free Variable, we have found one eigenvector associated with this eigenvalue. The above can be written as

$$\begin{bmatrix} -\frac{t}{3} \\ \frac{t}{3} \\ t \end{bmatrix} = t \begin{bmatrix} -\frac{1}{3} \\ \frac{1}{3} \\ 1 \end{bmatrix}$$

Let $t = 1$ the eigenvector becomes

$$\begin{bmatrix} -\frac{1}{3} \\ \frac{1}{3} \\ 1 \end{bmatrix} = \begin{bmatrix} -\frac{1}{3} \\ \frac{1}{3} \\ 1 \end{bmatrix}$$

Which is normalized to

$$\begin{bmatrix} -\frac{1}{3} \\ \frac{1}{3} \\ 1 \end{bmatrix} = \begin{bmatrix} -1 \\ 1 \\ 3 \end{bmatrix}$$

The following table gives a summary of this result. It shows for each eigenvalue the algebraic multiplicity m , and its geometric multiplicity k and the eigenvectors associated with the eigenvalue. If $m > k$ then the eigenvalue is defective which means the number of normal linearly independent eigenvectors associated with this eigenvalue (called the geometric multiplicity k) does not equal the algebraic multiplicity m , and we need to determine an additional $m - k$ generalized eigenvectors for this eigenvalue.

eigenvalue	multiplicity		defective?	eigenvectors
	algebraic m	geometric k		
3	1	1	No	$\begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}$
5	1	1	No	$\begin{bmatrix} -\frac{1}{3} \\ \frac{1}{3} \\ 1 \end{bmatrix}$
2	1	1	No	$\begin{bmatrix} -\frac{10}{3} \\ \frac{7}{3} \\ 1 \end{bmatrix}$

Now that we found the eigenvalues and associated eigenvectors, we will go over each eigenvalue and generate the solution basis. The only problem we need to take care of is if the eigenvalue is defective. Since eigenvalue 3 is real and distinct then the corresponding eigenvector solution is

$$\begin{aligned} \vec{x}_1(t) &= \vec{v}_1 e^{3t} \\ &= \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix} e^{3t} \end{aligned}$$

Since eigenvalue 5 is real and distinct then the corresponding eigenvector solution is

$$\begin{aligned} \vec{x}_2(t) &= \vec{v}_2 e^{5t} \\ &= \begin{bmatrix} -\frac{1}{3} \\ \frac{1}{3} \\ 1 \end{bmatrix} e^{5t} \end{aligned}$$

Since eigenvalue 2 is real and distinct then the corresponding eigenvector solution is

$$\begin{aligned}\vec{x}_3(t) &= \vec{v}_3 e^{2t} \\ &= \begin{bmatrix} -\frac{10}{3} \\ \frac{7}{3} \\ 1 \end{bmatrix} e^{2t}\end{aligned}$$

Therefore the final solution is

$$\vec{x}_h(t) = c_1 \vec{x}_1(t) + c_2 \vec{x}_2(t) + c_3 \vec{x}_3(t)$$

Which is written as

$$\begin{bmatrix} x(t) \\ y(t) \\ z(t) \end{bmatrix} = c_1 \begin{bmatrix} -e^{3t} \\ e^{3t} \\ e^{3t} \end{bmatrix} + c_2 \begin{bmatrix} -\frac{e^{5t}}{3} \\ \frac{e^{5t}}{3} \\ e^{5t} \end{bmatrix} + c_3 \begin{bmatrix} -\frac{10e^{2t}}{3} \\ \frac{7e^{2t}}{3} \\ e^{2t} \end{bmatrix}$$

Which becomes

$$\begin{bmatrix} x(t) \\ y(t) \\ z(t) \end{bmatrix} = \begin{bmatrix} -c_1 e^{3t} - \frac{c_2 e^{5t}}{3} - \frac{10c_3 e^{2t}}{3} \\ c_1 e^{3t} + \frac{c_2 e^{5t}}{3} + \frac{7c_3 e^{2t}}{3} \\ c_1 e^{3t} + c_2 e^{5t} + c_3 e^{2t} \end{bmatrix}$$

20.2.3 Maple step by step solution

Let's solve

$$[x'(t) = x(t) - y(t) - z(t), y'(t) = x(t) + 3y(t) + z(t), z'(t) = -3x(t) - 6y(t) + 6z(t)]$$

- Define vector

$$\vec{x}(t) = \begin{bmatrix} x(t) \\ y(t) \\ z(t) \end{bmatrix}$$

- Convert system into a vector equation

$$\vec{x}'(t) = \begin{bmatrix} 1 & -1 & -1 \\ 1 & 3 & 1 \\ -3 & -6 & 6 \end{bmatrix} \cdot \vec{x}(t) + \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

- System to solve

$$\vec{x}'(t) = \begin{bmatrix} 1 & -1 & -1 \\ 1 & 3 & 1 \\ -3 & -6 & 6 \end{bmatrix} \cdot \vec{x}(t)$$

- Define the coefficient matrix

$$A = \begin{bmatrix} 1 & -1 & -1 \\ 1 & 3 & 1 \\ -3 & -6 & 6 \end{bmatrix}$$

- Rewrite the system as

$$\vec{x}'(t) = A \cdot \vec{x}(t)$$

- To solve the system, find the eigenvalues and eigenvectors of A

- Eigenpairs of A

$$\left[\left[2, \begin{bmatrix} -\frac{10}{3} \\ \frac{7}{3} \\ 1 \end{bmatrix} \right], \left[3, \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix} \right], \left[5, \begin{bmatrix} -\frac{1}{3} \\ \frac{1}{3} \\ 1 \end{bmatrix} \right] \right]$$

- Consider eigenpair

$$\left[2, \begin{bmatrix} -\frac{10}{3} \\ \frac{7}{3} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{x}_1 = e^{2t} \cdot \begin{bmatrix} -\frac{10}{3} \\ \frac{7}{3} \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[3, \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{x}_2 = e^{3t} \cdot \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix}$$

- Consider eigenpair

$$\left[5, \begin{bmatrix} -\frac{1}{3} \\ \frac{1}{3} \\ 1 \end{bmatrix} \right]$$

- Solution to homogeneous system from eigenpair

$$\vec{x}_3 = e^{5t} \cdot \begin{bmatrix} -\frac{1}{3} \\ \frac{1}{3} \\ 1 \end{bmatrix}$$

- General solution to the system of ODEs

$$\vec{x} = c_1 \vec{x}_1 + c_2 \vec{x}_2 + c_3 \vec{x}_3$$

- Substitute solutions into the general solution

$$\vec{x} = c_1 e^{2t} \cdot \begin{bmatrix} -\frac{10}{3} \\ \frac{7}{3} \\ 1 \end{bmatrix} + c_2 e^{3t} \cdot \begin{bmatrix} -1 \\ 1 \\ 1 \end{bmatrix} + c_3 e^{5t} \cdot \begin{bmatrix} -\frac{1}{3} \\ \frac{1}{3} \\ 1 \end{bmatrix}$$

- Substitute in vector of dependent variables

$$\begin{bmatrix} x(t) \\ y(t) \\ z(t) \end{bmatrix} = \begin{bmatrix} -\frac{10c_1 e^{2t}}{3} - c_2 e^{3t} - \frac{c_3 e^{5t}}{3} \\ \frac{7c_1 e^{2t}}{3} + c_2 e^{3t} + \frac{c_3 e^{5t}}{3} \\ c_1 e^{2t} + c_2 e^{3t} + c_3 e^{5t} \end{bmatrix}$$

- Solution to the system of ODEs

$$\left\{ x(t) = -\frac{10c_1 e^{2t}}{3} - c_2 e^{3t} - \frac{c_3 e^{5t}}{3}, y(t) = \frac{7c_1 e^{2t}}{3} + c_2 e^{3t} + \frac{c_3 e^{5t}}{3}, z(t) = c_1 e^{2t} + c_2 e^{3t} + c_3 e^{5t} \right\}$$

✓ Solution by Maple

Time used: 0.031 (sec). Leaf size: 74

```
dsolve([diff(x(t),t)=x(t)-y(t)-z(t),diff(y(t),t)=x(t)+3*y(t)+z(t),diff(z(t),t)=-3*x(t)-6*y(t)
```

$$\begin{aligned}x(t) &= c_1 e^{3t} + c_2 e^{2t} + c_3 e^{5t} \\y(t) &= -c_1 e^{3t} - \frac{7c_2 e^{2t}}{10} - c_3 e^{5t} \\z(t) &= -c_1 e^{3t} - \frac{3c_2 e^{2t}}{10} - 3c_3 e^{5t}\end{aligned}$$

✓ Solution by Mathematica

Time used: 0.04 (sec). Leaf size: 217

```
DSolve[{x'[t]==x[t]-y[t]-z[t],y'[t]==x[t]+3*y[t]+z[t],z'[t]==3*x[t]-6*y[t]+6*z[t]},{x[t],y[t]
```

$$\begin{aligned}x(t) &\rightarrow -\frac{1}{45}e^{2t}\left(5(c_1 + 10c_2)e^{2t}\cos(\sqrt{5}t) + \sqrt{5}(7c_1 - 11c_2 + 9c_3)e^{2t}\sin(\sqrt{5}t) - 50(c_1 + c_2)\right) \\y(t) &\rightarrow \frac{1}{45}e^{2t}\left(5(c_1 + 10c_2)e^{2t}\cos(\sqrt{5}t) + \sqrt{5}(7c_1 - 11c_2 + 9c_3)e^{2t}\sin(\sqrt{5}t) - 5(c_1 + c_2)\right) \\z(t) &\rightarrow (c_1 + c_2)(-e^{2t}) + (c_1 + c_2 + c_3)e^{4t}\cos(\sqrt{5}t) + \frac{(c_1 - 8c_2 + 2c_3)e^{4t}\sin(\sqrt{5}t)}{\sqrt{5}}\end{aligned}$$